

# Trajectory planning with real time vision-based obstacle detection

by

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# Abstract

Here are some things that I did.

# Lay Summary

Here are some things that I did.

# Preface

Here are I describe what work has already been published.

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# List of Abbreviations

Short	Long
CIHR	Canadian Institutes of Health Research
MSFHR	Michael Smith Foundation for Health Research
NCI	National Cancer Institute
PMCOA	PubMed Central Open Access
WGS	whole genome sequencing

# Acknowledgements

I would like to thank Stack Overflow for everything.

# Dedication

To Stack Overflow.

# Chapter 1

## Introduction

Here is the introduction to this thesis. I will do several things. It is heavily based on previous seminal work on penguins (Meyer-Rochow and Gal, 2003).

## Chapter 2

# First Chapter of Research

Here is a research chapter. Look a graph in Figure ??.

Also check out the associated data in Table ??.

## Chapter 3

# Conclusions

I did several things and will now discuss why they are good.

# Bibliography

Meyer-Rochow, V. B. and Gal, J. (2003). Pressures produced when penguins pooh—calculations on avian defaecation. *Polar Biology*, 27(1):56–58.