

Octave (Matlab) compilation

Karina Olmos and Gordon Cichon

karina@cs.uu.nl, cichon@ifn.et.tu-dresden.de

Challenges for Digital Signal Processing

- ▶ High performance
 - Increasing algorithm complexity
- ▶ Low power
 - Weeks of Operation Time
 - Battery Power
- ▶ Development Time
 - Product cycle ~6 Months



The MOUSE project

Matlab **O**ptimized **U**niversal **S**ignal-Processing **E**nvironment

Goal: Provide an easily programmable platform

that combines:

- ▶ Flexibility of a FPGA
- ▶ Performance of an ASIC
- ▶ Cost and efficiency of an DSP

Why Octave?

To ease program development

- ▶ Heavily used for prototyping and simulations

Why Octave?

To ease program development

- ▶ Heavily used for prototyping and simulations
- ▶ High level language

Why Octave?

To ease program development

- ▶ Heavily used for prototyping and simulations
- ▶ High level language
- ▶ High level data structures (matrix)

Why Octave?

To ease program development

- ▶ Heavily used for prototyping and simulations
- ▶ High level language
- ▶ High level data structures (matrix)
- ▶ It is more declarative than procedural

Why Octave?

To ease program development

- ▶ Heavily used for prototyping and simulations
- ▶ High level language
- ▶ High level data structures (matrix)
- ▶ It is more declarative than procedural
- ▶ Rich library set
 - digital signal library
 - mathematical library
 - audio
 - video
 -

Octave challenges

- ▶ Undeclared, dynamically typed language

Octave challenges

- ▶ Undeclared, dynamically typed language
 - ▶ Overloaded operators
- $$m = x * y$$

Octave challenges

► Undeclared, dynamically typed language

► Overloaded operators

$m = x * y$

► Context dependent interpretation

$p = \text{find}([1 \ 0; 0 \ 1])$		$p = [1 \ ; \ 4]$
$[r, c] = \text{find}([1 \ 0; 0 \ 1])$	\Rightarrow	$r = [1 \ ; \ 2]$ and $c = [1 \ ; \ 2]$
$[r, c, v] = \text{find}([1 \ 0; 0 \ 1])$		$r = [1 \ ; \ 2]$, $c = [1 \ ; \ 2]$ and $v = [1 \ ; \ 1]$

Octave challenges

▶ Undeclared, dynamically typed language

▶ Overloaded operators

$m = x * y$

▶ Context dependent interpretation

<code>p = find([1 0; 0 1])</code>		<code>p = [1 ; 4]</code>
<code>[r, c] = find([1 0; 0 1])</code>	\Rightarrow	<code>r = [1 ; 2]</code> and <code>c = [1 ; 2]</code>
<code>[r, c, v] = find([1 0; 0 1])</code>		<code>r = [1 ; 2]</code> , <code>c = [1 ; 2]</code> and <code>v = [1 ; 1]</code>

▶ User defined functions

- inherit overloaded features from operators
- type and number of function arguments cannot be restricted
- special type checks are introduced to prevent runtime-errors

Example

```
function retval = reshape (a, m, n)
    if (nargin == 2 && prod (size (m)) == 2)
        n = m(2);
        m = m(1);
        nargin = 3;
    endif

    if (nargin == 3)
        [nr, nc] = size (a);
        if (nr * nc == m * n)
            retval = zeros (m, n);
            if (isstr (a))
                retval = setstr (retval);
            endif
            retval(:) = a;
        else error('reshape: sizes must match');
        endif
    else usage('reshape(a, m, n) or reshape (a, size(b))');
    endif
endfunction
```

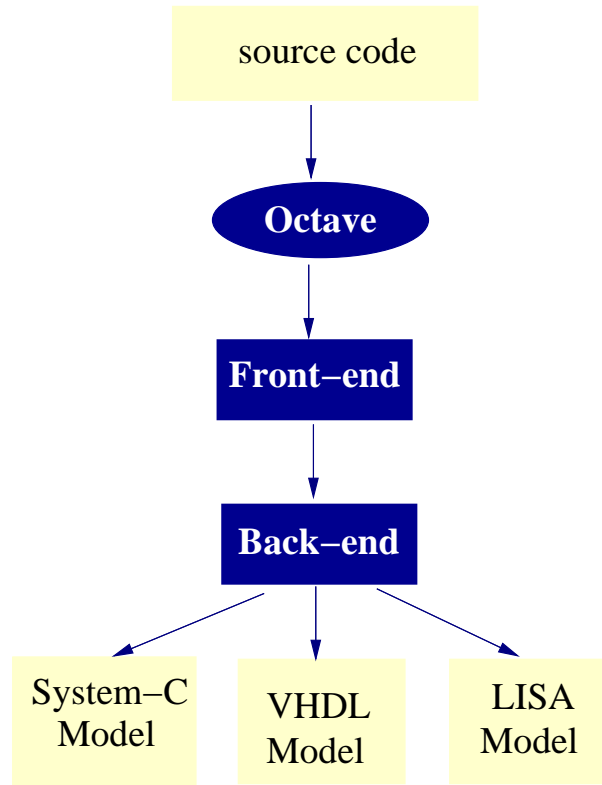
```
c = [ 1 2 3 ];
c1 = reshape(c, 3, 1);
```

Example ...

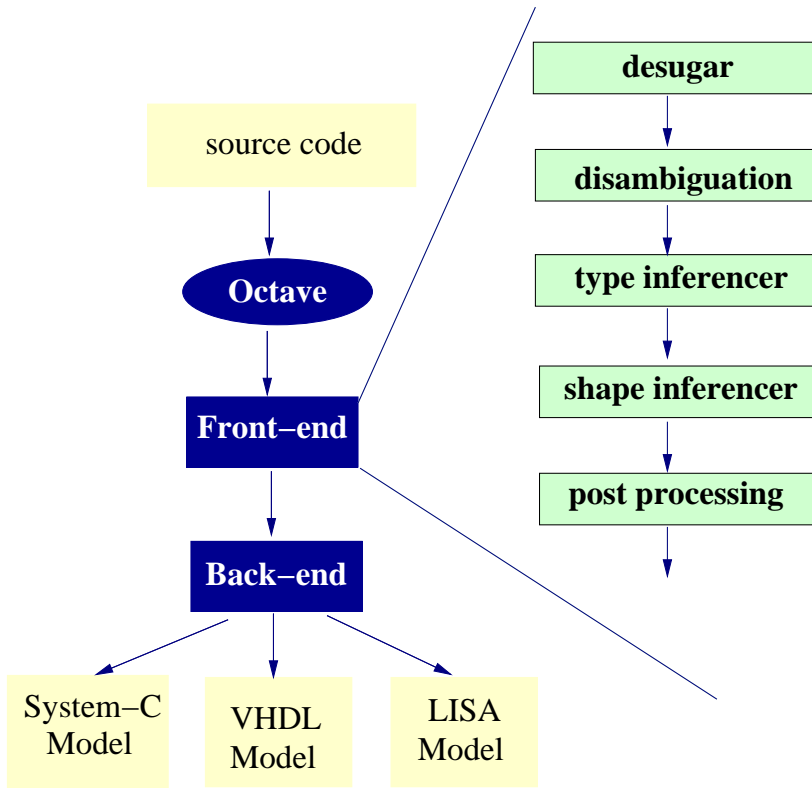
```
function retval = reshape_matrix(_int)_int_int(a, m, n)
    ()
    [nr, nc] = size_lib(a)
    if (nr * nc) == (m * n)
        retval = zeros_lib(m , n)
        ()
        retval(:) = a
    else
        error_lib('reshape: sizes must match');
    endif
end
```

```
c = [ 1 2 3 ];
c1 = reshape_matrix(_int)_int_int(c, 3, 1);
```

Structure of the compiler



Structure of the compiler



Desugaring

Complex statements are desugared into simpler ones

```
switch a
  case (1)
    x = 1;
  case (2)
    x = 2;
  case (3)
    x = 4;
  otherwise
    x = 5;
end
```

\Rightarrow

```
if a == 1
  then x = 1
else
  if a == 2
    then x = 2
  else
    if a == 3
      then x = 4
    else x = 5
    endif
  endif
endif
```

Desugaring

Complex statements are desugared into simpler ones

```
switch a
  case (1)
    x = 1;
  case (2)
    x = 2;
  case (3)
    x = 4;
  otherwise
    x = 5;
end
```

\Rightarrow

```
if a == 1
  then x = 1
else
  if a == 2
    then x = 2
  else
    if a == 3
      then x = 4
    else x = 5
    endif
  endif
endif
```

```
a = [10,11];
++a;
b = ++a ;
```

\Rightarrow

```
a = [ 10 11 ];
a = a + 1;
a = a + 1;
b = a;
```

Disambiguation

An identifier can represent a variable or a function depending on the context

```
function x = test(y)
    a = y + rand;
    rand(3) = a;
    x = rand(2) + 1;
```

⇒

```
function x = test(y)
    a = y + rand();
    rand[3] = a;
    x = rand[2] + 1;
end
```

Type inference

- ▶ No explicit type declarations
- ▶ Type casting is done transparently when required

Type inference

- ▶ No explicit type declarations
- ▶ Type casting is done transparently when required

```
function x = f(a, b)
    x = a + b;
```

⇒

```
function x = f_matrix(_int)_int(a,b)
    x = b + a;
end
function x = f_int_int(a,b)
    x = a + b;
end
```

```
c = 4;
r = f(c, c);
y = f([3, 4], r);
```

```
c = 4;
r = f_int_int(c, c);
y = f_matrix(_int)_int([3 4], r);
```

Shape inference

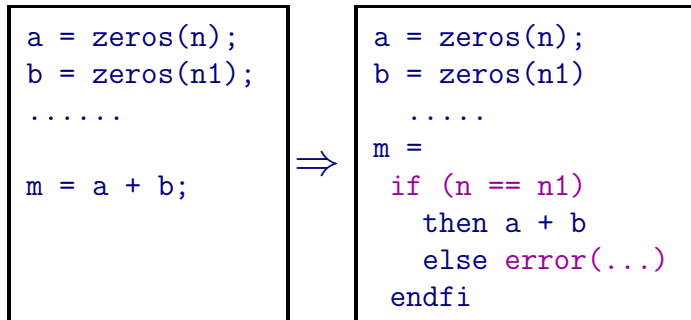
To determine the structure and size of a matrix

- ▶ Exact information avoids run-time memory allocation
- ▶ Give the same behaviour as the interpreter

Shape inference

To determine the structure and size of a matrix

- ▶ Exact information avoids run-time memory allocation
- ▶ Give the same behaviour as the interpreter



Transformations

- ▶ Code hoisting
- ▶ Type and shape propagation
- ▶ Unreachable code elimination
- ▶ Program specialization
- ▶ Side effect elimination
- ▶ Delaying contextual information

Contributions

Classify intrinsic functions into groups

Func Group	Func Name	#In arguments	# Out arguments	Type
I	abs	fixed	fixed	Arg. dependent
II	sqrt	fixed	fixed	Value dependent
III	cumsum	1,2	fixed	First arg. dependent
IV	zeros	0,1,2	fixed	Static
V	size	1,2	Multiple	Context dependent

Contributions

Classify intrinsic functions into groups

Func Group	Func Name	#In arguments	# Out arguments	Type
I	abs	fixed	fixed	Arg. dependent
II	sqrt	fixed	fixed	Value dependent
III	cumsum	1,2	fixed	First arg. dependent
IV	zeros	0,1,2	fixed	Static
V	size	1,2	Multiple	Context dependent

```
[// fname,[arg-types], [ret-type]
  ("abs",  [INT],      S([INT])) ),
  ("abs",  [FLOAT],   S([FLOAT])) ),
  ("abs",  [COMPLEX], S([FLOAT])) ),
  ("find", [INT],      M([INT, [INT, INT],
                        [INT, INT, INT]])),
  ("find", [FLOAT],   M([INT, [INT, INT],
                        [INT, INT, FLOAT]]))
]
```

Runtime elimination checks

Provide rules to eliminate unreachable code

```
EvalFirst:
  |[ &( (~int: 0){t}, e ) ]| ->
    |[ (~int: 0) {INT} ]|
EvalFirst:
  |[ &( e, (~int: 0){t} ) ]| ->
    |[ (~int: 0) {INT} ]|
EvalIfThen:
  |[ if (~int: 0){t} then e1 end ]| ->
    |[ nil {NIL} ]|
EvalFunc:
  Call(Func("isstr"), [ e {STRING} ] ) ->
    |[ (~int: 1) {INT} ]|
EvalFunc:
  Call(Func("isstr"), [ e {t} ] ) ->
    |[ (~int: 0) {INT} ]|
where <not(?STRING)>t
```

Including interpreter variables

Provide contextual information

```
tc-asg-multi(s) =
{| NumArgsOut:
  ?AssignMulti(vs, _)
  ; where(
    <length> vs => val
    ; rules(
      NumArgsOut: Var("nargout") -> val
    )
  )
  ; AssignMulti(id, s)
  ; try(TcAssg <+ TcAssg(s))
|}

tc-asg(s) =
{| NumArgsOut:
  Assign(id, id)
  ; rules(
    NumArgsOut: Var("nargout") -> 1
  )
  ; Assign(id, s)
  ; try(TcAssg <+ TcAssg(s))
|}
```

Conclusion and Future Work

- ▶ Static type determination
- ▶ Several compiler techniques were used for this purpose
- ▶ The framework eliminates most of the dynamic type checks

Conclusion and Future Work

- ▶ Static type determination
- ▶ Several compiler techniques were used for this purpose
- ▶ The framework eliminates most of the dynamic type checks
- ▶ Standard optimizations
- ▶ Vectorization
- ▶ Fixed-point data computation
- ▶ Translation into INSN (intermediate representation)