

#### PERCEPTRONS AND MULTILAYER PERCEPTRONS

Vincent Barra LIMOS, UMR 6158 CNRS, Université Clermont Auvergne





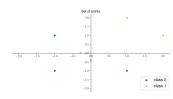


#### A toy example

- 5 points  $x_i = (x_i^1, x_i^2)$
- 2 classes (0,1)
- ▶ Linear perceptron  $w^Tx + b > 0$ ?
- ightharpoonup Error e = real class predicted class
- ▶ Init:  $(w_0, w_1, b) = (-0.1, 0.1, 0)$
- Parameters update:

$$\mathbf{1} \quad \mathbf{w}_{k+1} = \mathbf{w}_k + e\mathbf{x}$$

$$b_{k+1} = b_k + e$$



| $x^1$ | $x^2$ | c |
|-------|-------|---|
| 1     | 2     | 1 |
| 2     | 1     | 1 |
| -1    | 1     | 0 |
| -1    | -1    | 0 |
|       | -1    | 0 |













| $w_0$ | $w_1$ | b | $x^1$ | $x^2$ | С | $z = \boldsymbol{w}^T x + b$ | H(z) | e |
|-------|-------|---|-------|-------|---|------------------------------|------|---|
| -0.1  | 0.1   | 0 | 1     | 2     | 1 | 0.1                          | 1    | 0 |







|   | $w_0$ | $w_1$ | b | $x^1$ | $x^2$ | С | $z = \boldsymbol{w}^T x + b$ | H(z) | e |
|---|-------|-------|---|-------|-------|---|------------------------------|------|---|
| ĺ | -0.1  | 0.1   | 0 | 1     | 2     | 1 | 0.1                          | 1    | 0 |
| ĺ | -0.1  | 0.1   | 0 | 2     | 1     | 1 | -0.1                         | 0    | 1 |







| $w_0$ | $w_1$ | b | $x^1$ | $x^2$ | С | $z = \boldsymbol{w}^T x + b$ | H(z) | e  |
|-------|-------|---|-------|-------|---|------------------------------|------|----|
| -0.1  | 0.1   | 0 | 1     | 2     | 1 | 0.1                          | 1    | 0  |
| -0.1  | 0.1   | 0 | 2     | 1     | 1 | -0.1                         | 0    | 1  |
| 1.9   | 1.1   | 1 | -1    | 1     | 0 | 0.2                          | 1    | -1 |







| $w_0$ | $w_1$ | b | $x^1$ | $x^2$ | С | $z = \boldsymbol{w}^T x + b$ | H(z) | e  |
|-------|-------|---|-------|-------|---|------------------------------|------|----|
| -0.1  | 0.1   | 0 | 1     | 2     | 1 | 0.1                          | 1    | 0  |
| -0.1  | 0.1   | 0 | 2     | 1     | 1 | -0.1                         | 0    | 1  |
| 1.9   | 1.1   | 1 | -1    | 1     | 0 | 0.2                          | 1    | -1 |
| 2.9   | 0.1   | 0 | -1    | -1    | 0 | -3                           | 0    | 0  |







| $w_0$ | $w_1$ | b | $x^1$ | $x^2$ | С | $z = \boldsymbol{w}^T x + b$ | H(z) | e  |
|-------|-------|---|-------|-------|---|------------------------------|------|----|
| -0.1  | 0.1   | 0 | 1     | 2     | 1 | 0.1                          | 1    | 0  |
| -0.1  | 0.1   | 0 | 2     | 1     | 1 | -0.1                         | 0    | 1  |
| 1.9   | 1.1   | 1 | -1    | 1     | 0 | 0.2                          | 1    | -1 |
| 2.9   | 0.1   | 0 | -1    | -1    | 0 | -3                           | 0    | 0  |
| 2.9   | 0.1   | 0 | 1     | -1    | 0 | 2.8                          | 1    | -1 |







| $w_0$ | $w_1$ | b  | $x^1$ | $x^2$ | С | $z = \boldsymbol{w}^T x + b$ | H(z) | e  |
|-------|-------|----|-------|-------|---|------------------------------|------|----|
| -0.1  | 0.1   | 0  | 1     | 2     | 1 | 0.1                          | 1    | 0  |
| -0.1  | 0.1   | 0  | 2     | 1     | 1 | -0.1                         | 0    | 1  |
| 1.9   | 1.1   | 1  | -1    | 1     | 0 | 0.2                          | 1    | -1 |
| 2.9   | 0.1   | 0  | -1    | -1    | 0 | -3                           | 0    | 0  |
| 2.9   | 0.1   | 0  | 1     | -1    | 0 | 2.8                          | 1    | -1 |
| 1.9   | 1.1   | -1 | 1     | 2     | 1 | 3.1                          | 1    | 0  |







| $w_0$ | $w_1$ | b  | $x^1$ | $x^2$ | С | $z = \boldsymbol{w}^T x + b$ | H(z) | e  |
|-------|-------|----|-------|-------|---|------------------------------|------|----|
| -0.1  | 0.1   | 0  | 1     | 2     | 1 | 0.1                          | 1    | 0  |
| -0.1  | 0.1   | 0  | 2     | 1     | 1 | -0.1                         | 0    | 1  |
| 1.9   | 1.1   | 1  | -1    | 1     | 0 | 0.2                          | 1    | -1 |
| 2.9   | 0.1   | 0  | -1    | -1    | 0 | -3                           | 0    | 0  |
| 2.9   | 0.1   | 0  | 1     | -1    | 0 | 2.8                          | 1    | -1 |
| 1.9   | 1.1   | -1 | 1     | 2     | 1 | 3.1                          | 1    | 0  |
| 1.9   | 1.1   | -1 | 2     | 1     | 1 | 3.9                          | 1    | 0  |







| $w_0$ | $w_1$ | b  | $x^1$ | $x^2$ | С | $z = \boldsymbol{w}^T x + b$ | H(z) | e  |
|-------|-------|----|-------|-------|---|------------------------------|------|----|
| -0.1  | 0.1   | 0  | 1     | 2     | 1 | 0.1                          | 1    | 0  |
| -0.1  | 0.1   | 0  | 2     | 1     | 1 | -0.1                         | 0    | 1  |
| 1.9   | 1.1   | 1  | -1    | 1     | 0 | 0.2                          | 1    | -1 |
| 2.9   | 0.1   | 0  | -1    | -1    | 0 | -3                           | 0    | 0  |
| 2.9   | 0.1   | 0  | 1     | -1    | 0 | 2.8                          | 1    | -1 |
| 1.9   | 1.1   | -1 | 1     | 2     | 1 | 3.1                          | 1    | 0  |
| 1.9   | 1.1   | -1 | 2     | 1     | 1 | 3.9                          | 1    | 0  |
| 1.9   | 1.1   | -1 | -1    | ]     | 0 | -0.8                         | 0    | 0  |







| $w_0$ | $w_1$ | b  | $x^1$ | $x^2$ | С | $z = \boldsymbol{w}^T x + b$ | H(z) | e  |
|-------|-------|----|-------|-------|---|------------------------------|------|----|
| -0.1  | 0.1   | 0  | 1     | 2     | 1 | 0.1                          | 1    | 0  |
| -0.1  | 0.1   | 0  | 2     | 1     | 1 | -0.1                         | 0    | 1  |
| 1.9   | 1.1   | 1  | -1    | 1     | 0 | 0.2                          | 1    | -1 |
| 2.9   | 0.1   | 0  | -1    | -1    | 0 | -3                           | 0    | 0  |
| 2.9   | 0.1   | 0  | 1     | -1    | 0 | 2.8                          | 1    | -1 |
| 1.9   | 1.1   | -1 | 1     | 2     | 1 | 3.1                          | 1    | 0  |
| 1.9   | 1.1   | -1 | 2     | 1     | 1 | 3.9                          | 1    | 0  |
| 1.9   | 1.1   | -1 | -1    | 1     | 0 | -0.8                         | 0    | 0  |
| 1.9   | 1.1   | -1 | -1    | -1    | 0 | -3                           | 0    | 0  |







| $w_0$ | $w_1$ | b  | $x^1$ | $x^2$ | С | $z = \boldsymbol{w}^T x + b$ | H(z) | e  |
|-------|-------|----|-------|-------|---|------------------------------|------|----|
| -0.1  | 0.1   | 0  | 1     | 2     | 1 | 0.1                          | 1    | 0  |
| -0.1  | 0.1   | 0  | 2     | 1     | 1 | -0.1                         | 0    | 1  |
| 1.9   | 1.1   | 1  | -1    | 1     | 0 | 0.2                          | 1    | -1 |
| 2.9   | 0.1   | 0  | -1    | -1    | 0 | -3                           | 0    | 0  |
| 2.9   | 0.1   | 0  | 1     | -1    | 0 | 2.8                          | 1    | -1 |
| 1.9   | 1.1   | -1 | 1     | 2     | 1 | 3.1                          | 1    | 0  |
| 1.9   | 1.1   | -1 | 2     | 1     | 1 | 3.9                          | 1    | 0  |
| 1.9   | 1.1   | -1 | -1    | 1     | 0 | -0.8                         | 0    | 0  |
| 1.9   | 1.1   | -1 | -1    | -1    | 0 | -3                           | 0    | 0  |
| 1.9   | 1.1   | -1 | 1     | -1    | 0 | -0.8                         | 0    | 0  |







