ICPC Library | Ufes

Contents

```
1 C++
1.1 Template
1.2 Check Overflow

2 Divide and Conquer
2.1 Bisection Method
2.2 Ternary Search
2.3 Binary Search
3 Sorting
3.1 Merge Sort

4 Graph Algorithms
4.1 DFS
4.2 Strongly Connected Components
4.3 Edmonds-Karp
```

1 C++

1.1 Template

```
#include <bits/stdc++.h>
using namespace std;
#define fi first
#define se second
#define forn(i, n) for (int i = 0; i < (int)n; ++i)
#define for1(i, n) for (int i = 1: i \le (int)n: ++i)
#define fore(i, l, r) for (int i = (int)l; i <= (int)r; ++i)</pre>
#define ford(i, n) for (int i = (int)(n) - 1; i \ge 0; --i)
#define fored(i, l, r) for (int i = (int)r; i \ge (int)l; --i)
#define pb push_back
#define pf push_front
#define el '\n'
#define d(x) cout << #x << " " << x << el
#define ri(n) scanf("%d", &n)
#define sz(v) int(v.size())
#define all(v) v.begin(), v.end()
#define mset(x, y) memset(x, (y), sizeof(x));
typedef long long
                             ll:
typedef long double
                             ld:
typedef pair<int, int>
                             pii;
tvpedef pair<ll. ll>
                             pll:
typedef tuple<int, int, int> iii;
typedef vector<int>
                             vi:
typedef vector<pii>
                             vii:
typedef vector<ll>
                             vll:
typedef vector<ld>
                             vd:
const int INF = 0x3f3f3f3f3f:
const int MAX = 1e5 + 200;
const ld PI = acos(-1);
const ld EPS = 1e-9;
```

```
int dr[] = {1, -1, 0, 0, 1, -1, -1, 1};
int dc[] = {0, 0, 1, -1, 1, 1, -1, -1};

ostream& operator<<(ostream& os, const pii& pa) {
    return os << "(" << pa.fi << ", " << pa.se << ")";
}

int main() {
    ios_base::sync_with_stdio(false);
    cin.tie(NULL);
    cout.tie(NULL);
    cout << setprecision(20) << fixed;

    return 0;
}</pre>
```

1.2 Check Overflow

```
if (b > 0 && a > INFLL -b) //a+b vai dar overflow if (b < 0 && a < -INFLL -b) //a+b vai dar underflow if (b < 0 && a > INFLL+b) //a-b vai dar overflow if (b > 0 && a < -INFLL+b) //a-b vai dar underflow if (b > INFLL/a) //a*b vai dar overflow if (b < -INFLL/a) //a*b vai dar underflow if (b < -INFLL/a) //a*b vai dar underflow
```

2 Divide and Conquer

2.1 Bisection Method

```
// Bisection Method
// Very useful for finding roots of a function
// With 100 repetitions the value already converges.
// This implementation only works if the function in the range [lo, hi] has
    some
// zero.
//F(x)
        F(lo)
//
//
                             F(hi)
double bisection(double lo. double hi) {
    for (int i = 0; i < 100; i++) {
        double mid = (lo + hi) / 2;
        double F = f(mid): // Declare a function
        if (F > 0)
            lo = mid;
        else
            hi = mid;
```

```
}
return lo;
}
```

2.2 Ternary Search

```
// Ternary search
// Very useful for finding max/min values between interval
// The function on the interval must be unimodal (only 1 maximum)
// F(x)
// ^
                     Goal
//
//
//
//
//
//
                                  * F(r)
//
      * F(1)
double ternary_search(double l, double r) {
    double eps = 1e-9;
    while (r - l > eps) {
        double m1 = l + (r - l) / 3;
        double m2 = r - (r - 1) / 3;
        double f1 = f(m1);
        double f2 = f(m2);
        if (f1 < f2)
            l = m1;
        else
            r = m2;
    return f(l); // Return the maximum of f(x) in [l, r]
}
```

2.3 Binary Search

3 Sorting

3.1 Merge Sort

```
// Merge sort with inversion counter
int merge(int *arr, int *aux, int lo, int hi, int mid) {
    int inv = 0:
    for (int k = lo; k <= hi; k++) aux[k] = arr[k];</pre>
    int i = lo:
    int j = mid + 1;
    for (int k = lo; k <= hi; k++) {</pre>
        if (i > mid)
            arr[k] = aux[j++];
        else if (j > hi)
            arr[k] = aux[i++];
        else if (aux[j] < aux[i]) {</pre>
            arr[k] = aux[j++];
            inv += mid + 1 - i;
        } else
            arr[k] = aux[i++];
    return inv;
}
int mergesort(int *arr, int *aux, int lo, int hi) {
    int inv = 0;
    if (lo >= hi) return inv;
    int mid = lo + (hi - lo) / 2;
    inv += mergesort(arr, aux, lo, mid);
    inv += mergesort(arr, aux, mid + 1, hi);
    inv += merge(arr, aux, lo, hi, mid);
    return inv;
```

4 Graph Algorithms

4.1 DFS

4.2 Strongly Connected Components

```
// Tarjan's Algorithm
// Finding strongly connected components (Directed Graph)
int
vector<vi> adj;
٧i
           dfslow, dfsnum;
bool
           vis[VMAX];
int
           SCC. TIME:
stack<int> aux;
void tarjan_dfs(int s) {
    dfslow[s] = dfsnum[s] = ++TIME;
    aux.push(s);
    vis[s] = true;
    for (auto a : adj[s]) {
        if (!dfsnum[a]) tarjan_dfs(a);
        if (vis[a]) dfslow[s] = min(dfslow[s], dfslow[a]);
    if (dfslow[s] == dfsnum[s]) {
        SCC += 1;
        while (1) {
            int v = aux.top();
            aux.pop();
            vis[v] = 0:
            if (s == v) break;
}
void scc() {
          = stack<int>():
    dfslow = vi(V, 0);
    dfsnum = vi(V, 0);
    memset(vis, false, sizeof(vis));
    TIME = SCC = 0;
    for (int i = 0; i < V; i++) {
        if (!dfsnum[i]) tarjan_dfs(i);
}
```

4.3 Edmonds-Karp

```
// Edmonds-Karp Algorithm
// Min-Cut/Max-Flow problem
int
vector<vi> adi;
vector<vi> capacity;
int bfs(int s, int t, vi& parent) {
    fill(parent.begin(), parent.end(), -1);
    parent[s] = -2;
    queue<pair<int, int>> q;
    q.push({s, INF});
    while (!q.empty()) {
        int cur = q.front().first;
        int flow = q.front().second;
        q.pop();
        for (int next : adj[cur]) {
            if (parent[next] == -1 && capacity[cur][next]) {
                parent[next] = cur;
                int new_flow = min(flow, capacity[cur][next]);
                if (next == t) return new_flow;
                q.push({next, new_flow});
       }
    return 0;
int maxflow(int s, int t) {
    int flow = 0;
    vi parent(V);
    int new_flow;
    while ((new_flow = bfs(s, t, parent))) {
        flow += new_flow;
        int cur = t;
        while (cur != s) {
            int prev = parent[cur];
            capacity[prev][cur] -= new_flow;
            capacity[cur][prev] += new_flow;
            cur = prev;
    }
    return flow;
```