

Lecture 4: Dependent types and the Calculus of Constructions

Łukasz Czajka

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 - One could “erase” the judgements $\Gamma \vdash M : \varphi$ of intuitionistic first-order logic to $|\Gamma| \vdash \varphi$ and still have a reasonable formal system. Analogously with higher-order logic.
- Full dependent types abolish the a priori distinction between proof terms (proofs) and object terms (programs).
- It becomes possible to quantify over proofs (which are programs), and proofs (programs) may occur in types (formulas).

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- The type of the result depends on the value of the argument!
- $\sigma \rightarrow \tau$ is a special case of $\forall x : \sigma.\tau$ when $x \notin \text{FV}(\tau)$ (i.e. x does not occur free in τ).

Intermission: the simply-typed lambda-calculus

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- Uniqueness of normal forms: if t_1, t_2 are in β -normal form and $t_1 =_{\beta} t_2$, then $t_1 = t_2$.
- Exercise: β -equality on simply-typed terms is decidable.

Intermission: the simply-typed lambda-calculus

Let's assume the elements of \mathcal{B} are ordinary variables and $t_1 \rightarrow t_2$ is just another form of terms. Let $*$ be the universe of types.

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Let the contexts be sequences instead of sets.

$$\frac{\Gamma \vdash \tau : * \quad x \notin \text{dom}(\Gamma)}{\Gamma, x : \tau \vdash x : \tau} \quad \frac{\Gamma \vdash t : \tau \quad \Gamma \vdash \sigma : * \quad x \notin \text{dom}(\Gamma)}{\Gamma, x : \sigma \vdash t : \tau}$$
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Dependent types: the system λP

- A term t, τ, σ is a variable x, y, z, α, β , a universe $u \in \mathcal{U}$, an application $t_1 t_2$, a lambda-abstraction $\lambda x : \tau. t$, or a dependent function type $\forall x : \sigma. \tau$.

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- A context Γ is a finite sequence of declarations $x : \tau$.
 - The order matters!
 - We denote the empty sequence by $\langle \rangle$.
 - By $\text{dom}(\Gamma)$ we denote the set of all variables declared in Γ .
- A judgement has the form $\Gamma \vdash t : \tau$ with Γ context, t, τ terms.

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- Definitional equality \equiv is defined as $\beta\eta$ -equality.

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$$\frac{(u_1, u_2) \in \mathcal{A}}{\langle \rangle \vdash u_1 : u_2}$$

$$\frac{\Gamma \vdash \tau : u \quad x \notin \text{dom}(\Gamma)}{\Gamma, x : \tau \vdash x : \tau} \quad \frac{\Gamma \vdash t : \tau \quad \Gamma \vdash \sigma : u \quad x \notin \text{dom}(\Gamma)}{\Gamma, x : \sigma \vdash t : \tau}$$

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$$\frac{\Gamma \vdash \tau : u_1 \quad \Gamma, x : \tau \vdash \sigma : u_2 \quad (u_1, u_2, u_3) \in \mathcal{R}}{\Gamma \vdash (\forall x : \tau. \sigma) : u_3}$$

$$\frac{\Gamma \vdash t : \tau \quad \Gamma \vdash \tau' : u \quad \tau \equiv \tau'}{\Gamma \vdash t : \tau'}$$

- Universes: $\mathcal{U} = \{*, \square\}$.
- Axioms: $\mathcal{A} = \{(*, \square)\}$.
- Rules: $\mathcal{R} = \{(*, *, *), (*, \square, \square)\}$.

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- Unless stated otherwise, we consider only legal terms and contexts (i.e. those which appear in some derivable judgement).

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- The universe of types is a kind: $* : \square$ because $(*, \square) \in \mathcal{A}$. So each type (formula/proposition) is a type constructor (nullary predicate).

Dependent types: λP

\square				
	*	$\alpha \rightarrow *$	$(\alpha \rightarrow \alpha) \rightarrow \alpha \rightarrow *$...
α	$(\forall x : \alpha. Px) \rightarrow Py$	\dots	$\lambda x : \alpha. Px$	$\lambda f : \alpha \rightarrow \alpha. \lambda x : \alpha. P(fx)$
y	$\lambda f : \forall x : \alpha. Px. fy$	\dots	—	—

In the context: $\alpha : *, P : \alpha \rightarrow *, y : \alpha, p : \forall x : \alpha. Px.$

Dependent types: rules of λP

Objects depend on objects: $(*, *, *) \in \mathcal{R}$.

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But how do we actually derive $\Gamma \vdash P : \alpha \rightarrow *$?

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- For this we need $\alpha : * \vdash (\alpha \rightarrow *) : \square$.

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$$\frac{\vdots \quad \vdots}{\frac{\alpha : * \vdash \alpha : * \quad \alpha : *, x : \alpha \vdash * : \square}{\alpha : * \vdash \alpha \rightarrow * : \square}}$$

The rule $(*, \square, \Box)$ allows us to have “predicates” in the context (but not to quantify over them). λP is essentially a “first-order” system.

λP vs first-order logic

Consider the universal-implicational fragment $FOL^{\forall \rightarrow}$ of the system of intuitionistic first-order logic from the second lecture.

$$\overline{\Gamma, X : \varphi \vdash X : \varphi}$$

$$\frac{\Gamma, X : \varphi_1 \vdash M : \varphi_2}{\Gamma \vdash (\lambda X : \varphi_1. M) : \varphi_1 \rightarrow \varphi_2} \quad \frac{\Gamma \vdash M_1 : \varphi \rightarrow \psi \quad \Gamma \vdash M_2 : \varphi}{\Gamma \vdash M_1 M_2 : \psi}$$

$$\frac{\Gamma \vdash M : \varphi \quad x : A \quad x \notin FV(\Gamma)}{\Gamma \vdash (\lambda x : A. M) : \forall x : A. \varphi} \quad \frac{\Gamma \vdash M : \forall x : A. \varphi \quad t : A}{\Gamma \vdash Mt : \varphi[t/x]}$$

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Assuming the proof and object variables and the domains of $FOL^{\forall \rightarrow}$ are variables in λP , we define a translation from $FOL^{\forall \rightarrow}$ to λP :

- $[X] = X$, $[x] = x$, $[M_1 M_2] = [M_1][M_2]$, $[Mt] = [M][t]$,
- $[\lambda x : A.M] = \lambda x : A.[M]$, $[\lambda X : \varphi.M] = \lambda X : [\varphi].[M]$.
- $[A] = A$, $[\varphi \rightarrow \psi] = [\varphi] \rightarrow [\psi]$, $[\forall x : A.\varphi] = \forall x : A.[\varphi]$.

λP vs first-order logic

$$\begin{aligned} \lceil \Gamma \vdash M : \varphi \rceil = \\ A_1 : *, \dots, A_n : *, a_1 : A_1, \dots, a_n : A_n, x_1 : A_{x_1}, \dots, x_m : A_{x_m}, \\ X_1 : \lceil \psi_1 \rceil, \dots, X_k : \lceil \psi_k \rceil \vdash \lceil M \rceil : \lceil \varphi \rceil \end{aligned}$$

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Theorem (Soundness of translation from $FOL\forall\rightarrow$ to λP)

If $\Gamma \vdash M : \varphi$ is derivable in $FOL\forall\rightarrow$ then $[\Gamma \vdash M : \varphi]$ is derivable in λP .

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- Quantification over higher-order functions (but not predicates!),
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- Formulas (types) can refer to properties of proofs (dependently typed programs), e.g.:

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- Domains of quantifications may be empty, in contrast to “ordinary” first-order logic where they are implicitly assumed to be non-empty. E.g.: $(\forall x : \tau. \psi) \rightarrow \psi$ with $x \notin \text{FV}(\psi)$ is not inhabited unless we can construct an element of τ , even though the corresponding first-order formula $\forall x\psi \rightarrow \psi$ is an intuitionistic tautology when $x \notin \text{FV}(\psi)$.

Pure Type Systems

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- A term t is strongly $\beta\eta$ -normalising, denoted $\text{SN}_{\beta\eta}(t)$, if there are no infinite $\beta\eta$ -reduction sequences starting from t , i.e., no infinite sequences of terms $\{t_i\}_{i \in \mathbb{N}}$ such that $t_0 = t$ and $t_i \rightarrow_{\beta\eta} t_{i+1}$ for $n \in \mathbb{N}$.

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- A PTS is strongly (resp. weakly) normalising if every legal term is strongly (resp. weakly) normalising.

Exercise: postponement of η -reduction

Proposition

If t is strongly (resp. weakly) β -normalising, then it is strongly (resp. weakly) $\beta\eta$ -normalising.

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Proof (sketch).

For strong normalisation, show that if $t_1 \rightarrow_\eta t_2 \rightarrow_\beta t_3$ then there is t' with $t_1 \rightarrow_\beta^+ t' \rightarrow_\eta^* t_3$. For weak normalisation, it suffices to prove that η -reduction is normalising and that η -reducing a β -normal form produces a β -normal form. □

Pure Type Systems: properties

Theorem (Subject reduction for β)

In any PTS, if $\Gamma \vdash t : \tau$ and $t \rightarrow_{\beta}^ t'$ then $\Gamma \vdash t' : \tau$.*

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Theorem (Subject reduction for $\beta\eta$)

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Theorem (Uniqueness of normal forms)

In any PTS, if t_1, t_2 are legal (well-typed) $\beta\eta$ -normal forms such that $t_1 =_{\beta\eta} t_2$, then $t_1 = t_2$.

Pure Type Systems: benefits of normalisation

Theorem (Decidability of type checking)

In any weakly normalising PTS, type checking is decidable.

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Theorem (Consistency)

*Any weakly normalising PTS is consistent, i.e., there is no term t with $\vdash t : \forall p : *.p$.*

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Types depend on types: $(\square, \square, \square) \in \mathcal{R}$.

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- Let `Type0` = `Set`.

Universes: rules

- $(\text{Type}_i, \text{Type}_j, \text{Type}_{\max(i,j)}) \in \mathcal{R}$ for $i, j \geq 0$.

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- $(u, \text{Prop}, \text{Prop}) \in \mathcal{R}$ for any universe u .

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Impredicativity

Definition

A universe u_1 with $u_1 : u_2$ is impredicative if $(u_2, u_1, u_1) \in \mathcal{R}$, i.e.,

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- For a predicative universe u_1 with $u_1 : u_2$ we have $(u_2, u_1, u_2) \in \mathcal{R}$ instead, i.e.,

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Theorem (Girard's paradox)

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Corollary

Any PTS with $(, *) \in \mathcal{A}$ and $(*, *, *) \in \mathcal{R}$ is inconsistent.*

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- Indeed, Coq with impredicative **Set** would be consistent.
- But in Coq impredicative **Set** is inconsistent with the combination of classical logic and the axiom of choice!

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- In particular, $\text{Prop} : \text{Type}_i$ for $i > 0$ and $\text{Type}_i : \text{Type}_j$ for $i < j$.
- One consequence of subtyping: subject reduction for η -reduction fails – η -expansion on legal terms is considered instead.

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Decidability of equality (excluded middle for equality):

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Theorem

In Coq, proof irrelevance and the axiom of choice together imply decidability of equality.

Axioms

