## #2 Assignment - CMPT 405

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#1 First, we draw the table with cost c of multiplying two matrices in the dimensions  $\{1 \times 1, 1 \times d, d \times 1, d \times d\}$ 

$m_1$	$m_2$	$m_{res}$	$\cos t$	
$1 \times 1$	$1 \times 1$	$1 \times 1$	1	
$1 \times 1$	$1 \times d$	$1 \times d$	d	
$1 \times d$	$d \times 1$	$1 \times 1$	d	
$1 \times d$	$d \times d$	$1 \times d$	$d^2$	
$d \times 1$	$1 \times 1$	$d \times 1$	d	
$d \times 1$	$1 \times d$	$d \times d$	$d^2$	
$d \times d$	$d \times 1$	$d \times 1$	$d^2$	
$d \times d$	$d \times d$	$d \times d$	$d^3$	

## Intuition:

The algorithm should always choose the lowest possible cost  $c \in \{1, d, d^2, d^3\}$ because according to the table above, for any two given fixed matrices  $m_1, m_2$ in a formula  $\varphi$ , where  $\varphi$  is the formula multiplying n matrices with dimensions  $\{1 \times 1, 1 \times d, d \times 1, d \times d\}$ , if it chooses the lowest cost operation, it will also generate a matrix  $m_{res}$  that, by multiplying another (possible) matrix  $m_3$ , will have cost  $c' \ge c$ . If c' = c, we keep the same cost, which is good, since we picked the lowest cost c at first. If c' > c, then, by the table above, c' = cd, which is also the lowest possible cost. As a mean of contradiction, if the algorithm chooses a matrix for which c' > cd, then the matrix would have non-compatible dimensions. Therefore, it is important that formula  $\varphi$  be a valid formula. Because we know that  $\varphi$  is always valid, we know that we can group (or parenthesize) the matrices by their dimensions and you will see that it can be done in linear time. The approach of the algorithm is the that with a stack S, every time it comes across a matrix  $m_i = (1 \times x), x \in \{1, d\}, 1 \le i \le n$ , it pushes i onto S, as the idea of the algorithm is to prioritize low costs. At the end, it subdivides  $\varphi$ in ascending order subformulas  $\varphi'=\varphi'_1,...\varphi'_m$  (recall that we push onto S the indexes of  $(1 \times x)$  matrices). For each  $\varphi'_i \in \varphi'$ , we left-associate the matrices inside them. See the example and algorithm below:

$$\varphi = (d \times 1)(1 \times 1)(1 \times d)(d \times 1)(1 \times 1)$$

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\varphi' = \boxed{\begin{array}{c|c} 1 & 2 & 1 \\ \hline (d \times 1) & (1 \times 1) & (1 \times d)(d \times 1) & (1 \times 1) \\ \hline res = (d \times 1) \left( (1 \times 1) \left( \left( (1 \times d)(d \times 1) \right) (1 \times 1) \right) \right) \end{array}}
Algorithm:
Input: \varphi, n
    Make stack S
    for i from 1 to n do
           (row, col) \leftarrow \text{matrix}_i
          if row = 1 then
                push i onto S
          end if
    end for
    \varphi'=\varphi
    while S \neq \emptyset do
          t \leftarrow \text{ pop } S
          v \leftarrow \text{top } S \text{ // check top of } S \text{ without popping}
          diff \leftarrow t - v
          if diff > 0 then
                 \varphi' \leftarrow \text{break } \varphi' \text{ and add parenthesis at pos } v
                diff \leftarrow diff - 1
                 while diff > 0 do
                       \varphi' \leftarrow \text{break } \varphi' and add parenthesis by left-associating extraneous
                            matrices
                       diff \leftarrow diff - 1
                end while
          end if
    end while
    return \varphi'
#2
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## #3

Definition: Let A be an array with size n+1 and s be a sequence of integers. Initialize  $A[0] = -\infty$  and for  $1 \le i \le n$ , define A[i] as the largest contiguous subsequence sum in s after an iteration i. At the end, the largest possible sum will then be the highest element in A.

Recurrence:

$$A[i] = \begin{cases} -\infty & \text{if } i = 0 \\ \max \{A[i-1] + s[i], s[i]\} & \text{otherwise} \end{cases}$$

Algorithm: **Input:** *s*, *n* 

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Make array A of size n+1
A[0] \leftarrow -\infty
insert none in the index 0 of s // make |s| = |A| for the loop
best_i \leftarrow 0
for i from 1 to n do
    A[i] \leftarrow \max \{A[i-1] + s[i], s[i]\}
    if A[i] > A[i-1] then
        best_i \leftarrow i
    end if
end for
s' \leftarrow \emptyset // find best subsequence index set s'
while A[best_i] = A[best_i - 1] + s[best_i] do
    s' \leftarrow s' \cup \{best_i\}
    best_i \leftarrow best_i - 1
end while
s' \leftarrow s' \cup best_i // add the lowest index of subsequence
return s'
```

Demonstration:

s = [	none	-2	11	-4	13	-5	-2
A =	$-\infty$	-2	11	7	20	15	13
s' =	$\{2, 3, 4\}$	}					

At the end, as s' demonstrates, we will have the range 2..4 comprising the largest possible sum of a contiguous subsequence in s.

Running time: The running time of the loops are O(n). All operations on A (inside the loops) are constant (O(1)) and therefore the total running time of the algorithm is O(n).

## #4

The idea of the problem is to take any node on the tree T, consider it as a root and then do a **postorder traversal** applying a recurrence similar do the one on question #3. Consider all vertices are labelled  $v_1, ..., v_i, ..., v_n, 1 \le i \le n$ . Let A be an array that keeps the highest sum of a subtree with root on vertex v. As we are doing a postorder traversal, when we compute  $A[v_p]$ ,  $v_p$  being a parent vertex, we will have the sum of the children already computed. We only sum over  $A[v_c]$ , for all c children of  $v_p$ , if  $A[v_c] > 0$  (call it  $A[v_c+]$ ). The recurrence and algorithm would then be:

$$A[v_i] = \left\{ \max \left\{ \sum_{c^+ \in children(v_i)} A[v_c^+] + w(v_i), w(v_i) \right\} \right\}$$

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Algorithm:  \begin{split} \textbf{Input:} & \ \textbf{Input:} & \ \textbf{T} \\ & \ \textbf{Make array } A \text{ of size } n \\ & \ \textit{best}_i \leftarrow 0 \ / / \ v_{best_i} \ \textit{will be the root of } H \\ & \ \textbf{for each } v_i \in T_{postorder} \ \textbf{do} \\ & \ A[v_i] \leftarrow \max \left\{ \ \sum_{c^+ \in children(v_i)} A[v_c^+] + w(v_i), w(v_i) \ \right\} \\ & \ \textbf{if } A[v_i] > A[best_i] \ \textbf{then} \\ & \ \textit{best}_i \leftarrow i \\ & \ \textbf{end if} \\ & \ \textbf{end for} \\ & \ \textit{H} \leftarrow \text{Recursively do } (v_i, \text{ all } v_c^+ \in \text{children}(v_i)) \} \ \text{starting on root } A[v_{best_i}] \\ & \ \textbf{return } H, A[v_{best_i}] \end{split}
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