DHOscillator_PINN_tuning

March 12, 2024

```
[1]: # import numpy, scipy, and matplotlib
     import numpy as np
     import scipy as sp
     import matplotlib.pyplot as plt
     from itables import init_notebook_mode
     init_notebook_mode(all_interactive=True)
     from sklearn.model_selection import train_test_split
     # import from scipy solve_ivp
     from scipy.integrate import solve_ivp
     import torch
     %matplotlib widget
     from ray import train, tune
     from ray.train import Checkpoint, session, report
     from ray.tune.schedulers import ASHAScheduler
     import os
     import tempfile
```

<IPython.core.display.HTML object>

```
[2]: path = os.getcwd()
  results_dir = os.path.join(path, "../tune")
  os.makedirs(results_dir, exist_ok=True)
```

1 Tuning of the PINN for the Damped Harmonic Oscillator ODE

In this notebook we tune the hyperparameters of the PINN.

1.1 Load data

```
[3]: # import data
     # data are generated by "src/DHOscillator_data_gen.py"
     data = np.load('../data/DHOscillator_data.npy')
     data_X = data[:,0]
     data_Y = data[:,1:]
[4]: def data_loader(X, Y, batch_size, grid_num):
         11 11 11
         Function to load data and divide it in batches, specific for
         PINN with grid_num, tunable number of point where enforce the ODE
         input: X, Y, batch_size, grid_num
         output: train X batches, train Y batches, val X, val Y, test X, test Y
         # divide in train, validation and test
         train_frac = 0.7
         val_frac = 0.15
         test_frac = 0.15
         train val X = X[:int((train frac+val frac)*len(X))]
         train_val_Y = Y[:int((train_frac+val_frac)*len(X)), :]
         train_X, val_X, train_Y, val_Y = train_test_split(
             train_val_X,
             train_val_Y,
             test_size=val_frac/(train_frac+val_frac),
             random_state=42
         test_X = X[int((train_frac+val_frac)*len(X)):]
         test_Y = Y[int((train_frac+val_frac)*len(X)):, :]
         # dummy PINN dataset for train
         train_X = np.linspace(0, 30, grid_num)
         train_Y = np.zeros((grid_num, 2))
         # convert to torch tensor
         train_X = torch.tensor(train_X, dtype=torch.float32).view(-1, 1)
         train_Y = torch.tensor(train_Y, dtype=torch.float32)
         val_X = torch.tensor(val_X, dtype=torch.float32).view(-1, 1)
         val_Y = torch.tensor(val_Y, dtype=torch.float32)
         test_X = torch.tensor(test_X, dtype=torch.float32).view(-1, 1)
         test_Y = torch.tensor(test_Y, dtype=torch.float32)
         # divide in batches train
         train_X_batches = torch.split(train_X, batch_size)
```

```
train_Y_batches = torch.split(train_Y, batch_size)

return train_X_batches, train_Y_batches, val_X, val_Y, test_X, test_Y
```

1.2 Define hyper model

```
[5]: # define the model
    class FFNN(torch.nn.Module):
        def __init__(self, n_layers, n_neurons):
            super(FFNN, self).__init__()
        layers = []
        for i in range(n_layers):
            if i == 0:
                layers.append(torch.nn.Linear(1, n_neurons))
        else:
            layers.append(torch.nn.Linear(n_neurons, n_neurons))
        layers.append(torch.nn.Tanh())
        layers.append(torch.nn.Linear(n_neurons, 2))
        self.model = torch.nn.Sequential(*layers)
        def forward(self, x):
        return self.model(x)
```

1.3 Define the Objective

```
[6]: def objective(config):
         net = FFNN(config["n_layers"], config["n_neurons"])
         device = "cpu"
         criterion = torch.nn.MSELoss()
         optimizer = torch.optim.Adam(net.parameters(), lr=config["lr"])
         scheduler = torch.optim.lr_scheduler.ReduceLROnPlateau(
             optimizer,
             'min',
             factor=config["factor"],
             patience=config["patience"]
         )
         train_X_batches, train_Y_batches, val_X, val_Y, test_X, test_Y =
      -data_loader(data_X, data_Y, config["batch_size"], config["grid_num"])
         for epoch in range(50000):
             for i, (X, Y) in enumerate(zip(train_X_batches, train_Y_batches)):
                 optimizer.zero_grad()
                 X.requires_grad = True
```

```
Y_pred = net(X)
           # get the derivatives
          dx_dt = torch.autograd.grad(Y_pred[:,0], X, grad_outputs=torch.
→ones_like(Y_pred[:,0]), create_graph=True)[0]
          dv_dt = torch.autograd.grad(Y_pred[:,1], X, grad_outputs=torch.
→ones_like(Y_pred[:,1]), create_graph=True)[0]
           # loss_ode and loss_ic
          loss_ode = torch.mean((dx_dt[:,0] - Y_pred[:,1])**2 + (dv_dt[:,0] +__
→0.1*Y_pred[:,1] + Y_pred[:,0])**2)
          loss_ic = ((Y_pred[0,0] - 1)**2 + (Y_pred[0,1] - 0)**2)
          loss = config["lambda"]*loss_ode + loss_ic
          loss.backward()
          optimizer.step()
           scheduler.step(loss)
      val_loss = criterion(net(val_X), val_Y).item()
      report(metrics={"loss": val_loss})
      if epoch % 100 == 0:
          torch.save(net.state_dict(), "./model.pth")
```

1.4 Tuning

```
[7]: # configuration space and sampling method
config = {
    "n_layers": tune.randint(2, 6),
    "n_neurons": tune.randint(20, 40),
    "lr": tune.loguniform(0.001, 0.01),
    "factor": tune.uniform(0.7, 0.99),
    "patience": tune.lograndint(100, 1000),
    "batch_size": tune.lograndint(100, 1000),
    "grid_num": tune.lograndint(100, 1000),
    "lambda": tune.loguniform(10, 100)
}

# schedueler ASHA
scheduler = ASHAScheduler(
    metric="loss",
    mode="min",
```

```
\max_{t=50000}
         grace_period=7000,
         reduction_factor=2
     tuner = tune.Tuner(
         objective,
         param_space=config,
         tune_config=tune.TuneConfig(
             num_samples=128,
             scheduler=scheduler,
         ),
         run_config=train.RunConfig(
             name="DHO_PINN_tuning",
             storage_path=results_dir
         )
[8]: results = tuner.fit()
    <IPython.core.display.HTML object>
    2024-03-12 15:56:54,209 INFO tune.py:1042 -- Total run time: 8658.72 seconds
    (8651.95 seconds for the tuning loop).
[9]: df = results.get dataframe()
     df
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```

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124	9b065_00124	2024-03-12_15-54-	-22 0	.039076 3	314.353094	5335
125	-	2024-03-12_15-52-			132.105762	5342
126	-	2024-03-12_15-55-			227.598845	5343
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2	0.005881	0.730474	887		118	
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4	0.001437	0.826627	568		407	
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123	0.002230	0.953331	969		117	
124	0.008645	0.911701	270		115	
125	0.007100	0.810383	223		299	
126	0.007937	0.951226	102		624	
127	0.001029	0.930717	567		520	
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124		998 22.106460	_			
125		587 21.774259	-			
126		787 38.707303	_			
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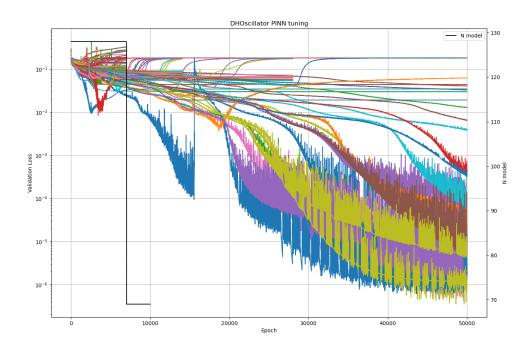
[128 rows x 23 columns]

```
[10]: def get_alive_model(df, max_epoch):
    """
    Function to get the number of alive models at each epoch
    input: df, max_epoch
    output: alive_model
    """

# get training_iteration vector
    training_iteration = df["training_iteration"]
    training_iteration = training_iteration.to_numpy()
    # alive_model = number of entries of training_iteration > epoch
    # epoch = (0, max_epoch)
    alive_model = np.zeros(max_epoch)
    for i in range(max_epoch):
        alive_model[i] = np.sum(training_iteration > i)
    return alive_model

alive_model = get_alive_model(df, 10000)
```

```
[11]: # show results
      dfs = {result.path: result.metrics_dataframe for result in results}
      # twinx plot alive_model and validation loss
      fig, ax1 = plt.subplots(figsize=(15, 10))
      # plot the validation loss
      for path, df in dfs.items():
          ax1.plot(df["training_iteration"], df["loss"], label=path)
      ax1.set_yscale("log")
      ax1.set_xlabel("Epoch")
      ax1.set_ylabel("Validation Loss")
      ax1.grid()
      # plot the alive model
      ax2 = ax1.twinx()
      ax2.plot(alive_model, label="N model", color="black")
      ax2.set ylabel("N model")
      ax2.legend()
      ax2.grid()
      plt.title("DHOscillator PINN tuning")
      plt.grid()
      # save the plot
      plt.savefig("../plot/DHOscillator_PINN_tuning.png")
```



```
best_result = results.get_best_result("loss", mode="min")
      logdir = best_result.path
      state_dict = torch.load(os.path.join(logdir, "model.pth"))
      best_model = FFNN(best_result.config["n_layers"], best_result.
       ⇔config["n_neurons"])
      best_model.load_state_dict(state_dict)
      # save best model
      torch.save(best_model, "../models/DHO_PINN_tuned.pt")
[13]: # print validation and test loss
      train_X_batches, train_Y_batches, val_X, val_Y, test_X, test_Y = data_loader(
          data_X,
          data_Y,
          best_result.config["batch_size"],
          best_result.config["grid_num"]
      val_loss = torch.nn.MSELoss()(best_model(val_X), val_Y).item()
      test_loss = torch.nn.MSELoss()(best_model(test_X), test_Y).item()
```

[12]: # get best model

```
print(f"Validation Loss: {val_loss}")
print(f"Test Loss: {test_loss}")
```

Validation Loss: 1.239517246176547e-06 Test Loss: 1.7491795460955473e-06

1.5 Restore results

```
[14]: # restore results
experiment_path = os.path.join(results_dir, "DHO_PINN_tuning")
experiment_path
```

[14]: '/home/luigi/Documents/PHYSICS/ML/Project1/src/../tune/DHO_PINN_tuning'

```
[15]: restored_tuner = tune.Tuner.restore(experiment_path, objective)
restored_results = restored_tuner.get_results()
```

```
[16]: restored_df = restored_results.get_dataframe()
restored_df
```

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[16]:	_	loss	_	checkpoint_d			raining_iteration	
	0	0.094820	1710247709		None	True	700	
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	2	0.000015	1710248027		None	True	5000	0
	3	0.178123	1710246995		None	True	700	0
	4	0.000001	1710248556		None	True	5000	0
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	123	0.175027	1710255092		None	True	700	0
	124	0.157358	1710255262		None	True	700	0
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[128 rows x 23 columns]

[]: