Parallel Programming in Rust



Lukáš Hozda

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Braiins Systems s.r.o

Language Model & Fundamentals

Data Race Definition



- Multiple threads accessing shared data
- At least one thread is writing
- No synchronization between accesses
- Undefined behavior in unsafe code
- Impossible in safe Rust

Race Conditions vs Data Races



- Race conditions: Logic-level timing issues
- Safe Rust allows race conditions
- Race conditions cannot violate memory safety alone
- Only unsafe code + race condition can break safety

Example: Safe Race Condition



```
use std::thread;
use std::sync::atomic::{AtomicUsize, Ordering};
use std::sync::Arc;
let data = vec![1, 2, 3, 4];
let idx = Arc::new(AtomicUsize::new(0));
let other_idx = idx.clone();
thread::spawn(move | | {
    other idx.fetch add(10, Ordering::SeqCst);
});
// Race condition: May panic, but memory safe
println!("{}", data[idx.load(Ordering::SeqCst)]);
```

Example: Unsafe Race Condition



```
use std::thread;
use std::sync::atomic::{AtomicUsize, Ordering};
use std::sync::Arc;
let data = vec![1, 2, 3, 4];
let idx = Arc::new(AtomicUsize::new(0));
let other idx = idx.clone();
thread::spawn(move | | {
    other idx.fetch add(10, Ordering::SeqCst);
});
if idx.load(Ordering::SegCst) < data.len() {</pre>
    unsafe { // UNSAFE: idx could change after bounds check
        println!("{}", data.get unchecked(idx.load(Ordering::SeqCst)));
```

Rust's Memory Model



- Single writer XOR multiple readers
- Enforced at compile time
- Extends to concurrent code
- Built around preventing data races

Send and Sync Traits



- Send: Safe to transfer between threads
- Sync: Safe to share reference between threads
- Automatically derived for most types
- Unsafe traits incorrect impl causes UB
- T is Sync if and only if &T is Send

Notable Send/Sync Types



Not Send or Sync:

- Raw pointers
- Rc (refcount not threadsafe)
- Non-threadsafe cells (UnsafeCell is Send, but not Sync)

Send and Sync:

- Most standard collections
- Arc<T> where T: Send + Sync
- Atomic types

Thread Basics



- OS-level threads
- Guaranteed preemptive multitasking
- Heavier than async tasks
- Can use all CPU cores

```
use std::thread;
let handle = thread::spawn(|| {
    // New thread
    println!("Hello from thread!");
});
handle.join().unwrap(); // Wait for completion
```

Moving Values Into Threads



- Closure must be 'static
- Use move keyword
- Values are transferred between threads

```
let v = vec![1, 2, 3];

let handle = thread::spawn(move || {
    println!("Vector: {:?}", v);
}); // v is moved into thread

// Cannot use v here anymore
handle.join().unwrap();
```

Scoped Threads



- Allows borrowing from parent scope
- Guarantees threads finish before scope ends
- More flexible than regular threads

```
let mut v = vec![1, 2, 3];
thread::scope(|s| {
   s.spawn(|| {
       // Can borrow v here!
       println!("First: {:?}", &v);
  });
   s.spawn(|| {
       v.push(4); // But we cannot mutate here!
  });
});
v.push(5); // We can mutate here :)
```

Sharing Immutable Data



- Arc = Atomic Reference Counting
- Thread-safe shared ownership
- Clone = increment reference count
- Drop = decrement reference count

```
use std::sync::Arc;
let data = Arc::new(vec![1, 2, 3]);
let data_clone = Arc::clone(&data);
thread::spawn(move || {
    println!("Thread sees: {:?}", *data_clone);
});
```

Arc vs Rc



- Rc = single-threaded reference counting
- Arc = atomic (thread-safe) reference counting
- Arc has small performance overhead
- Cannot convert between them

```
use std::rc::Rc; // Wrong!
use std::sync::Arc; // Correct!
let bad = Rc::new(42);
// thread::spawn(move || { // Compile error!
// println!("{}", bad);
// });
let good = Arc::new(42);
thread::spawn(move | { // Works!
  println!("{}", good);
});
```

Shared Mutable State

Mutex<T>



- Mutual exclusion
- Only one thread can access data at once
- Others must wait
- RAII-style locking

```
use std::sync::{Arc, Mutex};

let counter = Arc::new(Mutex::new(0));
let counter2 = Arc::clone(&counter);

thread::spawn(move || {
    let mut num = counter2.lock().unwrap();
    *num += 1;
}); // lock automatically released here
```

parking_lot::Mutex



- Smaller and faster than std::sync::Mutex
- No poisoning on panic
- More efficient spinning
- Platform-specific optimizations

```
use parking_lot::Mutex;
let mutex = Mutex::new(0);
{
   let mut guard = mutex.lock(); // No unwrap needed!
   *guard += 1;
} // lock released here
```

RwLock - Reader-Writer Lock



- Multiple readers OR single writer
- Good for read-heavy workloads
- Higher overhead than Mutex

```
use std::sync::RwLock;
let data = RwLock::new(vec![1, 2, 3]);
// Multiple readers
let r1 = data.read().unwrap();
let r2 = data.read().unwrap();
// Only one writer
let mut w = data.write().unwrap();
w.push(4);
```

Deadlock Prevention



- Lock ordering matters
- Try to acquire locks in same order
- Use scope-based RAII locks, shortest possible lifetime
- Nested lock problems (use ReentrantMutex from parking_lot)

```
let mutex1 = Mutex::new(0);
let mutex2 = Mutex::new(0);

// Potential deadlock!
let _guard1 = mutex1.lock().unwrap();
let _guard2 = mutex2.lock().unwrap();

// Better: always lock in same order
// across all code paths
```

Condition Variables



- Wait for condition to become true
- Avoids busy waiting
- Always paired with mutex
- Allows thread park/wake



```
use std::sync::{Arc, Mutex, Condvar};
use std::thread;
let pair = Arc::new((Mutex::new(false), Condvar::new()));
let pair2 = Arc::clone(&pair);
thread::spawn(move | | {
    let (lock, cvar) = \delta*pair2;
    let mut started = lock.lock().unwrap();
    *started = true;
    cvar.notify one();
});
let (lock, cvar) = &*pair;
let mut started = lock.lock().unwrap();
while !*started {
    started = cvar.wait(started).unwrap();
```

Memory Models and Atomics

C++ Memory Model Inheritance



- Rust uses C++20 memory model
- Pragmatic choice for tooling
- Based on happens-before relationships
- Bridges hardware and software needs

Compiler Reordering



- Compilers optimize aggressively
- May change execution order
- Example transformation:

```
// Original code
x = 1;
y = 3;
x = 2;

// What compiler might do
x = 2;
y = 3;
```

Hardware Memory Models



- x86/64: Strongly ordered
 - Most operations implicitly synchronized
 - Cheaper to provide strong guarantees
 - Might hide incorrect sync code
- ARM/RISC: Weakly ordered
 - Operations freely reordered
 - Explicit barriers needed
 - ▶ Better tests concurrent code

Memory Access Types



- Data accesses
 - Unsynchronized
 - Can be reordered
 - Cause data races
 - Cannot be used for synchronization
- Atomic accesses
 - ► Thread-aware
 - Ordering guarantees
 - Safe for synchronization
 - Various strength levels

Memory Ordering Levels



- SeqCst (Strongest)
 - Global operation order
 - All threads agree
 - Most expensive
 - ► Safe default choice
- Release-Acquire
 - Paired operations
 - Good for locks
 - Prior writes visible
 - Cheaper than SeqCst
- Relaxed (Weakest)
 - Only atomicity
 - No synchronization
 - Good for counters
 - Best performance

Sequentially Consistent (SeqCst)



```
use std::sync::atomic::{AtomicBool, Ordering};
static FLAG: AtomicBool = AtomicBool::new(false);

// All threads will agree on operation order
FLAG.store(true, Ordering::SeqCst);
let x = FLAG.load(Ordering::SeqCst);
```

Release-Acquire Example



```
use std::sync::atomic::{AtomicBool, Ordering};
static LOCK: AtomicBool = AtomicBool::new(false);
// Thread 1: Release ensures all writes visible
LOCK.store(false, Ordering::Release);
// Thread 2: Acquire sees released writes
while LOCK.compare exchange(
   false, true,
   Ordering::Acquire,
   Ordering::Relaxed
).is err() {}
```

Relaxed Atomics



```
use std::sync::atomic::{AtomicUsize, Ordering};
static COUNTER: AtomicUsize = AtomicUsize::new(0);
// Simple counter, no synchronization needed
thread::spawn(move || {
        COUNTER.fetch_add(1, Ordering::Relaxed);
});
```

Memory Fences



- CPU instruction enforcing memory order
- Prevents reordering across fence
- Types:
 - ► LoadLoad: Orders loads before/after
 - StoreStore: Orders stores before/after
 - ► LoadStore: Orders loads before stores
 - StoreLoad: Strongest, orders all access

```
use std::sync::atomic::fence;
use std::sync::atomic::Ordering;

// Ensure all previous stores visible
fence(Ordering::Release);

// Strongest fence, ensures all ordering
fence(Ordering::SeqCst);
```

Message Passing

Channel Basics



- MPSC = Multiple Producer, Single Consumer
- Thread-safe message queue
- Send values between threads
- Built into standard library

```
use std::sync::mpsc::channel;
let (tx, rx) = channel();
thread::spawn(move || {
    tx.send(42).unwrap();
});
println!("Got: {}", rx.recv().unwrap());
```

Channel Types



- channel() Unbounded sync
- sync_channel(n) Bounded sync
- Bounded channels block when full
- Choose based on backpressure needs
- Many types of channels (spsc, mpsc, etc.)

```
use std::sync::mpsc::{sync_channel, channel};

// Unbounded
let (tx1, rx1) = channel();

// Bounded to 5 messages
let (tx2, rx2) = sync_channel(5);

// Will block if buffer full
tx2.send(42).unwrap();
```

Channel Libraries



Flume

- Drop-in replacement for std::sync::mpsc
- Better performance
- Bounded/unbounded variants
- Select operation support

```
use flume::unbounded;
let (tx, rx) = unbounded();
thread::spawn(move || {
    tx.send("Hello from flume!").unwrap();
});
assert_eq!(rx.recv().unwrap(), "Hello from flume!");
```

Real World Patterns

Producer-Consumer



- Common concurrent pattern
- Multiple producers feed queue
- Single consumer processes items

```
let (tx, rx) = flume::unbounded();
// Spawn multiple producers
for i in 0..3 {
    let tx = tx.clone();
    thread::spawn(move || {
        tx.send(format!("msg from {}", i)).unwrap();
    });
}
// Single consumer
for msg in rx.iter() {
    println!("Got: {}", msg);
}
```

Work Stealing



- Dynamic task distribution
- Threads steal work when idle
- Good for variable workloads

```
use crossbeam_deque::{Worker, Stealer};
let w = Worker::new_fifo();
let s = w.stealer();
// Main thread produces work
w.push(42);
// Other thread steals work
thread::spawn(move || {
    while let Some(work) = s.steal() {
        println!("Stolen: {}", work);
    }
});
```

Thread Pools



- Reuse threads instead of creating new
- Better performance
- Control system resource usage
- Common in real applications

```
use rayon::prelude::*;
let data: Vec<_> = (0..100).collect();

// Parallel iterator using thread pool
let sum: i32 = data.par_iter()
    .map(|x| x * x)
    .sum();
```

Advanced Patterns

Memory Ordering



- Atomic operations have ordering guarantees
- Different levels of synchronization
- Performance vs. strictness tradeoff

```
use std::sync::atomic::{AtomicBool, Ordering};
static STOP: AtomicBool = AtomicBool::new(false);
// Relaxed - fastest, weakest guarantees
STOP.store(true, Ordering::Relaxed);
// Release-Acquire - synchronizes data
STOP.store(true, Ordering::Release);
let must stop = STOP.load(Ordering::Acquire);
// SeqCst - strongest, slowest
STOP.store(true, Ordering::SeqCst);
```

Barrier Synchronization



- Coordinate multiple threads
- Wait for all threads to reach point
- Useful for phased computations

```
use std::sync::{Arc, Barrier};
let barrier = Arc::new(Barrier::new(3));
for _ in 0..3 {
    let b = Arc::clone(&barrier);
    thread::spawn(move || {
        println!("before barrier");
        b.wait(); // Wait for others
        println!("after barrier");
    });
}
```

Lock-Free Data Structures



- No mutex required
- Uses atomic operations
- Higher performance potential
- More complex to implement

```
use crossbeam_queue::ArrayQueue;
let queue = ArrayQueue::new(100);

// Producer
queue.push(42).unwrap();

// Consumer
while let Some(item) = queue.pop() {
   println!("Got: {}", item);
}
```

Custom Sync Types



• Implement Send and Sync traits • Make your types thread-safe • Careful with unsafe code struct MyThreadSafeType { data: Arc<Mutex<Vec<i32>>>, // Automatically Send + Sync because // all fields are Send + Sync impl MyThreadSafeType { fn push(&self, value: i32) { self.data.lock().unwrap().push(value); **Best Practices**

Choose Right Tool



- Channels for message passing
- Mutex for shared state
- Atomic for simple values
- Thread pools for CPU work

```
// Bad: Mutex for single counter
let counter = Arc::new(Mutex::new(0));

// Better: Atomic for counter
let counter = Arc::new(AtomicUsize::new(0));
```

Performance Considerations



- Measure before optimizing
- Consider contention
- Right granularity of locks
- Cache coherency effects

```
// Bad: Too fine-grained
let numbers: Vec<_> = (0..1000)
    .map(|i| Arc::new(Mutex::new(i)))
    .collect();

// Better: Coarser granularity
let numbers = Arc::new(Mutex::new(
    (0..1000).collect::<Vec<_>>()
));
```

Questions?