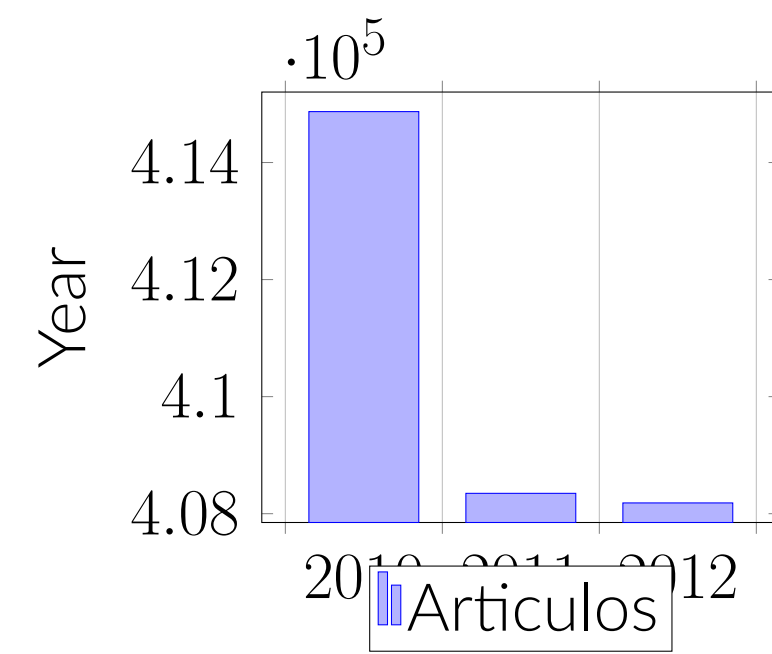
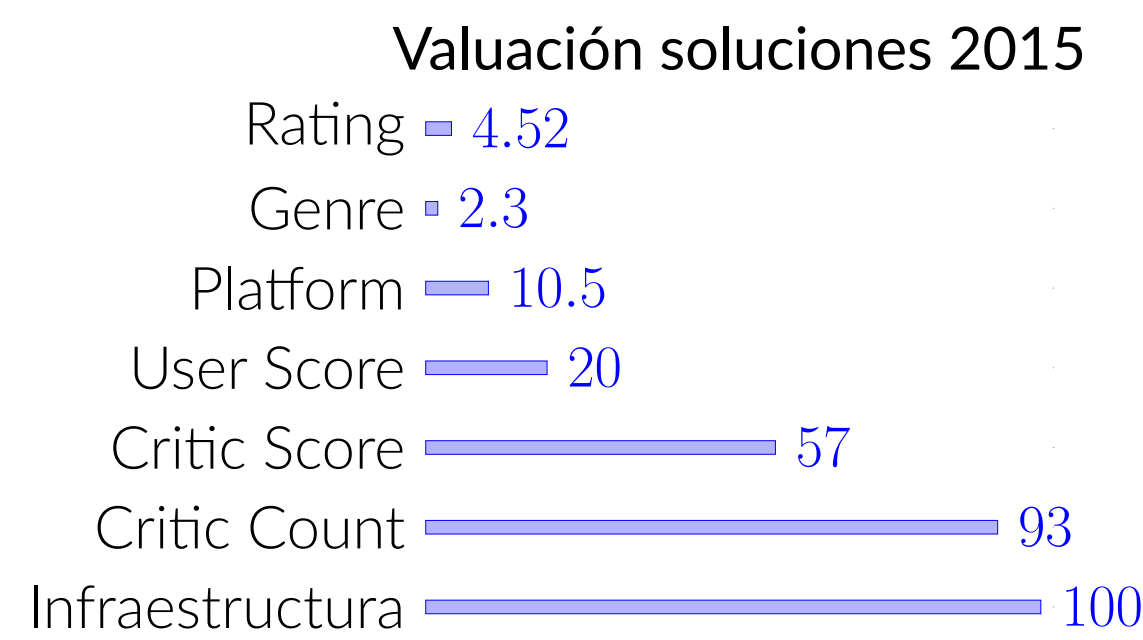


## Datos VANT

Leer paper <https://arxiv.org/pdf/1909.01423.pdf>



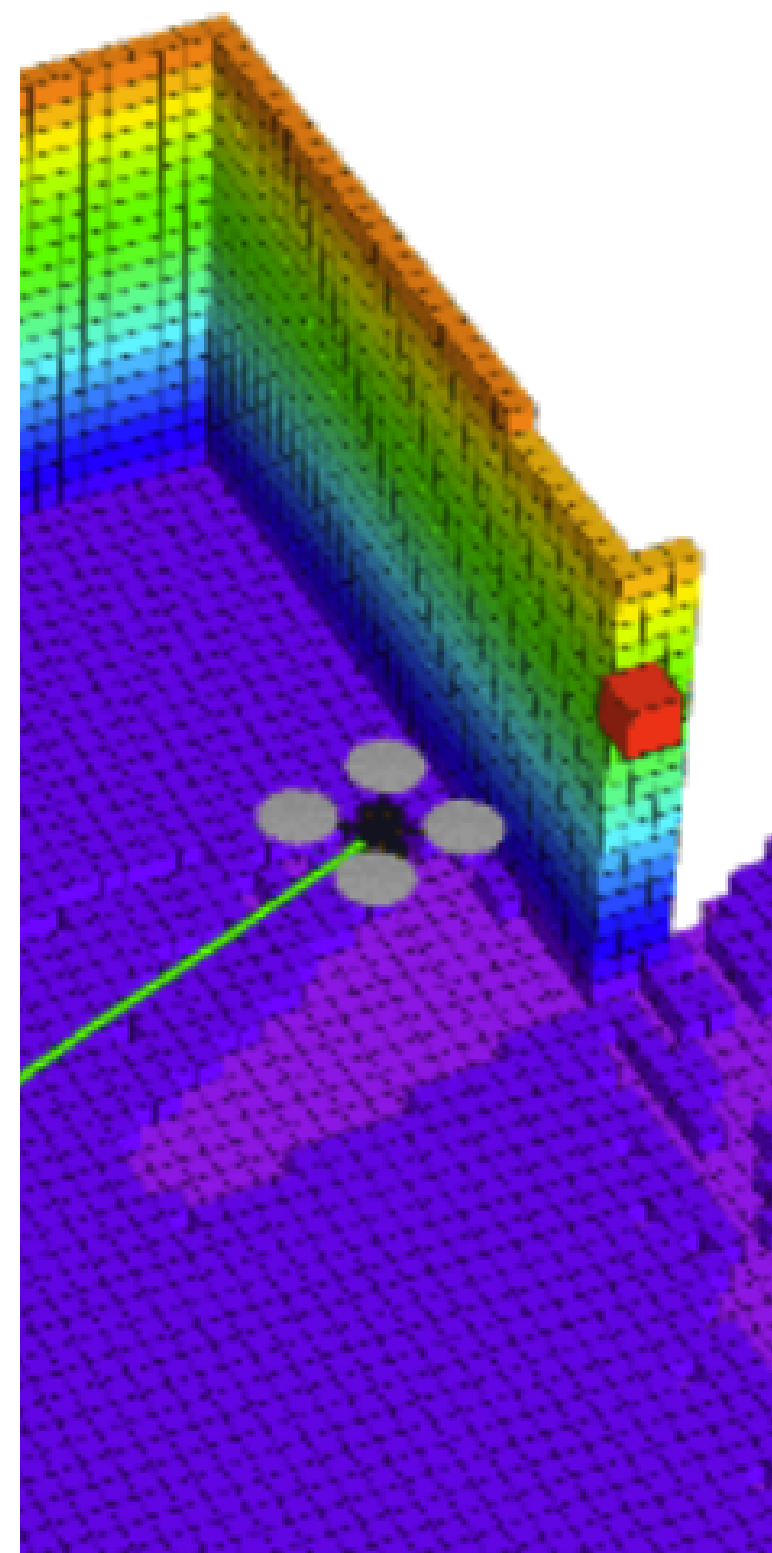
- Fusce dapibus tellus vel tellus semper finibus. In consequat, nibh sed mattis luctus, augue diam fermentum lectus.[3]
- Fusce dapibus tellus vel tellus semper finibus. In consequat, nibh sed mattis luctus, augue diam fermentum lectus.[1]
- Fusce dapibus tellus vel tellus semper finibus. In consequat, nibh sed mattis luctus, augue diam fermentum lectus.[2]

## Robot Autonomo

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## Taxonomia VANT Multi-rotor

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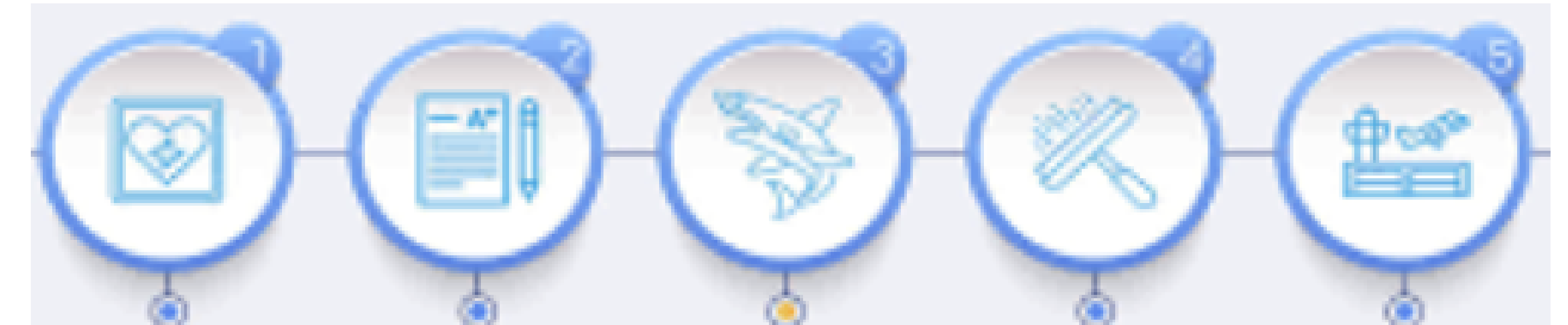


## Arquitectura Búsqueda y Rescate

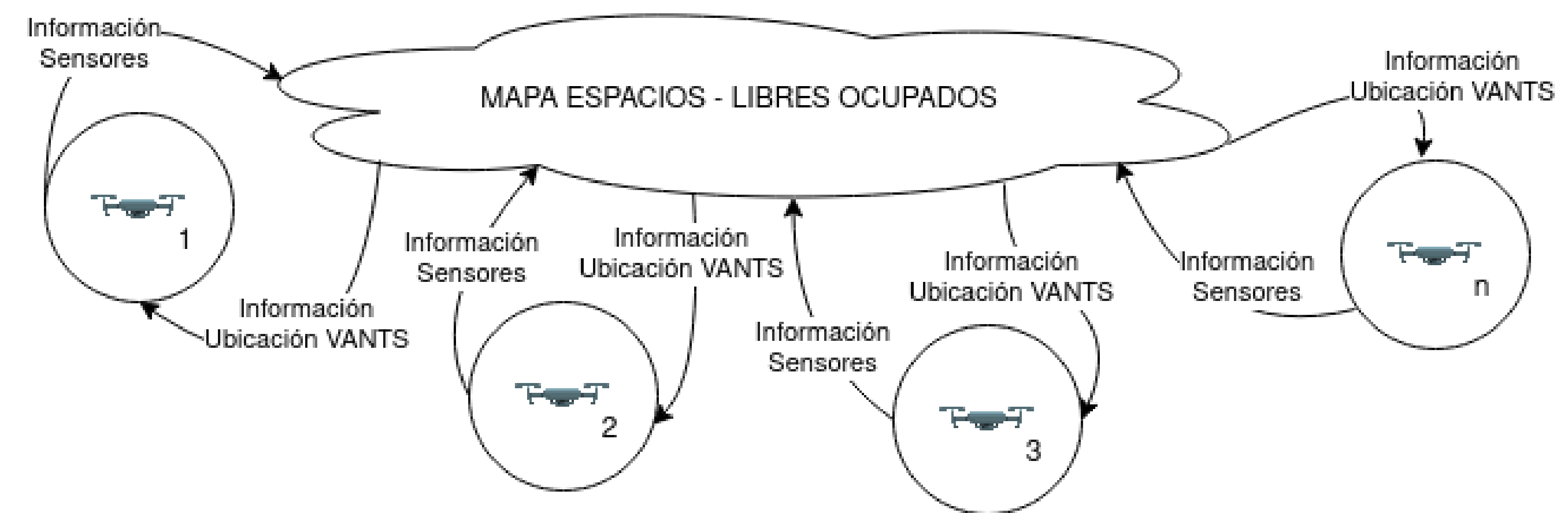
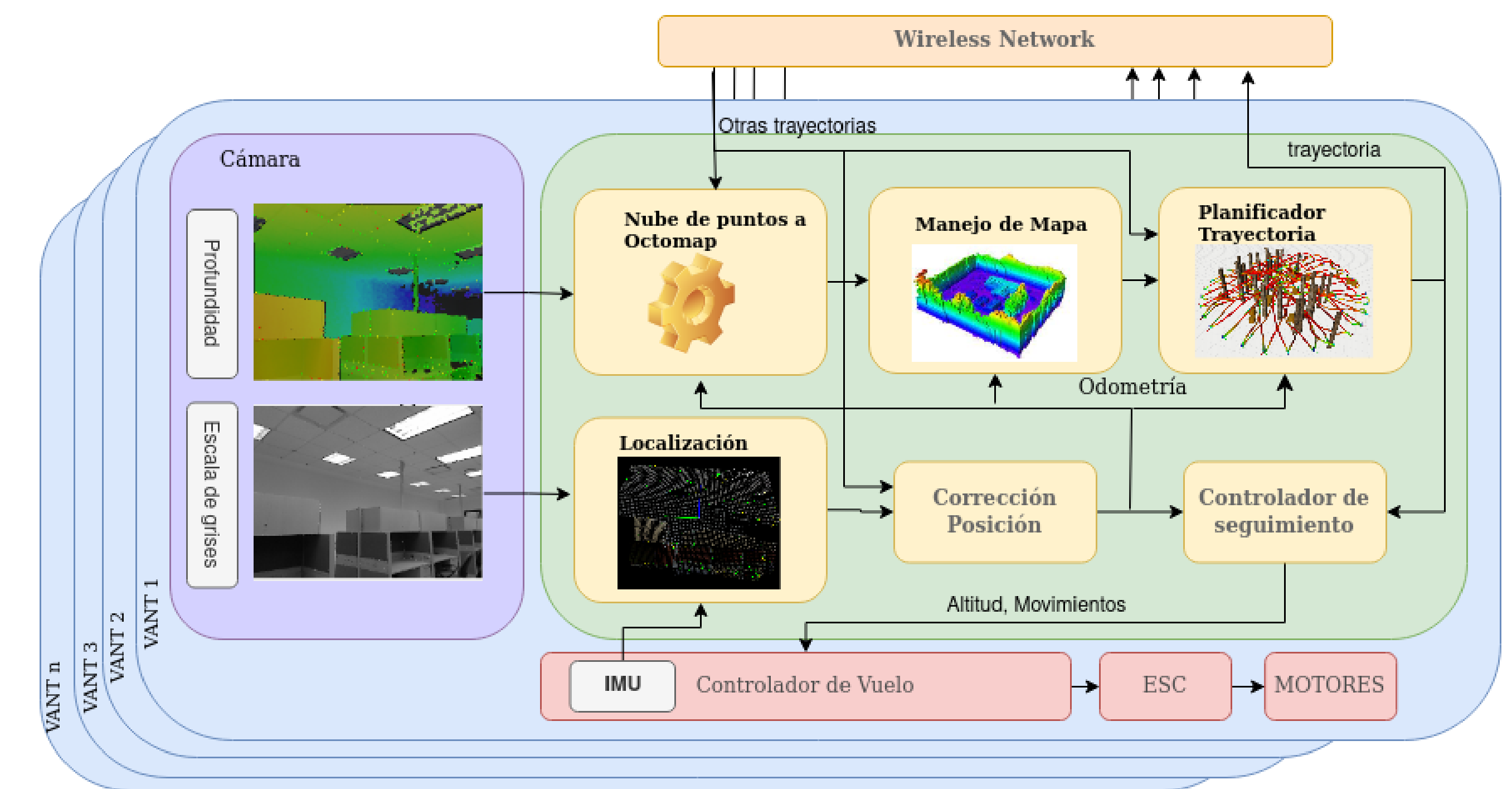
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## Aplicaciones



## Estrategia exploración coordinada



## Referencias

- [1] Ashten Akemoto and Frances Zhu. Informative path planning to explore and map unknown planetary surfaces with gaussian processes. In *2022 IEEE Aerospace Conference (AERO)*, pages 1–12, 2022.
- [2] Yixin Jiang, Lingyun Zhou, Yijia Tang, Ya Tu, Chunhong Liu, and Qingjiang Shi. A collaborative jamming algorithm based on multi-uav scheduling, 2023.
- [3] Claude E. Shannon. A mathematical theory of communication. *Bell System Technical Journal*, 27(3):379–423, 1948.