REGRESION LINEAL 1D:

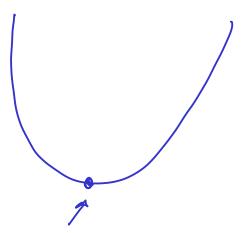
$$(x_1,t_1),(x_1,t_2)$$
 (x_N,t_N)

$$E = \frac{1}{2} \underset{i=1}{\leq} (y_i - t_i)^2$$

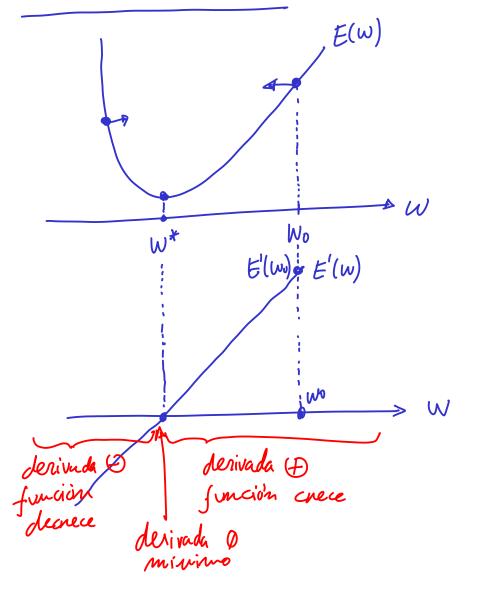
Planteauriento habitual:

$$\frac{\partial E}{\partial w} = \emptyset$$

$$\frac{\partial E}{\partial b} = \emptyset$$
resulvo $\rightarrow \mathbb{E}$ Socución



DESCENSO YOR GRADIENTE:



Siempre >0

Si
$$\xi'(w_0) > \emptyset \implies w_2 = w_0 (\Delta)$$

Si
$$\not\in'(w_0)$$
 < $\sigma \Rightarrow w_2 = w_0 \not= \omega$

$$W_0$$

$$W_1 = W_0 - \eta \cdot E'(W_0)$$

DESCENSO POR GRADIENTE

$$W_{t} = W_{t-1} - \gamma \cdot E'(W_{t-1})$$

PARA R. LINEAL:

$$W_{t} = W_{t-1} - \eta \cdot \frac{\Im E}{\Im W} \Big|_{W_{t-1}}$$

$$b_{t} = b_{t-1} - \eta \cdot \frac{\Im E}{\Im b} \Big|_{b_{t-1}}$$

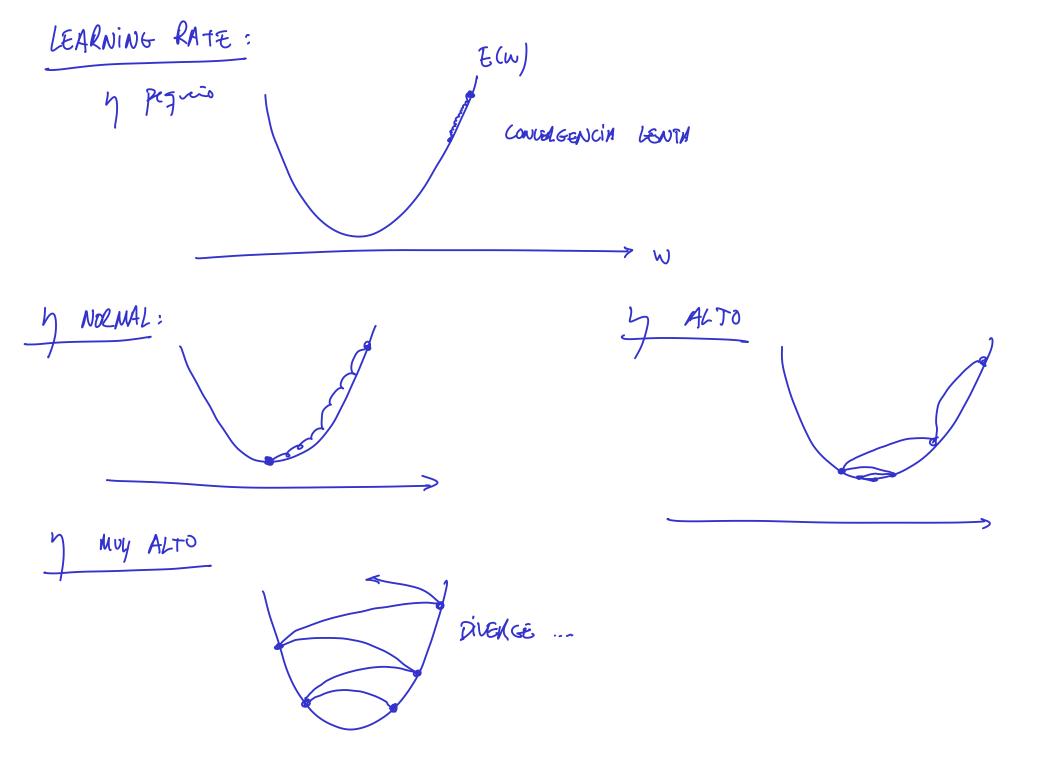
$$w_t = w_{t-1} - \gamma \cdot \underbrace{z}_{i=1}^{N} (y_i - t_i) \cdot x_i$$

$$b_t = b_{t-1} - \gamma \cdot \underbrace{z}_{i=1}^{N} (y_i - t_i)$$

D.GRAD. REGR. LINEAL

$$E = \frac{1}{2} \sum_{i=1}^{N} (y_i - t_i)^2 \qquad y_i = w x_i + b$$

$$\frac{\partial E}{\partial b} - \sum_{i=1}^{N} (y_i - t_i) \frac{\partial y_i}{\partial b} \qquad \frac{\partial E}{\partial w} = \sum_{i=1}^{N} (y_i - t_i) \frac{\partial y_i}{\partial w} = \sum_{i=1}^{N} (y_i - t_i) x_i$$



REGR. LINEAL & DIMENSIONES:

$$\{(\overline{X}_1, t_1), (\overline{X}_1, t_2), \dots, (\overline{X}_N, t_N)\}$$

$$\overline{X}_{i} \in \mathbb{R}^{d}$$
 $\overline{X}_{i} = (X_{i4}, X_{i2}, --, X_{id})^{T}$

$$y_{i} = f(\overline{x}_{i}) = \overline{W}^{T}.\overline{x}_{i} + b = \underbrace{\underbrace{\underbrace{\underbrace{X}_{i}}_{j=1}}^{N} \underbrace{\underbrace{Y}_{i} - t_{i}}^{N}}_{j=1} \underbrace{\underbrace{\underbrace{X}_{i}}_{j=1}}^{N} \underbrace{\underbrace{\underbrace{Y}_{i} - t_{i}}^{N}}_{j=1} \underbrace{\underbrace{\underbrace{X}_{i}}_{j=1}}^{N} \underbrace{\underbrace{\underbrace{Y}_{i} - t_{i}}^{N}}_{j=1} \underbrace{\underbrace{\underbrace{X}_{i}}_{j=1}}^{N} \underbrace{\underbrace{\underbrace{X}_{i}}_{j=1}}^{N} \underbrace{\underbrace{\underbrace{X}_{i}}_{j=1}}^{N} \underbrace{\underbrace{X}_{i}}_{j=1} \underbrace{\underbrace{X}_{i}}_{j=1}}^{N} \underbrace{\underbrace{X}_{i}}_{j=1} \underbrace{X}_{i}}_{j=1} \underbrace{\underbrace{X}_{i}}_{j=1} \underbrace{\underbrace{X}_{i}}_{j=1} \underbrace{X}_{i}}_{j=1} \underbrace{X}_{i}}_{j=1$$

$$b \leftarrow b - \gamma \cdot \frac{\partial E}{\partial b}$$
 $\longrightarrow \frac{\partial E}{\partial b} - \frac{N}{i=1}(y_i - t_i)$

$$w_j \leftarrow w_j - \gamma \frac{\partial E}{\partial w_j}$$

$$\frac{\partial E}{\partial w_j} = \underbrace{\frac{\partial E}{\partial w_j}}_{i=1} (\gamma_i - t_i) \cdot x_{ij}$$

$$\overline{\nabla E} = \left(\frac{\partial E}{\partial \omega_{a}}, \frac{\partial E}{\partial \omega_{2}}, \dots, \frac{\partial E}{\partial \omega_{d}}\right)^{T}$$

$$\overline{\nabla} \mathcal{E} = \left(\frac{\partial \mathcal{E}}{\partial \omega_{a}}, \frac{\partial \mathcal{E}}{\partial \omega_{a}}, \dots, \frac{\partial \mathcal{E}}{\partial \omega_{d}}\right)^{T} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{2} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{2} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{2} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{2} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{2} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{2} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{2} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{2} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{2} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{2} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{2} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{2} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{2} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{2} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{2} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{2} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{2} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{2} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{2} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{2} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{2} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{2} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{1} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{1} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{1} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{1} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{1} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{1} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{1} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{1} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{1} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{1} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{1} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{1} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{1} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{1} \\ \omega_{1} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{1} \\ \omega_{1} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{1} \\ \omega_{2} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{1} \\ \omega_{1} \\ \omega_{2} \\ \vdots \\ \omega_{d} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{1} \\ \omega_{2} \\ \omega_{2} \\ \omega_{3} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{1} \\ \omega_{2} \\ \omega_{2} \\ \omega_{2} \\ \omega_{3} \\ \omega_{4} \end{array} \qquad \begin{array}{c} \langle \omega_{1} \\ \omega_{1} \\ \omega_{2} \\ \omega_{2} \\ \omega_{3} \\ \omega_{2} \\ \omega_{3} \\ \omega_{4} \\ \omega_{2} \\ \omega_{2} \\ \omega_{3} \\ \omega_{3} \\ \omega_{4} \\ \omega_{2} \\ \omega_{2} \\ \omega_{3} \\ \omega_{3} \\ \omega_{4} \\ \omega_{4} \\ \omega_{2} \\ \omega_{4} \\ \omega_{5} \\ \omega_{5} \\ \omega_{4} \\ \omega_{5} \\ \omega_{$$

 $\overline{W} = (w_1, w_2, \dots, w_d)'$

$$\overline{W} \leftarrow \overline{W} - \gamma \cdot \overline{Z} = \overline{W} = \overline{W} + \overline{W} = \overline{W$$

$$\overline{V_W E} = \underbrace{\underbrace{\underbrace{S(y_i - t_i)}}_{X_i = 1} \cdot \underbrace{\underbrace{X_{i2}}_{X_{i2}}}_{X_i d}$$

$$\underbrace{\underbrace{X_{id}}_{X_i d}}_{X_i d}$$

PROGRAMACIÓN:

$$y = \overline{w}^{t}.\overline{x} + b$$

$$y = np.dot(x, w^T) + b$$

$$\begin{array}{c} X \\ X \\ \end{array}$$

$$b = h * mp. sum (y-t)$$

$$w = h * mp. sum ((y-t) * x, axis = p) / w = h \cdot (y-t) @ x$$

$$keep dhus = The$$

REGRESION LOGISTICA:

$$\overline{X}_i = (X_{i4}, X_{i2}, \dots, X_{id})^T \in \mathbb{R}^d$$

$$\widetilde{W} = (W_1, W_2, ..., W_d)^T$$

$$b$$

$$y_i = PROB(t=4|\overline{X_i})$$

 $1-y_i = PROB(t=\emptyset|\overline{X_i})$

MAXIMIZAR LA PROB. QUE EL MODELO ASIGNA A LAS CLASES REALES

VEROSIMICITUD/LIKELI HOOD

$$l = \prod_{i=1}^{N} P(t=t_i) X_i$$

$$L = \log l = \sum_{i=1}^{N} \log P(t=t_i | X_i)$$

VEROSIMICITUD LOGARITMICA

$$P(t=t_i)X_i) = \begin{cases} y_i & \text{si } t_i = 1 \\ 1-y_i & \text{si } t_i = \infty \end{cases}$$

$$P(t=t_i)X_i) = \begin{cases} y_i & \text{si } t_i = 1 \\ 1-y_i & \text{si } t_i = \infty \end{cases}$$

PARA HA CLASE REAL ti

$$L = \underbrace{\exists}_{i=1}^{N} \underbrace{\exists}_{1-y_i}^{y_i} \text{ si } t_i = 1$$

$$-y_i \text{ si } t_i = \emptyset$$

MAXIMIZAR

$$XE = -L = -\frac{Z}{Z} \left(t_i \cdot l_0 y_i + (n - t_i) l_0 (n - y_i) \right)$$

CROSS-ENTROPY -> MINIMIZAMOS

DESCENSU POR GRADIENTE

$$b \leftarrow b - \eta \cdot \frac{\partial x \epsilon}{\partial b}$$

$$\overrightarrow{w} \leftarrow \overrightarrow{w} - \eta \cdot \frac{\partial x \epsilon}{\partial x \epsilon}$$

$$\frac{\partial x \mathcal{E}}{\partial b} = \frac{\partial x \mathcal{E}}{\partial y^{i}} \cdot \frac{\partial y^{i}}{\partial b} = \frac{\partial x \mathcal{E}}{\partial y^{i}} \cdot \frac{\partial y^{i}}{\partial z^{i}} \cdot \frac{\partial z^{i}}{\partial b}$$

$$\frac{\partial x \mathcal{E}}{\partial w_{i}} = \frac{\partial x \mathcal{E}}{\partial y_{i}} \cdot \frac{\partial y^{i}}{\partial w_{i}} = \frac{\partial x \mathcal{E}}{\partial y_{i}} \cdot \frac{\partial y^{i}}{\partial z^{i}} \cdot \frac{\partial z^{i}}{\partial w_{i}}$$

$$\frac{\partial x \mathcal{E}}{\partial w_{i}} = \frac{\partial x \mathcal{E}}{\partial y_{i}} \cdot \frac{\partial y^{i}}{\partial w_{i}} = \frac{\partial x \mathcal{E}}{\partial y_{i}} \cdot \frac{\partial y^{i}}{\partial z^{i}} \cdot \frac{\partial z^{i}}{\partial w_{i}}$$

$$\frac{\partial XE}{\partial b} = \frac{\partial XE}{\partial y_i} \cdot \frac{\partial y_i}{\partial b} = \frac{\partial XE}{\partial y_i} \cdot \frac{\partial y_i}{\partial z_i} \cdot \frac{\partial y_i}{\partial b} - \frac{\partial XE}{\partial y_i} \cdot \frac{\partial y_i}{\partial z_i} \cdot \frac{\partial y_i}{\partial z_i} \cdot \frac{\partial z_i}{\partial w_i}$$

$$\frac{\partial XE}{\partial w_j} = \frac{\partial XE}{\partial y_i} \cdot \frac{\partial y_i}{\partial w_j} = \frac{\partial XE}{\partial y_i} \cdot \frac{\partial y_i}{\partial z_i} \cdot \frac{\partial z_i}{\partial w_i} \cdot \frac{\partial z_i}{\partial w_i}$$

$$XE = -\frac{2}{2}(t_{i}l_{0}y_{i} + (1-t_{i})l_{0}(1-y_{i}))$$

$$\frac{\partial XE}{\partial y_i} = -\frac{2}{|z|} \left[\frac{E_i}{y_i} - \frac{1-t_i}{1-y_i} \right] = \underbrace{\frac{N}{|z|}}_{i=1} \frac{y_i(1-t_i)}{y_i(1-y_i)}$$

$$\frac{t_i}{y_i} - \frac{1-t_i}{1-y_i} = \frac{t_i - t_i y_i - y_i + t_i y_i}{y_i \left[1-y_i\right]} = \frac{t_i - y_i}{y_i \left[1-y_i\right]}$$

$$\hat{y_i} = \sqrt{(z_i)} = \frac{1}{1 + e^{-z_i}} \qquad \frac{\partial y_i}{\partial z_i} = \frac{+1}{(1 + e^{-z_i})^2} \cdot e^{-z_i} = \frac{1 + e^{-z_i} - 1}{(1 + e^{-z_i})(1 + e^{-z_i})} = \frac{1}{(1 + e^{-z_i})(1 + e^{-z_i})} = \frac{1}{(1 + e^{-z_i})(1 + e^{-z_i})} = \frac{1}{(1 + e^{-z_i})(1 + e^{-z_i})(1 + e^{-z_i})} = \frac{1}{(1 + e^{-z_i})(1 + e^{-z_i})(1 + e^{-z_i})} = \frac{1}{(1 + e^{-z_i})(1 + e^{-z_i})(1 + e^{-z_i})(1 + e^{-z_i})} = \frac{1}{(1 + e^{-z_i})(1 + e^{-z_i$$

$$= \frac{1}{1 + e^{-z_i}} - \frac{1}{(1 + e^{-z_i})(1 + e^{-z_i})} = T(z_i) - T(z_i)^2 = T(z_i)(1 - T(z_i)) = y_i(1 - y_i)$$

$$T(z_i)^2$$

$$\frac{\partial XE}{\partial b} = \underbrace{\frac{N}{(y_i - t_i)}}_{i=1}$$

$$\frac{2XE}{2Wi} = \underbrace{2(yi-ti)\cdot Xij}_{i=1}$$

$$\frac{\partial \mathcal{L}}{\partial w_{i}} = \underbrace{\frac{\partial \mathcal{L}}{\partial y_{i} - t_{i}} \cdot \chi_{i}}_{i=1} \longrightarrow \underbrace{\frac{\partial \mathcal{L}}{\partial x_{i}}}_{w_{i}} = \underbrace{\frac{\partial \mathcal{L}}{\partial y_{i} - t_{i}} \cdot \chi_{i}}_{w_{i}}$$

becomes por GRADIENTE

$$W = W - y \cdot \underbrace{S(y_i - t_i)}_{i=1} \cdot X_i$$

DESCENSO POR GRADIENTE

PARA REGR. LOGISTICA

REGL. LINEAL

```
num_iters = 8 # number of iterations
eta = 0.0001 # learning rate
for i in range(num_iters):
    y = w*x + b
    y_minus_t = y - t
    dw = np.sum(y_minus_t*x)
    db = np.sum(y_minus_t)
    w -= eta*dw
    b -= eta*db
```

REGR. LOGISTICA

```
num_iters = 1000 # number of iterations
eta = 0.0002 # learning rate
for i in range(num_iters):
    z = w*x + b
    y = 1.0/(1.0 + np.exp(-z))
    y_minus_t = y - t
    dw = np.sum(y_minus_t*x)
    db = np.sum(y_minus_t)
    w -= eta*dw
    b -= eta*db
```