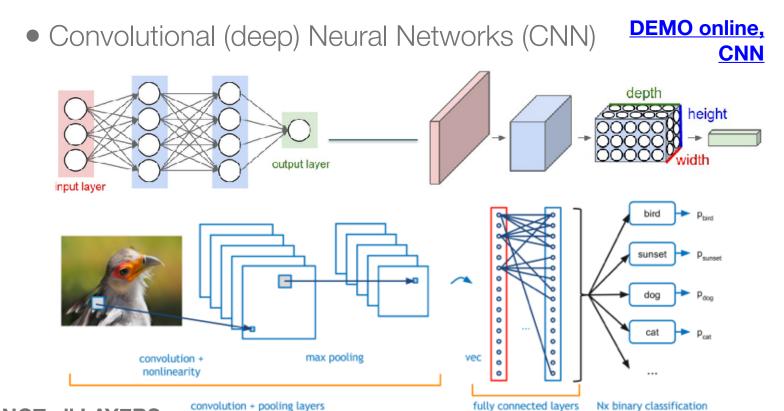
# Machine Learning - Deep Learning fundamentals (69152) CNNs

Master in Robotics, Graphics and Computer Vision Ana C. Murillo



## Today

- What's a CNN?
- Well-known CNN arquitectures



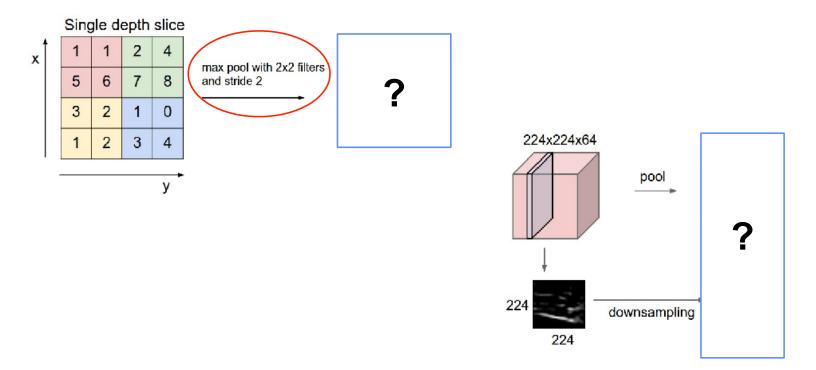
NOT all LAYERS are the same

Fei-Fei, Karpathy, Johnson. Convolutional Neural Networks for Visual Recognition (http://cs231n.stanford.edu) Evan Shelhamer, Jeff Donahue, Jon Long, Yangqing Jia, and Ross Girshick. *Deep Learning for Vision:* a Hands-On <u>Tutorial</u>

### CNNs - Basic Layers

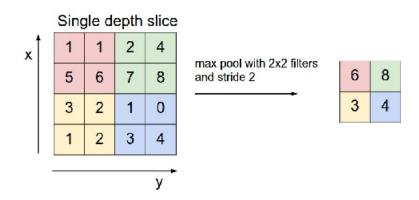
- Input: raw pixel values. RGB image 32x32, volume [32x32x3]
- **Convolutional**: compute output of neurons connected to local input regions (each computes dot product between their weights and the region). Larger volume [32x32x12].
- **RELU**: element-wise activation function (e.g. thresholding at zero). Volume unchanged ([32x32x12]).
- Pooling: downsampling operation. e.g. reduce volume to [16x16x12].
- **Fully-connected**: compute class scores. Each neuron in this layer will be connected to all the numbers in the previous volume. Volume of size [1x1x10].

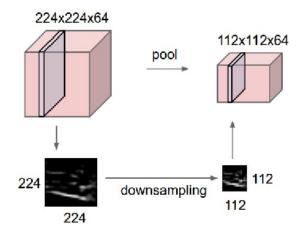
## CNNs - pooling example



Fei-Fei, Karpathy, Johnson. Convolutional Neural Networks for Visual Recognition (http://cs231n.stanford.edu) Evan Shelhamer, Jeff Donahue, Jon Long, Yangqing Jia, and Ross Girshick. *Deep Learning for Vision:* a Hands-On <u>Tutorial</u>

## CNNs - pooling example



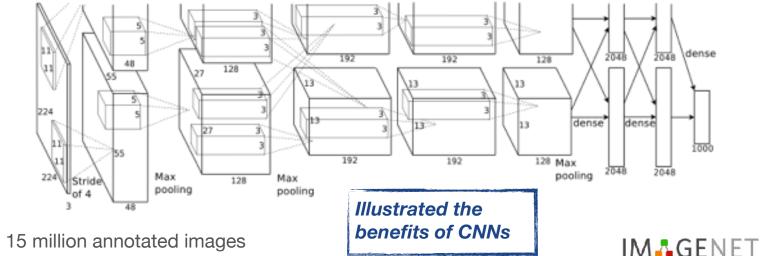


Fei-Fei, Karpathy, Johnson. Convolutional Neural Networks for Visual Recognition (http://cs231n.stanford.edu) Evan Shelhamer, Jeff Donahue, Jon Long, Yangqing Jia, and Ross Girshick. *Deep Learning for Vision:* a Hands-On <u>Tutorial</u>

A bit of "history" about CNNs

## **CNNs - Image Classification**

CNNs basics: AlexNet (Beginning of the new CNN boom): a layered model composed of convolution, subsampling, and further operations followed by a holistic representation.



- over 22000 classes
- ReLU, data augmentation, dropout

#### **CNNs** basics: DeConvNet

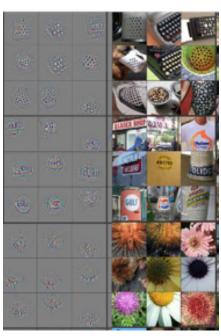






1st layer filters

better understanding: earlier vs later layers



conv<sub>5</sub> DeConv visualization [Zeiler-Fergus]

Similar architecture to AlexNet

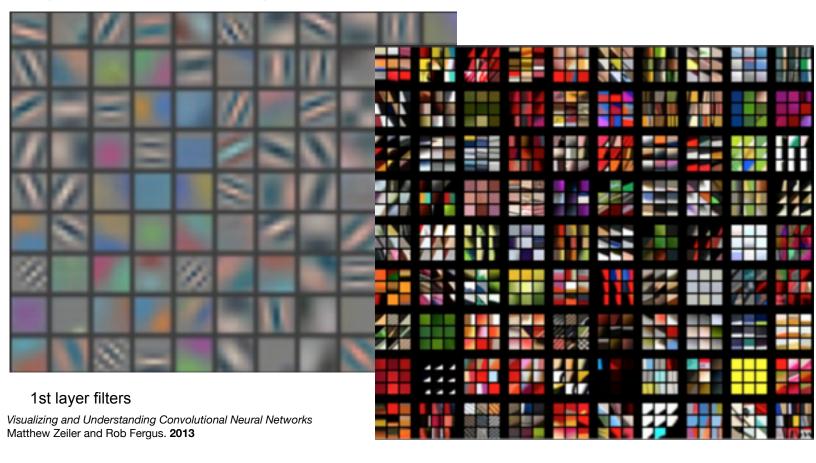
· less training data - smaller filters

• Deconvolutional Network - visualization

Visualizing and Understanding Convolutional Neural Networks Matthew Zeiler and Rob Fergus. 2013

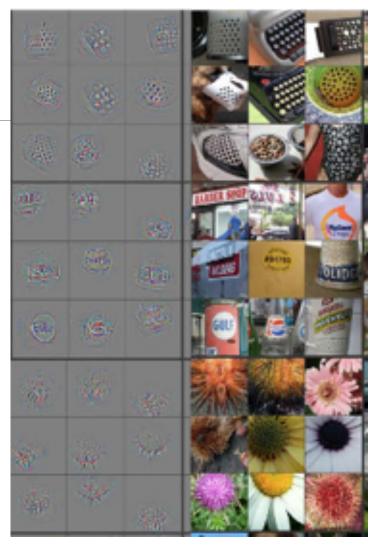
http://people.csail.mit.edu/torralba/research/drawCNN/drawNet.html

#### **CNNs** basics: DeConvNet



**CNNs** basics: DeConvNet

top 9 activations for a few feature maps (projection to pixel space using DeConv and actual image patches)



conv<sub>5</sub> DeConv visualization [Zeiler-Fergus]

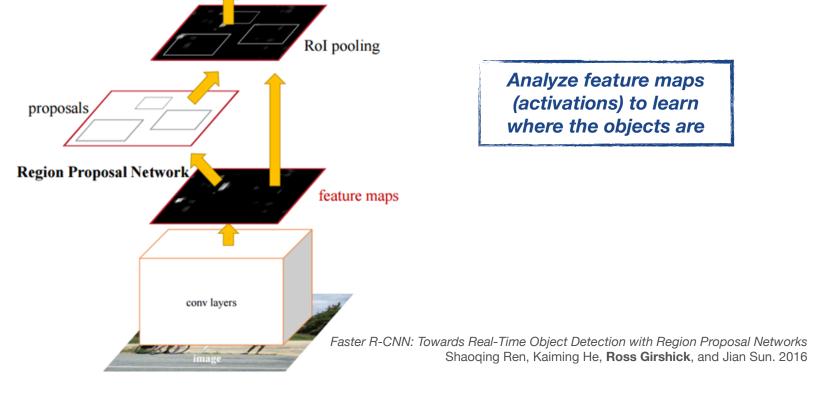
Visualizing and Understanding Convolutional Neural Networks Matthew Zeiler and Rob Fergus. 2013

## CNNs - Image Classification + Detection

#### • Analyze the feature maps: Region - CNN

classifier

(R-CNN - 2013, Fast R-CNN - 2015, Faster R-CNN - 2016)



## CNNs - Image classification

Deeper classification: VGG - very deep ConvNets

- Smaller filters less params
- more depth! —> always good (?)
- Consecutive conv. layers (smaller filters).
- Compare to AlexNet 5 conv. layers



How deep?

Very Deep Convolutional Networks for Large-Scale Image Recognition. K. Simonyan, A. Zisserman. **2014** Deep Face Recognition: O. M. Parkhi, A. Vedaldi, A. Zisserman. BMVC. **2015** 

image
Conv-64
Conv-64
maxpool
Conv-128
Conv-128
maxpool
Conv-256
Conv-256
maxpool
Conv-512
Conv-512
Conv-512
Conv-512
Conv-512
Conv-512
Conv-512

fc-4096

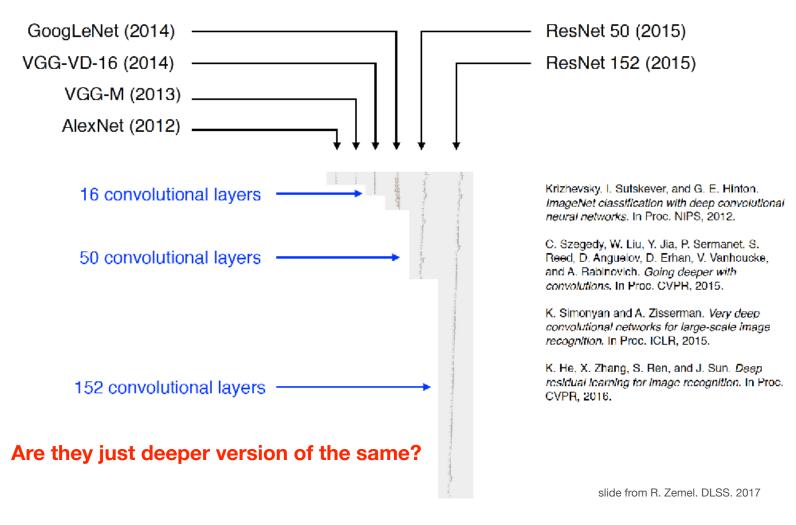
fc-4096

fc-2622

Softmax

slide from R. Zemel. DLSS. 2017

## Image classification (deeper)



## Deeper: How does memory get affected?

image

Conv-64

Conv-128

Conv-128

Conv-256

Conv-512

Conv-512

Conv-512

Conv-512

fc-4096

fc-4096 fc-2622

Softmax

K. Simonyan, A. Zisserman. 2014

```
(not counting biases)
                      memory: 224*224*3=150K params: 0
INPUT: [224x224x3]
CONV3-64: [224x224x64] memory: 224*224*64=3.2M params: (3*3*3)*64 = 1,728
CONV3-64: [224x224x64] memory: 224*224*64=3.2M aparams: (3*3*64)*64 = 36,864
POOL2: [112x112x64] memory: 112*112*64=800K params: 0
CONV3-128: [112x112x128] memory: 112*112*128=1.6M params: (3*3*64)*128 = 73,728
CONV3-128: [112x112x128] memory: 112*112*128=1.6M params: (3*3*128)*128 = 147,456
POOL2: [56x56x128] memory: 56*56*128=400K params: 0
CONV3-256: [56x56x256] memory: 56*56*256=800K params: (3*3*128)*256 = 294,912
CONV3-256: [56x56x256] memory: 56*56*256=800K params: (3*3*256)*256 = 589,824
CONV3-256: [56x56x256] memory: 56*56*256=800K params: (3*3*256)*256 = 589,824
POOL2: [28x28x256] memory: 28*28*256=200K params: 0
CONV3-512: [28x28x512] memory: 28*28*512=400K params: (3*3*256)*512 = 1,179,648
CONV3-512: [28x28x512] memory: 28*28*512=400K params: (3*3*512)*512 = 2,359,296
CONV3-512: [28x28x512] memory: 28*28*512=400K params: (3*3*512)*512 = 2,359,296
POOL2: [14x14x512] memory: 14*14*512=100K params: 0
CONV3-512: [14x14x512] memory: 14*14*512=100K
                                                params: (3*3*512)*512 = 2,359,296
CONV3-512: [14x14x512] memory: 14*14*512=100K params: (3*3*512)*512 = 2,359,296
CONV3-512: [14x14x512] memory: 14*14*512=100K params: (3*3*512)*512 = 2,359,296
POOL2: [7x7x512] memory: 7*7*512=25K params: 0
FC: [1x1x4096] memory: 4096 params: 7*7*512*4096 = 102,760,448
FC: [1x1x4096] memory: 4096 params: 4096*4096 = 16,777,216
FC: [1x1x1000] memory: 1000 params: 4096*1000 = 4,096,000
TOTAL memory: 24M * 4 bytes ~= 96MB / image (only forward! ~*2 for bwd)
TOTAL params: 138M parameters
                                         Very Deep Convolutional Networks for Large-Scale Image Recognition.
```

## Deeper: How does memory get affected?

```
(not counting biases)
                     memory: 224*224*3=150K params: 0
INPUT: [224x224x3]
CONV3-64: [224x224x64] memory: 224*224*64=3.2M params: (3*3*3)*64 = 1,728
                                                                                         Note:
CONV3-64: [224x224x6()] memory: 224*224*64=3.2M arams: (3*3*64)*64 = 36,864
POOL2: [112x112x64] memory: 112*112*64=800K params: 0
                                                                                         Most memory is in
CONV3-128: [112x112x128] memory. 112 112*128=1.6M params: (3*3*64)*128 = 73,728
                                                                                         early CONV
CONV3-128: [112x112x128] memory: 112*112*128=1.6M params: (3*3*128)*128 = 147.456
POOL2: [56x56x128] memory: 56*56*128=400K params: 0
CONV3-256: [56x56x256] memory: 56*56*256=800K params: (3*3*128)*256 = 294,912
CONV3-256: [56x56x256] memory: 56*56*256=800K params: (3*3*256)*256 = 589,824
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POOL2: [28x28x256] memory: 28*28*256=200K params: 0
CONV3-512: [28x28x512] memory: 28*28*512=400K params: (3*3*256)*512 = 1,179,648
CONV3-512: [28x28x512] memory: 28*28*512=400K params: (3*3*512)*512 = 2,359,296
CONV3-512: [28x28x512] memory: 28*28*512=400K params: (3*3*512)*512 = 2,359,296
POOL2: [14x14x512] memory: 14*14*512=100K params: 0
                                                                                         Most params are
CONV3-512: [14x14x512] memory: 14*14*512=100K params: (3*3*512)*512 = 2,359,296
                                                                                         in late FC
CONV3-512: [14x14x512] memory: 14*14*512=100K params: (3*3*512)*512 = 2,359,296
CONV3-512: [14x14x512] memory: 14*14*512=100K params: (3*3*512)*512 = 2,359,296
POOL2: [7x7x512] memory: 7*7*512=25K params:
FC: [1x1x4096] memory: 4096 params: 7*7*512*4096 = 102,760,448
FC: [1x1x4096] memory: 4096 params: 4096*4 96 = 16,777,216
FC: [1x1x1000] memory: 1000 params: 4096*1008 = 4,096,000
TOTAL memory: 24M * 4 bytes ~= 96MB / image (only forward! ~*2 for bwd)
TOTAL params: 138M parameters
```

slide from Fei-Fei Li & Justin Johnson & Serena Yeung http://cs231n.stanford.edu

What is more relevant for batch size design decisions?

Very Deep Convolutional Networks for Large-Scale Image Recognition. K. Simonyan, A. Zisserman. 2014 image

Conv-64

CONV-04

пахроо

Conv-128

Conv-128

Пахроо

Conv-256

Conv-256

maxpool

Conv-512

Conv-512

Conv-512

Παλροσί

Conv-512

Conv-512

Conv-512

Шахроо

fc-4096

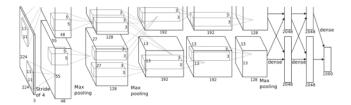
fc-4096

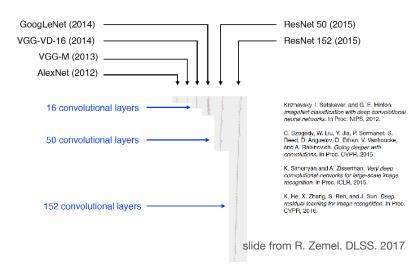
fc-2622

Softmax

## Image classification (deeper)

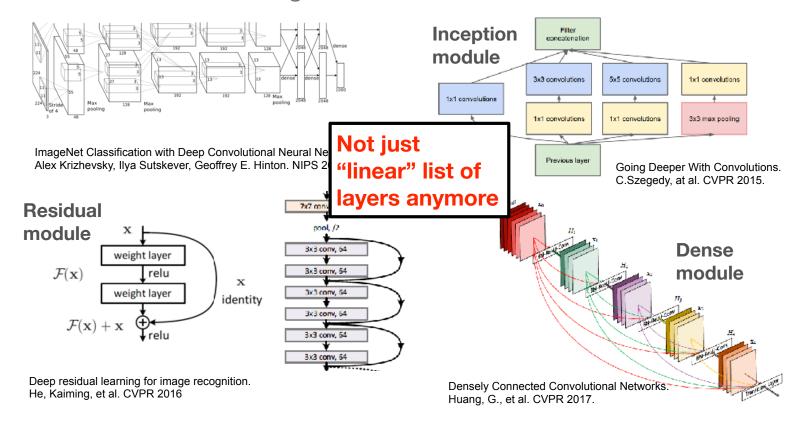
### • Not only more layers! it's getting hard(er) to train ...





#### Some reference modules for CNN architectures ...

• to train better: GoogLeNet, ResNet, DenseNet, ...



Open or interesting problems related to deep learning?

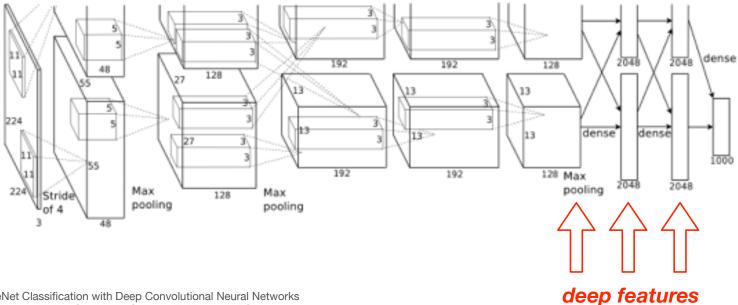
Not enough data to train? (or resources)

## **CNNs & Transfer Learning**

• CNNs are able to generalize well!

Lab 2 you'll practice some of this

- great **features**
- fine-tuning

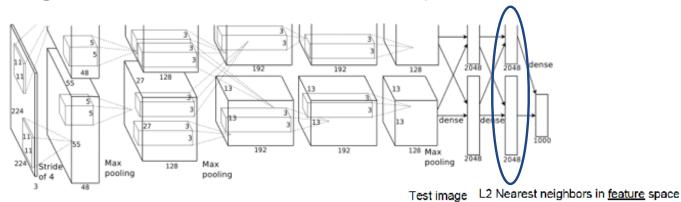


## Transfer Learning

- What is it?
- When would you use transfer learning?
- Types of transfer learning?

## Transfer Learning: features

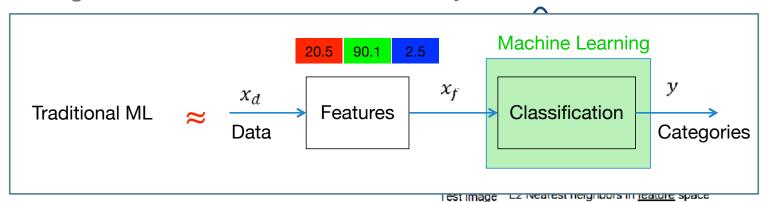
• E.g., features from AlexNet last layer: 4096 dims. vector



How do we get these features?

## Transfer Learning: features

• E.g., features from AlexNet last layer: 4096 dims. vector

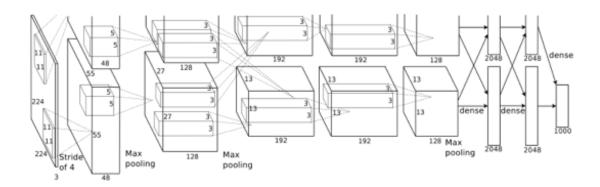


How do we use these features?



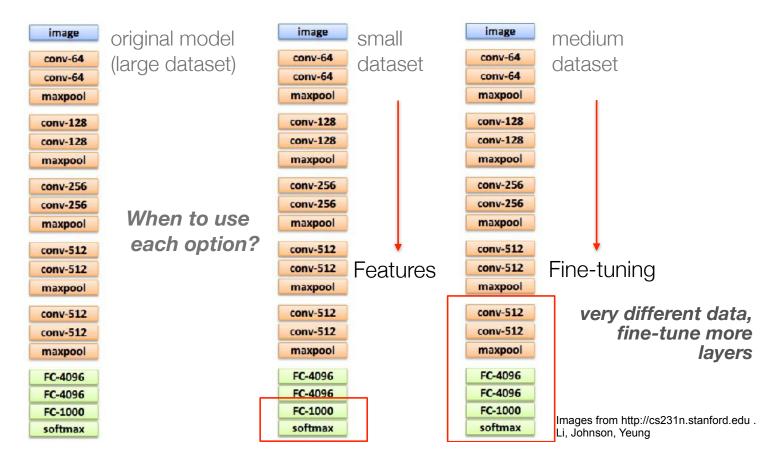
## Transfer Learning: fine-tune

- For example, fine-tune ImageNet AlexNet for non Image-Net classes
- Basically, initialise weighs to something more "interesting" than random (careful also with hyperparameters!)



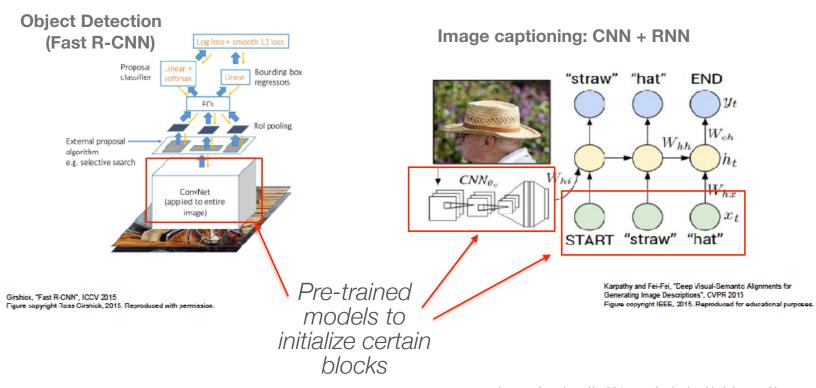
## Transfer Learning

... when not enough resources to train from scratch



## Transfer Learning: fine-tuning

• not just that! very very spread out strategy:



Images from http://cs231n.stanford.edu . Li, Johnson, Yeung

## Lab 2: NN and CNNs applied in Computer Vision

- Understand a DNN implemented from scratch
- Implement a toy CNN with Keras
- Fine-tune a well-known CNN architecture with Keras

All this is applied to Image Classification

- Optional tasks:
  - implement variations of the classification networks
  - explore object recognition model
  - explore semantic segmentation model

Available in Moodle.

Please check the prior-work task (prepare your set up and data)

#### TO-DO ...

- Lab 2 TOMORROW (18 OCT , 20 OCT) -> WED. @ A07 / FRIDAY @ L0.06a ADA BYRON
- PLEASE have your computer ready with Tensorflow2+Keras (ideally with GPU available)
   AND/OR we will use Google COLAB
- Recommended COLAB tutorial if you have not used it much before:
   https://colab.research.google.com/notebooks/intro.ipynb
   https://colab.research.google.com/notebooks/basic\_features\_overview.ipynb
   Loading data: Drive, Sheets, and Google Cloud Storage

#### **ASSIGNMENT BEFORE YOUR LAB:**

- 1. Pick 5 to 10 classes from one of these datasets (do not take all images from each class if you don't have space)
  - https://www.kaggle.com/kmader/food41/version/5#
  - http://www.robots.ox.ac.uk/~vgg/data/pets/
  - http://www.robots.ox.ac.uk/~vgg/data/flowers/
  - any other dataset you have?
- 2. Put them in folders like ———————>
- 3. Upload to Google Drive if you plan to use COLAB

```
data/
dogs/
dog001.jpg
dog002.jpg
...
cats/
cat001.jpg
cat002.jpg
```

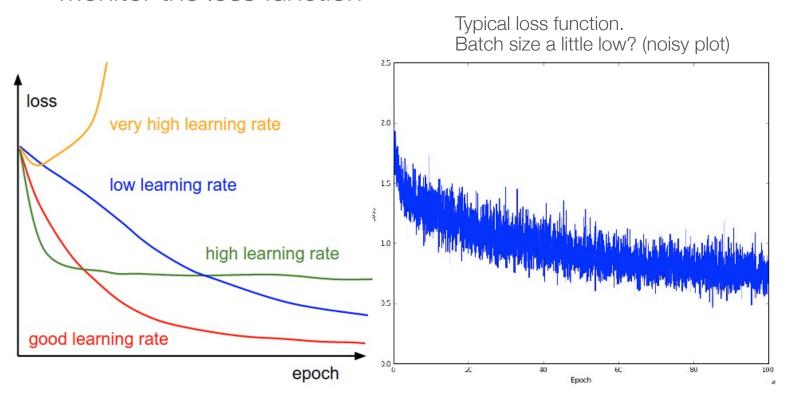
## Lab 2: NN and CNNs applied in Computer Vision

- Frameworks
  - Caffe, Tensorflow+Keras, Pytorch, ...
- Model zoos
  - in every framework (you should always start by looking into existing models. "rare" to "require" to implement a network from scratch)

Initial sanity checks (after a few "toy" iterations)

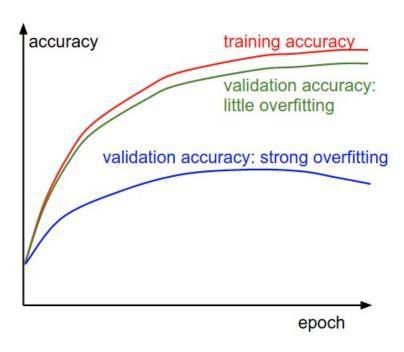
- Correct loss at chance
- Increasing regularisation strength increases loss
- Overfit a tiny training set (you can set regularisation strength to zero to better see this)

Monitor the loss function



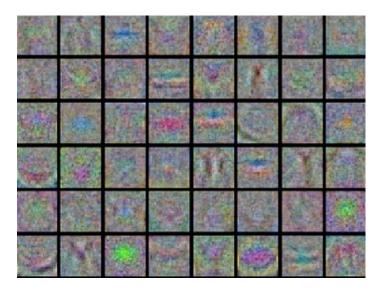
http://cs231n.stanford.edu Class notes

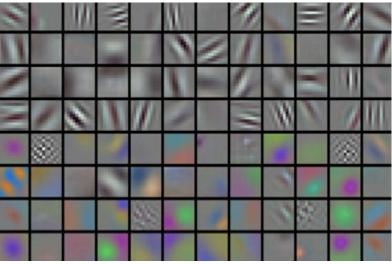
Monitor train/val accuracy



http://cs231n.stanford.edu Class notes

Visualize first conv layer weights





#### Additional tips:

- Decay your learning rate during training
- If you can afford it
  - Search for good hyperparameters with random search (not grid search). Fom coarse to fine
  - Consider model ensembles (not in our labs)

## Lab 2: NN and CNNs applied in Computer Vision

- Understand a DNN implemented from scratch
- Implement a toy CNN with Keras
- Fine-tune a well-known CNN architecture with Keras

All this is applied to Image Classification

- Optional tasks:
  - implement variations of the classification networks
  - explore object recognition model
  - explore semantic segmentation model

Exercise now (start for Lab2)

**COLAB**