

Outcome include:

1. “Roboteq Controller KBL1xxx” Labview driver
2. “Pump Controller” Labview 2017 examples and tests project

1 “Roboteq Controller KBL1xxx” Labview driver

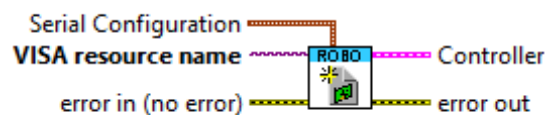
Should be copying to Labview instrumentation driver’s folder.

For example: *c:\Program Files (x86)\National Instruments\LabVIEW 2017\instr.lib*

Workflow (common for all instrument Labview drivers):

VISA Resource name → Initialize.vi → Controller.ctl (Type Def)

Roboteq Controller KBL1xxx.lvlib:Initialize.vi



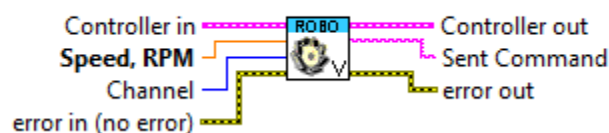
Establishes communication with the instrument and optionally performs an instrument identification query and/or an instrument reset. It also places the instrument in a default state needed for other instrument driver operations. Therefore, call this VI before calling other instrument driver VIs for this instrument. Generally, you need to call the **Initialize** VI only once at the beginning of an application.

Terminal Data Type

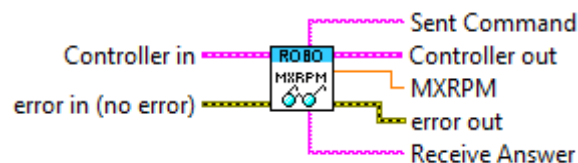
VISA resource name (VISA session of class Instr)

Using Controller “reference” execute commands and acquire parameters.

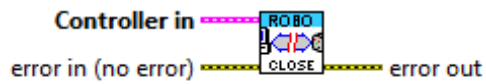
Roboteq Controller KBL1xxx.lvlib:Go to Speed.vi



Roboteq Controller KBL1xxx.lvlib:Max RPM Value.vi



Roboteq Controller KBL1xxx.lvlib:Close.vi



Performs termination the software connection to the instrument.

Driver features can be extended

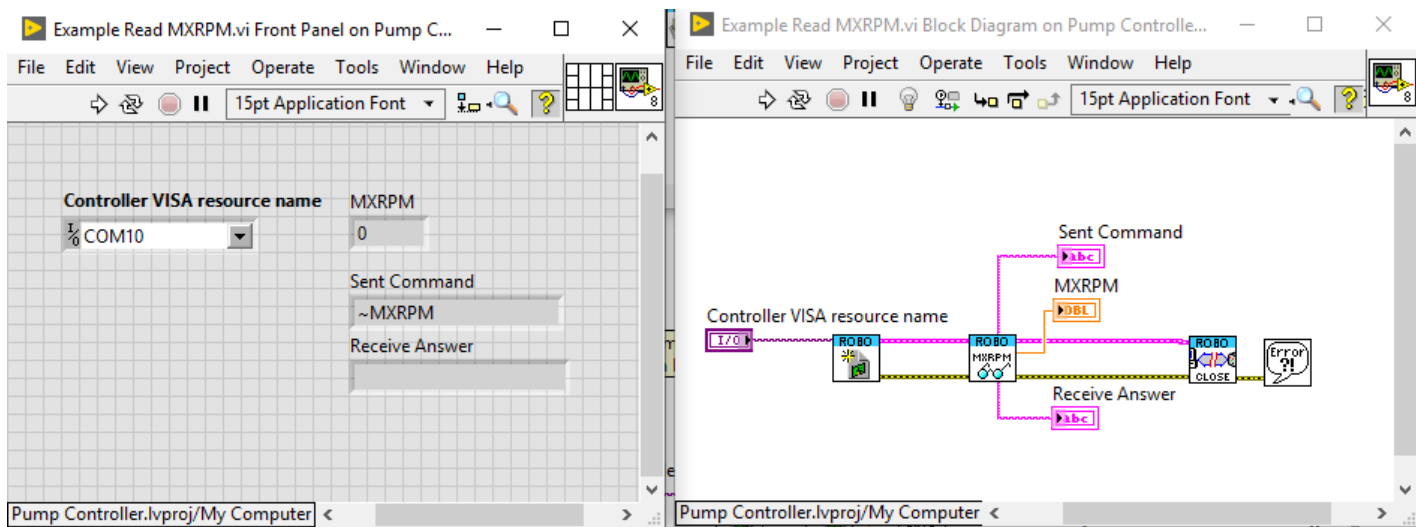
2 “Pump Controller” Labview 2017 examples and tests project

Include several Low and High level examples and tests VIs.

Example Read MXRPM.vi

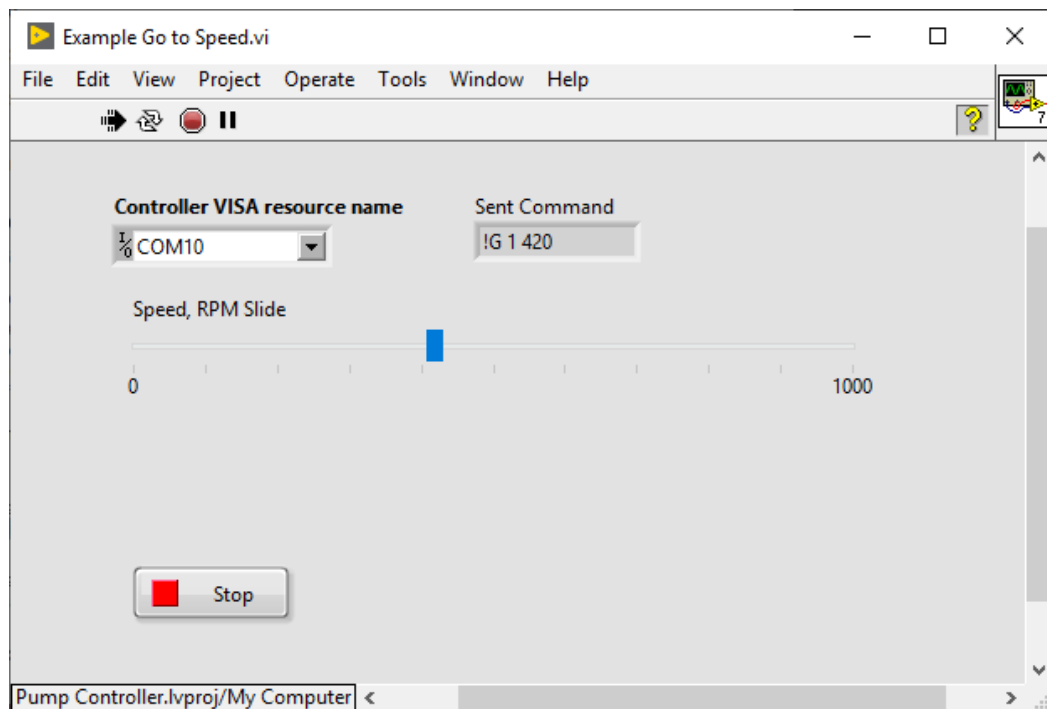
To use “G - Go to Speed” command in Closed Loop Speed mode it is necessary to know maximum speed that is stored in the MXRPM configuration parameter.

Please execute **Example Read MXRPM.vi** test VI, enter valid **Controller VISA resource name** and provide **Receive Answer** from controller.

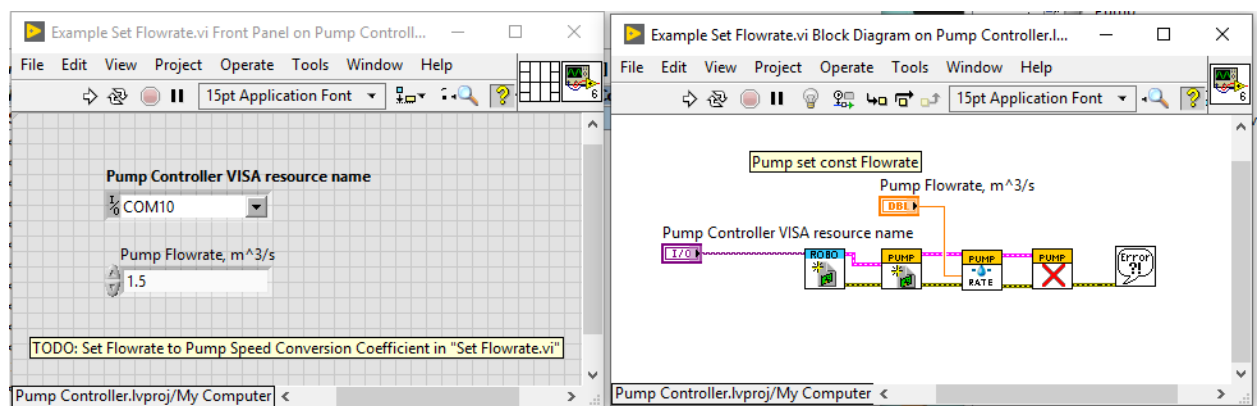


Example Go to Speed.vi

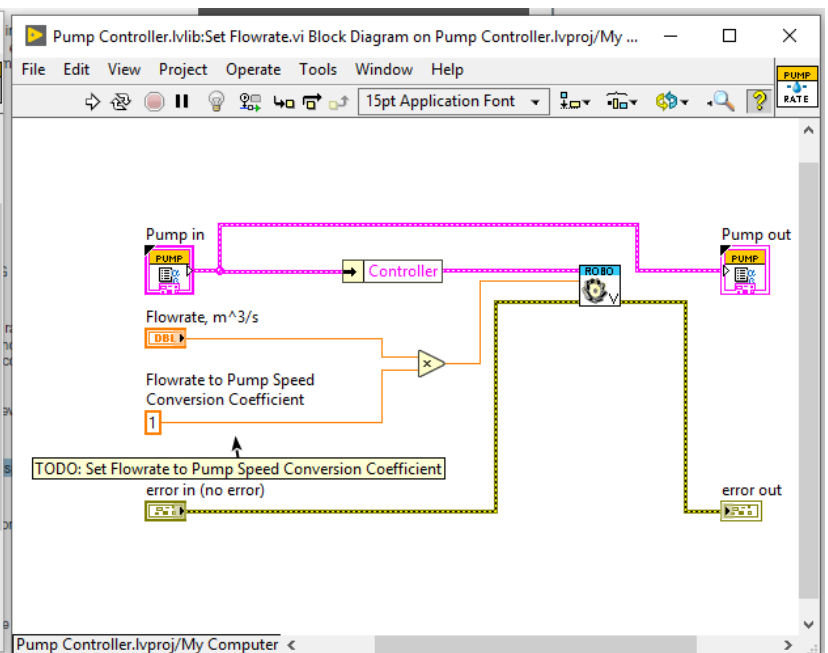
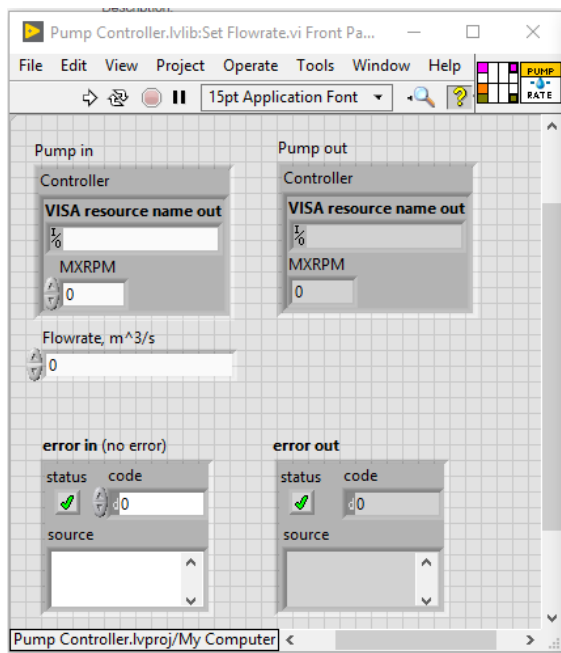
This example use **MXRPM=1000** (will be modified to read the real value)



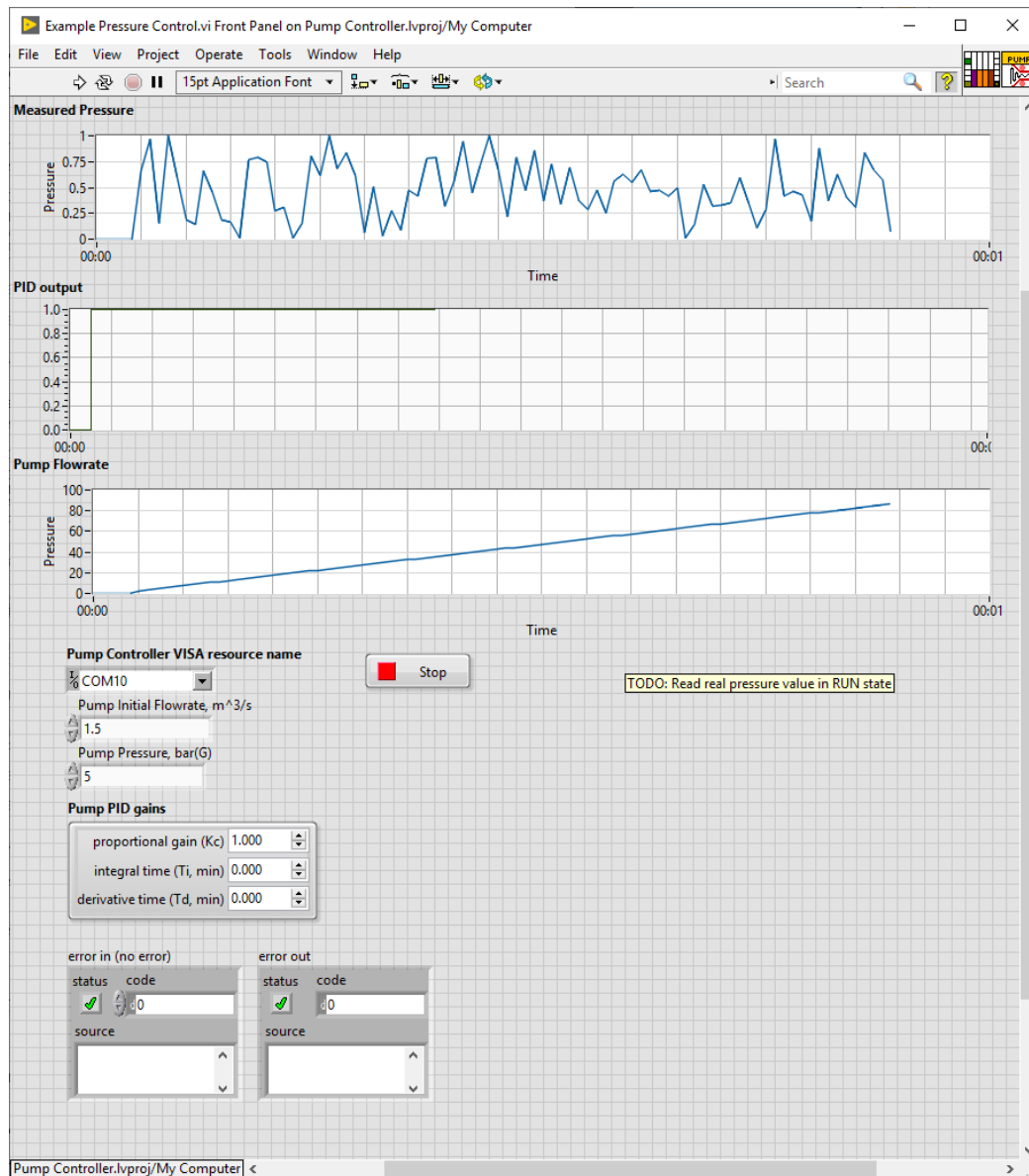
Example Set Flowrate.vi



To test flowrate control it is need to set Flowrate to Pump Speed Conversion Coefficient in **Pump Controller.lvlib:Pump\Set Flowrate.vi** (see below)



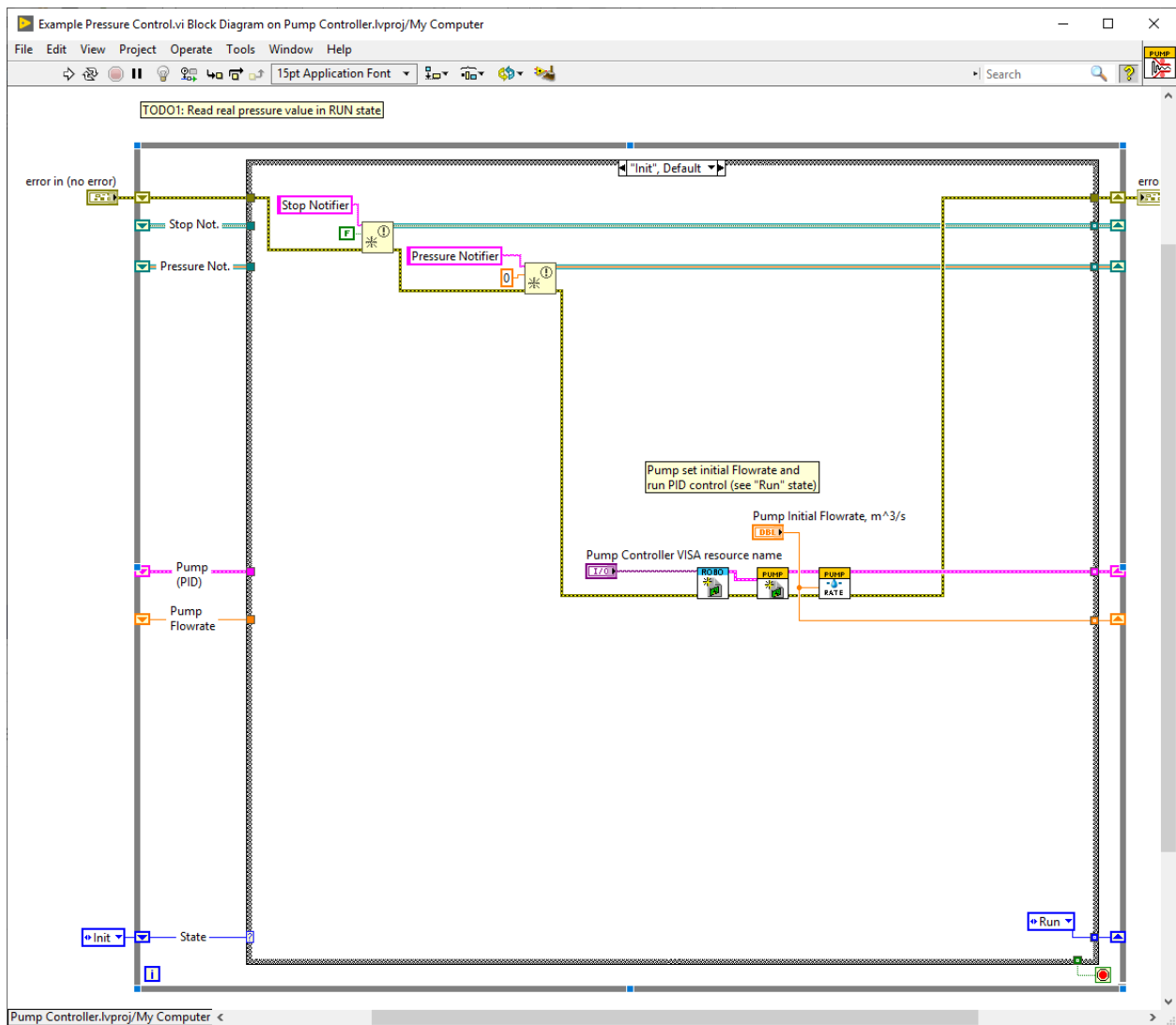
Example Pressure Control.vi



You need to select **Pump Controller VISA resource name**, enter **Pump Initial Flowrate, m³/s** and required **Pump Pressure, bar(G)**. Change **Pump PID gains** if required.

Example works using State Machine pattern. There is three states: Init, Run and Stop.

On **Init state** program creates Controller reference, Pump reference and sets initial flowrate value.



On **Run state** program perform pressure measurement (with pause) and control pump flowrate using PID.

