

# MTMCT

Multi-Target Multi-Camera Tracking and Re-Identification  
from Detection to Tracking in Real-Time Scenarios

Luca Uckermann

Cologne University of Applied Sciences

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# Table of Contents

Introduction

Background

Literature Review

Discussion

Conclusion

# Introduction

## Table of Contents

### Introduction

#### MTMCT

#### Objectives

### Background

### Literature Review

### Discussion

### Conclusion

# Introduction

## MTMCT

- ▶ Object detection and tracking across multiple cameras

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- ▶ Important area in computer vision with many applications:
  - ▶ **Video Surveillance:** Monitor public places,  
e.g. airports, train stations, ...

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  - ▶ **Sports Analysis:** Analyse sport events,  
e.g. football, basketball, ...
  - ▶ **Crowd Management:** Analyse crowd behavior,  
e.g. demonstrations, concerts, ...
  - ▶ ...

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## Objectives

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- ▶ Explain background and fundamentals
- ▶ Discuss evolution (traditional → deep learning)
- ▶ Identify:
  - ▶ Research gaps
  - ▶ Potential improvements
  - ▶ Future directions

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- ▶ Explain background and fundamentals
- ▶ Discuss evolution (traditional → deep learning)
- ▶ Identify:
  - ▶ Research gaps
  - ▶ Potential improvements
  - ▶ Future directions
- ▶ Consider ethical and privacy aspects

# Background

## Table of Contents

### Introduction

### Background

Steps of MTMCT

Intra- vs. Inter-Camera Tracking

Tracking Process

Fundamental Concepts

Challenges in MTMCT

Metrics and Evaluation

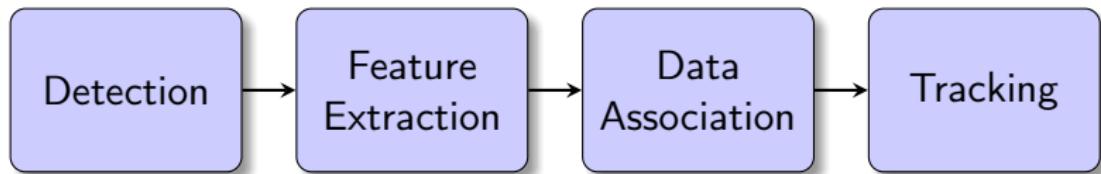
### Literature Review

### Discussion

### Conclusion

# Background

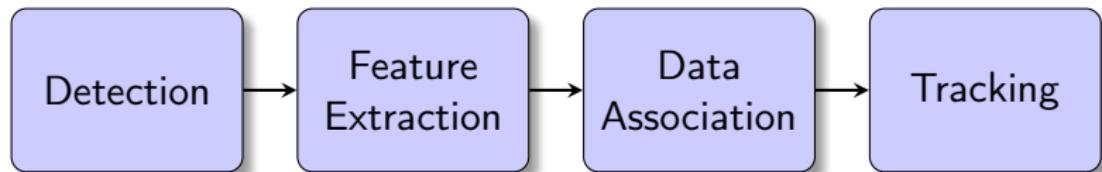
## Steps of MTMCT



**Figure:** Steps of an MTMCT System

# Background

## Steps of MTMCT



**Figure:** Steps of an MTMCT System

- ▶ **Detection:** Detect objects in each frame of each camera

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## Steps of MTMCT

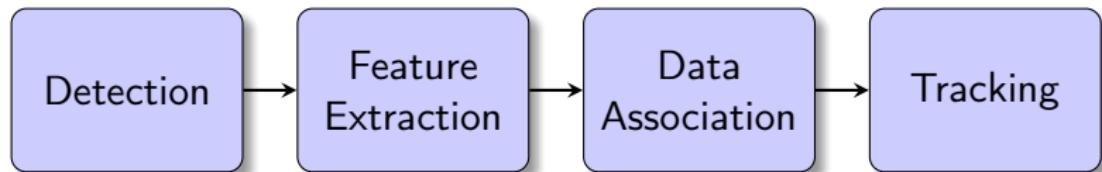


Figure: Steps of an MTMCT System

- ▶ **Detection:** Detect objects in each frame of each camera
- ▶ **Feature Extraction:** Extract features from each detection

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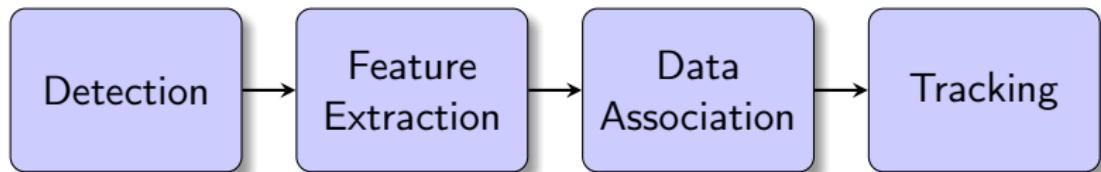


Figure: Steps of an MTMCT System

- ▶ **Detection:** Detect objects in each frame of each camera
- ▶ **Feature Extraction:** Extract features from each detection
- ▶ **Data Association:** Associate detections with existing trajectories (hierarchical)
  - ▶ **Intra-Camera:** Within each camera
  - ▶ **Inter-Camera:** Across cameras

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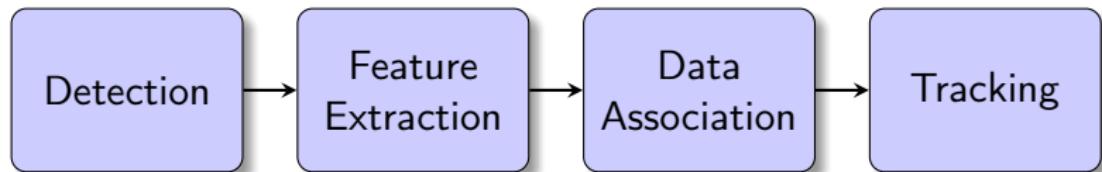
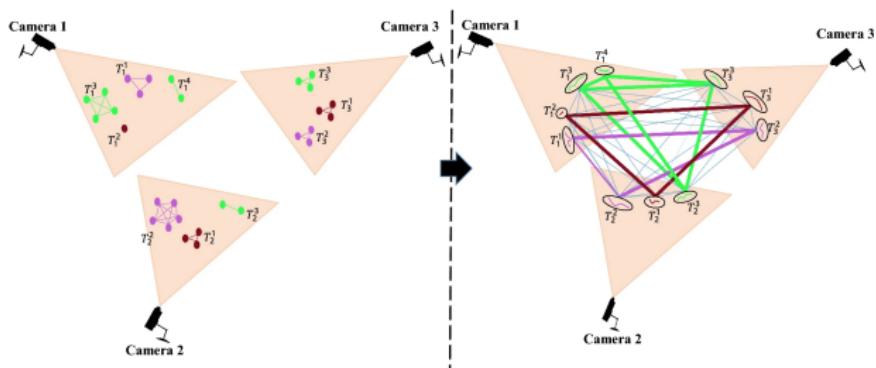


Figure: Steps of an MTMCT System

- ▶ **Detection:** Detect objects in each frame of each camera
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  - ▶ **Intra-Camera:** Within each camera
  - ▶ **Inter-Camera:** Across cameras
- ▶ **Tracking:** Maintaining trajectories over time  
(create, update, delete)

# Background

## Intra- vs. Inter-Camera Tracking



**Figure:** Intra- (left) and Inter-Camera (right) Tracking [1, Fig. 1]

# Background

## Tracking Process

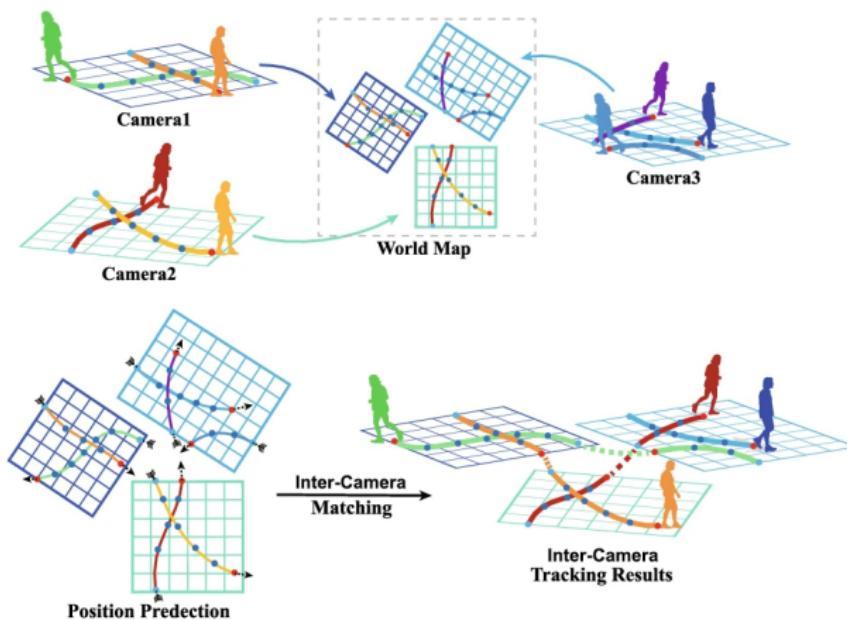


Figure: Tracking Process [2, Fig. 1]

# Background

## Fundamental Concepts

- ▶ Single-Target Single-Camera Tracking (STSCT)
  - ▶ Simplest form of tracking
  - ▶ Track a single target in FOV of a single camera
  - ▶ **Goal:** Maintain ID and trajectory of target

# Background

## Fundamental Concepts

- ▶ Single-Target Single-Camera Tracking (STSCT)
  - ▶ Simplest form of tracking
  - ▶ Track a single target in FOV of a single camera
  - ▶ **Goal:** Maintain ID and trajectory of target
- ▶ Multi-Target Single-Camera Tracking (MTSCT)
  - ▶ Builds on principles of STSCT
  - ▶ Adds complexity of multiple targets
  - ▶ **Goal:** Maintain IDs and trajectories of targets, avoid ID switches

# Background

## Challenges in MTMCT

- ▶ **Occlusions:** Targets can be occluded by other targets or objects

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- ▶ **Varying Lighting Conditions:** Lighting conditions can change over time and across cameras
- ▶ **Camera Specifications:** Cameras can have different specifications (e.g. resolution, FPS, FOV, angle, ...)

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## Challenges in MTMCT

- ▶ **Occlusions:** Targets can be occluded by other targets or objects
- ▶ **Varying Lighting Conditions:** Lighting conditions can change over time and across cameras
- ▶ **Camera Specifications:** Cameras can have different specifications (e.g. resolution, FPS, FOV, angle, ...)
- ▶ **Uncertainties (unknown number of):**
  - ▶ Targets in entire camera
  - ▶ Targets in single camera
  - ▶ Cameras a tracked target appears

# Background

## Metrics and Evaluation

- ▶ **MOTP:** Multiple Object Tracking Precision  
(accuracy of object localization) [3]
- ▶ **MOTA:** Multiple Object Tracking Accuracy  
(three in one: misses, false positives, ID switches) [3]

# Background

## Metrics and Evaluation

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## Metrics and Evaluation

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- ▶ **MOTA:** Multiple Object Tracking Accuracy  
(three in one: misses, false positives, ID switches) [3]
- ▶ **IDF1:** ID F1 Score (harmonic mean of precision and recall) [4]
- ▶ **MT:** Mostly Tracked ( $\geq 80\%$  correctly tracked) [5]
- ▶ **ML:** Mostly Lost ( $\leq 20\%$  correctly tracked) [5]

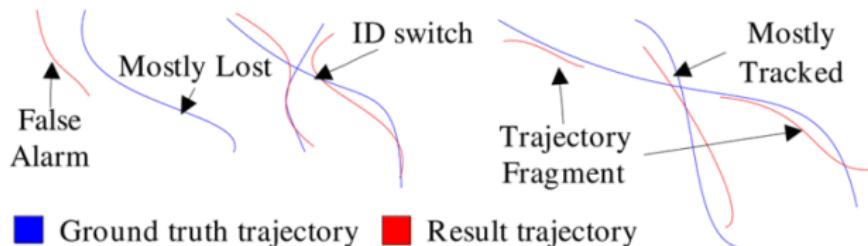


Figure: MT and ML [source image: 5, Fig. 5]

# Literature Review

## Table of Contents

Introduction

Background

Literature Review

Milestones

Tracking Paradigms

Graph-Based

Edge-Computing

Online and Real-Time

State-of-the-Art

Honorable Mentions

Discussion

Conclusion

# Literature Review

## Milestones

- ▶ Detection

# Literature Review

## Milestones

- ▶ Detection
  - ▶ (Faster) R-CNN [6]–[8]
  - ▶ YOLO [9]
  - ▶ SSD [10]
  - ▶ ...

# Literature Review

## Milestones

- ▶ Detection
- ▶ Feature Extraction

# Literature Review

## Milestones

- ▶ Detection
- ▶ Feature Extraction
  - ▶ Scale-Invariant Feature Transform (SIFT) [11]
  - ▶ Histogram of Oriented Gradients (HOG) [12]
  - ▶ CNNs [13]
  - ▶ ...

# Literature Review

## Milestones

- ▶ Detection
- ▶ Feature Extraction
- ▶ Data Association

# Literature Review

## Milestones

- ▶ Detection
- ▶ Feature Extraction
- ▶ Data Association
  - ▶ Hungarian Algorithm [14]
  - ▶ Joint Probabilistic Data Association Filters (JPDAF) [15]
  - ▶ Probabilistic Occupancy Map (POM) [16]
  - ▶ RNNs [17]
  - ▶ ...

# Literature Review

## Milestones

- ▶ Detection
- ▶ Feature Extraction
- ▶ Data Association
- ▶ Tracking

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## Milestones

- ▶ Detection
- ▶ Feature Extraction
- ▶ Data Association
- ▶ Tracking
  - ▶ Kalman Filter [18]
  - ▶ Multiple Hypothesis Tracking (MHT) [19]
  - ▶ ...

# Literature Review

## Milestones

- ▶ Detection
- ▶ Feature Extraction
- ▶ Data Association
- ▶ Tracking
- ▶ Datasets and Challenges

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## Milestones

- ▶ Detection
- ▶ Feature Extraction
- ▶ Data Association
- ▶ Tracking
- ▶ Datasets and Challenges
  - ▶ see Table 1

# Literature Review

## Milestones - Datasets and Challenges

Table: Overview of Datasets

Dataset	Environment	Num. of Scenarios	Num. of Cameras (Overlap)	FPS	IDs	Year	Class
PETS [20]	Outdoor	3	8 (✓)	25	—	2009	Person
MARS [21]	Mixed	Multiple	6 (✓)	—	1261	2016	Person
MOT16 [22]	Outdoor	14	1	25-30	—	2016	Person, Vehicle
DukeMTMC [4]	Outdoor	1	8 (✓)	60	2834	2016	Person
MOT17 [22]	Outdoor	14	1	25-30	—	2018	Person
Wildtrack [23]	Outdoor	Multiple	7 (✓)	2	313	2018	Person
MSMT17 [24]	Mixed	12	15 (✓)	15	4101	2018	Person
CityFlowV1 [25]	Outdoor	5	40 (✓)	10	666	2019	Vehicle
MOT20 [26]	Outdoor	8	1	25	—	2020	Person, Vehicle
CityFlowV2 [25]	Outdoor	6	46 (✓)	10	880	2021	Vehicle
MMPTRACK [27]	Indoor	5	23 (✓)	15	—	2023	Person
MEVID [28]	Mixed	17	33 (✓)	—	158	2023	Person

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## Challenges:

- ▶ MOT [22], [26]
- ▶ AICity [29]
- ▶ VOT(S) [30], [31]
- ▶ ...

# Literature Review

## Milestones - Datasets and Challenges



Figure: DukeMTMC [2, Fig. 2]

# Literature Review

## Tracking Paradigms

- ▶ Tracking-by-Detection

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## Tracking Paradigms

- ▶ **Tracking-by-Detection**
- ▶ Tracking-by-Regression

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- ▶ **Tracking-by-Detection**
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- ▶ Tracking-by-Segmentation

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- ▶ **Tracking-by-Detection**
- ▶ Tracking-by-Regression
- ▶ Tracking-by-Segmentation
- ▶ Tracking-by-Attention
- ▶ **Single-Shot Approaches**

# Literature Review

## Tracking Paradigms

- ▶ **Tracking-by-Detection**
  - ▶ Sort [32]
  - ▶ DeepSORT [33]
- ▶ Tracking-by-Regression
- ▶ Tracking-by-Segmentation
- ▶ Tracking-by-Attention
- ▶ **Single-Shot Approaches**

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- ▶ Tracking-by-Regression
- ▶ Tracking-by-Segmentation
- ▶ Tracking-by-Attention
- ▶ **Single-Shot Approaches**
  - ▶ Tracktor [34]
  - ▶ Single-Shot Multi-Object Tracking (SMOT) [35]
  - ▶ Joint Detection and Embedding (JDE) [36]
  - ▶ FairMOT [37]

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## Tracking Paradigms

- ▶ **Tracking-by-Detection**
  - ▶ Sort [32]
  - ▶ DeepSORT [33]
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  - ▶ Single-Shot Multi-Object Tracking (SMOT) [35]
  - ▶ Joint Detection and Embedding (JDE) [36]
  - ▶ FairMOT [37]
- ▶ **Note:** Only refers to detection and intra-camera tracking  
(inter-camera tracking requires additional step)

# Literature Review

## Graph-Based

- ▶ Data association problem as graph

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- ▶ Data association problem as graph
- ▶ Nodes represent detections

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- ▶ Nodes represent detections
- ▶ Edges represent association costs

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- ▶ Data association problem as graph
- ▶ Nodes represent detections
- ▶ Edges represent association costs
- ▶ Recently use of Graph Neural Networks (GNNs) [38]

# Literature Review

## Edge-Computing

### ► Advantages:

- Process data near source
- Reduce latency and bandwidth
- Improve security and privacy (data not stored)

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## Edge-Computing

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  - ▶ Improve security and privacy (data not stored)
- ▶ **Drawback:** Limited resources

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## Edge-Computing

- ▶ **Advantages:**
  - ▶ Process data near source
  - ▶ Reduce latency and bandwidth
  - ▶ Improve security and privacy (data not stored)
- ▶ **Drawback:** Limited resources
- ▶ **Examples:**
  - ▶ Multi-Camera TrackingChain (MCTChain) [39]
  - ▶ Multi-Camera Tracking using Edge-Computing and Low-Power Communication [40]

# Literature Review

## Online and Real-Time

- ▶ “People Detection and Tracking Using a Fisheye Camera Network” [41]
  - ▶ Simulate checkout-free store
  - ▶ Fisheye cameras
  - ▶ Enter and exit store by scanning QR code
  - ▶ POM for data association
  - ▶ About 10 FPS without GPU

# Literature Review

## Online and Real-Time

- ▶ “People Detection and Tracking Using a Fisheye Camera Network” [41]
  - ▶ Simulate checkout-free store
  - ▶ Fisheye cameras
  - ▶ Enter and exit store by scanning QR code
  - ▶ POM for data association
  - ▶ About 10 FPS without GPU
- ▶ Fast-Constrained Dominant Set Clustering (FCDSC) [1]
  - ▶ Graph-based approach
  - ▶ Consider only a sub-graph at each step
  - ▶ Solve intra- and inter-camera tracking simultaneously
  - ▶ About 18 FPS

# Literature Review

## State-of-the-Art

- ▶ Self-supervised Camera Link Model (SCLM) [42]
  - ▶ Graph Auto-Encoder (GAE) [43]
  - ▶ Zone generation algorithm
  - ▶ State-of-the-art on CityFlow 2019 and 2020

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  - ▶ Zone generation algorithm
  - ▶ State-of-the-art on CityFlow 2019 and 2020
- ▶ Lifted Multicut Meets Geometry Projections (LMGP) [44]
  - ▶ Use of POM
  - ▶ Bottom center of bounding box projection
  - ▶ State-of-the-art on Wildtrack

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  - ▶ Bottom center of bounding box projection
  - ▶ State-of-the-art on Wildtrack
- ▶ EarlyBird [45]
  - ▶ Early fusion in bird's eye view
  - ▶ Encoder network
  - ▶ Projection onto ground plane
  - ▶ Second best on Wildtrack

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  - ▶ Encoder network
  - ▶ Projection onto ground plane
  - ▶ Second best on Wildtrack
- ▶ AOT, DeAOT, DMAOT [46], [47]
  - ▶ Transformer architecture
  - ▶ Segmentation-based tracking
  - ▶ Winner of VOTS2023 challenge

# Literature Review

## Honorable Mentions

- ▶ Harry Potter's Marauder's Map [48]
  - ▶ Draws parallels to Marauder's Map from Harry Potter
  - ▶ Localizes and tracks people
  - ▶ Uses color information and face recognition
  - ▶ Real-world nursing home, 15 cameras

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  - ▶ Draws parallels to Marauder's Map from Harry Potter
  - ▶ Localizes and tracks people
  - ▶ Uses color information and face recognition
  - ▶ Real-world nursing home, 15 cameras
- ▶ MTA Dataset [49]
  - ▶ MTMCT dataset
  - ▶ Virtual environment (GTA V)
  - ▶ Innovative approach
  - ▶ No privacy concerns

# Discussion

## Table of Contents

Introduction

Background

Literature Review

## Discussion

Summary

Gaps and Limitations

Future Research

Ethical and Privacy Concerns

Conclusion

## Discussion

### Summary

- ▶ High complexity of MTMCT systems

# Discussion

## Summary

- ▶ High complexity of MTMCT systems
- ▶ Many challenges

# Discussion

## Summary

- ▶ High complexity of MTMCT systems
- ▶ Many challenges
- ▶ A lot of different approaches

## Discussion

### Gaps and Limitations

- ▶ Existing datasets and challenges focus primarily on intra-camera tracking

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- ▶ No challenge focuses solely on real-time inter-camera tracking

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- ▶ Intra-camera tracking frameworks not optimized for inter-camera tracking

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## Gaps and Limitations

- ▶ Existing datasets and challenges focus primarily on intra-camera tracking
- ▶ No challenge focuses solely on real-time inter-camera tracking
- ▶ Intra-camera tracking frameworks not optimized for inter-camera tracking
- ▶ Trade-off between accuracy and speed

# Discussion

## Future Research

- ▶ Evaluation metric for MTMCT systems  
(currently based on single-camera tracking metrics)

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- ▶ Investigate semi- and unsupervised learning approaches  
(reduce amount of labeled data)

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### Future Research

- ▶ Evaluation metric for MTMCT systems  
(currently based on single-camera tracking metrics)
- ▶ Challenge for real-time inter-camera tracking
- ▶ Investigate semi- and unsupervised learning approaches  
(reduce amount of labeled data)
- ▶ Processing of heterogeneous data

# Discussion

## Ethical and Privacy Concerns

- ▶ Balance technological progress with ethical and privacy concerns

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- ▶ Synthetical data generation
- ▶ YOLO developer stopped working due to ethical concerns [50]

# Discussion

## Ethical and Privacy Concerns

- ▶ Balance technological progress with ethical and privacy concerns
- ▶ Synthetical data generation
- ▶ YOLO developer stopped working due to ethical concerns [50]
- ▶ DukeMTMC has been withdrawn due to privacy concerns [51]

# Conclusion

## Table of Contents

Introduction

Background

Literature Review

Discussion

Conclusion

General

Next Steps

# Conclusion

## General

- ▶ Intra-camera tracking well researched

# Conclusion

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- ▶ Intra-camera tracking well researched
- ▶ Inter-camera tracking still open research area with many challenges, especially in real-time scenarios

# Conclusion

## General

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- ▶ Need for robust data association methods across cameras

# Conclusion

## General

- ▶ Intra-camera tracking well researched
- ▶ Inter-camera tracking still open research area with many challenges, especially in real-time scenarios
- ▶ Need for robust data association methods across cameras
- ▶ Edge computing could lead to more comprehensive and versatile systems

# Conclusion

## General

- ▶ Intra-camera tracking well researched
- ▶ Inter-camera tracking still open research area with many challenges, especially in real-time scenarios
- ▶ Need for robust data association methods across cameras
- ▶ Edge computing could lead to more comprehensive and versatile systems
- ▶ Ethical and privacy concerns need to be considered in the development of MTMCT systems

# Conclusion

## General

- ▶ Intra-camera tracking well researched
- ▶ Inter-camera tracking still open research area with many challenges, especially in real-time scenarios
- ▶ Need for robust data association methods across cameras
- ▶ Edge computing could lead to more comprehensive and versatile systems
- ▶ Ethical and privacy concerns need to be considered in the development of MTMCT systems
- ▶ MTMCT will, as it already does, play an important role in many applications

# Conclusion

## Next Steps

- ▶ Implement a simple MTMCT system

# Conclusion

## Next Steps

- ▶ Implement a simple MTMCT system
- ▶ Follow a multi-shot tracking approach

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## Next Steps

- ▶ Implement a simple MTMCT system
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# Conclusion

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- ▶ Evaluate performance and optimize system

The End

Thank you for your attention!

Questions? Comments?

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