

NachOS如何創造一個Thread

- 我們把NachOS創造Thread的步驟可以分為三個流程說明
 1. **Kernel Part**
 2. **Thread Part**
 3. **AddrSpace Part**
-

Kernel Part

- Kernel::Kernel()
 - main.cc第250行new一個kernel時執行
 - kernel的建構子
 - 當收到-e參數時把要執行的檔案加入execfile裡面
 - 執行完畢後回到main.cc繼續執行

```
1 else if (strcmp(argv[i], "-e") == 0) {
2     execfile[++execfileNum]= argv[++i];
3     cout << execfile[execfileNum] << "\n";
4 }
```

- Kernel::ExecAll()
 - main.cc第288行call入
 - 用一個for迴圈把exefile裡面每一個元素都call一次Exec()去執行

```
1 for (int i=1;i<=execfileNum;i++) {
2     int a = Exec(execfile[i]);
3 }
4 currentThread->Finish();
```

- 完成後用currentThread->Finish()把目前占用CPU的Thread free掉並call Sleep來觸發Switch做context switch
-

- Kernel::Exec(char* name)

```
1 t[threadNum] = new Thread(name, threadNum);
2 t[threadNum]->space = new AddrSpace(usedPhysicalPage);
3 t[threadNum]->Fork((VoidFunctionPtr) &ForkExecute, (void *)t[threadNum]);
4 threadNum++;
5
6 return threadNum-1;
```

- 這個function先new一個Thread object(定義在Thread.cc)
- 接著透過AddrSpace.cc幫這個thread allocate一些memory以及創建pageTable
- 接著call thread.cc 的fork，把kernel::ForkExecute傳進Thread::Fork內
- Thread::Fork幫傳進來的function allocate一塊execution stack，並把Thread放進Ready-queue裡面等待執行
- Kernel::ForkExecute內又call了AddrSpace::Execute
- AddrSpace::Execute先把page table load進kernel，再call kernel->machine->Run()
- kernel->machine->Run()把kernel->currentThread設成傳進來的Thread

Thread Part

- 在NachOS中Process等於Thread
- Thread.cc定義了在NachOS中一個Thread是如何被創造與控制的
- 在這邊我們只說明從創建Thread到把它放進Ready-queue會使用到的function，其他像是Yield或是Sleep這些用來change Thread state以handle context switch或是interrupt的function就沒有說明
- Thread::Thread(char* threadName, int threadID)

```
1 Thread::Thread(char* threadName, int threadID)
2 {
3     ID = threadID;
4     name = threadName;
5     stackTop = NULL;
6     stack = NULL;
7     status = JUST_CREATED;
8     for (int i = 0; i < MachineStateSize; i++) {
9         machineState[i] = NULL;
10    }
11    space = NULL;
12 }
```

- Thread的建構子只先初始化Thread Control Block的一些設定值，像是ID以及thread就回到kernel::Exec了

- Thread::Fork(VoidFunctionPtr func, void *arg)

```

1 Thread::Fork(VoidFunctionPtr func, void *arg)
2 {
3     Interrupt *interrupt = kernel->interrupt;
4     Scheduler *scheduler = kernel->scheduler;
5     IntStatus oldLevel;
6
7     DEBUG(dbgThread, "Forking thread: " << name
8           << " f(a): " << (int) func << " " << arg);
9     StackAllocate(func, arg);
10
11     oldLevel = interrupt->SetLevel(IntOff);
12     scheduler->ReadyToRun(this);
13     (void) interrupt->SetLevel(oldLevel);
14 }

```

- Thread::Fork讓被傳進來的function(kernel::ForkExecute)可以和call Thread::Fork的function可以work concurrently
- Thread在這裡被放進Ready-queue內排程準備執行
- Interrupt會先被關掉，等Thread被放進scheduler的Ready-queue後才設回原本的狀態
- 被傳進來的ForkExecute會去call AddrSpace::Load，準備創建pageTable並把thread的page搬到MainMemory裡面來

AddrSpace Part

- AddrSpace.cc定義了我們如何為每個Thread allocate pageTable以及如何將page load到physical memory裡面
- kernel::ForkExecute(Thread *t)

```

1 void ForkExecute(Thread *t)
2 {
3     if ( !t->space->Load(t->getName()) ) {
4         return;          // executable not found
5     }
6
7     t->space->Execute(t->getName());
8 }

```

- 這個function先把Thread t load到MainMemory內
- 然後call AddrSpace::Execute執行它

- AddrSpace::Load(char* fileName)

```

1 AddrSpace::Load(char *fileName)
2 {
3     OpenFile *executable = kernel->fileSystem->Open(fileName);
4     NoffHeader noffH;
5     unsigned int size;
6
7     if (executable == NULL) {
8         cerr << "Unable to open file " << fileName << "\n";
9         return FALSE;
10    }
11
12    executable->ReadAt((char *)&noffH, sizeof(noffH), 0);
13    if ((noffH.noffMagic != NOFFMAGIC) &&
14        (WordToHost(noffH.noffMagic) == NOFFMAGIC))
15        SwapHeader(&noffH);
16
17    ASSERT(noffH.noffMagic == NOFFMAGIC);

```

- 這個function先用file system把在disk上的thread資料打開，並把它Read進新創立的NoffHeader物件
- 接著做一些endian的轉換
- NoffHeader object使用segmentation，分成三個segment
 1. Code
 2. initData
 3. readonlyData或uninitData
- NoffHeader定義NachOS的object code format

```

1 # ifdef RDATA
2 // how big is address space?
3 size = noffH.code.size + noffH.readonlyData.size + noffH.initData.size
4       + noffH.uninitData.size + UserStackSize;
5                                     // we need to increase the size
6                                     // to leave room for the stack
7 #else
8 // how big is address space?
9     size = noffH.code.size + noffH.initData.size + noffH.uninitData.size
10          + UserStackSize;    // we need to increase the size
11                              // to leave room for the stack
12 #endif
13 numPages = divRoundUp(size, PageSize);
14 size = numPages * PageSize;
15
16 ASSERT(numPages <= NumPhysPages);    // check we're not trying
17                                     // to run anything too big --
18                                     // at least until we have
19                                     // virtual memory
20
21 DEBUG(dbgAddr, "Initializing address space: " << numPages << ", " << size);

```

- 然後依據是不是ReadOnly data來計算整個thread的大小，再除以PageSize就可以知道需要多少page

```

1 //handle code segment
2 if (code_size > 0) {
3     DEBUG(dbgAddr, "Initializing code segment.");
4     DEBUG(dbgAddr, noffH.code.virtualAddr << " ", " << noffH.code.size);
5
6     while(code_size > 0) {
7         // cout << "\n[!] code_size remain: " << code_size << endl;
8         exception = Translate(virtual_addr, &phyaddr, 0);
9         // cout << "[!] code_segment exception: " << exception << endl << "[!]phyaddr: "
10        << phyaddr <<endl;
11        if (code_size <= PageSize) {
12            executable->ReadAt(&(kernel->machine->mainMemory[phyaddr]), code_size,
13            infile_addr);
14            code_size = 0;
15        } else {
16            executable->ReadAt(&(kernel->machine->mainMemory[phyaddr]), PageSize,
17            infile_addr);
18            code_size -= PageSize;
19            virtual_addr += PageSize;
20            infile_addr += PageSize;
21        }
22    }
23 }
24
25 // handle data segment
26 code_size = noffH.initData.size;
27 virtual_addr = noffH.initData.virtualAddr;
28 infile_addr = noffH.initData.inFileAddr;
29 if (code_size > 0) {
30     DEBUG(dbgAddr, "Initializing data segment.");
31     DEBUG(dbgAddr, noffH.initData.virtualAddr << " ", " << noffH.initData.size);
32     while(code_size > 0) {
33         //cout << "[!] data_size remain: " << code_size << endl;
34         exception = Translate(virtual_addr, &phyaddr, 1);
35         // cout << "[!!]data_segment exception: " << exception << endl;
36         if (code_size < PageSize) {
37             executable->ReadAt(&(kernel->machine->mainMemory[phyaddr]), code_size,
38             infile_addr);
39             break;
40         } else {
41             executable->ReadAt(&(kernel->machine->mainMemory[phyaddr]), PageSize,
42             infile_addr);
43             code_size -= PageSize;
44             virtual_addr += PageSize;
45             infile_addr += PageSize;
46         }
47     }
48 }
49
50 #ifdef RDATA
51 code_size = noffH.readonlyData.size;
52 virtual_addr = noffH.readonlyData.virtualAddr;
53 infile_addr = noffH.readonlyData.inFileAddr;

```

```

49
50 if (code_size > 0) {
51     DEBUG(dbgAddr, "Initializing read only data segment.");
52     DEBUG(dbgAddr, noffH.readonlyData.virtualAddr << " , " << noffH.readonlyData.size);
53     while (code_size > 0) {
54         //cout << "[!] RDATA_size remain: " << code_size << endl;
55         exception = Translate(virtual_addr , &phyaddr ,0);
56         // cout << "[!!]RDATA_segment exception: " << exception << endl;
57         if (code_size < PageSize) {
58             executable->ReadAt(&(kernel->machine->mainMemory[phyaddr]), code_size,
infile_addr);
59             break;
60         } else {
61             executable->ReadAt(&(kernel->machine->mainMemory[phyaddr]), PageSize,
infile_addr);
62             code_size -= PageSize;
63             virtual_addr += PageSize;
64             infile_addr += PageSize;
65         }
66     }
67 }
68 #endif

```

- 接著把已經讀進thread data的NoffHeader依照它內部的結構一個部分一個部分的load到MainMemory裡面
- 關於Translate以及pageTable如何實作我們放在Report部分
- 最後再把開起來的檔案關掉

- AddrSpace::Execute(char* fileName)

```

1 AddrSpace::Execute(char* fileName)
2 {
3
4     kernel->currentThread->space = this;
5
6     this->InitRegisters();      // set the initial register values
7     this->RestoreState();      // load page table register
8
9     kernel->machine->Run();      // jump to the user program
10
11     ASSERTNOTREACHED();        // machine->Run never returns;
12                                // the address space exits
13                                // by doing the syscall "exit"
14 }

```

- 這個function先把currentThread的AddrSpace設成自己
 - 然後修改machine裡面的Program Counter與pageTable
 - 接著開始執行Thread
 - 因為kernel->machine->Run()不會return回來，所以在call了Run之後要放一個ASSERTNOTREACHED()來偵測是不是執行出了問題讓Run return回來了
-

2017OSteam19 MP2 Report

kernel.h

我們在public的地方，新增一個可以紀錄frame有無被使用過的array。

```
1 bool    usedPhysicalPage[NumPhysPages];
2
```

[kernel.cc](#)

接著將原本的AddrSpace()改為AddrSpace(usedPhysicalPage) 傳入frame的資訊來實作multiprogramming。

```
1 int Kernel::Exec(char* name)
2 {
3     t[threadNum] = new Thread(name, threadNum);
4     t[threadNum]->space = new AddrSpace(usedPhysicalPage);
5     t[threadNum]->Fork((VoidFunctionPtr) &ForkExecute, (void *)t[threadNum]);
6     threadNum++;
7
8     return threadNum-1;
9
```

addrspace.h

將constructor改成可以接usedPhysicalPage指標的參數，然後新增一個used指標。

```
1 AddrSpace(bool *usedPhysicalPage);
2 bool *used;
3
```

[addrspace.cc](#)

用used指標指到剛剛在kernel.h所maintain的array，如此一來thread才知道有哪些frame可以用。原本是在這邊做address mapping，但是我們將它改到Load(char* filename)再做。因為原本是一個thread就佔據整個physical memory，如此一來就無法實作multiprogramming。所以要等到算出thread所佔的page數後再來mapping。

```
1 AddrSpace::AddrSpace(bool *usedPhysicalPage)
2 {
3     used = usedPhysicalPage;
4 }
5
```

假如thread要被free掉的時候，將不用的frame改為false，釋放空間出來，並且將Pagetable delete掉。

```

1 AddrSpace::~AddrSpace()
2 {
3     for (int i = 0; i < NumPhysPages; i++) {
4         used[pageTable[i].physicalPage] = false;
5     }
6     delete pageTable;
7 }
8

```

這邊一開始先create一個pagetable。接著我們改變了6~9行的code。先用numPages的for loop判斷需要給到幾個pages，再用while loop去尋找到可以使用的frame將它改為TRUE，然後將這個資訊給pagetable，把它紀錄下來。最後再紀錄下這個page的 valid、use、dirty、readonly的資訊。

page table

virtualPage	physicalPage	valid	use	dirty	readOnly
i	find_empty_page	TRUE	False	False	False

```

1  pageTable = new TranslationEntry[numPages];
2  int find_empty_page = 0;
3      // cout << "Pages needed: " << numPages << endl;
4      for (int i = 0; i < numPages; i++) {
5          pageTable[i].virtualPage = i;    // for now, virt page # = phys page #
6          while(used[find_empty_page] == TRUE) {
7              find_empty_page ++;
8          }
9          used[find_empty_page] = TRUE;
10         pageTable[i].physicalPage = find_empty_page;
11         pageTable[i].valid = TRUE;
12         pageTable[i].use = FALSE;
13         pageTable[i].dirty = FALSE;
14         pageTable[i].readOnly = FALSE;
15     }
16

```

我們將noffH的資料結構傳到我們設的變數裡面，方便programming。

```

1      ExceptionType exception;
2      unsigned int code_size = noffH.code.size;
3      unsigned int virtual_addr = noffH.code.virtualAddr;
4      unsigned int infile_addr = noffH.code.inFileAddr;
5      unsigned int phyaddr = 0;
6

```


最後是將page做translate寫到memory的部分。將thread的3個 segment用page為單位一個一個寫回memory。而physical address則是Translate這個function來決定，它會去查pagetable來把virtual address對應的physical address算出來。

再來是將寫到memory的size分成兩種情況:

1. size比pagesize還小的
2. size可以用一個以上pagesize來表示

如果比pagesize小就傳剩下的size進ReadAt就好，如果比較大就以pagesize為單位來切，切到剩下比pagesize小就用 **1.** 的情況解決。

然後每次做完一次translate都要更新 code_size、virtual_addr、infile_addr。最後用code_size來判斷是否做完所有的translate。

```
1 //handle code segment
2 if (code_size > 0) {
3     DEBUG(dbgAddr, "Initializing code segment.");
4     DEBUG(dbgAddr, noffH.code.virtualAddr << ", " << noffH.code.size);
5
6     while(code_size > 0) {
7         // cout << "\n[!] code_size remain: " << code_size << endl;
8         exception = Translate(virtual_addr, &phyaddr, 0);
9         // cout << "[!] code_segment exception: " << exception << endl << "[!]phyaddr: "
<< phyaddr <<endl;
10        if (code_size <= PageSize) {
11            executable->ReadAt(&(kernel->machine->mainMemory[phyaddr]), code_size,
infile_addr);
12            code_size = 0;
13        } else {
14            executable->ReadAt(&(kernel->machine->mainMemory[phyaddr]), PageSize,
infile_addr);
15            code_size -= PageSize;
16            virtual_addr += PageSize;
17            infile_addr += PageSize;
18        }
19    }
20 }
21
```

Translate

vpn: 算出第幾個virtual pagetable **offset:** 算出offset

把pte拿去指向pagetable[vpn]，再拿pfn紀錄放在pagetable的物理Page。然後再利用paddr = pfn*Pagesize + offset算出實體位址，這樣就translate完成了。

```

1  ExceptionType
2  AddrSpace::Translate(unsigned int vaddr, unsigned int *paddr, int isReadWrite)
3  {
4      TranslationEntry *pte;
5      int                pfn;
6      unsigned int       vpn    = vaddr / PageSize;
7      unsigned int       offset = vaddr % PageSize;
8      //cout << "[!] Vpn: " << vpn << " numpages: " << numPages << endl;
9      if(vpn >= numPages) {
10         return AddressErrorException;
11     }
12
13     pte = &pageTable[vpn];
14     if(isReadWrite && pte->readOnly) {
15         return ReadOnlyException;
16     }
17
18     pfn = pte->physicalPage;
19     // if the pageFrame is too big, there is something really wrong!
20     // An invalid translation was loaded into the page table or TLB.
21     if (pfn >= NumPhysPages) {
22         DEBUG(dbgAddr, "Illegal physical page " << pfn);
23         return BusErrorException;
24     }
25
26     pte->use = TRUE;          // set the use, dirty bits
27
28     if(isReadWrite)
29         pte->dirty = TRUE;
30
31     *paddr = pfn*PageSize + offset;
32     cout << "physical page: " << pfn << ", " << "Mainmemory: " << *paddr << endl;
33     ASSERT((*paddr < MemorySize));
34
35     //cerr << " -- AddrSpace::Translate(): vaddr: " << vaddr <<
36     // " ", paddr: " << *paddr << "\n";
37
38     return NoException;
39 }
40

```

initialData 與上面相同

```

1 // handle data segment
2 code_size = noffH.initData.size;
3 virtual_addr = noffH.initData.virtualAddr;
4 infile_addr = noffH.initData.inFileAddr;
5 if (code_size > 0) {
6     DEBUG(dbgAddr, "Initializing data segment.");
7     DEBUG(dbgAddr, noffH.initData.virtualAddr << ", " << noffH.initData.size);
8     while(code_size > 0) {
9         //cout << "[!] data_size remain: " << code_size << endl;
10        exception = Translate(virtual_addr, &phyaddr, 1);
11        // cout << "[!!]data_segment exception: " << exception << endl;
12        if (code_size < PageSize) {
13            executable->ReadAt(&(kernel->machine->mainMemory[phyaddr]), code_size,
infile_addr);
14            break;
15        } else {
16            executable->ReadAt(&(kernel->machine->mainMemory[phyaddr]), PageSize,
infile_addr);
17            code_size -= PageSize;
18            virtual_addr += PageSize;
19            infile_addr += PageSize;
20        }
21    }
22 }
23

```

readonly 與上面相同

```

1  #ifdef RDATA
2      code_size = noffH.readonlyData.size;
3      virtual_addr = noffH.readonlyData.virtualAddr;
4      infile_addr = noffH.readonlyData.inFileAddr;
5
6      if (code_size > 0) {
7          DEBUG(dbgAddr, "Initializing read only data segment.");
8          DEBUG(dbgAddr, noffH.readonlyData.virtualAddr << ", " << noffH.readonlyData.size);
9          while (code_size > 0) {
10             //cout << "[!] RDATA_size remain: " << code_size << endl;
11             exception = Translate(virtual_addr , &phyaddr ,0);
12             // cout << "[!!]RDATA_segment exception: " << exception << endl;
13             if (code_size < PageSize) {
14                 executable->ReadAt(&(kernel->machine->mainMemory[phyaddr]), code_size,
infile_addr);
15                 break;
16             } else {
17                 executable->ReadAt(&(kernel->machine->mainMemory[phyaddr]), PageSize,
infile_addr);
18                 code_size -= PageSize;
19                 virtual_addr += PageSize;
20                 infile_addr += PageSize;
21             }
22         }
23     }
24

```

Group Contribution

陳麒懋: trace code , code report , debugging 鍾昀諳: trace code , coding , trace report , debugging