# An Introduction To Algebraic Topology

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### 1 Introduction

#### 1.1 Notation

$$I = [0, 1].$$

$$S^n = \{ x \in \mathbb{R}^{n+1} \mid ||x|| = 1 \}$$

 $S^n$  is called the n-sphere.  $S^n \subset \mathbb{R}^{n+1}$  ( $S^1$  is the circle); 0-sphere  $S^0$  consists of the two points  $\{-1,1\}$  and hence is a discrete two-point space. We may regard  $S^n$  as the **equator** of  $S^{n+1}$ 

$$S^n = \mathbb{R}^{n+1} \cap S^{n+1} = \{(x_1, \dots, x_{n+2}) \in S^{n+1} : x_{n+2} = 0\}$$

The **north pole** is  $(0,0,\dots,0,1)\in S^n$ ; the **south pole** is  $(0,0,\dots,0,-1)$ . The **antipode** of  $x=(x_1,\dots,x_{n+1})\in S^n$  is the other endpoint of the diameter

having one endpoint x; thus the antipode of x is  $-x = (-x_1, \dots, -x_{n+1})$ , for the distance from -x to x is 2.

$$D^n = \{ x \in \mathbb{R}^n \mid ||x|| \le 1 \}$$

 $D^n$  is called the n-disk (or n-ball). Observe that  $S^{n-1} \subset D^n \subset \mathbb{R}^n$ ; indeed  $S^{n-1}$  is the boundary of  $D^n$  in  $\mathbb{R}^n$ 

$$\Delta^n = \{(x_1,\ldots,x_{n+1}) \in \mathbb{R}^{n+1}: \text{ each } x_i \geq 0 \text{ and } \sum x_i = 1\}$$

 $\Delta^n$  is called the **standard** *n***-simplex**.  $\Delta^0$  is a point,  $\Delta^1$  is a closed interval,  $\Delta^2$  is a triangle (with interior),  $\Delta^3$  is a (solid) tetrahedron, and so on.

There is a standard homeomorphism from  $S^n$  - {north pole} to  $\mathbb{R}^n$ , called **stereographic projection**. Denote the north pole by N, and define  $\sigma: S^n - \{N\} \to \mathbb{R}^n$  to be the intersection of  $\mathbb{R}^n$  and the line joining x and N. Points on the latter line have the form tx + (1-t)N, hence they have coordinates  $(tx_1, \ldots, tx_n, tx_{n+1} + (1-t))$ . The last coordinate is zero for  $t = (1-x_{n+1})^{-1}$ ; hence

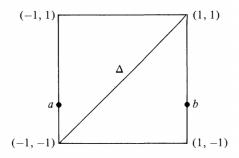
$$\sigma(x) = (tx_1, \dots, tx_n)$$

where  $t = (1 - x_{n+1})^{-1}$ . It is now routine to check that  $\sigma$  is indeed a homeomorphism. Note that  $\sigma(x) = x$  iff x lies on the equator  $S^{n-1}$ 

### 1.2 Brouwer Fixed Point Theorem

**Theorem 1.1.** Every continuous  $f: D^1 \to D^1$  has a fixed point

*Proof.* Let f(-1) = a and f(1) = b. If either f(-1) = -1 or f(1) = 1, we are done. Therefore we may assume that f(-1) = a > -1 and that f(1) = b < 1 as drawn. If G is the graph of f and  $\Delta$  is the graph of the identity



function, then we must prove that  $G \cap \Delta \neq \emptyset$ . The idea is to use a connectness argument to show that every path in  $D^1 \times D^1$  from a to b must cross  $\Delta$ .

Since f is continuous,  $G = \{(x, f(x)) : x \in D^1\}$  is connected (continuous image of connected space is connected). Define  $A = \{(x, f(x)) : f(x) > x\}$  and  $B = \{(x, f(x)) : f(x) < x\}$ . Note that  $a \in A$  and  $b \in B$ , so that  $A \neq \emptyset$  and  $B \neq \emptyset$ . If  $G \cap \Delta = \emptyset$ , then G is the disjoint union of A and B.

**Theorem 1.2** (Brouwer fixed point theorem). *If*  $f: D^n \to D^n$  *is continuous, then there exists*  $x \in D^n$  *with* f(x) = x

## 2 Categories and Functors

**Definition 2.1.** A category C consists of three ingredients: a class of **objects**, obj C; sets of **morphisms**  $\operatorname{Hom}(A,B)$ , one for every ordered pair  $A,B \in \operatorname{obj} C$ ; **composition**  $\operatorname{Hom}(A,B) \times \operatorname{Hom}(B,C) \to \operatorname{Hom}(A,C)$ , denoted by  $(f,g) \to g \circ f$ , for every  $A,B,C \in \operatorname{obj} C$  satisfying the following axioms

- 1. the family of Hom(A, B)'s is pairwise disjoint
- 2. composition is associative when defined
- 3. for each  $A \in \operatorname{obj} \mathcal{C}$  there exists an identity  $1_A \in \operatorname{Hom}(A,A)$  satisfying  $1_A \circ f = f$  for every  $f \in \operatorname{Hom}(B,A)$ , all  $B \in \operatorname{obj} \mathcal{C}$  and  $g \circ 1_A = g$  for every  $g \in \operatorname{Hom}(A,C)$ , all  $C \in \operatorname{obj} \mathcal{C}$

**Definition 2.2.** Let  $\mathcal{C}$  and  $\mathcal{A}$  be categories with obj  $\mathcal{C} \subset \operatorname{obj} \mathcal{A}$ . If  $A, B \in \operatorname{obj} \mathcal{C}$ , let's denote the two possible Hom sets by  $\operatorname{Hom}_{\mathcal{C}}(A, B)$  and  $\operatorname{Hom}_{\mathcal{A}}(A, B)$ . Then  $\mathcal{C}$  is a **subcategory** of  $\mathcal{A}$  if  $\operatorname{Hom}_{\mathcal{C}}(A, B) \subset \operatorname{Hom}_{\mathcal{A}}(A, B)$  for all  $A, B \in \operatorname{obj} \mathcal{C}$  and if composition in  $\mathcal{C}$  is the same as composition in  $\mathcal{A}$ 

**Example 2.1.**  $C = \mathbf{Top}^2$ . here obj C consists of all ordered pairs (X, A) where X is a topological space and A is a subspace of X. A morphism  $f:(X,A) \to (Y,B)$  is an ordered pair (f,f') where  $f:X \to Y$  is continuous and fi=jf' (where i and j are inclusions)

$$\begin{array}{ccc}
A & \stackrel{i}{\smile} & X \\
f' \downarrow & & \downarrow f \\
B & \stackrel{j}{\smile} & Y
\end{array}$$

and composition is coordinatewise. **Top**<sup>2</sup> is called the category of **pairs** (of topological spaces)

**Example 2.2.**  $C = \mathbf{Top}_*$ . Here obj C consists of all ordered pairs  $(X, x_0)$  where X is a topological space and  $x_0$  is a point of X.  $\mathbf{Top}_*$  is a subcategory of  $\mathbf{Top}^2$  and it is called the category of **pointed spaces**;  $x_0$  is called the **basepoint** of  $(X, x_0)$  and morphisms are called **pointed maps** (or **basepoint preserving maps**). The category  $\mathbf{Sets}_*$  of pointed sets is defined similarly

*Exercise* 2.0.1. Let  $f \in \operatorname{Hom}(A, B)$  be a morphism in a category  $\mathcal{C}$ . If f has a left inverse g ( $g \in \operatorname{Hom}(B, A) \setminus \operatorname{and} g \circ f = 1_A$ ) and a right inverse h ( $h \in \operatorname{Hom}(B, A)$  and  $f \circ h = 1_B$ ), then g = h

*Exercise* 2.0.2. A set X is called **quasi-ordered** (or **pre-ordered**) if X has a transitive and reflexive relation  $\leq$  (such a set is partially ordered if  $\leq$  is antisymmetric). Prove that the following construction gives a category C. Define obj C = X, if  $x, y \in X$  and  $x \nleq y$ , define  $\operatorname{Hom}(x, y) = \emptyset$ ; if  $x \leq y$ , define  $\operatorname{Hom}(x, y)$  to be a set with exactly one element, denoted by  $i_y^x$ ; if  $x \leq y \leq z$  define composition by  $i_z^y \circ i_y^x = i_z^x$ 

*Exercise* 2.0.3. Let G be a **monoid**, that is, a semigroup with 1. Show that the following gives a category C. Let obj C have exactly one element, denoted by ; **define**  $\backslash (Hom(,*) = G \backslash)$  and define composition  $G \times G \to G$  as the given multiplication in G

**Definition 2.3.** A **diagram** in a category  $\mathcal{C}$  is a directed graph whose vertices are labeled by objects of  $\mathcal{C}$  and whose directed edges are labeled by morphisms in  $\mathcal{C}$ . A **commutative diagram** in  $\mathcal{C}$  is a diagram in which, for each pair of vertices, every two paths (composites) between them are equal as morphisms.

*Exercise* 2.0.4. Given a category  $\mathcal{C}$ , shows that the following construction gives a category  $\mathcal{M}$ . First, an object of  $\mathcal{M}$  is a morphism of  $\mathcal{C}$ . Next, if  $f,g \in \text{obj } \mathcal{M}$ , say  $f:A \to B$  and  $g:C \to D$ , then a morphism in  $\mathcal{M}$  is an ordered pair (h,k) of morphisms in  $\mathcal{C}$  s.t. the diagram

$$\begin{array}{ccc}
A & \xrightarrow{f} & B \\
\downarrow h & & \downarrow k \\
C & \xrightarrow{g} & D
\end{array}$$

commutes. Define composition coordinatewise

$$(h',k')\circ(h,k)=(h'\circ h,k'\circ k)$$

**Definition 2.4.** A **congruence** on a category C is an equivalence relation  $\sim$  on the class  $\bigcup_{(A,B)} \operatorname{Hom}(A,B)$  of all morphisms in C s.t.

- 1.  $f \in \text{Hom}(A, B)$  and  $f \sim f'$  implies  $f' \in \text{Hom}(A, B)$
- 2.  $f \sim f'$ ,  $g \sim g'$  and the composite  $g \circ f$  exists imply that

$$g \circ f \sim g' \circ f'$$

**Theorem 2.5.** Let C be a category with congruence  $\sim$  and let [f] denote the equivalence class of a morphism f. Define C' as follows

$$obj C' = obj C$$

$$Hom_{C'}(A, B) = \{ [f] : f \in Hom_{C}(A, B) \}$$

$$[g] \circ [f] = [g \circ f]$$

*Then C'* is a category

*Proof.* Property 1 in the definition of congruence shows that  $\sim$  partitions each set  $\operatorname{Hom}_{\mathcal{C}}(A,B)$  and this implies that  $\operatorname{Hom}_{\mathcal{C}'}(A,B)$  is a set; moreover, the family of these sets is pairwise disjoint. Property 2 in the definition of congruence shows that composition in  $\mathcal{C}'$  is well.  $\mathcal{C}'$  is associative and  $[1_A]$  is the identity is not hard

The category C' is called a **quotient category** of C; one usually denotes  $\operatorname{Hom}_{C'}(A,B)$  by [A,B]

Exercise 2.0.5. Let G be a group and let C be the one-object category it defines: obj  $C = \{*\}$ ,  $\operatorname{Hom}(*,*) = G$  and composition is the group operation. If H is a normal subgroup of G, define  $x \sim y$  to mean  $xy^{-1} \in H$ . Show that  $\sim$  is a congruence on C and that [\*,\*] = G/H in the corresponding quotient category

**Definition 2.6.** If A and C are categories, a **functor**  $T : A \to C$  is a function, that is,

- 1.  $A \in \text{obj } A \text{ implies } TA \in \text{obj } C$
- 2. if  $f:A\to A'$  is a morphism in A, then  $Tf:TA\to TA'$  is a morphism in C
- 3. if f, g are morphisms in A for which  $g \circ f$  is defined, then

$$T(g \circ f) = (Tg) \circ (Tf)$$

4.  $T(1_A) = 1_{TA}$  for every  $A \in \text{obj } A$ 

**Example 2.3.** If C is a category, the **identity functor**  $J: C \to C$  is defined by JA = A for every object A and Jf = f for every morphism

**Example 2.4.** If M is a fixed topological space, Then  $T_m: \mathbf{Top} \to \mathbf{Top}$  is a functor, where  $T_M(X) = X \times M$  and if  $f: X \to Y$  is continuous, then  $T_M(f): X \times M \to Y \times M$  is defined by  $(x,m) \mapsto (f(x),m)$ 

**Example 2.5.** Fix an object A in category C. Then  $\operatorname{Hom}(A, -) : C \to \mathbf{Sets}$  is a functor assigning to each object B the set  $\operatorname{Hom}(A, B)$  and to each morphism  $f: B \to B'$  the **induced map**  $\operatorname{Hom}(A, f) : \operatorname{Hom}(A, B) \to \operatorname{Hom}(A, B')$  defined by  $g \mapsto f \circ g$ . One usually denotes the induced map  $\operatorname{Hom}(A, f)$  by  $f_*$ 

Functors as just defined are also called **covariant functors** to distinguish them from **contravariant functors** that reverse the direction of arrows. Thus the functor of the example is sometimes called a **covariant Hom functor**.

**Definition 2.7.** if A and C are categories, a **contravariant functor**  $S : A \to C$  is a function that

- 1.  $A \in \text{obj } A \text{ implies } SA \in \text{obj } C$
- 2. if  $f:A\to A'$  is a morphism in  $\mathcal C$ , then  $Sf:SA'\to SA$  is a morphism in  $\mathcal C$
- 3. if f, g are morphisms in A for which  $g \circ f$  is defined, then

$$S(g \circ f) = S(f) \circ S(g)$$

4.  $S(1_A) = 1_{SA}$  for every  $A \in \text{obj } A$ 

**Example 2.6.** Fix an object B in a category C. Then  $\operatorname{Hom}(-,B):C\to\operatorname{Sets}$  is a contravariant functor assigning to each object A the set  $\operatorname{Hom}(A,B)$  and to each morphism  $g:A\to A'$  the **induced map**  $\operatorname{Hom}(g,B):\operatorname{Hom}(A',B)\to\operatorname{Hom}(A,B)$  defined by  $h\mapsto h\circ g$ . One usually denotes the induced map  $\operatorname{Hom}(g,B)$  by  $g^*$ ;  $\operatorname{Hom}(-,B)$  is called a **contravariant Hom functor** 

**Definition 2.8.** An **equivalence** in a category C is a morphism  $f: A \to B$  for which there exists a morphism  $g: B \to A$  with  $f \circ g = 1_B$  and  $g \circ f = 1_A$ 

**Theorem 2.9.** *If* A *and* C *are categories and*  $T : A \to C$  *is a functor of either variance, then* f *an equivalence in* A *implies that* Tf *is an equivalence in* C

*Exercise* 2.0.6. Let C and A be categories, let  $\sim$  be a congruence on C. If  $T:C\to A$  is a functor with T(f)=T(g) whenever  $f\sim g$ , then T defines a functor  $T':C'\to A$  (where C' is the quotient category) by T'(X)=T(X) for every object X and T'([f])=T(f) for every morphism f.

Exercise 2.0.7. 1. if X is a topological space, show that C(X), the set of all continuous real-valued functions on X, is a commutative ring with 1 under pointwise operations

$$f + g : x \mapsto f(x) + g(x)$$
 and  $f \cdot g \mapsto f(x)g(x)$ 

for all  $x \in X$ 

2. show that  $X \mapsto C(X)$  gives a (contravariant) functor **Top**  $\rightarrow$  **Rings** 

*Proof.* 2. From exercise 2.0.4

# 3 Some Basic Topological Notions

### 3.1 Homotopy

**Definition 3.1.** If X and Y are spaces and if  $f_0, f_1$  are continuous maps from X to Y, then  $f_0$  is **homotopic** to  $f_1$ , denoted by  $f_0 \simeq f_1$  if there is a continuous map  $F: X \times \mathbf{I} \to Y$  with

$$F(x,0) = f_0(x)$$
 and  $F(x,1) = f_1(x)$  for all  $x \in X$ 

Such a map F is called a **homotopy**, written as  $F: f_0 \simeq f_1$ 

If  $f_t: X \to Y$  is defined by  $f_t(x) = F(x,t)$ , then a homotopy F gives a one-parameter family of continuous maps deforming  $f_0$  into  $f_1$ 

**Lemma 3.2** (Gluing lemma). Assume that a space X is a finite union of closed subsets  $X = \bigcup_{i=1}^n X_i$ . If, for some space Y, there are continuous maps  $f_i : X_i \to Y$  that agree on overlaps  $(f_i|X_i \cap X_j = f_j|X_i \cap X_j$  for all i,j), then there exists a unique continuous  $f: X \to Y$  with  $f|X_i = f_i$  for all i

*Proof.* If *C* is closed in *Y*, then

$$\begin{split} f^{-1}(C) &= X \cap f^{-1}(C) = (\bigcup X_i) \cap f^{-1}(C) \\ &= \bigcup (X_i \cap f^{-1}(C)) \\ &= \bigcup (X_i \cap f_i^{-1}(C)) = \bigcup f_i^{-1}(C) \end{split}$$

Since each  $f_i$  is continuous,  $f_i^{-1}(C)$  is closed in  $X_i$ . Since  $X_i$  is closed in X,  $f_i^{-1}(C)$  is closed in X, therefore  $f^{-1}(C)$  is closed in X and f is continuous  $\square$ 

**Lemma 3.3** (Gluing Lemma). Assume that a space X has a (possibly infinite) open cover  $X = \bigcup X_i$ . If for some space Y, there are continuous maps  $f_i : X_i \to Y$  that agree on overlaps, then there exists a unique continuous  $f: X \to Y$  with  $f|X_i = f_i$  for all i

**Theorem 3.4.** Homotopy is an equivalence relation on the set of all continuous maps  $X \to Y$ 

*Proof. Reflexivity.* If  $f: X \to Y$ , define  $F: X \times \mathbf{I} \to Y$  by F(x,t) = f(x) for all  $x \in X$  and  $t \in \mathbf{I}$ ; clearly  $F: f \simeq f$ 

*Symmetry*: Assume that  $f \simeq g$ , so there is a continuous  $F: X \times \mathbf{I} \to Y$  with F(x,0) = f(x) and F(x,1) = g(x) for all  $x \in X$ . Define  $G: X \times \mathbf{I} \to Y$  by G(x,t) = F(x,1-t), and note that  $G: g \simeq f$ .

*Transivity*: assume that  $F : f \simeq g$  and  $G : g \simeq h$ . Define  $H : X \times I \to Y$  by

$$H(x,t) = \begin{cases} F(x,2t) & 0 \le t \le 1/2 \\ G(x,2t-1) & 1/2 \le t \le 1 \end{cases}$$

Because these functions agree on the overlap  $\{(x, 1/2) : x \in X\}$ , the gluing lemma shows that H is continuous. Therefore  $H : f \simeq h$ 

**Definition 3.5.** If  $f: X \to Y$  is continuous, its **homotopy class** is the equivalence class

$$[f] = \{ continuous g : X \to Y : g \simeq f \}$$

The family of all such homotopy classes is denoted by [X, Y]

**Theorem 3.6.** Let  $f_i: X \to Y$  and  $g_i: Y \to Z$ , for i = 0, 1, be continuous. If  $f_0 \simeq f_1$  and  $g_0 \simeq g_1$ , then  $g_0 \circ f_0 \simeq g_1 \circ f_1$ ; that is,  $[g_0 \circ f_0] = [g_1 \circ f_1]$ 

*Proof.* Let  $F: f_0 \simeq f_1$  and  $G: g_0 \simeq g_1$  be homotopies. First, we show that

$$g_0 \circ f_0 \simeq g_1 \circ f_0$$

Define  $H: X \times \mathbf{I} \to Z$  by  $H(x,t) = G(f_0(x),t)$ . Clearly, H is continuous; moreover,  $H(x,0) = G(f_0(x),0) = g_0(f_0(x))$  and  $H(x,1) = G(f_0(x),1) = g_1(f_0(x))$ . Now observe that

$$K:g_1\circ f_0\sim g_1\circ f_1$$

where  $K: X \times \mathbf{I} \to Z$  is the composite  $g_1 \circ F$ . Now use the transitivity of the homotopy relation, we have  $g_0 \circ f_0 \simeq g_1 \circ f_1$ 

**Corollary 3.7.** *Homotopy is a congruence on the category Top.* 

It follows from Theorem 2.5 that there is a quotient category whose objects are topological spaces X, whose Hom sets are Hom(X,Y) = [X,Y] and whose composition is  $[g] \circ [f] = [g \circ f]$ 

**Definition 3.8.** The quotient category just described is called the **homotopy category**, and it is denoted by **hTop** 

All the functors  $T: \mathbf{Top} \to \mathcal{A}$  that we shall construct, where  $\mathcal{A}$  is some "algebraic" category (e.g. **Ab**, **Groups**, **Rings**) will have the property that  $f \simeq g$  implies T(f) = T(g). This fact, aside from a natural wish to identify homotopic maps, makes homotopy valuable, beacause it guarantees that the algebraic problem in  $\mathcal{A}$  arising from a topological problem via T is simpler than the original problem

**Definition 3.9.** A continuous map  $f: X \to X$  is a **homotopy equivalence** if there is a continuous map  $g: Y \to X$  with  $g \circ f \simeq 1_X$  and  $f \circ g \simeq 1_Y$ . Two spaces X and Y have the **same homotopy type** if there is a homotopy equivalence  $f: X \to Y$ 

f is a homotopy equivalence iff  $[f] \in [X, Y]$  is an equivalence in **hTop**. ()

**Definition 3.10.** Let X and Y be spaces, and let  $y_0 \in Y$ . The **constant map** at  $y_0$  is the function  $c: X \to Y$  with  $c(x) = y_0$  for all  $x \in X$ . A continuous map  $f: X \to Y$  is **nullhomotopic** if there is a constant map  $c: X \to Y$  with  $f \simeq c$ 

**Theorem 3.11.** Let  $\mathbb{C}$  denote the complex numbers, let  $\Sigma_{\rho} \subset \mathbb{C} \approx \mathbb{R}^2$  denote the circle with center at the origin 0 and radius  $\rho$ , and let  $f_{\rho}^n : \Sigma_{\rho} \to \mathbb{C} - \{0\}$  denote the restriction to  $\Sigma^{\rho}$  of  $z \mapsto z^n$ . If none of the maps  $f_{\rho}^n$  is nullhomotopic ( $n \ge 1$  and  $\rho > 0$ ) then the fundamental theorem of algebra is true (i.e., every nonconstant complex polynomial has a complex root)

*Proof.* Consider the polynomial with complex coefficients

$$g(z) = z^n + a_{n-1}z^{n-1} + \dots + a_1z + a_0$$

Choose  $\rho>\max\{1,\sum_{i=1}^{n-1}|a_i|\}$  and define  $F:\Sigma_{\rho}\times\mathbf{I}\to\mathbb{C}$ 

$$F(z,t) = z^{n} + \sum_{i=0}^{n-1} (1-t)a_{i}z^{i}$$

It's obvious that  $F:g|\Sigma_{\rho}\simeq f_{\rho}^{n}$  if we can show that the image of F is contained in  $\mathbb{C}-\{0\}$ . that is,  $F(z,t)\neq 0$ . If, on the contrary, F(z,t)=0 for some  $t\in \mathbf{I}$  and some z with  $|z|=\rho$ , then  $z^{n}=-\sum_{i=0}^{n-1}(1-t)a_{i}z^{i}$ . The triangle inequality gives

$$\rho^n \leq \sum_{i=0}^{n-1} (1-t) |a_i| \rho^i \leq \sum_{i=0}^{n-1} |a_i| \rho^i \leq \left(\sum_{i=0}^{n-1} |a_i|\right) \rho^{n-1}$$

for  $\rho > 1$  implies that  $\rho^i \leq \rho^{n-1}$ . Canceling  $\rho^{n-1}$  gives  $\rho \leq \sum_{i=0}^{n-1} |a_i|$ , a contradiction.

Assume now that g has no complex roots. Define  $G: \Sigma_{\rho} \times \mathbf{I} \to \mathbb{C} - \{0\}$  by G(z,t) = g((1-t)z). (Since g has no roots, the values of G do lie in  $\mathbb{C} - \{0\}$ ) Visibly,  $G: g|\Sigma_{\rho} \simeq k$ , where k is the constant function at  $a_0$ . Therefore  $g|\Sigma_{\rho}$  is nullhomotopic and by transitivity,  $f_{\rho}^n$  is nullhomotopic, contradicting the hypothesis.

A common problem involves extending a map  $f: X \to Z$  to a larger space Y; the picture is



Homotopy itself raises such a problem: if  $f_0, f_1: X \to Z$  then  $f_0 \simeq f_1$  if we can extend  $f_0 \cup f_1: X \times \{0\} \cup X \times \{1\} \to Z$  to all of  $X \times I$ 

### 4 Problem

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