

MC-Kit Manual

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1 Introduction

The problem of Matrix Completion (MC) is to recover a matrix \mathbf{A} from only a small sample of its entries. Let $\mathbf{A} \in \mathbb{R}^{m \times n}$ be the matrix we would like to know as precisely as possible while only observing a subset of its entries $(i, j) \in \Omega$. It is assumed that observed entries in Ω are uniform randomly sampled. Low-Rank Matrix Completion is a variant that assumes that \mathbf{A} is low-rank. The tolerance for “low” is dependant upon the size of \mathbf{A} and the number of sampled entries.

For further explanation let us define the sampling operator $\mathcal{P}_\Omega : \mathbb{R}^{m \times n} \rightarrow \mathbb{R}^{m \times n}$ as

$$[\mathcal{P}_\Omega(X)]_{ij} = \begin{cases} X_{ij}, & (i, j) \in \Omega, \\ 0, & \text{otherwise.} \end{cases} \quad (1)$$

We also define the opposite operator $\mathcal{P}_{\bar{\Omega}}$, which keeps those outside Ω unchanged and sets values inside Ω (i.e. $\bar{\Omega}$) to 0. Since we assume that the matrix to recover is low-rank, one could recover the unknown matrix by solving

$$\begin{aligned} \min_{\mathbf{A}} \quad & \text{rank}(\mathbf{A}) \\ \text{s.t.} \quad & \mathcal{P}_\Omega(\mathbf{A}) = \mathcal{P}_\Omega(\mathbf{M}) \end{aligned} \quad (2)$$

where matrix \mathbf{M} is the partially observed matrix. In practice this problem is intractable therefore we use the closest convex relaxation i.e. the nuclear norm

$$\begin{aligned} \min_{\mathbf{A}} \quad & \tau \|\mathbf{A}\|_* \\ \text{s.t.} \quad & \mathcal{P}_\Omega(\mathbf{M}) = \mathcal{P}_\Omega(\mathbf{A}) \end{aligned} \quad (3)$$

We also consider the case where our observed entries may contain a limited amount of noise. Our corresponding objective is the following

$$\begin{aligned} \min_{\mathbf{A}} \quad & \tau \|\mathbf{A}\|_* + \frac{\lambda}{2} \|\mathcal{P}_\Omega(\mathbf{E})\|_F^2 \\ \text{s.t.} \quad & \mathcal{P}_\Omega(\mathbf{M}) = \mathcal{P}_\Omega(\mathbf{A}) + \mathcal{P}_\Omega(\mathbf{E}) \end{aligned} \quad (4)$$

2 Singular Value Shrinkage Operator

Central to this work is the **singular value shrinkage operator**. Consider the singular value decomposition (SVD) of a matrix $\mathbf{Y} \in \mathbb{R}^{m \times n}$ with rank r

$$\mathbf{Y} = \mathbf{U}\mathbf{\Sigma}\mathbf{V}^T, \quad \mathbf{\Sigma} = \text{diag}(\{\sigma_i\}_{i=1}^r). \quad (5)$$

Then we define the singular value shrinkage operator for any $\tau \geq 0$ as

$$\mathcal{D}_\tau(\mathbf{Y}) = \mathbf{U}S_\tau(\mathbf{\Sigma})\mathbf{V}^T, \quad S_\tau(\mathbf{\Sigma}) = \text{diag}(\{\max(\sigma_i - \tau, 0)\}). \quad (6)$$

It has been shown [?] that the operator $\mathcal{D}_\tau(\mathbf{Y})$ is the solution to the proximal nuclear norm problem i.e.

$$\mathcal{D}_\tau(\mathbf{Y}) = \underset{\mathbf{X}}{\text{argmin}} \quad \tau\|\mathbf{X}\|_* + \frac{1}{2}\|\mathbf{X} - \mathbf{Y}\|_F^2 \quad (7)$$

The implementation of the singular value shrinkage operator is implemented by the function $[\mathbf{X}, \mathbf{s}] = \text{nn_prox}(\mathbf{Y}, \tau)$, where \mathbf{s} is the vector of the singular values of \mathbf{X} .

3 Function Listing

Problem	Implementation	Section
$\min_{\mathbf{A}} \tau\ \mathbf{A}\ _* + \frac{1}{2}\ \mathbf{A}\ _F^2$ s.t. $\mathcal{P}_\Omega(\mathbf{M}) = \mathcal{P}_\Omega(\mathbf{A})$	Singular Value Thresholding (SVT)	4.1
$\min_{\mathbf{A}} \tau\ \mathbf{A}\ _*$ s.t. $\mathcal{P}_\Omega(\mathbf{M}) = \mathcal{P}_\Omega(\mathbf{A})$	Inexact ALM	4.2
	Linearised ALM	4.3
$\min_{\mathbf{A}} \tau\ \mathbf{A}\ _* + \frac{\lambda}{2}\ \mathcal{P}_\Omega(\mathbf{E})\ _F^2$ s.t. $\mathcal{P}_\Omega(\mathbf{M}) = \mathcal{P}_\Omega(\mathbf{A}) + \mathcal{P}_\Omega(\mathbf{E})$	Linearised ALM	5.1

4 Noise-Free Implementations

4.1 SVT

The function

$$[\mathbf{A}, \mathbf{f_values}, \mathbf{stop_vals}] = \text{solve_svt}(\mathbf{M}, \tau, \mu, \text{iterations}, \text{tol}) \quad (8)$$

solves the following

$$\begin{aligned} \min_{\mathbf{A}} \quad & \tau \|\mathbf{A}\|_* + \frac{1}{2} \|\mathbf{A}\|_F^2 \\ \text{s.t.} \quad & \mathcal{P}_\Omega(\mathbf{M}) = \mathcal{P}_\Omega(\mathbf{A}) \end{aligned} \quad (9)$$

as proposed by the authors of [?].

- \mathbf{M} - matrix with observed entries and zeros for all others
- τ - regularisation (optional)
- μ - step size (optional)
- *iterations* - maximum number of iterations (optional)
- *tol* - stopping criteria tolerance (optional)

4.2 Inexact ALM

The function

$$[\mathbf{A}, \mathbf{f_vals}, \mathbf{stop_vals}] = \text{solve_ialm}(\mathbf{M}, \tau, \mu, \text{iterations}, \text{tol}) \quad (10)$$

solves the following

$$\begin{aligned} \min_{\mathbf{A}} \quad & \tau \|\mathbf{A}\|_* \\ \text{s.t.} \quad & \mathcal{P}_\Omega(\mathbf{M}) = \mathcal{P}_\Omega(\mathbf{A}) \end{aligned} \quad (11)$$

as proposed by the authors of [?].

- \mathbf{M} - matrix with observed entries and zeros for all others
- τ - regularisation (optional)
- μ - step size (optional)
- *iterations* - maximum number of iterations (optional)
- *tol* - stopping criteria tolerance (optional)

4.3 Linearised ALM

The function

$$[\mathbf{A}, \mathbf{f_vals}, \mathbf{stop_vals}] = \text{solve_lin_alm}(\mathbf{M}, \tau, \mu, \rho, \text{iterations}, \text{tol}) \quad (12)$$

solves the following

$$\begin{aligned} \min_{\mathbf{A}} \quad & \tau \|\mathbf{A}\|_* \\ \text{s.t.} \quad & \mathcal{P}_\Omega(\mathbf{M}) = \mathcal{P}_\Omega(\mathbf{A}) \end{aligned} \quad (13)$$

- \mathbf{M} - matrix with observed entries and zeros for all others
- τ - regularisation (optional)
- μ - step size (optional)
- ρ - linearisation step size (optional)
- *iterations* - maximum number of iterations (optional)
- *tol* - stopping criteria tolerance (optional)

5 Noise Inclusive Implemetations

5.1 Linearised ALM

The functions

$$[\mathbf{A}, \mathbf{f_vals}, \mathbf{stop_vals}] = \text{solve_e_lin_alm}(\mathbf{M}, \tau, \lambda, \rho, \textit{iterations}, \textit{tol}) \quad (14)$$

$$[\mathbf{A}, \mathbf{f_vals}, \mathbf{stop_vals}] = \text{solve_e_lin_extalm}(\mathbf{M}, \tau, \lambda, \rho, \textit{iterations}, \textit{tol}) \quad (15)$$

$$[\mathbf{A}, \mathbf{f_vals}, \mathbf{stop_vals}] = \text{solve_e_lin_extalm}(\mathbf{M}, \tau, \lambda, \rho, \textit{iterations}, \textit{tol}) \quad (16)$$

solve the following

$$\begin{aligned} \min_{\mathbf{A}} \quad & \tau \|\mathbf{A}\|_* + \frac{\lambda}{2} \|\mathcal{P}_\Omega(\mathbf{E})\|_F^2 \\ \text{s.t.} \quad & \mathcal{P}_\Omega(\mathbf{M}) = \mathcal{P}_\Omega(\mathbf{A}) + \mathcal{P}_\Omega(\mathbf{E}) \end{aligned} \quad (17)$$

with increasing convergence speed based on [?].

- \mathbf{M} - matrix with observed entries and zeros for all others
- τ - regularisation (optional)
- λ - regularisation (optional)
- ρ - linearisation step size (optional)
- *iterations* - maximum number of iterations (optional)
- *tol* - stopping criteria tolerance (optional)