



Graphics and
Imaging Lab

Computational Imaging – Master in Robotics, Graphics, and Computer Vision





✓ Computational displays (Lecture #6)

Computational illumination (Lecture #7)

✓ Computational displays (Lecture #6)

Computational illumination (Lecture #7)

- Generalized optics encode world into intermediate representation.
- Generalized computation decodes representation into multiple images.





✓ Computational displays (Lecture #6)

→ Computational illumination (Lecture #6)



- a) Ultrashort exposure time
- b) Ultrashort illumination

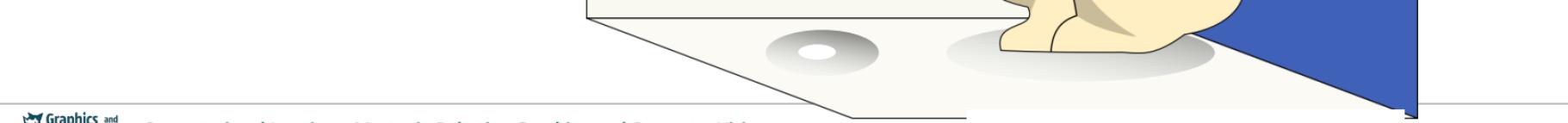
H. Edgerton's strobsocope (1930)



N. Edgerton's stroboscope (1930)

19



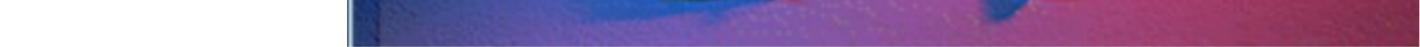












(computational light transport)





Does this ring a bell?

✓ Computational displays (Lecture #6)

→ Computational illumination (Lecture #6)

a) Pulsed/Stroboscopic Light, b) Temporally Modulated Light, ...

b) A decent mask (e.g. an LCoS display) in front of the light source





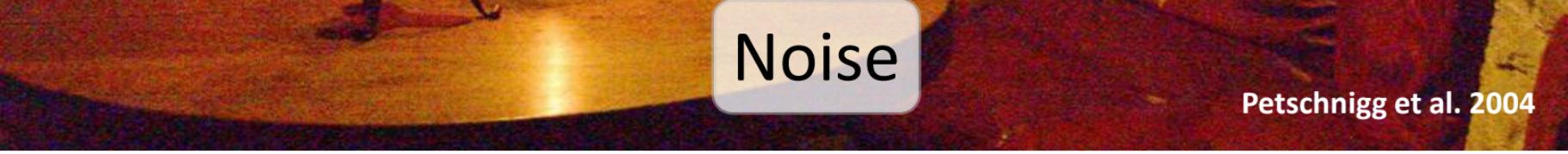
Red Eye

Petschnigg et al. 2004



Unflattering Lighting

Petschnigg et al. 2004



Noise

Petschnigg et al. 2004

A lot of Noise

Petschnigg et al. 2004

Ruined Ambiance

Petschnigg et al. 2004

- + Sharp
- Artificial Light
- Jarring Look

- Lacks Detail
- + Ambient Light
- + Natural Look

Petschnigg et al. 2004

Denoising Result

Petschnigg et al. 2004

No-Flash

Petschnigg et al. 2004

Denoising Result

Petschnigg et al. 2004

$$\dot{i} = tp$$

$$\mathbf{i} = \mathbf{t}\mathbf{p}$$

$$\mathbf{i} = \mathbf{T}\mathbf{p}$$

$\mathbf{i} = \mathbf{T}\mathbf{p}$ Light Transport Equation

[Ng et al. 2003]





i
(64x1)

8x8 image

Known 
(64x1)

8x8 image



Known **i**
(64x1)

Unknown **T**
(64x3)

p
(4x1)

8x8 image

Known **i**
(64x1)

Unknown **T**
(64x3)

p
(4x1)

8x8 image

Known **i**
(64x1)

Unknown **T**
(64x3)

p
(4x1)

Maybe known
Maybe unknown

8x8 image

Known **i**
(64x1)

Unknown **T**
(64x3)

p
(4x1)

Maybe known
Maybe unknown

8x8 image

Known **i**
(64x1)

Unknown **T**
(64x3)

p
(4x1)

Maybe known
Maybe unknown

8x8 image

Known

i
(20e6x1)

Unknown

T
(20e6x?)

p
(?x1)

Maybe known
Maybe unknown

20MP image



(a)

(b)

(c)

(d)

(a) Scene

(b) Direct Component

(c) Global Component





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Inspired by a slide by Srinivas Narasimhan



Correspondence is hard!



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surface or volume.



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Inspired by a slide by Srinivas Narasimhan



Correspondence becomes much easier!



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many images and takes time

Can we do better?



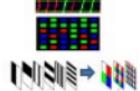
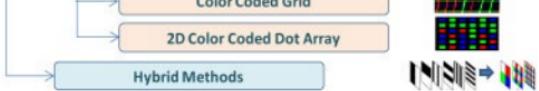
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Inspired by a slide by Srinivas Narasimhan



- Need very few images (one or two), real-time and dynamic scenes
- But needs a more complex correspondence algorithm

[Geng 2011]



Slow, robust

Fast, fragile



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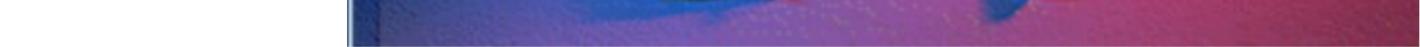
Sources: [CMU 15-463](#), [Dartmouth College CS89/189](#).

• Can we do more?









$$\dot{i} = tp$$

$$\mathbf{i} = \mathbf{T}\mathbf{p}$$

[Debevec et al. 2000]

(N²x1)

Known

(N²xM)

Unknown

(Mx1)

Maybe
(un)known

NxN image



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[O'Toole & Kutulakos 2010]



Avatar © 2009 20th Century Fox & Weta Digital Ltd

Source: [Pantaleoni et al. SIG 2010]



Halo 3 ©Bungie

Source: [Chen and Liu, SIG 2008]





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n pixels

Non-symmetric LTM

Symmetric LTM

n pixels





(c)



(d)



(e)



(f)

[O'Toole et al. 2012]



Source: [O'Toole et al. 2012]



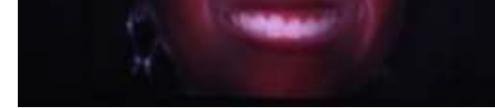
(d)

(f)

SOURCE: LOU, ROQUE ET AL. 2012

light paths





Indirect light paths



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Source: [O'Toole et al. 2012]

light paths





for direct multi-view separation.



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$$L[c, \ell] = L_d[c, \ell] + L_g[c, \ell]$$

| | |
radiance direct global

$$L_g[c, \ell] = \sum_P A[\ell, J] L[\ell, J]$$

BRDF and geometry

$$L[c, t] = L_d[c, t] + \alpha L_g[c, t]$$

fraction of activated source elements

$$L[c, t] = L_d[c, t] + \alpha L_g[c, t]$$

$$L[c, t] = (1 - \alpha) L_g[c, t]$$

fraction of activated source elements





Direct



Global



Direct



Global





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(N²x1)

Known

(N²xM)

Known

(Mx1)

Maybe
(un)known

NxN image

(MxN²)

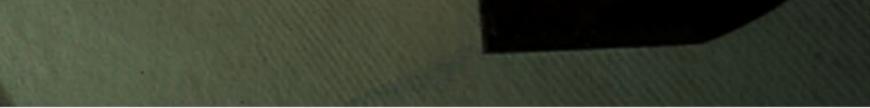
Known

(N²x1) (Mx1)

Known Unknown

NxN light sources







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(N²x1)

(N²xM)

(Mx1)

Known

Unknown

Calibrated

NxN image



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decomposition, denazing or dual photography.



