model bywindow

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```
import matplotlib.pyplot as plt
import numpy as np
import pandas as pd
import tensorflow as tf
import torch

from sklearn.metrics import accuracy_score, precision_score, recall_score,
confusion_matrix
from sklearn.decomposition import PCA
#from sklearn.model_selection import train_test_split

from tensorflow.keras import layers, losses
from tensorflow.keras.models import Model

DEVICE = ('cuda:0' if torch.cuda.is_available() else 'cpu')
print('Device being used: ', DEVICE)

torch.backends.cudnn.deterministic = True
```

Device being used: cuda:0

0.0.1 Splitting Data

Since we want our model to learn what "normal" log events look like, we'll remove all original row indices labeled as anomalies. We can use the anom label index as our filter.

Training Data: - First 8 million rows minus the anomalies (~ 7.7 million rows)

Unofficial Test Set: - First 8 million rows with the anomalies

Test Set: - 2 million rows (index 8mil to 10mil) with anomalies

Validation Set: - Last 1-2 million rows, never before seen, with anomalies

```
[2]: # FOR TESTING WE ONLY IMPORT THE FIRST 100'000 ROWS

limit = 600000

## Import Anomaly Labels

anom = pd.read_csv('Data/anomaly_labels.csv', header=None, index_col=None,

→names=['anomaly'])[0:limit]
```

```
anom_idx = anom[anom.anomaly==1].index # anomaly index
normal_idx = anom[anom.anomaly==0].index # normal event index

anom = np.array(anom.anomaly)
unofficial_test_key = anom[:400000]
official_test_key = anom[400000:500000]
validation_key = anom[500000:]

## Import Scaled Data
scaled = np.load('Data/ONEHOT_SCALED.npy')[0:limit]
```

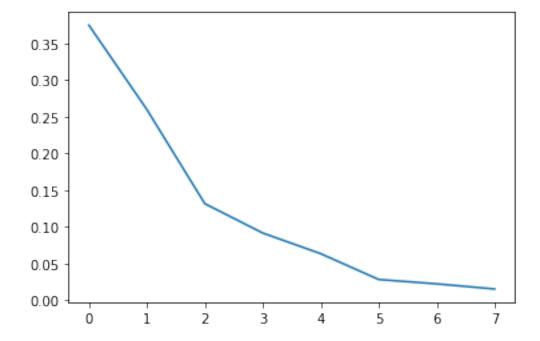
0.0.2 See if we can reduce dimensionality -> Yes

We will train and test both on a reduced and original dataframe to see if there's a difference.

```
[3]: ## Reduce column dimensionality as the 128 columns are extremely sparse
visualize_pca = PCA().fit(scaled)

plt.plot(visualize_pca.explained_variance_ratio_[0:8])
plt.show()

visualize_pca.explained_variance_ratio_[0:32]
```



```
[3]: array([3.74442407e-01, 2.59742555e-01, 1.31593622e-01, 9.16514730e-02, 6.35354417e-02, 2.84450951e-02, 2.24996402e-02, 1.55092849e-02, 7.75151938e-03, 1.41001060e-03, 1.29544694e-03, 4.95385133e-04,
```

```
4.25560874e-04, 3.05632251e-04, 2.45593193e-04, 2.15670925e-04, 9.68049297e-05, 6.51079710e-05, 5.76354636e-05, 4.45650490e-05, 3.11143077e-05, 2.97853181e-05, 2.16445934e-05, 1.24389351e-05, 1.02427252e-05, 9.60806537e-06, 8.87263647e-06, 8.13570446e-06, 6.97132161e-06, 5.52759663e-06, 4.86530011e-06, 4.65038152e-06])
```

```
[4]: ## Perform PCA with dimensionality reduction on first 32 principal components
pca = PCA(n_components=32)
scaled_pca = pca.fit_transform(scaled)
```

0.1 Model Training (by window)

Since we saw that PCA gives decent improvements, we will run a sliding window over the already existing reduced dataset.

Object: windows Size: 0.921590912 GiB

```
[18]: x_train = tf.convert_to_tensor(windows[normal_idx[normal_idx<400000]].
       →reshape(385675, 6, 32, 1), dtype=np.float32) # train first 80'000 rows
      print('Training after anomaly removal:', x_train.shape)
      x_test_unofficial_anoms = tf.

→convert_to_tensor(windows[anom_idx[anom_idx<400000]].reshape(14325, 6, 32, □)
      →1), dtype=np.float32) # for validation during training
      print('x_test_unofficial_anoms:', x_test_unofficial_anoms.shape)
      x_test_unofficial = tf.convert_to_tensor(windows[:400000].reshape(400000, 6,_
       \rightarrow32, 1), dtype=np.float32) # test on the same 80'000 rows
      print('x_test_unofficial:', x_test_unofficial.shape)
      print()
      x_{test} = tf.convert_{to_{tensor}(windows[400000:500000].reshape(100000, 6, 32, 1),_{u})}
      →dtype=np.float32) # test on new 16'000 rows
      print('x_test:', x_test.shape)
      validation = tf.convert_to_tensor(windows[500000:600000].reshape(99994, 6, 32,_
       →1), dtype=np.float32) # validate on completely new 4'000 rows
      print('validation:', validation.shape)
```

```
Training after anomaly removal: (385675, 6, 32, 1)
     x_test_unofficial_anoms: (14325, 6, 32, 1)
     x_test_unofficial: (400000, 6, 32, 1)
     x test: (100000, 6, 32, 1)
     validation: (99994, 6, 32, 1)
[20]: # EXPERIMENTAL REDUCED DATA WINDOW MODEL
      class AnomalyDetector(Model):
       def __init__(self):
         super(AnomalyDetector, self). init ()
          self.encoder = tf.keras.Sequential([
             # layers. Input(shape = (6,32,1)),
             layers.Conv2D(16, (3,3), activation='relu', padding='same'), #
             layers.Conv2D(8, (3,3), activation='relu', padding='same')])
          self.decoder = tf.keras.Sequential([
              layers.Conv2DTranspose(8, kernel_size=3, activation='relu',_
       →padding='same'),
             layers.Conv2DTranspose(16, kernel_size=3, activation='relu', ___
       →padding='same'),
              layers.Conv2D(1, kernel_size=(3, 3), activation='sigmoid',__
       →padding='same')])
              #layers.Reshape((10, 32))])
       def call(self, x):
         encoded = self.encoder(x)
         decoded = self.decoder(encoded)
         return decoded
      autoencoder = AnomalyDetector()
      autoencoder.compile(optimizer='adam', loss='mae')
[21]: autoencoder.fit(x_train, x_train,
                      epochs=10,
                     batch_size = 512,
                     shuffle=True,
                     validation_data=(x_test_unofficial_anoms,_
      →x_test_unofficial_anoms))
     Epoch 1/10
     754/754 [============= ] - 31s 41ms/step - loss: 0.1602 -
     val_loss: 0.0869
     Epoch 2/10
     754/754 [============== ] - 30s 39ms/step - loss: 0.0855 -
     val_loss: 0.0869
     Epoch 3/10
```

```
val_loss: 0.0869
Epoch 4/10
754/754 [============= ] - 30s 40ms/step - loss: 0.0855 -
val loss: 0.0869
Epoch 5/10
val loss: 0.0869
Epoch 6/10
val_loss: 0.0869
Epoch 7/10
val loss: 0.0869
Epoch 8/10
754/754 [============== ] - 26s 34ms/step - loss: 0.0855 -
val_loss: 0.0869
Epoch 9/10
val loss: 0.0869
Epoch 10/10
val_loss: 0.0869
```

[21]: <tensorflow.python.keras.callbacks.History at 0x1d829a9eaf0>

0.2 Model Evaluation

To evaluate models we'll first encode a set of data, decode it, then measure the loss between the original data and decoded data.

The losses will then be converted to binary to represent a prediction key of either normal or anomalous events. This will require a threshold for anomalies which we can compute using the mean and standard deviation of losses from the training set without anomalies.

Using the converted prediction key, we can directly compare it to the real anomaly key to get benchmarks. Our anomaly keys are: - unofficial_test_key (original training window) - official_test_key (new testing window) - validation_key (never before seen testing window)

Let's start by getting our threshold hyperparameter:

- 1. Use x train to create normal event reconstructions
- 2. Compute the losses
- 3. Get average and standard deviation of losses
- 4. Set threshold to be almost 2 std > mean loss

```
[130]: # Threshold function on reduced windowed data
normal_reconstructions = autoencoder.predict(x_train)

train_loss = tf.keras.losses.mae(normal_reconstructions, x_train)
```

```
avg_train_loss = np.mean(np.sum(train_loss, axis=2)) # the mean of summed error_u \( \to across rows \)

std_train_loss = np.std(np.sum(test_loss, axis=2)) # the std of summed error_u \( \to across rows \)

threshold = avg_train_loss + std_train_loss*1.880794

print('Mean Loss :', avg_train_loss, '\nStd Loss :', std_train_loss, \( \to '\n\nThreshold \) for Anomalies (rounded) :', threshold)

## Define a function for converting the losses to binary

## Any loss > threshold = anomaly

loss_to_prediction = np.vectorize(lambda loss: 1 if (loss>threshold) else 0)
```

Mean Loss: 2.7365532 Std Loss: 0.3630454

Threshold for Anomalies (rounded): 3.4193667916926147

```
[140]: ### WINDOWED PCA DATA
       print('REDUCED WINDOWED DATA')
       ## Make windowed predictions on x test unofficial
       test_reconstructions = autoencoder.predict(x_test)
       test_loss_6x32 = tf.keras.losses.mae(test_reconstructions, x_test).numpy()
       ## Take mean of each row in each window
       test_loss_6x1 = np.sum(test_loss_6x32, axis=2)
       ## Convert test_loss to anomaly predictions
       prediction_windows = loss_to_prediction(test_loss_6x1)
       ## Convert windowed predictions to array
       predictions = np.array([(1 if
           sum(np.diagonal(np.fliplr(prediction_windows[row:
       →row+window_size])))==window_size else 0)
          for row in range(len(prediction_windows)-window_size)])
       key = official_test_key[:-window_size]
       ## Benchmarcks
       print(confusion_matrix(key, predictions), end = '\n\n')
       print('Accuracy:', round(accuracy_score(key, predictions), 4)) # of all_u
       → predictions, how many were correct?
       print('Precision:', round(precision_score(key, predictions), 4)) # of predicted_
       → anomalies, how many were correct?
```

```
print('Recall:', round(recall_score(key, predictions), 4)) # of all true

→ anomalies, how many were recovered?
```

```
[[74705 20519]
[ 3758 1012]]
```

Accuracy: 0.7572 Precision: 0.047 Recall: 0.2122

The issue here is, the errors look exactly like the normal messages. To find errors, we need a feature that captures the order of message groups within a specific type of block ID. For example, a block ID that was received cannot be in a state of receiving after being received. Thus we need to organize our data around the unique block IDs and to model their sequences.

Let's try a more basic autoencoder that flattens all the data.

```
[171]: | # REDUCED DATA WINDOW MODEL --> precidion of almost 30% on window of 6
       class AnomalyDetector(Model):
         def __init__(self):
           super(AnomalyDetector, self).__init__()
           self.encoder = tf.keras.Sequential([
               layers.Flatten(),
               layers.Dense(32, activation='relu'),
               layers.Dense(16, activation='relu'),
               layers.Dense(8, activation='relu')])
           self.decoder = tf.keras.Sequential([
               layers.Dense(16, activation='relu'),
               layers.Dense(32, activation='relu'),
               layers.Dense(192, activation='sigmoid'),
               layers.Reshape((6, 32))])
         def call(self, x):
           encoded = self.encoder(x)
           decoded = self.decoder(encoded)
           return decoded
       autoencoder = AnomalyDetector()
       autoencoder.compile(optimizer='adam', loss='mae')
```

```
print('x_test_unofficial_anoms:', x_test_unofficial_anoms.shape)
     x_test_unofficial = tf.convert_to_tensor(windows[:400000], dtype=np.float32)
     print('x_test_unofficial:', x_test_unofficial.shape)
     print()
     x_test = tf.convert_to_tensor(windows[400000:500000], dtype=np.float32)
     print('x_test:', x_test.shape)
     validation = tf.convert_to_tensor(windows[500000:600000], dtype=np.float32) #
     print('validation:', validation.shape)
    Training after anomaly removal: (385675, 6, 32)
    x_test_unofficial_anoms: (14325, 6, 32)
    x_test_unofficial: (400000, 6, 32)
    x_test: (100000, 6, 32)
    validation: (99994, 6, 32)
[172]: autoencoder.fit(x_train, x_train,
                epochs=8,
                batch_size = 512,
                 shuffle=True,
                 validation_data=(x_test_unofficial_anoms,_
     →x_test_unofficial_anoms))
    Epoch 1/8
    754/754 [============== ] - 11s 14ms/step - loss: 0.1876 -
    val_loss: 0.0870
    Epoch 2/8
    754/754 [============== ] - 14s 18ms/step - loss: 0.0855 -
    val_loss: 0.0869
    Epoch 3/8
    val_loss: 0.0869
    Epoch 4/8
    val_loss: 0.0867
    Epoch 5/8
    val_loss: 0.0866
    Epoch 6/8
    val_loss: 0.0861
    Epoch 7/8
    val_loss: 0.0858
    Epoch 8/8
```

```
val_loss: 0.0853
[172]: <tensorflow.python.keras.callbacks.History at 0x1dda58812e0>
[173]: # Threshold function on reduced windowed data
      normal_reconstructions = autoencoder.predict(x_train)
      train_loss = tf.keras.losses.mae(normal_reconstructions, x_train)
      avg_train_loss = np.mean(np.mean(train_loss, axis=0)) # the mean row error //u
       \hookrightarrow float(tf.math.reduce_mean(train_loss))
      std_train_loss = np.mean(np.std(train_loss, axis=0)) # the std of row error //_
       \rightarrow float(tf.math.reduce_std(train_loss))
      threshold = avg_train_loss + std_train_loss*1.880794 # for 97% of data
      print('Mean Loss:', avg_train_loss, '\nStd Loss:', std_train_loss, __
       ## Define a function for converting the losses to binary
      ## Any loss > threshold = anomaly
      loss_to_prediction = np.vectorize(lambda loss: 1 if (loss>threshold) else 0)
     Mean Loss: 0.083813615
     Std Loss: 0.011368076
     Threshold for Anomalies: 0.10519462487187796
[174]: ### WINDOWED PCA DATA
      print('REDUCED WINDOWED DATA\n')
      ## Make windowed predictions on x test
      test_reconstructions = autoencoder.predict(x_test)
      test_loss = tf.keras.losses.mae(test_reconstructions, x_test).numpy()
      ## Convert test loss to anomaly predictions
      prediction_windows = loss_to_prediction(test_loss)
      ## Convert windowed predictions to array
      predictions = np.array([(1 if
          sum(np.diagonal(np.fliplr(prediction_windows[row:
       →row+window_size])))==window_size else 0)
          for row in range(len(prediction_windows)-window_size)])
      key = official_test_key[:-window_size]
```

Benchmarcks

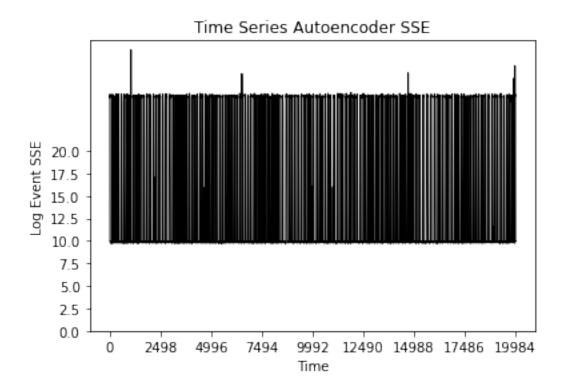
REDUCED WINDOWED DATA

```
[[71026 24198]
[ 3596 1174]]
```

Accuracy: 0.722 Precision: 0.0463 Recall: 0.2461

0.2.1 Visualizing the Reconstruction Loss

```
[138]: encoded_frames = autoencoder.encoder(x_test).numpy()
       decoded_frames = autoencoder.decoder(encoded_frames).numpy()
       sse_per_encoding = tf.math.reduce_sum(tf.math.square(x_test - decoded_frames),_
       \rightarrowaxis = [1,2])
       import matplotlib
       import matplotlib.pyplot as plt
       %matplotlib inline
       fig = plt.figure()
       ax = plt.axes()
       l, u = 0, 19990
       stp = int((u-1)/8)
       ax.plot(sse_per_encoding[1:u], c = 'black', lw = 1)
       ax.set_yticks(np.arange(0,22,2.5))
       ax.set_xticks(np.arange(0,u-1,stp))
       ax.set xlabel('Time')
       ax.set_ylabel('Log Event SSE')
       ax.set_title('Time Series Autoencoder SSE')
       plt.show()
       print('Std of event SSE: ', np.std(sse_per_encoding), '\nMean of event SSE: u
        →', np.mean(sse per encoding), '\n4 std : ', 4*np.std(sse per encoding))
```



Std of event SSE: 8.600297 Mean of event SSE: 17.764029 4 std: 34.401187896728516

[]: