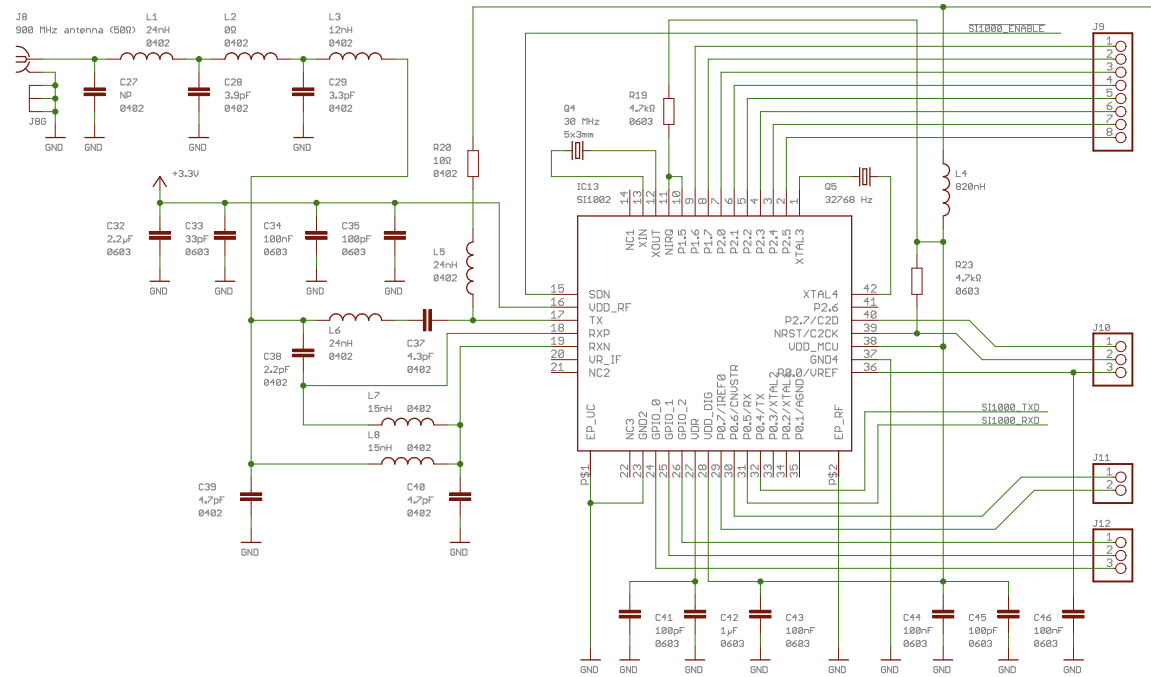
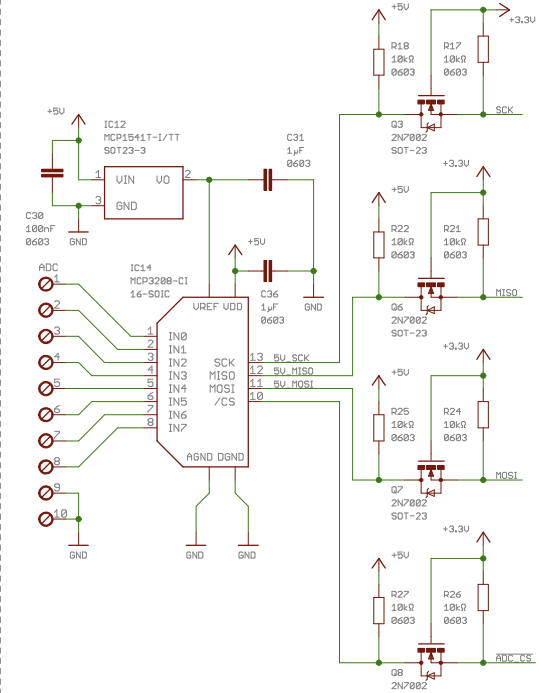


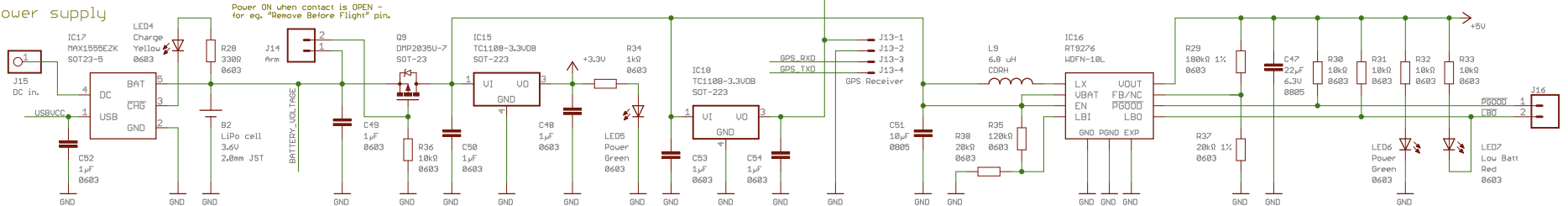
## Microcontroller / Sub-Gigahertz Transceiver (Si1000 series)



## 0-4096 mV Analog Inputs x 8 (MCP3208)



## Power supply



TITLE: SSRPGenericTelemetryModule

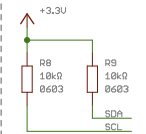
Document Number:

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Date: not saved!

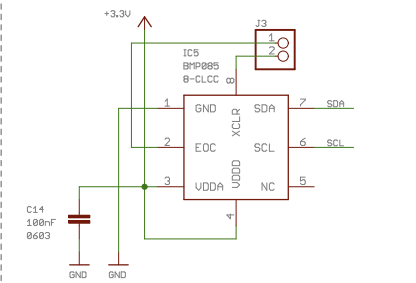
Sheet: 1/1

## I2C pull-ups

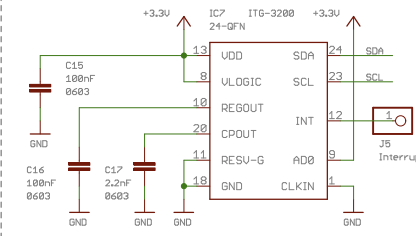


## Barometric Pressure Sensor (BMP085)

Max. altitude approx. 9000m (30000 ft) above sea level.

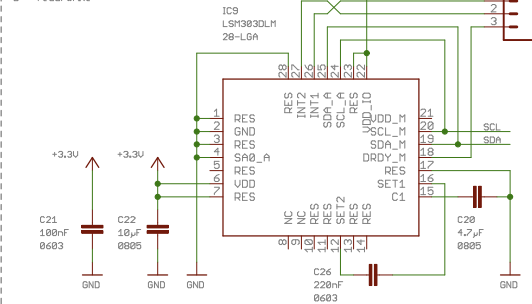


## 3-axis MEMS Gyroscope (ITG-3200)

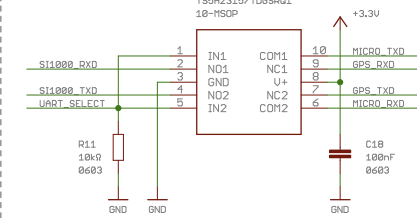


## 3-axis magnetometer/accelerometer (LSM303DLM)

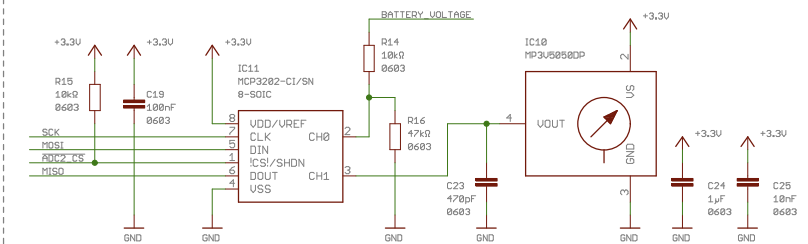
Accelerometer I2C address 0B1100b  
Magnetometer I2C address 0E1110b  
x = hardware address select LSB  
b = read/write



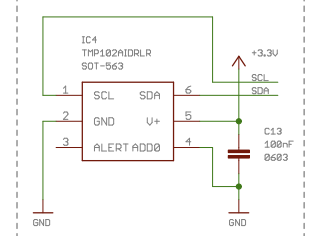
## UART Multiplexer



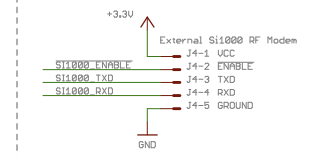
## Pitot differential pressure / ADC



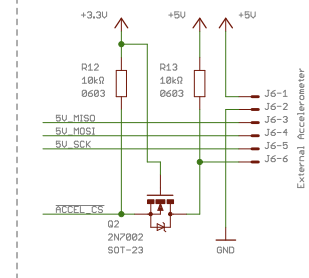
## Temp sensor (TMP102)



## External RF Modem



## External accelerometer



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To do:

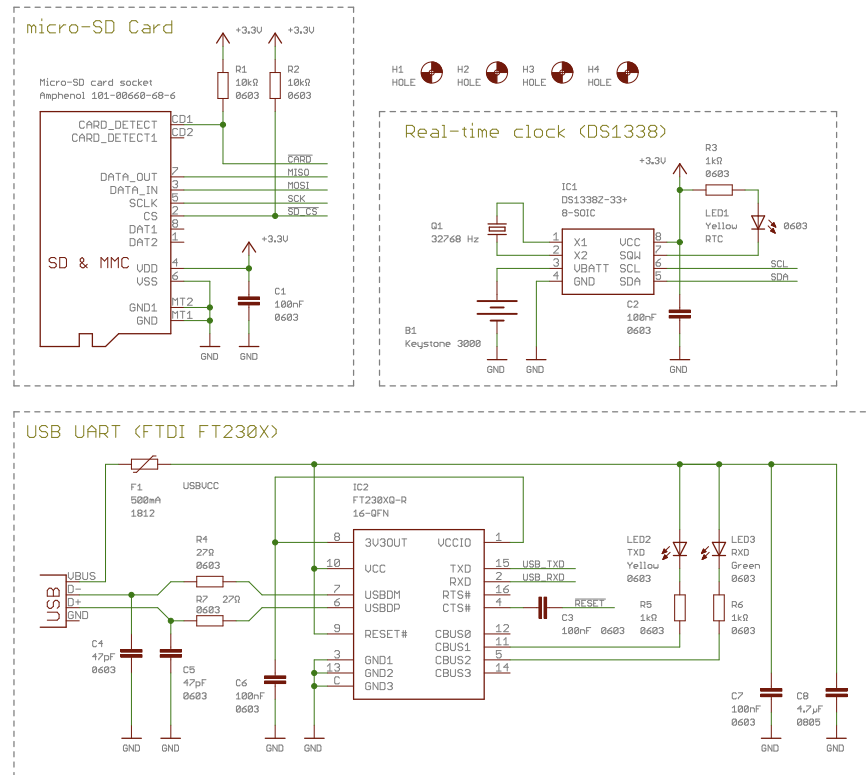
Document all I2C addresses and check collisions

High-range accelerometer choice - AD22282 or MMA2301

Document current budget for all ICs

Breakout spare AVR pins

ITG-3200 supply current = 6.5 mA  
DS1338 supply current = 200  $\mu$ A max.  
LSM303DL1 supply current = 360  $\mu$ A  
Maximum current draw for AT4508011D = 25 mA



General-purpose Rocket/Aircraft/Vehicle Telemetry Payload

Luke Weston, 2013

<https://github.com/lukeweston/SSRPGenericTelemetryModule>

Released under the CERN Open Hardware License:

<http://ohw.org/cernohl>



TITLE: SSRPGenericTelemetryModule

Document Number:

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Date: not saved!

Sheet: 1/1