

# THE CONVERSE ENVELOPE THEOREM

Ludvig Sinander  
University of Oxford

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Envelope theorem: optimal decision-making  $\implies$   $\boxtimes$  formula.

Textbook intuition:  $\boxtimes$  formula  $\iff$  FOC.

Modern envelope theorem of MS02:<sup>\*</sup> almost no assumptions.

$\hookrightarrow$  FOC ill-defined, so need different intuition.

My theorem: with almost no assumptions,  
 $\boxtimes$  formula equivalent to generalised FOC.

- an envelope theorem: FOC  $\implies$   $\boxtimes$
- a converse:  $\boxtimes \implies$  FOC.

Application to mechanism design.

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\*Milgrom, P., & Segal, I. (2002). Envelope theorems for arbitrary choice sets. *Econometrica*, 70(2), 583–601. <https://doi.org/10.1111/1468-0262.00296>

# Setting

Agent chooses action  $x$  from a set  $\mathcal{X}$ .

Objective  $f(x, t)$ , where  $t \in [0, 1]$  is a parameter.

No assumptions on  $\mathcal{X}$ , almost none on  $f$ :

- (1)  $f(x, \cdot)$  differentiable for each  $x \in \mathcal{X}$
- (2)  $\{f(x, \cdot)\}_{x \in \mathcal{X}}$  absolutely equi-continuous. (def'n: slide 17)
  - a sufficient condition (maintained by MS02):
    - (a)  $f(x, \cdot)$  absolutely continuous  $\forall x \in \mathcal{X}$ , and
    - (b)  $t \mapsto \sup_{x \in \mathcal{X}} |f_2(x, t)|$  dominated by an integrable f'n.
  - a stronger sufficient condition:  $f_2$  bounded.

*Decision rule:* a map  $X : [0, 1] \rightarrow \mathcal{X}$ .

*Associated value function:*  $V_X(t) := f(X(t), t)$ .

# Envelope theorem

$X$  satisfies the  $\boxtimes$  formula iff

$$V_X(t) = V_X(0) + \int_0^t f_2(X(s), s) ds \quad \text{for every } t \in [0, 1].$$

Equivalently:  $V_X$  is absolutely continuous and

$$V'_X(t) = f_2(X(t), t) \quad \text{for a.e. } t \in (0, 1).$$

$X$  is optimal iff for every  $t$ ,  $X(t)$  maximises  $f(\cdot, t)$ .

**Modern envelope theorem (MS02).**<sup>†</sup>

Any optimal decision rule satisfies the  $\boxtimes$  formula.

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<sup>†</sup>Really a slight refinement of MS02.

# Textbook intuition

Differentiation identity for  $V_X(t) := f(X(t), t)$ :

$$V'_X(t) = \underbrace{\frac{d}{dm} f(X(t+m), t) \Big|_{m=0}}_{\text{'indirect effect'}} + \underbrace{f_2(X(t), t)}_{\text{'direct effect'}}.$$

*Indirect effect:*  $t$ 's gain from mimicking  $t + m$  (for small  $m$ ).

$$\begin{aligned} \text{indirect effect} &= 0 && (\text{FOC}) \\ \iff V'_X(t) &= \text{direct effect} && (\boxtimes \text{ formula}). \end{aligned}$$

*Problem:* ‘indirect effect’ (hence FOC) ill-defined!

- $f(\cdot, t)$  &  $X$  need not be differentiable.
- actions  $\mathcal{X}$  need have no convex or topological structure.

# The outer first-order condition

*Disjuncture:* in general,  $\boxtimes$  formula  $\Leftrightarrow$  FOC.

- one solution: add strong ‘classical’ assumptions. (slide 18)
- my solution: find the correct FOC!

Decision rule  $X$  satisfies the outer FOC iff

$$\frac{d}{dm} \int_r^t f(X(s+m), s) ds \Big|_{m=0} = 0 \quad \text{for all } r, t \in (0, 1).$$

Motivation: given decision rule  $X : [0, 1] \rightarrow \mathcal{X}$ ,

- type  $s$  can ‘mimic’  $s + m$  by choosing  $X(s + m)$ .
- oFOC: if types  $s \in [r, t]$  do this,  
it’s collectively unprofitable (to first order).

# Housekeeping

**Housekeeping lemma.** Under classical assump'ns,  
oFOC  $\iff$  classical FOC.

(sketch proof: slide 19)

**Necessity lemma.** Any optimal decision rule  $X$   
satisfies oFOC & has  $V_X(t) := f(X(t), t)$  absolutely continuous.

(sketch proof: slide 20)

# Main theorem

**Envelope theorem & converse.**

For a decision rule  $X : [0, 1] \rightarrow \mathcal{X}$ , the following are equivalent:

- (1)  $X$  satisfies the oFOC

$$\frac{d}{dm} \int_r^t f(X(s+m), s) ds \Big|_{m=0} = 0 \quad \text{for all } r, t \in (0, 1),$$

and  $V_X(t) := f(X(t), t)$  is absolutely continuous.

- (2)  $X$  satisfies the  $\boxtimes$  formula

$$V_X(t) = V_X(0) + \int_0^t f_2(X(s), s) ds \quad \text{for every } t \in [0, 1].$$

# Main theorem

**Envelope theorem & converse.** For  $X : [0, 1] \rightarrow \mathcal{X}$ , TFAE:

- (1)  $X$  satisfies the oFOC, &  $V_X(t) := f(X(t), t)$  is AC.
  - (2)  $X$  satisfies the  $\boxtimes$  formula.
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$\implies$ : an envelope theorem.

Implies the MS02 envelope theorem.

$\Leftarrow$ : converse envelope theorem.

# The key lemma

Textbook intuition relied on differentiation identity

$$V'_X(s) = \underbrace{\frac{d}{dm} f(X(s+m), s) \Big|_{m=0}}_{\text{'indirect effect'}} + \underbrace{f_2(X(s), s)}_{\text{'direct effect'}}$$

or (integrated & rearranged)

$$\int_r^t \frac{d}{dm} f(X(s+m), s) \Big|_{m=0} ds = V_X(t) - V_X(r) - \int_r^t f_2(X(s), s) ds.$$

The ‘outer’ version is valid:

**Identity lemma.** If  $V_X$  is AC, then

$$\frac{d}{dm} \int_r^t f(X(s+m), s) ds \Big|_{m=0} = V_X(t) - V_X(r) - \int_r^t f_2(X(s), s) ds.$$

(Where both sides are well-defined.)

(sketch proof: slide 21)

(proof of th'm: slide 24)

# Application: environment

Agent with preferences  $f(y, p, t)$  over outcome  $y \in \mathcal{Y}$  and payment  $p \in \mathbf{R}$ .

- $\mathcal{Y}$  partially ordered
- type  $t \in [0, 1]$  is agent's private info
- assume single-crossing.

An *allocation* is  $Y : [0, 1] \rightarrow \mathcal{Y}$ .

$Y$  is *implementable* iff  $\exists$  payment rule  $P : [0, 1] \rightarrow \mathbf{R}$  s.t.  $(Y, P)$  is incentive-compatible.

# Application: goal

Classical result: implementable  $\iff$  increasing.

' $\iff$ ' is the substantial part. Versions: (lit: slide 25)

	literature	this paper
outcomes $\mathcal{Y}$	$\subseteq \mathbf{R}$	general
preferences $f$	quasi-linear	general.

# Application: result

**Implementability theorem.** Under regularity assumptions, any increasing allocation is implementable.

Argument:

- fix an increasing allocation  $Y : [0, 1] \rightarrow \mathcal{Y}$
- choose a payment rule  $P$  so that  $\boxtimes$  formula holds
- then by *converse envelope theorem*, oFOC holds  
 $\iff$  mechanism  $(Y, P)$  is locally IC.
- finally, local IC  $\implies$  global IC by single-crossing.

# Application: example

Monopolist selling information.

Outcomes  $\mathcal{Y}$ :  
distributions of posterior beliefs, ordered by Blackwell.

By the implementability theorem,  
any Blackwell-increasing information allocation  
can be implemented.

# Application: details

*Regular  $\mathcal{Y}$ :* ‘rich’ & ‘not too large’. (def’n: slide 26)

Examples:

- $\mathbf{R}^n$  ordered by ‘coordinate-wise smaller’
- finite-expectation RVs ordered by ‘a.s. smaller’
- distributions of posteriors updated from a given prior ordered by Blackwell.

*Regular  $f$ :* (def’n: slide 27)

- (a) type derivative  $f_3$  exists, bounded, continuous in  $p$ .
- (b)  $f$  jointly continuous (when  $\mathcal{Y}$  has order topology).

*Single-crossing  $f$ :* (def’n: slide 28)  
if type  $t$  willing to pay to increase  $y \in \mathcal{Y}$ , then so is type  $t' > t$ .

Thanks!



# Absolute equi-continuity

A family  $\{\phi_x\}_{x \in \mathcal{X}}$  of functions  $[0, 1] \rightarrow \mathbf{R}$  is *AEC* iff the family

$$\left\{ t \mapsto \sup_{x \in \mathcal{X}} \left| \frac{\phi_x(t+m) - \phi_x(t)}{m} \right| \right\}_{m>0} \text{ is uniformly integrable.}$$

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Name inspired by the following (Fitzpatrick & Hunt, 2015):

**AC–UI lemma.** A continuous  $\phi : [0, 1] \rightarrow \mathbf{R}$  is AC iff

$$\left\{ t \mapsto \frac{\phi(t+m) - \phi(t)}{m} \right\}_{m>0} \text{ is uniformly integrable.}$$

As name ‘AEC’ suggests, an AEC family

- is (uniformly) equi-continuous
- has AC functions as its members.

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# The classical approach

*Classical assumptions:*

- $\mathcal{X}$  is a convex subset of  $\mathbf{R}^n$
- action derivative  $f_1$  exists & is bounded
- only Lipschitz continuous decision rules  $X$  are considered.

(Bad for applications. Especially the Lipschitz restriction!)

$\implies$  ‘mimicking payoff’  $m \mapsto f(X(t+m), t)$  diff’able a.e.

$\implies$  FOC well-defined, differentiation identity valid.

Thus  $\boxtimes$  formula  $\iff$  FOC.

$\hookrightarrow$  back to slide 6

# Sketch proof of the housekeeping lemma

**Housekeeping lemma.** Under classical assump'ns,  
oFOC  $\iff$  classical FOC.

*Sketch proof.* Fix a decision rule  $X : [0, 1] \rightarrow \mathcal{X}$ .

Classical assump'ns & Vitali convergence theorem:

$$\underbrace{\frac{d}{dm} \int_r^t f(X(s+m), s) ds}_{= 0 \text{ for all } r, t \text{ iff oFOC holds}} \Big|_{m=0} = \underbrace{\int_r^t \frac{d}{dm} f(X(s+m), s) \Big|_{m=0} ds}_{= 0 \text{ for all } r, t \text{ iff classical FOC holds.}}$$



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# Sketch proof of the necessity lemma

**Necessity lemma.** Any optimal decision rule  $X$  satisfies the oFOC & has  $V_X(t) := f(X(t), t)$  AC.

*Sketch proof.*  $X$  optimal &  $\{f(x, \cdot)\}_{x \in \mathcal{X}}$  AEC  $\implies V_X$  AC.

Since  $X$  optimal, have for any  $s$  and  $m > 0 > m'$  that

$$\frac{f(X(s+m), s) - f(X(s), s)}{m} \leq 0 \leq \frac{f(X(s+m'), s) - f(X(s), s)}{m'}.$$

Integrating over  $(r, t)$  and letting  $m, m' \rightarrow 0$ ,

both sides (in fact) converge to same limit:

$$\frac{d}{dm} \int_r^t f(X(s+m), s) ds \Big|_{m=0} \leq 0 \leq \frac{d}{dm} \int_r^t f(X(s+m'), s) ds \Big|_{m=0}. \blacksquare$$

## Sketch proof of the identity lemma I

For  $m > 0$ , write

$$\begin{aligned} & \left. \frac{V_X(t+m) - V_X(t)}{m} \right\} =: \phi_m(t) \\ = & \left. \frac{f(X(t+m), t+m) - f(X(t+m), t)}{m} \right\} =: \psi_m(t) \\ + & \left. \frac{f(X(t+m), t) - f(X(t), t)}{m} \right\} =: \chi_m(t). \end{aligned}$$

$$\lim_{m \downarrow 0} \int_r^t \chi_m = \frac{d}{dm} \int_r^t f(X(s+m), s) ds \Big|_{m=0} \quad \text{if limit exists.}$$

Must show: limit exists & equals

$$V_X(t) - V_X(r) - \int_r^t f_2(X(s), s) ds.$$

## Sketch proof of the identity lemma II

$$\begin{aligned}
 & \left. \frac{V_X(t+m) - V_X(t)}{m} \right\} =: \phi_m(t) \\
 = & \left. \frac{f(X(t+m), t+m) - f(X(t+m), t)}{m} \right\} =: \psi_m(t) \\
 + & \left. \frac{f(X(t+m), t) - f(X(t), t)}{m} \right\} =: \chi_m(t).
 \end{aligned}$$


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$\{\psi_m\}_{m>0}$  need not converge a.e. (Even with strong assump'ns.)

But consider  $\psi_m^*(t) := \frac{f(X(t), t) - f(X(t), t-m)}{m}$ .

$\{\psi_m^*\}_{m>0}$  is UI & converges pointwise to  $t \mapsto f_2(X(t), t)$ . And

$$\begin{aligned}
 \int_r^t \psi_m &= \int_{r+m}^{t+m} \psi_m^* = \int_r^t \psi_m^* + \left( \int_t^{t+m} \psi_m^* - \int_r^{r+m} \psi_m^* \right) \\
 &= \int_r^t \psi_m^* + o(1) \quad \text{by UI.}
 \end{aligned}$$

# Sketch proof of the identity lemma III

$$\begin{aligned}
 & \left. \frac{V_X(t+m) - V_X(t)}{m} \right\} =: \phi_m(t) \\
 = & \left. \frac{f(X(t+m), t+m) - f(X(t+m), t)}{m} \right\} =: \psi_m(t) \\
 + & \left. \frac{f(X(t+m), t) - f(X(t), t)}{m} \right\} =: \chi_m(t).
 \end{aligned}$$

$\int_r^t \psi_m = \int_r^t \psi_m^\star + o(1)$ ,  $\{\psi_m^\star\}_{m>0}$  UI & converges pointwise to  $t \mapsto f_2(X(t), t)$ .

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$V_X$  AC  $\implies \{\phi_m\}_{m>0}$  UI & converges a.e. to  $V'_X$ . So

$$\begin{aligned}
 \lim_{m \downarrow 0} \int_r^t \chi_m &= \lim_{m \downarrow 0} \int_r^t [\phi_m - \psi_m] = \lim_{m \downarrow 0} \int_r^t [\phi_m - \psi_m^\star] \\
 (\text{Vitali}) &= \int_r^t \lim_{m \downarrow 0} [\phi_m - \psi_m^\star] = \int_r^t [V'_X(s) - f_2(X(s), s)] ds \\
 (\text{FToC}) &= V_X(t) - V_X(r) - \int_r^t f_2(X(s), s) ds.
 \end{aligned}$$

# Proof of the main theorem

**Identity lemma.** If  $V_X$  is AC, then

$$\underbrace{\frac{d}{dm} \int_r^t f(X(s+m), s) ds \Big|_{m=0}}_{\begin{array}{c} = 0 \text{ for all } r, t \\ \text{iff oFOC holds.} \end{array}} = \underbrace{V_X(t) - V_X(r) - \int_r^t f_2(X(s), s) ds}_{\begin{array}{c} = 0 \text{ for all } r, t \\ \text{iff } \boxtimes \text{ formula holds.} \end{array}}.$$

*Proof of main theorem.*  $X$  satisfies the oFOC &  $V_X$  is AC  
 $\implies$  identity lemma applies. So oFOC  $\implies$   $\boxtimes$  formula.

$X$  satisfies the  $\boxtimes$  formula  $\implies V_X$  is AC (by Lebesgue's FToC)  
 $\implies$  identity lemma applies. So  $\boxtimes$  formula  $\implies$  oFOC. ■

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# Application: existing results

- $\mathcal{Y} \subseteq \mathbf{R}$ 
  - classical assump'ns  $\left\{ \begin{array}{l} \text{Mirrlees (1976), Spence (1974),} \\ \text{Guesnerie and Laffont (1984)} \end{array} \right.$
  - no classical assump'ns Nöldeke and Samuelson (2018)
- general  $\mathcal{Y}$ 
  - quasi-linear  $f$   $\left\{ \begin{array}{l} \text{Matthews and Moore (1987),} \\ \text{García (2005)} \end{array} \right.$
  - general  $f$  this paper.

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# Application: outcome regularity

A set  $\mathcal{A}$  partially ordered by  $\lesssim$  is

- (1) *order-dense-in-itself* iff for any  $a < a'$  in  $\mathcal{A}$ ,  
there is a  $b \in \mathcal{A}$  such that  $a < b < a'$ ,
- (2) *chain-separable* iff for each chain  $C \subseteq \mathcal{A}$ ,  
there is a countable set  $B \subseteq \mathcal{A}$  that is order-dense in  $C$ ,<sup>‡</sup>
- (3) *countably chain-complete* iff every countable chain in  $\mathcal{A}$   
with a lower (upper) bound in  $\mathcal{A}$   
has an infimum (a supremum) in  $\mathcal{A}$ .

(1) & (2):  $\mathcal{A}$  ‘rich’. (3):  $\mathcal{A}$  ‘not too large’.

**Definition.**  $\mathcal{Y}$  is *regular* iff it satisfies properties (1)–(3).

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<sup>‡</sup> $B \subseteq \mathcal{A}$  is *order-dense* iff for any  $a < a'$  in  $\mathcal{A}$ ,  $\exists b \in B$  s.t.  $a \lesssim b \lesssim a'$ .

# Application: preference regularity

*Order topology* on a set  $\mathcal{A}$  partially ordered by  $\lesssim$ :  
the topology generated by the open order rays

$$\{b \in \mathcal{A} : b < a\} \quad \text{and} \quad \{b \in \mathcal{A} : a < b\}.$$

**Definition.**  $f$  is *regular* iff

- (a) type derivative  $f_3$  exists & is bounded & continuous in  $p$
- (b) for any chain  $\mathcal{C} \subseteq \mathcal{Y}$ ,  $f$  jointly continuous on  $\mathcal{C} \times \mathbf{R} \times [0, 1]$   
when  $\mathcal{C}$  has relative top'gy inherited from order top'gy on  $\mathcal{Y}$ .

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# Application: single-crossing

**Definition.** For  $\phi : [0, 1] \rightarrow \mathbf{R}$ , upper & lower derivatives

$$\begin{aligned} D^* \phi(t) &:= \limsup_{m \rightarrow 0} \frac{\phi(t + m) - \phi(t)}{m} \\ D_* \phi(t) &:= \liminf_{m \rightarrow 0} \frac{\phi(t + m) - \phi(t)}{m}. \end{aligned}$$

Partial upper/lower derivatives:  $(D^*)_i$  &  $(D_*)_i$ .

**Definition.**  $f$  is *single-crossing* iff

for any increasing  $Y : [0, 1] \rightarrow \mathcal{Y}$  & any  $P : [0, 1] \rightarrow \mathbf{R}$ ,  
mis-reporting payoff  $U(r, t) := f(Y(r), P(r), t)$  satisfies

$$\begin{aligned} (D^*)_1 U(t, t) \geq 0 \quad \text{implies} \quad (D_*)_1 U(t, t') > 0 &\quad \text{for } t' > t \\ \text{and} \quad (D_*)_1 U(t, t) \leq 0 \quad \text{implies} \quad (D^*)_1 U(t, t') < 0 &\quad \text{for } t' < t. \end{aligned}$$

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