# ROBIN:

(ROBUSTNESS IN NETWORK)

AN R PACKAGE FOR VALIDATION OF

COMMUNITY ROBUSTNESS

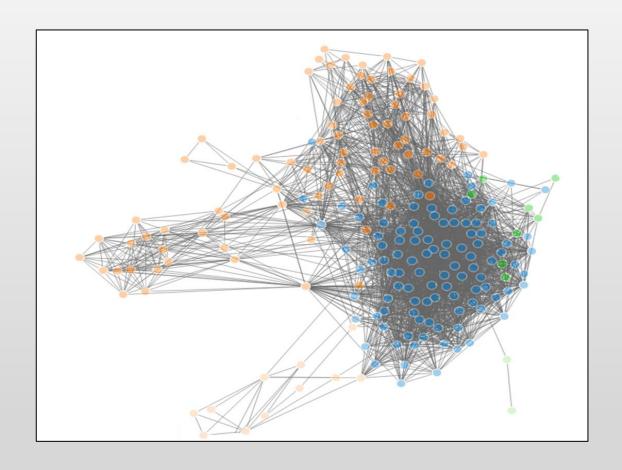
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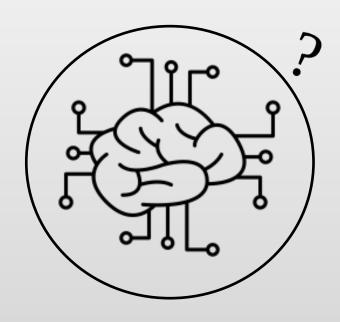
### COMMUNITY DETECTION

One of the most relevant features of graphs representing real systems is their community structure

How can we say that is statistically robust?

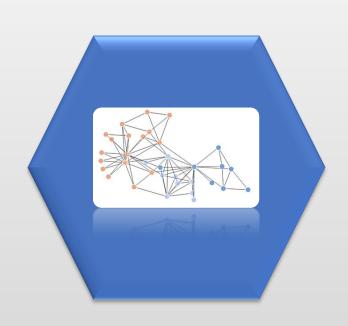


### ROBUSTNESS



Are the detected communities significant or are they a result of chance only due to the positions of edges in the network?

# ROBIN: (ROBustness In Network)



An R package that gives a statistical answer to the *validation of the community structure* by looking at the robustness of the network

Carissimo A., Cutillo L., De Feis I., Validation of community robustness Computational Statistics and Data Analysis 2017

### ROBUSTNESS AGAINST RANDOM PERTURBATION



❖ If a partition is significant, it will be recovered even if the structure of the graph is modified

#### ROBIN

\* ROBIN gives the possibility to analyze community detection in all different aspects:

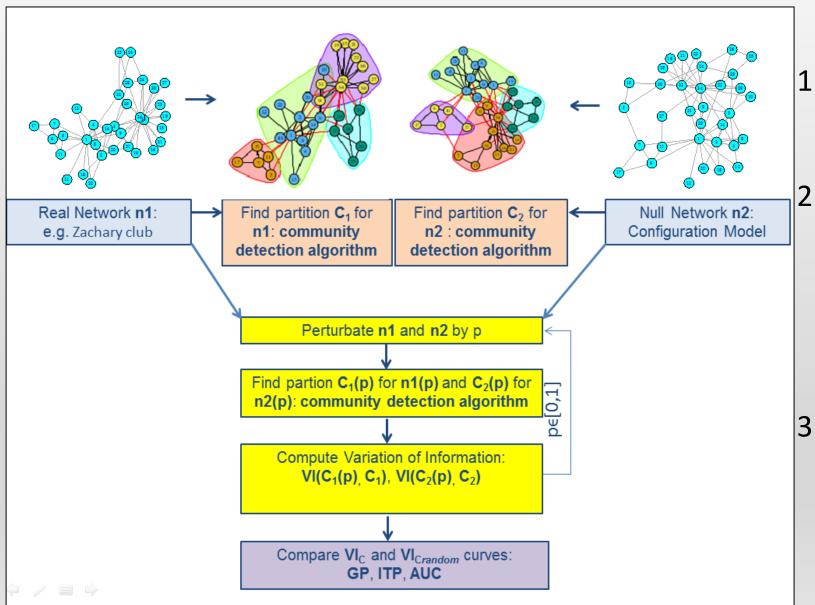
- ✓ Community detection algorithms
- ✓ Validation of the community structure
- ✓ Comparison of different community algorithms
- ✓ Graphical interactive representation of 3D networks

#### **PROCEDURE**

❖ Given a community detection method and a network of interest ROBIN analyses the stability of the partitions

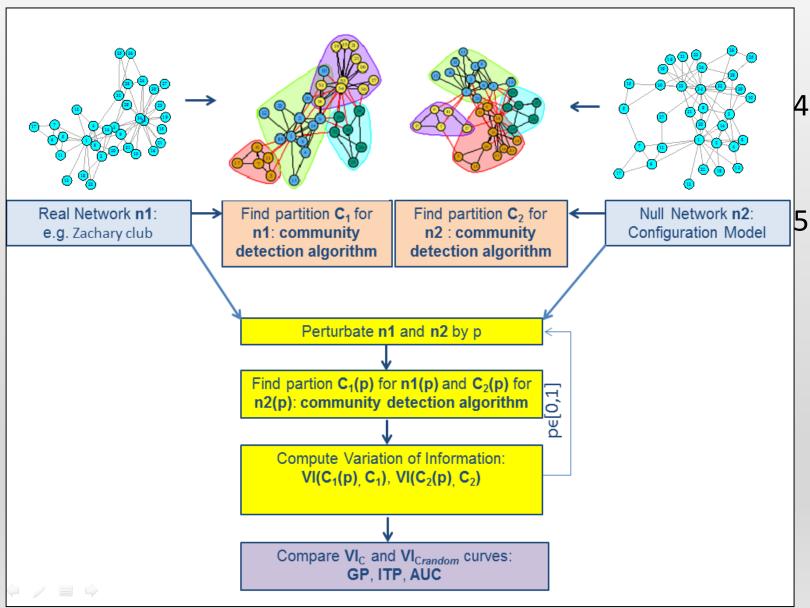
It implements a perturbation strategy and a null model to build a procedure based on Variation of Information

### ROBIN WORKFLOW

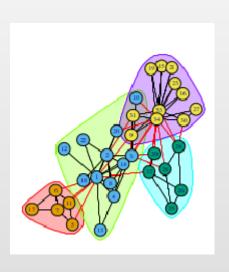


- Given a network, find a partition
   with some algorithm
- Perturb the network to create a new network, find the partition C' for the perturbed network, compare C and C' computing the Variation of Information VI
- 3. Repeat this calculation for different perturbation levels **p**

### ROBIN WORKFLOW



- Perform 2. and 3. on a random graph (null model)
- 5. Compare the curves obtained plotting the average VI versus p of the original and the null model



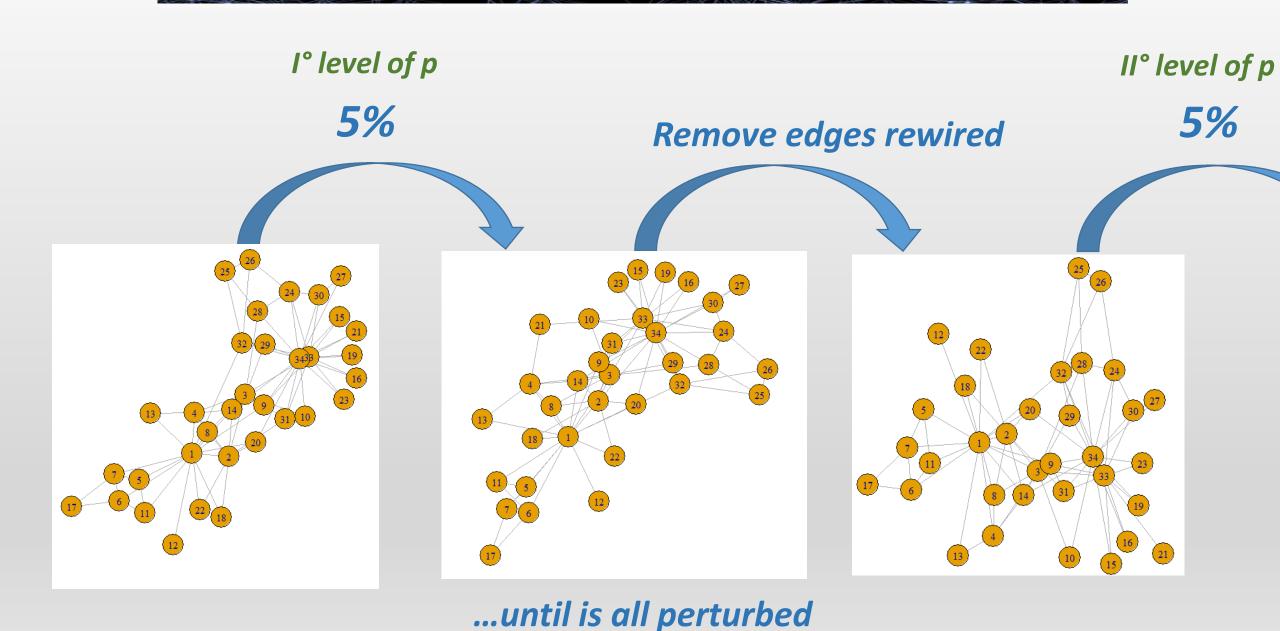
The perturbed network has the same number of vertices and edges as the original unperturbed network

*p*∈[0,1]

p=0 The original unperturbed graphp=1 The maximal perturbation level (random graph)

- \*Rewire algorithm: chooses two arbitrary edges in each step (e.g. (a,b) and (c,d))and substitutes them with (a,d) and (c,b) if they do not already exist in the graph
- keeping\_degseq: preserving the original graph's degree distribution

rewireComplete(graph, number)



#### Generates 20 levels of p

For each different level it generates 10 perturbed graph. Then, from each of the obtained graphs, it generates other 10 graphs rewiring 1% of edges each time

Result: 100 graphs for each level !!!

### ROBIN NULL MODEL

### **Configuration Model:**

- Able to preserve strongly heterogeneous degree distribution of the real network.
- It randomly assign edges between vertices with a given degree distribution.

graphRandom(graph)

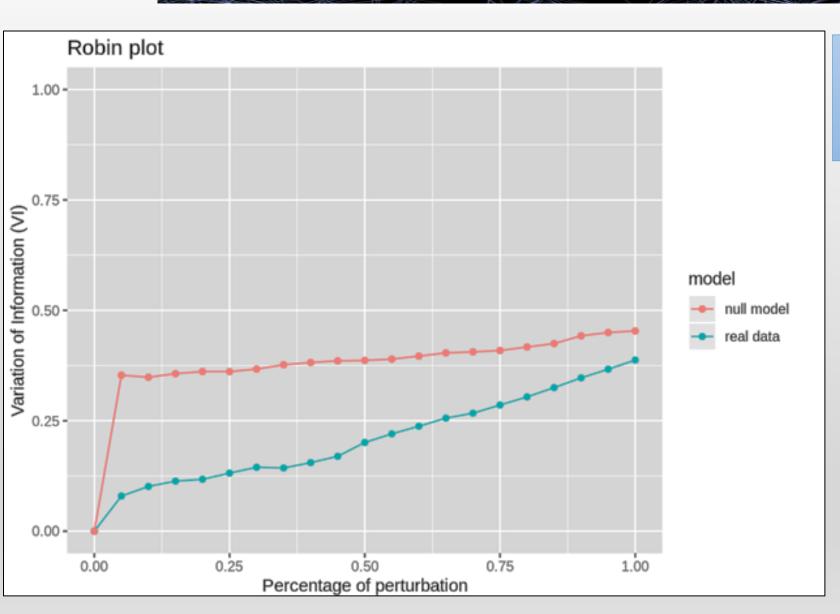
### VARIATION OF INFORMATION (VI)

At each level of perturbation *p* ROBIN compares the partition obtained from the original graph with the partition obtained from the perturbed graph computing Variation of Information (*VI*)

compare(comReal, comR, method="vi")

comReal = Community Real ComR = Community Rewire at a specific level

## VI AS FUNCTION OF AMOUNT OF PERTURBATION P



plotRobin (graph, model1, model2, legend)

model1= mean vi real data model2= mean vi null model

How can ROBIN test the differences between the two curves?

### ROBIN TESTS

The percentage of perturbation as time points of two time series

**Gaussian Process(GP)** 

Functional data analysis

**Interval Testing Procedure (ITP)** 

Compare the area under the curves

**AUC** 

### GAUSSIAN PROCESS

❖ Are the two curves from the same process or not?

**Gprege** package: Gaussian Process Ranking and Estimation of Gene Expression time-series

callGp (ratio)

ratio= log2(viMean/viMeanRandom) for each level



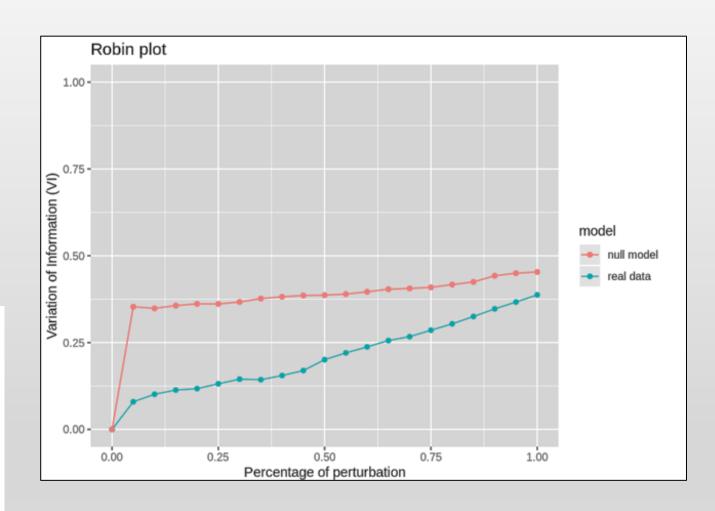
**Bayes Factor:** score based on the log-ratio of marginal likelihoods

bf=gpregeOutput\$rankingScores[1]

## GAUSSIAN PROCESS

Bayes\_Factor 383.8757

| K                                    | dHart    | bits       | Strength of evidence                |
|--------------------------------------|----------|------------|-------------------------------------|
| < 10 <sup>0</sup>                    | 0        | _          | Negative (supports M <sub>2</sub> ) |
| 10 <sup>0</sup> to 10 <sup>1/2</sup> | 0 to 5   | 0 to 1.6   | Barely worth mentioning             |
| 10 <sup>1/2</sup> to 10 <sup>1</sup> | 5 to 10  | 1.6 to 3.3 | Substantial                         |
| 10 <sup>1</sup> to 10 <sup>3/2</sup> | 10 to 15 | 3.3 to 5.0 | Strong                              |
| 10 <sup>3/2</sup> to 10 <sup>2</sup> | 15 to 20 | 5.0 to 6.6 | Very strong                         |
| > 10 <sup>2</sup>                    | > 20     | > 6.6      | Decisive                            |



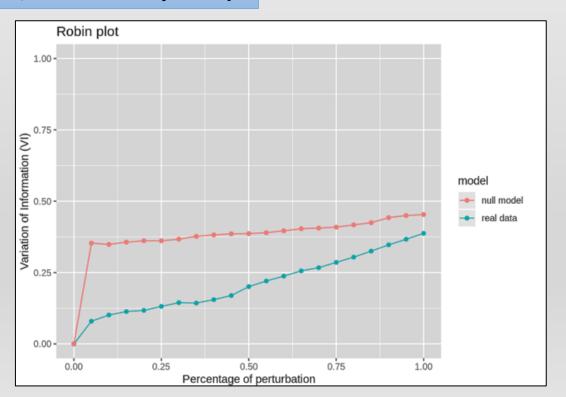


Calculate the area under the curve with a spline approach

**DescTools** package: Tools for Descriptive Statistics

AUC(x=percPerturb, y=mvimeanmodel1, method ="spline")

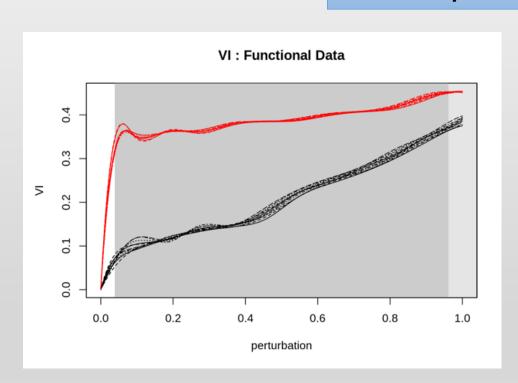
Area Under the Curve:
Area1 0.2082588
Area2 0.3840378

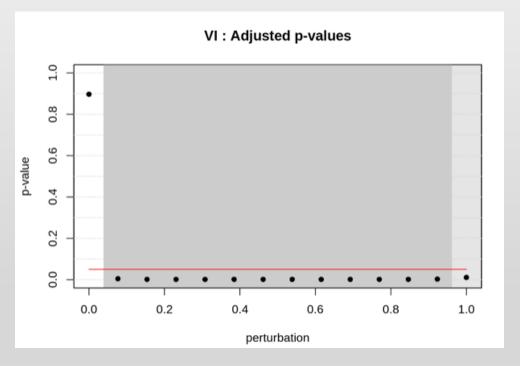


### INTERVAL-WISE FUNCTIONAL TESTING PROCEDURE

Provides an interval-wise non parametric functional testing able to point out specific differences

createITPSplineResult (graph, model1, model2)





The community structure found is statistically significant!!

### IGRAPH COMMUNITY DETECTION ALGORITHMS

Modularity

Random walk

> Node

> Edges

Fast greedy

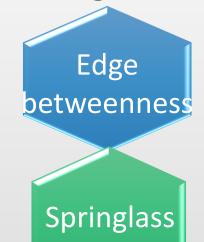
Louvain

Optimal

Leading eigenvector







### HOW CAN WE SAY WHICH METHOD IS THE BEST?

❖ A procedure to compare different algorithms

To check which algorithm fits better your network!

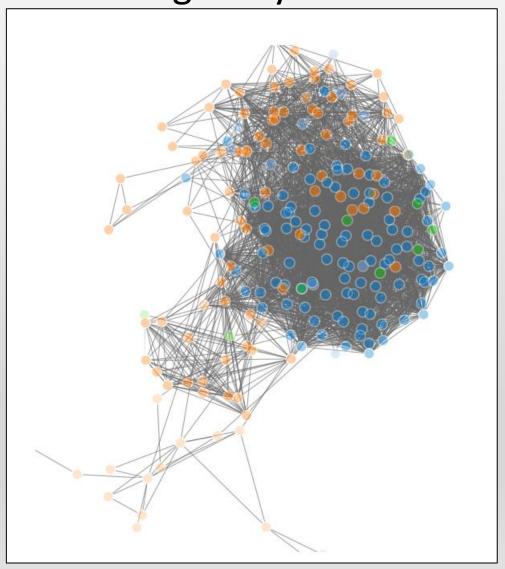
comparison(graph,graphRandom,method1,method2)

❖ At each perturbation level the procedure calculates the **VI** for both methods

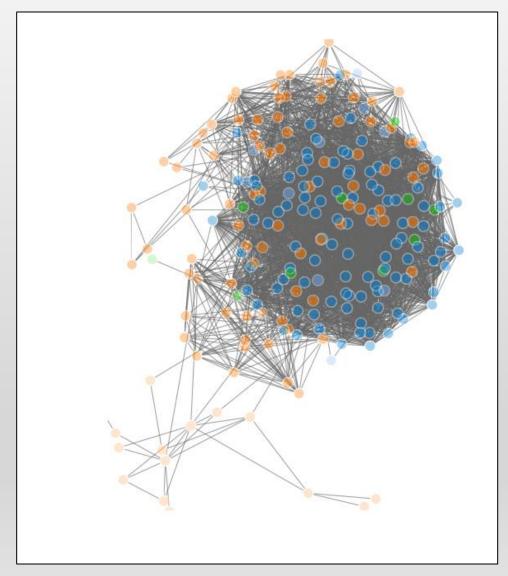
compare(comr1, comReal1, method="vi") for the first method
compare(comr2, comReal2, method="vi") for the second method

## HOW CAN WE SAY WHICH METHOD IS THE BEST?

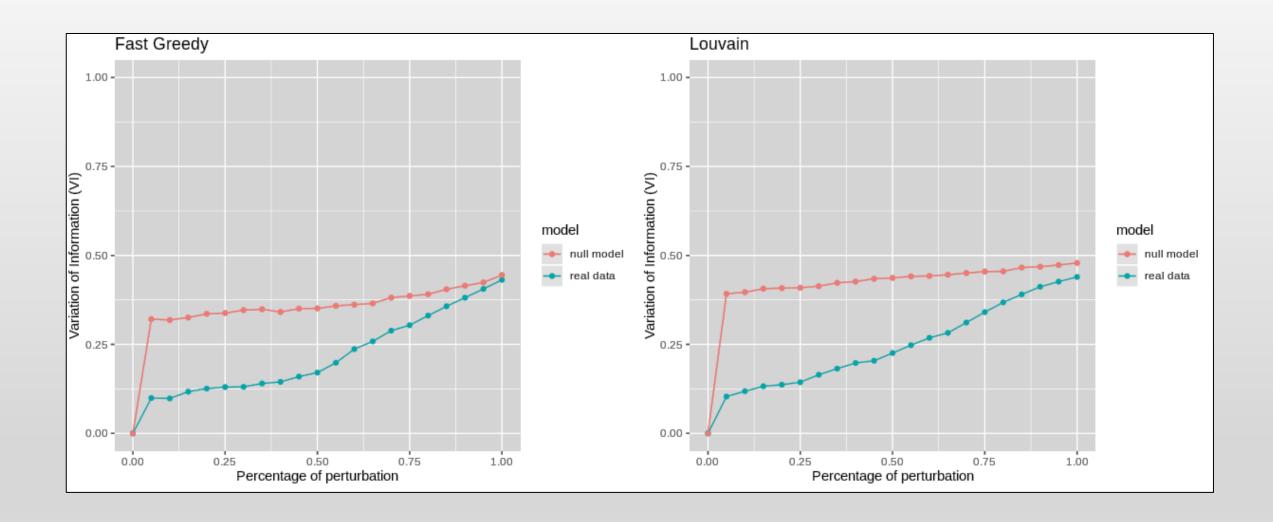
> Fast greedy



> Louvain



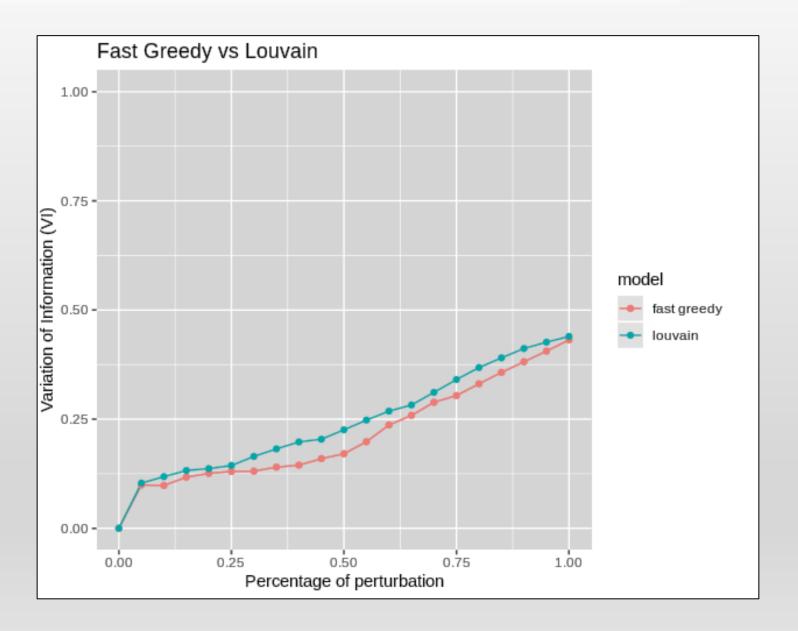
# VI CURVES



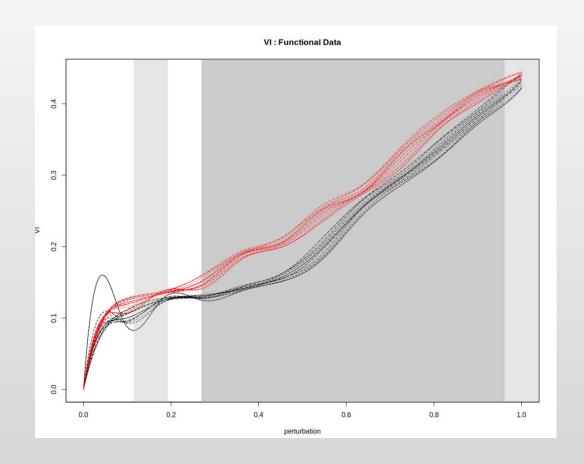
plotRobinCompare(graph, legend, legend1vs2, title1, title2, title1vs2)

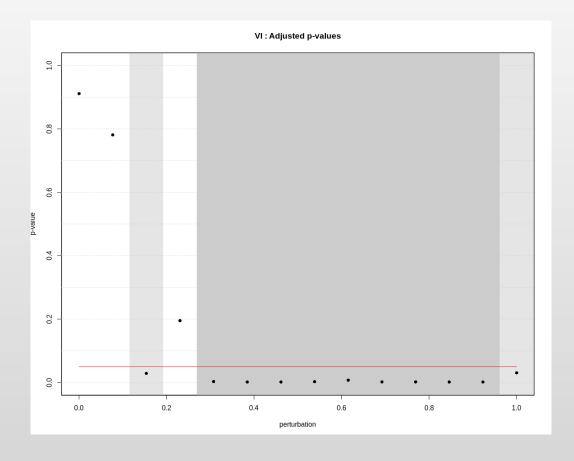
### **VI** CURVES

```
plotRobinCompare(graph,
legend=c("real data", "null model"),
legend1vs2=c("fast greedy",
"louvain"),
title1="Fast Greedy",
title2="Louvain",
title1vs2="Fast Greedy vs Louvain")
```



## ITP, GP and AUC





Bayes Factor 120.642

Areal 0.2151066 Area2 0.2442918

robinTest(graph, model1, model2, ratio, legend)

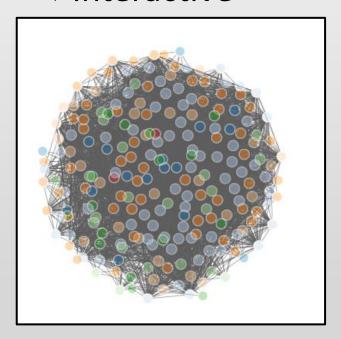
### REPRESENTATIONS

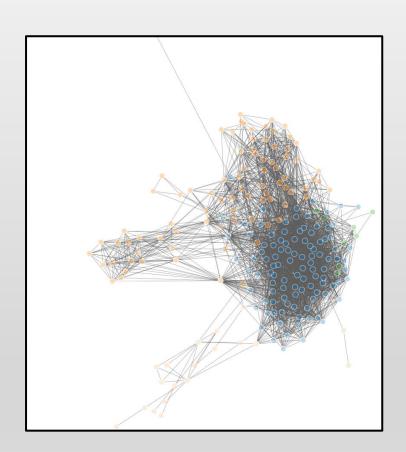
Graph communities

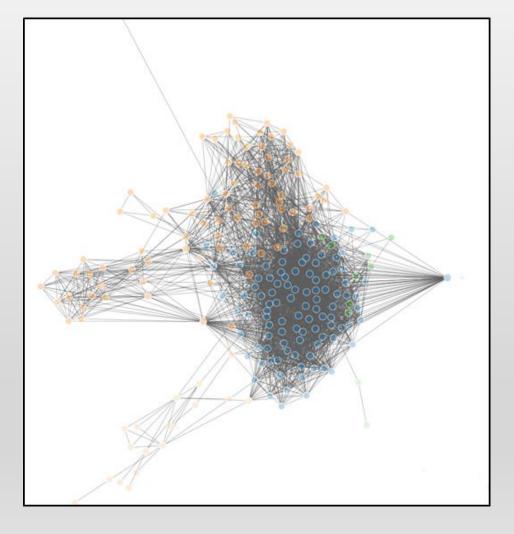
plotCommunity(graph,method)

> Fast greedy method

- **❖**3D
- **❖**Interactive







# ROBIN (ROBustness In Network)

- ✓ Community detection algorithms
- √ Validation of the community structure
- ✓ Comparison of different community algorithms
- ✓ Graphical interactive representation of 3D networks

#### FUTURE

#### **❖** To Publish ROBIN

- To use a different clustering stability measure
- To compare the performance of different measures for community structure comparison
- To test if the differences of the different methods are only due to the degree distribution of the network or are influenced by other factors

#### **BIBLIOGRAPHY**

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Thanks for the attention!



#### MODULARITY

A network with strong community structure has high modularity

Q is not sufficient, not all networks with high modularity have strong community structure

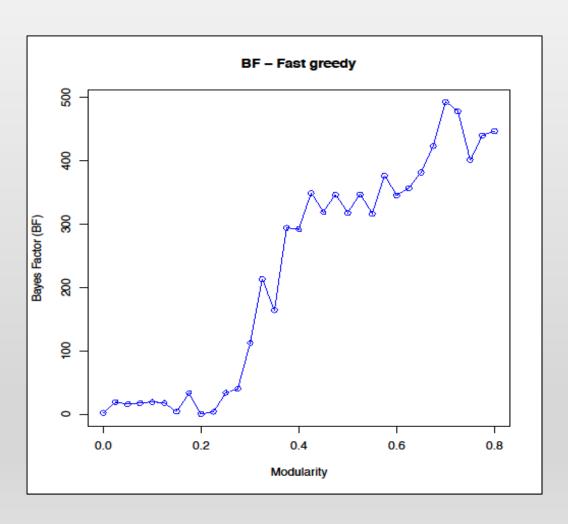
#### SIMULATION

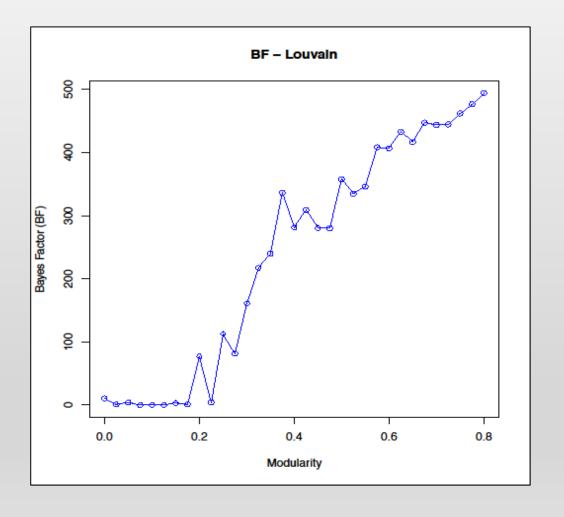
We used a literature model that generates undirected, simple and connected graphs with prescribed degree sequences and a specified level of community structure

We constructed networks with 2000 nodes, 10 communities, an average degree equal to 10 at different value of modularity Q

### SIMULATION STUDY

### Null models with different modularity





### VARIATION OF INFORMATION (VI)

At each level of perturbation **p** we compared the partition obtained from the original with the partition obtained from the perturbed graph computing Variation of Information (**VI**)

$$VI(C,C')=H(C|C')+H(C'|C)$$

- $0 \le VI(C,C') \le 2logK$
- C and C' are two generic partitions
- K is the number of clusters

### GAUSSIAN PROCESS

\*Are the two curves from the same process or not?

❖ The hypothesis testing problem can be reformulated over the perturbation interval [0,1] as:

$$H_0: \log_2 \frac{VIc(x)}{VIc_{random}(x)} \sim \mathcal{GP}(0, k(x, x'))$$

$$H_1: \log_2 \frac{VIc(x)}{VIc_{random}(x)} \sim \mathcal{GP}(m(x), k(x, x'))$$

**Bayes Factor** is approximated with a log-ratio of marginal likelihoods of two GPs, each one representing the hypothesis of differential (the profile has a significant underlying signal) and non differential expression (there is no underlying signal in the profile, just random noise).

- 1. **Basis Expansion:** functional data are projected on a functional basis (i.e. Fourier or B-splines expansion);
- 2. **Interval-Wise Testing:** statistical tests are performed on each interval of basis coefficients;
- 3. **Multiple Correction:** for each component of the basis expansion, an adjusted p-value is computed from the p-values of the tests performed in the previous step.