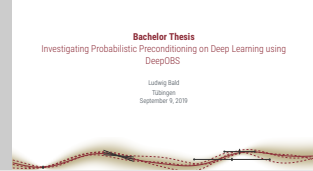


Bachelor Thesis

Investigating Probabilistic Preconditioning on Deep Learning using DeepOBS

Ludwig Bald
Tübingen
September 9, 2019

2019-09-09



- Introduce myself, I study Cognitive Science
- I chose this topic because I wanted to get to know deep learning from the inside. I had never done Deep Learning before and wanted to learn it hands-on.
- In this talk I will talk about the science, but also about the process I used.
- If you have questions during the talk, ask them right away!

Definition ¹

"A computer program is said to learn from **experience E** with respect to some class of **tasks T** and **performance measure P** if its performance at tasks in T, as measured by P, improves with experience E"

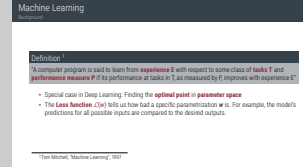
- ✦ Special case in Deep Learning: Finding the **optimal point** in **parameter space**
- ✦ The **Loss function** $\mathcal{L}(w)$ tells us how bad a specific parametrization w is. For example, the model's predictions for all possible inputs are compared to the desired outputs.

¹Tom Mitchell, "Machine Learning", 1997

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└ Background

└ Machine Learning



- Most of you will have seen this definition before.
- As an example, have a look at this 2-parametrical problem

Gradient Descent

Optimization

Gradient Descent uses knowledge of the **gradient** at a point in parameter space to take an update step:

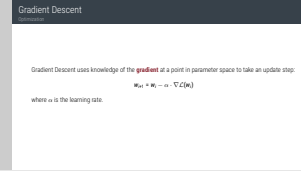
$$\mathbf{w}_{i+1} = \mathbf{w}_i - \alpha \cdot \nabla \mathcal{L}(\mathbf{w}_i)$$

where α is the learning rate.

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└ Background

└ Gradient Descent



Stochastic Gradient Descent

Optimization

- ✦ In real life, we have Big Data. The true $\nabla \mathcal{L}(\mathbf{w})$ is expensive to compute.
- ✦ To speed things up, we compute the noisy estimate $\hat{\mathcal{L}}(\mathbf{w}_i)$ on a minibatch of for example 128 data points.

The update rule still looks the same:

$$\mathbf{w}_{i+1} = \mathbf{w}_i - \alpha \cdot \nabla \hat{\mathcal{L}}(\mathbf{w}_i)$$

where α is the learning rate.

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└ Background

└ Stochastic Gradient Descent

Stochastic Gradient Descent

Optimization

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where α is the learning rate.

Preconditioning

The condition number of the Hessian

- ✦ The performance of (S)GD depends heavily on the shape of the loss landscape
- ✦ The **condition number** is defined as

$$\kappa = \frac{\lambda_n}{\lambda_1} > 1$$

where λ_n, λ_1 are the largest/smallest eigenvalues of the Hessian $\nabla\nabla\mathcal{L}(\mathbf{w})$

- ✦ For larger κ , (S)GD can converge slower.
- ✦ The condition number can be changed by carefully rescaling the gradient before taking the optimization step

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└ Background

└ Preconditioning

Preconditioning
The condition number of the Hessian

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Probabilistic Preconditioning

by Filip & Philipp, 2019

In the stochastic (minibatched) setting and while only having access to **Hessian-vector products**, it isn't obvious how to construct the preconditioner. This is the method I'm testing:

1. Empirically construct a prior for the multivariate Gaussian distribution and set the learning rate for SGD
2. Gather observations and update the posterior estimate for the Hessian, using Bayes
3. Create a rank-2 approximation of the Preconditioner
4. apply the preconditioner at every step and do SGD

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└ Background

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If I'm grossly misrepresenting the algorithm, please correct me now! For an exact description check out the paper

For the purposes of this talk, a neural net is a model

- ✦ with many (> hundreds of thousands) parameters, weights \mathbf{w}
- ✦ with an available noisy gradient $\nabla \hat{\mathcal{L}}(\mathbf{w}_0)$, which was obtained by backpropagation

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└ Background

└ Deep learning

Deep learning

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Evaluating an Optimizer

Empirically

This is a hard problem in itself! How do you chose:

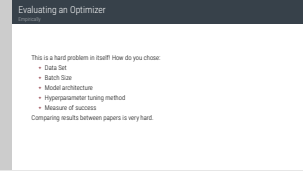
- ✦ Data Set
- ✦ Batch Size
- ✦ Model architecture
- ✦ Hyperparameter tuning method
- ✦ Measure of success

Comparing results between papers is very hard.

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└─ Approach

└─ Evaluating an Optimizer



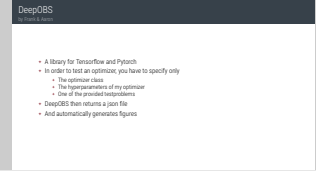
Now that we have roughly defined the algorithm, how do we test it?

- ✦ A library for Tensorflow and Pytorch
- ✦ In order to test an optimizer, you have to specify only
 - ✦ The optimizer class
 - ✦ The hyperparameters of my optimizer
 - ✦ One of the provided testproblems
- ✦ DeepOBS then returns a json file
- ✦ And automatically generates figures

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└─ Approach

└─ DeepOBS



Implementation Details

The class Preconditioner

```
Preconditioner(params, est_rank=2, num_observations=5, prior_iterations=10,  
               weight_decay=0, lr=None,  
               optim_class=torch.optim.SGD, **optim_hyperparams)  
start_estimate()  
step()  
get_log()
```

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└─ Approach

└─ Implementation Details

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How to use the TCML Cluster

Cloud Computing

1. Request an account by sending an email
2. If you have any special code requirements, build a Singularity container (kind of like a virtual machine). Alternatively use a provided one.
3. Create & Submit a Slurm Batch job file
4. Get an e-mail when your jobs start of finish
5. Download the output files to your local machine. You can mount the cluster as a virtual drive.

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└─ Approach

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Experiments

Overview

- ✦ Effectiveness of Preconditioning
- ✦ Computational Complexity
- ✦ Stability
- ✦ Learning Rate sensitivity

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└ Experiments + Results + Discussion

└ Experiments

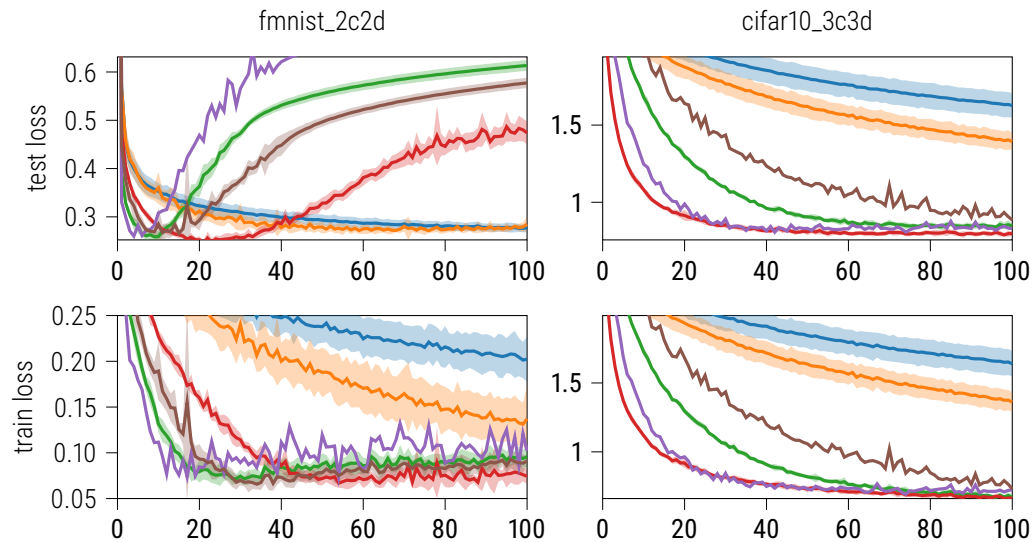
Experiments
Overview

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Effectiveness of Preconditioning

AdaptiveSGD

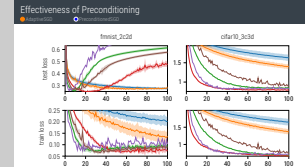
PreconditionedSGD



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Experiments + Results + Discussion

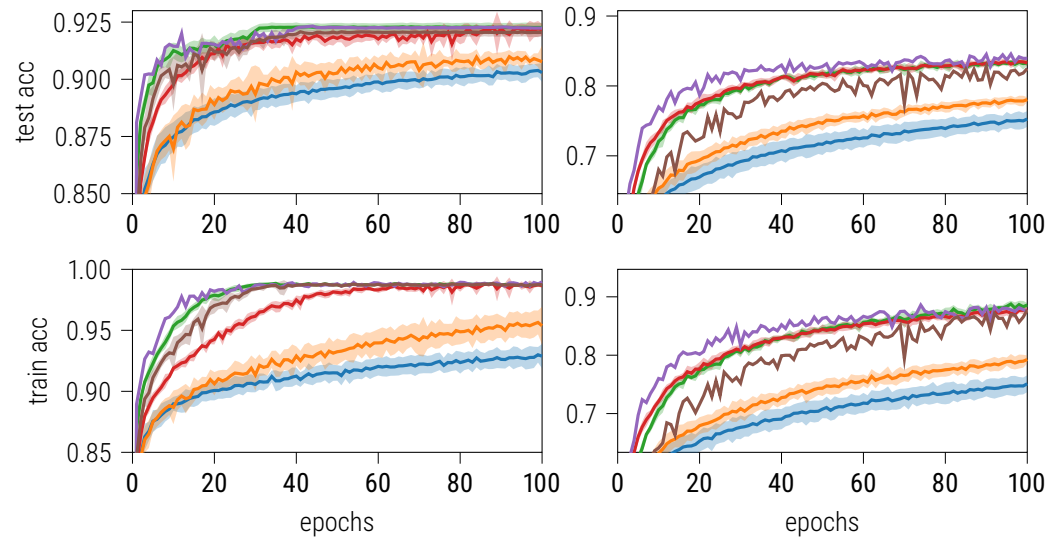
Effectiveness of Preconditioning



Effectiveness of Preconditioning

AdaptiveSGD

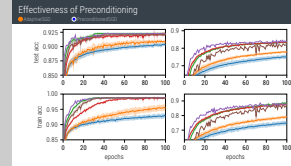
PreconditionedSGD



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Experiments + Results + Discussion

Effectiveness of Preconditioning



Discussion: Effectiveness

Why might it be worse than plain SGD?

- ✦ It's very noisy: Noise from the Hessian is amplified through the whole epoch.
- ✦ The constructed learning rate is not optimal
- ✦ PreconditionedSGD is worse than AdaptiveSGD, so the Preconditioning makes things worse
- ✦ The preconditioner has only rank 2, while there might be thousands large eigenvalues (usually 10%)
- ✦ The other optimizers are exhaustively tuned
- ✦ The other optimizers use more data for actual parameter updates: 1920/50.000 images per epoch are only used for the Hessian

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└ Experiments + Results + Discussion

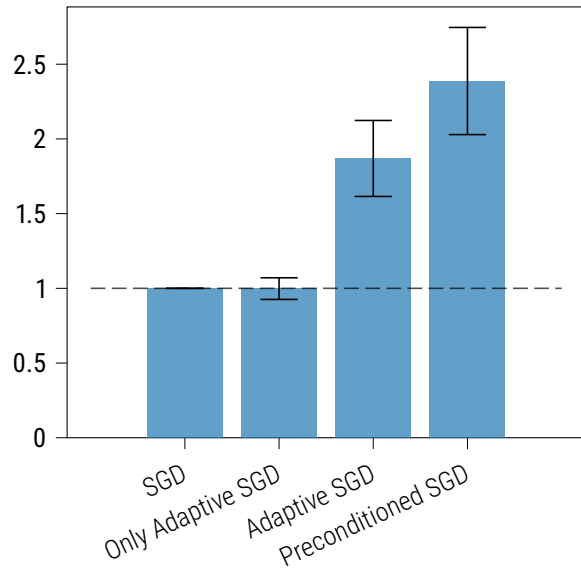
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Performance penalty

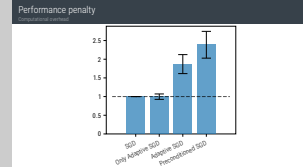
Computational overhead

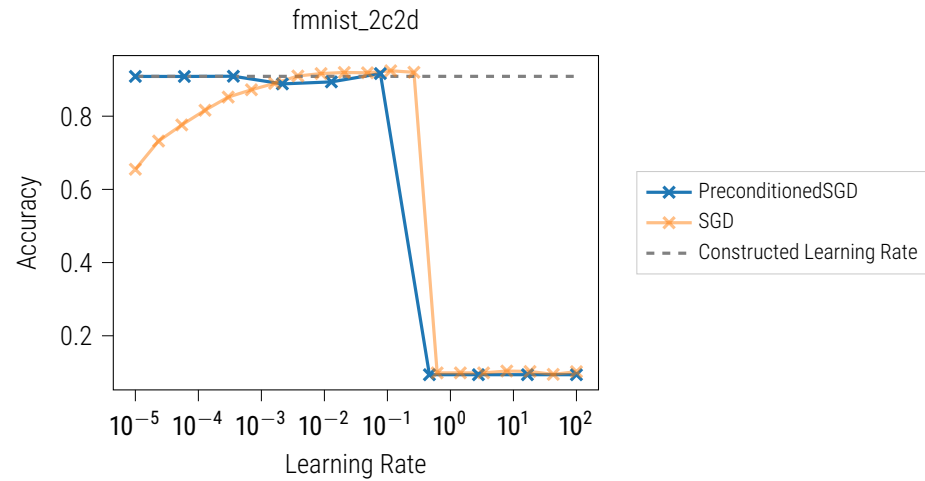
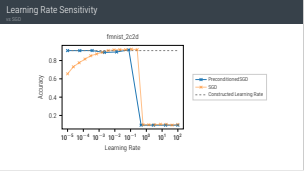


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└ Experiments + Results + Discussion

└ Performance penalty





Conclusion/Final Remarks

- └ Experiments + Results + Discussion
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Conclusion/Final Remarks

end of presentation

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└ Experiments + Results + Discussion