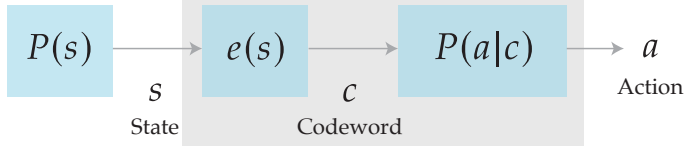


APolicy, $\pi(a|s)$

State distribution

**B**