Parameter and Posterior Inference Tables for ATC Experiment E1

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Nondecision Time

Parameter Table: Nondecision Time

| | M | SD |
|----|------|---------|
| t0 | 0.35 | 0.00795 |

SDV

Parameter Table: sdv

| | M | SD |
|-------------------------------|-------|---------|
| $\overline{\mathrm{sdv.ccC}}$ | 0.366 | 0.00782 |
| sdv.nnC | 0.551 | 0.0144 |
| $\operatorname{sdv.pcC}$ | 0.542 | 0.0239 |
| $\operatorname{sdv.pnC}$ | 0.591 | 0.0301 |
| sdv.ccN | 0.532 | 0.011 |
| $\operatorname{sdv.nnN}$ | 0.461 | 0.0084 |
| $\operatorname{sdv.pcN}$ | 0.54 | 0.0301 |
| $\operatorname{sdv.pnN}$ | 0.625 | 0.0243 |
| $\operatorname{sdv.ppP}$ | 1.15 | 0.0291 |
| | | |

Capacity Sharing

Posterior Inference Z Table: Capacity Sharing

Table 3: Table continues below

| | Conflict | Nonconflict | Conflict (Error) |
|--------------------|-------------|-------------|------------------|
| A.PM.minus.Control | 7.25(0) | 6.94(0) | 4.98(0) |
| B.PM.minus.Control | 10.16(0) | 8.37(0) | 8.09(0) |
| C.PM.minus.Control | 7.36(0) | 2.88(0.003) | 4.51(0) |
| D.PM.minus.Control | 0.53(0.298) | 2.17(0.015) | 5.24(0) |

| | Nonconflict (Error) |
|--------------------|---------------------|
| A.PM.minus.Control | 6.7(0) |
| B.PM.minus.Control | 9.85(0) |
| C.PM.minus.Control | 8.68(0) |

| | Nonconflict (Error) |
|--------------------|---------------------|
| D.PM.minus.Control | 7.01(0) |

Parameter Table: Drift Rates by PM Block

| | PM_Block | M | SD |
|--------------------------|----------|--------|--------|
| V.cor2_Ongoing | Control | 1.39 | 0.017 |
| $ m V.cor3_Ongoing$ | PM | 1.54 | 0.0165 |
| ${ m V.err2_Ongoing}$ | Control | 0.418 | 0.0234 |
| ${ m V.err3_Ongoing}$ | PM | 0.768 | 0.0181 |
| $V.cc2_Conflict$ | Control | 1.26 | 0.0182 |
| $ m V.cc3_Conflict$ | PM | 1.42 | 0.0176 |
| $ m V.pc3_Conflict_RC$ | PM | 0.867 | 0.0415 |
| ${f V.nn2_Conflict}$ | Control | 0.231 | 0.0368 |
| ${f V.nn3_Conflict}$ | PM | 0.606 | 0.0287 |
| $ m V.pn3_Conflict_RC$ | PM | -0.168 | 0.069 |
| ${f V.nn2_Nonconflict}$ | Control | 1.53 | 0.0208 |
| ${f V.nn3_Nonconflict}$ | PM | 1.67 | 0.0199 |
| $V.pn3_Nonconflict_RC$ | PM | 1.19 | 0.0383 |
| $V.cc2_Nonconflict$ | Control | 0.605 | 0.0258 |
| $V.cc3_Nonconflict$ | PM | 0.929 | 0.0194 |
| $V.pc3_Nonconflict_RC$ | PM | 0.198 | 0.0611 |
| $V.pp3_PM$ | PM | 2.09 | 0.0363 |

Proactive Control

Posterior Inference Z Table: Proactive Control

| | Conflict | Nonconflict |
|--------------------|----------|-------------|
| A.PM.minus.Control | 21.19(0) | 26.24(0) |
| B.PM.minus.Control | 19.76(0) | 26.53(0) |
| C.PM.minus.Control | 21.06(0) | 26.12(0) |
| D.PM.minus.Control | 13.74(0) | 17.49(0) |

Parameter Table: Thresholds by PM Block

| | PM_Block | \mathbf{M} | SD |
|-----------------|-------------|--------------|--------|
| B.2_Ongoing | Control | 1.55 | 0.0189 |
| B.3_Ongoing | PM | 2.52 | 0.024 |
| B.2_Conflict | Control | 1.6 | 0.0244 |
| B.3_Conflict | PM | 2.51 | 0.0314 |
| B.2_Nonconflict | Control | 1.49 | 0.0238 |
| B.3_Nonconflict | PM | 2.54 | 0.0303 |
| B.3_PM | PM | 1.95 | 0.0345 |

Reactive Control

Posterior Inference Z Table: Reactive Inhibition

Table 8: Table continues below

| | Conflict | Nonconflict | Conflict (Error) |
|------------------|----------|-------------|------------------|
| A.NonPM.minus.PM | 8.57(0) | 8.53(0) | 5.43(0) |
| B.NonPM.minus.PM | 8.04(0) | 8.27(0) | 8.07(0) |
| C.NonPM.minus.PM | 7.56(0) | 7.49(0) | 4.42(0) |
| D.NonPM.minus.PM | 7.34(0) | 7(0) | 7.59(0) |

| | Nonconflict (Error) | |
|------------------|---------------------|--|
| A.NonPM.minus.PM | 7.43(0) | |
| B.NonPM.minus.PM | 6.93(0) | |
| C.NonPM.minus.PM | 6.9(0) | |
| D.NonPM.minus.PM | 6.75(0) | |

Parameter Table: Drift Rates by PM Block

| | PM_Block | M | SD |
|-----------------------------|------------------|--------|--------|
| V.cor2_Ongoing | Control | 1.39 | 0.017 |
| $ m V.cor3_Ongoing$ | $_{\mathrm{PM}}$ | 1.54 | 0.0165 |
| $V.err2_Ongoing$ | Control | 0.418 | 0.0234 |
| $V.err3_Ongoing$ | $_{\mathrm{PM}}$ | 0.768 | 0.0181 |
| $V.cc2_Conflict$ | Control | 1.26 | 0.0182 |
| ${f V.cc3_Conflict}$ | $_{\mathrm{PM}}$ | 1.42 | 0.0176 |
| $V.pc3_Conflict_RC$ | $_{\mathrm{PM}}$ | 0.867 | 0.0415 |
| ${f V.nn2_Conflict}$ | Control | 0.231 | 0.0368 |
| ${f V.nn3_Conflict}$ | $_{\mathrm{PM}}$ | 0.606 | 0.0287 |
| $V.pn3_Conflict_RC$ | $_{\mathrm{PM}}$ | -0.168 | 0.069 |
| ${f V.nn2_Nonconflict}$ | Control | 1.53 | 0.0208 |
| ${f V.nn3_Nonconflict}$ | $_{\mathrm{PM}}$ | 1.67 | 0.0199 |
| $ m V.pn3_Nonconflict_RC$ | $_{\mathrm{PM}}$ | 1.19 | 0.0383 |
| $V.cc2_Nonconflict$ | Control | 0.605 | 0.0258 |
| $ m V.cc3_Nonconflict$ | $_{\mathrm{PM}}$ | 0.929 | 0.0194 |
| $ m V.pc3_Nonconflict_RC$ | PM | 0.198 | 0.0611 |
| ${ m V.pp3_PM}$ | PM | 2.09 | 0.0363 |

Proactive Control by Time Pressure

Posterior Inference Z Table: Proactive Control by Time Pressure

| | Conflict | Nonconflict |
|-------------------|--------------|-------------|
| PM.Cost.A.minus.B | 4.07(0) | 2.65(0.004) |
| PM.Cost.B.minus.C | -0.84(0.201) | 1.19(0.118) |
| PM.Cost.C.minus.D | 8.27(0) | 8.22(0) |

Parameter Table: Thresholds by Time Pressure

| | ${\bf Time_Pressure}$ | M | SD |
|--------------------|------------------------|------|--------|
| B.A_Ongoing | A | 2.46 | 0.028 |
| B.B_Ongoing | В | 2.1 | 0.0242 |
| B.C_Ongoing | $^{\mathrm{C}}$ | 2.02 | 0.0236 |
| B.D_Ongoing | D | 1.56 | 0.0207 |
| $\mathbf{B.A_PM}$ | A | 2.38 | 0.0522 |
| $B.B_PM$ | В | 1.94 | 0.0481 |
| $B.C_PM$ | $^{\mathrm{C}}$ | 2.02 | 0.0485 |
| $B.D_PM$ | D | 1.47 | 0.0438 |

Effort/Arousal by Time Pressure

Posterior Inference Z Table: Effort/Arousal by Time Pressure

Table 13: Table continues below

| | A-B (Control) | B-C (Control) | C-D (Control) |
|--------------------|---------------|---------------|---------------|
| Conflict | -4.59(0) | 1.28(0.101) | -13.17(0) |
| Nonconflict | -4.02(0) | -0.03(0.488) | -11.49(0) |
| Conflict.FA | -5.35(0) | 2.48(0.007) | -10.21(0) |
| Nonconflict.FA | -3.19(0.001) | 2.8(0.003) | -13.25(0) |
| ${ m PM.to.PM}$ | - | _ | - |
| Conflict.to.PMC | - | - | - |
| Nonconflict.to.PMN | - | - | - |
| Conflict.to.PMN | - | - | - |
| Nonconflict.to.PMC | - | - | - |

| | A-B (PM) | B-C (PM) | C-D (PM) |
|--------------------|--------------|--------------|-----------|
| Conflict | -8.56(0) | 5.87(0) | -11.64(0) |
| Nonconflict | -7.36(0) | 6.55(0) | -14.88(0) |
| Conflict.FA | -10.06(0) | 6.18(0) | -13.69(0) |
| Nonconflict.FA | -8.51(0) | 5.58(0) | -18.64(0) |
| ${ m PM.to.PM}$ | 4.26(0) | 0.52(0.304) | 4.81(0) |
| Conflict.to.PMC | -2.99(0.001) | -0.48(0.315) | -3.43(0) |
| Nonconflict.to.PMN | -2.41(0.008) | 0.96(0.17) | -6.27(0) |
| Conflict.to.PMN | -1.54(0.059) | -0.98(0.164) | -3.83(0) |
| Nonconflict.to.PMC | -2.77(0.003) | 1.29(0.098) | -6.16(0) |

Parameter Table: Drift Rates by Time Pressure

| | M | SD |
|------------------------|------|--------|
| V.corA_Ongoing | 1.3 | 0.0167 |
| $V.corB_Ongoing$ | 1.45 | 0.0175 |
| ${ m V.corC_Ongoing}$ | 1.38 | 0.0173 |
| $V.corD_Ongoing$ | 1.73 | 0.0209 |

| | M | SD |
|-------------------|-------|--------|
| V.errA_Ongoing | 0.261 | 0.0296 |
| $V.errB_Ongoing$ | 0.614 | 0.0226 |
| $V.errC_Ongoing$ | 0.411 | 0.0271 |
| $V.errD_Ongoing$ | 1.09 | 0.0215 |
| $V.ppA_PM$ | 2.41 | 0.053 |
| $V.ppB_PM$ | 2.13 | 0.0569 |
| $V.ppC_PM$ | 2.09 | 0.0545 |
| $V.ppD_PM$ | 1.73 | 0.0601 |