

CS331-HW9-Lukang-Sun

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p1. (see Figure 1.) $a = [\text{matrix}([0.1]), \text{matrix}([0.424466]), \text{matrix}([0.77981303]), \text{matrix}([0.20033184]), \text{matrix}([0.51116473]), \text{matrix}([0.2604399]), \text{matrix}([0.97100656]), \text{matrix}([0.21263449]), \text{matrix}([0.26417151]), \text{matrix}([0.15995097])]$

$b = [\text{matrix}([0.4231786]), \text{matrix}([0.524466]), \text{matrix}([0.17981303]), \text{matrix}([0.50033184]), \text{matrix}([0.71116473]), \text{matrix}([0.0604399]), \text{matrix}([0.37100656]), \text{matrix}([0.91263449]), \text{matrix}([0.66417151]), \text{matrix}([0.65995097])]$, $f = \frac{1}{10} \sum_{i=1}^{10} f_i(x, y)$, $f_i(x, y) = \sin(x + a[i]) + \cos(y + b[i])$, for the SGD method, I use SGD-Uniform sampling.

(i) each f_i is at most 1-smoothness, since its Hessian is diagonal and bound by $\text{diag}(1, 1)$, so f is at most 1-smoothness, and it's obvious f_i, f are not convex at all. And this method satisfy ABC - assumption, $\mathbb{E}[\|g_i(x)\|_2^2] \leq 2A(f(x) - f^{\inf}) + B\|\nabla f(x)\|^2 + C$, obviously, C is less 2 since f_i, f bounded by 2, and we can set $A = 0, B = 0$ ($\mathbb{E}[\|g_i\|_2^2] \leq 2$).

(ii) I test how the error change in terms of K and the step size. Since in this case, only step size γ and K influence the error.

(iii) First I set γ fixed and change K . Then I set K fixed and change γ . By control one variable, we can clearly find the error change in terms of the other variable.

(iv) Theory states that the error change proportional to $\frac{1}{K}$ in certain error bound when γ is small and fixed and proportional to γ when K is fixed (generally very large $\gg \frac{1}{\gamma}$), these theory statements quite match my experiment results and my experiments shows the error change proportional to $\frac{1}{K}$ in certain error bound when γ is small and fixed and proportional to γ when K is fixed (generally very large $\gg \frac{1}{\gamma}$).

p2.

Lemma. Assume that f is μ -convex, g^t is unbiased (Assumption 1) and that the AC assumption (Assumption 2) is satisfied. Choose a stepsize satisfying

$$0 < \gamma_t \leq \frac{1}{A}$$

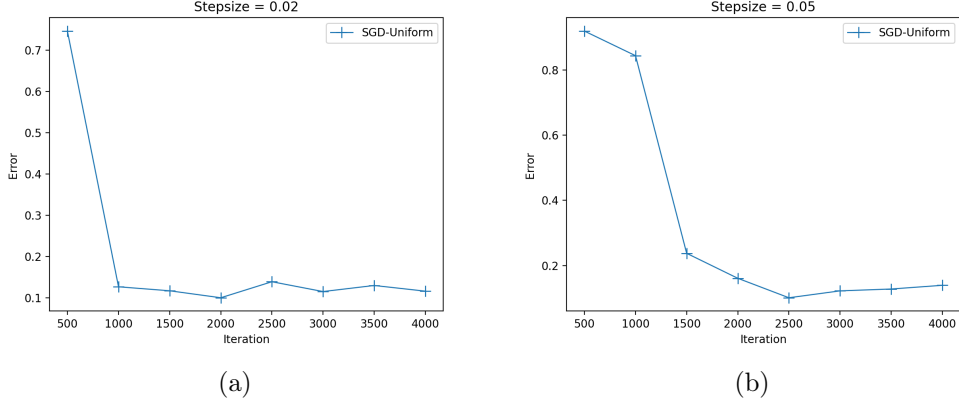


Figure 1: (a) shows $E[\|\nabla f\|^2]$ changes in terms of iteration number K when set step size $\gamma = 0.02$, (b) shows $E[\|\nabla f\|^2]$ changes in terms of iteration number K when set step size $\gamma = 0.05$.

Then the iterates $\{x^t\}_{t \geq 0}$ of SGD (Algorithm 3) satisfy

$$E[\|x^{t+1} - x^*\|^2] \leq (1 - \gamma_t \mu) E[\|x^t - x^*\|^2] + \gamma_t^2 C$$

Proof. the proof is exactly the same as theorem 30 \square

Lemma. Let $a, b, c \geq 0$ with $0 < a \leq b$. Consider a sequence $\{d_t\}_{t \geq 0}$ satisfying

$$d_{t+1} \leq (1 - \gamma_t a) d_t + \gamma_t^2 c$$

where $\gamma_t \leq \frac{1}{b}$ for all $t \geq 0$. Fix $K > 0$ and let $\theta = \lceil \frac{K}{2} \rceil$ and $s = \frac{2b}{a}$. Then choosing the stepsize as

$$\gamma_t = \begin{cases} \frac{1}{b}, & \text{if } K \leq 2(s-1) \\ \frac{1}{b}, & \text{if } K > 2(s-1) \text{ and } t < \theta \\ \frac{2}{a(s+t-\theta)}, & \text{if } K > 2(s-1) \text{ and } t \geq \theta \end{cases}$$

gives

$$d_K \leq \exp\left(-\frac{aK}{2b}\right) d_0 + \frac{12c}{a^2 K}$$

Proof. this is exactly lemma 117. \square

Theorem. Assume that f is μ -convex, g^t is unbiased (Assumption 1) and that the AC assumption is satisfied. Choose the stepsize as

$$\gamma_t = \begin{cases} \frac{1}{A}, & \text{if } K \leq 2(s-1) \\ \frac{1}{A}, & \text{if } K > 2(s-1) \text{ and } t < \theta, \\ \frac{2}{\mu(s+t-\theta)}, & \text{if } K > 2(s-1) \text{ and } t \geq \theta \end{cases}$$

where K is any chosen integer, $\theta = \lceil \frac{K}{2} \rceil$, $s = \frac{2A}{\mu}$, then we have

$$\mathbb{E} [\|x^K - x^*\|_2^2] \leq \exp\left(-\frac{\mu K}{2A}\right) \|x^0 - x^*\|^2 + \frac{12C}{\mu^2 K}$$

Proof. this is an corollary of the last lemma. \square

p3.

Proof. (i) Let's assume A is a matrix with full row rank. (if not, assume its row rank is l , then left multiply a $m \times m$ full rank matrix L , such that LA 's first l row has full rank and the left row is 0, then we can do the same analysis in a affine subspace (ϕ is strongly convex when constrained in a affine space $\{Ax + b, x \in \mathbb{R}^d\}$). Further if $\phi(x)$ is strongly convex if and only if $\phi_L(x) := \phi(Lx)$ is strongly convex. Since it is easy to see that $D_\phi(x, y) \geq \mu_1 \|x - y\|_2^2 \iff D_{\phi_L}(x, y) \geq \mu_2 \|x - y\|_2^2$). It's easy to verify that f is convex ($f(\lambda x + (1 - \lambda)y) = \phi(\lambda(Ax + b) + (1 - \lambda)(Ay + b)) \leq \lambda\phi(Ax + b) + \lambda\phi((1 - \lambda)(Ay + b)) = \lambda f(x) + (1 - \lambda)f(y)$), so there is x^* , such that $\nabla f(x^*) = A^T \nabla \phi(Ax^* + b) = 0$. Due to $D_\phi(a, y) \leq C \|\nabla \phi(a) - \nabla \phi(y)\|_2^2$, for any $a, y \in \mathbb{R}^m$, insert $a = Ax + b$ and $Ax^* + b$, we get $f(x) - f(x^*) - \langle \nabla \phi(Ax^* + b), A(x - x^*) \rangle \leq C \|\nabla \phi(Ax + b) - \nabla \phi(Ax^* + b)\|_2^2 = C \|\nabla \phi(Ax + b)\|_2^2$ since A^T has full column rank $A^T \nabla \phi(Ax^* + b) = 0 \iff \phi(Ax^* + b) = 0$, where $\langle \nabla \phi(Ax^* + b), A(x - x^*) \rangle = \langle A^T \nabla \phi(x^*), x - x^* \rangle = 0$, so we have $f(x) - f(x^*) \leq C \|\nabla \phi(Ax + b)\|_2^2 \leq CM \|\nabla f(x)\|_2^2$, where $M = \max_{x \in \mathbb{R}^m} \frac{\|x\|_2^2}{\|A^T x\|_2^2} \leq +\infty$, since A^T has full column rank.

(ii) $D_\phi(Ax + b, Ax^* + b) \geq C_1 \|A(x - x^*)\|_2^2 \geq C_1 N \|x - x^*\|_2^2$, so we have $f(x) - f(x^*) \geq C_1 N \|x - x^*\|_2^2$, where $N := \min_{x \in \mathbb{R}^d} \frac{\|Ax\|_2^2}{\|x\|_2^2}$, N could be 0. Actually, let $\phi = \frac{x^2}{2}$, $A = (1, 0)$, $b = 0$, then $f(x, y) = \frac{x^2}{2}$, $f(0, y) - f(0, 0) = 0 = 0 \|(0, y) - (0, 0)\|_2^2 = 0y^2$. \square