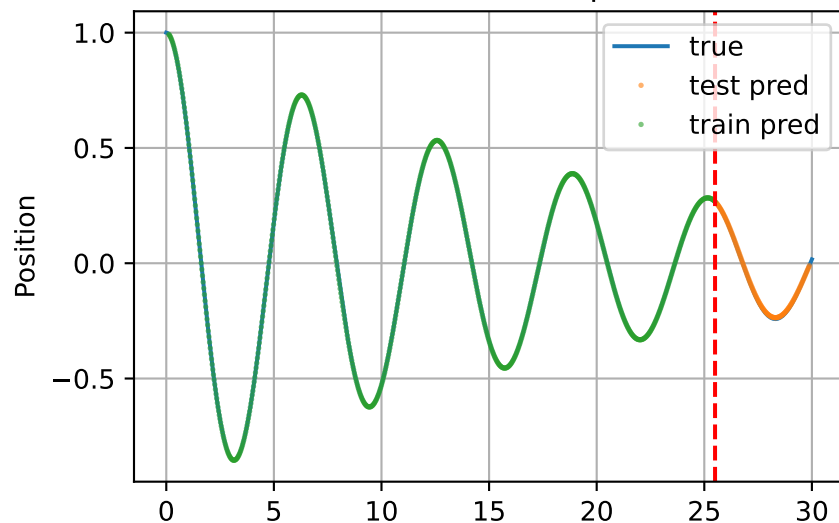


Position (true and RNN prediction)



Velocity (true and RNN prediction)

