Gradient Checking

Gradient checking will assure that our backpropagation works as intended. We can approximate t function with:

$$rac{\partial}{\partial \Theta} J(\Theta) pprox rac{J(\Theta + \epsilon) - J(\Theta - \epsilon)}{2\epsilon}$$

With multiple theta matrices, we can approximate the derivative **with respect to** Θ_j as follows:

$$rac{\partial}{\partial \Theta_j} J(\Theta) pprox rac{J(\Theta_1, \dots, \Theta_j + \epsilon, \dots, \Theta_n) - J(\Theta_1, \dots, \Theta_j - \epsilon, \dots, \Theta_n)}{2\epsilon}$$

A small value for ϵ (epsilon) such as $\epsilon=10^{-4}$, guarantees that the math works out properly. If the end up with numerical problems.

Hence, we are only adding or subtracting epsilon to the Θ_i matrix. In octave we can do it as follow

```
1  epsilon = 1e-4;
2  for i = 1:n,
3    thetaPlus = theta;
4    thetaPlus(i) += epsilon;
5    thetaMinus = theta;
6    thetaMinus(i) -= epsilon;
7    gradApprox(i) = (J(thetaPlus) - J(thetaMinus))/(2*epsilon)
8    end;
9
```

We previously saw how to calculate the deltaVector. So once we compute our gradApprox vector, \approx deltaVector.

Once you have verified **once** that your backpropagation algorithm is correct, you don't need to co code to compute gradApprox can be very slow.