

2-Channel PID servo motor controller board

Luke Weston, 2012

<http://github.com/lukeweston/>*

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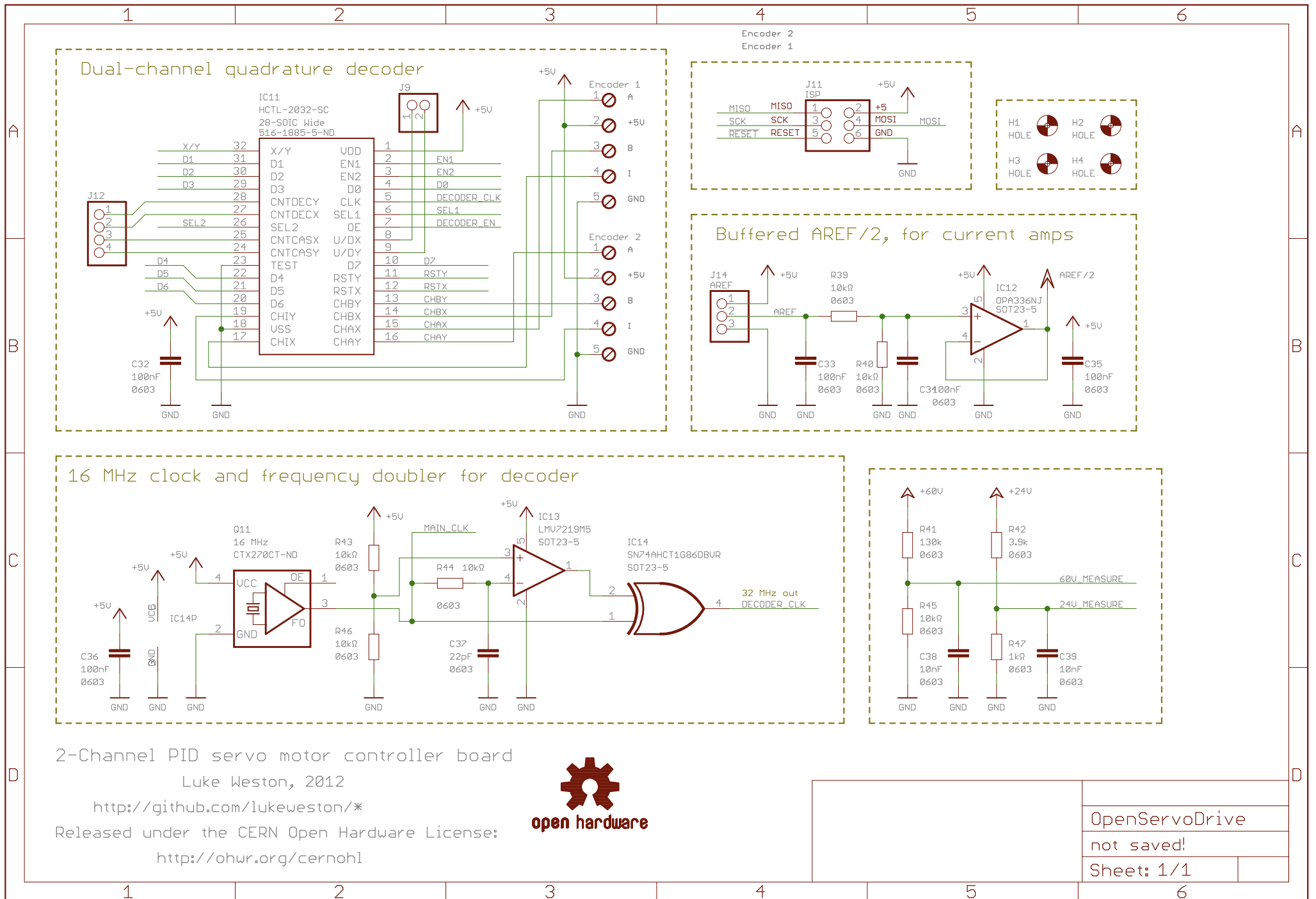
<http://ohw.org/cernohl>



OpenServoDrive

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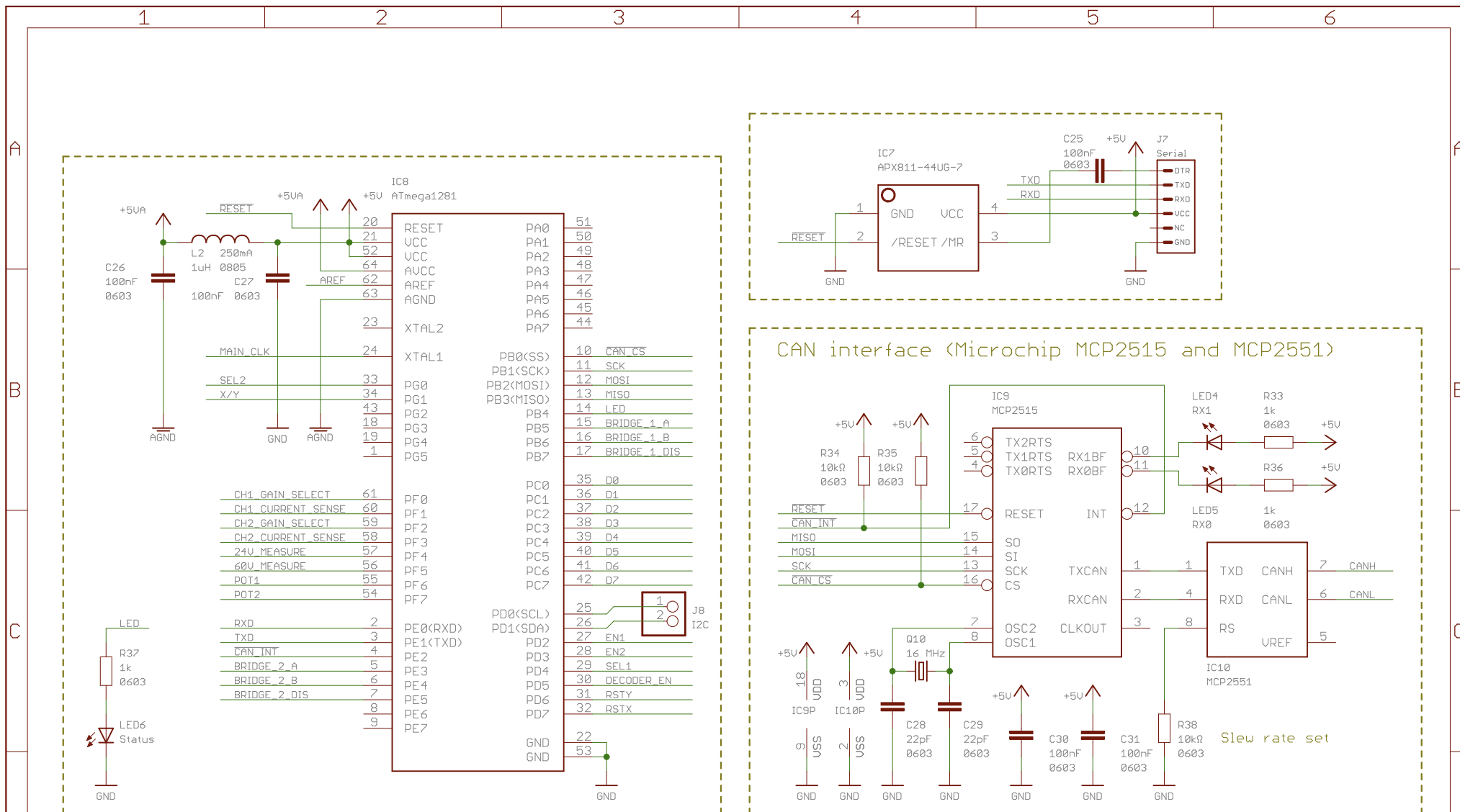
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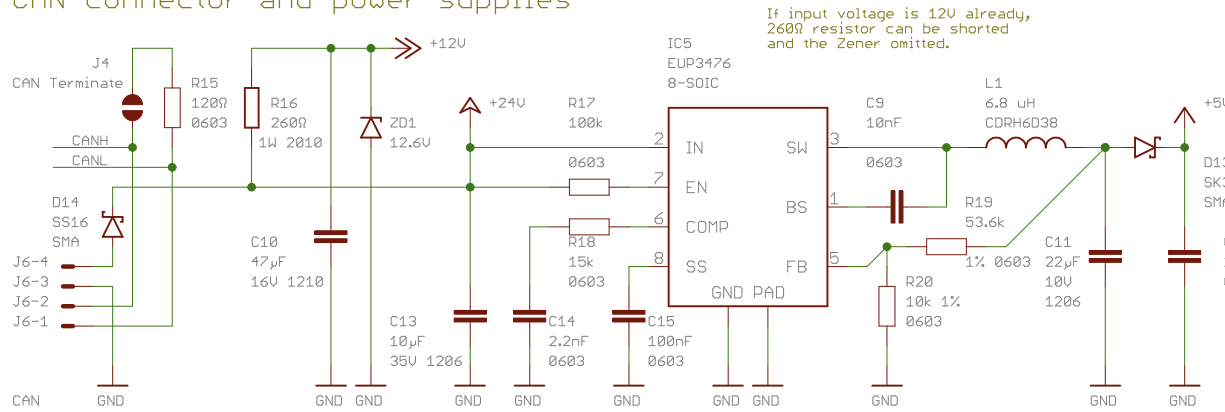


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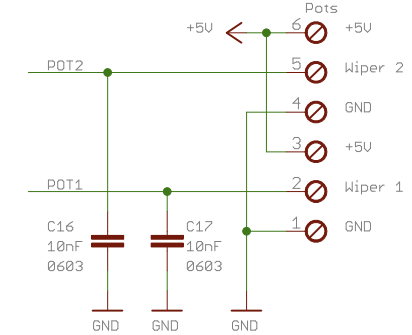
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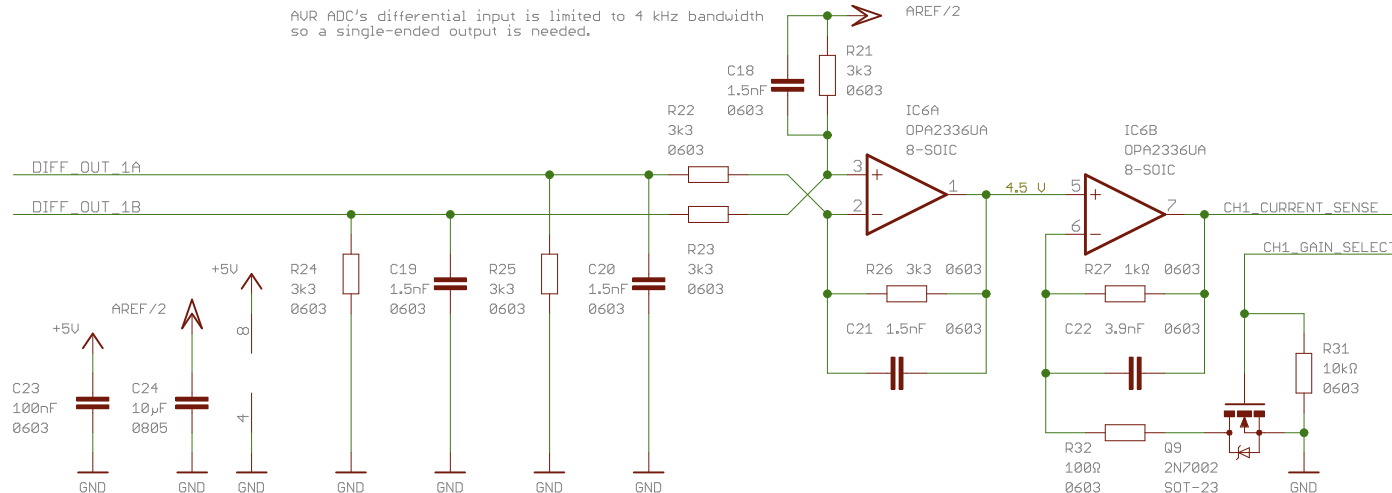
CAN connector and power supplies



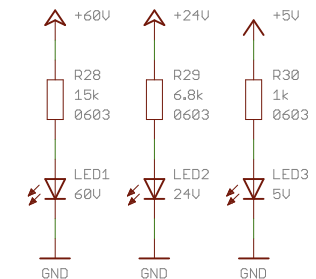
Valve home pots



AUR ADC's differential input is limited to 4 kHz bandwidth so a single-ended output is needed.



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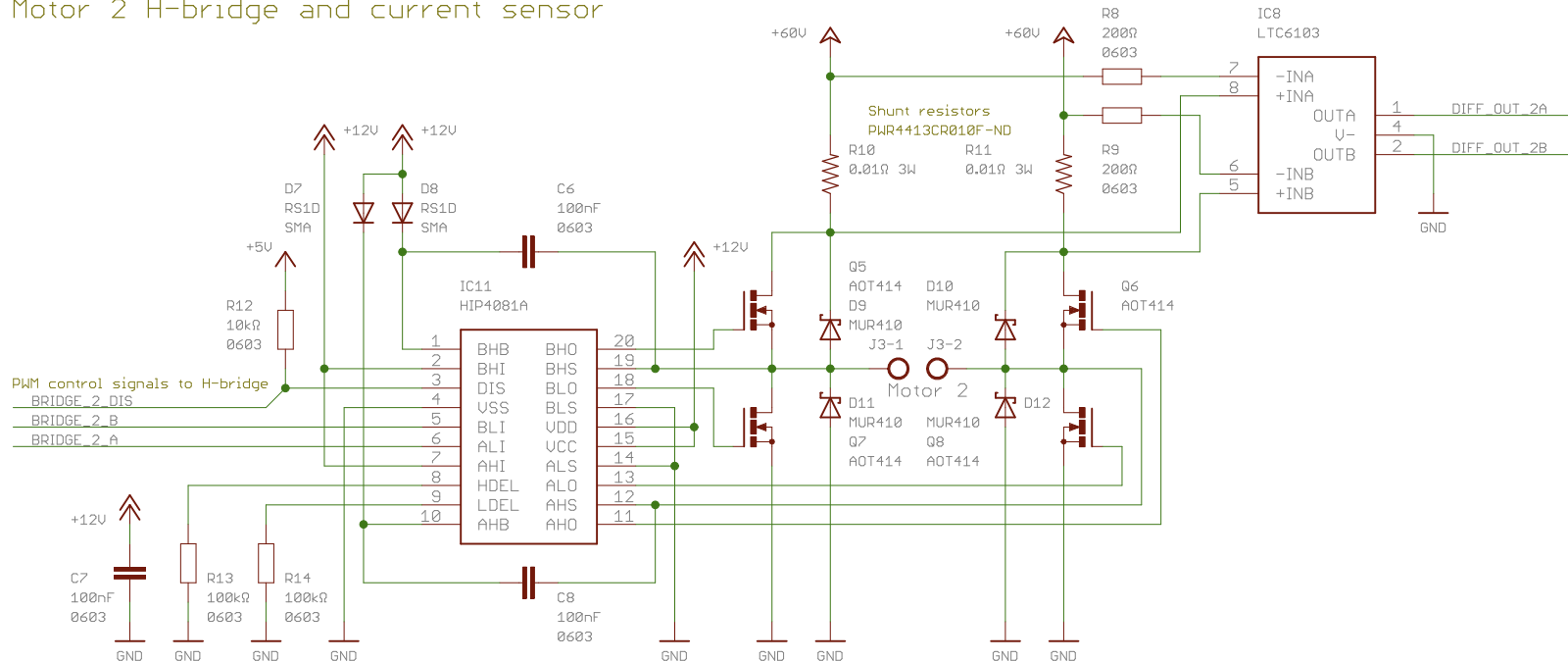


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Motor 2 H-bridge and current sensor



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