



HALMSTAD  
UNIVERSITY



# Hard metrology of the human visual perception

by

Lukas Schwörer

Matriculation number: 65283

A bachelor thesis submitted in partial fulfillment of the  
requirements for the degree of the

Bachelor of Engineering (B. Eng.)

in Mechatronics

at Aalen University

Supervisors:

Prof. Dr. Ulrich Schmitt (Aalen University)

Sabina Rebeggiani (Halmstad University)

Submitted on:

November 20<sup>th</sup>, 2020



# Preface

# **Abstract**

# Kurzfassung

# Acknowledgement

At this point I would like to thank the following people who made my bachelor thesis possible and supported me during my time in Sweden:

- **Sabina Rebeggiani** for being a great supervisor during my time in Sweden. She taught me a lot of knowledge about surface metrology and the scientific of working.
- **Martin Bergman** for supervising me in the relationship with Volvo and teaching me about design and soft metrology.
- **Lars Bååth** for supervising me with the optics and physics of the project.
- **Ulrich Schmitt** for supervising me at Aalen University during my bachelor thesis.
- **Rainer Börret** for supervising me at Aalen University during my bachelor thesis and making my studies abroad possible.
- **Volvo Cars**, especially Ola Wagersten, Anna Larsson and Viktor Wadenvik for the bi-weekly meetings and the provided information about soft metrology and the quality control process at Volvo Cars.
- **Tim Malmgren and Joakim Wahlberg** for always helping out with practical work and the machines in FabLAB.
- **Lukas Ziegler** for his help during the last month of my thesis.

Last but not least I want to thank my family for their continuous support they have given me throughout my time in Sweden and my whole studies.

---

# Table of Contents

<b>Preface</b>	<b>i</b>
<b>Abstract</b>	<b>ii</b>
<b>Kurzfassung</b>	<b>iii</b>
<b>Acknowledgement</b>	<b>iv</b>
<b>1. Introduction</b>	<b>1</b>
1.0.1. University of Aalen . . . . .	1
<b>2. Theoretical Background</b>	<b>2</b>
2.1. Numerical Mathematic . . . . .	2
2.1.1. Fractional Mathematic . . . . .	2
2.1.2. Floatingpoint Mathematic . . . . .	2
2.2. Motors . . . . .	2
2.3. Manufacturing . . . . .	2
2.3.1. Additive Manufacturing . . . . .	2
2.3.2. Subtractive Manufacturing . . . . .	2
<b>3. Hardware and Software</b>	<b>3</b>
3.1. Hardware . . . . .	3
3.2. Software . . . . .	3
3.2.1. Matlab - Simulink . . . . .	3
3.2.2. Code Composer Studio . . . . .	3
3.2.3. Python . . . . .	3
3.2.4. Git . . . . .	3
3.2.5. Stepper Motors . . . . .	3
3.2.6. Touchscreen . . . . .	3
3.2.7. Raspberry Pi . . . . .	3
3.2.8. TI LaunchXL F280049C . . . . .	3
3.2.9. Logic Level Shifter . . . . .	3
<b>4. Experimental</b>	<b>4</b>
4.1. Initial Considerations . . . . .	4
4.2. Parameter Identification . . . . .	4
4.3. Simulink Model . . . . .	4
4.4. Code Generation . . . . .	4
4.5. Mechanical Implementation . . . . .	4
4.6. System Testing . . . . .	4
4.6.1. Arythmatic . . . . .	4
4.6.2. Threading . . . . .	4

---

4.6.3. Turning . . . . .	4
<b>5. Results and Discussion</b>	<b>5</b>
5.0.1. Arythmatic . . . . .	5
5.0.2. Threading . . . . .	5
5.0.3. Turning . . . . .	5
<b>6. Conclusion</b>	<b>6</b>
<b>7. Outlook</b>	<b>7</b>
<b>8. List of Figures</b>	<b>8</b>
<b>9. List of Tables</b>	<b>9</b>
<b>Appendix</b>	<b>I</b>



# **1. Introduction**

## **1.0.1. University of Aalen**

## **2. Theoretical Background**

### **2.1. Numerical Mathematic**

#### **2.1.1. Fractional Mathematic**

#### **2.1.2. Floatingpoint Mathematic**

### **2.2. Motors**

### **2.3. Manufacturing**

#### **2.3.1. Additive Manufacturing**

#### **2.3.2. Subtractive Manufacturing**

## **3. Hardware and Software**

### **3.1. Hardware**

### **3.2. Software**

#### **3.2.1. Matlab - Simulink**

#### **3.2.2. Code Composer Studio**

#### **3.2.3. Python**

#### **3.2.4. Git**

#### **3.2.5. Stepper Motors**

#### **3.2.6. Touchscreen**

#### **3.2.7. Raspberry Pi**

#### **3.2.8. TI LaunchXL F280049C**

#### **3.2.9. Logic Level Shifter**

## **4. Experimental**

### **4.1. Initial Considerations**

### **4.2. Parameter Identification**

### **4.3. Simulink Model**

### **4.4. Code Generation**

### **4.5. Mechanical Implementation**

### **4.6. System Testing**

#### **4.6.1. Arithmetic**

#### **4.6.2. Threading**

#### **4.6.3. Turning**

## **5. Results and Discussion**

**5.0.1. Arythmatic**

**5.0.2. Threading**

**5.0.3. Turning**

## **6. Conclusion**

## 7. Outlook

## **8. List of Figures**



## **9. List of Tables**

# Appendix

<b>A. Additional Topics</b>	<b>II</b>
A.1. Pin Out . . . . .	II
A.2. External Reset . . . . .	II
<b>B. List of Companies</b>	<b>III</b>
<b>C. Network setup and configuration</b>	<b>V</b>
<b>D. Organisation Chart</b>	<b>VI</b>
<b>E. Source Code</b>	<b>VII</b>
E.1. C - Code . . . . .	VIII
E.2. Python Code . . . . .	X

## **A. Additional Topics**

### **A.1. Pin Out**

### **A.2. External Reset**

## B. List of Companies



Company: Volvo Cars

Website: <https://www.volvocars.com/se>

---



Company: The MathWorks, Inc.

Website: <https://www.mathworks.com/>

---



Company: National Instruments

Website: <https://www.ni.com/>

---

---

# TAMRON

Company: Tamron

Website: <https://www.tamron.com/>

---



Company: LUCID Vision Labs

Website: <https://thinklucid.com/>

---



Company: Thorlabs, Inc.

Website: <https://www.thorlabs.com/>

---



Company: DIGI International, Inc.

Website: <https://www.digi.com/>

---



Company: MikroTik

Website: <https://mikrotik.com/>

## **C. Network setup and configuration**

## **D. Organisation Chart**

## **E. Source Code**



---

## E.1. C - Code

```
1 function TransmissionEvaluation()
2 % FUNCTION NAME:
3 %   TransmissionEvaluation()
4 %
5 % DESCRIPTION:
6 %   Computes the the average intensity of all binary
7 %       images in a directory selected by the user.
8 %
9 % INPUT:
10 %   None
11 %
12 % OUTPUT:
13 %   None
14 %
15 % Created:
16 %   Author:           Lukas Schwoerer
17 %   Date:             03.07.2020
18 %   Version:          V1.0
19 %
20
21 %% Initialize variables
22 clear all
23 listcounter = 1;
24
25
26 %% Select image folder and compile image list
27 path = uigetdir(pwd, 'Select_image_folder');
28 dircontent = dir(path);
29
30 for i = 1 : length(dircontent)
31     if contains(dircontent(i).name, '.bin')
32
33         imagelist(listcounter) = strcat(dircontent(i).
34             folder, "/", dircontent(i).name);
35         listcounter = listcounter + 1;
36
37     end
38 end
```

---

```

39
40 %% Calculate mean value for all images in imagelist
41 for i = 1 : length(imagelist)
42
43     fid = fopen(imagelist(i), 'r');
44     tmpimg = fread(fid, [2048, 2048], '*uint16'); %Read images
45     from binary file
46     fclose(fid);
47
48     tmpimg = double(tmpimg)/2^12; %Scale 16bit image value
49     into a range from 0-1
50
51     disp(imagelist(i)); %Display image name
52     disp(mean(tmpimg, 'all')); %Display mean intensity
53 end
end

```

---

## E.2. Python Code

```
1 function TransmissionEvaluation()
2 % FUNCTION NAME:
3 %   TransmissionEvaluation()
4 %
5 % DESCRIPTION:
6 %   Computes the the average intensity of all binary
7 %   images in a directory selected by the user.
8 %
9 % INPUT:
10 %   None
11 %
12 % OUTPUT:
13 %   None
14 %
15 % Created:
16 %   Author:           Lukas Schwoerer
17 %   Date:            03.07.2020
18 %   Version:         V1.0
19 %
20
21 %% Initialize variables
22 clear all
23 listcounter = 1;
24
25
26 %% Select image folder and compile image list
27 path = uigetdir(pwd, 'Select_image_folder');
28 dircontent = dir(path);
29
30 for i = 1 : length(dircontent)
31     if contains(dircontent(i).name, '.bin')
32
33         imagelist(listcounter) = strcat(dircontent(i).
34             folder, "/", dircontent(i).name);
35         listcounter = listcounter + 1;
36
37     end
38 end
```

---

```

39
40 %% Calculate mean value for all images in imagelist
41 for i = 1 : length(imagelist)
42
43     fid = fopen(imagelist(i), 'r');
44     tmpimg = fread(fid, [2048, 2048], '*uint16'); %Read images
45     from binary file
46     fclose(fid);
47
48     tmpimg = double(tmpimg)/2^12; %Scale 16bit image value
49     into a range from 0-1
50
51     disp(imagelist(i)); %Display image name
52     disp(mean(tmpimg, 'all')); %Display mean intensity
53
54 end
55 end

```

# Eidesstattliche Erklärung

**Name:** Schwörer

**Vorname:** Lukas

**Matrikel-Nr.:** 65283

**Studiengang:** Mechatronik

Hiermit versichere ich, **Lukas Schwörer**, an Eides statt, dass ich die vorliegende Bachelorarbeit

an der **University of Halmstad**

mit dem Titel „**Hard metrology of the human visual perception**“

selbständig und ohne fremde Hilfe verfasst und keine anderen als die angegebenen Hilfsmittel benutzt habe. Die Stellen der Arbeit, die dem Wortlaut oder dem Sinne nach anderen Werken entnommen wurden, sind in jedem Fall unter Angabe der Quelle kenntlich gemacht.

Ich habe die Bedeutung der eidesstattlichen Versicherung und prüfungsrechtlichen Folgen (§23 Abs. 3 des allg. Teils der Bachelor-SPO der Hochschule Aalen) sowie die strafrechtlichen Folgen (siehe unten) einer unrichtigen oder unvollständigen eidesstattlichen Versicherung zur Kenntnis genommen.

## Auszug aus dem Strafgesetzbuch (StGB)

**§156 StGB** Falsche Versicherung an Eides Statt Wer von einer zur Abnahme einer Versicherung an Eides Statt zuständigen Behörde eine solche Versicherung falsch abgibt oder unter Berufung auf eine solche Versicherung falsch aussagt, wird mit Freiheitsstrafe bis zu drei Jahren oder mit Geldstrafe bestraft.

---

Ort, Datum

---

Unterschrift