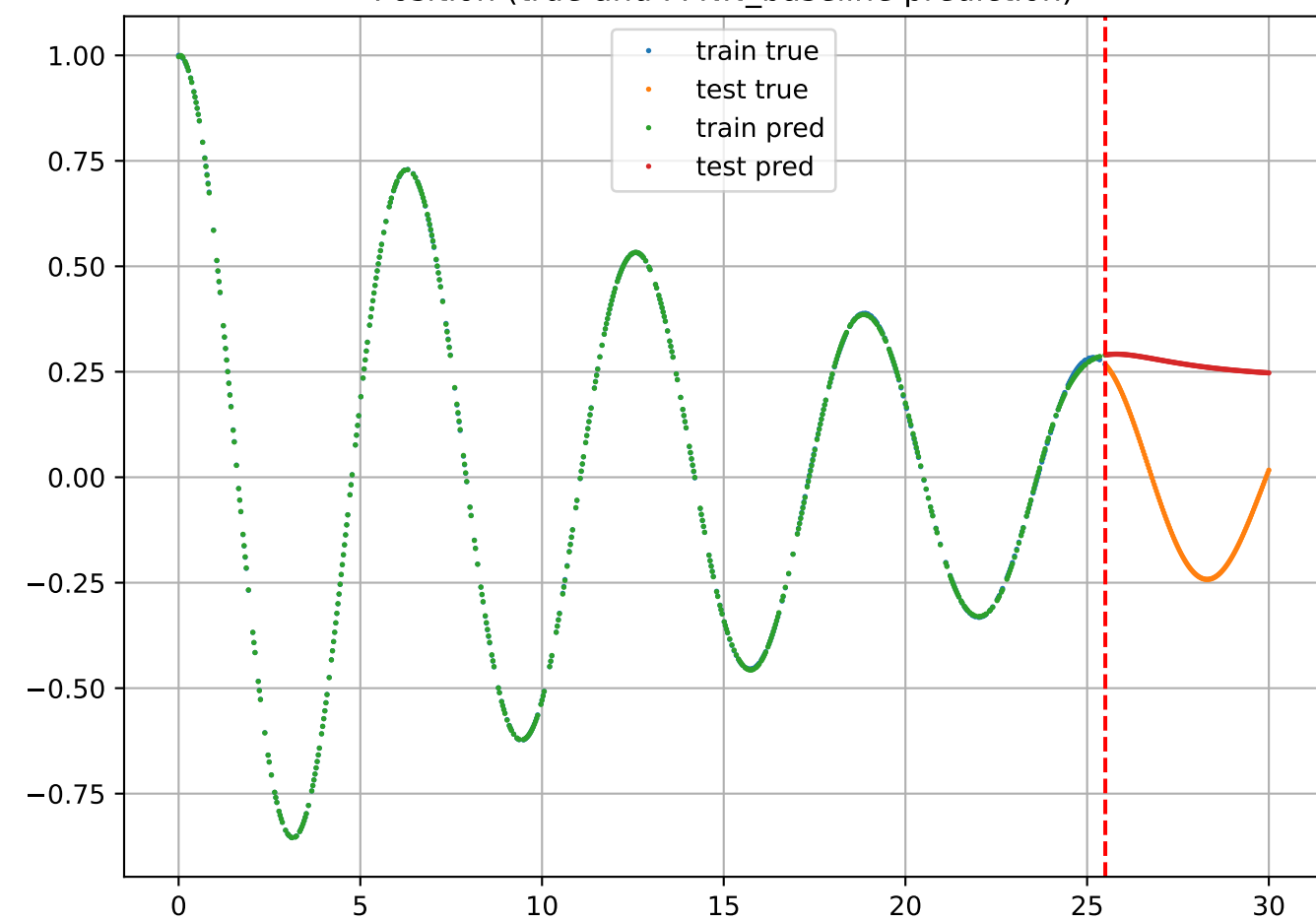


Position (true and FFNN\_baseline prediction)



Velocity (true and FFNN\_baseline prediction)

