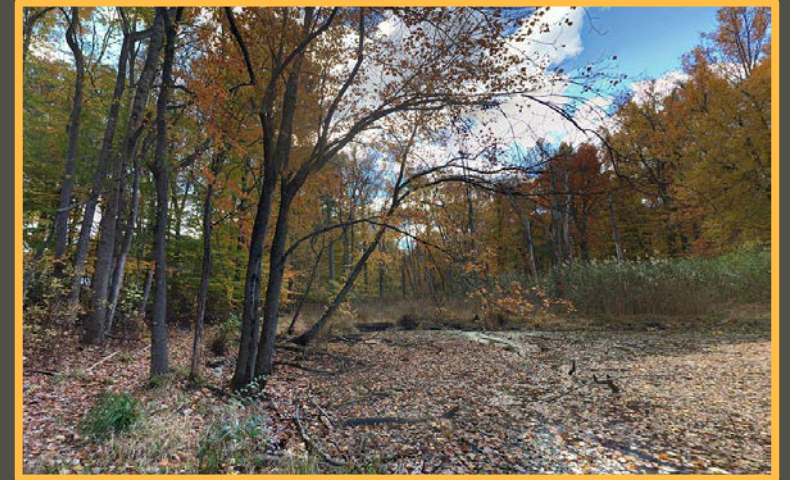


UPDATING THE NEW CANAAN LAND TRUST ANNUAL PROPERTY MAP USING PYTHON



Luke Menard
Yale School of Forestry and Environmental Studies
Geospatial Software Design, Fall 2016

BACKGROUND AND OBJECTIVES



New Canaan
Land Trust

Preserving 380 acres of *Open Space* in
Your Neighborhood since 1967



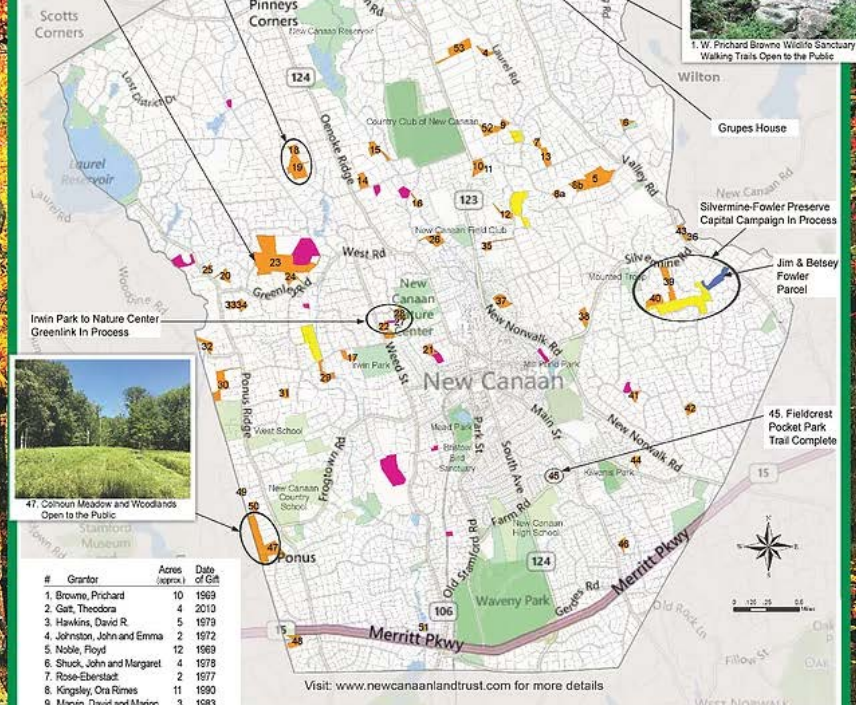
23. Nancy Watson-Symington Woodlands
Walking Trails Open to the Public



18, 19. Livingston-Higley Meadows
Apple Tree Lane Entrance



1. W. Pritchard Browne Wildlife Sanctuary
Walking Trails Open to the Public



#	Grantor	Acres (approx.)	Date of Gift
1.	Browne, Pritchard	10	1969
2.	Gatt, Theodora	4	2010
3.	Hawkins, David R.	5	1979
4.	Johnson, John and Emma	2	1972
5.	Noble, Floyd	12	1969
6.	Shuck, John and Margaret	4	1978
7.	Rose-Eberstadt	2	1977
8.	Kingsley, Ora Rimes	11	1990
9.	Marvin, David and Marion	3	1983

10.	Hannon, Kenneth H.	4	1976
11.	Eberstadt, Andrew and Ann	1	1976
12.	Stanton, Sidney	3	1975
13.	Schumacher, Robert	4	1977
14.	Walker, John and Adele	4	1976
15.	Barker, Robert and Elizabeth	5	1995
16.	Anderson - Atkins	2	1986
17.	Cutler, Isabel C.	3	1969
18.	Livingston-Higley	3	1974
19.	Livingston et al	11	1973
20.	MacDonald - Lapham	3	1995
21.	McKay, Emily	3	1996
22.	Bette, Bertha	5	1974
23.	Watson-Symington, Nancy	42	1984

24.	Lancaster, Jean	4	1969
25.	Murray, Paul B.	2	1981
26.	Donaldson & Maloney	5	1986
27.	Hopper, Joel & Joan	2	1974
28.	Fischer, Neils and Virginia	1	1977
29.	Dunn, Kempton	5	1988
30.	Small, Barry J.	10	1984
31.	Eberman, Janet Ross	3	1973
32.	Gaglio, Theresa A.	3	1976
33.	Wippeny et al	2	1971
34.	Rohde, Woffey & Lacagnina	4	1975
35.	Erdmann, Wilma	3	1973
36.	Danzon, Peter B.	1	1980
37.	Spalding, Mary Miller	5	1980

38.	Colborn, Barbara	4	1969
39.	Hicks, Ira and Margaret	13	1970
40.	Riedel and Bothwell	2	1986
41.	D'Aldano, Francis	2	1980
42.	Hoyt, Louise P.	3	1974
43.	Ernst, Susan B.	3	1978
44.	Bothwell, Gerald	2	1984
45.	Calbi - Kravanevsky	1	1973
46.	Candler, Roy and Inez	3	1982
47.	Colbourn, Richard	21	1974
48.	Benedict, Raymond T.	4	1970
49.	Frick, Edward & Jean	1	1984
50.	Stout, Carol E.	2	1974
51.	Smith, Earl	1	1972
52.	Massarella & Friends	4	2015
53.	Anonymous	8	2015

Legend

- New Canaan Land Trust Preserves - 274 acres total
- New Canaan Land Trust Easements - 50 acres total
- New Canaan Land Trust Bird Sanctuary - 56 acres total
- Protected Open Space
- Open Space
- Tax Parcel

Map & graphic design by
Kara Albers

BACKGROUND

The New Canaan Land Trust releases an annual property map, which is distributed in hard copy to land trust members and town residents. Presently, the map provides a visual representation of the preserves, easements, and bird sanctuaries owned by the land trust. It also includes an extended legend with the grantor(s) and approximate acreage of each property.

To construct the property map in the past, the land trust enlisted a third-party mapping and graphic design consultant. New Canaan taxlot and parcel data is overlain on a gray canvas basemap. New Canaan Land Trust properties and municipal open space is color coordinated according to function. Key properties are highlighted and an image of each is included along the map border.

The reverse side of the paper map provides aerial photographs of two flagship land trust properties, the W. Pritchard Browne Wildlife Sanctuary and the Nancy Watson-Symington Woodlands. The images are superimposed with a simple outline of the walking trails on the property.



New Canaan
Land Trust

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Your Neighborhood since 1967



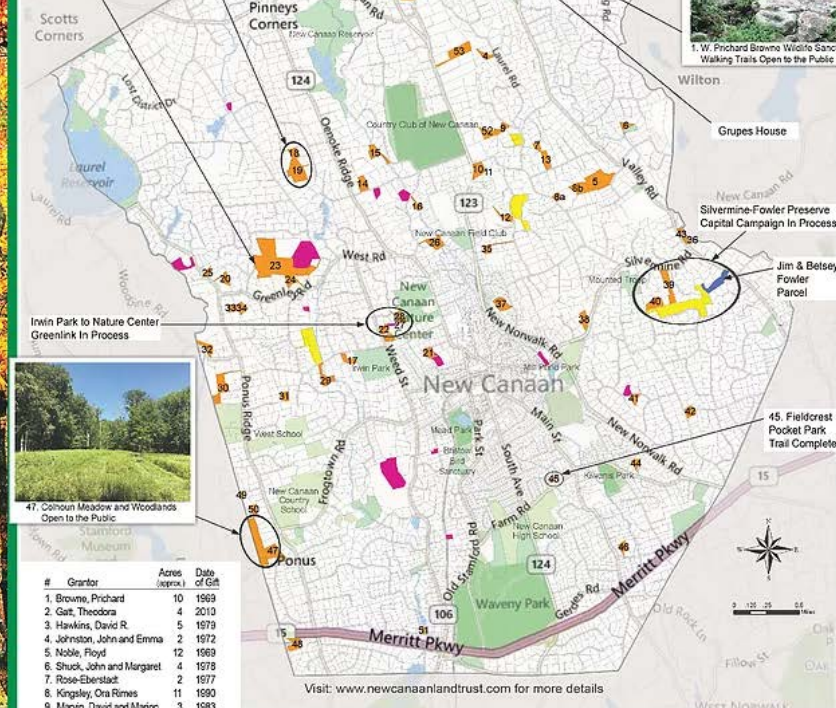
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Walking Trails Open to the Public



18, 19. Livingston-Higley Meadows
Apple Tree Lane Entrance



1. W. Prichard Browne Wildlife Sanctuary
Walking Trails Open to the Public



#	Grantor	Acres (approx.)	Date of Gift
1	Browne, Prichard	10	1969
2	Galt, Theodora	4	2010
3	Hawkins, David R.	5	1979
4	Johnston, John and Emma	2	1972
5	Noble, Floyd	12	1969
6	Shuck, John and Margaret	4	1978
7	Rose-Eberstadt	2	1977
8	Kingsley, Ora Rimes	11	1990
9	Marvin, David and Marion	3	1983

10	Hannon, Kenneth H.	4	1976
11	Eberstadt, Andrew and Ann	1	1976
12	Stanton, Sidney	3	1975
13	Schumacher, Robert	4	1977
14	Walker, John and Adele	4	1976
15	Barker, Robert and Elizabeth	5	1995
16	Anderson-Johns	2	1986
17	Cutler, Isabel C.	3	1969
18	Livingston-Higley	3	1974
19	Livingston et al	11	1973
20	MacDonald-Lapham	3	1995
21	McKay, Emily	3	1996
22	Bette, Bertha	5	1974
23	Watson-Symington, Nancy	42	1984

24	Lancaster, Jean	4	1969
25	Murray, Paul B.	2	1981
26	Donaldson & Maloney	5	1986
27	Hugger, Joel & Joan	2	1974
28	Fischer, Neils and Virginia	1	1977
29	Dunn, Kempton	5	1968
30	Small, Barry J.	10	1984
31	Eberman, Janet Ross	3	1973
32	Gaglio, Theresa A.	3	1976
33	Wippeny et al	2	1971
34	Rohde, Woffley & Lacagnina	4	1975
35	Erdmann, Wilma	3	1973
36	Dawson, Peter B.	1	1980
37	Spalding, Mary Miller	5	1980

38	Colborn, Barbara	4	1969
39	Hicks, Ira and Margaret	13	1970
40	Riedel and Bothwell	2	1986
41	D'Aldano, Francis	2	1980
42	Hoyt, Louise P.	3	1974
43	Ernst, Susan B.	3	1978
44	Bothwell, Gerald	2	1984
45	Calbi - Kravanevsky	1	1973
46	Carter, Roy and Inez	3	1982
47	Colhoun, Richard	21	1974
48	Benedict, Raymond T.	4	1970
49	Frick, Edward & Jean	1	1984
50	Stout, Carol E.	2	1974
51	Smith, Earl	1	1972
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BACKGROUND

All of the property boundaries depicted on the map are up to date and accurate. However, the property shapefiles that the land trust has in its possession are outdated, with some incorrect property boundaries and missing land holdings. In the past, this has resulted in the need to conduct post-hoc image editing following the creation of the map. The land trust has stressed some need to have updated land parcel shapefiles to increase their capacity to map their properties themselves and ensure that this additional editing work is unnecessary in the future.

Anecdotal evidence suggests that values of properties increase following the introduction of a park or wildlife sanctuary in their proximity. Many New Canaan residents associated with the land trust believe that this positive relationship exists between New Canaan Land Trust land holdings and monetary values of the properties nearby these land parcels. However, no real consideration of this trend has taken place.

Additionally, the New Canaan Land Trust suggested an interest in a more structured method of identifying ecologically and recreationally valuable properties in the town to assist with the prioritization of land for future purchases.

Popular Properties

(Click the photos for map locations)



Watson-Symington

The Watson-Symington property features 47 wooded acres with loop trails great for hiking, dog walking, or mountain biking.

Browne Wildlife Sanctuary

Browne wildlife sanctuary is home to a diverse population of plants and animals across its 10 acres, including a rare American chestnut tree. Look for interpretive signage along the trails.



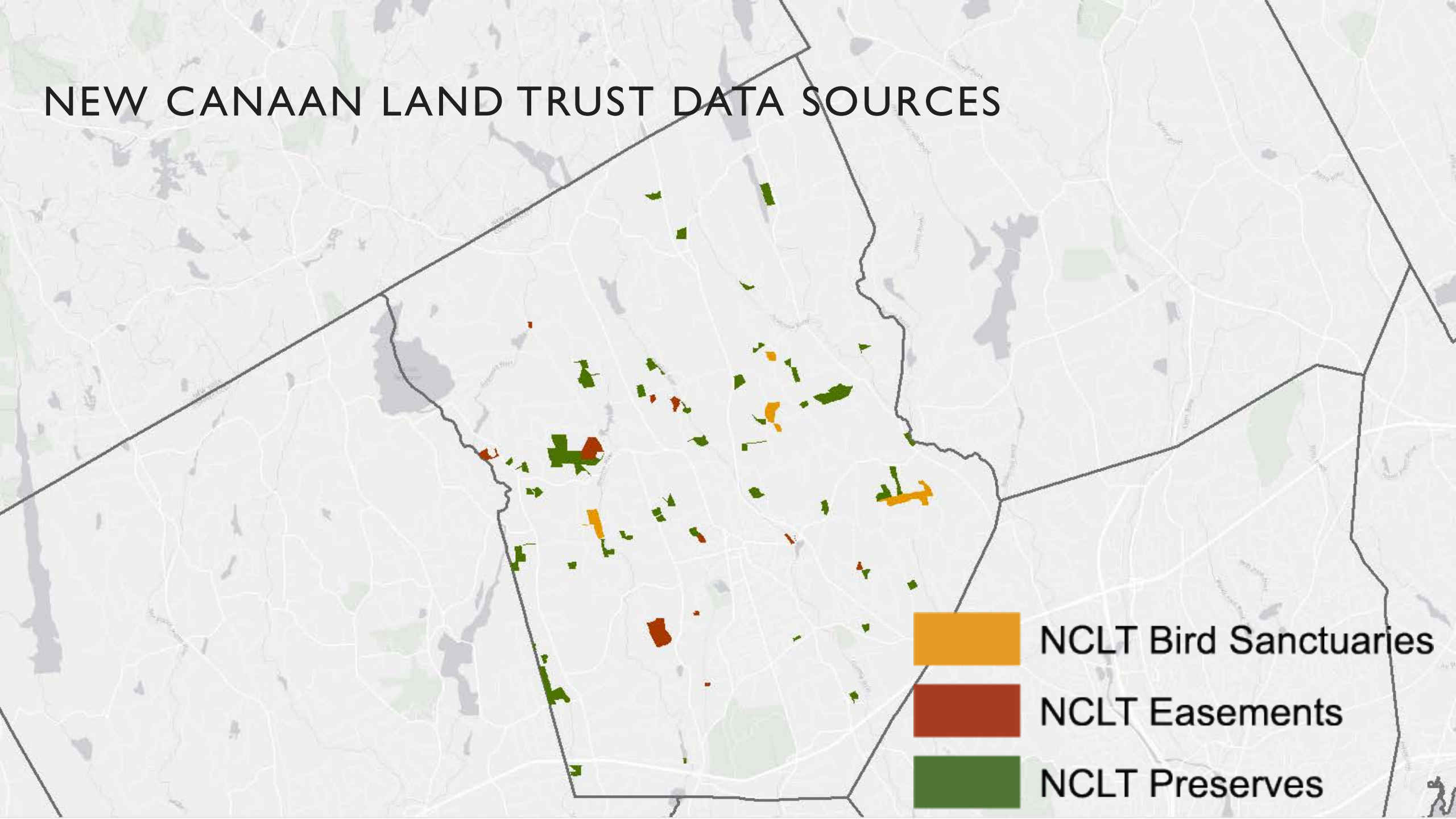
OBJECTIVES

Through conversations with Mike Johnson, the Executive Direction of the New Canaan Land Trust, and exploration of available data, I identified the following as primary objectives for my work in Python:

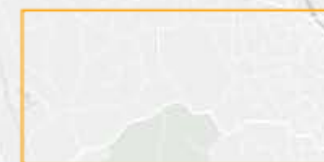
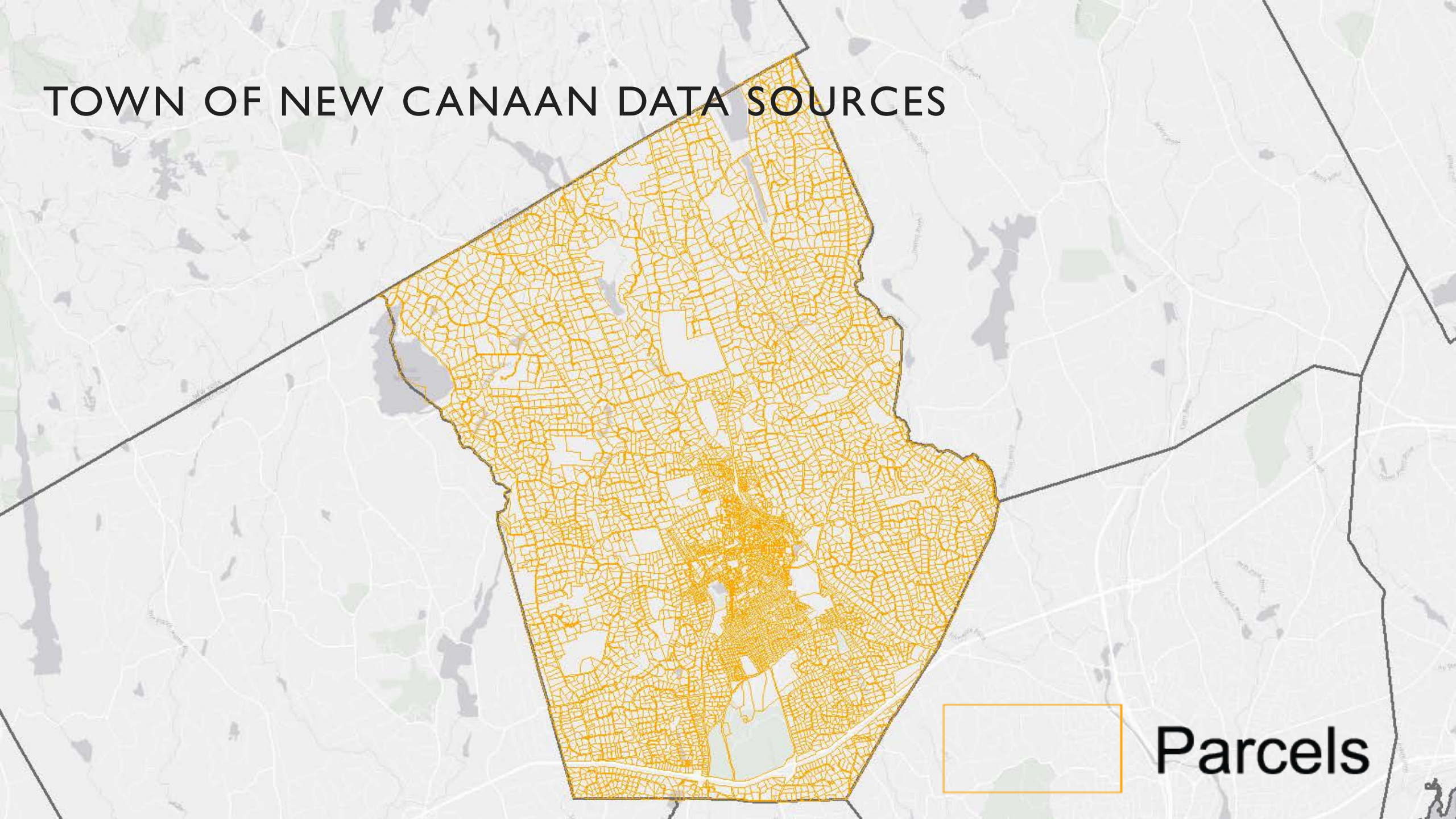
1. Update the land trust's parcel shapefiles to more accurately represent currently holdings and remove the need for post-hoc image editing.
2. Conduct cursory analyses to provide a rough sense of property value fluctuations for properties neighboring New Canaan Land Trust land holdings over time.
3. Generate interesting statistics for inclusion in flagship property profiles on the annual property map and New Canaan Land Trust website.
4. Conduct a site suitability assessment of New Canaan land parcels to identify high priority land for future purchases.

DATA COLLECTION

NEW CANAAN LAND TRUST DATA SOURCES



TOWN OF NEW CANAAN DATA SOURCES



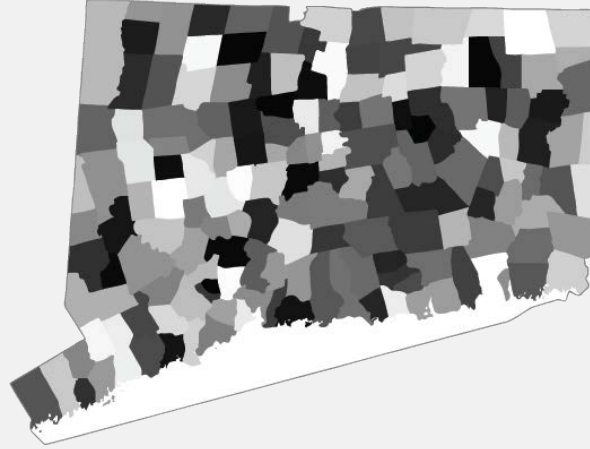
Parcels

CONNECTICUT DEEP DATA SOURCES

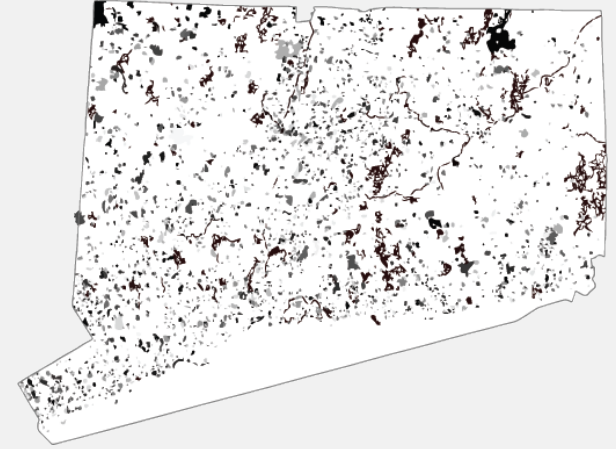
Connecticut Roads and Highways



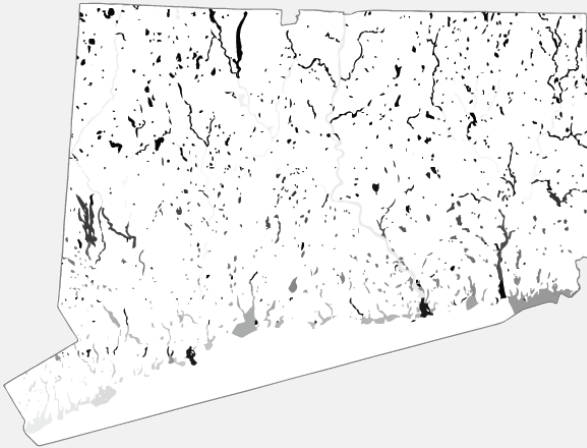
Connecticut Town Boundaries



Municipal Protected Open Space



Water Bodies



Statewide Hiking Trails

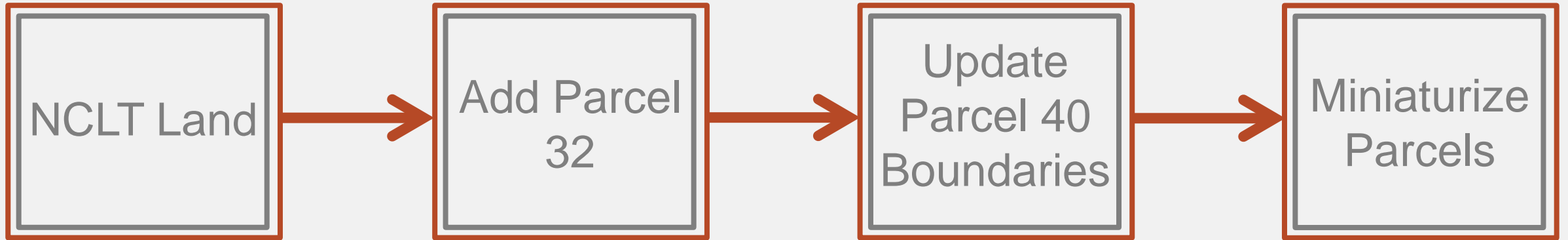


Connecticut Railroads



OBJECTIVE 1: UPDATE NCLT SHAPEFILES

OBJECTIVE 1 WORKFLOW



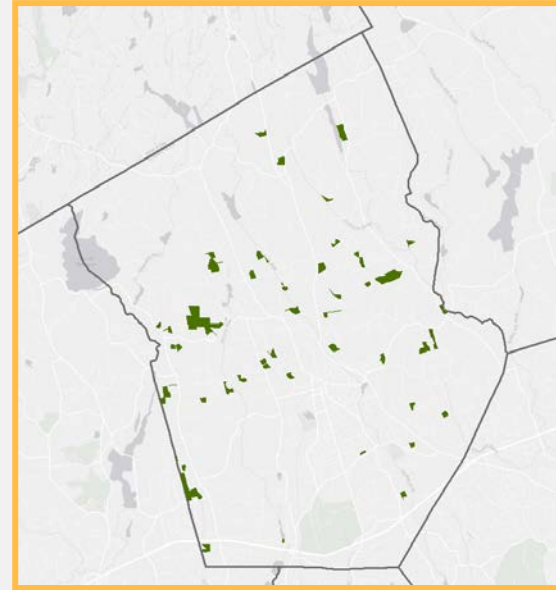
Objective: Update the land trust's parcel shapefiles to more accurately represent currently holdings and remove the need for post-hoc image editing.

SAMPLE CODE

```
FEATURE (FID = 5)  
PART:
```

```
(784592.808899,615926.5177)  
(784556.208923,615933.00769)  
(784538.827698,615940.116516)  
(784513.078918,615950.647522)  
(784493.33313,615977.678528)  
(784481.068909,615994.467529)  
(784473.954895,616010.112915)  
(784453.259277,616036.02771)  
(784453.248901,616055.647522)  
(784448.874878,616098.046875)  
(784436.658875,616216.457703)  
(784417.852905,616254.310486)  
(784397.770874,616287.285522)  
(784370.178894,616324.987671)  
(784346.193115,616337.665283)  
(784282.433472,616371.365479)  
(784223.307312,616402.616698)  
(784186.920288,616421.849921)  
(784133.138916,616449.28772)
```

```
(784076.138916,616449.28772)  
(784025.138916,616449.28772)  
(784008.138916,616449.28772)  
(784646.138916,616449.28772)  
(784647.138916,616449.28772)  
(784594.138916,616449.28772)  
(784592.808899,615926.5177)  
  
# Loop through vertices  
for feature in VertexCoordinates:  
  
    # Reset vertex coordinates and add to PointsArray  
    for vertex in feature:  
        Point.X = vertex[0]  
        Point.Y = vertex[1]  
        PointsArray.add(Point)  
  
    # Add the first vertex again to close the polygon  
    PointsArray.add(PointsArray.getObject(0))  
  
    # Create a polygon object from the array of vertex points  
    Polygon = arcpy.Polygon(PointsArray)  
  
    # Clear the array of vertex points for future use  
    PointsArray.removeAll()  
  
    # Append this polygon to Features list  
    Features.append(Polygon)  
  
# Create an output shapefile from Features list  
arcpy.CopyFeatures_management(Features, OutputShapefile)
```



Start with NCLT parcels
shapefile

Set vertices for parcel 30

Edit vertices for parcel 40



SAMPLE CODE

```
Point = arcpy.Point()

# Create list to hold all new features
NewFeatures = []

# Get attribute table and name of shape field for polygons created above
attributeTable = arcpy.SearchCursor(OutputShapefile)
ShapeField = arcpy.Describe(OutputShapefile).shapeFieldName

# Loop through features
for nextRecord in attributeTable:
    # Get the next feature and centroid
    arcpy.AddMessage("FEATURE (FID = " + str(nextRecord.getValue("FID")) + ")")
    nextFeature = nextRecord.getValue(ShapeField)
    Centroid = nextFeature.centroid

    # Create array to hold the parts of new feature
    NewParts = arcpy.Array()

    # Cycle through parts of the current feature
    for nextPart in nextFeature:
        arcpy.AddMessage("\tPART:")

        # Create array to hold the points for a new part to be created
        NewPoints = arcpy.Array()

        # Cycle through original vertices and create new point from each
        for nextVertex in nextPart:
            if nextVertex:
                arcpy.AddMessage("\t\t(" + str(nextVertex.X) + ', ' + str(nextVertex.Y) + ")")
                # If the next vertex is non-Null, create a new point and add it to the array of new points
                Point.X = ((nextVertex.X * 2.0) + Centroid.X) / 1.5
                Point.Y = ((nextVertex.Y * 2.0) + Centroid.Y) / 1.5
                NewPoints.add(Point)
            else:
                arcpy.AddMessage("\t\tNULL: (beginning with a Null point)")
                # If the next vertex is Null, insert a new point that is also Null
                NewPoints.append(None)

        # After creating an array of new points for a given part, add it to this feature's array of new parts
        NewParts.append(NewPoints)

    # After creating an array of new parts for a given feature, create a new feature from that array
    newFeature = arcpy.Polygon(NewParts)

    # After creating a new feature, append it to a list of all new features
    NewFeatures.append(newFeature)

# Create the new feature class
arcpy.CopyFeatures(NewFeatures, OutputShapefile)

# Delete row and del nextRecord
```

CHARACTERIZE POLYGONS

```
#Find feature type
arcpy.AddField_management(OutputShapefile, "ShapeType", "TEXT", 10)
arcpy.CalculateField_management(OutputShapefile,"ShapeType","!shape.type!", "PYTHON_9.3")

#Find length on shape in feet
arcpy.AddField_management(OutputShapefile, "Feet", "DOUBLE", 20, 5)
arcpy.CalculateField_management(OutputShapefile,"Feet","!shape.length@feet!", "PYTHON_9.3")

#Find area of shape in acres
arcpy.AddField_management(OutputShapefile, "Acres", "DOUBLE", 20, 5)
arcpy.CalculateField_management(OutputShapefile,"Acres","!shape.area@acres!", "PYTHON_9.3")
```

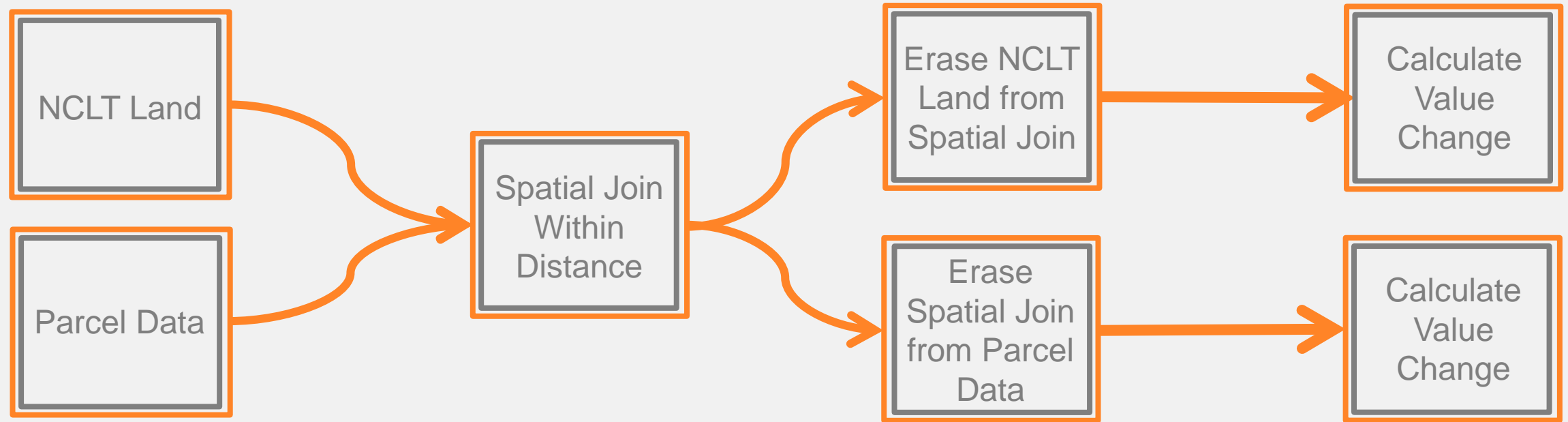
Miniaturize Polygons

	FID	Shape *	Id	ShapeType	Feet	Acres
▶	0	Polygon	0	polygon	3368.80739	149.84814
	1	Polygon	0	polygon	2295.94282	79.57222
	2	Polygon	0	polygon	5873.54938	295.07193
	3	Polygon	0	polygon	3125.4176	107.51038
	4	Polygon	0	polygon	3647.61055	94.52174
	5	Polygon	0	polygon	2571.60124	45.53853
	6	Polygon	0	polygon	592.34946	2.36088

Characterize Polygons

OBJECTIVE III: MAP PROPERTY VALUE CHANGE

OBJECTIVE II WORKFLOW



Objective: Conduct cursory analyses to provide a rough sense of property value fluctuations for properties neighboring New Canaan Land Trust land holdings over time.

SAMPLE CODE

```
targetFeatures = Parcels
joinFeatures = NCLTLand
outfc = os.path.join(outWorkspace, "Parcels_NCLTLand")
outfc1 = os.path.join(outWorkspace, "Parcels_NCLTLand1")
```

```
fieldmappings = arcpy.FieldMappings()
fieldmappings.addTable(targetFeatures)
fieldmappings.addTable(joinFeatures)
```

#Spatially join parcel layer with NCLTLand layer

```
#Parcels_JOIN_NCLTLand = Parcels[:-4] + "_spj.shp"
Parcels_NCLTLand = arcpy.SpatialJoin_analysis(targetFeatures, joinFeatures, outfc, '#', "KEEP_COMMON", fieldmappings, "WITHIN_A_DISTANCE", "100 FEET")
Parcels_NCLTLand1 = arcpy.SpatialJoin_analysis(targetFeatures, joinFeatures, outfc1, '#', "KEEP_COMMON", fieldmappings, "WITHIN_A_DISTANCE", "100 FEET")
```

#Erase NCLT preserves from spatial join results

```
#Join_ERASE_NCLTLand = Parcels[:-4] + "_erase.shp"
eraseOutput1 = r"C:\Users\llm47\Desktop\Scratch\Join_ERASE_NCLTLand"
eraseOutput1 = arcpy.Erase_analysis(Parcels_NCLTLand1, joinFeatures, eraseOutput1)
```

#Add a Value_Change field to the Erase shapefile, that will store the change in land values from the first to last land appraisal

```
fieldName = "Val_Change"
arcpy.AddField_management(eraseOutput1, fieldName, "Double")
```

#Calculate the change in land appraisal value between the final and first appraisals

```
arcpy.CalculateField_management(eraseOutput1, fieldName, "[Total_Ap_7] - [Total_Ap_1]", "VB")
```

#

#Erase spatial join results from Parcel Data

```
#Parcels_ERASE_Join = Parcels[:-4] + "_erase2.shp"
eraseOutput = r"C:\Users\llm47\Desktop\Scratch\Parcels_ERASE_Join"
eraseOutput = arcpy.Erase_analysis(targetFeatures, Parcels_NCLTLand, eraseOutput)
```

#Add a Value_Change field to the Erase shapefile, that will store the change in land values from the first to last land appraisal

```
arcpy.AddField_management(eraseOutput, fieldName, "Double")
```

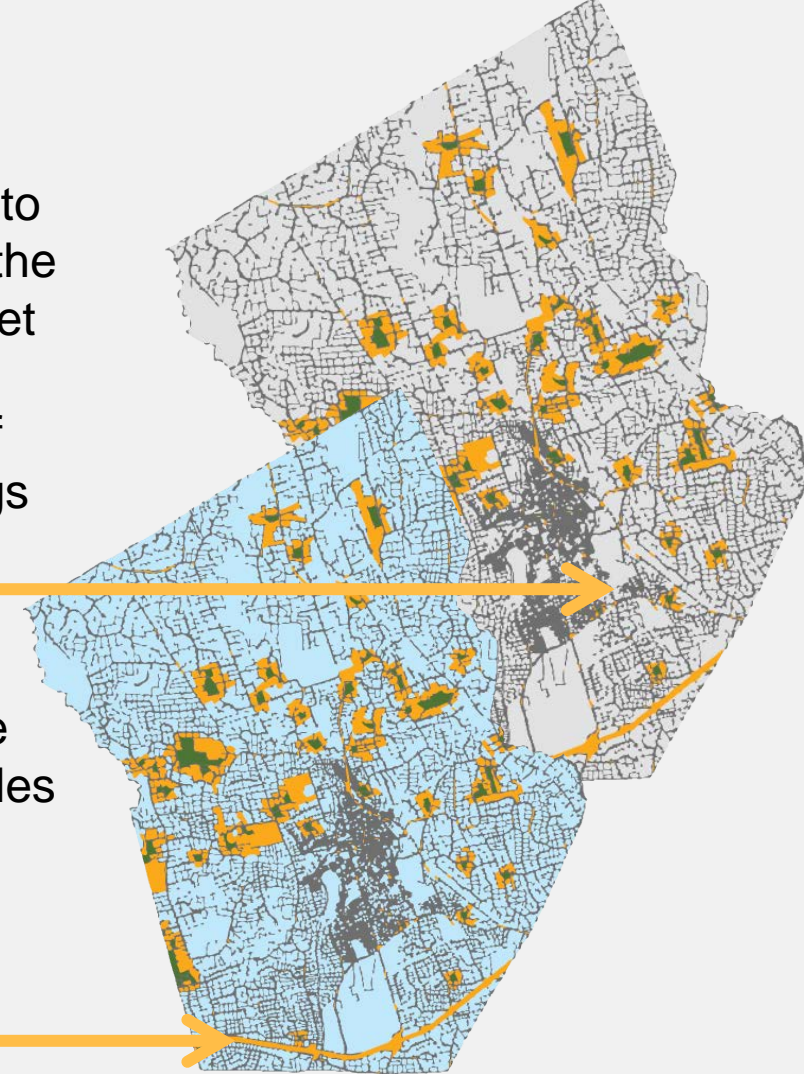
#Calculate the change in land appraisal value between the final and first appraisals

```
arcpy.CalculateField_management(eraseOutput, fieldName, "[Total_Ap_7] - [Total_Ap_1]", "VB")
```

```
#arcpy.CopyFeatures_management(eraseOutput, OutputMap)
```

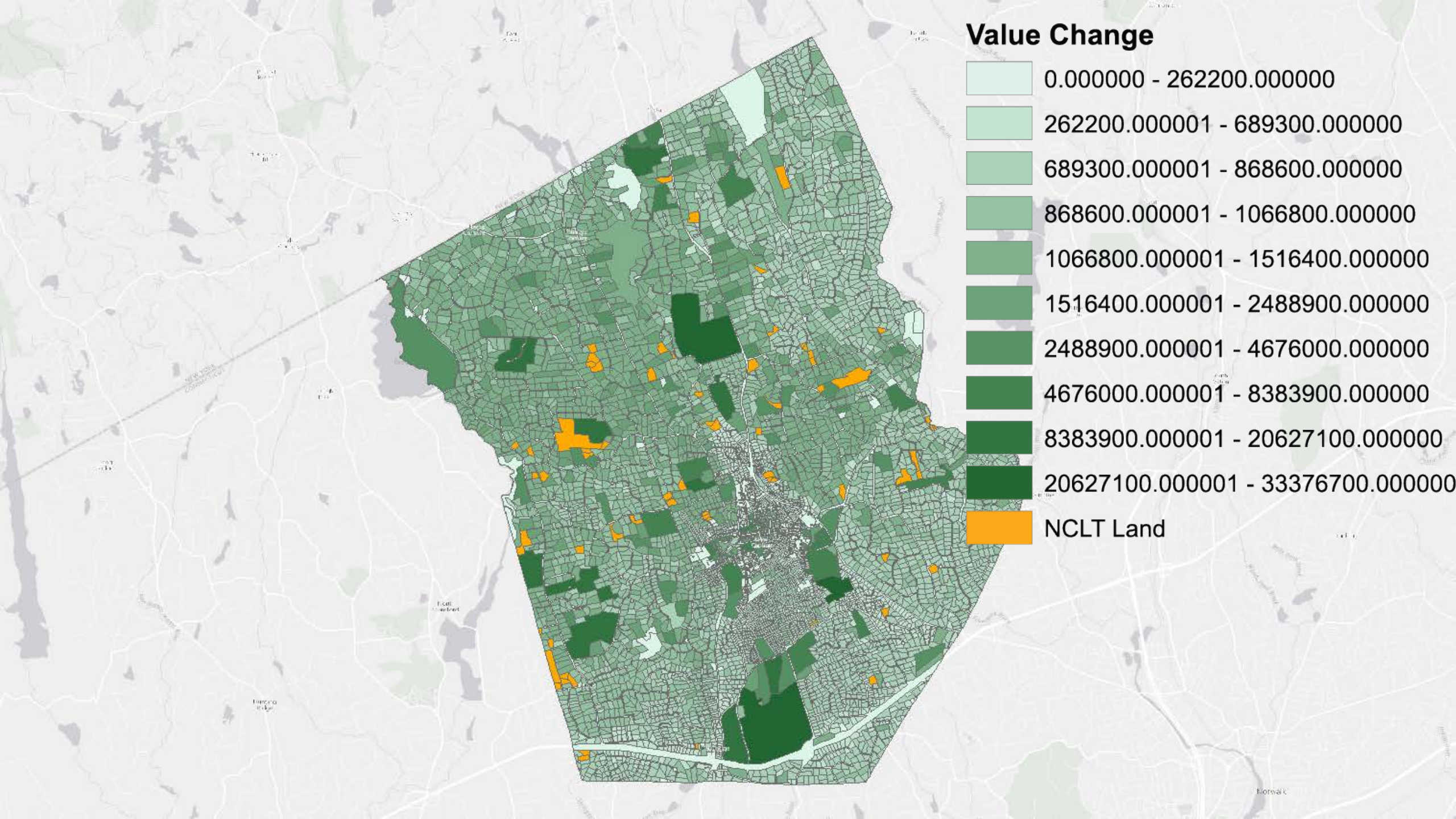
Use Spatial Join to link attributes of the NCLT land dataset to those parcels within 100 feet of land trust holdings

Use the Erase function to create separate shapefiles of neighboring parcels and all others



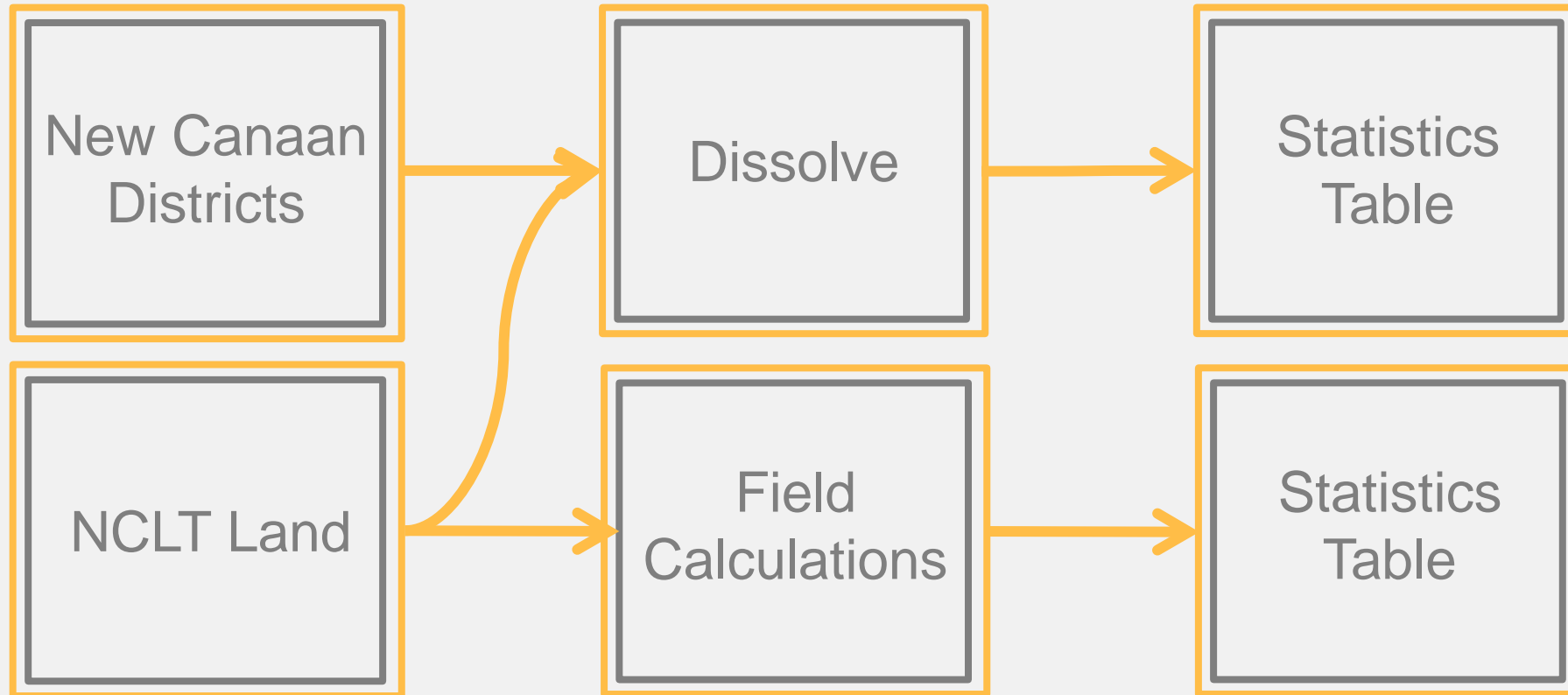
Val_Change
812700
719600
745100
794900
715200
795600
793400
795600

Add a value change field and subtract the initial land appraisal from the terminal appraisal



OBJECTIVE III: GENERATE STATISTICS

OBJECTIVE III WORKFLOW



Objective: Generate interesting statistics for inclusion in flagship property profiles on the annual property map and New Canaan Land Trust website.

SAMPLE CODE

```
#Create Enumerators -- Thanks to Yanan Xin's 2013 work here
OriginalEnumeration = arcpy.SearchCursor(Input,""," ", "FID;NAME10;Total_Ap_7", "NAME10 D")
TargetEnumeration = arcpy.UpdateCursor(OutputMap,""," ", "NAME10;Total_Ap_7", "NAME10 A")

#Loop
for record in TargetEnumeration:
    Name2 = record.getValue(Name)
    Appr2 = record.getValue(Appr)
    ID2 = record.getValue(ID)

    n=1
    while n:
        Next = OriginalEnumeration.next()
        NextName = Next.getValue(Name)
        NextAppr = Next.getValue(Appr)
        NextID = Next.getValue(ID)

        while ID2 != NextID:
            if Name2 == NextName:
                NextAppr = Appr2 + NextAppr
                #TargetEnumeration.deleteRow(record)
                record = TargetEnumeration.next()
                Name2 = record.getValue(Name)
                Appr2 = record.getValue(Appr)
                ID2 = record.getValue(ID)
            else:
                break

        if ID2 == NextID:
            record.setValue(Appr, NextAppr)
            TargetEnumeration.updateRow(record)
            arcpy.AddMessage("The value of NCLT holdings in "+str(Name)+" is "+str(NextAppr)+"\n")
            nextRecord = OriginalEnumeration.reset()
            n = 0
```

CHARACTERIZE POLYGONS

```
#Find feature type
arcpy.AddField_management(OutputShapefile, "ShapeType", "TEXT", 10)
arcpy.CalculateField_management(OutputShapefile,"ShapeType","!shape.type!", "PYTHON_9.3")

#Find length on shape in feet
arcpy.AddField_management(OutputShapefile, "Feet", "DOUBLE", 20, 5)
arcpy.CalculateField_management(OutputShapefile,"Feet","!shape.length@feet!", "PYTHON_9.3")

#Find area of shape in acres
arcpy.AddField_management(OutputShapefile, "Acres", "DOUBLE", 20, 5)
arcpy.CalculateField_management(OutputShapefile,"Acres","!shape.area@acres!", "PYTHON_9.3")
```

	FID	Shape *	NAME10	SUM_Total_
▶	0	Polygon	New Canaan 1	55774200
	1	Polygon	New Canaan 2	17882700
	2	Polygon	New Canaan 3	6326500

Use enumerations and search cursors to dissolve the parcel data by New Canaan district and sum the amount of value of NCLT holdings in each

Use field calculator to characterize NCLT preserves and easements

	FID	Shape *	Id	ShapeType	Feet	Acres
▶	0	Polygon	0	polygon	3368.80739	149.84814
	1	Polygon	0	polygon	2295.94282	79.57222
	2	Polygon	0	polygon	5873.54938	295.07193
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	6	Polygon	0	polygon	592.34946	2.36088

OBJECTIVE IV: SITE SUITABILITY ASSESSMENT

CRITERIA

- **Criterion 1: Proximity to an existing New Canaan Land Trust Preserve**

To maximize the land preserved in New Canaan, we want to prioritize new land that is not in close proximity to existing preserves.

- **Criterion 2: Proximity to highways and major roads**

We want to preserve land that is far from major roads and highways to avoid noise and car traffic.

- **Criterion 3: Proximity to water bodies**

We want to preserve land that is close to water, both to protect water bodies and to provide recreational opportunities to preserve visitors.

- **Criterion 4: Proximity to existing state trails**

We want land close to state trails to maximize use for recreational opportunities for patrons.

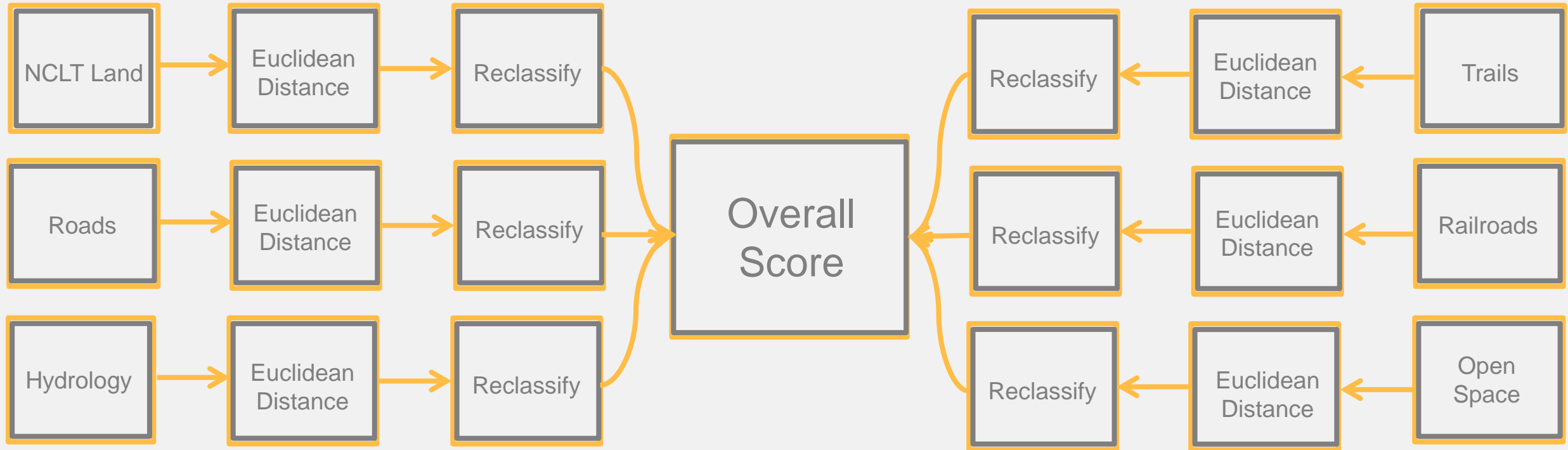
- **Criterion 5: Proximity to railroads**

Because unused railroads can often be easily converted to walking and biking trails, we want to find land in close proximity to rail lines.

- **Criterion 6: Presence of municipal open space**

Because municipal open space is already well regulated, we should prioritize other land.

OBJECTIVE IV WORKFLOW



Objective: Conduct a site suitability assessment of New Canaan land parcels to identify high priority land for future purchases

SAMPLE CODE

```
#Criterion 1: Use Euclidean Distance to estimate the distance away from existing New Caanan
#Land Trust preserves. Reclassify output to create a score grid, with higher scores allocated to
#those areas further from existing preserves.

Pres_BUFFER = arcpy.sa.EucDistance(Preserves)
Pres_SCORE = arcpy.sa.Reclassify(Pres_BUFFER, "Value", RemapRange([[0, 1200, 0], [1200, 2400, 20], [2400, 3200, 40], [3200, 4800, 60], [4800, 6834, 80]]), "DATA")

#Criterion 2: Reclassify to select only state highways and interstates. Use Euclidean Distance to
#estimate the distance away from roads. Reclassify output to create a score grid, with higher
#scores allocated to those areas further from roads.

#Roads_RECLASS = arcpy.sa.Reclassify(Roads,"Value","3 1; 4 1","NODATA")
#Roads_BUFFER = arcpy.sa.EucDistance(Roads)
Roads_SCORE = arcpy.sa.Reclassify(Roads_BUFFER, "Value", RemapRange([[0, 199, 0], [200, 299, 20], [300, 399, 40], [400, 450, 60], [450, 599, 80], [600, 130000, 100]]), "DATA")

#Criterion 3: Use Euclidean Distance to estimate the distance away from a water feature.
#Reclassify output to create a score grid, with higher scores allocated to regions closer to a water
#body.

Hydro_BUFFER = arcpy.sa.EucDistance(Hydrology)
Hydro_SCORE = arcpy.sa.Reclassify(Hydro_BUFFER, "Value", RemapRange([[0, 60, 100], [60, 120, 80], [120, 180, 60], [180, 240, 40], [240, 300, 20], [300,132623, 0]]), "DATA")

#Criterion 4: Use Euclidean Distance to estimate the distance away from an existing state trail.
#Reclassify output to create a score grid, with higher scores allocated to regions closer to a state
#trail.

Trails_BUFFER = arcpy.sa.EucDistance(Trails)
Trails_SCORE = arcpy.sa.Reclassify(Trails_BUFFER, "Value", RemapRange([[0, 200, 100], [200, 400, 80], [400, 600, 60], [600,800, 40], [800, 1000, 20], [1000,99000, 0]]), "DATA")

#Criterion 5: Use Euclidean Distance to estimate the distance away from a railroad. Reclassify
#output to create a score grid, with higher scores allocated to regions closer to a railroad.

Railroads_BUFFER = arcpy.sa.EucDistance(Railroads)
Railroads_SCORE = arcpy.sa.Reclassify(Railroads_BUFFER, "Value", RemapRange([[0, 200, 100], [200, 300, 80], [300, 400, 60], [400, 500, 40], [500, 600, 20], [600, 122000, 0]]), "DATA")

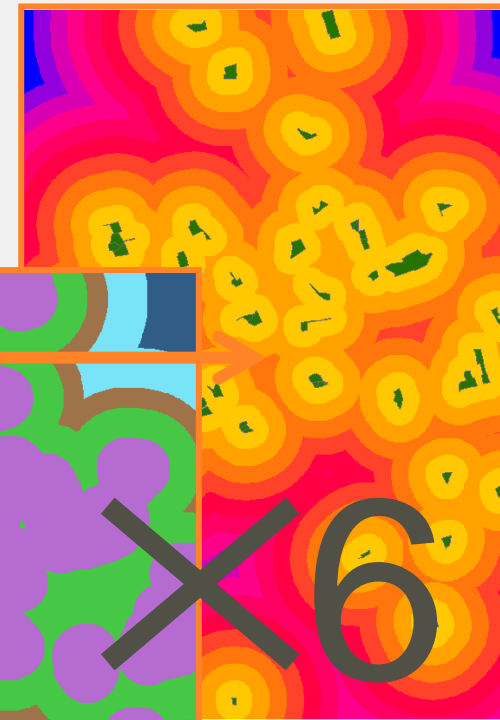
#Criterion 6: Use Euclidean Distance to estimate the distance away from existing municipal open space.
#Reclassify output to create a score grid, with higher scores allocated to those areas further from existing preserves.

OS_BUFFER = arcpy.sa.EucDistance(OpenSpace)
OS_SCORE = arcpy.sa.Reclassify(OS_BUFFER, "Value", RemapRange([[0, 200, 0], [200, 400, 20], [400, 600, 40], [600,800, 60], [800, 1000, 80], [1000,130000, 100]]), "DATA")

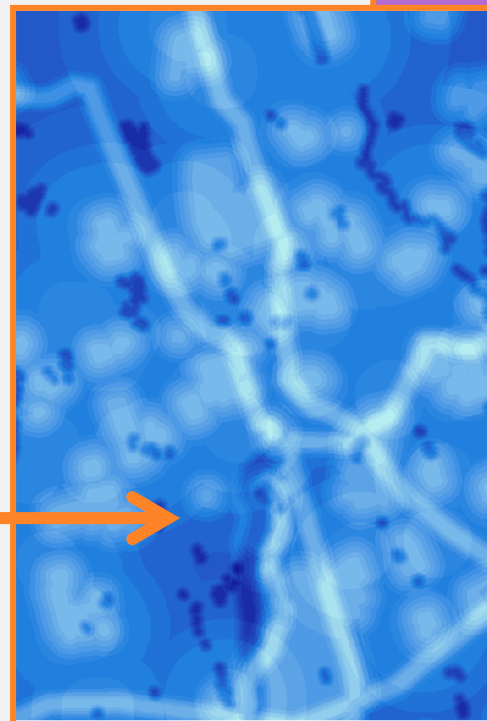
# Create a layer of combined scores to estimate the best overall locations.
Score = Pres_SCORE + Roads_SCORE + Hydro_SCORE + Trails_SCORE + Railroads_SCORE + OS_SCORE

#Select the areas with the highest scores.
Score_RECLASS = arcpy.sa.Reclassify(Score, "Value", "420 1; 400 1; 380 1; 360 1; 340 1; 320 1; 300 1", "NODATA")
```

Use Euclidean Distance to calculate distance from features



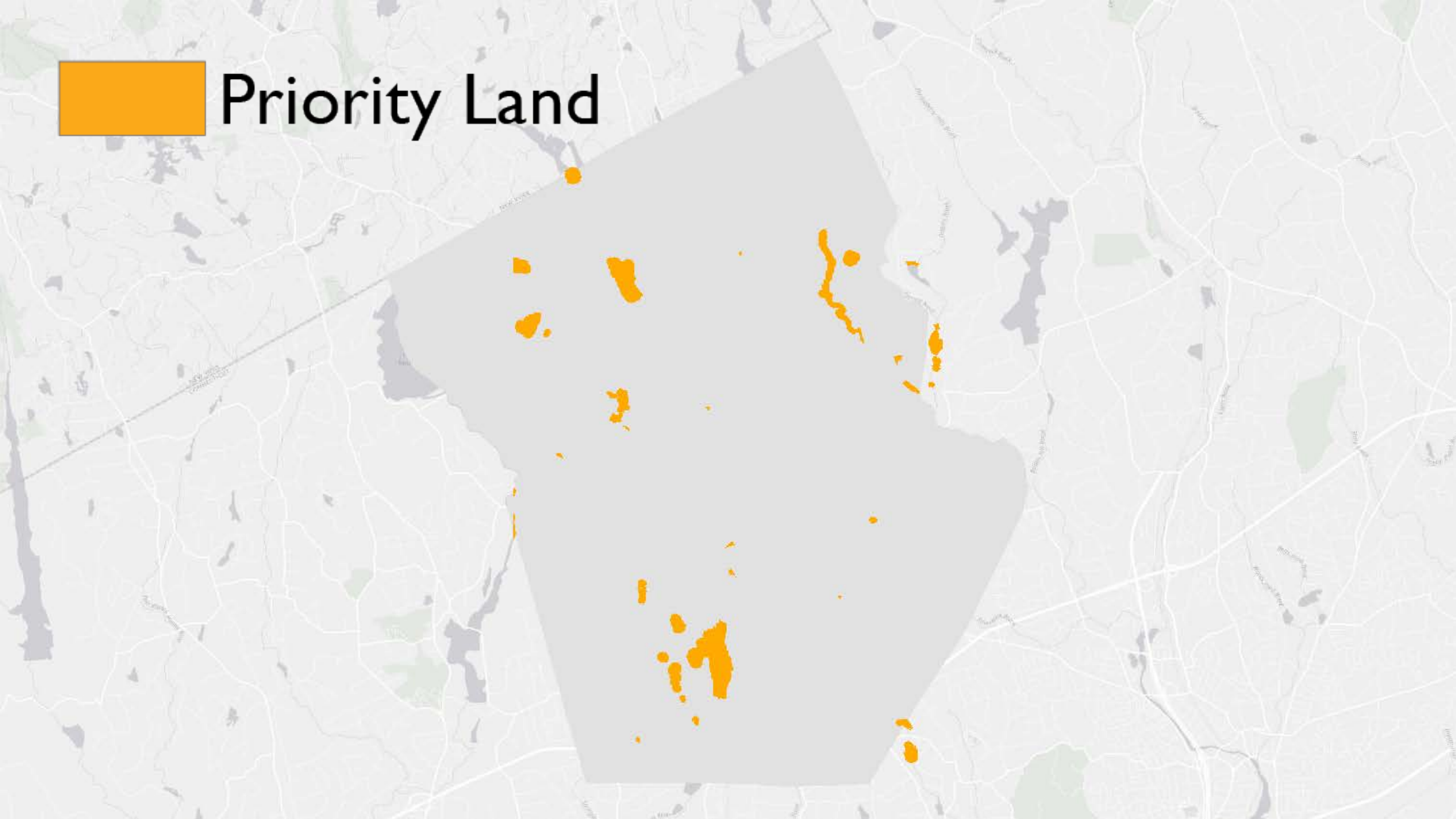
Reclassify to calculate sub scores



Calculate an overall score



Priority Land



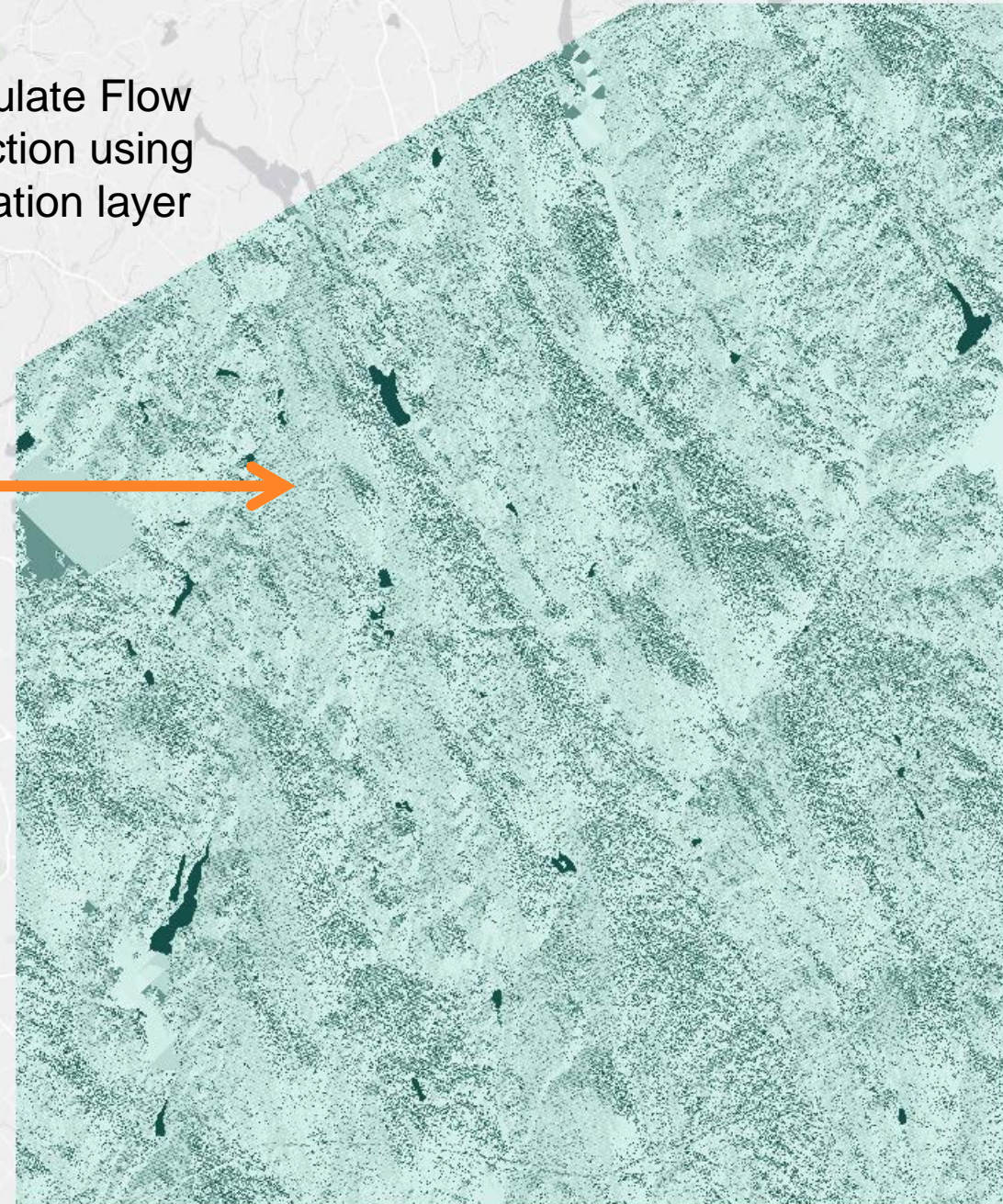
SAMPLE CODE

Calculate Flow
Direction using
Elevation layer

```
#Select the areas with the highest scores.
Score_RECLASS = arcpy.sa.Reclassify(Score, "Value", "420 1; 400 1; 380 1; 360 1; 340 1; 320 1; 300 1", "NODATA")
Directions = arcpy.sa.FlowDirection(Elevation)
Accumulations = arcpy.sa.FlowAccumulation(Directions,Score_RECLASS)
Accumulations.save(OutputName)

# Deactivate ArcGIS Spatial Analyst license
arcpy.CheckInExtension("spatial")

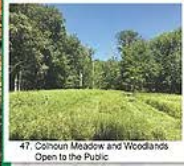
except Exception as e:
    arcpy.AddError('\n' + "Script failed because: \t\t" + e.message )
    exceptionreport = sys.exc_info()[2]
    fullermesssage = traceback.format_tb(exceptionreport)[0]
    arcpy.AddError("at this location: \n\n" + fullermesssage + "\n")
```



FUTURE PROJECTS AND ANALYSES



Preserving 380 acres of *Open Space* in
Your Neighborhood since 1967



#	Grantor	Acres (approx.)	Date of Gift
1.	Browne, Prichard	10	1969
2.	Galt, Theodora	4	2010
3.	Hawkins, David R.	5	1979
4.	Johnson, John and Emma	2	1972
5.	Noble, Floyd	12	1969
6.	Shuck, John and Margaret	4	1978
7.	Rose-Ebenstadt	2	1977
8.	Kingsley, Ora Rimes	11	1980
9.	Marvin, David and Marion	3	1983

10.	Hannan, Kenneth H.	4	1976
11.	Eberstadt, Andrew and Ann	1	1976
12.	Stauton, Sidney	3	1975
13.	Schumacher, Robert	4	1977
14.	Walker, John and Adele	4	1976
15.	Barkir, Robert and Elizabeth	5	1965
16.	Anderson - Adams	2	1980
17.	Cutler, Isabel C.	3	1969
18.	Livingston-Higley	3	1974
19.	Livingston et al	11	1973
20.	MacDonald - Lapham	3	1996
21.	McKay, Emily	3	1996
22.	Betts, Bertha	5	1974
23.	Watson-Symington, Nancy	42	1984

24.	Lancaster, Jean	4	1969
25.	Murray, Paul B.	2	1981
26.	Donaldson & Maione	5	1986
27.	Hopper, Joel & Joan	2	1974
28.	Fischer, Neils and Virginia	1	1977
29.	Dunn, Kempton	5	1968
30.	Small, Barry J.	10	1984
31.	Eberman, Janet Ross	3	1973
32.	Gaglio, Theresa A.	3	1976
33.	Wipprey et al	2	1971
34.	Rohde, Victor & Laograna	1	1975
35.	Endmann, Wilma	3	1973
36.	Danzon, Peter B.	1	1980
37.	Spalding, Mary Miller	5	1980

38.	Colborn, Barbara	4	1969
39.	Hicks, Ira and Margaret	13	1970
40.	Riedel and Bothwell	2	1968
41.	D'Aaddio, Francis	2	1980
42.	Hoyt, Louise P.	3	1974
43.	Ernst, Susan B.	3	1978
44.	Bothwell, Gerald	2	1964
45.	Caltri - Kravanevsky	1	1973
46.	Carter, Roy and Inez	3	1982
47.	Colbourn, Richard	21	1974
48.	Benedict, Raymond T.	4	1970
49.	Frick, Edward & Jean	1	1984
50.	Slout, Carol E.	2	1974
51.	Smith, Earl	1	1972
52.	Massarella & Friends	4	2015
53.	Anonymous	8	2015

Legend	
New Canaan Land Trust Preserves - 274 acres total	
New Canaan Land Trust Easements - 50 acres total	
New Canaan Land Trust Bird Sanctuary - 56 acres total	
Protected Open Space	
Open Space	
Tax Parcel	



DATA VISUALIZATION AND GRAPHIC DESIGN

- Use ArcGIS map outputs and Adobe Creative Suite to develop a compelling spatial data new annual map for the NCLT
- Feature large map with updated parcels
- Snapshots of flagship properties
- Highlighted data found in phase 2 analyses

STORY MAPPING

- Use updated parcel info to create an ArcGIS Story Map that highlights properties and lives on the NCLT website

ADDITIONAL STATISTICAL ANALYSES

- Conduct a more rigorous analysis of the economic and ecological factors associated with New Canaan land preservation over time

FULL SCRIPTS

""""

The New Canaan Land Trust's shapefile of land parcels is outdated and the shapes of several of their holdings have shifted over time.

Instead of changing the shapes of polygons in their source file, the team has historically done post hoc alterations of the shapes holdings

in photoshop before distributing property maps to their members. This script will recreate NCLT polygons and edit vertices to create

a more accurate polygon layer for use by the NCLT in the future.

""""

Import necessary modules

import arcpy, sys, os, string, math, traceback

Allow the output file to overwrite

arcpy.env.overwriteOutput = True

try:

Request user output of data type = Shapefile and direction = Output

OutputShapefile = arcpy.GetParameterAsText(0)

arcpy.AddMessage("Output shapefile: \t" + OutputShapefile + "\n")

#

Parcel 32 is missing from the current NCLT preserves shapefile

Parcel 32 crosses the boundaries of multiple taxlots, so can't be recreated by simply selecting features from the town's taxlot shapefile

Create Parcel 32 by finding its xy coordinates and generating a new polygon

The shape of parcel 40 is incorrect

Create a new parcel 40 with updated vertices

#

Find coordinates of NCLT parcel polygon vertices

#for row in arcpy.SearchCursor(InputClass, ["OID@", "SHAPE@"]):

print("Feature {}:".format(row[0]))

number = 0

for part in row[1]:

print("Part {}:".format(number))

for point in part:

if point:

print("{}, {}".format(point.X, point.Y))

else:

print("Interior Ring:")

number += 1


```

# Create list of five polygonal features defined by the XY coordinates of its vertices from above
VertexCoordinates = [ [ [797016.470969,631610.831902], [796645.287,631509.958088],
[796270.129942,632549.317886], [796707.377099,632650.656922], [797016.470969,631610.831902]
],
    [ [792838.717841,630514.372153], [792855.226995,629916.327089],
[792372.861162,629924.641049], [792401.479871,630378.780889], [792838.717841,630514.372153]
],
    [ [800106.204947,623087.599933], [800405.518981,622876.037036],
[800694.450161,622891.513055], [800488.049984,622463.520144], [799992.288836,622241.372951],
[799162.130063,622080.14099], [798824.618927,622386.138081], [799570.625966,622602.74001],
[799449.622927,622715.010127], [799956.080903,622978.537159], [800106.204947,623087.599933] ],
    [ [802508.641087,617630.567868], [801802.16809,617371.153033],
[801795.20485,617711.179912], [802080.909987,617828.462157], [801992.077159,618168.008066],
[802255.325977,618235.28385], [802508.641087,617630.567868]
],
    [ [803012.999986,617758.552848], [802749.60386,617697.556907],
[802763.709146,618071.595857], [802379.988129,619082.151907], [802663.584018,619083.005908],
[802912.428009,618049.345902], [803012.999986,617758.552848]
],
    [ [784592.808899,615926.517639],
[784556.208801,615933.00769],[784538.827698,615940.116516],[784513.078918,615950.647461],[78
4493.333008,615977.678467],[784481.068909,615994.467529],[784473.954773,616010.112854],[7844
53.259155,616036.02771],[784453.248779,616055.647522],[784448.874756,616098.046814],[784436.
658813,616216.457642],[784417.852783,616254.310425],[784397.770935,616287.285522],[784370.17
8772,616324.98761],[784346.193054,616337.665344],[784282.433533,616371.365356],[784223.30719
,616402.616577],[784186.920288,616421.848999],[784133.138916,616449.287598],[784076.188782,6
16453.9375],[784025.458801,616450.667664],[784008.053955,616571.034302],[784646.648804,61638
5.867554],[784647.472046,616049.68512],[784594.670044,616063.583801],[784592.808899,615926.5
17639]],
    [ [801762.8888, 617594.1575], [801762.8888, 617597.9875], [801762.9588,
617601.8075],[801763.0988, 617605.6175],[801763.2988, 617609.4075],[801763.5588,
617613.1875],[801763.8888, 617616.9475],[801764.2788, 617620.6975],[801764.7388,
617624.4275],[801765.2488, 617628.1475],[801765.8288, 617631.8375],[801766.4688,
617635.5275],[801767.1688, 617639.1975],[801767.9288, 617642.8475],[801768.7588,
617646.4775],[801769.6188, 617650.0975],[801770.5588, 617653.6975],[801771.5588,
617657.2675],[801772.6088, 617660.8175],[801773.7288, 617664.3575],[801774.8988,
617667.8675],[801776.1288, 617671.3575],[801777.4088, 617674.8175],[801778.7588,
617678.2675],[801780.1488, 617681.6775],[801781.6088, 617685.0675],[801783.1188,
617688.4375],[801784.6788, 617691.7775],[801786.2988, 617695.0775],[801787.9788,
617698.3575],[801789.6988, 617701.6175],[801791.4788, 617704.8375],[801793.3188,
617708.0275],[801795.2088, 617711.1775],[801797.1388, 617714.3075],[801799.1388,
617717.3975],
    [801801.1788, 617720.4475],[801803.2688, 617723.4775],[801805.4188,
617726.4575],[801807.6088, 617729.3975],[801809.8588, 617732.3075],[801812.1488,
617735.1875],[801814.4988, 617738.0275],[801816.8888, 617740.8175],[801819.3288,
617743.5775],[801821.8088, 617746.2875],[801824.3488, 617748.9575],[801826.9288,

```

```

617751.5775],[801829.5588, 617754.1675],[801832.2288, 617756.6975],[801834.9488,
617759.1975],[801837.7088, 617761.6375],[801840.5188, 617764.0375],[801843.3688,
617766.3975],[801846.2588, 617768.6975],[801849.1988, 617770.9475],[801852.1788,
617773.1475],[801855.2088, 617775.2975],[801858.2688, 617777.3975],[801861.3788,
617779.4475],[801864.5288, 617781.4375],[801867.7188, 617783.3775],[801870.9488,
617785.2675],[801874.2188, 617787.0875],[801877.5288, 617788.8575],[801880.8788,
617790.5775],[801884.2688, 617792.2275],[801887.6988, 617793.8175],[801891.1688,
617795.3475],[801894.6688, 617796.8275],[801898.2188, 617798.2275],[801901.8088,
617799.5675],
    [801905.4288, 617800.8375],[801909.0988, 617802.047, [801912.7988,
617803.1875],[801916.5388, 617804.2575],[801920.3388, 617805.2575],[801924.1588,
617806.1775],[801928.0288, 617807.0275],[801931.9488, 617807.8075],[801933.9188,
617808.1575],[801935.8988, 617808.4975],[801937.8988, 617808.8075],[801939.8988,
617809.1075],[801941.9188, 617809.3775],[801943.9488, 617809.6275],[801945.9988,
617809.8675],[801948.0488, 617810.0775],[801950.1188, 617810.2575],[801952.1988,
617810.4275],[801954.3088, 617810.5675],[802080.9088, 617828.4575],[802084.7388,
617845.2575],[801991.2088, 617950],[801975.2788, 617950],[802008.4888,
617950],[802006.1988, 617950],[802017.2688, 617950],[802217.4188, 617950],[802231.5288,
617950],[802248.7888, 617950],[802341.7088, 617932.0675],[802391.6788,
617941.5875],[802408.1288, 617892.1175],[802501.7888, 617626.2875],[802396.9588,
617608.6575],[802289.9588, 617587.6275],[802181.2688, 617565.7475],[802018.2988,
617527.7175],[801817.9588, 617442.4975],
    [801818.4588, 617379.5575],[801815.9888, 617378.7375], [801812.6288,
617377.3775],[801809.3688, 617375.7875],[801806.2288, 617373.9675],[801802.1688,
617371.1575],[801777.3288, 617450.3775],[801763.0888, 617586.4475],[801762.9488,
617590.3075],[801762.8888, 617594.1575]]]

```

```
# Create empty point
```

```
Point = arcpy.Point()
```

```
# Create empty array of points
```

```
PointsArray = arcpy.Array()
```

```
# Create empty list of polygons
```

```
Features = []
```

```
# Loop through vertices
```

```
for feature in VertexCoordinates:
```

```
    # Reset vertex coordinates and add to PointsArray
```

```
    for vertex in feature:
```

```
        Point.X = vertex[0]
```

```
        Point.Y = vertex[1]
```

```
        PointsArray.add(Point)
```

```
# Add the first vertex again to close the polygon
```

```
PointsArray.add(PointsArray.getObject(0))
```

```
# Create a polygon object from the array of vertex points
Polygon = arcpy.Polygon(PointsArray)
```

```
# Clear the array of vertex points for future use
PointsArray.removeAll()
```

```
# Append this polygon to Features list
Features.append(Polygon)
```

```
# Create an output shapefile from Features list
arcpy.CopyFeatures_management(Features, OutputShapefile)
```

```
# _____
_____
```

```
# MINIATURIZE POLYGONS
```

```
# Create object to hold new points
Point = arcpy.Point()
```

```
# Create list to hold all new features
NewFeatures = []
```

```
# Get attribute table and name of shape field for polygons created above
attributeTable = arcpy.SearchCursor(OutputShapefile)
ShapeField = arcpy.Describe(OutputShapefile).shapeFieldName
```

```
# Loop through features
for nextRecord in attributeTable:
    # Get the next feature and centroid
    arcpy.AddMessage("FEATURE (FID = " + str(nextRecord.getValue("FID")) + ")")
    nextFeature = nextRecord.getValue(ShapeField)
    Centroid = nextFeature.centroid
```

```
# Create array to hold the parts of new feature
NewParts = arcpy.Array()
```

```
# Cycle through parts of the current feature
for nextPart in nextFeature:
    arcpy.AddMessage("\tPART:")
```

```
# Create array to hold the points for a new part to be created
NewPoints = arcpy.Array()
```

```
# Cycle through original vertices and create new point from each
for nextVertex in nextPart:
    if nextVertex:
```

```

        arcpy.AddMessage("\t\t(" + str(nextVertex.X) + ',' + str(nextVertex.Y) + ")")
        # If the next vertex is non-Null, create a new point and add it to the array of new points
        Point.X = ((nextVertex.X * 2.0) + Centroid.X) / 1.5
        Point.Y = ((nextVertex.Y * 2.0) + Centroid.Y) / 2.0
        NewPoints.add(Point)
    else:
        arcpy.AddMessage("\t\tHOLE: (beginning with a Null point)")
        # If the next vertex is Null, insert a new point that is also Null
        NewPoints.append(None)
    # After creating an array of new points for a given part, add it to this feature's array of new parts
    NewParts.append(NewPoints)

# After creating an array of new parts for a given feature, create a new feature from that array
newFeature = arcpy.Polygon(NewParts)

# After creating a new feature, append it to a list of all new features
NewFeatures.append(newFeature)

# Create the new shapefile from that list of all new features
arcpy.CopyFeatures_management(NewFeatures, OutputShapefile)

# Delete row and update cursor objects to avoid locking attribute table
del nextRecord
del attributeTable

# _____

# CHARACTERIZE POLYGONS

#Find feature type
arcpy.AddField_management(OutputShapefile, "ShapeType", "TEXT", 10)
arcpy.CalculateField_management(OutputShapefile, "ShapeType", "!shape.type!", "PYTHON_9.3")

#Find length on shape in feet
arcpy.AddField_management(OutputShapefile, "Feet", "DOUBLE", 20, 5)
arcpy.CalculateField_management(OutputShapefile, "Feet", "!shape.length@feet!", "PYTHON_9.3")

#Find area of shape in acres
arcpy.AddField_management(OutputShapefile, "Acres", "DOUBLE", 20, 5)
arcpy.CalculateField_management(OutputShapefile, "Acres", "!shape.area@acres!", "PYTHON_9.3")

# _____

except Exception as e:
    # If unsuccessful, end gracefully by indicating why

```



```
arcpy.AddError("\n" + "Script failed because: \t\t" + e.message )
# ... and where
exceptionreport = sys.exc_info()[2]
fullermessage = traceback.format_tb(exceptionreport)[0]
arcpy.AddError("at this location: \n\n" + fullermessage + "\n")
```

```
"""
```

This script conducts a site suitability assessment of New Canaan land parcels to identify high priority land for future purchases.

```
"""
```

```
# Import external modules
# Note that math modules isn't needed
import sys, os, string, arcpy, math, traceback
```

```
from arcpy import env
from arcpy.sa import *
```

```
# Check to see if Spatial Analyst license is available. If available, continue with script.
if arcpy.CheckExtension("spatial") == "Available":
    try:
```

```
# Activate ArcGIS Spatial Analyst license
    arcpy.CheckOutExtension("spatial")
```

```
# Read user inputs from dialog box
```

```
Towns = arcpy.GetParameterAsText(0)
Preserves = arcpy.GetParameterAsText(1)
Roads = arcpy.GetParameterAsText(2)
Hydrology = arcpy.GetParameterAsText(3)
Trails = arcpy.GetParameterAsText(4)
Railroads = arcpy.GetParameterAsText(5)
OpenSpace = arcpy.GetParameterAsText(6)
Elevation = arcpy.GetParameterAsText(7)
OutputName = arcpy.GetParameterAsText(8)
```

```
# Reclassify Towns to identify only those of interest. Here, New Caanan is selected.
Towns = arcpy.sa.Reclassify(Towns,"Value","90 1","NODATA")
```

```
#Criterion 1: Use Euclidean Distance to estimate the distance away from existing New Caanan
#Land Trust preserves. Reclassify output to create a score grid, with higher scores allocated to
#those areas further from existing preserves.
```

```
Pres_BUFFER = arcpy.sa.EucDistance(Preserves)
```

```
Pres_SCORE = arcpy.sa.Reclassify(Pres_BUFFER, "Value", RemapRange([[0, 1200, 0], [1200, 2400, 20], [2400, 3200, 40], [3200, 4800, 60], [4800, 6834, 80]]), "DATA")
```

#Criterion 2: Reclassify to select only state highways and interstates. Use Euclidean Distance to
#estimate the distance away from roads. Reclassify output to create a score grid, with higher
#scores allocated to those areas further from roads.

```
#Roads_RECLASS = arcpy.sa.Reclassify(Roads,"Value","3 1; 4 1","NODATA")  
Roads_BUFFER = arcpy.sa.EucDistance(Roads)  
Roads_SCORE = arcpy.sa.Reclassify(Roads_BUFFER, "Value", RemapRange([[0, 199, 0], [200, 299, 20], [300, 399, 40], [400, 450, 60], [450, 599, 80], [600, 130000, 100]]), "DATA")
```

#Criterion 3: Use Euclidean Distance to estimate the distance away from a water feature.
#Reclassify output to create a score grid, with higher scores allocated to regions closer to a water
#body.

```
Hydro_BUFFER = arcpy.sa.EucDistance(Hydrology)  
Hydro_Score = arcpy.sa.Reclassify(Hydro_BUFFER, "Value", RemapRange([[0, 60, 100], [60, 120, 80], [120, 180, 60], [180, 240, 40], [240, 300, 20], [300,132623, 0]]), "DATA")
```

#Criterion 4: Use Euclidean Distance to estimate the distance away from an existing state trail.
#Reclassify output to create a score grid, with higher scores allocated to regions closer to a state
#trail.

```
Trails_BUFFER = arcpy.sa.EucDistance(Trails)  
Trails_SCORE = arcpy.sa.Reclassify(Trails_BUFFER, "Value", RemapRange([[0, 200, 100], [200, 400, 80], [400, 600, 60], [600,800, 40], [800, 1000, 20], [1000,99000, 0]]), "DATA")
```

#Criterion 5: Use Euclidean Distance to estimate the distance away from a railroad. Reclassify
#output to create a score grid, with higher scores allocated to regions closer to a railroad.

```
Railroads_BUFFER = arcpy.sa.EucDistance(Railroads)  
Railroads_SCORE = arcpy.sa.Reclassify(Railroads_BUFFER, "Value", RemapRange([[0, 200, 100], [200, 300, 80], [300, 400, 60], [400, 500, 40], [500, 600, 20], [600, 122000, 0]]), "DATA")
```

#Criterion 6: Use Euclidean Distance to estimate the distance away from existing municipal open space.
#Reclassify output to create a score grid, with higher scores allocated to those areas further from
existing preserves.

```

OS_BUFFER = arcpy.sa.EucDistance(OpenSpace)
OS_SCORE = arcpy.sa.Reclassify(OS_BUFFER, "Value", RemapRange([[0, 200, 0], [200, 400, 20],
[400, 600, 40], [600,800, 60], [800, 1000, 80], [1000,130000, 100]]), "DATA")

# Create a layer of combined scores to estimate the best overall locations.
Score = Pres_SCORE + Roads_SCORE + Hydro_Score + Trails_SCORE + Railroads_SCORE + OS_SCORE

#Select the areas with the highest scores.
Score_RECLASS = arcpy.sa.Reclassify(Score, "Value", "420 1; 400 1; 380 1; 360 1; 340 1; 320 1; 300
1", "NODATA")
Directions = arcpy.sa.FlowDirection(Elevation)
Accumulations = arcpy.sa.FlowAccumulation(Directions,Score) #Note that I've gotten this to run
before, but for some reason, Arc crashes every time I use this set of files
Accumulations.save(OutputName)

# Deactivate ArcGIS Spatial Analyst license
arcpy.CheckInExtension("spatial")

except Exception as e:
    arcpy.AddError('\n' + "Script failed because: \t\t" + e.message )
    exceptionreport = sys.exc_info()[2]
    fullermessage = traceback.format_tb(exceptionreport)[0]
    arcpy.AddError("at this location: \n\n" + fullermessage + "\n")

else:

# Report error message if Spatial Analyst license is unavailable
arcpy.AddMessage ("Spatial Analyst license is unavailable")

```



```

# Import external modules
# Note that math modules isn't needed
import sys, os, string, arcpy, math, traceback

from arcpy import env
from arcpy.sa import *

# Check to see if Spatial Analyst license is available. If available, continue with script.
if arcpy.CheckExtension("spatial") == "Available":
    try:

# Activate ArcGIS Spatial Analyst license
    arcpy.CheckOutExtension("spatial")

# Read user inputs from dialog box

    Towns = arcpy.GetParameterAsText(0)
    Preserves = arcpy.GetParameterAsText(1)
    Roads = arcpy.GetParameterAsText(2)
    Hydrology = arcpy.GetParameterAsText(3)
    Trails = arcpy.GetParameterAsText(4)
    Railroads = arcpy.GetParameterAsText(5)
    OpenSpace = arcpy.GetParameterAsText(6)
    Elevation = arcpy.GetParameterAsText(7)
    OutputName = arcpy.GetParameterAsText(8)

# Reclassify Towns to identify only those of interest. Here, New Caanan is selected.
    Towns = arcpy.sa.Reclassify(Towns,"Value","90 1","NODATA")

#Criterion 1: Use Euclidean Distance to estimate the distance away from existing New Caanan
#Land Trust preserves. Reclassify output to create a score grid, with higher scores allocated to
#those areas further from existing preserves.

    Pres_BUFFER = arcpy.sa.EucDistance(Preserves)
    Pres_SCORE = arcpy.sa.Reclassify(Pres_BUFFER, "Value", RemapRange([[0, 1200, 0], [1200, 2400,
20], [2400, 3200, 40], [3200, 4800, 60], [4800, 6834, 80]]), "DATA")

#Criterion 2: Reclassify to select only state highways and interstates. Use Euclidean Distance to
#estimate the distance away from roads. Reclassify output to create a score grid, with higher
#scores allocated to those areas further from roads.

    #Roads_RECLASS = arcpy.sa.Reclassify(Roads,"Value","3 1; 4 1","NODATA")
    Roads_BUFFER = arcpy.sa.EucDistance(Roads)
    Roads_SCORE = arcpy.sa.Reclassify(Roads_BUFFER, "Value", RemapRange([[0, 199, 0], [200, 299,
20], [300, 399, 40], [400, 450, 60], [450, 599, 80], [600, 130000, 100]]), "DATA")

```

#Criterion 3: Use Euclidean Distance to estimate the distance away from a water feature.
#Reclassify output to create a score grid, with higher scores allocated to regions closer to a water
#body.

```
Hydro_BUFFER = arcpy.sa.EucDistance(Hydrology)
Hydro_Score = arcpy.sa.Reclassify(Hydro_BUFFER, "Value", RemapRange([[0, 60, 100], [60, 120, 80],
[120, 180, 60], [180, 240, 40], [240, 300, 20], [300,132623, 0]]), "DATA")
```

#Criterion 4: Use Euclidean Distance to estimate the distance away from an existing state trail.
#Reclassify output to create a score grid, with higher scores allocated to regions closer to a state
#trail.

```
Trails_BUFFER = arcpy.sa.EucDistance(Trails)
Trails_SCORE = arcpy.sa.Reclassify(Trails_BUFFER, "Value", RemapRange([[0, 200, 100], [200, 400,
80], [400, 600, 60], [600,800, 40], [800, 1000, 20], [1000,99000, 0]]), "DATA")
```

#Criterion 5: Use Euclidean Distance to estimate the distance away from a railroad. Reclassify
#output to create a score grid, with higher scores allocated to regions closer to a railroad.

```
Railroads_BUFFER = arcpy.sa.EucDistance(Railroads)
Railroads_SCORE = arcpy.sa.Reclassify(Railroads_BUFFER, "Value", RemapRange([[0, 200, 100],
[200, 300, 80], [300, 400, 60], [400, 500, 40], [500, 600, 20], [600, 122000, 0]]), "DATA")
```

#Criterion 6: Use Euclidean Distance to estimate the distance away from existing municipal open space.
#Reclassify output to create a score grid, with higher scores allocated to those areas further from
existing preserves.

```
OS_BUFFER = arcpy.sa.EucDistance(OpenSpace)
OS_SCORE = arcpy.sa.Reclassify(OS_BUFFER, "Value", RemapRange([[0, 200, 0], [200, 400, 20],
[400, 600, 40], [600,800, 60], [800, 1000, 80], [1000,130000, 100]]), "DATA")
```

Create a layer of combined scores to estimate the best overall locations.

```
Score = Pres_SCORE + Roads_SCORE + Hydro_Score + Trails_SCORE + Railroads_SCORE + OS_SCORE
```

#Select the areas with the highest scores.

```
Score_RECLASS = arcpy.sa.Reclassify(Score, "Value", "420 1; 400 1; 380 1; 360 1; 340 1; 320 1; 300
1", "NODATA")
```

```
Directions = arcpy.sa.FlowDirection(Elevation)
```

```
Accumulations = arcpy.sa.FlowAccumulation(Directions,Score_RECLASS)
```

```
Accumulations.save(OutputName)
```

Deactivate ArcGIS Spatial Analyst license

```
arcpy.CheckInExtension("spatial")
```

```
except Exception as e:
    arcpy.AddError('\n' + "Script failed because: \t\t" + e.message )
    exceptionreport = sys.exc_info()[2]
    fullermessage = traceback.format_tb(exceptionreport)[0]
    arcpy.AddError("at this location: \n\n" + fullermessage + "\n")
```

else:

```
# Report error message if Spatial Analyst license is unavailable
arcpy.AddMessage ("Spatial Analyst license is unavailable")
```