Let us consider the set of m points

$$\mathcal{P} = \{p_1, \dots, p_m\} \subset \mathbb{R}^d$$
.

The problem is to find a center of ball such that the maximum distance between this center and points in  $\mathcal{P}$  is minimal, i.e.

$$\bar{p} := \arg \min_{p} \{ \max_{p_i \in \mathcal{P}} \| p_i - p \| \} , \qquad (1)$$

and the radius of this ball is given by the value of maximum distance between the center and points from  $\mathcal{P}$ , i.e.

$$r := \max_{p_i \in \mathcal{P}} \|p_i - p\|.$$

Similarly to polytope example (test 03), we will search for a coeficient vector of the convex linear combination

$$p = \sum_{i=1}^{m} \alpha_i p_i$$
, where  $\sum_{i=1}^{m} \alpha_i = 1$  and  $0 \le \alpha_i \le 1 \ \forall i = 1, \dots, m$ .

The reason is that the center of enclosing ball lies in the convex hull of  $\mathcal{P}$  (see Schönherr). Afterwards, we denote

$$y := [\alpha_1, \dots, \alpha_m]^T \in \mathbb{R}^m ,$$

$$C := [p_1, \dots, p_m] \in \mathbb{R}^{d,m} ,$$

$$b := [p_1^T p_1, \dots, p_m^T p_m] \in \mathbb{R}^m .$$

The problem (1) can be reformulated to QP. See next lemma.

Lemma 1. The solution of optimization problem

$$\bar{p} := C\bar{y}, \quad \bar{y} := \arg\min_{y \in \Omega_E \cap \Omega_I} y^T C^T C y - b^T C y,$$

where

$$\begin{array}{lcl} \Omega_E & := & \{y \in \mathbb{R}^m : Bx = 1\} \\ \Omega_I & := & \{y \in \mathbb{R}^m : x \geq 0\} \\ B & := & [1, \dots, 1] \in \mathbb{R}^{1,m} \end{array},$$

is equivalent to the solution of the problem (1).

*Proof.* See Schönherr. The proof is based on KKT optimality conditions.

Moreover, the problem can be homogenized and solved using the same methodology as in *polytope* example (test 03). We solve the problem to obtain the center of ball  $\bar{p}$ . Afterwards, the radius can be computed by

$$r = \sqrt{-\bar{p}^T A \bar{p} + 2b^T \bar{p}} \ .$$

**Numerical example** We work with random data in our benchmark. We generate m = 100 random points from circle

$$\{p\in\mathbb{R}^2:\|p-[1,1]^T\|^2\leq 1\}.$$

Afterwards, we discard the information about the circle and try to find the enclosing ball using the process described above.

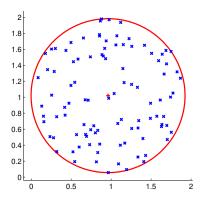


Figure 1: Enclosing ball: the solution of the benchmark.