# An Introduction To Algebraic Topology

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## 1 Introduction

#### 1.1 Notation

$$I = [0, 1].$$

$$S^n = \{ x \in \mathbb{R}^{n+1} \mid ||x|| = 1 \}$$

 $S^n$  is called the n-sphere.  $S^n \subset \mathbb{R}^{n+1}$  ( $S^1$  is the circle); 0-sphere  $S^0$  consists of the two points  $\{-1,1\}$  and hence is a discrete two-point space. We may regard  $S^n$  as the **equator** of  $S^{n+1}$ 

$$S^n = \mathbb{R}^{n+1} \cap S^{n+1} = \{(x_1, \dots, x_{n+2}) \in S^{n+1} : x_{n+2} = 0\}$$

The **north pole** is  $(0,0,...,0,1) \in S^n$ ; the **south pole** is (0,0,...,0,-1). The **antipode** of  $x = (x_1,...,x_{n+1}) \in S^n$  is the other endpoint of the diameter having one endpoint x; thus the antipode of x is  $-x = (-x_1,...,-x_{n+1})$ , for the distance from -x to x is 2.

$$D^n = \{x \in \mathbb{R}^n \mid ||x|| \le 1\}$$

 $D^n$  is called the n-disk (or n-ball). Observe that  $S^{n-1} \subset D^n \subset \mathbb{R}^n$ ; indeed  $S^{n-1}$  is the boundary of  $D^n$  in  $\mathbb{R}^n$ 

$$\Delta^n = \{(x_1, \dots, x_{n+1}) \in \mathbb{R}^{n+1} : \text{ each } x_i \ge 0 \text{ and } \sum x_i = 1\}$$

 $\Delta^n$  is called the **standard** *n***-simplex**.  $\Delta^0$  is a point,  $\Delta^1$  is a closed interval,  $\Delta^2$  is a triangle (with interior),  $\Delta^3$  is a (solid) tetrahedron, and so on.

There is a standard homeomorphism from  $S^n$  - {north pole} to  $\mathbb{R}^n$ , called **stereographic projection**. Denote the north pole by N, and define  $\sigma: S^n - \{N\} \to \mathbb{R}^n$  to be the intersection of  $\mathbb{R}^n$  and the line joining x and N. Points on the latter line have the form tx + (1-t)N, hence they have coordinates  $(tx_1, \dots, tx_n, tx_{n+1} + (1-t))$ . The last coordinate is zero for  $t = (1-x_{n+1})^{-1}$ ; hence

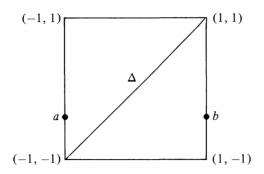
$$\sigma(x) = (tx_1, \dots, tx_n)$$

where  $t = (1 - x_{n+1})^{-1}$ . It is now routine to check that  $\sigma$  is indeed a homeomorphism. Note that  $\sigma(x) = x$  iff x lies on the equator  $S^{n-1}$ 

#### 1.2 Brouwer Fixed Point Theorem

**Theorem 1.1.** Every continuous  $f: D^1 \to D^1$  has a fixed point

*Proof.* Let f(-1) = a and f(1) = b. If either f(-1) = -1 or f(1) = 1, we are done. Therefore we may assume that f(-1) = a > -1 and that f(1) = b < 1 as drawn. If



G is the graph of f and  $\Delta$  is the graph of the identity function, then we must prove that  $G \cap \Delta \neq \emptyset$ . The idea is to use a connectness argument to show that every path in  $D^1 \times D^1$  from a to b must cross  $\Delta$ .

Since f is continuous,  $G = \{(x, f(x)) : x \in D^1\}$  is connected (continuous image of connected space is connected). Define  $A = \{(x, f(x)) : f(x) > x\}$  and  $B = \{(x, f(x)) : f(x) < x\}$ . Note that  $a \in A$  and  $b \in B$ , so that  $A \neq \emptyset$  and  $B \neq \emptyset$ . If  $G \cap \Delta = \emptyset$ , then G is the disjoint union of A and B.

**Theorem 1.2** (Brouwer fixed point theorem). *If*  $f: D^n \to D^n$  *is continuous, then there exists*  $x \in D^n$  *with* f(x) = x

# 1.3 Categories and Functors

**Definition 1.3.** A category C consists of three ingredients: a class of **objects**, obj C; sets of **morphisms** Hom(A, B), one for every ordered pair A,  $B \in \text{obj } C$ ; **composition** Hom(A, B) × Hom(B, C)  $\rightarrow$  Hom(A, C), denoted by (f, g)  $\rightarrow$   $g \circ f$ , for every A, B,  $C \in \text{obj } C$  satisfying the following axioms

- 1. the family of Hom(A, B)'s is pairwise disjoint'
- 2. composition is associative when defined
- 3. for each  $A \in \operatorname{obj} \mathcal{C}$  there exists an identity  $1_A \in \operatorname{Hom}(A,A)$  satisfying  $1_A \circ f = f$  for every  $f \in \operatorname{Hom}(B,A)$ , all  $B \in \operatorname{obj} \mathcal{C}$  and  $g \circ 1_A = g$  for every  $g \in \operatorname{Hom}(A,C)$ , all  $C \in \operatorname{obj} \mathcal{C}$

**Definition 1.4.** Let  $\mathcal{C}$  and  $\mathcal{A}$  be categories with obj  $\mathcal{C} \subset \operatorname{obj} \mathcal{A}$ . If  $A, B \in \operatorname{obj} \mathcal{C}$ , let's denote the two possible Hom sets by  $\operatorname{Hom}_{\mathcal{C}}(A, B)$  and  $\operatorname{Hom}_{\mathcal{A}}(A, B)$ . Then  $\mathcal{C}$  is a **subcategory** of  $\mathcal{A}$  if  $\operatorname{Hom}_{\mathcal{C}}(A, B) \subset \operatorname{Hom}_{\mathcal{A}}(A, B)$  for all  $A, B \in \operatorname{obj} \mathcal{C}$  and if composition in  $\mathcal{C}$  is the same as composition in  $\mathcal{A}$ 

**Example 1.1.**  $C = \mathbf{Top}^2$ . here obj C consists of all ordered pairs (X,A) where X is a topological space and A is a subspace of X. A morphism  $f:(X,A)\to (Y,B)$  is an ordered pair (f,f') where  $f:X\to Y$  is continuous and fi=jf' (where i and j are inclusions)

$$\begin{array}{ccc}
A & \stackrel{i}{\smile} & X \\
f' \downarrow & & \downarrow f \\
B & \stackrel{j}{\smile} & Y
\end{array}$$

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