

Diagnosis for FL01

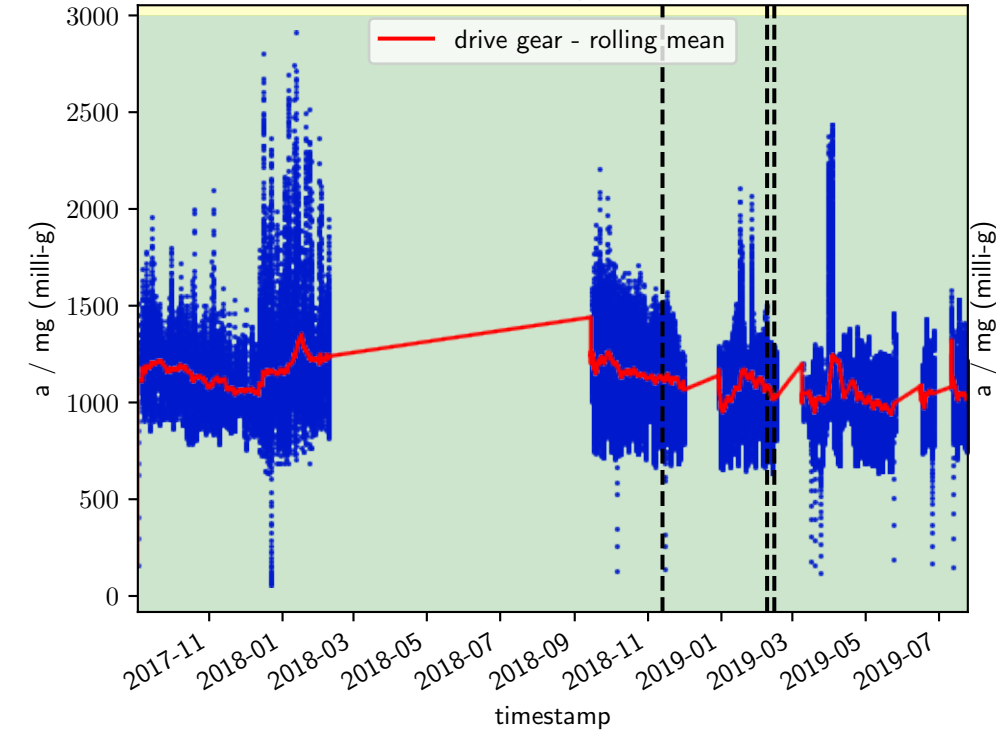
Categorization of measurements

Acceleration sensors

Time interval: all data

Acceleration sensors all data

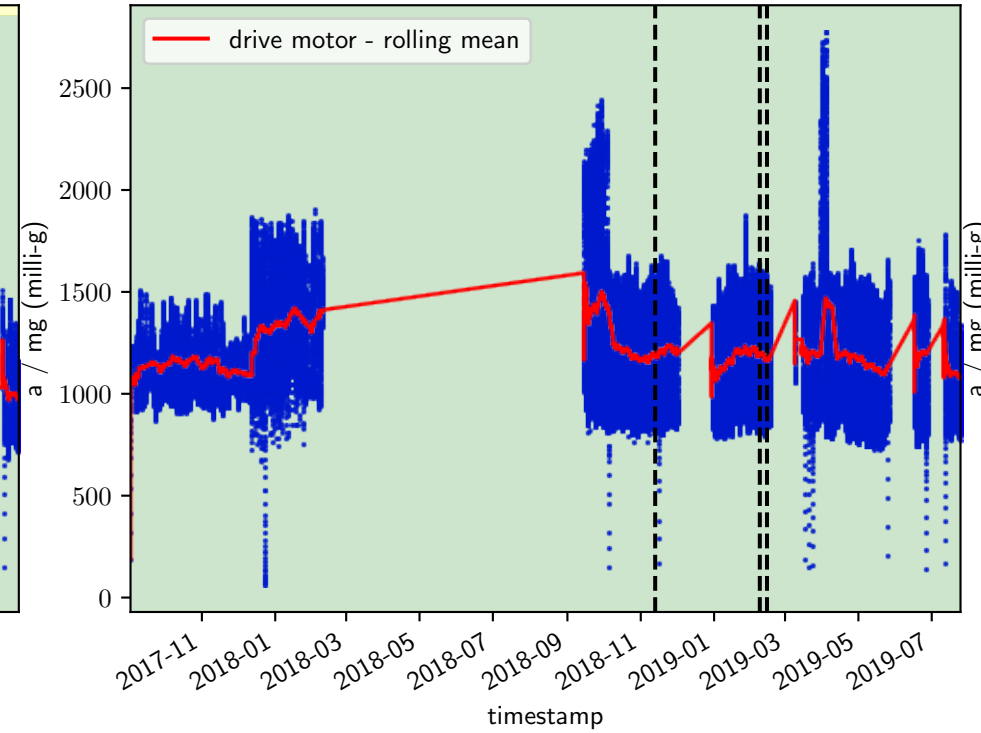
drive gear



Good: 110061/110061 = 100%
Satisfactory: 0/110061 = 0%
Unsatisfactory: 0/110061 = 0%
Unacceptable: 0/110061 = 0%

Good

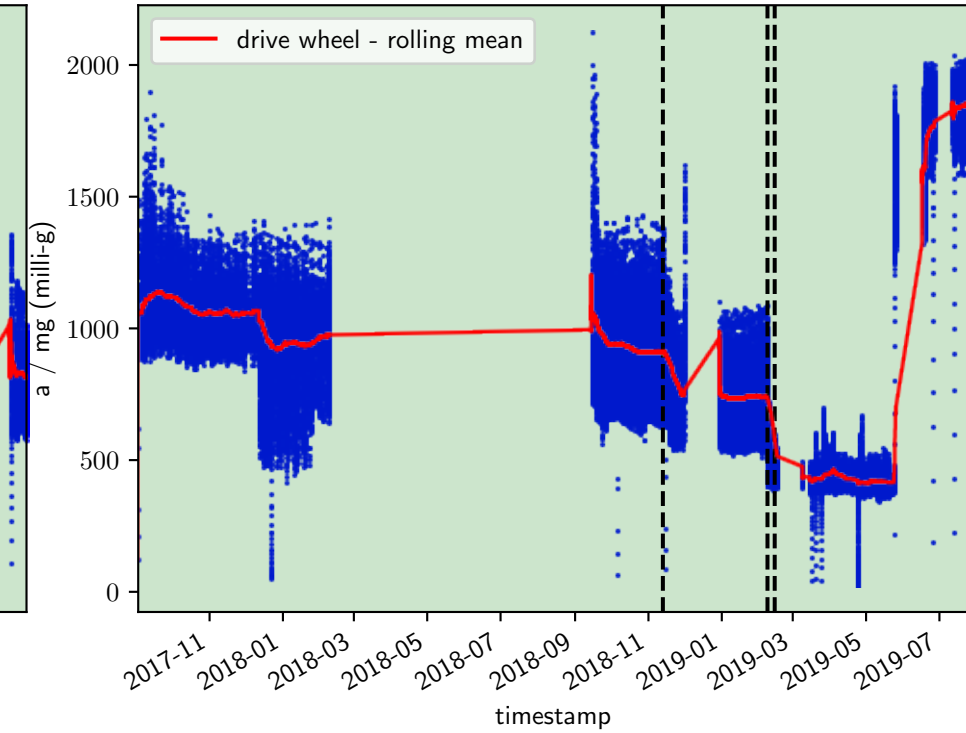
drive motor



Good: 110059/110059 = 100%
Satisfactory: 0/110059 = 0%
Unsatisfactory: 0/110059 = 0%
Unacceptable: 0/110059 = 0%

Good

drive wheel

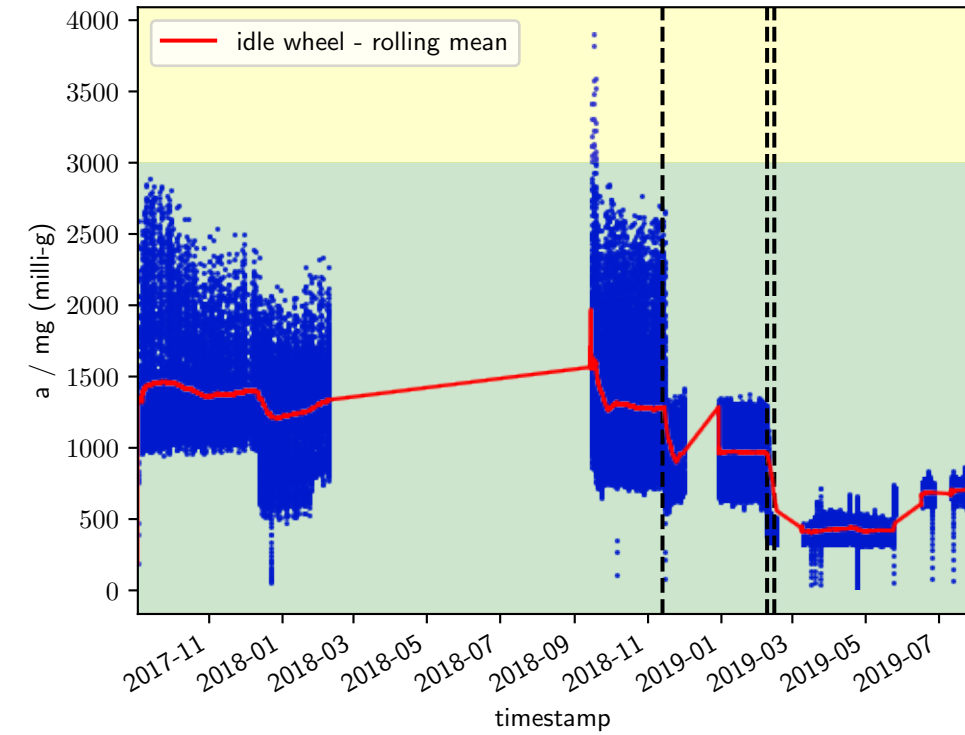


Good: 110180/110180 = 100%
Satisfactory: 0/110180 = 0%
Unsatisfactory: 0/110180 = 0%
Unacceptable: 0/110180 = 0%

Good

Acceleration sensors all data

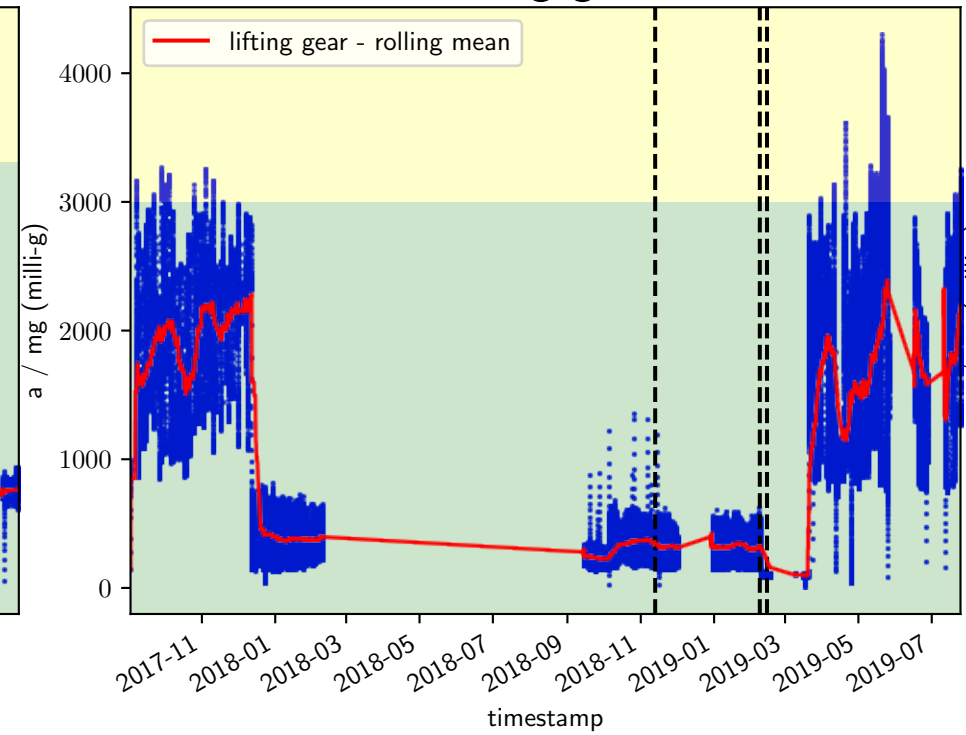
idle wheel



Good: 110152/110177 = 100%
 Satisfactory: 25/110177 = 0%
 Unsatisfactory: 0/110177 = 0%
 Unacceptable: 0/110177 = 0%

Satisfactory

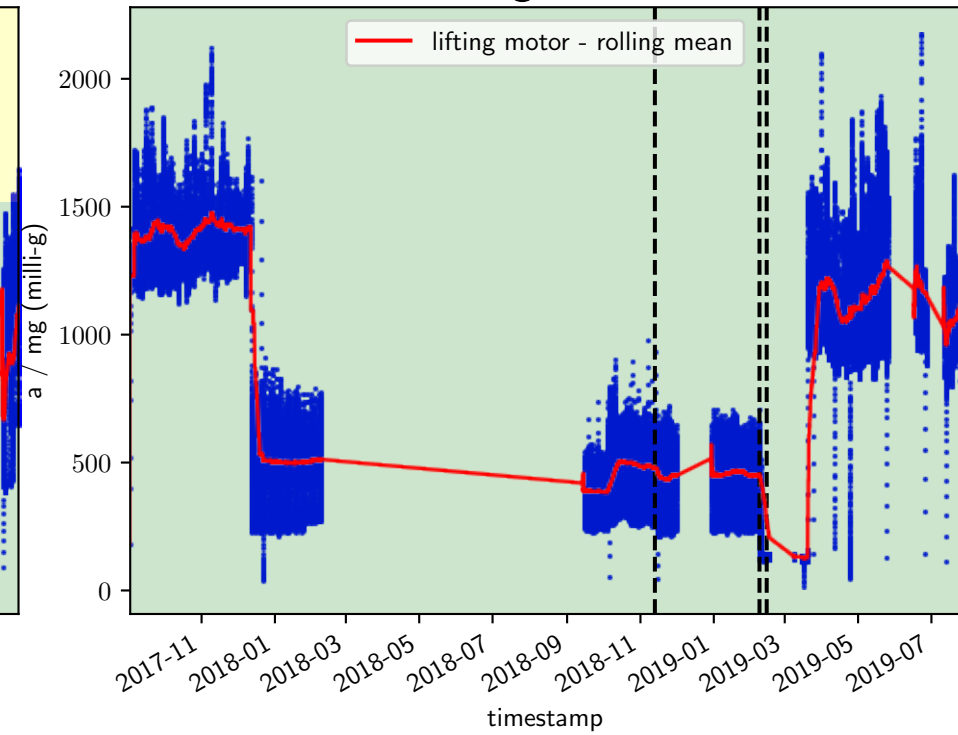
lifting gear



Good: 119218/121014 = 99%
 Satisfactory: 1796/121014 = 1%
 Unsatisfactory: 0/121014 = 0%
 Unacceptable: 0/121014 = 0%

Satisfactory

lifting motor



Good: 121012/121012 = 100%
 Satisfactory: 0/121012 = 0%
 Unsatisfactory: 0/121012 = 0%
 Unacceptable: 0/121012 = 0%

Good

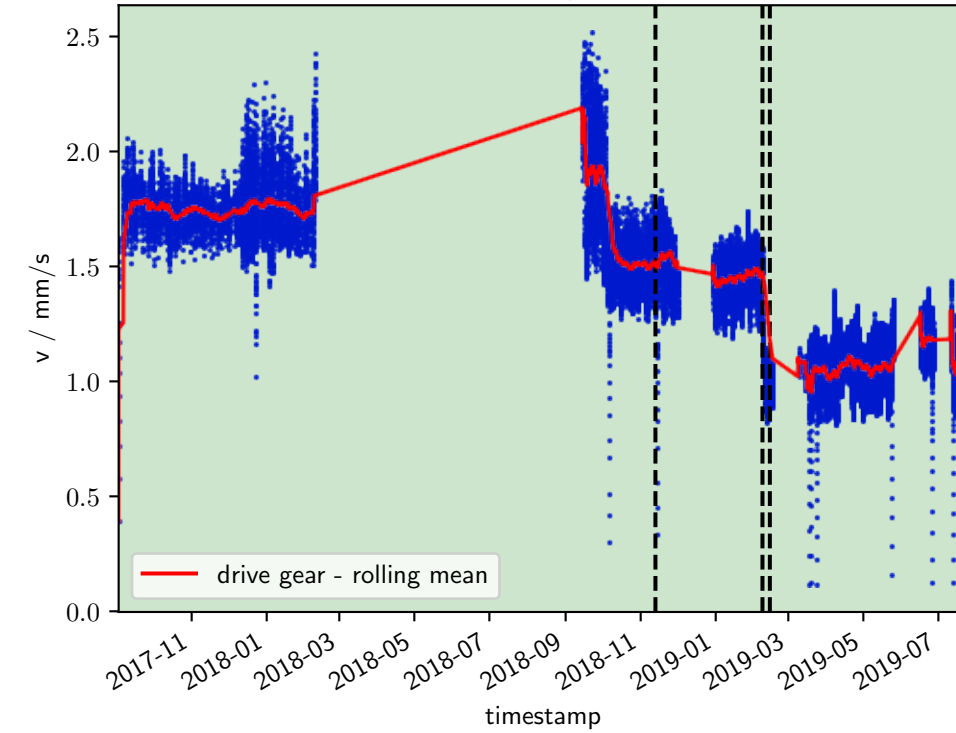
Categorization of measurements

Velocity sensors

Time interval: all data

Velocity sensors all data

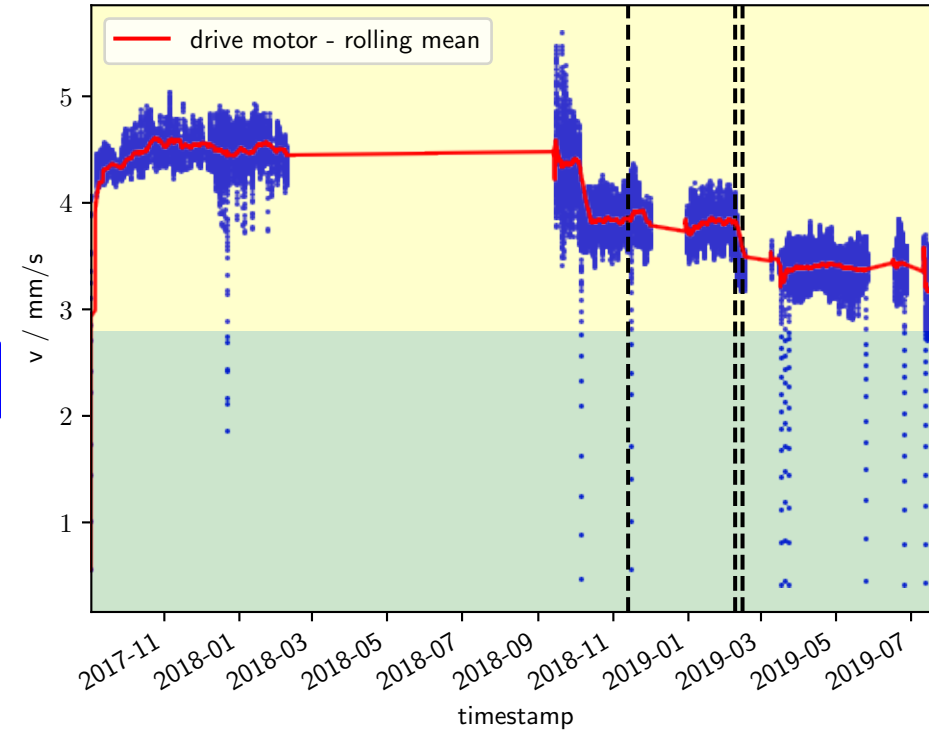
drive gear



Good: 32554/32554 = 100%
 Satisfactory: 0/32554 = 0%
 Unsatisfactory: 0/32554 = 0%
 Unacceptable: 0/32554 = 0%

Good

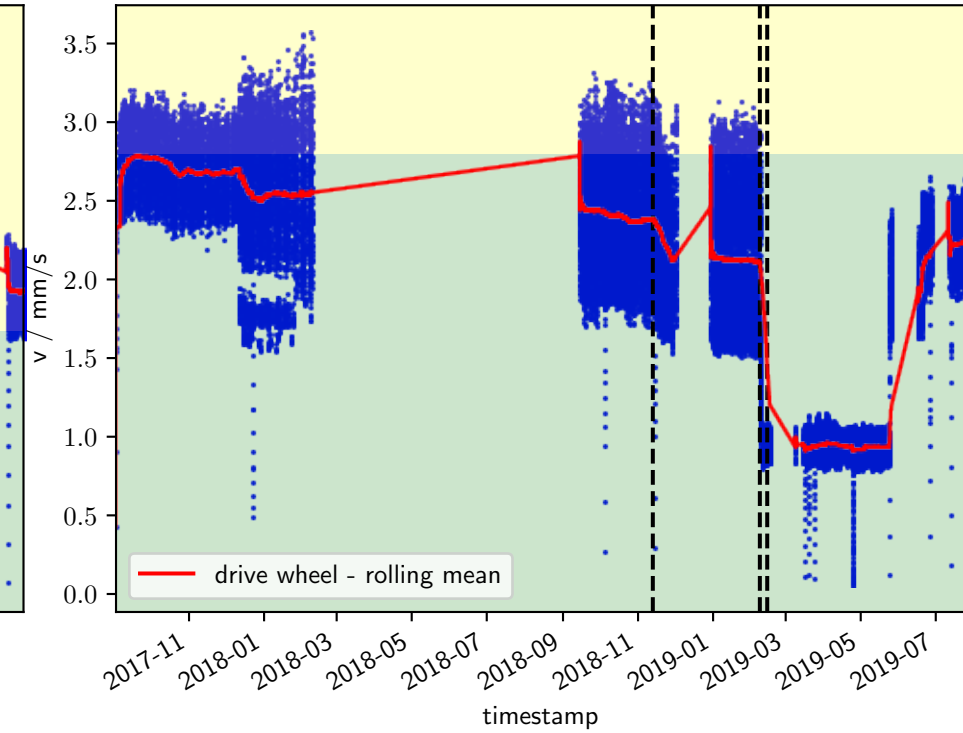
drive motor



Good: 141/33940 = 0%
 Satisfactory: 33799/33940 = 100%
 Unsatisfactory: 0/33940 = 0%
 Unacceptable: 0/33940 = 0%

Satisfactory

drive wheel

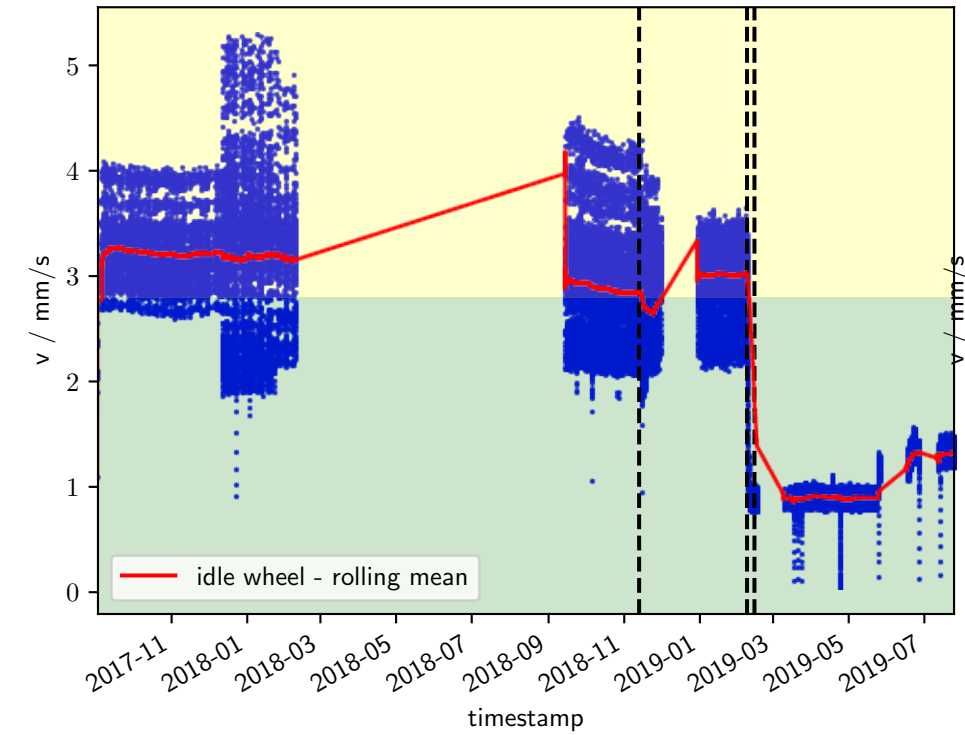


Good: 46261/51461 = 90%
 Satisfactory: 5200/51461 = 10%
 Unsatisfactory: 0/51461 = 0%
 Unacceptable: 0/51461 = 0%

Satisfactory

Velocity sensors all data

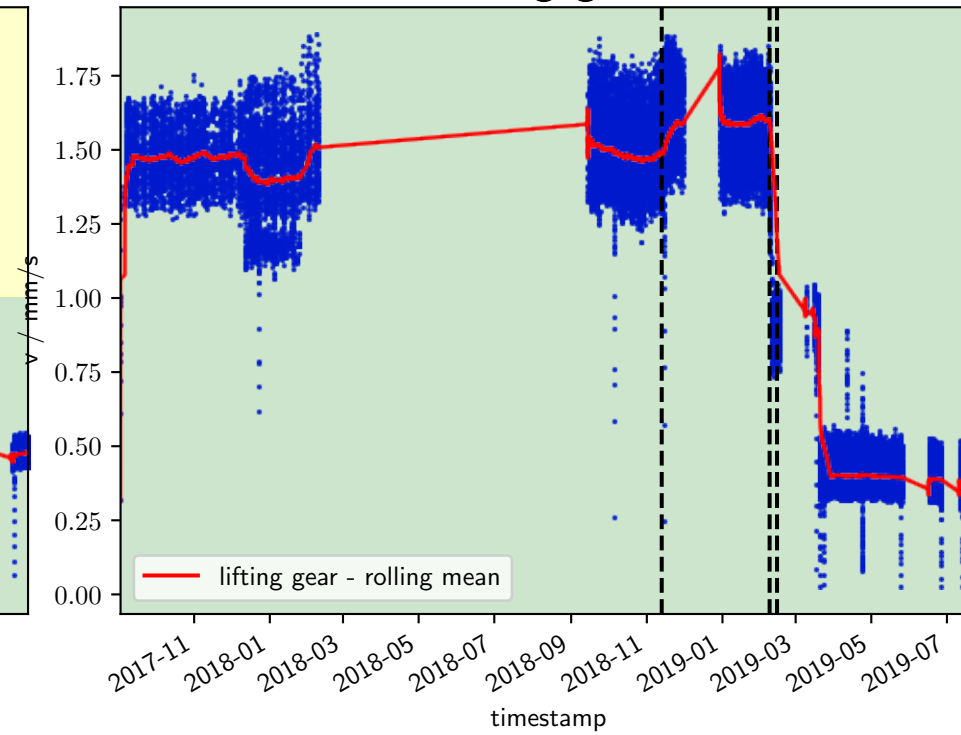
idle wheel



Good: 28222/50188 = 56%
 Satisfactory: 21966/50188 = 44%
 Unsatisfactory: 0/50188 = 0%
 Unacceptable: 0/50188 = 0%

Satisfactory

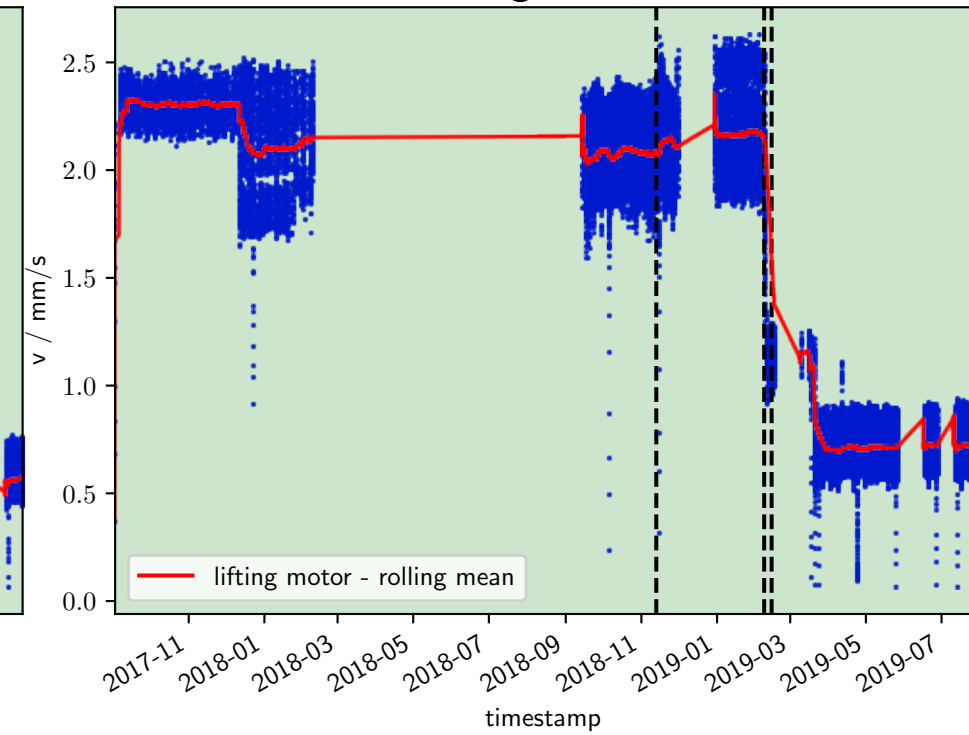
lifting gear



Good: 38446/38446 = 100%
 Satisfactory: 0/38446 = 0%
 Unsatisfactory: 0/38446 = 0%
 Unacceptable: 0/38446 = 0%

Good

lifting motor



Good: 39163/39163 = 100%
 Satisfactory: 0/39163 = 0%
 Unsatisfactory: 0/39163 = 0%
 Unacceptable: 0/39163 = 0%

Good

Compatibility check for velocity sensors

New data: from 2019-06-06 until 2019-07-25

Referent data: last 60 days

Velocity sensors

drive gear

$$\begin{aligned}\mu_{ref} &= 1.07 \\ \sigma_{ref} &= 0.1 \\ \sigma_{ref}^2 &= 0.01\end{aligned}$$

$$\begin{aligned}\mu_{new} &= 1.1 \\ \sigma_{new} &= 0.12 \\ \sigma_{new}^2 &= 0.02\end{aligned}$$

$$\begin{aligned}good_{cnt}/all_{cnt} \\ 4409 / 4448 = 99\%\end{aligned}$$

GOOD FIT

drive motor

$$\begin{aligned}\mu_{ref} &= 3.39 \\ \sigma_{ref} &= 0.12 \\ \sigma_{ref}^2 &= 0.02\end{aligned}$$

$$\begin{aligned}\mu_{new} &= 3.3 \\ \sigma_{new} &= 0.25 \\ \sigma_{new}^2 &= 0.06\end{aligned}$$

$$\begin{aligned}good_{cnt}/all_{cnt} \\ 3874 / 4692 = 83\%\end{aligned}$$

PARTIAL FIT

drive wheel

$$\begin{aligned}\mu_{ref} &= 0.98 \\ \sigma_{ref} &= 0.24 \\ \sigma_{ref}^2 &= 0.06\end{aligned}$$

$$\begin{aligned}\mu_{new} &= 2.2 \\ \sigma_{new} &= 0.19 \\ \sigma_{new}^2 &= 0.04\end{aligned}$$

$$\begin{aligned}good_{cnt}/all_{cnt} \\ 55 / 4731 = 1\%\end{aligned}$$

BAD FIT

idle wheel

$$\begin{aligned}\mu_{ref} &= 0.91 \\ \sigma_{ref} &= 0.1 \\ \sigma_{ref}^2 &= 0.01\end{aligned}$$

$$\begin{aligned}\mu_{new} &= 1.32 \\ \sigma_{new} &= 0.09 \\ \sigma_{new}^2 &= 0.01\end{aligned}$$

$$\begin{aligned}good_{cnt}/all_{cnt} \\ 224 / 4479 = 5\%\end{aligned}$$

BAD FIT

lifting gear

$$\begin{aligned}\mu_{ref} &= 0.4 \\ \sigma_{ref} &= 0.05 \\ \sigma_{ref}^2 &= 0.0\end{aligned}$$

$$\begin{aligned}\mu_{new} &= 0.39 \\ \sigma_{new} &= 0.04 \\ \sigma_{new}^2 &= 0.0\end{aligned}$$

$$\begin{aligned}good_{cnt}/all_{cnt} \\ 5785 / 5801 = 100\%\end{aligned}$$

GOOD FIT

lifting motor

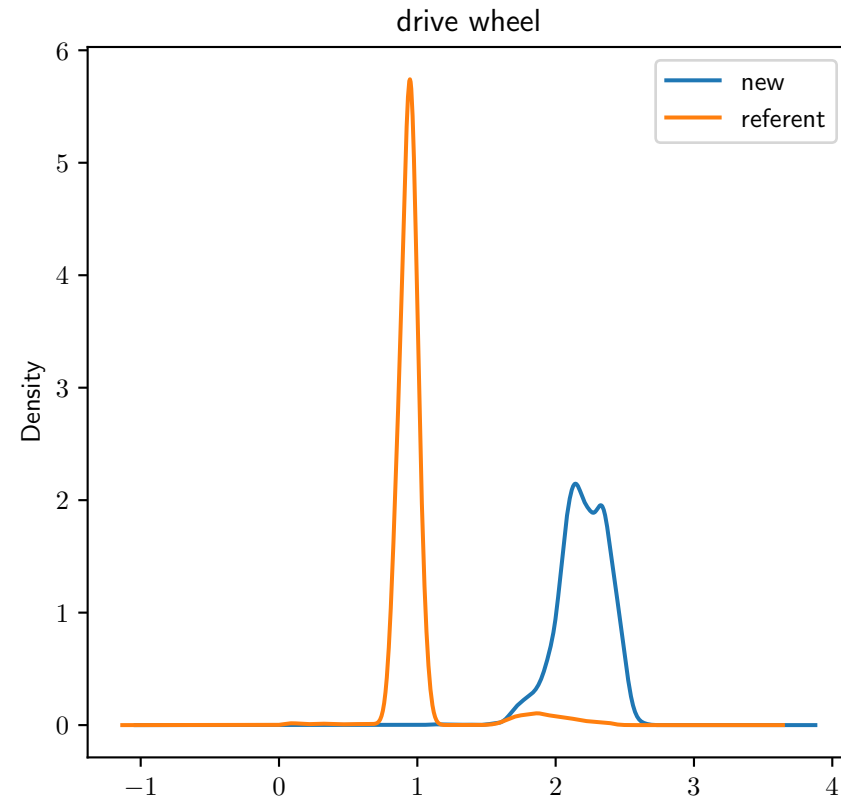
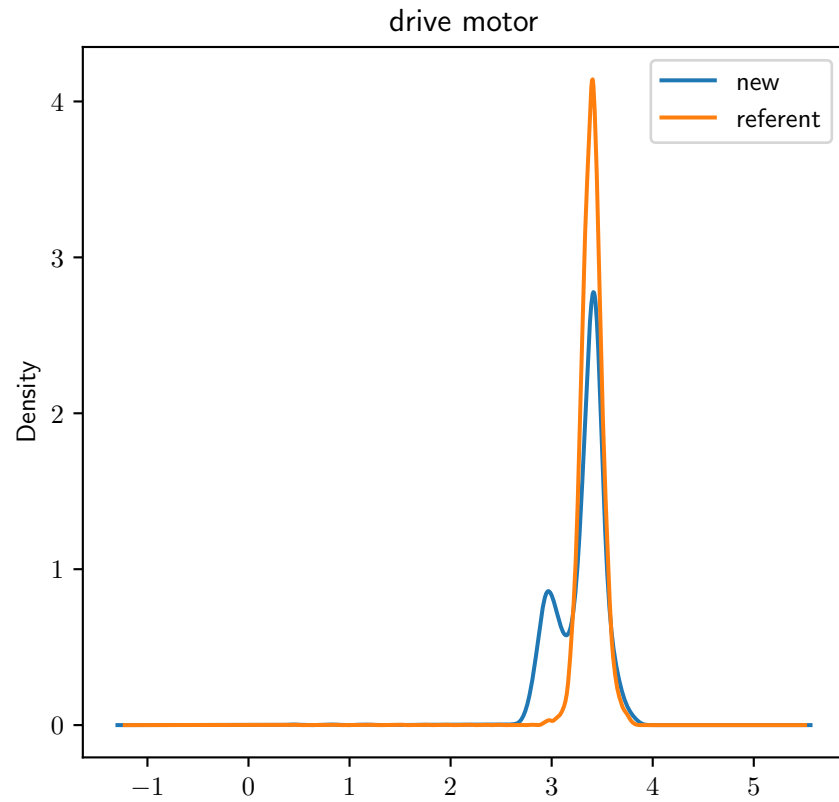
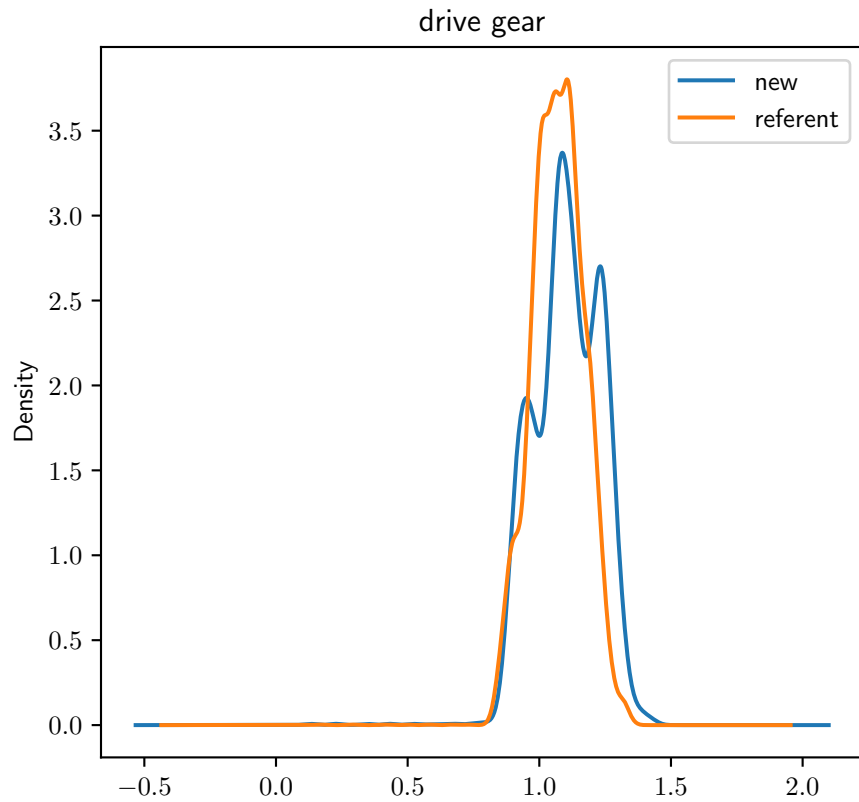
$$\begin{aligned}\mu_{ref} &= 0.71 \\ \sigma_{ref} &= 0.09 \\ \sigma_{ref}^2 &= 0.01\end{aligned}$$

$$\begin{aligned}\mu_{new} &= 0.72 \\ \sigma_{new} &= 0.1 \\ \sigma_{new}^2 &= 0.01\end{aligned}$$

$$\begin{aligned}good_{cnt}/all_{cnt} \\ 5951 / 5960 = 100\%\end{aligned}$$

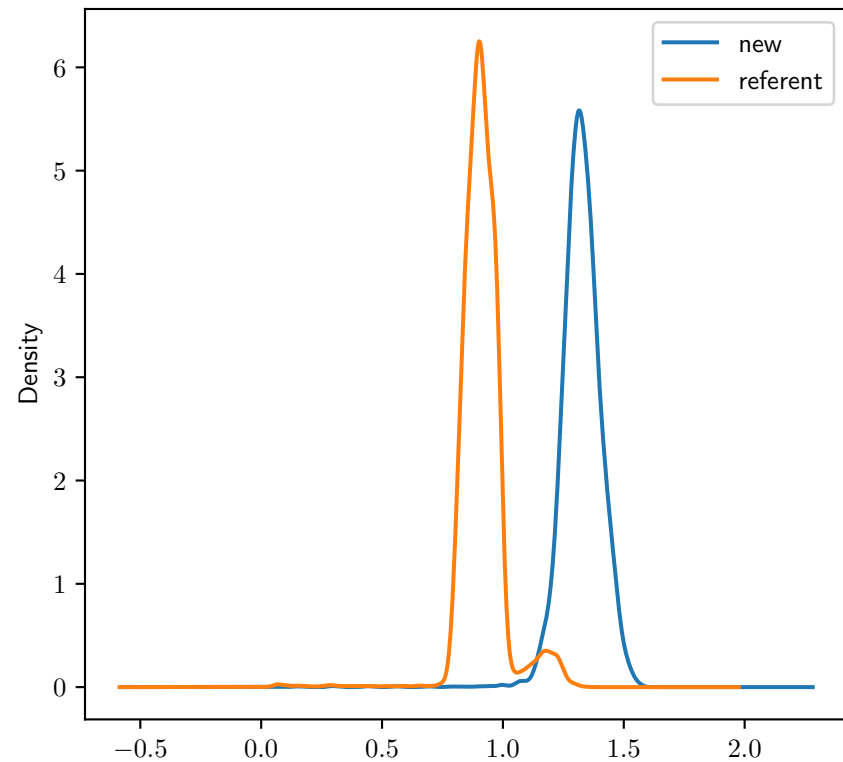
GOOD FIT

Distribution for drive sensors (velocity)

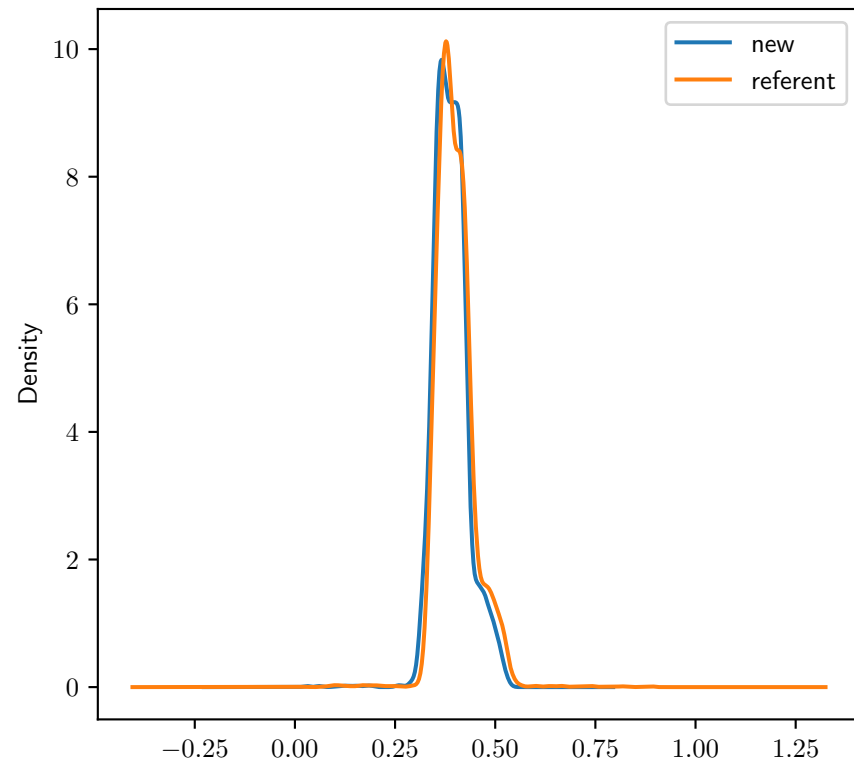


Distribution for other sensors (velocity)

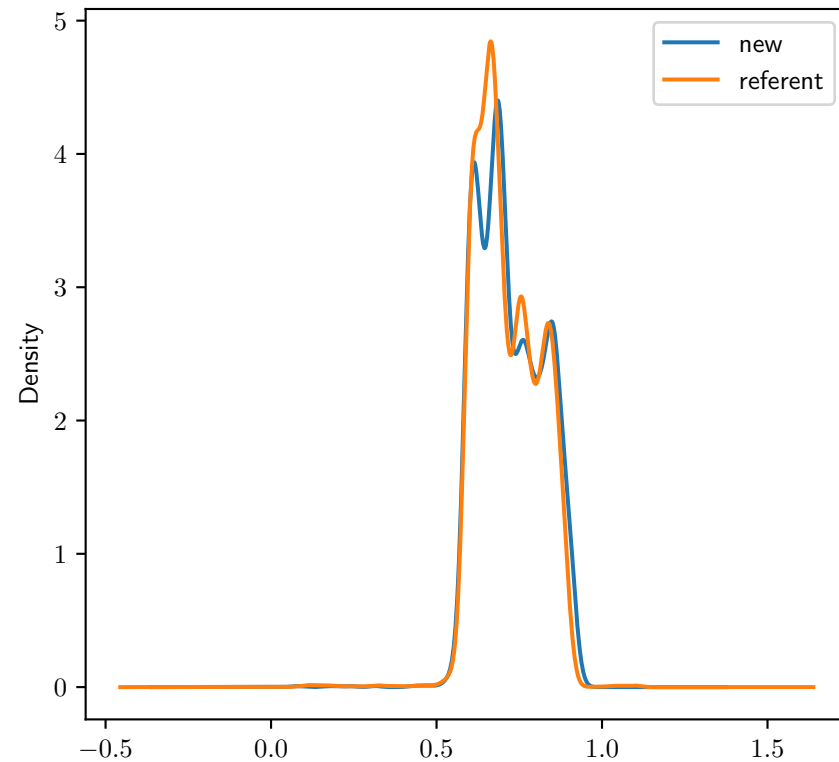
idle wheel



lifting gear



lifting motor



Compatibility check for acceleration sensors

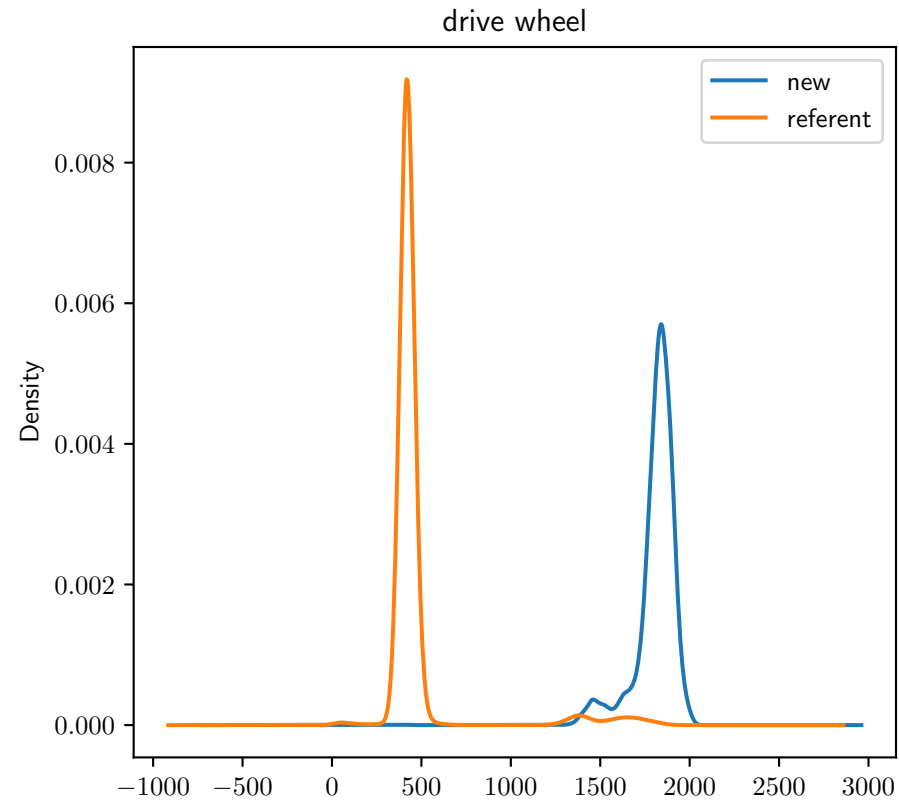
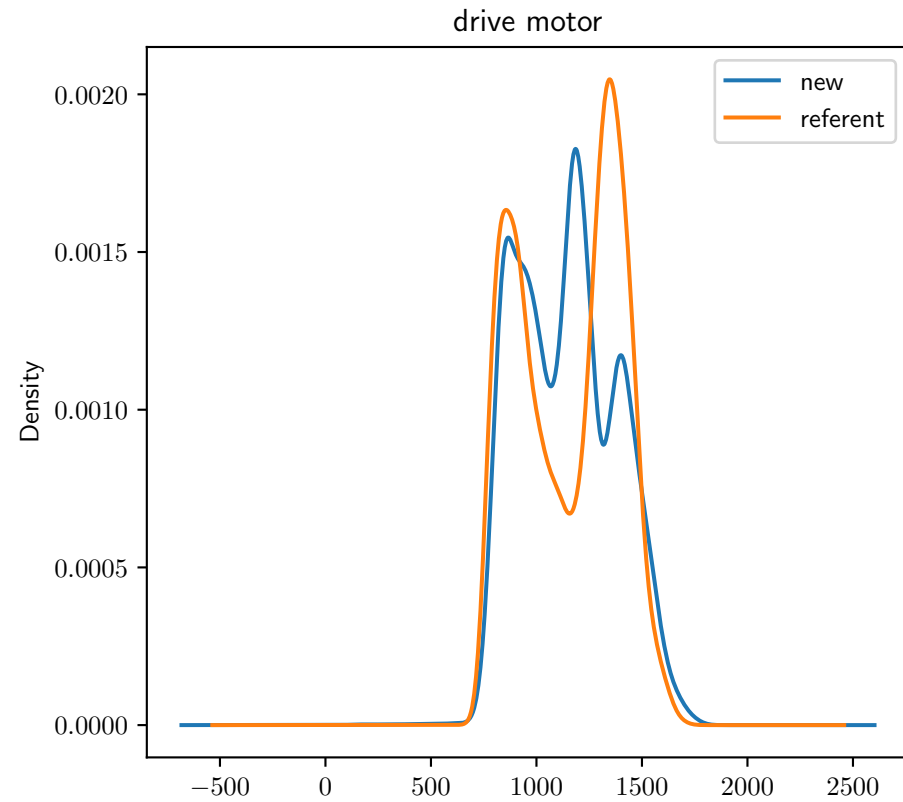
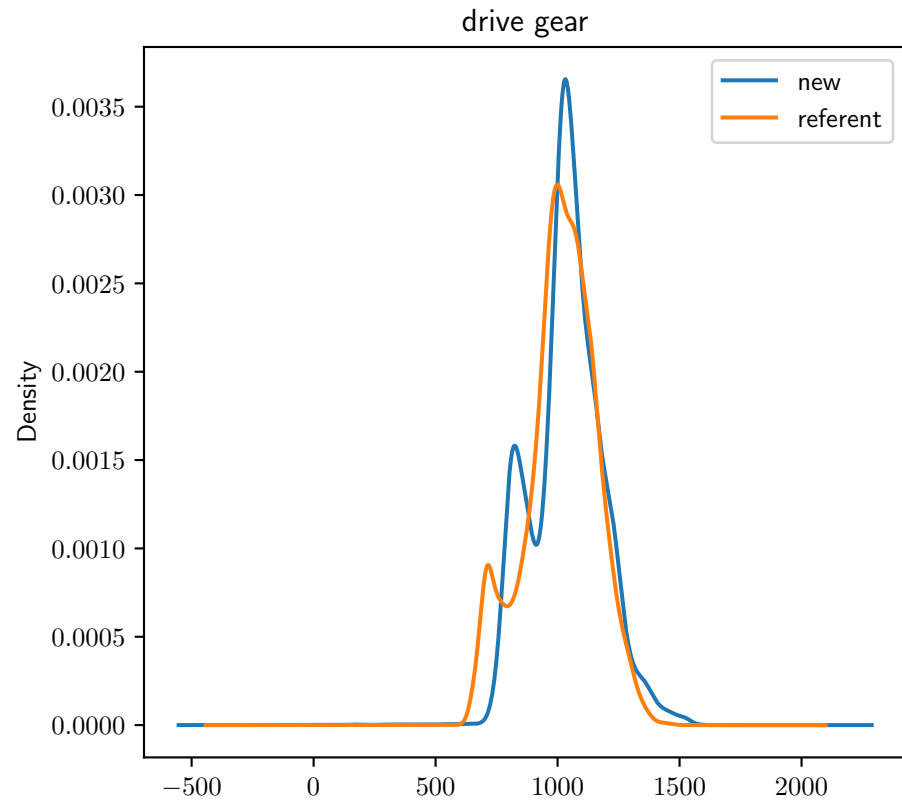
New data: from 2019-06-06 until 2019-07-25

Referent data: last 60 days

Acceleration sensors

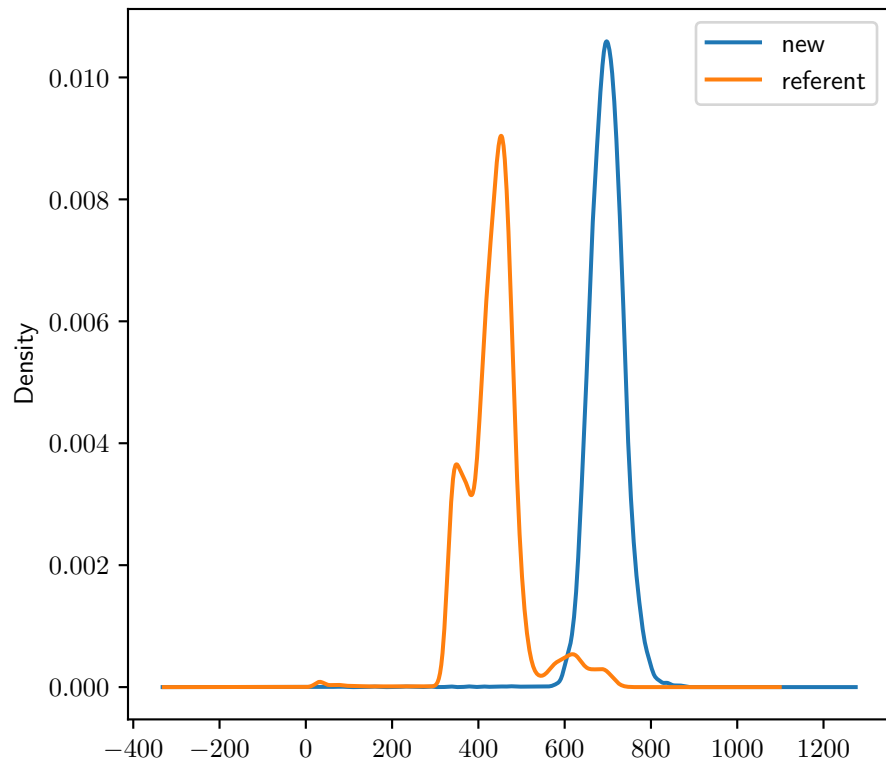
<div>drive gear</div> <div>$\mu_{ref} = 1011.5$ $\sigma_{ref} = 145.68$ $\sigma^2_{ref} = 21222.68$ $\mu_{new} = 1037.93$ $\sigma_{new} = 144.17$ $\sigma^2_{new} = 20785.45$ $good_{cnt}/all_{cnt}$ 9924 / 9992 = 99%</div> <div>GOOD FIT</div>	<div>drive motor</div> <div>$\mu_{ref} = 1152.44$ $\sigma_{ref} = 239.79$ $\sigma^2_{ref} = 57497.57$ $\mu_{new} = 1143.62$ $\sigma_{new} = 227.16$ $\sigma^2_{new} = 51600.11$ $good_{cnt}/all_{cnt}$ 9985 / 9992 = 100%</div> <div>GOOD FIT</div>	<div>drive wheel</div> <div>$\mu_{ref} = 477.51$ $\sigma_{ref} = 252.95$ $\sigma^2_{ref} = 63983.63$ $\mu_{new} = 1808.57$ $\sigma_{new} = 116.83$ $\sigma^2_{new} = 13648.16$ $good_{cnt}/all_{cnt}$ 16 / 9997 = 0%</div> <div>BAD FIT</div>	<div>idle wheel</div> <div>$\mu_{ref} = 436.57$ $\sigma_{ref} = 71.95$ $\sigma^2_{ref} = 5176.52$ $\mu_{new} = 696.98$ $\sigma_{new} = 41.36$ $\sigma^2_{new} = 1710.63$ $good_{cnt}/all_{cnt}$ 1093 / 9997 = 11%</div> <div>BAD FIT</div>	<div>lifting gear</div> <div>$\mu_{ref} = 1684.47$ $\sigma_{ref} = 732.16$ $\sigma^2_{ref} = 536053.19$ $\mu_{new} = 1823.78$ $\sigma_{new} = 580.91$ $\sigma^2_{new} = 337459.05$ $good_{cnt}/all_{cnt}$ 12972 / 12972 = 100%</div> <div>GOOD FIT</div>	<div>lifting motor</div> <div>$\mu_{ref} = 1146.71$ $\sigma_{ref} = 211.98$ $\sigma^2_{ref} = 44933.75$ $\mu_{new} = 1119.91$ $\sigma_{new} = 157.44$ $\sigma^2_{new} = 24788.01$ $good_{cnt}/all_{cnt}$ 12947 / 12971 = 100%</div> <div>GOOD FIT</div>
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Distribution for drive sensors (acceleration)

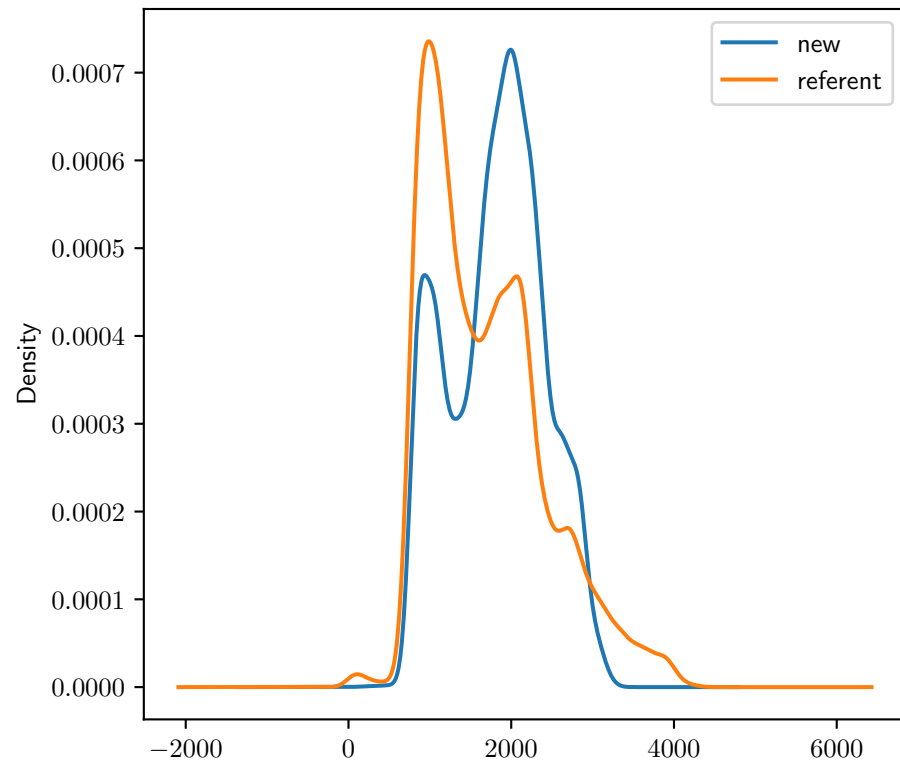


Distribution for other sensors (acceleration)

idle wheel



lifting gear



lifting motor

