MicroBlaze Core Interfaces

Creation of the Hardware Platform

Examples of IP Cores

Software Development

LECTURE 6

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Typical Errors

Rem and / operators and timing constraints

```
• signal s counter : natural;
• if (s counter rem 65536 = 0) then
o pulseDisplay <= '1';</pre>
• else
o pulseDisplay <= '0';</pre>
• end if;
o if (s counter >= 10000000) then
o pulseDisplay <= '0';</pre>
 pulse1Hz <= '0';</pre>
 blink1Hz <= '0';
   s counter <= 0;
• else
    if (s counter rem 50000000 = 0) then
  pulse2Hz <= '1';</pre>
   else
   pulse2Hz <= '0';</pre>
    end if;
```

Typical Errors

Gated clock

- The warning is being issued because one of the clock net is sourced by a combinational logic, making it a gated-clock.
- Xilinx highly recommends that you use the clock enable pin instead of gated clocks.

```
entity gate clock is
            port (DATA, IN1, IN2, LOAD, CLOCK: in STD LOGIC;
                      OUT1: out STD LOGIC);
end gate clock;
architecture BEHAVIORAL of gate clock is
signal GATECLK: STD LOGIC;
begin
            GATECLK <= (IN1 and IN2 and LOAD and CLOCK);
            GATE PR: process (GATECLK)
                                                         entity clock enable is
            begin
                                                                      port (DATA, IN1, IN2, LOAD, CLOCK: in STD LOGIC;
               if (GATECLK'event and GATECLK='1') then
                                                                                OUT1: out STD LOGIC);
                     OUT1 <= DATA;
                                                         end clock enable;
               end if;
                                                         architecture BEHAVIORAL of clock enable is
            end process; -- End GATE PR
                                                                   signal ENABLE: std logic;
end BEHAVIORAL;
                                                          begin
                                                            ENABLE <= IN1 and IN2 and LOAD;
                                                                      EN PR: process (CLOCK)
                                                                      begin
                                                                         if (CLOCK'event and CLOCK='1') then
                                                                            if (ENABLE = '1') then
                                                                               OUT1 <= DATA;
                                                                            end if;
                                                                         end if;
                                                                      end process;
                                                          end BEHAVIORAL;
```

MicroBlaze Interfaces

MicroBlaze does not separate data accesses to I/O and memory (it uses memory-mapped I/O).

The processor has up to three interfaces for memory accesses:

- Local Memory Bus (LMB) providing single-cycle access to on-chip dual-port block RAM.
- Advanced eXtensible Interface (AXI4) for connection to both on-chip and offchip peripherals and memory.
- Advanced eXtensible Interface (AXI4) or AXI Coherency Extension (ACE) for cache coherent connections to memory.

MicroBlaze also supports up to 16 AXI4-Stream interface ports, each with one master and one slave interface.

The interfaces on MicroBlaze are 32 bits wide.

MicroBlaze Core Interfaces

M_AXI_DP: Peripheral Data Interface, AXI4-Lite or AXI4 interface

DLMB: Data interface, Local Memory Bus (BRAM only)

M_AXI_IP: Peripheral Instruction interface, AXI4-Lite interface

ILMB: Instruction interface, Local Memory Bus (BRAM only)

MO_AXIS..M15_AXIS: AXI4-Stream interface master direct connection interfaces

SO_AXIS..S15_AXIS: AXI4-Stream interface slave direct connection interfaces

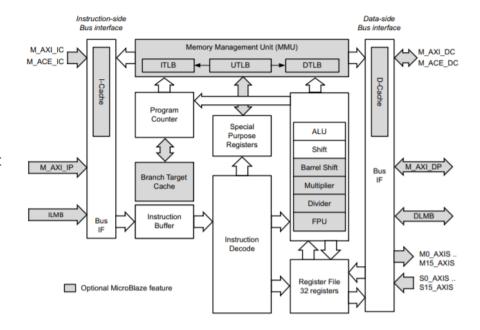
M AXI DC: Data-side cache AXI4 interface

M_ACE_DC: Data-side cache AXI Coherency Extension (ACE) interface

M_AXI_IC: Instruction-side cache AXI4 interface

M_ACE_IC: Instruction-side cache AXI Coherency Extension (ACE) interface

Core: Miscellaneous signals for: clock, reset, interrupt, debug, trace



AXI

Advanced eXtensible Interface is a point to point interconnect that is designed for high performance, high speed microcontroller systems.

The **AXI** protocol is based on a point to point interconnect to avoid bus sharing and therefore allow higher bandwidth and lower latency.

There are three types of AXI4 interfaces:

- AXI4-Lite—for simple, low-throughput memory-mapped communication, providing a register-like structure with reduced features and complexity (1 transfer per transaction)
- AXI4—for high-performance memory-mapped requirements (up to 256 data transfers)
- AXI4-Stream—for high-speed streaming data (unlimited amount of data)

The AXI specifications describe an interface between a single AXI master and a single AXI slave.

AXI interconnects allow multiple masters and/or multiple slaves to interface with each other.

In reality, interconnects contain slave interfaces that connect to AXI masters and master interfaces that connect to AXI slaves. What goes on in an interconnect—i.e., how different masters communicate to different slaves—depends on the implementation. Interconnects can allow a shared address bus, shared data bus, both shared, or neither shared.

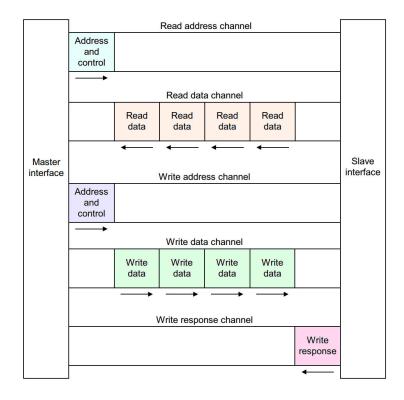
AXI4 and AXI4-Lite Channels

There are five independent channels between an AXI master and slave.

The address channels are used to send address and control information while performing a basic handshake between master and slave.

A master reads data from and writes data to a slave. Read response information is placed on the read data channel, while write response information has a dedicated channel. This way the master can verify a write transaction has been completed.

Every exchange of data is called a transaction. A transaction includes the address and control information, the data sent, as well as any response information. The actual data is sent in bursts which contain multiple transfers.



Debug Overview

MicroBlaze features a debug interface to support JTAG based software debugging tools.

The debug interface is designed to be connected to the Xilinx Microprocessor Debug Module (MDM) core, which interfaces with the JTAG port of Xilinx FPGAs.

To be able to download programs, set software breakpoints and disassemble code, the instruction and data memory ranges must overlap, and use the same physical memory.

MicroBlaze-based Project Example

MicroBlaze processor

Local instruction and data memory

Clock and reset units

General purpose I/O ports (connected to Nexys-4 LEDs, switches, buttons and 7-segment displays)

RS232 UART

AXI interconnect (crossbar for microprocessor and peripherals interconnect)

Interrupt controller

Board File Installation

Configure the board:

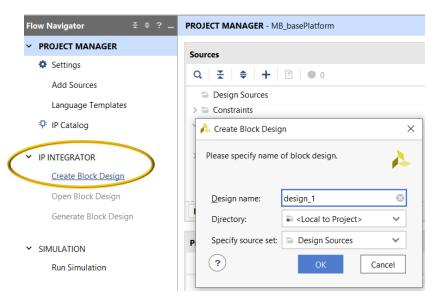
- Do not use Install/Update feature when creating a new project
- Download the board files from <u>Ficheiro "Nexys4.rar" (board support files da</u> Nexys-4 para Xilinx Vivado) on eLearning
- Copy nexys4 folder to Vivado installation folder (C:\Xilinx\Vivado\2020.2\data\boards\board files)
 - By default this folder contains XML files for different FPGA boards manufactured by Xilinx
 - XML files define various interfaces on the board, such as slide switches, push buttons, LEDs, USB-UART, memory, Ethernet etc.
- Restart Vivado
- You are now ready to start a new IP Integrator based Vivado project for the Nexys-4 board

IP Integrator

As FPGAs become larger and more complex, and as design schedules become shorter, use of third-party IP and design reuse is becoming mandatory.

IP Integator aims to aid designers with IP design and reuse issues.

The Vivado IP integrator lets you create complex system designs by instantiating and interconnecting IP from the Vivado IP catalog on a design canvas.

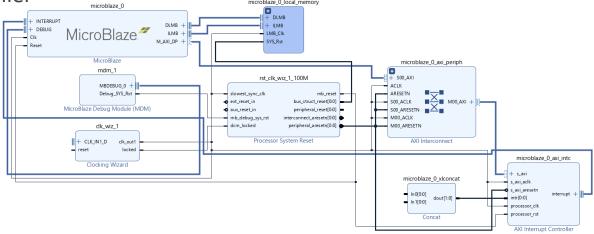


Block Automation

Add MicroBlaze IP

Block Automation assists you in putting together a basic MicroBlaze system consisting of the following:

- A MicroBlaze debug module
- A hierarchical block called the microblaze_0_local_memory
- A clocking wizard
- A reset module
- An AXI interconnect
- An AXI interrupt controller

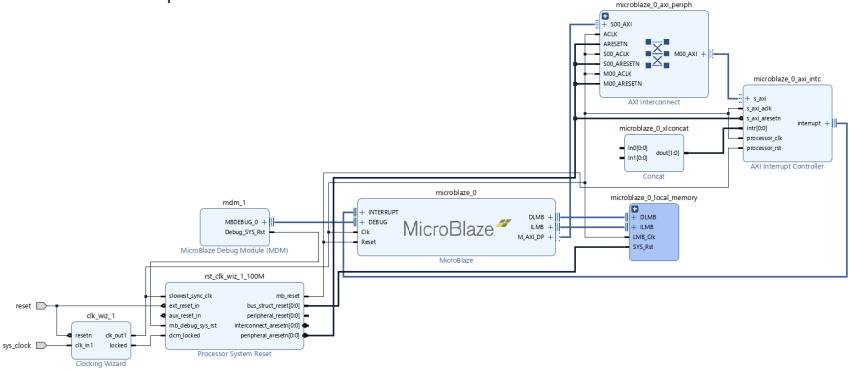


Connection Automation

Connection Automation assists you in making internal connections between different blocks and connections to external interfaces.

Several adjustments have to be done to guide and accomplish the

connection process.



External Interface

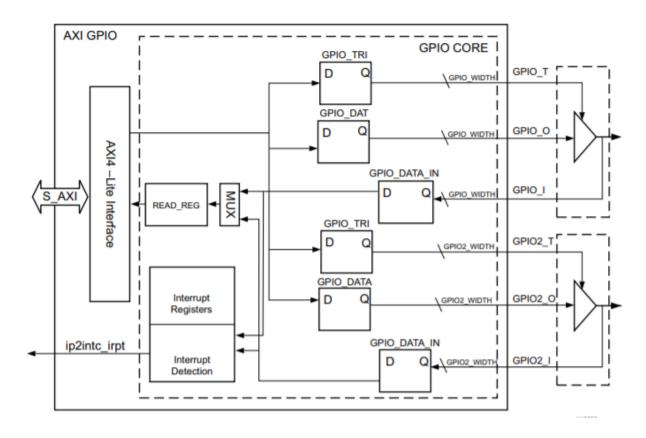
GPIO interface can be tied to one of the several interfaces present on the target board.

GPIO core provides a general purpose input/output interface to the AXI interface. This 32-bit soft IP core supports:

- the AXI4-Lite interface specification
- configurable single or dual GPIO channel(s)
- configurable channel width for GPIO pins from 1 to 32 bits
- dynamic programming of each GPIO bit as input or output
- individual configuration of each channel
- independent reset values for each bit of all registers
- optional interrupt request generation

AXI GPIO

The GPIO core consists of registers and multiplexers for reading and writing the AXI GPIO channel registers. It also includes the necessary logic to identify an interrupt event when the channel input changes.



GPIO Registers

The AXI GPIO data register is used to read the general purpose input ports and write to the general purpose output ports. When a port is configured as input, writing to the AXI GPIO data register has no effect.

The AXI GPIO 3-state control register is used to configure the ports dynamically as input or output. When a bit within this register is set, the corresponding I/O port is configured as an input port. When a bit is cleared, the corresponding I/O port is configured as an output port.

Address Space Offset ⁽³⁾	Register Name	Access Type	Default Value	Description
0x0000	GPIO_DATA	R/W	0x0	Channel 1 AXI GPIO Data Register.
0x0004	GPIO_TRI	R/W	0x0	Channel 1 AXI GPIO 3-state Control Register.
0x0008	GPIO2_DATA	R/W	0x0	Channel 2 AXI GPIO Data Register.
0x000C	GPIO2_TRI	R/W	0x0	Channel 2 AXI GPIO 3-state Control.
0x011C	GIER ⁽¹⁾	R/W	0x0	Global Interrupt Enable Register.
0x0128	IP IER ⁽¹⁾	R/W	0x0	IP Interrupt Enable Register (IP IER).
0x0120	IP ISR ⁽¹⁾	R/TOW ⁽²⁾	0x0	IP Interrupt Status Register.

GPIO Configuration

For input ports when the Interrupt is not enabled, use the following steps:

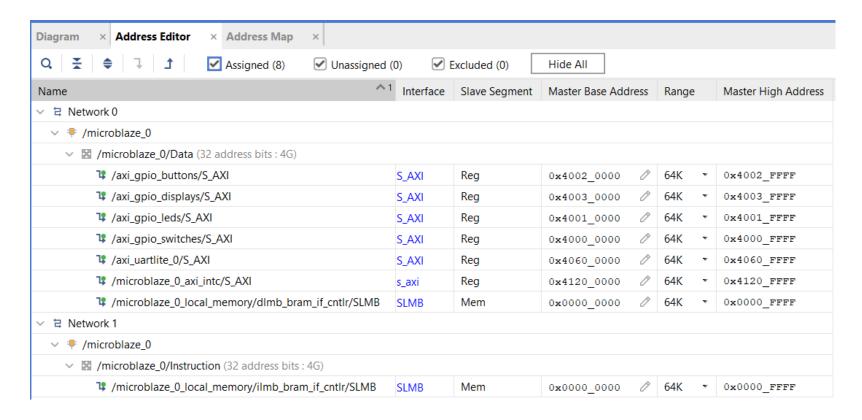
- Configure the port as input by writing the corresponding bit in GPIOx TRI register with the value of 1.
- Read the corresponding bit in GPIOx_DATA register.

For output ports, use the following steps:

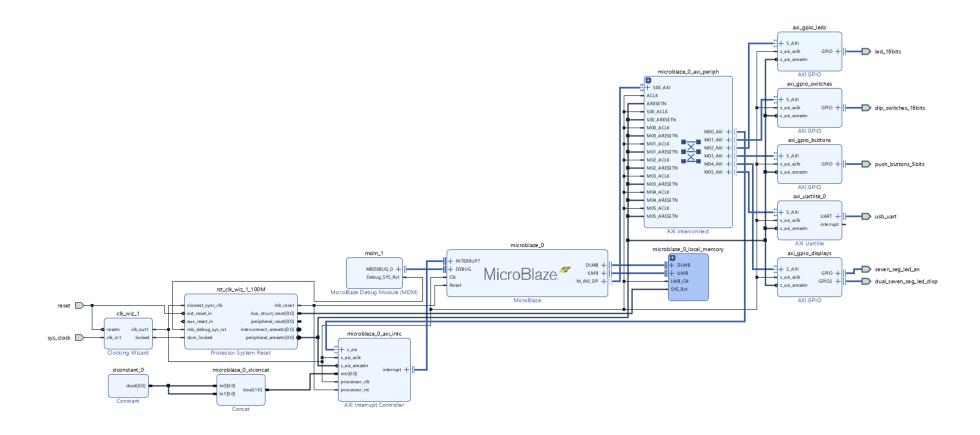
- Configure the port as output by writing the corresponding bit in GPIOx TRI register with a value of 0.
- Write the corresponding bit in GPIOx DATA register.

Address Editor

The address editor is a tree-table view that lists all address paths.



Block Design (BD)



Implementing Hardware

Validate design

you can run a comprehensive design check on the design.

Generate output products (Global)

- After the BD is complete and the design is validated, you must generate output products for synthesis and simulation, to integrate the BD into a toplevel RTL design. The source files and the appropriate constraints for all the IP are generated and made available in the Vivado® Design Suite (IDE) Sources window.
- Generating the output products generates the top-level netlist of the BD.
 The netlist is generated in the HDL language specified by the
 Settings → General → Target Language for the project.

Create HDL Wrapper

 This command generates a top-level HDL file with an instantiation template for the IP integrator BD.

Generate Bitstream

Problems and Results

If a synthesis warning will appear regarding the clock period of the processor's local memory (BRAM), execute the following TCL commands:

```
o set_property CONFIG.Port_A_Clock 100 [get_bd_cells
/microblaze_0_local_memory/lmb_bram]
```

```
o report_property [get_bd_cells
/microblaze_0_local_memory/lmb_bram]
```

Open the synthesized design and execute the following TCL commands:

- o set_property CONFIG_VOLTAGE 3.3 [get_designs synth 1]
- o set_property CFGBVS VCCO [get_designs synth_1]
- Then close the synthesized design and save an XDC file with any name

Development Tools

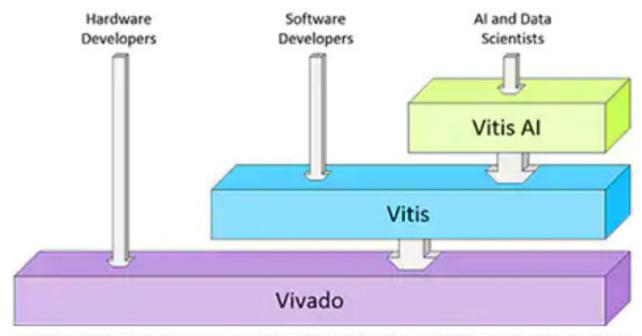


Figure 6: A high-level view of the Xilinx Vivado and Vitis design tool stack reflects how users can work with the tools at the most appropriate levels of abstraction. Hardware designers work with Vivado, software developers work with Vitis, and AI and data scientists work with Vitis AI. (Image source: Max Maxfield)

Software Development

Export hardware

Launch Vitis

Create a Vitis workspace

Create new application project

- Create a new platform from hardware (XSA)
- Create a "helloworld" project

Program device

Launch Vitis serial terminal (or any other similar application)

Build the project

Execute the software application

Final Remarks

At the end of this lecture you should be able to:

- create a hardware platform with the MicroBlaze and GPIOs
- create and execute a simple Vitis project

To do:

- Construct the considered hardware platform
- Test the given applications in Vitis