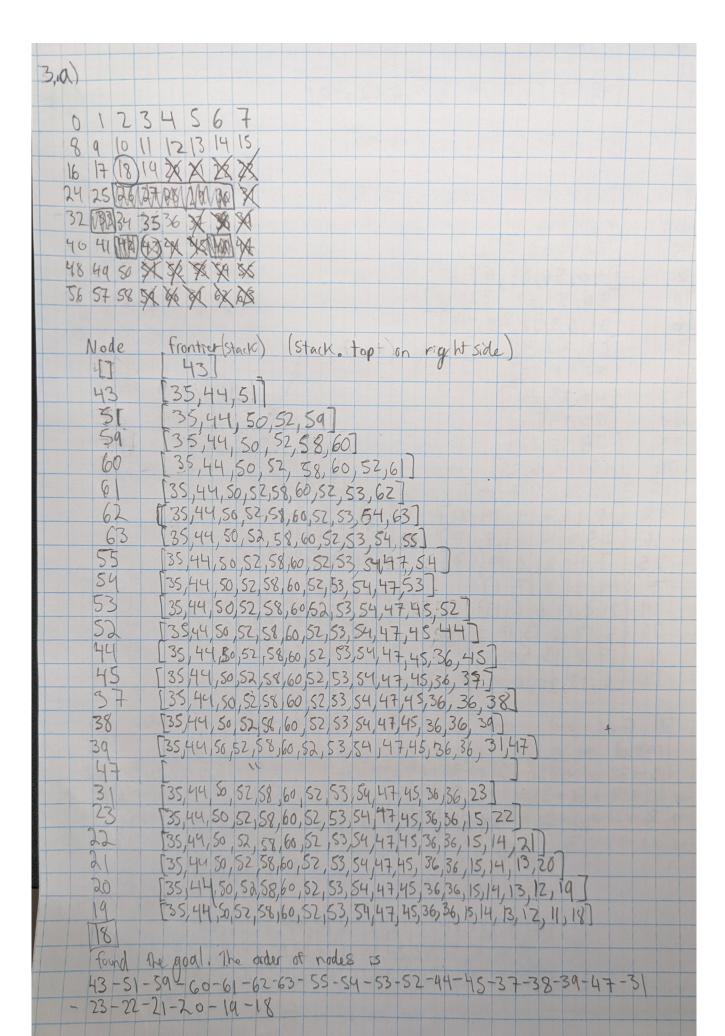
1)

- Playing Soccer:
 - The expected utility: Number of goals scored
 - The environment: Soccer field, players, soccer ball
 - The actions: Kicking, running, passing, shooting, planning plays to score
 - The sensors: Cameras, tracking devices for players and ball
 - Fully Observable: All players, and ball are visible
 - Multi-agent: Multiple players and a soccer ball
 - Stochastic: Injuries, different player skills and strength. Makes it hard to predict the game.
 Goalies will a save percentage that could be based on location of shot. For example, goalie
 A saves 10% of shots that are in the top right corner.
 - Semi-dynamic: The field stays the same, but the players are constantly moving. A player's performance will be different throughout the game based on stamina and adrenaline.
 - Continuous: the state of the game is continuously changing and has infinitely many states.
- Exploring the subsurface of the an ocean:
 - The expected utility: correct analysis of ocean foliage, animals, sea floor terrain, water quality, etc.
 - The environment: The ocean foliage, animals, sea floor terrain, water quality, etc.
 - The actions: Scanning, moving about the ocean.
 - The sensors: Camera's, radar, sonar, other scientific devices to measure desired ocean factor.
 - o Partially: Possible, though improbable to measure all the aspects of the ocean .
 - Multi-agent: Many different attributes to the ocean.
 - Stochastic: Too complex to observe all unobserved attributes.
 - Dynamic: Environment is always changing.
 - Continuous: The state of the environment is always changing.
- Bidding on an item at an auction:
 - The expected utility: Getting the item for the cheapest amount possible
 - The environment: Yourself, other bidders, the item
 - The actions: bidding, waiting
 - The sensors: Timer, people's bid amount
 - Partially observable: You don't know how much each person is willing to pay
 - Multi-agent: Could be many different people bidding on the item
 - Deterministic: The state of the bid is determined by the previous state. If the bid increased, then the next state will be bid increased or item sold
 - Static: The states are the current bid or sold
 - Discrete: Their are a finite number of states and a discrete set of percepts and action

2)

- a) Using only four colours, you have to colour a planar map in such a way that no two adjacent regions have the same colour:
 - States: the state is the colours that have been coloured in so far
 - Initial State: Nothing has been coloured yet
 - Action: Check adjacent regions of what their colours are, and then try each colour that will work. A transition will work if the colour chosen is not the same as its adjacent colours
 - Transition: Colour in a region
 - Goal States: The planar map is completely coloured in such that no adjacent regions are the same colour
 - Action Cost: The cost is the cost of checking all the adjacent regions of the region to be coloured
- b) You have a program that outputs the message "illegal input record" when fed a certain file of input records. You know that the processing of each record is independent of the other records. You want to discover what record is illegal.
 - States: Legal or illegal
 - Initial State: Legal
 - Action: change state to illegal or stay in state legal
 - Transition: If illegal return "illegal input record" else keep going until end of input files
 - Goal States: Illegal input state or empty set of files to process
 - Action Cost: Cost O(how every long it takes to check a file)
- c) You have three jugs measuring 12 gallons, 8 gallons and 3 gallons, and a water faucet. You can fill the jug up, empty it out from one to another or onto the ground. You need to measure out exactly one gallon.
 - State: The measurement of total water at a given instance
 - Initial State: 0 gallons
 - Actions: Fill 1 of the jugs, empty a jug into another, empty jug onto ground
 - Transition: One of the jugs going from empty to full, One jug getting filled by another, one jug getting dumped on the ground
 - Goal States: 1 Gallon of water total
 - Action Costs: Each action costs the amount of water exhanged



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3) c) For C, there where way too many nodes to keep track of so I wrote a program and will post the results of program below, and below the results I will post my source code

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node: 42 depth: 1	
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node: 35 depth: 1
max depth: 10
node: 43 depth: 0
node: 51 depth: 1
node: 59 depth: 2
node: 60 depth: 3
node: 61 depth: 4
node: 62 depth: 5
node: 63 depth: 6
node: 55 depth: 7
node: 54 depth: 8
node: 53 depth: 9
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node: 25 depth: 10
node: 16 depth: 10
node: 49 depth: 5
node: 50 depth: 4
node: 52 depth: 2
node: 50 depth: 2
node: 44 depth: 1
node: 36 depth: 2
node: 42 depth: 1

node: 35 depth: 1
max depth: 11
node: 43 depth: 0
node: 51 depth: 1
node: 59 depth: 2
node: 60 depth: 3
node: 61 depth: 4
node: 62 depth: 5
node: 63 depth: 6
node: 55 depth: 7
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node: 35 depth: 11
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node: 40 depth: 7
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node: 50 depth: 4
node: 52 depth: 2
node: 50 depth: 2
node: 44 depth: 1
node: 42 depth: 1
node: 35 depth: 1

max depth: 12
node: 43 depth: 0
node: 51 depth: 1
node: 59 depth: 2
node: 60 depth: 3
node: 61 depth: 4
node: 62 depth: 5
node: 63 depth: 6
node: 55 depth: 7
node: 54 depth: 8
node: 53 depth: 9
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node: 44 depth: 11
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node: 15 depth: 12
node: 54 depth: 6
node: 53 depth: 5
node: 52 depth: 4
node: 58 depth: 3
node: 57 depth: 4
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node: 48 depth: 6
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node: 41 depth: 8
node: 40 depth: 7
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node: 52 depth: 2
node: 50 depth: 2

node: 44 depth: 1
node: 42 depth: 1
node: 35 depth: 1
max depth: 13
node: 43 depth: 0
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node: 50 depth: 2
node: 44 depth: 1
node: 42 depth: 1
node: 35 depth: 1
max depth: 15
node: 43 depth: 0
node: 51 depth: 1
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node: 60 depth: 3
node: 61 depth: 4
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node: 63 depth: 6
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node: 50 depth: 8 node: 42 depth: 9 node: 41 depth: 10 node: 40 depth: 11 node: 32 depth: 12 node: 24 depth: 13 node: 25 depth: 14 node: 17 depth: 15 node: 18 depth: 16

```
#include <iostream>
#include <utility>
#include <stack>
using namespace std;
// (i, j) location on grid
typedef pair<int, int> pr;
// Convert a number to it's (i, j) location
pr getLoc(const int& n) {
  pr p;
  p.first = n / 8 + 1;
  p.second = n \% 8 + 1;
  return p;
}
// convert (i, j) location to node number
int getNum(const pr& p) {
  return (p.first-1) * 8 + (p.second -1);
}
// Node
typedef struct {
  int num;
  int depth;
} Node;
int main () {
  // Number the nodes
  int arr[10][10];
  int k = 0;
  for (int i = 1; i < 9; ++i) {
     for (int j = 1; j < 9; ++j) {
       arr[i][j] = k++;
     }
   }
  // goal state (node.num == 18)
  bool goal = false;
```

```
// iterative deepening depth-first search
for (int depth = 0; depth < 20; ++depth) {
  // if goal state found then we are done
  if (goal) {
     break;
  // print the current max depth
  cout << "max depth: " << depth << "\n";</pre>
  stack<Node> s;
  // initialize start node
  Node node;
  node.num = 43;
  node.depth = 0;
  s.push(node);
  // initialize the checked state
  bool checked[10][10];
  for (int i = 0; i < 10; ++i) {
     for (int j = 0; j < 10; ++j) {
       // border around the board
       if (i == 0 || j == 0 || i == 9 || j == 9) {
          checked[i][j] = true;
       } else {
          checked[i][j] = false;
     }
  }
  // set the marked out position and start node to already checked
  pr p = getLoc(43);
  checked[p.first][p.second] = true;
  p = getLoc(26);
  checked[p.first][p.second] = true;
  p = getLoc(27);
  checked[p.first][p.second] = true;
  p = getLoc(28);
  checked[p.first][p.second] = true;
  p = getLoc(29);
  checked[p.first][p.second] = true;
```

```
p = getLoc(30);
checked[p.first][p.second] = true;
p = getLoc(33);
checked[p.first][p.second] = true;
p = getLoc(46);
checked[p.first][p.second] = true;
// conduct search
while (!s.empty()) {
  auto current = s.top();
  s.pop();
  // don't print the nodes that we can't explore
  if (current.depth <= depth) {</pre>
     cout << "node: " << current.num << " depth: " << current.depth << "\n";</pre>
  // get (i,j) location of current node
  p = getLoc(current.num);
  // set current node to explored to prevent cycles
  // mark the current node to checked
  checked[p.first][p.second] = true;
  // if goal state then we are done
  if (current.num == 18) {
     goal = true;
     cout << "node: " << current.num << " depth: " << current.depth << "\n";</pre>
     break;
  // if we have not met our depth limit
  } else if (current.depth <= depth) {</pre>
     p = getLoc(current.num);
     // add up
     if (!checked[p.first-1][p.second]) {
       pr temp;
       temp.first = p.first-1;
       temp.second = p.second;
       node.num = getNum(temp);
       node.depth = current.depth+1;
       s.push(node);
     // add left
```

```
if (!checked[p.first][p.second-1]) {
         pr temp;
         temp.first = p.first;
         temp.second = p.second-1;
         node.num = getNum(temp);
         node.depth = current.depth+1;
         s.push(node);
       // add right
       if (!checked[p.first][p.second+1]) {
         pr temp;
         temp.first = p.first;
         temp.second = p.second +1;
          node.num = getNum(temp);
         node.depth = current.depth+1;
         s.push(node);
       }
       // add down
       if (!checked[p.first+1][p.second]) {
         pr temp;
         temp.first = p.first+1;
         temp.second = p.second;
         node.num = getNum(temp);
         node.depth = current.depth+1;
         s.push(node);
       }
    // case that node is past the depth limit, then do nothing
     } else {
     }
  }
return 0;
```