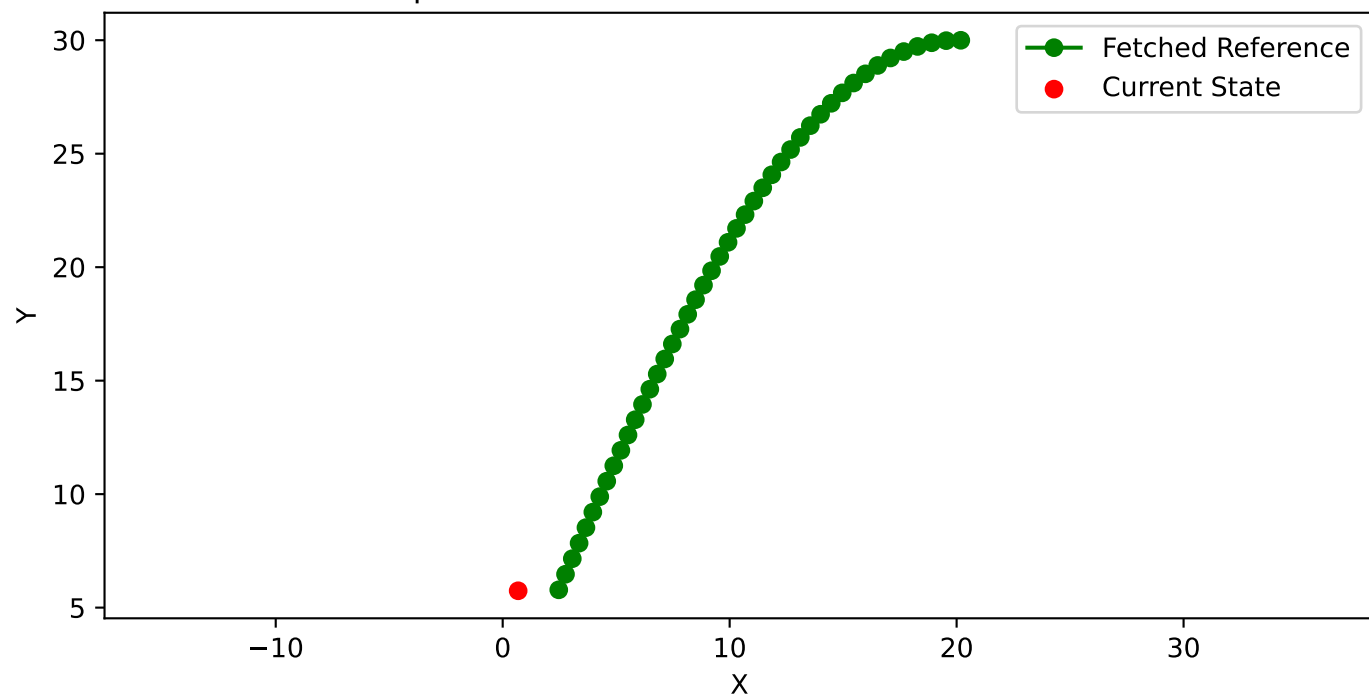
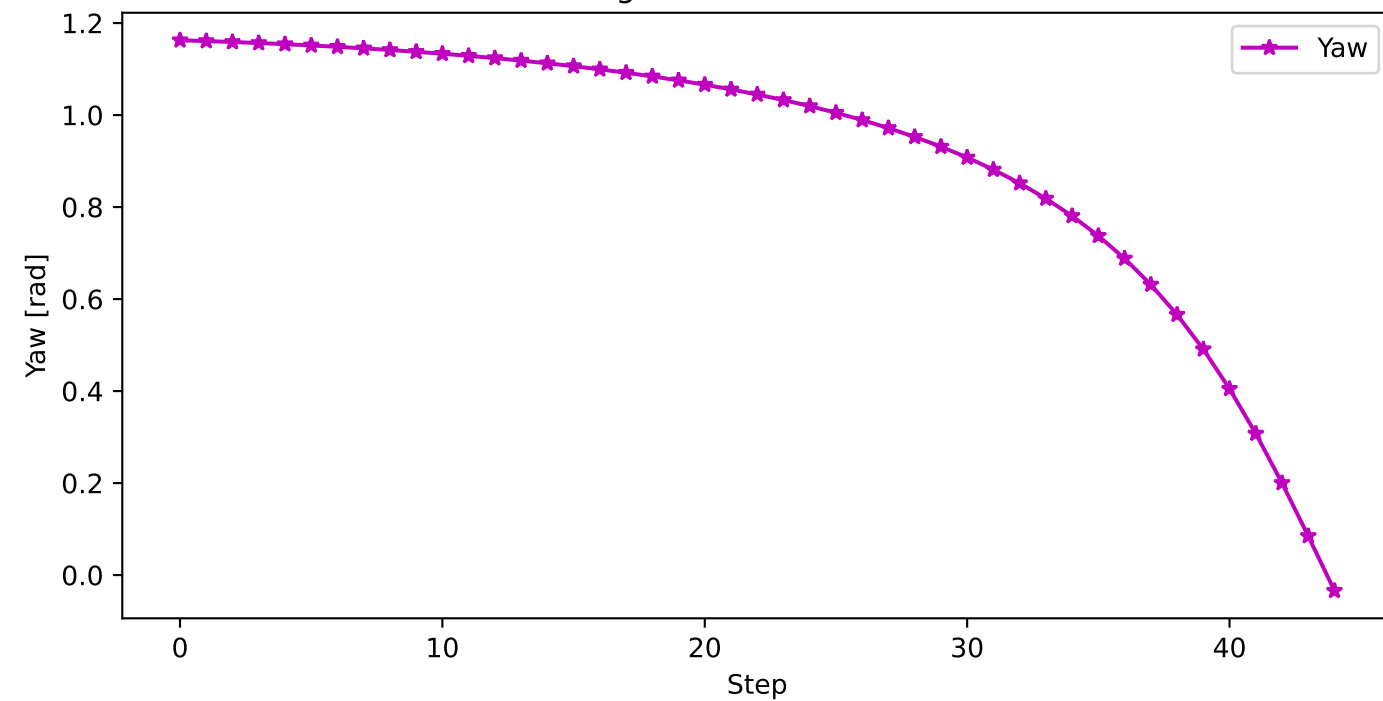


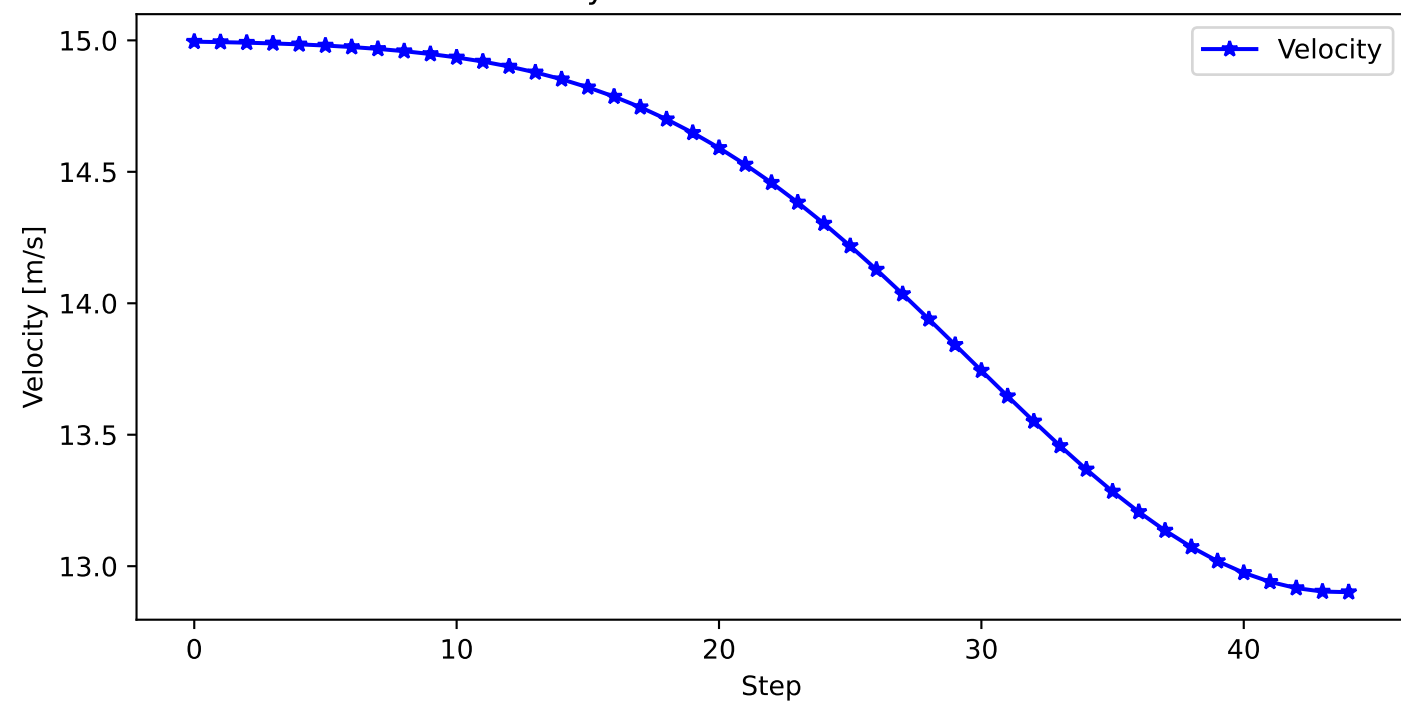
Step 1: Current Position and Fetched Reference



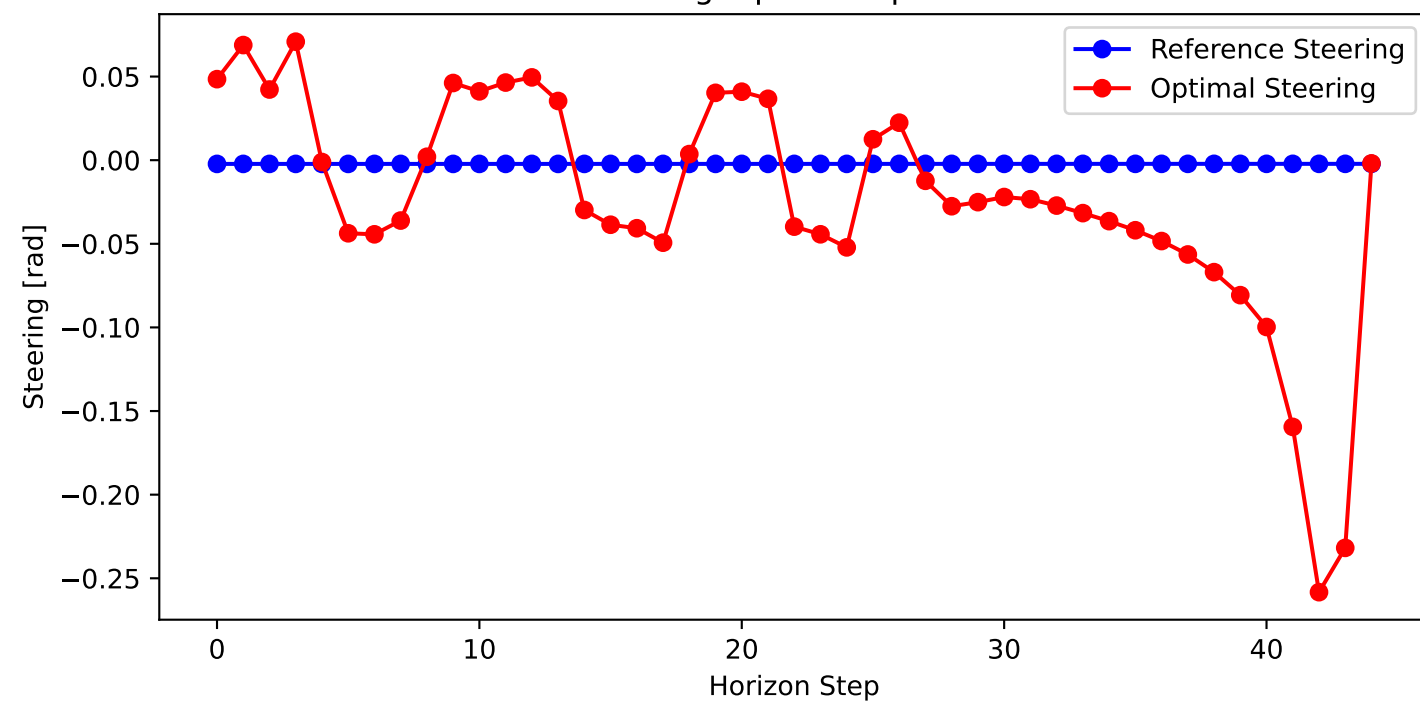
Yaw Angle in Fetched Reference



Velocity Profile in Fetched Reference



Steering Input Comparison



Acceleration Input Comparison

