Lukas Fu Homework 3

Chaotic Time Series - Matlab Code

Lukas Fu

Matlab Code

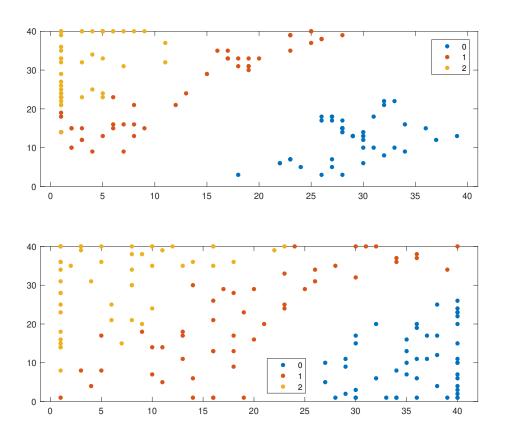
Main

```
clear; clc; clf;
  % initialize variables
4 xTrain = load ('training-set.csv');
  xTest = load('test-set-5.csv');
_{6} nInput = size(xTrain,1);
  nReservoir = 500;
  kRidge = 0.01;
   [wIn, wReservoir] = InitializeNetwork(nInput, nReservoir);
9
  predictTimeStep = 500;
11
  wOut = TrainReservoir (wIn, wReservoir, kRidge, xTrain);
13
  predictionOutput = Predict(wIn, wReservoir, xTest, wOut, predictTimeStep);
  hold on
15
  grid on
  plot3 (predictionOutput (1,:), predictionOutput (2,:), predictionOutput (3,:), ...
17
       ^{\prime}b^{\prime}, LineWidth=0.01)
  plot3 (xTest (1,:), xTest (2,:), xTest (3,:), 'r')
19
  v = [-2 \ 3 \ 2];
 [caz, cel] = view(v);
 legend ('Test Data', 'Prediction')
23 % csv write
  writematrix(predictionOutput(2,:), 'prediction.csv')
  Initialize Network
1 function [wIn, wReservoir] = InitializeNetwork(nInput, nReservoir)
variance1 = sqrt(0.002);
3 variance2 = 2/nReservoir;
  wIn = normrnd(0, variance1, nReservoir, nInput);
  wReservoir = normrnd(0, variance2, nReservoir, nReservoir);
  Train Reservoir
   function wOut = TrainReservoir(wIn, wReservoir, kRidge, xTrain)
       nReservoir = size (wReservoir, 1);
       trainT = size(xTrain, 2);
       R = zeros(nReservoir, trainT);
       rNext = zeros (nReservoir, 1);
5
```

Self-Organizing Maps

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The figure shows the difference between the output using the randomly initialized weights compared to the output after 10 epochs of training. While the clustering is not very clear, the regions are somewhat clearly defined. It does seem like the program is struggling with separating 1 and 2, seeing as they occasionally intrude on each others areas. The empty boundary between 0 and 1 is still present in the lower figure, although to a lesser extent. I find it likely that both of these could be solved by iterating more, since the direction of movement shown between the epoch 0 and 10 tend toward filling out the output space and more clearly differentiating between the classes.



Figur 1: The upper figure shows the output using the randomly chosen weights for the 0:th epoch. The lower figure shows the result of iterating the learning rule for 10 epochs.

Self-Organizing Maps - Matlab Code

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Matlab Code

Main

```
clear; clc; clf;
  nEpoch = 10;
  eta = 0.1;
  sigma = 10;
  irisData = load('iris-data.csv');
   irisLabels = load('iris-labels.csv');
   \max IrisData = \max(irisData);
   stdIrisData = irisData/maxIrisData;
   nPattern = size(irisData,1);
11
   output Dimensions = 40; % dimensions as in matrix dimensions dim x dim
12
13
   weights = zeros(40,40,4);
   for k = 1: size (weights, 1)
15
       for l = 1: size (weights, 2)
16
            for m = 1: size (weights, 3)
17
                weights (k, l, m) = rand;
            end
19
       \quad \text{end} \quad
  end
21
22
   for epoch = 1:nEpoch
23
24
       for trial = 1:nPattern
25
            iPattern = 1 + fix (rand*nPattern);
26
            pattern(1,1,:) = irisData(iPattern,:);
27
            [i0, j0] = FindWinningNeuron(pattern, weights);
28
            i0 = i0 + normrnd(0, 0.02);
            j0 = j0 + normrnd(0, 0.02);
30
            r0 = [i0 \ j0];
31
32
            for i = 1:outputDimensions
                for j = 1:outputDimensions
34
                     r = [i j];
35
                     distanceToR0 = vecnorm(r-r0);
36
                     if distanceToR0 < 3 * sigma
38
                         h = \exp(-distanceToR0^2 / (2*sigma^2));
39
                         dw = eta * h * (pattern - weights(i, j,:));
40
                         weights(i,j,:) = weights(i,j,:) + dw;
41
```