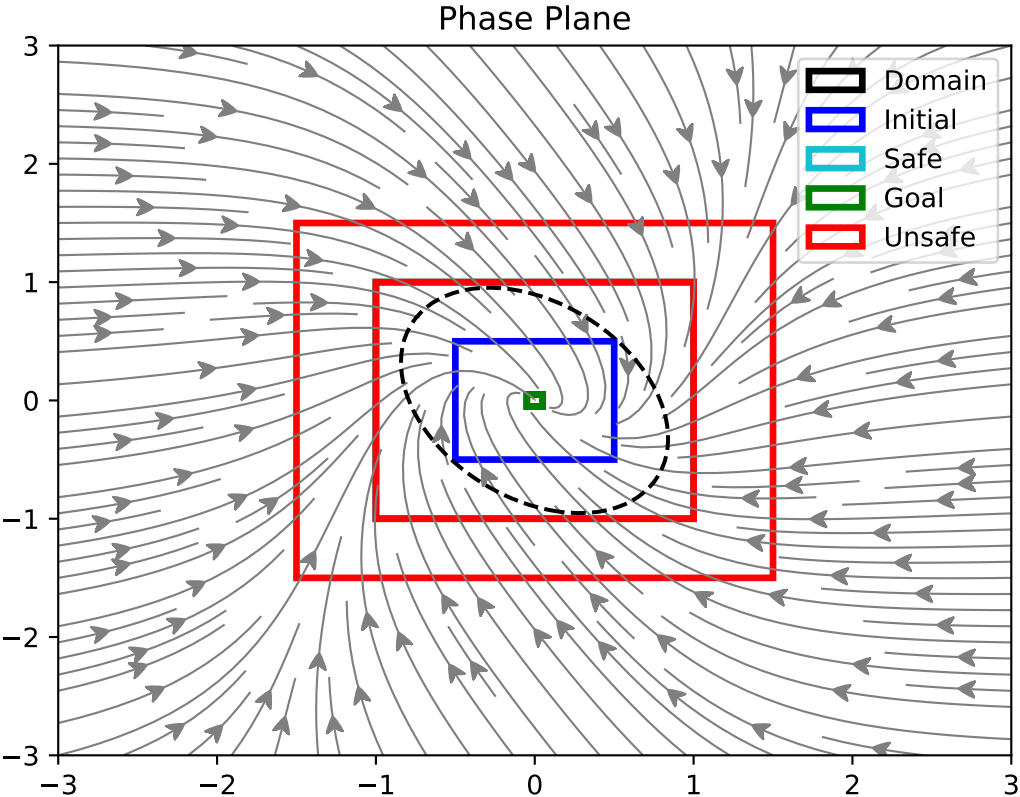
Phase Plane
Domain
Initial
Safe
Goal
Unsafe
3
2
1
0
−1
−2
−3
−3
−2
−1
0
1
2
3