

Luis M. Pimentel

✉: lpimentel3@gatech.edu

☎: +1 (678) 768-2626

🌐: www.luismpimentel.com

United States Citizen

<i>Education</i>	Georgia Institute of Technology , Atlanta, GA <i>Master of Science</i> , Computer and Electrical Engineering	January 2022 - present GPA: 4.00/4.00
	Georgia Institute of Technology , Atlanta, GA <i>Bachelor of Science</i> , Computer Engineering, Minor in Robotics	August 2017 - December 2021 GPA: 3.71/4.00
	Georgia Tech Lorraine , Metz, France <i>Study Abroad Program</i>	August 2019 - December 2019
<i>Technical Skills</i>	Programming Languages: Python, C++, C, MATLAB. Robotics: ROS/ROS2, Gazebo, PX4-Autopilot Software: Linux, Git, PyTorch, Python ML & Scientific tools/libraries, Google Cloud Hardware: Robotics sensing technologies: camera, LIDAR, IMU; embedded systems and microcontrollers; strong electronics and prototyping skills Communication: L ^A T _E X, Jupyter, Git/Wiki documentation, design proposals, technical & research posters, technical & research writing	
<i>Selected Coursework</i>	Machine Learning: Math Foundations of Data Science, Machine Learning , Deep Learning, Statistical Machine Learning*, Probabilistic Graphical Models* Control Systems: Signals and Systems, Feedback Control Systems, Control System Design, Linear Systems and Controls* (IP), Networked Control and Multiagent Systems* (IP) Robotics: Robotics and Autonomy, Robotics and Perception, Computer Vision Other: Programming HW/SW Systems, Engineering Software Design, Digital Signals Processing, Digital Design * indicates graduate level; (IP) In Progress	
<i>Professional Experience</i>	Graduate Research & Development Intern Summer 2019, Summer 2020 - present Manager: Dr. Julie Parish, PI: Dr. Zahi Kakish	Sandia National Laboratories Albuquerque, NM
	* Designed and developed new multi-copter platforms with increased computational capabilities, and expanded the sensor suites for advanced autonomous flight. Contributed to establishing robotics infrastructure for an indoor multi-agent experimental test-bed. * Developed software infrastructure for performing physical and simulated experiments aiding in the research and development of autonomous algorithms. Aided in implementing several algorithms related to optimal control, path planning, trajectory generation, and intelligence-aided navigation. * Currently researching and developing multi-agent algorithms for advanced perception, navigation, and control using control using techniques from Control Systems and Deep Reinforcement Learning.	
	Undergrad Research & Development Intern Summer 2018 Manager/PI: Chris Roberts	Georgia Tech Research Institute Atlanta, GA
	* Designed and developed a custom communication system using four STM32 embedded systems. This system used a custom communications protocol to transmit/receive messages through radio frequencies. * Developed software applications to identify security vulnerabilities within the hardware devices and peripherals.	
<i>Research Experience & Projects</i>	Perception Software Lead Spring 2021 - Fall 2021 PI: Dr. Micheal E. West	Georgia Institute of Technology Atlanta, NM
	* Sponsored culminating design project with the task of designing an Autonomous Surface Vehicle (ASV) with the capability of eliminating plastic pollution in rivers. * Integrating autonomous capabilities of an ASV for plastic detection, localization, and autonomous navigation. Integrated an underwater stereo camera for plastic detection and localization using real-time deep learning based object detection algorithm and 3D point-cloud data.	

	Undergraduate Research, Special Topics Fall 2019 PI: Dr. Cedric Pradalier <ul style="list-style-type: none"> * Wrote a software driver for operating an autonomous 1/10 th scale racecar robot used for control and state estimation research. * Integrated the software and hardware components for state estimation through an Extended Kalman Filter using an RGBD camera, GPS, and IMU. 	The Dream Lab, Georgia Tech Lorraine Metz, France
	VIP Active Safety for Autonomous and Semi-Autonomous Vehicles Fall 2017 - Spring 2019 PI: Dr. Panagiotis Tsiotras <ul style="list-style-type: none"> * Managed students on the team in setting semester goals, tracking progress, and communicating progress to PI. * Built and maintained the hardware of three AutoRally platforms: 1/5th scale racecar robots used for research applications in autonomous control and perception. * Built ten 1/10th scale racecar robots and developed software applications for an autonomous navigation stack using ROS to implement SLAM, path planning, and trajectory generation in simulation and hardware using onboard sensors such as IMU, LIDAR, and stereo cameras. 	Georgia Institute of Technology Atlanta, GA
<i>Workshop Papers</i>	[W1] Scaling Multi-agent Reinforcement Learning via State Upsampling Luis Pimentel* , Rohan Paleja*, Zheyuan Wang, Esmail Seraj, James Pagan, and Matthew Gombolay In Proc. RSS Workshop on Scaling Robot Learning (RSS22-SRL), 2022	
<i>Leadership & Service</i>	Boxing Club at Georgia Tech: 2021 Founder and former President of Georgia Tech's first amateur college boxing team competing through USA Boxing and USIBA. Developed core club organization and operations, leading to growth of over 100 members within two semesters since founding. Organized team competition at the 2019 USIBA National Tournament in Syracuse, New York. Organized the 2020 USIBA National Tournament in Atlanta, GA, hosting over 20+ universities (cancelled due to COVID-19).	Fall 2018 - Spring
	Georgia Tech Eta Kappa Nu (HKN): International IEEE honor society where I am involved in social, corporate, and service events.	Spring 2021 - present
	Georgia Tech RoboJackets: Worked in the software development and integration of sensors for race cars used in autonomous racing competitions. Competed in the 2018 Sparkfun Autonomous Vehicle Challenge in Boulder, Colorado, and the 2018 International Autonomous Robot Racing Competition in Toronto, Canada.	Fall 2017 - Spring 2018
<i>Honors & Awards</i>	Sandia National Laboratories Employee Recognition Award Georgia Tech Tower Award Georgia Tech Best New Organization of the Year Award – Boxing Club 1st Place – Sparkfun AVC Speed Demons Competition (RoboJackets) Martin Marietta Scholarship GCAA Scholarship Hispanic Heritage Youth Award (Gold – Engineering) Hispanic Scholarship Fund Scholar	2021 2017-2020 2019 2018 2018 2018 2017 2017