

Background

Linear Algebra

$$\begin{aligned}\|\mathbf{x}\|_p &= (\sum |x_i|^p)^{1/p} & \|\mathbf{x}\|_\infty &= \max |x_i| \\ \text{tr}(\mathbf{A}\mathbf{x}\mathbf{x}^T) &= \mathbf{x}^T \mathbf{A} \mathbf{x} \\ |\mathbf{AB}| &= |\mathbf{A}||\mathbf{B}| & |\mathbf{A}^m| &= |\mathbf{A}|^m \\ (\mathbf{A} + \mathbf{UCV})^{-1} &= \mathbf{A}^{-1} - \mathbf{A}^{-1} \mathbf{U}(\mathbf{C} + \mathbf{VA}^{-1} \mathbf{U})^{-1} \mathbf{VA}^{-1} \\ (\mathbf{A} + \mathbf{B})^{-1} &= \mathbf{A}^{-1} - \mathbf{A}^{-1}(\mathbf{A} + \mathbf{B})^{-1} \mathbf{A}^{-1} \\ \mathbf{U}(\mathbf{VU} + \mathbf{I})^{-1} &= (\mathbf{UV} + \mathbf{I})^{-1} \mathbf{U} \\ \mathbf{I} - \mathbf{A}(\mathbf{I} + \mathbf{A})^{-1} &= (\mathbf{I} + \mathbf{A})^{-1}\end{aligned}$$

Probability

$$\begin{aligned}B(a, b) &= \Gamma(a)\Gamma(b)\Gamma^{-1}(a+b) \\ \Gamma(a) &= \int_0^\infty e^{-x} x^{a-1} dx \\ \text{Ber}(x|\theta) &= \theta^x (1-\theta)^{1-x} \quad 0 \leq \theta \leq 1 \\ p_Y(y) &= p_X(g^{-1}(y)) \left| \det \frac{\partial g^{-1}(y)}{\partial y} \right| \\ \mathbb{E}_{Y|X}[Y] &= \mathbb{E}_Y[Y|X] \mathbb{I} \mathbb{E}_Y[\mathbb{E}_X[X|Y]] = \mathbb{E}_X[X] \\ \mathbb{E}_{X,Y}[f(X, Y)] &= \mathbb{E}_X \mathbb{E}_{Y|X}[f(X, Y)|X] \\ \text{Var}(X) &= \mathbb{E}[\text{Var}(X|Y)] + \text{Var}(\mathbb{E}[X|Y]) \\ \mathbb{V}[X+Y] &= \text{Var}[X] + \text{Var}[Y] + 2\text{Cov}(X, Y) \\ \text{Cov}(\mathbf{X}, \mathbf{Y}) &= \mathbb{E}[\mathbf{XY}^T] - \mathbb{E}[\mathbf{X}]\mathbb{E}[\mathbf{Y}]^T \\ \text{Cov}(\mathbf{AX} + c, \mathbf{BY} + d) &= A\text{Cov}(\mathbf{X}, \mathbf{Y})B^T \\ \mathcal{N}(x|\mu, \Sigma) &= \frac{\exp(-\frac{1}{2}(x-\mu)^T \Sigma^{-1}(x-\mu))}{(2\pi)^{D/2} |\Sigma|^{1/2}} \\ X &= \Sigma^{1/2} \mathcal{N}(0, 1) + \mu \sim \mathcal{N}(\mu, \Sigma) \\ Y &= MX + b \sim \mathcal{N}(M\mu + b, M\Sigma M^T) \\ X, Y &\stackrel{\text{iid}}{\sim} \mathcal{N}: \quad X+Y \sim \mathcal{N}(\mu + \mu', \Sigma + \Sigma')\end{aligned}$$

Conditional Gaussian

$$\begin{aligned}P\left(\begin{bmatrix} \mathbf{X} \\ \mathbf{Y} \end{bmatrix}\right) &= \mathcal{N}\left(\begin{bmatrix} \mathbf{X} \\ \mathbf{Y} \end{bmatrix}; \begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix}, \begin{bmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{bmatrix}\right) \\ p(\mathbf{Y}|\mathbf{X} = \mathbf{x}) &= \mathcal{N}(\mu, \Sigma) \\ \mu &= \mu_2 + \Sigma_{21}\Sigma_{11}^{-1}(\mathbf{x} - \mu_1) \\ \Sigma &= \Sigma_{22} - \Sigma_{21}\Sigma_{11}^{-1}\Sigma_{12}\end{aligned}$$

Inequalities and Estimators

$$\begin{aligned}\text{Jensen:} \quad \log(\sum_i \lambda_i^{(\geq 0)} x_i) &\geq \sum_i \lambda_i \log(x_i) \\ \text{Chebyshev: } \mathbb{P}(|\hat{X} - X| \geq \varepsilon) &\leq \frac{MSE[\hat{X}]}{\varepsilon^2} \\ \text{Estimators:} \quad \text{Unbiased: } \mathbb{E}[\hat{\theta}] &= \theta^* \\ \text{Consistent: } \mathbb{P}(|\hat{\theta} - \theta^*| < \varepsilon) &\rightarrow 0 \text{ convP} \\ \text{Asymp Normal: } (\hat{\theta} - \theta^*)\hat{se}^{-1} &\sim \mathcal{N}(0, 1) \\ \text{Rao-Cra.: } \mathbb{E}_{x|\theta}[(\theta - \hat{\theta})^2] &\geq \frac{(\frac{\partial}{\partial \theta} b_\theta + 1)^2}{\mathbb{E}_{x|\theta}[\Lambda^2]} + b_\theta^2 \\ b_\theta &= \mathbb{E}_{x|\theta}[\hat{\theta}] - \theta \quad \Lambda = \frac{\partial}{\partial \theta} \log p(x|\theta) \\ \mathbb{E}_{x|\theta}[\Lambda] &= 0 \rightarrow \mathbb{E}_{x|\theta}[\Lambda \hat{\theta}] = \frac{\partial}{\partial \theta} b_\theta + 1 \\ \rightarrow \text{Cov}(\Lambda, \hat{\theta}) &\rightarrow \text{Cauchy} \\ \text{Var}[\hat{\theta}] &\geq \mathcal{I}_n(\theta)^{-1} = -\mathbb{E}\left[\frac{\partial^2 \log p[\mathcal{X}_n|\theta]}{\partial \theta^2}\right]^{-1} \\ \text{Efficiency of } \hat{\theta}: e(\theta_n) &= \frac{1}{\text{Var}[\hat{\theta}_n|\mathcal{I}_n(\theta)]} \\ \hat{\theta}_{JS} &= \left(1 - \frac{(d-2)\sigma^2}{\|\mathbf{y}\|^2}\right) \mathbf{y}\end{aligned}$$

$$\begin{aligned}\text{Derivatives: } \frac{\partial}{\partial \mathbf{x}}(\mathbf{b}^T \mathbf{x}) &= \frac{\partial}{\partial \mathbf{x}}(\mathbf{x}^T \mathbf{b}) = \mathbf{b} \\ \frac{\partial}{\partial \mathbf{x}}(\mathbf{x}^T \mathbf{Ax}) &= (\mathbf{A}^T + \mathbf{A})\mathbf{x} \\ \frac{\partial}{\partial \mathbf{X}}(\mathbf{c}^T \mathbf{Xb}) &= \mathbf{cb}^T \\ \frac{\partial}{\partial \mathbf{x}}\|\mathbf{x}\|_2 &= \frac{\mathbf{x}}{\|\mathbf{x}\|_2} \quad \frac{\partial}{\partial \mathbf{x}}\|f(\mathbf{x})\|_1 = \frac{\partial f(\mathbf{x})}{\partial \mathbf{x}}^T \text{sgn}(\mathbf{x}) \\ \frac{\partial}{\partial \mathbf{x}}(\|\mathbf{Ax} - \mathbf{b}\|_2^2) &= 2\mathbf{A}^T(\mathbf{Ax} - \mathbf{b}) \\ \frac{\partial}{\partial \mathbf{X}}(\|\mathbf{X}\|) &= |\mathbf{X}| \cdot \mathbf{X}^{-1}, \quad |\mathbf{X}|^{-1} = |\mathbf{X}^{-1}| \\ \frac{\partial}{\partial \mathbf{X}}f(\mathbf{X})^T &= \frac{\partial f(\mathbf{X})}{\partial \mathbf{X}}^T \quad \frac{\partial}{\partial \mathbf{X}}\text{tr}f(\mathbf{X}) = \text{tr}\frac{\partial f(\mathbf{X})}{\partial \mathbf{X}} \\ \frac{\partial}{\partial \mathbf{X}}\det f(\mathbf{X}) &= \det f(\mathbf{X}) \text{tr}(f(\mathbf{X})^{-1} \frac{\partial f(\mathbf{X})}{\partial \mathbf{X}}) \\ \frac{\partial}{\partial \mathbf{X}}f(\mathbf{X})^{-1} &= -f(\mathbf{X})^{-1} \frac{\partial f(\mathbf{X})}{\partial \mathbf{X}} f(\mathbf{X})^{-1}\end{aligned}$$

Quadratic Forms

$$\begin{aligned}\mathbf{x}^T \mathbf{Ax} + 2\mathbf{b}^T \mathbf{x} + c &= (\mathbf{x} + \mathbf{A}^{-1}\mathbf{b})^T \mathbf{A}(\mathbf{x} + \mathbf{A}^{-1}\mathbf{b}) - \mathbf{b}^T \mathbf{A}^{-1} \mathbf{b} + c, \\ ax^2 + bx + c &= (x + \frac{b}{2a})^2 - (\frac{b}{2a})^2 + c\end{aligned}$$

Information Theory

$$\begin{aligned}H[p] &= \mathbb{E}_{\mathbf{x} \sim p}[-\log p(\mathbf{x})] \\ H[p||q] &= \mathbb{E}_{\mathbf{x} \sim p}[-\log q(\mathbf{x})] \\ \text{KL}[p||q] &= H[p||q] - H[p] \\ \text{KL}[p||q] &= \mathbb{E}_{\theta \sim p} \left[\log \left(\frac{p(\theta)}{q(\theta)} \right) \right] \\ \text{KL}[p||q] \neq \text{KL}[q||p] &\geq 0 \\ H[\mathbf{X}] &= \mathbb{E}_{\mathbf{x} \sim p}[-\log p(\mathbf{X})] \\ H[\mathbf{X}|\mathbf{Y} = y] &= \mathbb{E}_{\mathbf{x} \sim p(\cdot|y)}[-\log p(\mathbf{X}|y)] \\ H[\mathbf{X}|\mathbf{Y}] &= \mathbb{E}_y[H[\mathbf{X}|\mathbf{Y} = y]] \\ H[\mathbf{X}|\mathbf{Y}] &= H[\mathbf{Y}|\mathbf{X}] + H[\mathbf{X}] - H[\mathbf{Y}] \\ H[\mathbf{X}, \mathbf{Y}] &= \mathbb{E}_{(\mathbf{x}, \mathbf{y}) \sim p(\cdot, \cdot)}[-\log p(\mathbf{X}, \mathbf{Y})] \\ \mathbb{I}[\mathbf{X}; \mathbf{Y}] &= H[\mathbf{X}] - H[\mathbf{X}|\mathbf{Y}] \geq 0 \\ \mathbb{I}[\mathbf{X}; \mathbf{Y}|\mathbf{Z}] &= \mathbb{I}[\mathbf{X}; \mathbf{Y}, \mathbf{Z}] - \mathbb{I}[\mathbf{X}; \mathbf{Z}] \\ H(\mathcal{N}(\mu, \Sigma)) &= \frac{1}{2} \ln(\det(2\pi e \Sigma)) \\ \text{KL}(\mathcal{N}(a, A)||\mathcal{N}(b, B)) &= \frac{1}{2}(\text{tr}(B^{-1}A) + (a-b)^T B^{-1}(a-b) - d + \ln(\frac{\det B}{\det A}))\end{aligned}$$

Risks

$$\begin{aligned}\text{Expected Risk: } R(f) &= P(f(X) \neq y) \\ \mathcal{R}(f) &= \sum_{y \leq k} P(y) \mathbb{E}_{P(x|y)}[1_{f(x) \neq y} | Y = y] \\ \text{Empirical Risk Minimizer (ERM)} \hat{f}: & \\ \hat{f} &\in \arg \min_{f \in \mathcal{H}} \hat{R}(\hat{f}, \mathcal{D}^{train}) \\ \hat{R}(\hat{f}, \mathcal{D}^{train}) &= \frac{1}{n} \sum_{i=1}^n \mathcal{L}(Y_i, \hat{f}(X_i)) \\ \hat{R}(\hat{f}, \mathcal{D}^{test}) &= \frac{1}{m} \sum_{i=n+1}^{n+m} \mathcal{L}(Y_i, \hat{f}(X_i)) \\ \text{Loss Fcts: } \mathcal{L}(y, z) &= z - w^T x \\ \mathcal{L}^{0/i} &= \mathbb{I}[\text{sign}(z) \neq y] \\ \mathcal{L}^{hinge} &= \max(0, 1 - yz) \quad \text{for SVM's} \\ \mathcal{L}^{percep} &= \max(0, -yz) \\ \mathcal{L}^{logistic} &= \log(1 + \exp(-yz)) \\ \mathcal{L}^{exp} &= \exp(-yz) \quad \text{for AdaBoost} \\ \mathcal{L}^{CE} &= -[y' \log z' + (1 - y') \log(1 - z')] \\ y' &= \frac{1+y}{2}, \quad z' = \frac{1+z}{2}\end{aligned}$$

Optimization

$$\begin{aligned}\theta^{(t+1)} &\leftarrow \theta^{(t)} - \eta \nabla_\theta \mathcal{L} + \mu(\theta^{(t)} - \theta^{(t-1)}) \\ GD: \quad \theta^{(t+1)} &\leftarrow \theta^{(t)} - \eta \nabla_\theta \mathcal{L} \\ SGD: \quad \theta^{(t+1)} &\leftarrow \theta^{(t)} - \eta \nabla \mathcal{L}(\theta^{(t)}, x_i, y_i) \\ NGD: \quad \theta^{(t+1)} &\leftarrow \theta^{(t)} - \eta (\nabla_\theta^2 \mathcal{L})^{-1} \nabla_\theta \mathcal{L} \\ &\rightarrow f(x+t) \approx f(x) + t f'(x) + \frac{1}{2} f''(x) t^2 = 0\end{aligned}$$

Parametric Density Estimation

$$\begin{aligned}\text{Assume prior } \mathbb{P}(\theta), \\ \text{Likelihood: } \mathbb{P}[\mathcal{X}|\theta] &= \prod_{i \leq n} p(x_i|\theta) \\ \hat{\theta}_{MLE} &= \arg \max_\theta \mathbb{P}[\mathcal{X}|\theta] \\ \hat{\theta}_{MAP} &= \arg \max_\theta [P(\theta|\mathcal{X}) = P(\mathcal{X}|\theta)P(\theta)] \\ \text{Solve } \nabla_\theta \log P(\mathcal{X}|\theta)P(\theta) &= 0\end{aligned}$$

1-D Gaussian Bayesian learning

$$\begin{aligned}X|\theta &\sim \mathcal{N}(\theta, \sigma^2) & \theta &\sim \mathcal{N}(m_0, s_0^2) \\ \theta|X &\sim \mathcal{N}(\mu_n, \sigma_n^2) \\ \sigma_n^2 &= \frac{\sigma^2 s_0^2}{ns_0^2 + \sigma^2}, \quad \mu_n = \frac{ns_0^2 \bar{x} + m_0 \sigma^2}{ns_0^2 + \sigma^2}\end{aligned}$$

Recursive Bayesian density learning

$$\mathcal{X}^n = x_{1:n} : p(\theta|\mathcal{X}^n) = \frac{p(x_n|\theta)p(\theta|\mathcal{X}^{n-1})}{\int p(x_n|\theta)p(\theta|\mathcal{X}^{n-1})d\theta}$$

Frequentist vs Bayesian

Bayes: priors, distributions, needs efficient integration, adds regularization term.
Frequentist: no priors, point estimate, requires only differentiation methods.
MLE are consistent, equivariant, asymptotically normal, asymptotically efficient (no efficient for finite samples).

Data Types

monadic: $X:O \rightarrow \mathbb{R}^d$ dyadic: $X:O_1 \times O_2 \rightarrow \mathbb{R}^d$. pairwise: $X:O_1 \times O_1 \rightarrow \mathbb{R}^d$ polyadic
data: $X:O_1 \times O_2 \times O_3 \rightarrow \mathbb{R}^d$ nominal = qualitative (sweet, sour ...), ordinal = absolute order, quantitative = numbers

Regression

$$\begin{aligned}\text{Model of data: } \mathbf{Y} &= \mathbf{X}\beta^* + \varepsilon \\ \mathbf{X} \in \mathbb{R}^{(d+1) \times n} \quad \beta &\in \mathbb{R}^{d+1} \quad \varepsilon \sim \mathcal{N}(\mathbf{0}, \mathbb{I}\sigma^2) \\ \mathbf{Y}|\mathbf{X}, \beta, \sigma^2 &\sim \mathcal{N}(\mathbf{Y}; \mathbf{X}^T \beta, \mathbb{I}_{(d+1)} \sigma^2)\end{aligned}$$

MLE: Ordinary Least Squares

$$\begin{aligned}\text{OLSE is unbiased, orthogonal projection} &\text{ with lowest variance. differentiate wrt } \beta. \\ \mathcal{L} = \text{RSS}(\beta) &= \sum_{i=1}^n (y_i - x_i^T \beta)^2 = (\mathbf{y} - \mathbf{X}\beta)^2 \\ \text{Estimator: } \hat{\beta}^{\text{OLS}} &= (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y} \\ \text{Prediction: } \hat{\mathbf{y}} = \mathbf{X}\hat{\beta} &= \mathbf{X}(\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y} \\ \text{MAP: Ridge Regression (L}^2 \text{ penalty)} & \\ \text{Penalize energy in } \beta. \text{ Prior: } \beta &\sim \mathcal{N}(\mathbf{0}, \lambda^{-1} \mathbb{I}) \\ \text{Loss: } \mathcal{L} &= (\mathbf{y} - \mathbf{X}\beta)^T (\mathbf{y} - \mathbf{X}\beta) + \lambda \beta^T \beta \\ \text{Estimator: } \hat{\beta}^{\text{ridge}} &= (\mathbf{X}^T \mathbf{X} + \lambda \mathbb{I})^{-1} \mathbf{X}^T \mathbf{y}\end{aligned}$$

GDM: MAP: Lasso (L¹ penalty)

$$\begin{aligned}\text{Penalize full } \beta. \text{ Lasso has no closed form.} \\ \beta &\sim \text{Lapl}(0, \lambda^{-1}) = \frac{\lambda}{2} \exp(-\lambda|\beta|) \\ \mathcal{L} &= \sum_{i=1}^n (y_i - x_i^T \beta)^2 + \lambda \sum_{j=1}^d |\beta_j| \\ &= (\mathbf{y} - \mathbf{X}\beta)^T (\mathbf{y} - \mathbf{X}\beta) + \lambda \|\beta\|_1 \\ \text{Bayesian view: } Y|(\mathbf{X}, \beta) &\sim \mathcal{N}(x^T \beta, \sigma^2 \mathbb{I})\end{aligned}$$

d-Dim Bayesian Linear Regression

$$\begin{aligned}\text{Prior: } \beta &\sim \mathcal{N}(\mu_0, \Lambda^{-1}) \\ \text{Likelihood: } Y|\beta, \mathbf{X}, \sigma &\sim \mathcal{N}(X\beta, \sigma_n^2 \mathbb{I}) \\ \text{Posterior: } \beta|\mathbf{X}, \mathbf{y} &\sim \mathcal{N}(\mu, \Sigma) \\ \cdot \Sigma &= (\sigma_n^{-2} \mathbf{X}^T \mathbf{X} + \Lambda)^{-1} \\ \cdot \mu &= \Sigma(\Lambda \mu_0 + \sigma_n^{-2} \mathbf{X}^T \mathbf{y})\end{aligned}$$

Nonlinear Regression

$$\begin{aligned}\text{Idea: Add feature space transformation,} &\text{ kernel to compute inner product. Suppose:} \\ \beta &\sim \mathcal{N}(\mathbf{0}, \Lambda^{-1}) \quad \varepsilon \sim \mathcal{N}(\mathbf{0}, \sigma_n^2 \mathbb{I}_d) \\ \mathbf{Y} = \mathbf{X}\beta + \varepsilon &\sim \mathcal{N}(\mathbf{0}, \mathbf{X}\Lambda^{-1} \mathbf{X}^T + \sigma_n^2 \mathbb{I}_d)\end{aligned}$$

Kernels

$$\begin{aligned}\text{Kernel: } k(x_i, x_j) &= \phi(x_i) \Lambda^{-1} \phi(x_j)^T \\ \text{Similarity based reasoning.} \\ \text{Gram Matrix: } K &= k(\mathbf{x}_i, \mathbf{x}_j), \quad 1 \leq i, j \leq n \\ \cdot k(\mathbf{x}, \mathbf{x}') &= k(\mathbf{x}', \mathbf{x}) \cdot k(\mathbf{x}, \mathbf{x}') \text{ pos.semi-def.} \\ \text{If } k_1, k_2 \text{ kernels, } c \in \mathbb{R}_{>0}, \mathbf{A}^{psd}, P_{\text{pos-coeff}}: & \\ k(\mathbf{x}, \mathbf{x}') &= k_1(\mathbf{x}, \mathbf{x}') + k_2(\mathbf{x}, \mathbf{x}') = \mathbf{x}^T \mathbf{A} \mathbf{x}' \\ &= k_1(\mathbf{x}, \mathbf{x}') \cdot k_2(\mathbf{x}, \mathbf{x}') = c \cdot k_1(\mathbf{x}, \mathbf{x}') \\ &= p(k_1(\mathbf{x}, \mathbf{x}')) = f(\mathbf{x}) k_1(\mathbf{x}, \mathbf{x}') f(\mathbf{x}')\end{aligned}$$

$$\begin{aligned}k(\mathbf{x}, \mathbf{x}') &= \phi(x)^T \phi(x') = (1 + \mathbf{x}^T \mathbf{x}')^m \\ &= \tanh(\alpha \mathbf{x}^T \mathbf{x}' + c) \\ &= \sigma^2 \exp\left(-\frac{2 \sin(p^{-1} \pi \|\mathbf{x} - \mathbf{x}'\|_1^2)}{l^2}\right) \\ &= \exp(-\|\mathbf{x} - \mathbf{x}'\|_1 l^{-1}) \\ &= \exp(-\|\mathbf{x} - \mathbf{x}'\|_2^2 (2l^2)^{-1})\end{aligned}$$

$$\begin{aligned}\text{RBF: } \phi_j(x) &= \exp\left(-\frac{\|x\|_2^2}{2}\right) \prod_{i=0}^d x^{j_i} (j_i!)^{-\frac{1}{2}} \\ \uparrow \text{Lengthscale, smoother fcts.}\end{aligned}$$

Gaussian Process Regression

$$\begin{aligned}\text{Applying a kernel, we get:} \\ \mathbf{Y} = \Phi \beta + \varepsilon \sim \mathcal{N}(\mathbf{0}, \Phi \Lambda^{-1} \Phi^T + \sigma_n^2 \mathbb{I}_d) &= \\ \mathcal{N}\left(\begin{bmatrix} \mathbf{y} \\ \mathbf{y}_* \end{bmatrix} \middle| \mathbf{0}, \begin{bmatrix} \mathbf{K} + \sigma^2 \mathbb{I} & \mathbf{k} \\ \mathbf{k}^T & k(x_*, x_*) + \sigma^2 \end{bmatrix}\right)\end{aligned}$$

Gaussian Process Prediction

$$\begin{aligned}\text{Given } \mathcal{GP}(\mu, K), \\ p(y_*|x_*, \mathbf{X}, \mathbf{y}) &= \mathcal{N}(\tilde{\mu}, \tilde{\sigma}^2), \\ \cdot \tilde{\mu} &= \mu(x_*) + \mathbf{k}^T (\mathbf{K} + \sigma_n^2 \mathbb{I})^{-1} (\mathbf{y} - \mu(\mathbf{X})), \\ \cdot \tilde{\sigma}^2 &= k(x_*, x_*) - \mathbf{k}^T (\mathbf{K} + \sigma^2 \mathbb{I})^{-1} \mathbf{k} \\ \cdot \mathbf{k} &= k(x_*, \mathbf{X}) \quad \mathbf{K}_{ij} = k(x_i, x_j) \\ \cdot \tilde{\sigma}_{ij}^2 &= k(x_i, x_j) - \mathbf{k}_i^T (\mathbf{K} + \sigma^2 \mathbb{I})^{-1} \mathbf{k}_j\end{aligned}$$

Suability

Counterfactual Invariance: A function f is invariant if $f(X(w)) = f(X(w')) \forall w, w'$,
 \downarrow bias from spurious correlations.
Confounding: A hidden variable influences W and X , \Rightarrow spurious correlation with Y .
Selection Bias: A hidden variable S filters the training data based on W and X , inducing non-causal associations.
If f is counterf. invar.:
anti-causal scenario: $f(X) \perp W | Y$.
causal scenario (no selection): $f(X) \perp W$.
causal scenario (no confounding): $Y \perp X | W, X_{\perp W}$ and $f(X) \perp W | Y$.

A set of variables Z **d-separates** X and Y in a DAG \mathcal{G} if all paths between X and Y are blocked by Z : $X \perp Y | Z$. A path is blocked if:
Collider: $A \rightarrow B \leftarrow C$ and neither B nor its descendants are in Z .
Chain: $A \rightarrow B \rightarrow C$.
Fork: $A \leftarrow B \rightarrow C$ where $B \in Z$.
Algos

$$\begin{aligned}\text{K-Means } J &= \sum_{x \in \mathcal{X}} \|x - \mu_{c(x)}\|^2 \\ \text{PCA proj. maximum variance subspace.} & \\ \text{top } d \text{ eigenv. of } S &= \frac{1}{n} \sum_{i=1}^n (x_i - \bar{X})(x_i - \bar{X})^T \\ \text{EM fit GMMs } (\sum_{k=1}^K \pi_k \mathcal{N}(x|\mu_k, \Sigma_k)) &\text{ by max. likelihood. Reaches local optimum.} \\ \text{Latent variable: } M_{Xc} &= 1\{c \text{ generated } x\} \\ P(\mathcal{X}, M|\theta) &= \prod_x \prod_{c=1}^K (\pi_c P(x|\theta_c))^{M_{xc}} \\ \gamma_{xc} &= \mathbb{E}[M_{xc}|\mathcal{X}, \theta^{(j)}] = \frac{\pi_c \mathcal{N}(x; \mu_c, \Sigma_c)}{\sum_{j=1}^K \pi_j \mathcal{N}(x; \mu_j, \Sigma_j)} \\ \mu_c^{(j+1)} &= \frac{\sum_{c \in \mathcal{X}} \gamma_{xc} x}{\sum_{c \in \mathcal{X}} \gamma_{xc}} \quad \pi_c^{(j+1)} = \frac{1}{|\mathcal{X}|} \sum_{c \in \mathcal{X}} \gamma_{xc} \\ (\sigma_c^2)^{(j+1)} &= \frac{\sum_{c \in \mathcal{X}} \gamma_{xc} (x - \mu_c)^2}{\sum_{c \in \mathcal{X}} \gamma_{xc}}\end{aligned}$$

$$\text{Perceptron Bound: } \frac{\max_{i \in \hat{\mathcal{X}}^{mc}} \|\tilde{x}_i\|^2 \|\hat{d}\|}{(\min_{i \in \hat{\mathcal{X}}^{mc}} (\hat{a}^T \tilde{x}_i))^2}$$

Bias-Variance tradeoff

$$\begin{aligned}\text{Bias}(\hat{f}) &= \mathbb{E}[\hat{f}] - f \\ \text{Var}(\hat{f}) &= \mathbb{E}[(\hat{f} - \mathbb{E}[\hat{f}])^2]\end{aligned}$$

Squared Error Decomposition

$$\begin{aligned}\mathbb{E}_D \mathbb{E}_{X,Y}[(\hat{f}(X) - Y)^2] &= \\ \mathbb{E}_{X,Y}[(\mathbb{E}_{Y|X}[Y] - Y)^2] &\text{ (noise var)} \\ + \mathbb{E}_X \mathbb{E}_D[(\hat{f}_D(X) - \mathbb{E}_D[\hat{f}(X)])^2] &\text{ (var.)} \\ + \mathbb{E}_X[(\mathbb{E}_D[\hat{f}_D(X)] - \mathbb{E}_{Y|X}[Y])^2] &\text{ (bias}^2\text{)} \\ \text{With } \mathbb{E}_{Y|X}[Y] &\text{ the expected label and } \\ \mathbb{E}_D[\hat{f}(X)] &\text{ the expected classifier.}\end{aligned}$$

p-value

p-value = $\inf\{\alpha : T(X^n) \in \{x|T(x) \geq c\}\}$
likelihood to accept H_0 . it is the least probable threshold for rejecting the H_0 .

Statistical Learning and Validation

Find $f : X \rightarrow Y$ to minimize expected risk by approximation with empirical risk.

Model Cross Validation

Partition data Z into K equal subsets:

$$Z = Z_1 \cup Z_2 \cup \dots \cup Z_K, Z_\mu \cap Z_\nu = \emptyset$$

$|Z_k| \approx n \frac{K-1}{K}$ # of training samples. Learn:

$$\hat{f}^{-\nu}(x) = \arg \min_{f \in \mathcal{F}} \frac{\sum_{i \in Z_\nu} L(y_i, f(x_i))}{|Z - Z_\nu|}$$

$$\hat{R}^{CV}(\mathcal{A}) = \frac{1}{n} \sum_{i \leq n} L(y_i, \hat{f}^{-\kappa(i)}(x_i))$$

Underfits because smaller dataset.

Leave-one-out: $K = n$ (unbiased but var can be large from correlated datasets)

Bootstrapping $Z^* = \{Z_1^*, \dots, Z_B^*\}$,

of same size as original, drawn with replacement. a sample to have appears in bootstrap with prob: $1 - (1 - n^{-1}) \approx 0.632$.

So if we compute the ERM on Z we could get 63% accuracy by memorization. Overconfident (shows too small bias)!

Leave-one-out/out of bucket error: compensates by computing the ERM where no memorization was for specific sample. E.g., for classification, like cross-validation:

$$\hat{R}(\mathcal{A}) = \frac{1}{B} \sum_{b=1}^B \sum_{z_i \notin Z^{*b}} \frac{\mathbb{I}_{c(z_i) \neq y_i}}{|Z - Z^{*b}|} \hat{R}_0.632 = 0.368 \hat{R}(\mathcal{A}(Z)) + 0.632 \hat{R}_{bs}$$

Wald Test: $W = \frac{\hat{\theta} - \theta_0}{\text{s.e.}(\hat{\theta})}$

Bayesian Neural Networks (BNN)

NN: no uncertainty quantification, overconfident, adversarial examples, poor generalization for domain shifts.

BNN: Using $p(w)$ and $p(D|w)$, approx. poster. by variational infer. (min over KL).

$$\sigma \leftarrow \sigma - \alpha \left(\varepsilon^\top \frac{\partial}{\partial w} F(w, \theta) + \frac{\partial}{\partial \sigma} F(w, \theta) \right)$$

Information-based Transductive Lear.

ITL selects x_n that maximizes mutual information of $y_x = f_x + \varepsilon_x$ about f :

$$x_n = \arg \max_{x \in S} I(f_A; y_x | D_{n-1})$$

If $f \sim \text{GP}(\mu, k)$, then:

$$I(f_A; y_x | D_{n-1}) = \frac{1}{2} \log \left(\frac{\text{Var}[y_x | D_{n-1}]}{\text{Var}[y_x | f_A, D_{n-1}]} \right)$$

Safe Bayesian Optimization

$$x_n = \arg \max_{x \in \hat{S}_n = \{x | u_n^g(x) \geq 0\}} u_n^f(x)$$

Batch Active Learning | ProbCover

$$G = (X, E), \quad E = \{(x, x') \mid \|x - x'\| \leq \delta\}$$

$$L \leftarrow \emptyset \quad \forall i = 1, 2, \dots, b \quad \hat{x} \leftarrow \arg \max_{x \in X} |\{x' \mid (x, x') \in E, x' \in X\}|$$

$$L \leftarrow L \cup \{\hat{x}\} \mid E \leftarrow E \setminus (\{\hat{x}\} \times (B_\delta(\hat{x}) \cap X))\}$$

Max Mean Discrep. $MMD^2(\mathcal{F}, X, Y) =$

$$\sup_{\|f\|_{\mathcal{H}} \leq 1} [(\mathbb{E}_P[f(x)] - \mathbb{E}_Q[f(y)])^2 =$$

$$(\mathbb{E}_P(\phi(x), f)_{\mathcal{H}} - \mathbb{E}_Q(\phi(y), f)_{\mathcal{H}})^2 =$$

$$\langle \mu_x - \mu_y, f \rangle_{\mathcal{H}}^2 = \|\mu_x - \mu_y\|_{\mathcal{H}}^2 = \mathbb{E}[k(x, x')] + \mathbb{E}[k(y, y')] - 2\mathbb{E}[k(x, y)]$$

Convex Optimization

Given constrained optimization problem:

$$\min_{w \in \mathbb{R}^d} f(w) : g_{1:n}(w) = 0, h_{1:n}(w) \leq 0$$

it is convex if $f, g_{1:n}, h_{1:n}$ are convex and the feasible region is convex.

The Lagrangian with Lagrange multipliers $\eta = (\lambda, \alpha)$: $L(\eta, w) = f(w) + \sum_{i \leq m} \lambda_i g_i(w) + \sum_{j \leq n} \alpha_j h_j(w)$

Any **optimal solution** W satisfies:

$$\nabla_w L(\eta, W) = 0, g_i(W) = 0, h_j(W) \leq 0, \alpha_j \geq 0$$

the **Dual Problem** is and satisfies $\forall w$:

$$\max_{\alpha \geq 0, \lambda} (\theta(\eta) := \inf_w L(\eta, w)) \leq f(w^*)$$

strong duality if $\theta(\eta^*) = f(w^*)$

Slater's cond. if $\exists w_0$ feasible: $h_{1:n}(w_0) < 0$

strong duality $\rightarrow w^*$: $f(w^*) = L(\eta^*, w^*)$

and $\alpha_j h_j(w^*) = 0, \quad \forall j \leq n$.

Support Vector Machine (SVM)

Convex constrained optimization problem with strong duality (if linearly separable).

x_i support vectors, $y_i \in \{-1, +1\}$.

$$\min_{w, w_0} |\forall i \leq n: y_i(w^\top x_i + w_0) \geq 1| \quad \frac{1}{2} \|w\|^2$$

Lagrangian: $\mathcal{L}(w, w_0, \alpha) = \frac{1}{2} \|w\|^2 +$

$$\sum_{i=1}^n \alpha_i (1 - y_i(w^\top x_i + w_0)) \quad \alpha_i \geq 0.$$

$$\text{KKT: } w^* = \sum_{i=1}^n \alpha_i y_i x_i \quad \sum_{i=1}^n \alpha_i y_i = 0$$

$$\text{Dual: } \max_{\alpha \geq 0: \sum_{i=1}^n \alpha_i y_i = 0} L(\alpha)$$

$$L(\alpha) = \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j x_i^\top x_j$$

The optimal hyperplane is given by

$$w^* = \sum_{i=1}^n \alpha_i^* y_i x_i$$

$$w_0^* = -\frac{1}{2} (\min_{y_i=1} w^{*T} x_i + \max_{y_i=-1} w^{*T} x_i)$$

Only Support Vectors ($\alpha_i^* \neq 0$) contribute.

Optimal Margin: $w^T w = \sum_{i \in SV} \alpha_i^*$

Discrim.: $g^*(x) = \sum_{i \in SV} y_i \alpha_i^* x_i^T x_i + w_0^*$

class = $\text{sign}(x^T w^* + w_0^*)$

Soft Margin SVM

Introduce slack to relax constraints.

C controls margin maximization vs. constraint violation.

$$\min_{\xi_i \geq 0, w, w_0} |\forall i \leq n: y_i(w^\top x_i + w_0) \geq 1 - \xi_i|$$

$$\frac{1}{2} \|w\|^2 + C \sum_{i=1}^n \xi_i$$

Lagrangian: $L(w, w_0, \xi, \alpha, \beta) = \frac{1}{2} w^T w +$

$$C \sum_{i=1}^n \xi_i - \sum_{i=1}^n \alpha_i [z_i(w^T y_i + w_0) - 1 + \xi_i]$$

$$- \sum_{i=1}^n \beta_i \xi_i$$

Dual Problem same as usual SVM but with supplementary constraint: $C \geq \alpha_i \geq 0$

KKT Conditions: $\alpha_i^*(z_i(w^{*T} y_i + w_0) - 1 + \xi_i) = 0, \xi_i(\alpha_i - C) = 0$

You should solve α via quadratic optimisation. Optimal hyperplane and classification as normal SVM. Optimal slack: $\xi_i^* = \max(0, 1 - y_i(w^{*T} x_i + w_0^*))$

$$\xi_i^* = \mathcal{L}^{\text{hinge}}(y_i, w^{*T} x_i + w_0^*)$$

Non-Linear SVM

Use kernel in discriminant function:

$$g(x) = \sum_{i,j=1}^n \alpha_{ij} z_{ij} K(x_i, x_j)$$

E.g solve the XOR Problem with:

$$K(x, y) = (1 + x_1 y_1 + x_2 y_2)^2$$

Multiclass SVM

$\forall \text{class } y \in \{1, 2, \dots, M\}$ we introduce w_y

and define our problem: (w is v-stacked)

$$\min_w \frac{1}{2} w^T w = \min_{\{w_y\}_{y=1}^M} \sum_{y=1}^M w_y^T w_y$$

s.t. $(w_{y_i}^T x_i + w_{y,0}) -$

$$\max_{y \neq y_i} (w_y^T x_i + w_{y,0}) \geq 1, \forall x_i \in \mathcal{X}$$

classification: $\hat{y} = \arg \max_y (w_y^T x + w_{y,0})$

Ensemble Methods

Combining Regressors

Set of estimators: $\hat{f}_1(x), \dots, \hat{f}_B(x)$

simple average: $\hat{f}(x) = \frac{1}{B} \sum_{i=1}^B \hat{f}_i(x)$

$$\text{Bias}[\hat{f}(x)] = \frac{1}{B} \sum_{i=1}^B \text{Bias}[f_i(x)]$$

$$\mathbb{V}[\hat{f}(x)] \approx \frac{\sigma^2}{B} \quad \text{if the estimators are uncorrelated.}$$

Combining Classifiers

Input: classifiers $c_1(x), \dots, c_B(x)$

$$\text{Infer } \hat{c}_B(x) = \text{sgn}(\sum_{b=1}^B \alpha_b c_b(x))$$

with weights $\{\alpha_b\}_{b=1}^B$

Requires diversity of the classifiers.

Bagging

Train on bootstrapped subsets. Covariance small, variance similar, bias weakly affected.

Random Forest Collection of uncorr. decision trees. Partition data space recursively. Grow the tree sufficiently deep to reduce bias. (random sample cuts to reduce bias). Prediction with voting.

Boosting (Weak to avoid overfitting)

Combine uncorr. weak learners in sequence.

Coeff. of \hat{c}_{b+1} depend on \hat{c}_b 's results

AdaBoost (minimizes exp. loss)

Init: $\mathcal{X} = \{(x_1, y_1), \dots, (x_n, y_n)\}, w_i^{(1)} = \frac{1}{n}$

Fit $\hat{c}_b(x)$ to \mathcal{X} weighted by $w^{(b)}$

$$\varepsilon_b = \sum_{i=1}^n w_i^{(b)} \mathbb{I}_{\{\hat{c}_b(x_i) \neq y_i\}} / \sum_{i=1}^n w_i^{(b)}$$

$$\alpha_b = \log \frac{1 - \varepsilon_b}{\varepsilon_b} > 0$$

$$w_i^{(b+1)} = w_i^{(b)} \exp(\alpha_b \mathbb{I}_{\{\hat{c}_b(x_i) \neq y_i\}})$$

return $\hat{c}_B(x) = \text{sgn}(\sum_{b=1}^B \alpha_b \hat{c}_b(x))$

Best approx. at log-odds ratio.

Like stagewise-additive modeling.

Difference Boosting: identical $\mathcal{D}, \forall c(x)$

prediction weighted on accuracy, Bagging: varies \mathcal{D} , gives same importance. **Notes**

AdaBoost gives high weight to hard-to-classify samples (maybe outliers). Bagging, if imbalanced dataset maybe \mathcal{Z} missing a class. then, make the bootstrap size large enough s.t. at least one point is included.

Logistic Regression

$$\log \frac{P(y=1|x)}{P(y=-1|x)} = \sum_{b=1}^B c_b(x) =: F(x)$$

$$P(y = 1|x) = \frac{\exp(F(x))}{1 + \exp(F(x))}$$

PAC learning

Exp./Gen. err: $\mathcal{R}(\hat{c}_n) = \mathbb{P}_{X,Y}(\hat{c}_n(x) \neq c(x))$

$$\text{Emp. err.}: \hat{\mathcal{R}}_n(\hat{c}_n) = \frac{1}{n} \sum_{i=1}^n 1\{\hat{c}_n(x_i) \neq y_i\}$$

Eff. PAC learnable: \mathcal{A} can learn a concept class \mathcal{C} from \mathcal{H} if, given a sufficiently large sample, it outputs a hypothesis that generalizes well with high probability.

$$0 < \varepsilon < \frac{1}{2}, 0 < \delta < \frac{1}{2}, (X, Y) \in \mathcal{X} \times \{0, 1\} :$$

$$\text{If } n \geq \text{poly}(\frac{1}{\varepsilon}, \frac{1}{\delta}, \text{dim}(\mathcal{X})), \text{ then}$$

$$\mathbb{P}_{X,Y}(\mathcal{R}(\hat{c}_n) - \inf_{c \in \mathcal{C}} \mathcal{R}(c) \leq \varepsilon) \geq 1 - \delta.$$

VC Inequality

Select ERM. Under uniform convergence:

$$\mathbb{P}(\mathcal{R}(\hat{c}_m^*) - \inf_{c \in \mathcal{C}} \mathcal{R}(c) > \varepsilon) \leq$$

$$\mathbb{P}(\sup_{c \in \mathcal{C}} |\hat{\mathcal{R}}_n(c) - \mathcal{R}(c)| > \frac{\varepsilon}{2}) :$$

$$P(\sup |\dots| > \varepsilon) \leq 2|\mathcal{C}| \exp(-2n\varepsilon^2)$$

$$P(\sup |\dots| > \varepsilon) \leq 9n^{Vc} \exp\left(-\frac{n\varepsilon^2}{32}\right)$$

$$\mathbb{P}[\mathcal{R}(\hat{c}) - \inf_{c \in \mathcal{C}} \mathcal{R}(c) > \varepsilon] < 1 - \delta.$$

$$\text{Def R.H.S.} \leq \delta: \varepsilon = \sqrt{\frac{\log N - \log(\delta/2)}{2n}}.$$

Consider $\mathcal{H}_\varepsilon = \{h \in \mathcal{H} : R(h) > \varepsilon\}$. We bound the probability of bad learning for consistent learn.: $P(\exists h \in \mathcal{H}_\varepsilon :$

$$\hat{R}(h) = 0) \leq \sum_{h \in \mathcal{H}_\varepsilon} P(\hat{R}(h) = 0)$$

$$\leq |\mathcal{H}_\varepsilon| (1 - \varepsilon)^m \leq |\mathcal{H}| \exp(-m\varepsilon) \leq \delta$$

$$\Rightarrow m \geq \frac{1}{\varepsilon} (\log(|\mathcal{H}|) + \log(\frac{1}{\delta}))$$

VC dimension

classifier can shatter any n but no some $n+1$ points. **Examples:** $(-\infty, a] = 1$ all intervals in \mathbb{R} : $V_C = 2$ For k intervals, $2k$ half planes in \mathbb{R}^2 : 3 for unit circles 3 convex polygons in \mathbb{R}^2 : ∞ convex polygons in \mathbb{R}^2 with at most k vertices: $2k + 1$

Nonparametric Bayesian methods

$$\text{Beta}(x|a, b) = B(a, b)^{-1} x^{a-1} (1-x)^{b-1} :$$

prob. of Bernoulli proc. after observing $a-1$ success and $b-1$ failures. Multivariate case: Dirichlet distr. that will give multivar. probs, *based on finite counts*! But we don't know exactly which multivar. distribution works. With more data, we update the Dirichlet distribution. Is a conjugate prior.

Stick-breaking Dirichl. proc.

Repeatedly draw from $\text{Beta}(x|1, \alpha)$ with fixed α , but from reducing stick:

$$\rho_k = \beta_k (1 - \sum_{i=1}^{k-1} \rho_i). \text{ The prior:}$$

$$\mathbb{P}[z_i = k | z_{-i}, \alpha] = \begin{cases} \frac{N_{k,-i}}{\alpha + N - 1} & \text{existing } k \\ \frac{\alpha}{\alpha + N - 1} & \text{otherwise} \end{cases}$$

Final Gibbs sampler:

$$\mathbb{P}[z_i = k | z_{-i}, \alpha, \mu] =$$

$$\begin{cases} \frac{N_{k,-i}}{\alpha + N - 1} p(x_i | x_{-i,k}, \mu) & \text{existing } k \\ \frac{\alpha}{\alpha + N - 1} p(x_i, \mu) & \text{otherwise} \end{cases}$$

Gibbs sampling

Init: assign all data to a cluster, with prior

π_i , with $\sum_{k=1}^K \pi_i < 1$ (s.t. new clusters possible). E.g. with stick-breaking.

Then remove x from k and compute new θ_k , then compute Gibbs sampler prob. (CRP), and sample the new cluster assignment

$z_i \sim p(z_i | x_{-i}, \theta_k)$. If cluster is empty, remove it and decrease K .