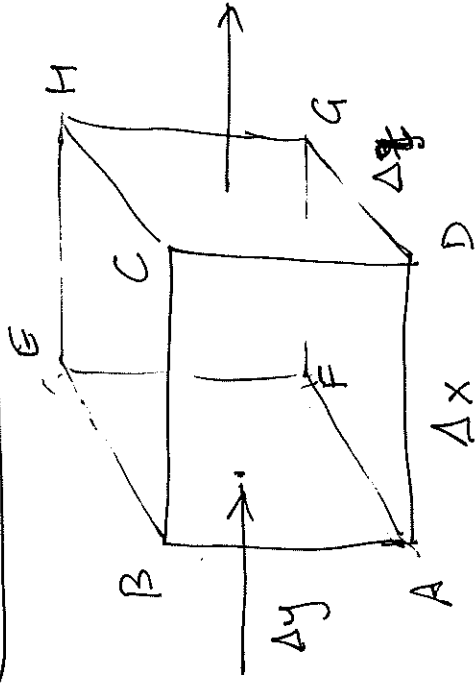


Differential Analysis

①

1) Mass conservation 1-D \rightarrow



$$\dot{m}_{ABEF} - \dot{m}_{CHGD} = \frac{\partial m_{cv}}{\partial t}$$

$$(\rho u)_x \Delta y \Delta z - (\rho u)_{x+\Delta x} \Delta y \Delta z =$$

$$\frac{\partial}{\partial t} (\rho \Delta x \Delta y \Delta z)$$

$$(\rho u)_x \Delta y \Delta z - [(\rho u)_x \Delta y \Delta z + \frac{\partial}{\partial x} (\rho u) \Delta x \Delta y \Delta z] = \frac{\partial}{\partial t} (\rho \Delta x \Delta y \Delta z)$$

$$-\frac{\partial}{\partial x} (\rho u) = \frac{\partial}{\partial t} (\rho)$$

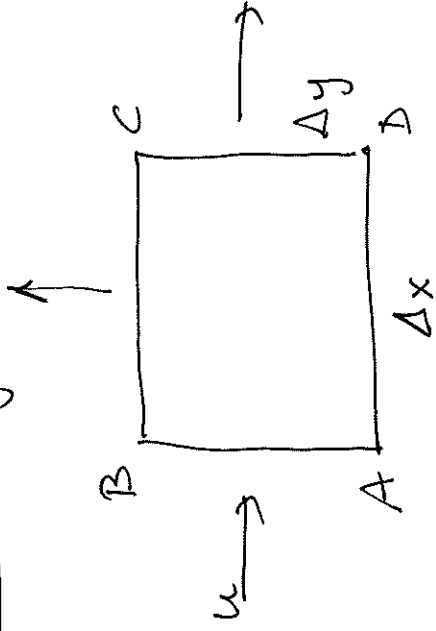
$$\boxed{\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x} (\rho u) = 0} *$$

Continuity Equation
in 1D

Steady State: $\frac{\partial \rho}{\partial t} = 0 \Rightarrow \frac{\partial}{\partial x} (\rho u) = 0$

Incompressible: $\rho \frac{\partial u}{\partial x} = 0 \Rightarrow \frac{\partial u}{\partial x} = 0 \Rightarrow u$ is constant in x

Continuity in 2D



$$\dot{m}_{AB} - \dot{m}_{CD} + \dot{m}_{AD} - \dot{m}_{CB} = \frac{\partial m_{CV}}{\partial t} \quad (2)$$

$$(\rho u)_x \Delta y \Delta z - (\rho u)_{x+\Delta x} \Delta y \Delta z + (\rho v)_y \Delta x \Delta z - (\rho v)_{y+\Delta y} \Delta x \Delta z =$$

$$\frac{\partial}{\partial t} (\rho \Delta x \Delta y \Delta z)$$

$$(\rho u)_x \Delta y \Delta z - \left[(\rho u)_x + \frac{\partial}{\partial x} (\rho u) \Delta x \right] \Delta y \Delta z$$

$$+ (\rho v)_y \Delta x \Delta z - \left[(\rho v)_y + \frac{\partial}{\partial y} (\rho v) \Delta y \right] \Delta x \Delta z = \Delta x \Delta y \Delta z \frac{\partial \rho}{\partial t}$$

$$-\frac{\partial}{\partial x} (\rho u) - \frac{\partial}{\partial y} (\rho v) = \frac{\partial \rho}{\partial t}$$

$$\Rightarrow \frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x} (\rho u) + \frac{\partial}{\partial y} (\rho v) = 0$$

$$\text{Let } \underline{\rho u} \triangleq \rho u \hat{i} + \rho v \hat{j} ; \quad \nabla \triangleq \hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} \quad (\text{Del operator})$$

$$\nabla \cdot \underline{\rho u} = \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} \right) \cdot (\rho u \hat{i} + \rho v \hat{j}) = \frac{\partial}{\partial x} \rho u + \frac{\partial}{\partial y} \rho v$$

$$\left[\frac{\partial \rho}{\partial t} + \nabla \cdot \underline{\rho u} = 0 \right]$$

$\nabla \cdot \underline{\rho u}$ is called the divergence of $\underline{\rho u}$

(3)

Steady State :

$$\frac{\partial \rho}{\partial t} = 0$$

$$\Rightarrow \nabla \cdot (\rho \mathbf{u}) = 0$$

Incompressible :

$$\Rightarrow \nabla \cdot \mathbf{u} = 0$$

$$\Rightarrow \nabla \cdot \mathbf{u} = 0$$

$$\Rightarrow \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$

In 3D :

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{u}) = 0$$

$$\rho \mathbf{u} = \rho u \hat{i} + \rho v \hat{j} + \rho w \hat{k}$$

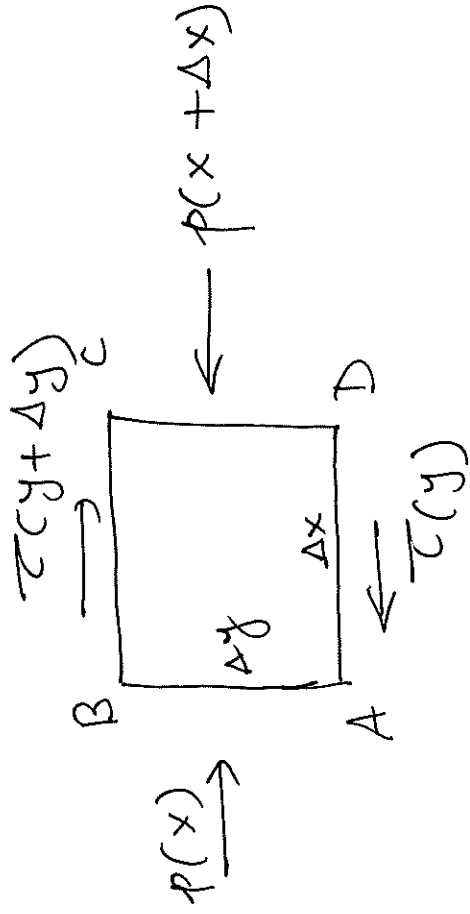
$$\nabla \cdot \mathbf{u} = i \frac{\partial}{\partial x} + j \frac{\partial}{\partial y} + k \frac{\partial}{\partial z}$$

Incompressible / Steady state

$$\nabla \cdot \mathbf{u} = 0$$

$$\Rightarrow \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

Momentum Balance:



$$\dot{L}_{AB} - \dot{L}_{CD} + \Sigma F = \frac{\partial L_{CV}}{\partial t}$$

$$\dot{L}_{AB} = \dot{m}_{AB} u$$

$$= (\rho u)(\Delta y \Delta z) u$$

$$= (\rho u^2)_x \Delta y \Delta z$$

$$\dot{L}_{CD} = \dot{m}_{CD} u$$

$$= (\rho u^2)_{x+\Delta x} \Delta y \Delta z$$

$$F_{CD} = -p(x+\Delta x) \Delta y \Delta z$$

$$F_{BC} = \tau(y+\Delta y) \Delta x \Delta z$$

$$F_{AD} = -\tau(y) \Delta x \Delta z$$

$$\left[(\rho u^2)_x \Delta y \Delta z - (\rho u^2)_{x+\Delta x} \Delta y \Delta z \right] + \left[p(x) \Delta y \Delta z - p(x+\Delta x) \Delta y \Delta z \right]$$

$$+ \left[\tau(y+\Delta y) \Delta x \Delta z \right] - \left[\tau(y) \Delta x \Delta z \right] = \frac{\partial}{\partial t} (\rho \Delta x \Delta y \Delta z u)$$

$$-\frac{\partial}{\partial x} (\rho u^2) \Delta x \Delta y \Delta z - \frac{\partial p}{\partial x} \Delta x \Delta y \Delta z + \frac{\partial \tau}{\partial y} \Delta x \Delta y \Delta z + \frac{\partial \tau}{\partial x} \Delta x \Delta y \Delta z = \Delta x \Delta y \Delta z \frac{\partial}{\partial t} (\rho u)$$

$$-\frac{\partial}{\partial x} (\rho u^2) - \frac{\partial p}{\partial x} + \frac{\partial \tau}{\partial y} = \frac{\partial}{\partial t} (\rho u)$$

$$-\frac{\partial}{\partial x} \left(\rho u \frac{\partial u}{\partial x} + \frac{\partial}{\partial y} (\rho u^2) \right) + \frac{\partial \tau}{\partial x} + \frac{\partial}{\partial y} (\rho u^2) + \frac{\partial}{\partial x} (\rho u^2) = \frac{\partial}{\partial t} (\rho u)$$

$$\frac{\partial}{\partial x} (\rho u^2) = \frac{\partial}{\partial x} (\rho u \cdot u)$$

$$= \rho u \frac{\partial u}{\partial x} + u \frac{\partial (\rho u)}{\partial x}$$

$$\frac{\partial}{\partial x} (\rho u) = \rho \frac{\partial u}{\partial x} + u \frac{\partial \rho}{\partial x}$$

⑤

$$\begin{aligned}
 \frac{\partial}{\partial t}(\rho u) + \frac{\partial}{\partial x}(\rho u^2) &= \rho \frac{\partial u}{\partial t} + u \frac{\partial \rho}{\partial t} + \rho u \frac{\partial u}{\partial x} + u \frac{\partial \rho u}{\partial x} \\
 &= \rho \frac{\partial u}{\partial t} + \rho u \frac{\partial u}{\partial x} + u \left[\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x}(\rho u) \right] \\
 &= \rho \left[\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} \right] \\
 &= \rho \left[\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} \right] u
 \end{aligned}$$

By continuity
(see slide 1)

$\frac{D}{Dt}$ ← Material Derivative
Substantive Derivative
Total Derivative

$$\frac{D}{Dt} \triangleq \frac{\partial}{\partial t} + u \frac{\partial}{\partial x}$$

$$\rho \frac{Du}{Dt} = \rho \frac{\partial u}{\partial t} + \frac{\partial}{\partial x}(\rho u^2)$$

Newtonian fluid $\tau = \mu \frac{du}{dy}$ ← Navier Stokes Equation

$$\left[\rho \frac{Du}{Dt} = -\frac{\partial p}{\partial x} + \mu \frac{\partial^2 u}{\partial y^2} \right] \quad 1D$$

2

Ion 2D

$$\begin{aligned} \bar{X}: & \rho \frac{D\mathbf{u}}{Dt} = \left[\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} + \frac{\partial \mathbf{u}}{\partial x} \frac{\partial \mathbf{u}}{\partial x} + \frac{\partial \mathbf{u}}{\partial y} \frac{\partial \mathbf{u}}{\partial y} \right] = \left[\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} + \frac{\partial \mathbf{u}}{\partial x} \frac{\partial \mathbf{u}}{\partial x} + \frac{\partial \mathbf{u}}{\partial y} \frac{\partial \mathbf{u}}{\partial y} \right] \\ \bar{Y}: & \rho \left[\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} + \frac{\partial \mathbf{u}}{\partial x} \frac{\partial \mathbf{u}}{\partial x} + \frac{\partial \mathbf{u}}{\partial y} \frac{\partial \mathbf{u}}{\partial y} \right] = \left[\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} + \frac{\partial \mathbf{u}}{\partial x} \frac{\partial \mathbf{u}}{\partial x} + \frac{\partial \mathbf{u}}{\partial y} \frac{\partial \mathbf{u}}{\partial y} \right] \end{aligned}$$

$$\begin{aligned} \frac{D\mathbf{u}}{Dt} &= \left(\frac{\partial}{\partial t} + \mathbf{u} \cdot \nabla + \frac{\partial}{\partial x} \frac{\partial}{\partial x} + \frac{\partial}{\partial y} \frac{\partial}{\partial y} \right) \cdot \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} \right) \\ &= \left(\frac{\partial}{\partial t} + \mathbf{u} \cdot \nabla + \frac{\partial}{\partial x} \frac{\partial}{\partial x} + \frac{\partial}{\partial y} \frac{\partial}{\partial y} \right) \cdot \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} \right) \\ &= \left(\frac{\partial}{\partial t} + \mathbf{u} \cdot \nabla \right) \cdot \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} \right) \end{aligned}$$

$$\boxed{\rho \frac{D\mathbf{u}}{Dt} = -\nabla p + \mu \nabla^2 \mathbf{u}}$$

$$\begin{aligned} \nabla^2 \mathbf{u} &= \nabla \cdot (\nabla \mathbf{u}) \\ \nabla \mathbf{u} &= \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} \right) \cdot \left(\hat{i} \frac{\partial \mathbf{u}}{\partial x} + \hat{j} \frac{\partial \mathbf{u}}{\partial y} \right) \\ &= \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} \right) \cdot \left(\hat{i} \frac{\partial \mathbf{u}}{\partial x} + \hat{j} \frac{\partial \mathbf{u}}{\partial y} \right) \\ &= \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} \right) \cdot \left(\hat{i} \frac{\partial \mathbf{u}}{\partial x} + \hat{j} \frac{\partial \mathbf{u}}{\partial y} \right) \end{aligned}$$

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$$\rho \frac{Du}{Dt} = -\frac{\partial p}{\partial x} + \mu \frac{\partial^2 u}{\partial y^2}$$

$$\rho \left[\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} \right] = -\frac{\partial p}{\partial x} + \mu \frac{\partial^2 u}{\partial y^2}$$

Steady State: $\frac{\partial u}{\partial t} = 0$

Uniform flow: $\frac{\partial u}{\partial x} = 0$

$$-\frac{\partial p}{\partial x} + \mu \frac{\partial^2 u}{\partial y^2} = 0$$

$$\mu \frac{d^2 u}{dy^2} = \frac{dp}{dx}$$

$$\mu \frac{du}{dy} = \frac{dp}{dx} y + c_1$$

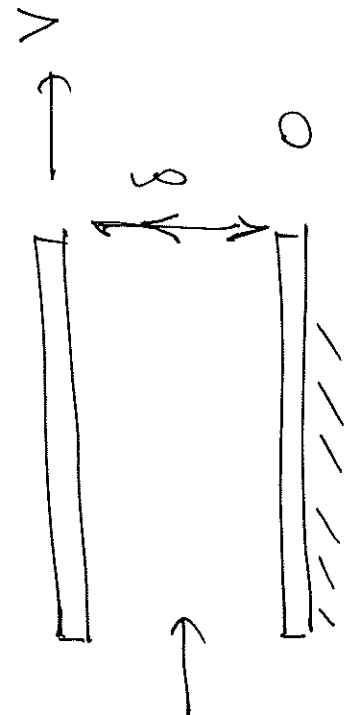
$$\mu u = \frac{dp}{dx} \frac{y^2}{2} + c_1 y + c_2$$

$$0 = 0 + c_1(0) + c_2 \Rightarrow c_2 = 0$$

$$\mu V = \frac{dp}{dx} \frac{\delta^2}{2} + c_1 \delta \Rightarrow c_1 = \mu V - \frac{dp}{dx} \frac{\delta^2}{2}$$

$$u(y=0) = 0 \Rightarrow$$

$$u(y=\delta) = V \Rightarrow$$

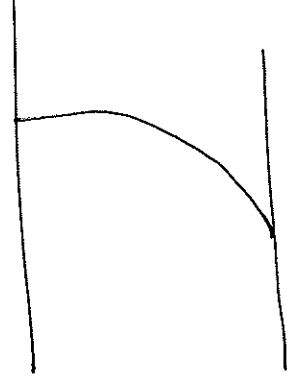
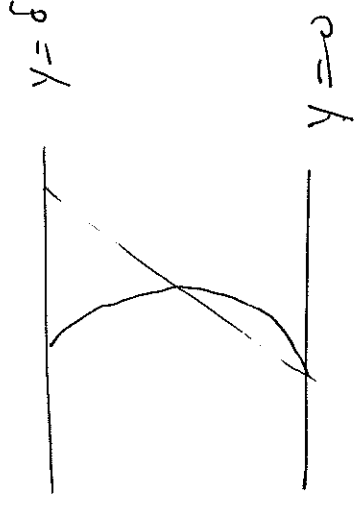


$$\begin{aligned}
 \mu u(y) &= \frac{dp}{dx} \frac{y^2}{2} + \left(\mu V - \frac{dp}{dx} \frac{\delta^2}{2} \right) f \\
 u(y) &= \frac{1}{2\mu} \frac{dp}{dx} (y^2 - \delta^2) + \frac{V}{\delta} f \\
 &= \frac{1}{2\mu} \left(-\frac{dp}{dx} \right) (\delta y - y^2) + \frac{V}{\delta} f \\
 &= \frac{1}{2\mu} \left(-\frac{dp}{dx} \right) \delta^2 \left[\frac{y}{\delta} - \left(\frac{y}{\delta} \right)^2 \right] + \left(\frac{V}{\delta} \right) f
 \end{aligned}$$

$$\begin{aligned}
 \text{when } y=0; \quad u(0) &= 0 \\
 y=\delta; \quad u(\delta) &= V
 \end{aligned}$$

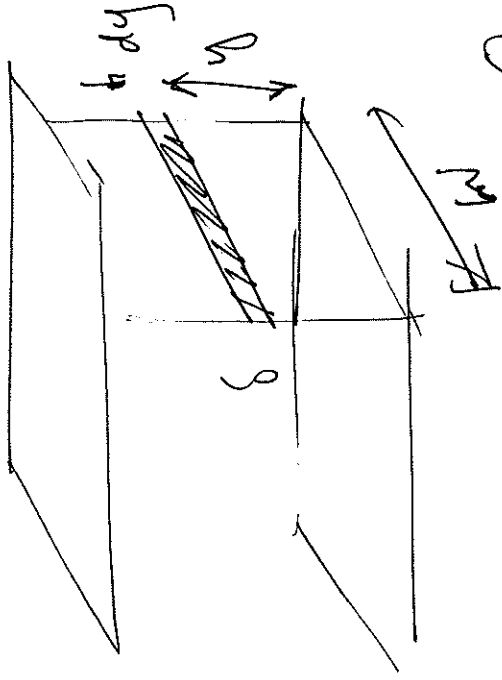
$$u(0) = \mu \frac{\partial u}{\partial y} \bigg|_{y=0}$$

$$u(\delta) = \mu \frac{\partial u}{\partial y} \bigg|_{y=\delta}$$



(8)

Flow Rate of fluid between the plates



$$Q = \int_{\delta} dQ = \int (dy W) u(y)$$

$$Q = W \int_0^{\delta} \left(\frac{1}{2\mu} \left(-\frac{dp}{dx} \right) \delta^2 \left[\left(\frac{y}{\delta} \right) - \left(\frac{y}{\delta} \right)^2 \right] + \frac{\nu}{g} y \right) dy$$

$$\text{Let } \eta = \frac{y}{\delta} \Rightarrow dy = \frac{d\eta}{\delta} \Rightarrow dy = \delta d\eta$$

$$\begin{aligned} Q &= W \int_0^{\delta} \left(\frac{1}{2\mu} \left(-\frac{dp}{dx} \right) \delta^2 \left[\eta - \eta^2 \right] + \nu \eta \right) \delta d\eta \\ &= W \left(\frac{1}{2\mu} \left(-\frac{dp}{dx} \right) \delta^3 \left[\frac{\eta^2}{2} - \frac{\eta^3}{3} \right]_0^{\delta} + \frac{\nu \eta^2}{2} \Big|_0^{\delta} \right) \\ &= W \left[\frac{1}{2\mu} \left(-\frac{dp}{dx} \right) \delta^3 \frac{1}{6} + \frac{\nu \delta}{2} \right] \end{aligned}$$

$$(u_{avg}) A = Q$$

$$(u_{avg}) W \delta = W \left[\frac{1}{2\mu} \left(-\frac{dp}{dx} \right) \frac{\delta^3}{6} + \frac{\nu \delta}{2} \right]$$

$$\boxed{u_{avg} = \frac{1}{2\mu} \left(-\frac{dp}{dx} \right) \frac{\delta^2}{6} + \frac{\nu}{2}}$$

(9)

Pressure gradient required to obtain a flow rate Q (10)

$$\text{Since } Q = W \left[\frac{1}{2\mu} \left(-\frac{dp}{dx} \right) \frac{\delta^3}{6} + \frac{V\delta}{2} \right]$$

$$\left(\frac{dp}{dx} \right) = \left(-\frac{Q}{W} + \frac{V\delta}{2} \right) \frac{6}{\delta^3} \quad \leftarrow 2\mu$$

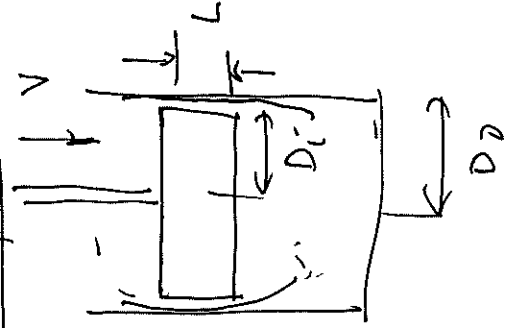
$$\frac{Q}{W} = \frac{1}{2\mu} \left(-\frac{dp}{dx} \right) \frac{\delta^3}{6} + \frac{V\delta}{2}$$

$$\frac{1}{2\mu} \left(\frac{dp}{dx} \right) \frac{\delta^3}{6} = \frac{V\delta}{2} - \frac{Q}{W}$$

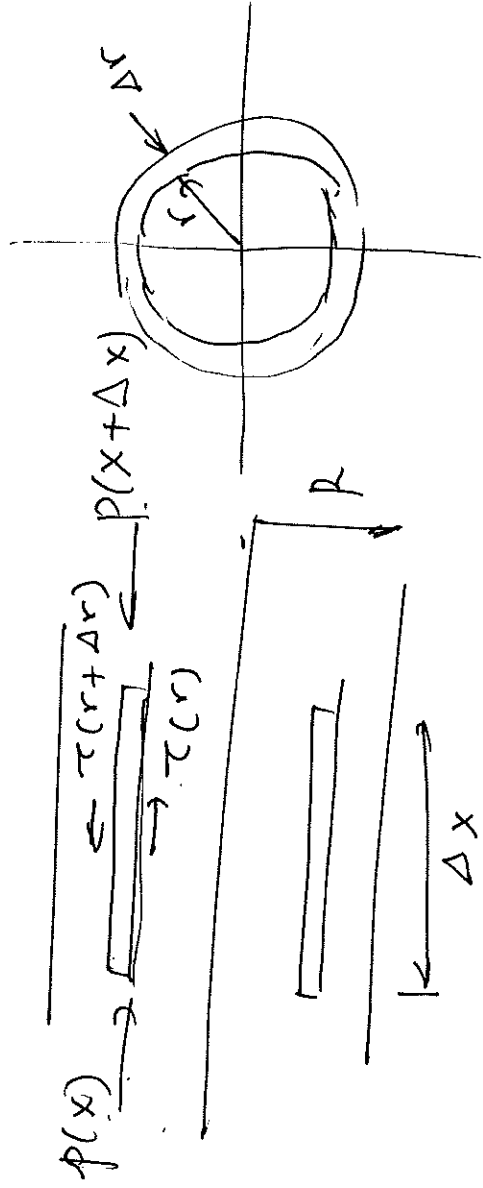
Diagram

$$\delta = \frac{D_o - D_i}{2}$$

$$\frac{dp}{dx} = \frac{P_2 - P_1}{L}$$



Flow in pipes



Steady and incompressible flow.

$$\Sigma F_x = 0.$$

$$p(x) 2\pi r \Delta r - p(x+\Delta x) 2\pi r \Delta r + (\tau(r) A(r))_{r+\Delta r} - (\tau(r) A(r))_r = 0$$

$$-\frac{\partial p}{\partial x} 2\pi r \Delta r \Delta x - \frac{\partial}{\partial r} (\tau A) \Delta r = 0$$

$$A = 2\pi r \Delta x$$

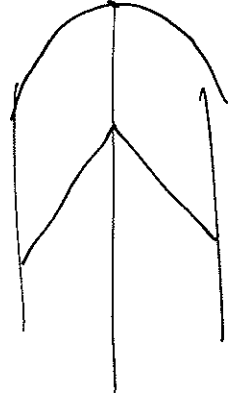
$$-\frac{\partial p}{\partial x} 2\pi r \Delta r \Delta x - \frac{\partial}{\partial r} \left(2\pi r \Delta x \tau(r) \right) \Delta r = 0$$

$$-\frac{\partial p}{\partial x} r - \frac{\partial}{\partial r} (\tau r) = 0$$

$$\frac{\partial}{\partial r} (\tau r) = -\frac{\partial p}{\partial x} r$$

$$\frac{\partial}{\partial r} \left(-\mu r \frac{\partial u}{\partial r} \right) = -\frac{\partial p}{\partial x} r$$

$$\Rightarrow \left[\frac{\partial}{\partial r} \left(\mu r \frac{\partial u}{\partial r} \right) = \frac{\partial p}{\partial x} r ; u(R) = 0 ; \frac{\partial u}{\partial r} \Big|_{r=0} = 0 \right]$$



- 1) Solve for u
- 2) Determine Q
- 3) Determine u_{avg}
- 4) Derive : $\Delta p = f \frac{L}{D} \frac{V^2}{2}$ where $f = \frac{64}{Re}$