# CS/COE 0447

The Stack: The Untold Story

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### What is the Stack?

- In previous lectures, we introduced the stack.
- It is full of mysterious behavior:
  - "Allocating" on the stack (making room) has you *subtract* from its base address.
- Let's visit this from a different direction.
- Let's consider... the problem itself.
  - And how we might solve it.



### The Problem

- We have a program. It uses memory.
- We don't know exactly how much memory we need.
  - It may depend on how long the program runs.
  - Or the size of the data it is working on (arbitrarily specified by a human being, perhaps)
  - Maybe our program **responds to the available memory** by choosing a different algorithm when it has more or less.
- Either way, a program does not have a static allocation of memory.
- How do we allow a program to allocate memory on-demand?

### **Our Example: Video Editor**

- Let's consider a video editing program.
  - But thankfully ignore all of the actual video details!
- Data is large, and the memory usage is relative to the size of our video.
- We want memory to be continuous.
  - Could you imagine if data were all broken up?
  - Your program would be difficult to code if an array was broken up.
    - Our array addressing math would no longer be general and would cease to work well. (You'd have multiple array base addresses)

**Memory** 

**Program** 

# **Allocating Memory**

- You'll learn a lot more about this in CS 449
  - But it's worth sequence breaking and talking about it now
- We will maintain a section of memory: the heap.
  - The heap is a section of memory used for dynamic memory.
  - **Dynamic memory** is memory that is allocated during the runtime of a program and may be reclaimed later. 0x46f0
  - "heap" a very conflated term, unfortunately.
- When we allocate memory, we add it to **the end** of the heap.
  - It's like appending to an array.
  - Look at it go!

0x4100 0x4000

Heap **Program** 0x0000

Memory

### **Revisiting Functions: A Problem Arises**

- Now, consider functions.
- When we call a function, we need to remember where we were.
  - This is stored in the \$ra register.
  - But if we call a function twice, what happens to \$ra?
    - It is overwritten, and our first value in \$ra is lost.
    - This means after our second function is called, the first function will now be lost, and it will return *to itself*. (Refer to the previous slides)
- What are our strategies for remembering ra?

### Remembering RA

Bad Idea #1: Place it in another register

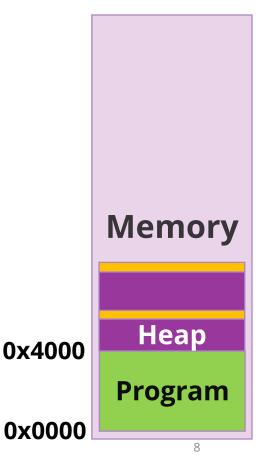
```
myFunction:
move t0, ra
# overwrites ra!
jal myOtherFunction
# it's ok though:
move ra, t0
ir ra
```

#### However:

- What if myOtherFunction uses t0?
- Ok, t0 isn't preserved, so let's use **s0**.
- Wait... **we** need to preserve **s0**...
- Where do we put that?? s1???
- Wait... we need to preserve s1!!
- We will run out of saved registers and we cannot trust unsaved registers. (other functions may overwrite them)
- Therefore, we need memory.

### Remembering RA

- We need memory. We have that *heap thing*.
- So can't we just allocate some on the heap?
- Sure can. But it is Bad Idea #2.
- What happens if that function allocates memory?
- And then calls another function.
- And then we return...
- And return from the first function...
- Leaving gaps in our memory!

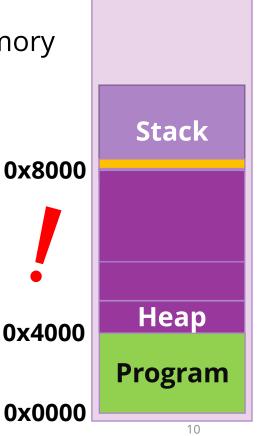


### Let's Design a Memory Layout (kinda)

- Our video editing application wants to use large, continuous memory regions.
  - Videos are big things! (Continuous memory makes things easier/faster... future courses will convince you.)
- We have very few registers, and need to remember \$ra
  - So, we need to place ra in memory to recall it before we jr ra
- However, placing it with other program memory creates gaps
  - This is very very trash!!
- How do we solve this.
  - Occam's Razor to the rescue... and it will create a very weird situation.
  - One that involves subtracting to allocate...

# **Solving our Problem: Step 1**

- How can we use memory, but not create gaps?
- Good [rational] Idea: Maintain two dynamic memory sections.
- We call our function.
- What happens if that function allocates memory?
- And then calls another function.
- And then we return...
- And return from the first function... WHEW! No gaps.
- (Ok, but now we start editing a LARGE video...)
  - Uh oh! We've lost our \$ra

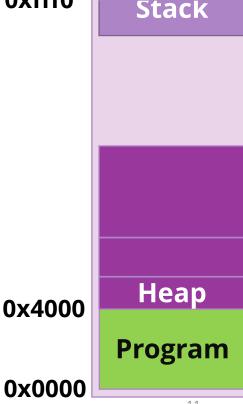


# **Solving our Problem: Step 2**

 Good [weird] Idea: Maintain two dynamic memory sections. One of which starts at the highest memory address. Allocate via **subtraction** (append to bottom)

0xfffc 0xfff0

- We call our function.
- What happens if that function allocates memory?
- And then calls another function.
- And then we return...
- And return from the first function... No gaps.
- As for our large memory case...
- It's fine! (only problem: running out of memory)
  - But, my goodness, you have a bigger problem, then.



# **Solving our Problem: Step 2**

 Good [weird] Idea: Maintain two dynamic memory sections. One of which starts at the highest memory address. Allocate via subtraction (append to bottom)

0xfffc 0xfff0

- We call our function. (subtract \$sp, store)
- What happens if that function allocates memory?
- And then calls another function. (sub, store)
- And then we return... (load, add to \$sp)
- And return from the first function... (load, add)
- Refer to the previous slides on the Stack with this knowledge in your mind.

0x4000

0x0000

Stack Heap **Program**