

Wednesday - 20/3/2024 - Nikhil Londhe

Paper - A Review of QAOA and its Variants, Kostas Bekas - arXiv:2306.09198v2

① Background of Optimization problems (Approximate Optimization)

Given a Combinatorial optimization problem

defined on a n -bit string $(x = x_1, \dots, x_n)$

where the goal is to maximize a objective

function $C(x) : \{0,1\}^n \rightarrow \mathbb{R}_{\geq 0}$, Ideally we want $\alpha = 1$.

Often optimization algorithm aims to find x^* We look for some optimality guarantee (lower bounds on the quality of the solution)

Such that approximation ratio α ,

α -approximated algorithm $\Rightarrow \alpha \leq 1$ for every instance of the problem

$$\alpha = \frac{C(x^*)}{C_{\max}}$$

"hardness of approximation" - gap between $C(x^*)$ and C_{\max}

cannot be reduced in poly time.

② QUBO - Quadratic Binary Unconstrained Optimization (Sec 2.2)

QUBO belong to the NP-Complete class

\Rightarrow Any NP Complete problem can be mapped to QUBO

A vector of unknown $x = (x_1, \dots, x_n)$, $x_i \in \{0,1\}$ (Set of Decision variables)

If we have a square symmetric matrix $Q \in \mathbb{R}^{n \times n}$

And Cost function $C(x) = x^T Q x = \sum_{i,j} Q_{ij} x_i x_j$

So the aim is to find x^* st $x^* = \arg \min_{x \in \{0,1\}^n} C(x)$

$$x^* = \arg \min_{x \in \{0,1\}^n} -C(x)$$

Because Q is square symmetric

$$\sum_{i,j} Q_{ij} x_i x_j + 2 \sum_{i,j} Q_{ij} x_i$$

Binary variable

OR more generally

$$C(x) = \sum_{i,j} Q_{ij} x_i x_j + \sum_i c_i x_i + c$$

Constant (Doesn't affect the solution)

Expansion

$$C(x) = c^2 + 4 \sum_{i,j} Q_{ij} x_i x_j + 4c \sum_{i,j} x_i x_j$$

Linear Terms \rightarrow

$$C(x) = c^2 + 4 \sum_{i,j} Q_{ij} x_i x_j + 4c \sum_{i,j} x_i x_j$$

Quadratic Terms \rightarrow

$$C(x) = c^2 + 4 \sum_{i,j} Q_{ij} x_i x_j + 4c \sum_{i,j} x_i x_j$$

Constant Term (Square of the sum)

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④ QUBO instances can be seen as 1-1 correspondence with Ising models.

Eg. mapping (Sec 2 - 05 paper arXiv:2401.06989v1)

$$\text{Ising model} \Rightarrow H(\sigma) = - \sum_{i,j} J_{ij} \sigma_i \sigma_j - \sum_i h_i \sigma_i, \sigma_i \in \{-1,1\}$$

Interaction External mag field

$$z_i = 2x_i - 1 \Leftrightarrow x_i = \frac{z_i + 1}{2}$$

So we need to find H_c such that

$$H_c(x) = C(x) |x\rangle$$

We have defined the Cost function above, so we just need to substitute H_c

$$C(x) = 4 \sum_{i,j} s_i s_j x_i x_j + 4 \sum_{i,j} s_i (b_i - c) x_i \quad (\text{Ignoring } c^2), \quad S = [s_1, \dots, s_n] \rightarrow \text{array}$$

$$\therefore H_c = 4 \sum_{i,j} s_i s_j \frac{(z_i + 1)}{2} \frac{(z_j + 1)}{2} + 4 \sum_{i,j} s_i (b_i - c) \frac{(z_i + 1)}{2}$$

$$= \sum_{i,j} s_i s_j z_i z_j + 2 \sum_{i,j} s_i s_j z_i + 2 \sum_{i,j} s_i (b_i - c) z_i + \sum_{i,j} s_i x_i + 2 \sum_{i,j} s_i$$

$$H_c = \sum_{i,j} s_i s_j z_i z_j + 2 \sum_{i,j} \left(s_i (b_i - c) + \sum_{j=1}^n s_j \right) z_i + \text{Constants}$$

or in general for

$$C(x) = \sum_{i,j=1}^n x_i Q_{ij} x_j + \sum_{i=1}^n c_i x_i$$

$$H_c = \sum_{i,j=1}^n \frac{1}{4} Q_{ij} z_i z_j - \sum_{i=1}^n \frac{1}{2} \left(c_i + \sum_{j=1}^n Q_{ij} \right) z_i + \left(\sum_{i,j=1}^n \frac{Q_{ij}}{4} + \sum_{i=1}^n \frac{c_i}{2} \right)$$

⑤ Adiabatic Theorem - Max Born + Vladimir Fock (1928)

"A physical system remains in its instantaneous eigenstate if a given perturbation is acting slowly enough and there is a gap between the eigenvalue and the rest of the Hamiltonian's spectrum."

Eg. If we are in ground state $|0\rangle$ of H_0 then
at T we will be in the ground state of H_T ($|0'\rangle$)
given that the perturbation is slow.
(Change)

Ideally $T = t_1 - t_0 \rightarrow \infty$