

Compatibility check for velocity sensors

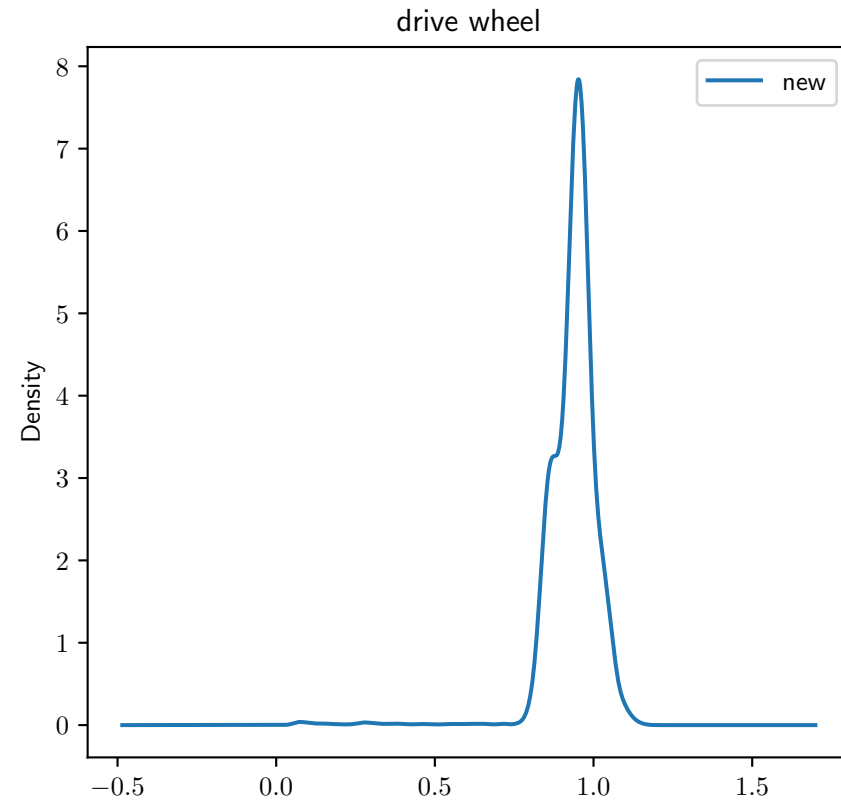
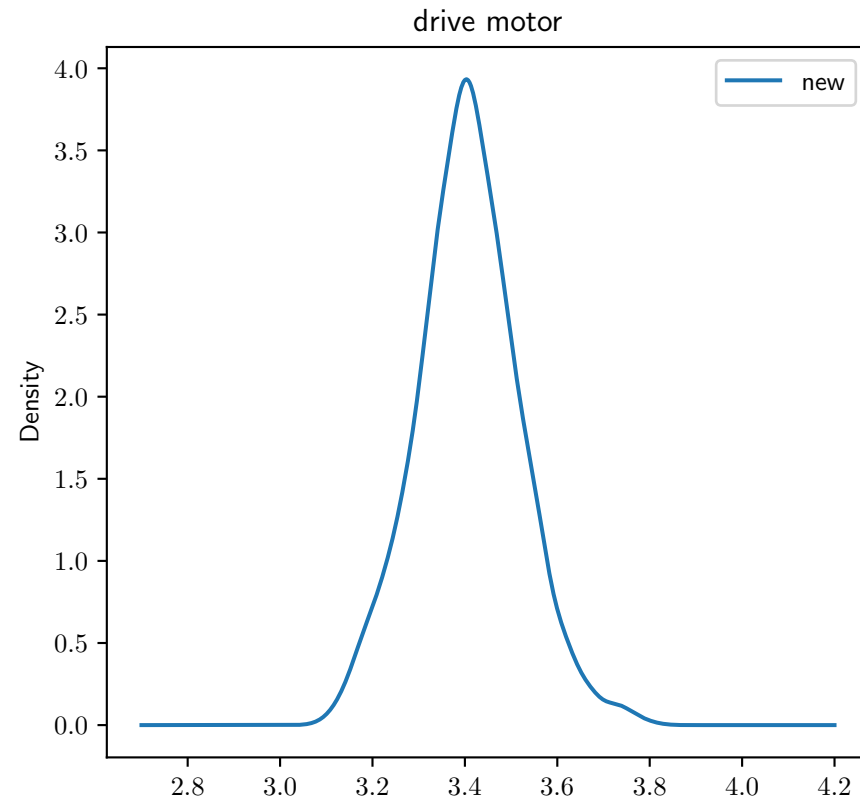
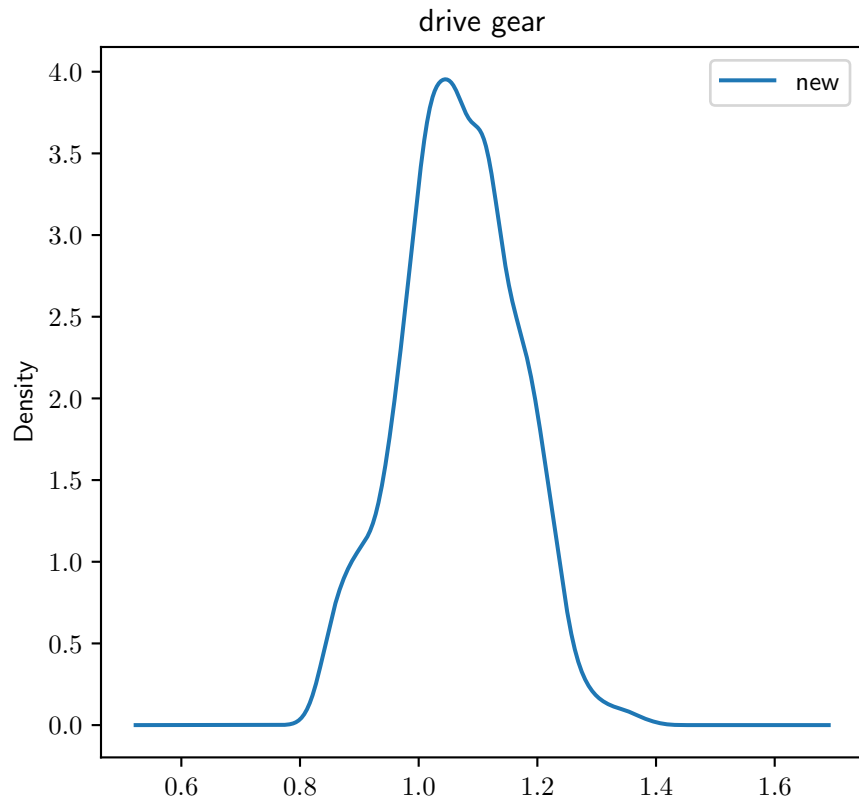
New data: from 2019-04-01 until 2019-05-01

Referent data: referent data

Velocity sensors

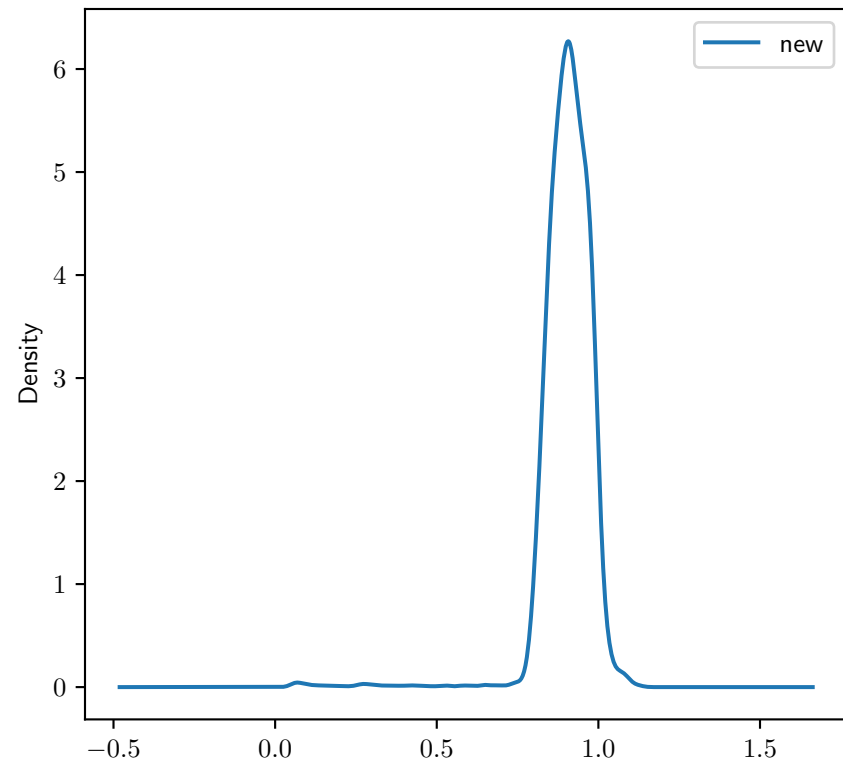
<div>drive gear</div> <div>$\mu_{ref} = \text{NA}$ $\sigma_{ref} = \text{NA}$ $\sigma^2_{ref} = \text{NA}$ $\mu_{new} = \text{NA}$ $\sigma_{new} = \text{NA}$ $\sigma^2_{new} = \text{NA}$ $good_{cnt}/all_{cnt}$ NA / NA = NA</div> <div>NO DATA</div>	<div>drive motor</div> <div>$\mu_{ref} = \text{NA}$ $\sigma_{ref} = \text{NA}$ $\sigma^2_{ref} = \text{NA}$ $\mu_{new} = \text{NA}$ $\sigma_{new} = \text{NA}$ $\sigma^2_{new} = \text{NA}$ $good_{cnt}/all_{cnt}$ NA / NA = NA</div> <div>NO DATA</div>	<div>drive wheel</div> <div>$\mu_{ref} = \text{NA}$ $\sigma_{ref} = \text{NA}$ $\sigma^2_{ref} = \text{NA}$ $\mu_{new} = \text{NA}$ $\sigma_{new} = \text{NA}$ $\sigma^2_{new} = \text{NA}$ $good_{cnt}/all_{cnt}$ NA / NA = NA</div> <div>NO DATA</div>	<div>idle wheel</div> <div>$\mu_{ref} = \text{NA}$ $\sigma_{ref} = \text{NA}$ $\sigma^2_{ref} = \text{NA}$ $\mu_{new} = \text{NA}$ $\sigma_{new} = \text{NA}$ $\sigma^2_{new} = \text{NA}$ $good_{cnt}/all_{cnt}$ NA / NA = NA</div> <div>NO DATA</div>	<div>lifting gear</div> <div>$\mu_{ref} = \text{NA}$ $\sigma_{ref} = \text{NA}$ $\sigma^2_{ref} = \text{NA}$ $\mu_{new} = \text{NA}$ $\sigma_{new} = \text{NA}$ $\sigma^2_{new} = \text{NA}$ $good_{cnt}/all_{cnt}$ NA / NA = NA</div> <div>NO DATA</div>	<div>lifting motor</div> <div>$\mu_{ref} = \text{NA}$ $\sigma_{ref} = \text{NA}$ $\sigma^2_{ref} = \text{NA}$ $\mu_{new} = \text{NA}$ $\sigma_{new} = \text{NA}$ $\sigma^2_{new} = \text{NA}$ $good_{cnt}/all_{cnt}$ NA / NA = NA</div> <div>NO DATA</div>
--	---	---	--	--	---

Distribution for drive sensors (velocity)

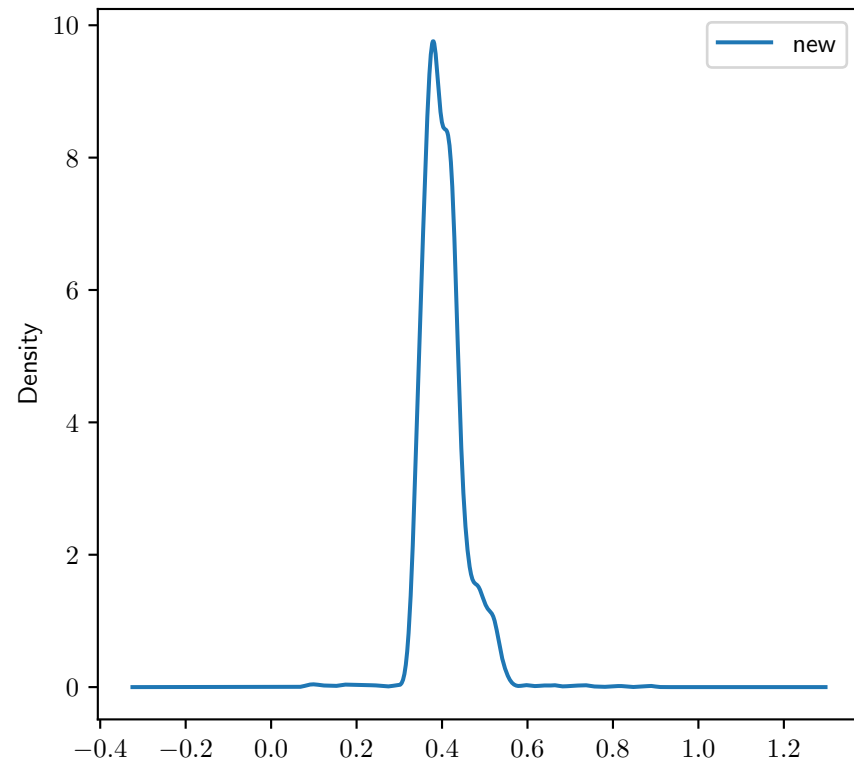


Distribution for other sensors (velocity)

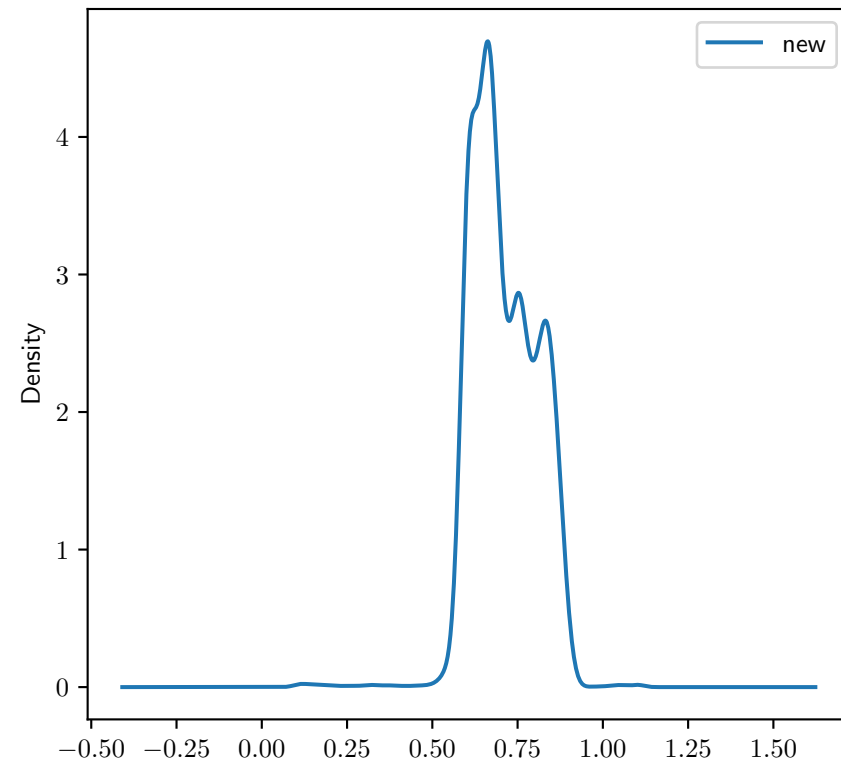
idle wheel



lifting gear



lifting motor



Compatibility check for acceleration sensors

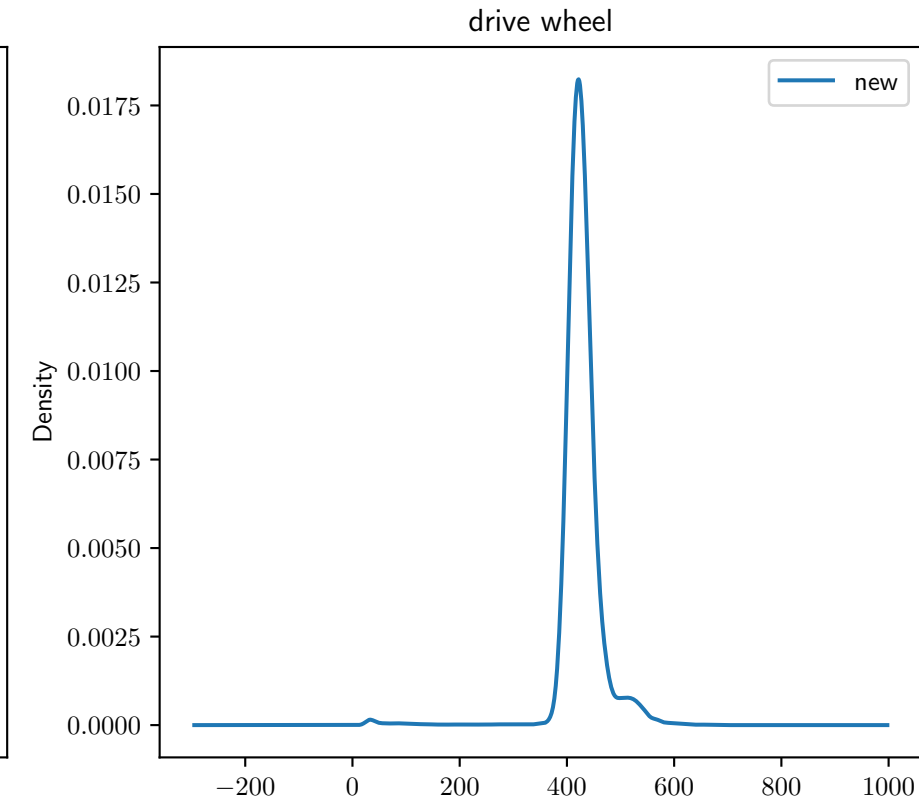
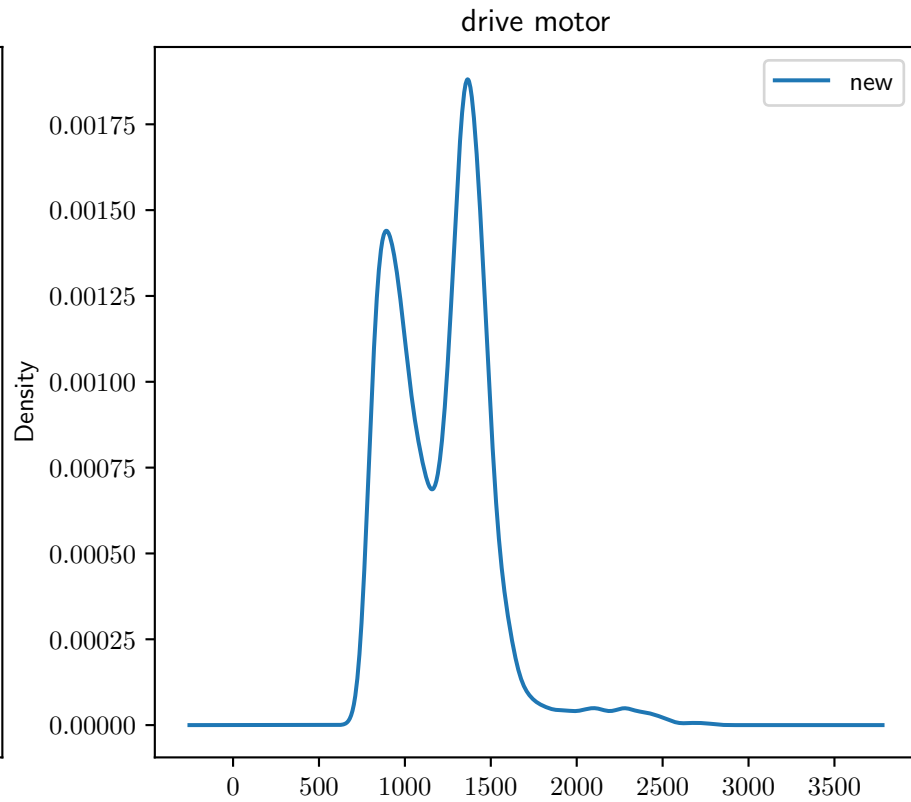
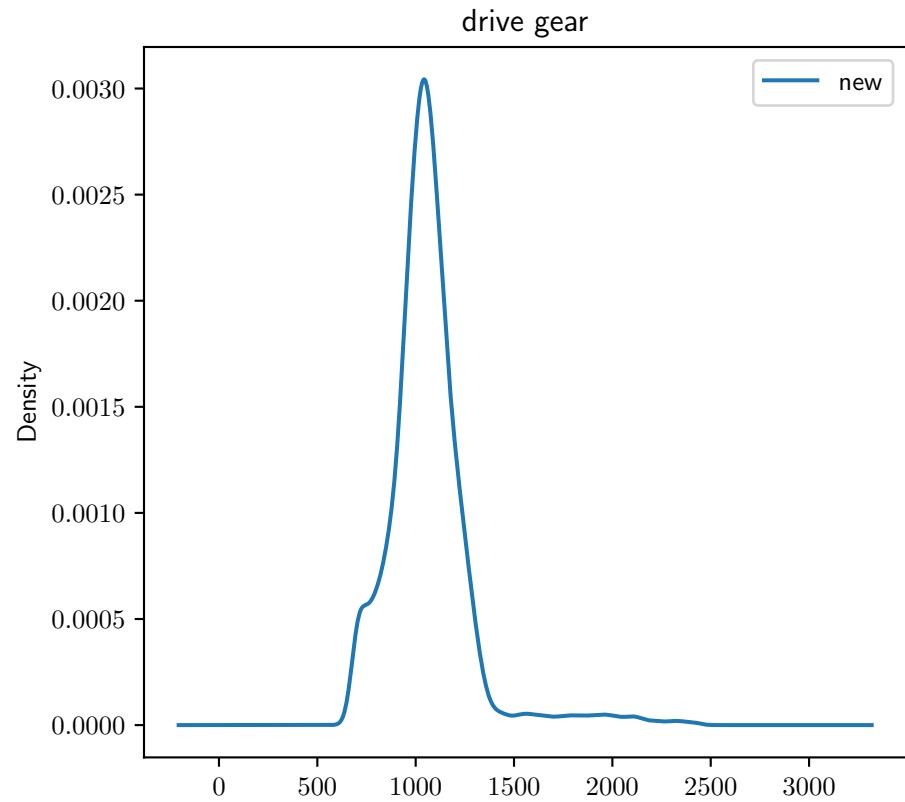
New data: from 2019-04-01 until 2019-05-01

Referent data: referent data

Acceleration sensors

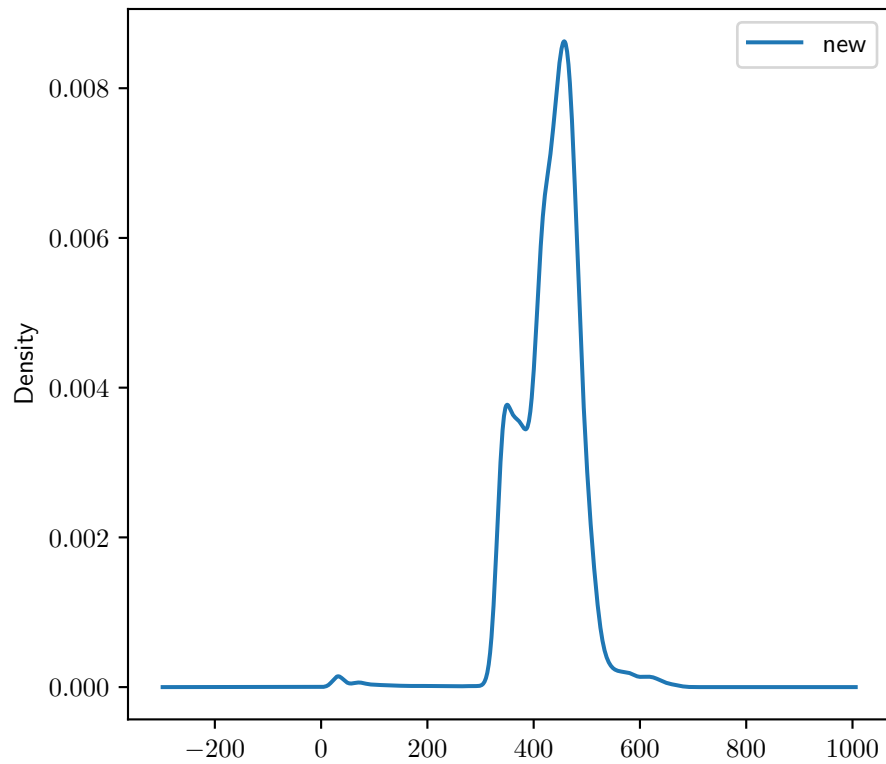
<div>drive gear</div> <div>$\mu_{ref} = \text{NA}$ $\sigma_{ref} = \text{NA}$ $\sigma^2_{ref} = \text{NA}$ $\mu_{new} = \text{NA}$ $\sigma_{new} = \text{NA}$ $\sigma^2_{new} = \text{NA}$ $good_{cnt}/all_{cnt}$ NA / NA = NA</div> <div>NO DATA</div>	<div>drive motor</div> <div>$\mu_{ref} = \text{NA}$ $\sigma_{ref} = \text{NA}$ $\sigma^2_{ref} = \text{NA}$ $\mu_{new} = \text{NA}$ $\sigma_{new} = \text{NA}$ $\sigma^2_{new} = \text{NA}$ $good_{cnt}/all_{cnt}$ NA / NA = NA</div> <div>NO DATA</div>	<div>drive wheel</div> <div>$\mu_{ref} = \text{NA}$ $\sigma_{ref} = \text{NA}$ $\sigma^2_{ref} = \text{NA}$ $\mu_{new} = \text{NA}$ $\sigma_{new} = \text{NA}$ $\sigma^2_{new} = \text{NA}$ $good_{cnt}/all_{cnt}$ NA / NA = NA</div> <div>NO DATA</div>	<div>idle wheel</div> <div>$\mu_{ref} = \text{NA}$ $\sigma_{ref} = \text{NA}$ $\sigma^2_{ref} = \text{NA}$ $\mu_{new} = \text{NA}$ $\sigma_{new} = \text{NA}$ $\sigma^2_{new} = \text{NA}$ $good_{cnt}/all_{cnt}$ NA / NA = NA</div> <div>NO DATA</div>	<div>lifting gear</div> <div>$\mu_{ref} = \text{NA}$ $\sigma_{ref} = \text{NA}$ $\sigma^2_{ref} = \text{NA}$ $\mu_{new} = \text{NA}$ $\sigma_{new} = \text{NA}$ $\sigma^2_{new} = \text{NA}$ $good_{cnt}/all_{cnt}$ NA / NA = NA</div> <div>NO DATA</div>	<div>lifting motor</div> <div>$\mu_{ref} = 100.4$ $\sigma_{ref} = 1139.61$ $\sigma^2_{ref} = 1298708.67$ $\mu_{new} = 1113.33$ $\sigma_{new} = 187.19$ $\sigma^2_{new} = 35041.34$ $good_{cnt}/all_{cnt}$ 15559 / 15559 = 100%</div> <div>GOOD FIT</div>
--	---	---	--	--	---

Distribution for drive sensors (acceleration)

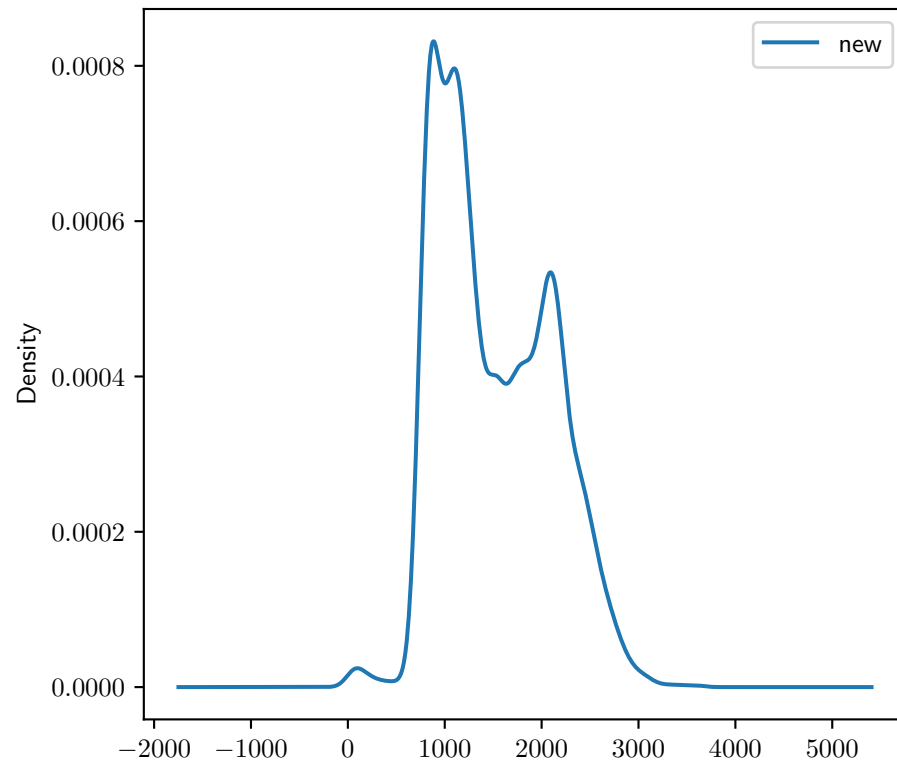


Distribution for other sensors (acceleration)

idle wheel



lifting gear



lifting motor

