



## **Topic 6**

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# **Single Cycle Processor**

# Introduction

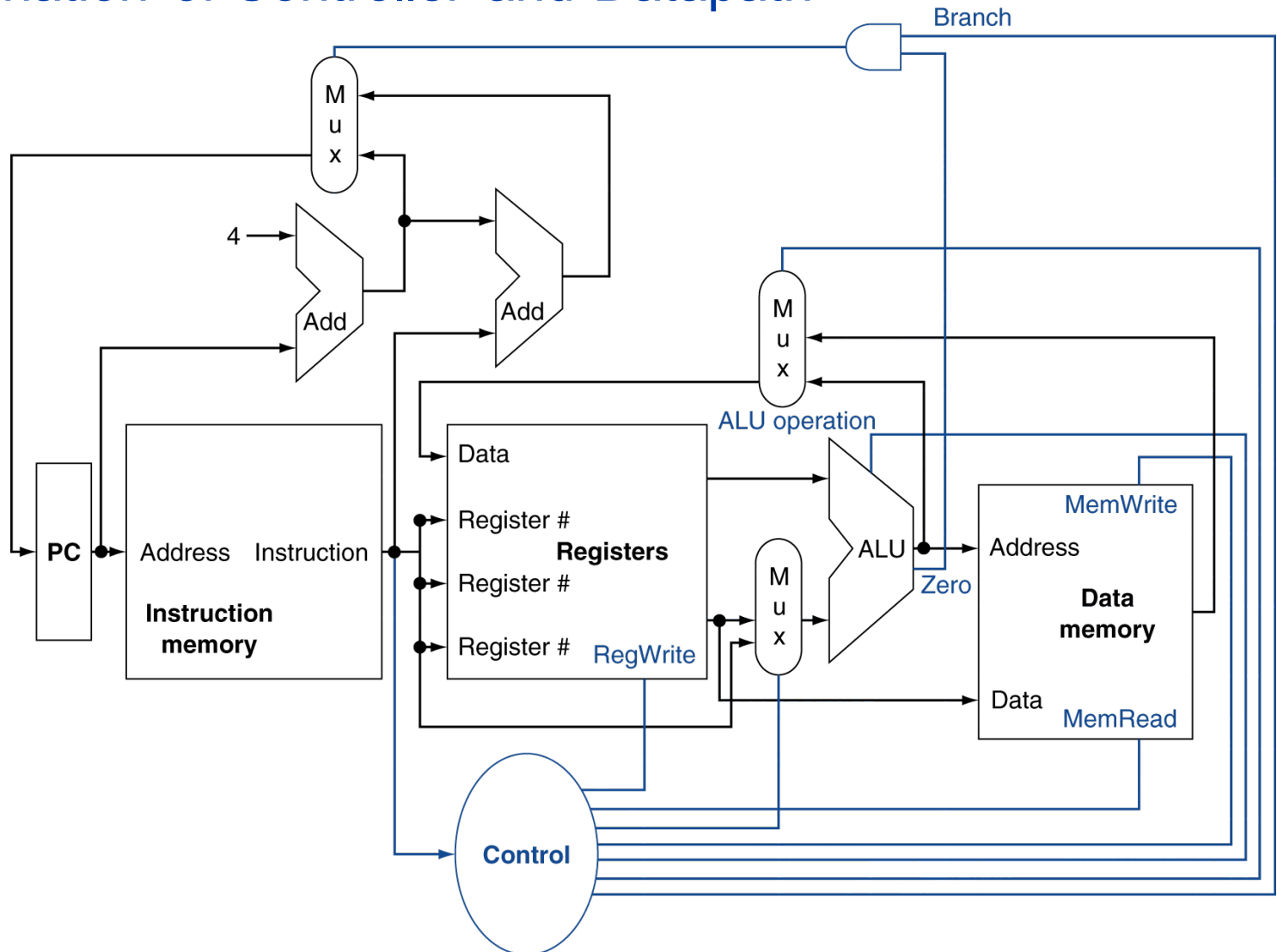
- MIPS implementations
  - A simplified single-cycle version
  - An FSM based multi-cycle version (not to be discussed)
  - A more realistic (simplified) pipelined version
- Supports simple subset, shows most aspects of MIPS architecture
  - Arithmetic/logical: add, sub, and, or, sllt
  - Memory reference: lw, sw
  - Control transfer: beq, j

# Instruction Execution

- PC  $\rightarrow$  program memory, fetch instruction
- Register addresses to access register file, read registers
- Depending on instructions
  - Use ALU/Adder to calculate
    - Arithmetic/logic result
    - Memory address for load/store
    - Branch target address
- Access register or data memory for load/store
- Update PC  $\leftarrow$  target address or PC + 4

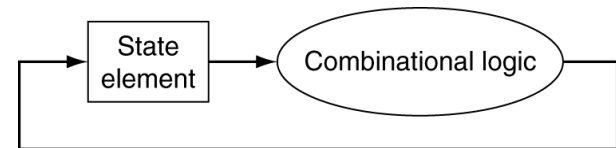
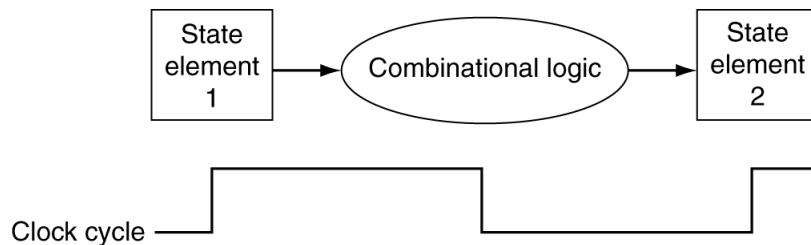
# First View of CPU

## Combination of Controller and Datapath



# Clocking Methodology

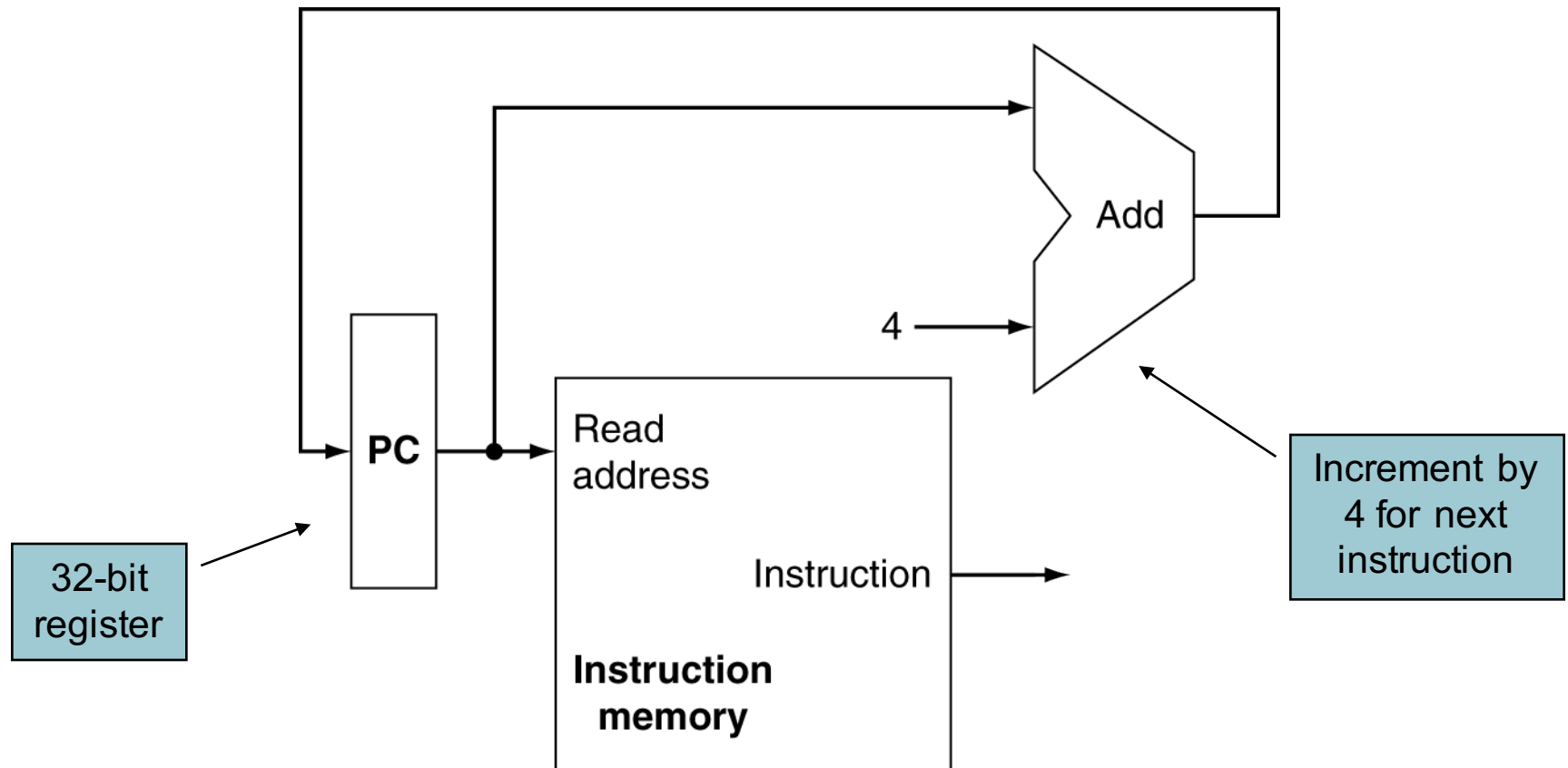
- Combinational logic does the computation during clock cycles
  - Between clock edges
  - Input (present state) from state elements, output (next state) to state element
  - Among all kinds of computations, longest delay determines clock period



# Building a Datapath

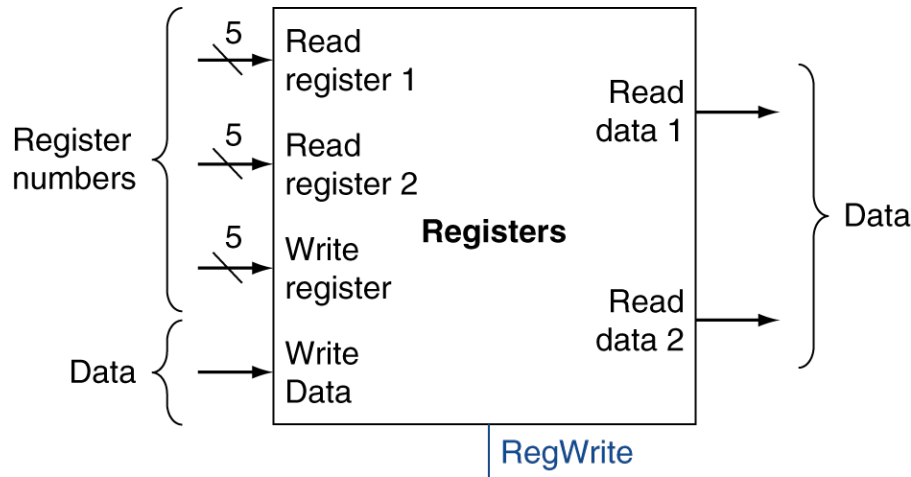
- Datapath
  - Elements that process data and addresses in the CPU
    - Registers, ALUs, mux's, memories, ...
- We will build a MIPS datapath incrementally

# Instruction Fetch

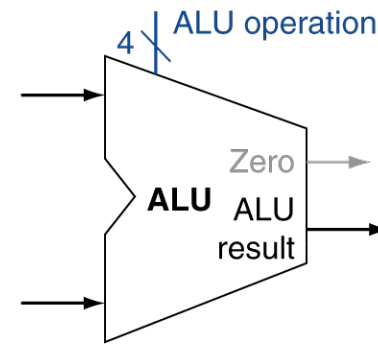


# R-Format Instructions

- Read two register operands
- Perform arithmetic/logical operation
- Write register result



a. Registers

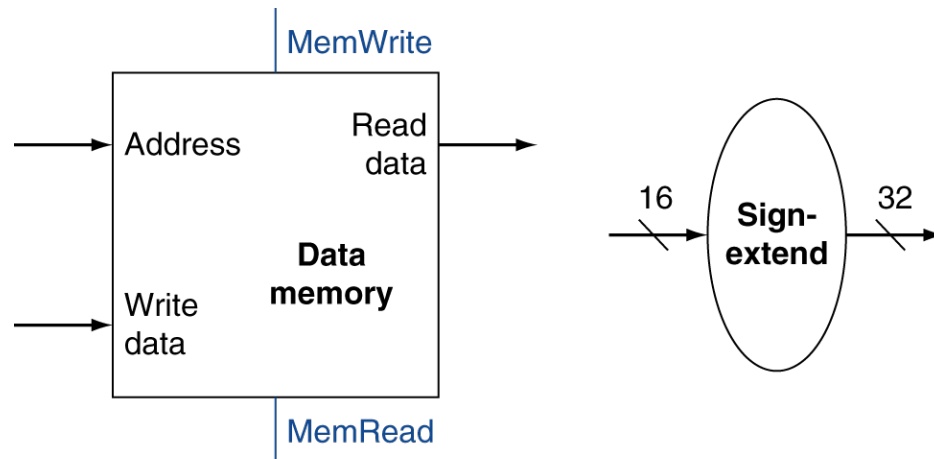


b. ALU



# Load/Store Instructions

- Read register operands
- Calculate address using 16-bit offset
  - Use ALU, but sign-extend offset
- Load: Read memory and update register
- Store: Write register value to memory



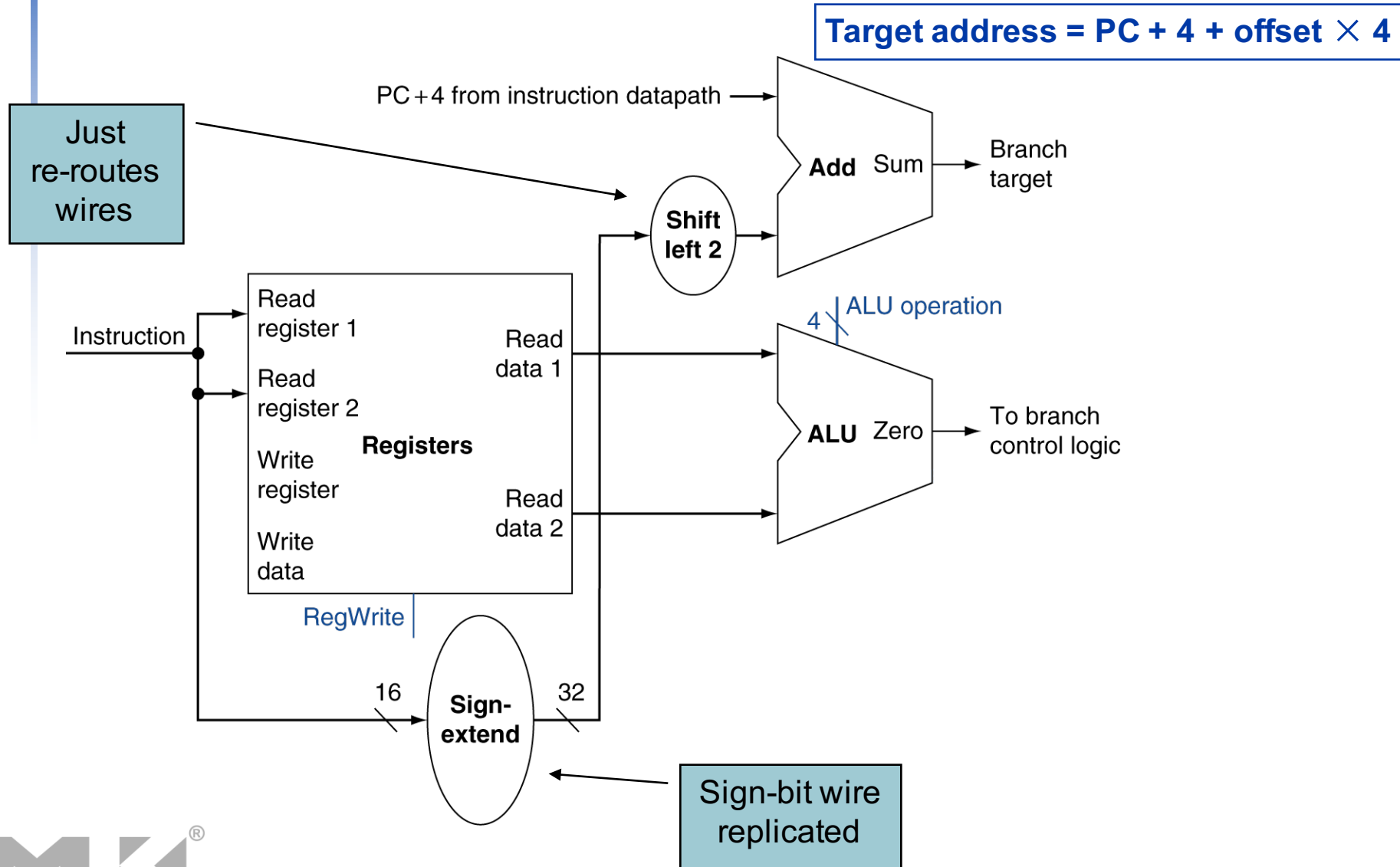
a. Data memory unit

b. Sign extension unit

# Branch Instructions

- Read register operands
- Compare operands
  - Use ALU, subtract and check Zero output
- Calculate target address
  - Sign-extend the immediate relative address
  - Shift left 2 places (word displacement)
  - Add to PC + 4
    - PC+4 already calculated by instruction fetch

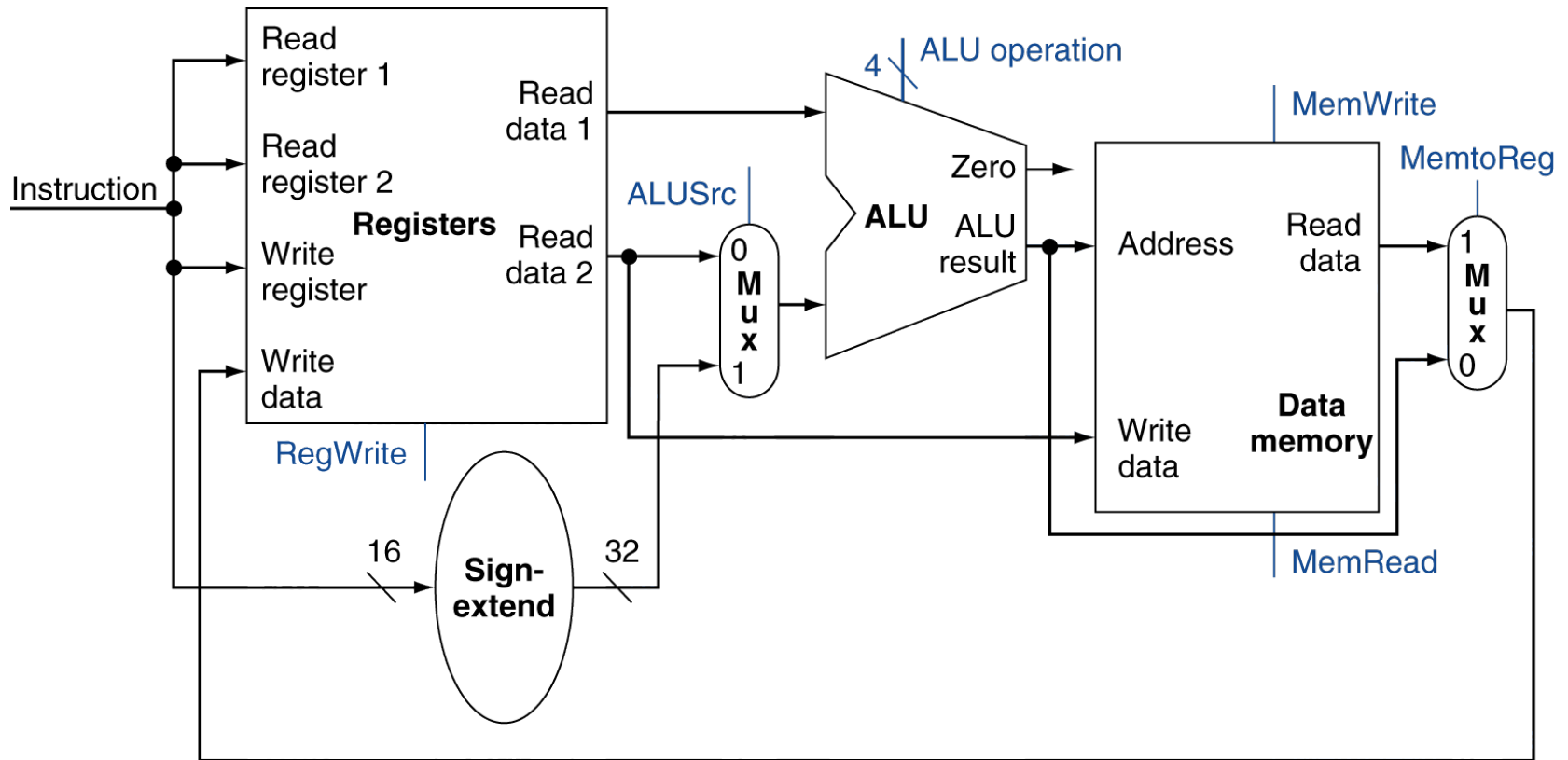
# Branch Instructions



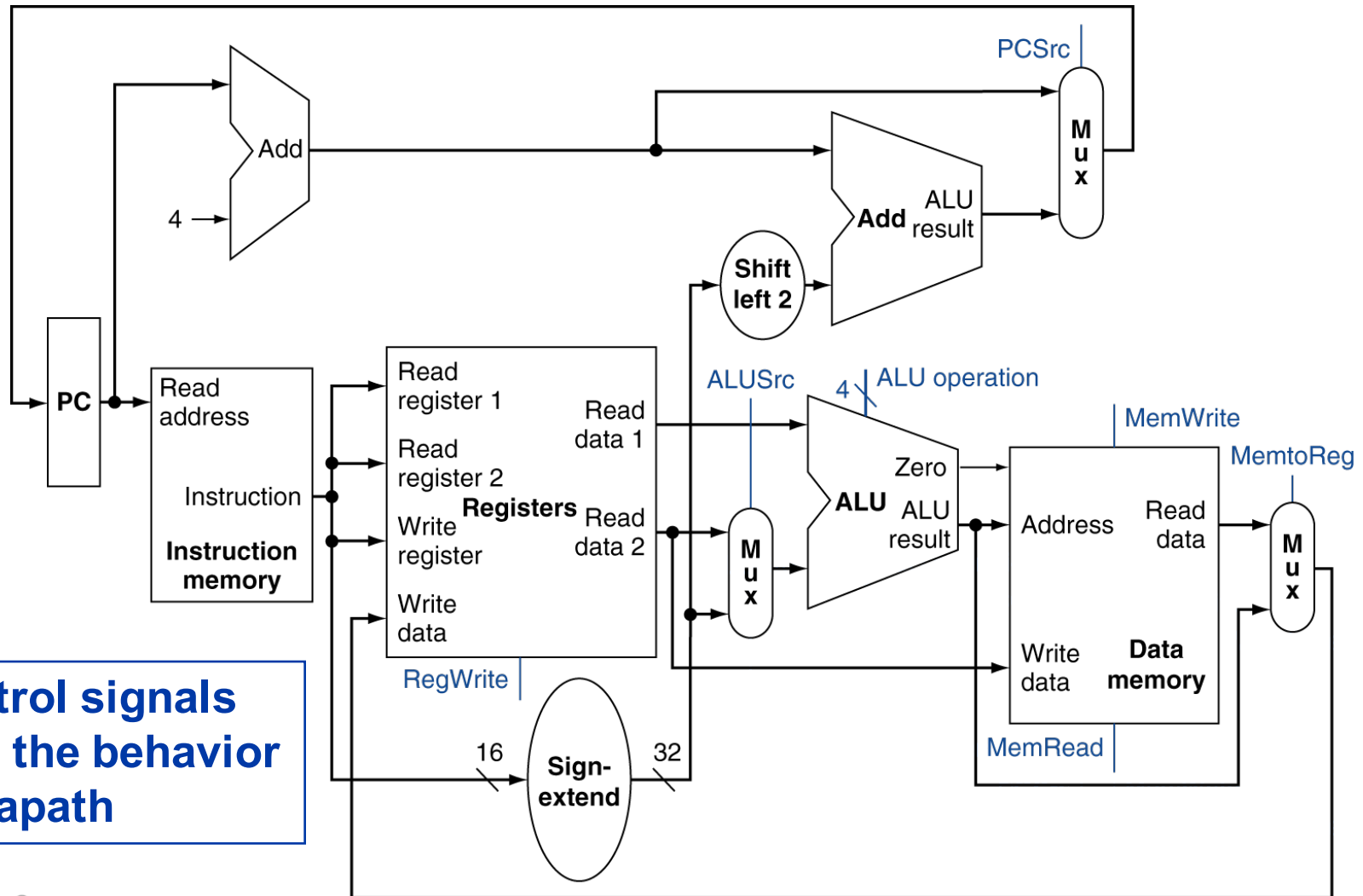
# Composing the Elements

- First version of data path does an instruction in one clock cycle
  - Each datapath element can only do one function at a time
    - Hence, we need separate instruction memory and data memory
- Use multiplexers where alternate data sources are used for different instructions

# R-Type/Load/Store Datapath

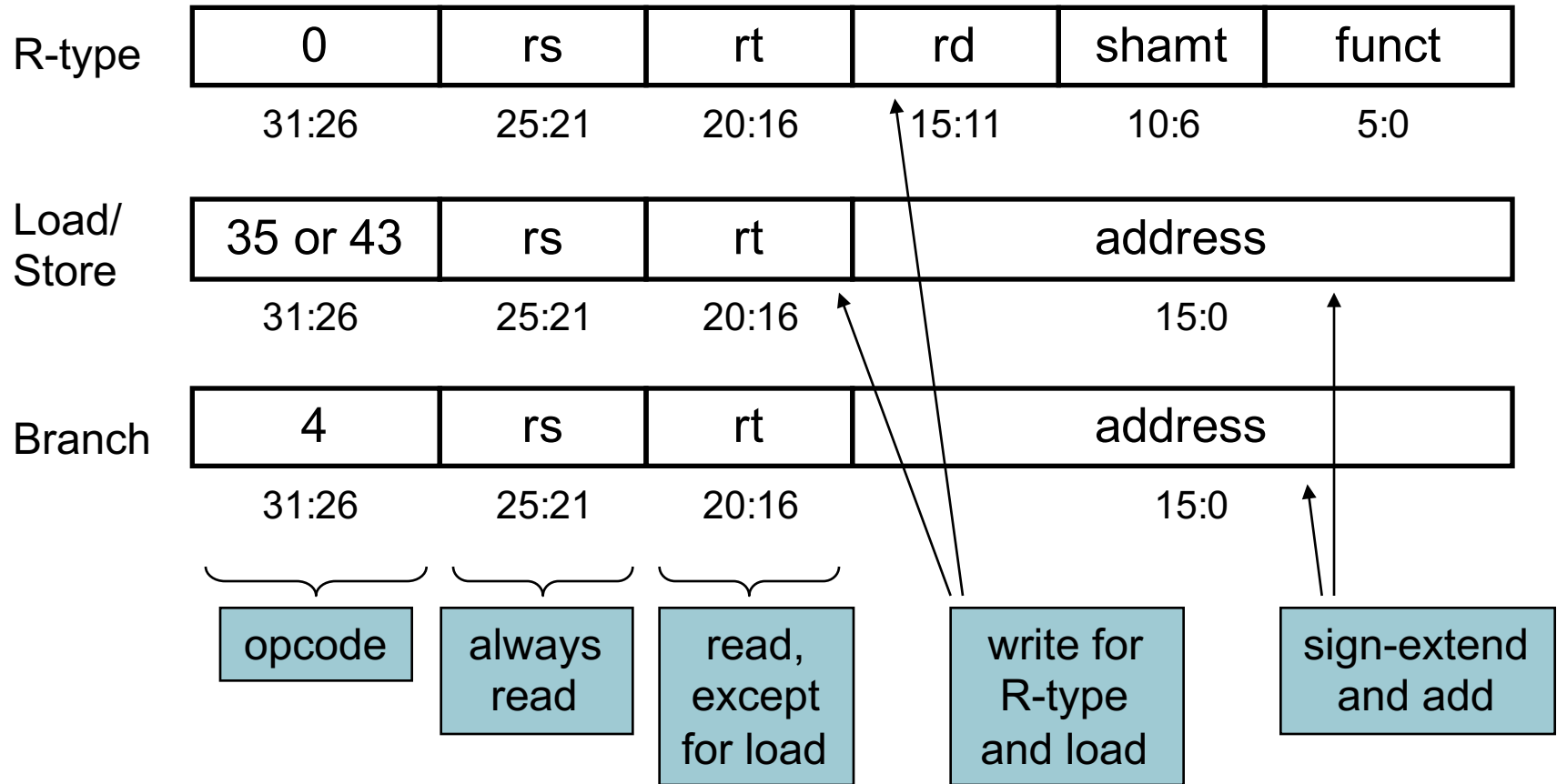


# First Version Datapath

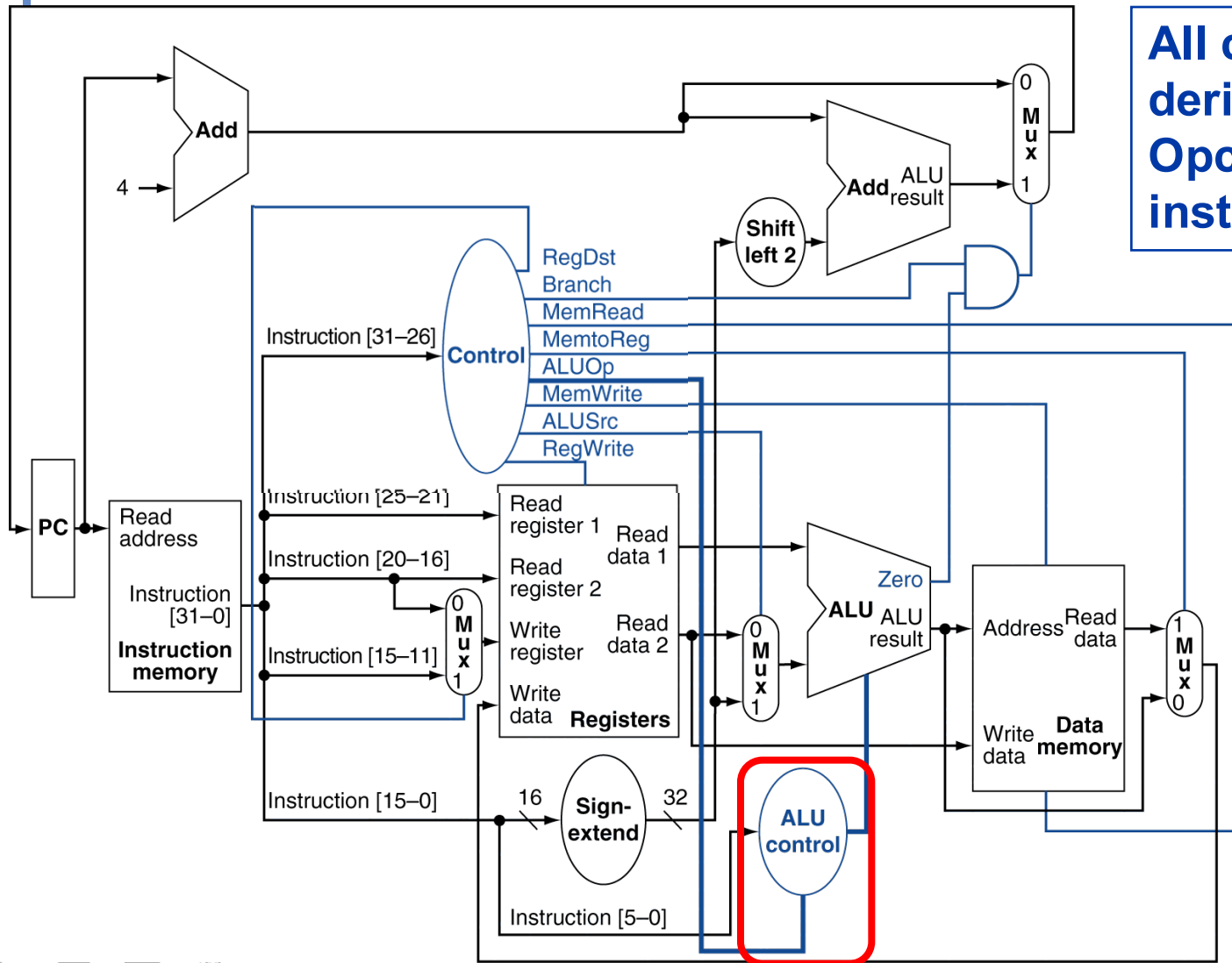


**Need control signals  
to control the behavior  
of the datapath**

# How Operands are Used?



# Datapath With Control



All control signals derived from 6-bit Opcode of an instruction



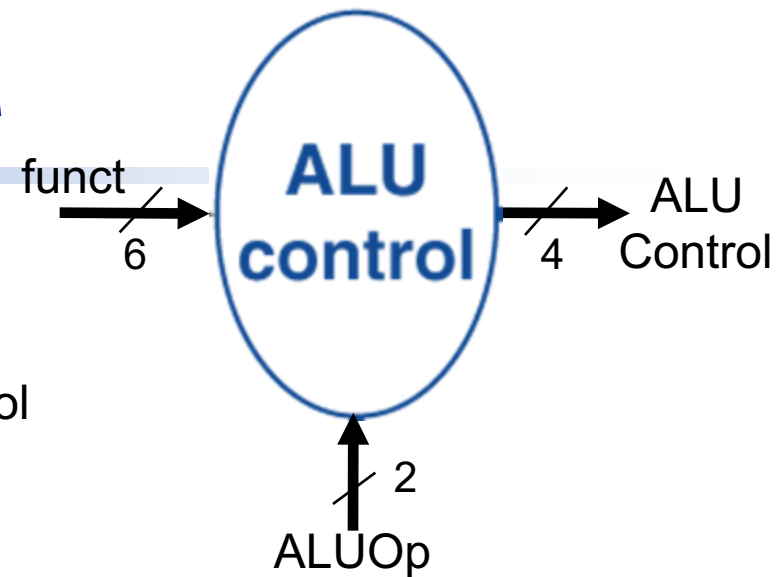
# ALU Control Unit

- ALU used for
  - Load/Store: Function = add
  - Branch: Function = subtract
  - R-type: Function = add/subtract/logical, depends on funct field in instructions

ALU Control (output)	Function
0000	AND
0001	OR
0010	add
0110	subtract
0111	set-on-less-than
1100	NOR

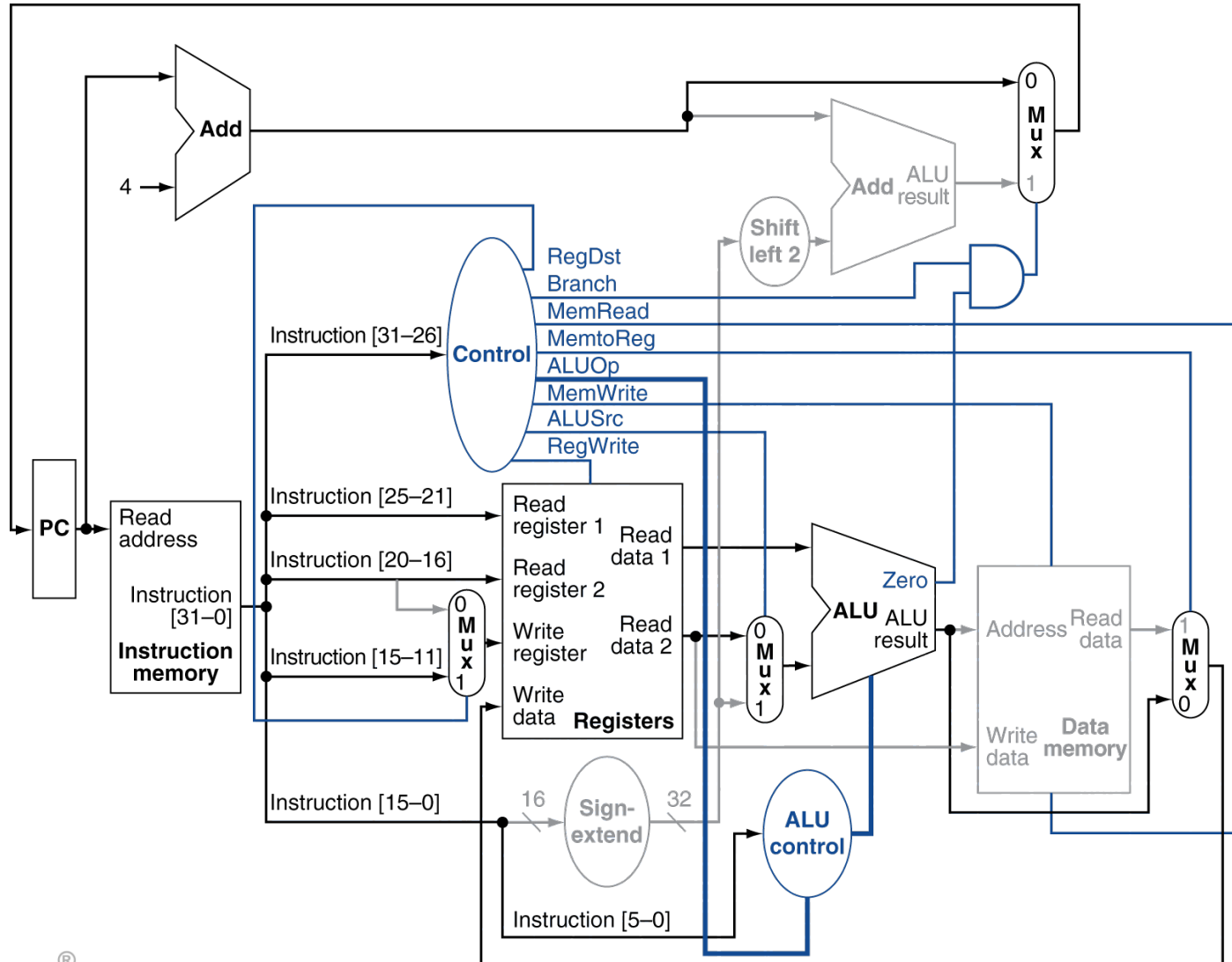
# ALU Control Unit

- Assume 2-bit ALUOp generated by CPU controller
  - Combinational logic derives ALU control
  - With inputs ALUOp and funct – 8 bits

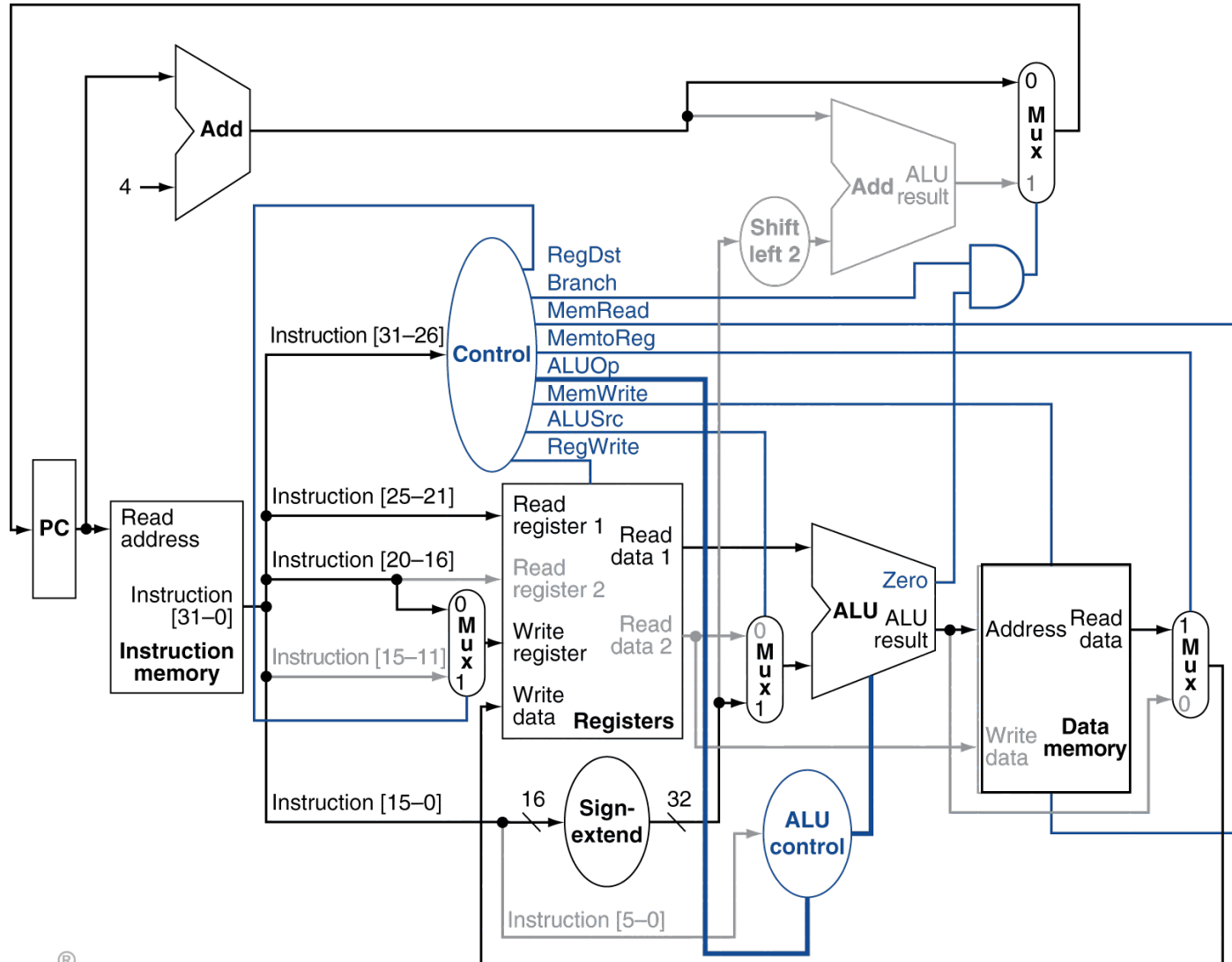


opcode	Operation	ALUOp	funct	ALU Control	ALU function
lw	load word	00	XXXXXX	0010	add
sw	store word				
beq	branch equal	01	XXXXXX	0110	subtract
R-type	add	10	100000	0010	add
	subtract		100010	0110	subtract
	AND		100100	0000	AND
	OR		100101	0001	OR
	set-on-less-than		101010	0111	set-on-less-than

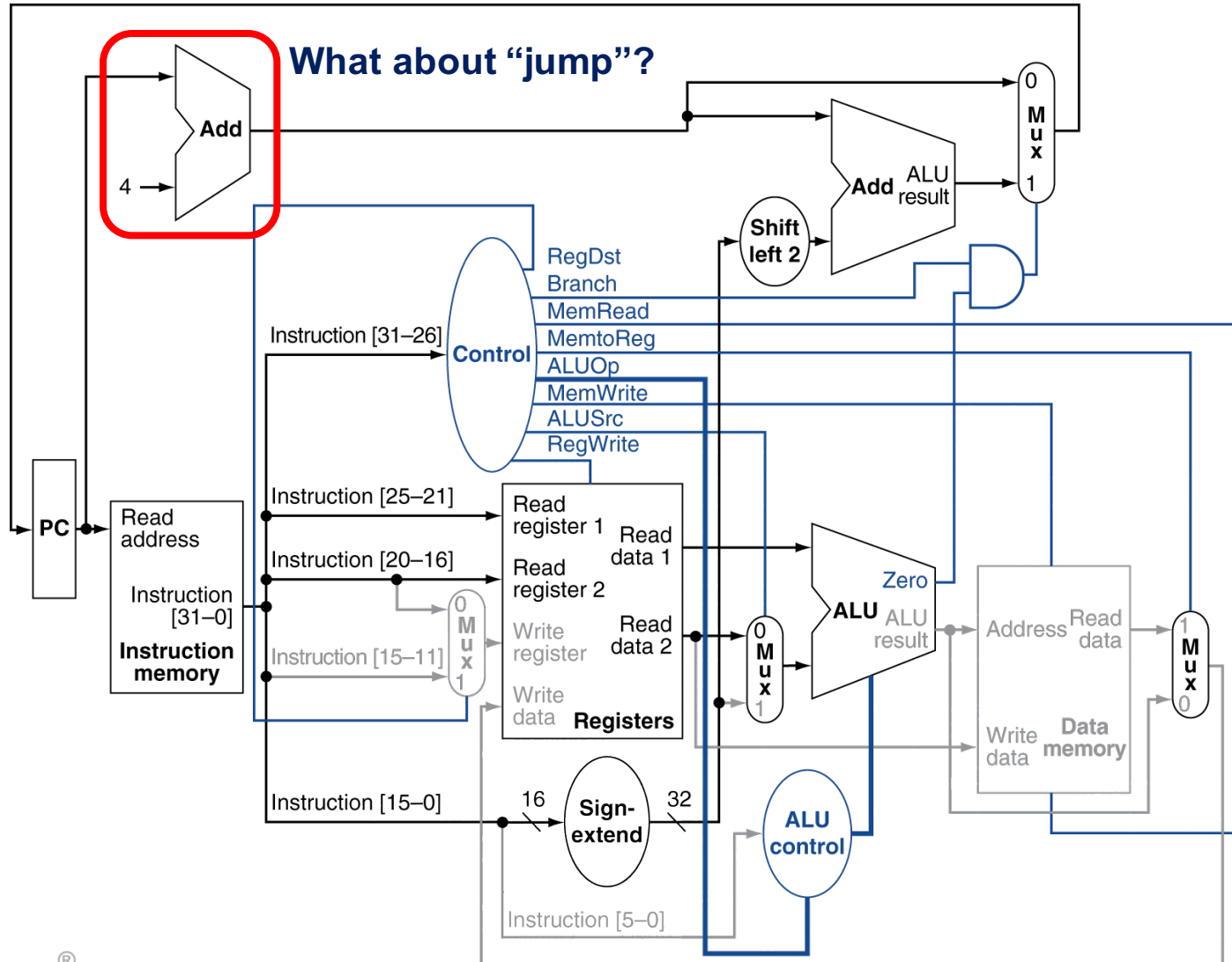
# R-Type Instruction



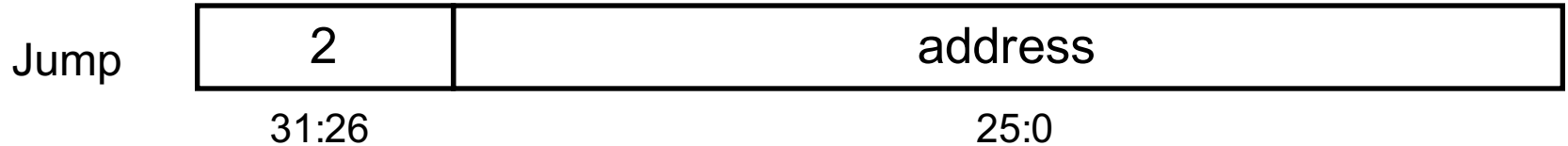
# Load Instruction



# Branch-on-Equal Instruction

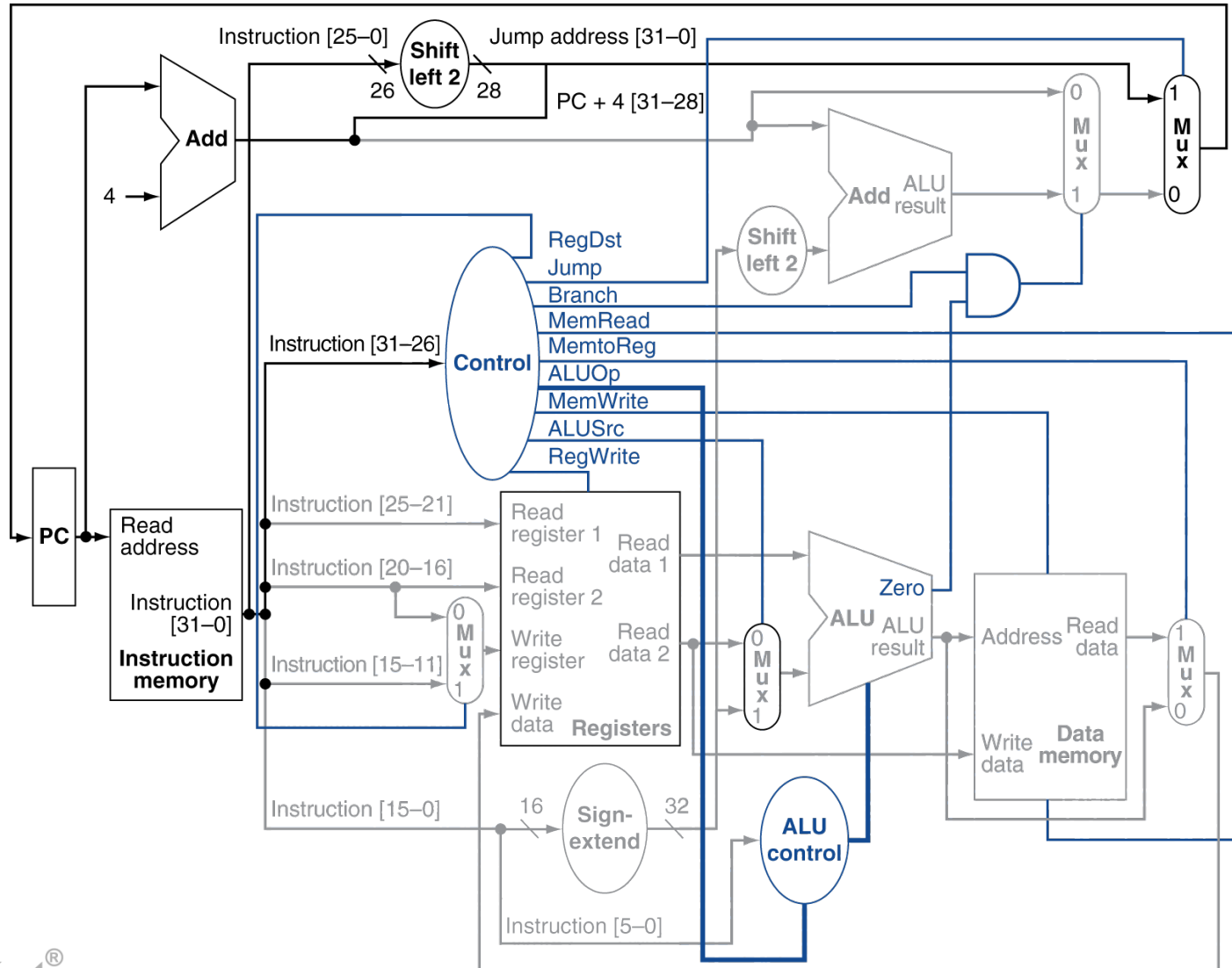


# Implementing Jumps



- Jump needs to calculate new address
- Update PC with new address:
  - Top 4 bits of old PC:26-bit jump address:00
- Need an extra control signal decoded from opcode by Control Unit to alternate the PC value

# Datapath With Jump Supported



# Performance Issues

- Longest delay determines clock period
  - Critical path: the path having longest delay
    - load instruction  
Instruction memory → register file → ALU → data memory → register file (plus MUXes)
- Not feasible to vary period for different instructions
  - Waste time on other instructions
- How to improve the performance (faster speed)?