Calculus II

MAT187 Student Slides

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Consider the plot of the complex numbers p_1 , p_2 , p_3 , p_4 in the complex plane.



- 1.1 For which complex numbers is the real part grater than the imaginary part?
- 1.2 Which complex number has the smallest modulus/absolute value?
- 1.3 Which complex number has the largest argument? Is your answer at all ambiguous?

Consider the plot of the complex number p in the complex 2.1 Sketch the complex number 2p.



- 2.2 Sketch the complex number p^2 .
- 2.3 Sketch the complex numbers p^n for n = 3, 4, ... Will your answer depend on r?
- 2.4 Use the geometry of the complex plane to find \sqrt{i} . Express your answer in both polar and rectangular form.

Consider the equation

3.1 Find a solution to Equation (1).

3.3 Find all solutions to Equation (1).

 $z^3 = -1$

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3.2 If
$$z = re^{i\theta}$$
 is a solution to Equation (1), what conditions must r and θ satisfy? Justify your conclusions.
3.3 Find all solutions to Equation (1).

(1)

For each situation, decide whether *least squares* curve fitting or *polynomial interpolation* would be more appropriate.

- 4.1 You are modelling the arch used in the construction of a particular Roman aqueduct. You have collected several hundred data points of height of the arch vs. distance from the base of the aqueduct.
- 4.2 You are creating a function to govern the brightness of a light which will be used for signalling a computer. There are three different brightnesses that must be achieved exactly and the transition between those brightnesses must be smooth.
- 4.3 You are given exact data points from a lab and told that the data was created with a 4th degree polynomial. You are asked to find the coefficients of the polynomial.

A baseball is thrown on the moon. You are trying to find the function

 h(t), the height (in meters) of the baseball above the moon's surface at time t (in seconds).

You collected the following data

t	h(t
1	4
2	3.8
3	2

- 5.2 Use polynomial interpolation to find h.
- 5.3 Find the maximum height of the baseball above the
 - moon's surface.

5.1 What degree polynomial would best model *h*?

5.4 What would change (if anything) if you were given 4 data points?

While developing a robotics control system, you find the 6.2 Complete the following table need for a function f which satisfies the following properties:

(i)
$$f(0) = -1$$
 and $f(1) = 2$

(ii)
$$f'(0) = -1$$
 and $f'(1) = 2$

Your friend suggests that you could use the following polynomial to come up with f:

$$L_1(x) = -(x-1)$$
 $L_2(x) = x$
 $S_1(x) = (x-1)^2 x$ $S_2(x) = (x-1)x^2$

Can Lagrange interpolation be used to directly find f? Explain.

g	g(0)	g(1)	g'(0)	g'(1)
L_1				
L_2				
S_1				
S_2				

- 6.3 Use L_1 , L_2 , S_1 , and S_2 to find a polynomial satisfying the properties of f.
- 6.4 Explain how Lagrange interpolation can be generalized to allow finding a polynomial that passes through particular points and takes on particular derivatives at those points.



7.1 For each polynomial approximation of the bell curve, is the approximation best at 0, best on the interval [-2,2], or best on the interval [0,2].





7.2 Based on the pictures, which polynomial(s) do you think come from a Taylor approximation?

The function *f* satisfies

$$f(0) = 1$$
 $f'(0) = 0$ $f''(0) = -2$
 $f'''(0) = 0$ $f''''(0) = 12$

- 8.1 Write down T_4 , the 4th degree Taylor approximation to *f* centered at 0.
- 8.2 Use Desmos to compare the graph of T_4 with the graphs

of g_1 , g_2 , g_3 , and g_4 . Which of the g's do you think is most likely equal to f?

(a) $g_1(x) = e^{-|x|}$

(b) $g_2(x) = e^{-x^2}$

(c) $g_3(x) = \frac{1}{1+x^2}$ (d) $g_4(x) = \frac{1}{1 + (2x)^4}$

A bee is flying back and forth along a window sill trying to escape from your living room.

The bee's position at time t along the window sill is given by r(t).

You know that a first-order Taylor approximation to r(t) at time t = 2 is

$$A_1(t) = 3(t-2) + 1$$

- 9.1 Estimate the position of the bee on the window sill at time 2.1. Is your answer exact or approximate?
- 9.2 Estimate the velocity of the bee at time 2.1. Is your answer exact or approximate?
- 9.3 Are there any times you can compute the *exact* position of the bee?
- 9.4 Are there any times you can compute the *exact* velocity?
- 9.5 What is your best estimate for the acceleration of the bee at time 2.1?



A bee is flying back and forth along a window sill trying to escape from your living room.

The bee's position at time t along the window sill is given by r(t).

You know that a second-order Taylor approximation to r(t) at time t = 2 is

$$A_2(t) = 2(t-2)^2 + 3(t-2) + 1$$

- 10.1 Estimate the position of the bee on the window sill at time 2.1. Is your answer exact or approximate?
- 10.2 Estimate the velocity of the bee at time 2.1. Is your answer exact or approximate?
- 10.3 Are there any times you can compute the *exact* position of the bee?
- 10.4 Are there any times you can compute the *exact* velocity?
- 10.5 What is your best estimate for the acceleration of the bee at time 2.1?

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Based on the pictures, which polynomial approximations of the bell curve do you think are Taylor polynomials?







tion to *f* centered at 0. In particular $P_3(x) = 1 + x + \frac{x^2}{2} + \frac{x^3}{6}$

Let $f(x) = e^x$ and let $P_n(x)$ be the nth Taylor approxima-

$$+\frac{x^3}{6}$$

Let $R_n(x)$ be the (signed) error in $P_n(x)$.

12.1 Find $R_3(1.5)$ (you may use a calculator).

12.2 What is the largest value of $R_3(x)$ when $0 \le x \le 2$?

12.3 Is there a value of x for which $R_3(x) = 0$? What does

(a) works for a fixed $x \in [0, 2]$ (b) works simultaneously for all $x \in [0, 2]$

12.4 Given that $|f^{(5)}(x)| \le 8$ when $x \in [0, 2]$, find an upper

12.5 Given what you know from the previous part(s), can you bound $R_n(x)$?

this say about P_3 ?

bound for $R_4(x)$ that

Let f be an infinitely differentiable function, and let P_n be a Taylor polynomial for f of degree n centered at a.

We approximate $f(x) \propto P_n(x)$. Which of the following affect the size of the error in $P_n(x)$ (i.e., the magnitude of

We approximate $f(x) \approx P_n(x)$. Which of the following affect the size of the error in $P_n(x)$ (i.e., the magnitude of $R_n(x)$)?

- (A) The degree of P_n , i.e., n.
- (B) The magnitude of f(a), i.e., |f(a)|.
- (C) The magnitudes of the derivatives of f at a, i.e., the size of |f'(a)|, |f''(a)|, etc..
- (D) The distance from a that you are approximating at, i.e., the size of |x-a|.

Use Desmos to conjecture about the following questions.

https://www.desmos.com/calculator/nrru5n0gqq

- 14.1 True/False? When approximating sin(x) using Taylor polynomials centered at x = 0, higher degree polynomials will approximate sin(2) better.
 14.2 True/False? When approximating tan(x) using Taylor polynomials centered at x = 0, higher degree polynomials
- will approximate tan(2) better. 14.3 True/False? When approximating $f(x) = \frac{1}{1+x^2}$ using Taylor polynomials centered at x = 0, higher degree
- 14.3 True/False? When approximating $f(x) = \frac{1}{1+x^2}$ using Taylor polynomials centered at x = 0, higher degree polynomials will approximate f(2) better.
- 14.4 Make a conjecture about the relationship between the degree of your Taylor approximation and the accuracy of its values. Does this contradict what you know from Taylor's remainder theorem?

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Consider the function
$$f(x) = \frac{1}{2}x^2 + 1$$
 and the value \int_0^3

$$I = \int_{-\pi}^{3} f(x) \, \mathrm{d}x.$$

- 15.1 Make three sketches: one where the left-endpoint rule is used to approximate *I*, one where the right-endpoint
 - rule is used, and one where the trapezoid rule is used. (Use at least three intervals.)
- 15.2 For the left-endpoint, right-endpoint, and trapezoid
 - rules, which will give over estimates of *I* and which
- will give underestimates? Will any give an exact value?

15.3 Consider the following estimates of *I*:

- $E_1 = 8.6875$ • $E_2 = 6.4375$
- $E_3 = 7.5625$
- Each estimate comes from using the same partition. Which estimates come from a left-endpoint approxima-
- tion, a right-endpoint approximation, and a trapezoid approximation?
 - Hint: you know calculus!
- 15.4 (Homework) Will the midpoint rule produce an over or under estimate of *I*?

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In a classic problem, you are trying to find the volume of 16.2 a wine barrel. Let $r(\ell)$ represent the radius of the barrel ℓ cm from the base. The total length of the barrel is 80cm.

You know the volume of the barrel can be computed exactly 16.3 by

$$\int_0^{80} \pi [r(\ell)]^2 \,\mathrm{d}\ell.$$

You have measured the barrel in several places and gotten the following data

16.1 Make a sketch of the barrel's profile. Make a second sketch of $\pi[r(\ell)]^2$.

- Based on your sketch, do you think using a trapezoid approximation will produce an over or under estimate for the volume?
- Use a trapezoid approximation to estimate the volume of the barrel.
- 16.4 Use a Simpson's approximation to estimate the volume of the barrel.

Reminder: if *p* is a quadratic polynomial,

$$\int_{a}^{b} p(x) dx = \frac{b-a}{6} \left(p(a) + 4p \left(\frac{a+b}{2} \right) + p(b) \right)$$

16.5 The exact (rounded) volume of the barrel is 104384cm³. What approximation method was most accurate? Why?



For this question, the domain of integration will be 0 to 5 and you will be using a uniform partition with 5 pieces.

- 17.1 Draw a function where the left endpoint approximation is an *under estimate*.
- 17.2 Draw a function where the right endpoint approximation is an *under estimate*.
- 17.3 Draw a function where the trapezoid approximation is an *under estimate*.
- 17.4 Draw a function where the midpoint approximation is an *under estimate*.



The graph above is of the function f. Marked on the graph are the intervals A = [0,2], B = [2,4], and C = [4,8]. We

are interested in the quantity $I = \int_0^8 f(x) dx$.

- 18.1 On each interval, identify whether left/right/mid-point/trapezoid approximations will produce an
 - (a) Underestimate
 - (b) Overestimate
 - (c) Cannot be determined
- 18.2 Is there any interval where you're confident that Simpson's rule would produce an over/under estimate?
- 18.3 Come up with a strategy (i.e., a choice of integration method for each interval) that gives the best possible upper and lower bounds for I.

Given an interval [a, b] the midpoint-rule (with one interval) says to use (b-a)f(0.5a+0.5b) as an estimate for

$$I = \int_{a}^{b} f(x) \, \mathrm{d}x.$$

A biased midpoint rule with bias $\alpha \in [0,1]$ uses $(b-a)f(\alpha a + (1-\alpha)b)$ as an estimate for I.

19.1 Is there a bias
$$\alpha$$
 so that with a single partition, $\int_0^1 x^2 dx$ is *perfectly* approximated? If so, what is the bias?

19.2 Is there a bias
$$\alpha$$
 so that with *two* partitions, $\int_0^1 x^2 dx$ is *perfectly* approximated? If so, what is the bias?

- 20.1 Explain to your table: What is the difference between a sequence and a series?
- 20.2 How can you produce a sequence from a series?
- 20.3 How can you produce a series from a sequence?
- 20.4 Give an example of a bounded sequence that when summed produces an unbounded series.

Define the sequence a_n by $a_n = \sin(\pi n)$ and the function f by $f(x) = \sin(\pi x)$.

- 21.1 Find $\lim_{n\to\infty} a_n$, if it exists.
- 21.2 Find $\lim_{x\to\infty} f(x)$, if it exists.
- 21.3 What is the difference between a sequence and a function.

Define

$$a_n = \frac{4+n}{2+n}$$
 $b_n = \frac{(-1)^n}{n^2}$

for $n \ge 1$.

- 22.1 If a_n and b_n define sequences, what values can n take on? (E.g., any number in \mathbb{R} , any number in \mathbb{Z} , etc.)
- 22.2 Malta a plat of a rea mand h rea m
- 22.2 Make a plot of a_n vs. n and b_n vs. n. 22.3 Which sequences (out of a_n and b_n) are (i) bounded above, (ii) bounded below, (iii) strictly increasing, (iv) strictly
 - decreasing, (v) alternating.
- 22.4 Define $c_n = a_{n-1} + b_{2n}$ for $n \ge 2$. Find a formula for c_n .
- 22.5 Based on your answer to Part 3, will c_n be bounded above or below? Neither?
- 22.6 Find $\lim_{n\to\infty} c_n$.

$$S_n = \sum_{i=1}^n a_n.$$

Let $S_{\infty} = \lim_{n \to \infty} S_n$.

- 23.1 Which of the following statements must be true?
 - (a) If $|a_n| \ge 1$ for all n, then S_n converges.
 - (b) If $|a_n| \le 1$ for all n, then S_n converges.
 - (c) If $|S_n| \ge 1$ for all n, then a_n diverges.
 - (d) If $|S_n| \le 1$ for all n, then a_n diverges.
 - (e) If $a_n \to 0$ then S_n converges.

23.2 If you switch *converges* ↔ *diverges*, which statements change their truth value? (I.e., switch from being true to false or false to true.)

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Consider the function f(x) = 1/x, the sequence $a_n = 1/n$ 24.2 Use Σ -notation to write down a formula for the rightand the sequence of partial sums $S_n = \sum_{i=1}^{n} a_i$.

whose intervals are width 1.

In this question we want to get bounds on the series

$$\sum_{i=1}^{\infty} a_i$$

endpoint approximation of $\int_{1}^{n} \frac{1}{x} dx$ using a partition whose intervals are width 1.

24.3 Use the actual value of $\int_{1}^{\pi} \frac{1}{x} dx$ to give upper and lower bounds for S_n .

24.4 Does S_n converge or diverge? Explain.

24.1 Use Σ -notation to write down a formula for the leftendpoint approximation of $\int_{1}^{n} \frac{1}{x} dx$ using a partition

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Consider the function
$$f(x) = 1/x^2$$
, the sequence $a_n = 25.2$ Use Σ -notation to write down a formula for the right-
$$1/n^2 \text{ and the sequence of partial sums } S_n = \sum_{i=1}^n a_i.$$
endpoint approximation of $\int_1^n \frac{1}{x^2} \, \mathrm{d}x$ using a partition whose intervals are width 1.

In this question we want to get bounds on the series

$$\sum_{i=1}^{\infty} a_i$$

25.3 Use the actual value of $\int_{1}^{n} \frac{1}{x^2} dx$ to give upper and lower bounds for S_n .

Use Σ -notation to write down a formula for the left- 25.4 Does S_n converge or diverge? Explain. endpoint approximation of $\int_{1}^{n} \frac{1}{x^2} dx$ using a partition whose intervals are width 1

25.5 Conjecture about the convergence of $\sum_{i=1}^{\infty} i^{\alpha}$ for $\alpha > 0$.

Can you justify your answer by comparing with known

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integrals?

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$$a_n = \frac{1}{\sqrt{n}}$$
 $b_n = \frac{1}{n^3}$ $c_n = e^{-n}$ $d_n = e^{-n^2}$

and consider the corresponding sequences of partial sums A_n , B_n , C_n , and D_n . (I.e., $A_n = \sum_{i=1}^n a_i$, etc.)

- 26.1 Use a comparison with known integrals to decide the convergence of A_n , B_n , C_n .
- 26.2 Can you decide the convergence of D_n using a comparison to a known integral? Explain.

Consider the function $f(x) = \sin(x)$.

- 27.1 Write down $T_k(x)$, the kth Taylor approximation to f centered at 0. You may use "..." notation or Σ -notation.
- 27.2 Write down, using Σ -notation, T(x), the Taylor series for f centered at 0.
- 27.3 In general a Taylor series may be written as $\sum_{n=0}^{\infty} a_n \frac{x^n}{n!}$, where a_n is a sequence. Find a_n in this case.
- 27.4 Let $R_k(x) = f(x) T_k(x)$. Find an expression for $R_k(x)$ using Taylor's Remainder Theorem. Use your expression to find an upper bound for $|R_k(x)|$ (Hint: your bound may depend on x).
- 27.5 Using the fact that for any $\alpha \in \mathbb{R}$, $\lim_{n \to \infty} \frac{\alpha^n}{n!} = 0$, find $\lim_{k \to \infty} R_k(x)$.
- 27.6 For which *x* is f(x) = T(x)? Justify your answer.

Consider the function $g(x) = \frac{1}{1-x}$. The kth Taylor approxi- 28.1 For which x is $\lim_{k\to\infty} R_k(x) = 0$? mation of g centered at 0 is

$$T_k(x) = \sum_{i=0}^k x^k$$

and the remainder $R_k(x) = g(x) - T_k(x)$ satisfies

$$|R_k(x)| \le \frac{1}{1-x} \left(\frac{x}{1-x}\right)^{k+1}$$

when $x \ge 0$ and

$$|R_k(x)| \le x^{k+1}$$

when x < 0.

- 28.2 Let T(x) be the Taylor series for g centered at 0. For
- which x can you guarantee that g(x) = T(x)?
- 28.3 Use the following Desmos link to numerically answer the question: for which x does g(x) = T(x)?
- https://www.desmos.com/calculator/yi4qczkxqn 28.4 Does your answer to the previous part contradict Tay
 - lor's remainder theorem?

Let
$$f(x) = \sin(x)$$
 and let

$$T(x) = \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n+1}}{(2n+1)!}$$

be the Taylor series for f centered at 0. We know that

be the Taylor series for
$$f$$
 centered at 0. We know th $f(x) = T(x)$ for all $x \in \mathbb{R}$.

- 29.1 Find a series representation for $g_1(x) = f(2x)$ (with-

29.2 Find a series representation for $g_2(x) = f(x^2)$.

out computing any derivatives).

29.4 Compute $g_3(x) = \int g_2(x) dx$ by integrating your series for $g_2(x)$ term by term. What should you do with the constants of integration?

29.3 Use WolframAlpha to integrate g_2 . Does WolframAl-

pha's solution make sense?

- 29.5 For which x do you expect $g_3(x)$ to be valid? Explain.
 - 29.6 When would it be advantageous to integrate a Taylor series term by term instead of integrating the original function? Explain.

Let
$$f(x) = \frac{1}{1-x}$$
 and let

$$T(x) = \sum_{n=0}^{\infty} x^n$$

be the Taylor series for f centered at 0. We know that f(x) = T(x) for all $x \in (-1,1)$.

- 30.1 Find a series representation for $g_1(x) = f(2x)$ (without computing any derivatives).
- 30.2 For which x do you expect your series for $g_1(x)$ to be valid (i.e. to equal f(2x)? Explain.
- 30.3 Find a series representation for $g_2(x) = f(x^2)$.
- 30.4 Compute $g_3(x) = \int g_2(x) dx$ by integrating your series for $g_2(x)$ term by term.
- 30.5 For which x do you expect $g_3(x)$ to be valid? Explain.

The function *f* has a Taylor series centered at 0 of the form

$$T(x) = -\frac{1}{2} + \frac{x}{3} - \frac{x^2}{4} + \frac{x^3}{5} - \frac{x^4}{6} + \cdots$$

- Express T using Σ -notation.
- 31.2 Find a series representation for f'(x) and $\int f(x) dx$.
- 31.3 Modify the following Desmos link and make a conjecture: for which values of x is f(x) = T(x)? https://www.desmos.com/calculator/try63qzvo5
- 31.4 Based on your conjecture, for which values of x should your series for f'(x) and $\int f(x) dx$ be valid?

Recall

$$\int_{n=0}^{\infty} for all x \in \mathbb{R}.$$

Let $f(x) = \cos(\sqrt{x})$.

32.1 Write down a Taylor series, T, for f.

Hint: you don't need to take any derivatives.

 $\sin x = \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n+1}}{(2n+1)!} \qquad \cos x = \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n}}{(2n)!}$

$$=\sum_{n=0}^{\infty}(-$$

$$(-1)^n \frac{3}{(2)^n}$$

32.2 Find $f^{(6)}(0)$.

32.3 For what x is T(x) = f(x)? Explain. 32.4 Using Desmos, make a conjecture: for which values of

x does your series converge?

https://www.desmos.com/calculator/try63qzvo5

32.5 Let T be a Taylor series for an unknown function g. If T converges at a value x_0 , must it be true that $T(x_0) = g(x_0)$? Explain.

The sequence a_n is defined by $a_0 = 10$ and

$$\frac{a_{n+1}}{a_n} = \frac{1}{4}$$

Define
$$S_n = \sum_{i=0}^n a_i$$
 and $S = \lim_{n \to \infty} S_n$.

- 33.1 Find an expression for a_n .
- 33.2 Is S_n bounded? Explain.
- 33.3 **Compute** *S*.

Recall:
$$\sum_{i=0}^{n} \alpha^i = \frac{1-\alpha^{n+1}}{1-\alpha}$$

Recall the sequence
$$a_n$$
 from Exercise 33 defined by $a_0 = 10$ and $\frac{a_{n+1}}{a_n} = \frac{1}{4}$.

$$=\frac{1}{4}$$
.

Consider the unknown, positive, sequence
$$b_n$$
. You know that $b_0 = 5$ and $\frac{b_{n+1}}{b_n} < \frac{1}{5}$.

34.1 Do you have enough information to write down an expression for
$$b_n$$
?

expression for
$$b_n$$
?

34.2 Which (if any) of the following relationships must hold

$$a_n < b_n$$
 $b_n < a_n$ $a_n = b_n$

Justify your answer.

34.3 Consider the series
$$\sum_{n=0}^{\infty} b_n$$
. Does the series converge?

34.4 If you were told that, actually,
$$b_0 = 100$$
, would that

change your answer to the previous part?

The ratio test states for a sequence c_n if

$$\lim_{n \to \infty} \frac{|c_{n+1}|}{|c_n|} < 1$$

then
$$\sum_{n=0}^{\infty} c_n$$
 converges.

Recall the sequence
$$a_n$$
 from Exercise 33 defined by $a_0 = 10$ and $\frac{a_{n+1}}{a_n} = \frac{1}{4}$.

$$\frac{1}{4} = \frac{1}{4}$$

w the following the following form
$$\frac{1}{1} = \rho < \frac{1}{2}$$

$$\lim_{n\to\infty}\frac{d_{n+1}}{d_n}=\rho<\frac{1}{5}.$$

$$n \to \infty$$
 d_n

You know the following about the positive sequence
$$d_n$$
:

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verges.

for all *n*?

Justify your answer.

$$a_n < d_n$$
 $d_n < a_n$ $a_n = d_n$

$$< a_n \qquad a_n = a_n$$

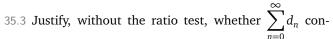
$$\alpha_n$$
 α_n

$$a_n < d_n$$
 $d_n < a_n$ $a_n = d_n$

$$a_n = d_n$$

$$a_n < a_n$$
 $a_n = a_n$













Theorem (Ratio Test). If c_n is a sequence and

$$\lim_{n\to\infty}\frac{|c_{n+1}|}{|c_n|}=\rho$$

then $\sum_{n=0}^{\infty} c_n$

- \blacksquare converges if $\rho < 1$
- diverges if $\rho > 1$
- **c**ould converge or diverge if $\rho = 1$

36.1 The Ratio Test talks about the convergence of $\sum_{n=0}^{\infty} c_n$.

Does it also apply to sums that don't start at n = 0? Explain.

- 36.2 Apply the ratio test to determine the convergence of the following series:
 - (a) $\sum_{n=1}^{\infty} \frac{2^n}{n!}$
 - (b) $\sum_{n=1}^{\infty} \frac{8^n}{(-2)^{n+1}n^n}$
 - (c) $\sum_{n=1}^{\infty} \frac{1}{n}$

The Taylor series for $f(x) = \frac{1}{1-2x}$ is

$$T(x) = \sum_{n=0}^{\infty} 2^n x^n$$

- 37.1 Apply the ratio test to T(x). Does T(x) converge? Does your answer depend on x?
- 37.2 Let G(x) be the Taylor series for $g(x) = e^x$. Apply the ratio test to G(x). Does your answer depend on x?
- 37.3 Write down the largest (open) interval of convergence and the radius of convergence for *T* and *G*.

The Taylor series for $h(x) = \frac{1}{1-x}$ centered at a > 1 is

$$H(x) = \sum_{n=0}^{\infty} \frac{(x-a)^n}{(1-a)^{n+1}}.$$

- 38.1 Find the largest (open) interval of converge and radius of convergence for *H*.
- 38.2 Graph *h*. Just looking at the graph, can you determine whether a Taylor series for *h* should have an infinite or finite radius of converge?

Theorem (Integration by Parts). If
$$f(x)$$
 and $g(x)$ are differentiable functions, then
$$\int f(x)g'(x) dx = f(x)g(x) - \int f'(x)g(x) dx$$

39.1 The integration by parts formula comes from reversing one of the differentiation rules (e.g., chain rule/product rule/quotient rule). Which rule does the integration by parts formula come from? 39.2 Let $h_1(x) = x \sin x$.

- (a) For h_1 , write down all the ways to divide it into a product of "parts" f and g' so that $h_1 = f \cdot g'$.
- (b) Pick the decomposition into parts that you think will be most useful and integrate h_1 .
- 39.3 Let $h_2(x) = x^3 e^{x^2}$.
 - (a) For h_2 , write down all the ways to divide it into
 - a product of "parts" f and g' so that $h_2 = f \cdot g'$. (b) Pick the decomposition into parts that you think will be most useful and integrate h_2 .

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Theorem (Integration by Parts). If f(x) and g(x) are differentiable functions, then

$$\int f(x)g'(x) dx = f(x)g(x) - \int f'(x)g(x) dx$$

- 40.1 Use integration by parts to find $\int e^x \sin x \, dx$.
- Hint: if at first you don't succeed, try, try again. 40.2 Use integration by parts to find $\int_{0}^{2} \ln x \, dx$.
 - Hint: sometimes g is hiding in plain sight.

We would like to compute

$$F(\theta) = \int \sin^2(\theta) \, \mathrm{d}\theta$$

41.1 (Review) Use integration by parts to find $F(\theta)$.

Hint: The identity $1 = \cos^2 \theta + \sin^2 \theta$ may reduce your workload.

- 41.2 Use the trig identity $\sin^2 \theta = \frac{1 \cos 2\theta}{2}$ to find $F(\theta)$.
- 41.3 Find $\int \cos^2(\theta) d\theta$ using any method you like.

Let $f(x) = \sqrt{1 - x^2}$ and consider

$$I = \int_0^1 f(x) \, \mathrm{d}x$$

42.1 If we define a change of variables $x = \sin \theta$, what would dx equal?

42.2 Apply the substitution
$$x = \sin \theta$$
 to get a new function

 $g(\theta)$ so that

$$\int_0^1 f(x) dx = \int_2^2 g(\theta) d\theta$$

Find the function *g* and the bounds for the new integral (i.e. fill in the ?'s).

42.3 Find I.

42.4 Graph f. What shape does the graph make? Use your

knowledge of geometry to find *I*.

In Exercise 42 we computed

$$I = \int_0^1 \sqrt{1 - x^2} \, \mathrm{d}x = \int_0^{\pi/2} \cos^2 \theta \, \mathrm{d}\theta$$

- 43.1 Explain why the bounds changed from [0,1] to $[0,\pi/2]$.
- 43.2 Would it be okay to change the bounds from [0,1] to $[2\pi, 5\pi/2]$?
- 43.3 Would it be okay to change the bounds from [0,1] to $[0,5\pi/2]$?
- 43.4 Compute I using the substitution $x = \cos \theta$. Pay close attention to make sure you use the correct bounds.

Let $f(x) = \frac{\sqrt{9-x^2}}{x^2}$ and consider

$$F(x) = \int f(x) \, \mathrm{d}x$$

Using a substitution of $x = 3 \sin \theta$, we arrive at

$$F(x) = -\frac{\cos \theta}{\sin \theta} - \theta + C.$$

- 44.1 Find an expression for F(x) that involves only x.
- 44.2 Are there restrictions on domain of x for which your answer makes sense?
- 44.3 The domain of arcsin is [-1,1]. Does this change your restrictions on the domain of x?

Let $f(x) = \sqrt{\cos x}$ and consider

$$I = \int_0^{\sqrt{2}} f(x) \, \mathrm{d}x$$

You would like to find *I*.

- 45.1 Use WolframAlpha to find an anti-derivative of f. Does WolframAlpha give you a useful answer?
- 45.2 Using a 2^{nd} degree Taylor approximation for cos, write down an integral that will approximate I.
- 45.3 Find an approximation for *I*.
- 45.4 Use a 2^{nd} degree Taylor approximation for f to approximate I.
- 45.5 Desmos claims $I \approx 1.15686930348$. Which of your estimates is more accurate?

$$f(x) = \frac{1}{x^2 - 1}$$
 and $g(x) = \frac{A}{x - 1} + \frac{B}{x + 1}$.

- 46.1 You would like to know if there are constants *A* and *B* such that f(x) = g(x) for all *x*.
 - Set up a system of linear equations (or a matrix equation) which has a solution if and only if there are constants A and B that make f(x) = g(x) for all x (in the domain of f).
- 46.2 Find *A* and *B*, if possible.
- 46.3 Compute $\int f(x) dx$ using any method of your choice.

Let

$$f(x) = \frac{1}{(x-1)x^2}$$
 and $g(x) = \frac{A}{x-1} + \frac{B}{x}$.

47.1 You would like to know if there are constants A and B such that f(x) = g(x) for all x.

Set up a system of linear equations (or a matrix equation) which has a solution if and only if there are constants A and B that make f(x) = g(x) for all x (in the domain of f).

47.2 Find A and B, if possible.

47.3 Let $h(x) = \frac{A}{x-1} + \frac{B}{x} + \frac{C}{x^2}$. Can you find constants A, B, and C so that f(x) = h(x) for all x (in the domain of f)? If so, do it.

47.4 Compute $\int f(x) dx$ using any method of your choice.

We know $\int \frac{1}{x^2+1} dx = \arctan x + C$. However, we can also use partial fraction decomposition over the complex numbers to integrate.

Let
$$f(x) = \frac{1}{1+x^2}$$
 and $g(x) = \frac{A}{1+ix} + \frac{B}{1-ix}$.

- 48.1 Find *A* and *B* so that f(x) = g(x) for all x (in the domain of f).
- 48.2 Compute $\int f(x) dx$ using your result from the previous part.

However: use $\ln x$ as the antiderivative of $\frac{1}{x}$ rather than $\ln |x|$.

48.3 Use the fact that $\ln(re^{i\theta}) = \ln r + i\theta$ to simplify your answer.

An improper integral formalizes the concept of the area under an "infinite" curve.

Suppose
$$f$$
 is a bounded function and let $I = \int_{0}^{\infty} f(x) dx$.

- 49.1 Write down a formal definition of *I*.
- 49.2 Compute, using the definition, $\int_0^\infty \frac{1}{(x+1)^2} dx$
- 49.3 Compute, using the definition, $\int_{0}^{\infty} \frac{1}{(x+1)} dx$

Let
$$f(x) = \frac{x}{x^2 + 1}$$

In this question, we will try to compute

$$Q = \int_{-\infty}^{\infty} f(x) \, \mathrm{d}x$$

0.1 Graph
$$f$$
. Make a guess on what

50.1 Graph f. Make a guess on what you think the "total area under the curve" (i.e. Q) should be.

50.2 Find
$$\int f(x) dx$$

$$\int_{0}^{N}$$

50.3 Compute
$$\lim_{N\to\infty}\int_{-N}^{N}f(x)dx$$
. Should your result be

equal to Q?

50.4 Should
$$\lim_{N \to \infty} \int_{-N}^{2N} f(x) dx$$
 correspond to *Q*? Compute it and compare with the previous part.

50.5 Compute $A = \int_{0}^{\infty} f(x) dx$ and $B = \int_{0}^{0} f(x) dx$.

50.6 By the properties of integrals, we must have

$$Q = A + B.$$

Do the properties of integrals hold for this improper integral? What does this say about Q?

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The moral of improper integral is:

Wherever an infinity might appear, take a separate limit.

51.1 Rewrite
$$\int_{-\infty}^{\infty} \frac{x}{x^2 + 1} dx$$
 using limits of definite integrals.

- 51.2 Let $g(x) = \frac{1}{x^{1/3}}$ and consider $I = \int_{-8}^{27} g(x) dx$.
 - (a) Identify all regions where $\int g(x) dx$ *could* produce infinities.
 - (b) Rewrite I using limit(s) of definite integrals.
 - (c) Find *I*.

Let
$$f(x) = \frac{\ln|x|}{x^4 + 1}$$

$$J = \int_{-\infty}^{\infty} f(x) dx$$

52.2 Consider the functions

$$\int_{\infty}^{\infty} f(x) dx$$

52.1 Rewrite *J* using limit(s) of definite integrals.

$$b_1(x) = \ln x \qquad b_2(x) = \frac{\ln x}{2}$$

$$b_3(x) = \frac{x}{x^4 + 1}$$
 $b_4(x) = 0$

(a) Let
$$A = \int_0^1 f(x) dx$$
. Find upper and lower bounds for A by comparing with the appropriate b_2 functions.

(b) Let
$$B = \int_{1}^{\infty} f(x) dx$$
. Find upper and lower bounds for B .

52.3 Use your results from the previous part to find upper and lower bounds for J.

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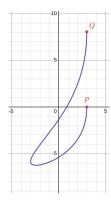


Consider the functions

$$A(t) = t$$
 $B(t) = t^2$ $C(t) = t^{1/2}$
 $D(t) = 2t$ $E(t) = 2t^2$ $F(t) = 2t^{1/2}$

- 53.1 Consider the parametric equations x(t) = A(t) and y(t) = D(t). Graph, by hand, (x, y) for $t \in [0, 4]$.
- 53.2 Consider the parametric equations x(t) = B(t) and y(t) = A(t).
 - Graph, by hand, (x, y) for $t \in [0, 4]$.
- 53.3 Identify all possible assignments of x(t) = ?? and y(t) = ?? (where ?? come from the functions above) so that the graph of (x, y) for $t \in [0, 4]$ is a line segment.
- 53.4 Out of your examples above, which example produces the *longest* line segment?

Shown is the graph of $\begin{cases} x(t) = 3\cos t \\ v(t) = t^2 - 5t \end{cases}$

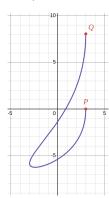


for $t \in [0, 2\pi]$.

The parametric equations describe the position of a particle at time t.

- 54.1 Is the particle moving from *P* to *Q* or *Q* to *P*? Explain.
- 54.2 At what time(s) is the particle moving up *and* to the right?
- 54.3 At what time(s) is the particle moving parallel to the x-axis?
- 54.4 Find the tangent line to the particles path at time $t = \pi/2$.

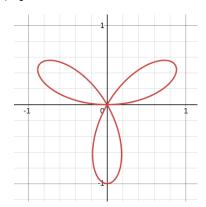
Shown is the graph of
$$\begin{cases} x(t) = 3\cos t \\ y(t) = t^2 - 5t \end{cases}$$
 for $t \in [0, 2\pi]$.



The parametric equations describe the position of a particle at time t.

- 55.1 Find a parameterization for a particle that traces the same path, but starts at Q and ends at P.
- 55.2 Find a parameterization so that the particle finishes its journey in π seconds instead of 2π seconds.
- 55.3 Is there a parameterization so that the particle finishes its journey in π seconds but starts its journey at the same speed as the original particle? If such a parameterization exists, how would you come up with it?

Shown is the graph of $r(\theta) = \sin(3\theta)$ in polar coordinates The curve models the boundary of a propeller. for $\theta \in [0, \pi]$.



- The blade in the first quadrant achieves a maximum length at an angle of $\theta = \pi/6$. Find the rectangular coordinates of the tip of the blade in the first quadrant.
- 56.2 Find parametric equations (x(t), y(t)) that trace out the propeller.
- 56.3 Find the tangent line to the propeller when $\theta = 0$ and when $\theta = \pi/3$.
- 56.4 We know that the propeller is contained in a circle with area π .

Come up with a better upper bound for the area of the propeller.

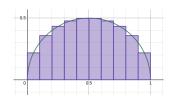
The same semi-circle can be described in polar coordinates by

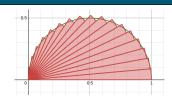
$$r(\theta) = \cos \theta$$
 with $\theta \in [0, \pi/2]$

or in rectangular coordinates by

$$y(x) = \sqrt{\frac{1}{4} - \left(x - \frac{1}{2}\right)^2}$$
 with $x \in [0, 1]$.

Below are two ways to divide up the semicircle to approximate its area: one with rectangles and one with circular sectors.

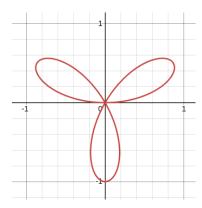




- 57.1 Write down a Riemann sum that approximates the area using rectangles. Use Δx as the width of a rectangle.
- 57.2 Write down a Riemann sum that approximates the area using sectors. Use $\Delta\theta$ as the sector angle.
- 57.3 Take limits of your previous two Riemann sums to find integrals that represent the exact area of the semicircle. Do not evaluate your integrals.
- 57.4 Which integral would you rather do?
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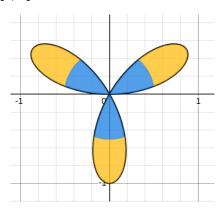


Shown is the graph of $r(\theta) = \sin(3\theta)$ in polar coordinates The curve models the boundary of a propeller. for $\theta \in [0, \pi]$.



- The first propeller blade is traced out for $\theta \in [0, \pi/3]$ Set up a Riemann sum that approximates the area of the first propeller blade.
- 58.2 Set up an integral that will give the exact area of the first propeller blade. Then, find the area of the first propeller blade.
- 58.3 Find the total area of the propeller.

Shown is the graph of $r(\theta) = \sin(3\theta)$ in polar coordinates for $\theta \in [0, \pi]$.



The curve models the boundary of a propeller. The parts of the propeller within distance 1/2 of the origin are painted blue. The rest is painted yellow.

- 59.1 Consider the propeller blade in the first quadrant. At what angle does the yellow paint start to appear? At what angle does it disappear?
- 59.2 Set up an integral that will give the amount of yellow paint needed for the first blade.
- 59.3 Set up an expression with integral(s) that will give the amount of blue paint needed for the first blade.
- 59.4 Find the amounts of each paint needed to paint the whole propeller.



60.1 Which of the following are solutions to the ODE t y' - 6y = 18

- (a) $y = 8 3t^6$
- (b) $y = 3t^6 8$
- (c) $y = 8t^6 3$
- (d) $y = 3 8t^6$
- (e) $y = t^6 3$

 $y'' = \cos(t)y' + t^3$

60.2 Consider the differential equation

- (a) What is the order of the ODE?
- (b) Is the ODE linear?

Consider y'(t) = 5y(1-y)

- 61.1 What do we call the special values y = 0 and y = 1? (*Hint: think back to MAT186.*)
- 61.2 Draw a phase diagram for the ODE.

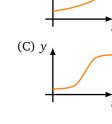


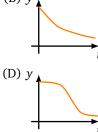
61.3 Which of the following plots show a possible solution

condition y(0) = 0.2?

(A) y(B) y

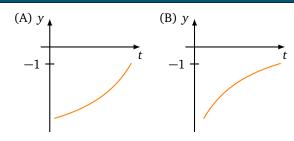
with initial condition y(0) = 1.5? What about initial





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$$y' = y^2$$



- 62.2 Sketch a slope field for this ODE.
- 62.3 Make sketches of all *qualitatively different* solutions to this ODE (i.e., all solutions whose shape is fundamentally different).
- 62.1 Which of the following could be sketches of solutions to this ODE?

3 litre/minute.

Level 1 Modelling

Let y(t) denote the mass (measured in grams) at time t of a chemical substance in a full 150 litre tank. A so- 63.4 lution of water and the chemical with a concentration of 10 grams/litre is pumped into the tank at a rate of

3 litres/minute. Assuming the tank is well mixed at all

times, the contents is pumped out of the tank at a rate of

63.1 What are the units of $\frac{dy}{dt}$?

63.2 At what rate is the chemical substance entering the tank? What should these units be?

cal in the 150 litre tank, write down an initial value problem modeling the amount of chemical in the tank. 63.5 Without solving the IVP, do we expect the amount of

chemical in the tank to initially increase or decrease?

63.6 You got a differential equation that looks like y' =F(y). Can you solve this differential equation by in-

tegrating both sides? I.e., is $\int F(y) dy$ a solution? Explain.

63.3 At what rate is the chemical substance exiting the

Assuming there is initially 100 grams of the chemi-

tank? What should these units be?

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Level 2 Modelling

In this problem we use the same setup as before but with one minor tweak: substance is being pumped out at 2 litres/minute (instead of 3). The same 3 litres/minute is being pumped into the tank at the same concentration stated previously. Assume the 150L tank initially has only 50 litres of fluid in it with 100 grams of chemical inside.

- 64.1 Write down an initial value problem modeling the amount of chemical in the tank.
- 64.2 For what interval of time is this an appropriate model?

Level 3 Modelling

In this problem we use the same setup as in Level 2 but now when the tank reaches 150 litres it begins to overflow, spilling the well mixed solution out of the top of the tank. (Assume an initial volume of 50 litres in the tank with 100 grams of chemical, the 3 litre/min inflow and 2L/min outflow; everything is still perfectly mixed).

65.1 Write down an initial value problem modeling the amount of chemical in the tank. What range of t val- 65.3

ues is your IVP valid for?

65.2 Write down an Initial value problem with a single ODE describing the amount of the chemical in the tank for $t \ge 100$. You may use the solution from Level 2:

$$y(t) = \frac{10(t^3 + 150t^2 + 7500t + 25000)}{(t+50)^2},$$

which satisfies y(100) = 1455.555...

Let y(t) denote the IVP solution to part (a) of this question. Compute $\lim_{t\to\infty} y(t)$.

Apple Products We are modelling the popularity, P(t), of Apple's newest

product over time. Market research shows that a reason- 66.2 able model could be created with the following assumptions:

- (A1) Ignoring all else, popularity grows in proportion to current popularity.
- (A2) Ignoring all else, popularity decreases in proportion

to elapsed time since release.

Popularity is non-negative and can be unbounded.

- 66.3 Assume the constants of proportionality are 1 and

- 66
- plain.

(A1) and (A2).

Come up with explanations for each.

make a slope field for your model using Desmos.

66.1 Are the marketing team's assumptions reasonable?

Write a differential equation based on assumptions

- https://www.desmos.com/calculator/yeusl7guu3
- 66.4 Use Desmos to explore which initial conditions give

Apple Products II

Recall the assumptions for modelling the popularity of a new Apple product.

- (A1) Ignoring all else, popularity grows in proportion to current popularity.
- (A2) Ignoring all else, popularity decreases in proportion to elapsed time since release.
- 67.1 From real-world data, we know that popularity of products eventually ends up near zero. Modify your model so that popularity always ends up at zero.
- 67.2 For certain *timeless* products, the time limit of popularity approaches a positive constant. Modify your model so that popularity will always tend towards a positive constant.