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Let A denote the nodes in X , B denotes the nodes in \bar{X} .

1.

Let v denotes the vertex in V_1 . Maximum total weight :

$$W_1(A, B) = \begin{cases} \sum_{u,v \in E} w(u, v) & \text{include } v \text{ in } A \\ 0 & \text{do not include } v \text{ in } A \end{cases}$$

Consider only V_1 , there are only two situations, put v in A or not. when v is put in A , then its maximum total weight is the weight sum of all eadges connected to v . If we put v in B , then A is empty set at this moment with the total weight 0. Thus, the maximun total weight over all partitions is $\sum_{u,v \in E} w(u, v)$.

2.

$V_{i+1} = V_i \cup \{v\}$:

$$OPT_{i+1}(A, B) = \begin{cases} OPT_i(A \setminus \{v\}, B \cup \{v\}) + \sum_{(u,v) \in E, u \notin A} w(u, v) - \sum_{(u,v) \in E, u \in A} w(u, v) & \text{include } v \text{ in } A \\ OPT_i(A, B) & \text{do not include } v \text{ in } A \end{cases}$$

As V_{i+1} has one more vertex than V_i , we only need to consider whether to put v in A or put v in B . If we put v in A , then we need to delete weight of edges between (u,v) where u already in A . In addition, we need to add weight of edges (u,v) where u in B . If we put v in B , then the result remains the same as node i , then we need to do nothing.

3.

$V_{i+1} = V_i \setminus \{v\}$:

$$OPT_{i+1}(A, B) = \max\{OPT_i(A, B), OPT_i(A \cup \{v\}, B \setminus \{v\})\}$$

In this case, V_{i+1} do not introduce new vertex, thus we only need discuss the already-existed partitions. As V_i do not contain vertex v , the optimal results can be generated by comparing maximum total weight between the exsiting partitions include v and exclude v .

4.

Let $f_i(A, B)$ denotes $OPT(A, B)$. The psuedocode of algorithms is:

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function MAXWEIGHT
  Root T at node r
  for each node t of T in post-order do
    if t is leaf node then
      for each partition (A,B) of  $V_t$  do
         $f_t(A, B) = W_t(A, B)$ 
      end for
    else
      if  $|V_t| > |V_{t-1}|$  then
        for each partition (A,B) of  $V_t$  do
           $f_t(A, B) = W_t(A, B)$ 
        end for
      else
        Let v denote the vertex in node  $V_{t-1}$  but not in node  $V_t$ 
        for each partition (A,B) of  $V_t$  do
           $f_t(A, B) = \max\{f_{t-1}(A, B), f_{t-1}(A \cup \{v\}, B \setminus \{v\})\}$ 
        end for
      end if
    end if
  end for
  return  $\max\{f_r(A, B) : \text{each partition } (A, B) \text{ of } V_r\}$ 
end function

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5.

As the width of the tree is k, the biggest node contains k+1 vertices. Thus, there are at most 2^{k+1} different partitions in each node. Also, there are r different tree node.

Therefore, the space complexity is $O(r \cdot 2^{k+1})$.

6.

In a path decomposition, we have r nodes, where there are $\frac{r}{2}$ introduce nodes and $\frac{r}{2}$ forget nodes.

For each introduce node, we need calculate $W_i(A, B)$, which requires $O(n)$ time for checking edges and getting weights. This needs to be done for at most 2^{k+1} different partitions for each node. Therefore, $O(\frac{r}{2} n 2^{k+1})$ time is need for all introduce nodes in the worst case.

For each forget node, we need to do at most 2^k compararations of partitions pairs with v and without v. Thus, the worst case for dealing with all forget nodes will need time $O(\frac{r}{2} 2^k)$.

In conclusion, the time complexity is $O(\frac{r}{2} n 2^{k+1} + \frac{r}{2} 2^k)$, which is simplified as $O(n \cdot r \cdot 2^k)$.