

THE GRADUATE SCHOOL

We recommend that the thesis prepared under our supervision by

Luke Adrian Fraser

Entitled

A Hierarchical Control Architecture for Robust and Adaptive Robot Control

be accepted in partial fulfillment of the requirements for the degree of

MASTER OF SCIENCE

Monica Nicolescu, Advisor

Mircea Nicolescu, Committee Member

David Feil-Seifer, Committee Member

Yantao Shen, Graduate School Representative

David W. Zeh, Ph. D., Dean, Graduate School

May, 2016