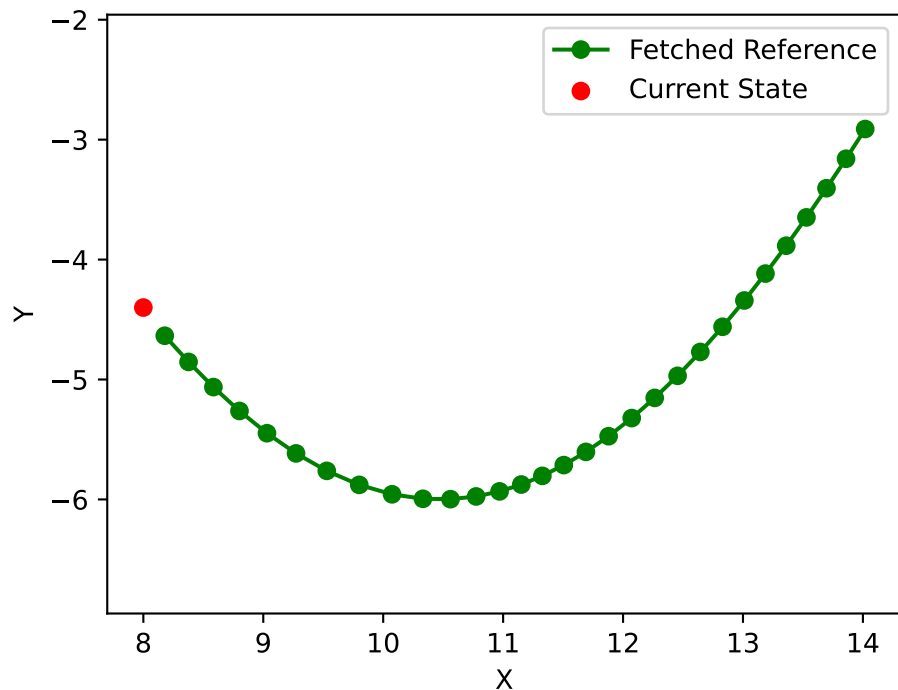
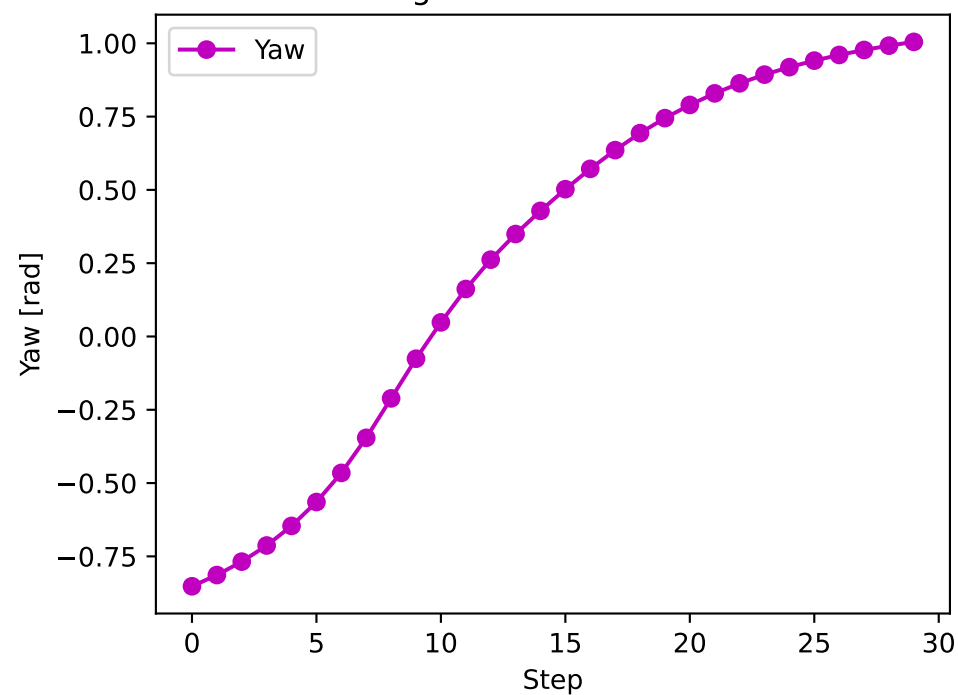


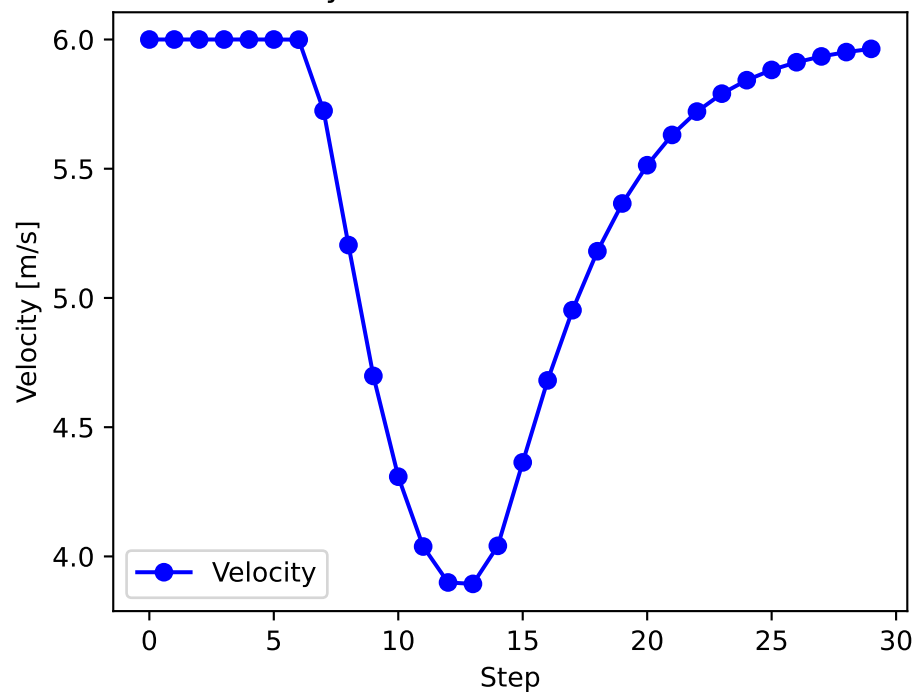
Current Position and Fetched Reference



Yaw Angle in Fetched Reference



Velocity Profile in Fetched Reference



Steering Input in Fetched Reference

