Introduction to Neural Machine Translation

Fabienne Cap



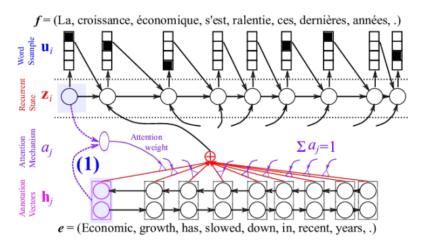
What is Neural Machine Translation?



"Neural Machine Translation is the approach of modeling the entire MT process via one big artificial neural network." (Manning, 2016)

NMT Example

... repeated from Introduction Lecture:



NMT Timeline

1987	Early encoder-decoder, with vocabulary size 30-40 (Allen, 1987)
2013	Pure neural MT system presented
	(Kalchbrenner & Blunsom, 2013)
2014	Competitive encoder-decoder for large-scale MT
	(Bahdanau et al., 2015, Luong et al., 2014)
2015	NMT systems in shared tasks
	performs well in WMT, state-of-the-art at IWSLT
2016	NMT systems top most language pairs in WMT
2016	Commercial deployments of NMT launched

Taken from EACL 2017 Tutorial on Practical NMT

Overview

NMT vs. SMT

A typical NMT system

Shortcomings of NMT and proposed solutions

Outlook

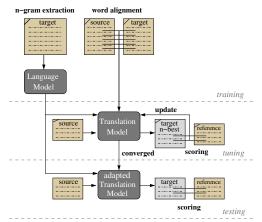
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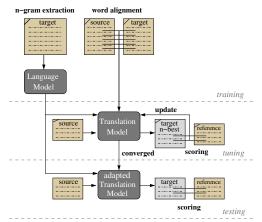
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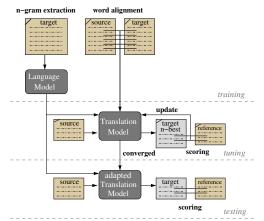
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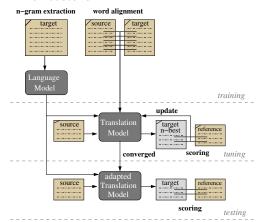
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- context-independent translations
- idependent models (TM, LM, RM)
- learn feature weights using minimum error rate training



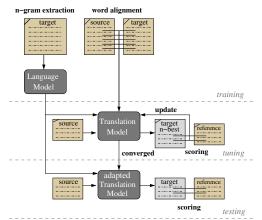
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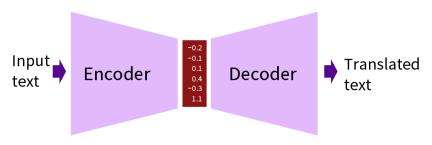


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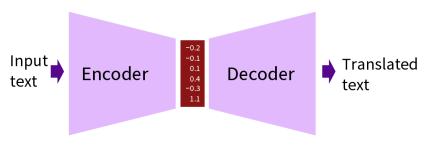
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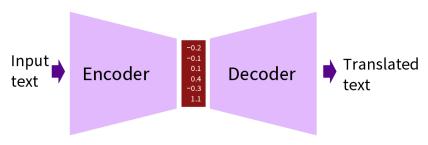
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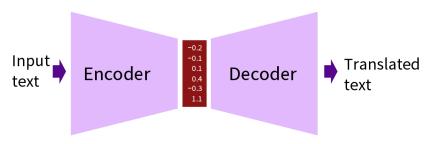
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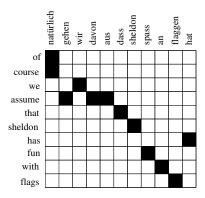


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SMT vs. NMT: Word Alignment

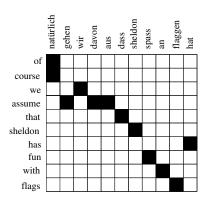
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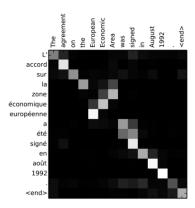


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NMT: Attention Models



Taken from (Bahdanau et al., 2015)

SMT vs. NMT: Context

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NMT:

- all translations are context-dependent!
- generate a translation with an LM also conditioned on the source language

NMT vs. SMT: Performance

system	BLEU	official rank
uedin-nmt	34.2	1
metamind	32.3	2
uedin-syntax	30.6	3
NYU-UMontreal	30.8	4
online-B	29.4	5-10
KIT/LIMSI	29.1	5-10
cambridge	30.6	5-10
online-A	29.9	5-10
promt-rule	23.4	5-10
KIT	29.0	6-10
jhu-syntax	26.6	11-12
jhu-pbmt	28.3	11-12
uedin-pbmt	28.4	13-14
online-F	19.3	13-15
online-G	23.8	14-15

WMT16 EN→DE

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online-G	30.1	8
jhu-syntax	31.0	9
online-F	20.2	10

WMT16 DE→EN

- pure NMT
- NMT component

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 use a recurrent neural network (RNN) to read a source
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- Encode source sentence: convert into fixed-length vector source_embj = WORDREP(source_wordj, parameters)
- 2) Map to hidden state using an RNN: $hidden_j = RNN(h_{j-1}, source_emb_j, parameters)$
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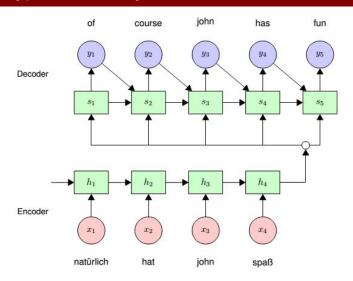
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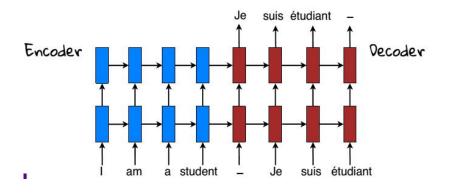
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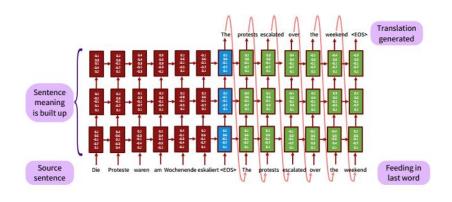
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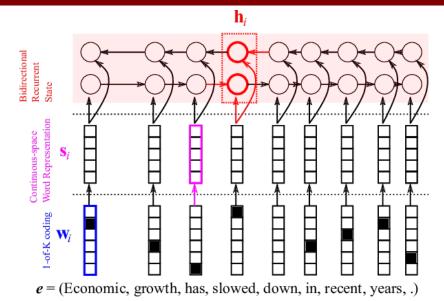
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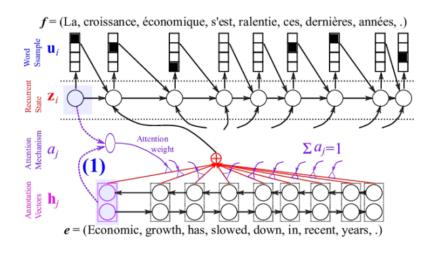


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This is a training loop! Based on https://github.com/neubig/nmt-tips

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- standard way of doing this: maximise the log lilkelihood of the training data:

$$\phi' = ARGMAX_{\phi}(\sum_{E,F} logP(E|F;\phi))$$

• equivalent: minimise the negative log likelihood:

$$\phi' = ARGMIN_{\phi}(-\sum_{E,F} logP(E|F;\phi)$$

minimisation using stochastic gradient descent (SGD)
 calculate gradient of the negative log probability:

$$\nabla \phi - logP(E|F;\phi)$$

• then update the parameters based on an update rule:

$$\phi \leftarrow UPDATE(\phi, \nabla_{\phi} - logP(E|F; \phi))$$

ullet substract the gradient of the negative log likelihood multiplied by a learning rate γ

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General concept in machine learning: minimise the distance between what has been predicted and what should have been predicted.

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Andrew Ng's Coursera course on Machine Learning: https://www.youtube.com/watch?v=LNOPLnDpGN4&t=121s

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Gradient descent for each single sentence takes time!

• Solution:

Update the gradients for multiple sentences at the same time
This is called Mini batching

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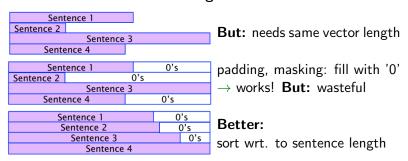
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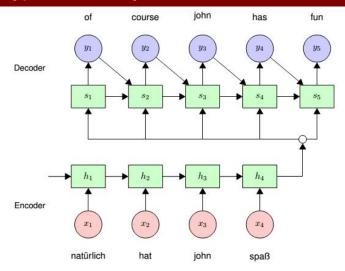
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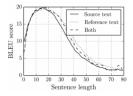
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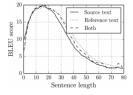


- Summary vector is an information bottleneck
- **Problem:** Sentence length! Fixed sized representation degrades as sentence length increases (Cho et al. 2014)



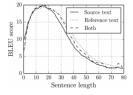
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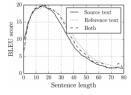
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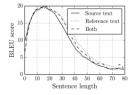
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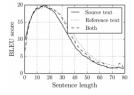
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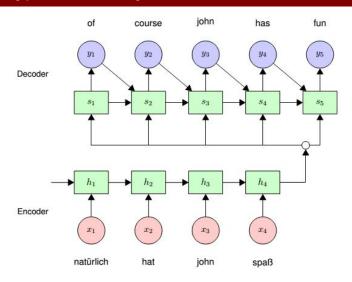


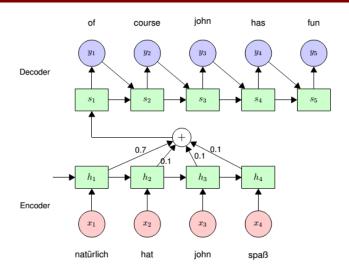
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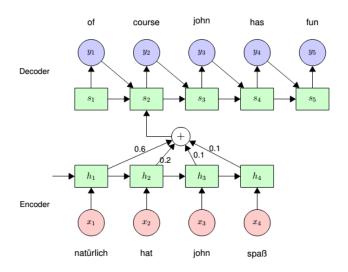
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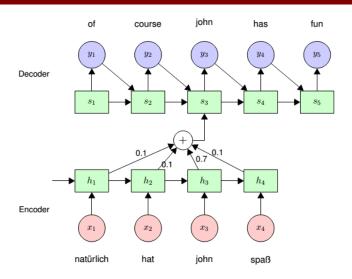


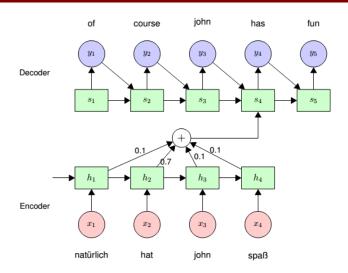
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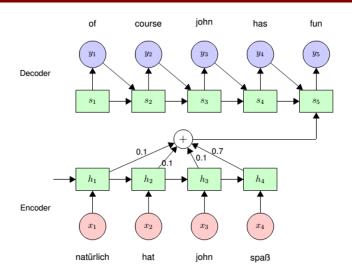










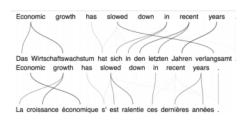


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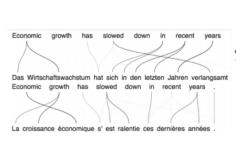
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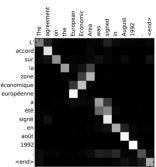
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Overview

NMT vs. SMT

A typical NMT system

Shortcomings of NMT and proposed solutions

Outlook

Overview

NMT vs. SMT

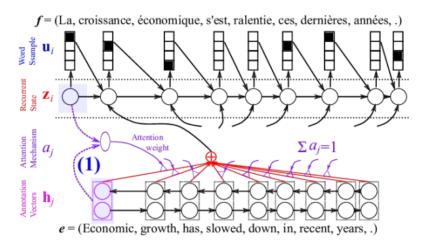
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NMT Example

... repeated from Introduction Lecture:



END OF TODAY

This is the end. Hold your breath and count to ten.