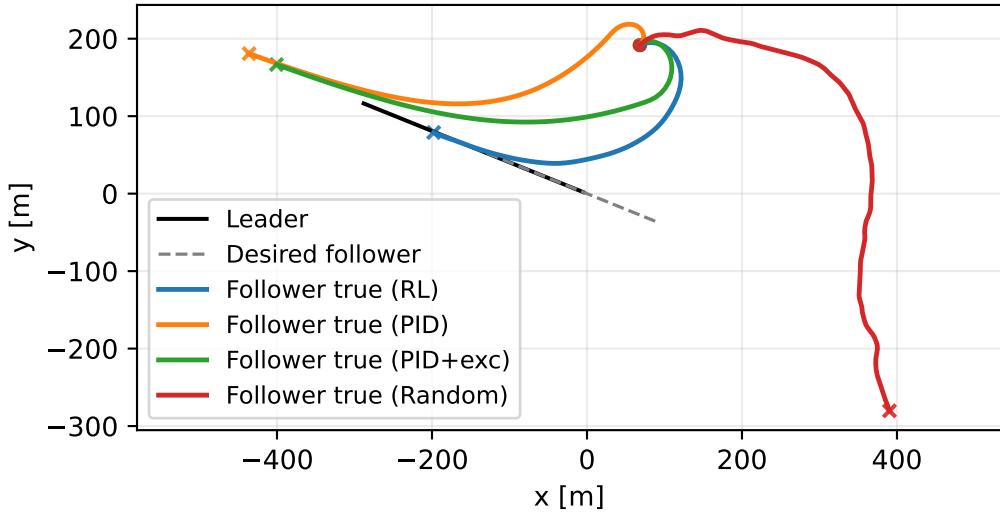
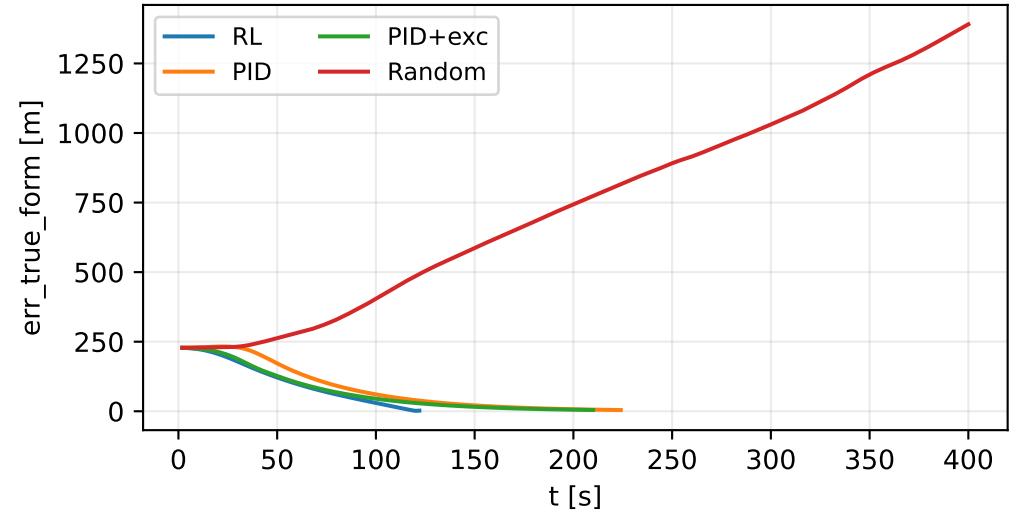


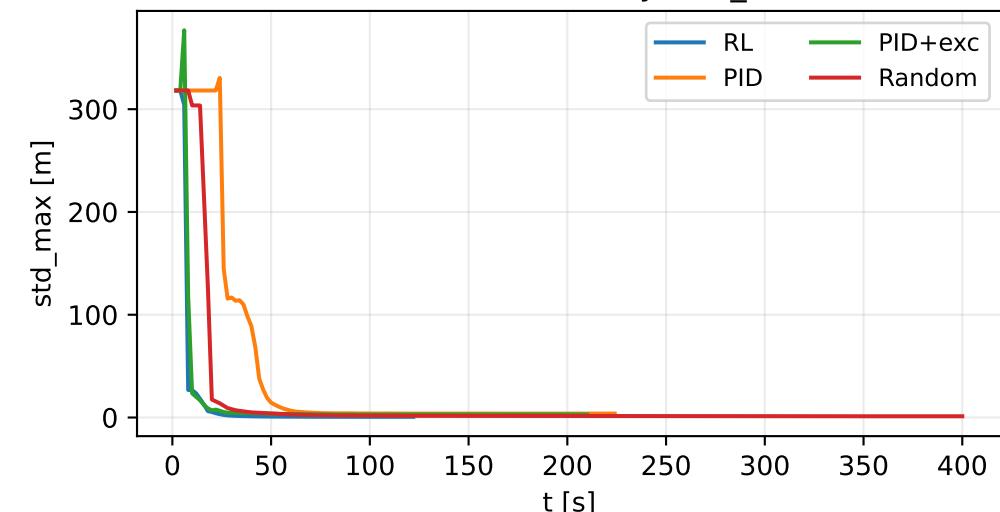
Trajectories (matched seed)



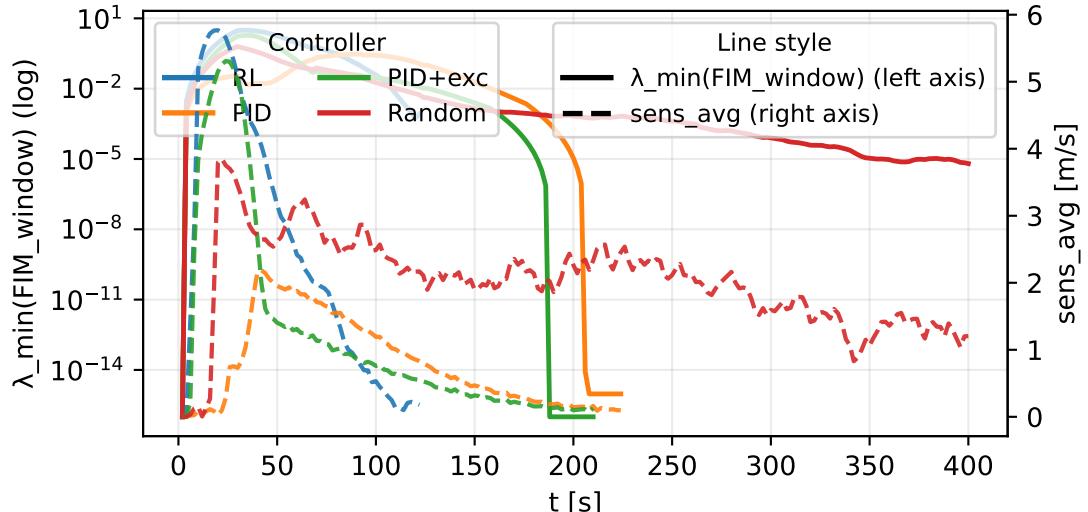
TRUE formation error



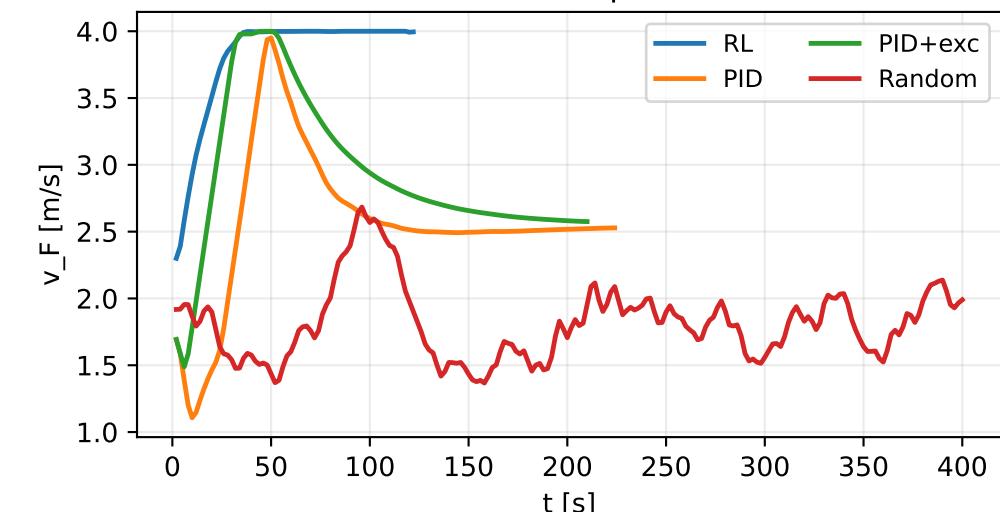
Estimator uncertainty (std_max)



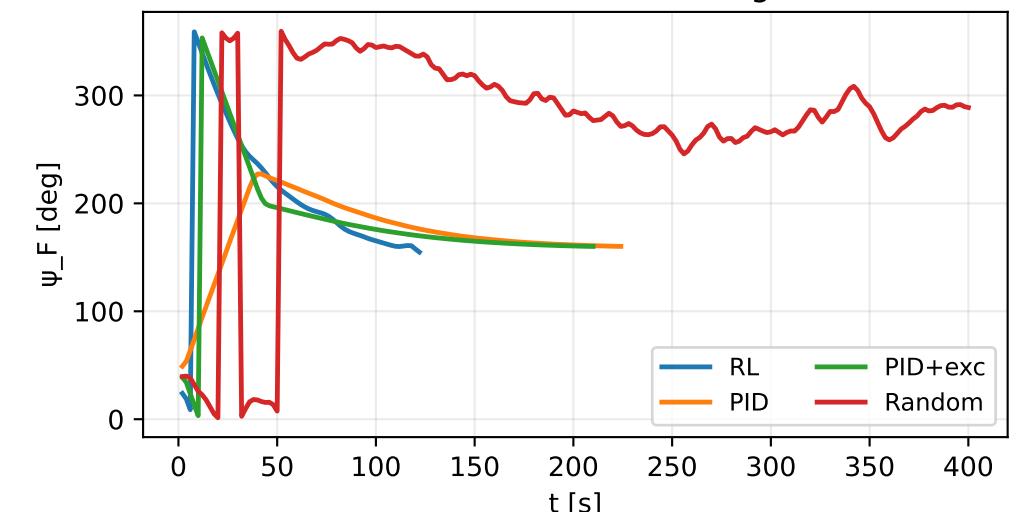
Information and excitation



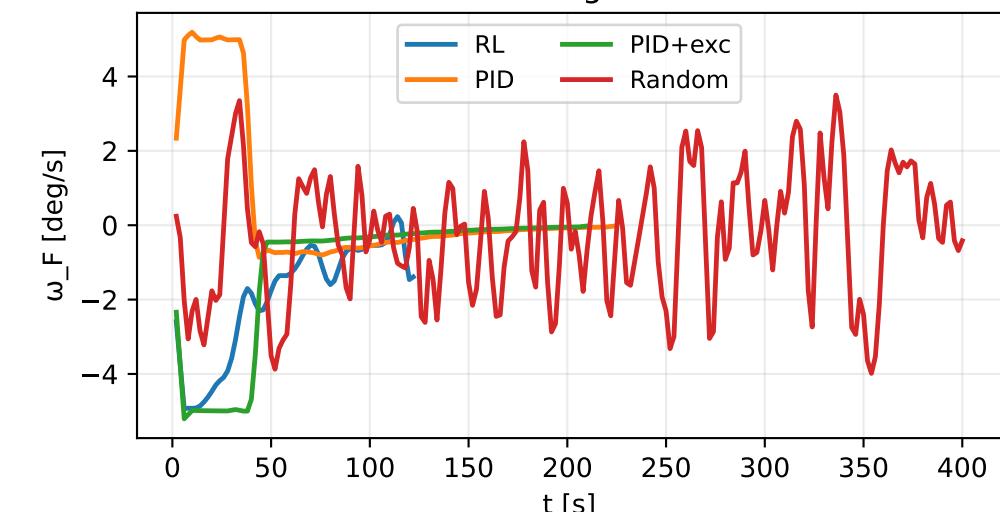
Follower speed



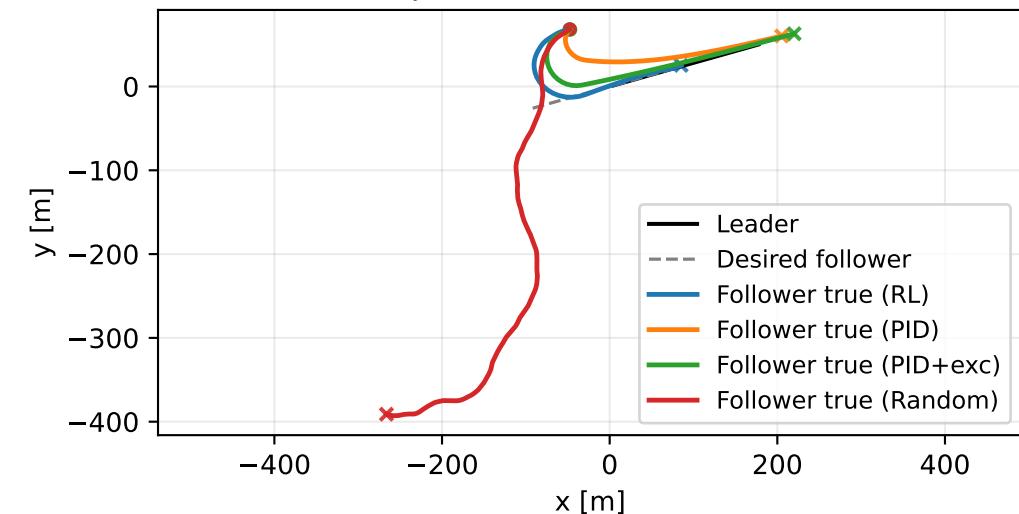
Follower course/heading



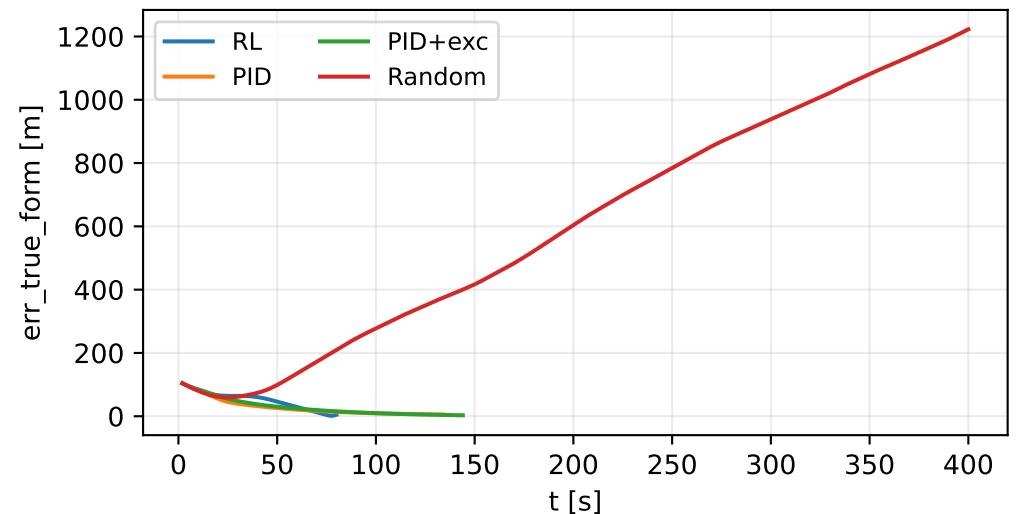
Follower angular rate



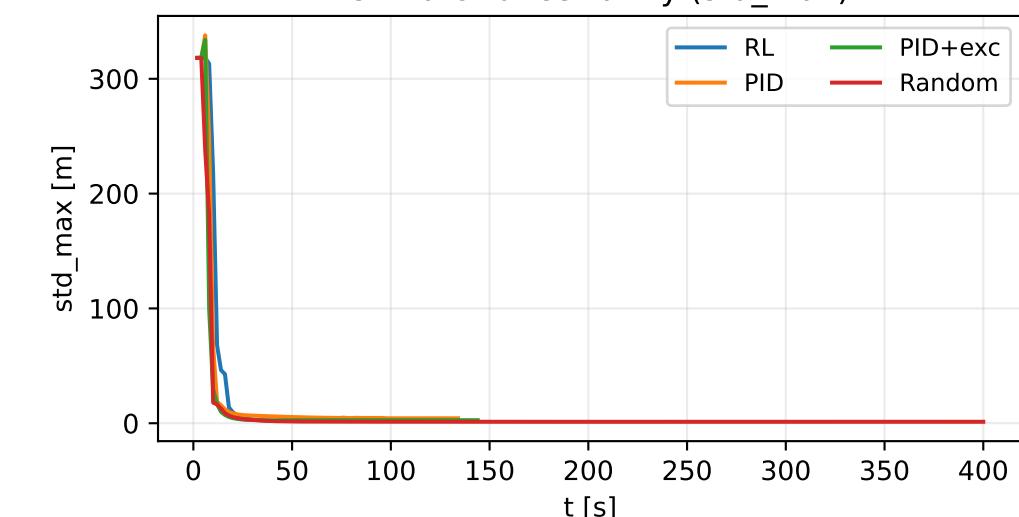
Trajectories (matched seed)



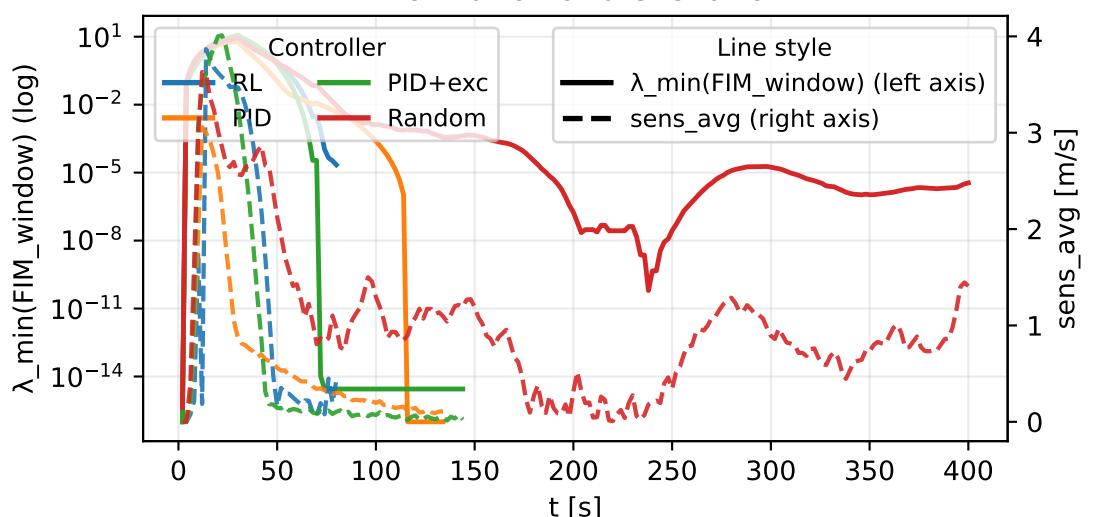
TRUE formation error



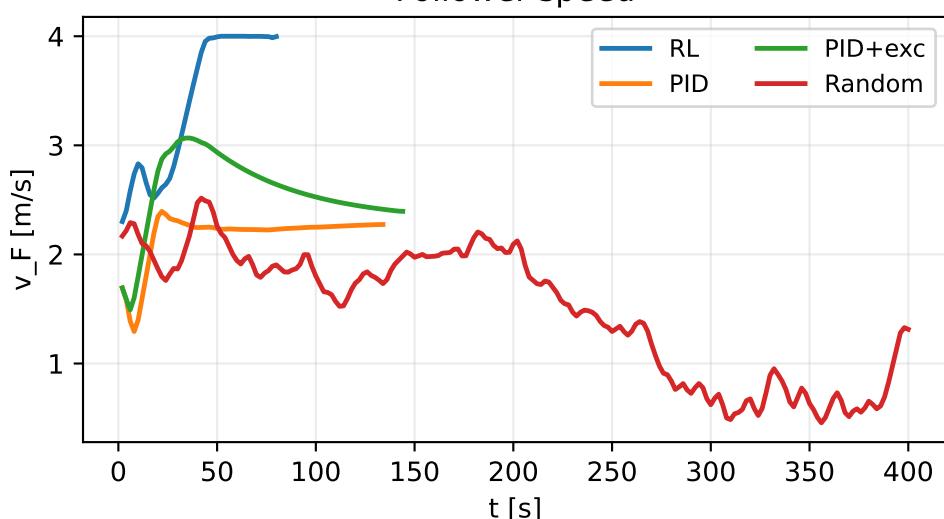
Estimator uncertainty (std_max)



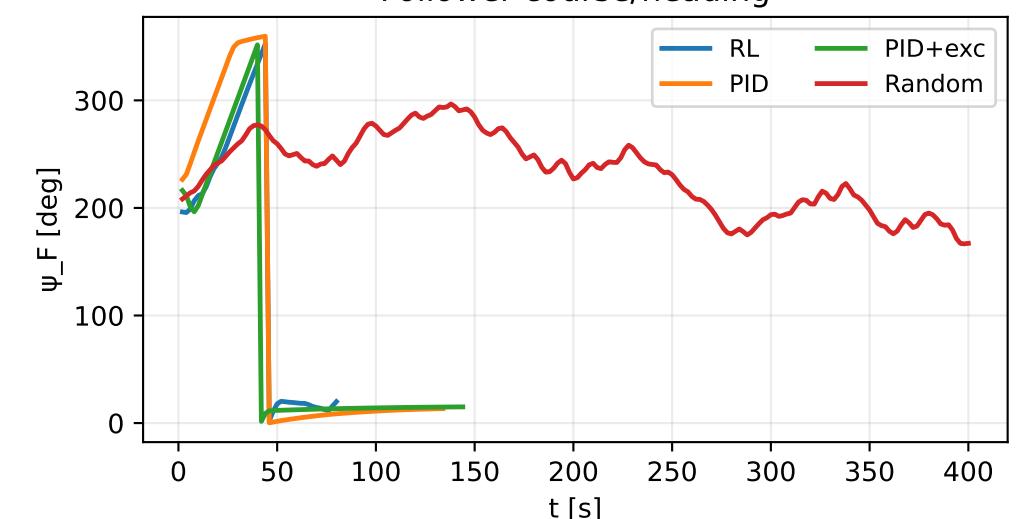
Information and excitation



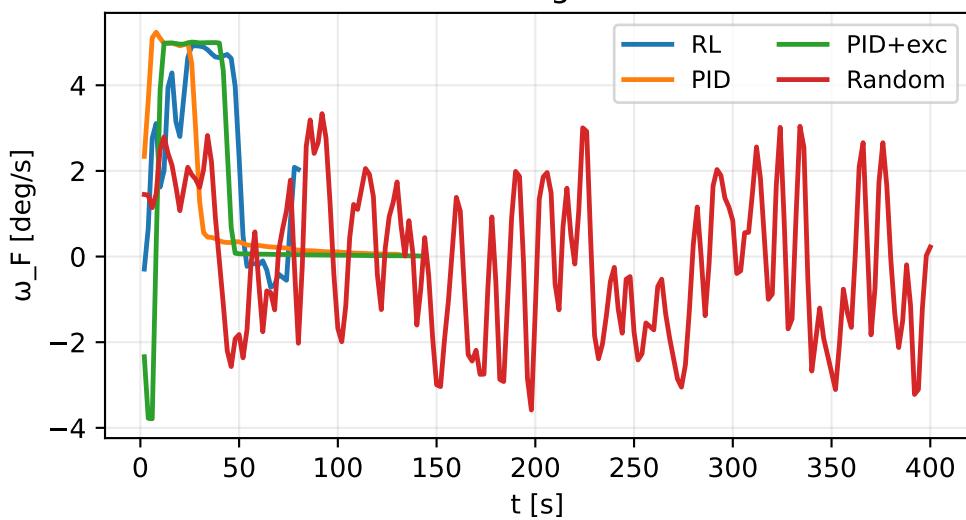
Follower speed



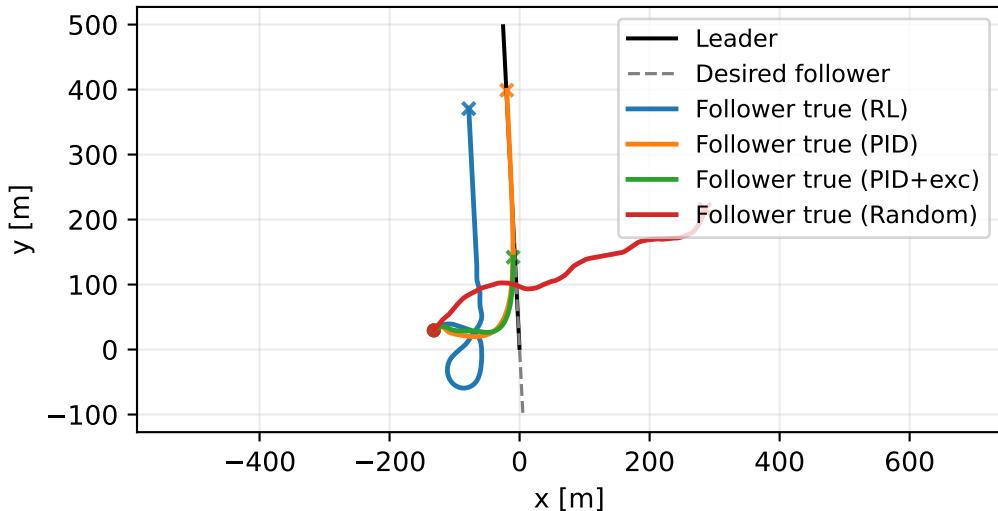
Follower course/heading



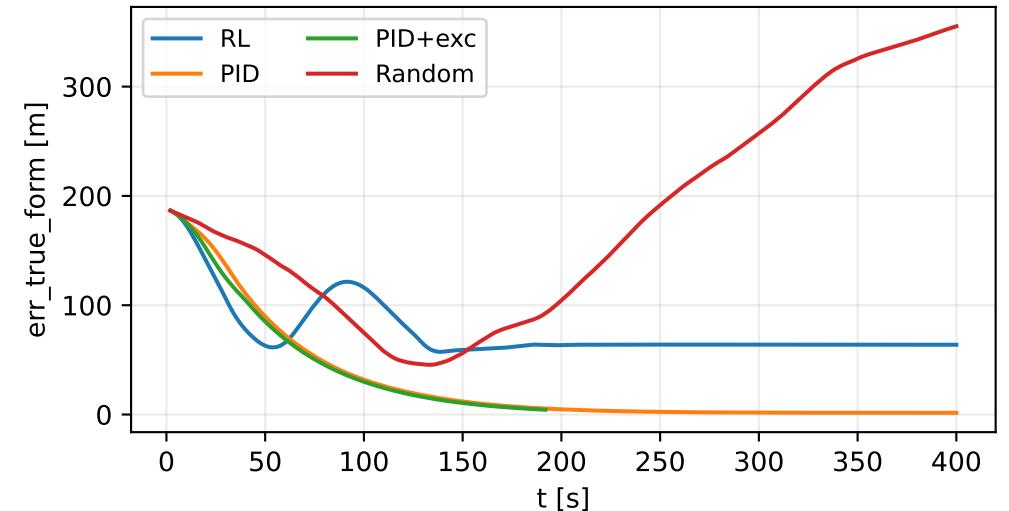
Follower angular rate



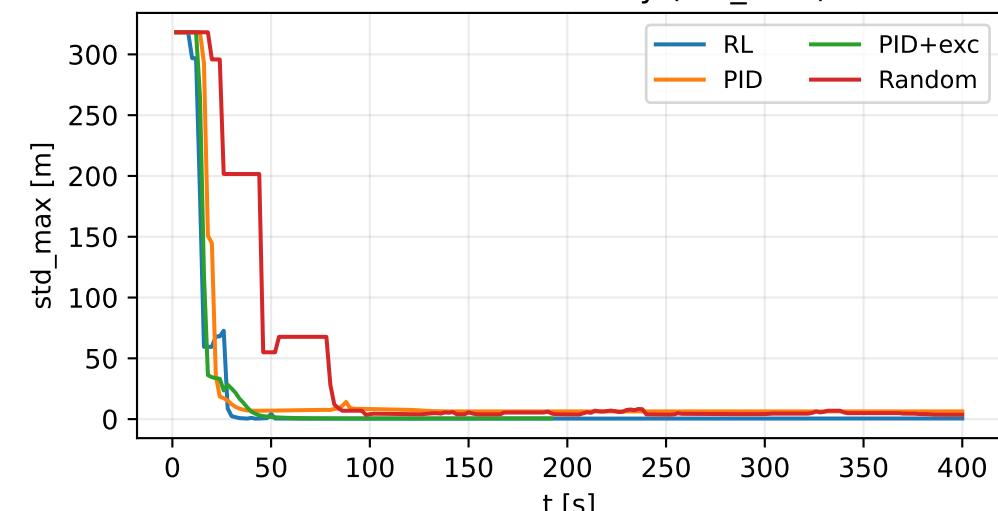
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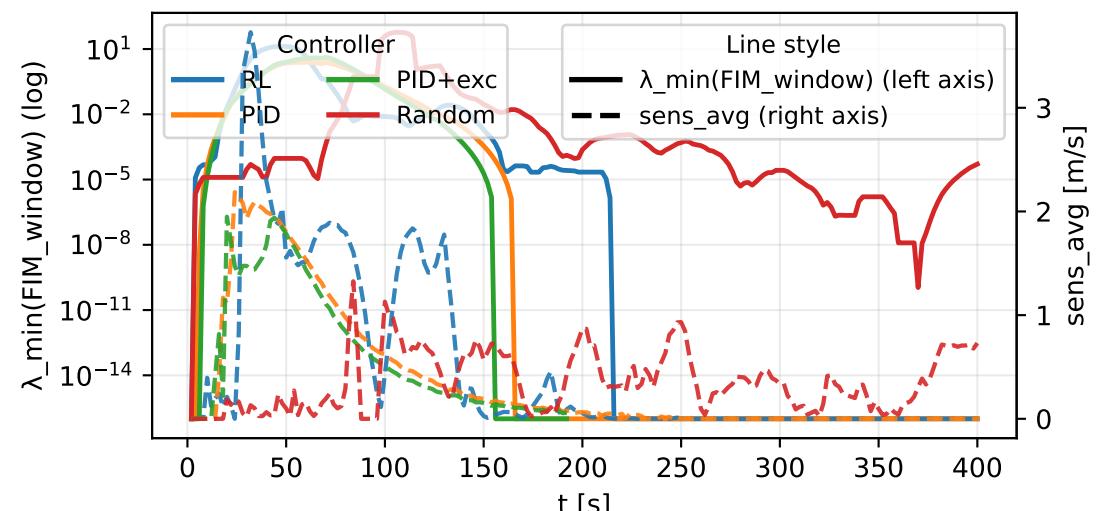
TRUE formation error



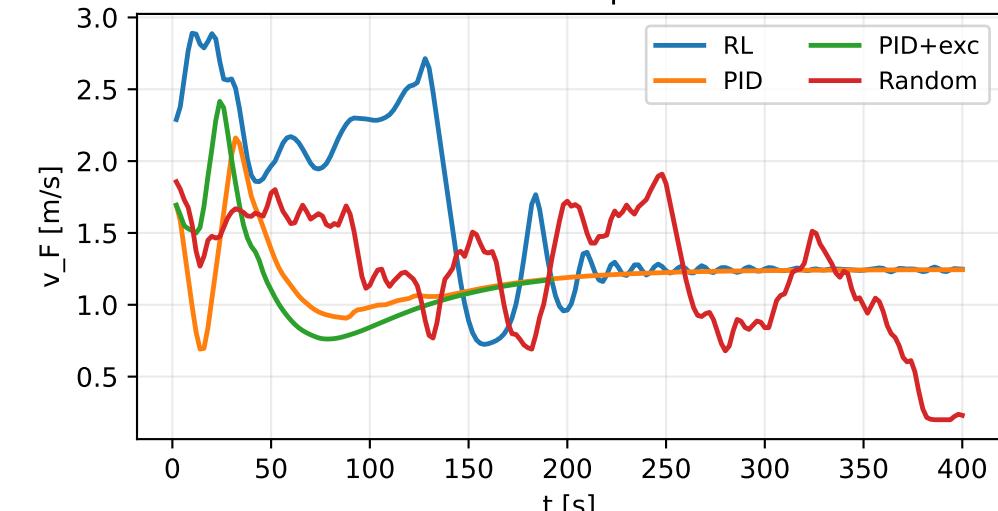
Estimator uncertainty (std_max)



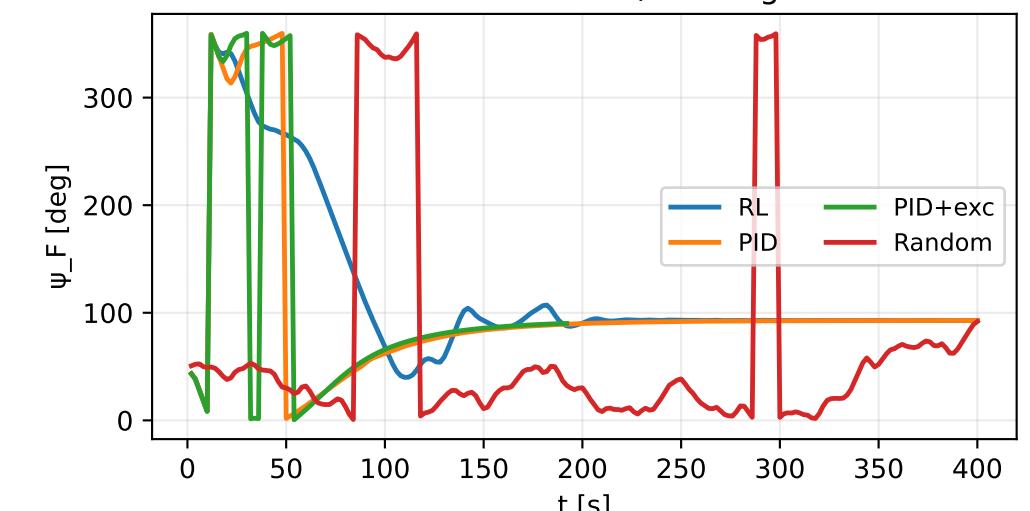
Information and excitation



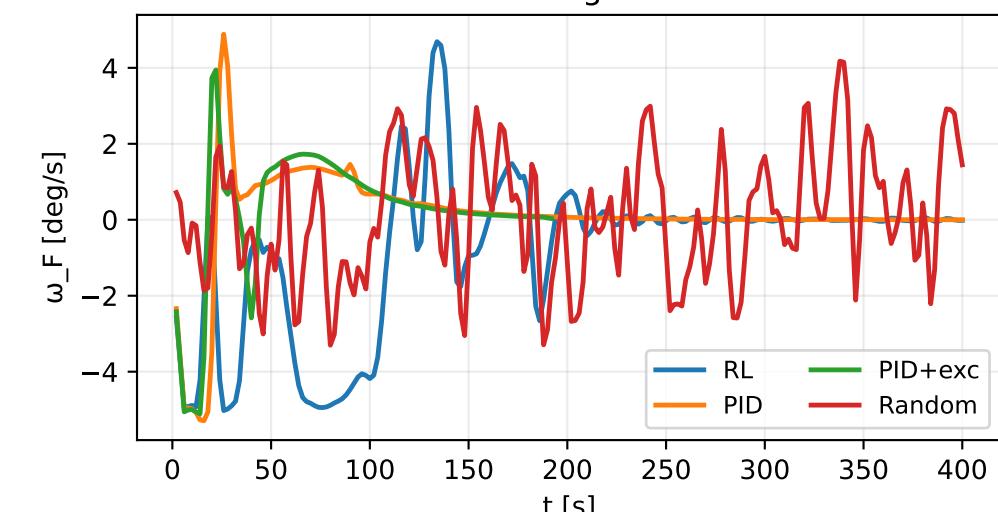
Follower speed



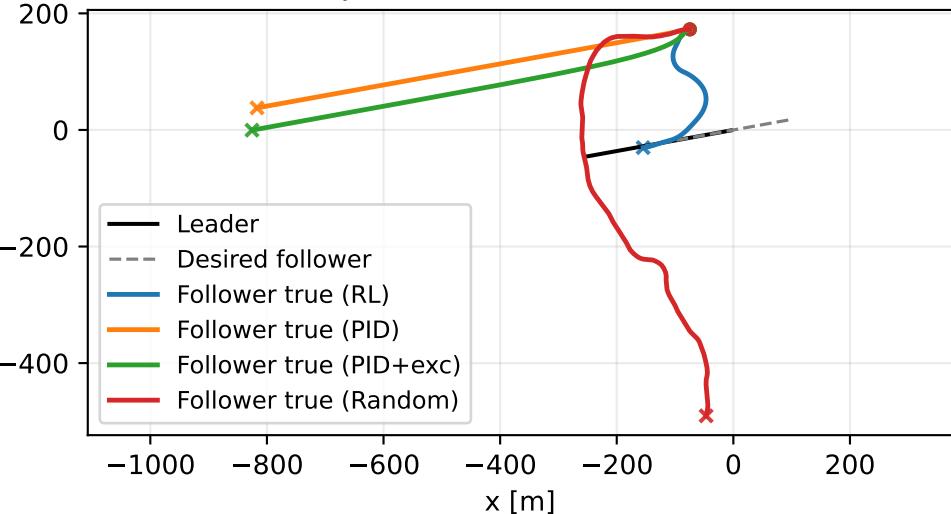
Follower course/heading



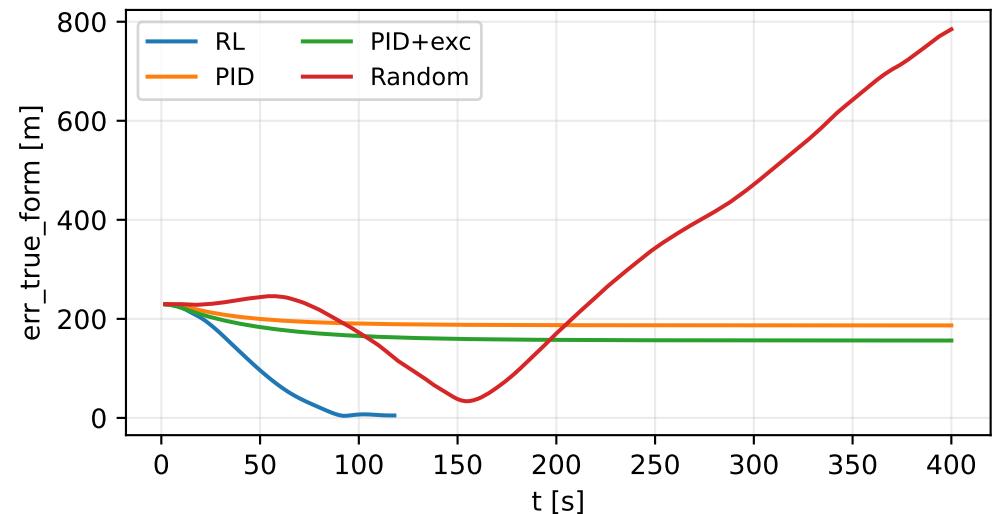
Follower angular rate



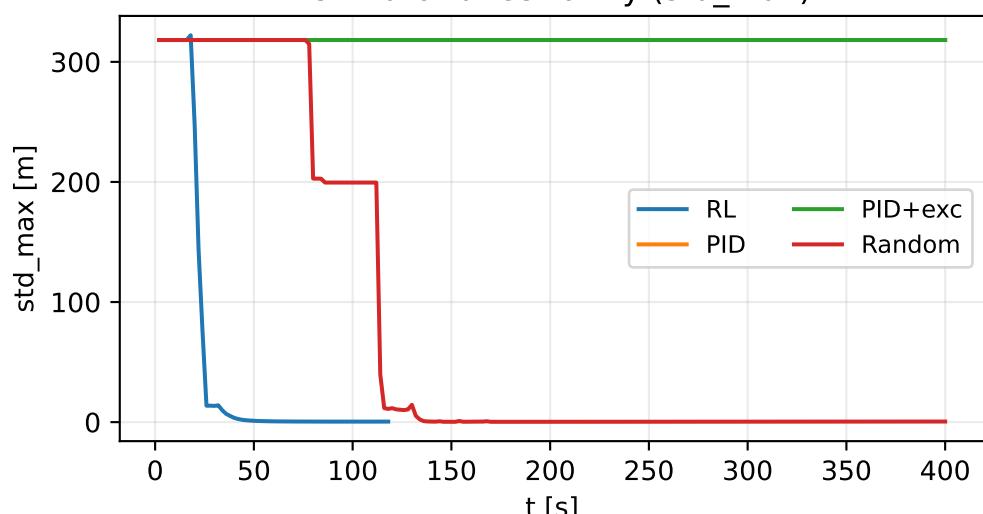
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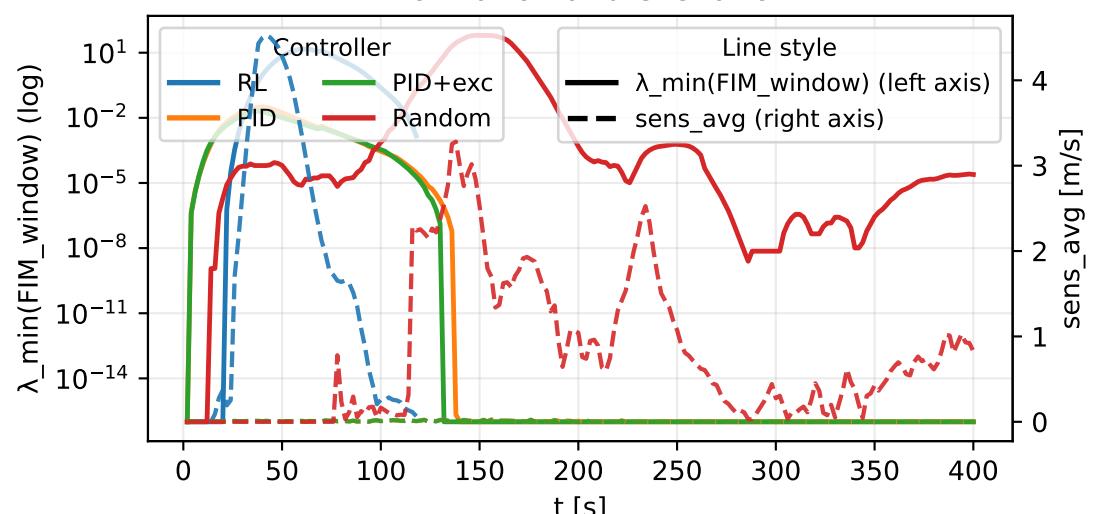
TRUE formation error



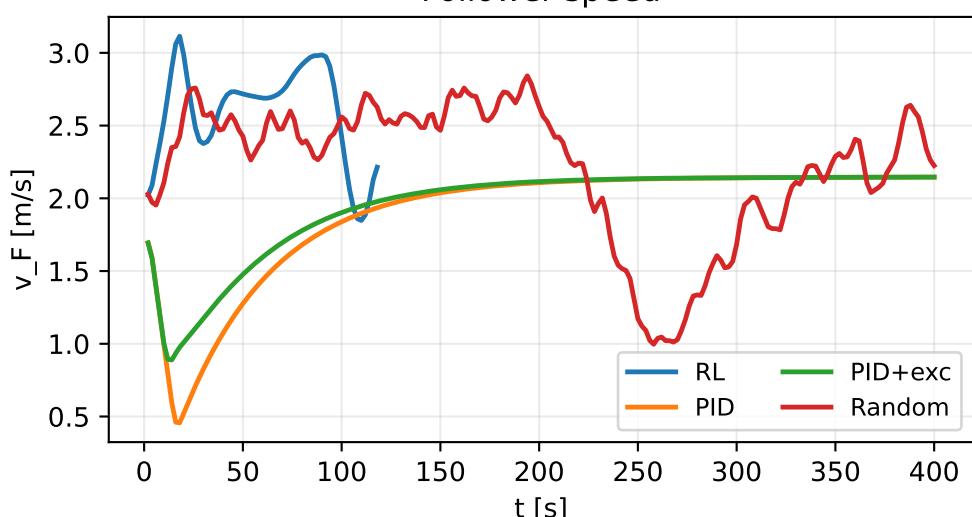
Estimator uncertainty (std_max)



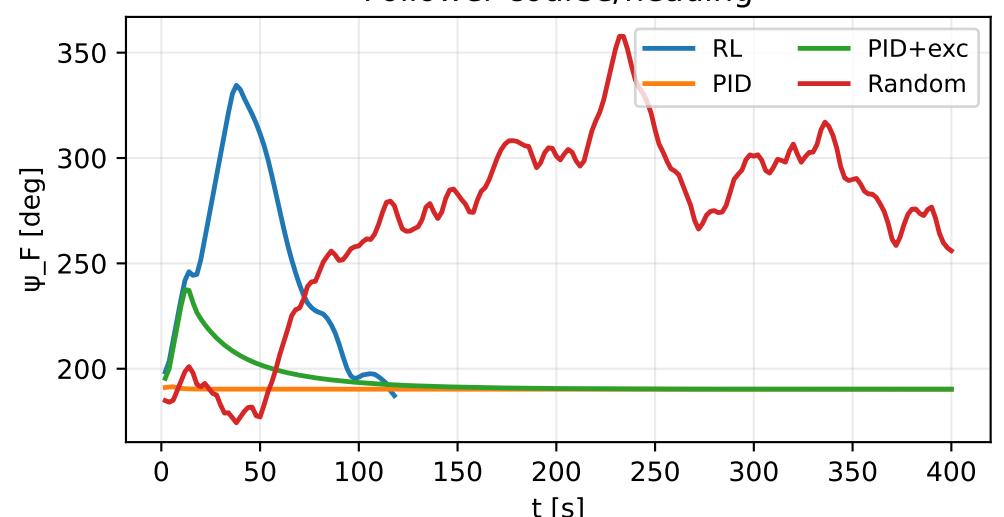
Information and excitation



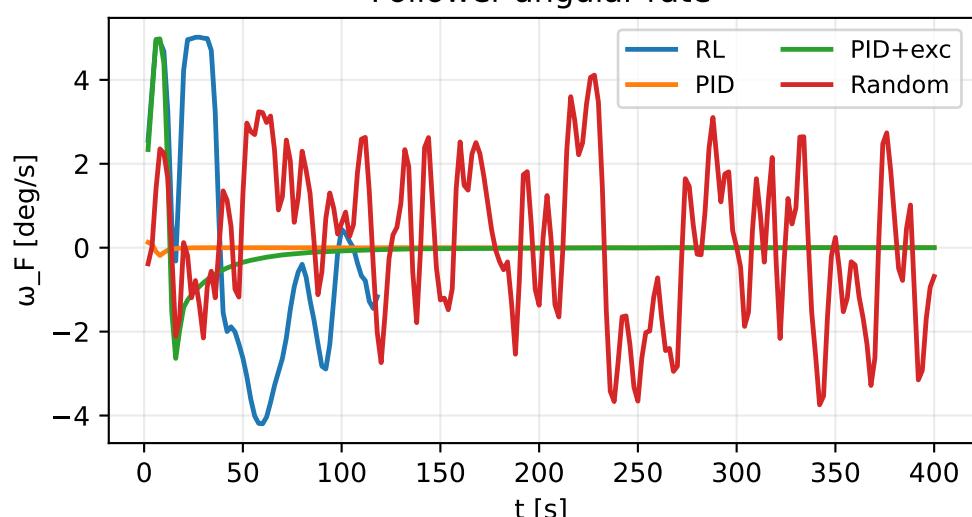
Follower speed



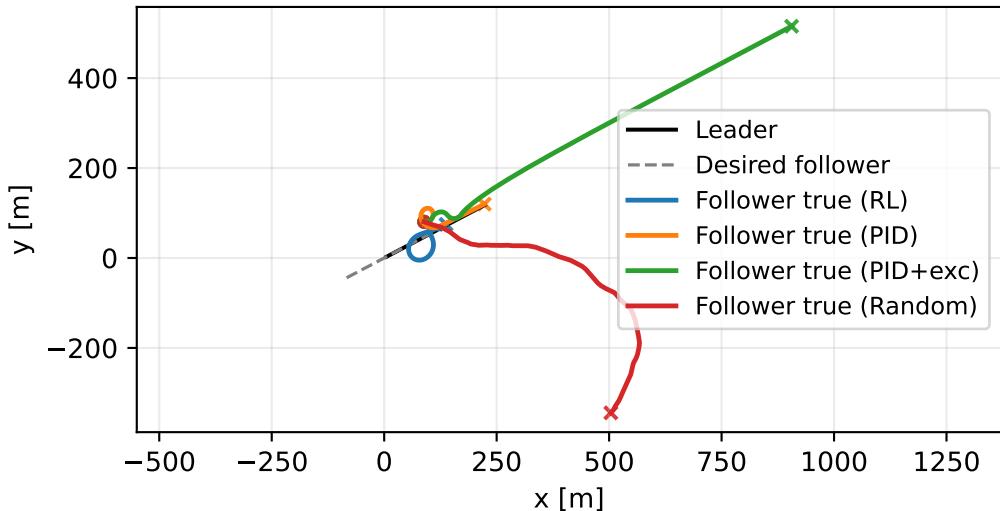
Follower course/heading



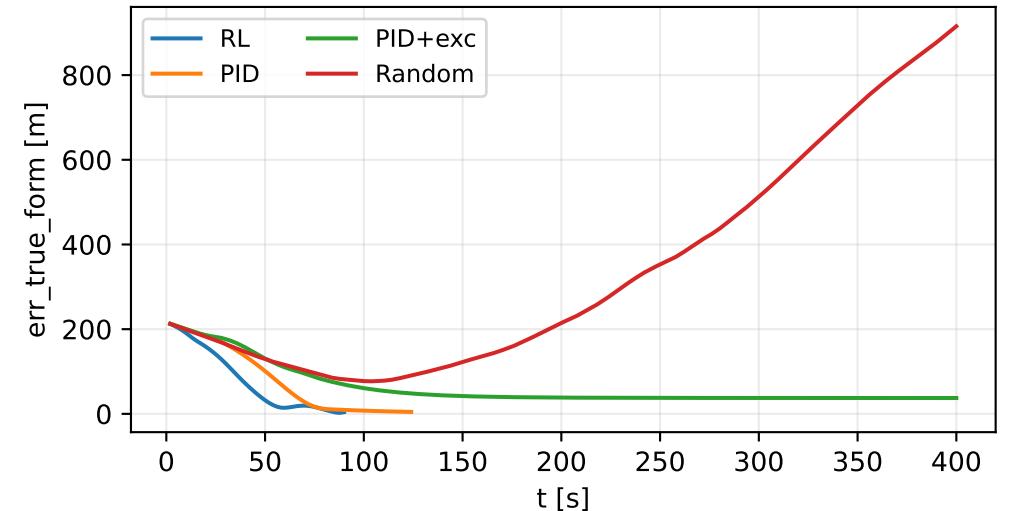
Follower angular rate



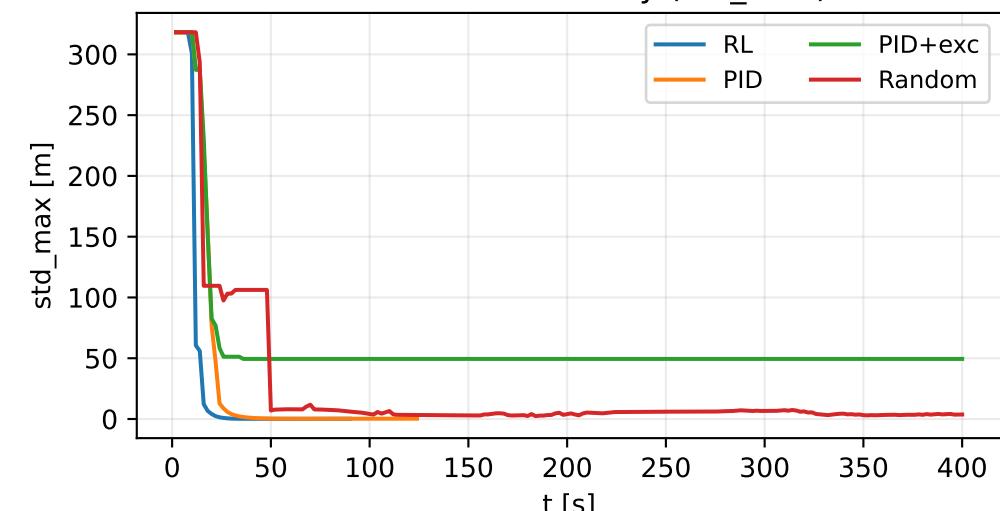
Trajectories (matched seed)



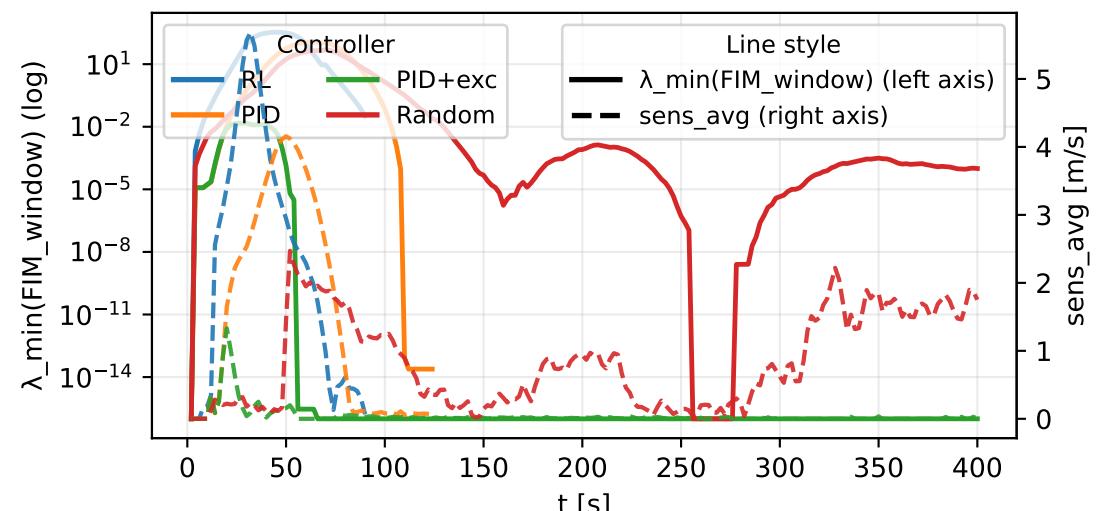
TRUE formation error



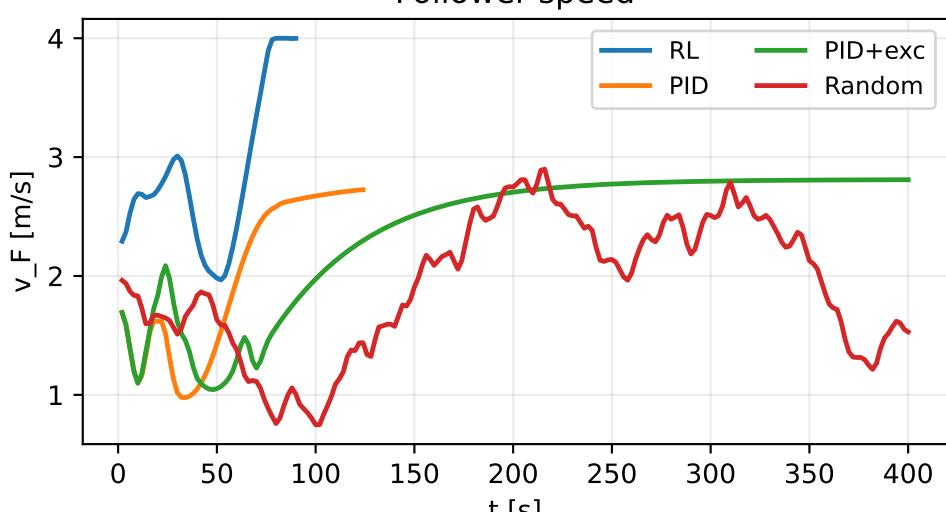
Estimator uncertainty (std_max)



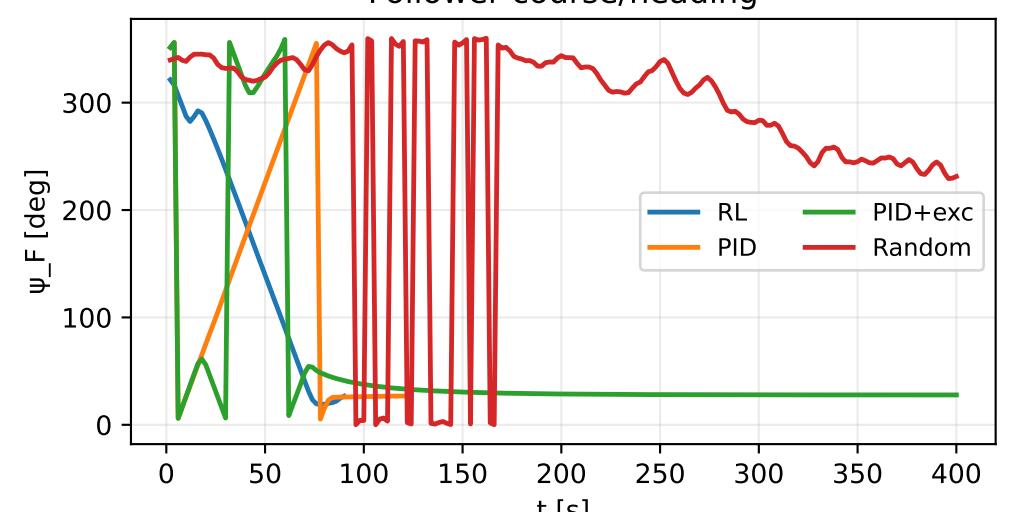
Information and excitation



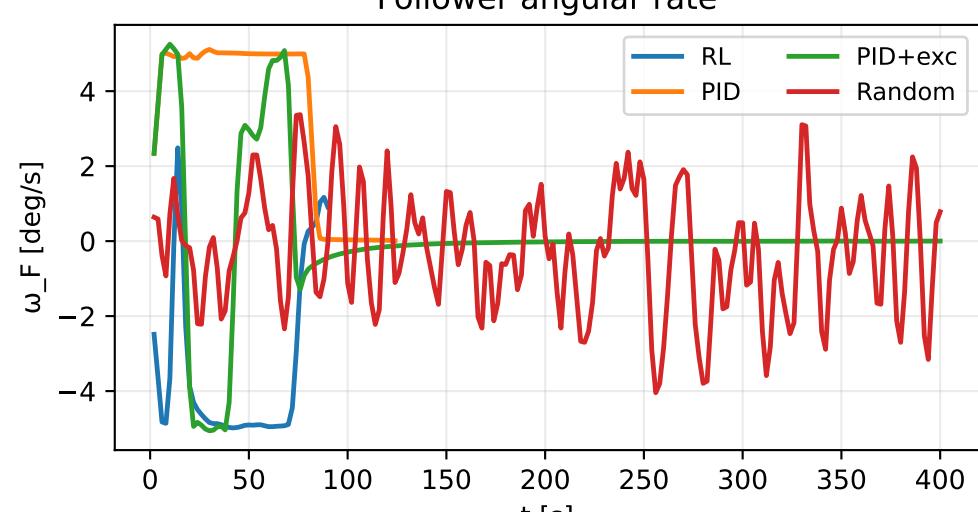
Follower speed



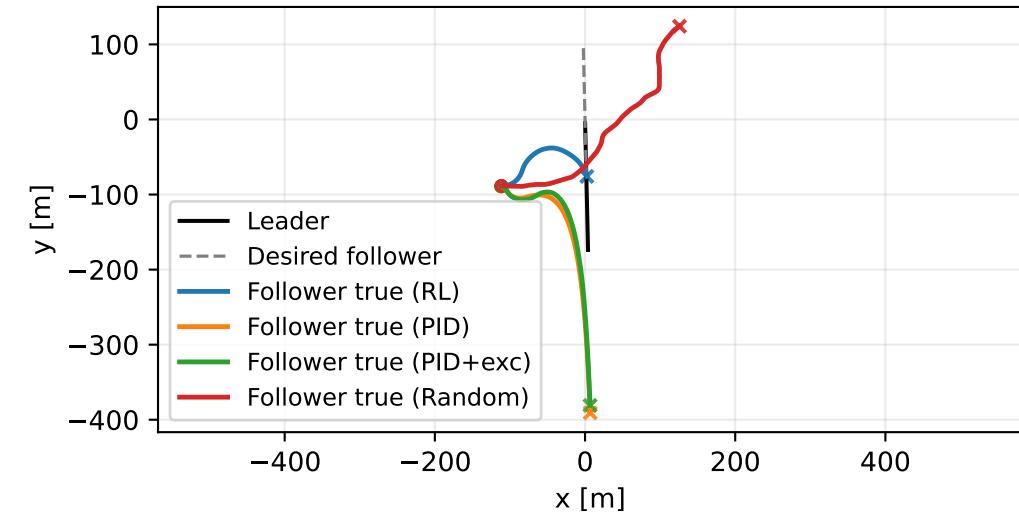
Follower course/heading



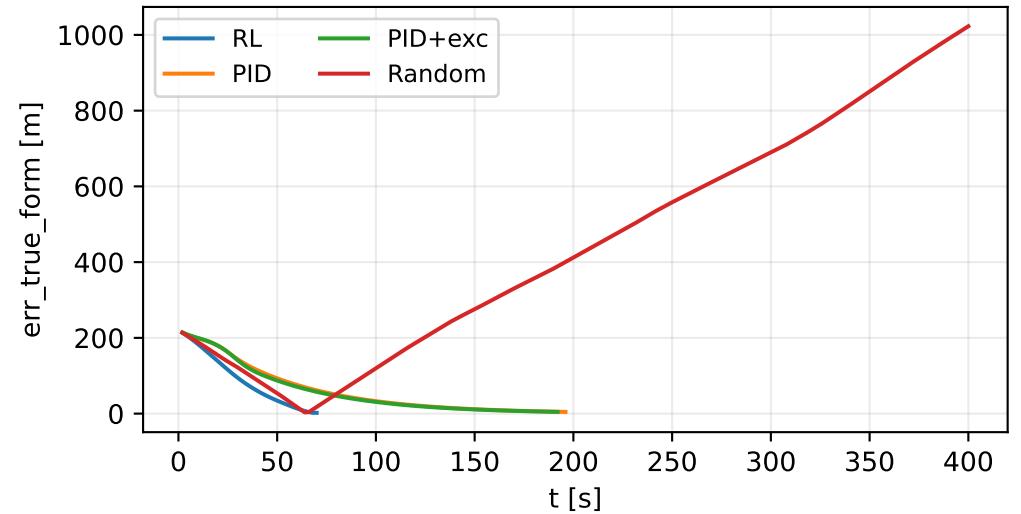
Follower angular rate



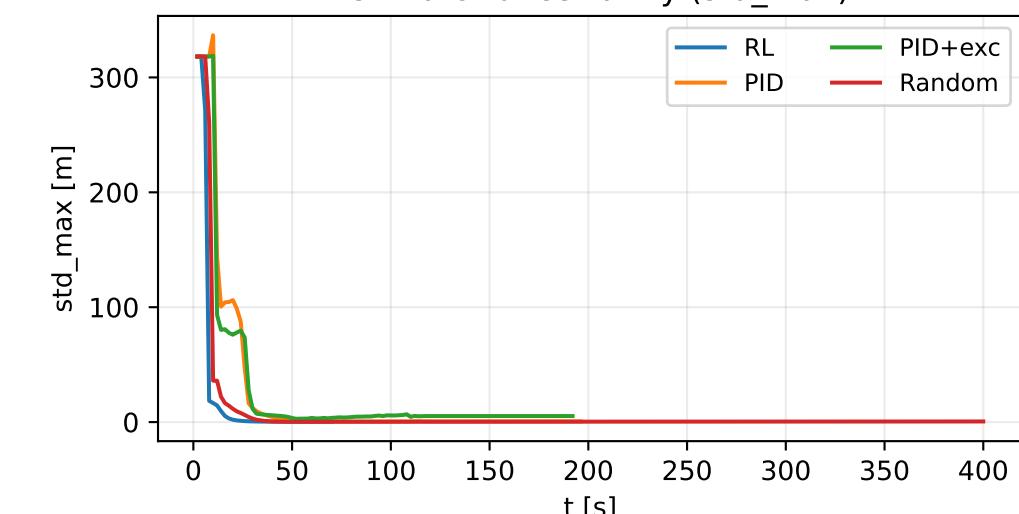
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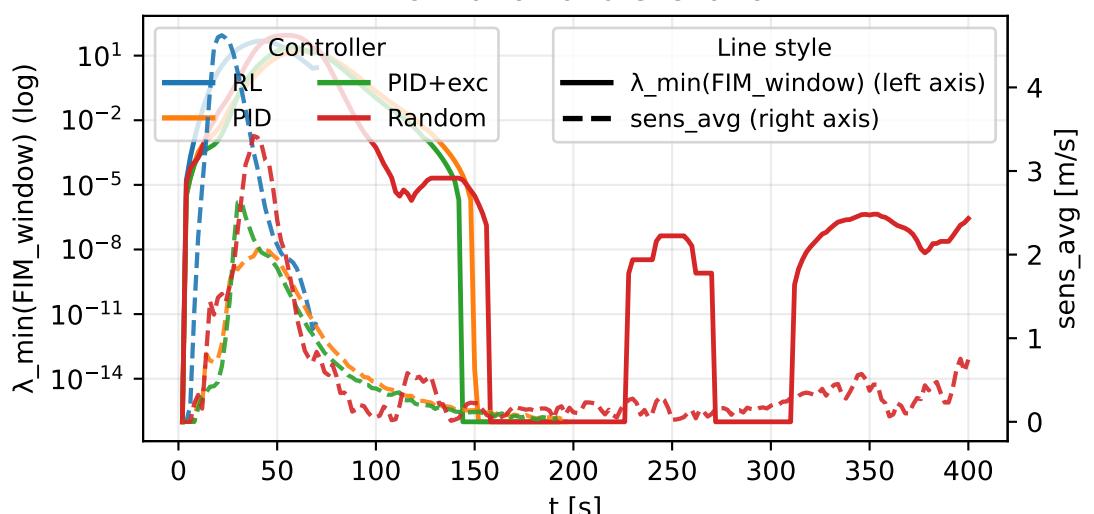
TRUE formation error



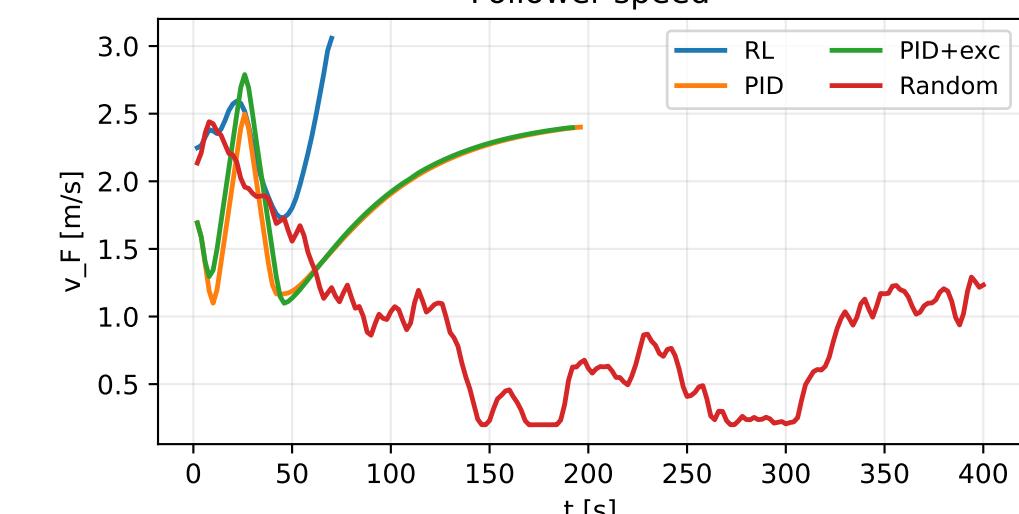
Estimator uncertainty (std_max)



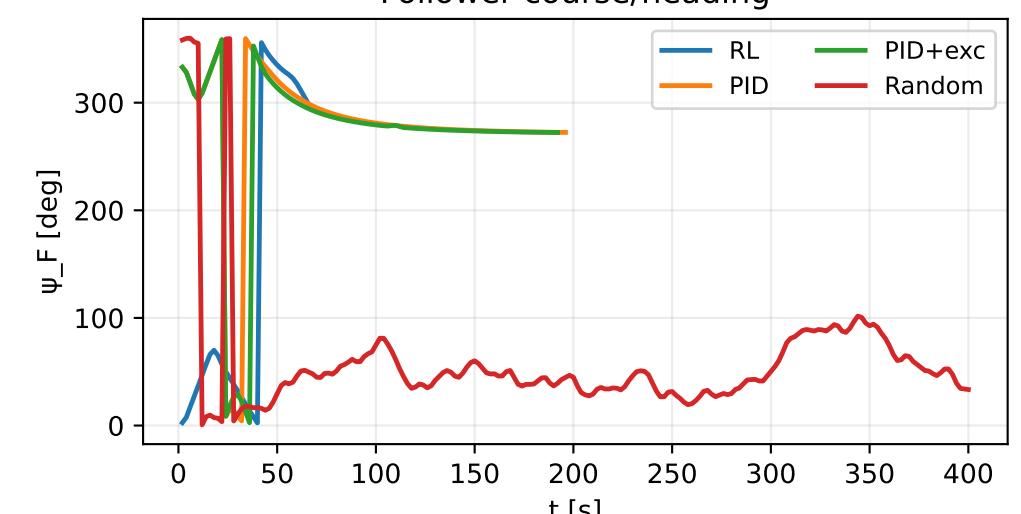
Information and excitation



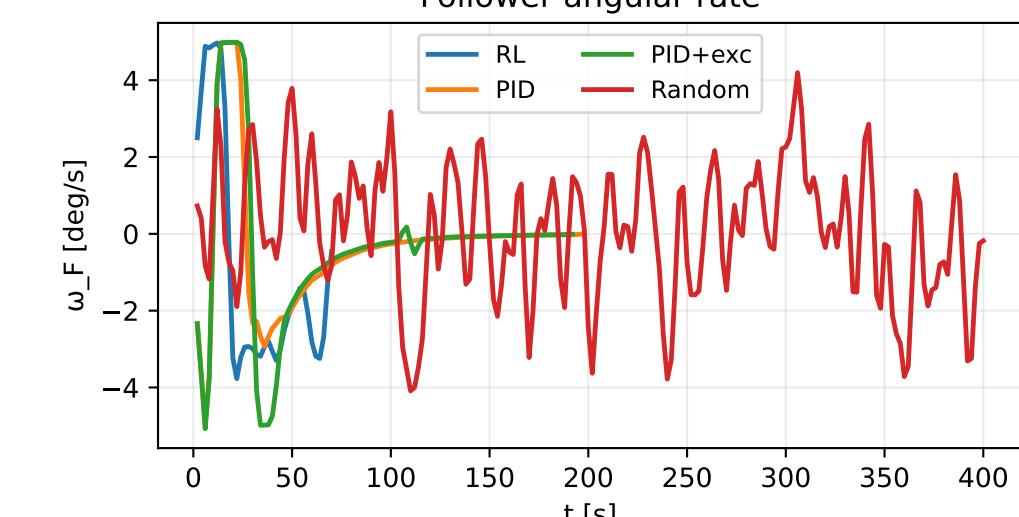
Follower speed



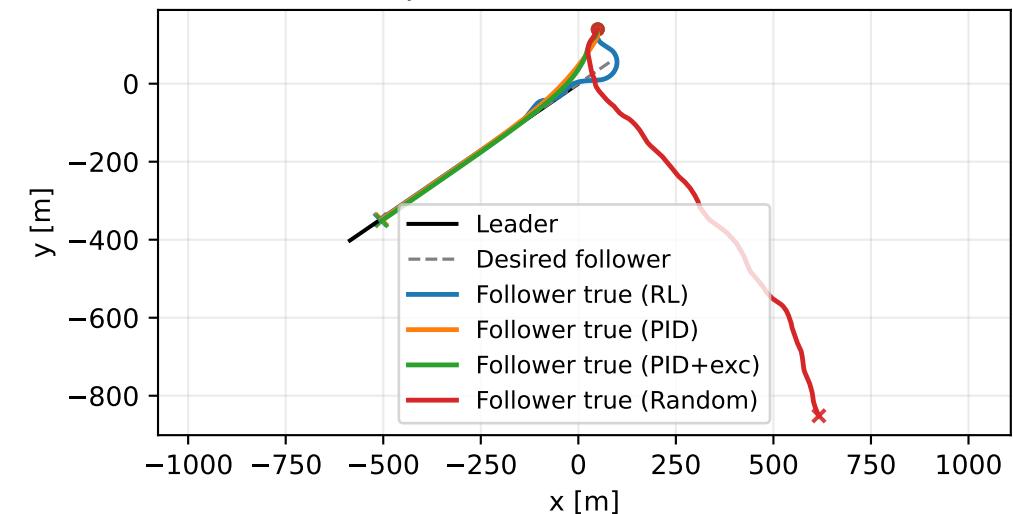
Follower course/heading



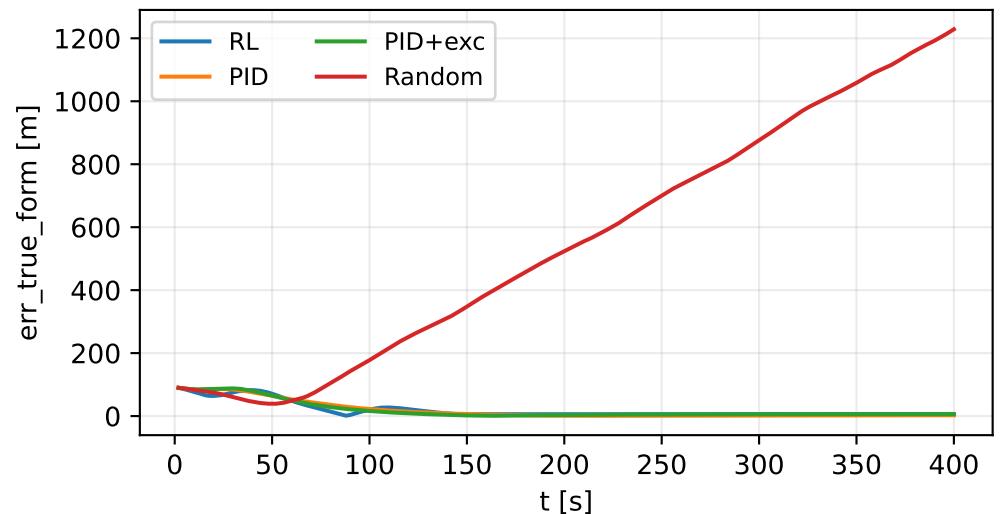
Follower angular rate



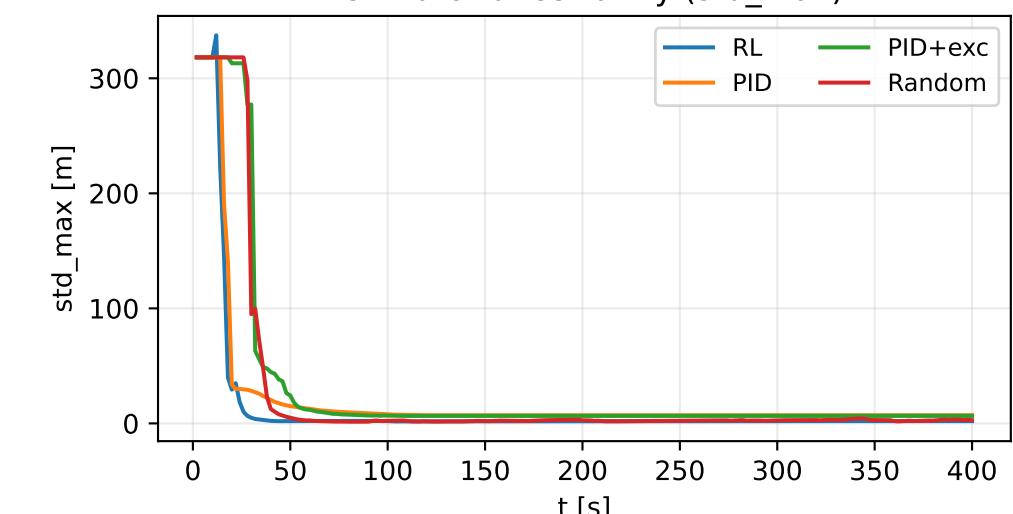
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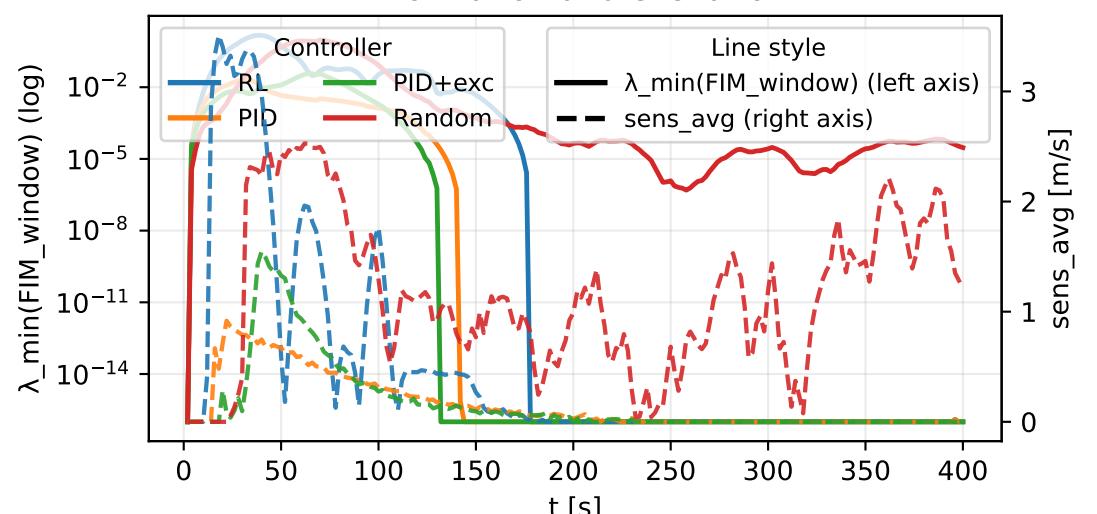
TRUE formation error



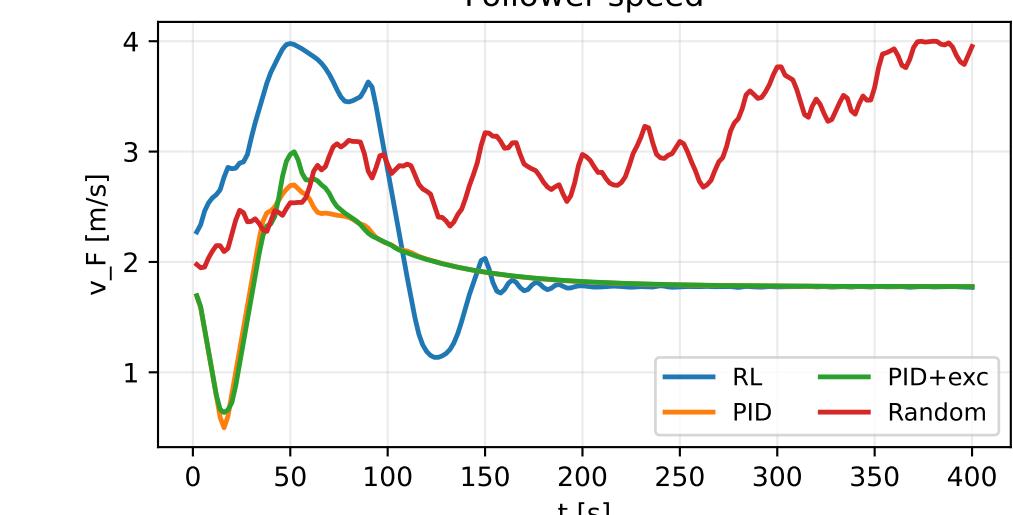
Estimator uncertainty (std_max)



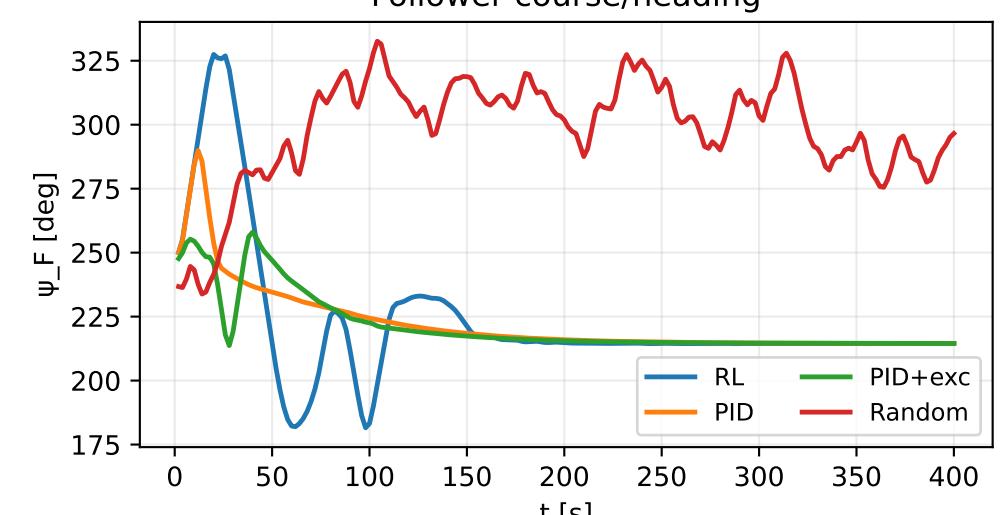
Information and excitation



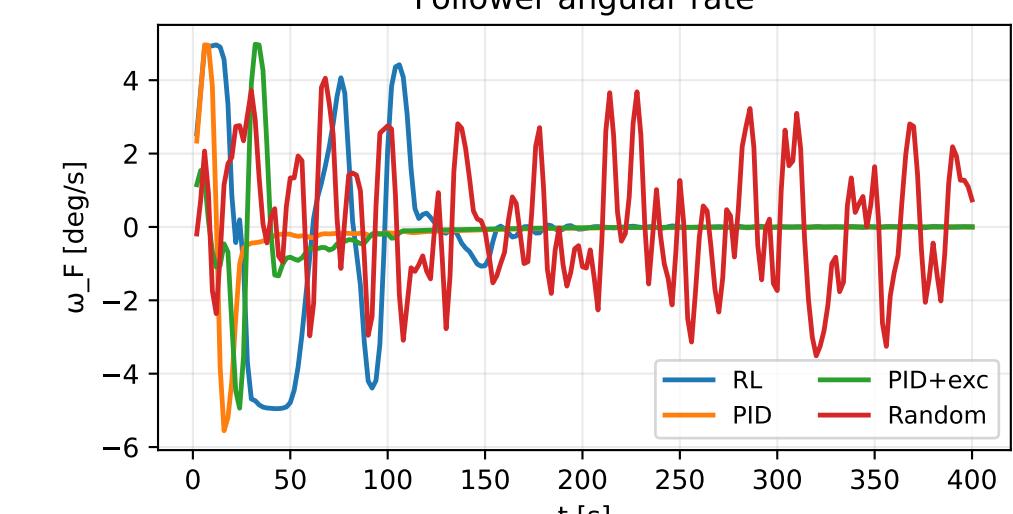
Follower speed



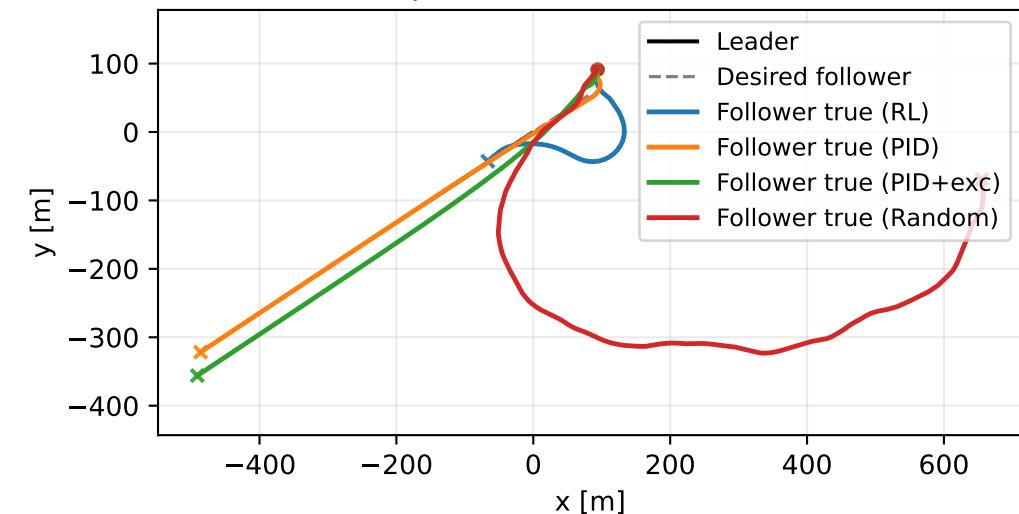
Follower course/heading



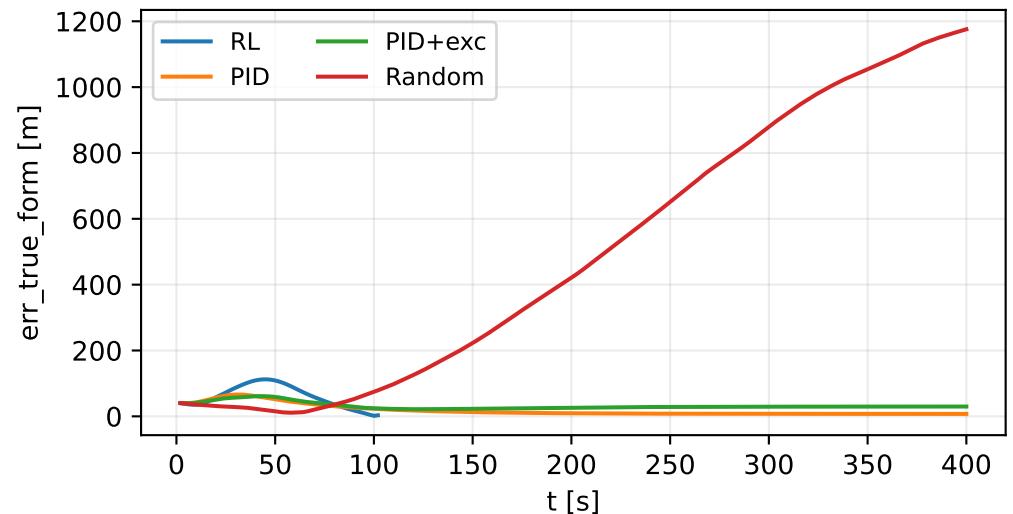
Follower angular rate



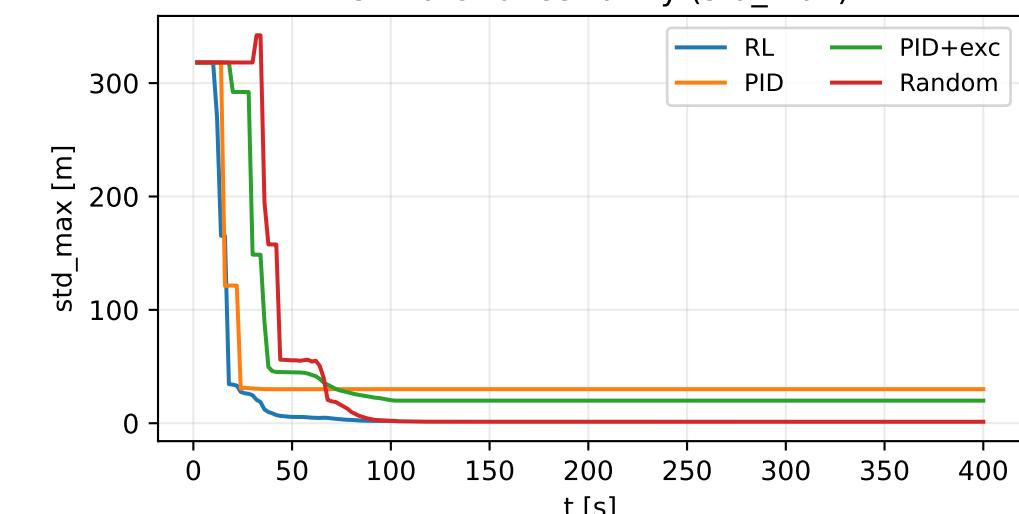
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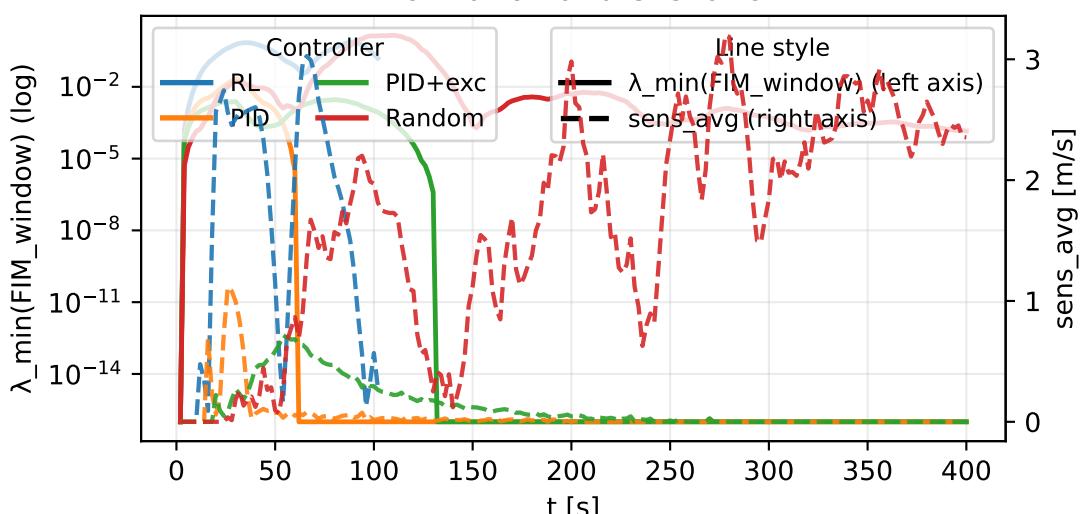
TRUE formation error



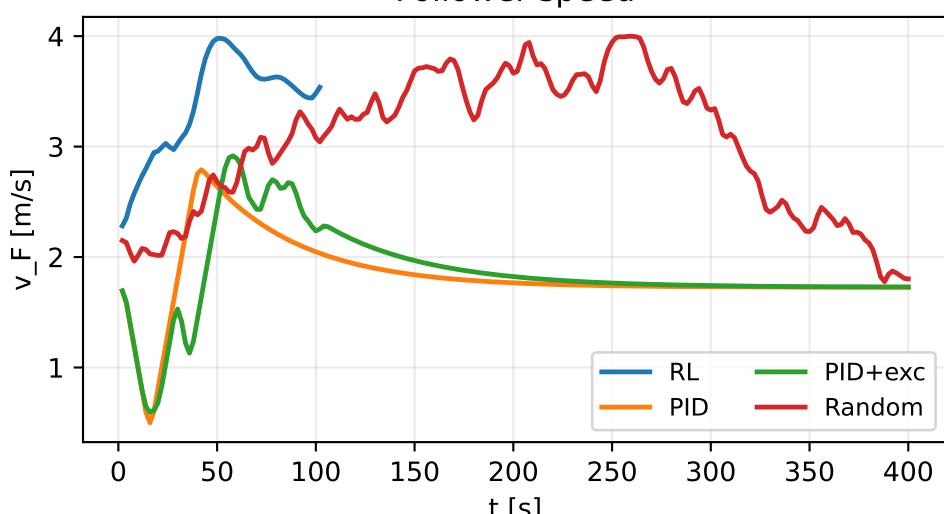
Estimator uncertainty (std_max)



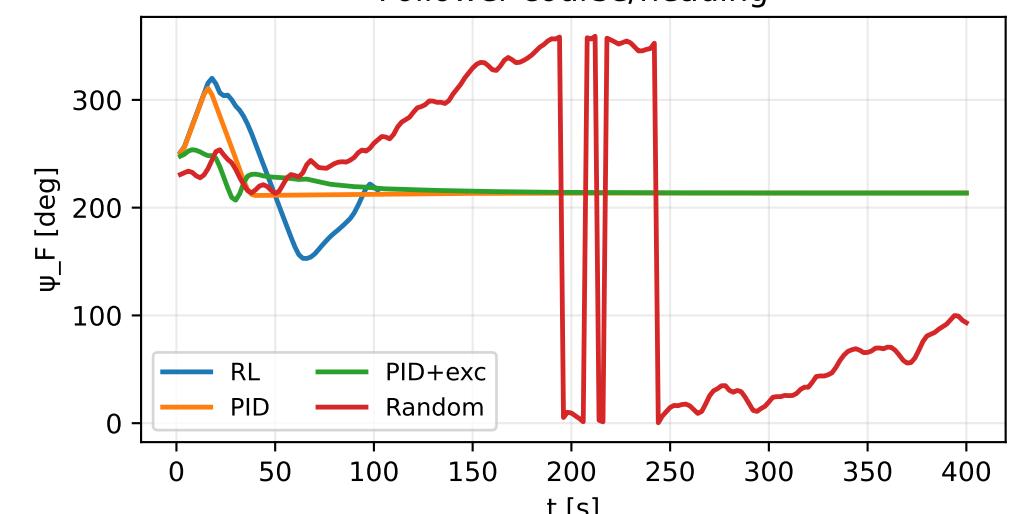
Information and excitation



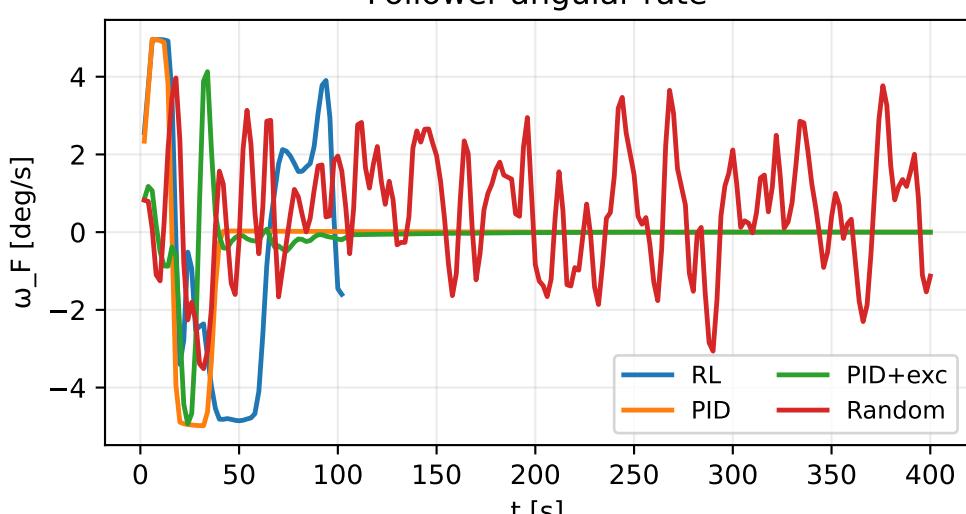
Follower speed



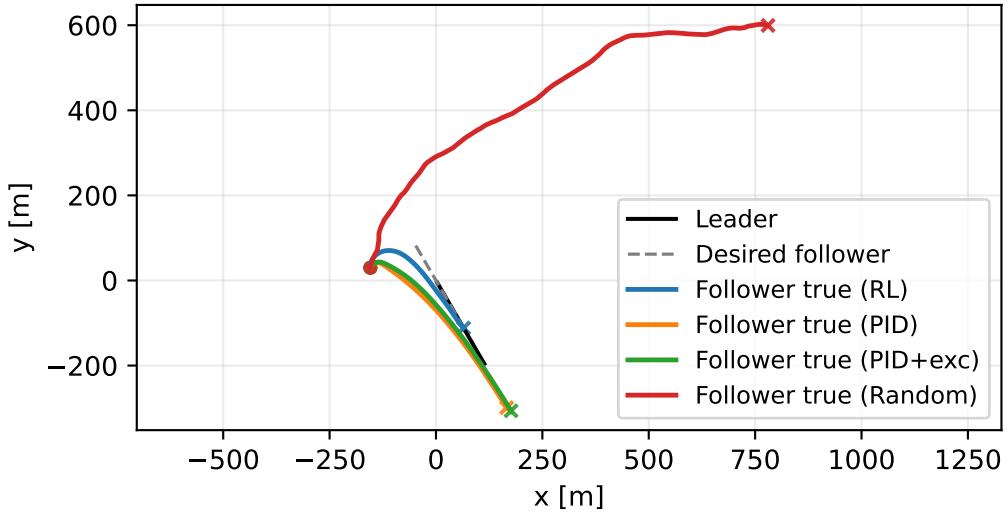
Follower course/heading



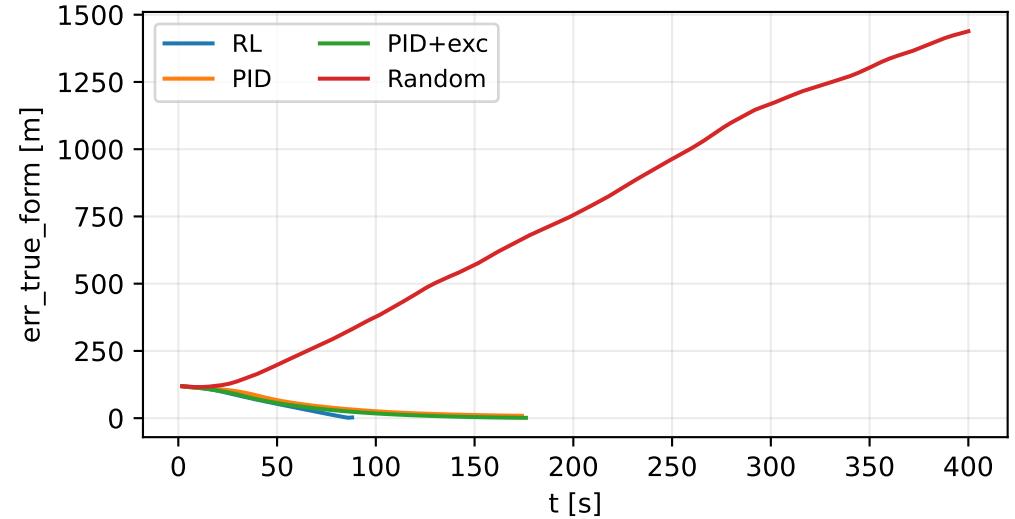
Follower angular rate



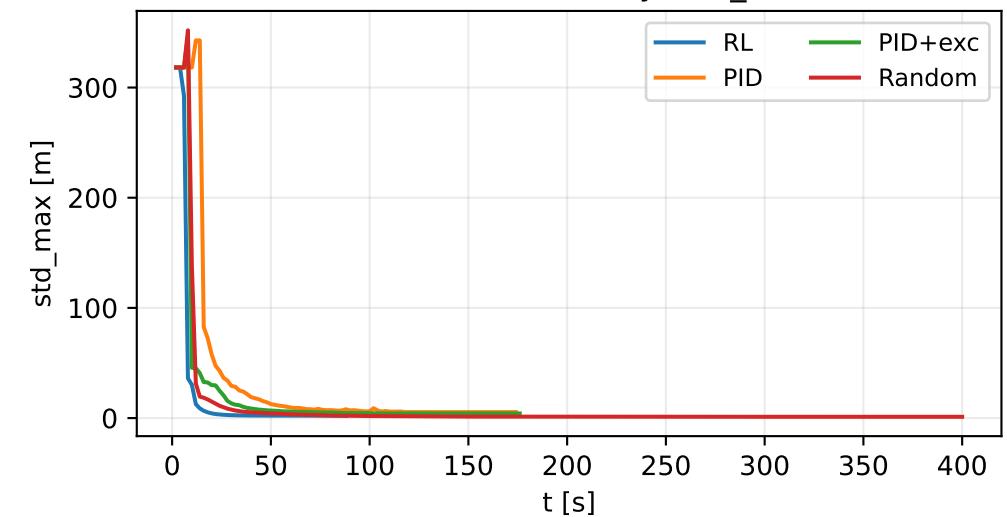
Trajectories (matched seed)



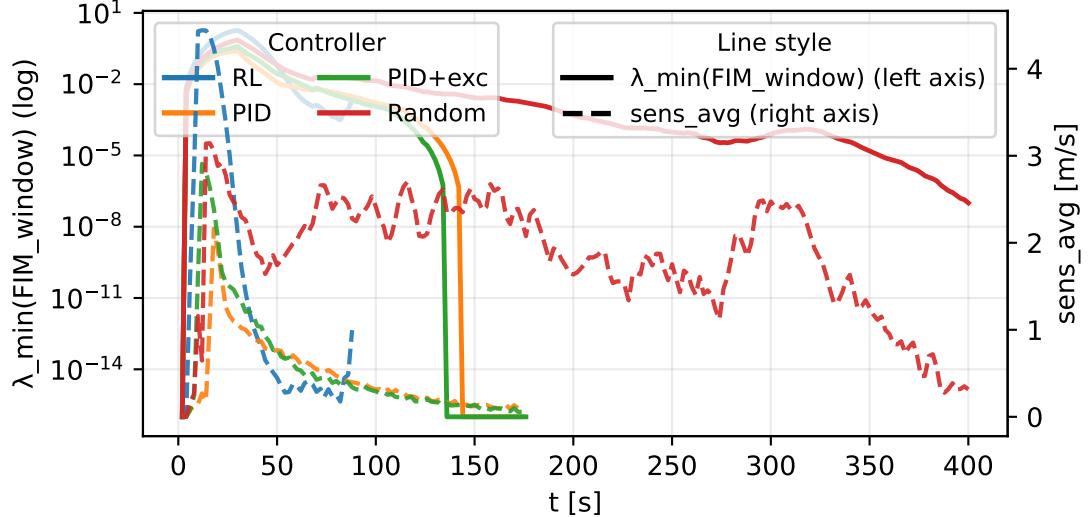
TRUE formation error



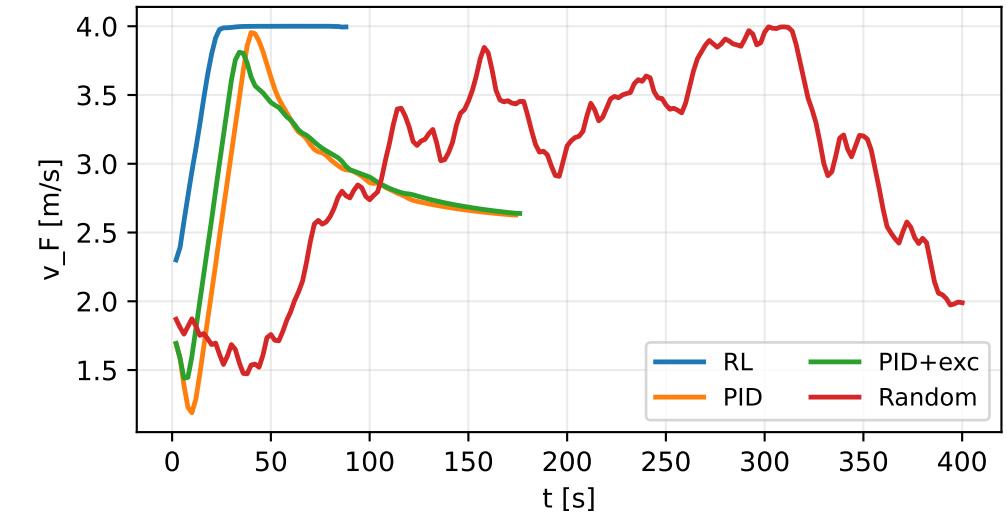
Estimator uncertainty (std_max)



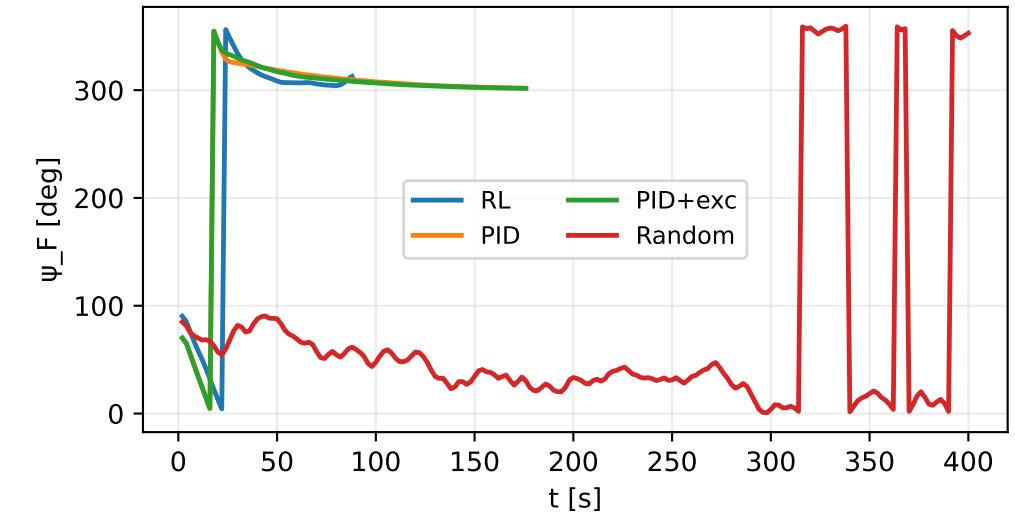
Information and excitation



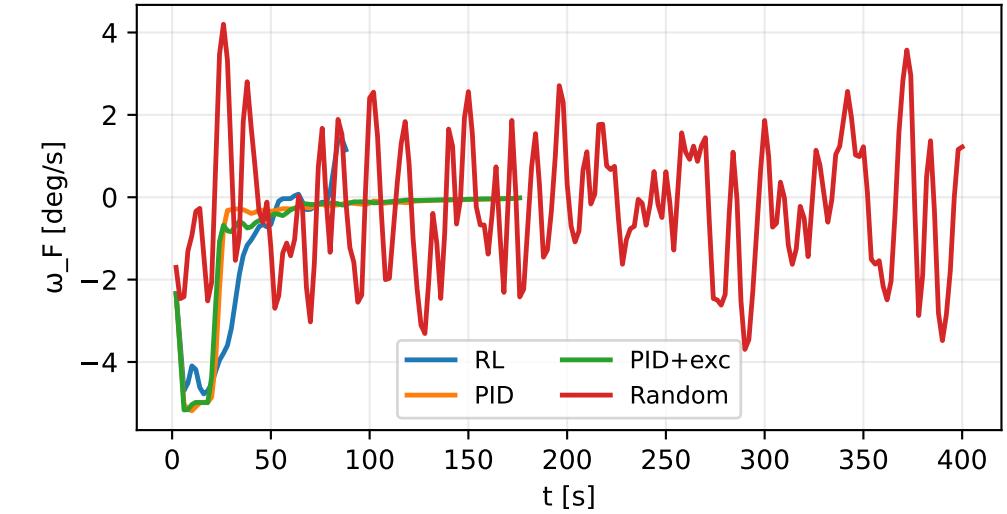
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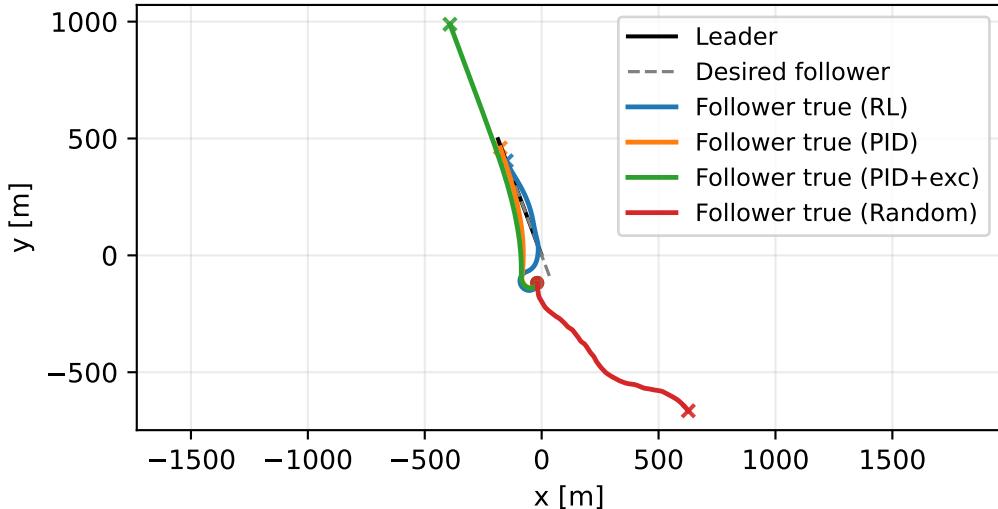
Follower course/heading



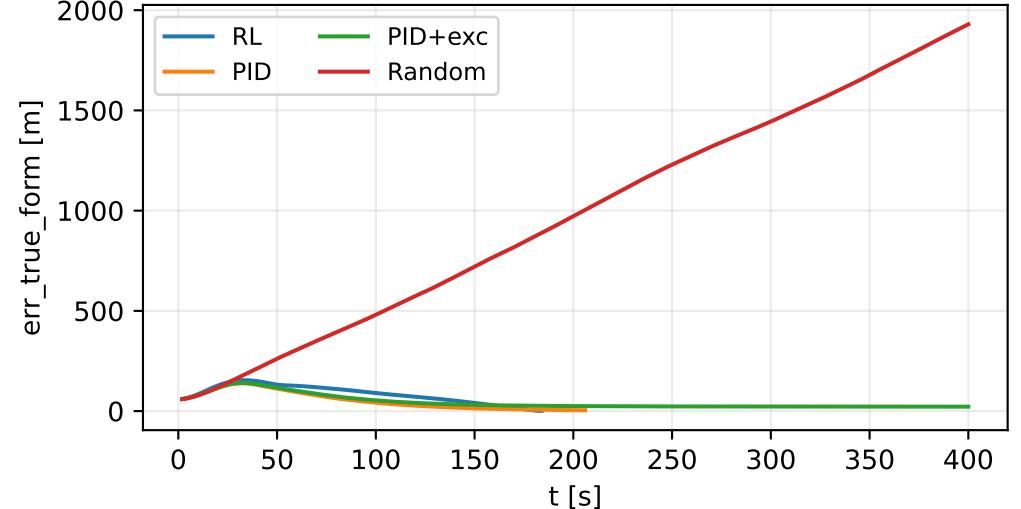
Follower angular rate



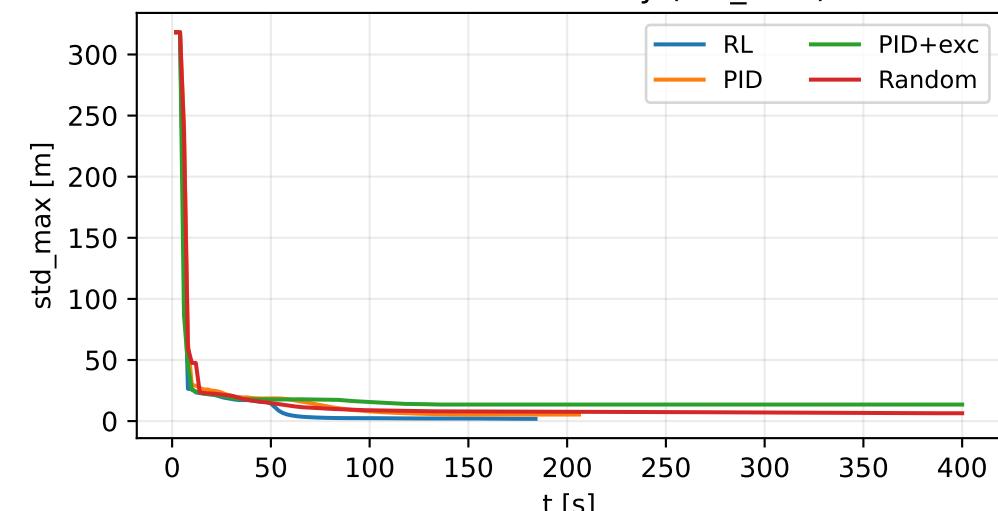
Trajectories (matched seed)



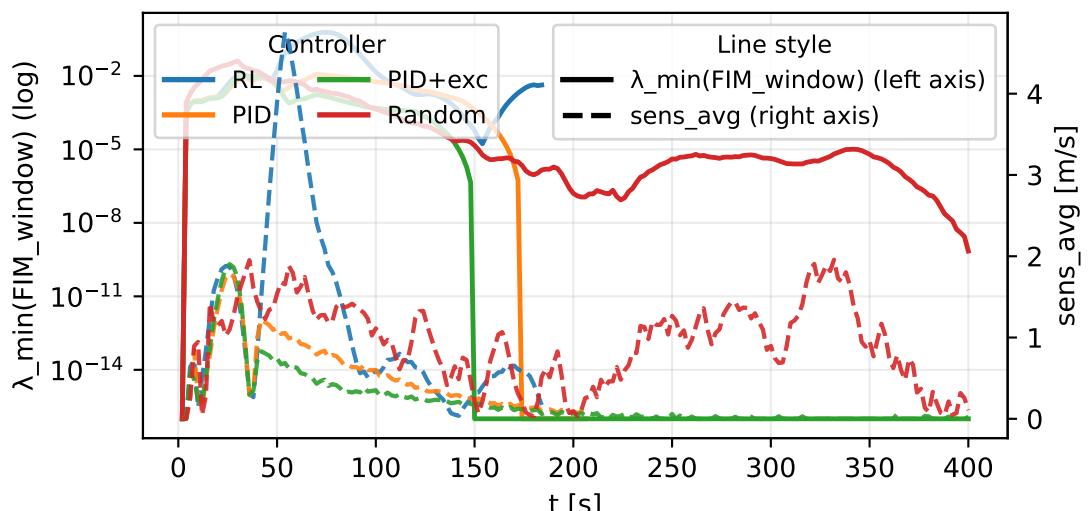
TRUE formation error



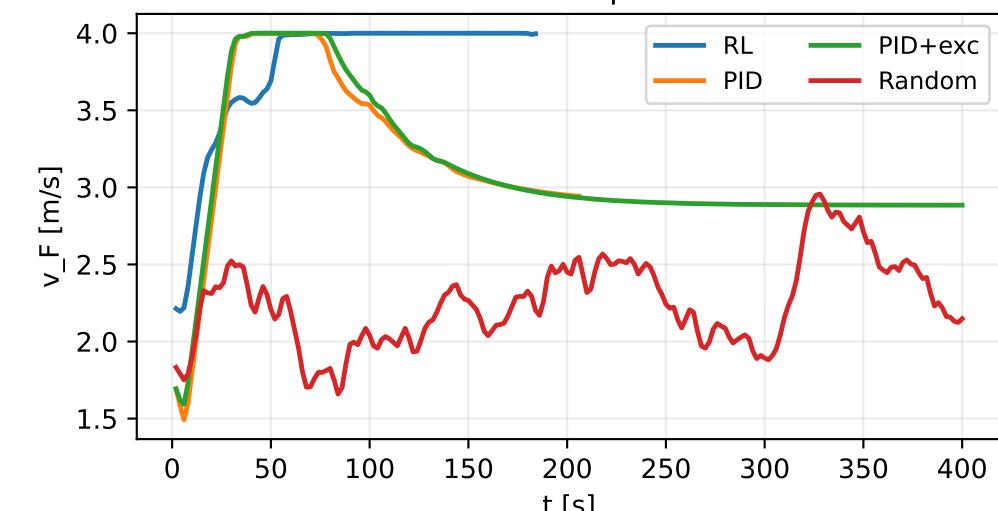
Estimator uncertainty (std_max)



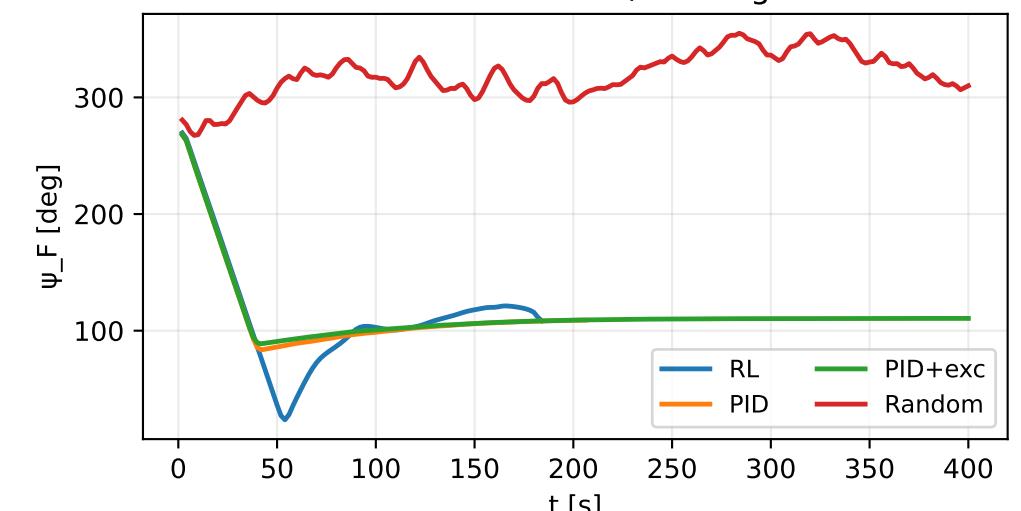
Information and excitation



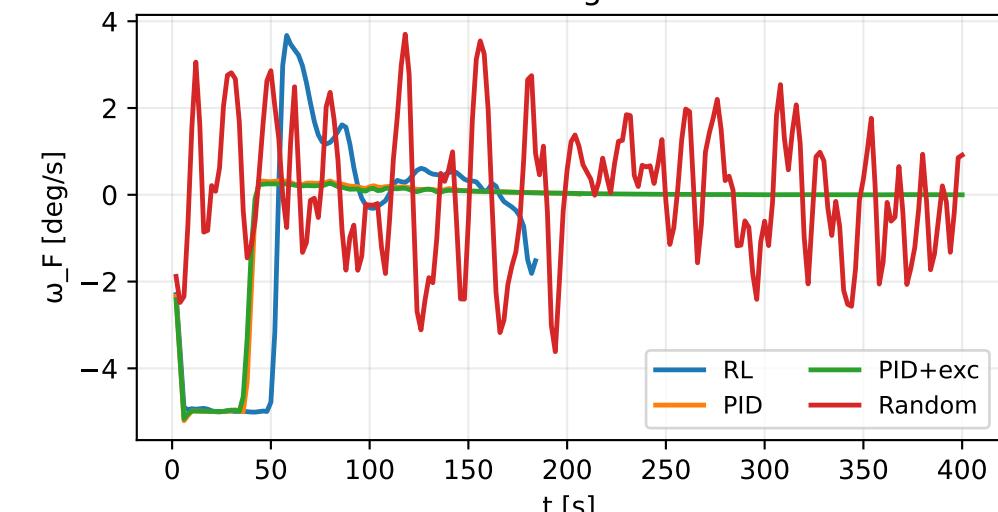
Follower speed



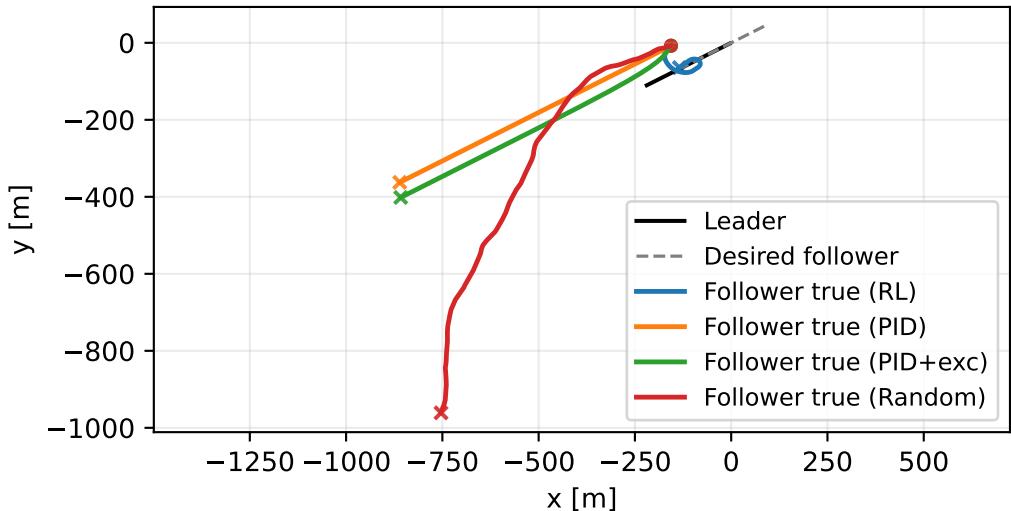
Follower course/heading



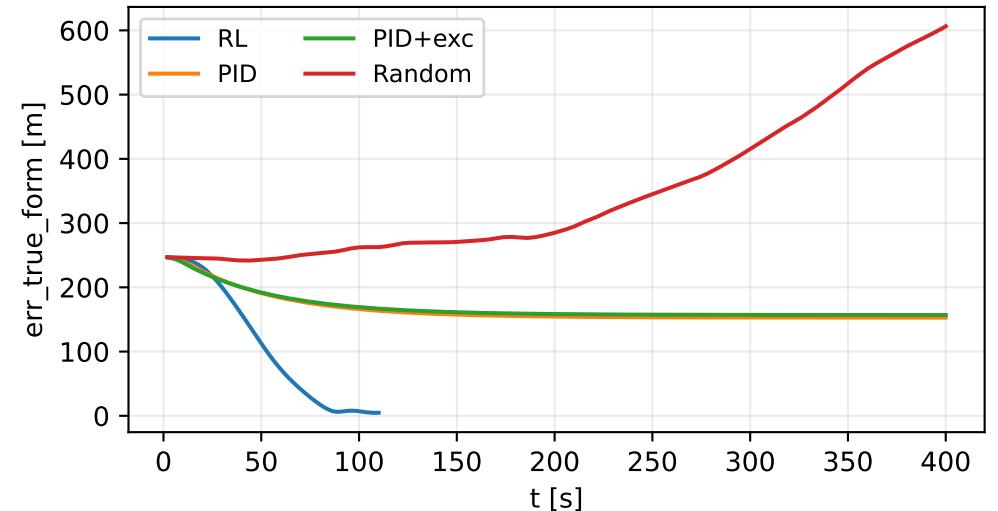
Follower angular rate



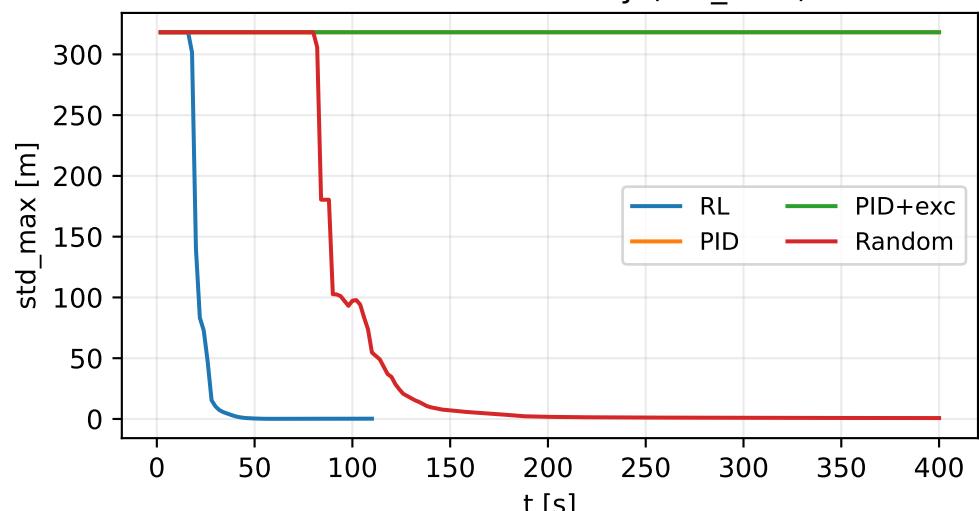
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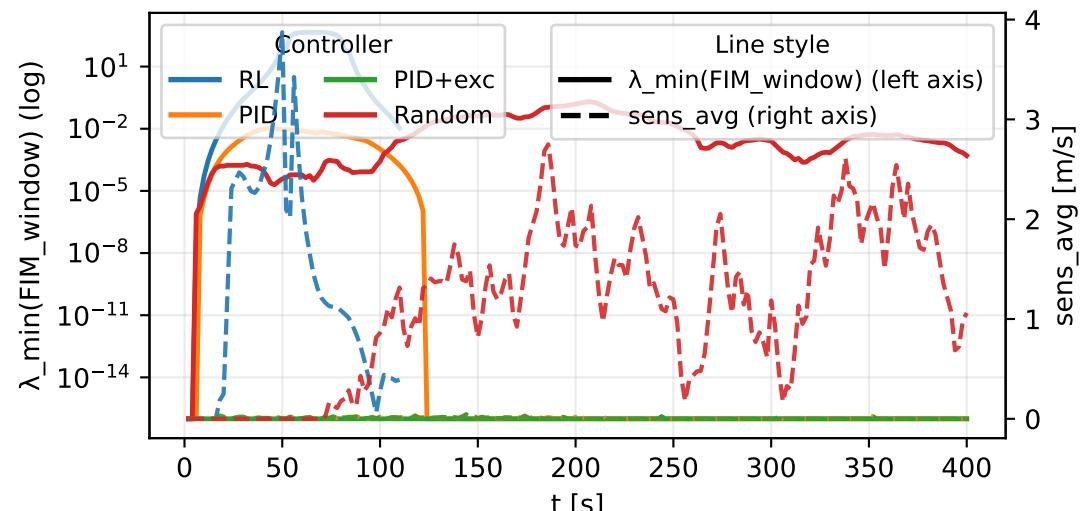
TRUE formation error



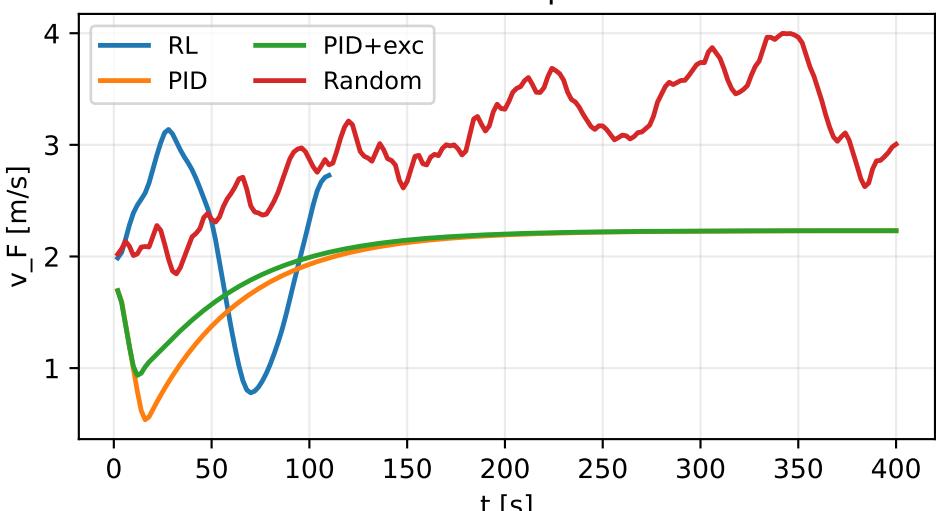
Estimator uncertainty (std_max)



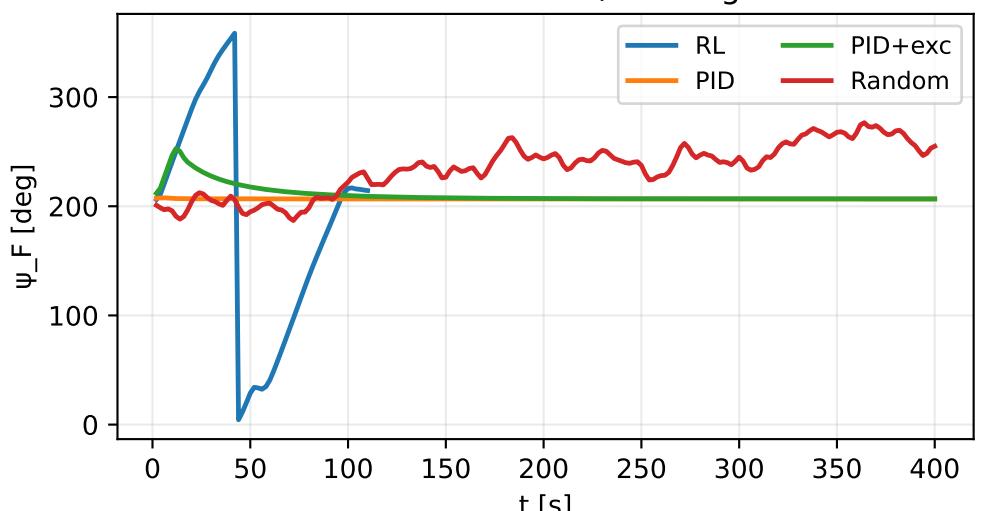
Information and excitation



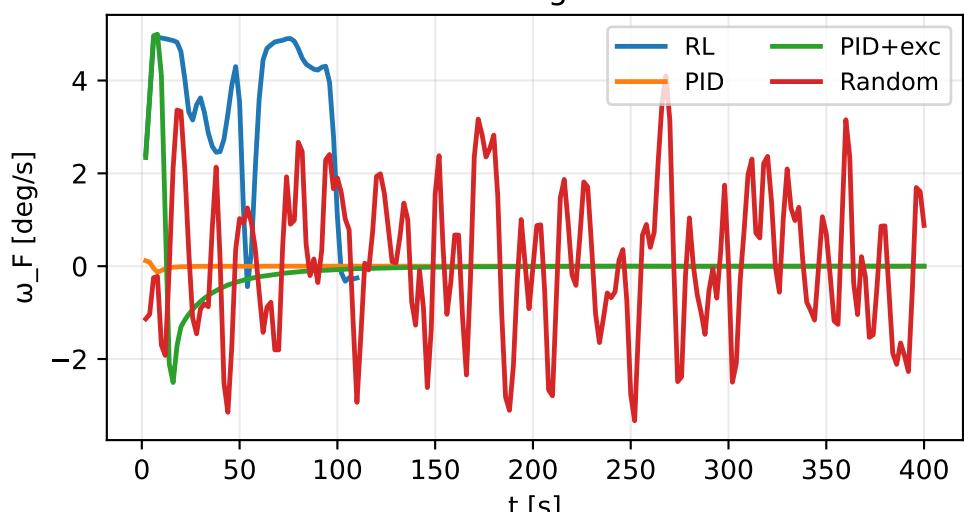
Follower speed



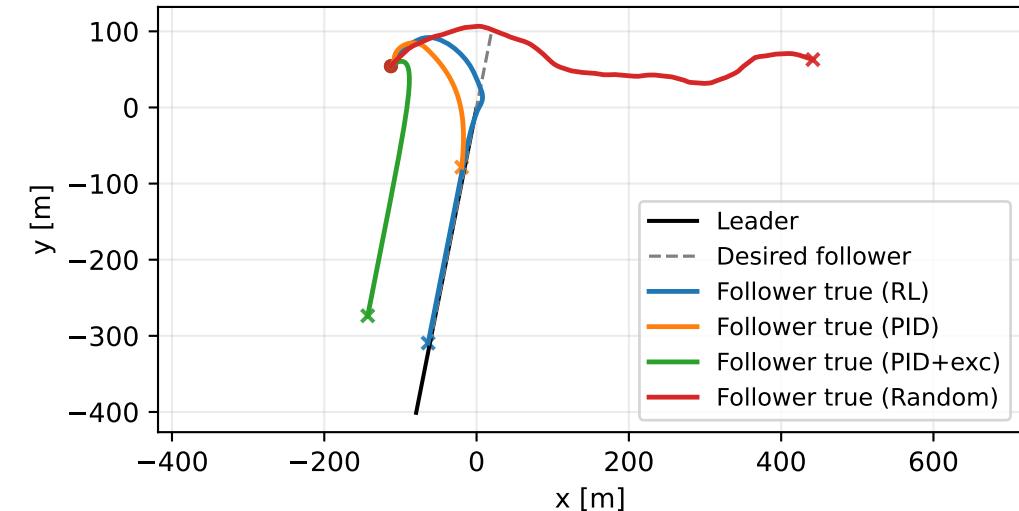
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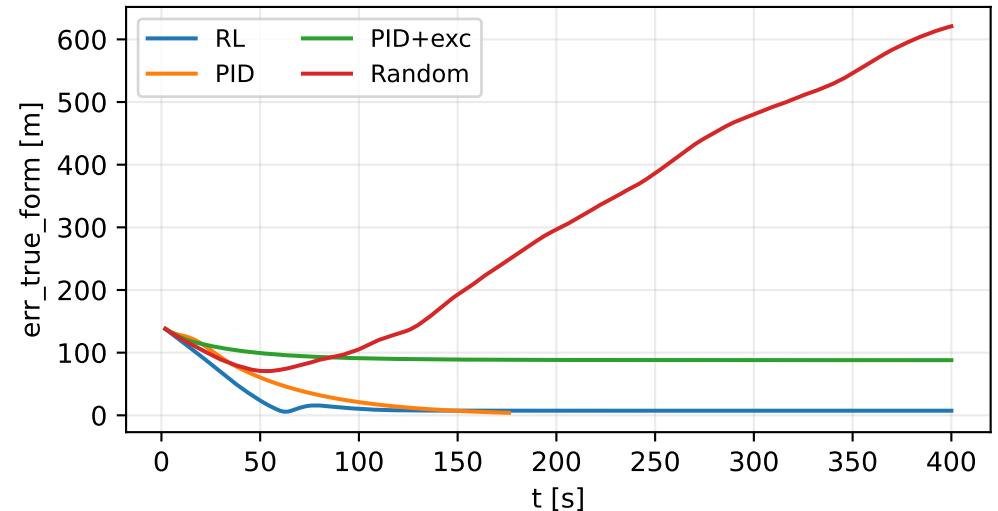
Follower angular rate



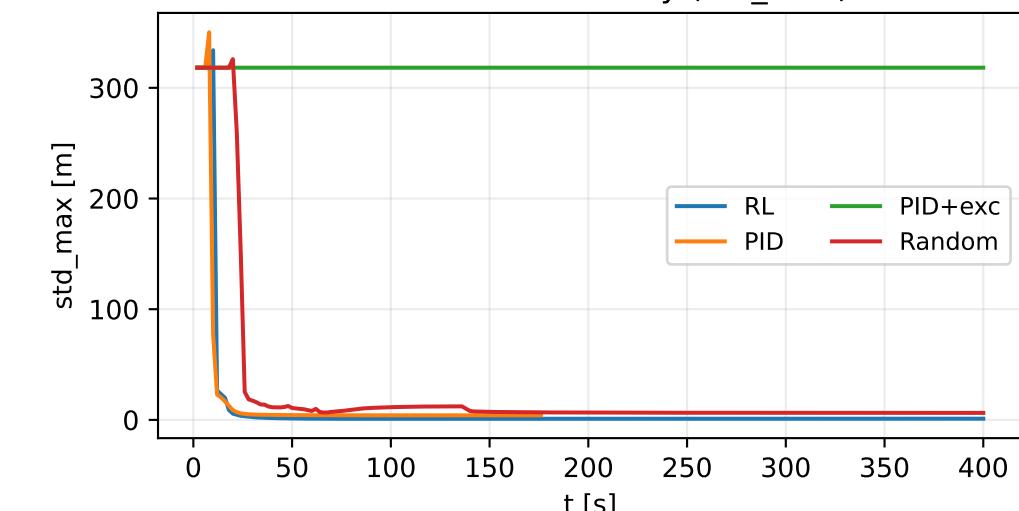
Trajectories (matched seed)



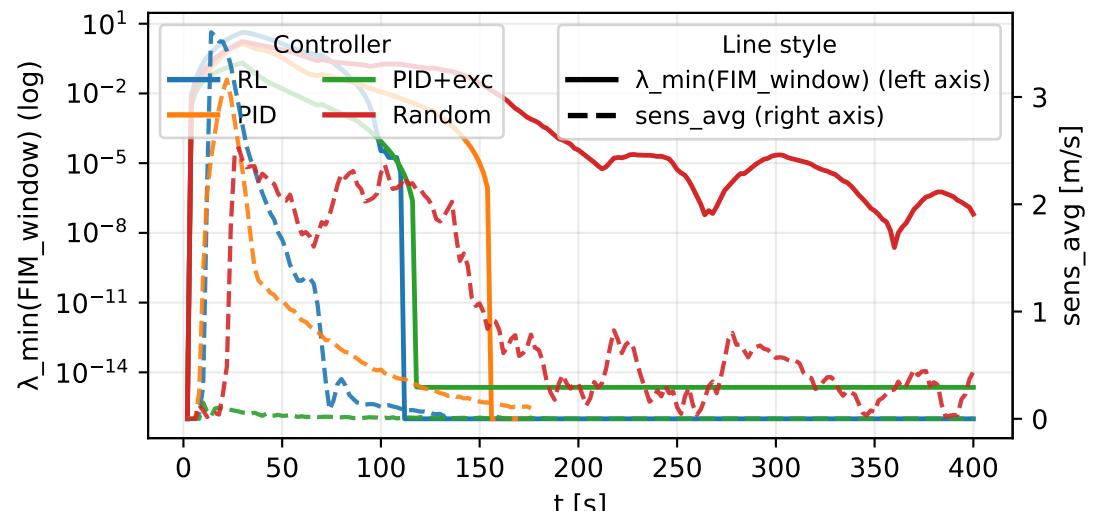
TRUE formation error



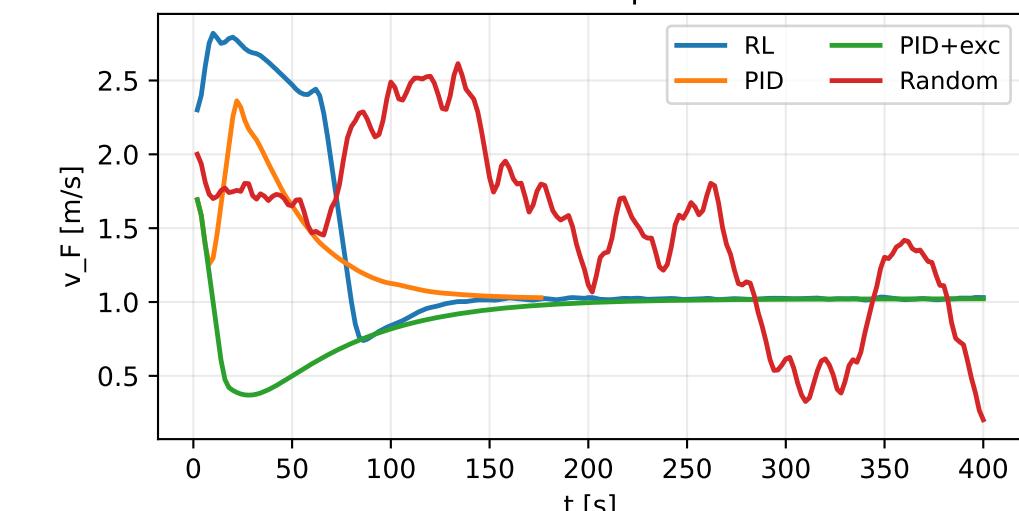
Estimator uncertainty (std_max)



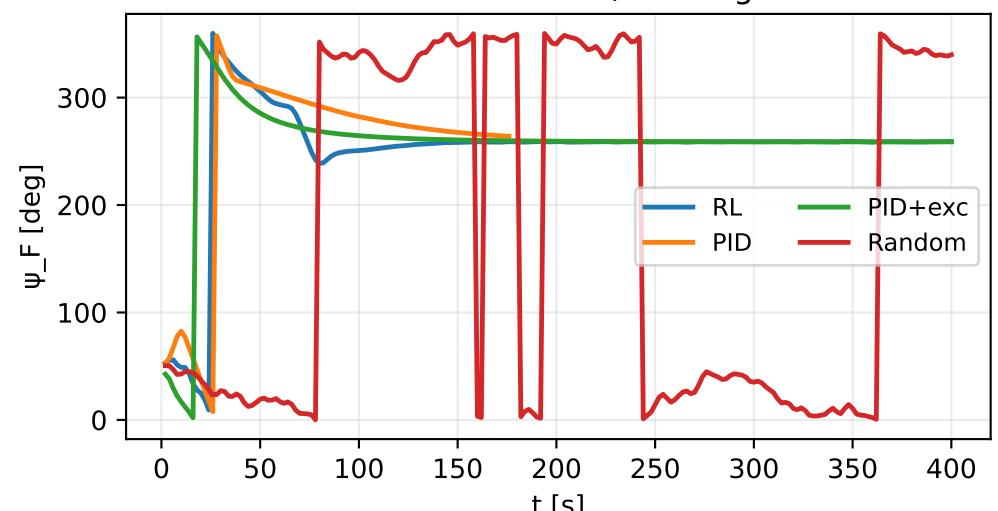
Information and excitation



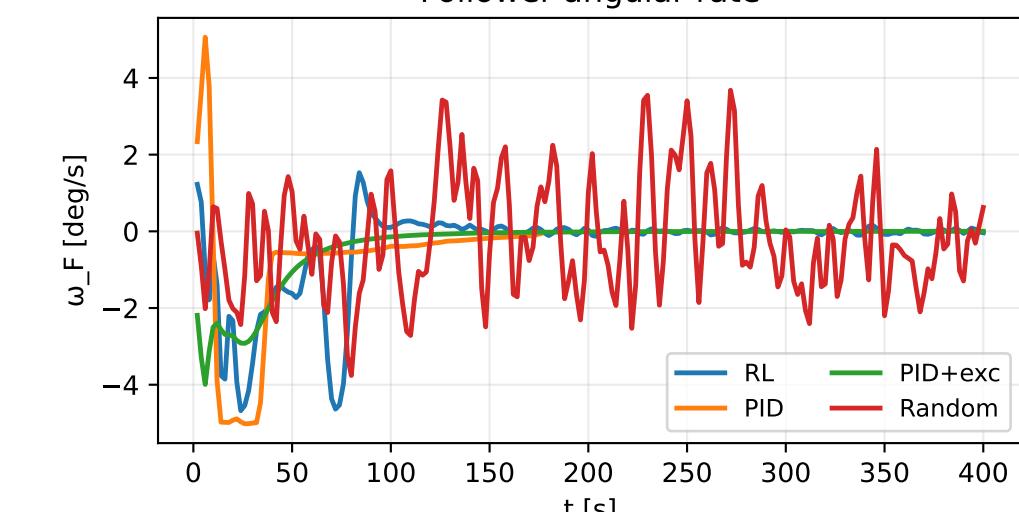
Follower speed



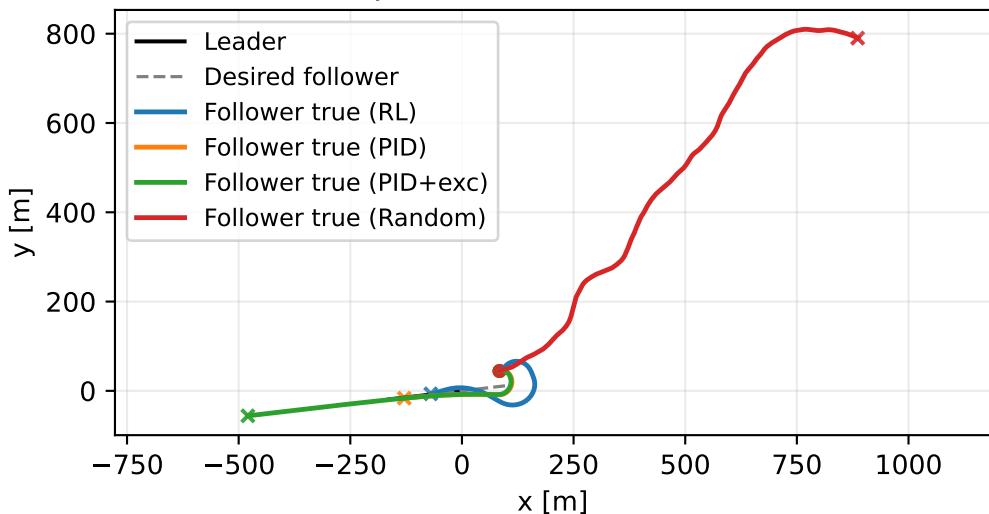
Follower course/heading



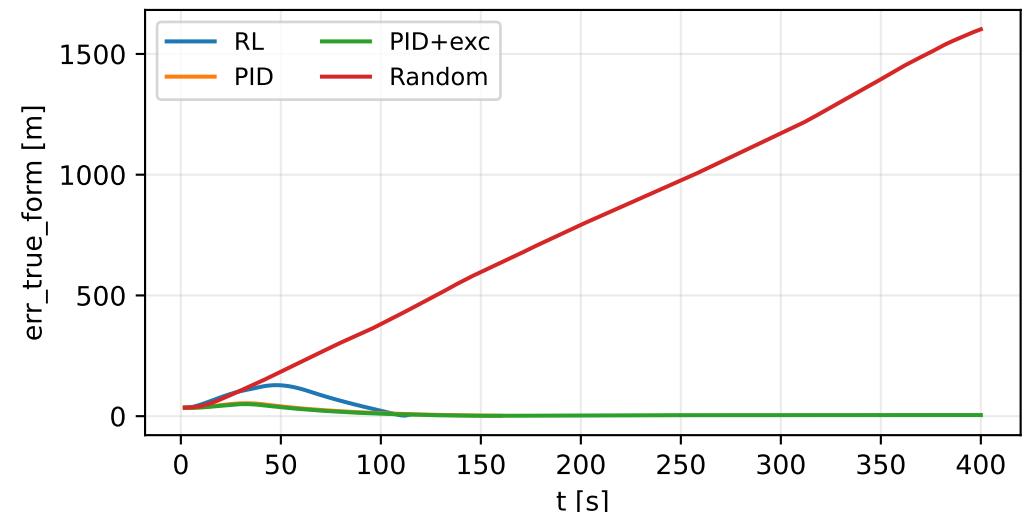
Follower angular rate



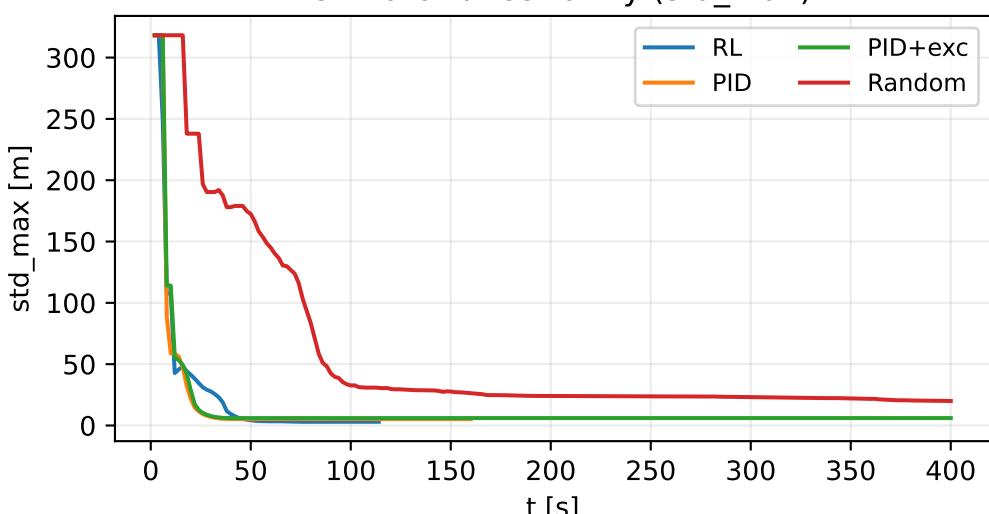
Trajectories (matched seed)



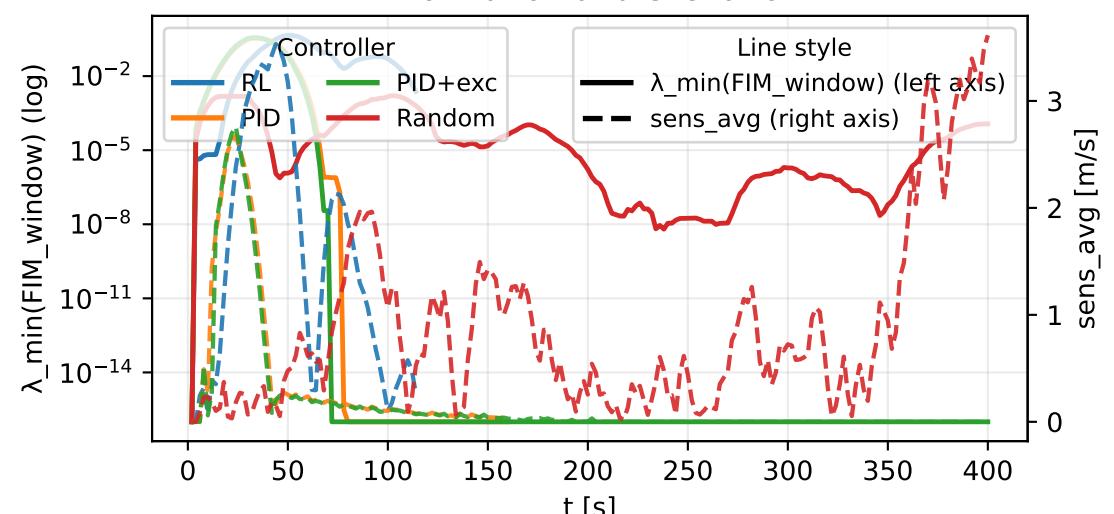
TRUE formation error



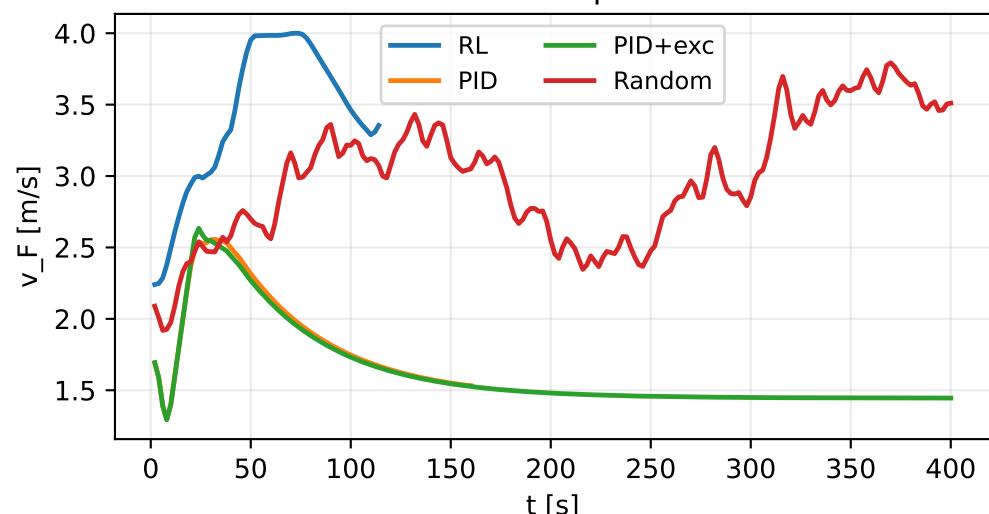
Estimator uncertainty (std_max)



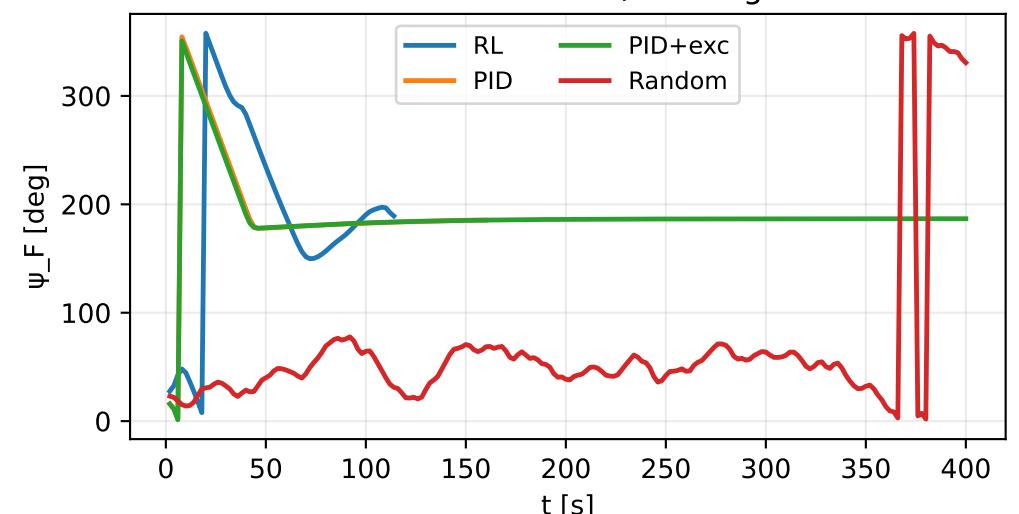
Information and excitation



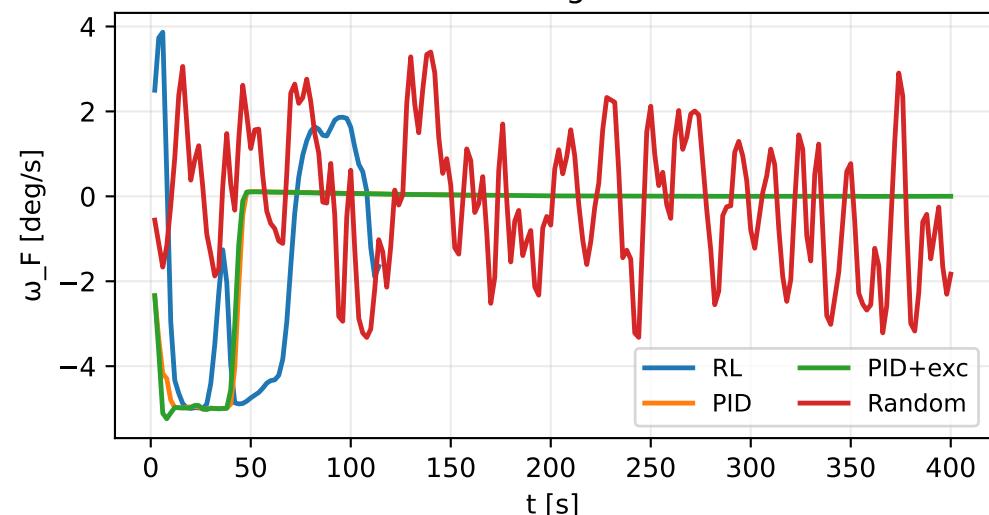
Follower speed



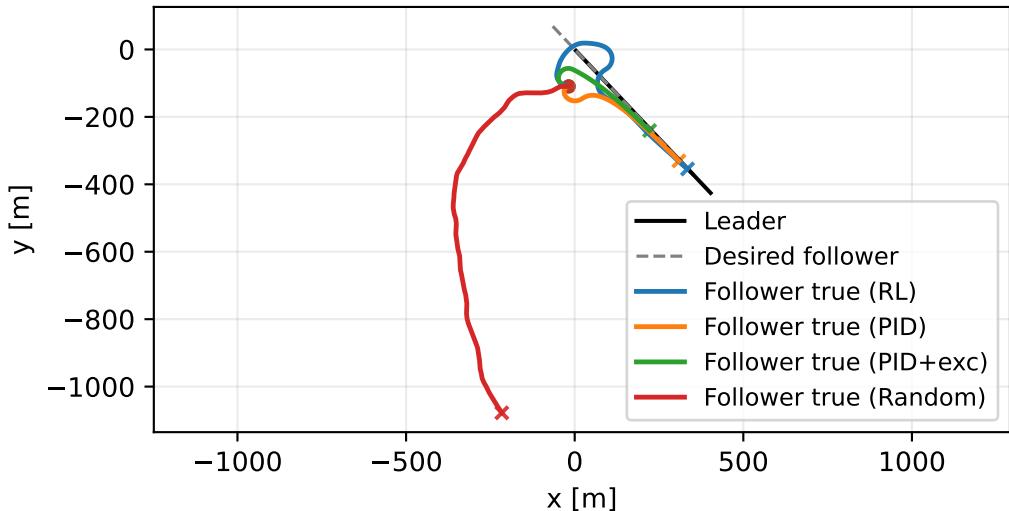
Follower course/heading



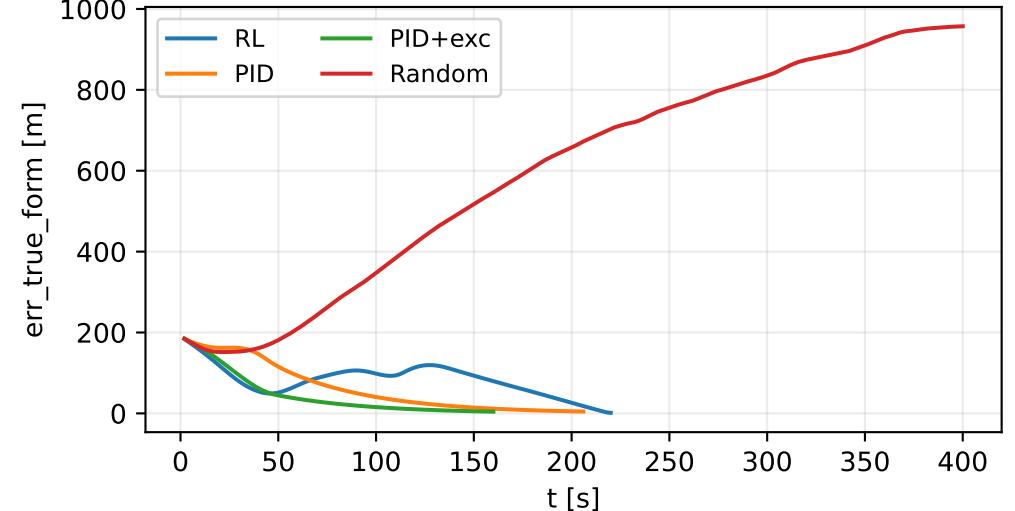
Follower angular rate



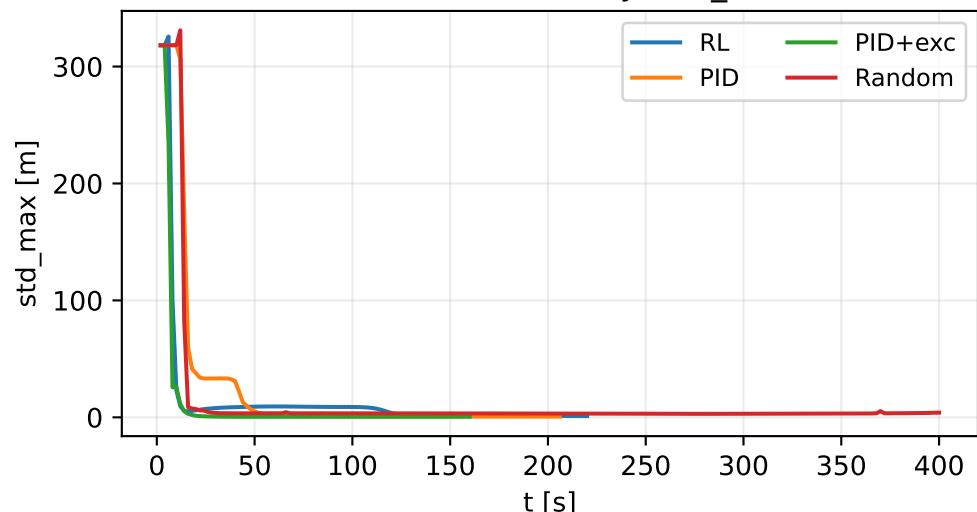
Trajectories (matched seed)



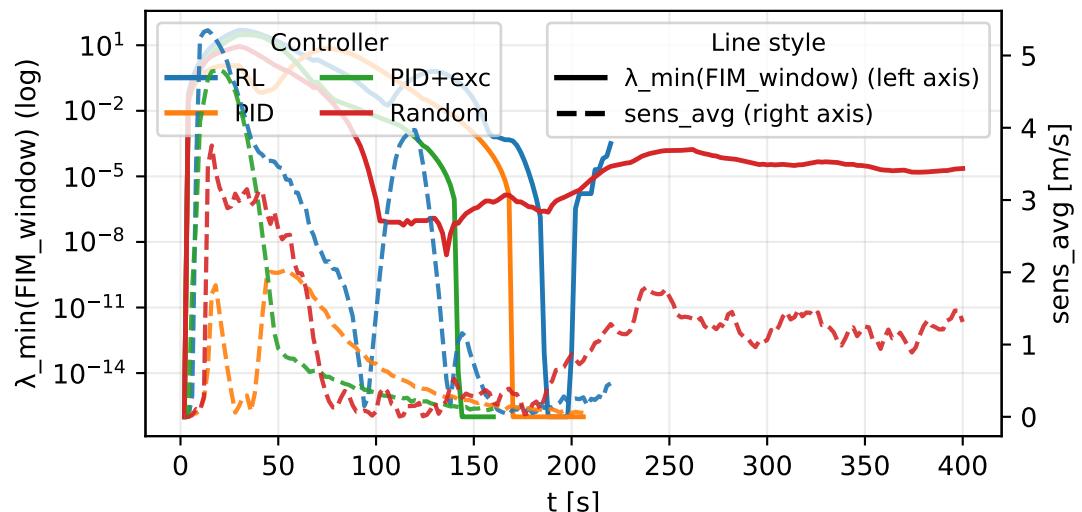
TRUE formation error



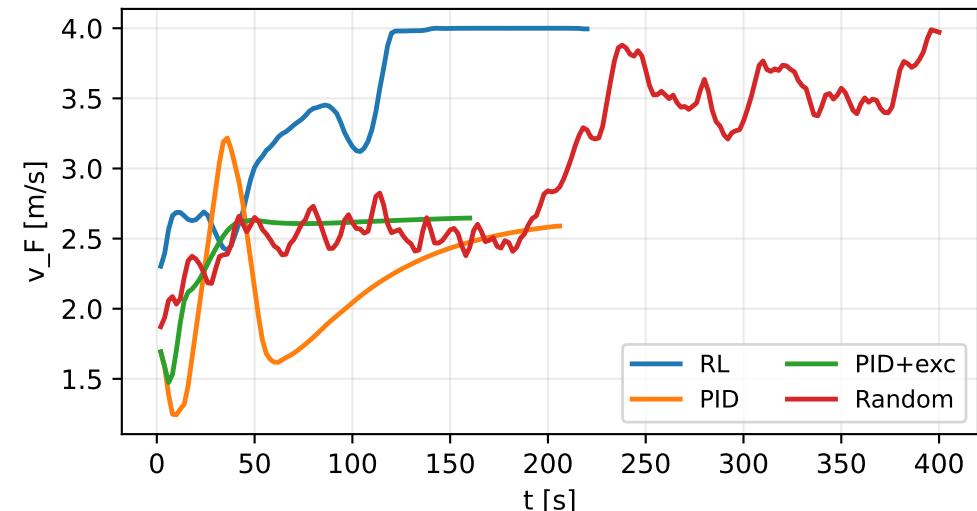
Estimator uncertainty (std_max)



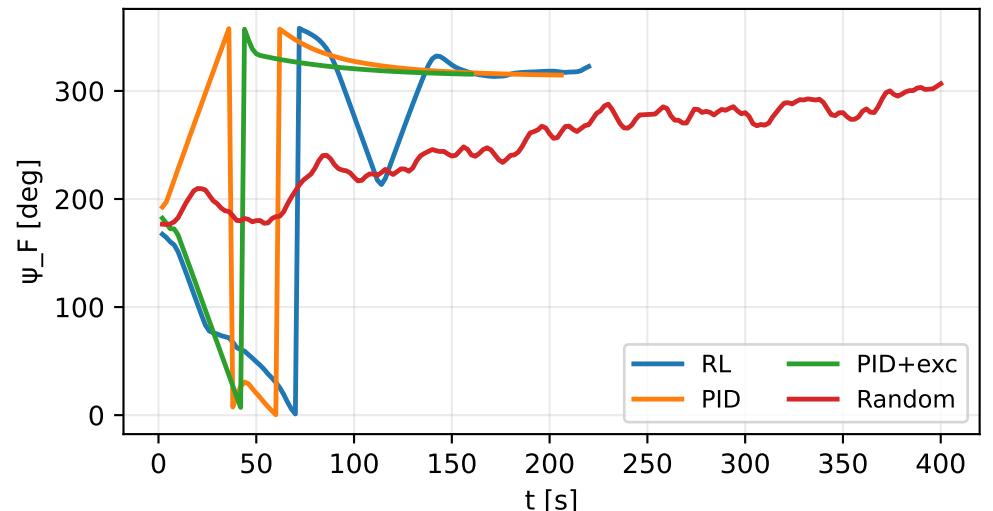
Information and excitation



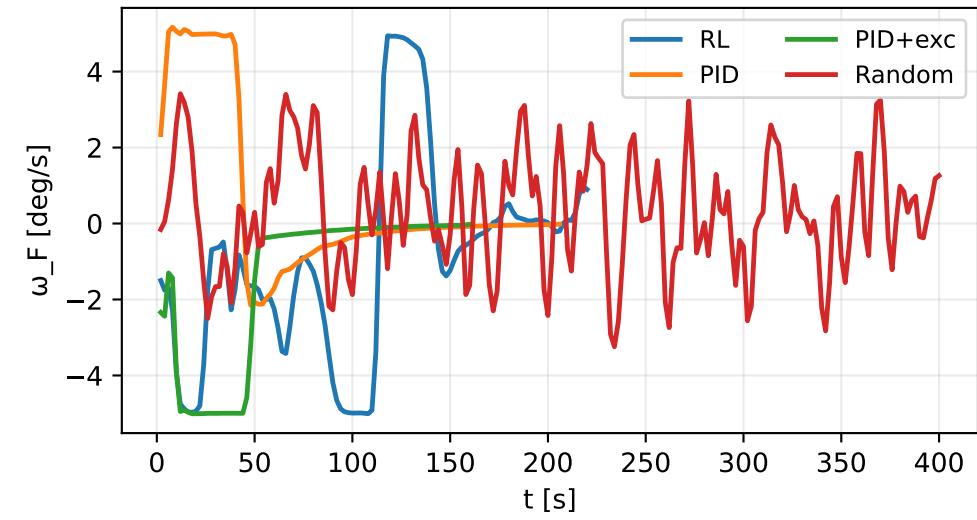
Follower speed



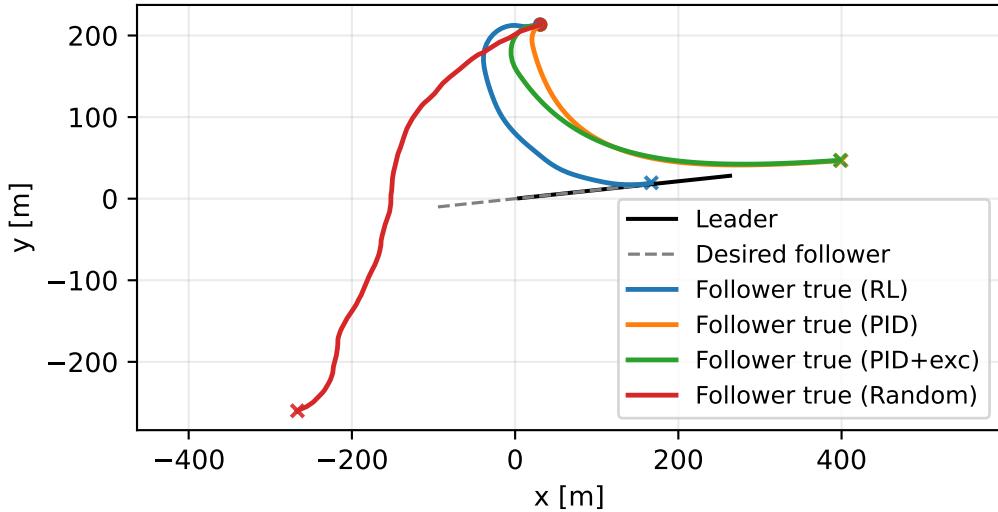
Follower course/heading



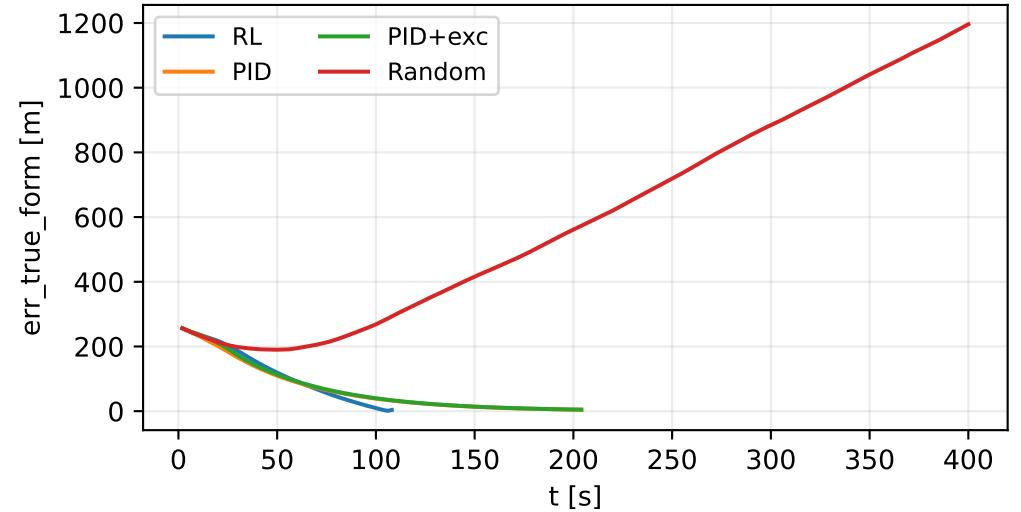
Follower angular rate



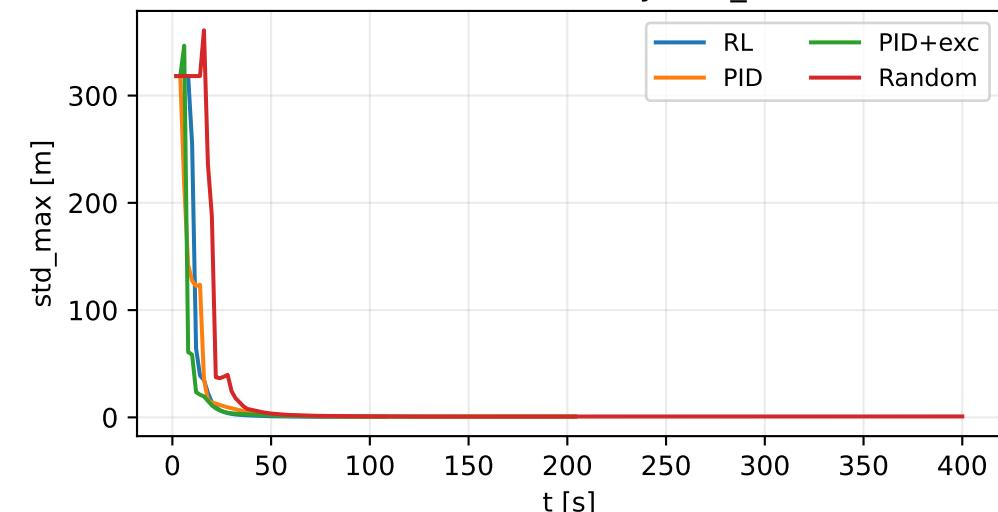
Trajectories (matched seed)



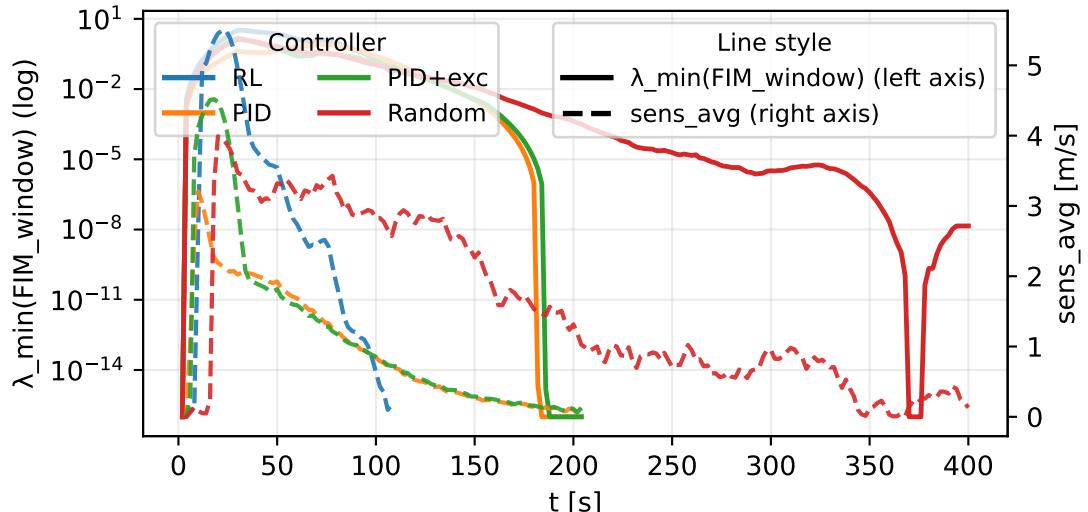
TRUE formation error



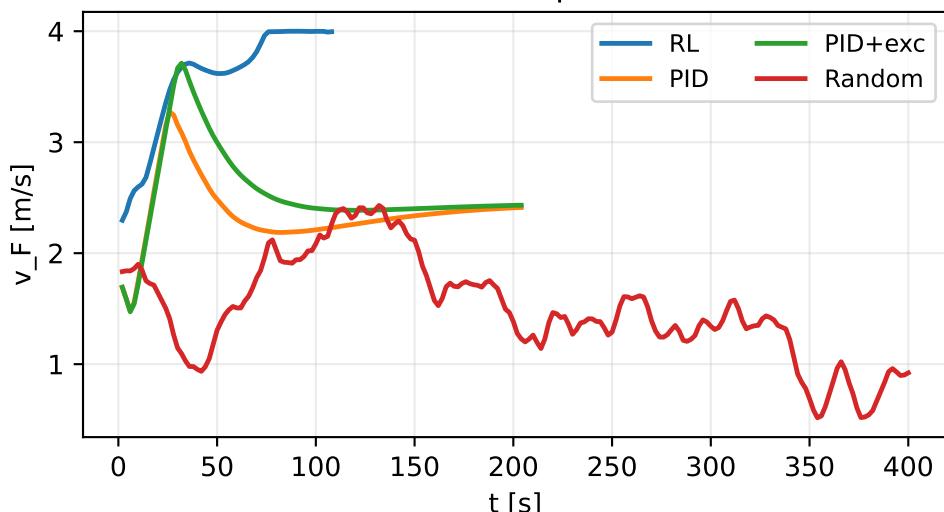
Estimator uncertainty (std_max)



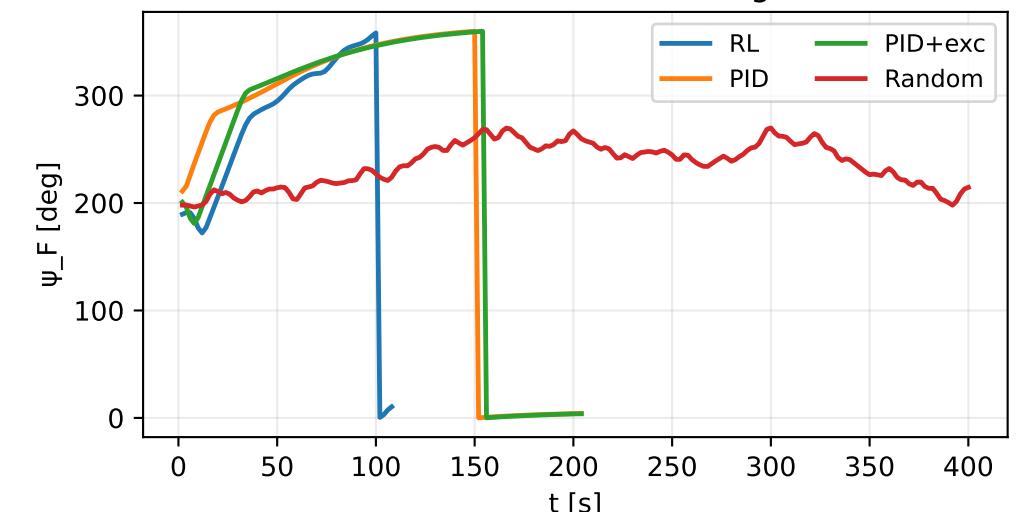
Information and excitation



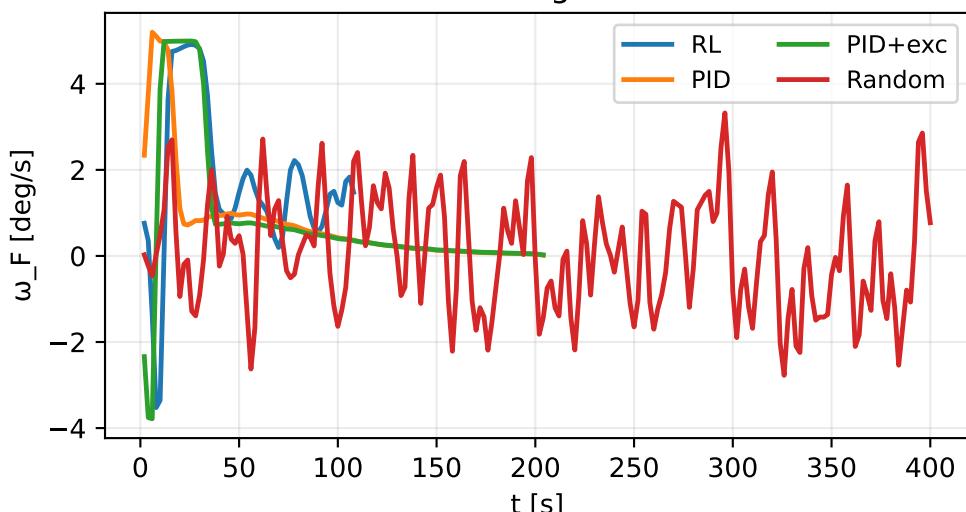
Follower speed



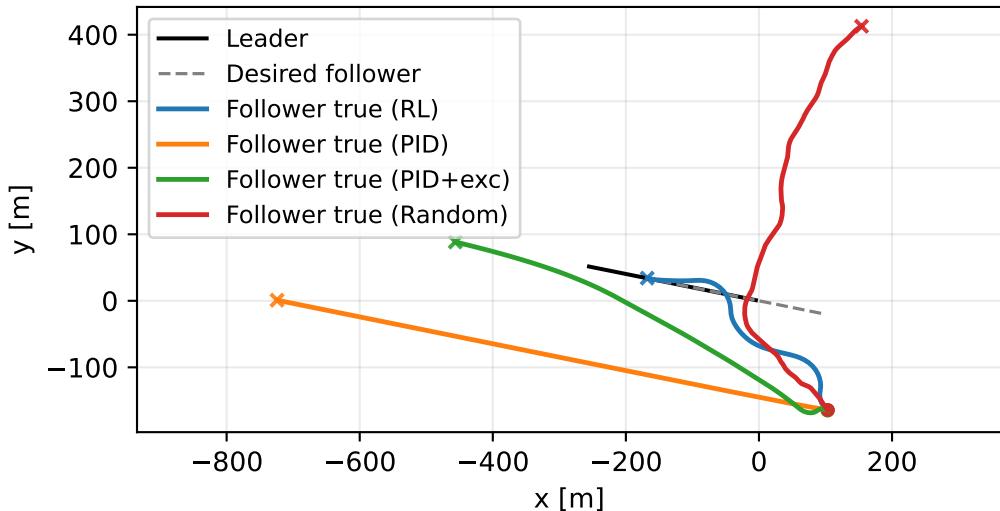
Follower course/heading



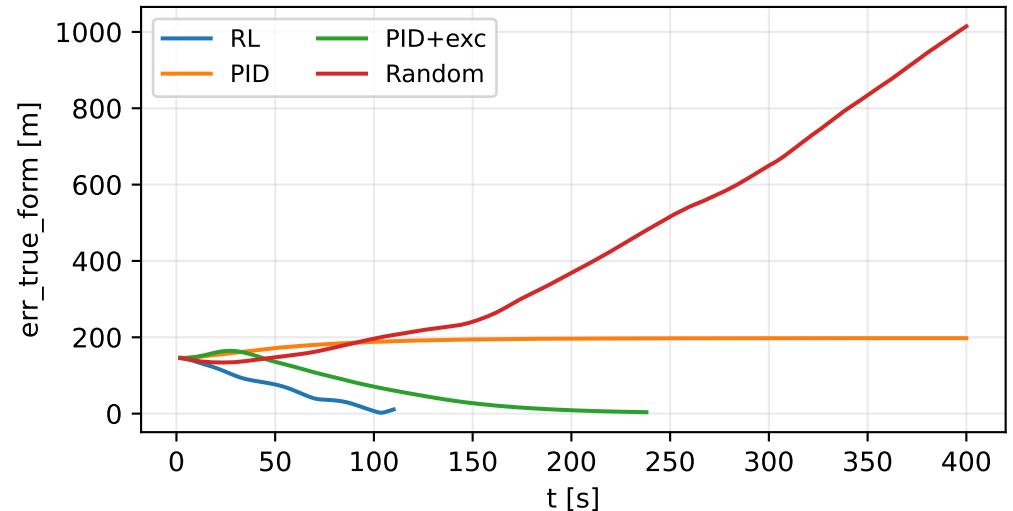
Follower angular rate



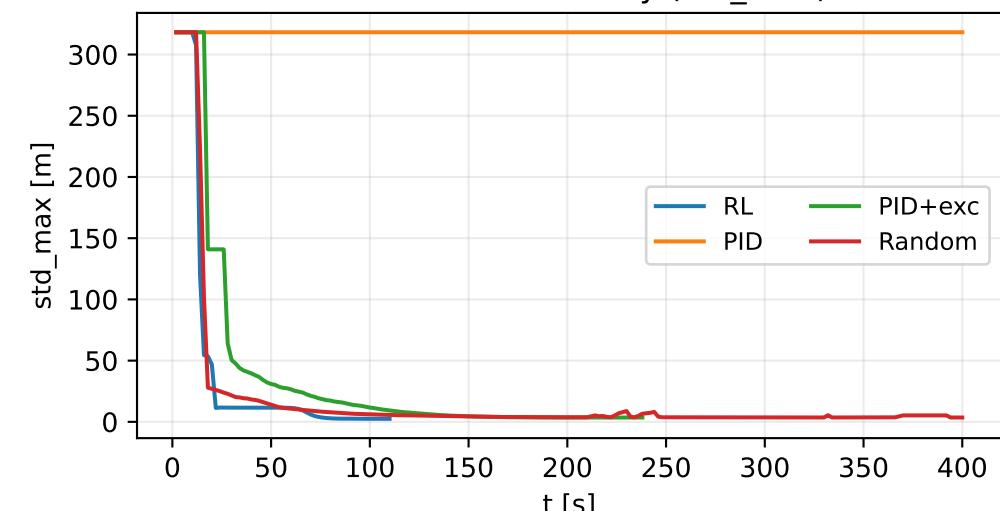
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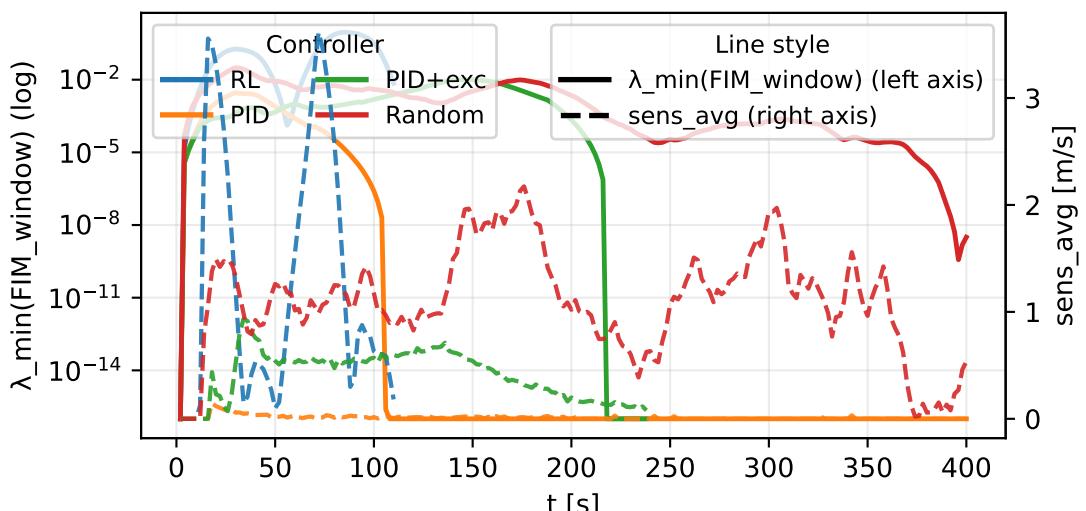
TRUE formation error



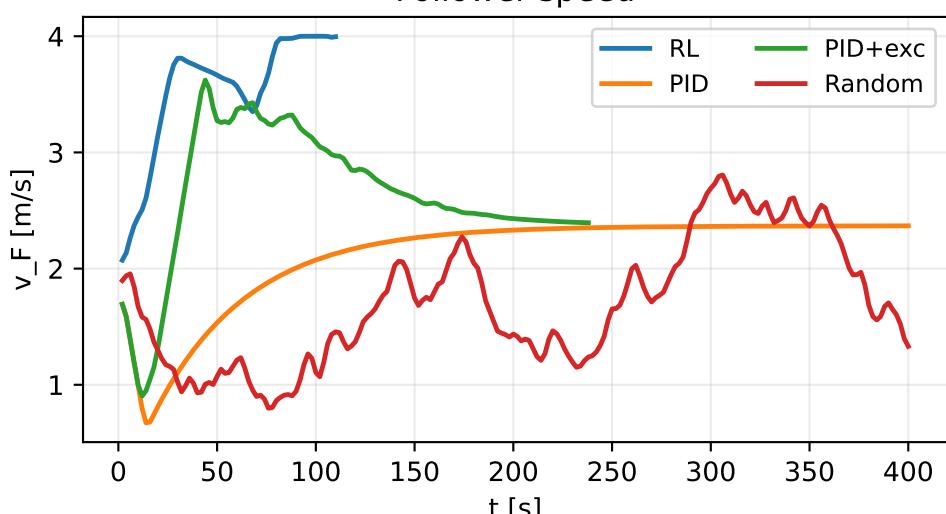
Estimator uncertainty (std_max)



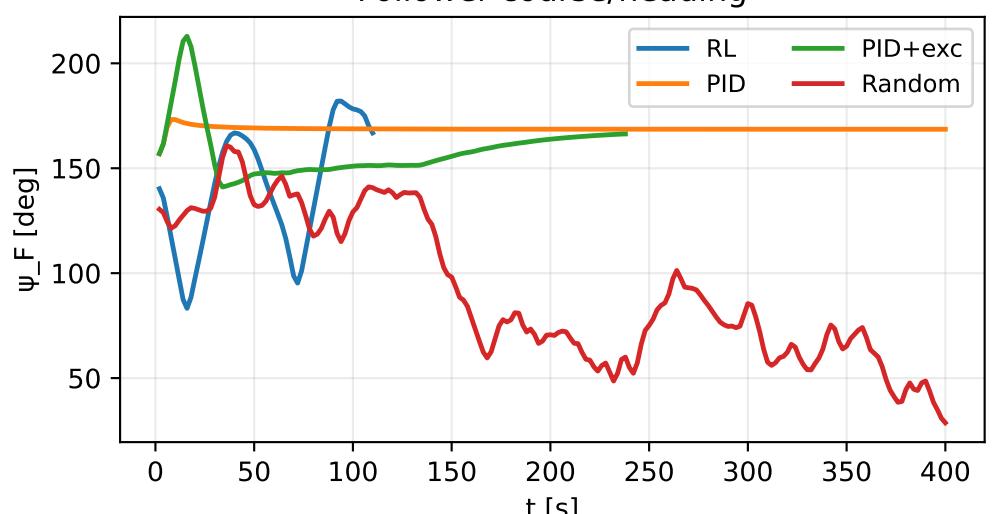
Information and excitation



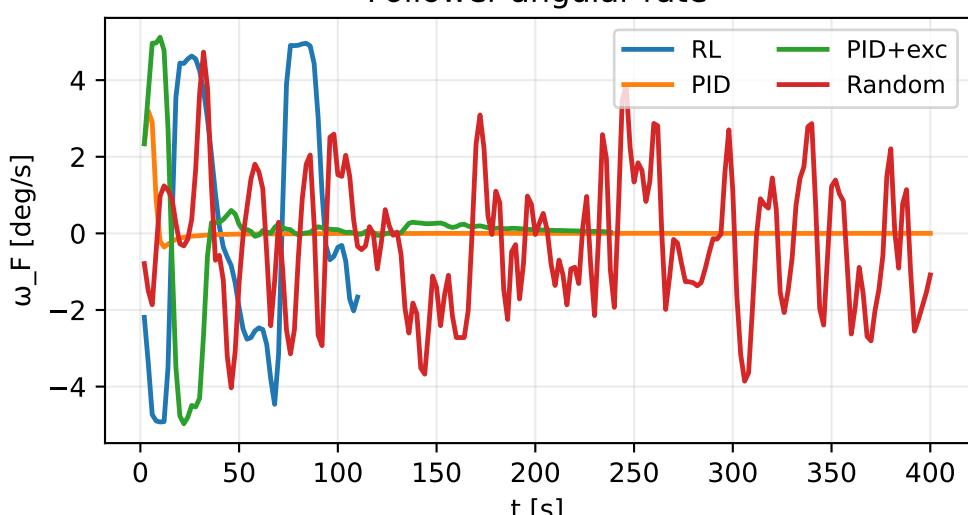
Follower speed



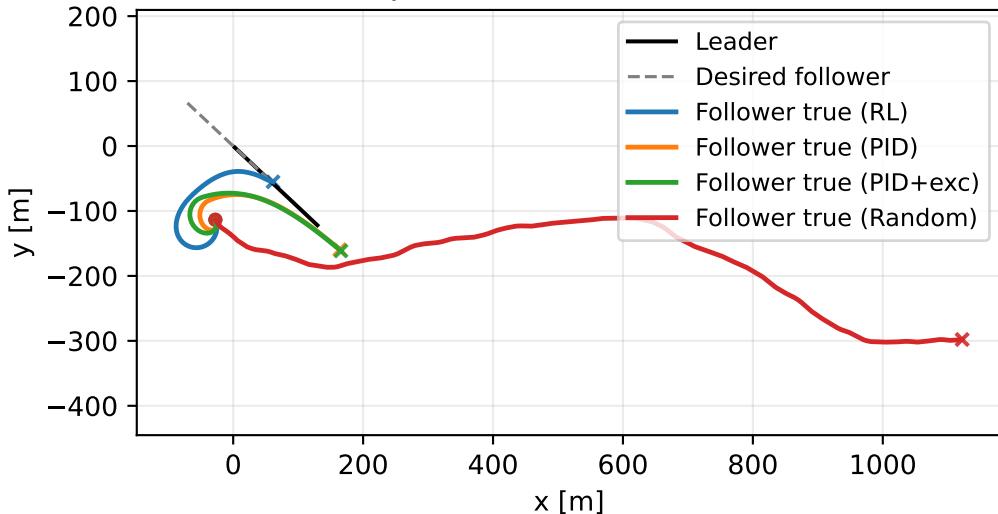
Follower course/heading



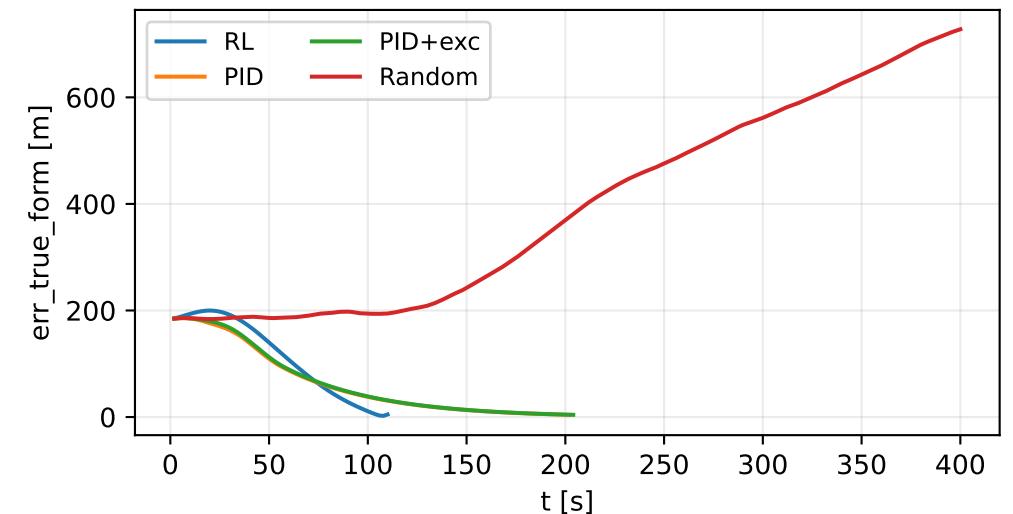
Follower angular rate



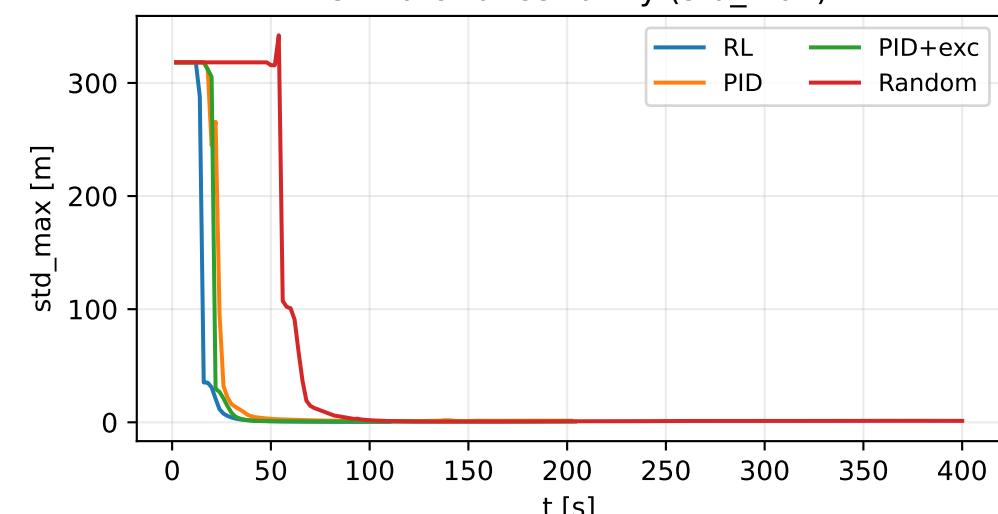
Trajectories (matched seed)



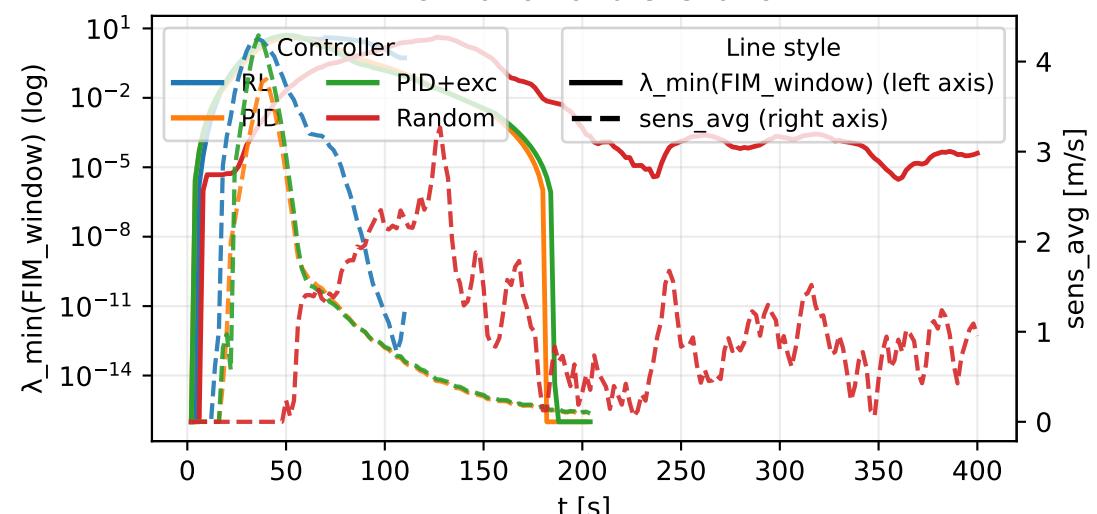
TRUE formation error



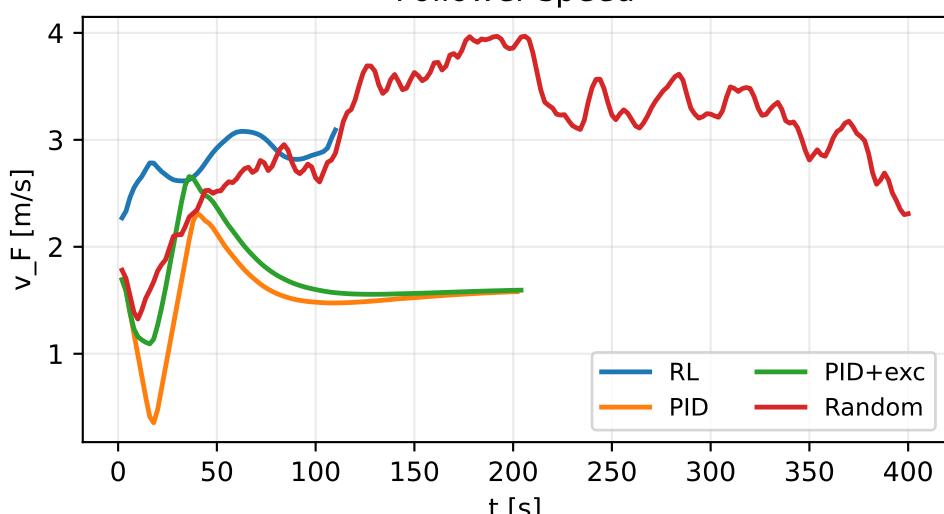
Estimator uncertainty (std_max)



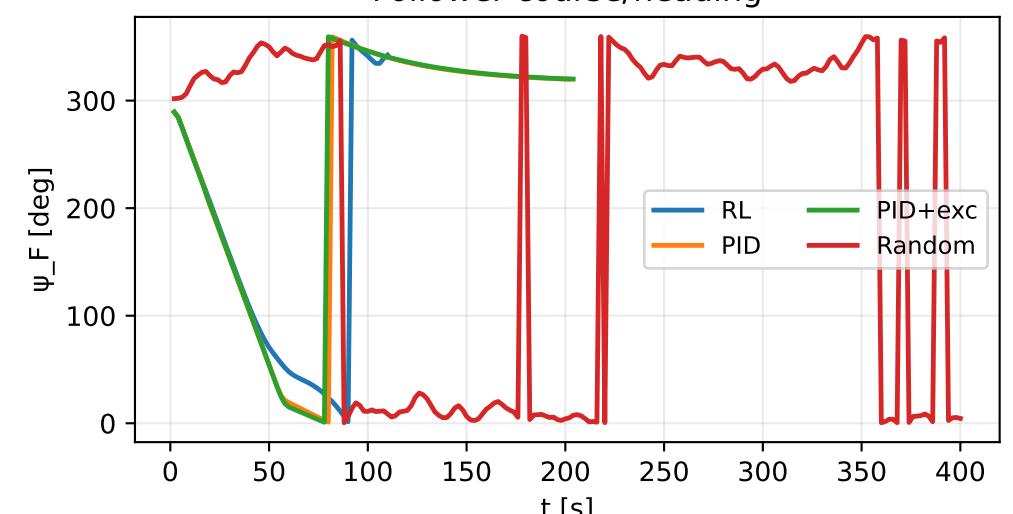
Information and excitation



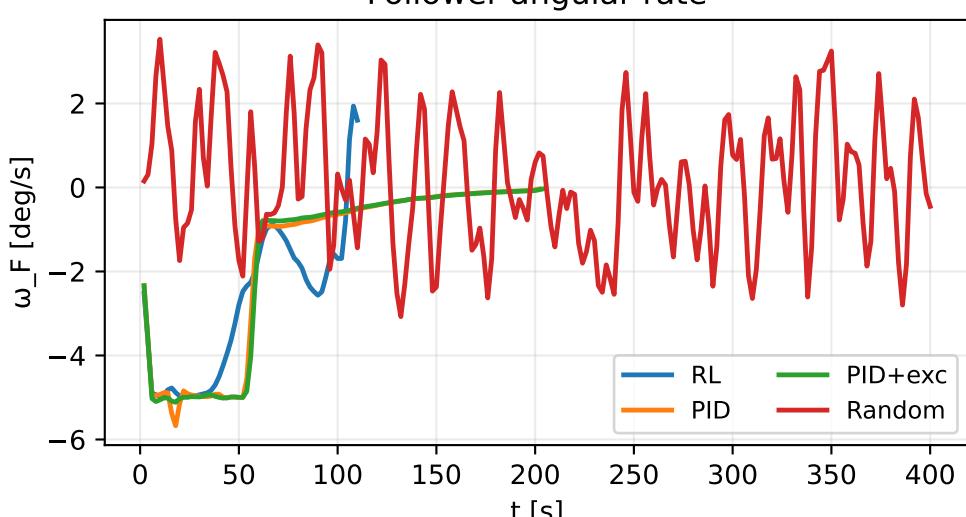
Follower speed



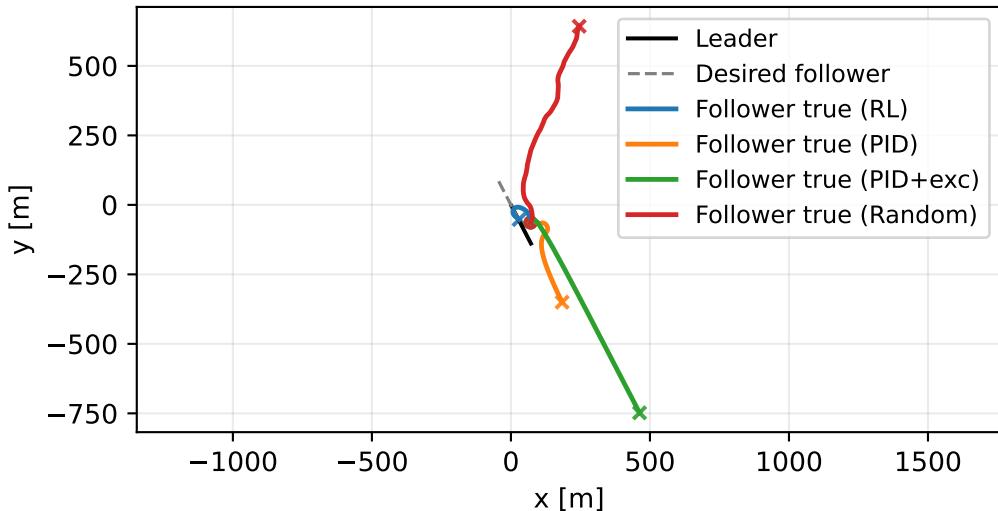
Follower course/heading



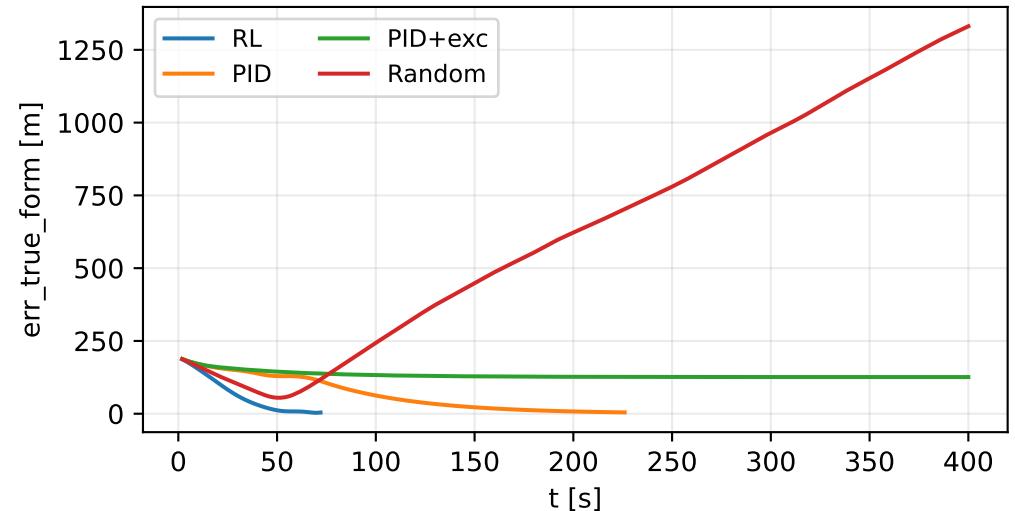
Follower angular rate



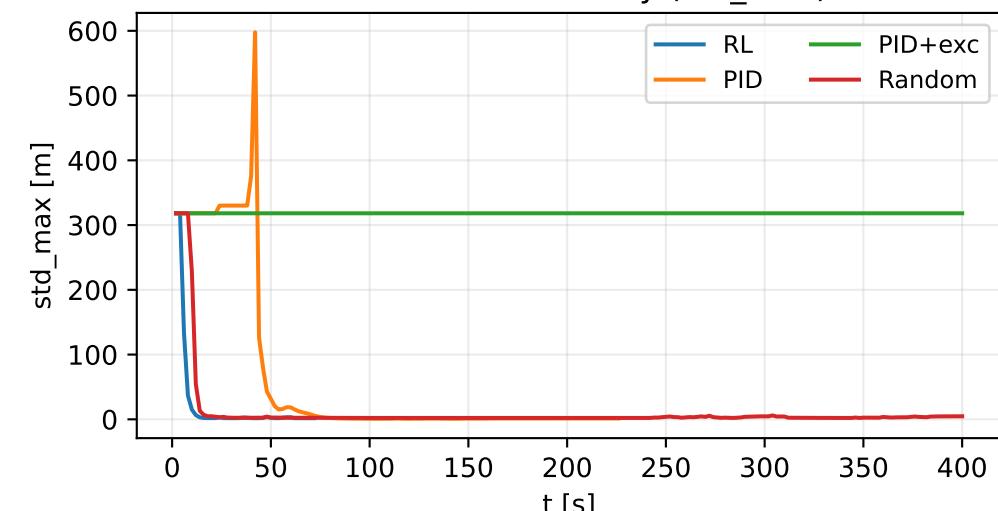
Trajectories (matched seed)



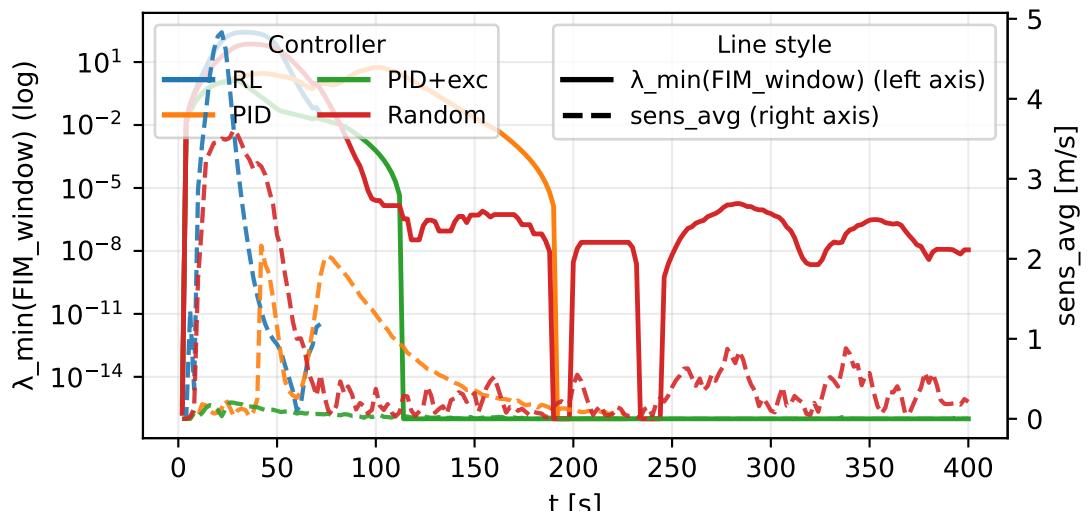
TRUE formation error



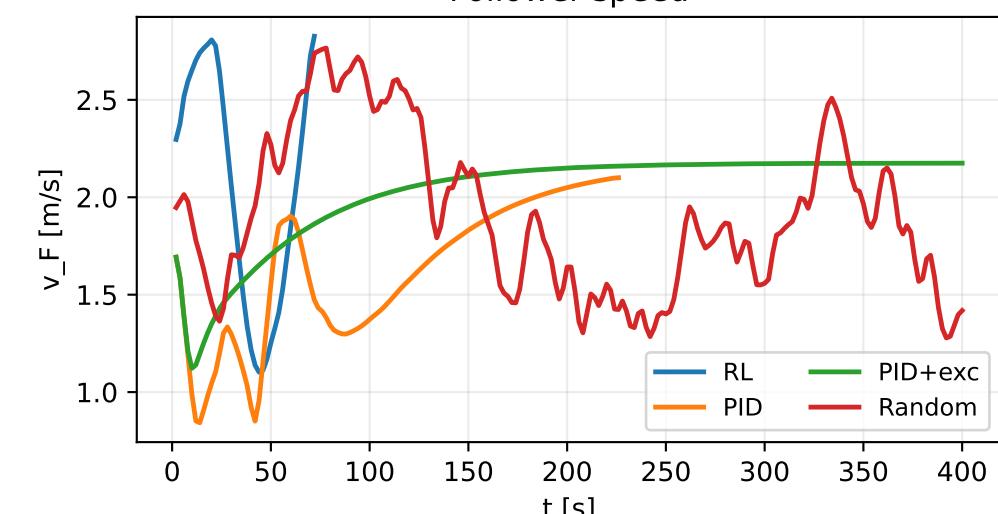
Estimator uncertainty (std_max)



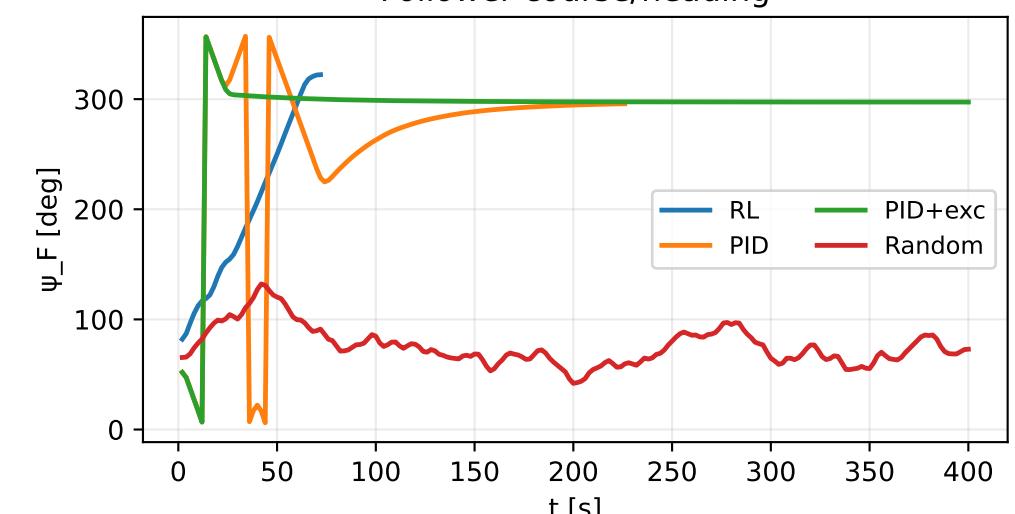
Information and excitation



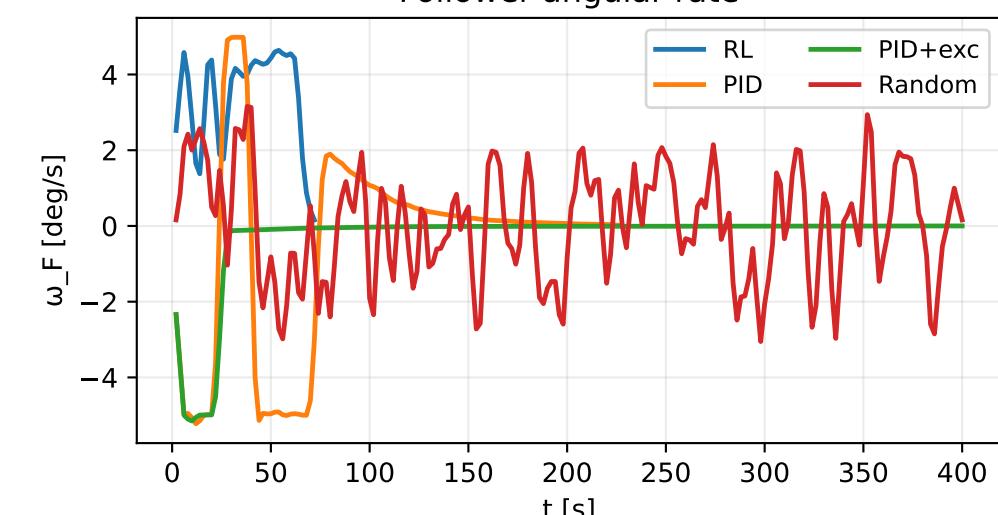
Follower speed



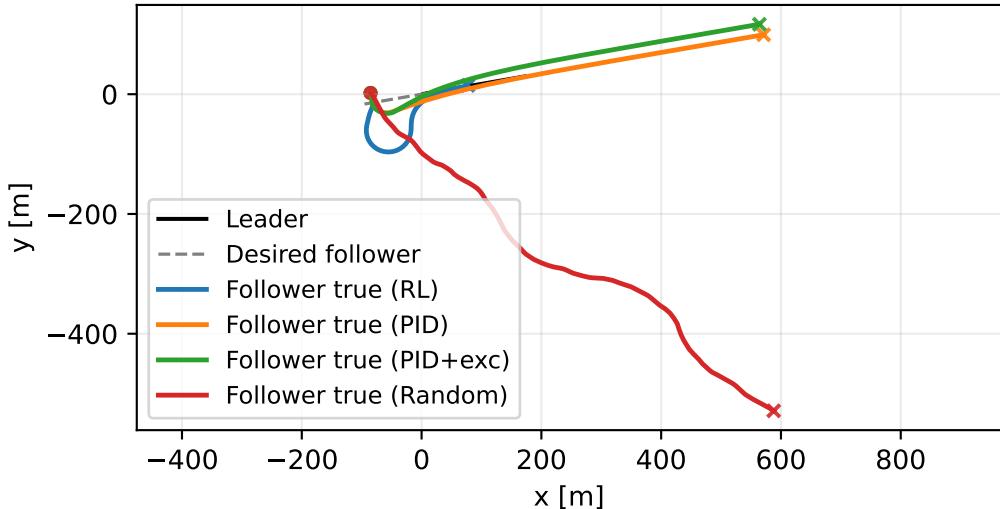
Follower course/heading



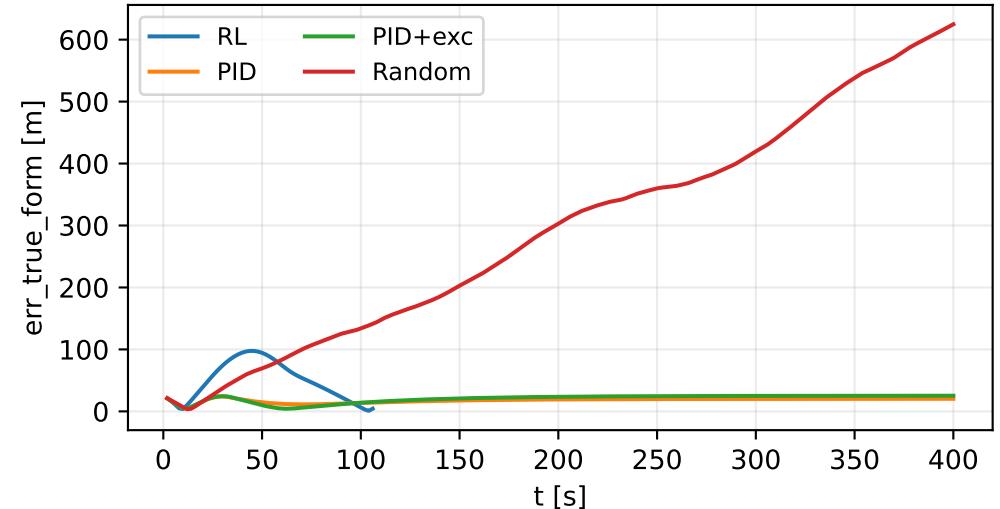
Follower angular rate



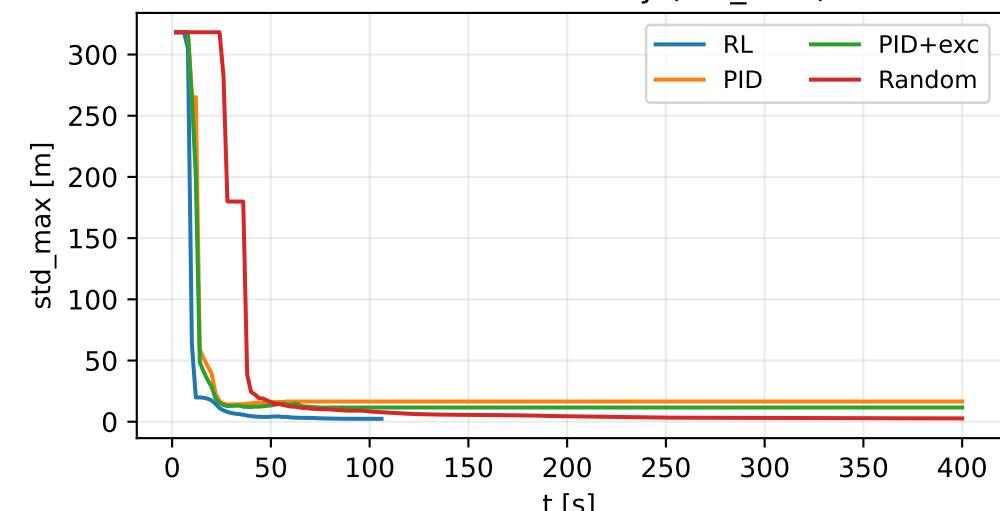
Trajectories (matched seed)



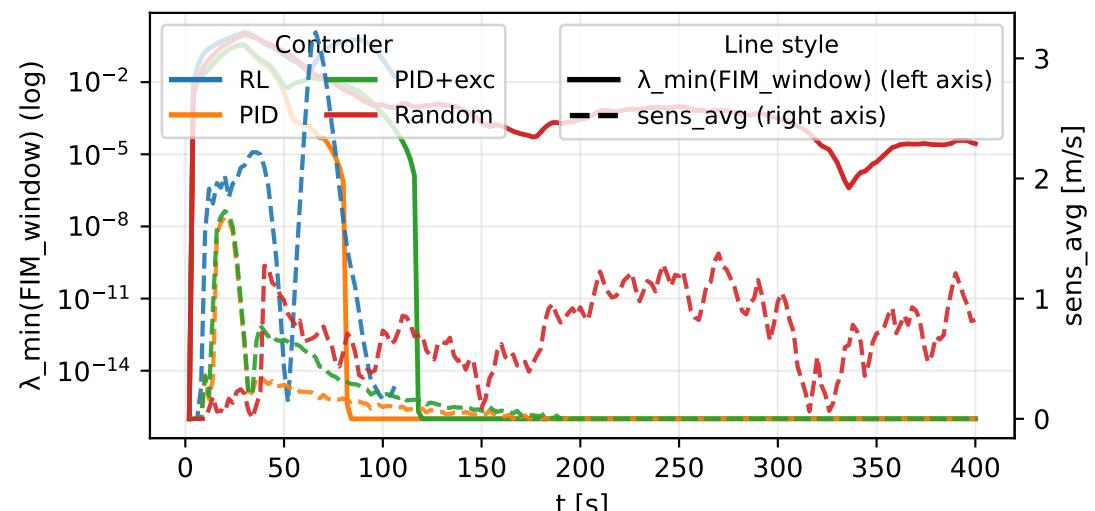
TRUE formation error



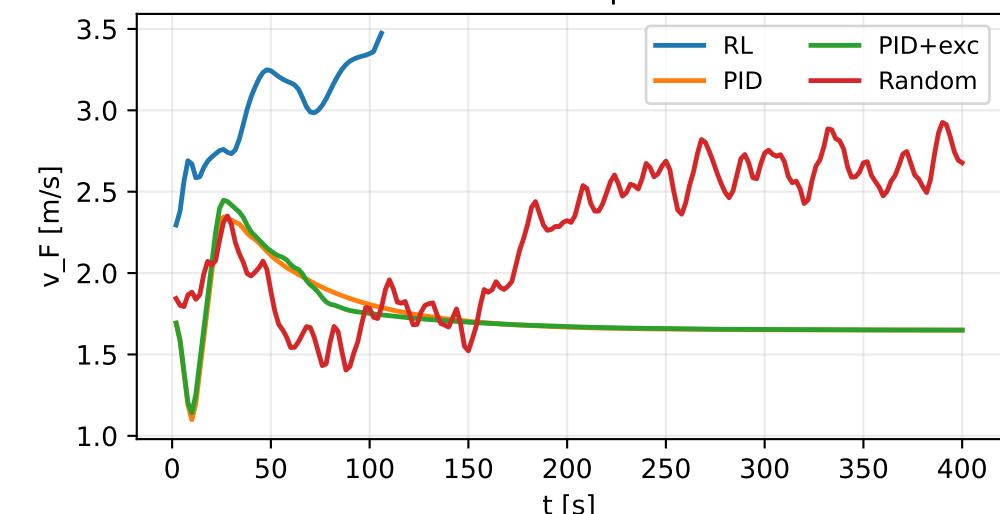
Estimator uncertainty (std_max)



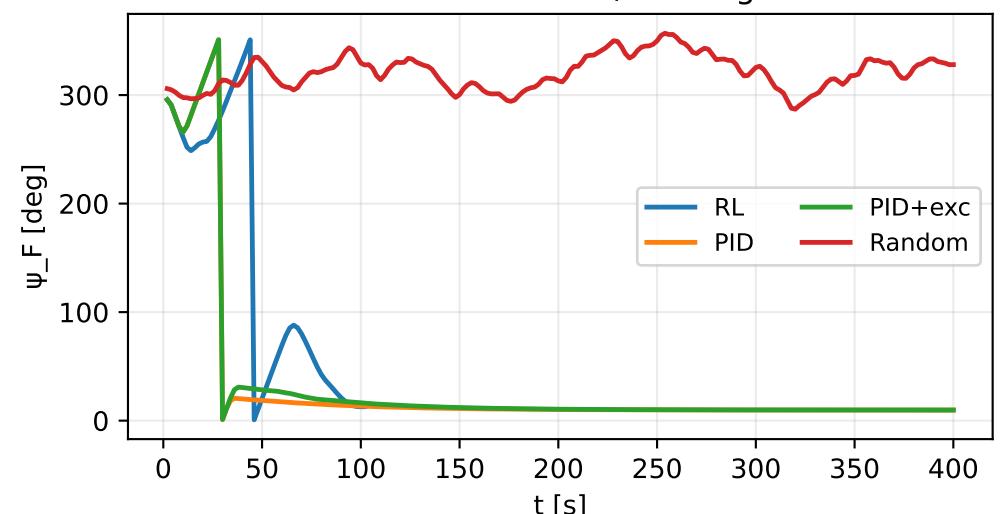
Information and excitation



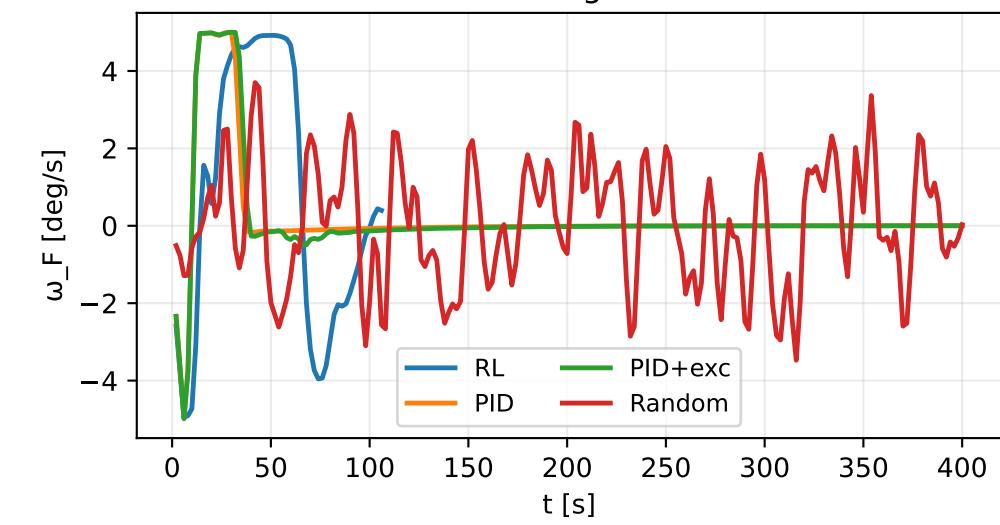
Follower speed



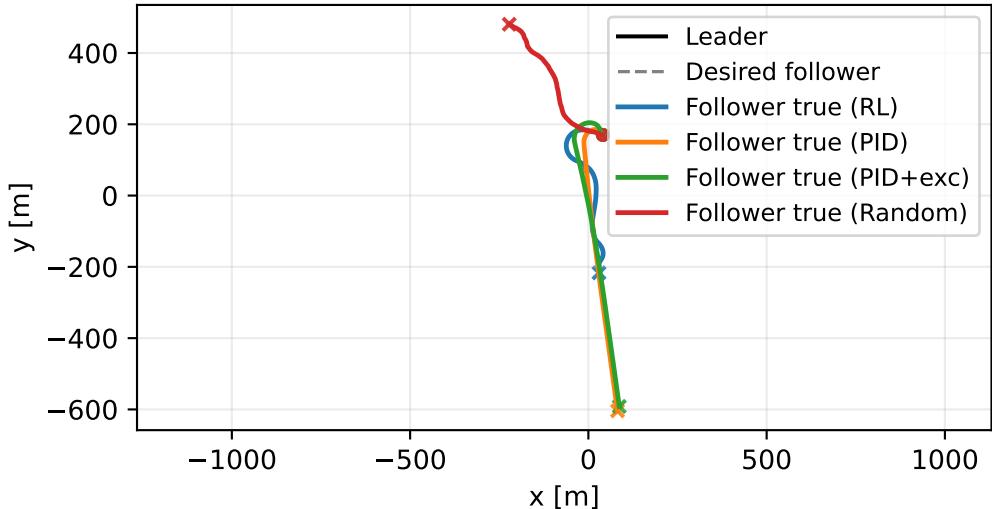
Follower course/heading



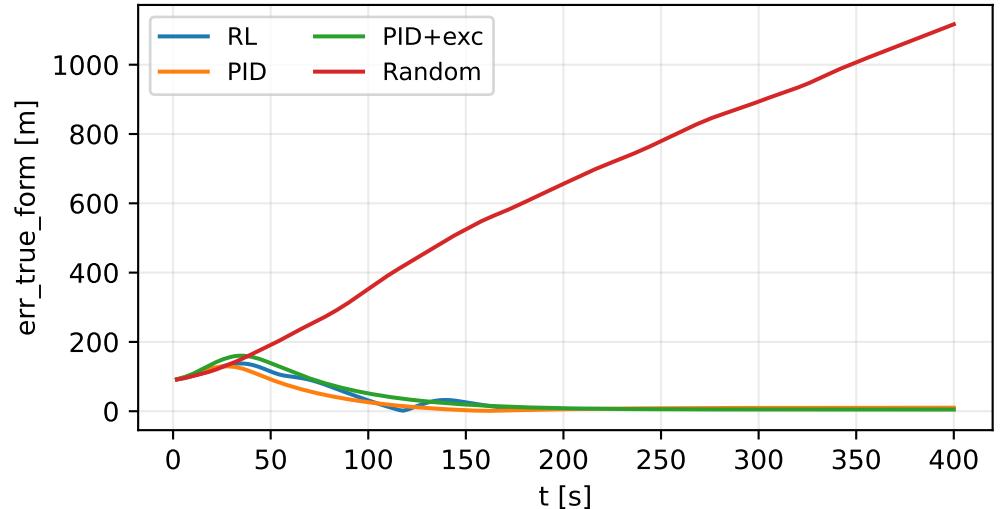
Follower angular rate



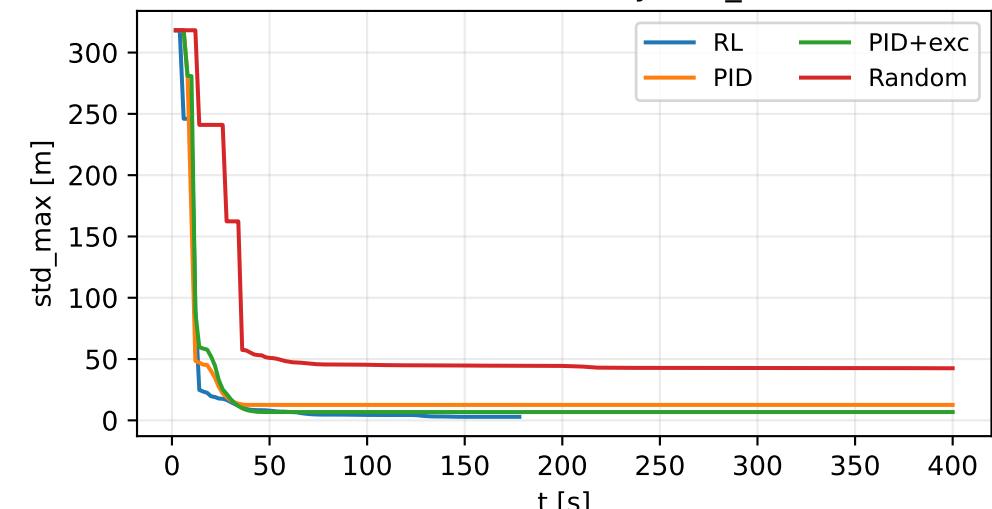
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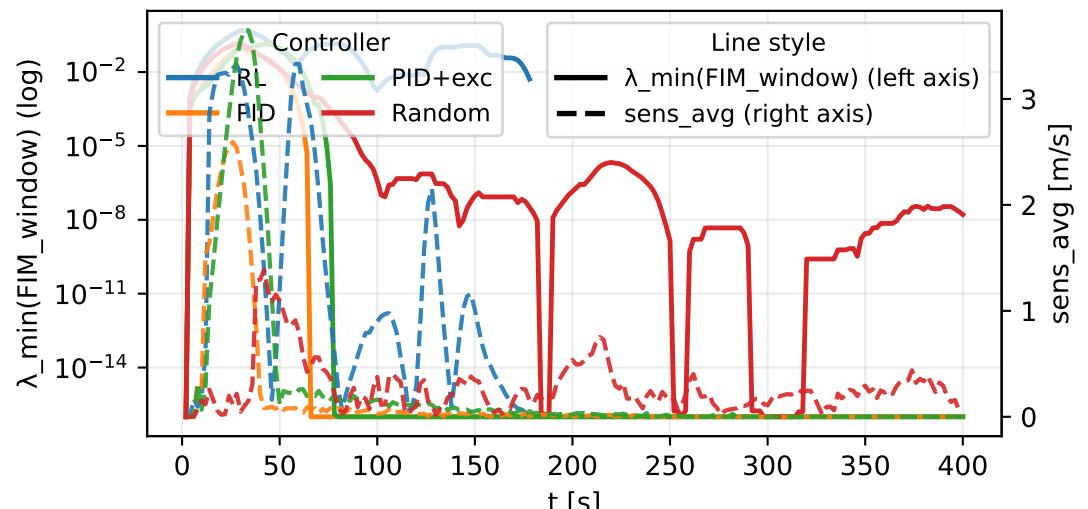
TRUE formation error



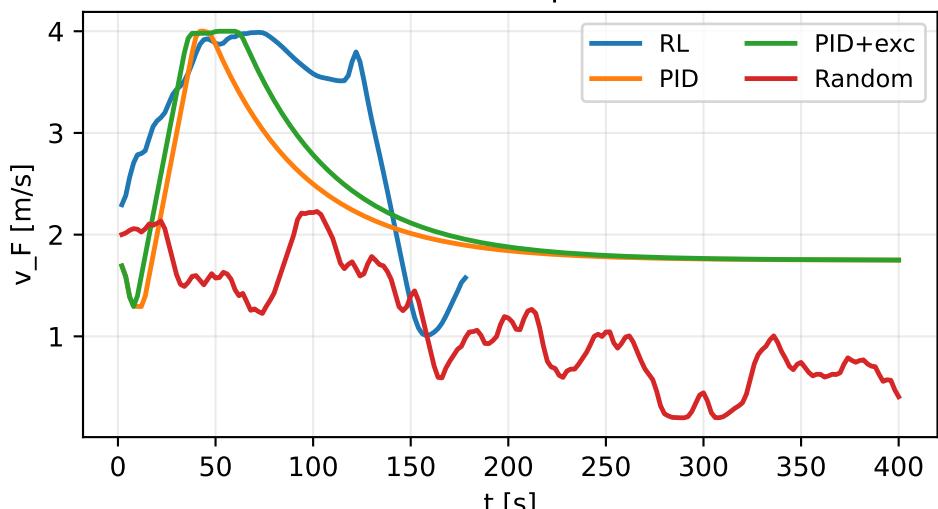
Estimator uncertainty (std_max)



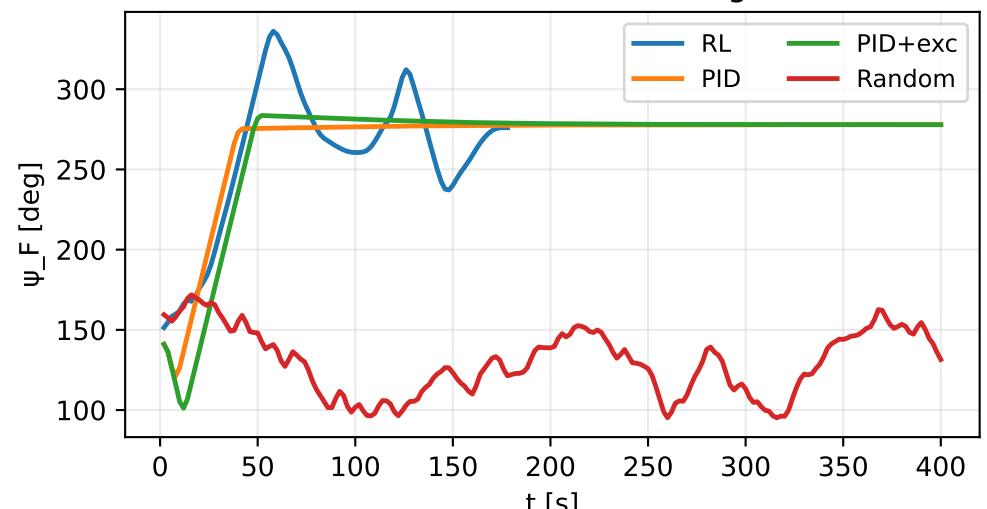
Information and excitation



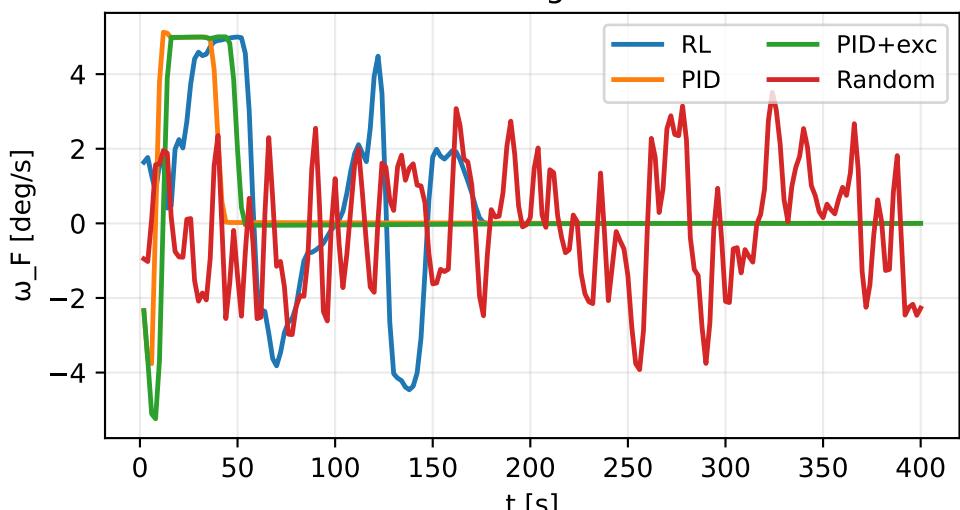
Follower speed



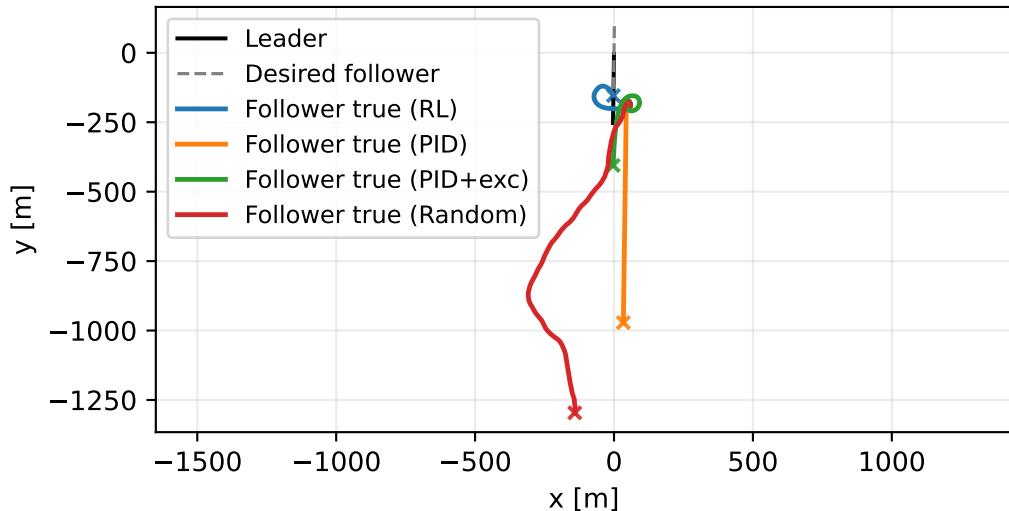
Follower course/heading



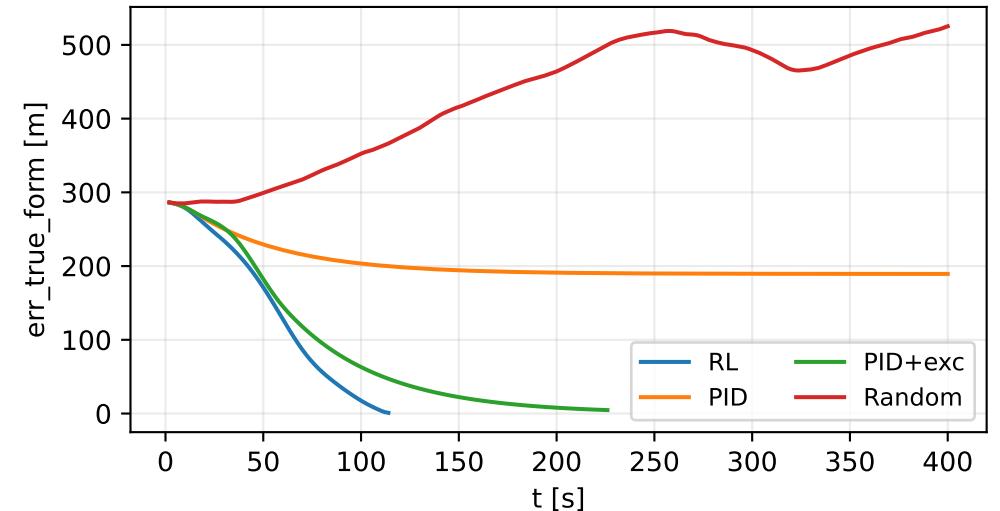
Follower angular rate



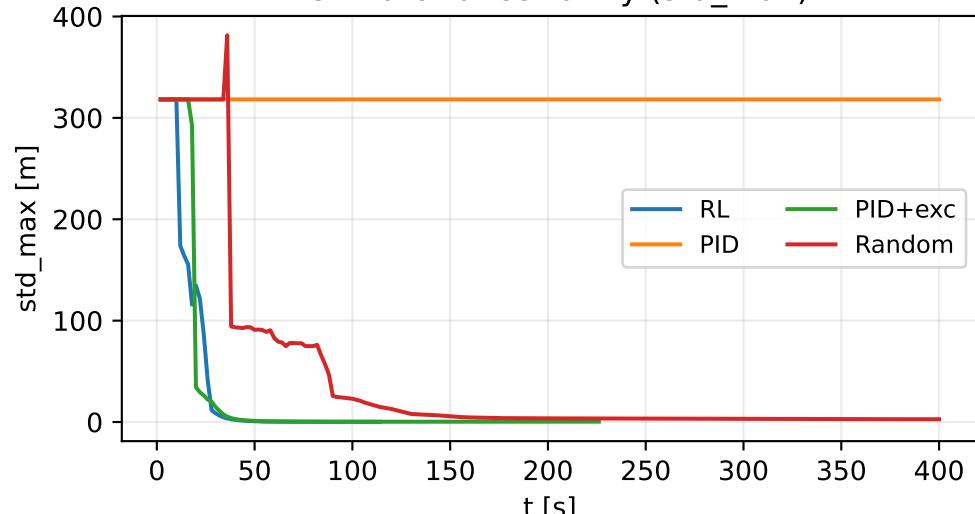
Trajectories (matched seed)



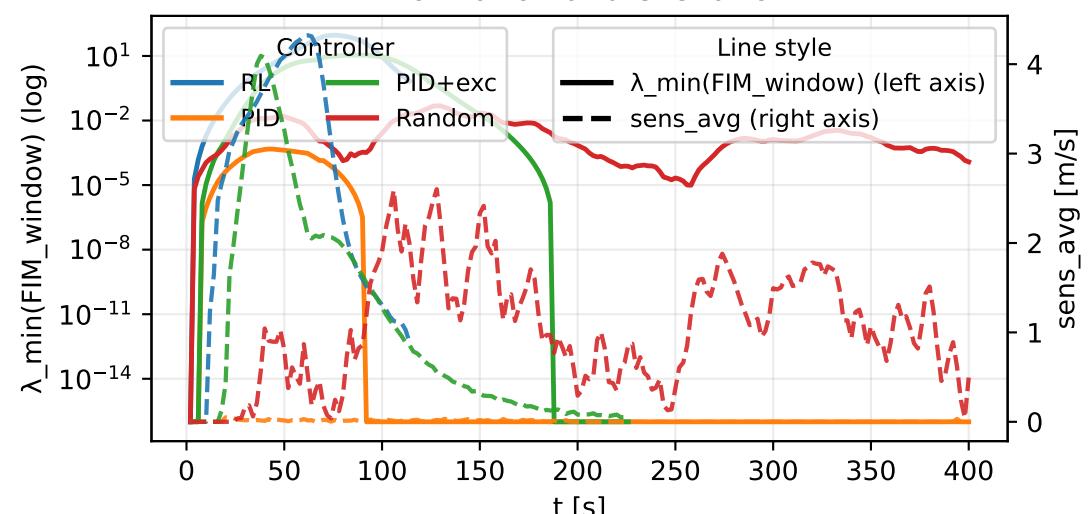
TRUE formation error



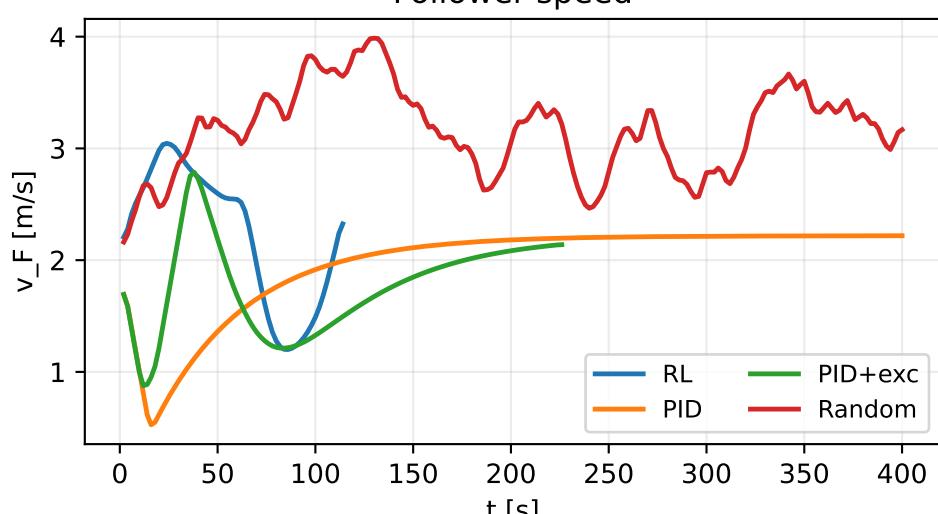
Estimator uncertainty (std_max)



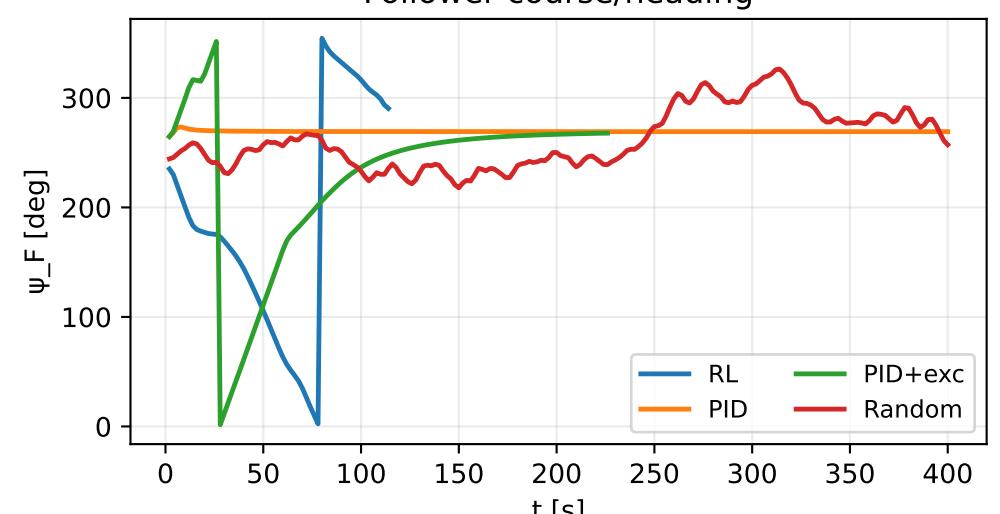
Information and excitation



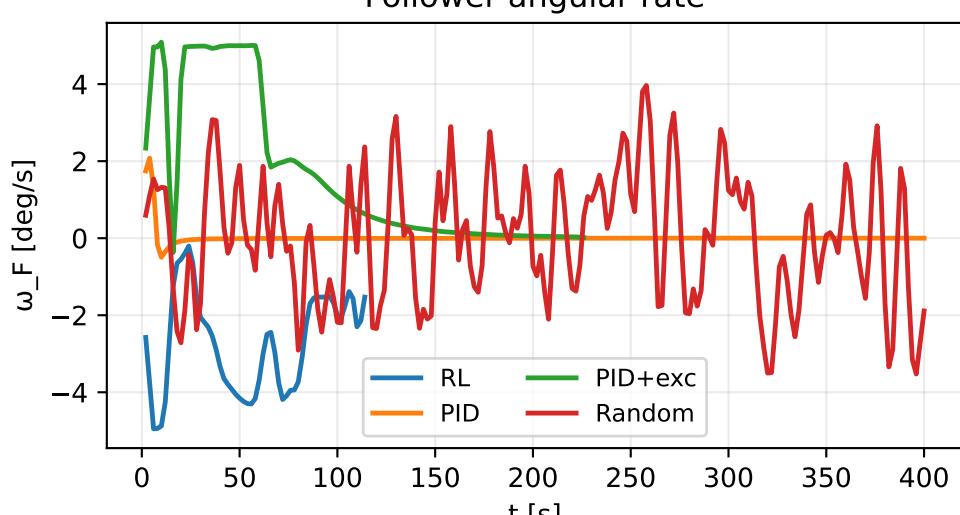
Follower speed



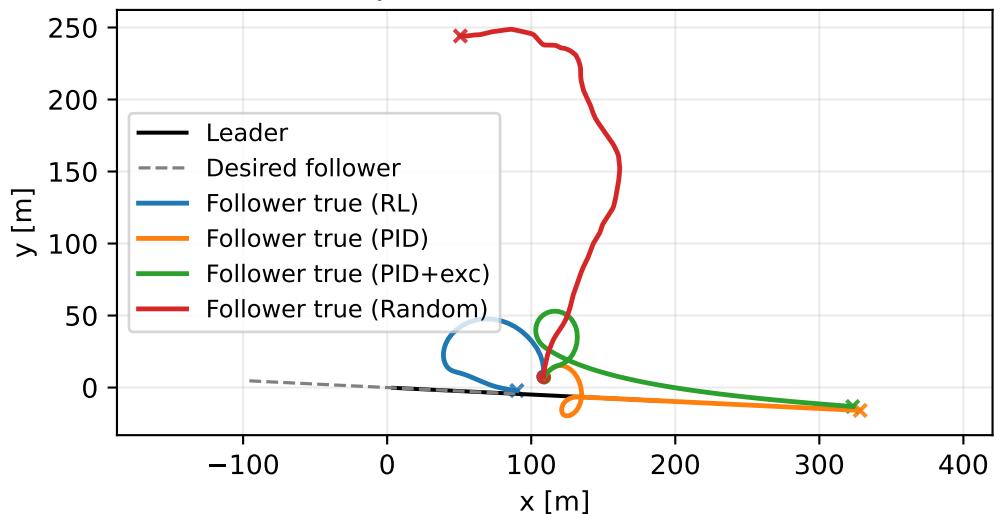
Follower course/heading



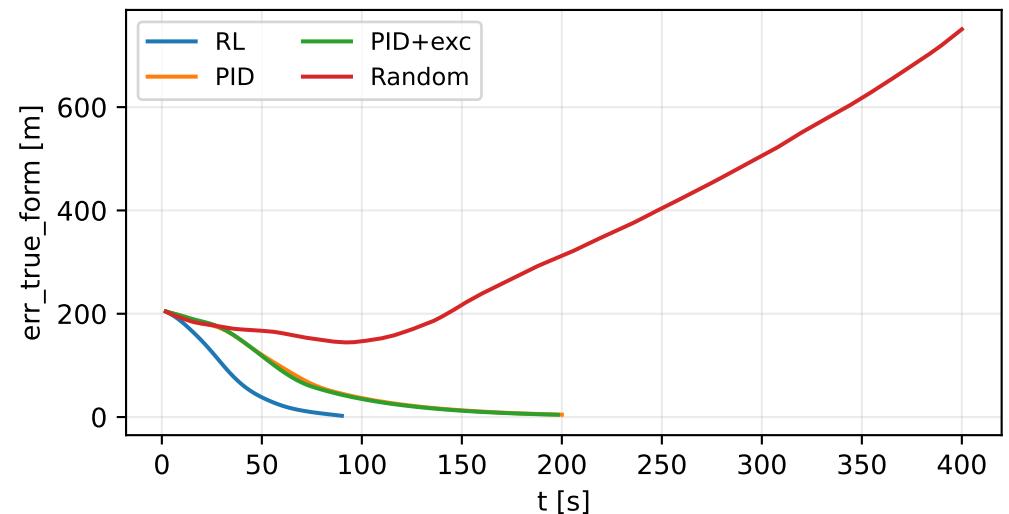
Follower angular rate



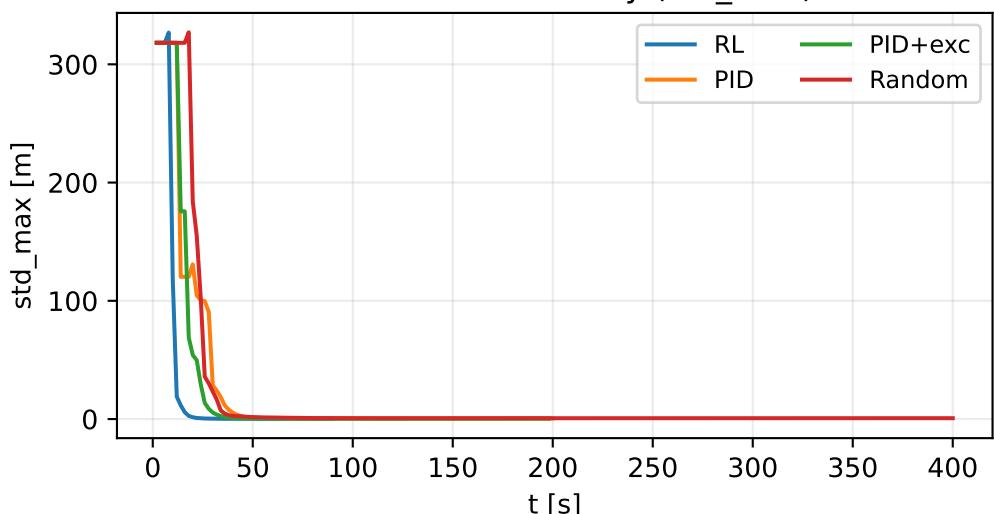
Trajectories (matched seed)



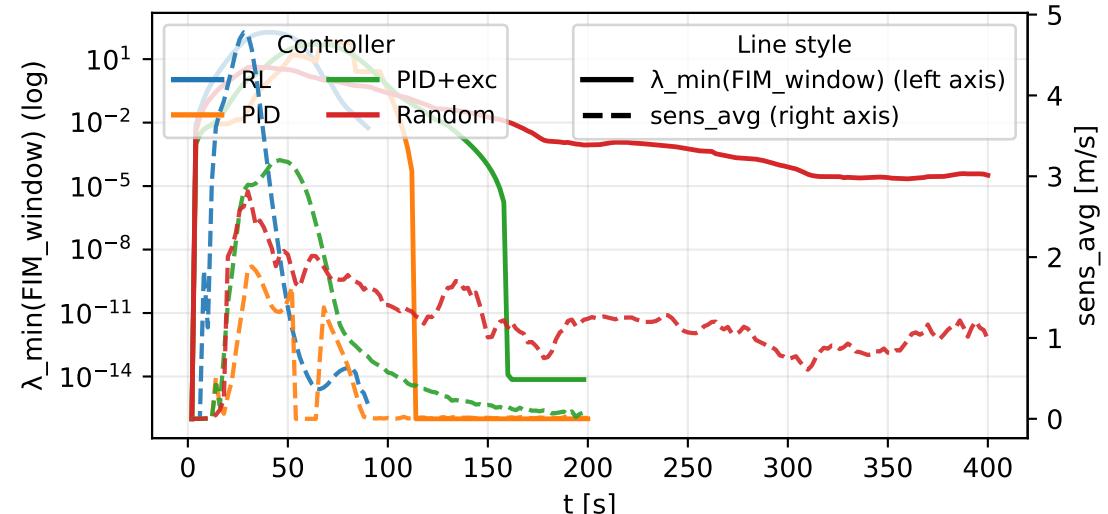
TRUE formation error



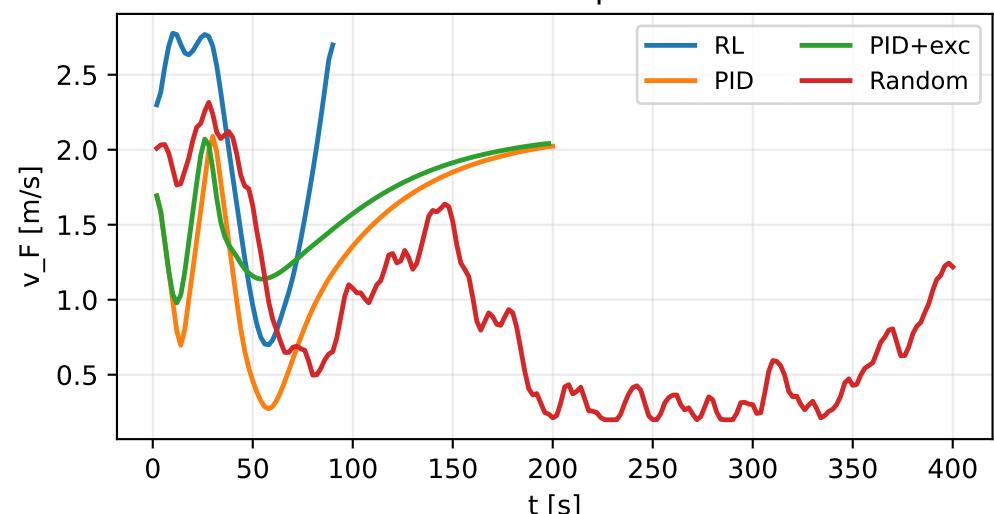
Estimator uncertainty (std_max)



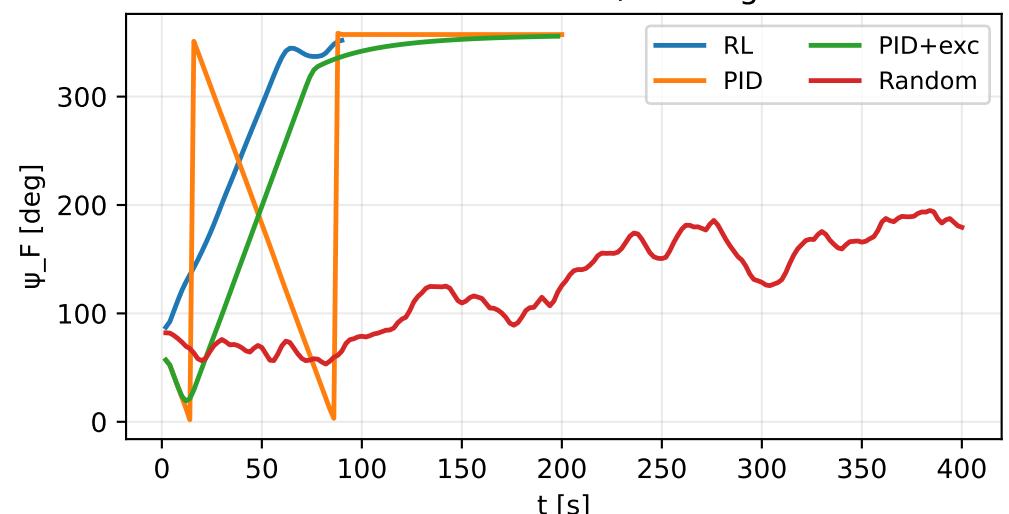
Information and excitation



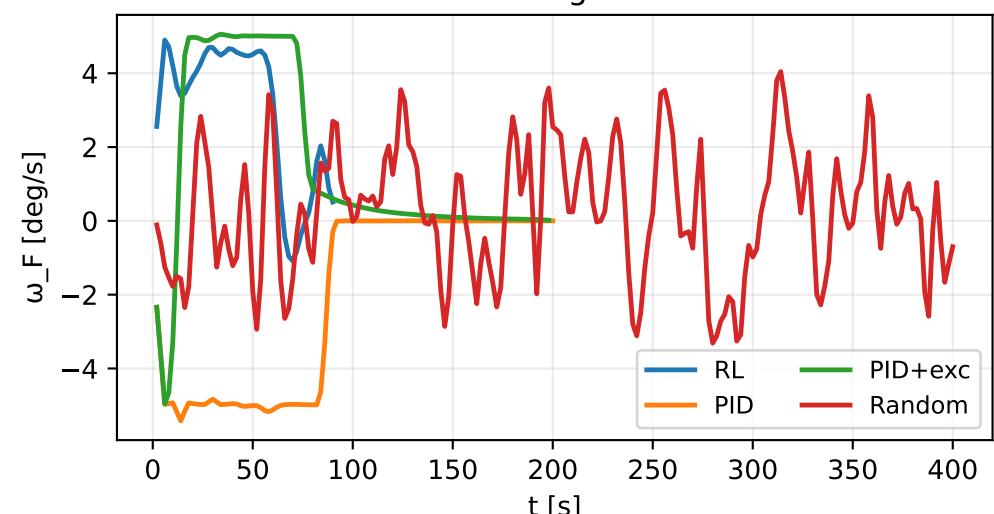
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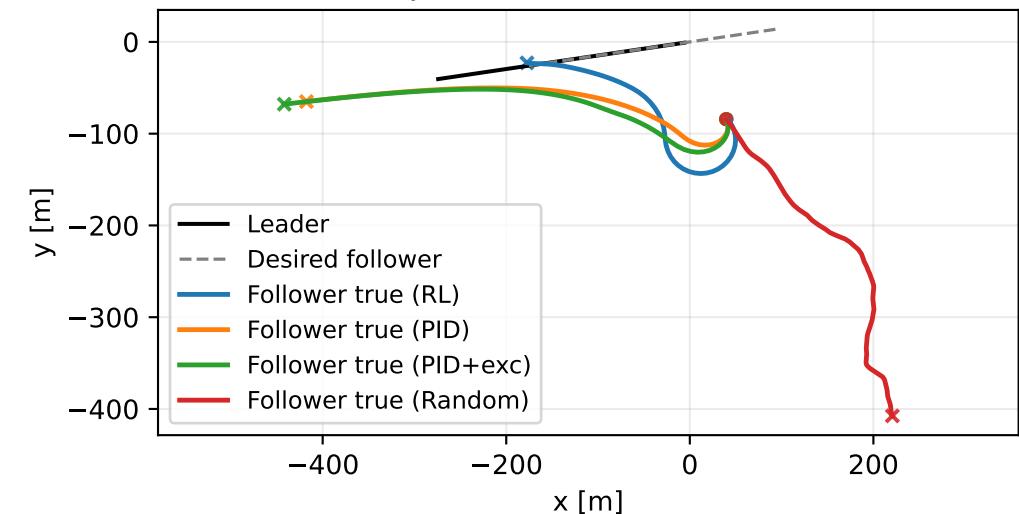
Follower course/heading



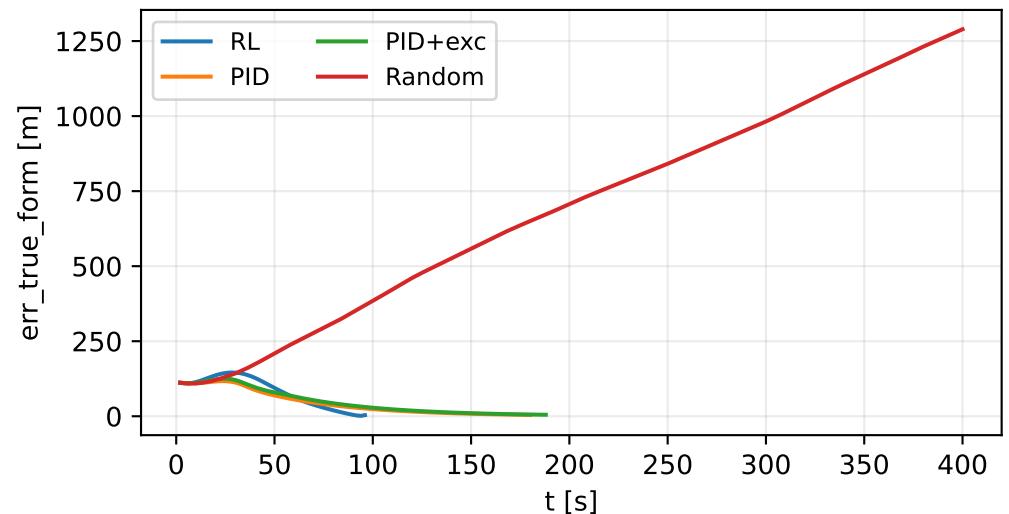
Follower angular rate



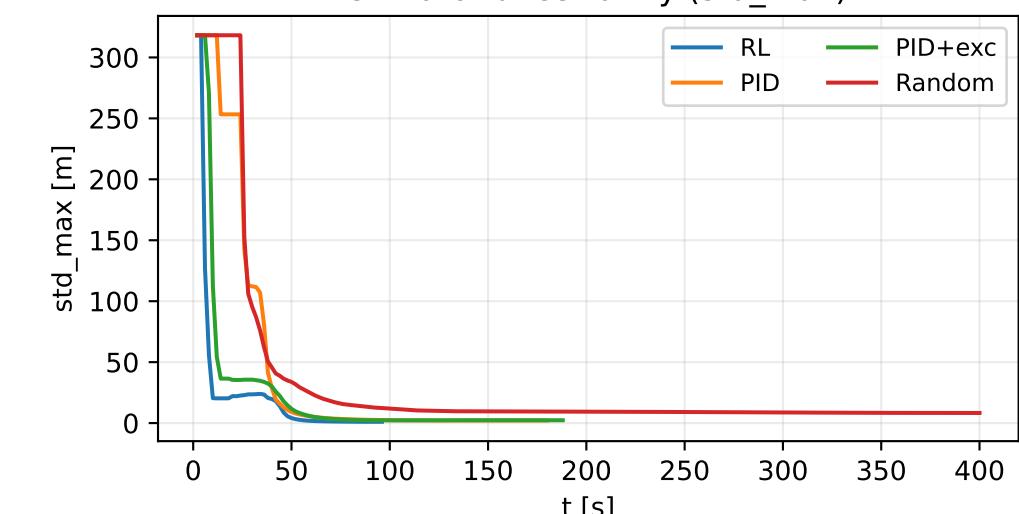
Trajectories (matched seed)



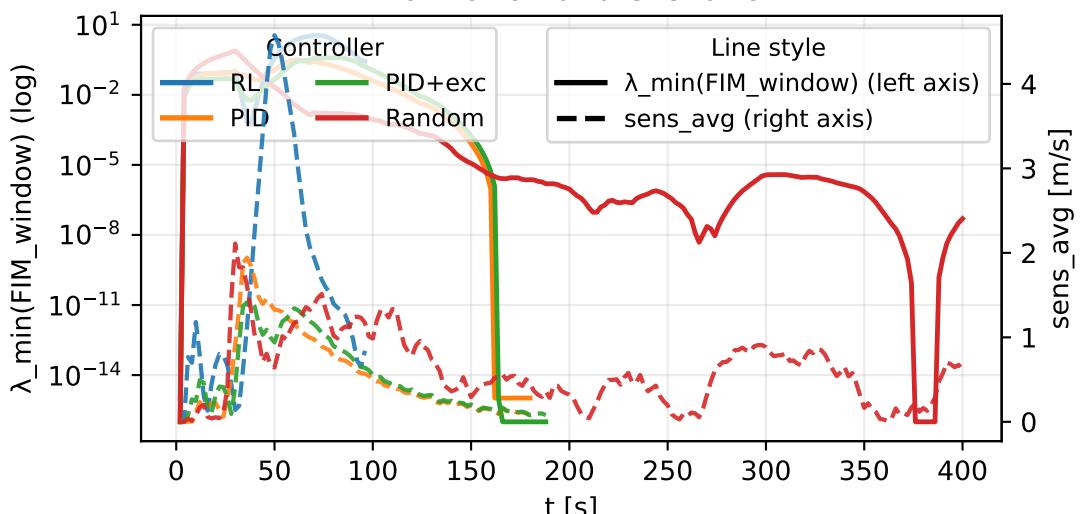
TRUE formation error



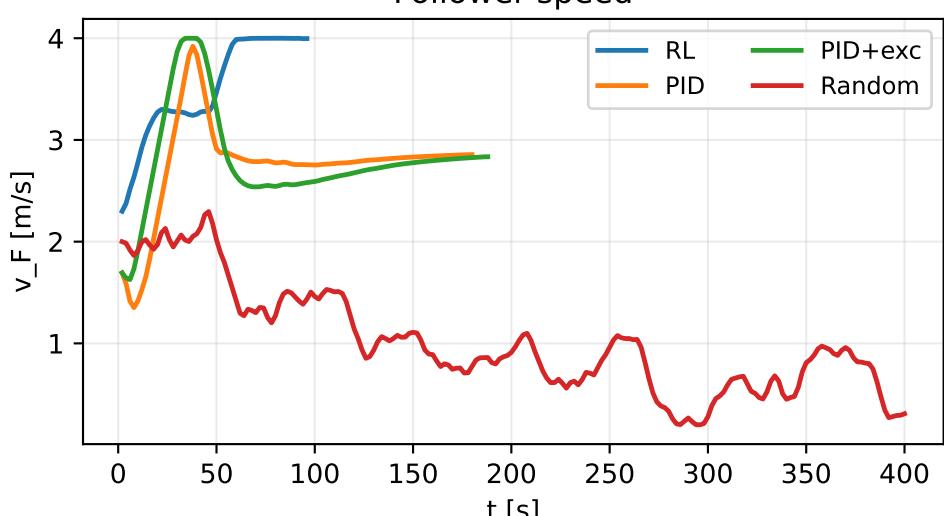
Estimator uncertainty (std_max)



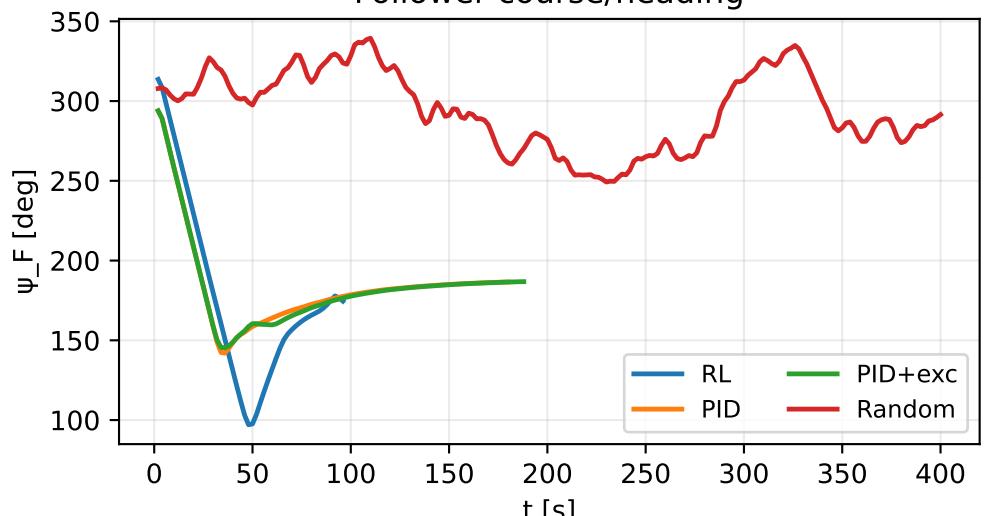
Information and excitation



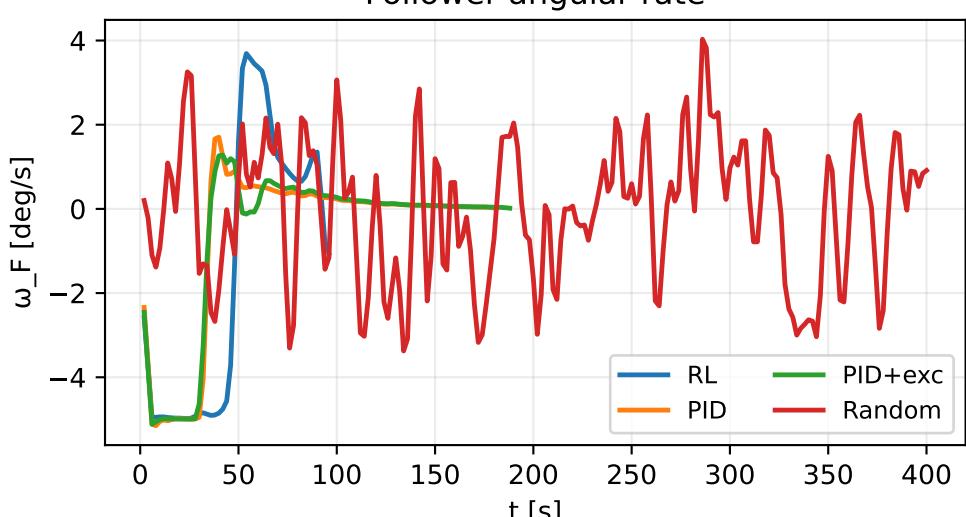
Follower speed



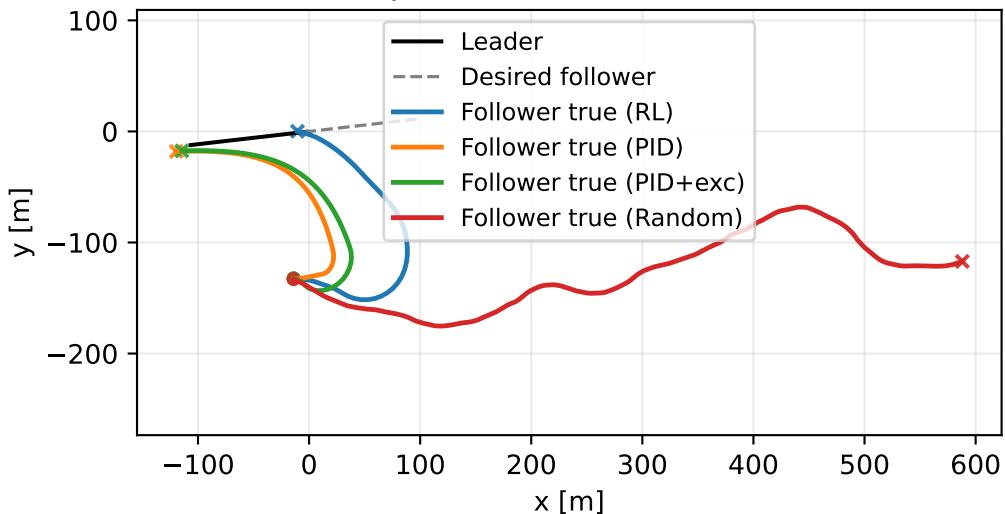
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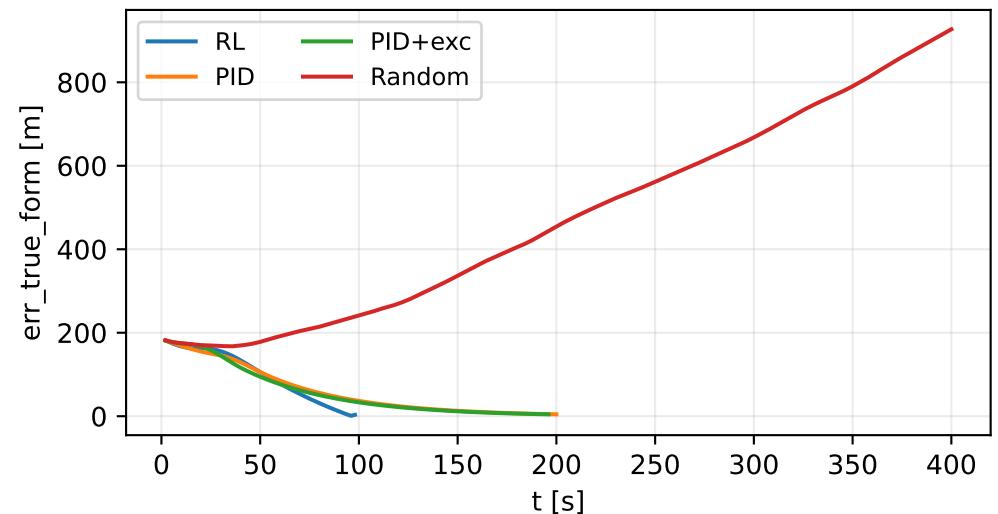
Follower angular rate



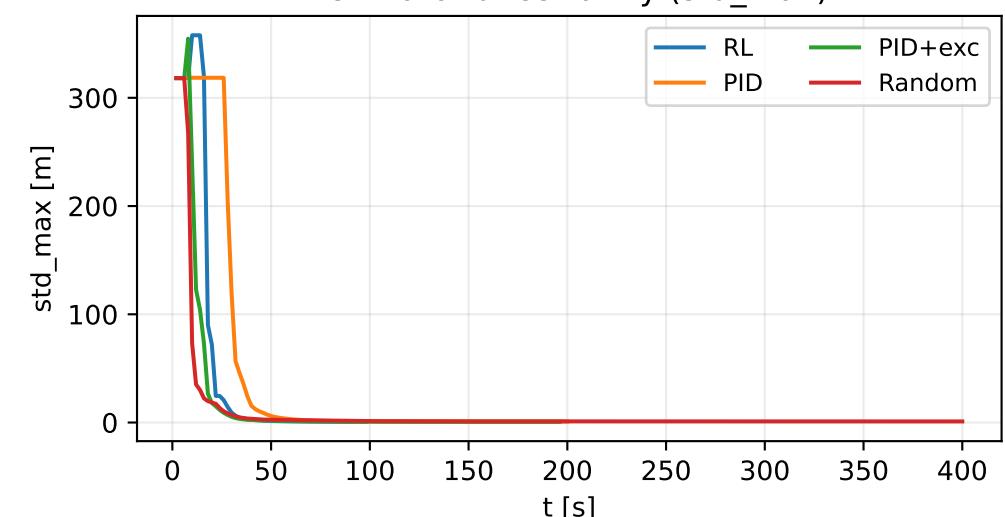
Trajectories (matched seed)



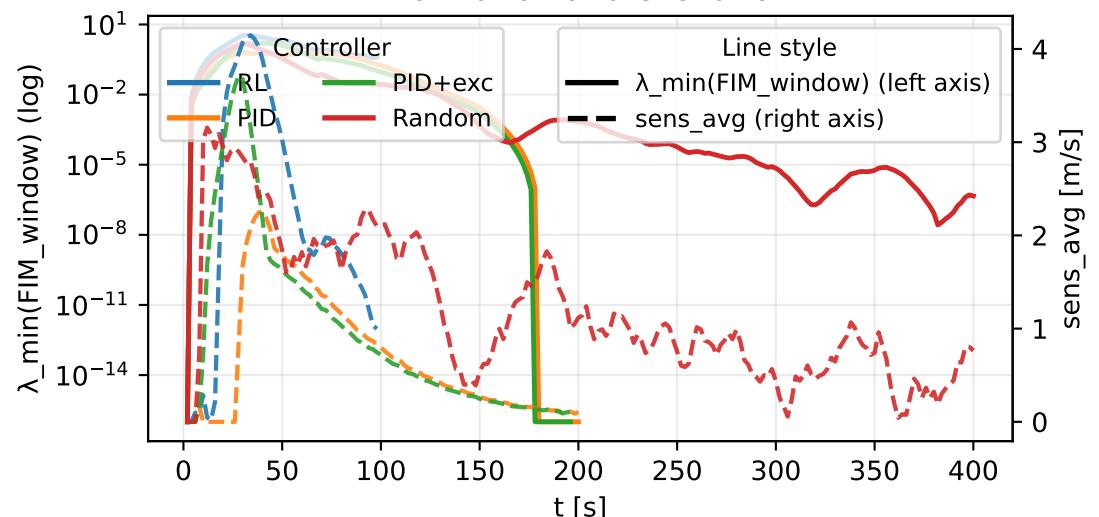
TRUE formation error



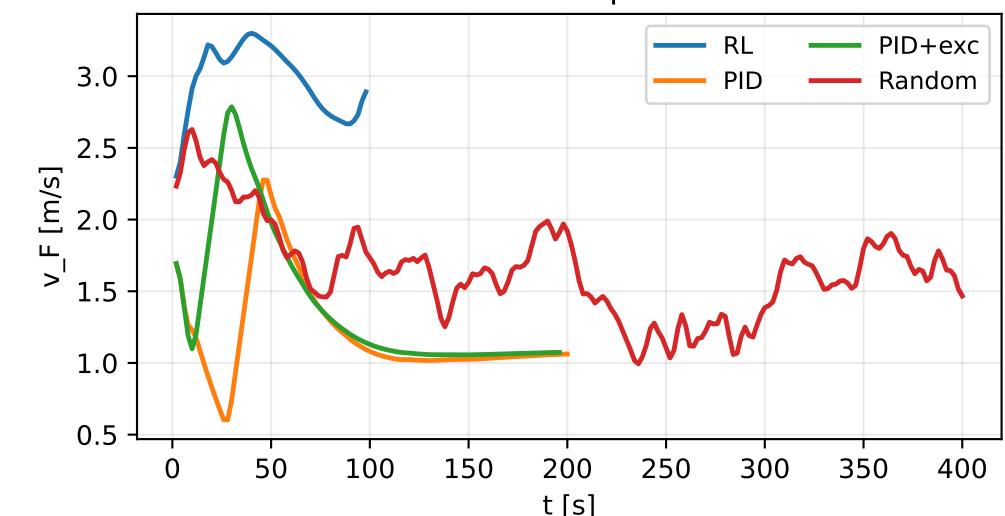
Estimator uncertainty (std_max)



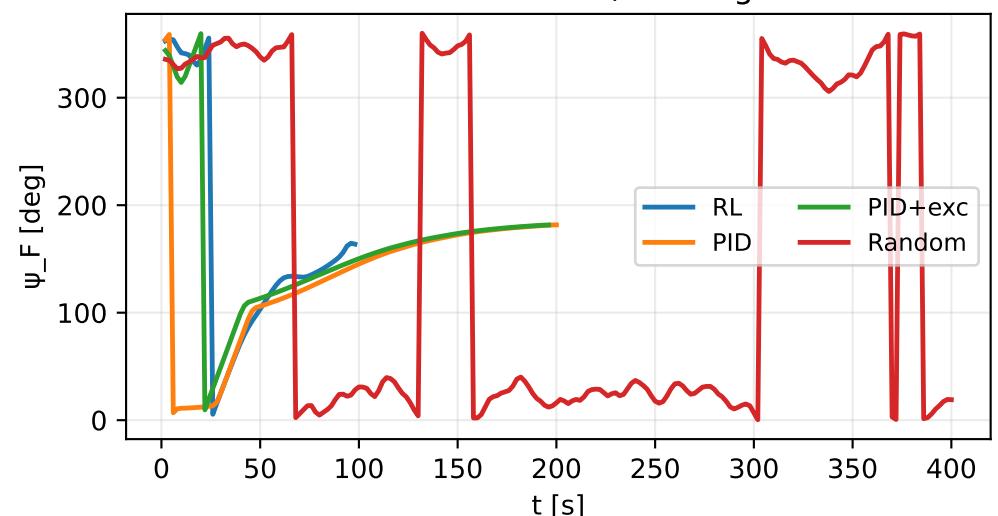
Information and excitation



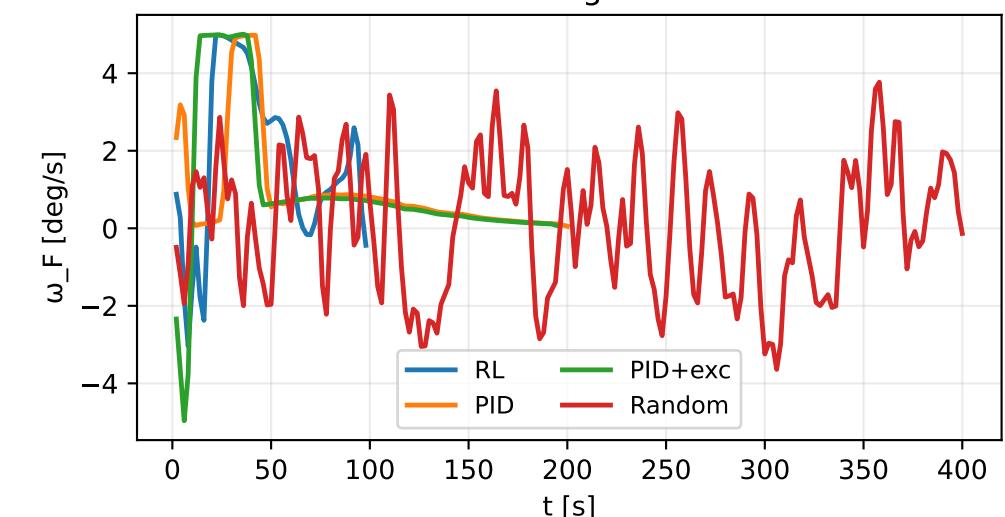
Follower speed



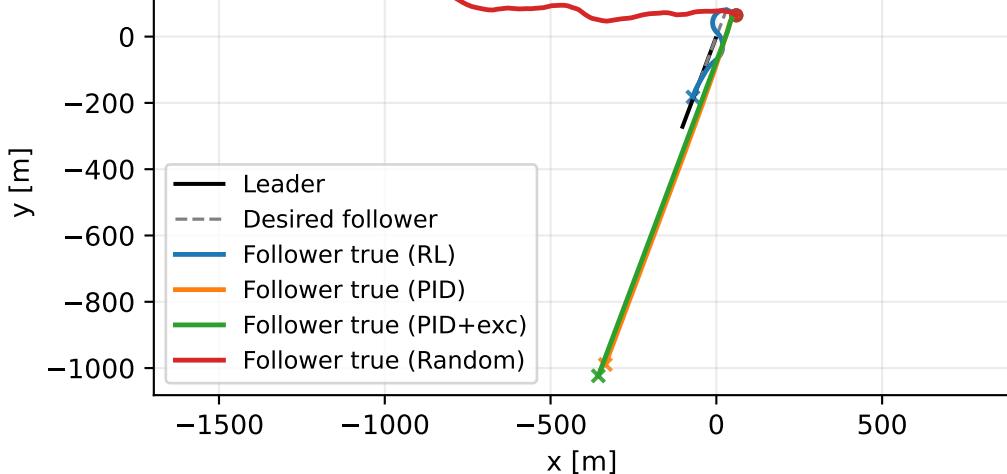
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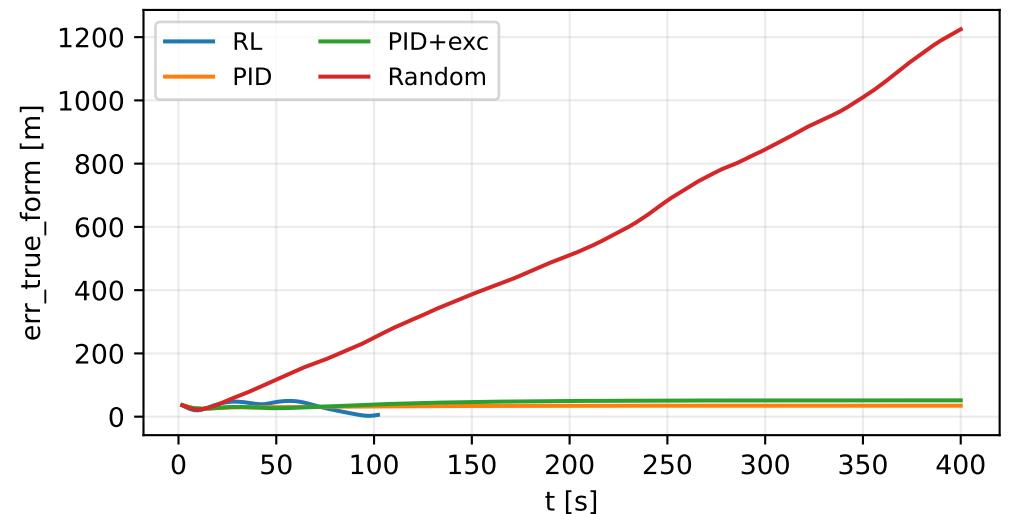
Follower angular rate



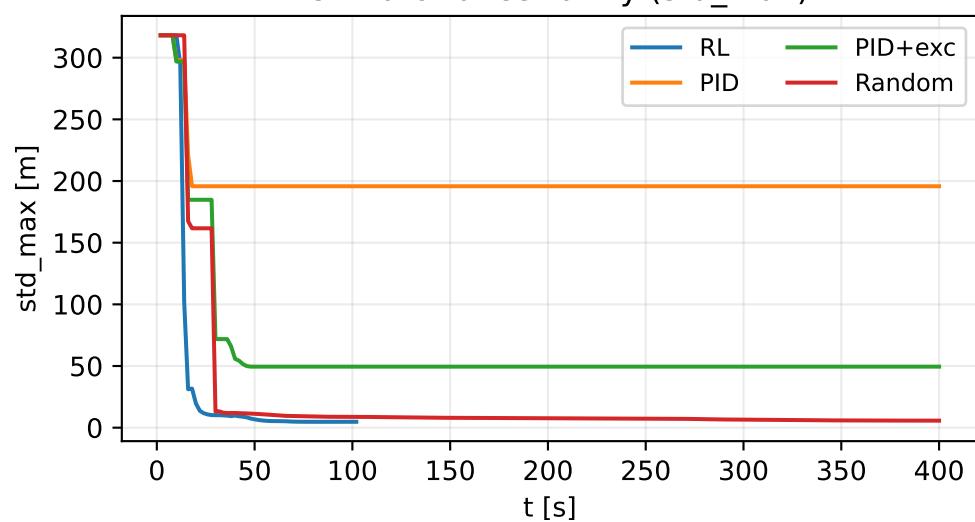
Trajectories (matched seed)



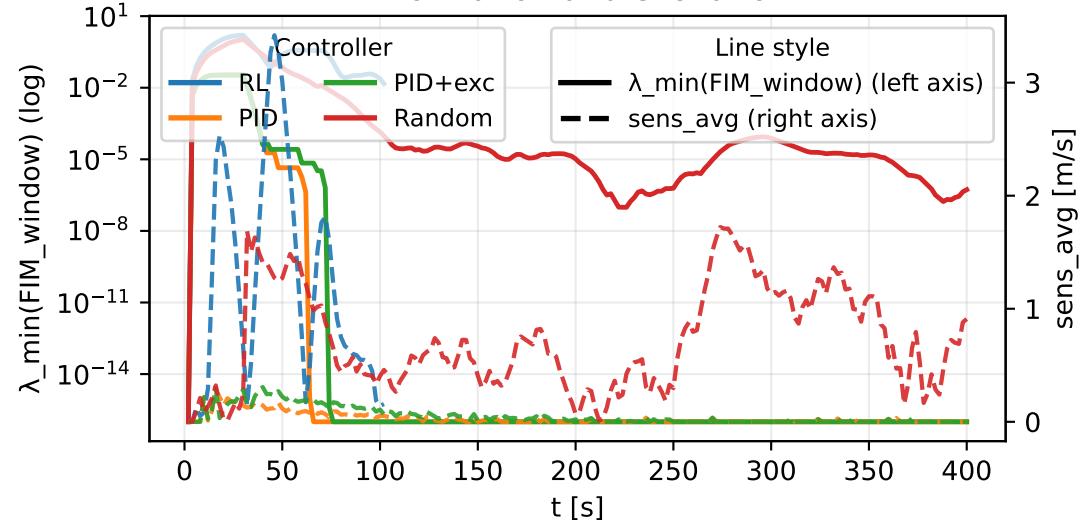
TRUE formation error



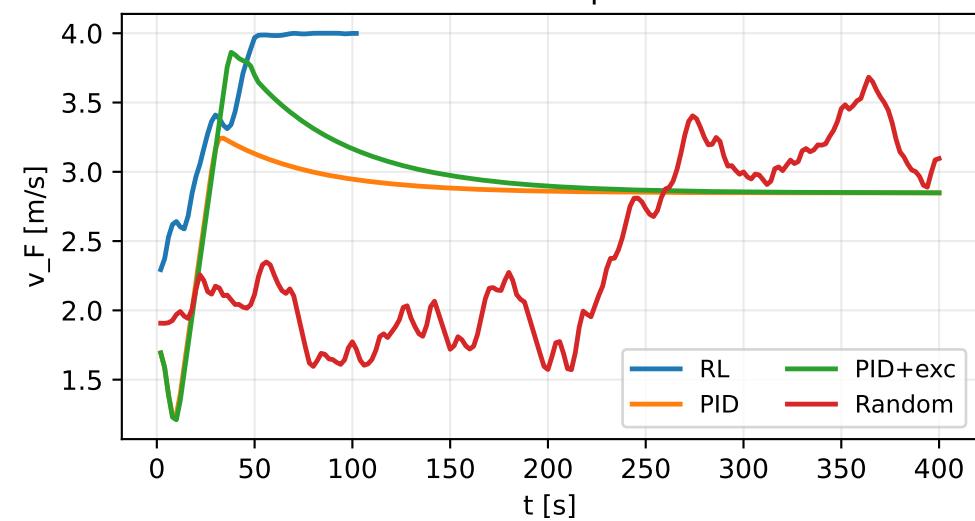
Estimator uncertainty (std_max)



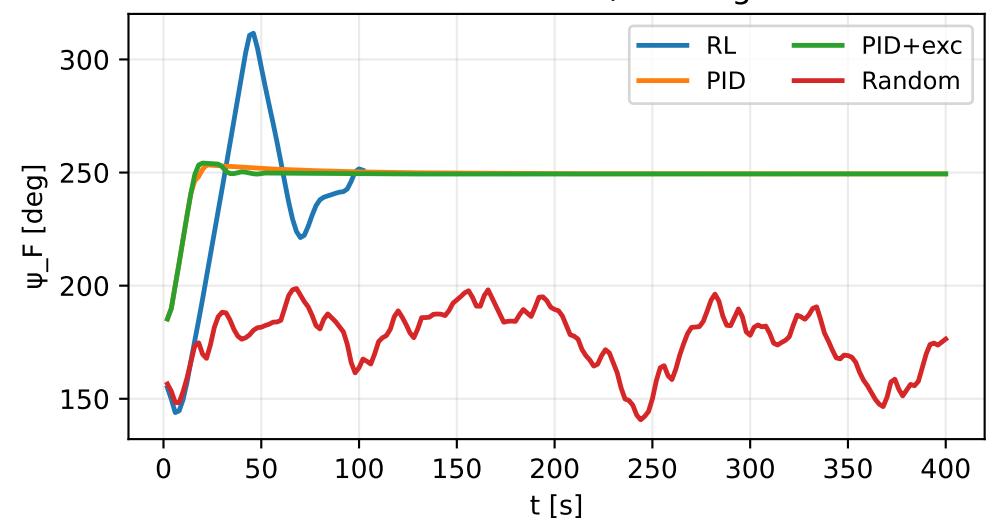
Information and excitation



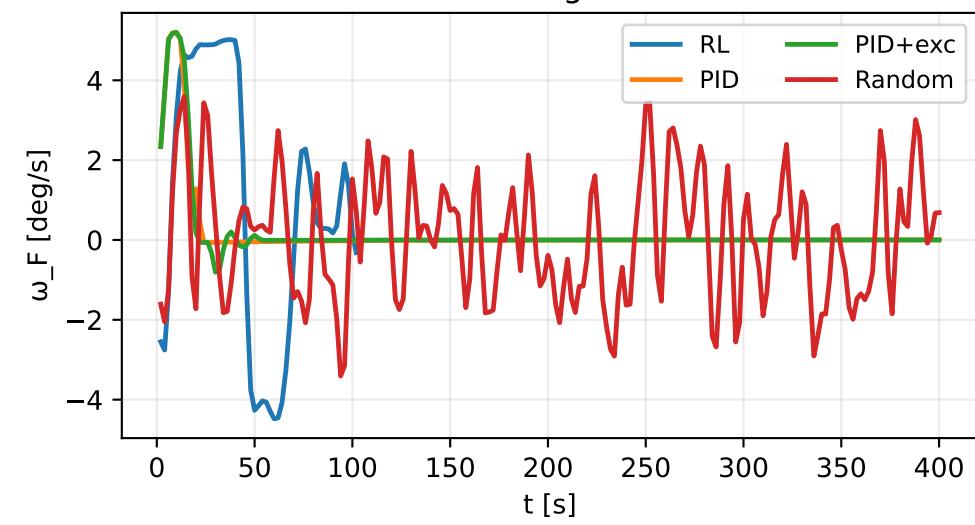
Follower speed



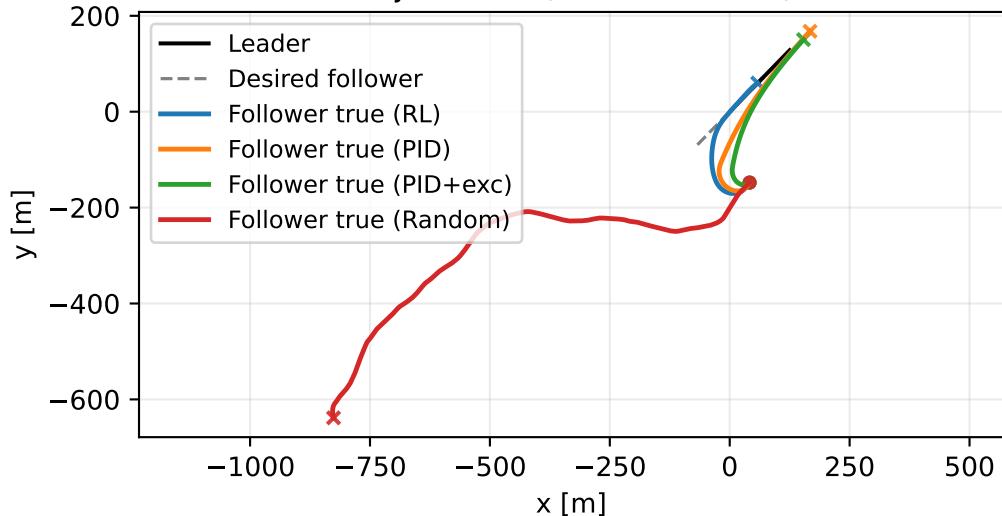
Follower course/heading



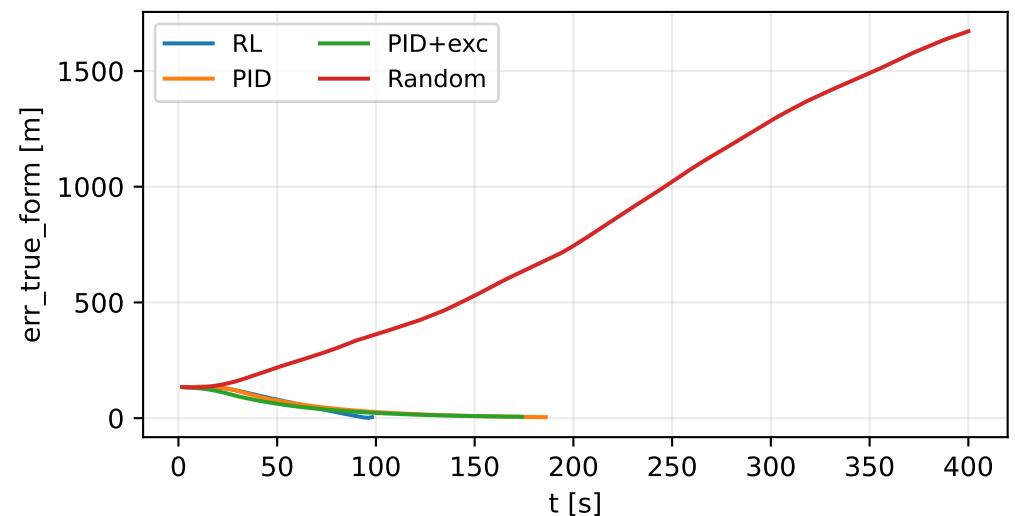
Follower angular rate



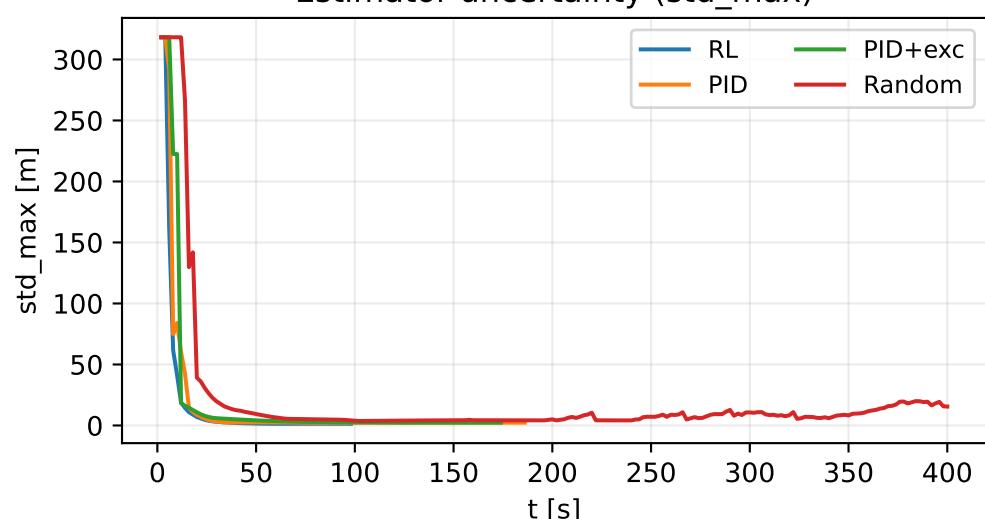
Trajectories (matched seed)



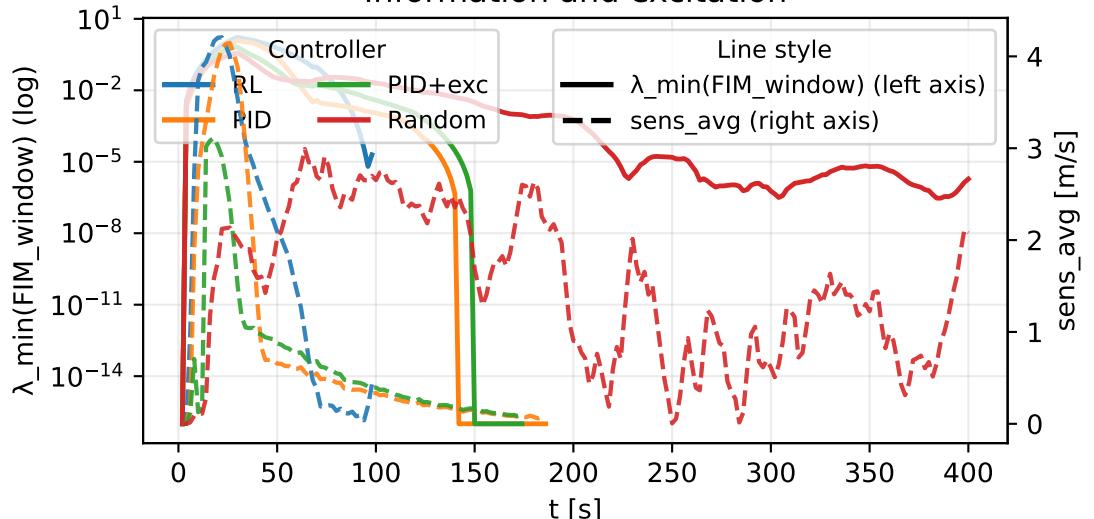
TRUE formation error



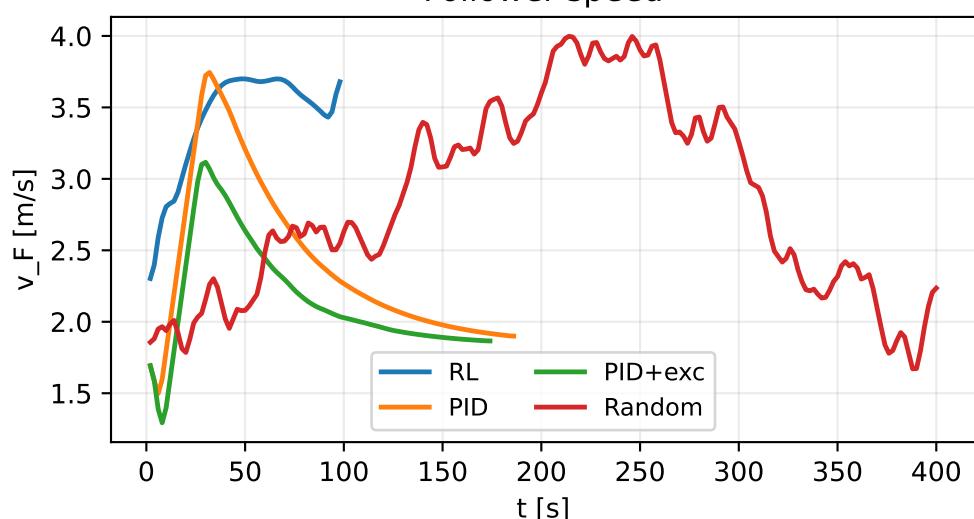
Estimator uncertainty (std_max)



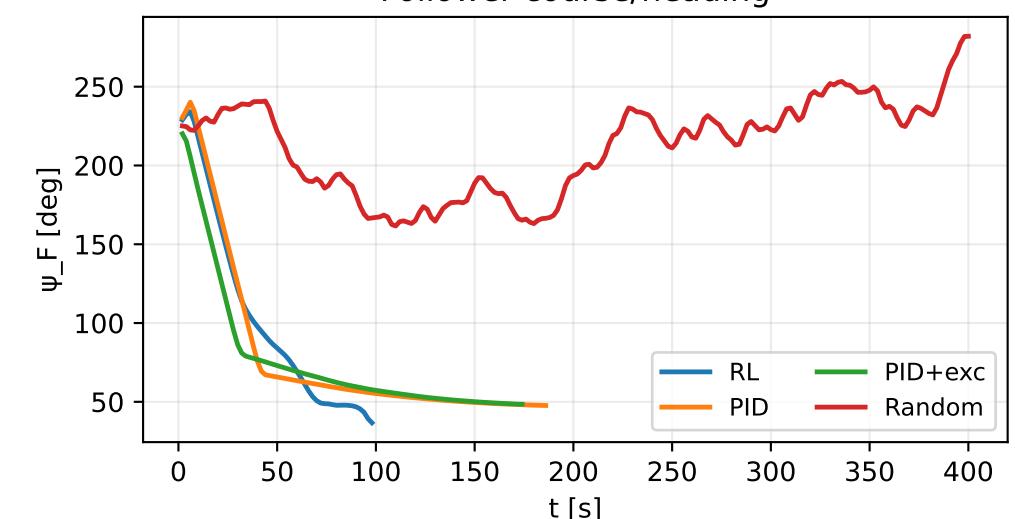
Information and excitation



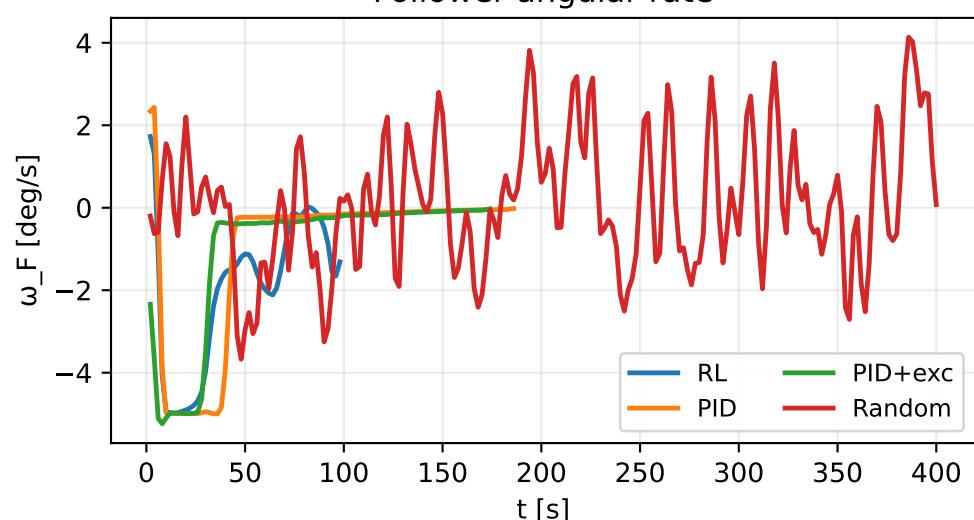
Follower speed



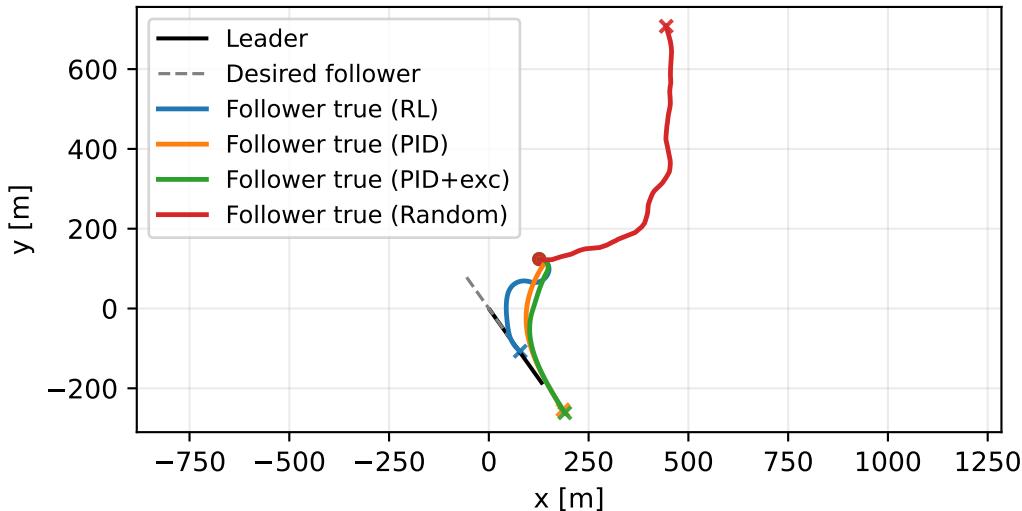
Follower course/heading



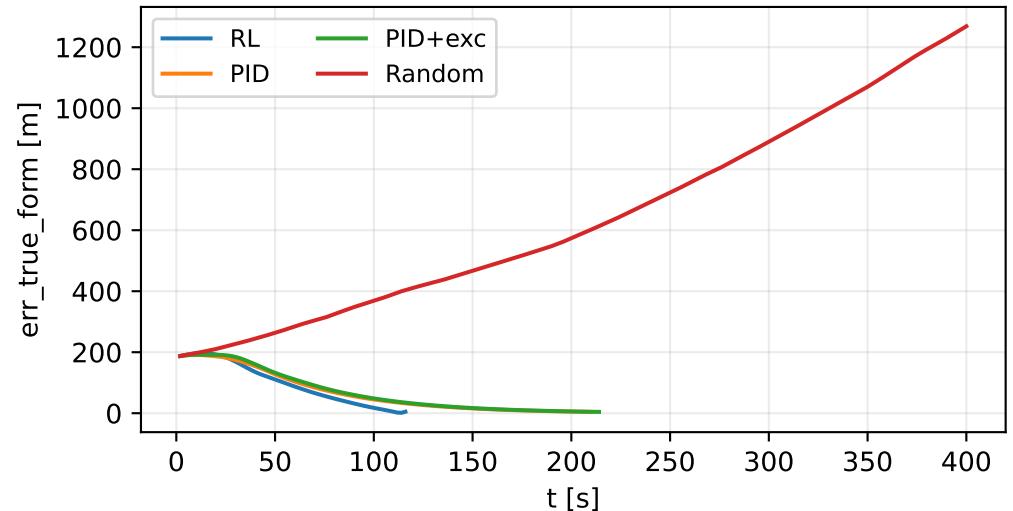
Follower angular rate



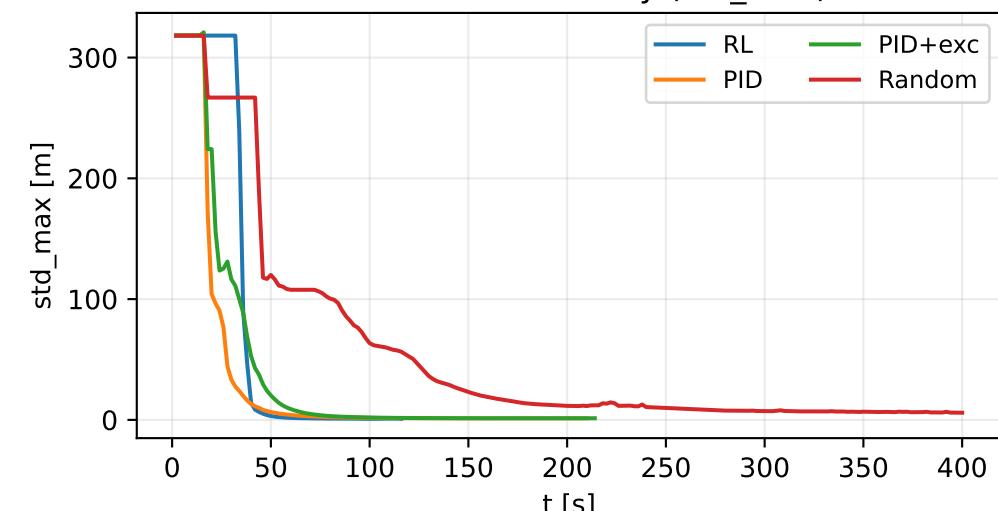
Trajectories (matched seed)



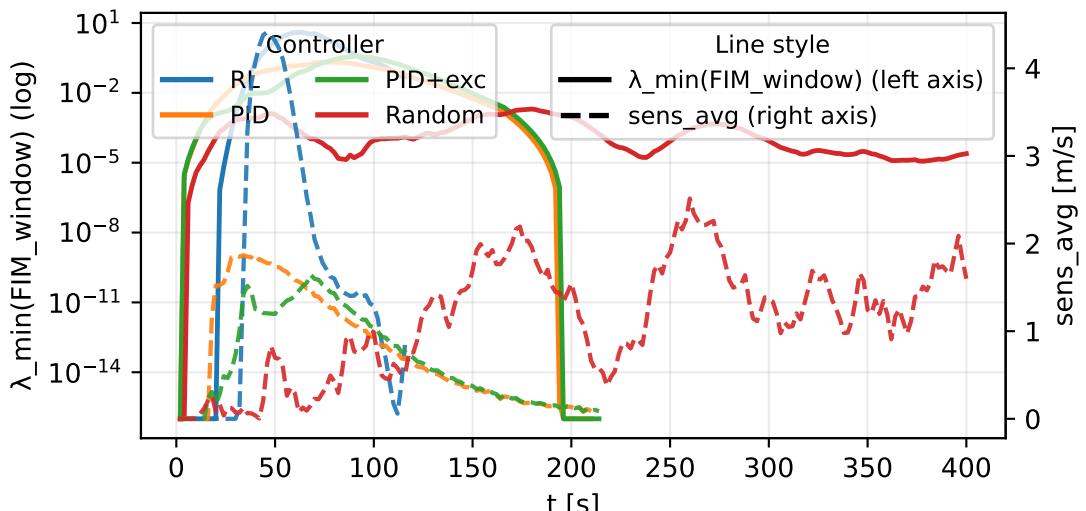
TRUE formation error



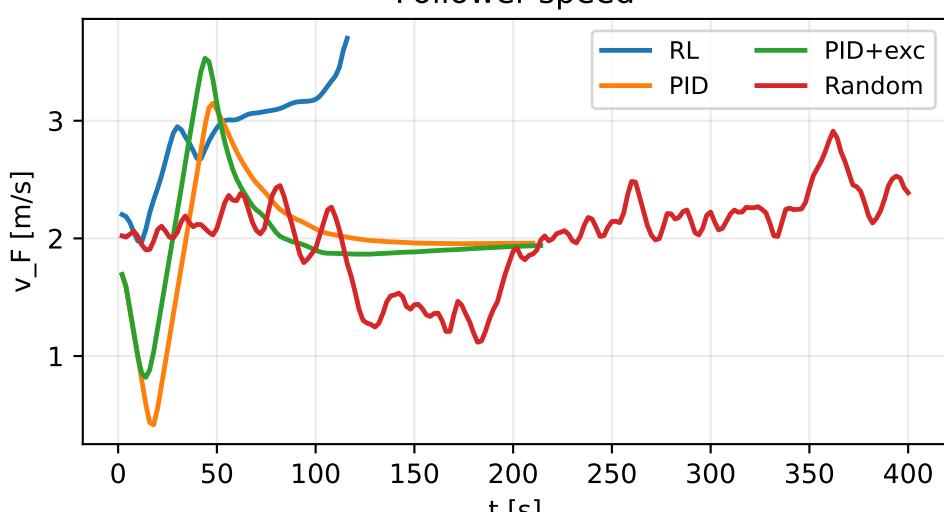
Estimator uncertainty (std_max)



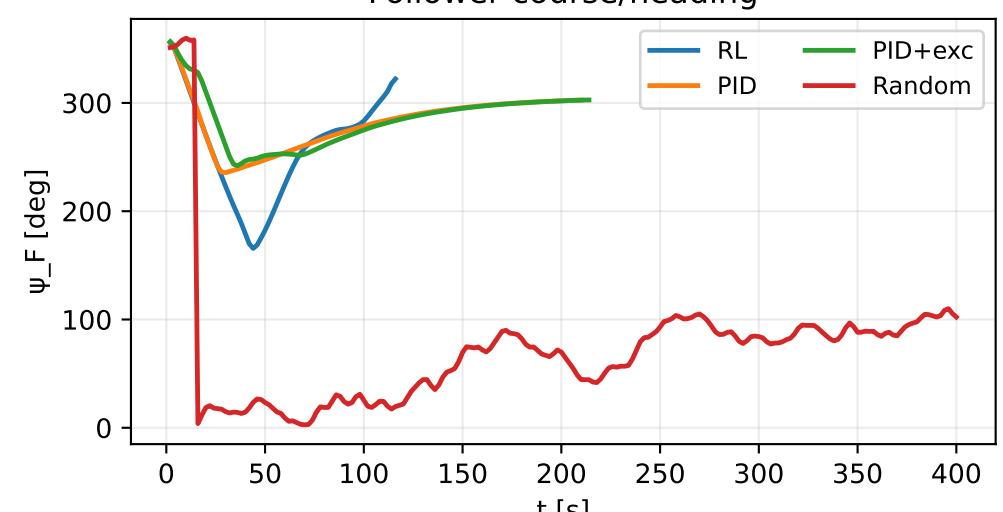
Information and excitation



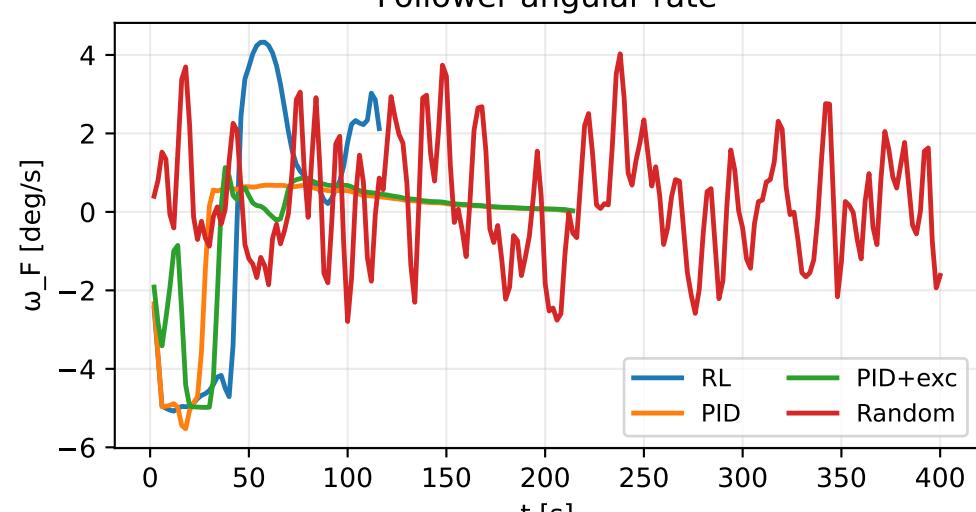
Follower speed



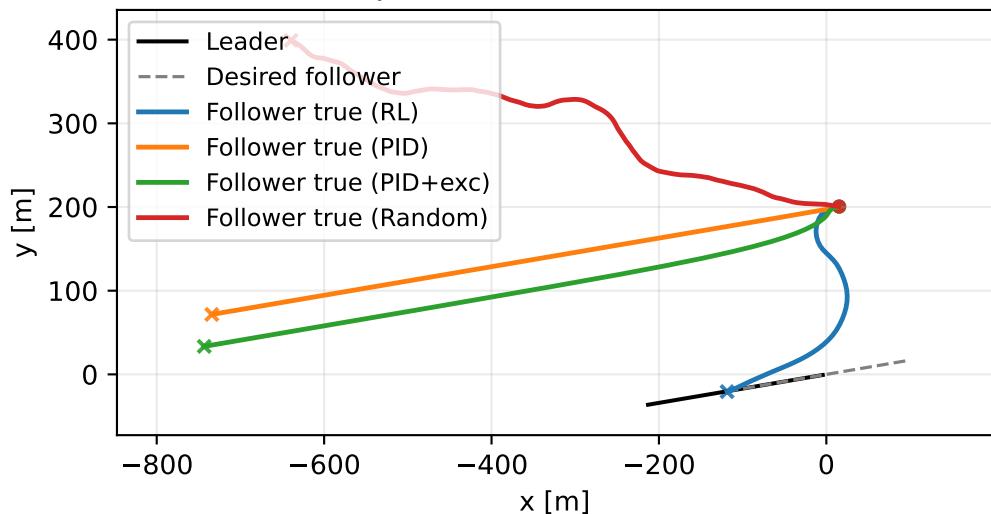
Follower course/heading



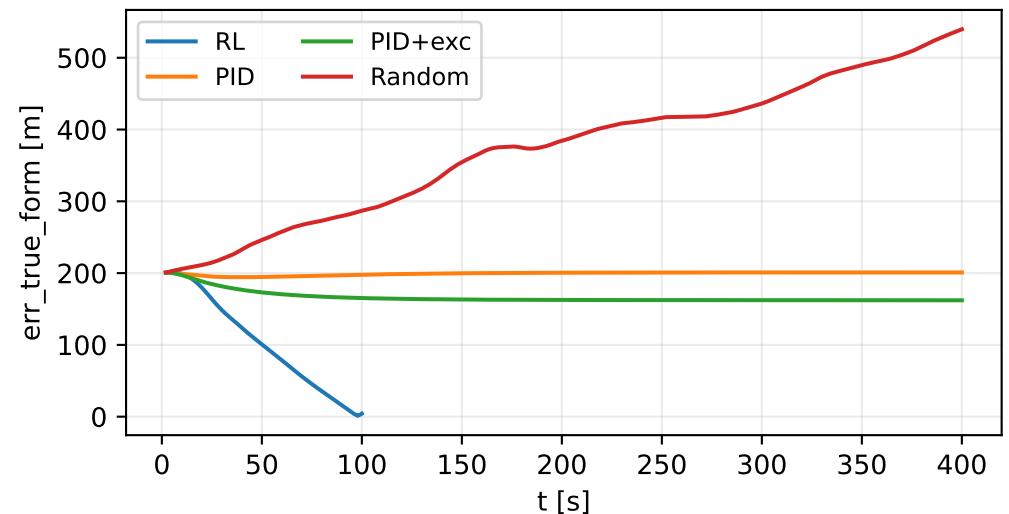
Follower angular rate



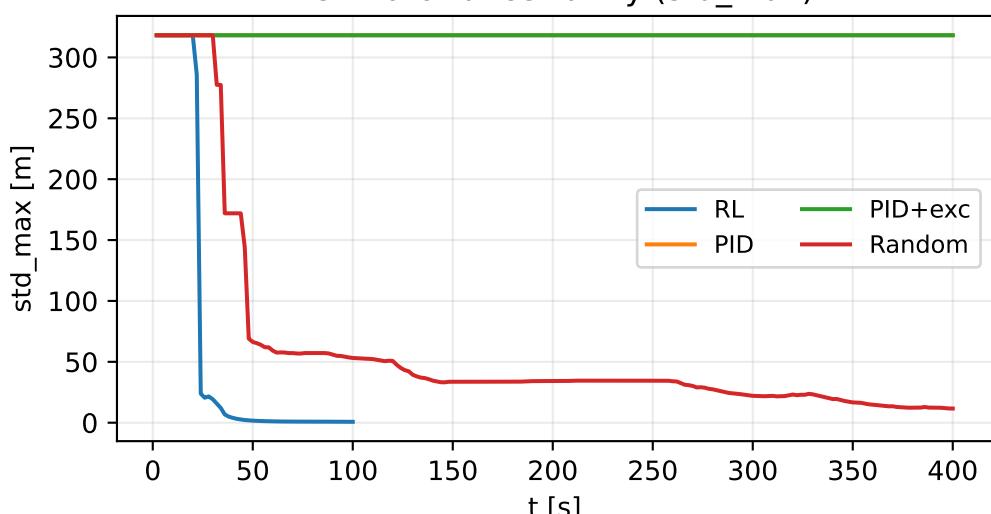
Trajectories (matched seed)



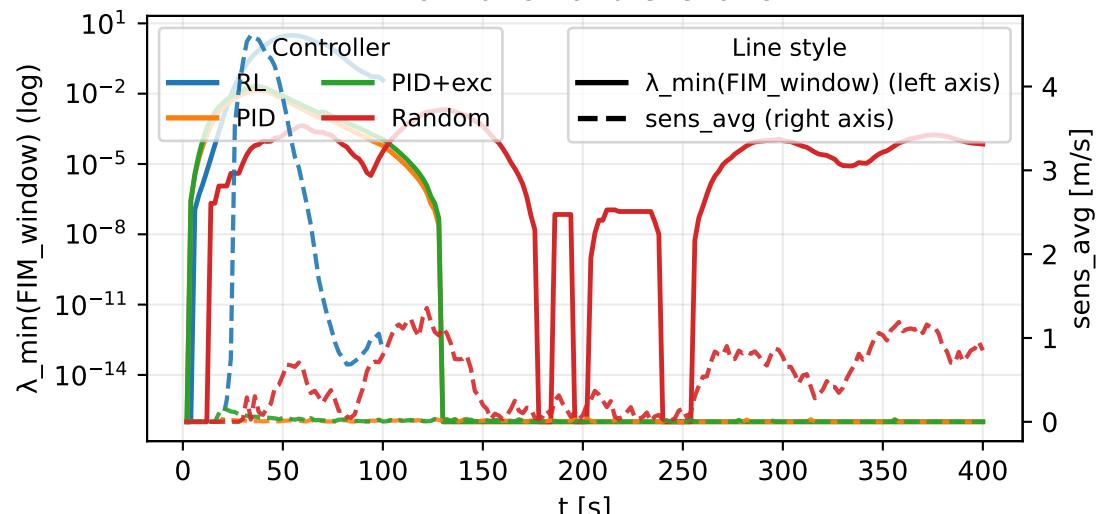
TRUE formation error



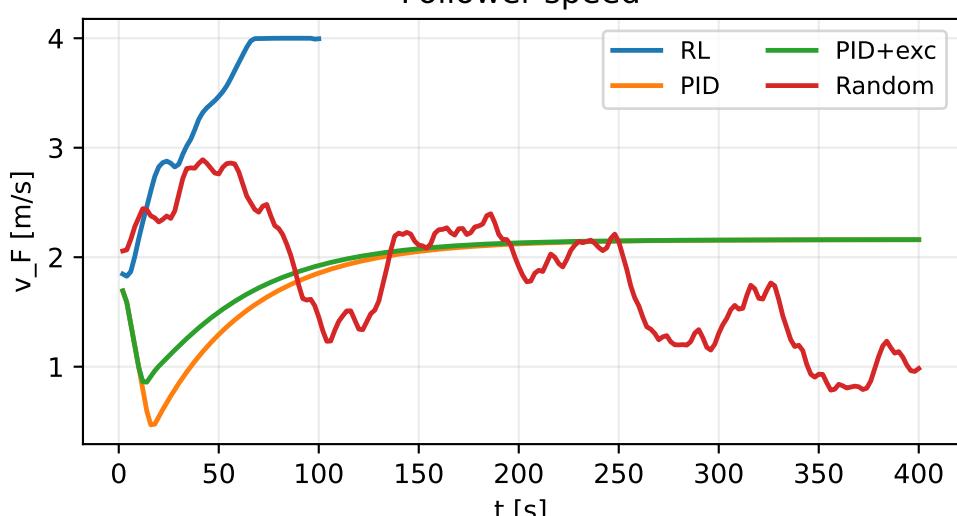
Estimator uncertainty (std_max)



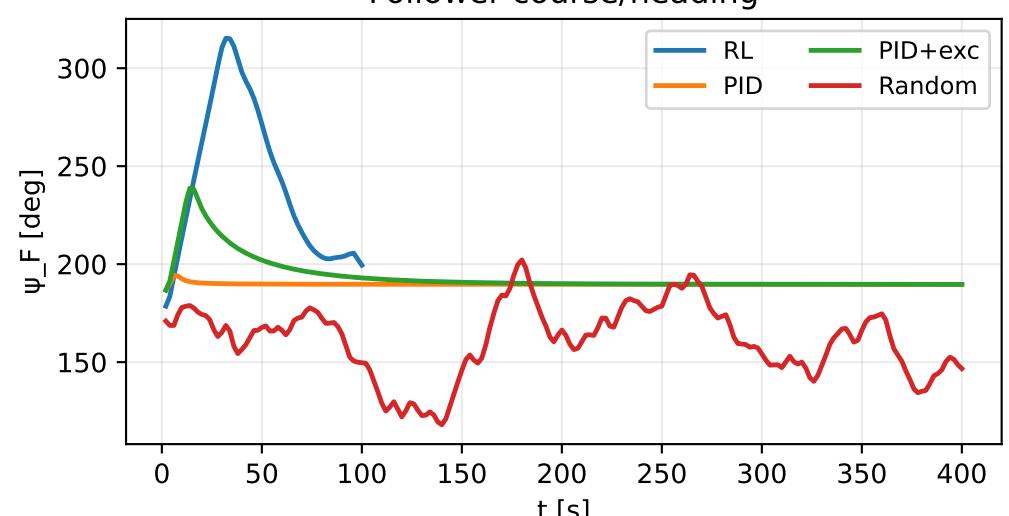
Information and excitation



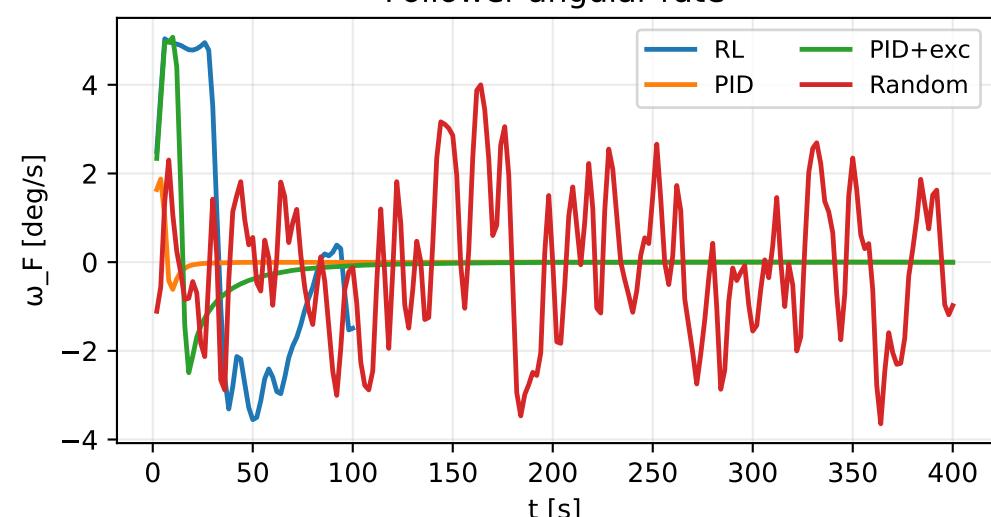
Follower speed



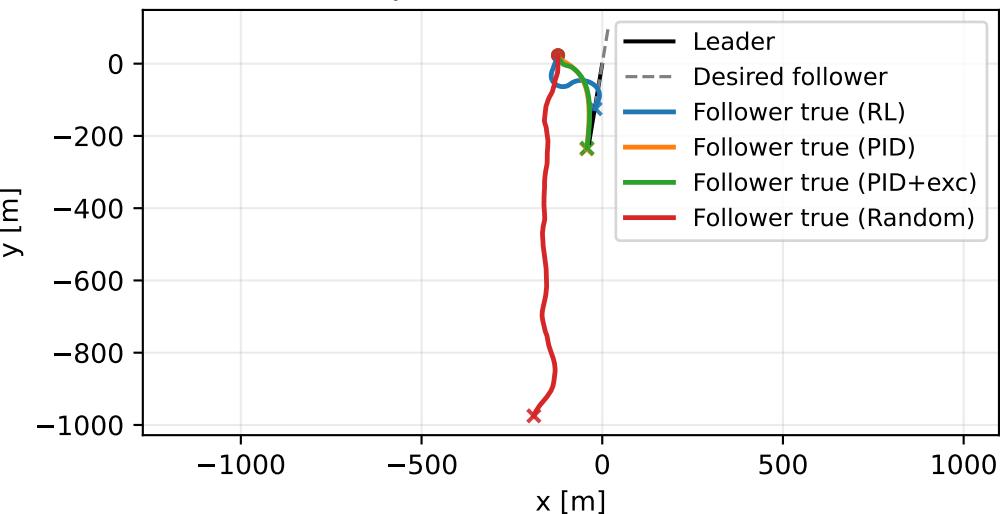
Follower course/heading



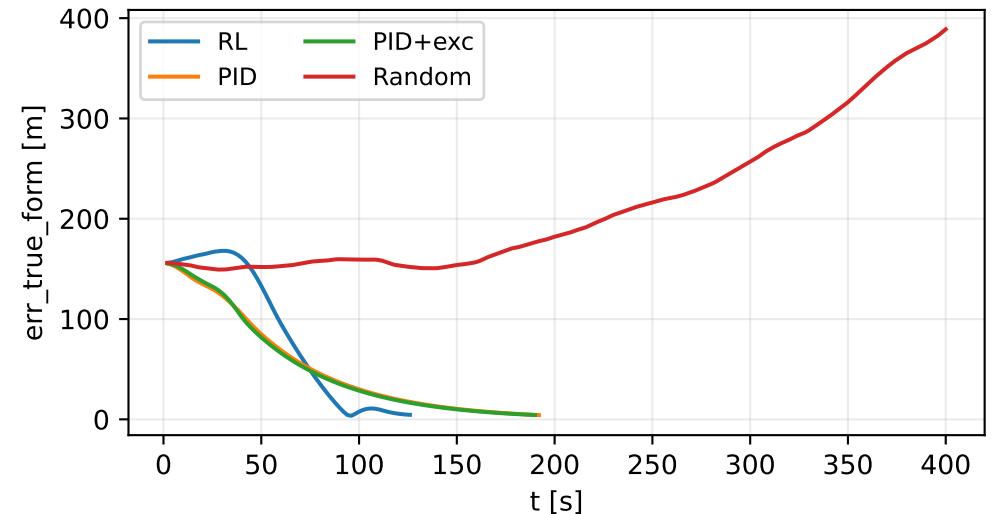
Follower angular rate



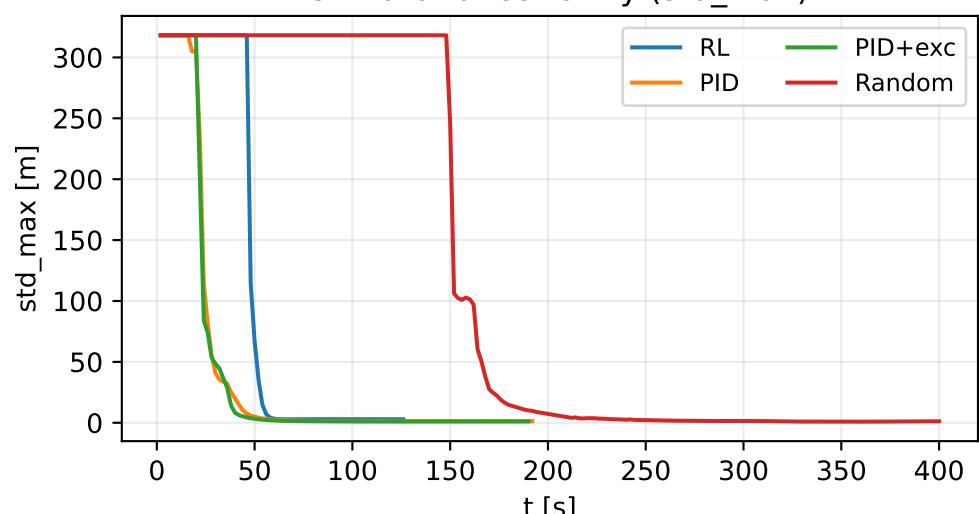
Trajectories (matched seed)



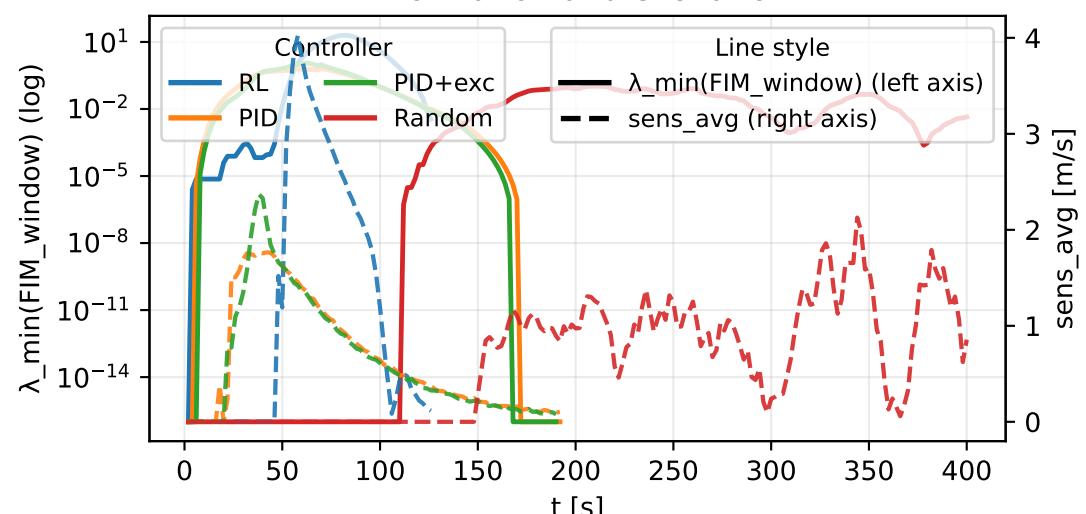
TRUE formation error



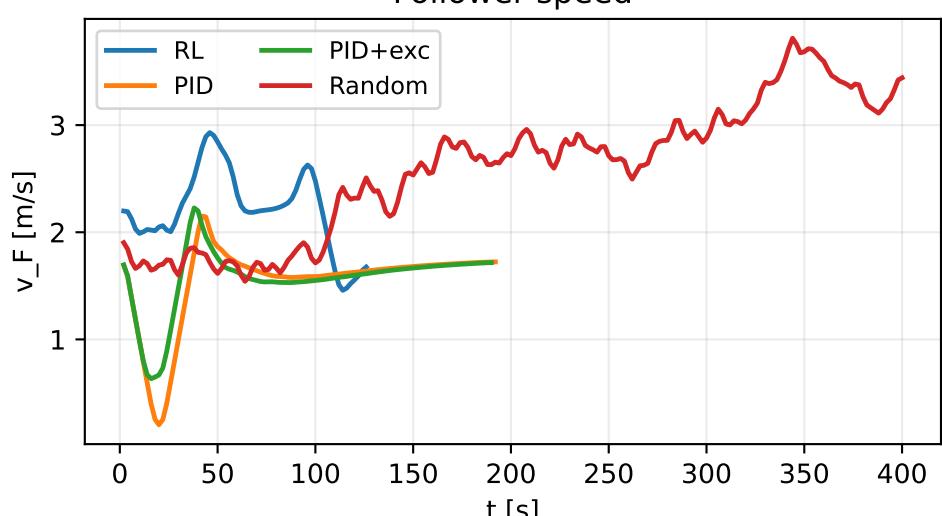
Estimator uncertainty (std_max)



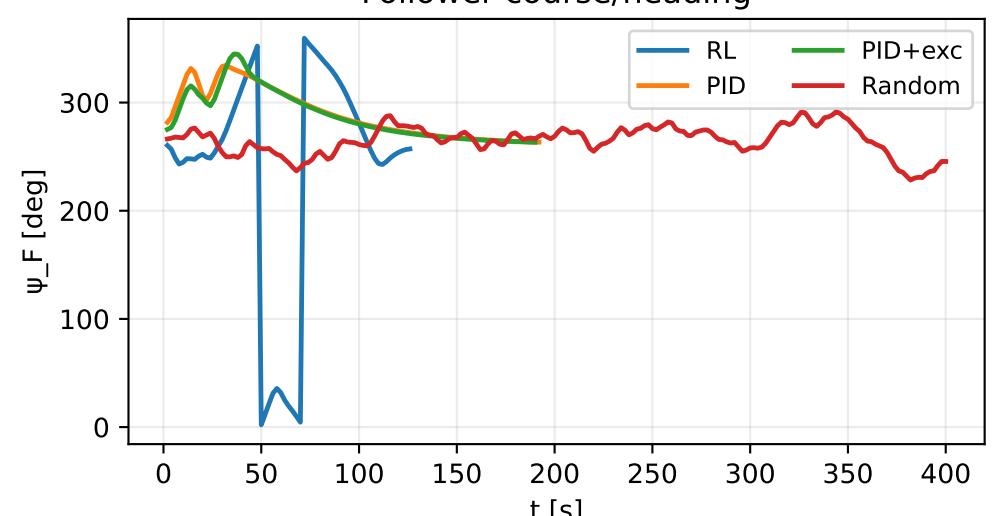
Information and excitation



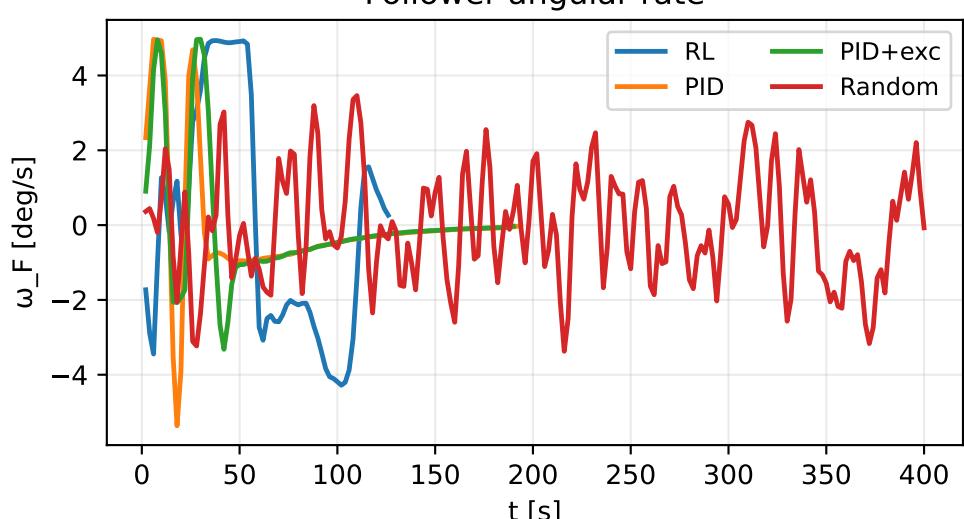
Follower speed



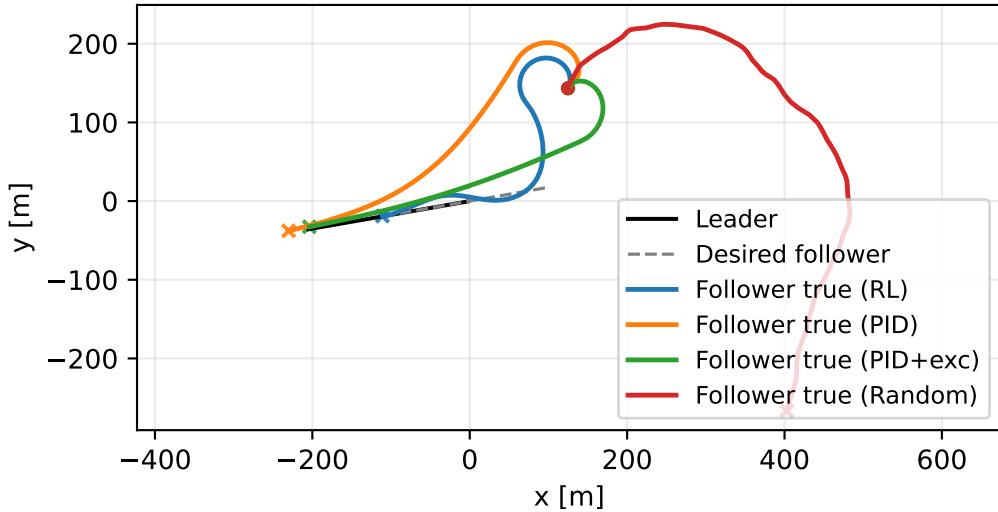
Follower course/heading



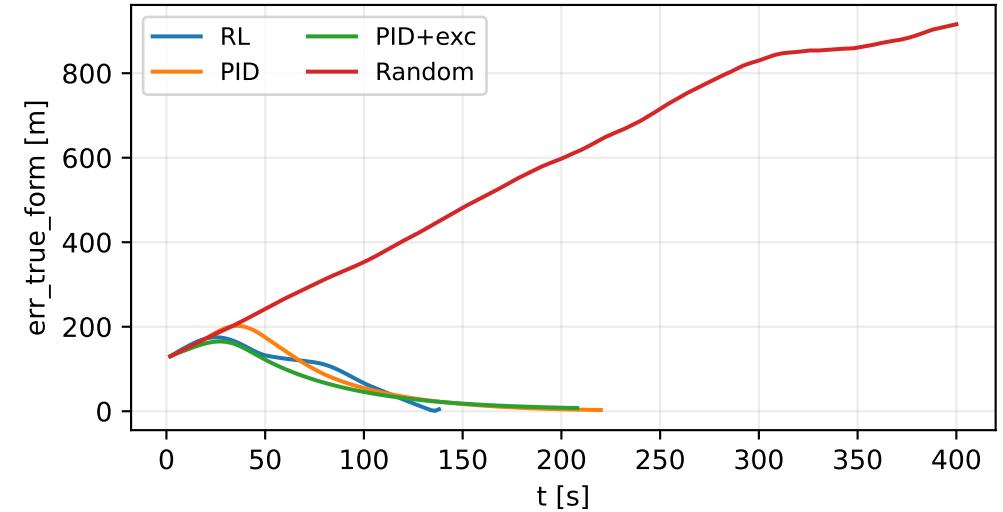
Follower angular rate



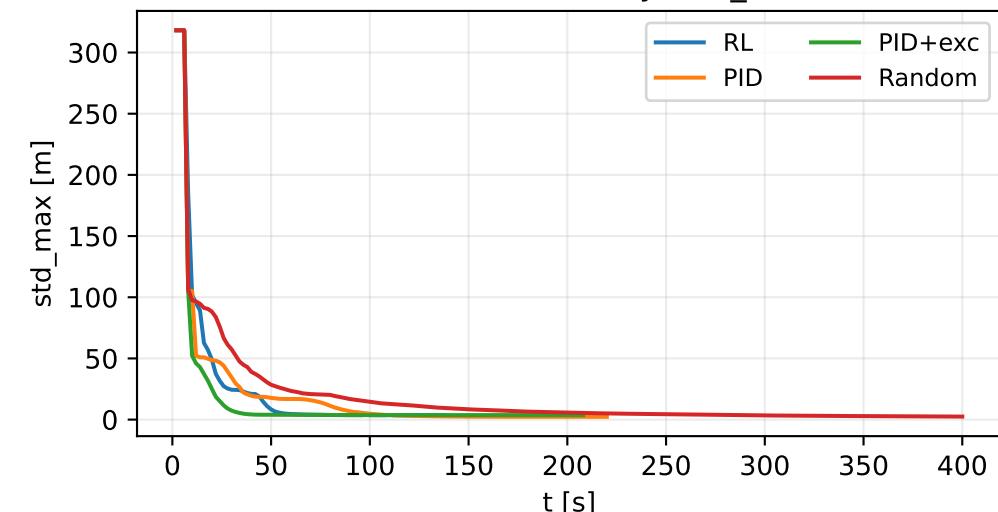
Trajectories (matched seed)



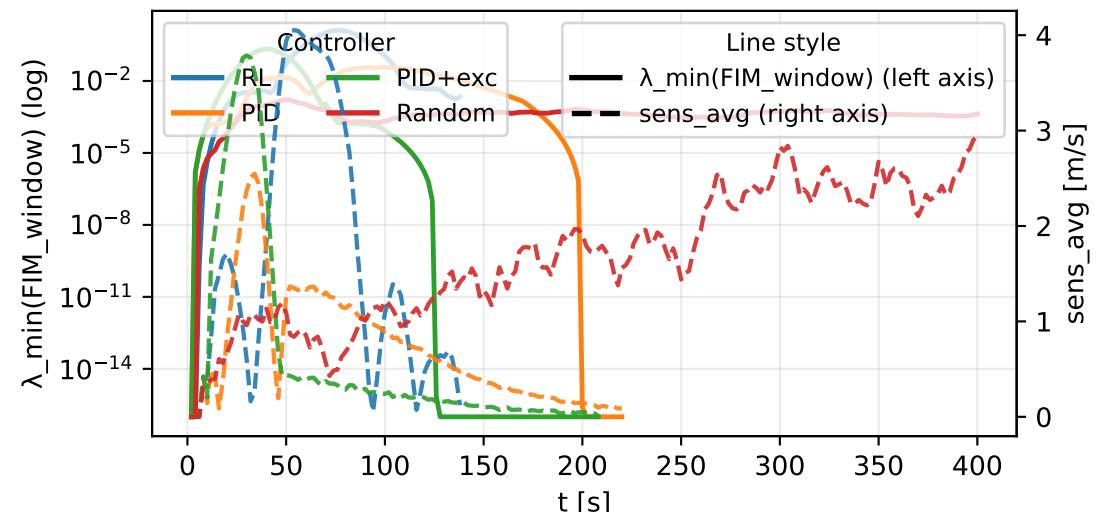
TRUE formation error



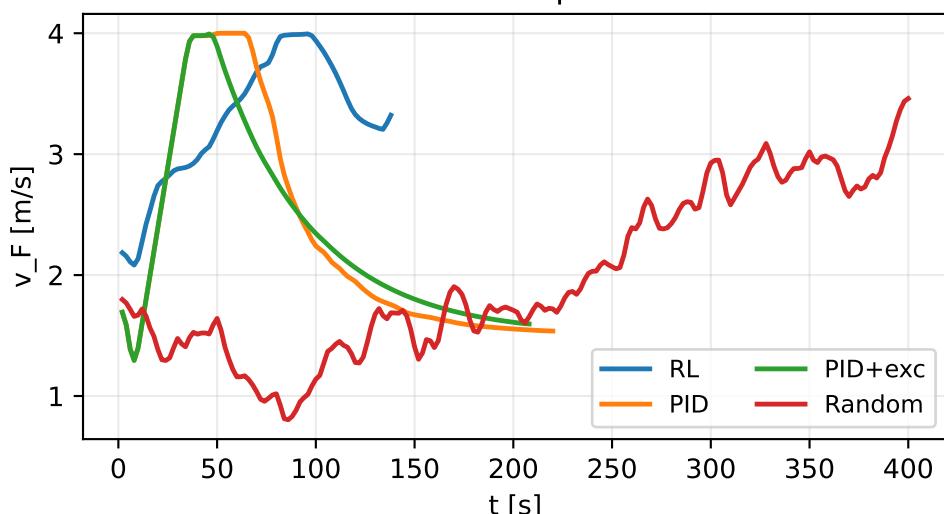
Estimator uncertainty (std_max)



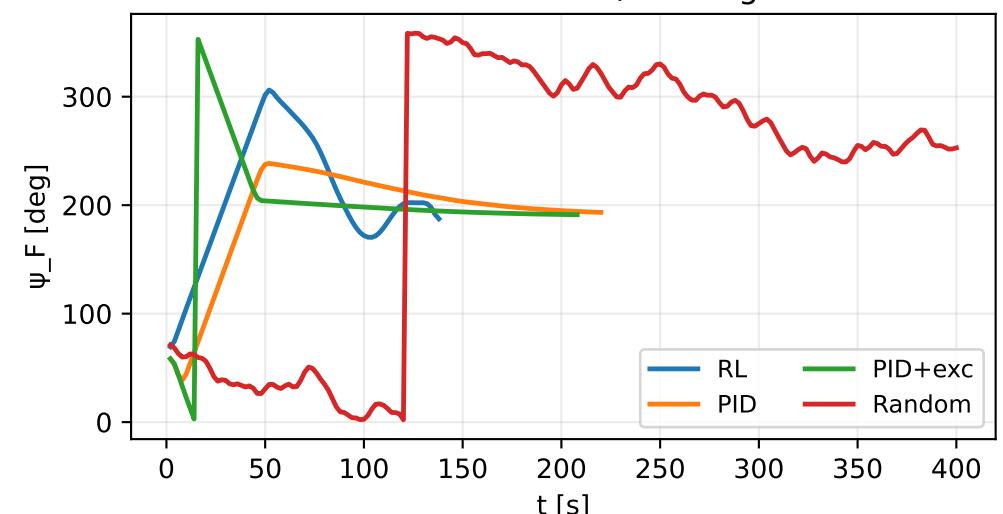
Information and excitation



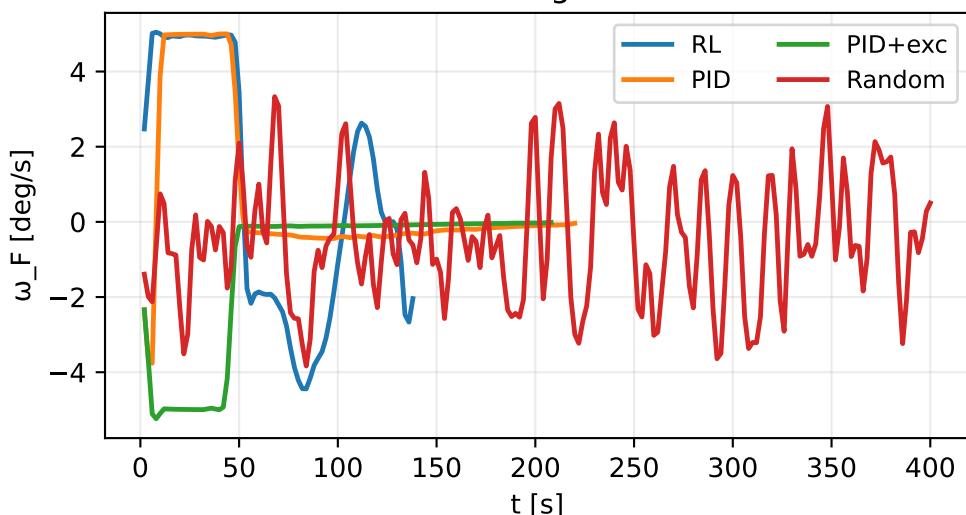
Follower speed



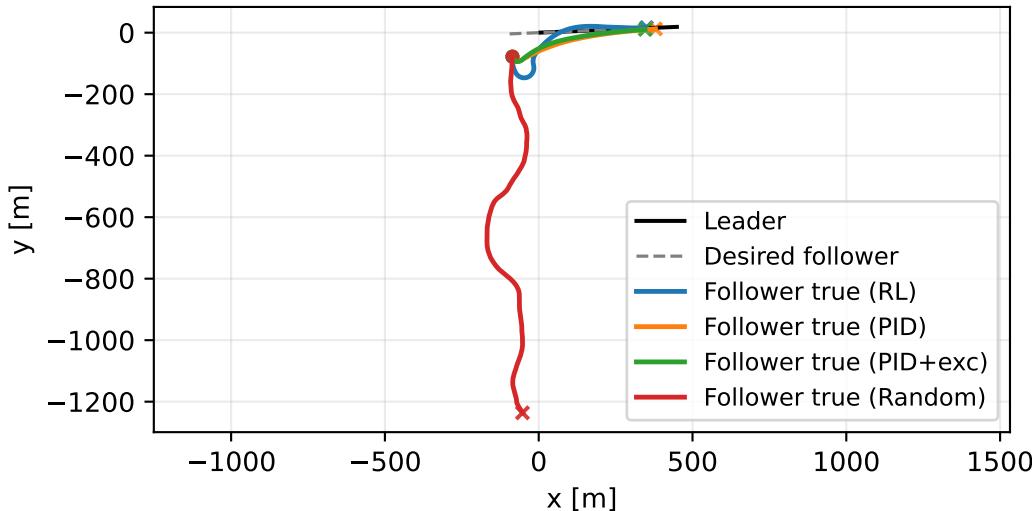
Follower course/heading



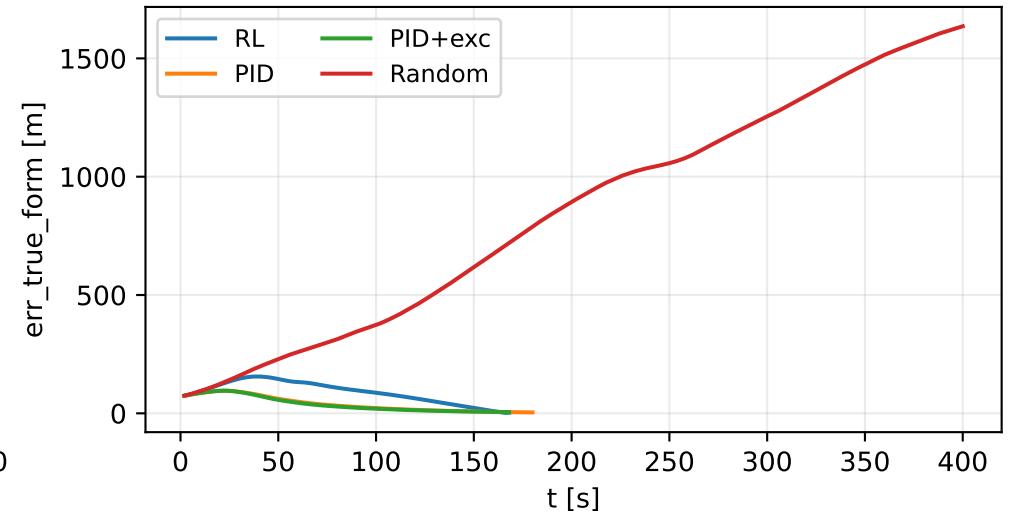
Follower angular rate



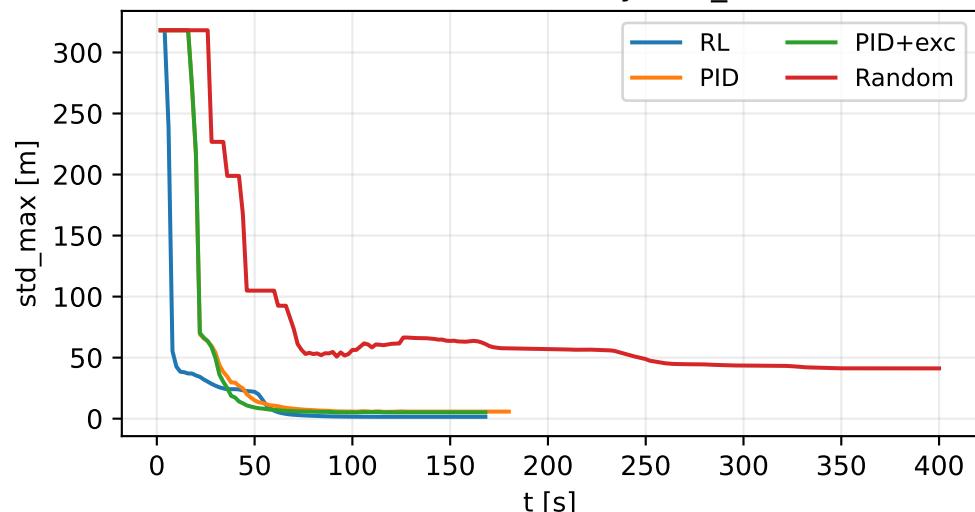
Trajectories (matched seed)



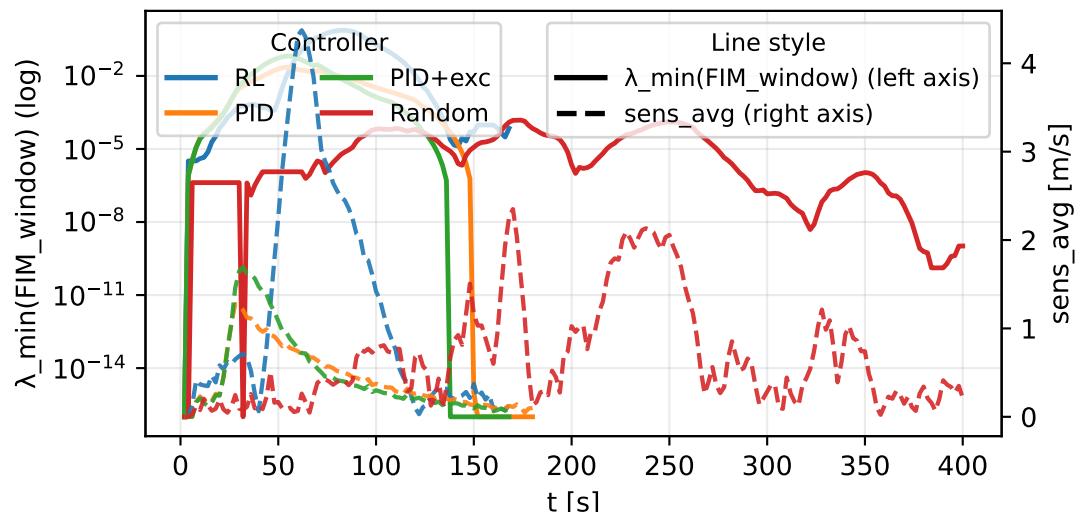
TRUE formation error



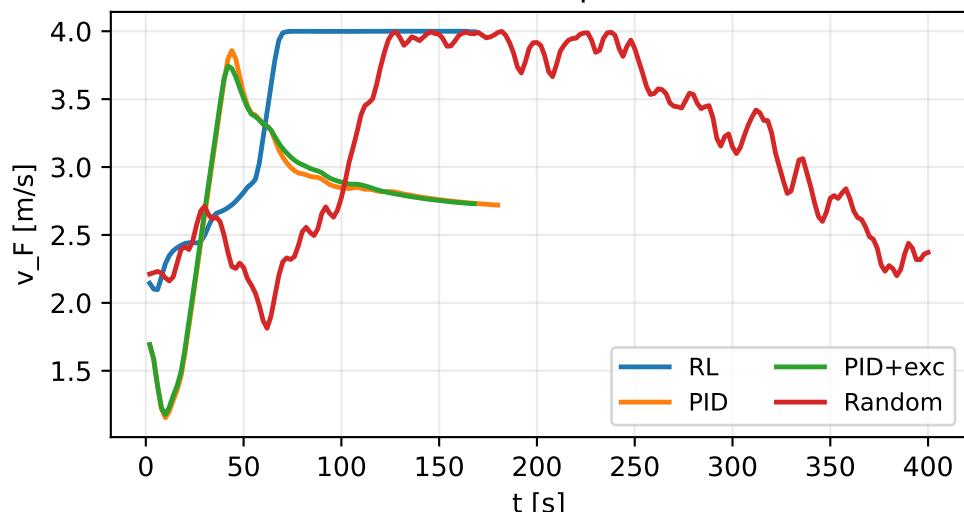
Estimator uncertainty (std_max)



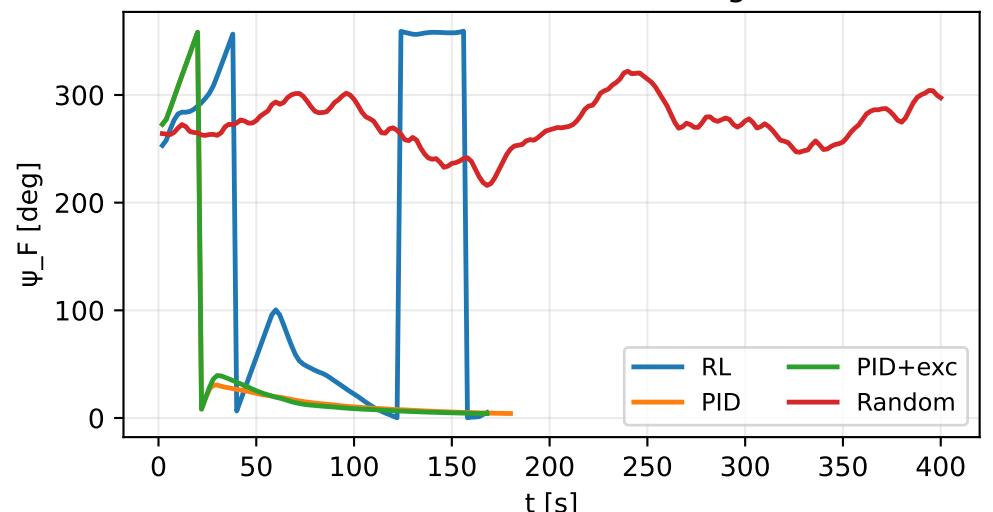
Information and excitation



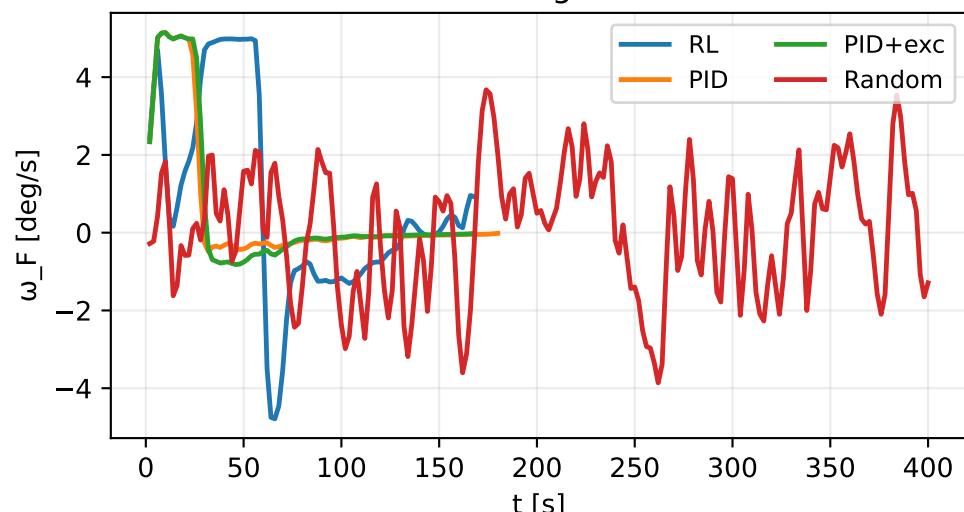
Follower speed



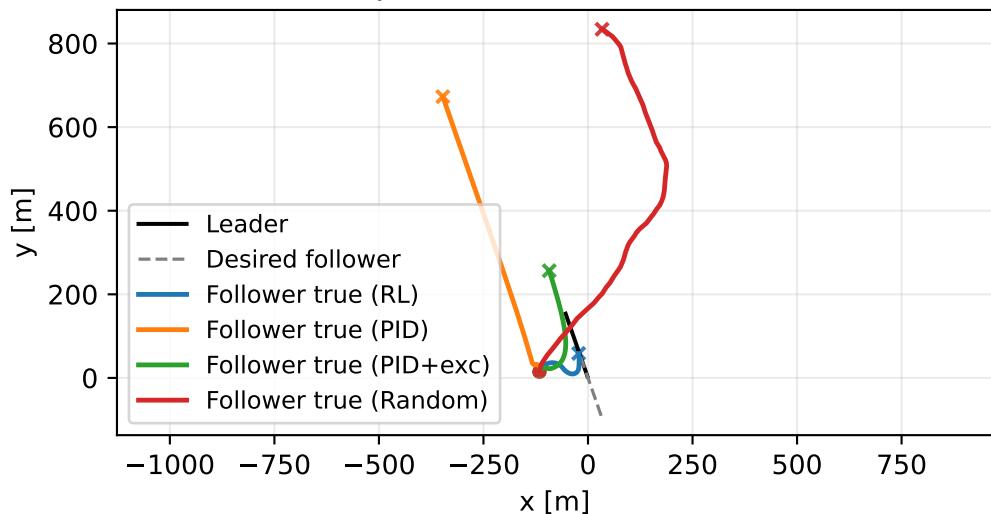
Follower course/heading



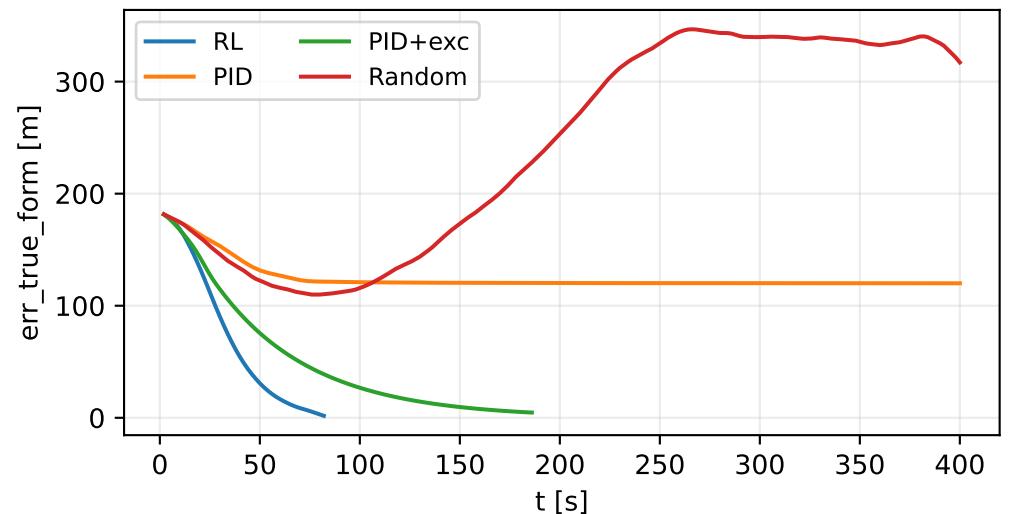
Follower angular rate



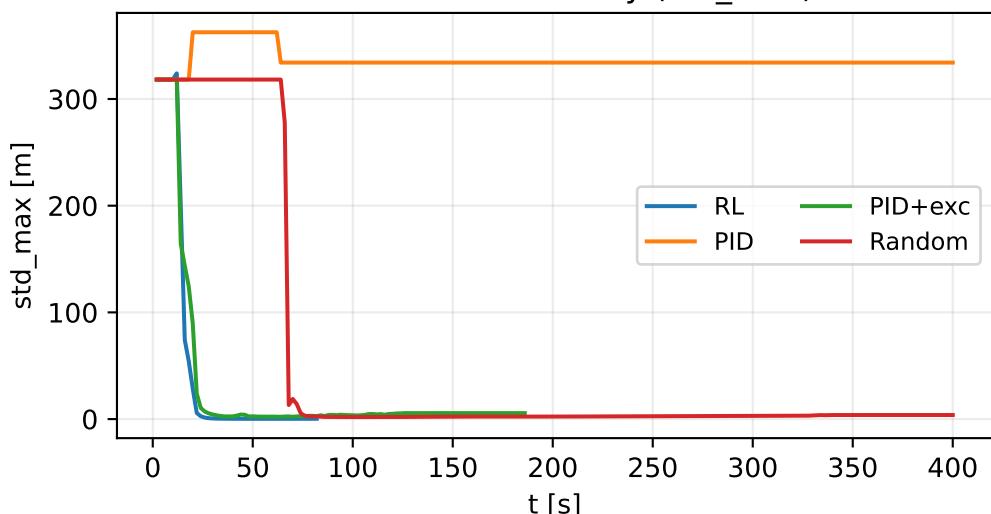
Trajectories (matched seed)



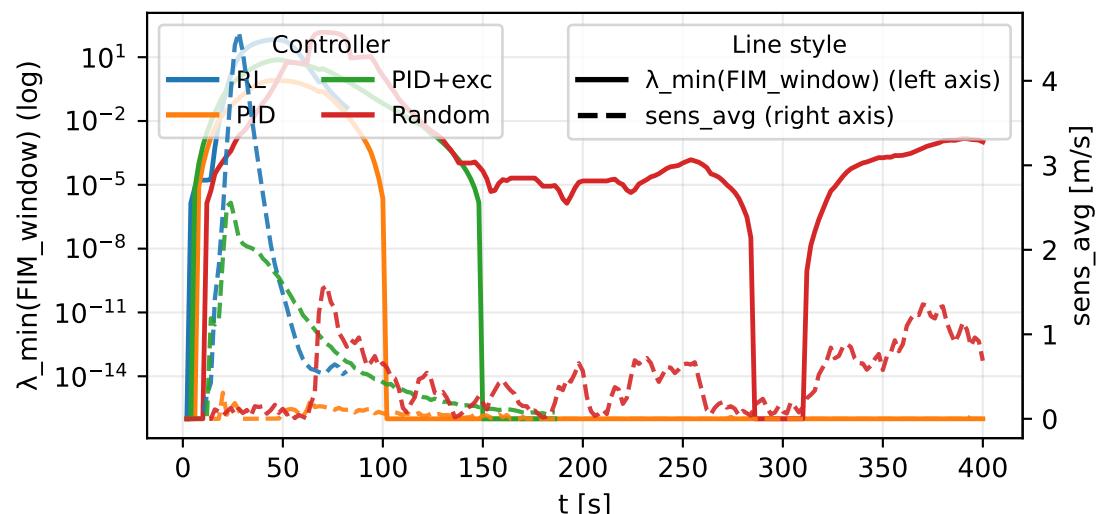
TRUE formation error



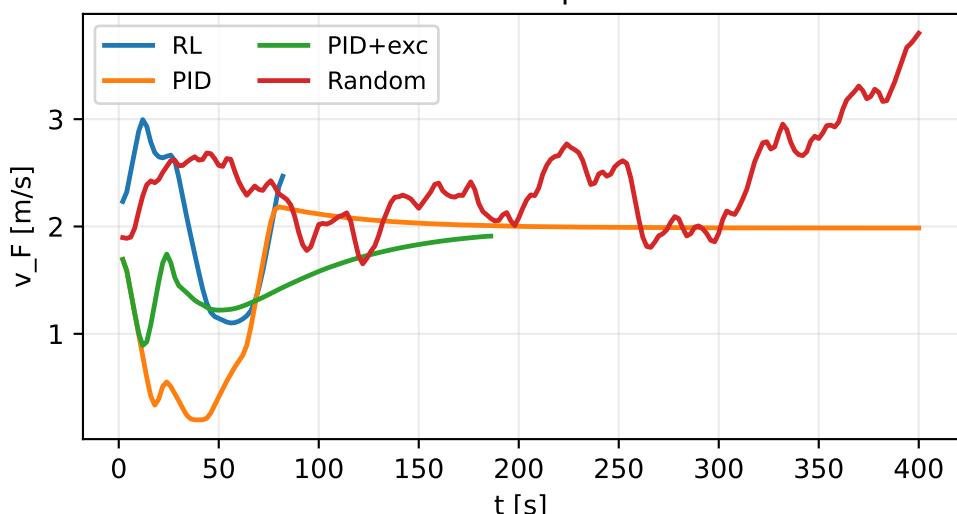
Estimator uncertainty (std_max)



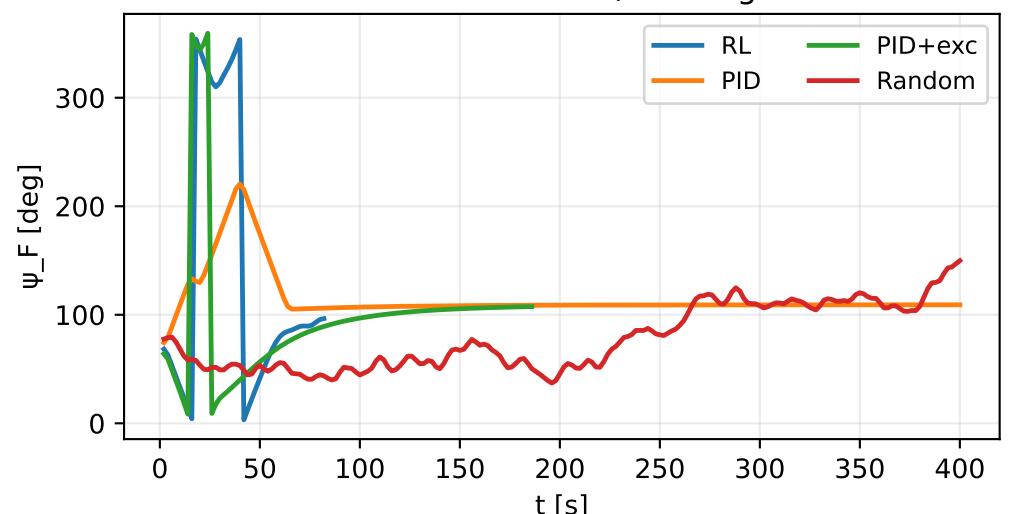
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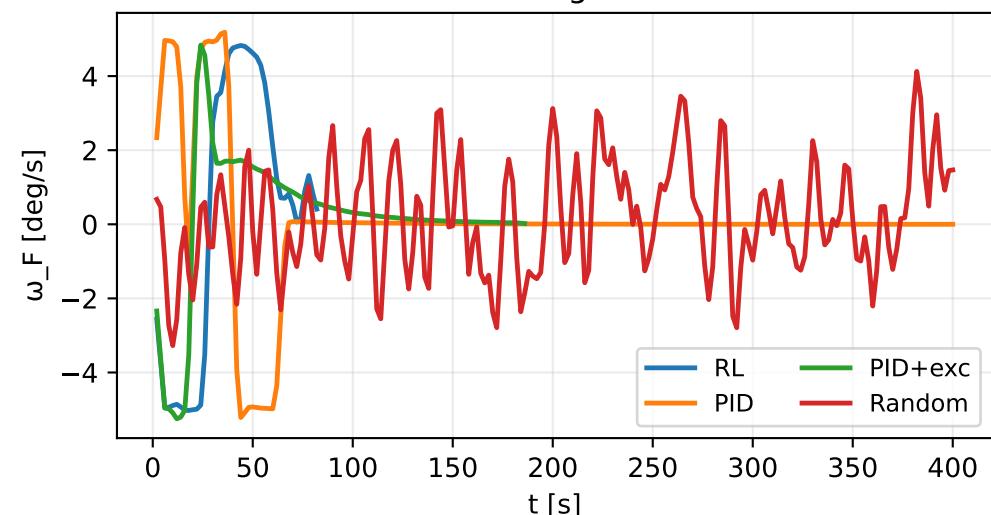
Follower speed



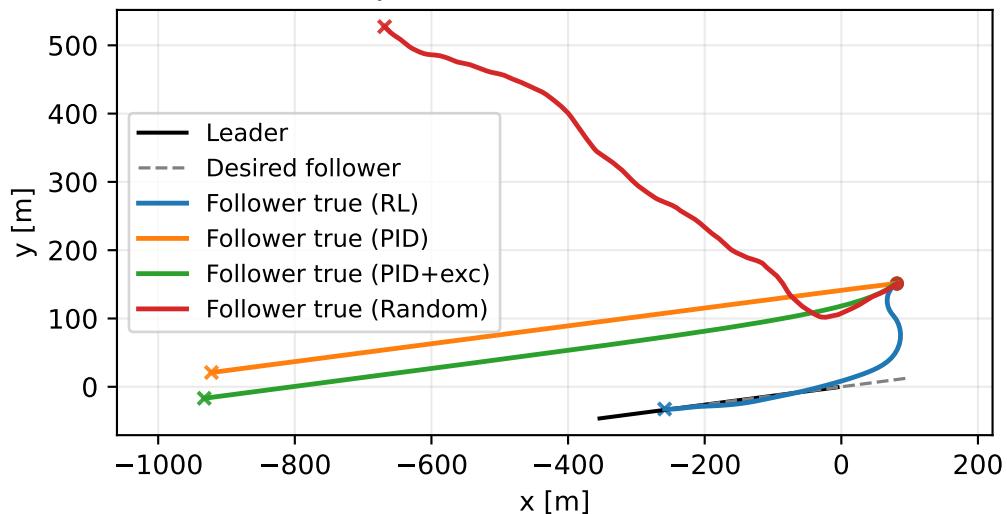
Follower course/heading



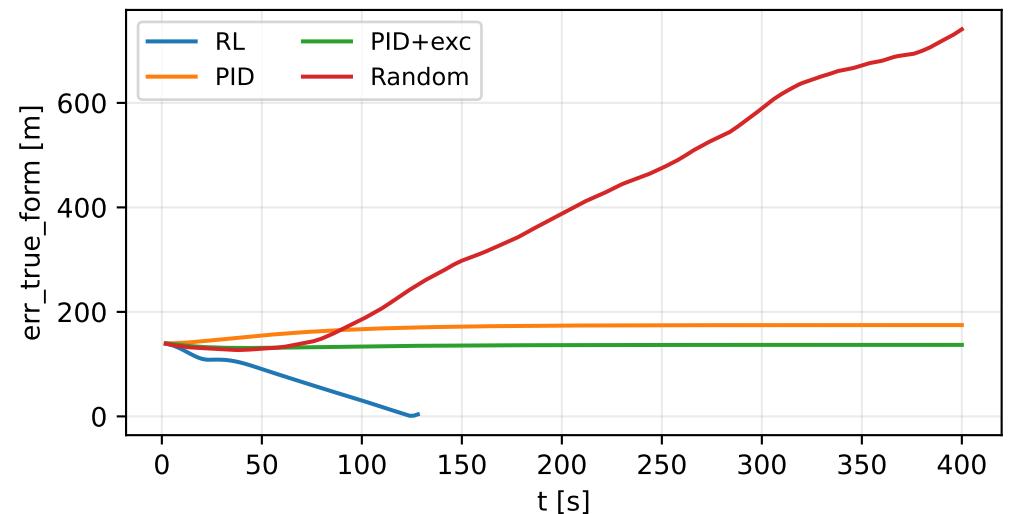
Follower angular rate



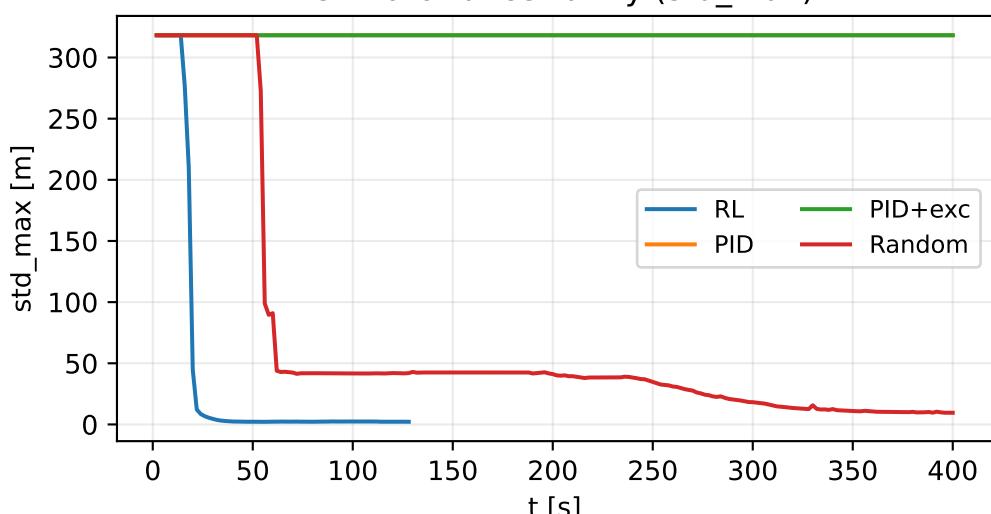
Trajectories (matched seed)



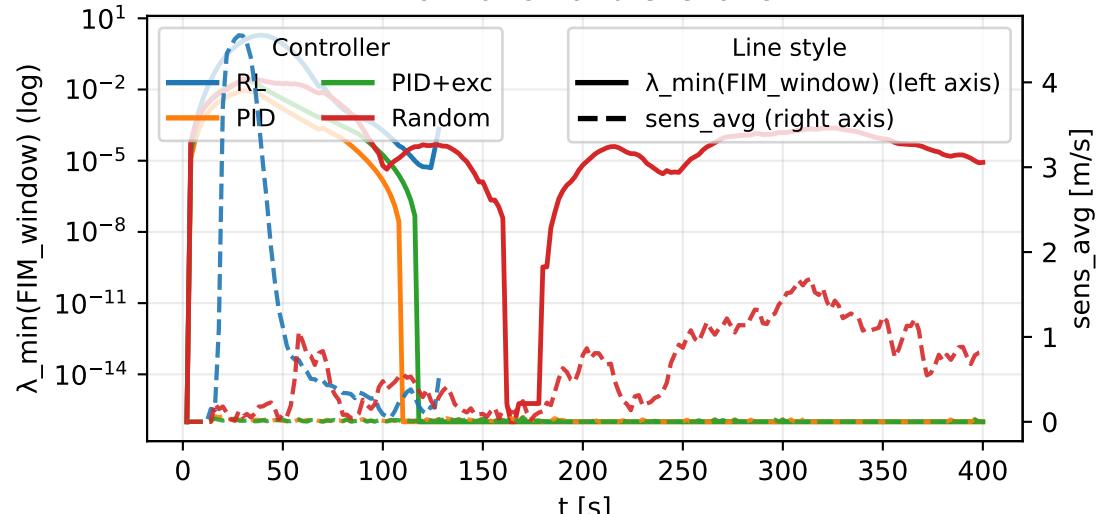
TRUE formation error



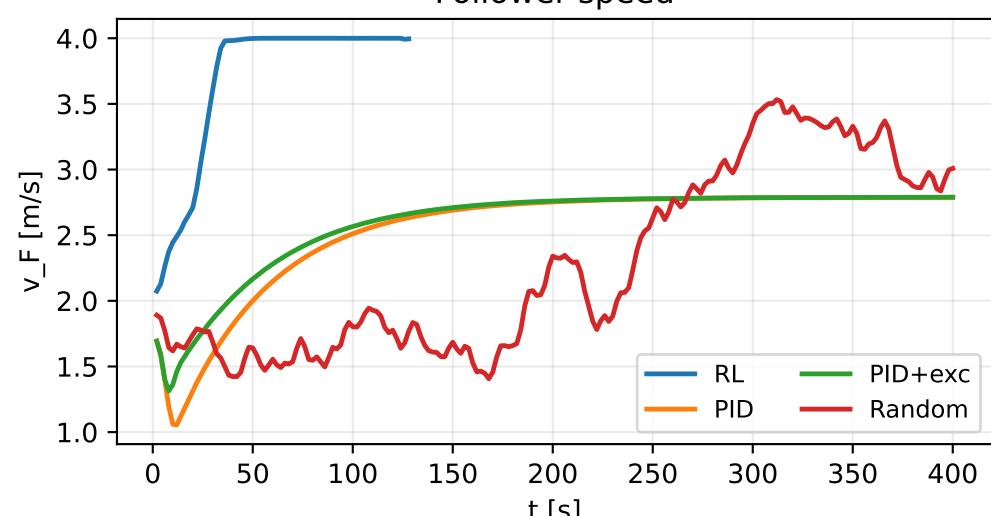
Estimator uncertainty (std_max)



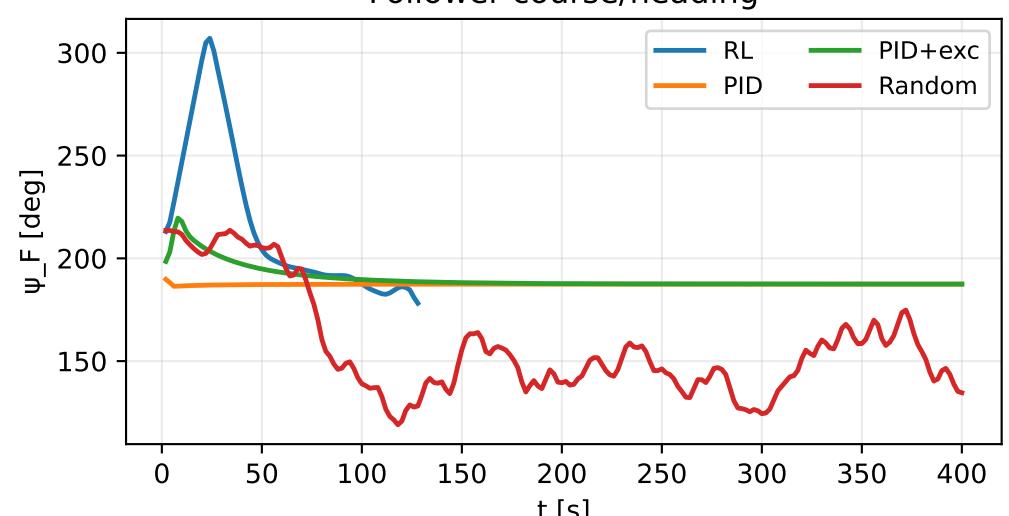
Information and excitation



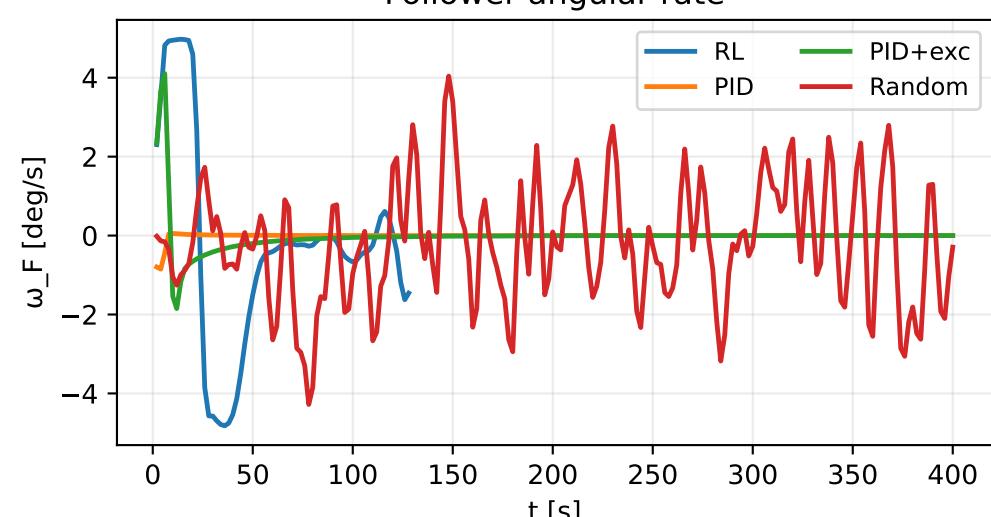
Follower speed



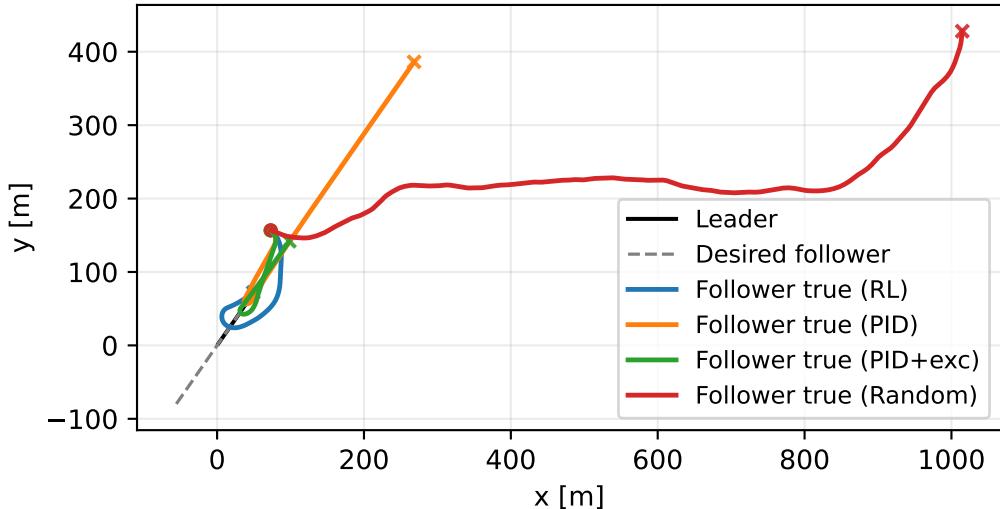
Follower course/heading



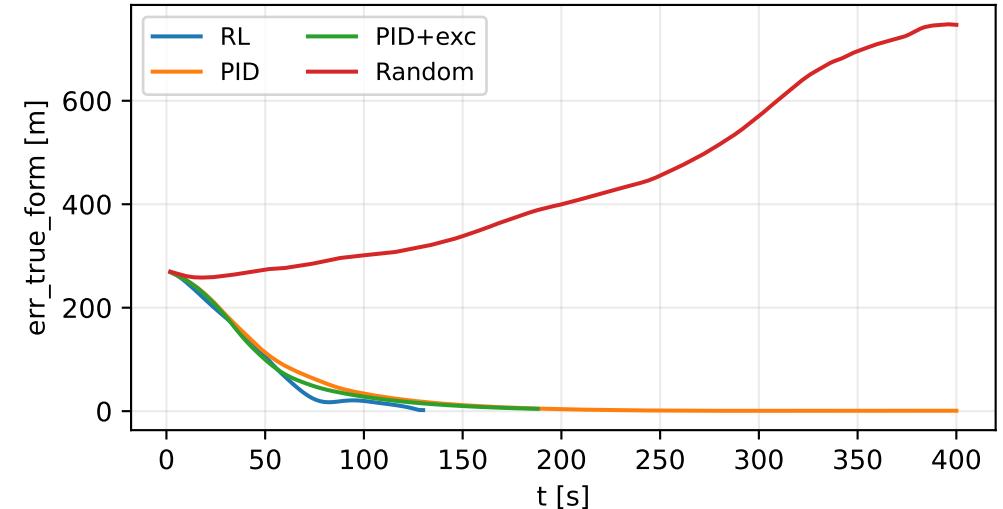
Follower angular rate



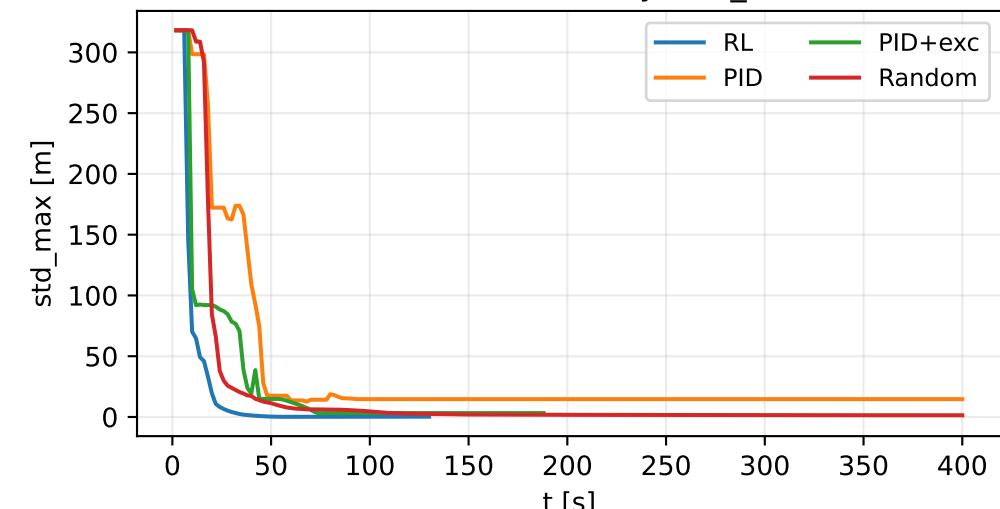
Trajectories (matched seed)



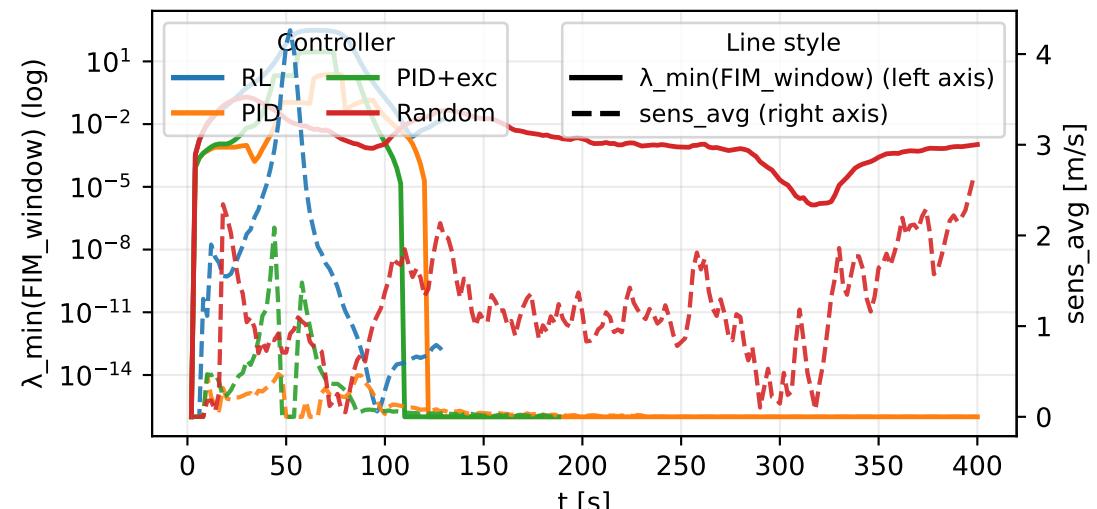
TRUE formation error



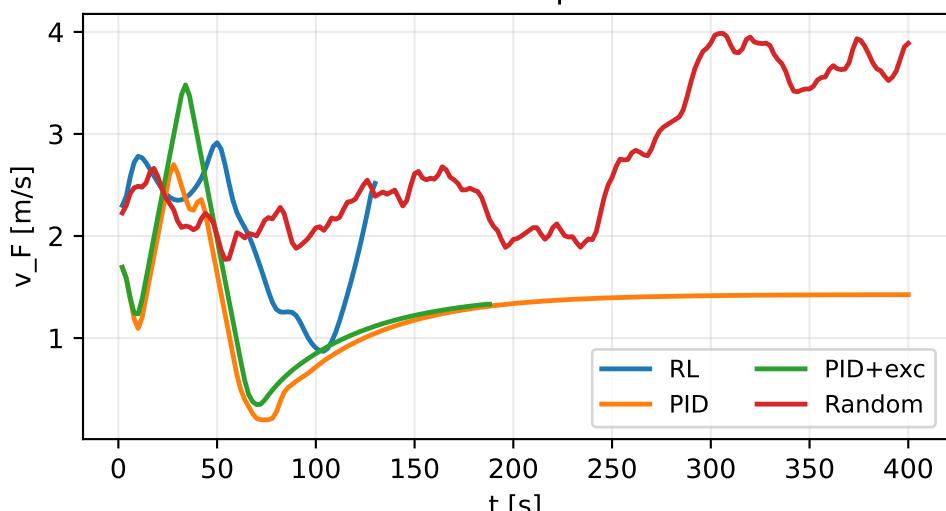
Estimator uncertainty (std_max)



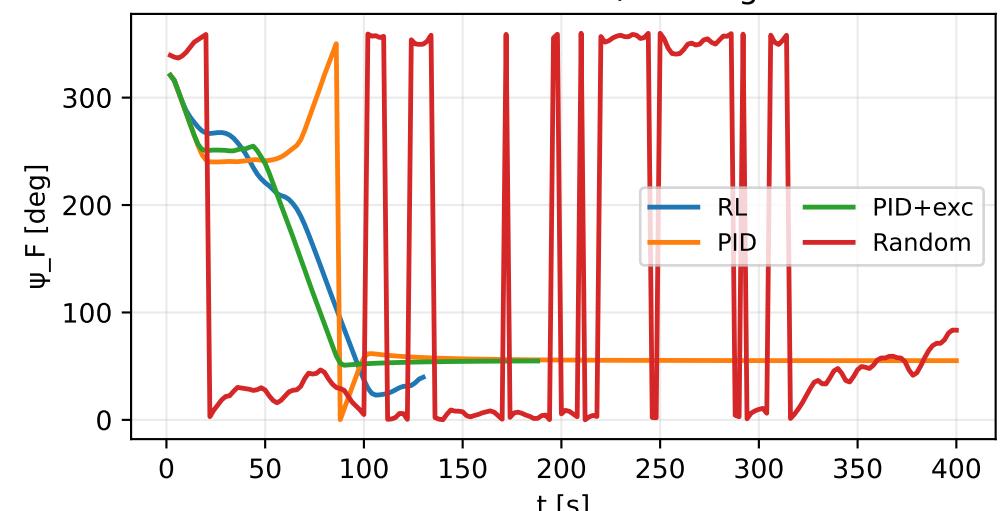
Information and excitation



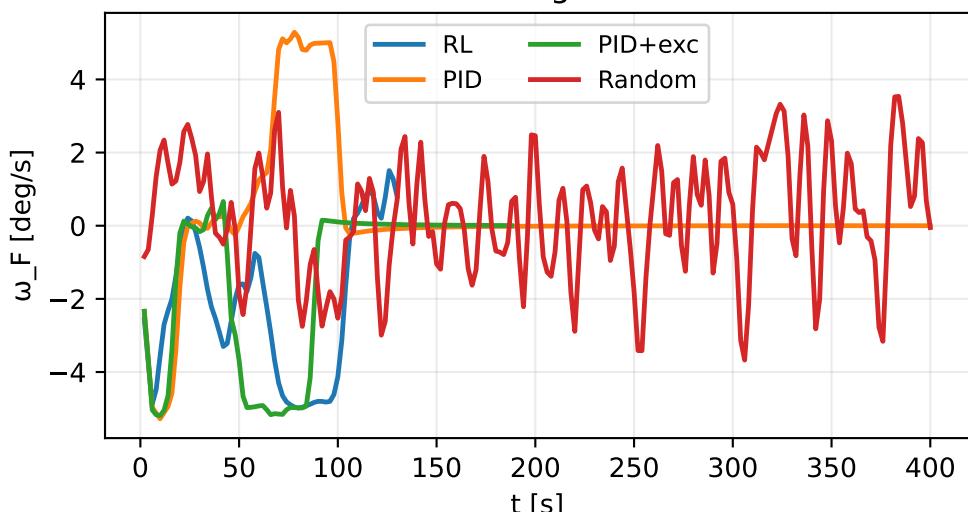
Follower speed



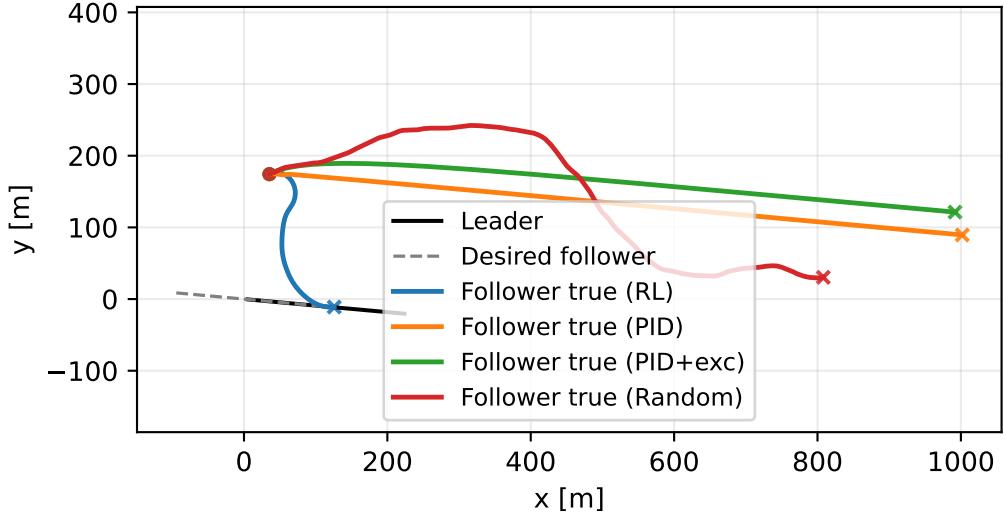
Follower course/heading



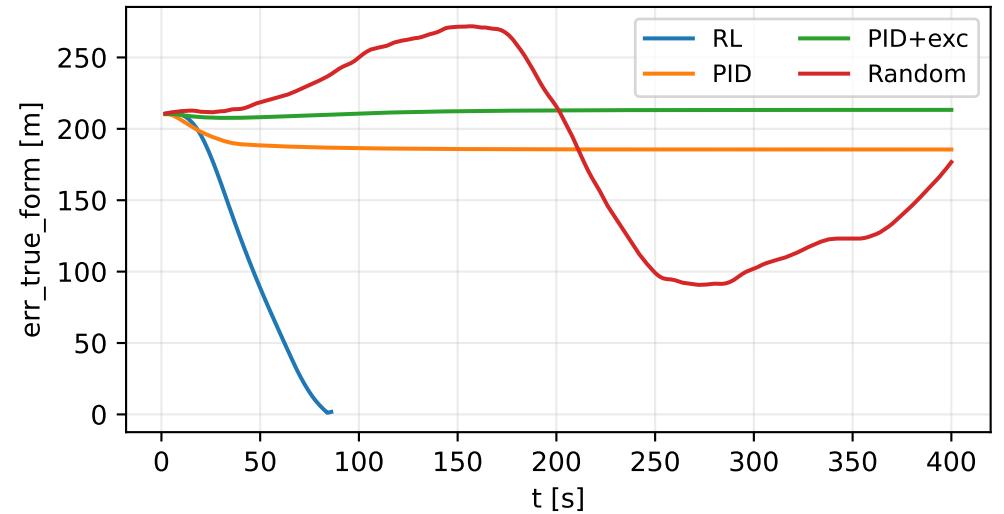
Follower angular rate



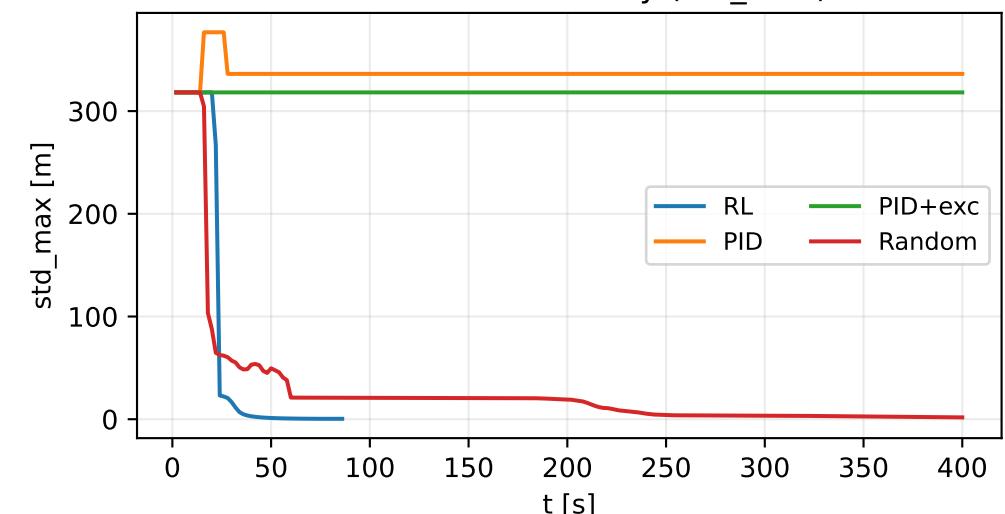
Trajectories (matched seed)



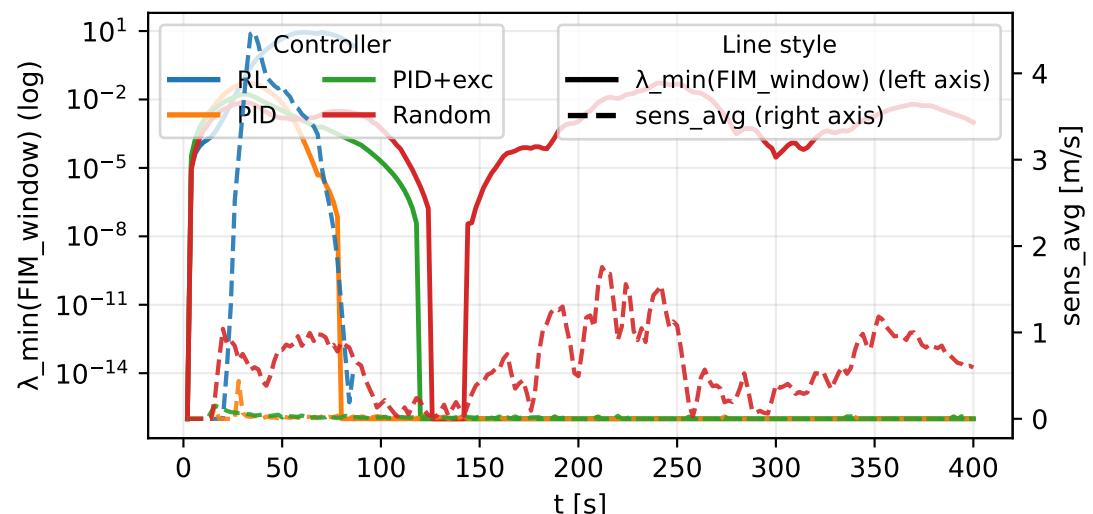
TRUE formation error



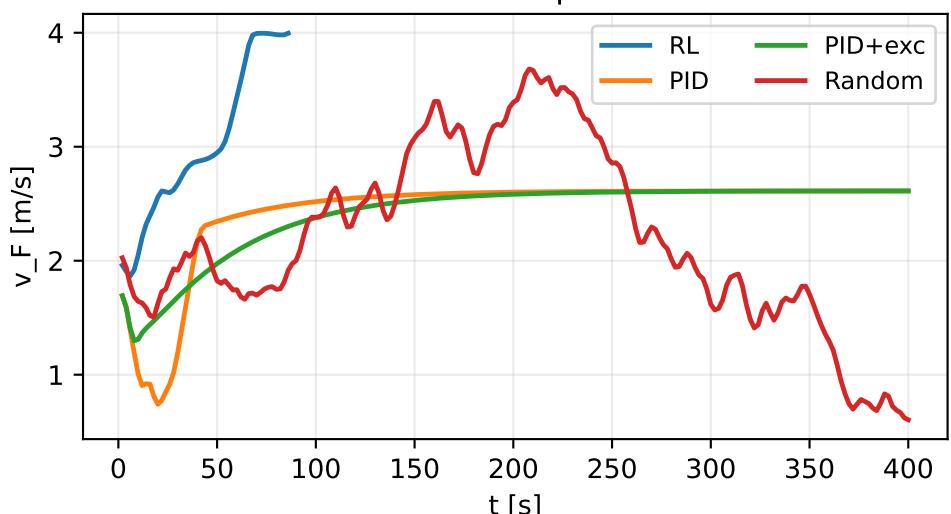
Estimator uncertainty (std_max)



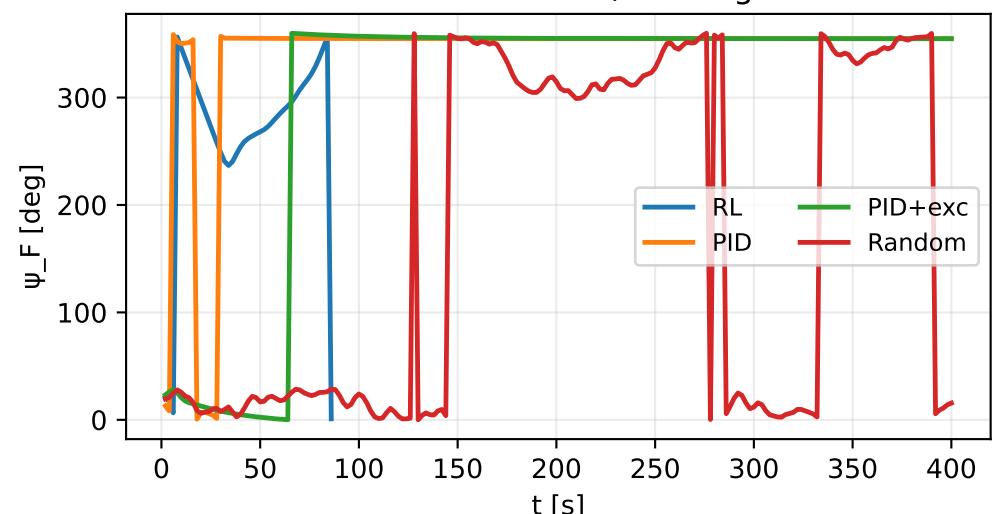
Information and excitation



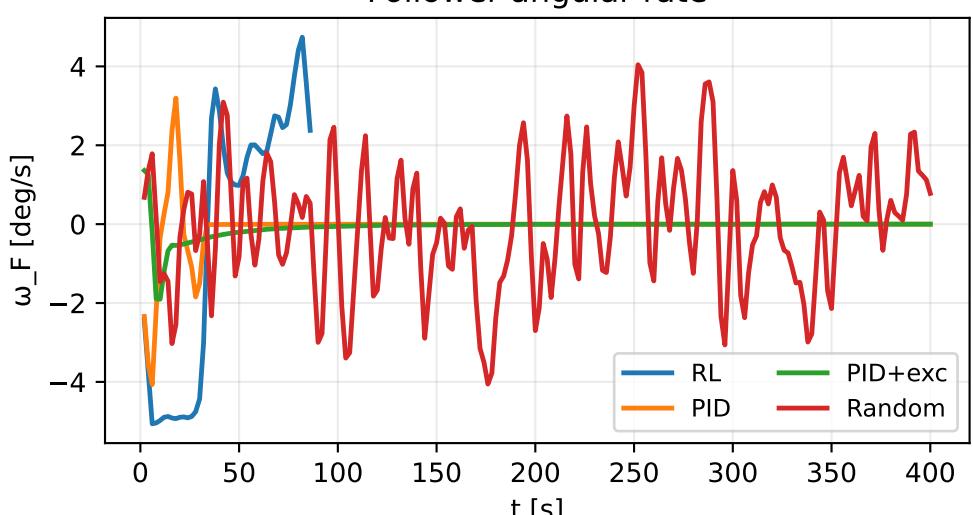
Follower speed



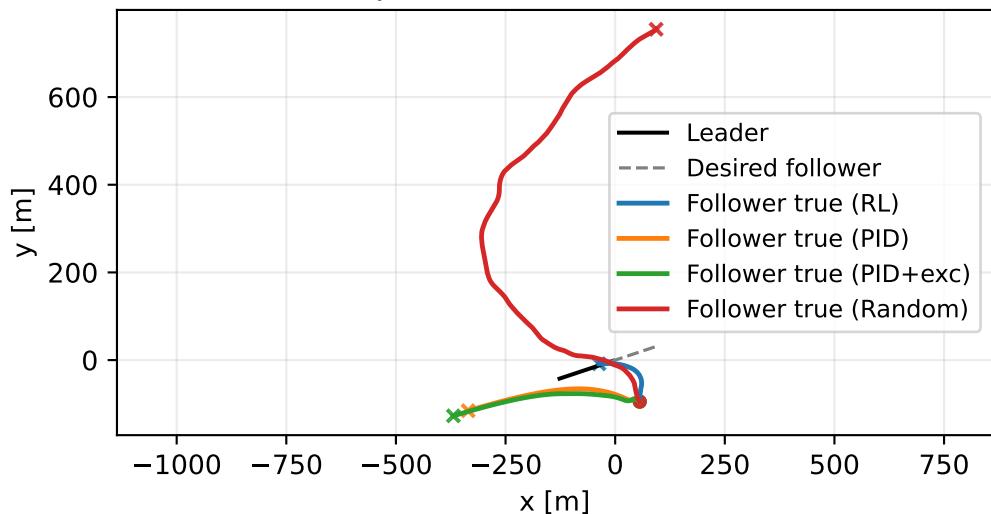
Follower course/heading



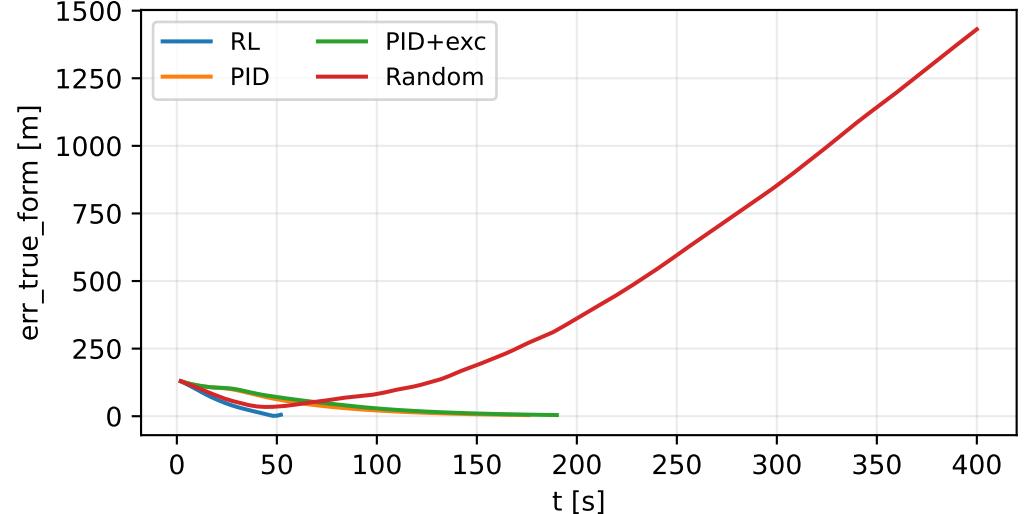
Follower angular rate



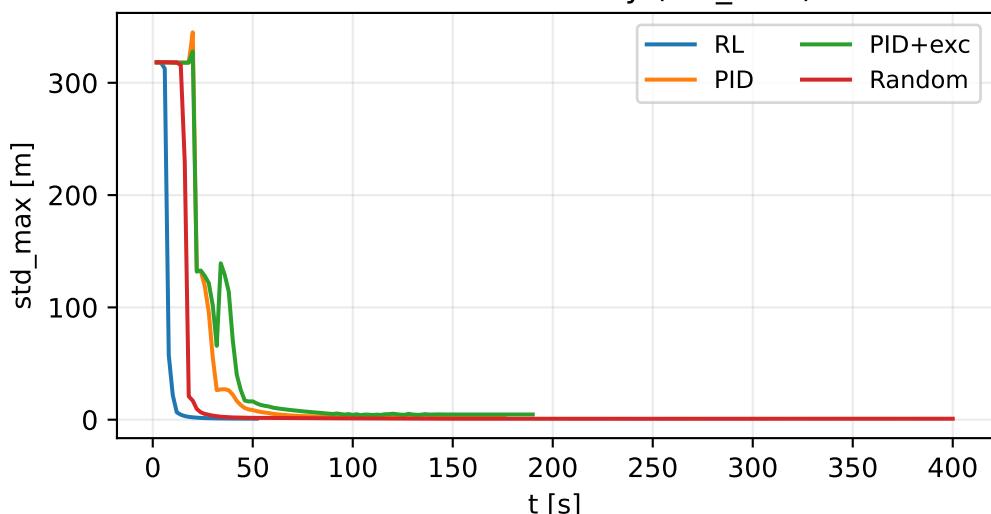
Trajectories (matched seed)



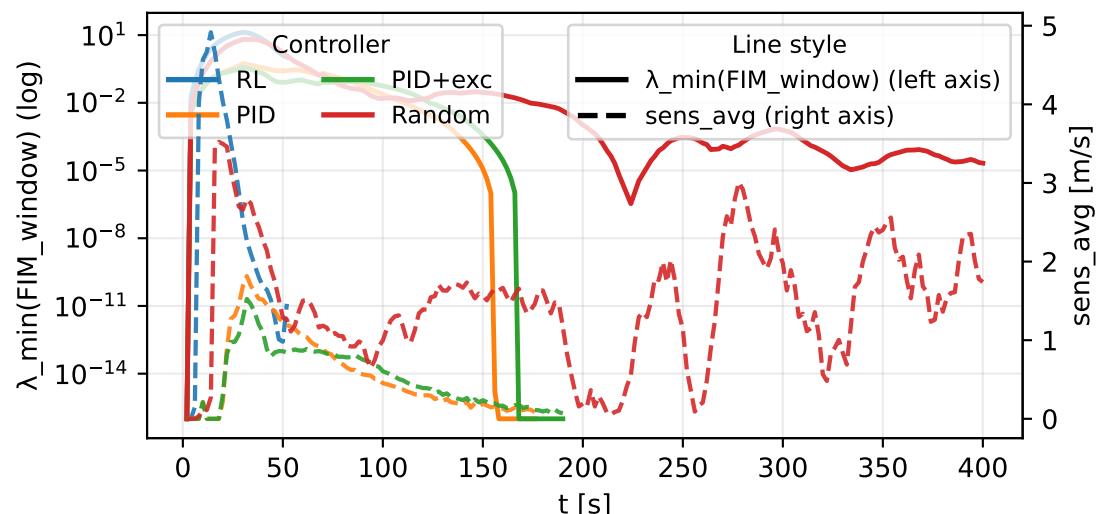
TRUE formation error



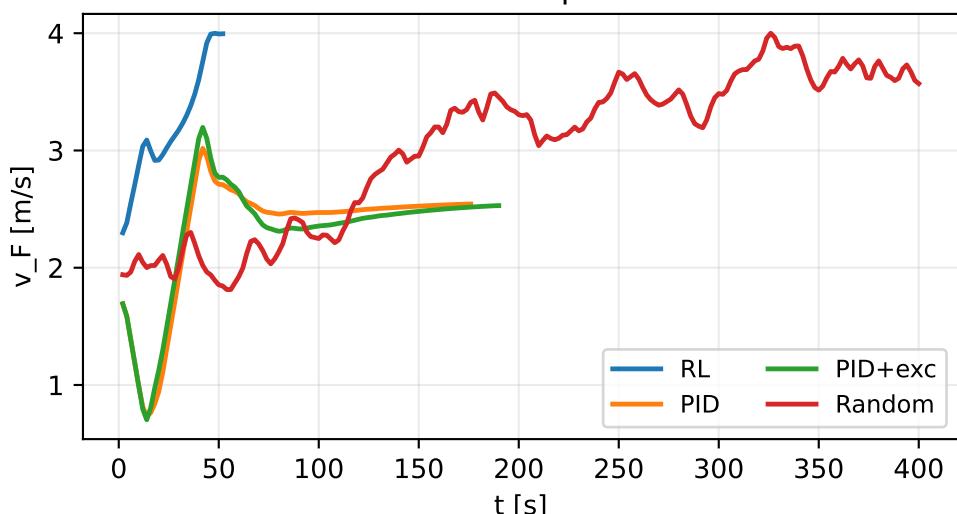
Estimator uncertainty (std_max)



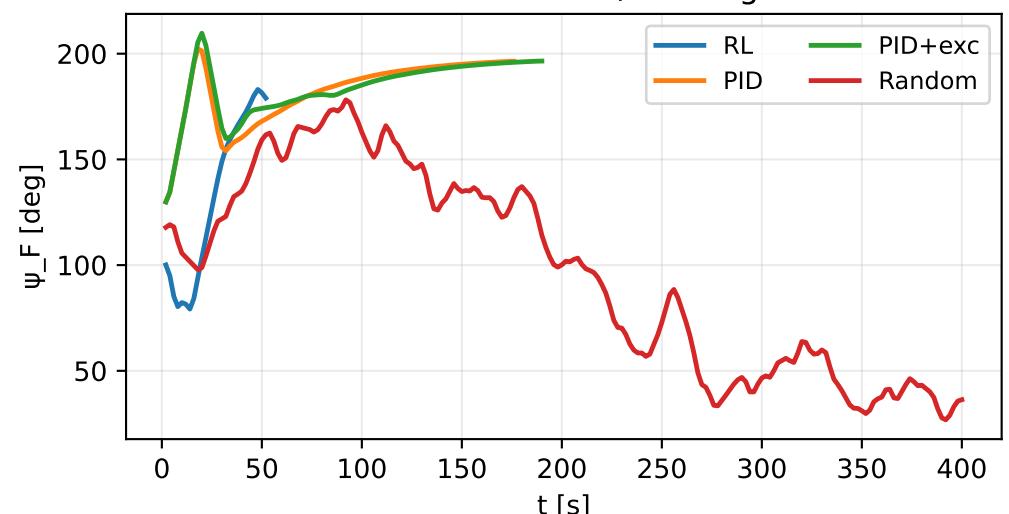
Information and excitation



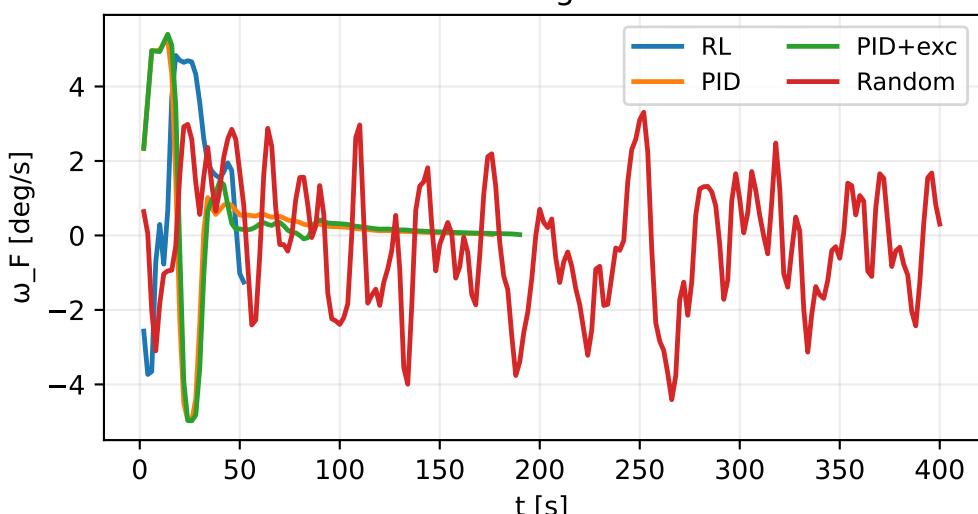
Follower speed



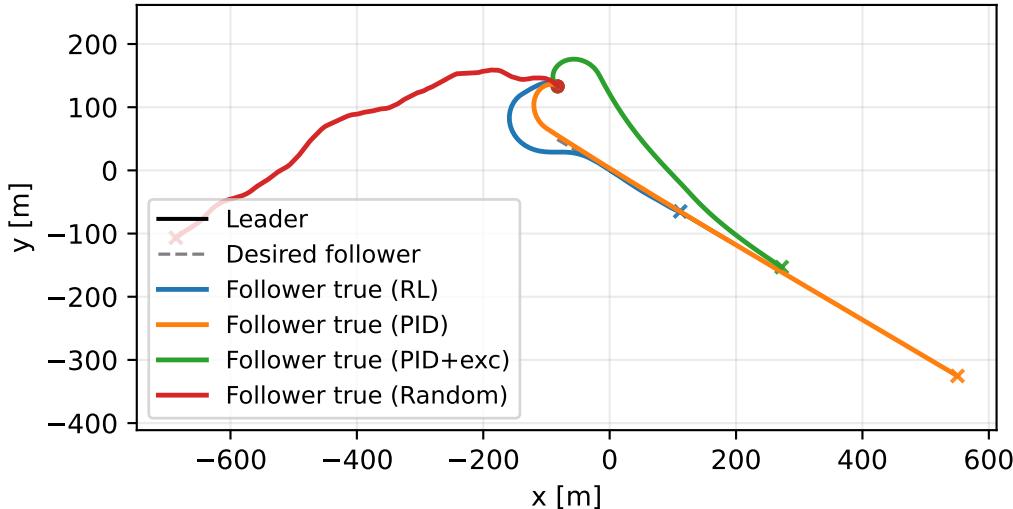
Follower course/heading



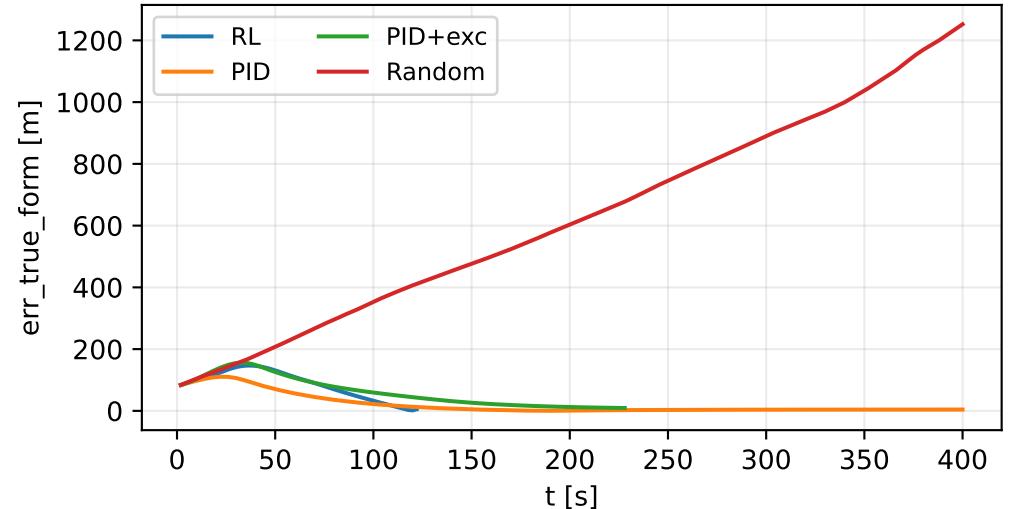
Follower angular rate



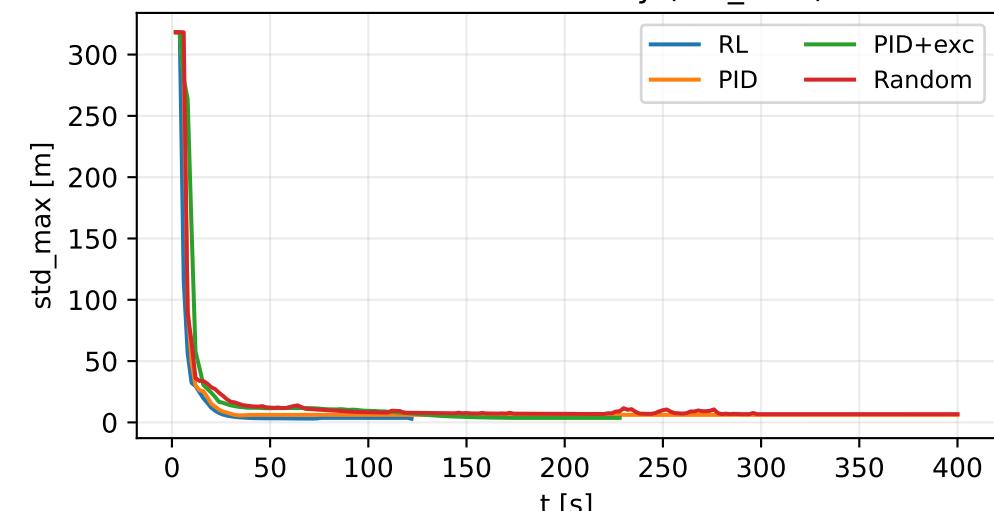
Trajectories (matched seed)



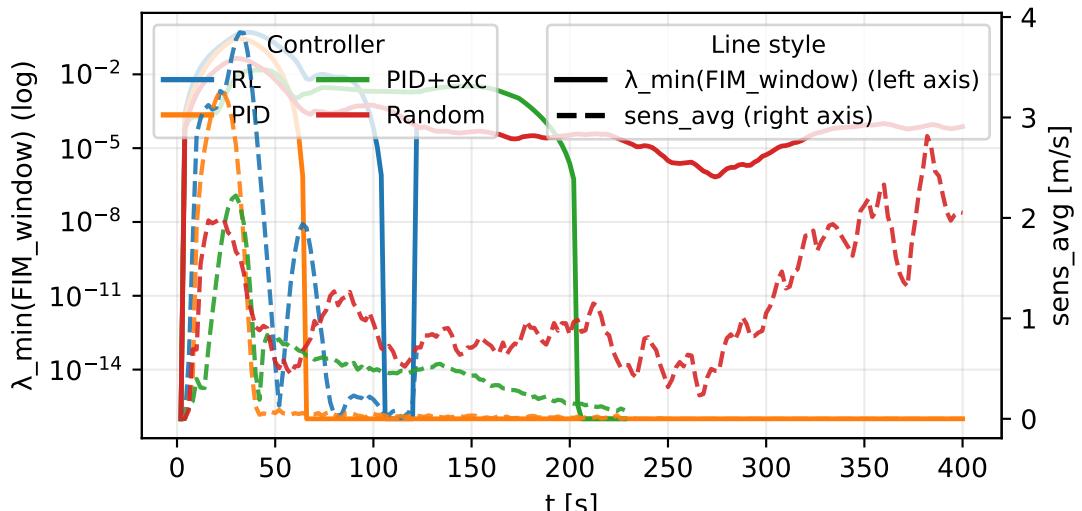
TRUE formation error



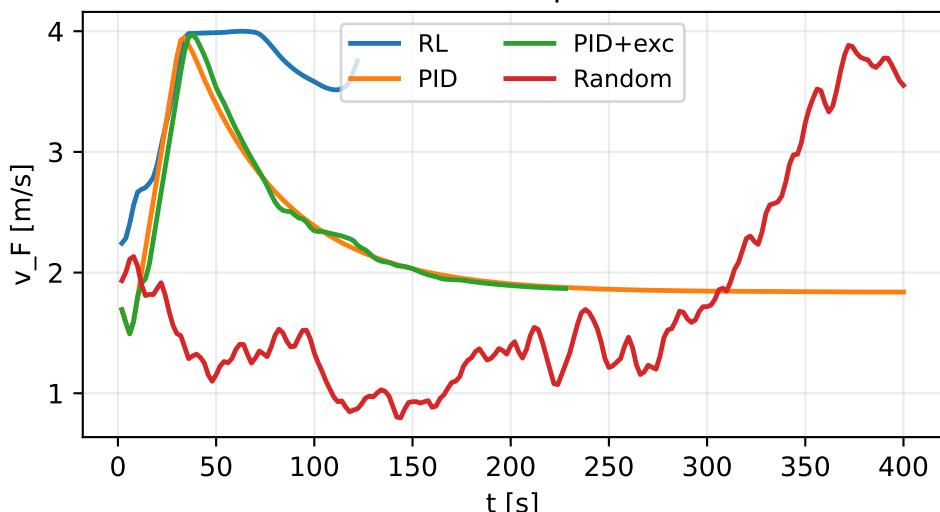
Estimator uncertainty (std_max)



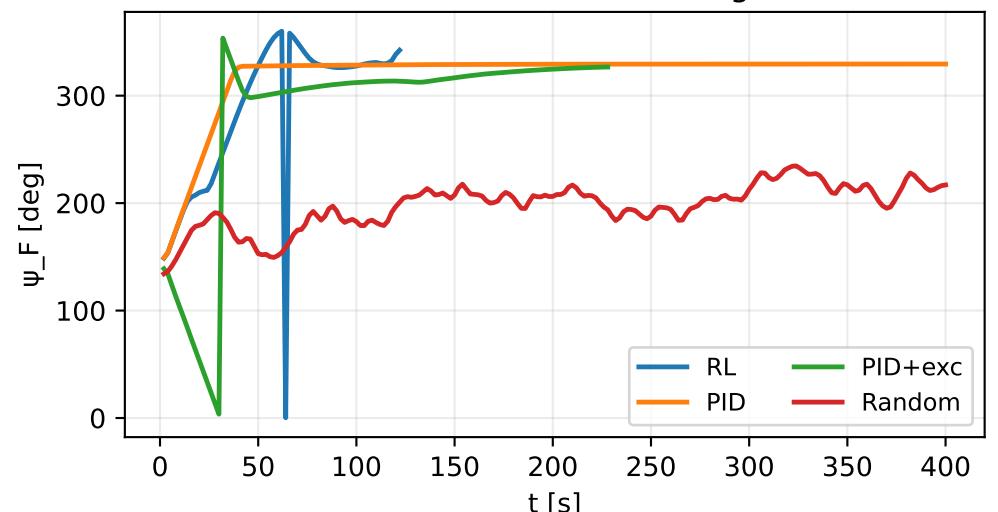
Information and excitation



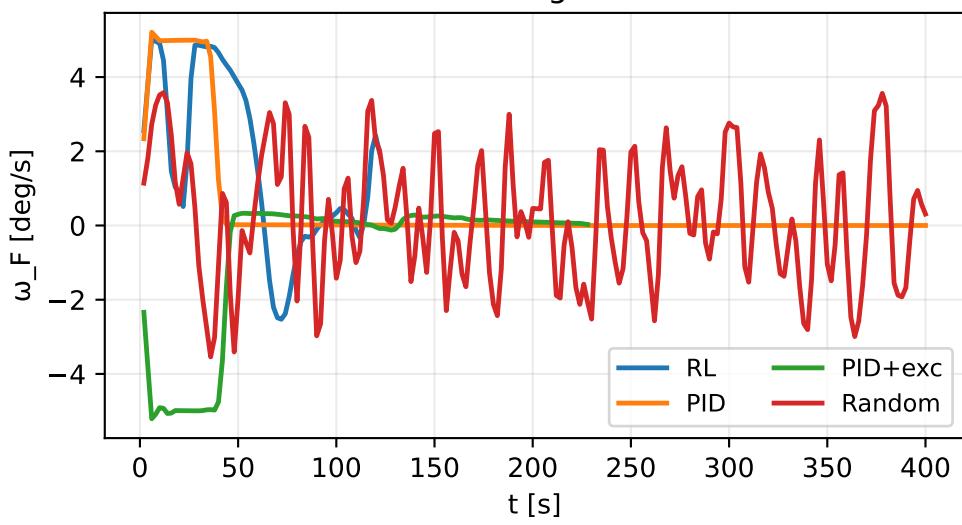
Follower speed



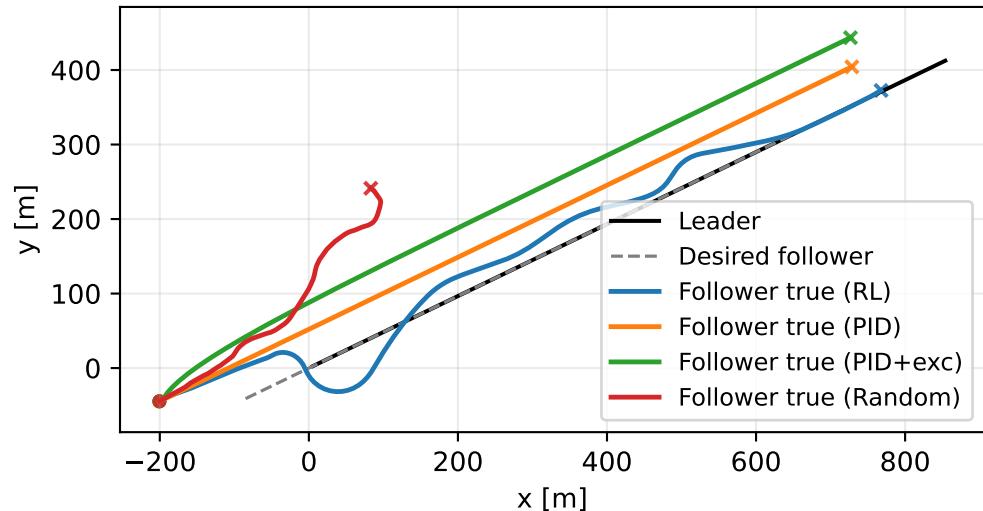
Follower course/heading



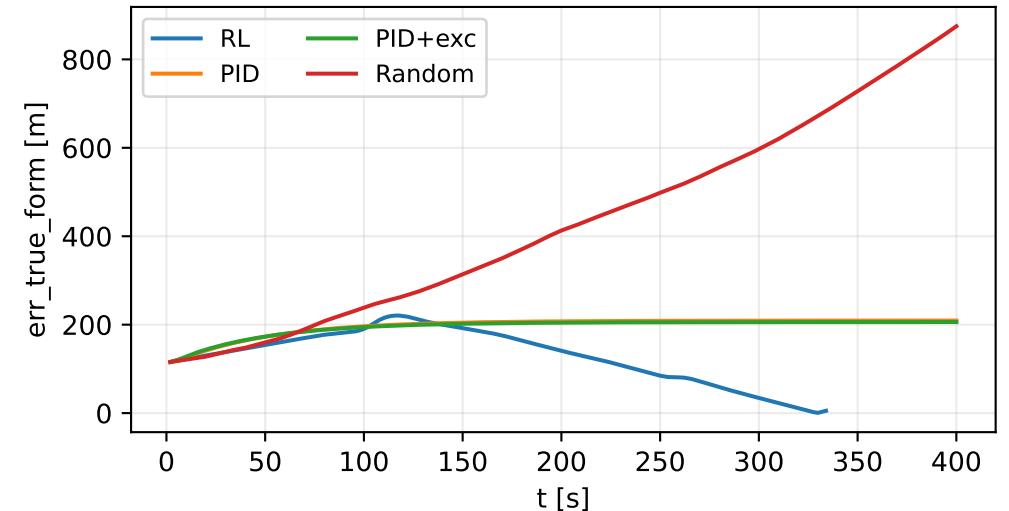
Follower angular rate



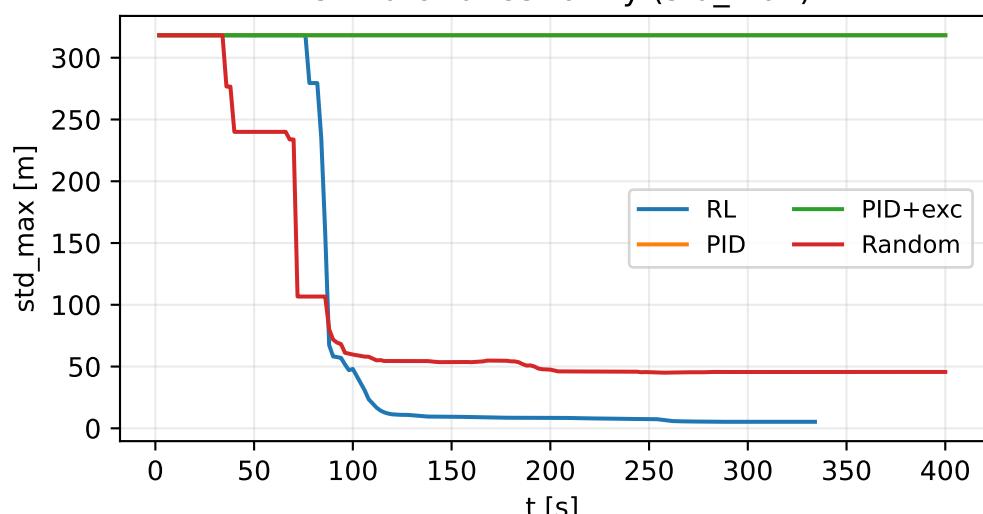
Trajectories (matched seed)



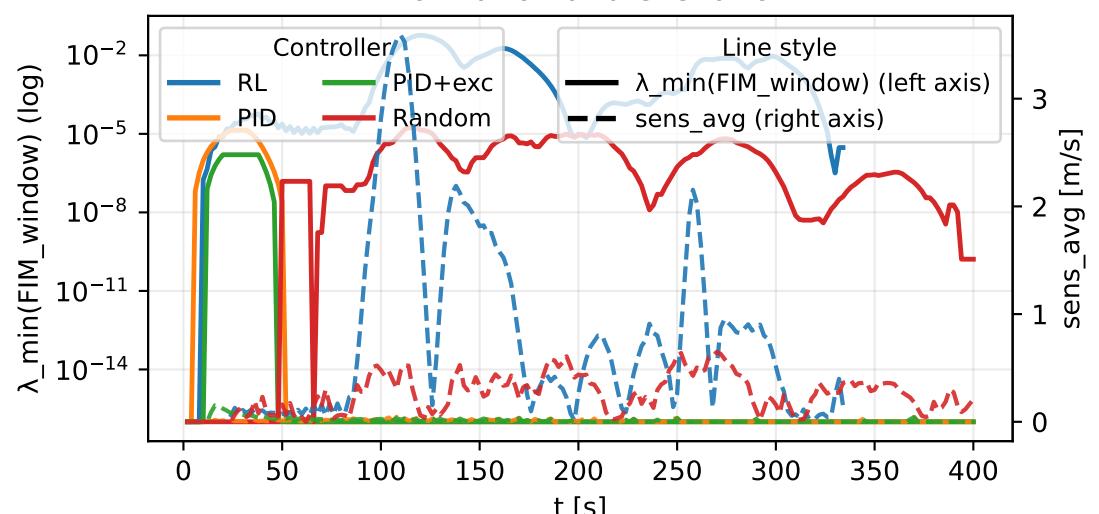
TRUE formation error



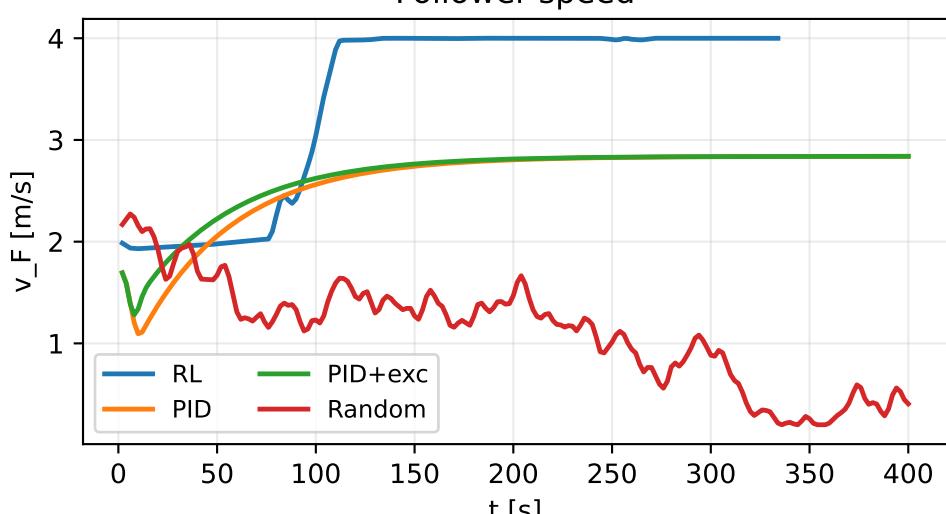
Estimator uncertainty (std_max)



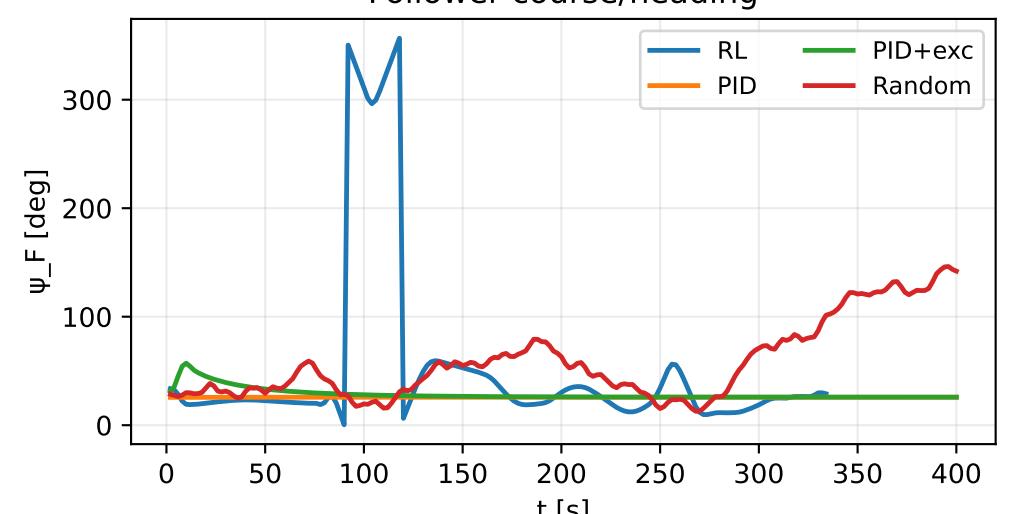
Information and excitation



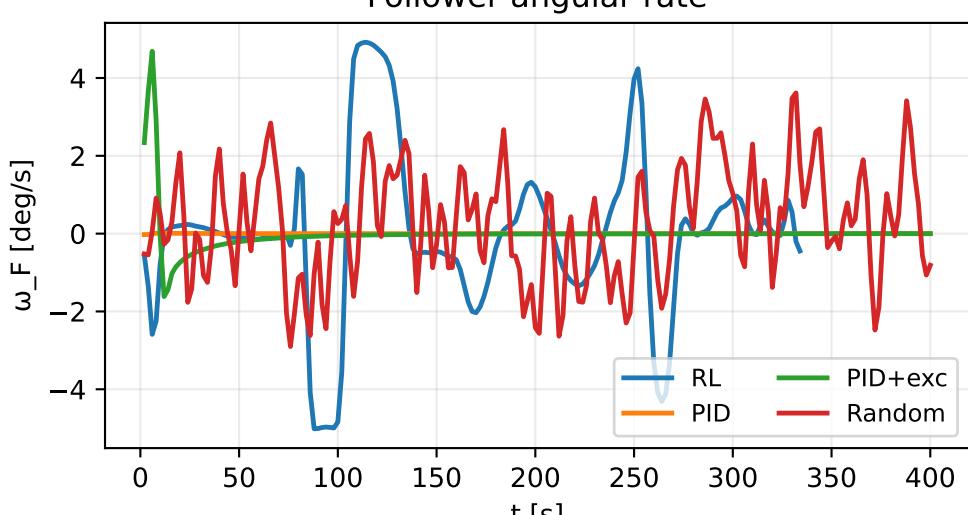
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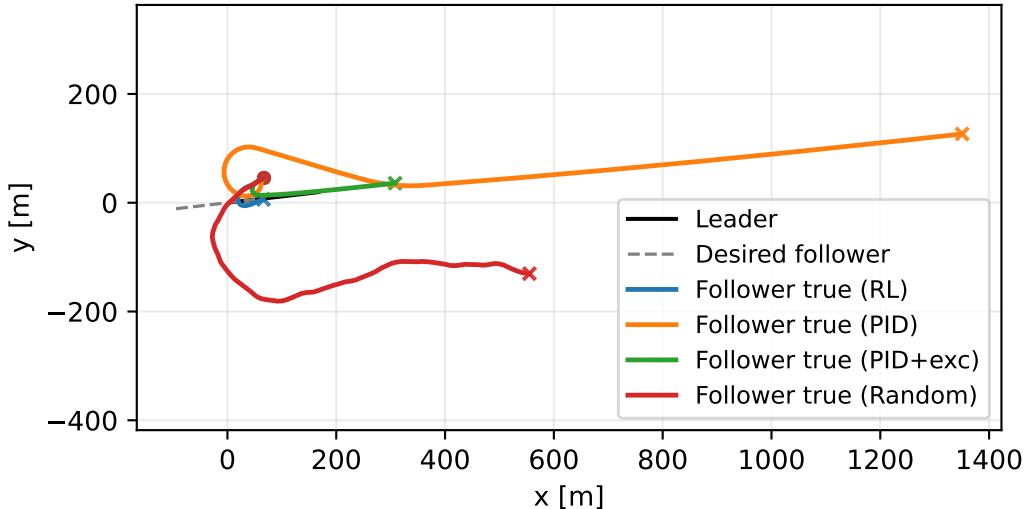
Follower course/heading



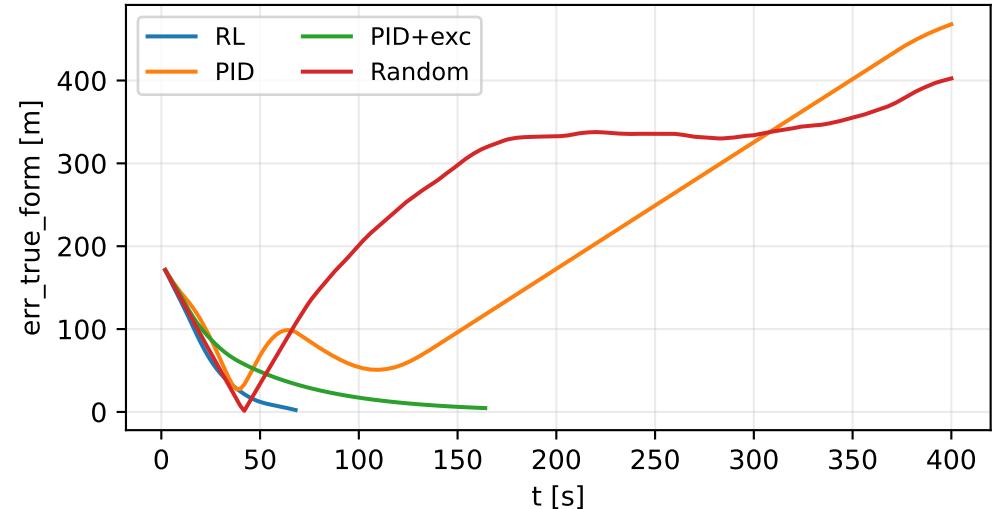
Follower angular rate



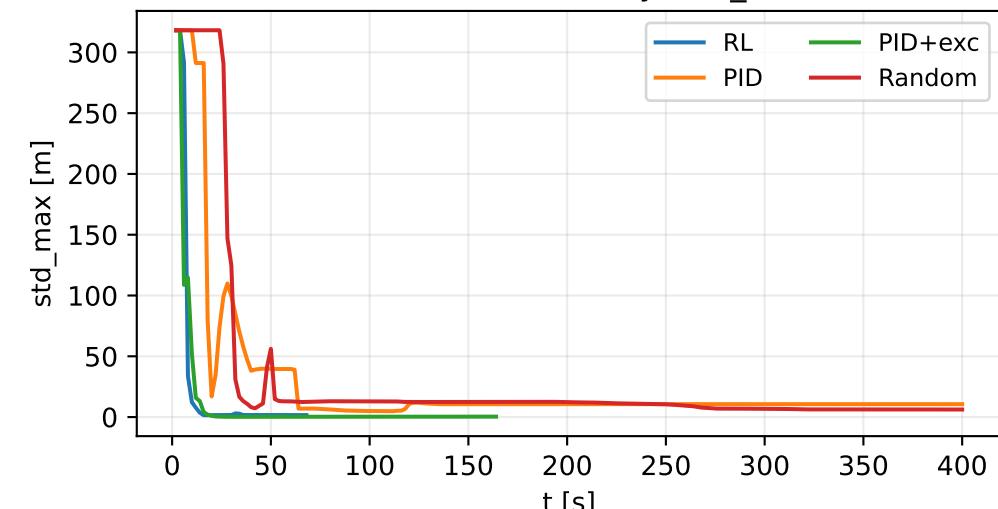
Trajectories (matched seed)



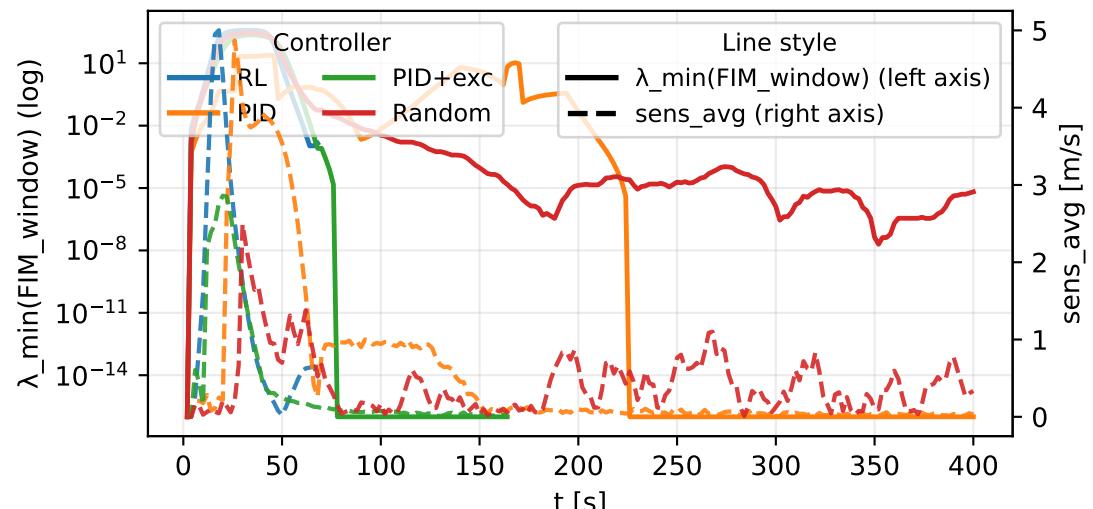
TRUE formation error



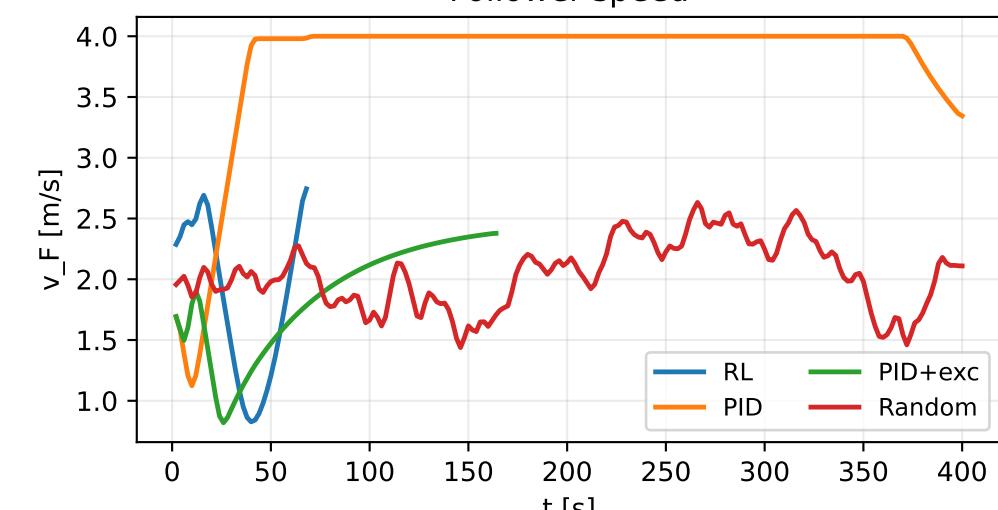
Estimator uncertainty (std_max)



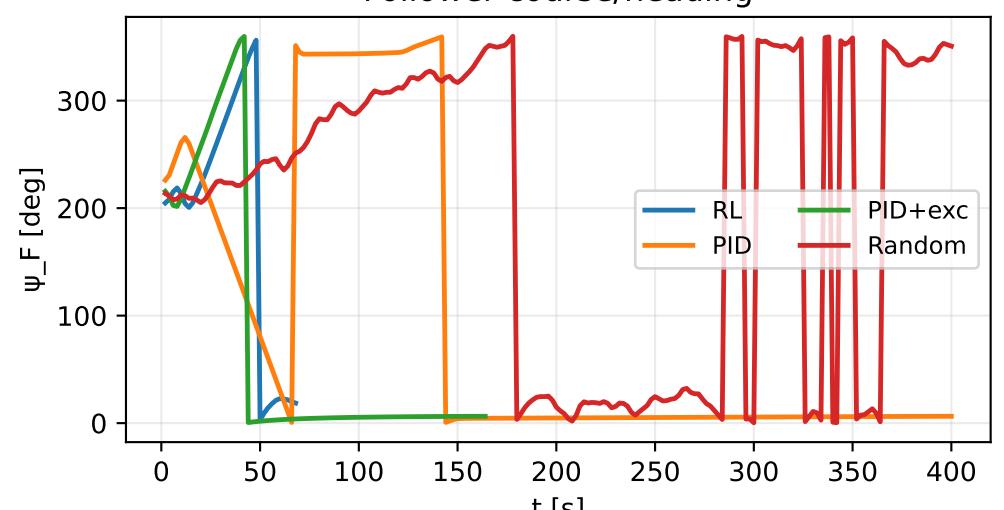
Information and excitation



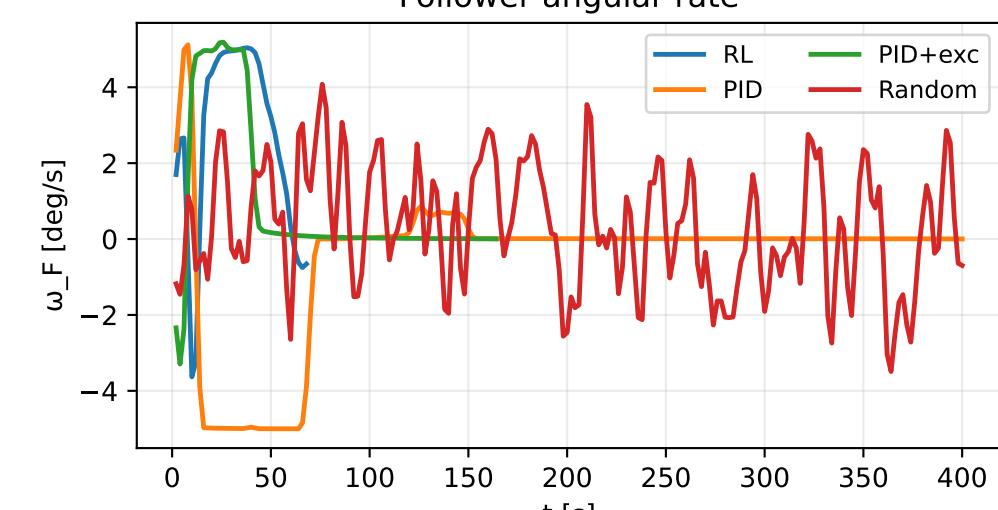
Follower speed



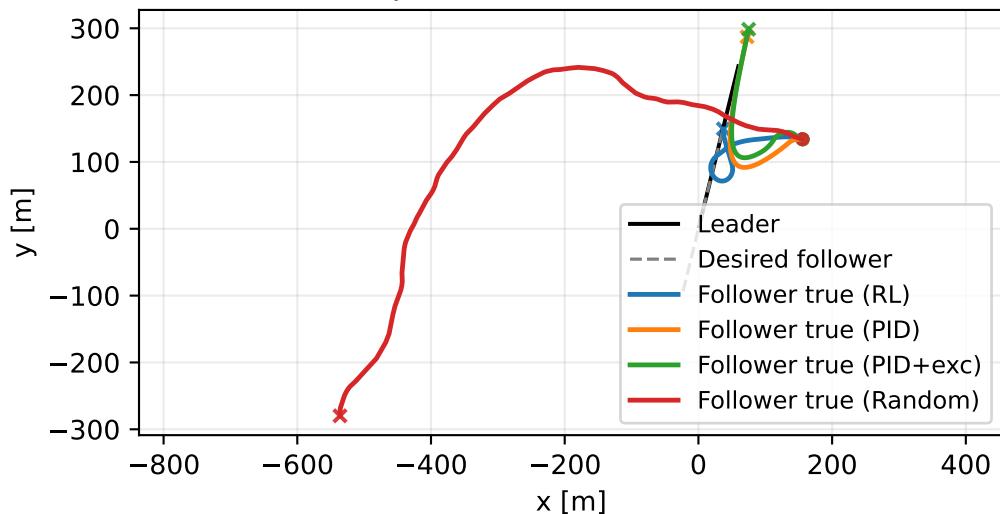
Follower course/heading



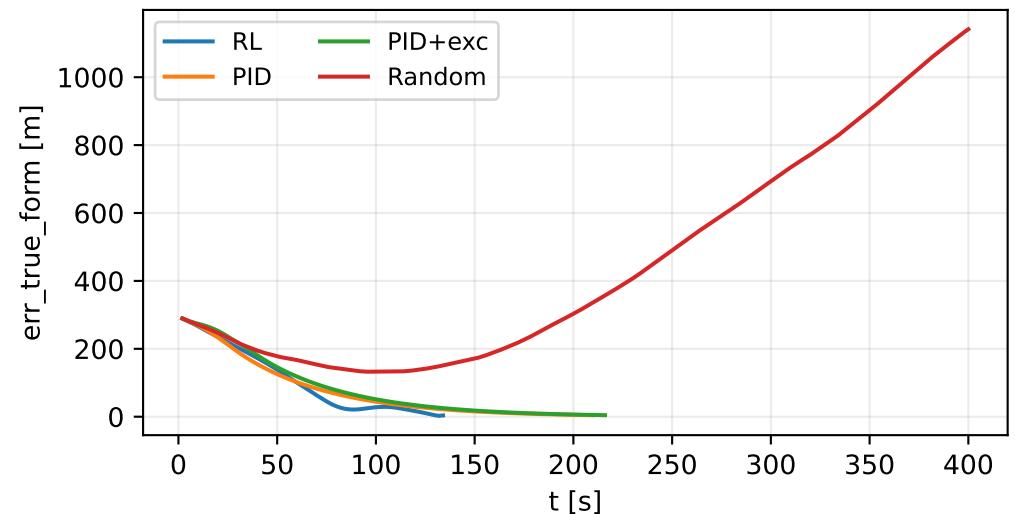
Follower angular rate



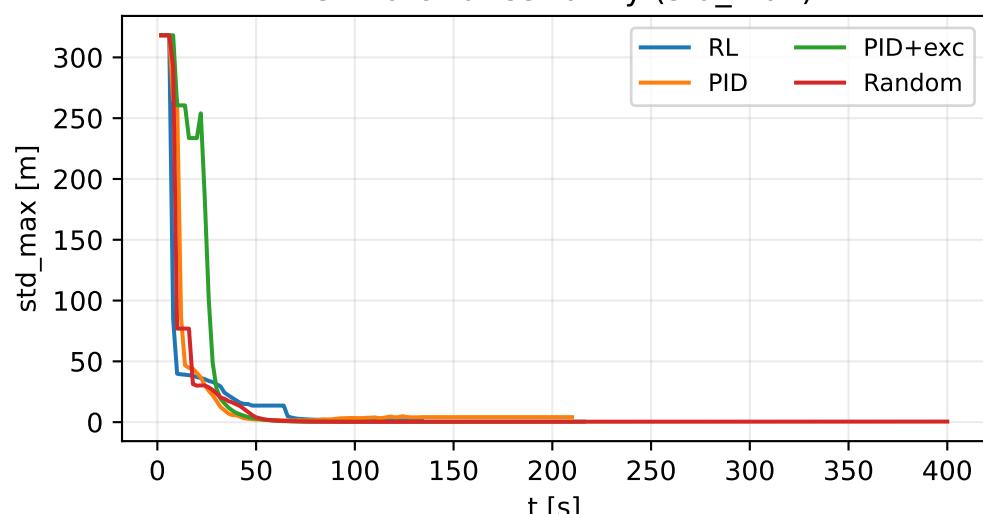
Trajectories (matched seed)



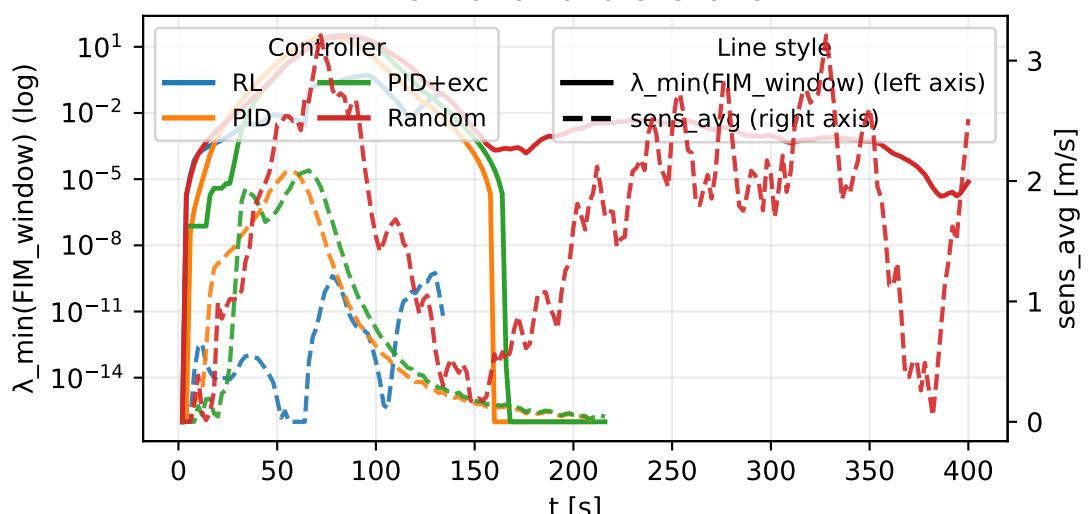
TRUE formation error



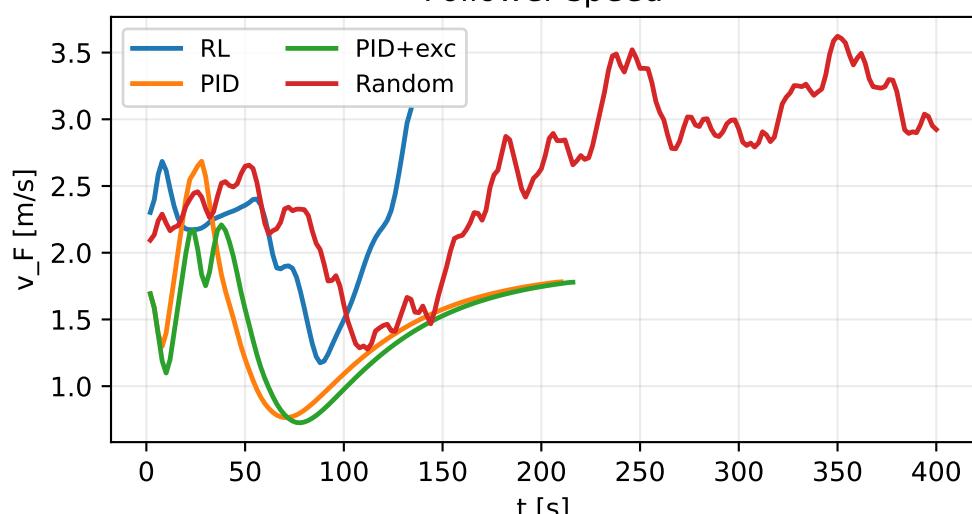
Estimator uncertainty (std_max)



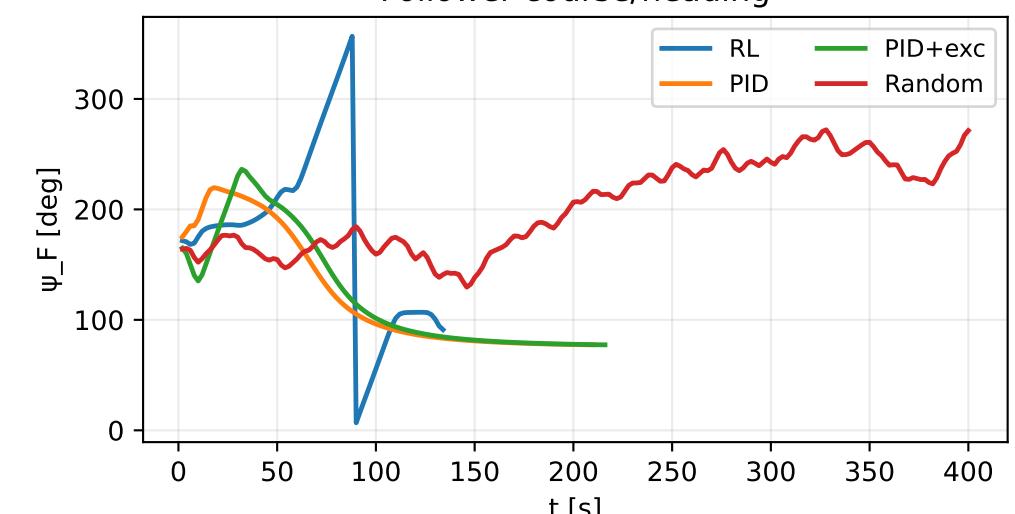
Information and excitation



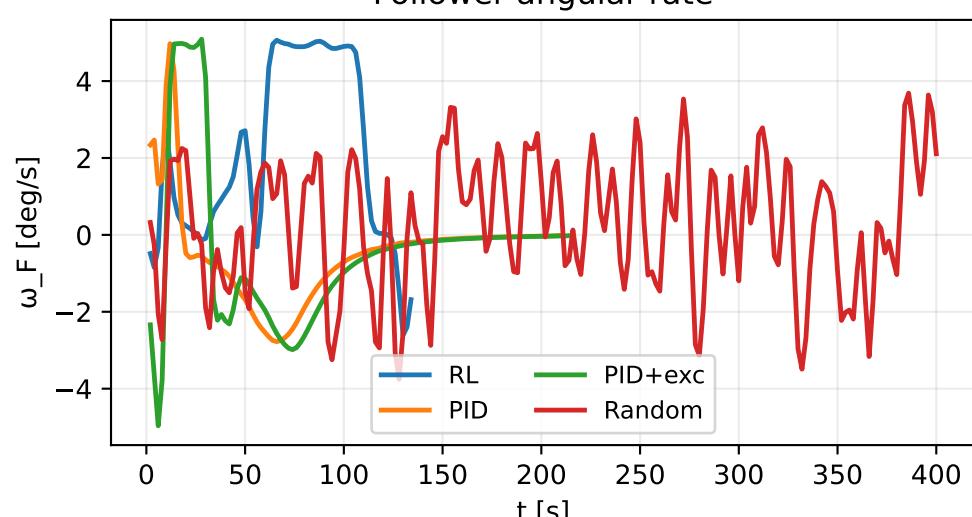
Follower speed



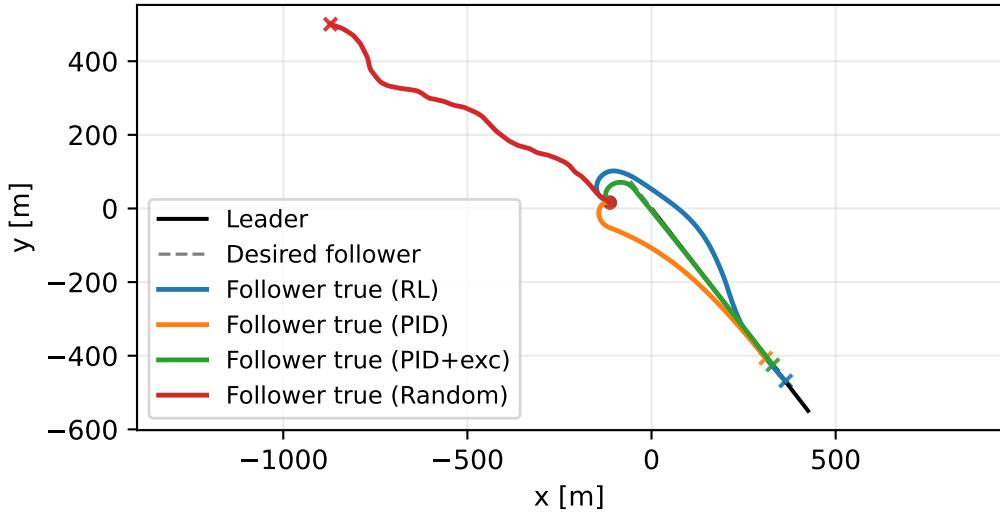
Follower course/heading



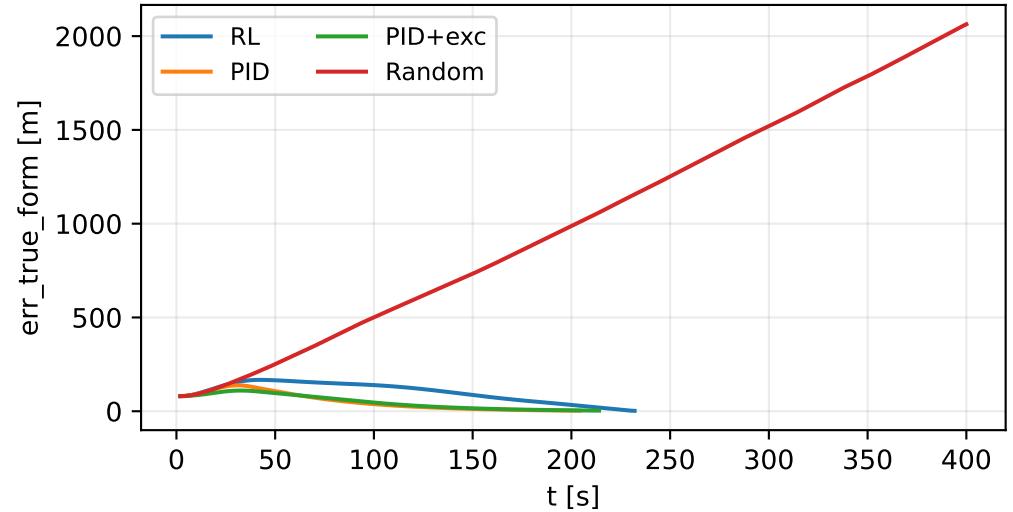
Follower angular rate



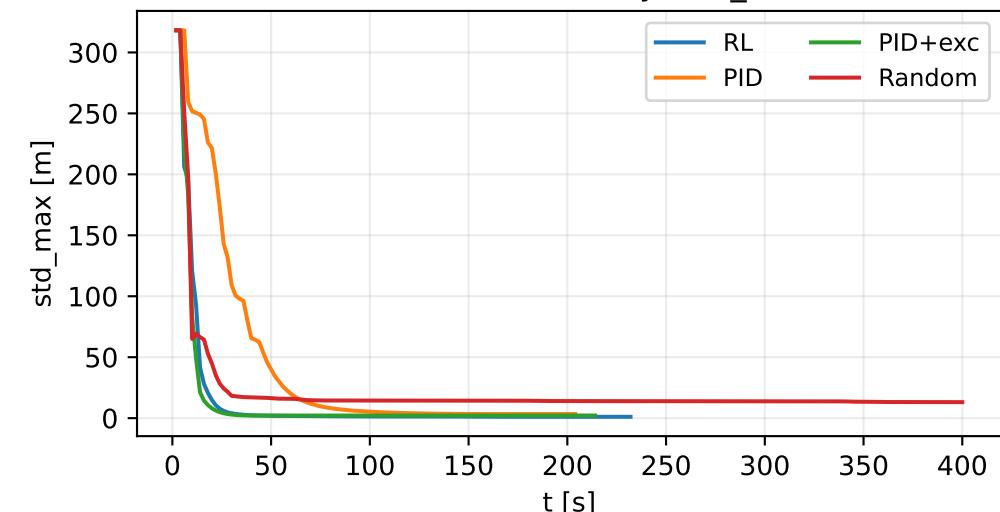
Trajectories (matched seed)



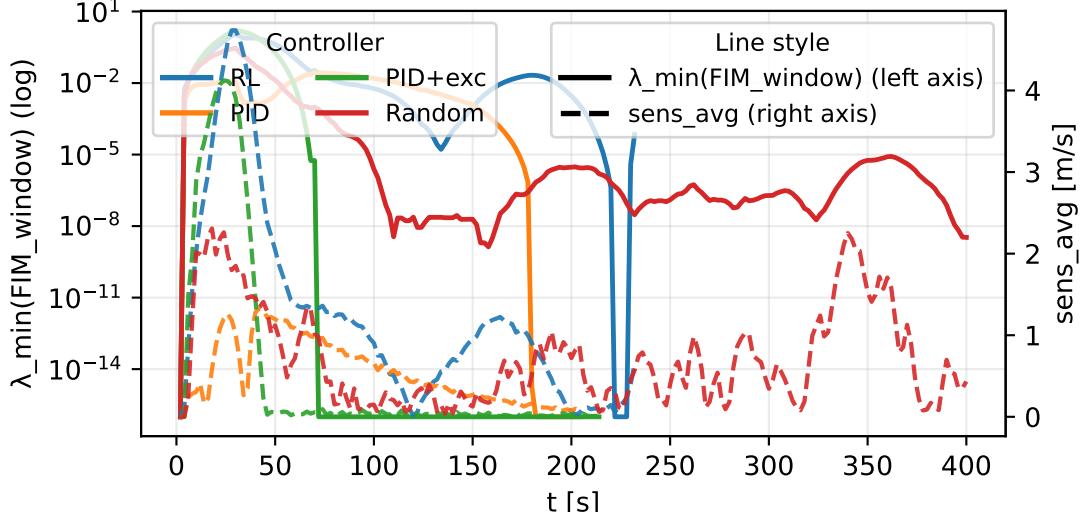
TRUE formation error



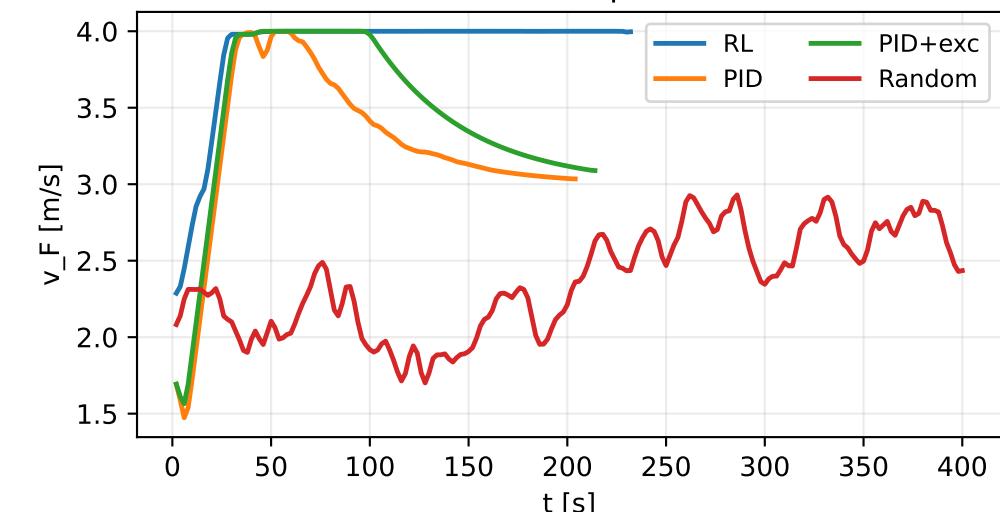
Estimator uncertainty (std_max)



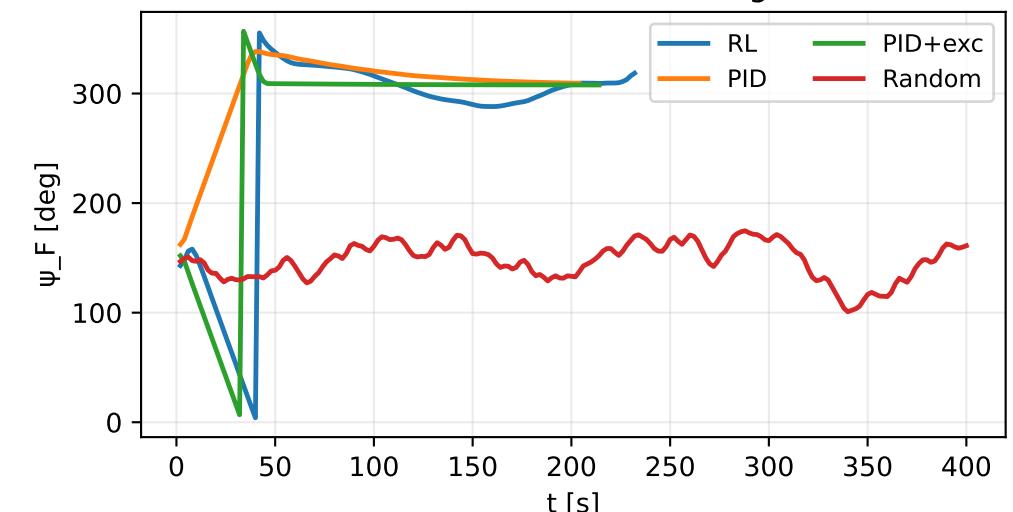
Information and excitation



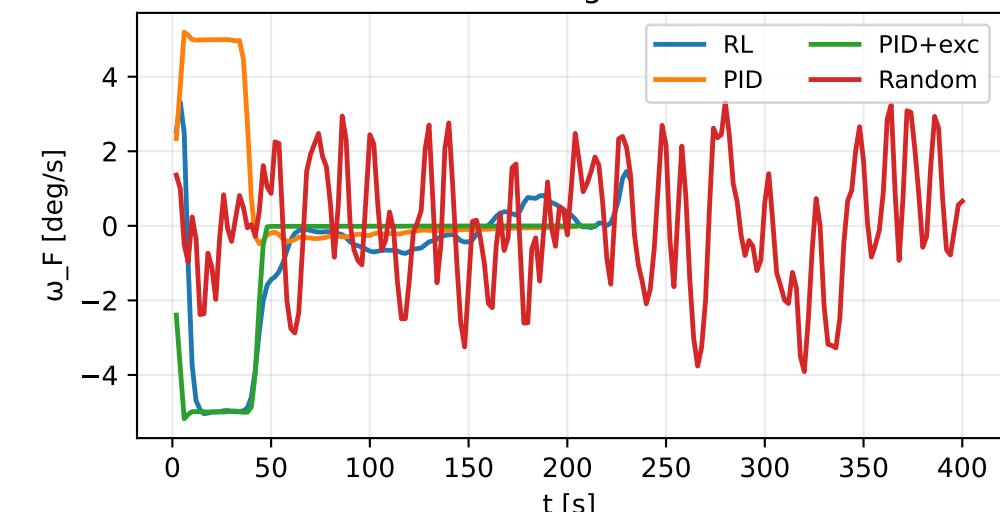
Follower speed



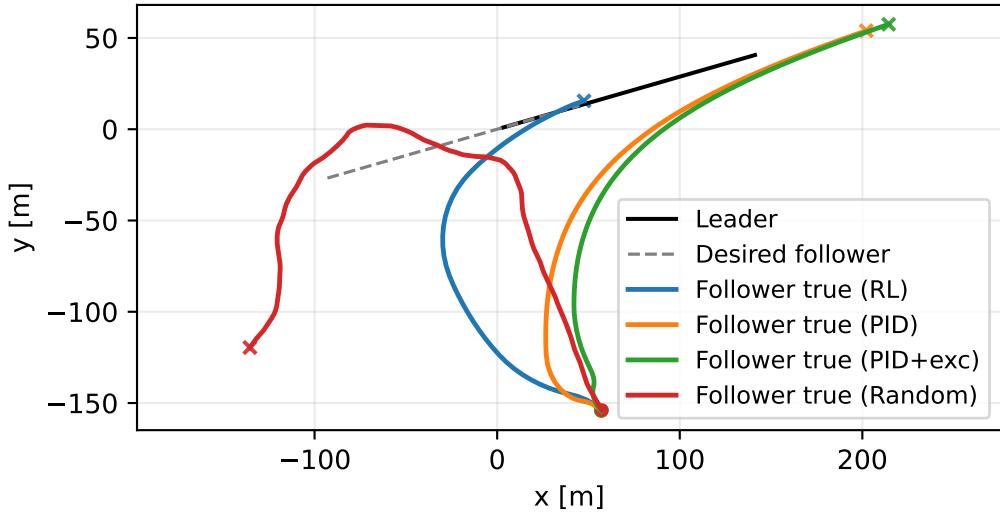
Follower course/heading



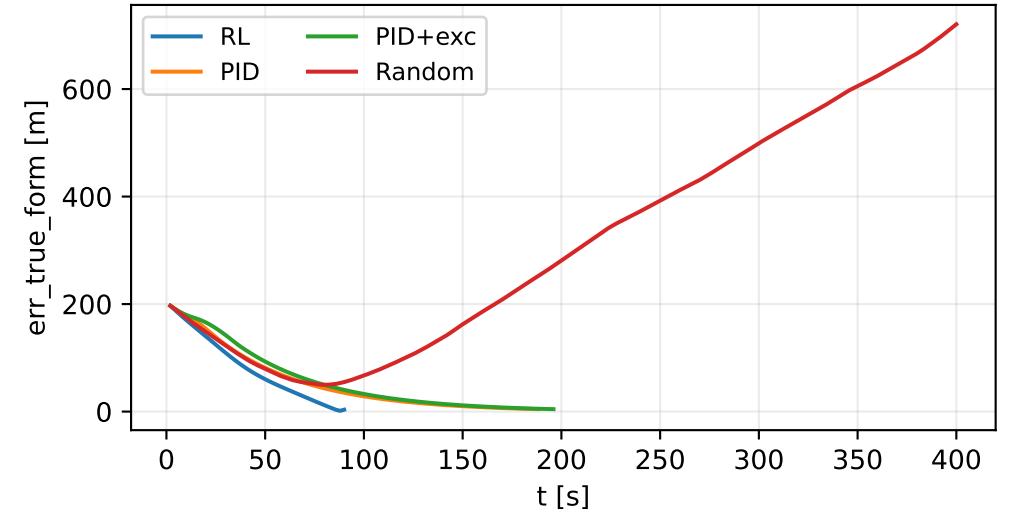
Follower angular rate



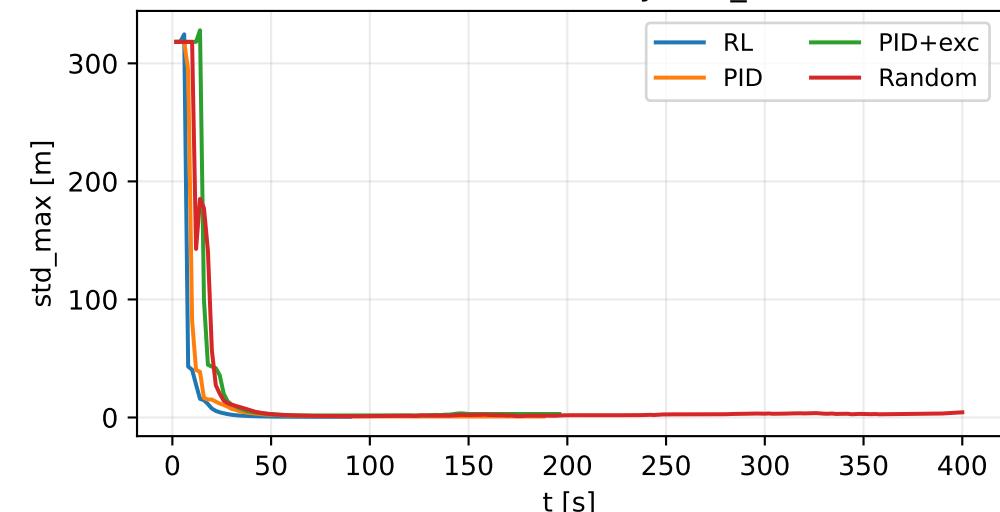
Trajectories (matched seed)



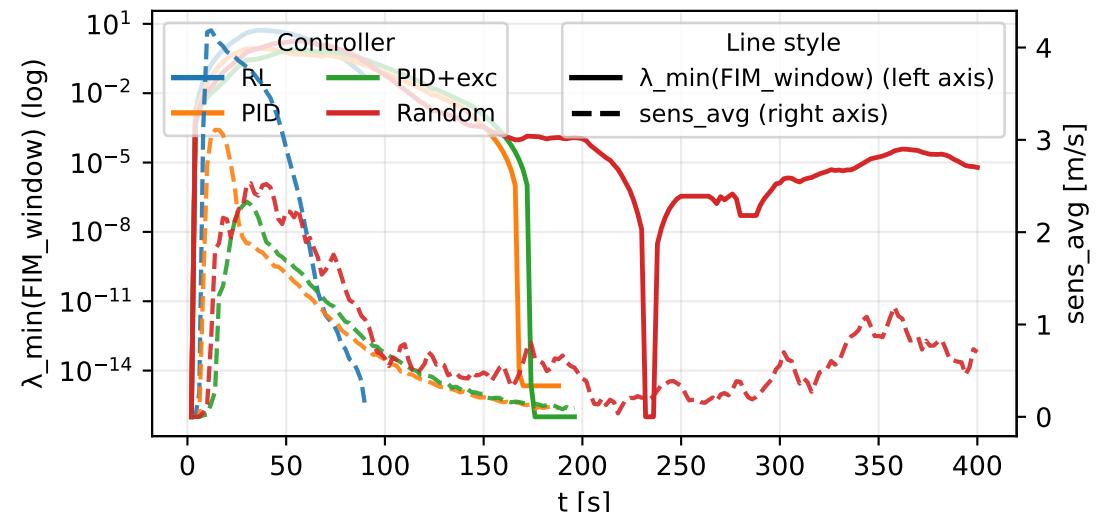
TRUE formation error



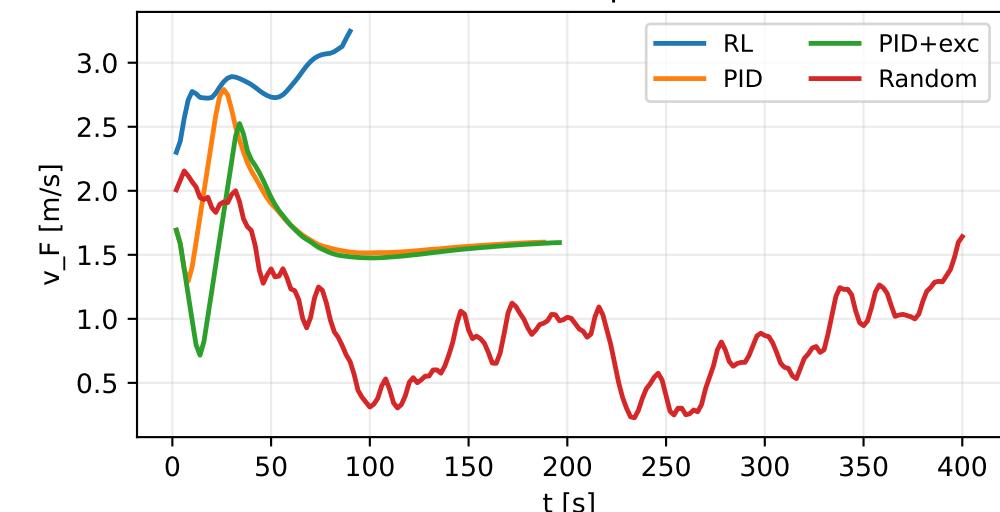
Estimator uncertainty (std_max)



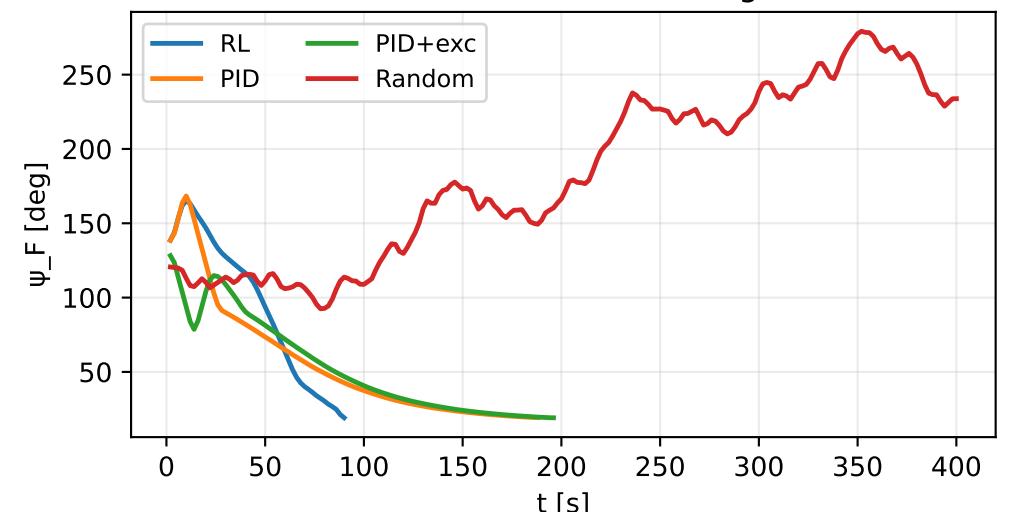
Information and excitation



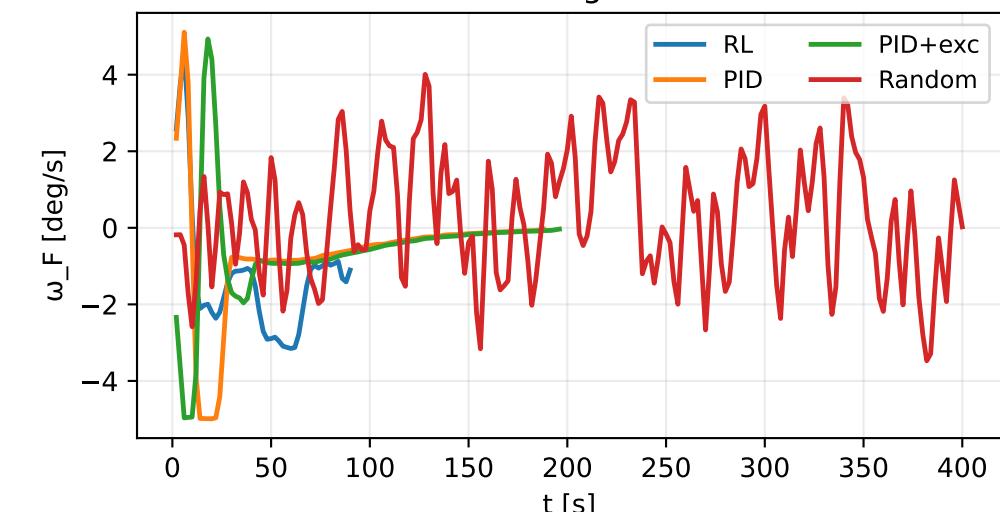
Follower speed



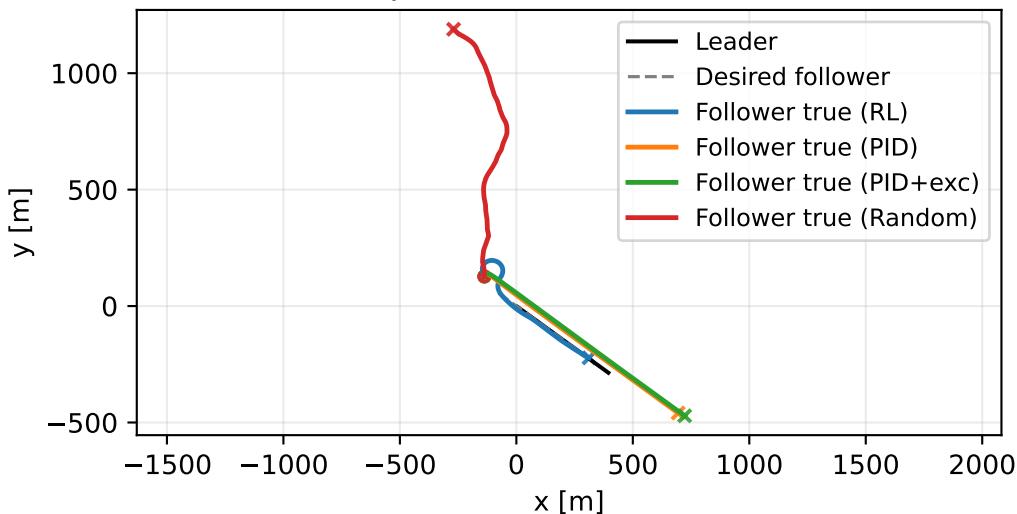
Follower course/heading



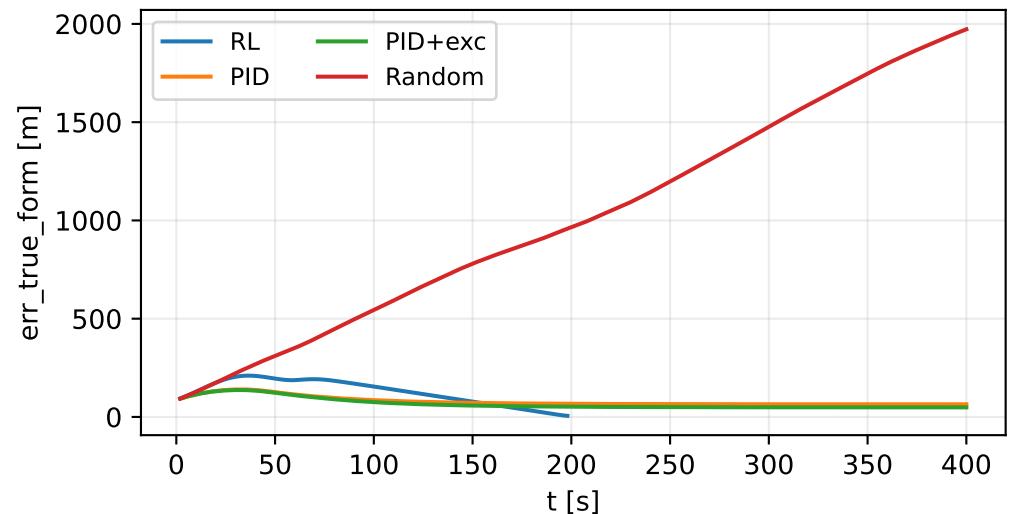
Follower angular rate



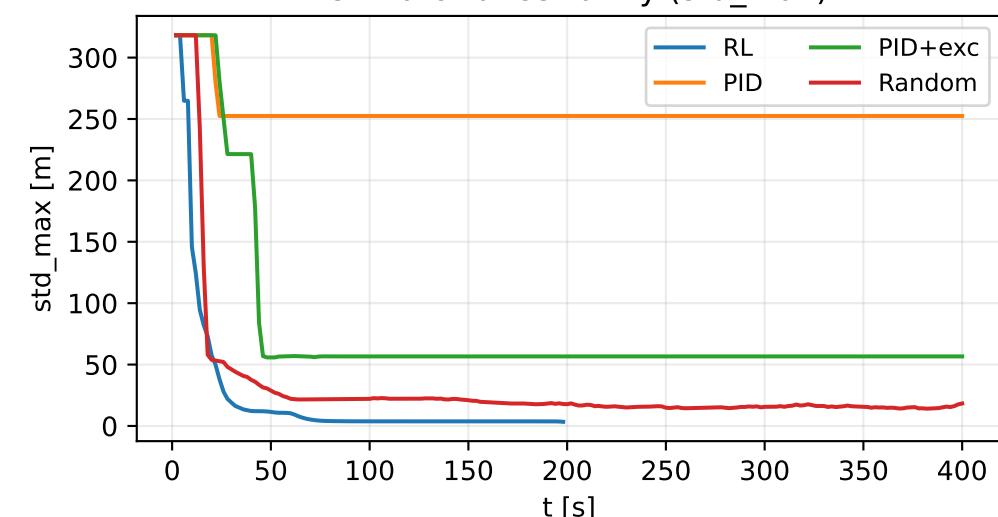
Trajectories (matched seed)



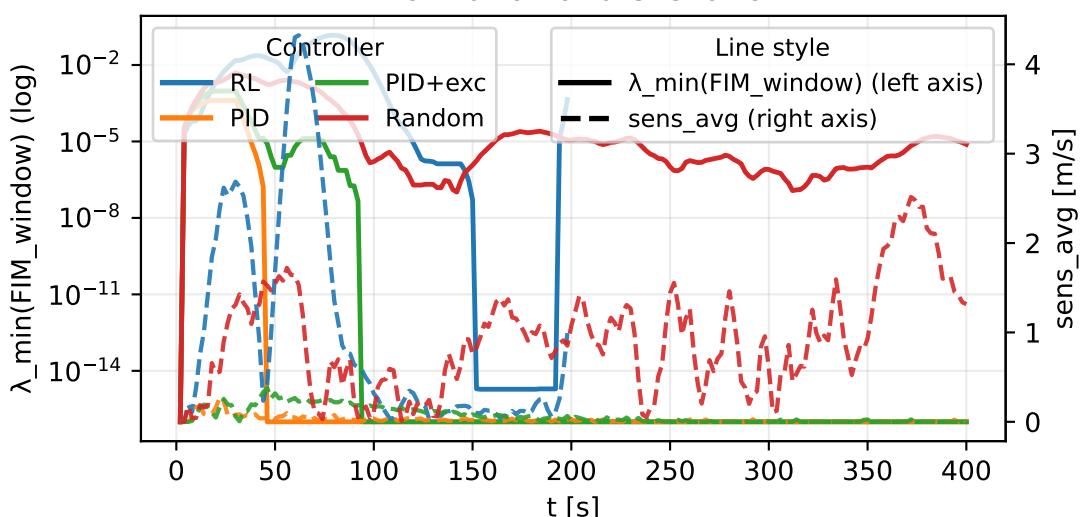
TRUE formation error



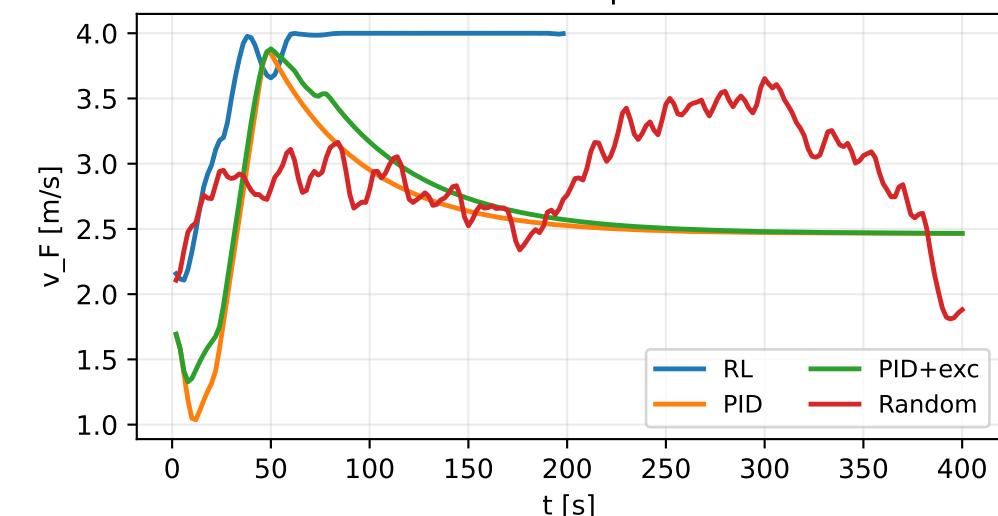
Estimator uncertainty (std_max)



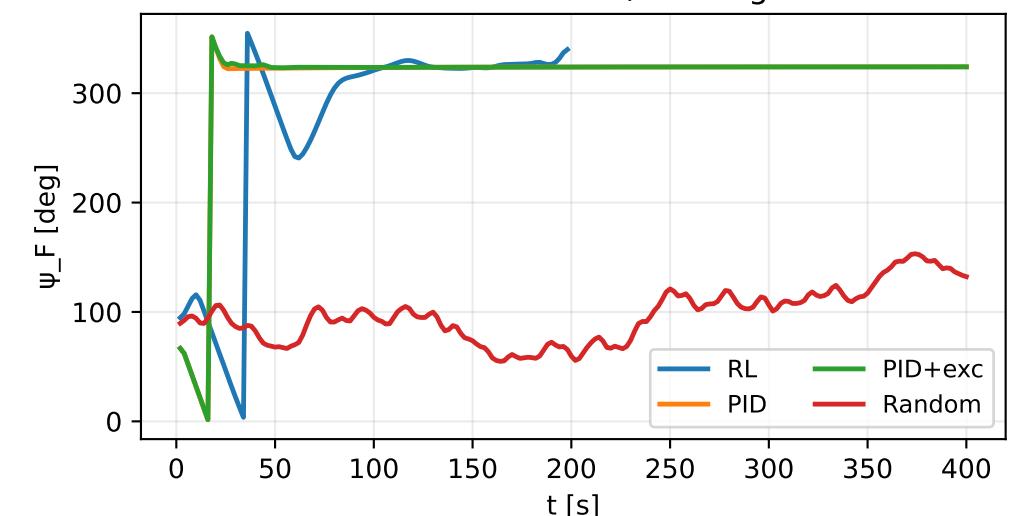
Information and excitation



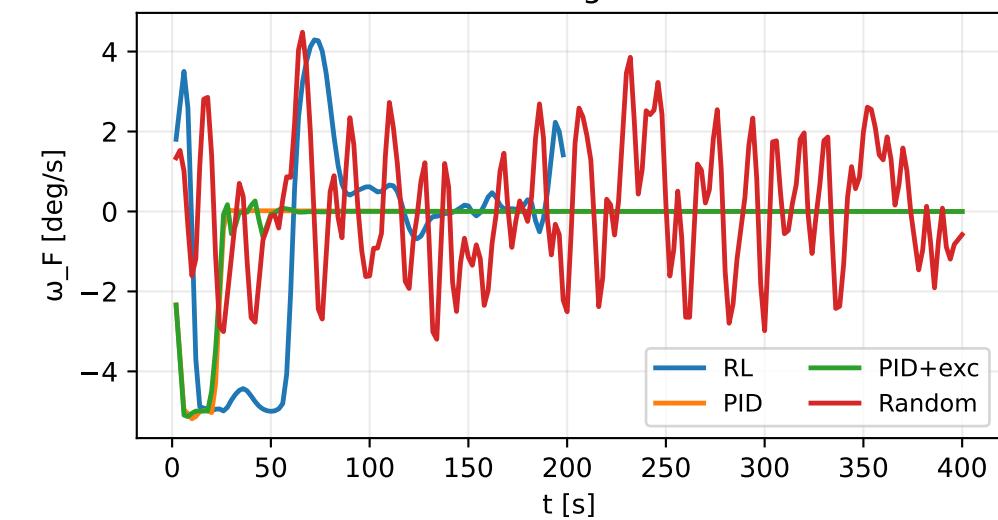
Follower speed



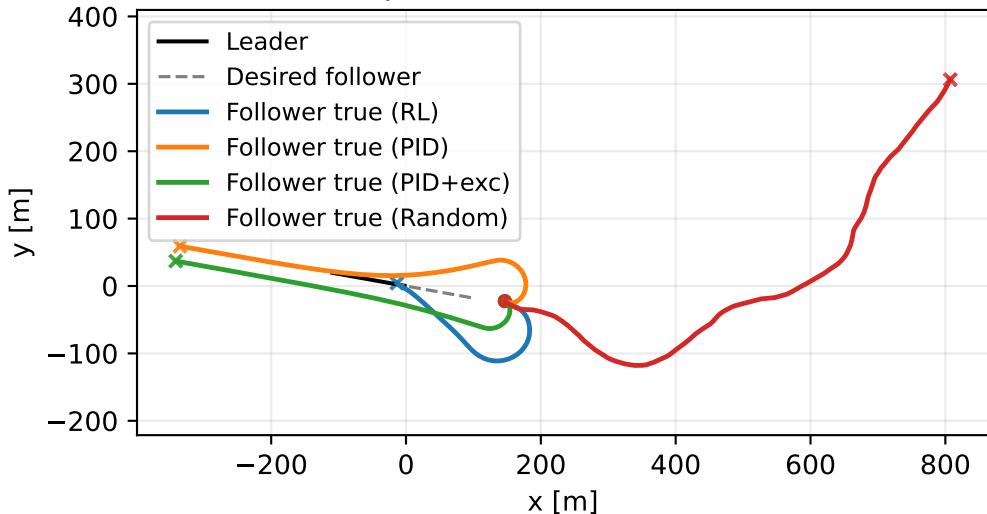
Follower course/heading



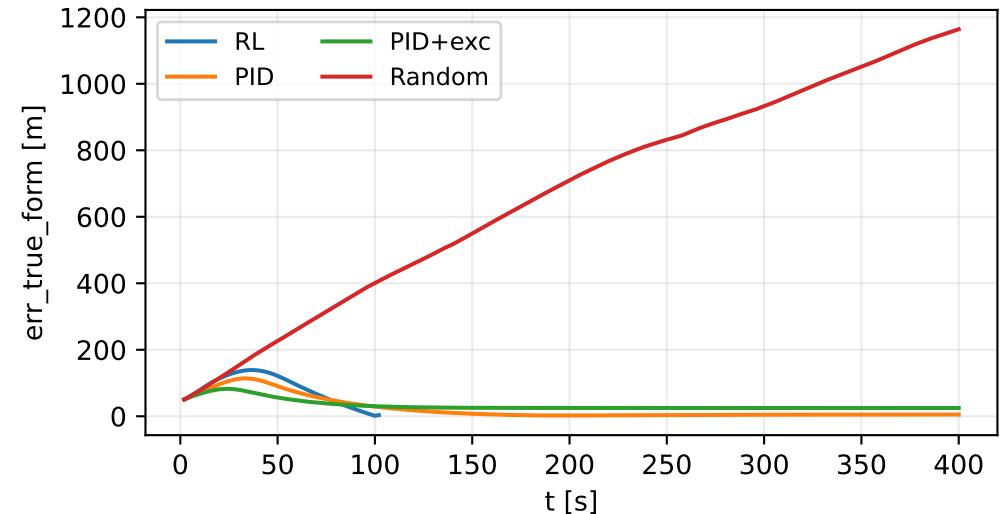
Follower angular rate



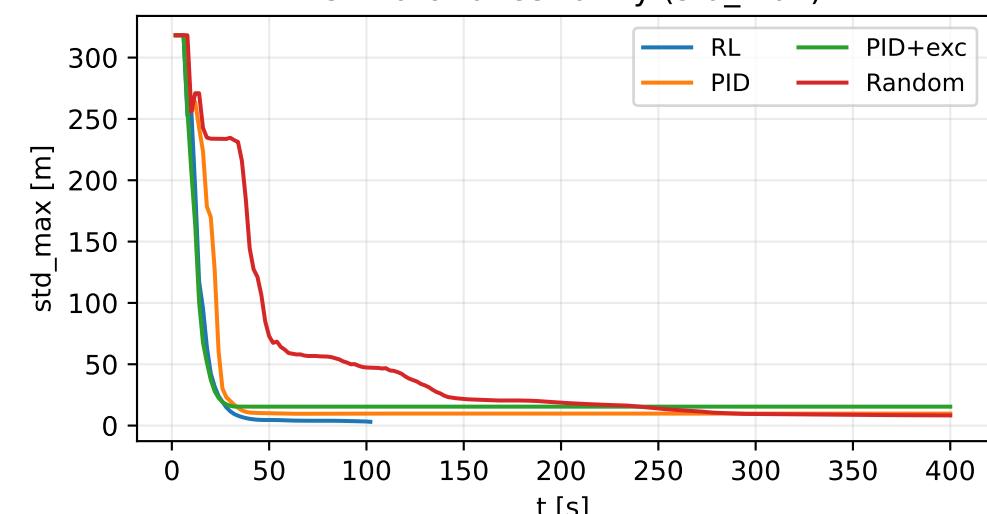
Trajectories (matched seed)



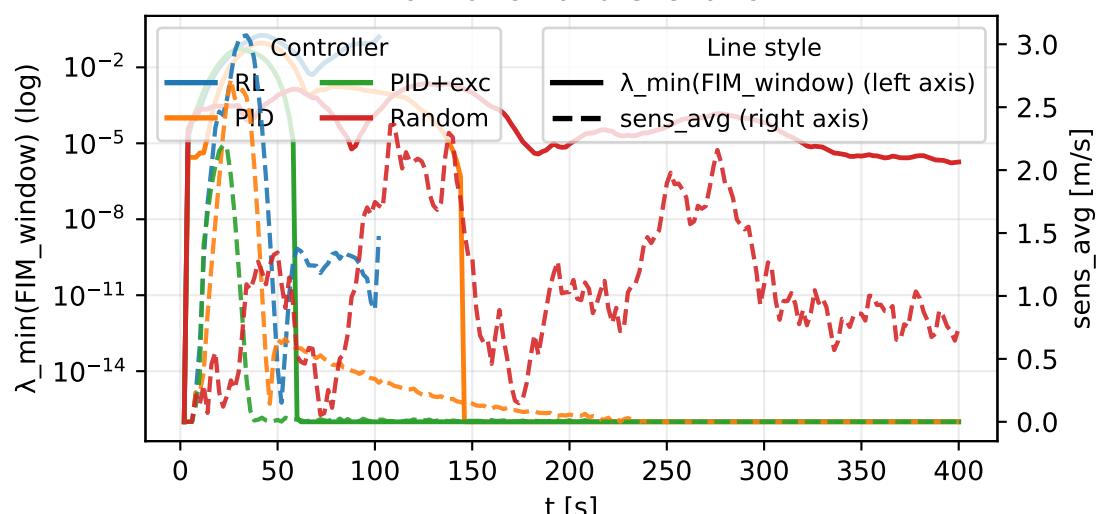
TRUE formation error



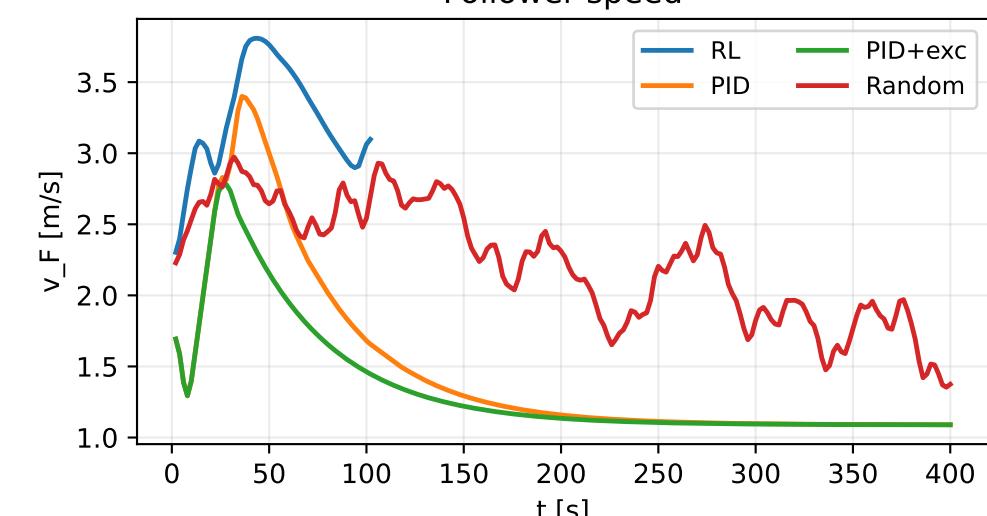
Estimator uncertainty (std_max)



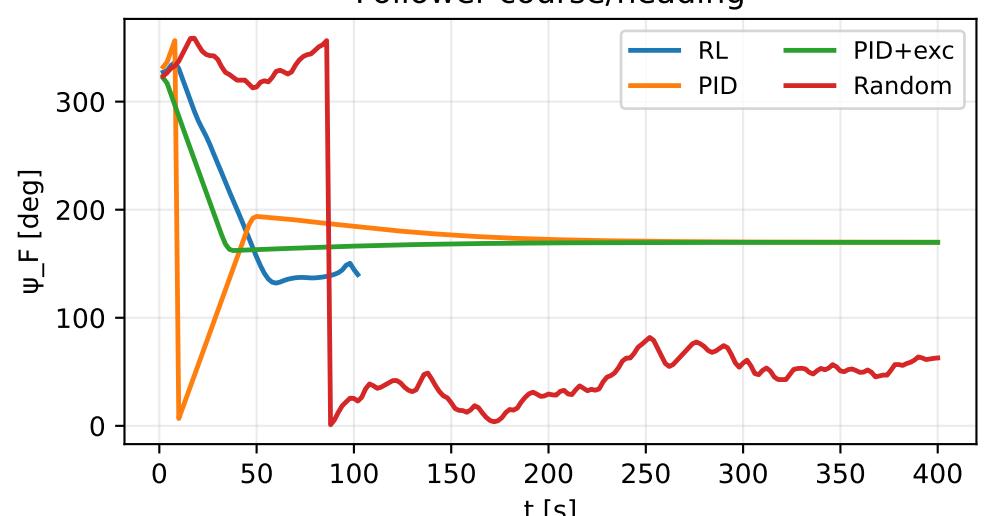
Information and excitation



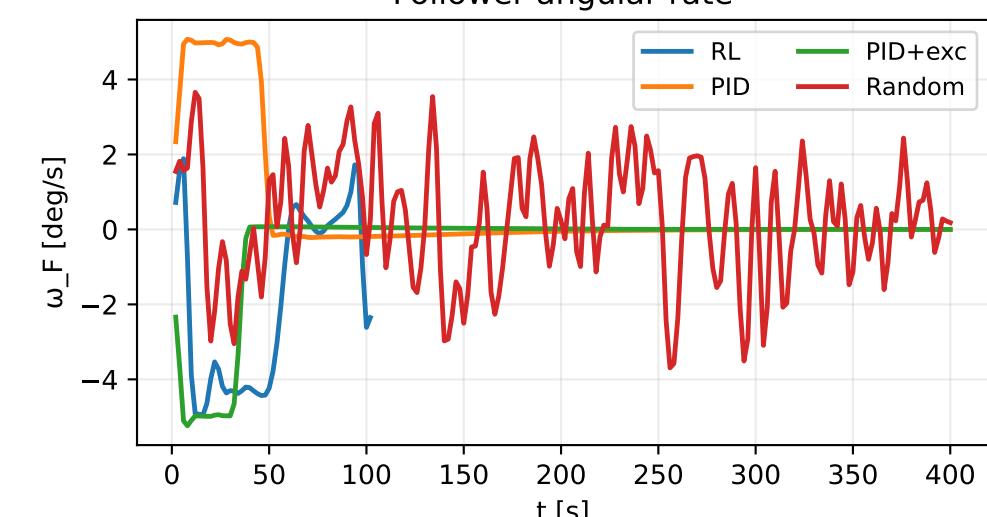
Follower speed



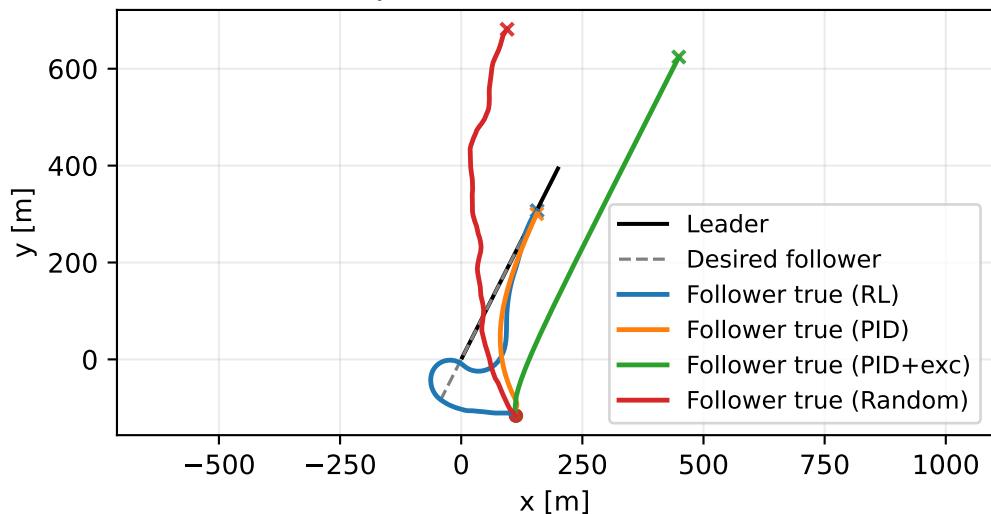
Follower course/heading



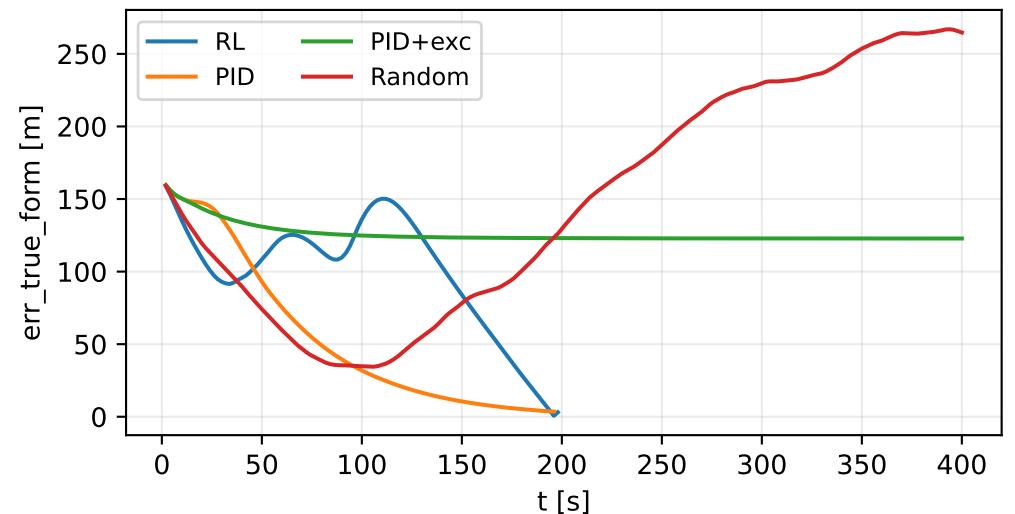
Follower angular rate



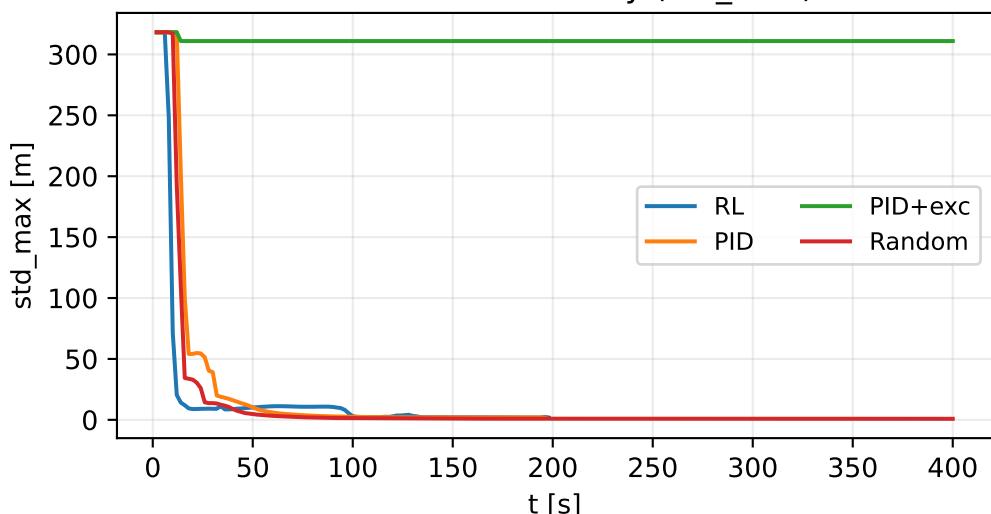
Trajectories (matched seed)



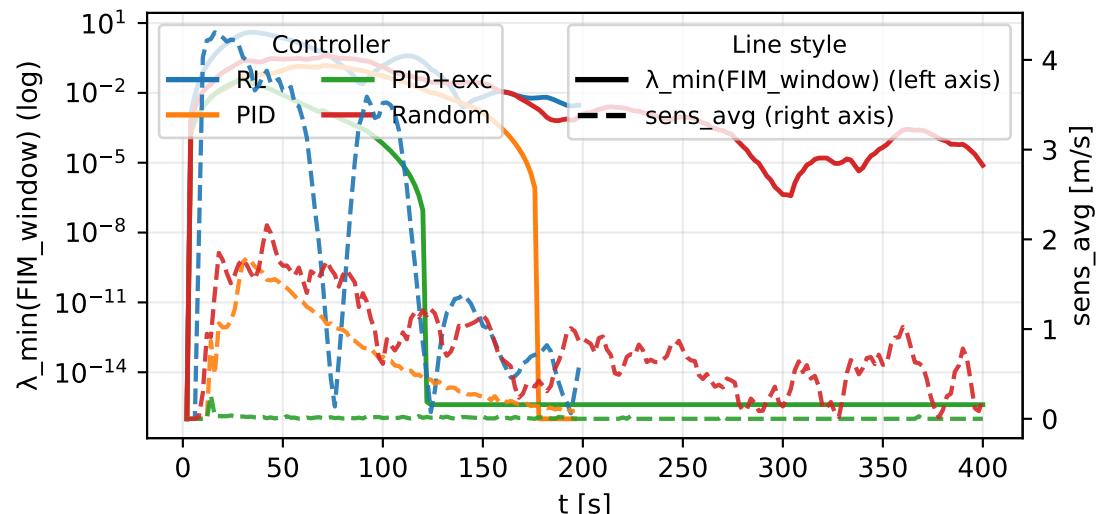
TRUE formation error



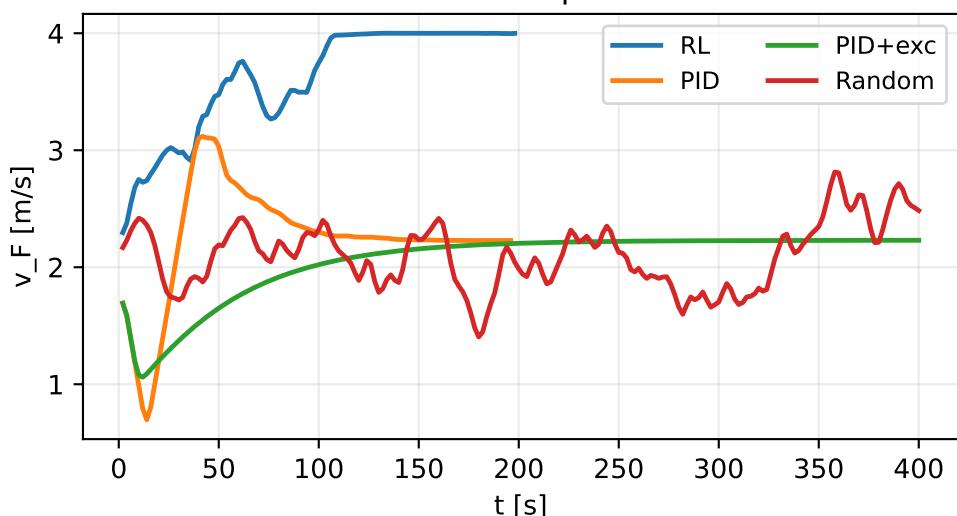
Estimator uncertainty (std_max)



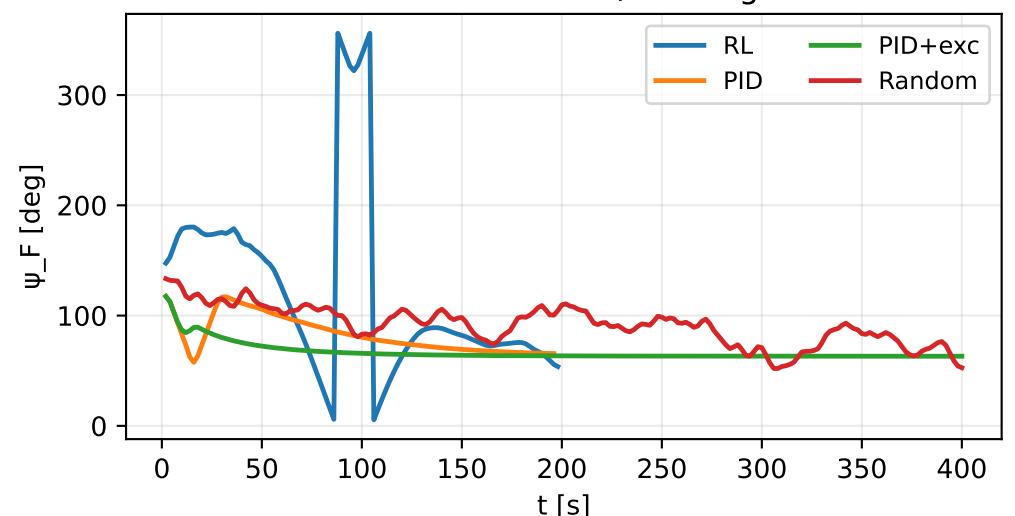
Information and excitation



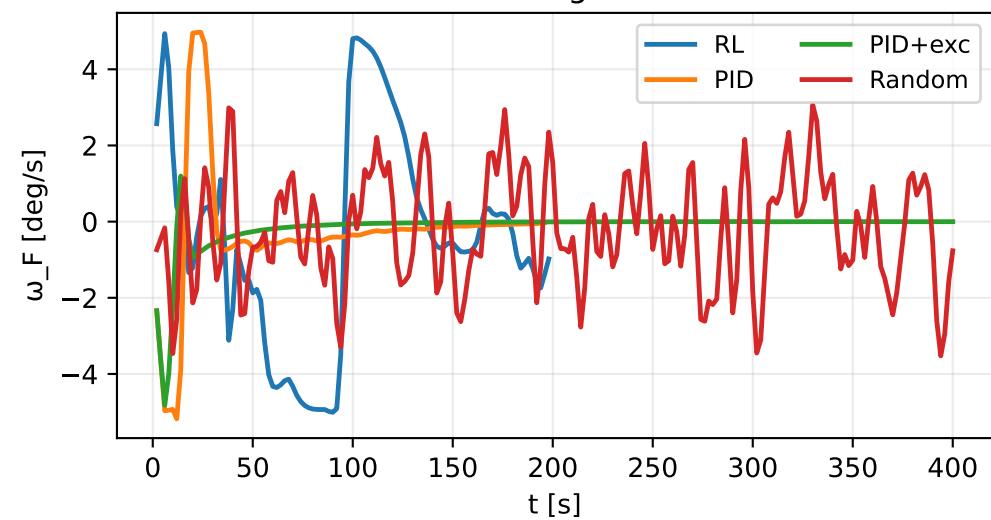
Follower speed



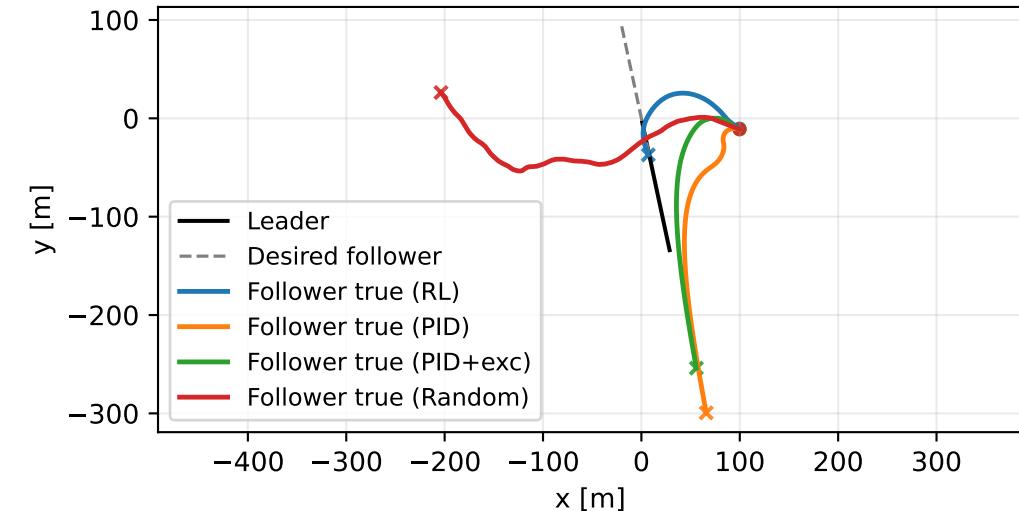
Follower course/heading



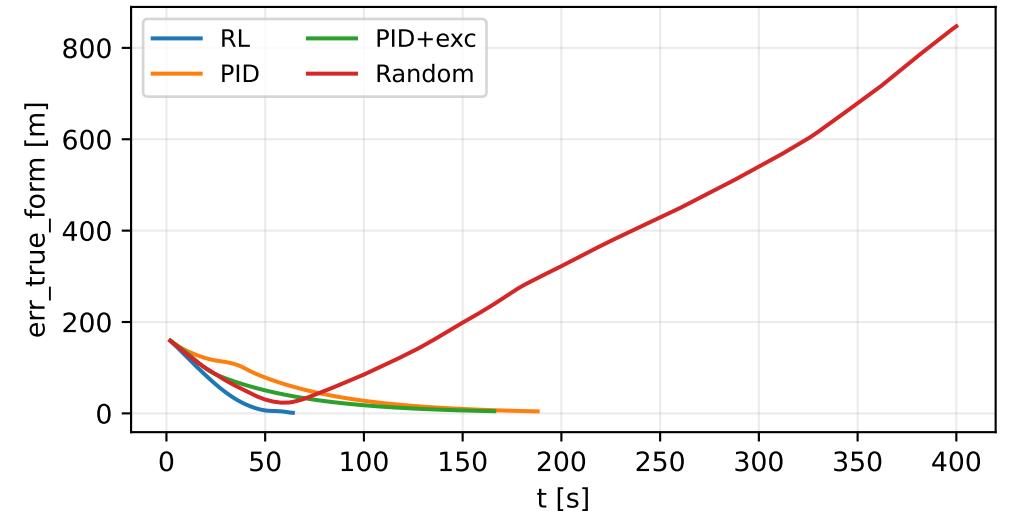
Follower angular rate



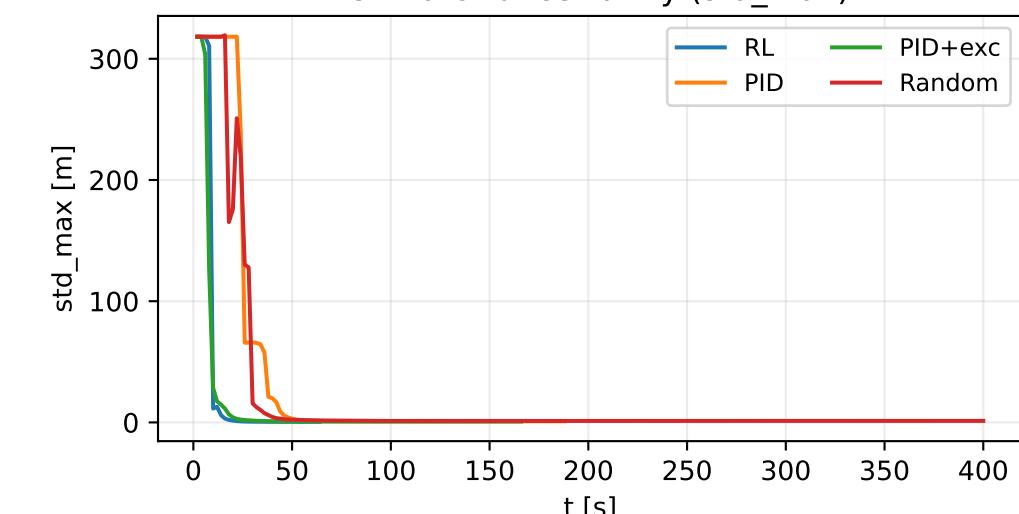
Trajectories (matched seed)



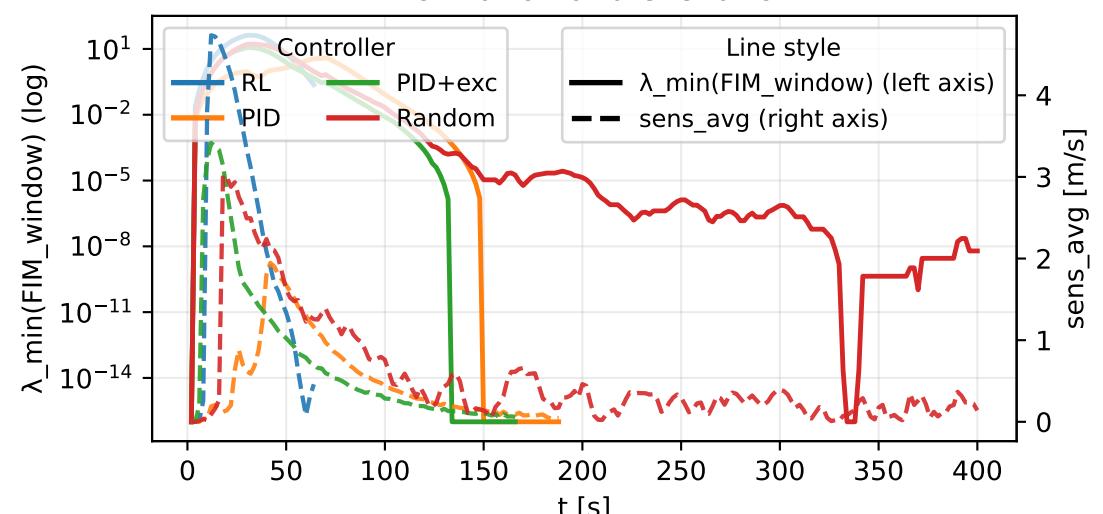
TRUE formation error



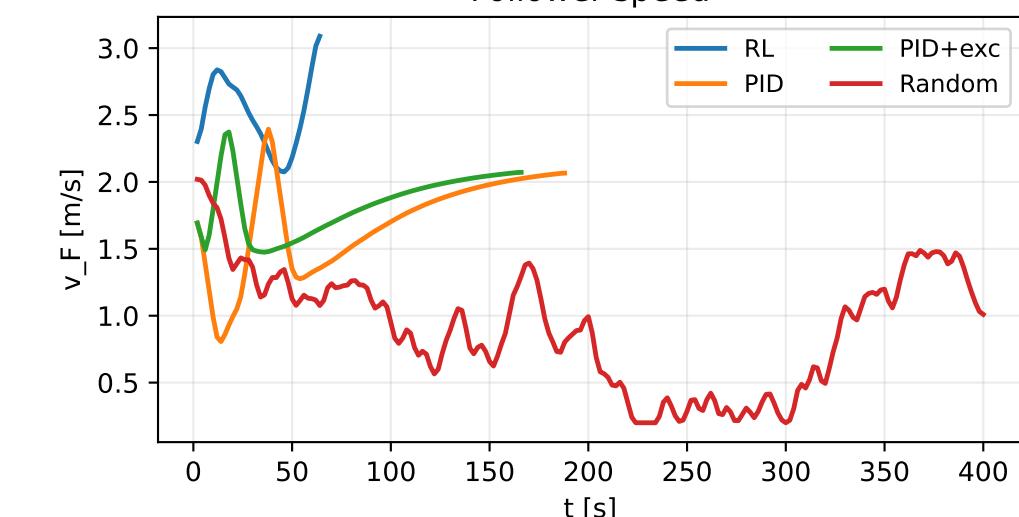
Estimator uncertainty (std_max)



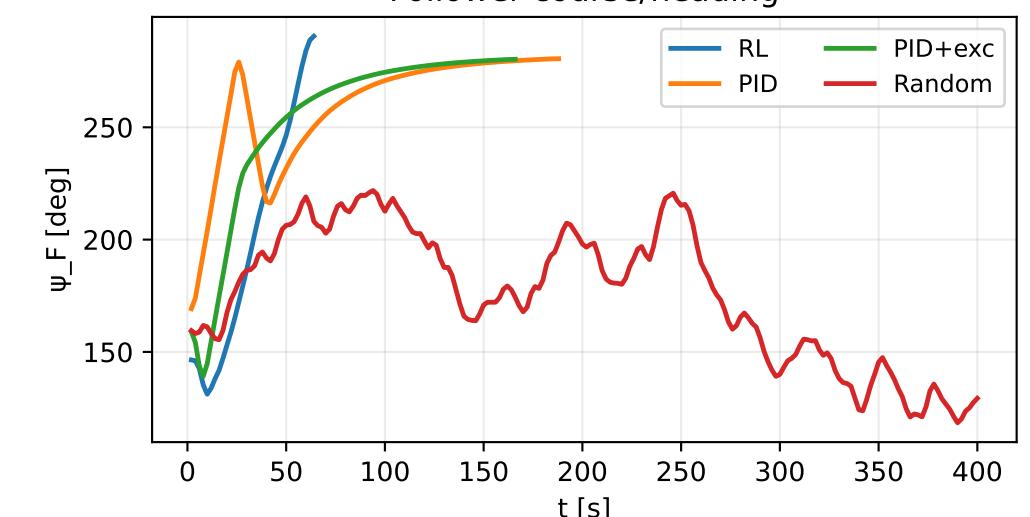
Information and excitation



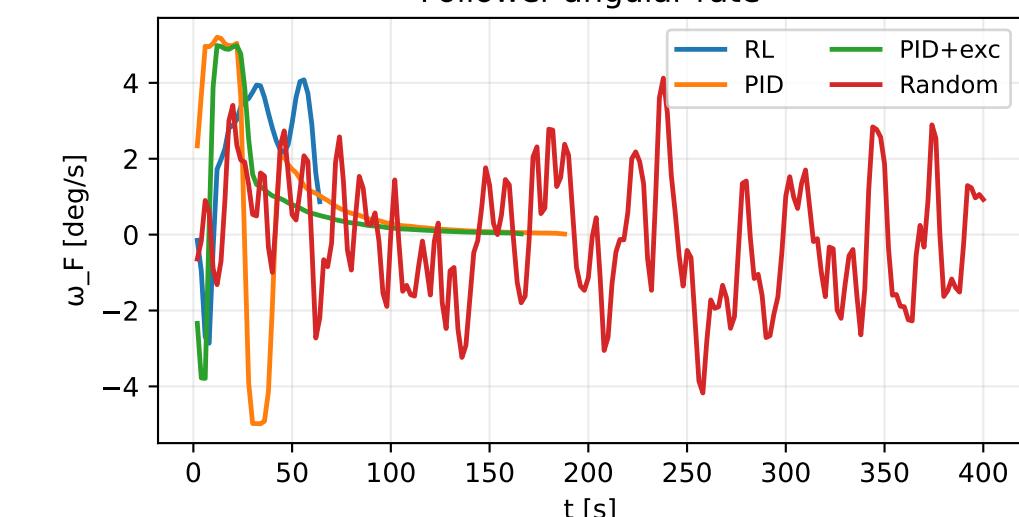
Follower speed



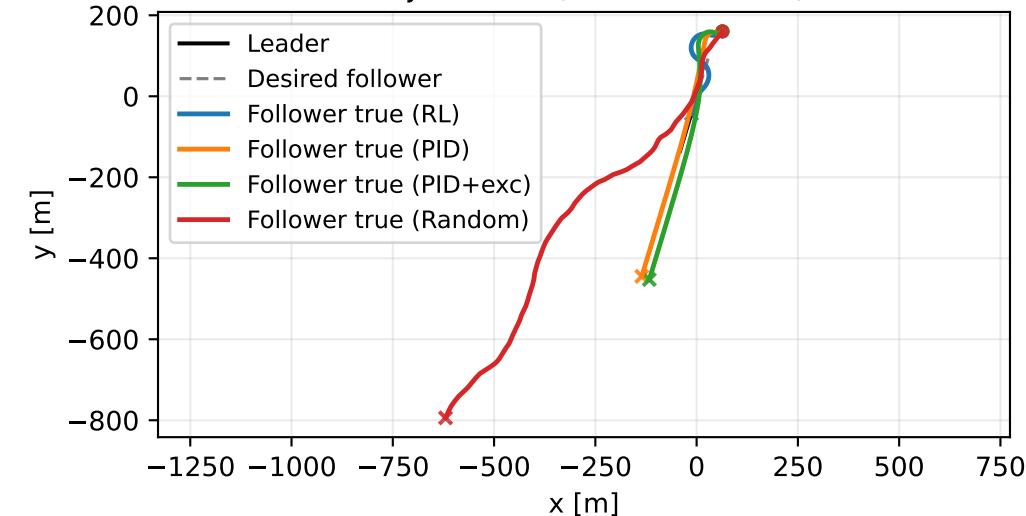
Follower course/heading



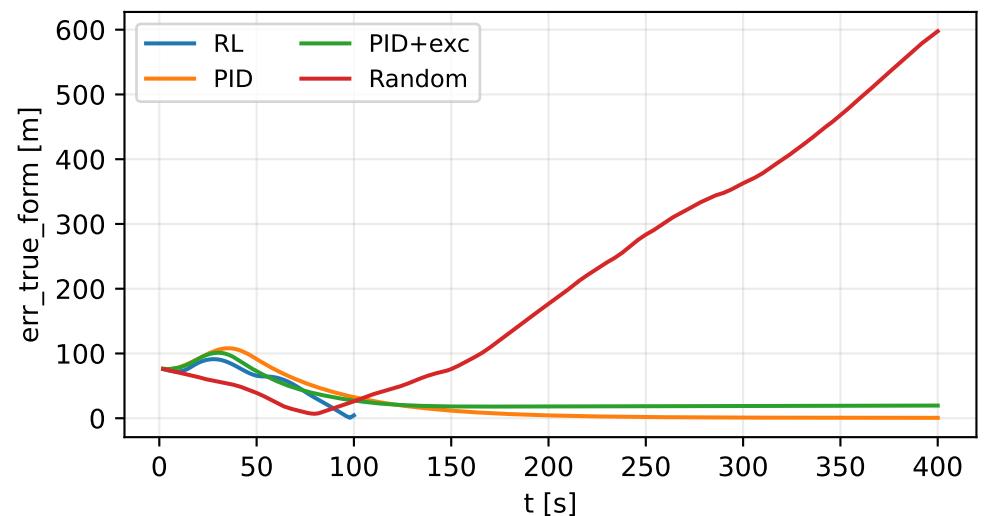
Follower angular rate



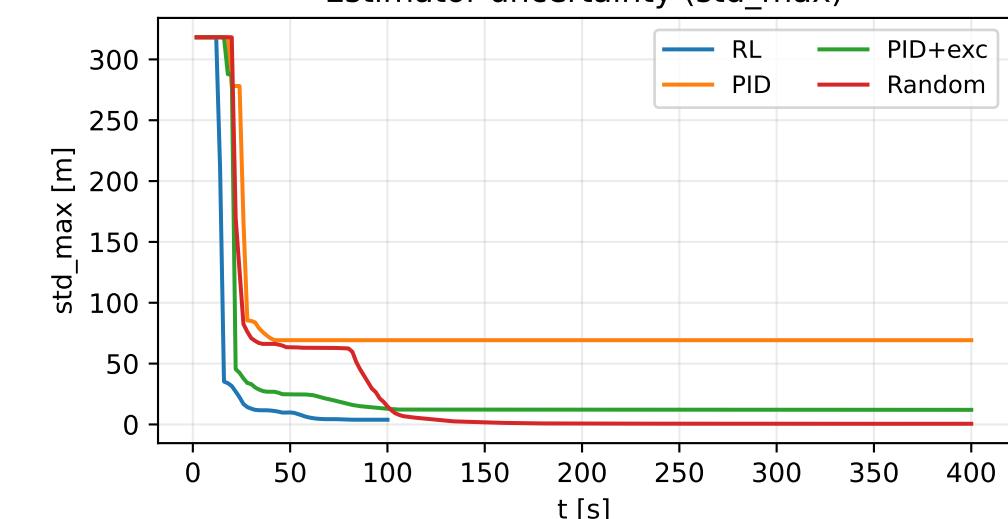
Trajectories (matched seed)



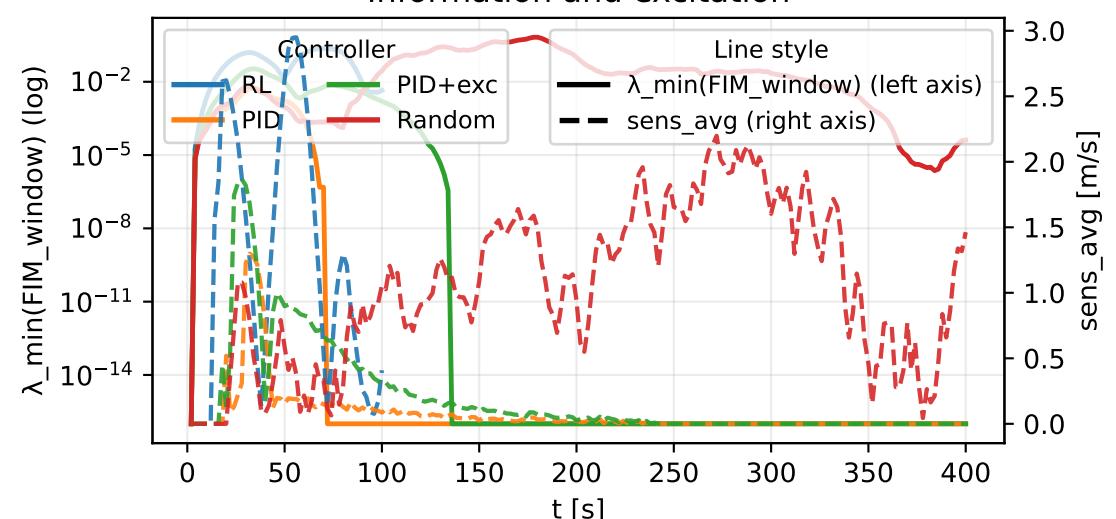
TRUE formation error



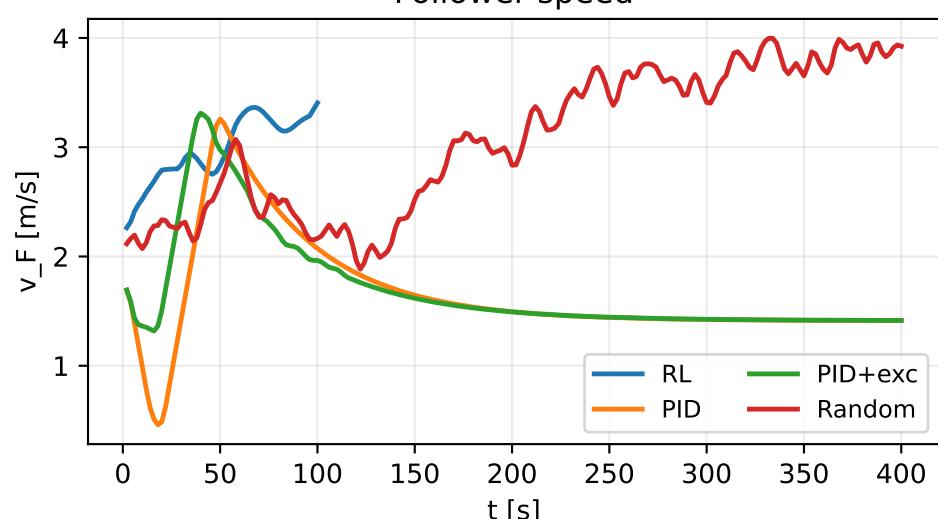
Estimator uncertainty (std_max)



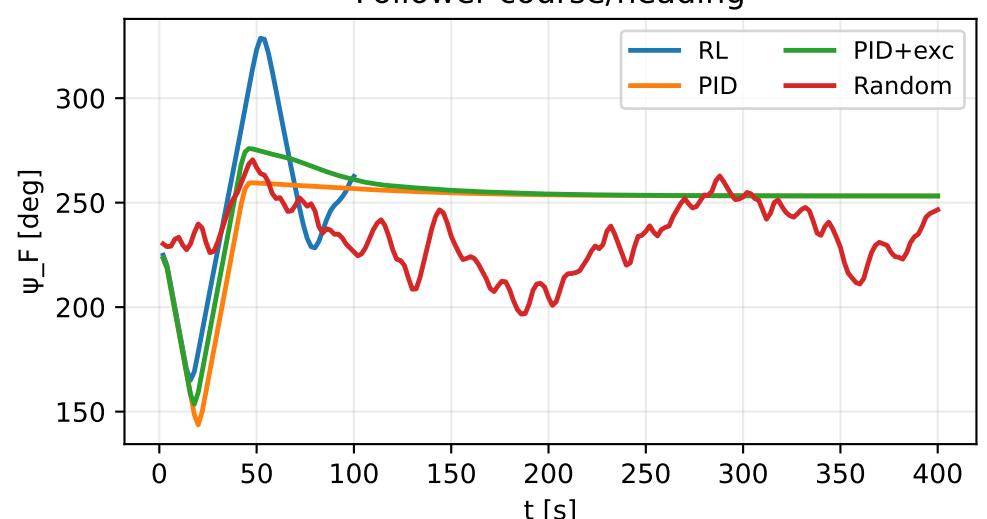
Information and excitation



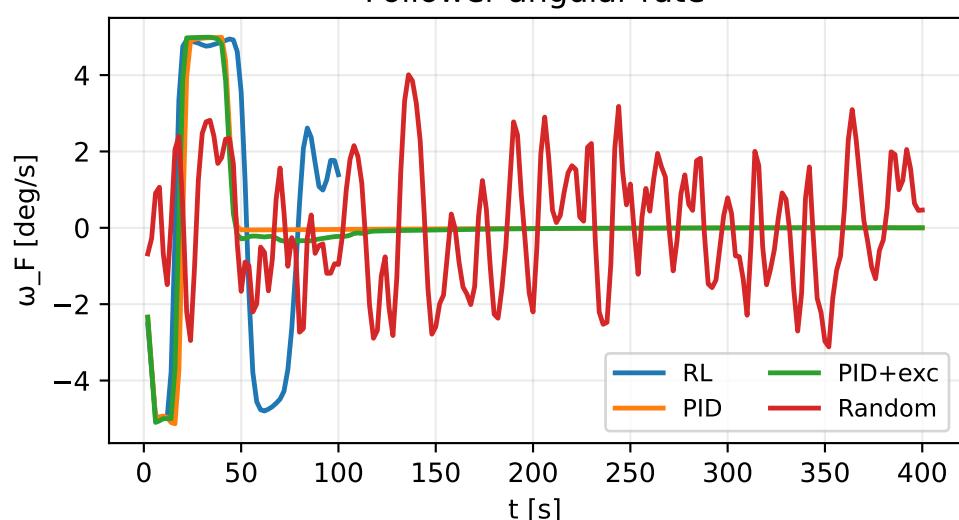
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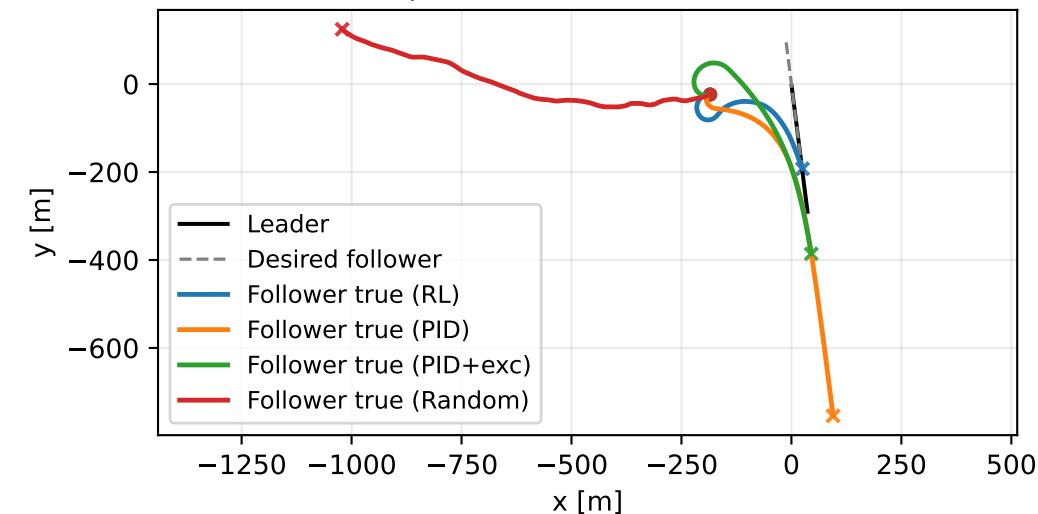
Follower course/heading



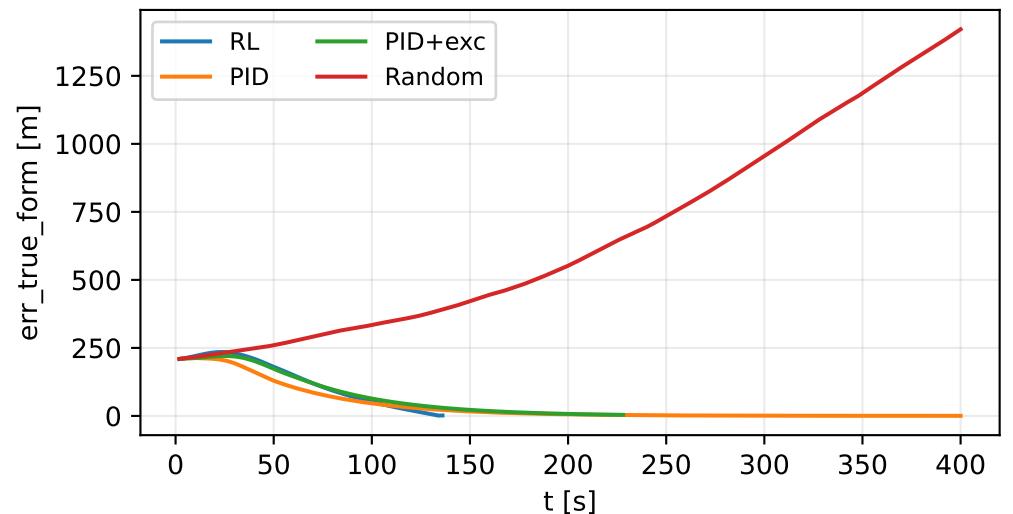
Follower angular rate



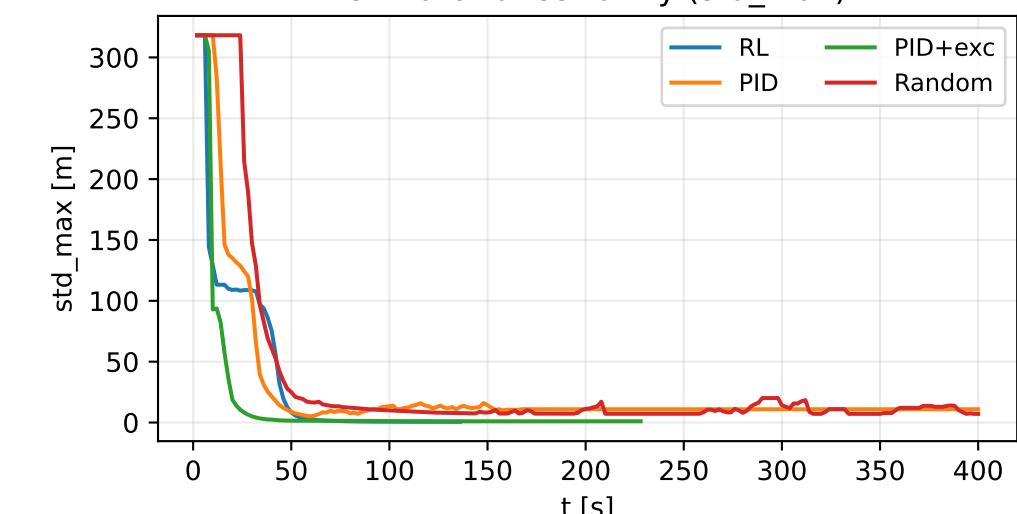
Trajectories (matched seed)



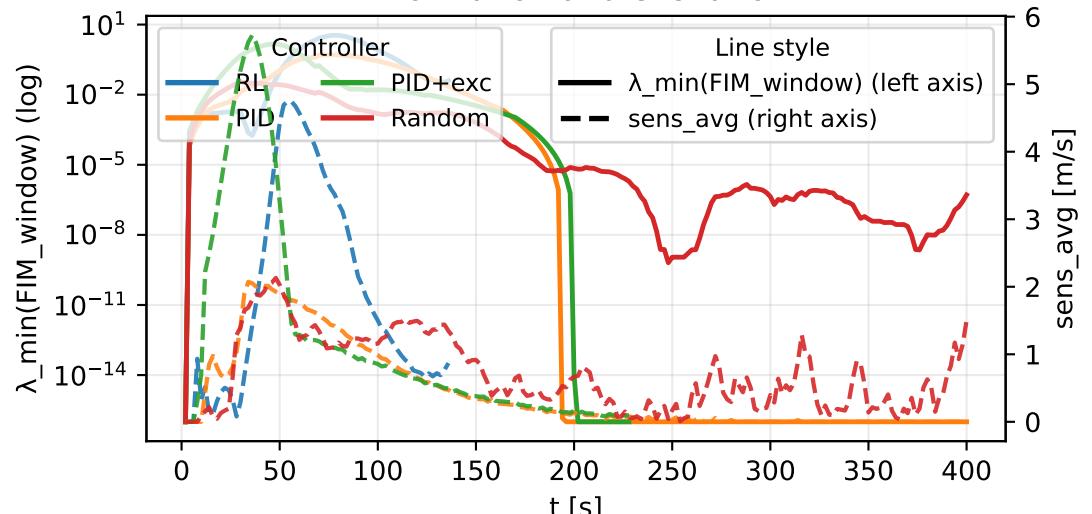
TRUE formation error



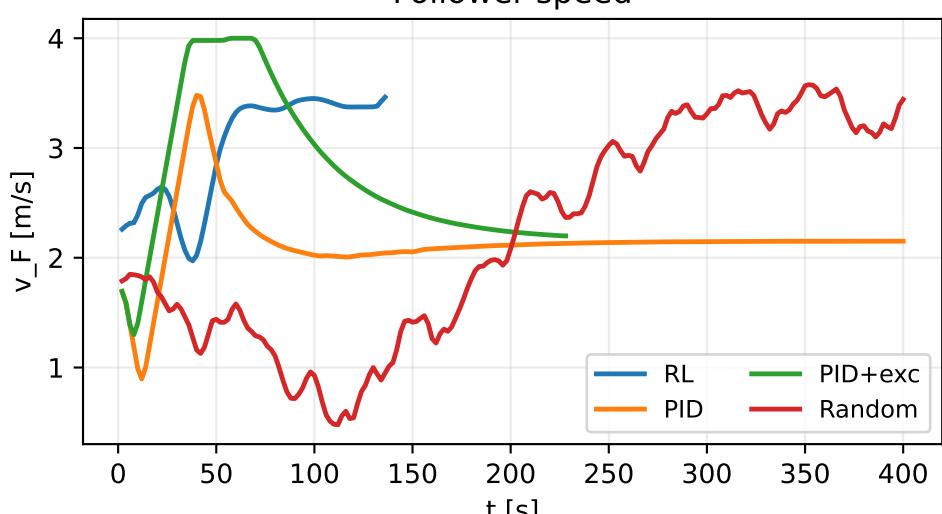
Estimator uncertainty (std_max)



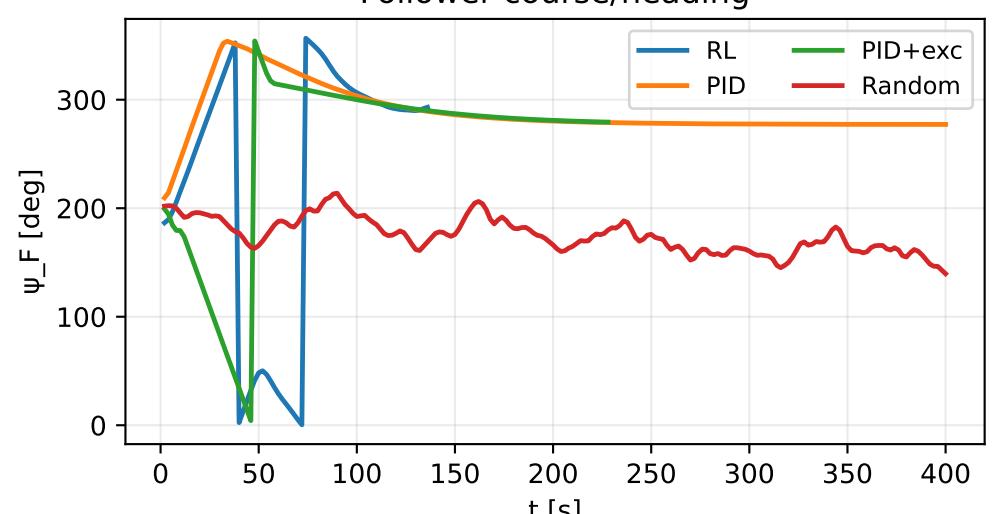
Information and excitation



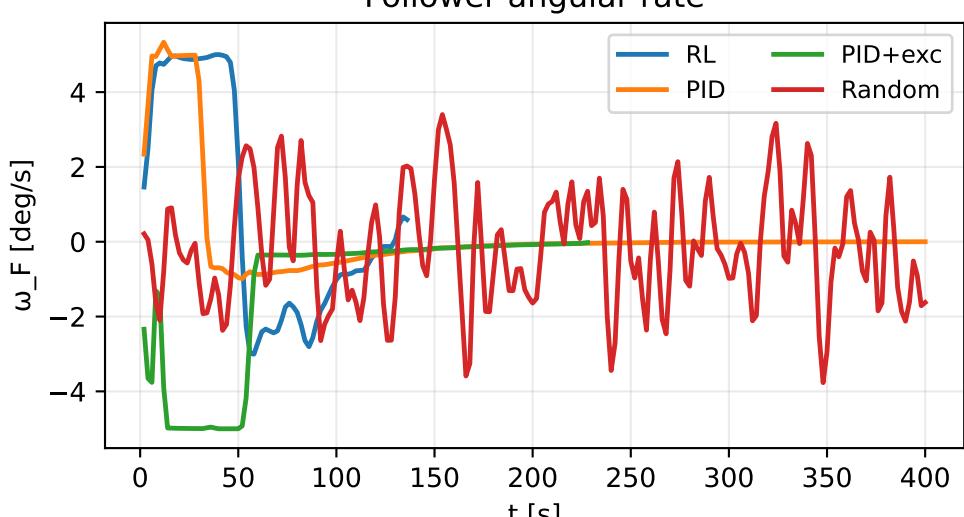
Follower speed



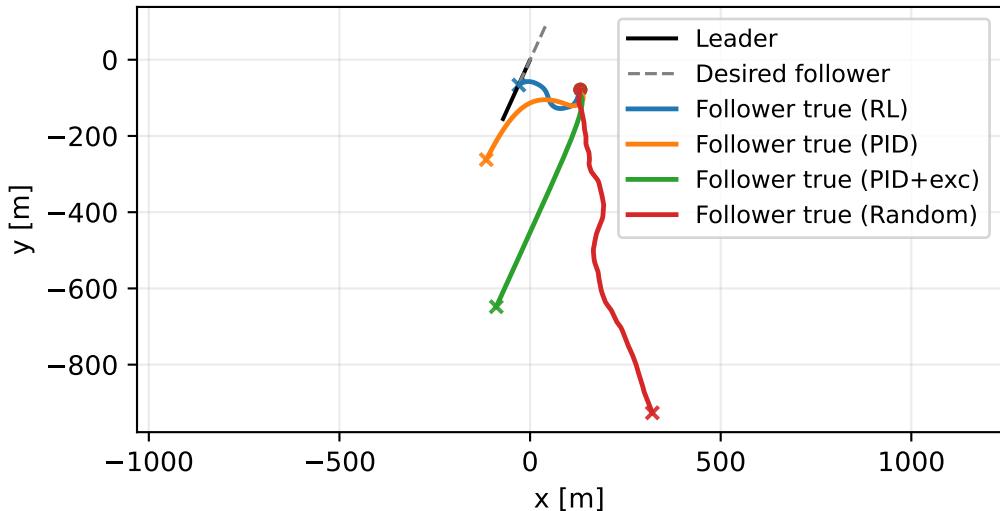
Follower course/heading



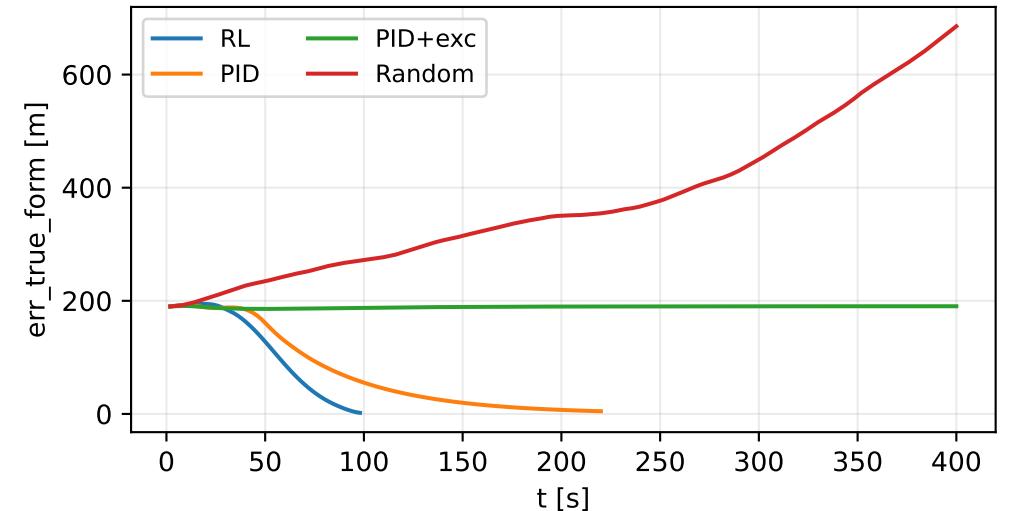
Follower angular rate



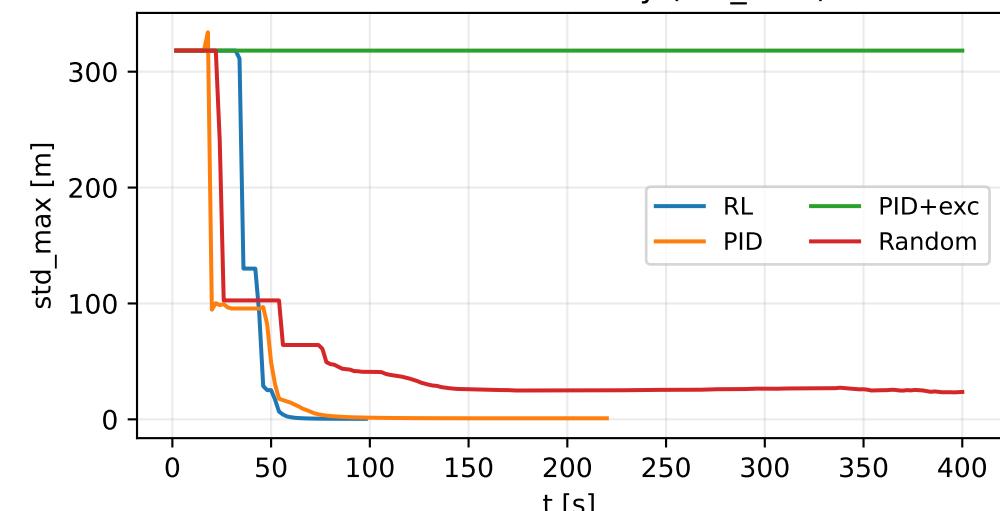
Trajectories (matched seed)



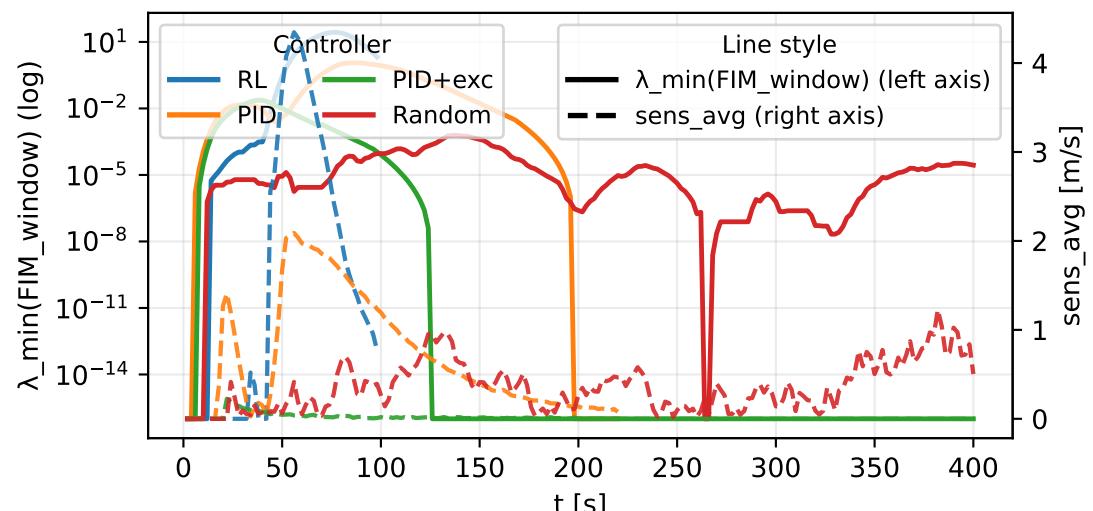
TRUE formation error



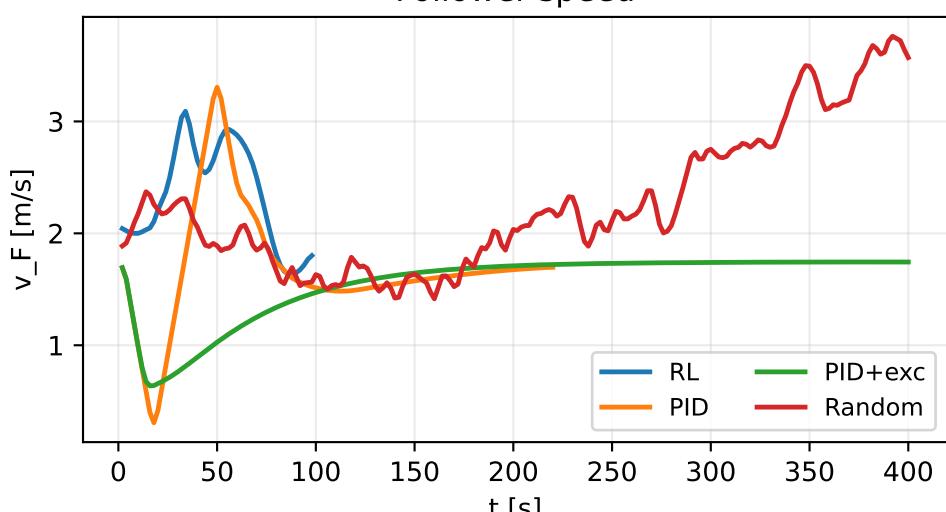
Estimator uncertainty (std_max)



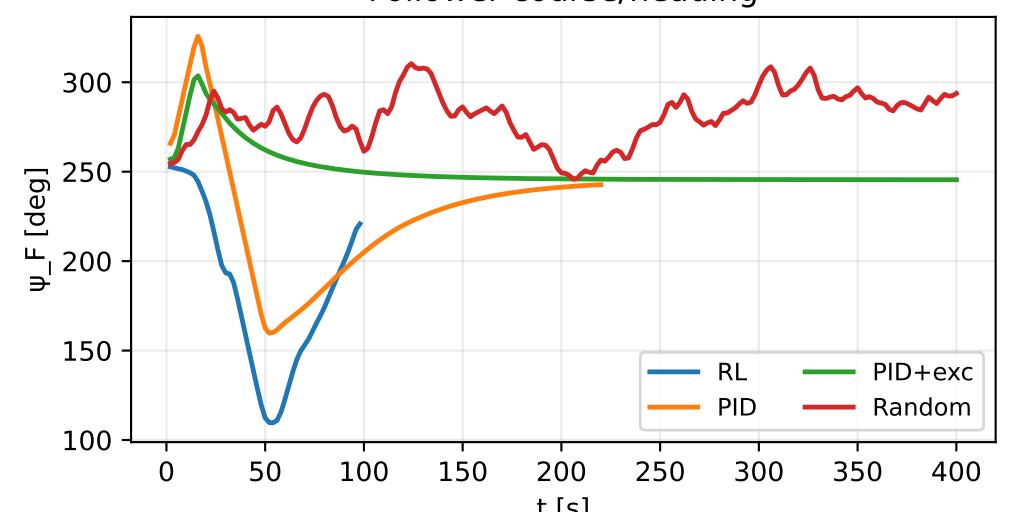
Information and excitation



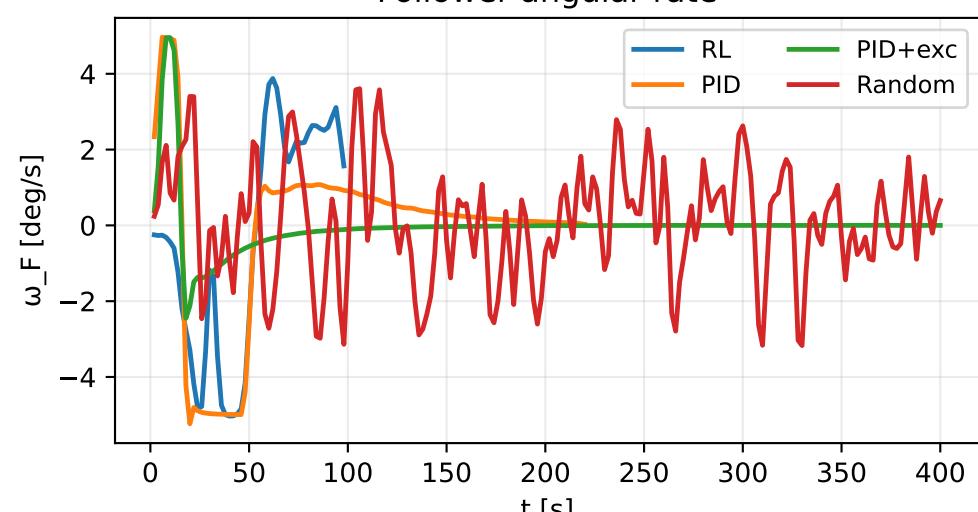
Follower speed



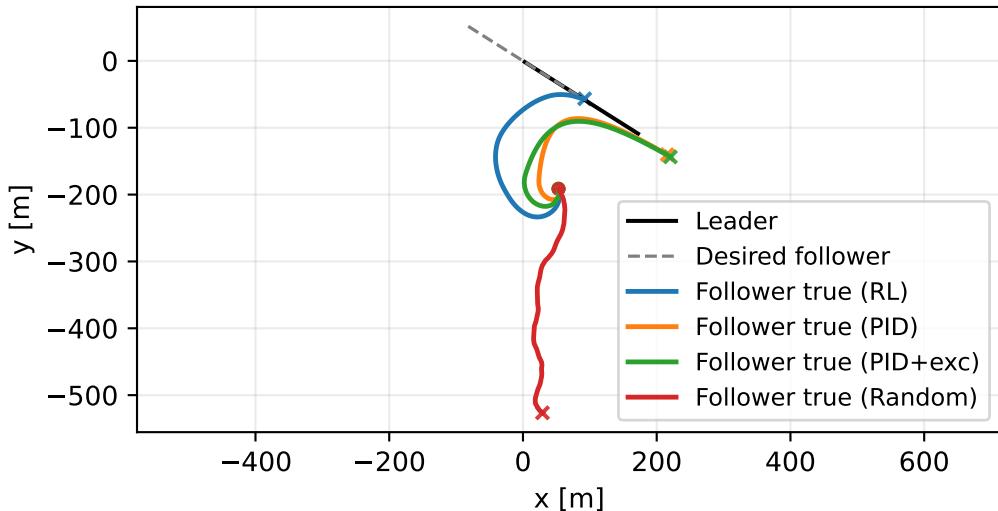
Follower course/heading



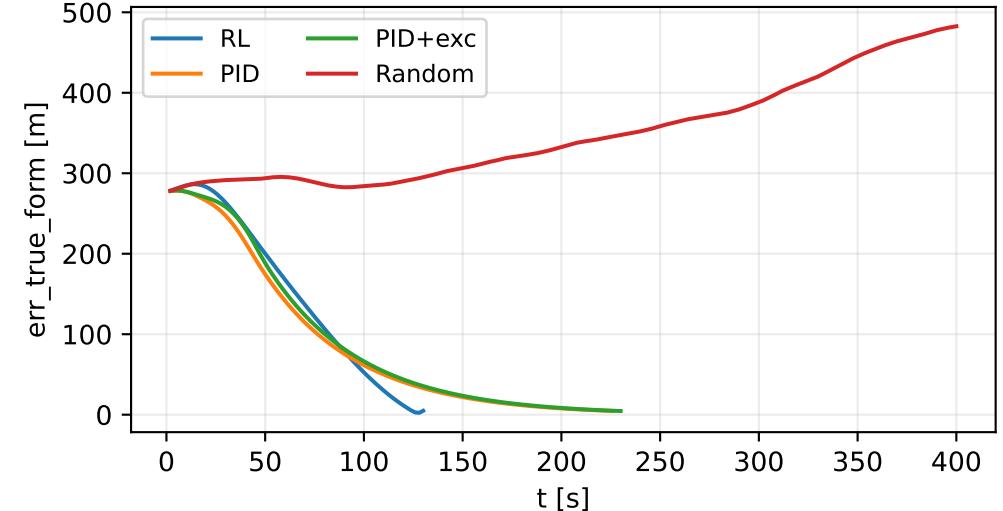
Follower angular rate



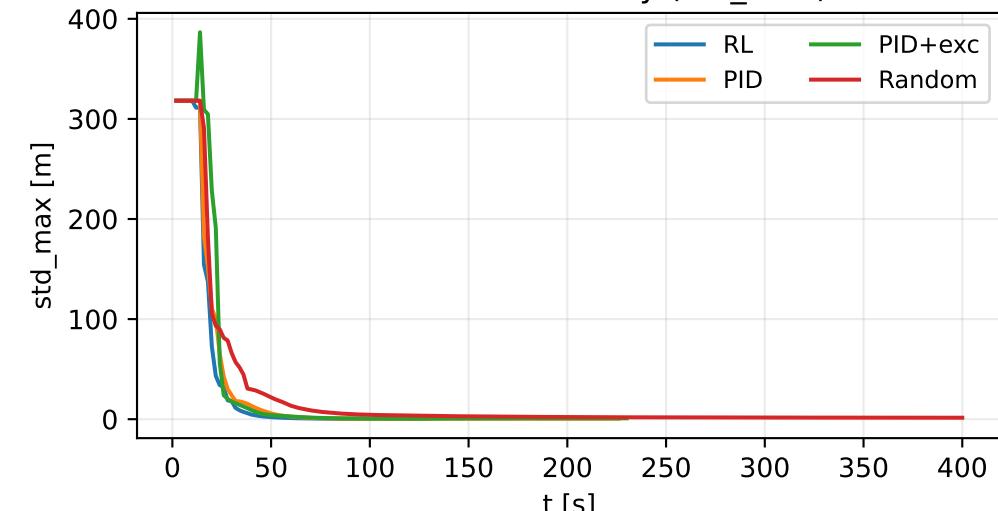
Trajectories (matched seed)



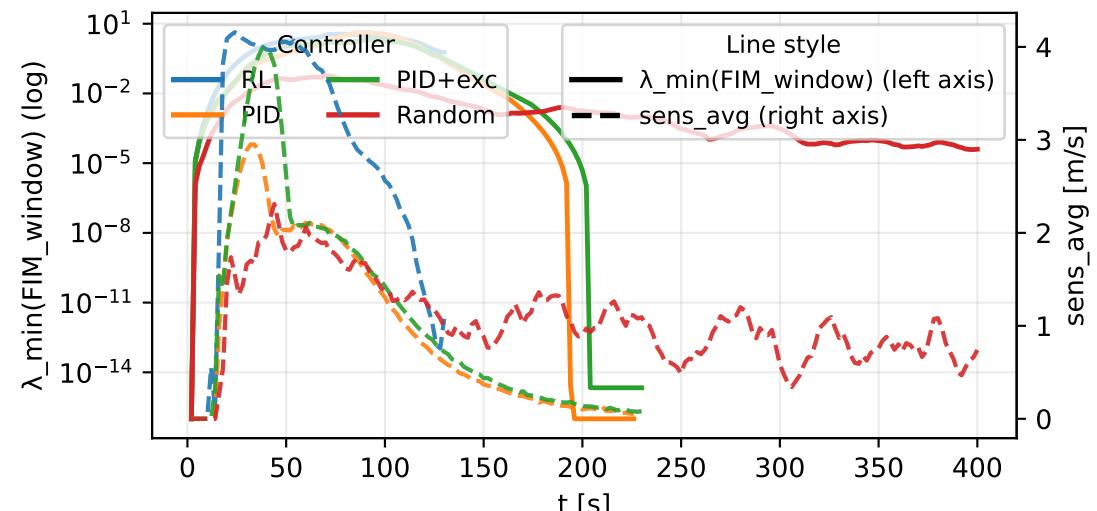
TRUE formation error



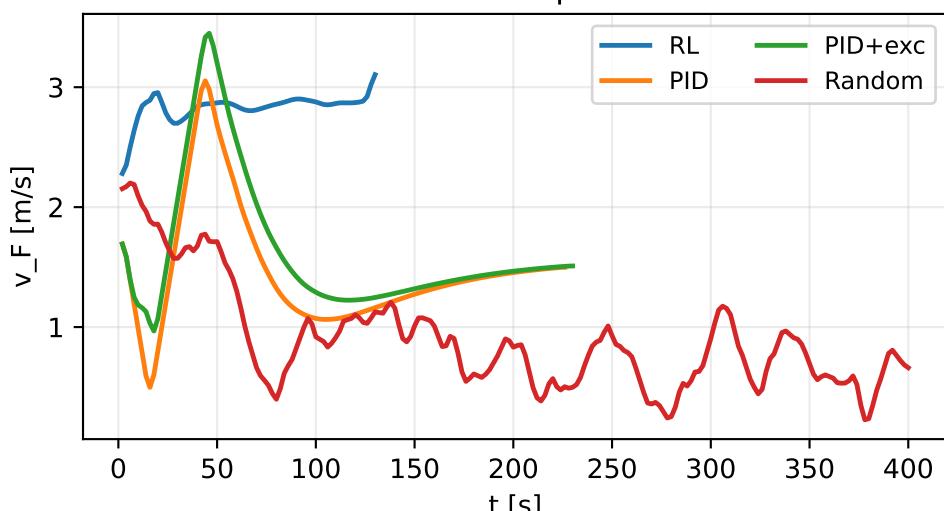
Estimator uncertainty (std_max)



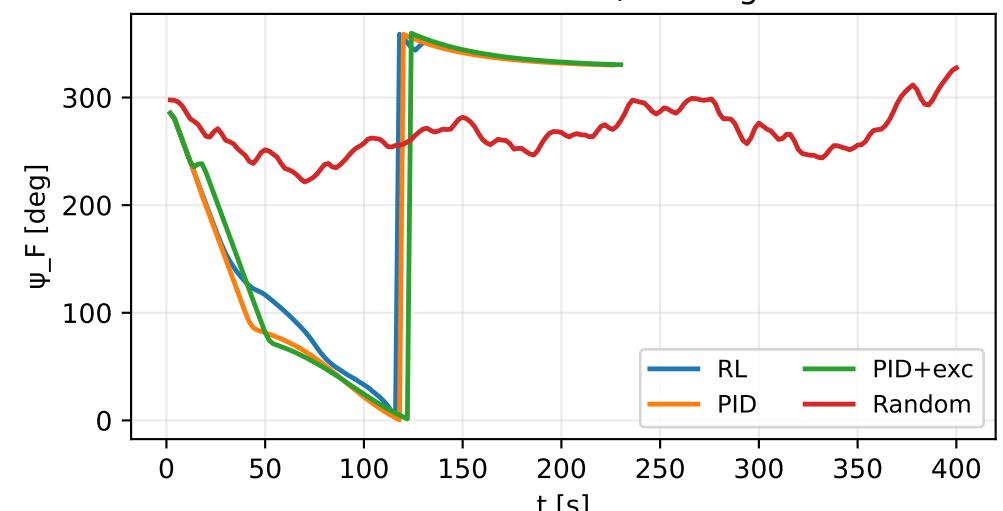
Information and excitation



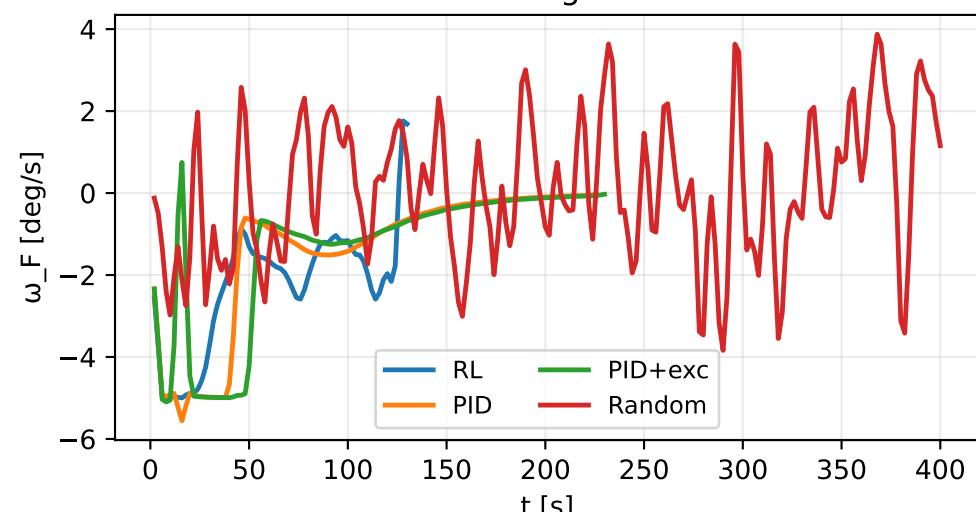
Follower speed



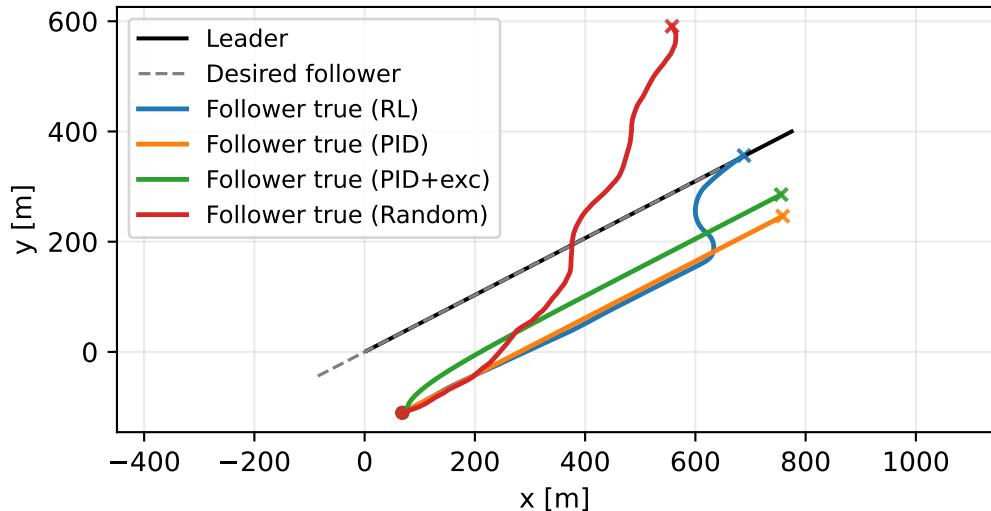
Follower course/heading



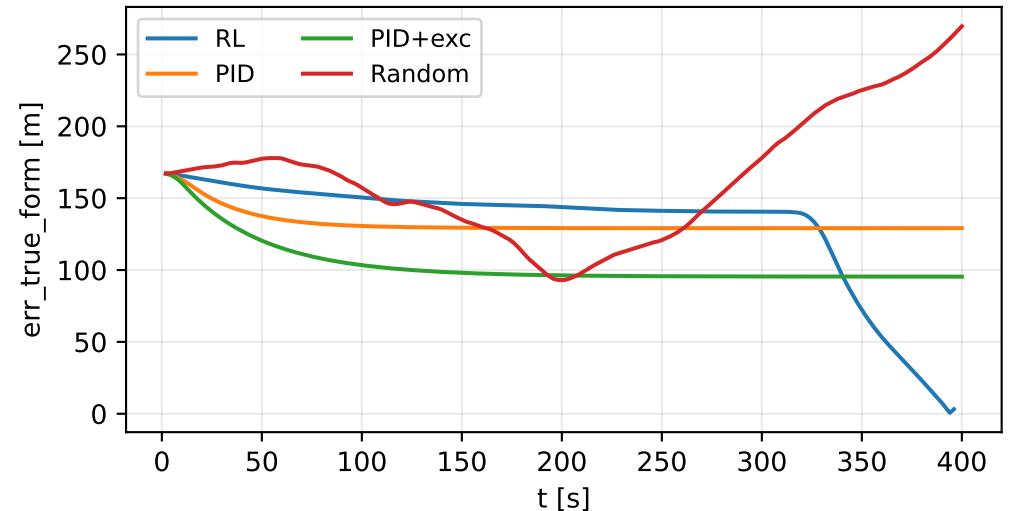
Follower angular rate



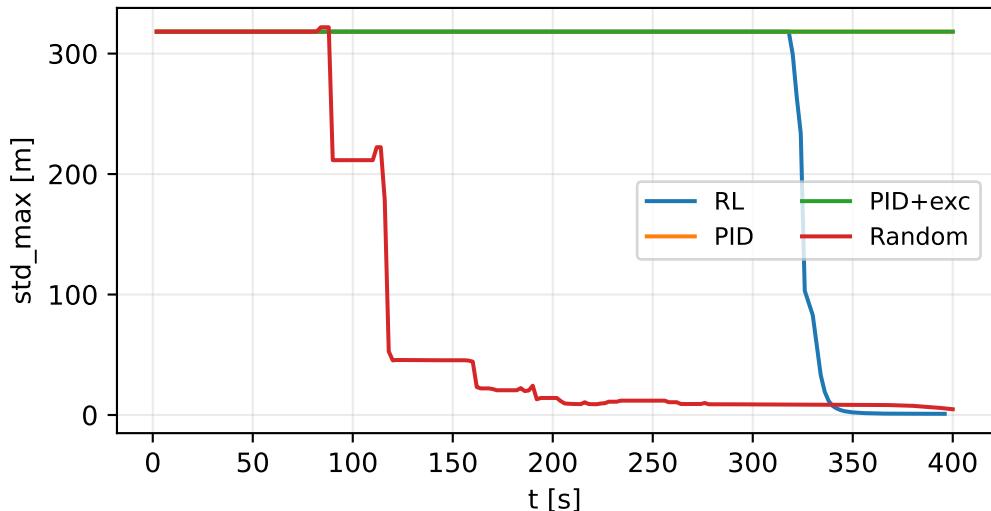
Trajectories (matched seed)



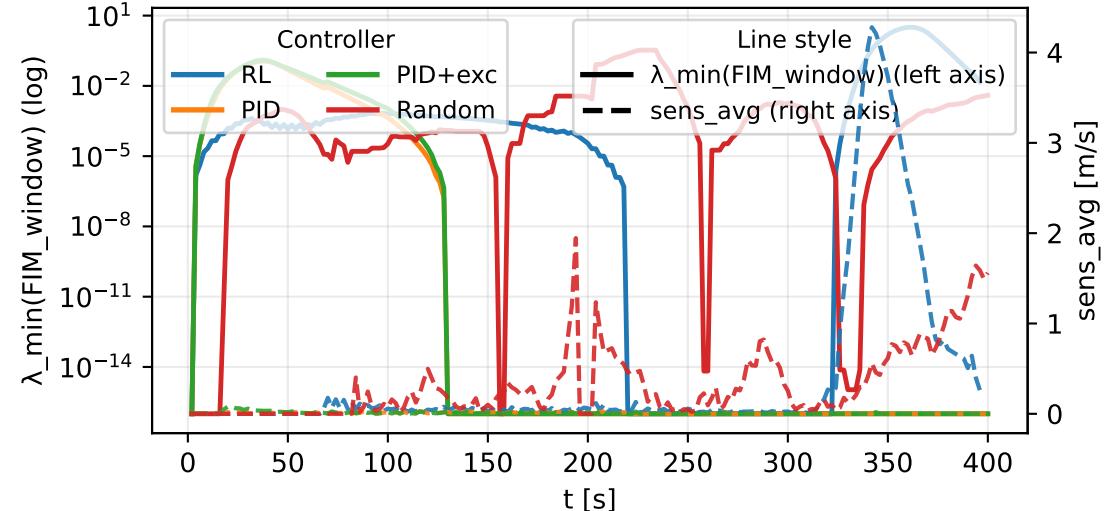
TRUE formation error



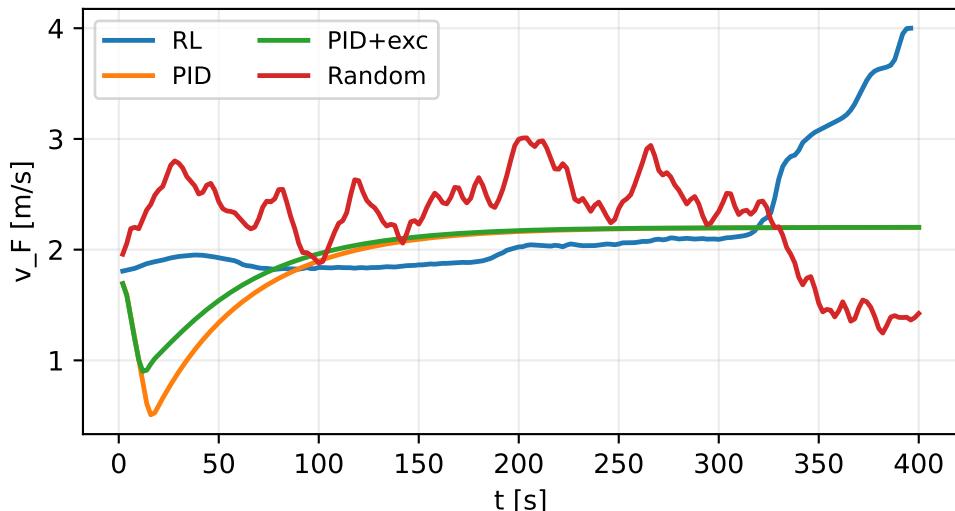
Estimator uncertainty (std_max)



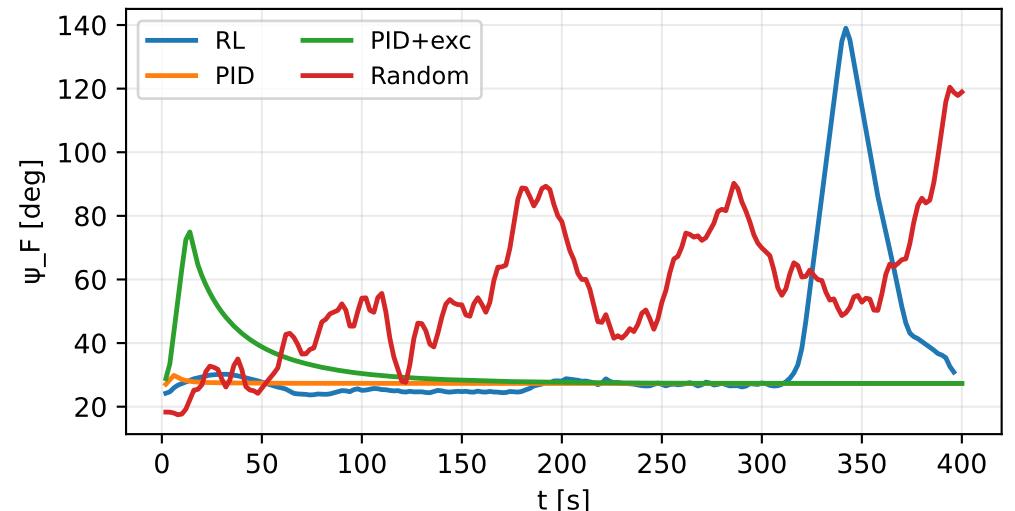
Information and excitation



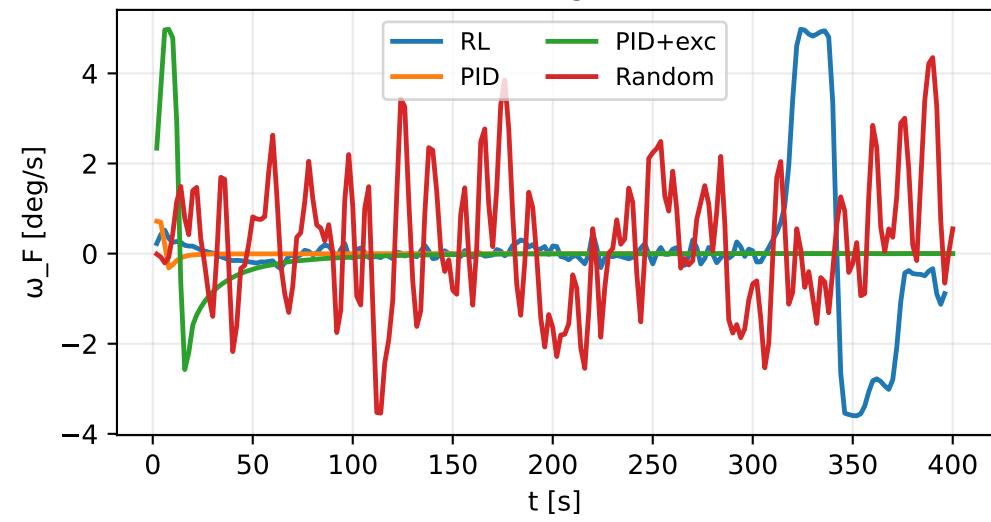
Follower speed



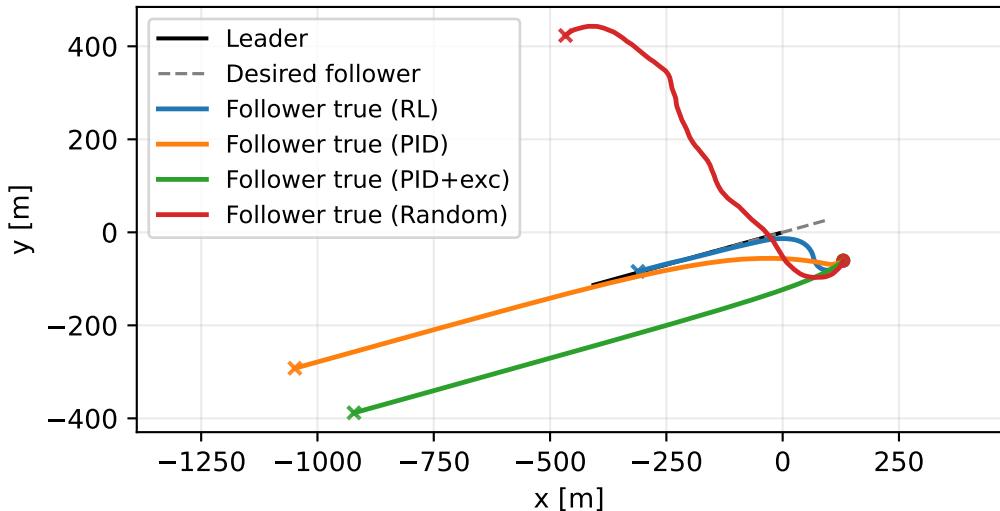
Follower course/heading



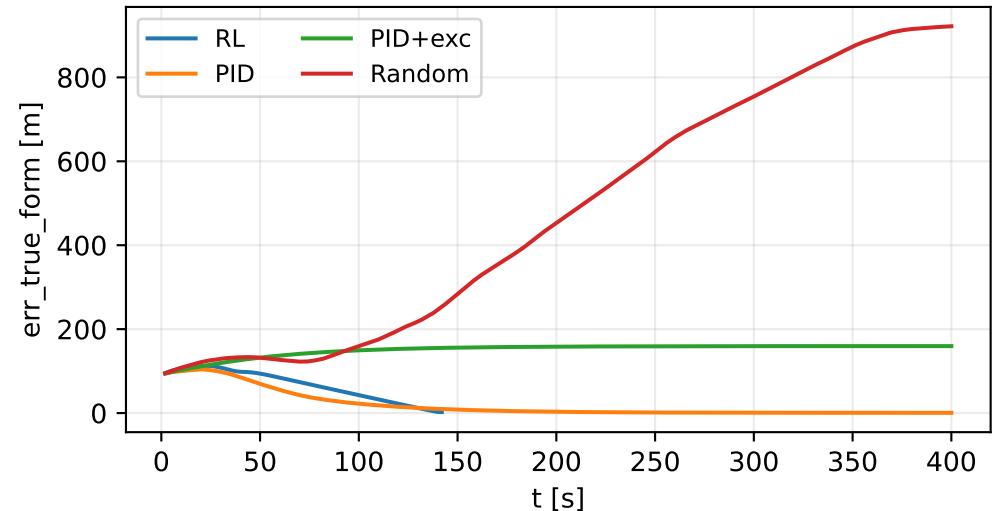
Follower angular rate



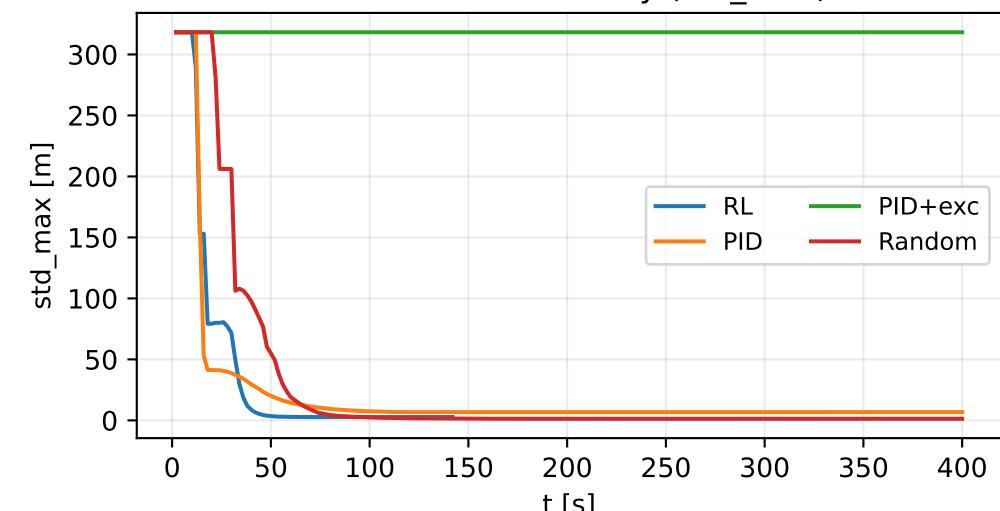
Trajectories (matched seed)



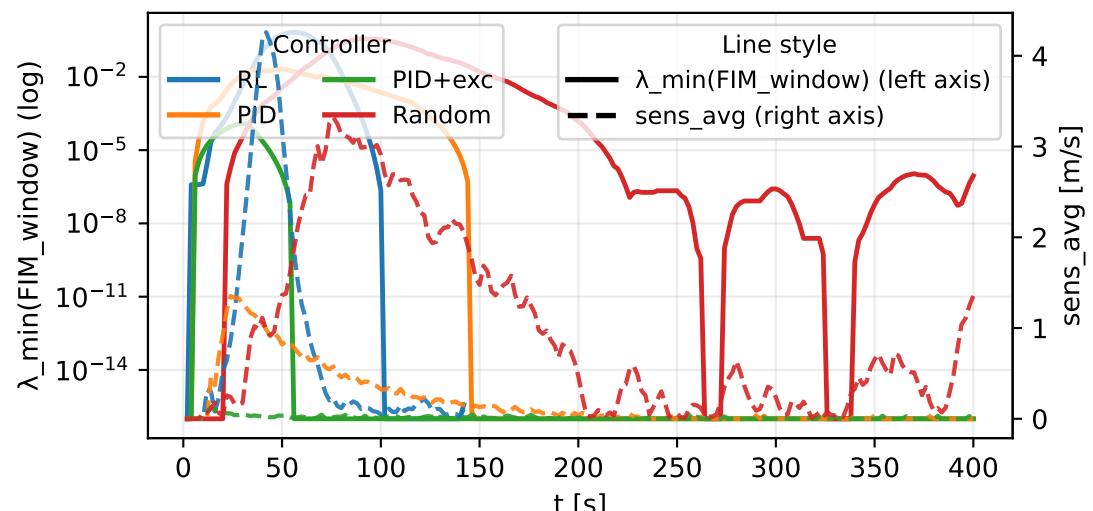
TRUE formation error



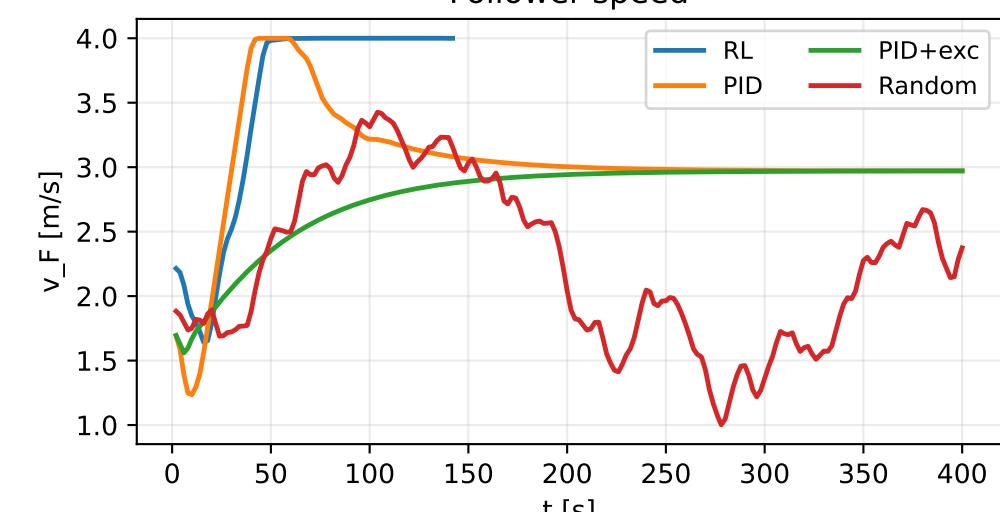
Estimator uncertainty (std_max)



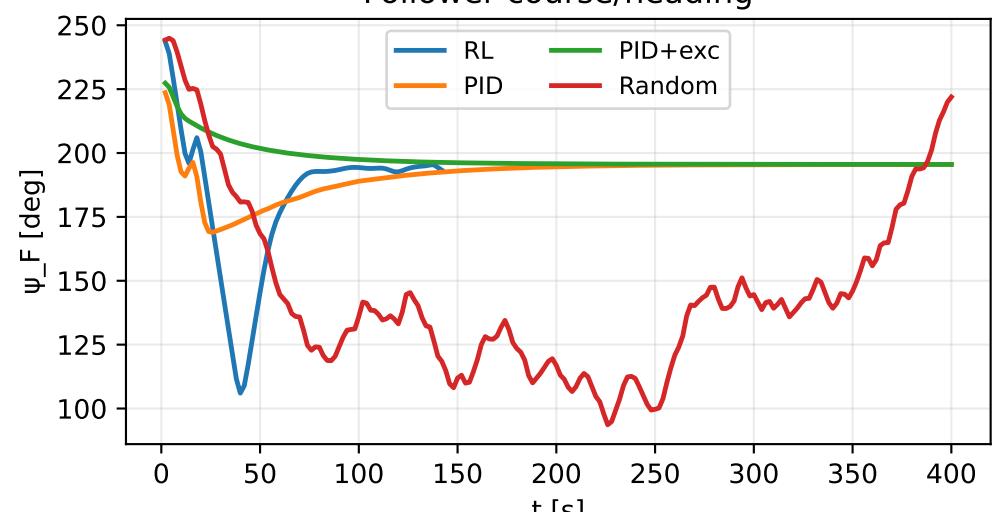
Information and excitation



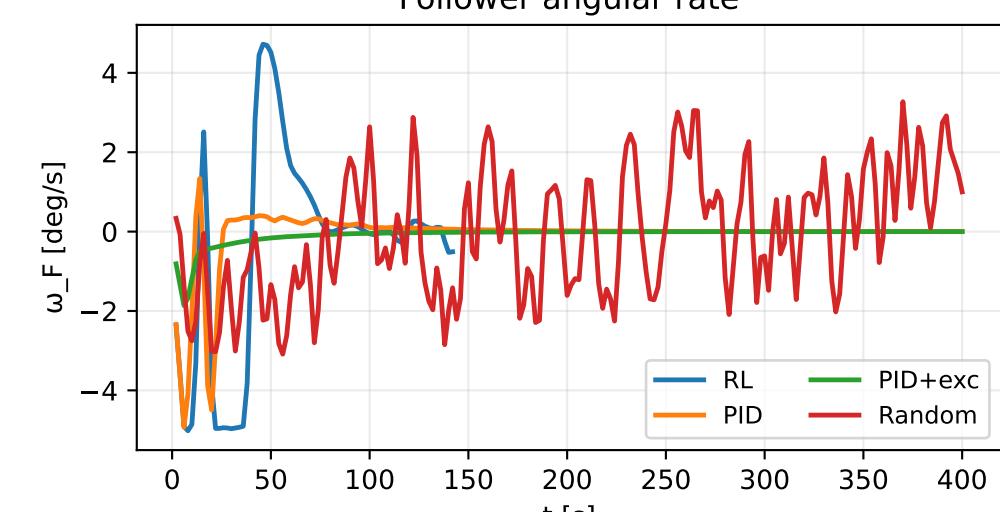
Follower speed



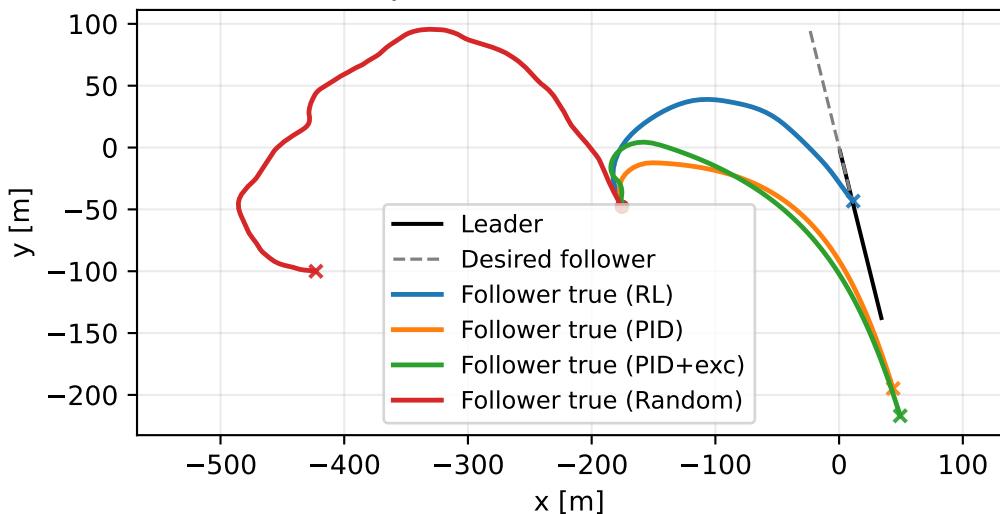
Follower course/heading



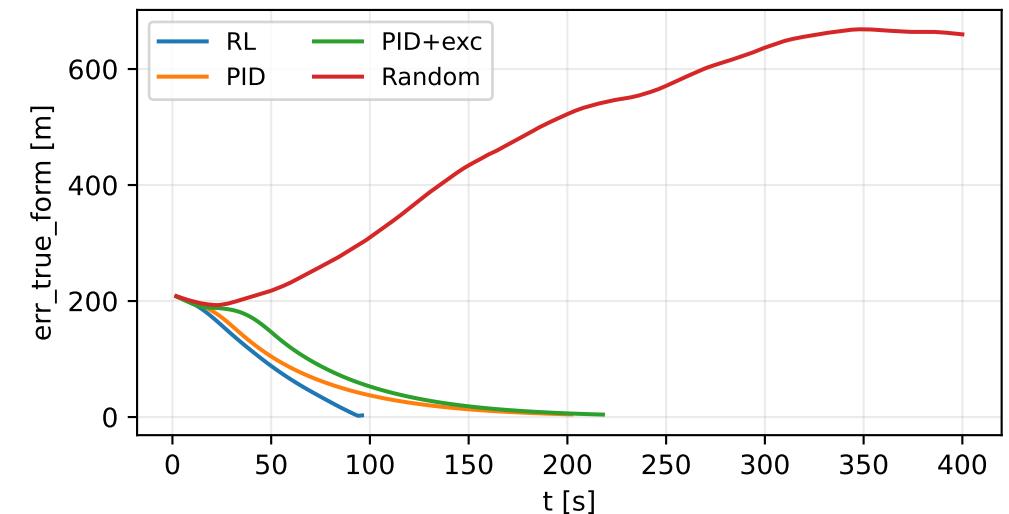
Follower angular rate



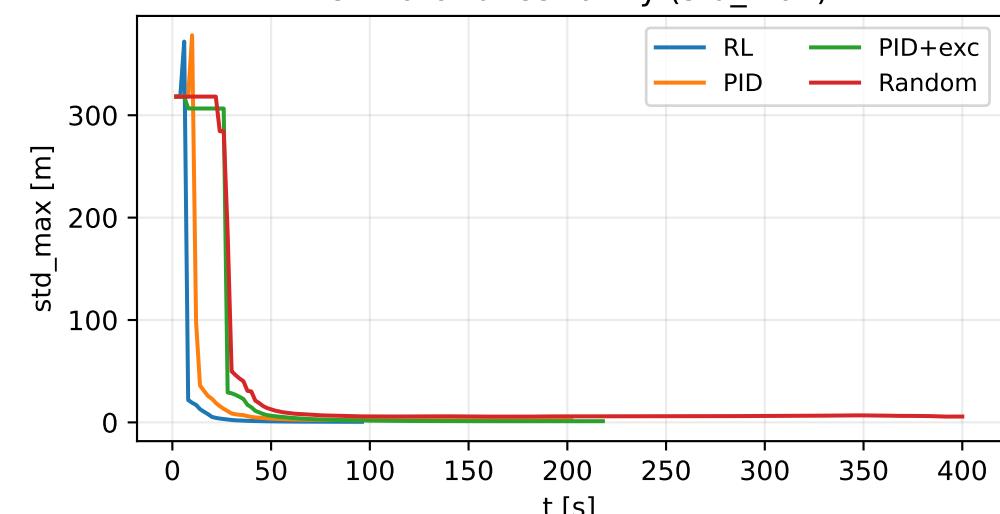
Trajectories (matched seed)



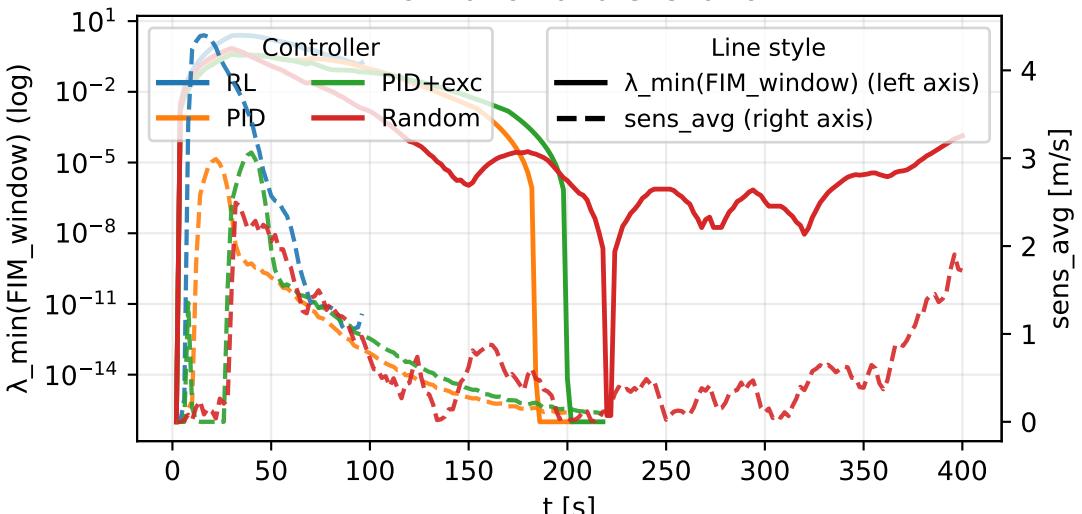
TRUE formation error



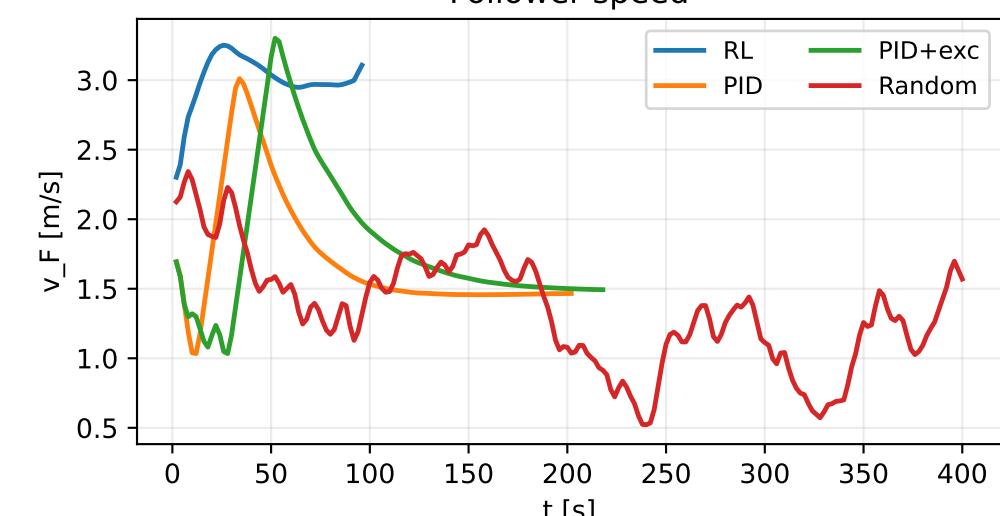
Estimator uncertainty (std_max)



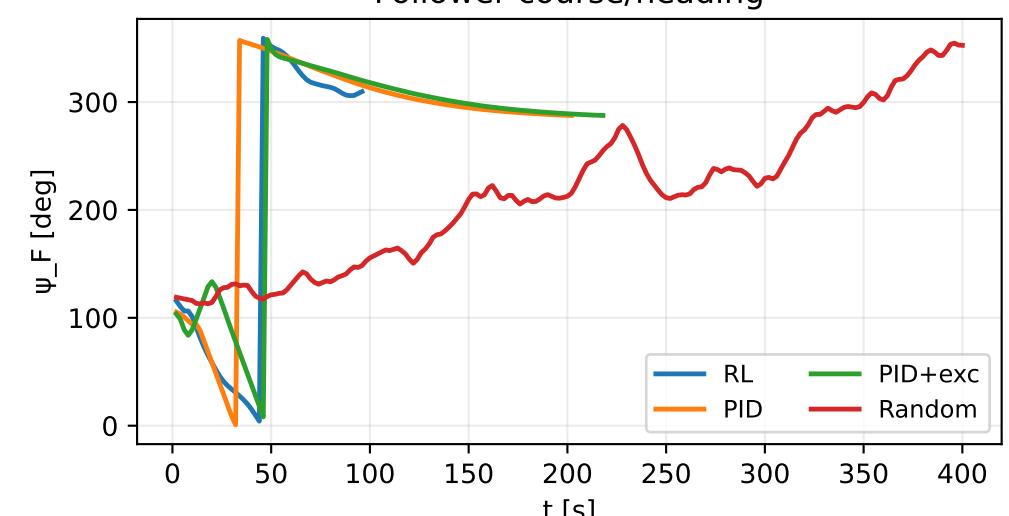
Information and excitation



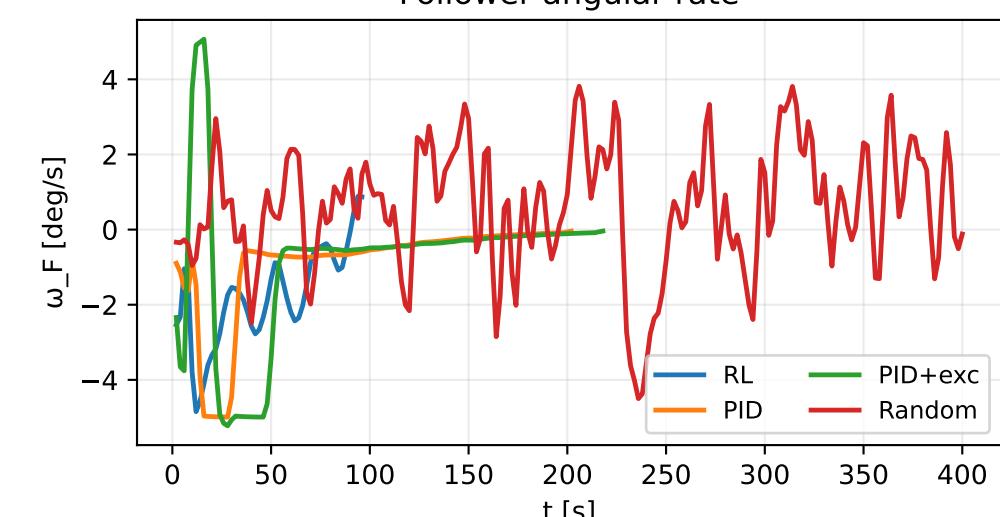
Follower speed



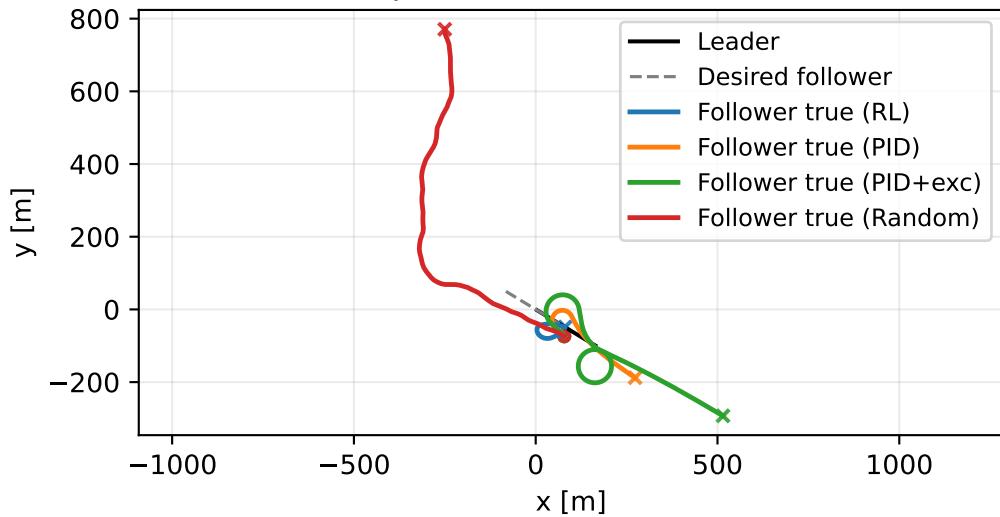
Follower course/heading



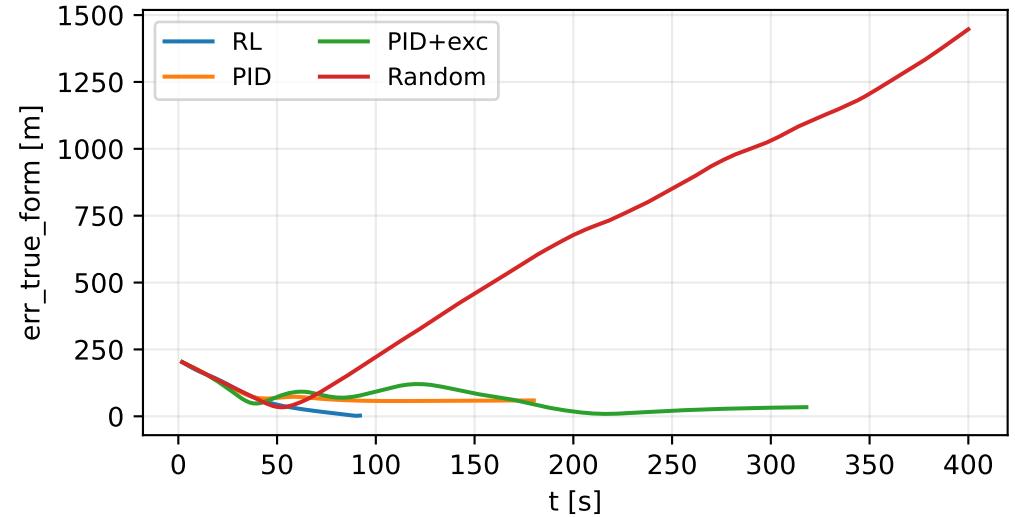
Follower angular rate



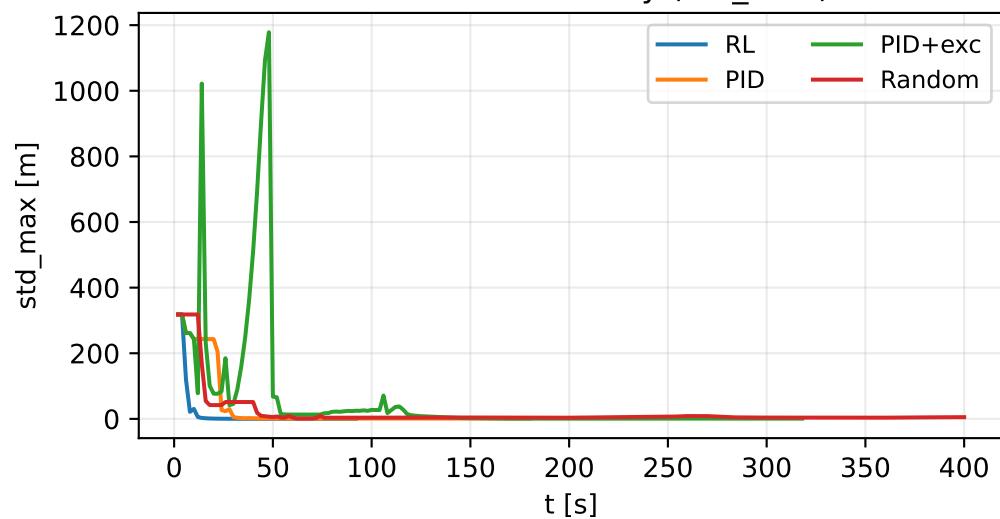
Trajectories (matched seed)



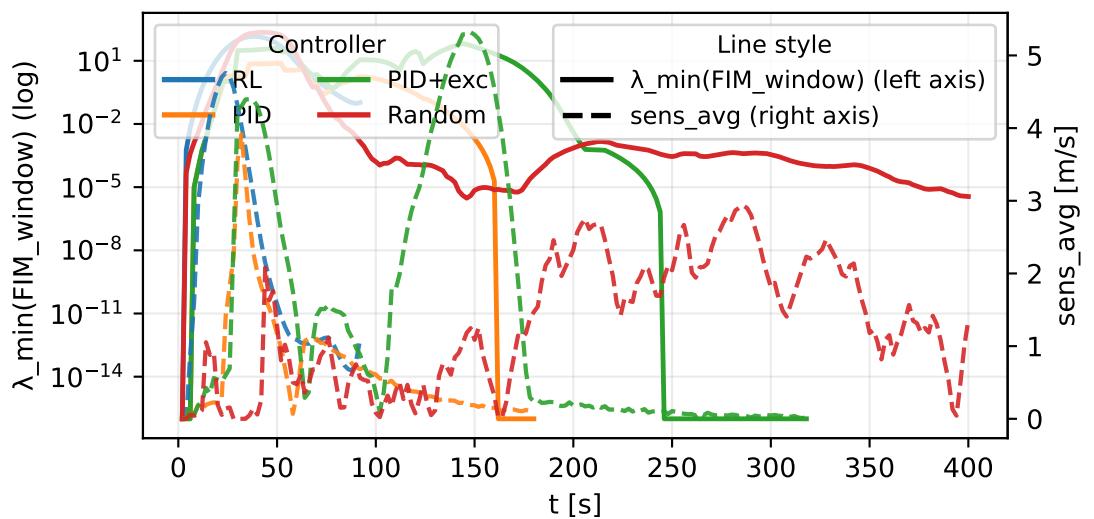
TRUE formation error



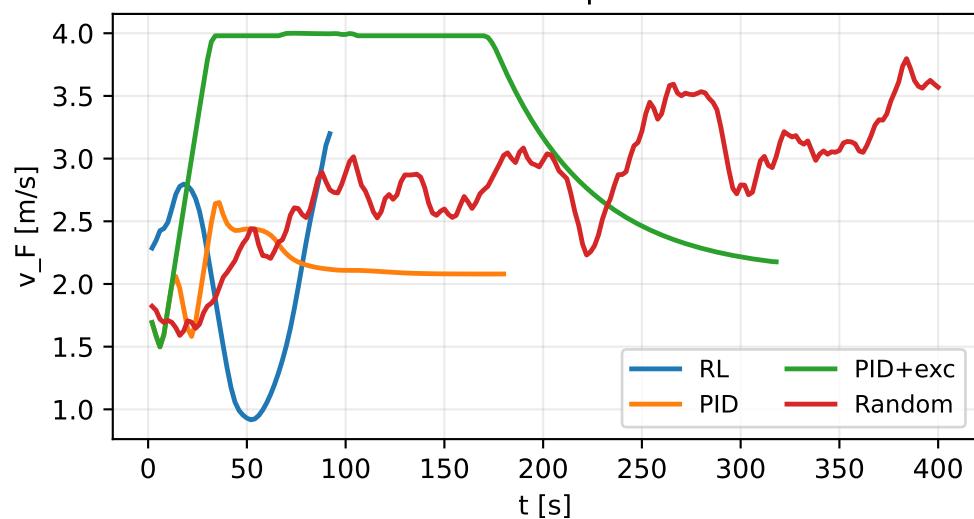
Estimator uncertainty (std_max)



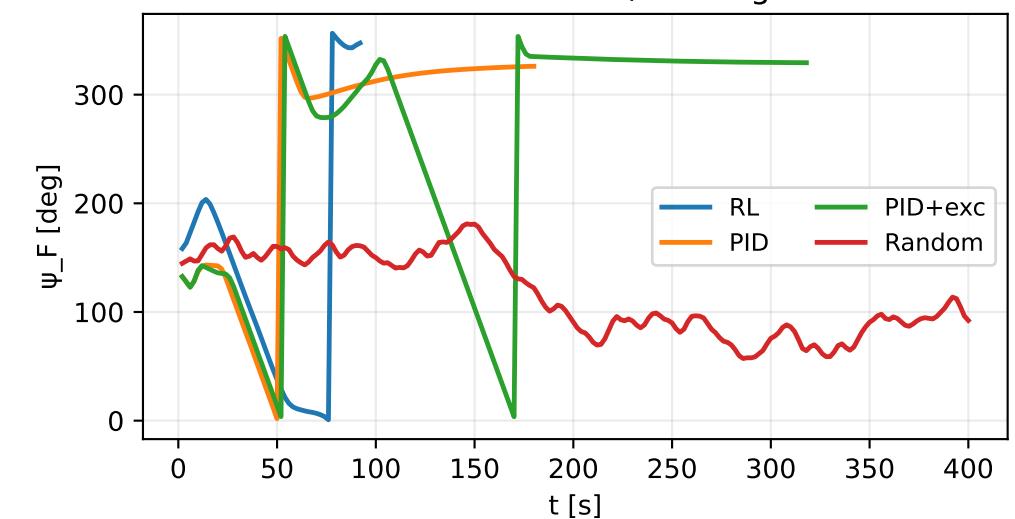
Information and excitation



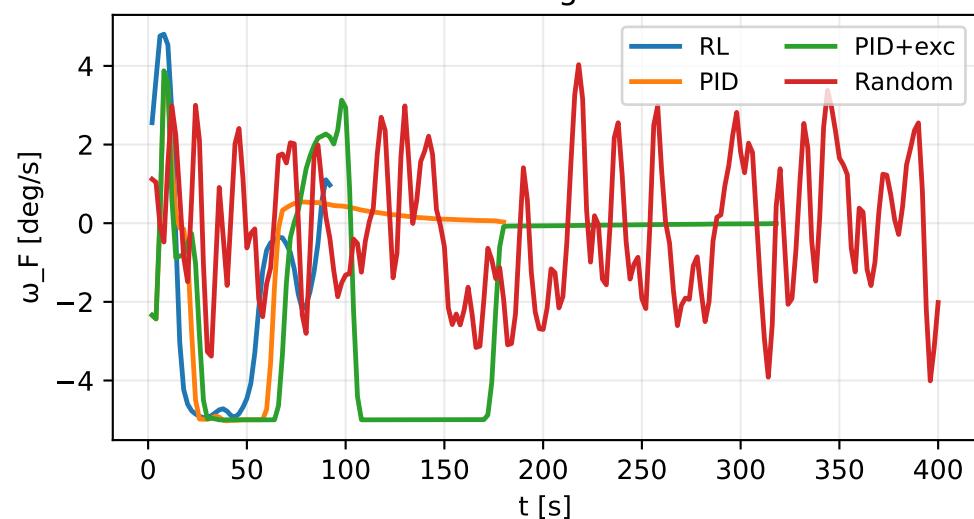
Follower speed



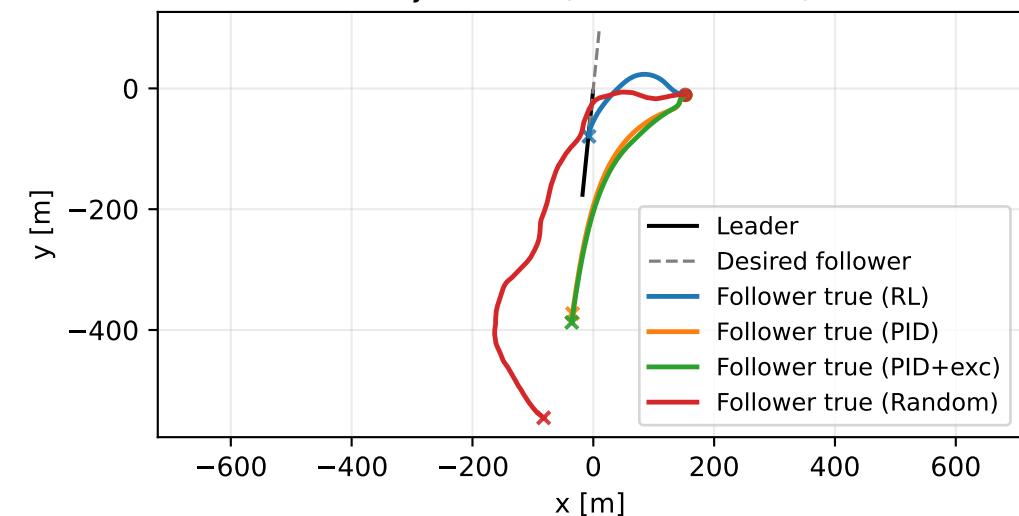
Follower course/heading



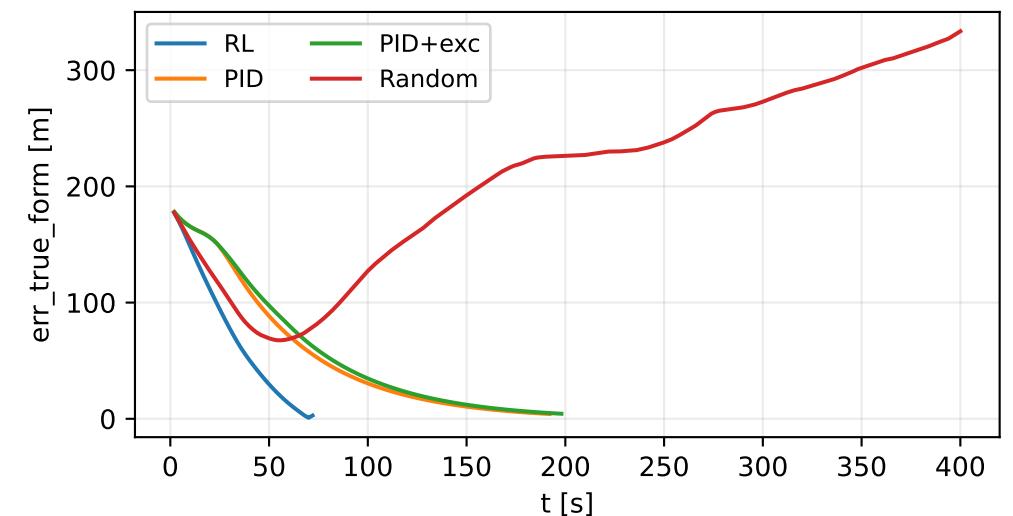
Follower angular rate



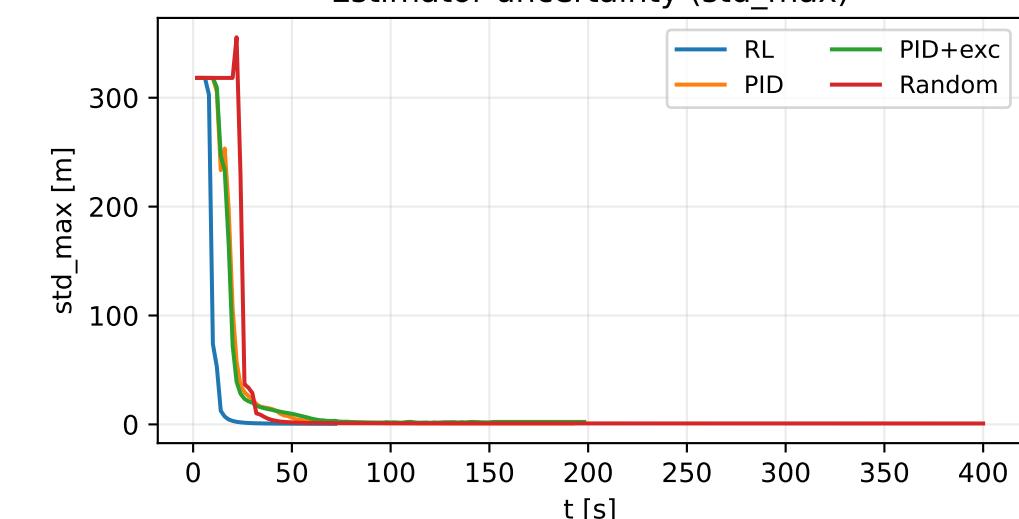
Trajectories (matched seed)



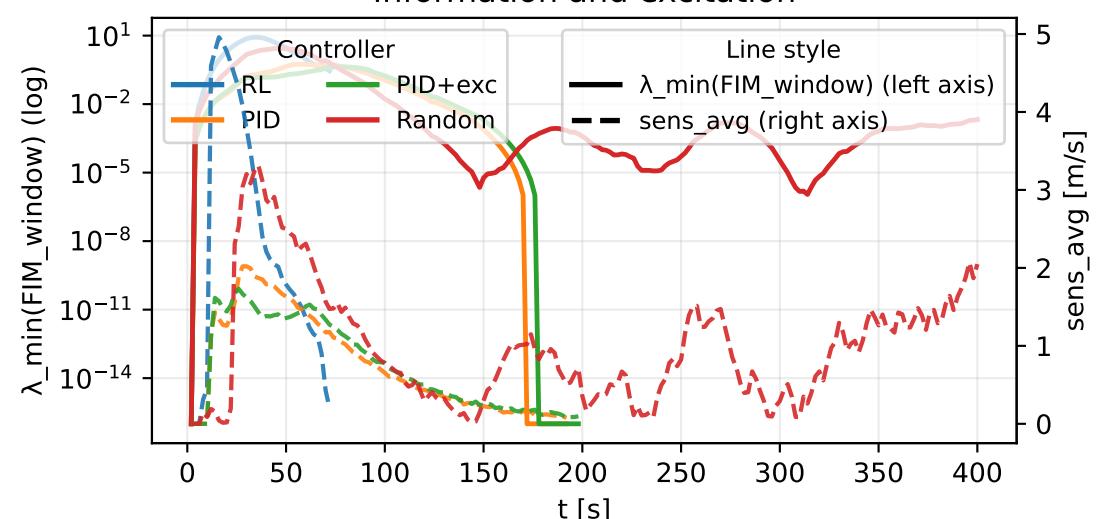
TRUE formation error



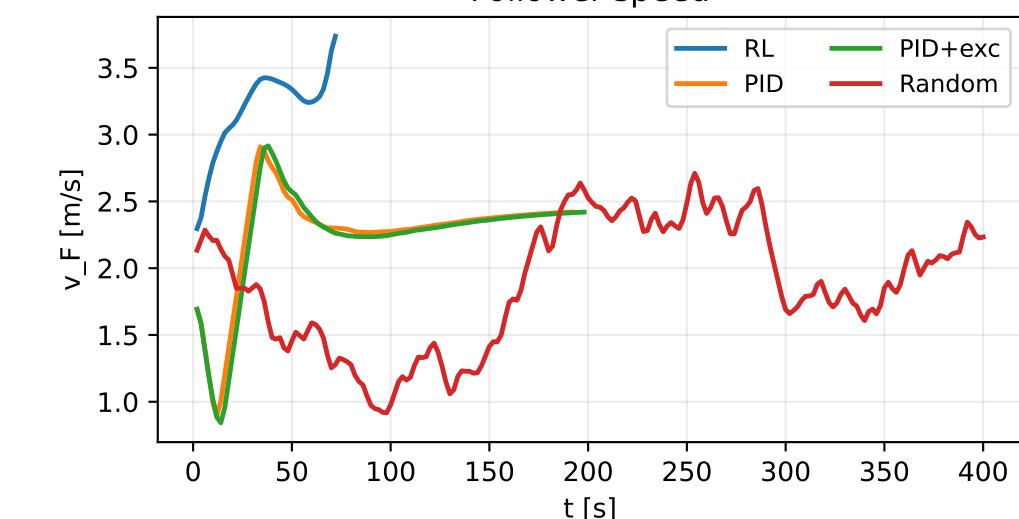
Estimator uncertainty (std_max)



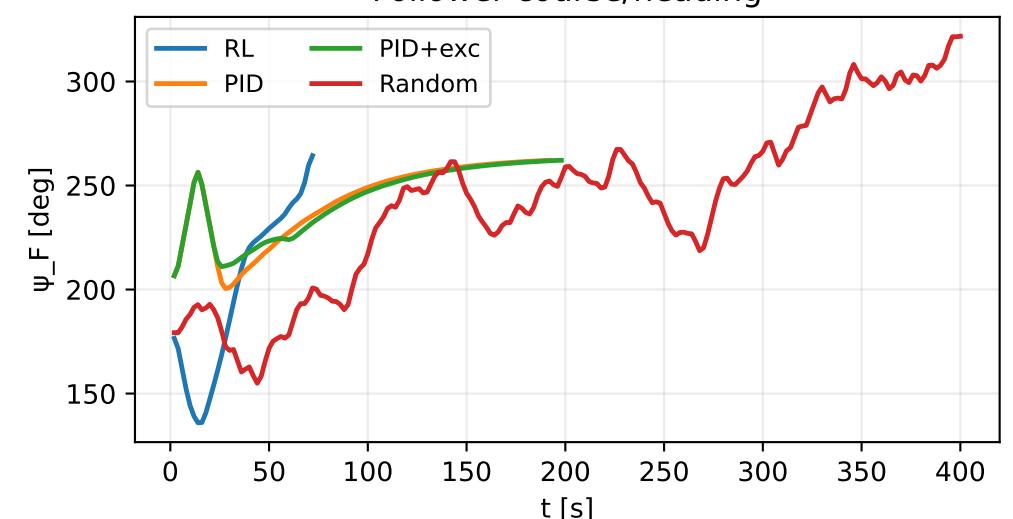
Information and excitation



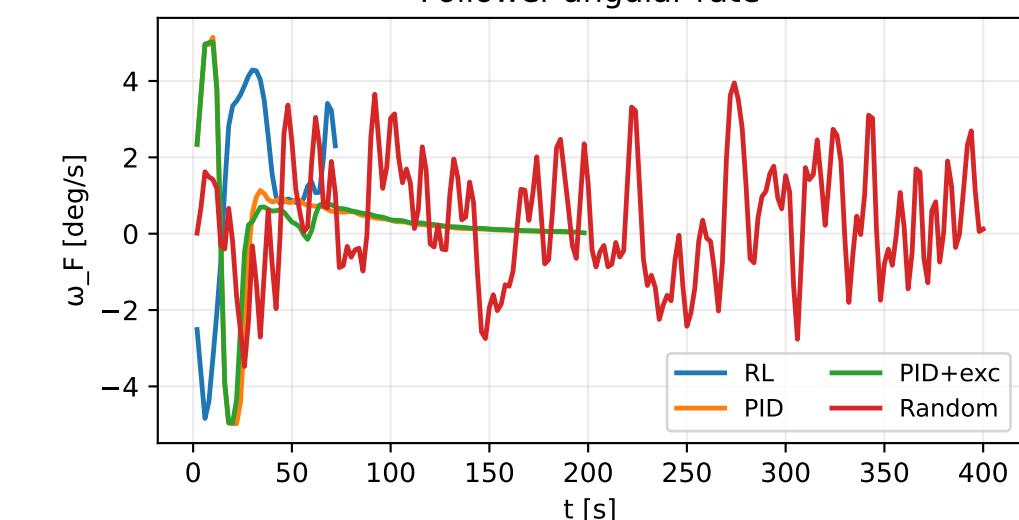
Follower speed



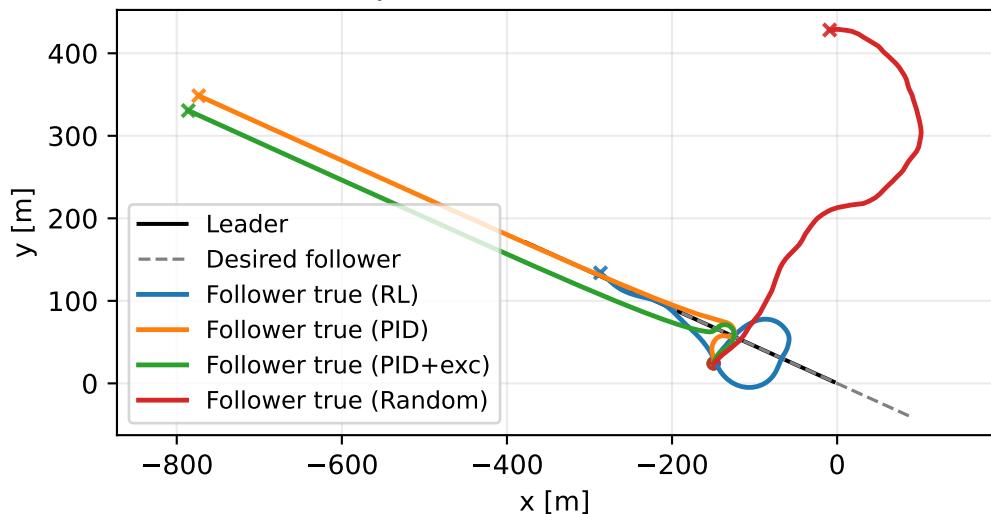
Follower course/heading



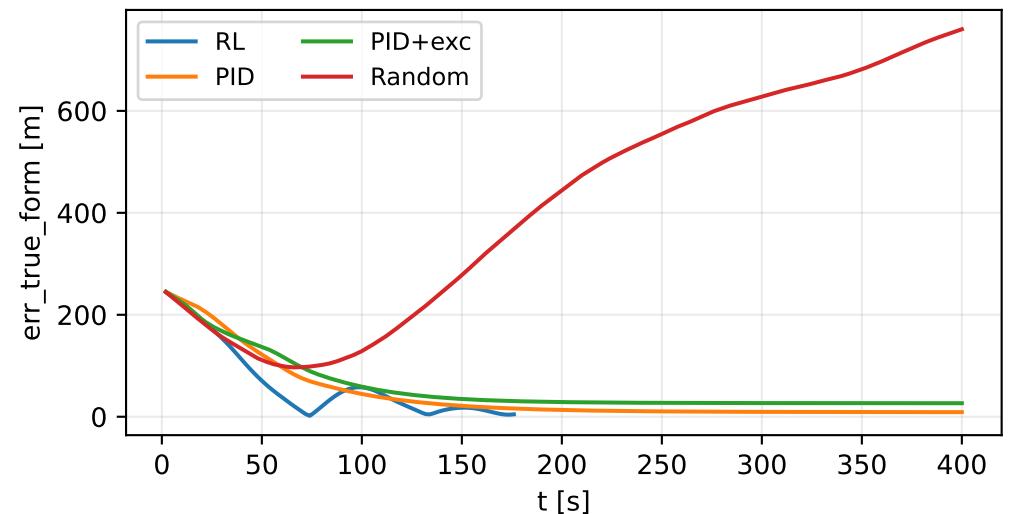
Follower angular rate



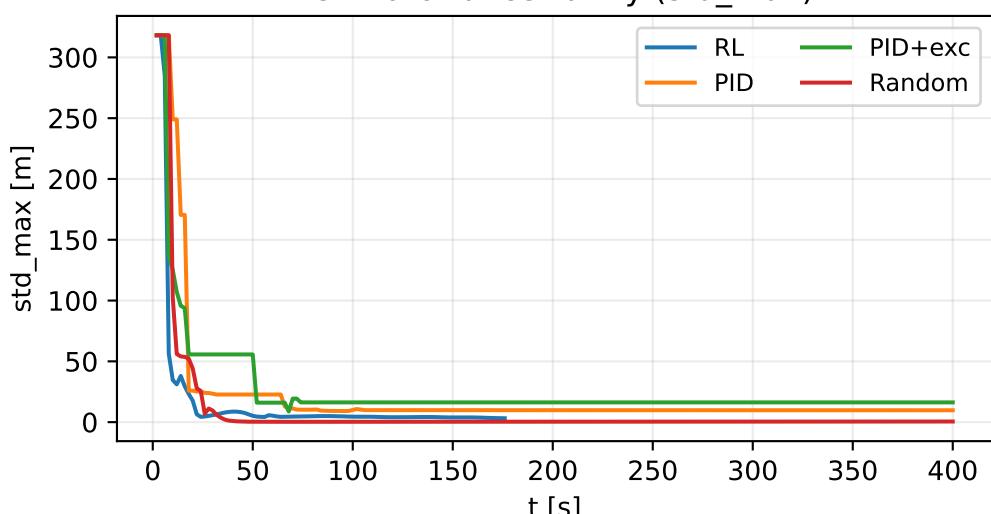
Trajectories (matched seed)



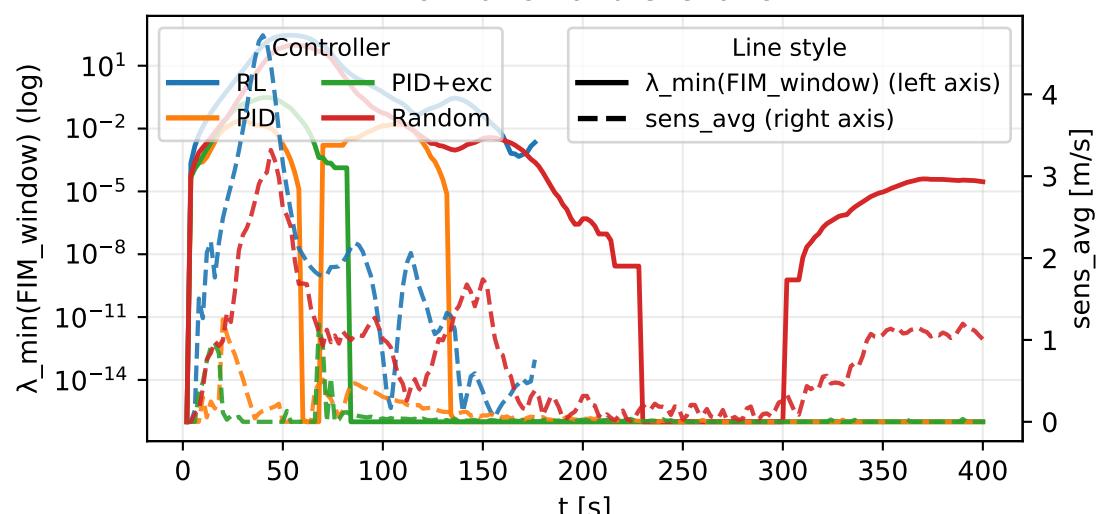
TRUE formation error



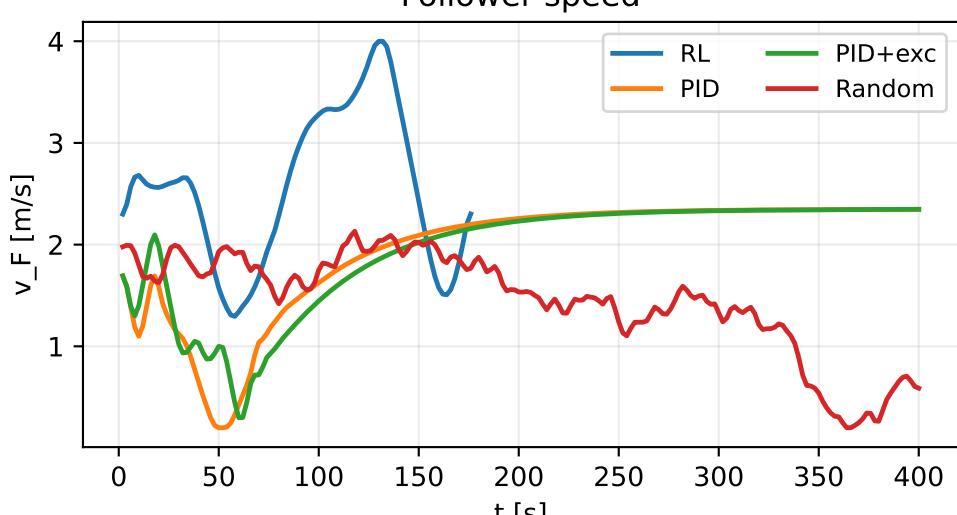
Estimator uncertainty (std_max)



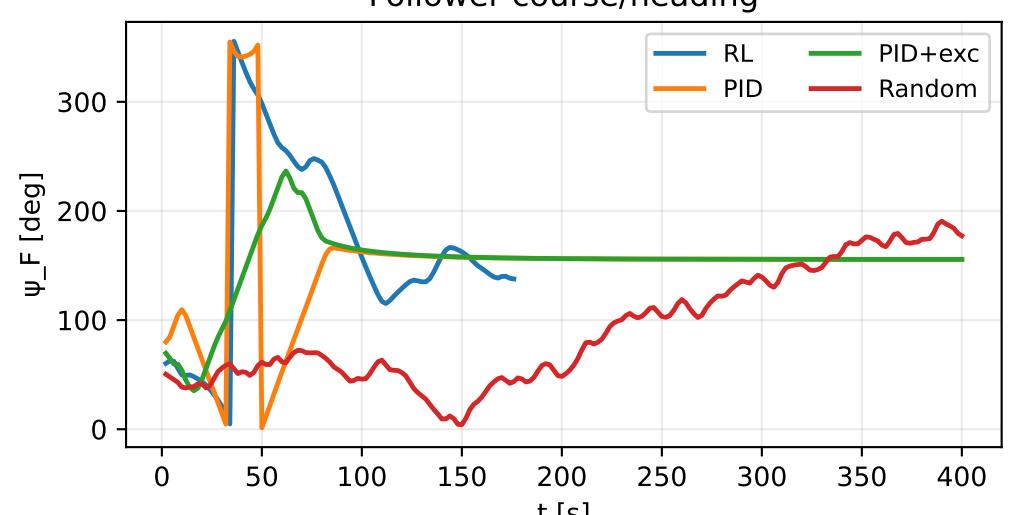
Information and excitation



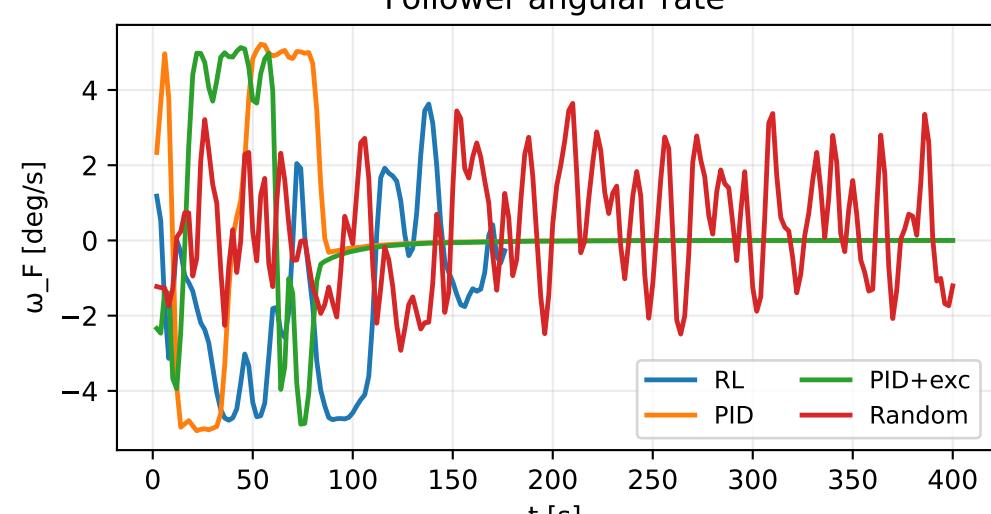
Follower speed



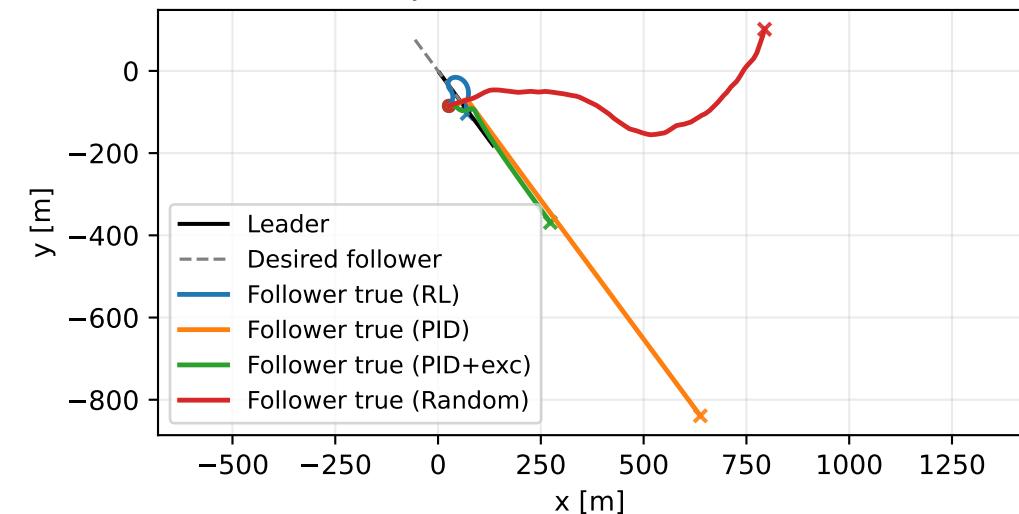
Follower course/heading



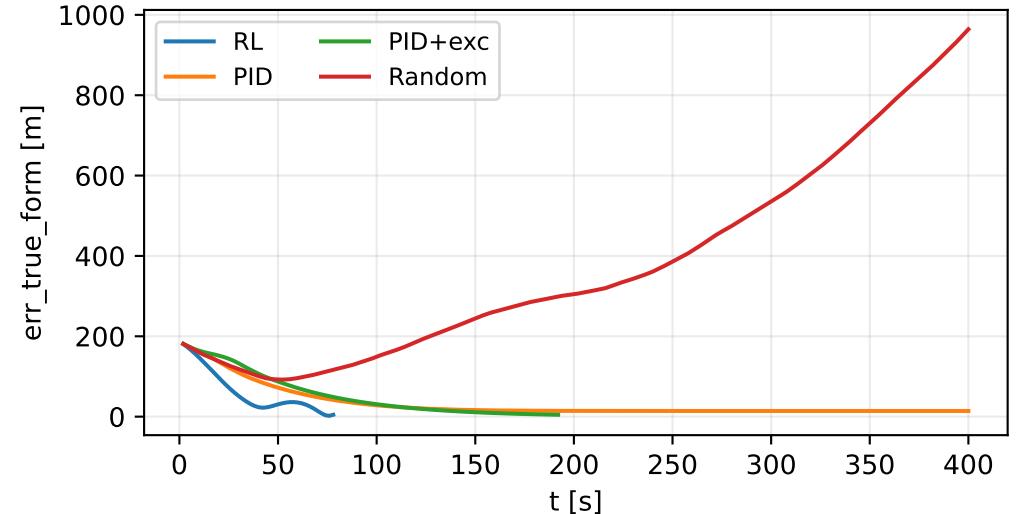
Follower angular rate



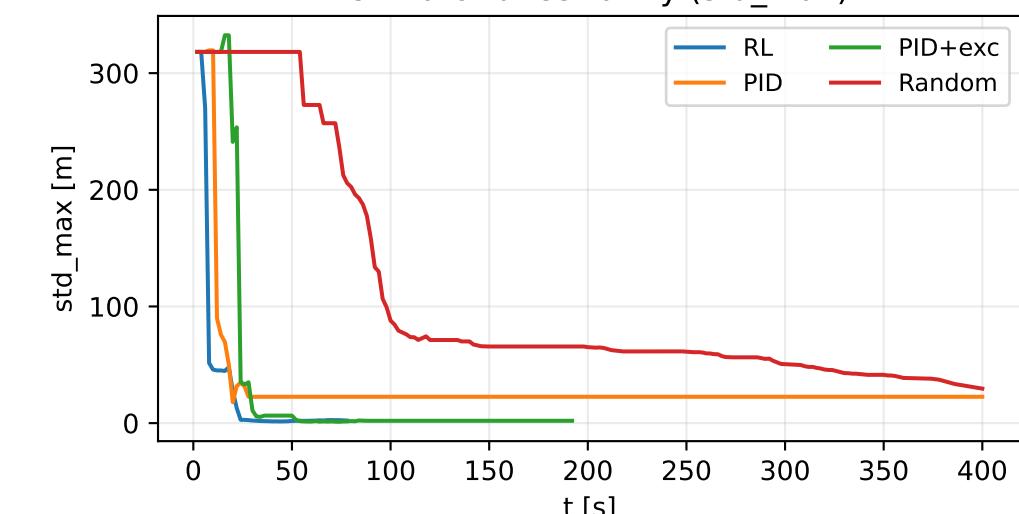
Trajectories (matched seed)



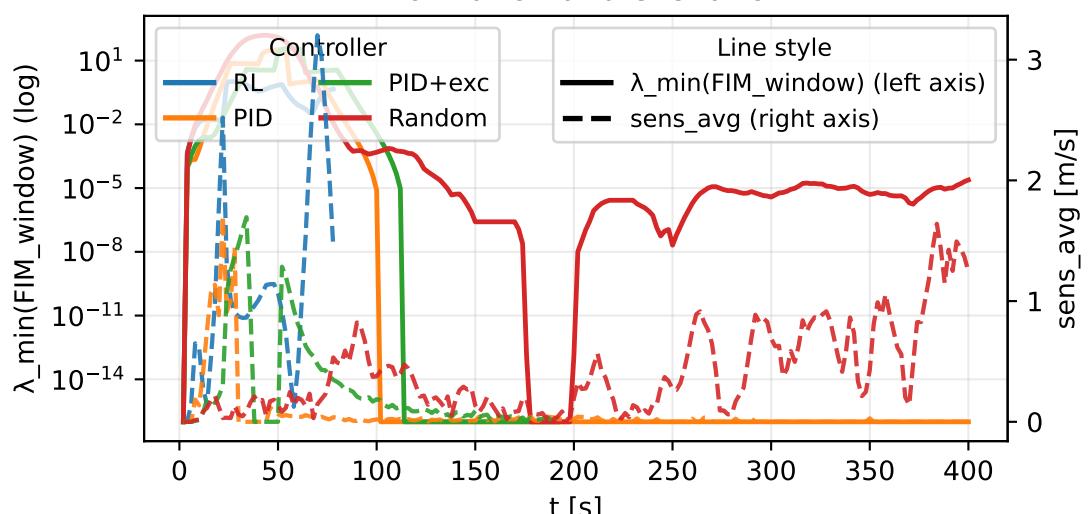
TRUE formation error



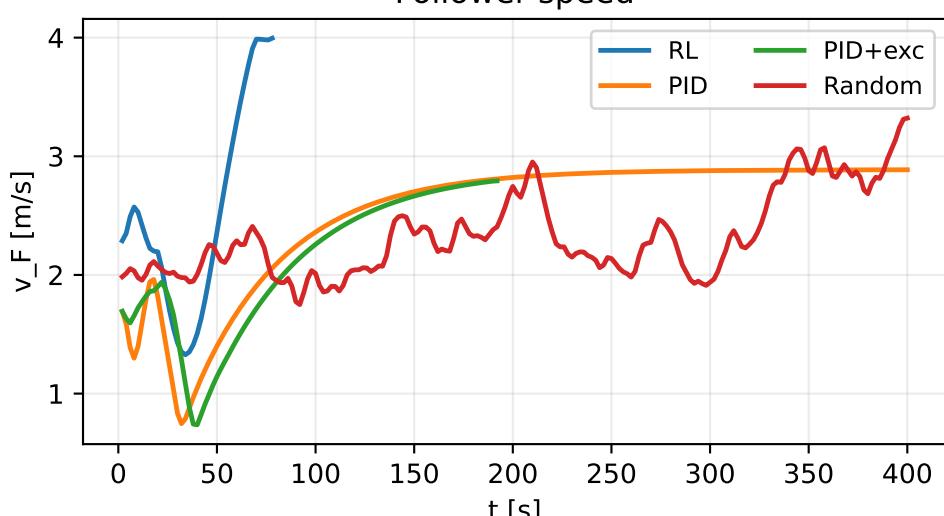
Estimator uncertainty (std_max)



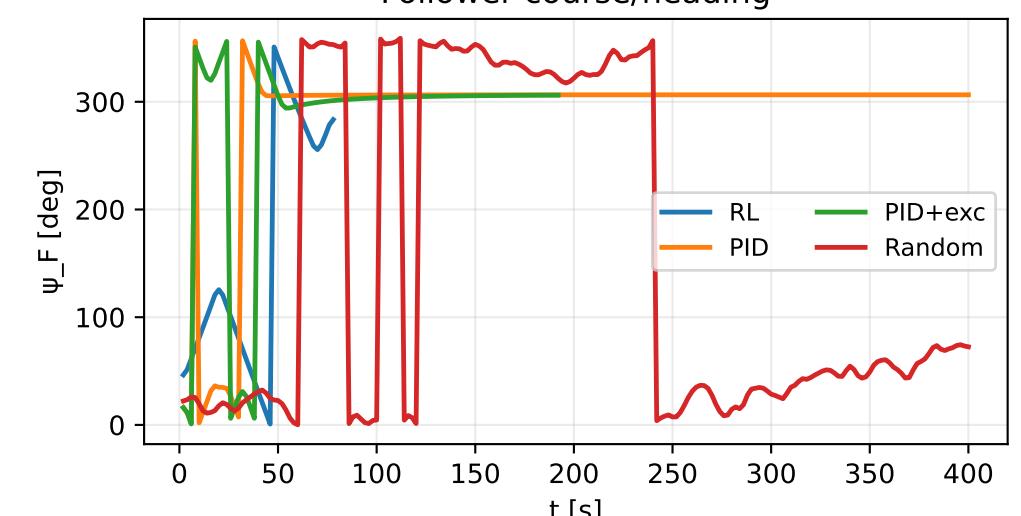
Information and excitation



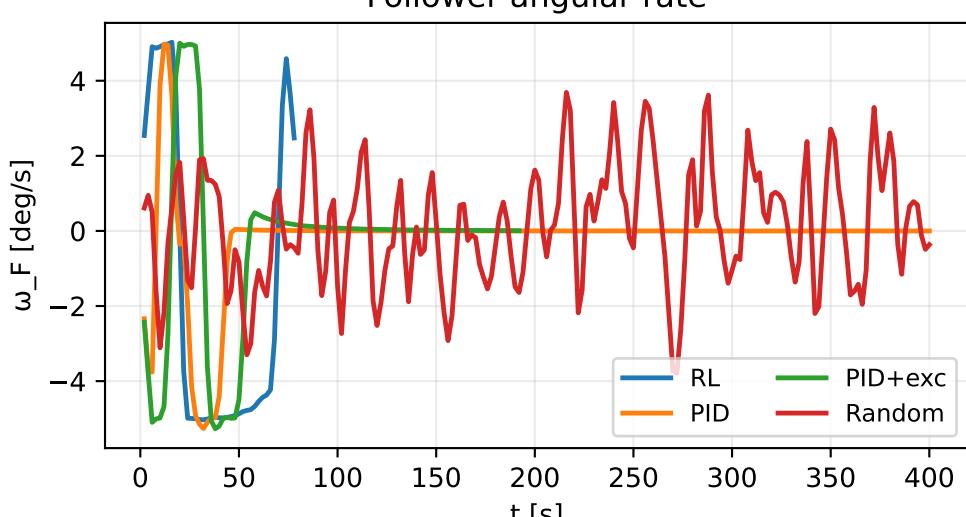
Follower speed



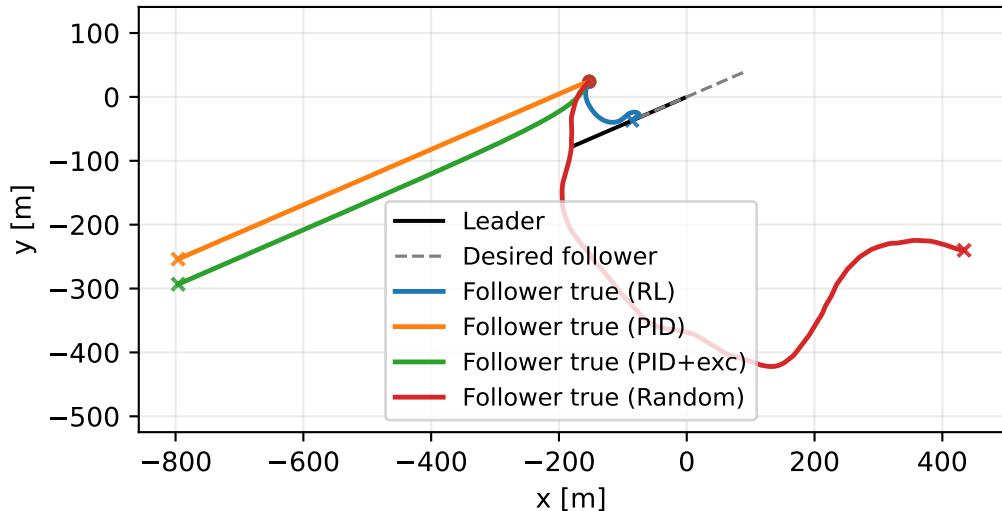
Follower course/heading



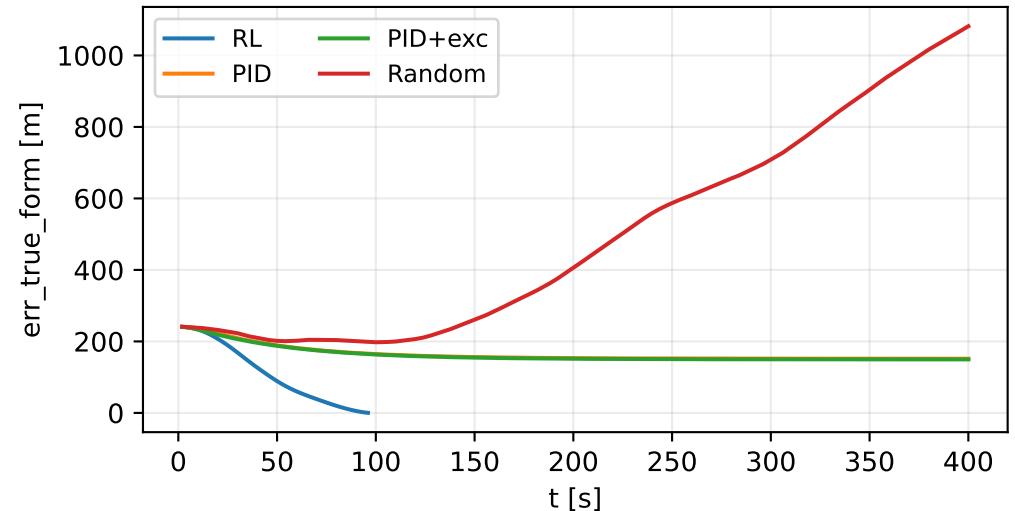
Follower angular rate



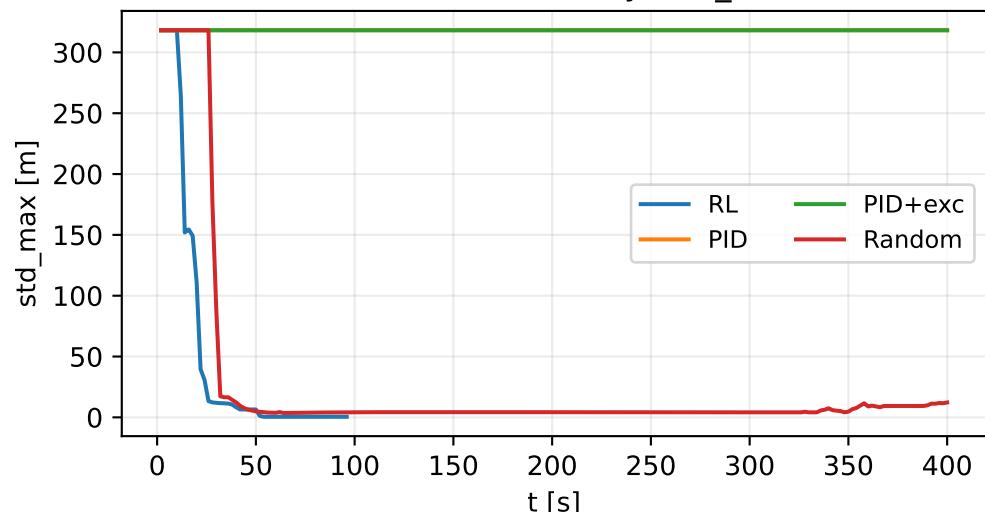
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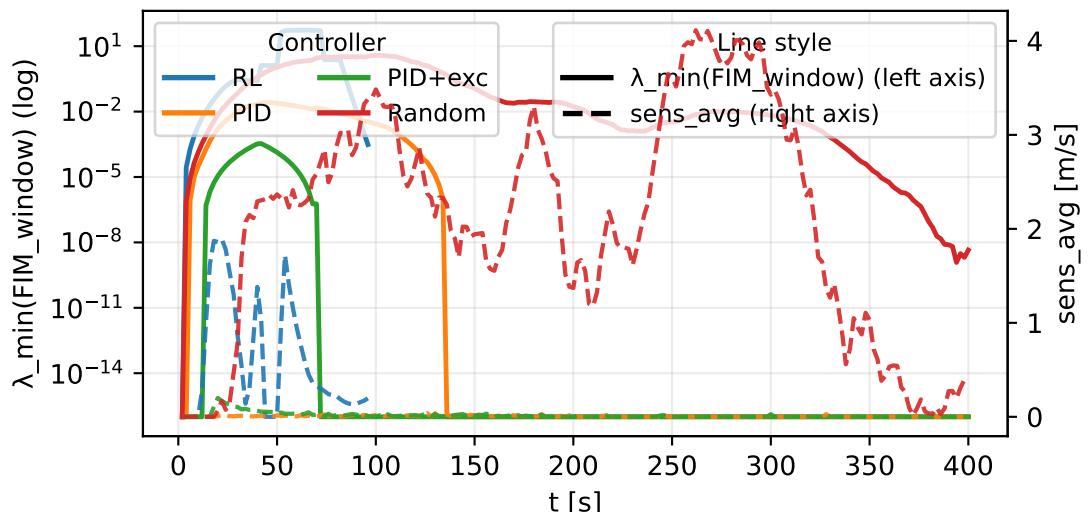
TRUE formation error



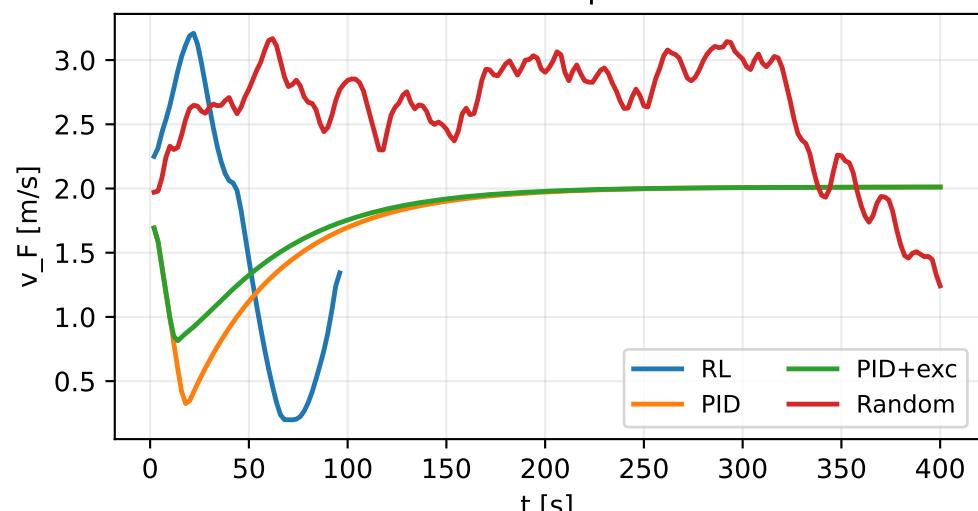
Estimator uncertainty (std_max)



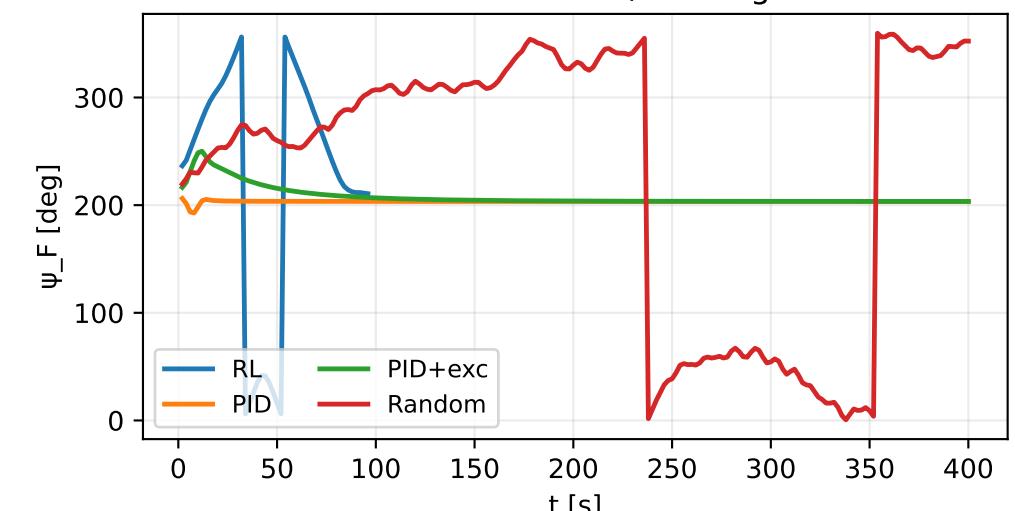
Information and excitation



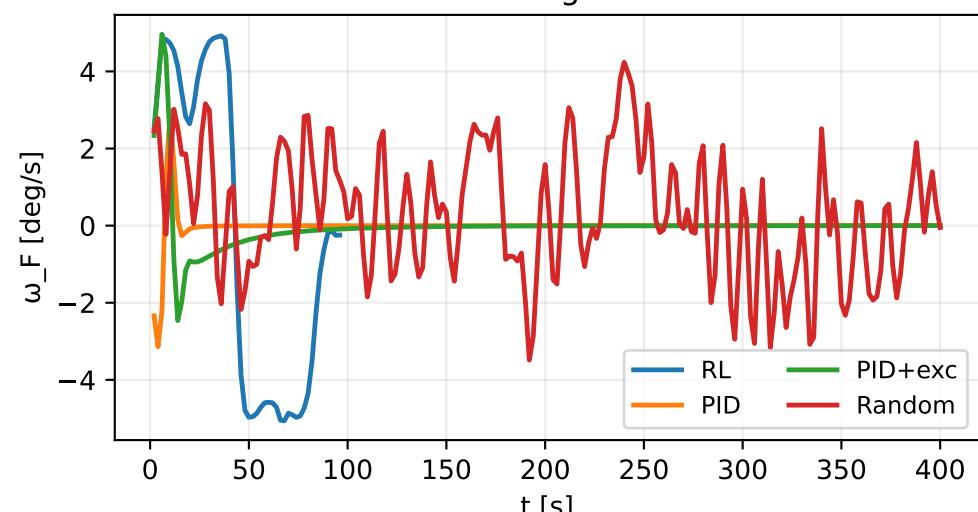
Follower speed



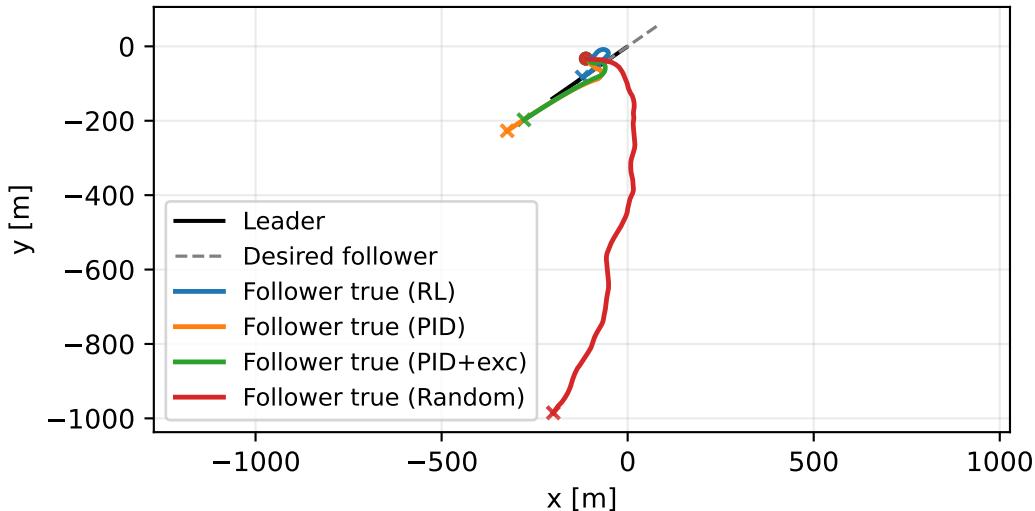
Follower course/heading



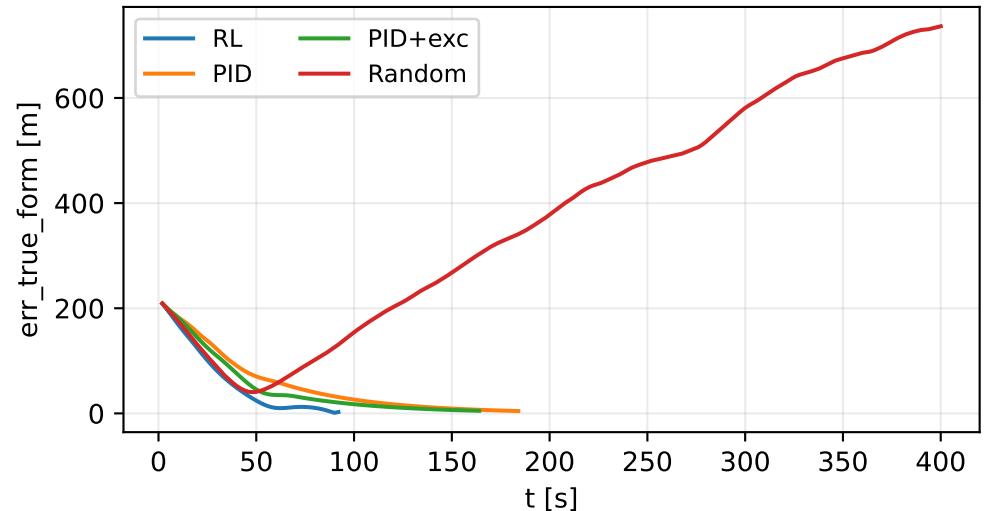
Follower angular rate



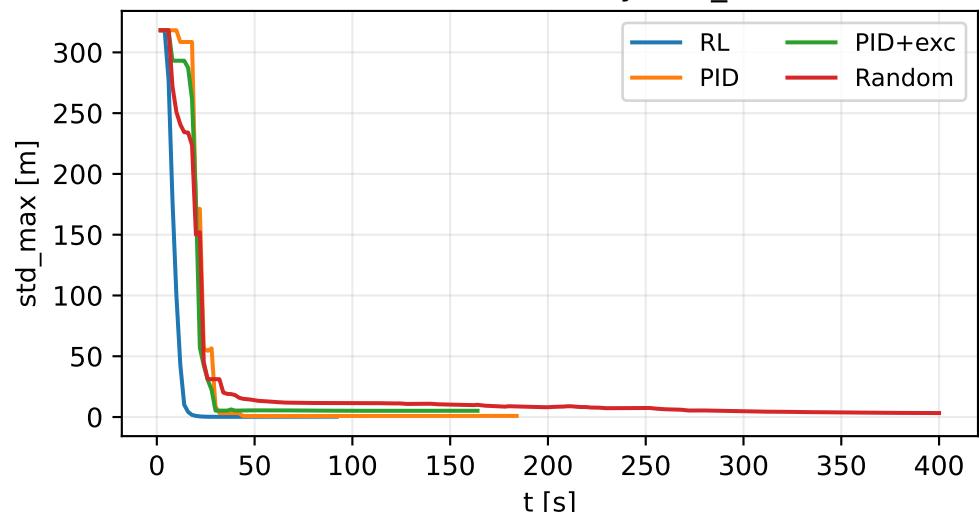
Trajectories (matched seed)



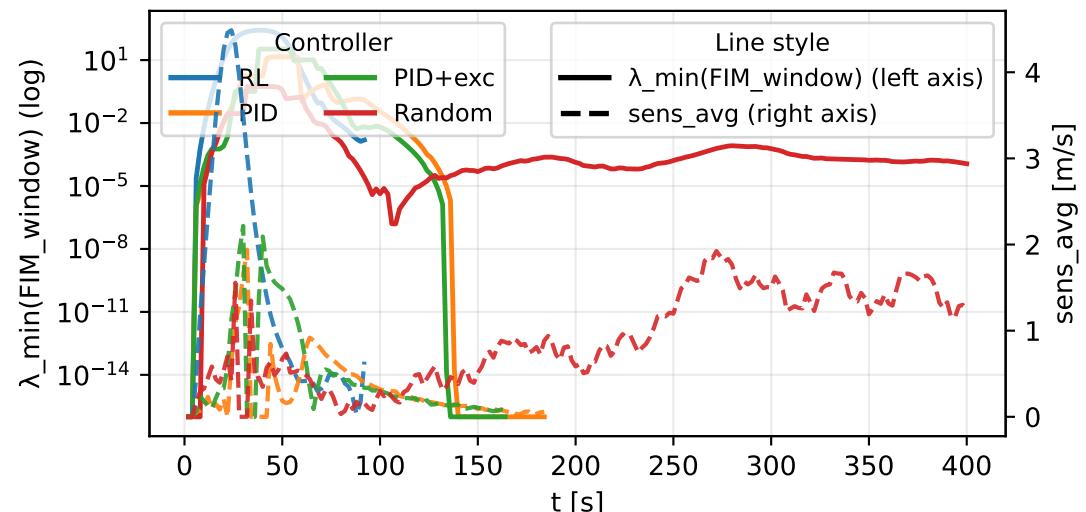
TRUE formation error



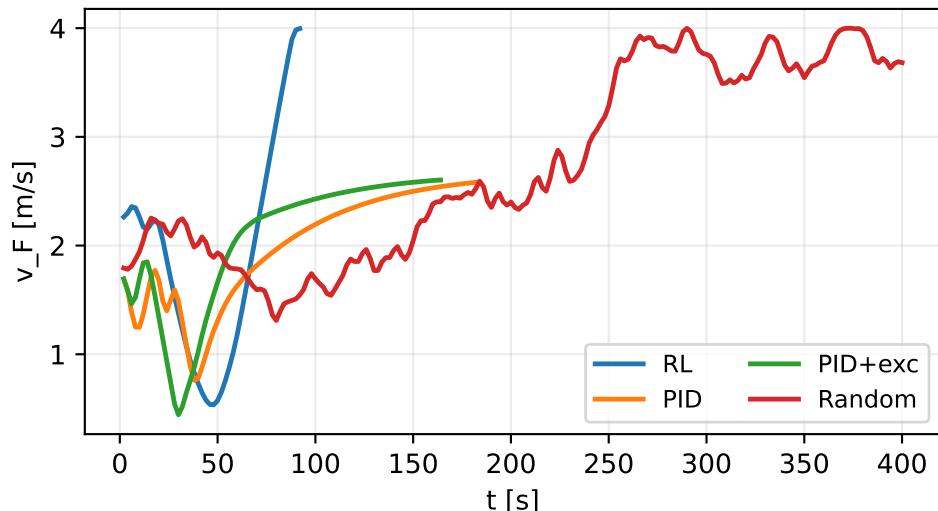
Estimator uncertainty (std_max)



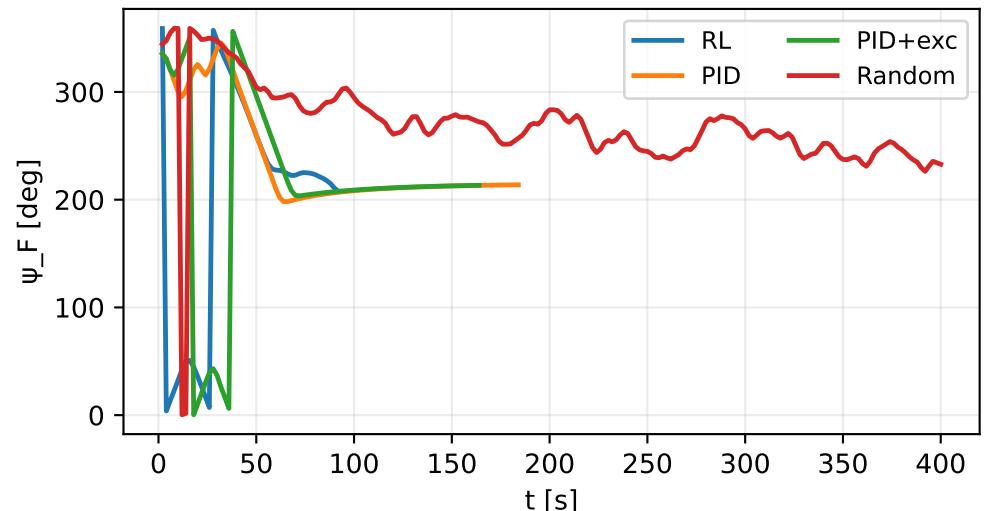
Information and excitation



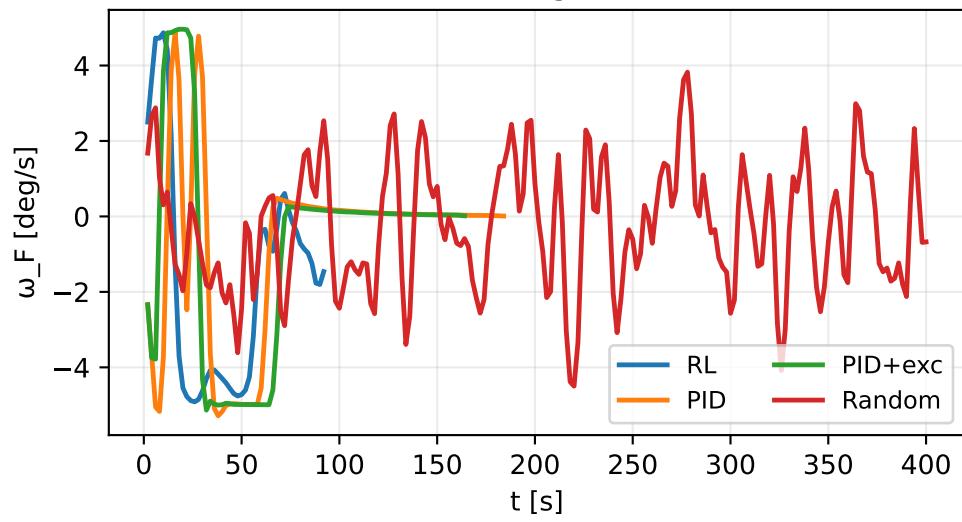
Follower speed



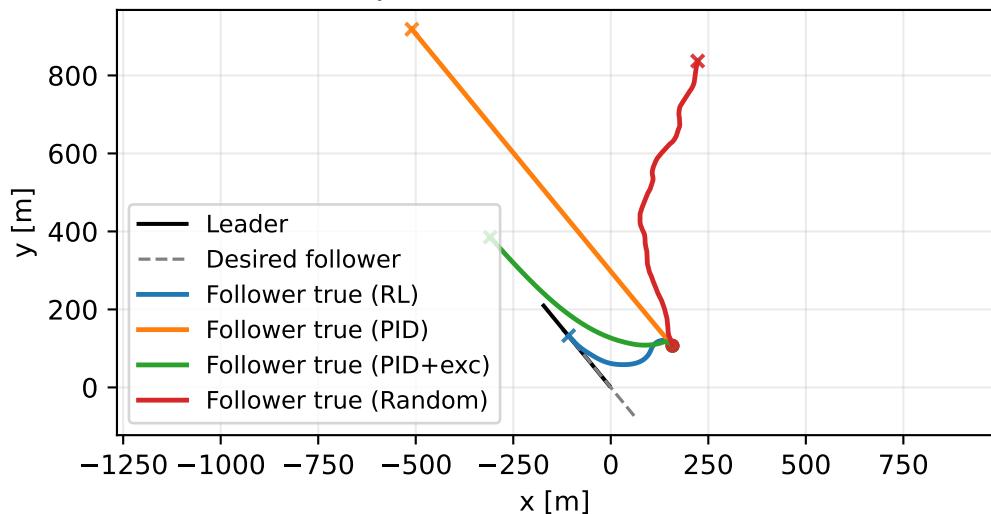
Follower course/heading



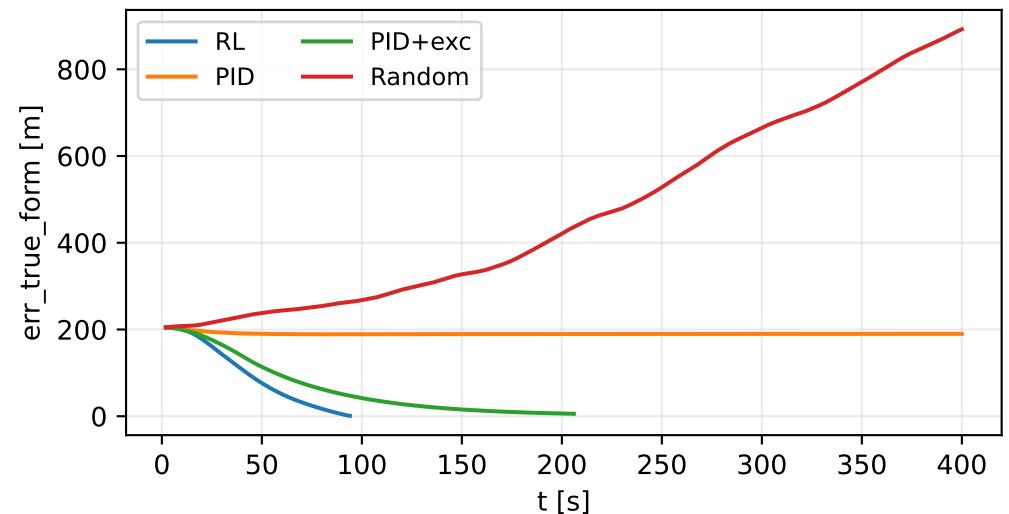
Follower angular rate



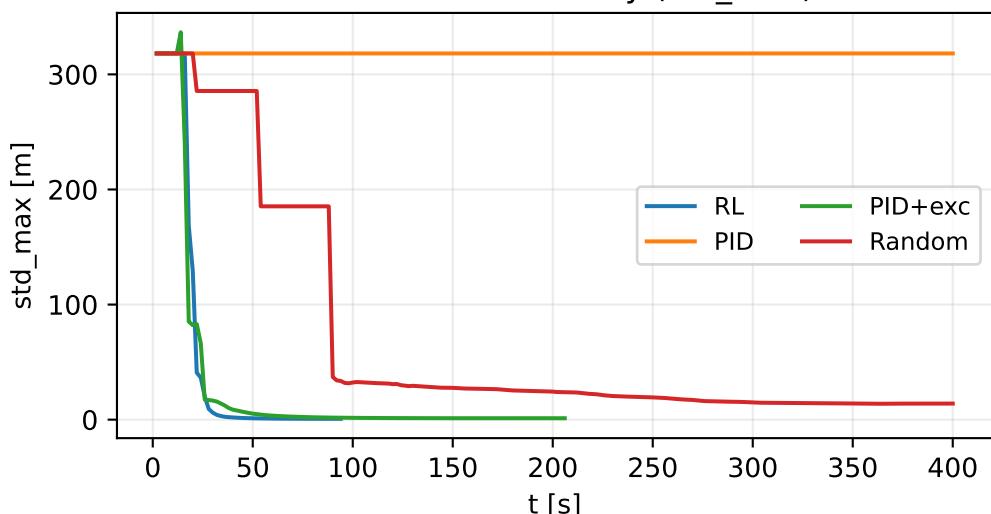
Trajectories (matched seed)



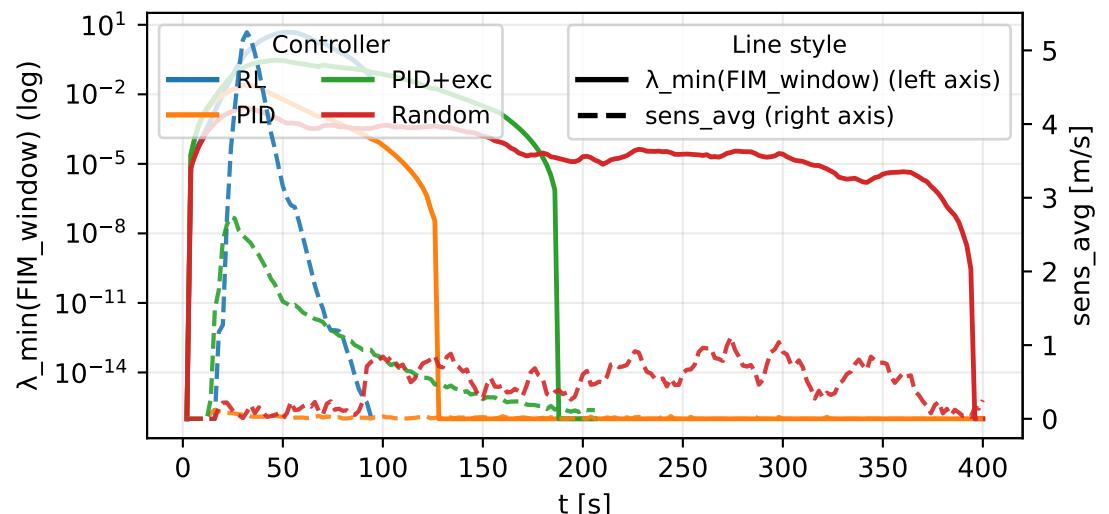
TRUE formation error



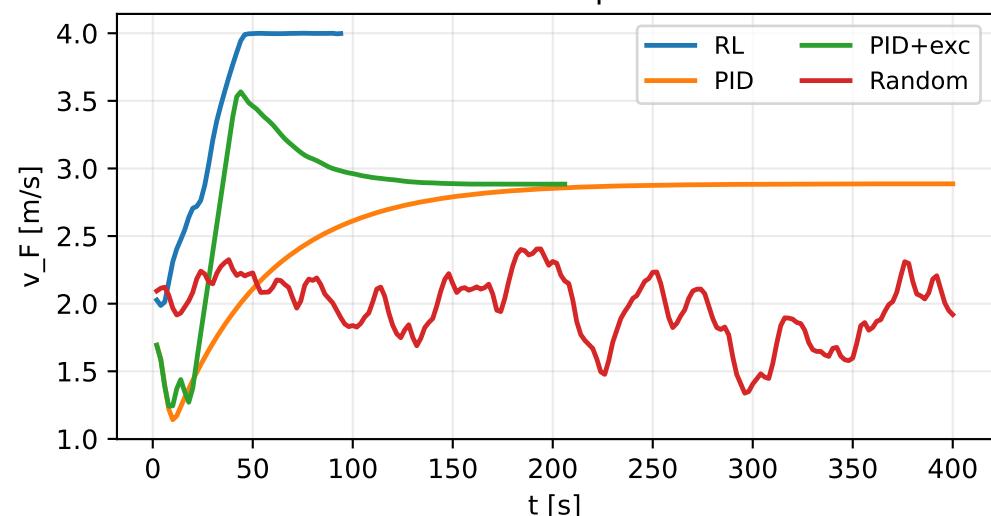
Estimator uncertainty (std_max)



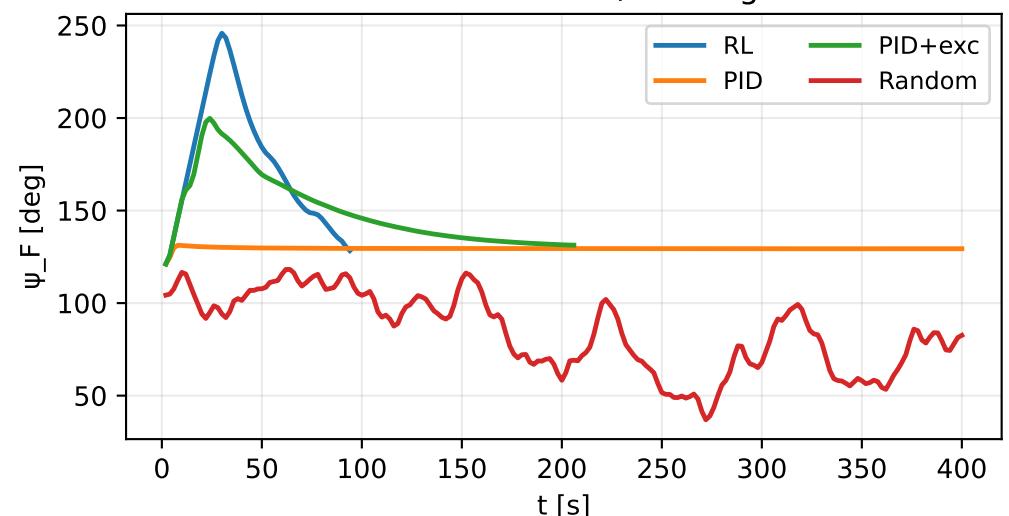
Information and excitation



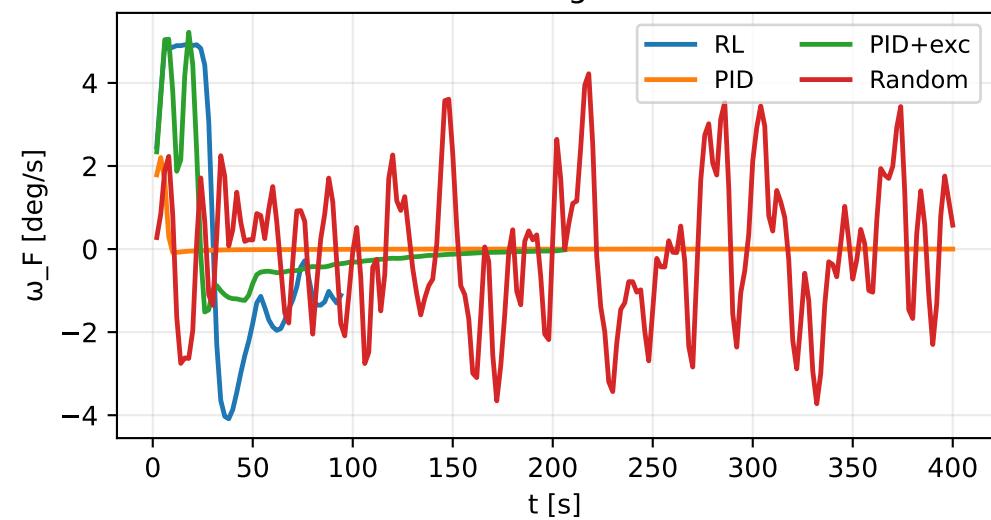
Follower speed



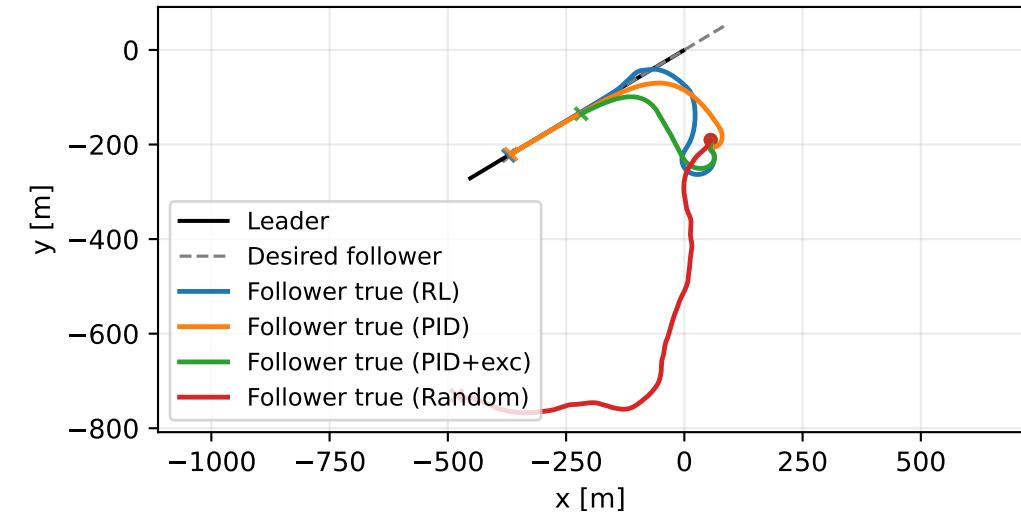
Follower course/heading



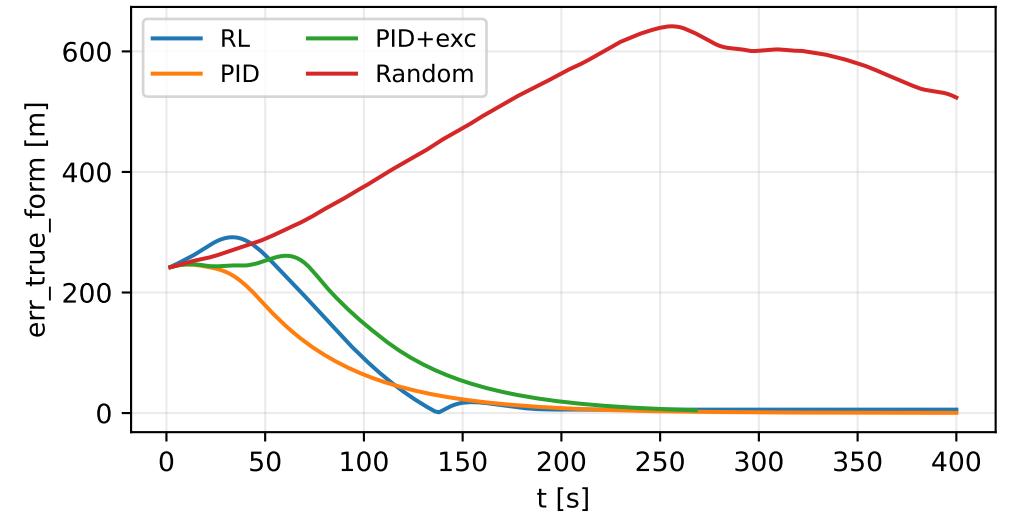
Follower angular rate



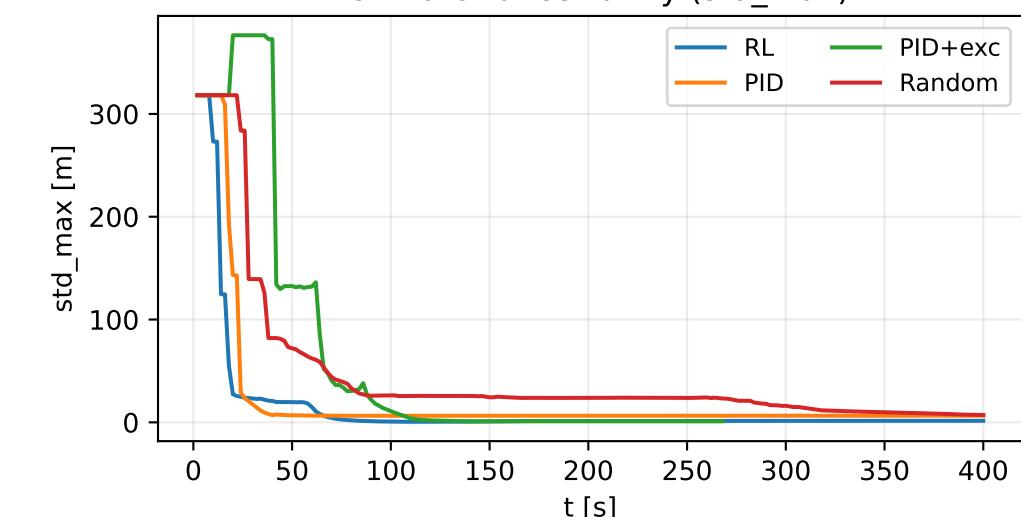
Trajectories (matched seed)



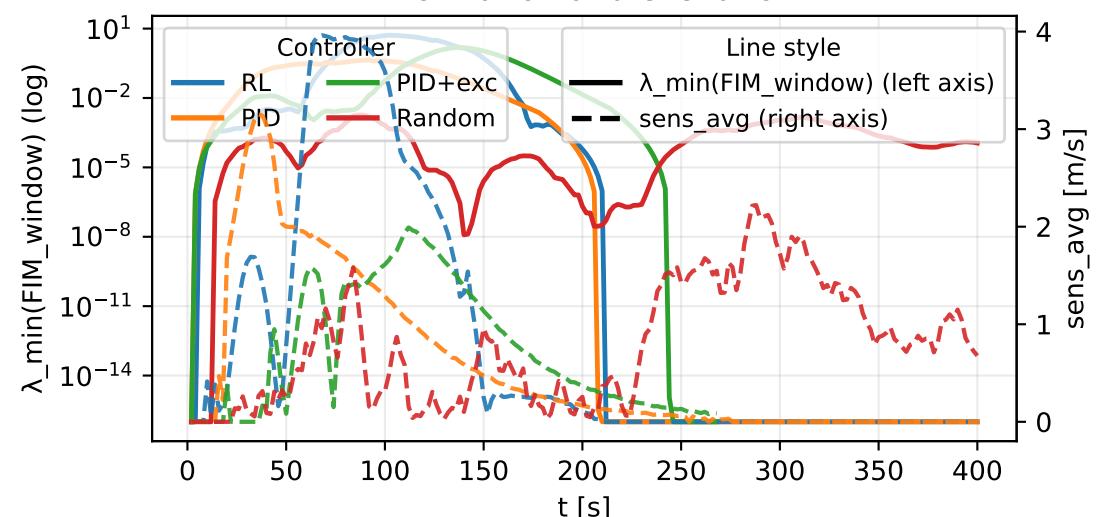
TRUE formation error



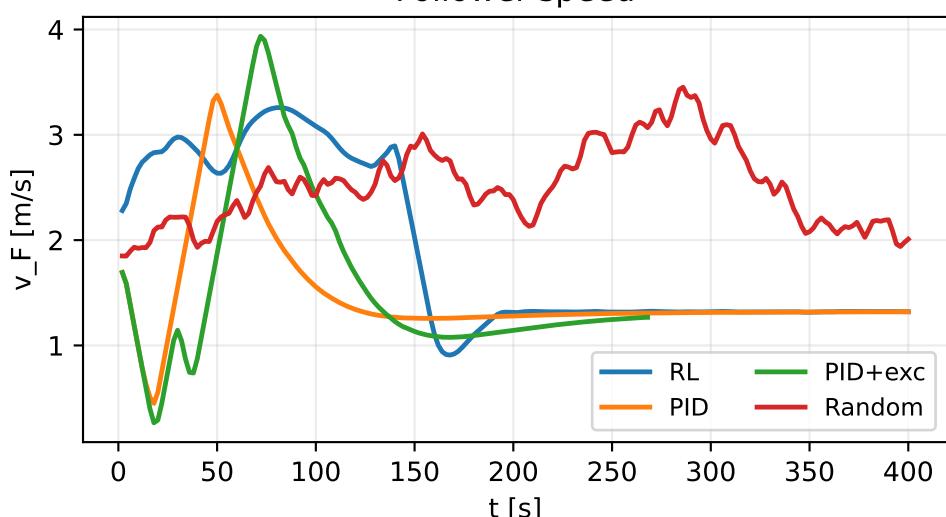
Estimator uncertainty (std_max)



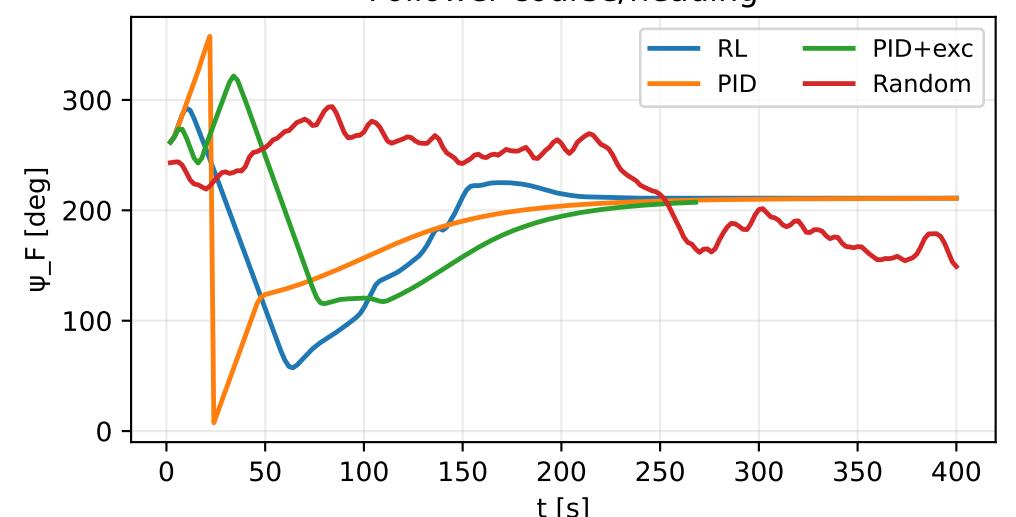
Information and excitation



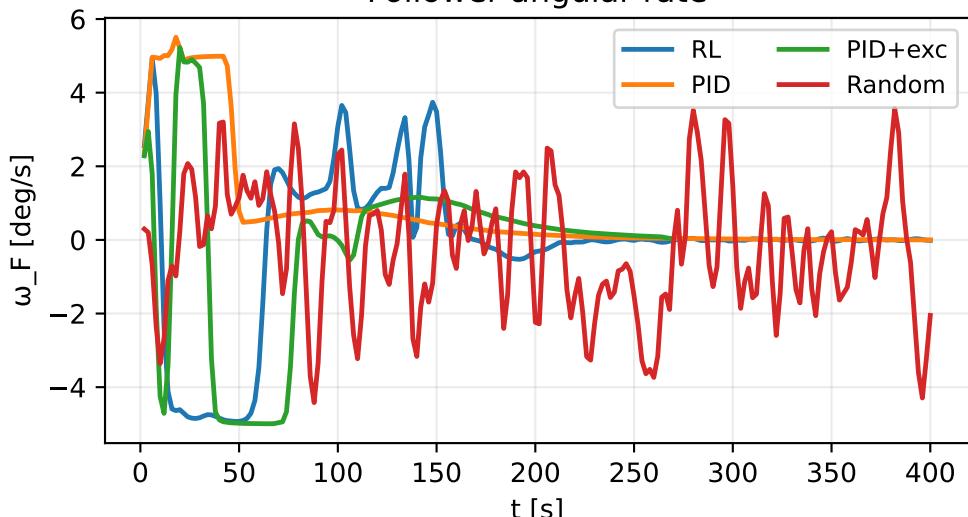
Follower speed



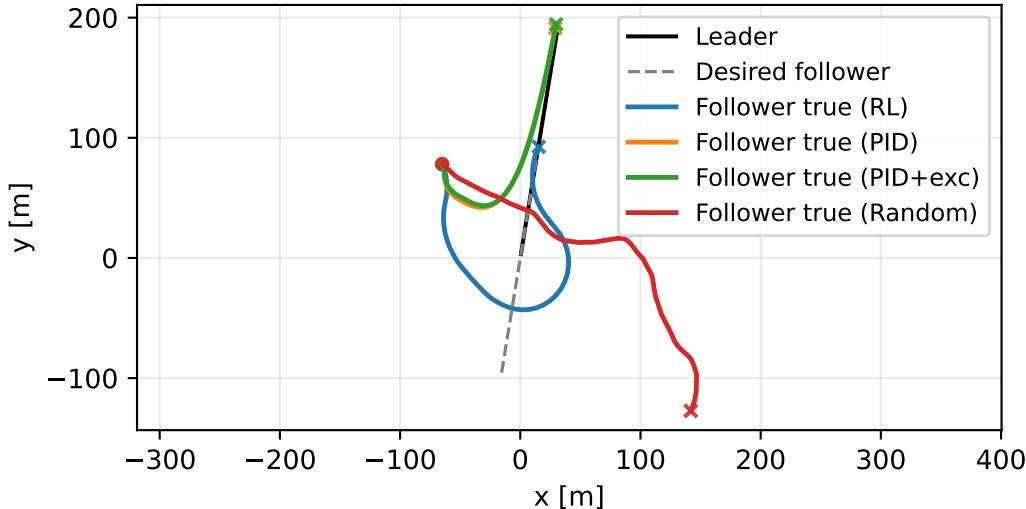
Follower course/heading



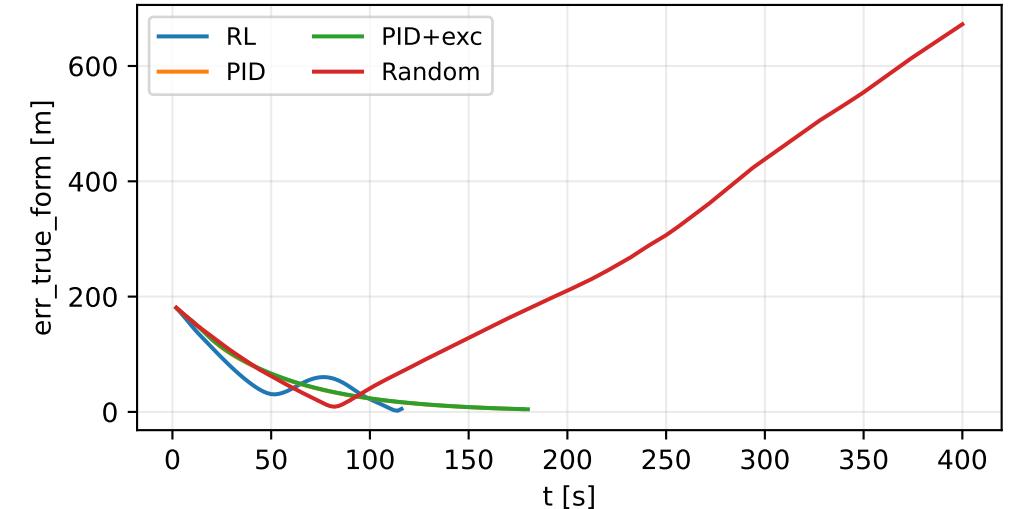
Follower angular rate



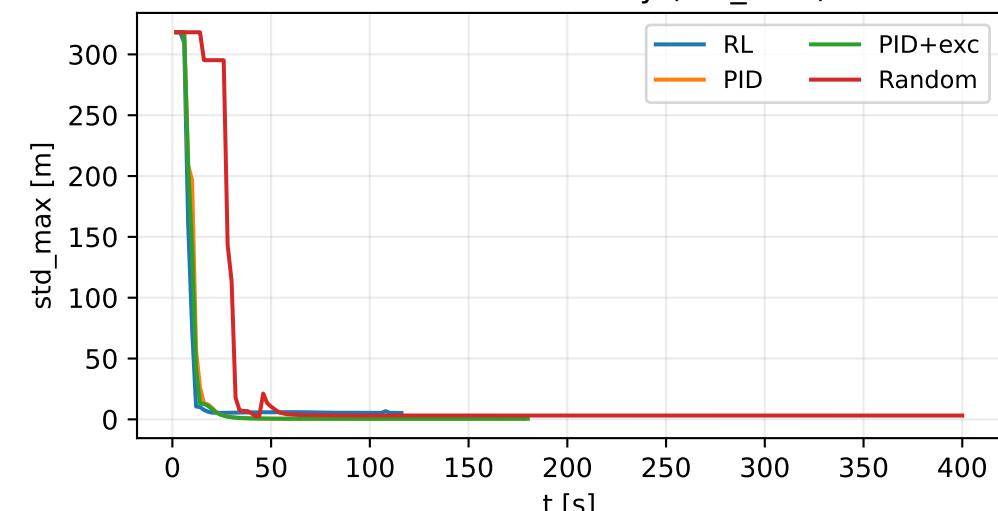
Trajectories (matched seed)



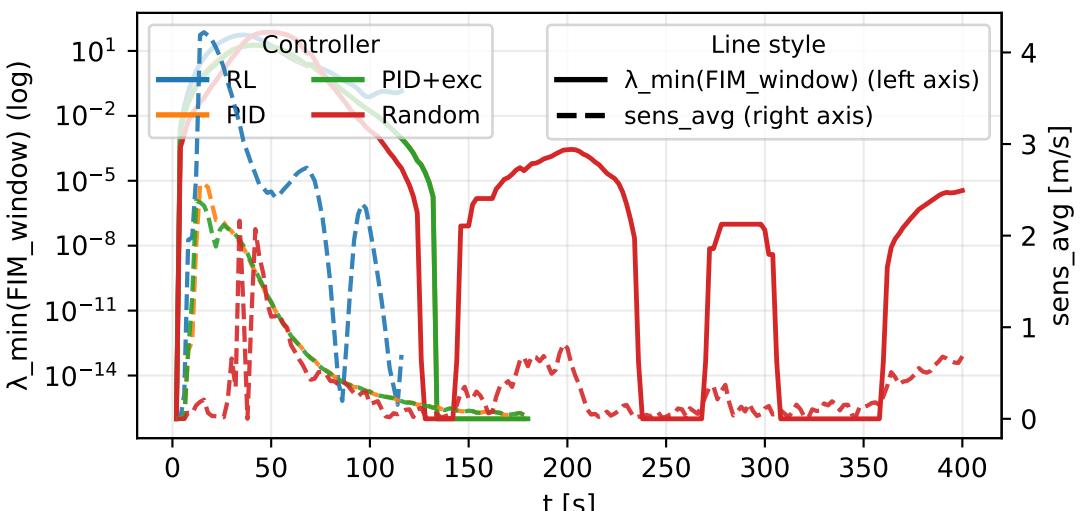
TRUE formation error



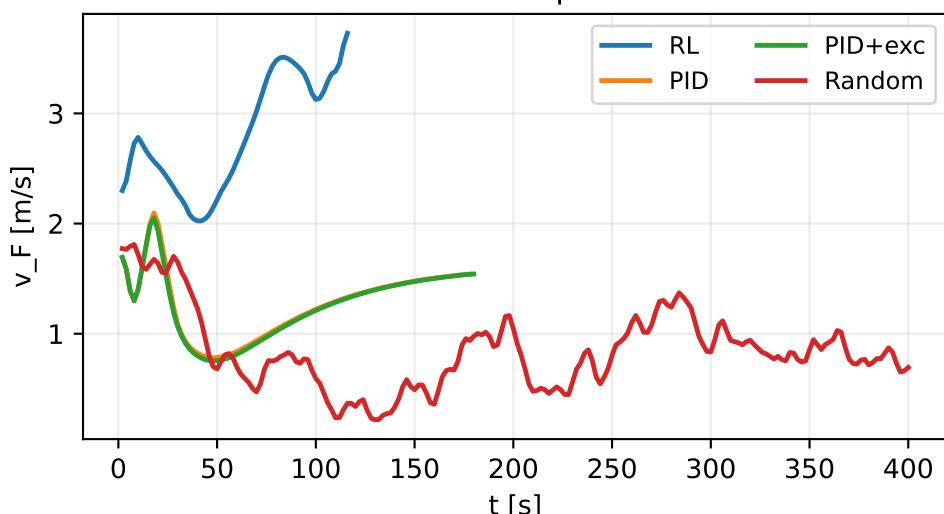
Estimator uncertainty (std_max)



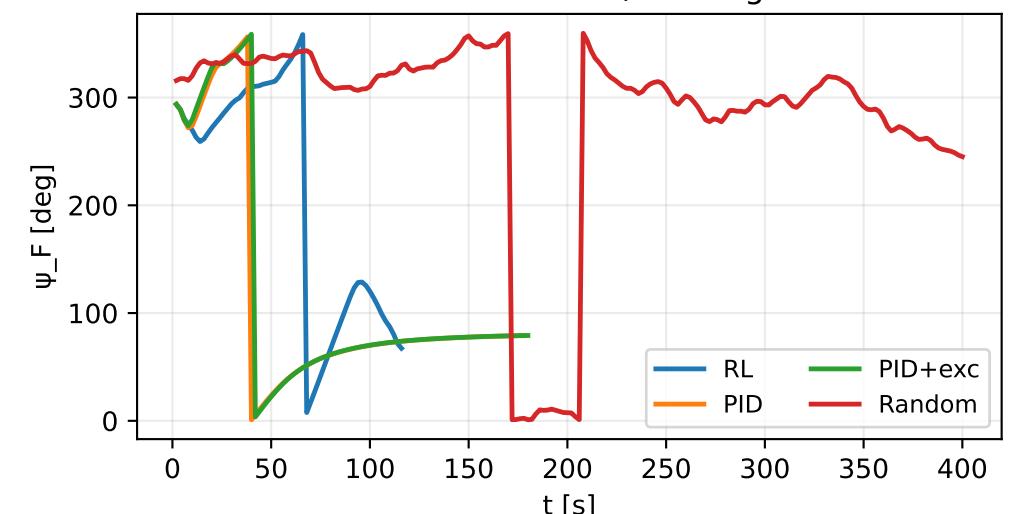
Information and excitation



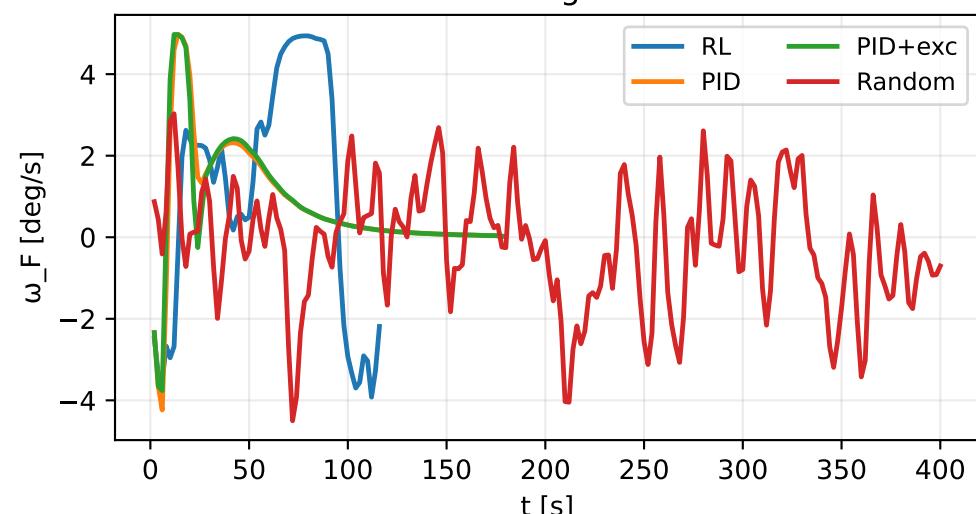
Follower speed



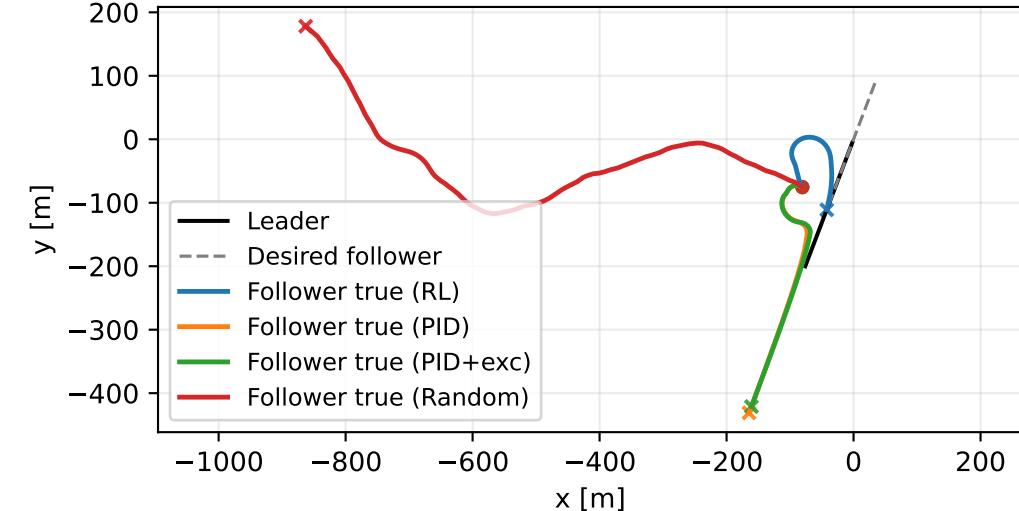
Follower course/heading



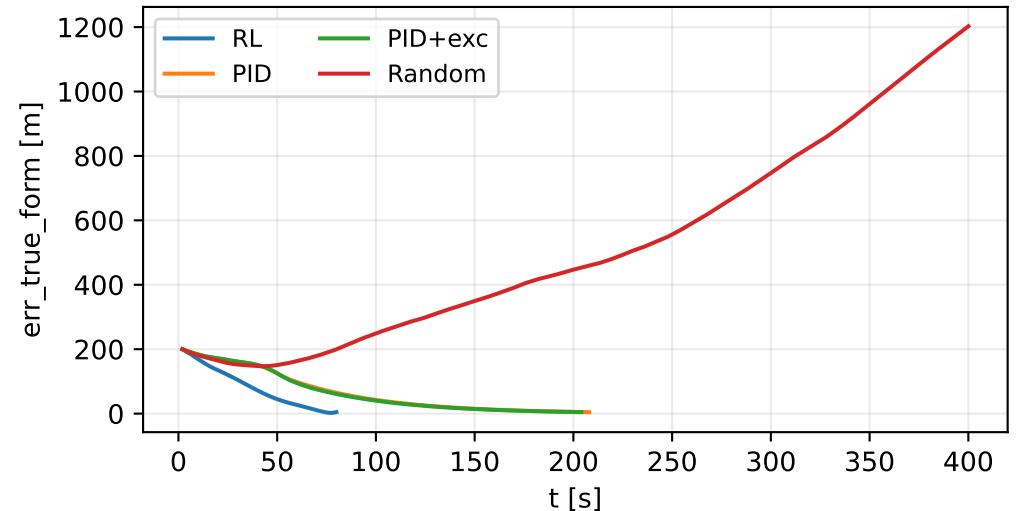
Follower angular rate



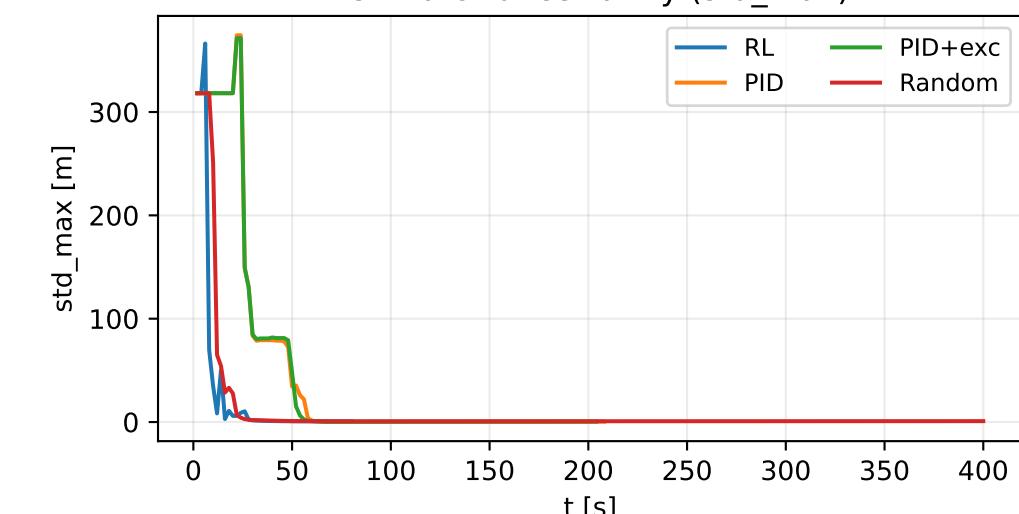
Trajectories (matched seed)



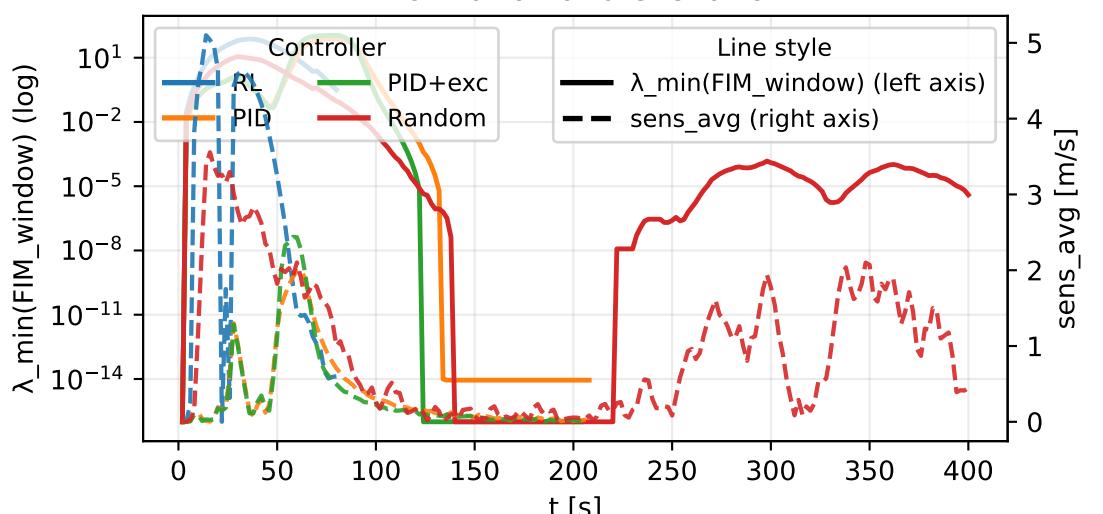
TRUE formation error



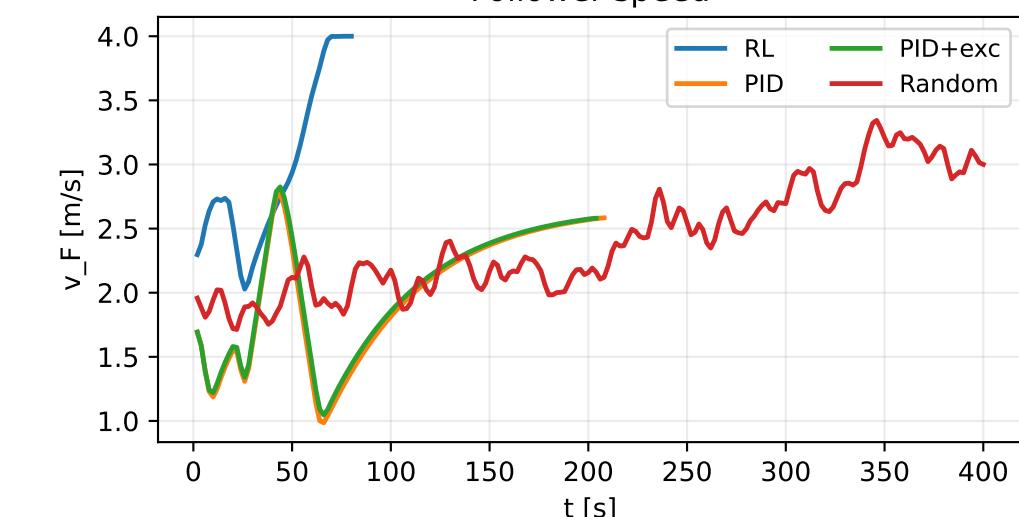
Estimator uncertainty (std_max)



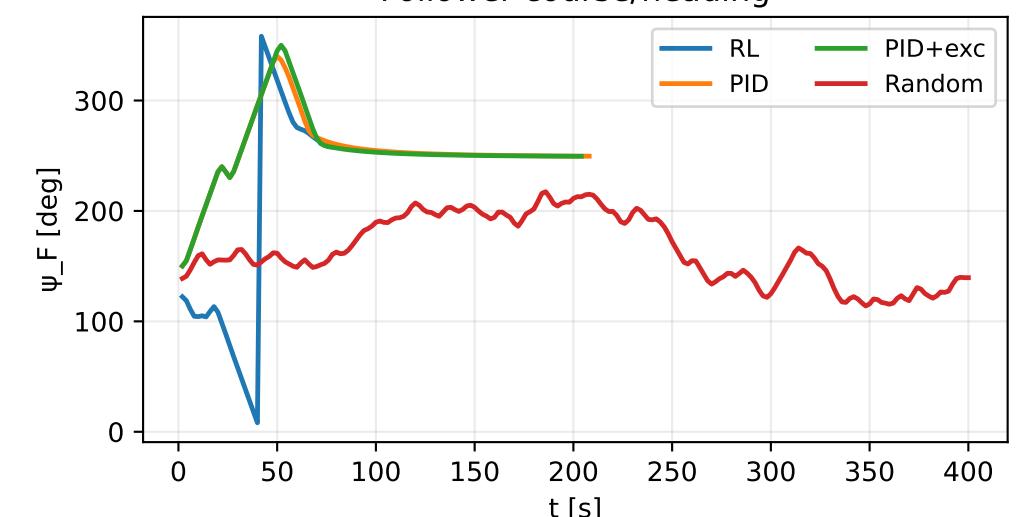
Information and excitation



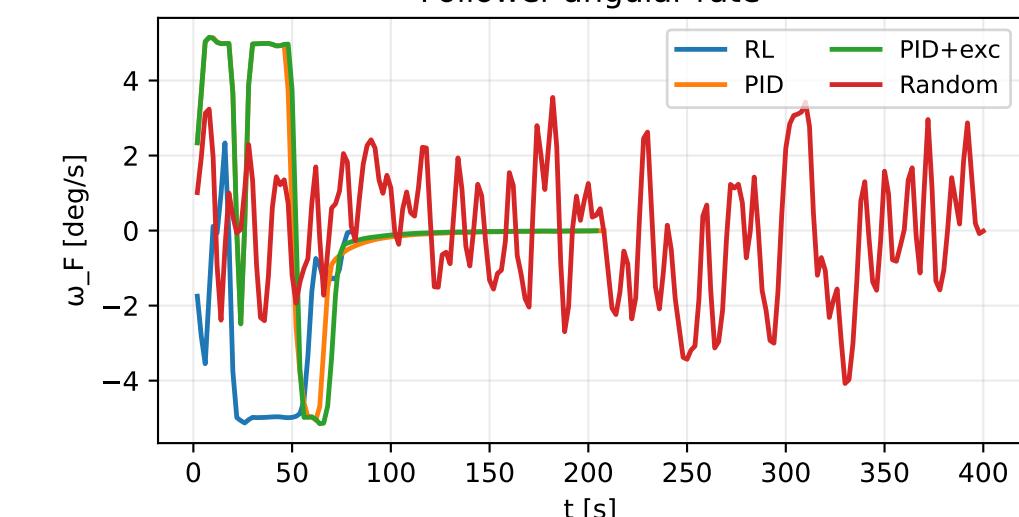
Follower speed



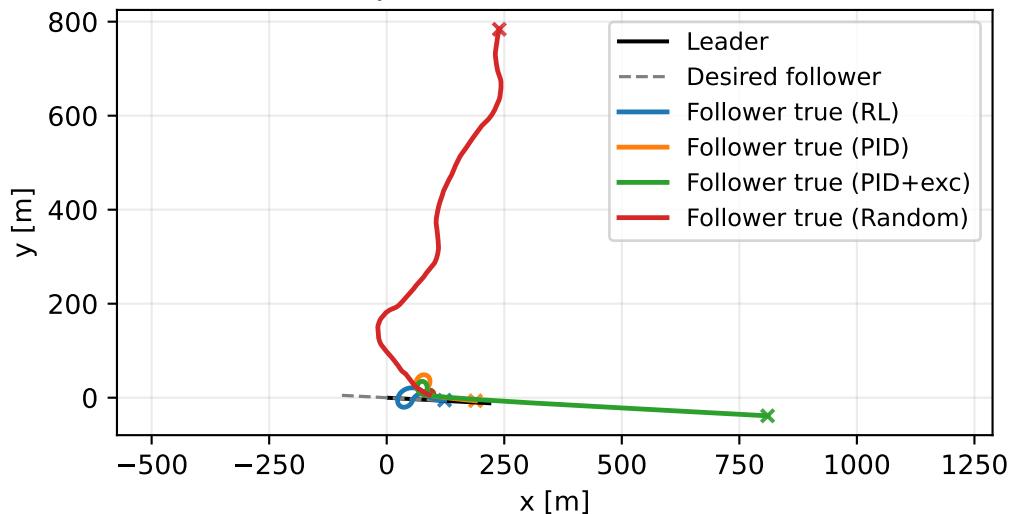
Follower course/heading



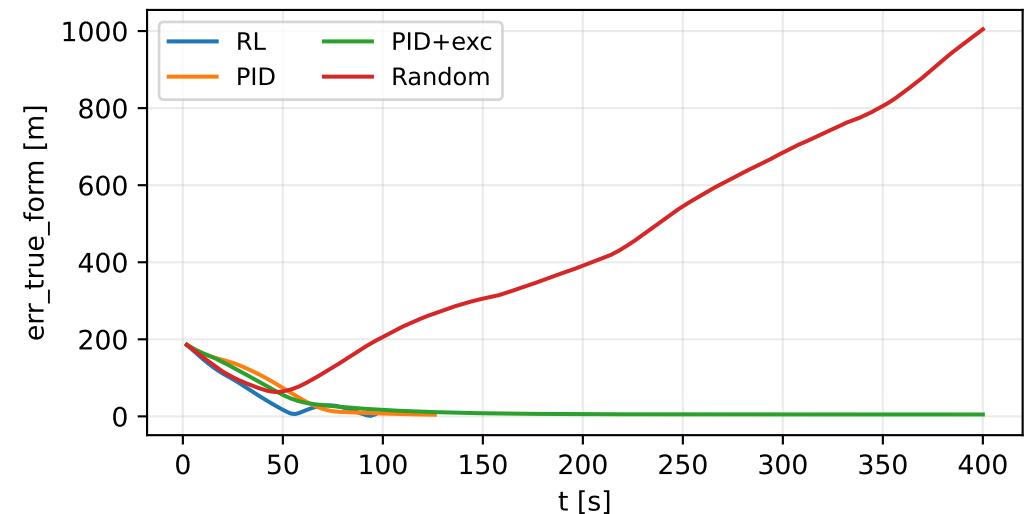
Follower angular rate



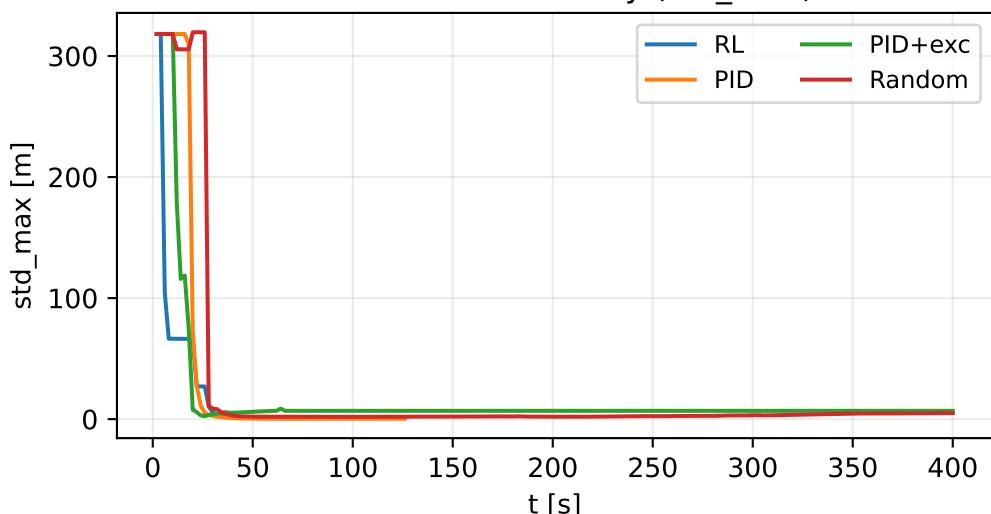
Trajectories (matched seed)



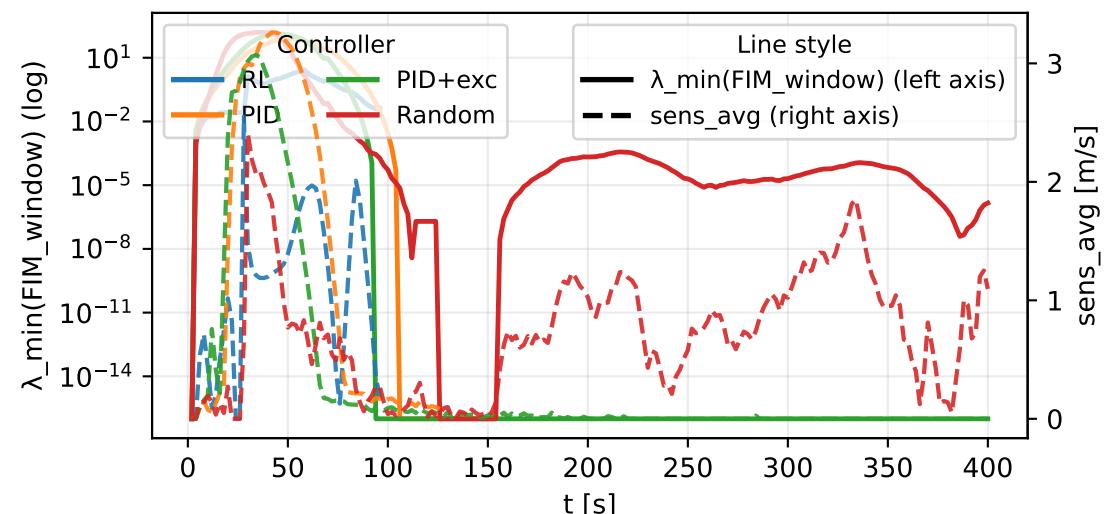
TRUE formation error



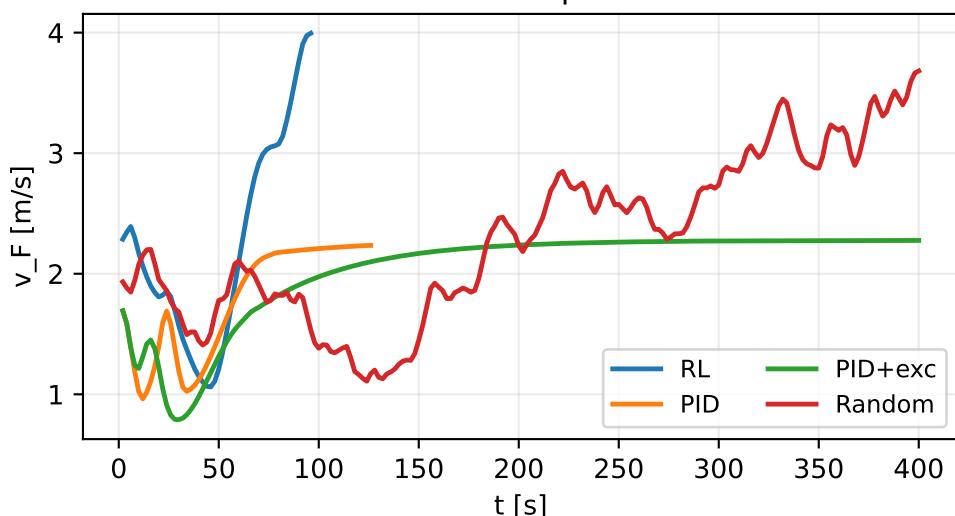
Estimator uncertainty (std_max)



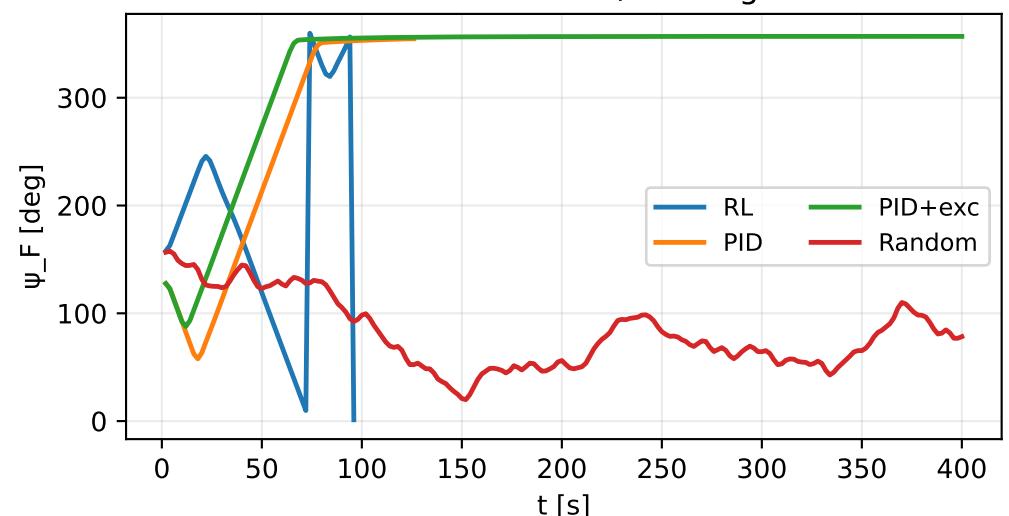
Information and excitation



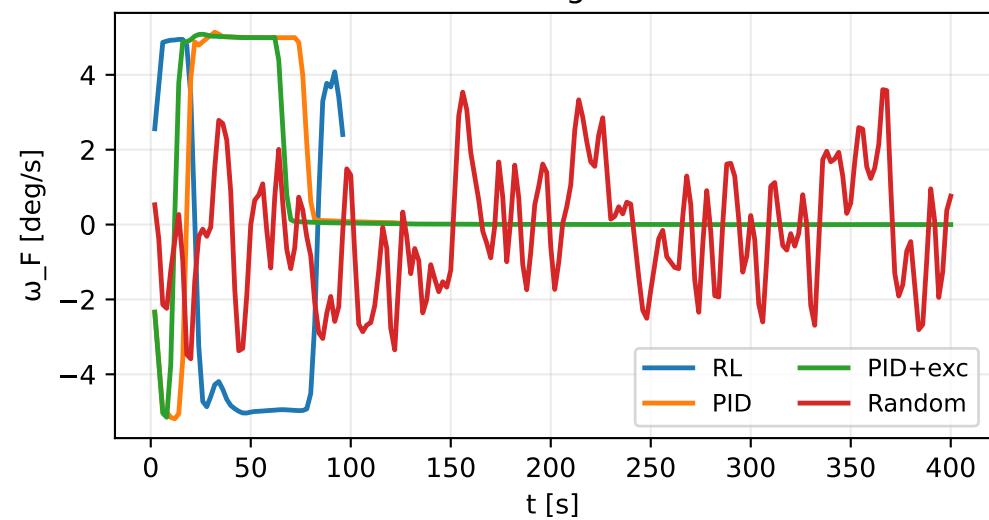
Follower speed



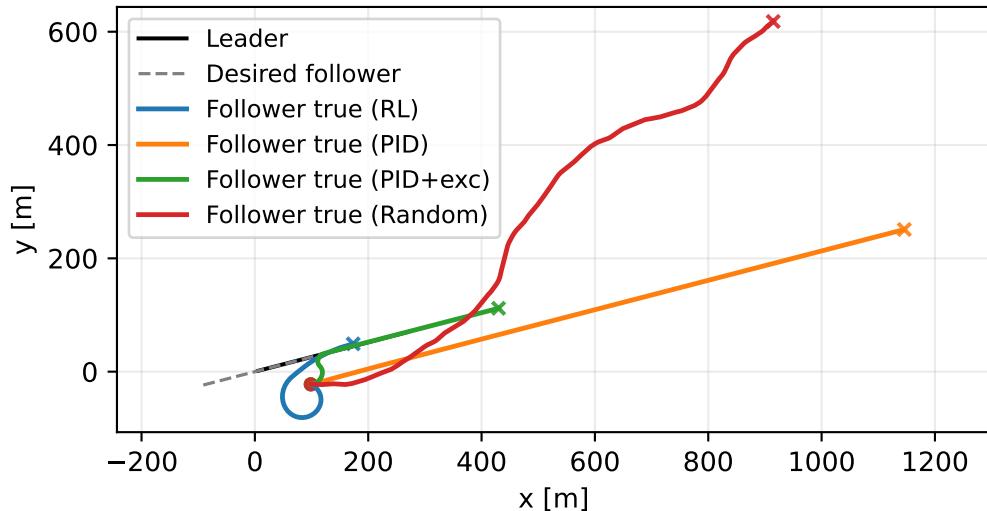
Follower course/heading



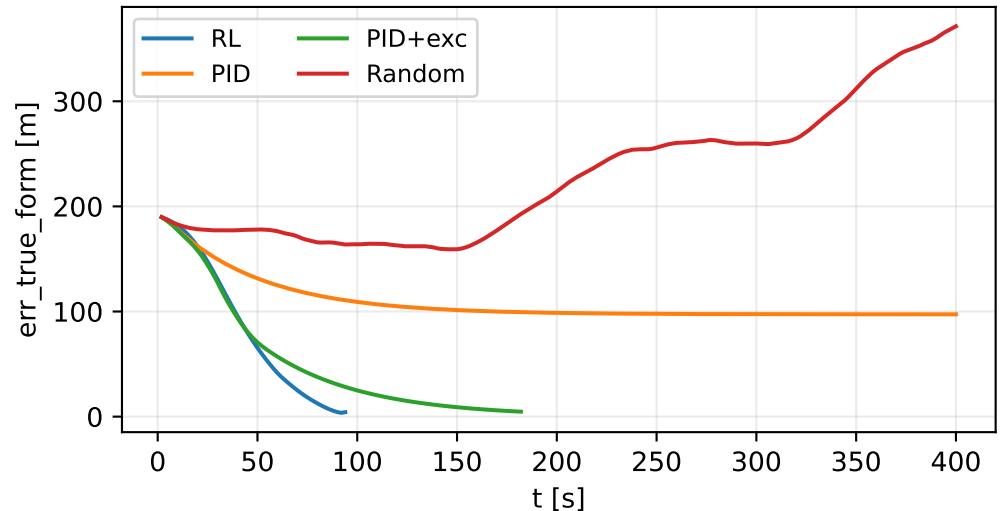
Follower angular rate



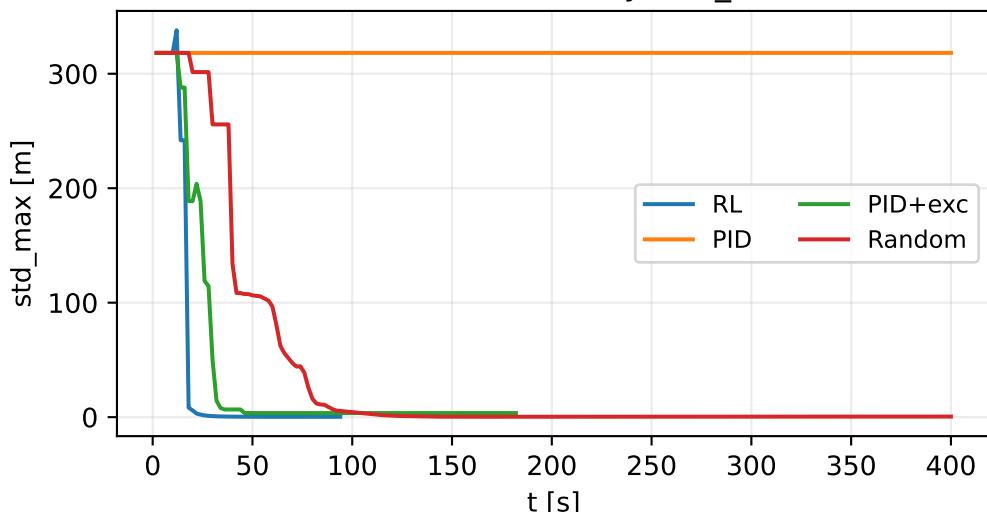
Trajectories (matched seed)



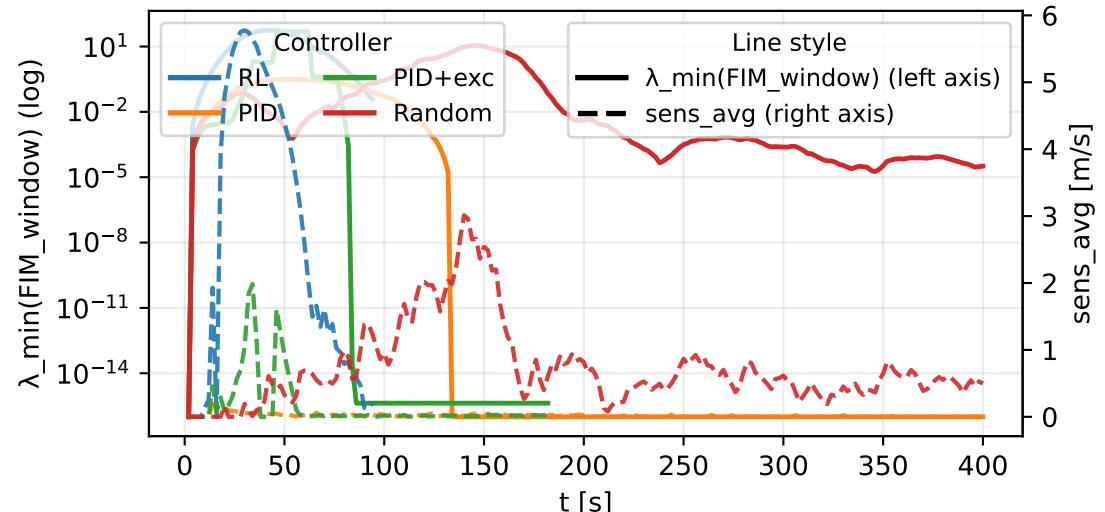
TRUE formation error



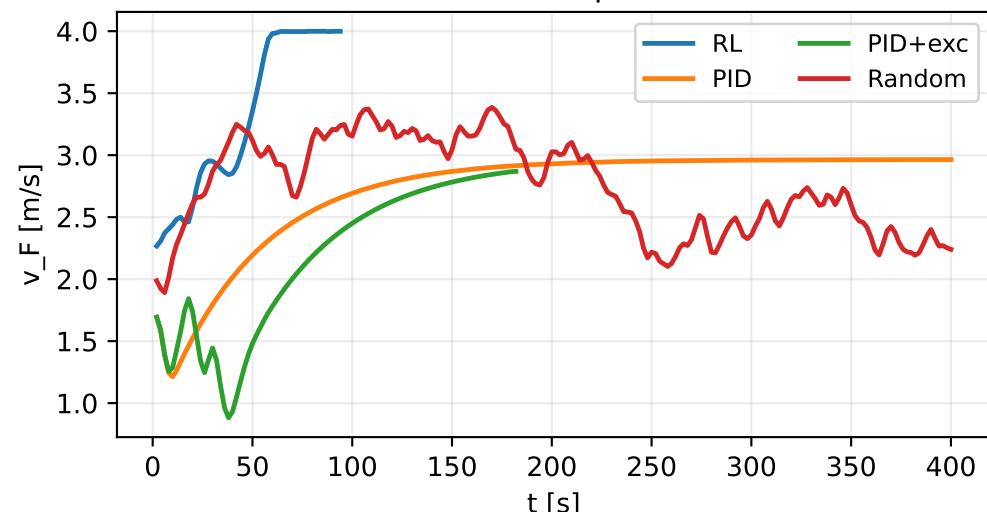
Estimator uncertainty (std_max)



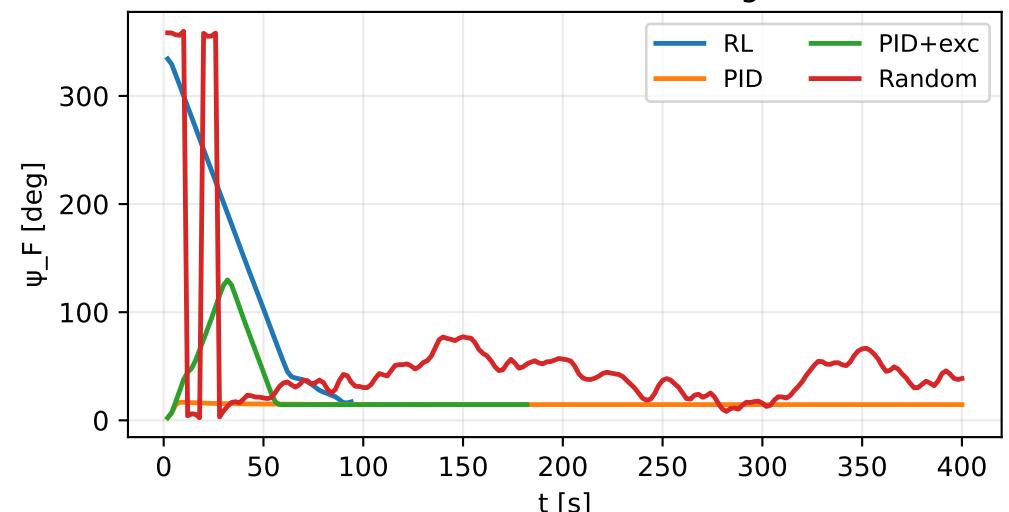
Information and excitation



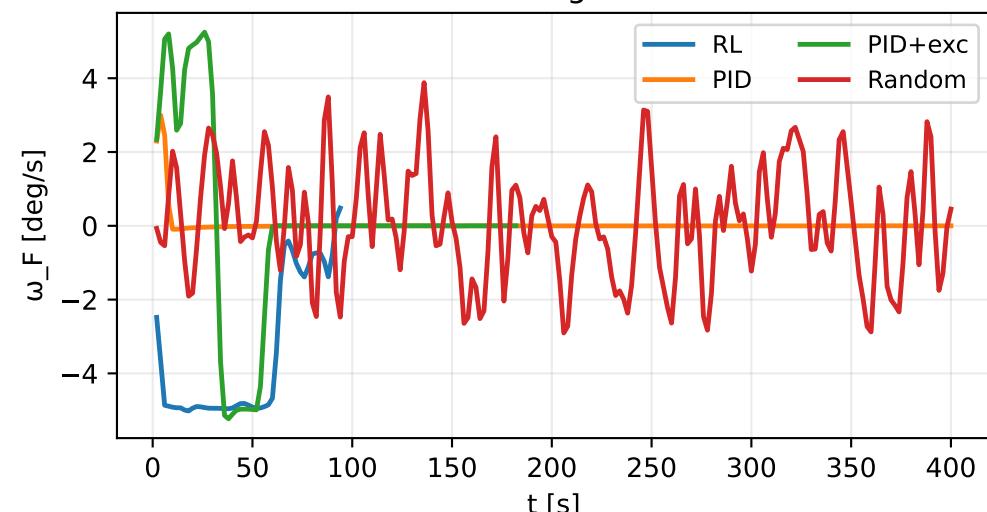
Follower speed



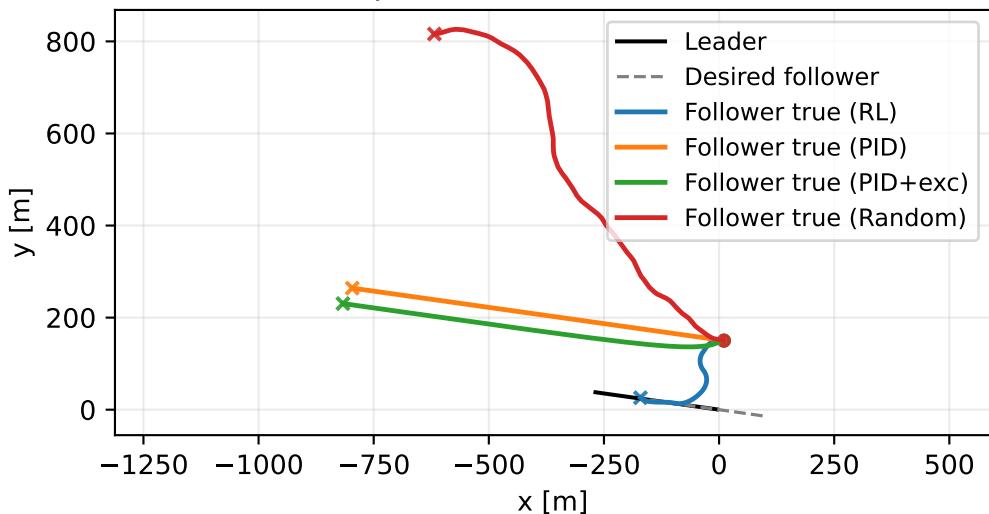
Follower course/heading



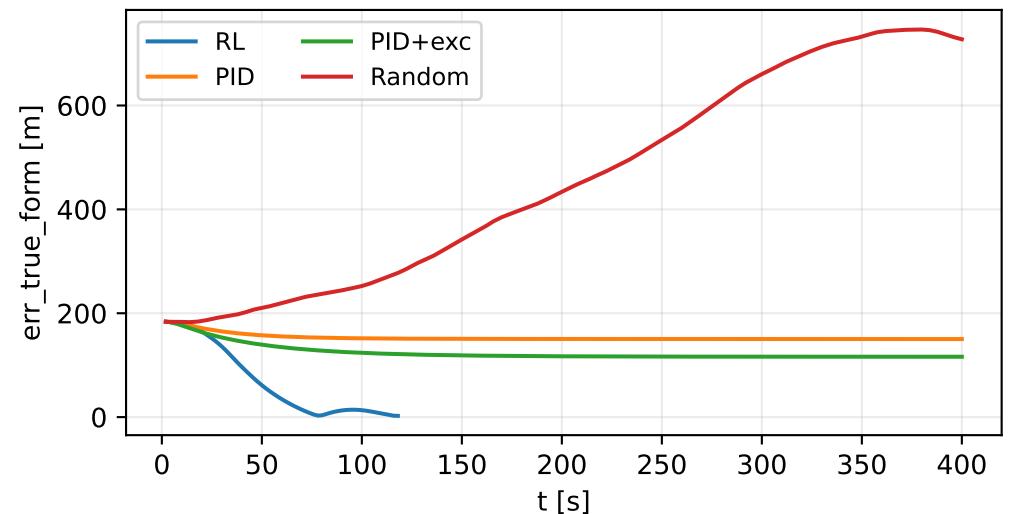
Follower angular rate



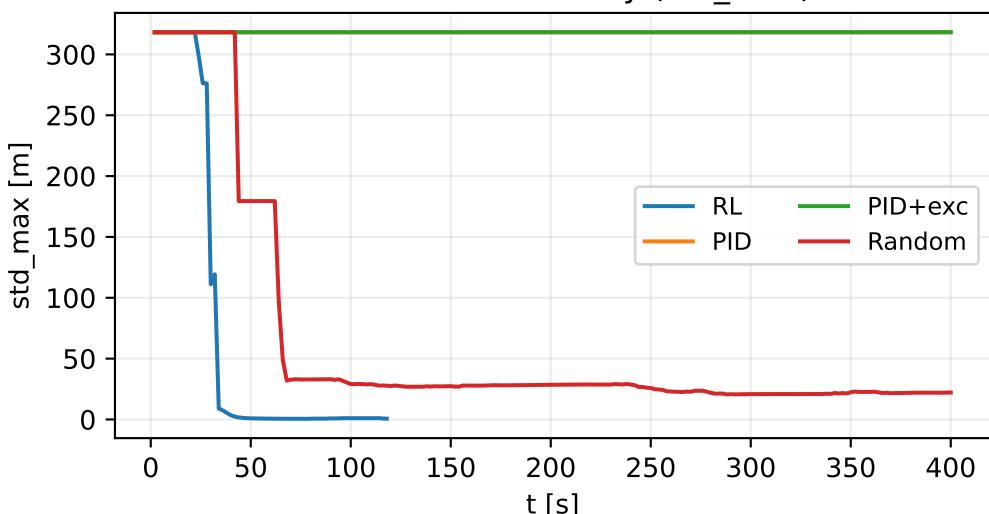
Trajectories (matched seed)



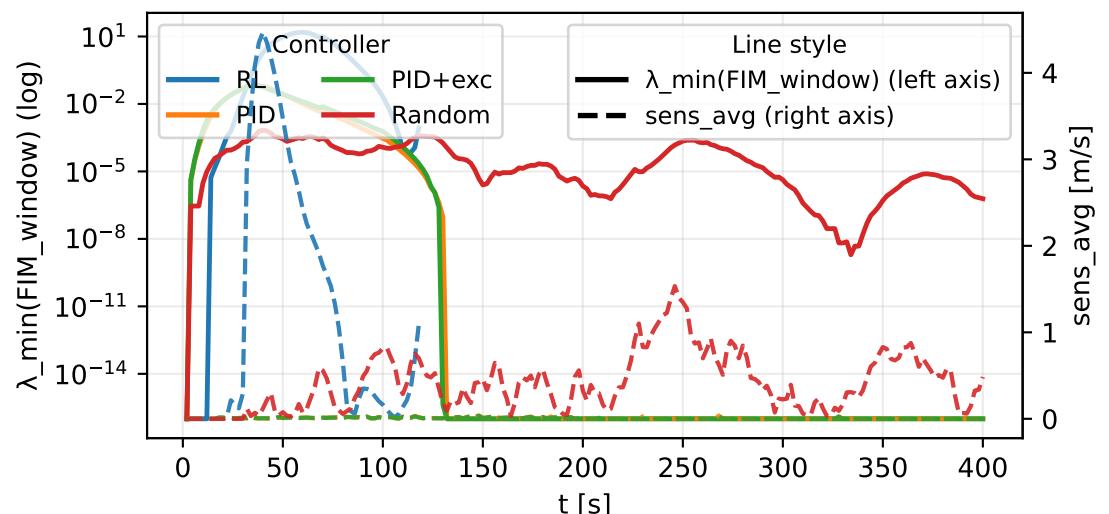
TRUE formation error



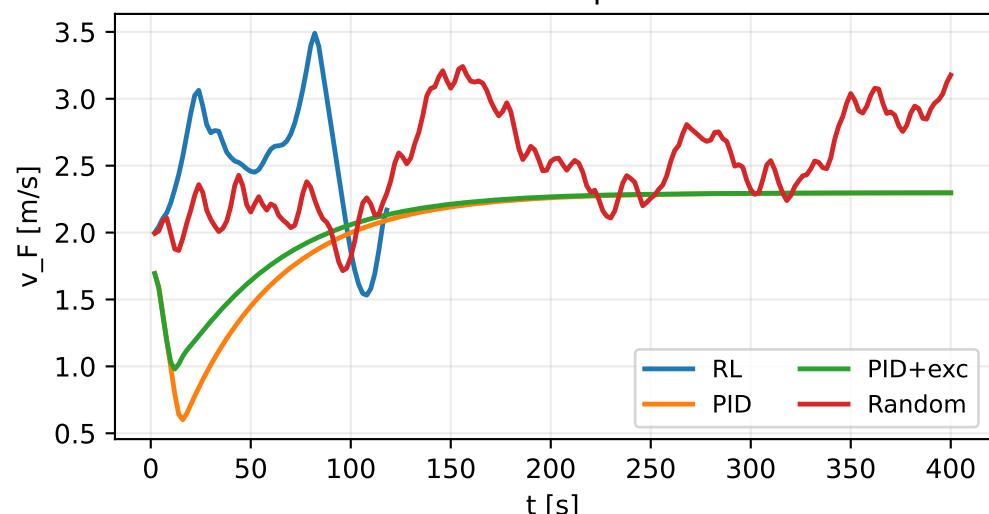
Estimator uncertainty (std_max)



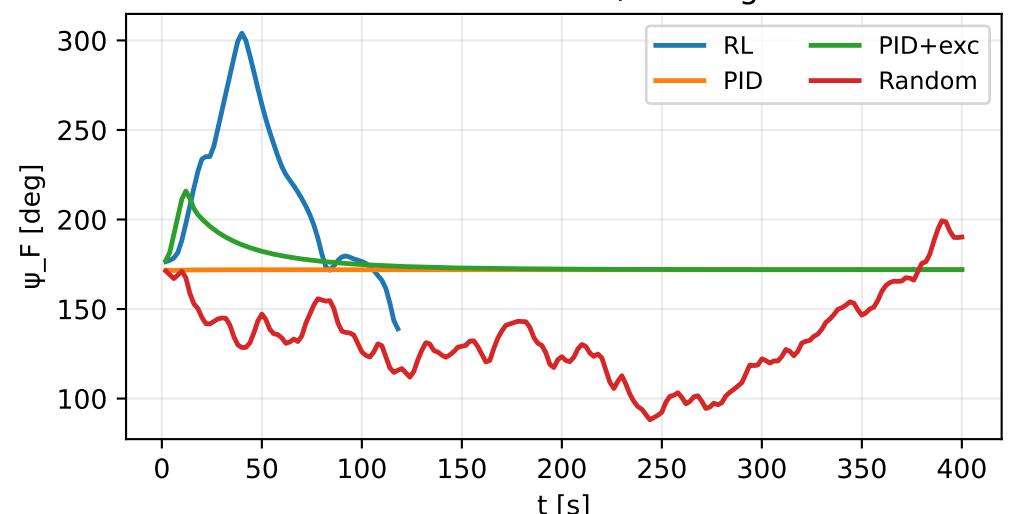
Information and excitation



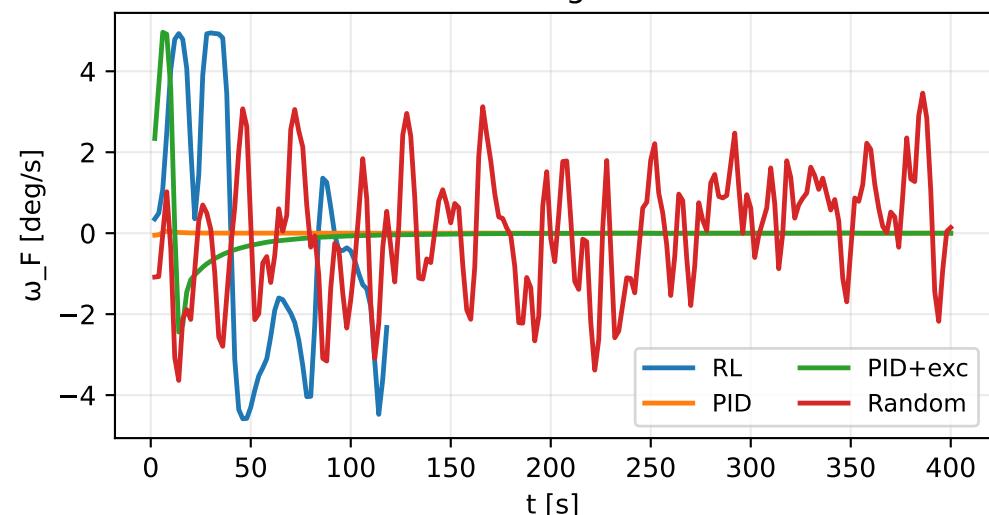
Follower speed



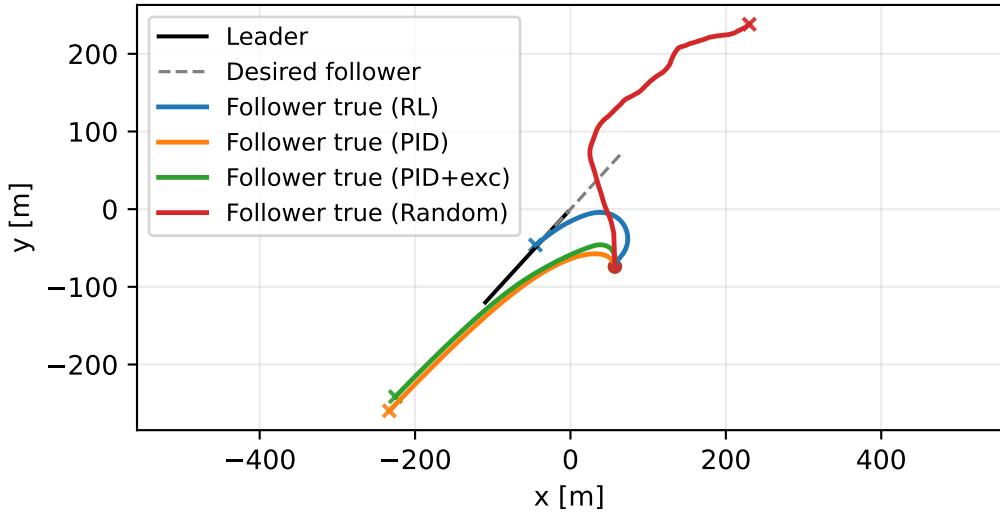
Follower course/heading



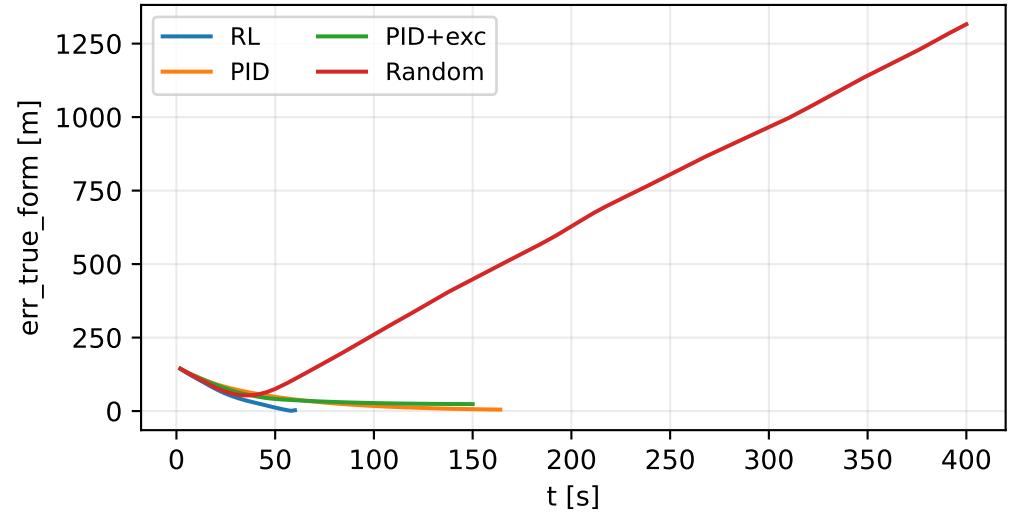
Follower angular rate



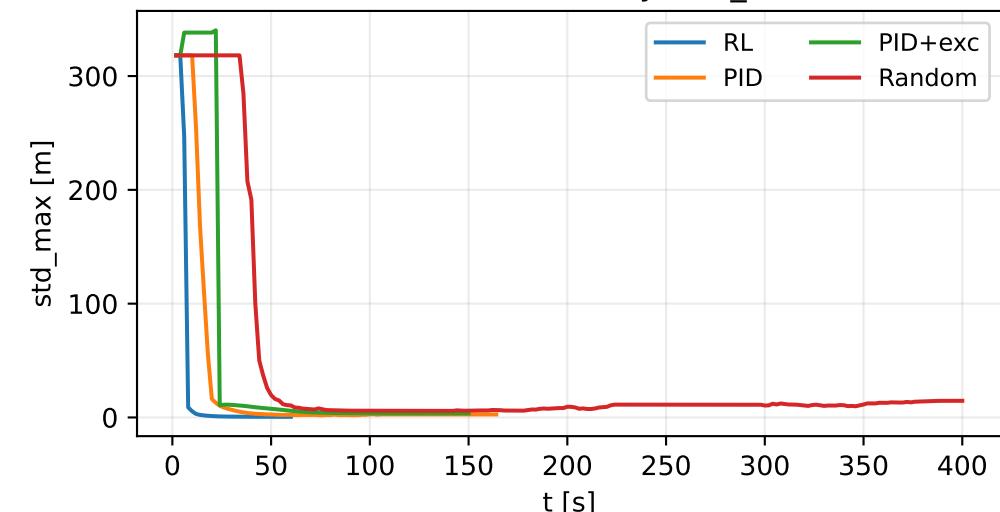
Trajectories (matched seed)



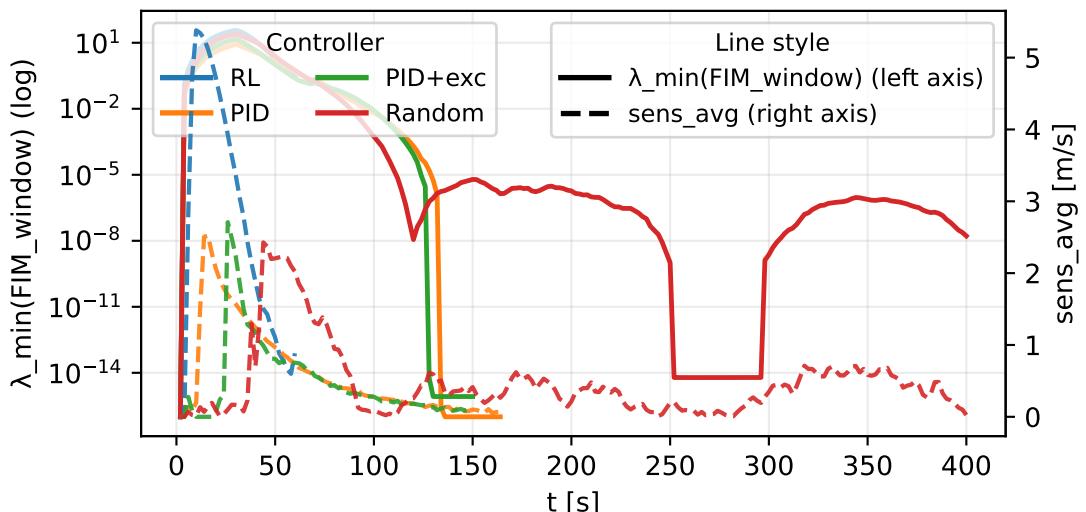
TRUE formation error



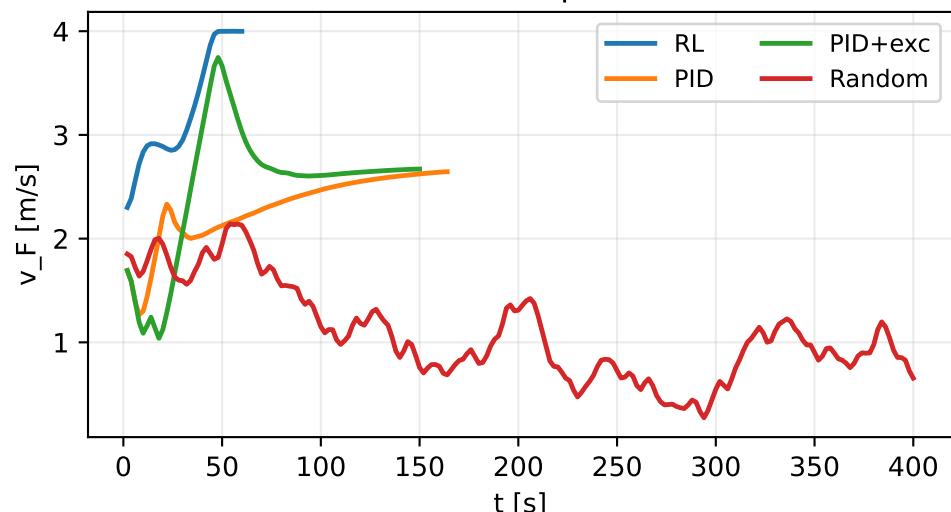
Estimator uncertainty (std_max)



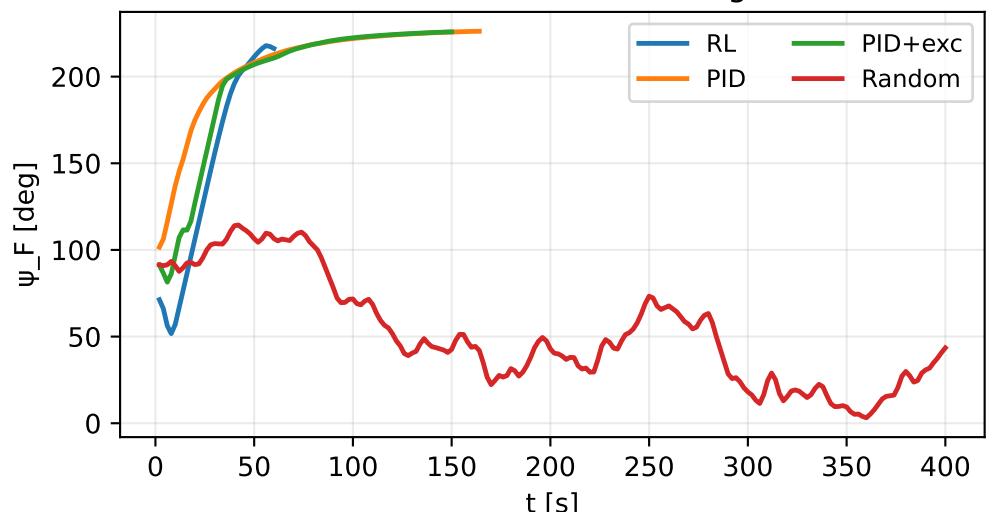
Information and excitation



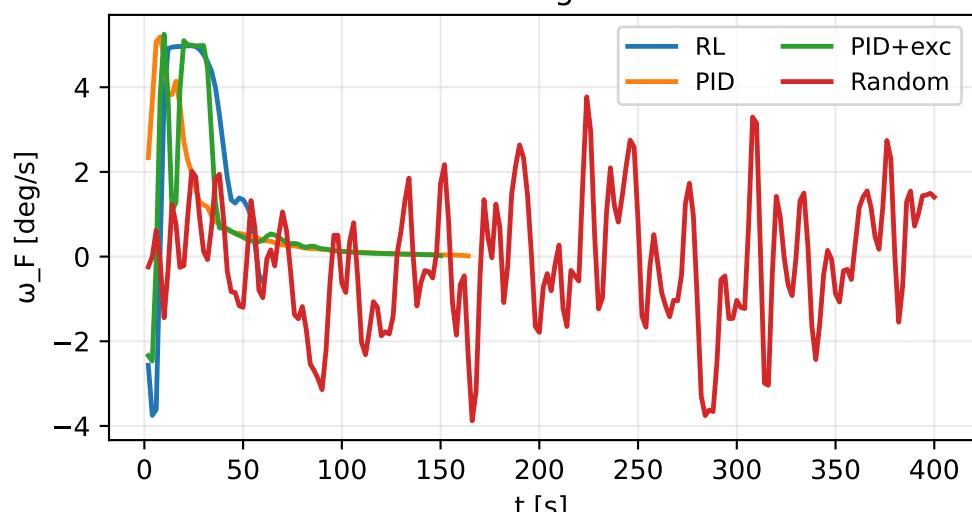
Follower speed



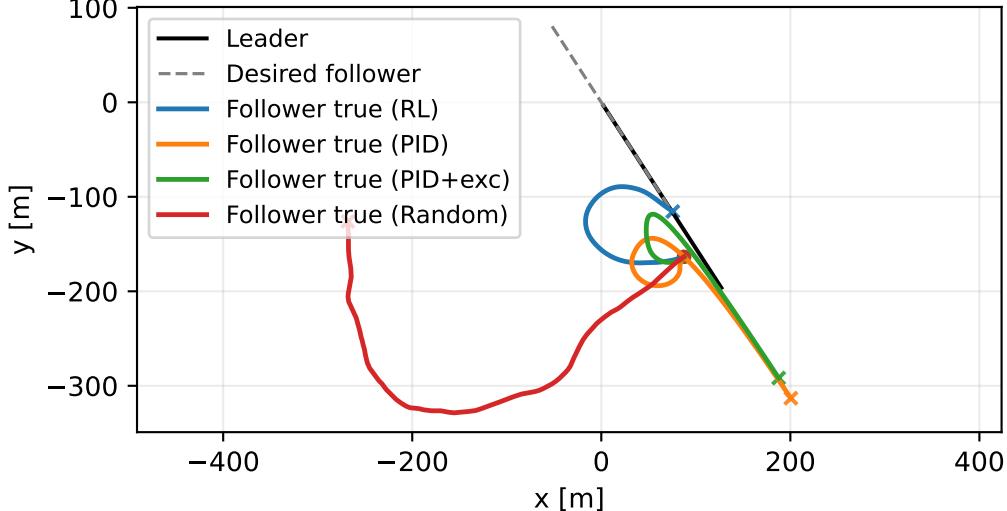
Follower course/heading



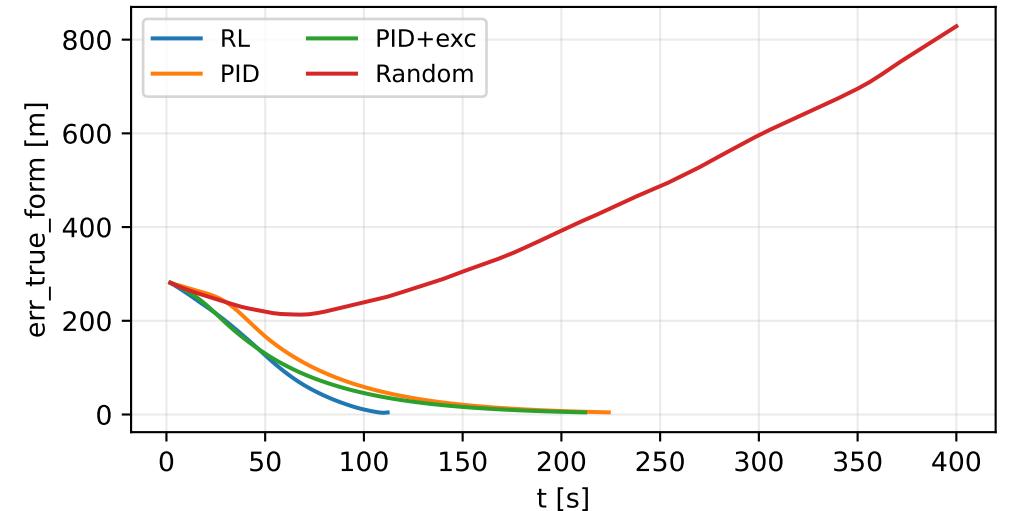
Follower angular rate



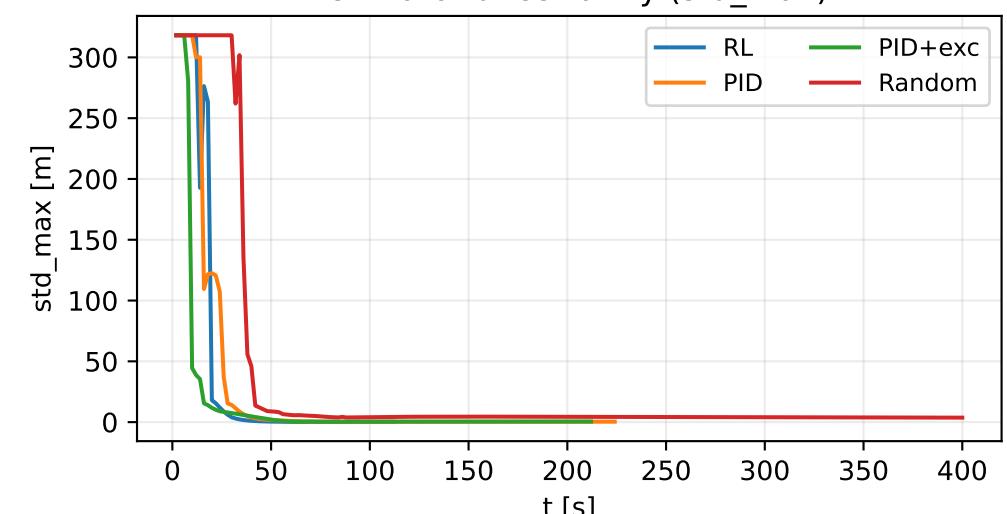
Trajectories (matched seed)



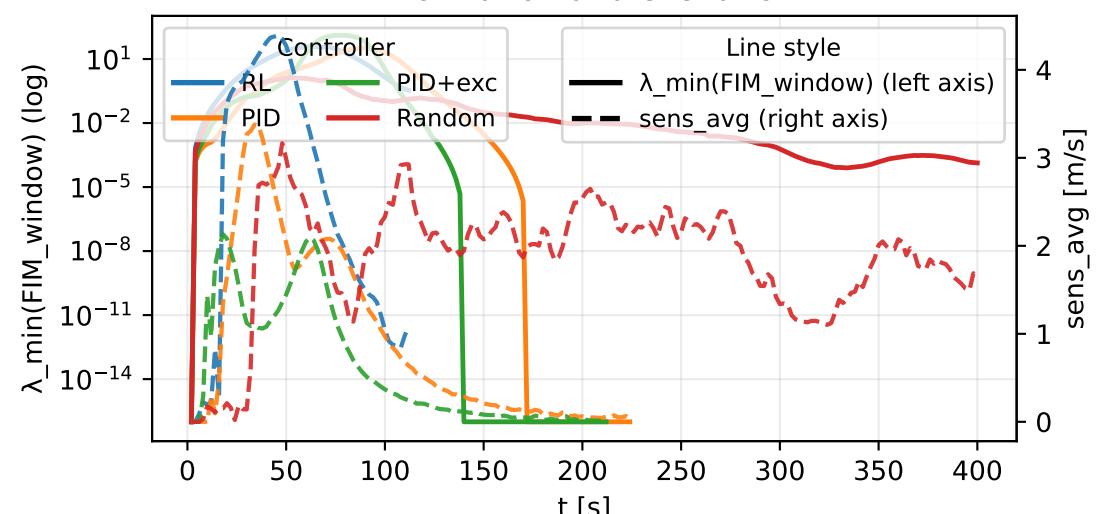
TRUE formation error



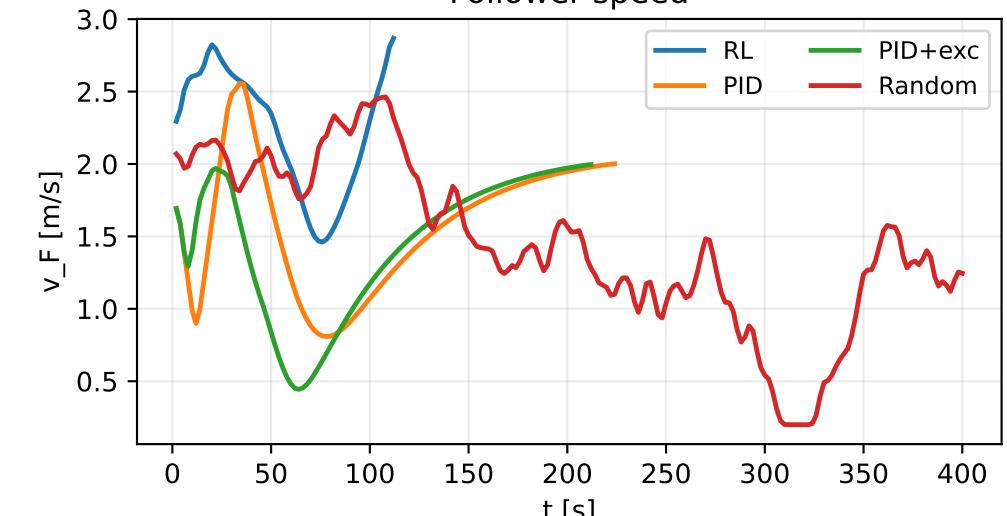
Estimator uncertainty (std_max)



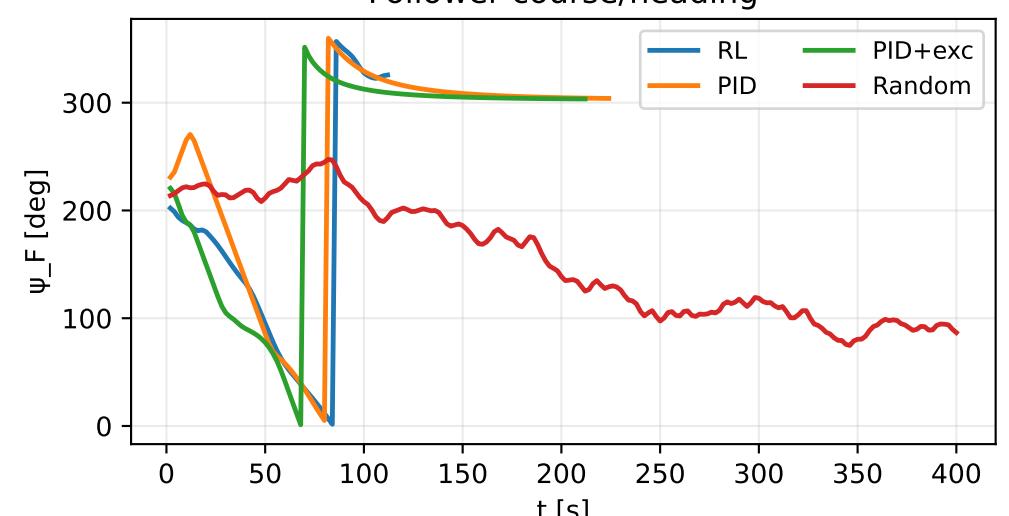
Information and excitation



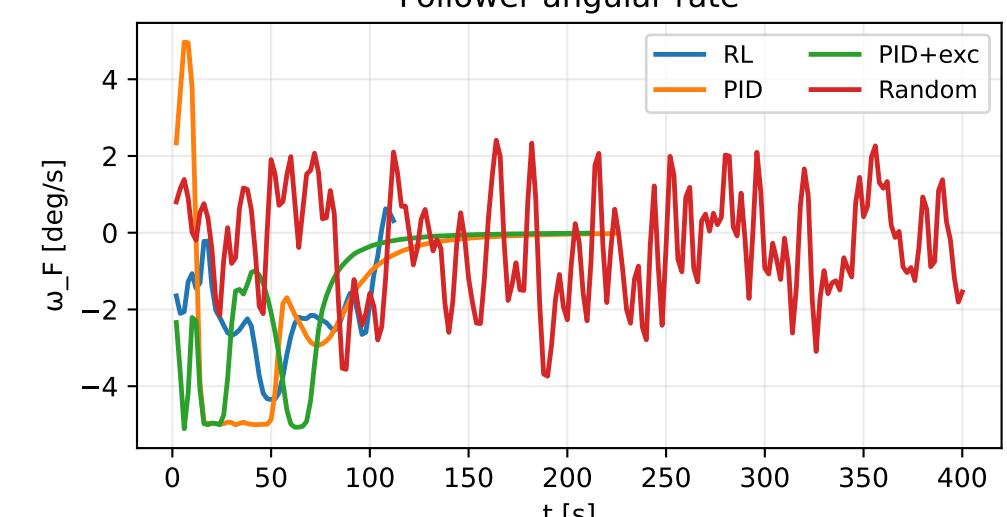
Follower speed



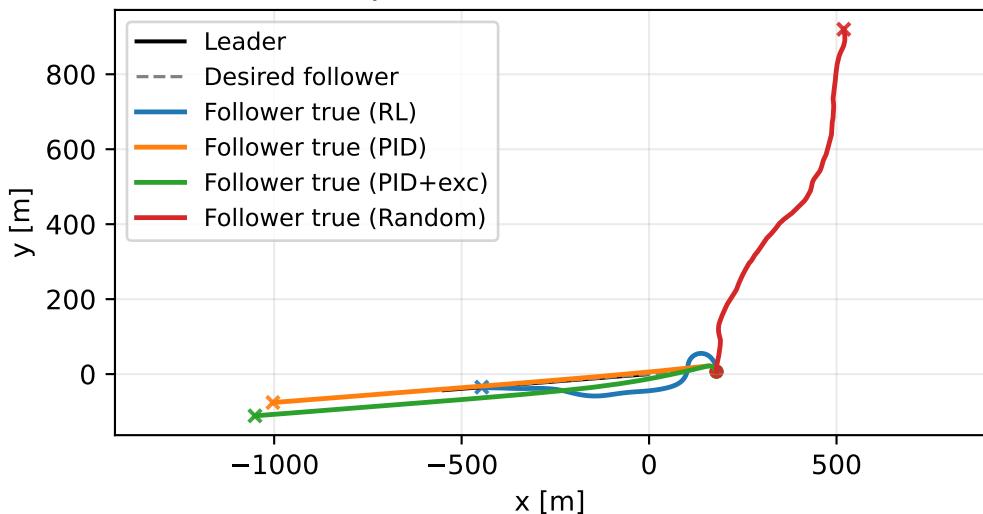
Follower course/heading



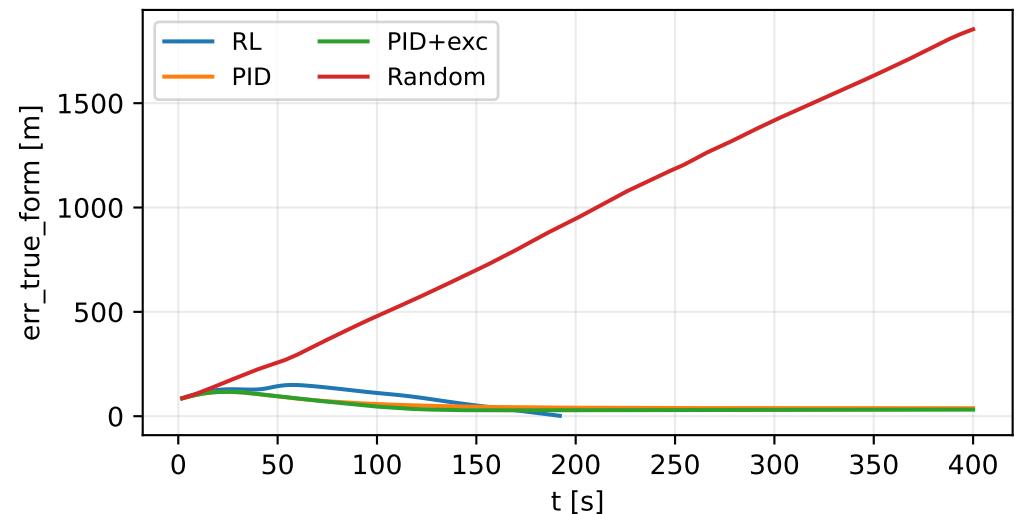
Follower angular rate



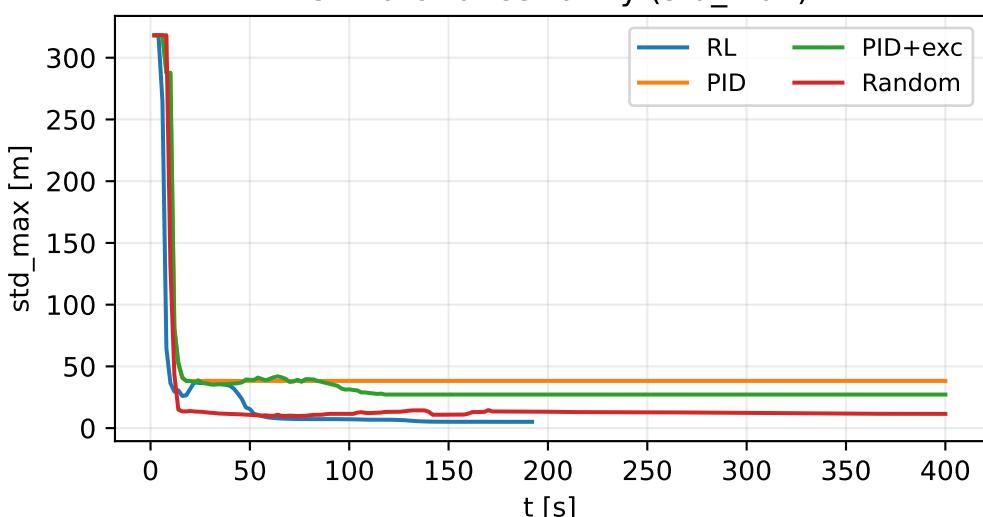
Trajectories (matched seed)



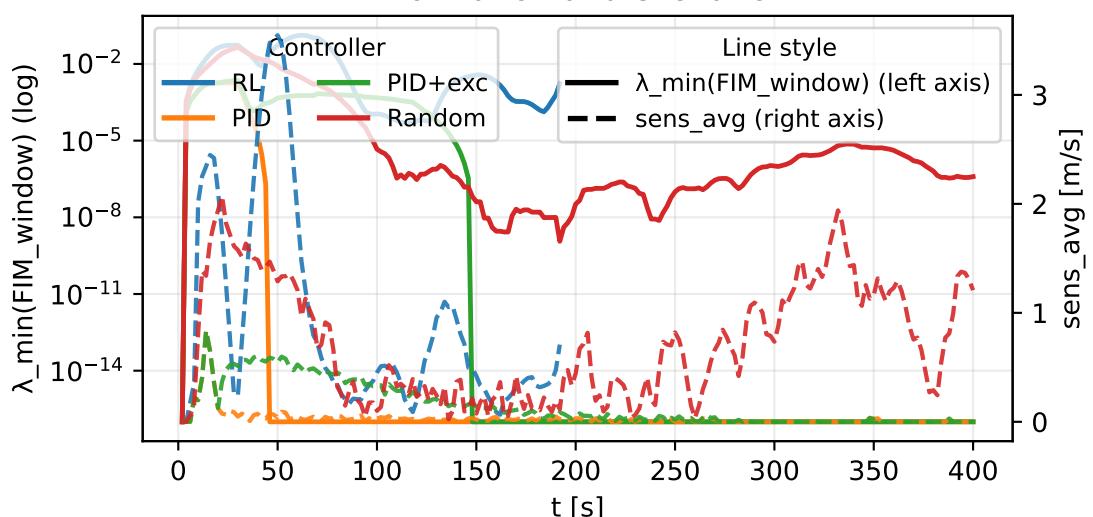
TRUE formation error



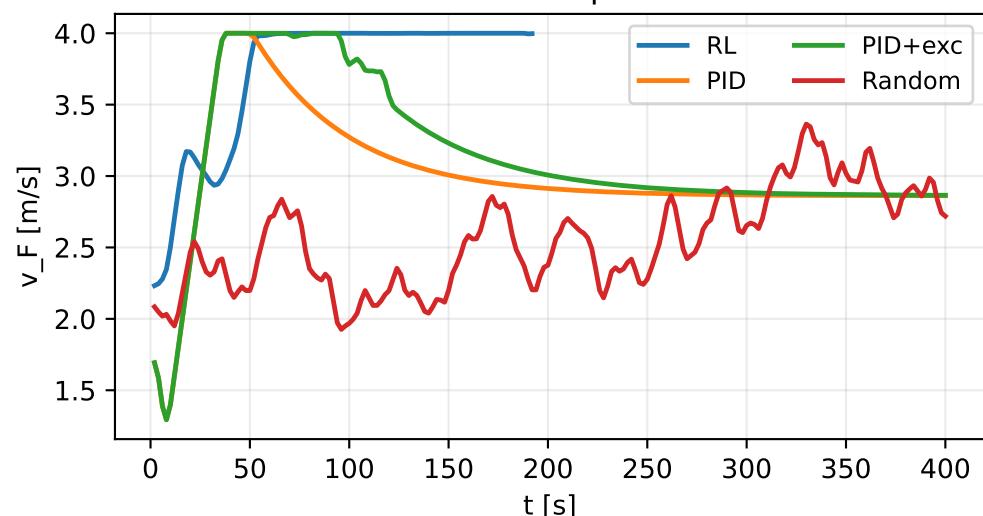
Estimator uncertainty (std_max)



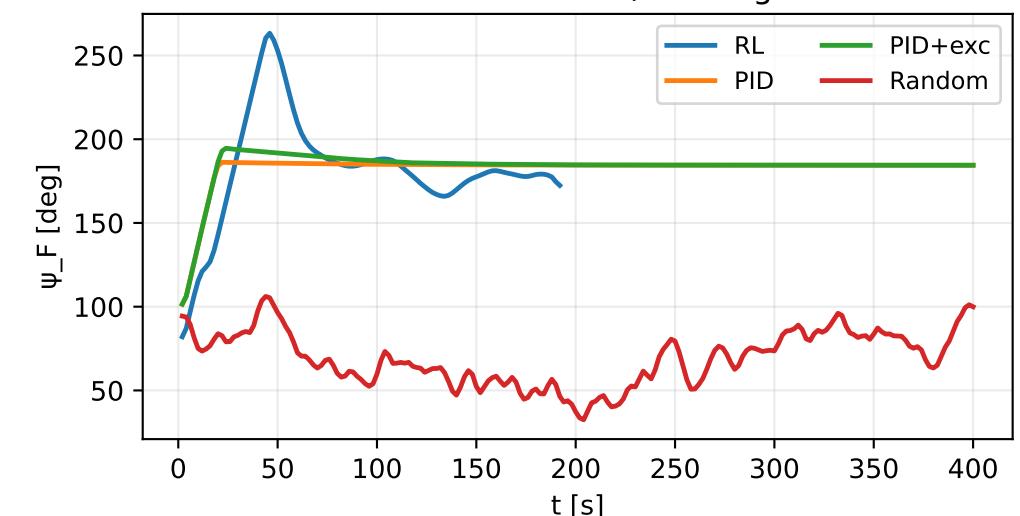
Information and excitation



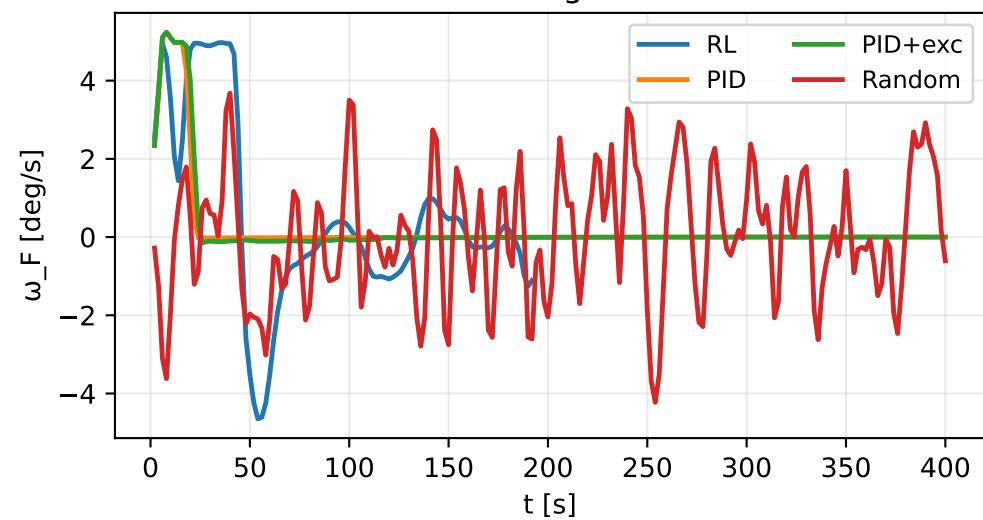
Follower speed



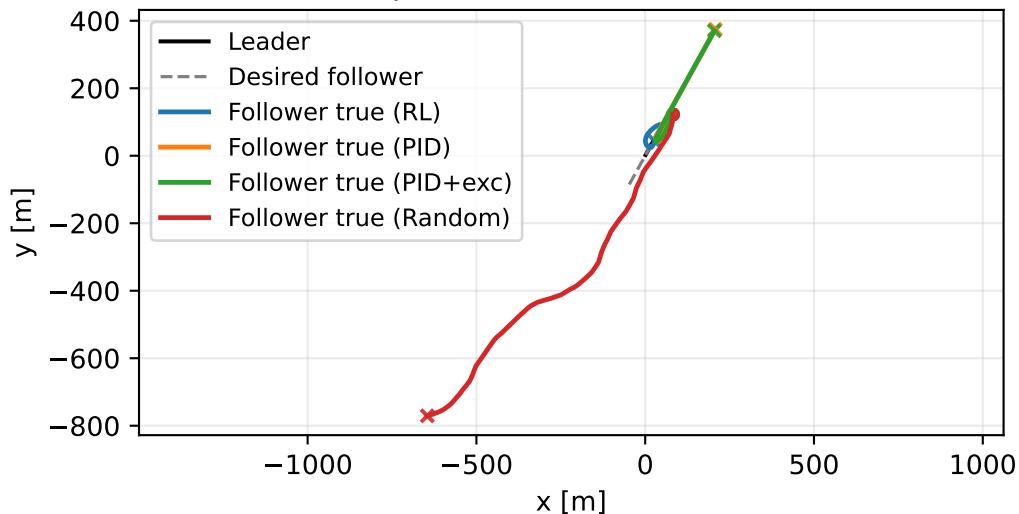
Follower course/heading



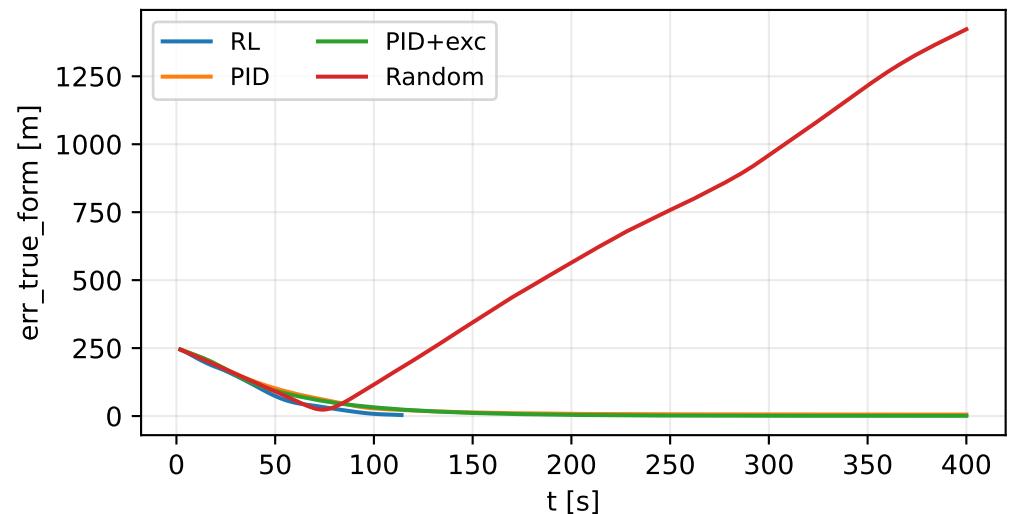
Follower angular rate



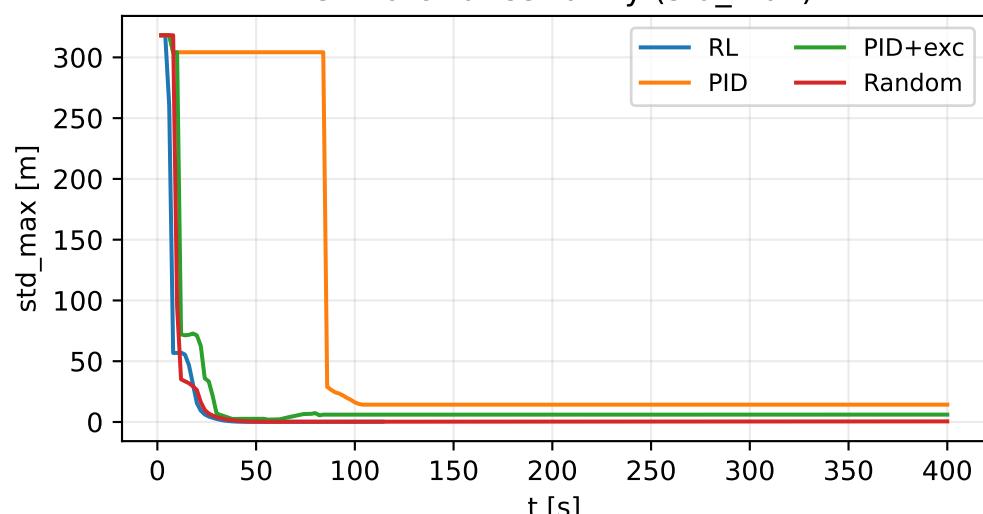
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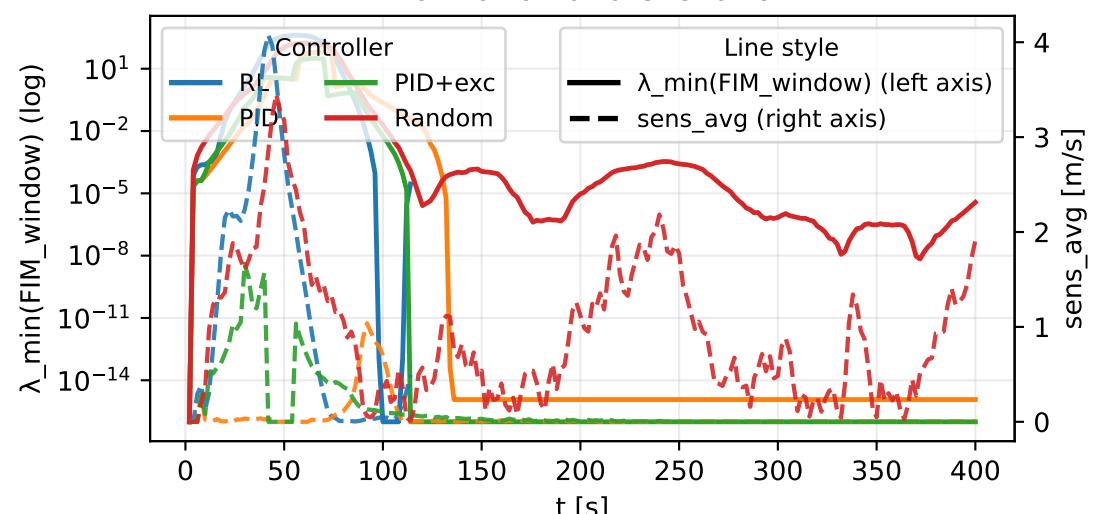
TRUE formation error



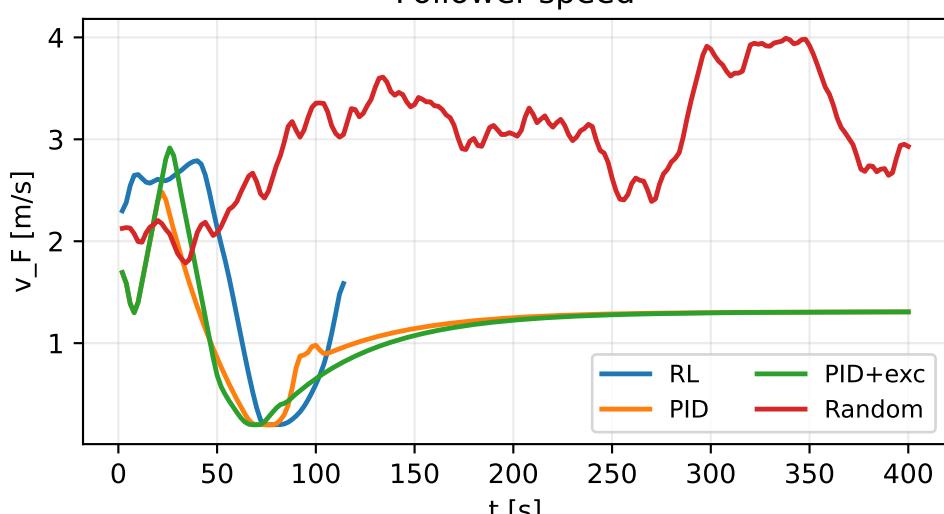
Estimator uncertainty (std_max)



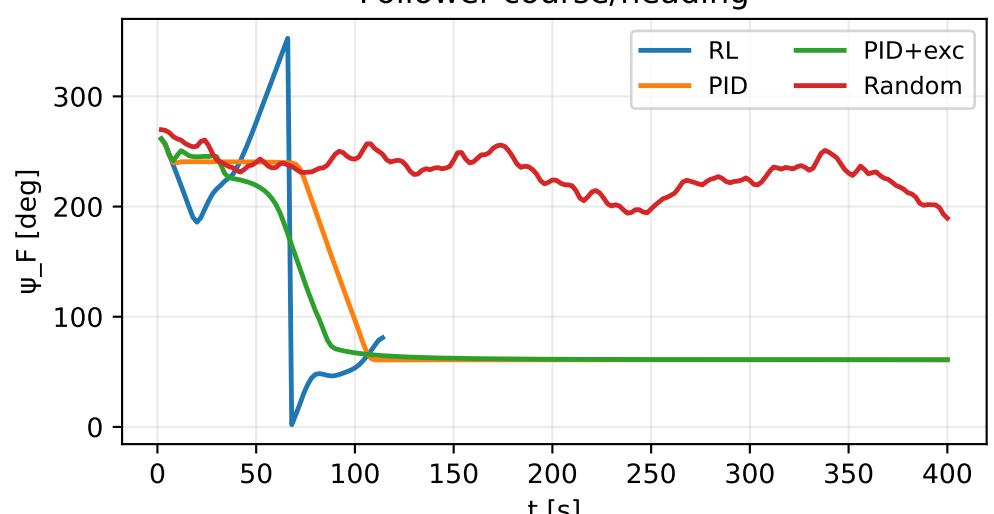
Information and excitation



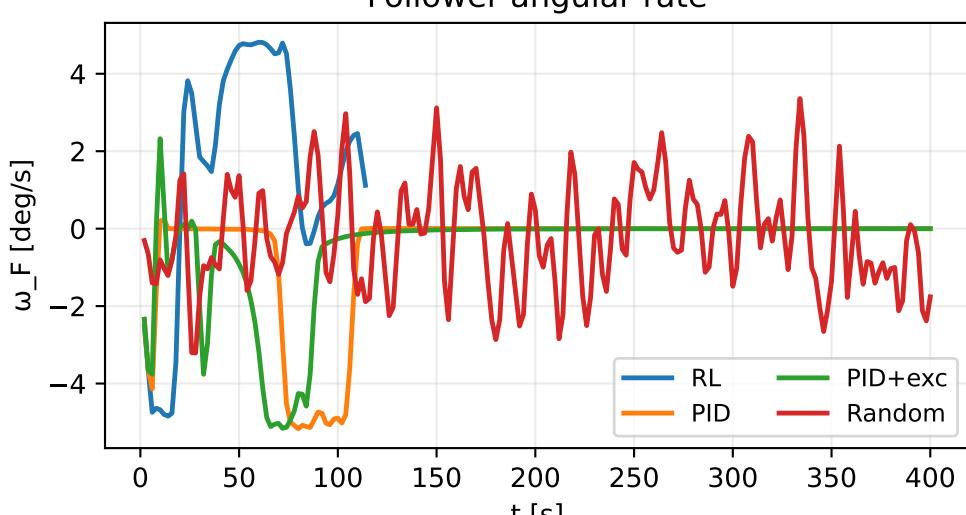
Follower speed



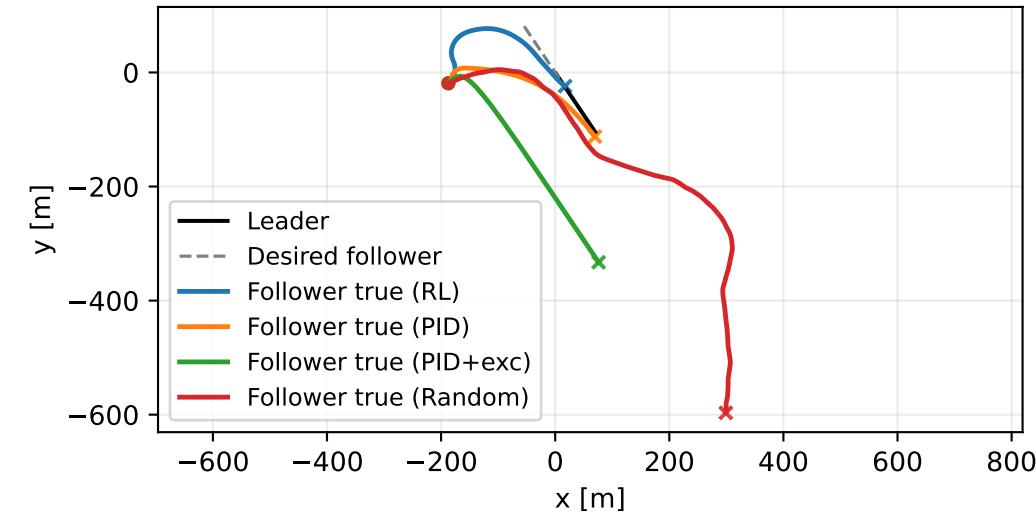
Follower course/heading



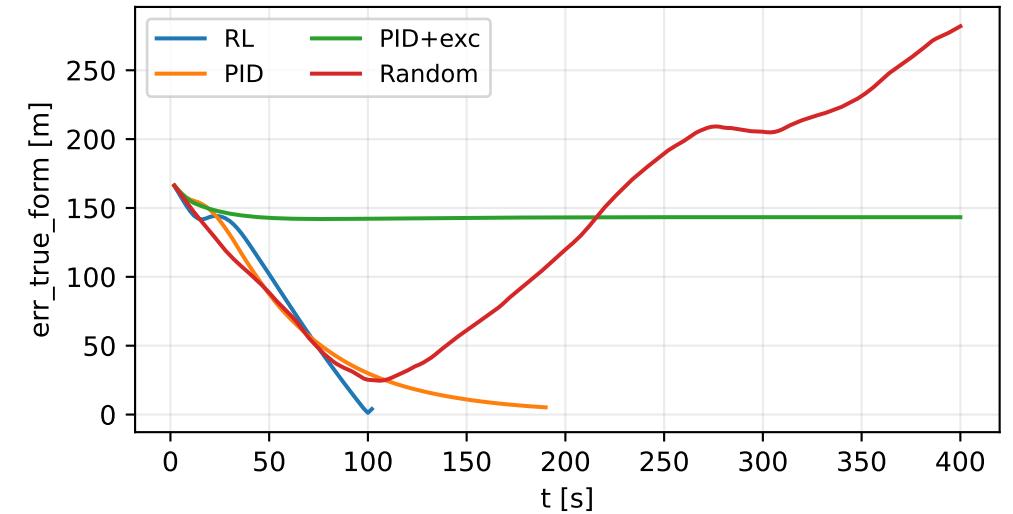
Follower angular rate



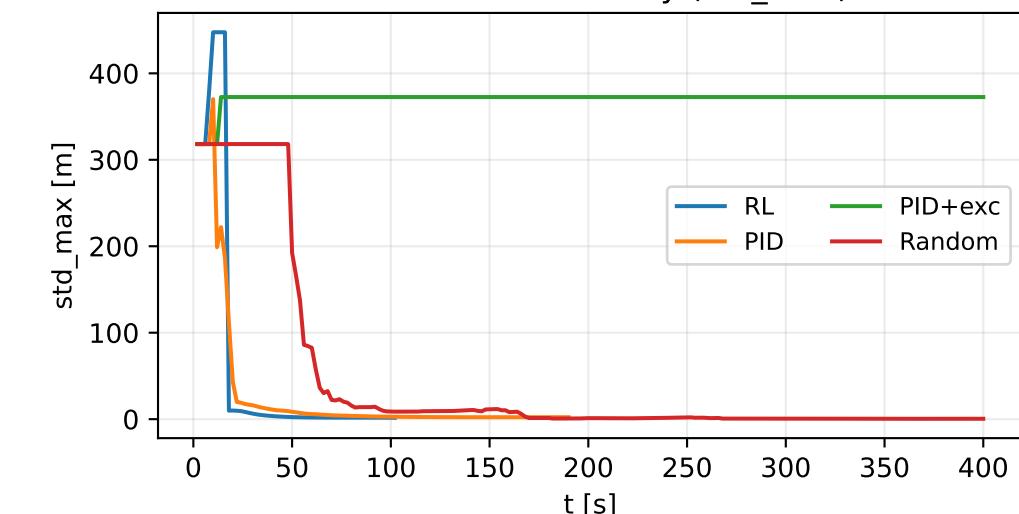
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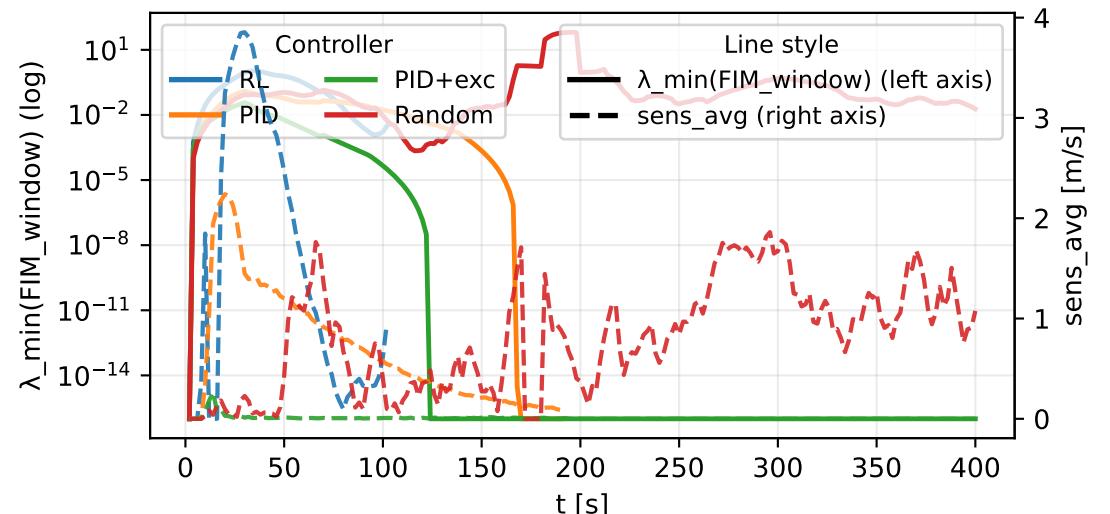
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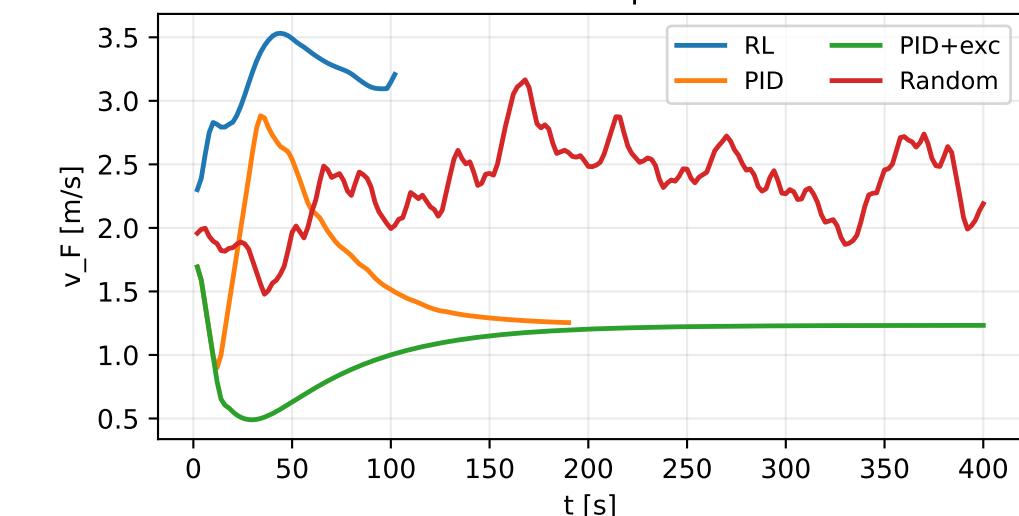
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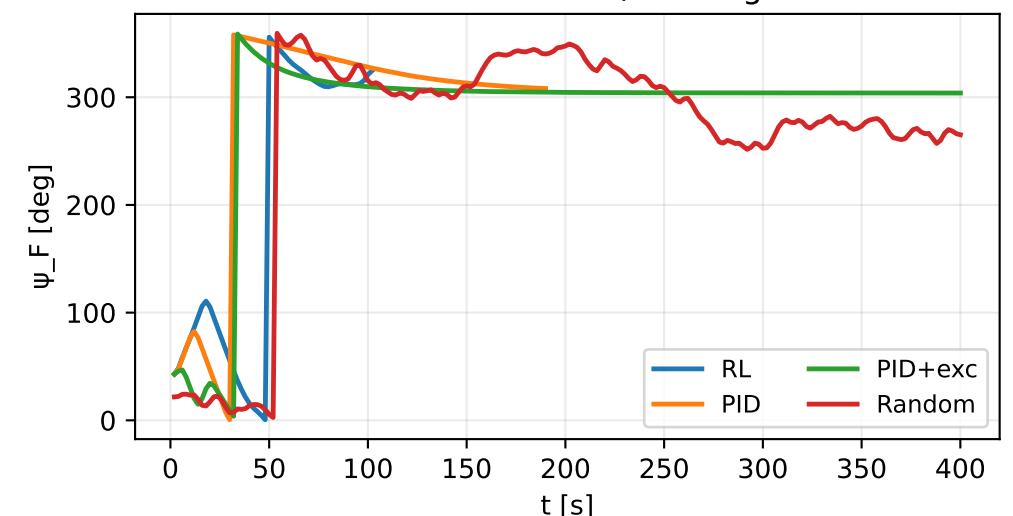
Information and excitation



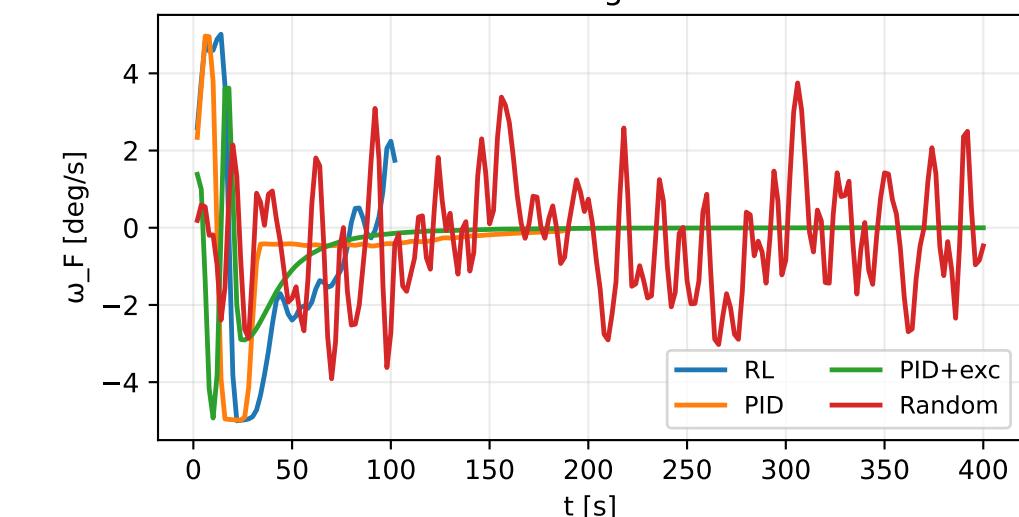
Follower speed



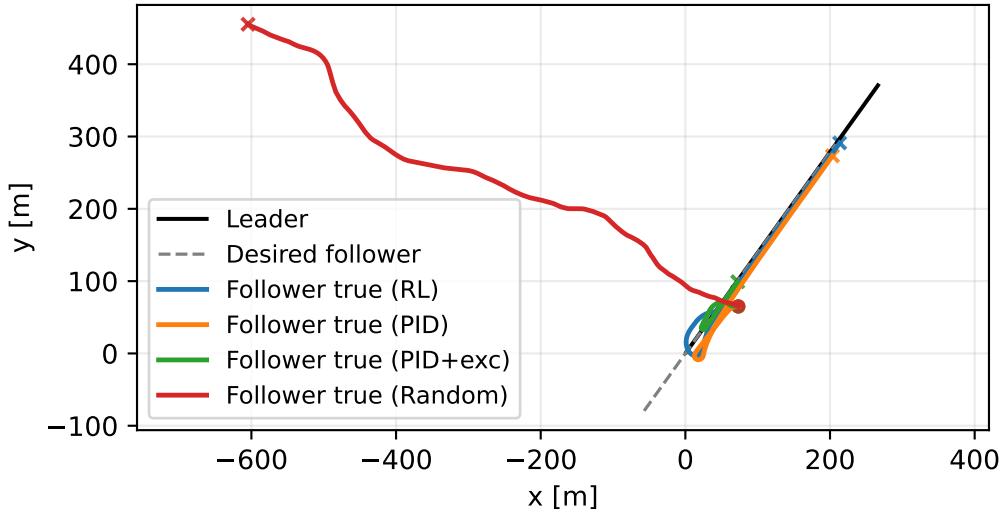
Follower course/heading



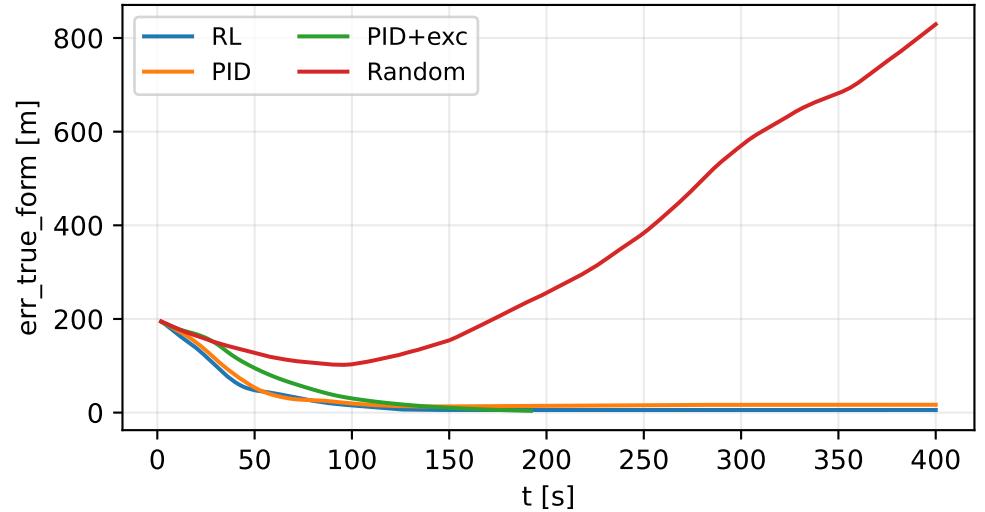
Follower angular rate



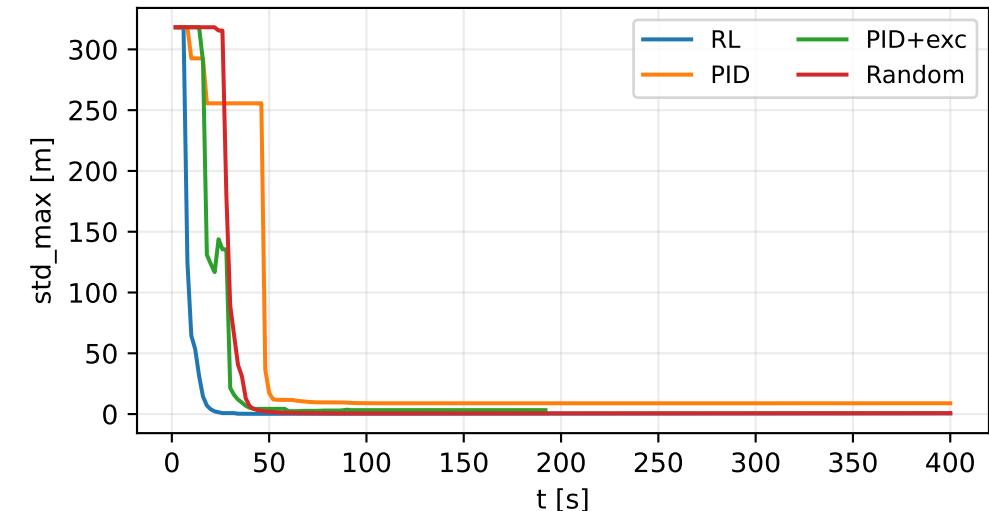
Trajectories (matched seed)



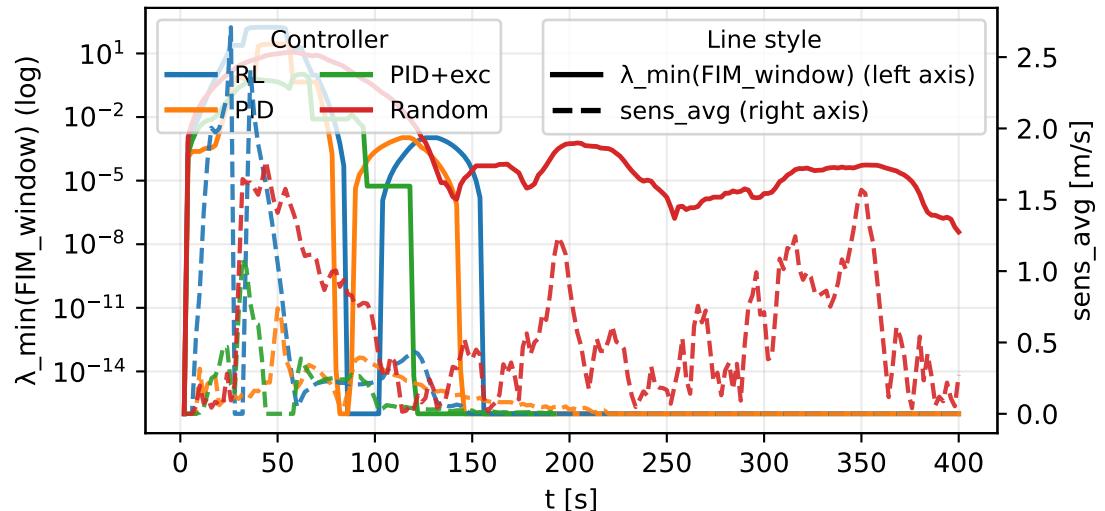
TRUE formation error



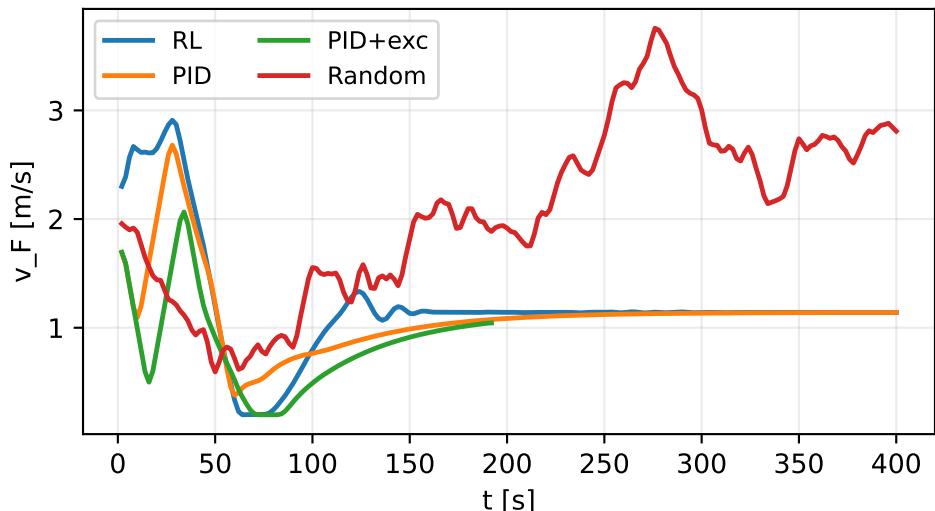
Estimator uncertainty (std_max)



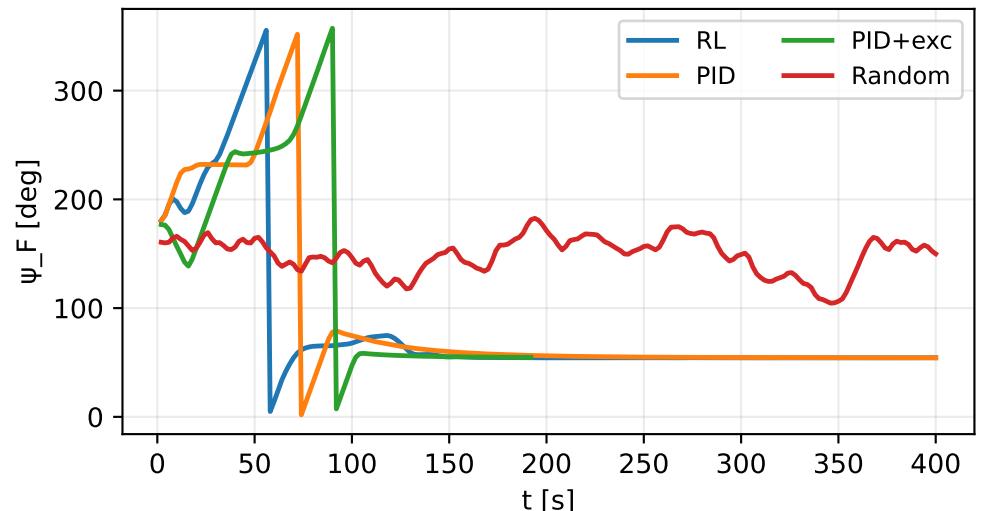
Information and excitation



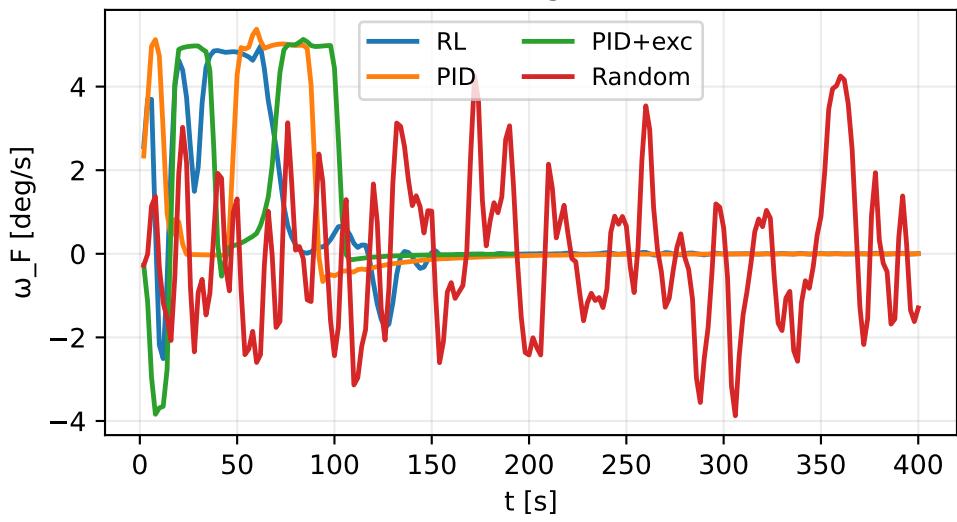
Follower speed



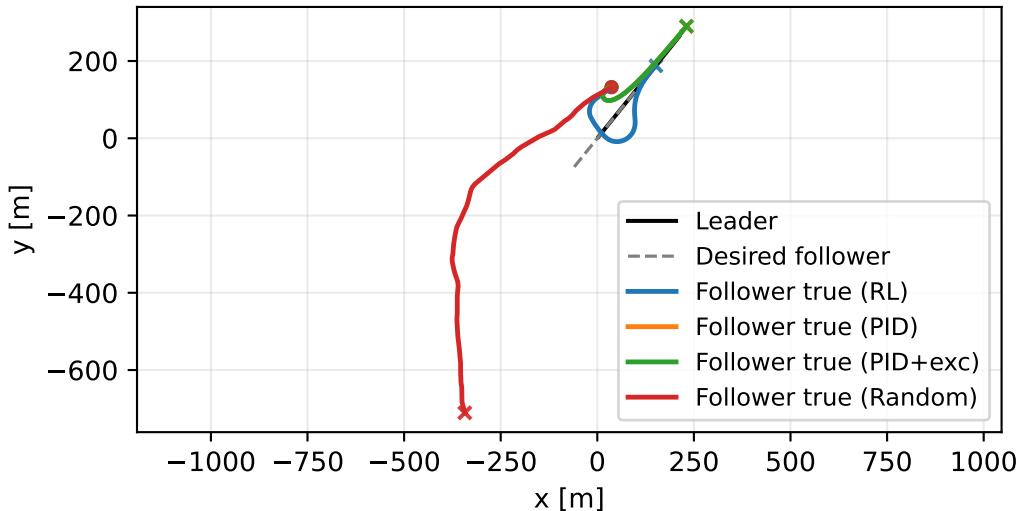
Follower course/heading



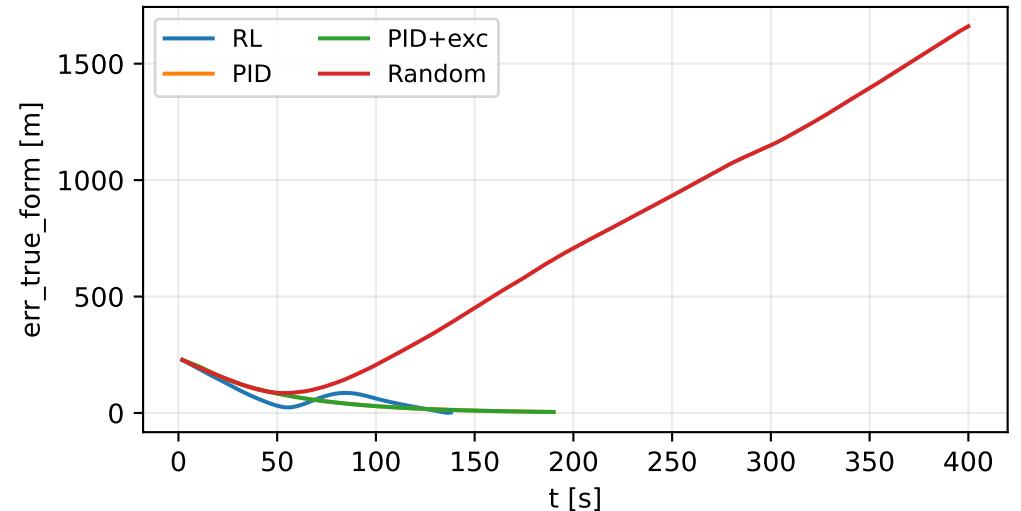
Follower angular rate



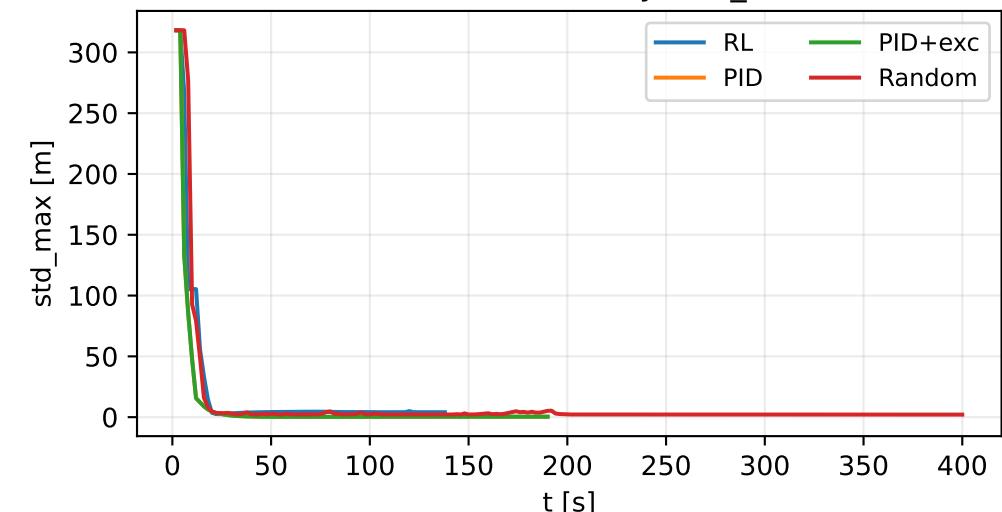
Trajectories (matched seed)



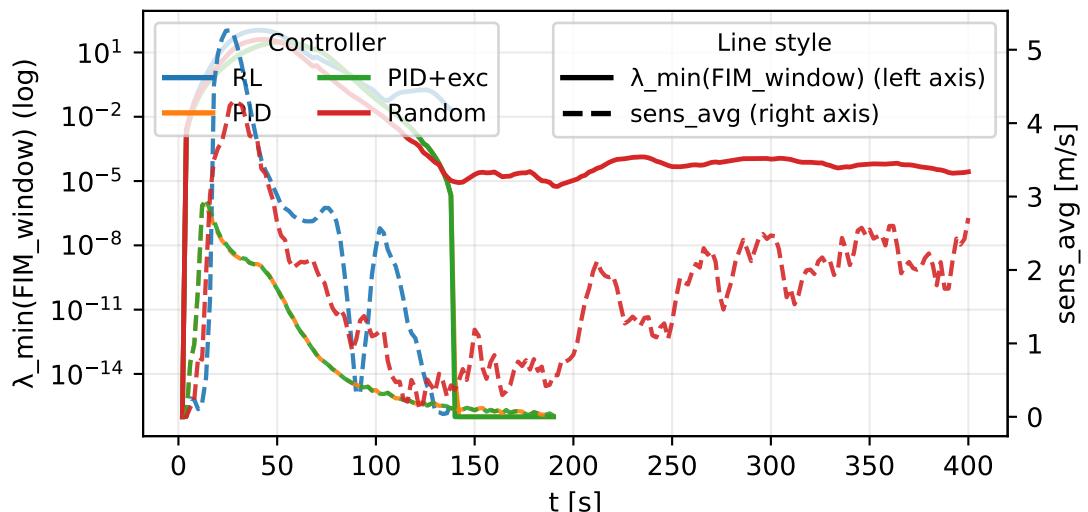
TRUE formation error



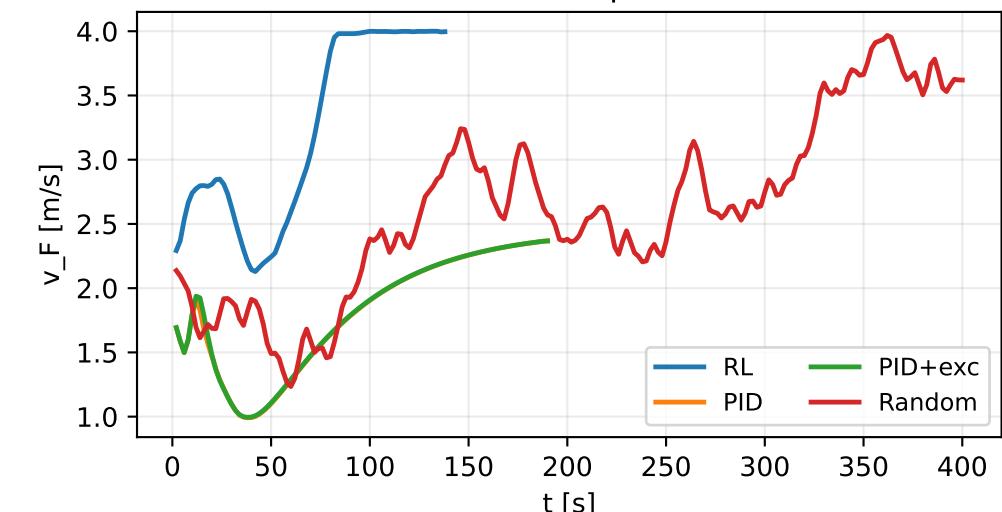
Estimator uncertainty (std_max)



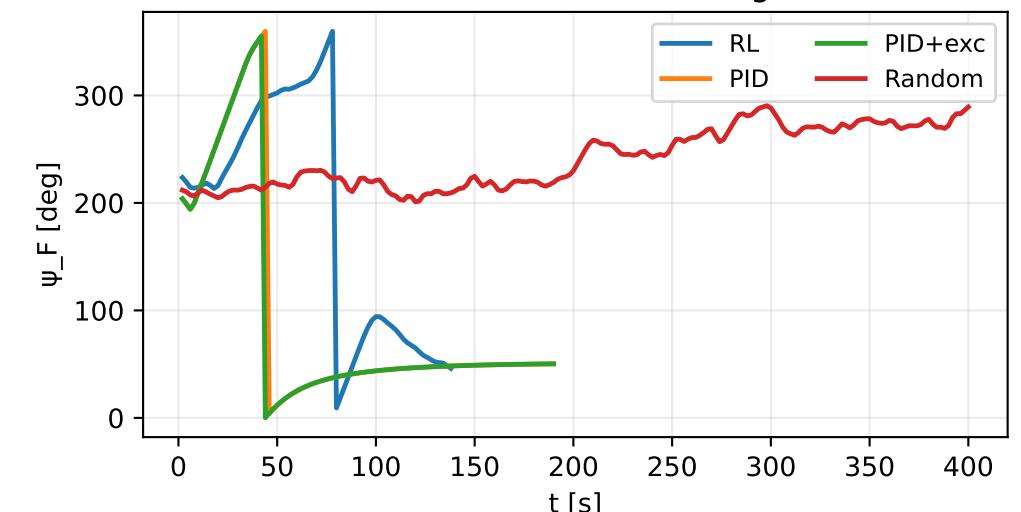
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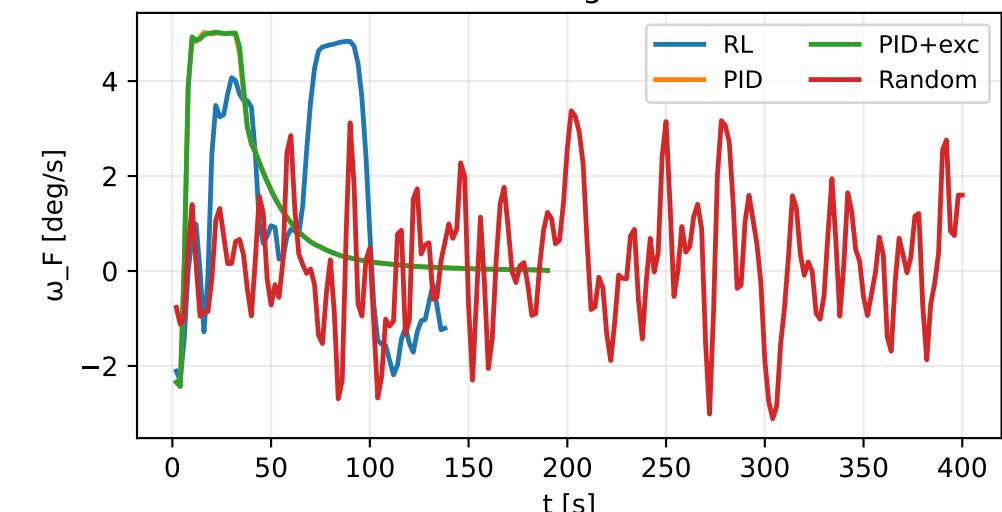
Follower speed



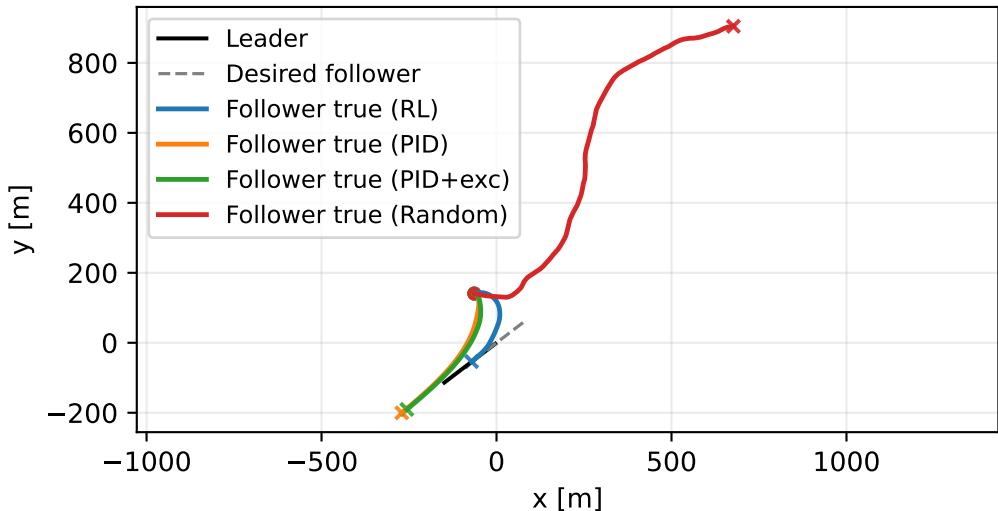
Follower course/heading



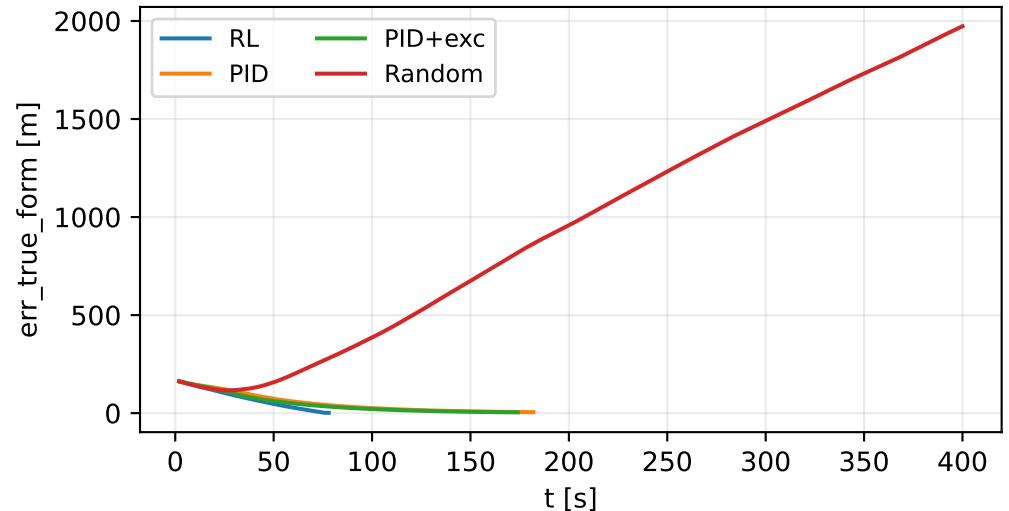
Follower angular rate



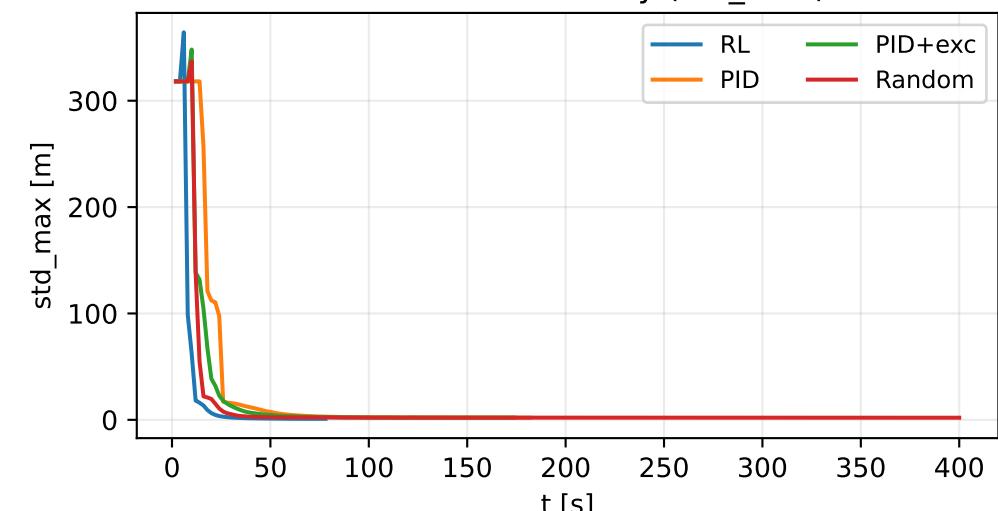
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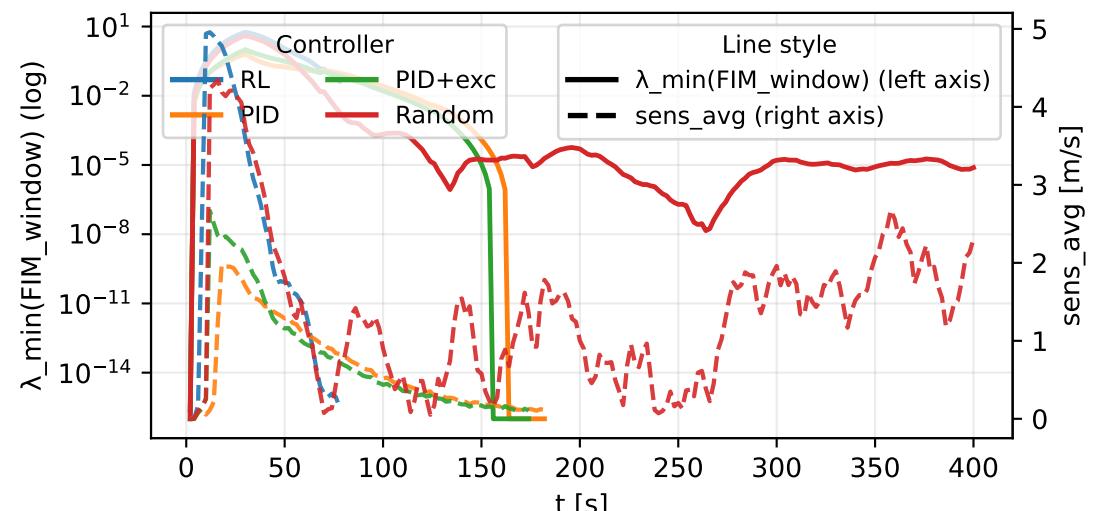
TRUE formation error



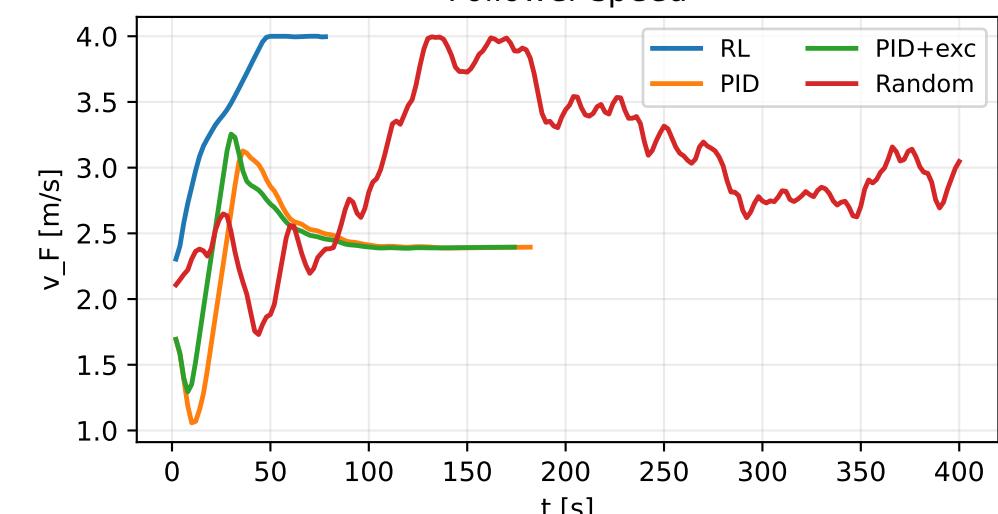
Estimator uncertainty (std_max)



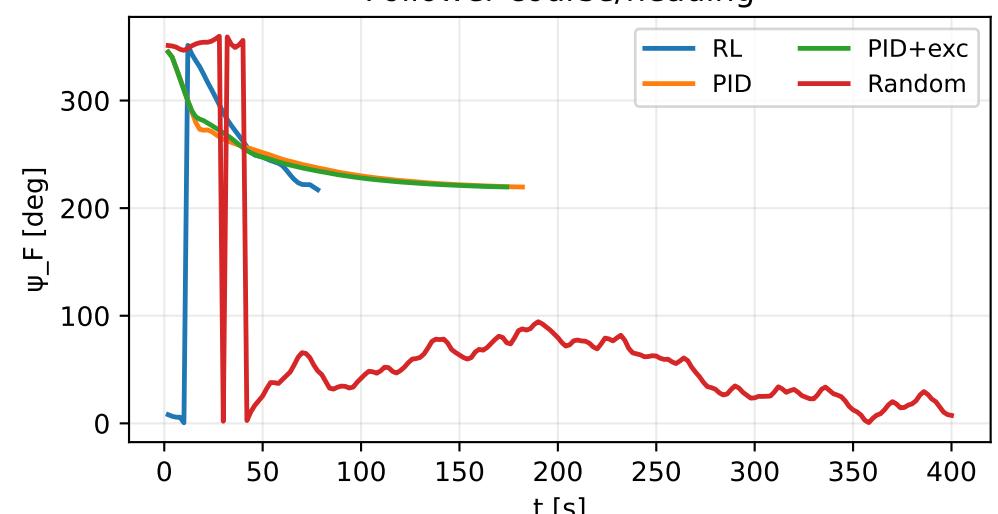
Information and excitation



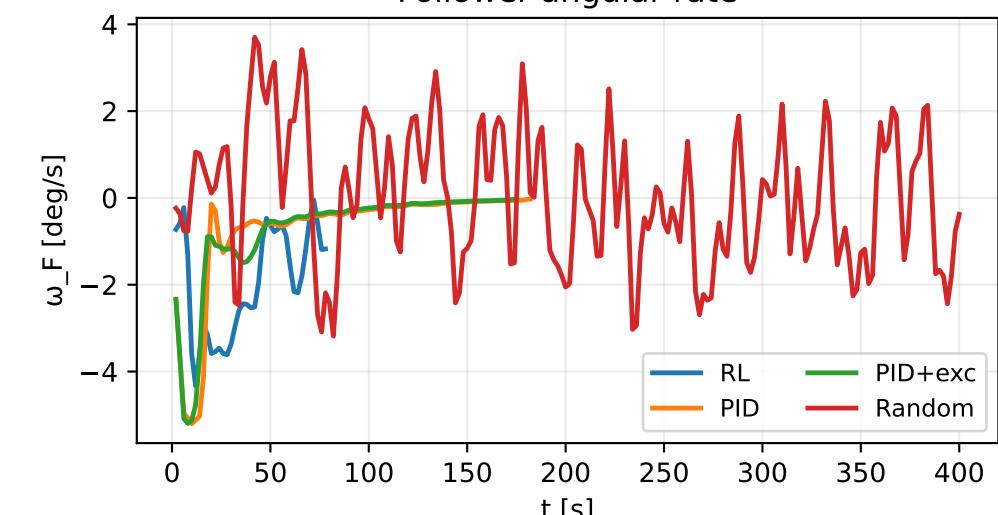
Follower speed



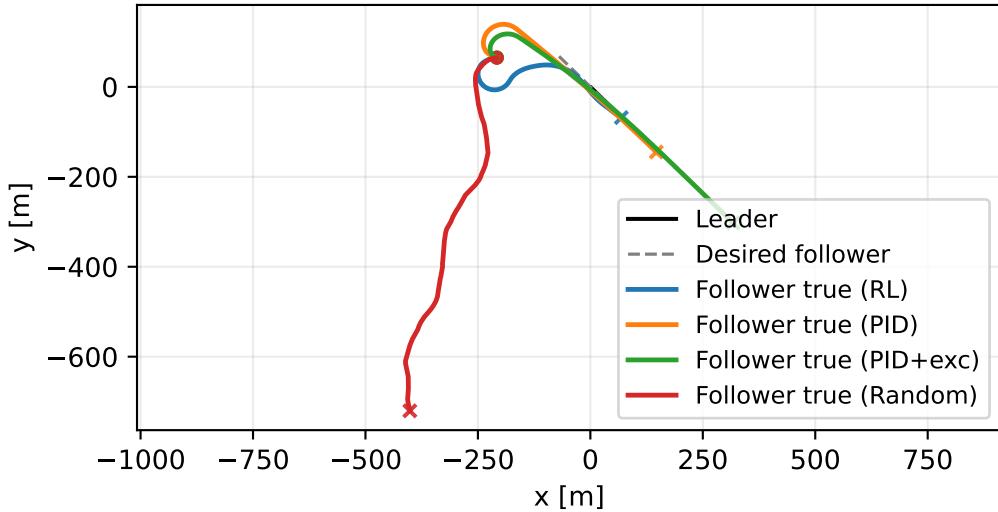
Follower course/heading



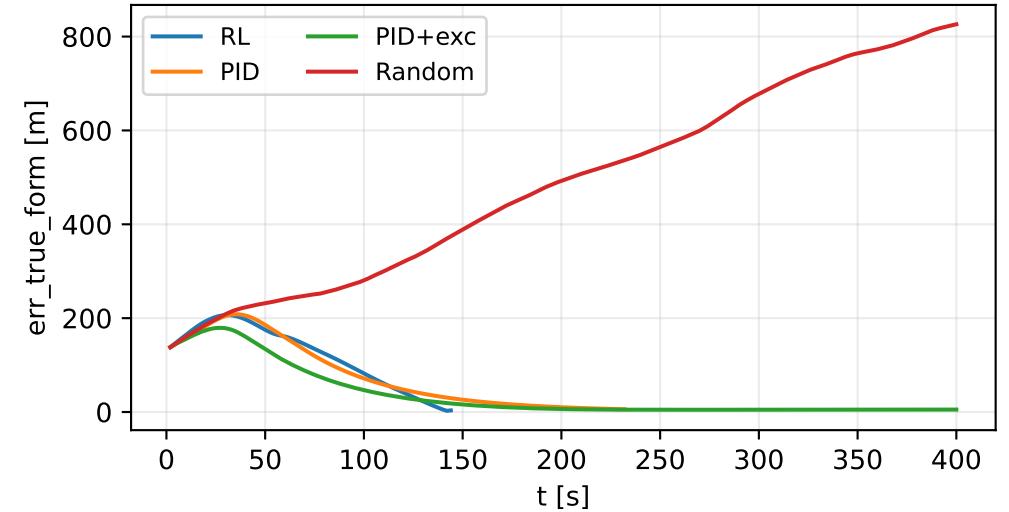
Follower angular rate



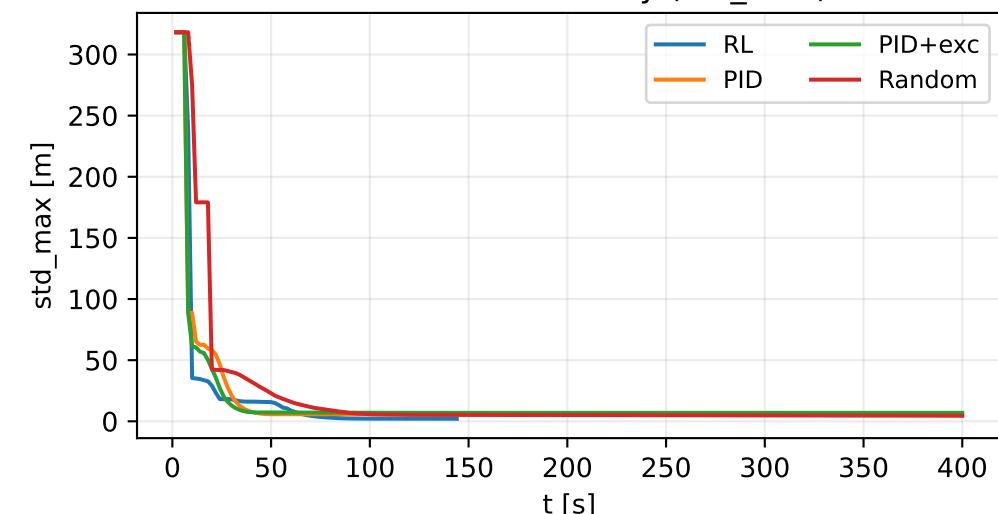
Trajectories (matched seed)



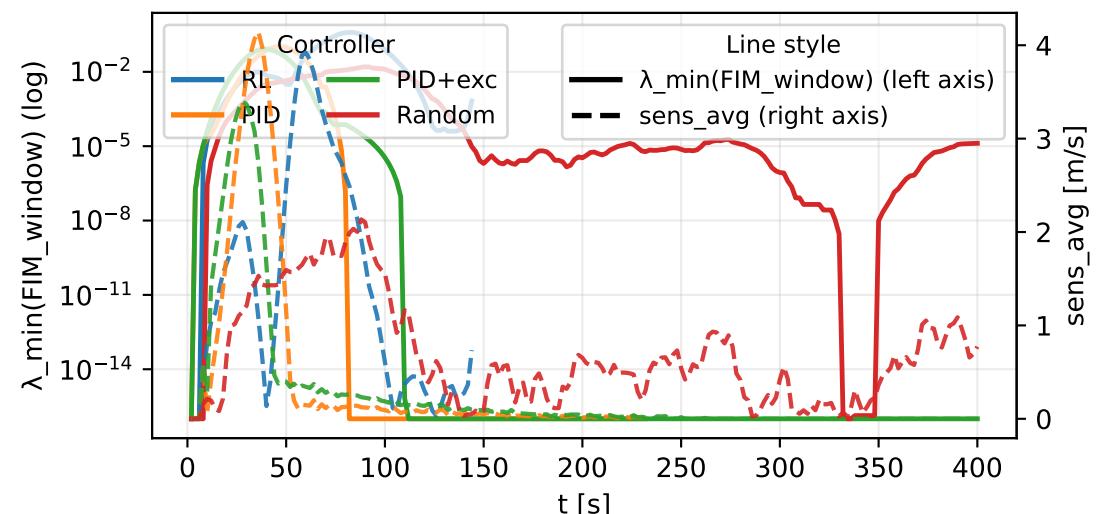
TRUE formation error



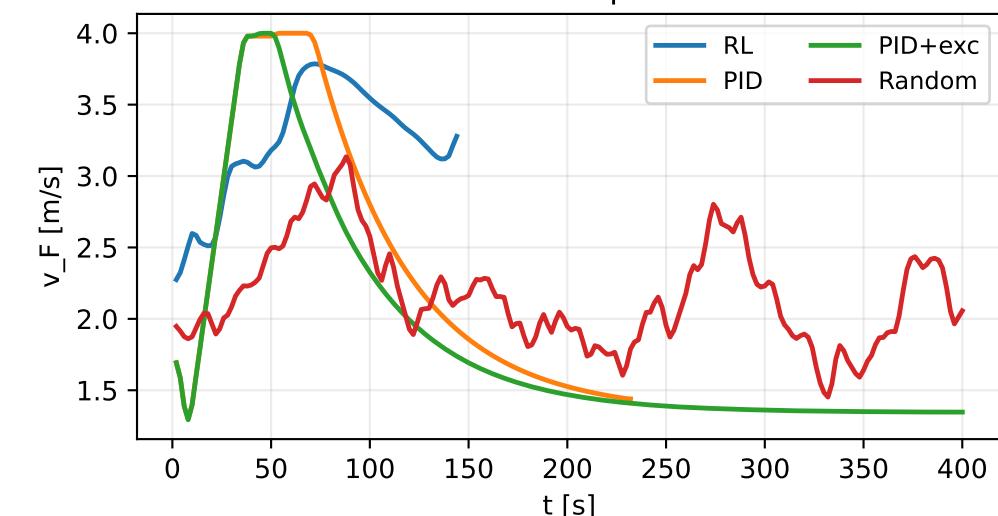
Estimator uncertainty (std_max)



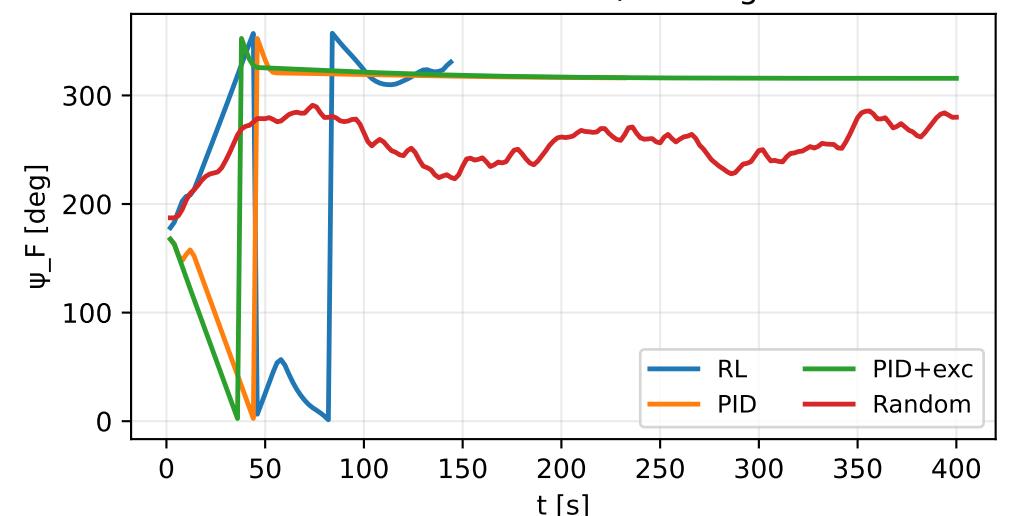
Information and excitation



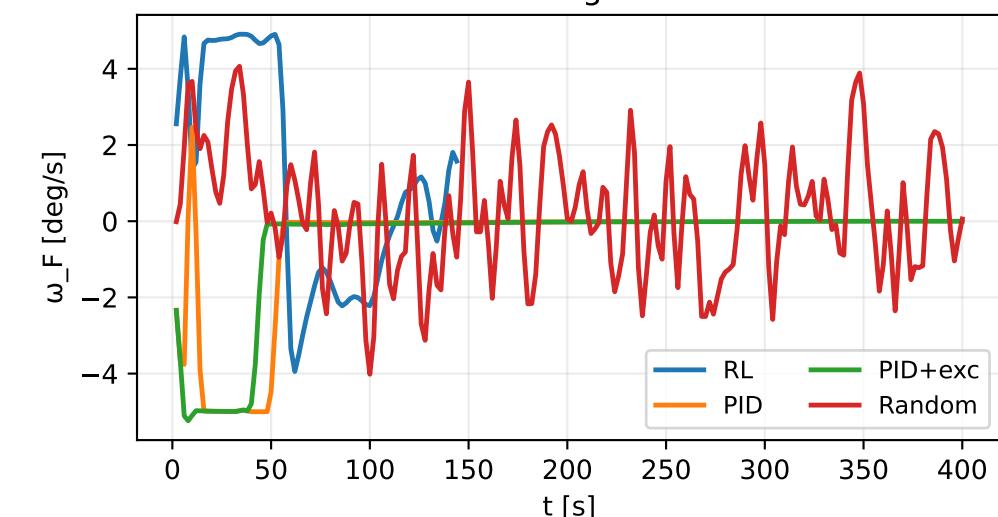
Follower speed



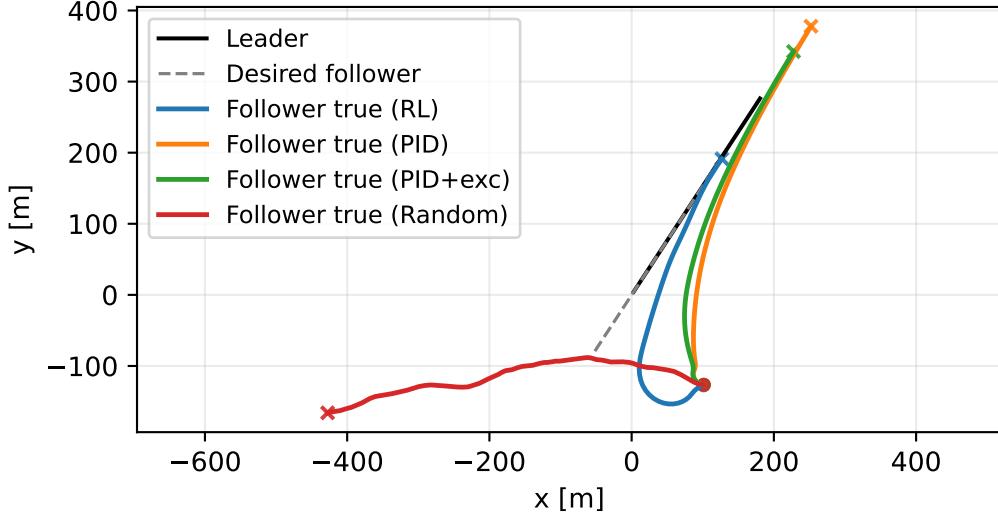
Follower course/heading



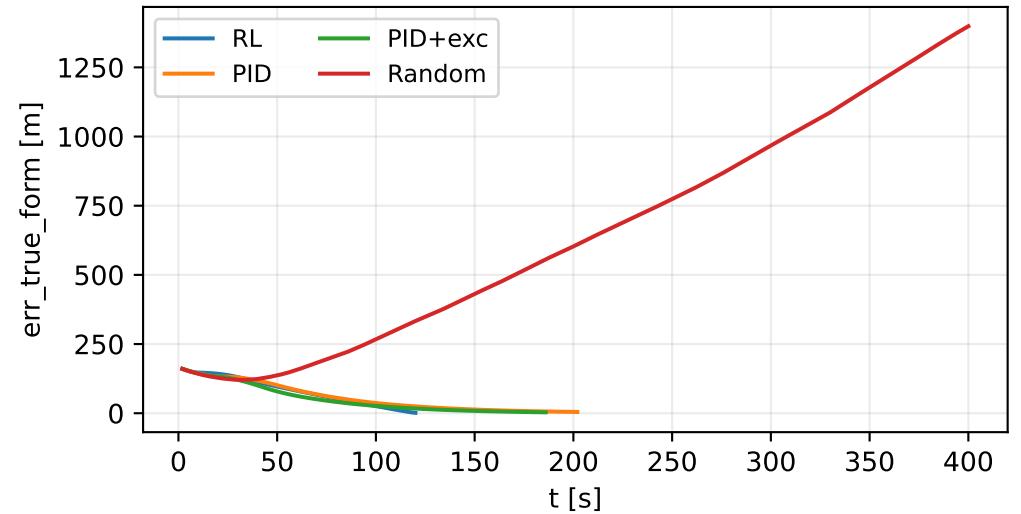
Follower angular rate



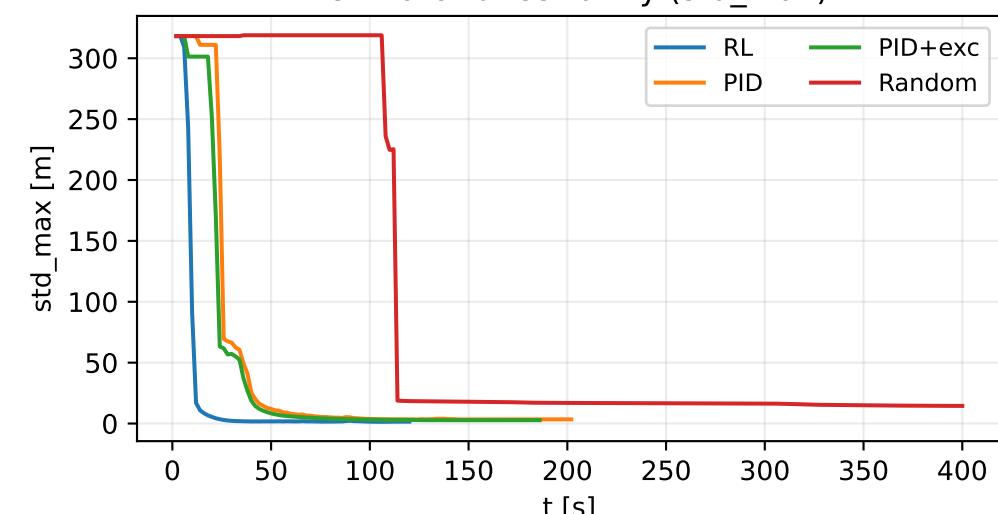
Trajectories (matched seed)



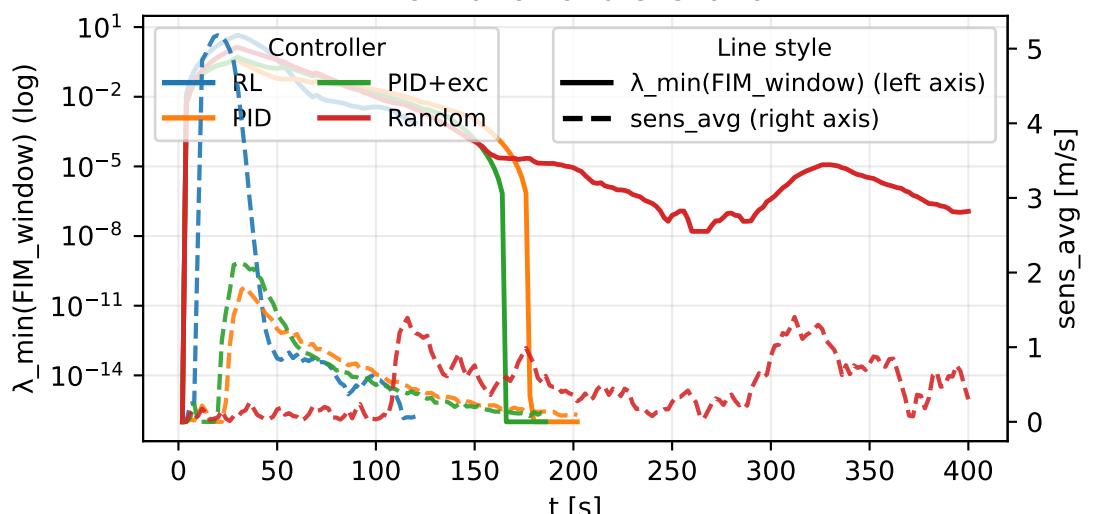
TRUE formation error



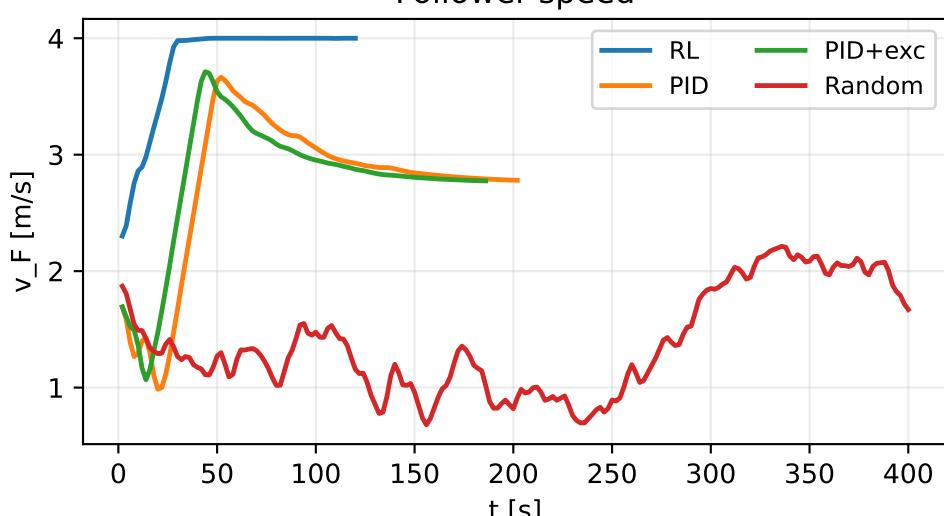
Estimator uncertainty (std_max)



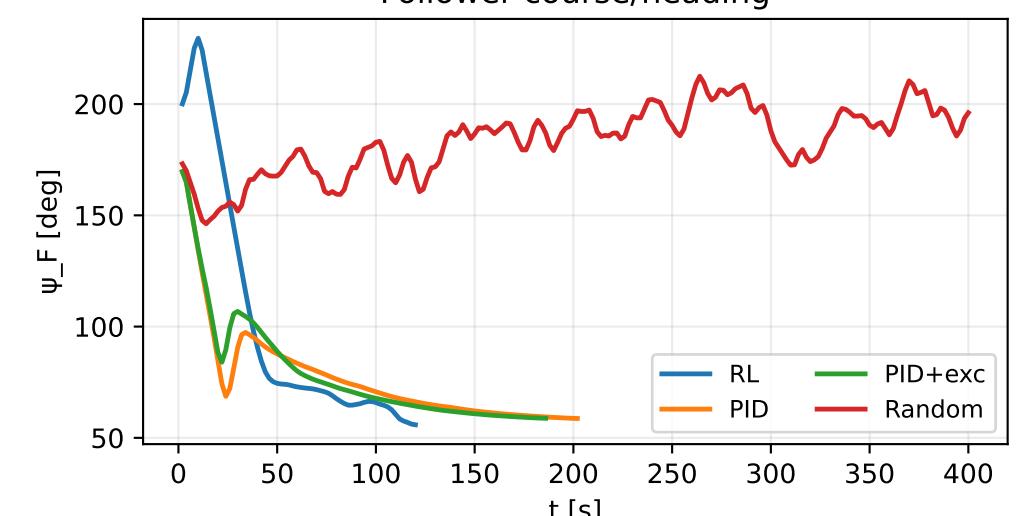
Information and excitation



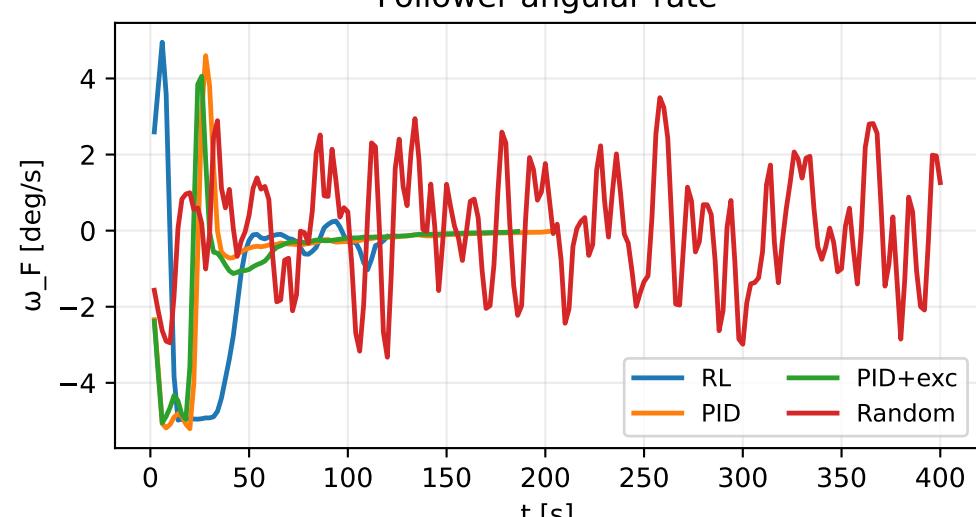
Follower speed



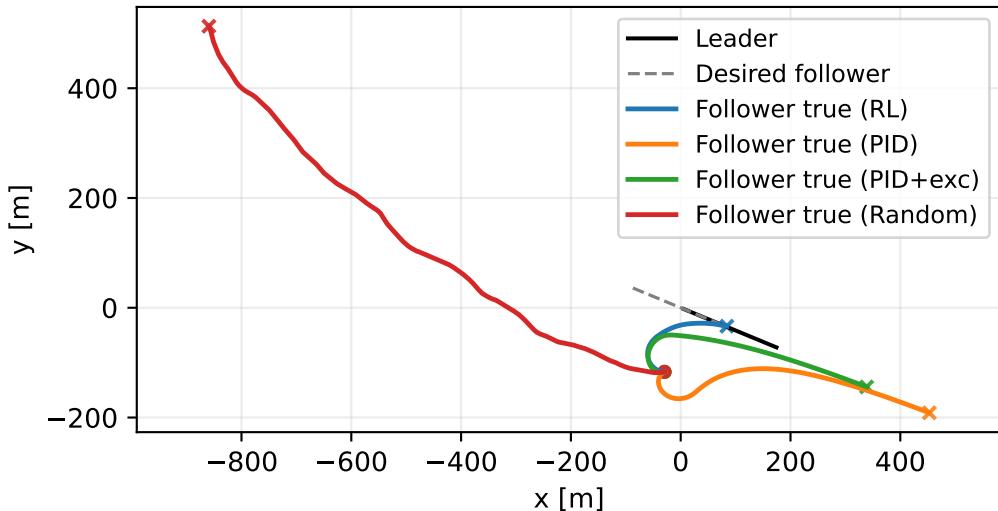
Follower course/heading



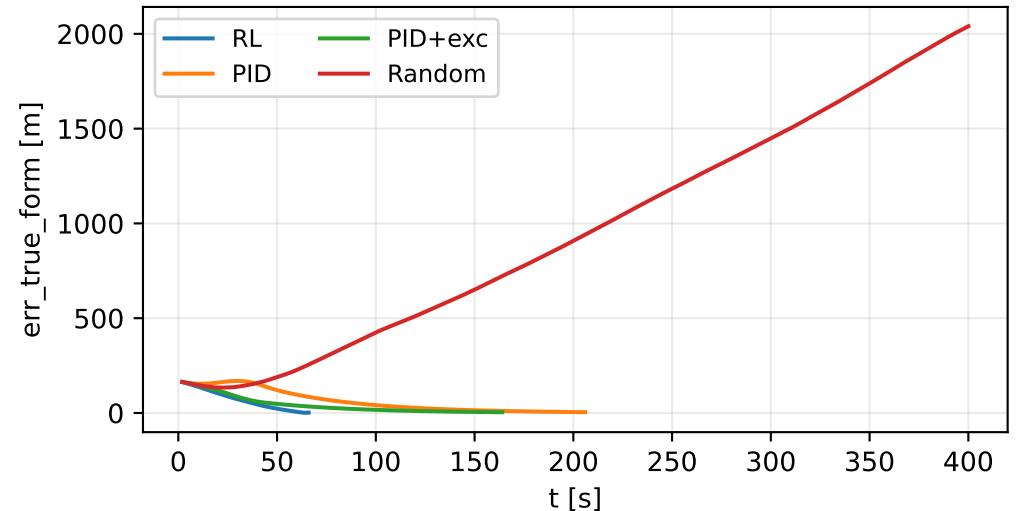
Follower angular rate



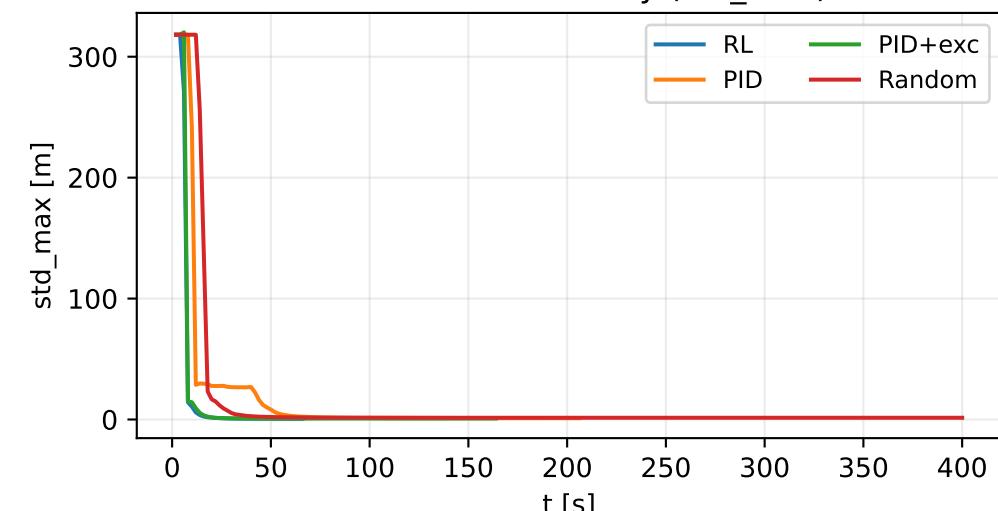
Trajectories (matched seed)



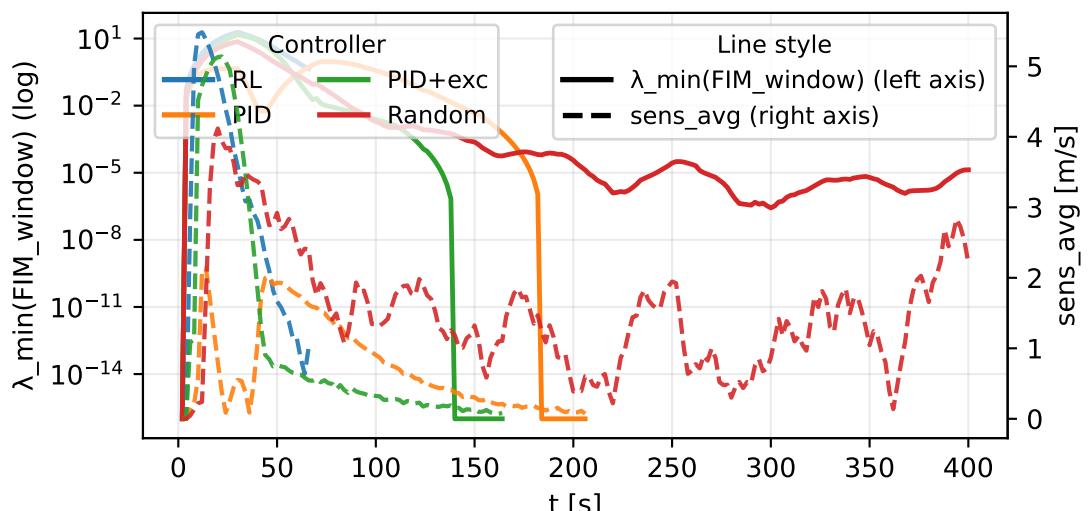
TRUE formation error



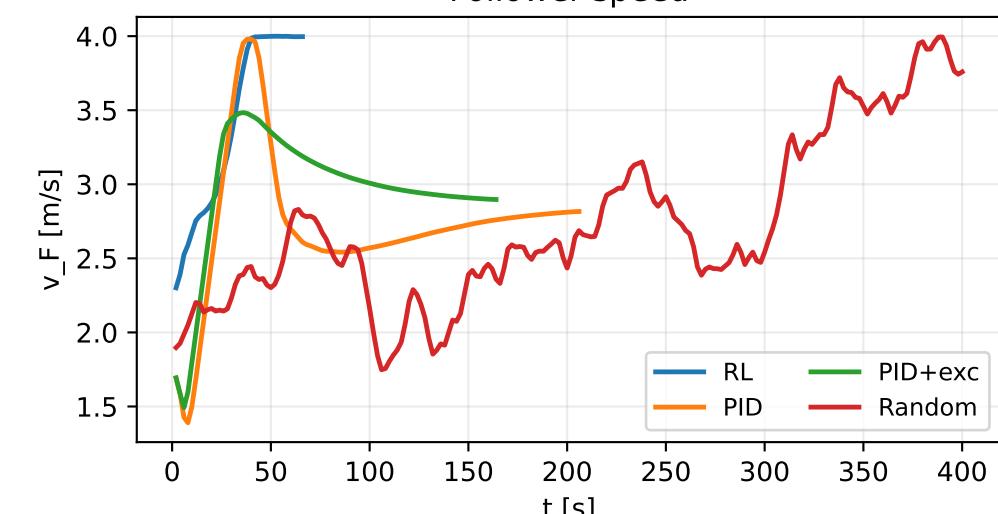
Estimator uncertainty (std_max)



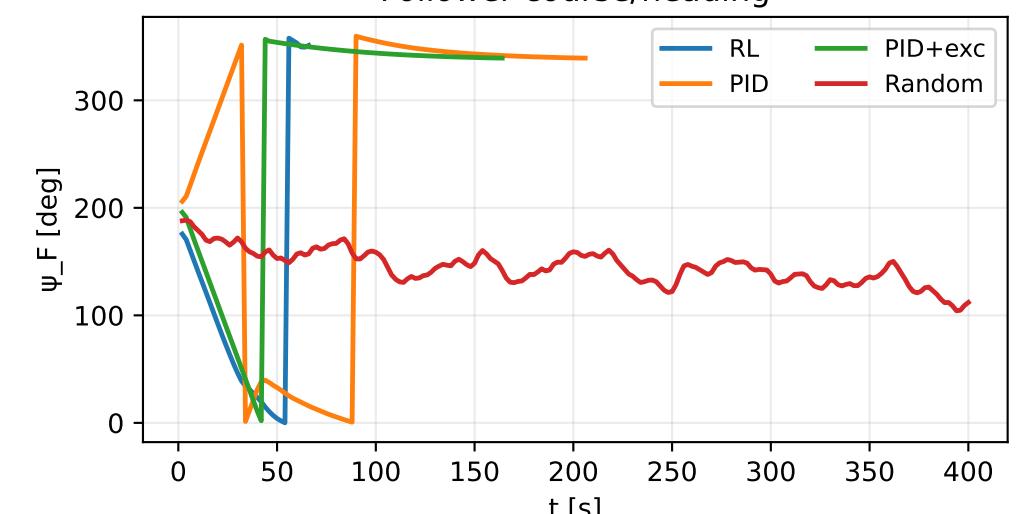
Information and excitation



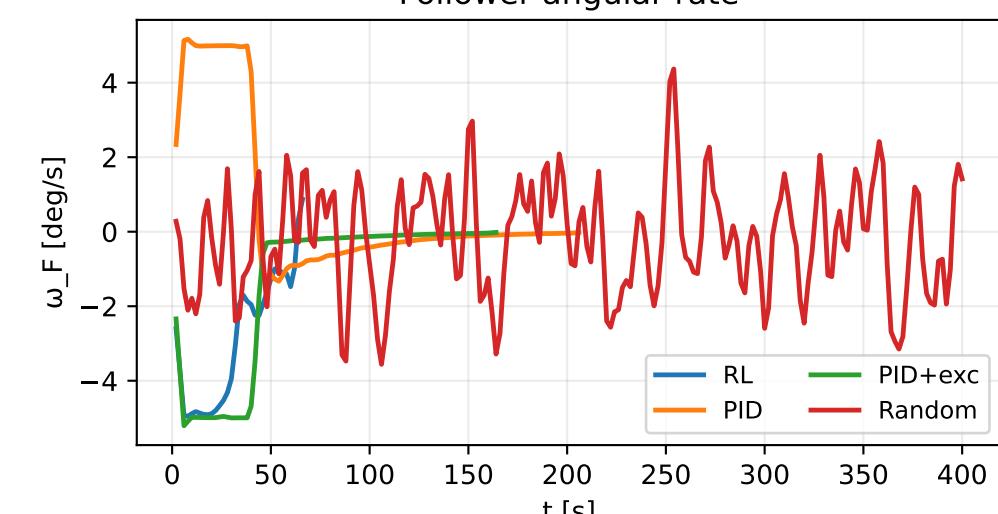
Follower speed



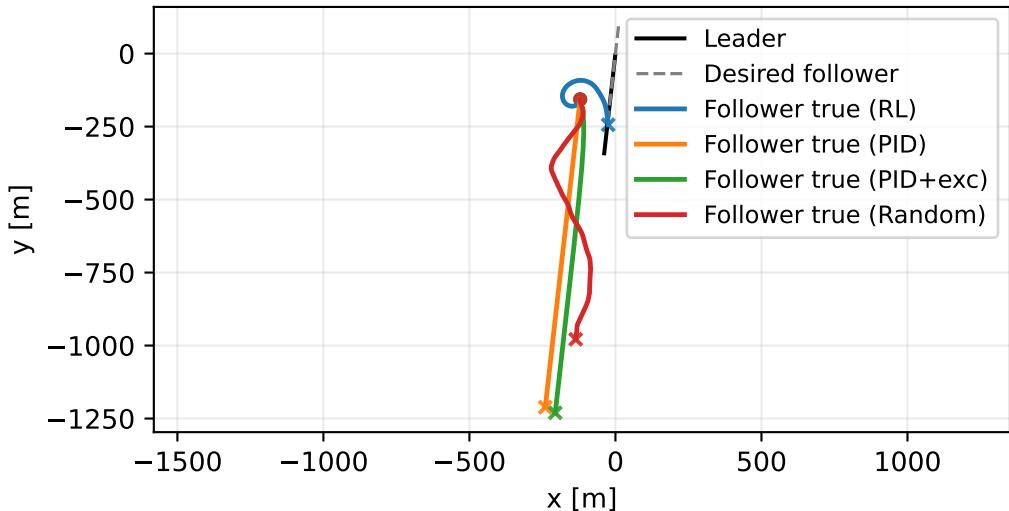
Follower course/heading



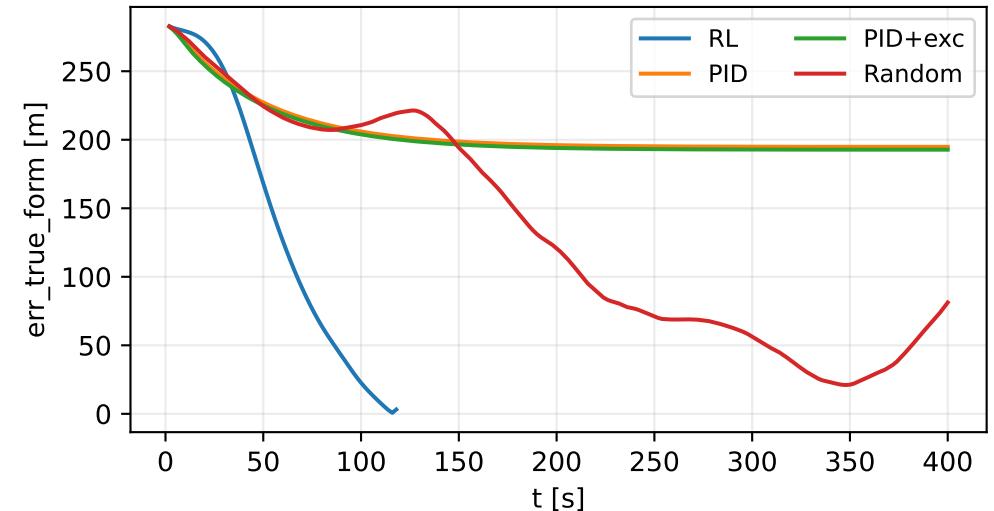
Follower angular rate



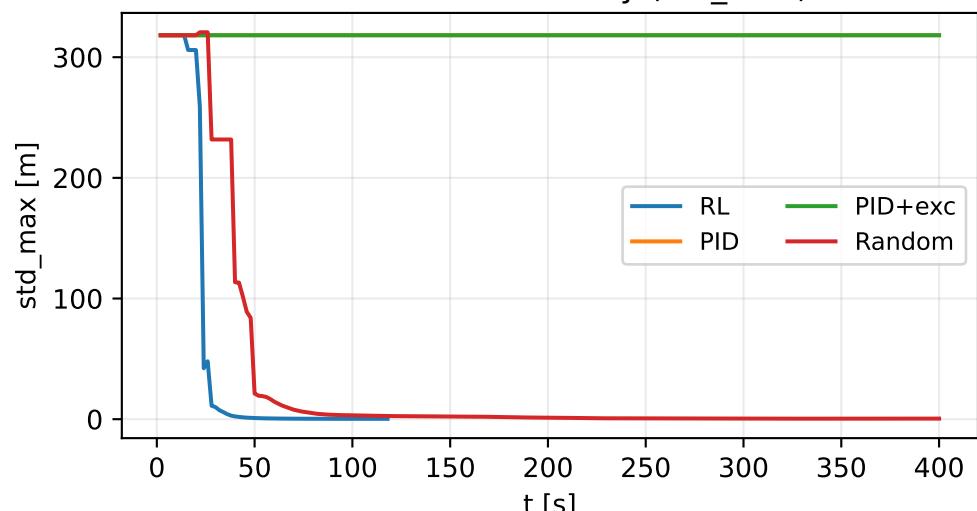
Trajectories (matched seed)



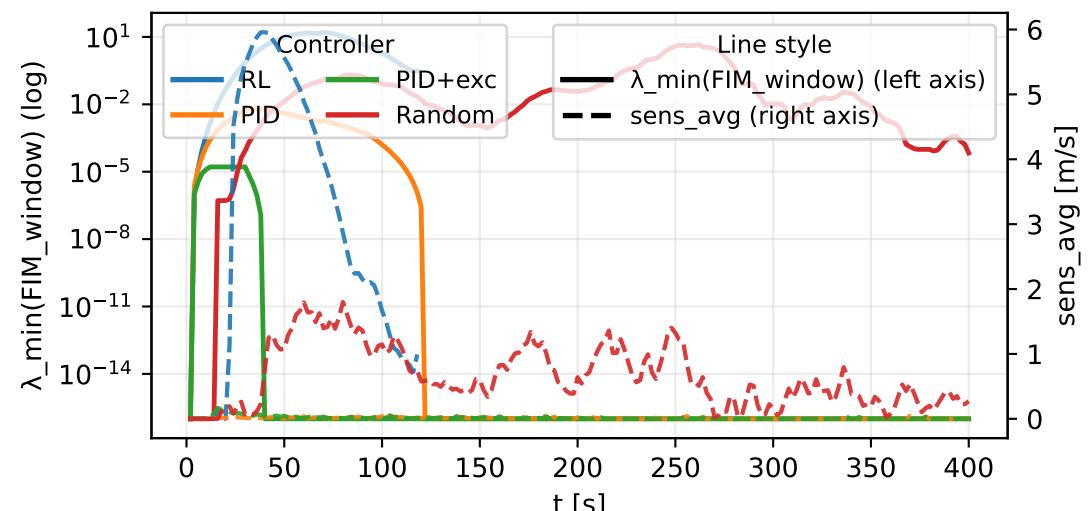
TRUE formation error



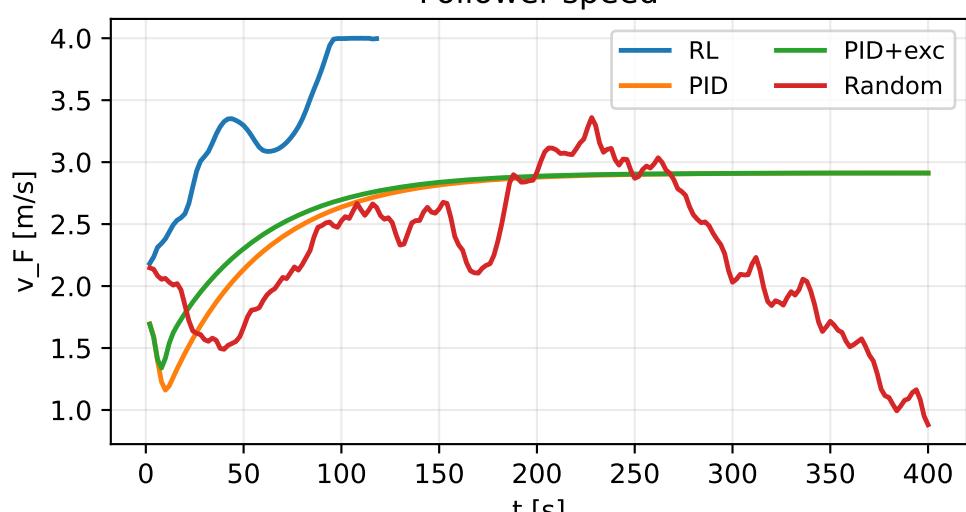
Estimator uncertainty (std_max)



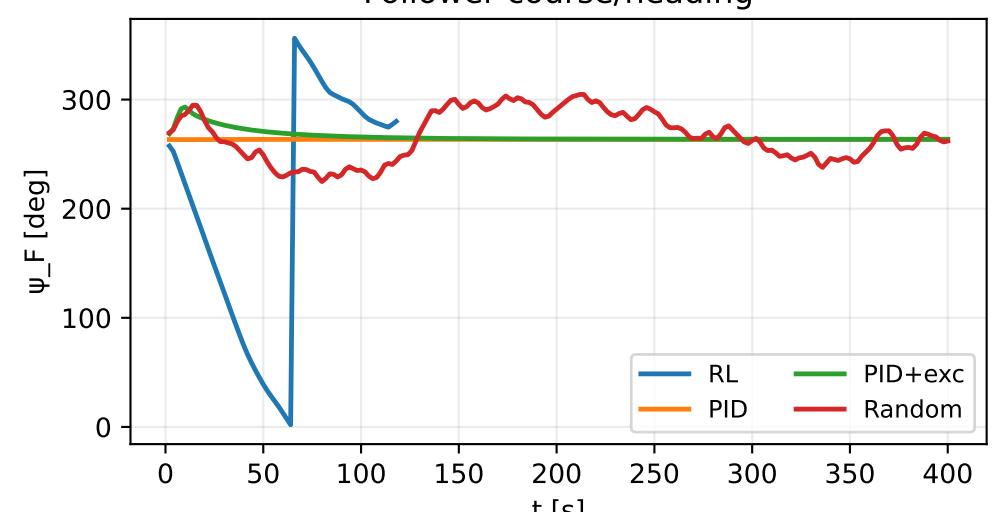
Information and excitation



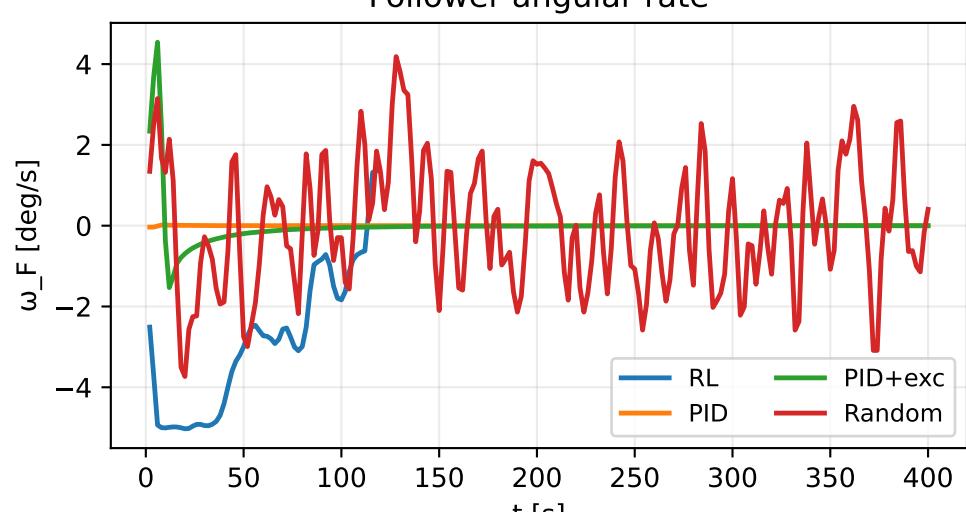
Follower speed



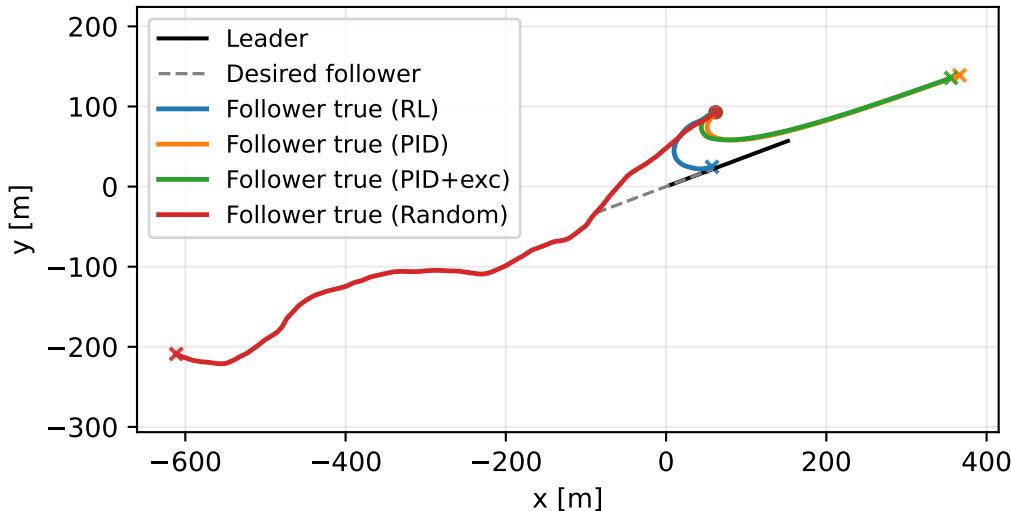
Follower course/heading



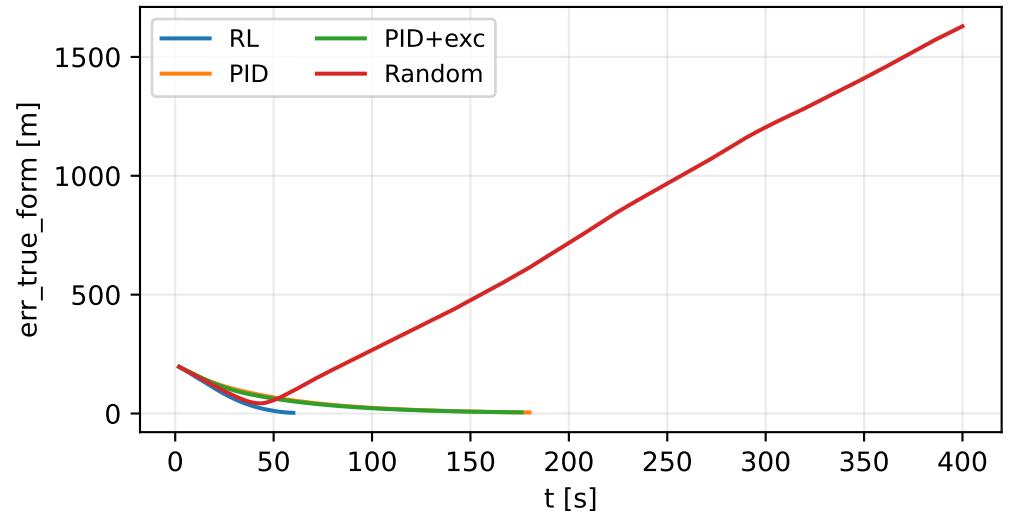
Follower angular rate



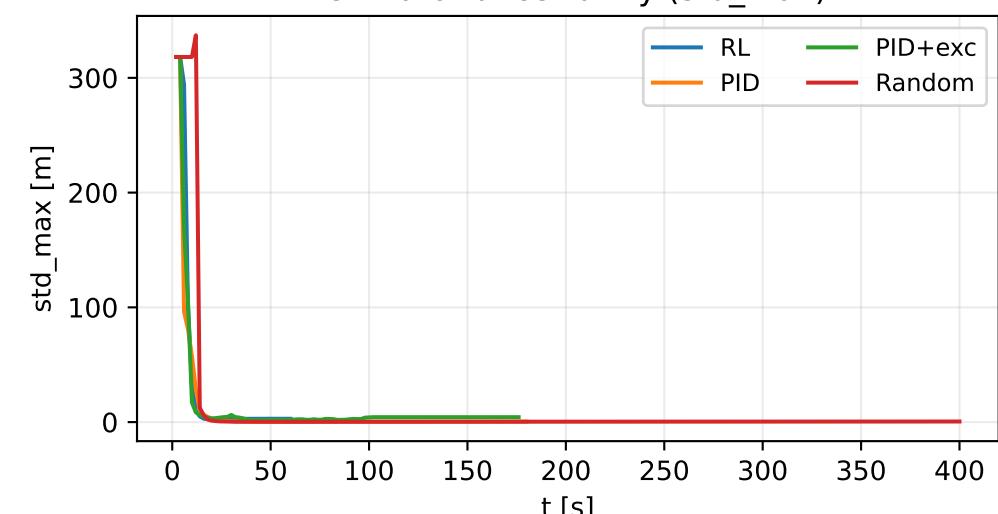
Trajectories (matched seed)



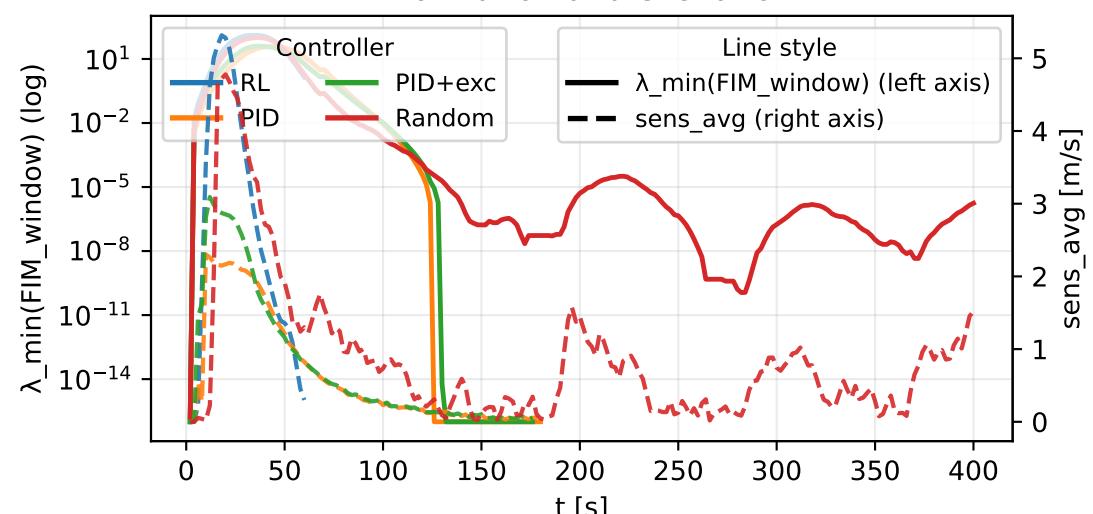
TRUE formation error



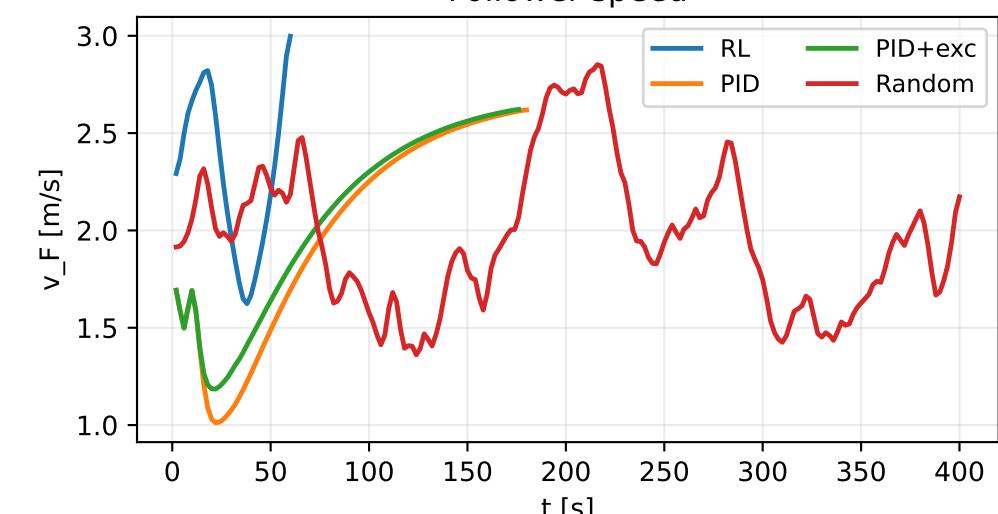
Estimator uncertainty (std_max)



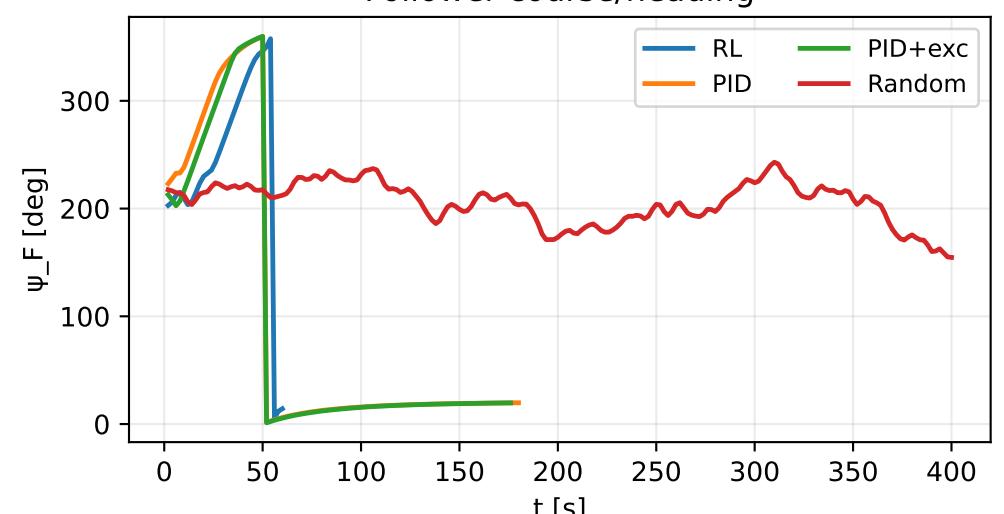
Information and excitation



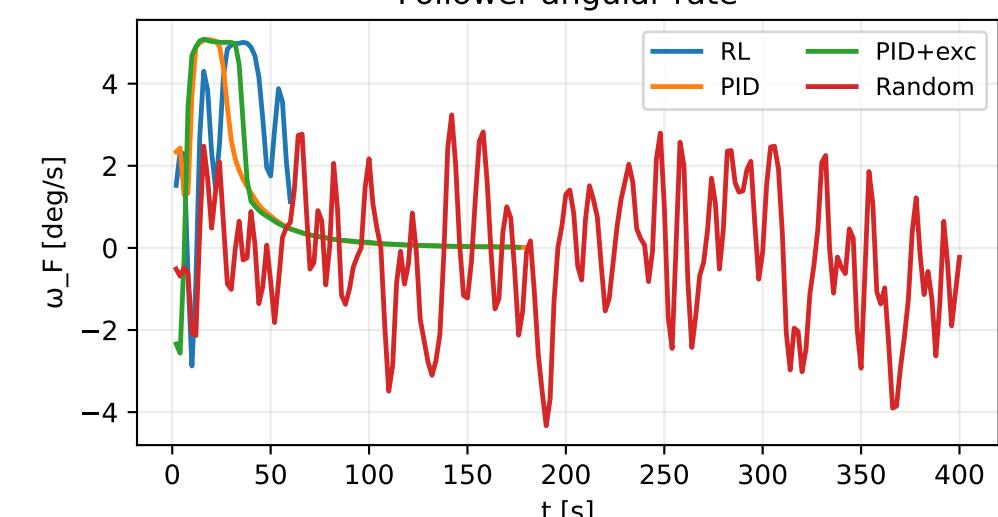
Follower speed



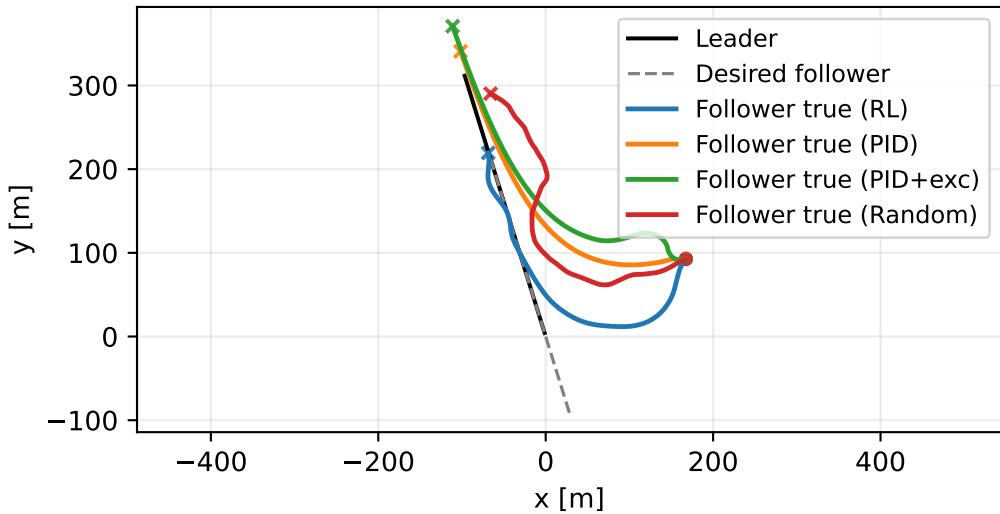
Follower course/heading



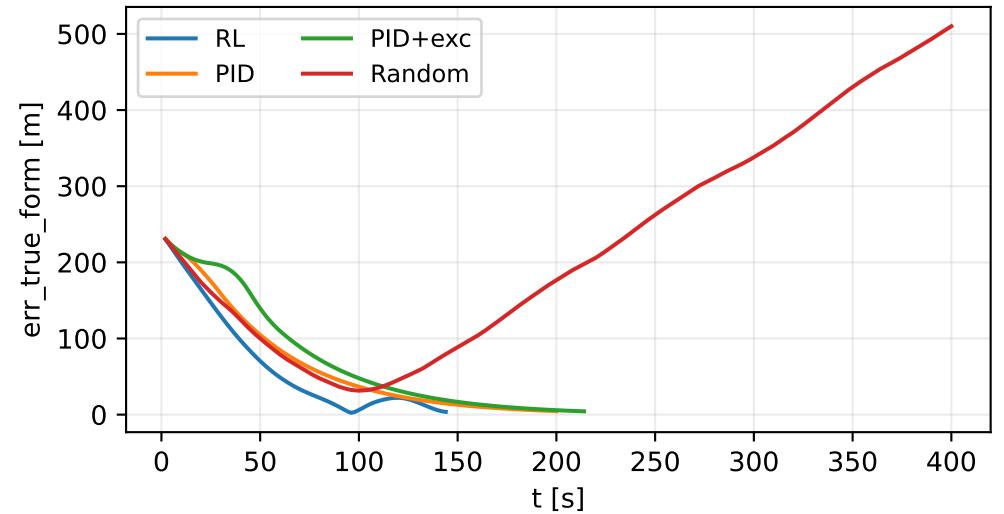
Follower angular rate



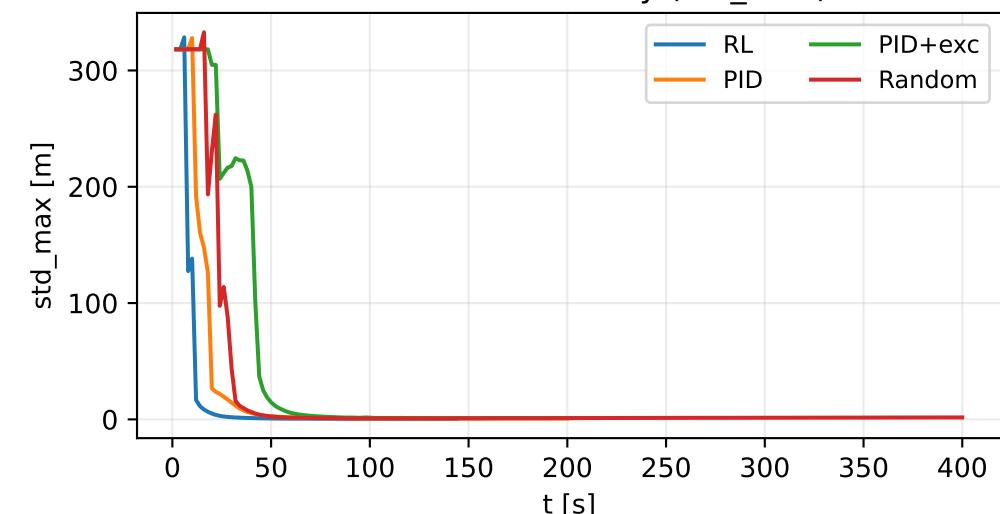
Trajectories (matched seed)



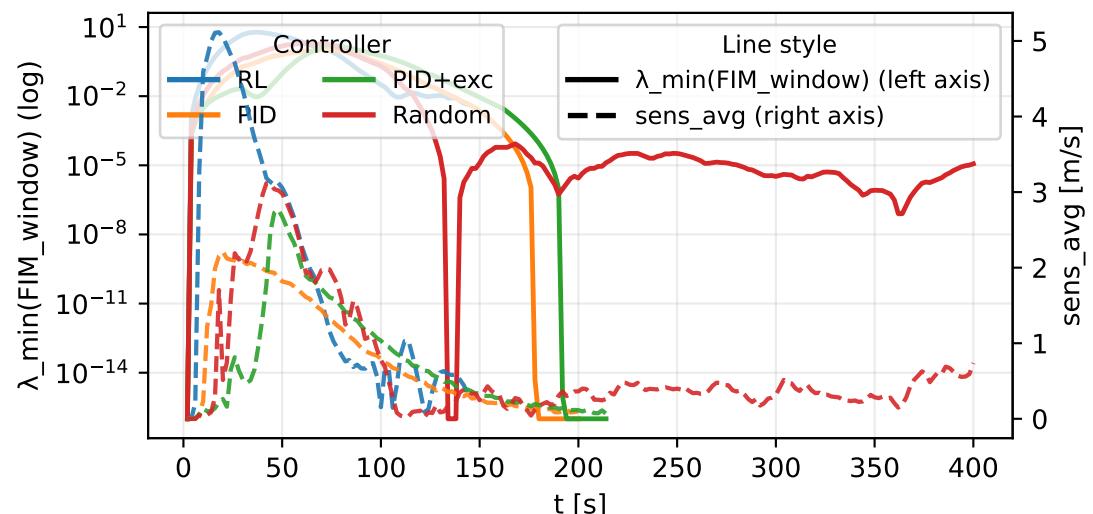
TRUE formation error



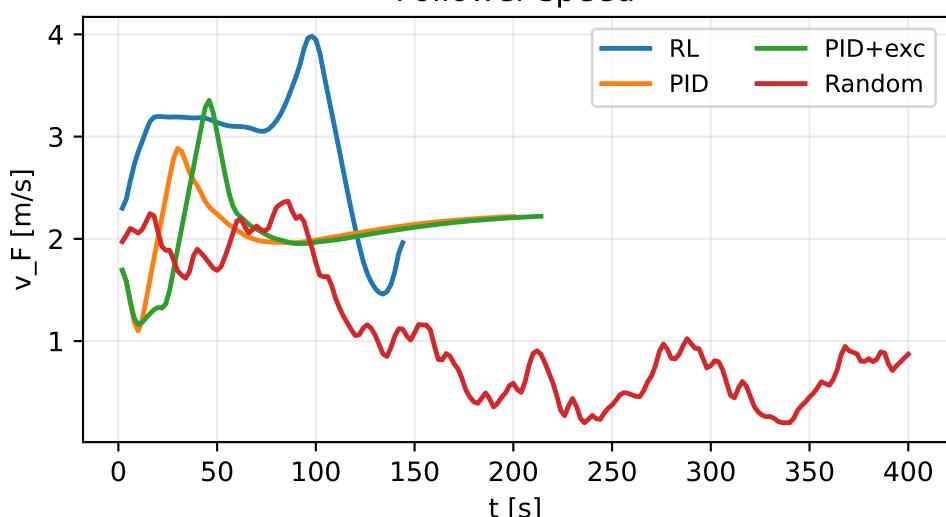
Estimator uncertainty (std_max)



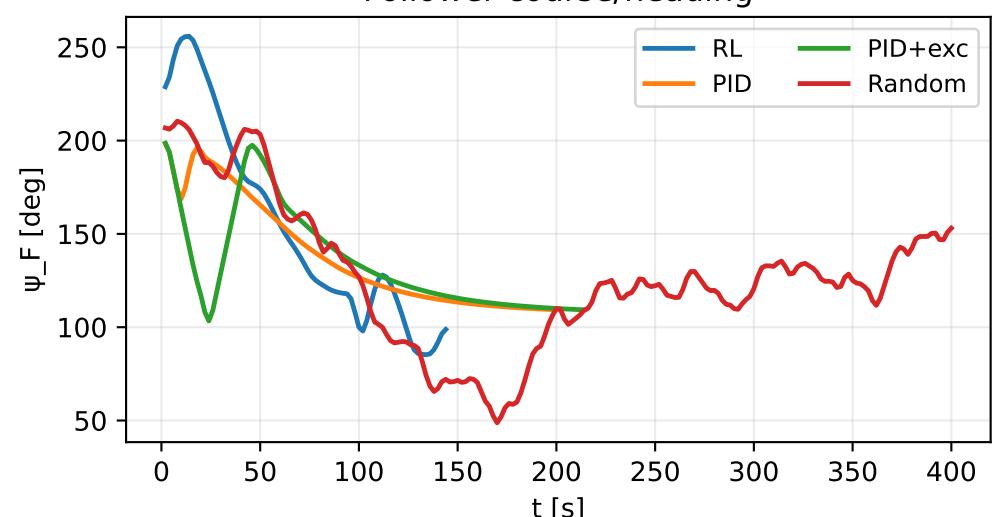
Information and excitation



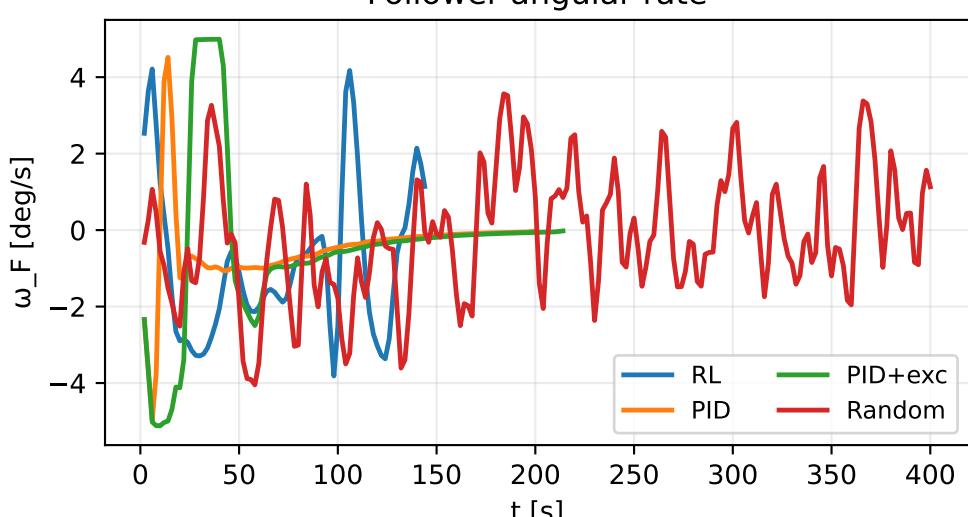
Follower speed



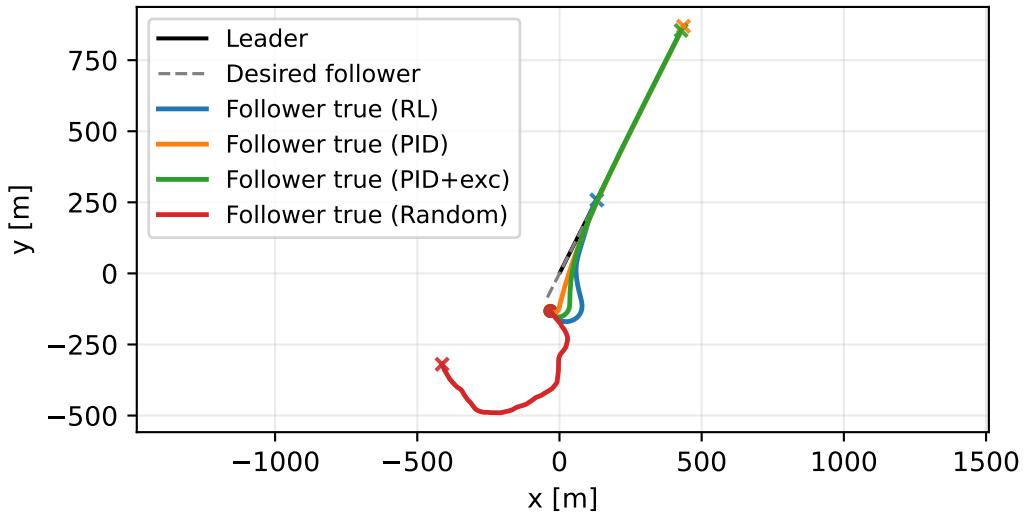
Follower course/heading



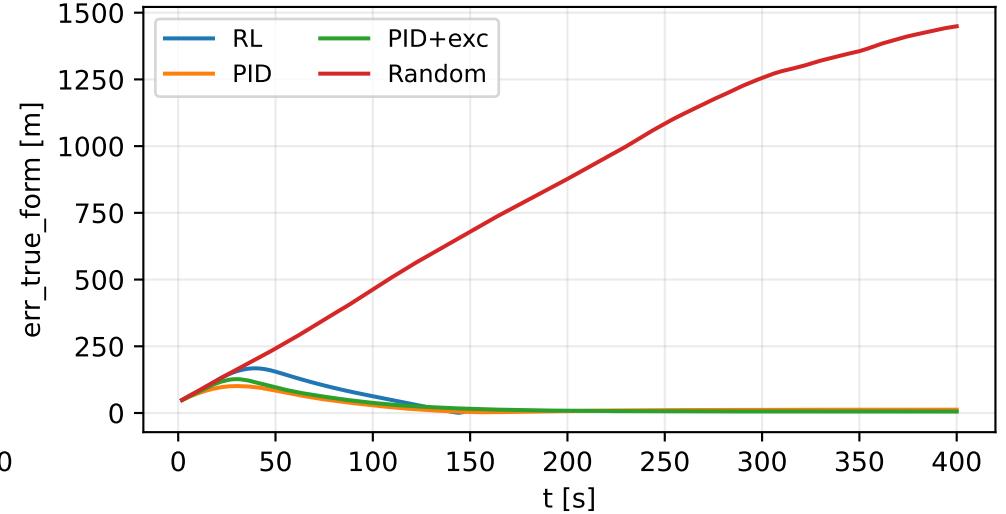
Follower angular rate



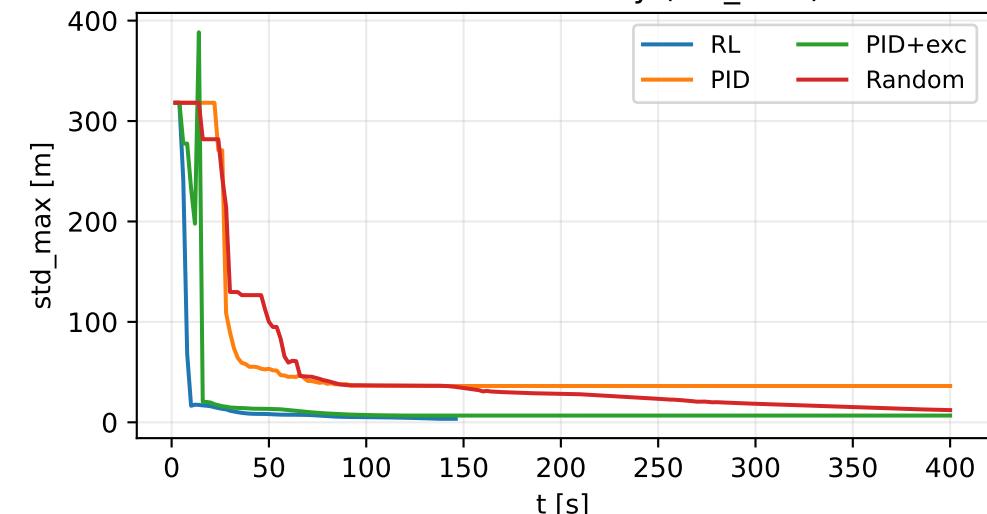
Trajectories (matched seed)



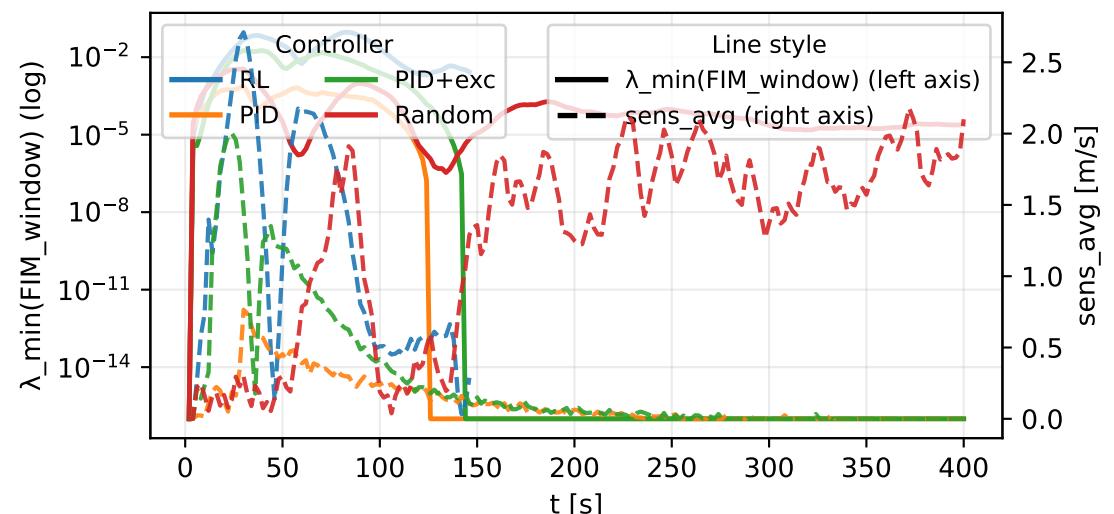
TRUE formation error



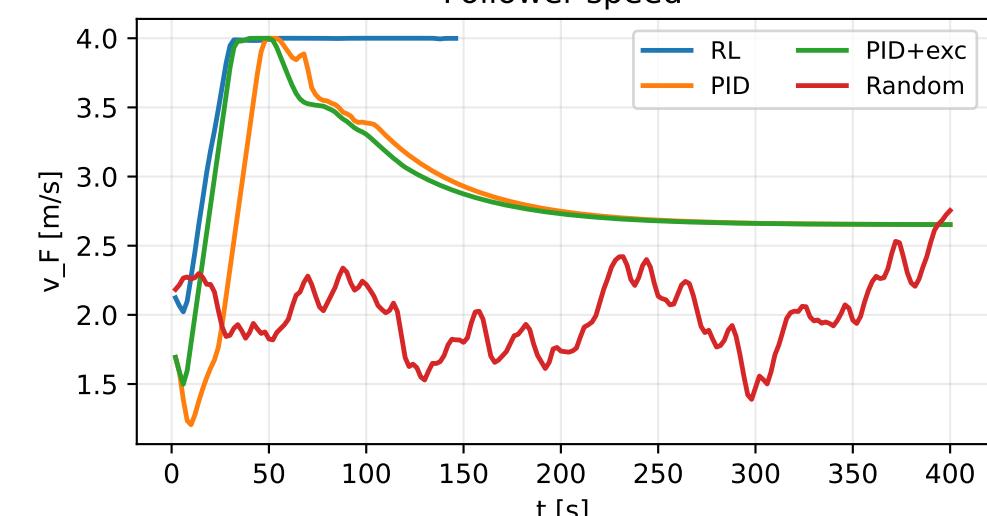
Estimator uncertainty (std_max)



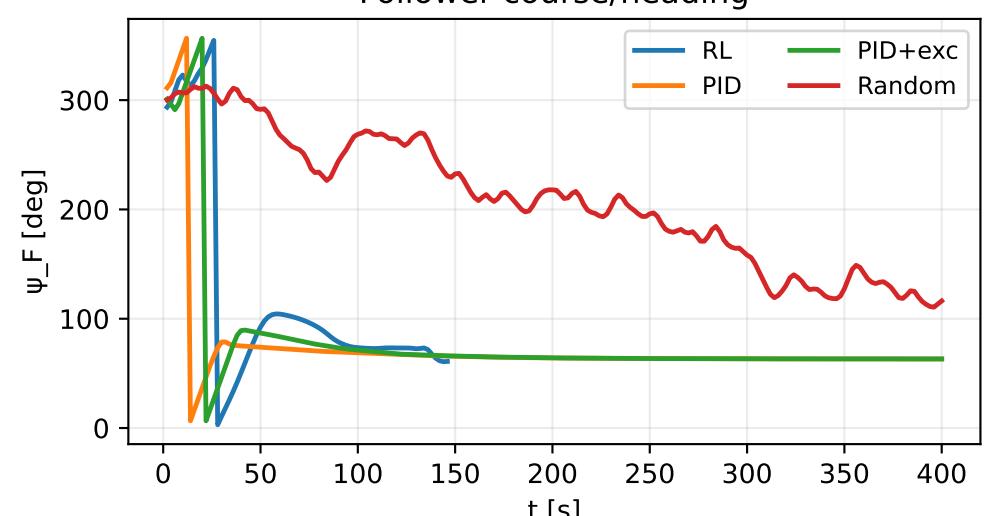
Information and excitation



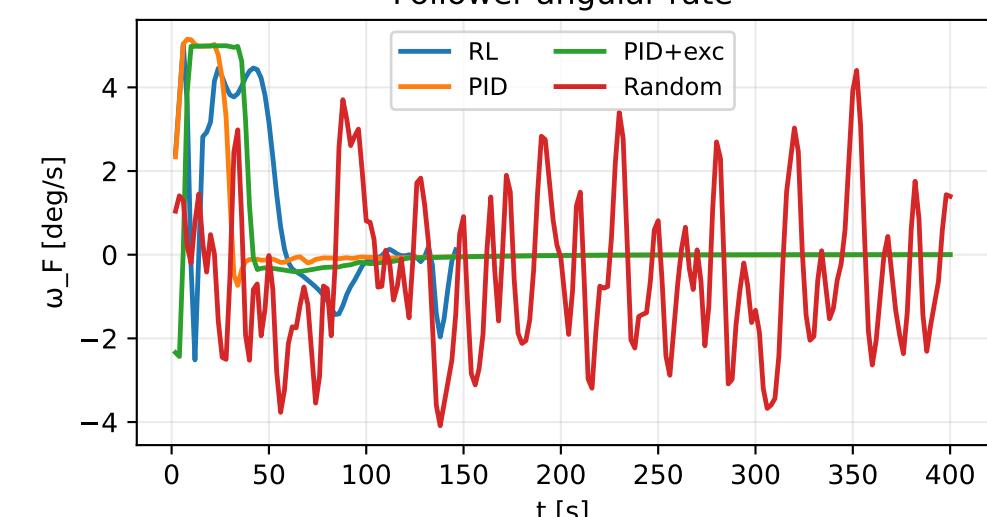
Follower speed



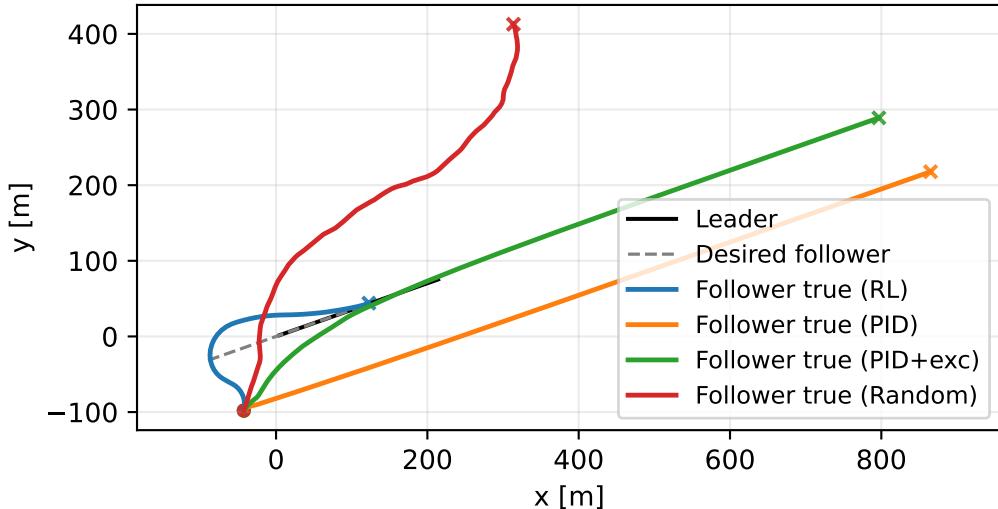
Follower course/heading



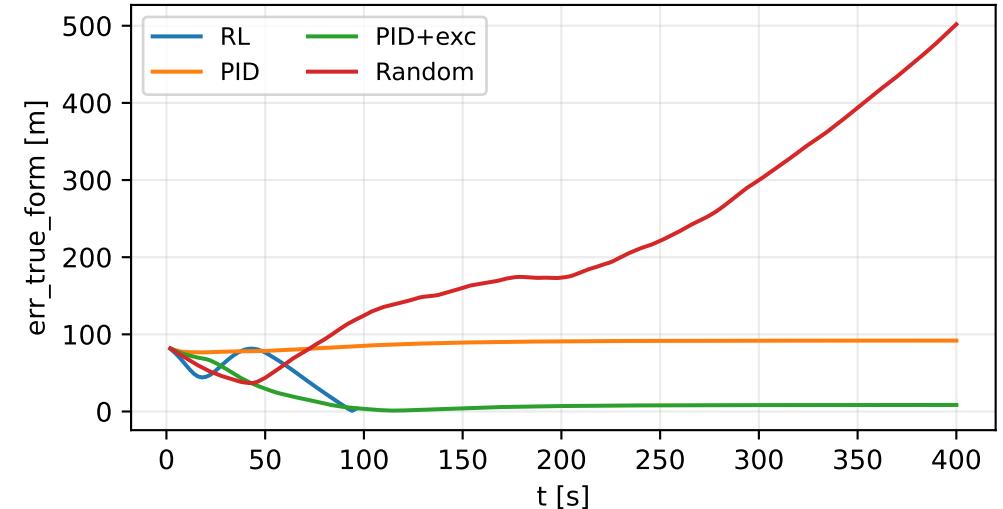
Follower angular rate



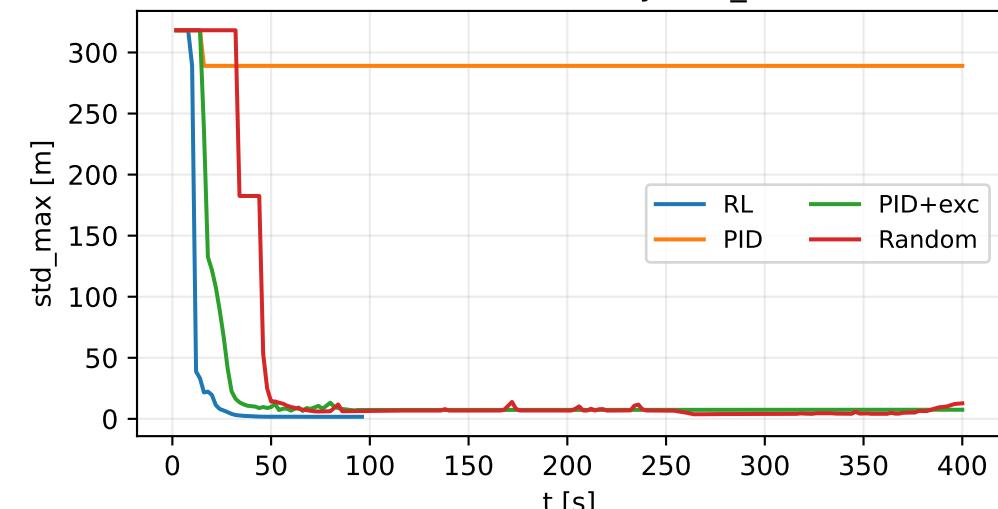
Trajectories (matched seed)



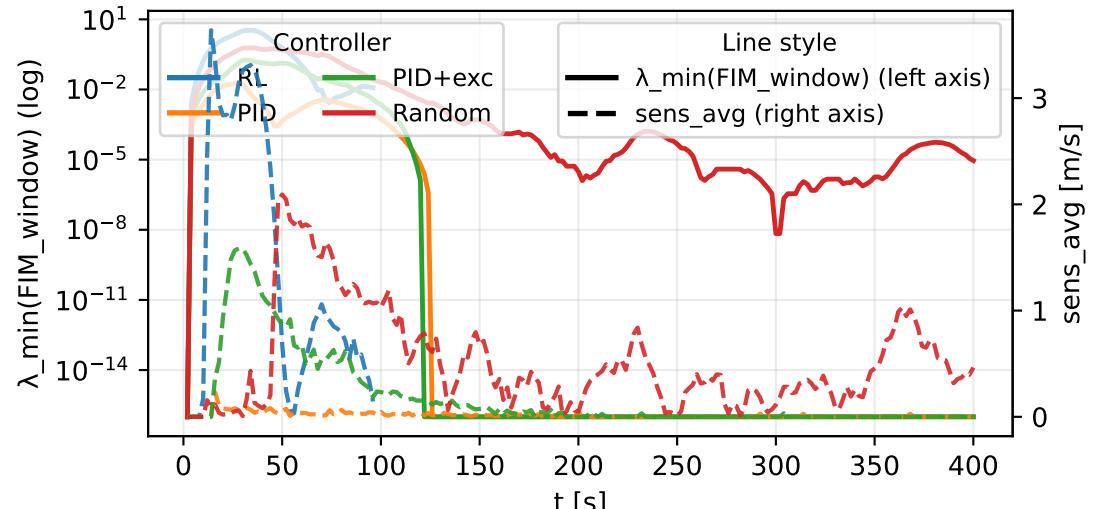
TRUE formation error



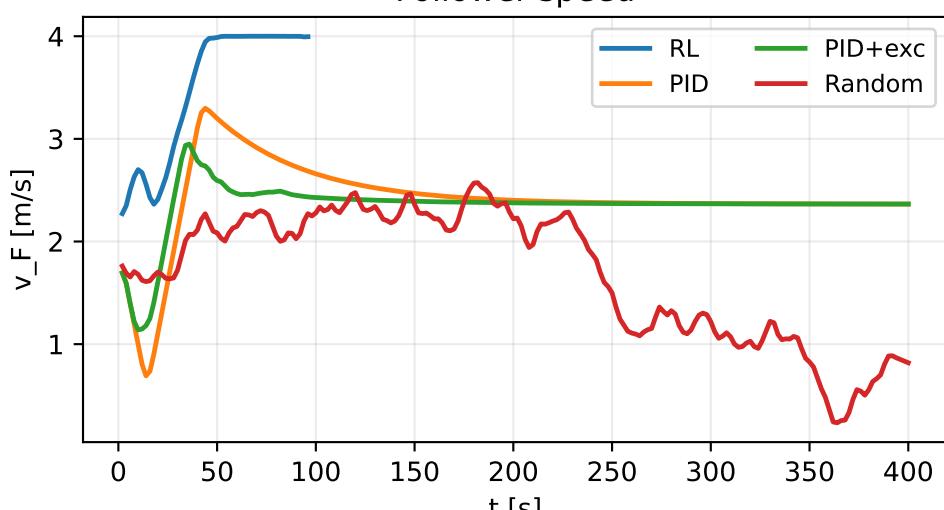
Estimator uncertainty (std_max)



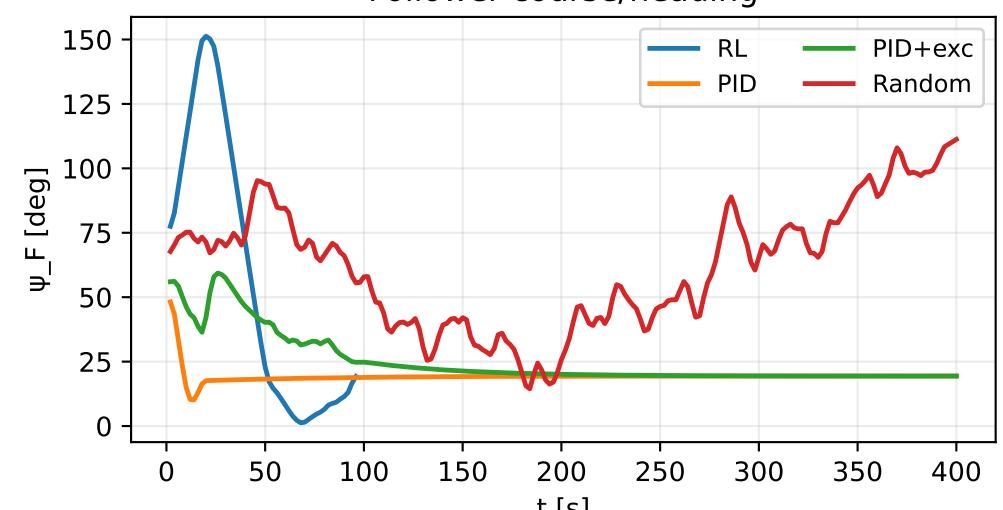
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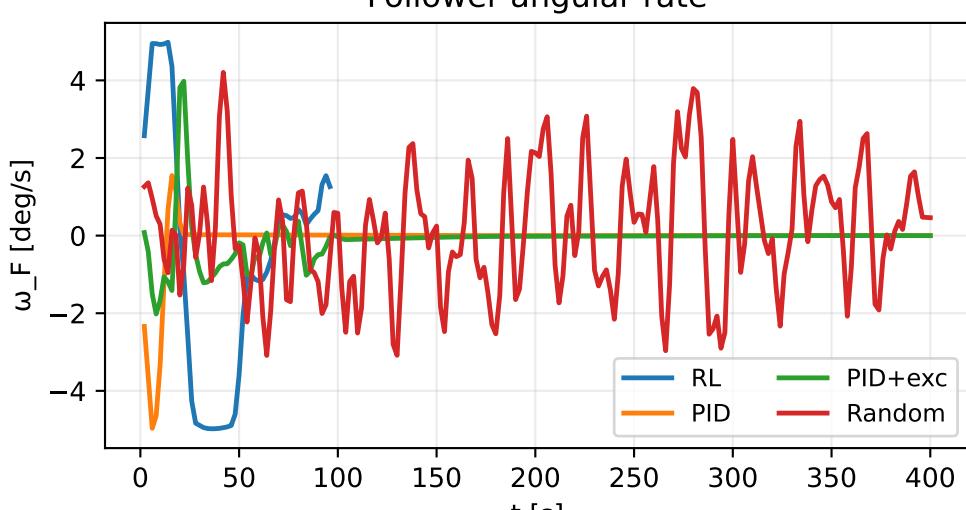
Follower speed



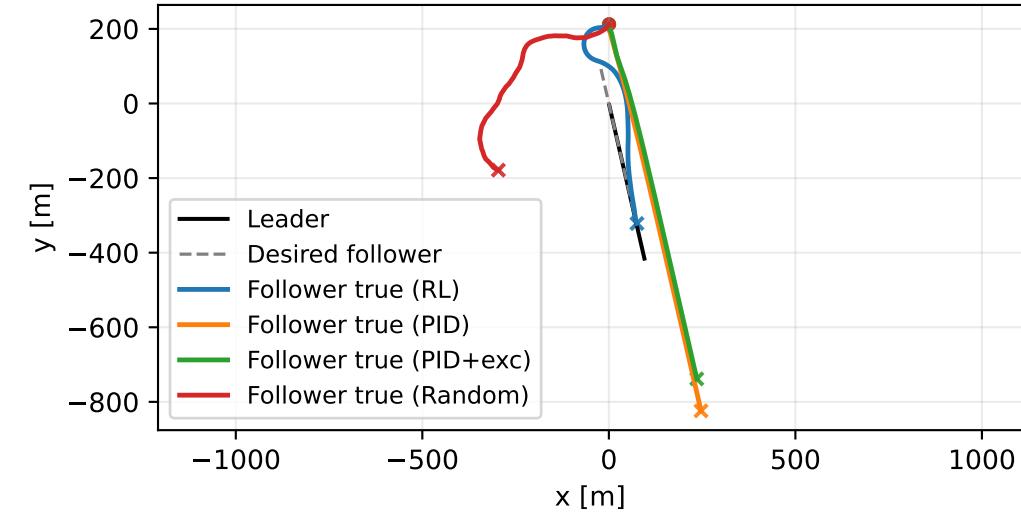
Follower course/heading



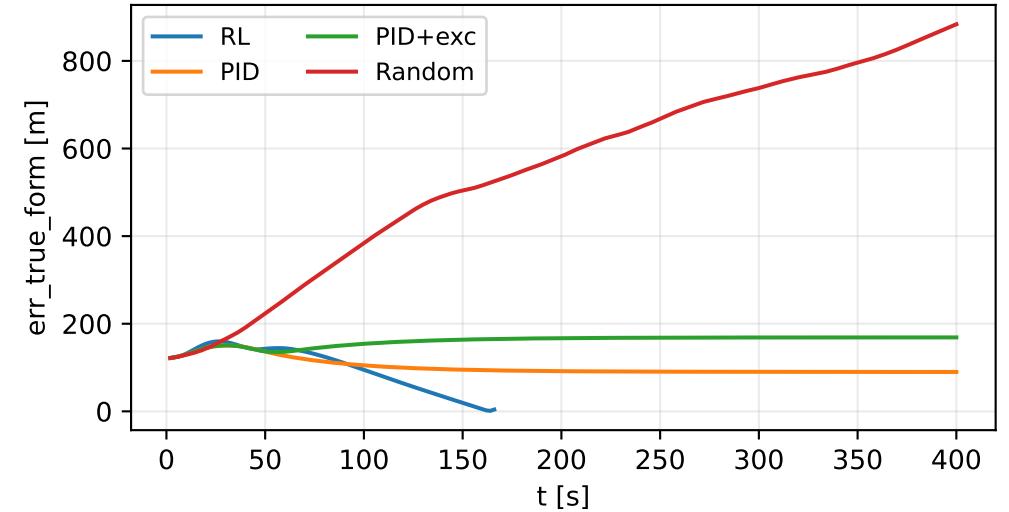
Follower angular rate



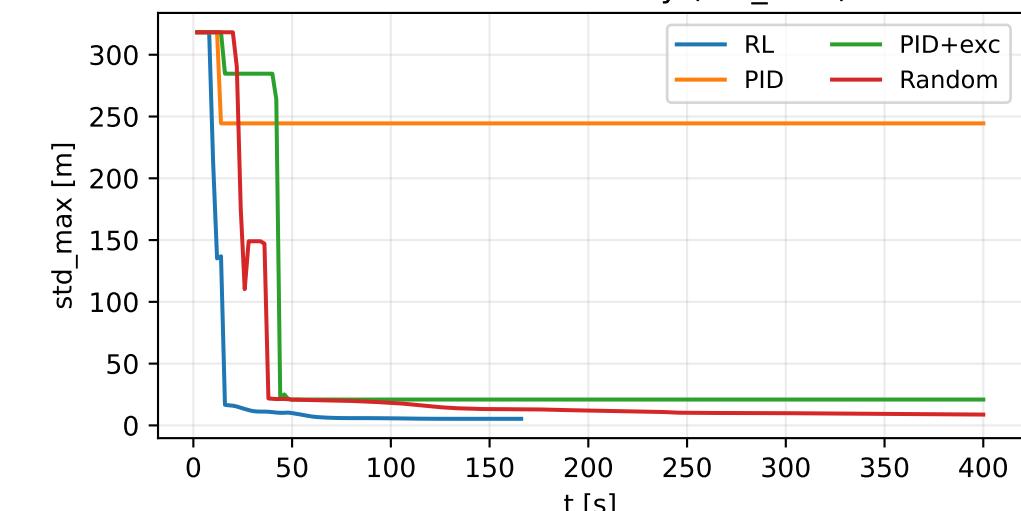
Trajectories (matched seed)



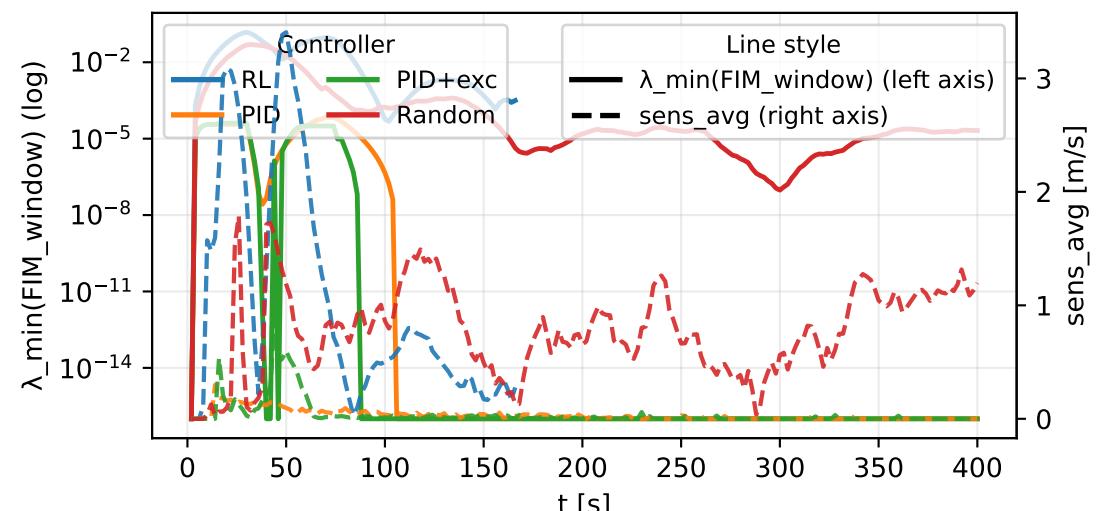
TRUE formation error



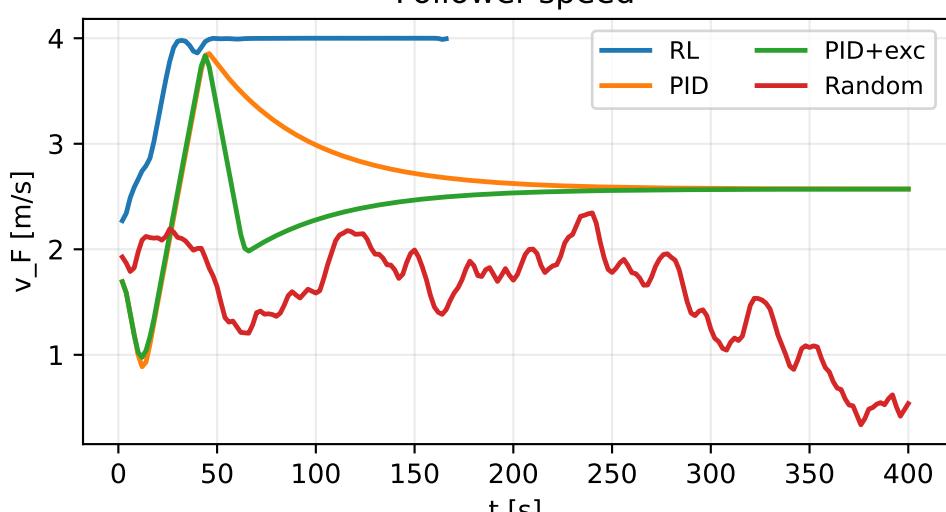
Estimator uncertainty (std_max)



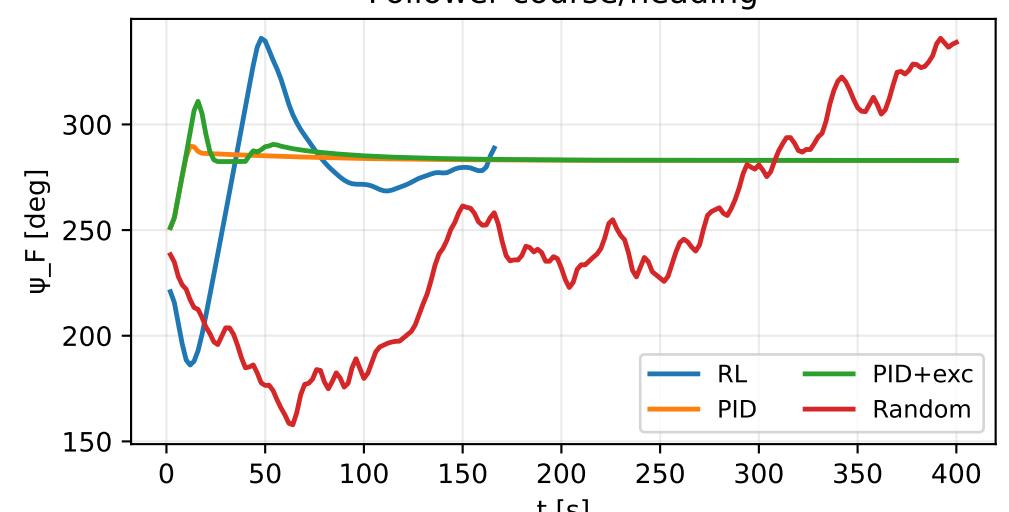
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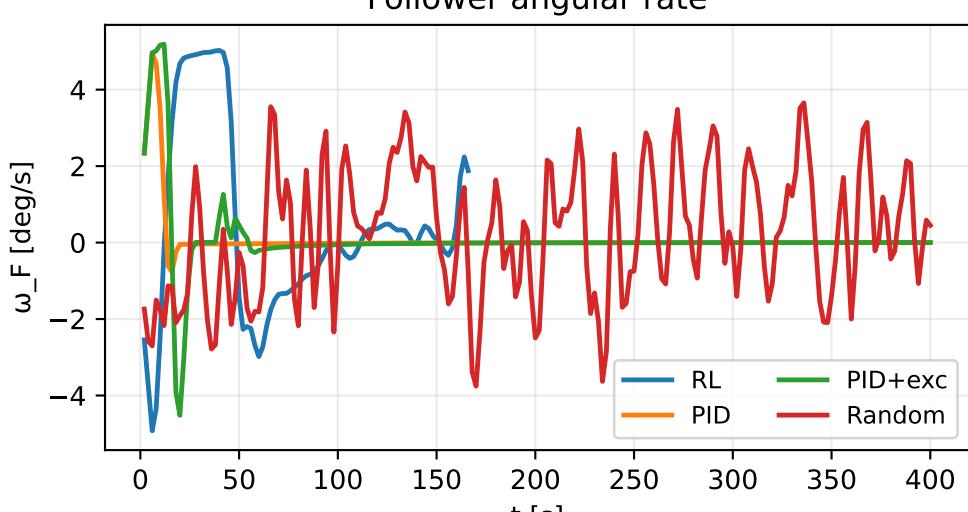
Follower speed



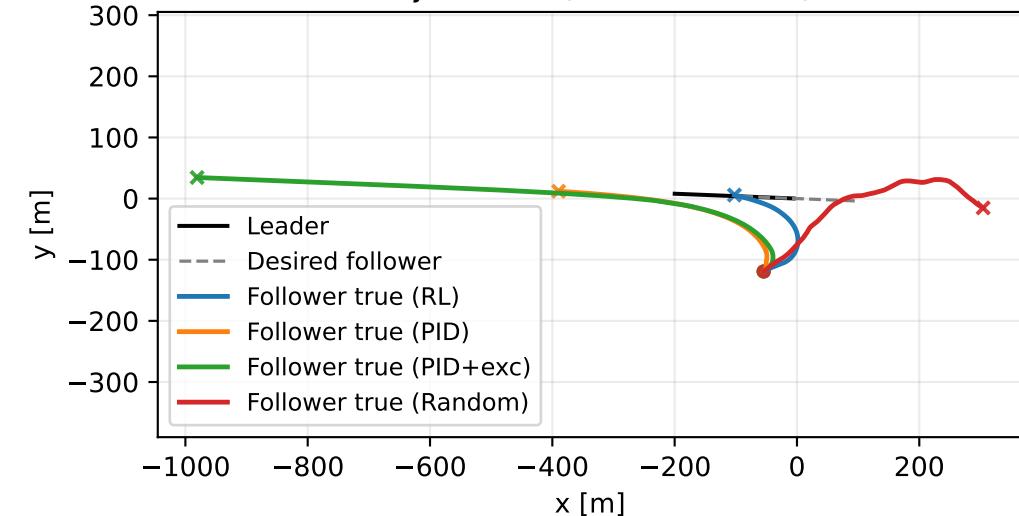
Follower course/heading



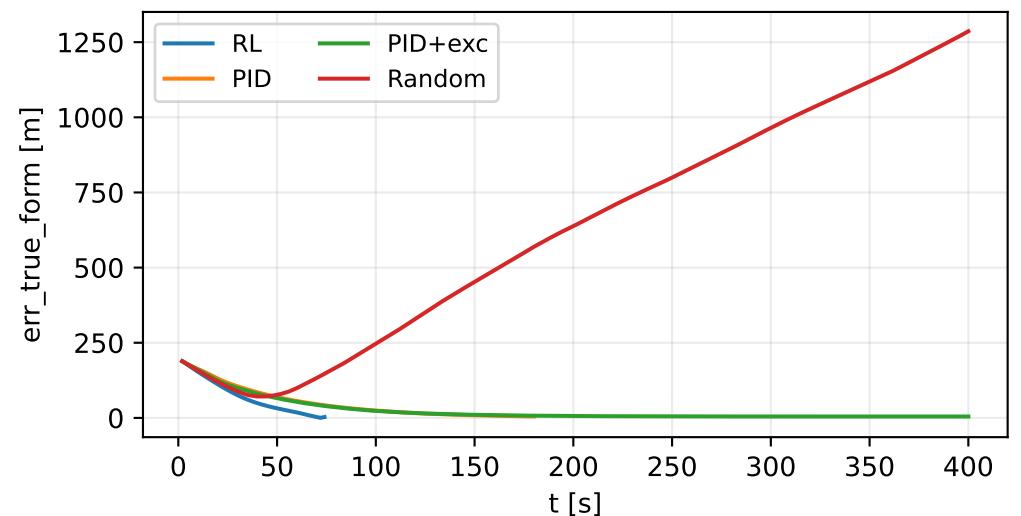
Follower angular rate



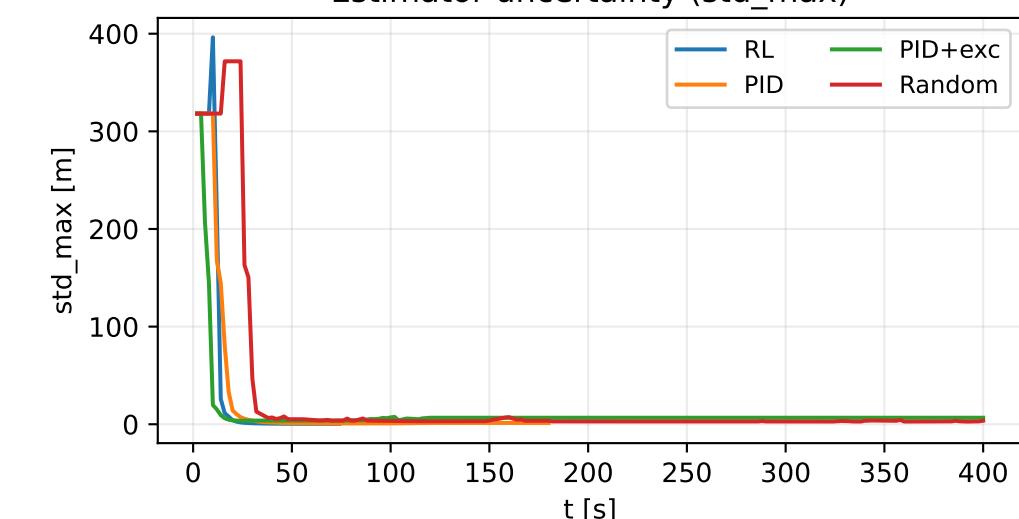
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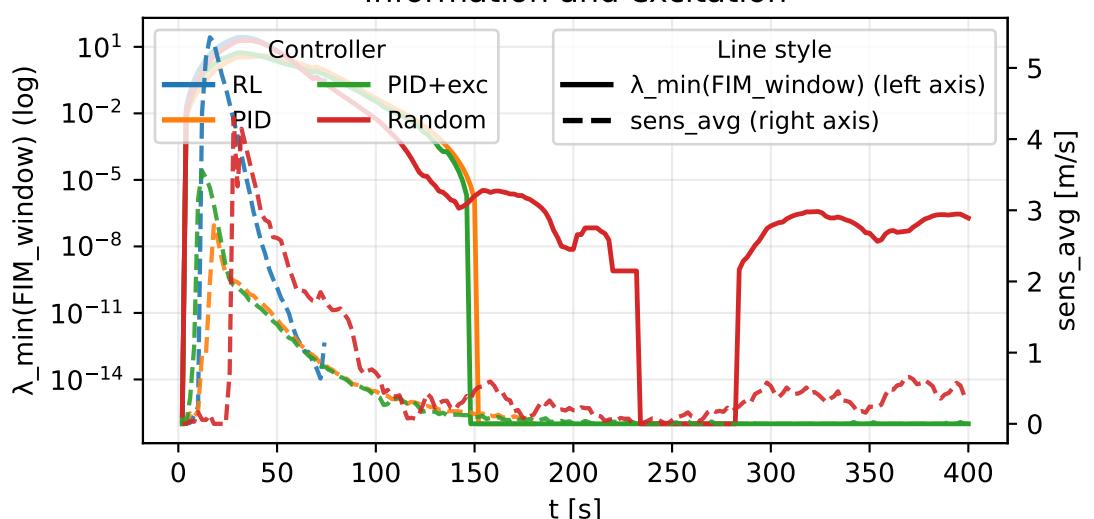
TRUE formation error



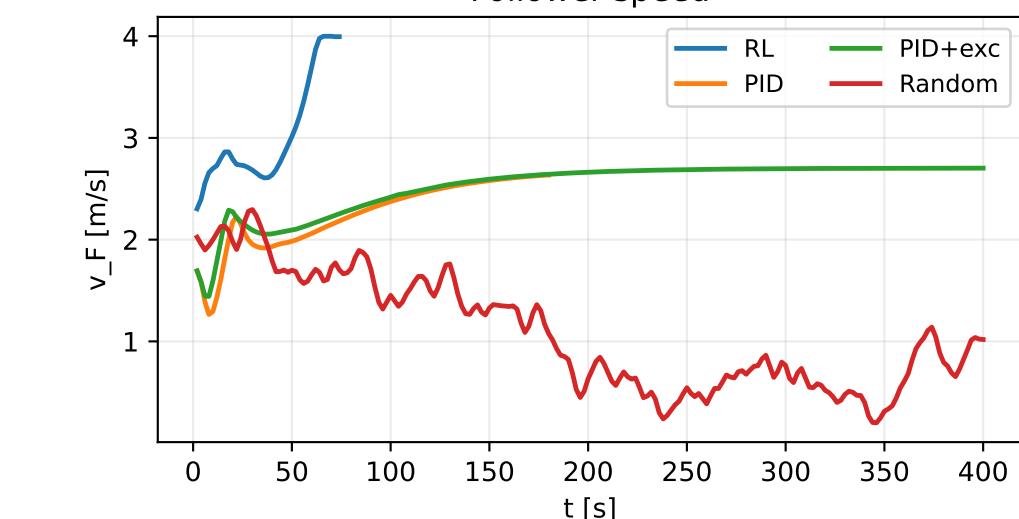
Estimator uncertainty (std_max)



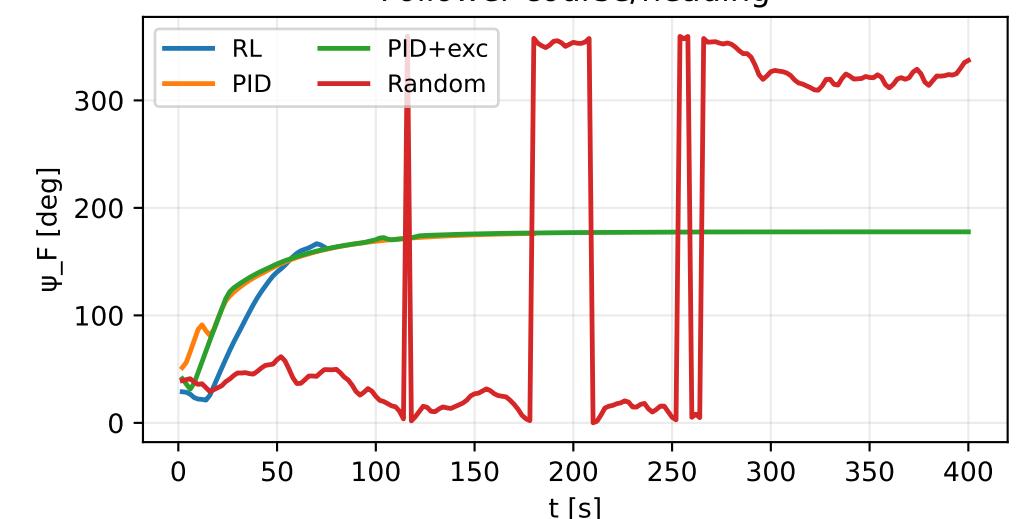
Information and excitation



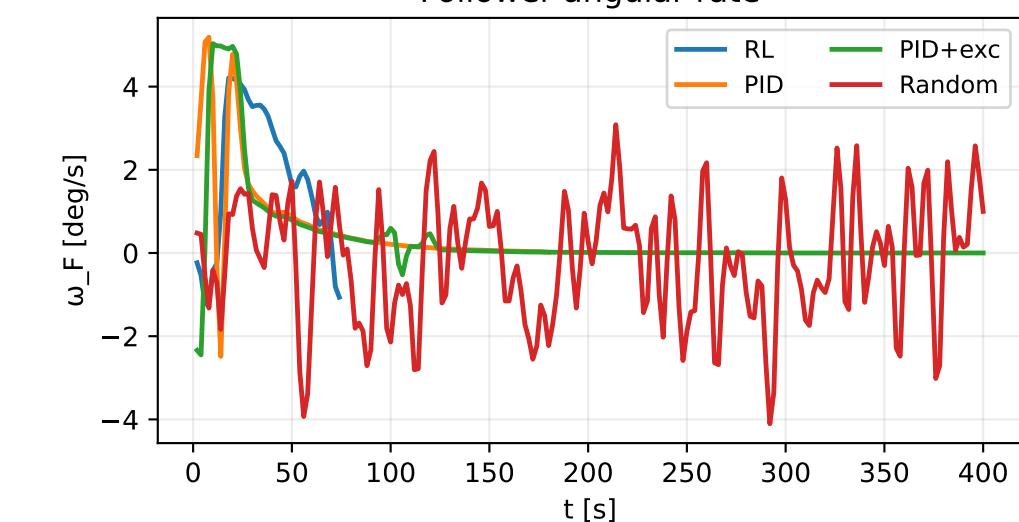
Follower speed



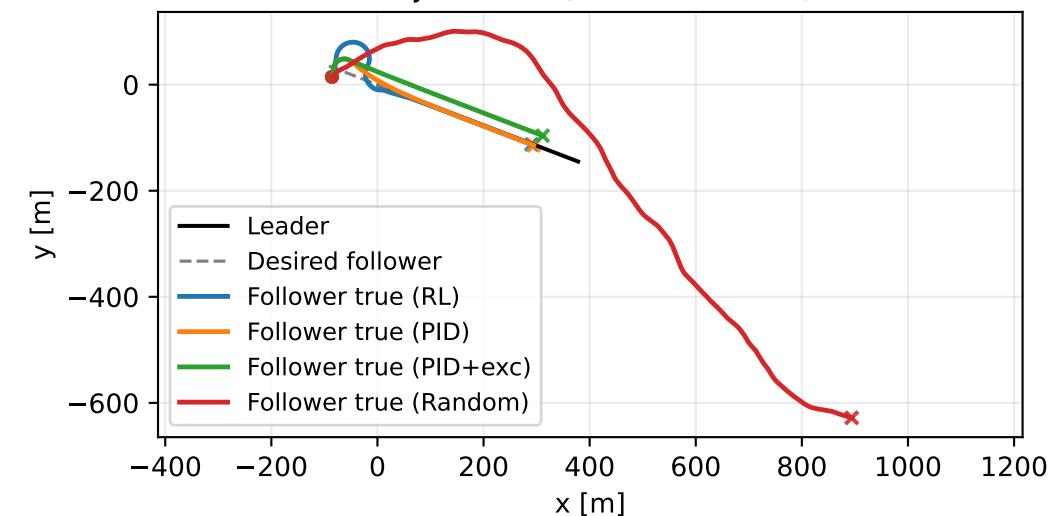
Follower course/heading



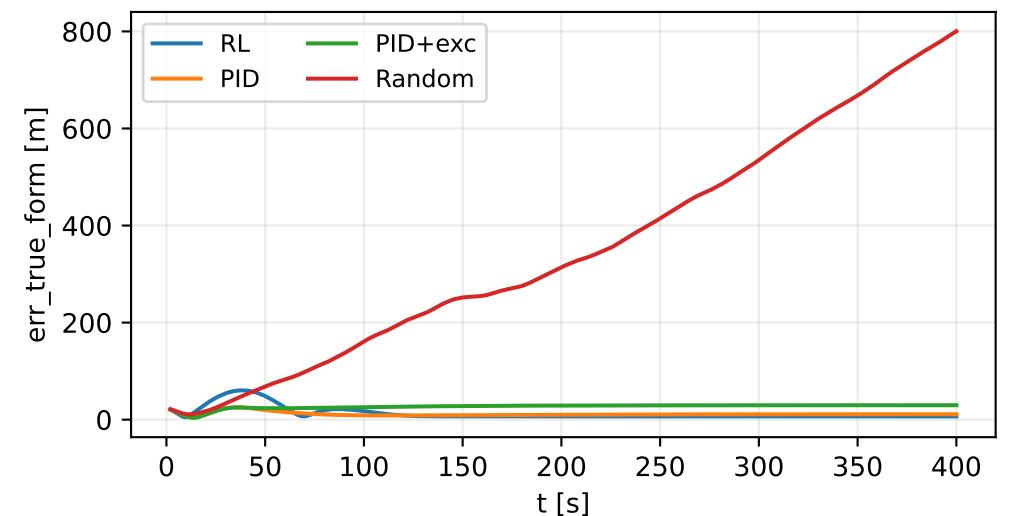
Follower angular rate



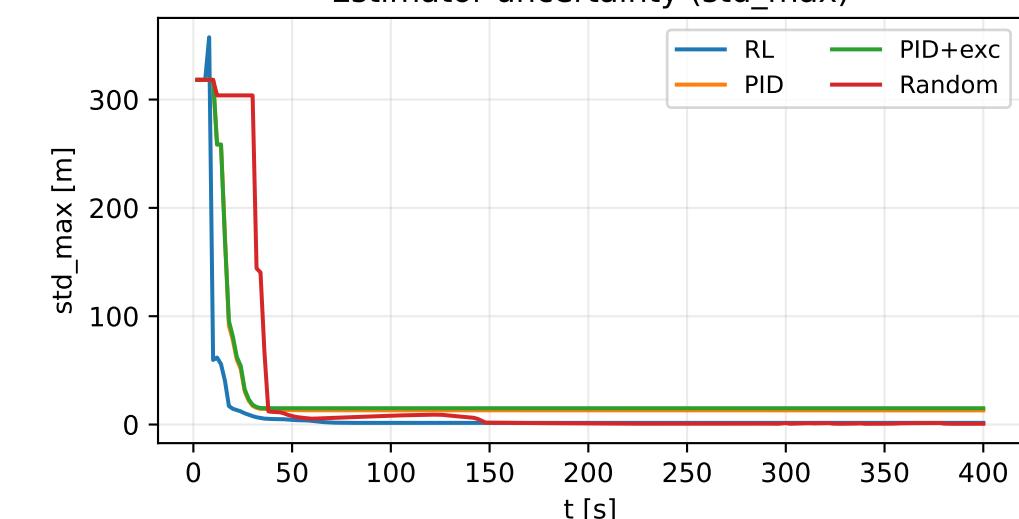
Trajectories (matched seed)



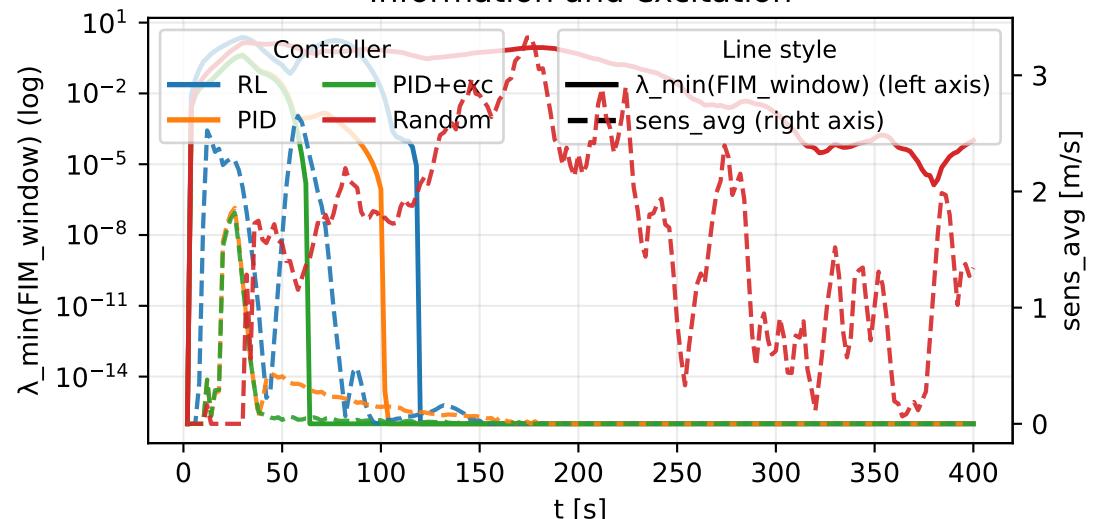
TRUE formation error



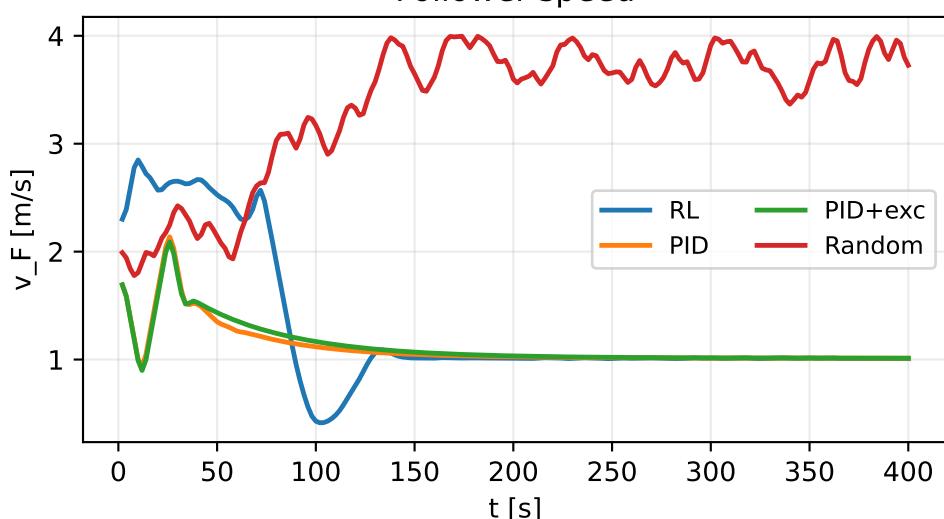
Estimator uncertainty (std_max)



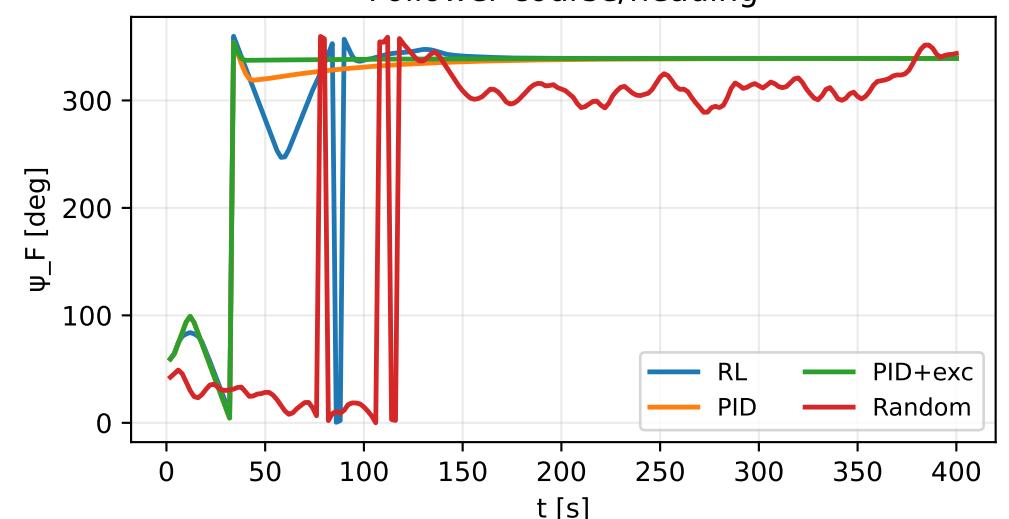
Information and excitation



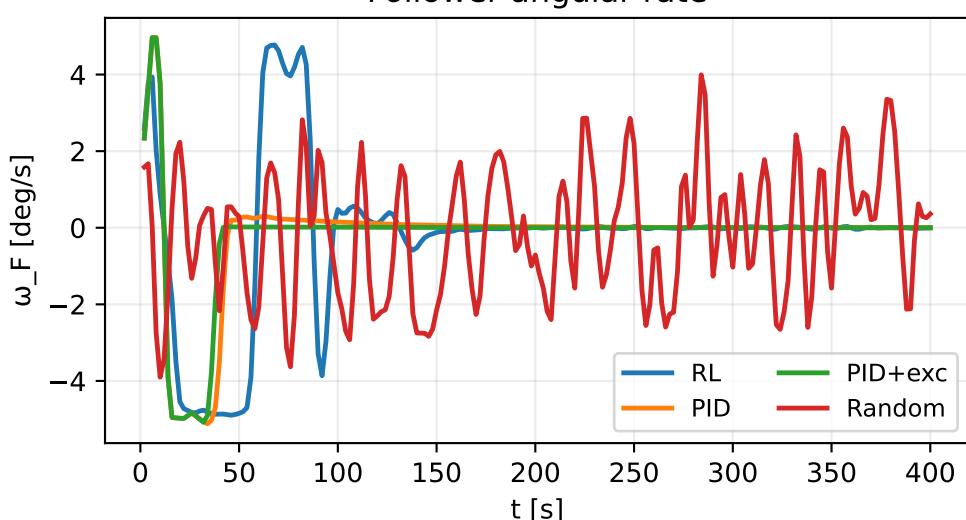
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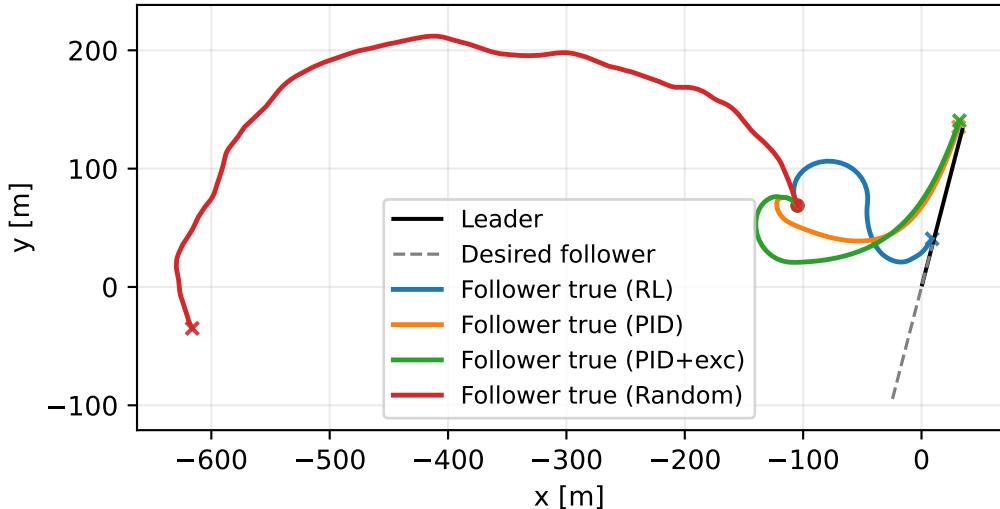
Follower course/heading



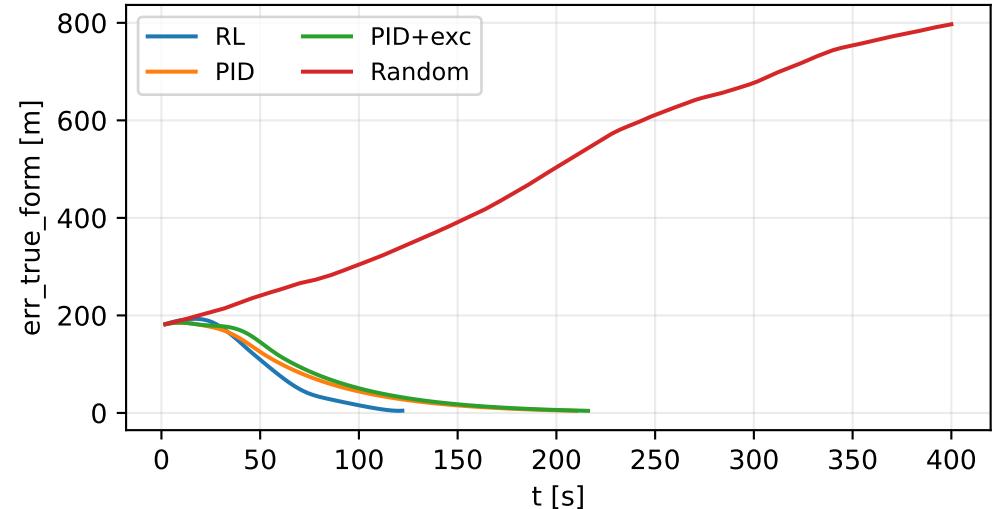
Follower angular rate



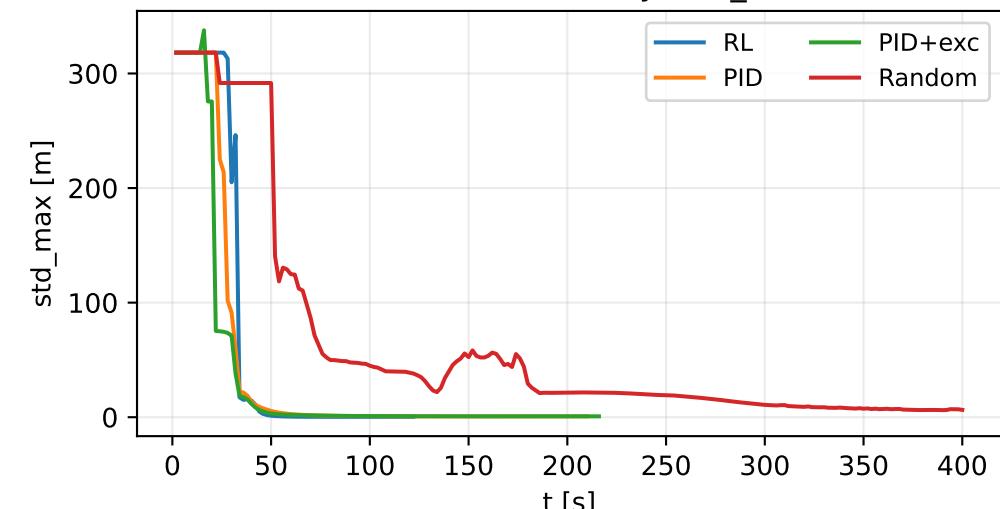
Trajectories (matched seed)



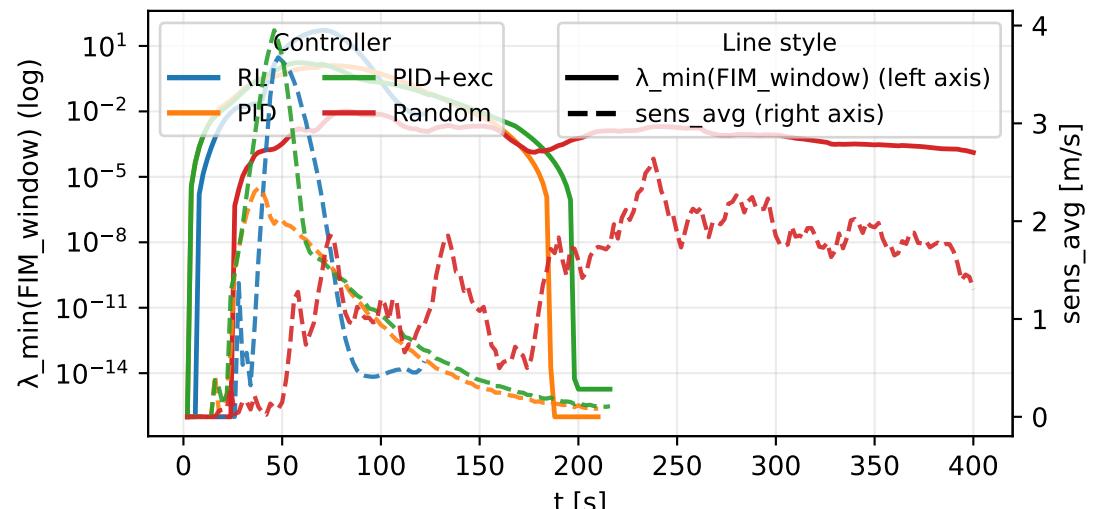
TRUE formation error



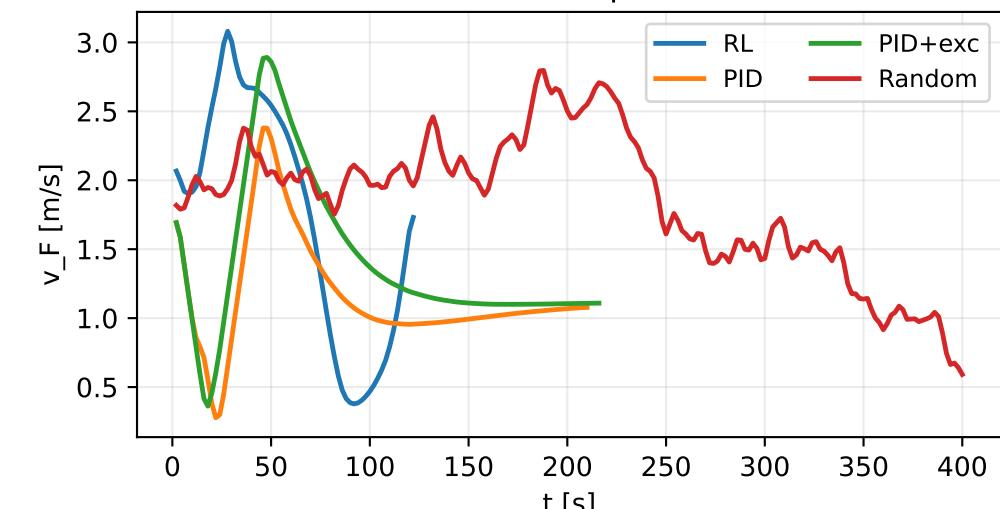
Estimator uncertainty (std_max)



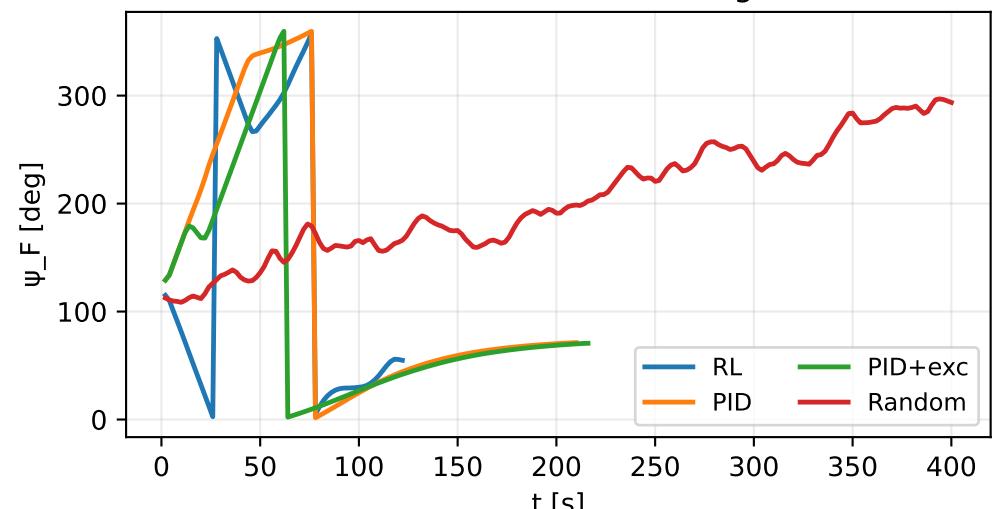
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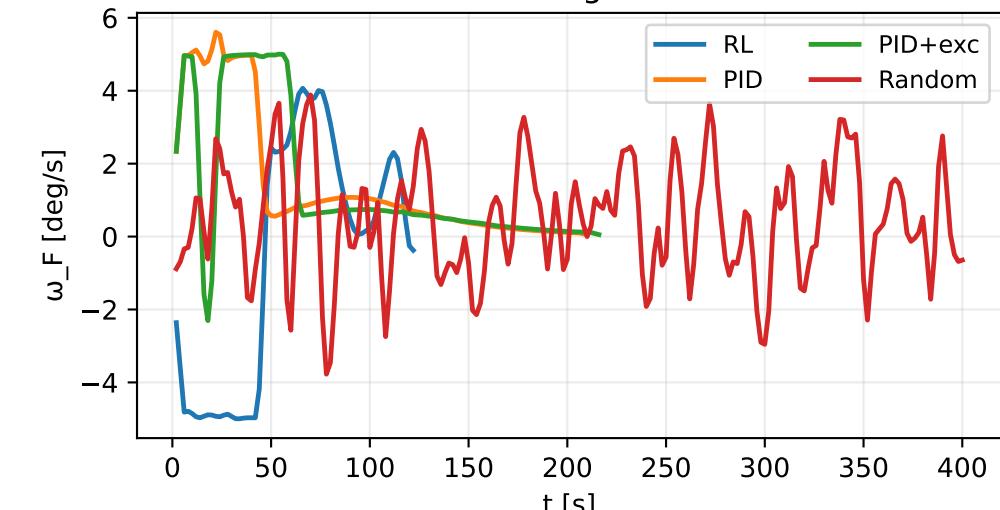
Follower speed



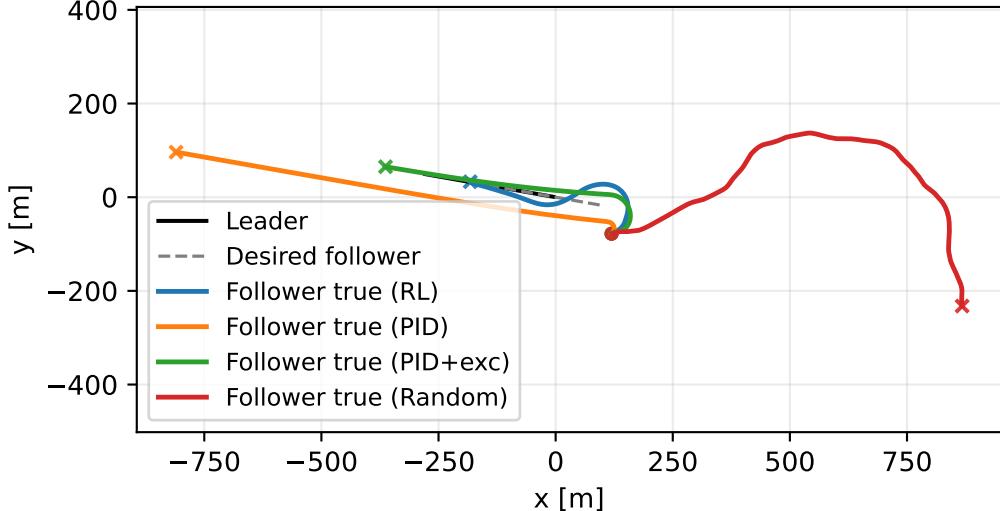
Follower course/heading



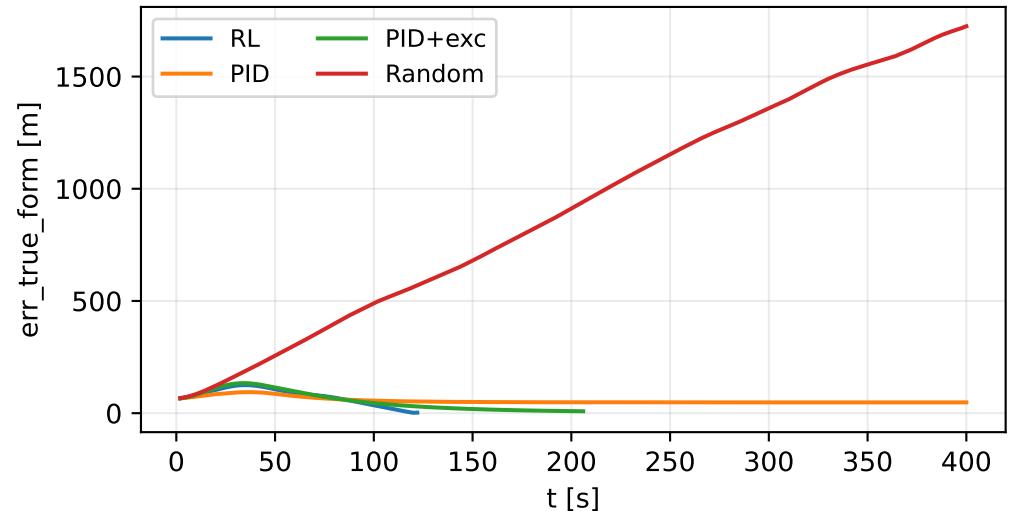
Follower angular rate



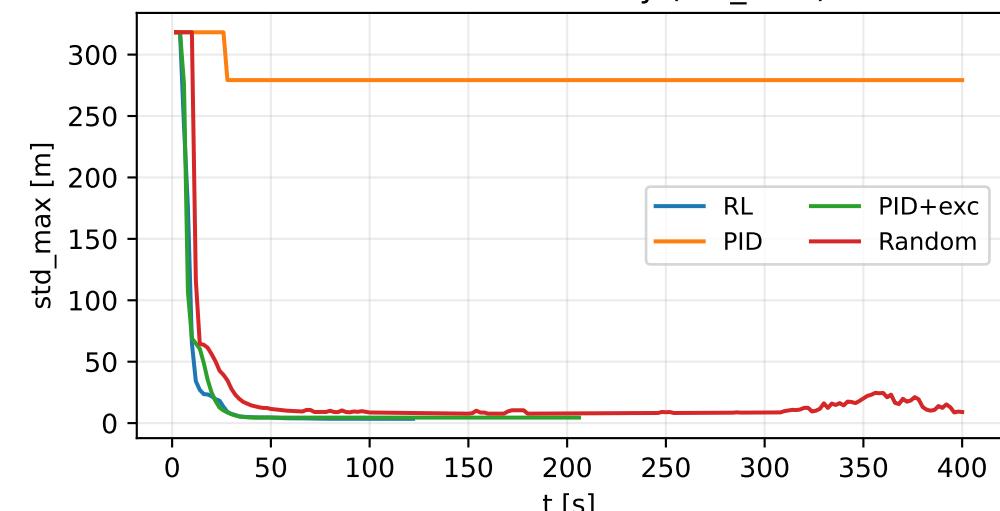
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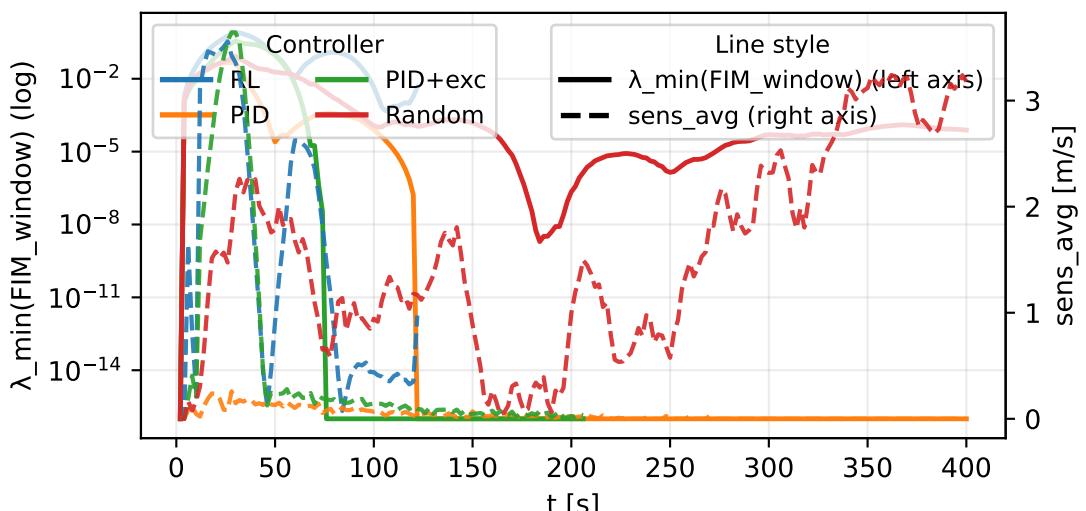
TRUE formation error



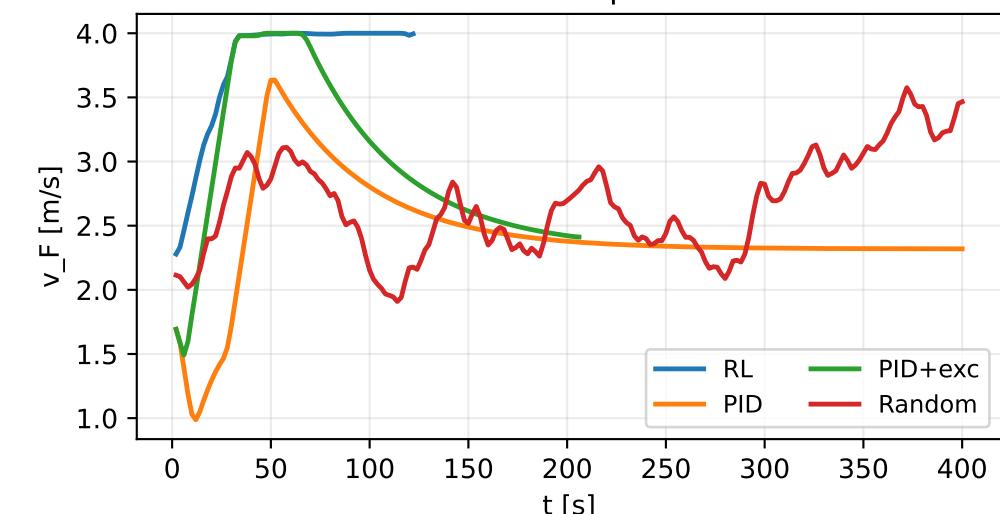
Estimator uncertainty (std_max)



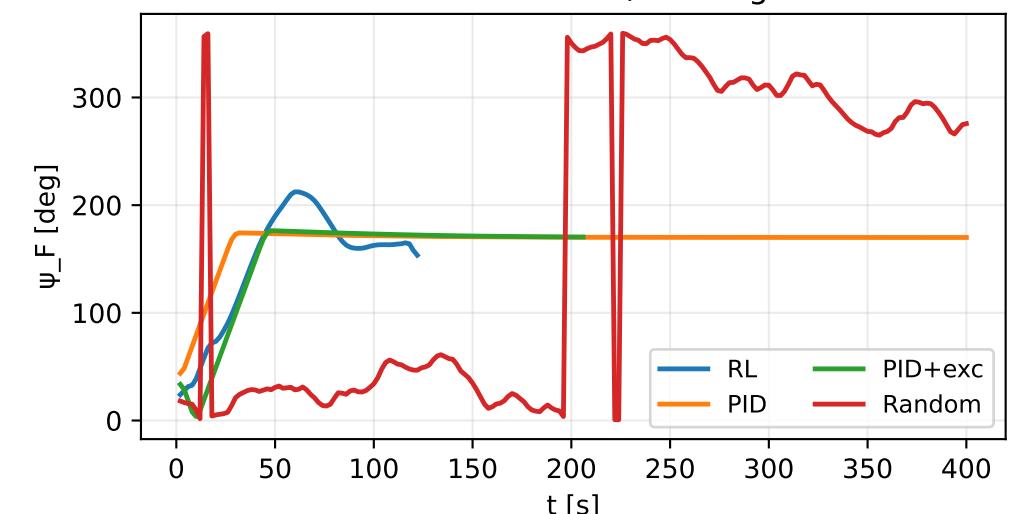
Information and excitation



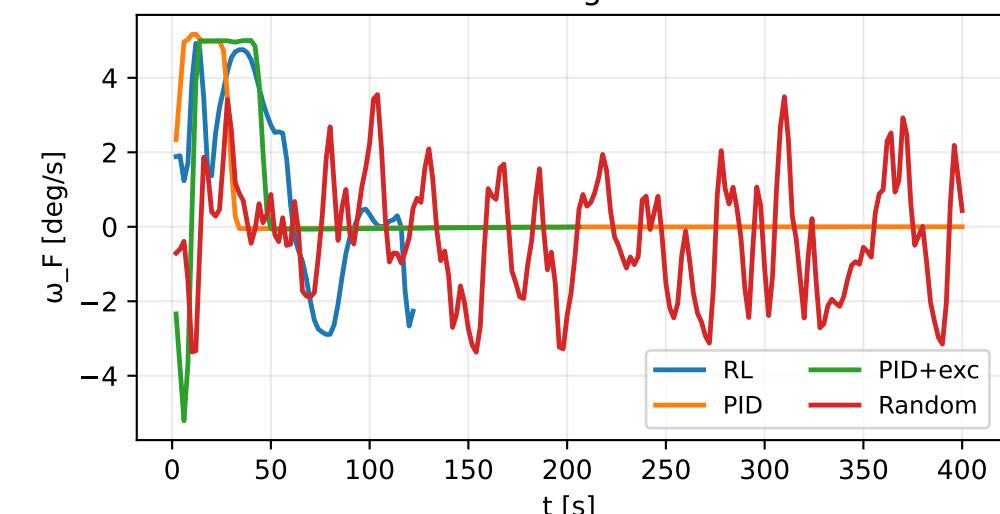
Follower speed



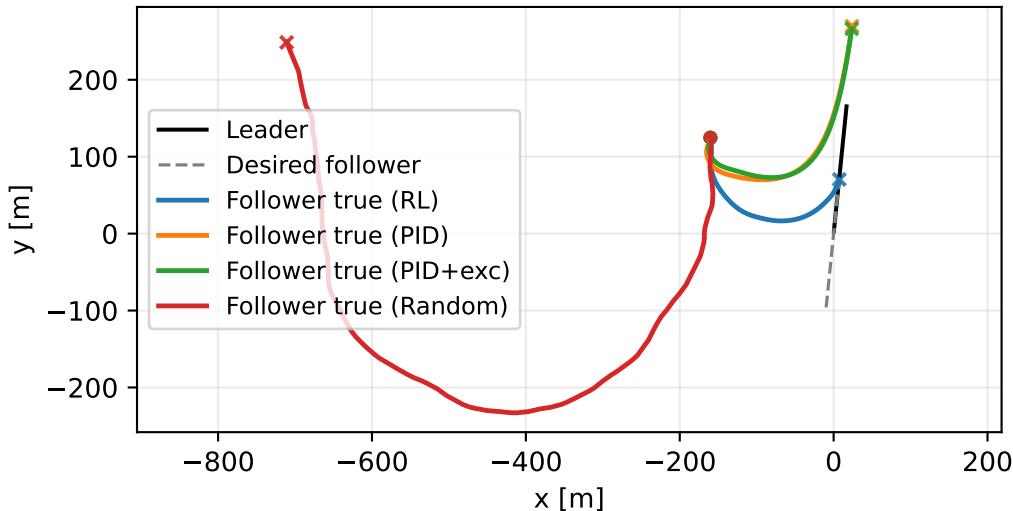
Follower course/heading



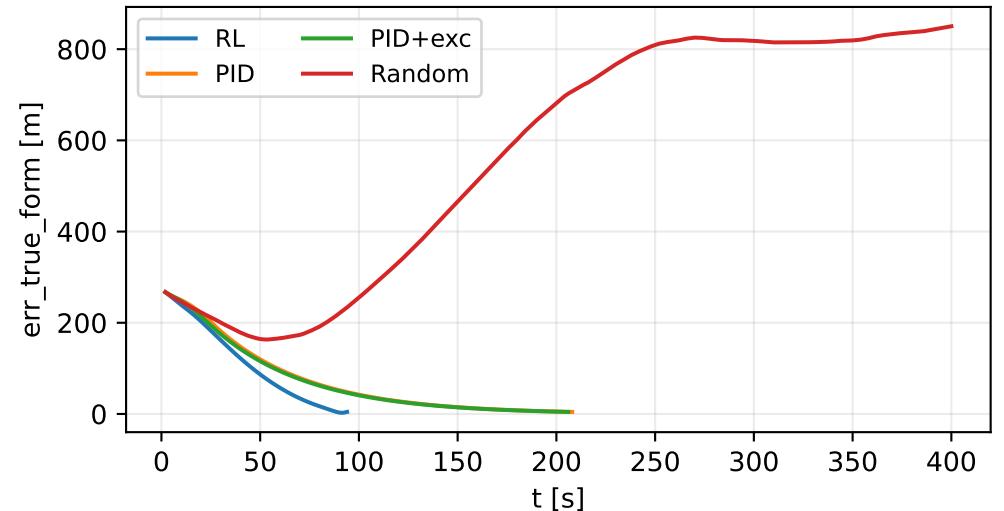
Follower angular rate



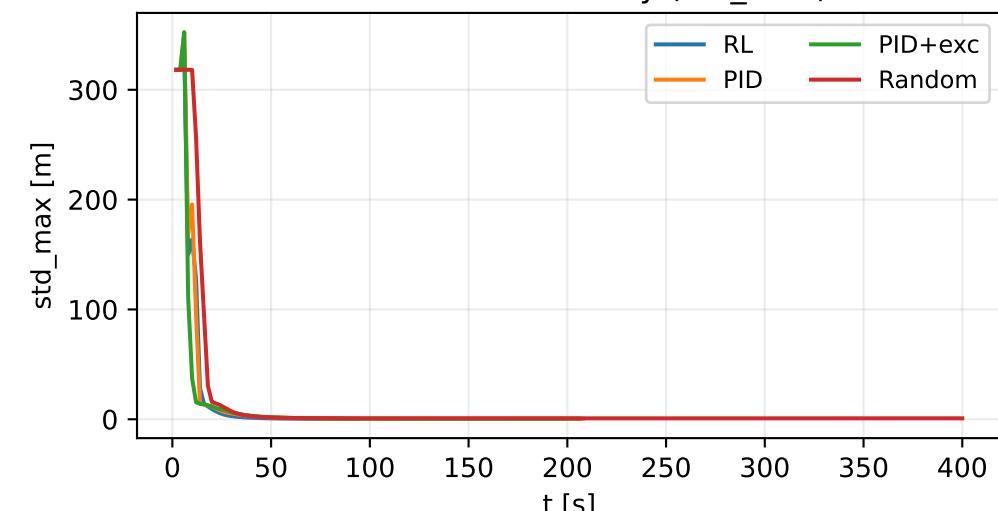
Trajectories (matched seed)



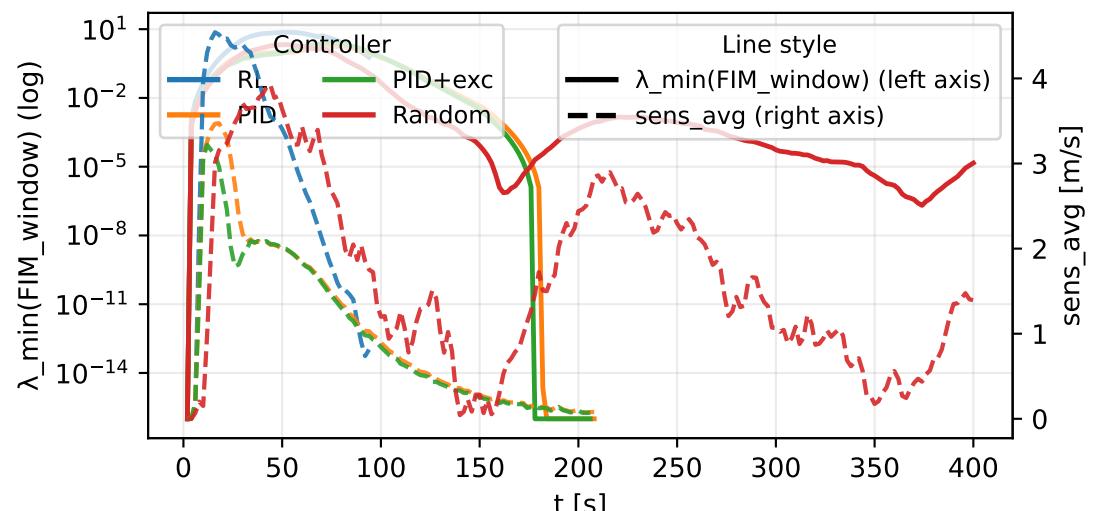
TRUE formation error



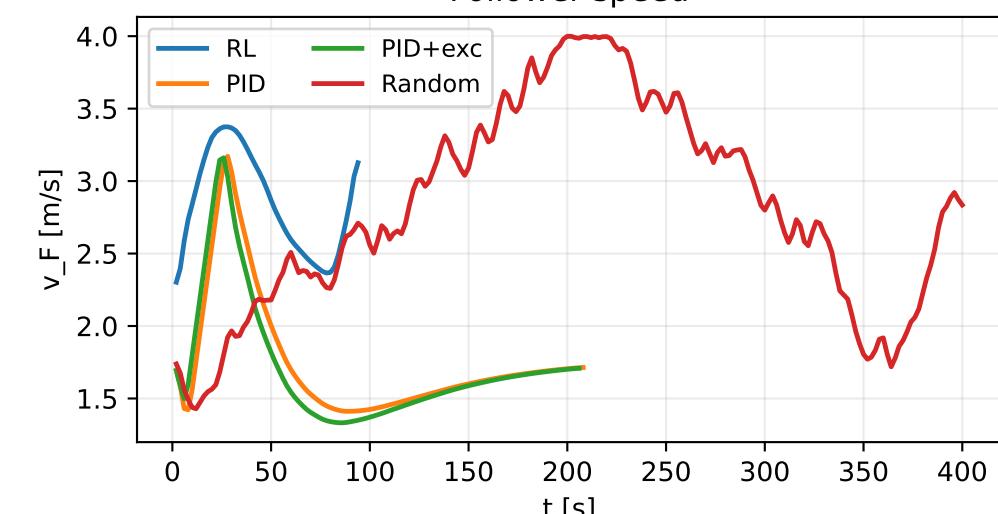
Estimator uncertainty (std_max)



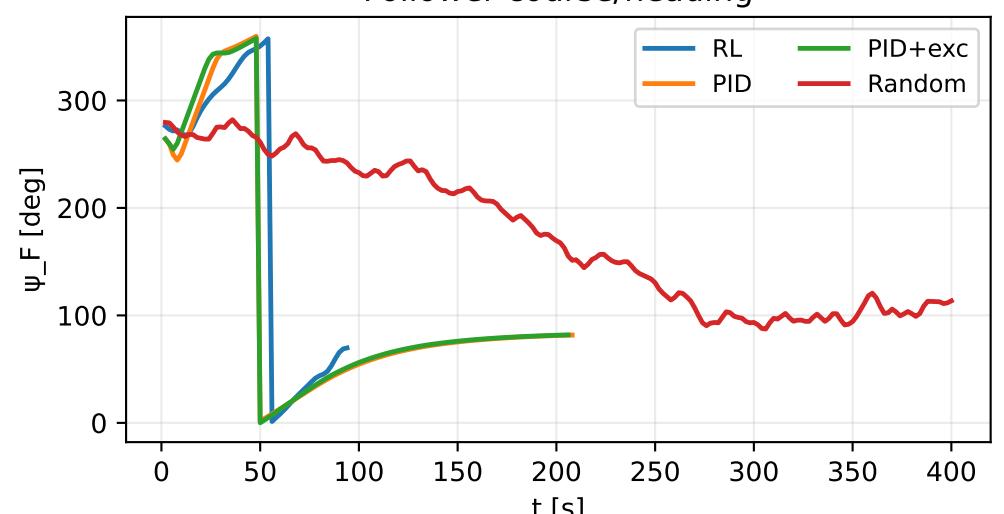
Information and excitation



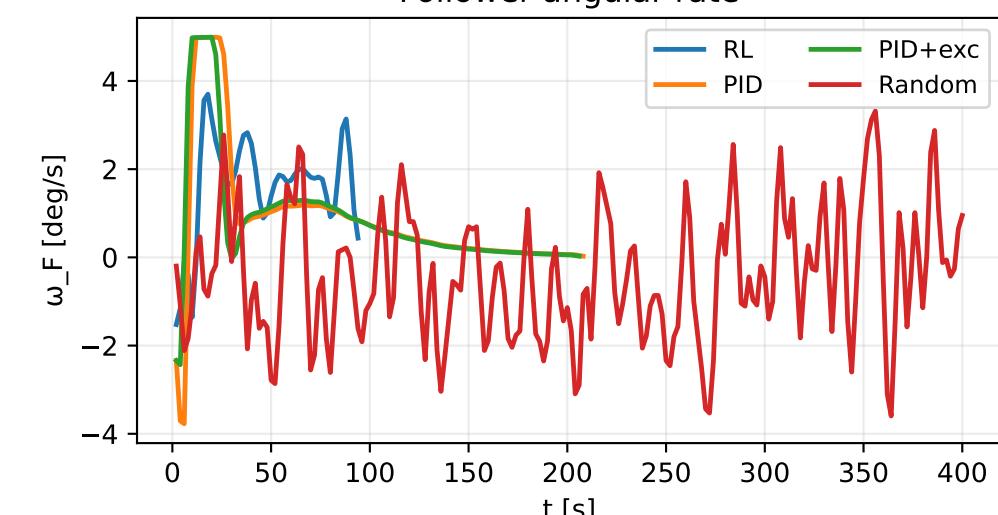
Follower speed



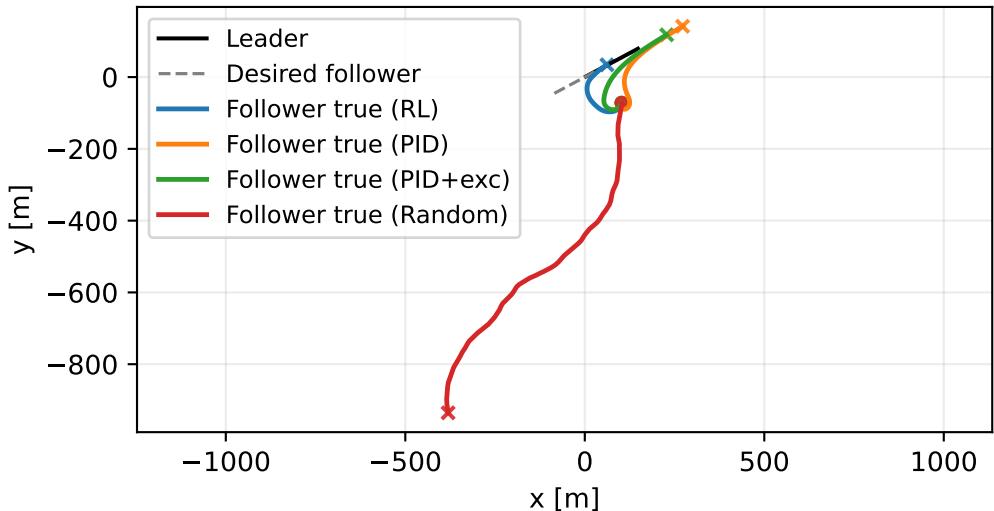
Follower course/heading



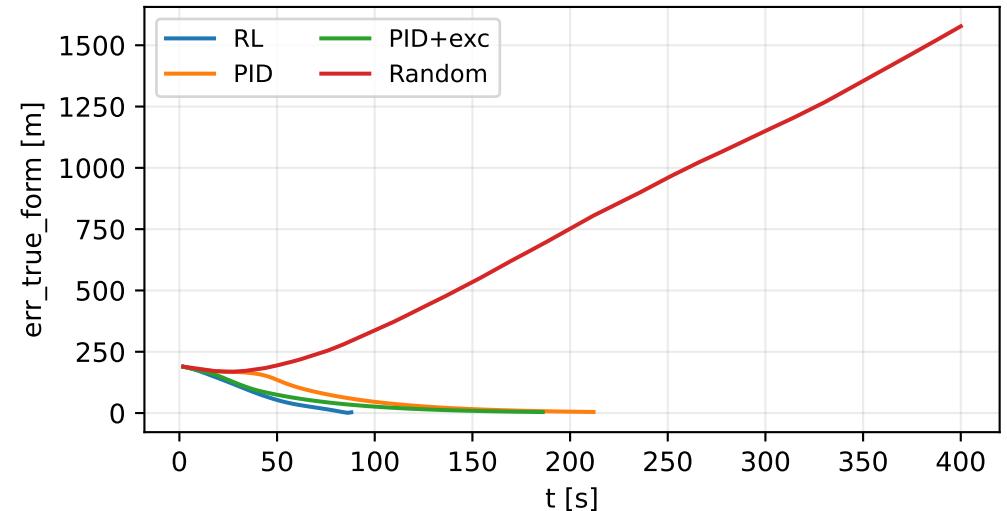
Follower angular rate



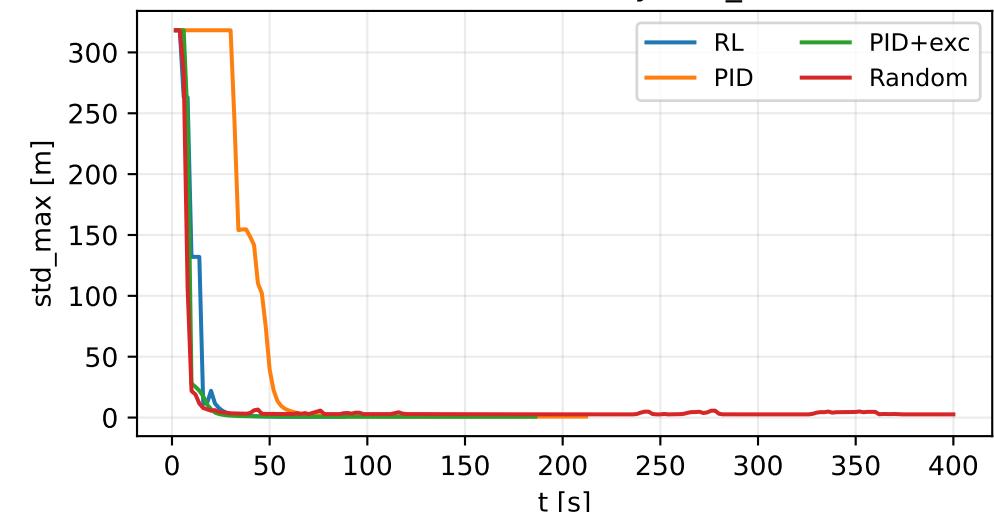
Trajectories (matched seed)



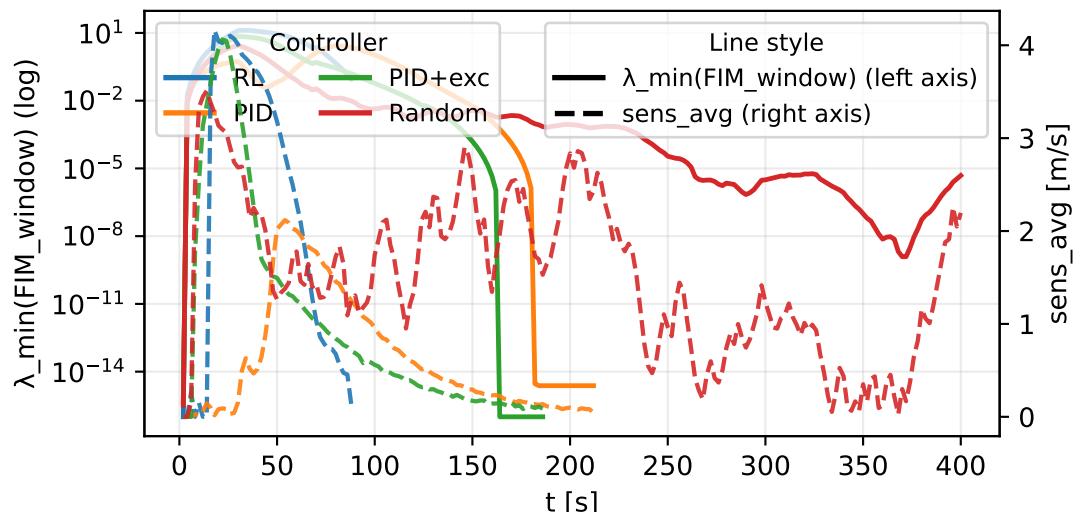
TRUE formation error



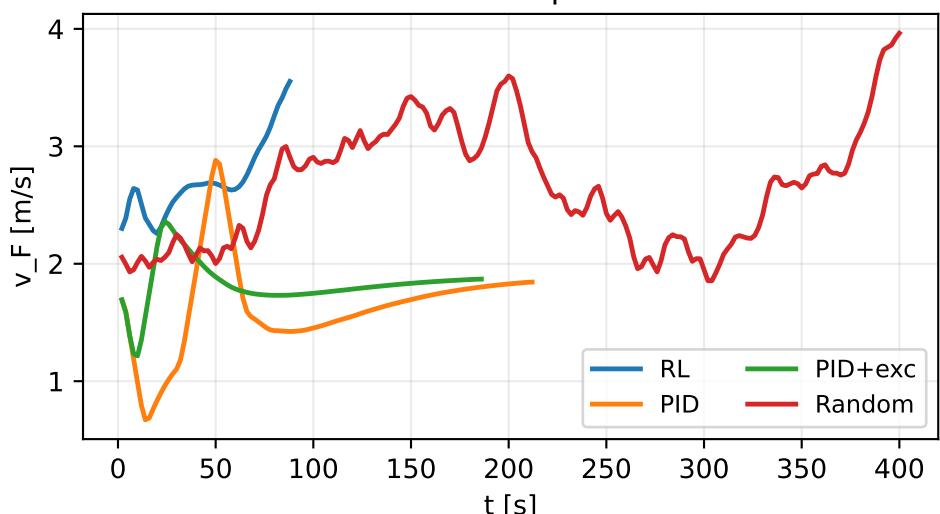
Estimator uncertainty (std_max)



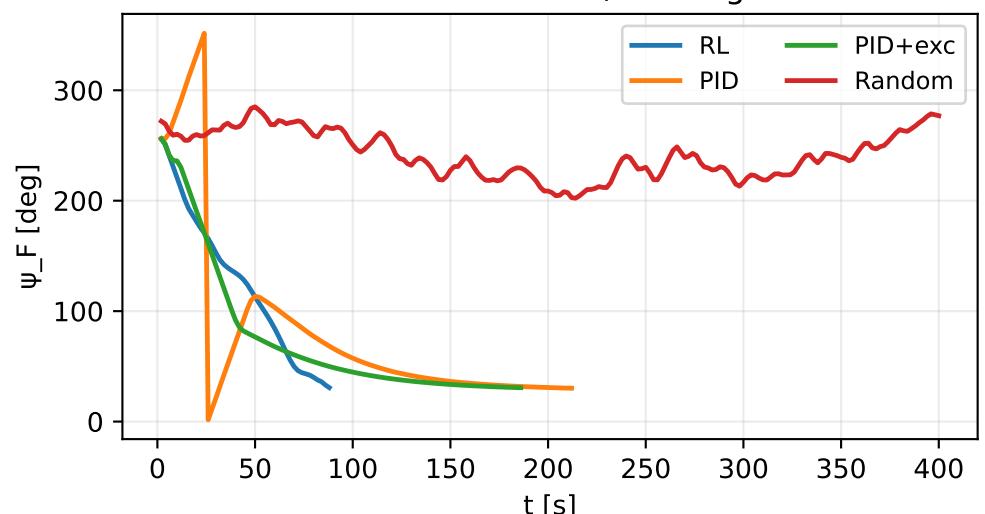
Information and excitation



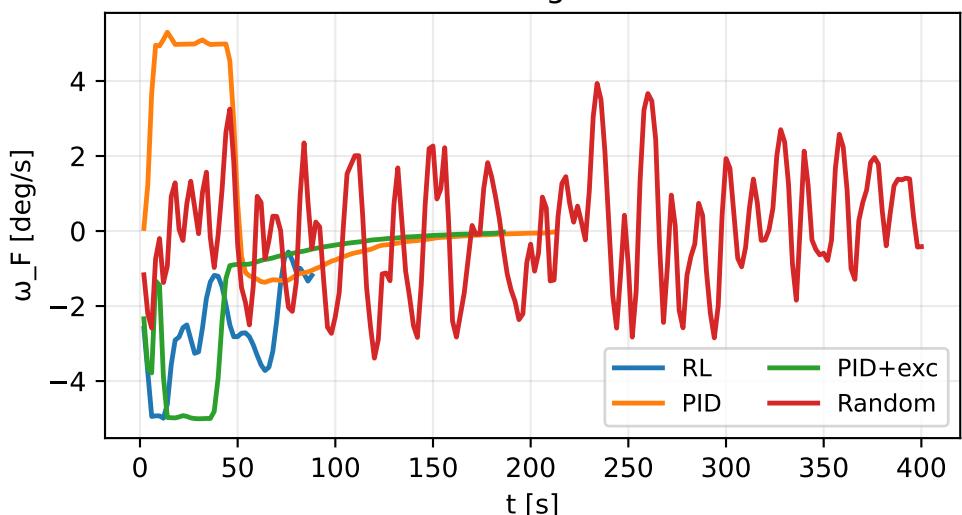
Follower speed



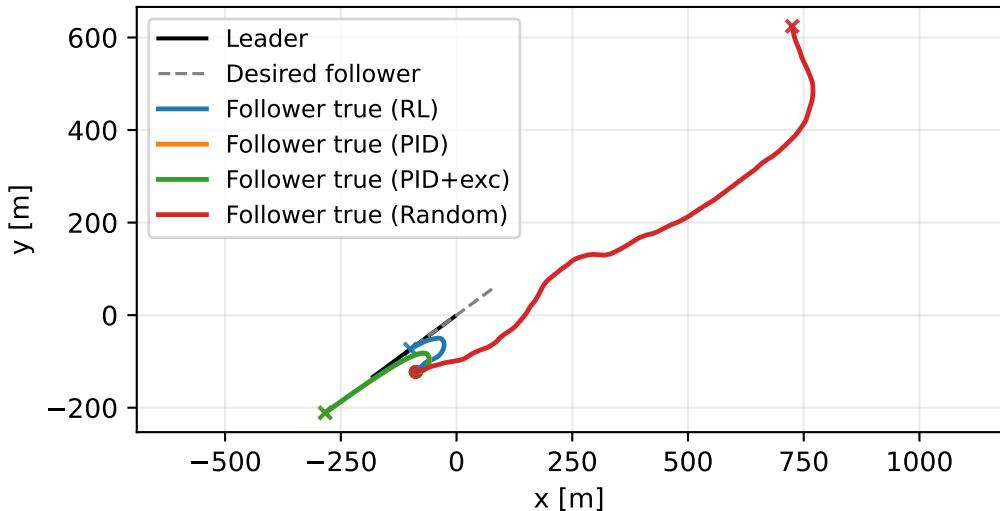
Follower course/heading



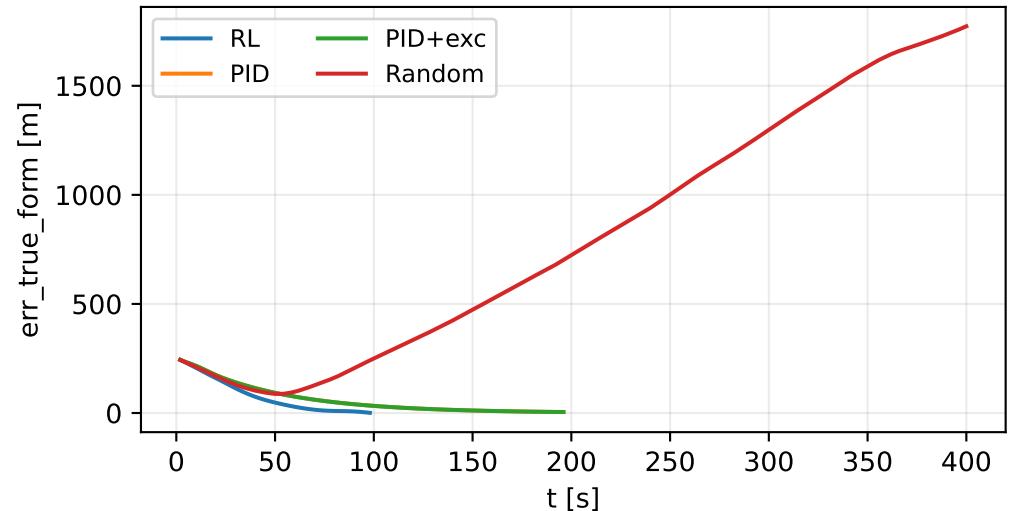
Follower angular rate



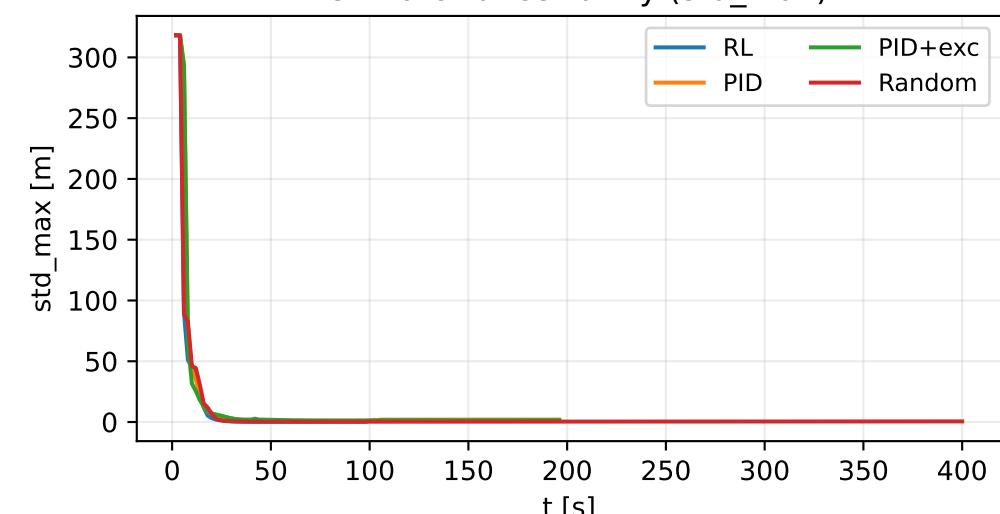
Trajectories (matched seed)



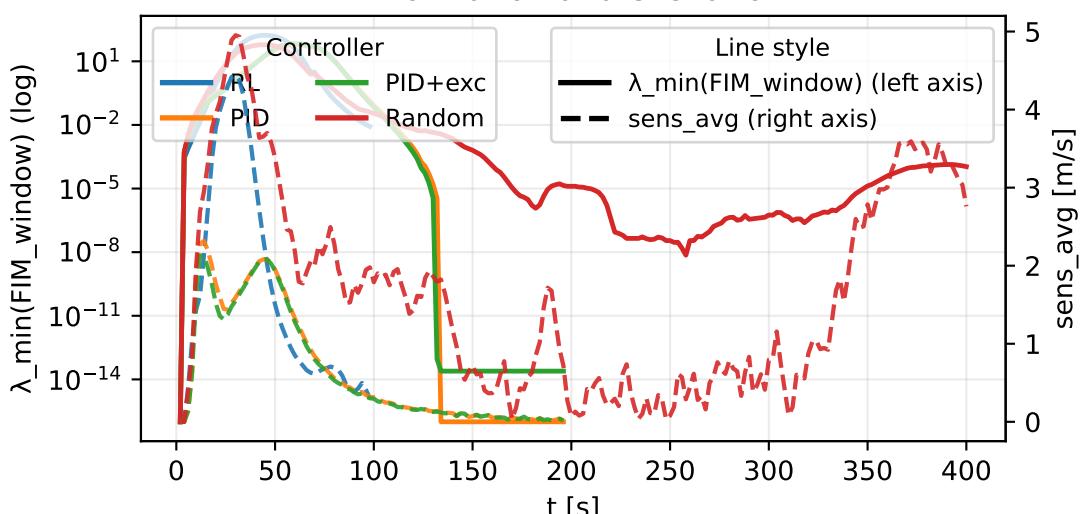
TRUE formation error



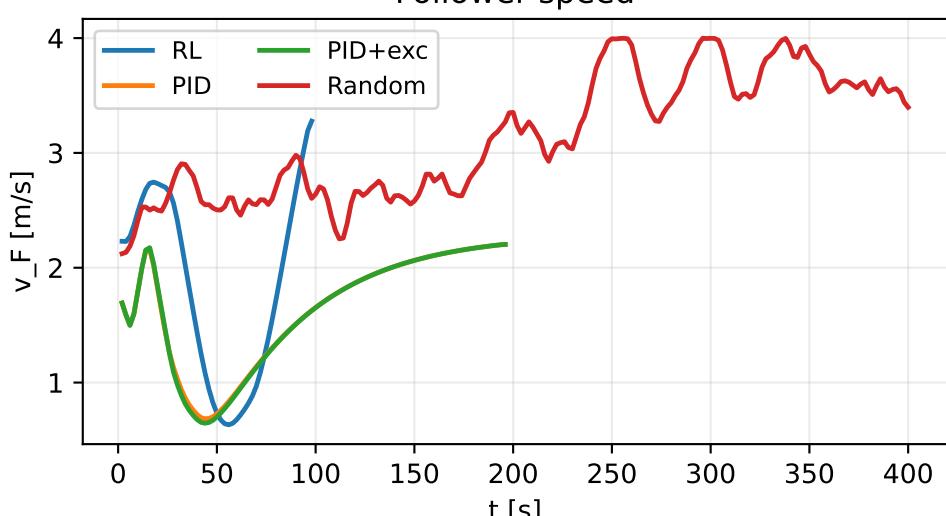
Estimator uncertainty (std_max)



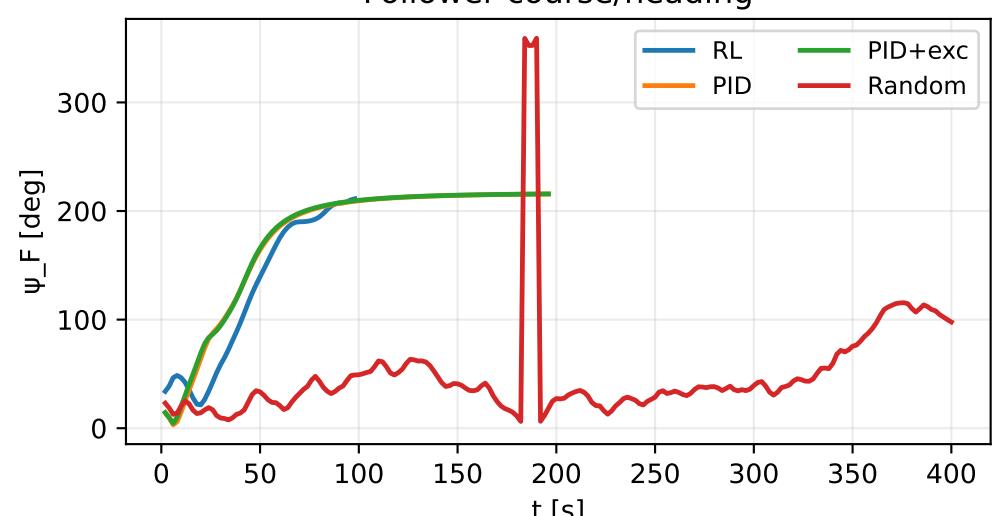
Information and excitation



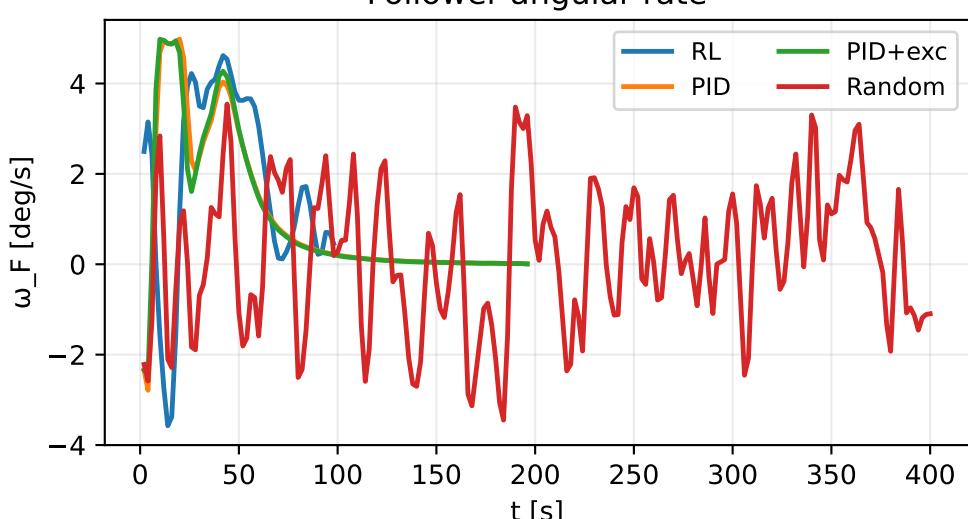
Follower speed



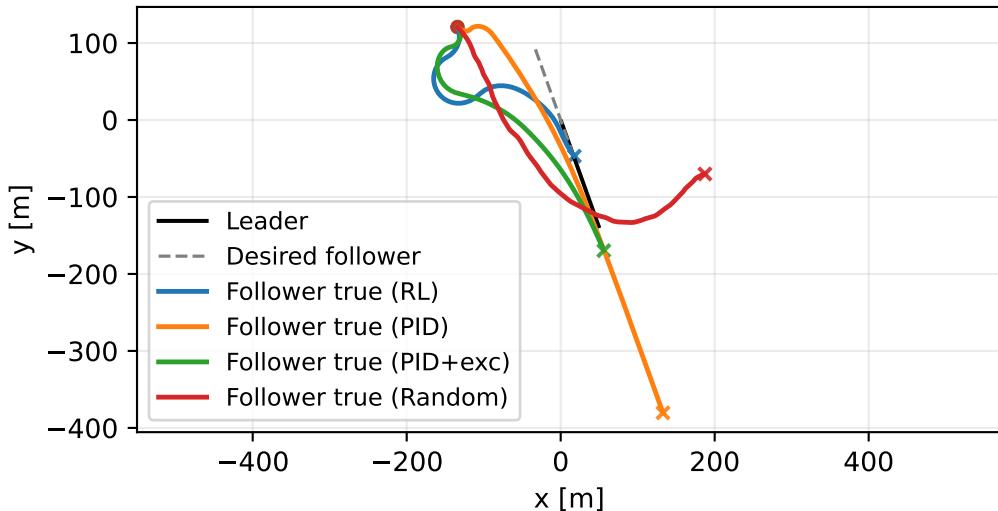
Follower course/heading



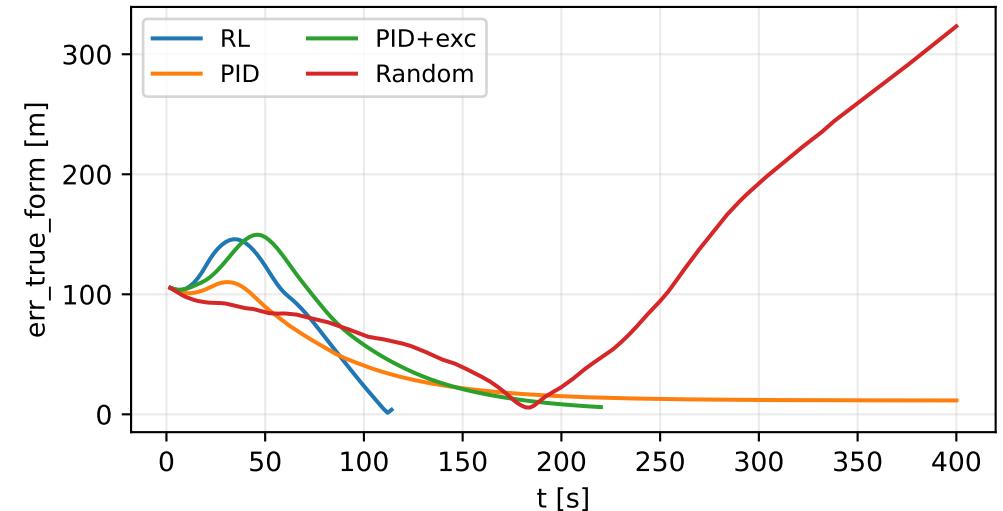
Follower angular rate



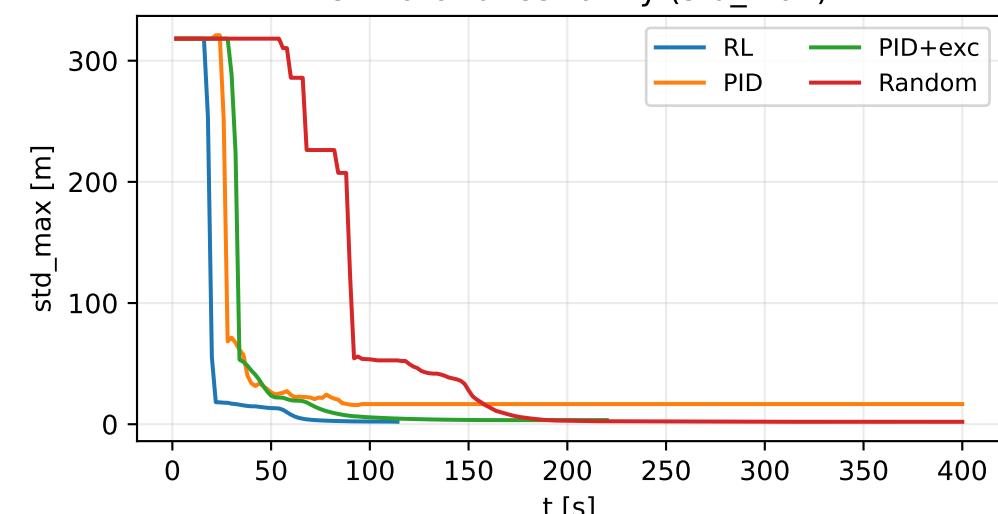
Trajectories (matched seed)



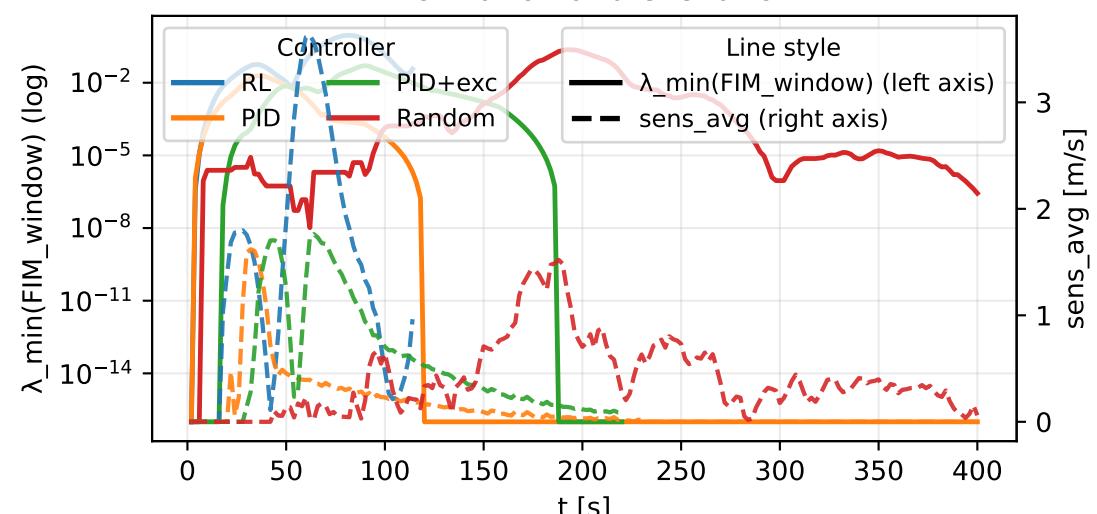
TRUE formation error



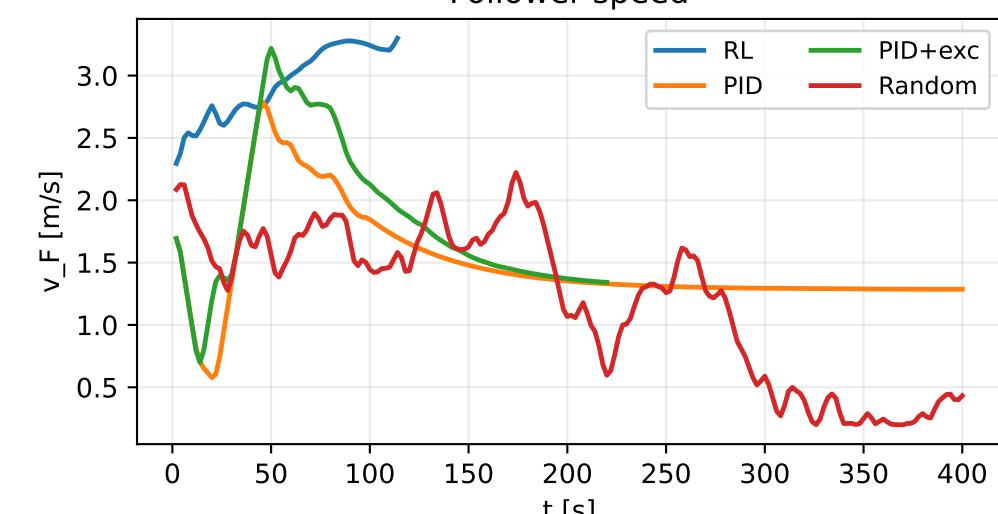
Estimator uncertainty (std_max)



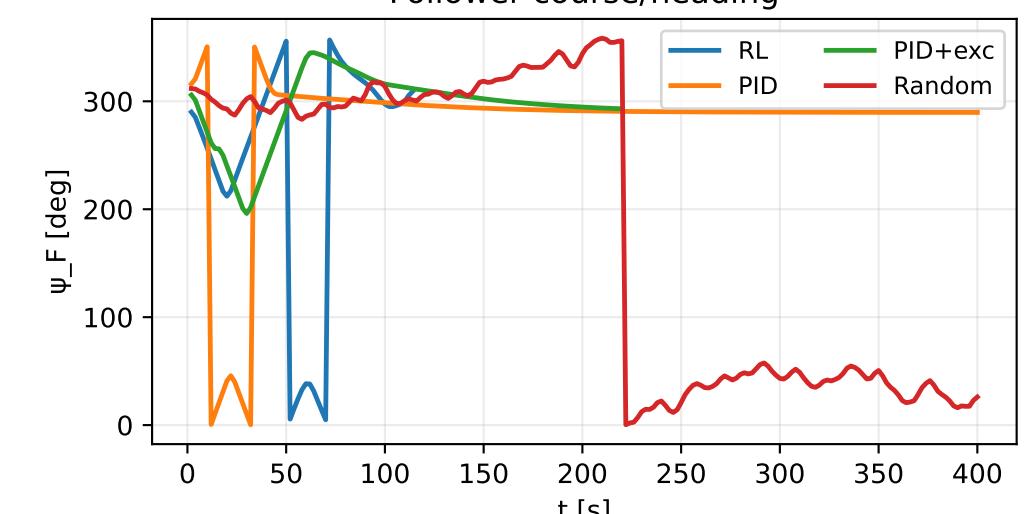
Information and excitation



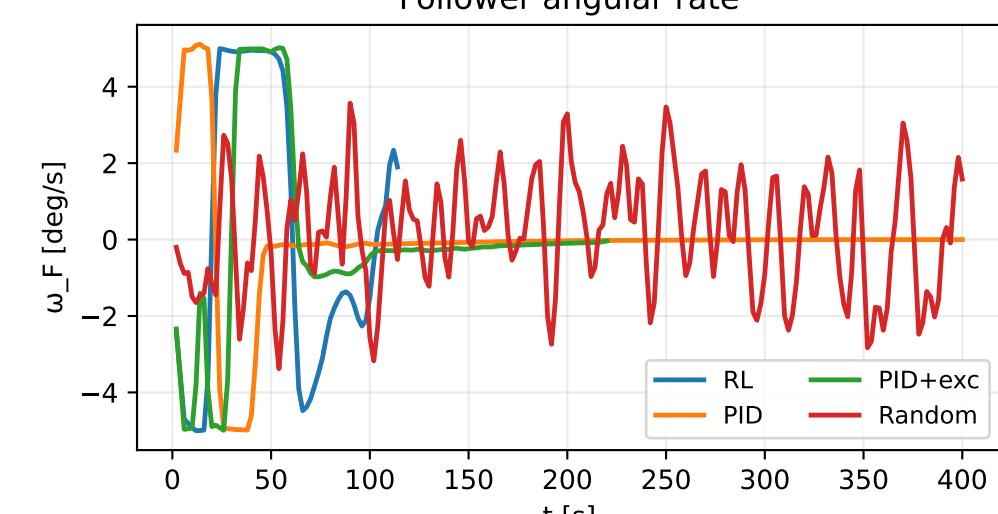
Follower speed



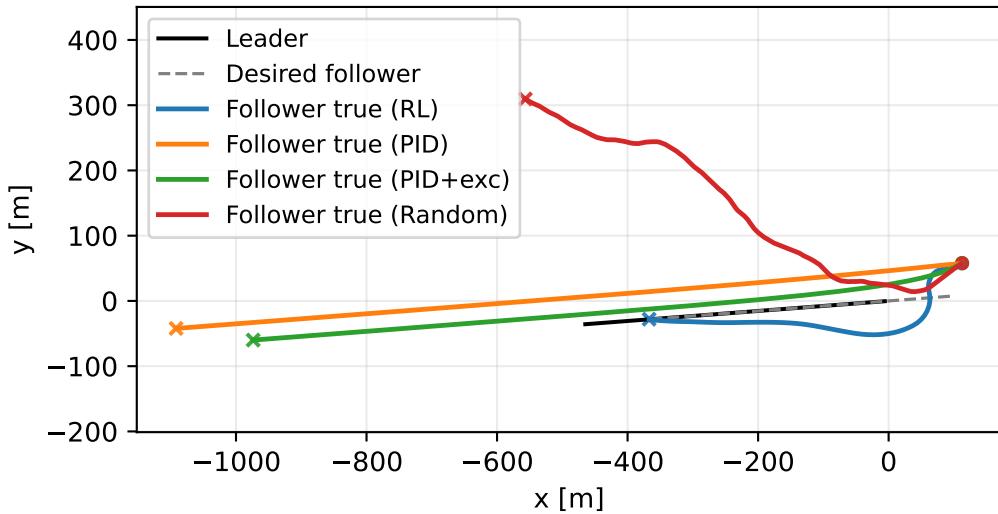
Follower course/heading



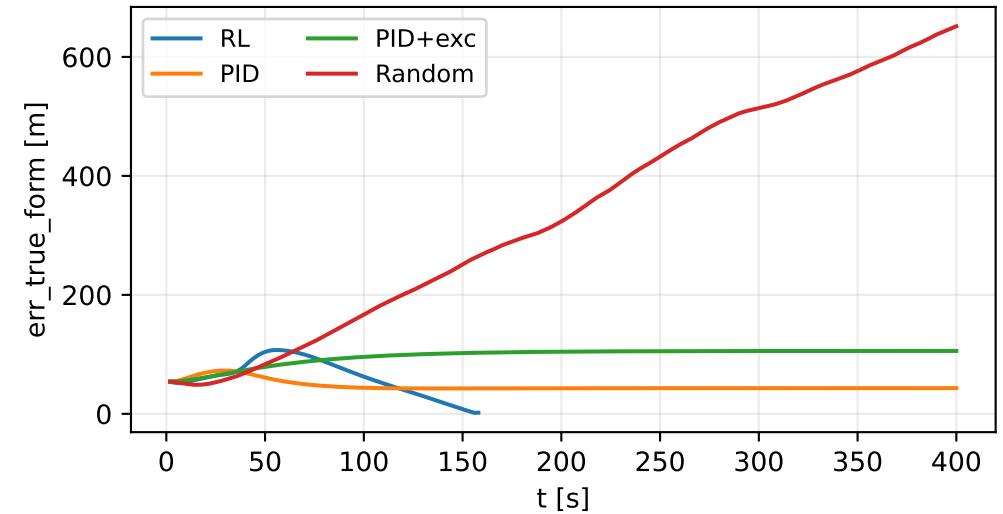
Follower angular rate



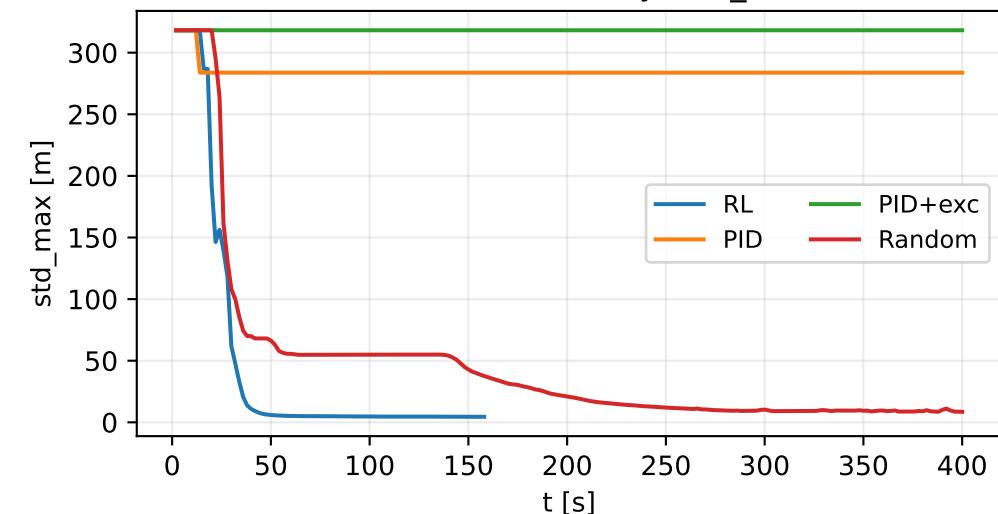
Trajectories (matched seed)



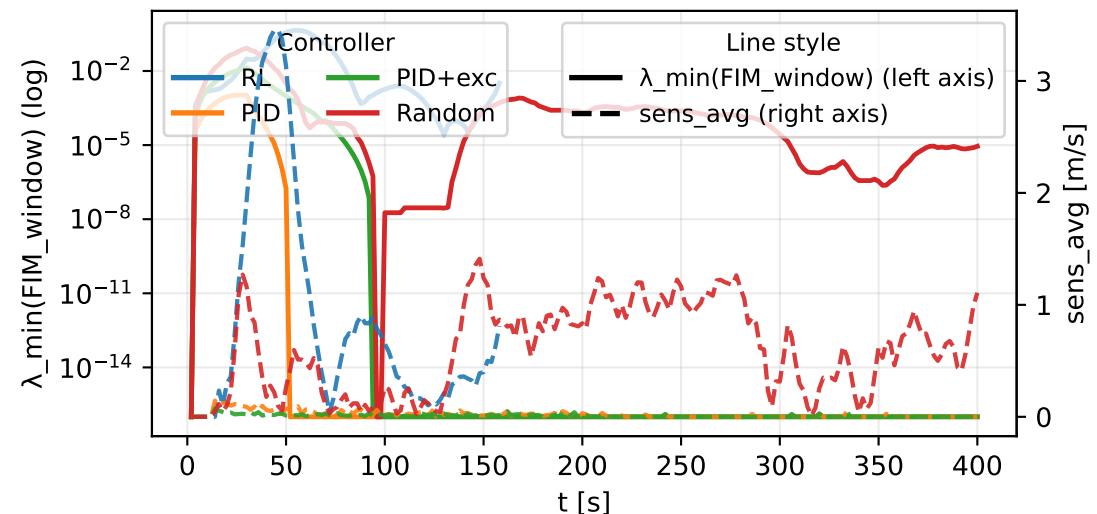
TRUE formation error



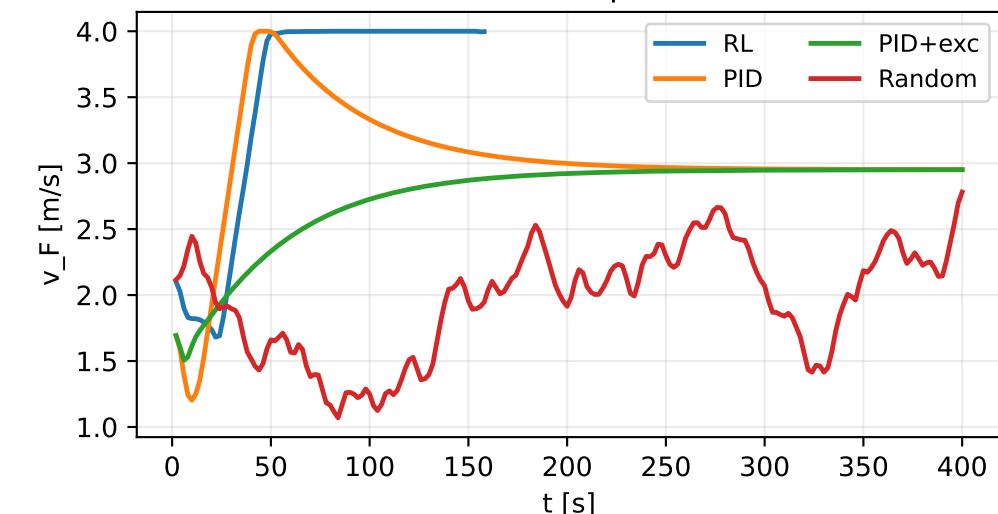
Estimator uncertainty (std_max)



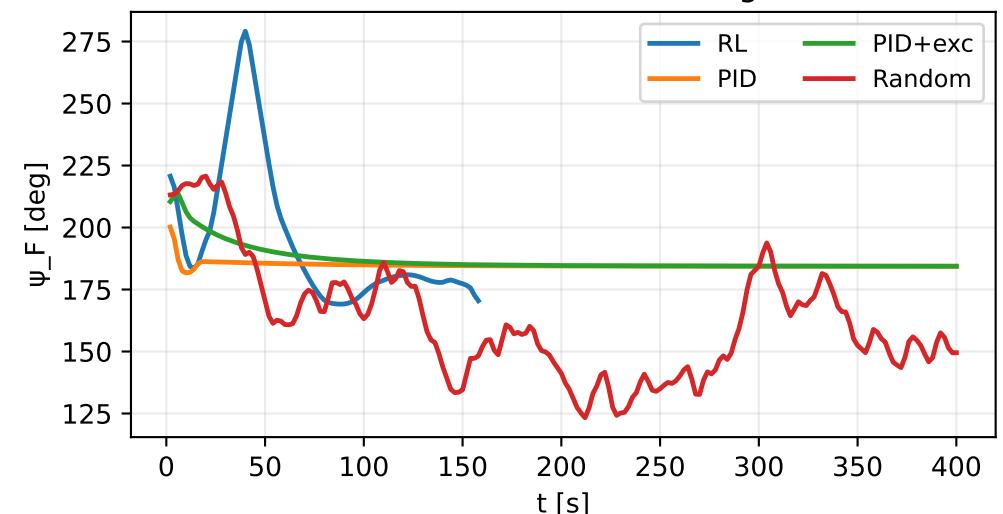
Information and excitation



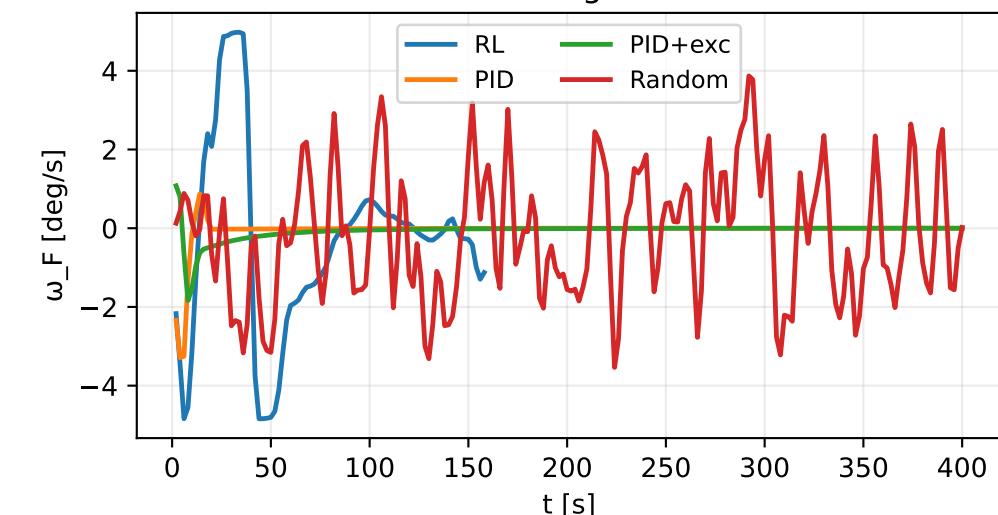
Follower speed



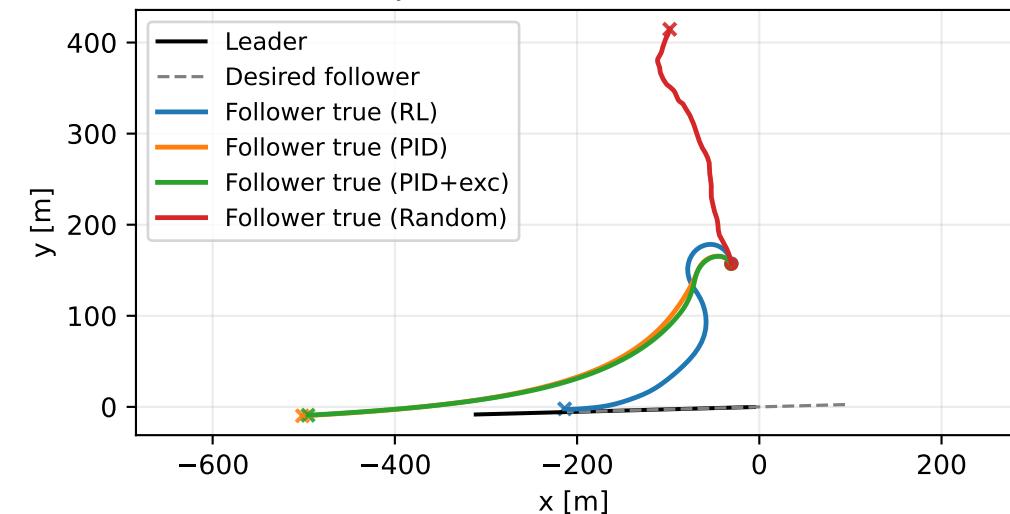
Follower course/heading



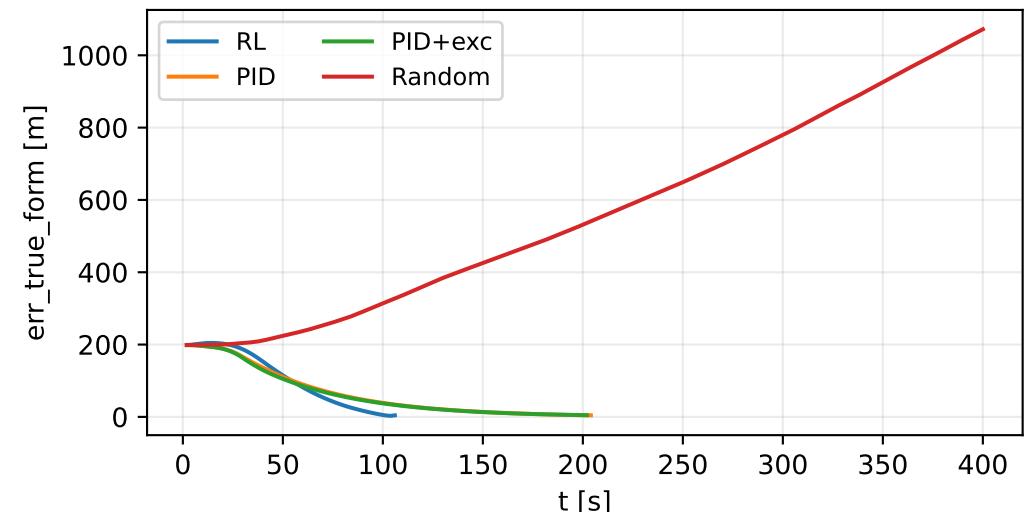
Follower angular rate



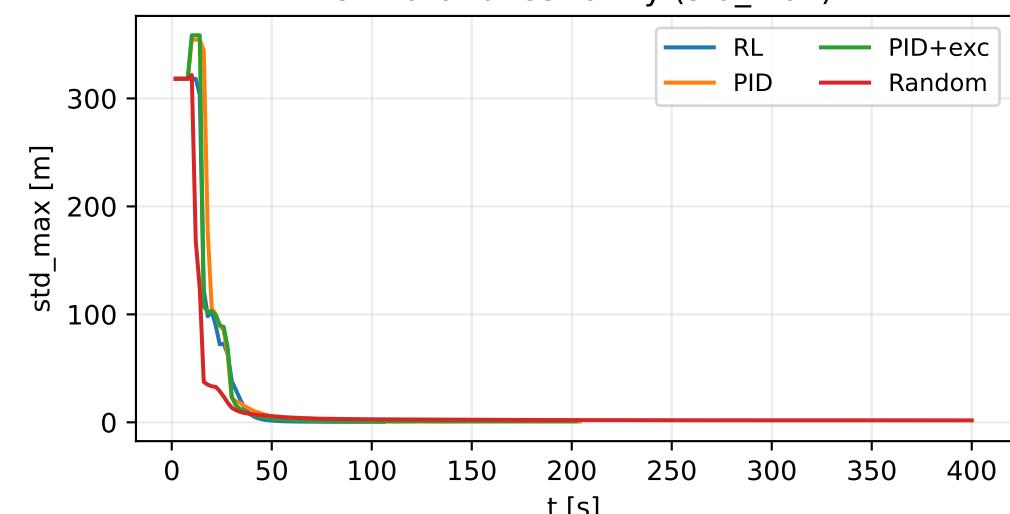
Trajectories (matched seed)



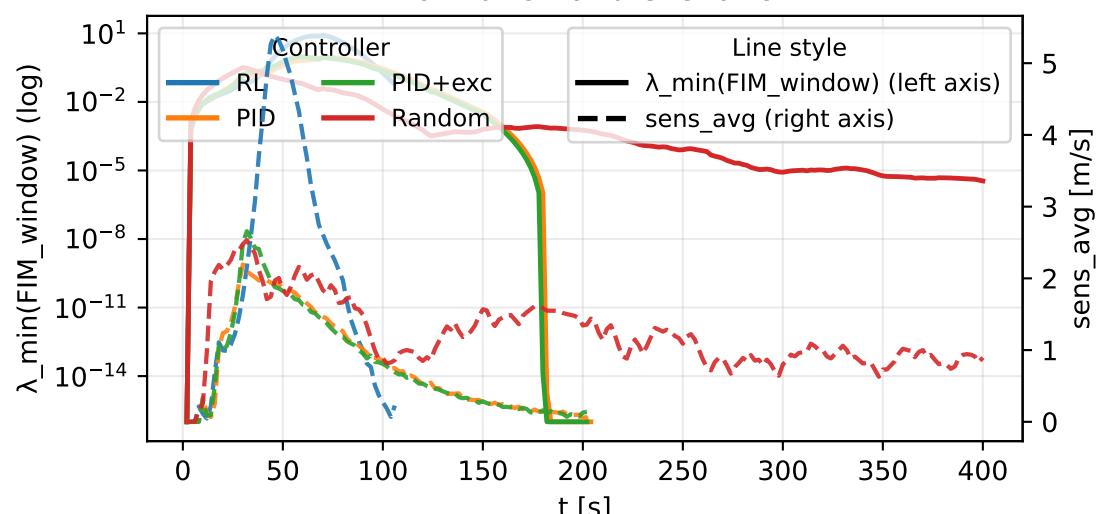
TRUE formation error



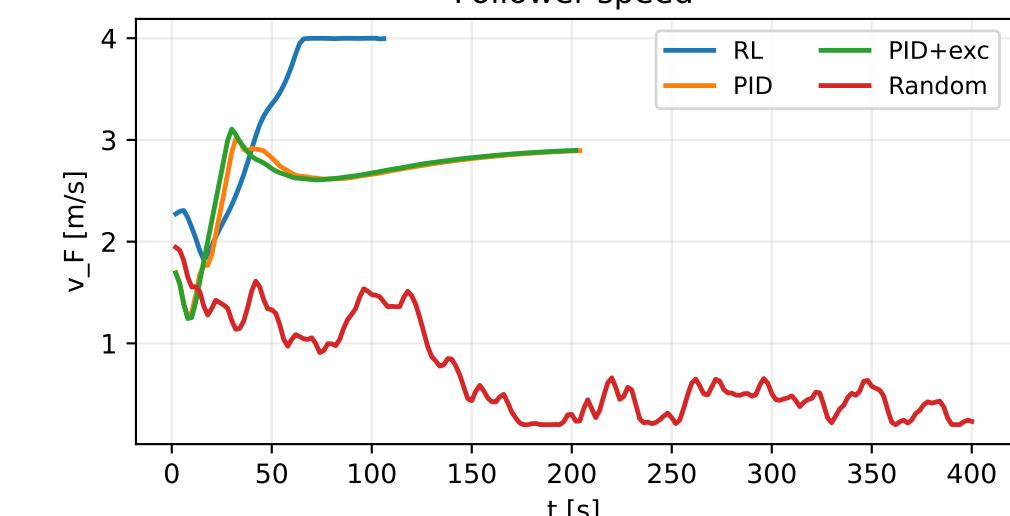
Estimator uncertainty (std_max)



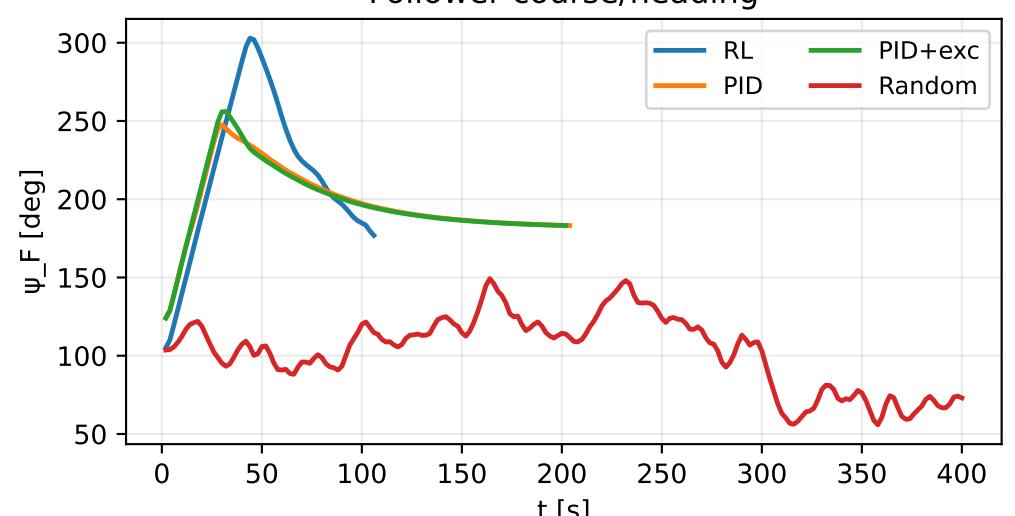
Information and excitation



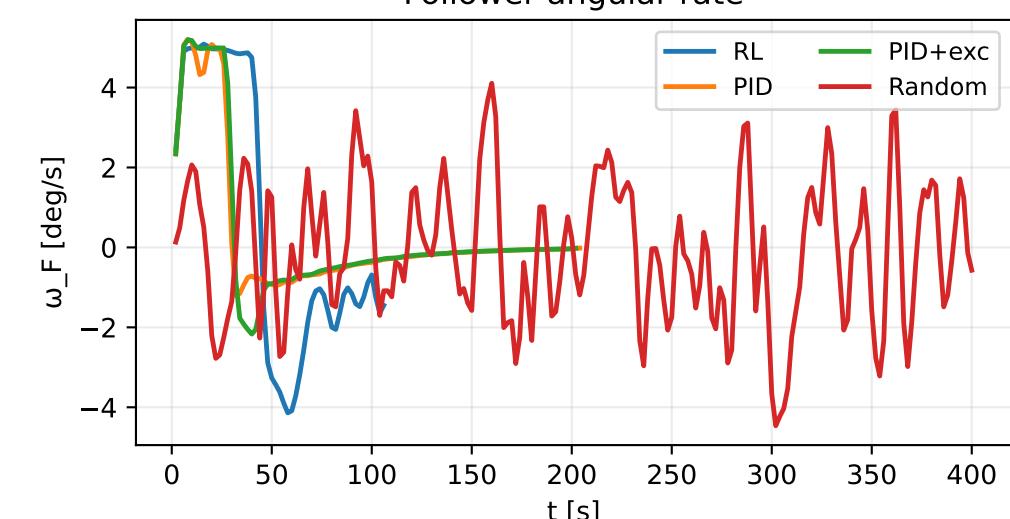
Follower speed



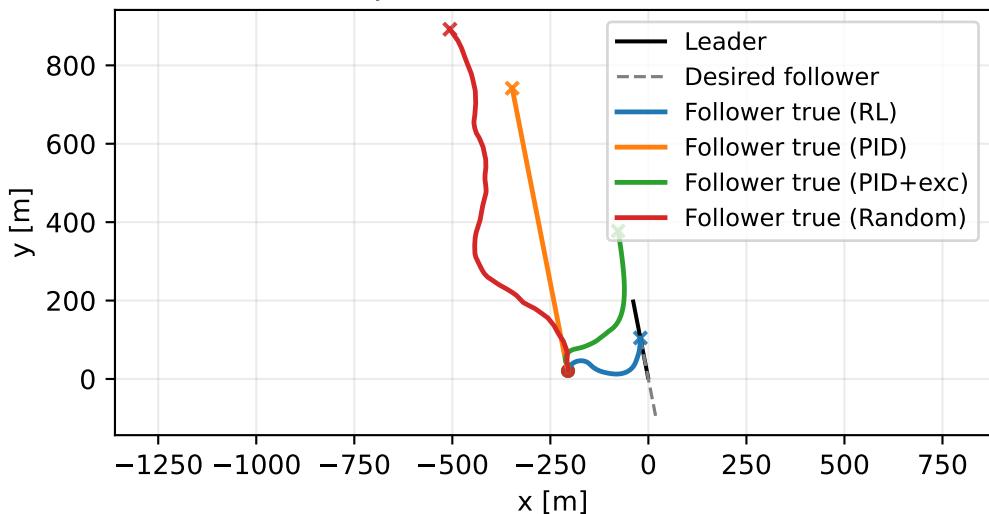
Follower course/heading



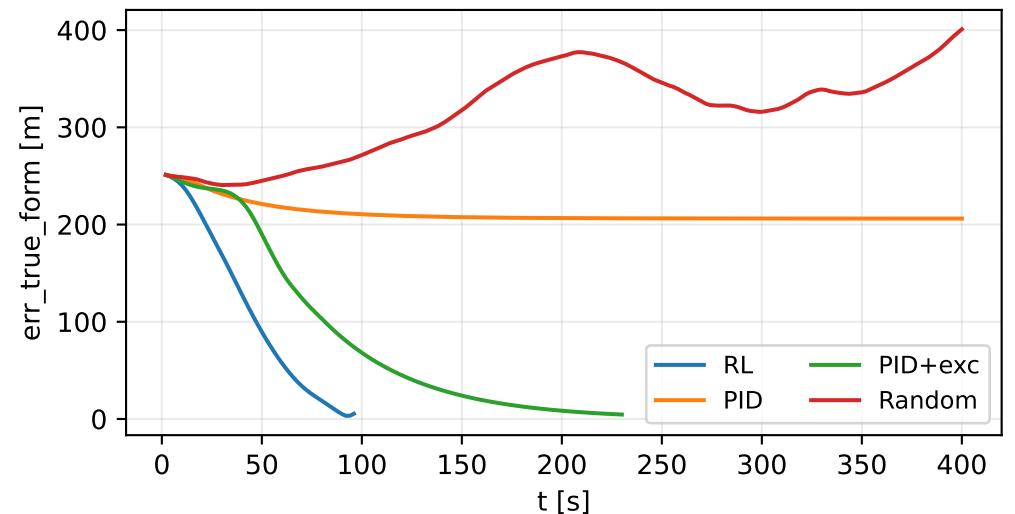
Follower angular rate



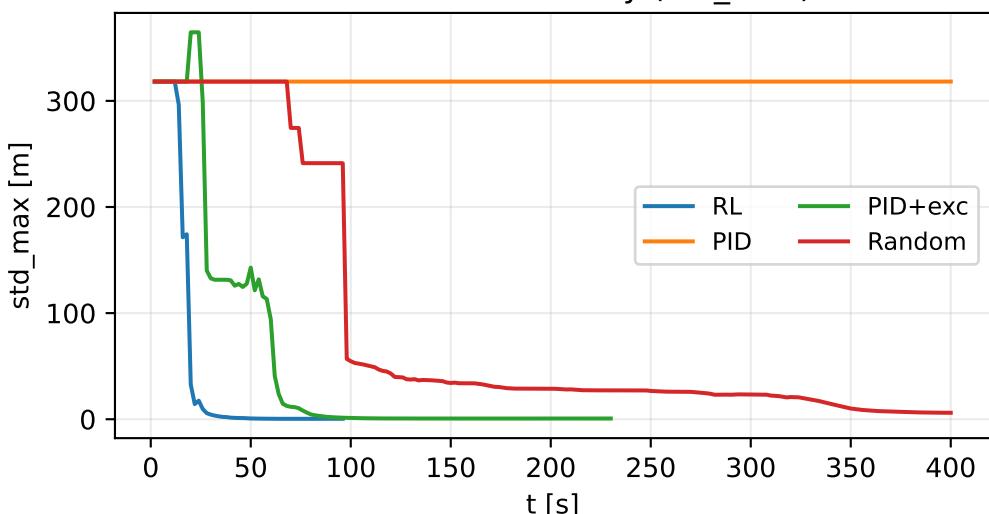
Trajectories (matched seed)



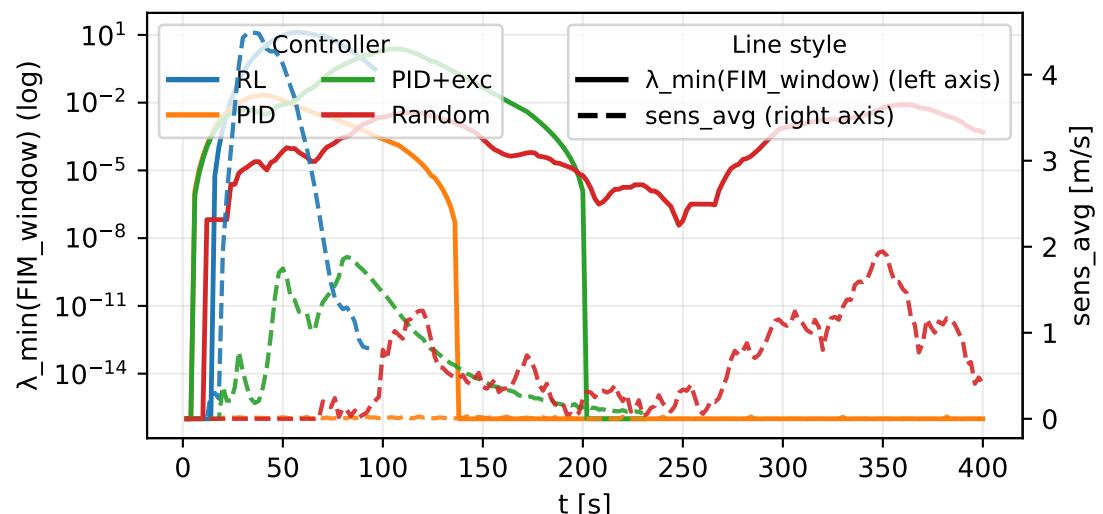
TRUE formation error



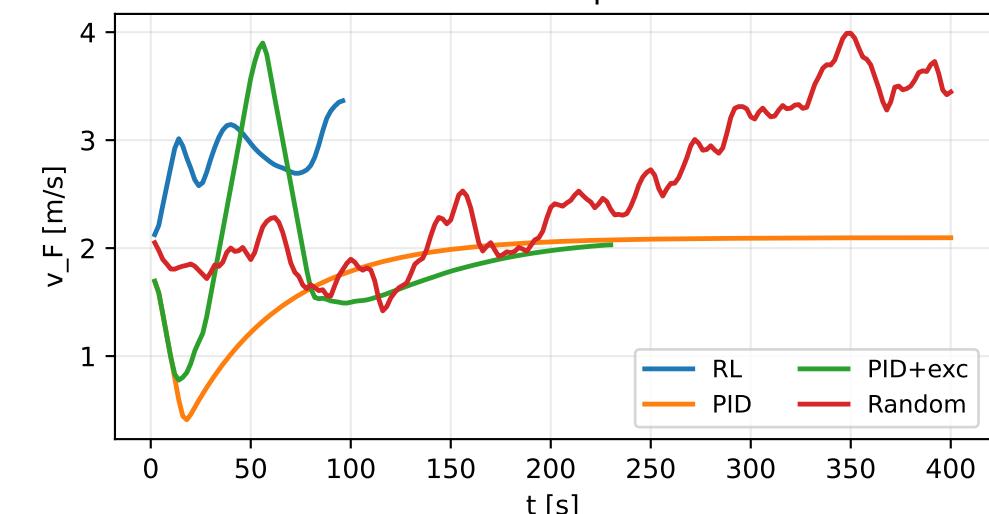
Estimator uncertainty (std_max)



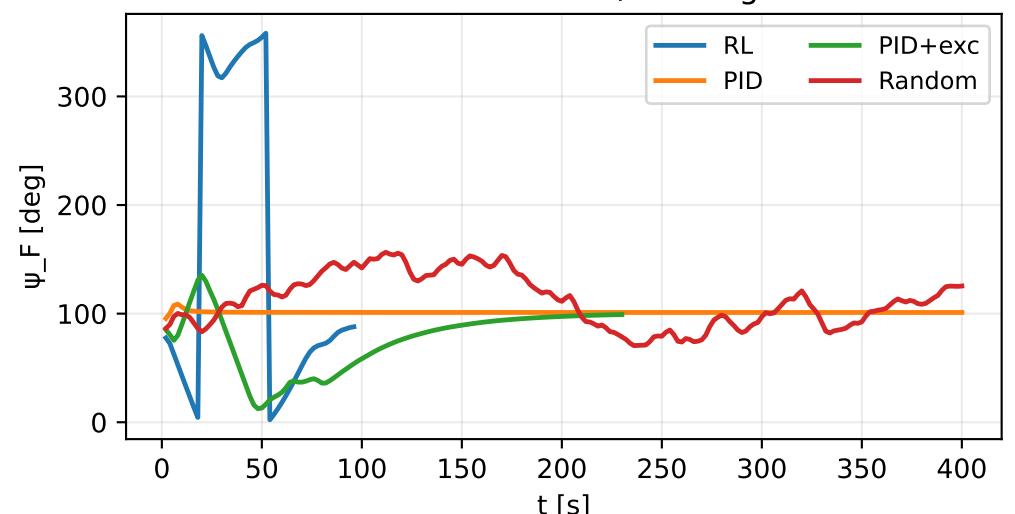
Information and excitation



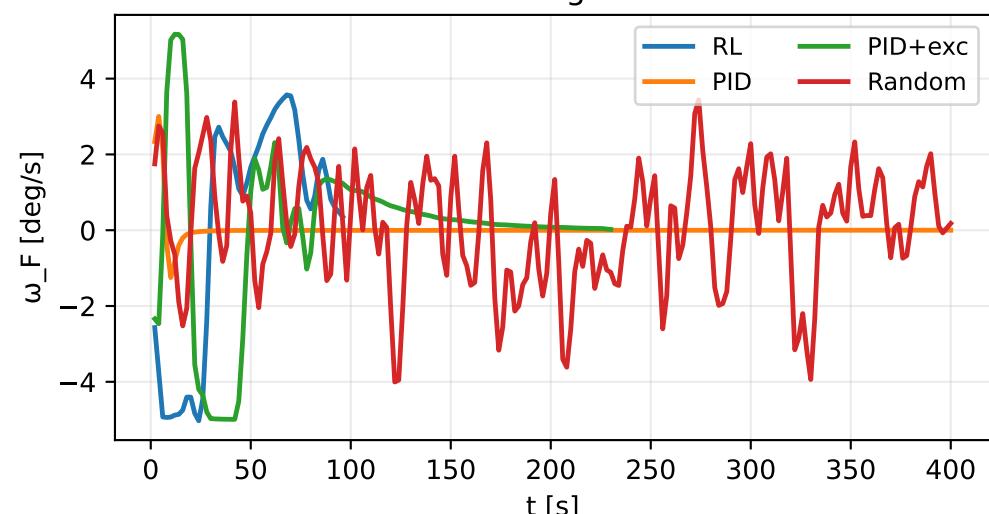
Follower speed



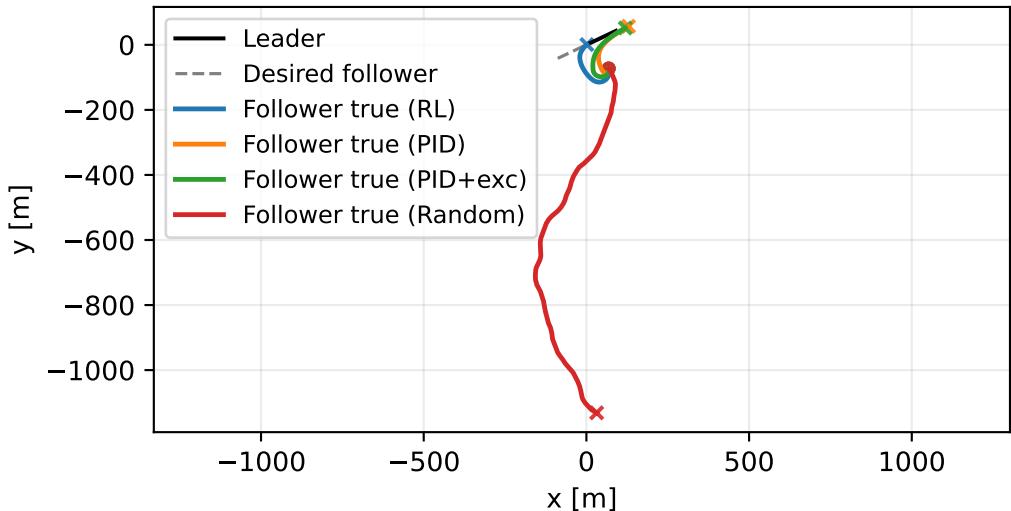
Follower course/heading



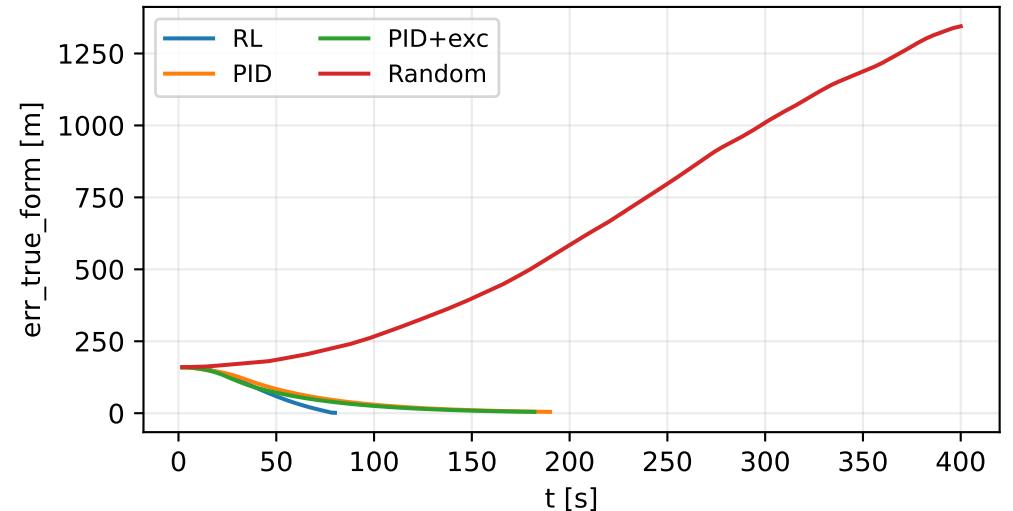
Follower angular rate



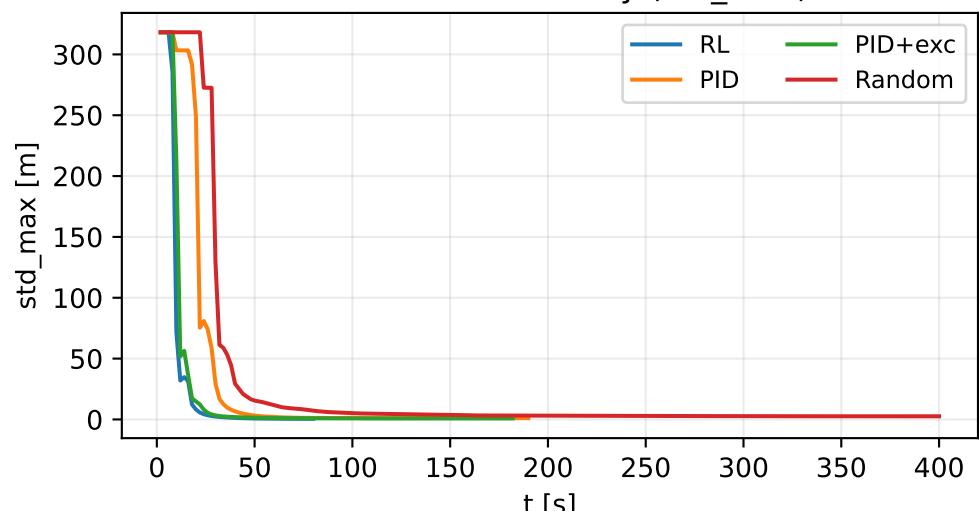
Trajectories (matched seed)



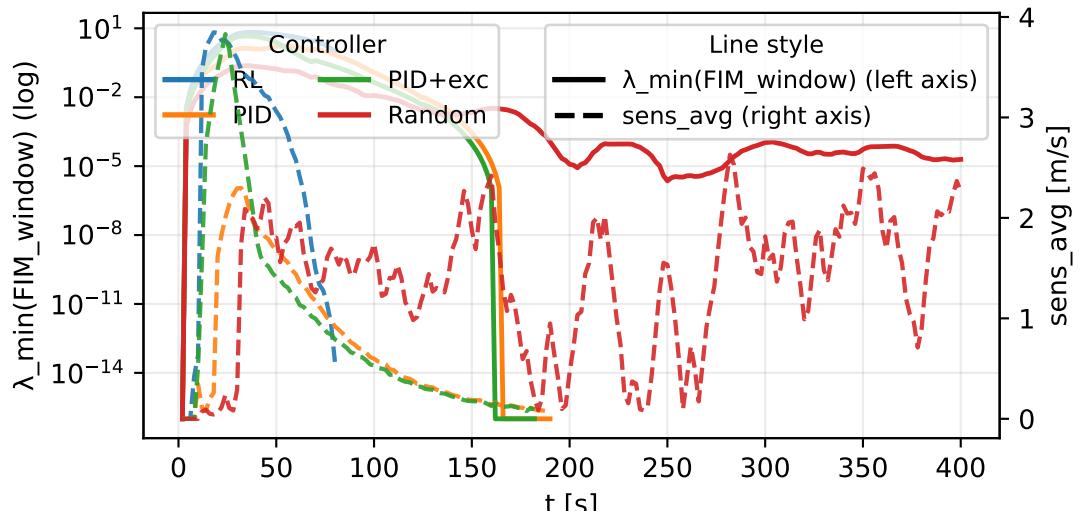
TRUE formation error



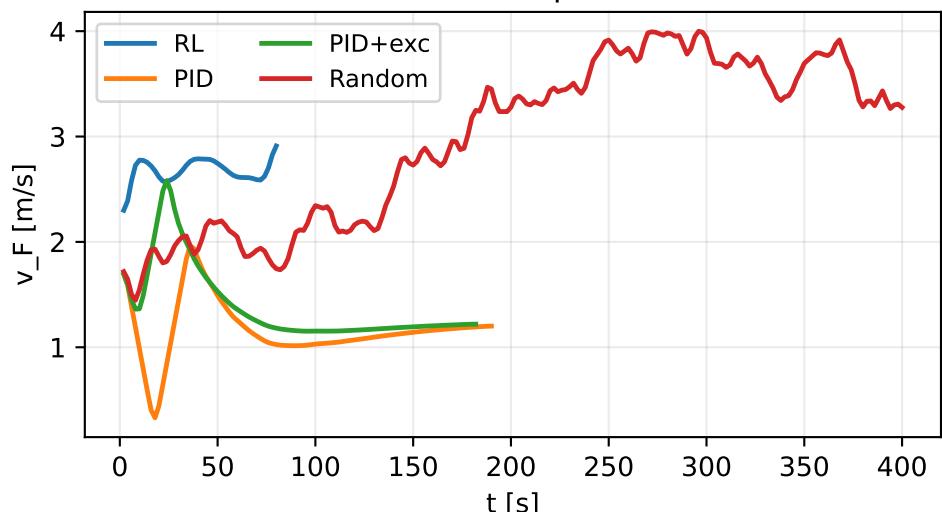
Estimator uncertainty (std_max)



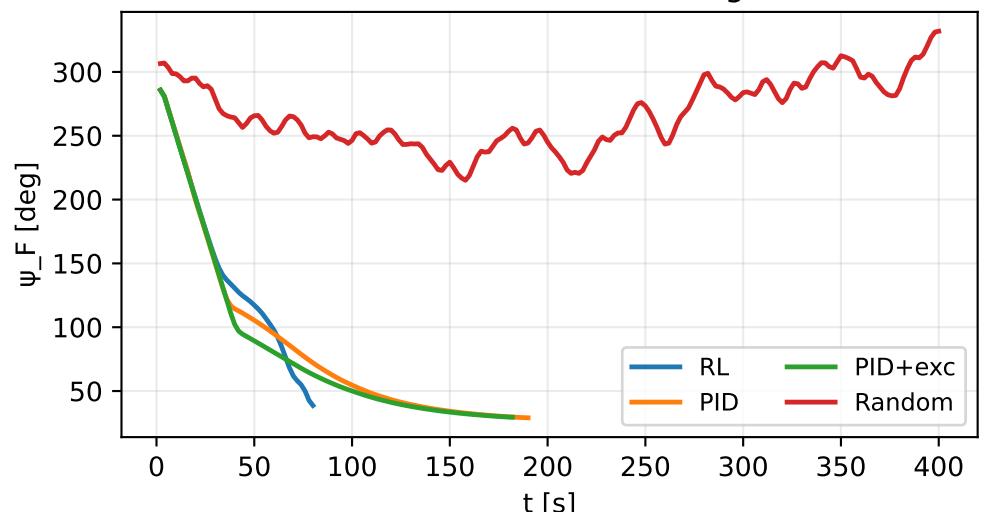
Information and excitation



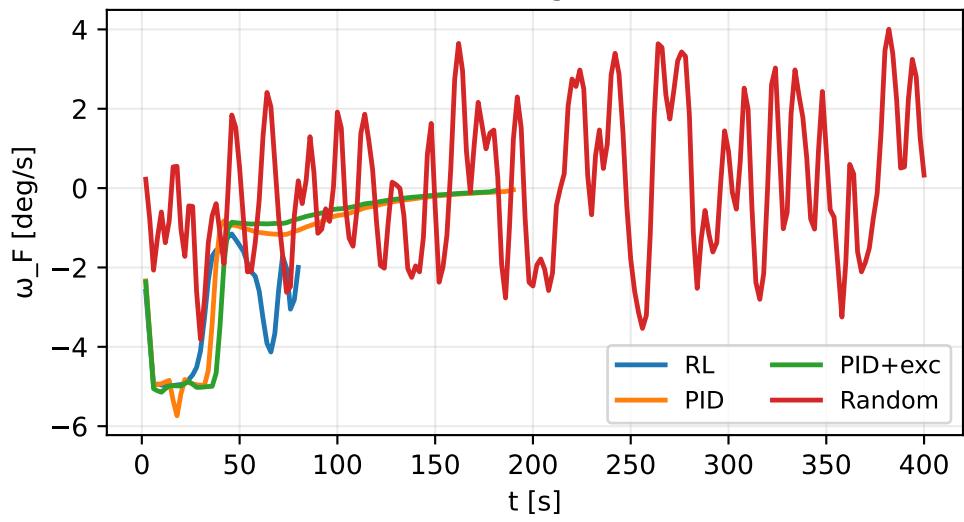
Follower speed



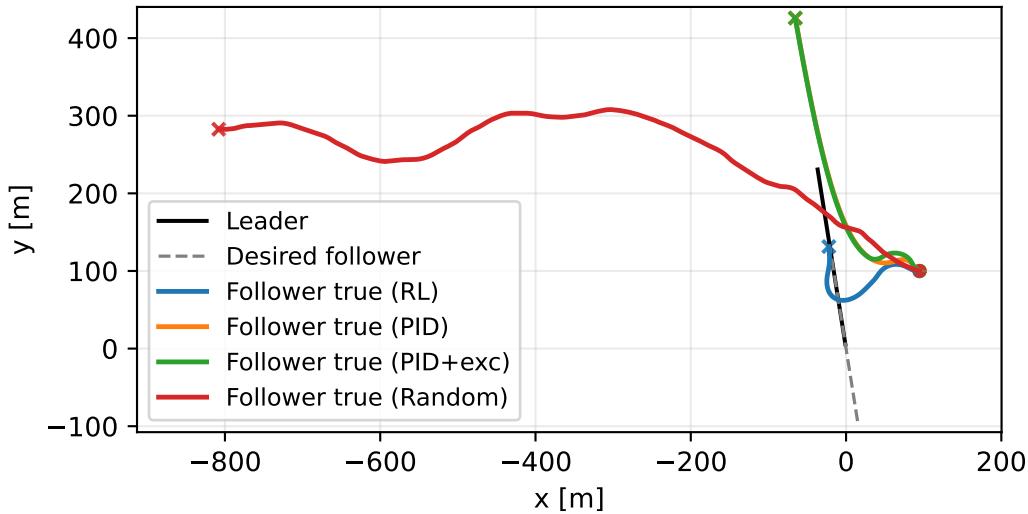
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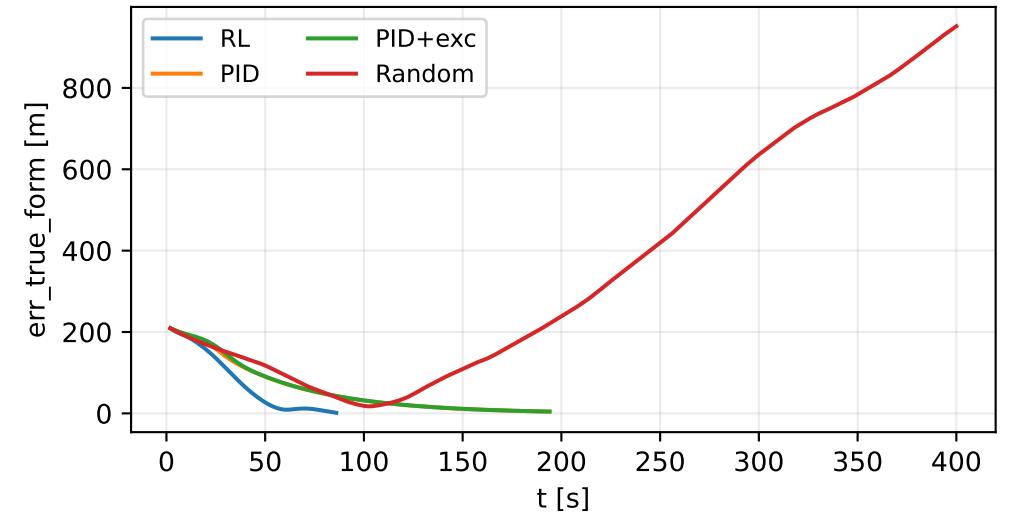
Follower angular rate



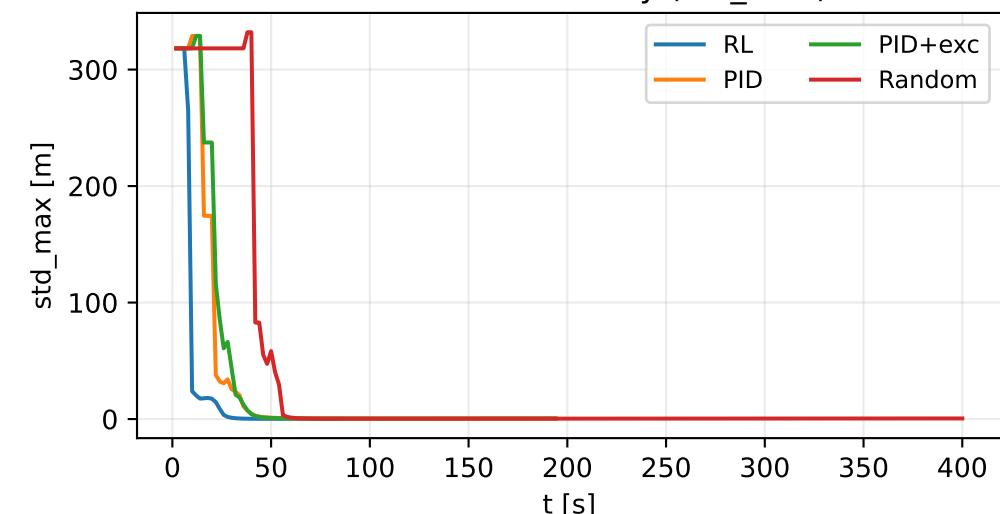
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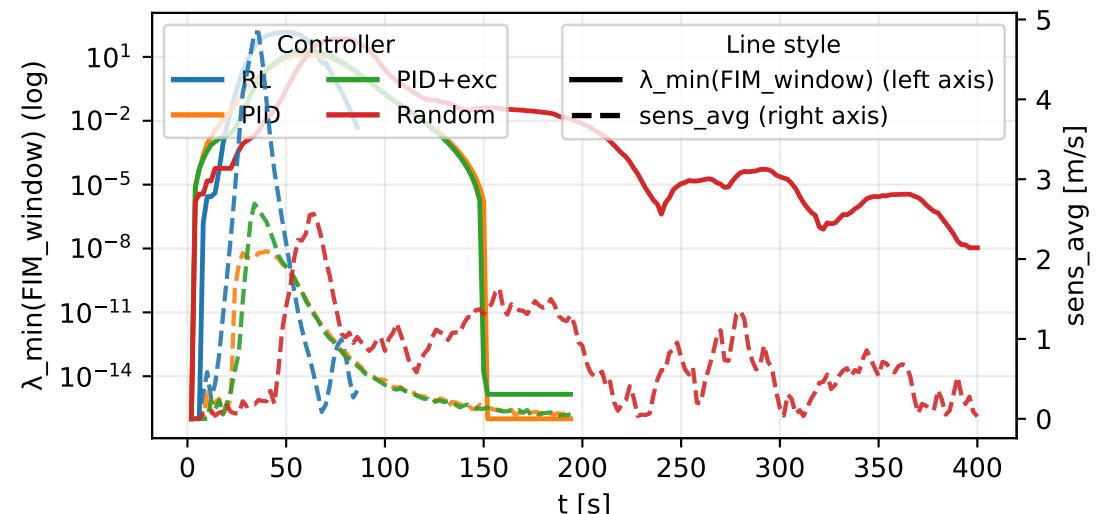
TRUE formation error



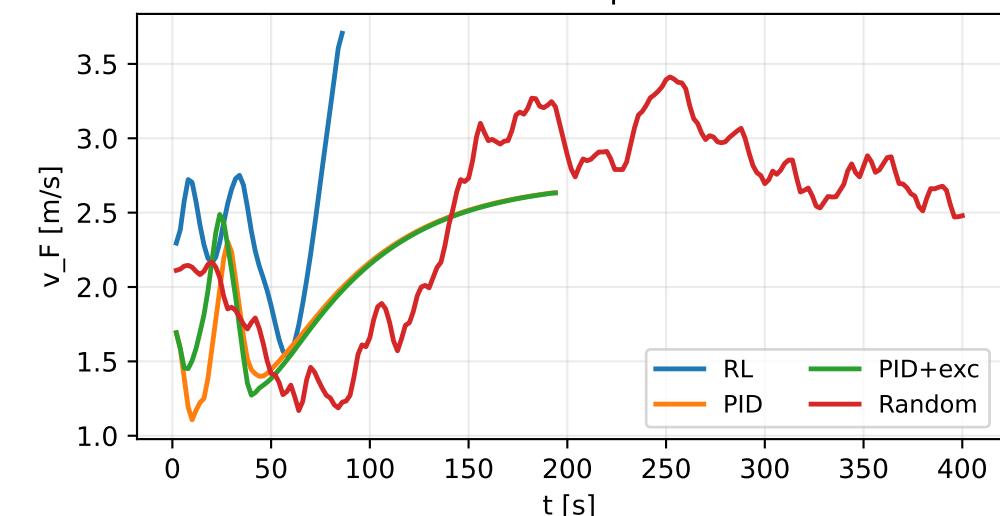
Estimator uncertainty (std_max)



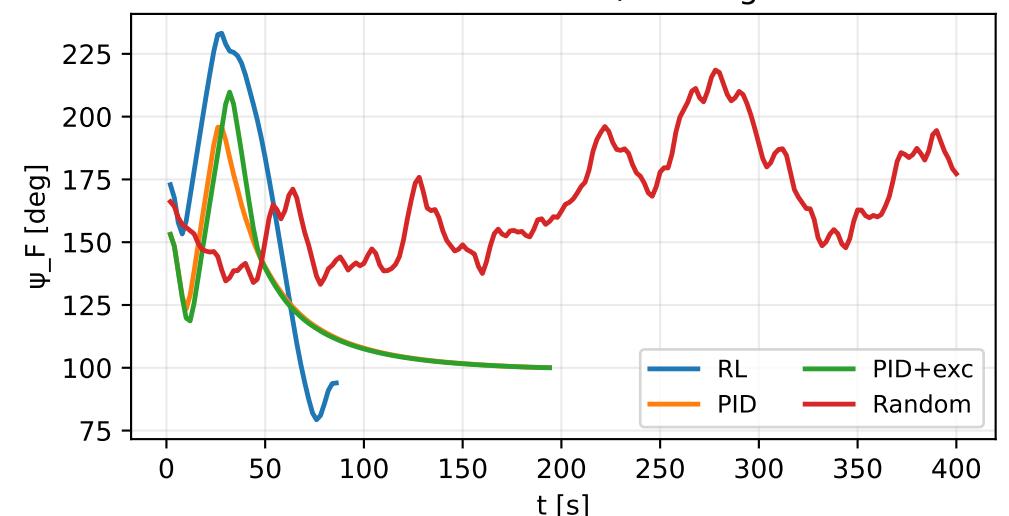
Information and excitation



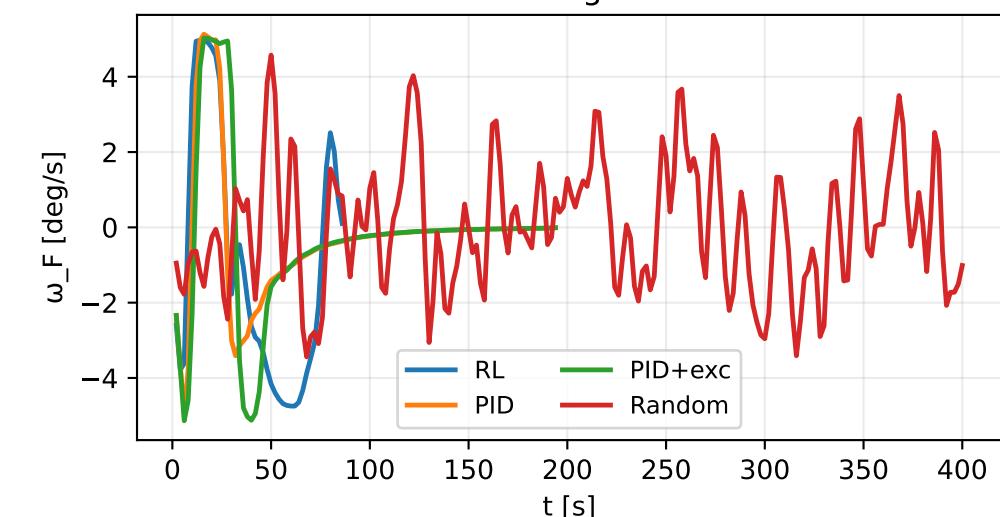
Follower speed



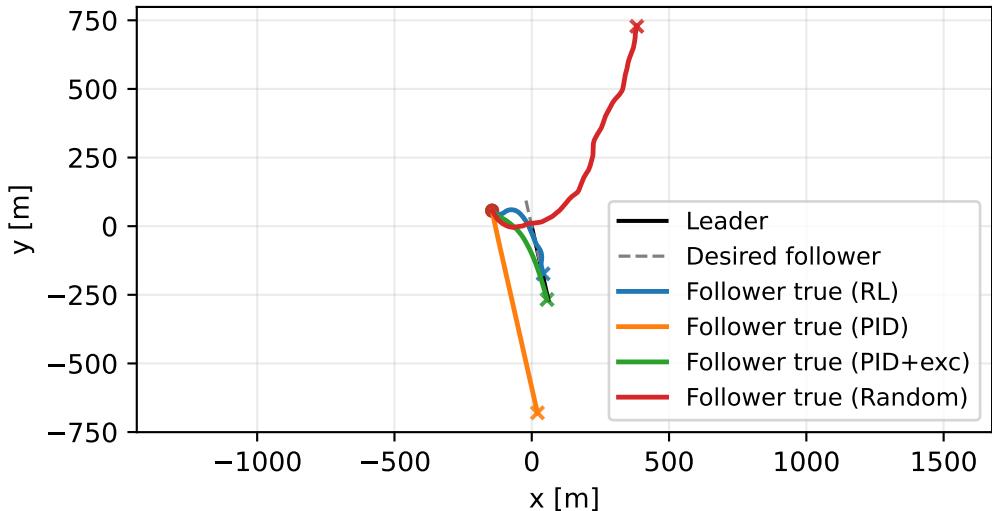
Follower course/heading



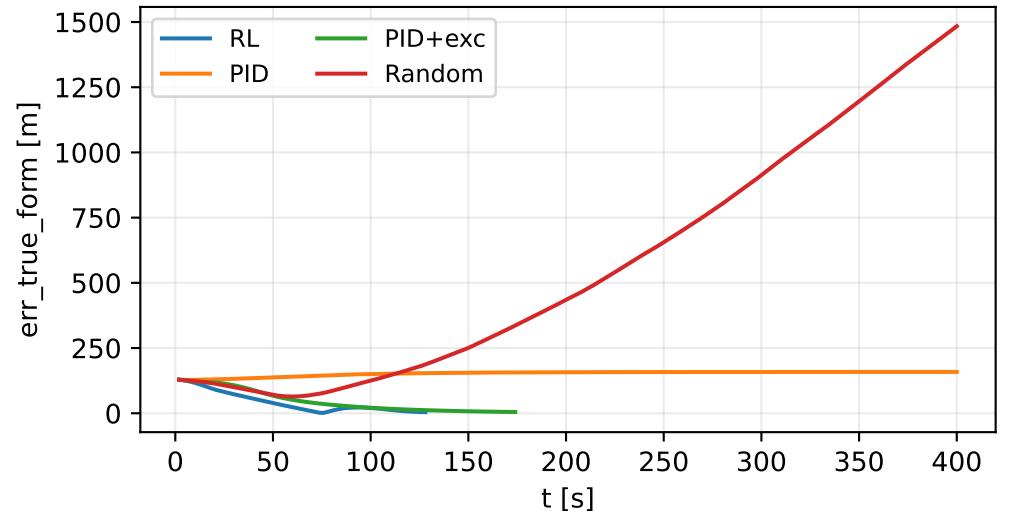
Follower angular rate



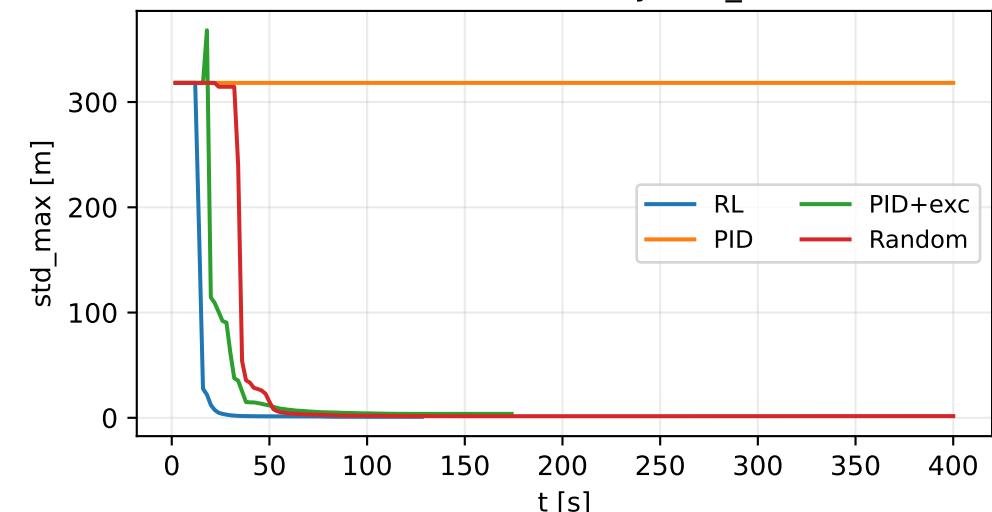
Trajectories (matched seed)



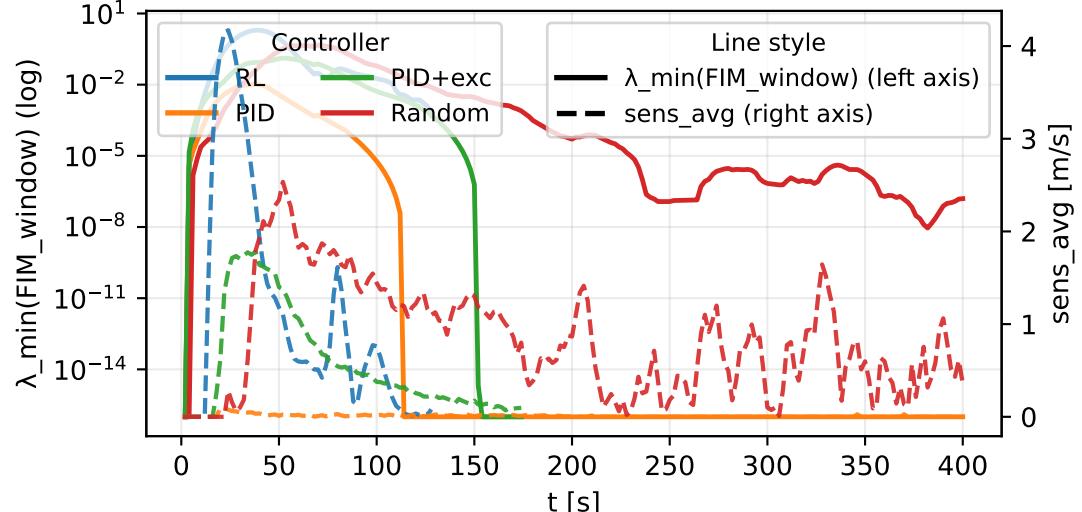
TRUE formation error



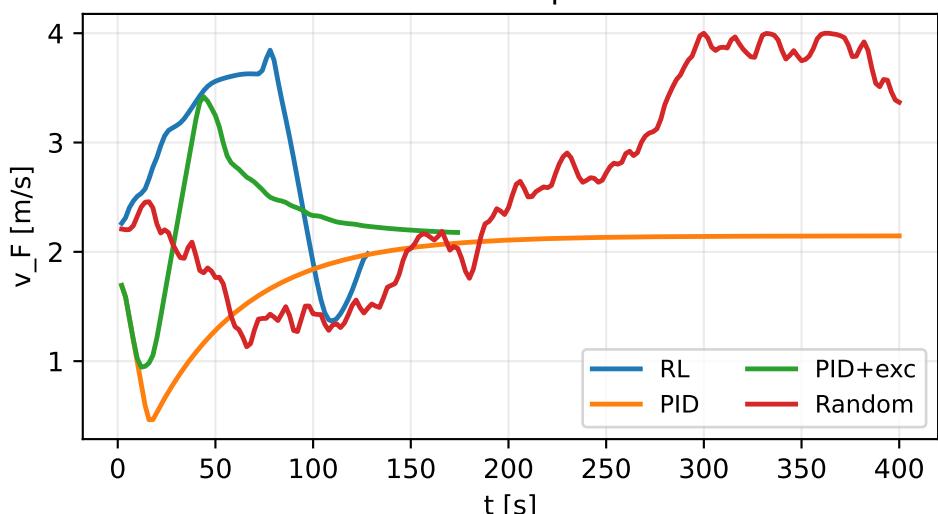
Estimator uncertainty (std_max)



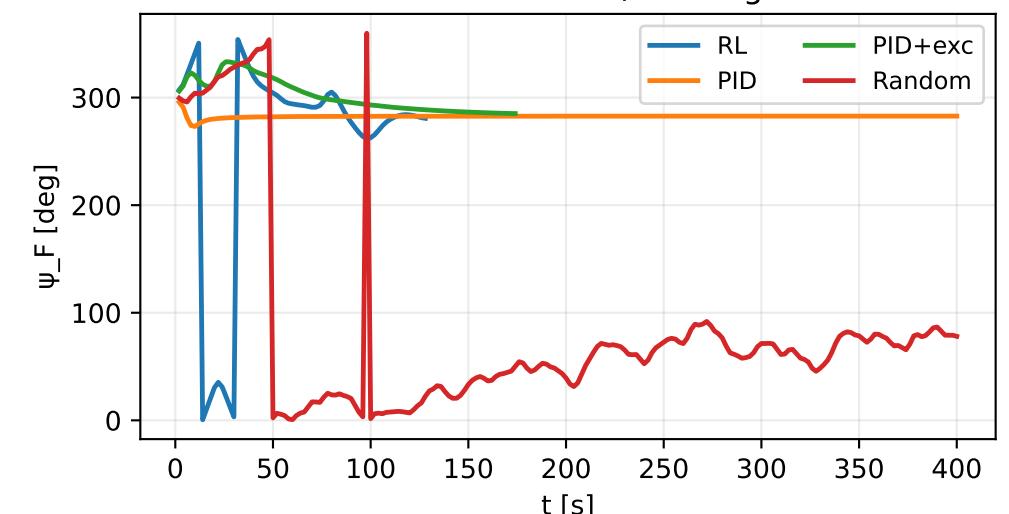
Information and excitation



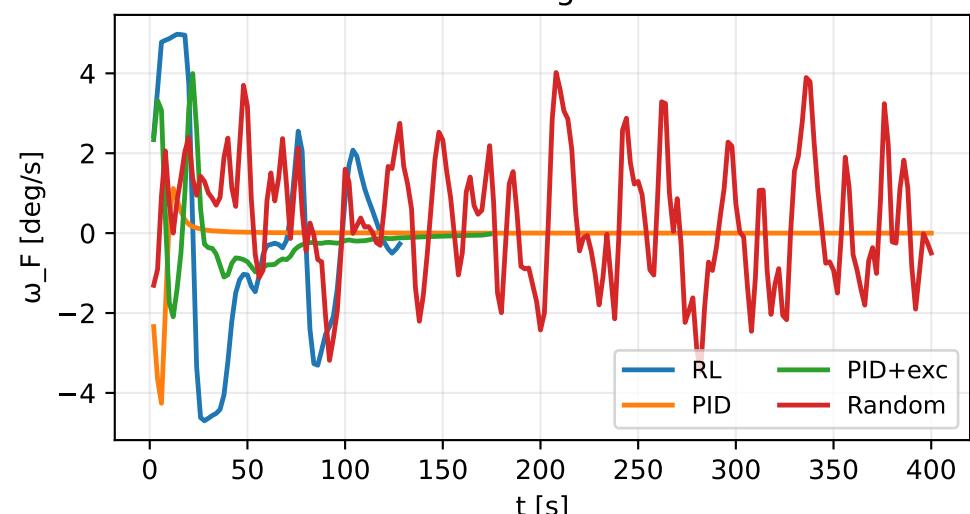
Follower speed



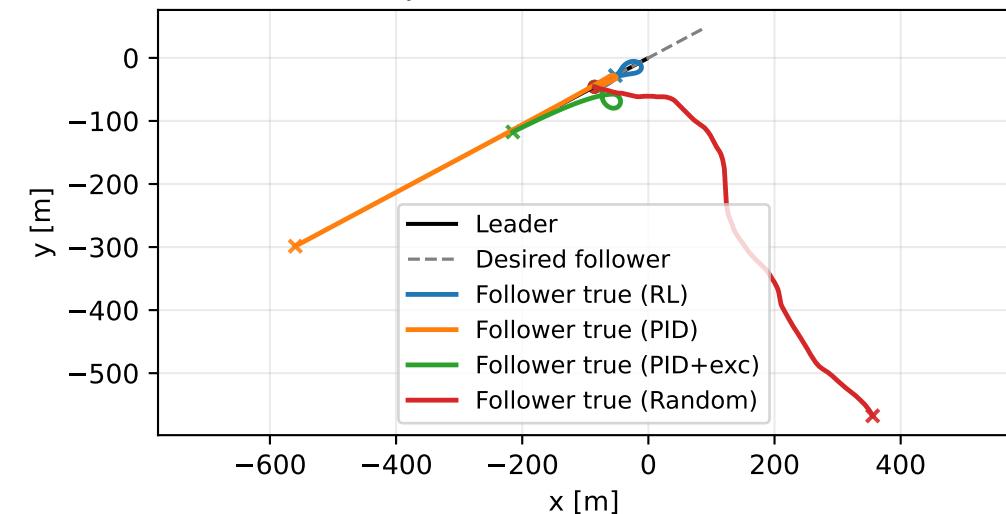
Follower course/heading



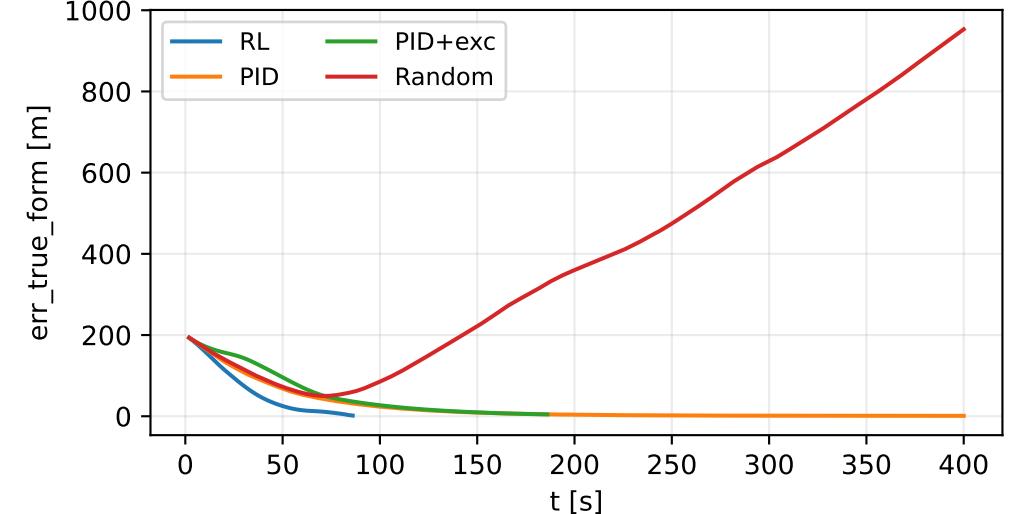
Follower angular rate



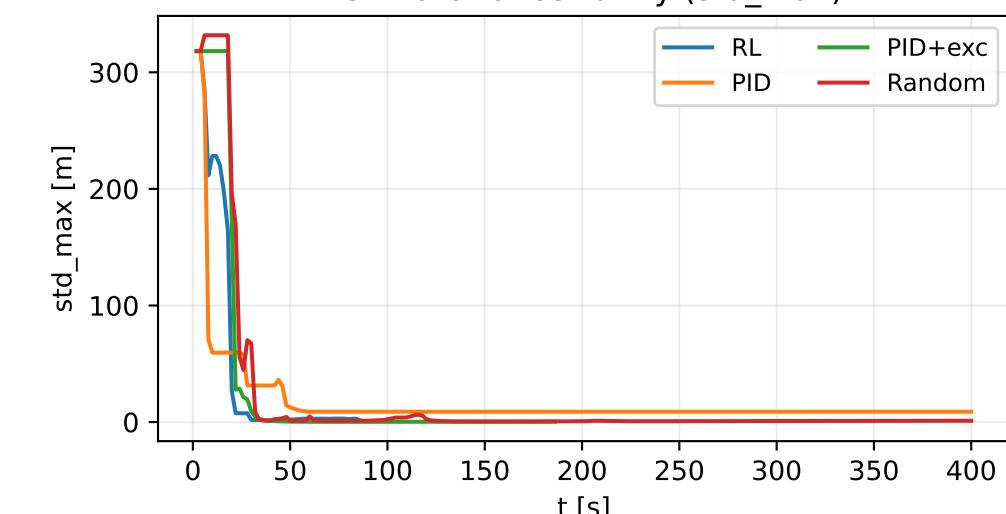
Trajectories (matched seed)



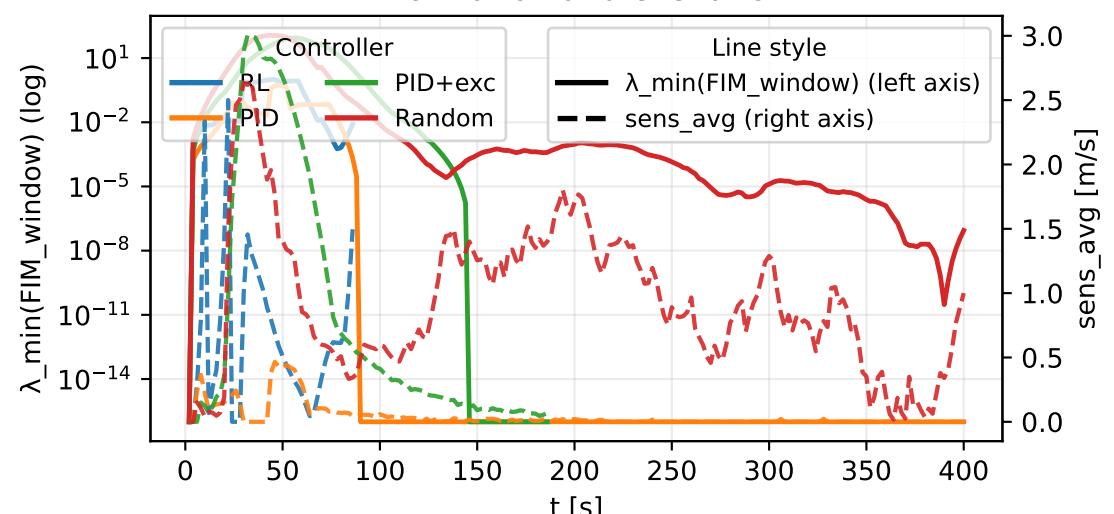
TRUE formation error



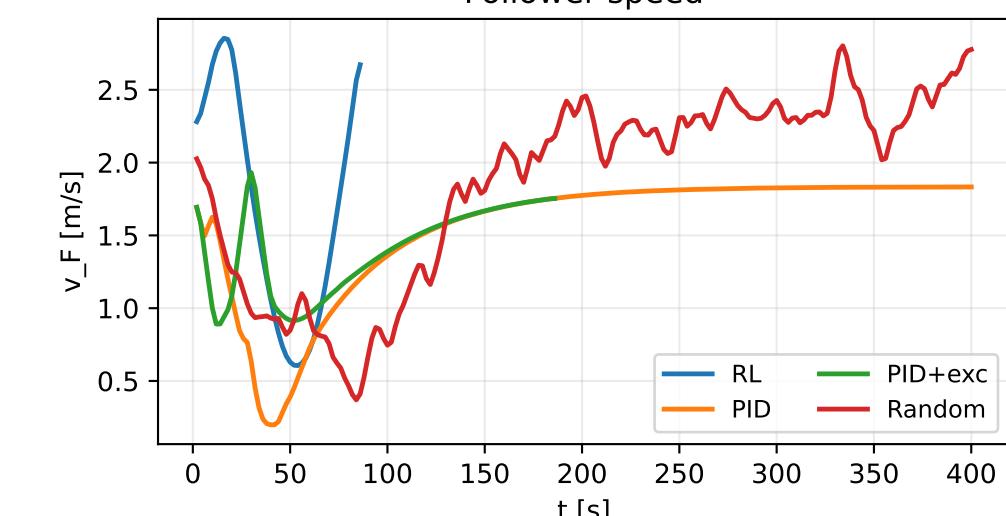
Estimator uncertainty (std_max)



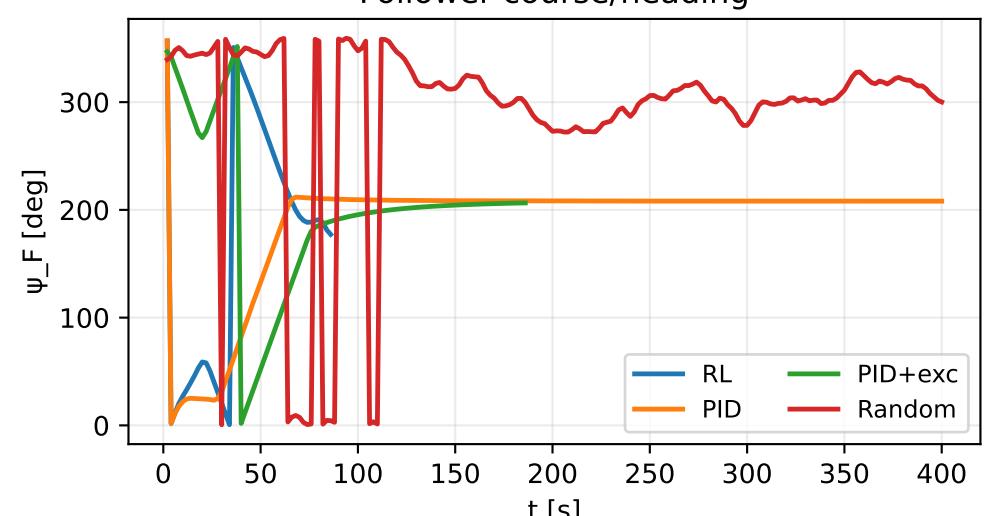
Information and excitation



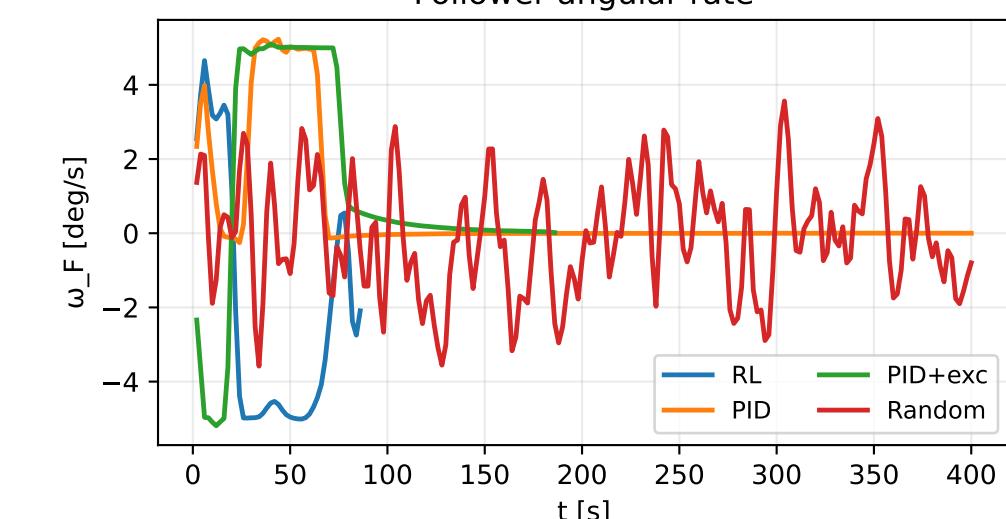
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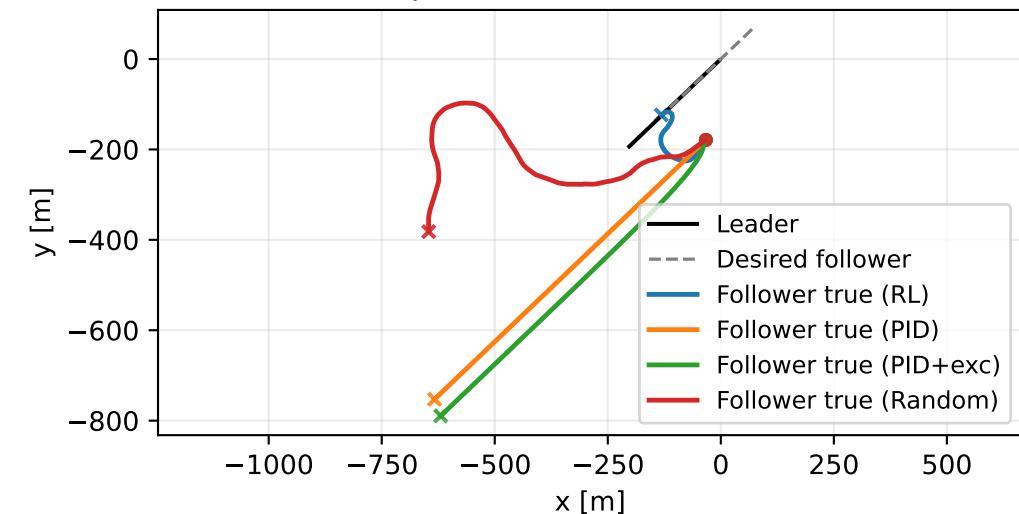
Follower course/heading



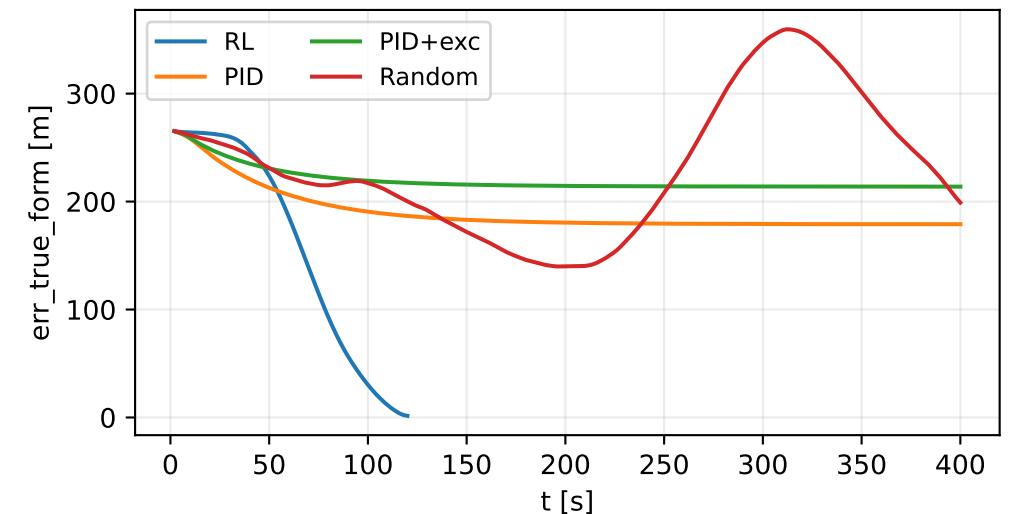
Follower angular rate



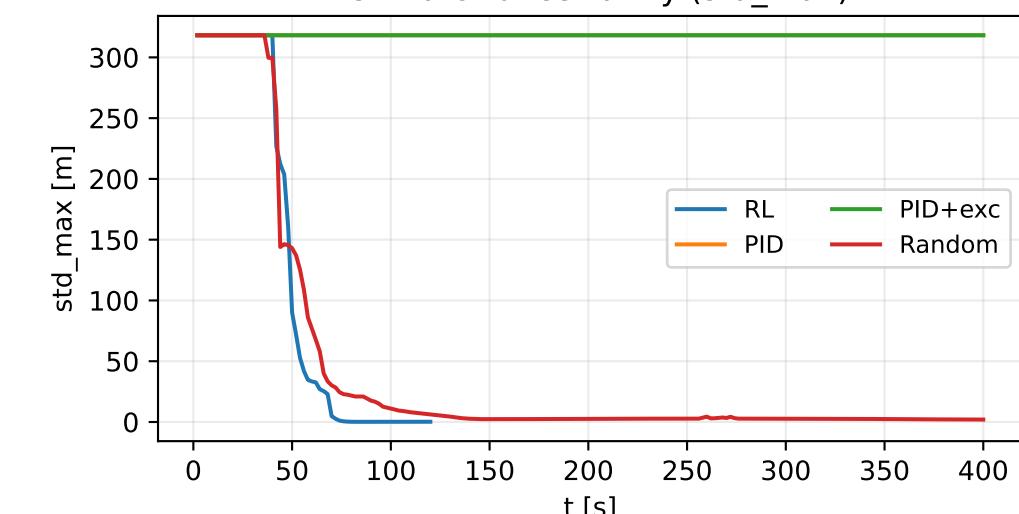
Trajectories (matched seed)



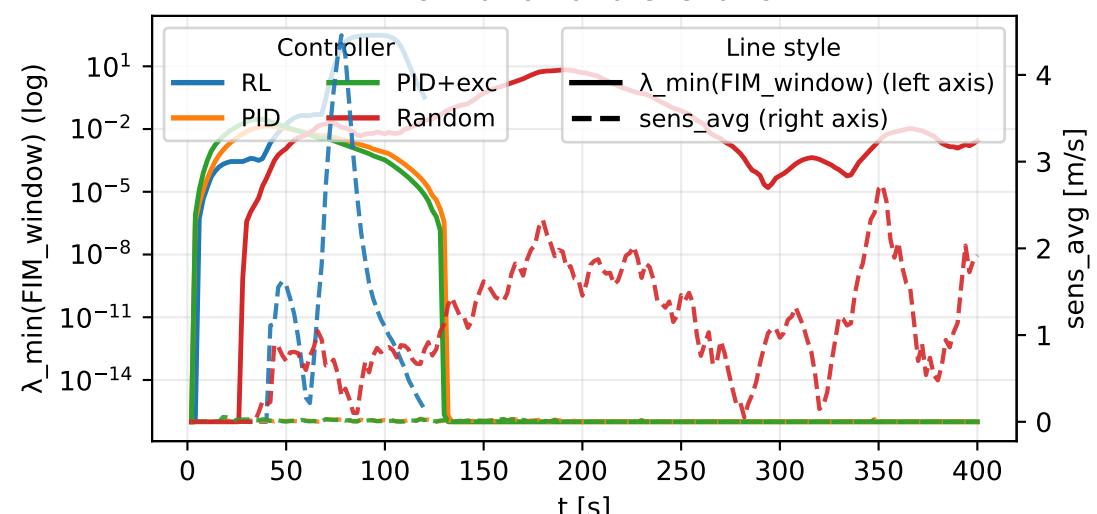
TRUE formation error



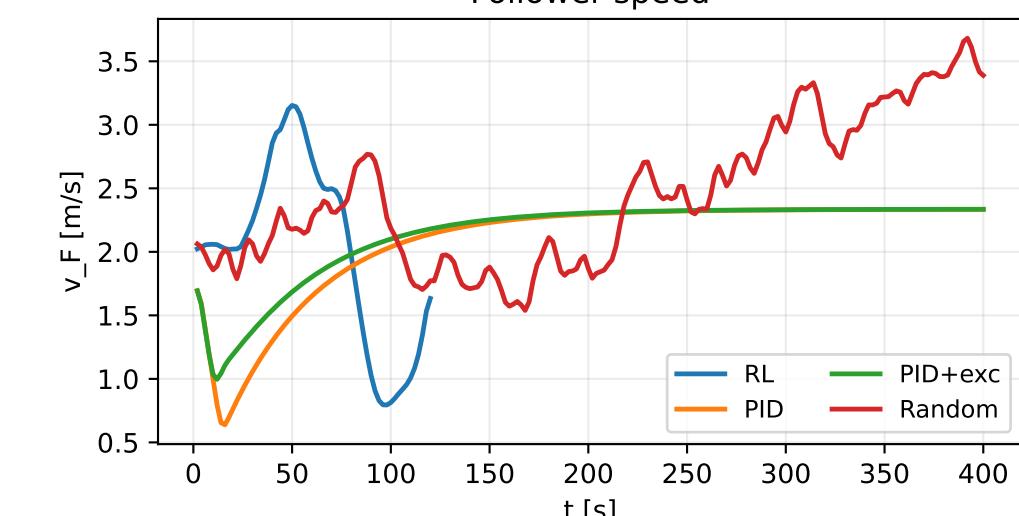
Estimator uncertainty (std_max)



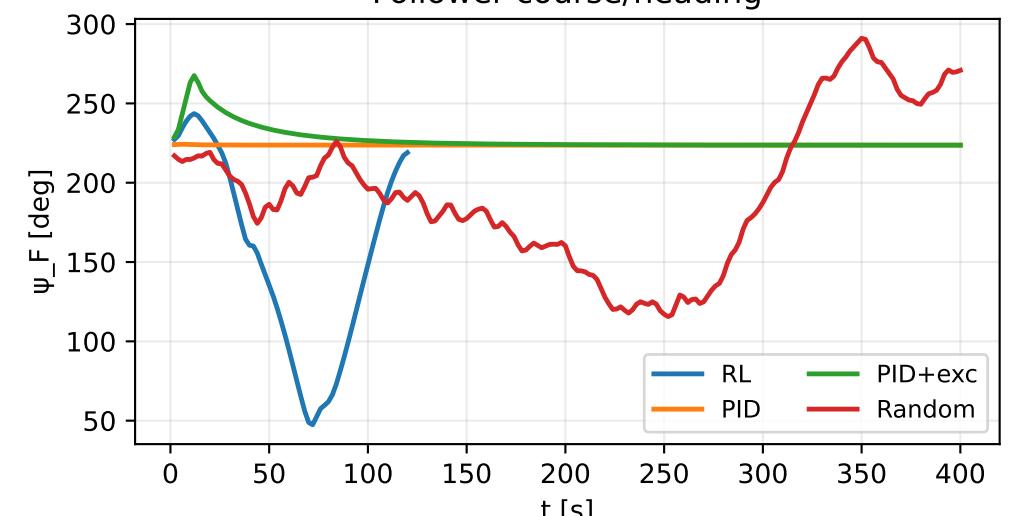
Information and excitation



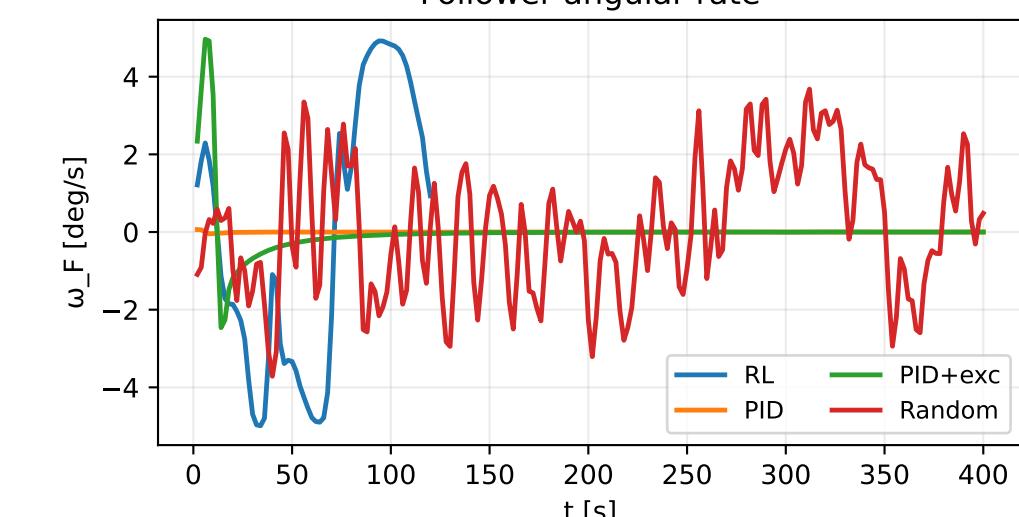
Follower speed



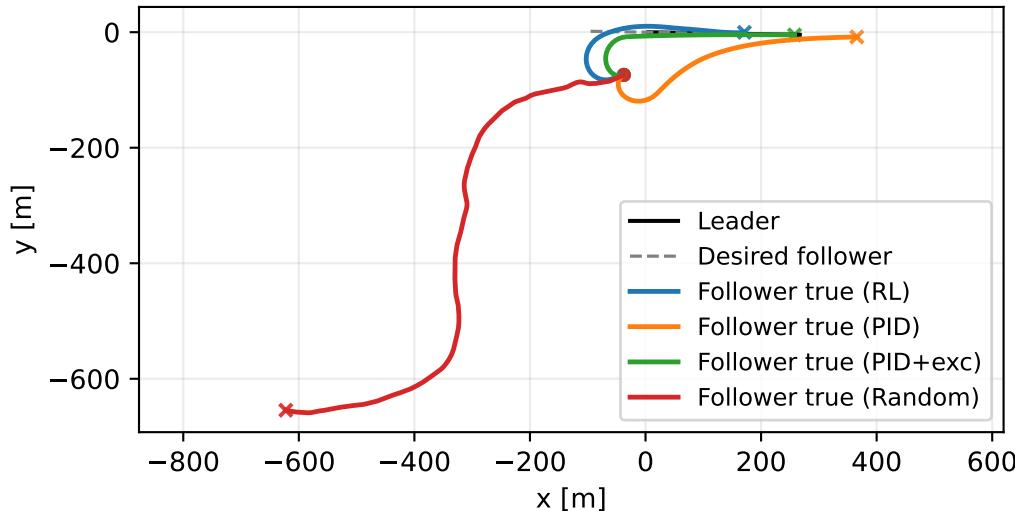
Follower course/heading



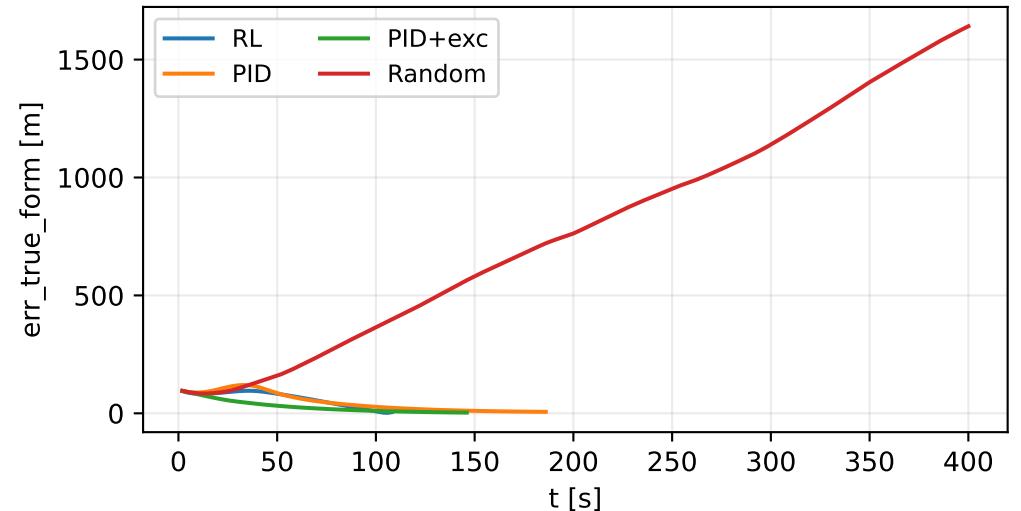
Follower angular rate



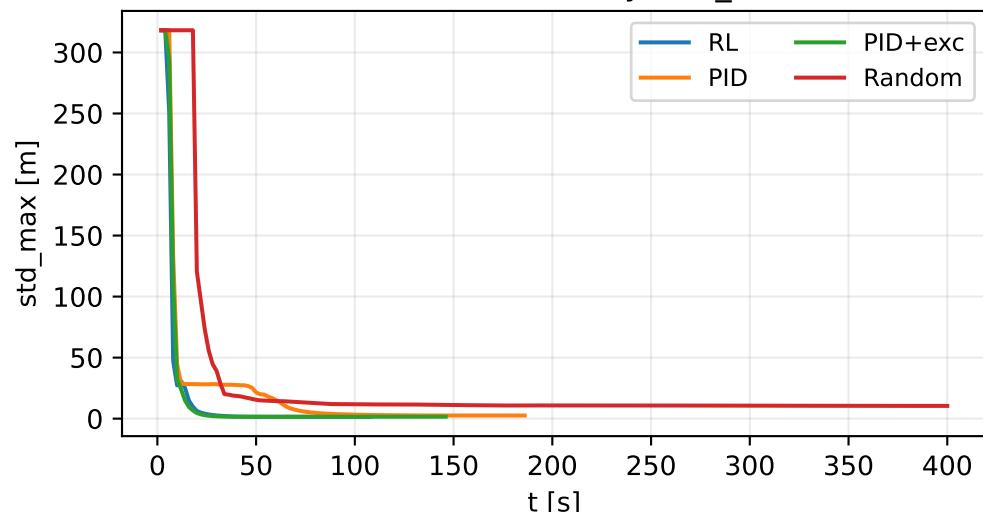
Trajectories (matched seed)



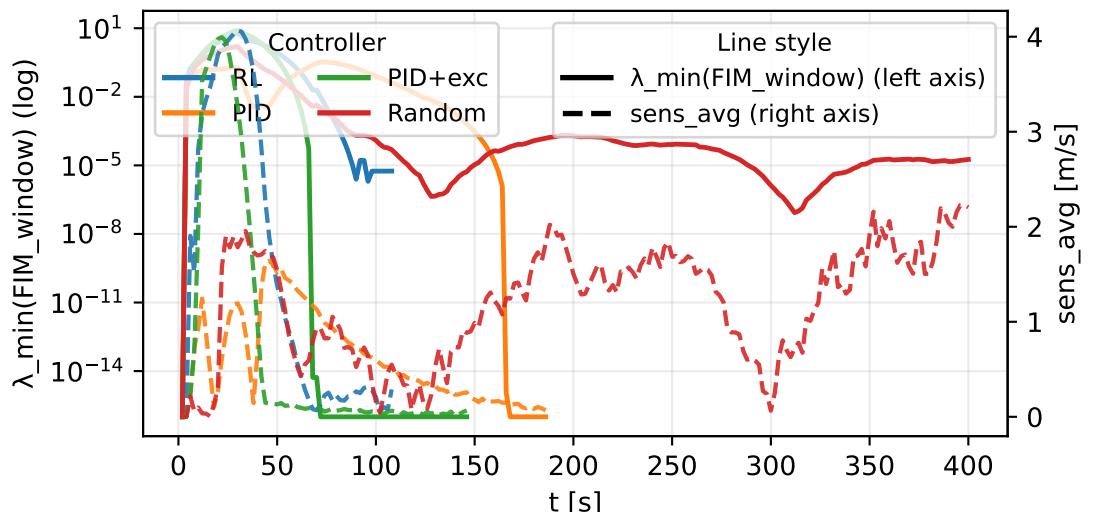
TRUE formation error



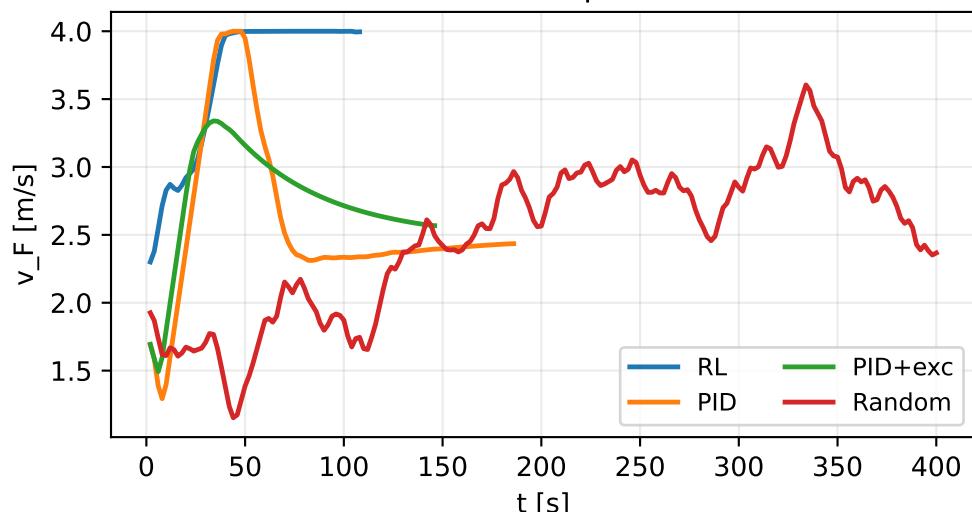
Estimator uncertainty (std_max)



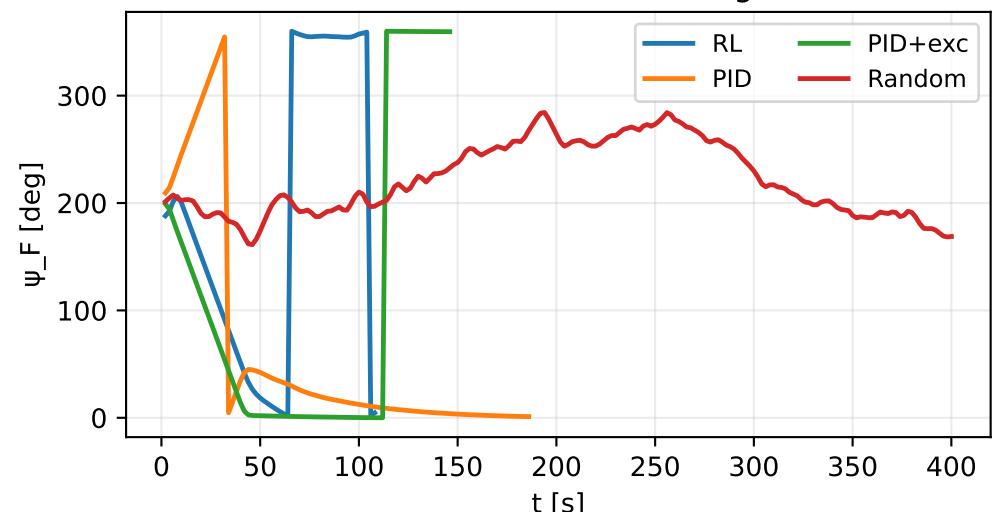
Information and excitation



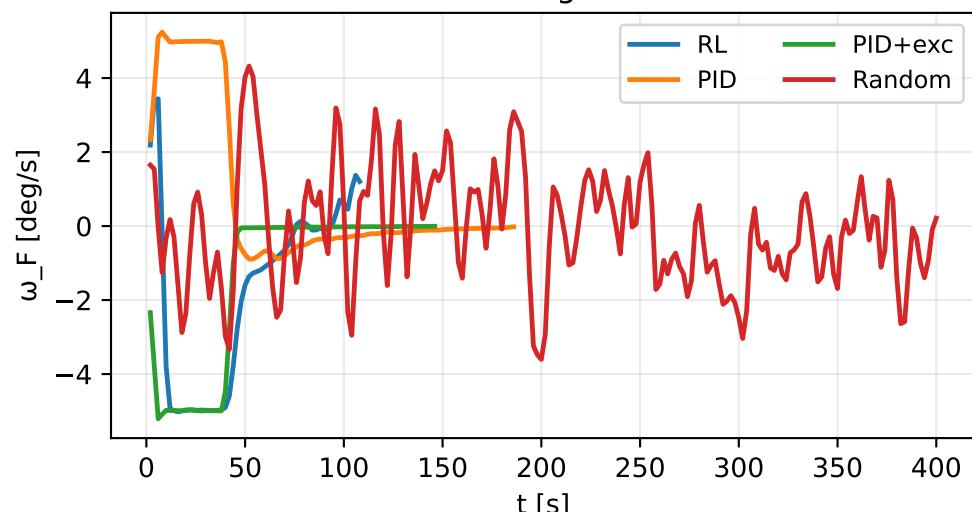
Follower speed



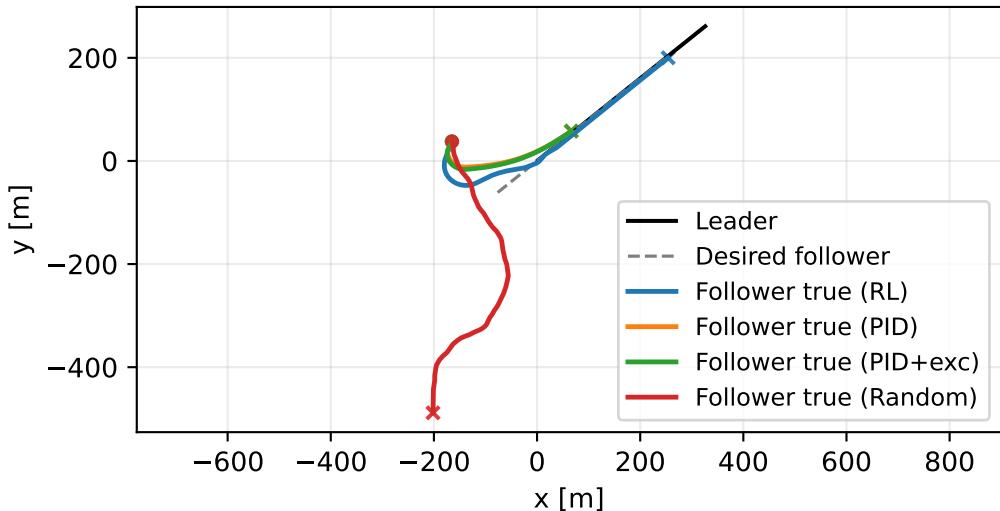
Follower course/heading



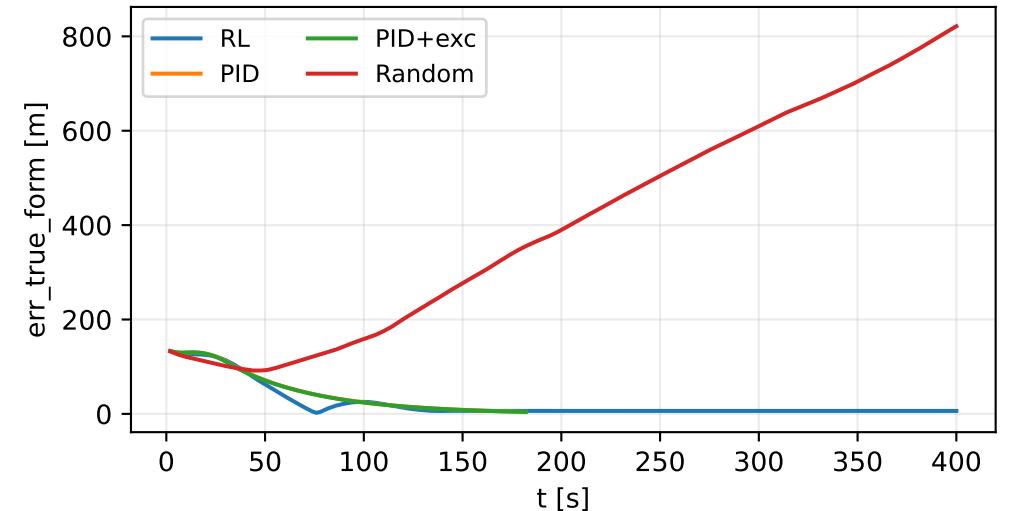
Follower angular rate



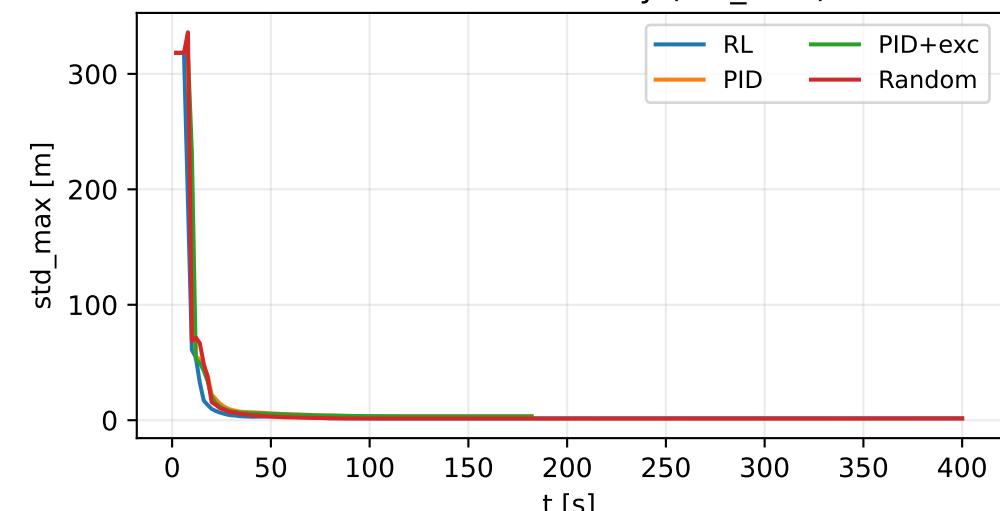
Trajectories (matched seed)



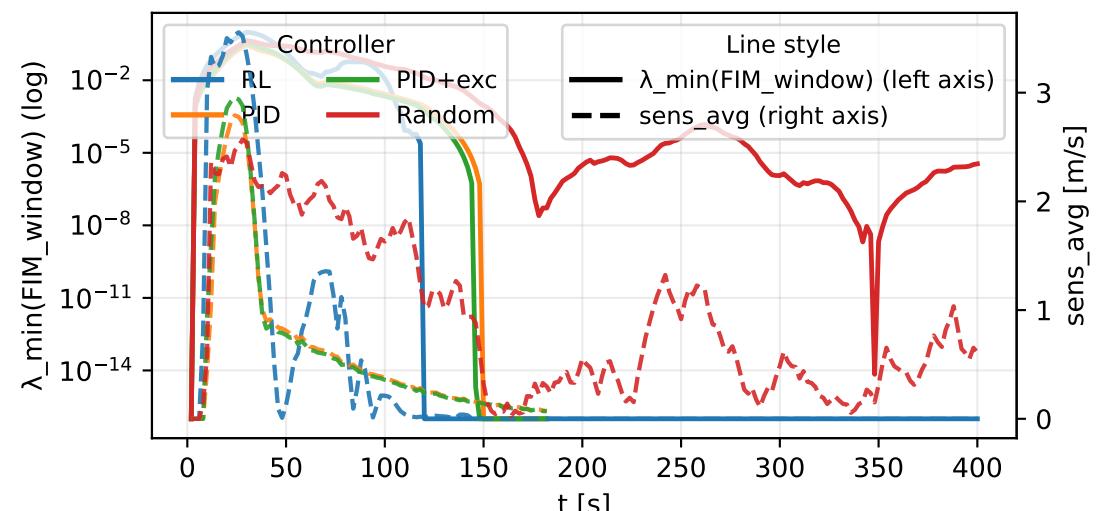
TRUE formation error



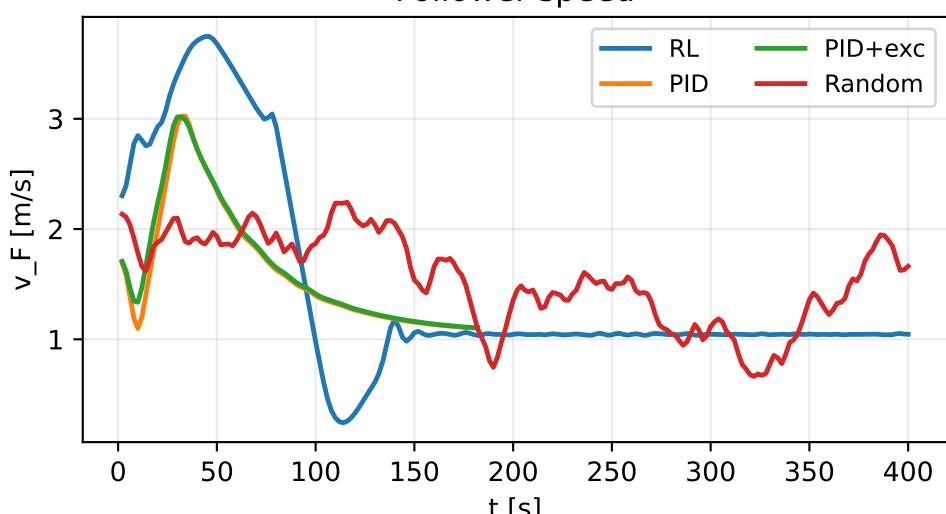
Estimator uncertainty (std_max)



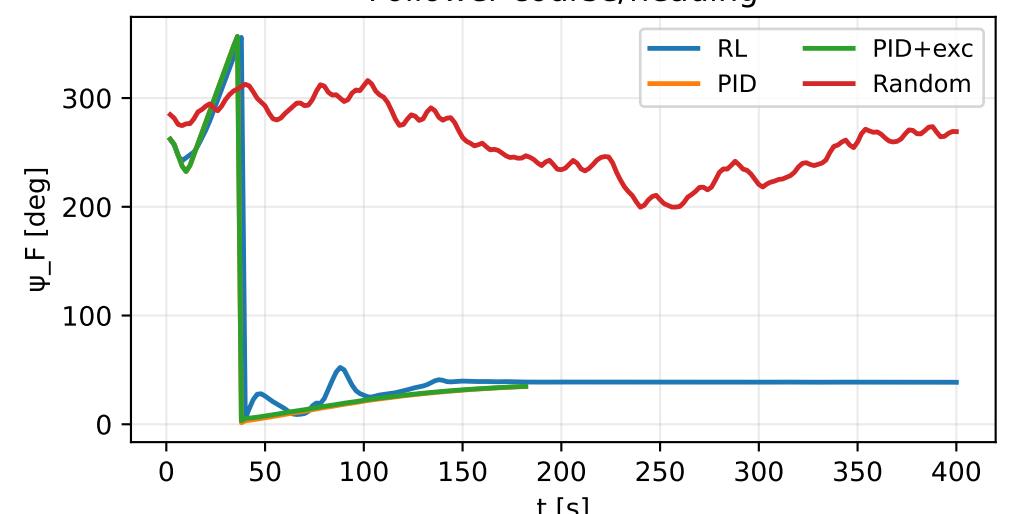
Information and excitation



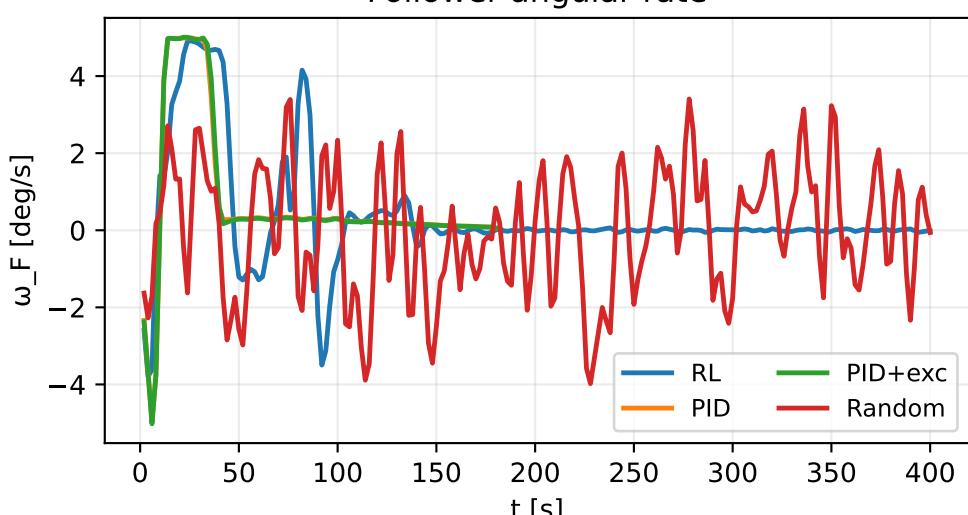
Follower speed



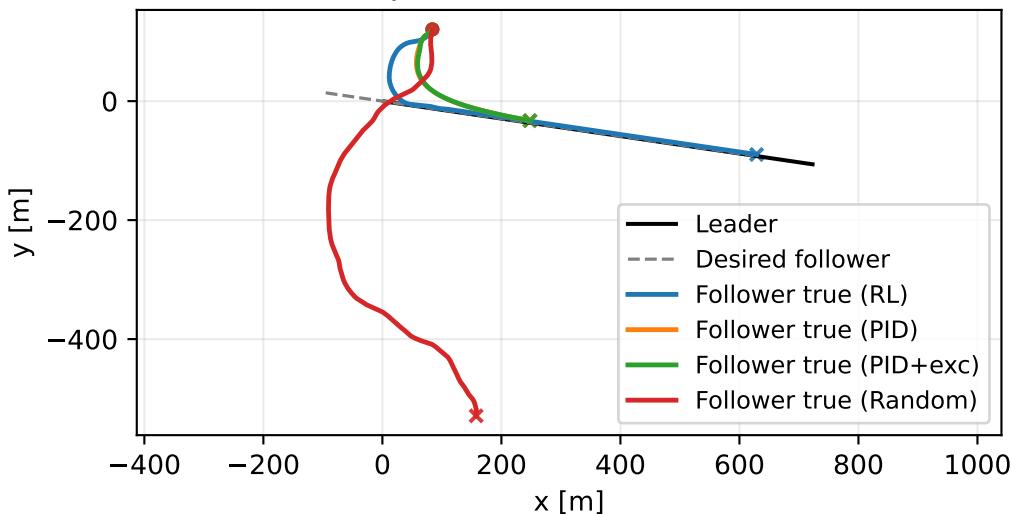
Follower course/heading



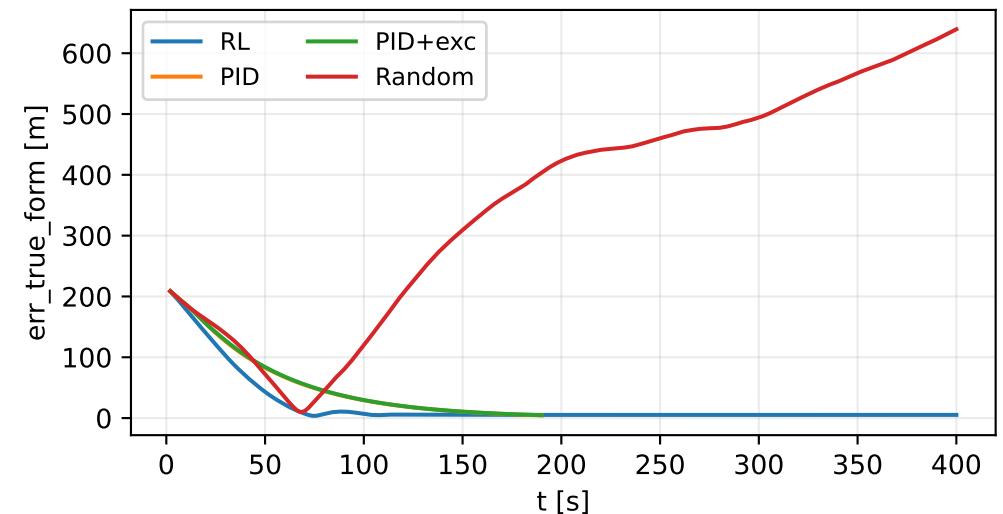
Follower angular rate



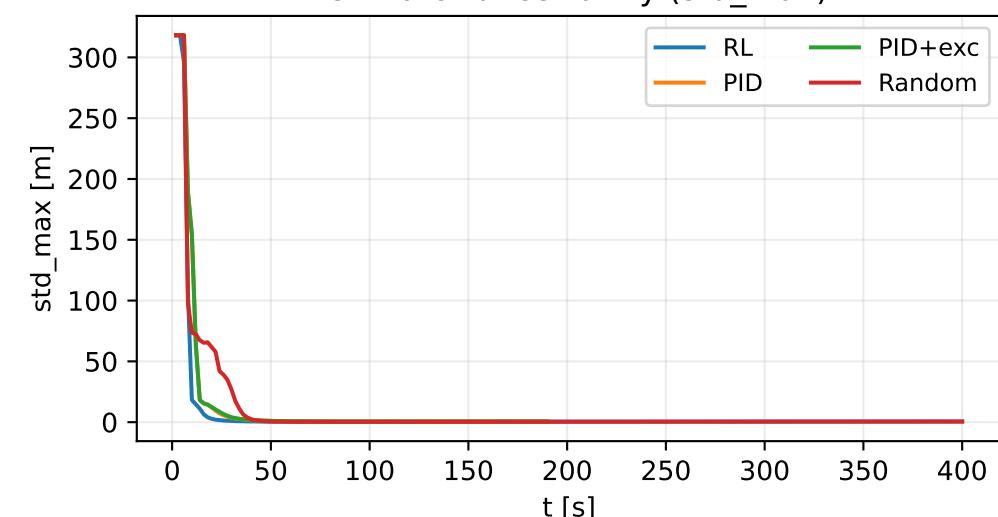
Trajectories (matched seed)



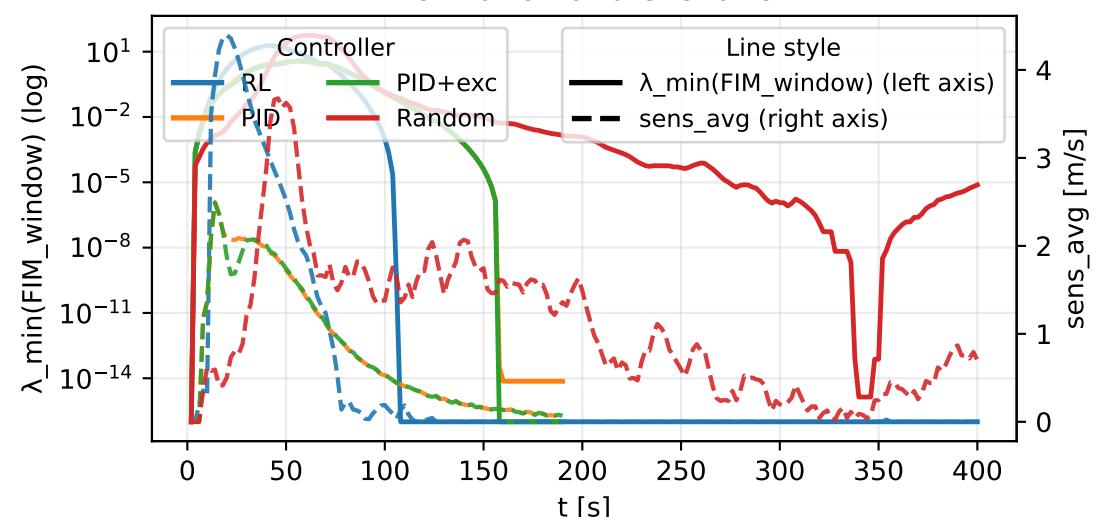
TRUE formation error



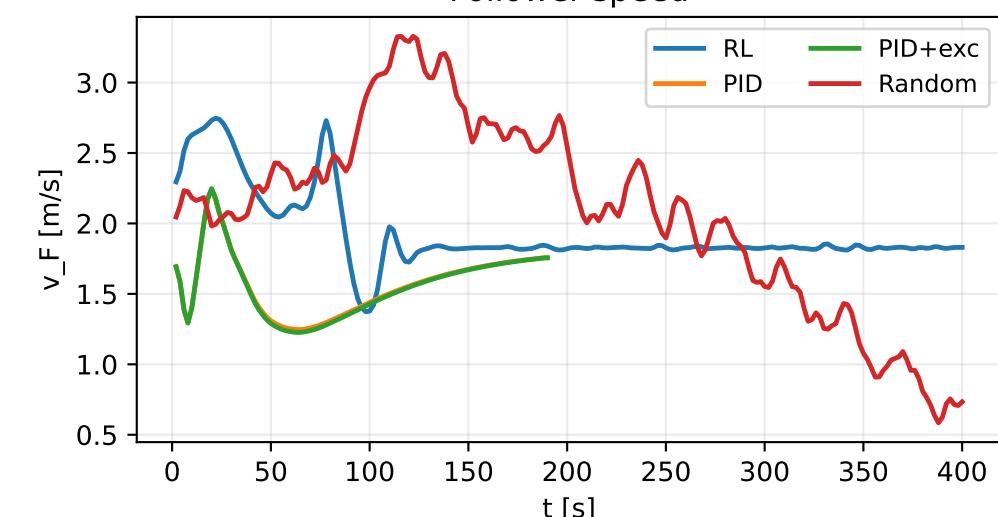
Estimator uncertainty (std_max)



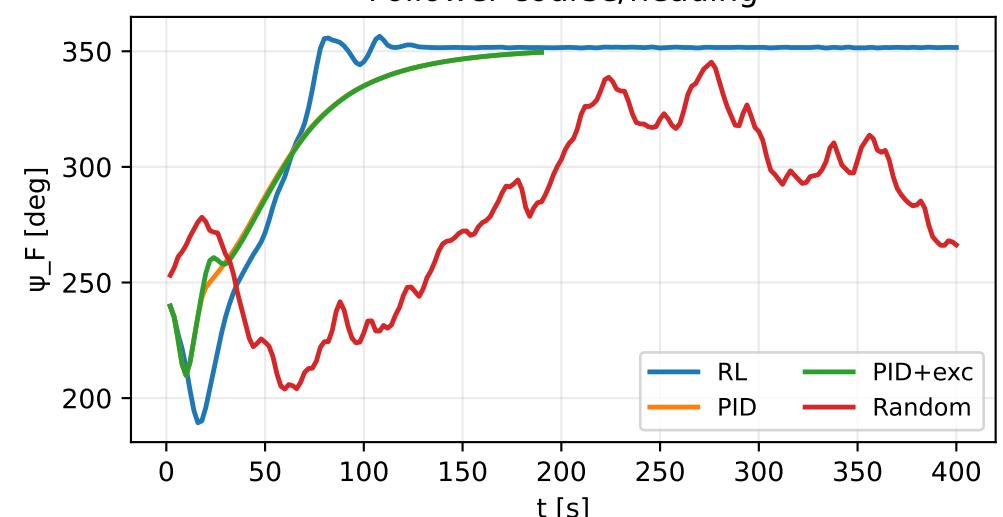
Information and excitation



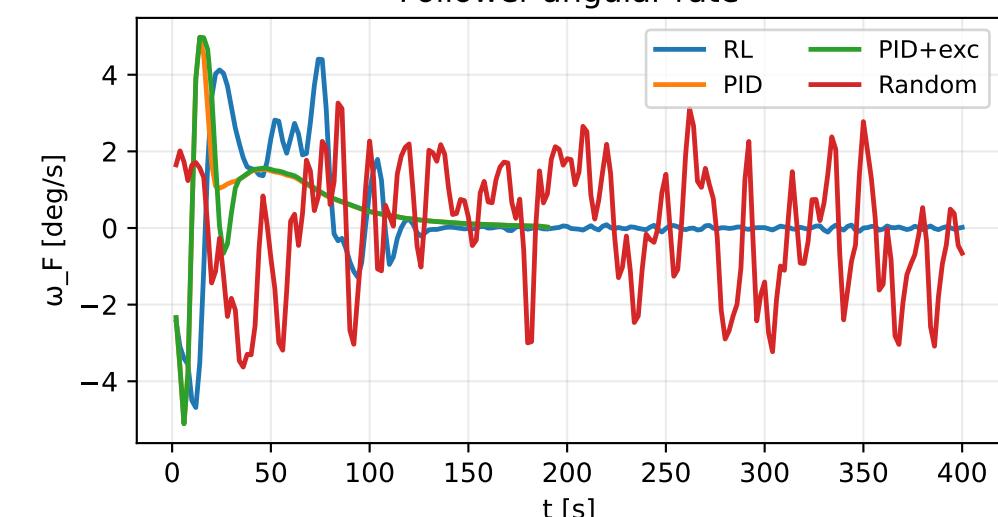
Follower speed



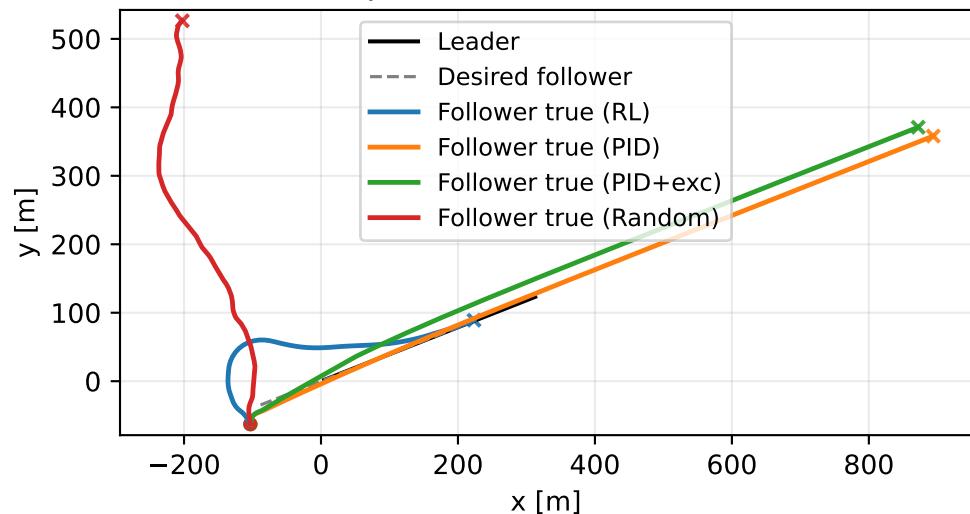
Follower course/heading



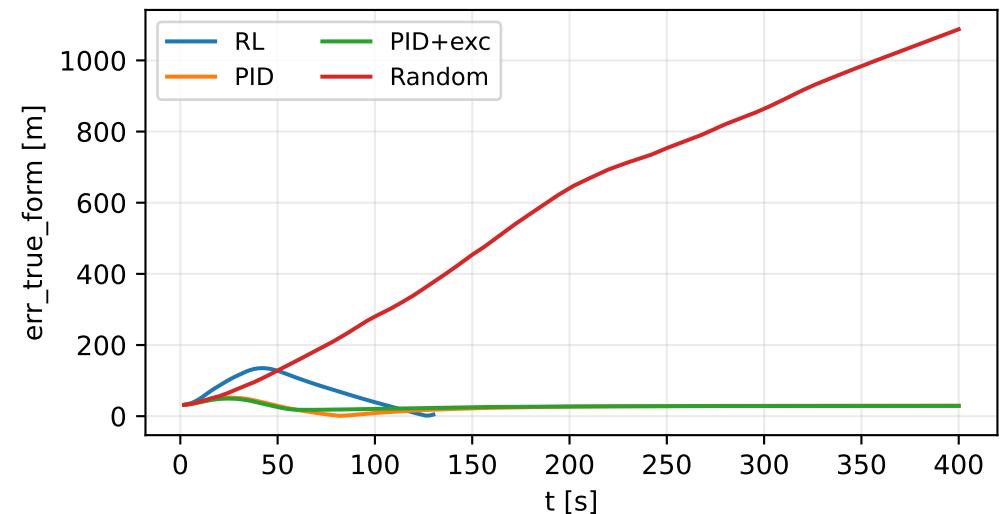
Follower angular rate



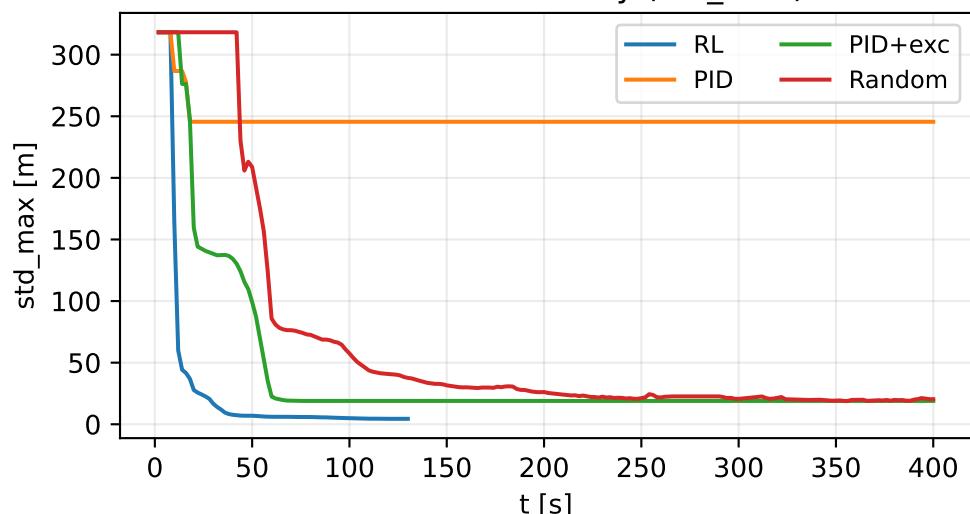
Trajectories (matched seed)



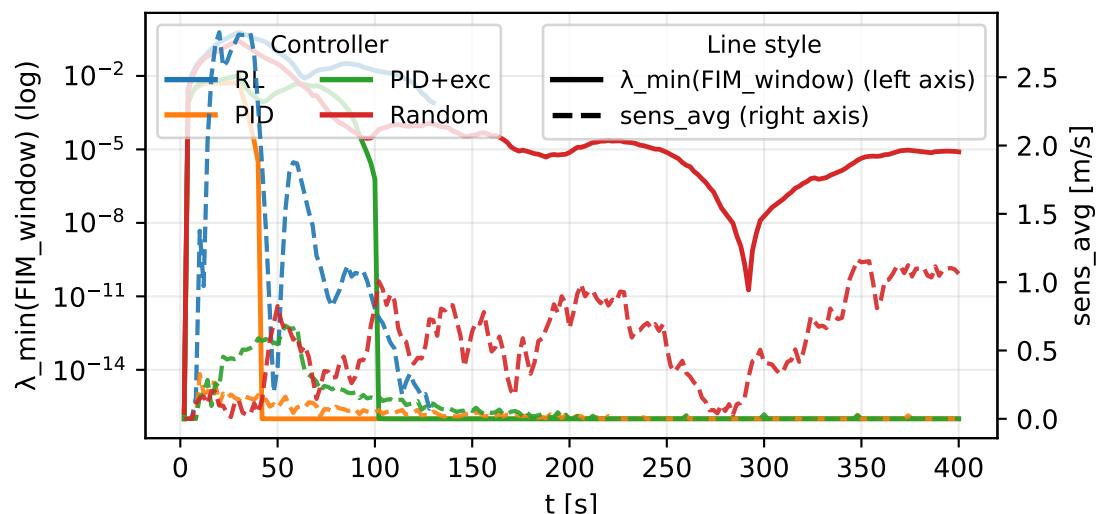
TRUE formation error



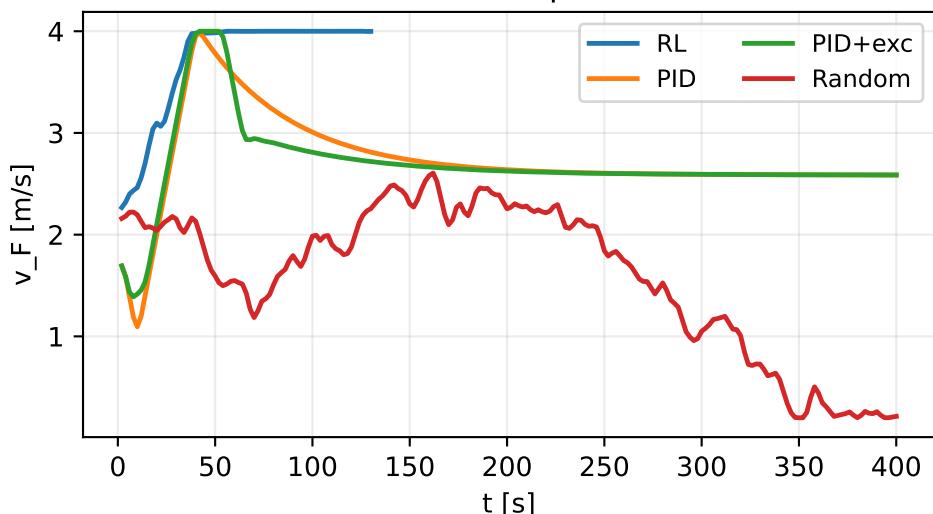
Estimator uncertainty (std_max)



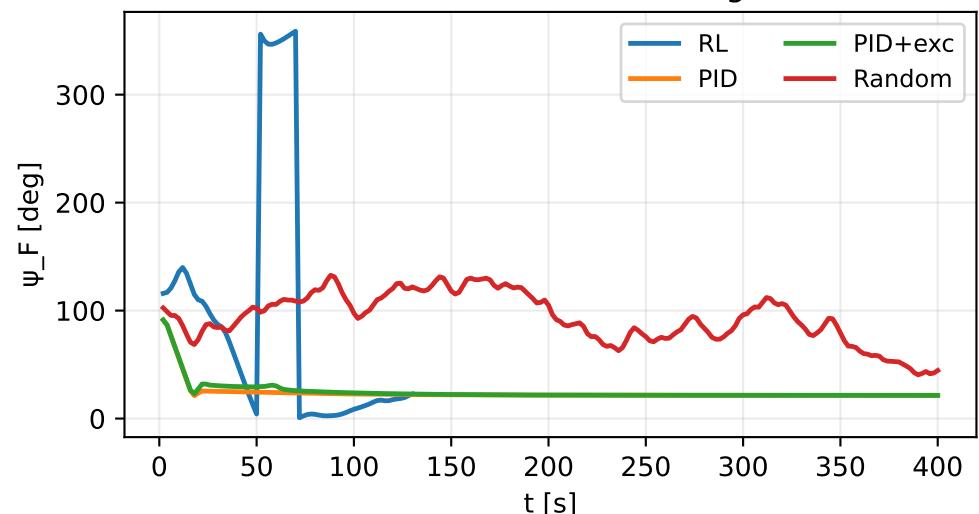
Information and excitation



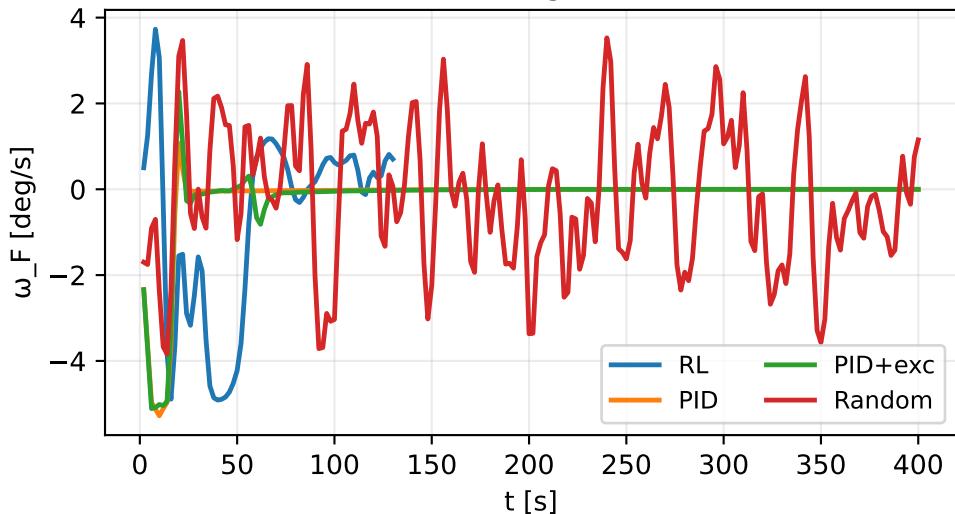
Follower speed



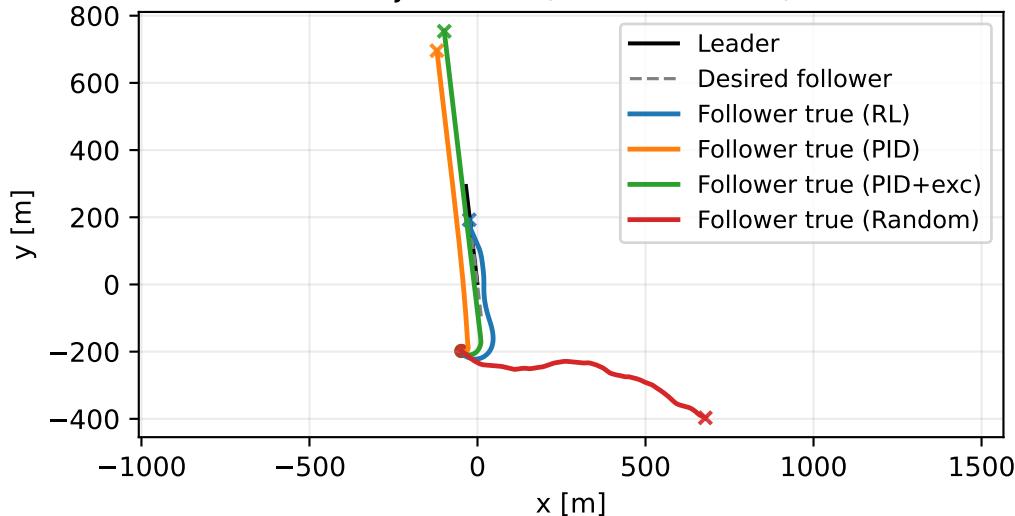
Follower course/heading



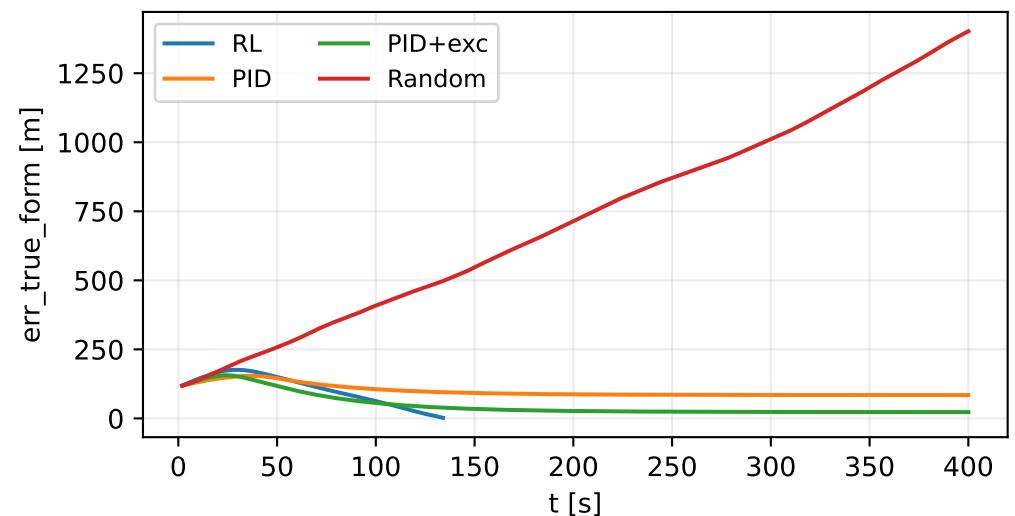
Follower angular rate



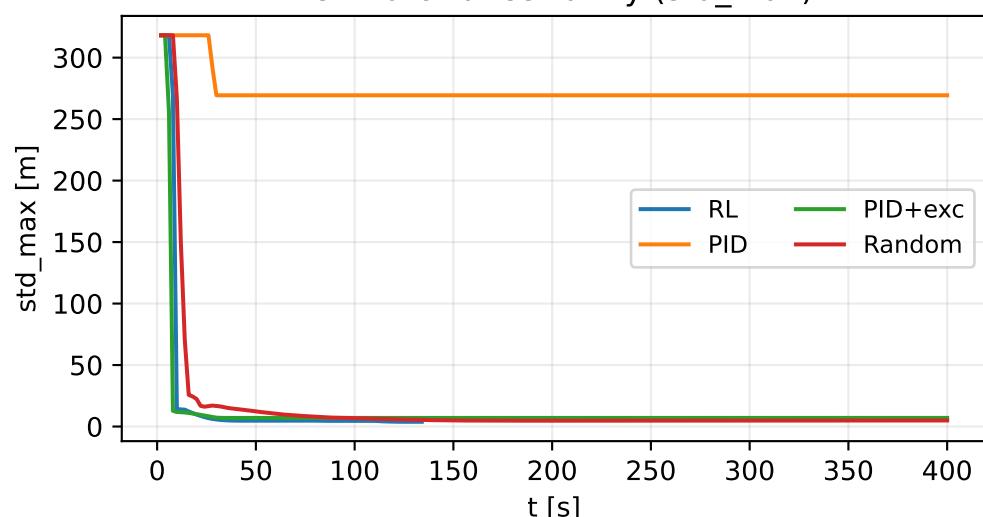
Trajectories (matched seed)



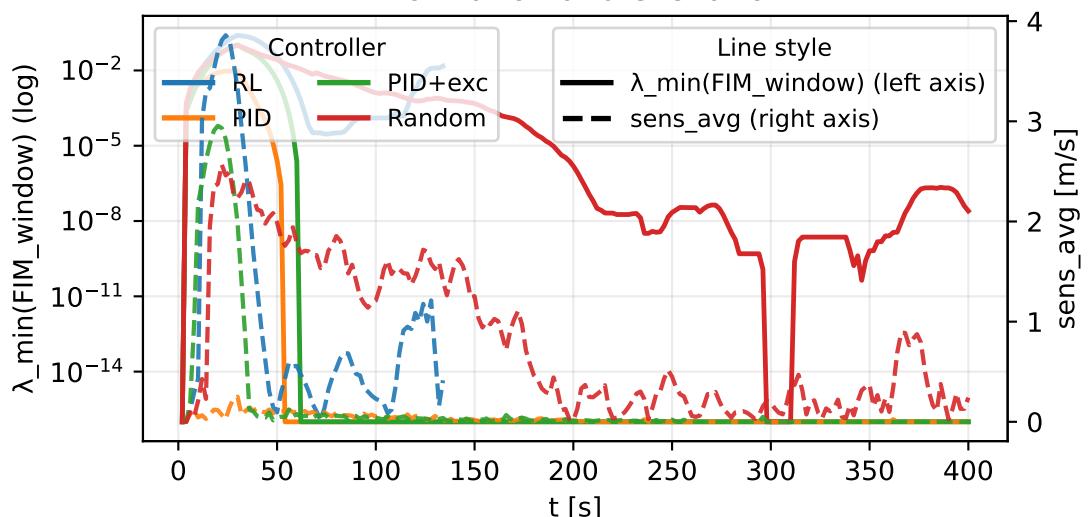
TRUE formation error



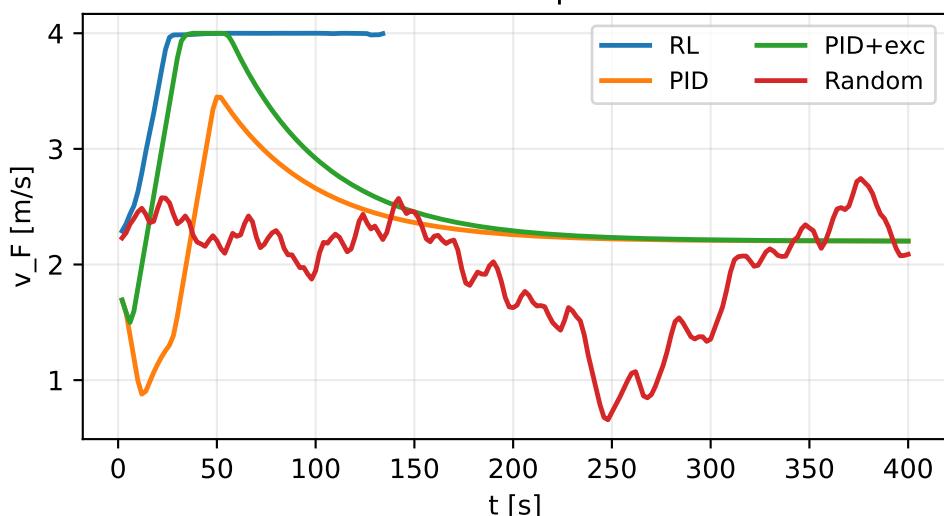
Estimator uncertainty (std_max)



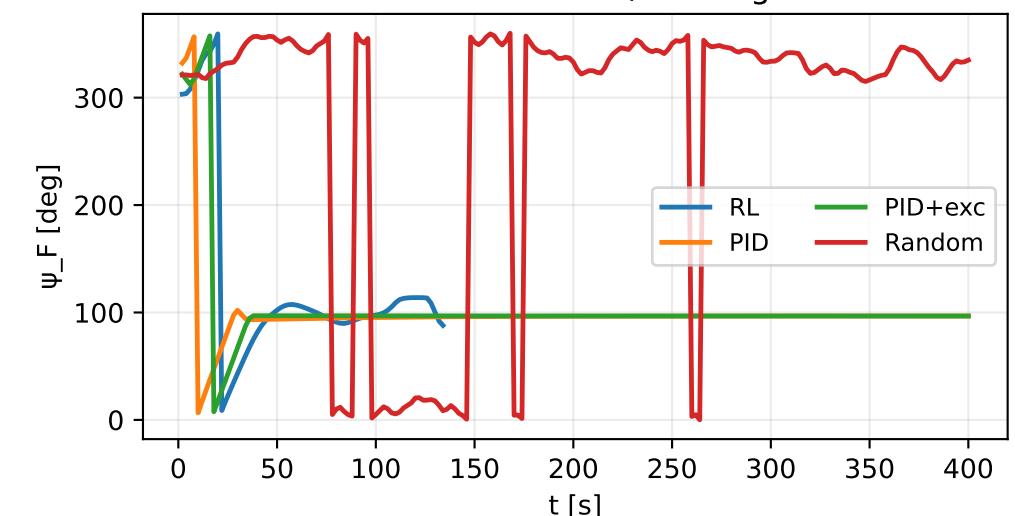
Information and excitation



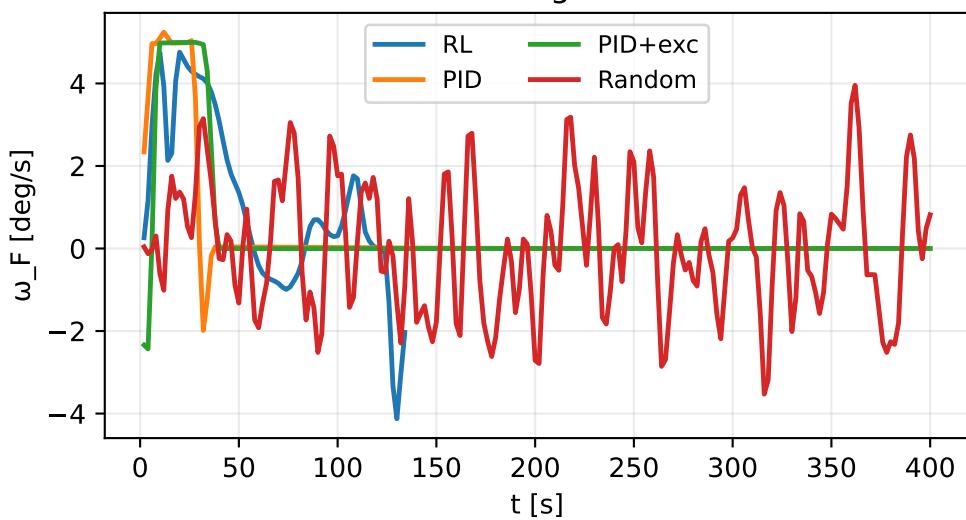
Follower speed



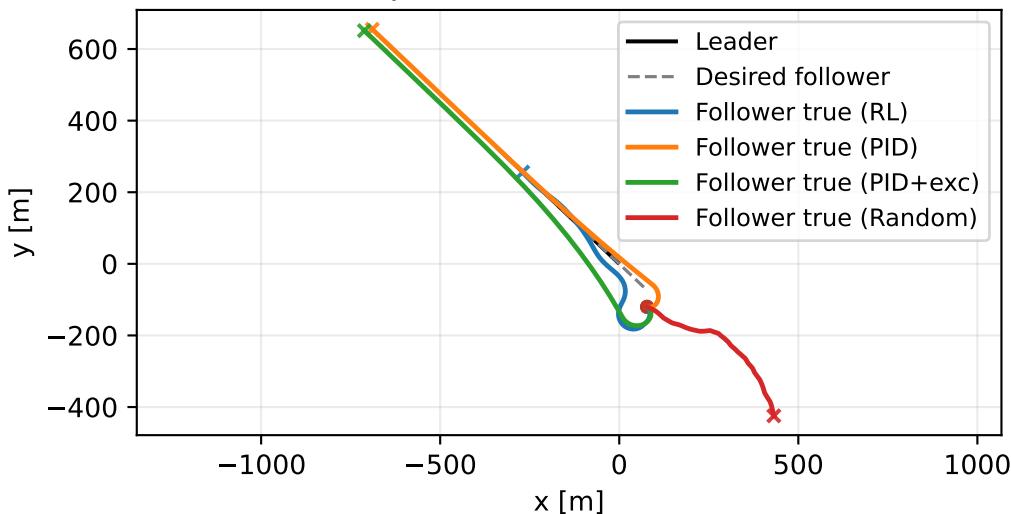
Follower course/heading



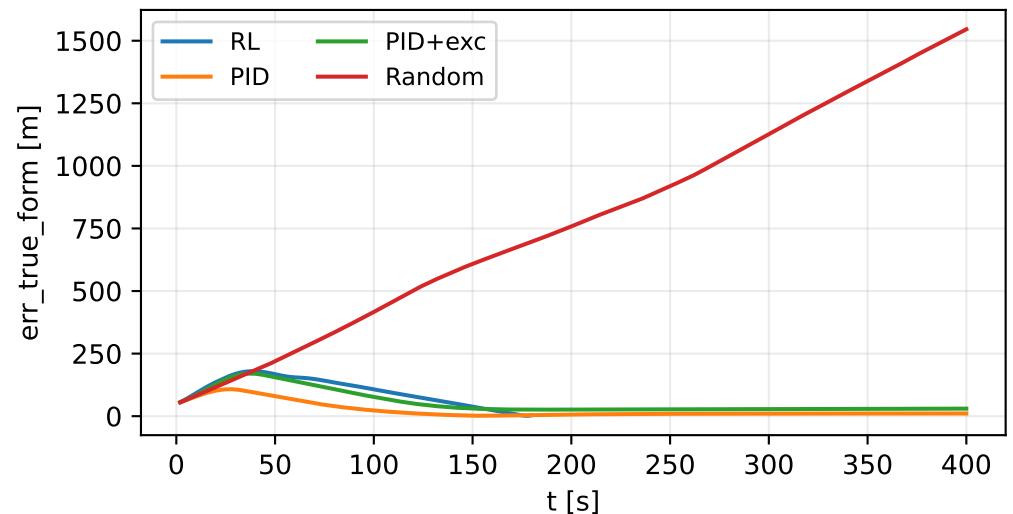
Follower angular rate



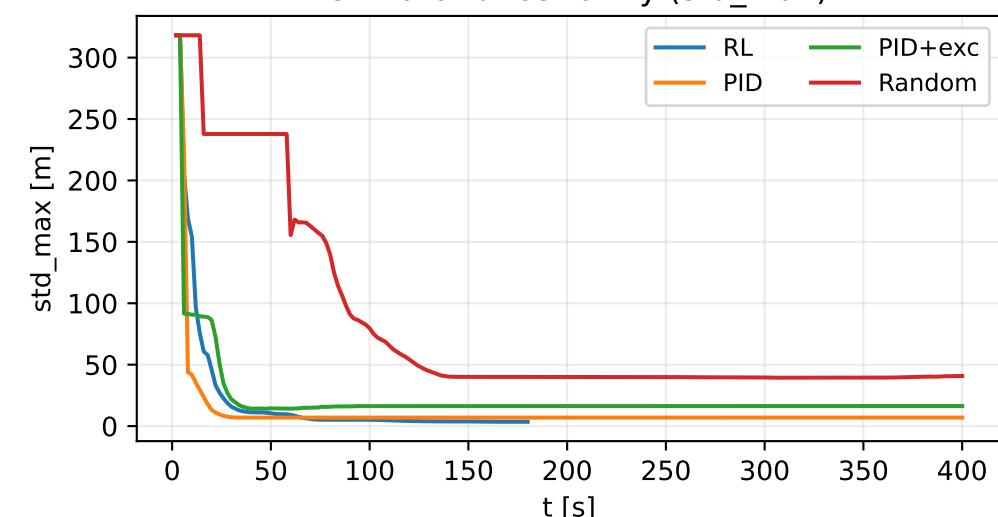
Trajectories (matched seed)



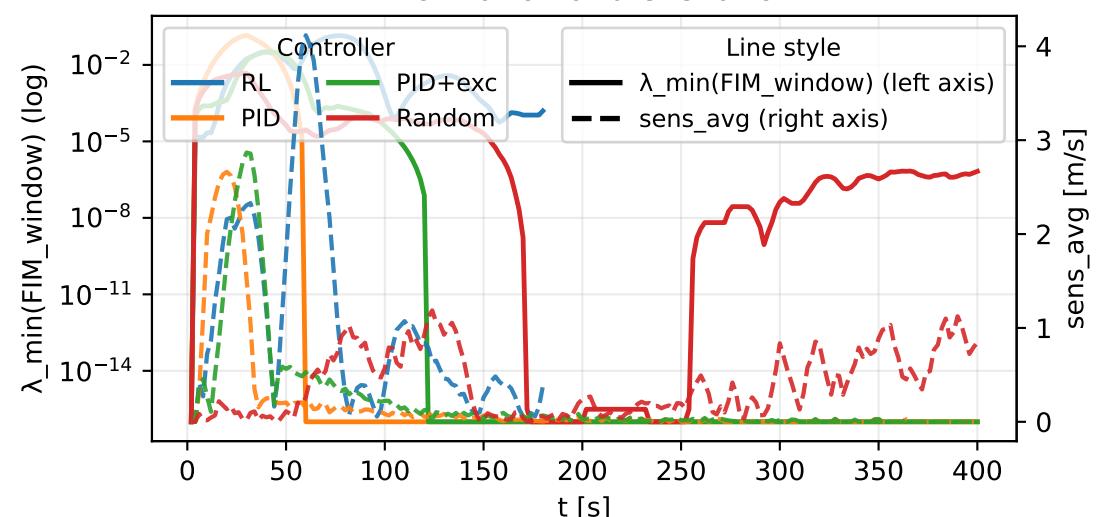
TRUE formation error



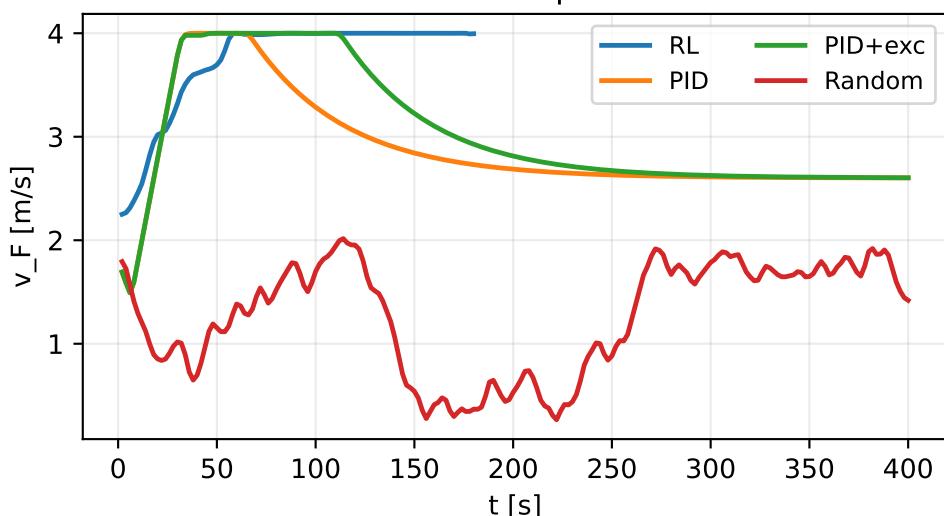
Estimator uncertainty (std_max)



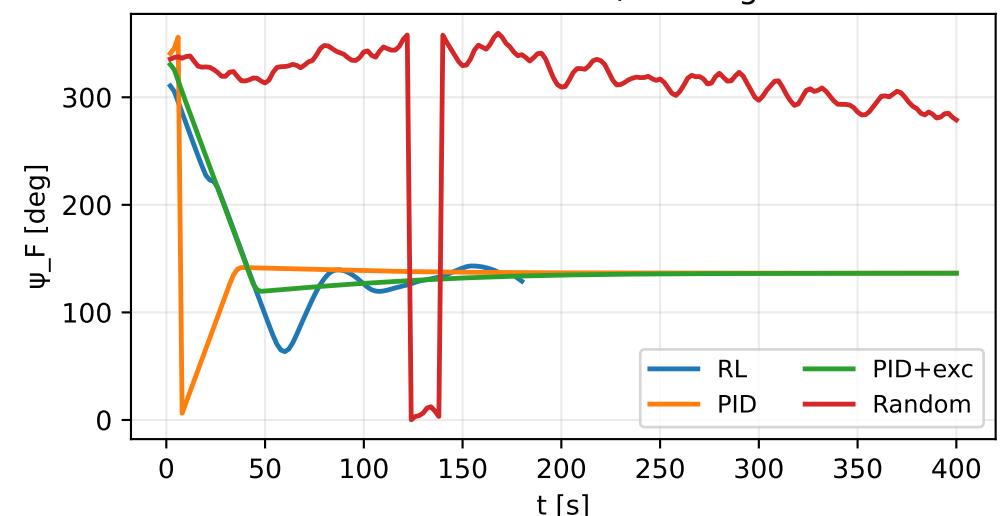
Information and excitation



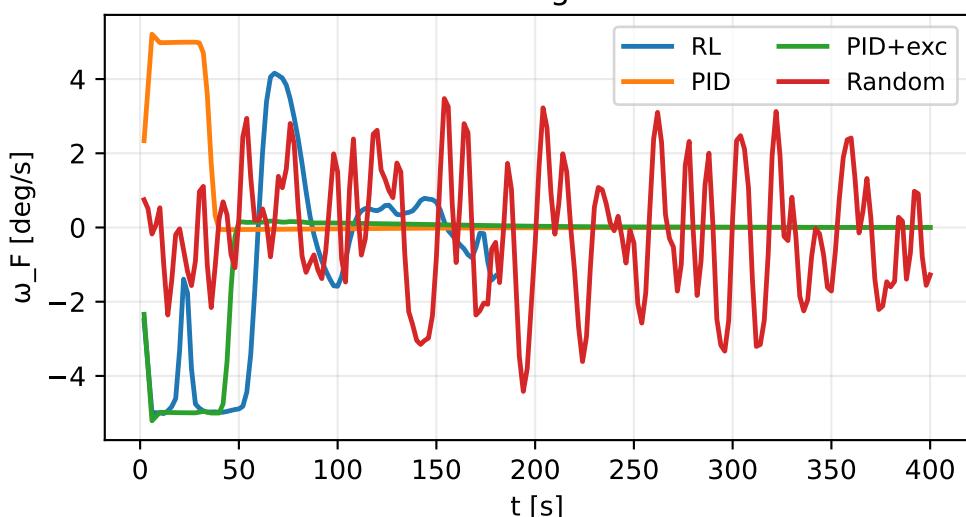
Follower speed



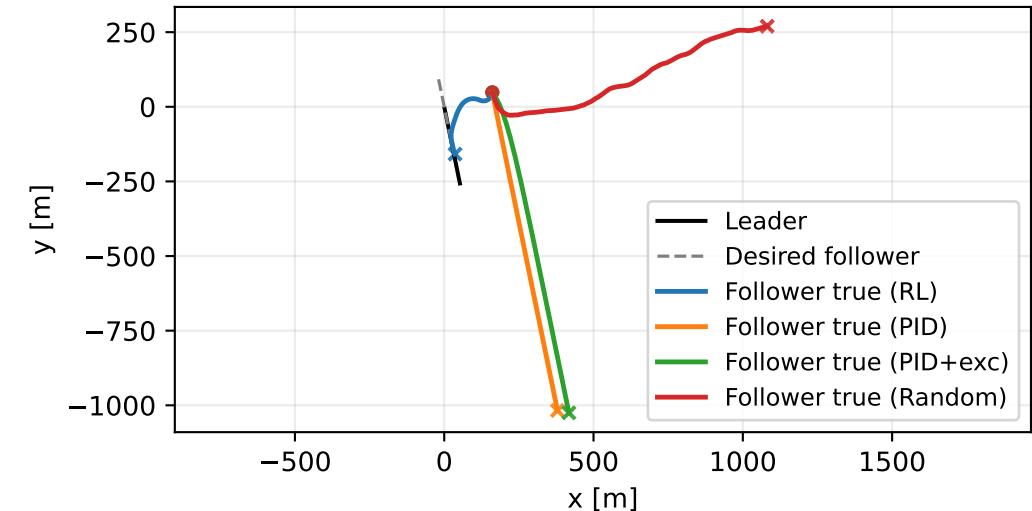
Follower course/heading



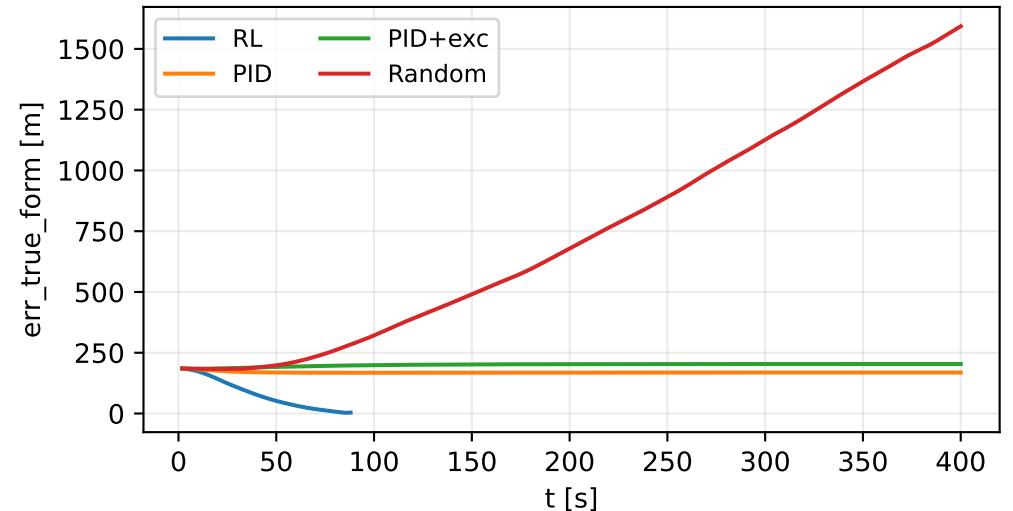
Follower angular rate



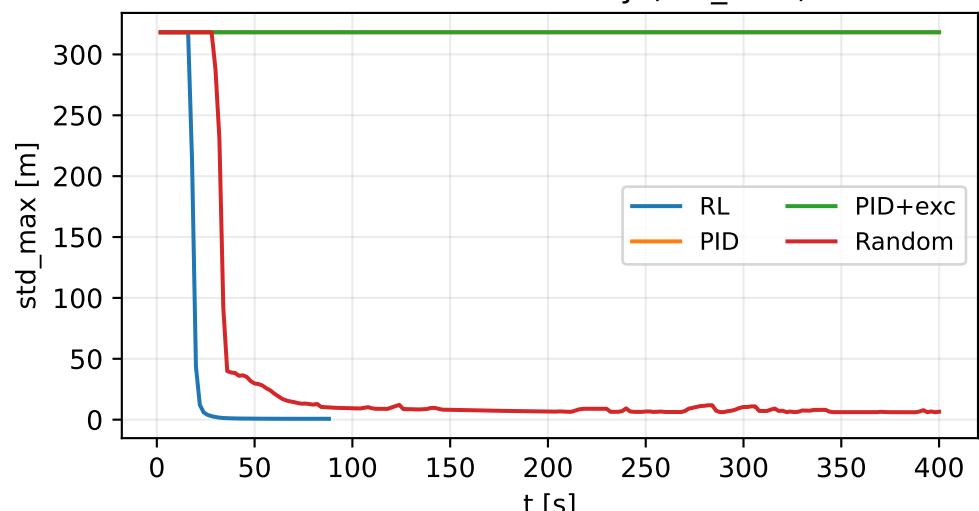
Trajectories (matched seed)



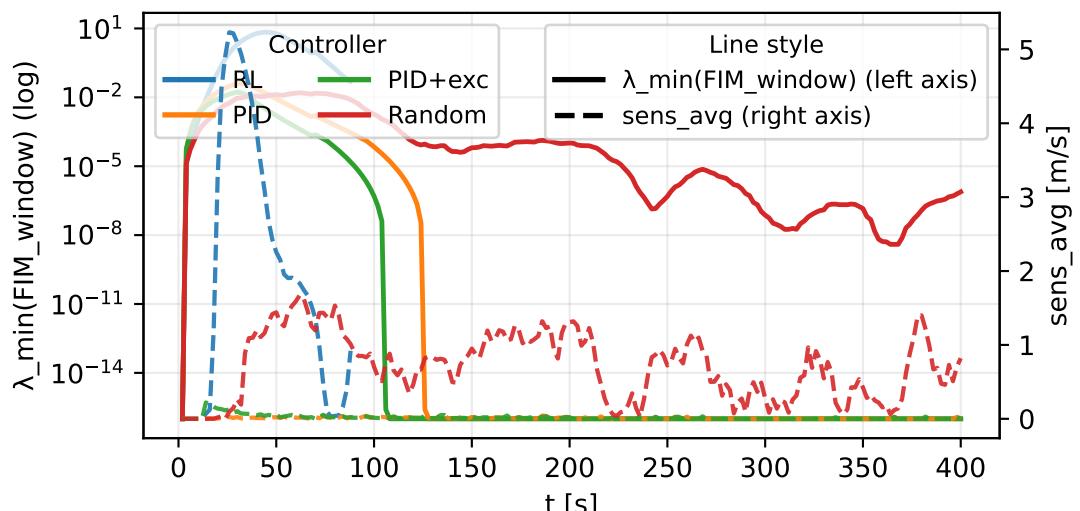
TRUE formation error



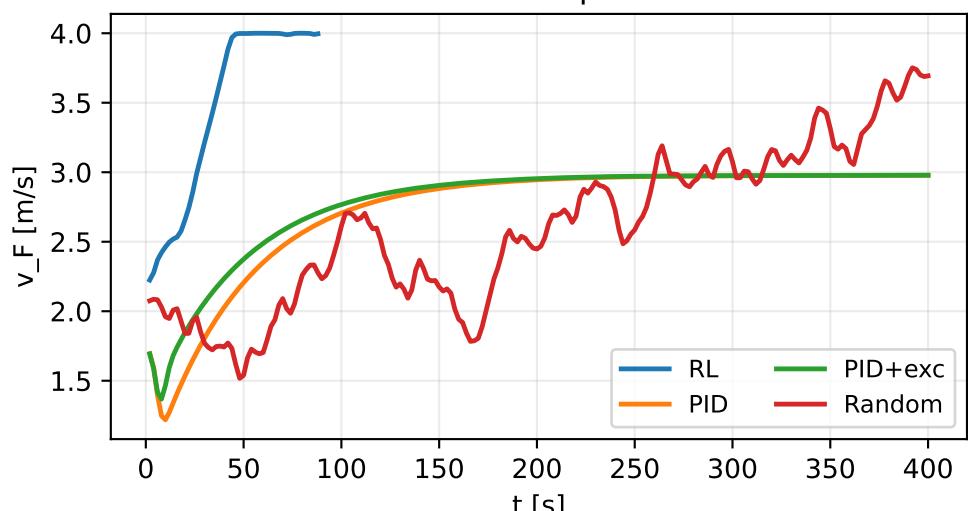
Estimator uncertainty (std_max)



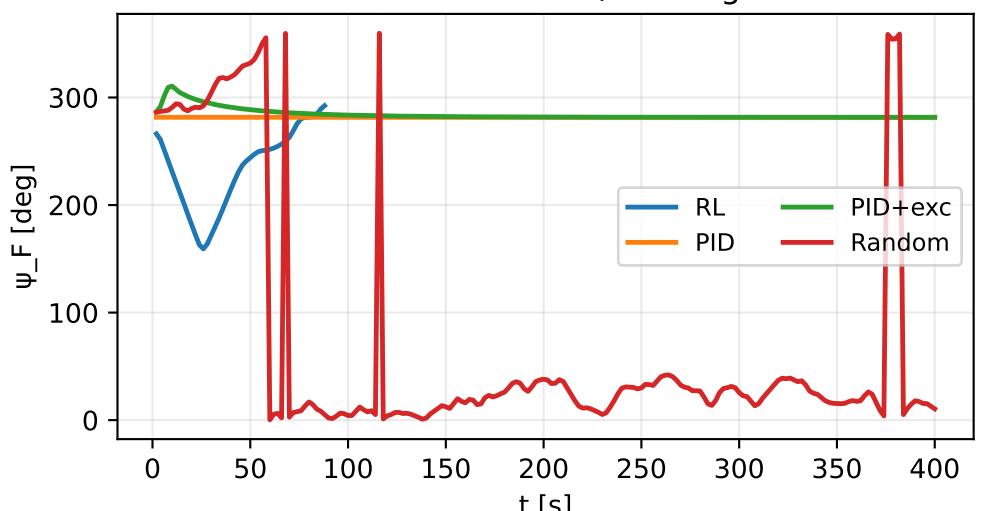
Information and excitation



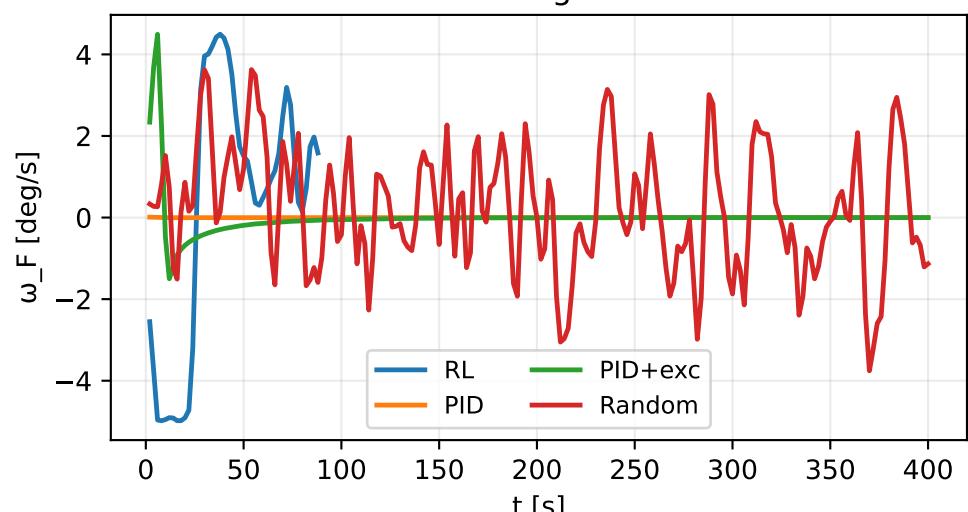
Follower speed



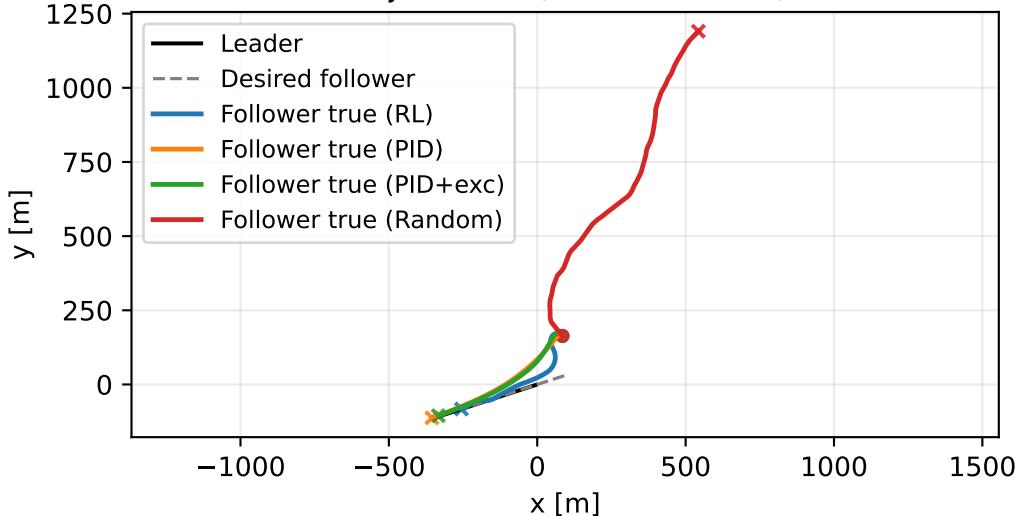
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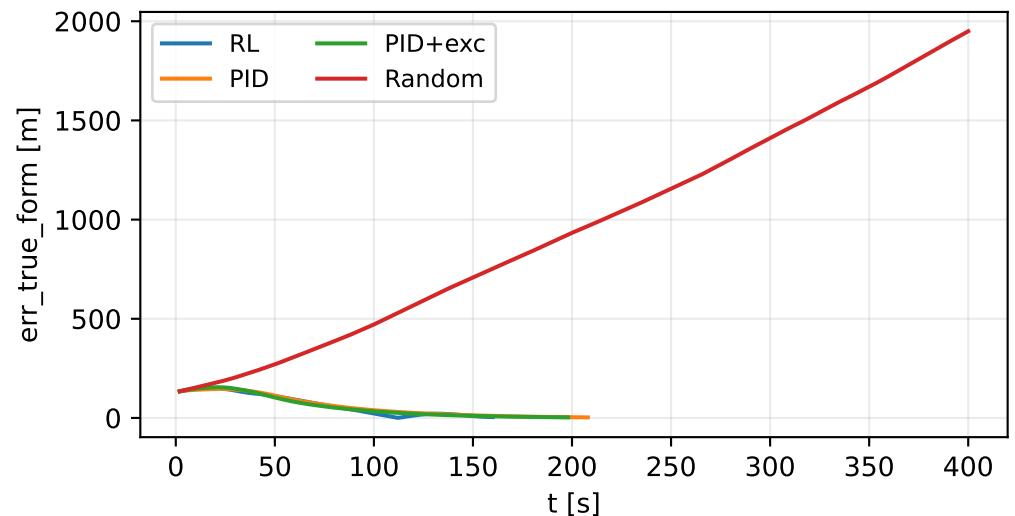
Follower angular rate



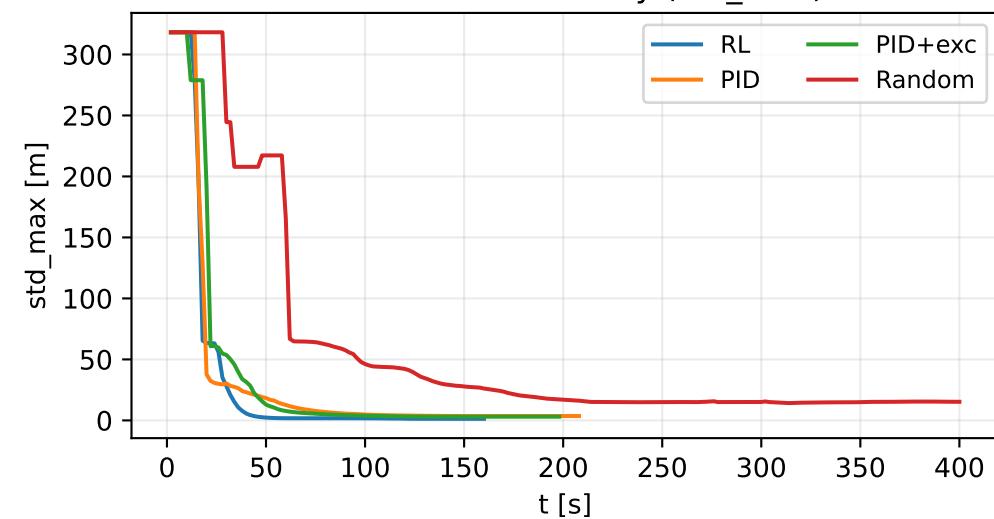
Trajectories (matched seed)



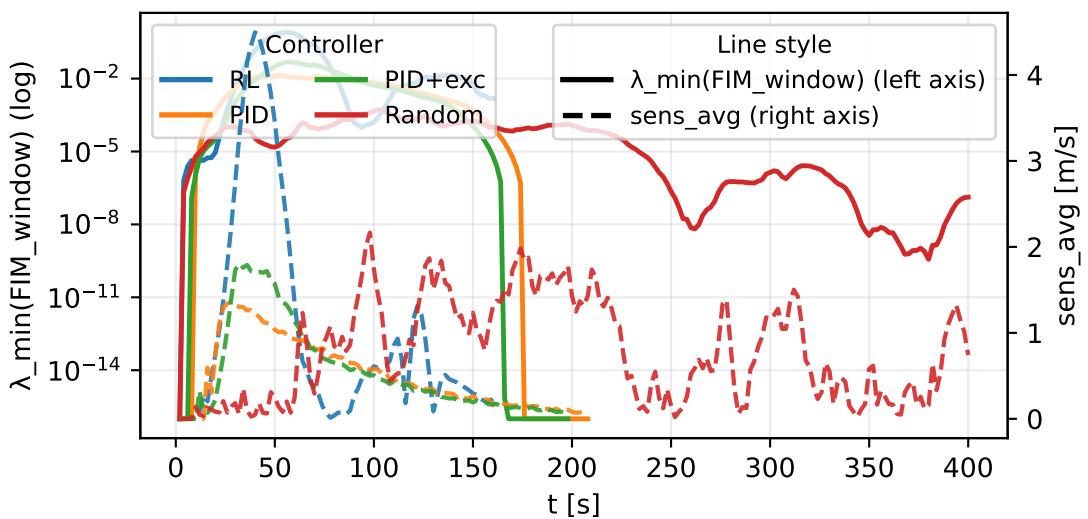
TRUE formation error



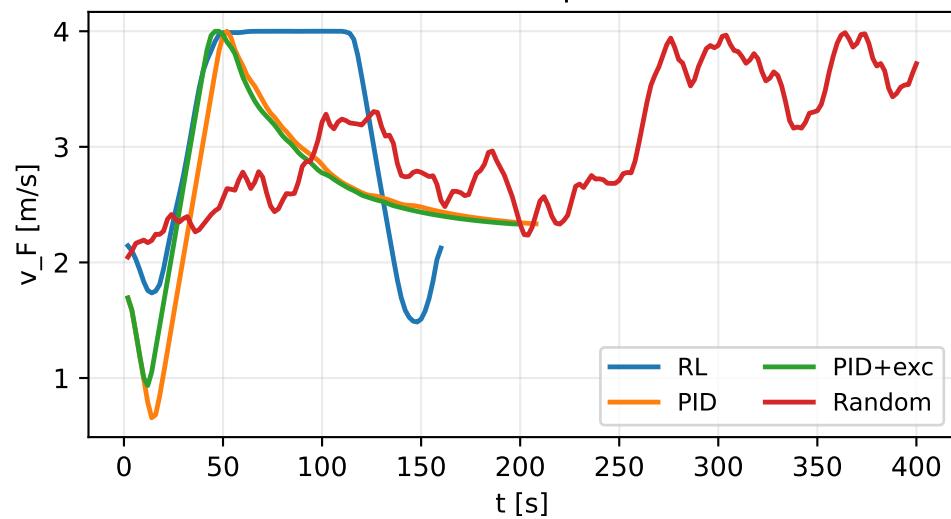
Estimator uncertainty (std_max)



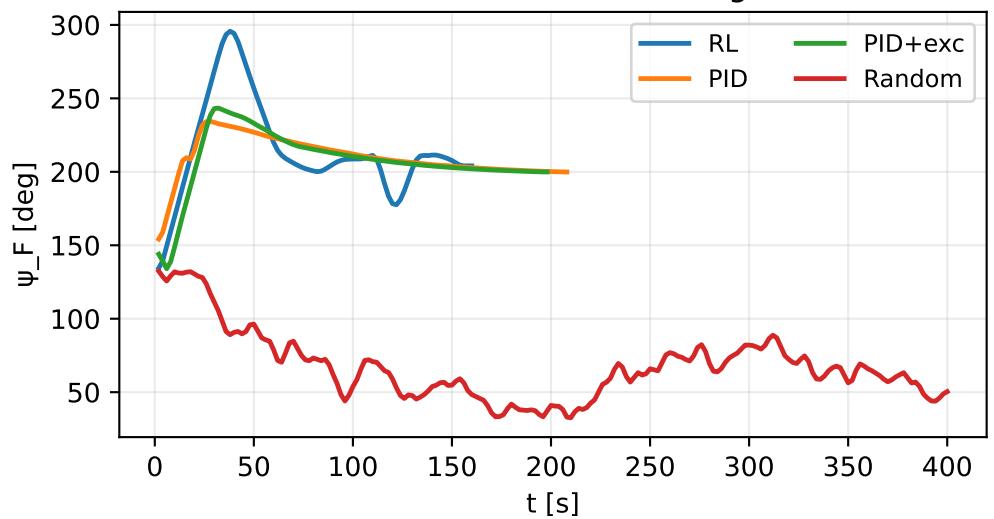
Information and excitation



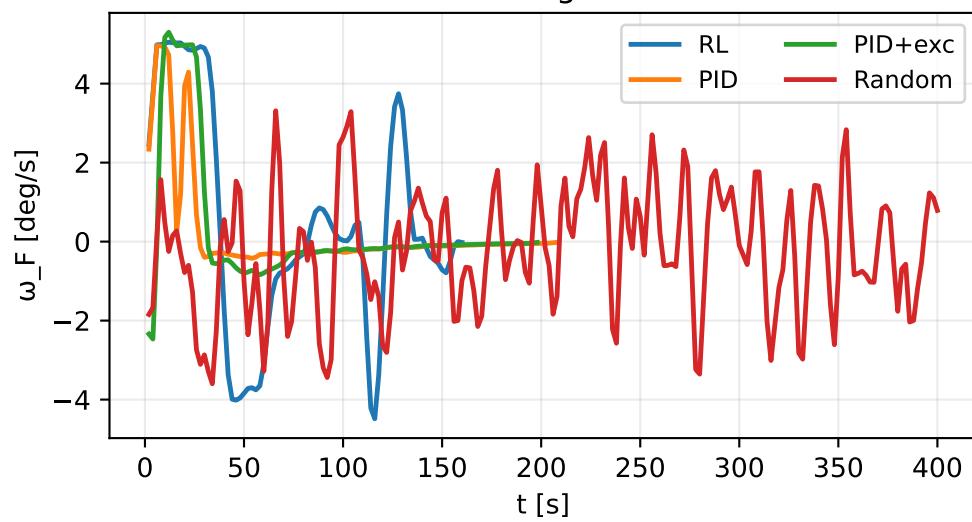
Follower speed



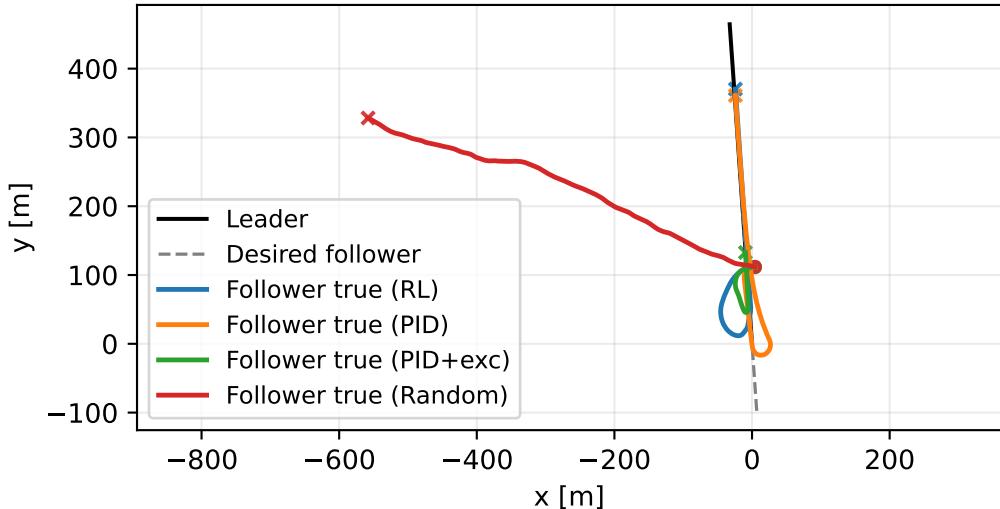
Follower course/heading



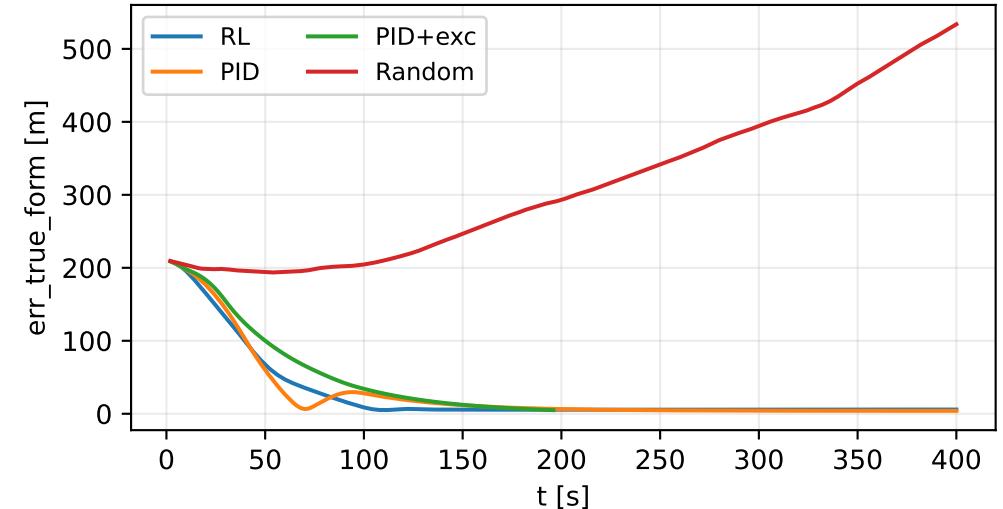
Follower angular rate



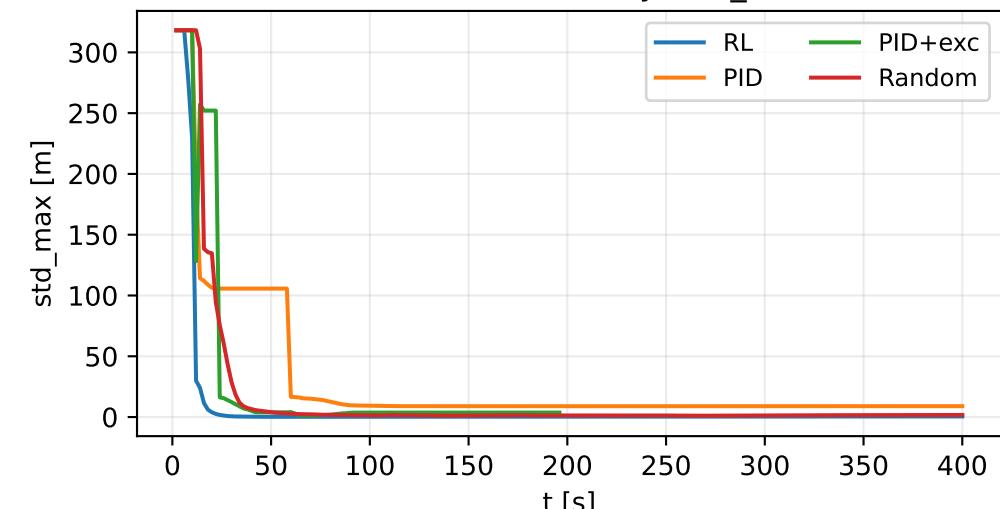
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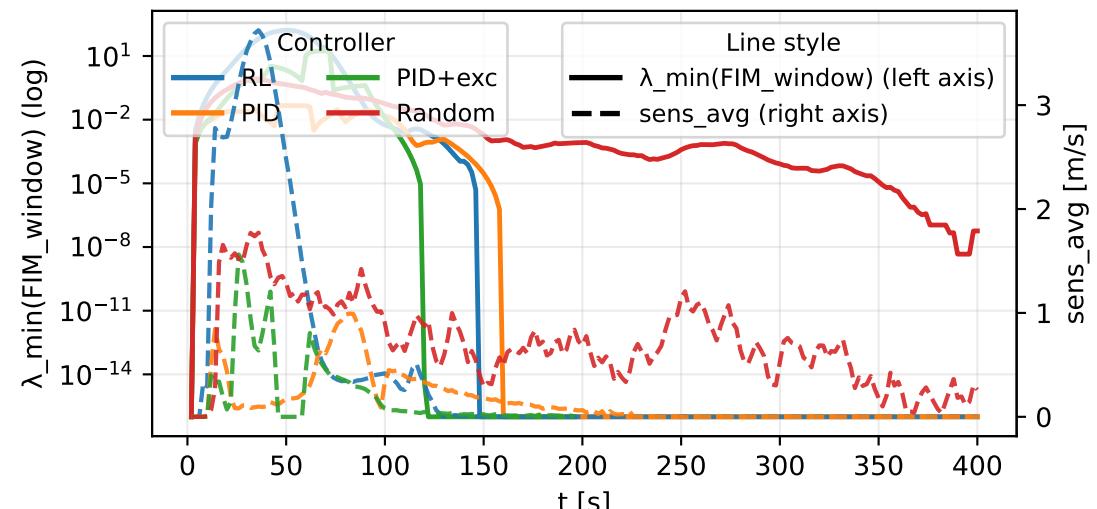
TRUE formation error



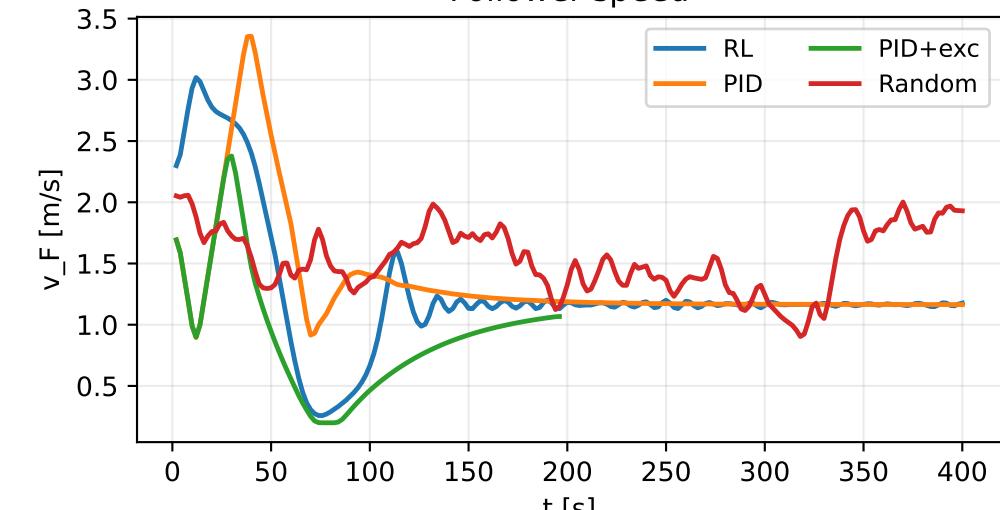
Estimator uncertainty (std_max)



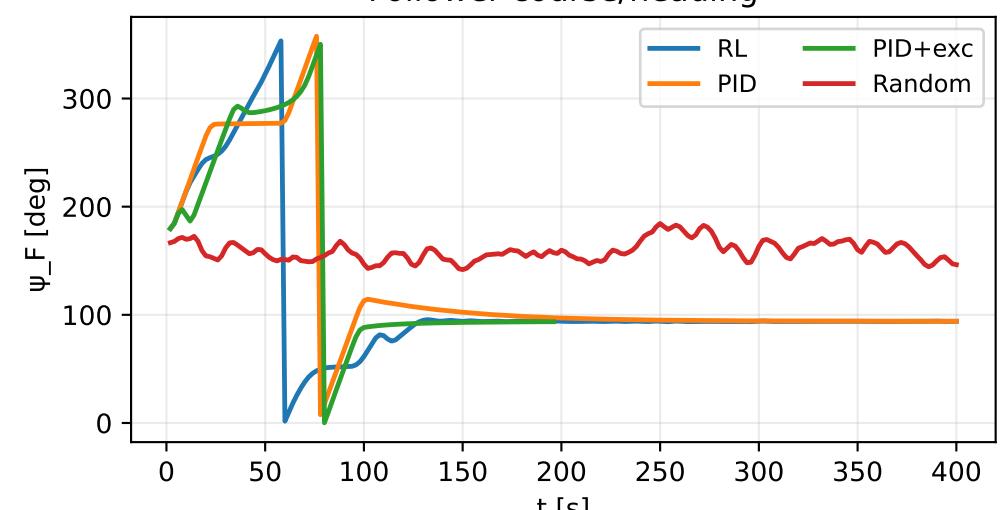
Information and excitation



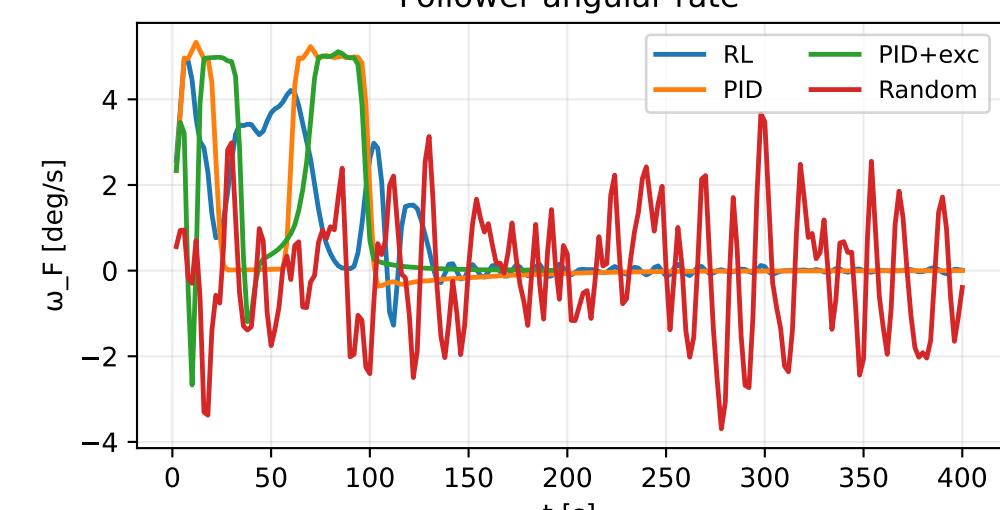
Follower speed



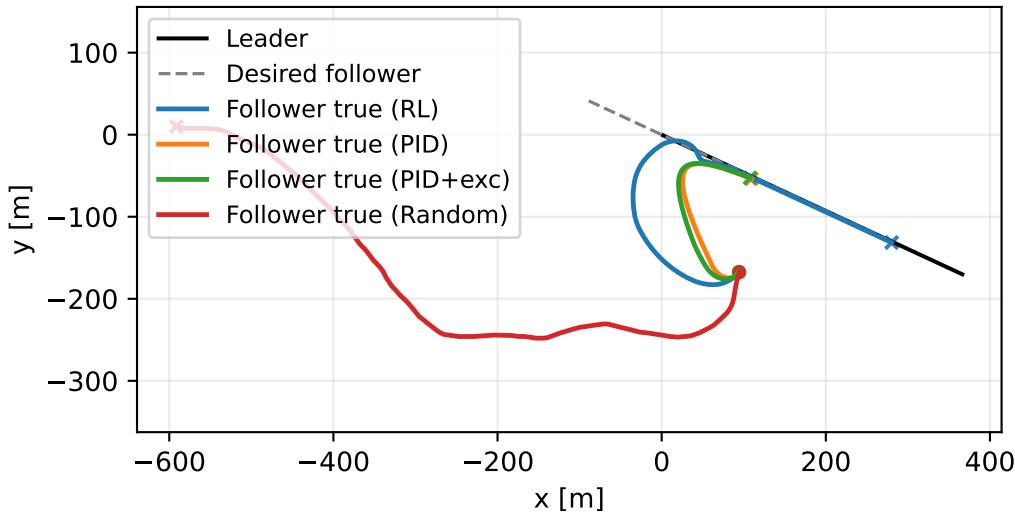
Follower course/heading



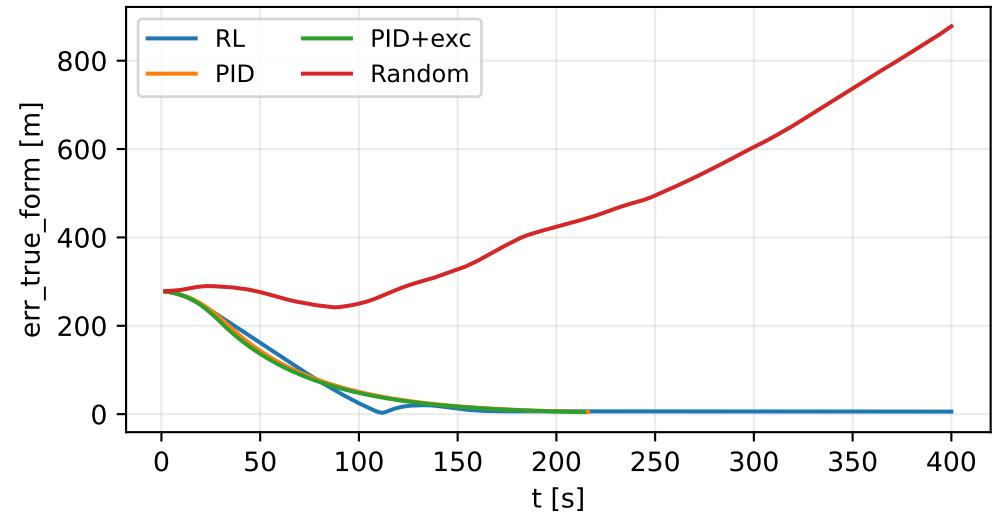
Follower angular rate



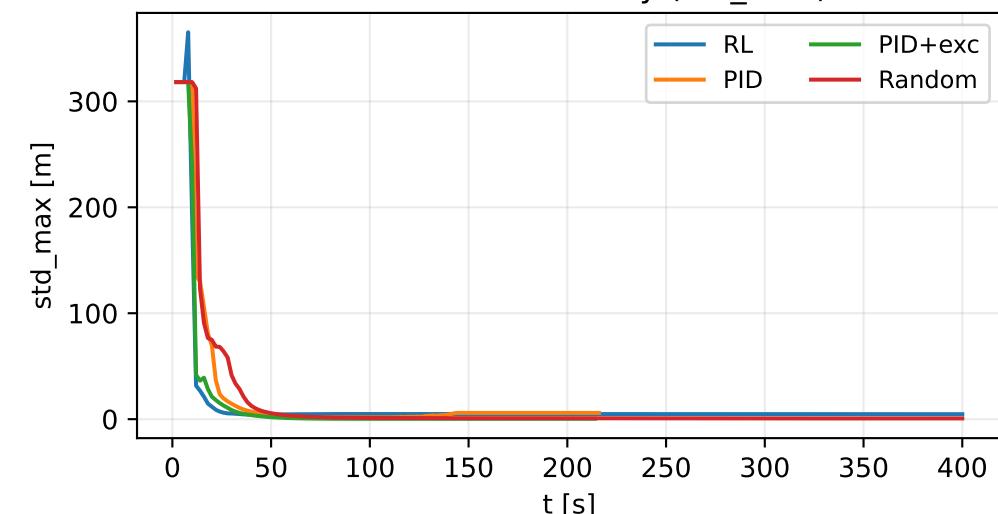
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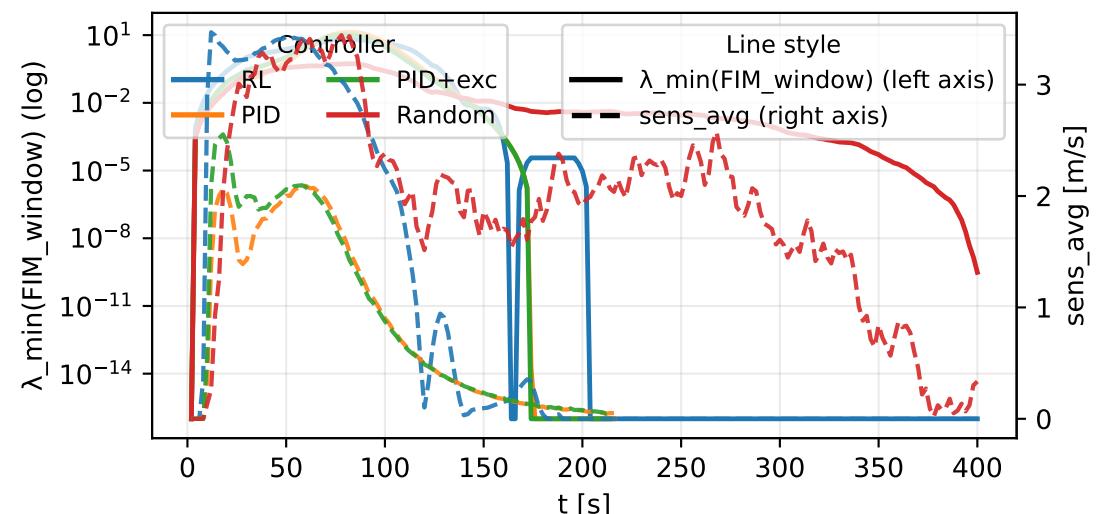
TRUE formation error



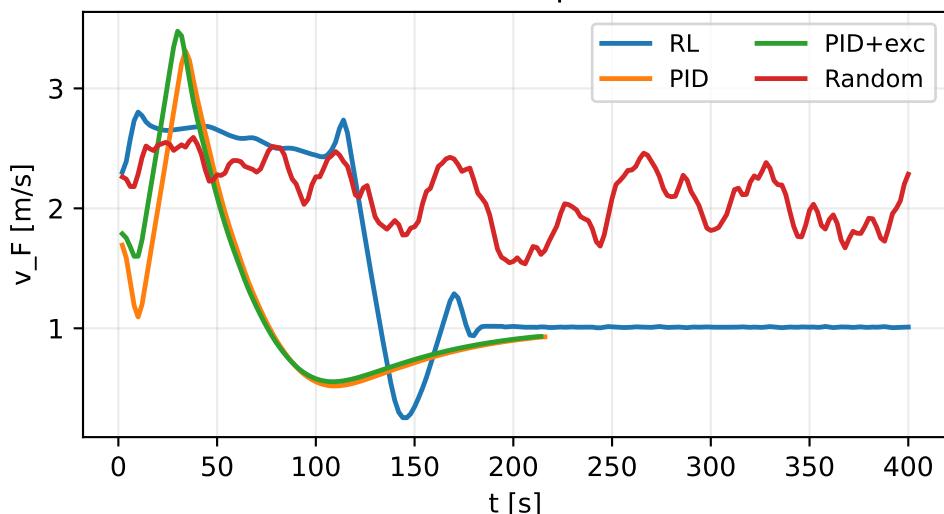
Estimator uncertainty (std_max)



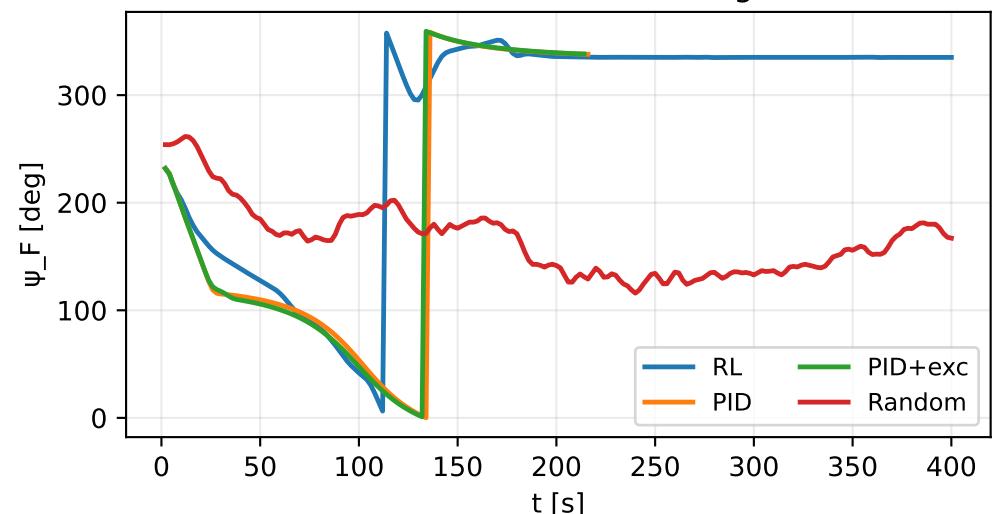
Information and excitation



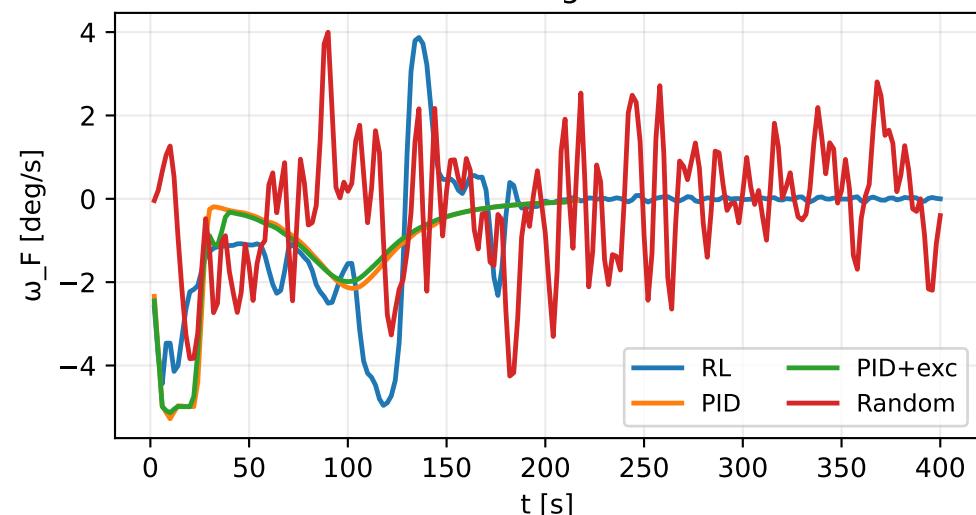
Follower speed



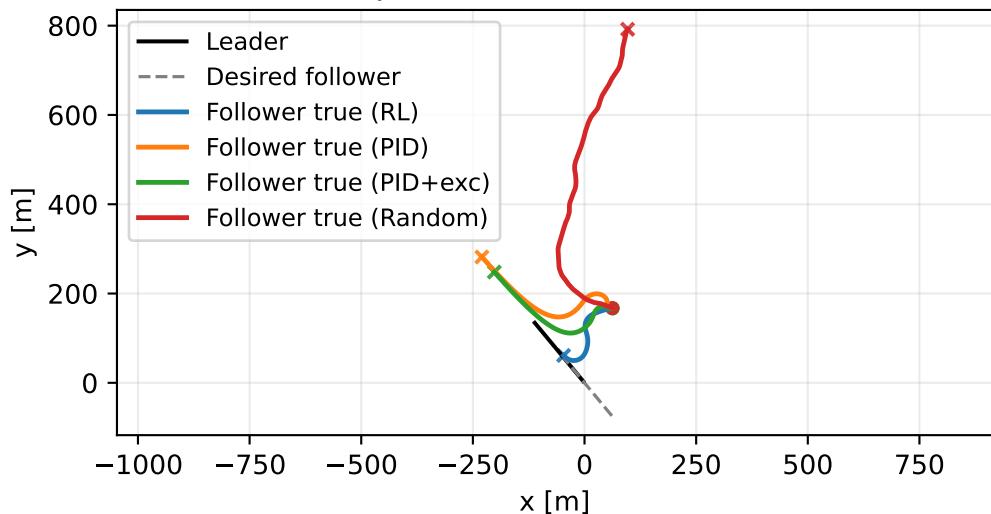
Follower course/heading



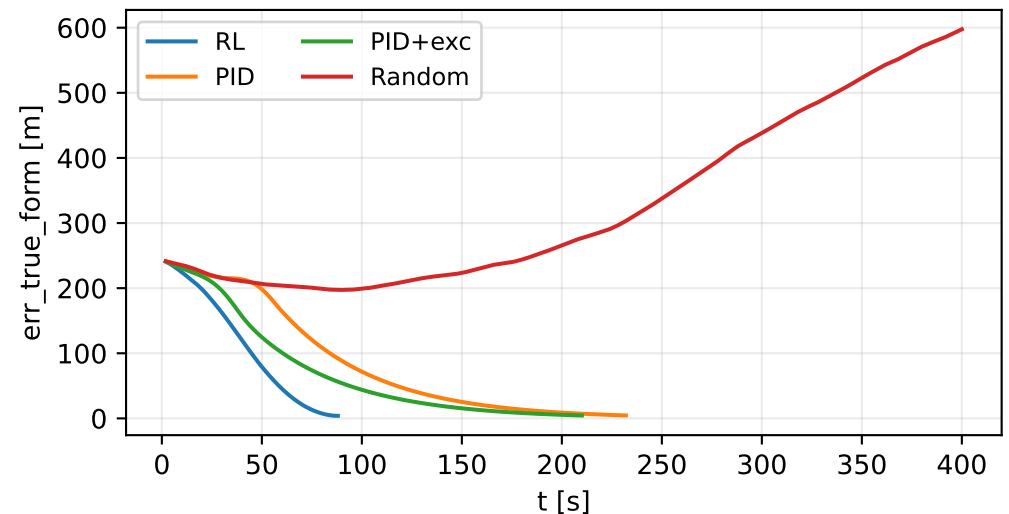
Follower angular rate



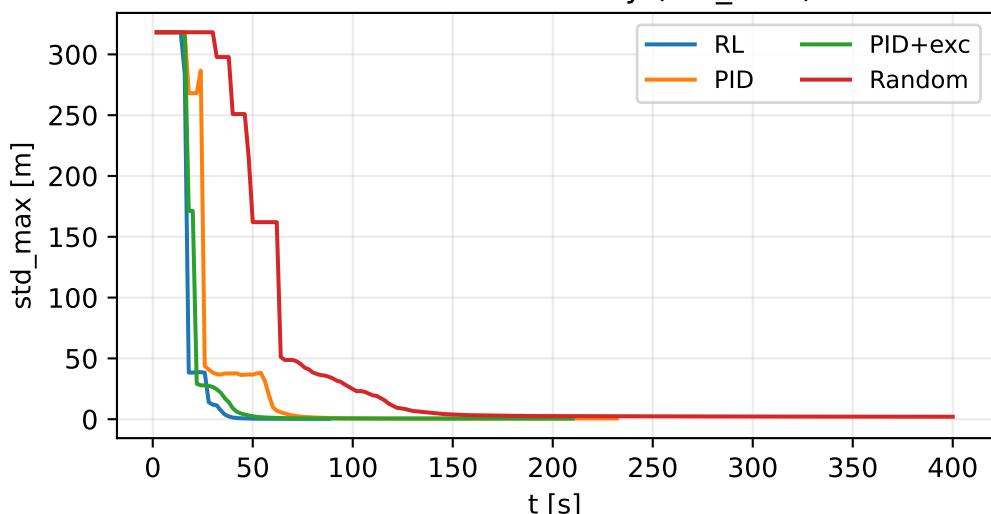
Trajectories (matched seed)



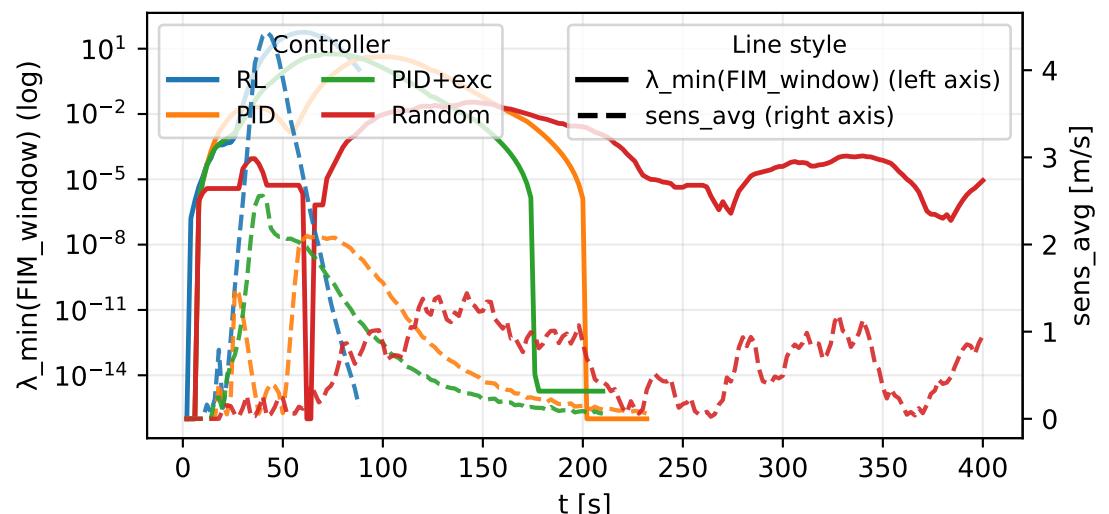
TRUE formation error



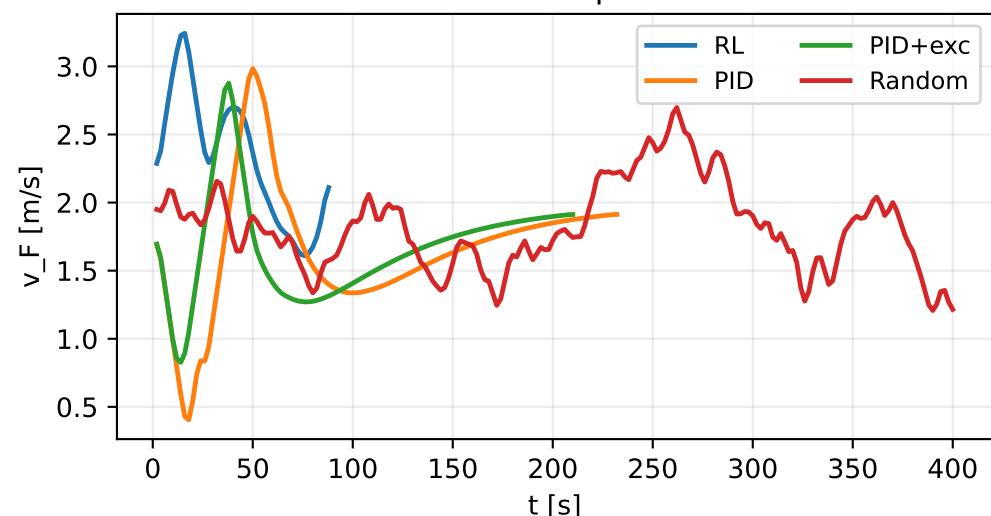
Estimator uncertainty (std_max)



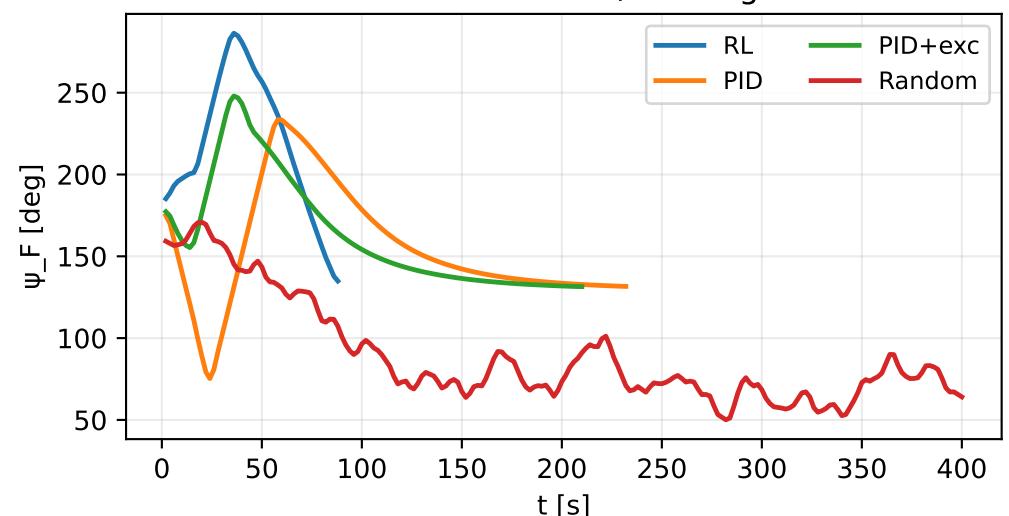
Information and excitation



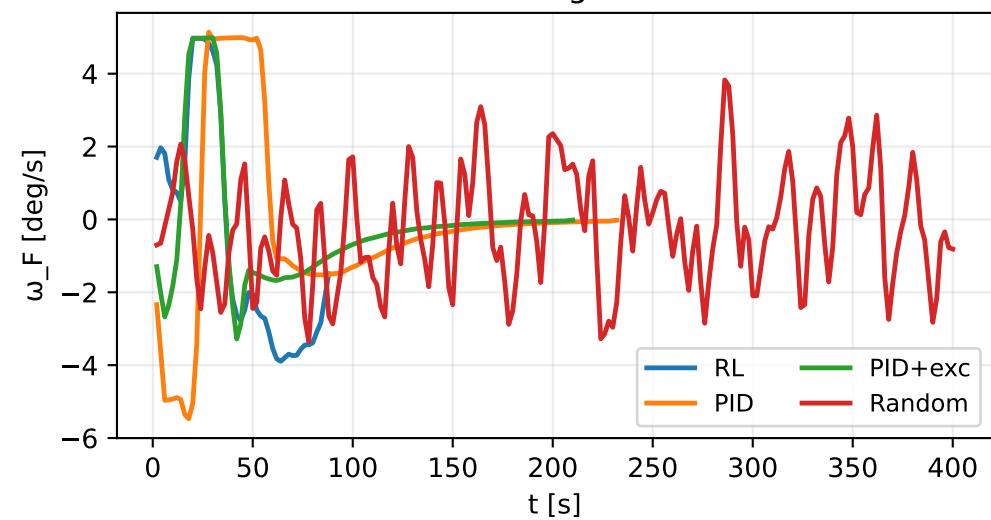
Follower speed



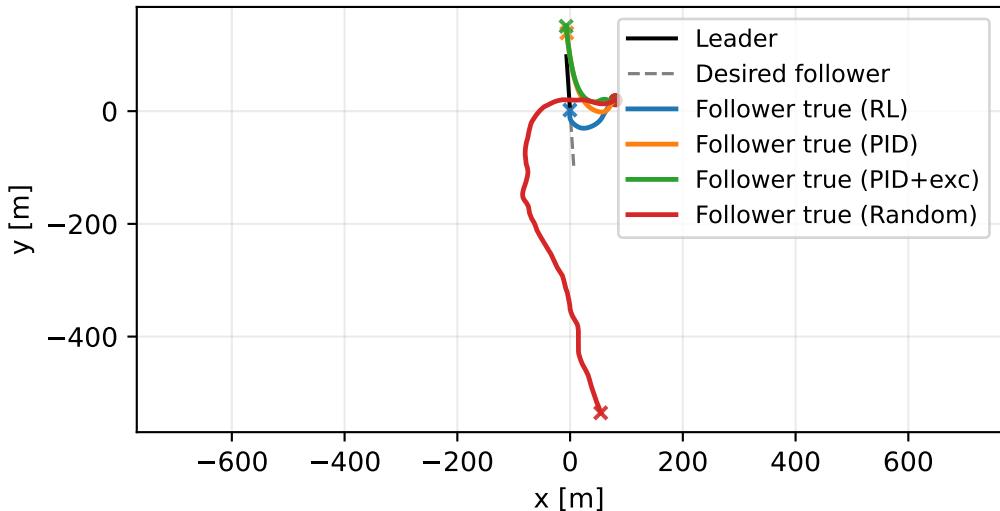
Follower course/heading



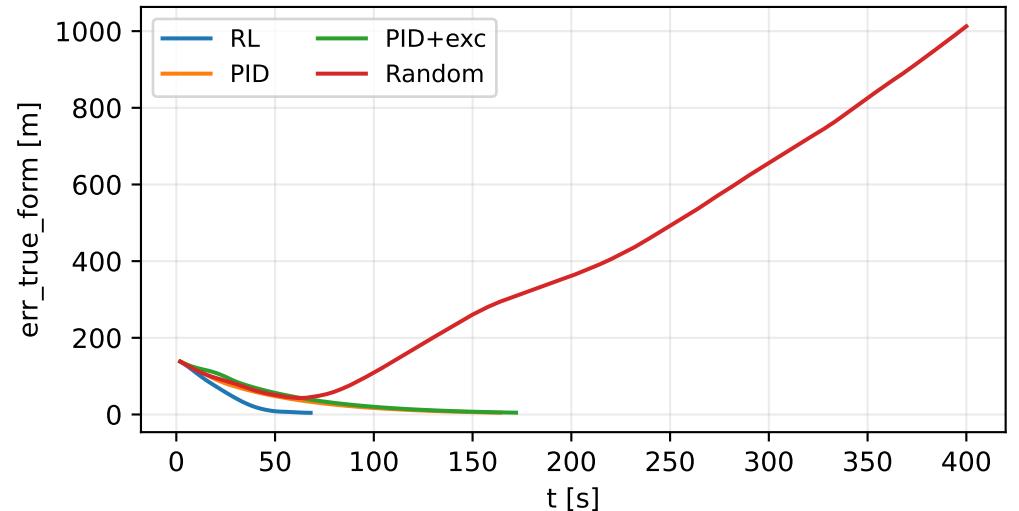
Follower angular rate



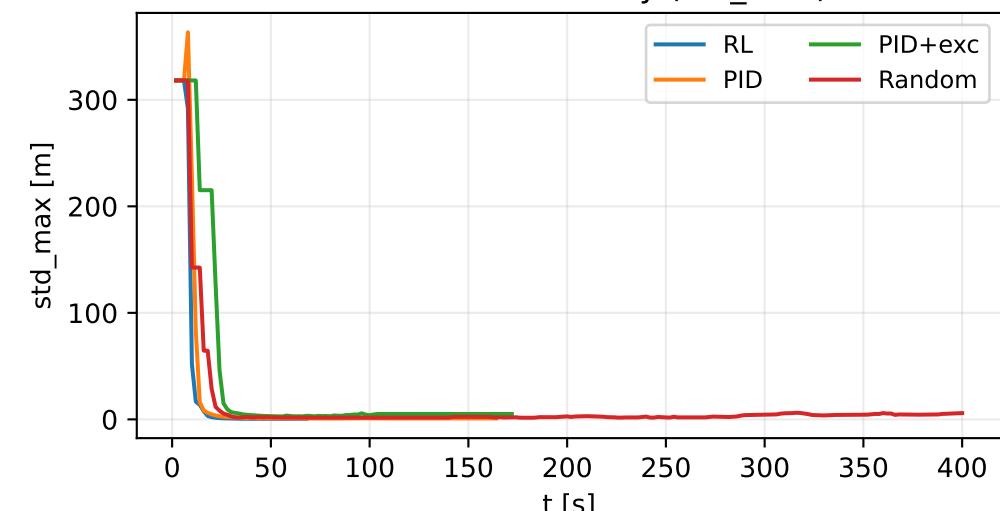
Trajectories (matched seed)



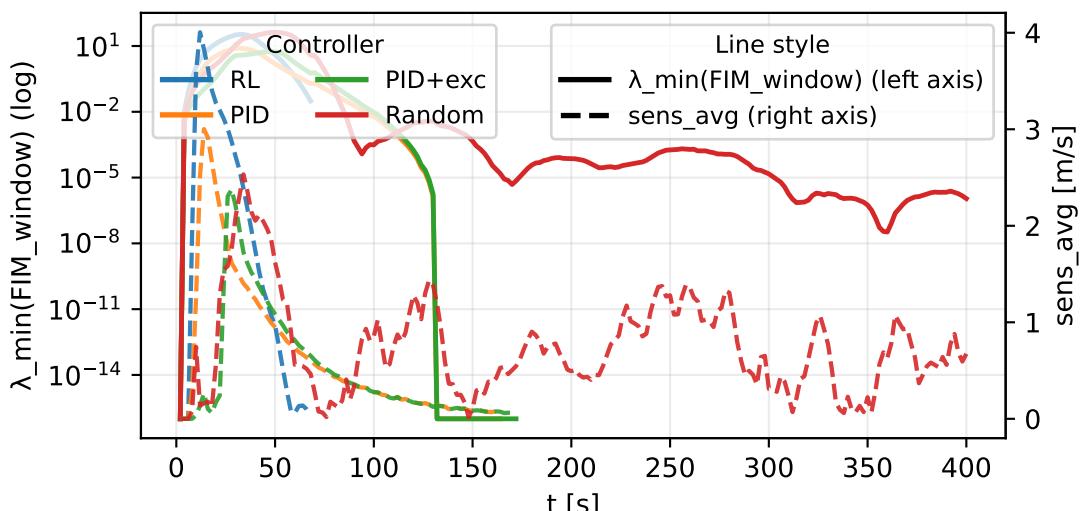
TRUE formation error



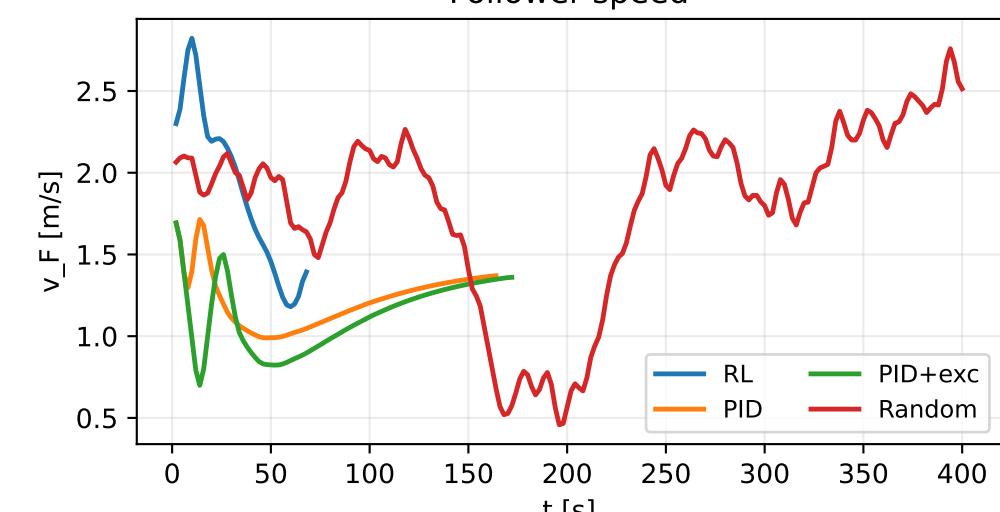
Estimator uncertainty (std_max)



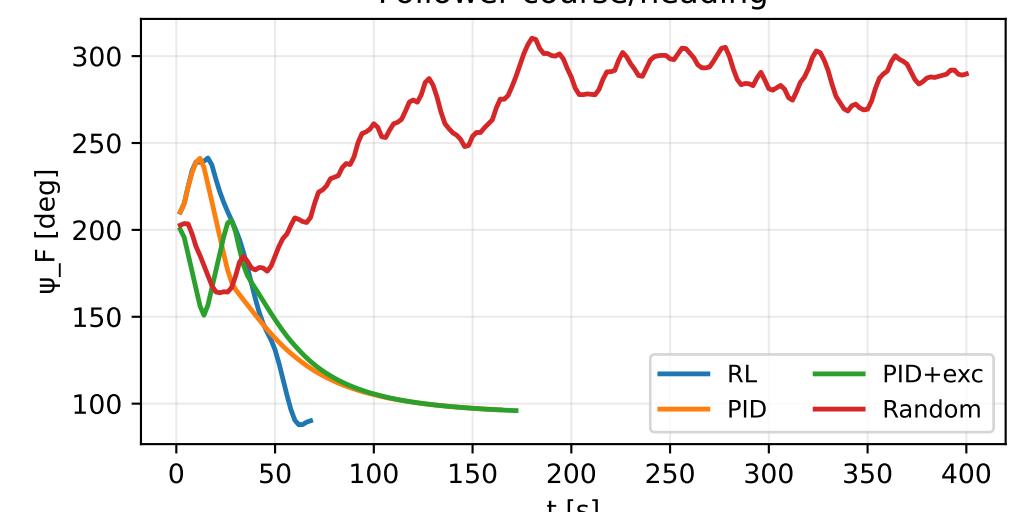
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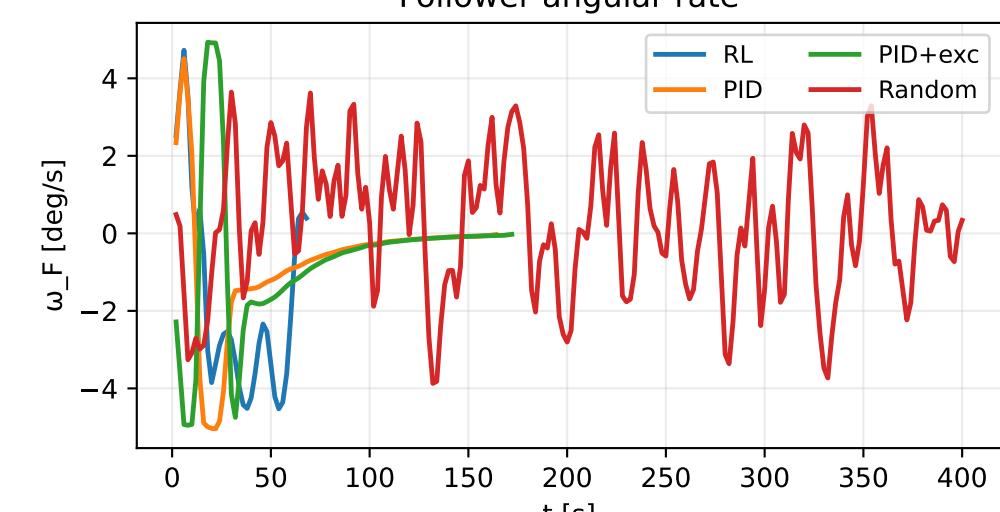
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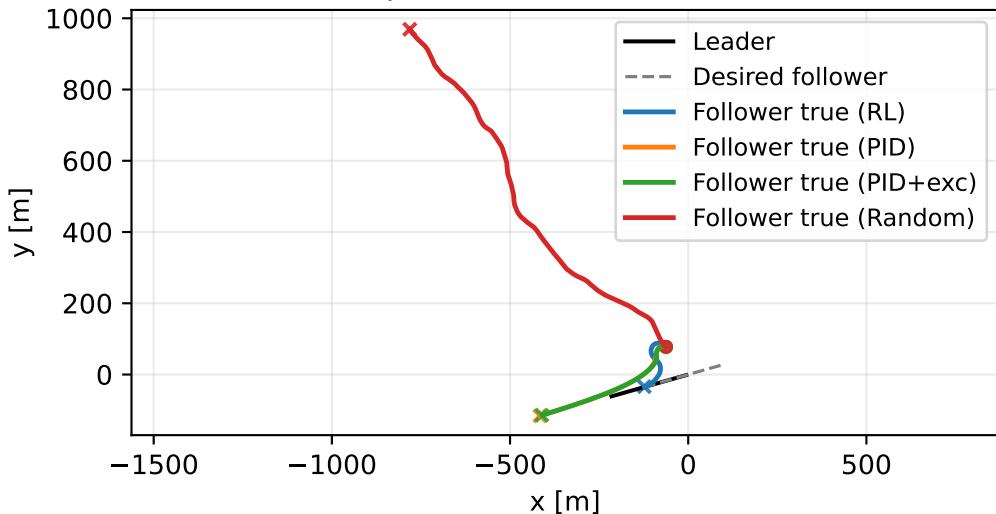
Follower course/heading



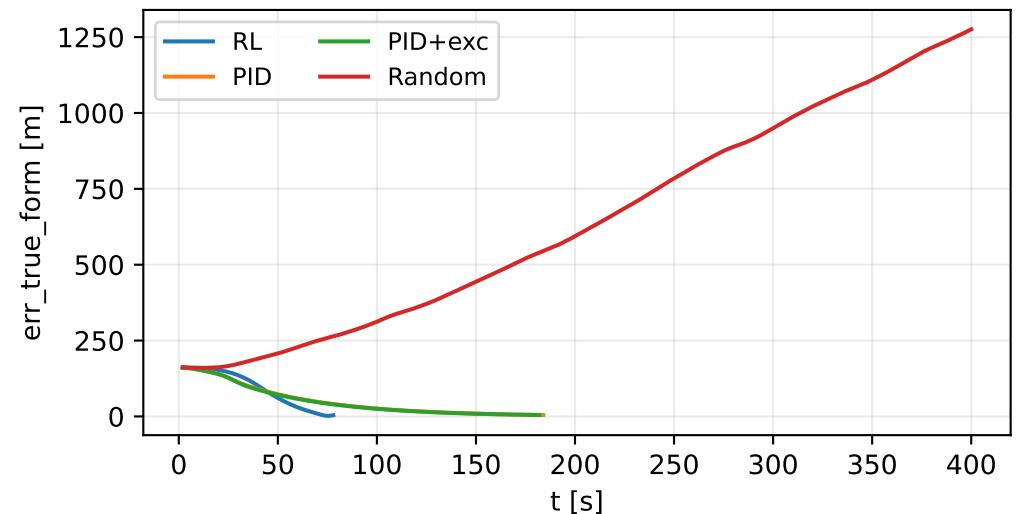
Follower angular rate



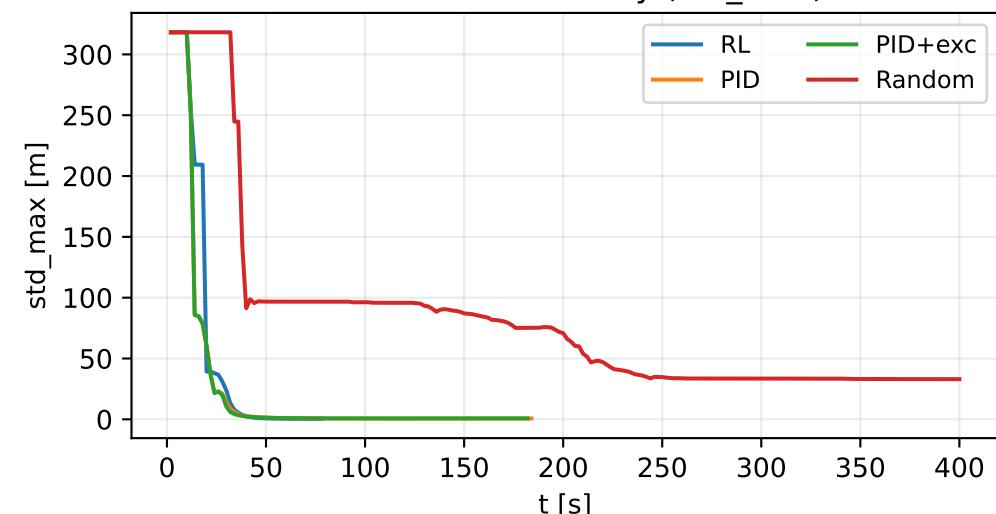
Trajectories (matched seed)



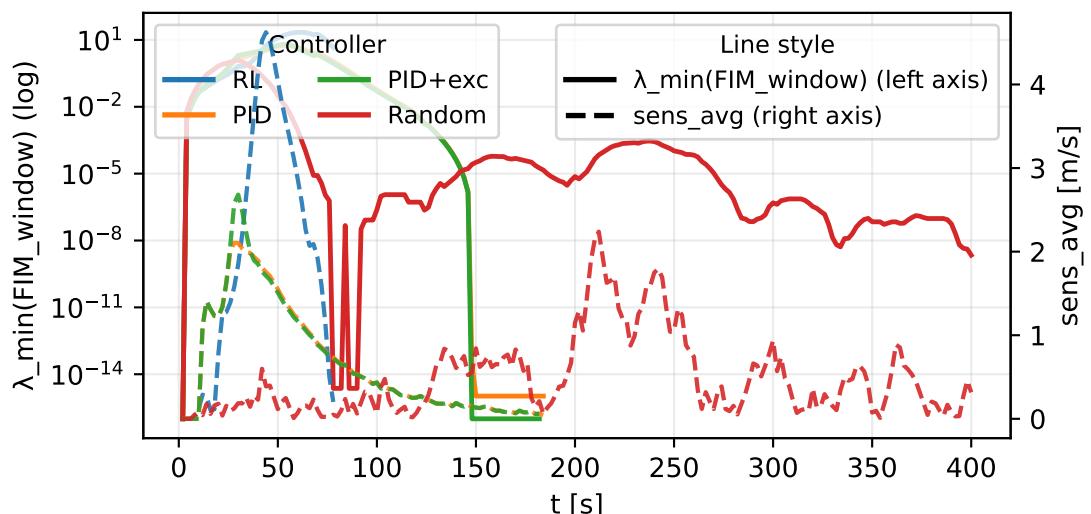
TRUE formation error



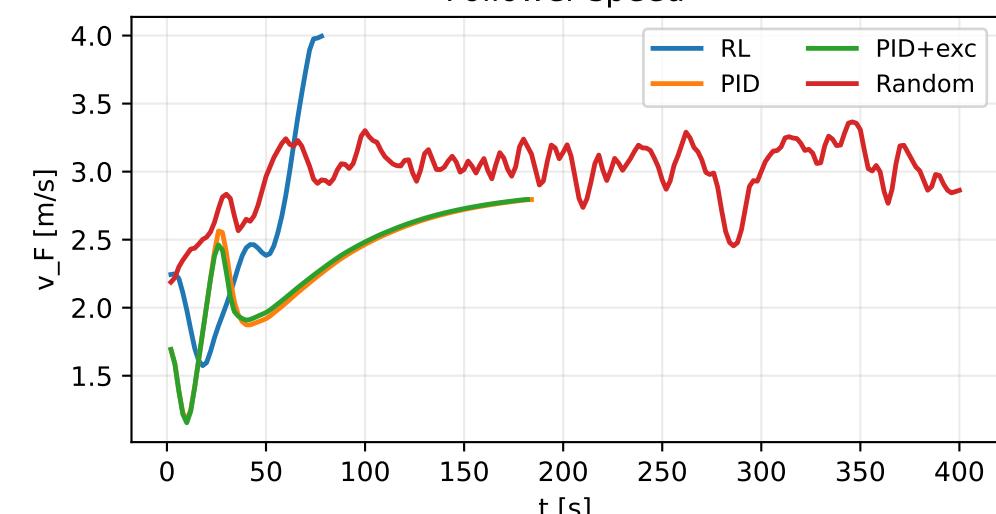
Estimator uncertainty (std_max)



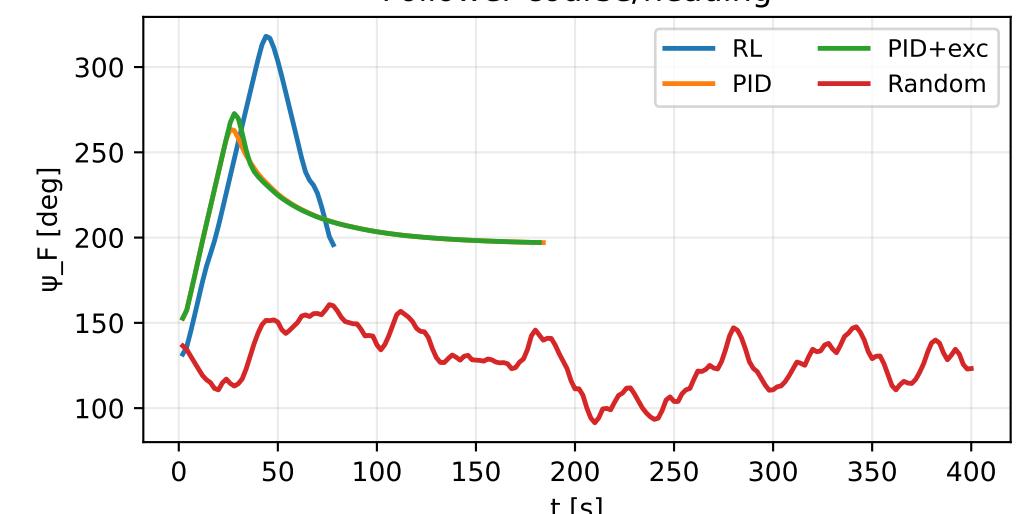
Information and excitation



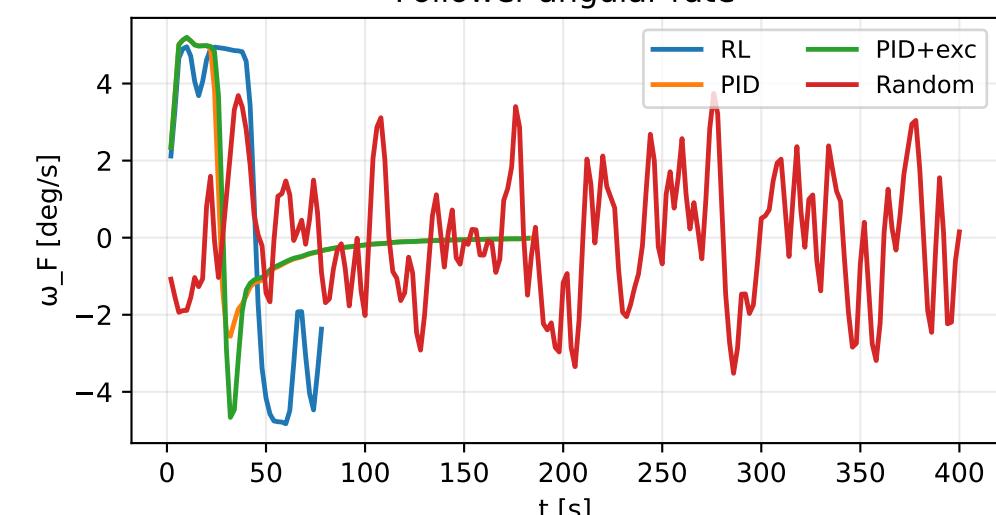
Follower speed



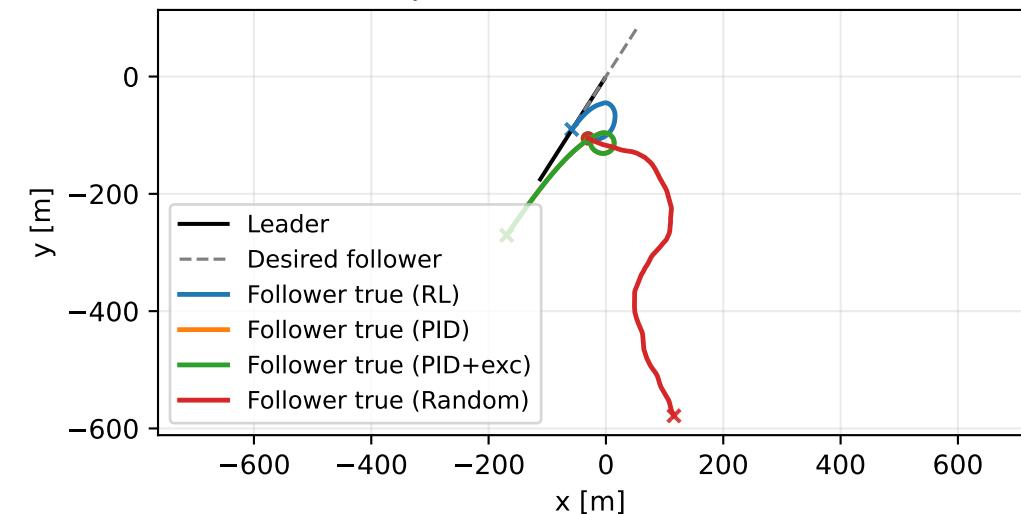
Follower course/heading



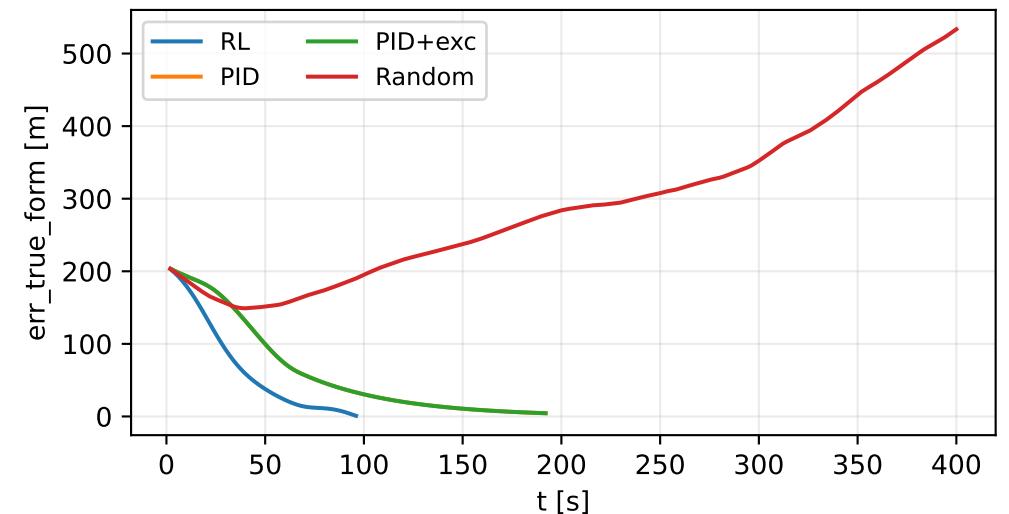
Follower angular rate



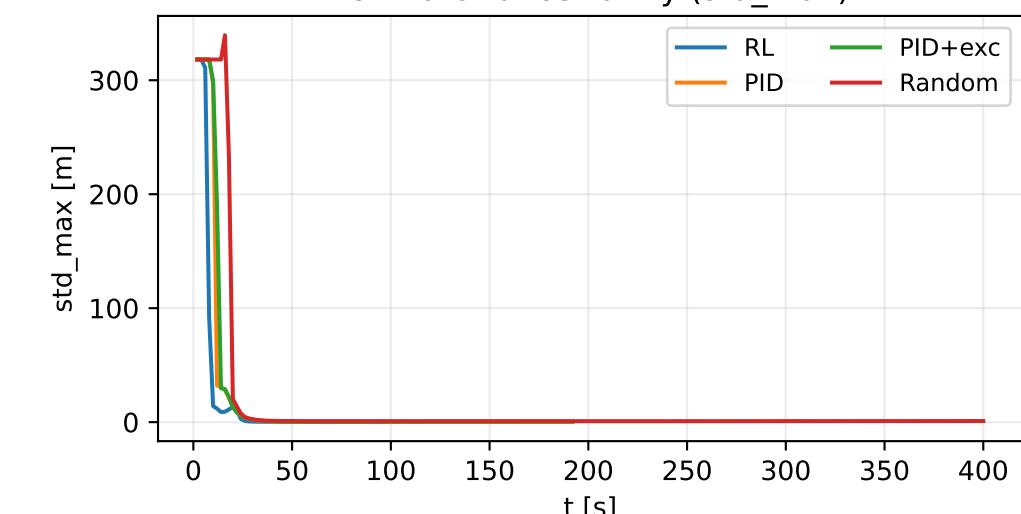
Trajectories (matched seed)



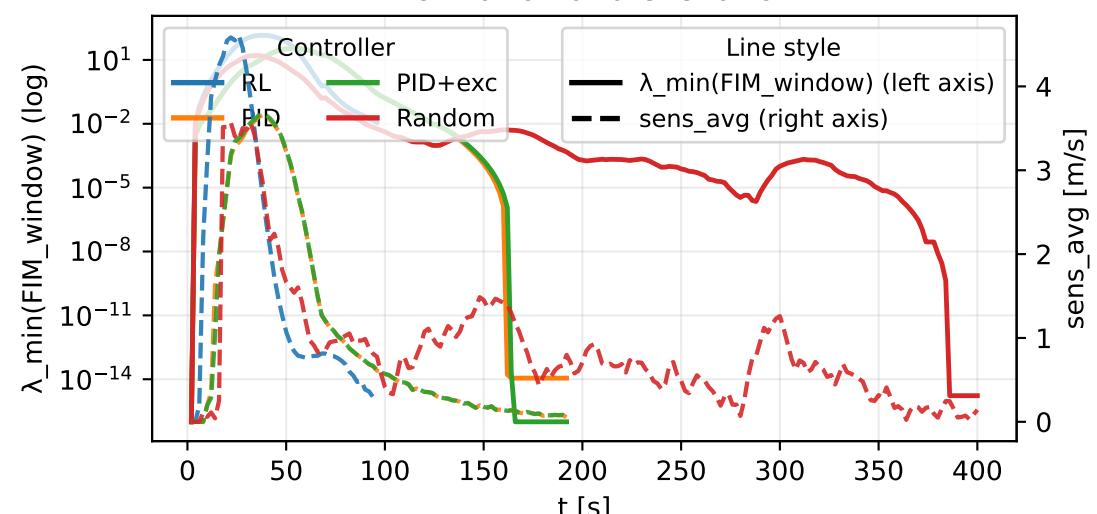
TRUE formation error



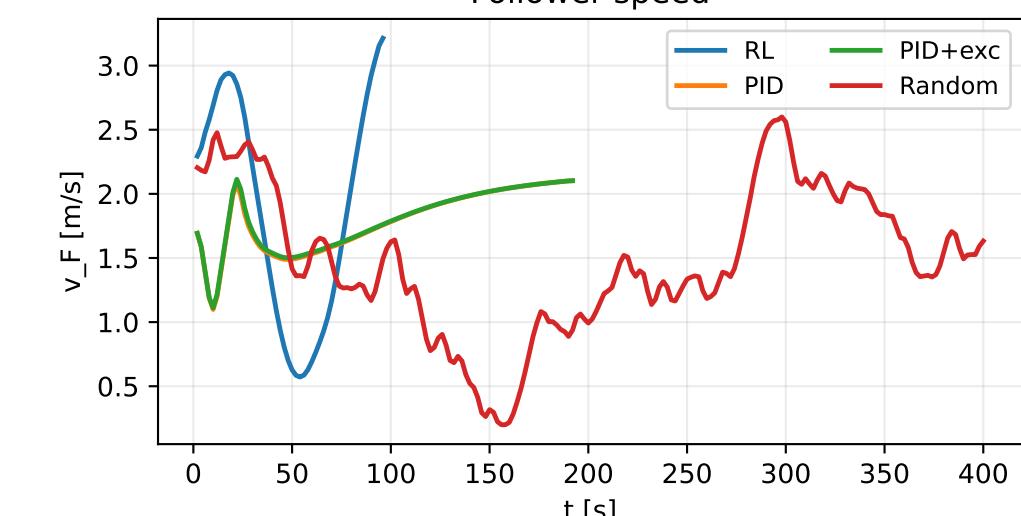
Estimator uncertainty (std_max)



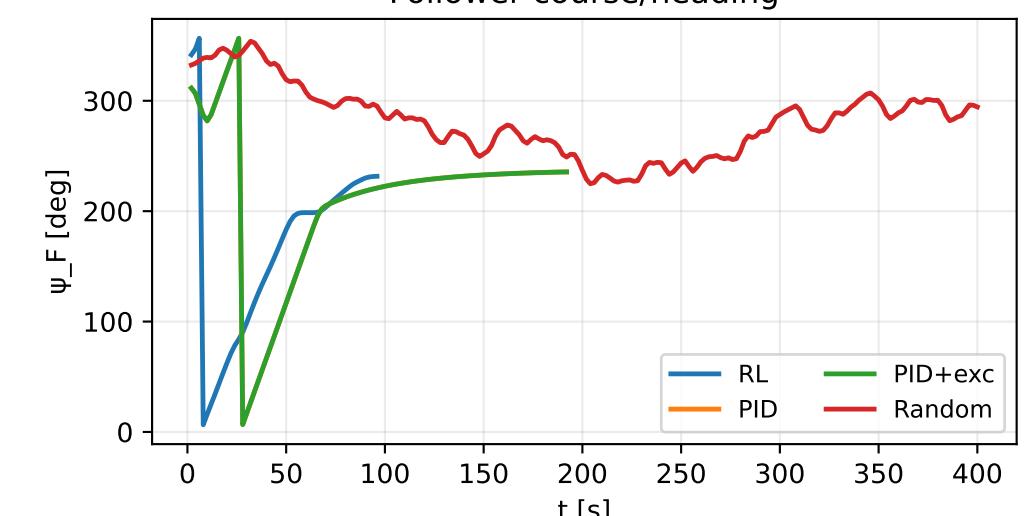
Information and excitation



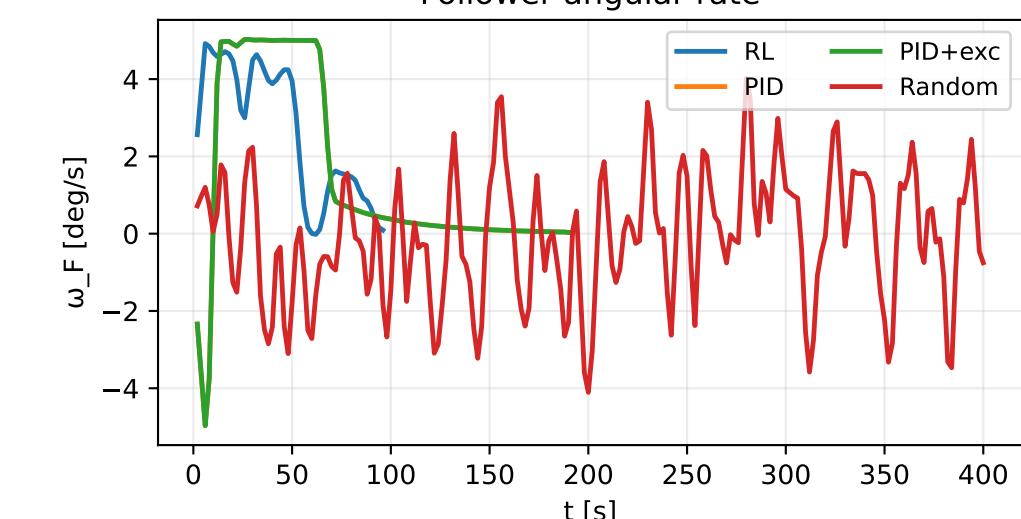
Follower speed



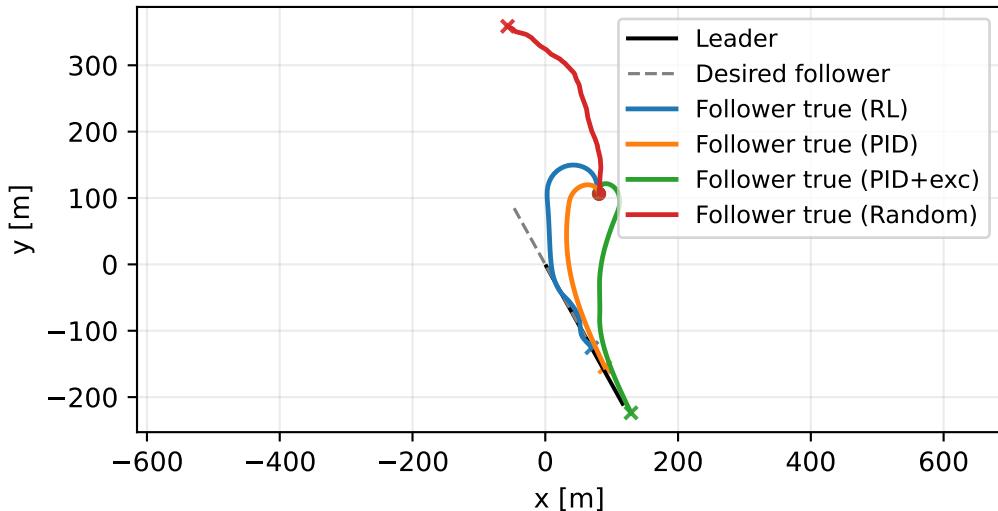
Follower course/heading



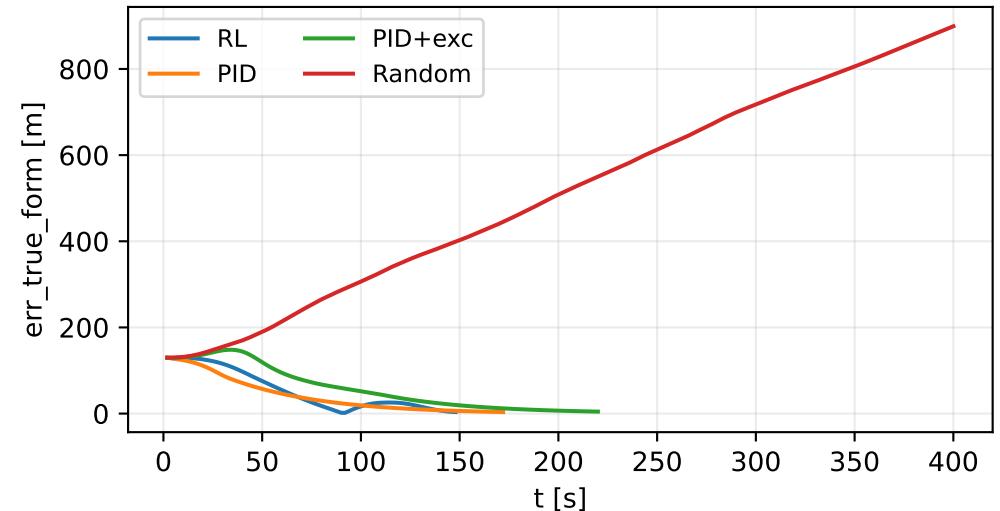
Follower angular rate



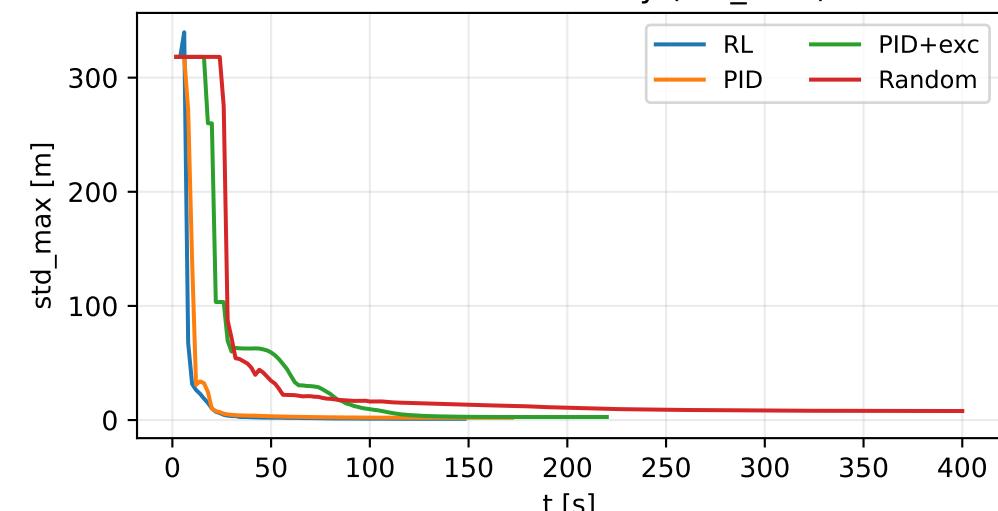
Trajectories (matched seed)



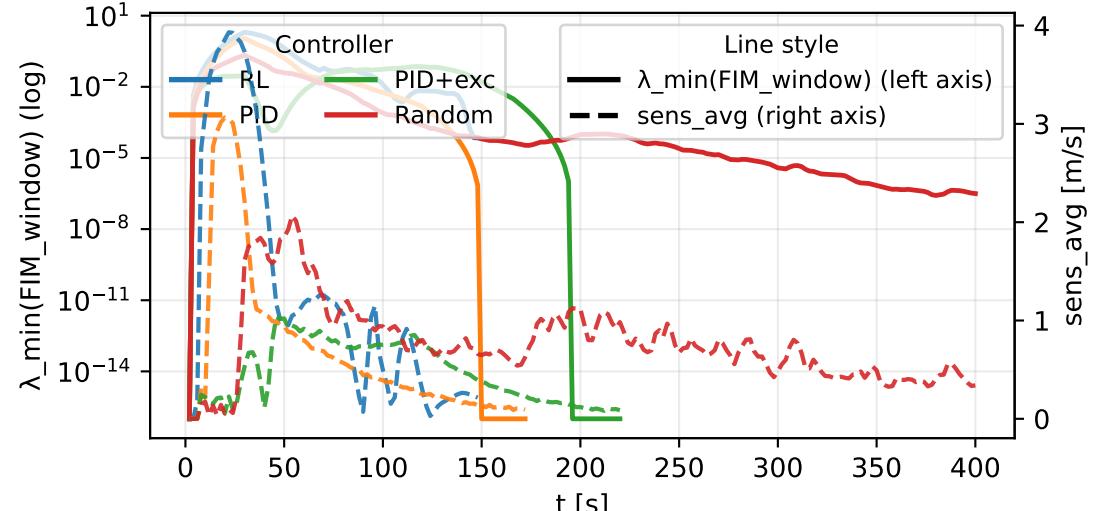
TRUE formation error



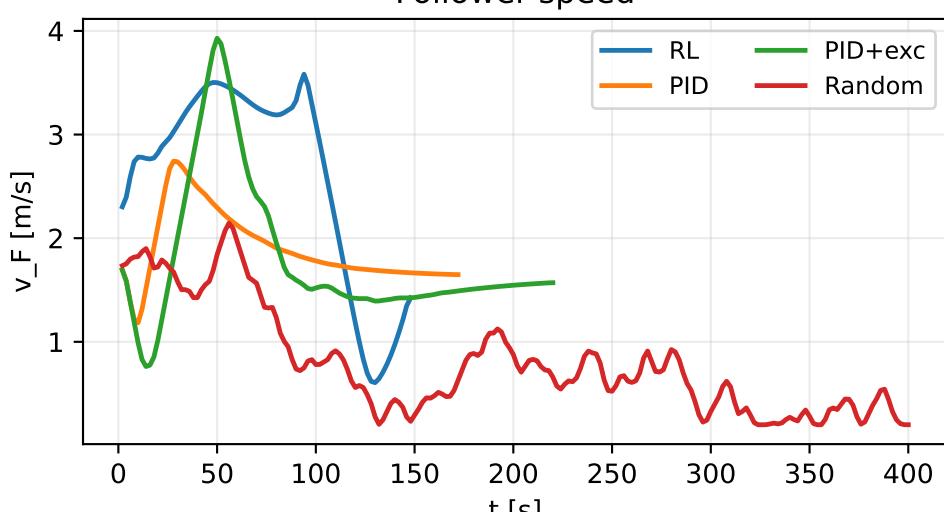
Estimator uncertainty (std_max)



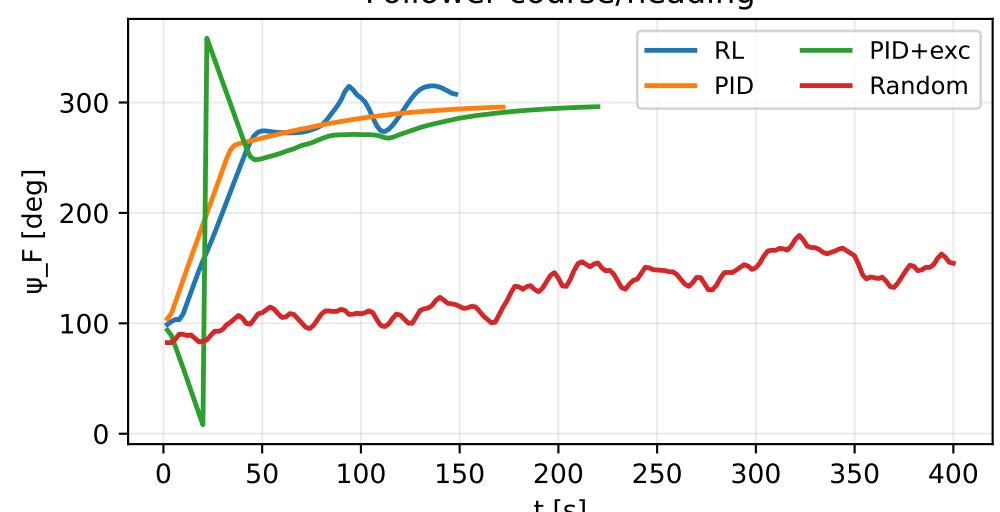
Information and excitation



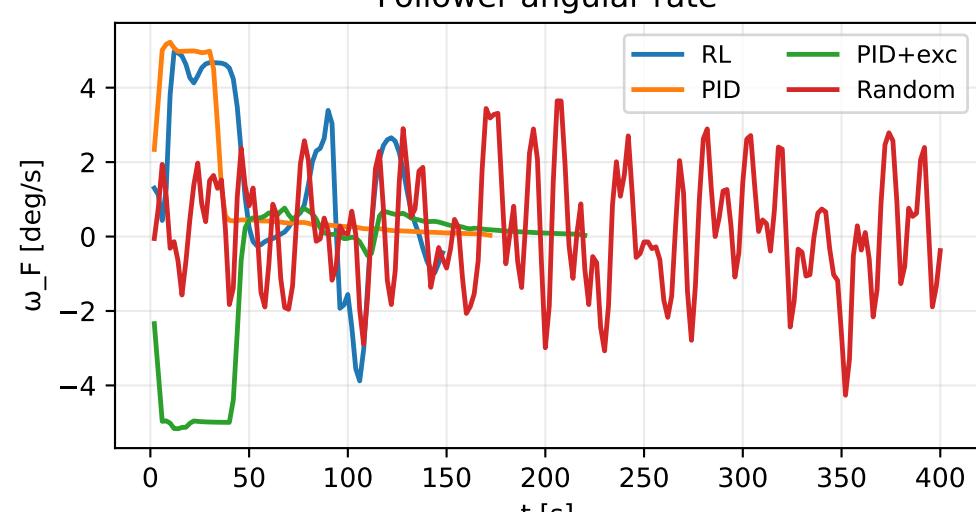
Follower speed



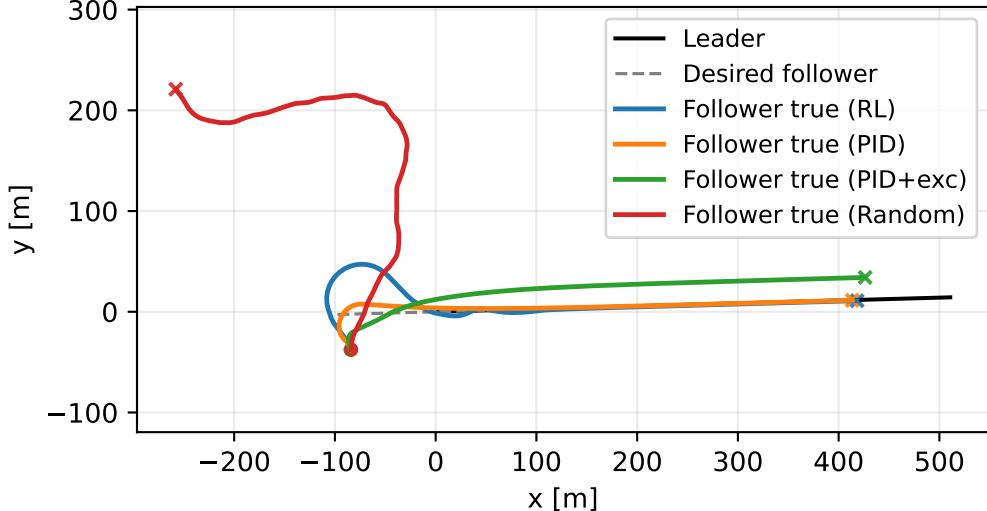
Follower course/heading



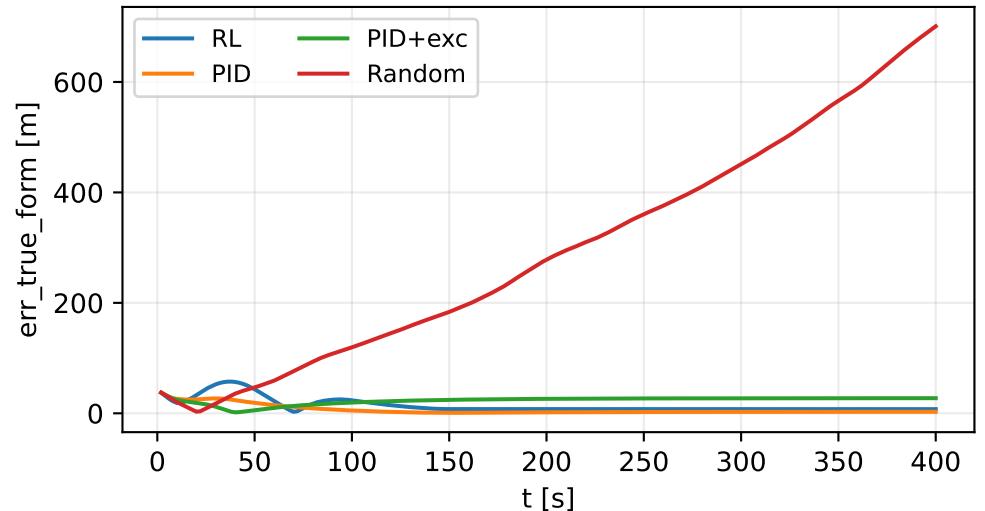
Follower angular rate



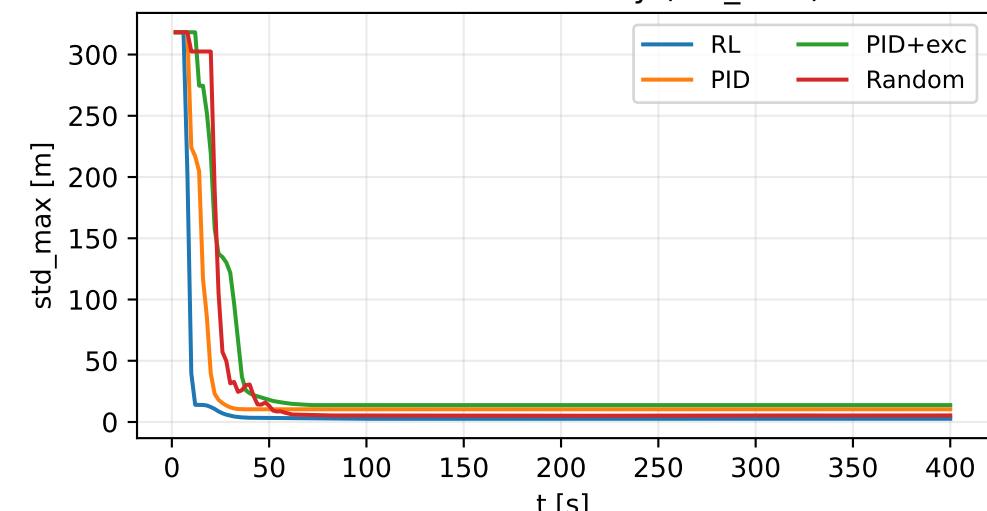
Trajectories (matched seed)



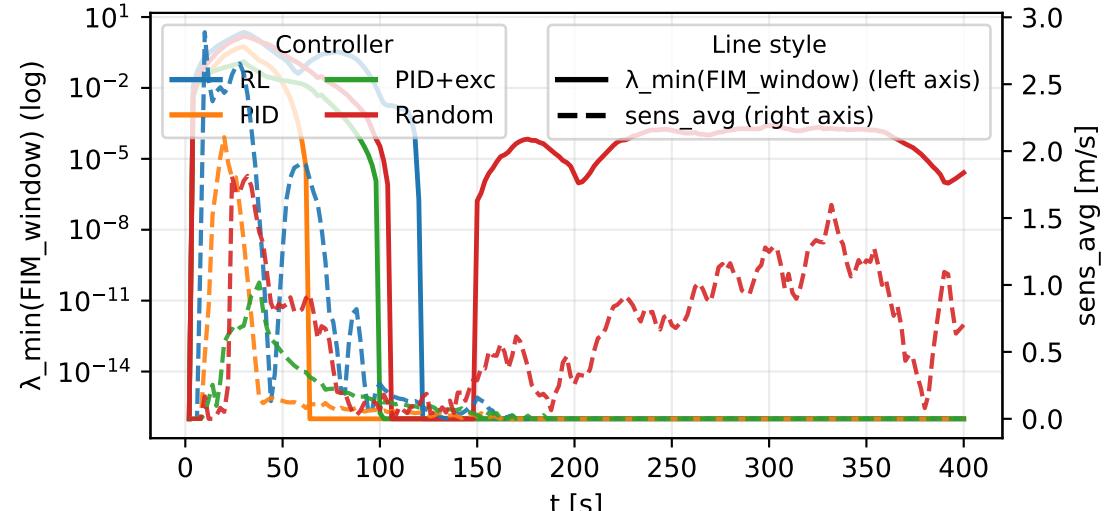
TRUE formation error



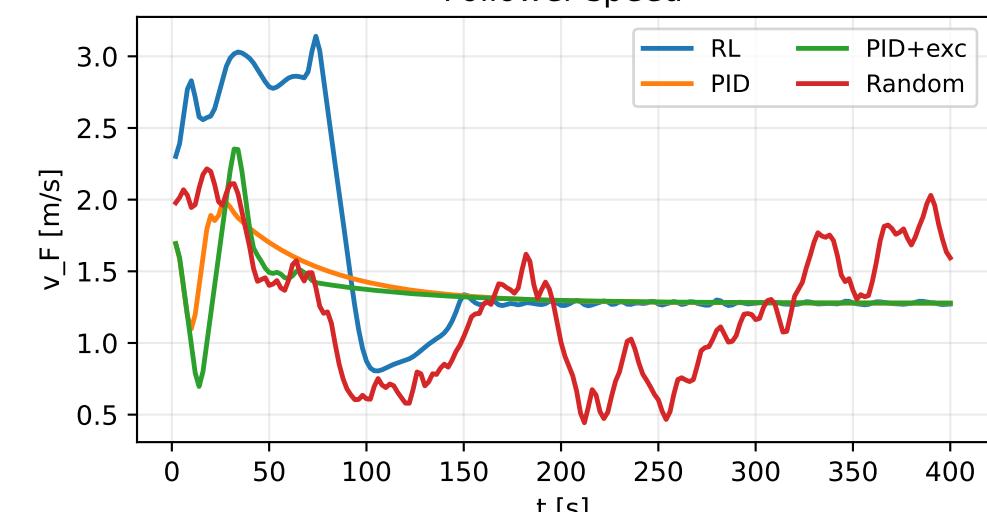
Estimator uncertainty (std_max)



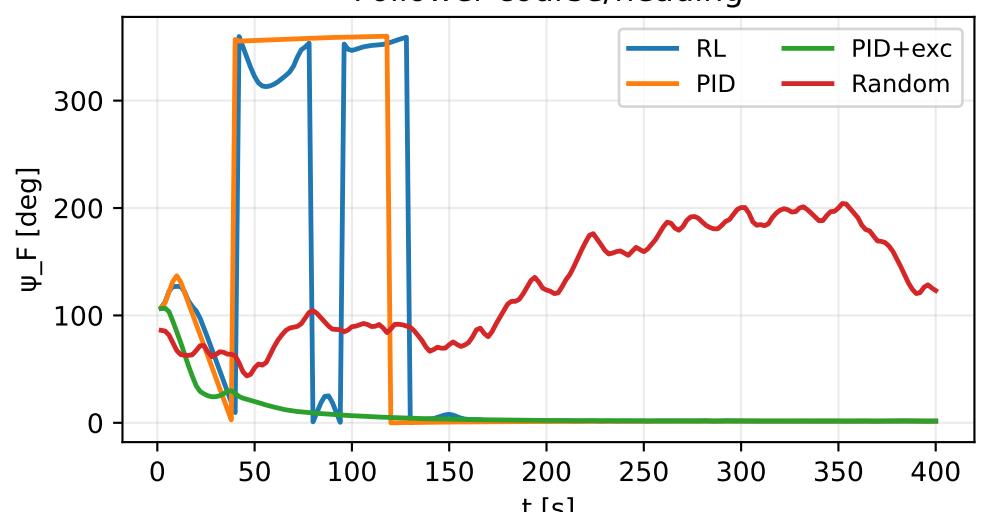
Information and excitation



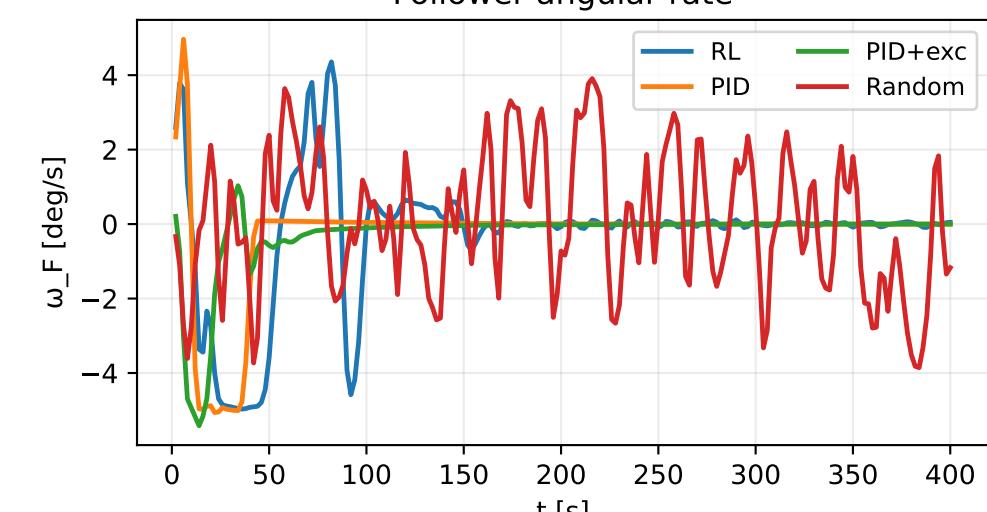
Follower speed



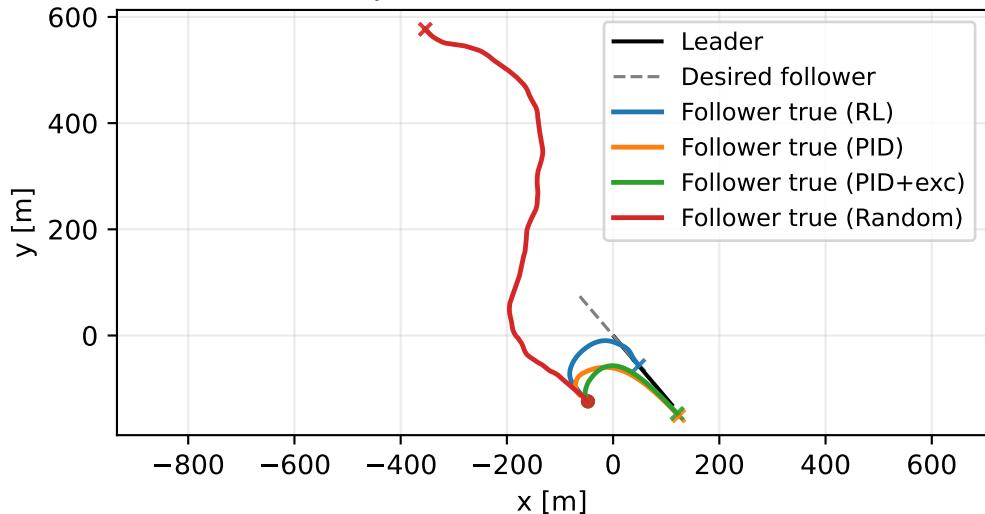
Follower course/heading



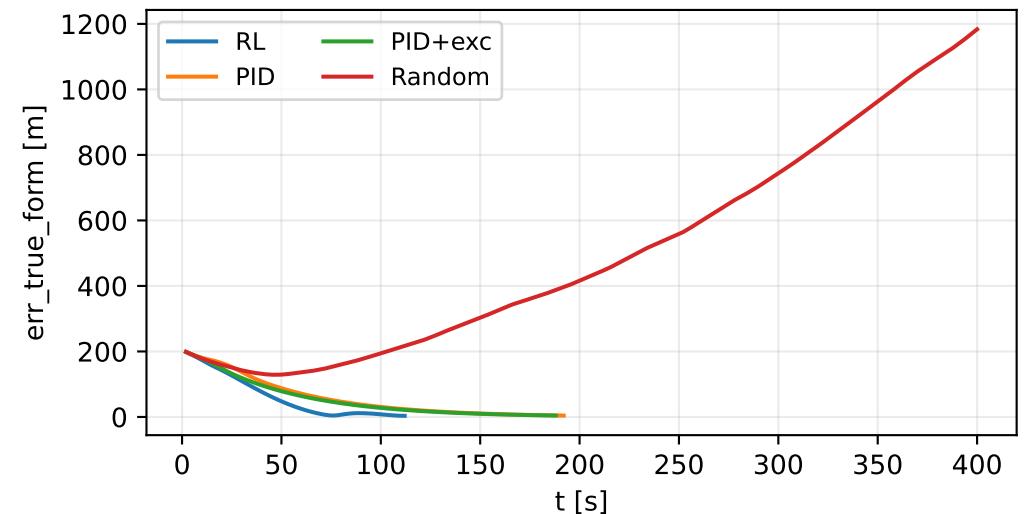
Follower angular rate



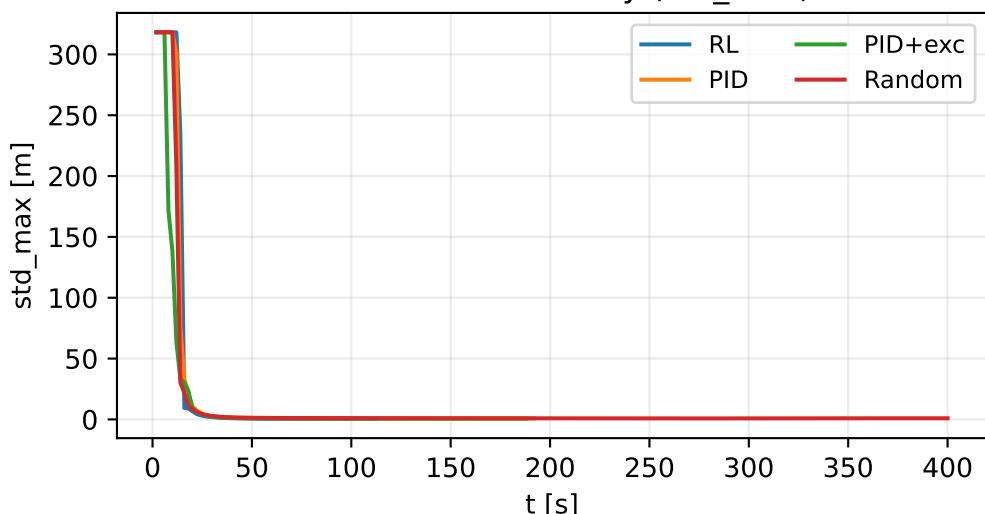
Trajectories (matched seed)



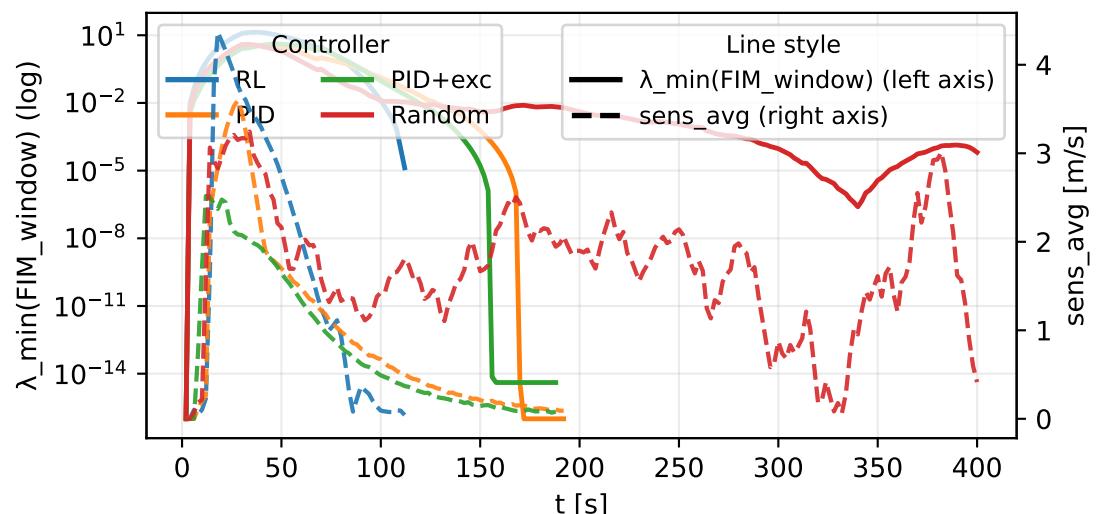
TRUE formation error



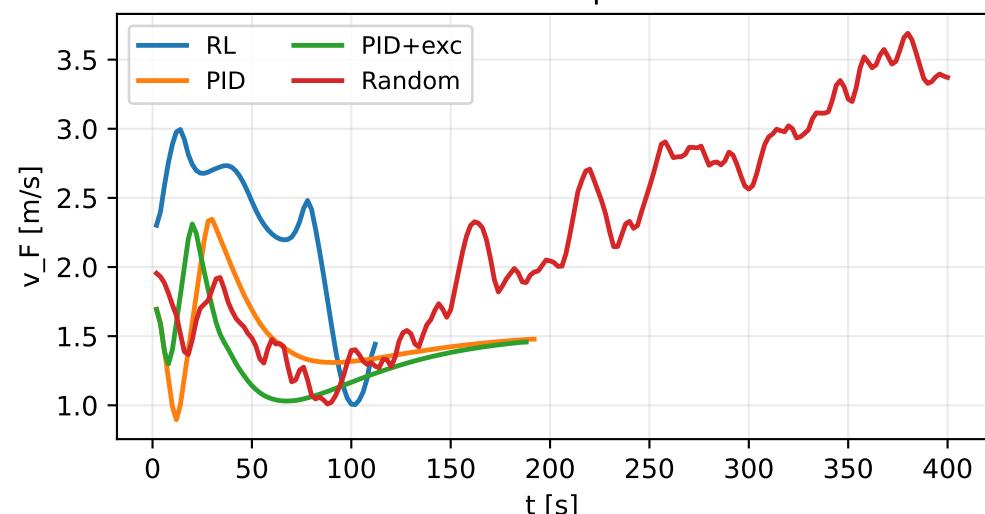
Estimator uncertainty (std_max)



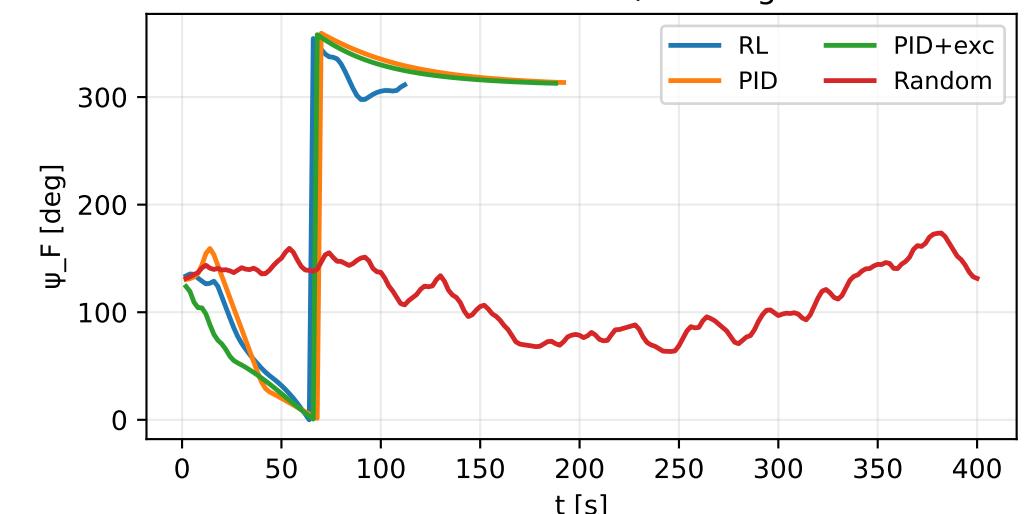
Information and excitation



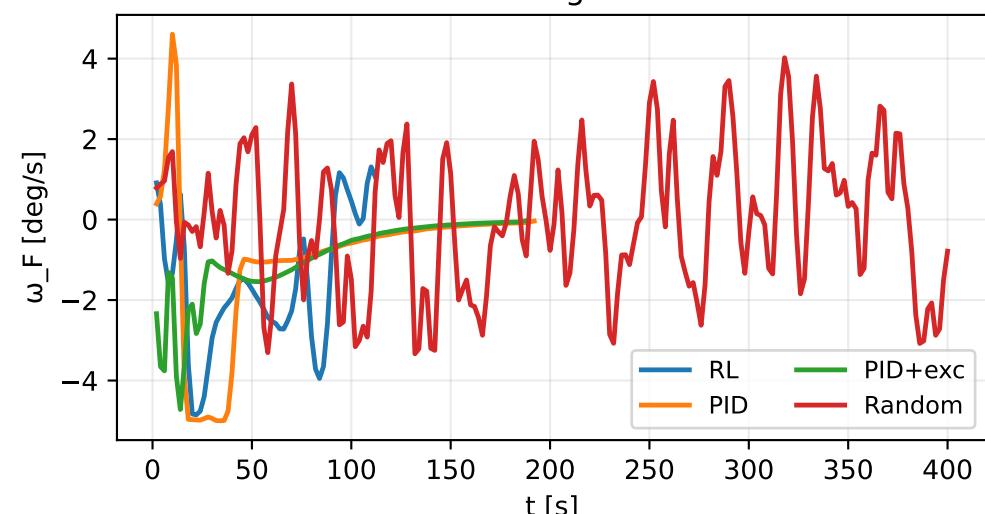
Follower speed



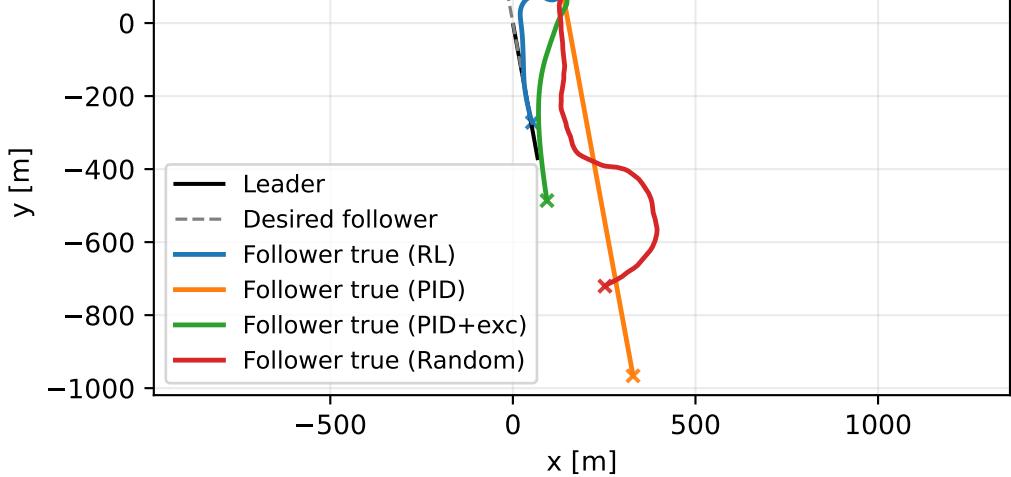
Follower course/heading



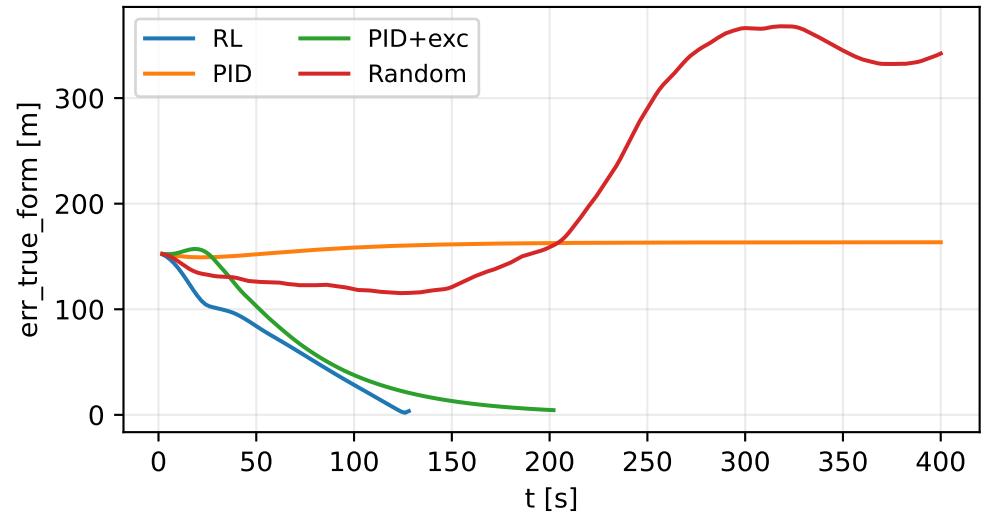
Follower angular rate



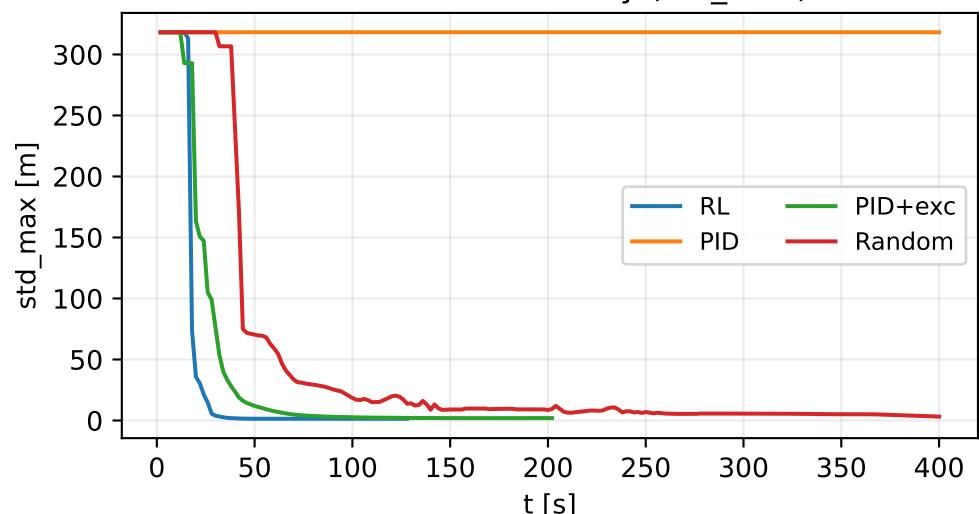
Trajectories (matched seed)



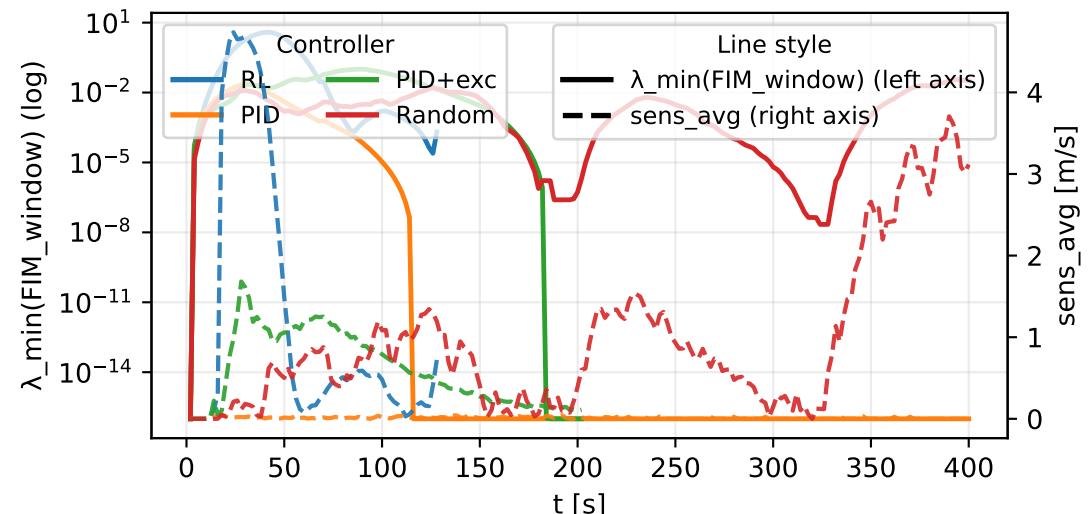
TRUE formation error



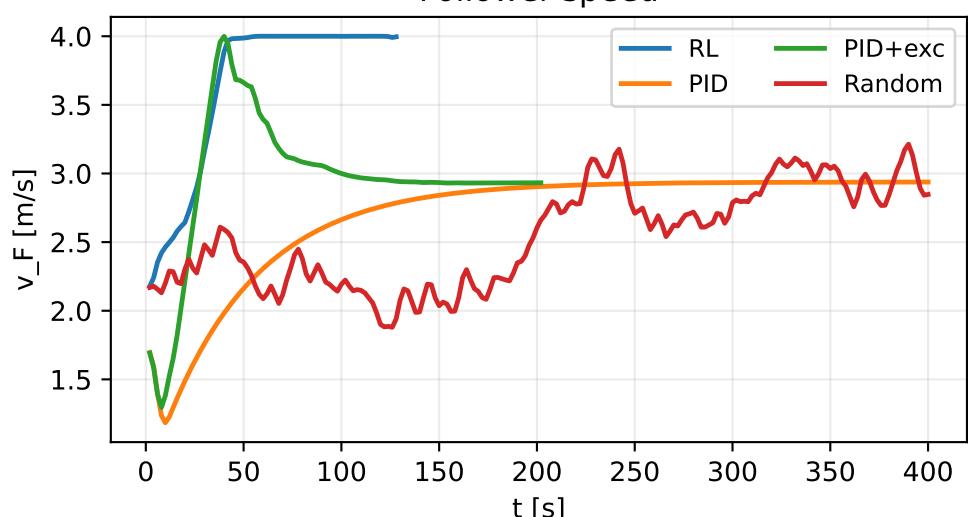
Estimator uncertainty (std_max)



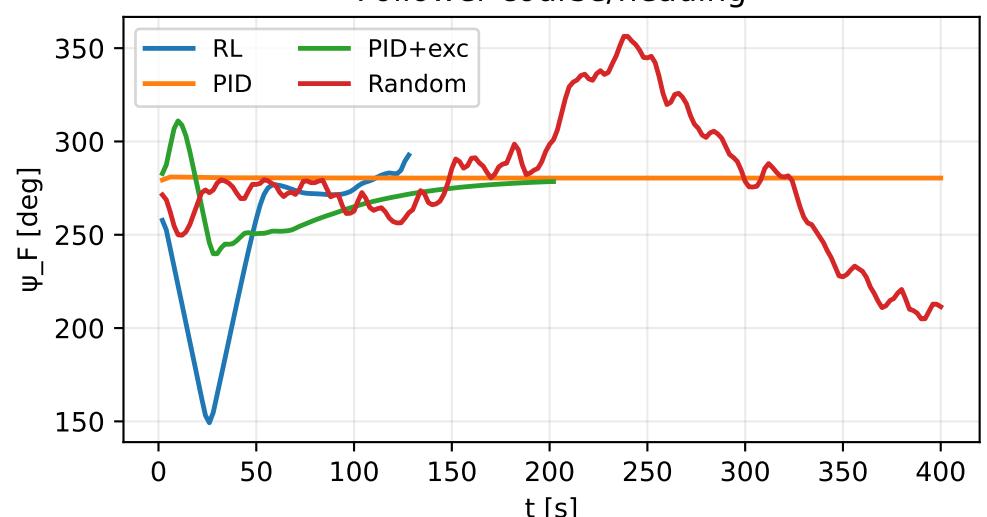
Information and excitation



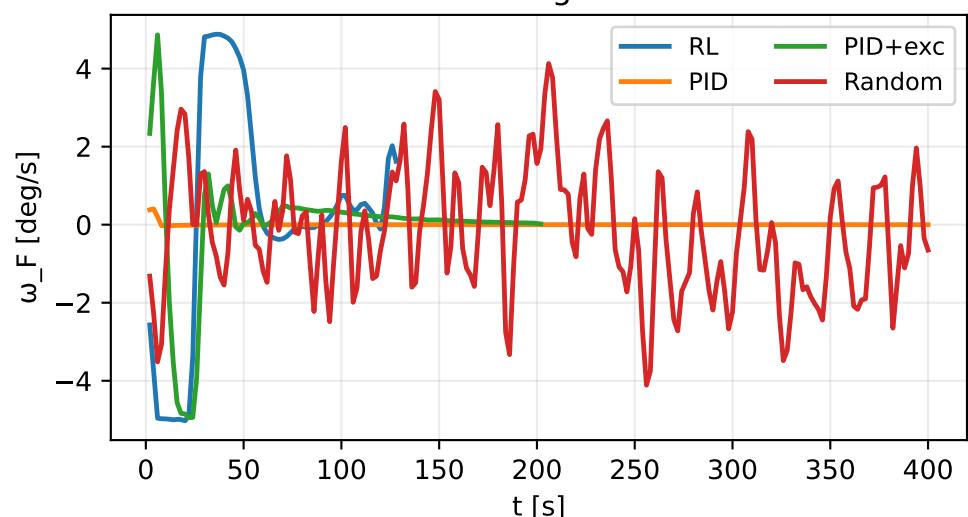
Follower speed



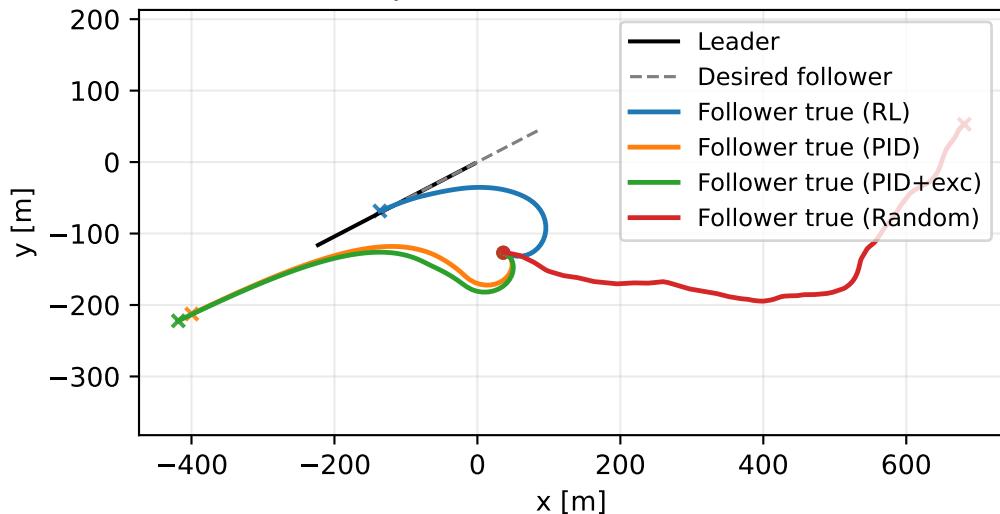
Follower course/heading



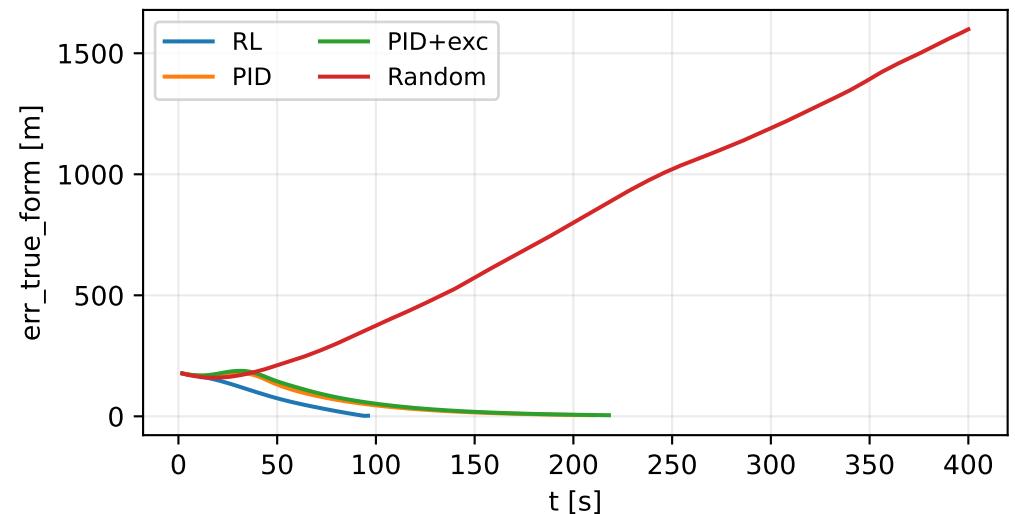
Follower angular rate



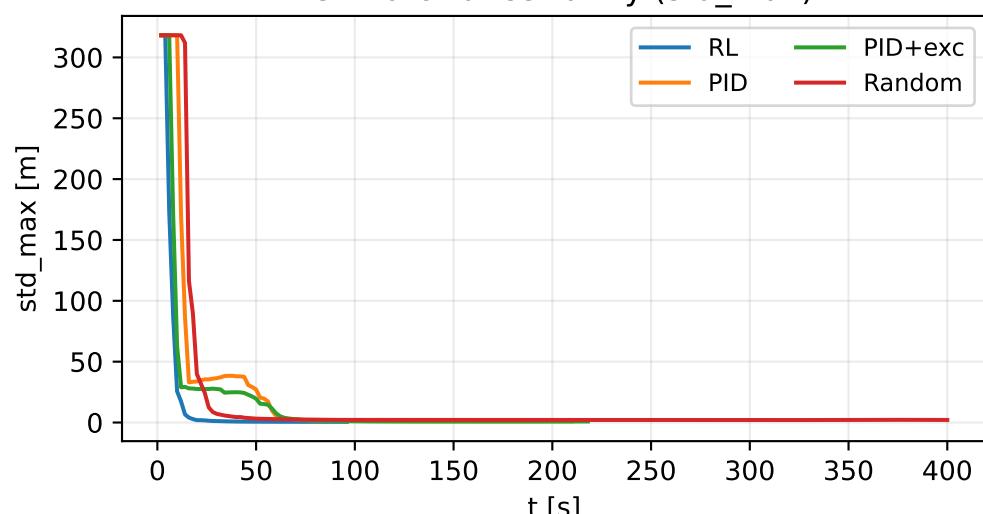
Trajectories (matched seed)



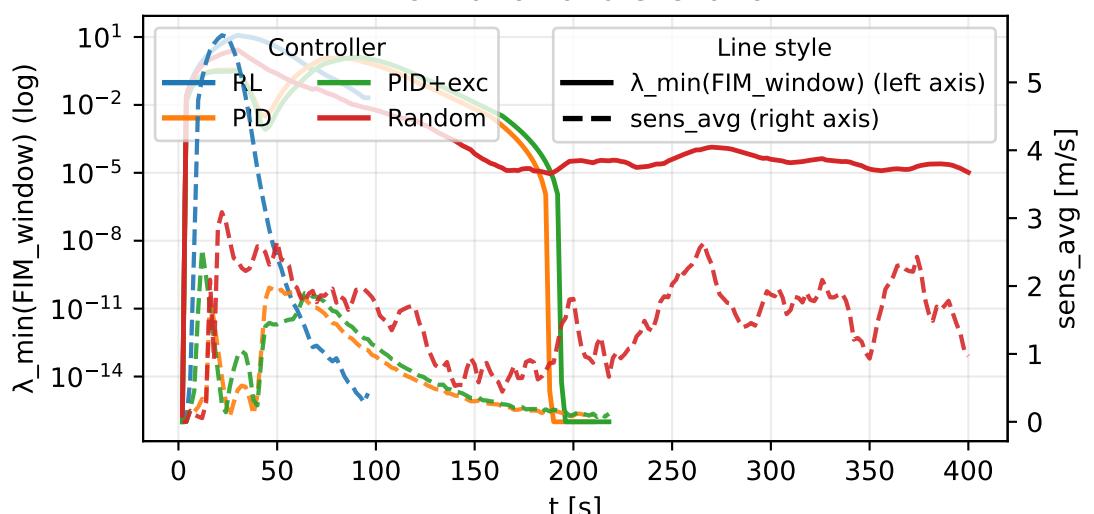
TRUE formation error



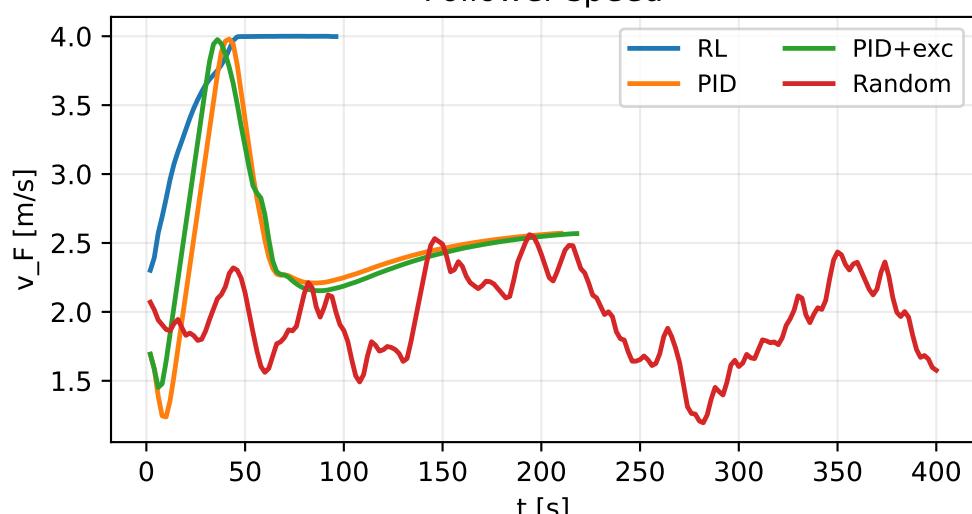
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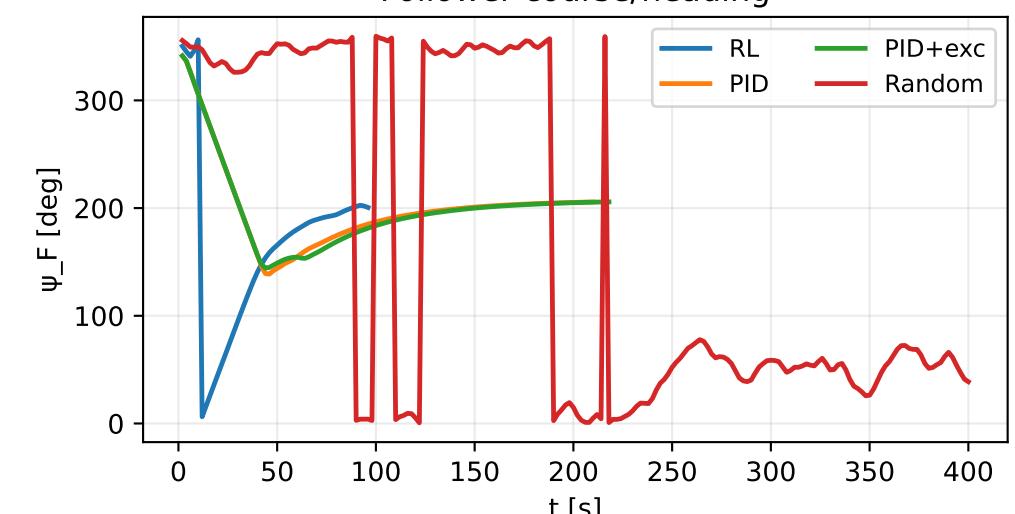
Information and excitation



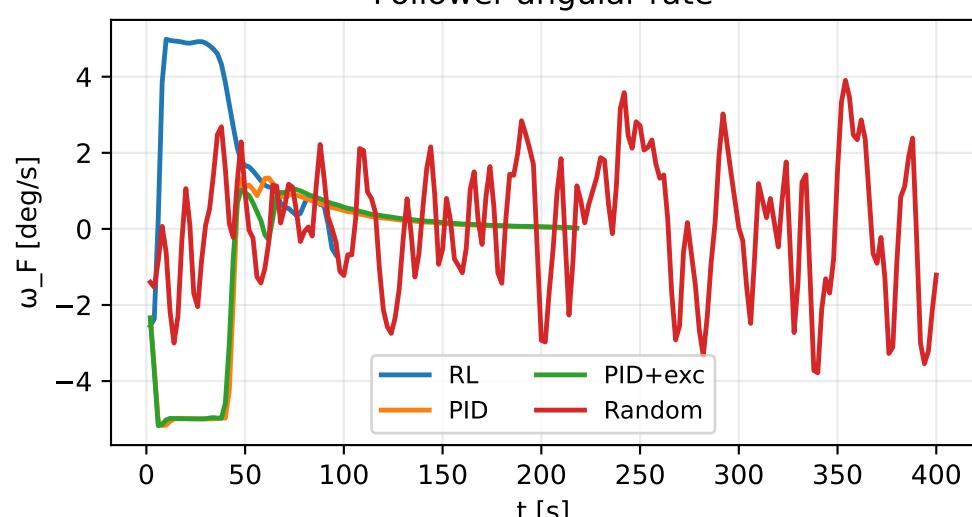
Follower speed



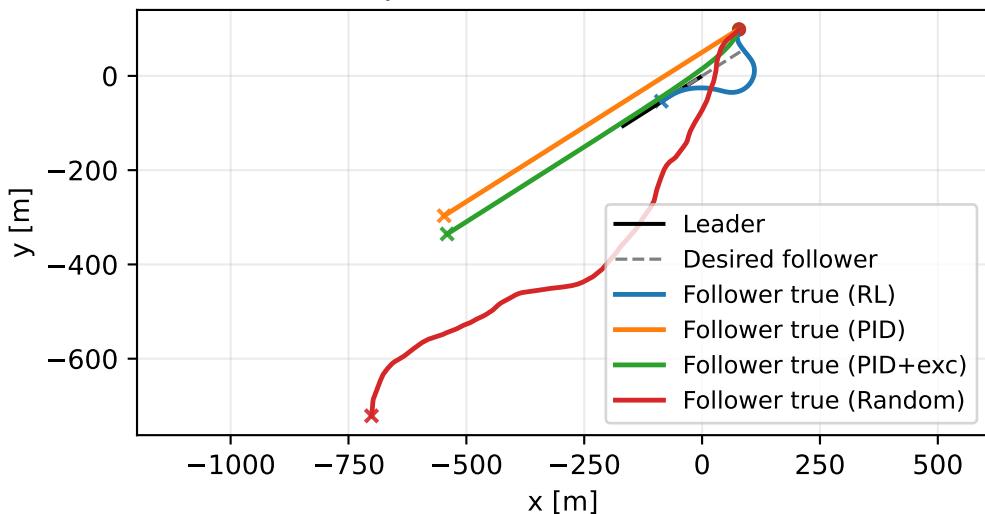
Follower course/heading



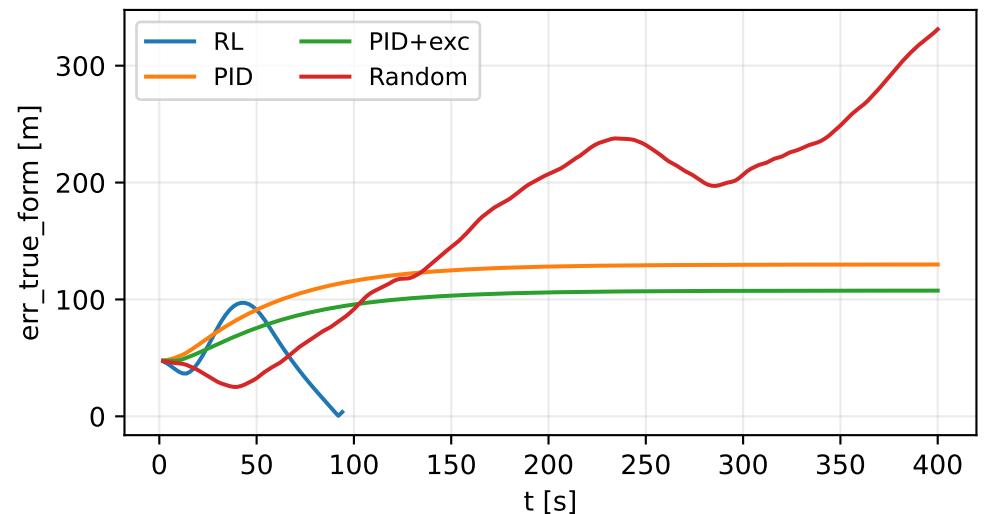
Follower angular rate



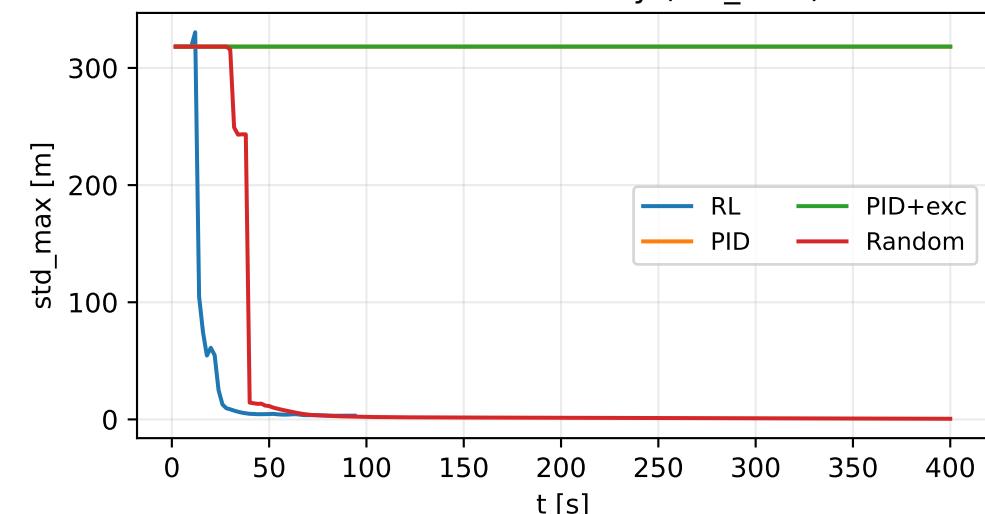
Trajectories (matched seed)



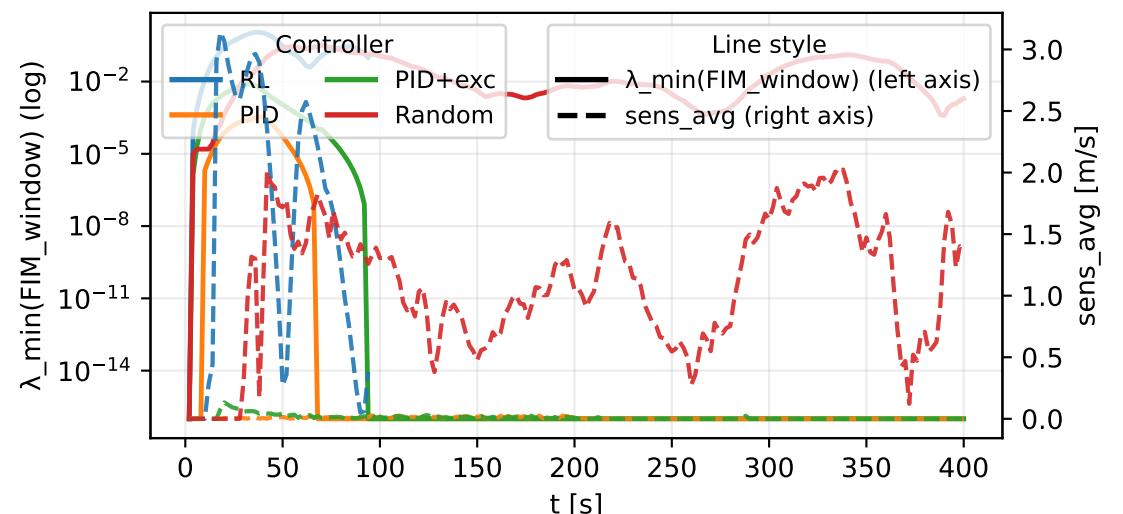
TRUE formation error



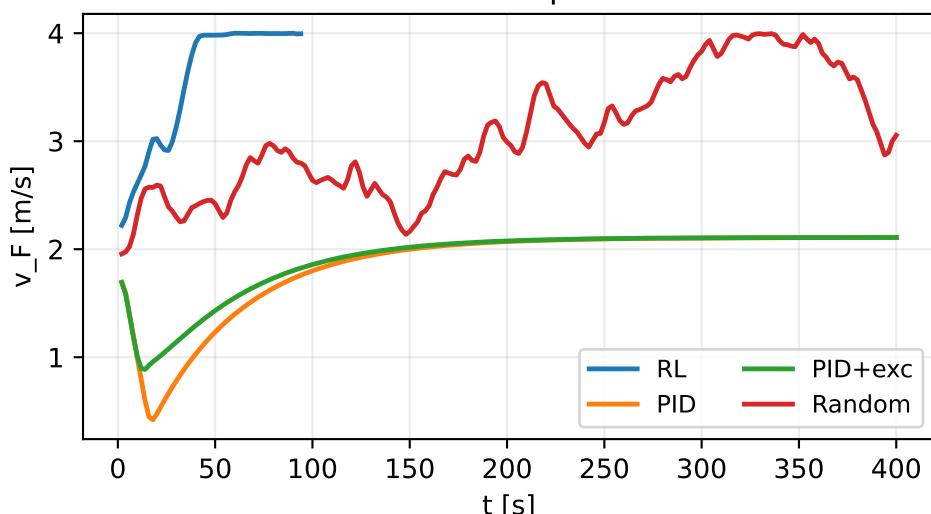
Estimator uncertainty (std_max)



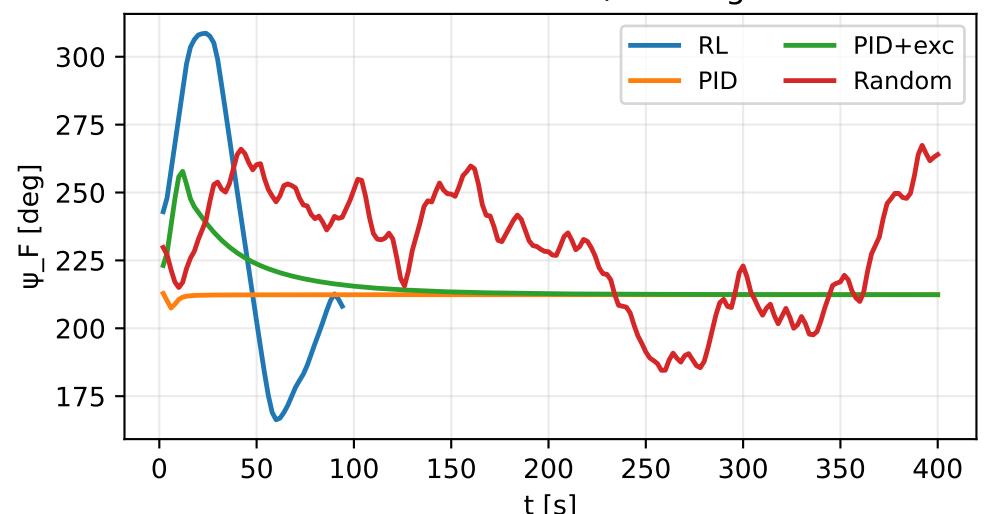
Information and excitation



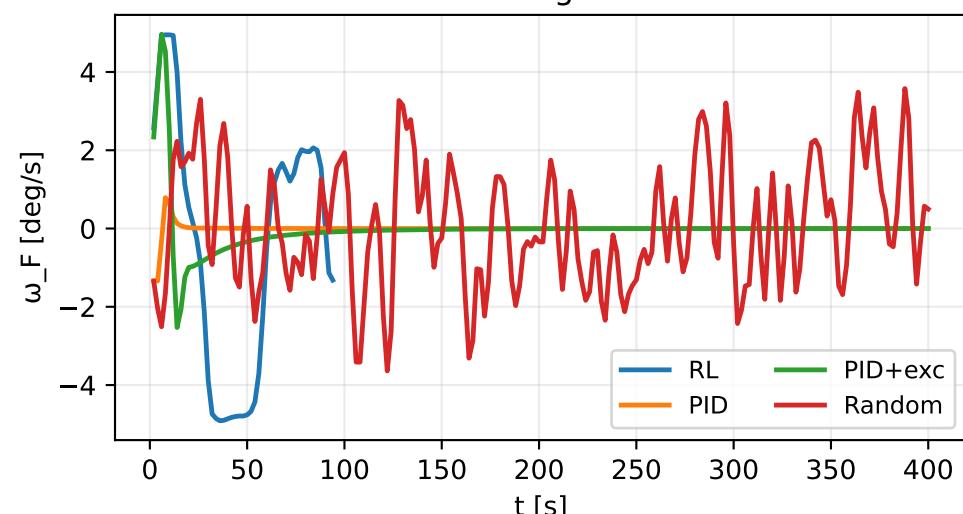
Follower speed



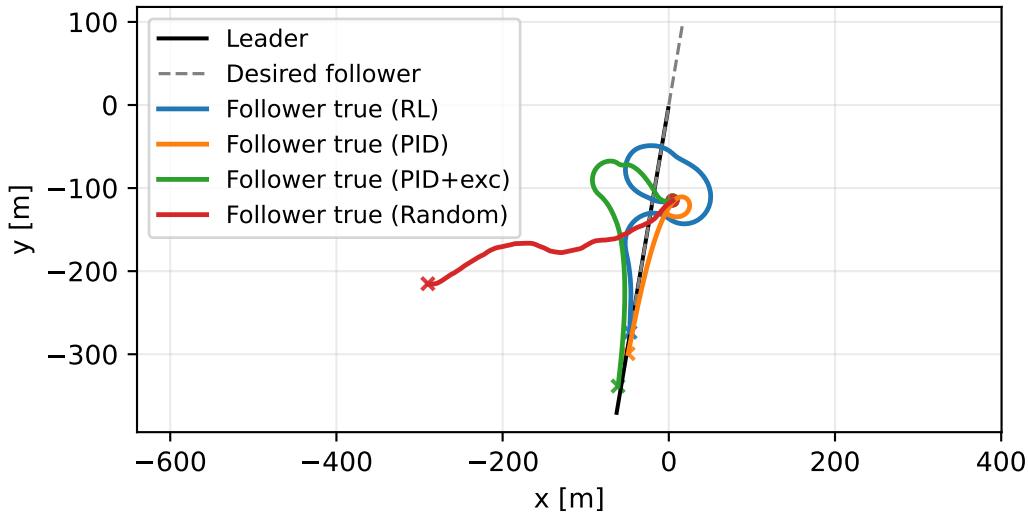
Follower course/heading



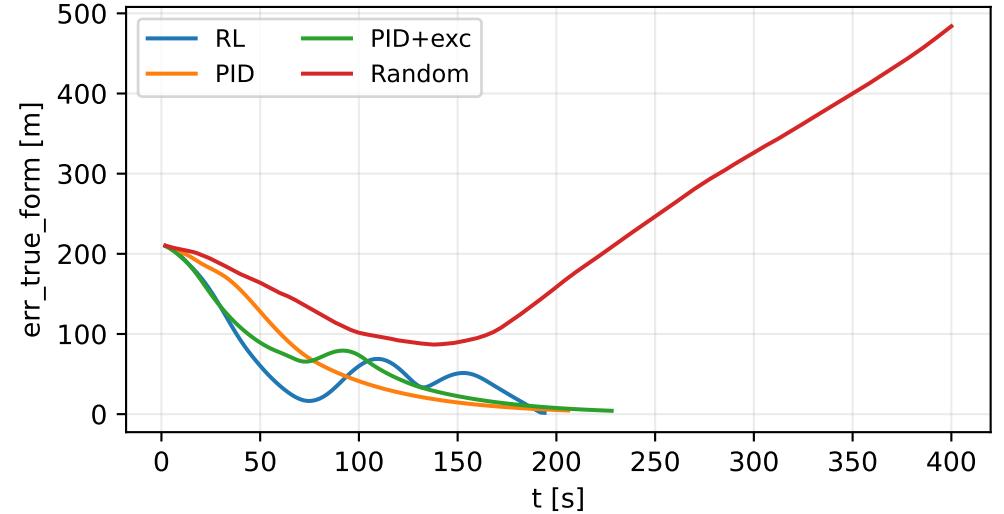
Follower angular rate



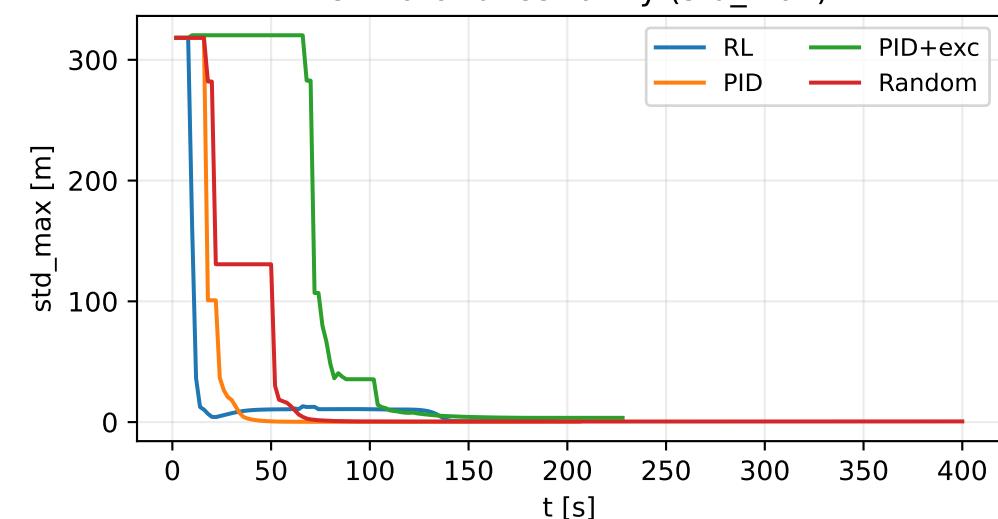
Trajectories (matched seed)



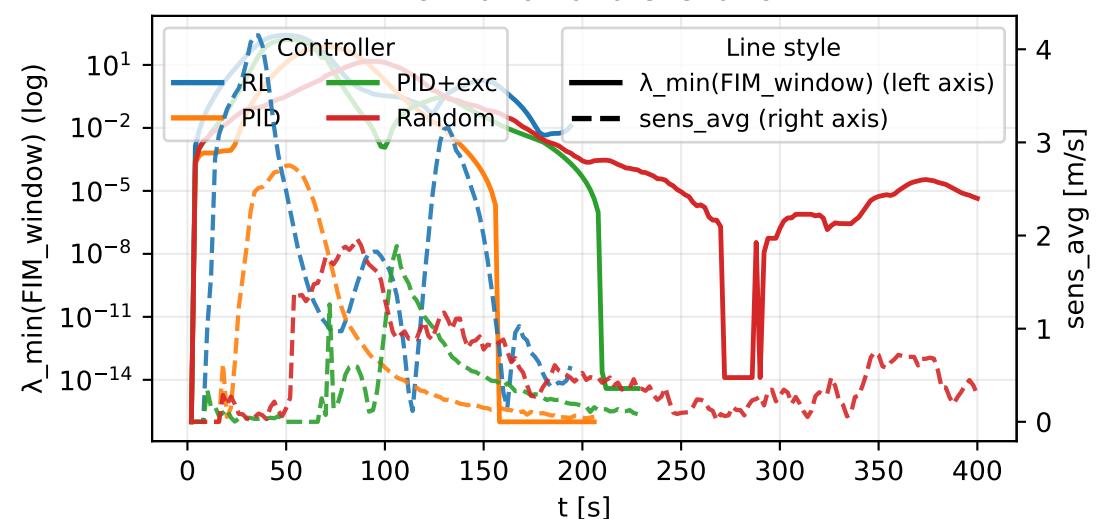
TRUE formation error



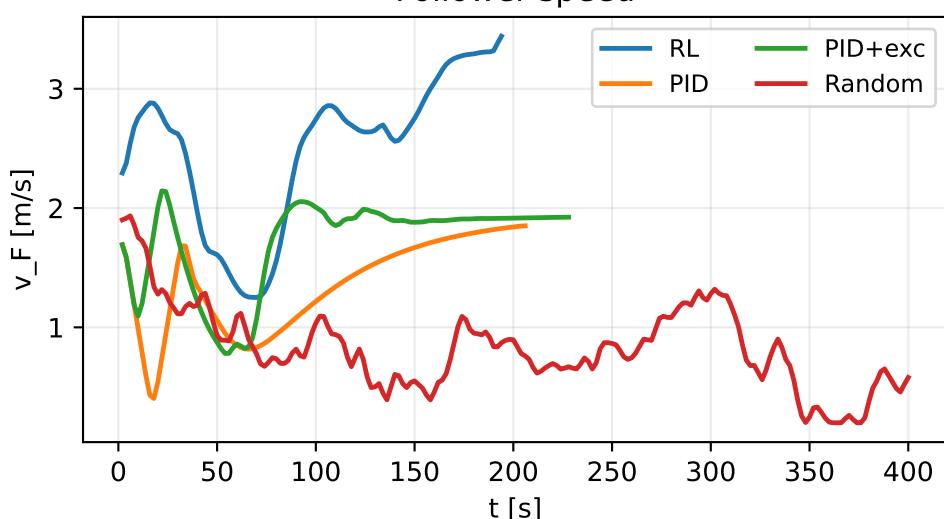
Estimator uncertainty (std_max)



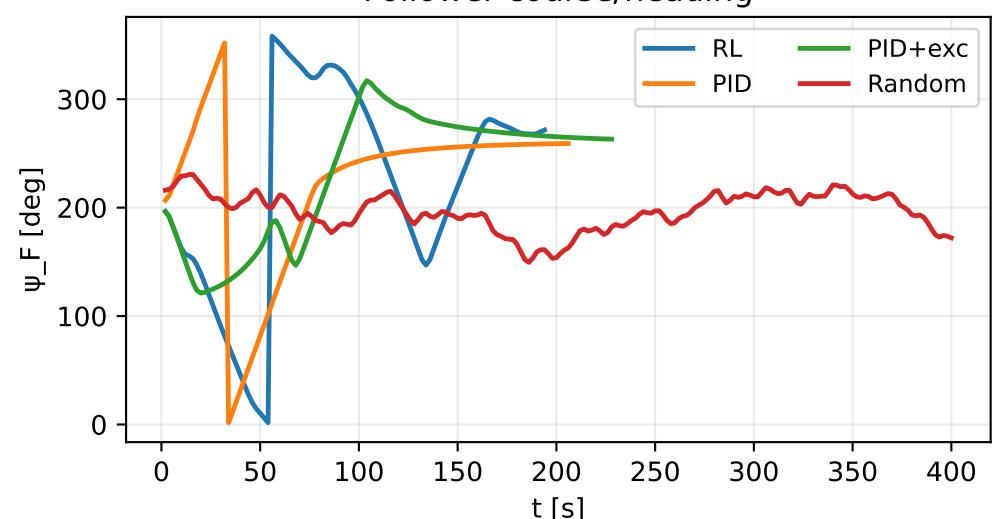
Information and excitation



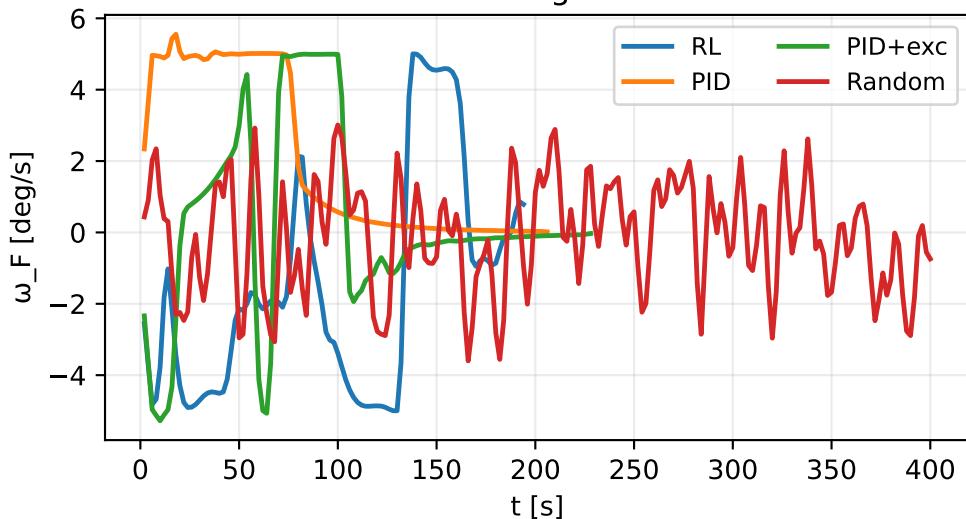
Follower speed



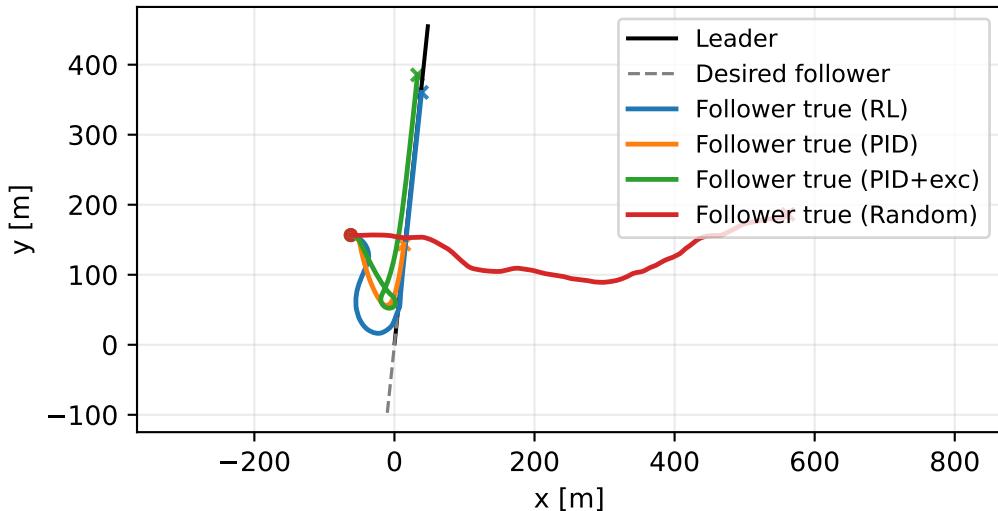
Follower course/heading



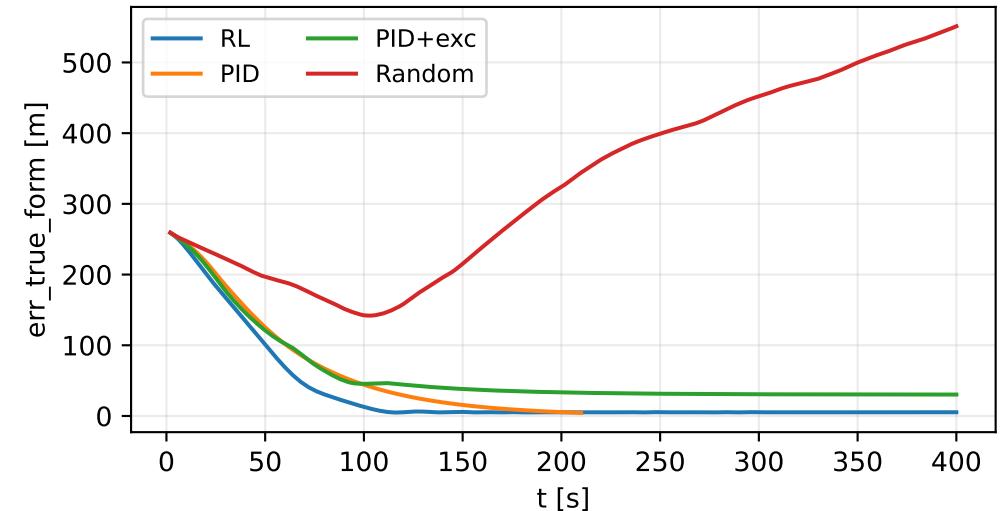
Follower angular rate



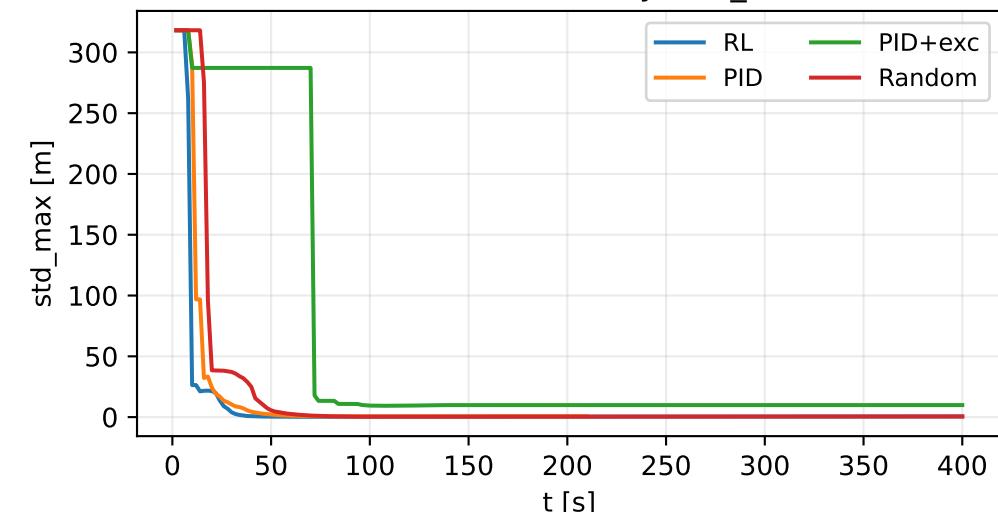
Trajectories (matched seed)



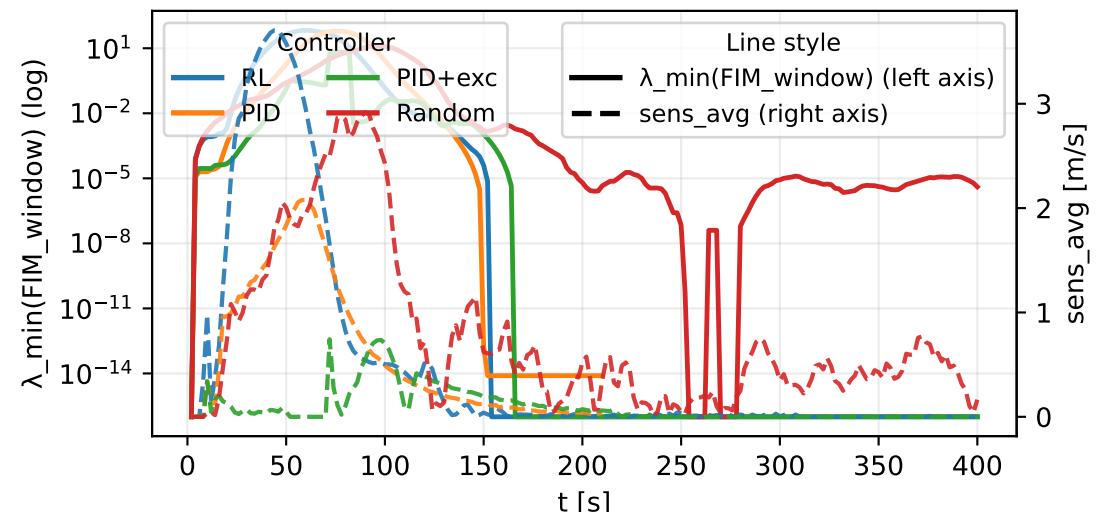
TRUE formation error



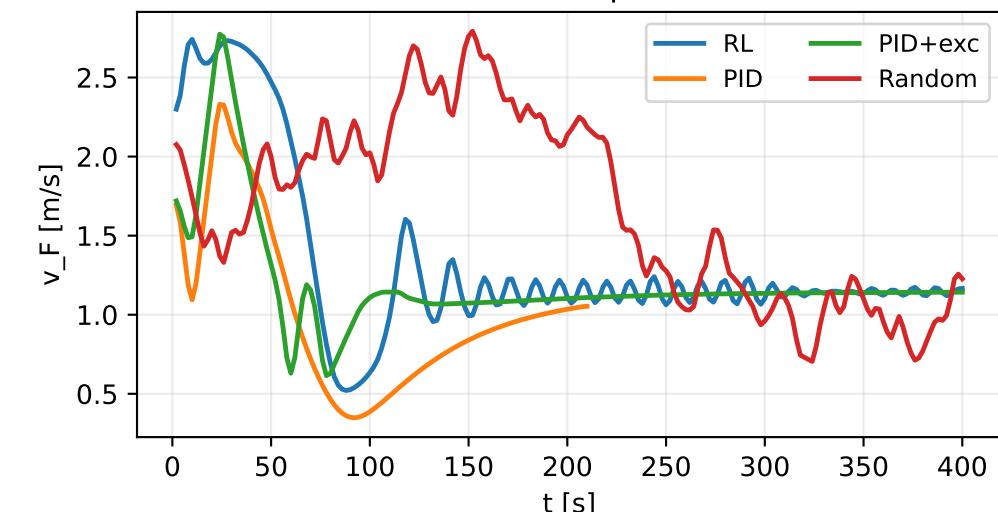
Estimator uncertainty (std_max)



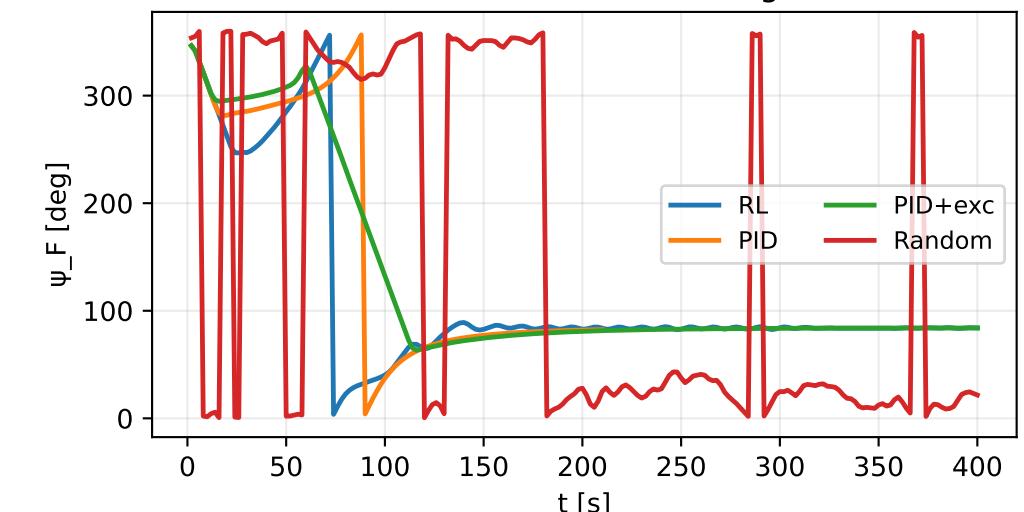
Information and excitation



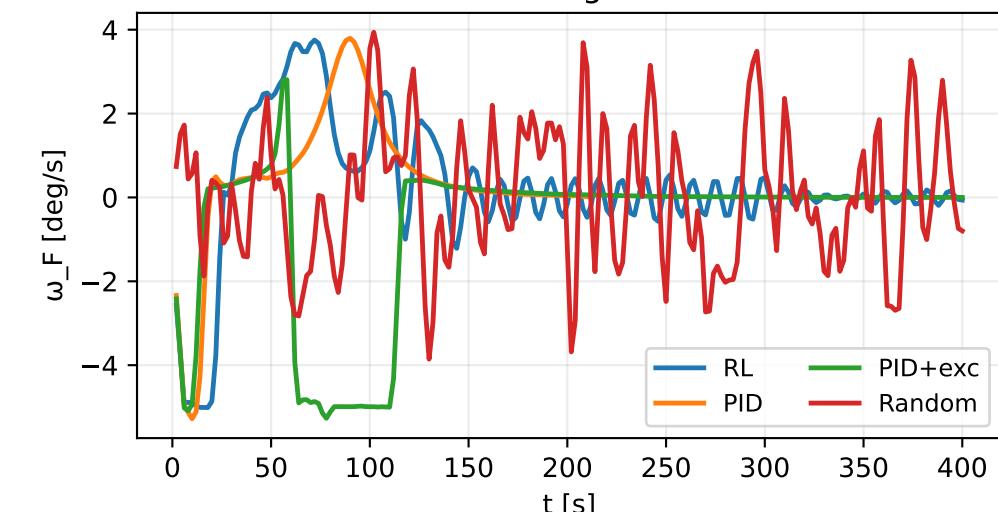
Follower speed



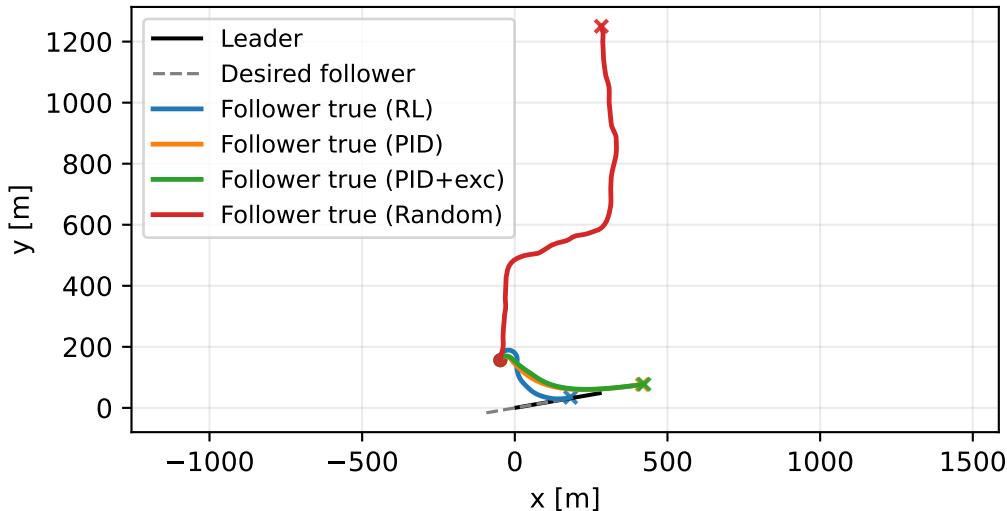
Follower course/heading



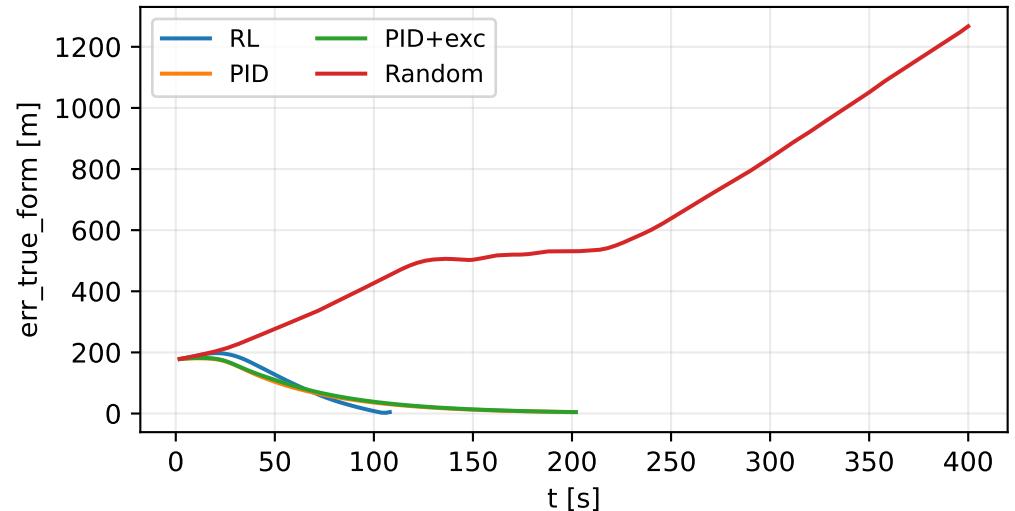
Follower angular rate



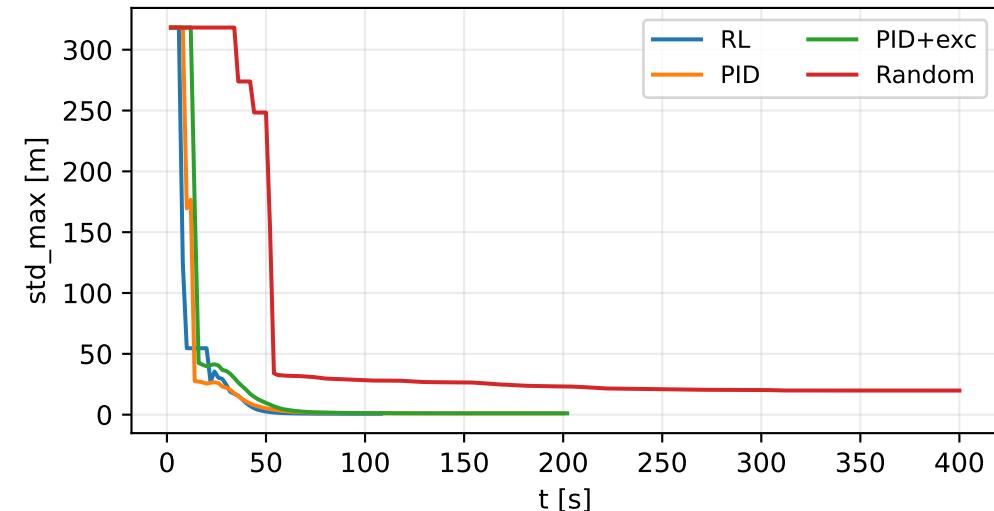
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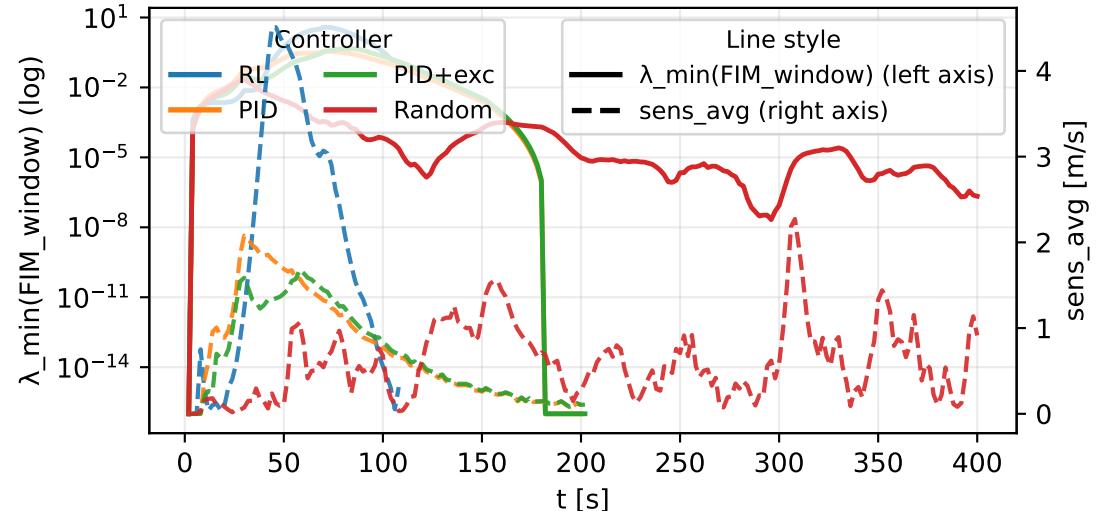
TRUE formation error



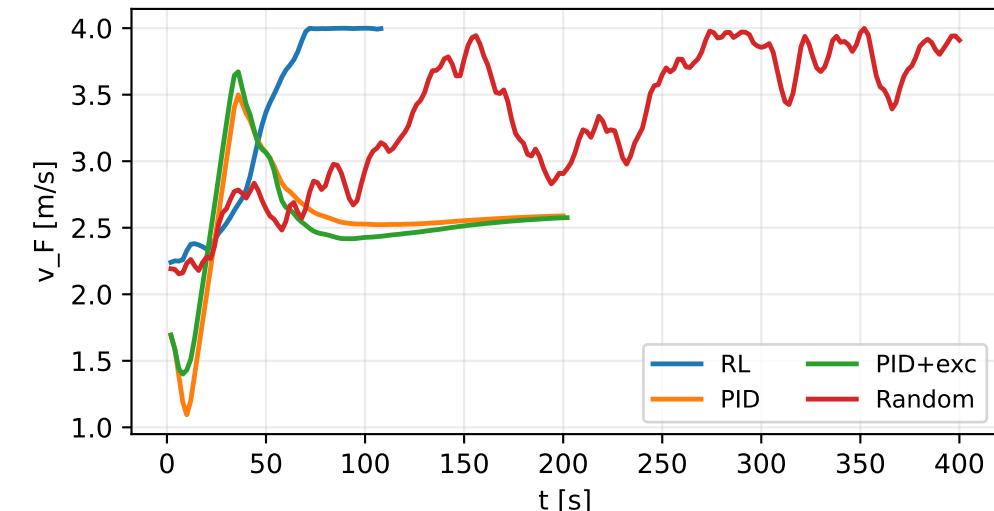
Estimator uncertainty (std_max)



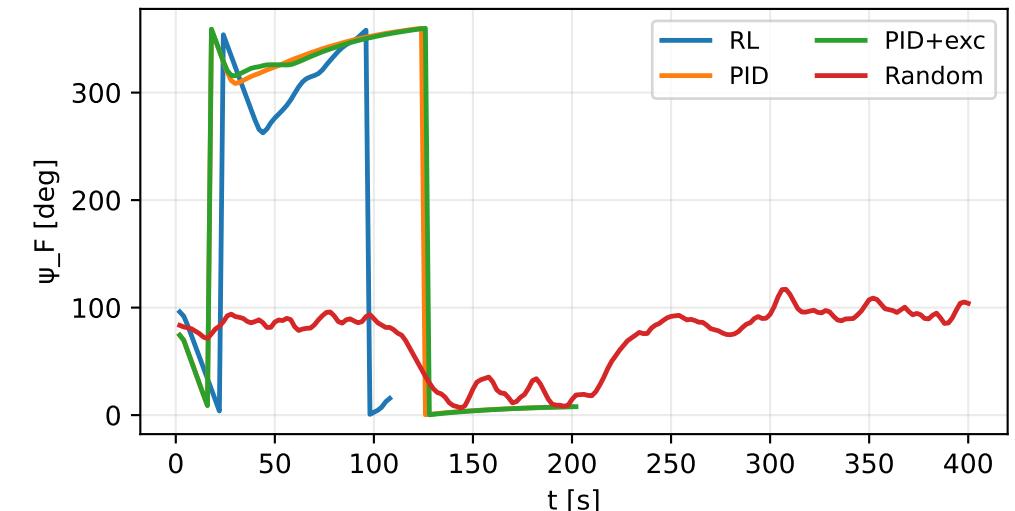
Information and excitation



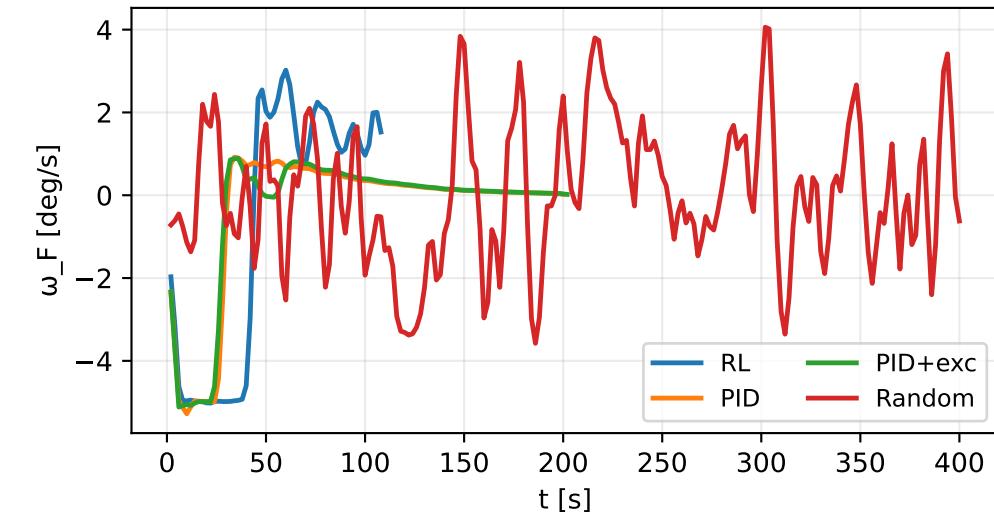
Follower speed



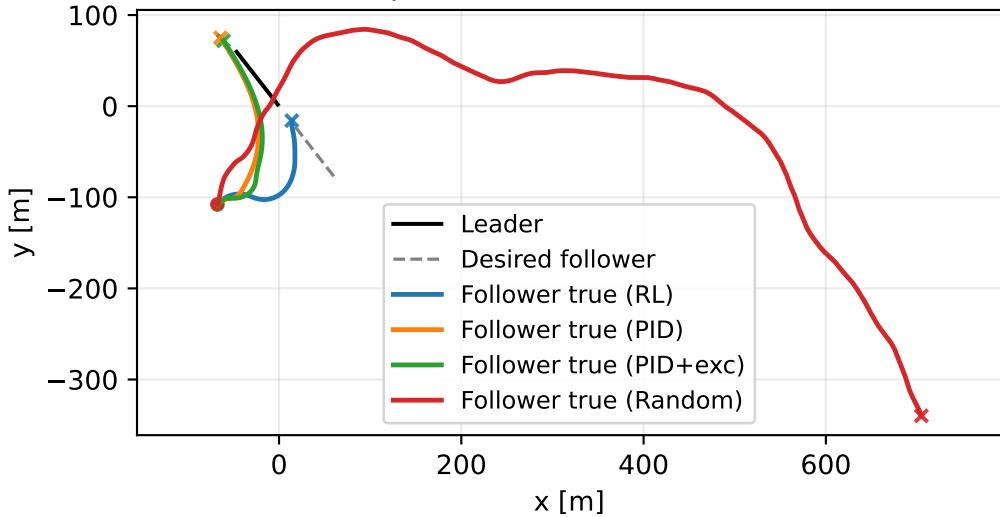
Follower course/heading



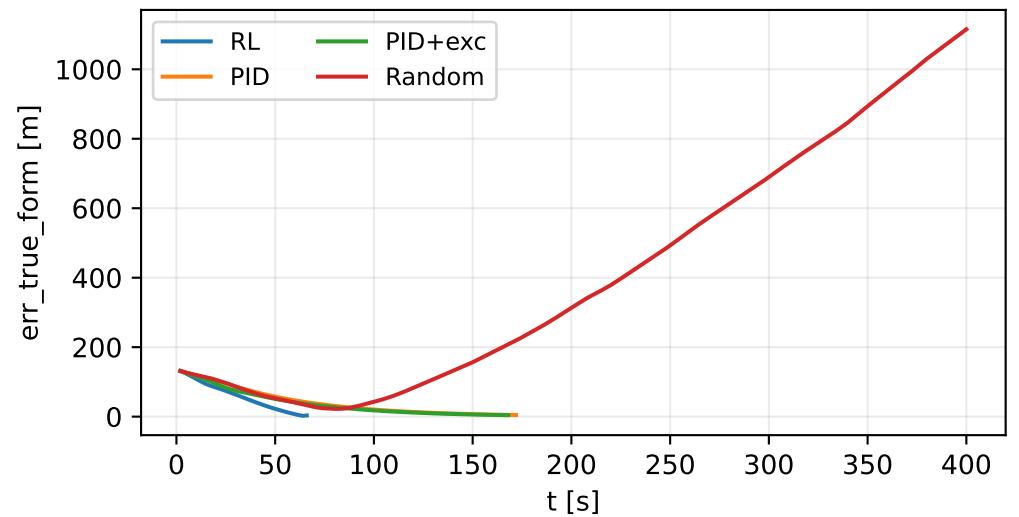
Follower angular rate



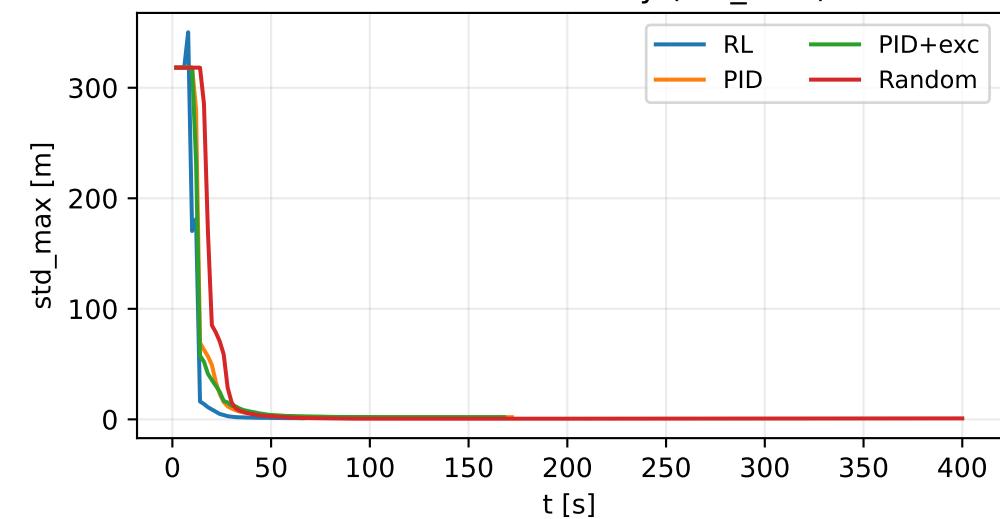
Trajectories (matched seed)



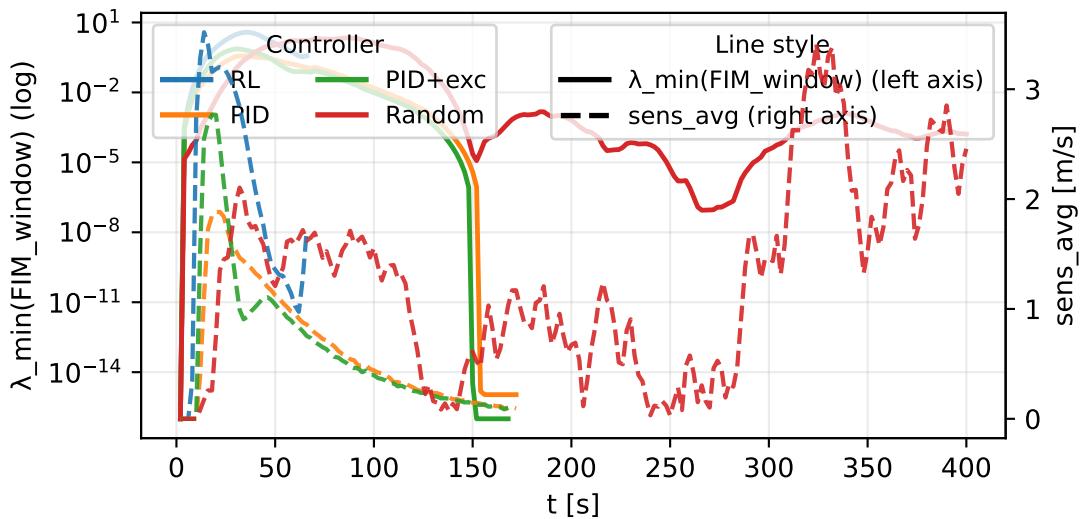
TRUE formation error



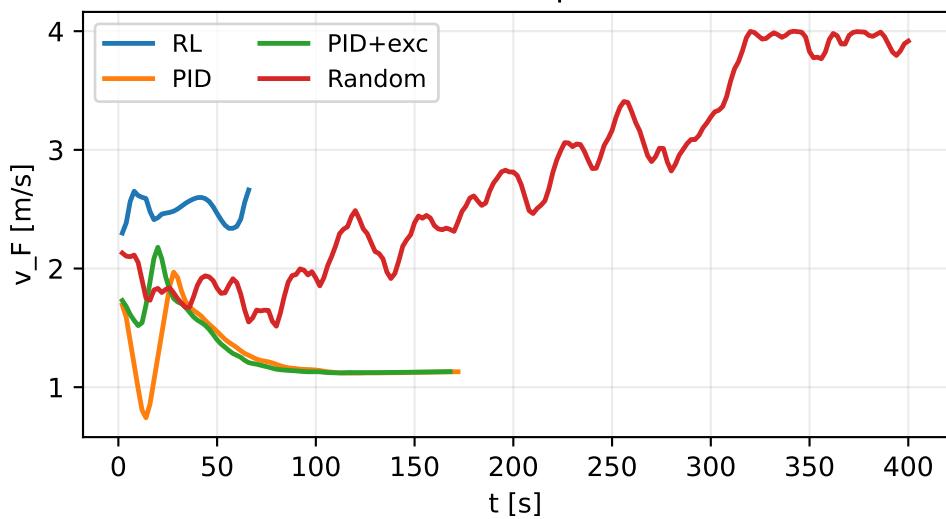
Estimator uncertainty (std_max)



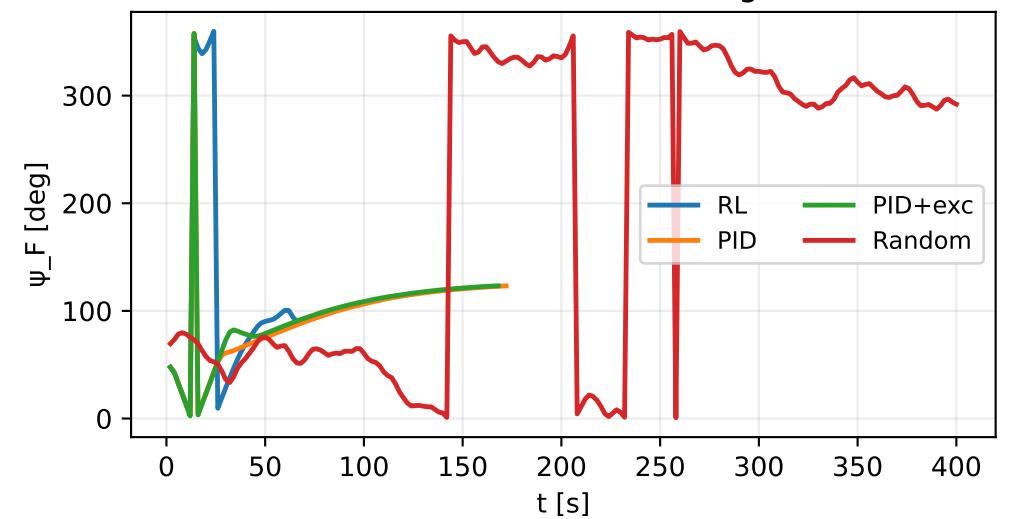
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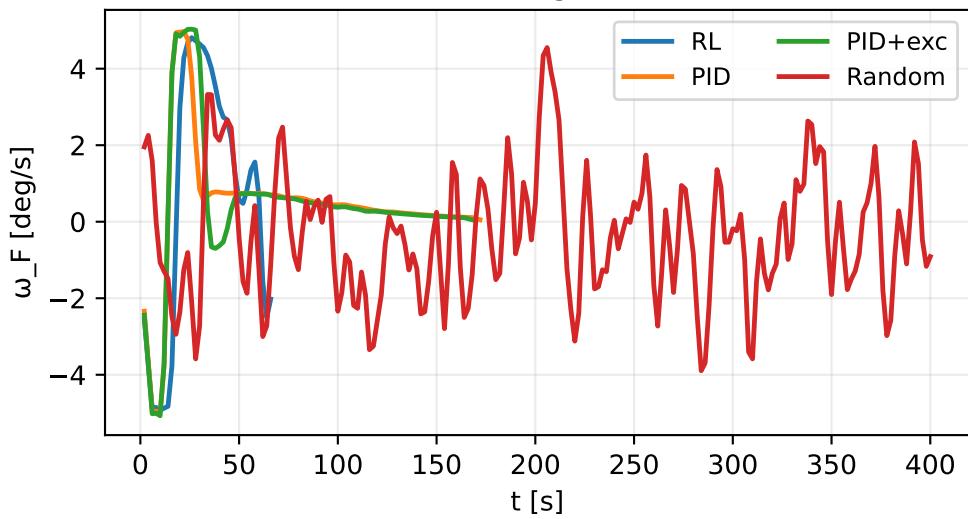
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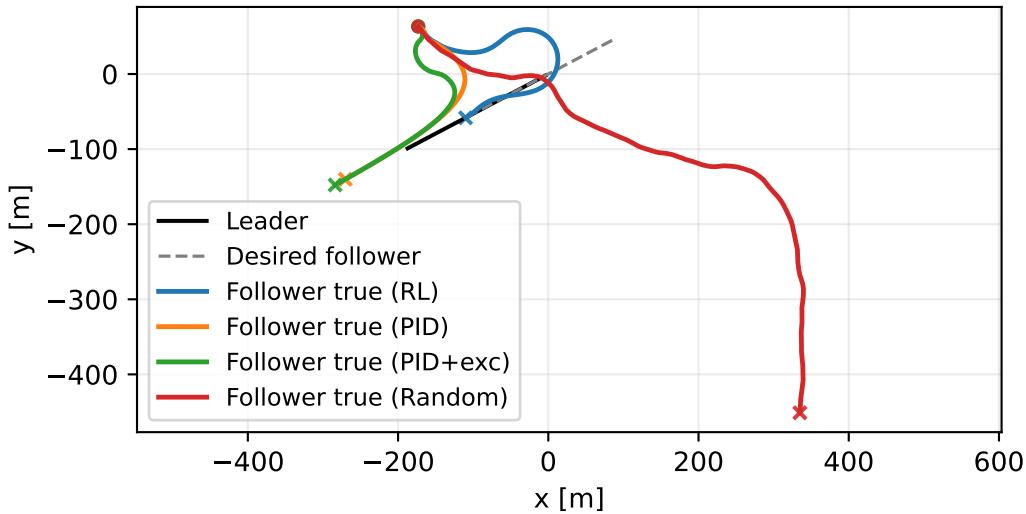
Follower course/heading



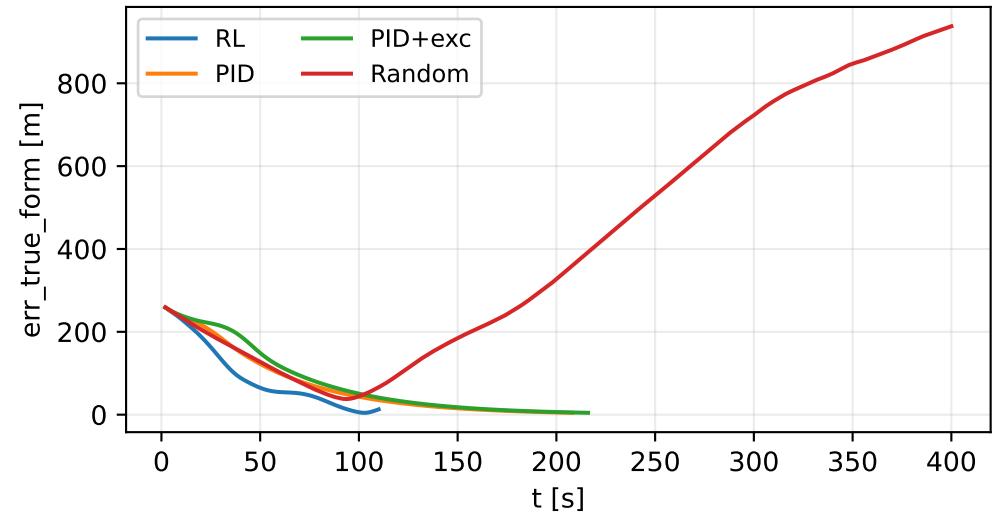
Follower angular rate



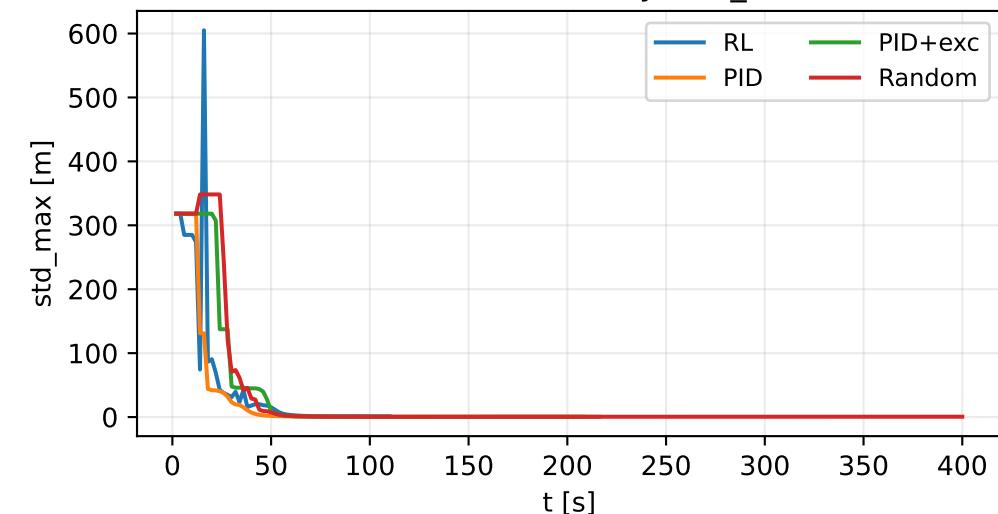
Trajectories (matched seed)



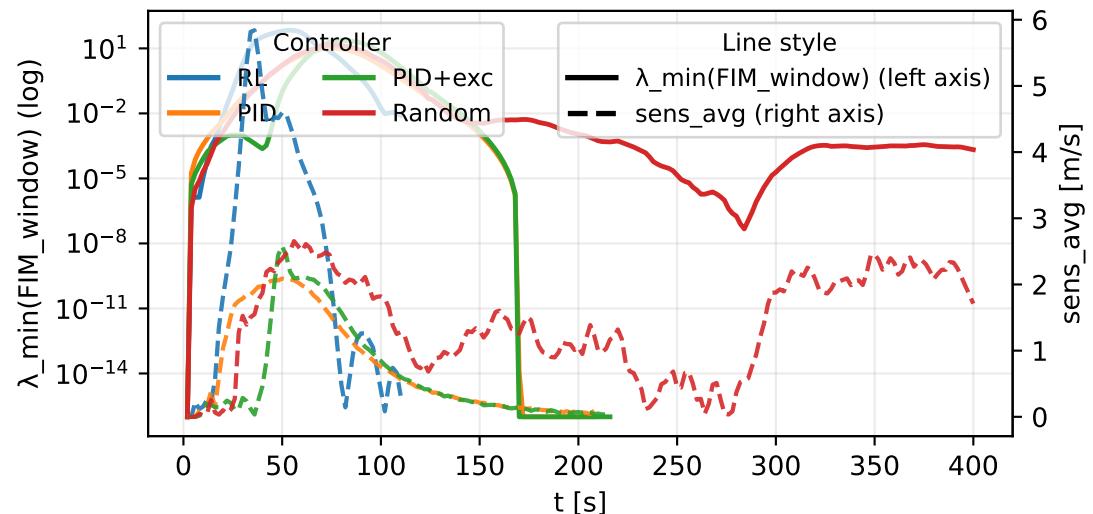
TRUE formation error



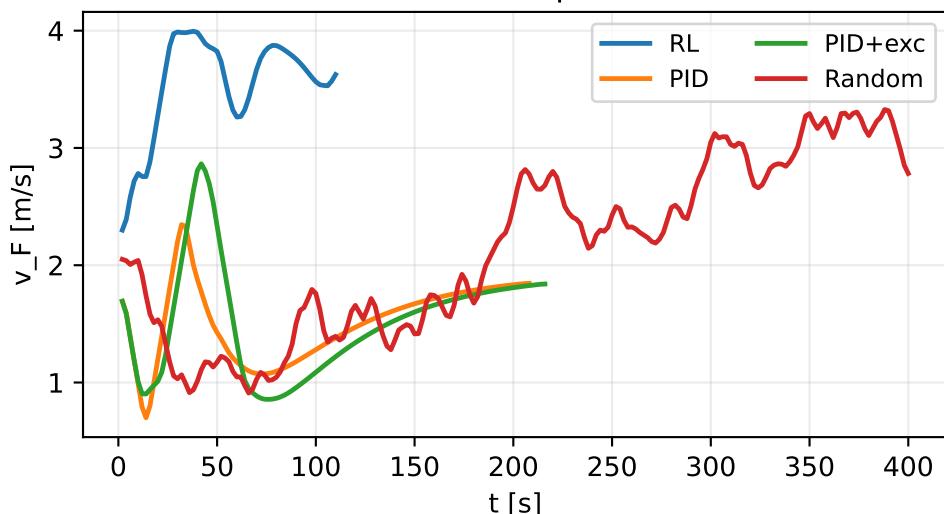
Estimator uncertainty (std_max)



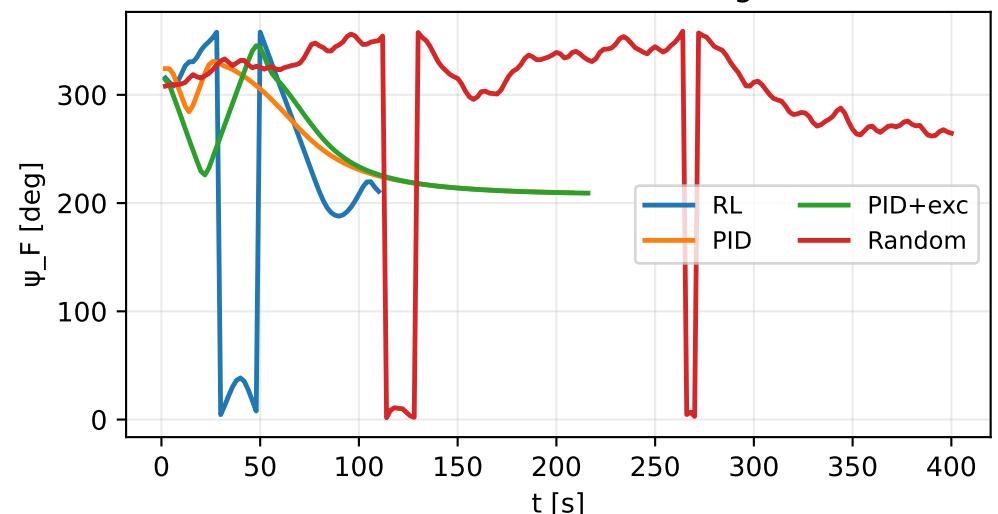
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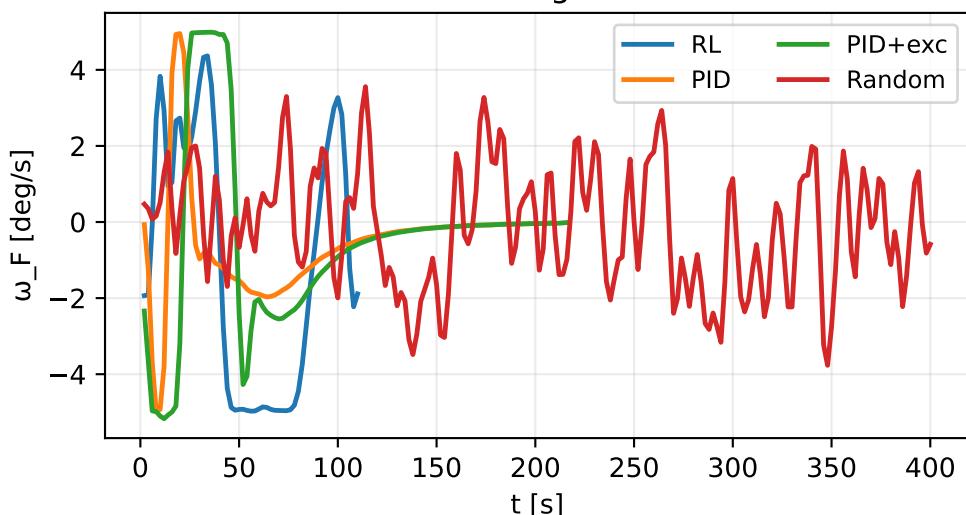
Follower speed



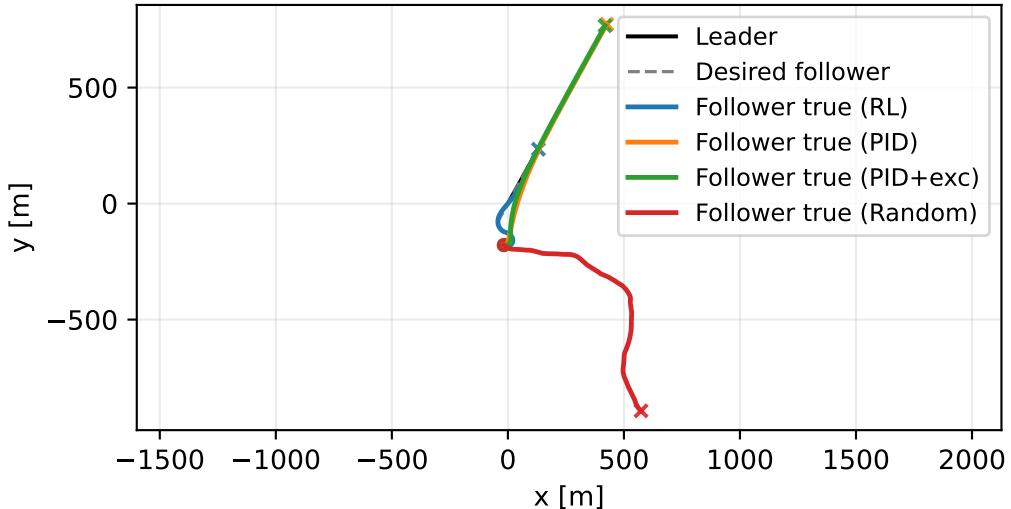
Follower course/heading



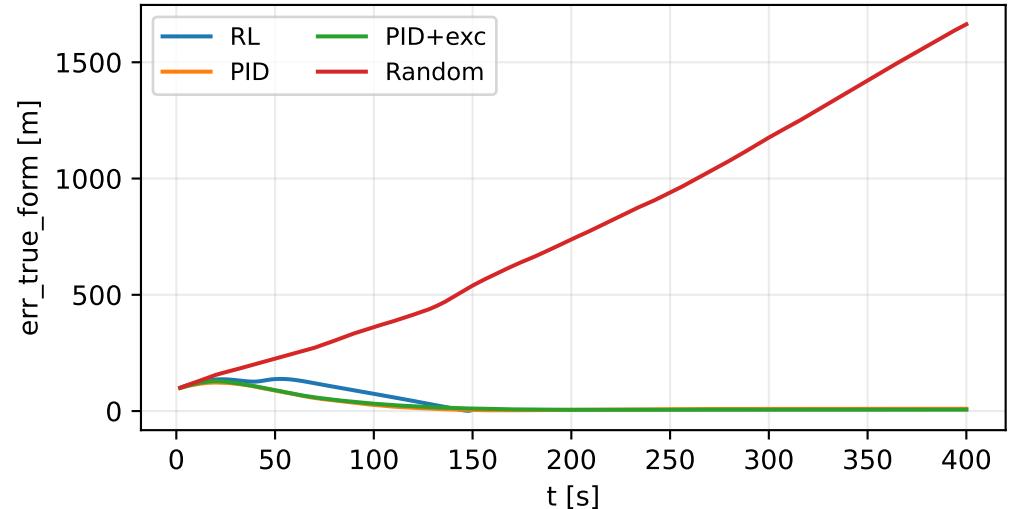
Follower angular rate



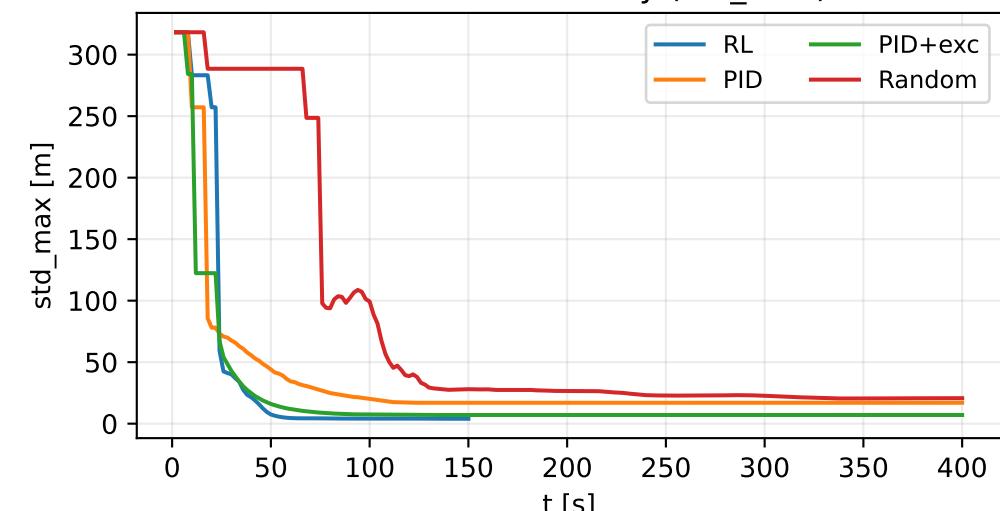
Trajectories (matched seed)



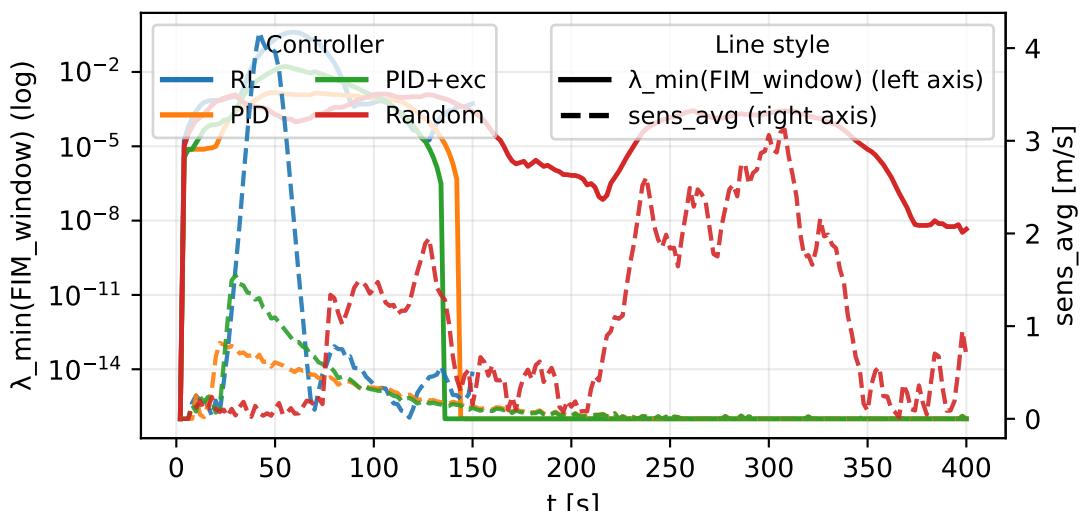
TRUE formation error



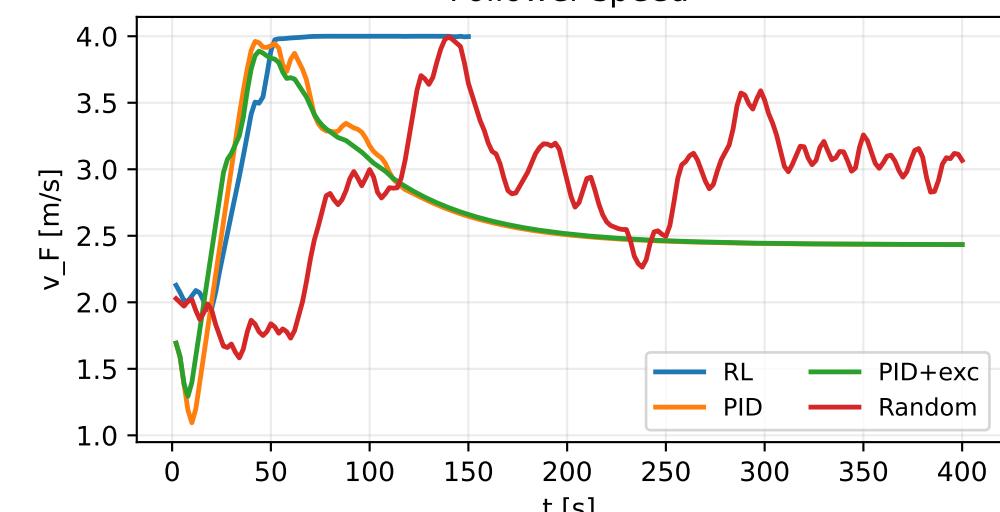
Estimator uncertainty (std_max)



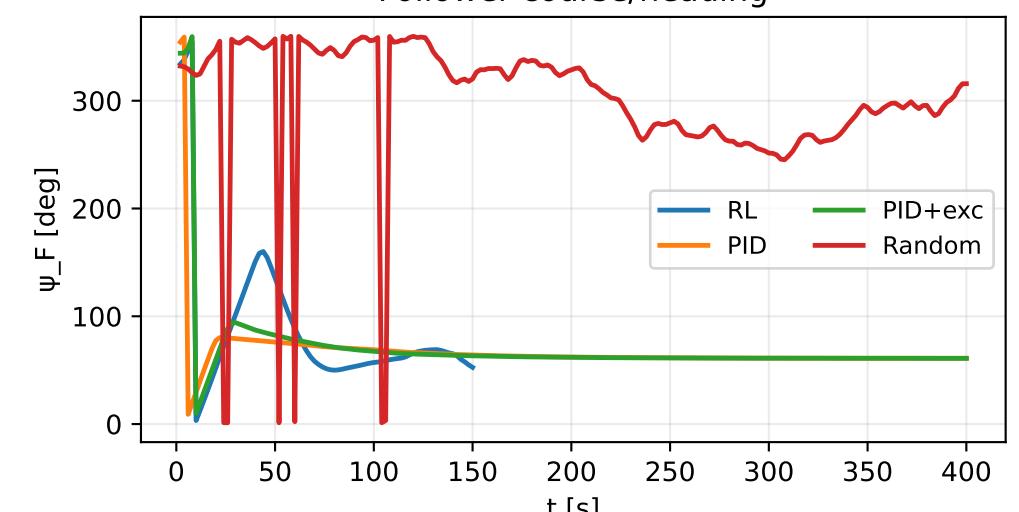
Information and excitation



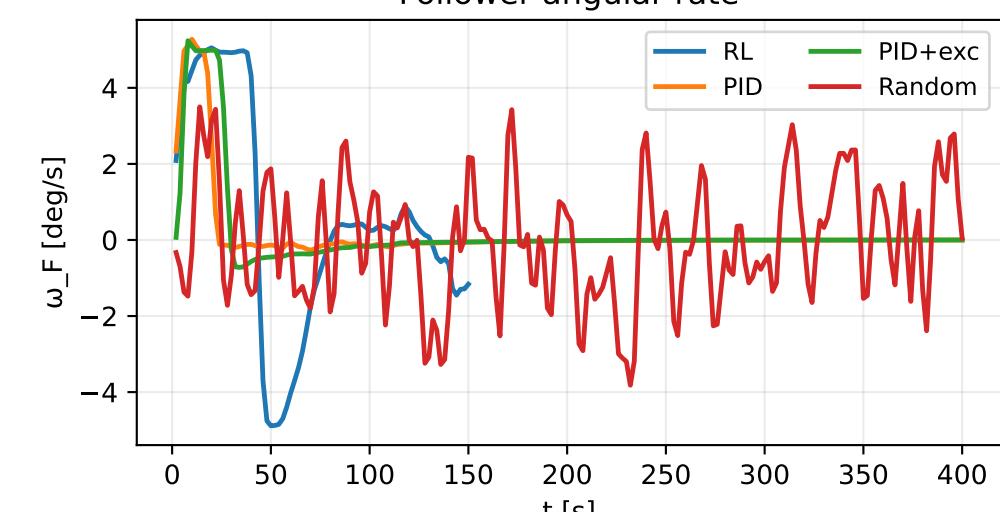
Follower speed



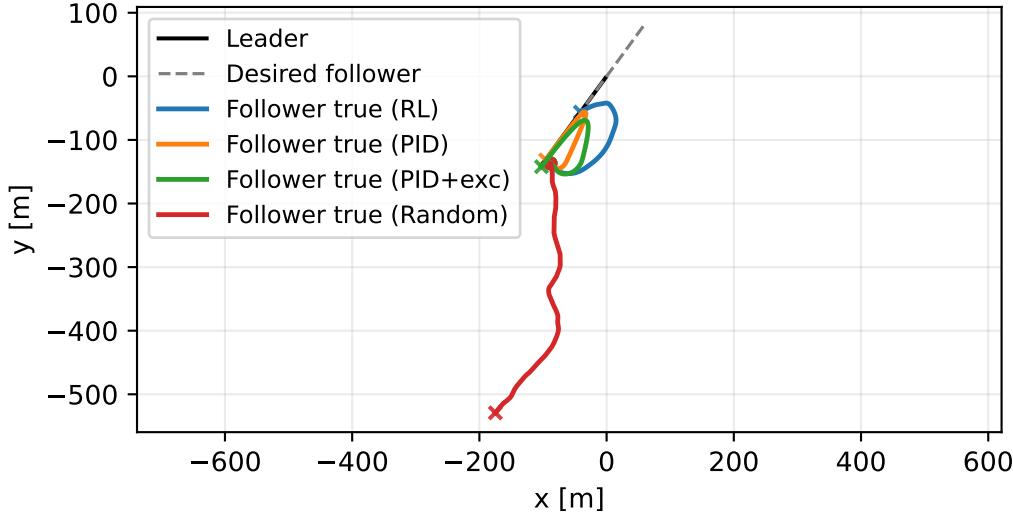
Follower course/heading



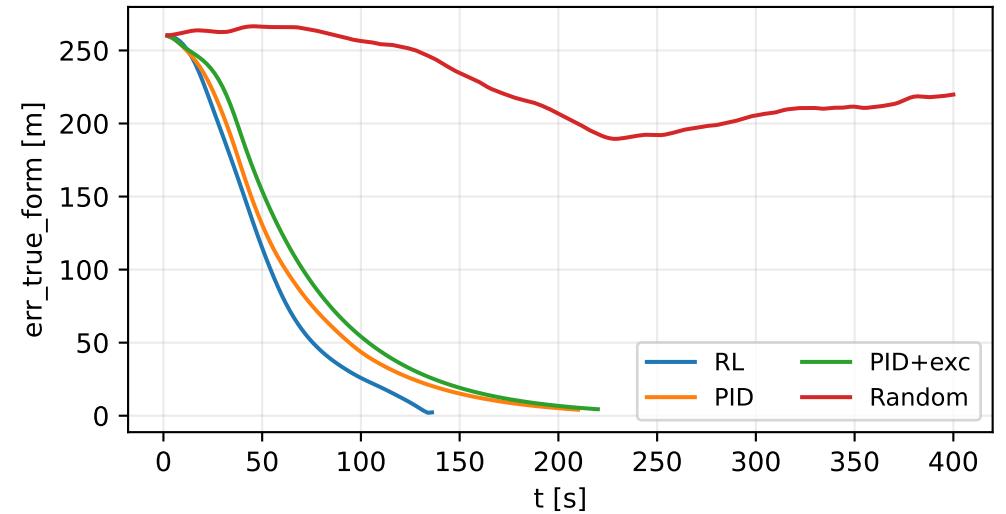
Follower angular rate



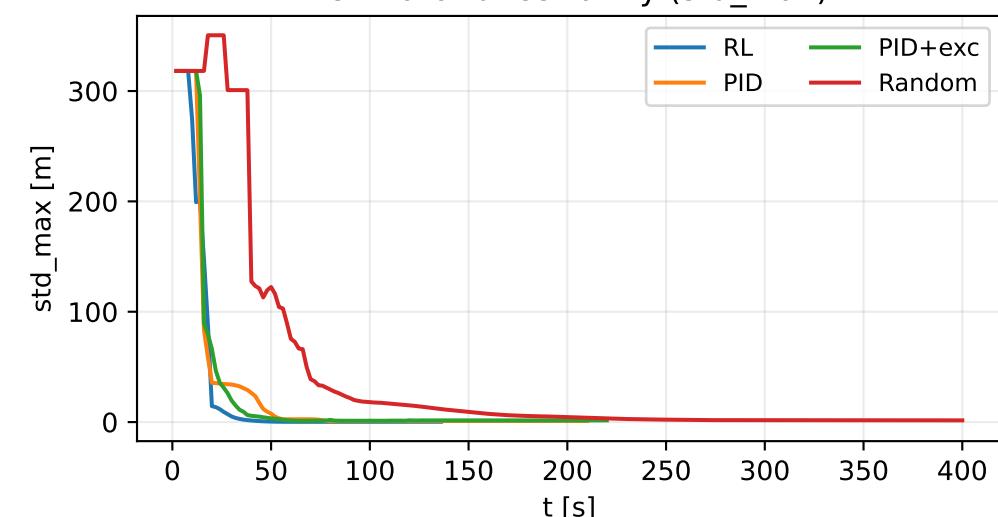
Trajectories (matched seed)



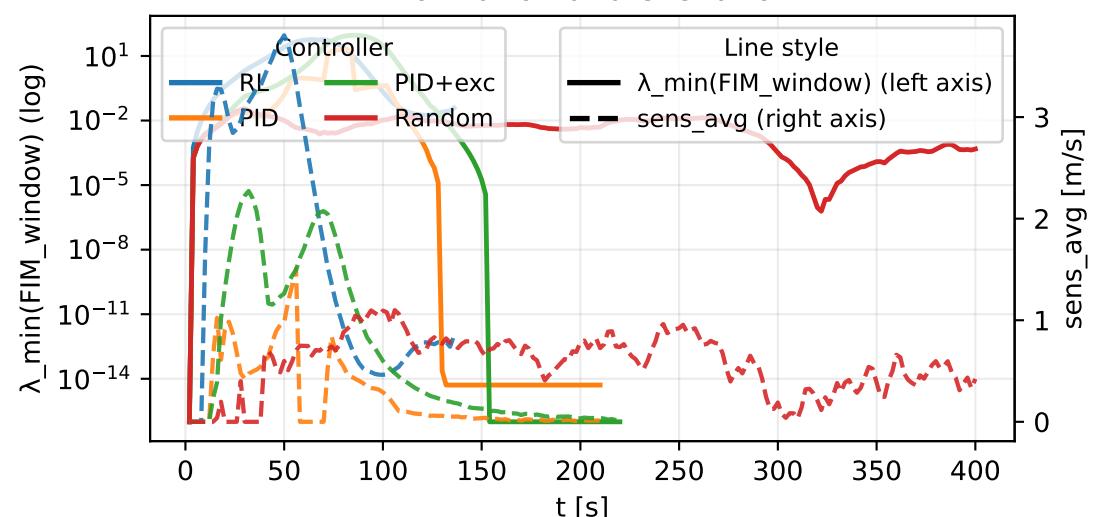
TRUE formation error



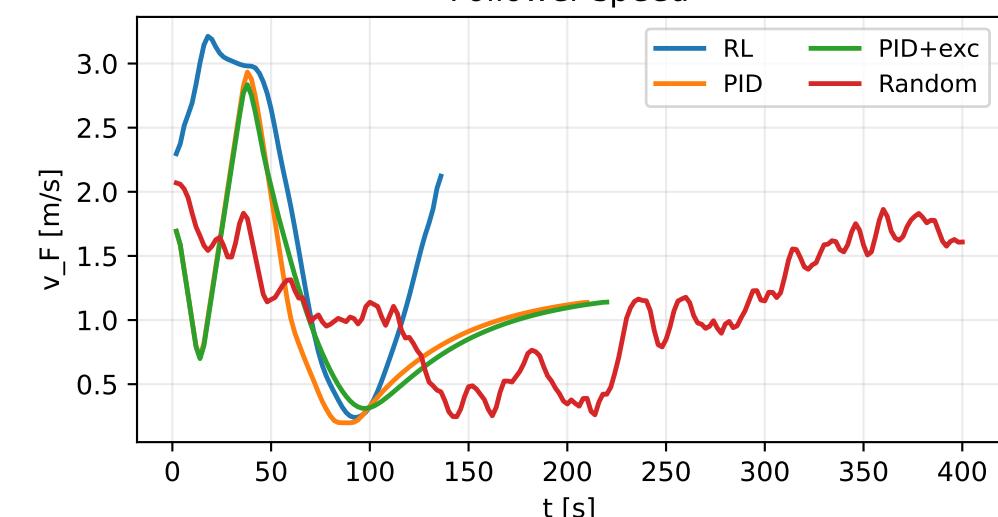
Estimator uncertainty (std_max)



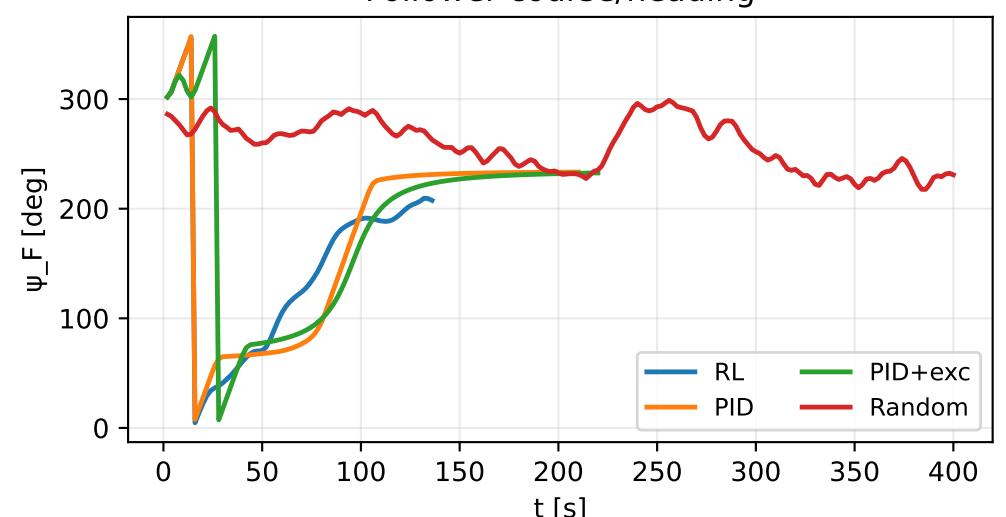
Information and excitation



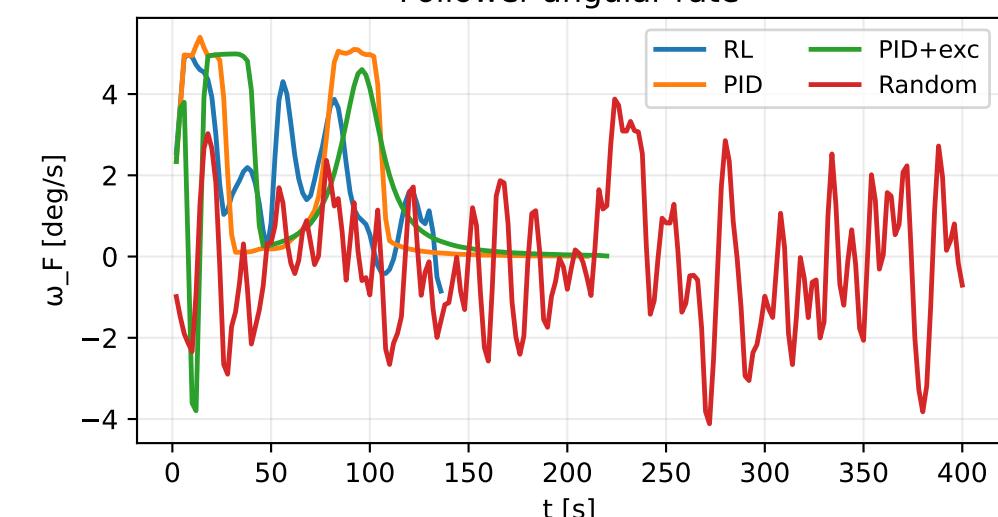
Follower speed



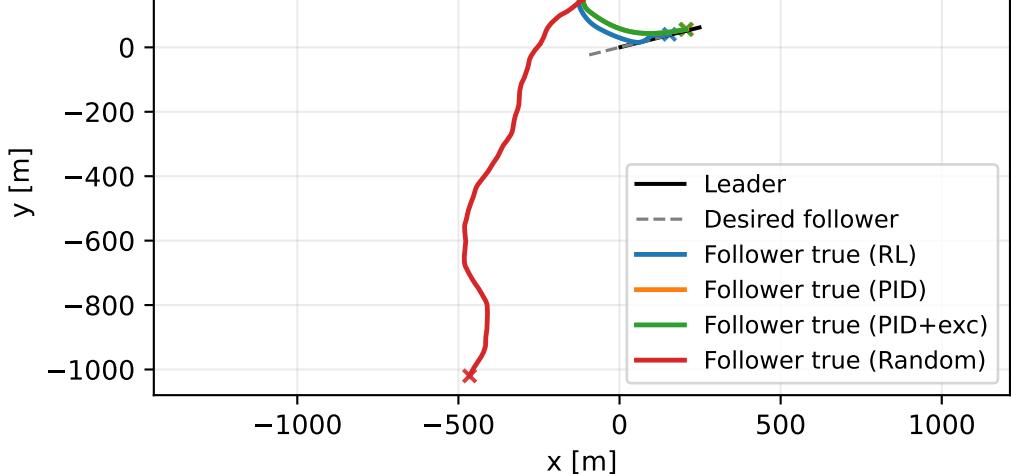
Follower course/heading



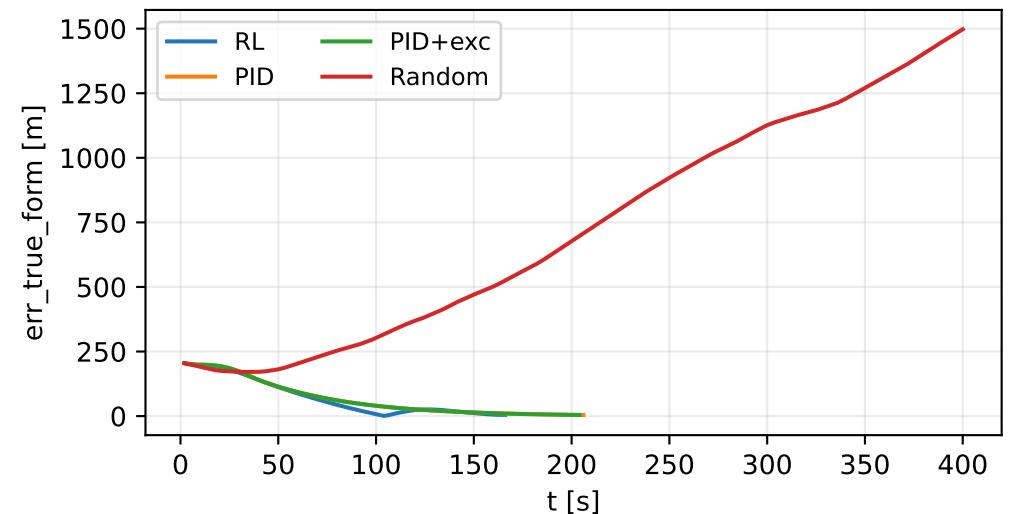
Follower angular rate



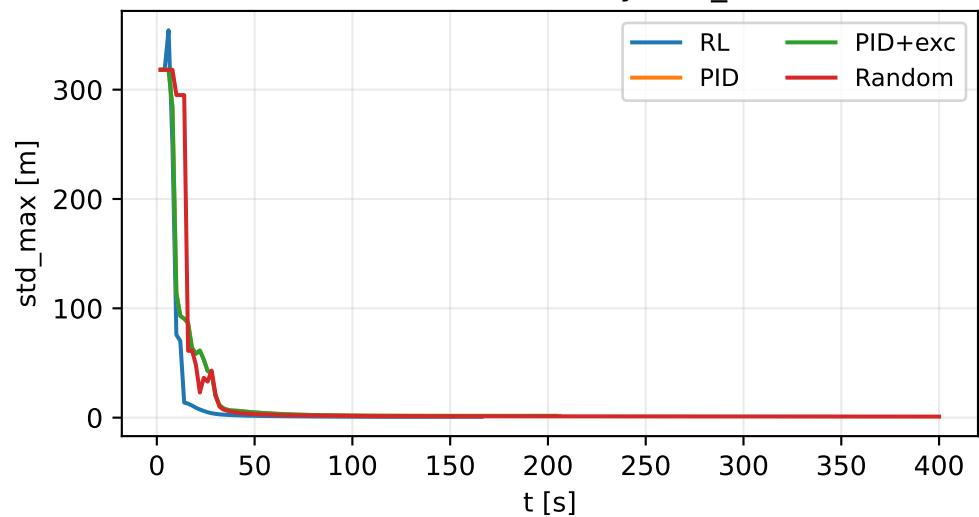
Trajectories (matched seed)



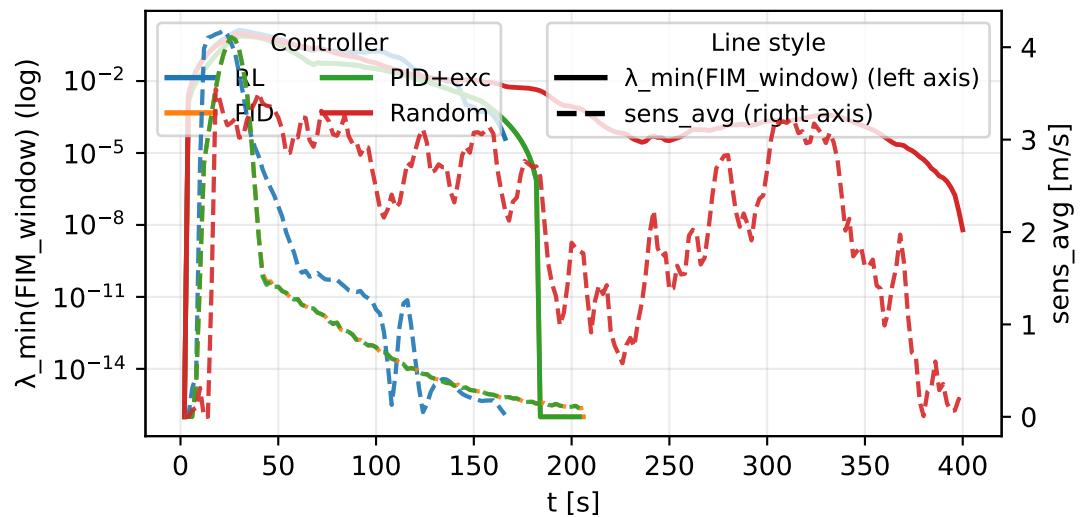
TRUE formation error



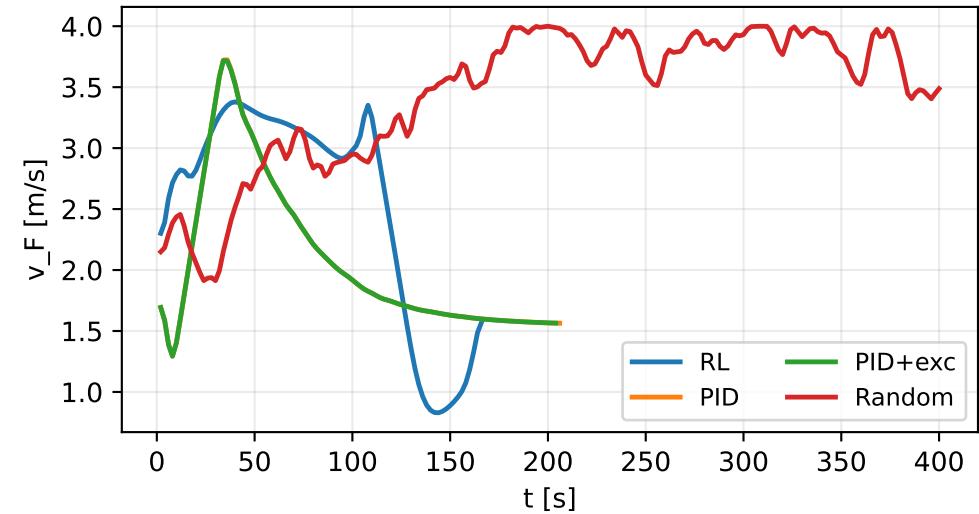
Estimator uncertainty (std_max)



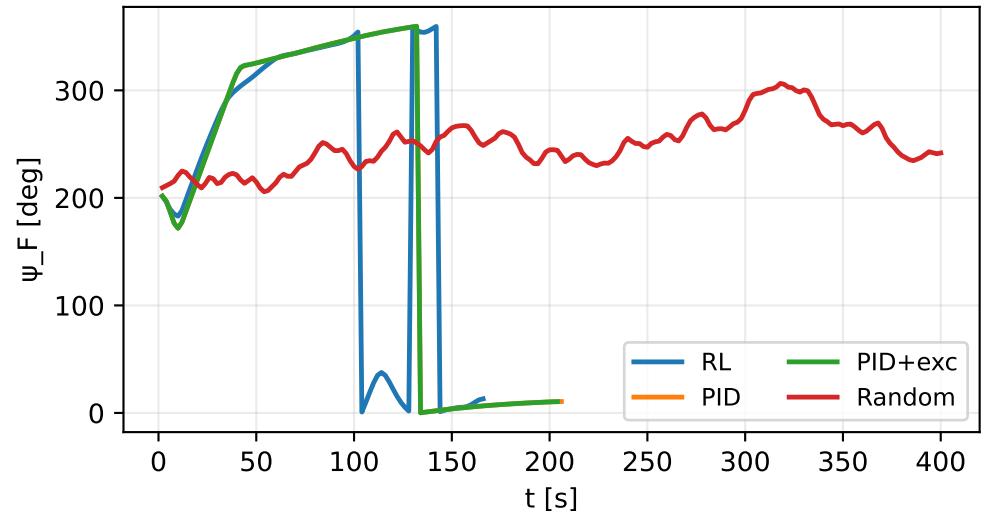
Information and excitation



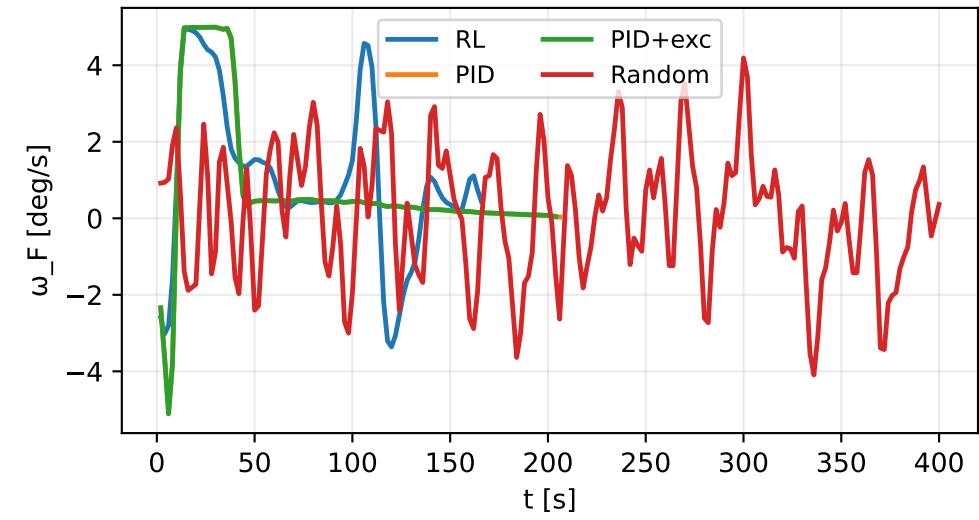
Follower speed



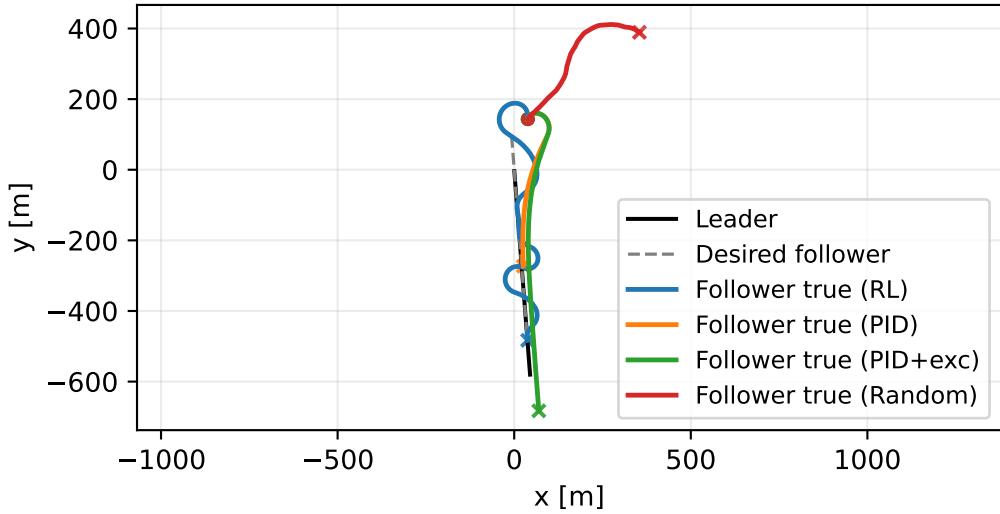
Follower course/heading



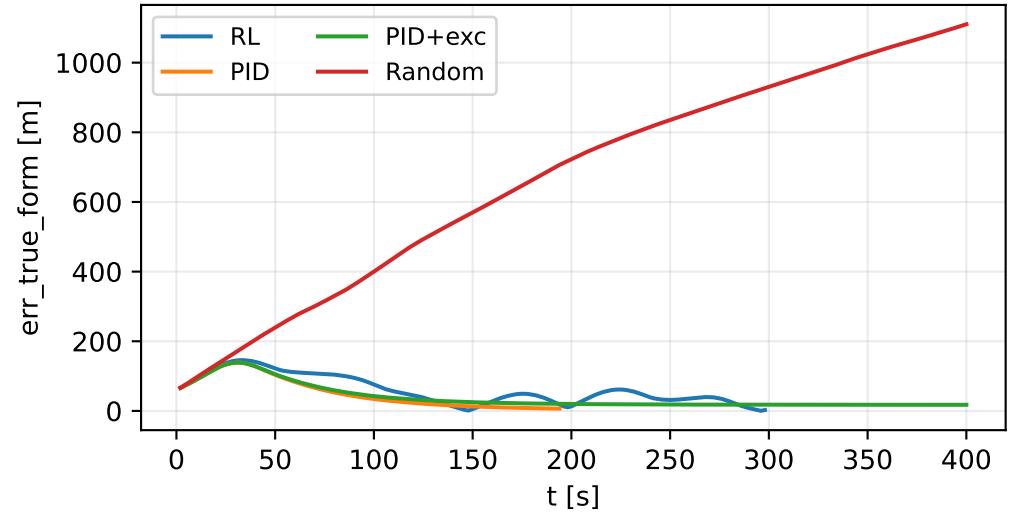
Follower angular rate



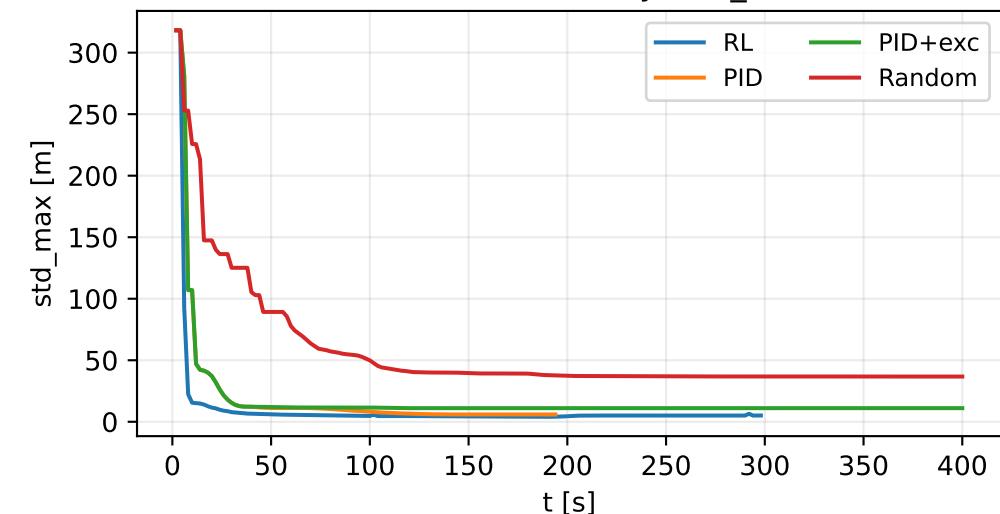
Trajectories (matched seed)



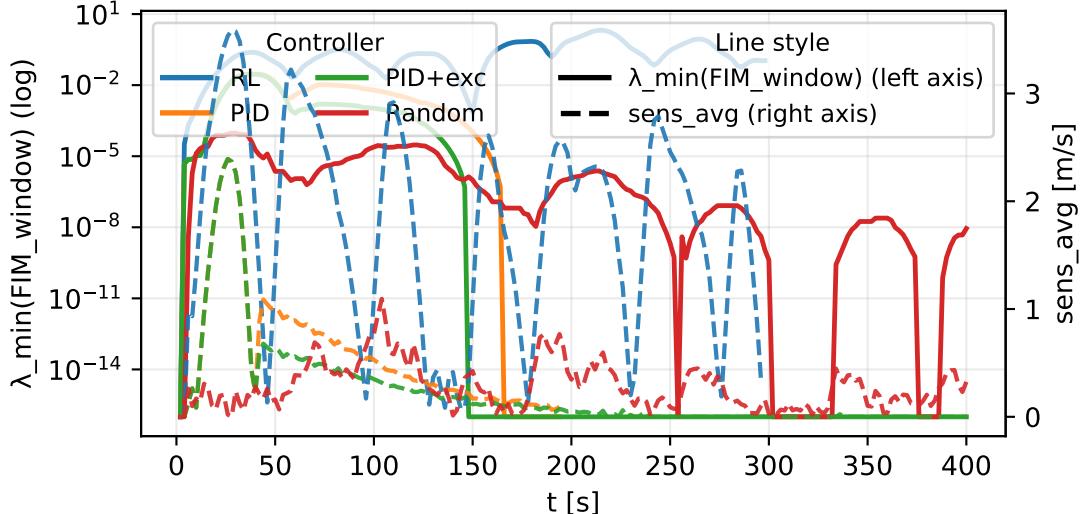
TRUE formation error



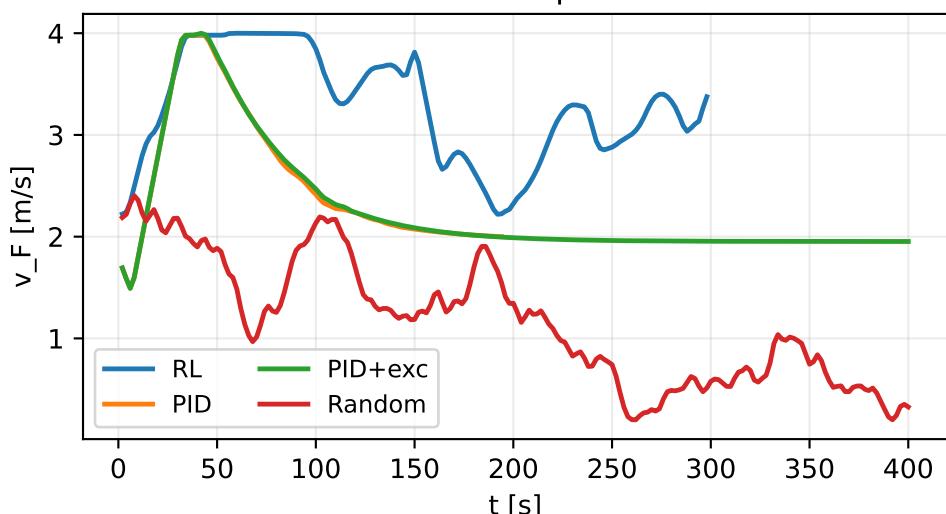
Estimator uncertainty (std_max)



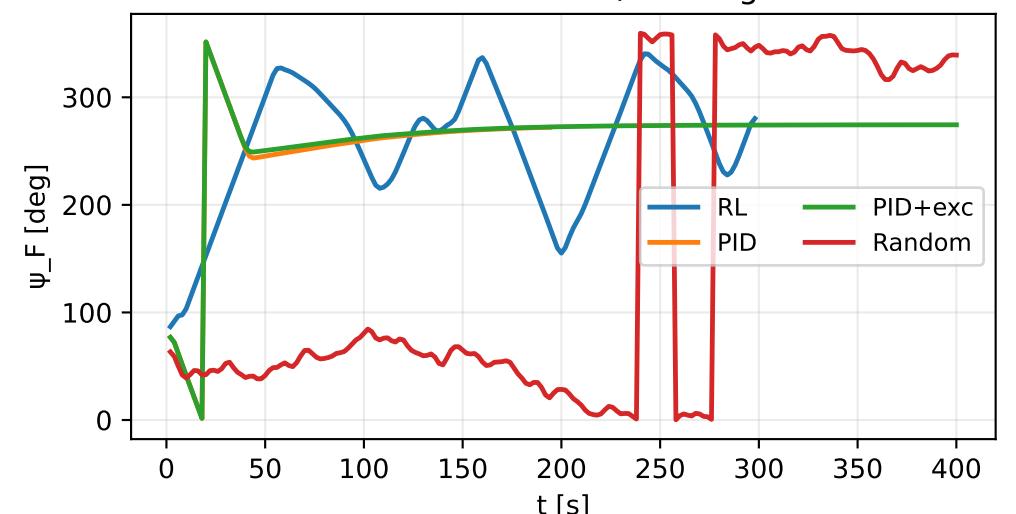
Information and excitation



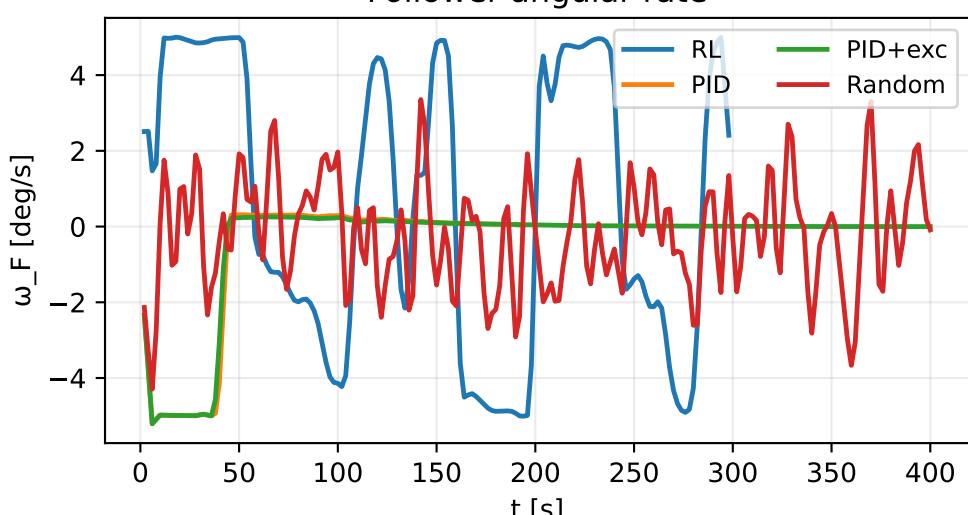
Follower speed



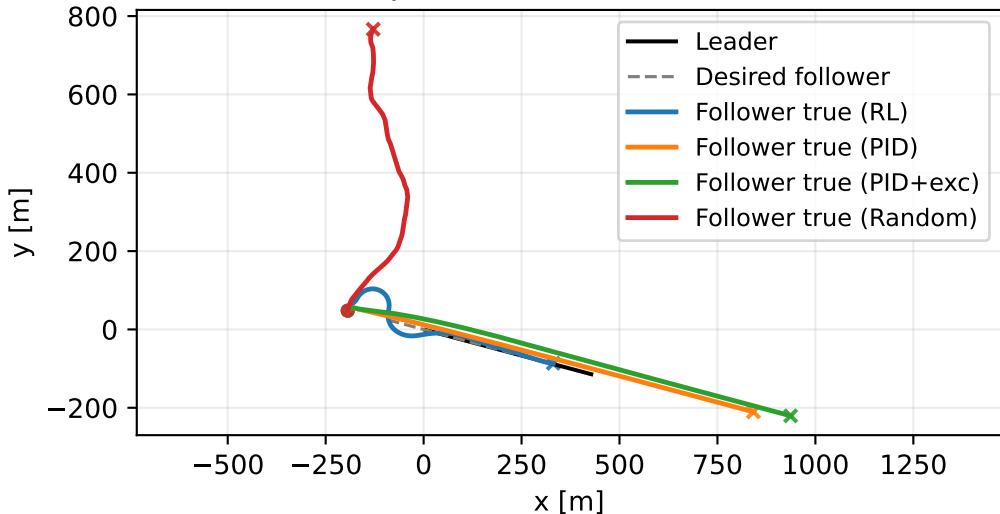
Follower course/heading



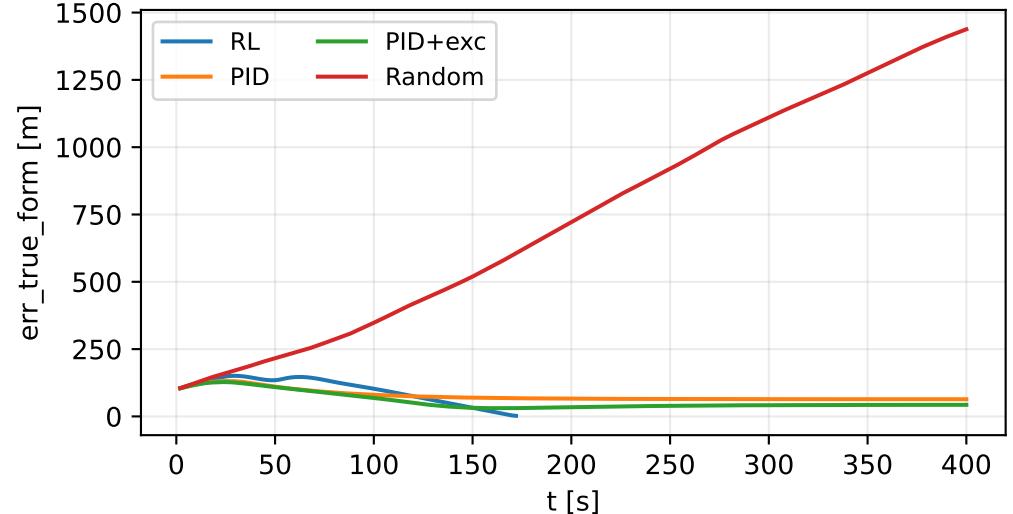
Follower angular rate



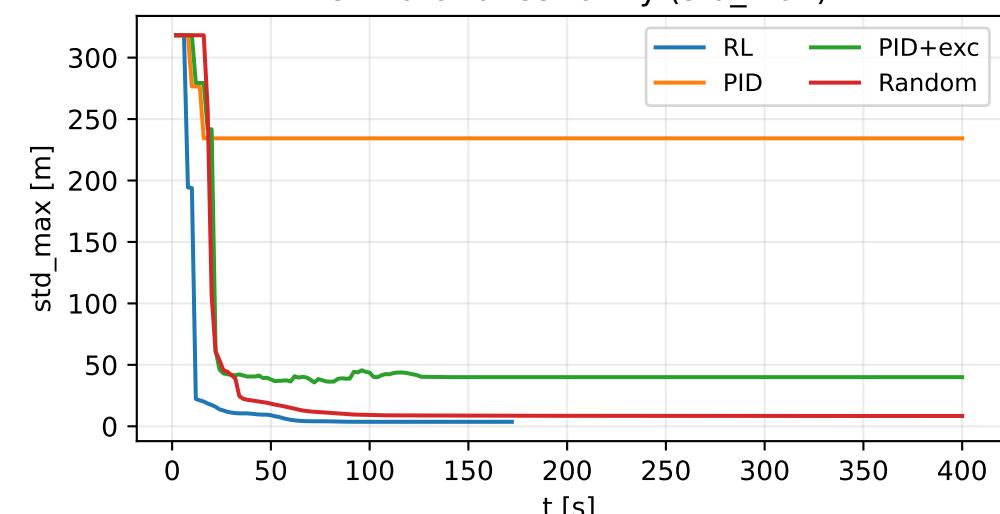
Trajectories (matched seed)



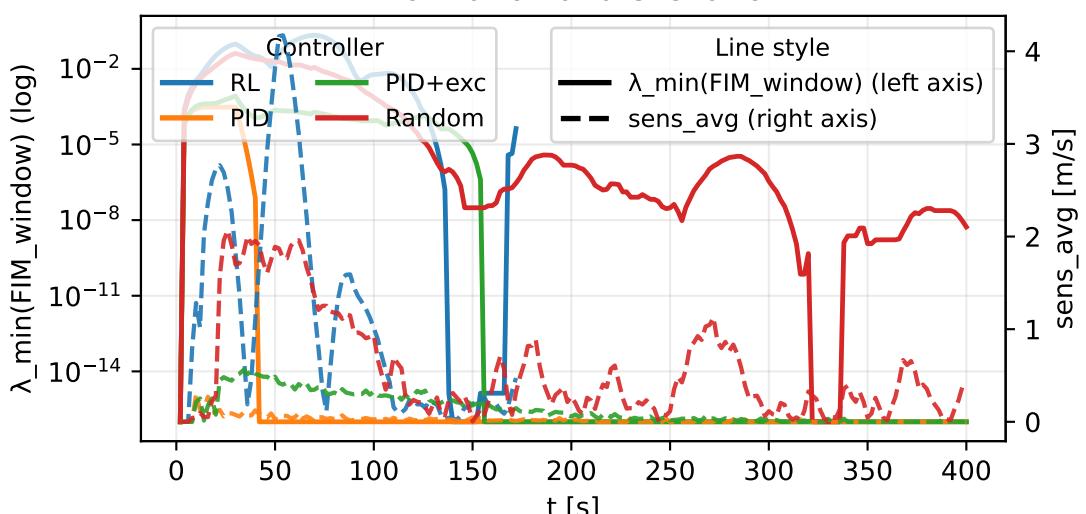
TRUE formation error



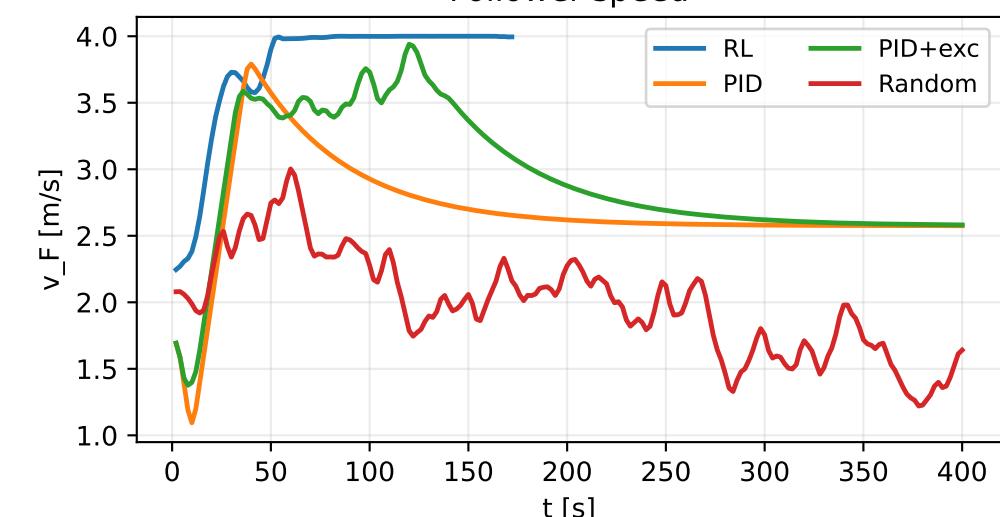
Estimator uncertainty (std_max)



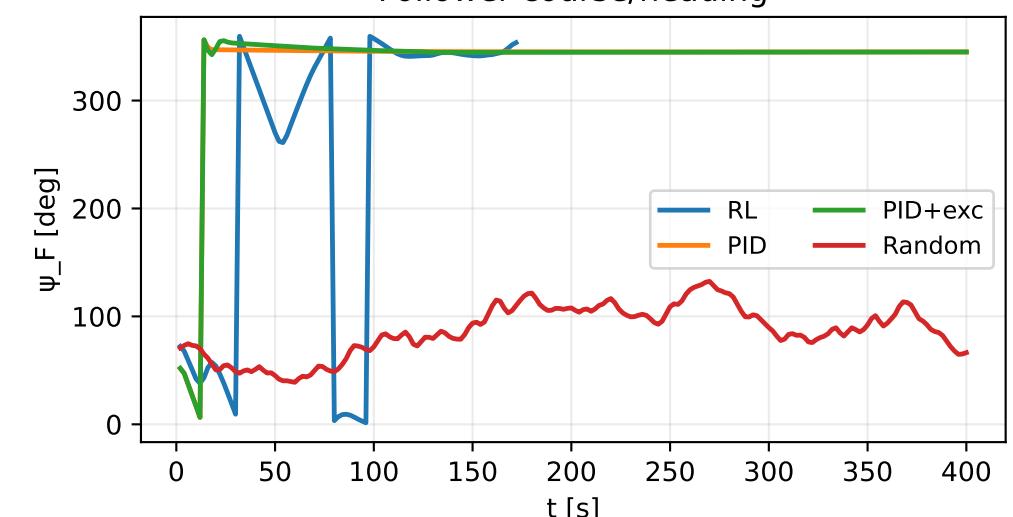
Information and excitation



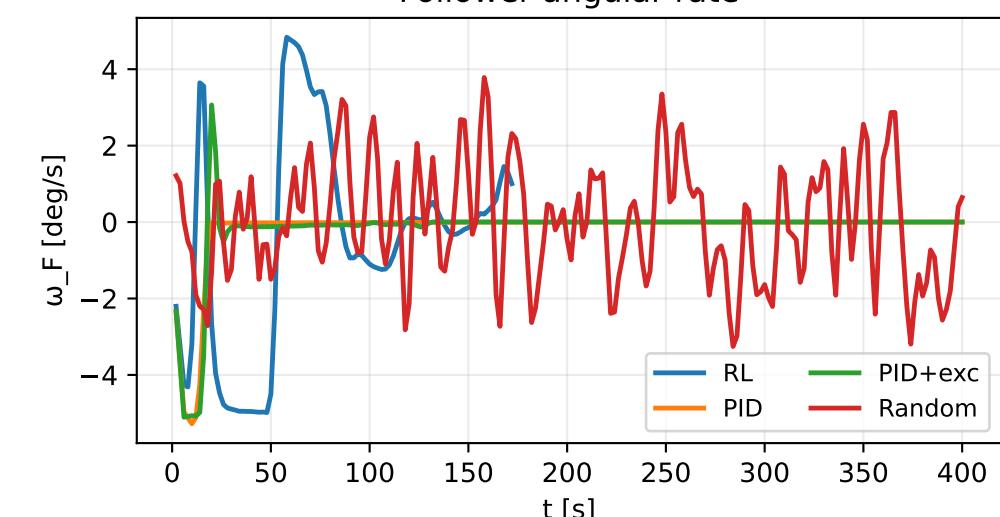
Follower speed



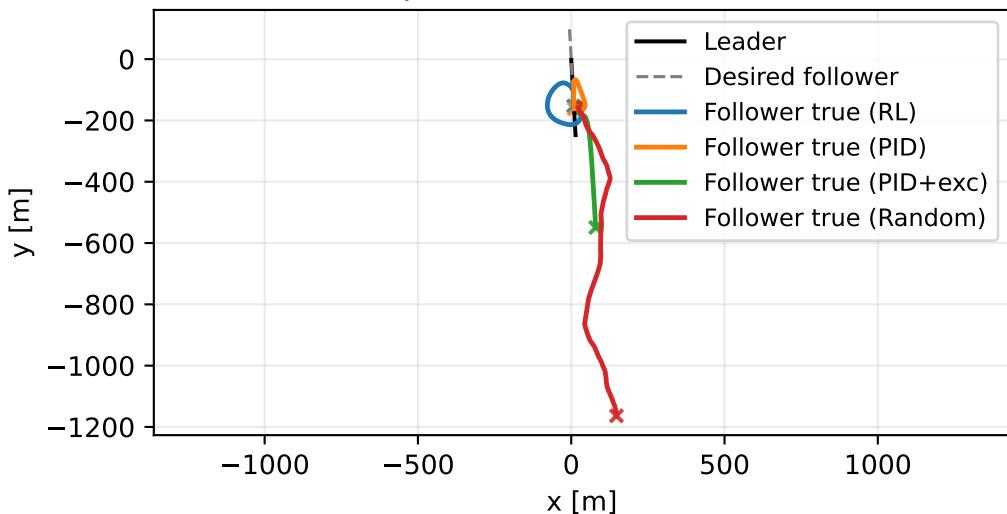
Follower course/heading



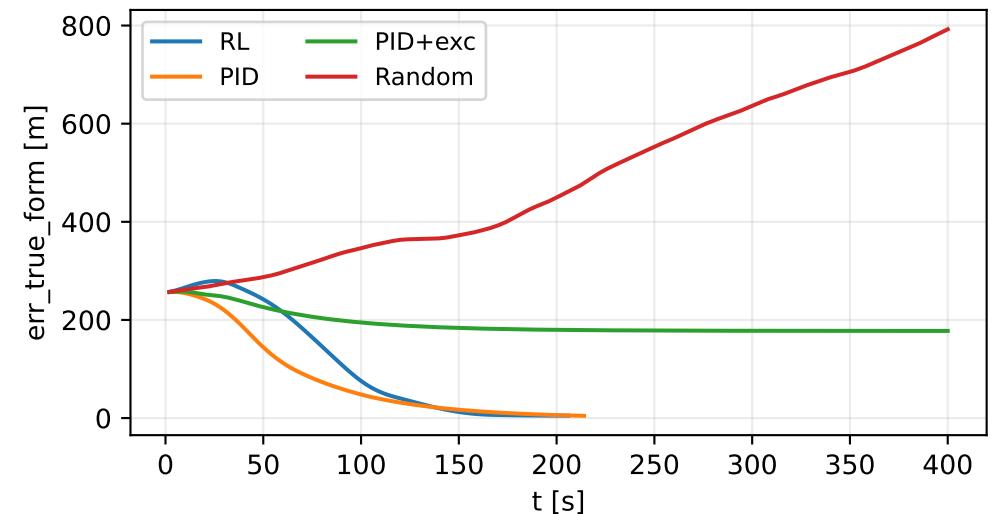
Follower angular rate



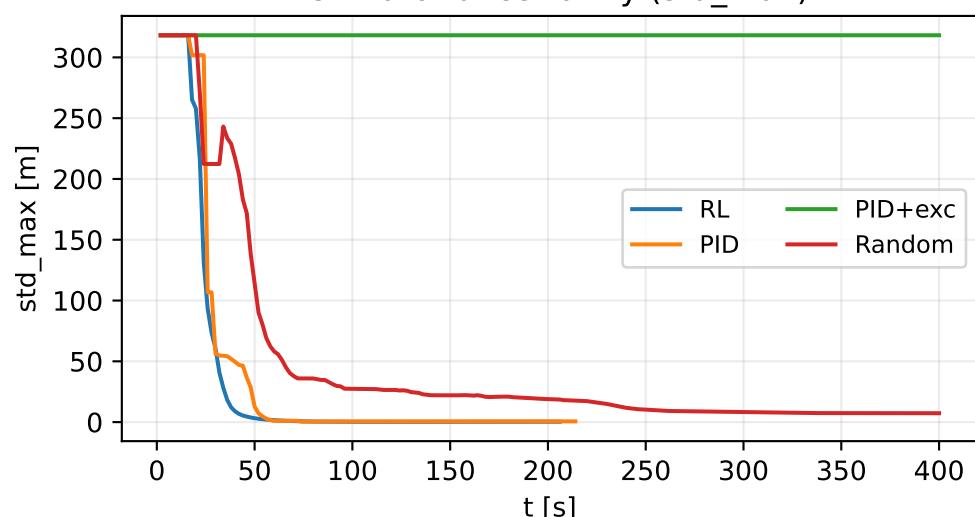
Trajectories (matched seed)



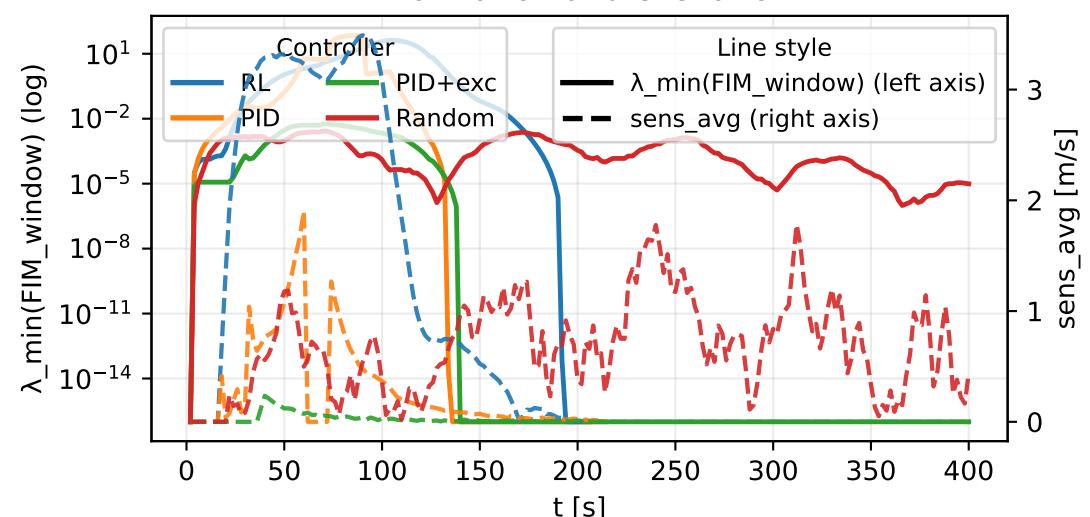
TRUE formation error



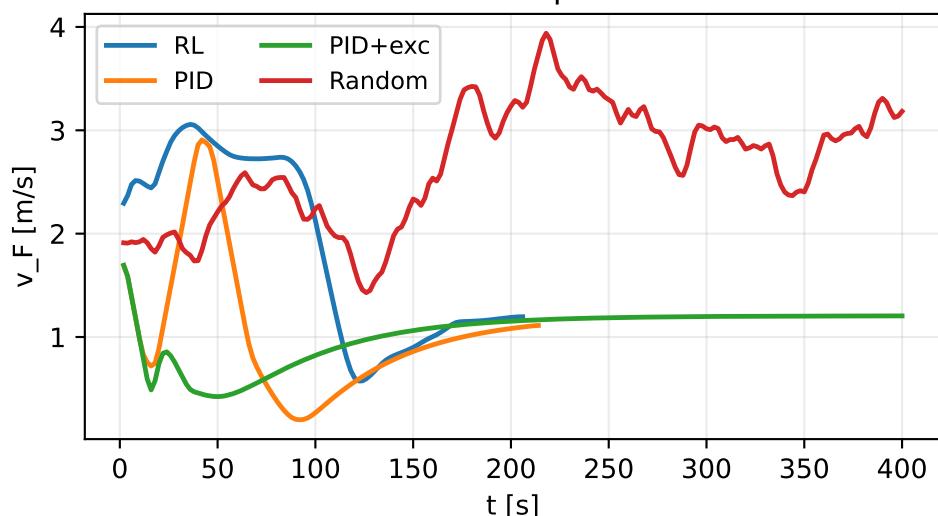
Estimator uncertainty (std_max)



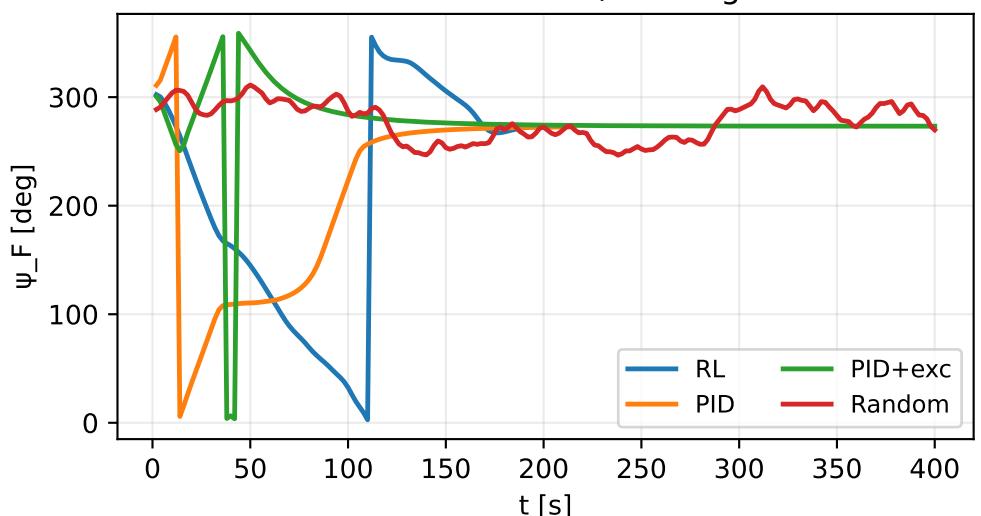
Information and excitation



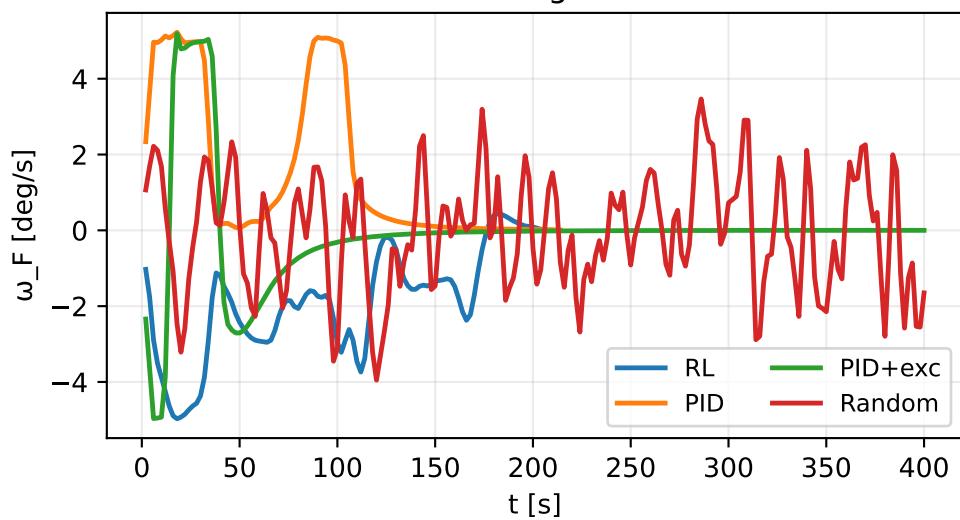
Follower speed



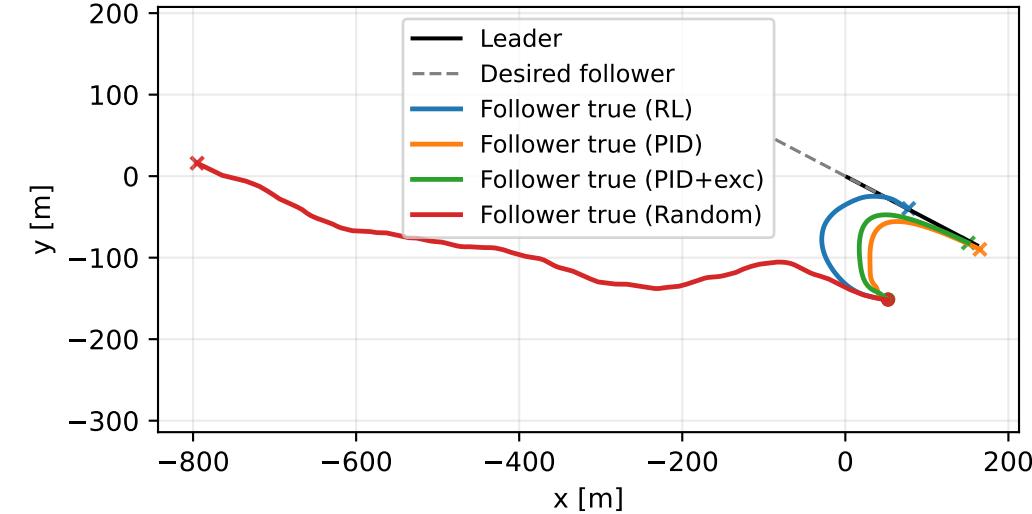
Follower course/heading



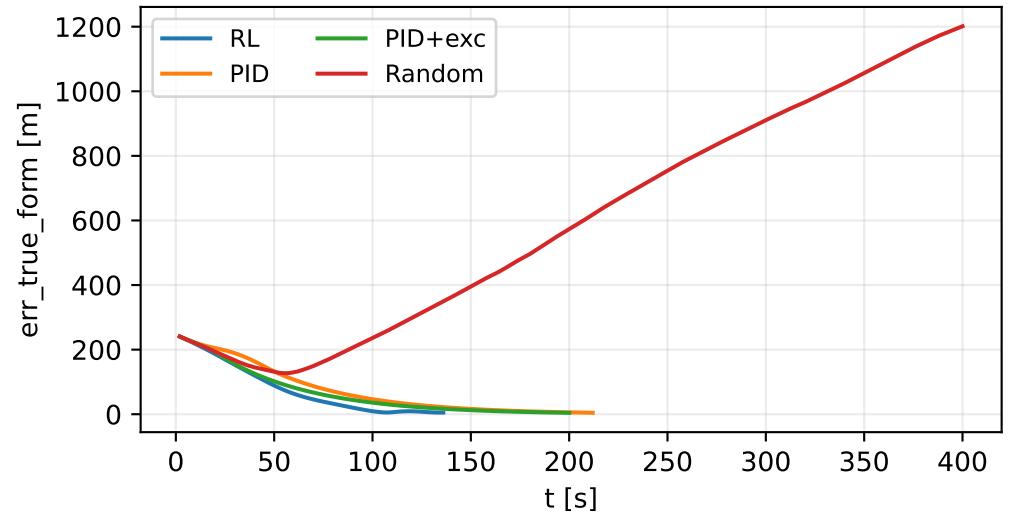
Follower angular rate



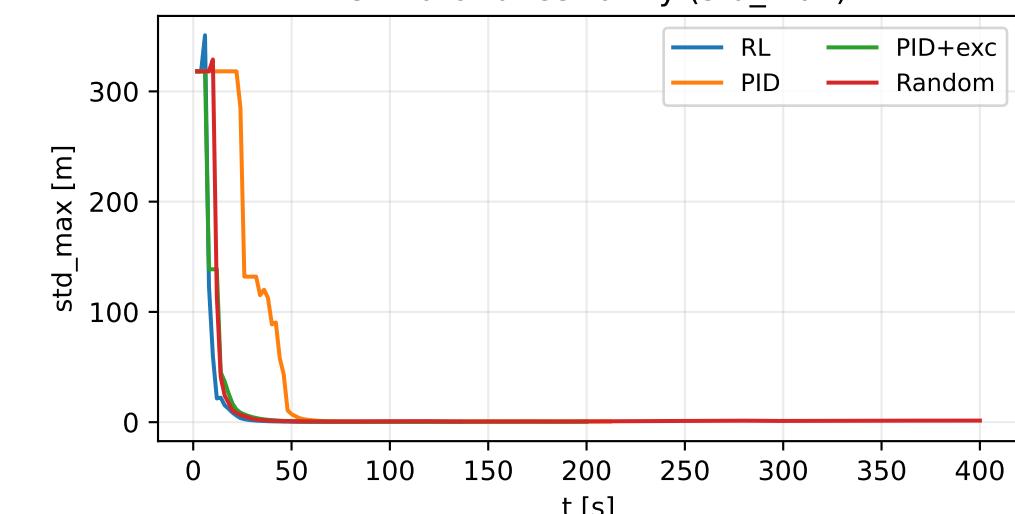
Trajectories (matched seed)



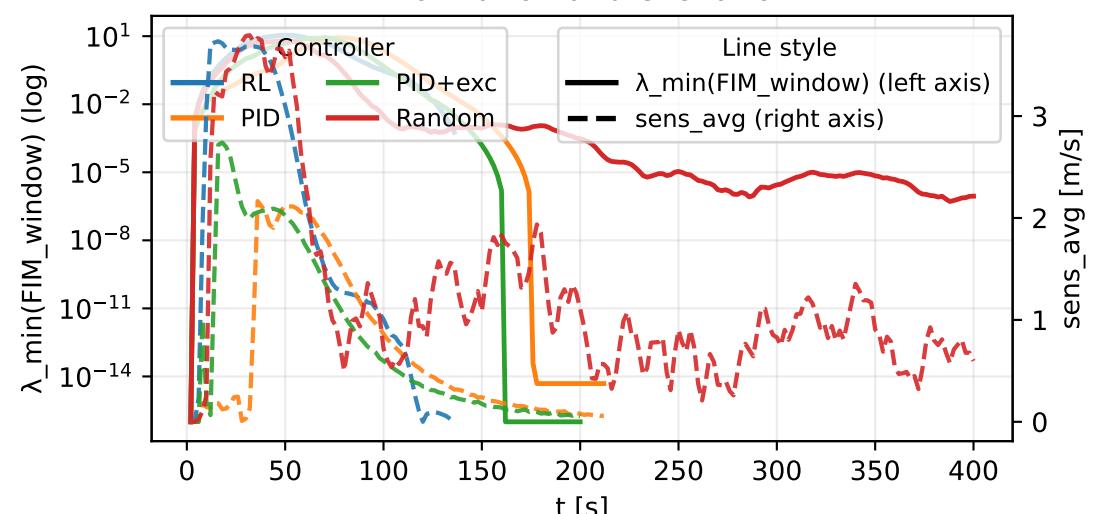
TRUE formation error



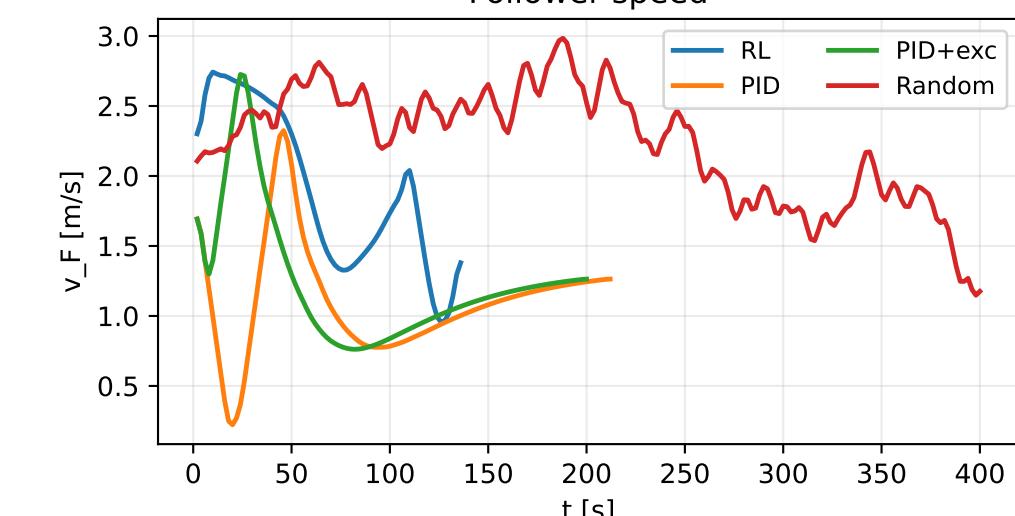
Estimator uncertainty (std_max)



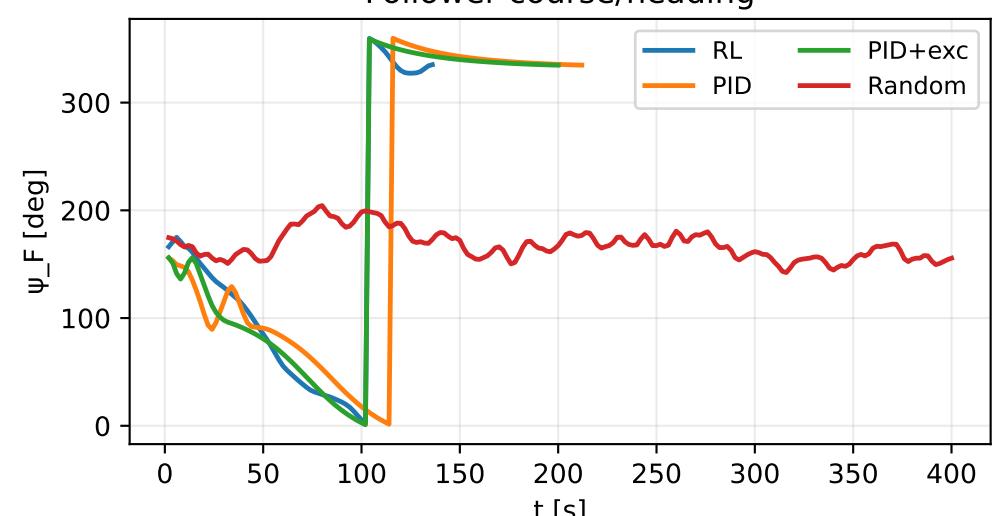
Information and excitation



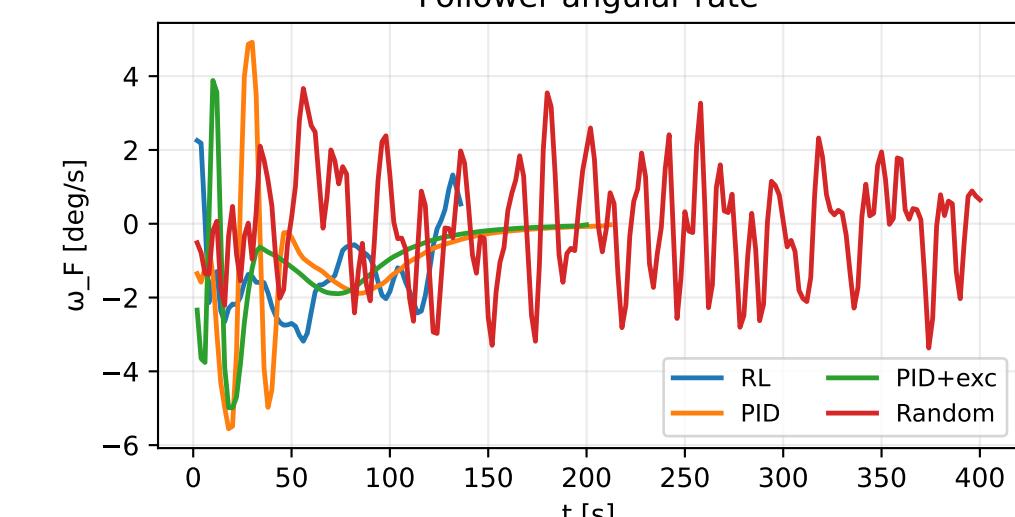
Follower speed



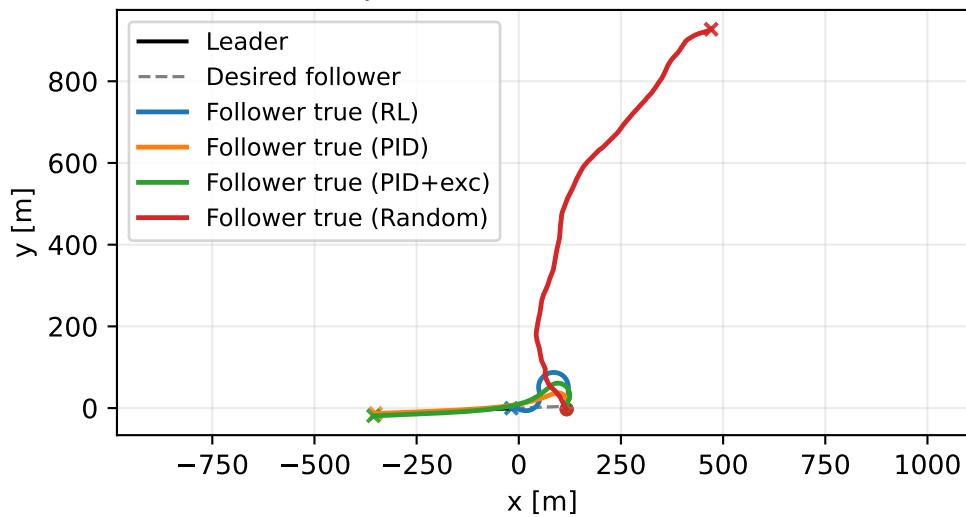
Follower course/heading



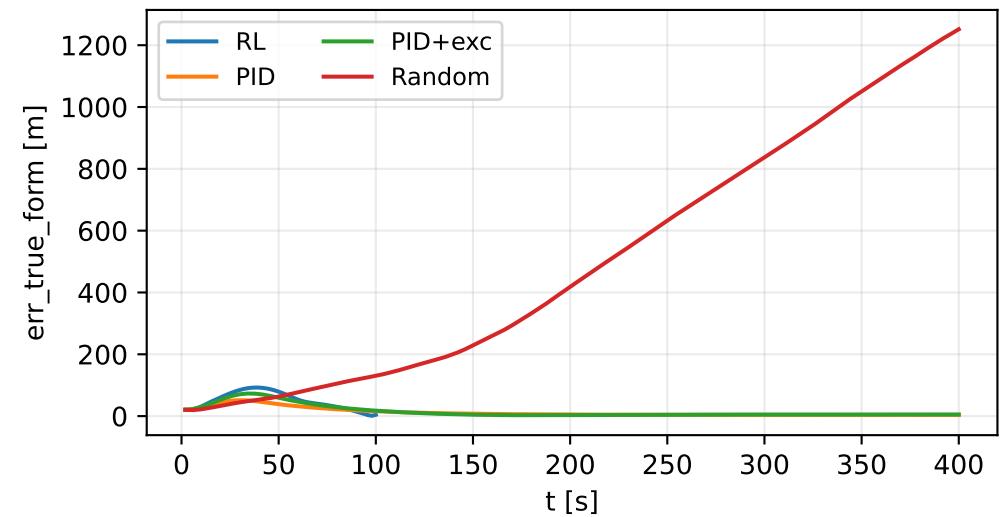
Follower angular rate



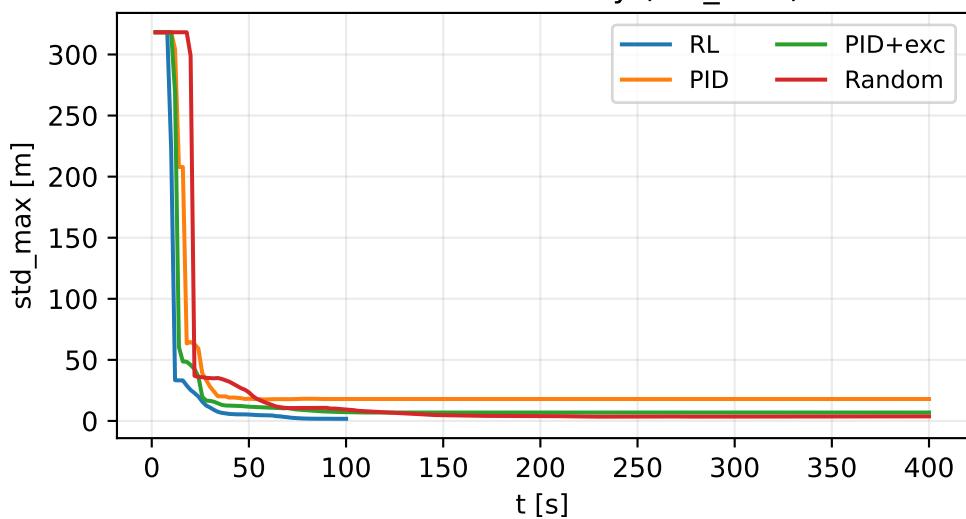
Trajectories (matched seed)



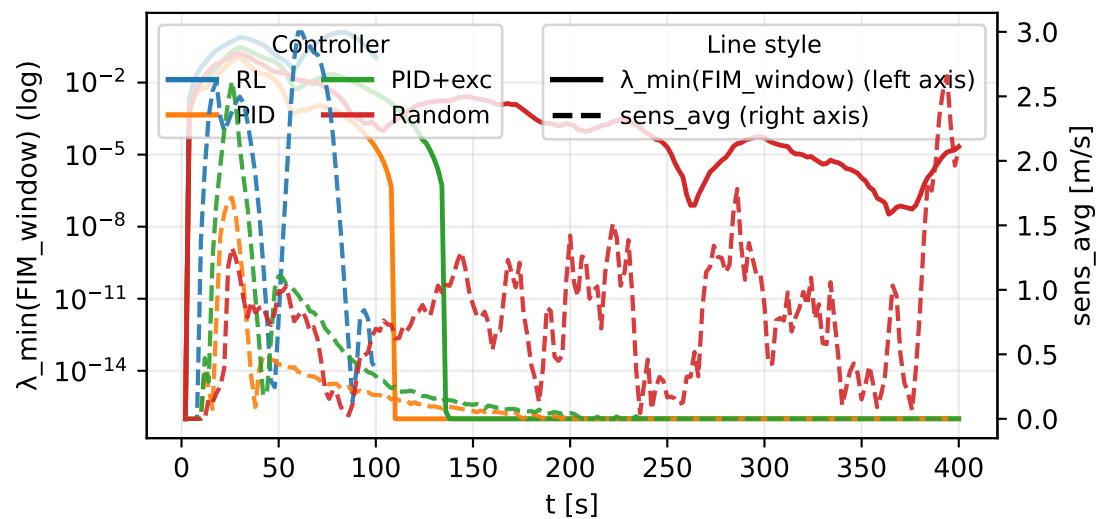
TRUE formation error



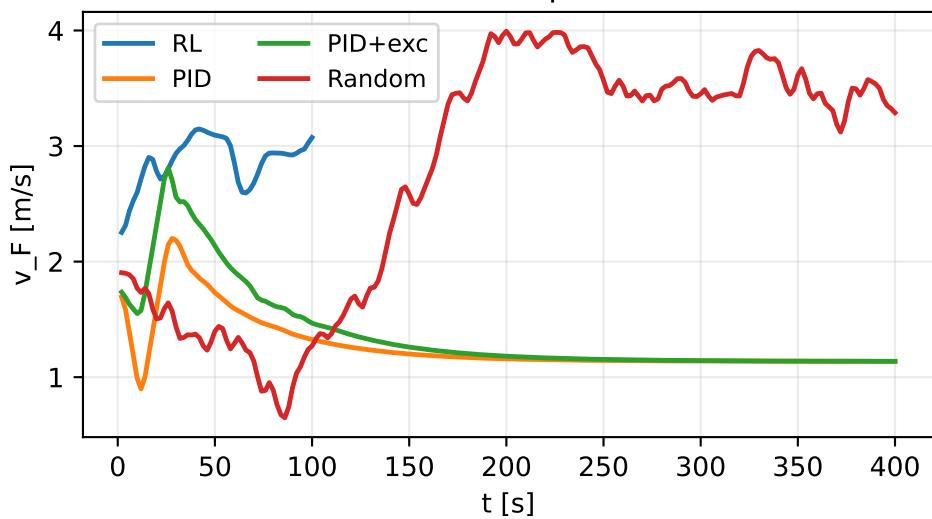
Estimator uncertainty (std_max)



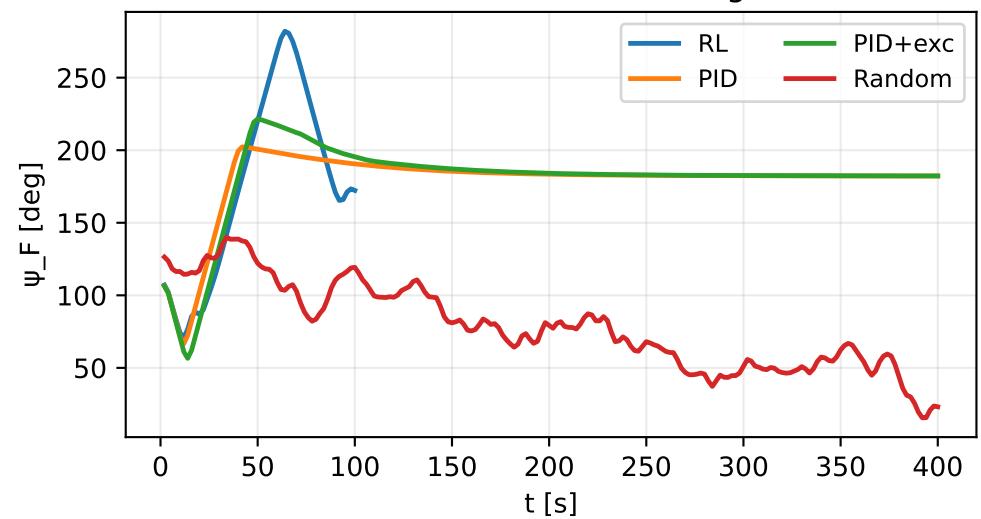
Information and excitation



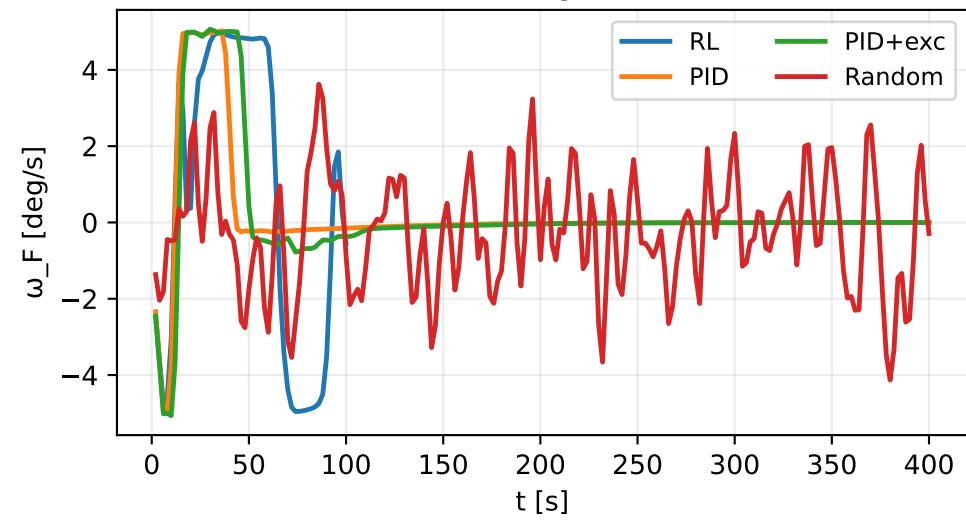
Follower speed



Follower course/heading

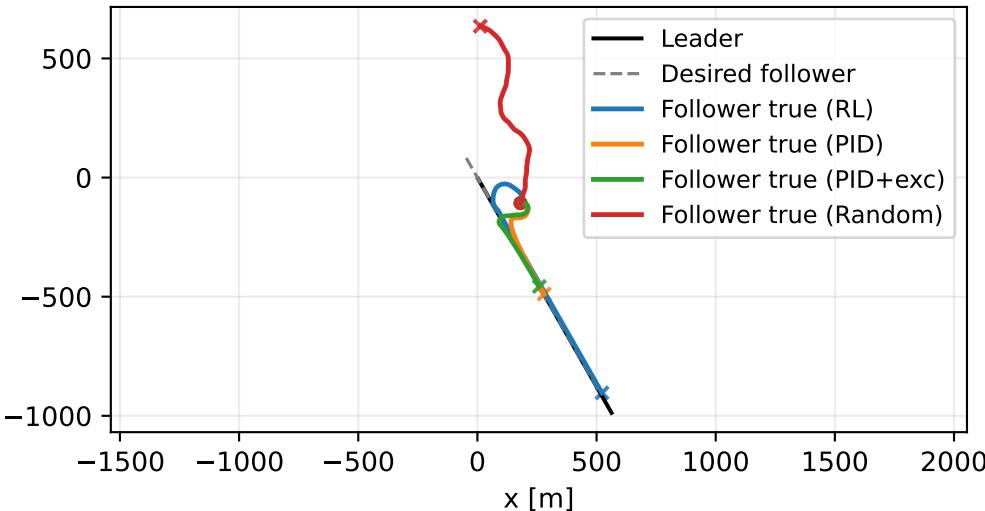


Follower angular rate



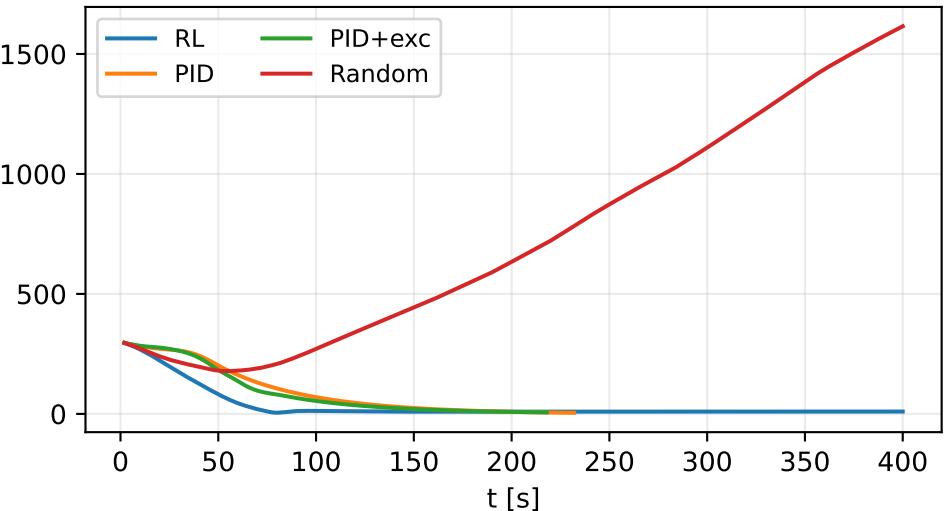
Trajectories (matched seed)

y [m]



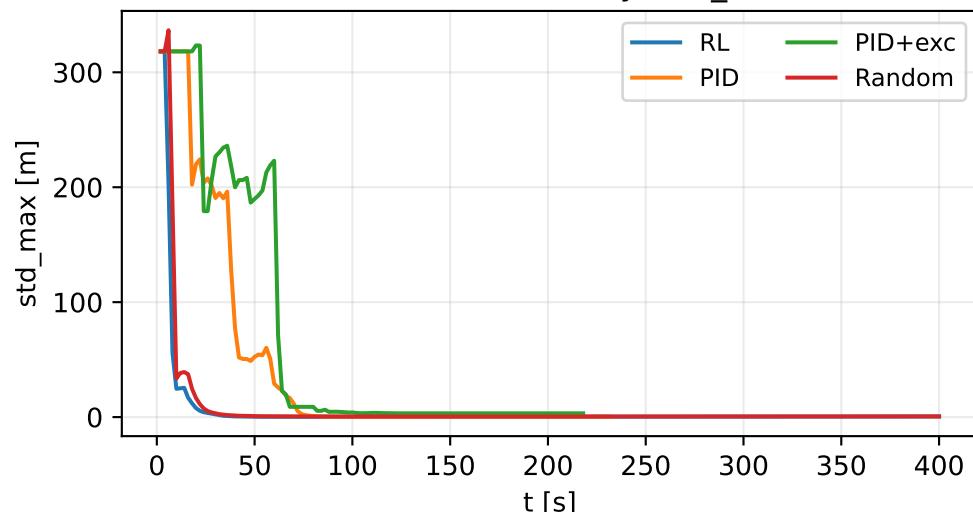
TRUE formation error

err_true_form [m]

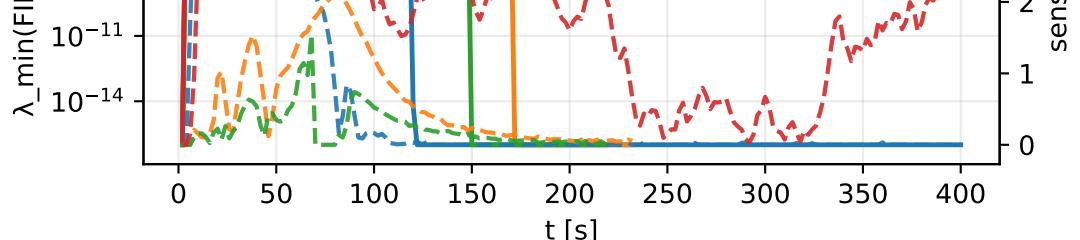


Estimator uncertainty (std_max)

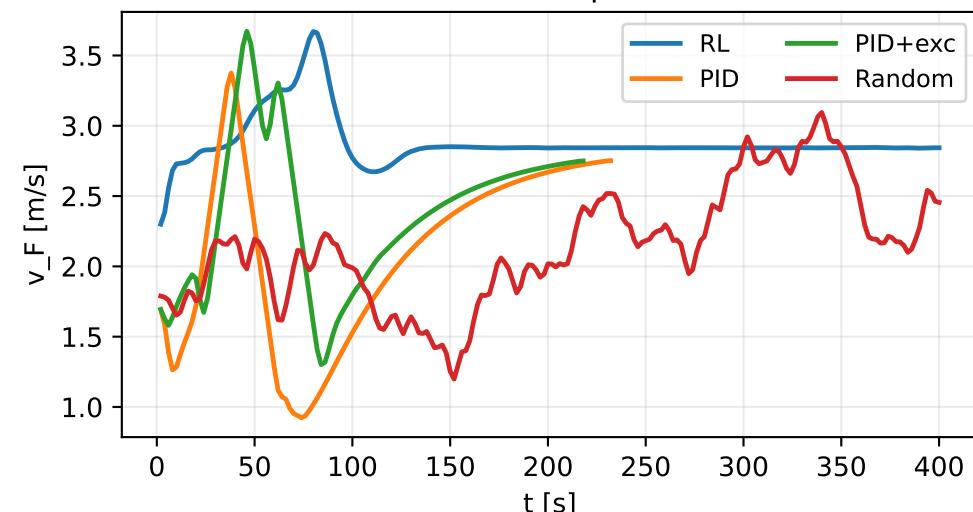
std_max [m]



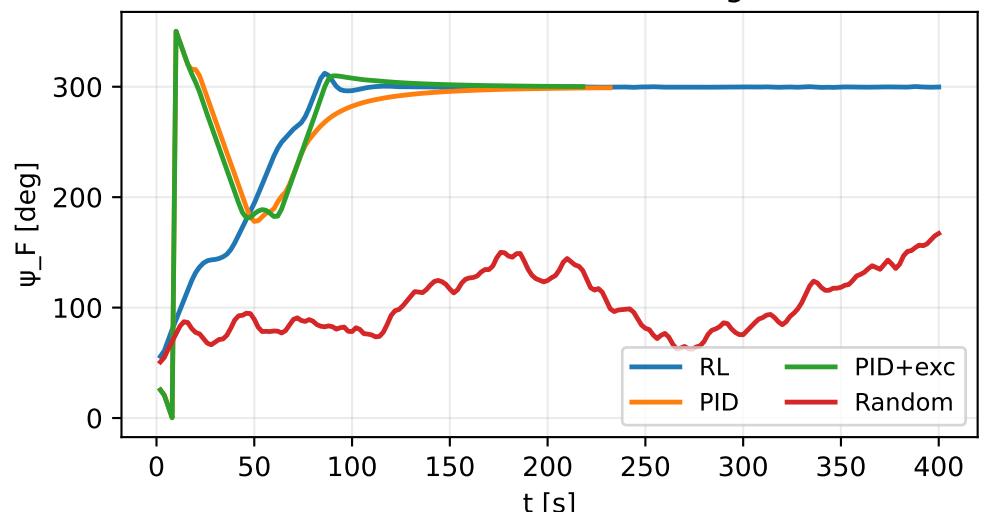
Information and excitation

 $\lambda_{\min}(\text{FIM_window})$ (log)

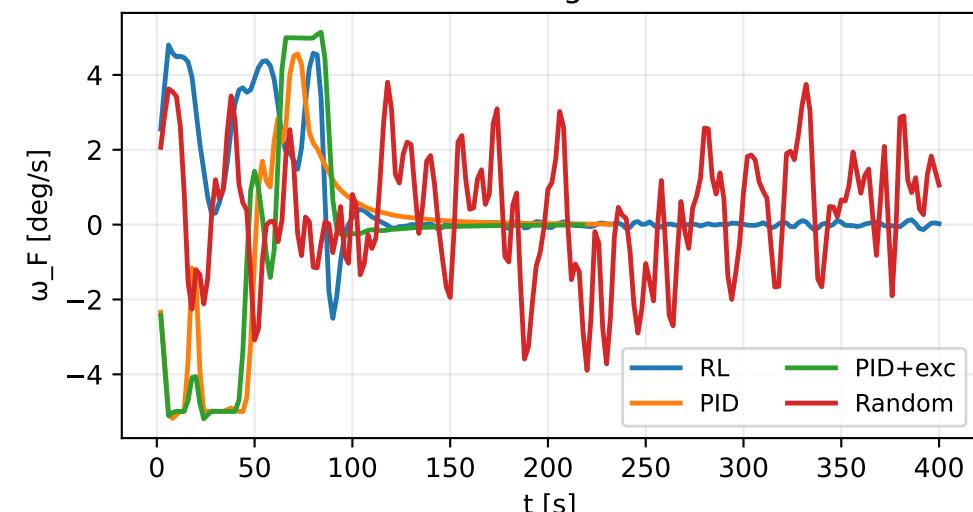
Follower speed

 v_F [m/s]

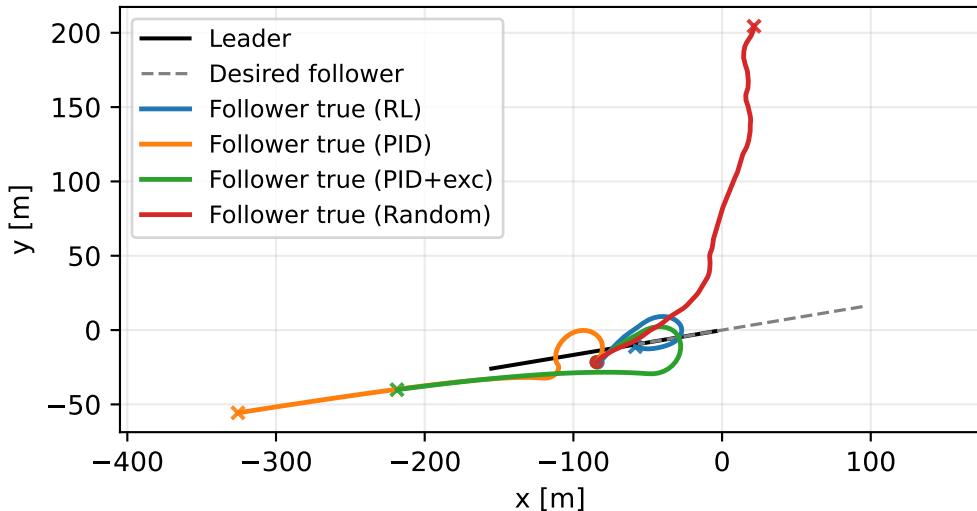
Follower course/heading

 ψ_F [deg]

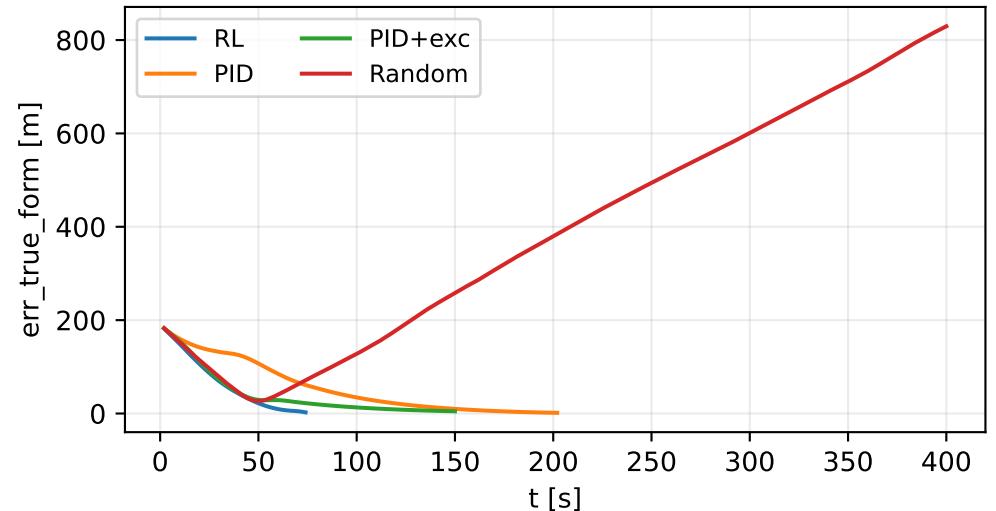
Follower angular rate

 ω_F [deg/s]

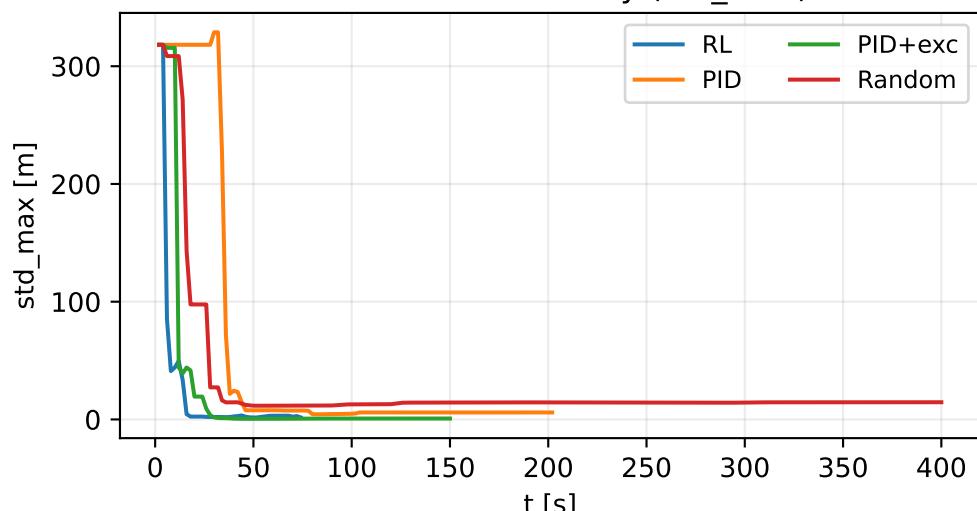
Trajectories (matched seed)



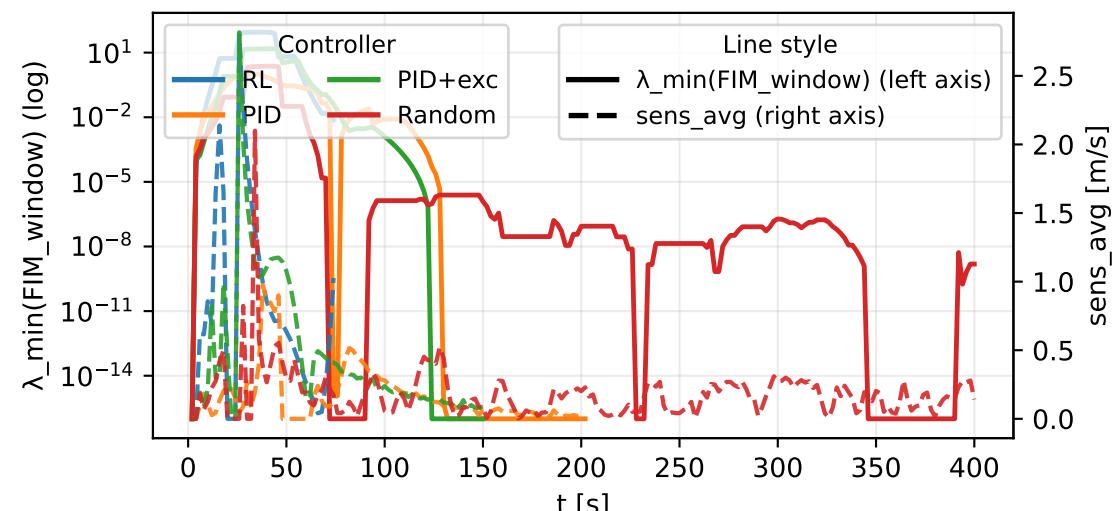
TRUE formation error



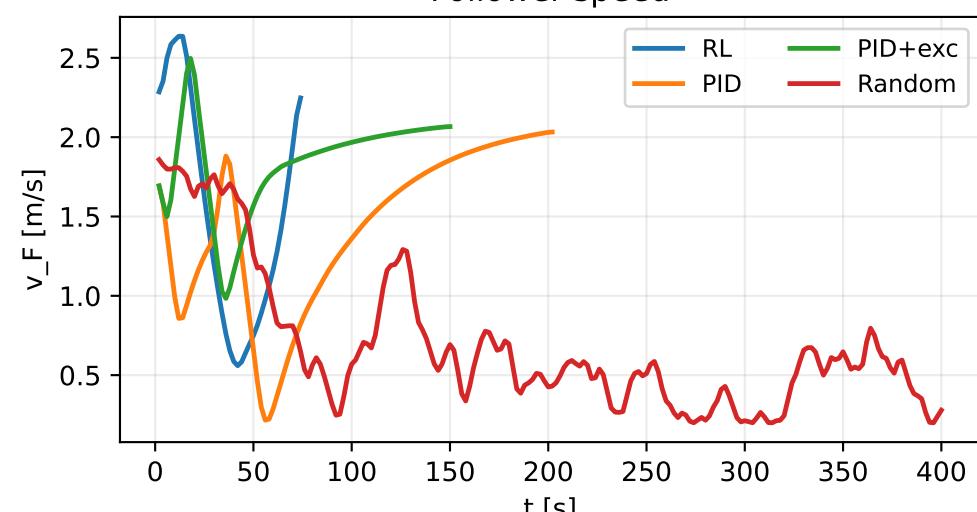
Estimator uncertainty (std_max)



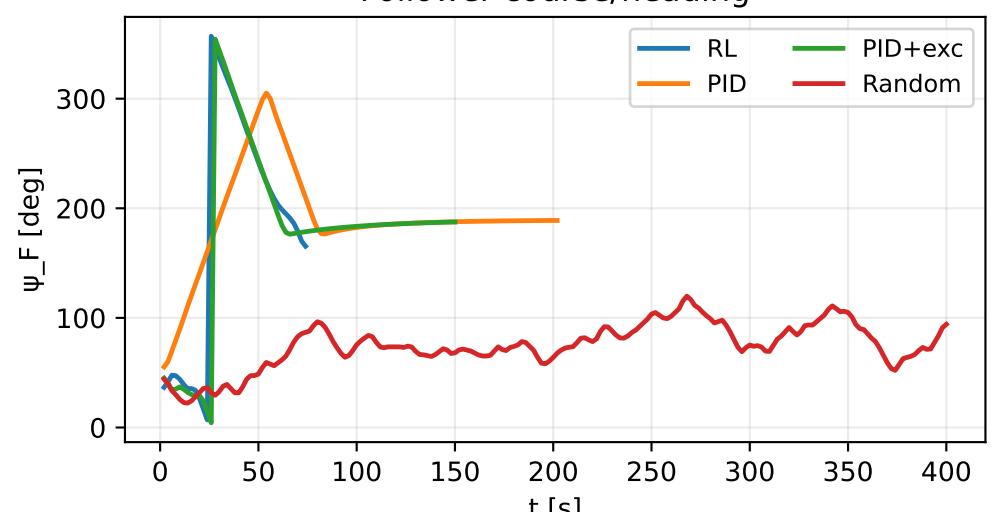
Information and excitation



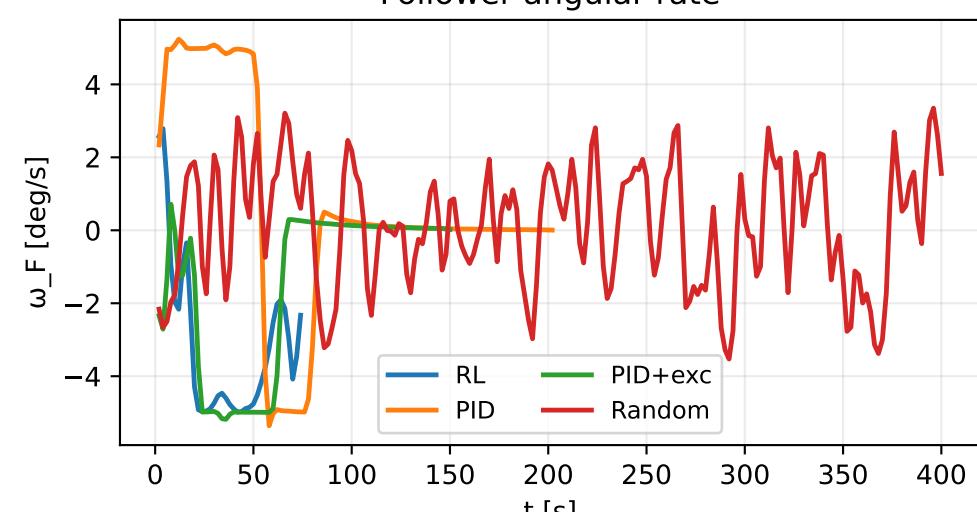
Follower speed



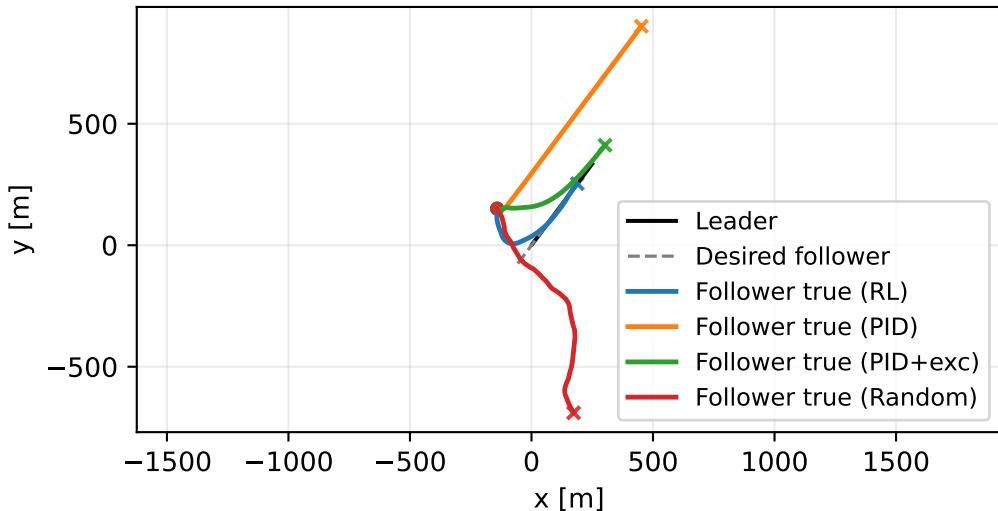
Follower course/heading



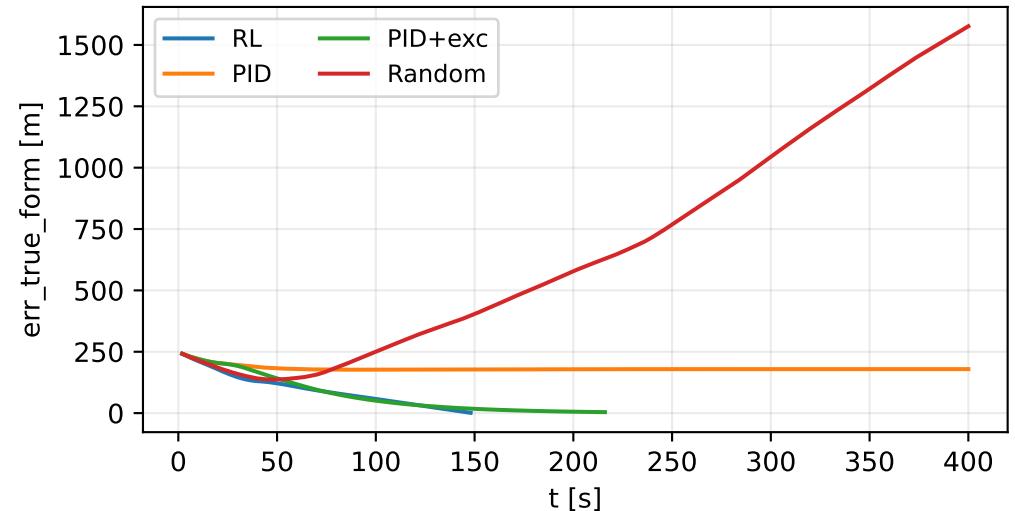
Follower angular rate



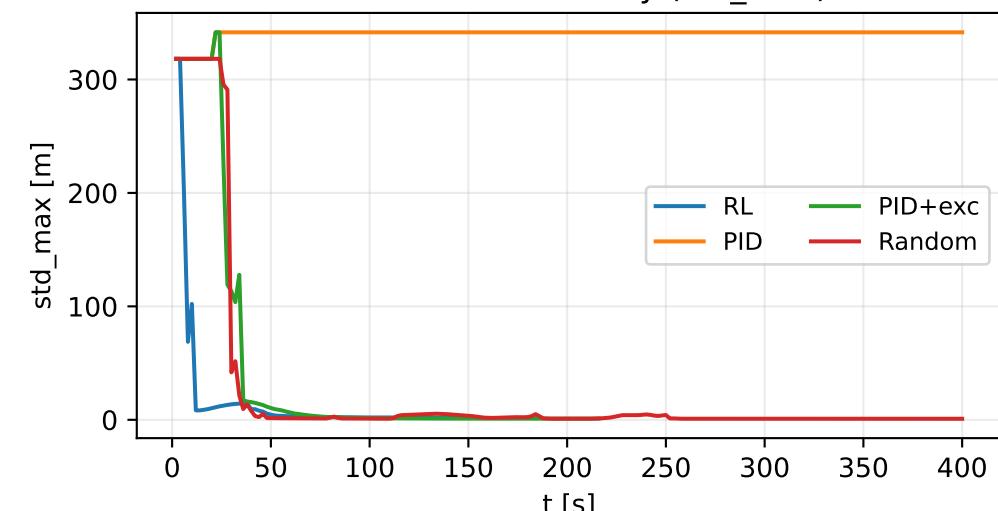
Trajectories (matched seed)



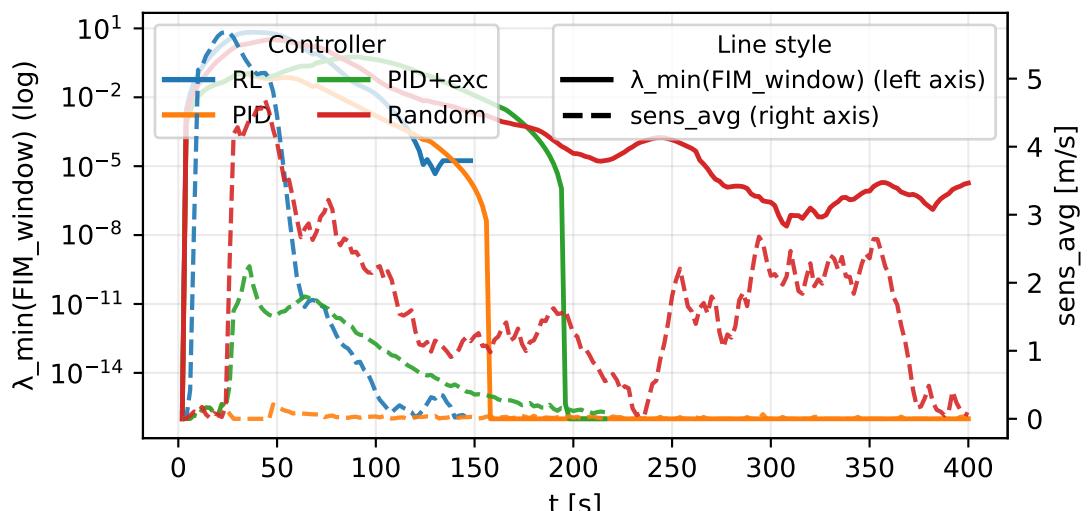
TRUE formation error



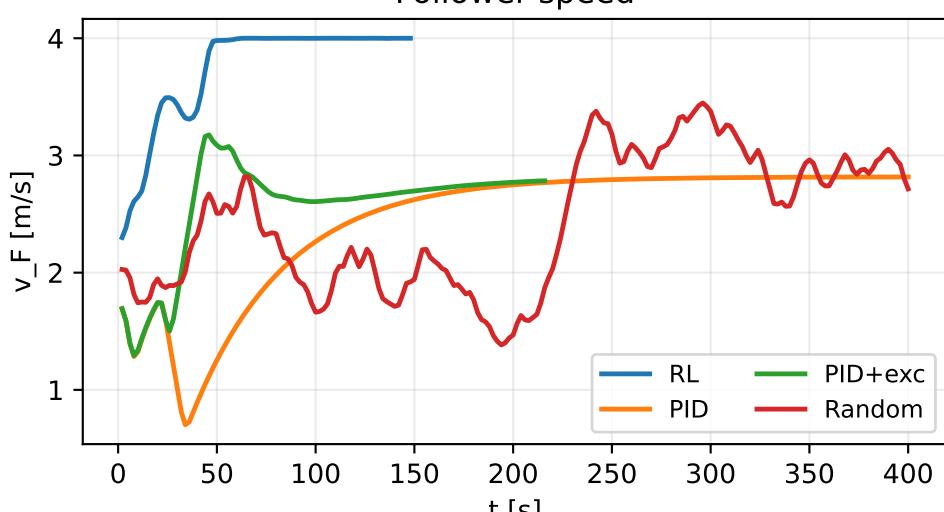
Estimator uncertainty (std_max)



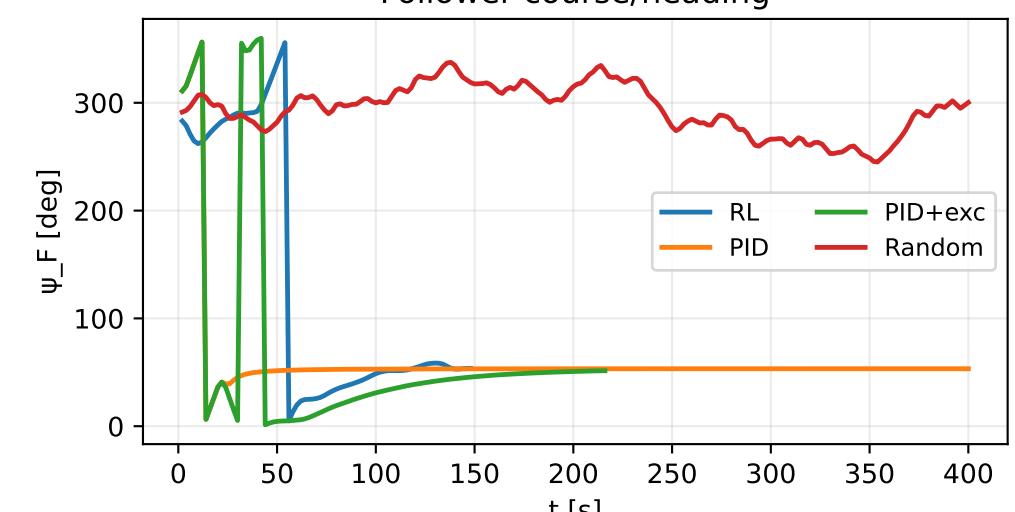
Information and excitation



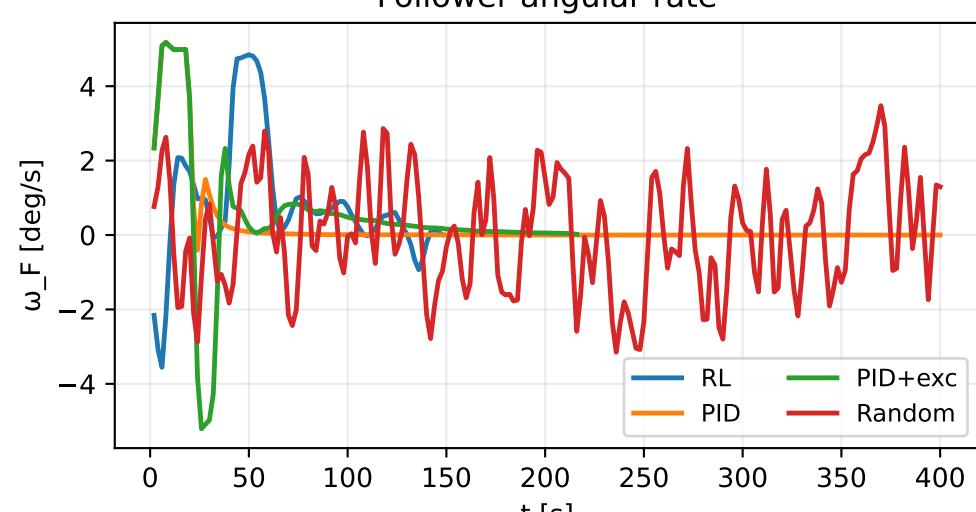
Follower speed



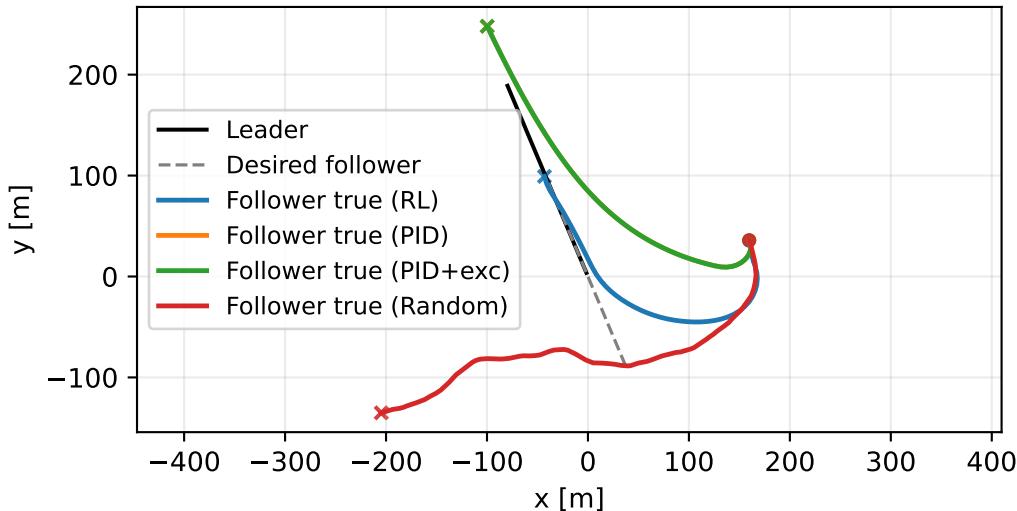
Follower course/heading



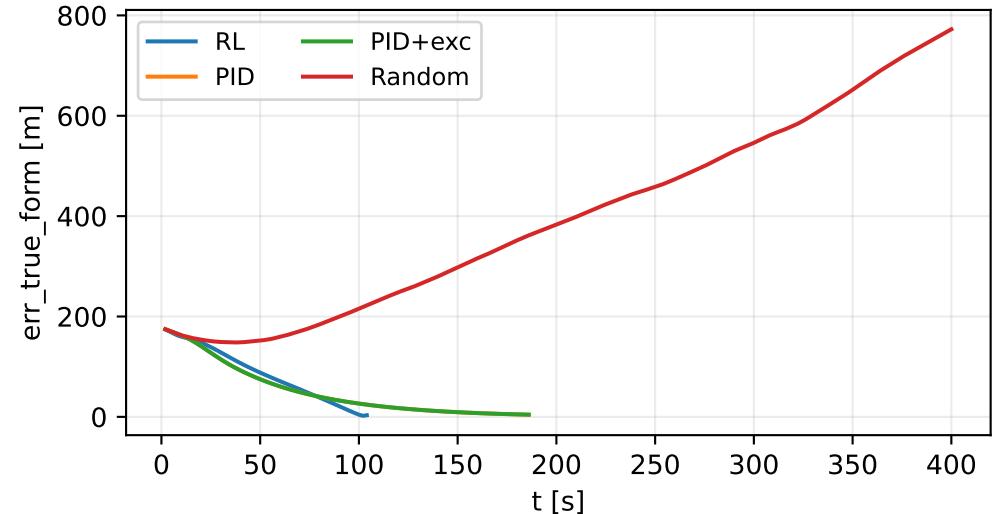
Follower angular rate



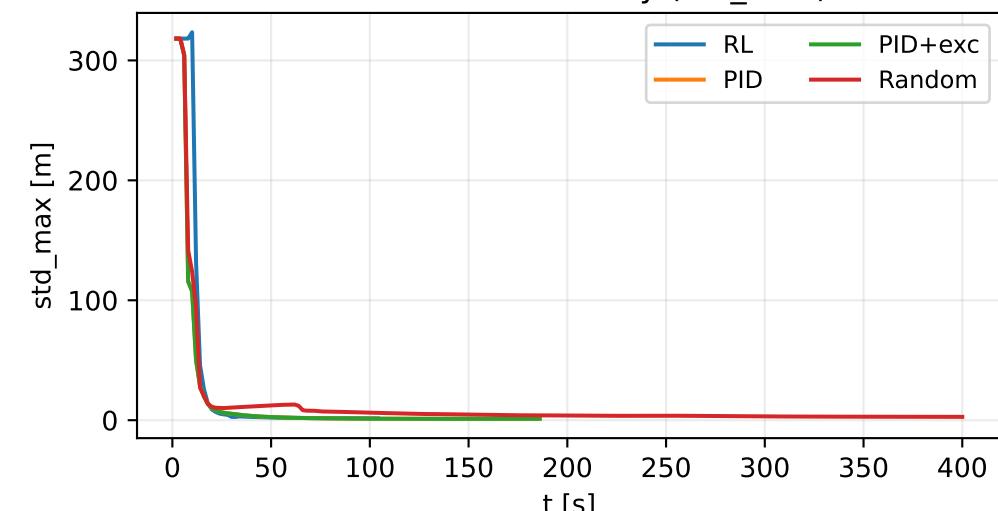
Trajectories (matched seed)



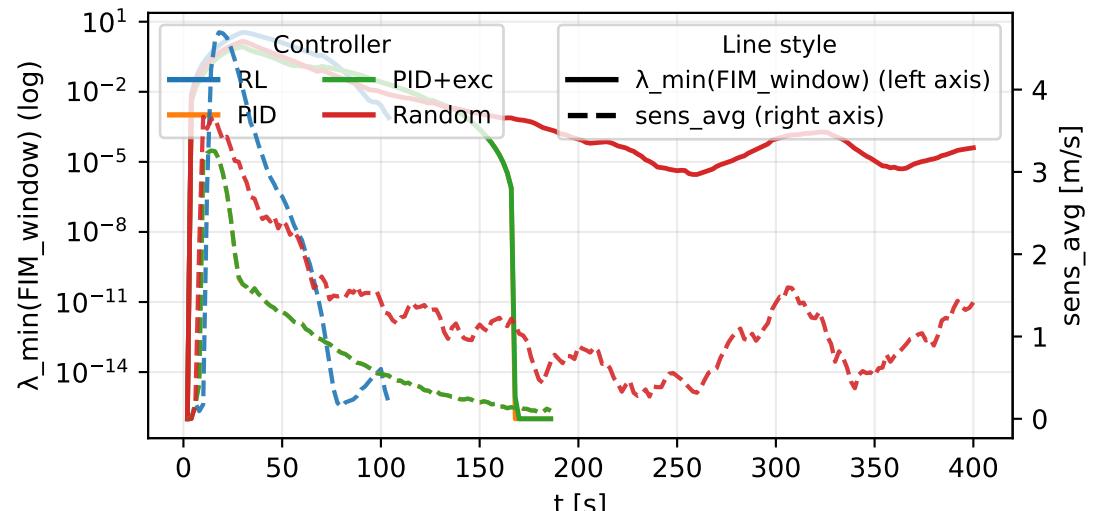
TRUE formation error



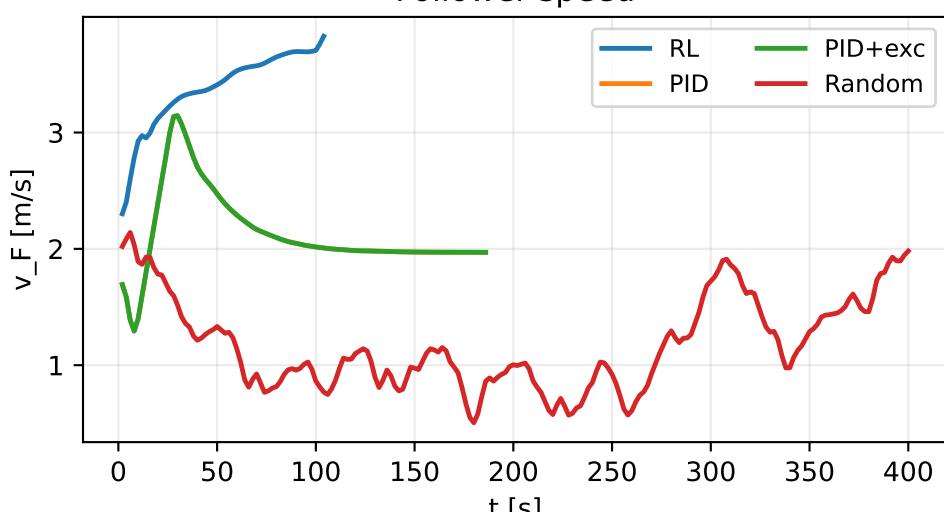
Estimator uncertainty (std_max)



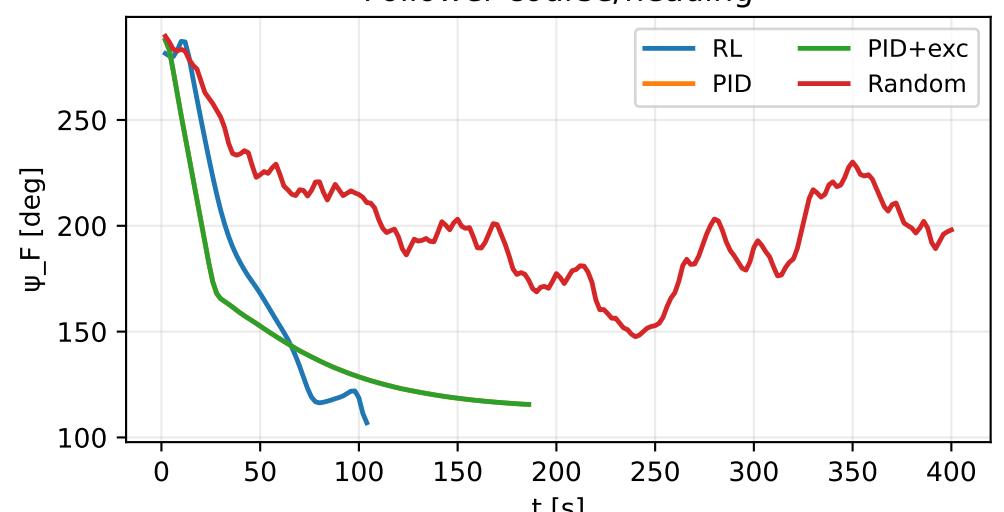
Information and excitation



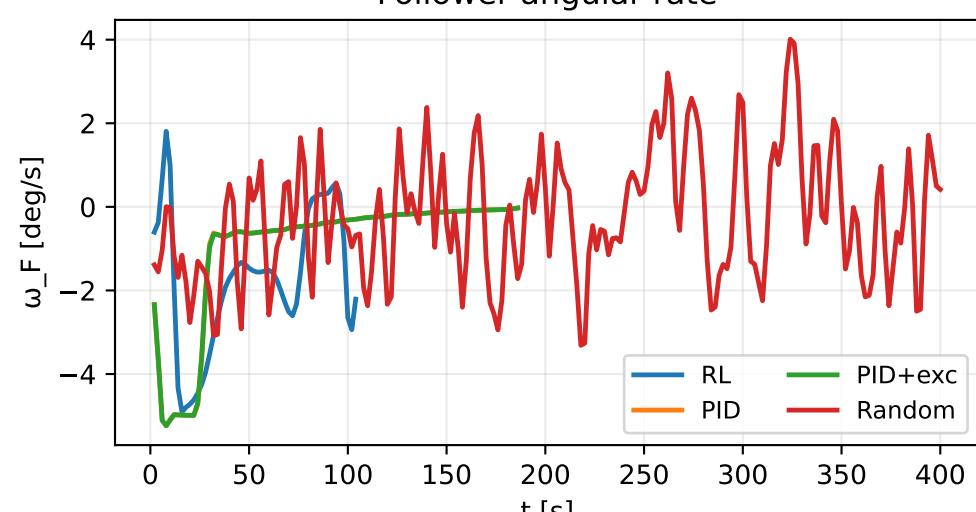
Follower speed



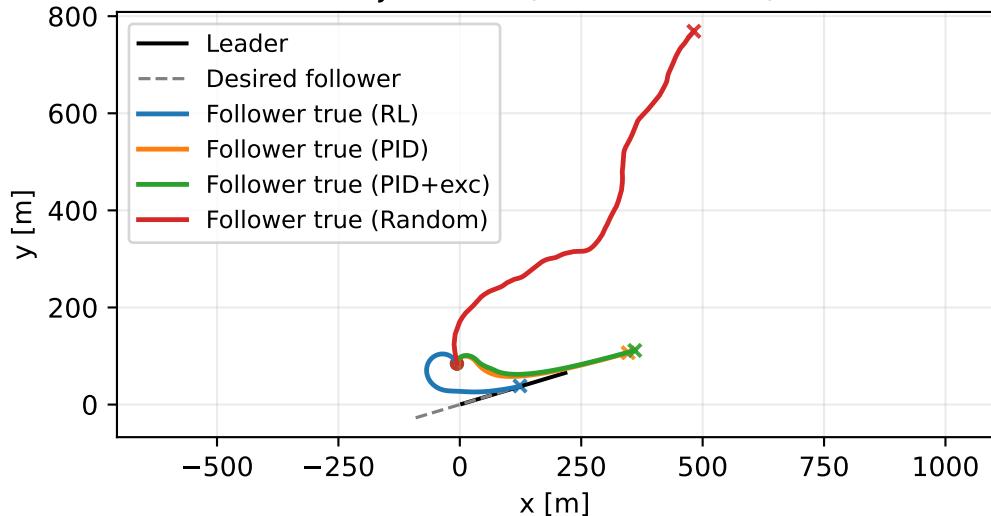
Follower course/heading



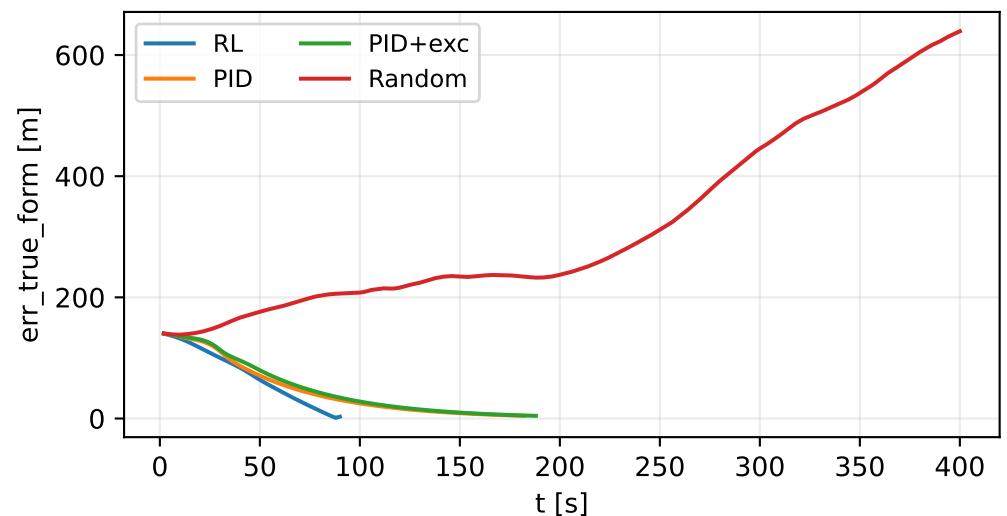
Follower angular rate



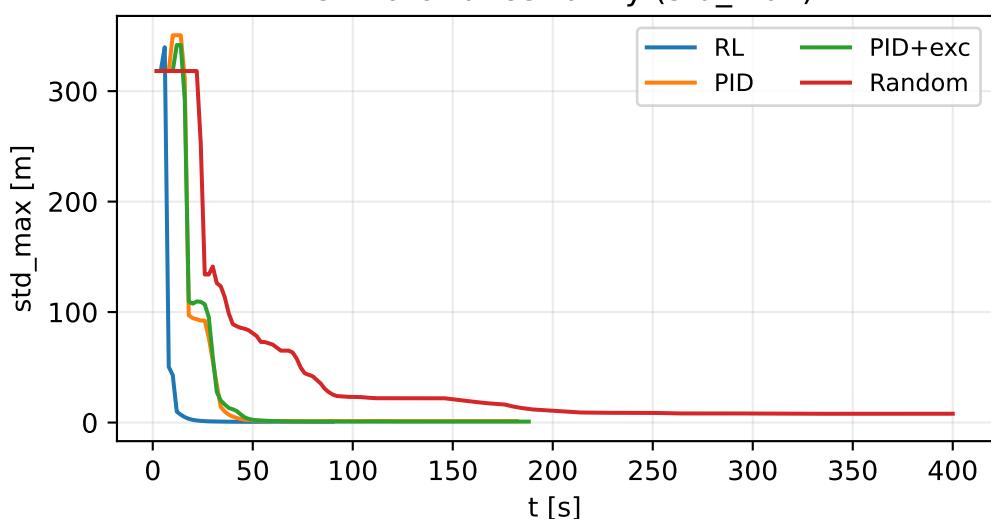
Trajectories (matched seed)



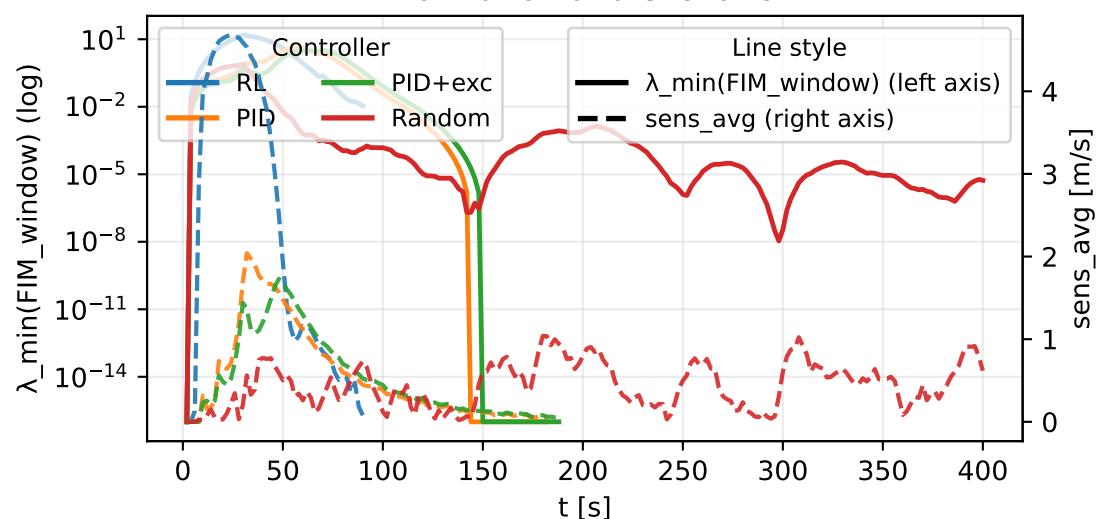
TRUE formation error



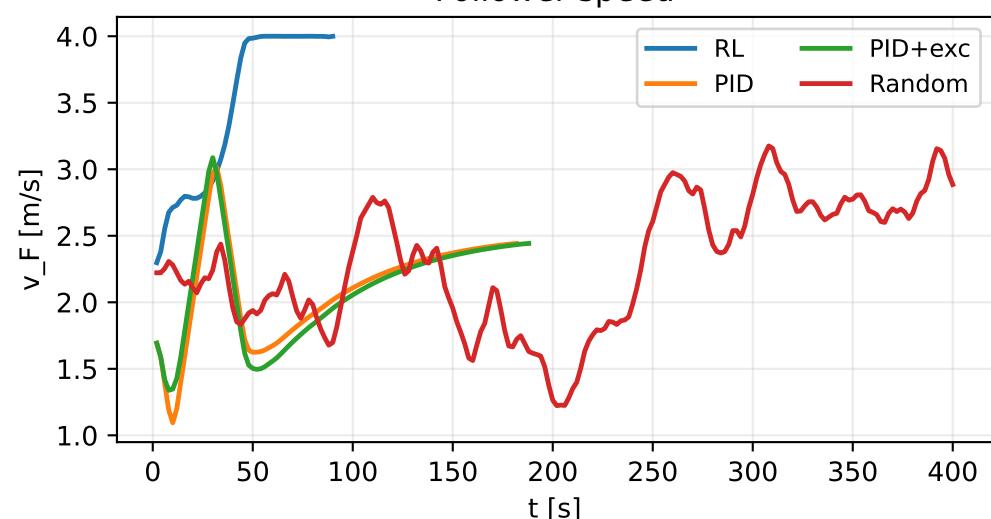
Estimator uncertainty (std_max)



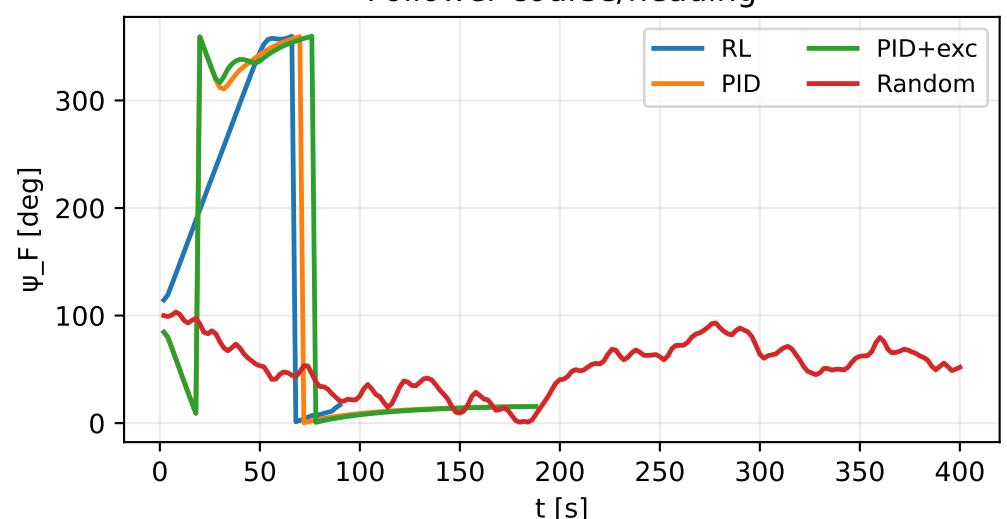
Information and excitation



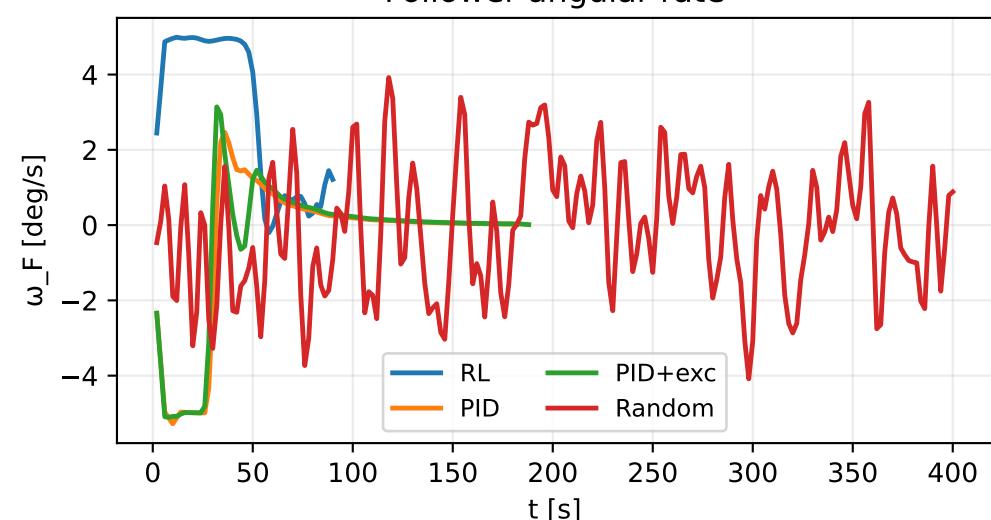
Follower speed



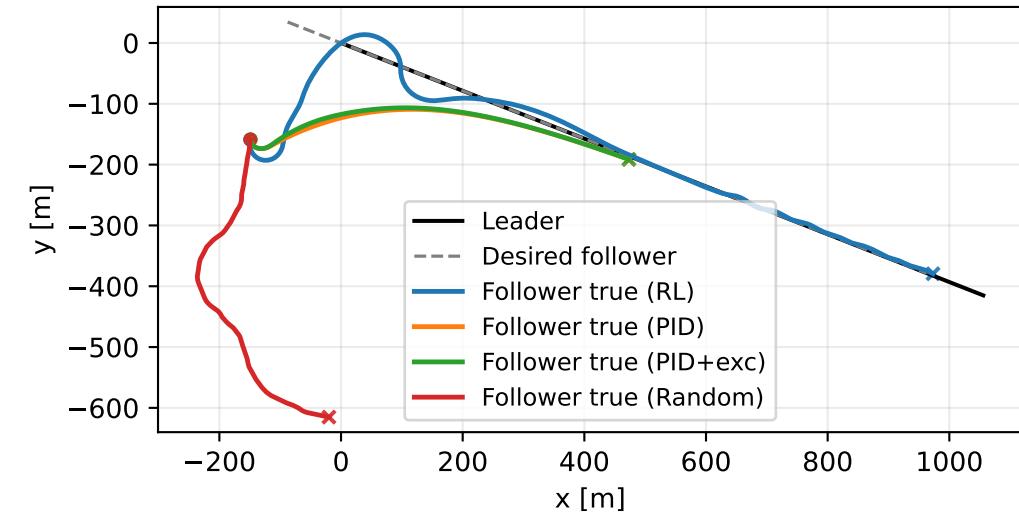
Follower course/heading



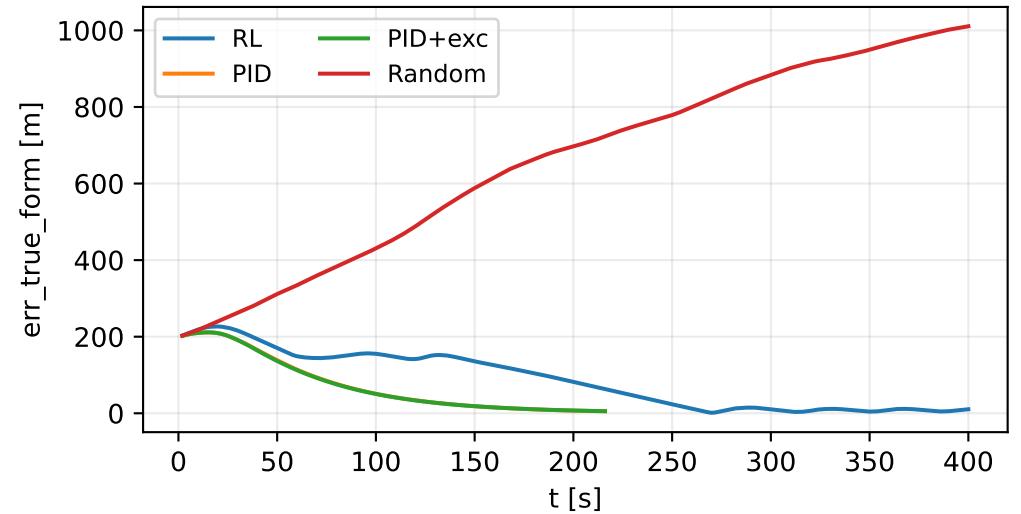
Follower angular rate



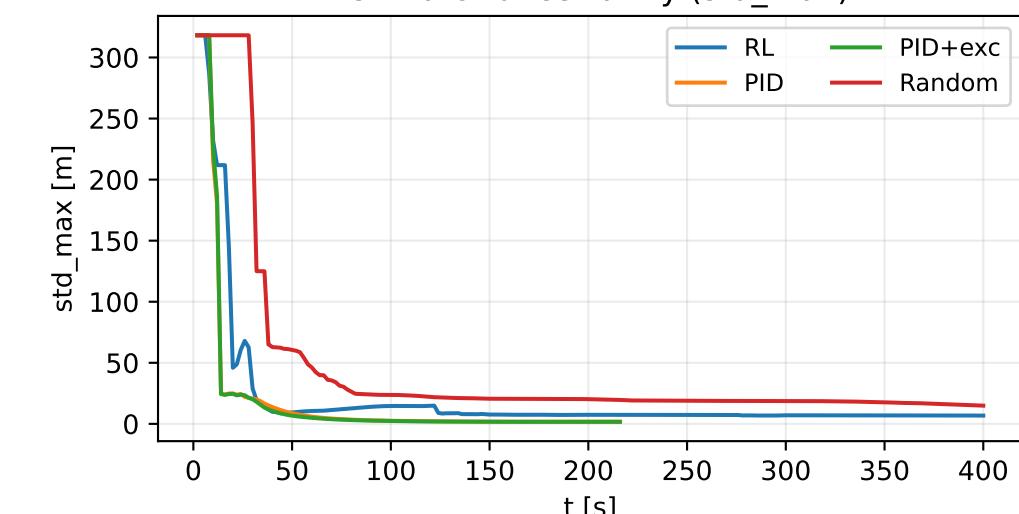
Trajectories (matched seed)



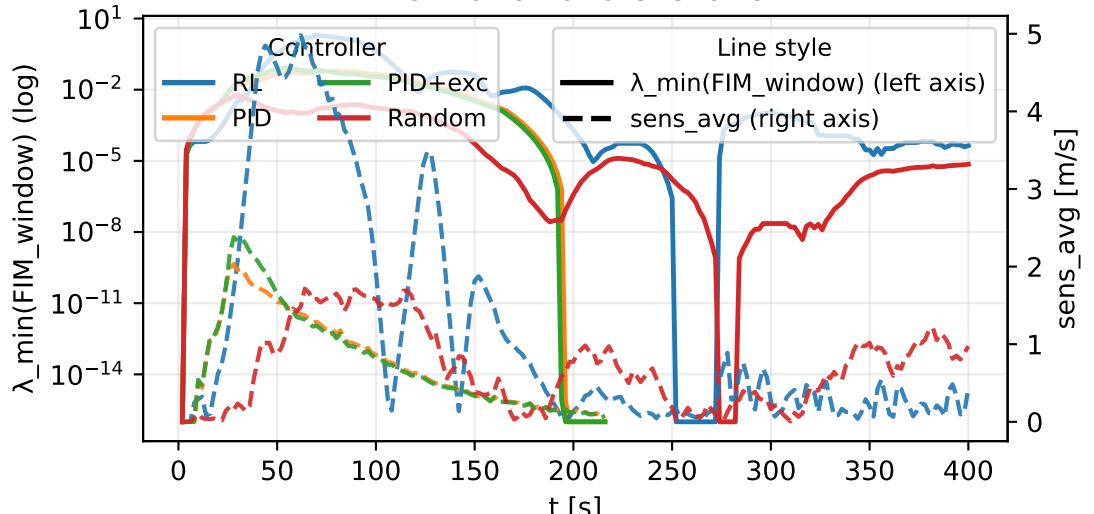
TRUE formation error



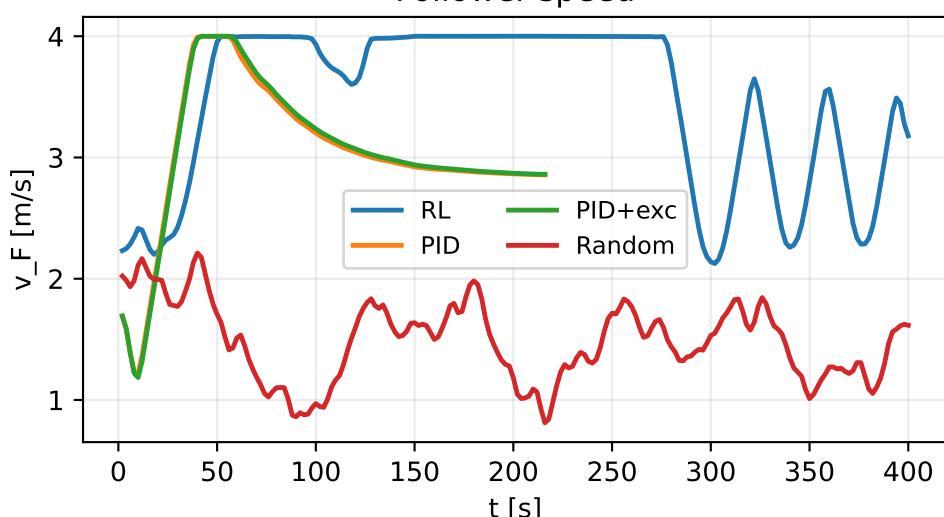
Estimator uncertainty (std_max)



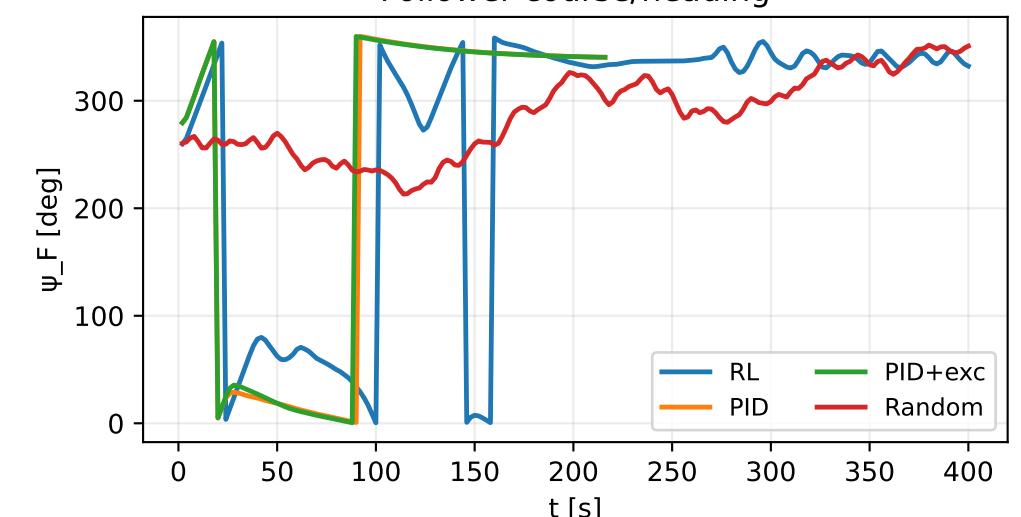
Information and excitation



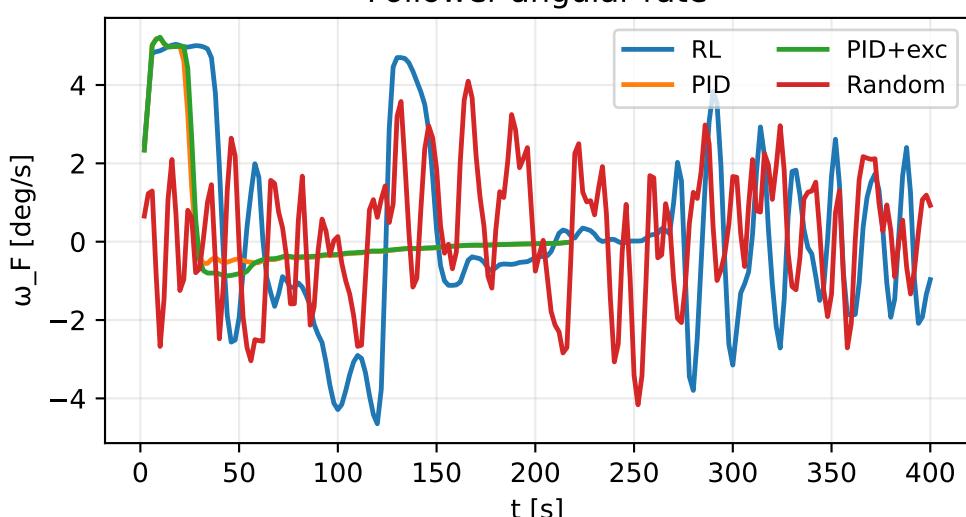
Follower speed



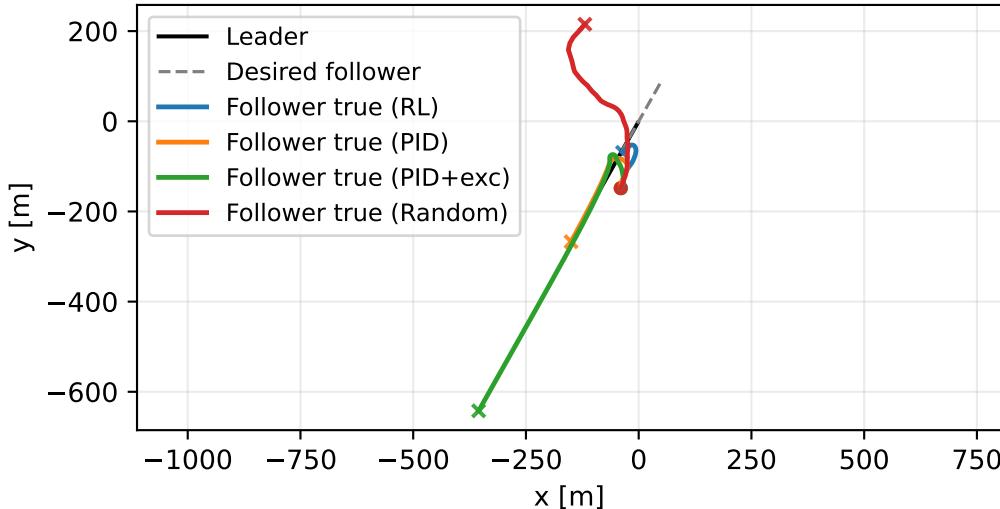
Follower course/heading



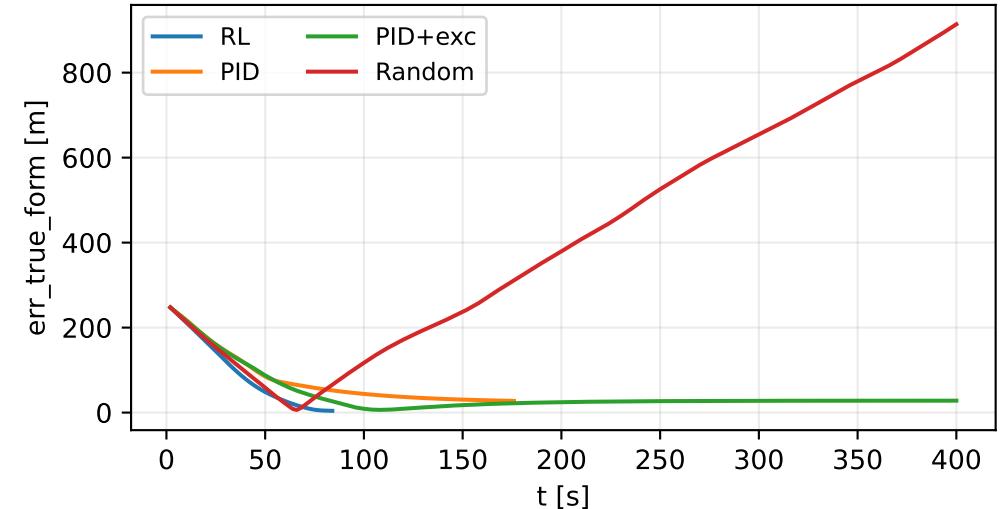
Follower angular rate



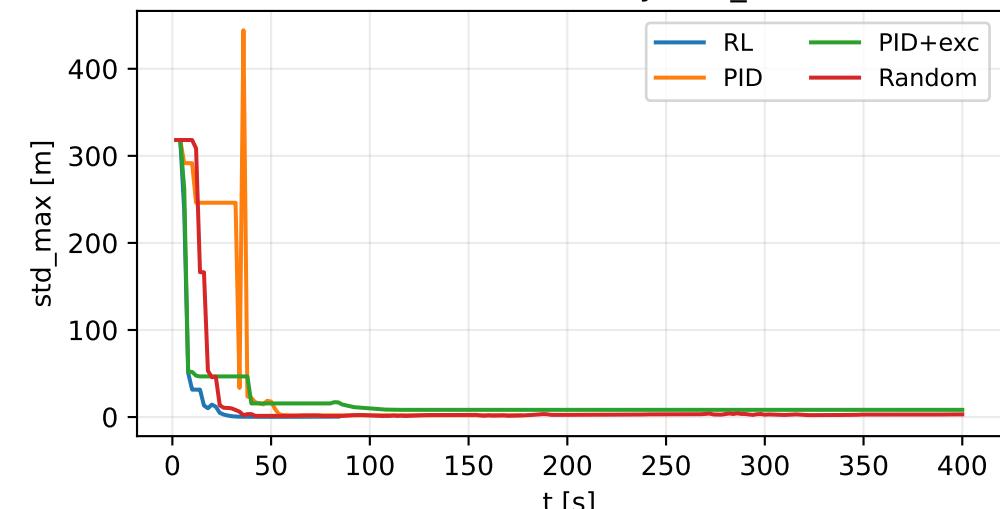
Trajectories (matched seed)



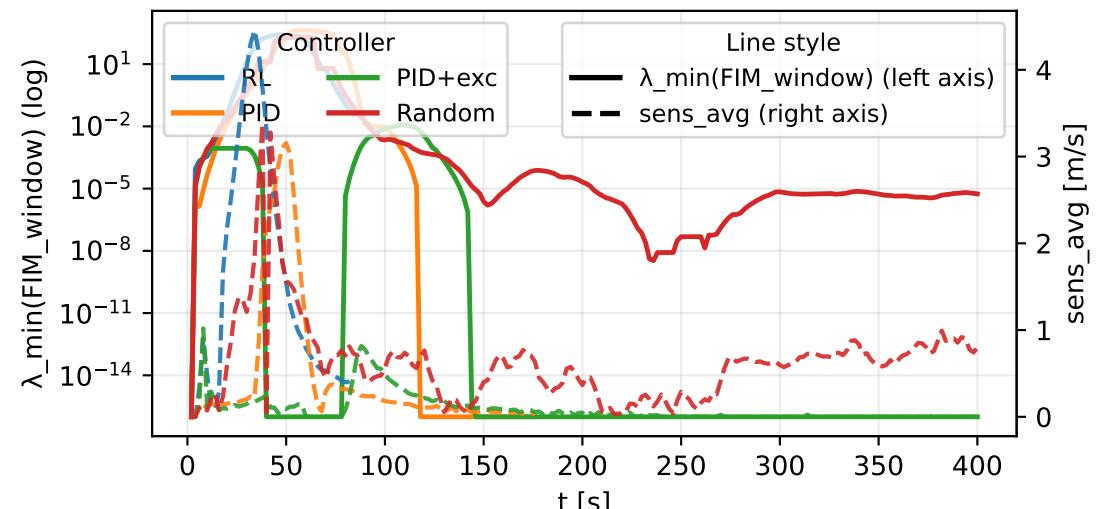
TRUE formation error



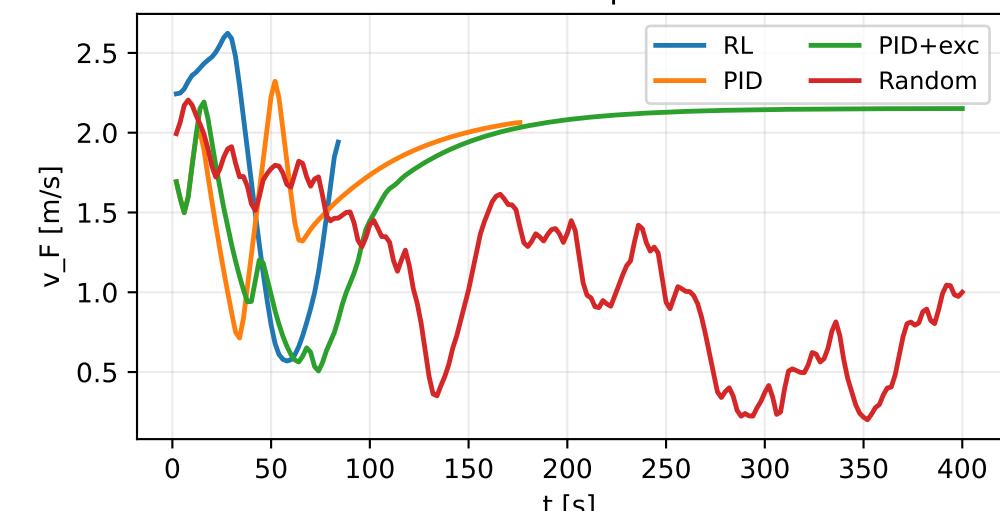
Estimator uncertainty (std_max)



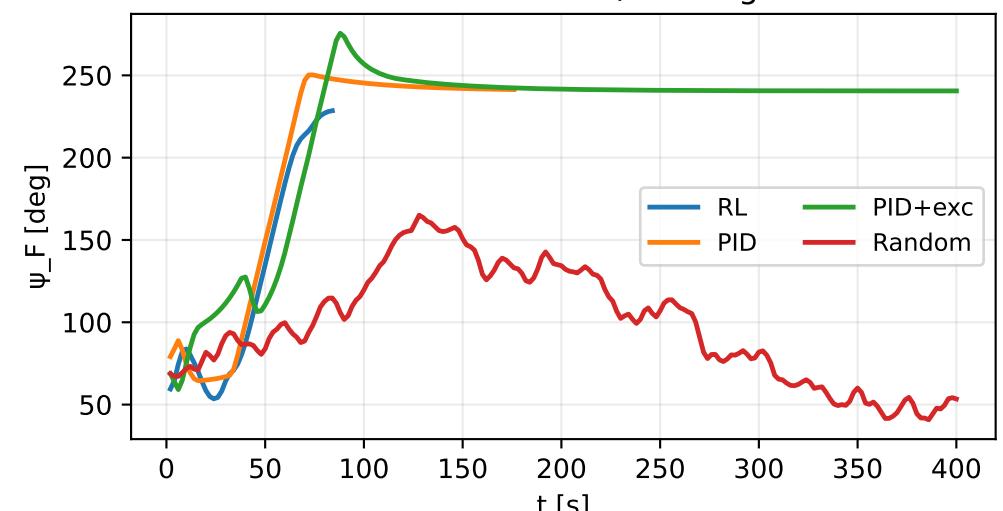
Information and excitation



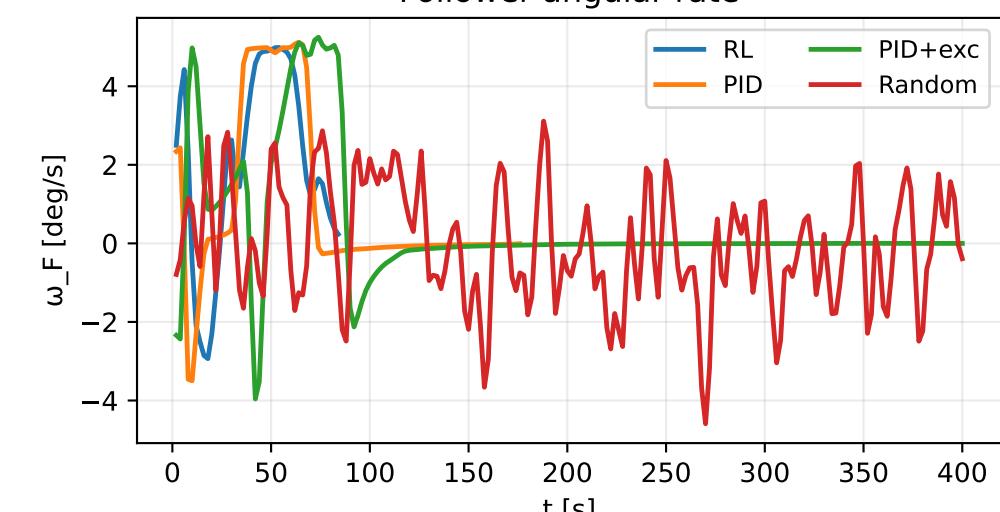
Follower speed



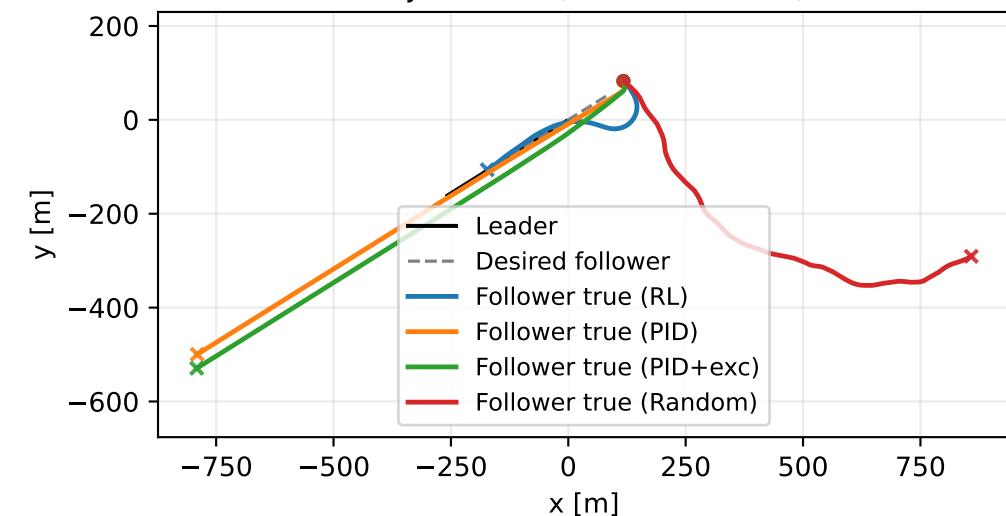
Follower course/heading



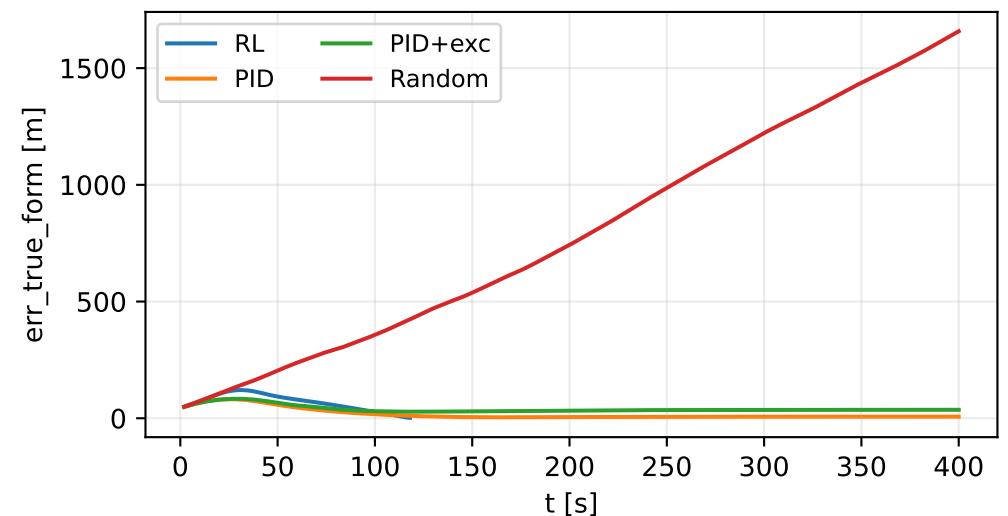
Follower angular rate



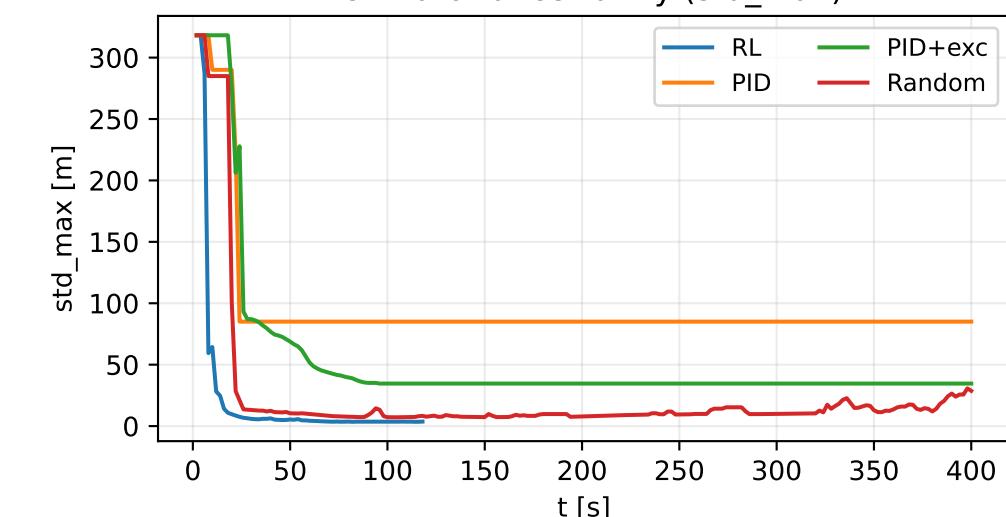
Trajectories (matched seed)



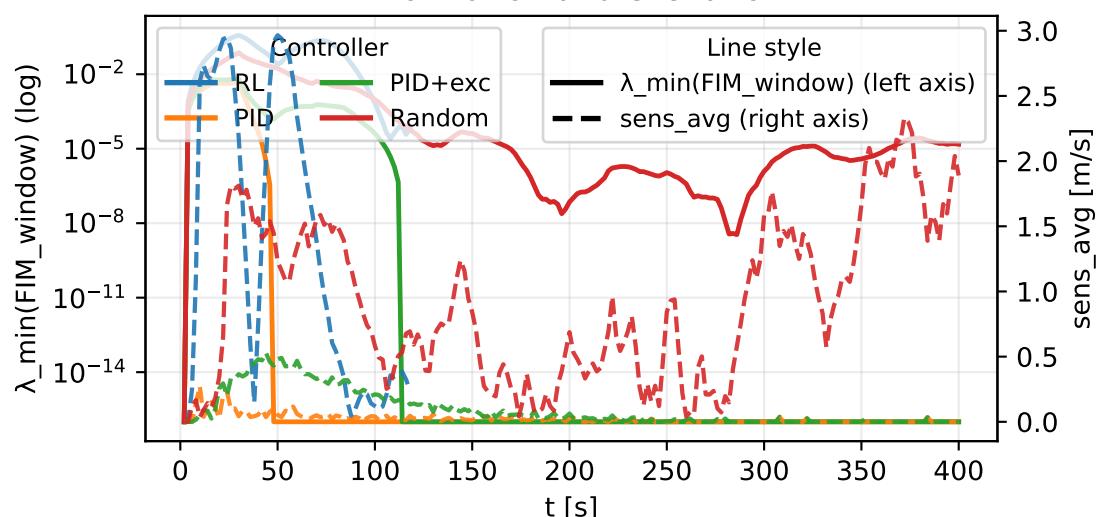
TRUE formation error



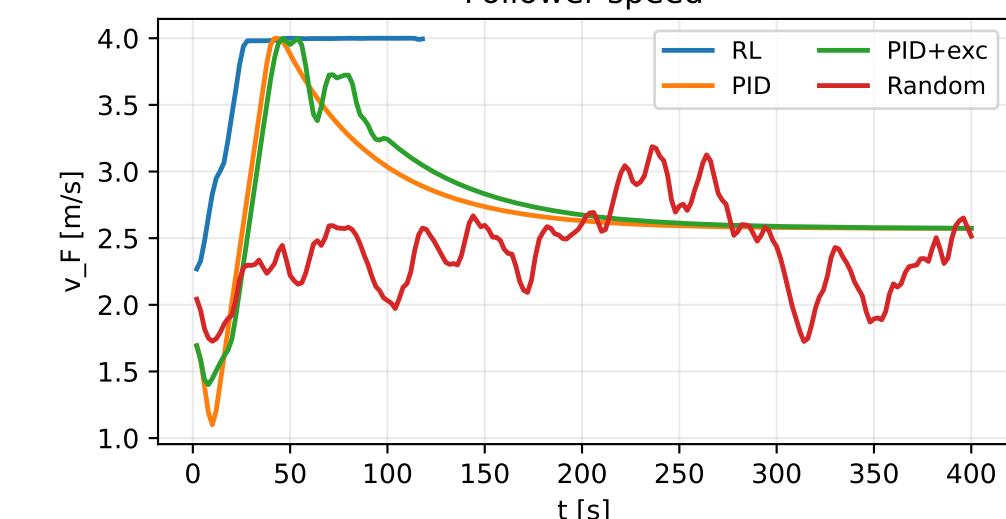
Estimator uncertainty (std_max)



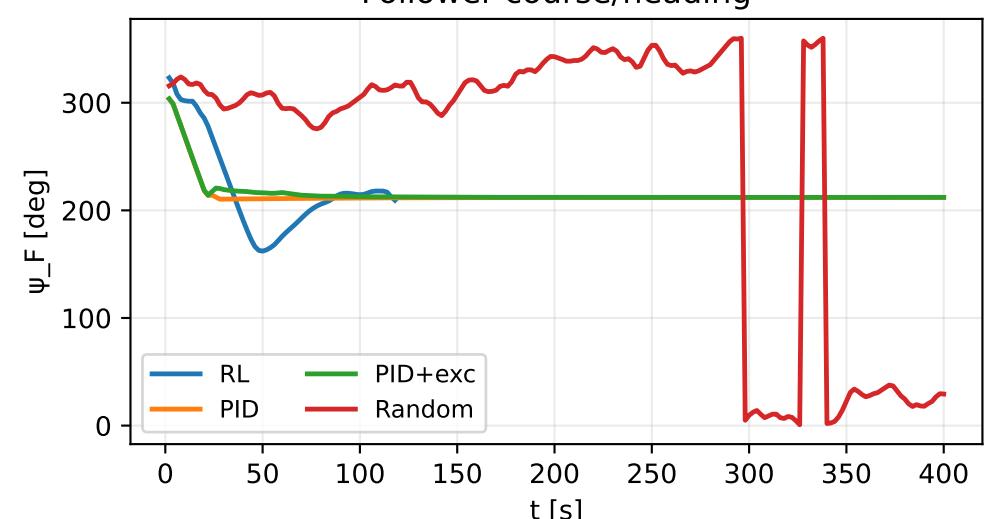
Information and excitation



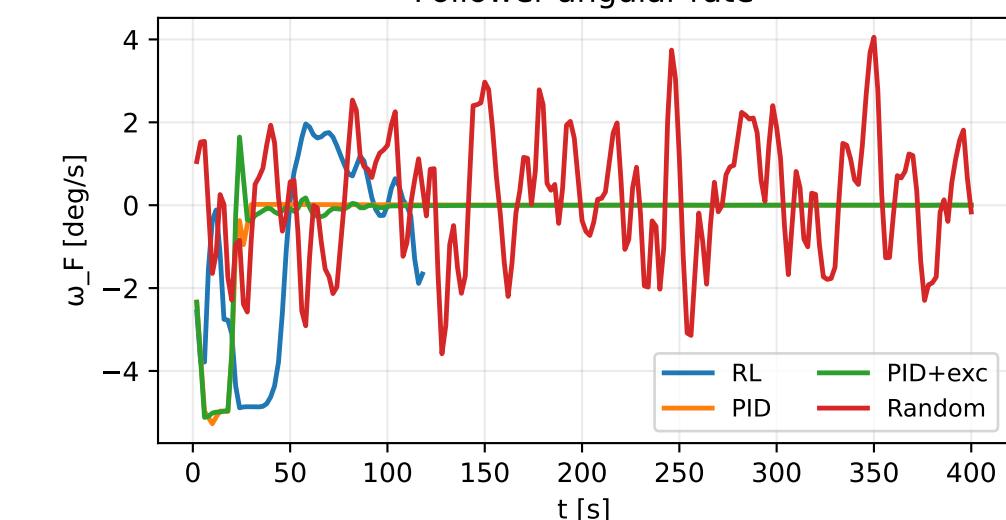
Follower speed



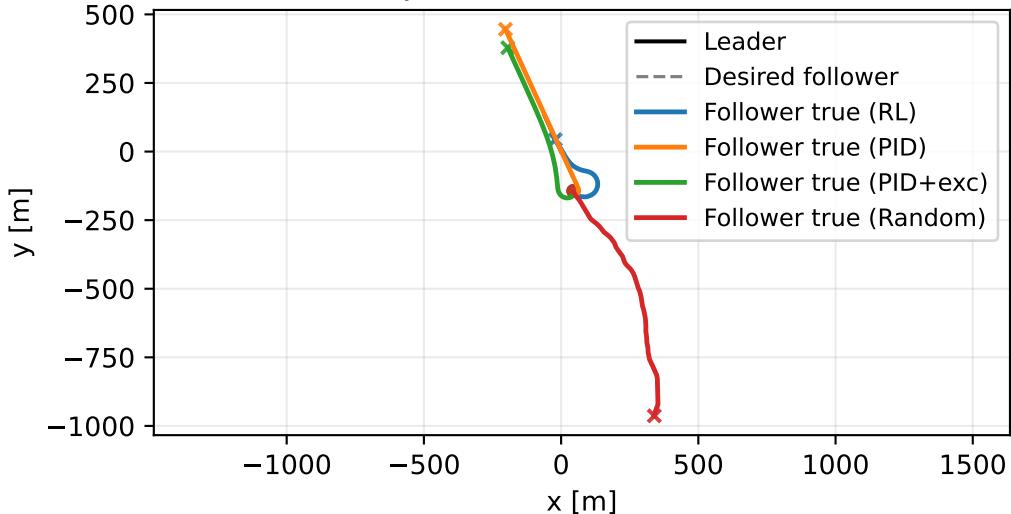
Follower course/heading



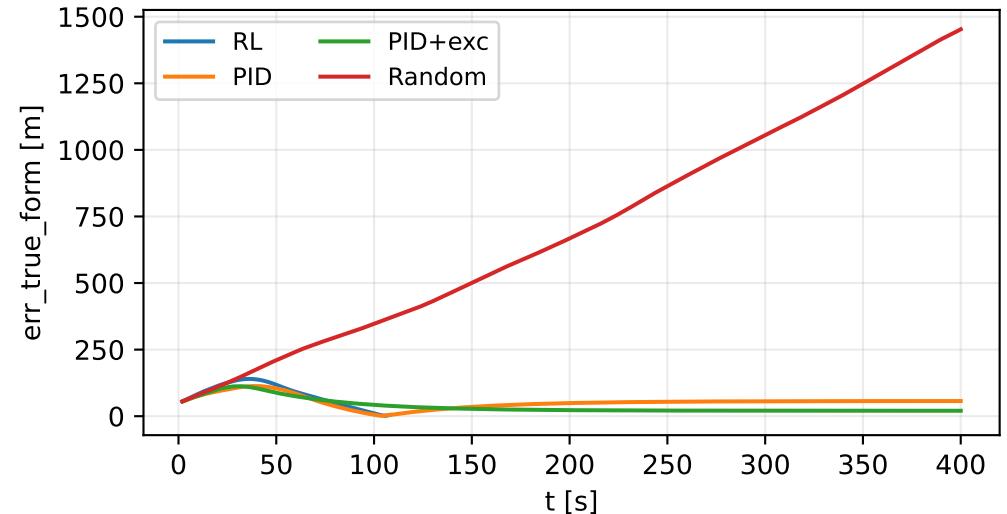
Follower angular rate



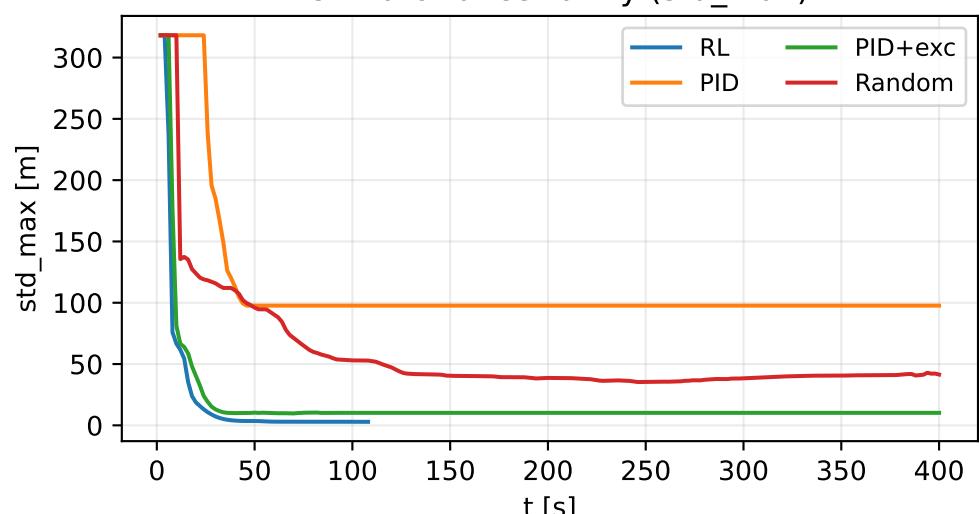
Trajectories (matched seed)



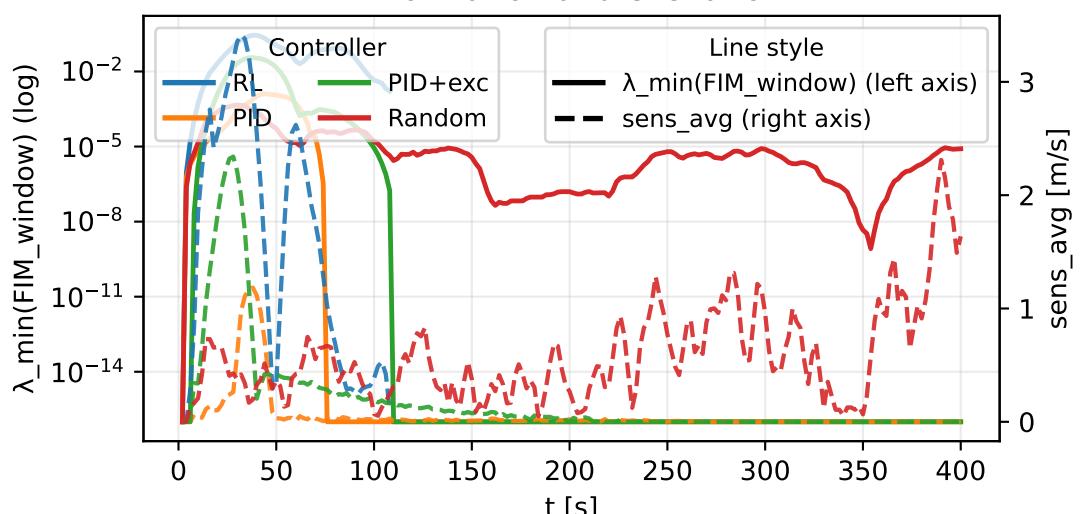
TRUE formation error



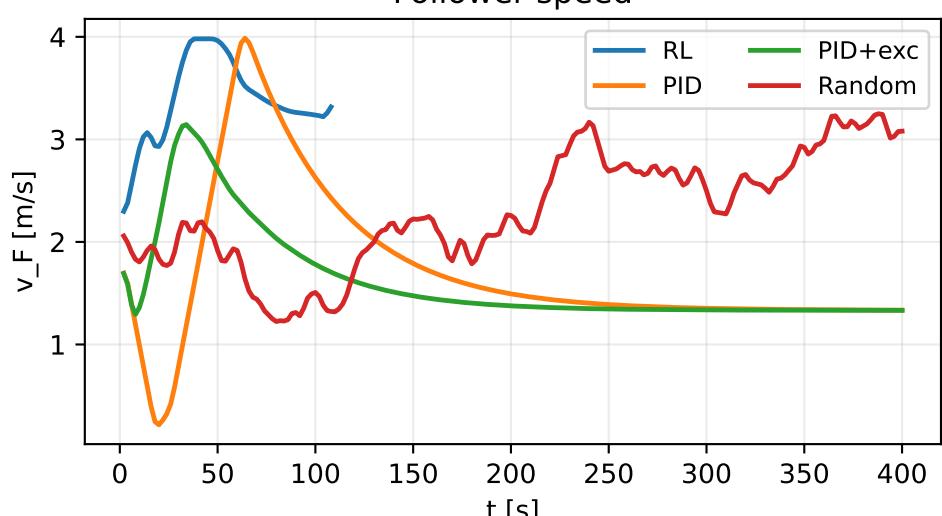
Estimator uncertainty (std_max)



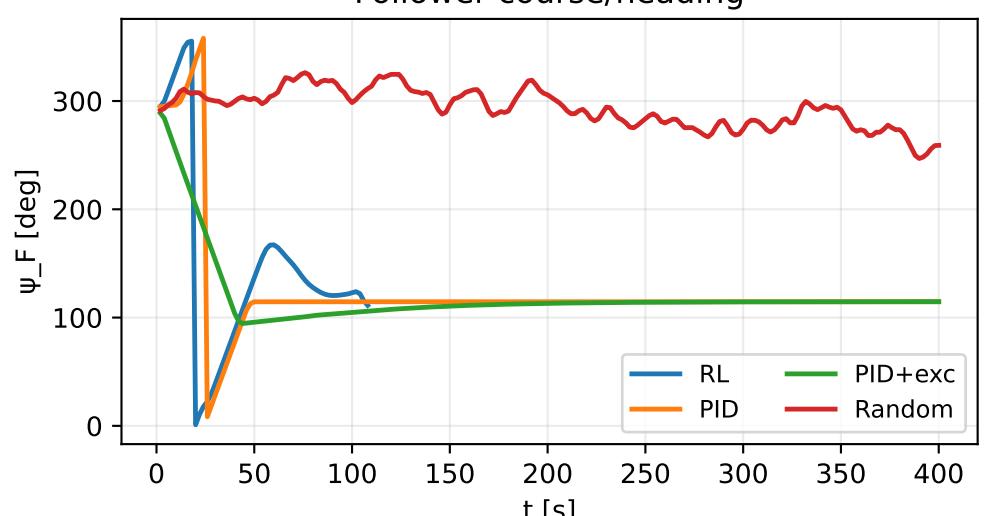
Information and excitation



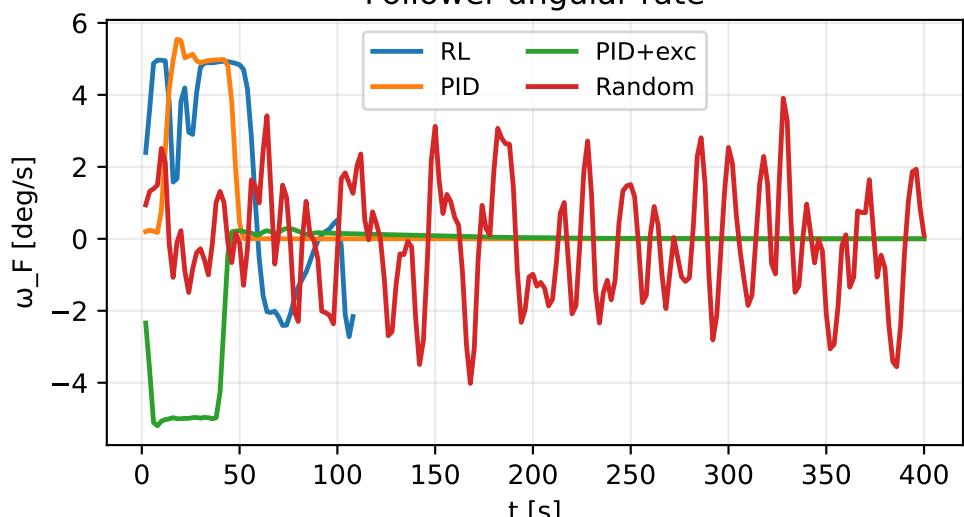
Follower speed



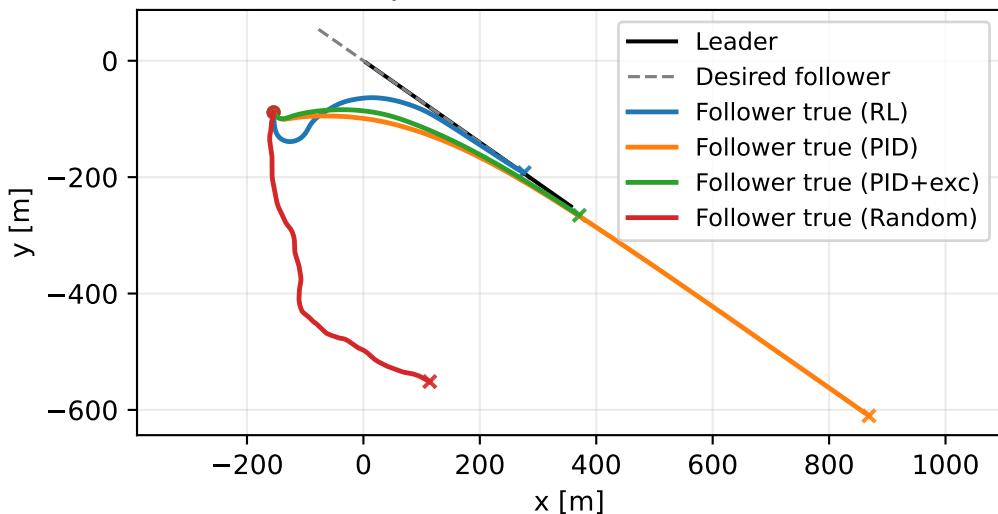
Follower course/heading



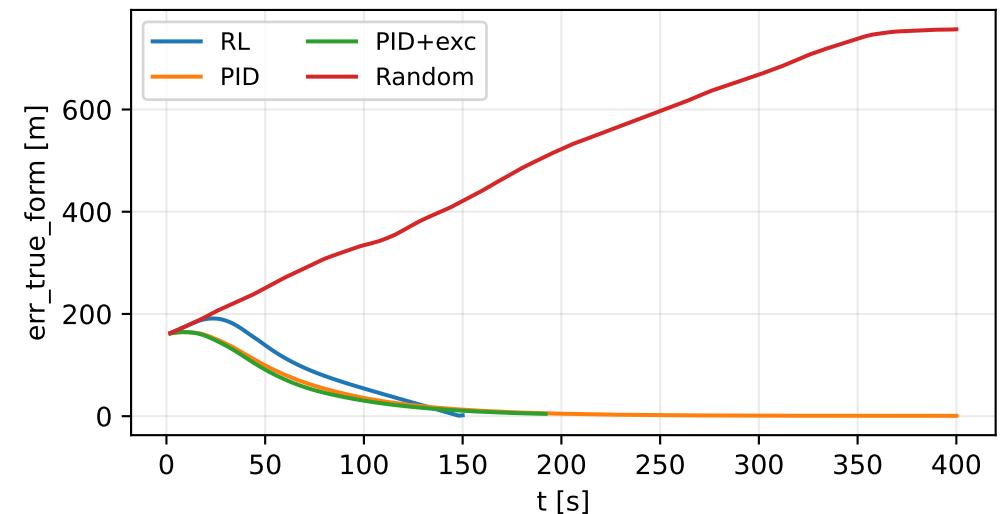
Follower angular rate



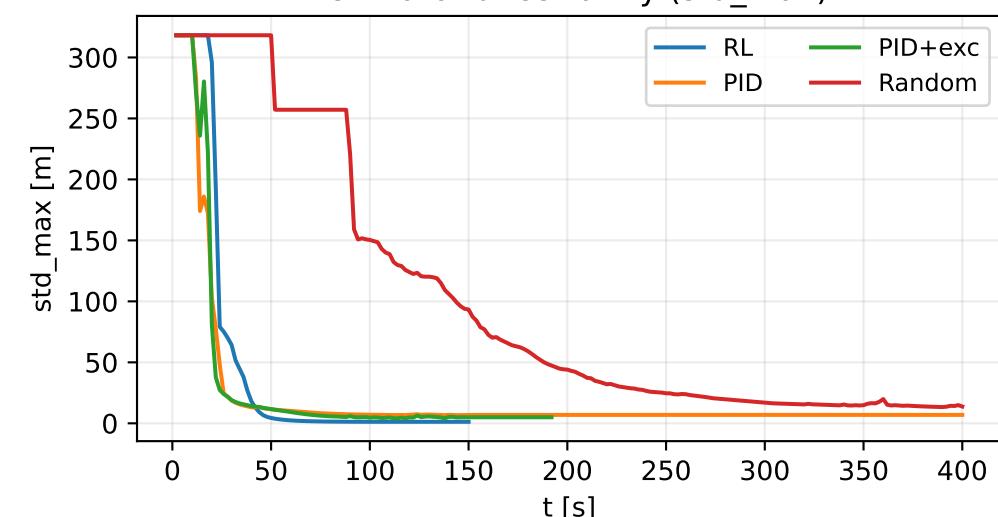
Trajectories (matched seed)



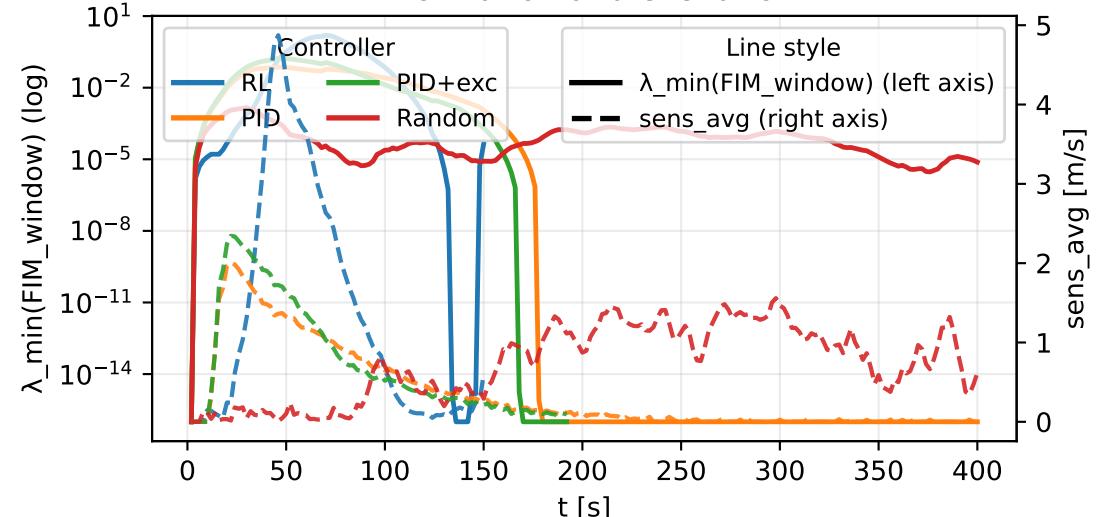
TRUE formation error



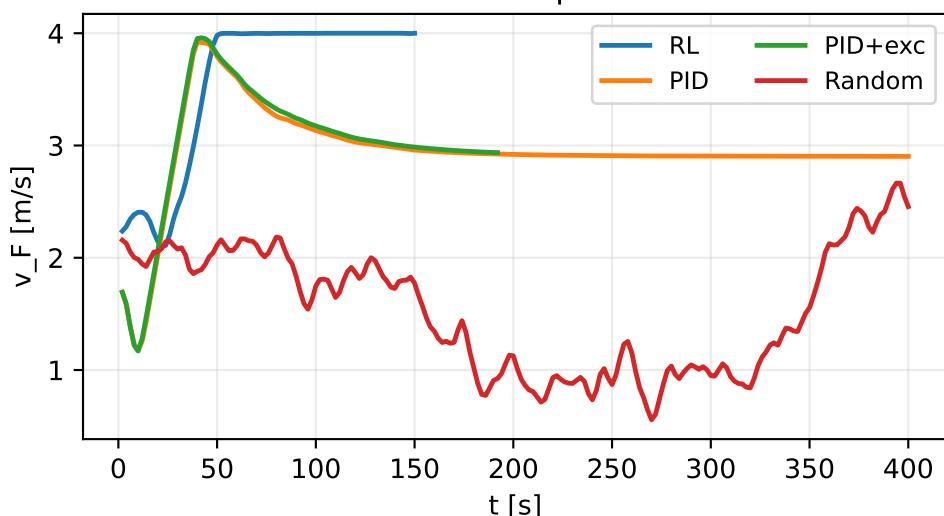
Estimator uncertainty (std_max)



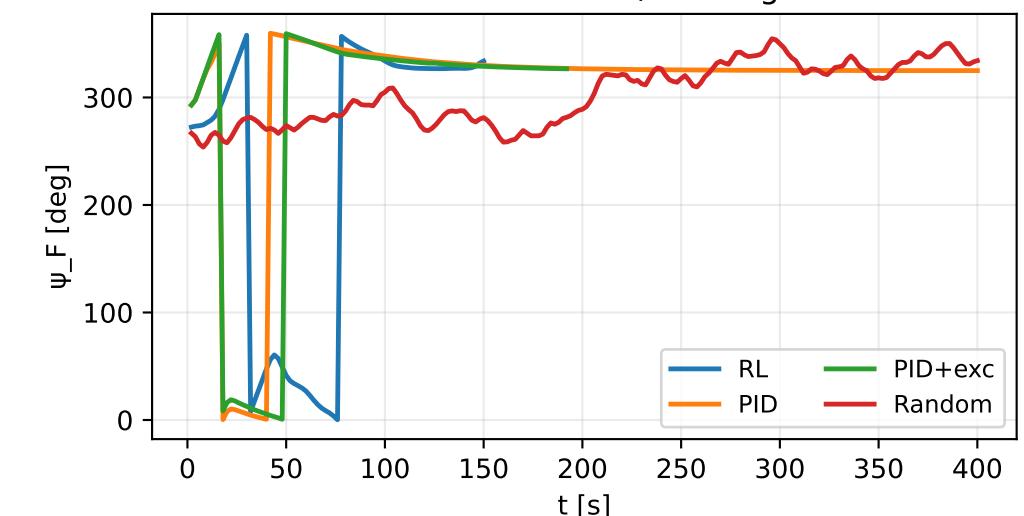
Information and excitation



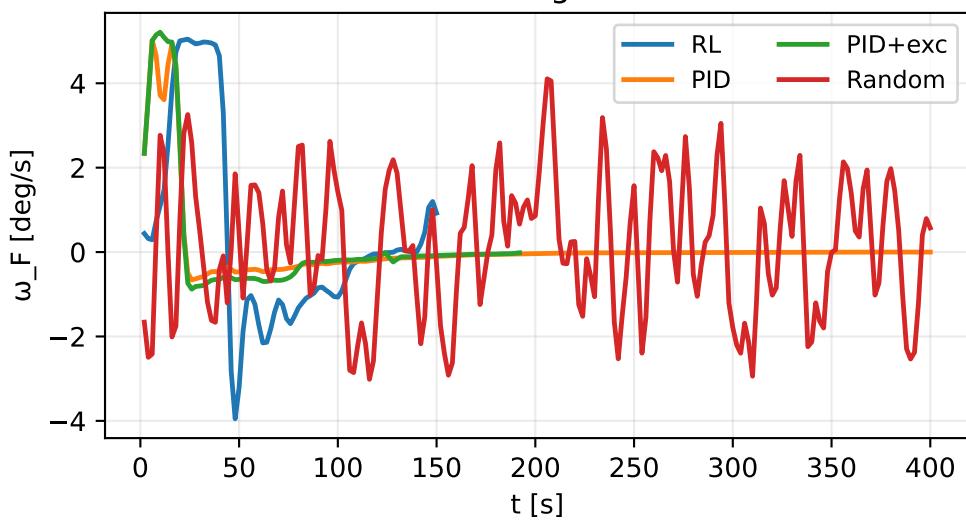
Follower speed



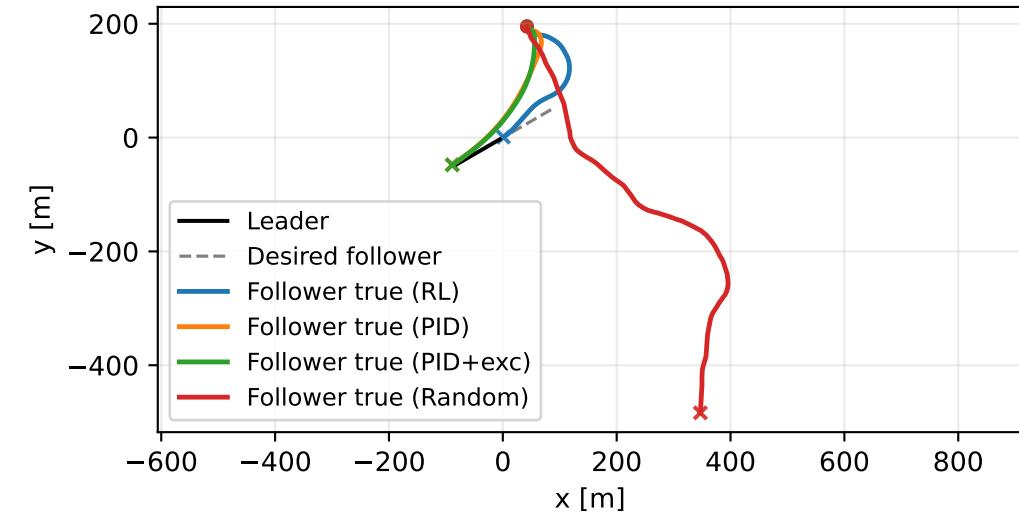
Follower course/heading



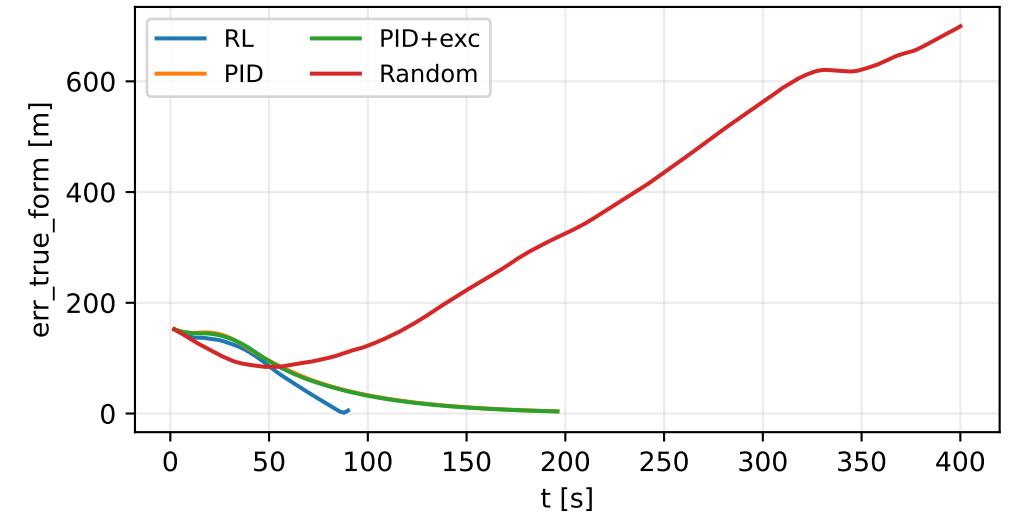
Follower angular rate



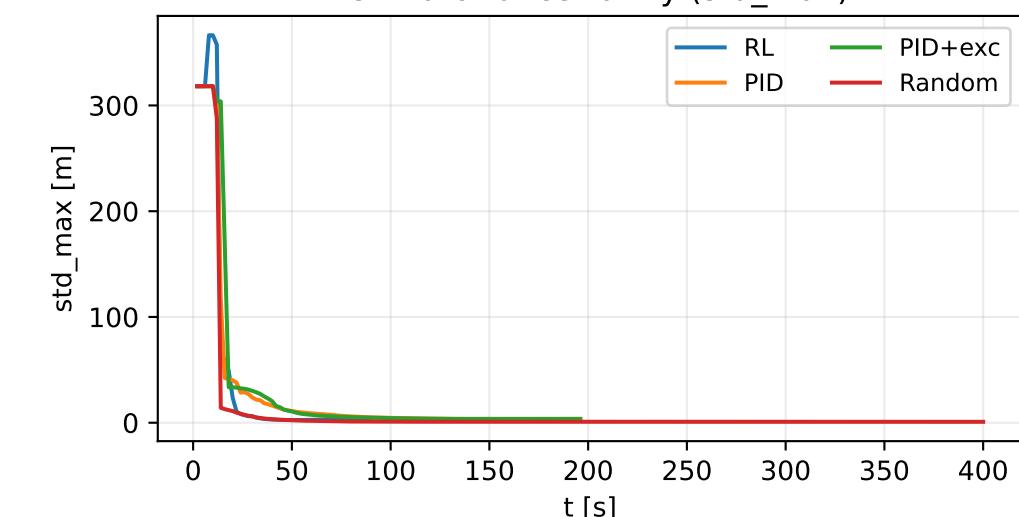
Trajectories (matched seed)



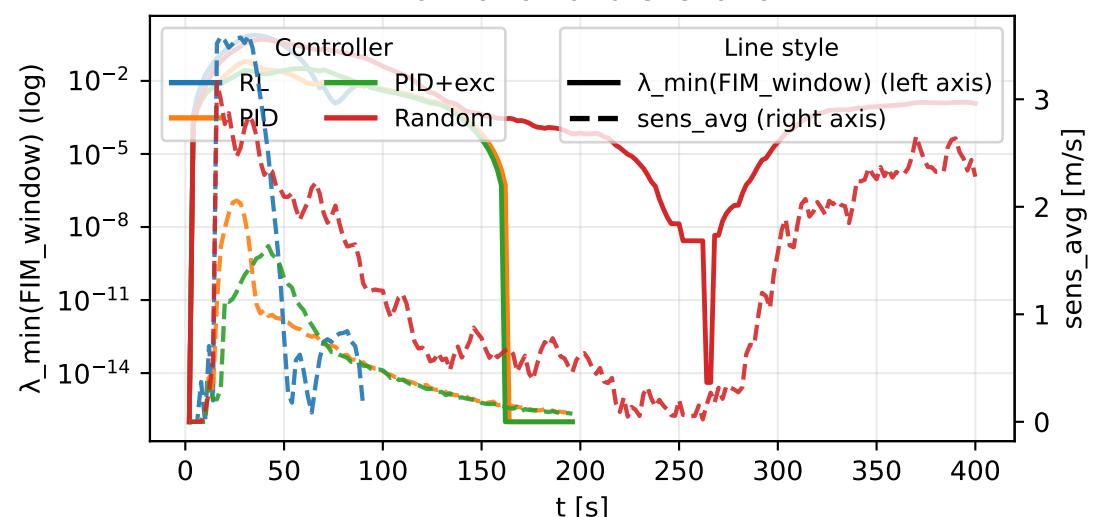
TRUE formation error



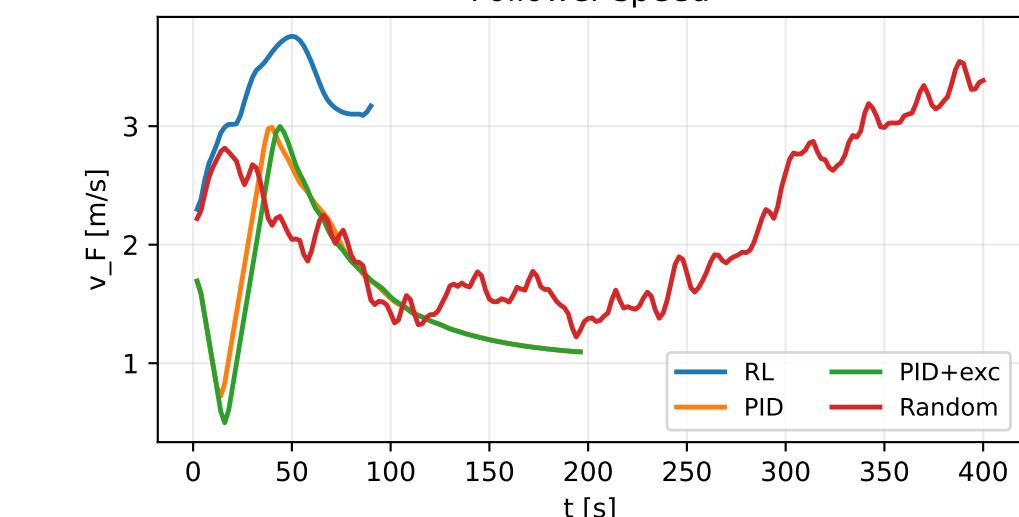
Estimator uncertainty (std_max)



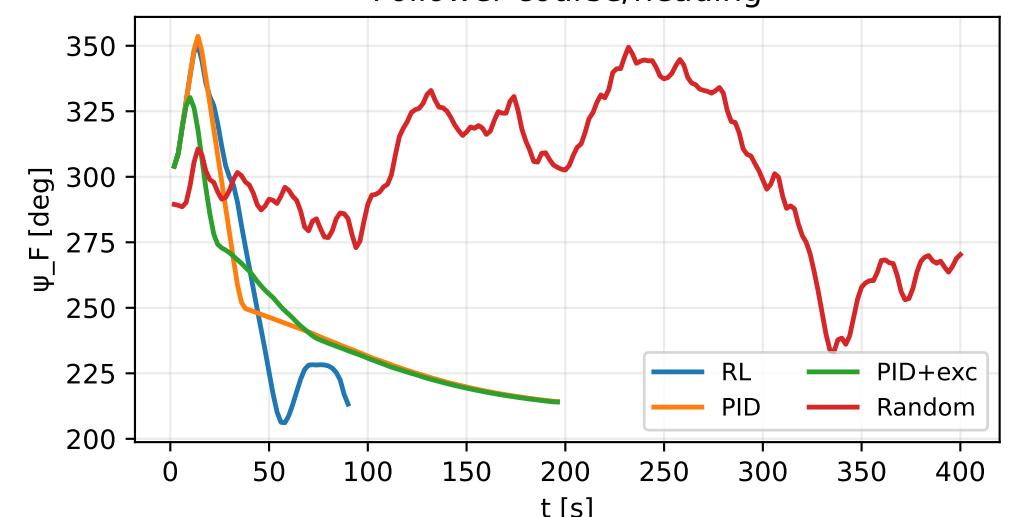
Information and excitation



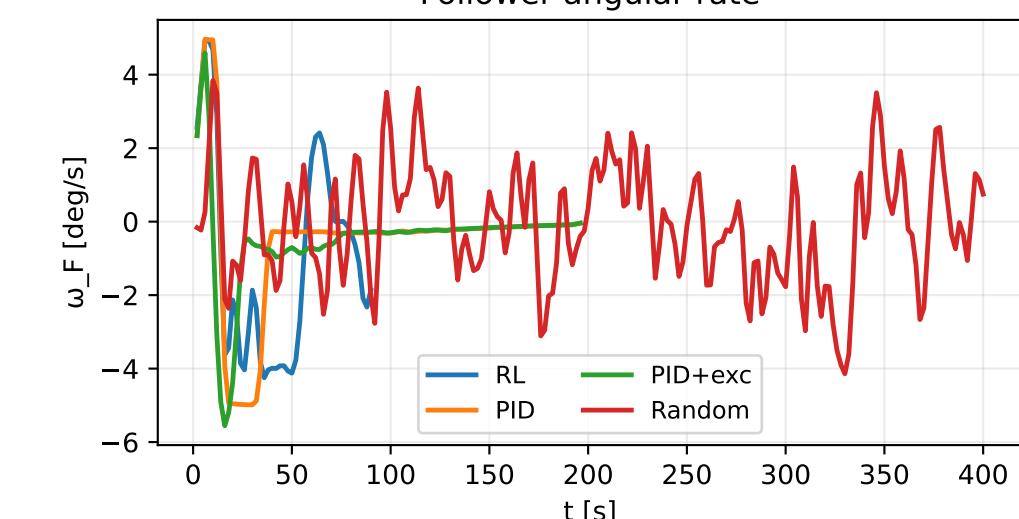
Follower speed



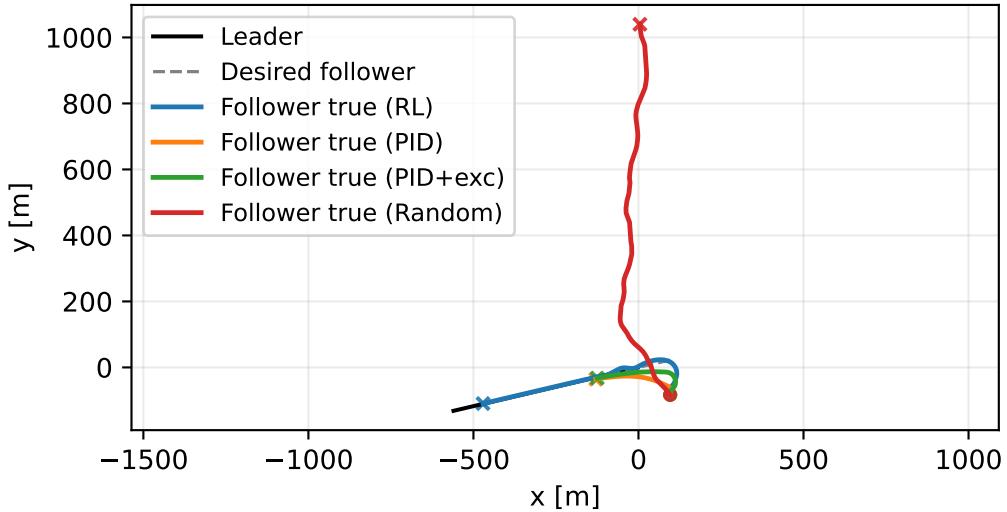
Follower course/heading



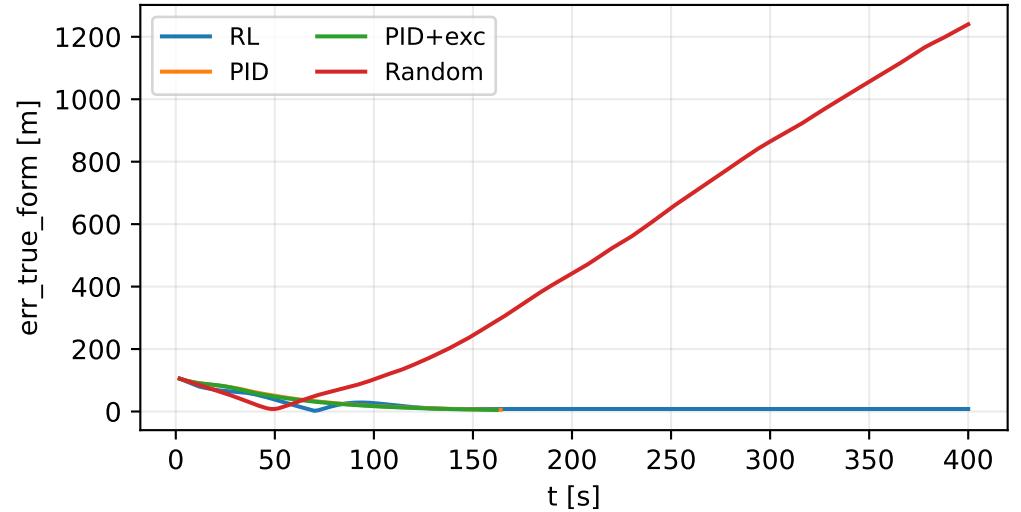
Follower angular rate



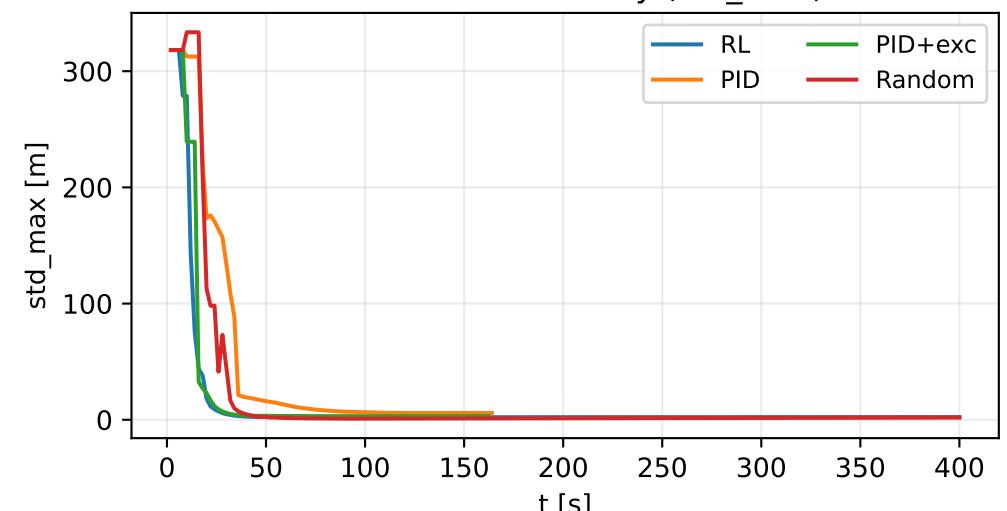
Trajectories (matched seed)



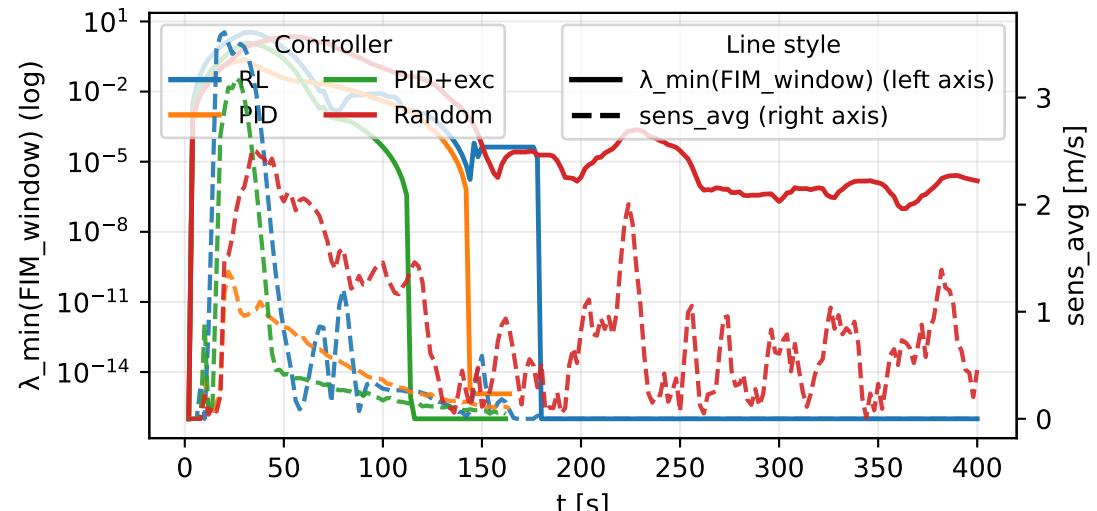
TRUE formation error



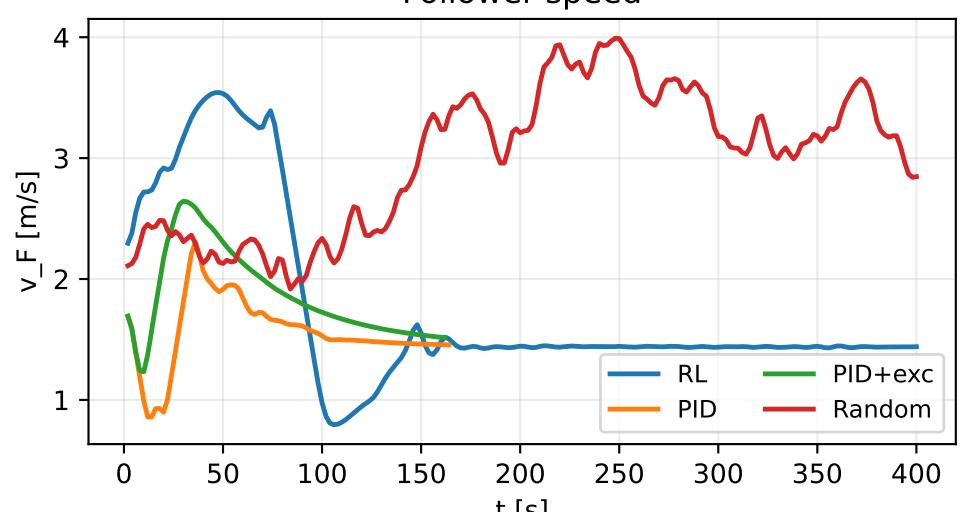
Estimator uncertainty (std_max)



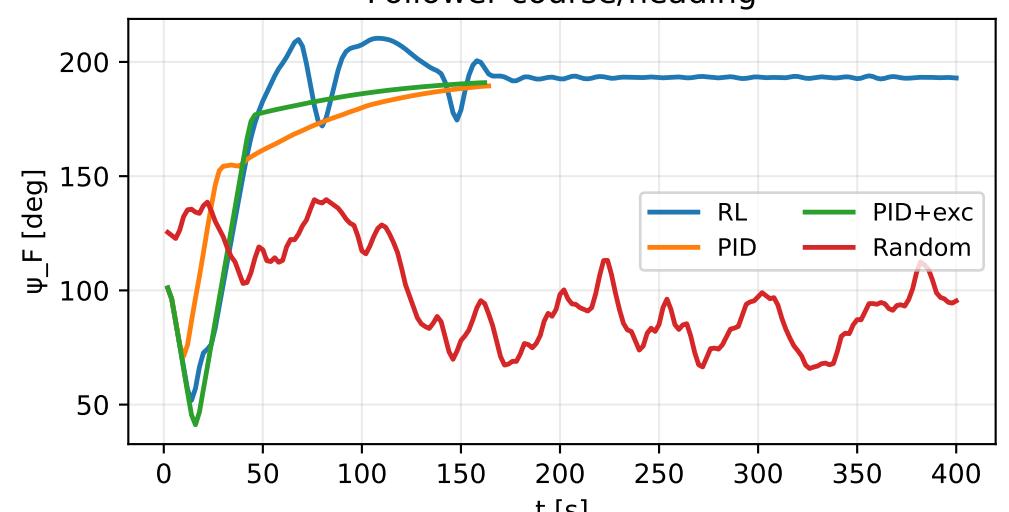
Information and excitation



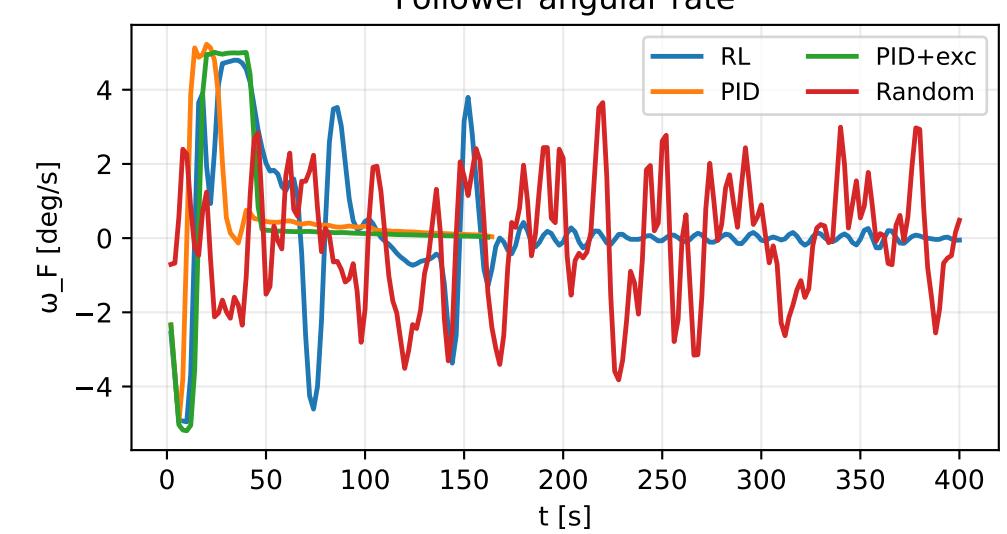
Follower speed



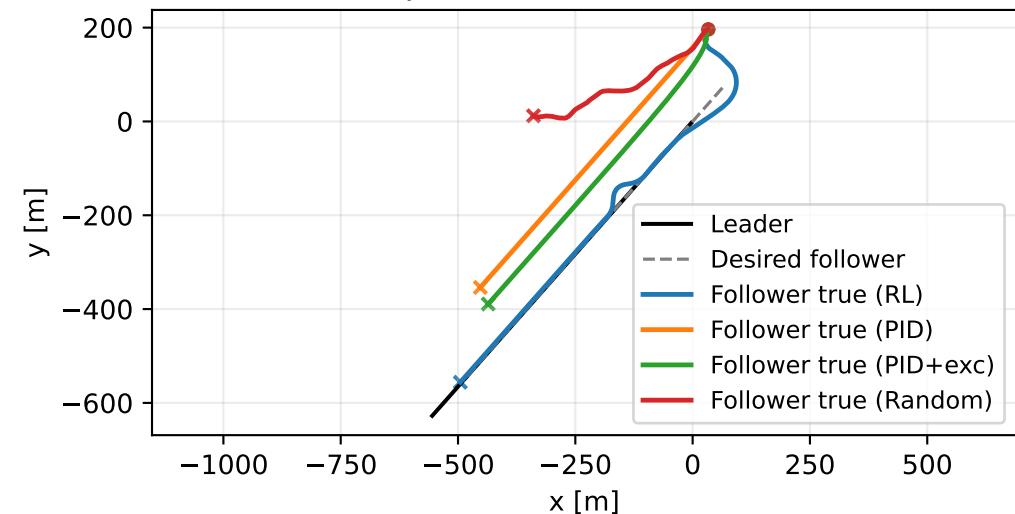
Follower course/heading



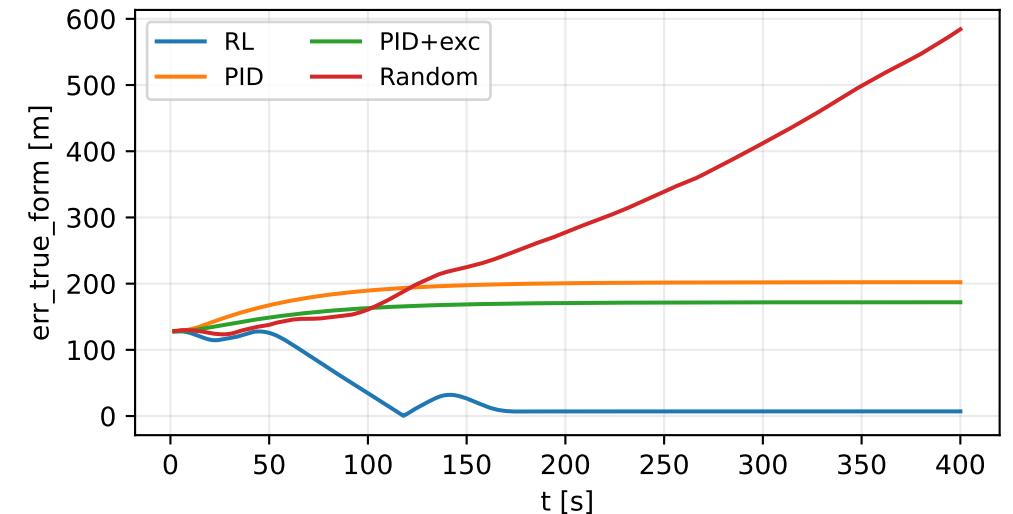
Follower angular rate



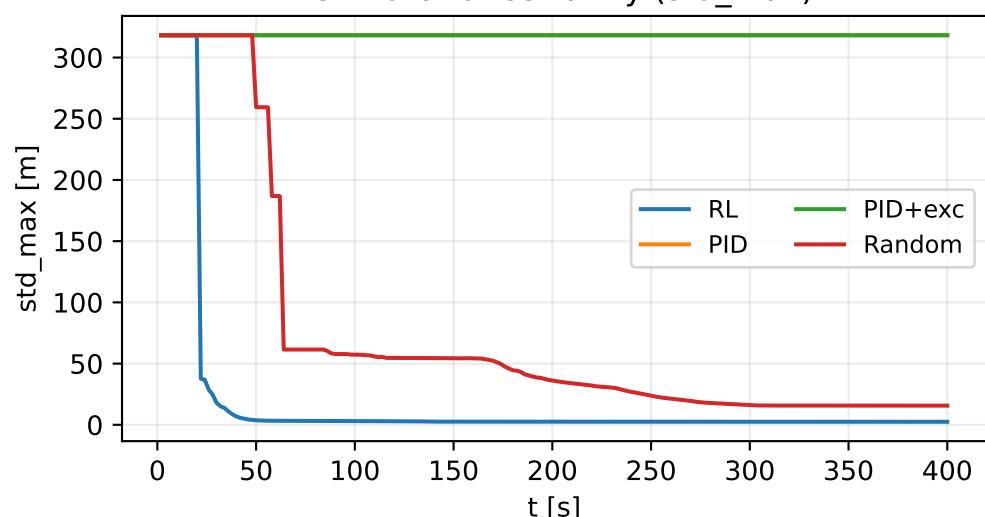
Trajectories (matched seed)



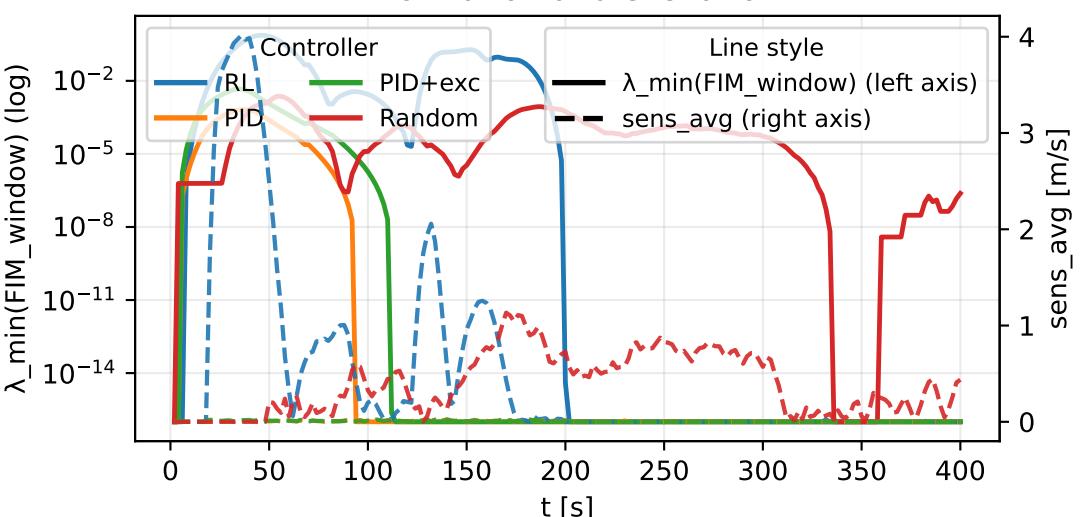
TRUE formation error



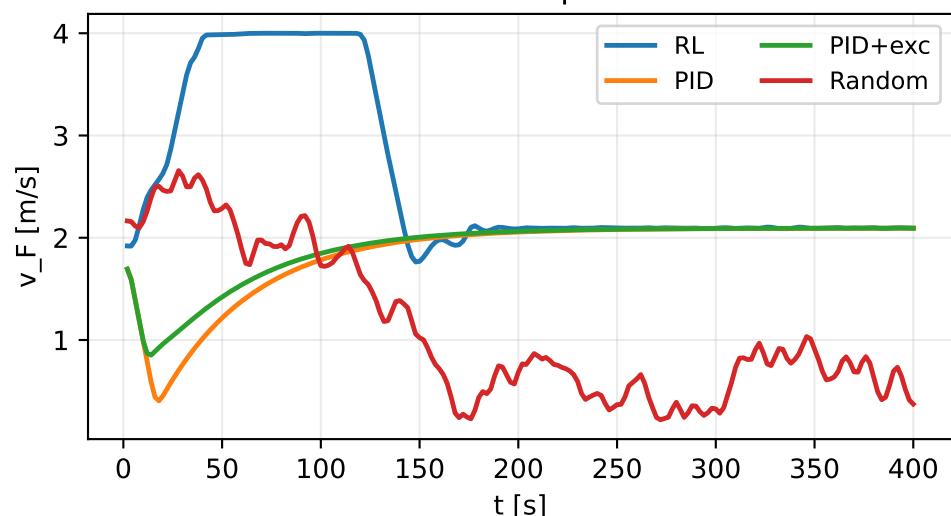
Estimator uncertainty (std_max)



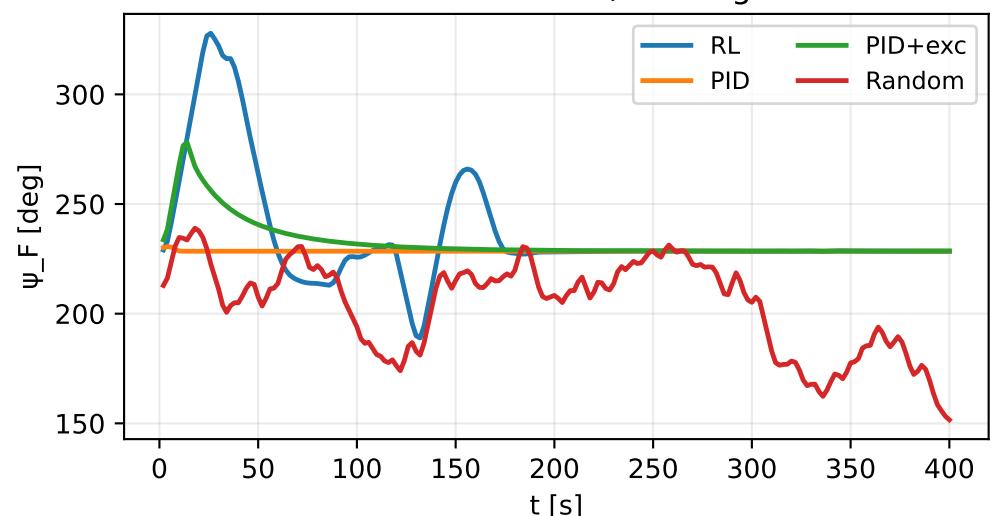
Information and excitation



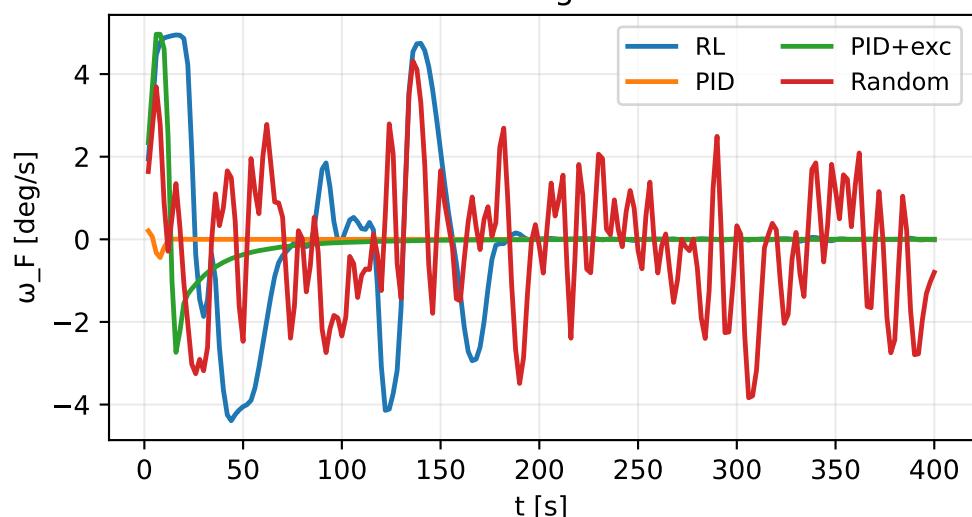
Follower speed



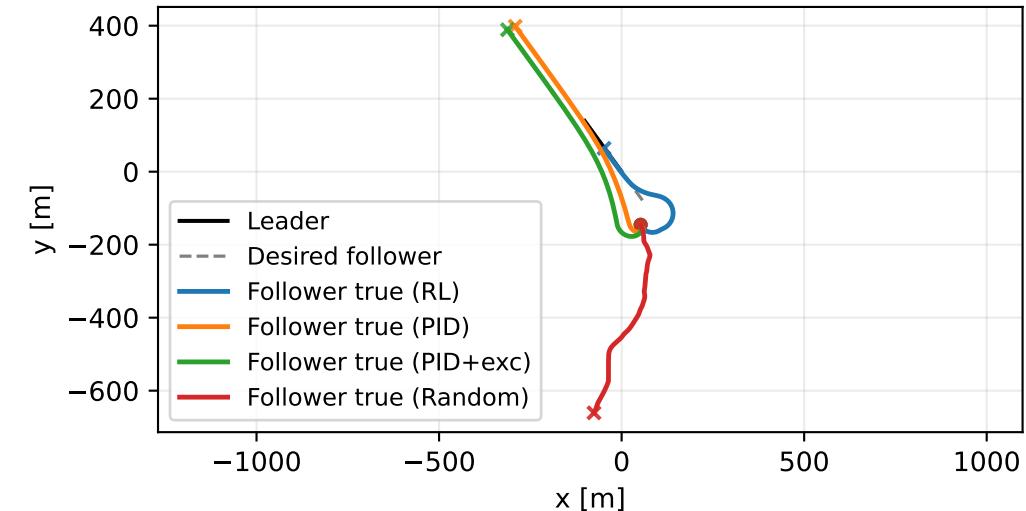
Follower course/heading



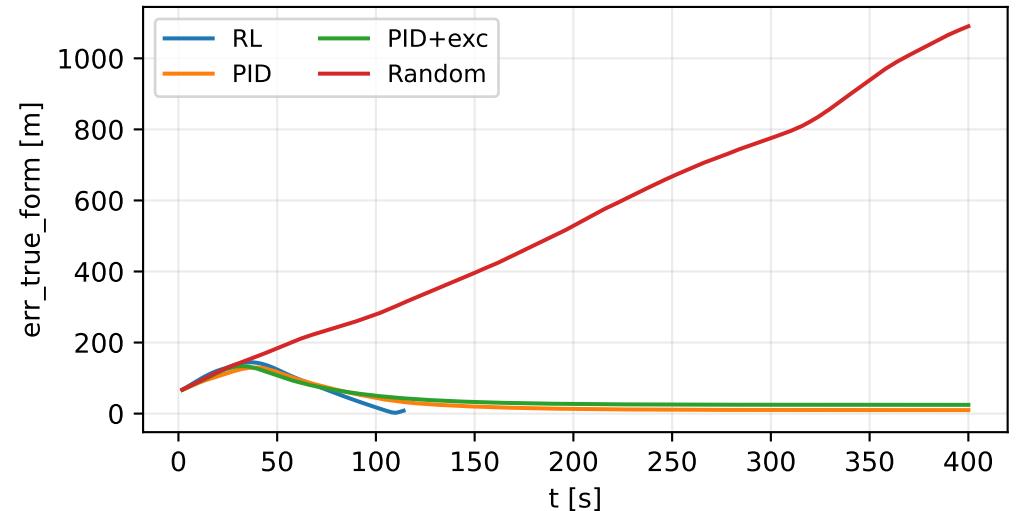
Follower angular rate



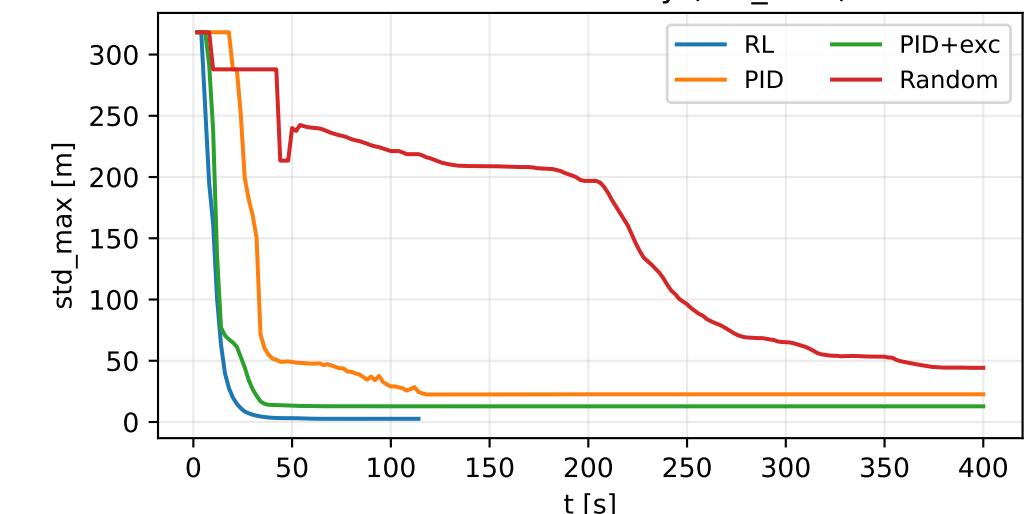
Trajectories (matched seed)



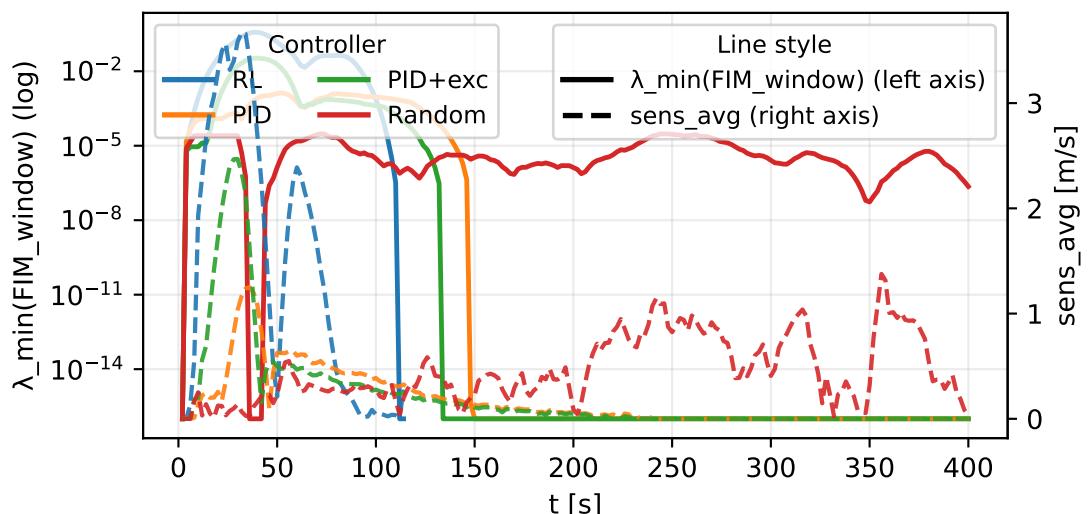
TRUE formation error



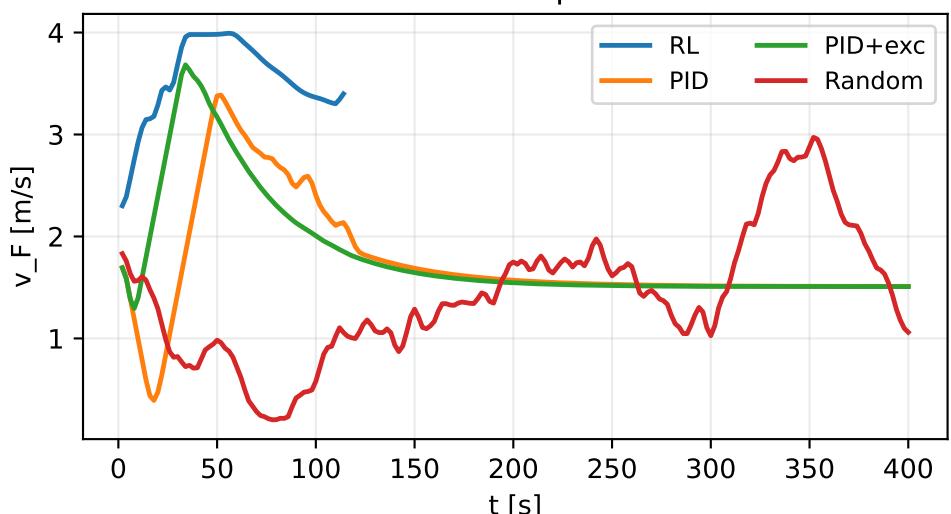
Estimator uncertainty (std_max)



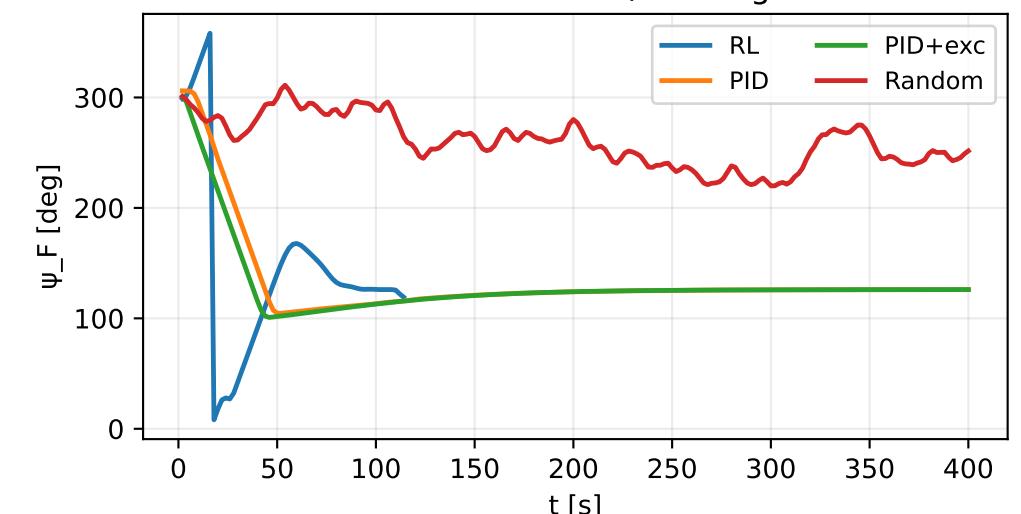
Information and excitation



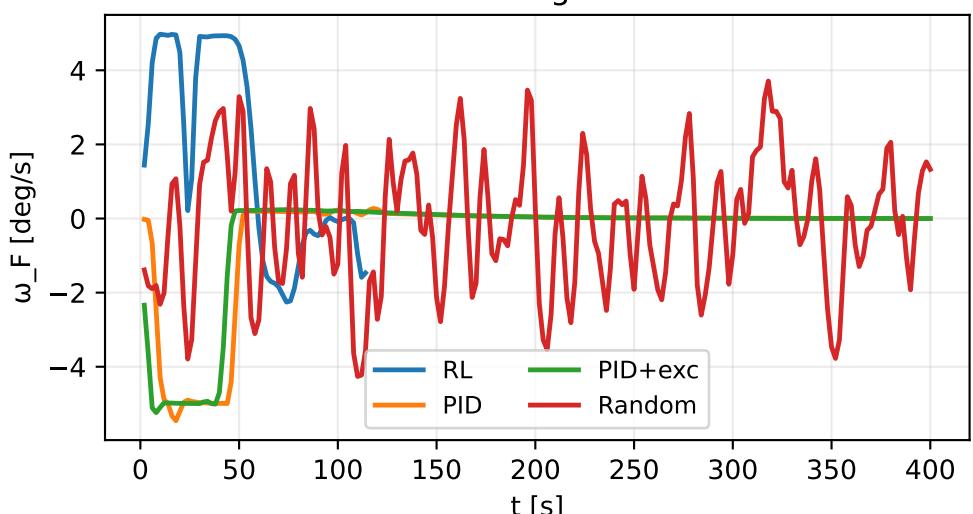
Follower speed



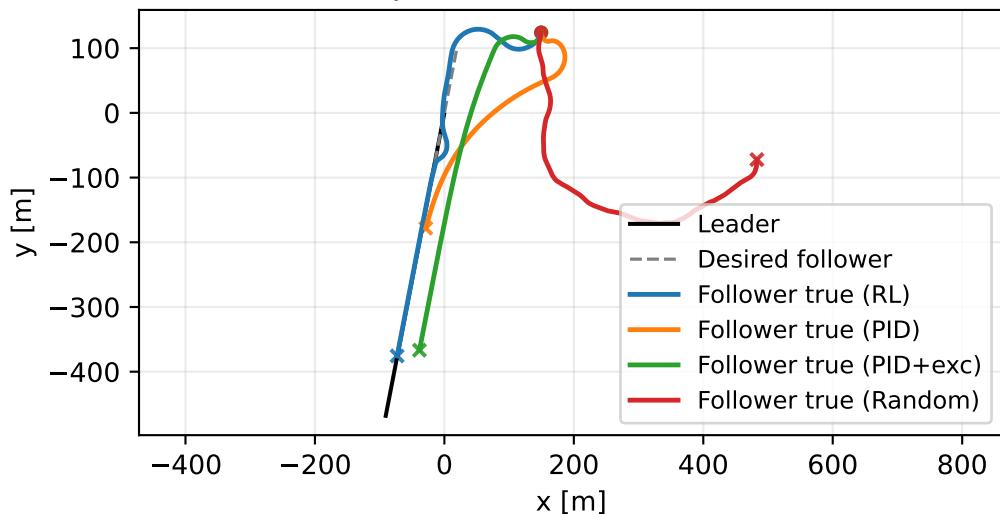
Follower course/heading



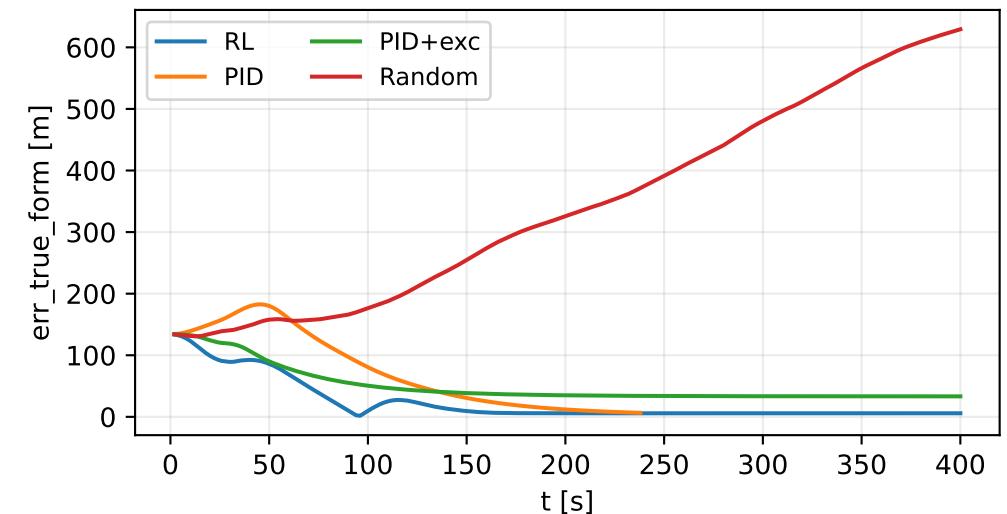
Follower angular rate



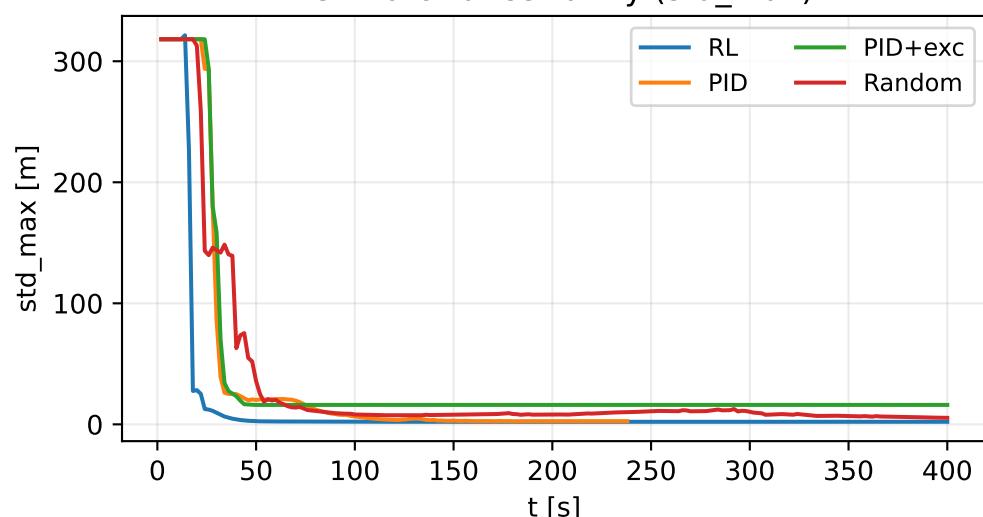
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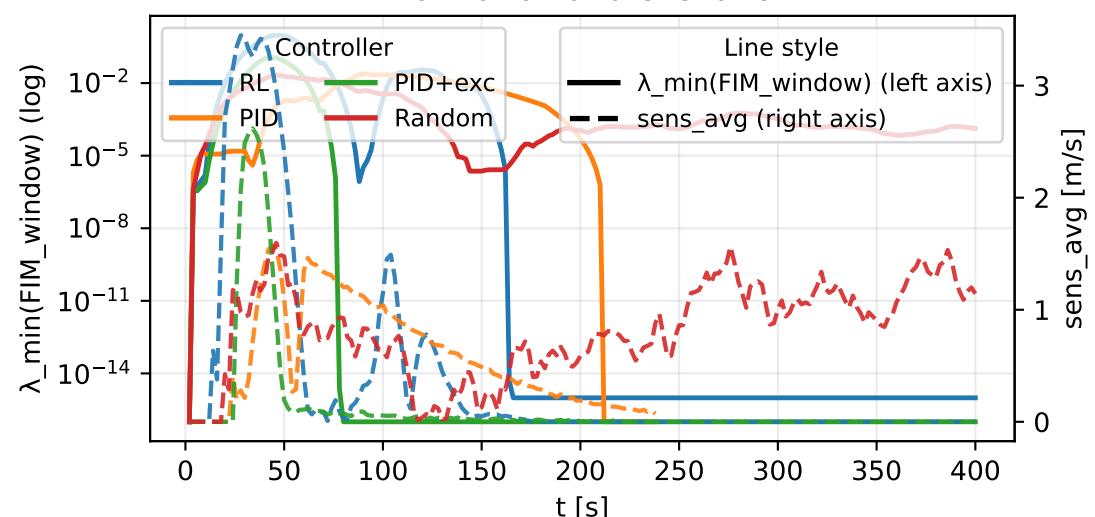
TRUE formation error



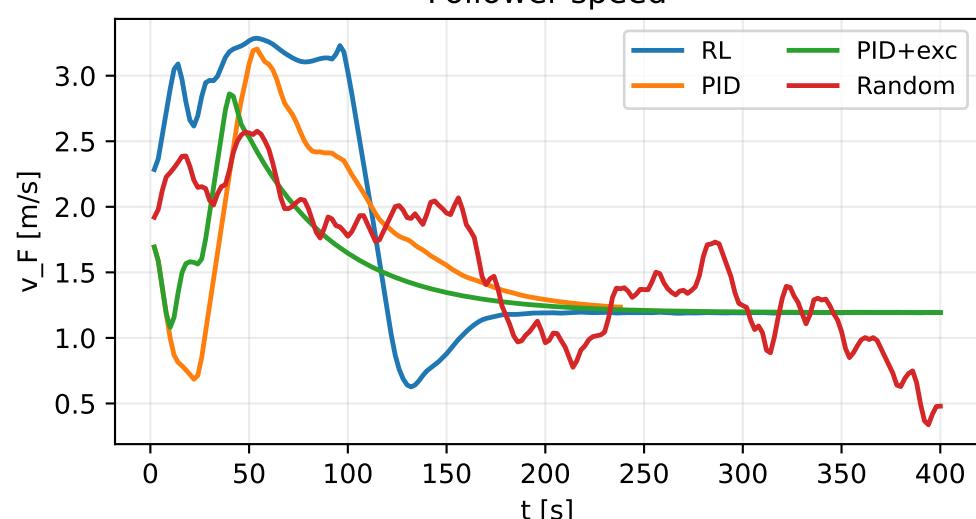
Estimator uncertainty (std_max)



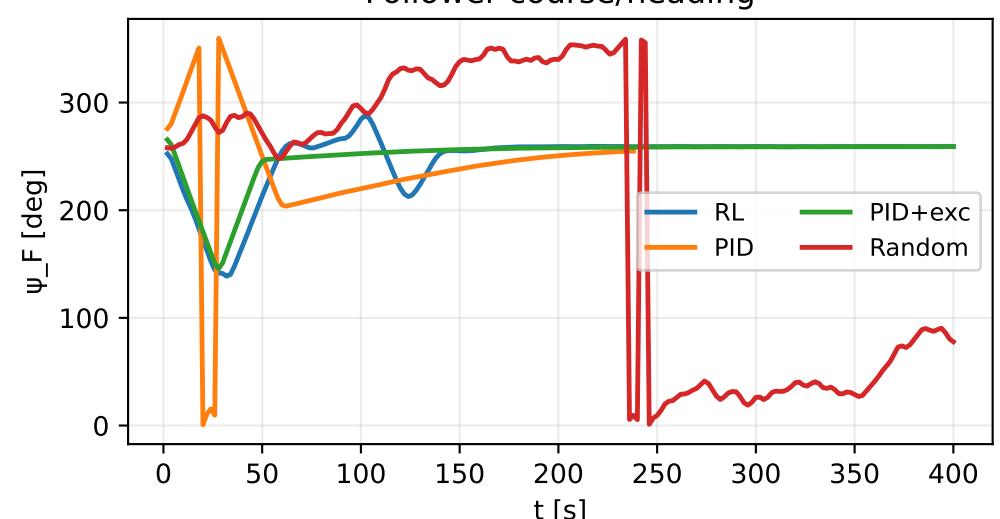
Information and excitation



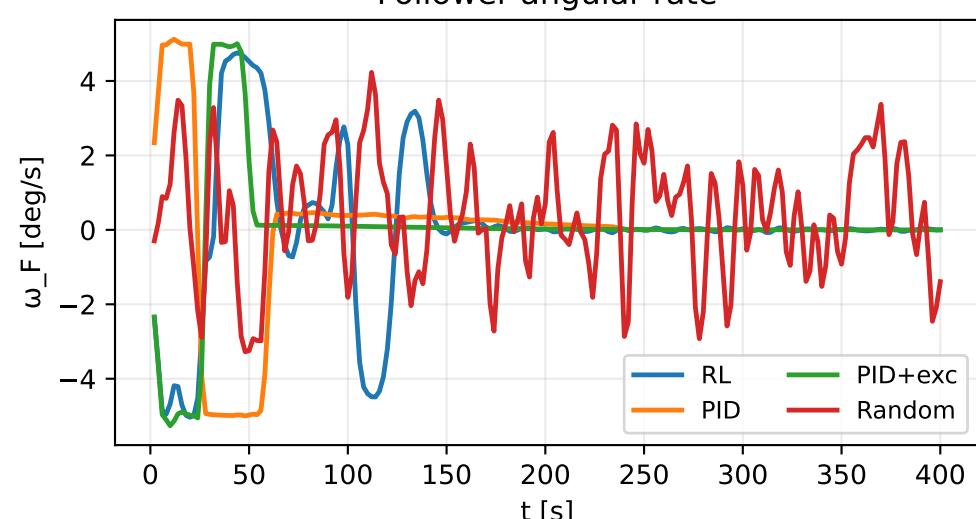
Follower speed



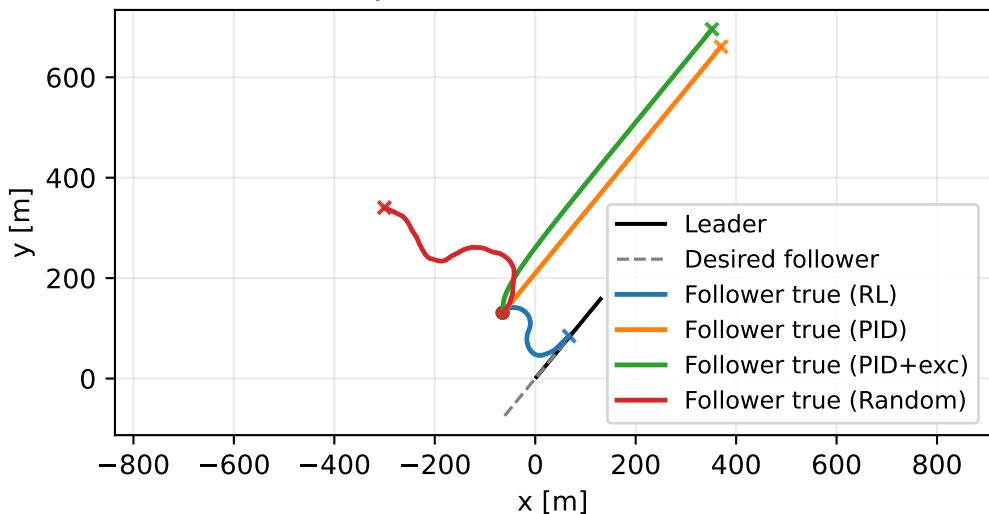
Follower course/heading



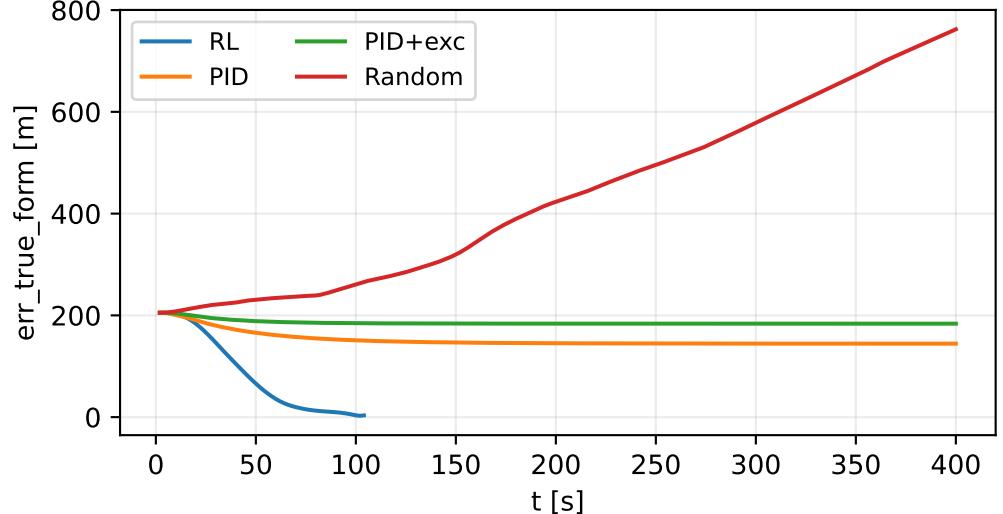
Follower angular rate



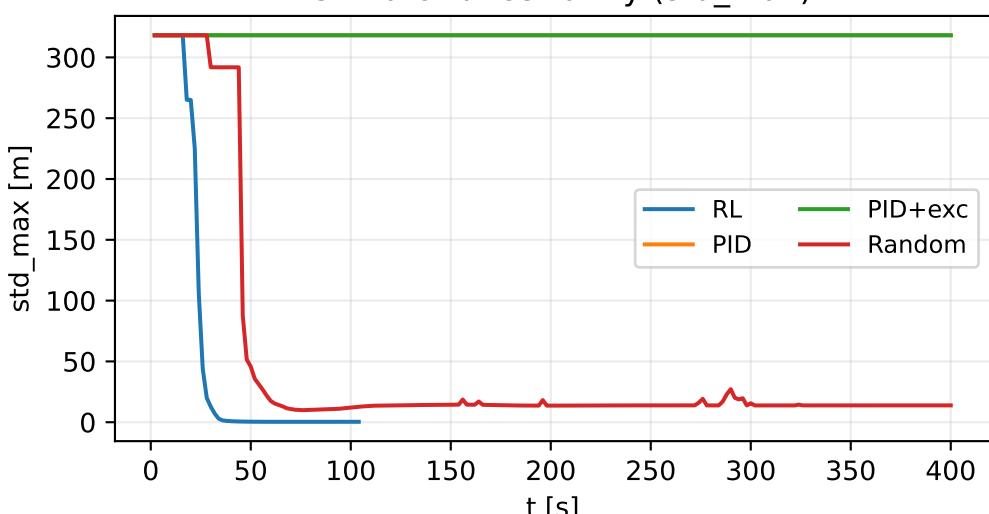
Trajectories (matched seed)



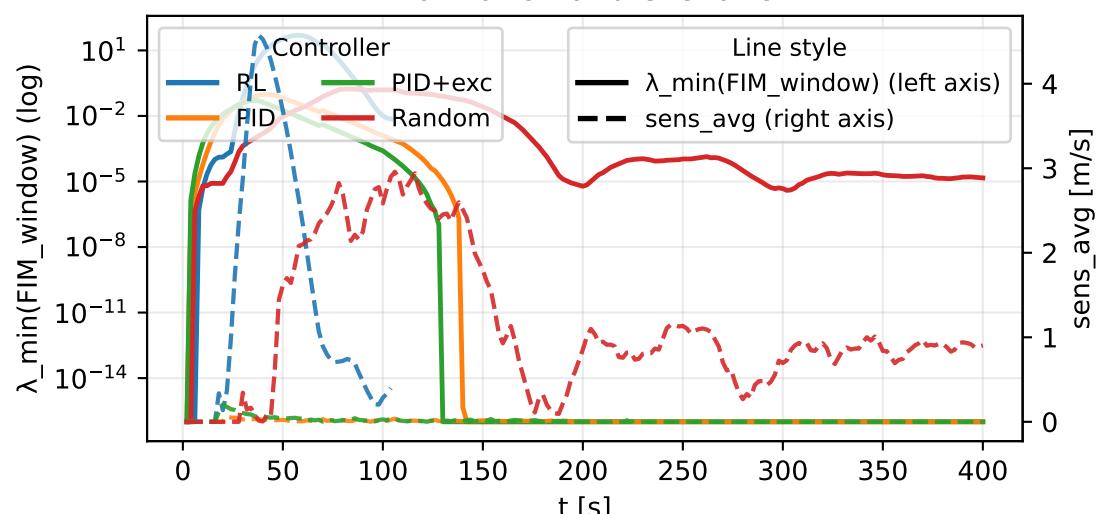
TRUE formation error



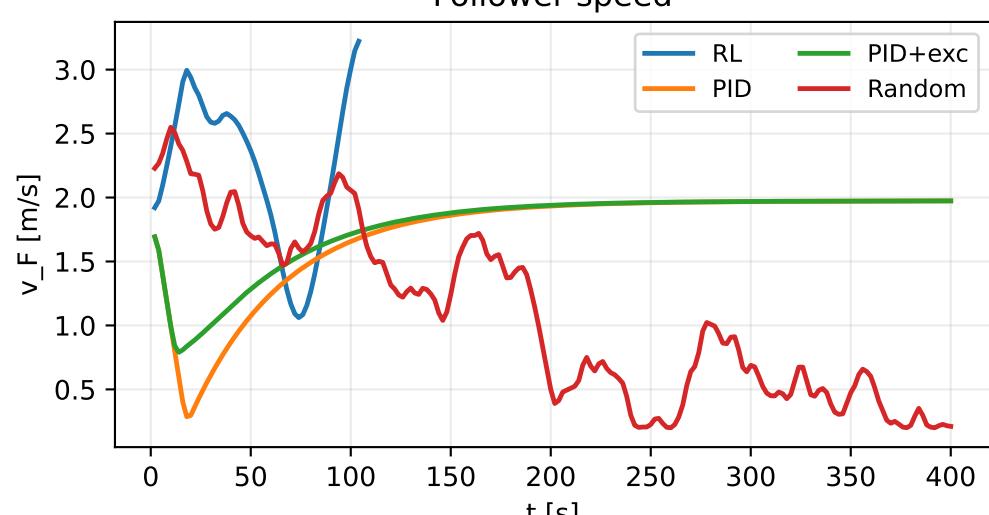
Estimator uncertainty (std_max)



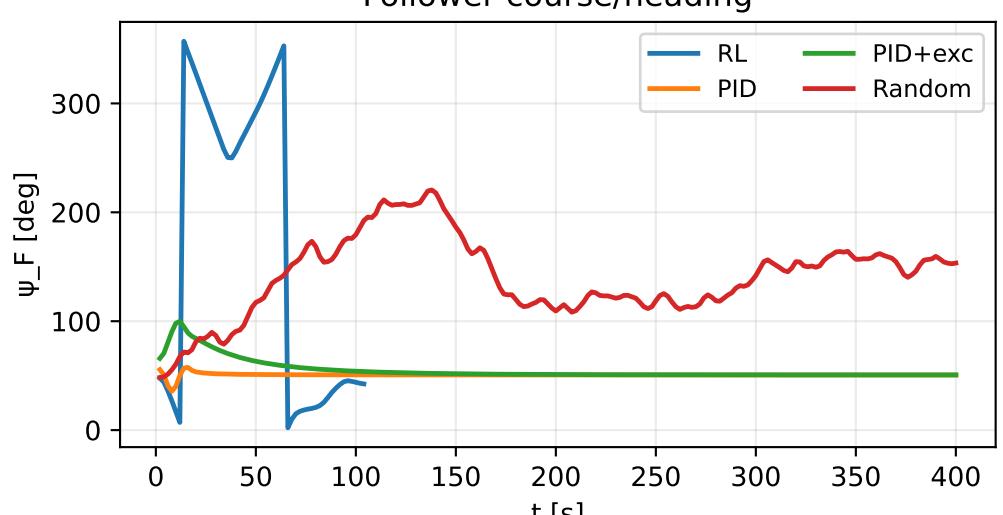
Information and excitation



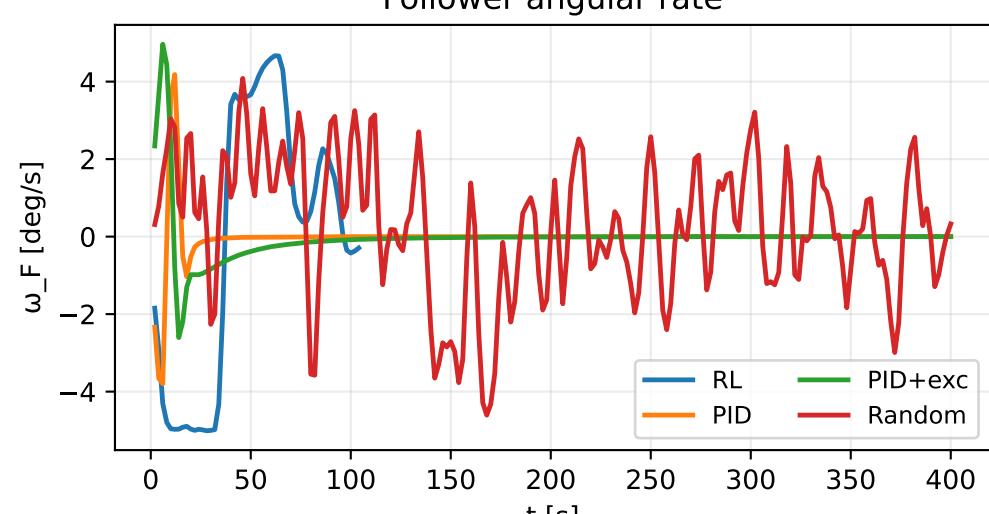
Follower speed



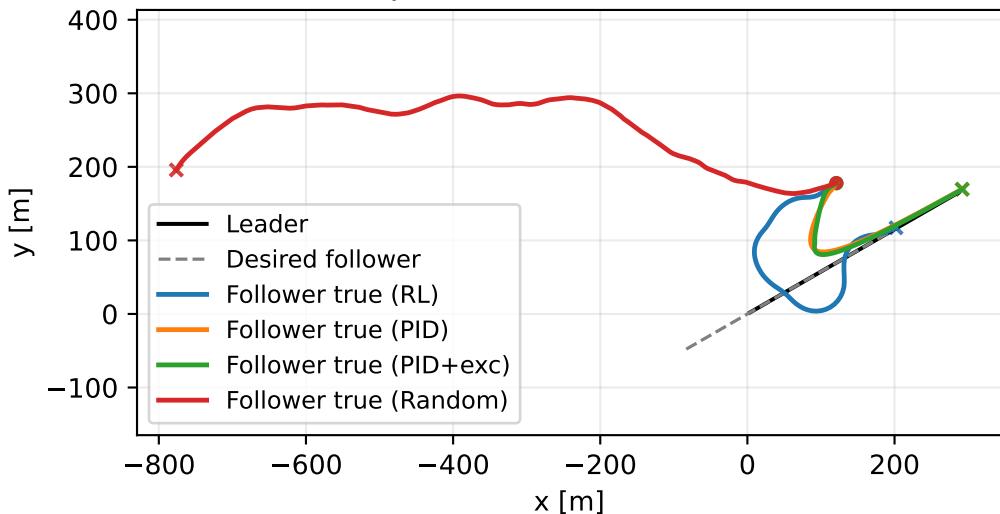
Follower course/heading



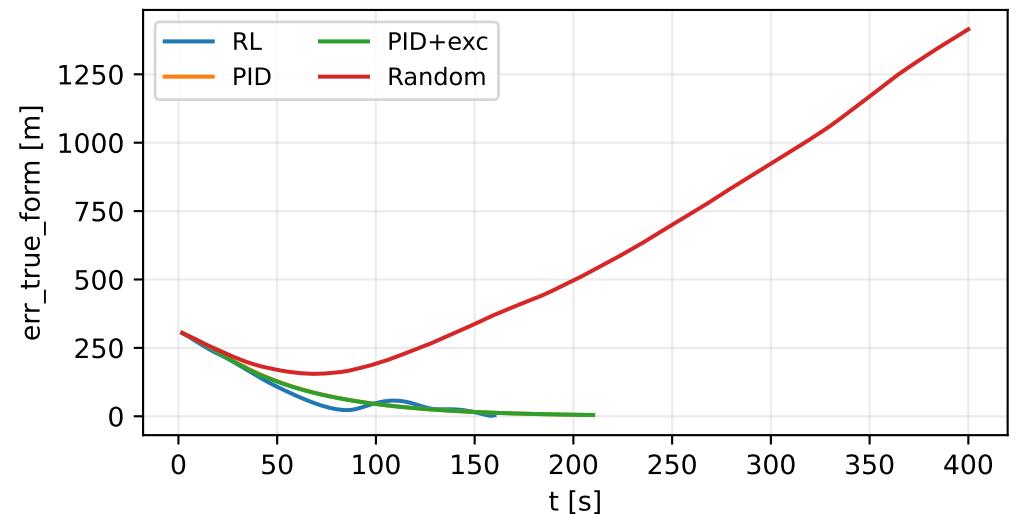
Follower angular rate



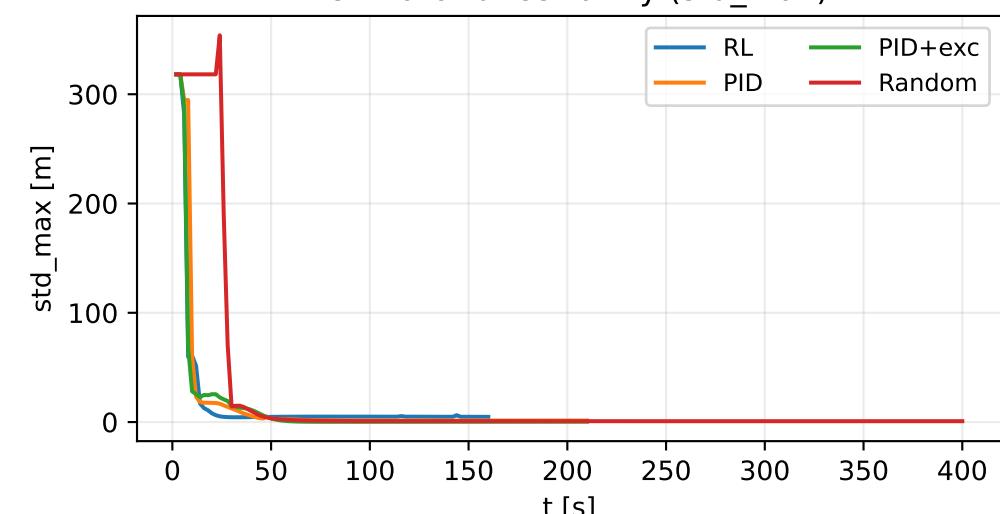
Trajectories (matched seed)



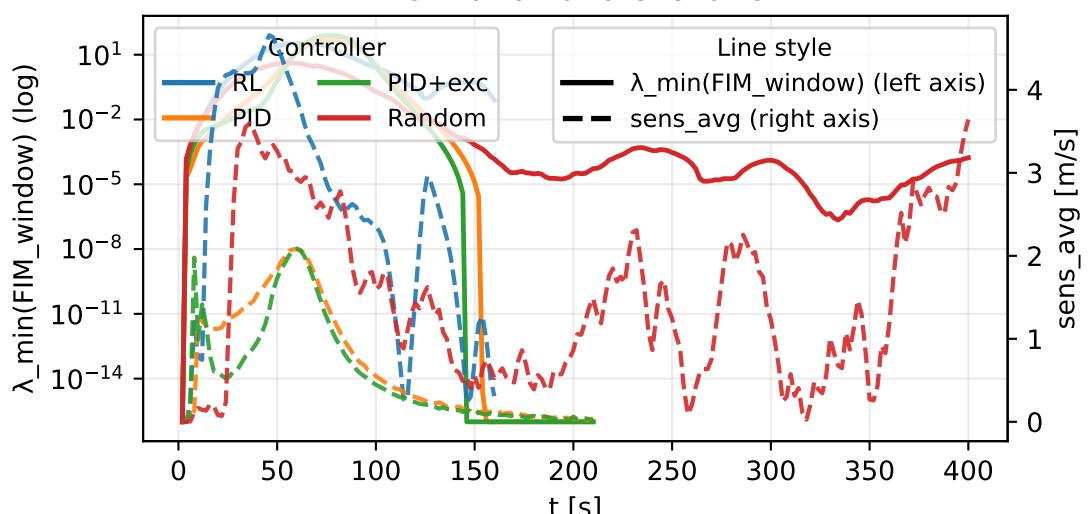
TRUE formation error



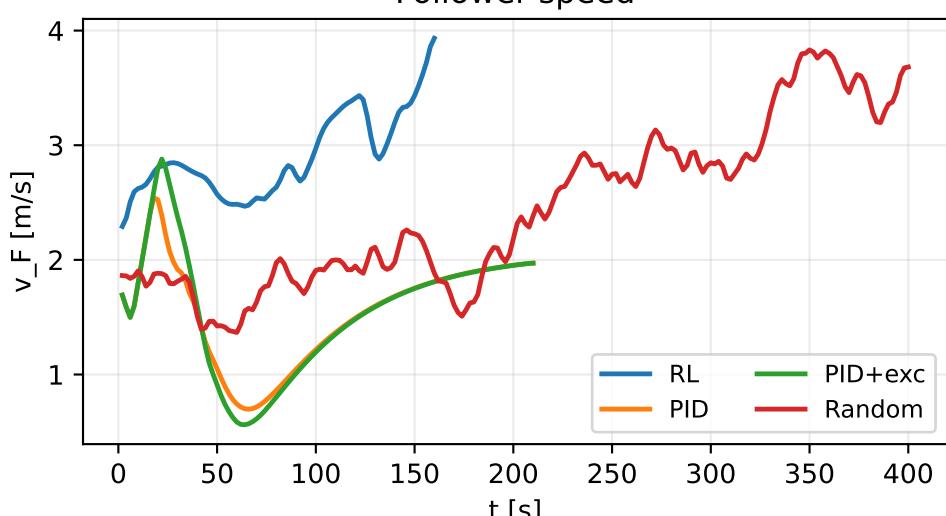
Estimator uncertainty (std_max)



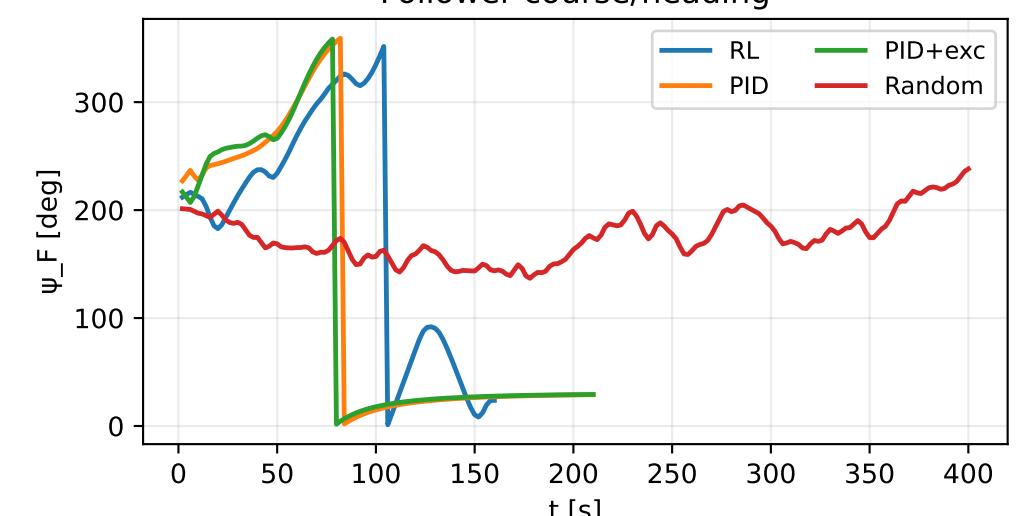
Information and excitation



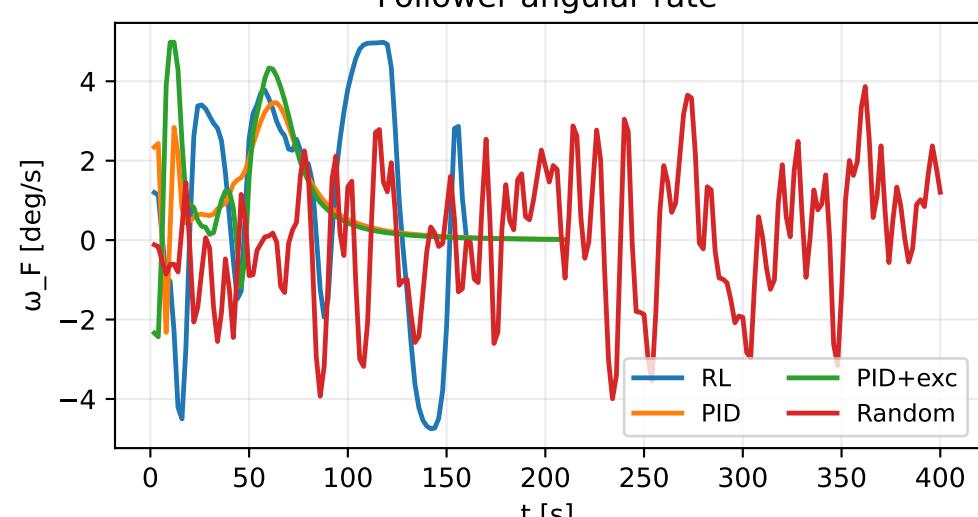
Follower speed



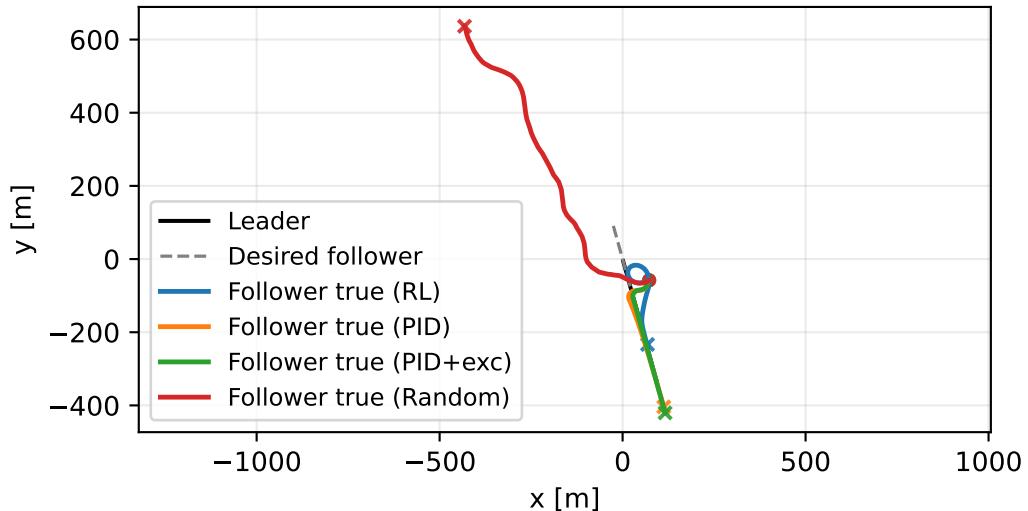
Follower course/heading



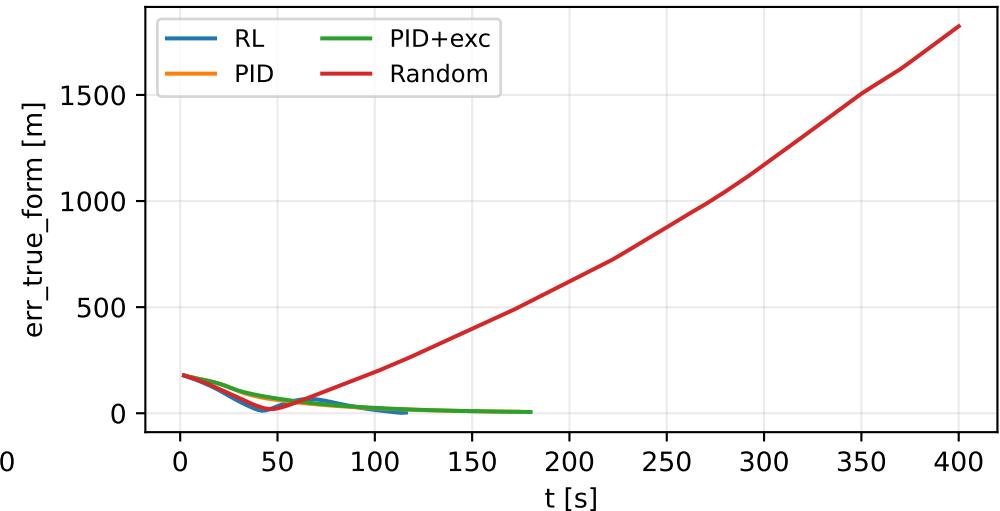
Follower angular rate



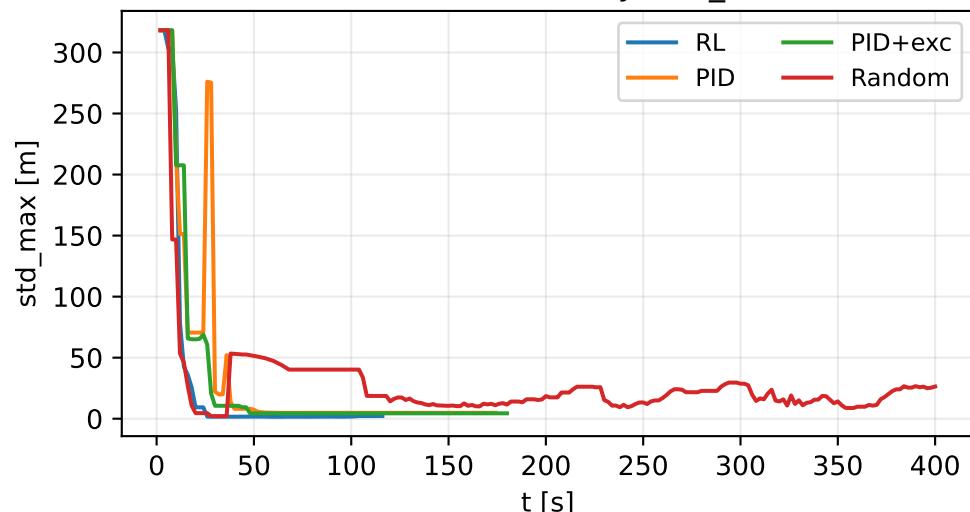
Trajectories (matched seed)



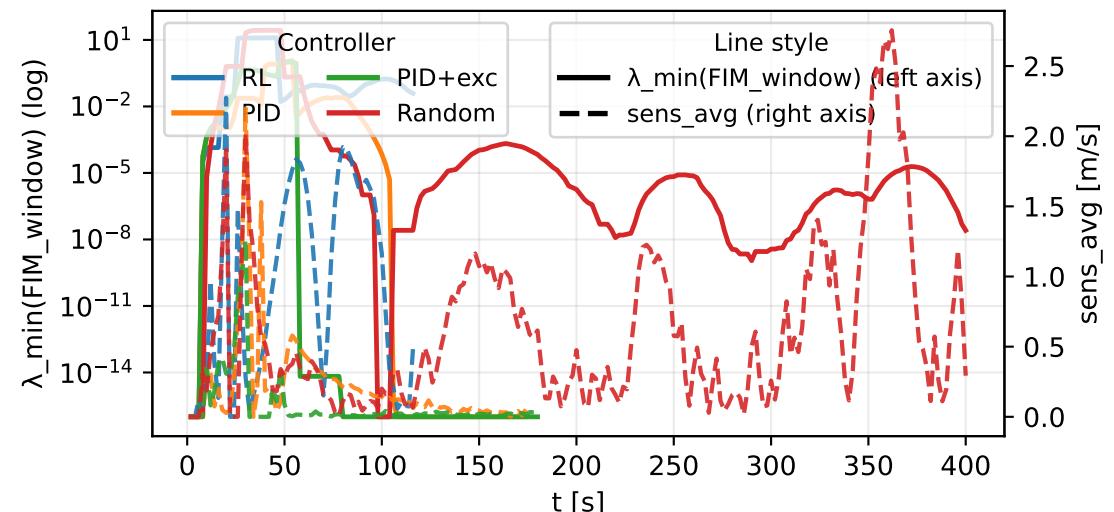
TRUE formation error



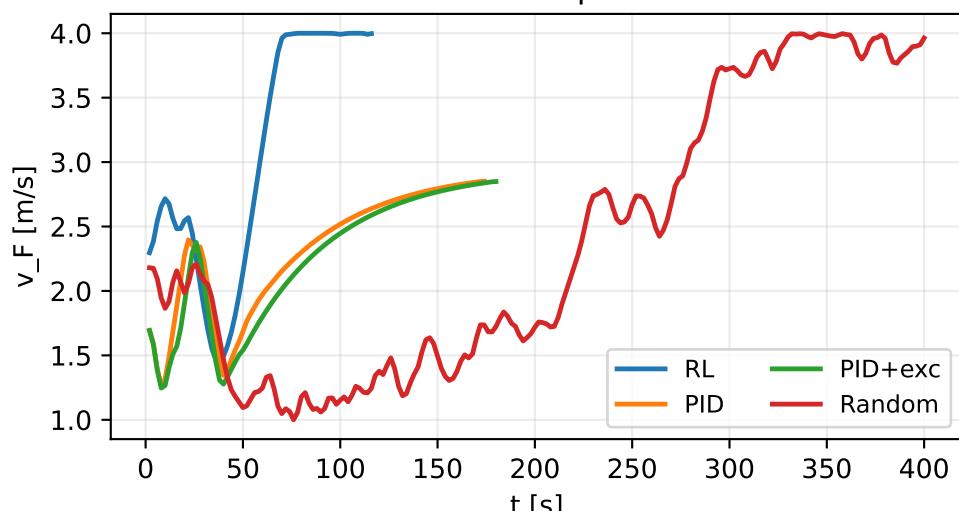
Estimator uncertainty (std_max)



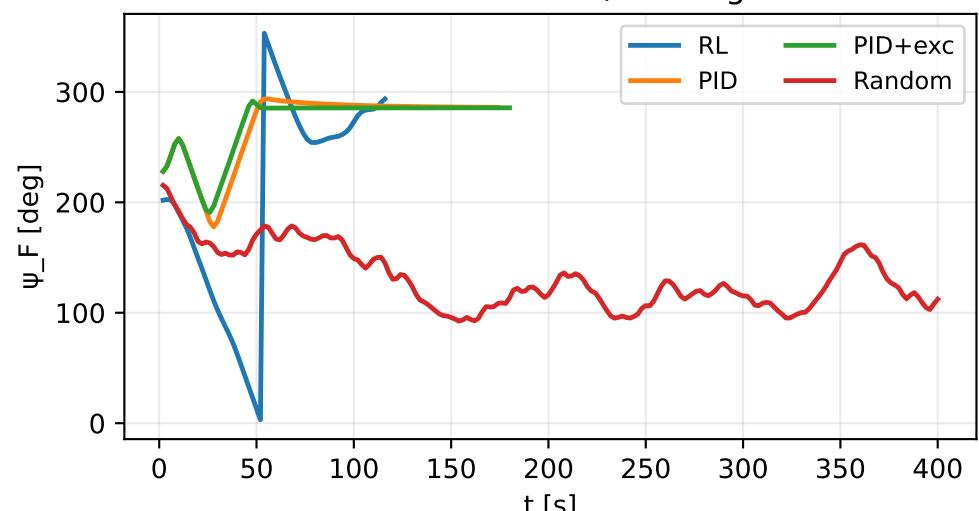
Information and excitation



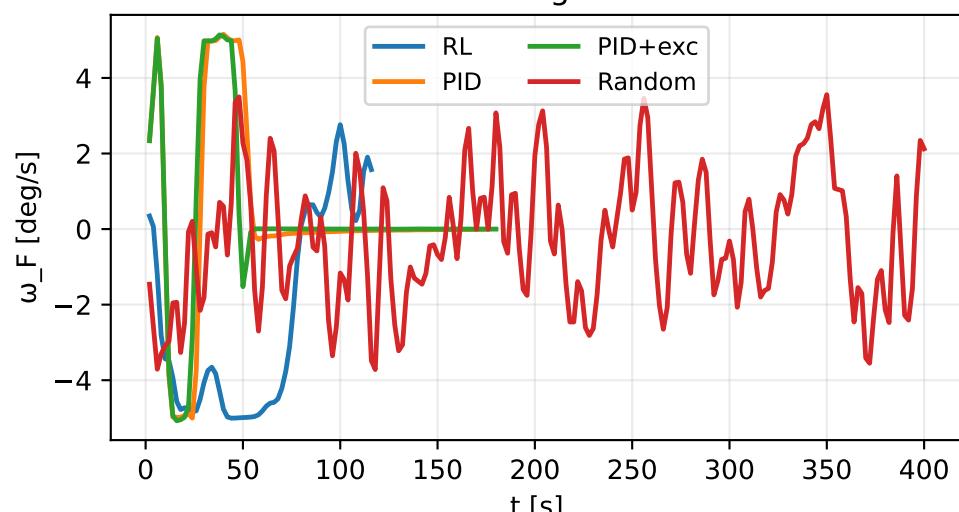
Follower speed



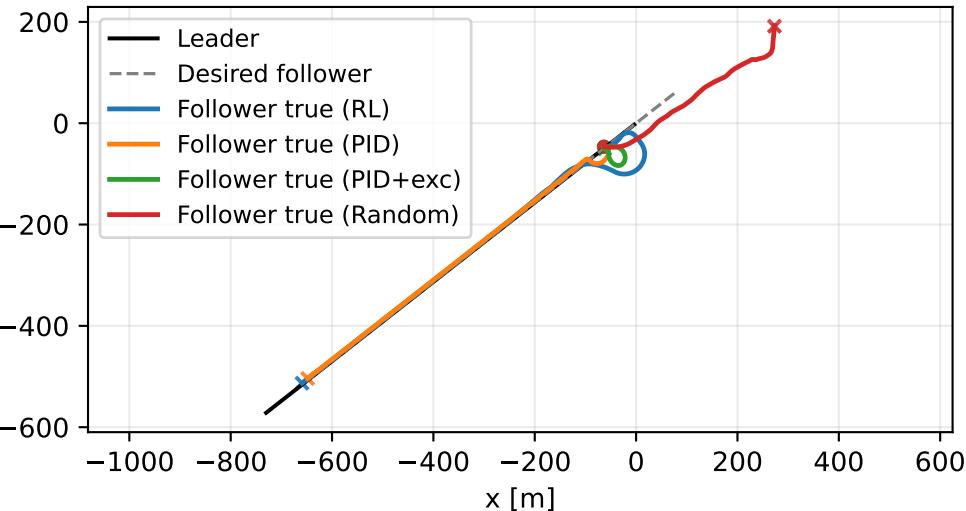
Follower course/heading



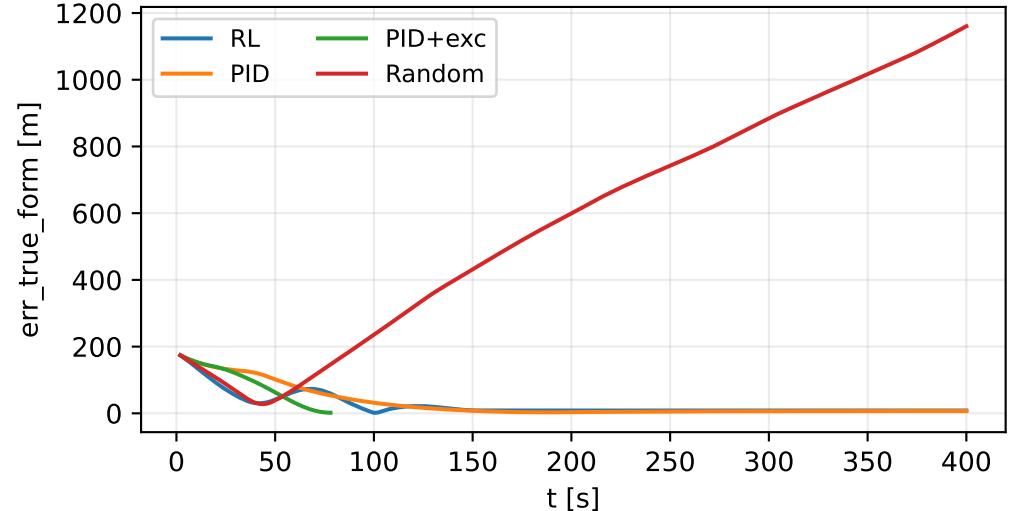
Follower angular rate



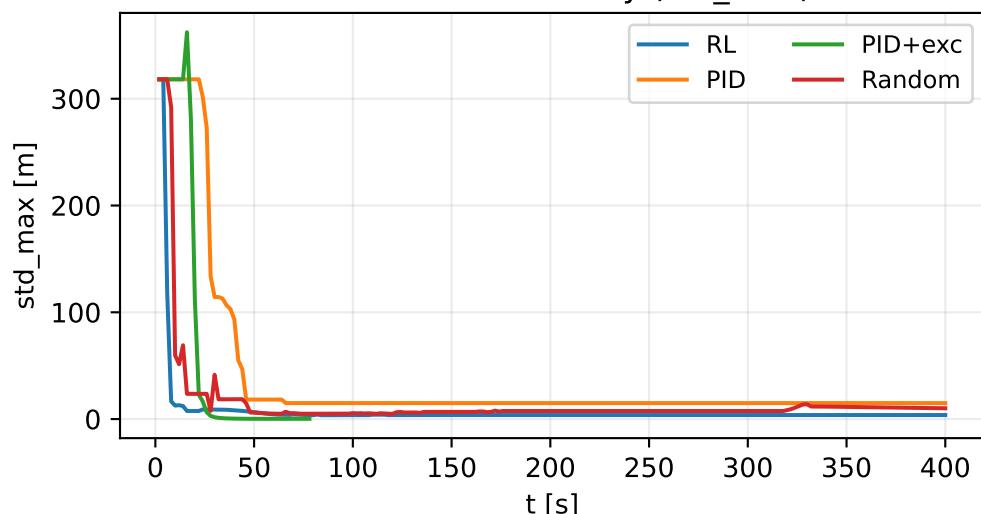
Trajectories (matched seed)



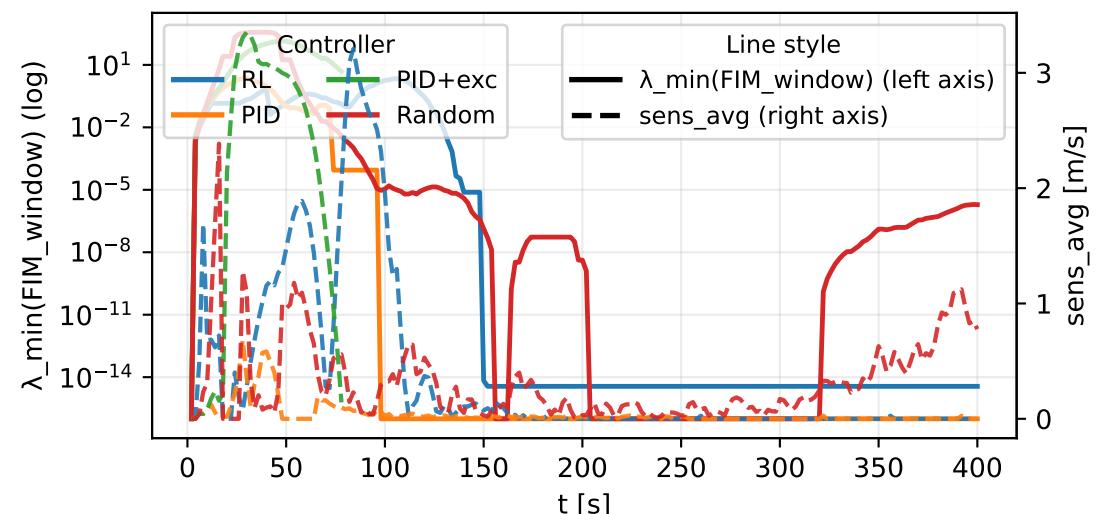
TRUE formation error



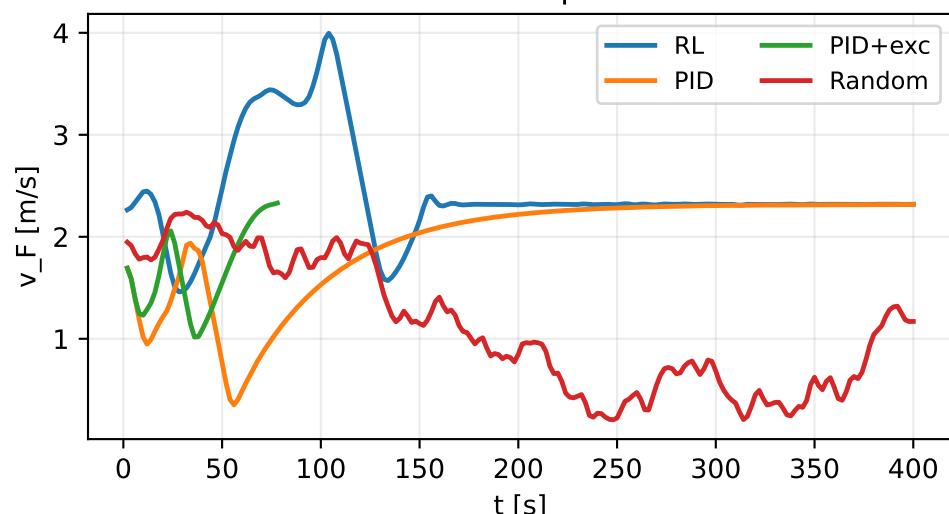
Estimator uncertainty (std_max)



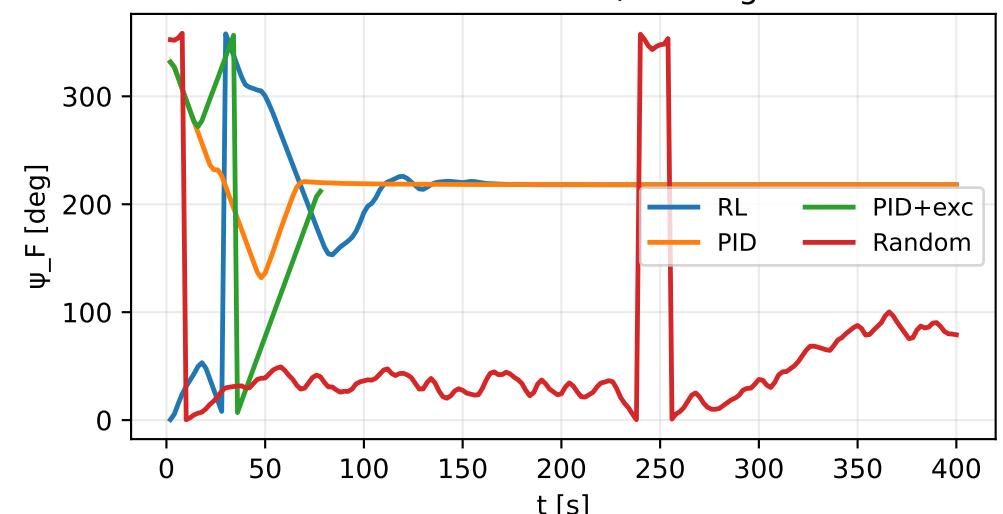
Information and excitation



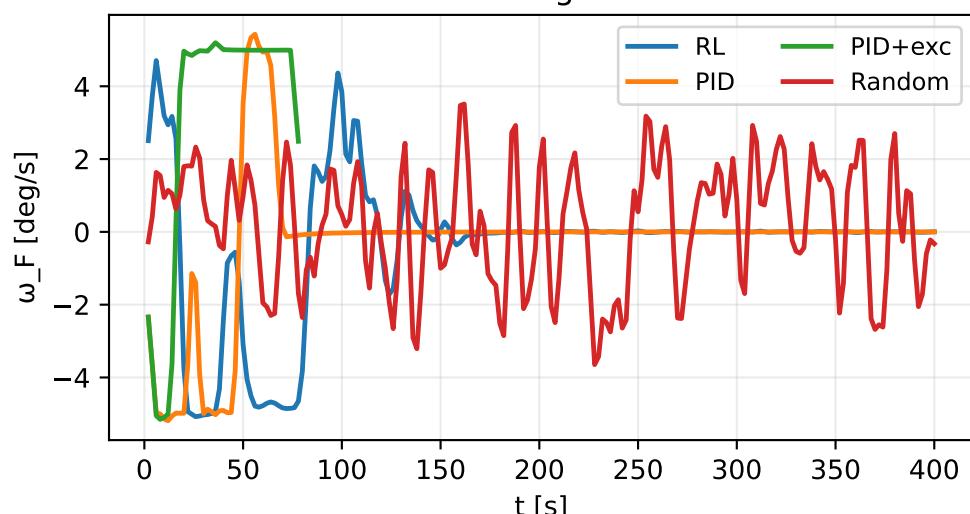
Follower speed



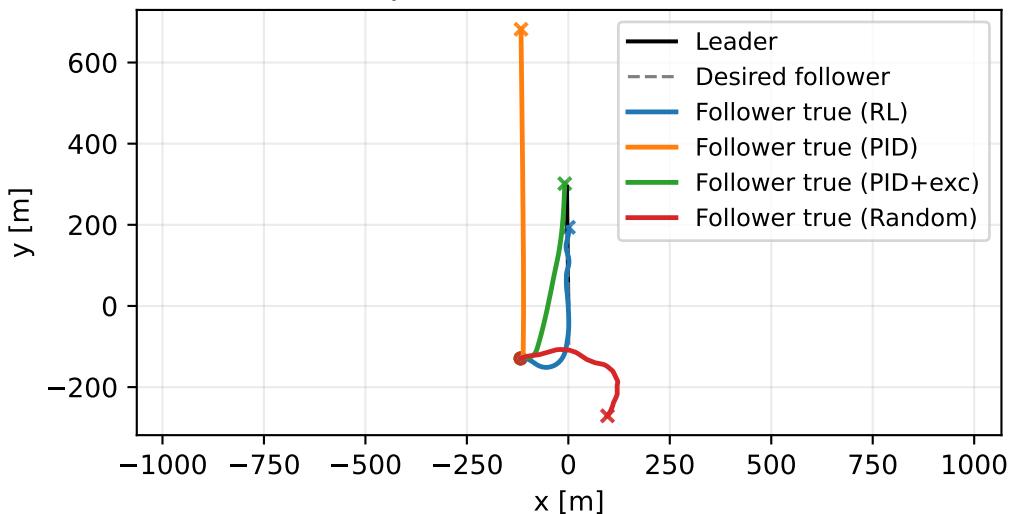
Follower course/heading



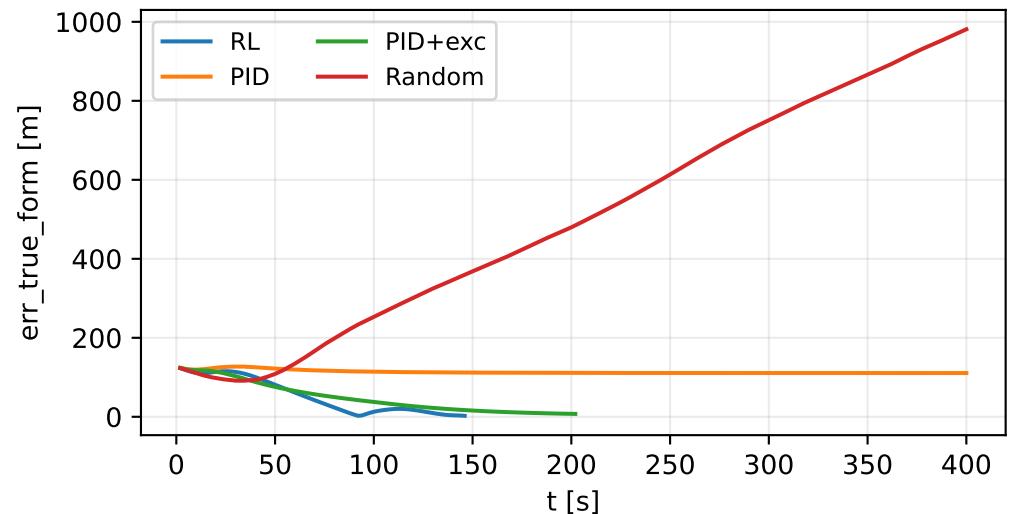
Follower angular rate



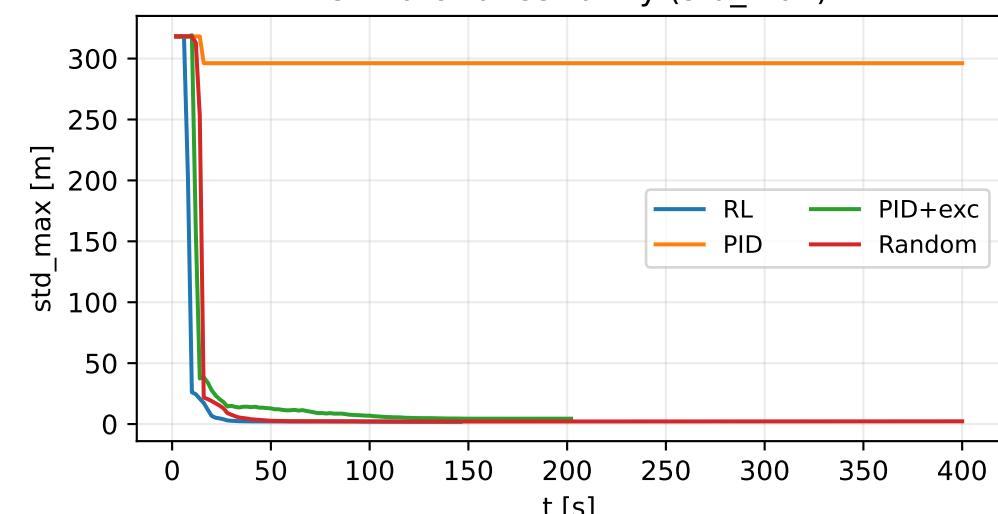
Trajectories (matched seed)



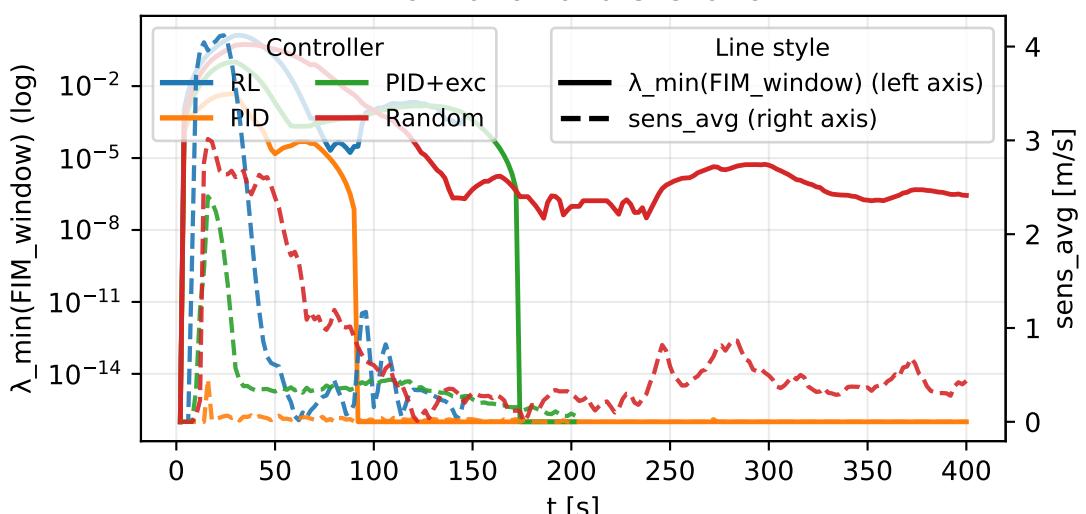
TRUE formation error



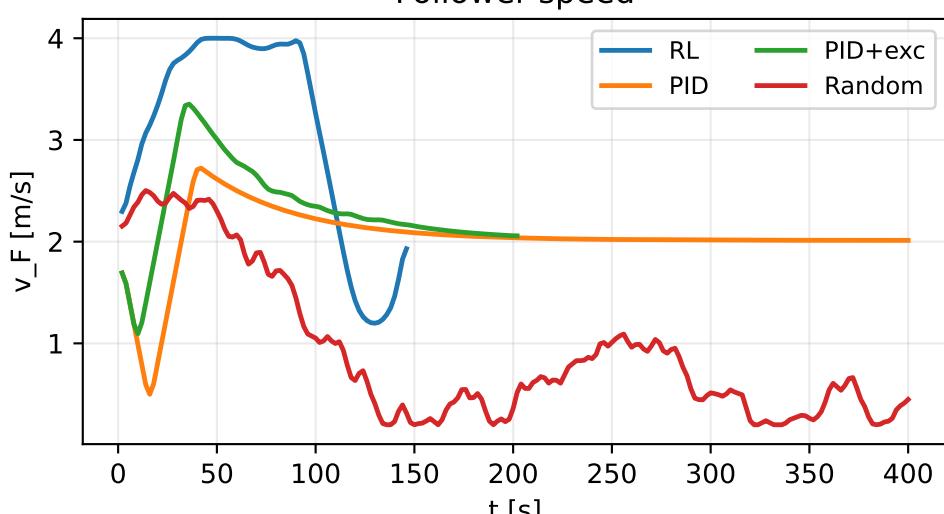
Estimator uncertainty (std_max)



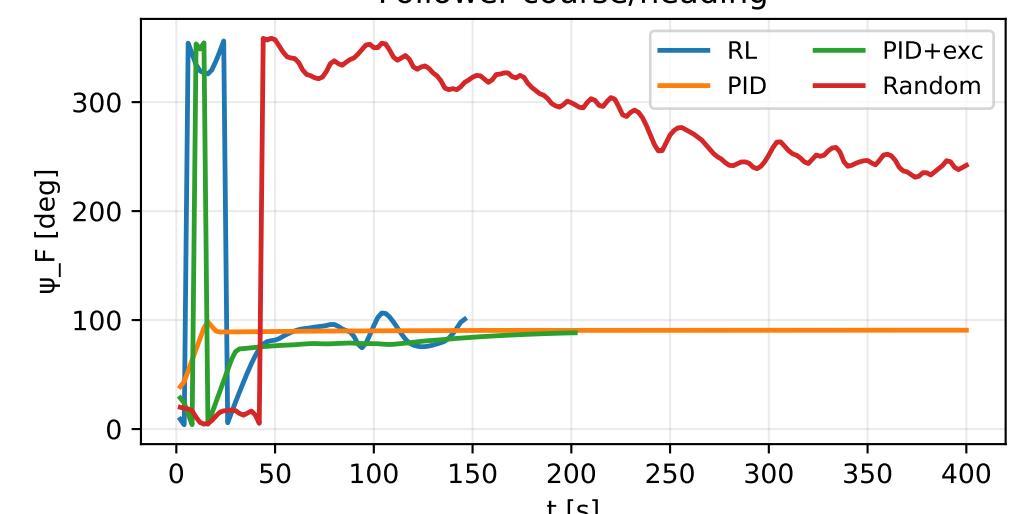
Information and excitation



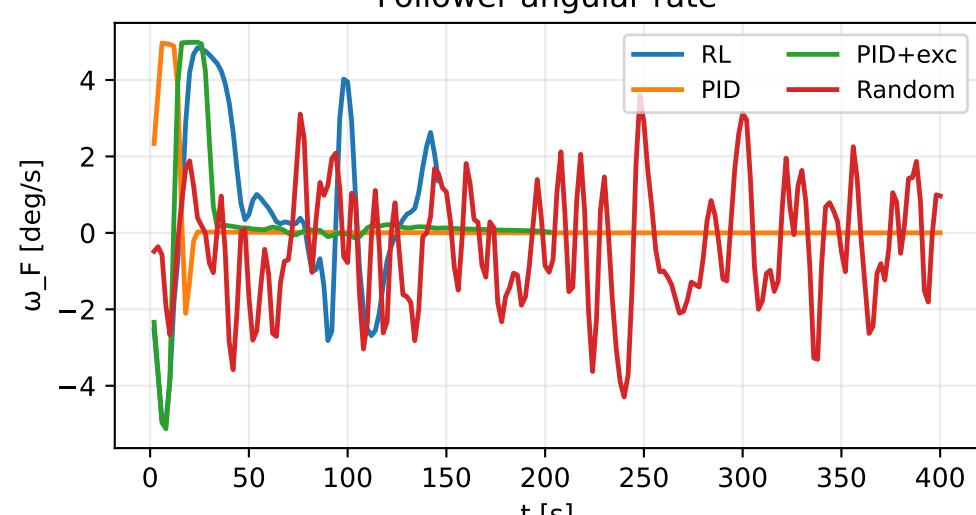
Follower speed



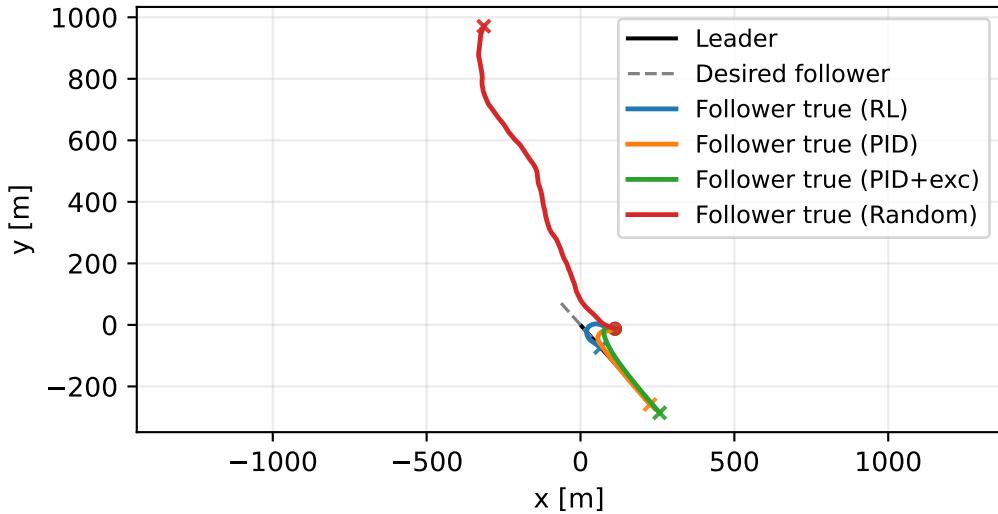
Follower course/heading



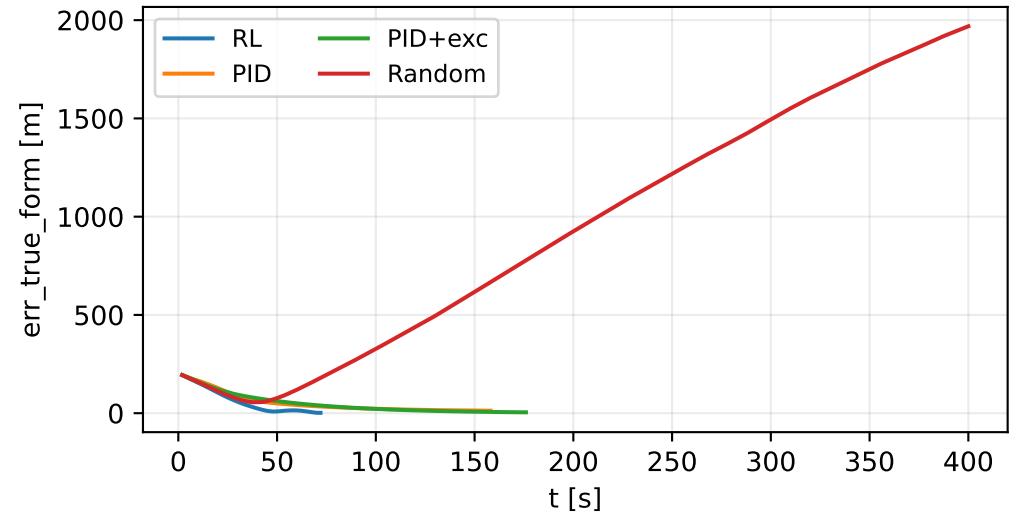
Follower angular rate



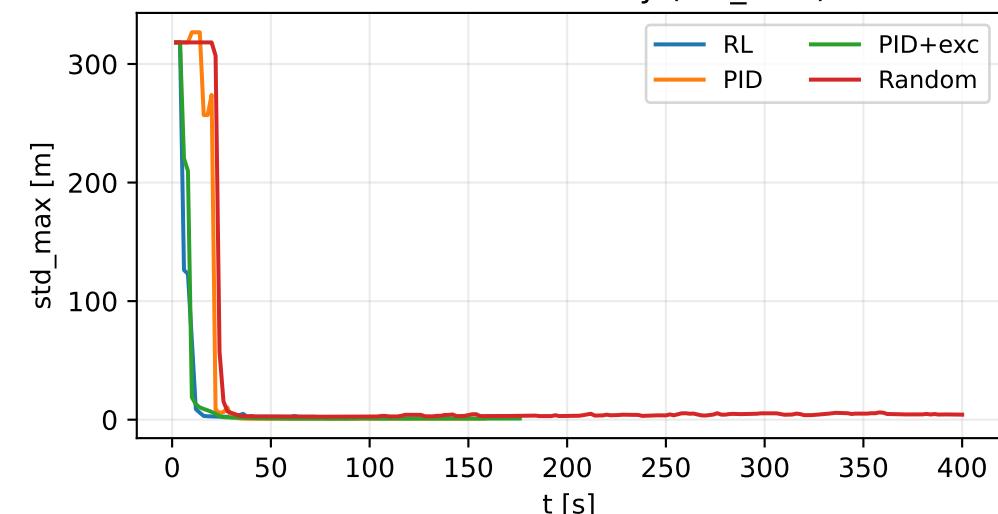
Trajectories (matched seed)



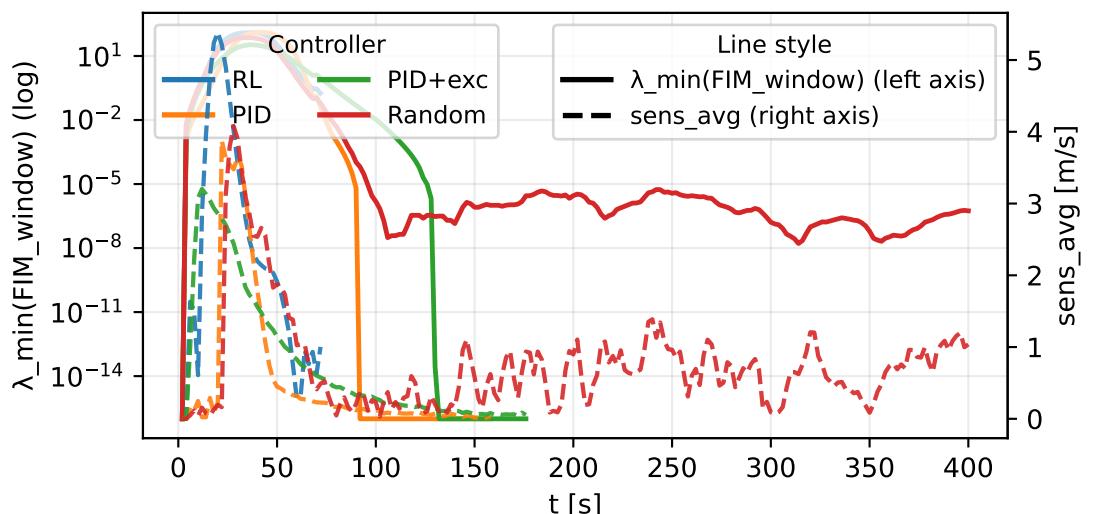
TRUE formation error



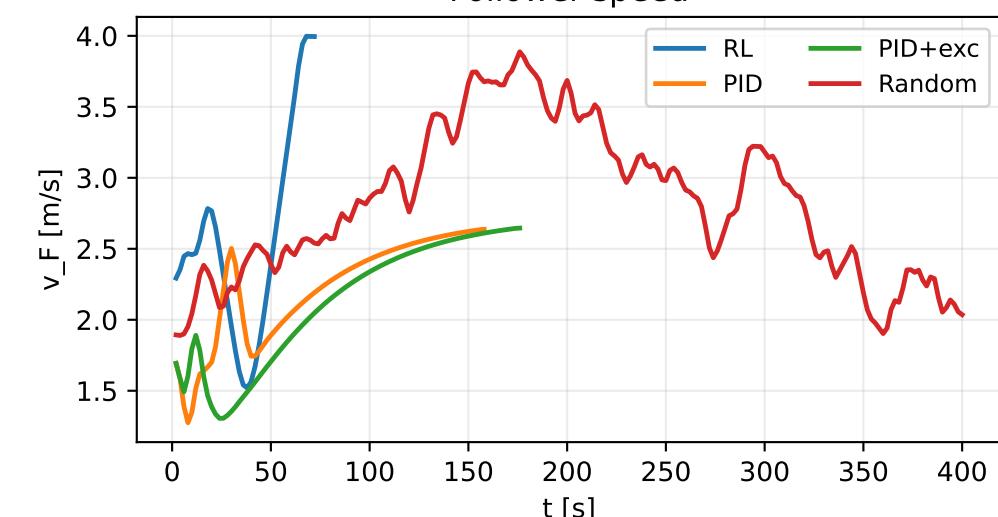
Estimator uncertainty (std_max)



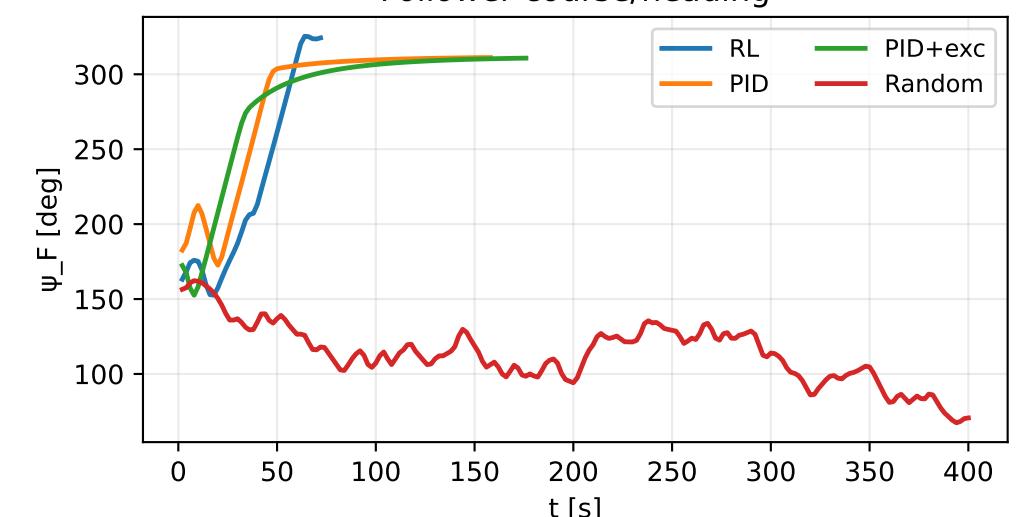
Information and excitation



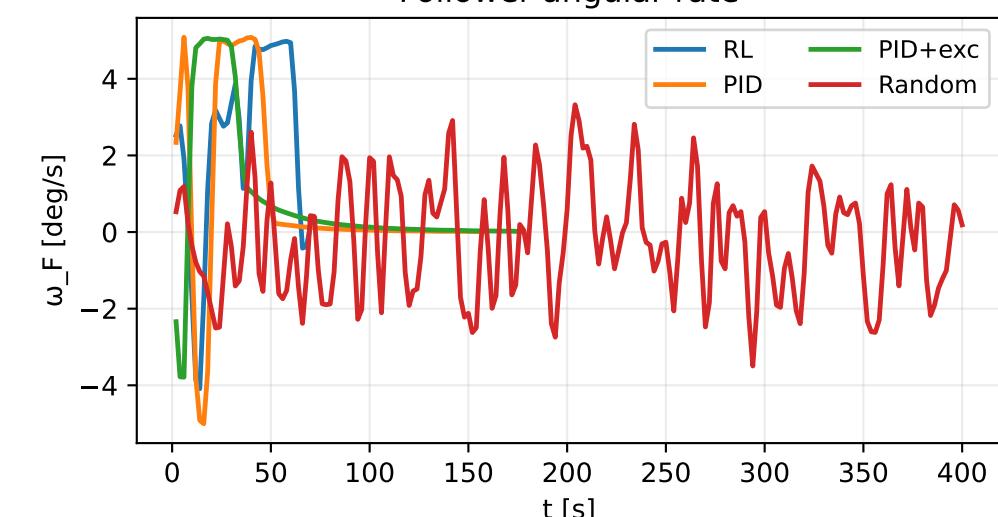
Follower speed



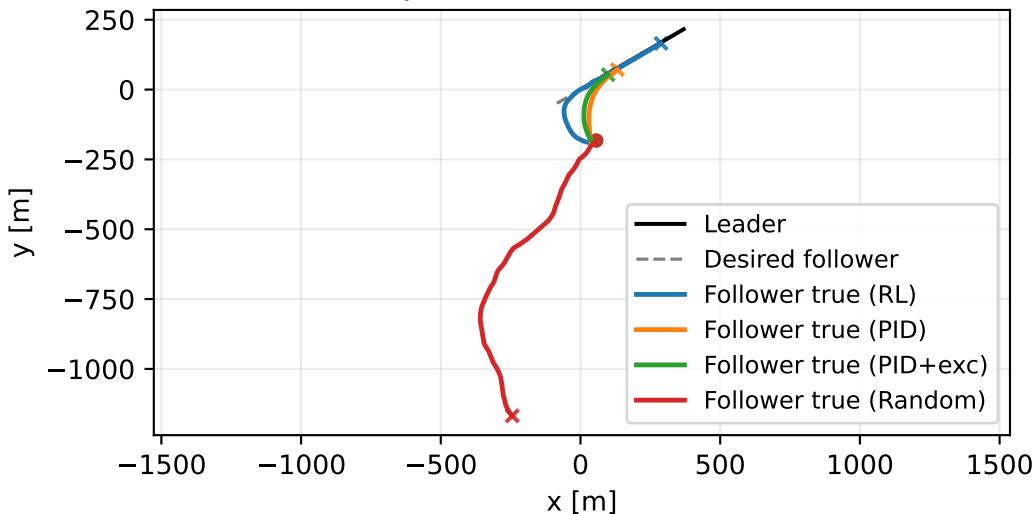
Follower course/heading



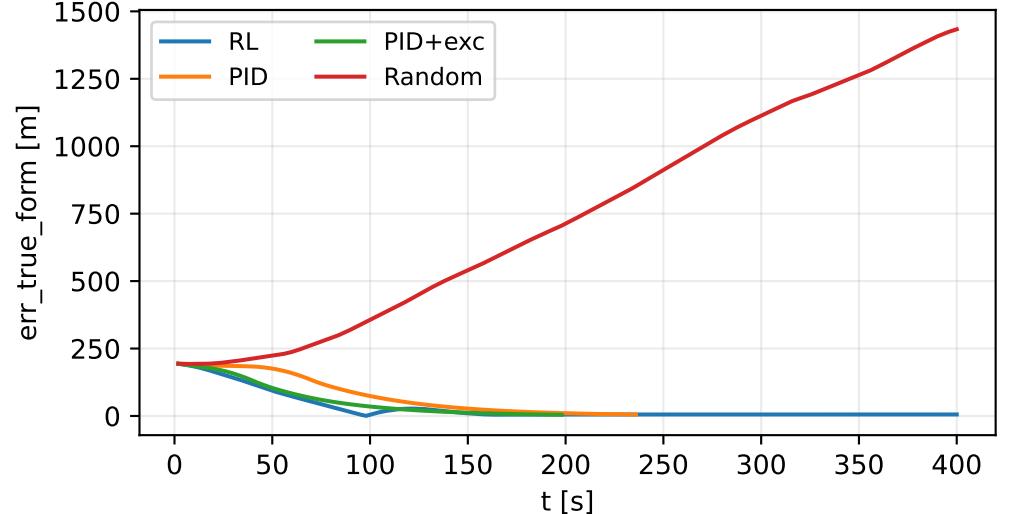
Follower angular rate



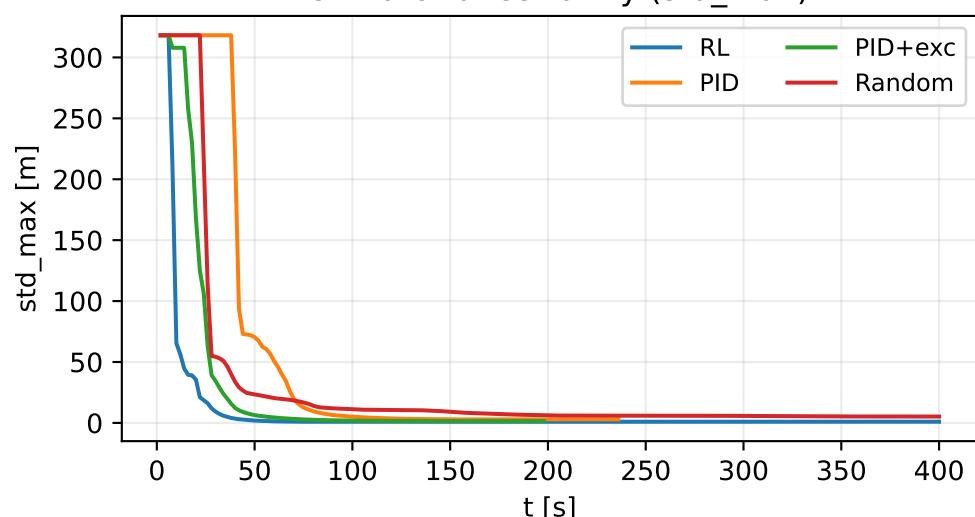
Trajectories (matched seed)



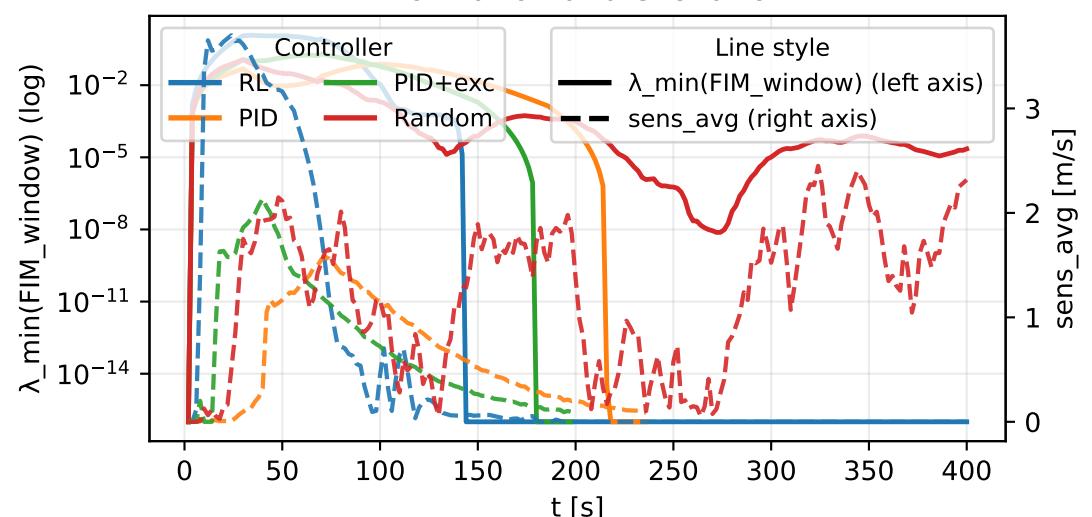
TRUE formation error



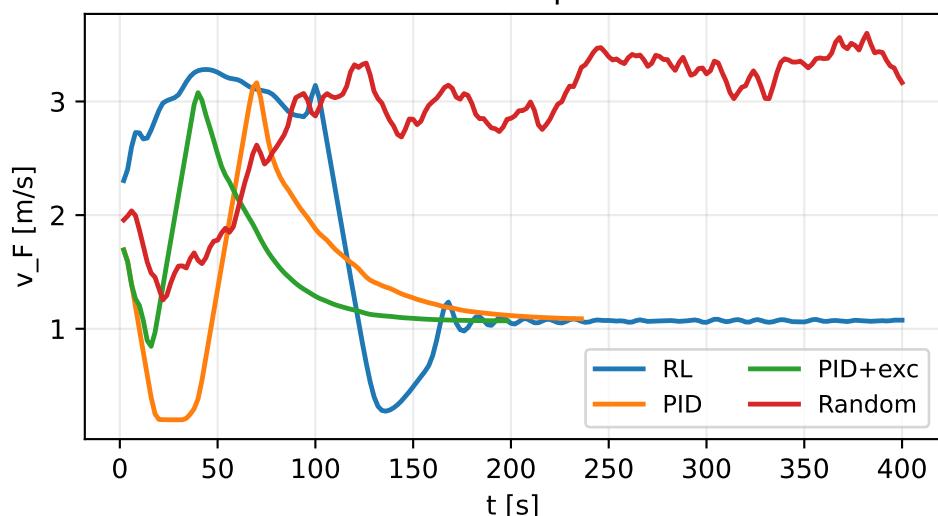
Estimator uncertainty (std_max)



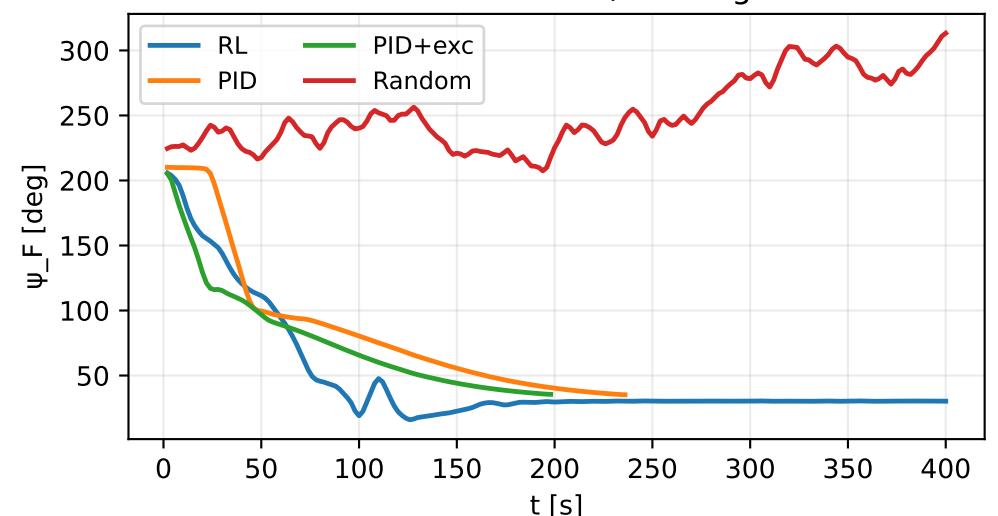
Information and excitation



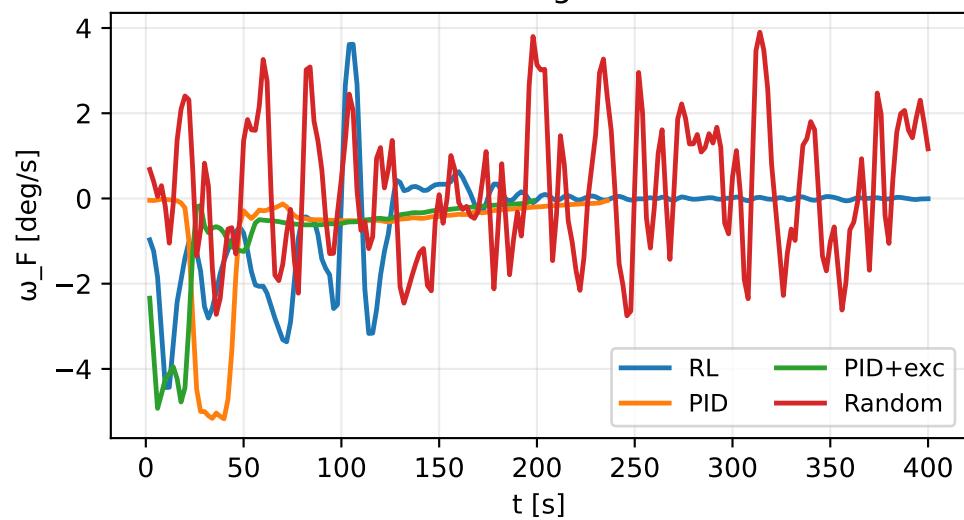
Follower speed



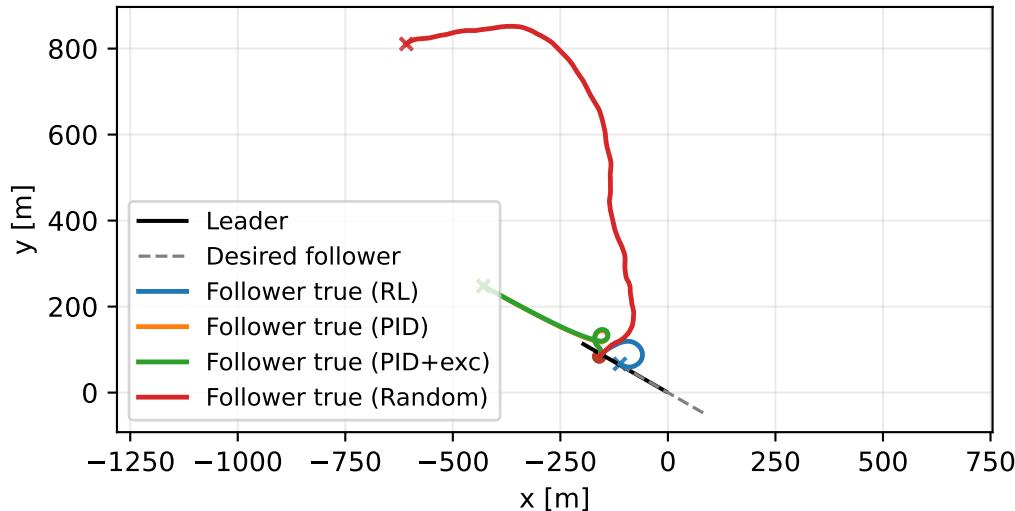
Follower course/heading



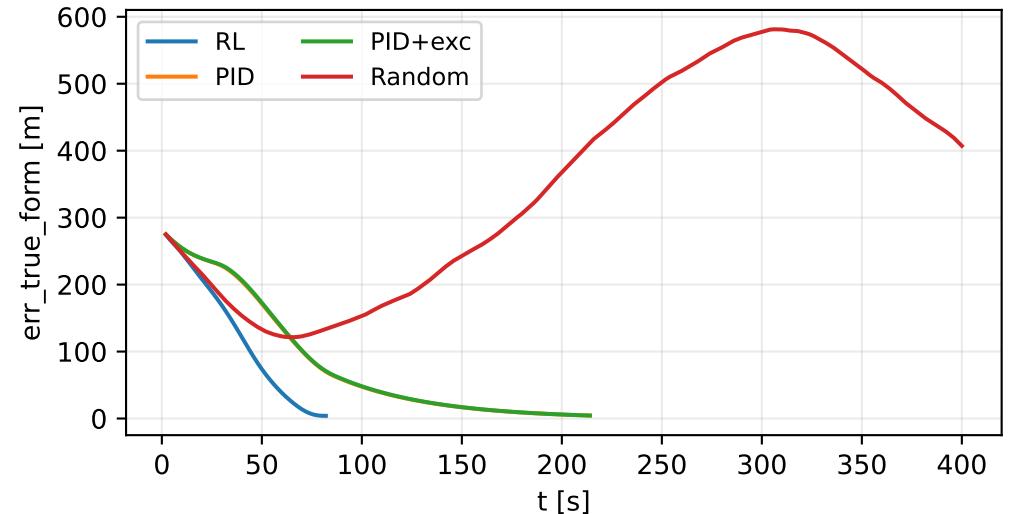
Follower angular rate



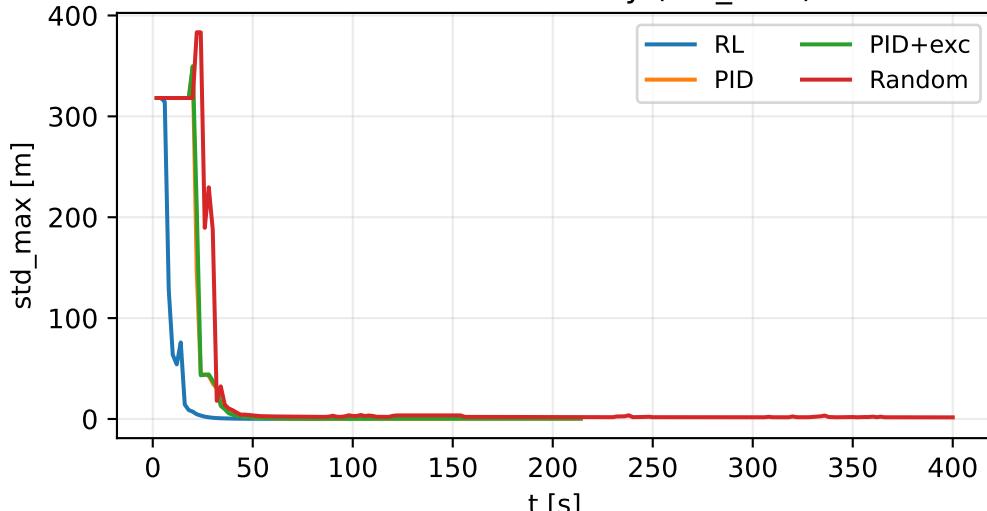
Trajectories (matched seed)



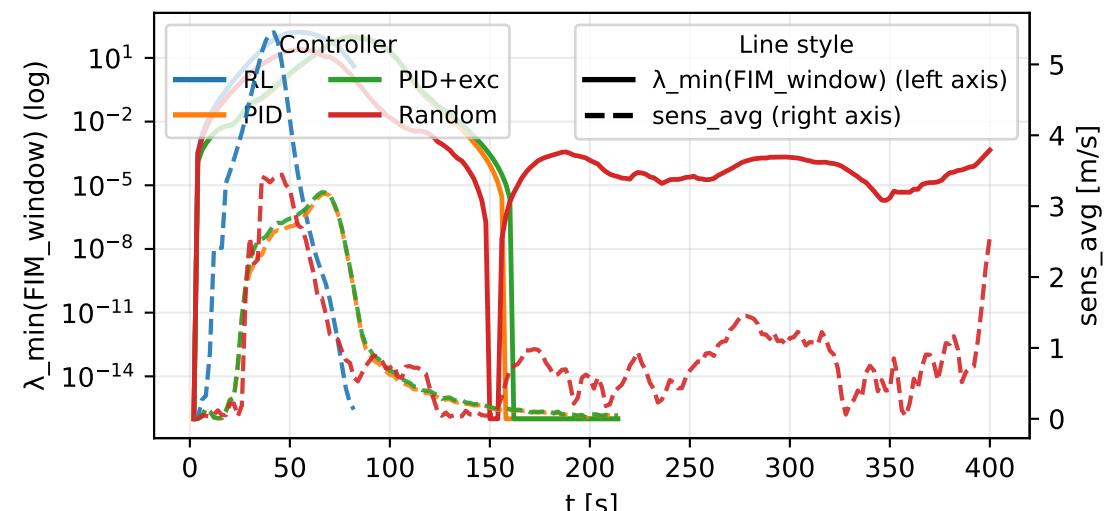
TRUE formation error



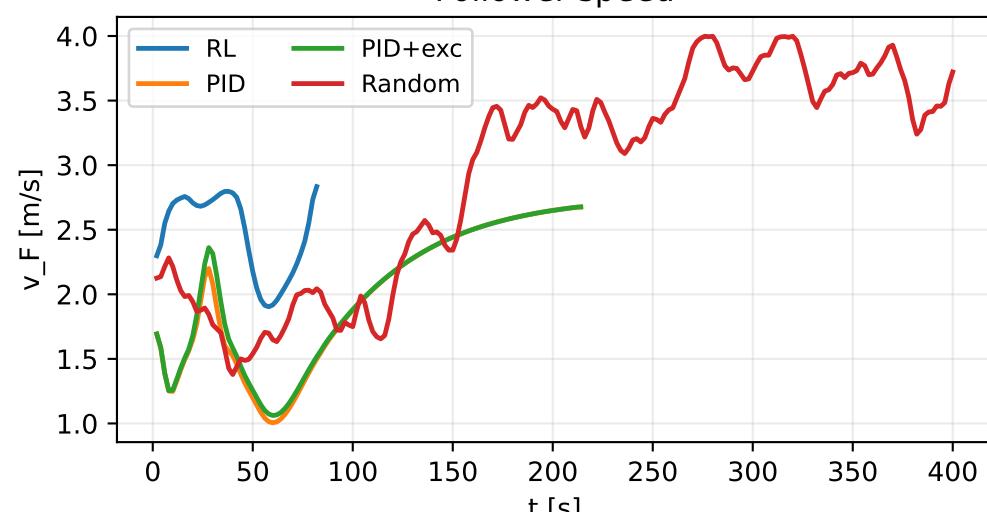
Estimator uncertainty (std_max)



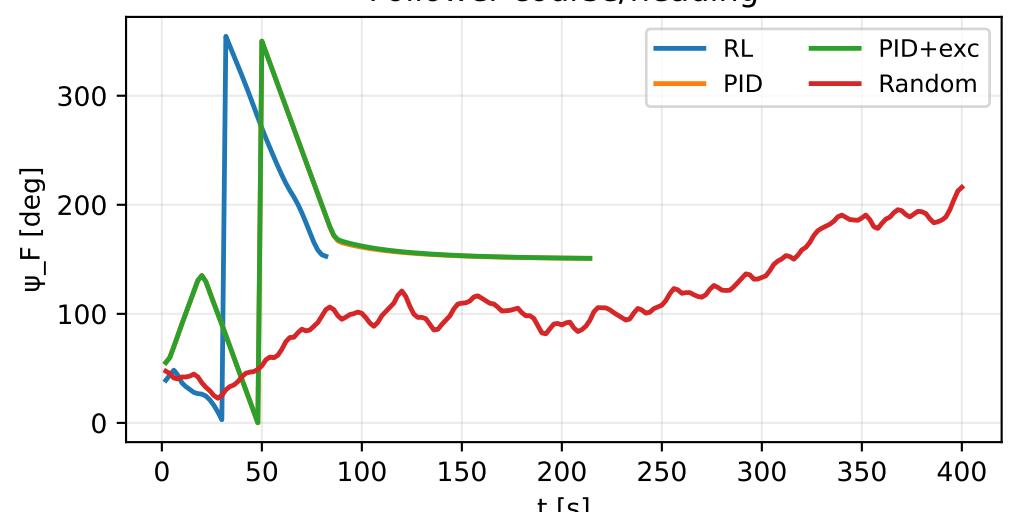
Information and excitation



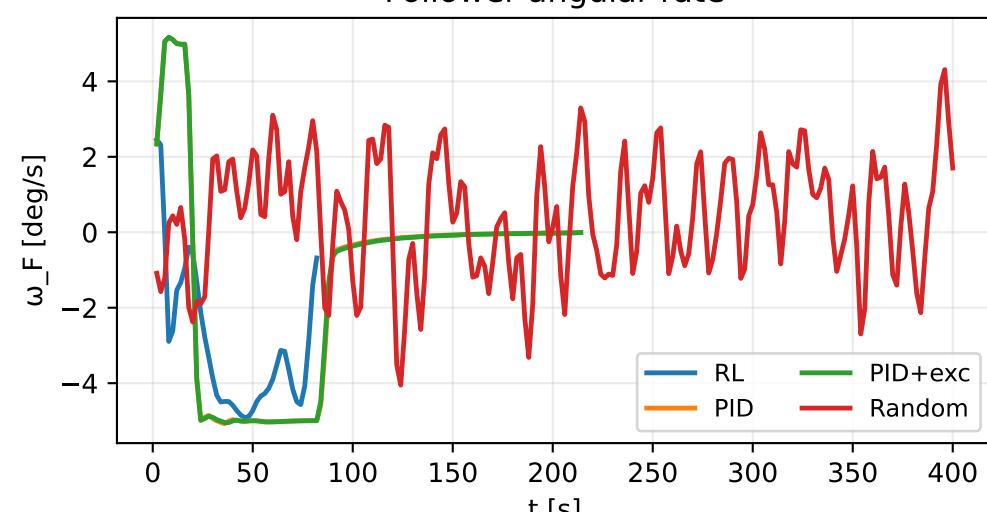
Follower speed



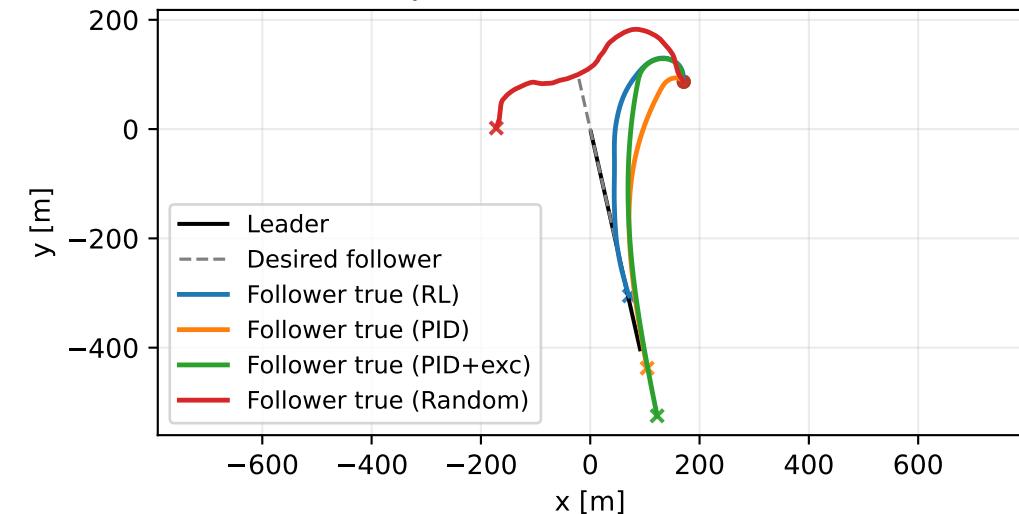
Follower course/heading



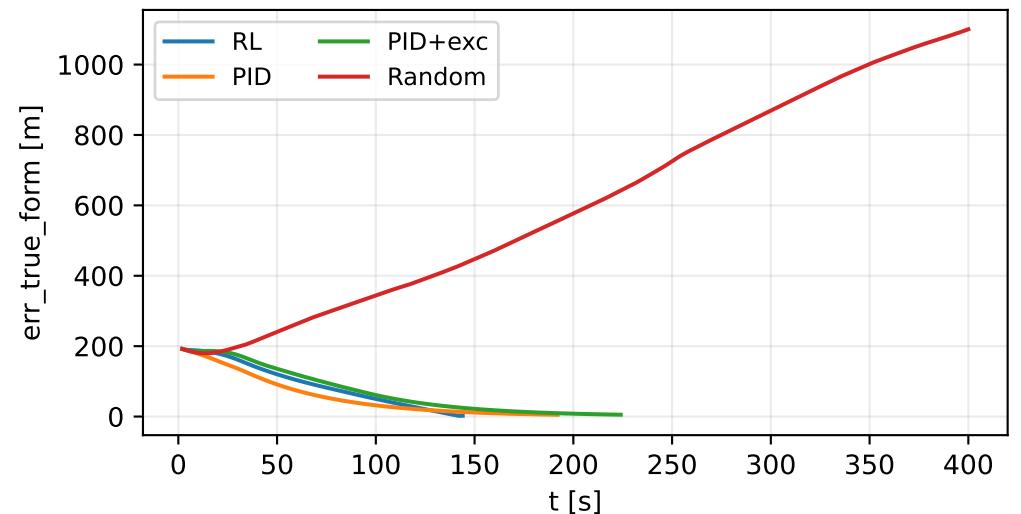
Follower angular rate



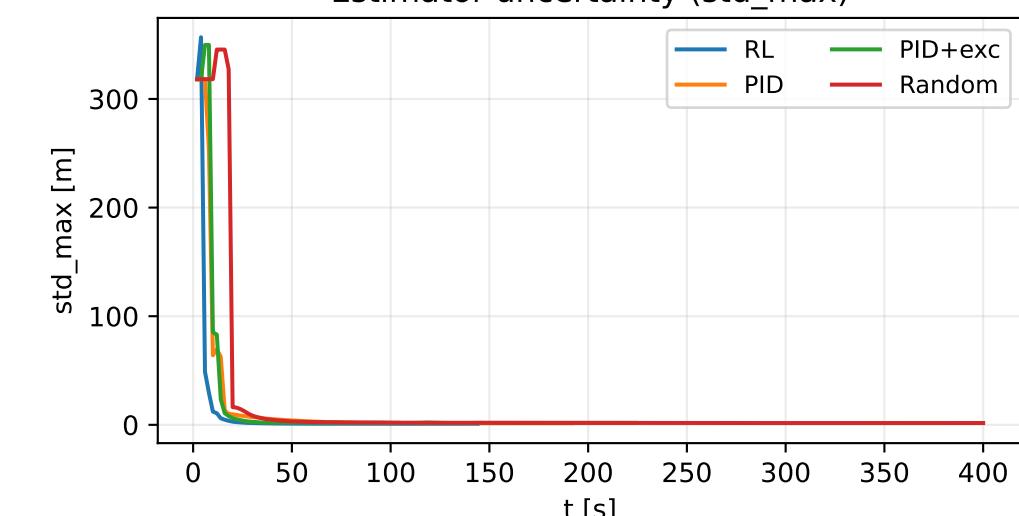
Trajectories (matched seed)



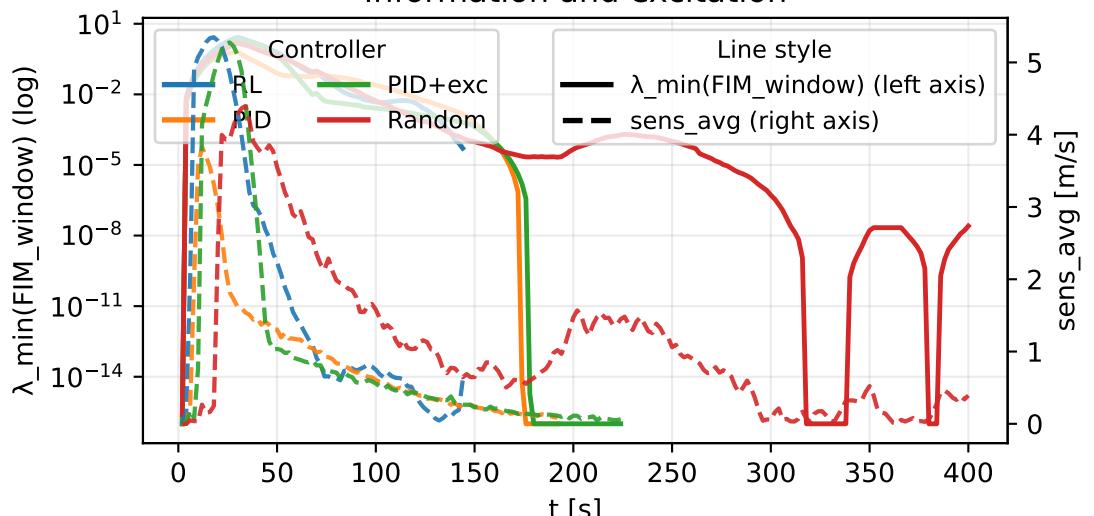
TRUE formation error



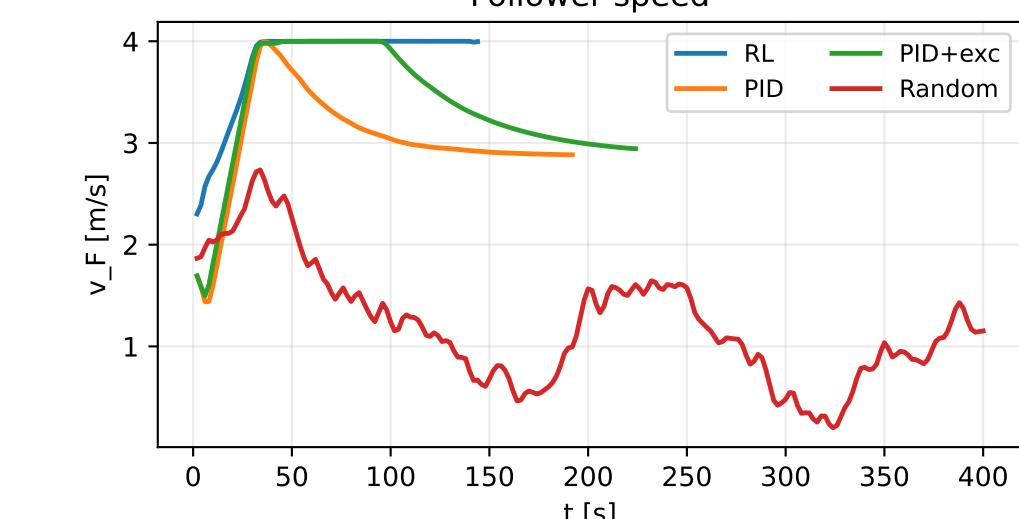
Estimator uncertainty (std_max)



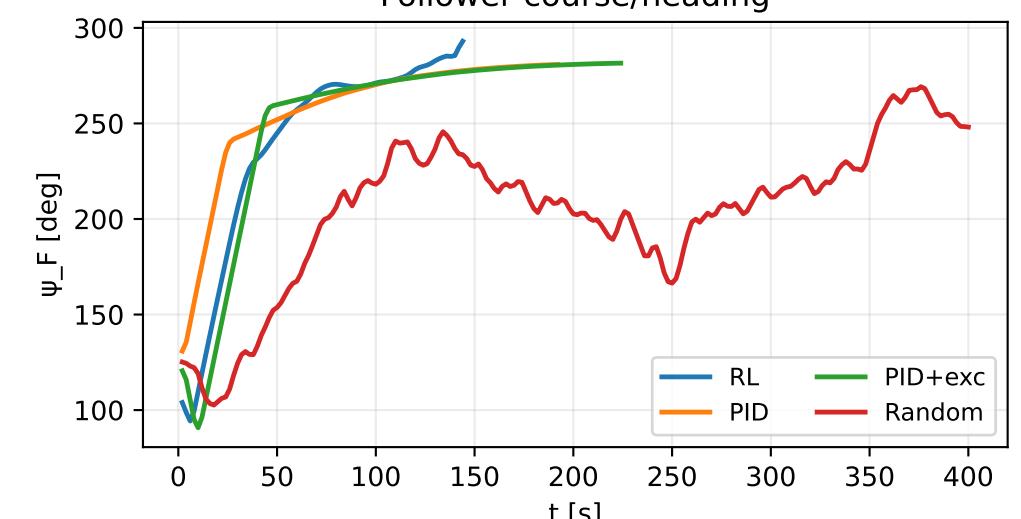
Information and excitation



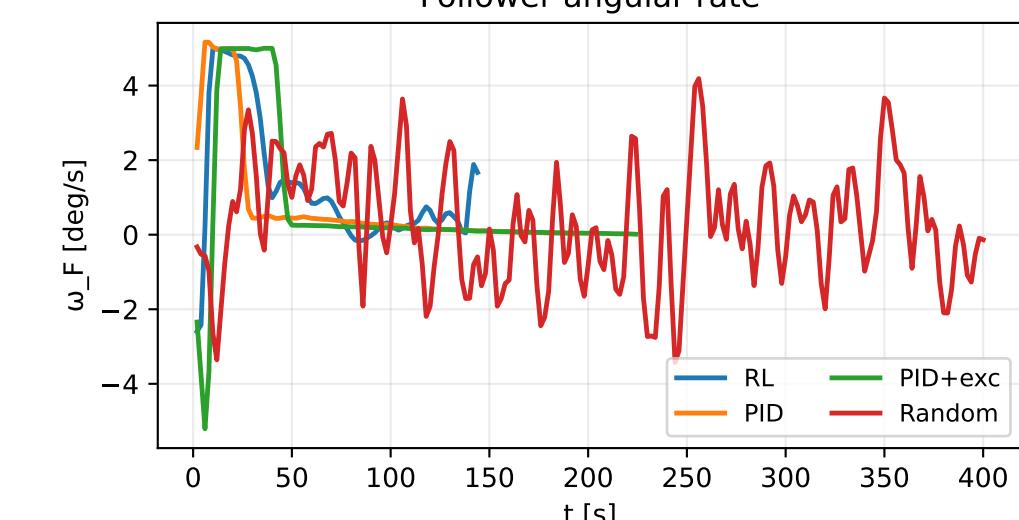
Follower speed



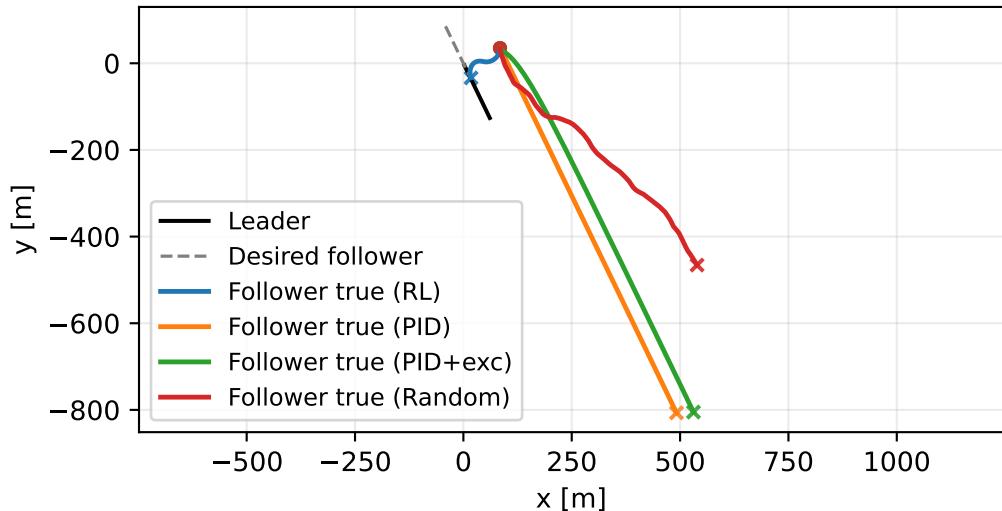
Follower course/heading



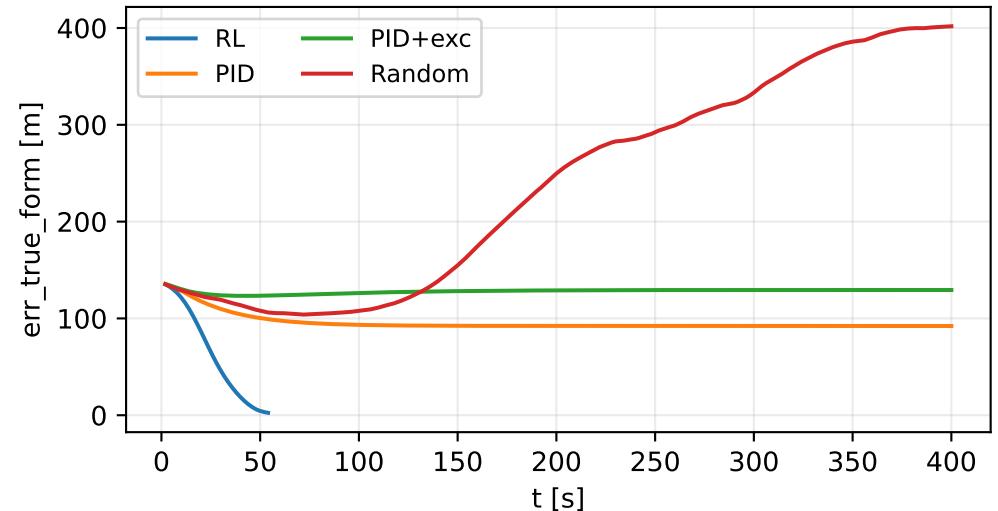
Follower angular rate



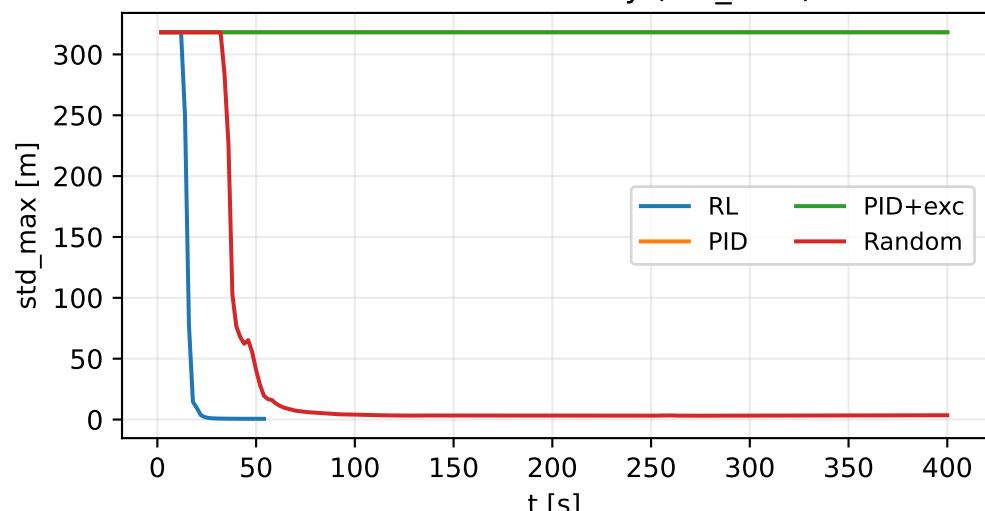
Trajectories (matched seed)



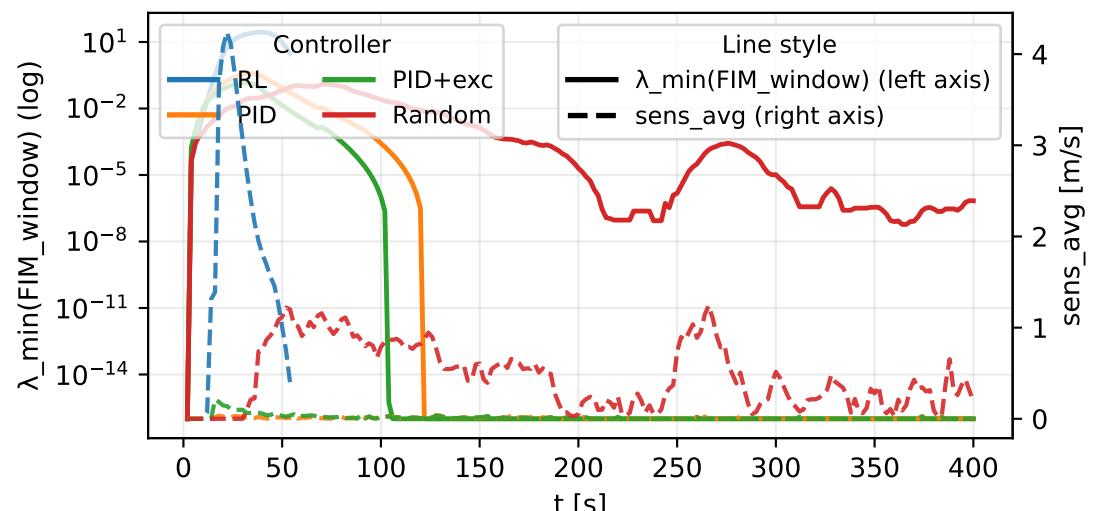
TRUE formation error



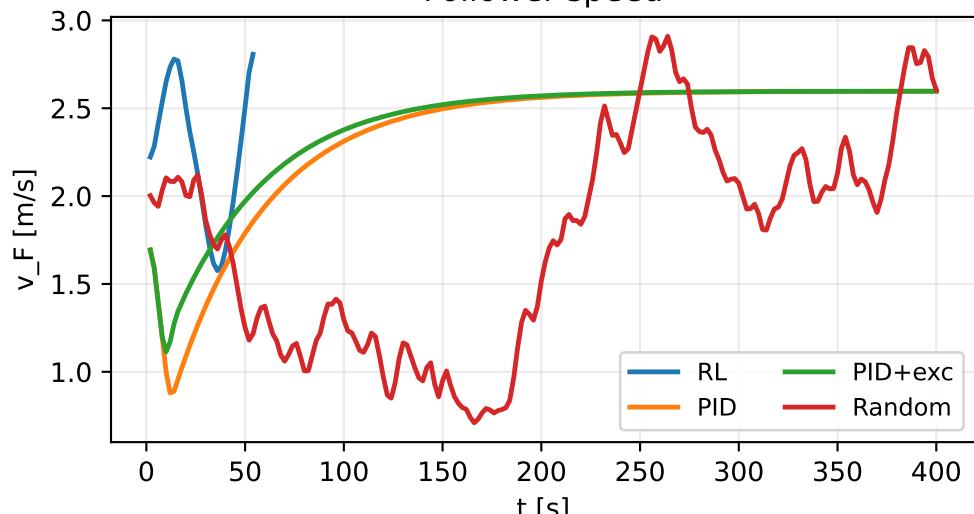
Estimator uncertainty (std_max)



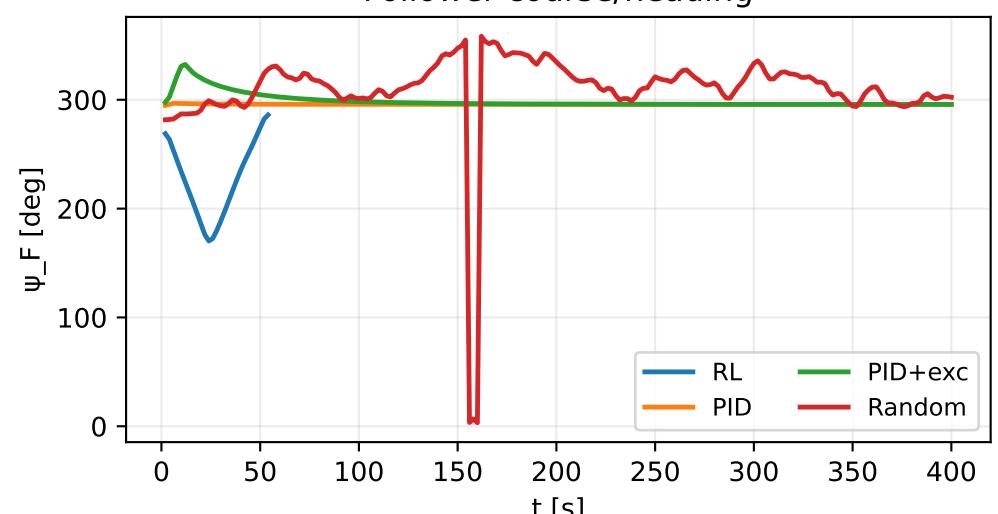
Information and excitation



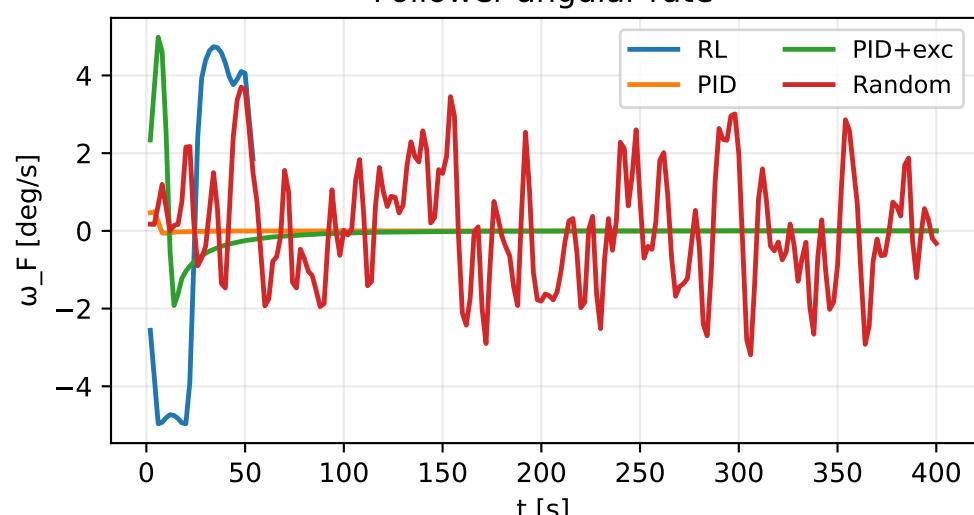
Follower speed



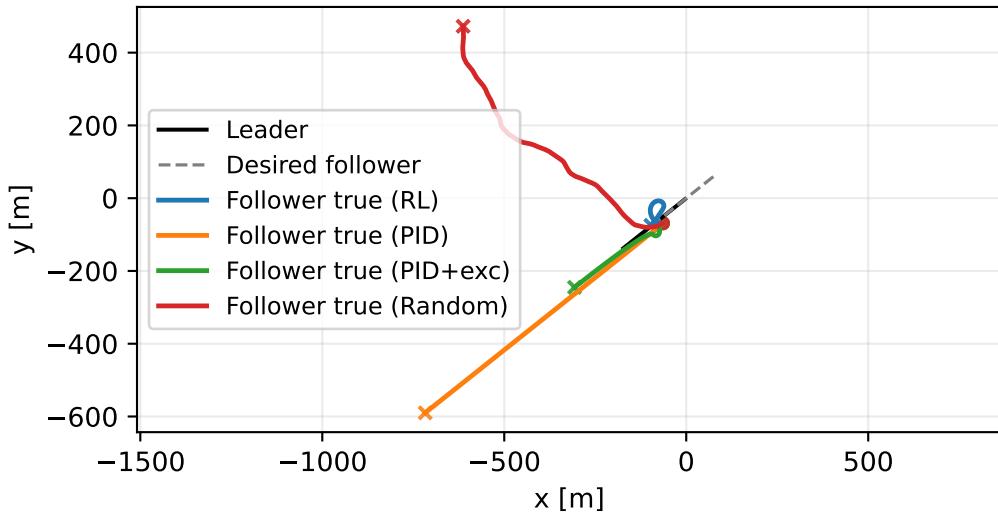
Follower course/heading



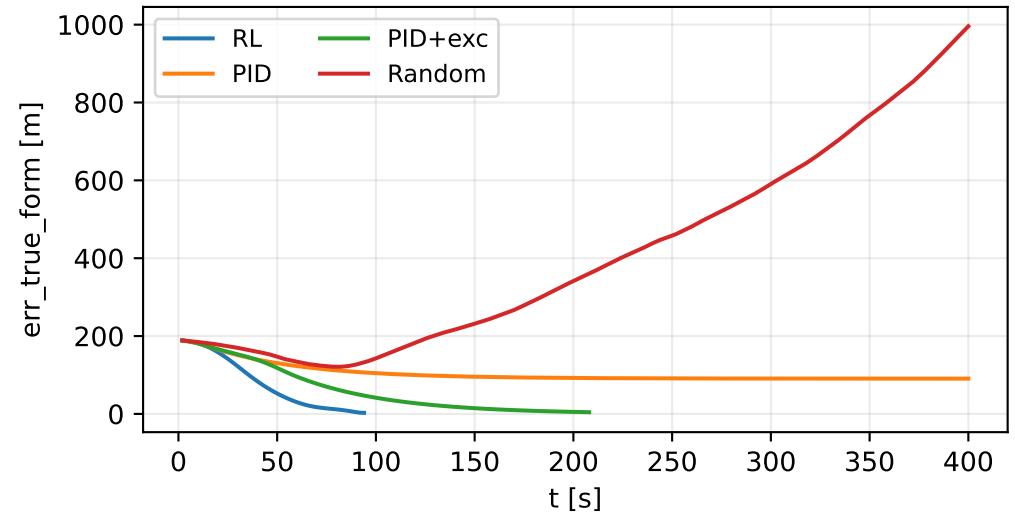
Follower angular rate



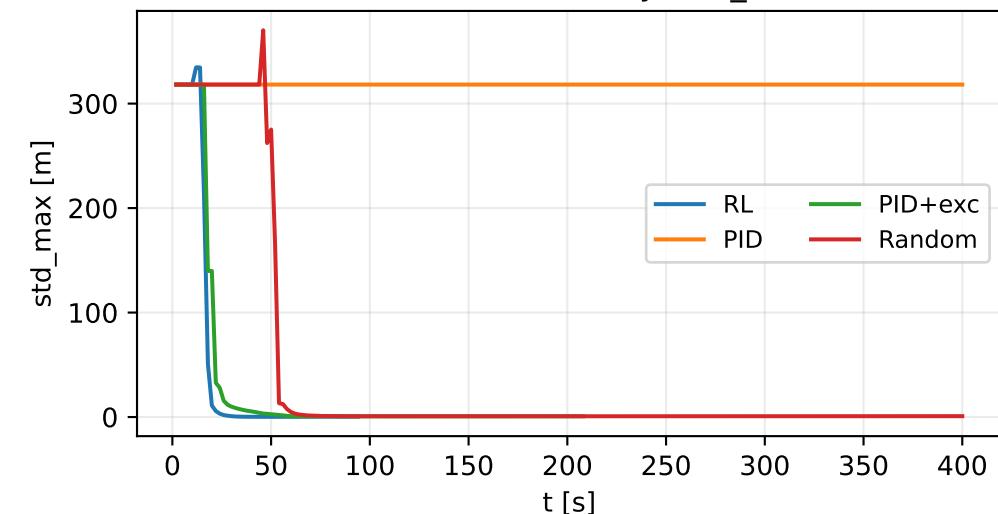
Trajectories (matched seed)



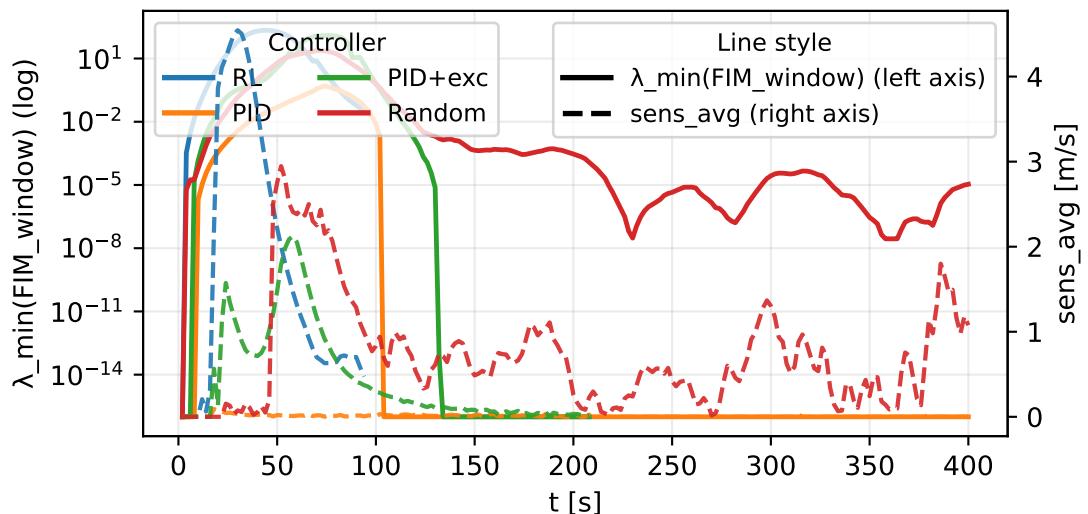
TRUE formation error



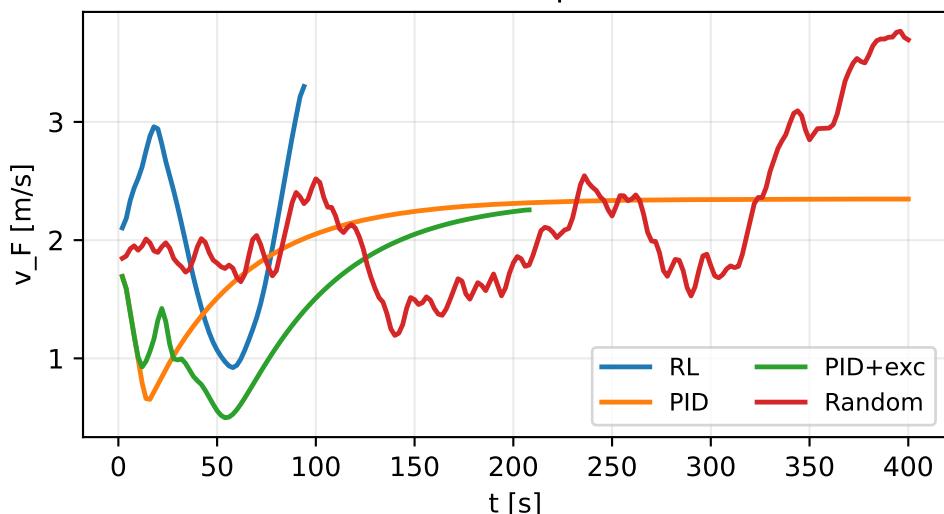
Estimator uncertainty (std_max)



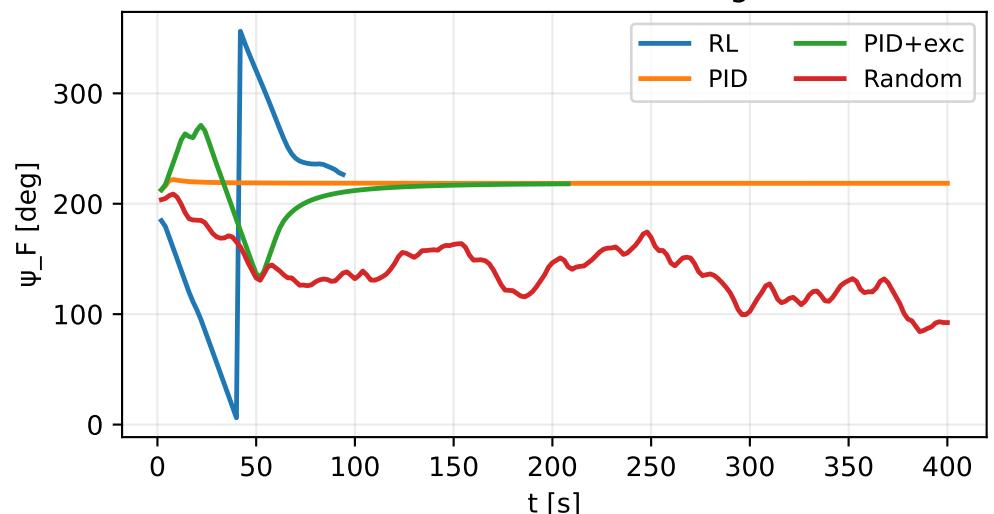
Information and excitation



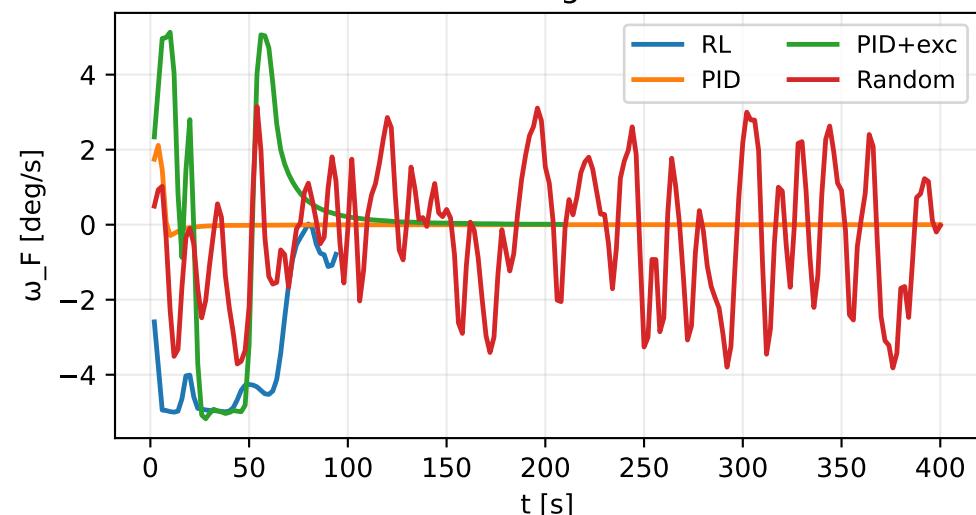
Follower speed



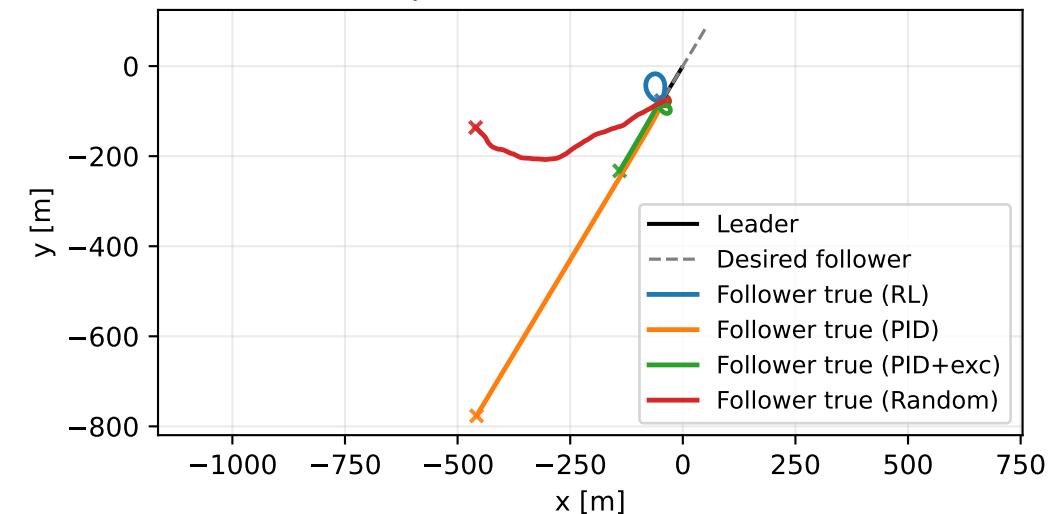
Follower course/heading



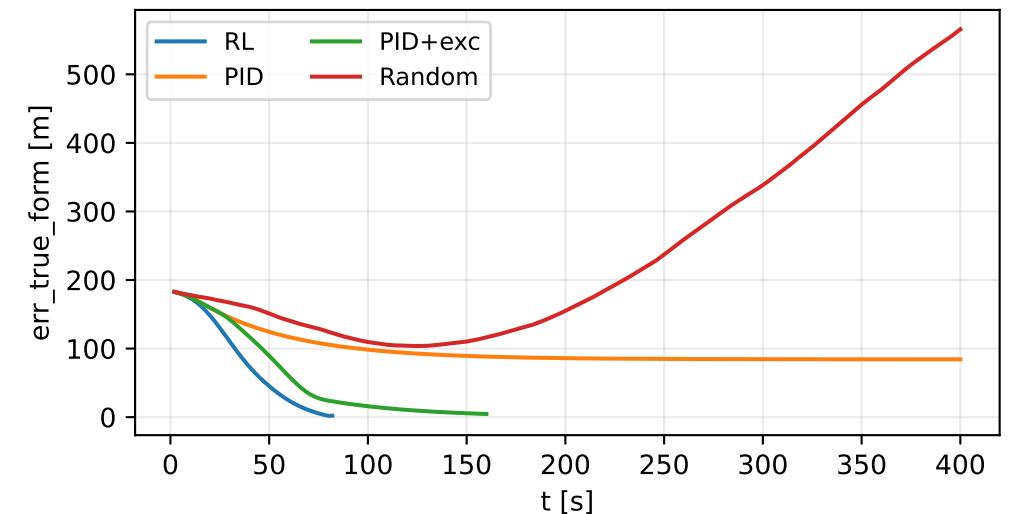
Follower angular rate



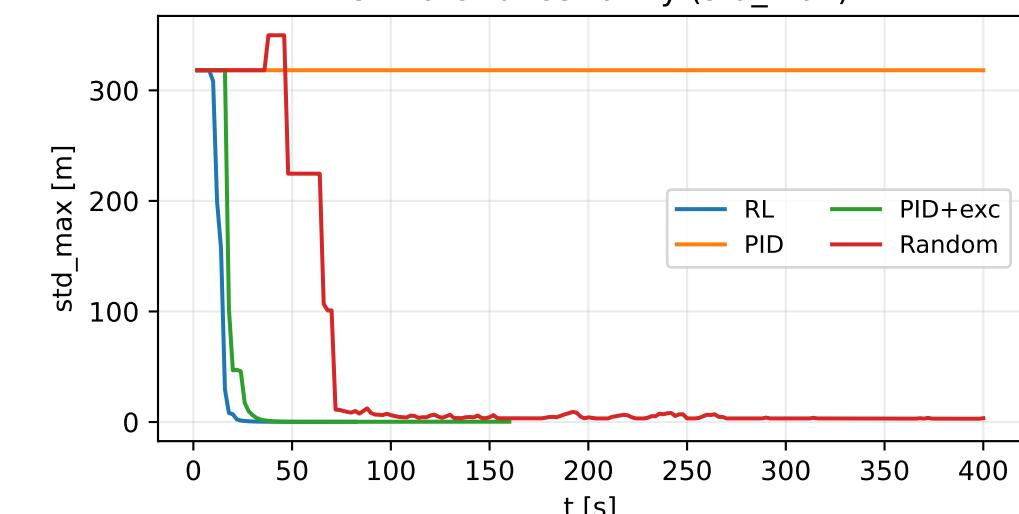
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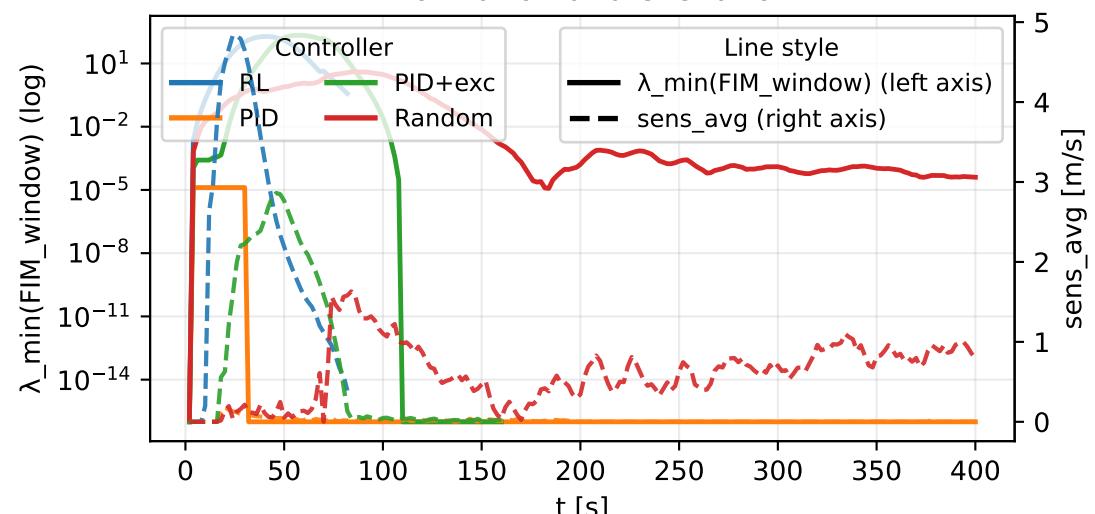
TRUE formation error



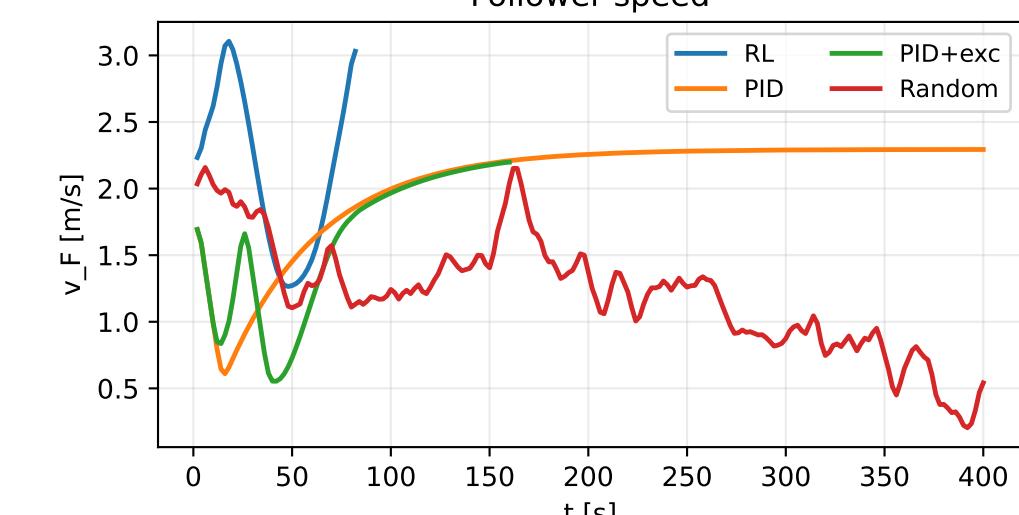
Estimator uncertainty (std_max)



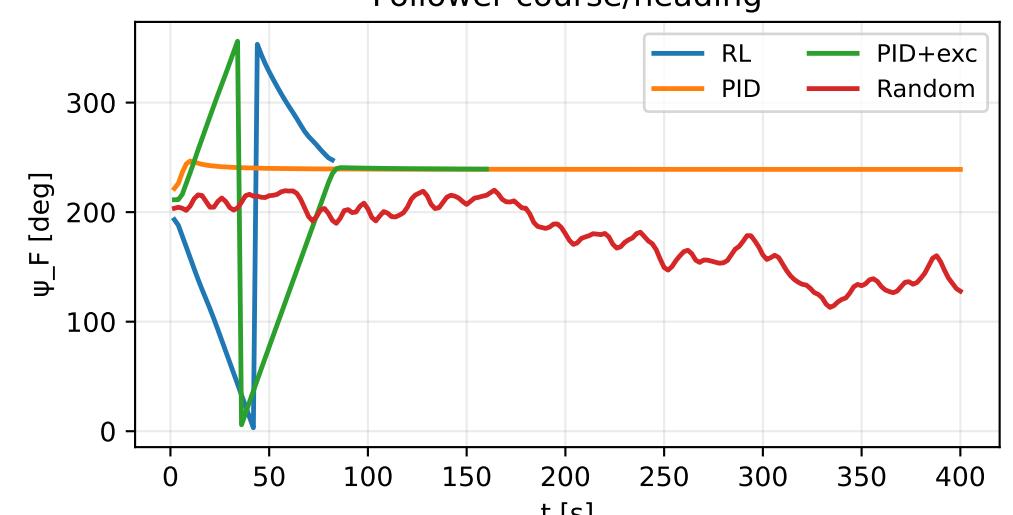
Information and excitation



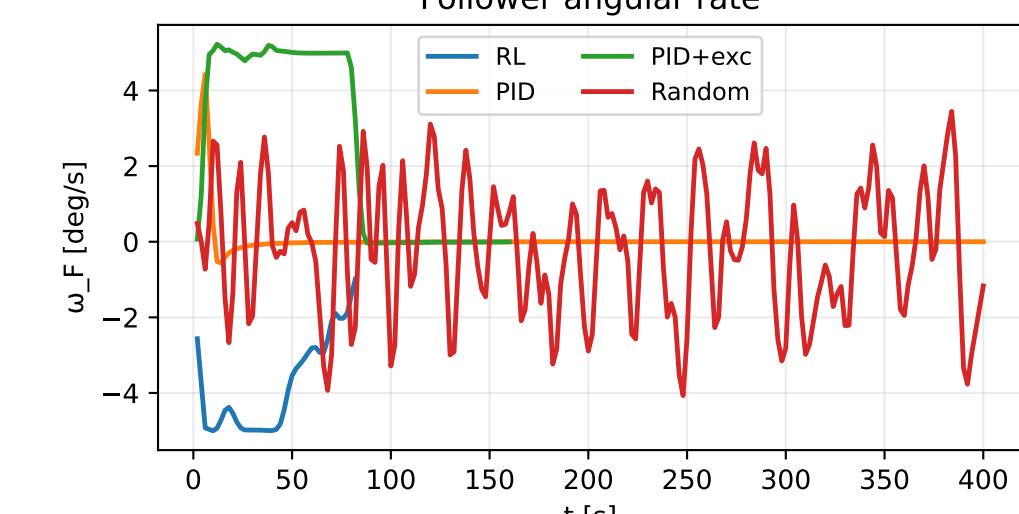
Follower speed



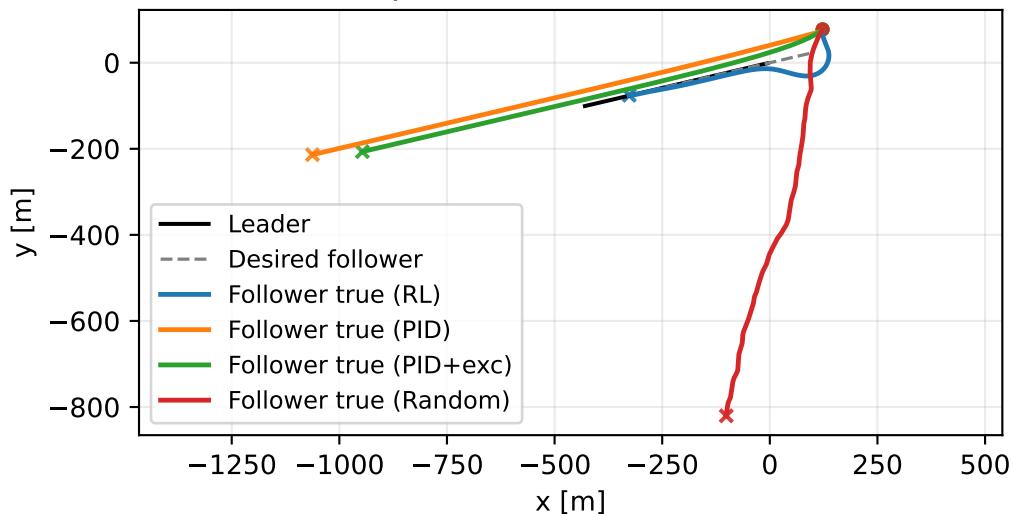
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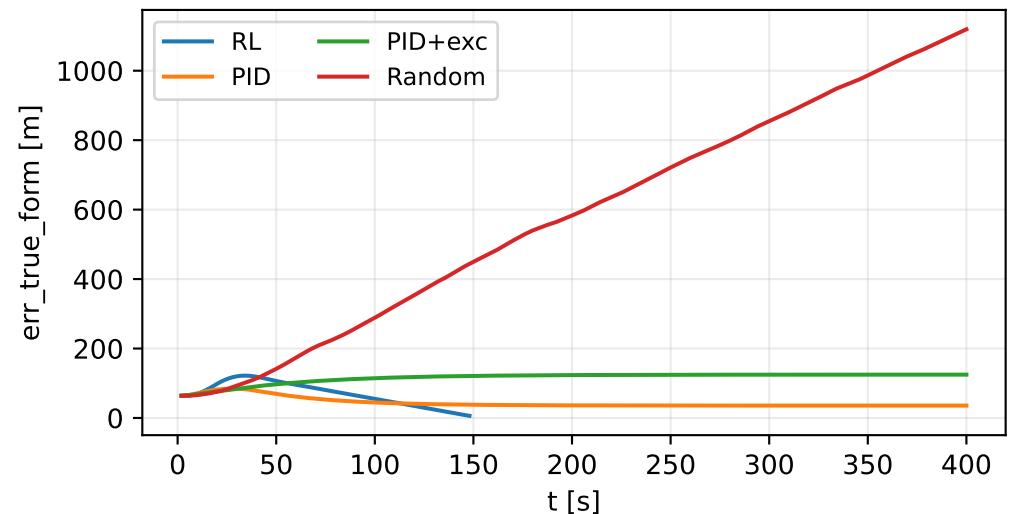
Follower angular rate



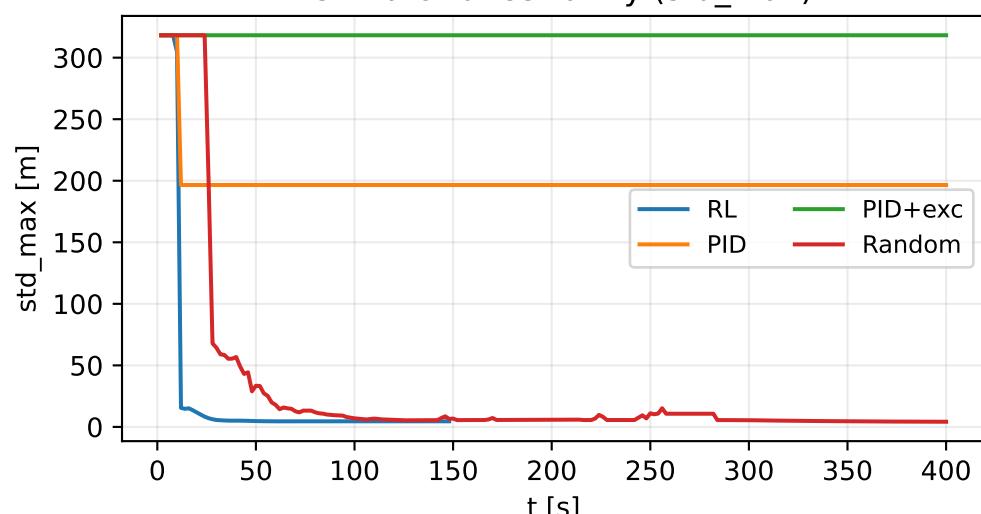
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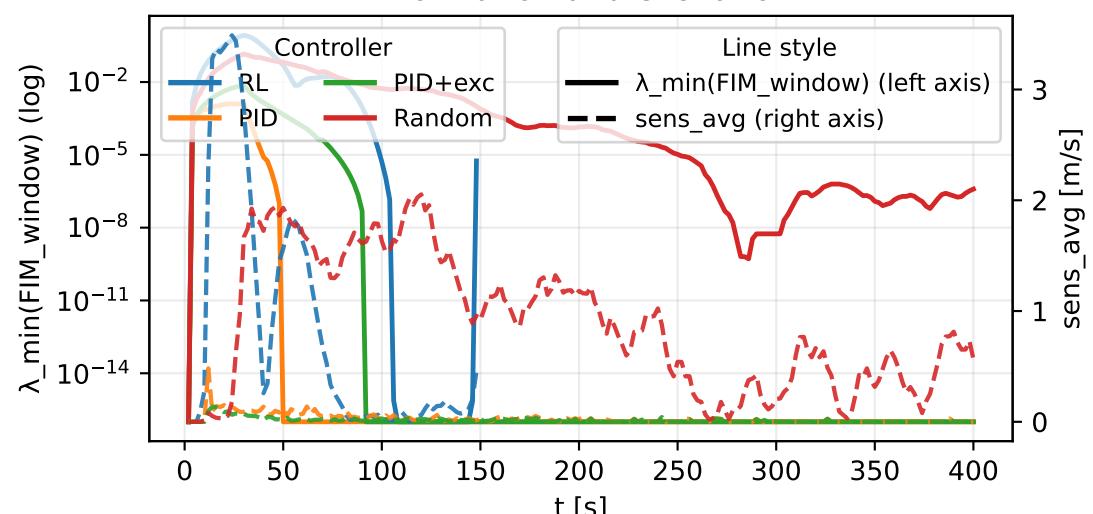
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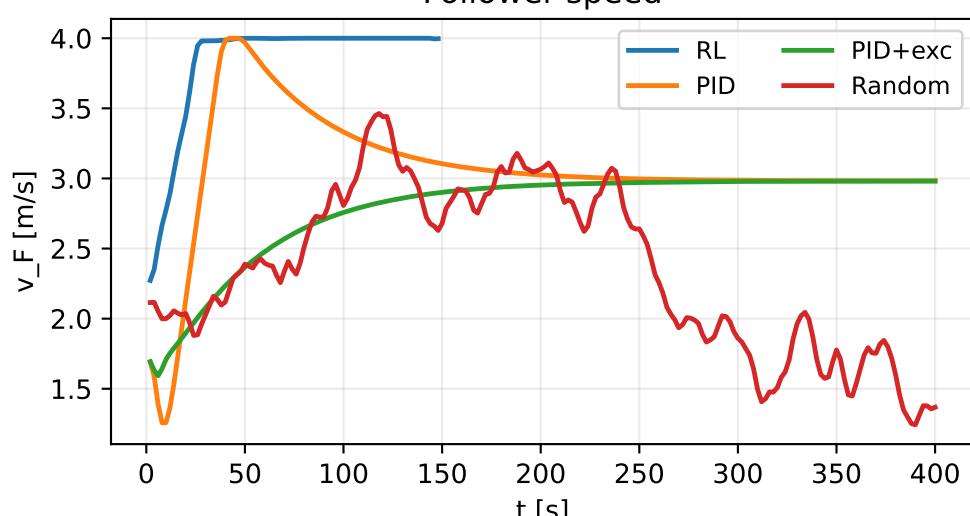
Estimator uncertainty (std_max)



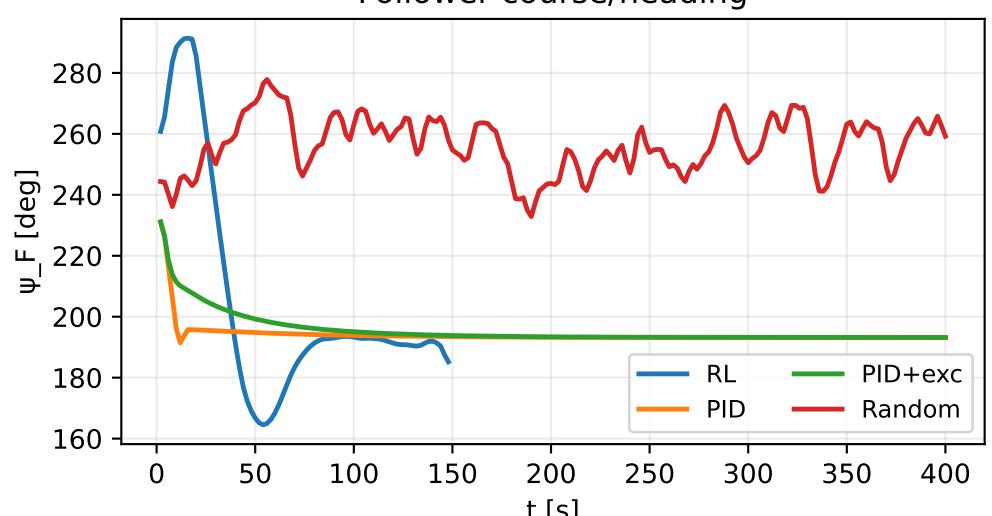
Information and excitation



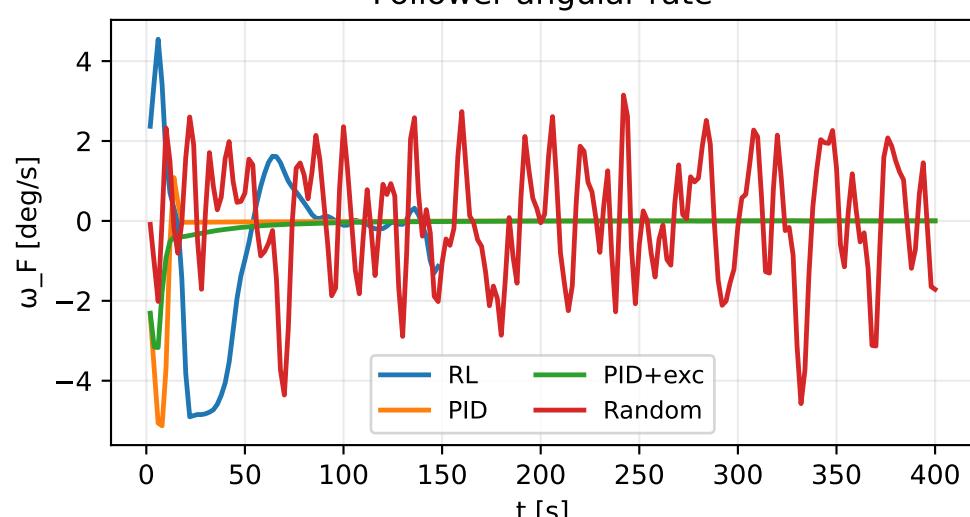
Follower speed



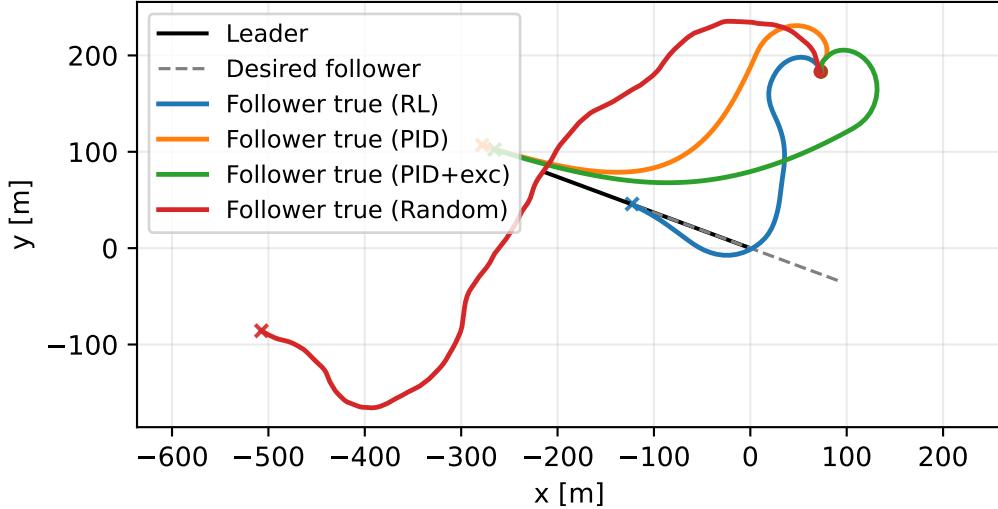
Follower course/heading



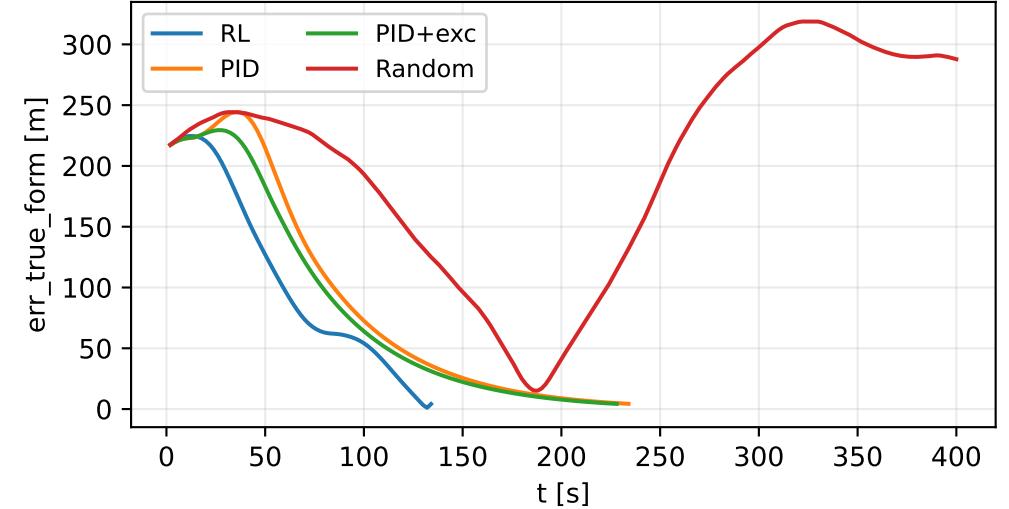
Follower angular rate



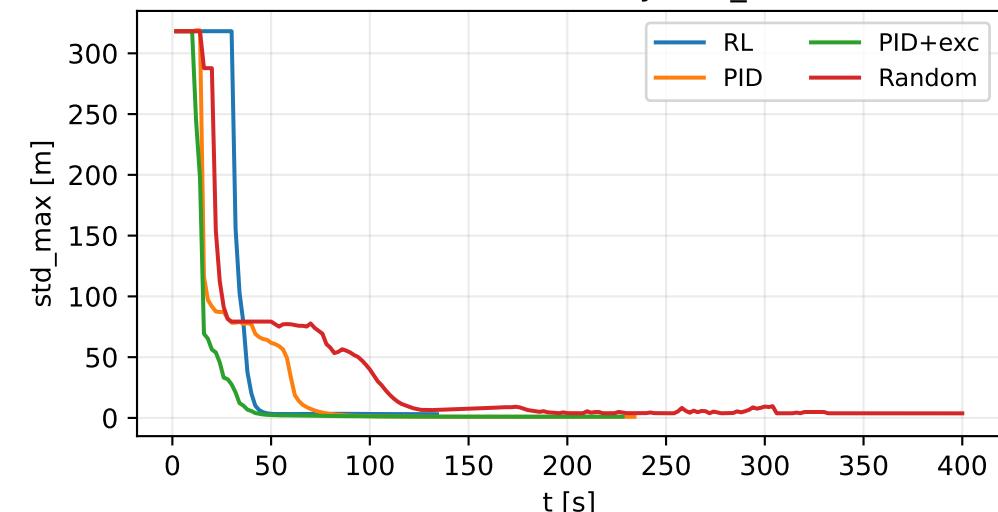
Trajectories (matched seed)



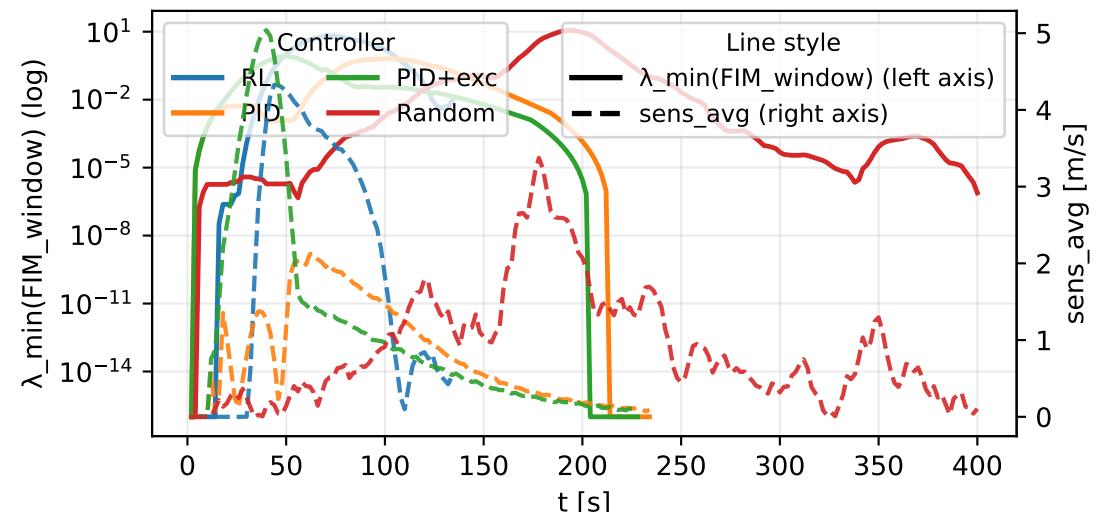
TRUE formation error



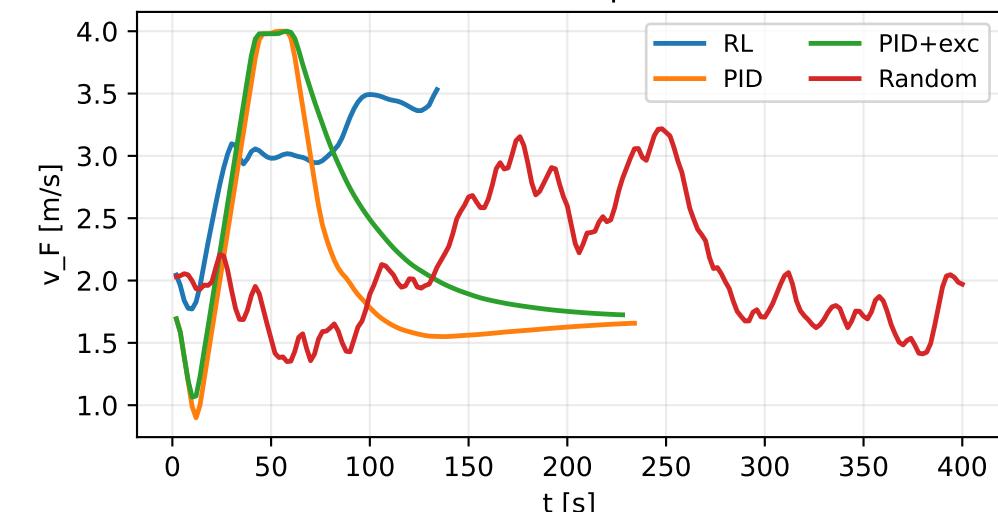
Estimator uncertainty (std_max)



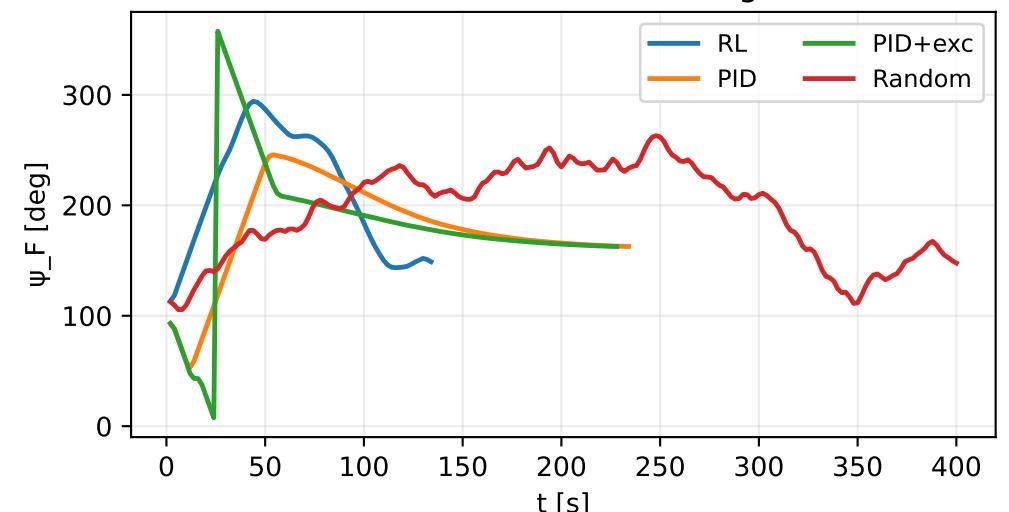
Information and excitation



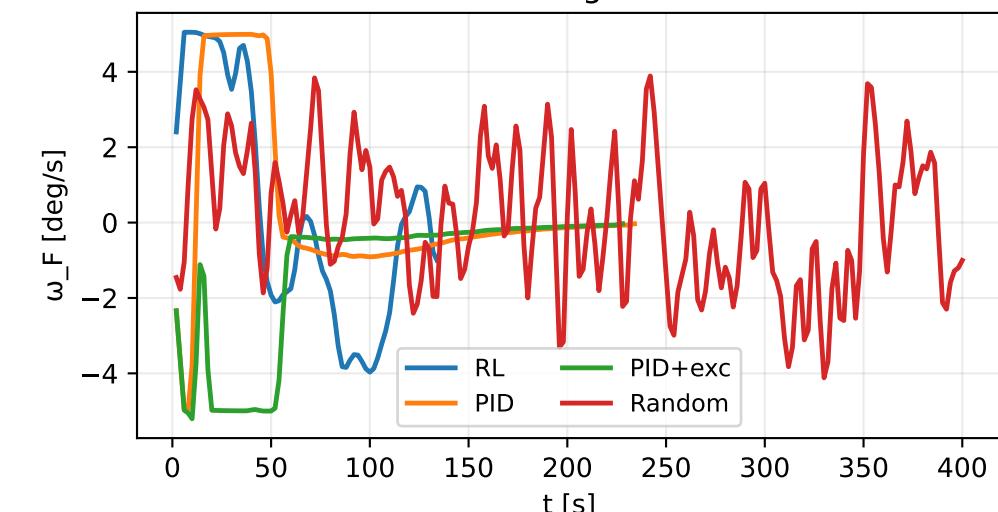
Follower speed



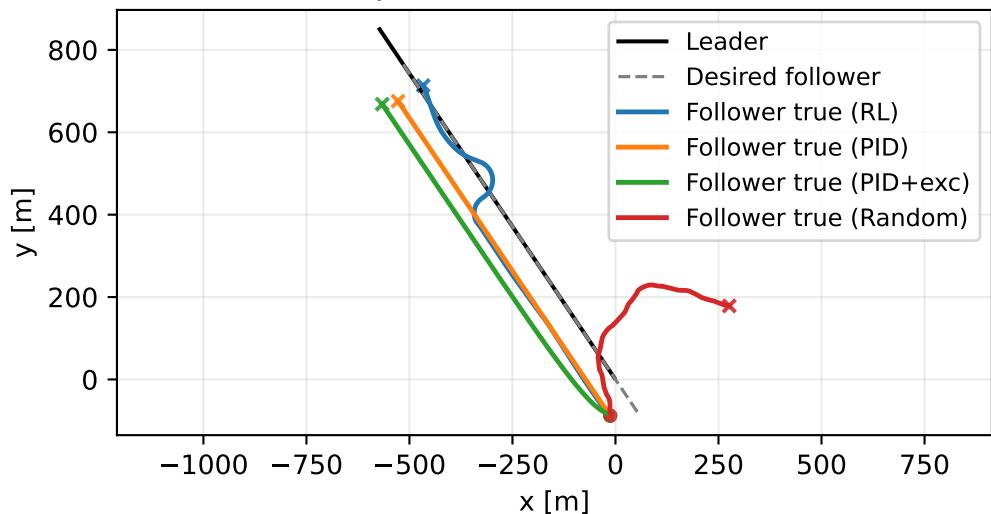
Follower course/heading



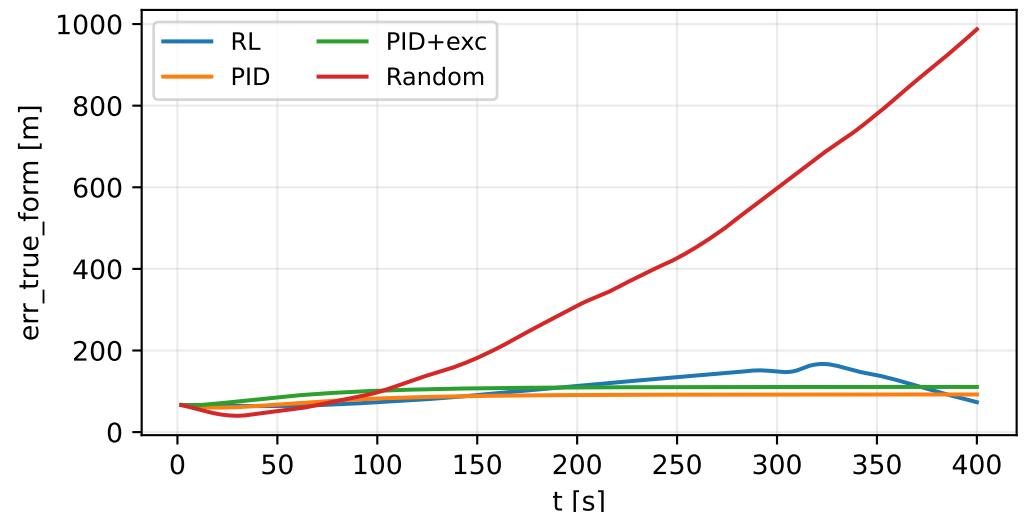
Follower angular rate



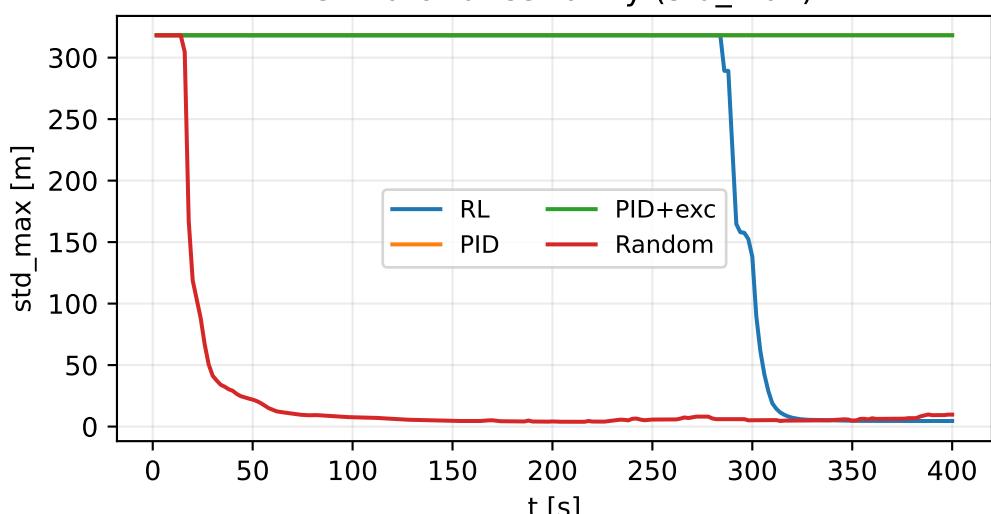
Trajectories (matched seed)



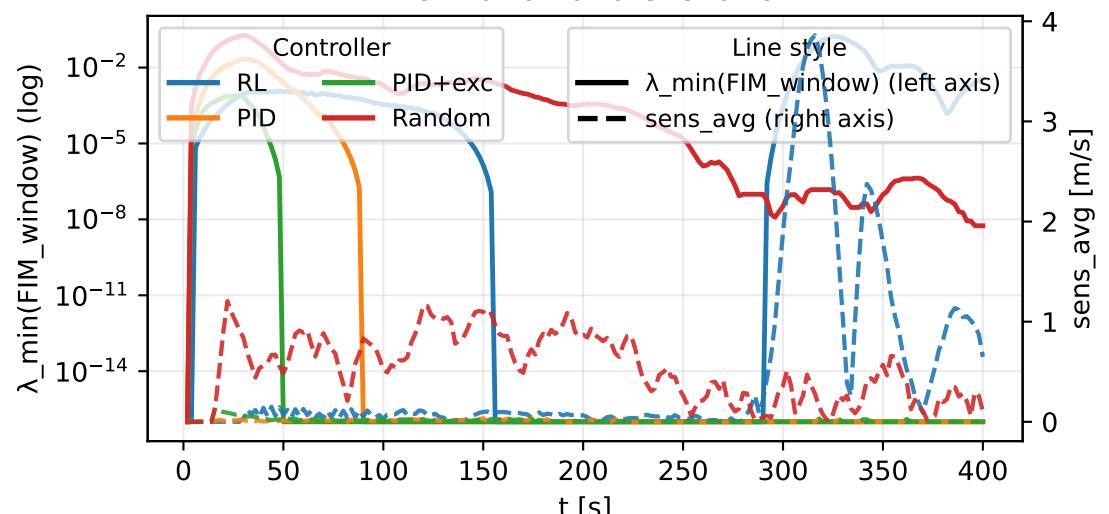
TRUE formation error



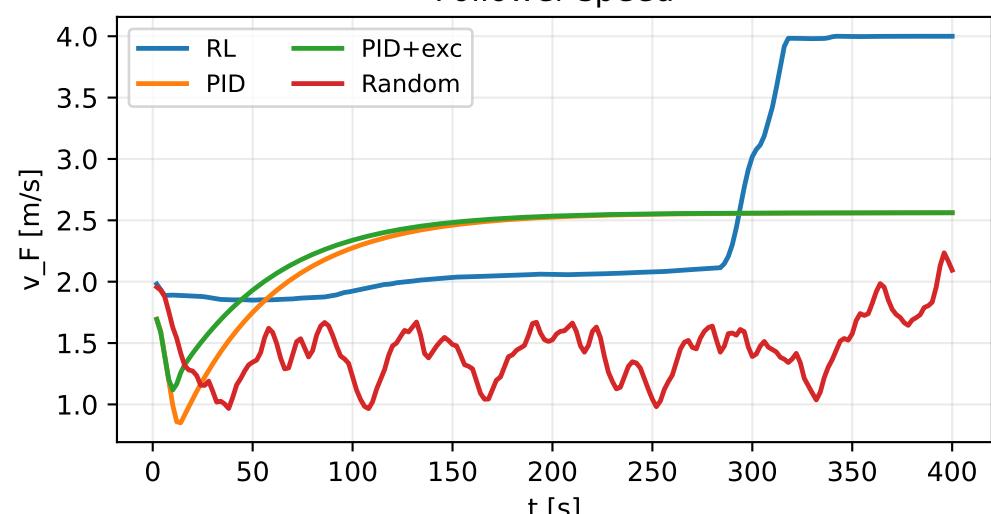
Estimator uncertainty (std_max)



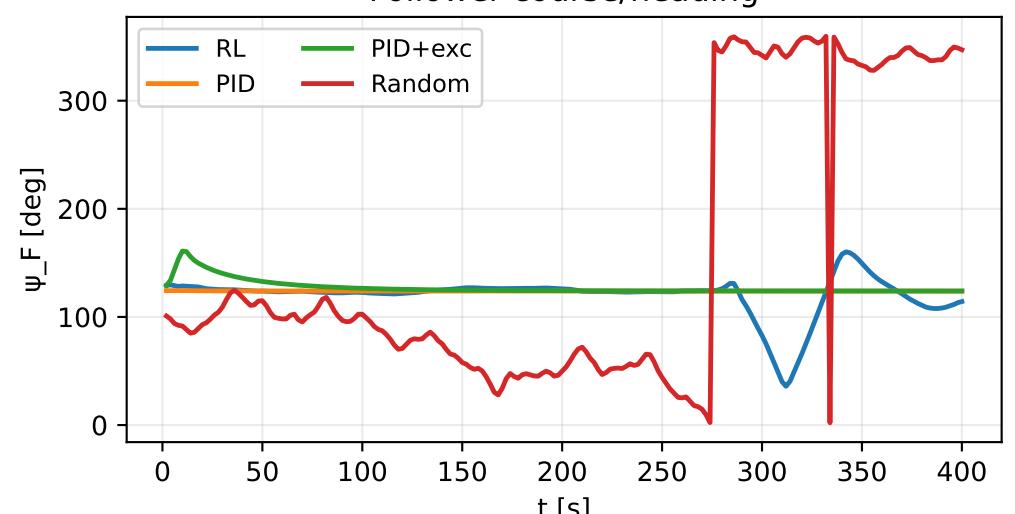
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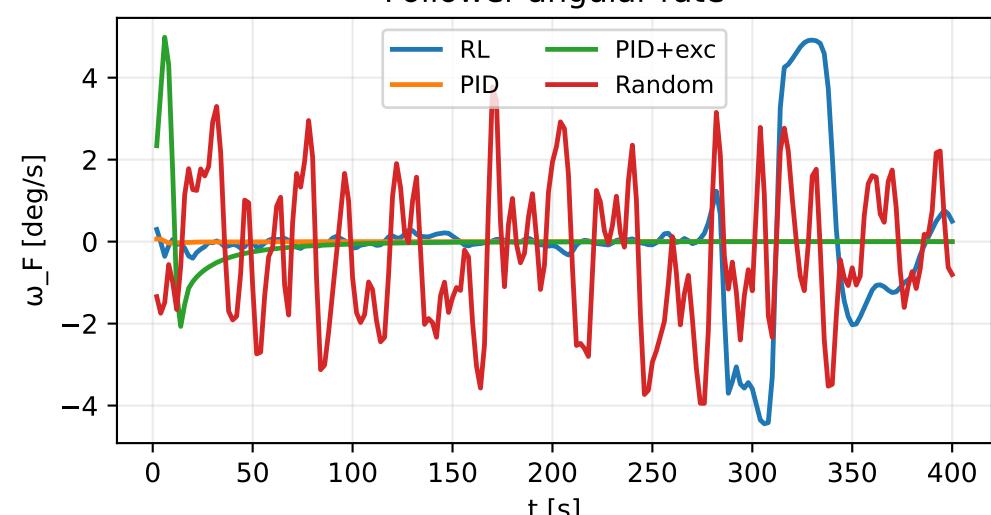
Follower speed



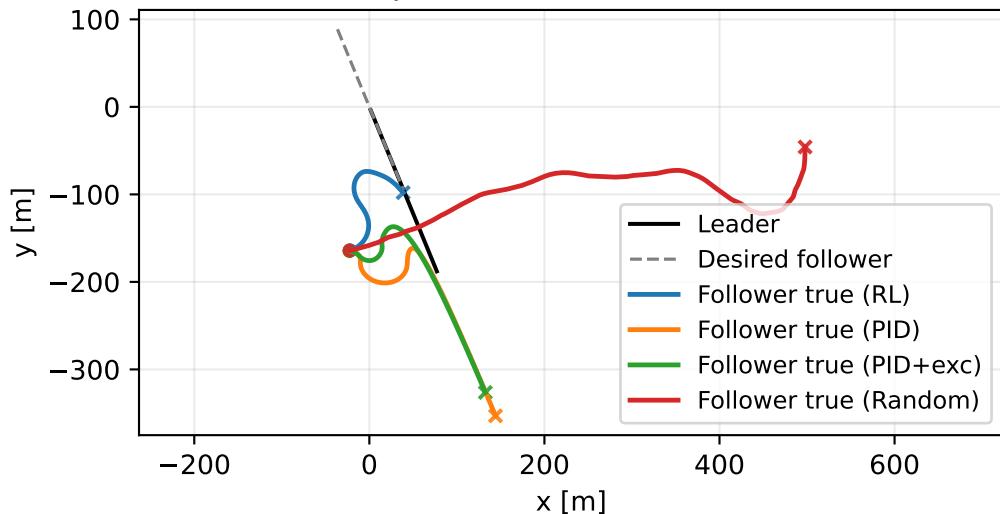
Follower course/heading



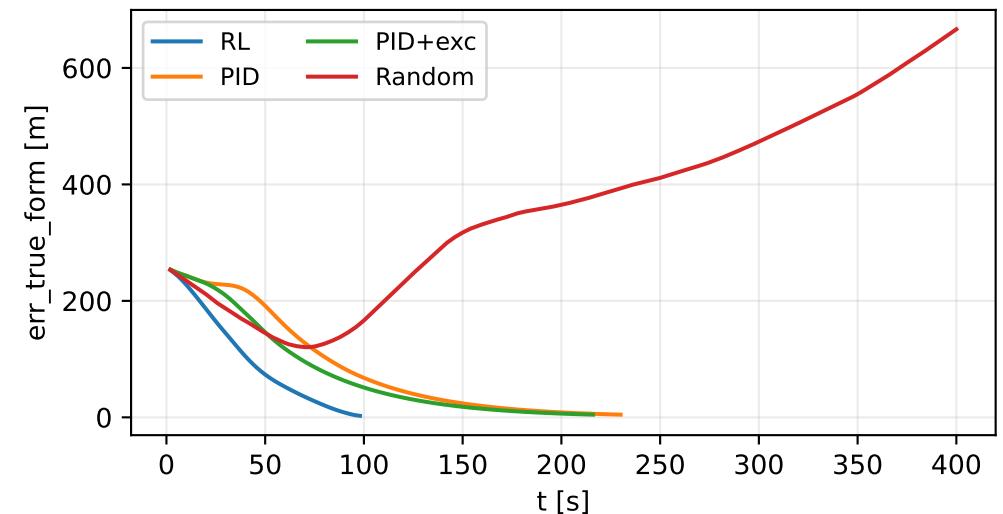
Follower angular rate



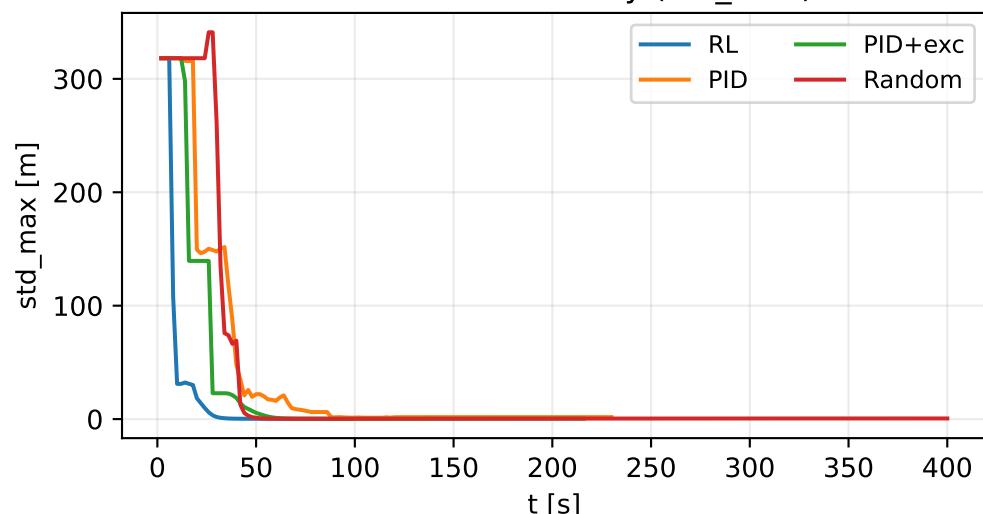
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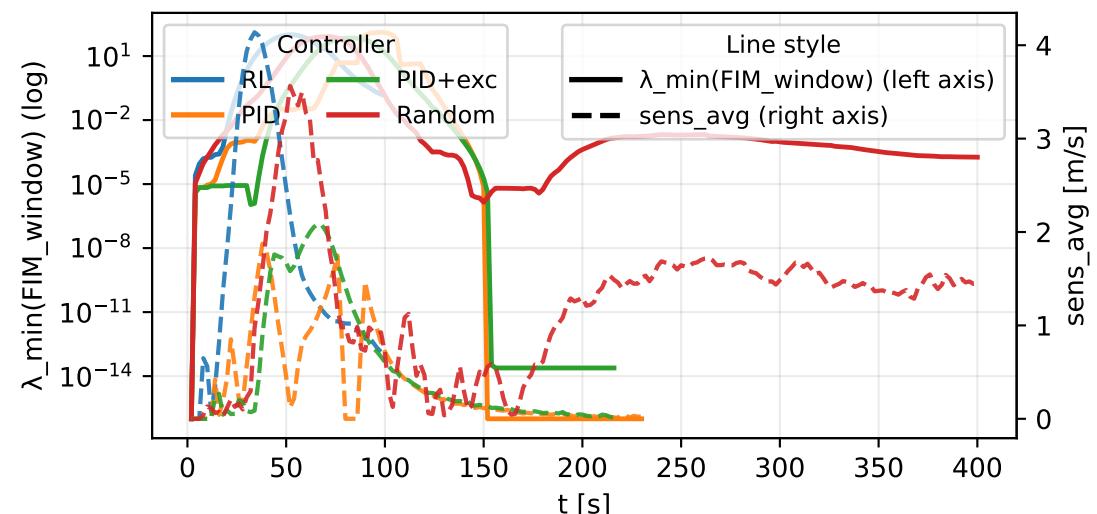
TRUE formation error



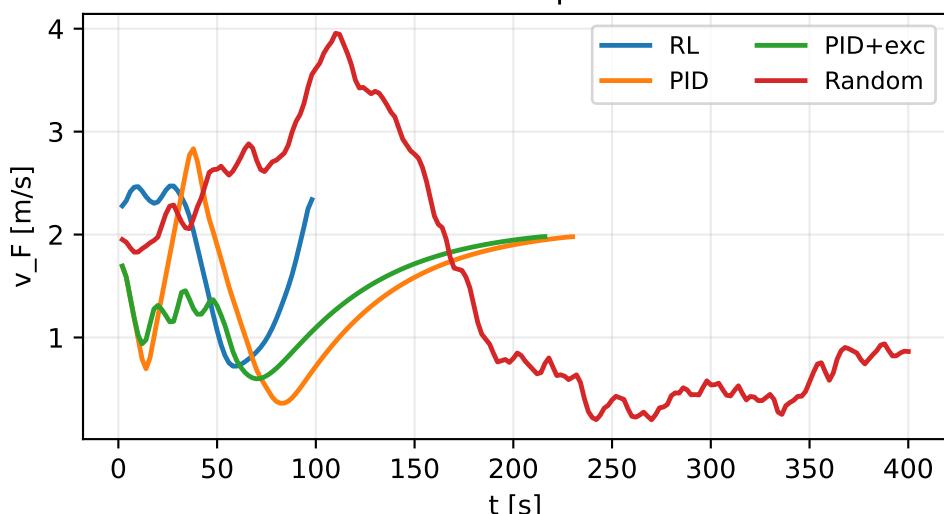
Estimator uncertainty (std_max)



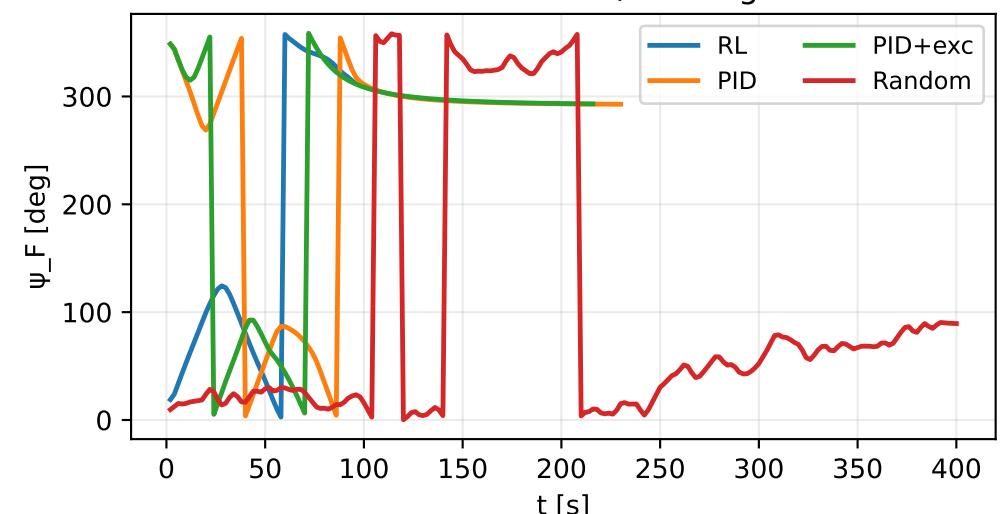
Information and excitation



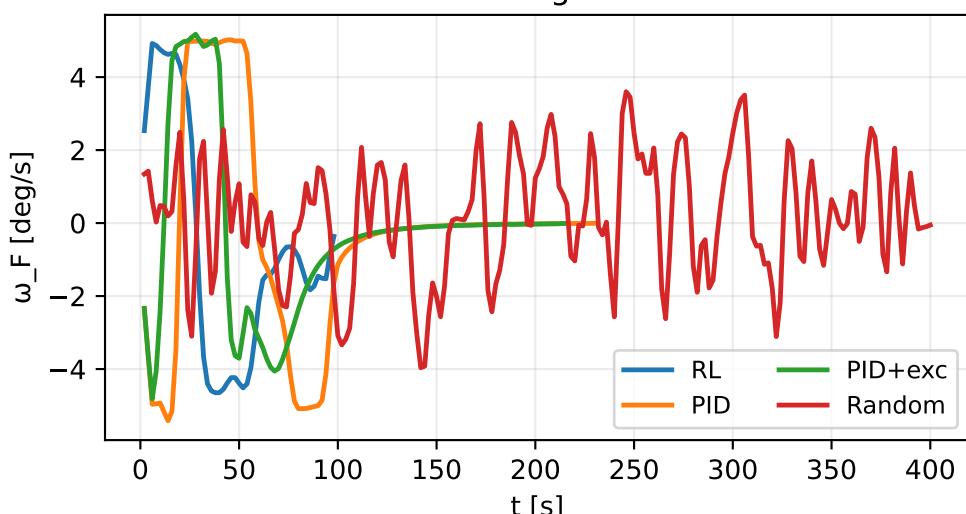
Follower speed



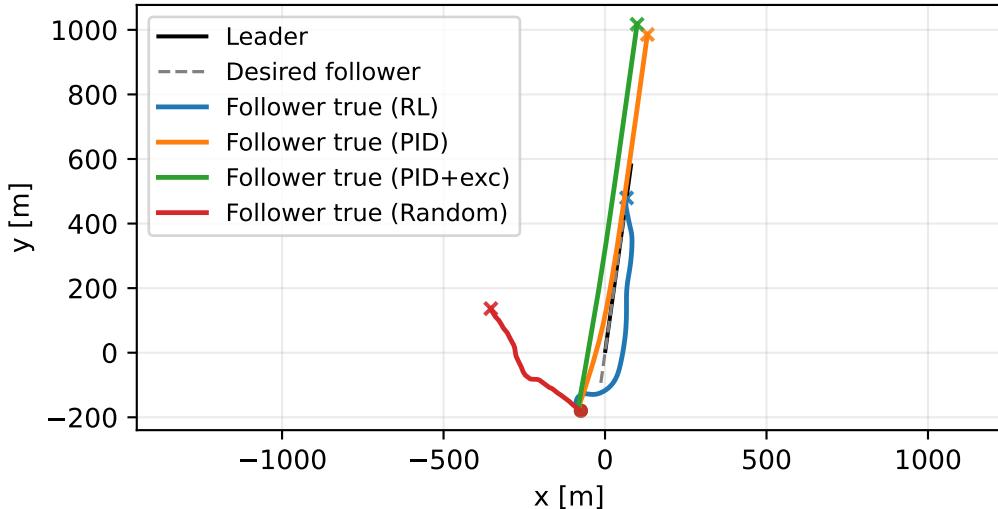
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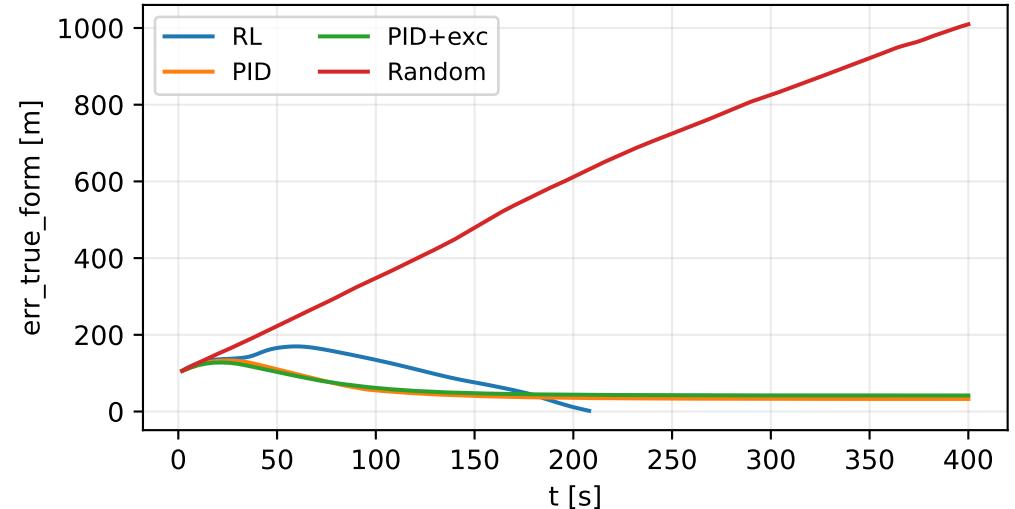
Follower angular rate



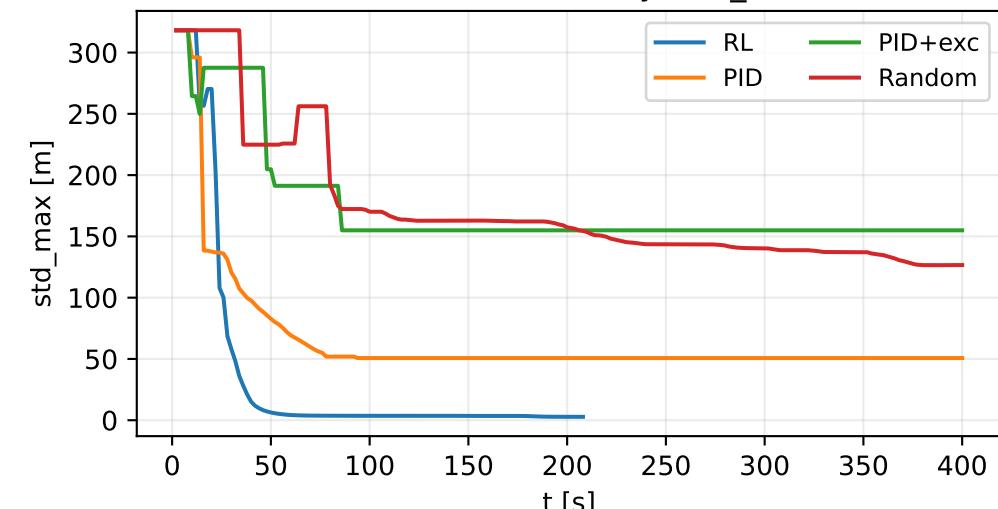
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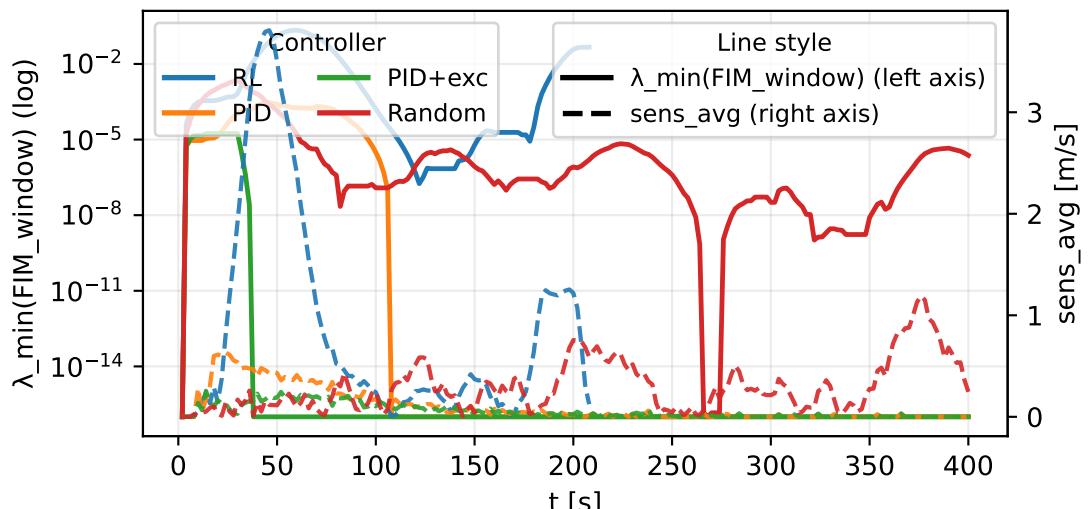
TRUE formation error



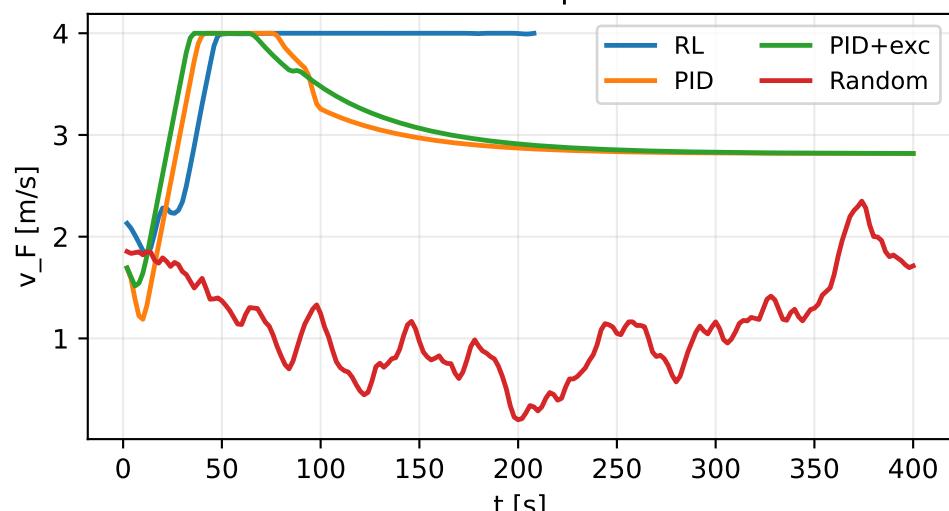
Estimator uncertainty (std_max)



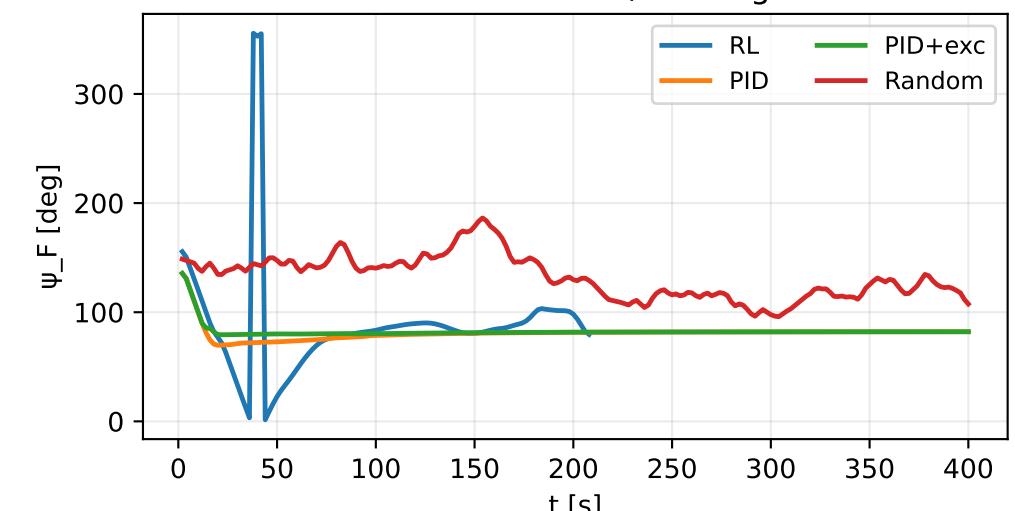
Information and excitation



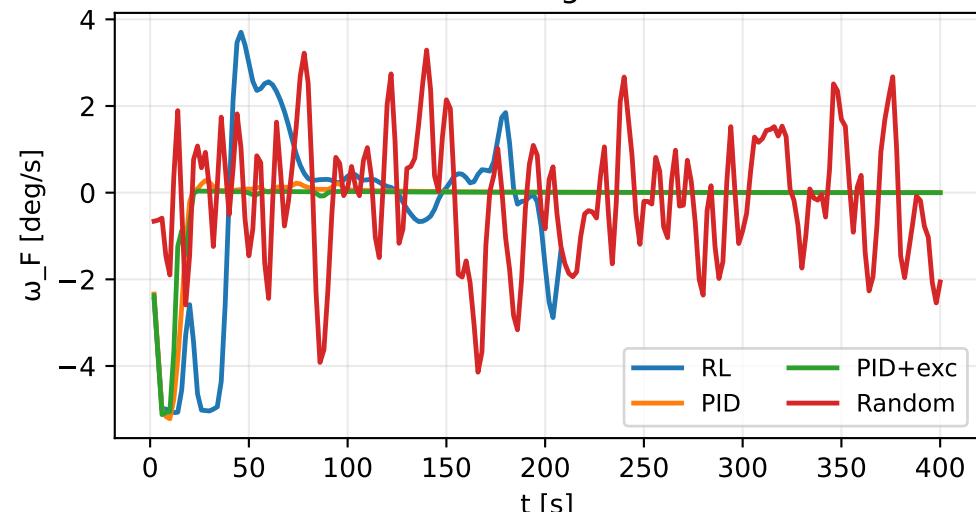
Follower speed



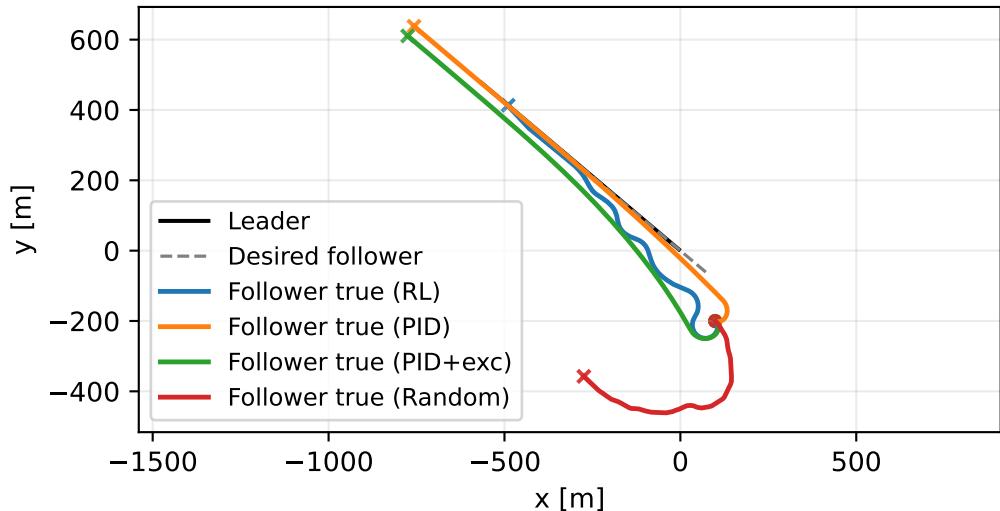
Follower course/heading



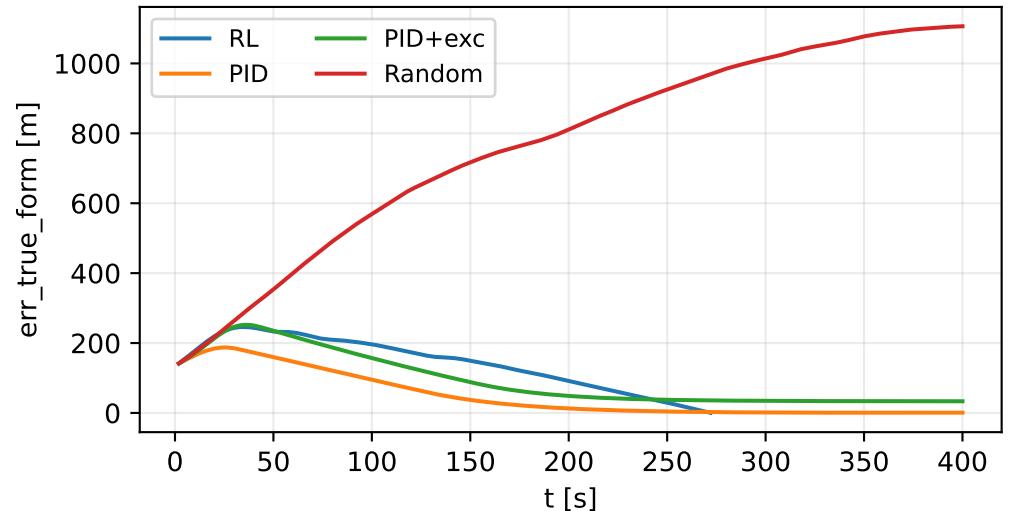
Follower angular rate



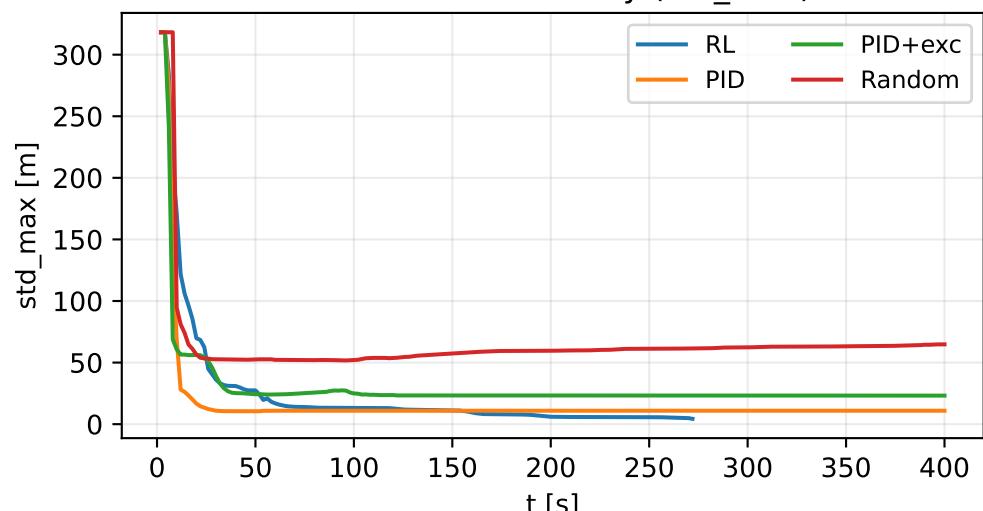
Trajectories (matched seed)



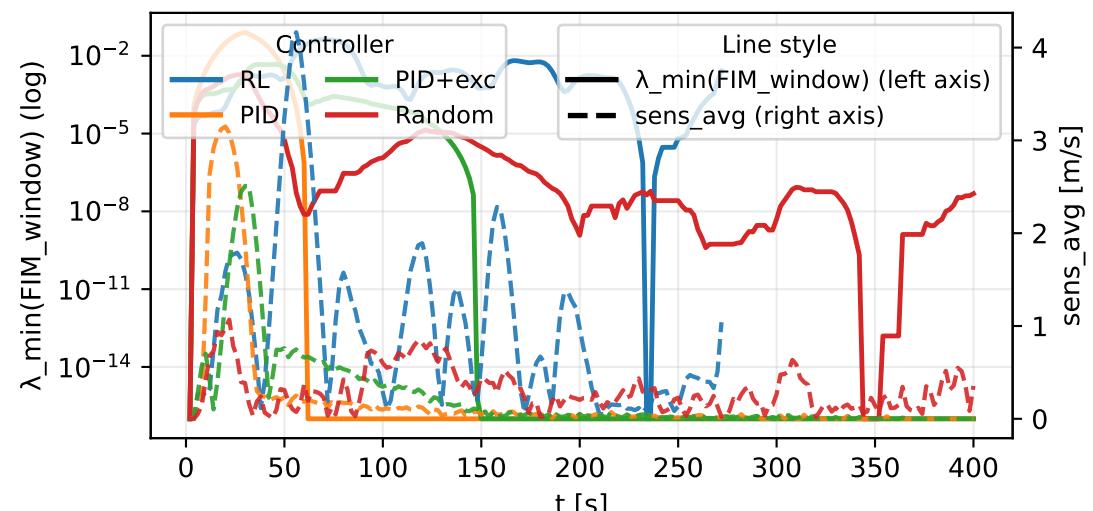
TRUE formation error



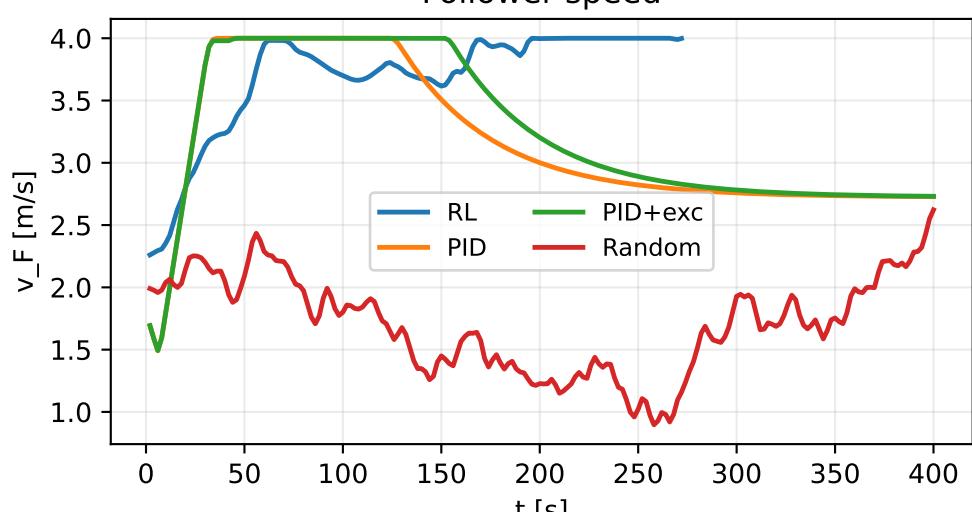
Estimator uncertainty (std_max)



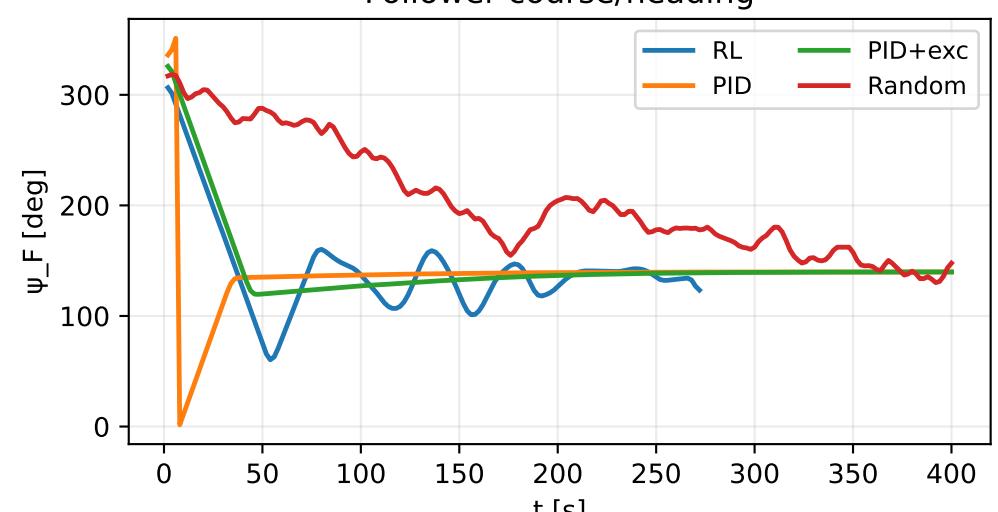
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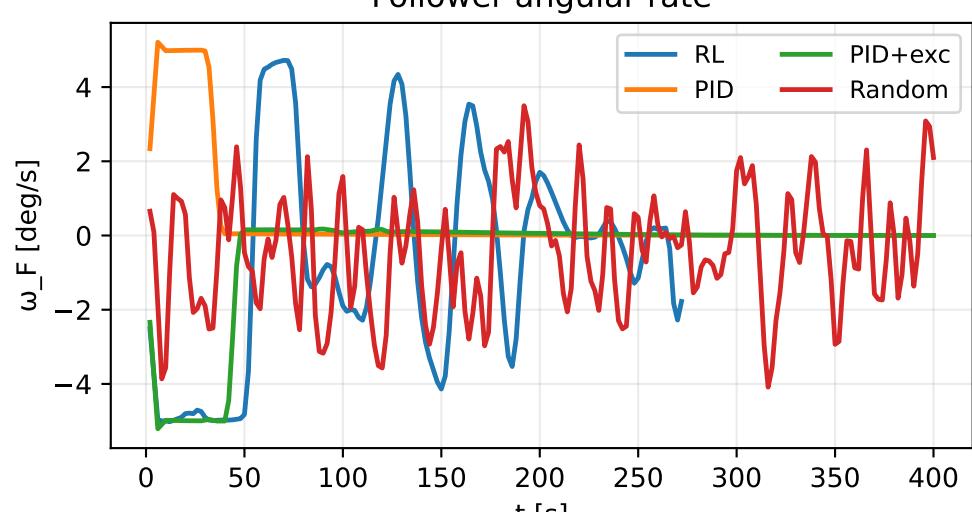
Follower speed



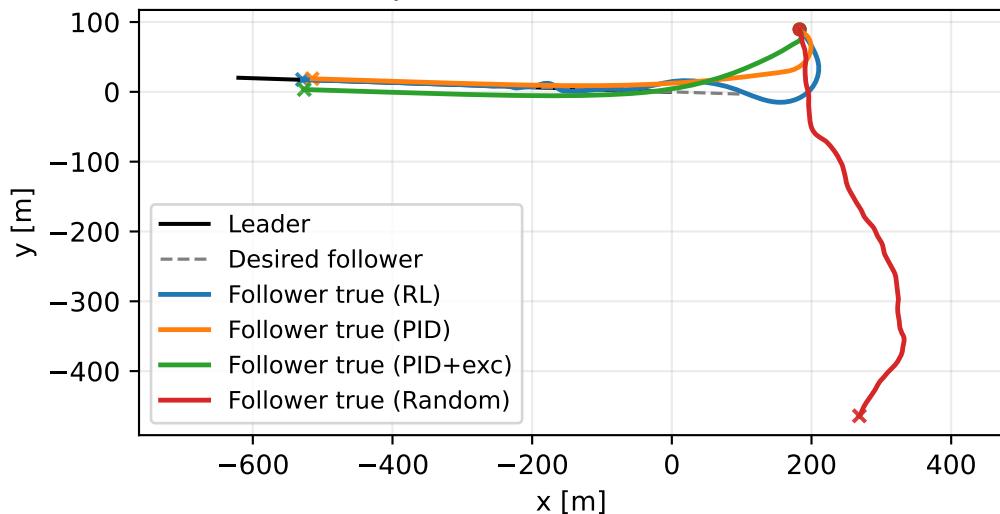
Follower course/heading



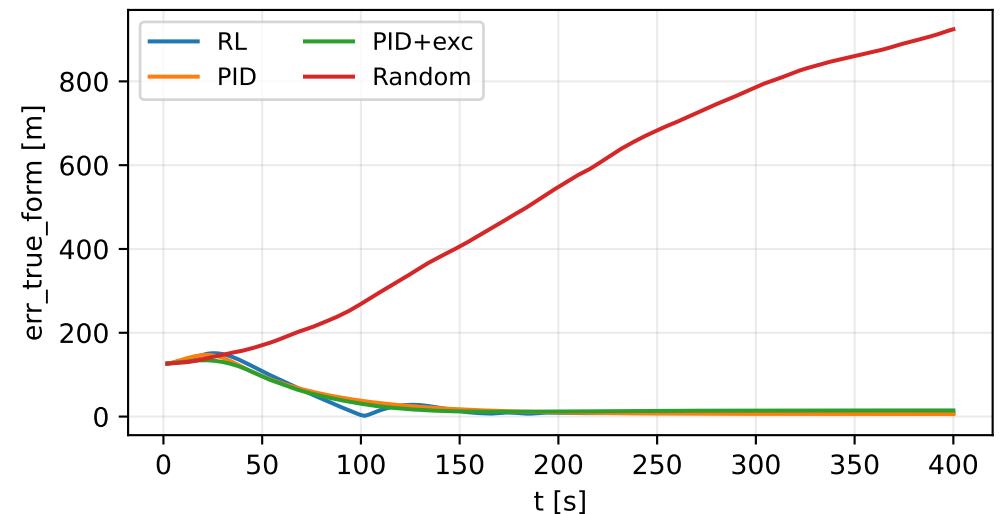
Follower angular rate



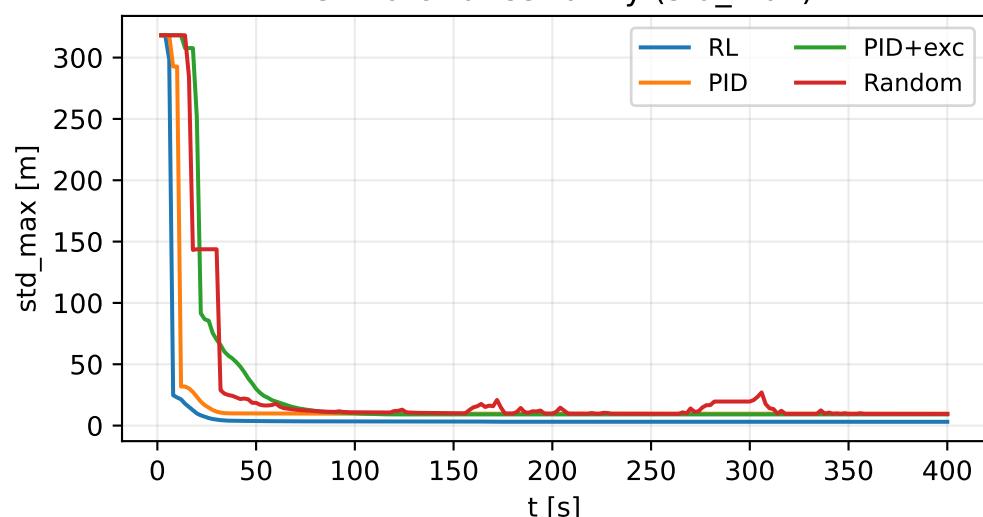
Trajectories (matched seed)



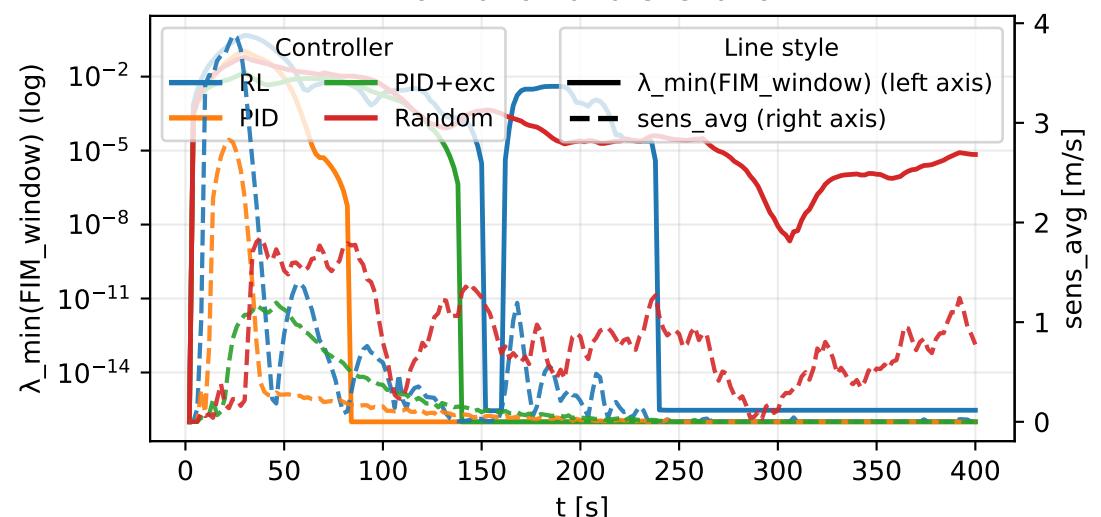
TRUE formation error



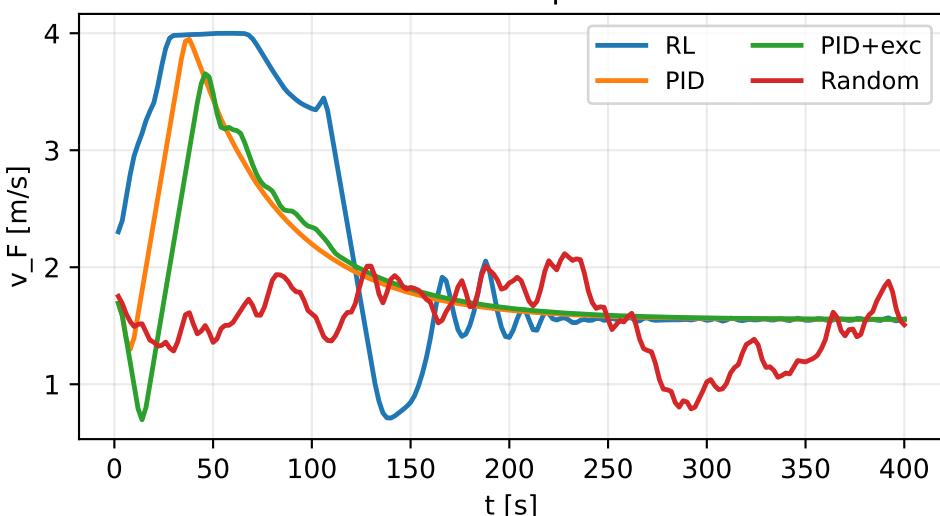
Estimator uncertainty (std_max)



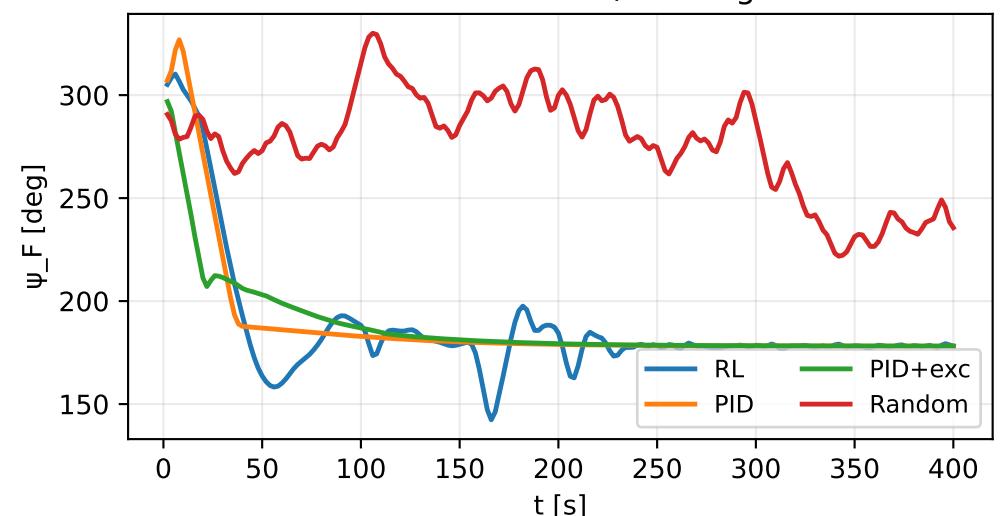
Information and excitation



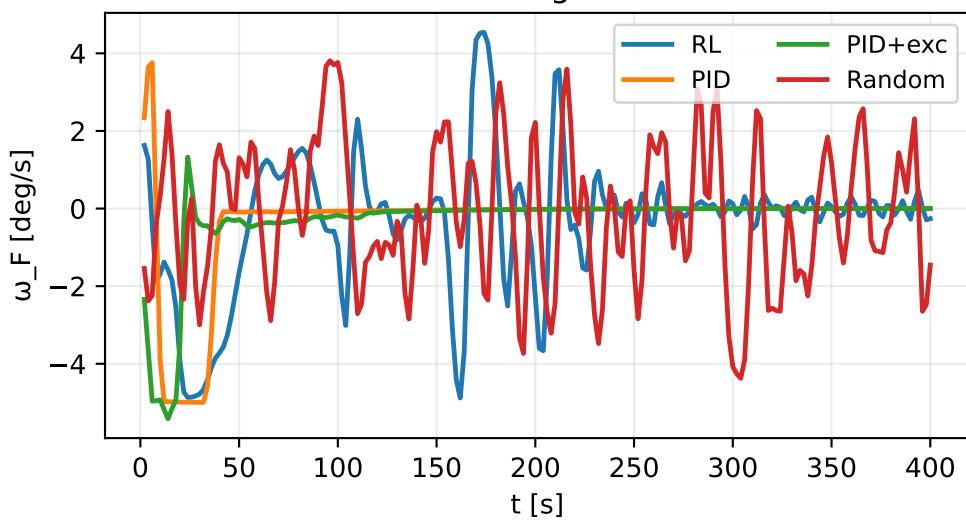
Follower speed



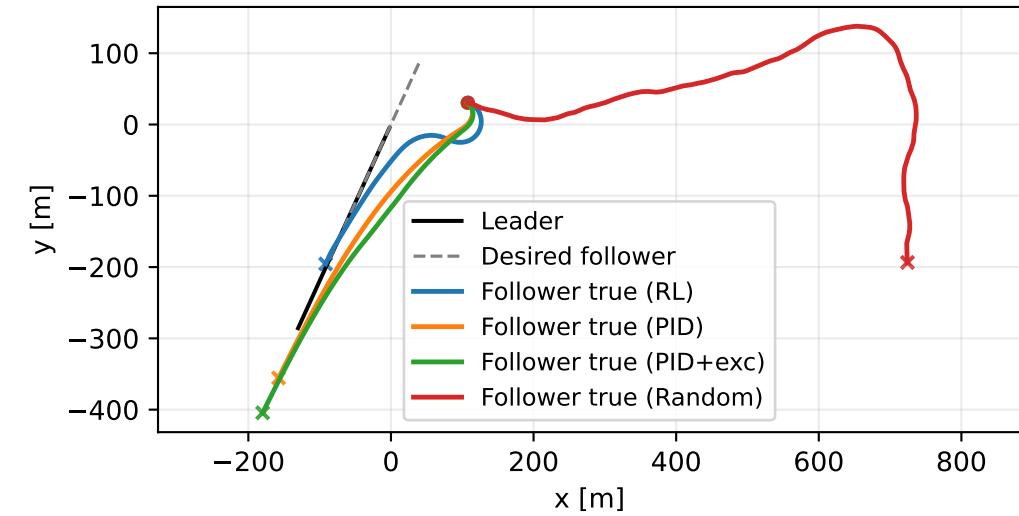
Follower course/heading



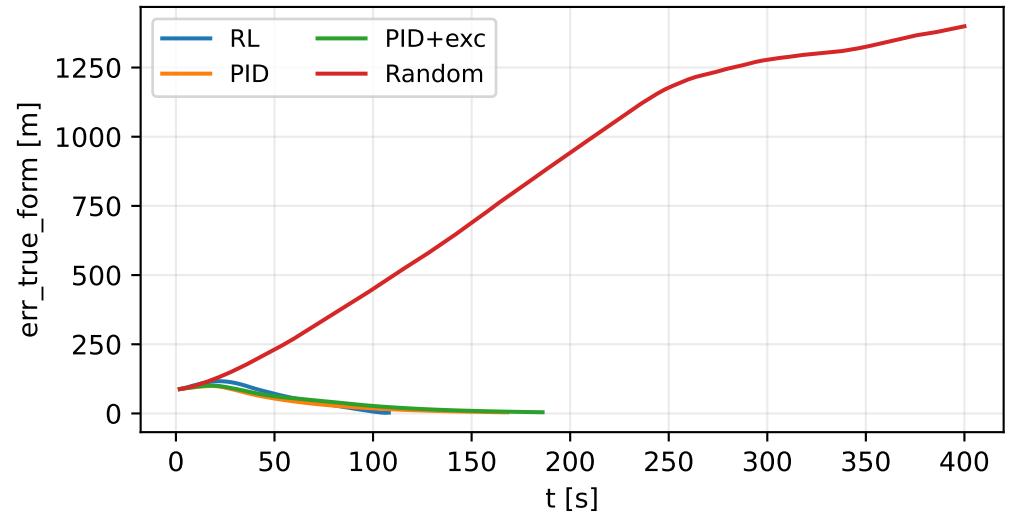
Follower angular rate



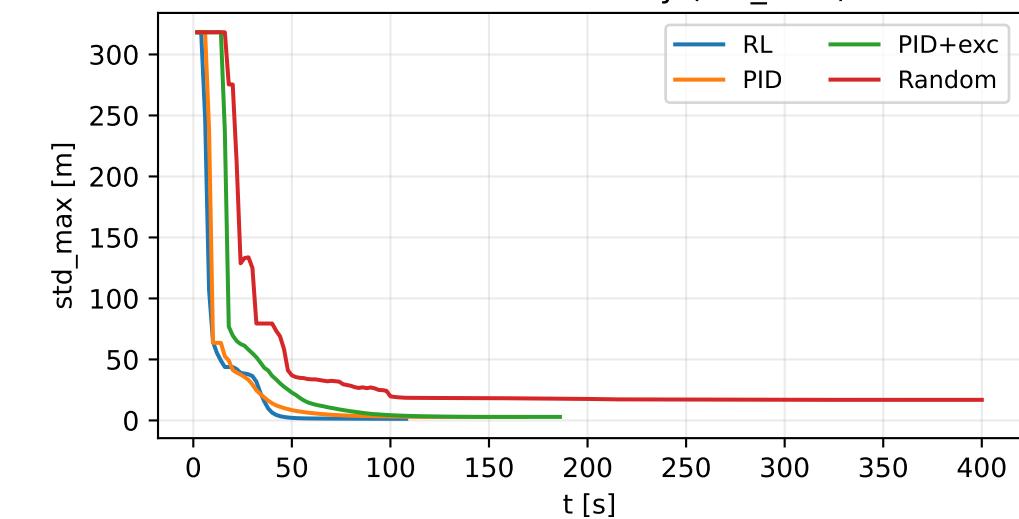
Trajectories (matched seed)



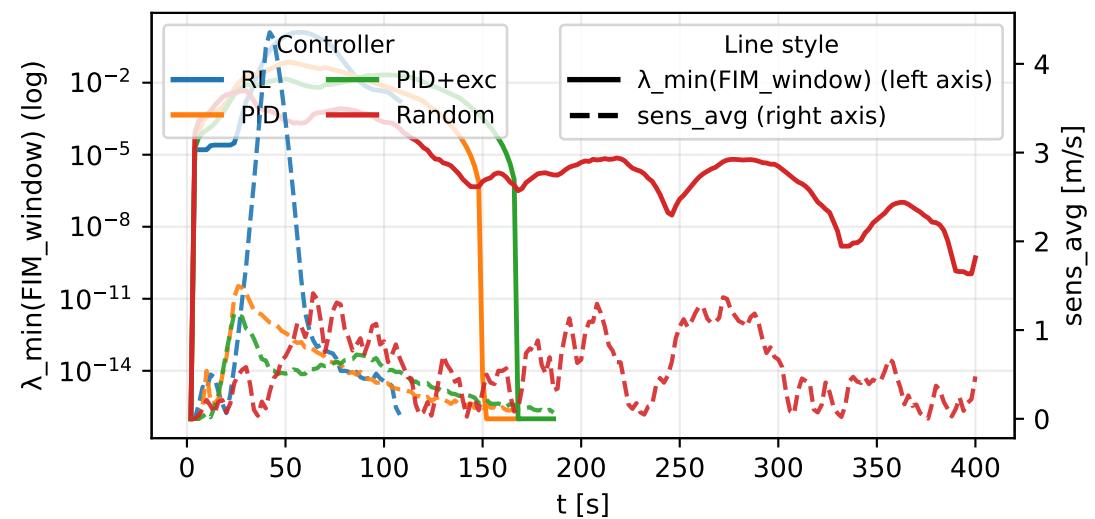
TRUE formation error



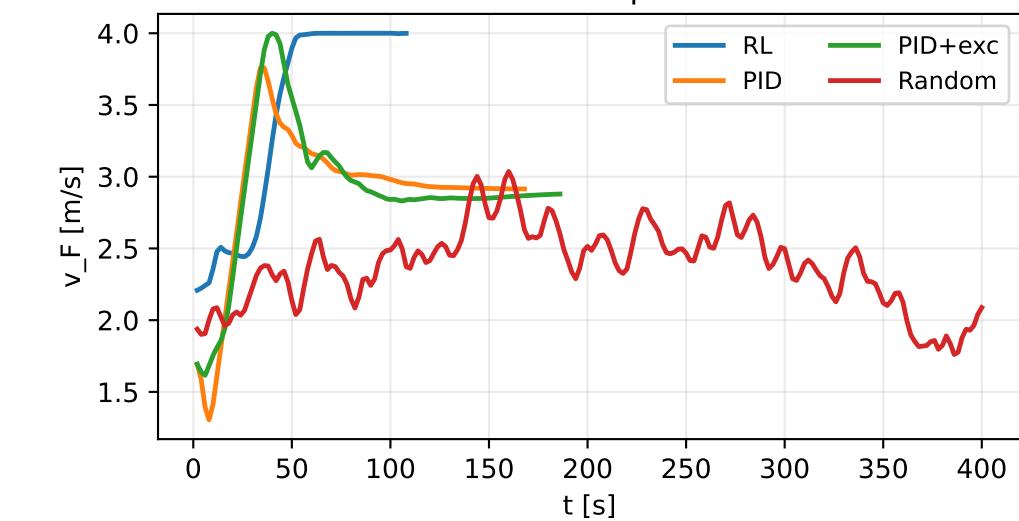
Estimator uncertainty (std_max)



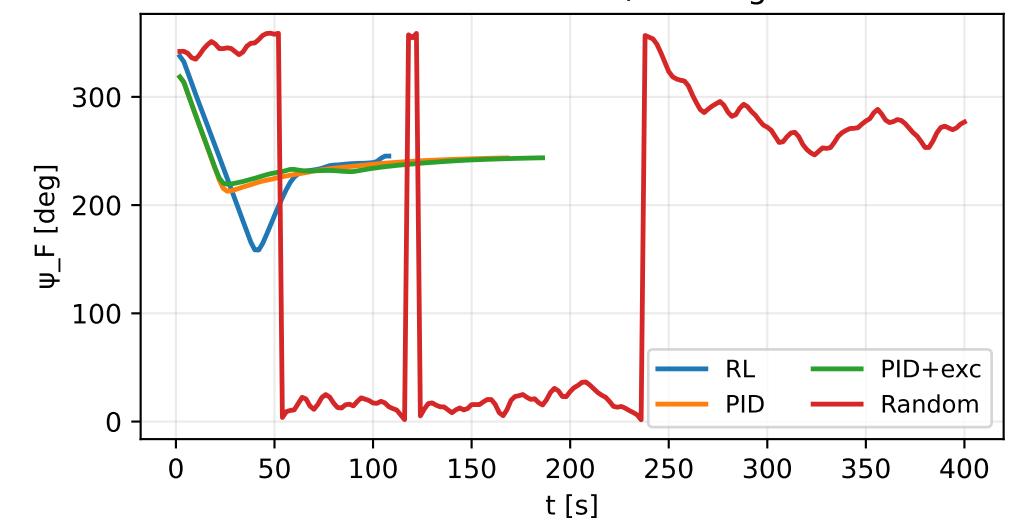
Information and excitation



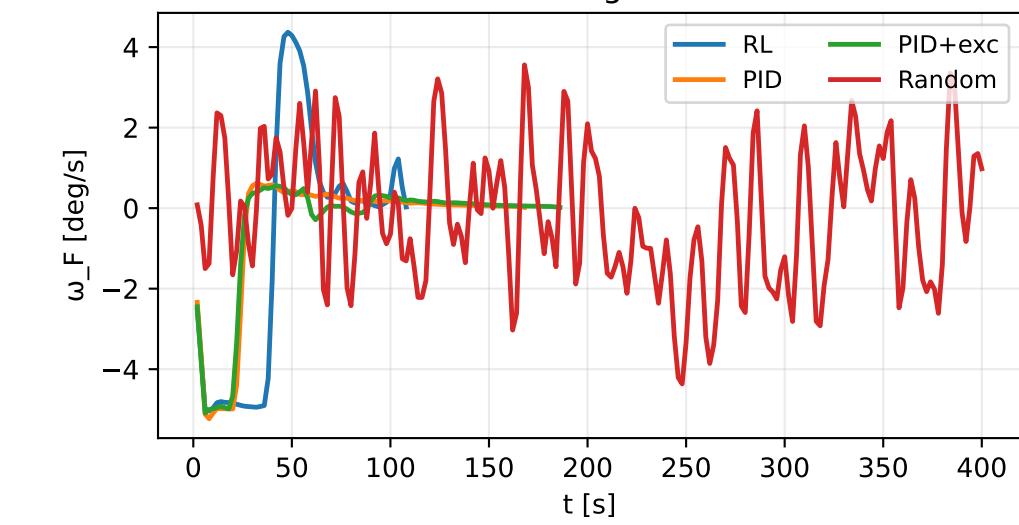
Follower speed



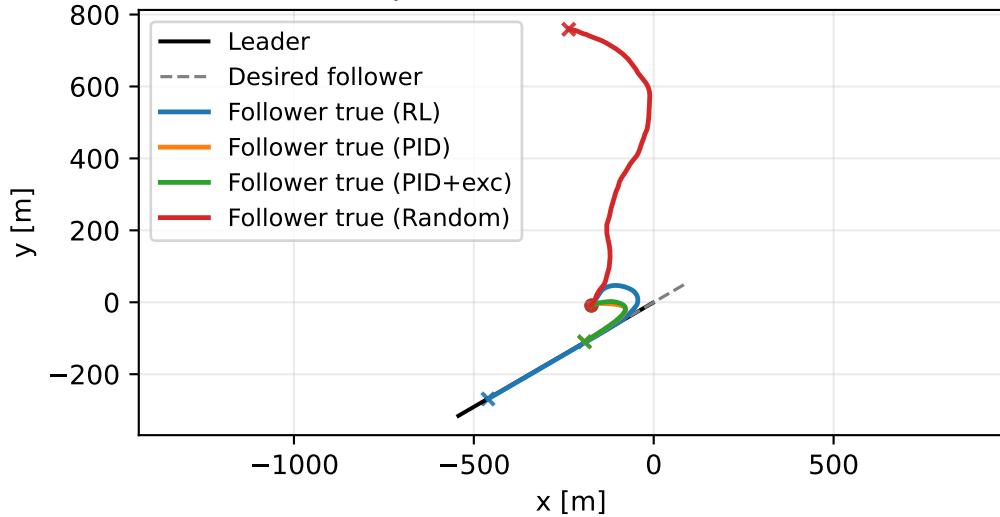
Follower course/heading



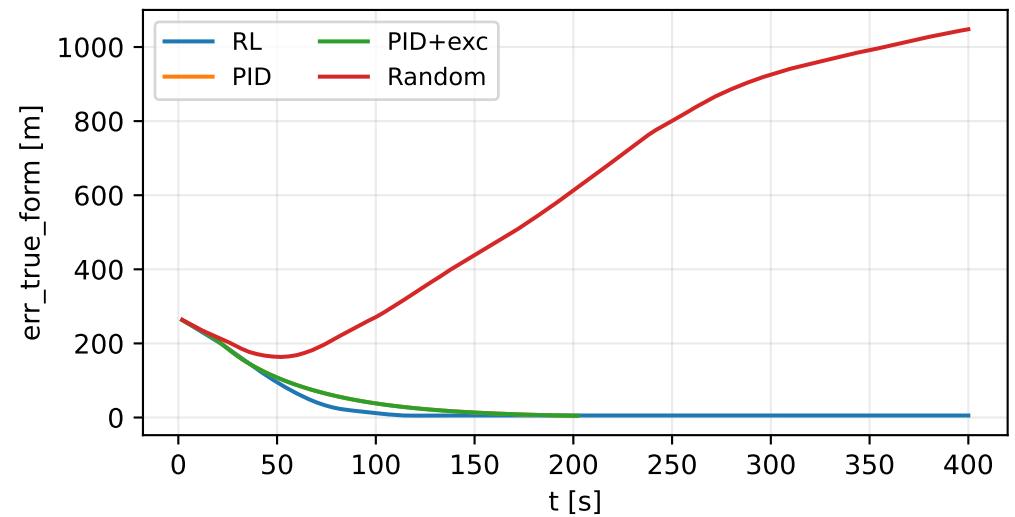
Follower angular rate



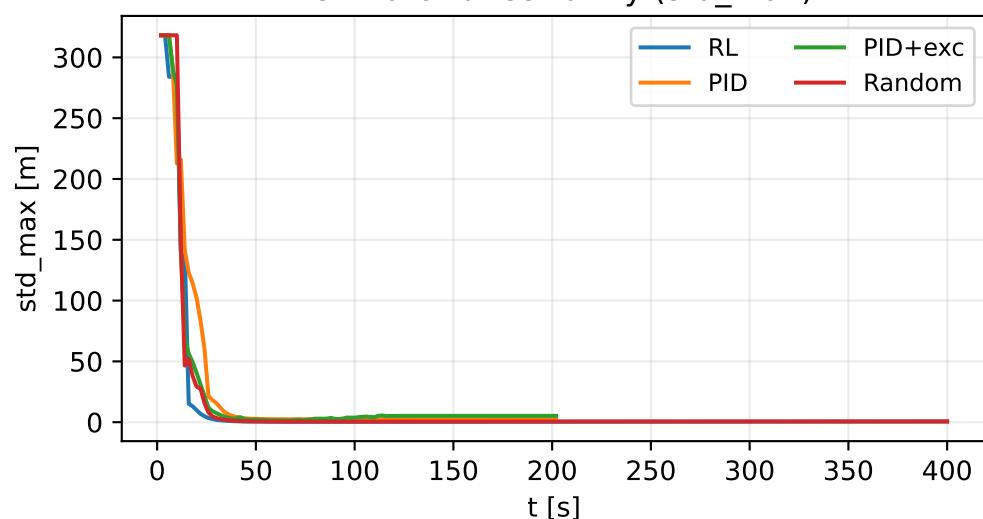
Trajectories (matched seed)



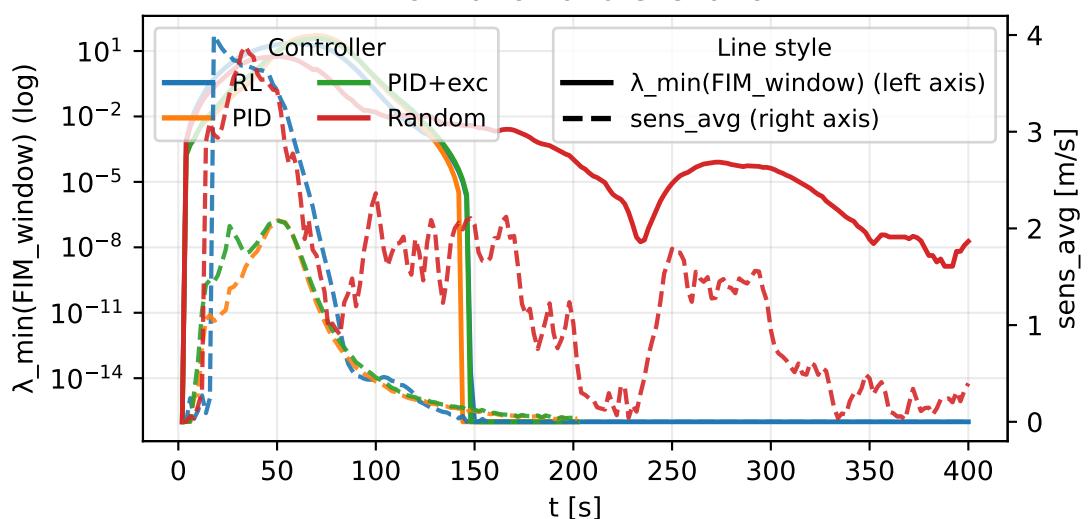
TRUE formation error



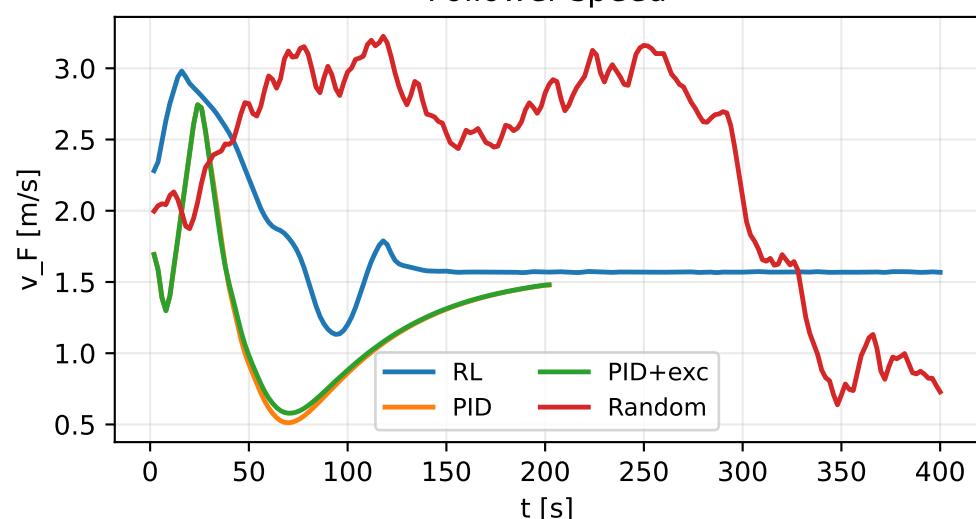
Estimator uncertainty (std_max)



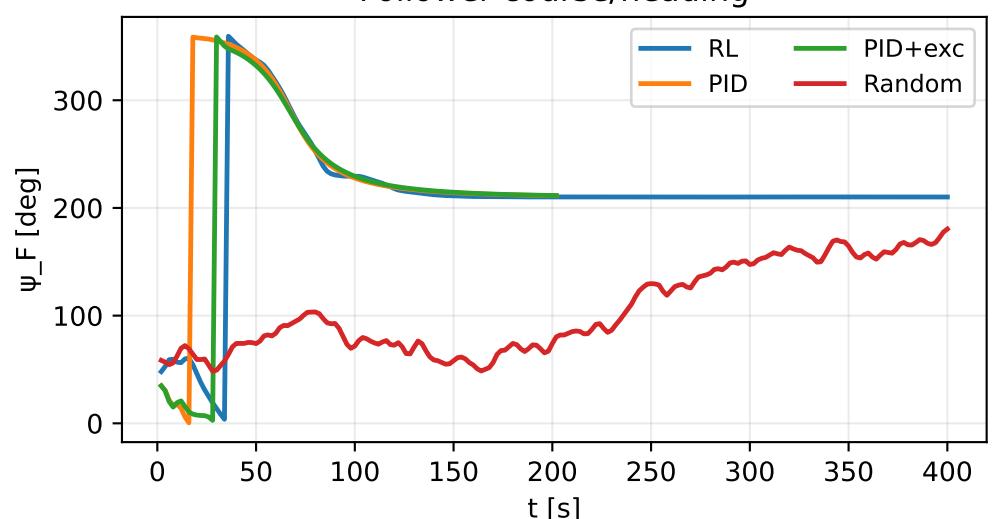
Information and excitation



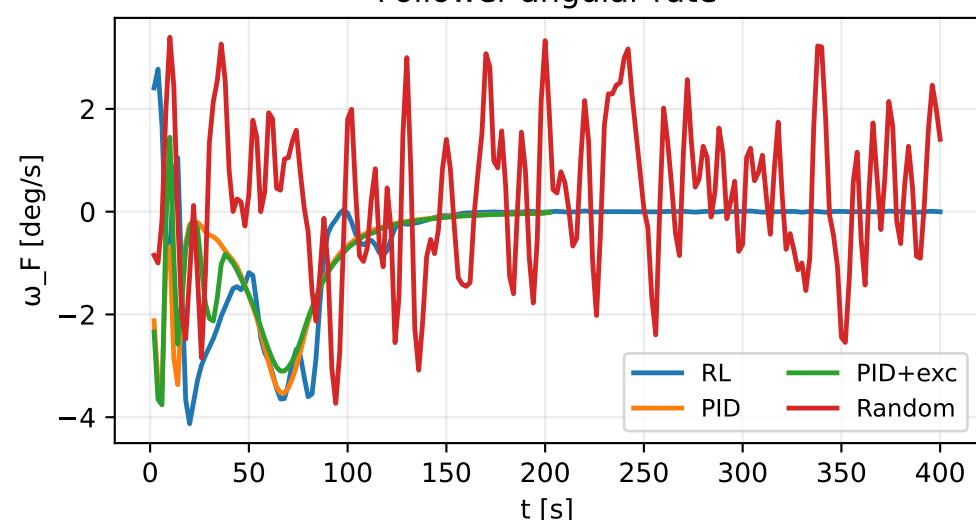
Follower speed



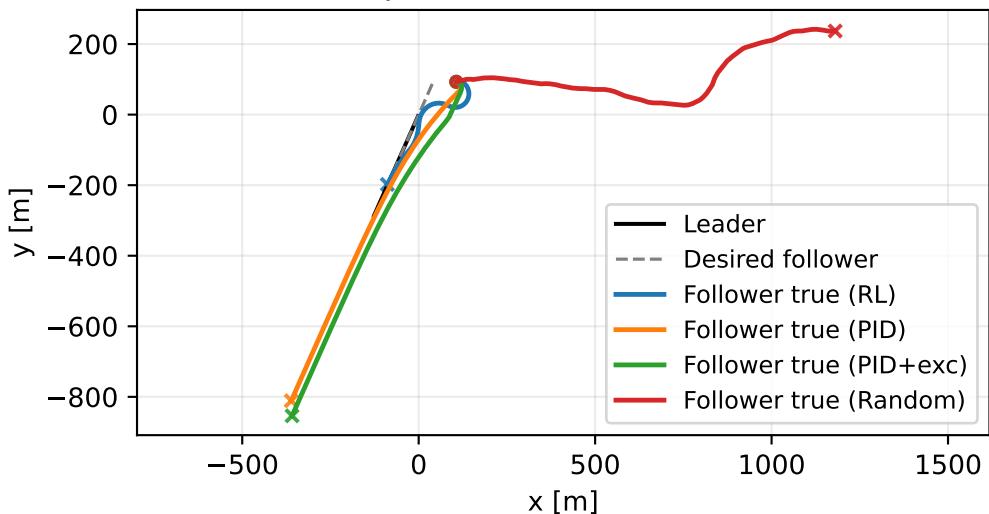
Follower course/heading



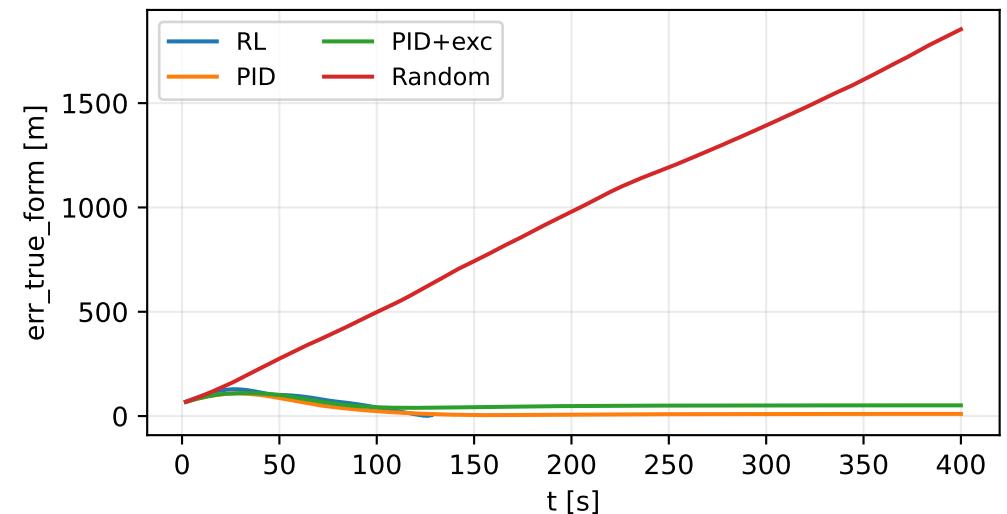
Follower angular rate



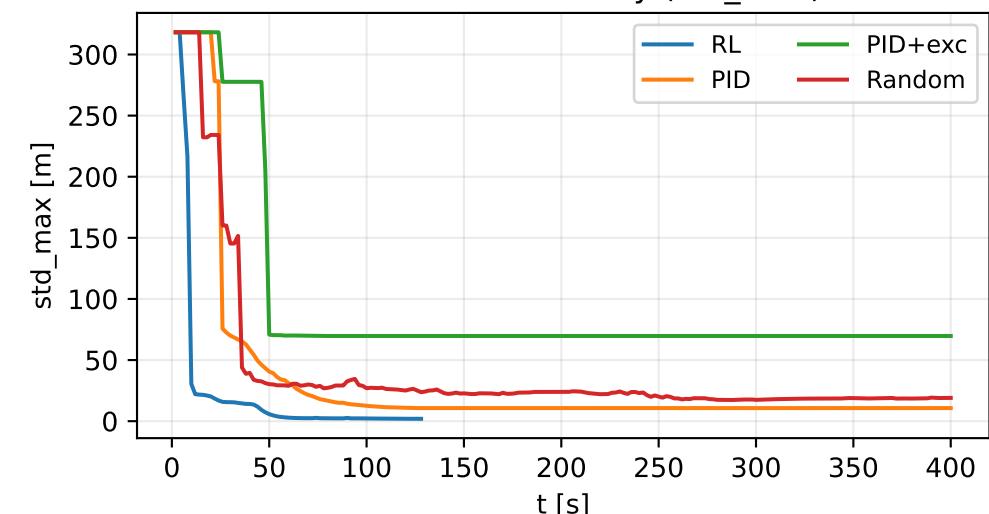
Trajectories (matched seed)



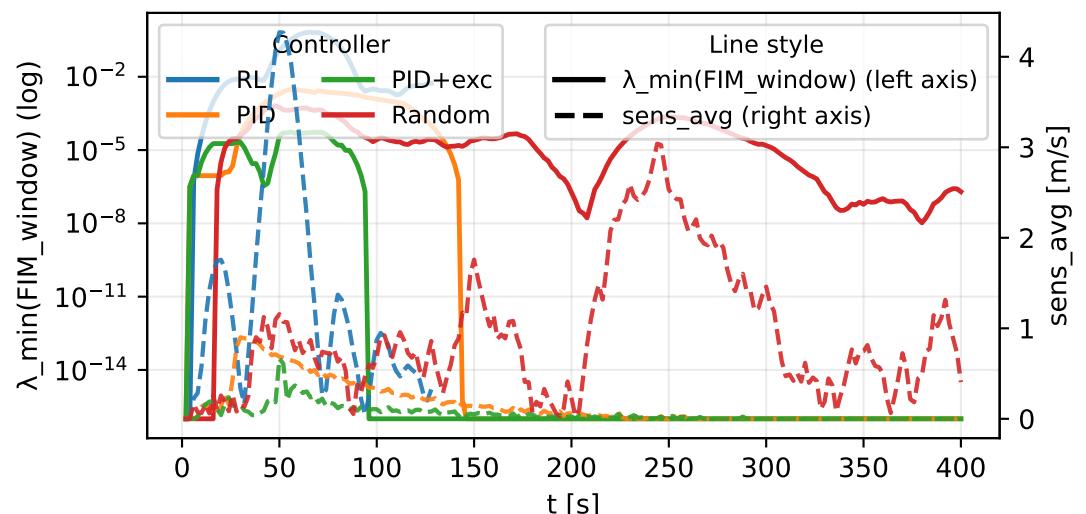
TRUE formation error



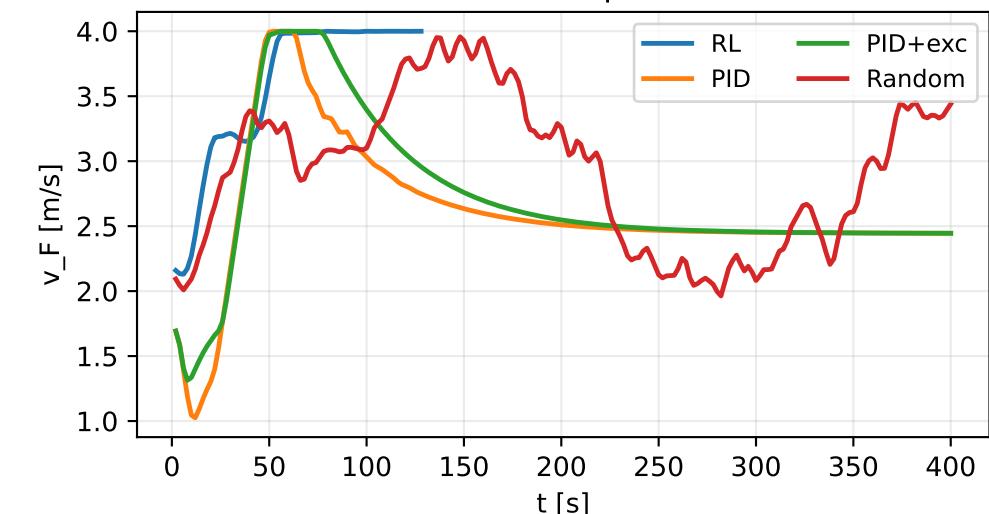
Estimator uncertainty (std_max)



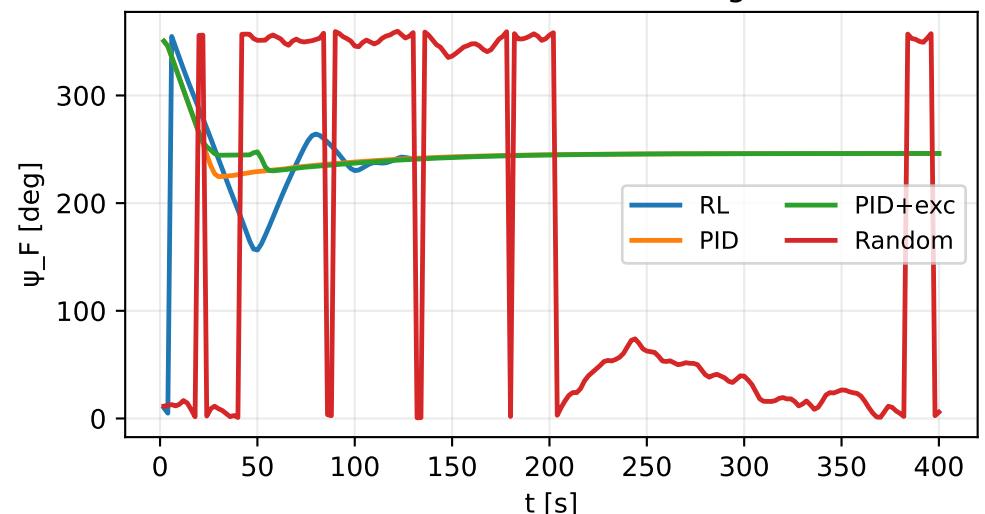
Information and excitation



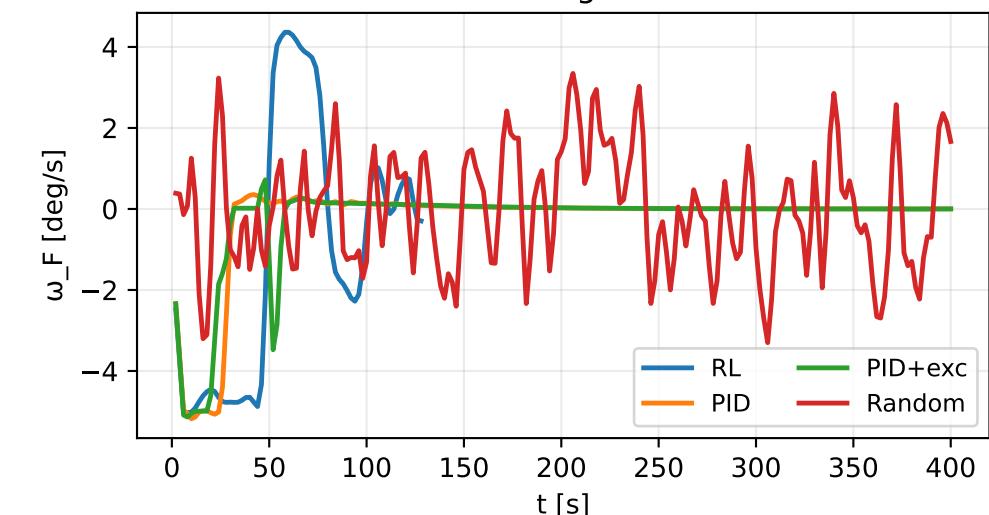
Follower speed



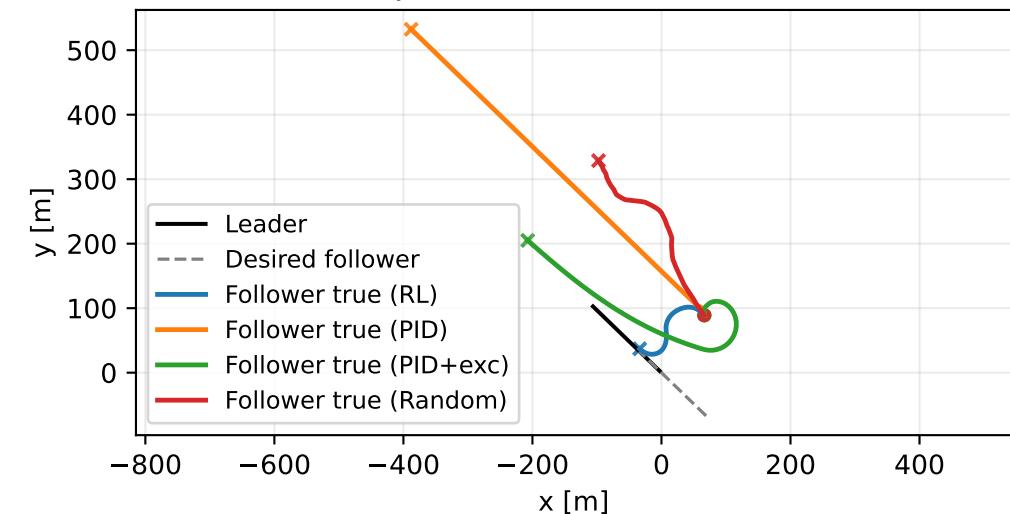
Follower course/heading



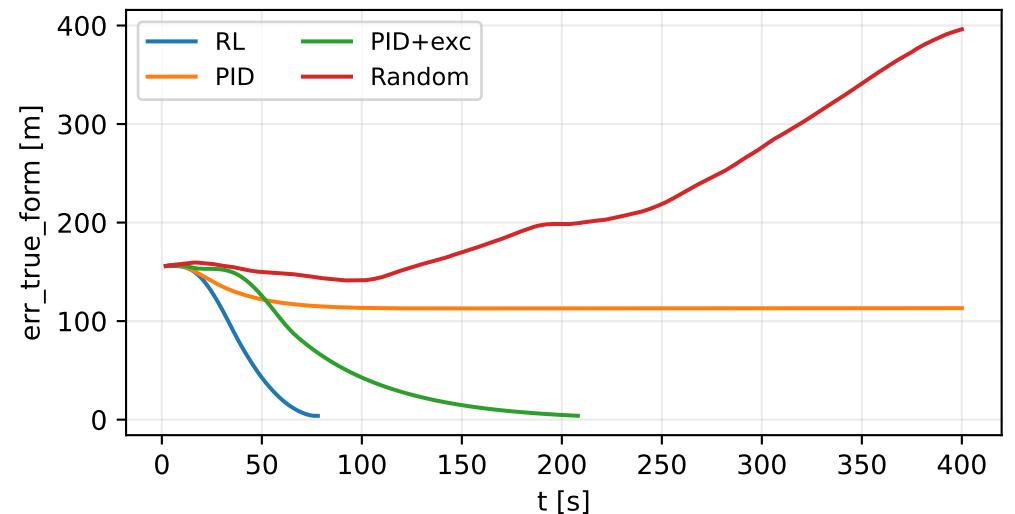
Follower angular rate



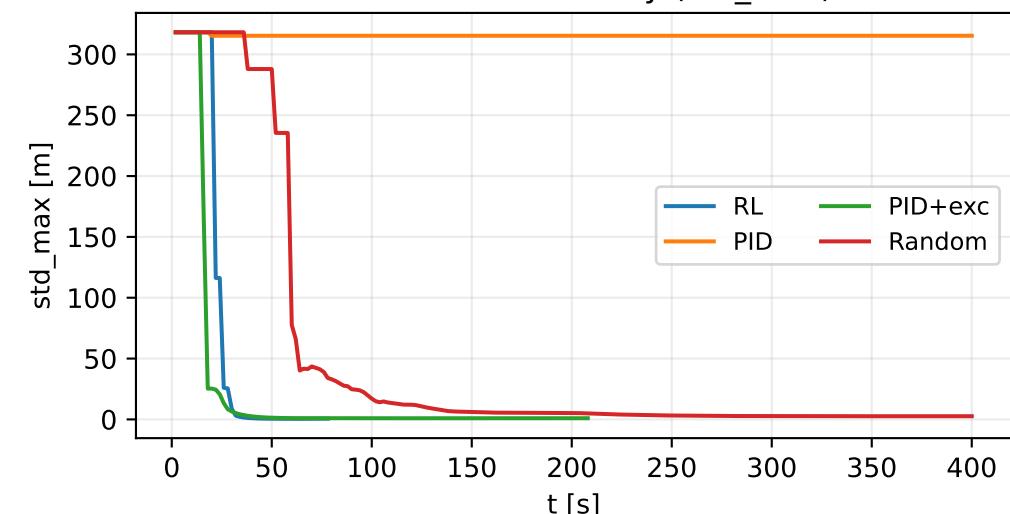
Trajectories (matched seed)



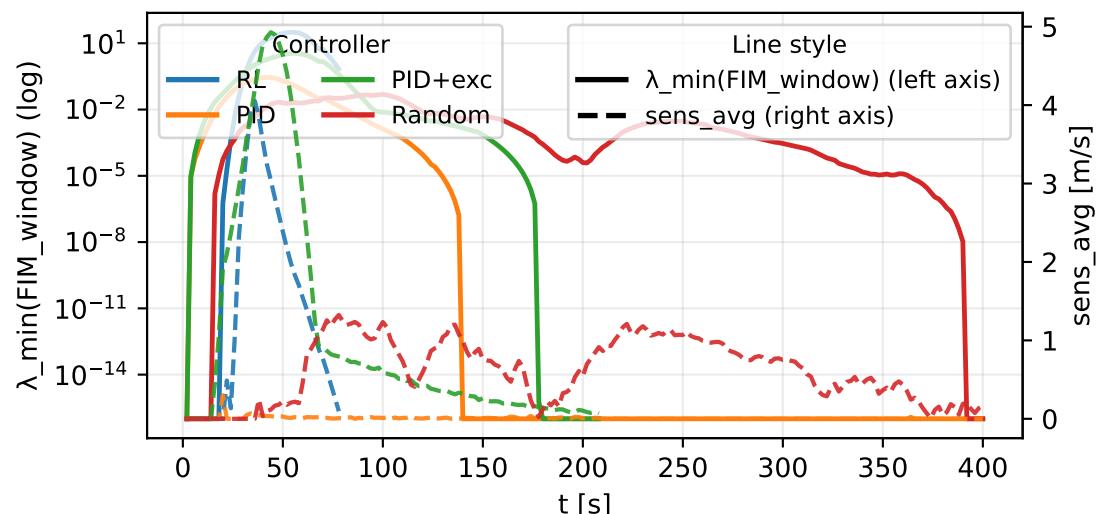
TRUE formation error



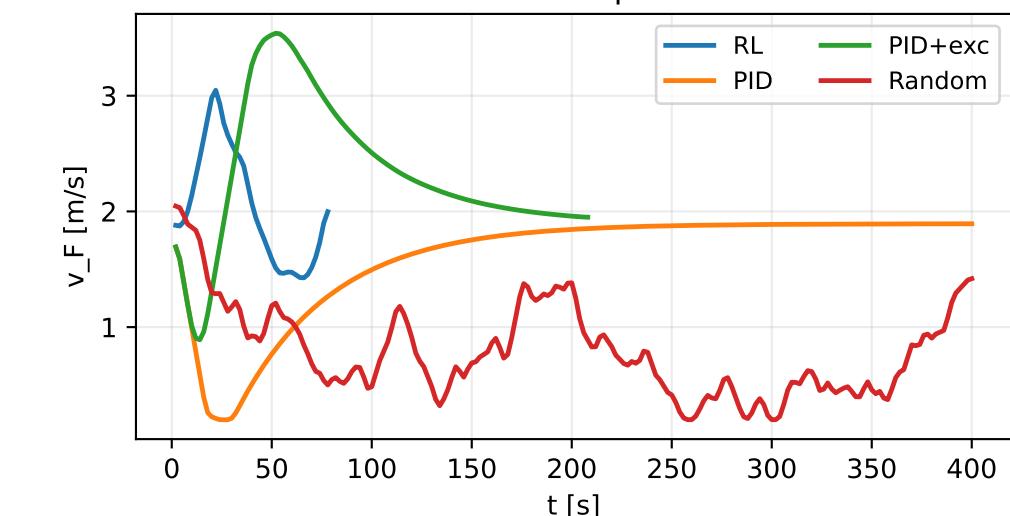
Estimator uncertainty (std_max)



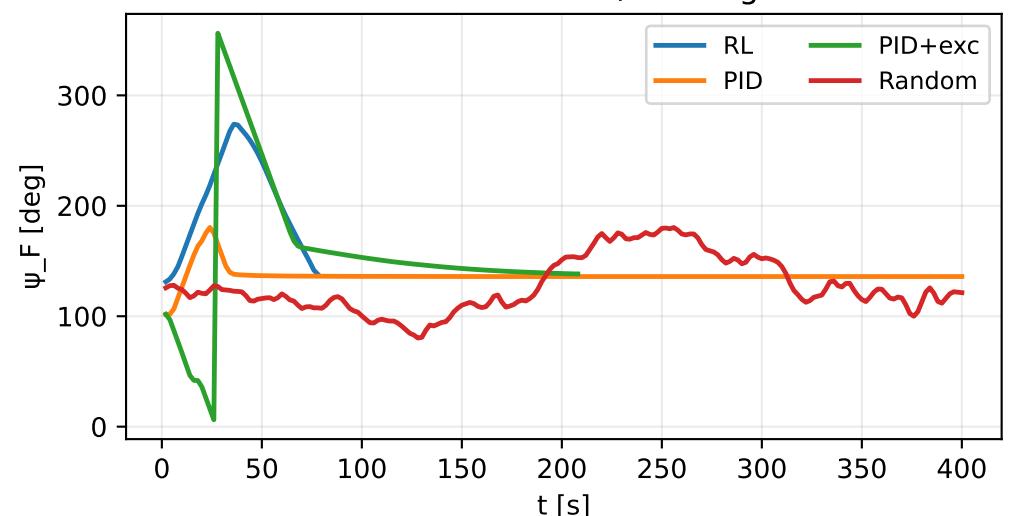
Information and excitation



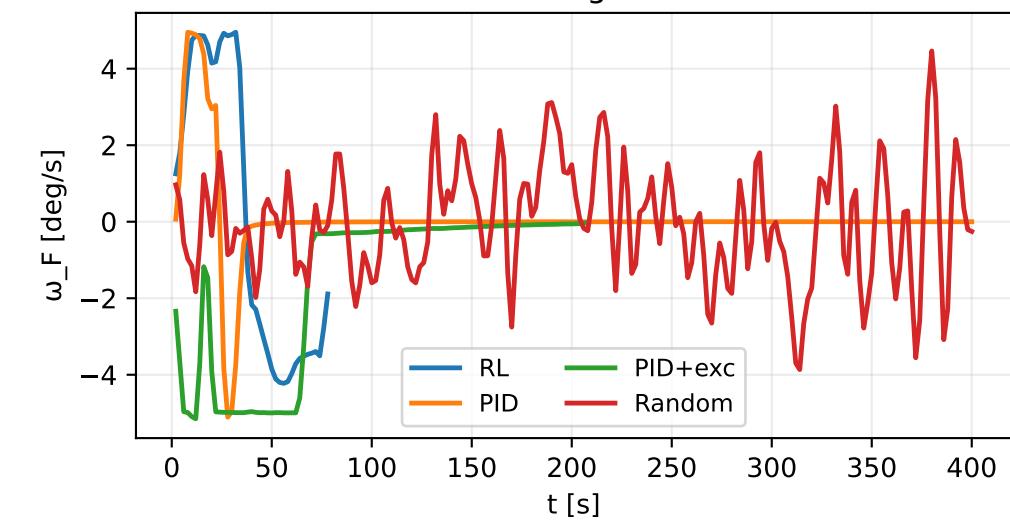
Follower speed



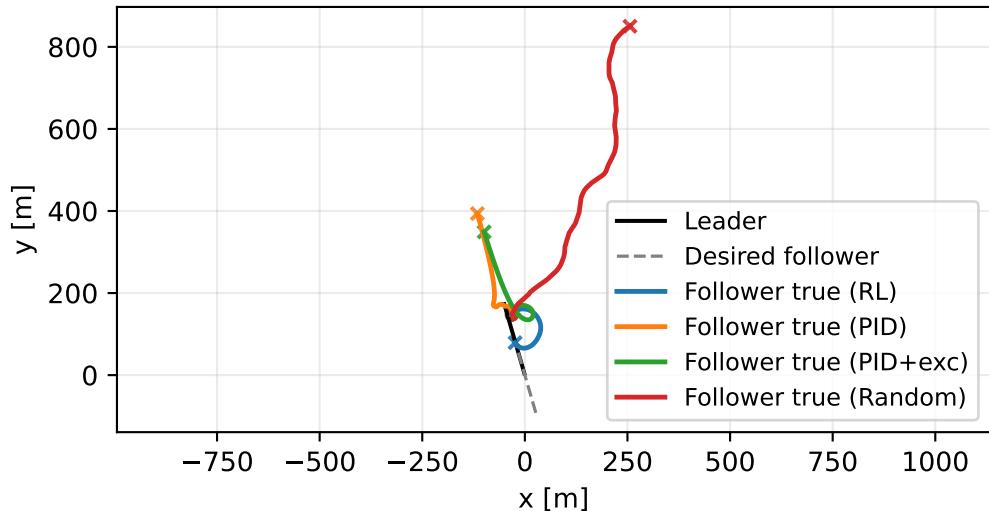
Follower course/heading



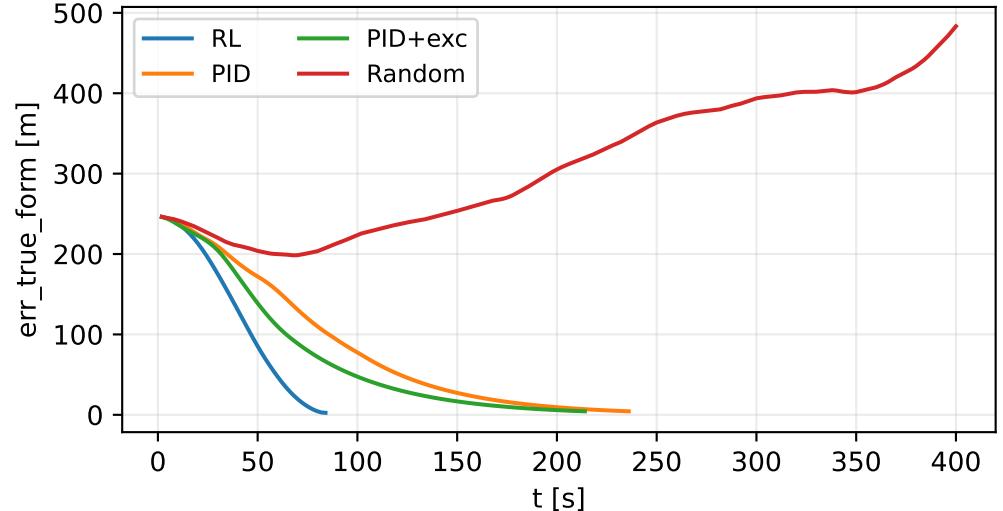
Follower angular rate



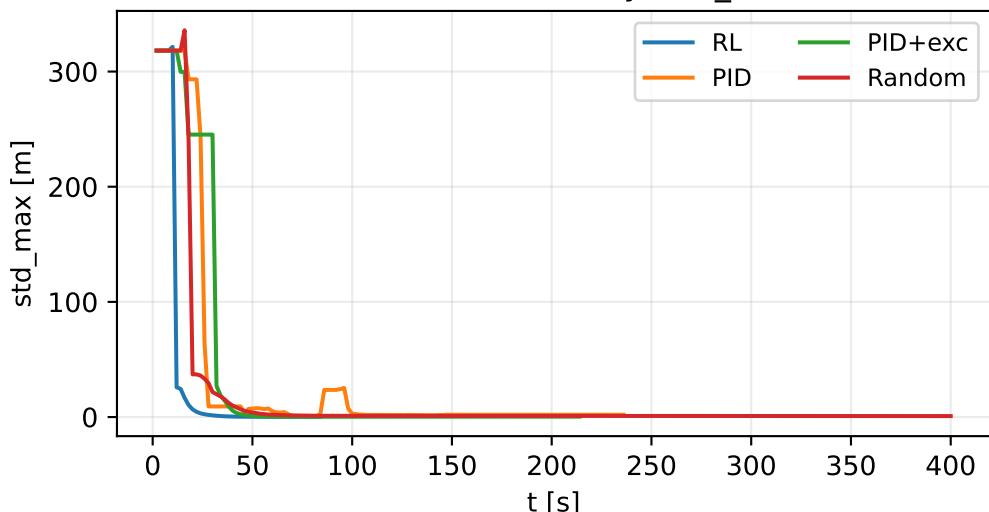
Trajectories (matched seed)



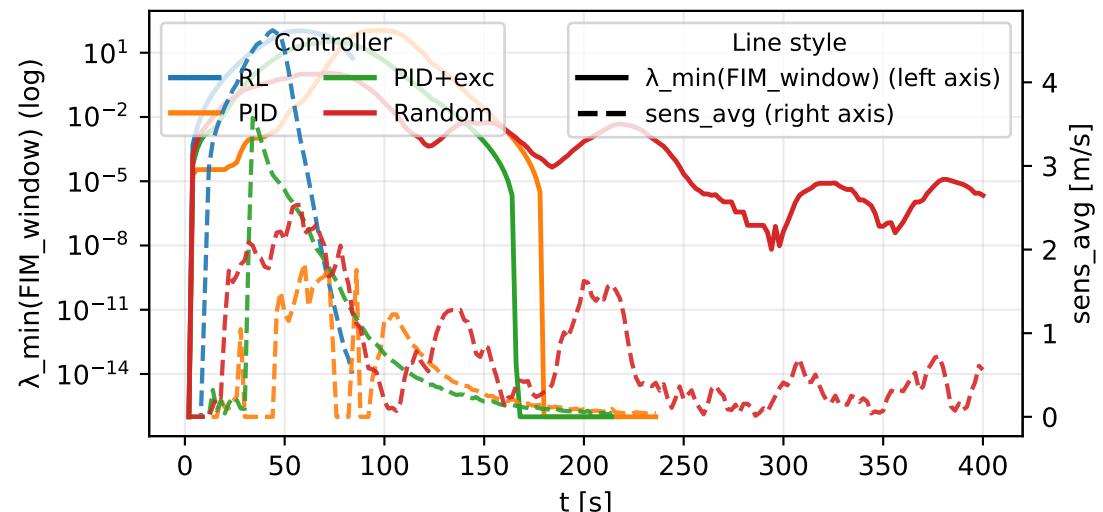
TRUE formation error



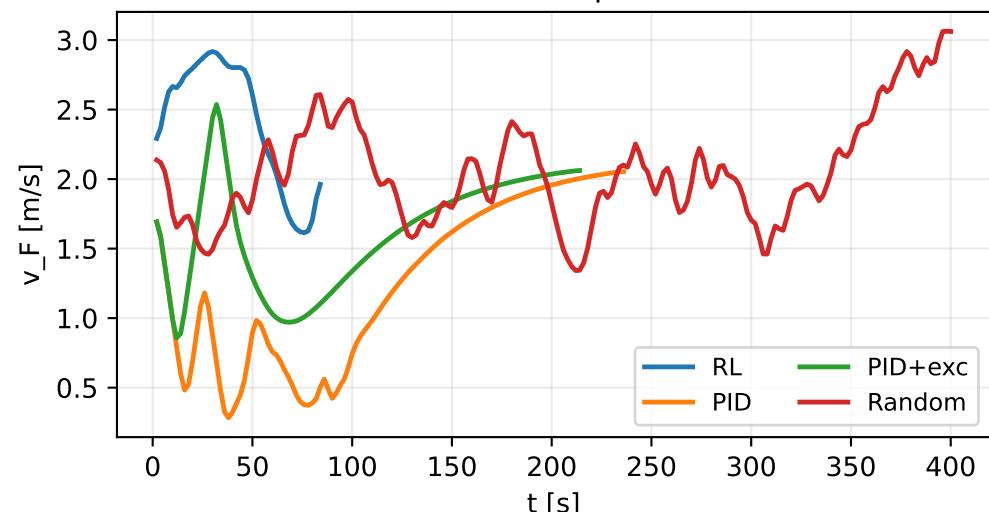
Estimator uncertainty (std_max)



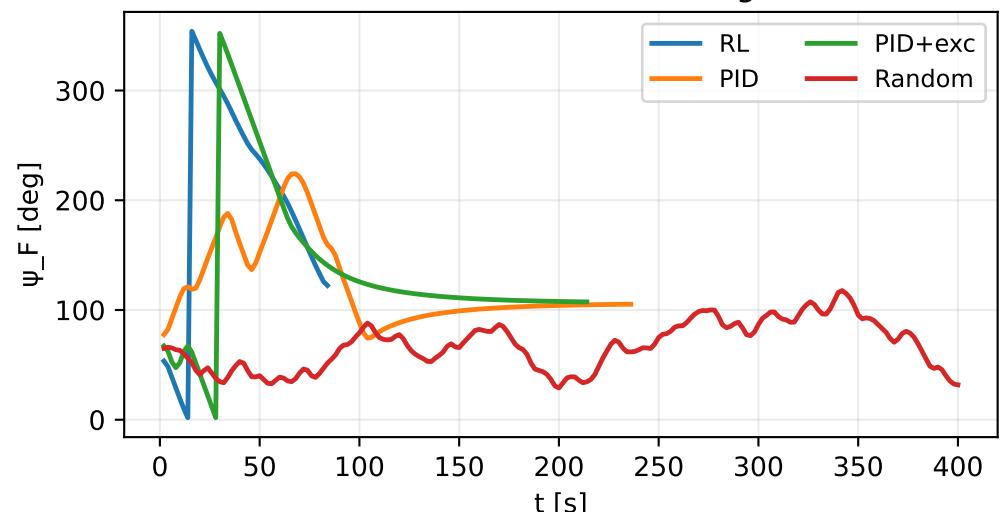
Information and excitation



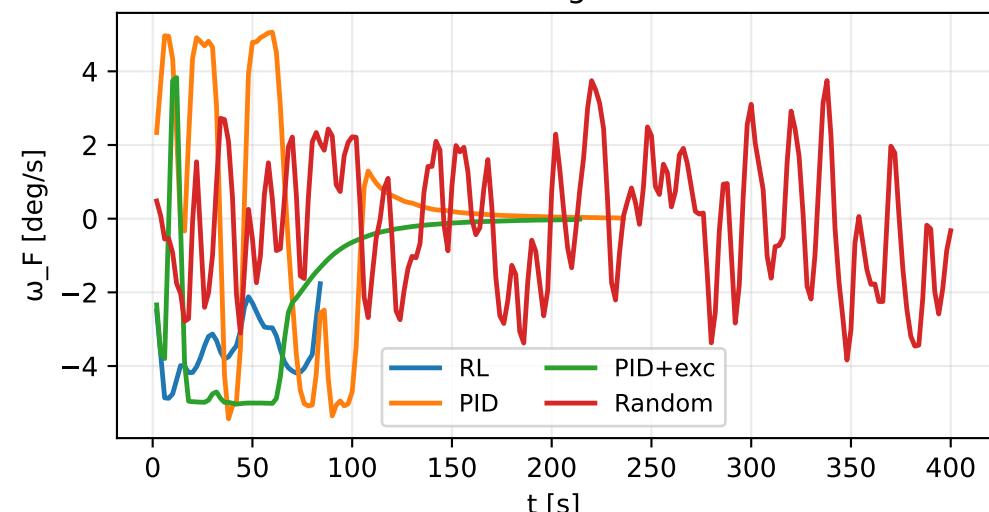
Follower speed



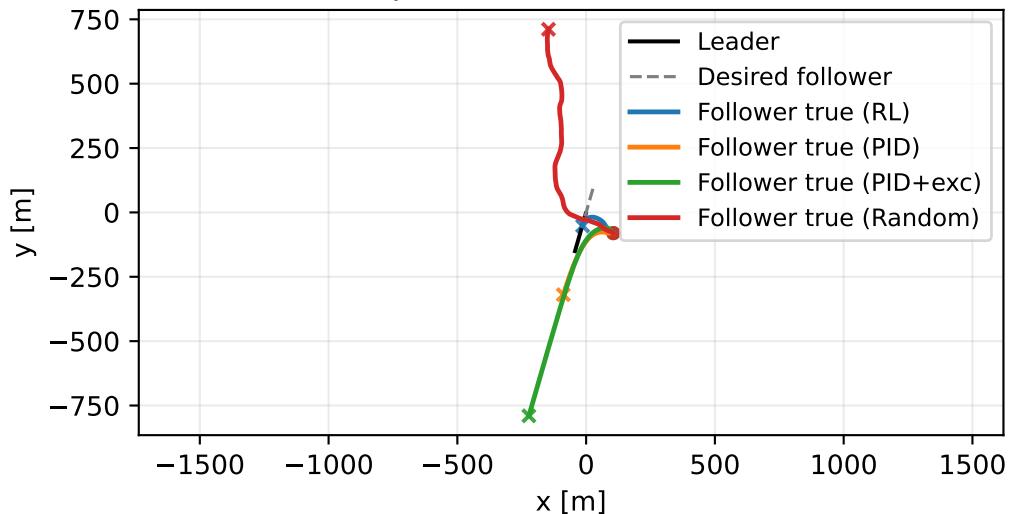
Follower course/heading



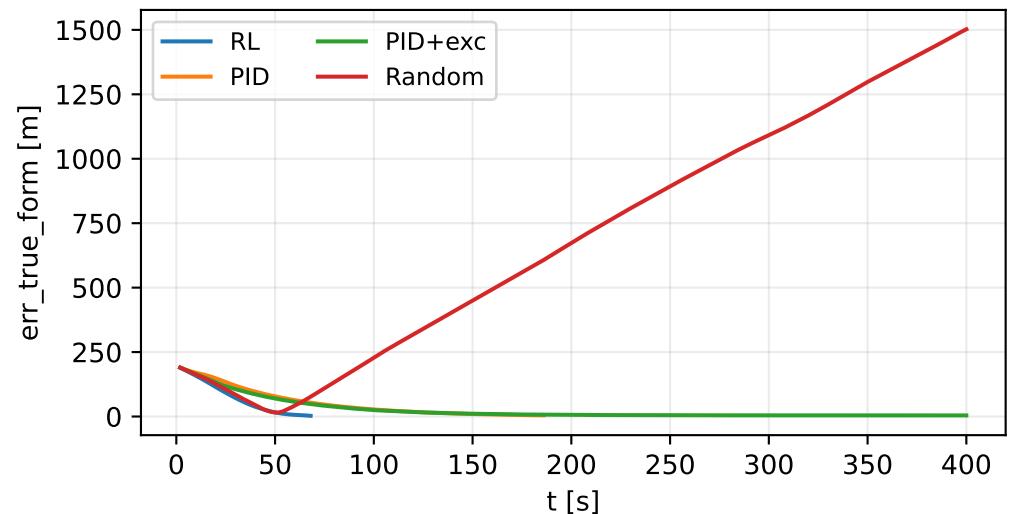
Follower angular rate



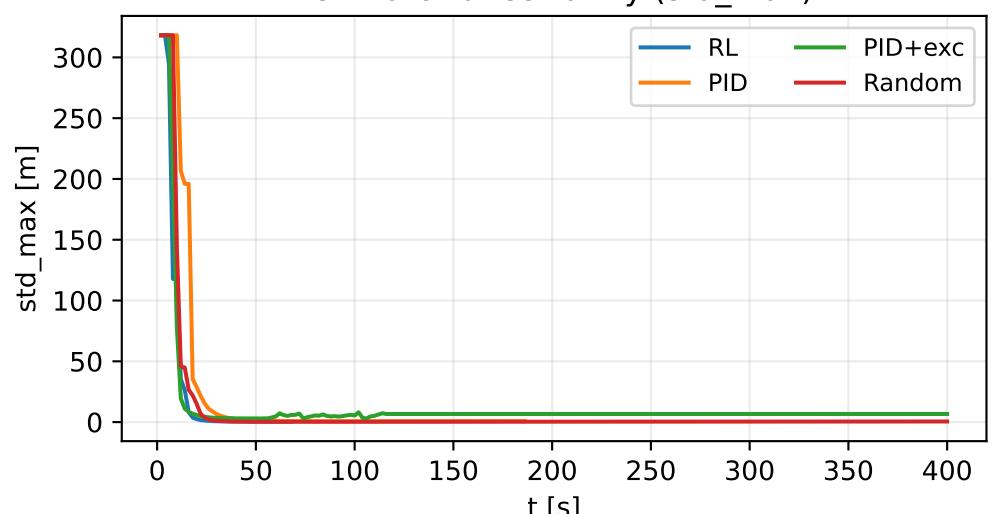
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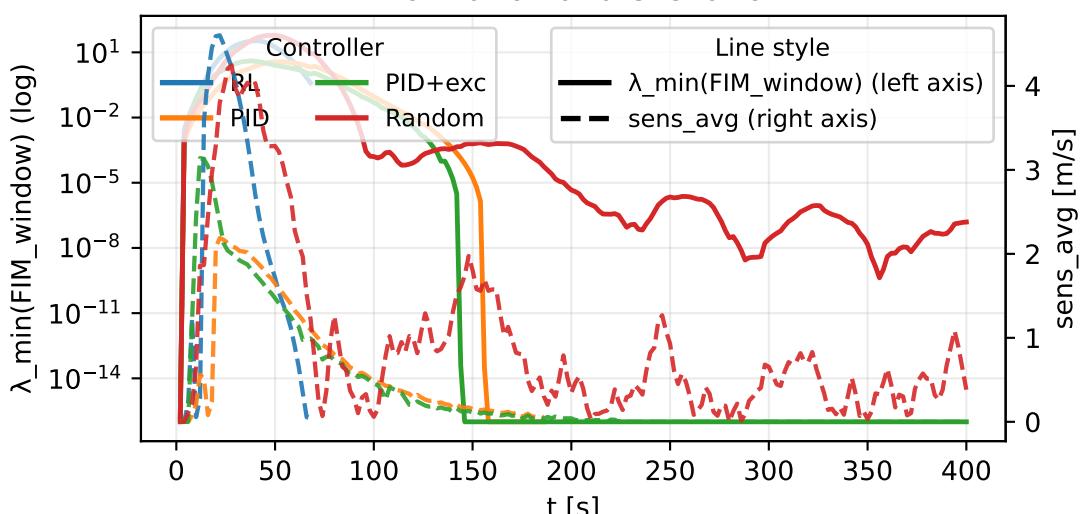
TRUE formation error



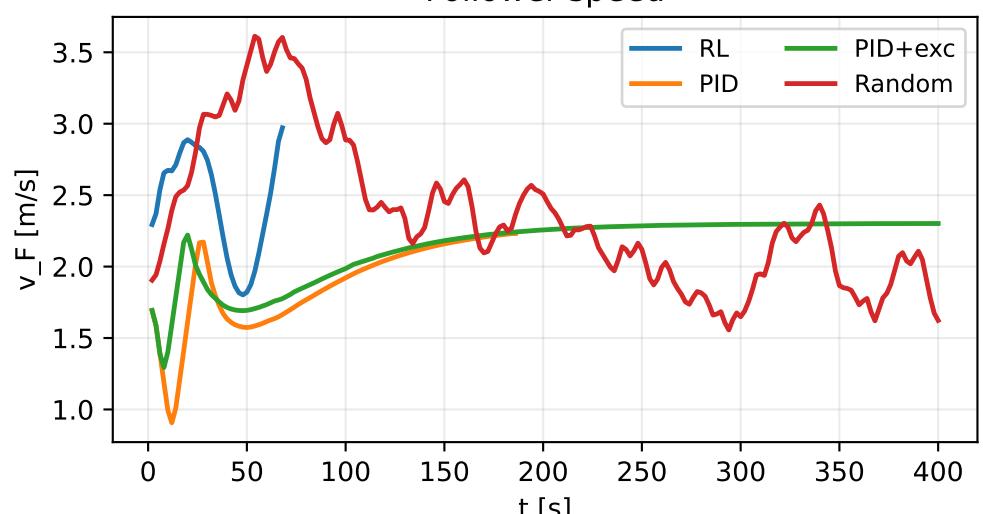
Estimator uncertainty (std_max)



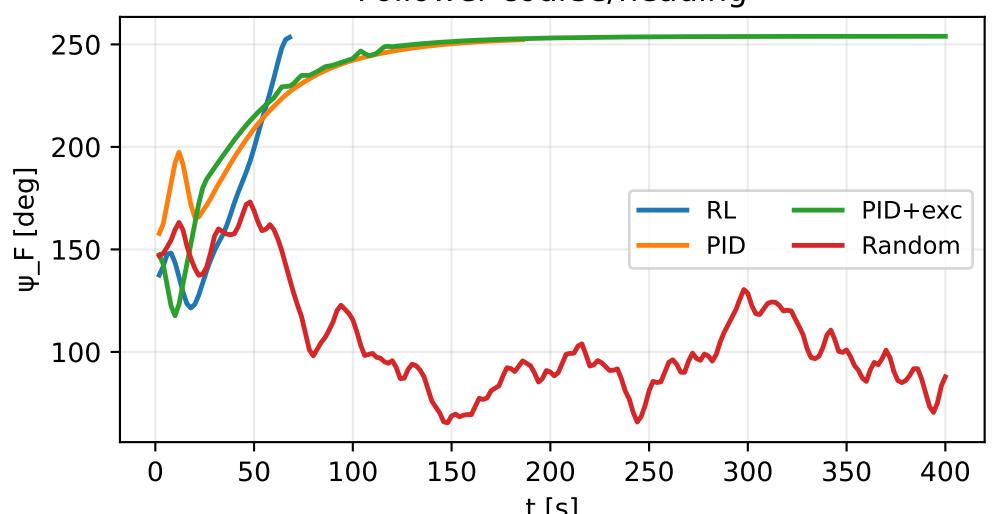
Information and excitation



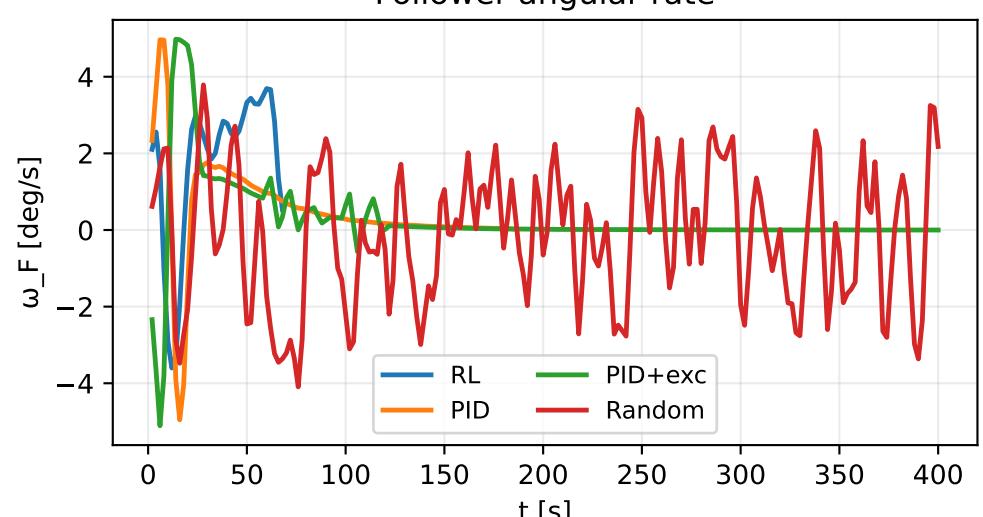
Follower speed



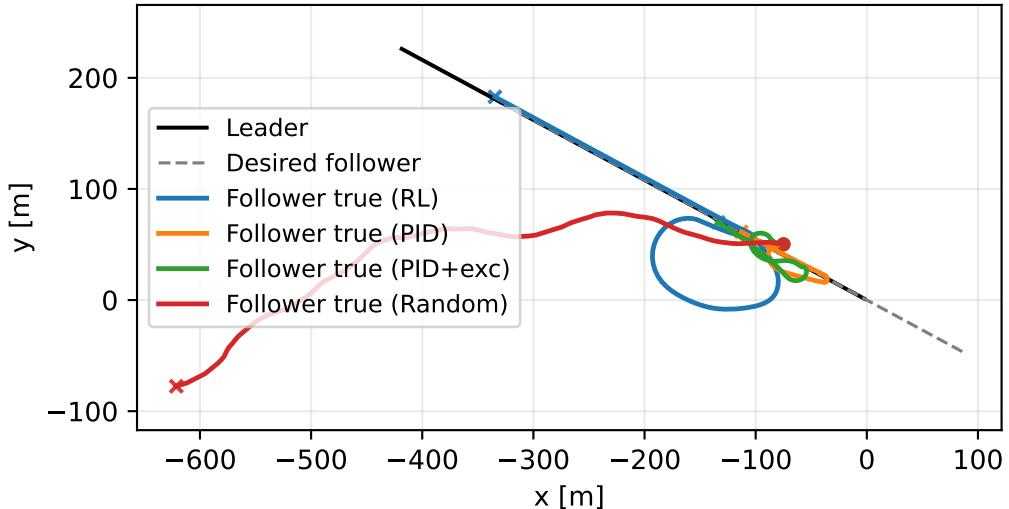
Follower course/heading



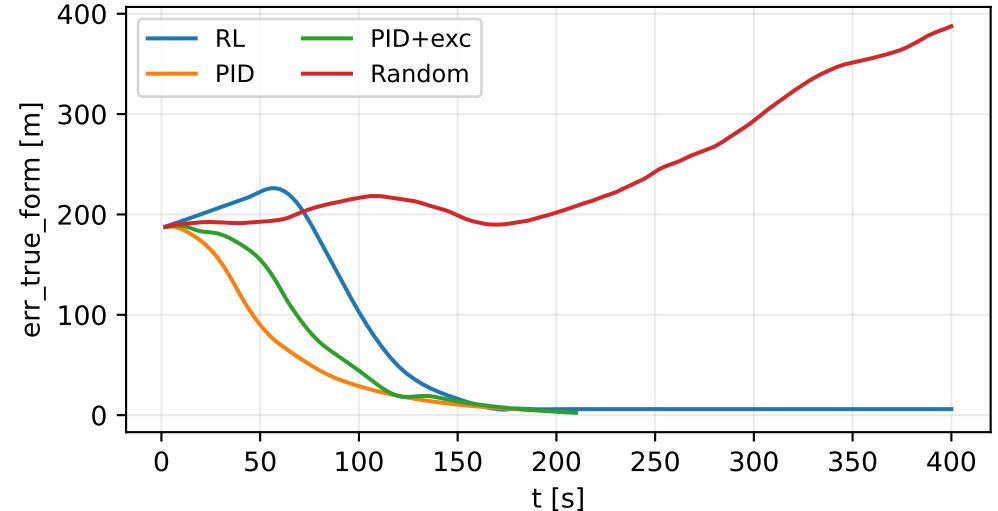
Follower angular rate



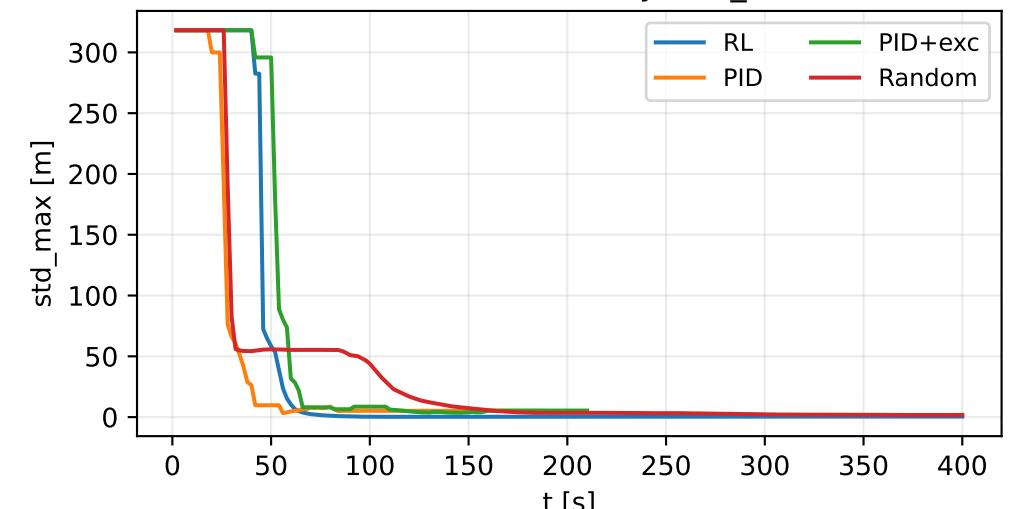
Trajectories (matched seed)



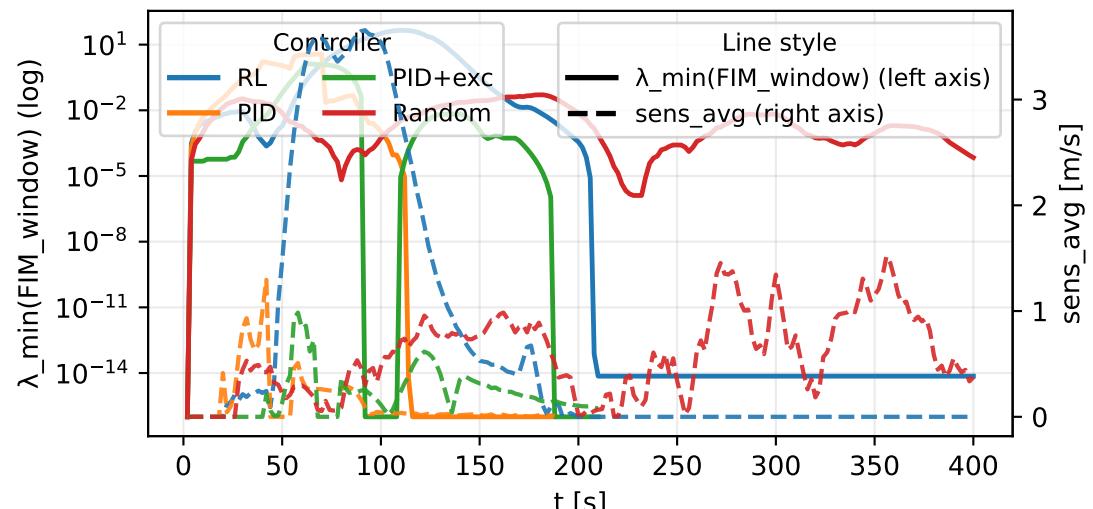
TRUE formation error



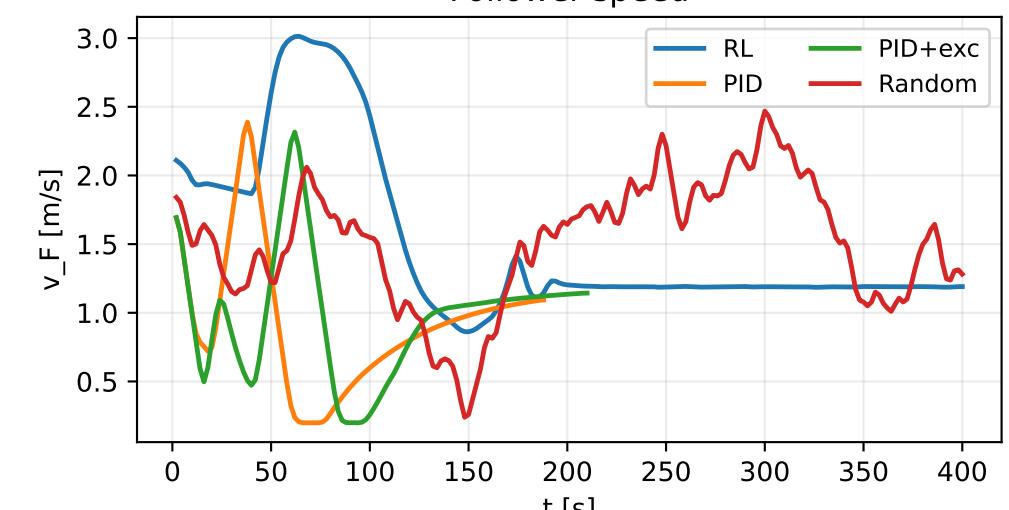
Estimator uncertainty (std_max)



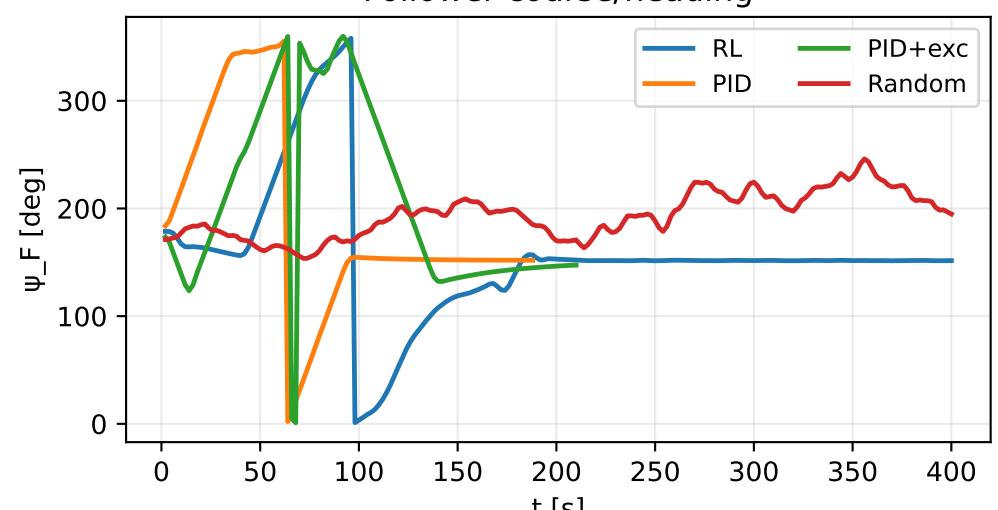
Information and excitation



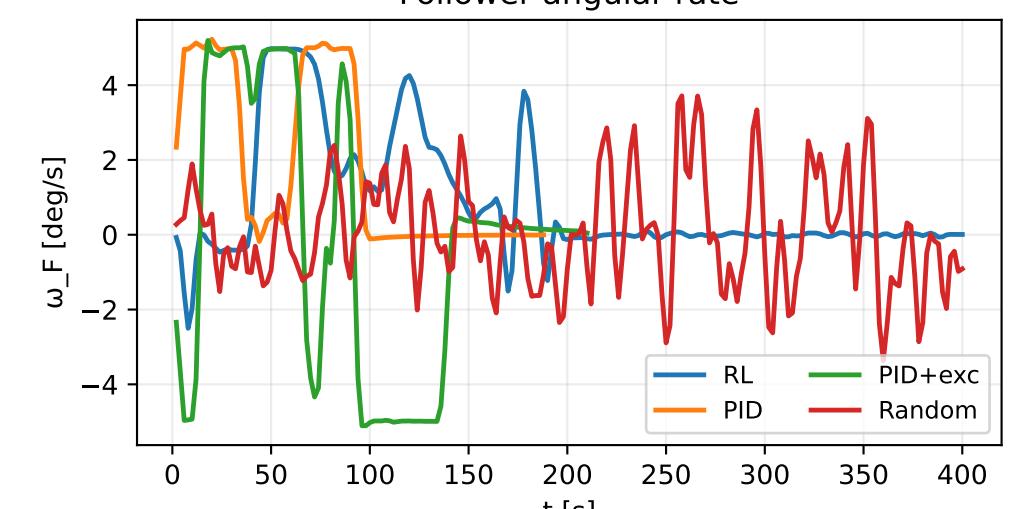
Follower speed



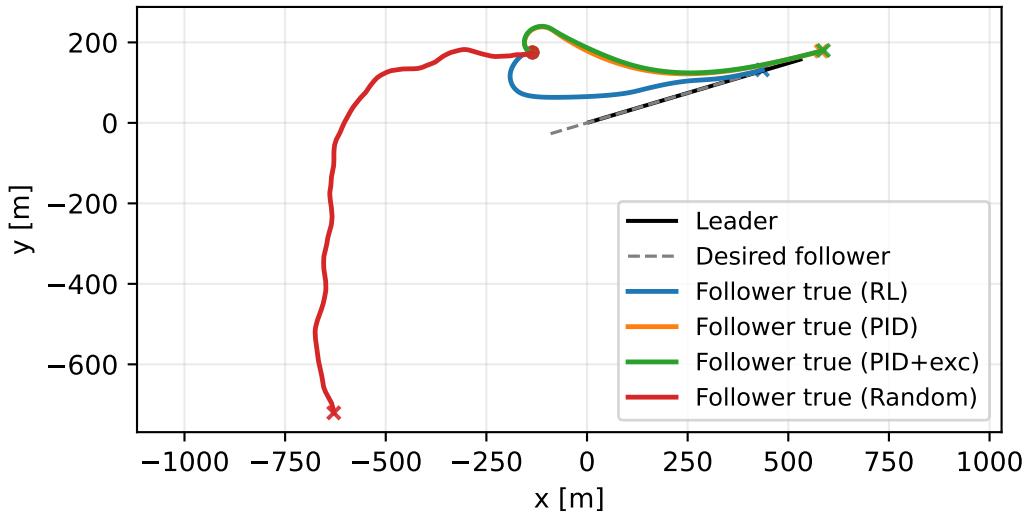
Follower course/heading



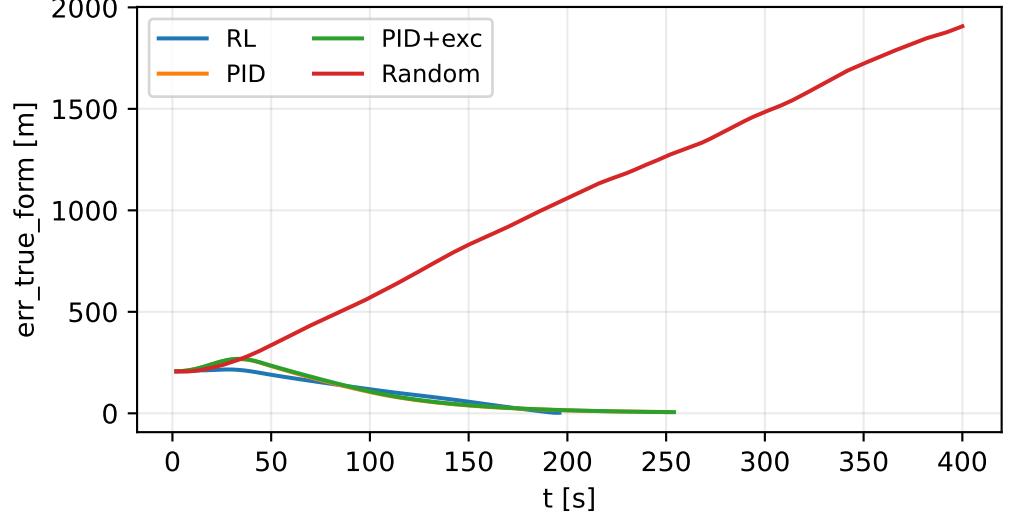
Follower angular rate



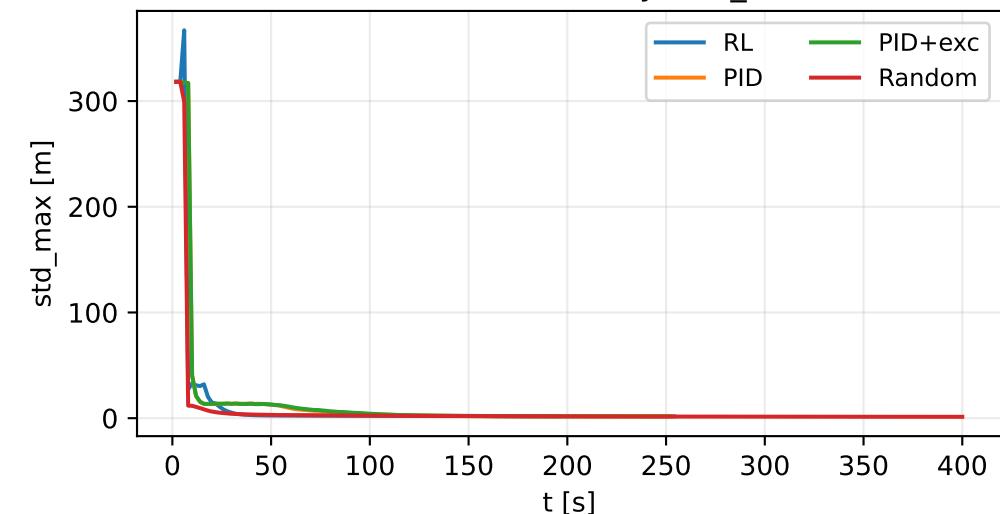
Trajectories (matched seed)



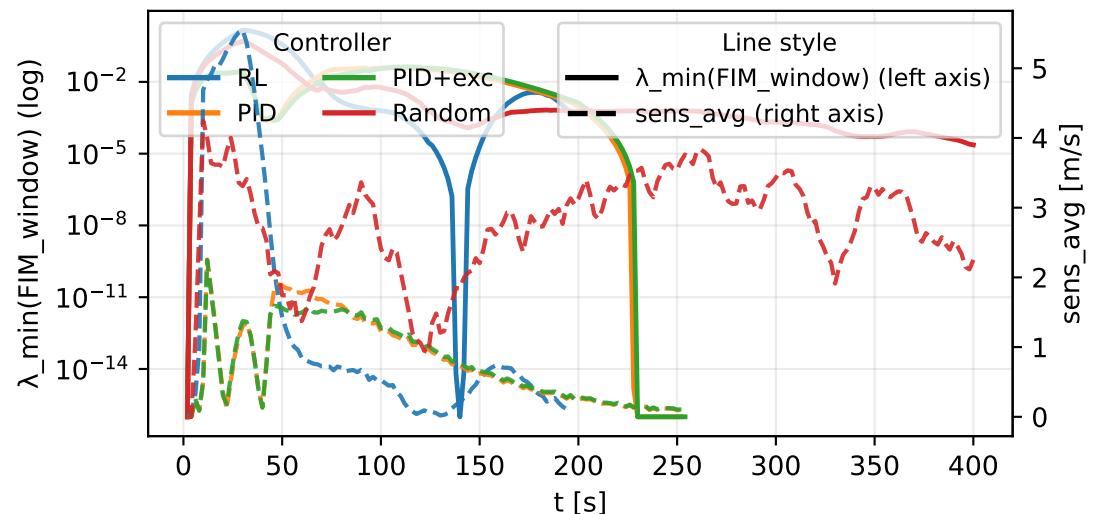
TRUE formation error



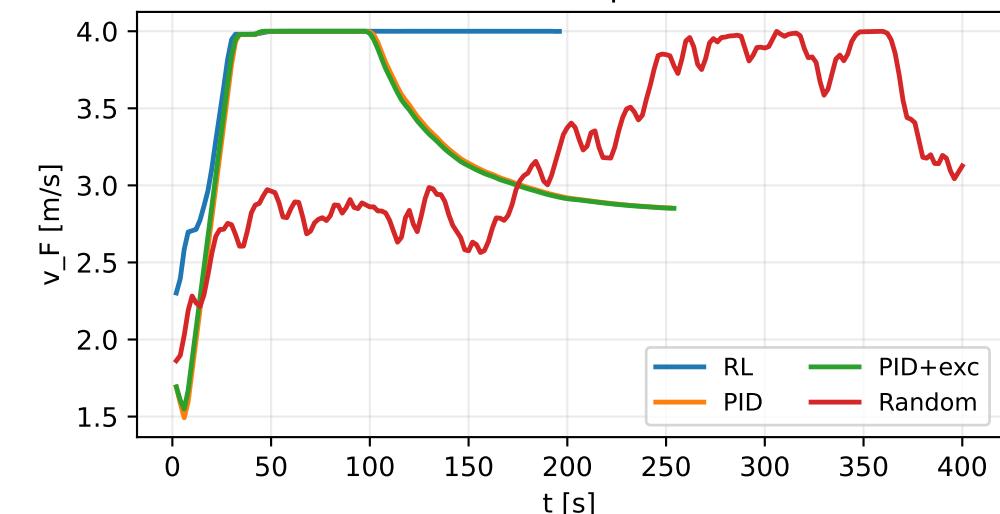
Estimator uncertainty (std_max)



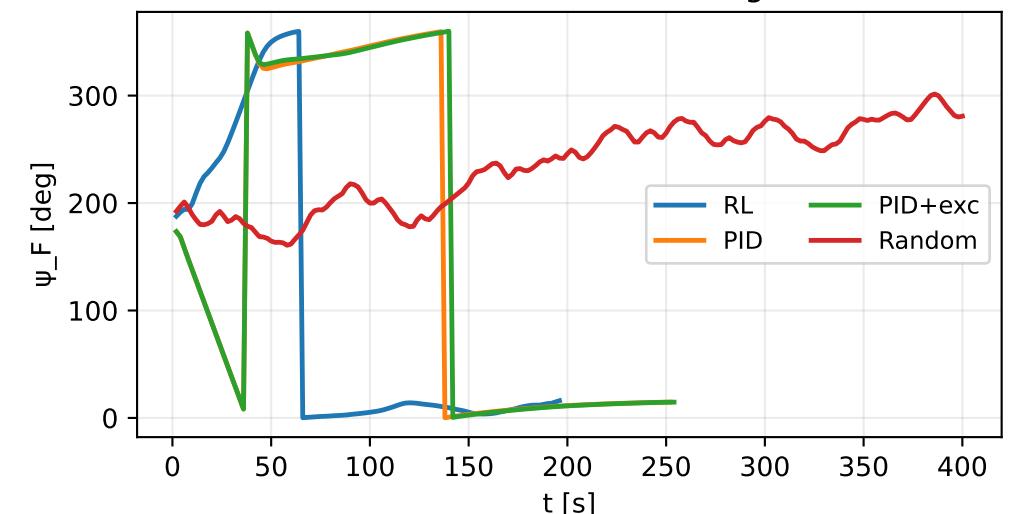
Information and excitation



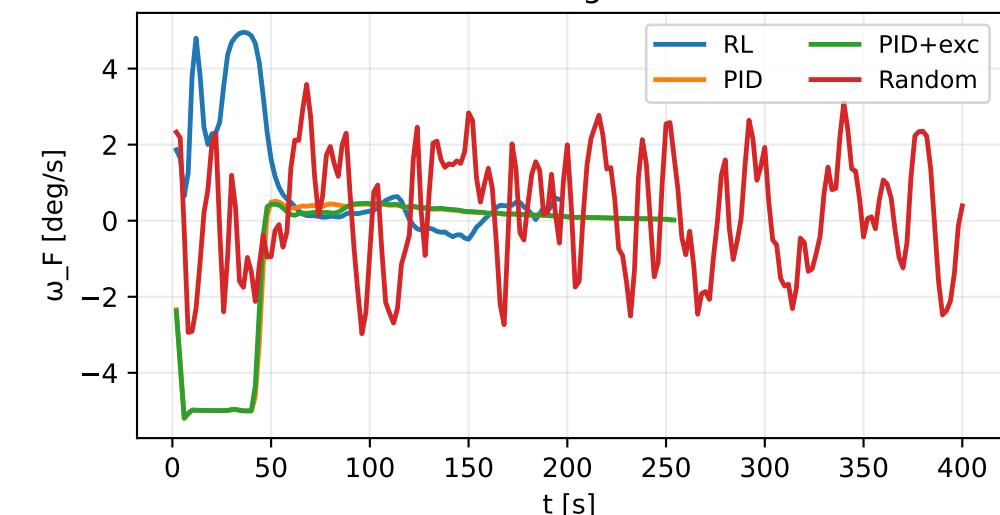
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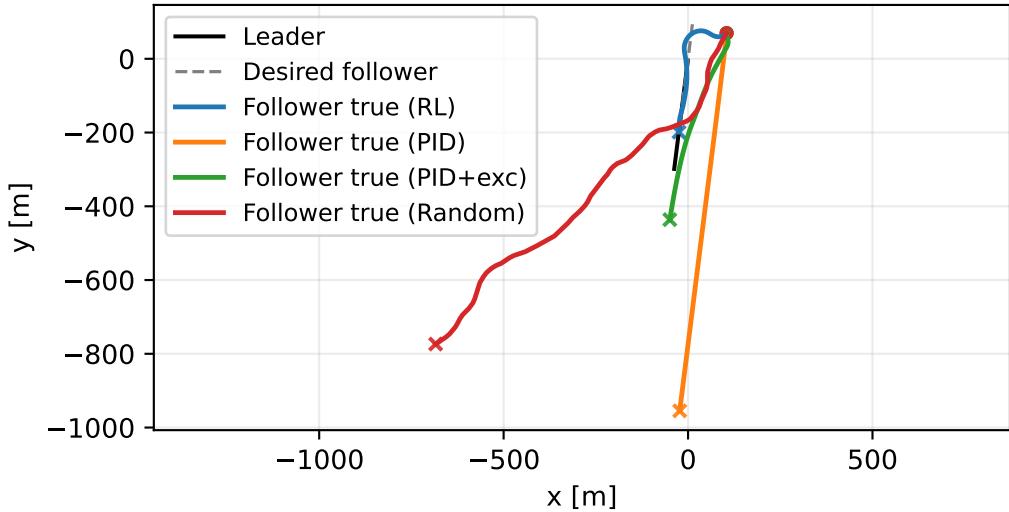
Follower course/heading



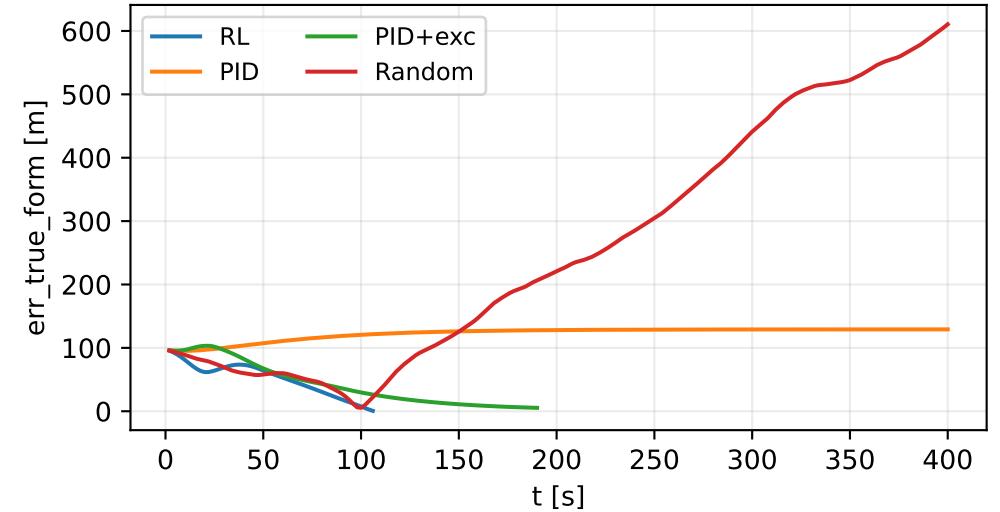
Follower angular rate



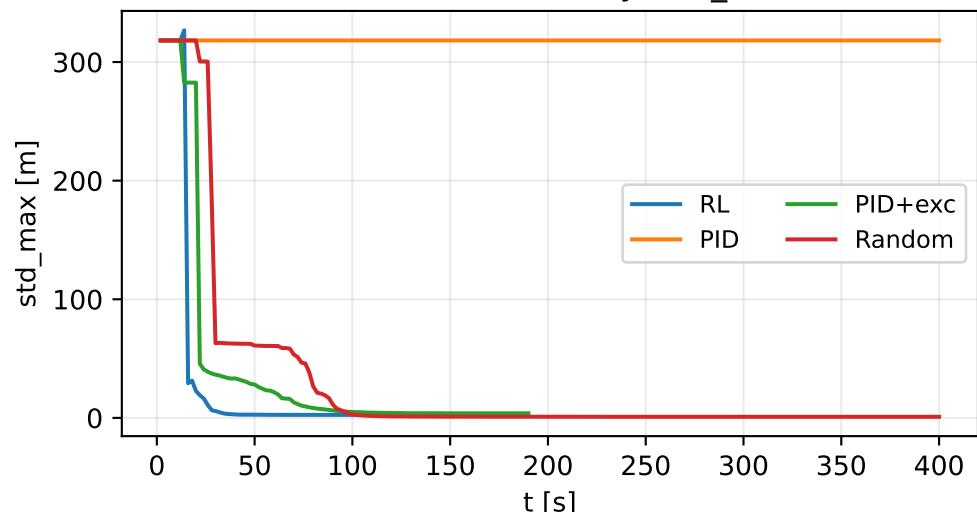
Trajectories (matched seed)



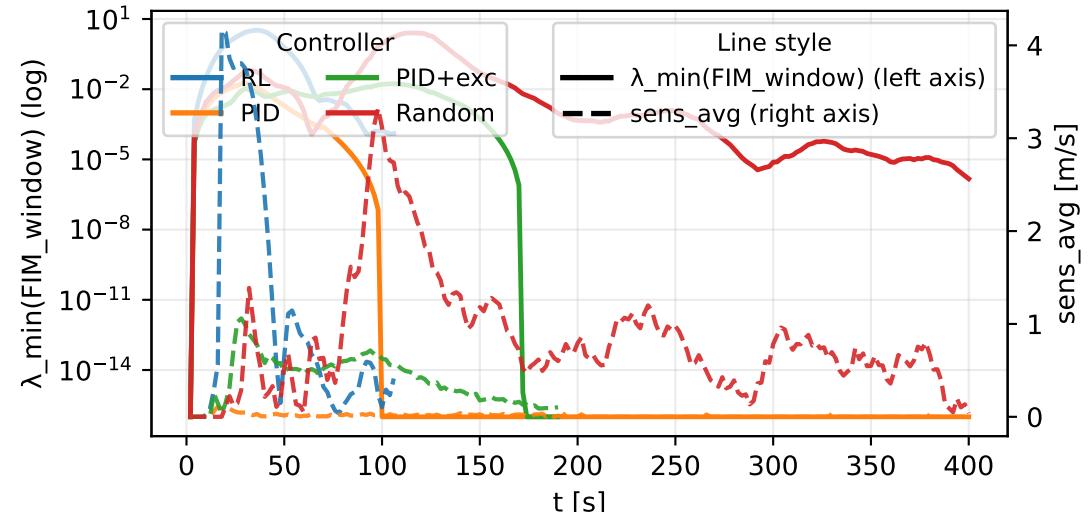
TRUE formation error



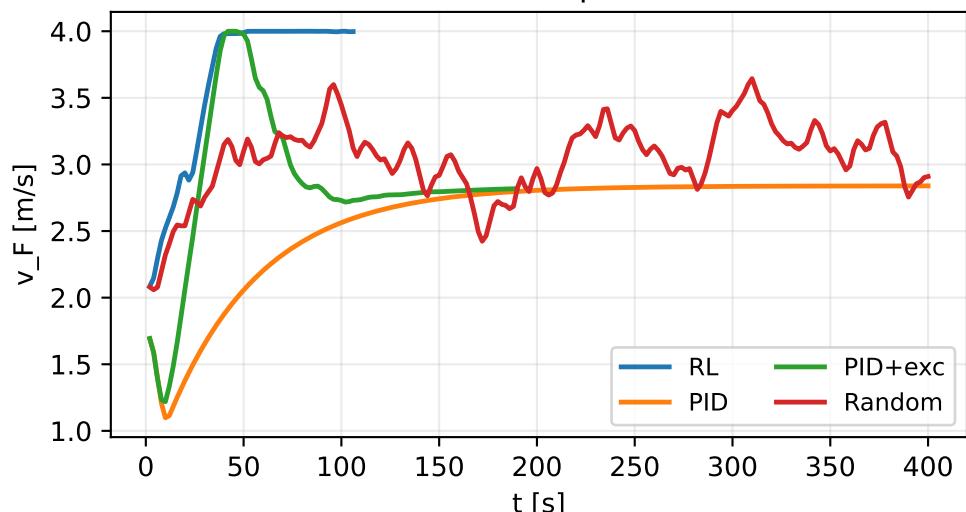
Estimator uncertainty (std_max)



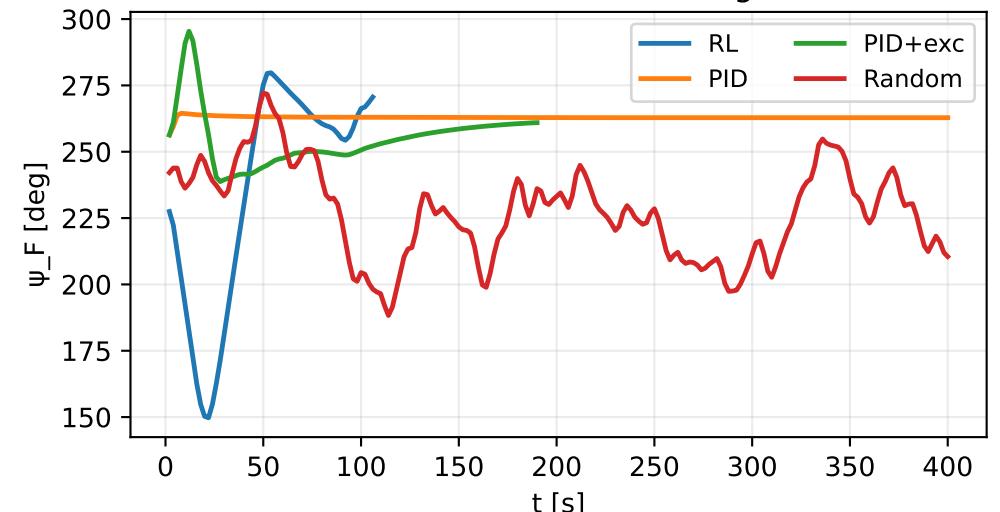
Information and excitation



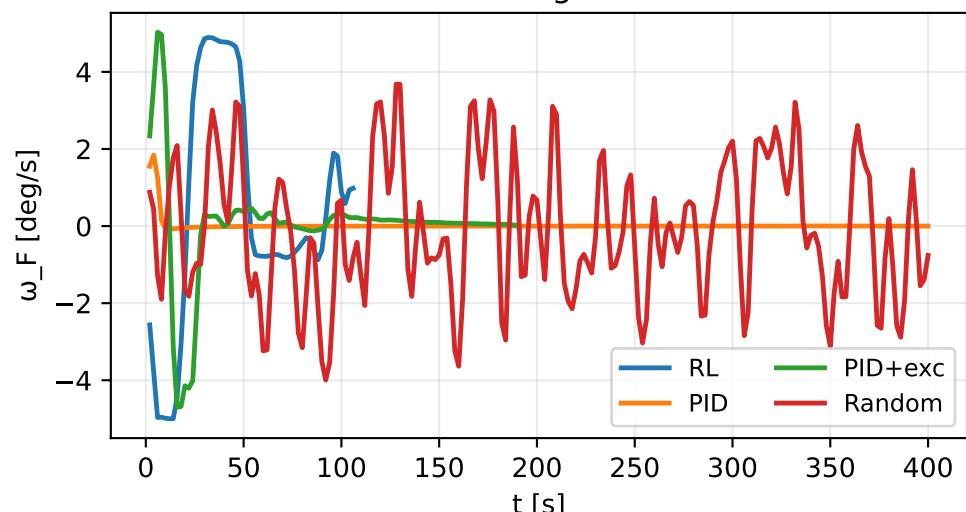
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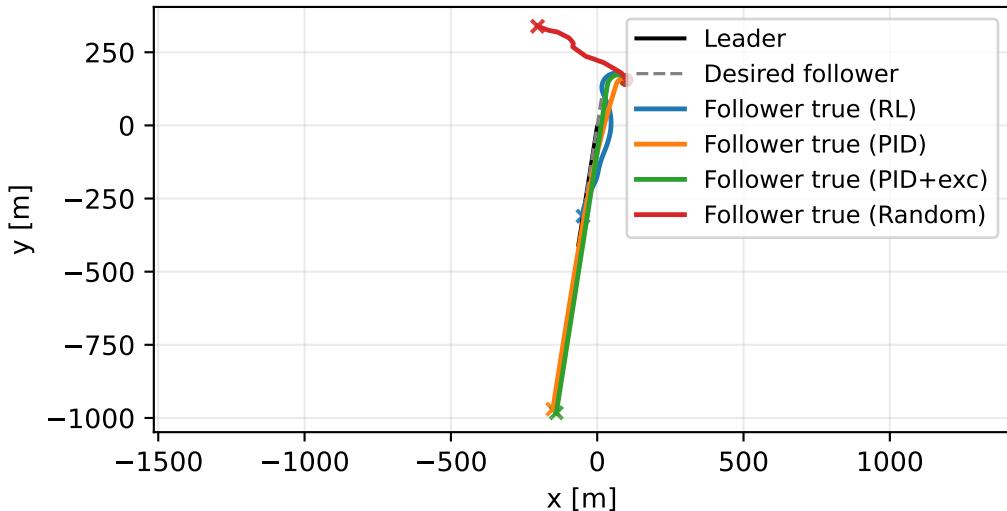
Follower course/heading



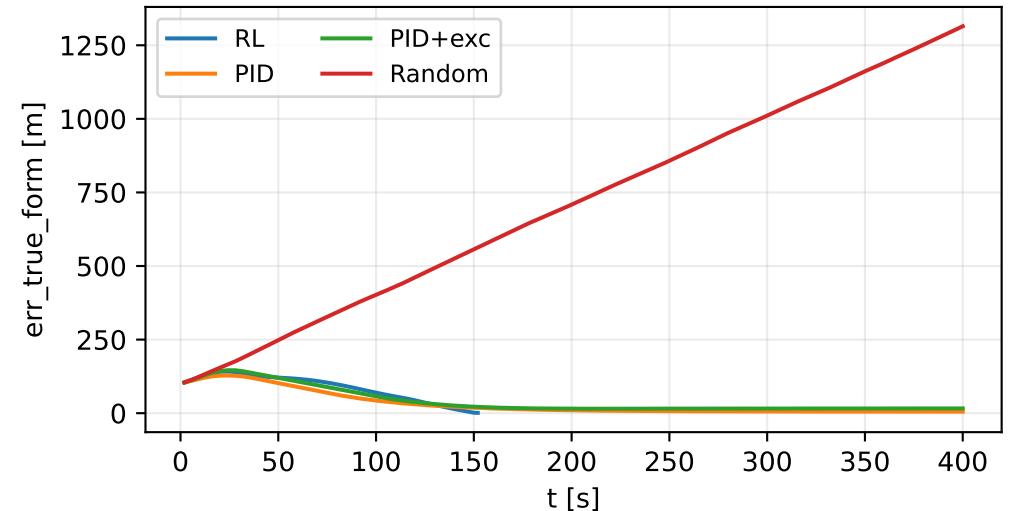
Follower angular rate



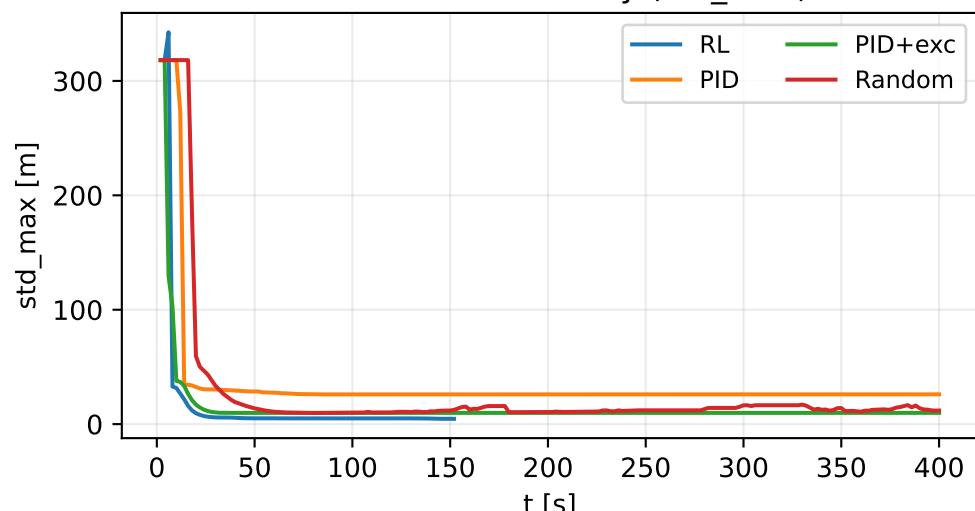
Trajectories (matched seed)



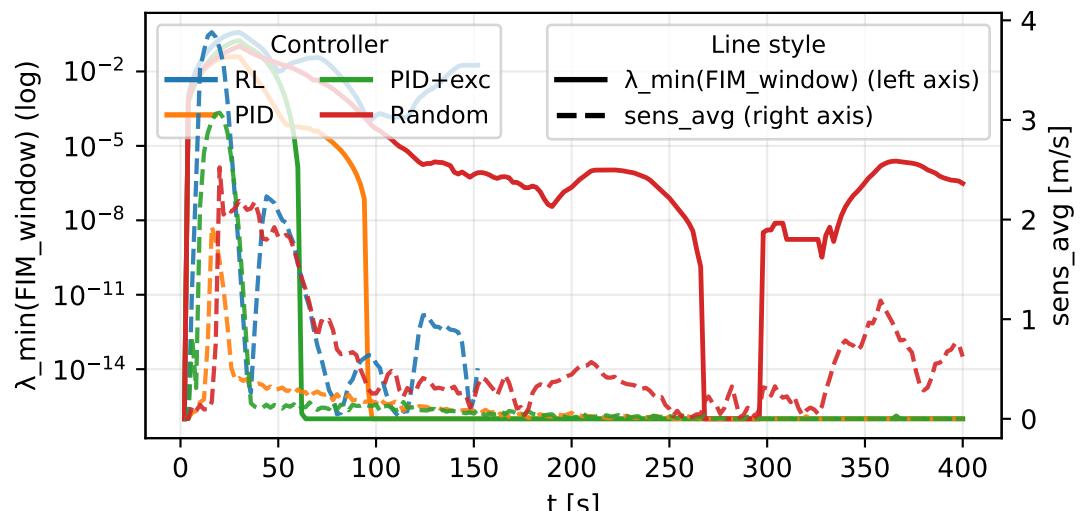
TRUE formation error



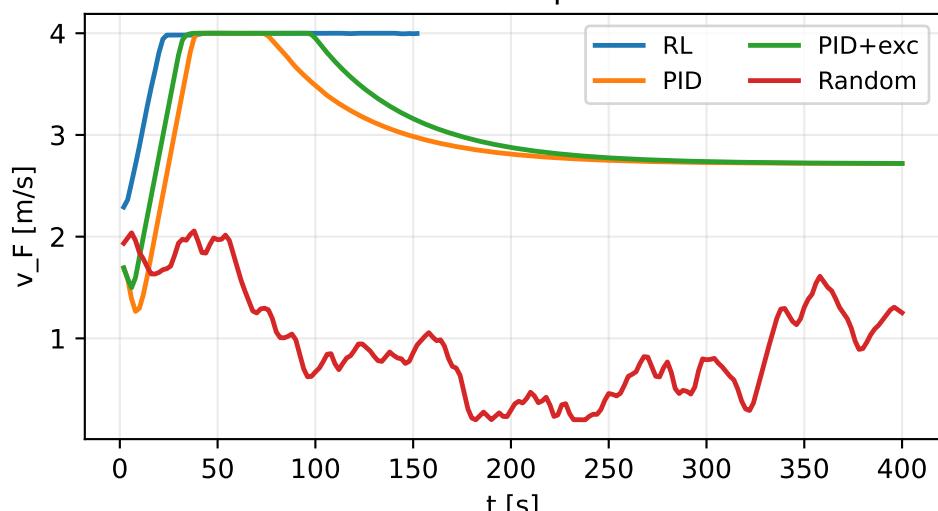
Estimator uncertainty (std_max)



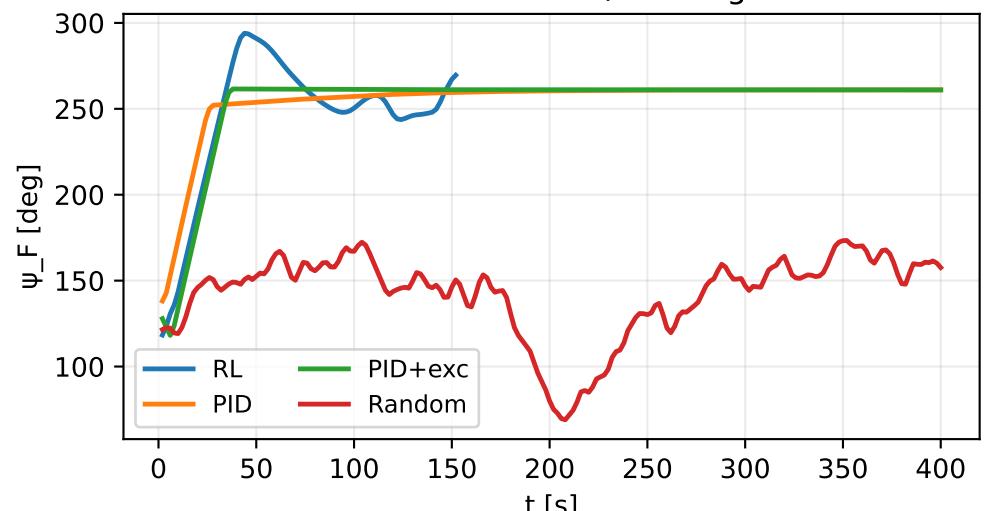
Information and excitation



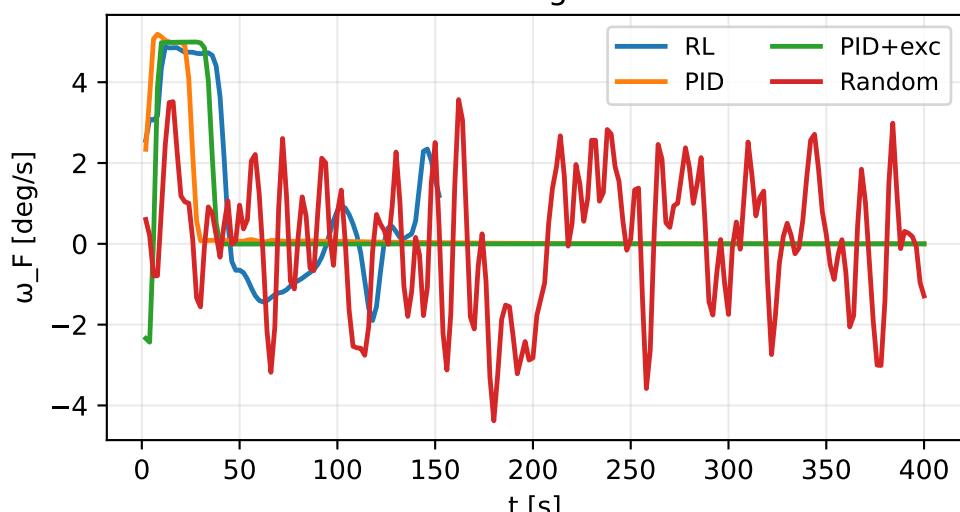
Follower speed



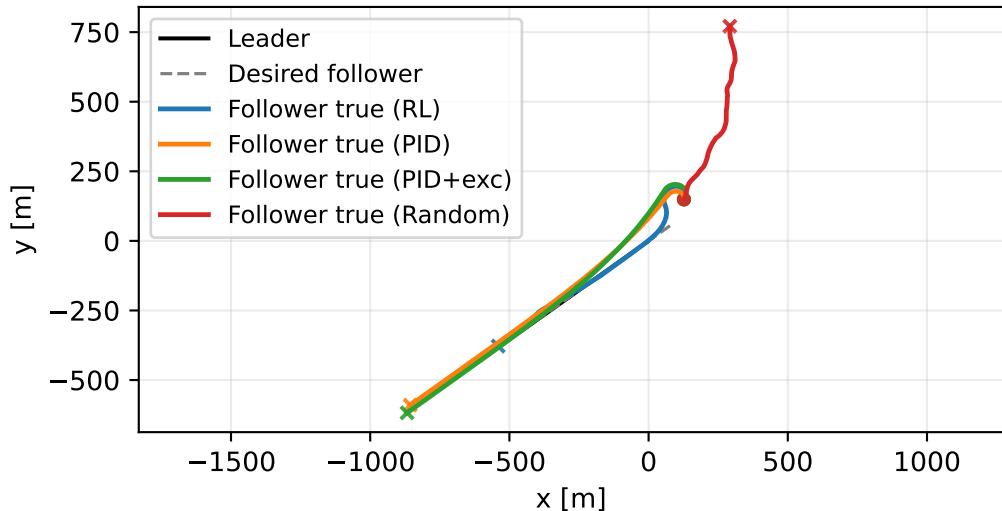
Follower course/heading



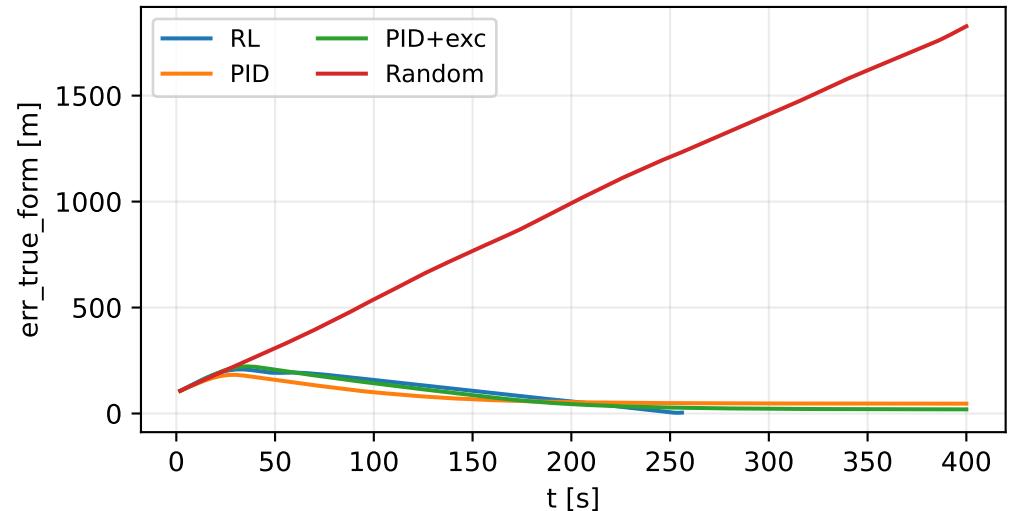
Follower angular rate



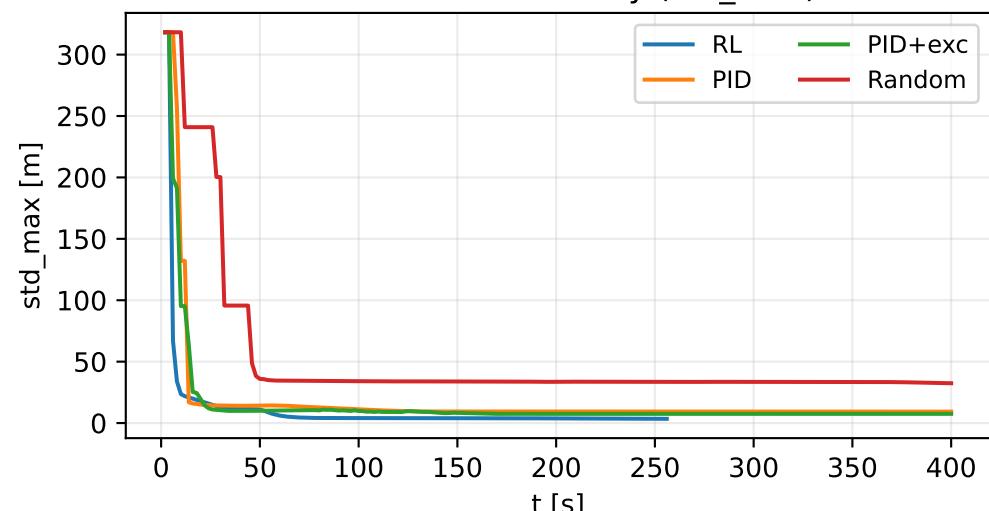
Trajectories (matched seed)



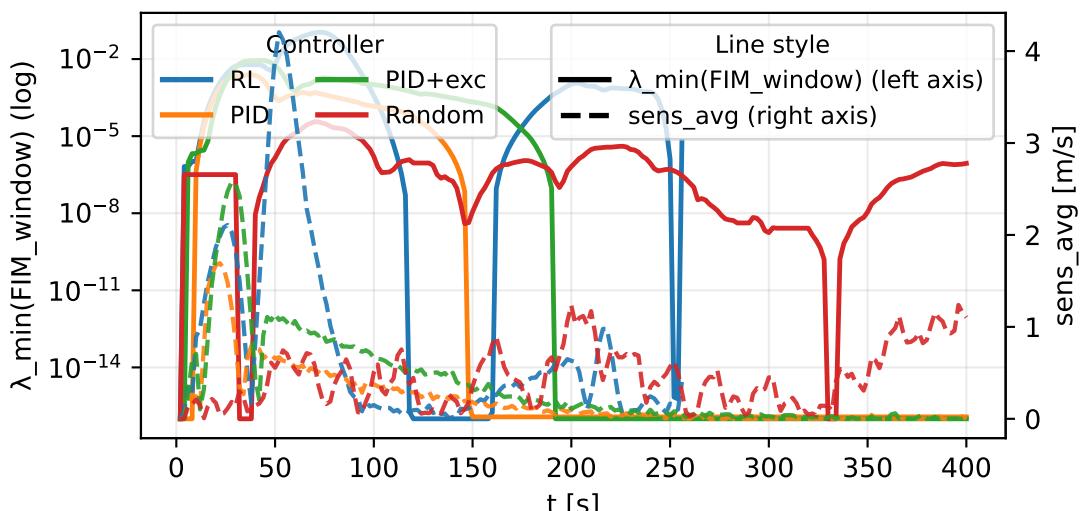
TRUE formation error



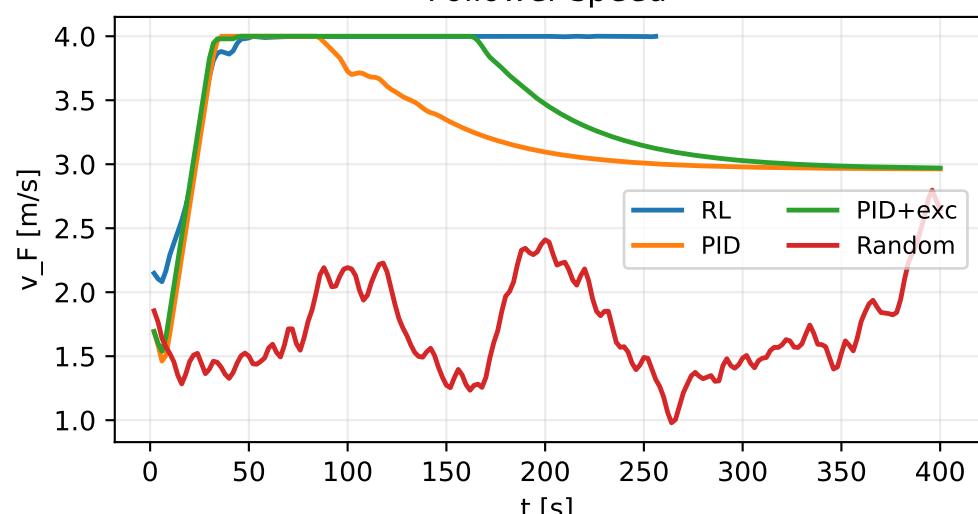
Estimator uncertainty (std_max)



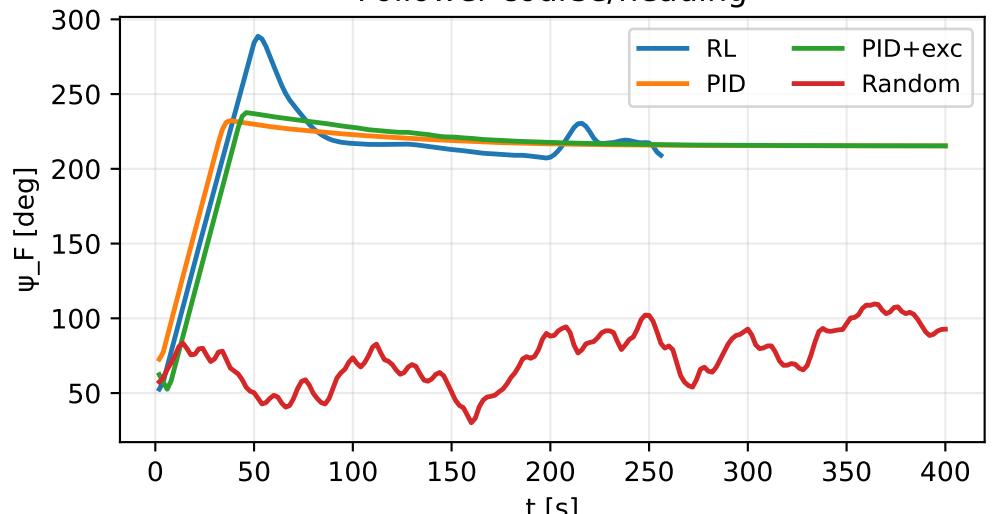
Information and excitation



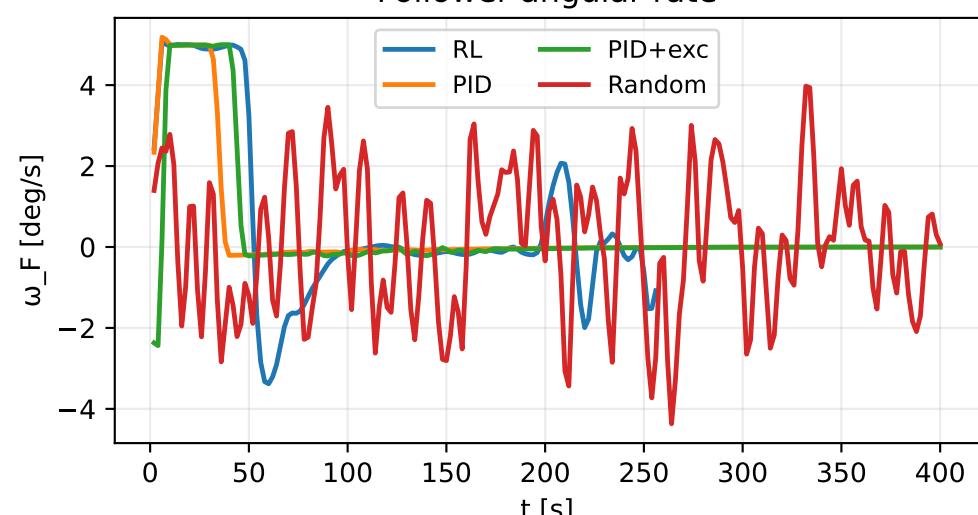
Follower speed



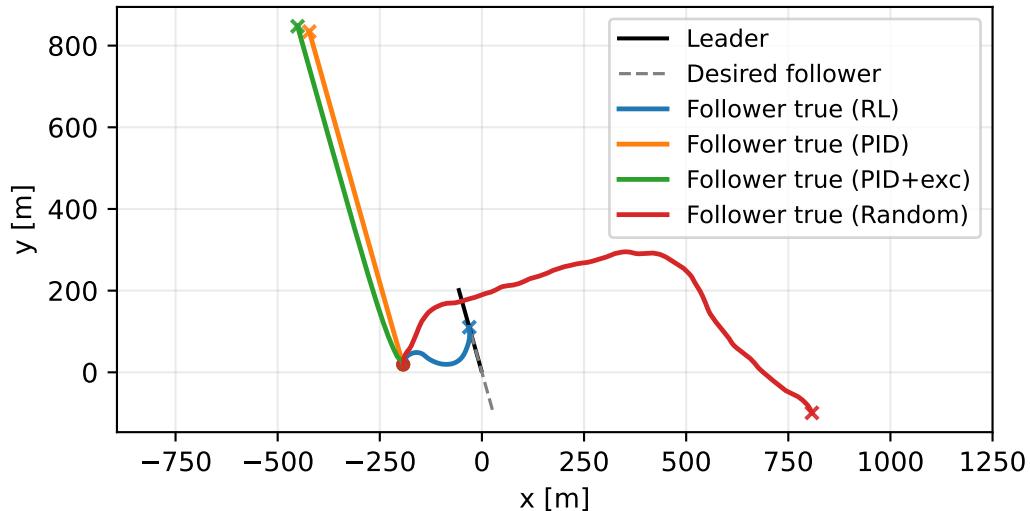
Follower course/heading



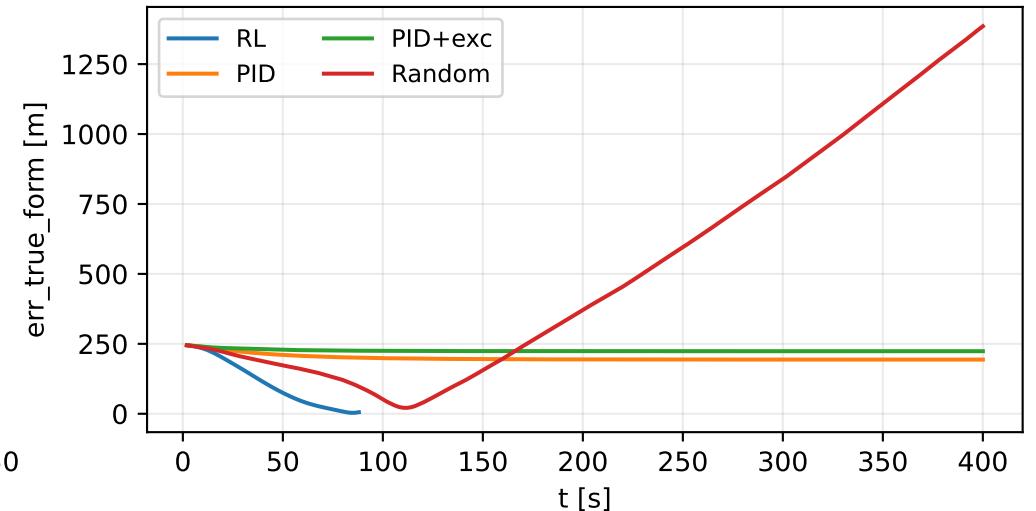
Follower angular rate



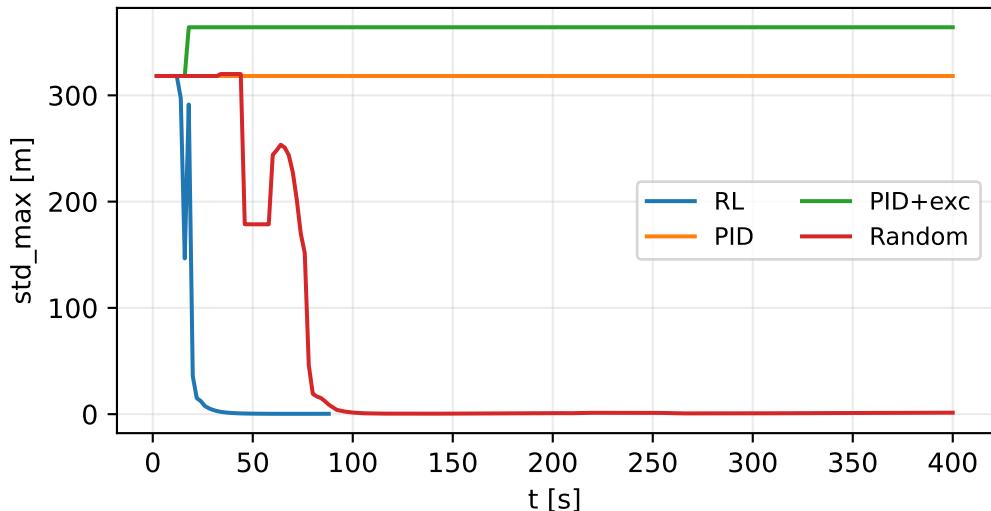
Trajectories (matched seed)



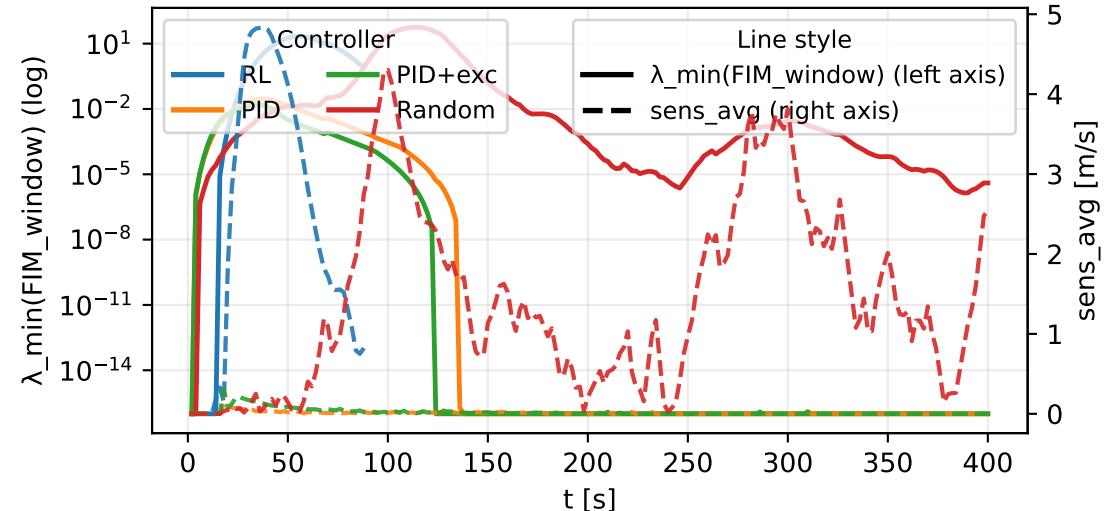
TRUE formation error



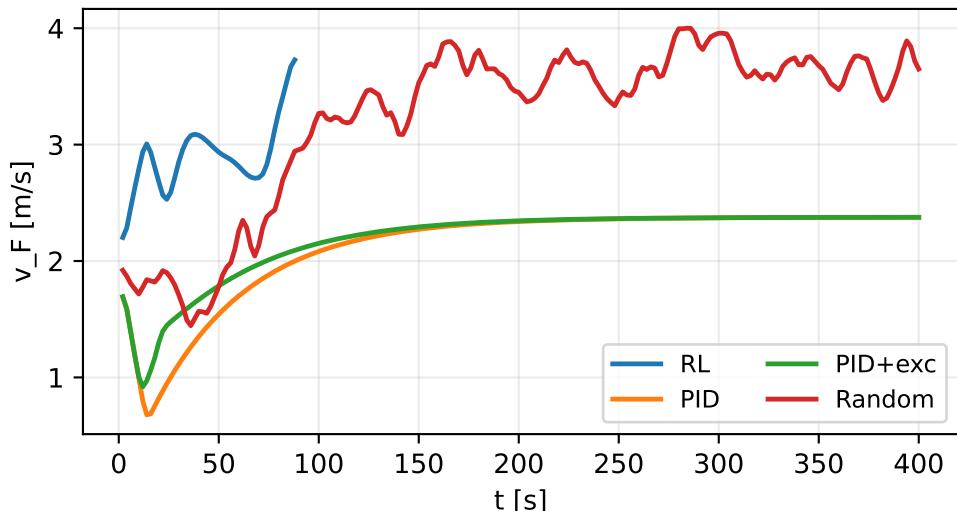
Estimator uncertainty (std_max)



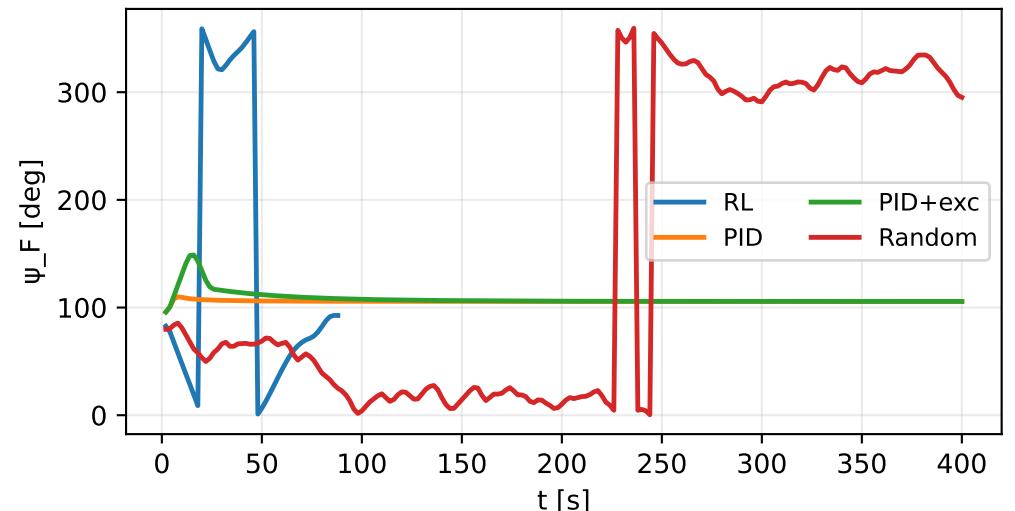
Information and excitation



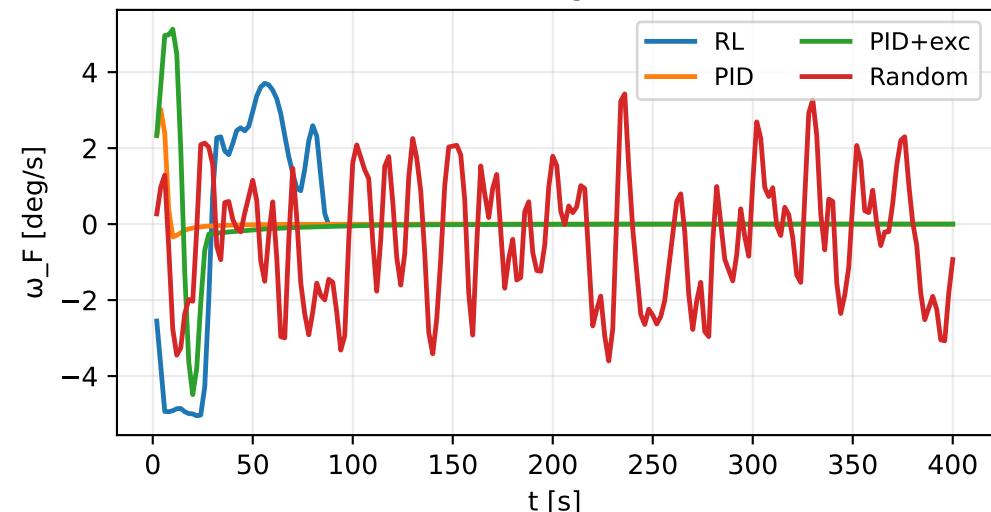
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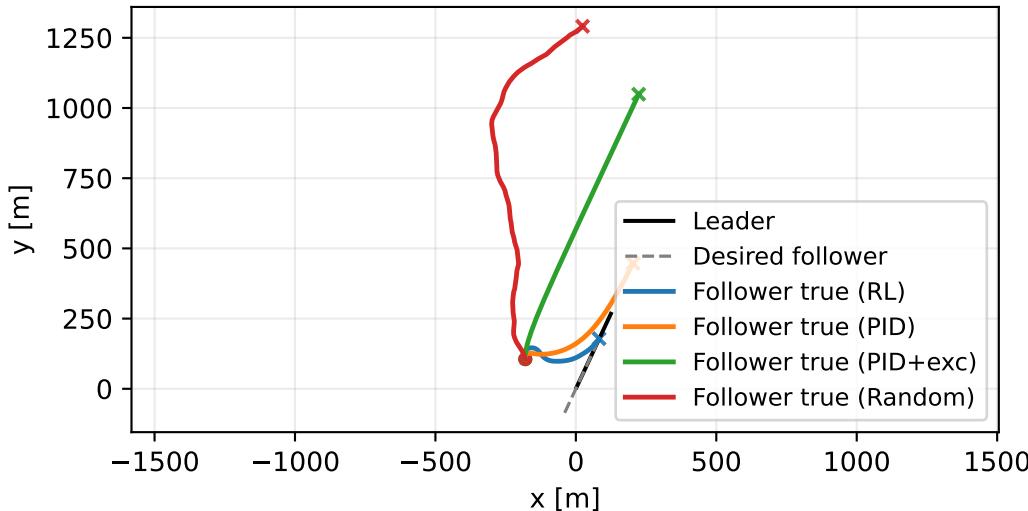
Follower course/heading



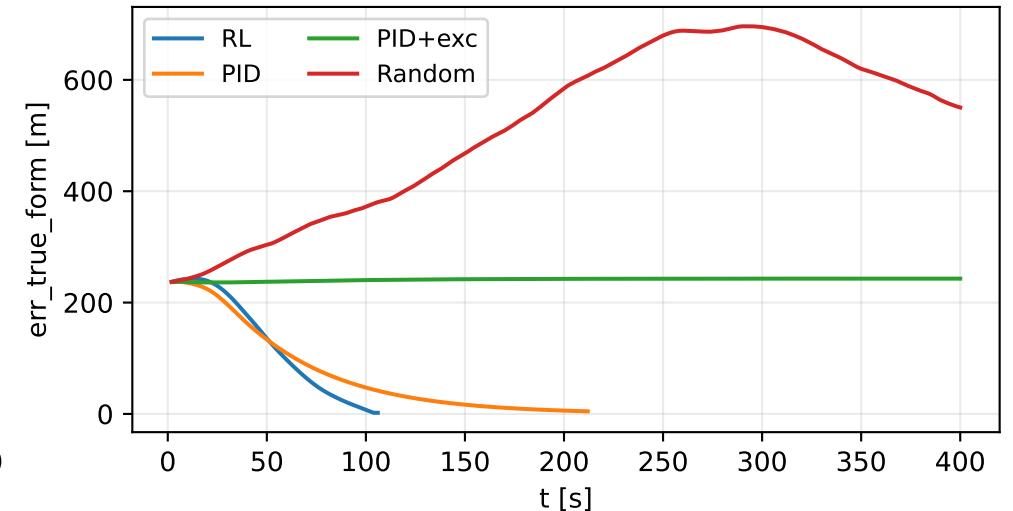
Follower angular rate



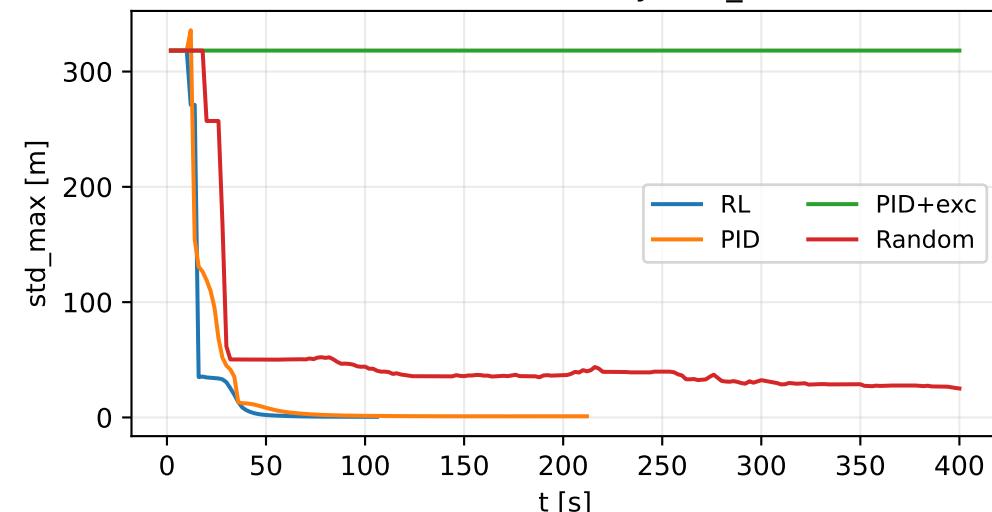
Trajectories (matched seed)



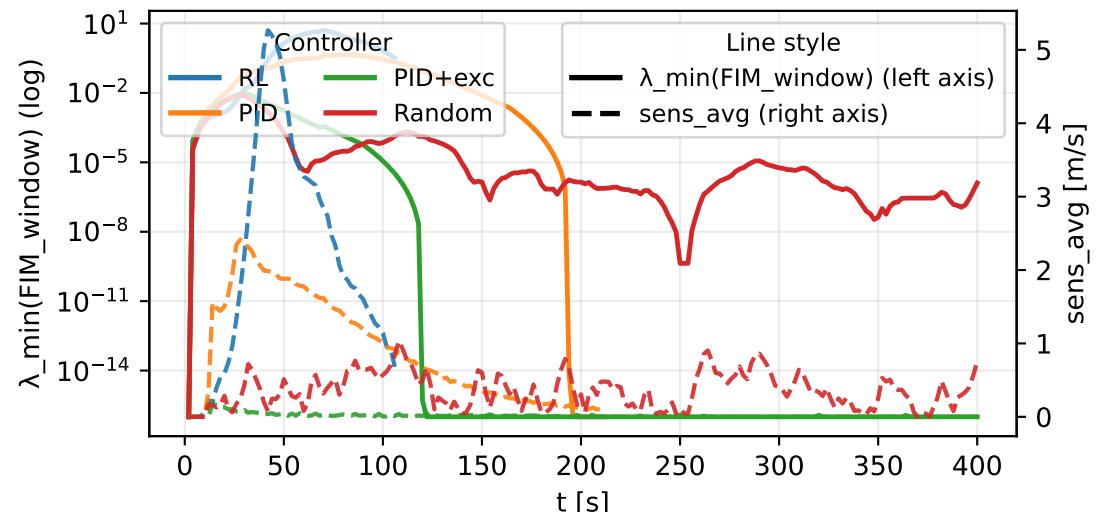
TRUE formation error



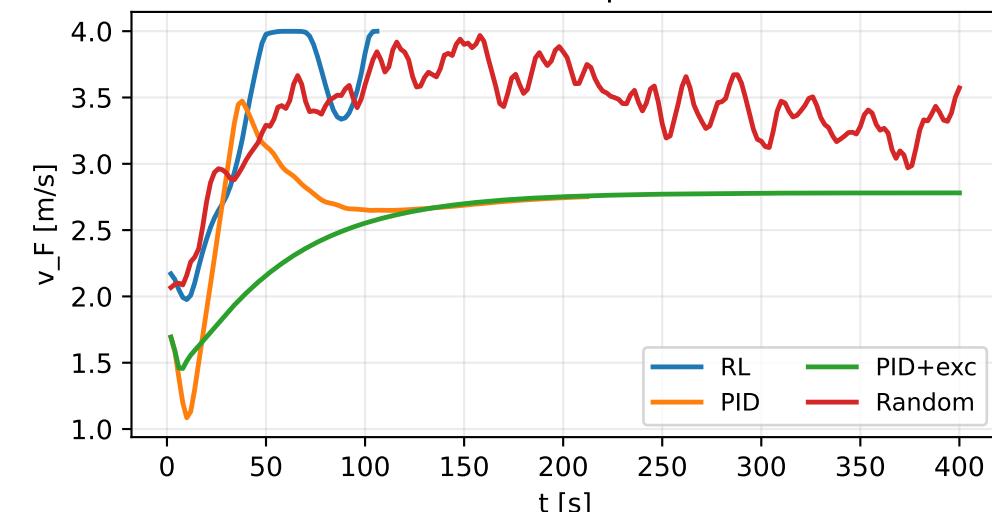
Estimator uncertainty (std_max)



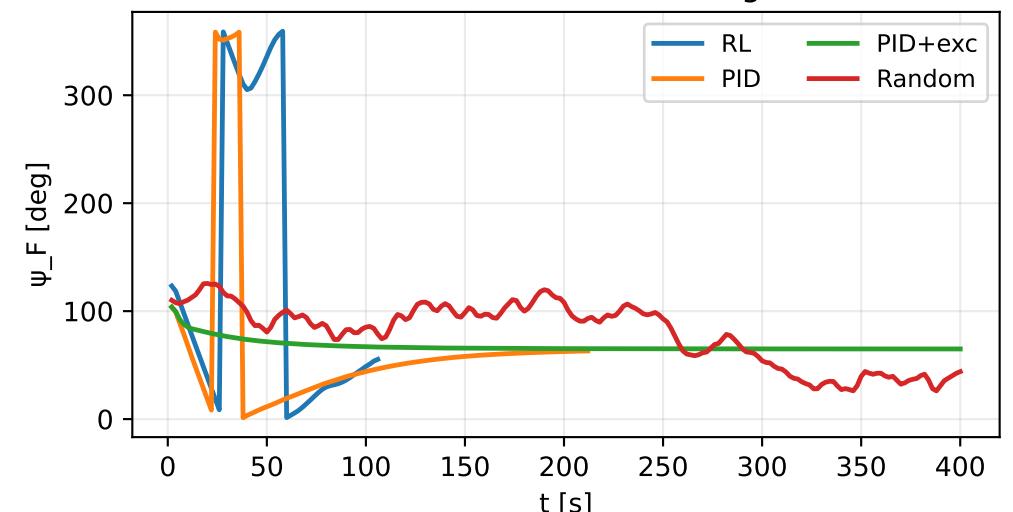
Information and excitation



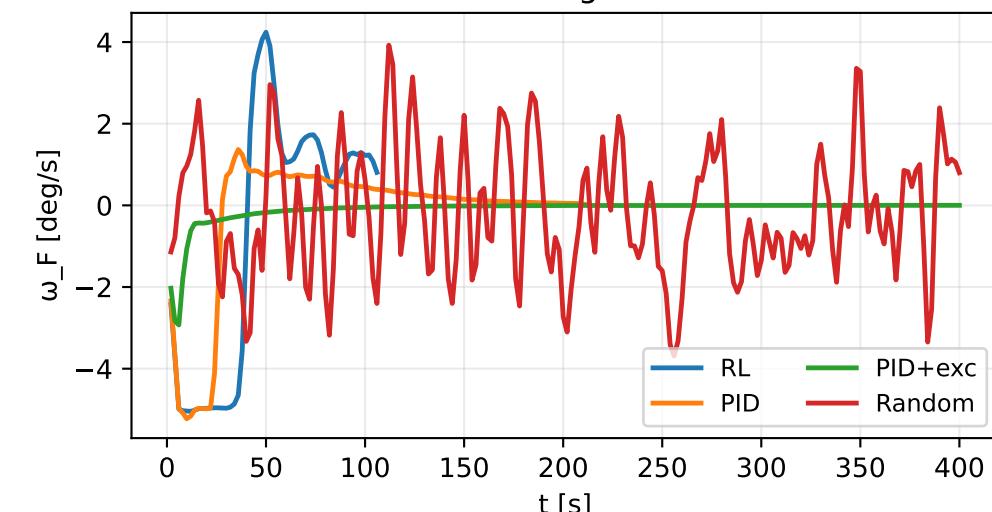
Follower speed



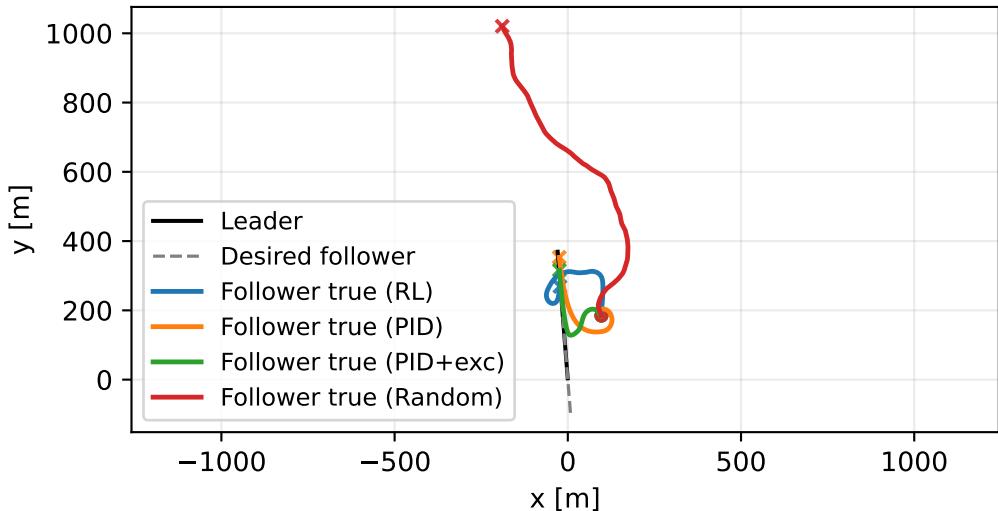
Follower course/heading



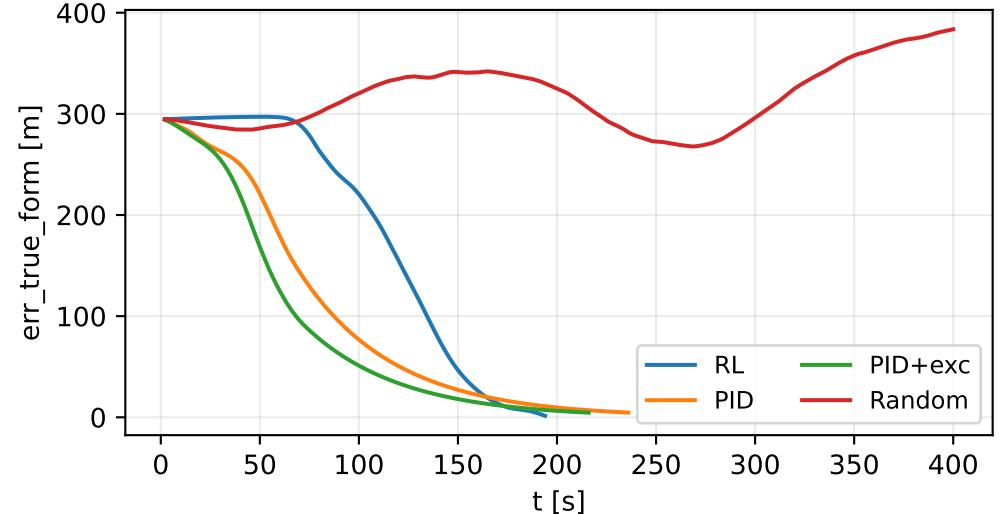
Follower angular rate



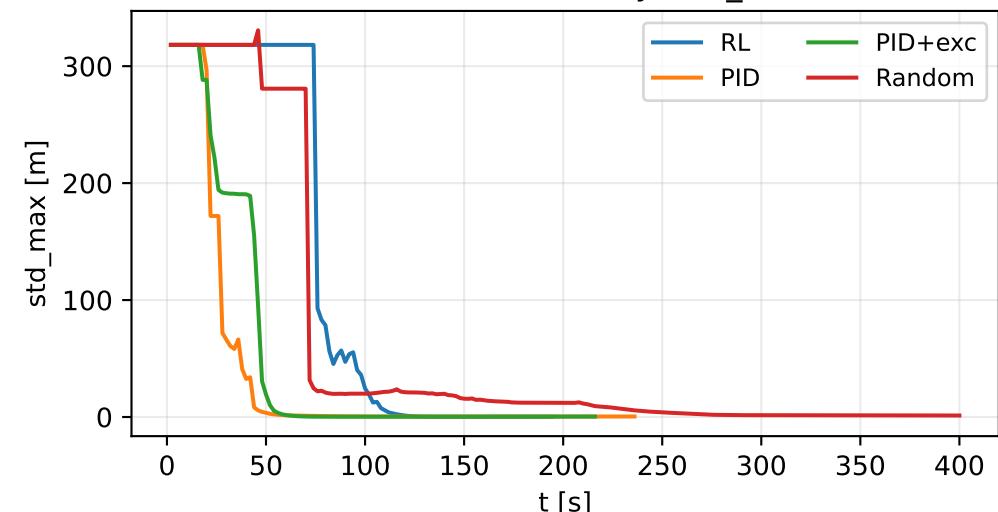
Trajectories (matched seed)



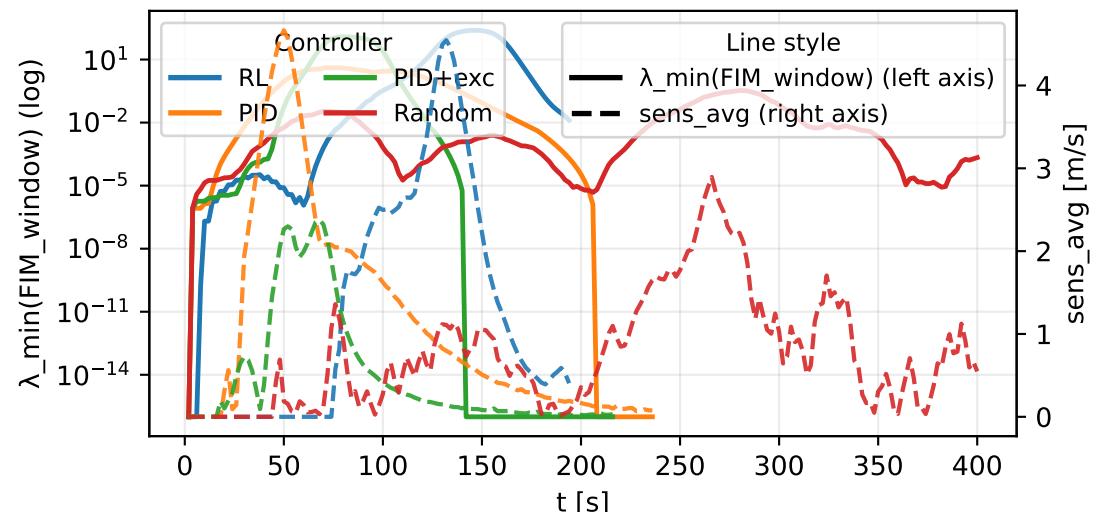
TRUE formation error



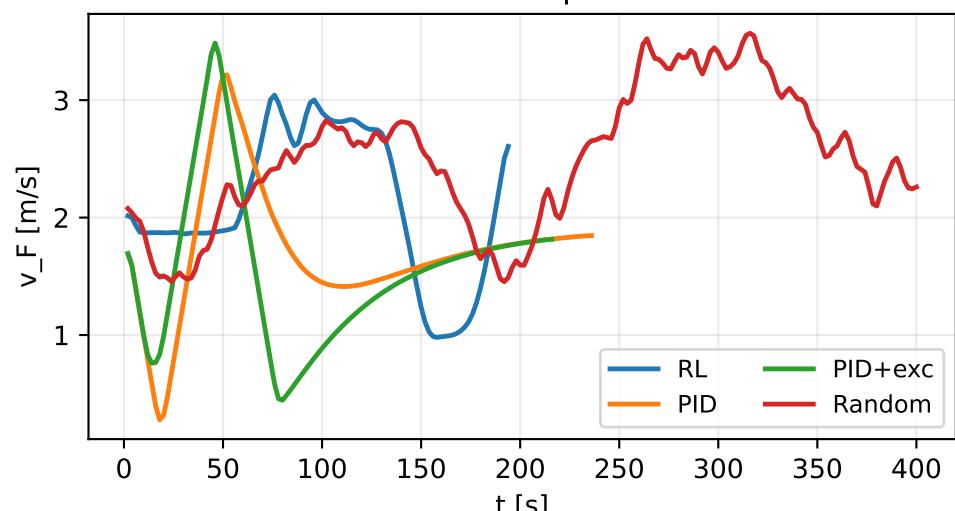
Estimator uncertainty (std_max)



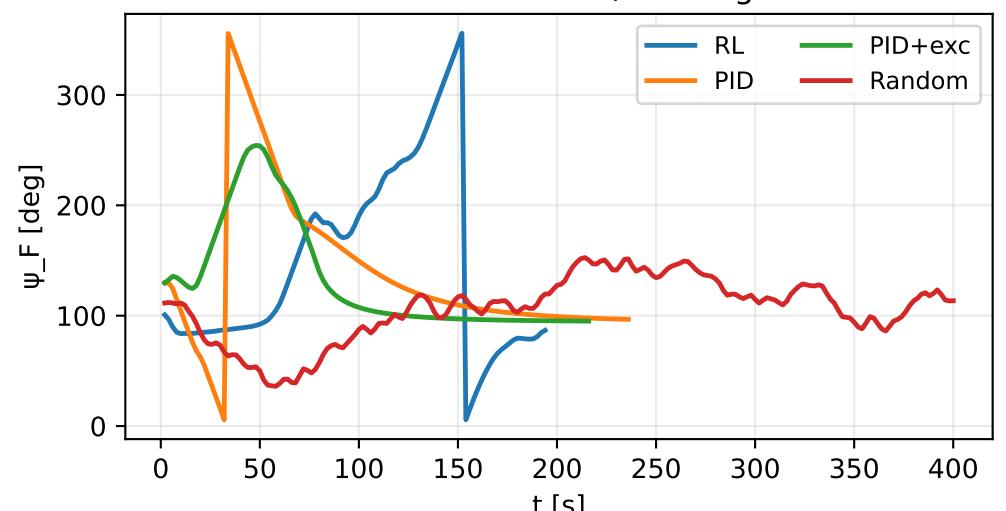
Information and excitation



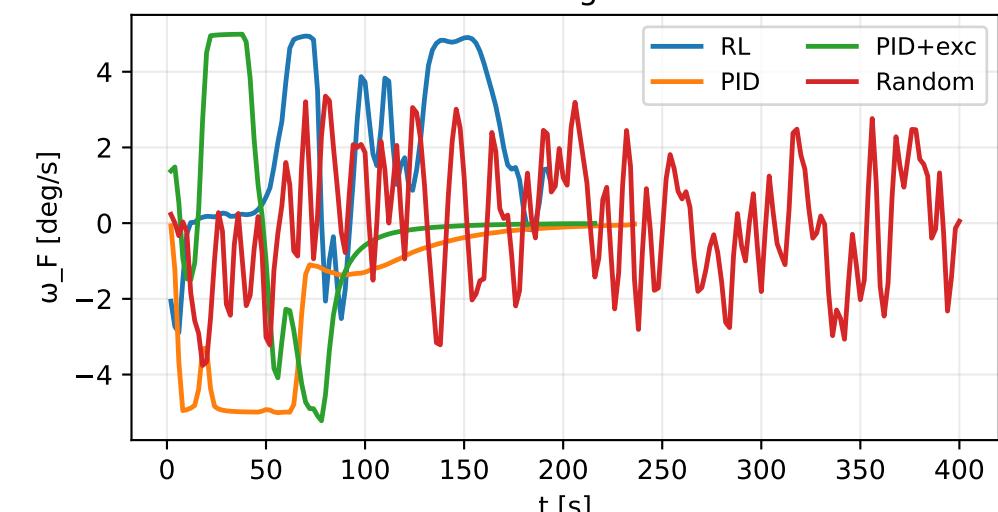
Follower speed



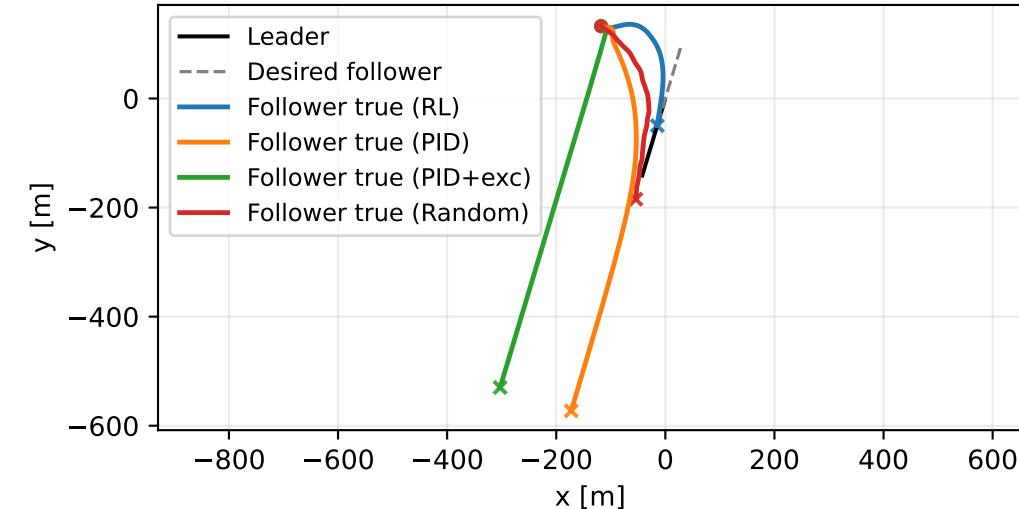
Follower course/heading



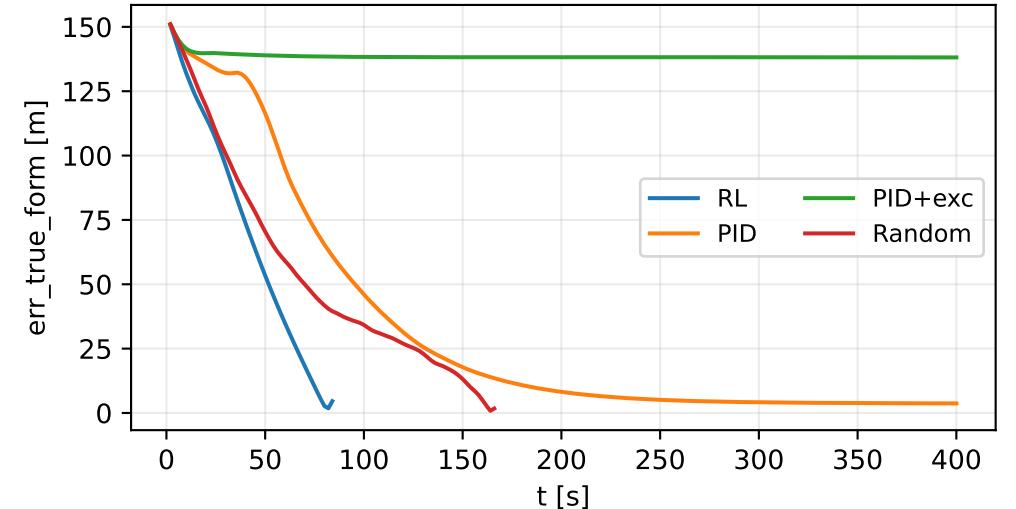
Follower angular rate



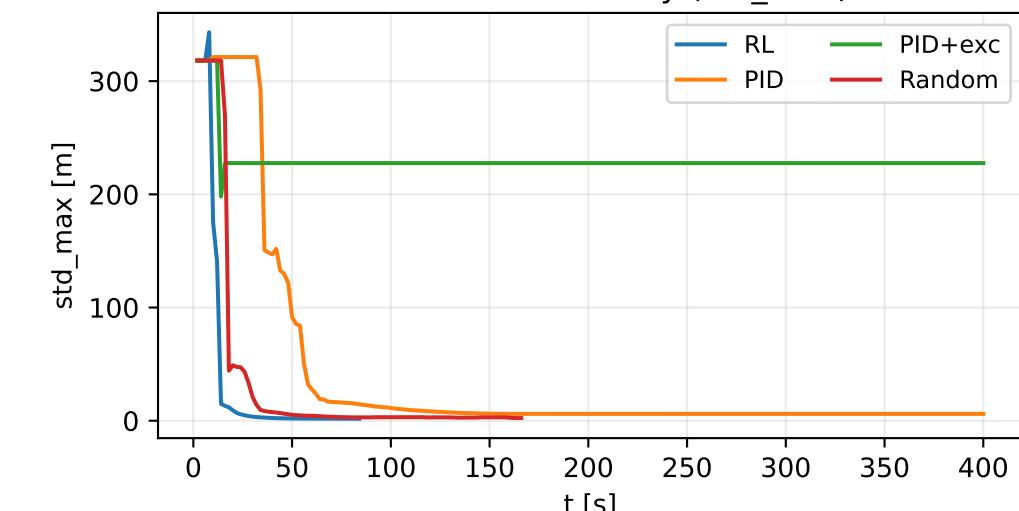
Trajectories (matched seed)



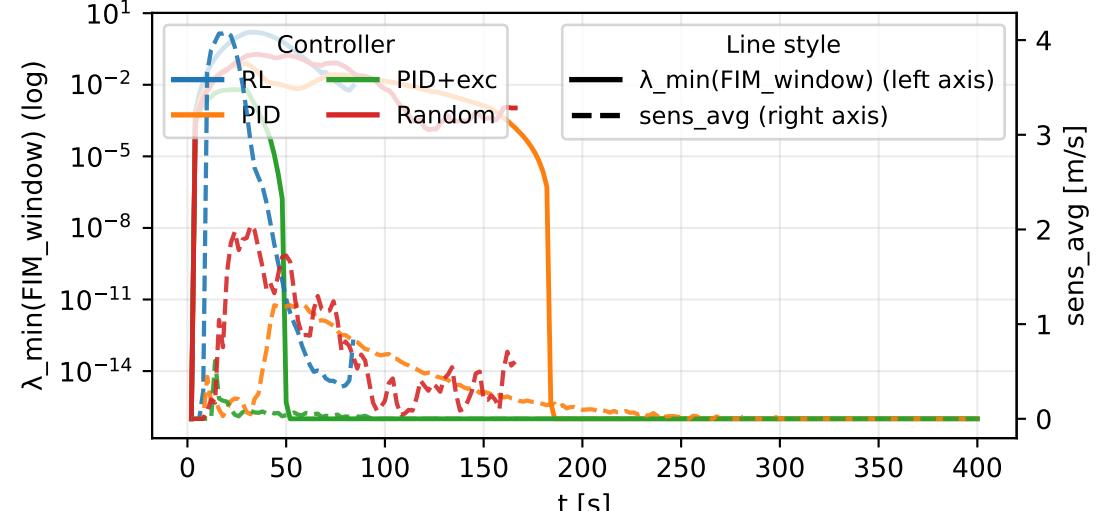
TRUE formation error



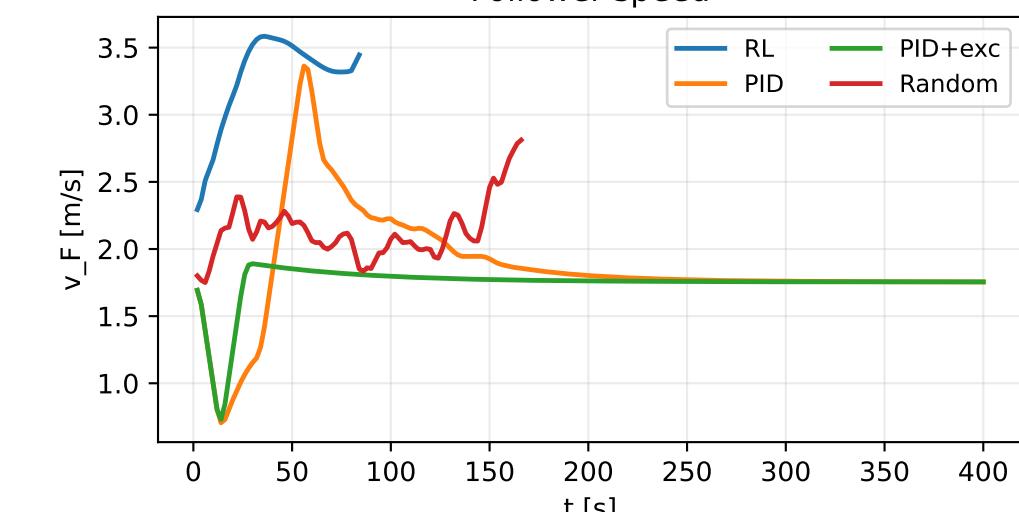
Estimator uncertainty (std_max)



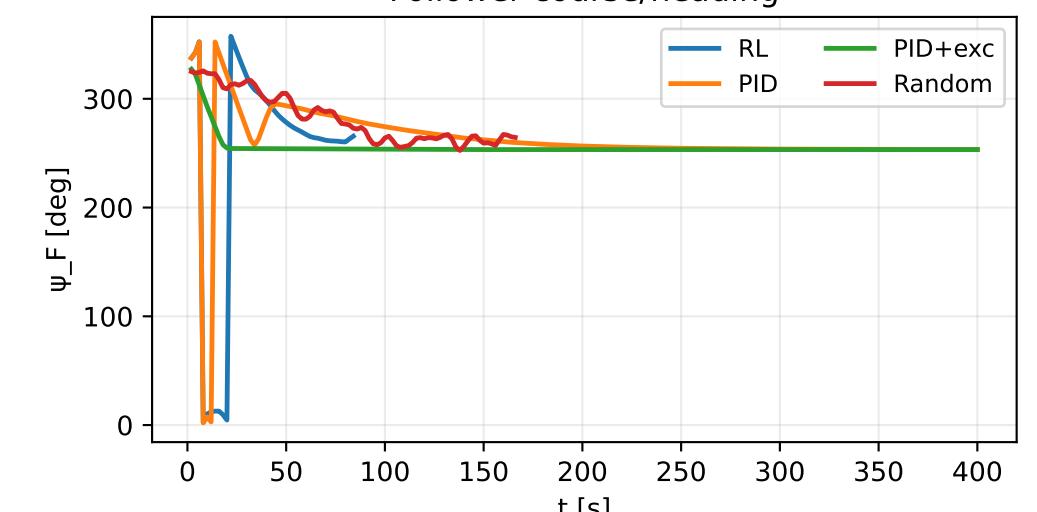
Information and excitation



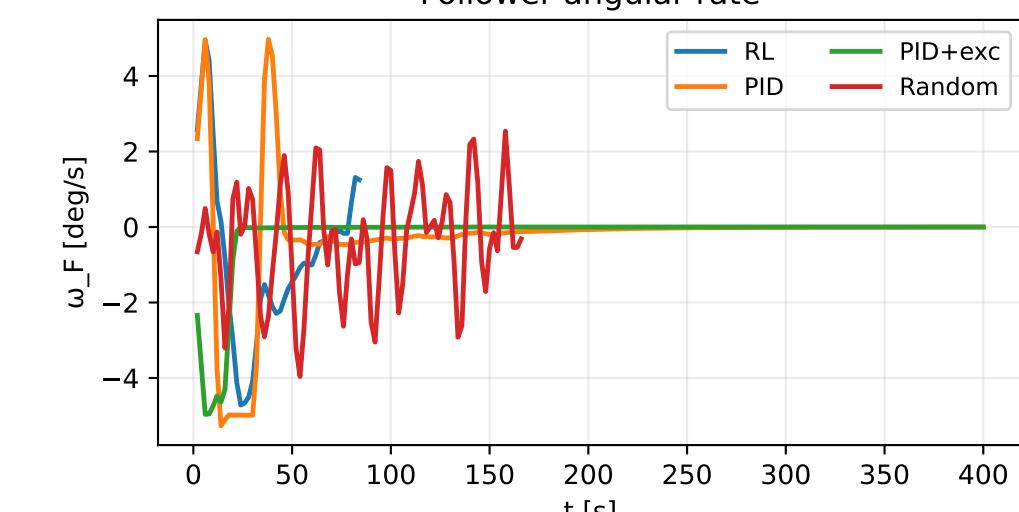
Follower speed



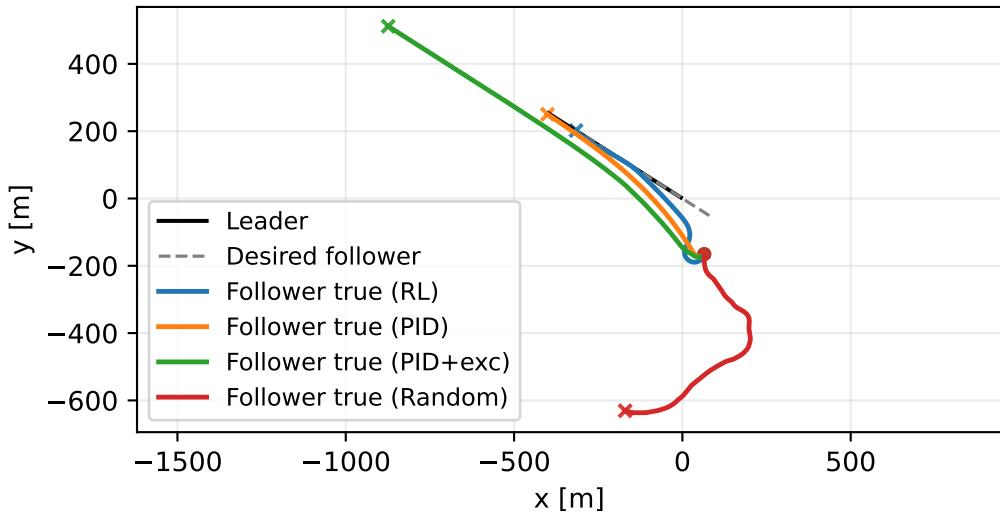
Follower course/heading



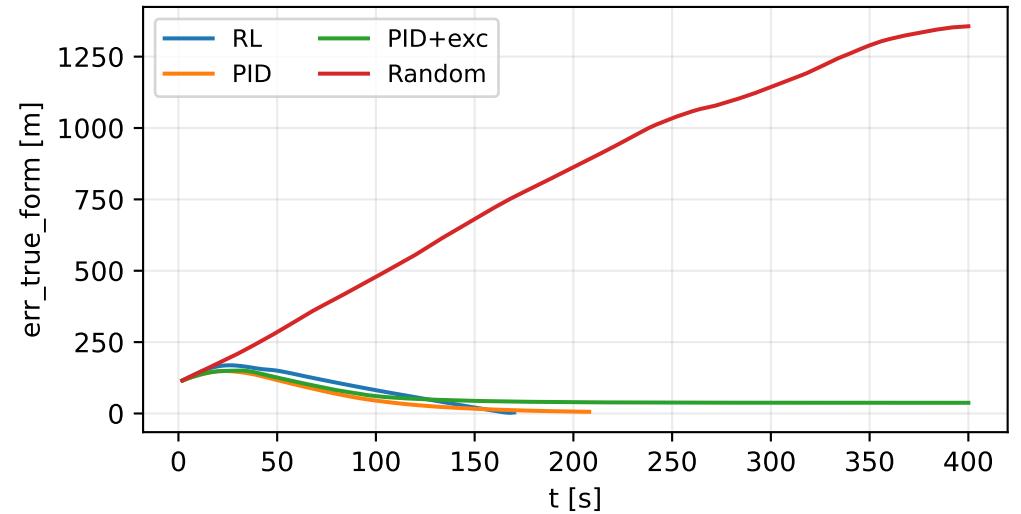
Follower angular rate



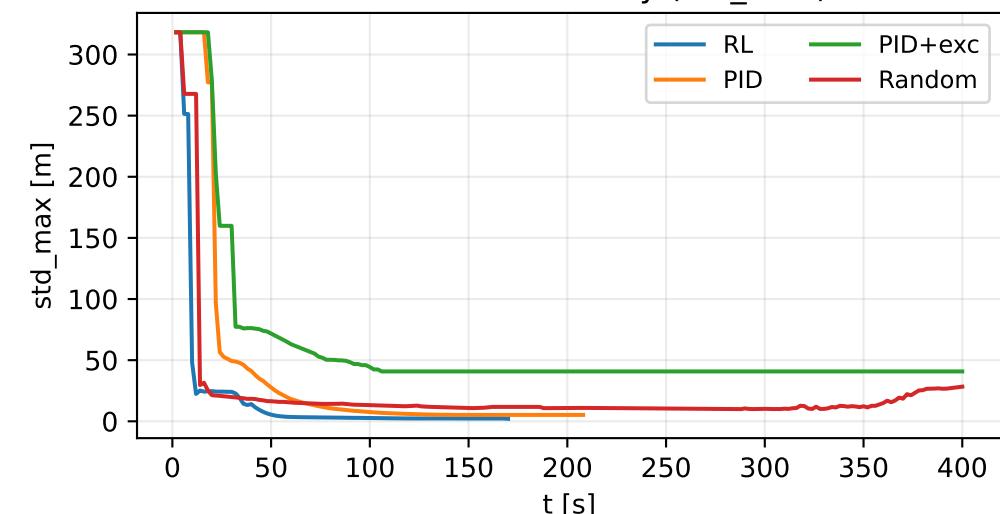
Trajectories (matched seed)



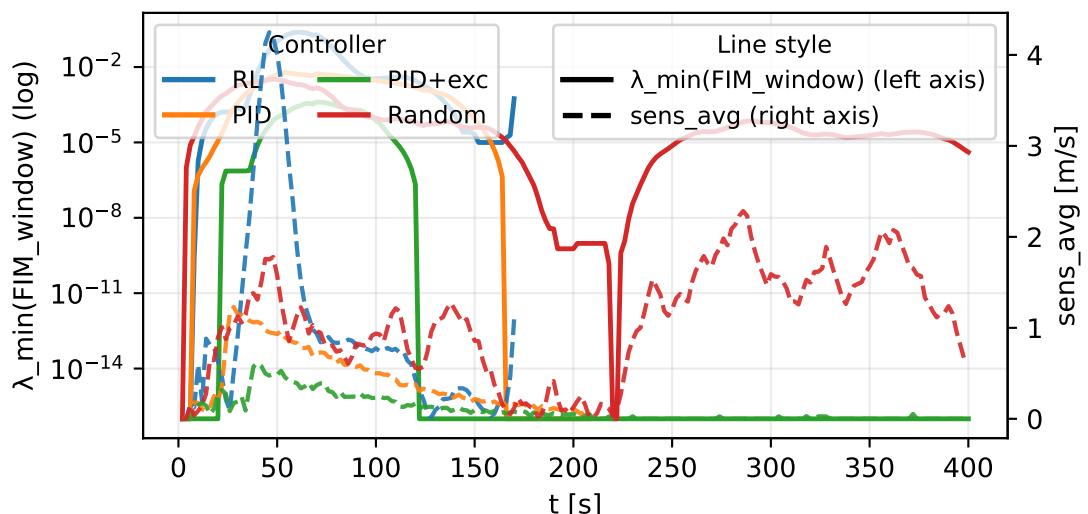
TRUE formation error



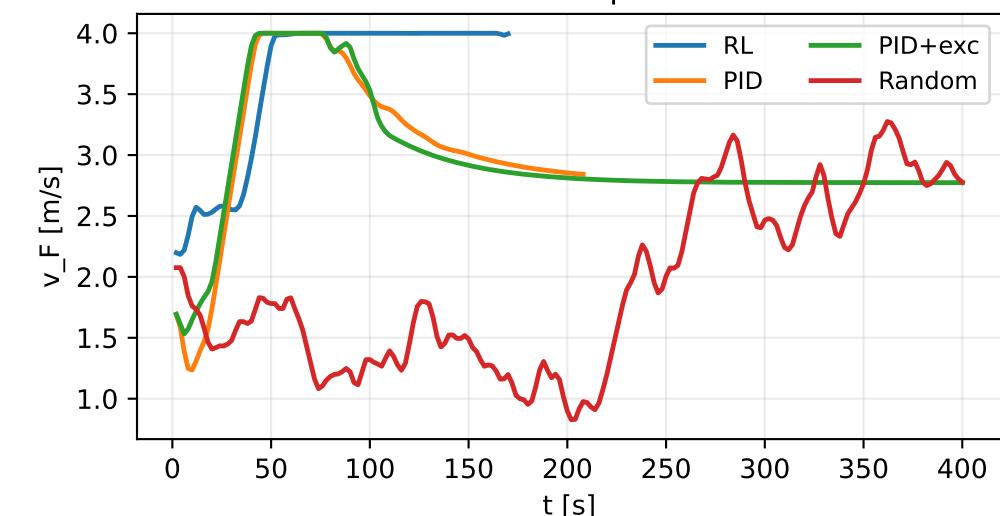
Estimator uncertainty (std_max)



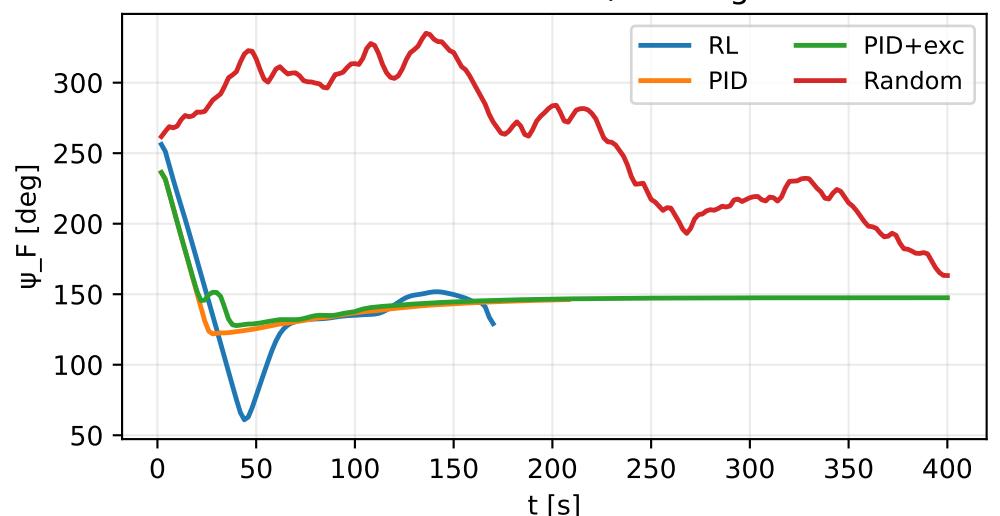
Information and excitation



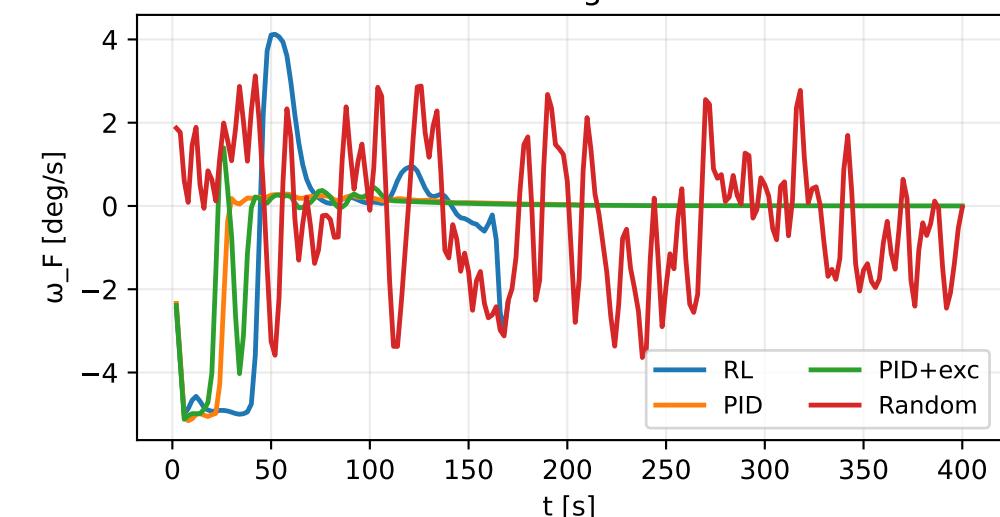
Follower speed



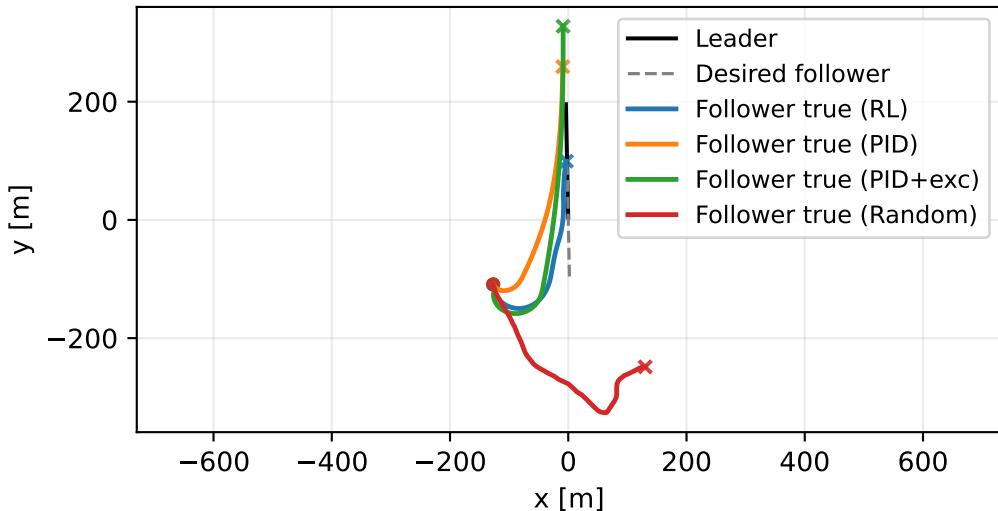
Follower course/heading



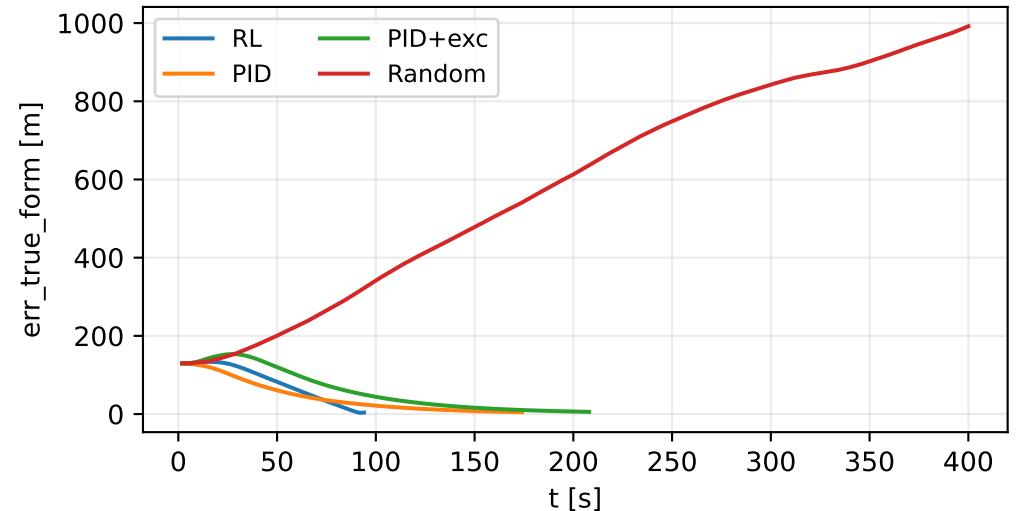
Follower angular rate



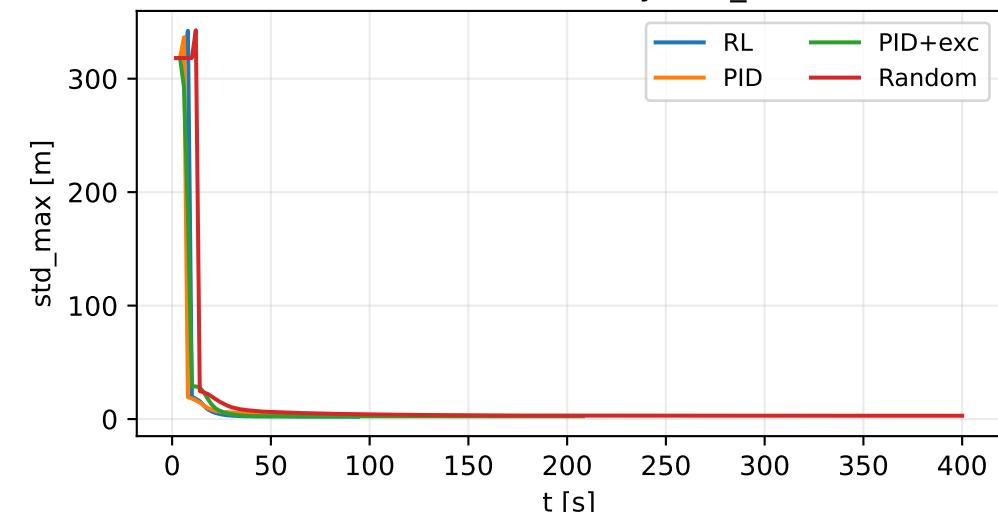
Trajectories (matched seed)



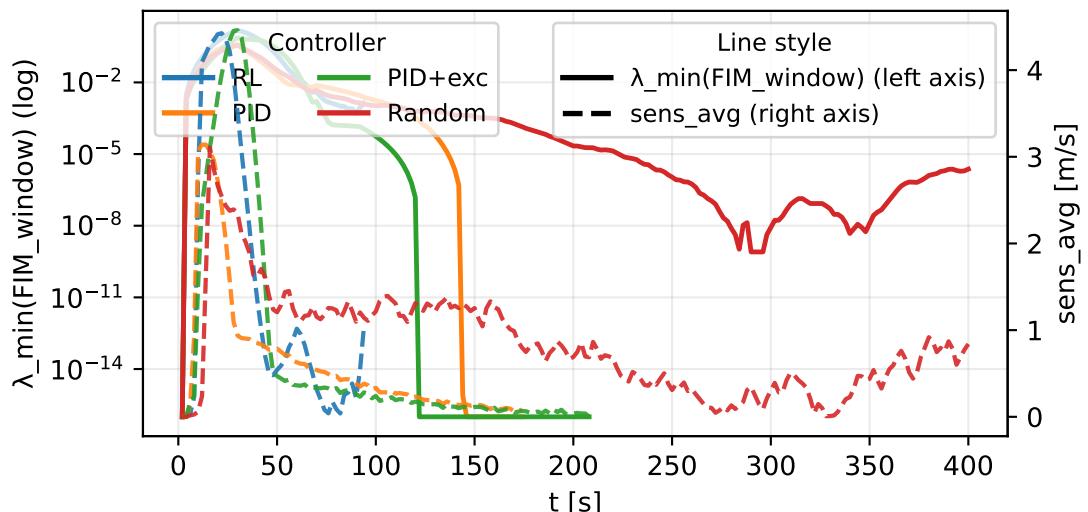
TRUE formation error



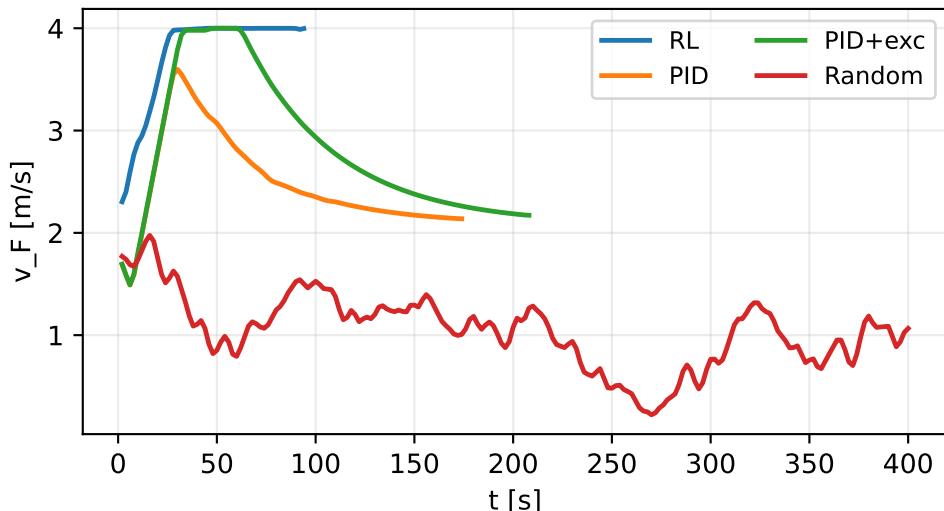
Estimator uncertainty (std_max)



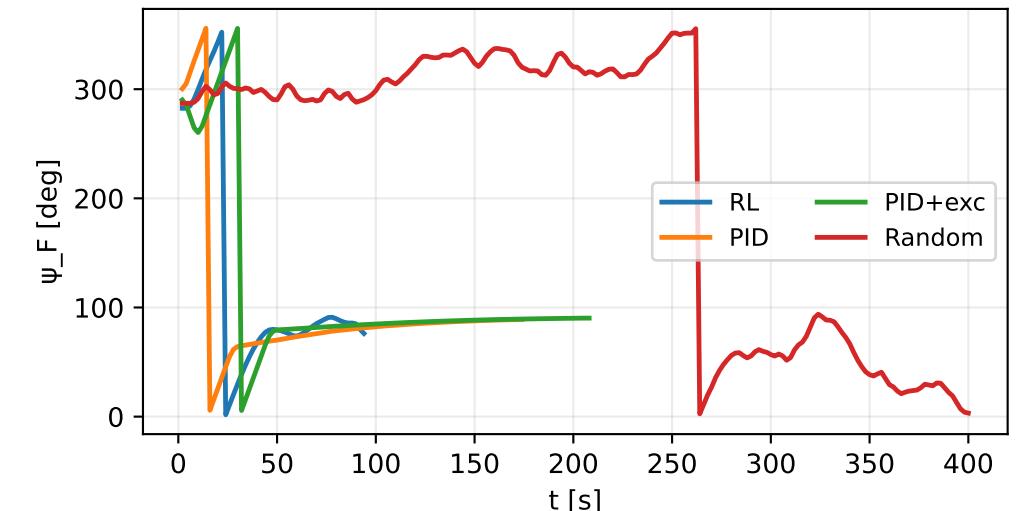
Information and excitation



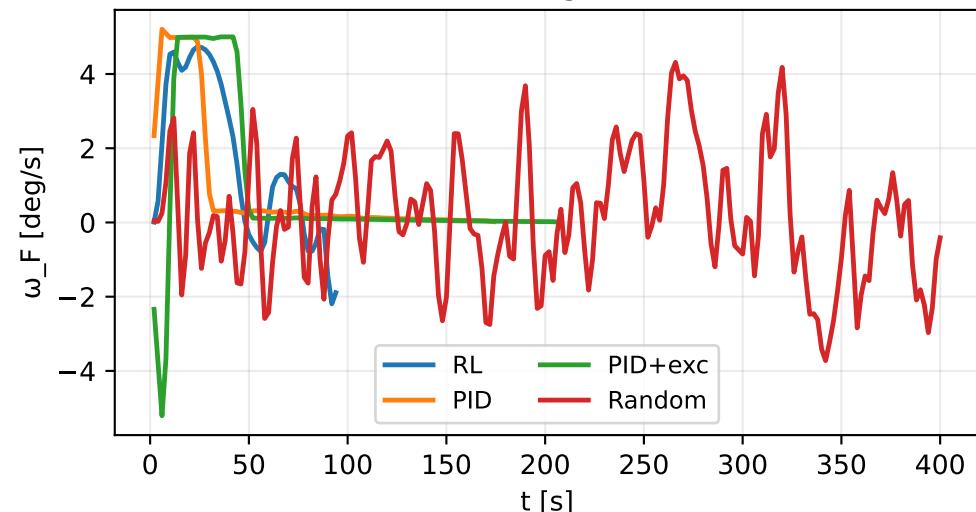
Follower speed



Follower course/heading

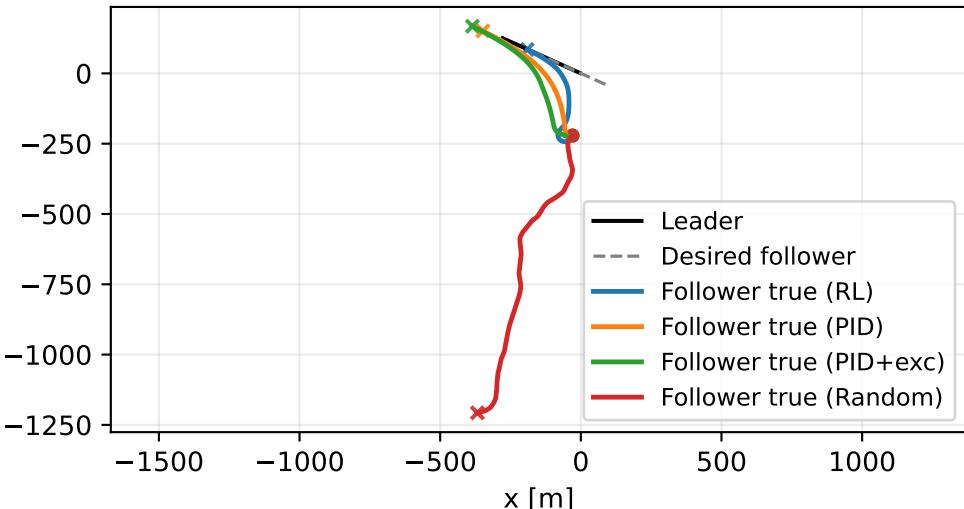


Follower angular rate



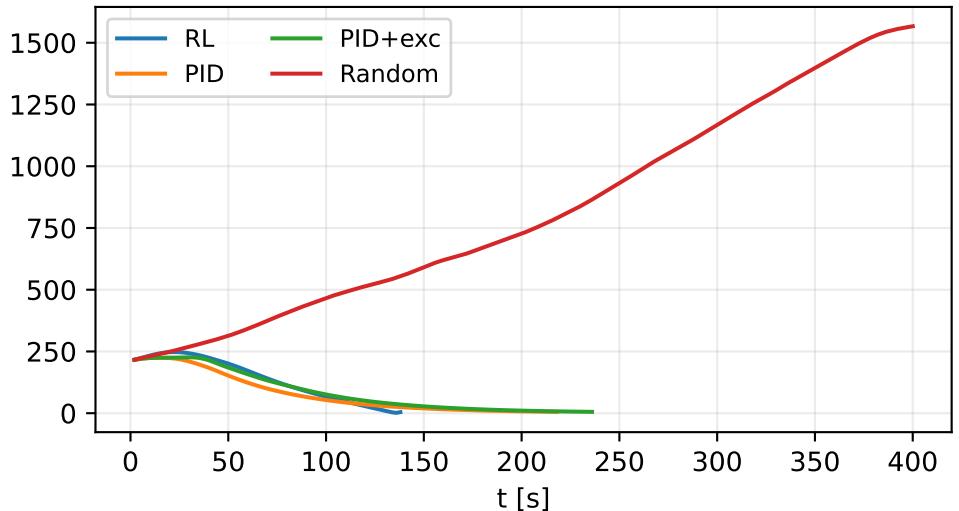
Trajectories (matched seed)

y [m]



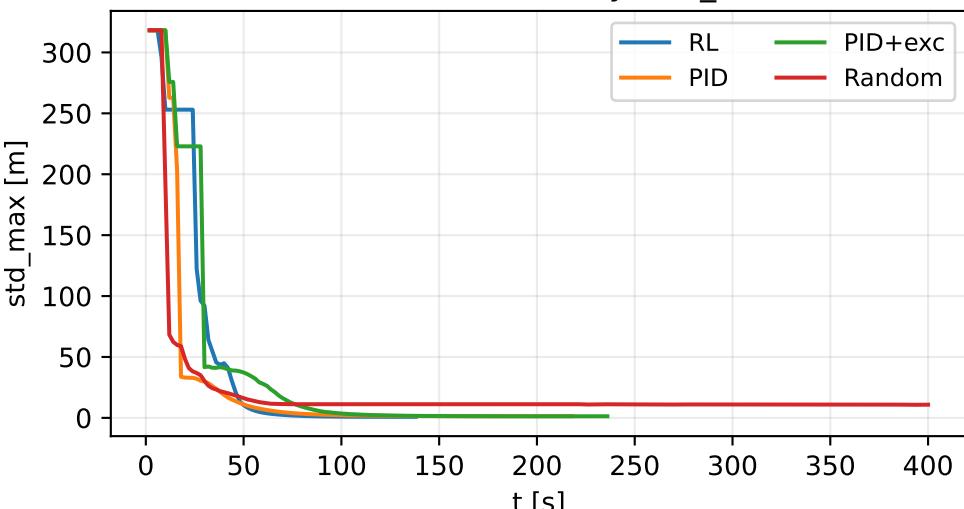
TRUE formation error

err_true_form [m]

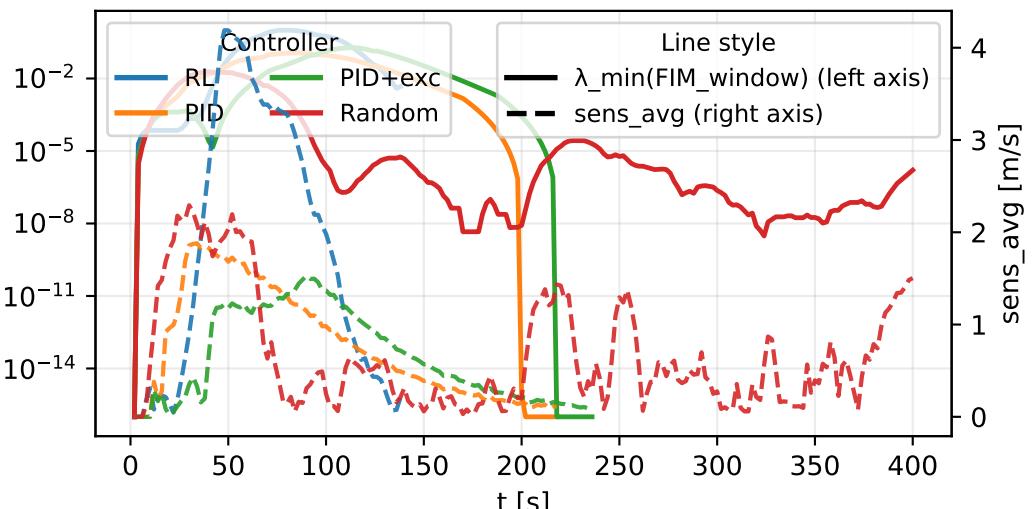


Estimator uncertainty (std_max)

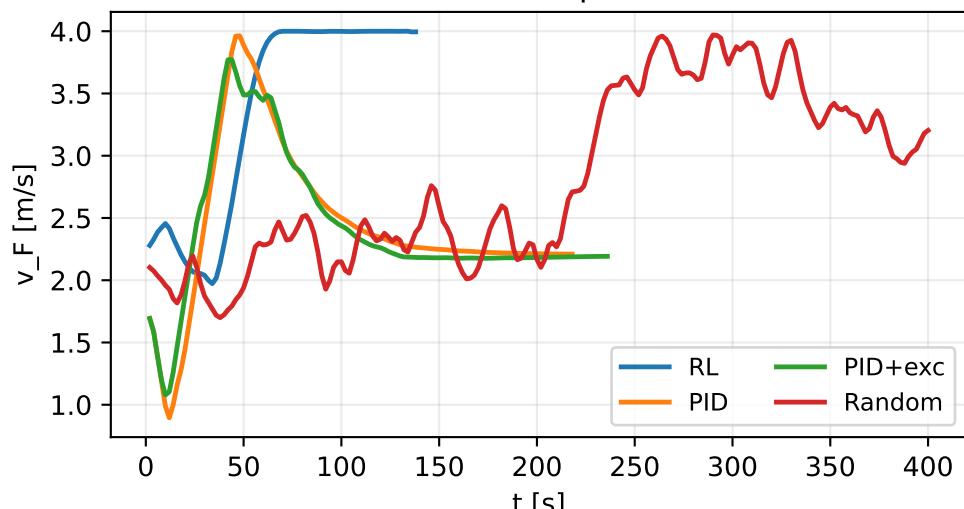
std_max [m]



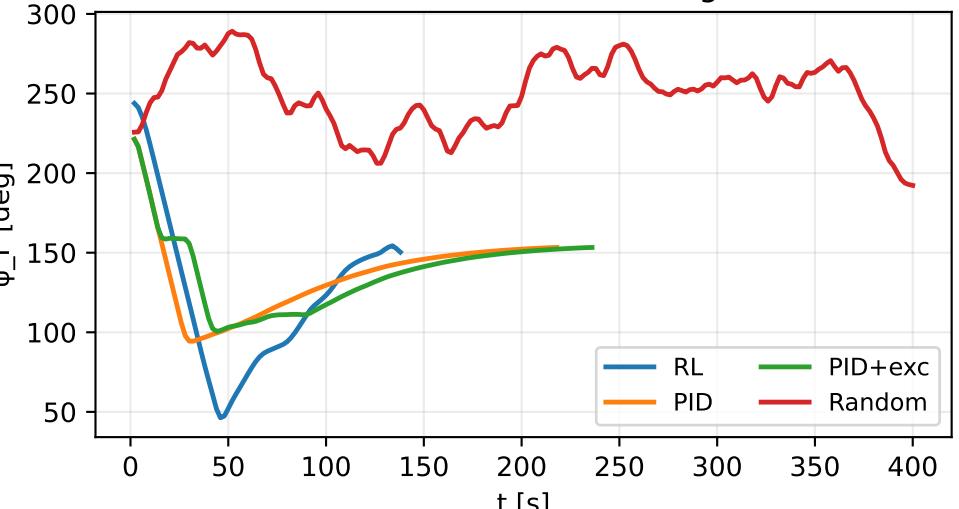
Information and excitation

 $\lambda_{\min}(\text{FIM_window})$ (log)

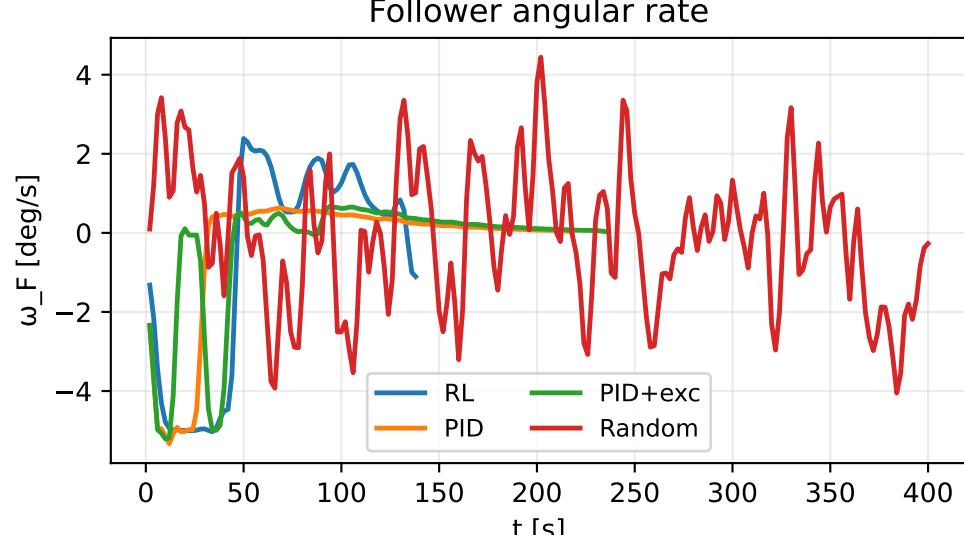
Follower speed

 v_F [m/s]

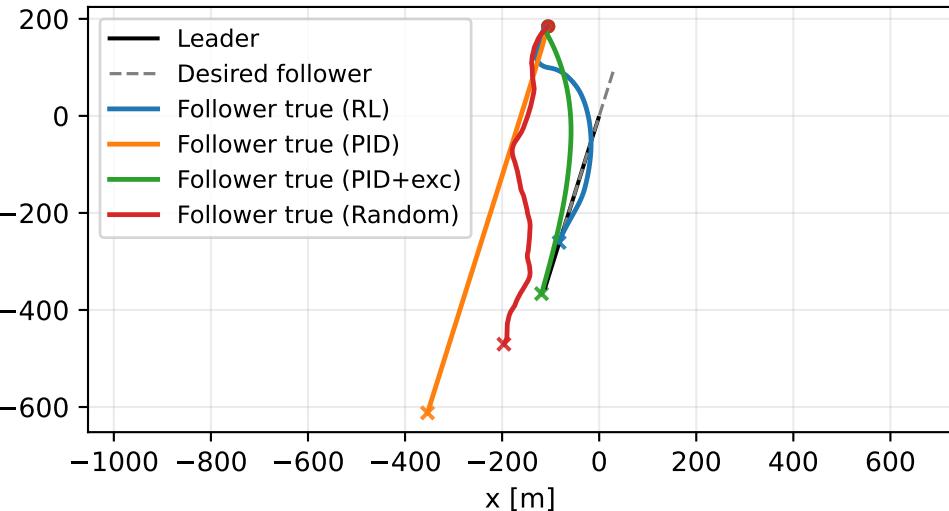
Follower course/heading

 ψ_F [deg]

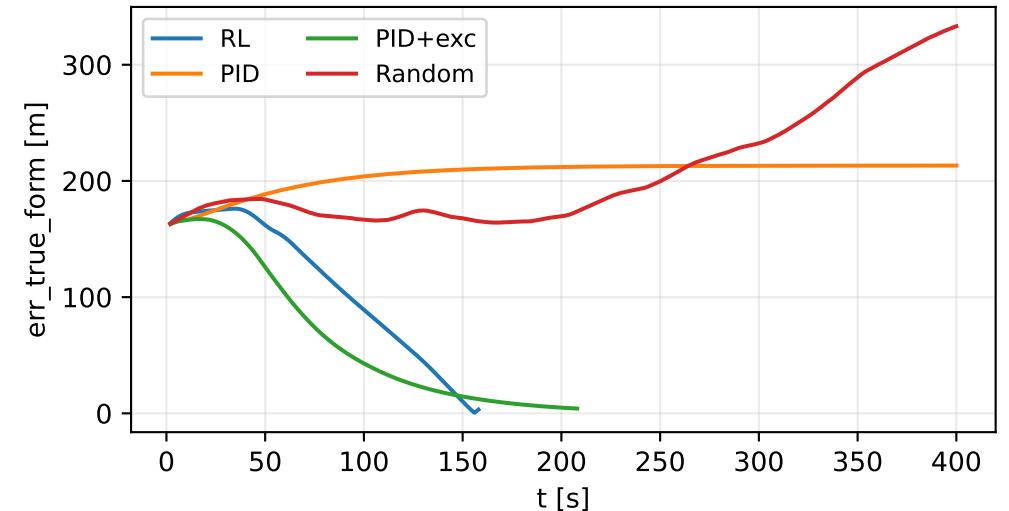
Follower angular rate

 ω_F [deg/s]

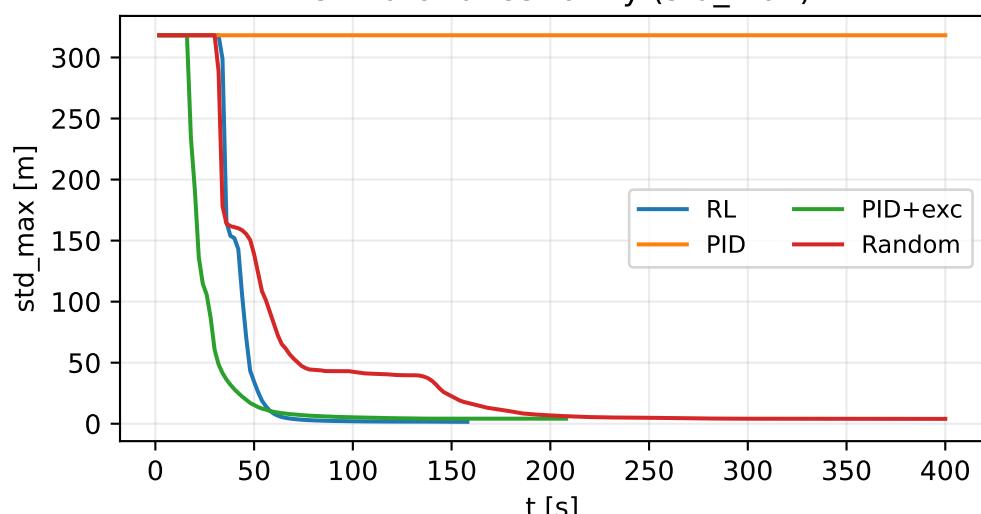
Trajectories (matched seed)



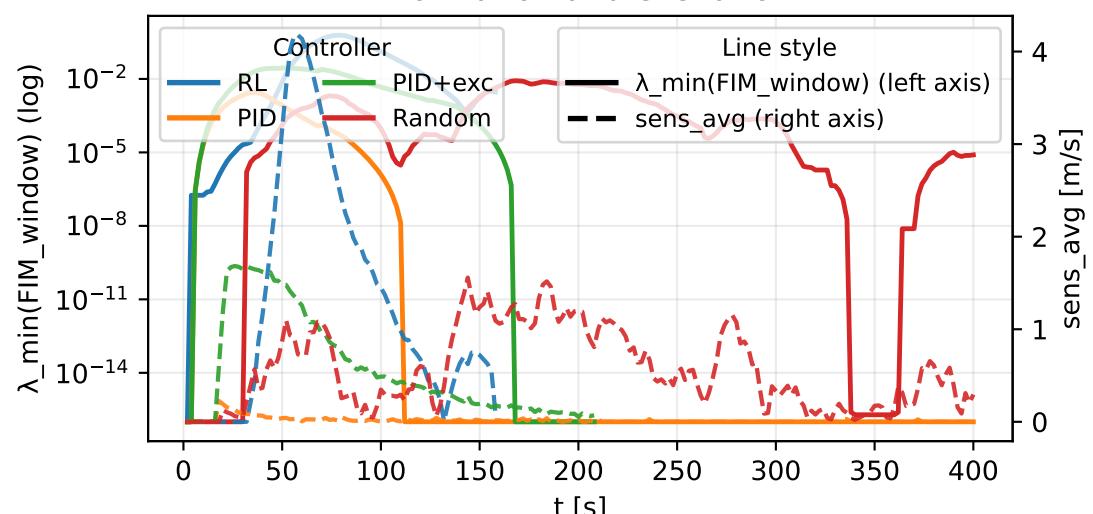
TRUE formation error



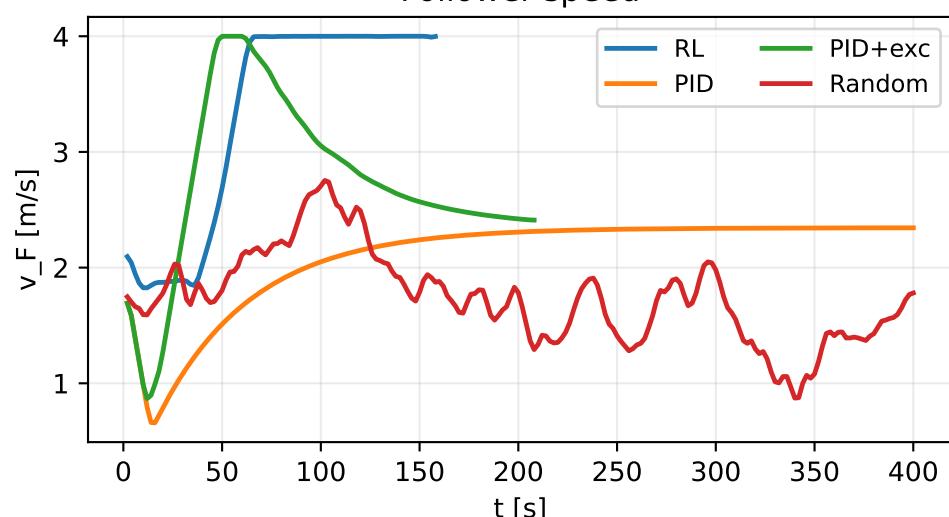
Estimator uncertainty (std_max)



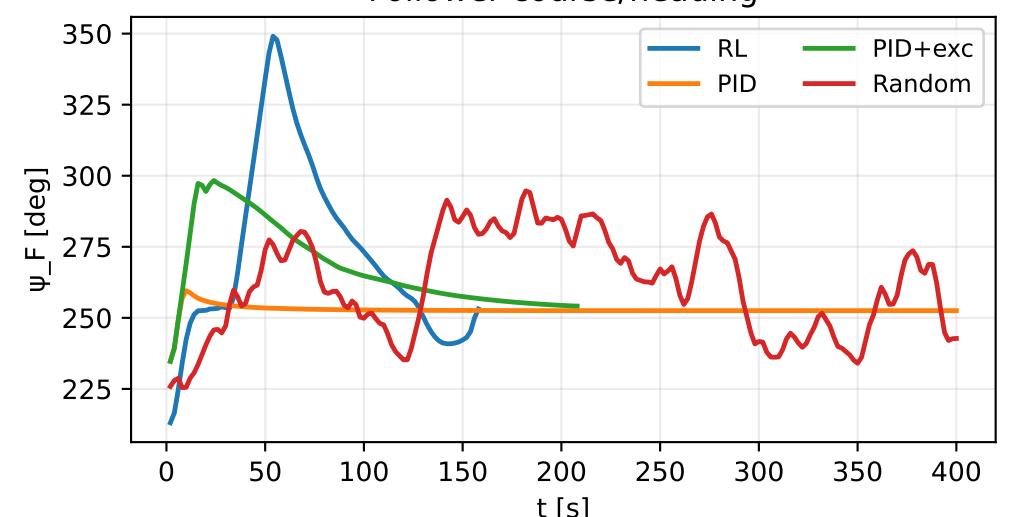
Information and excitation



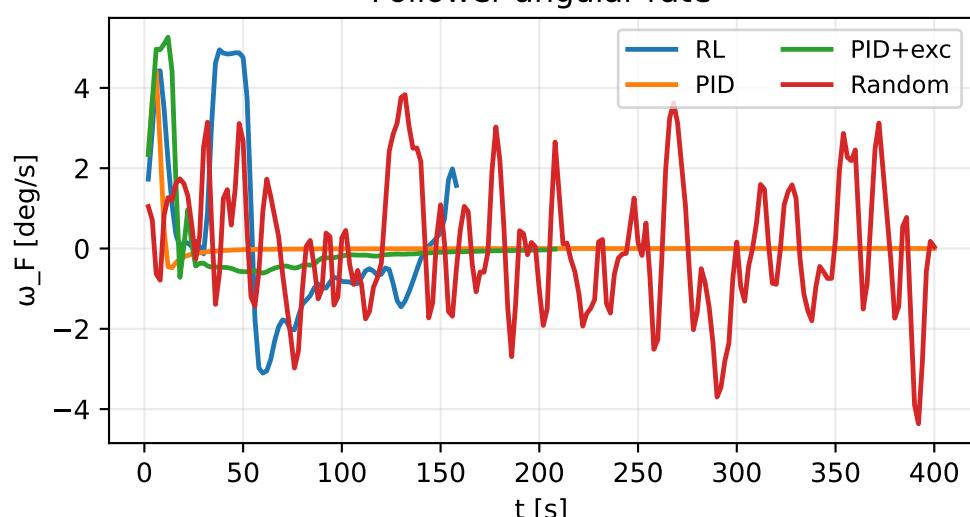
Follower speed



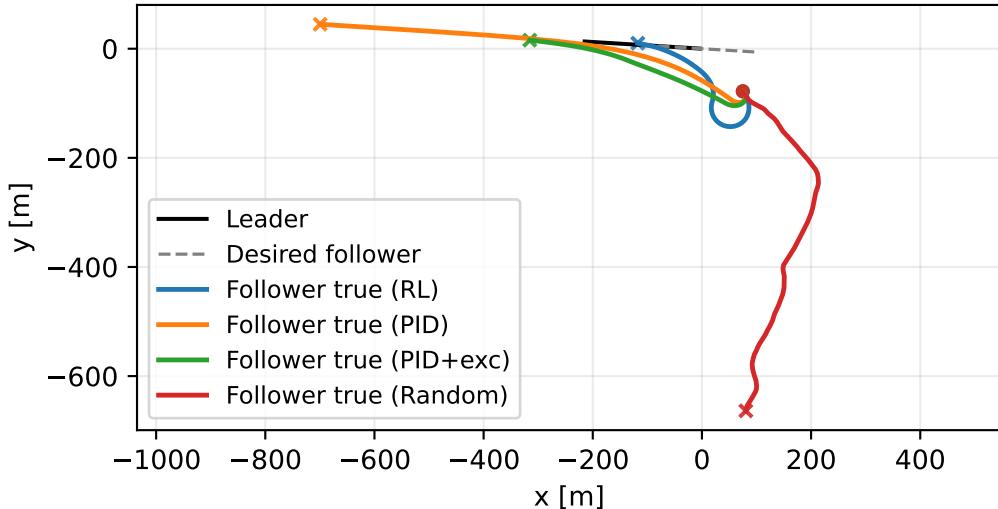
Follower course/heading



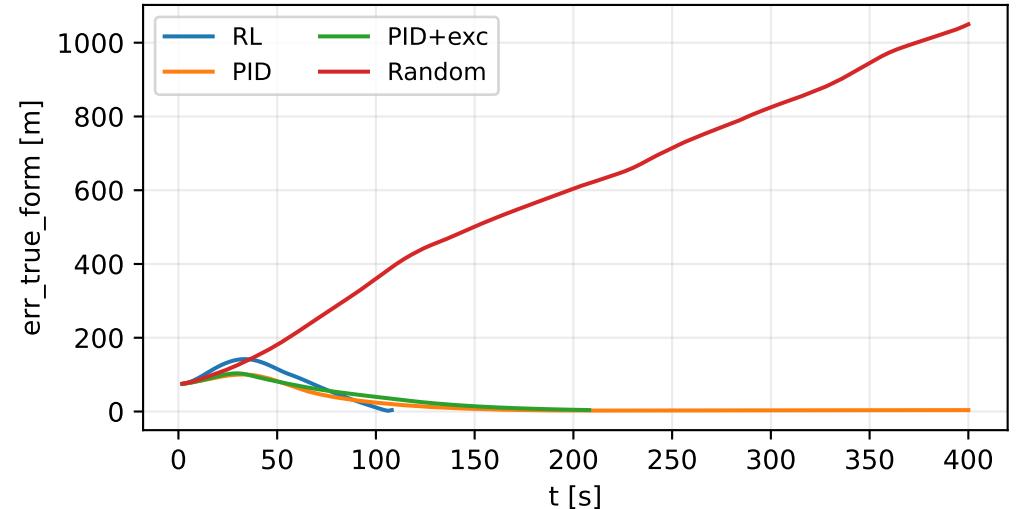
Follower angular rate



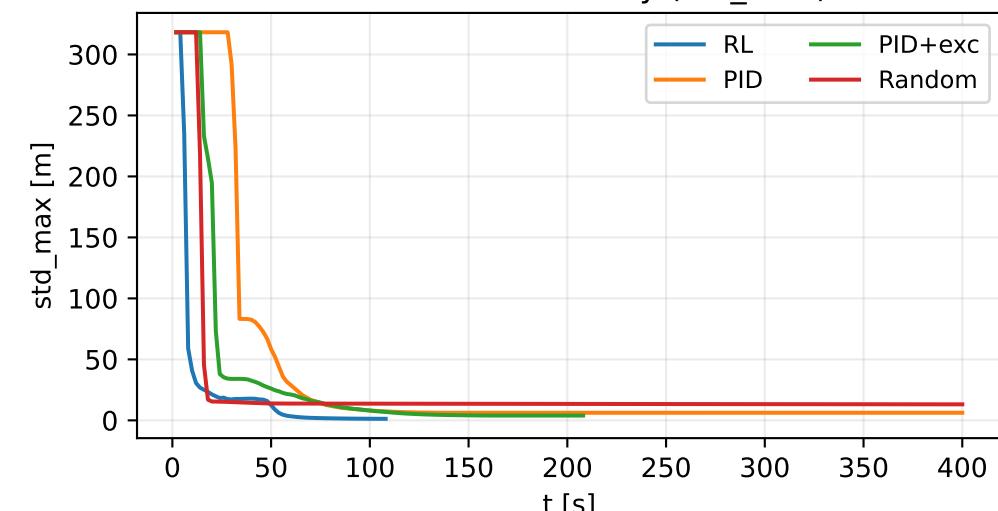
Trajectories (matched seed)



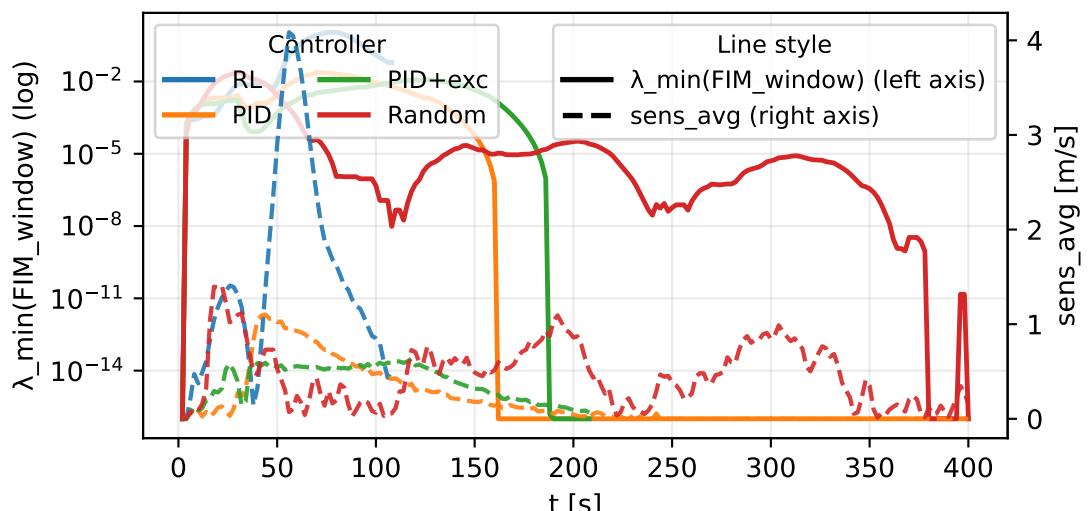
TRUE formation error



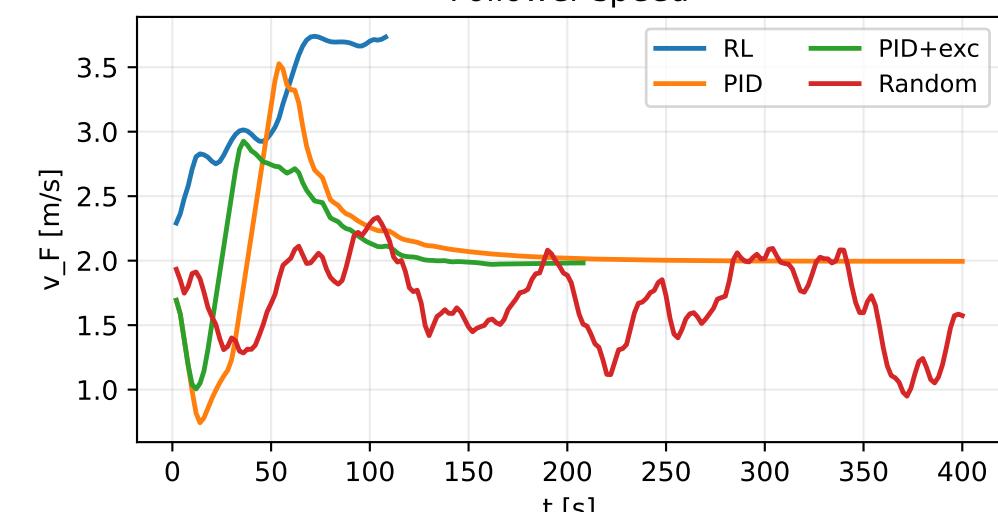
Estimator uncertainty (std_max)



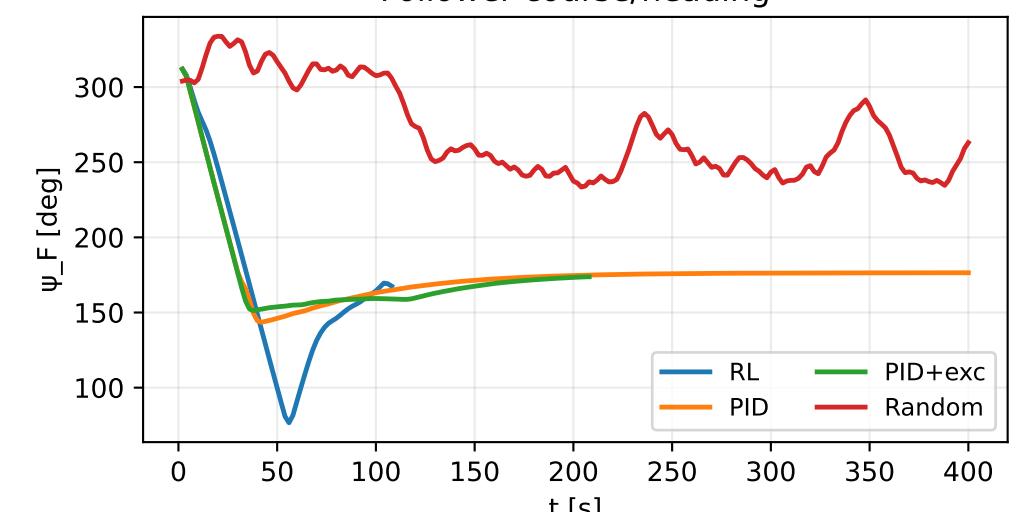
Information and excitation



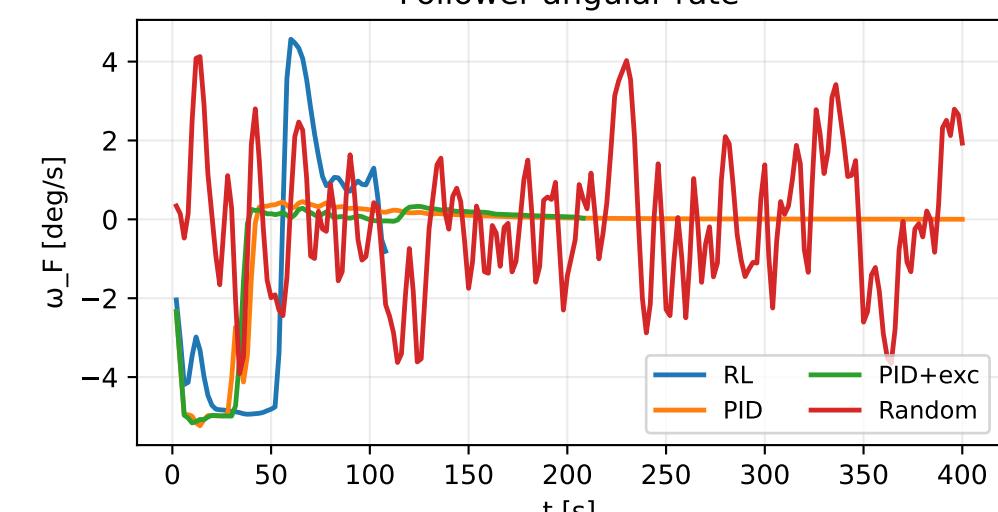
Follower speed



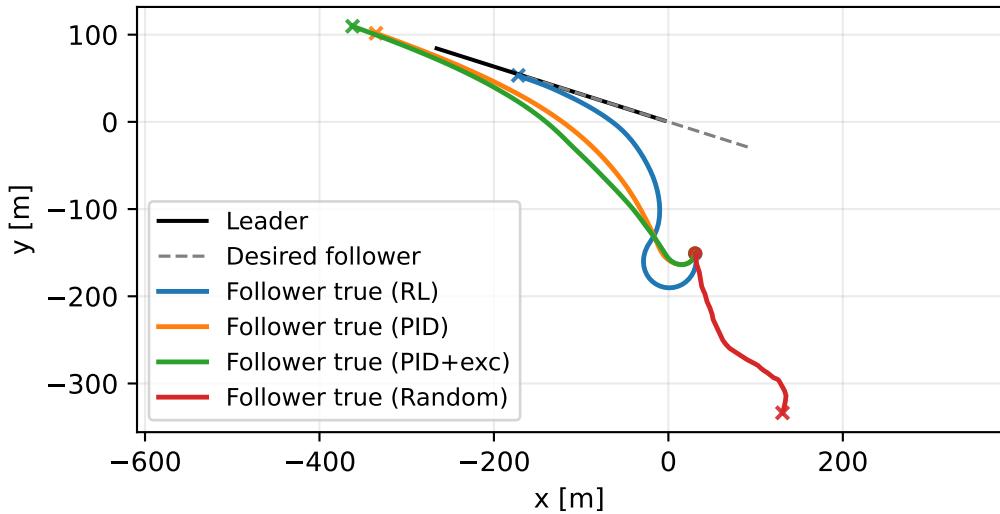
Follower course/heading



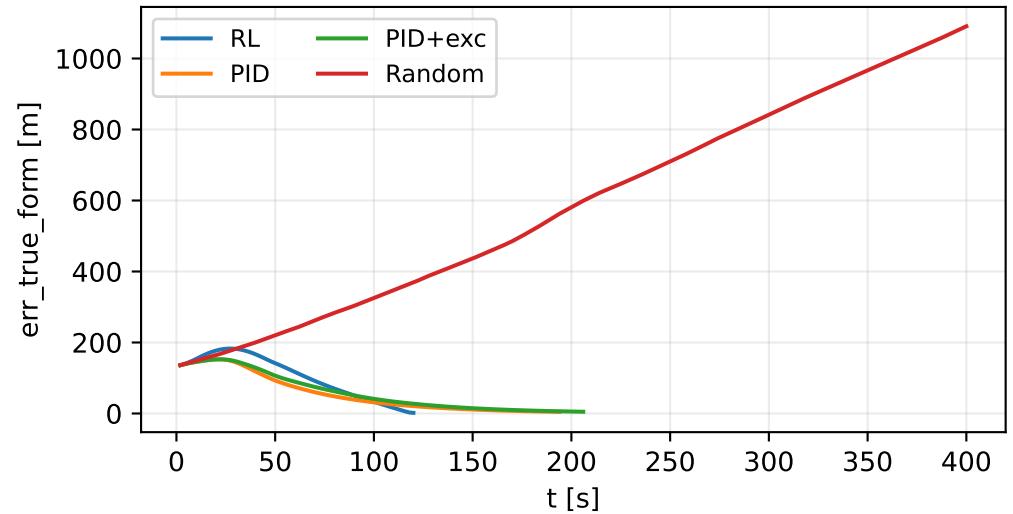
Follower angular rate



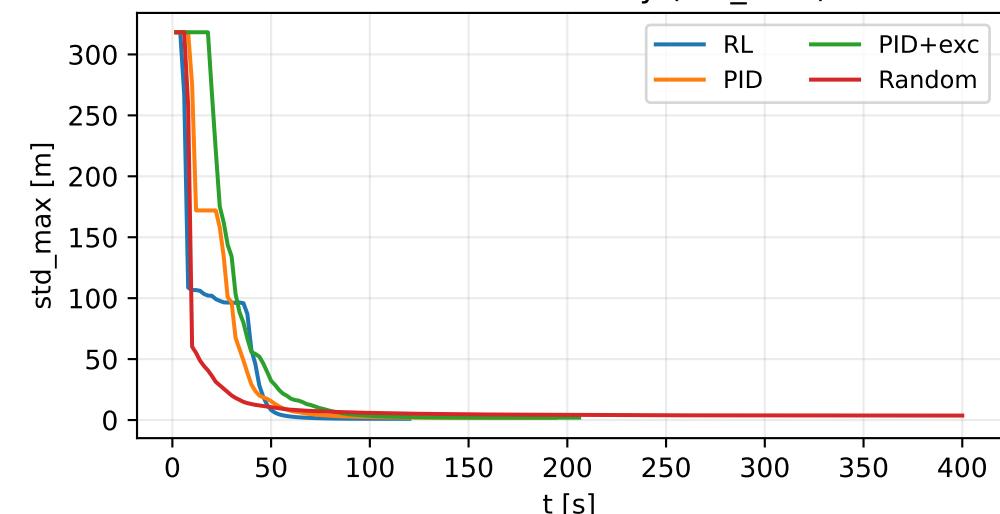
Trajectories (matched seed)



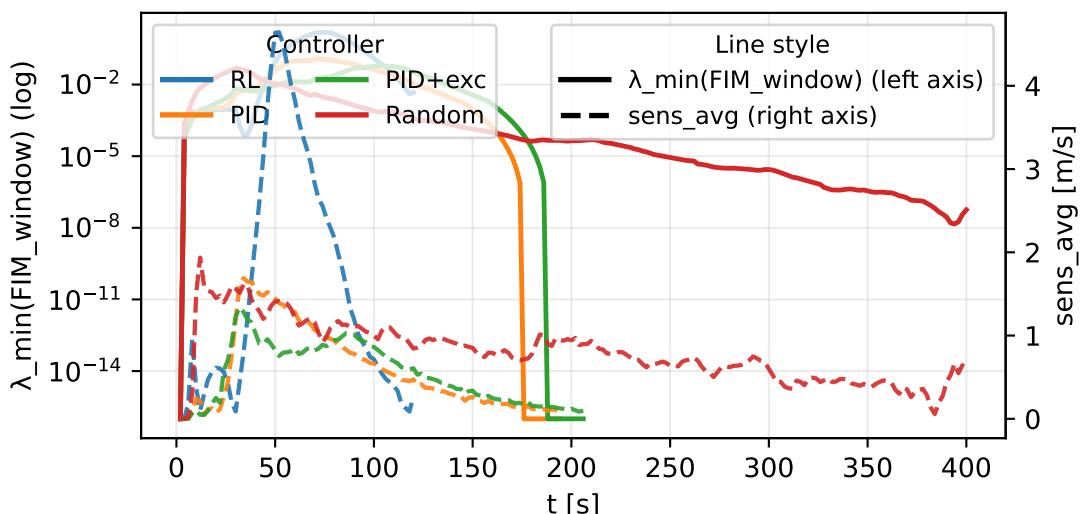
TRUE formation error



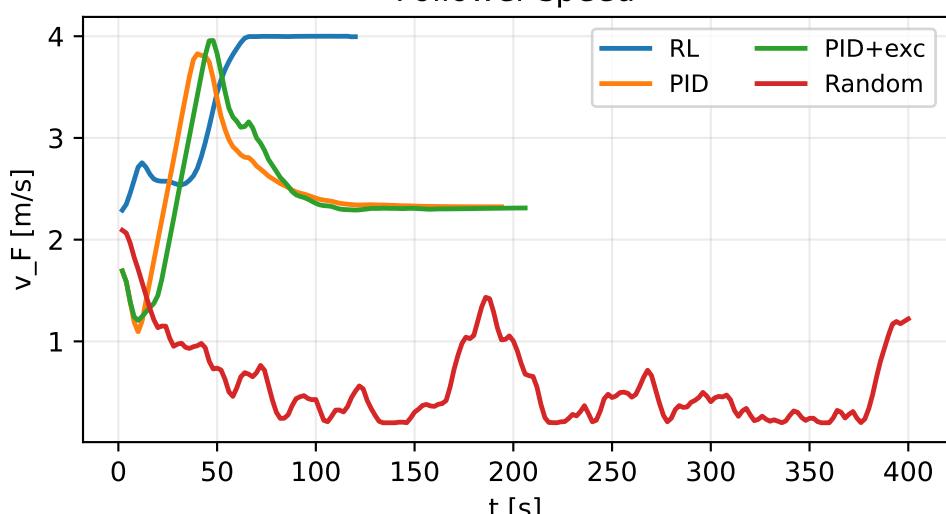
Estimator uncertainty (std_max)



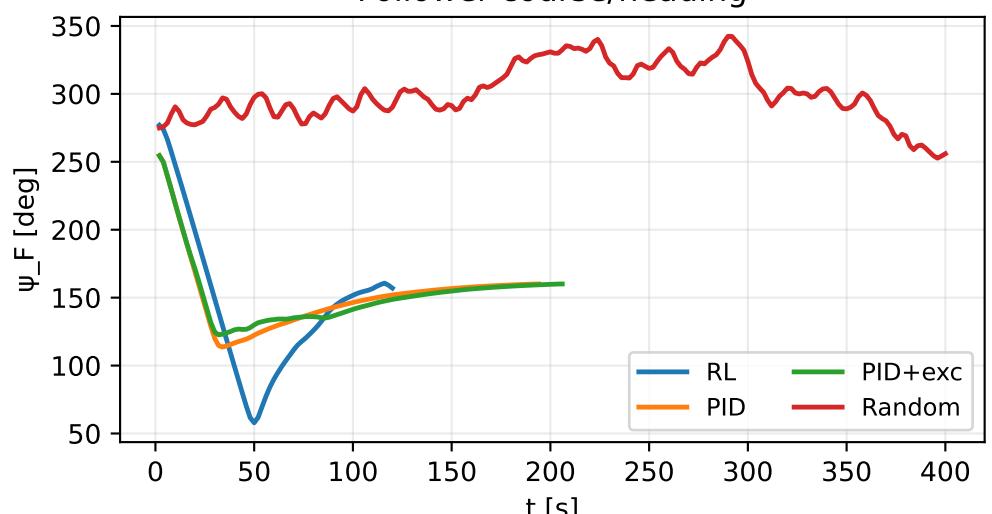
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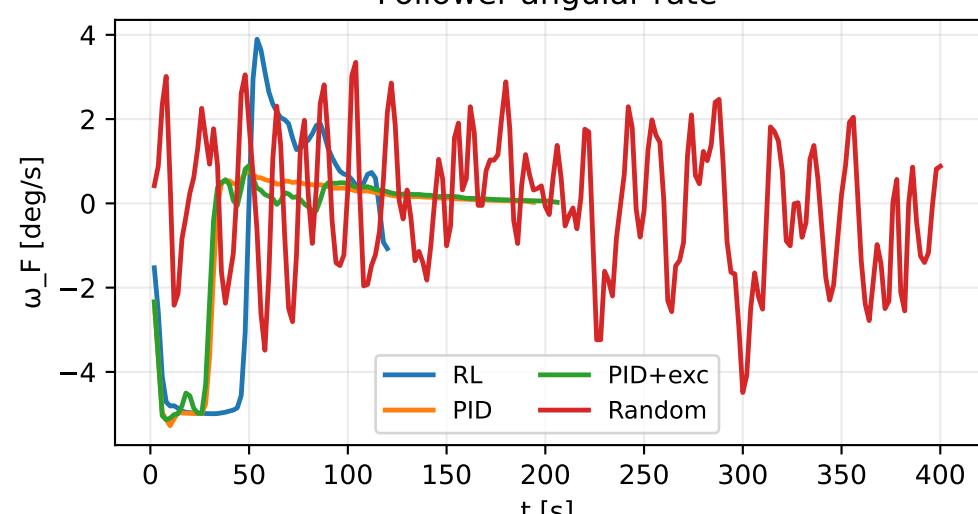
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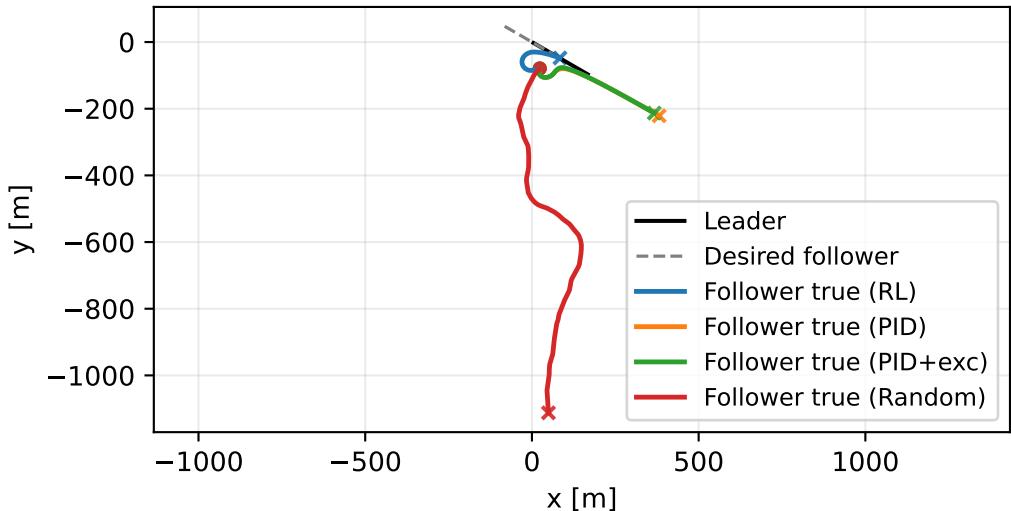
Follower course/heading



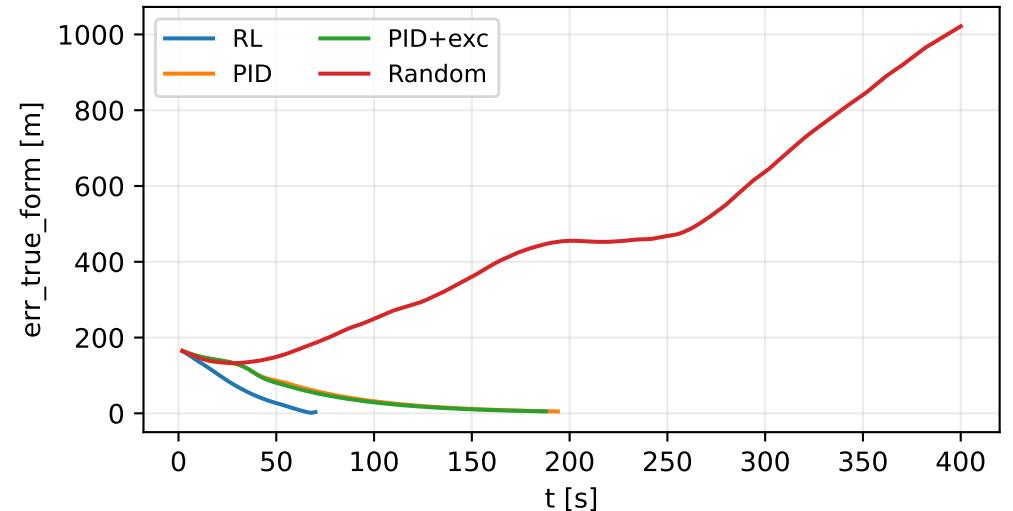
Follower angular rate



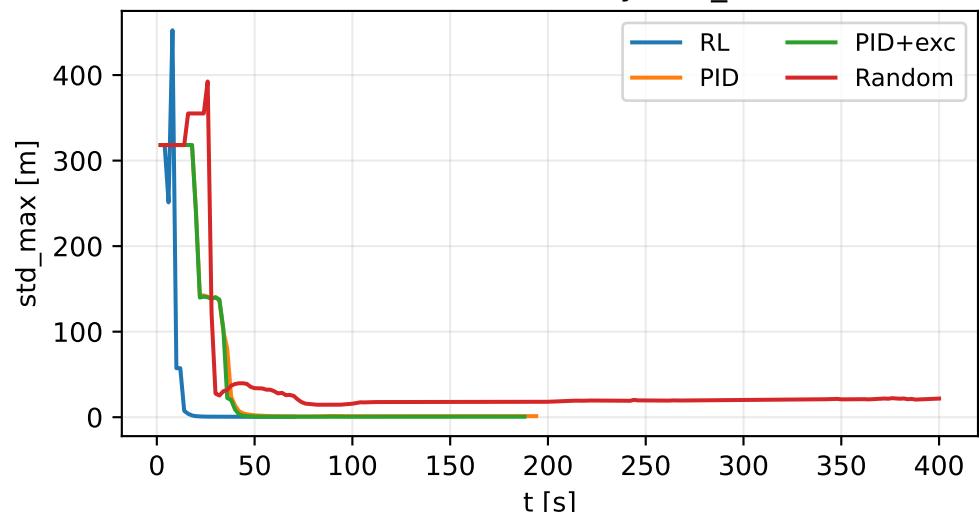
Trajectories (matched seed)



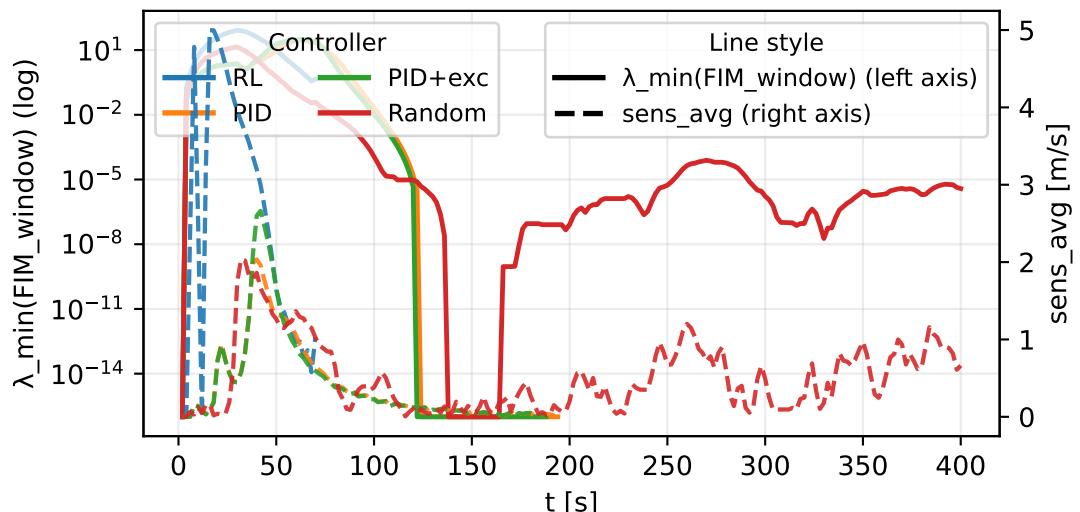
TRUE formation error



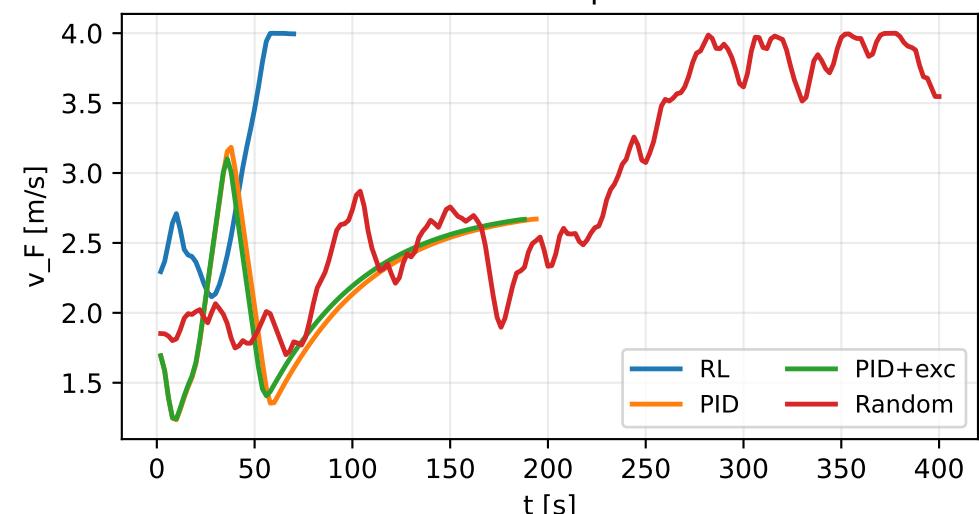
Estimator uncertainty (std_max)



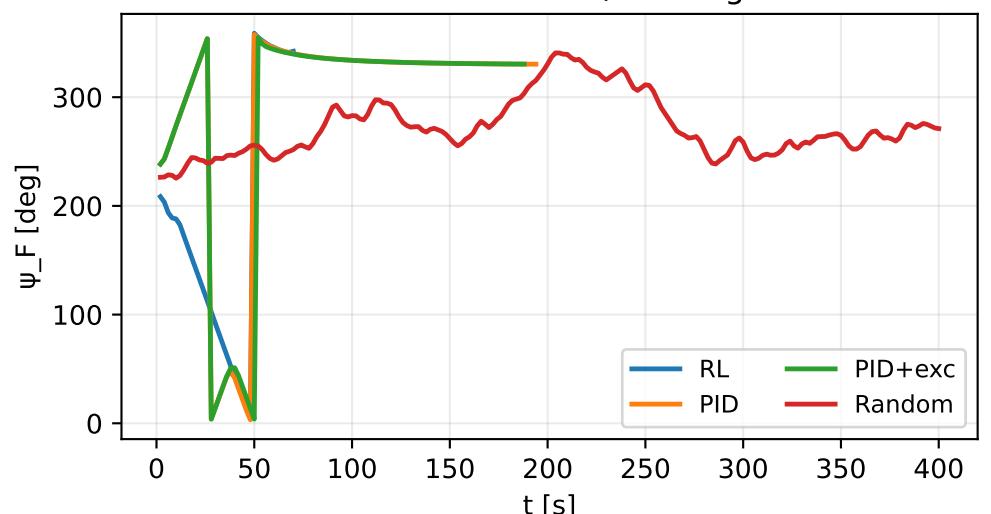
Information and excitation



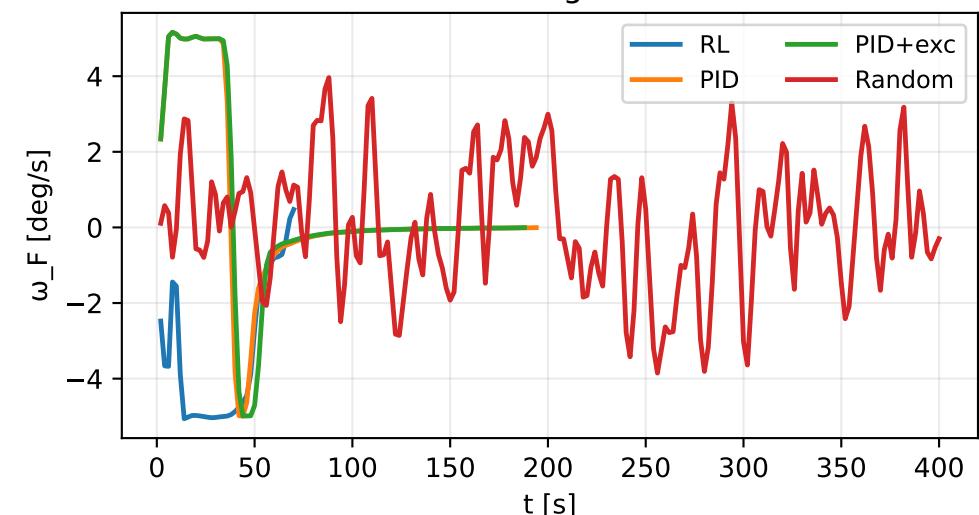
Follower speed



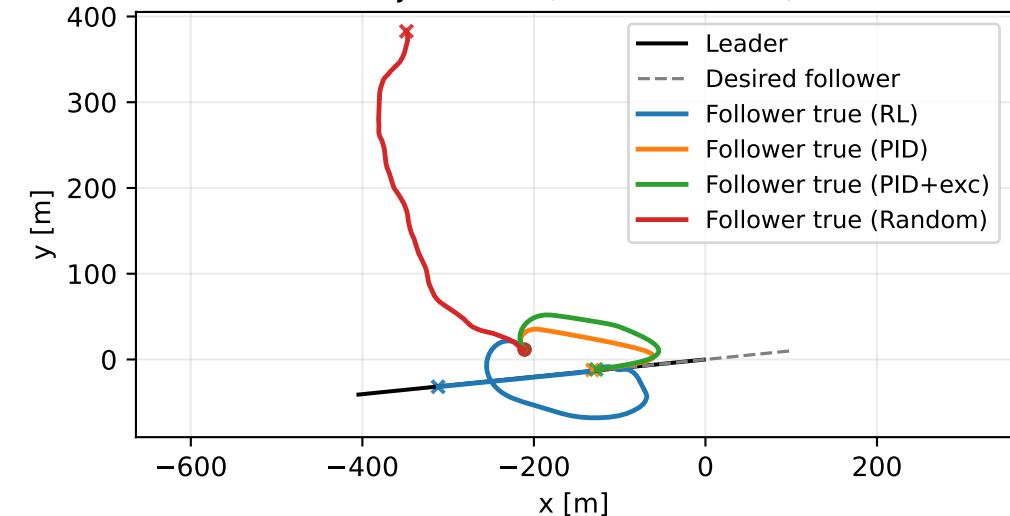
Follower course/heading



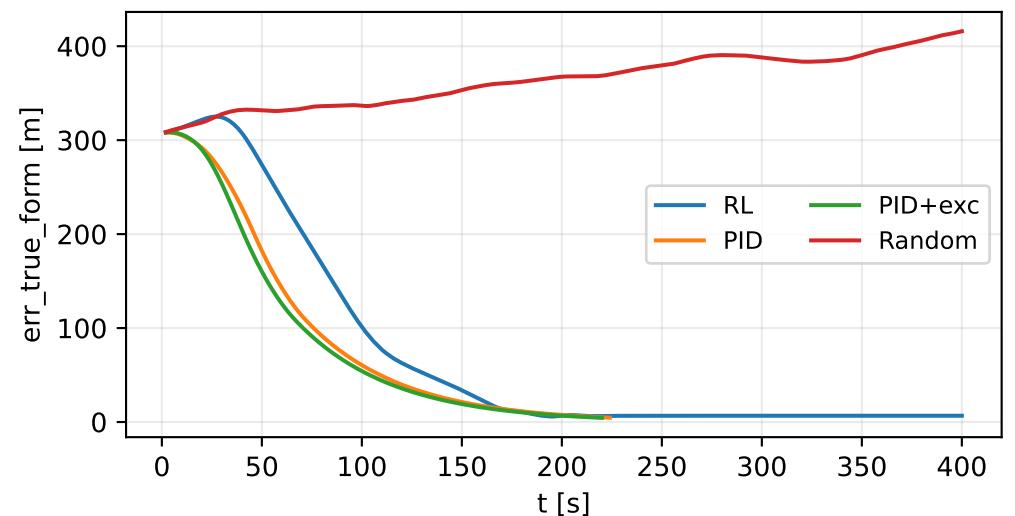
Follower angular rate



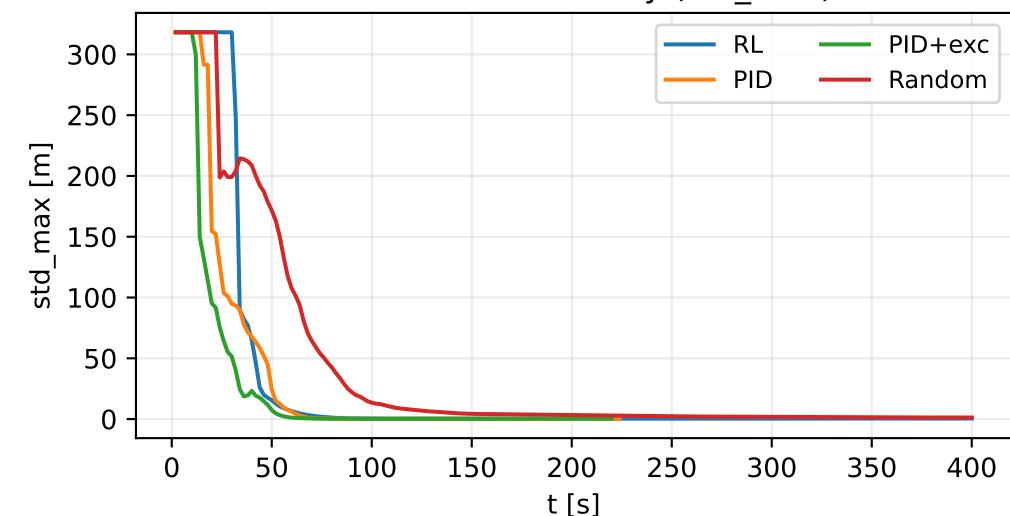
Trajectories (matched seed)



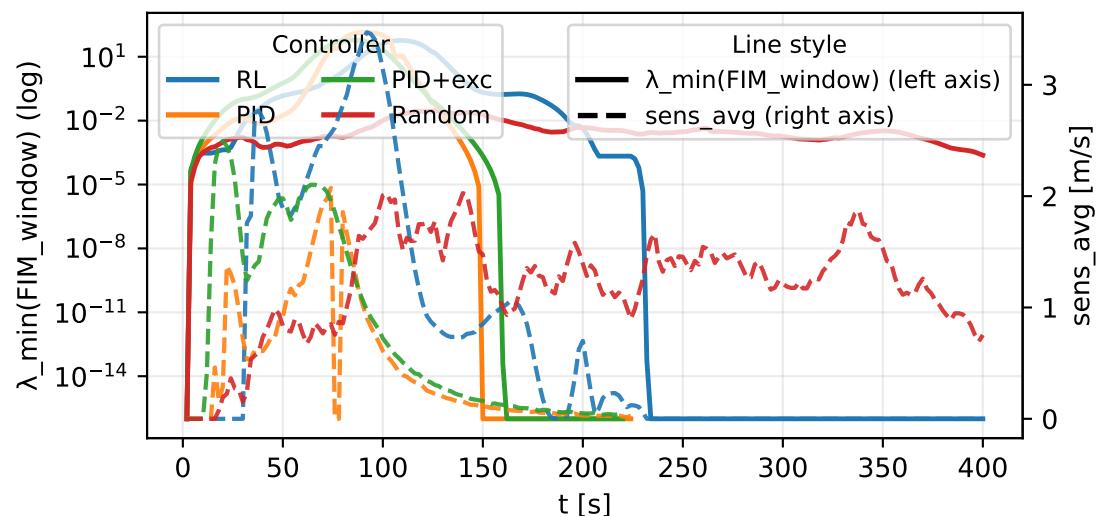
TRUE formation error



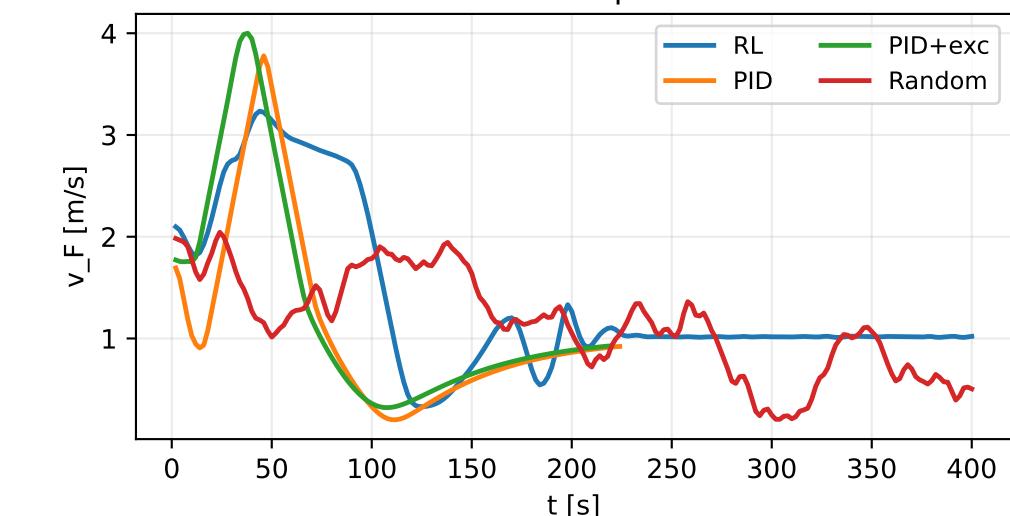
Estimator uncertainty (std_max)



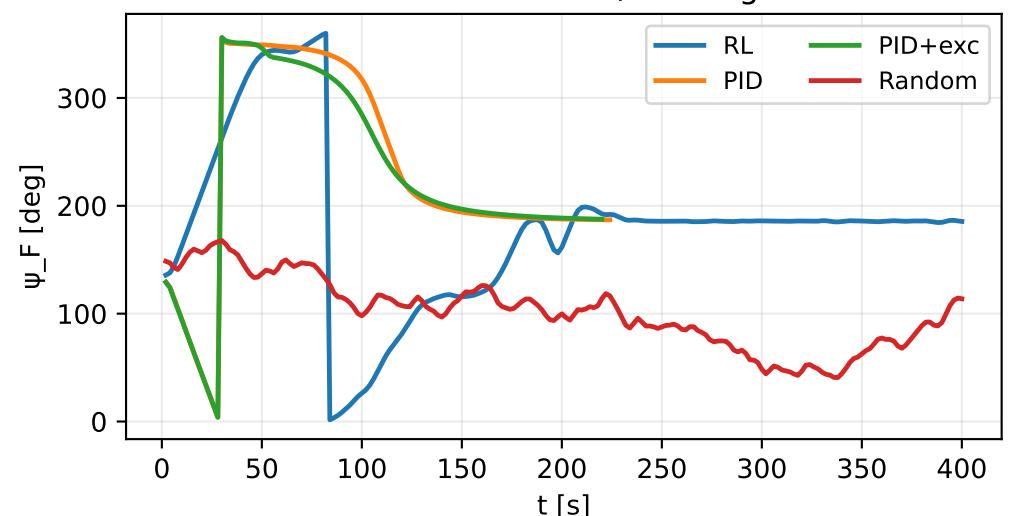
Information and excitation



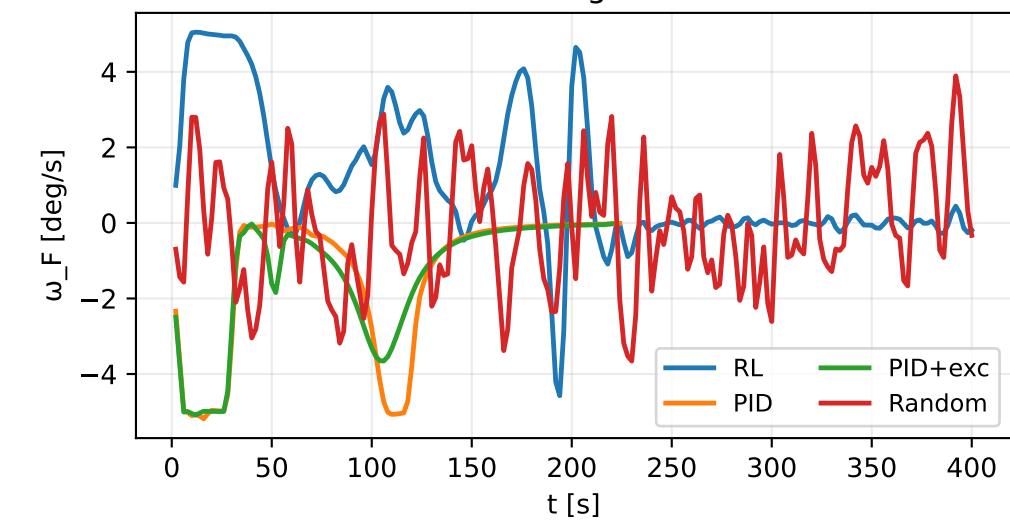
Follower speed



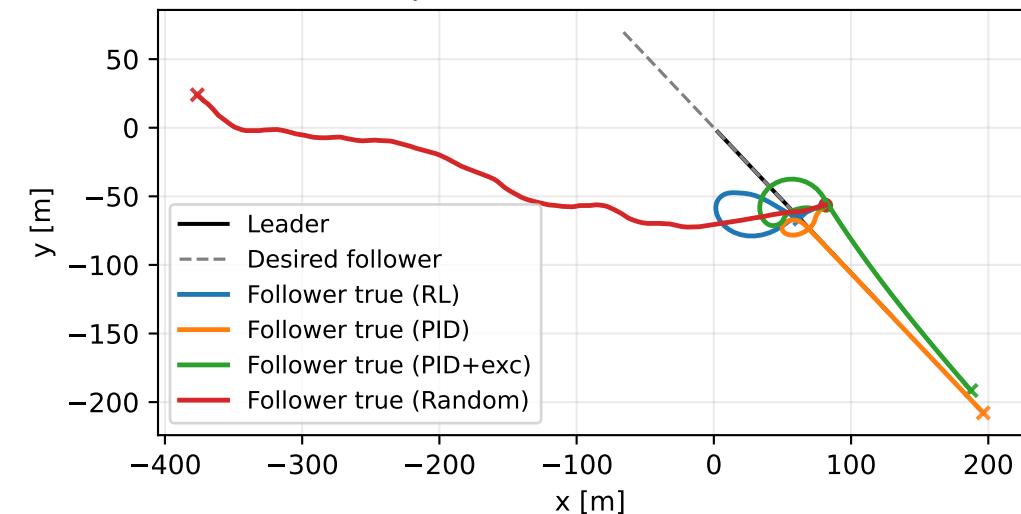
Follower course/heading



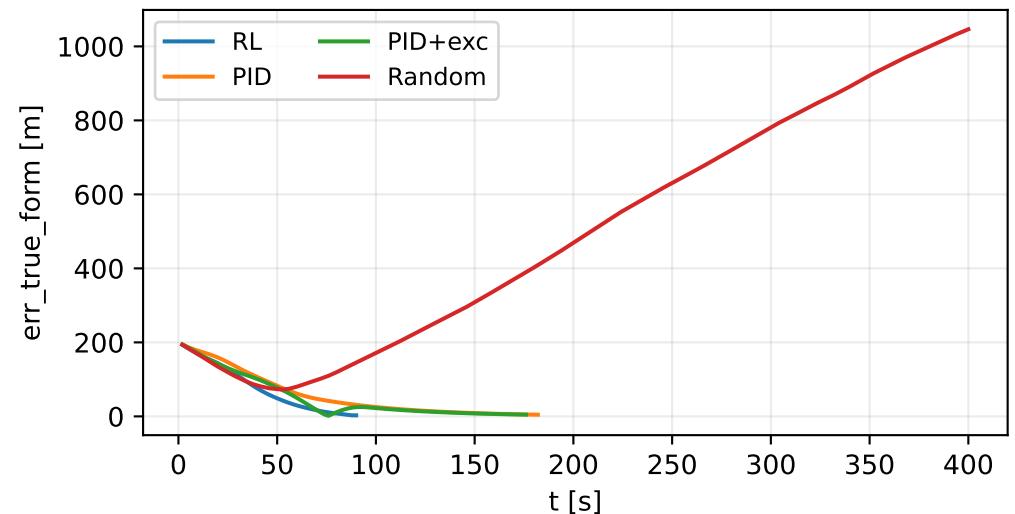
Follower angular rate



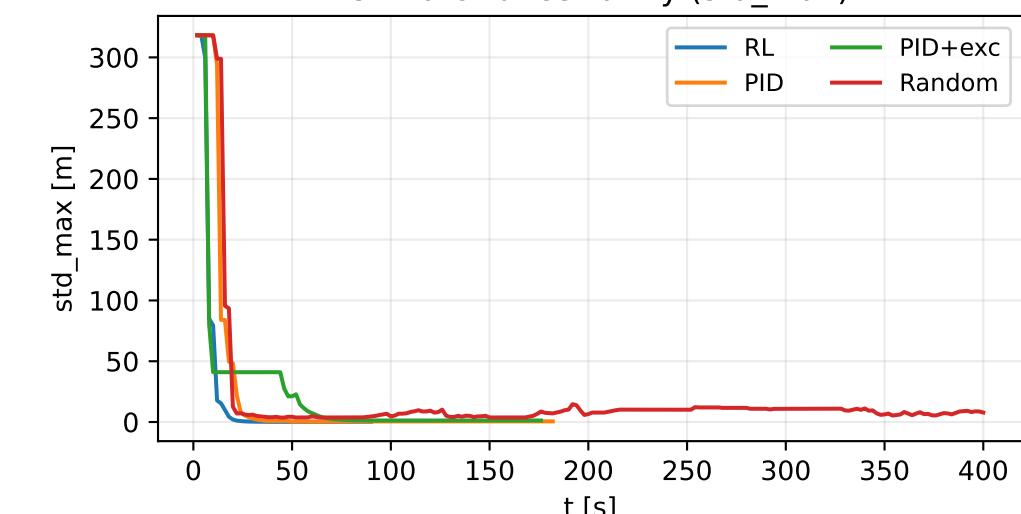
Trajectories (matched seed)



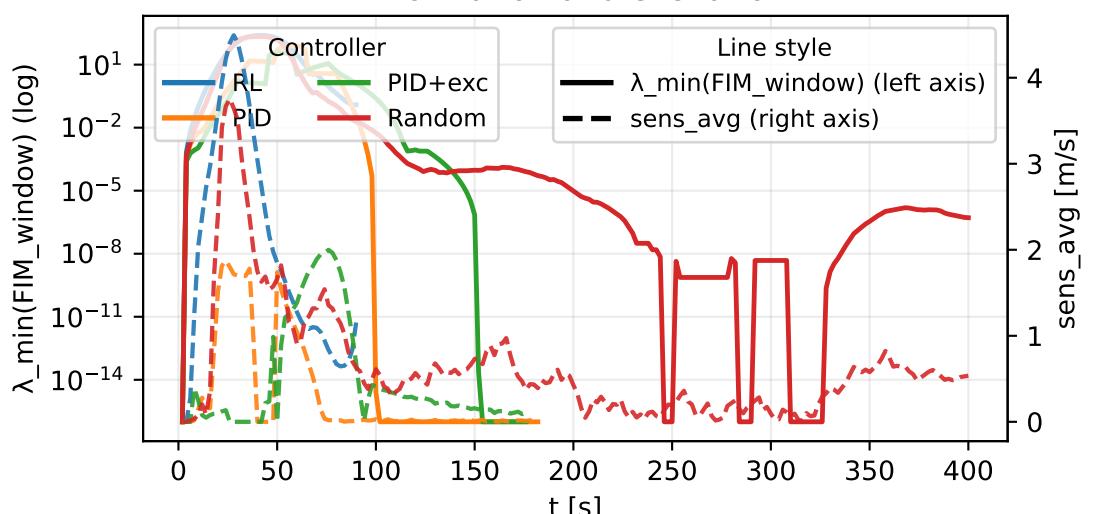
TRUE formation error



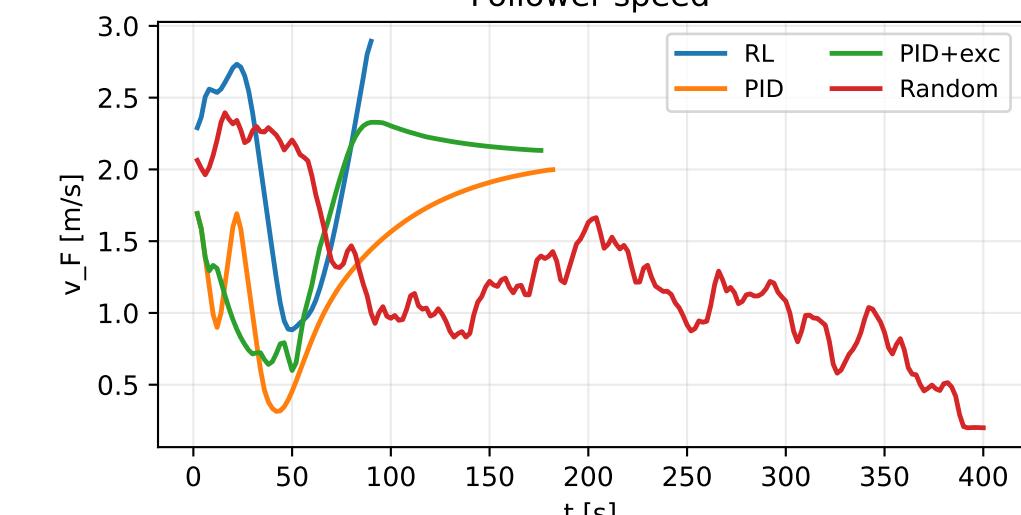
Estimator uncertainty (std_max)



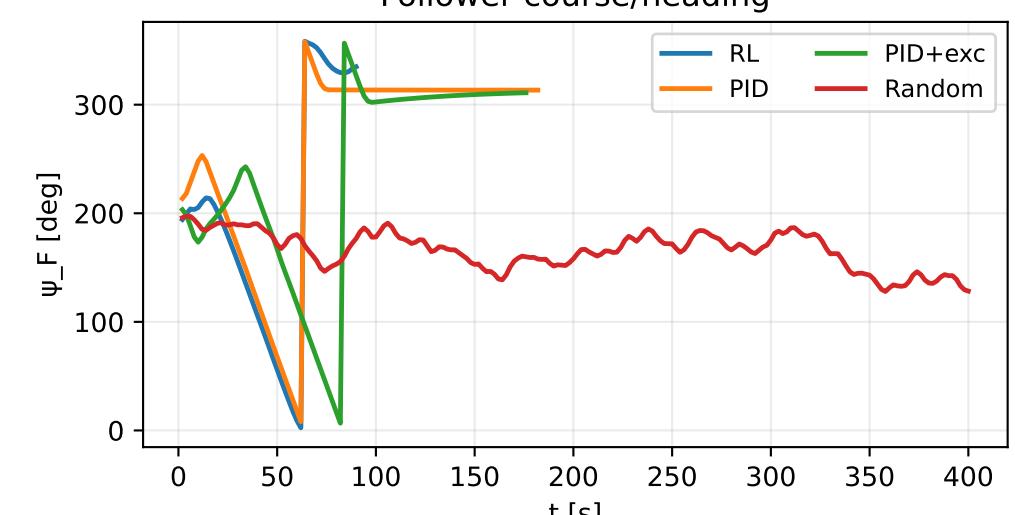
Information and excitation



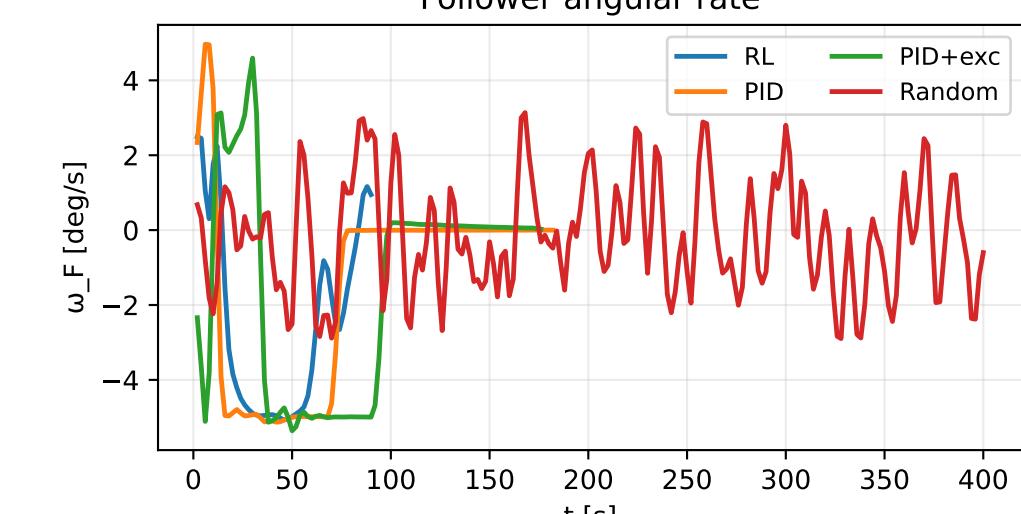
Follower speed



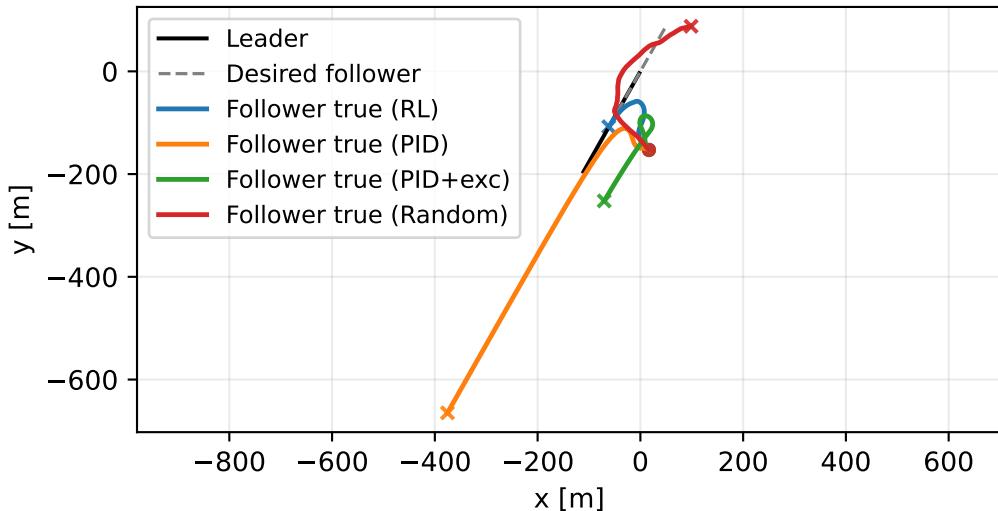
Follower course/heading



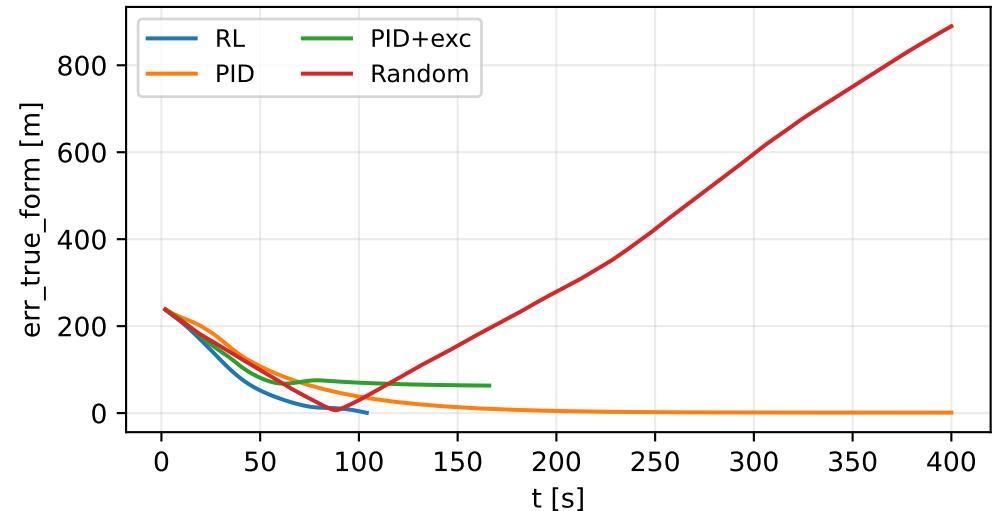
Follower angular rate



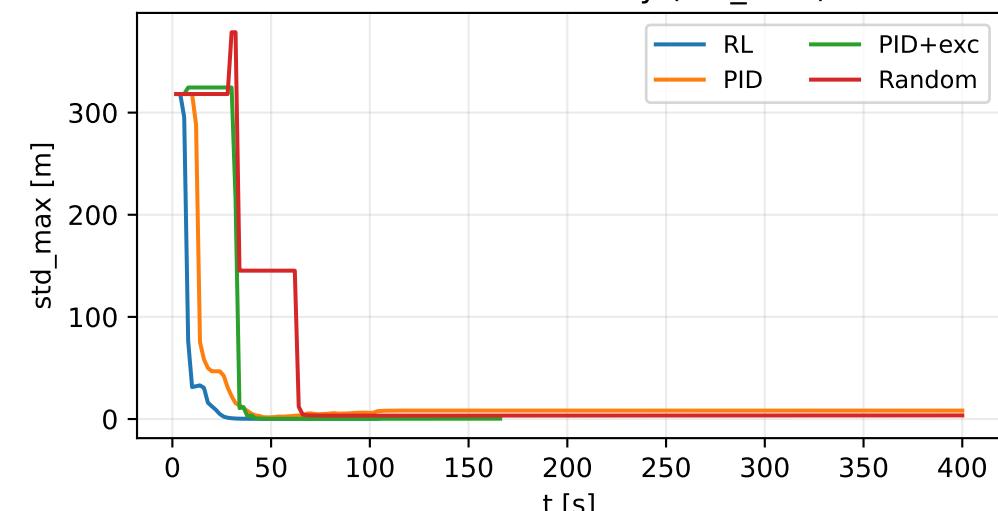
Trajectories (matched seed)



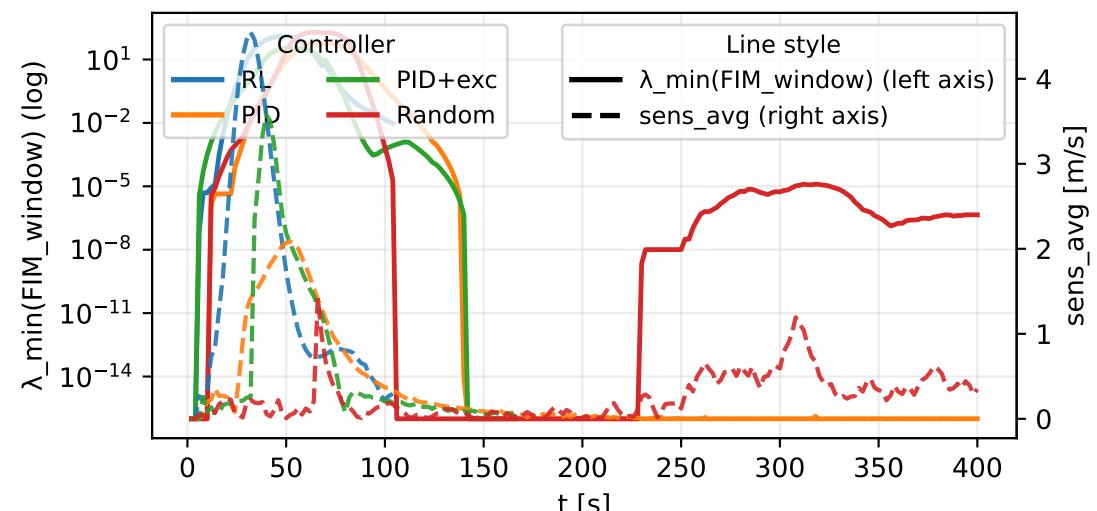
TRUE formation error



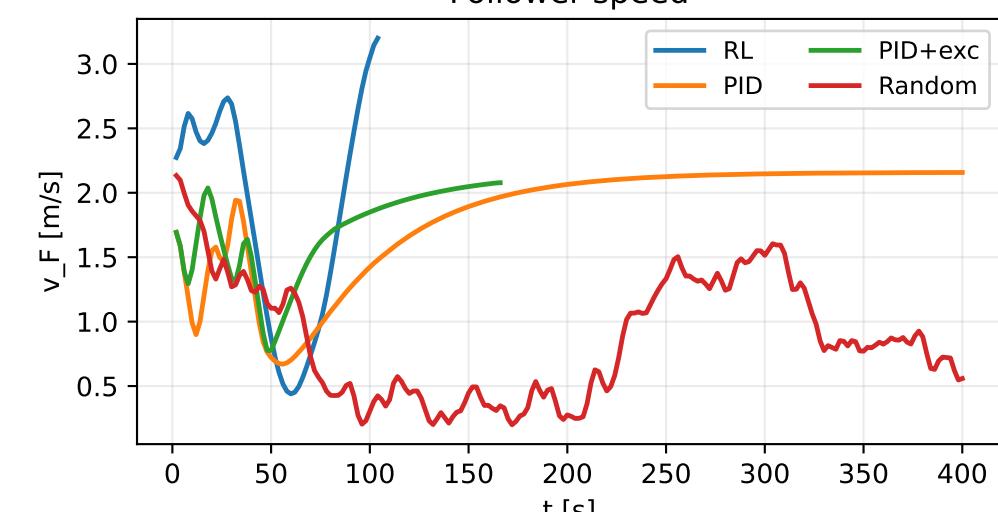
Estimator uncertainty (std_max)



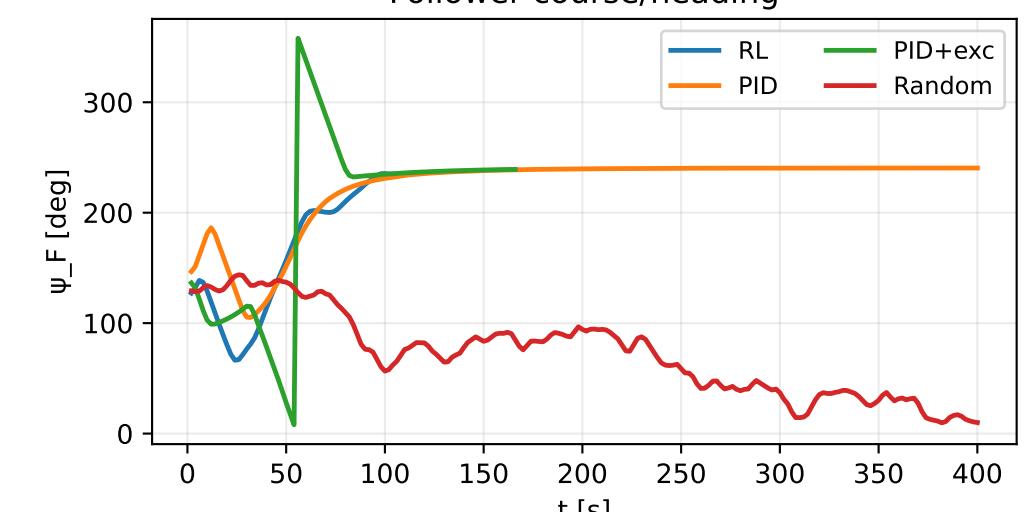
Information and excitation



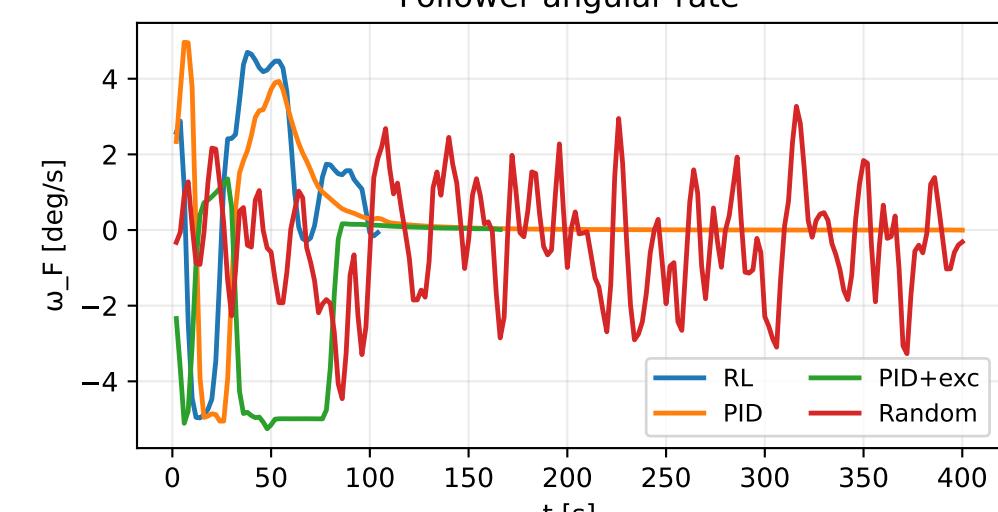
Follower speed



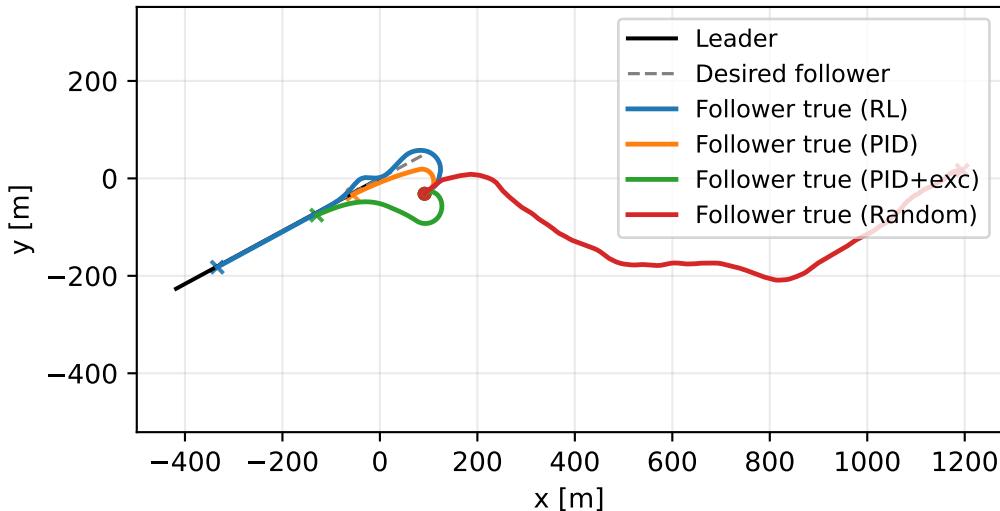
Follower course/heading



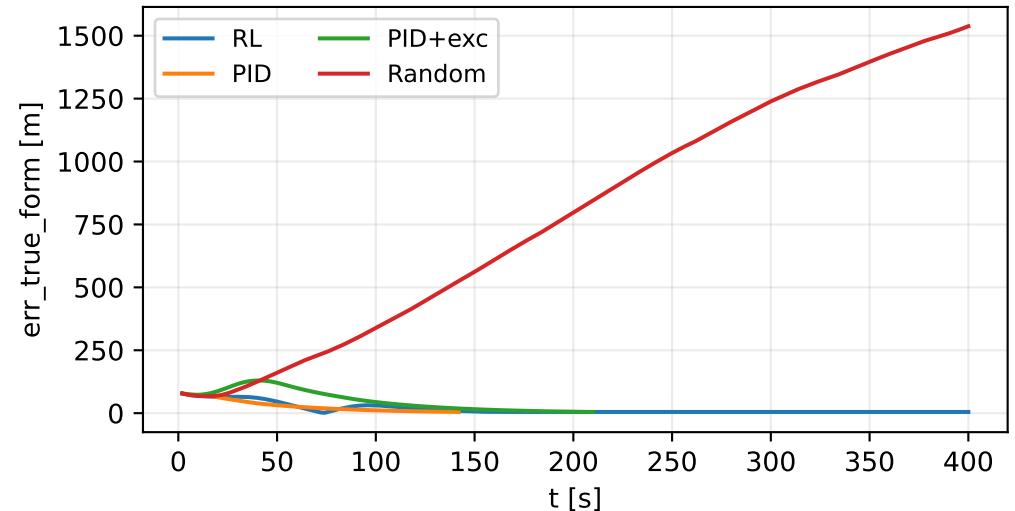
Follower angular rate



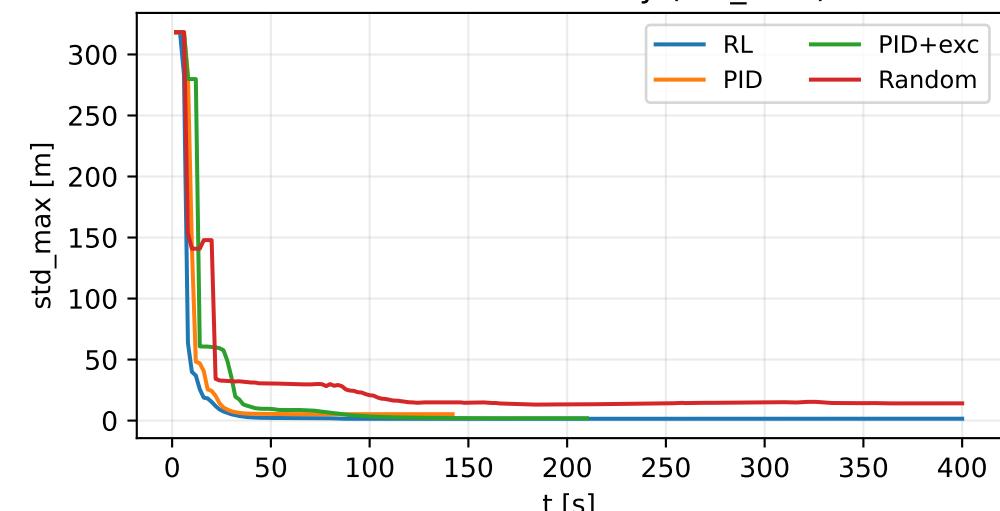
Trajectories (matched seed)



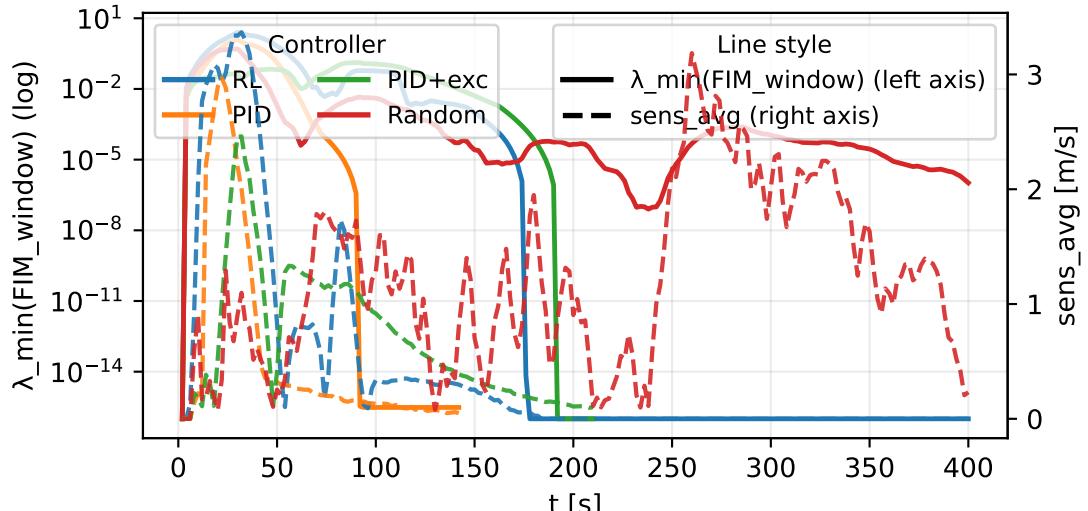
TRUE formation error



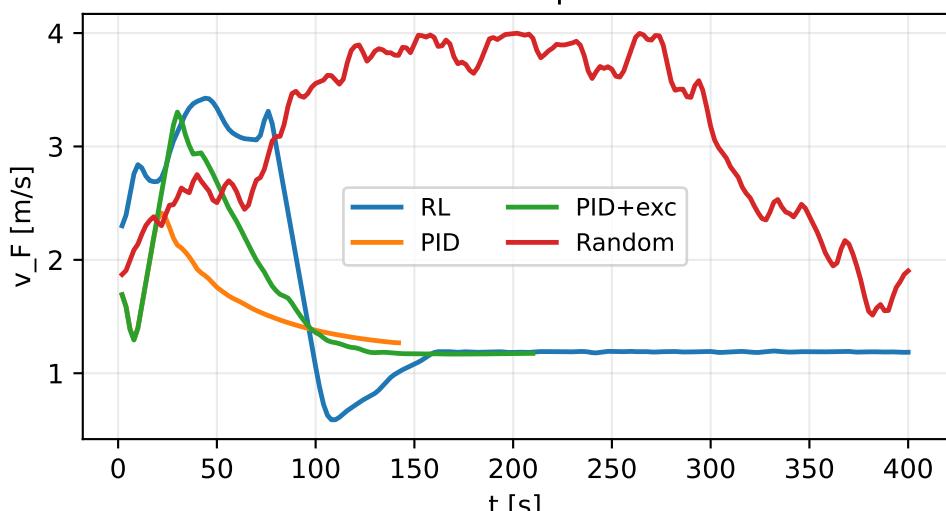
Estimator uncertainty (std_max)



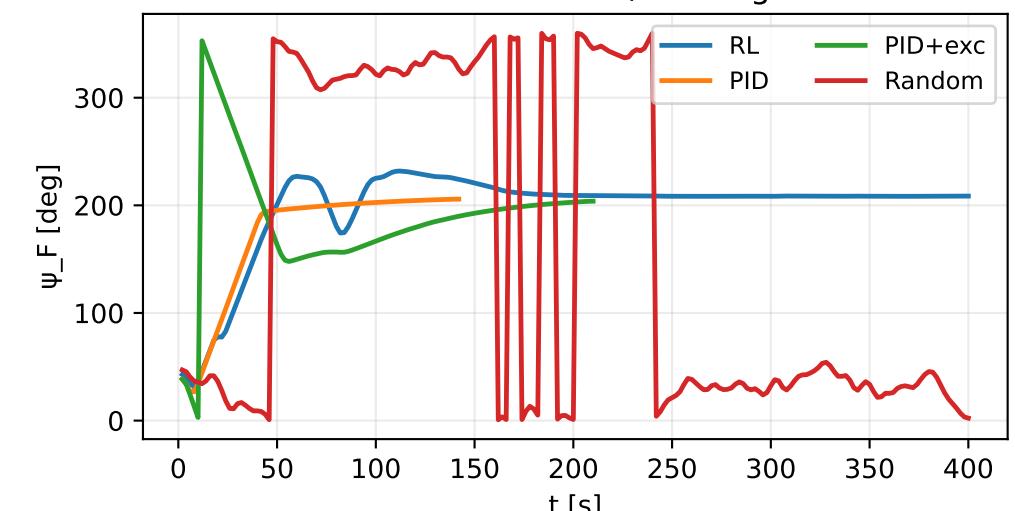
Information and excitation



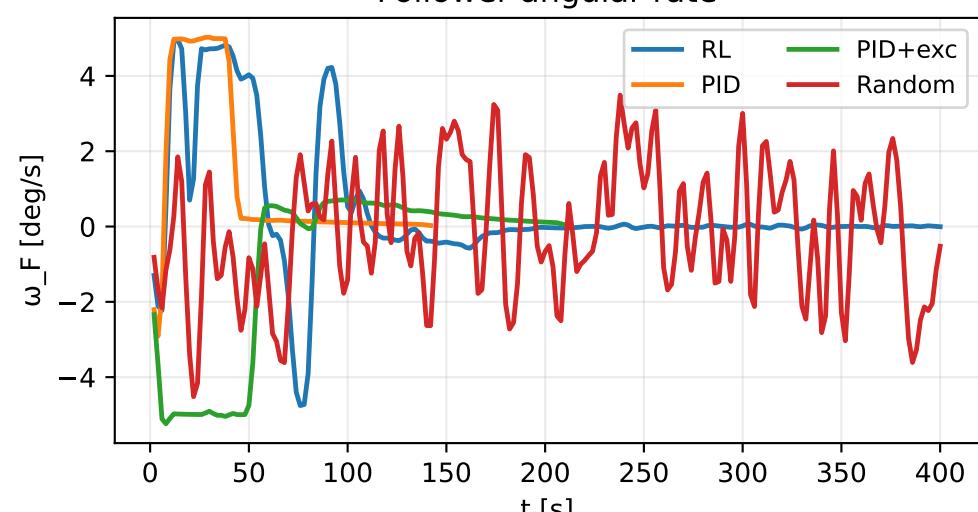
Follower speed



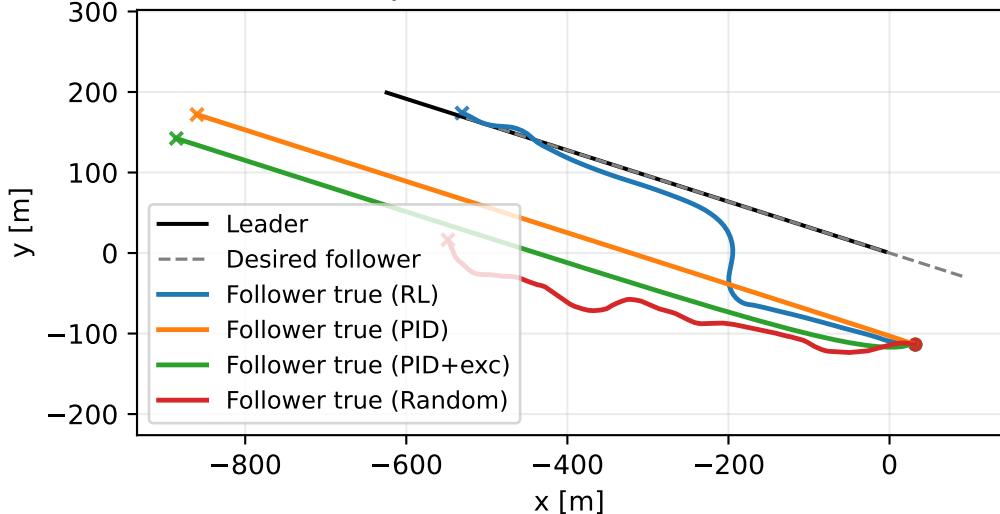
Follower course/heading



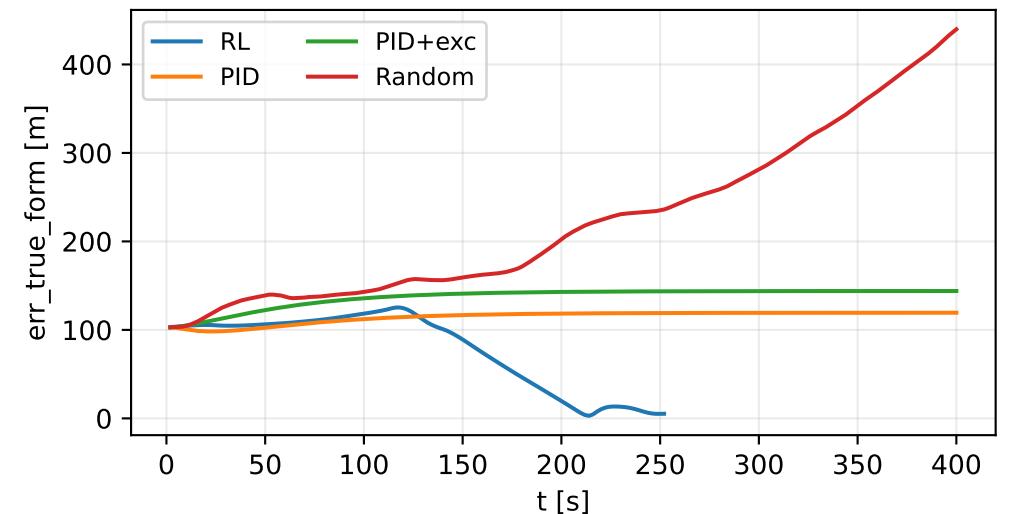
Follower angular rate



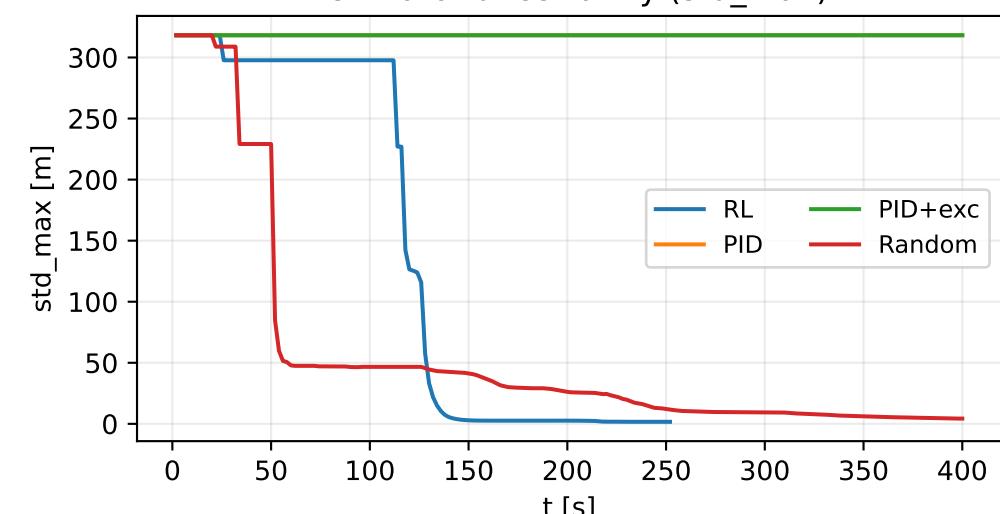
Trajectories (matched seed)



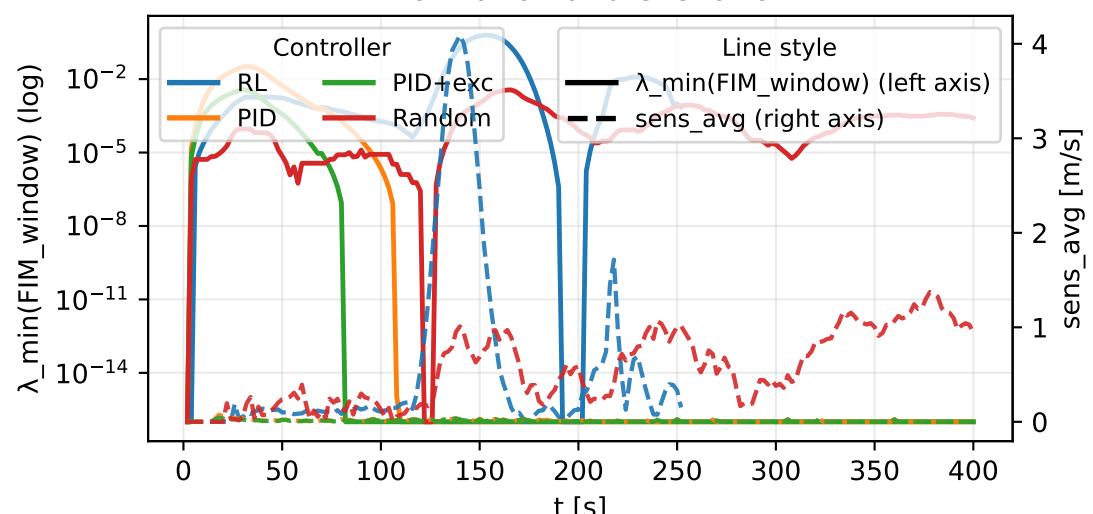
TRUE formation error



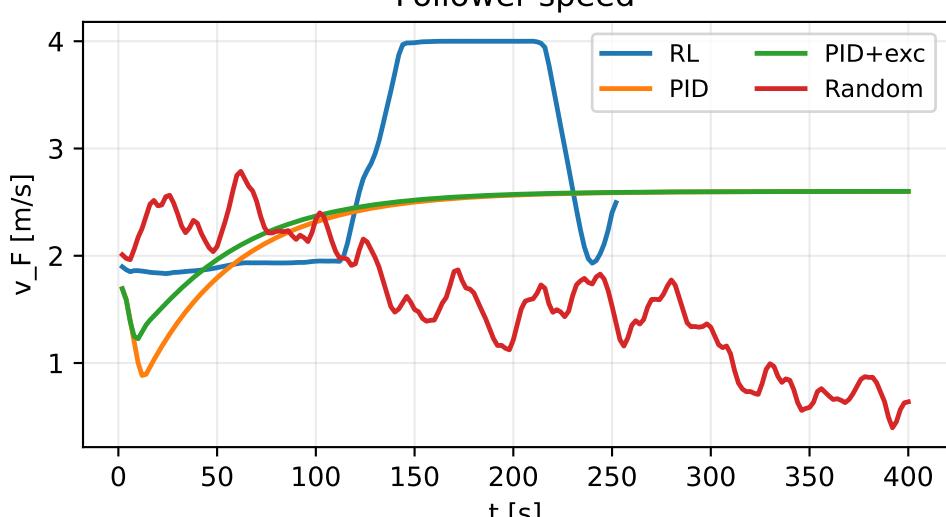
Estimator uncertainty (std_max)



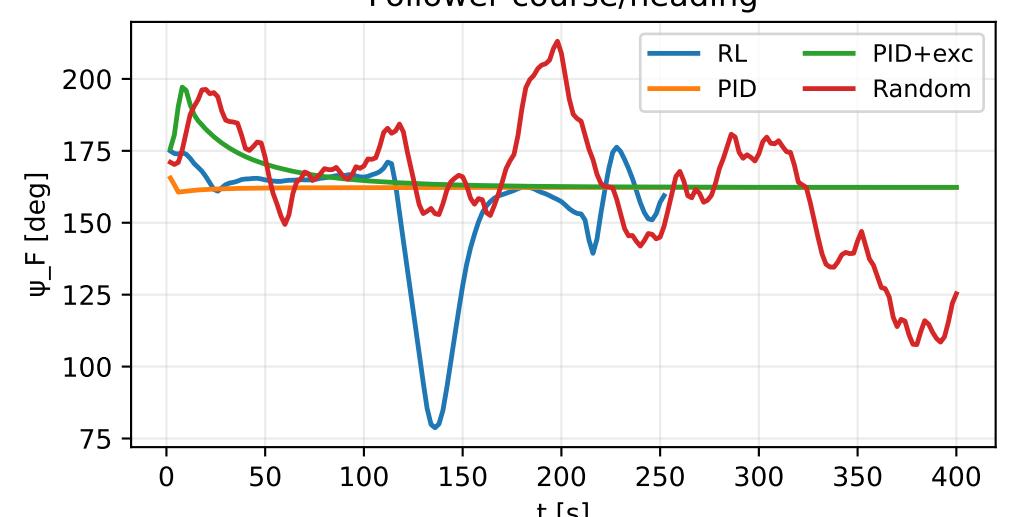
Information and excitation



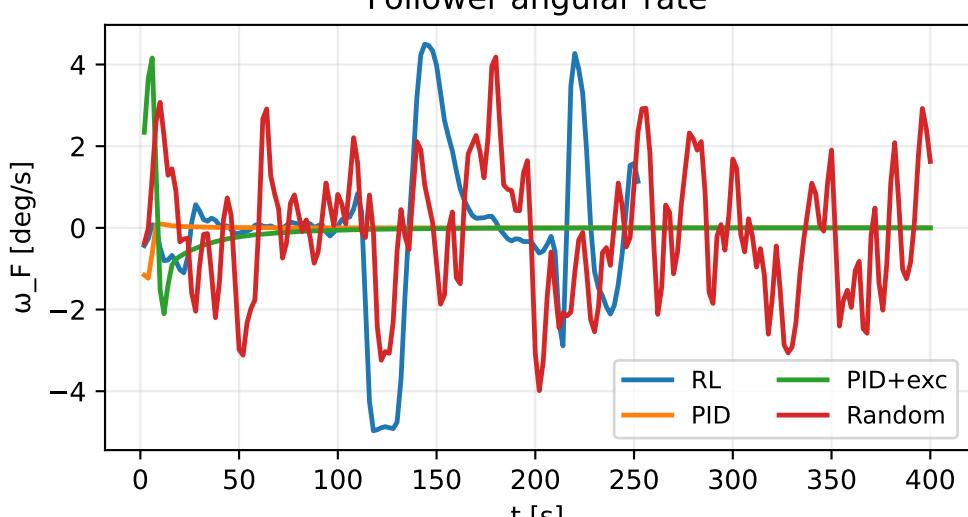
Follower speed



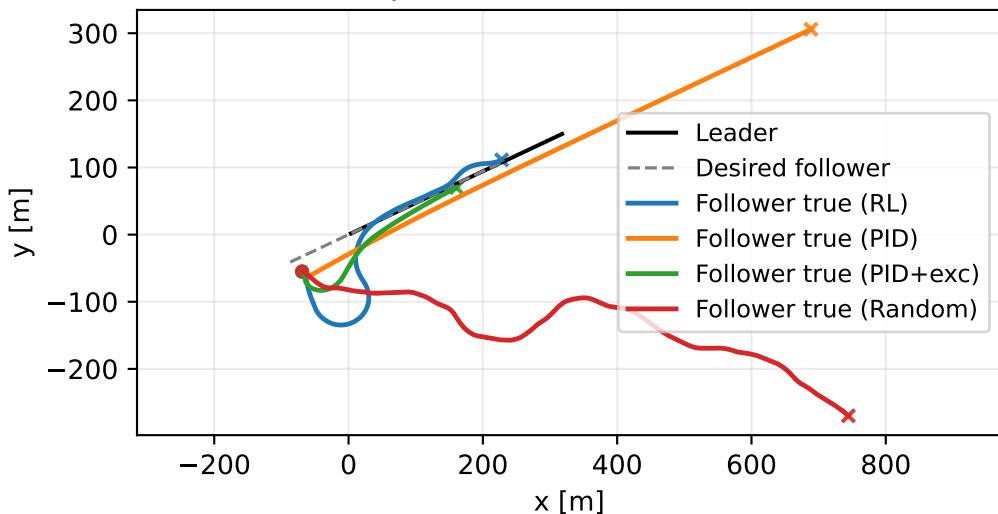
Follower course/heading



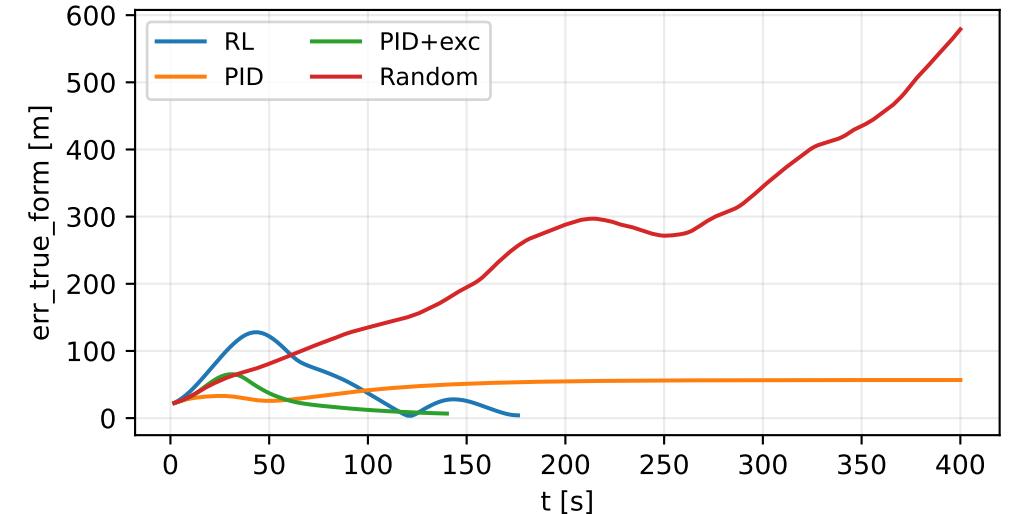
Follower angular rate



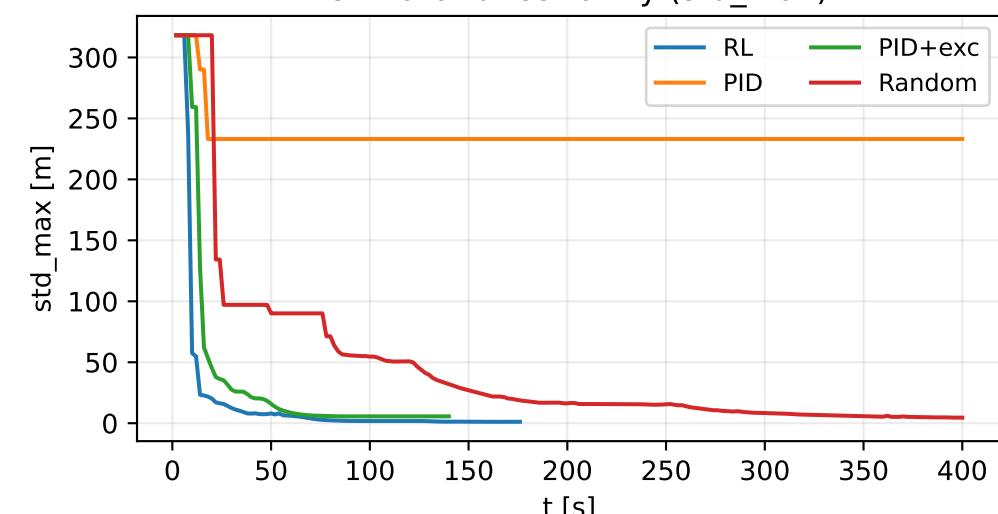
Trajectories (matched seed)



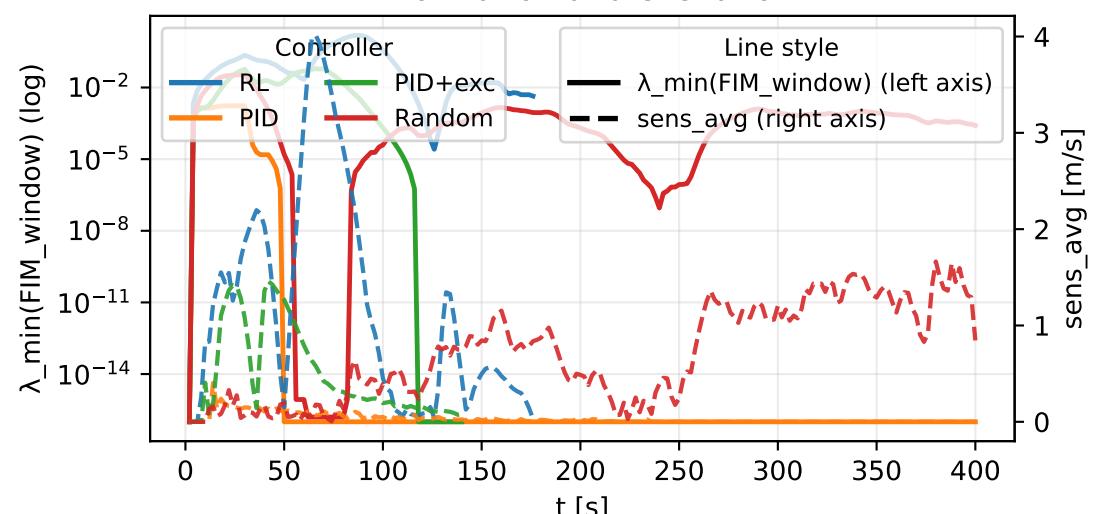
TRUE formation error



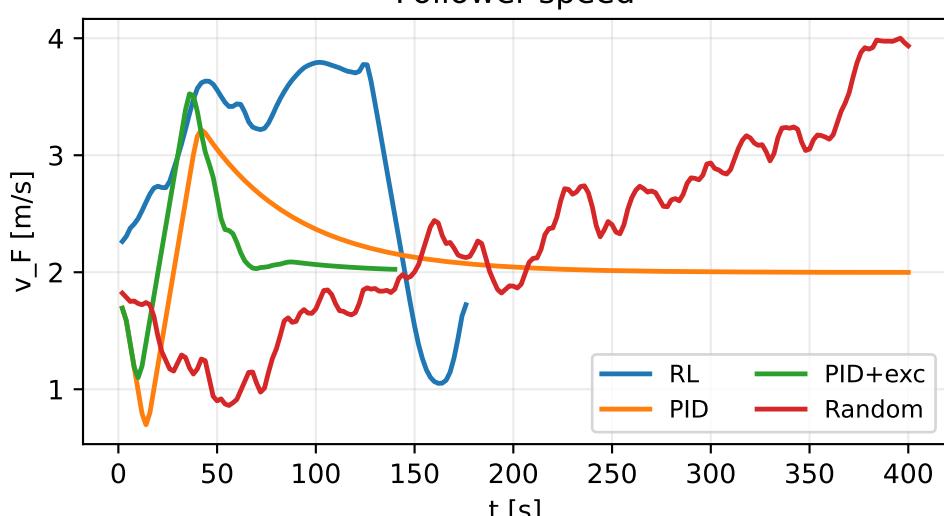
Estimator uncertainty (std_max)



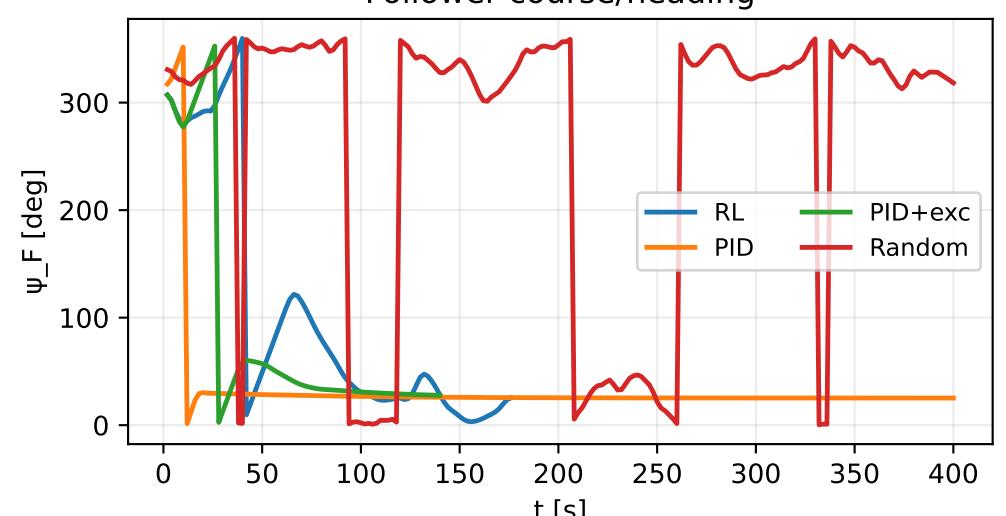
Information and excitation



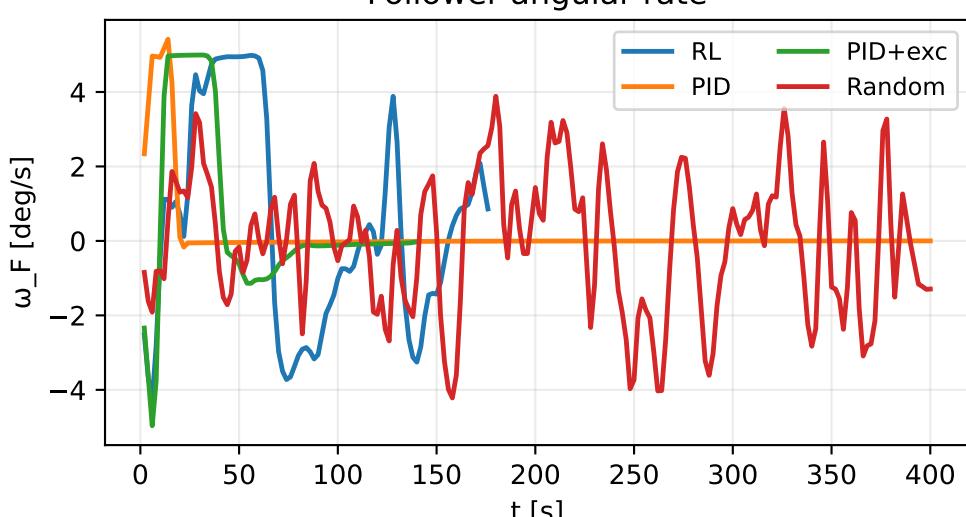
Follower speed



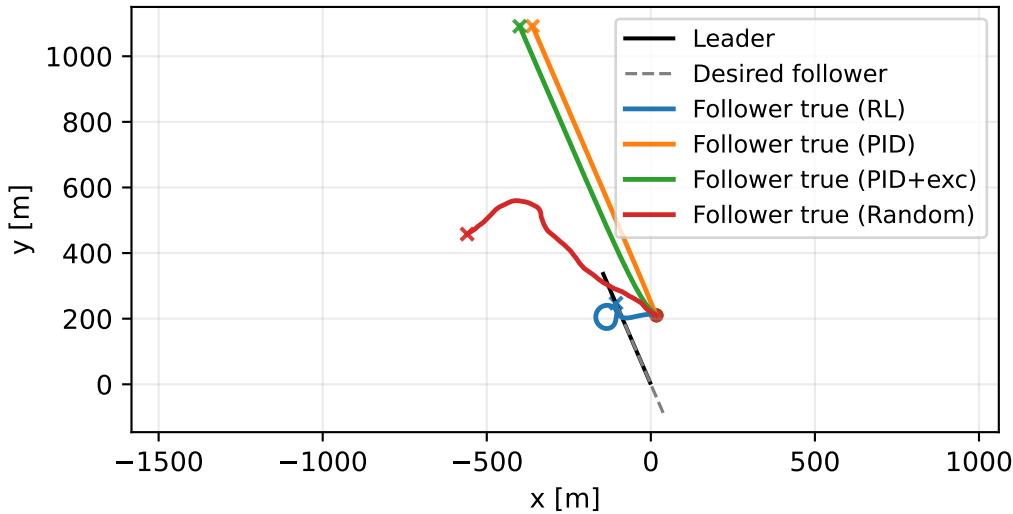
Follower course/heading



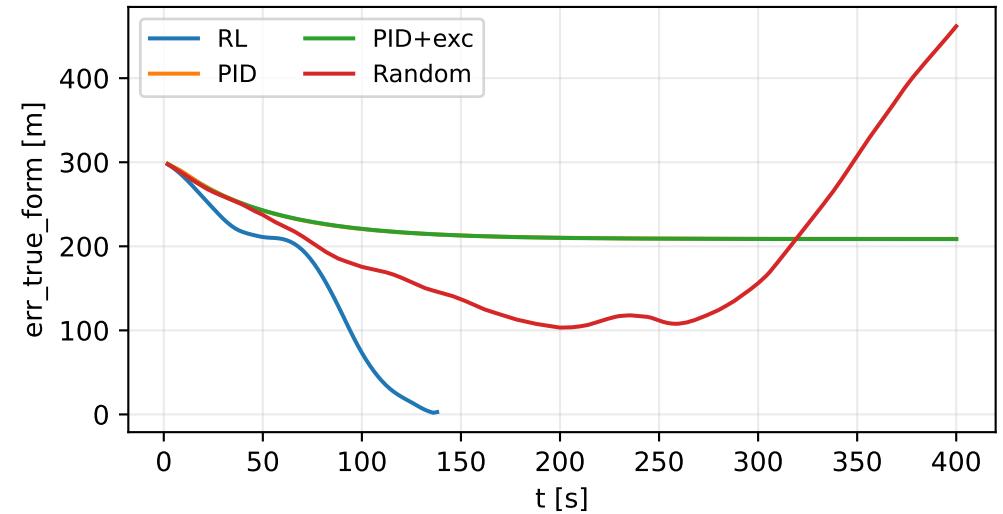
Follower angular rate



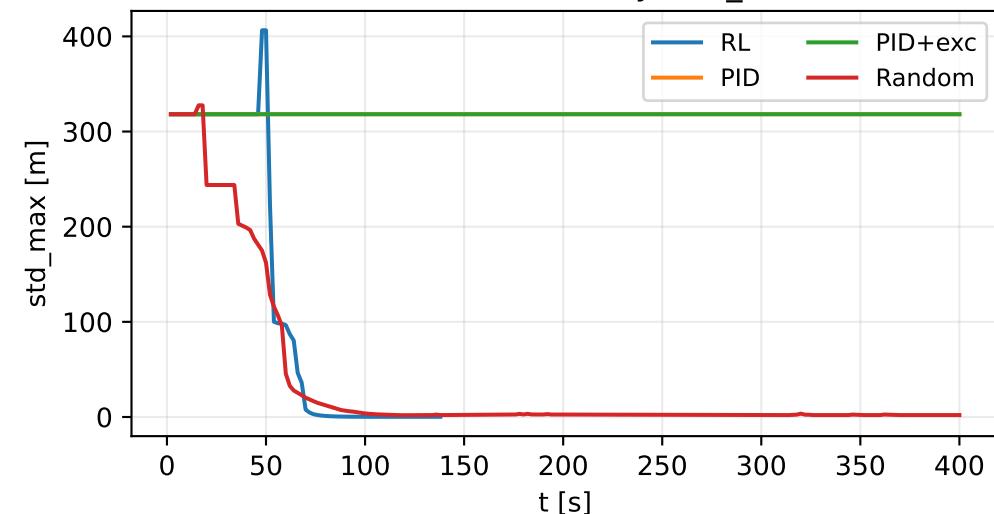
Trajectories (matched seed)



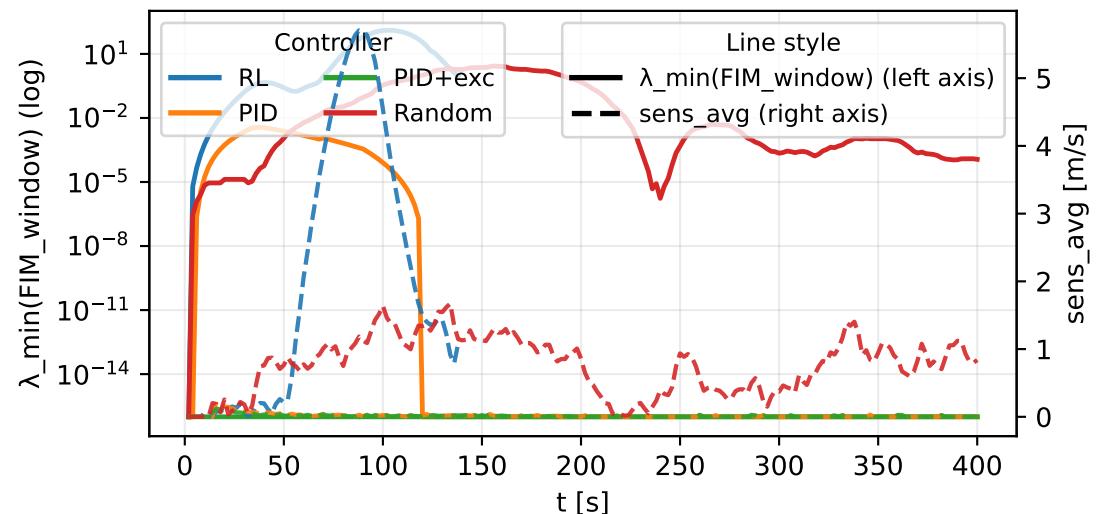
TRUE formation error



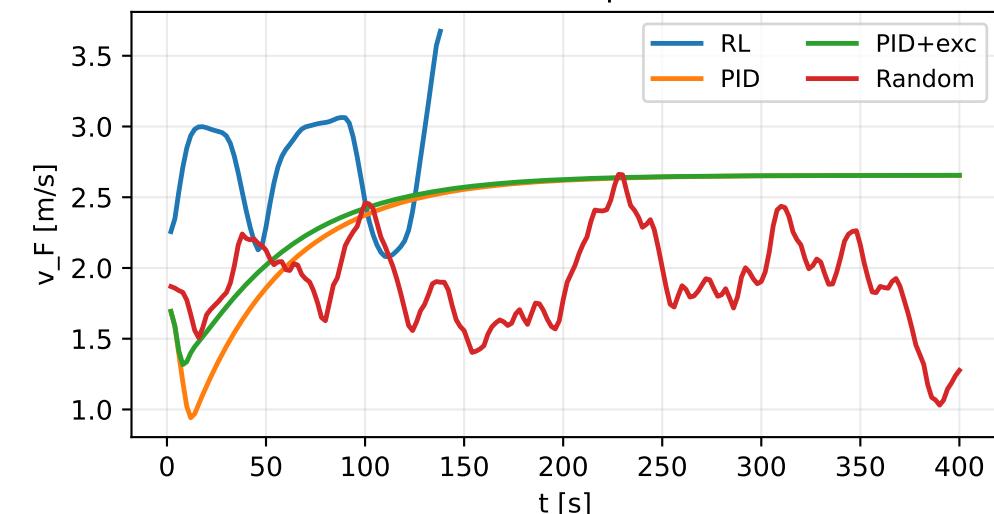
Estimator uncertainty (std_max)



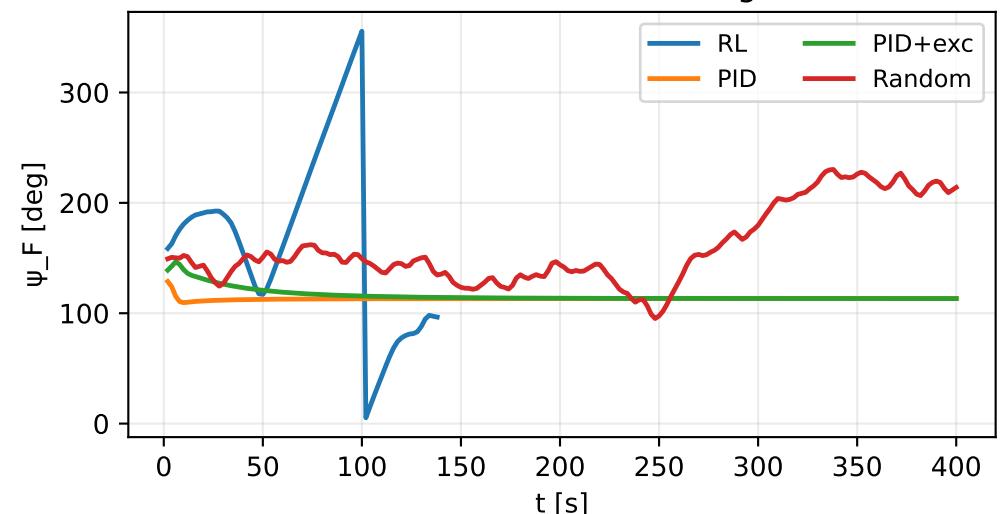
Information and excitation



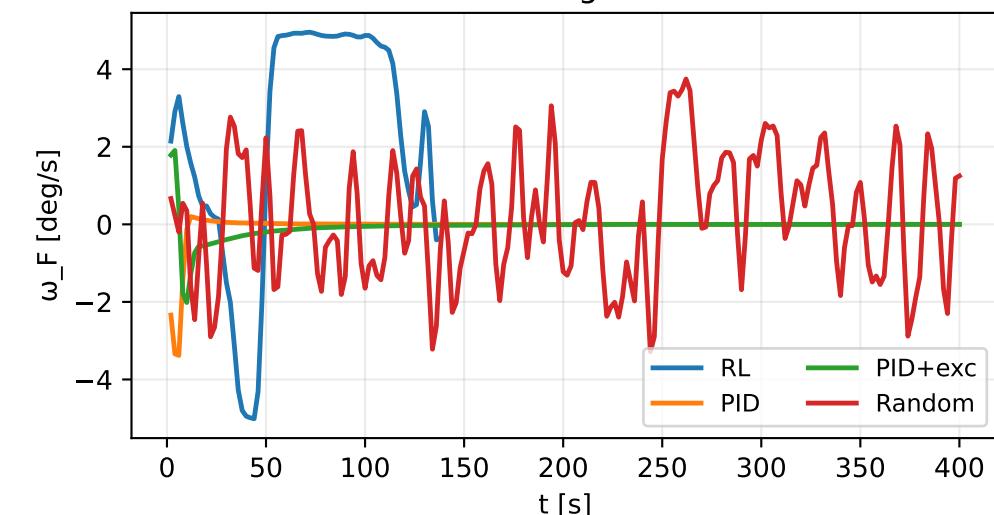
Follower speed



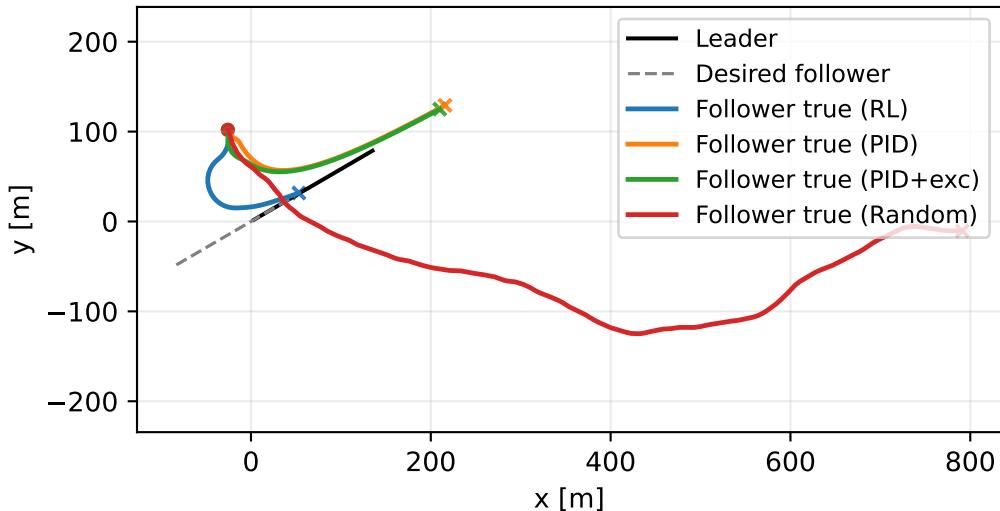
Follower course/heading



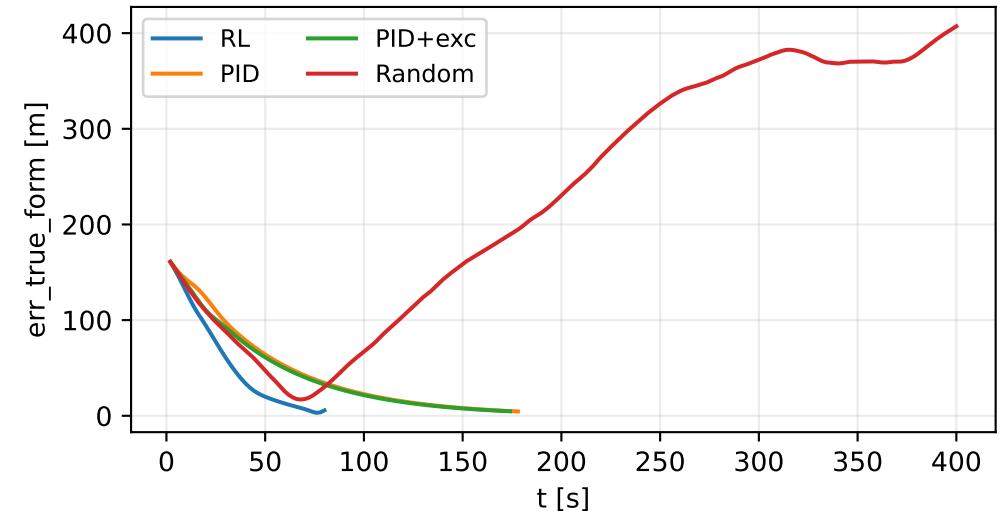
Follower angular rate



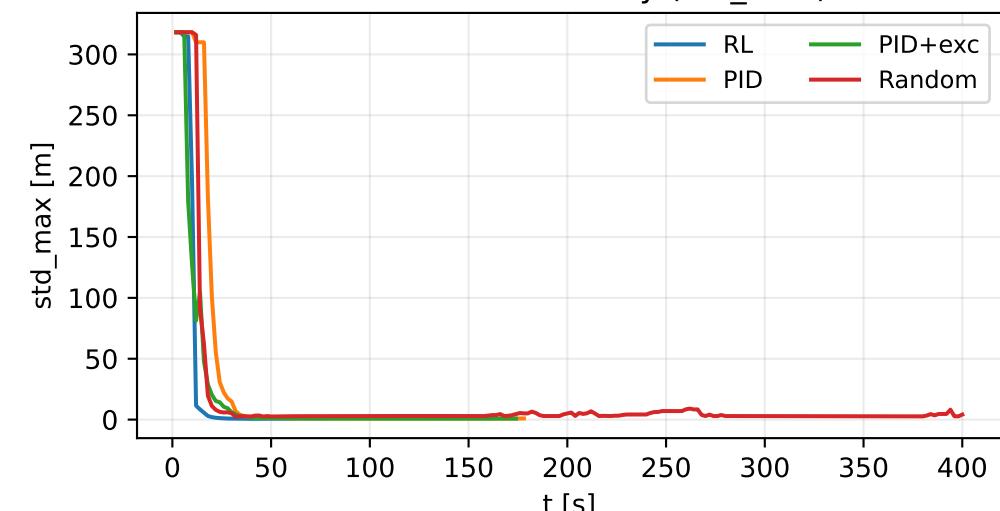
Trajectories (matched seed)



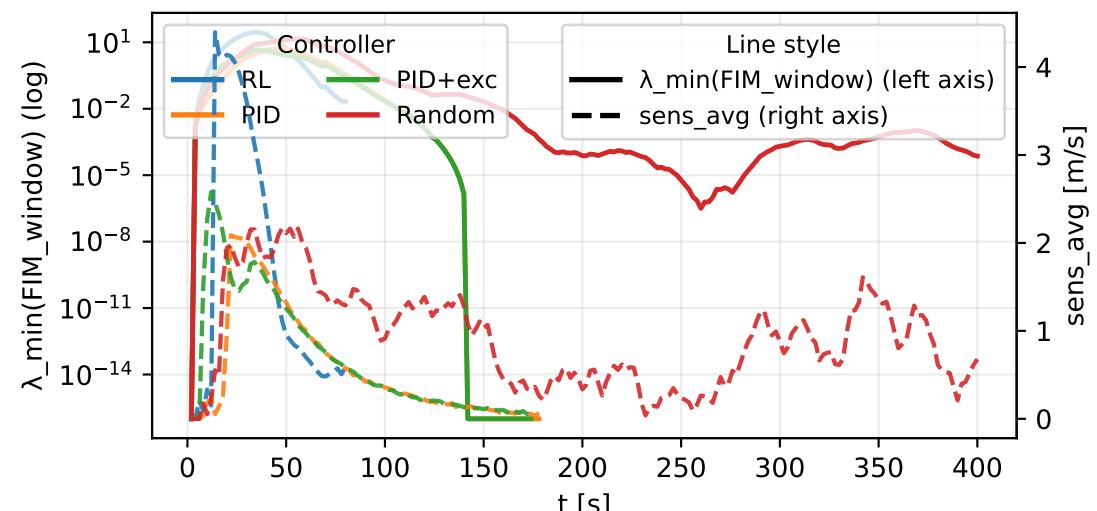
TRUE formation error



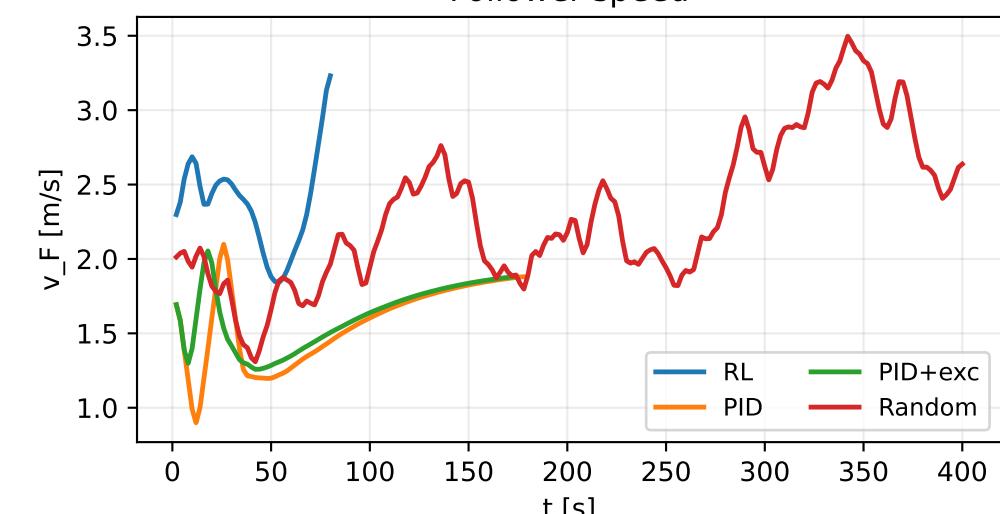
Estimator uncertainty (std_max)



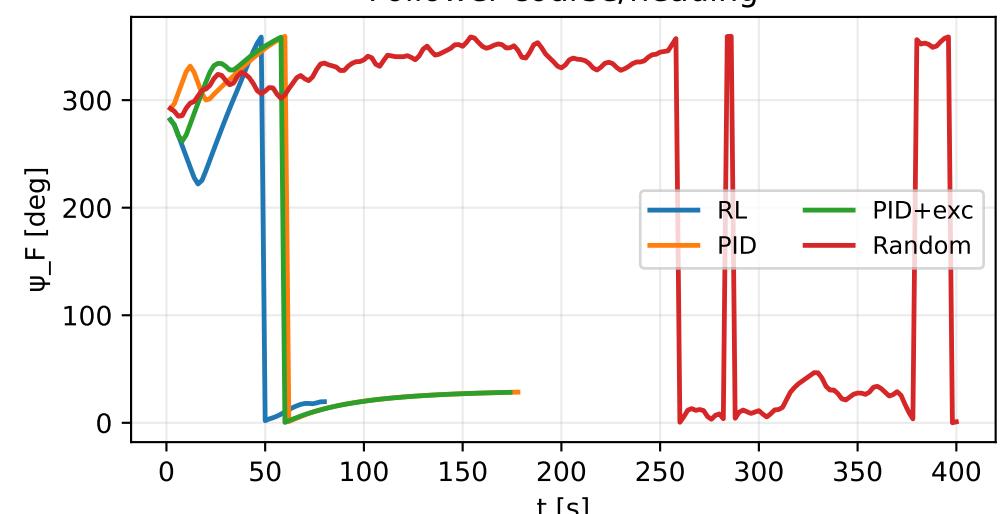
Information and excitation



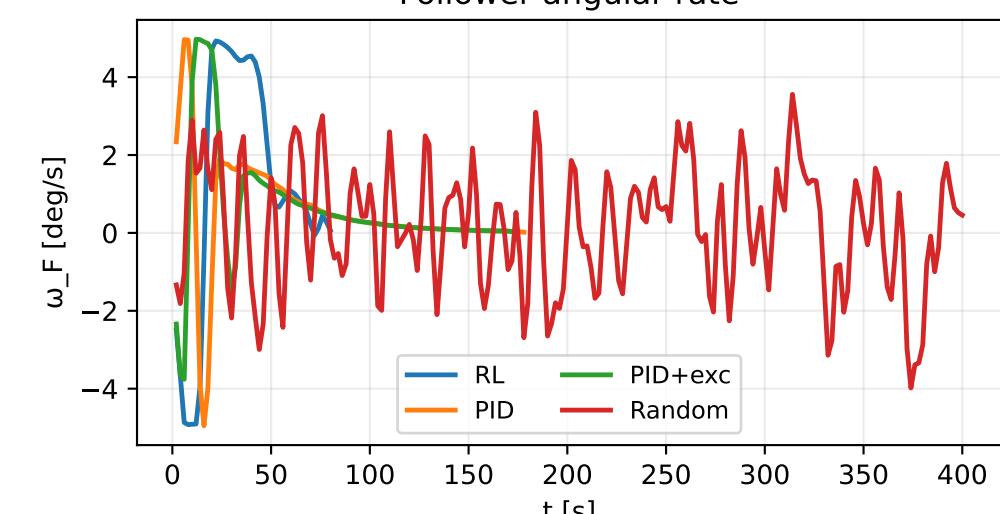
Follower speed



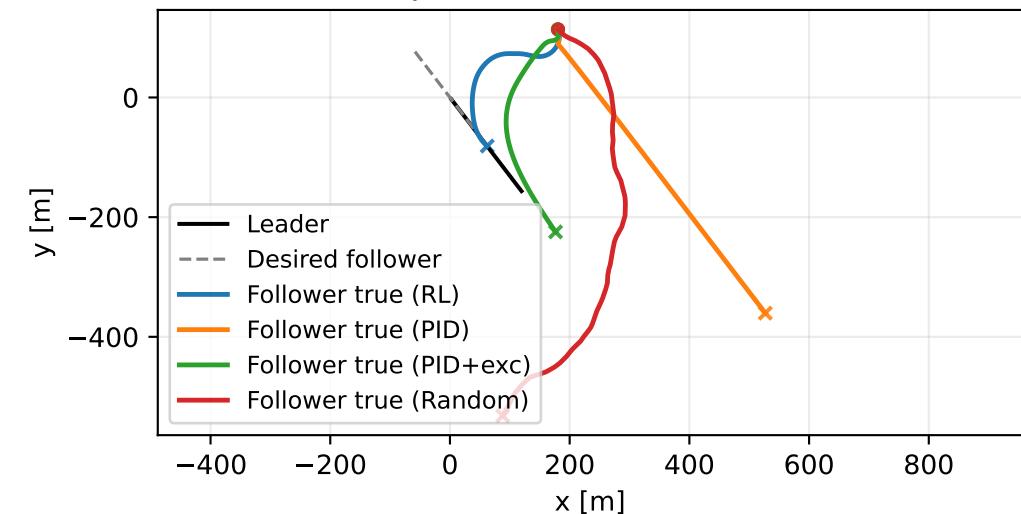
Follower course/heading



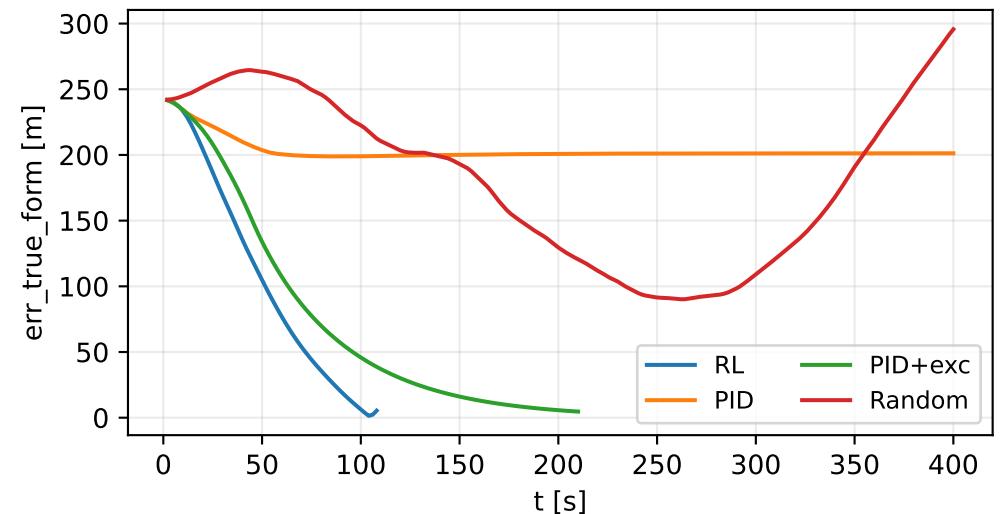
Follower angular rate



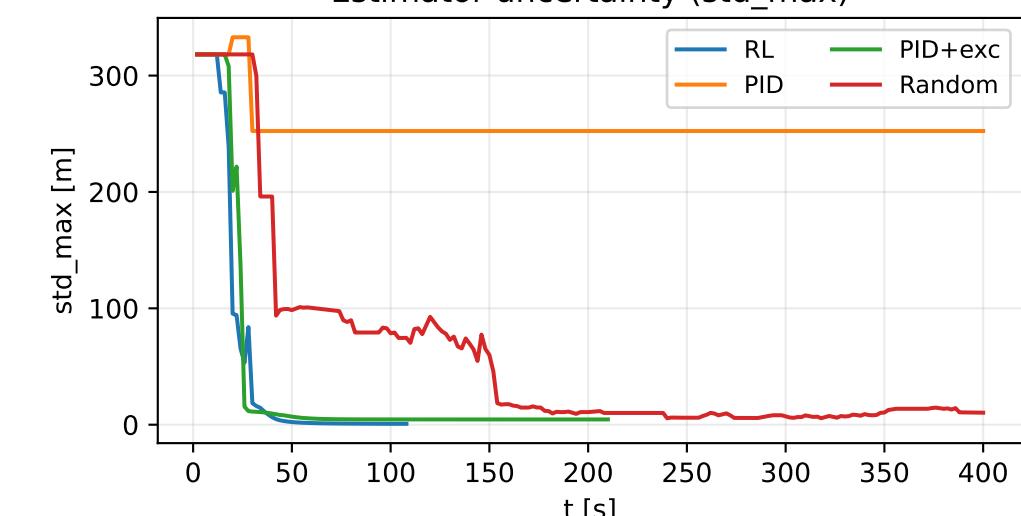
Trajectories (matched seed)



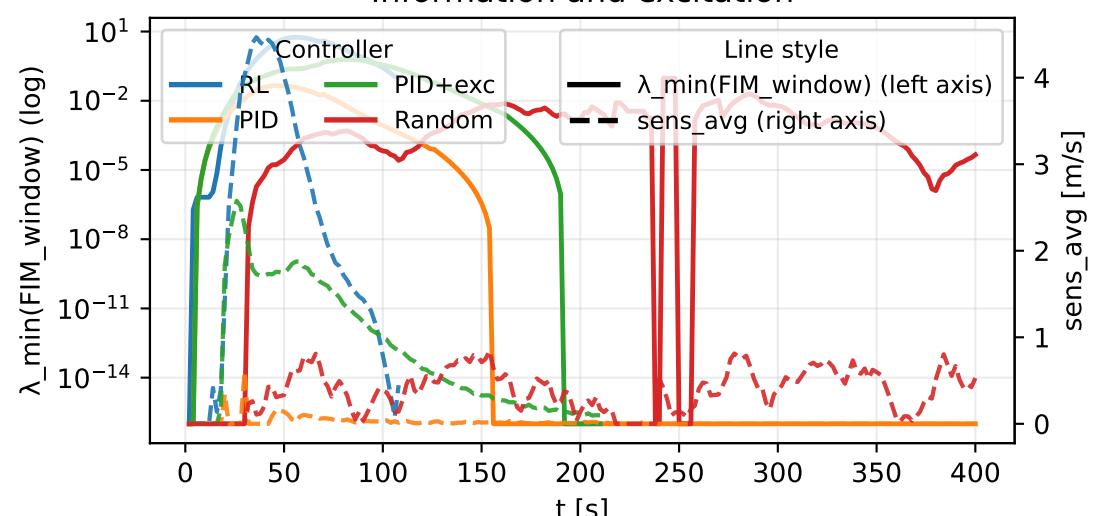
TRUE formation error



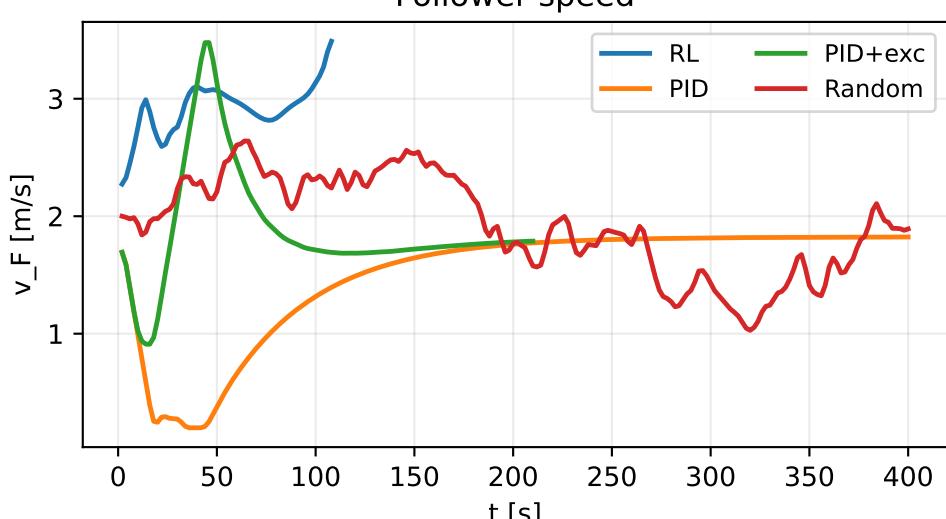
Estimator uncertainty (std_max)



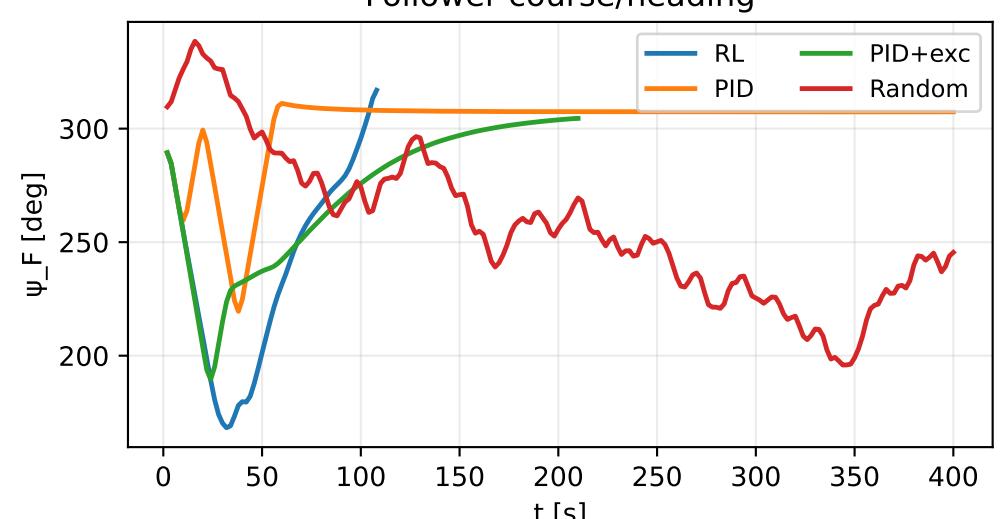
Information and excitation



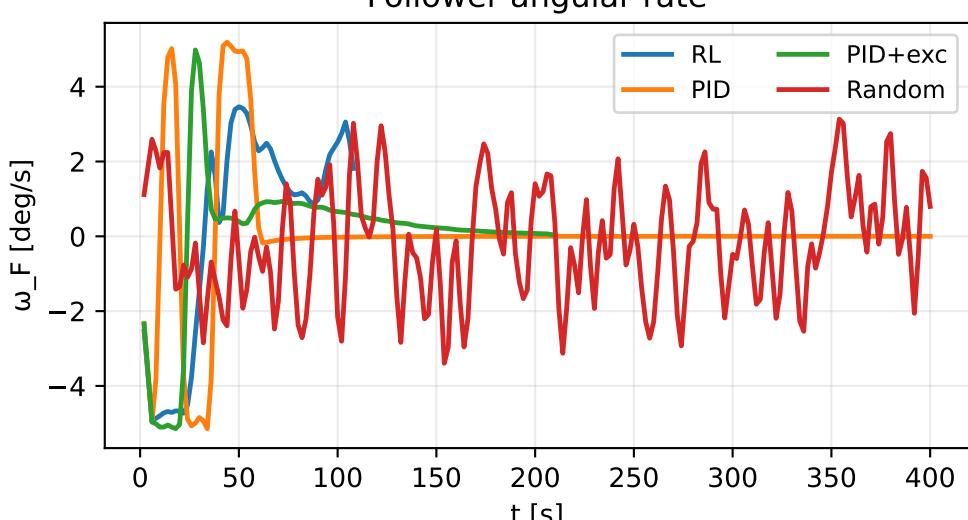
Follower speed



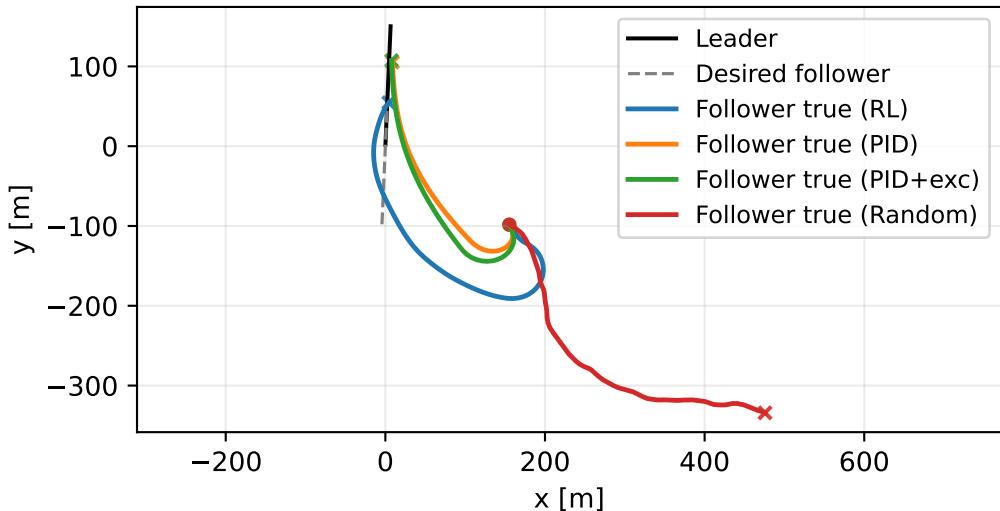
Follower course/heading



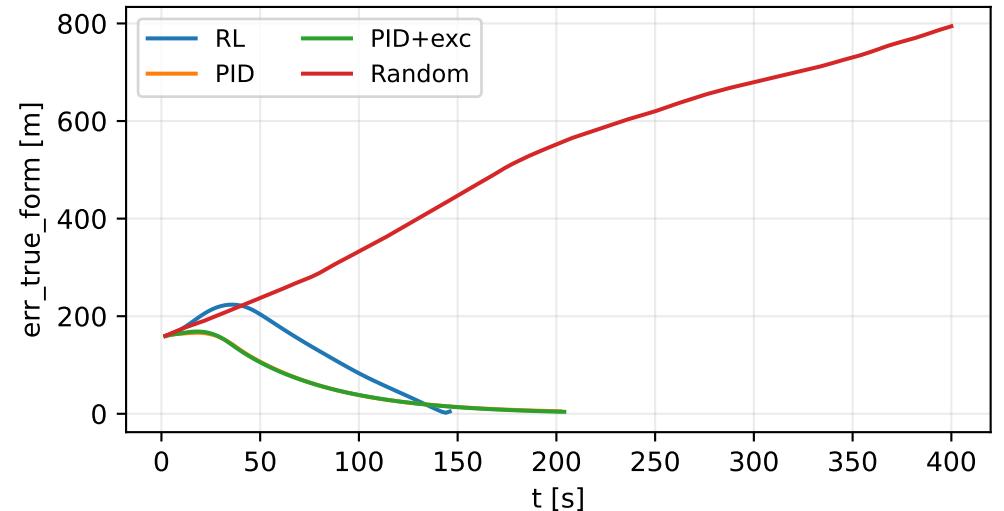
Follower angular rate



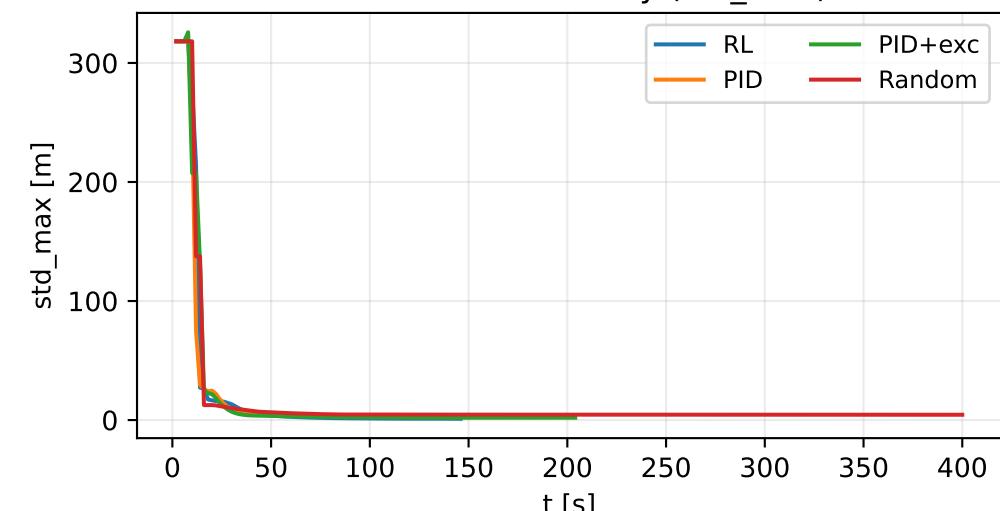
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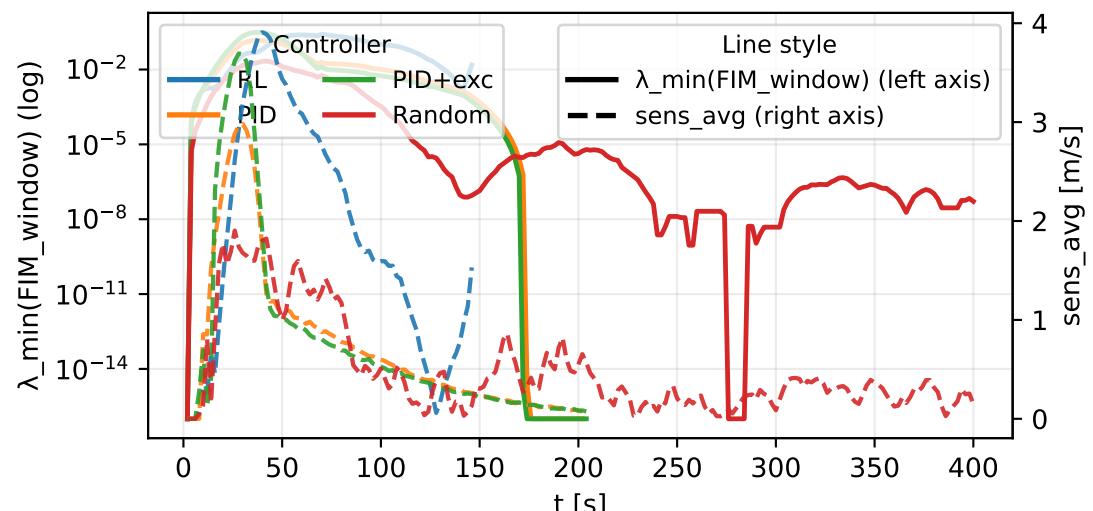
TRUE formation error



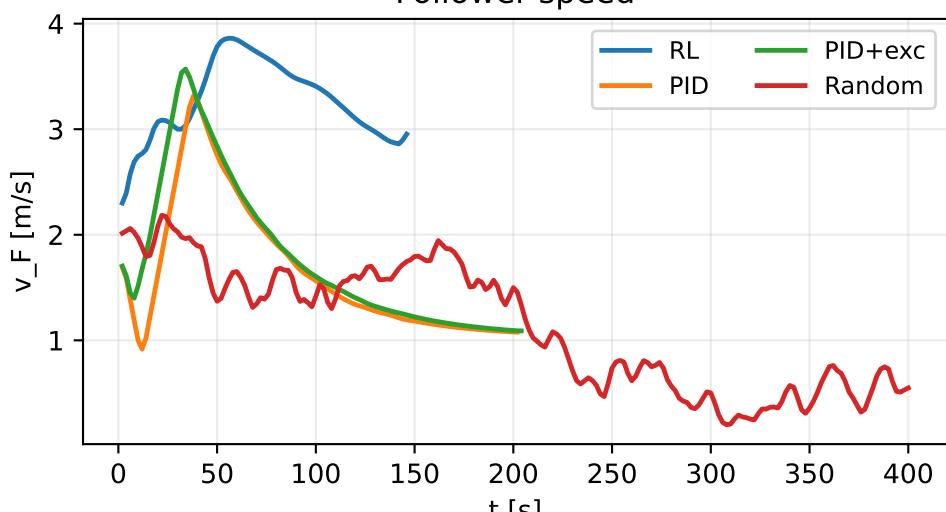
Estimator uncertainty (std_max)



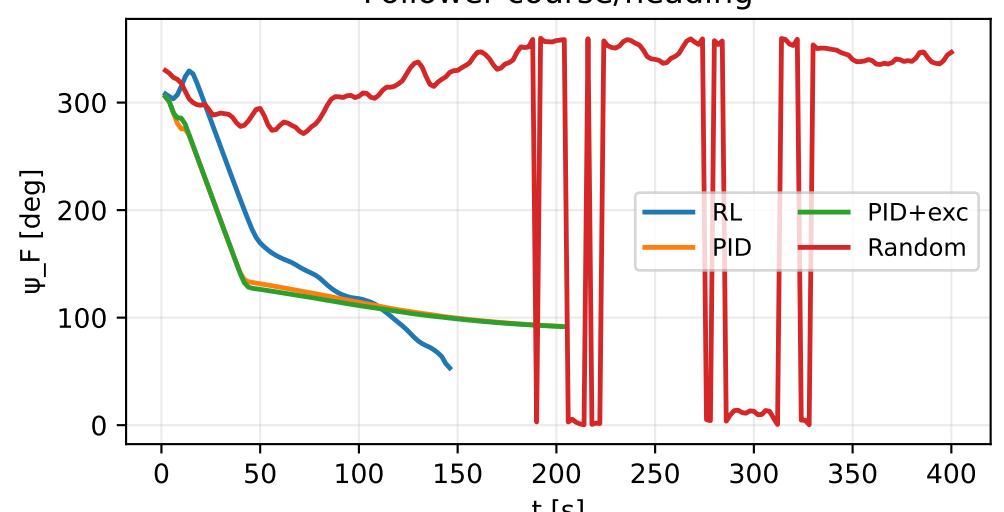
Information and excitation



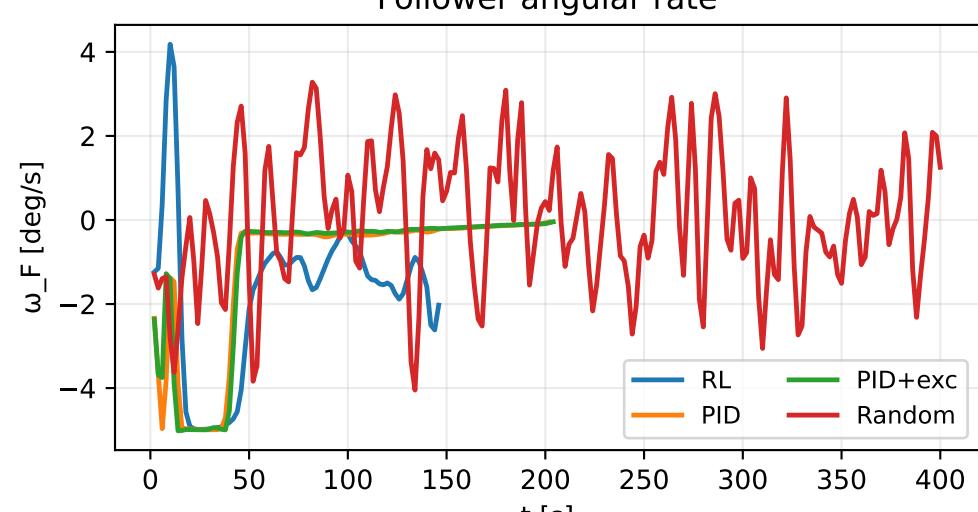
Follower speed



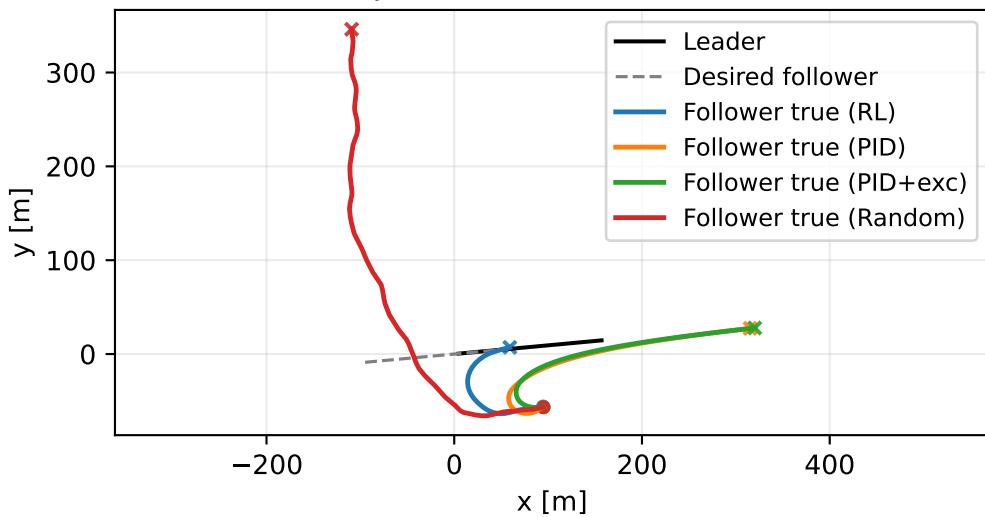
Follower course/heading



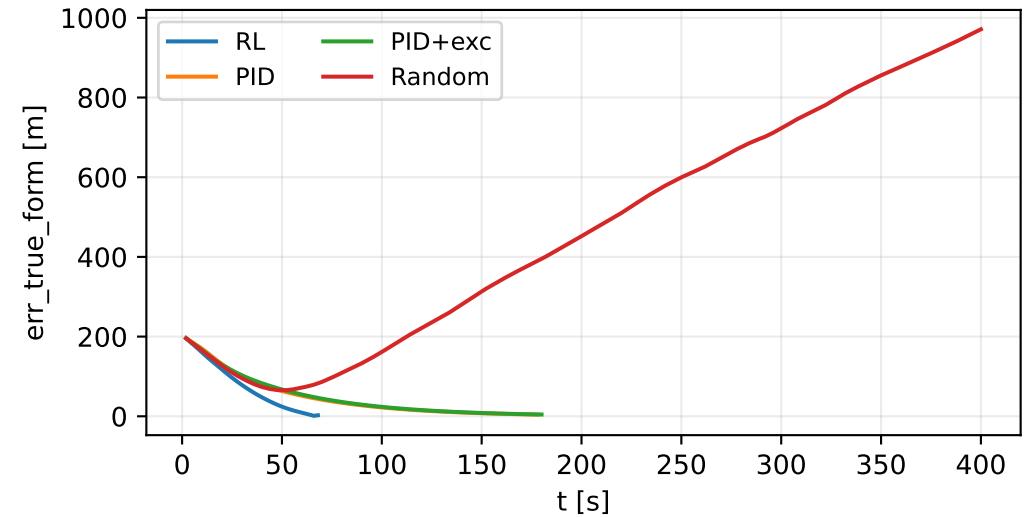
Follower angular rate



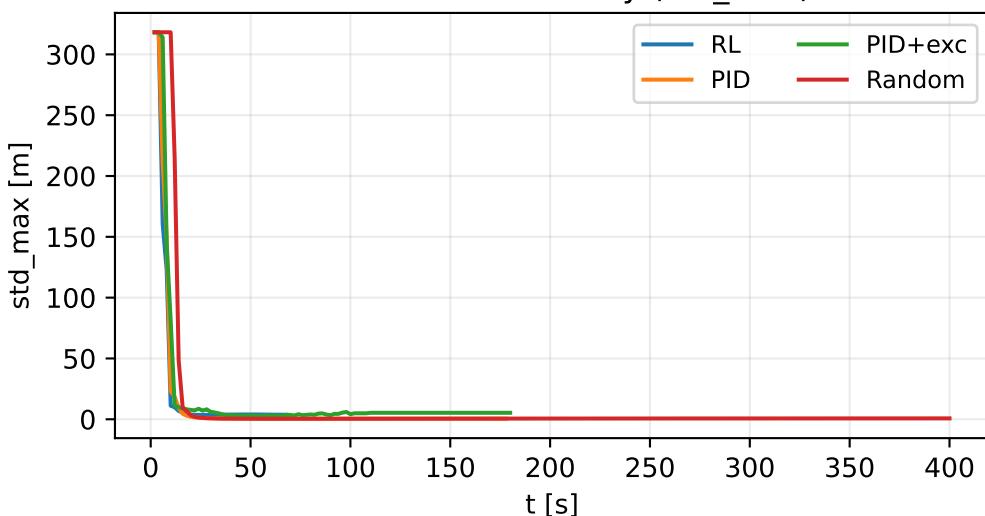
Trajectories (matched seed)



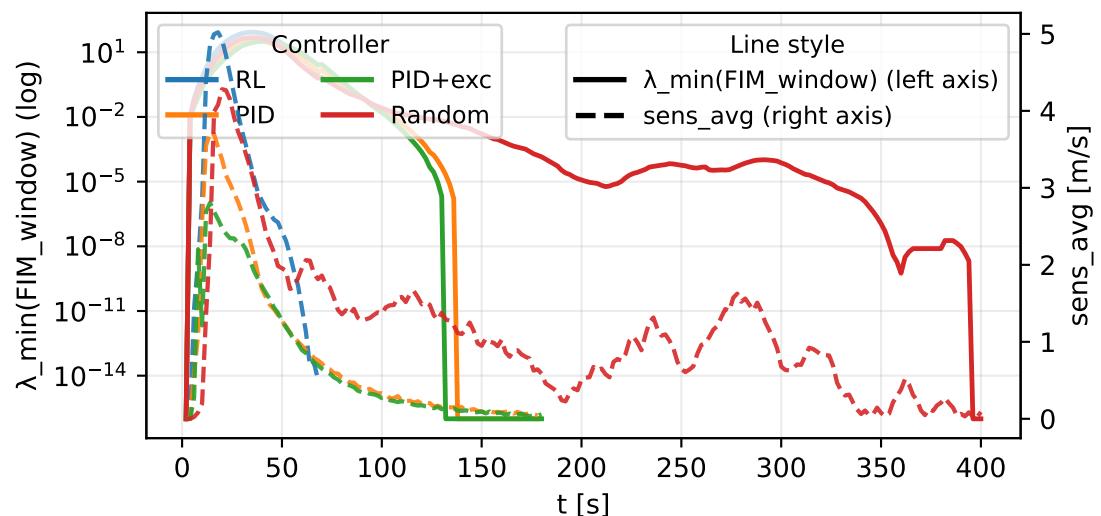
TRUE formation error



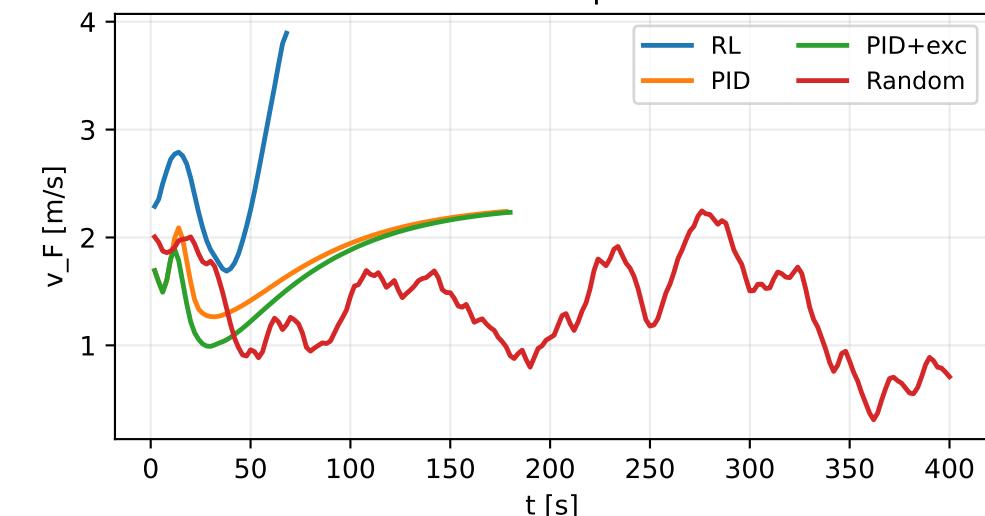
Estimator uncertainty (std_max)



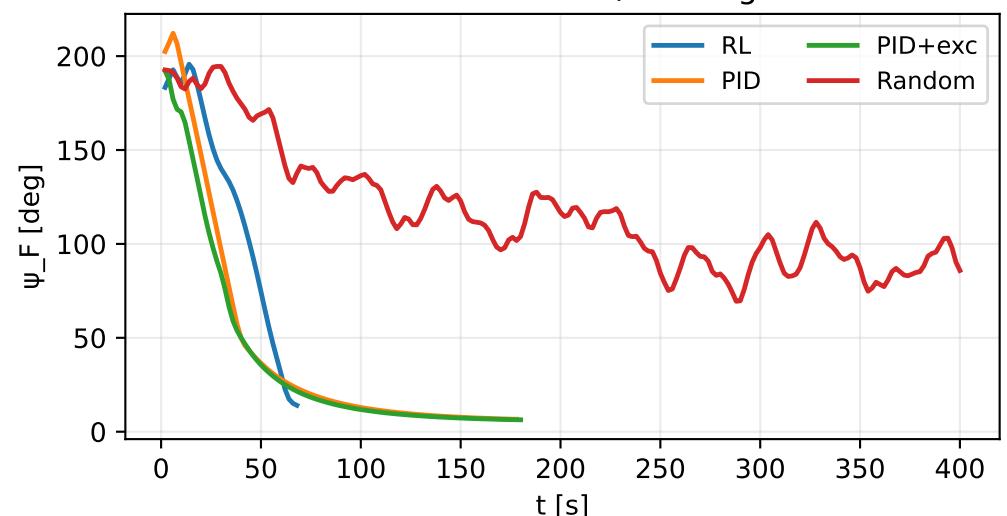
Information and excitation



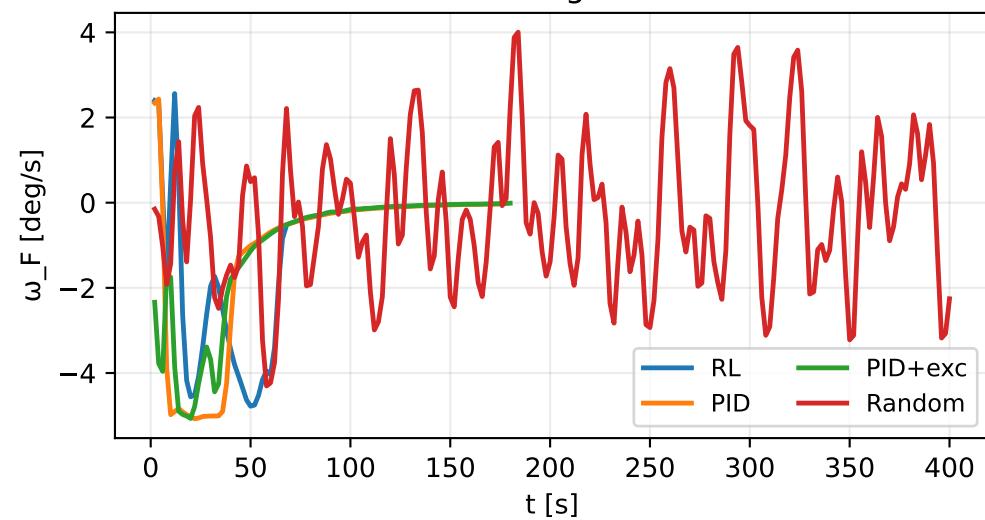
Follower speed



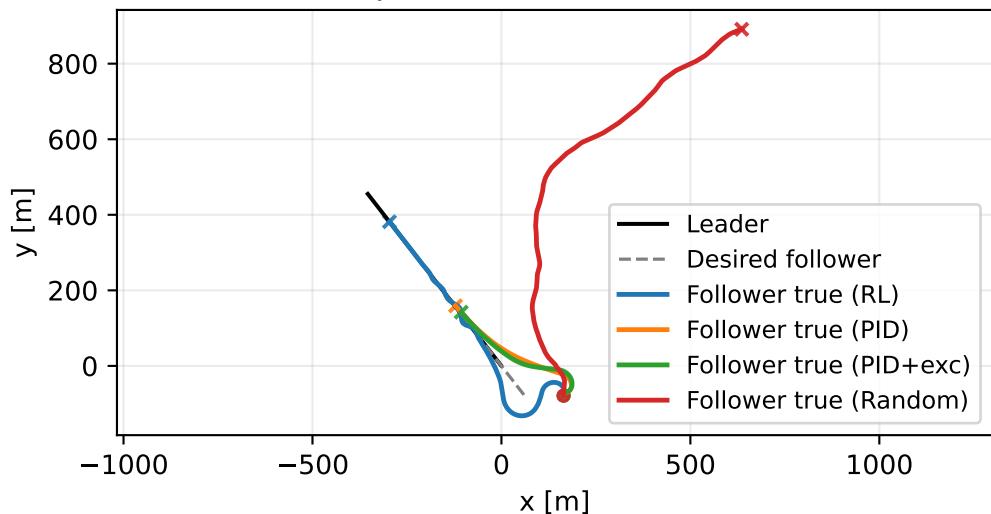
Follower course/heading



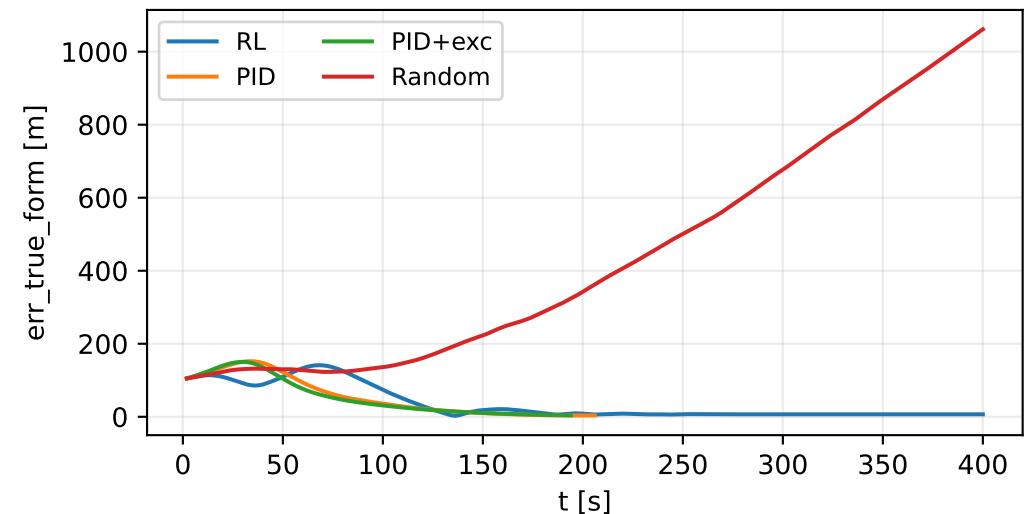
Follower angular rate



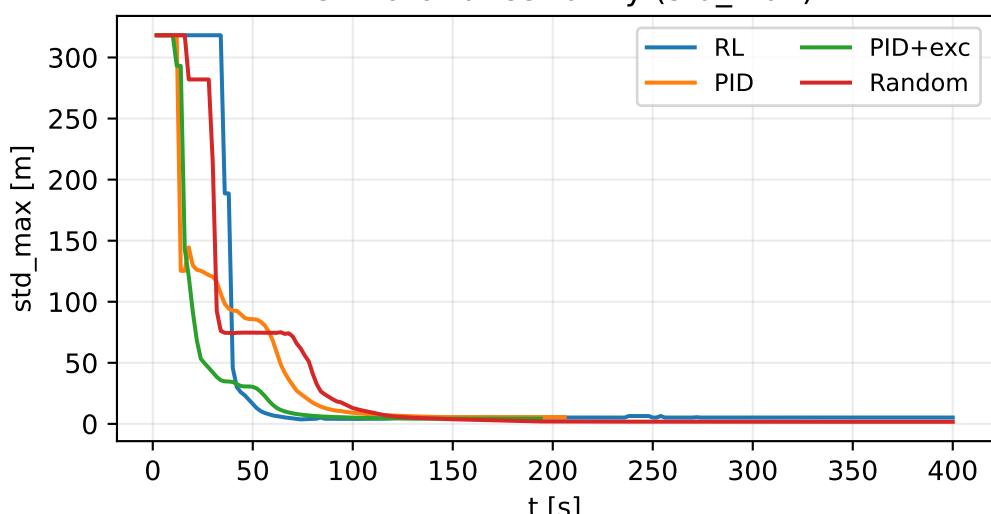
Trajectories (matched seed)



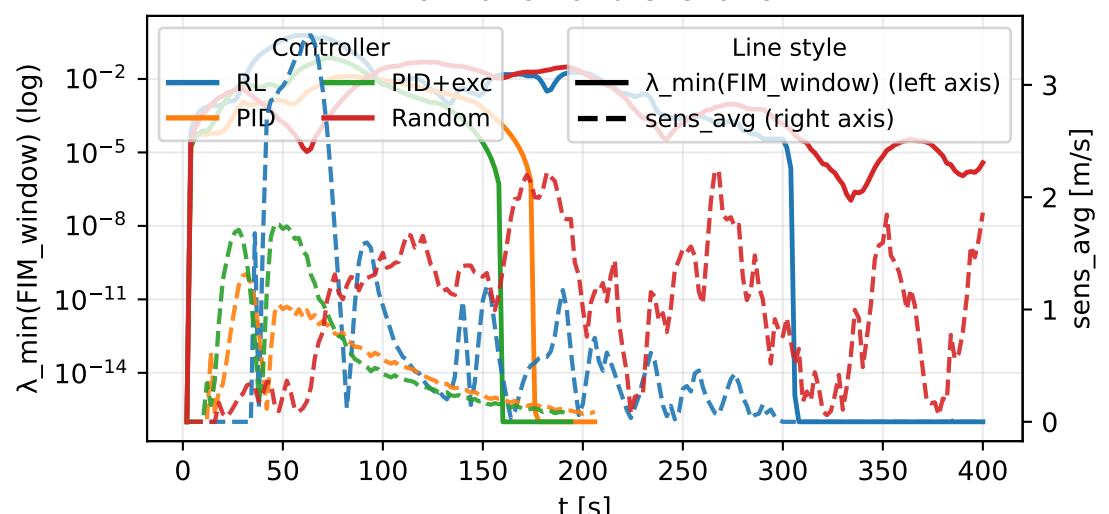
TRUE formation error



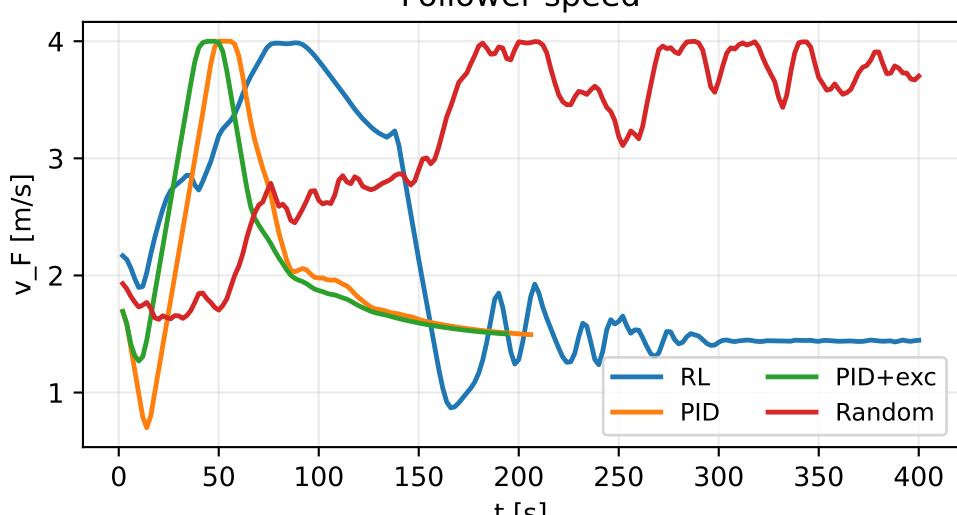
Estimator uncertainty (std_max)



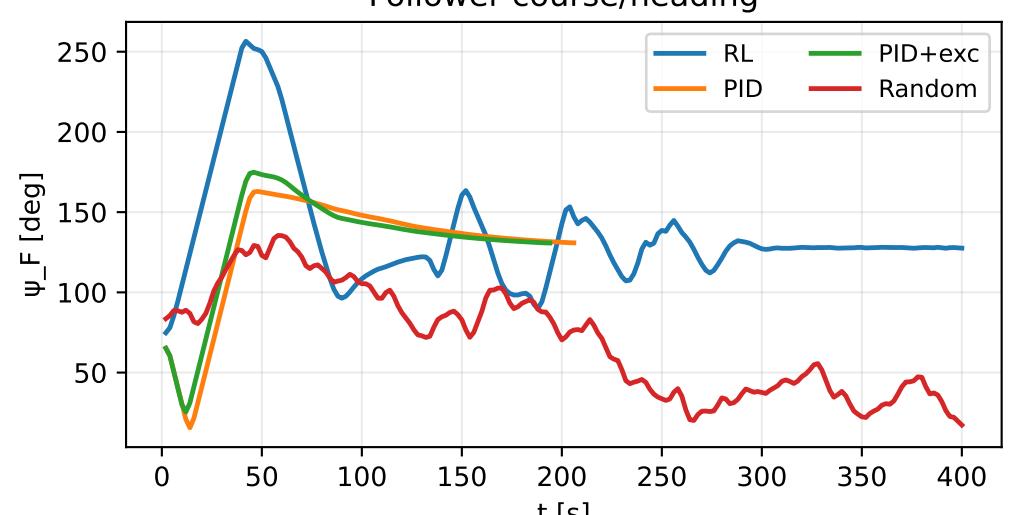
Information and excitation



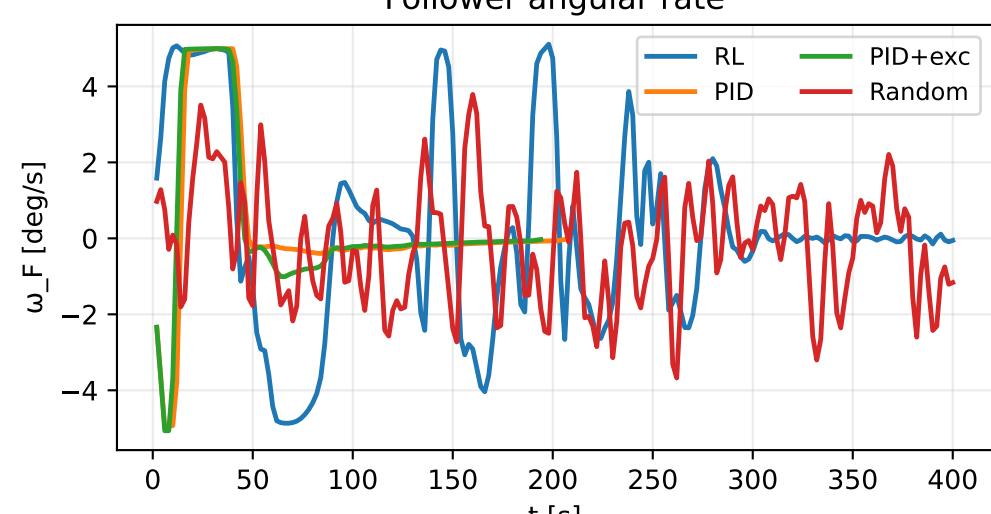
Follower speed



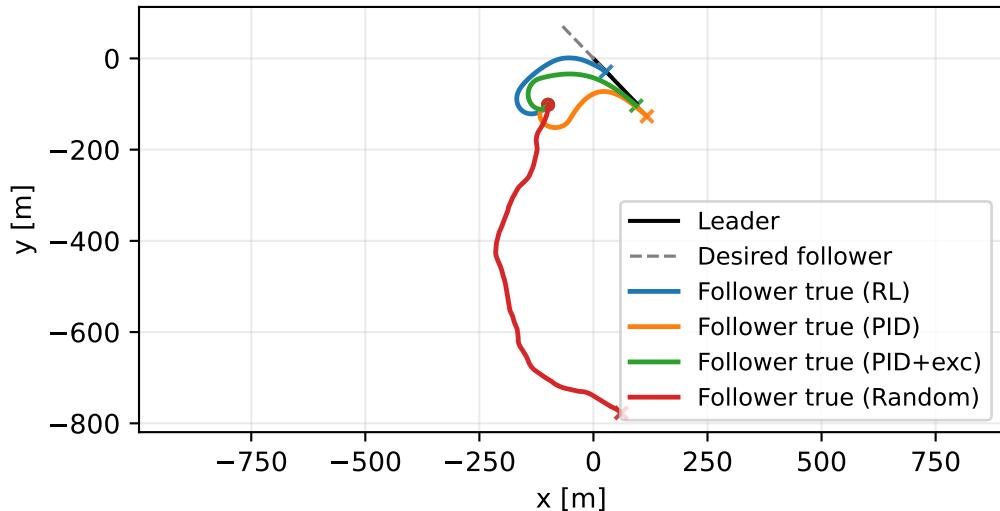
Follower course/heading



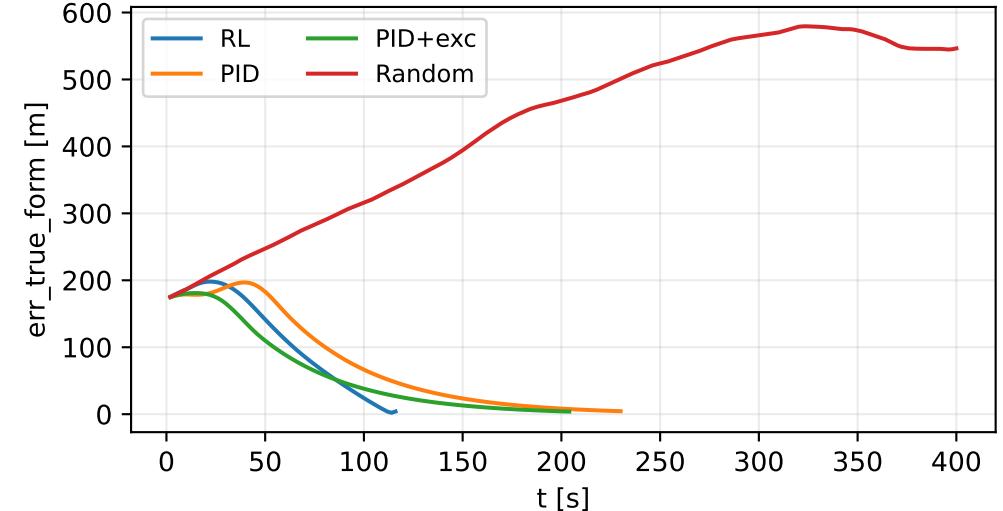
Follower angular rate



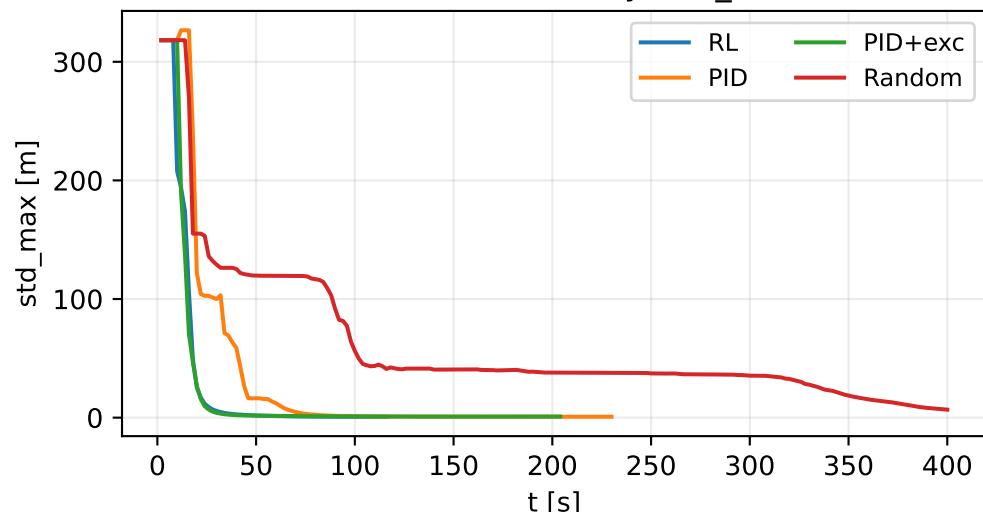
Trajectories (matched seed)



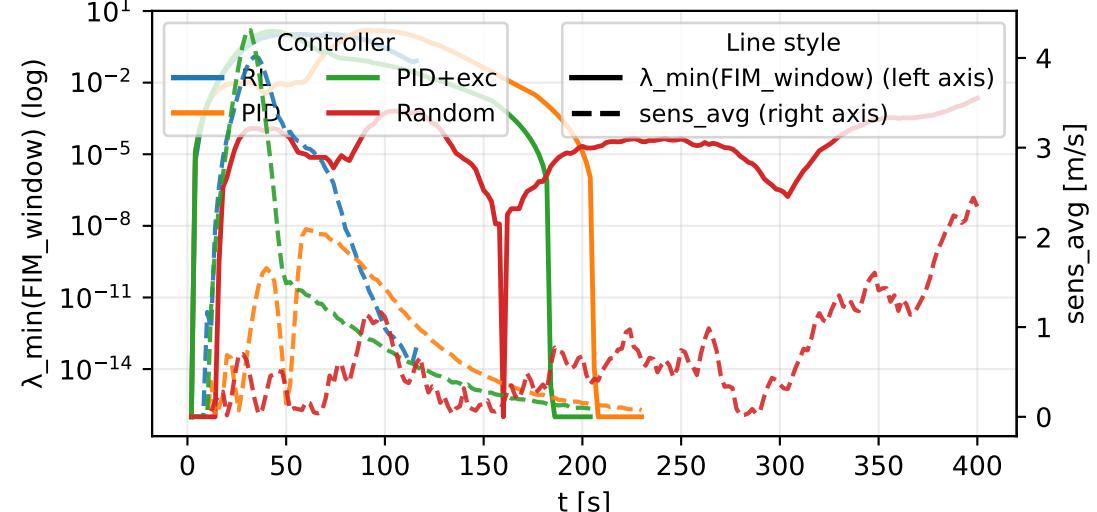
TRUE formation error



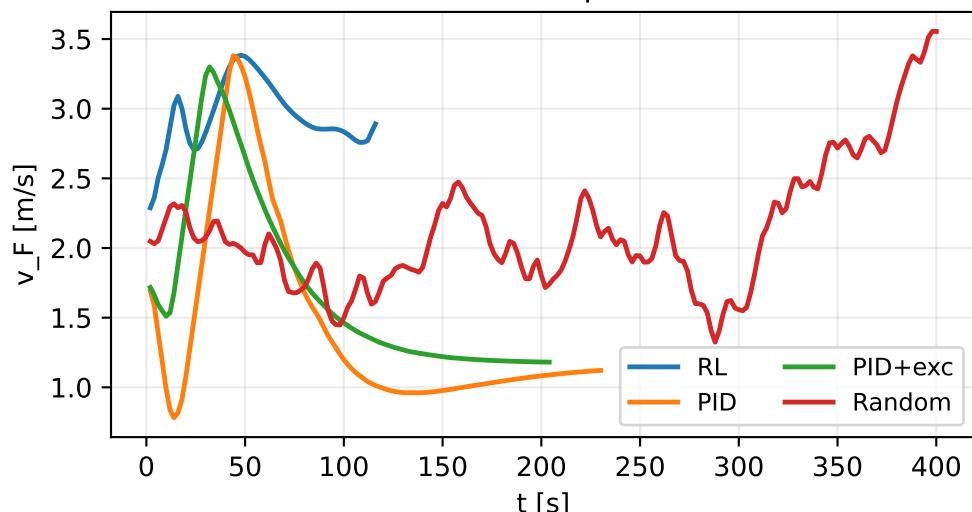
Estimator uncertainty (std_max)



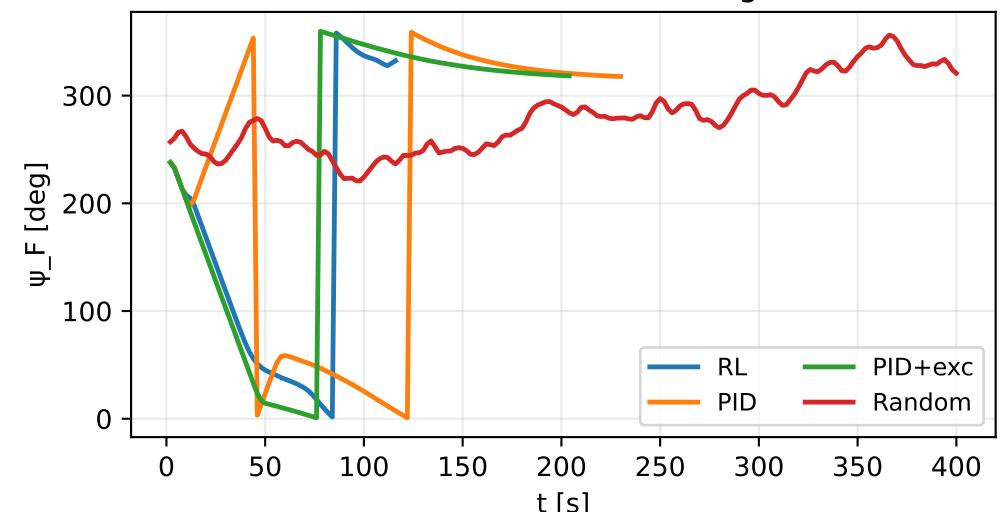
Information and excitation



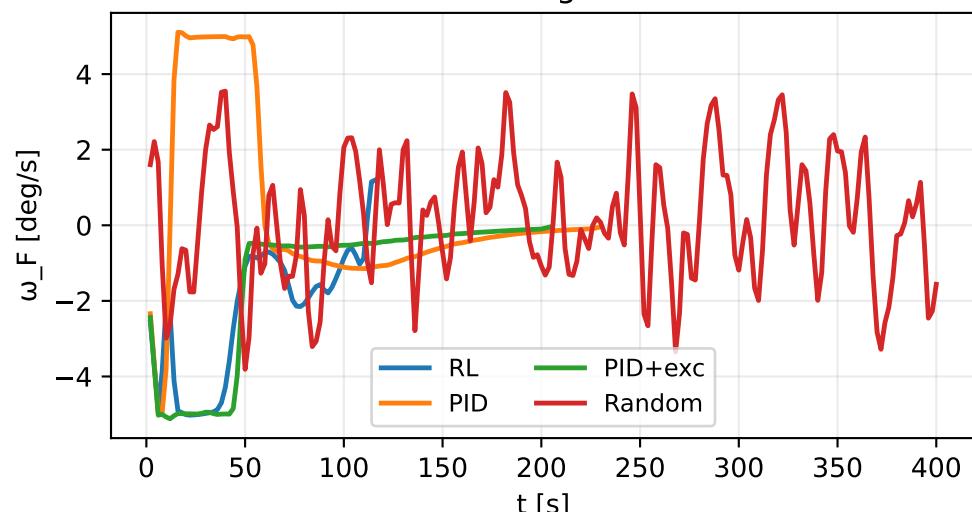
Follower speed



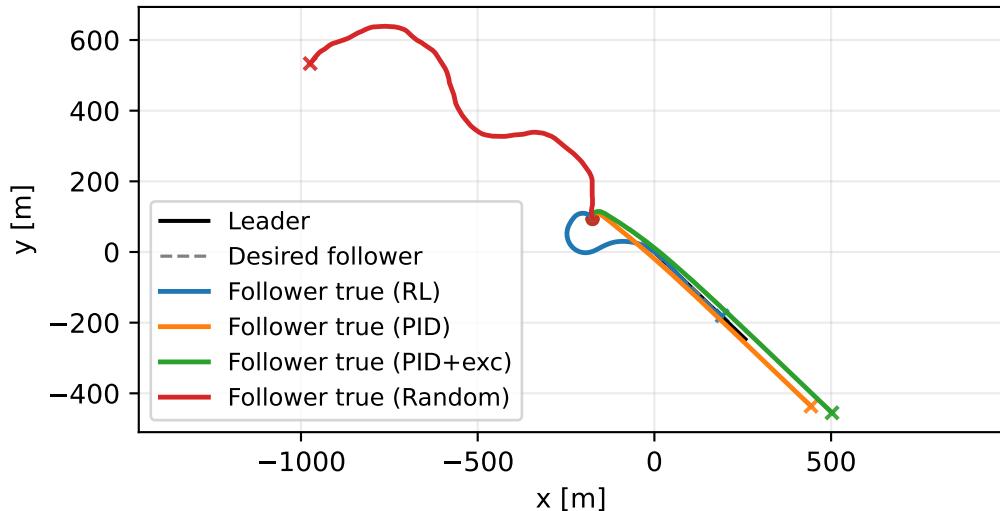
Follower course/heading



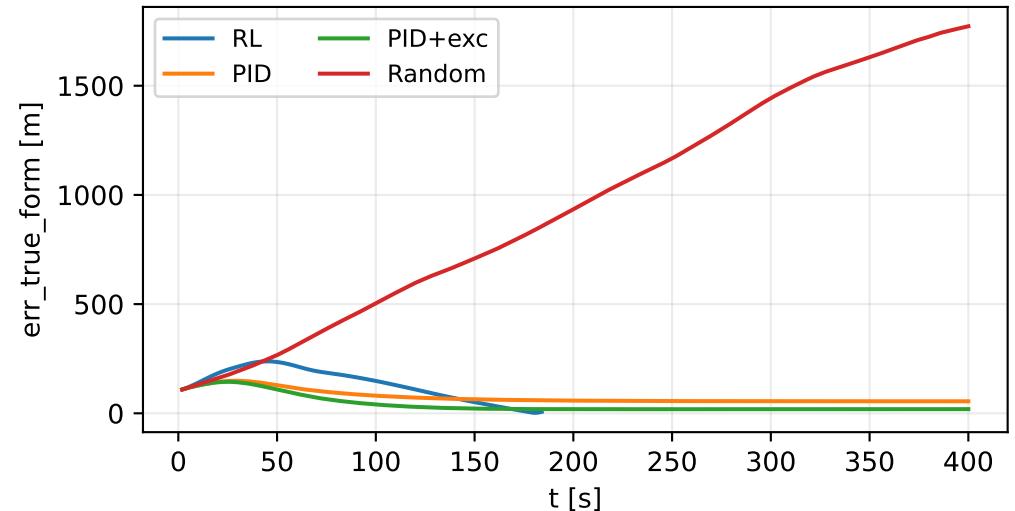
Follower angular rate



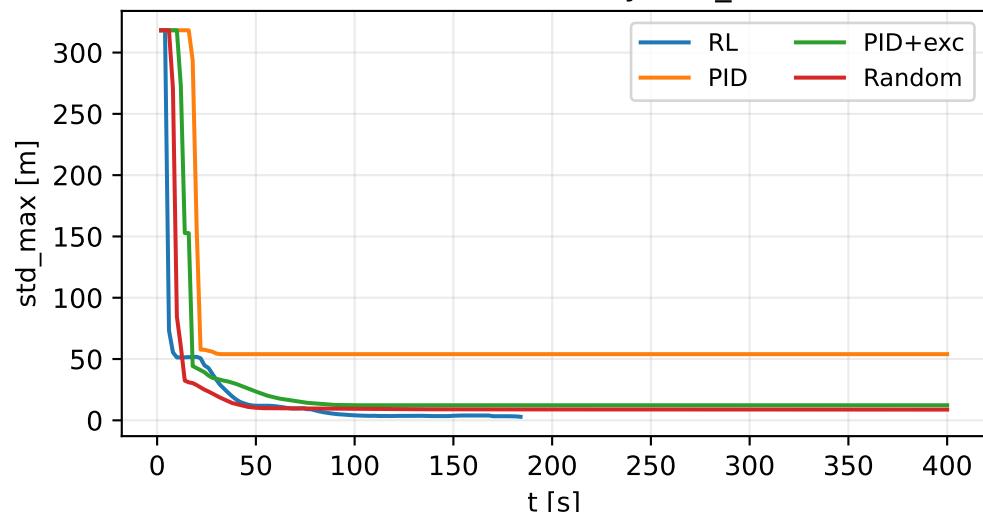
Trajectories (matched seed)



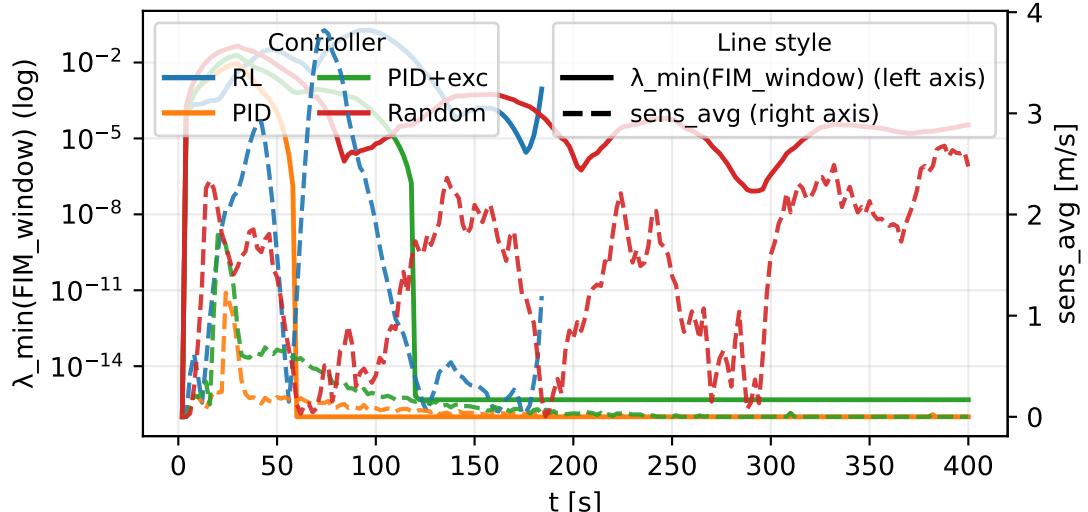
TRUE formation error



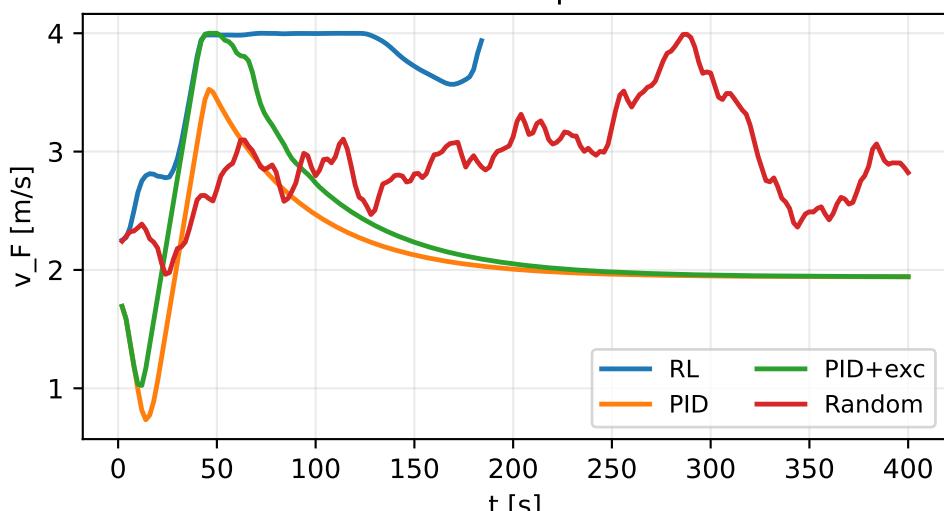
Estimator uncertainty (std_max)



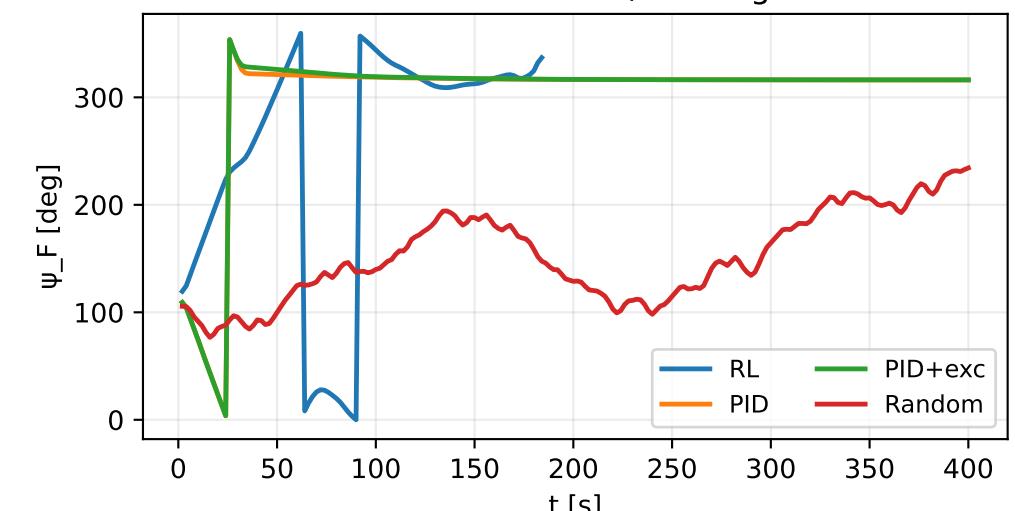
Information and excitation



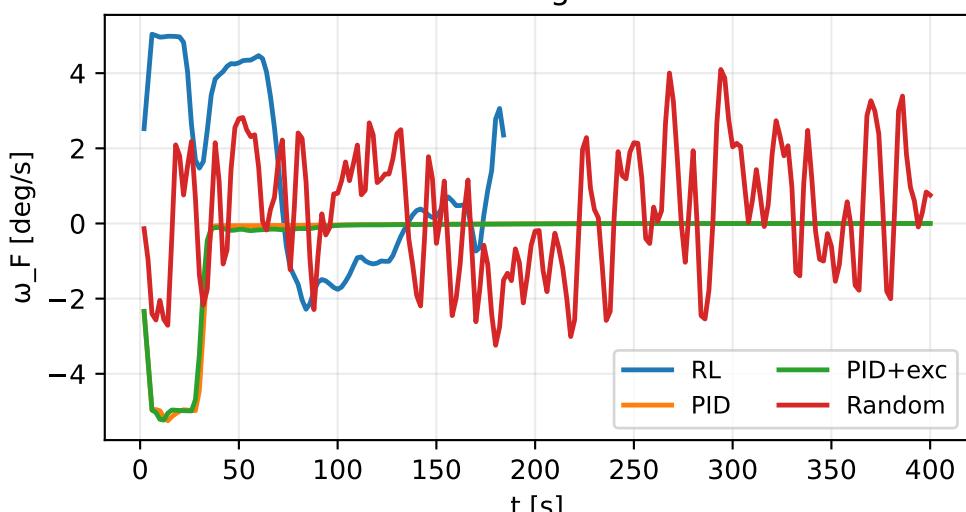
Follower speed



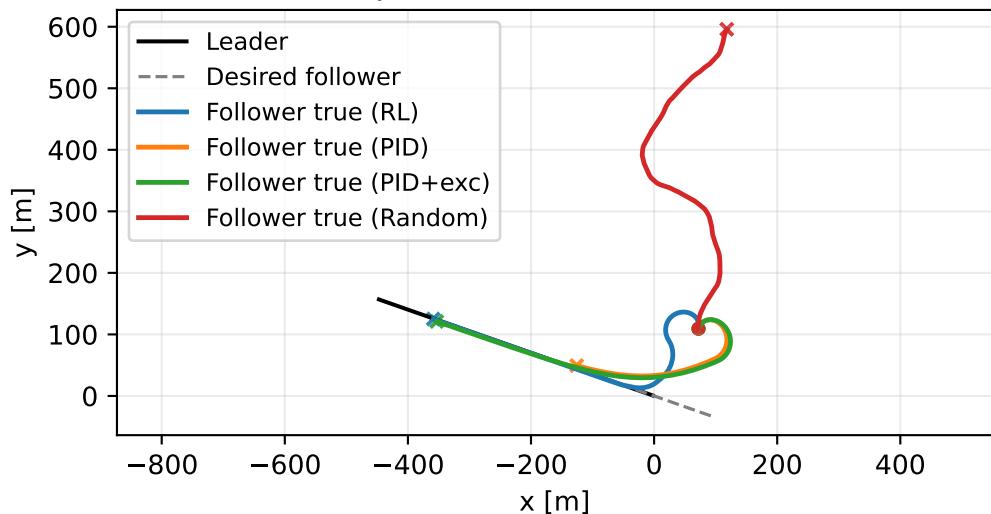
Follower course/heading



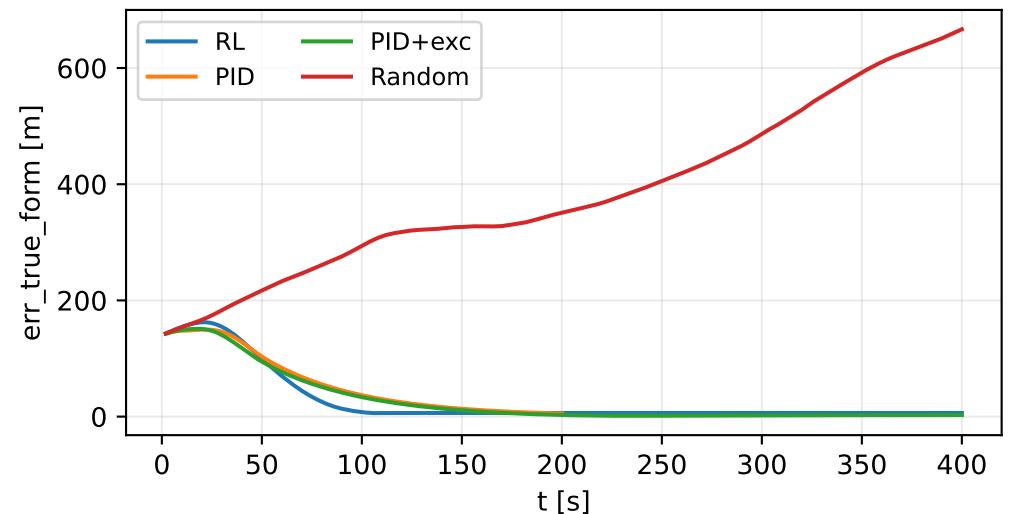
Follower angular rate



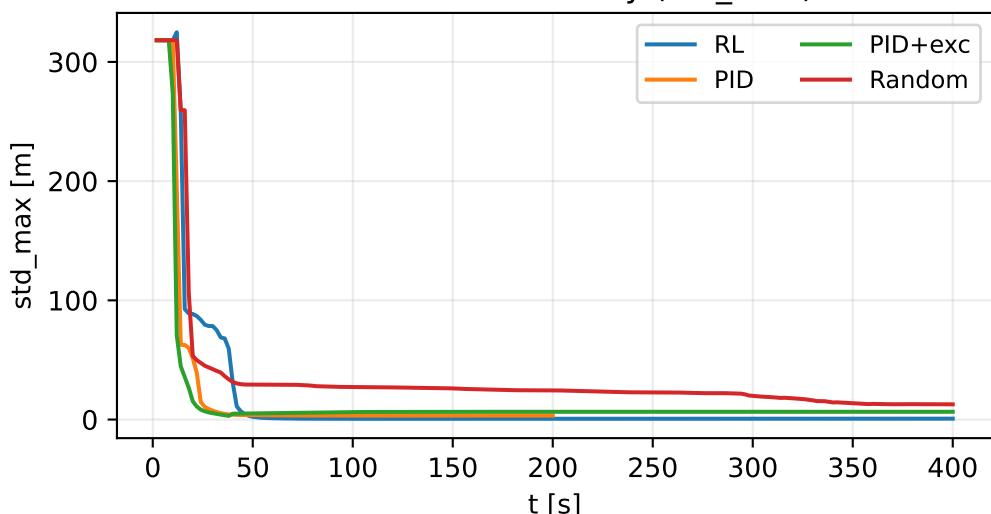
Trajectories (matched seed)



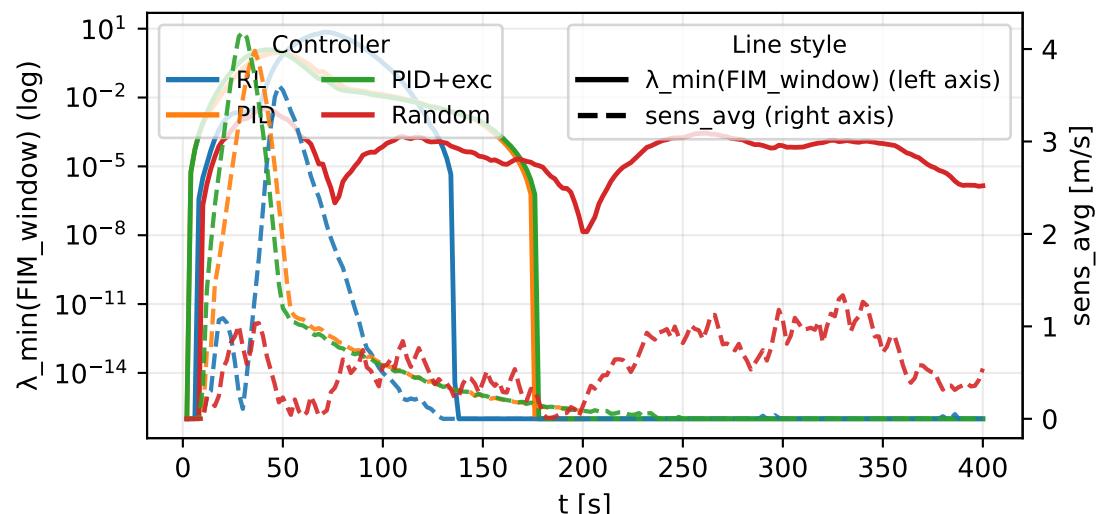
TRUE formation error



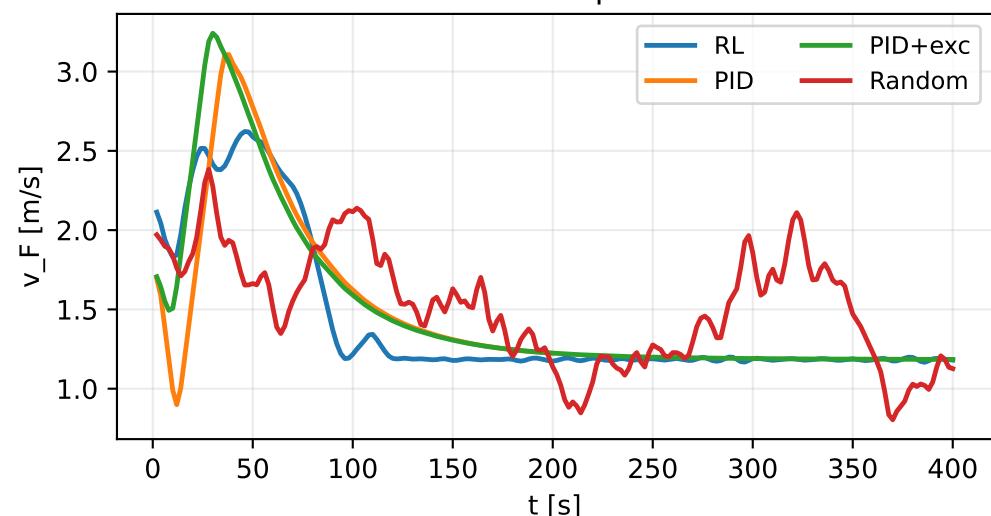
Estimator uncertainty (std_max)



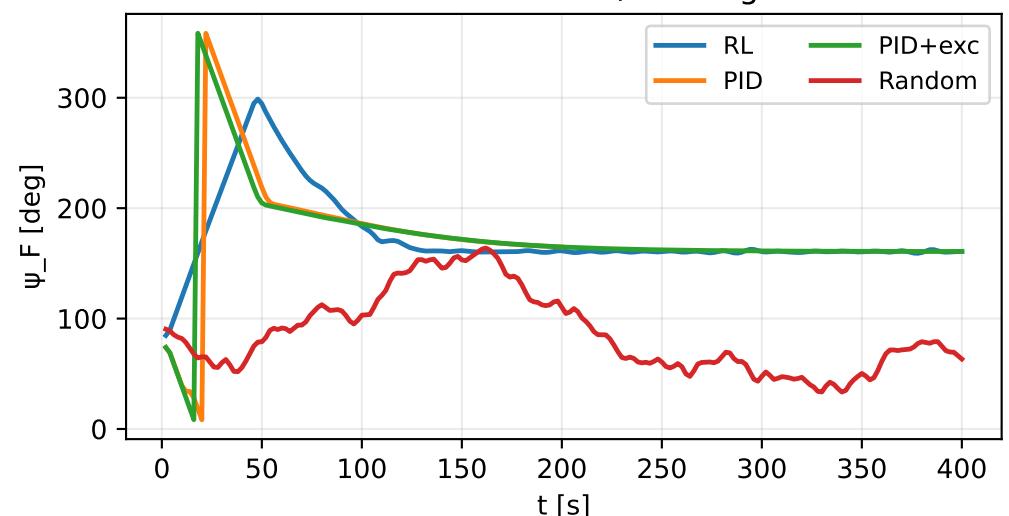
Information and excitation



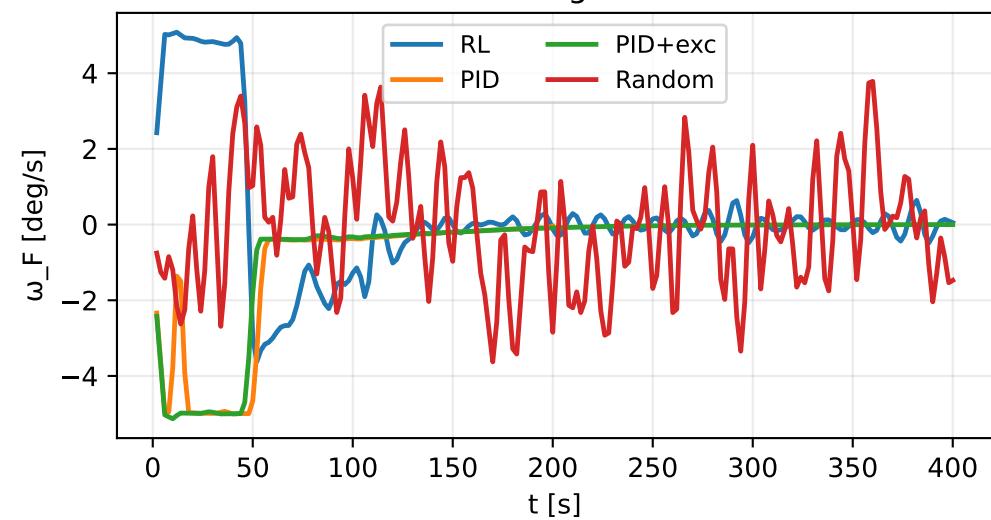
Follower speed



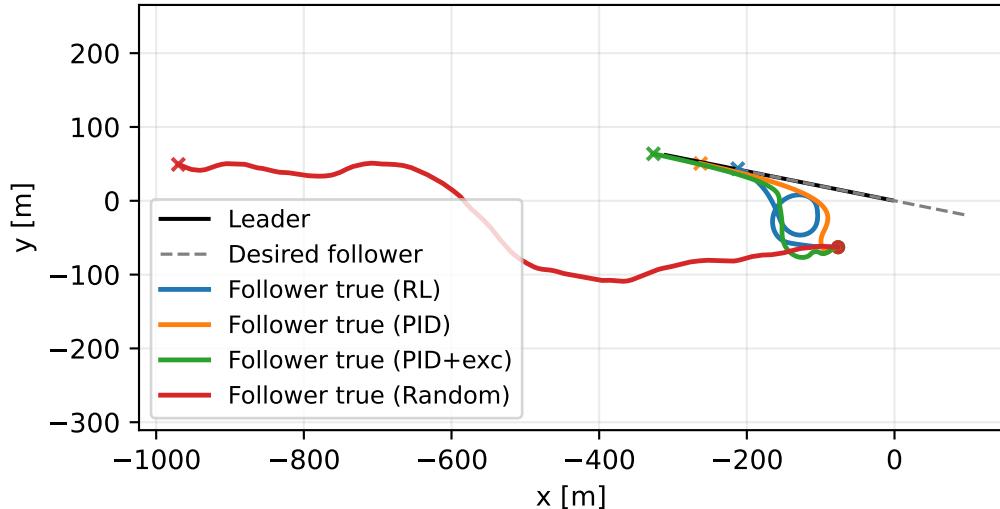
Follower course/heading



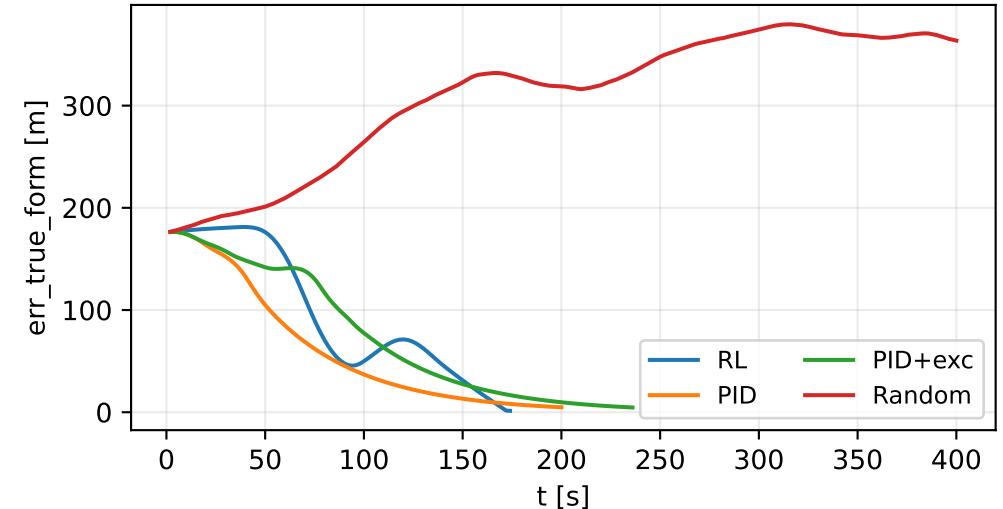
Follower angular rate



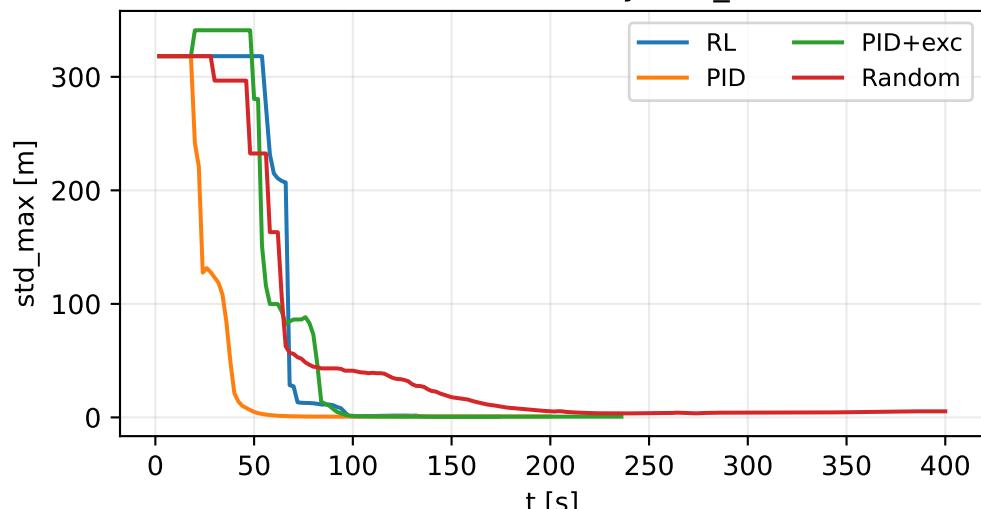
Trajectories (matched seed)



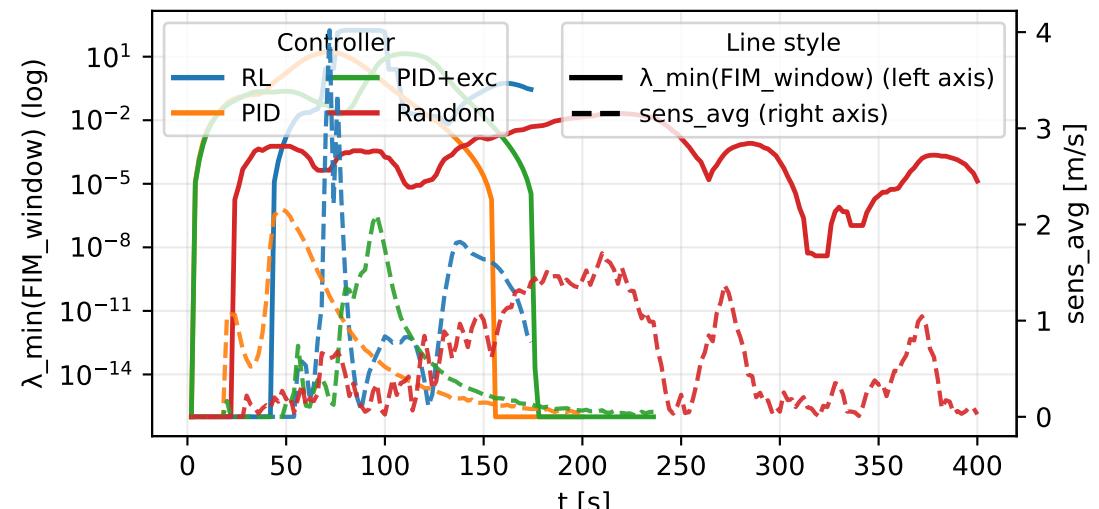
TRUE formation error



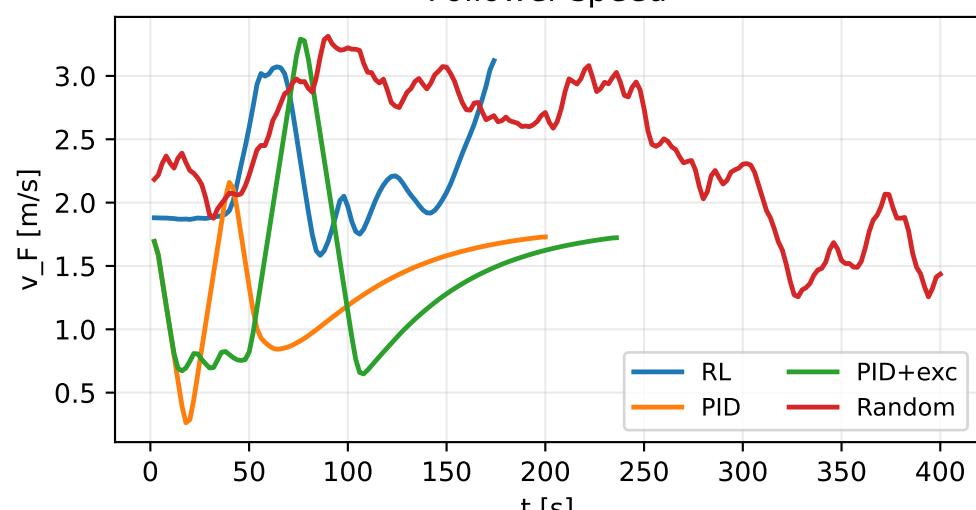
Estimator uncertainty (std_max)



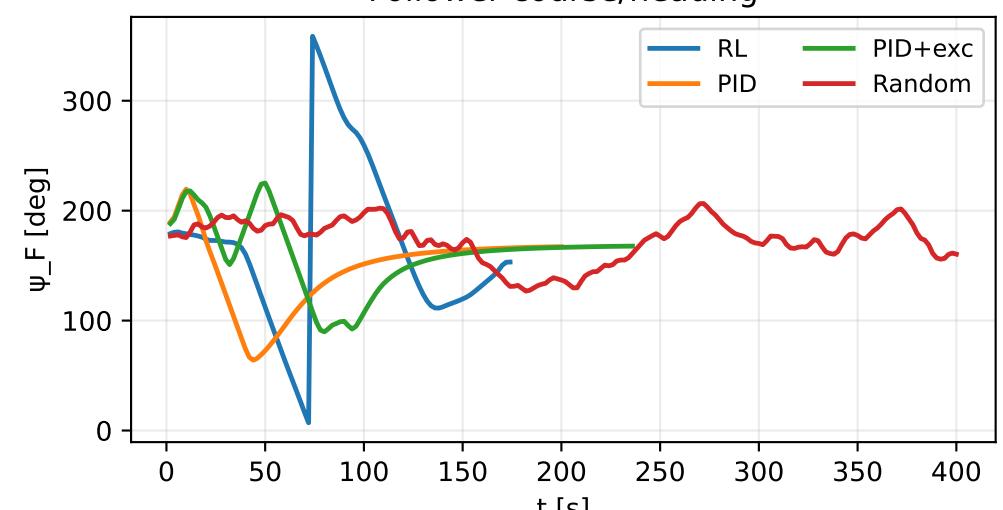
Information and excitation



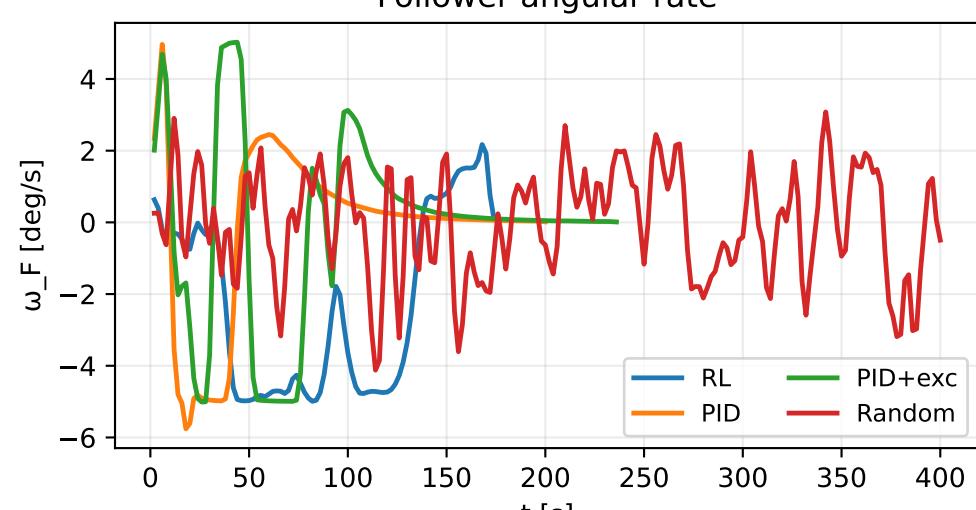
Follower speed



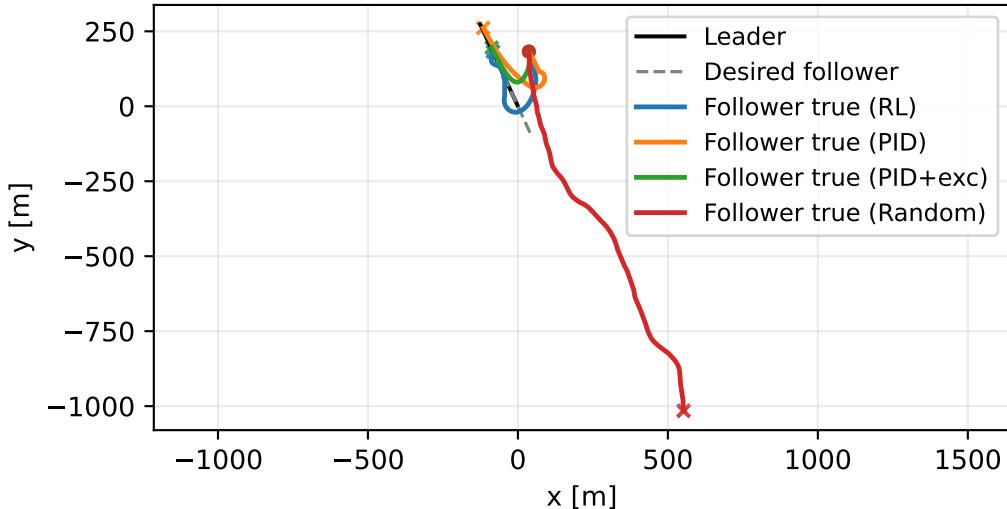
Follower course/heading



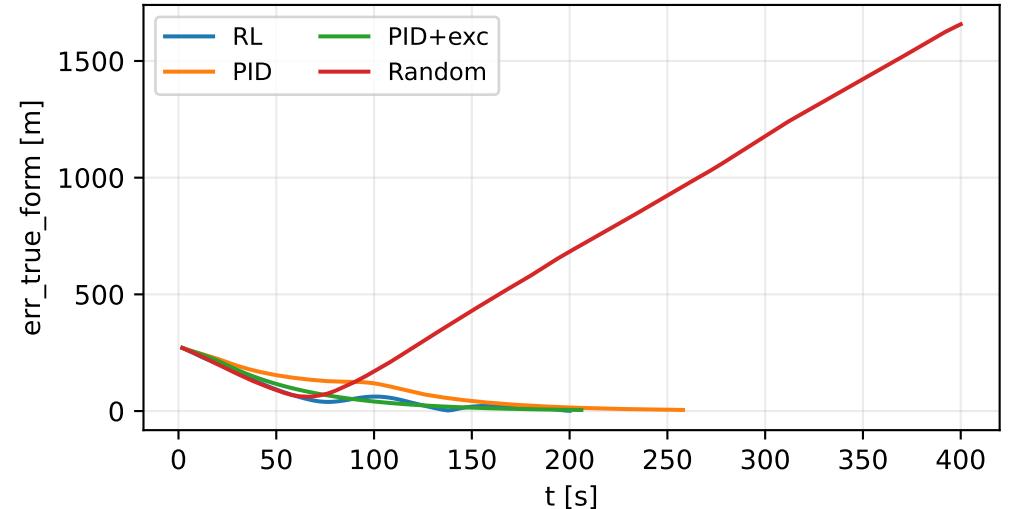
Follower angular rate



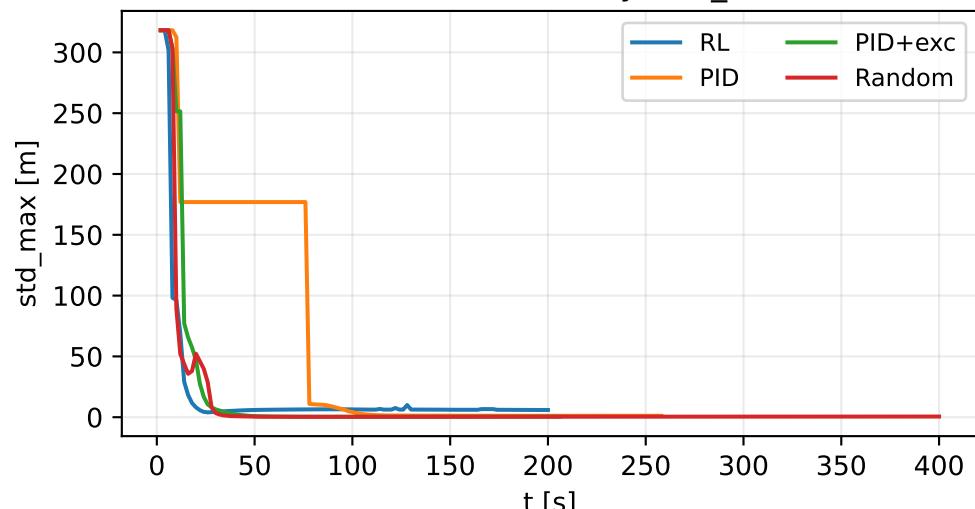
Trajectories (matched seed)



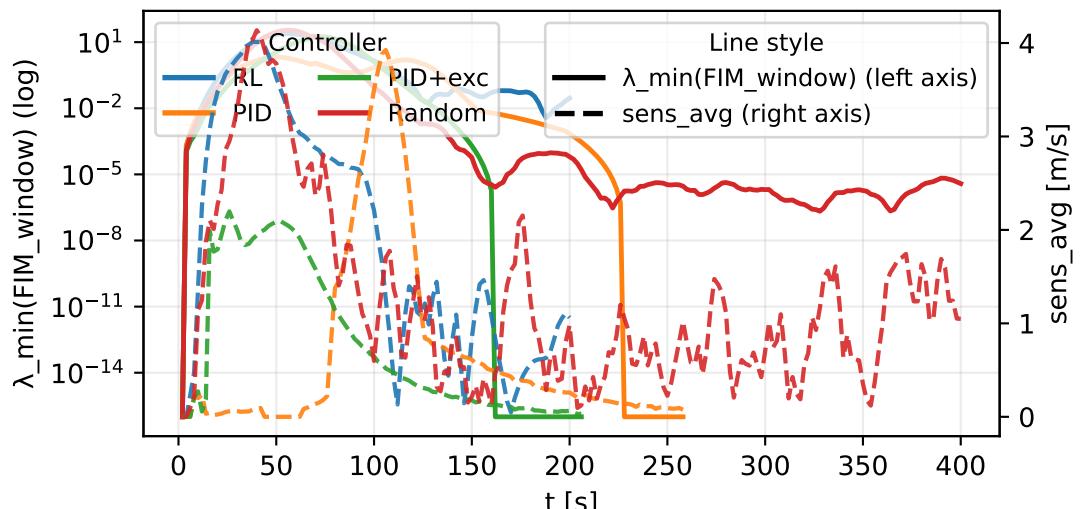
TRUE formation error



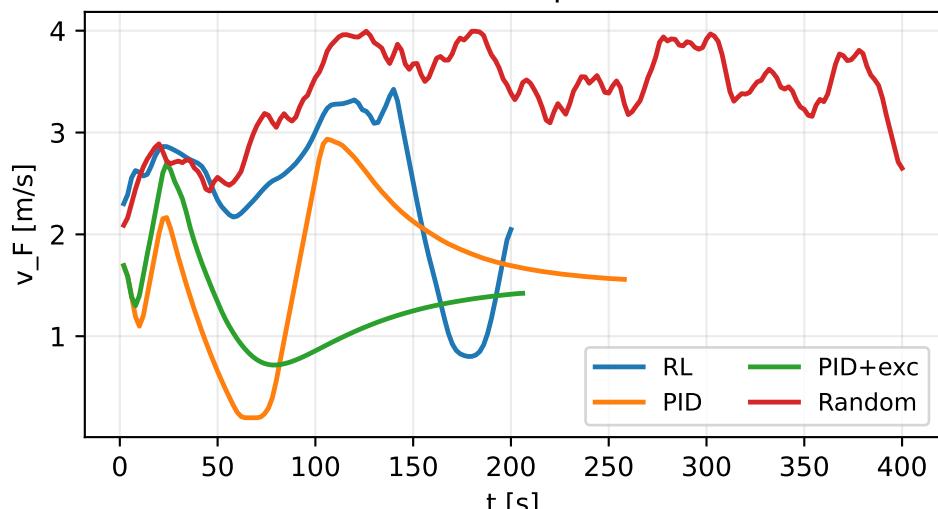
Estimator uncertainty (std_max)



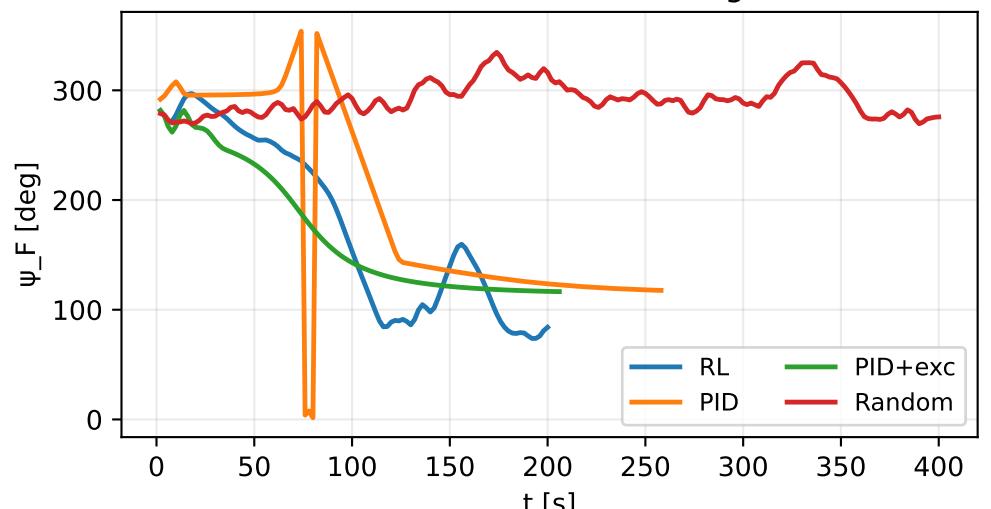
Information and excitation



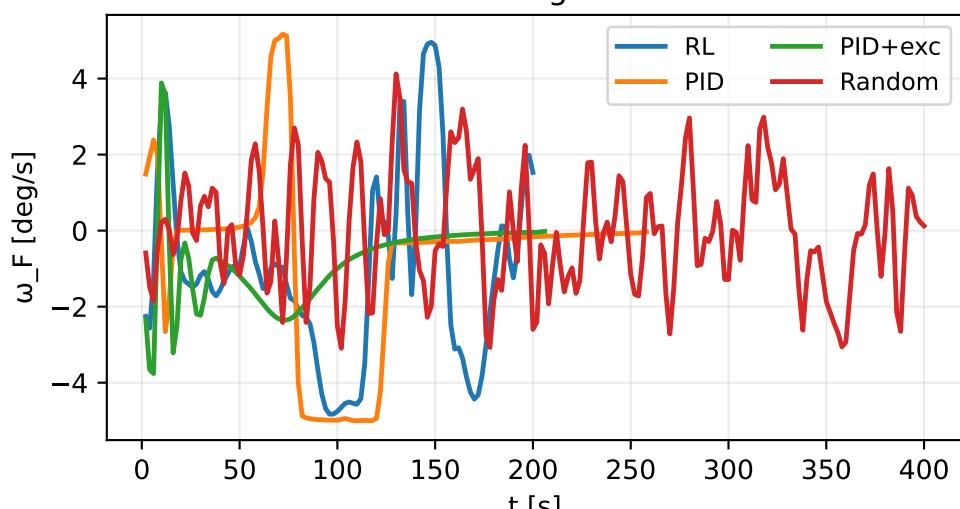
Follower speed



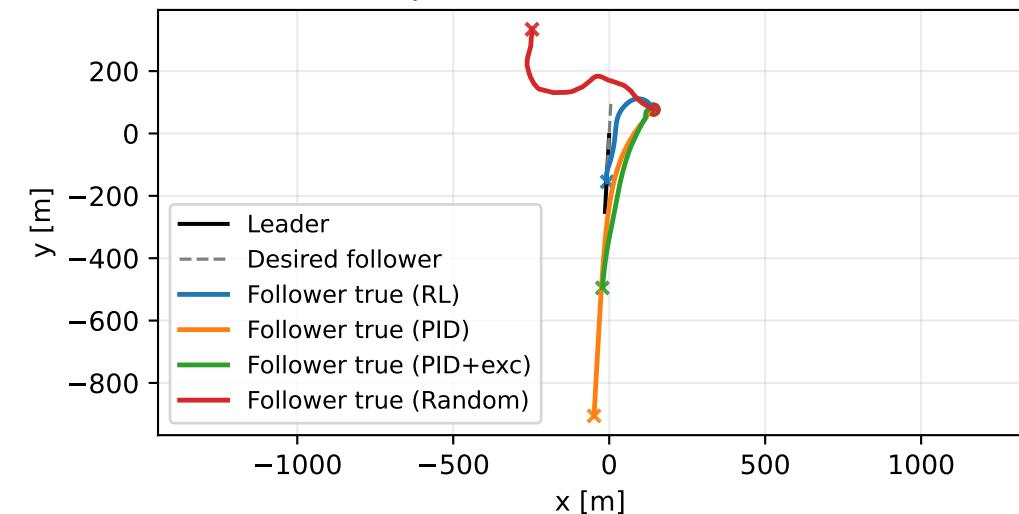
Follower course/heading



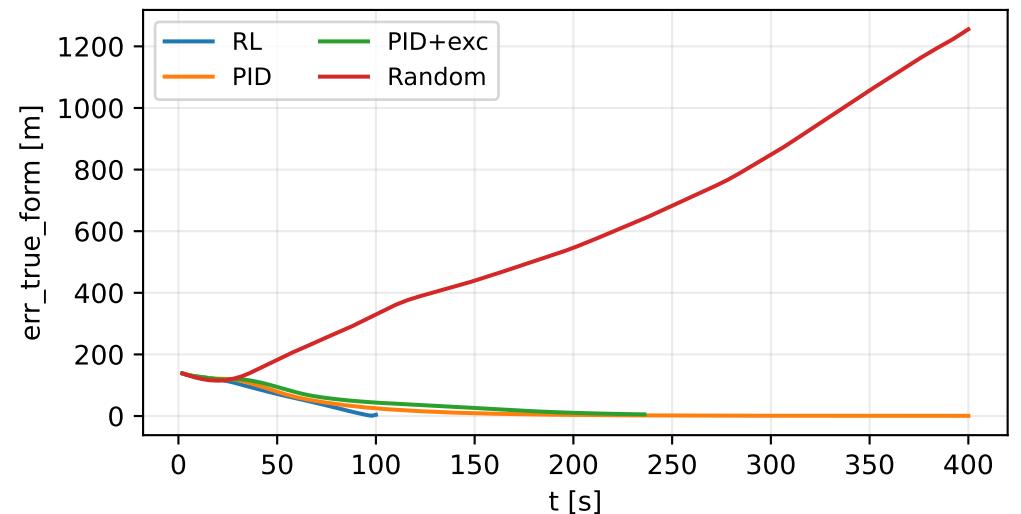
Follower angular rate



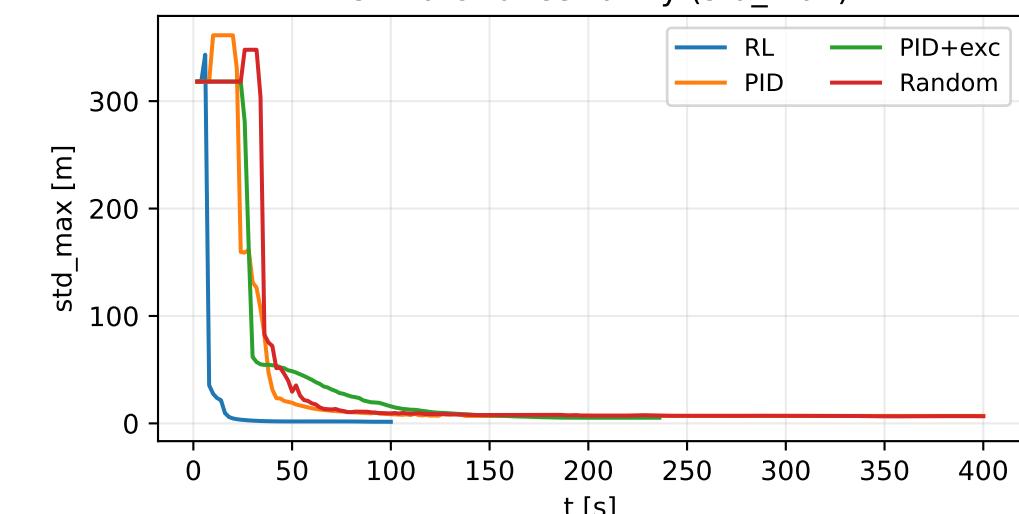
Trajectories (matched seed)



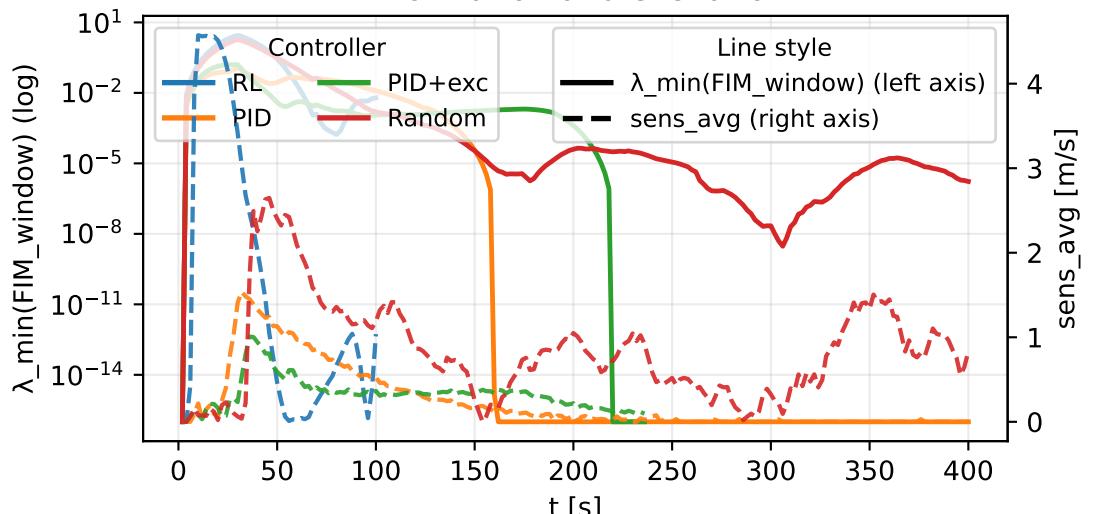
TRUE formation error



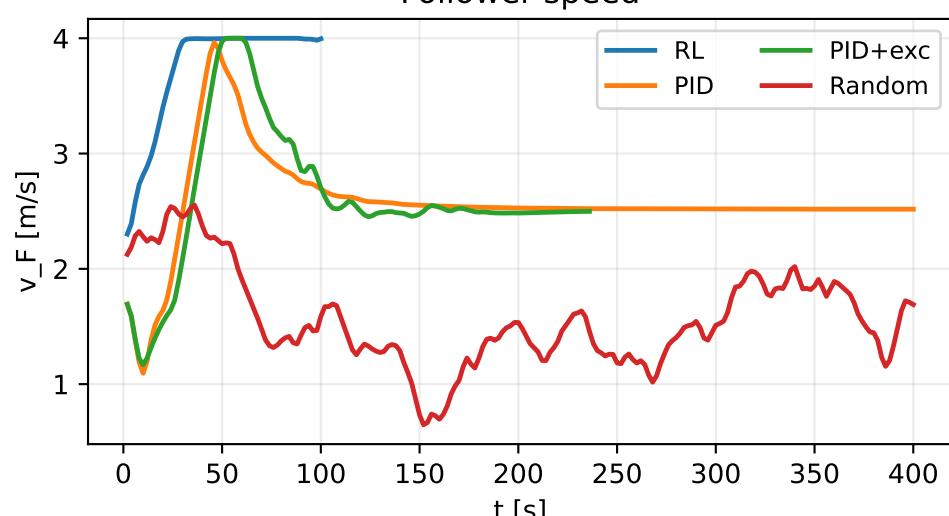
Estimator uncertainty (std_max)



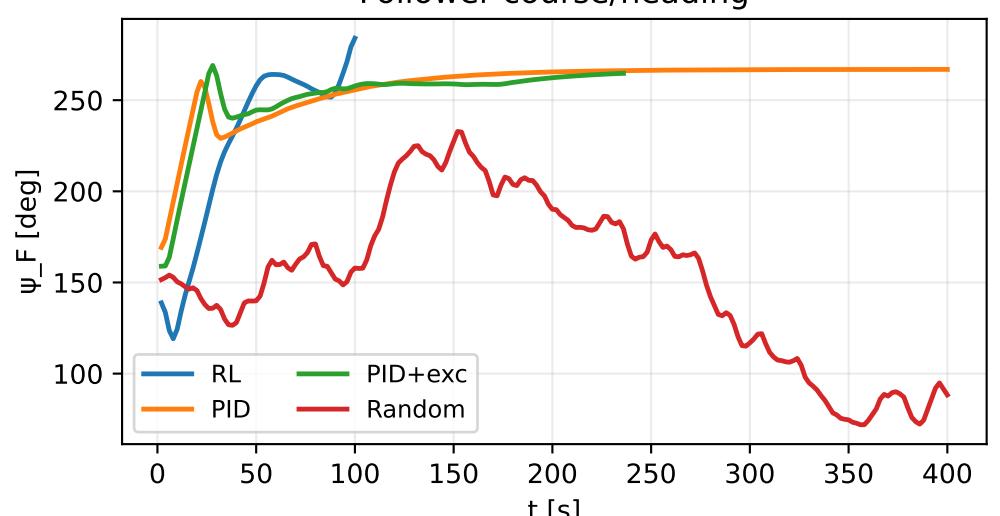
Information and excitation



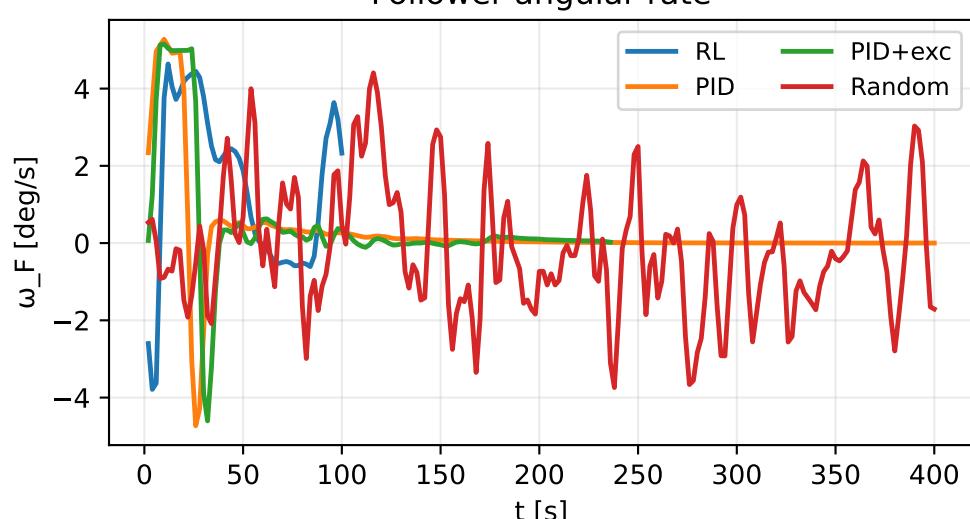
Follower speed



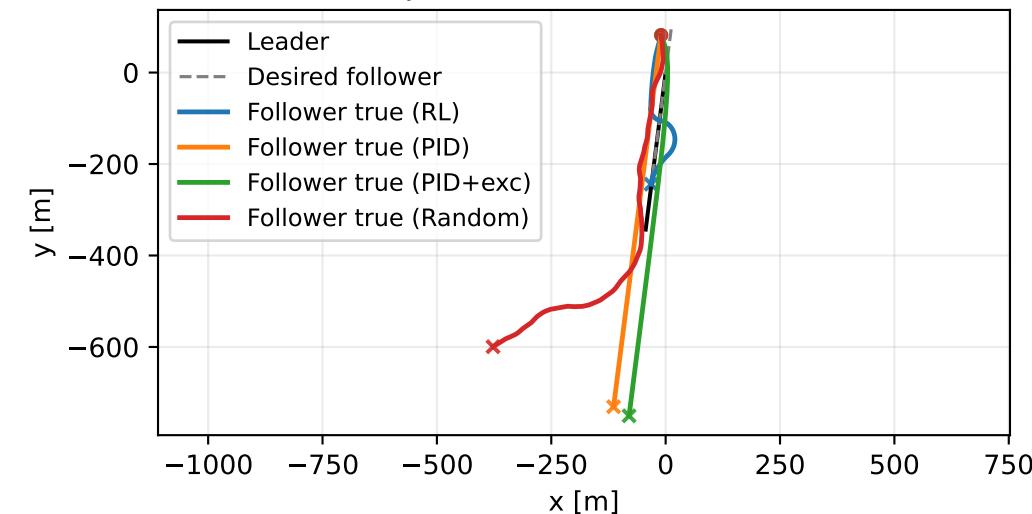
Follower course/heading



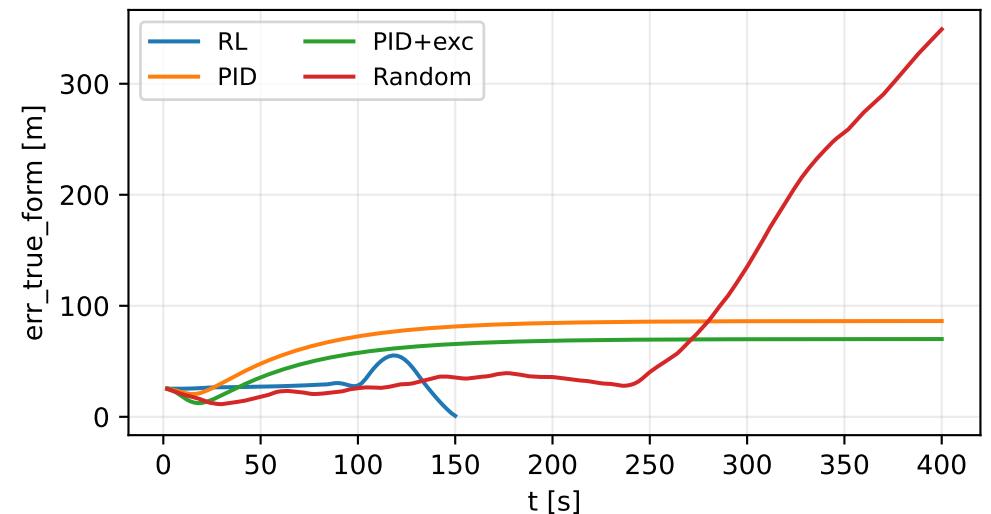
Follower angular rate



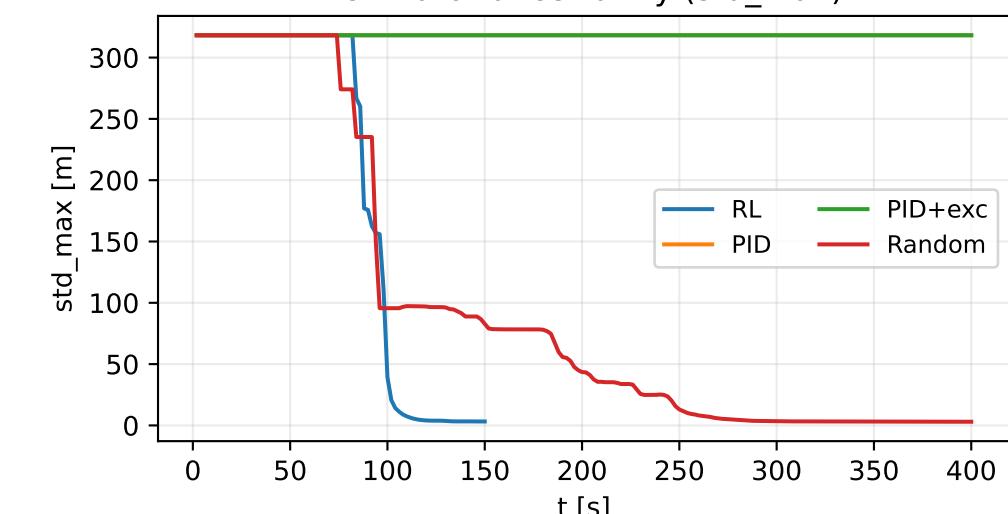
Trajectories (matched seed)



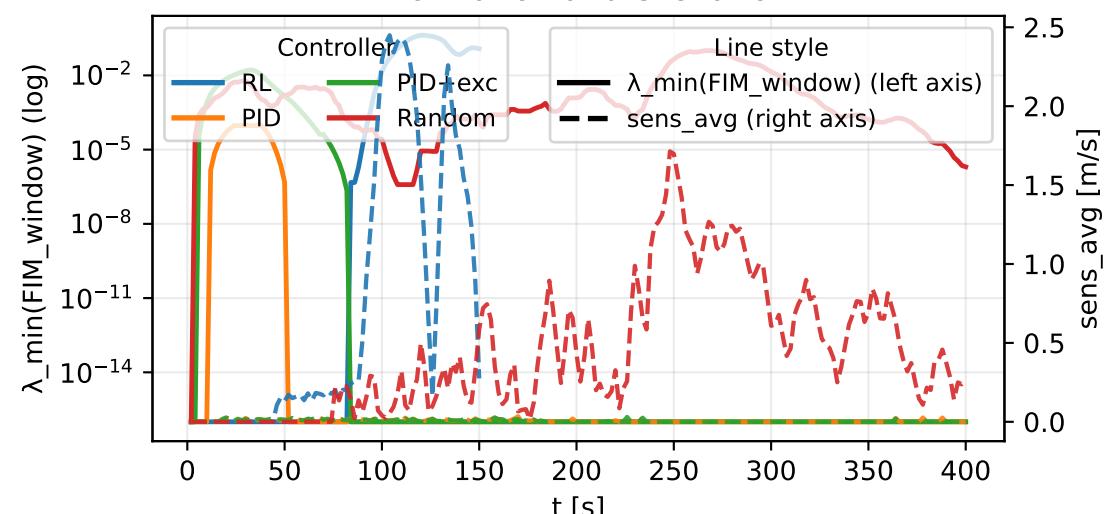
TRUE formation error



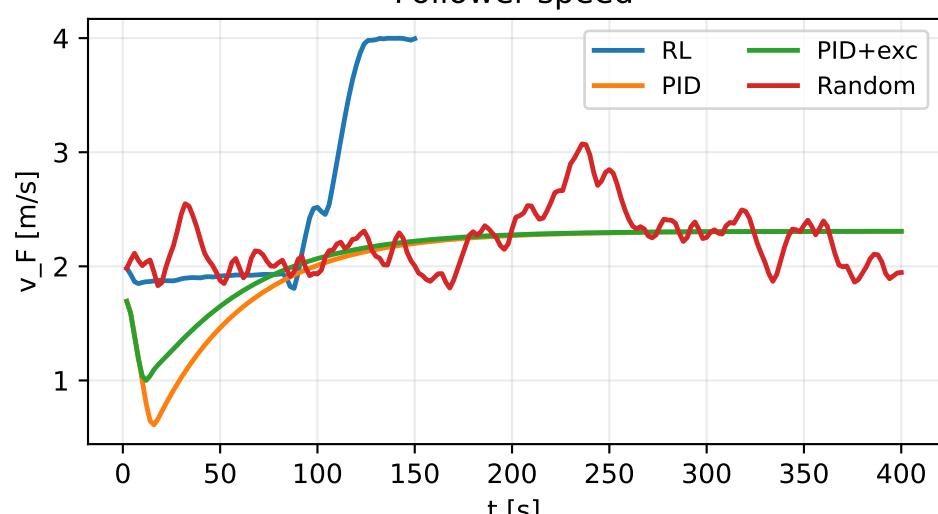
Estimator uncertainty (std_max)



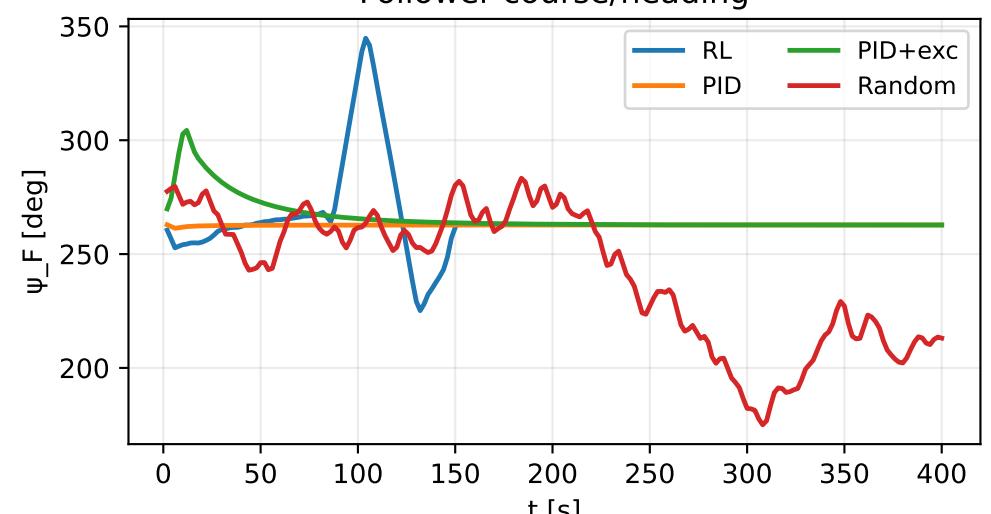
Information and excitation



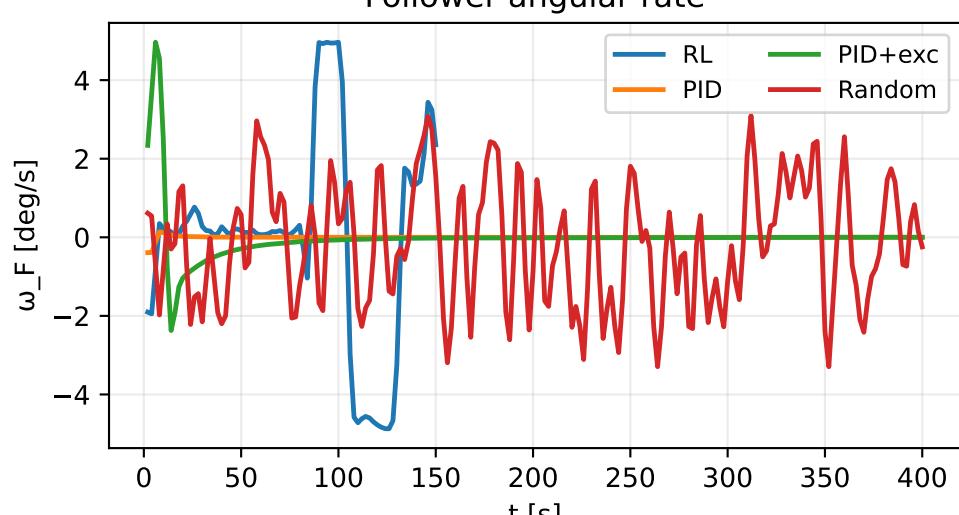
Follower speed



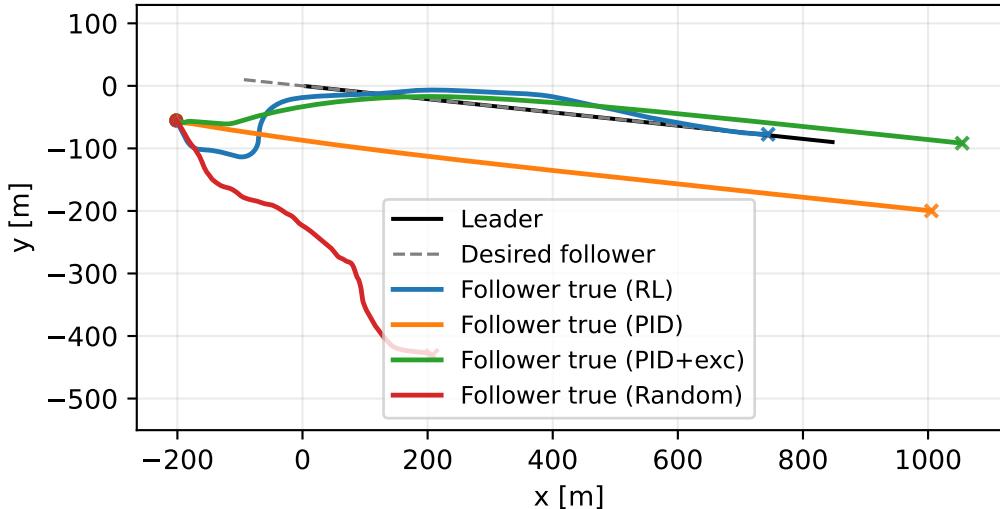
Follower course/heading



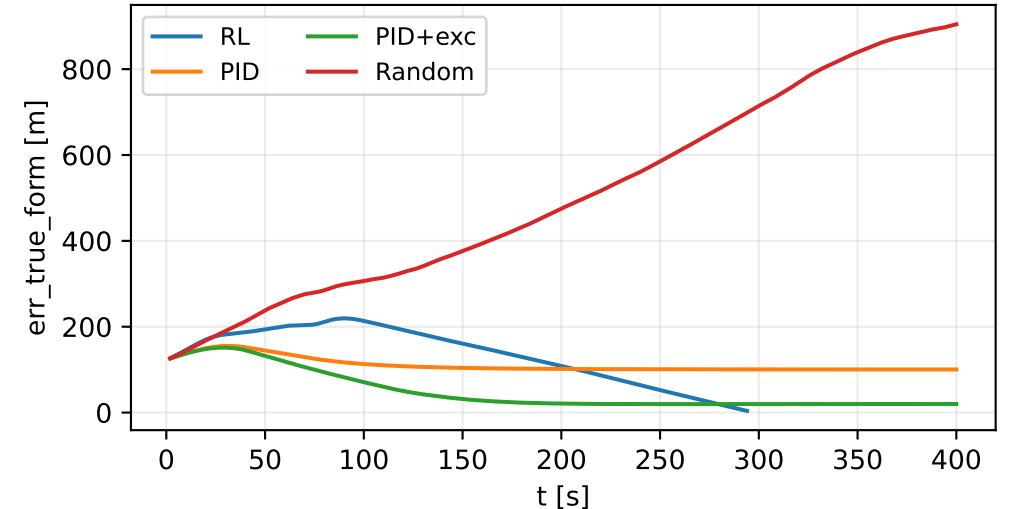
Follower angular rate



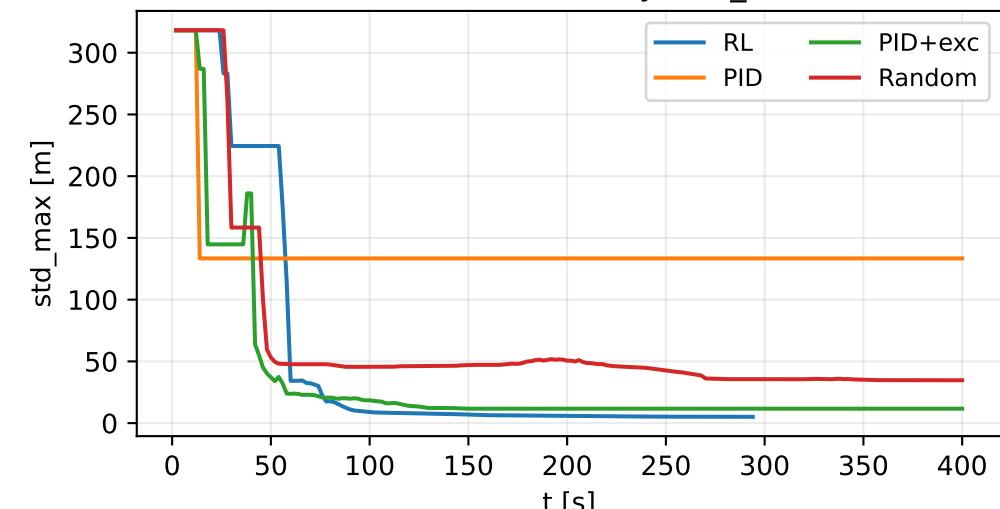
Trajectories (matched seed)



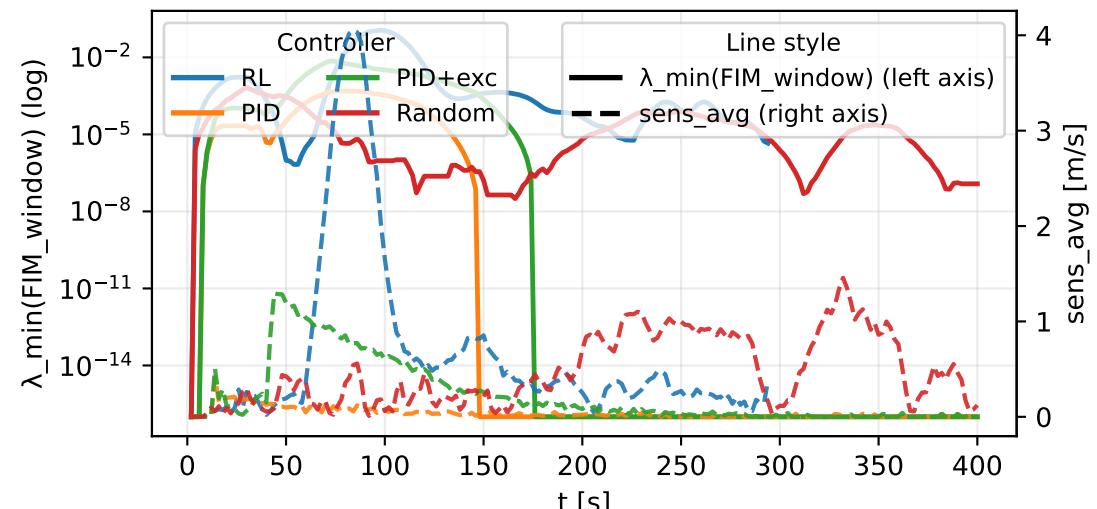
TRUE formation error



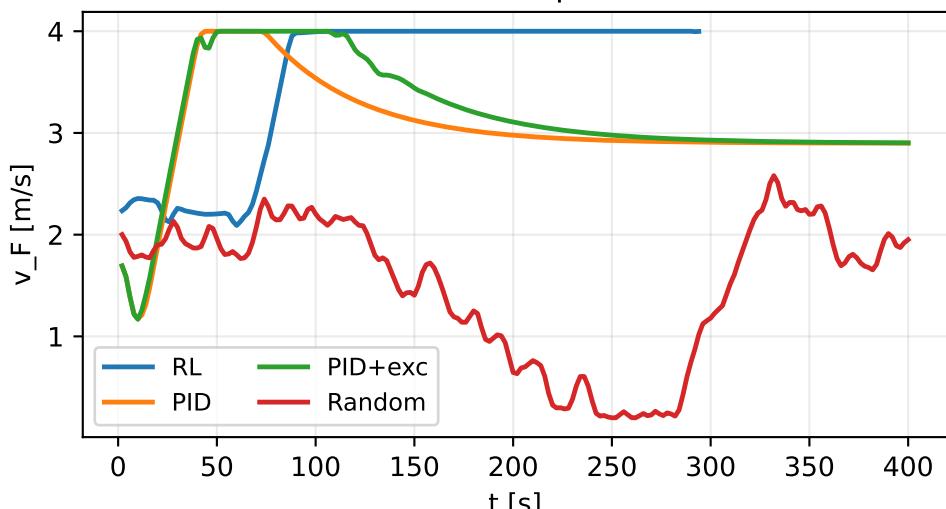
Estimator uncertainty (std_max)



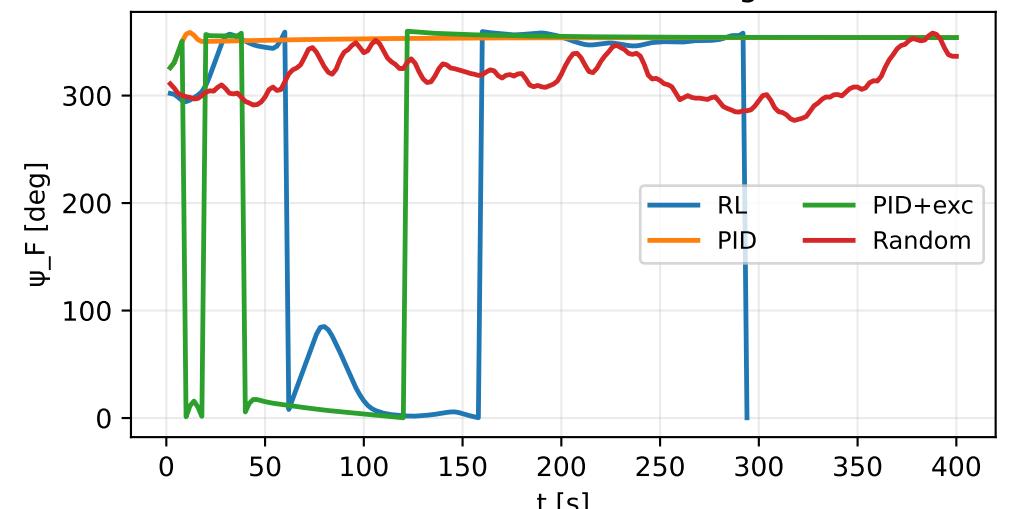
Information and excitation



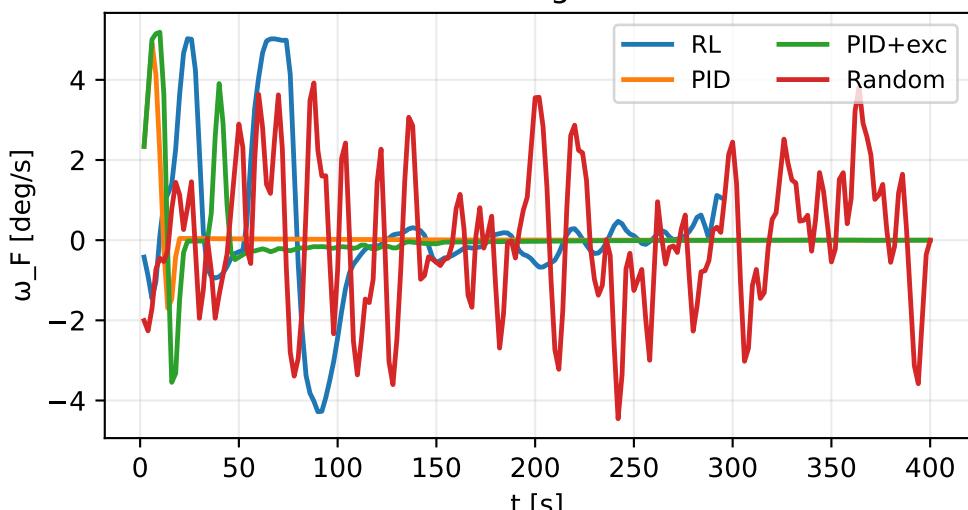
Follower speed



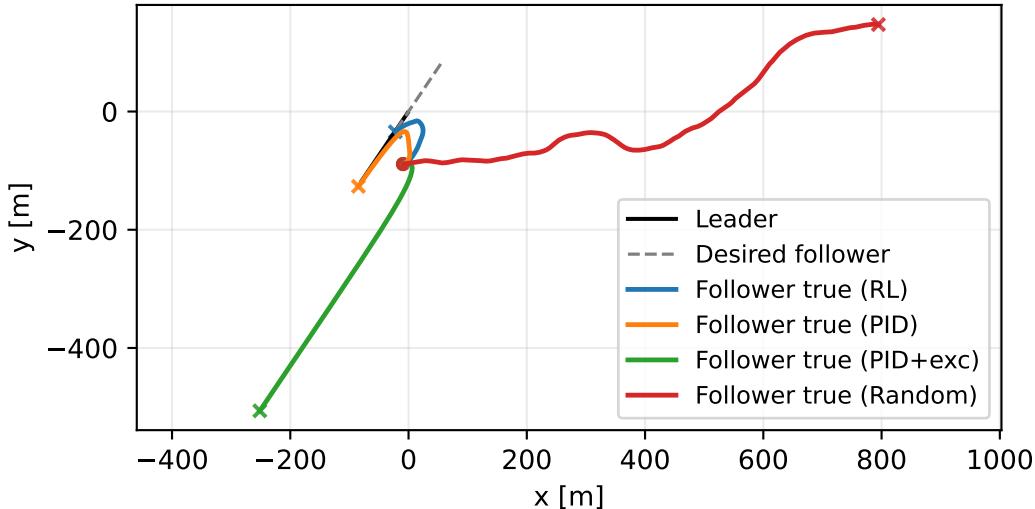
Follower course/heading



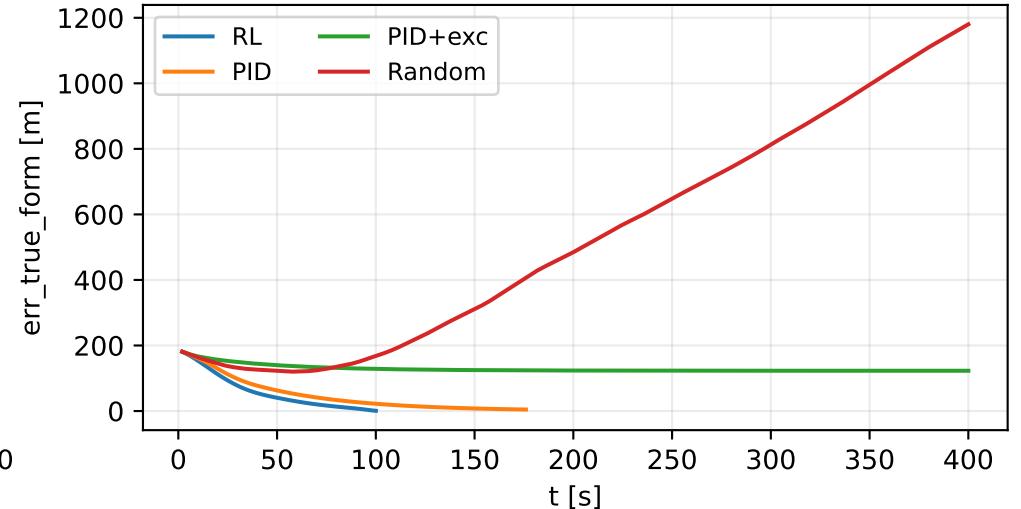
Follower angular rate



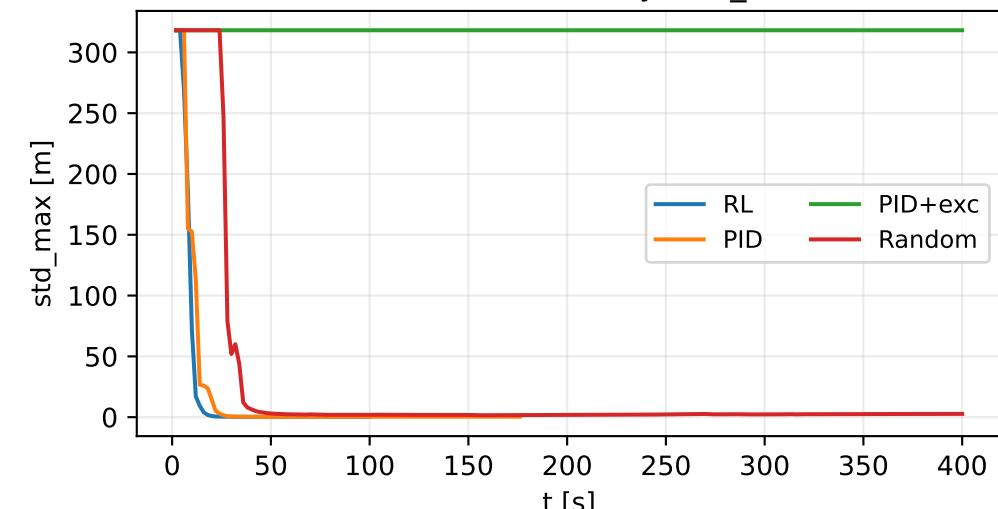
Trajectories (matched seed)



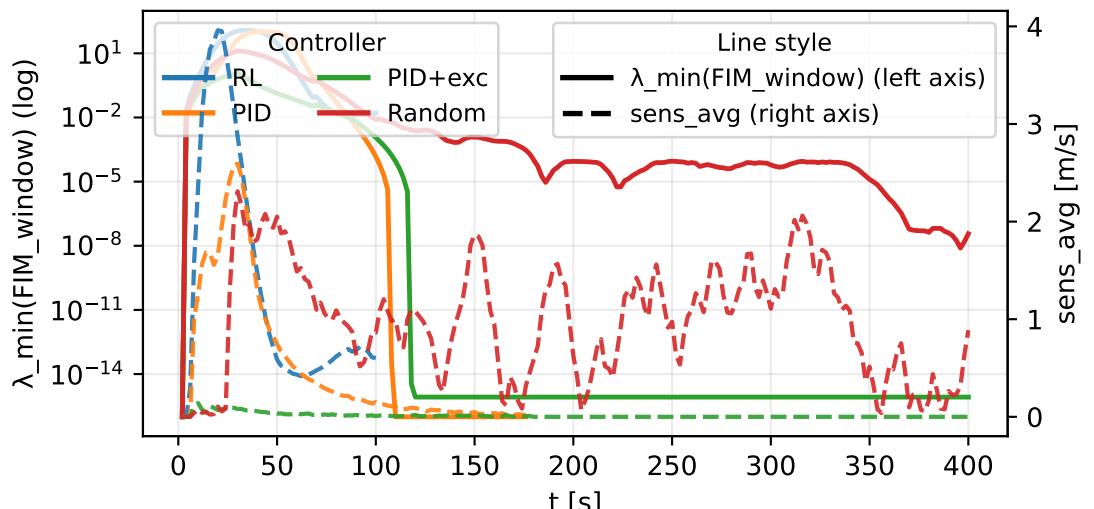
TRUE formation error



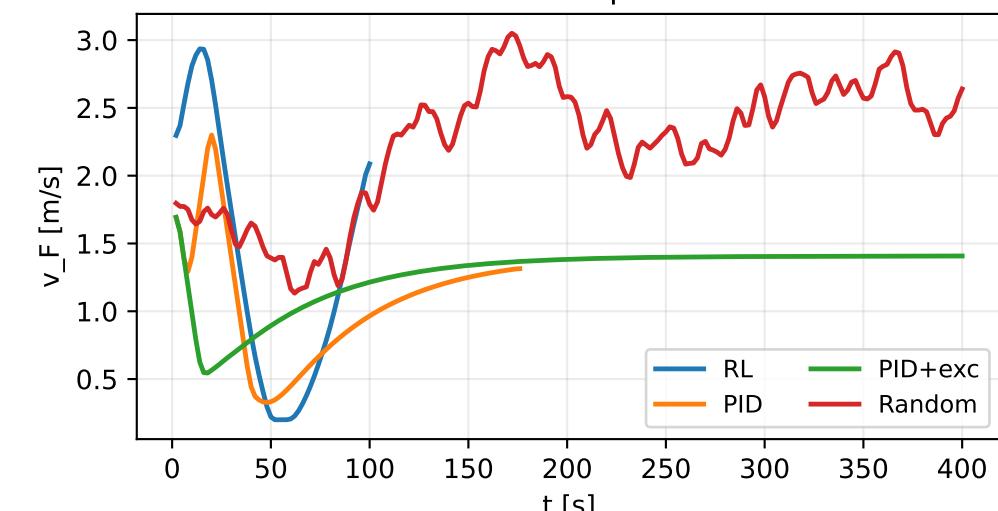
Estimator uncertainty (std_max)



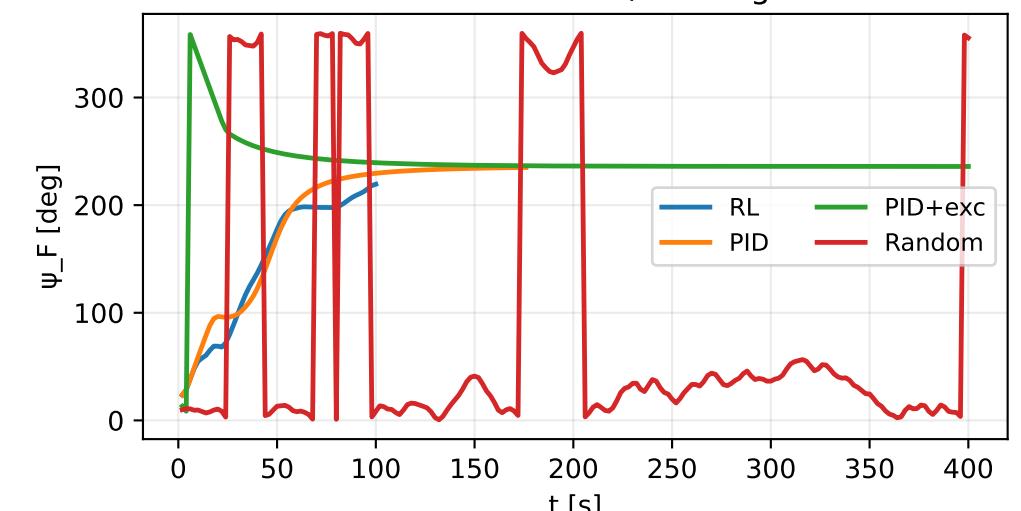
Information and excitation



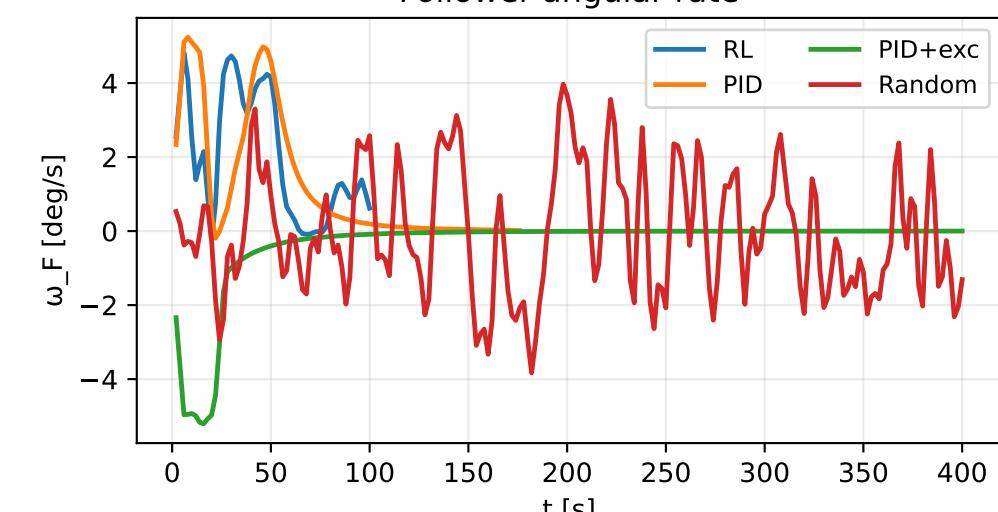
Follower speed



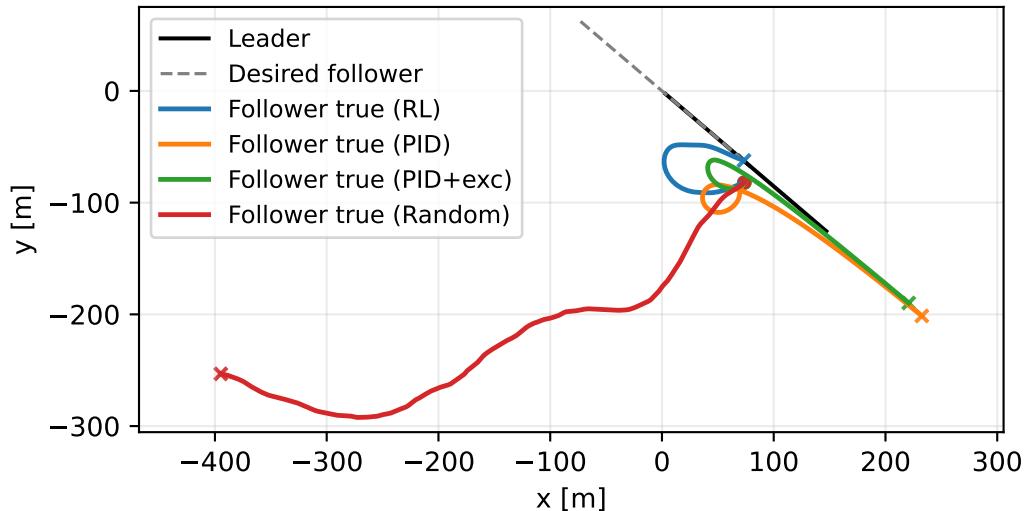
Follower course/heading



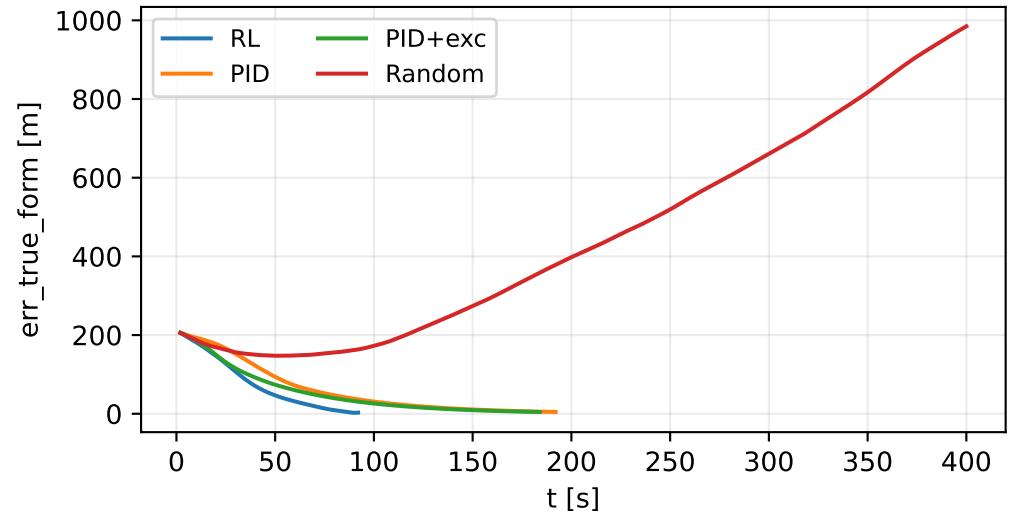
Follower angular rate



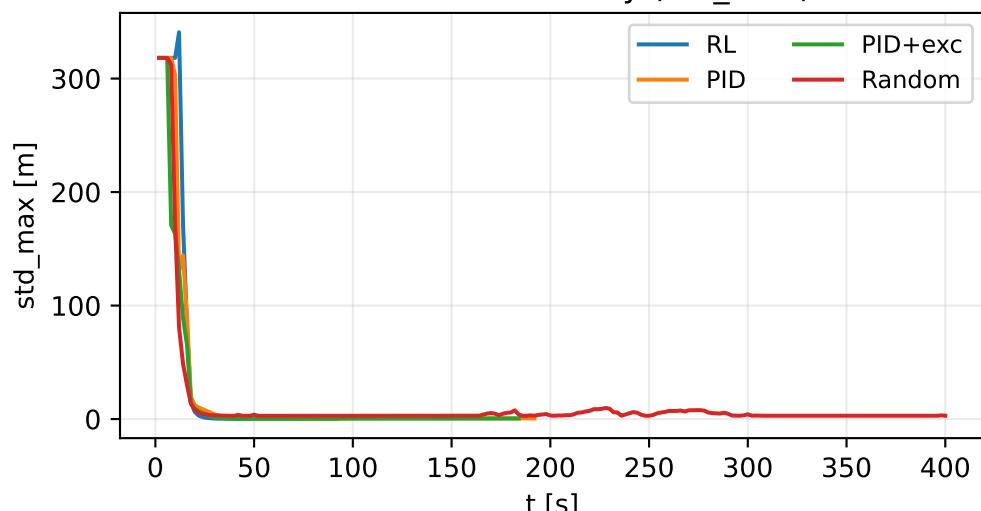
Trajectories (matched seed)



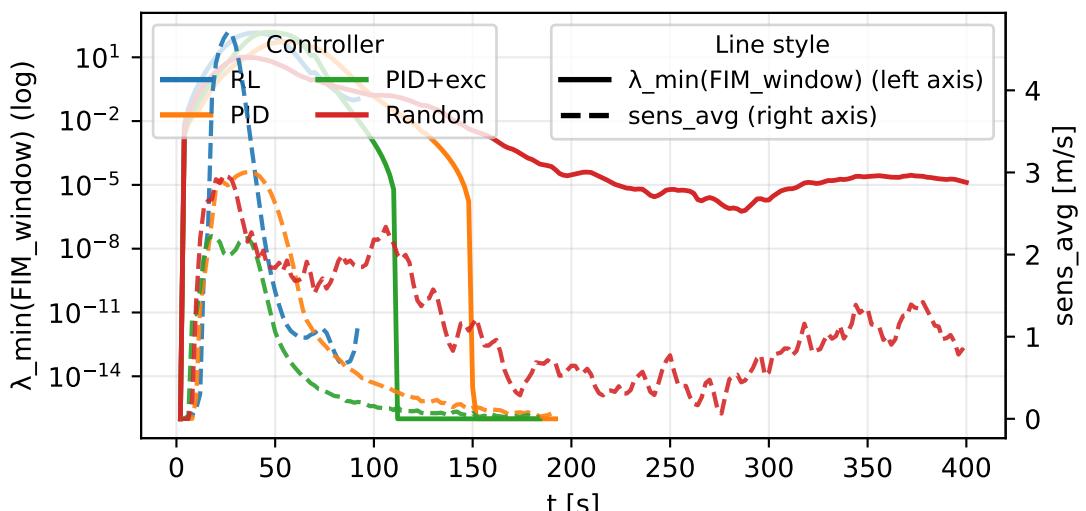
TRUE formation error



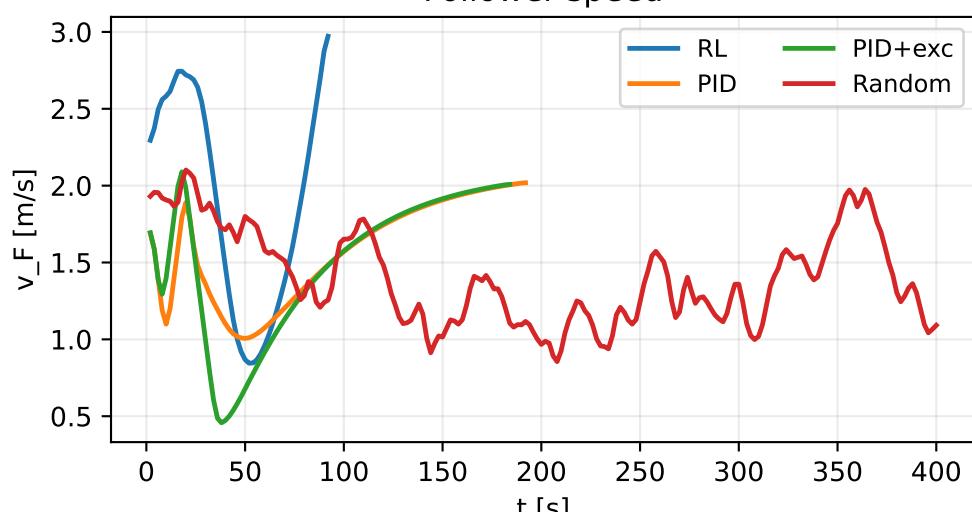
Estimator uncertainty (std_max)



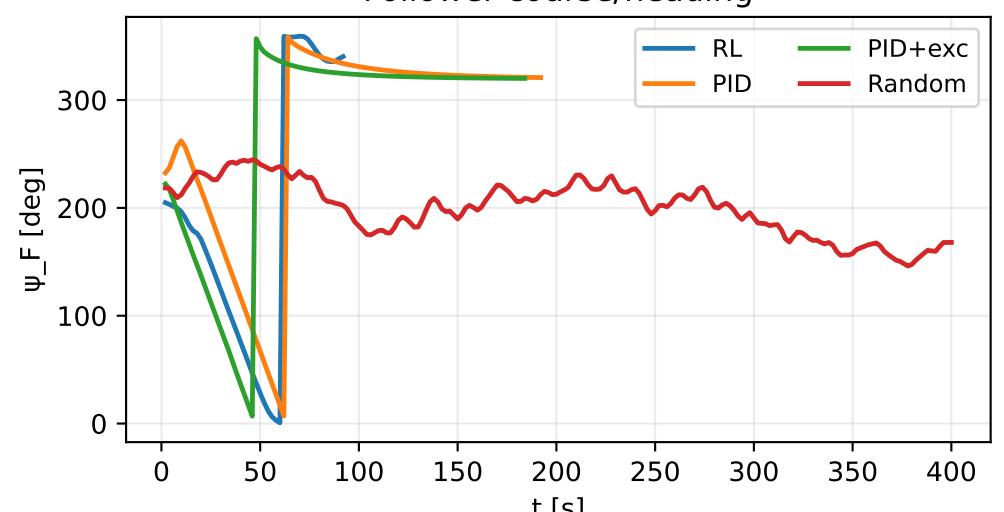
Information and excitation



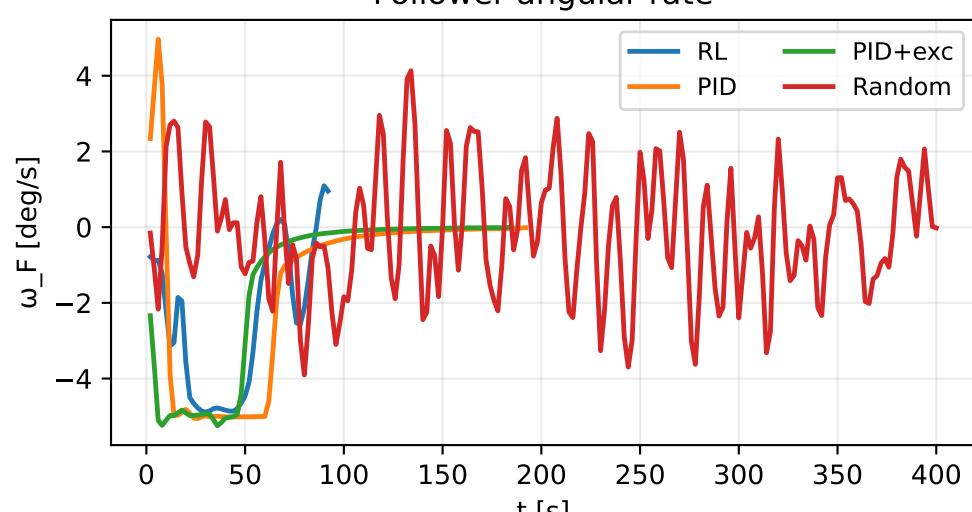
Follower speed



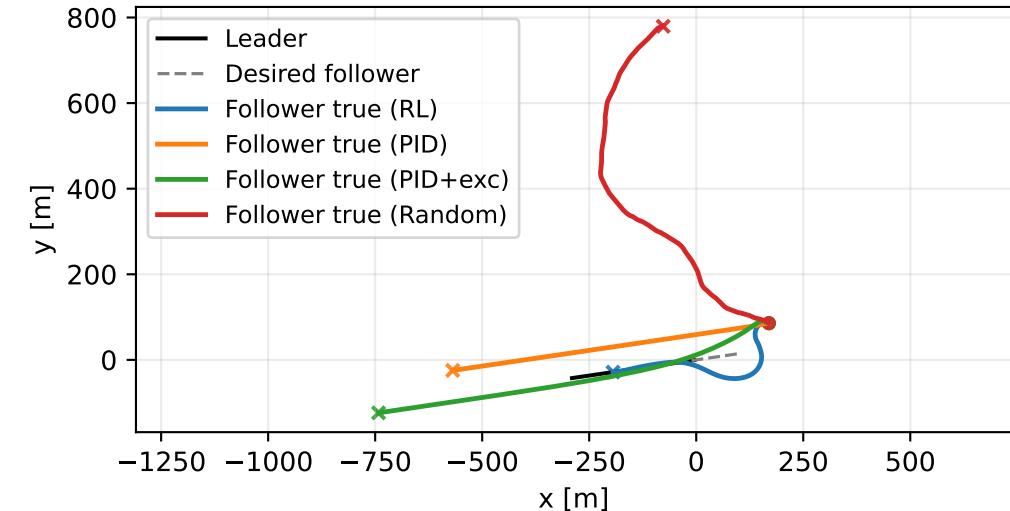
Follower course/heading



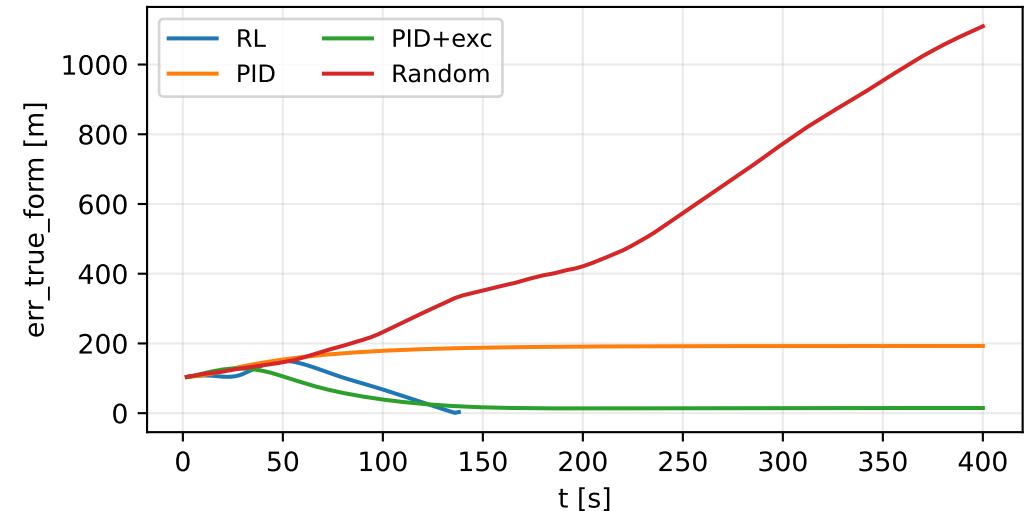
Follower angular rate



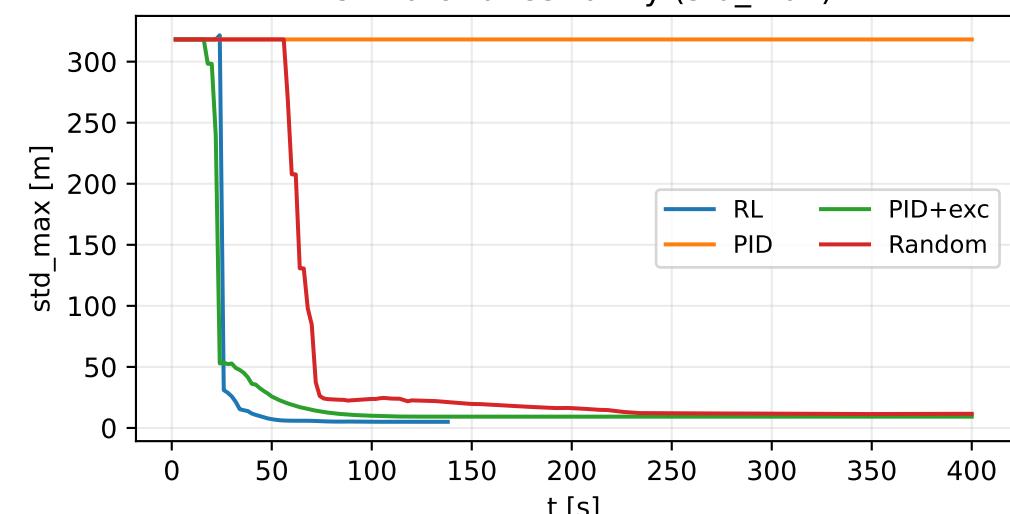
Trajectories (matched seed)



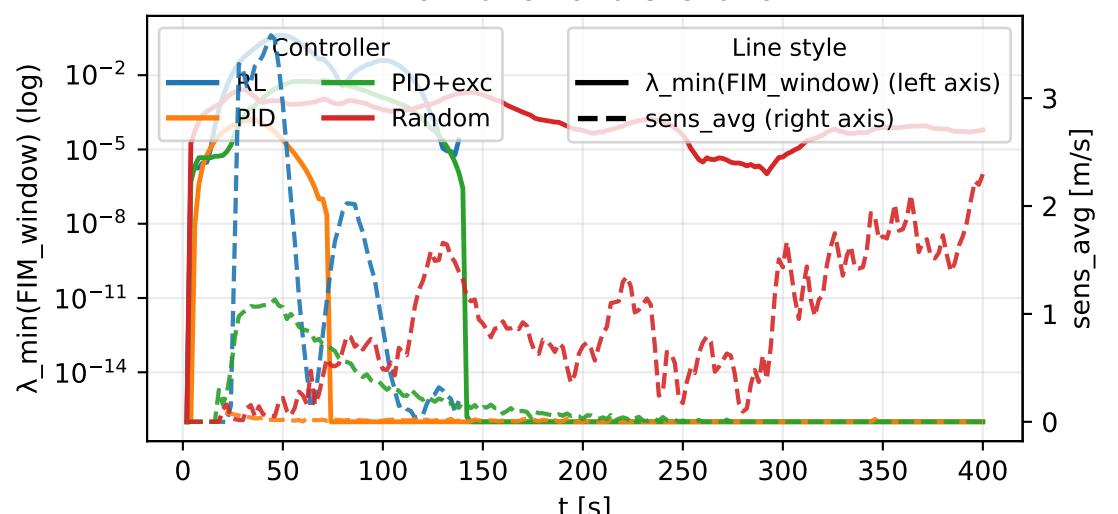
TRUE formation error



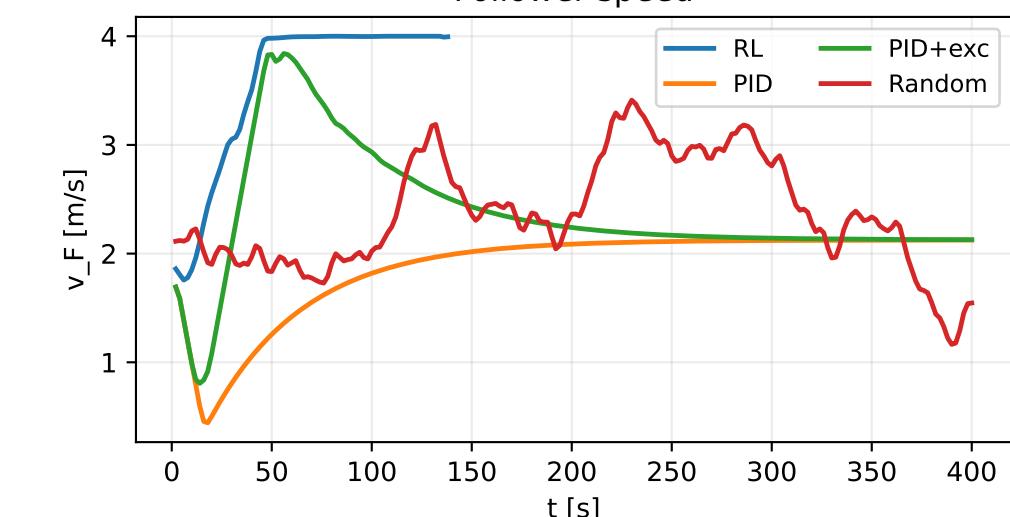
Estimator uncertainty (std_max)



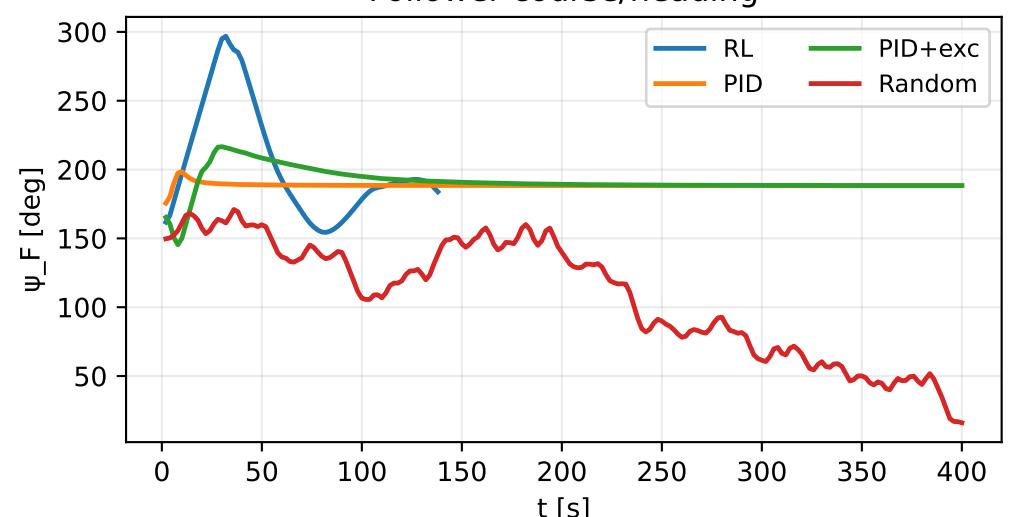
Information and excitation



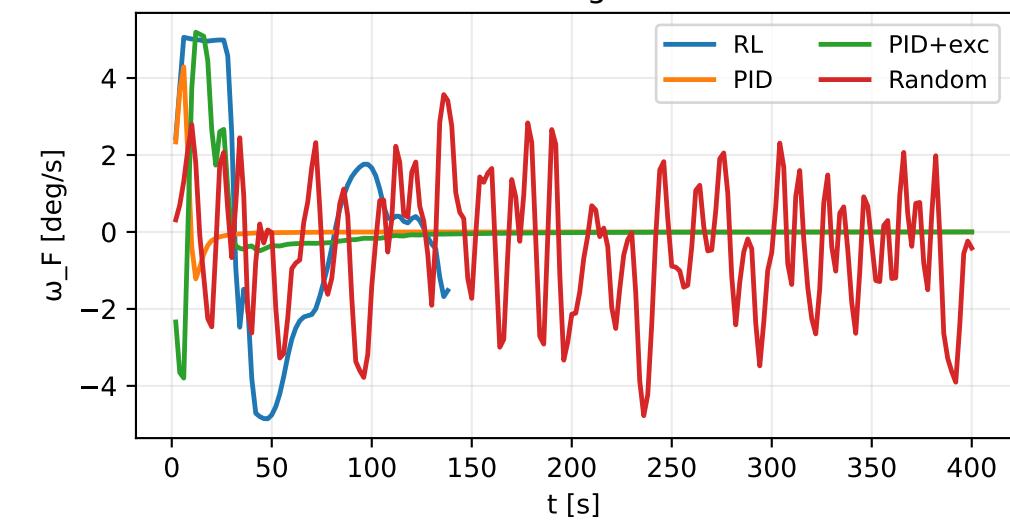
Follower speed



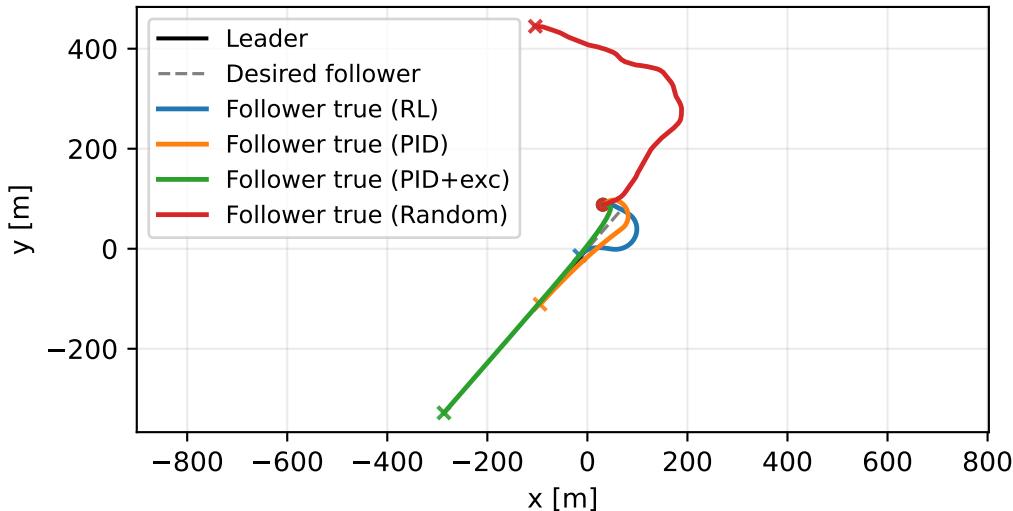
Follower course/heading



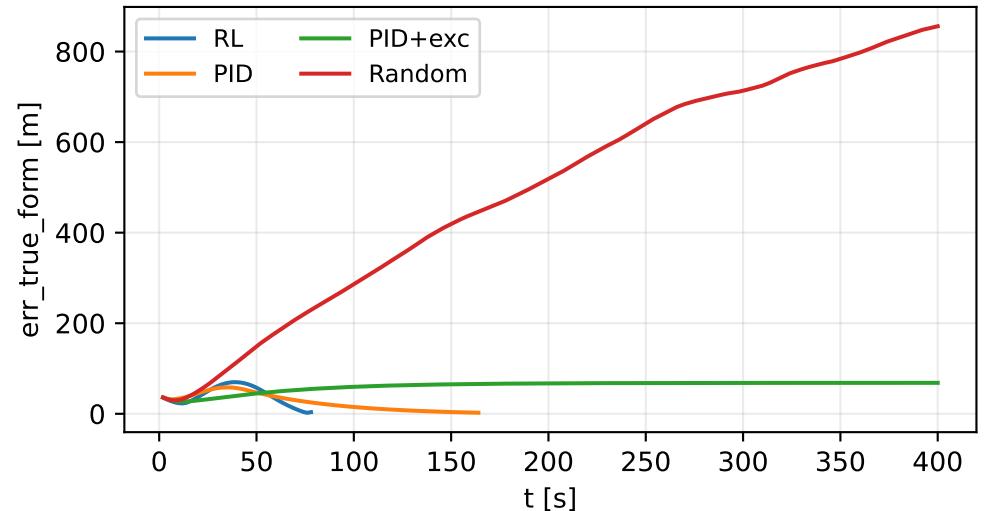
Follower angular rate



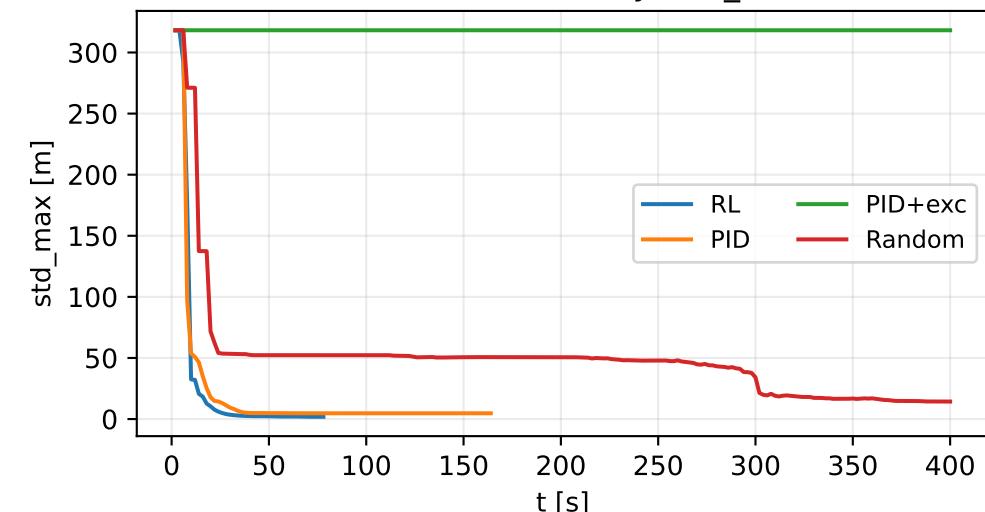
Trajectories (matched seed)



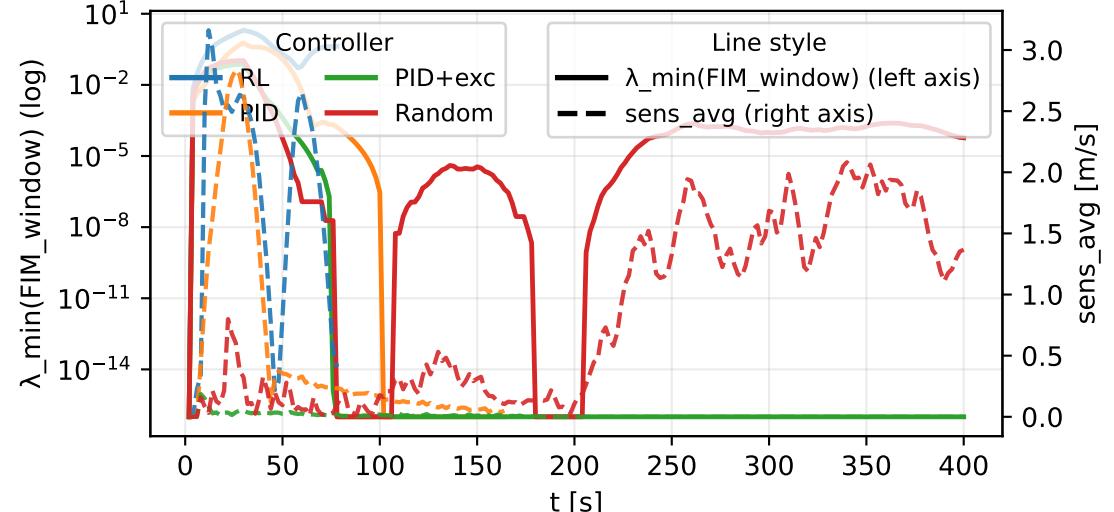
TRUE formation error



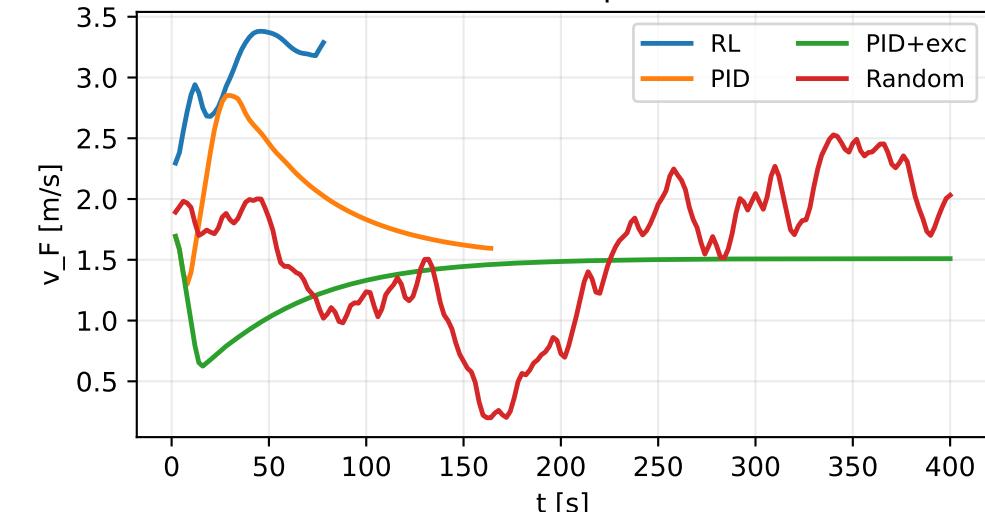
Estimator uncertainty (std_max)



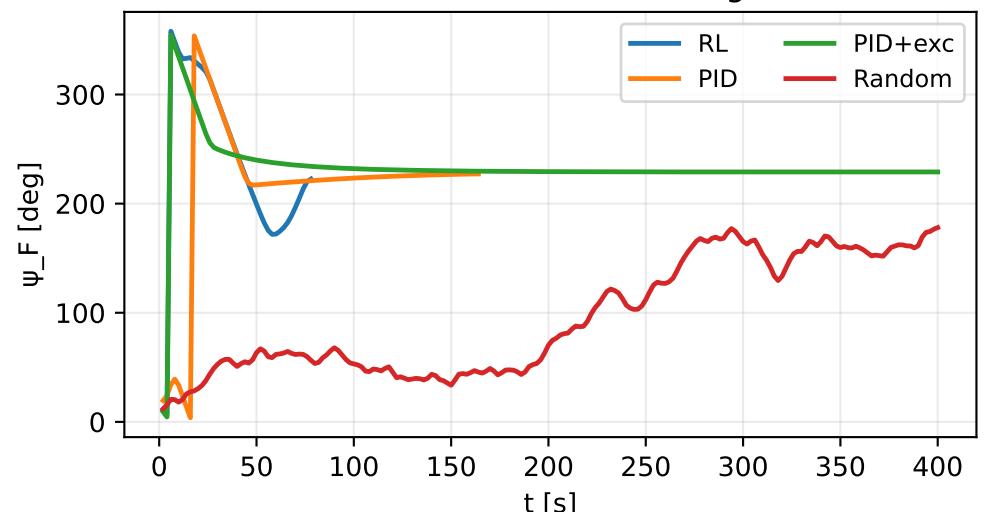
Information and excitation



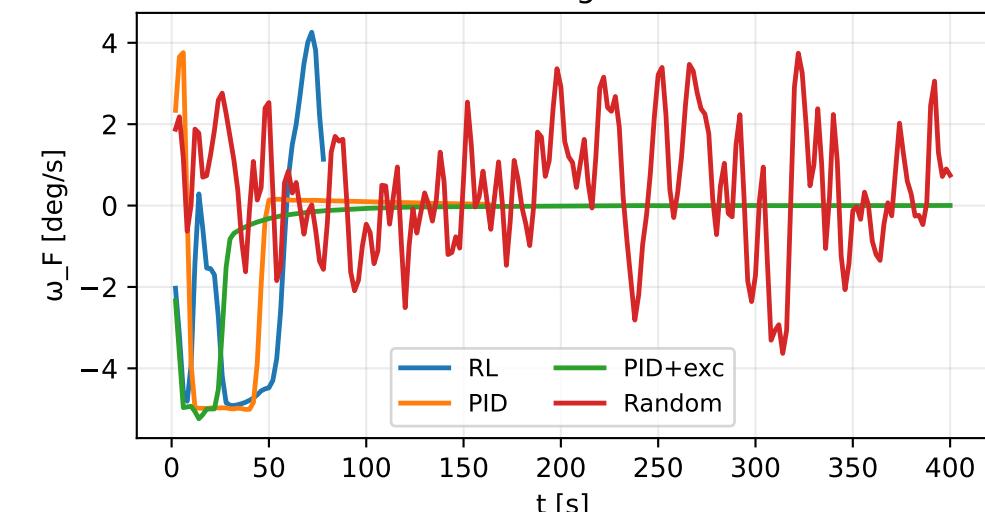
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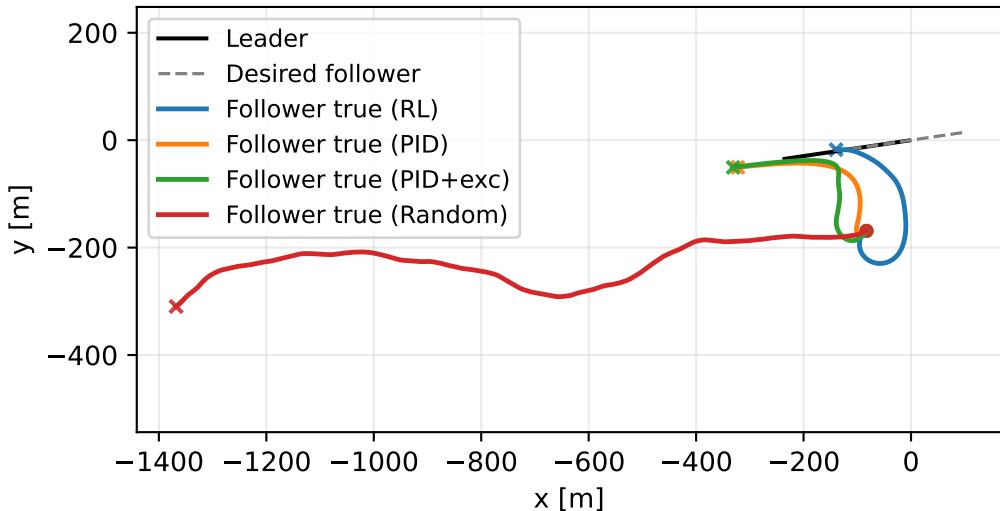
Follower course/heading



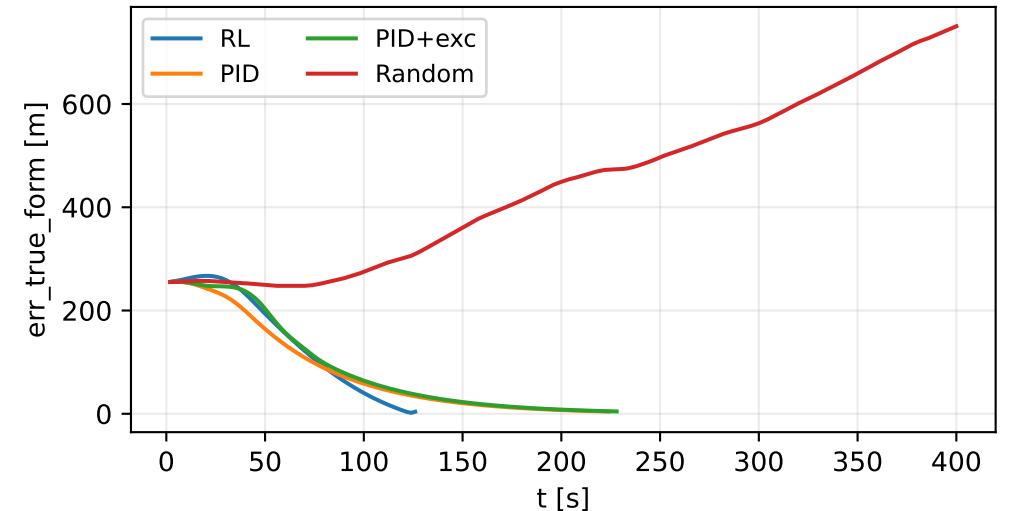
Follower angular rate



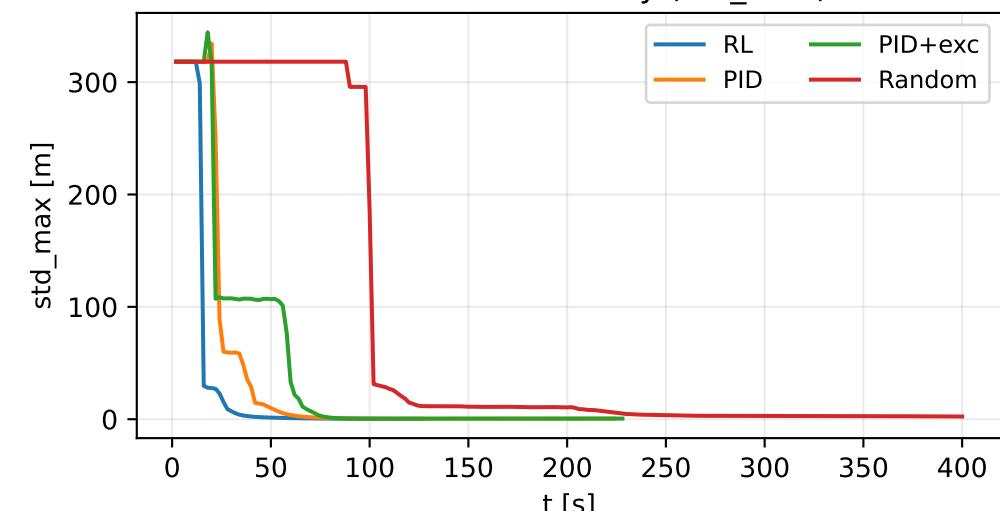
Trajectories (matched seed)



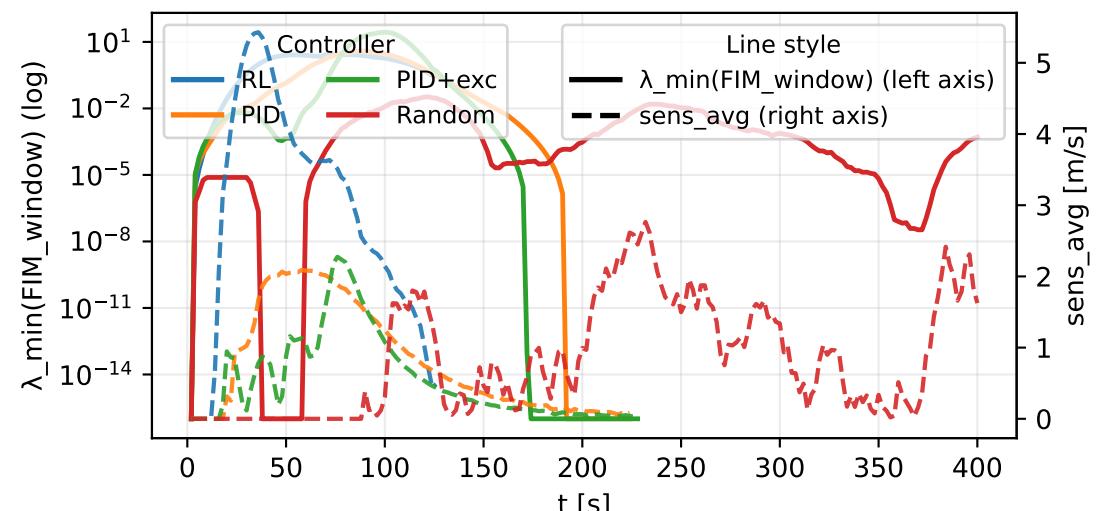
TRUE formation error



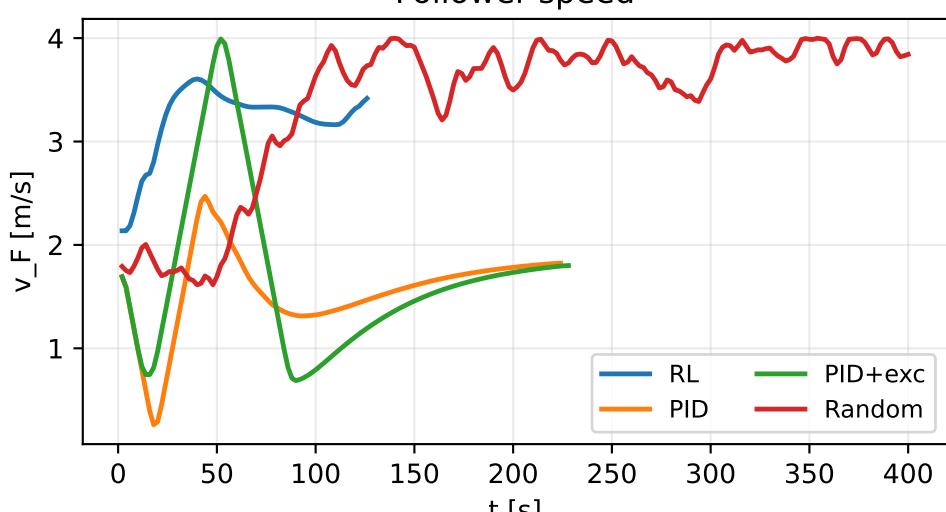
Estimator uncertainty (std_max)



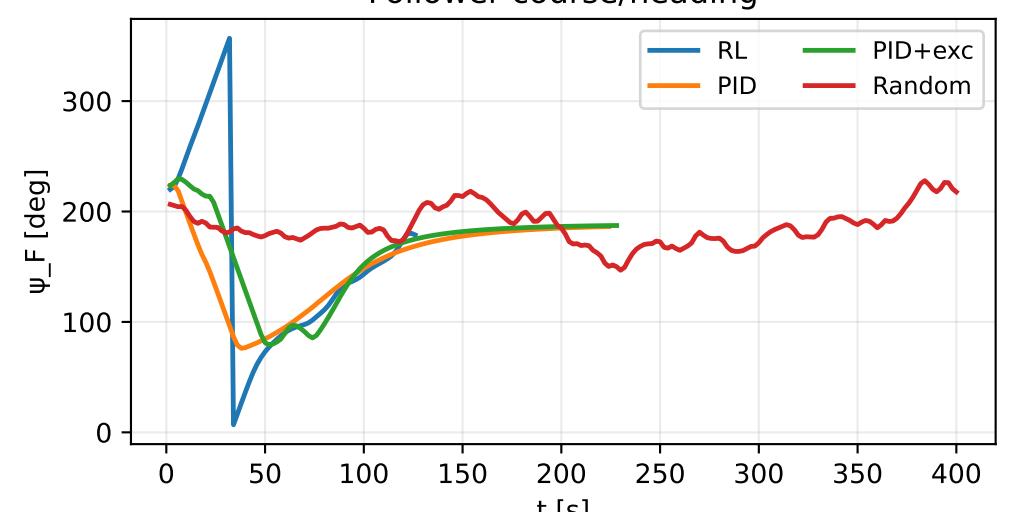
Information and excitation



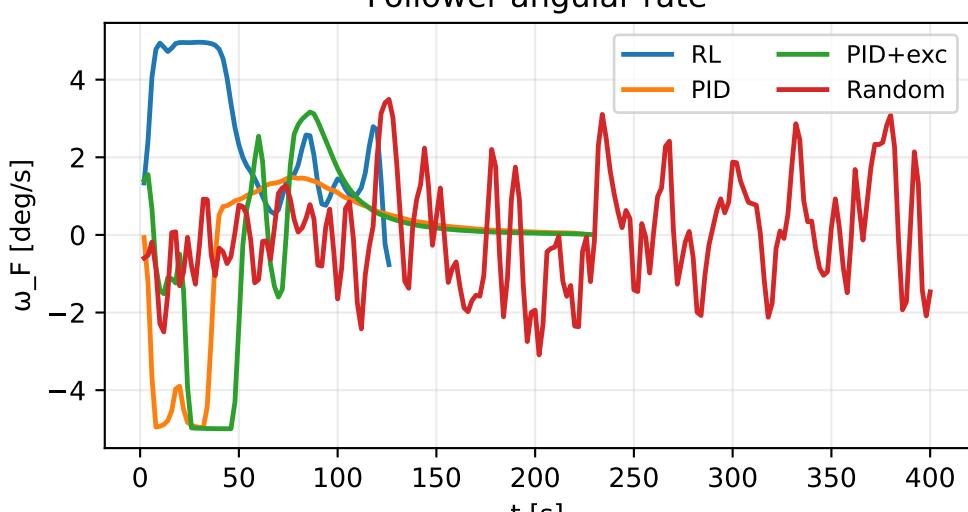
Follower speed



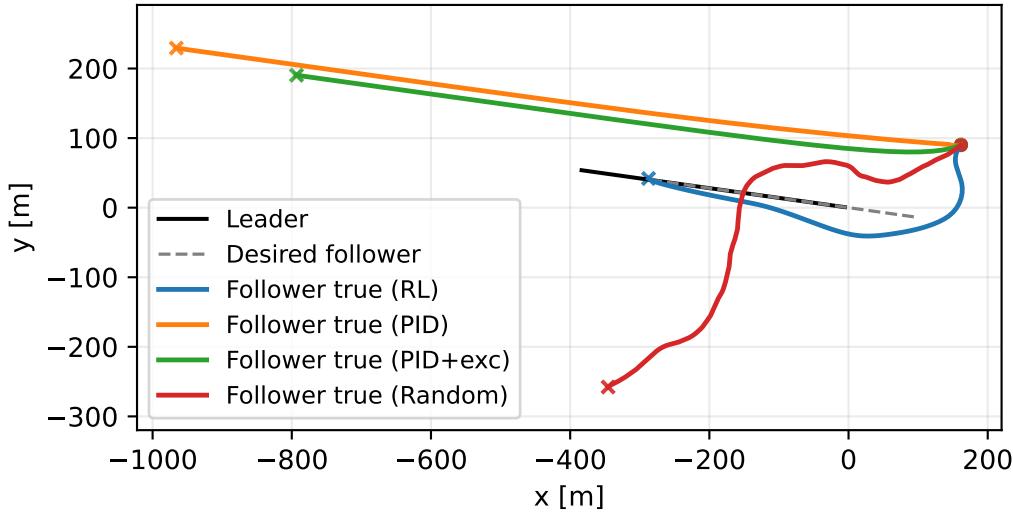
Follower course/heading



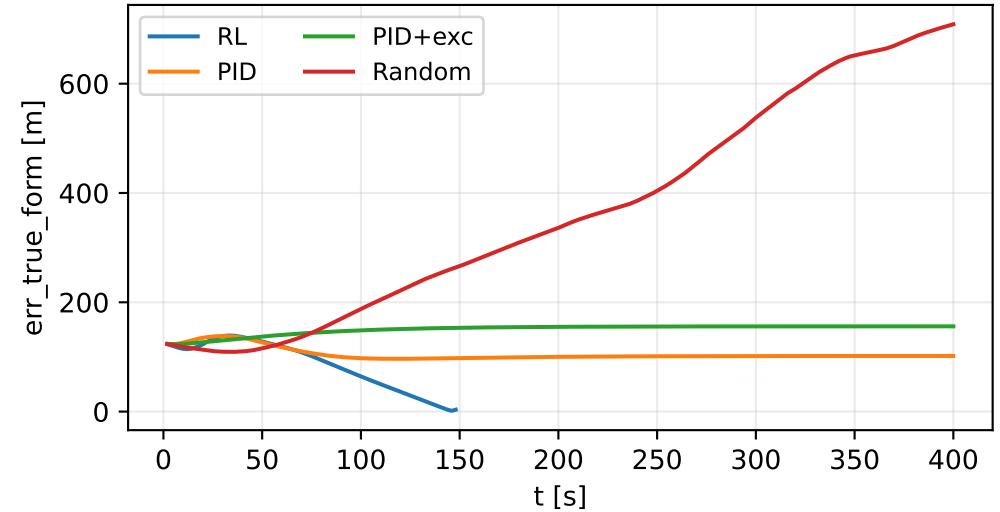
Follower angular rate



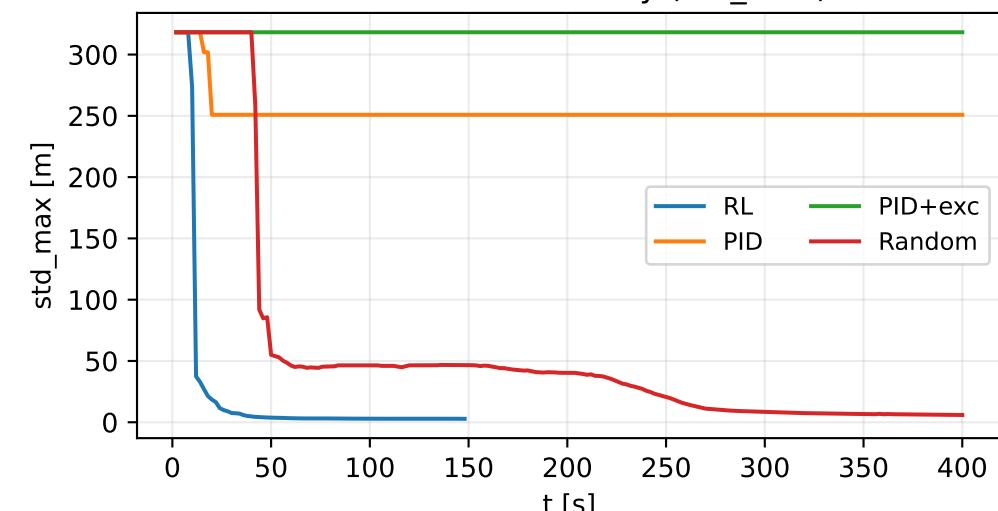
Trajectories (matched seed)



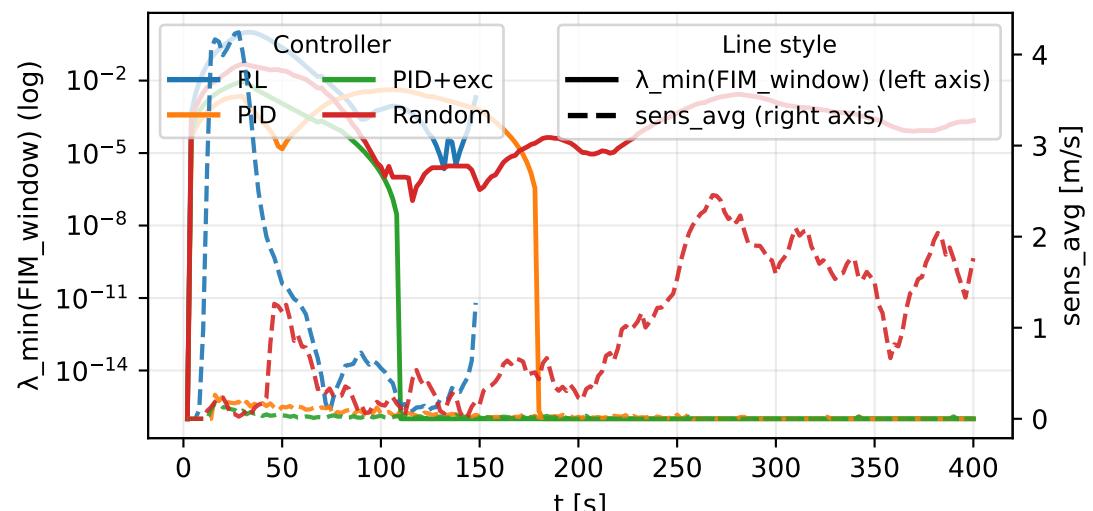
TRUE formation error



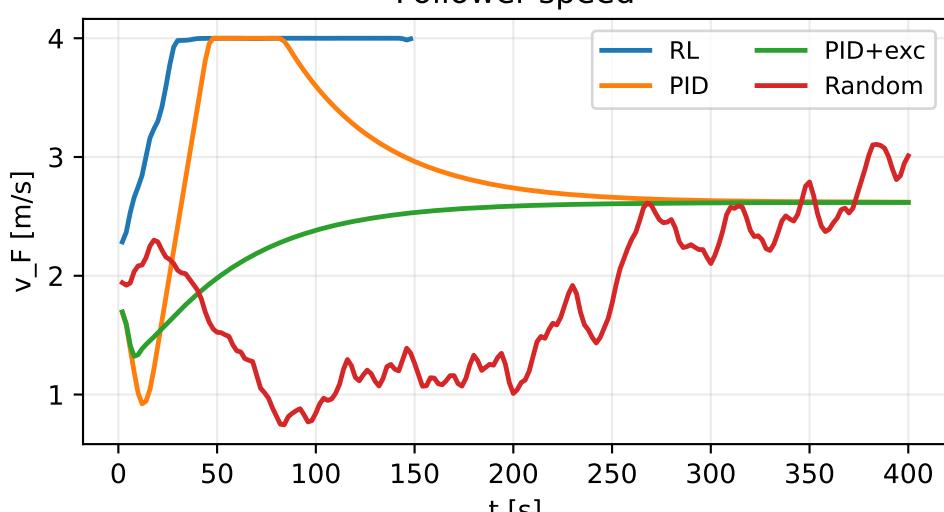
Estimator uncertainty (std_max)



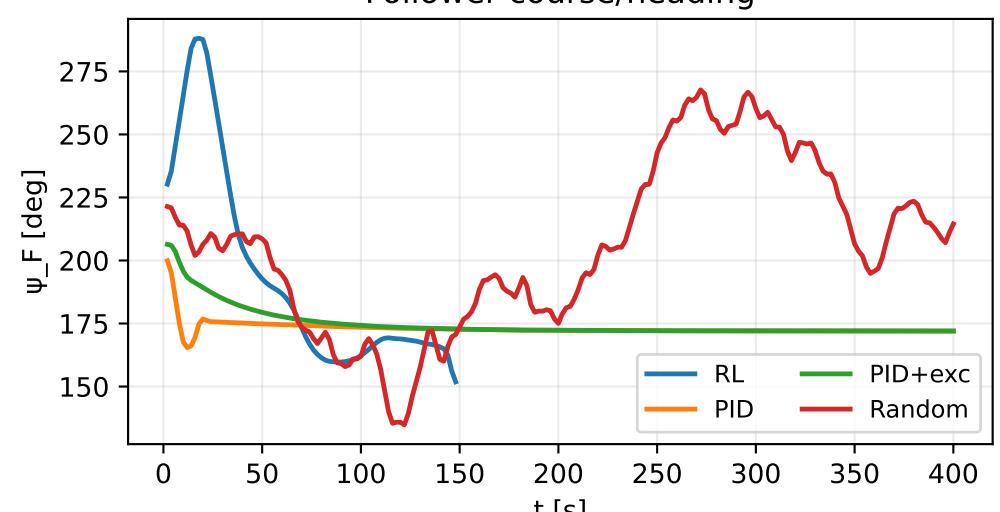
Information and excitation



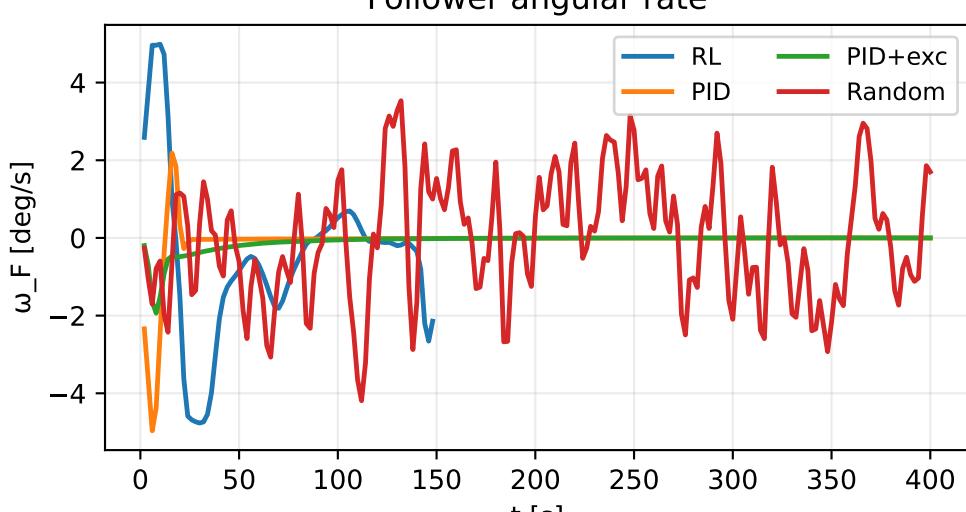
Follower speed



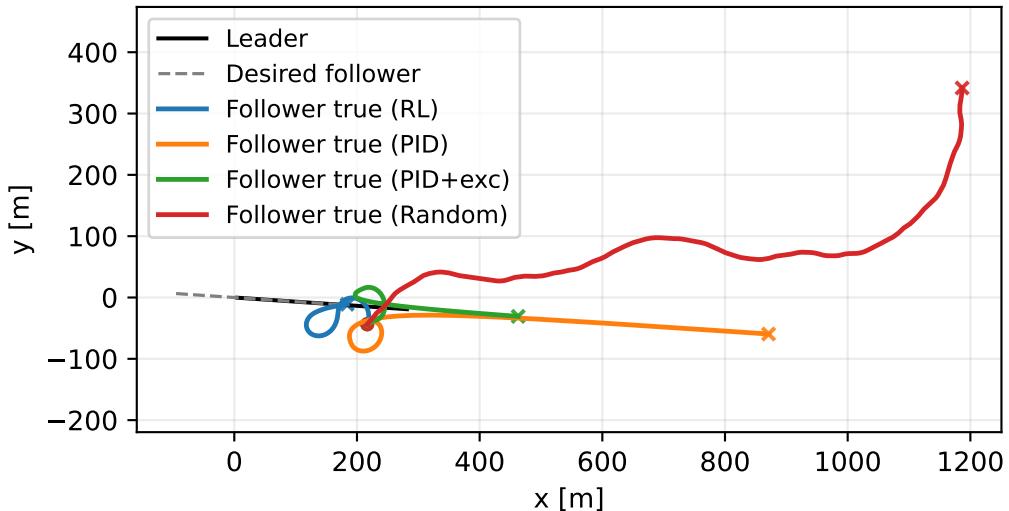
Follower course/heading



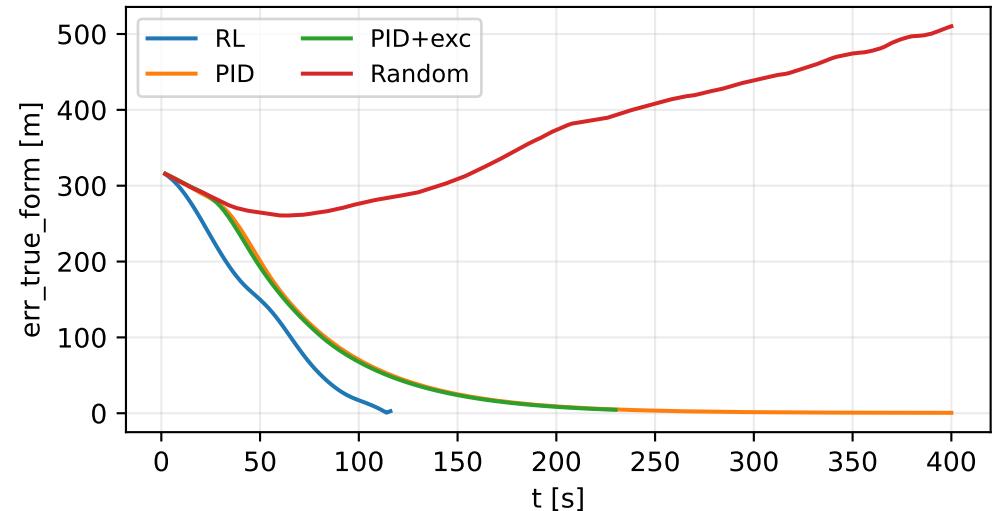
Follower angular rate



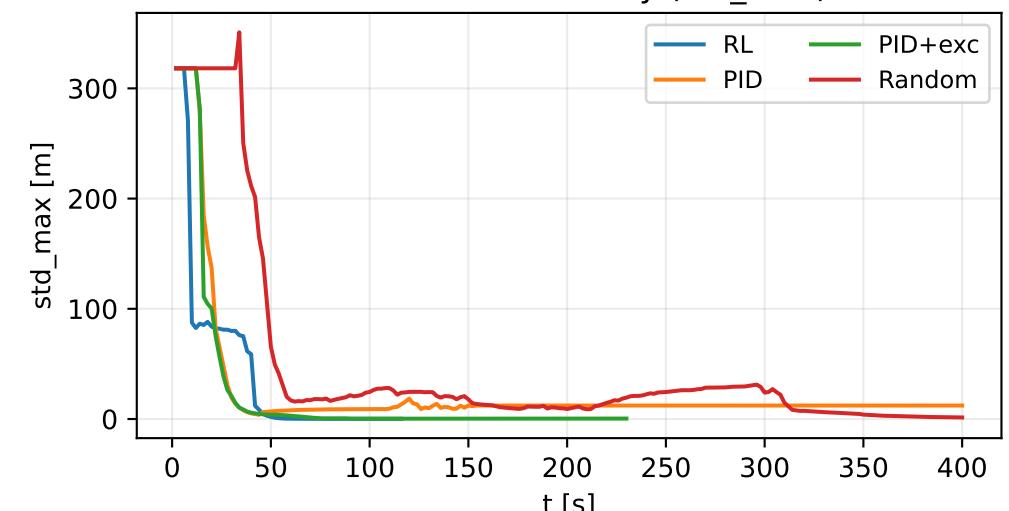
Trajectories (matched seed)



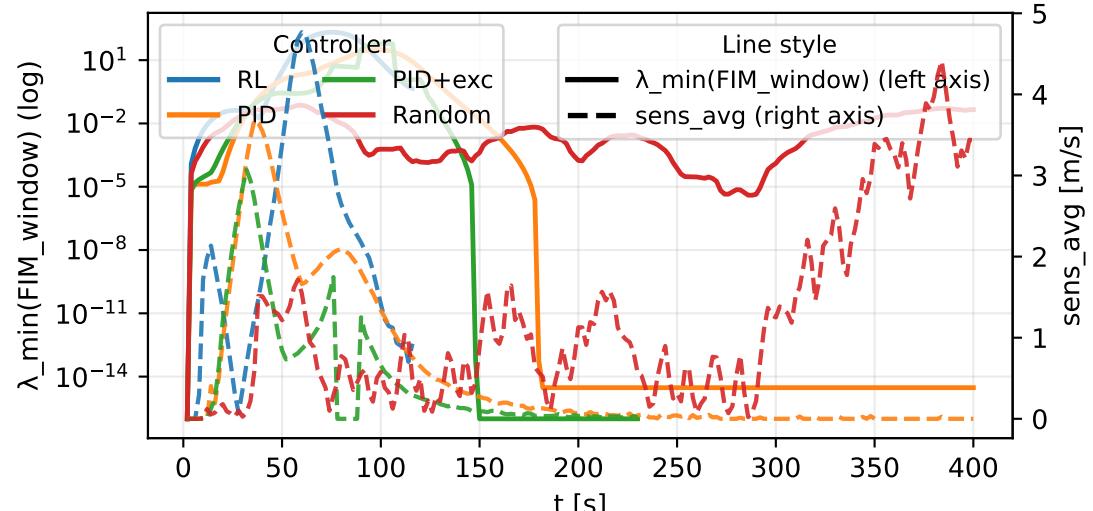
TRUE formation error



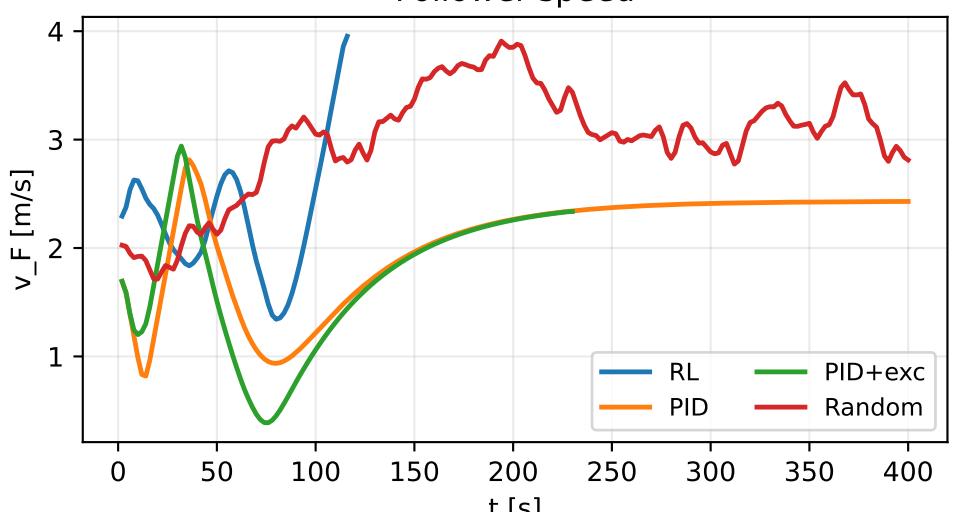
Estimator uncertainty (std_max)



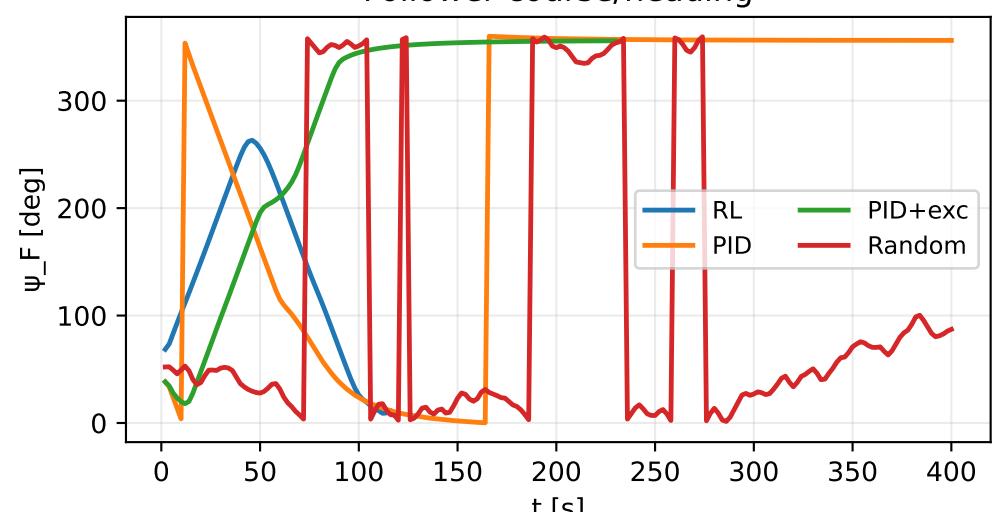
Information and excitation



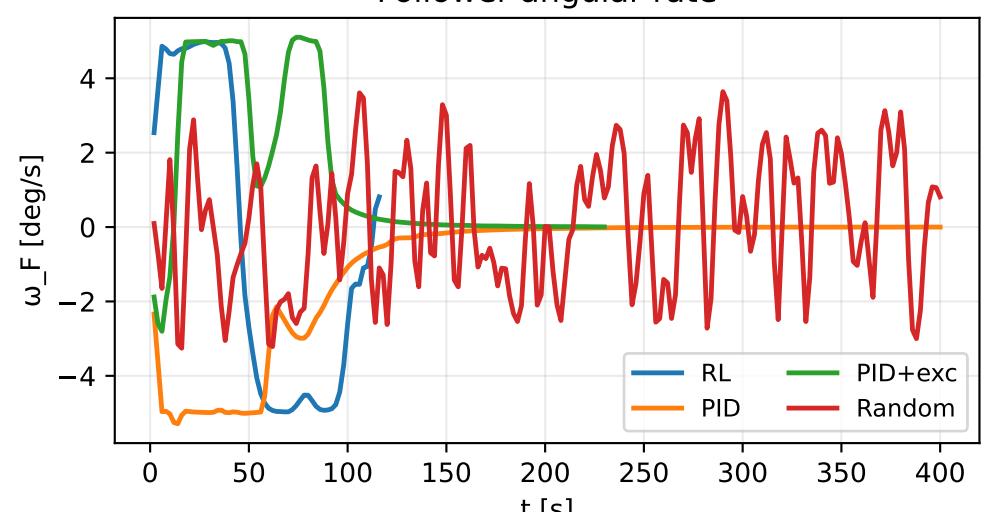
Follower speed



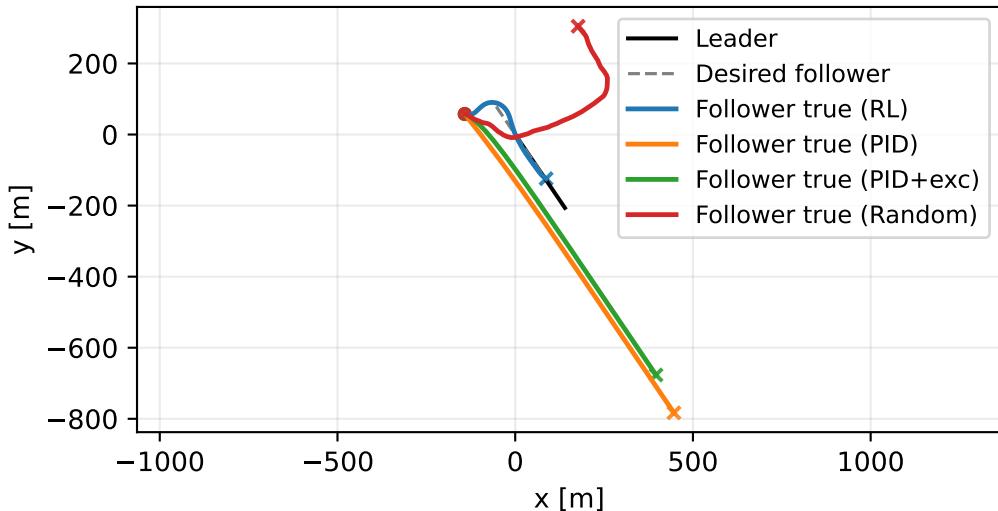
Follower course/heading



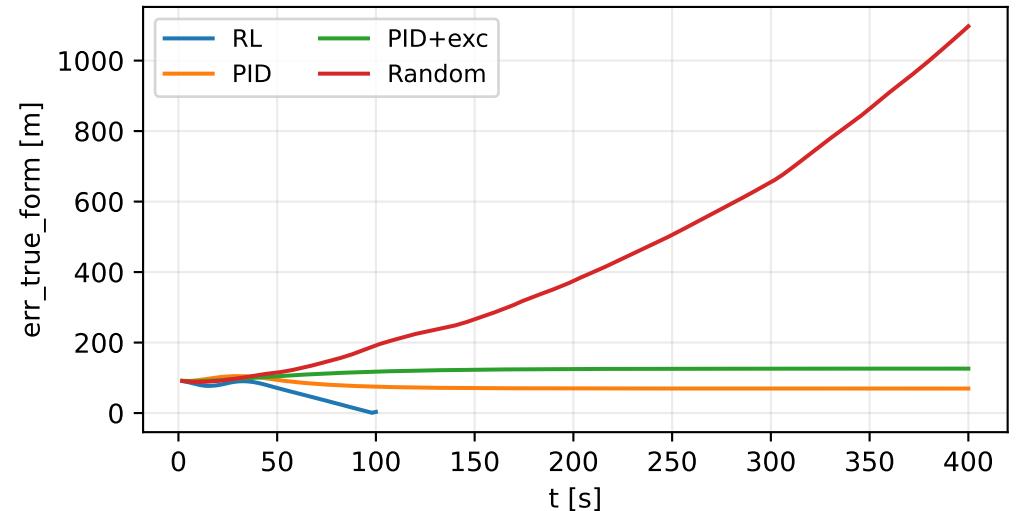
Follower angular rate



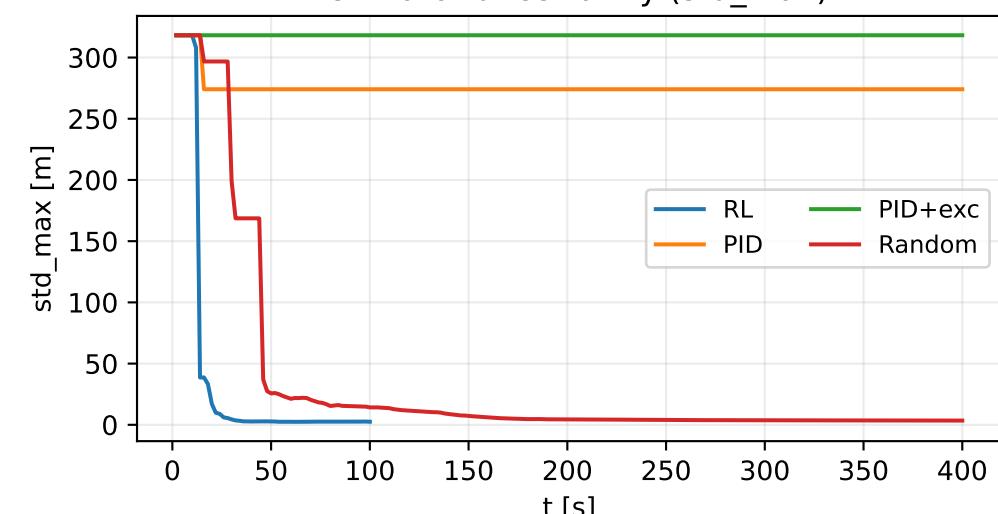
Trajectories (matched seed)



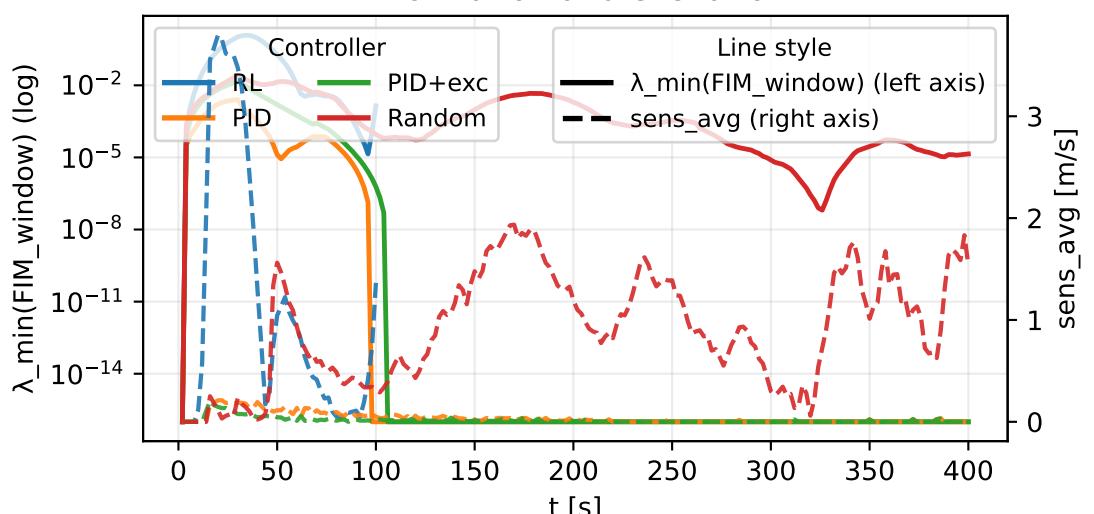
TRUE formation error



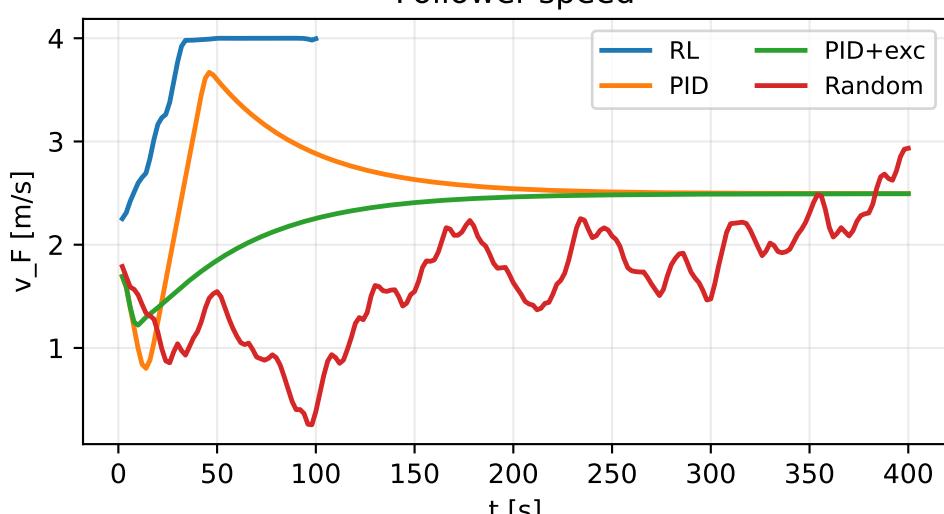
Estimator uncertainty (std_max)



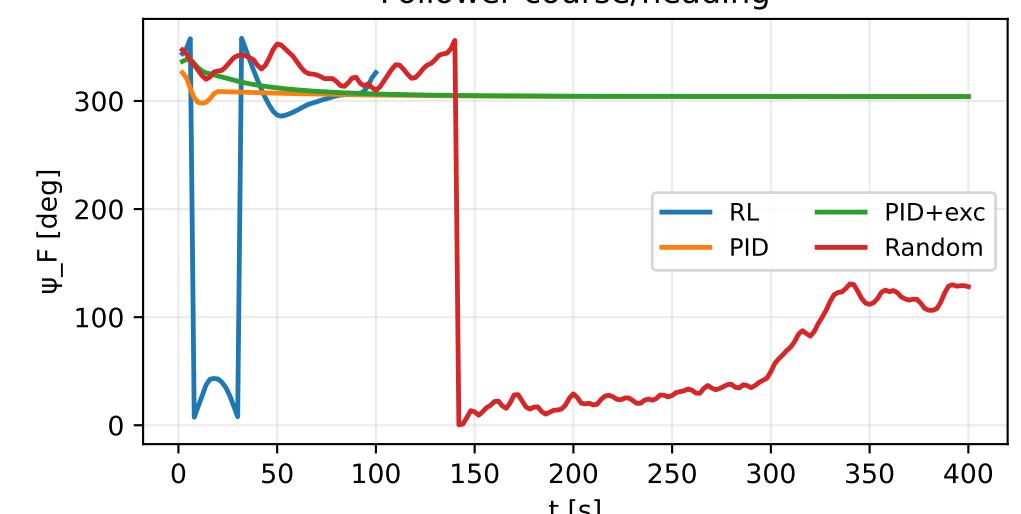
Information and excitation



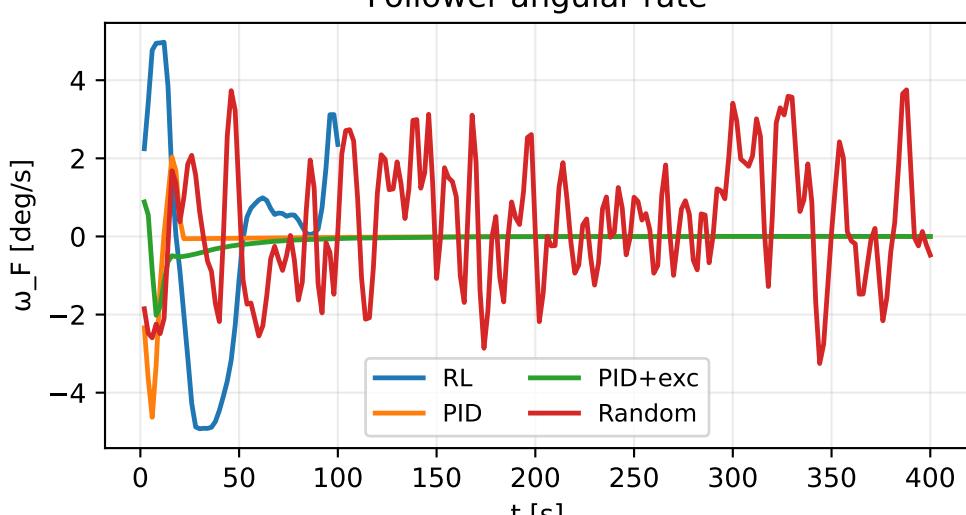
Follower speed



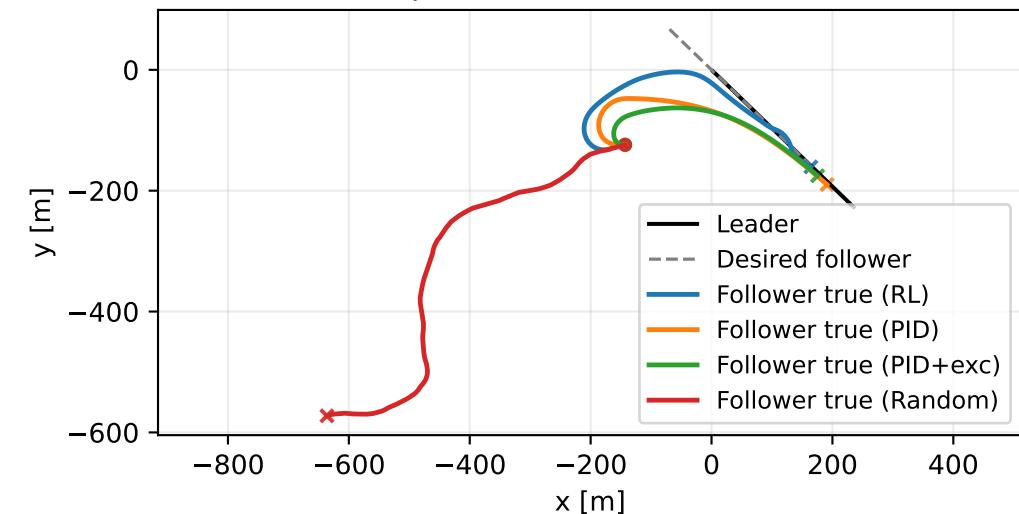
Follower course/heading



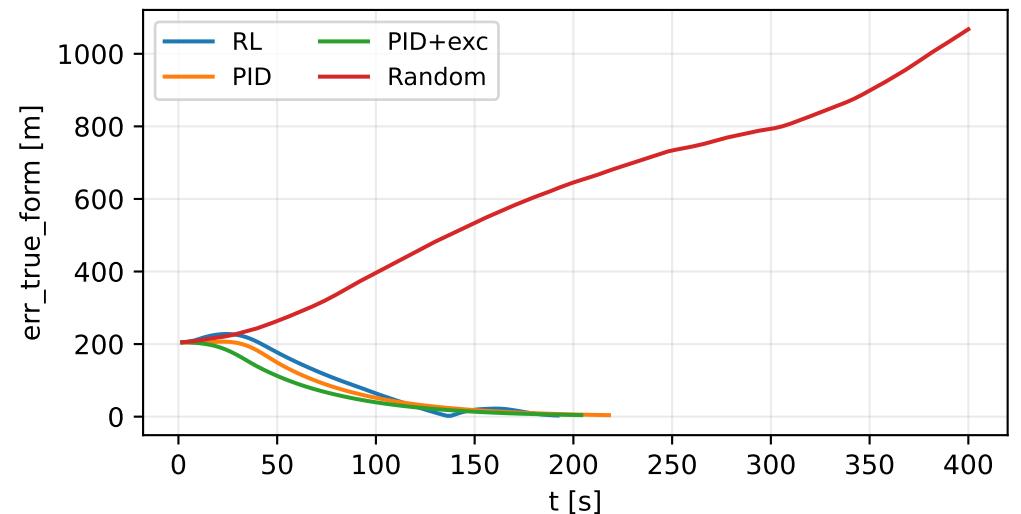
Follower angular rate



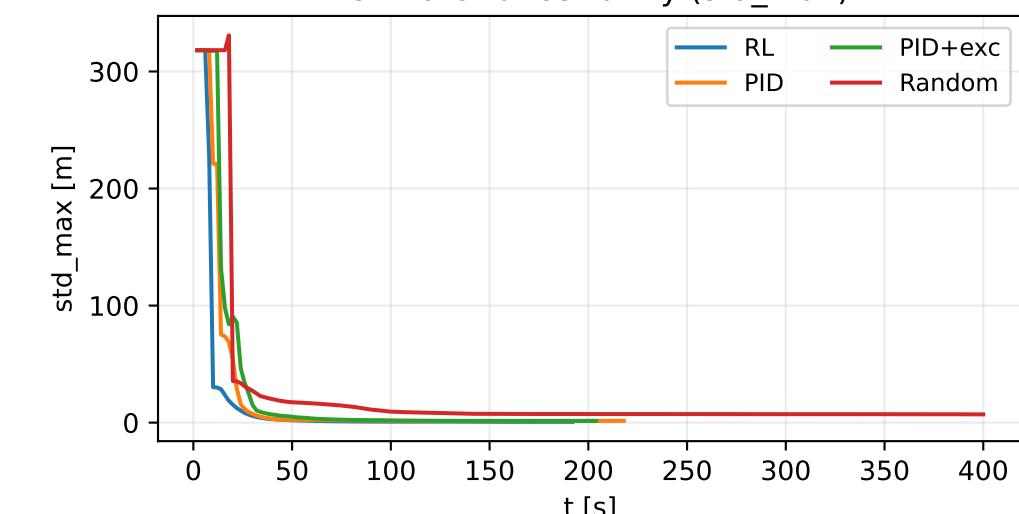
Trajectories (matched seed)



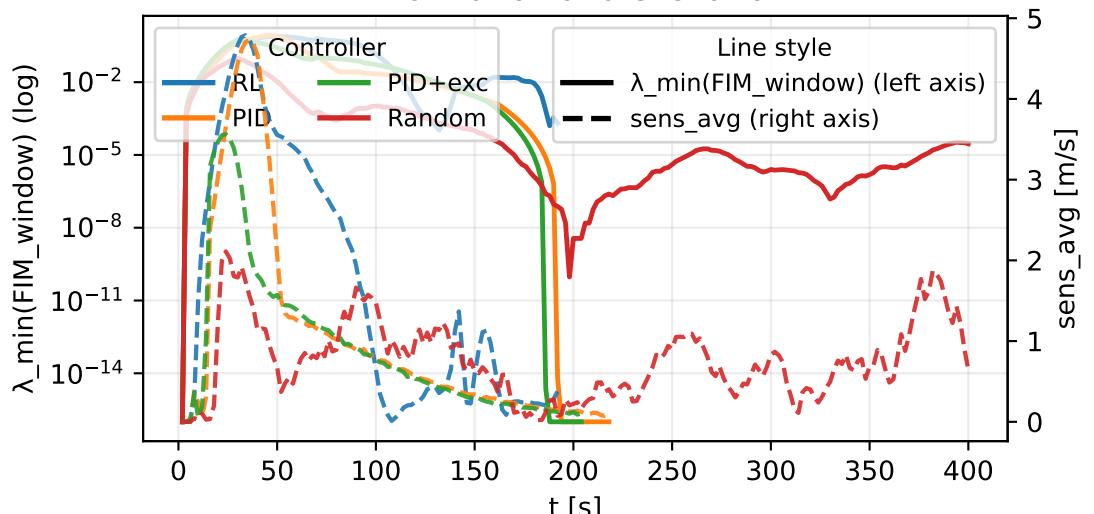
TRUE formation error



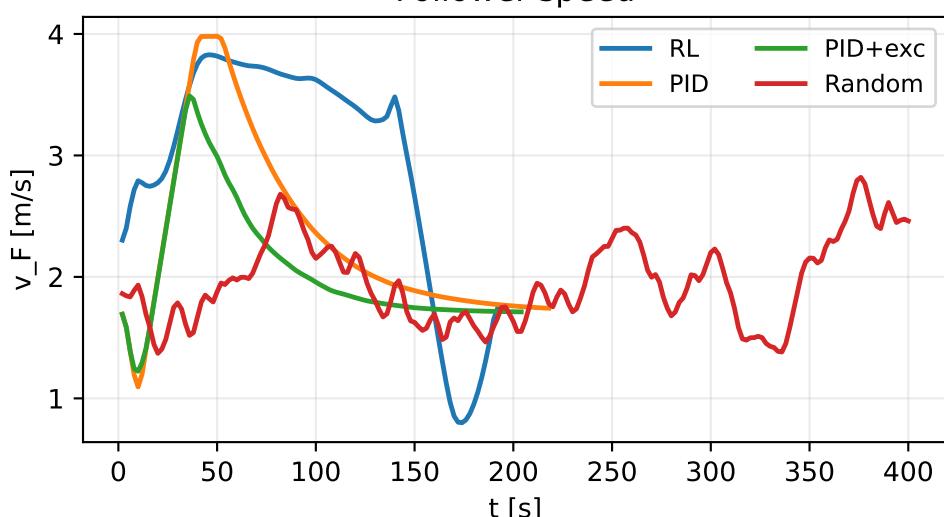
Estimator uncertainty (std_max)



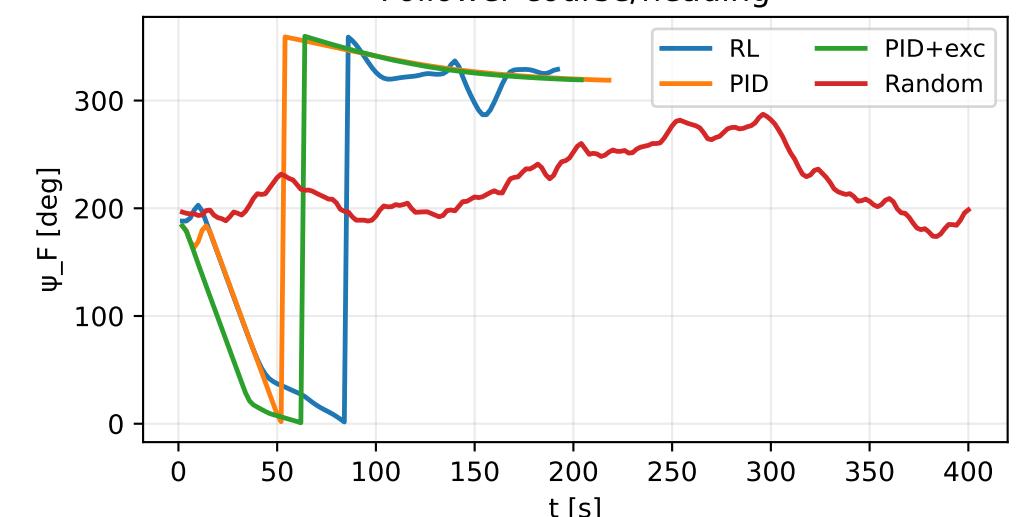
Information and excitation



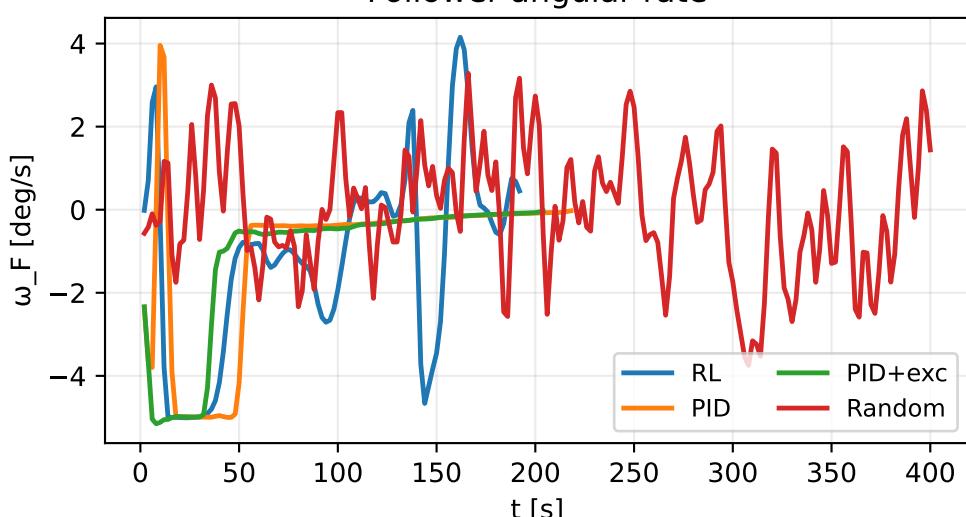
Follower speed



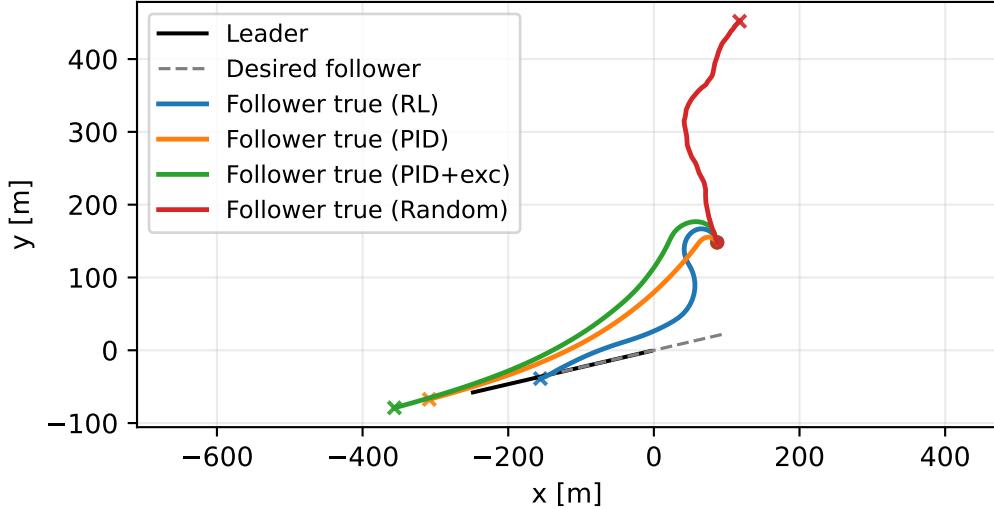
Follower course/heading



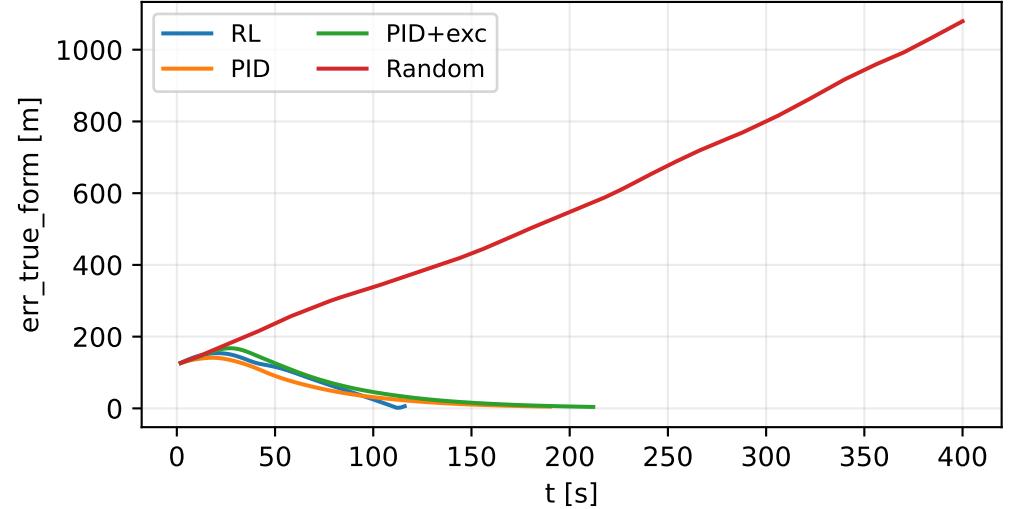
Follower angular rate



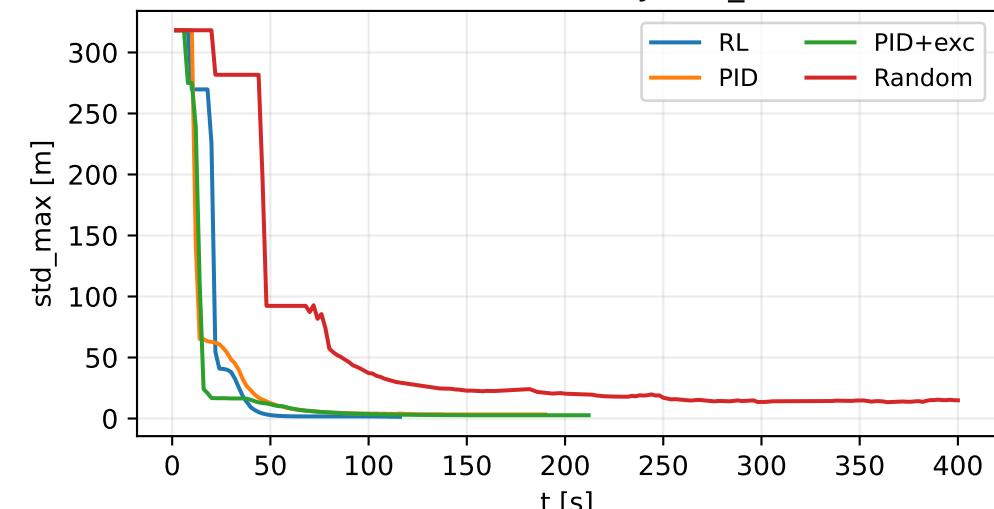
Trajectories (matched seed)



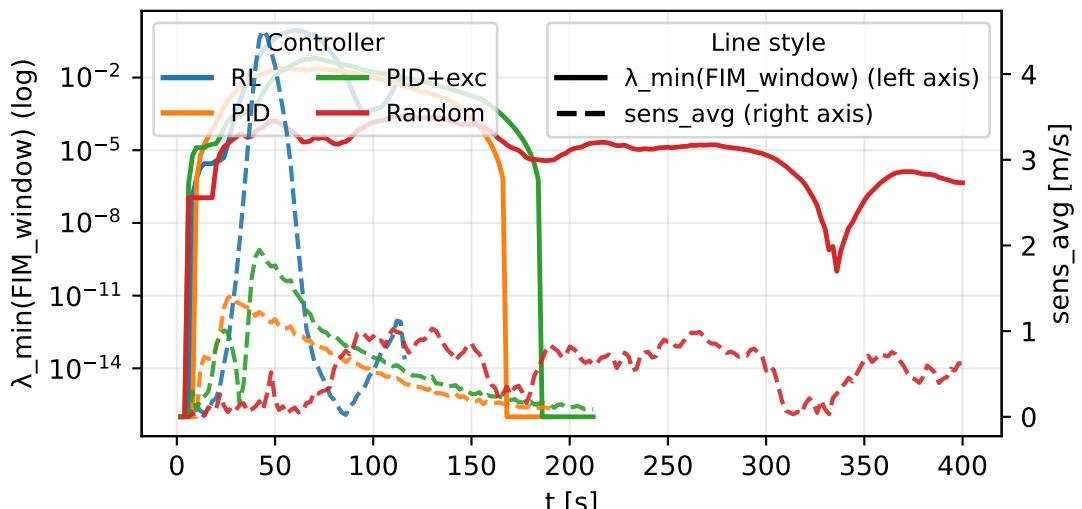
TRUE formation error



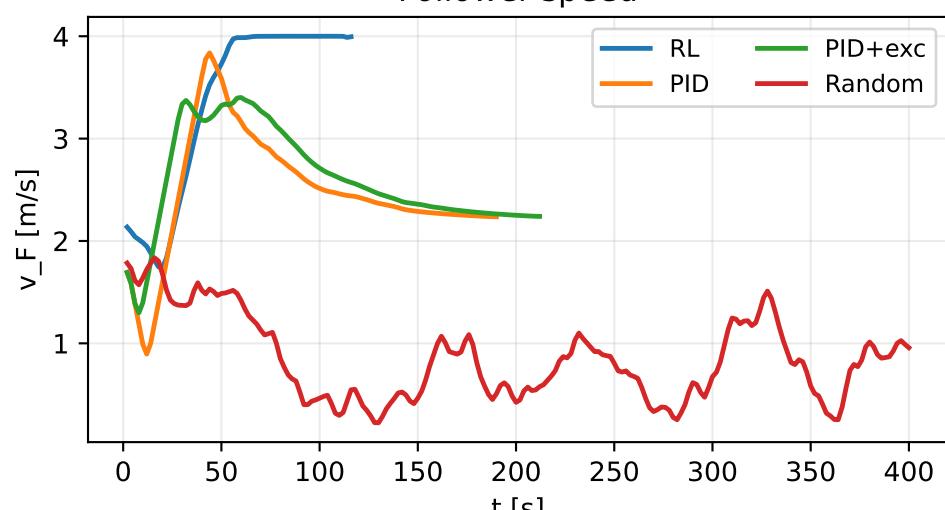
Estimator uncertainty (std_max)



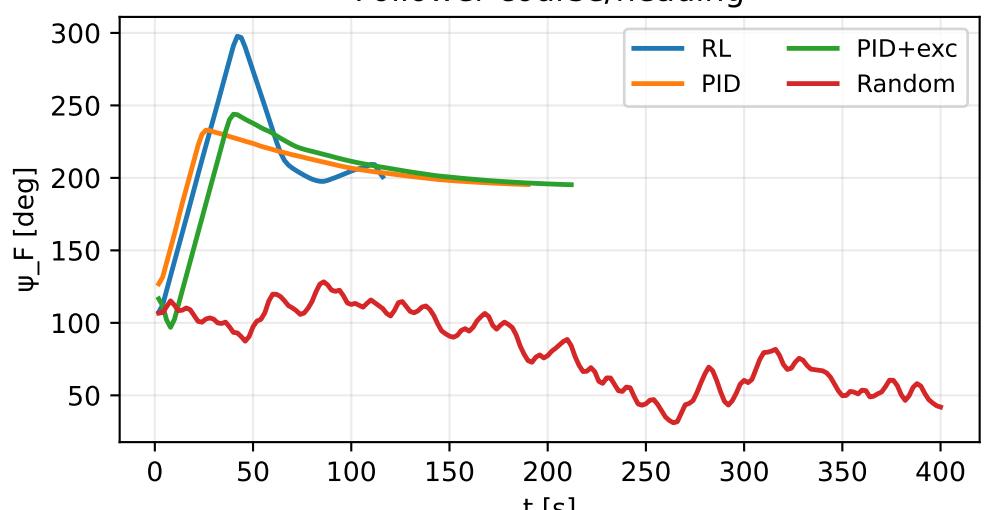
Information and excitation



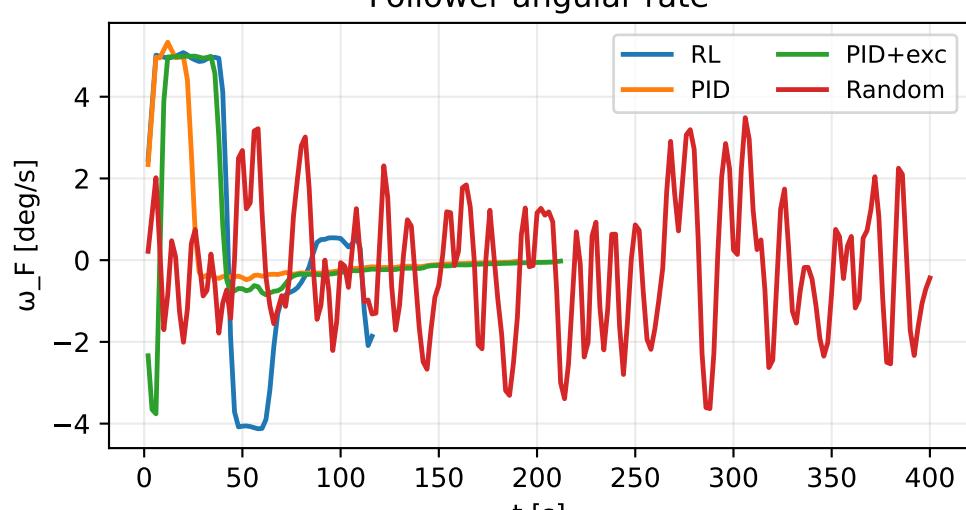
Follower speed



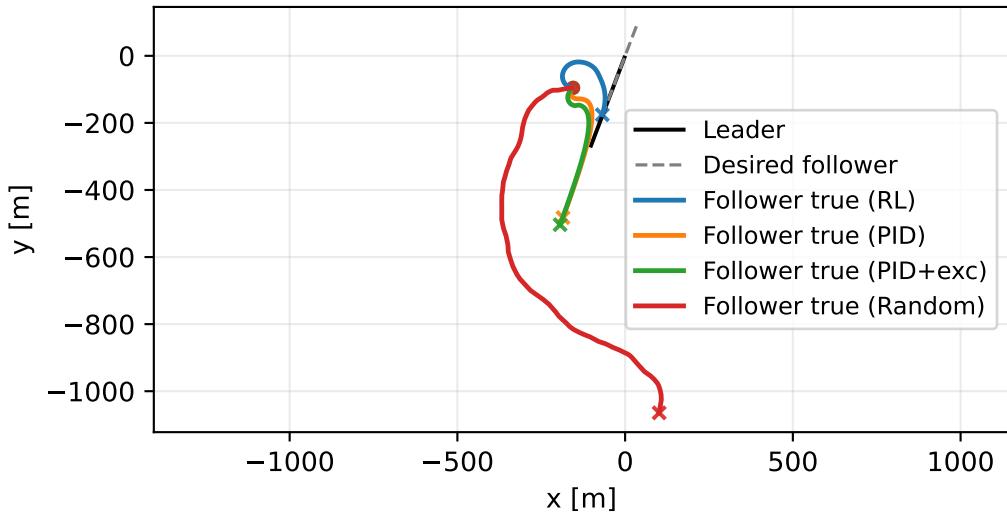
Follower course/heading



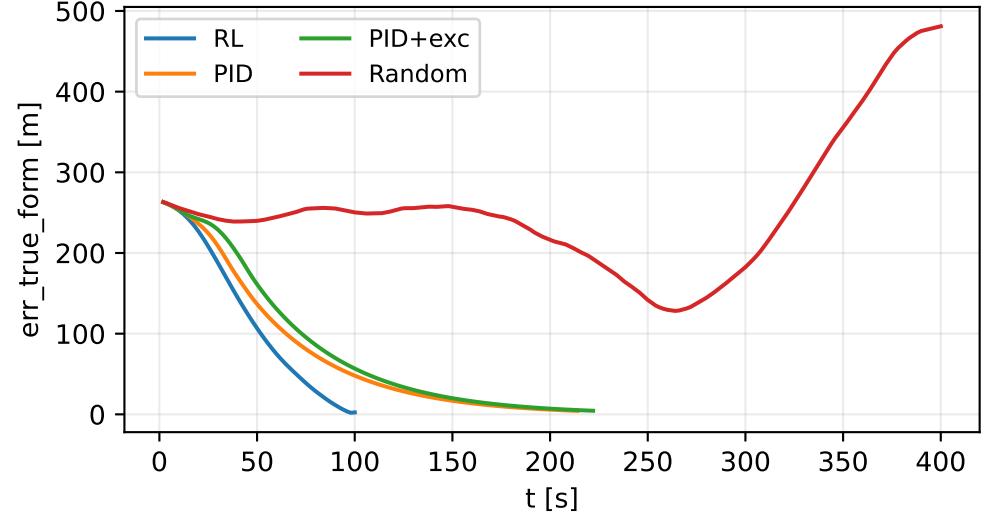
Follower angular rate



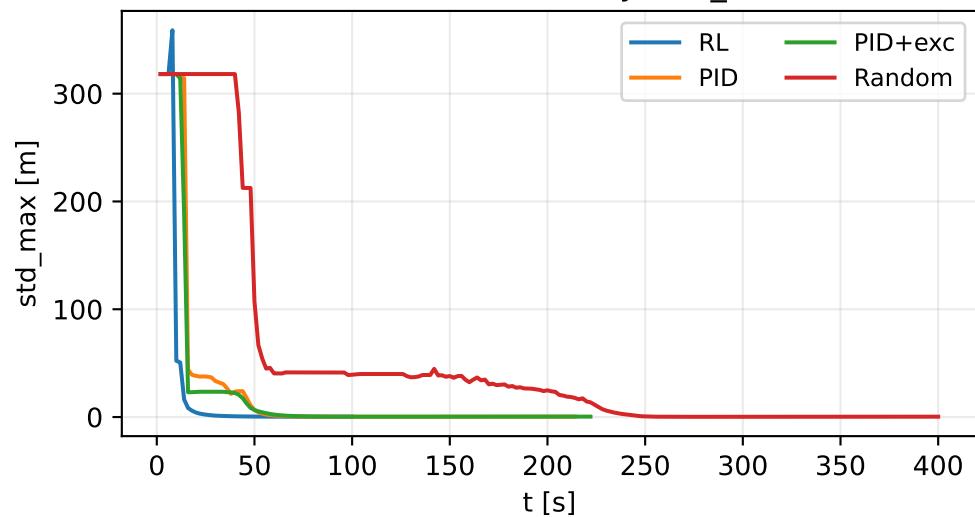
Trajectories (matched seed)



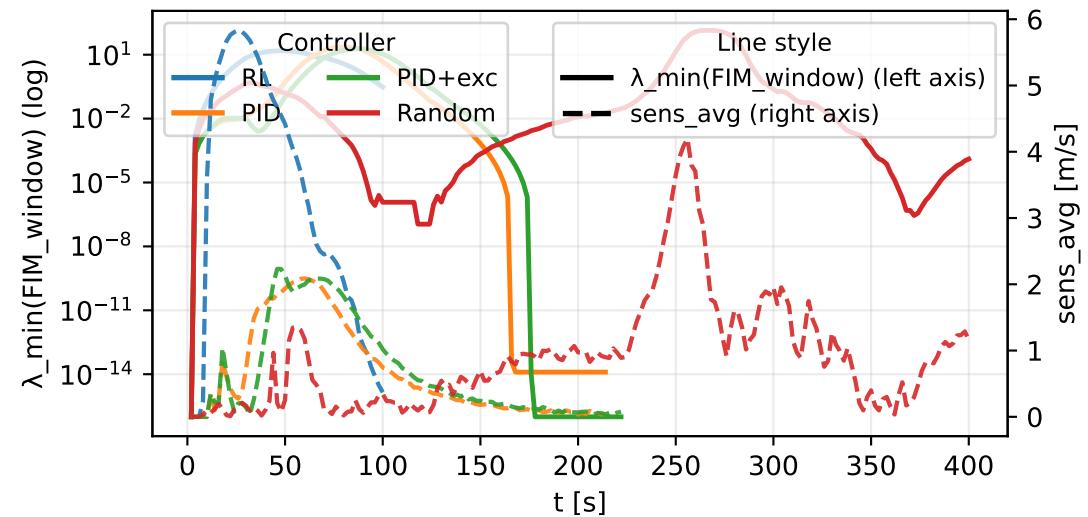
TRUE formation error



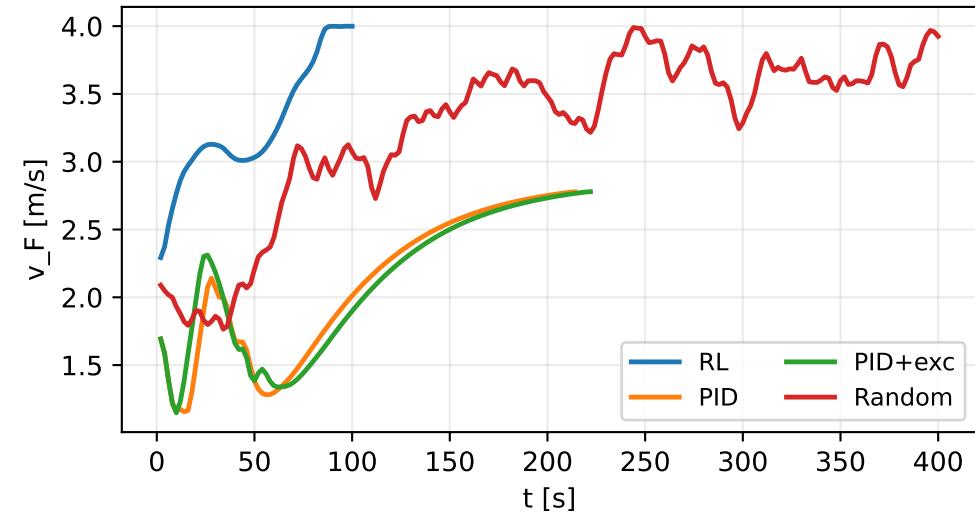
Estimator uncertainty (std_max)



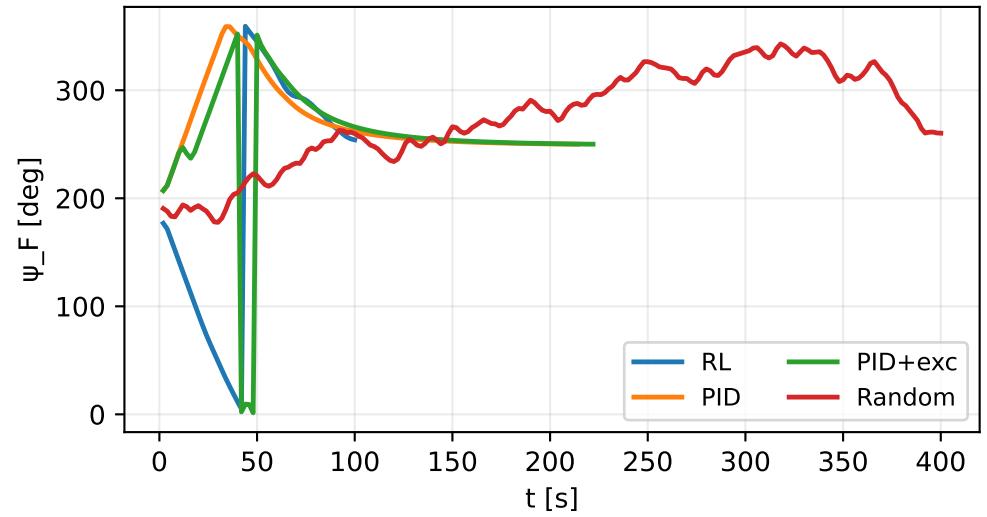
Information and excitation



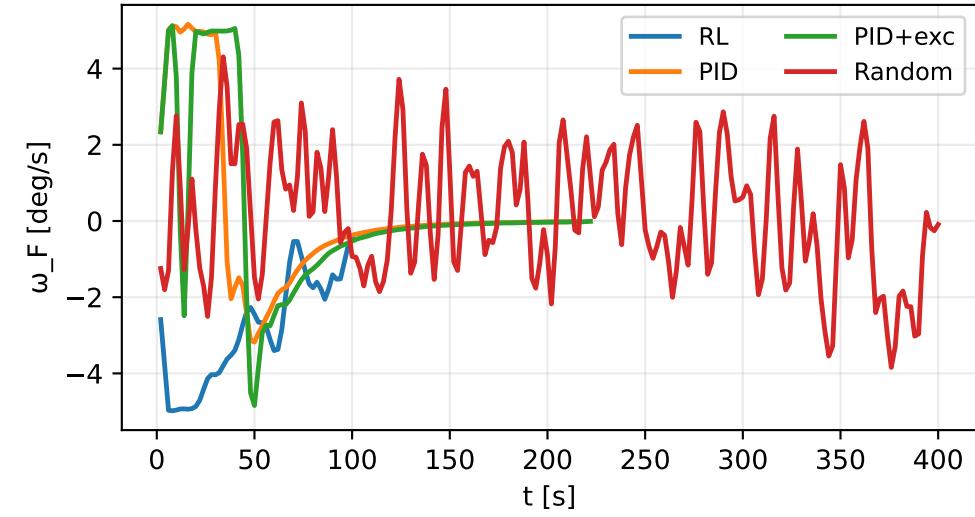
Follower speed



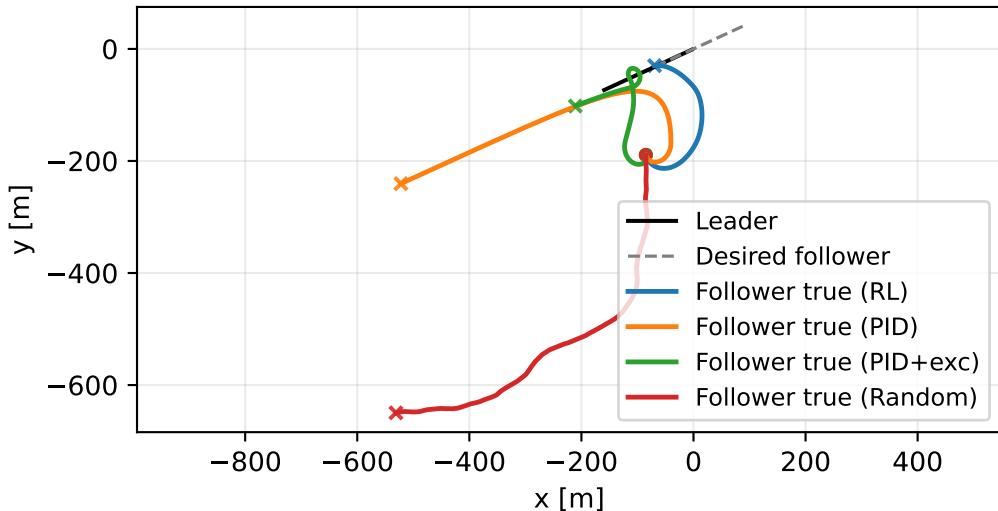
Follower course/heading



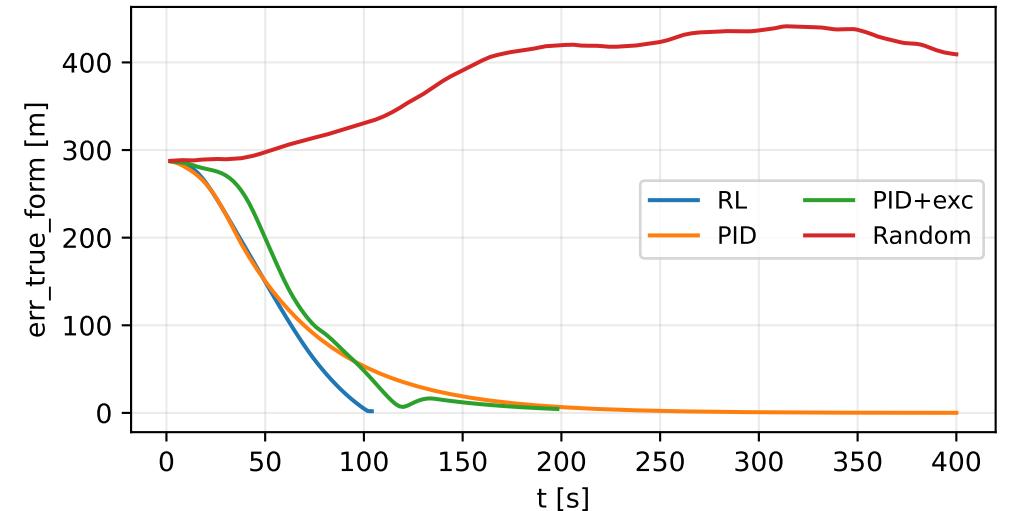
Follower angular rate



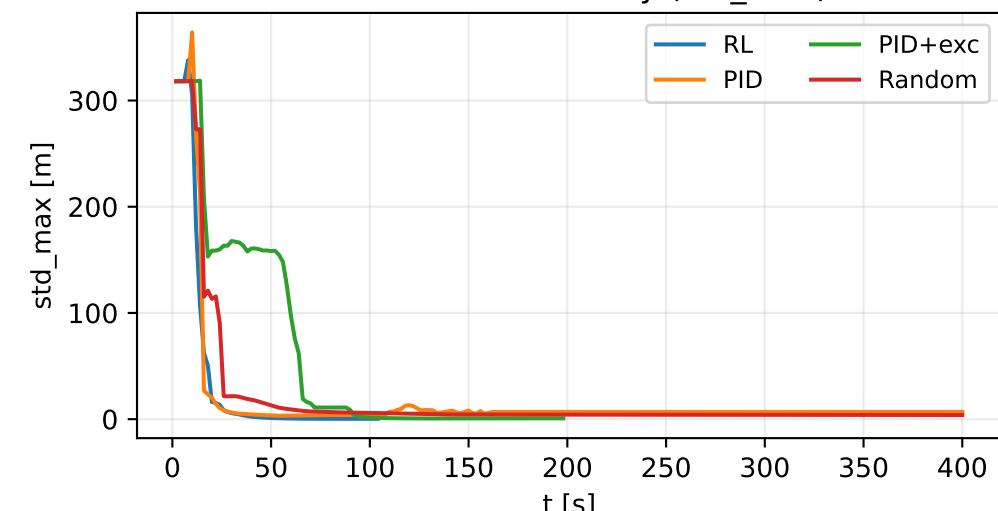
Trajectories (matched seed)



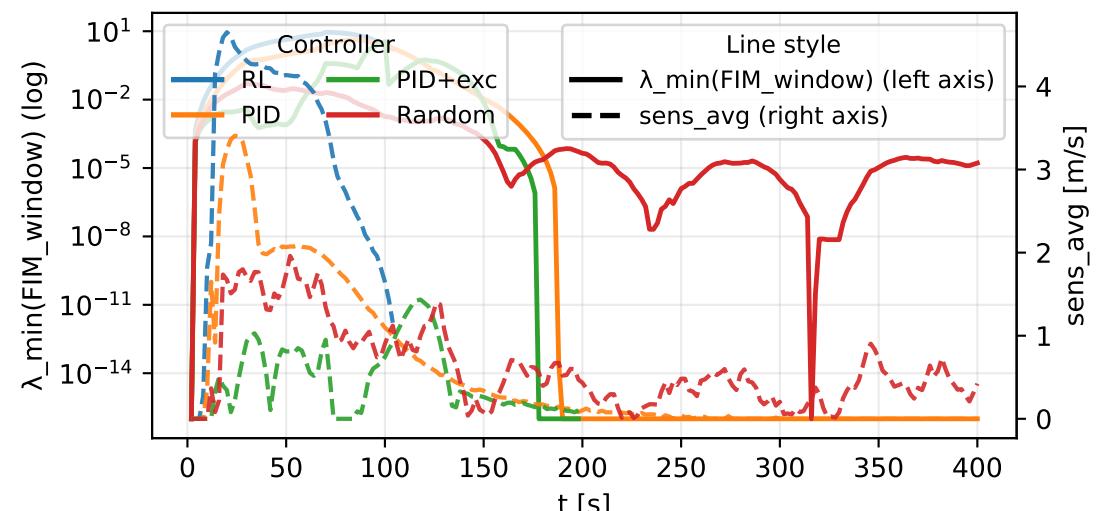
TRUE formation error



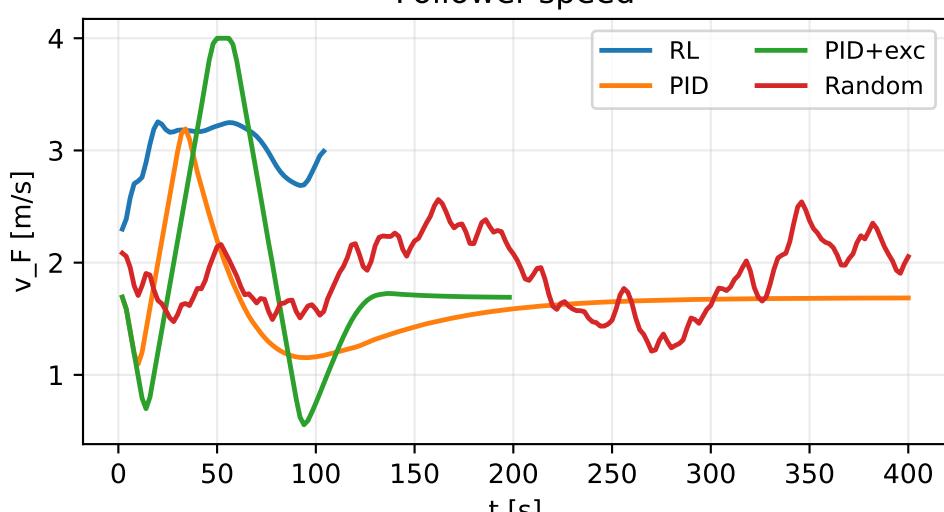
Estimator uncertainty (std_max)



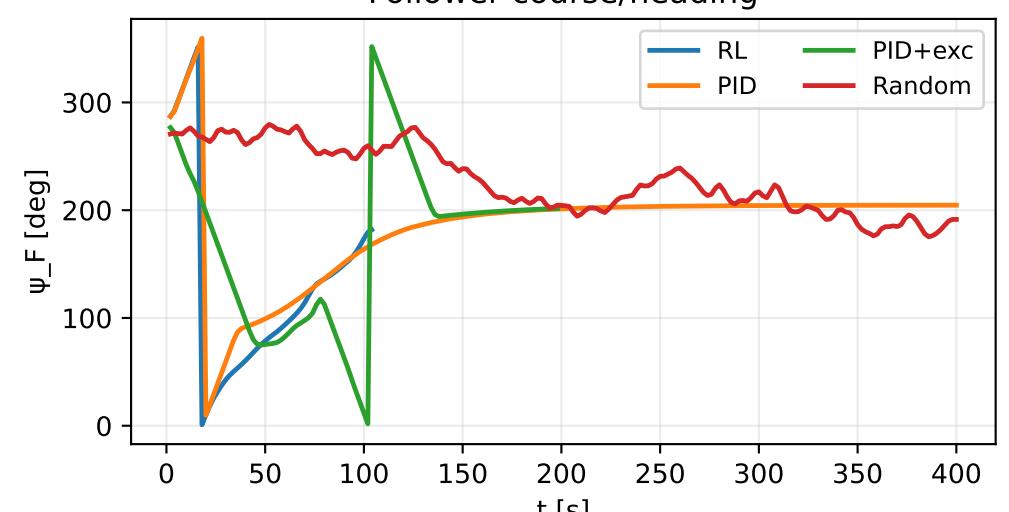
Information and excitation



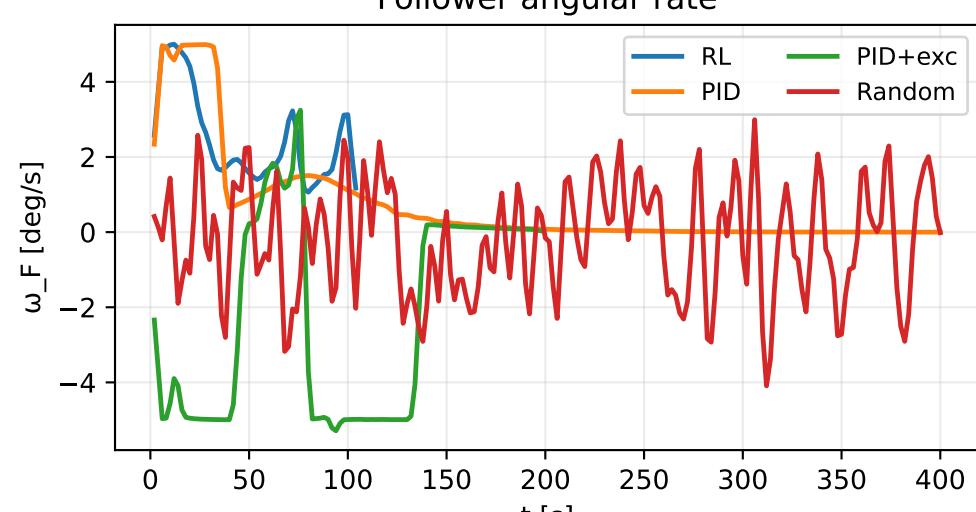
Follower speed



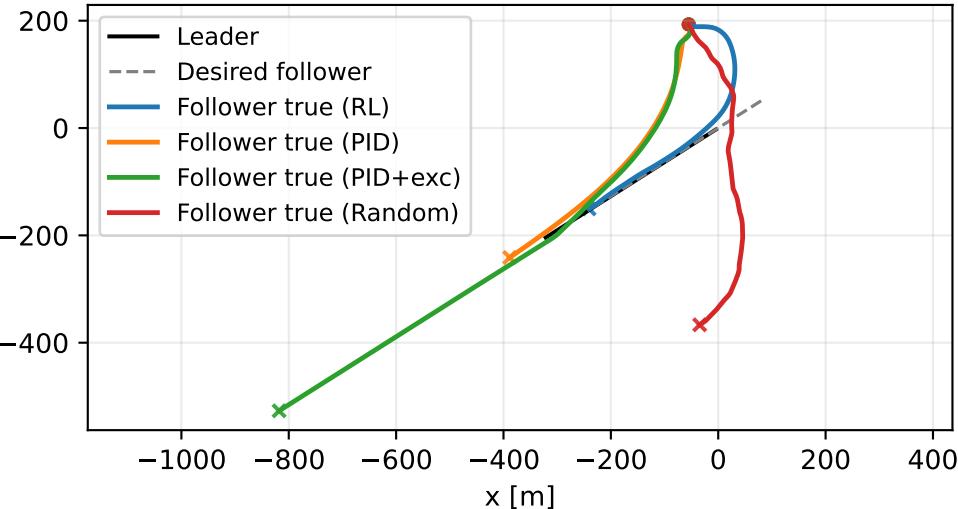
Follower course/heading



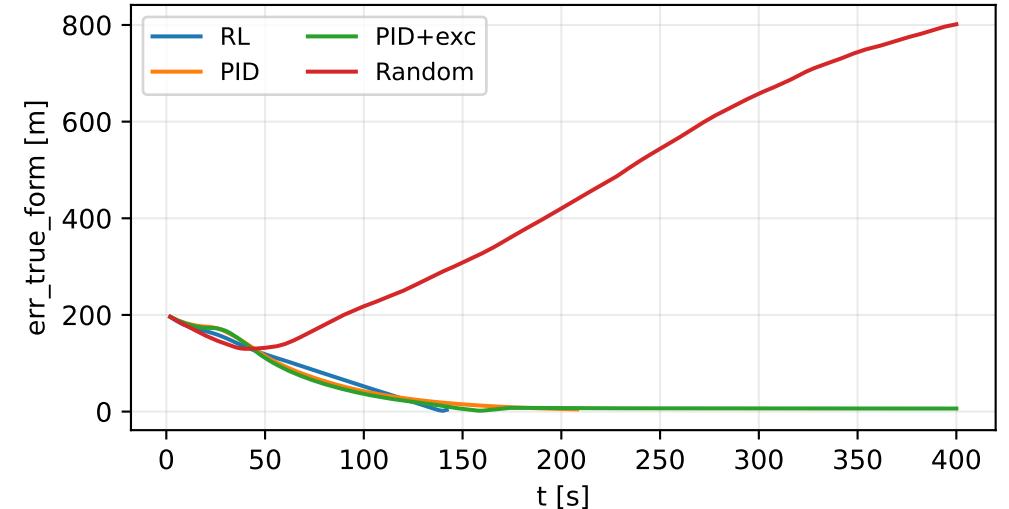
Follower angular rate



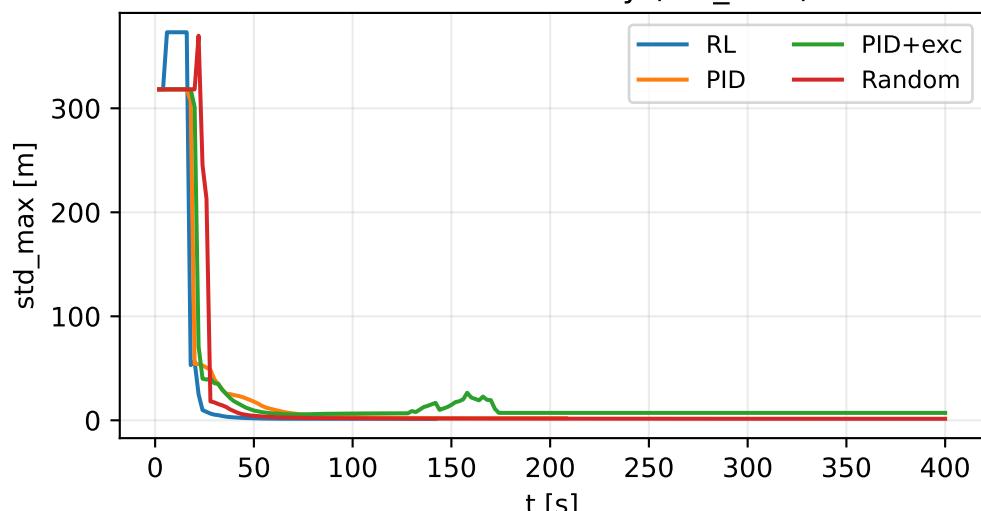
Trajectories (matched seed)



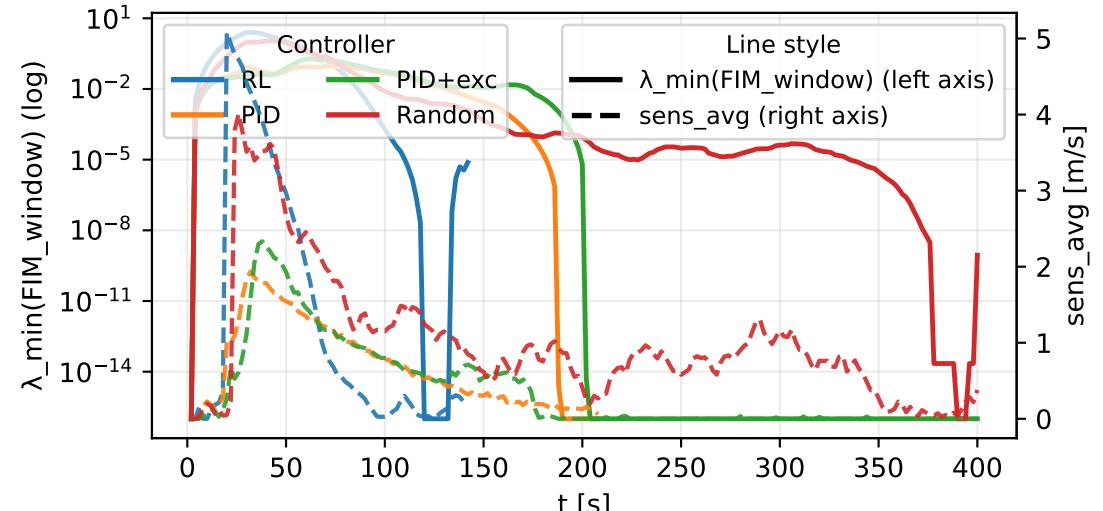
TRUE formation error



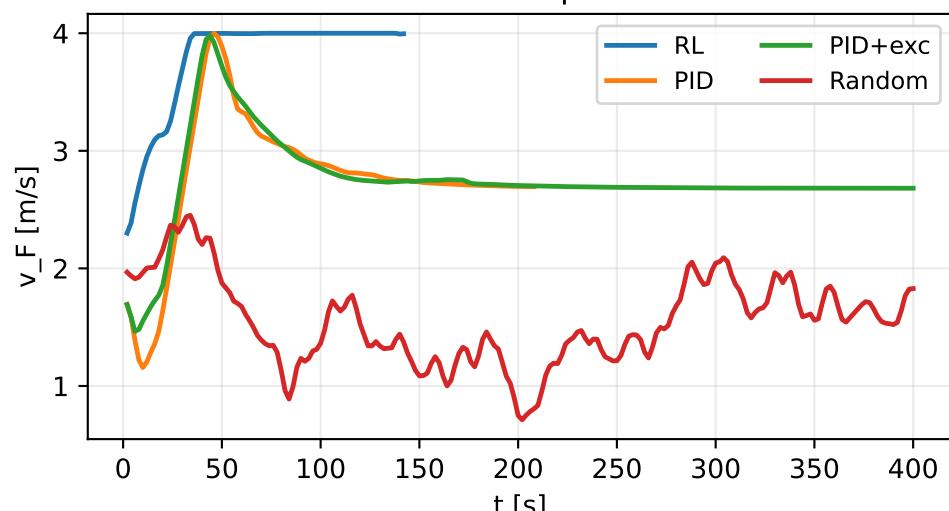
Estimator uncertainty (std_max)



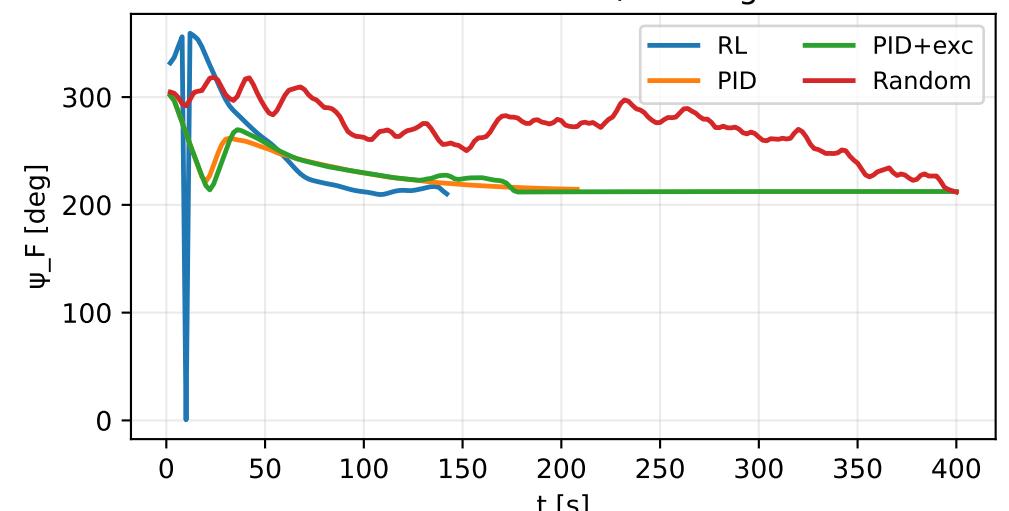
Information and excitation



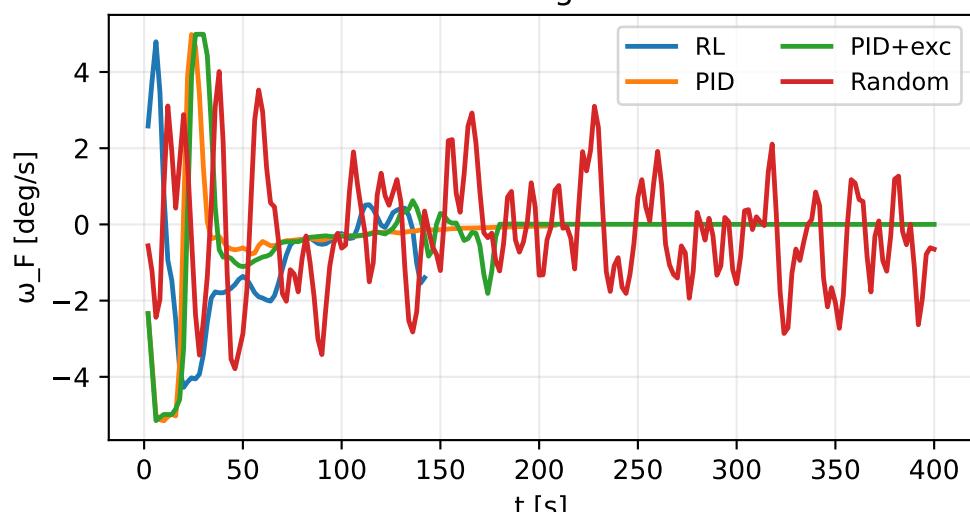
Follower speed



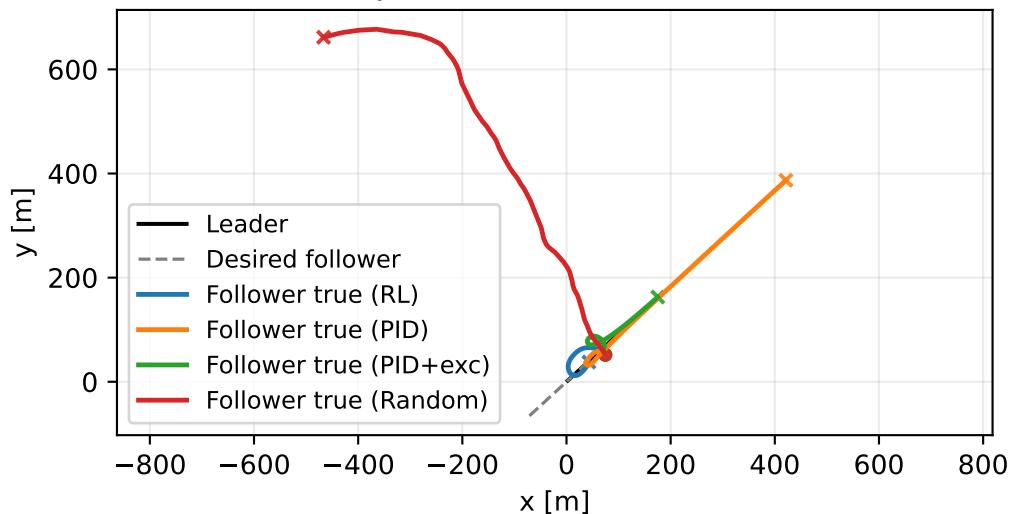
Follower course/heading



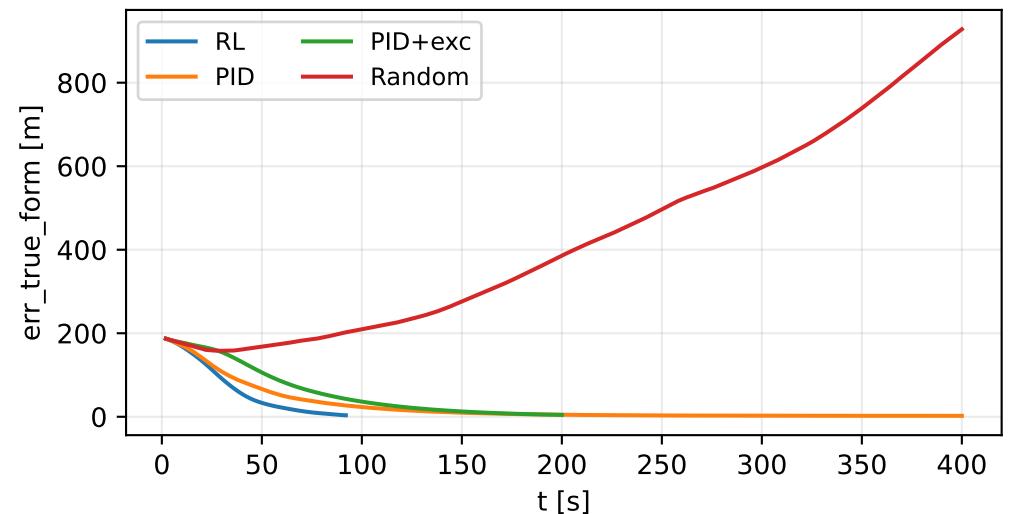
Follower angular rate



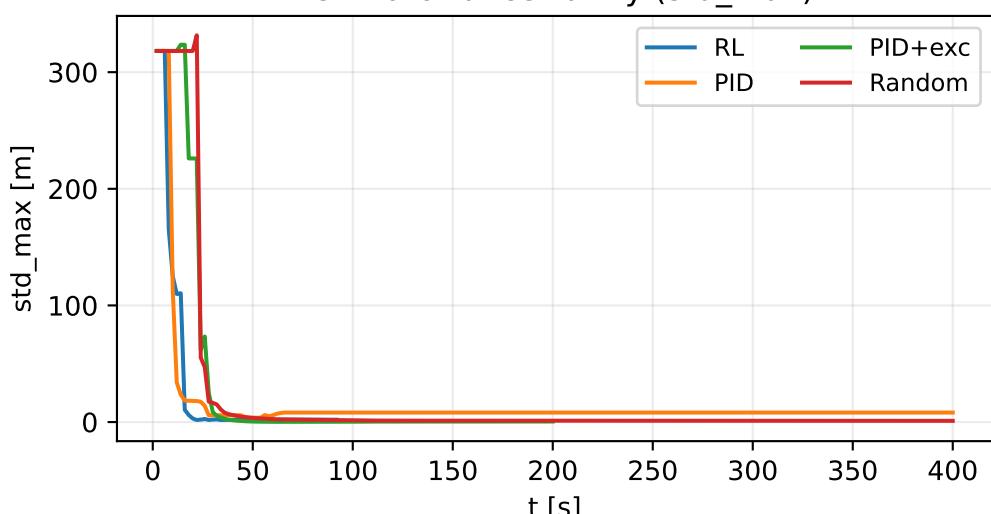
Trajectories (matched seed)



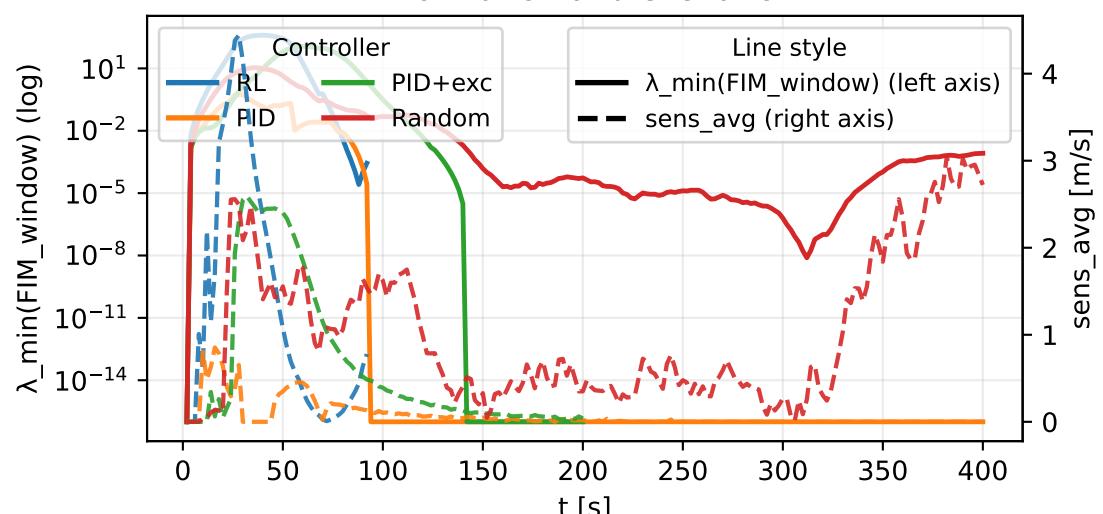
TRUE formation error



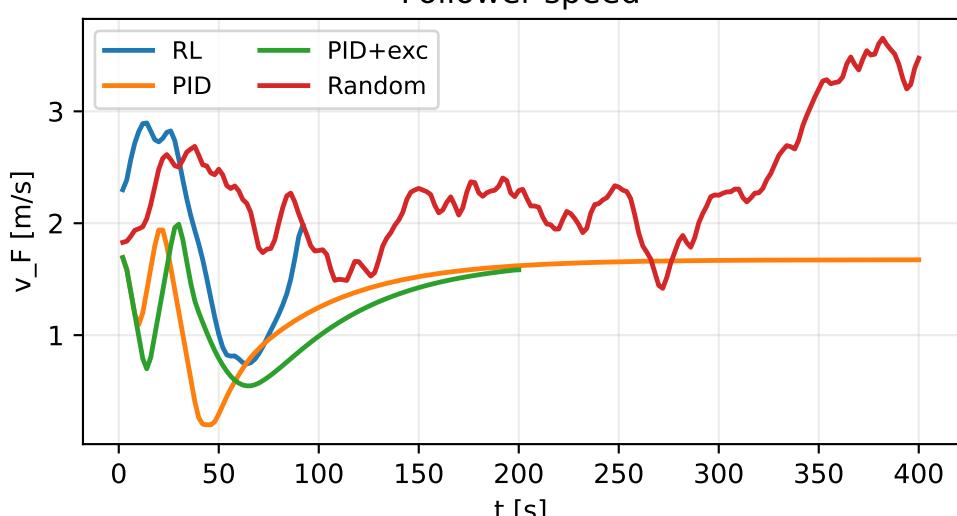
Estimator uncertainty (std_max)



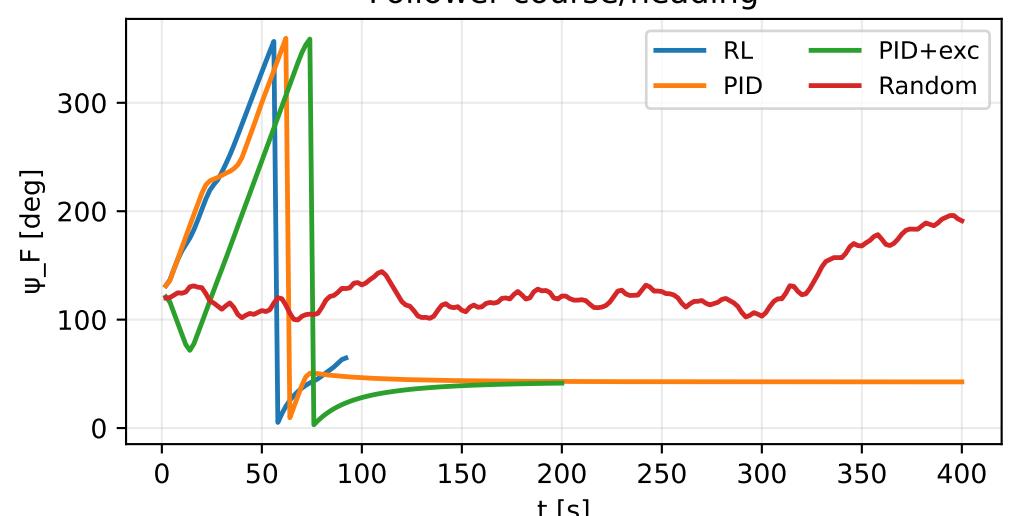
Information and excitation



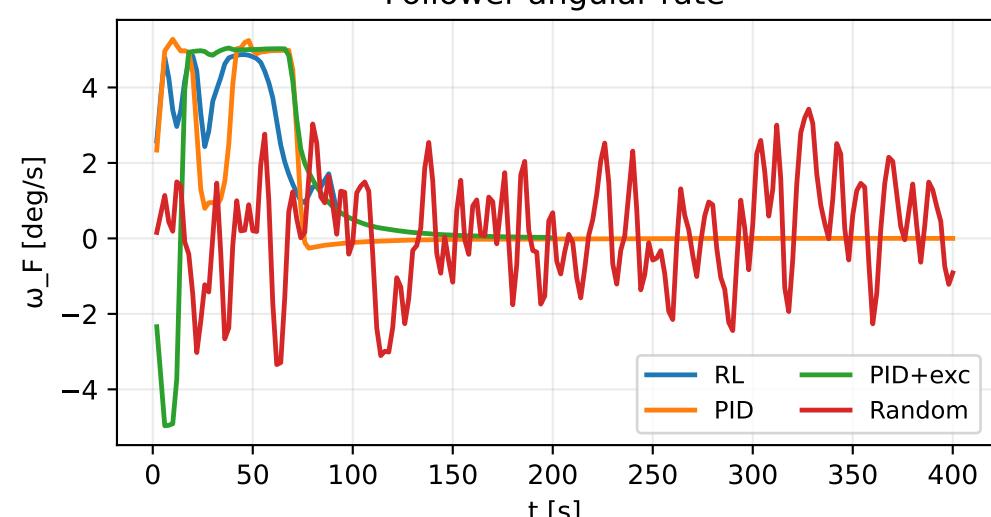
Follower speed



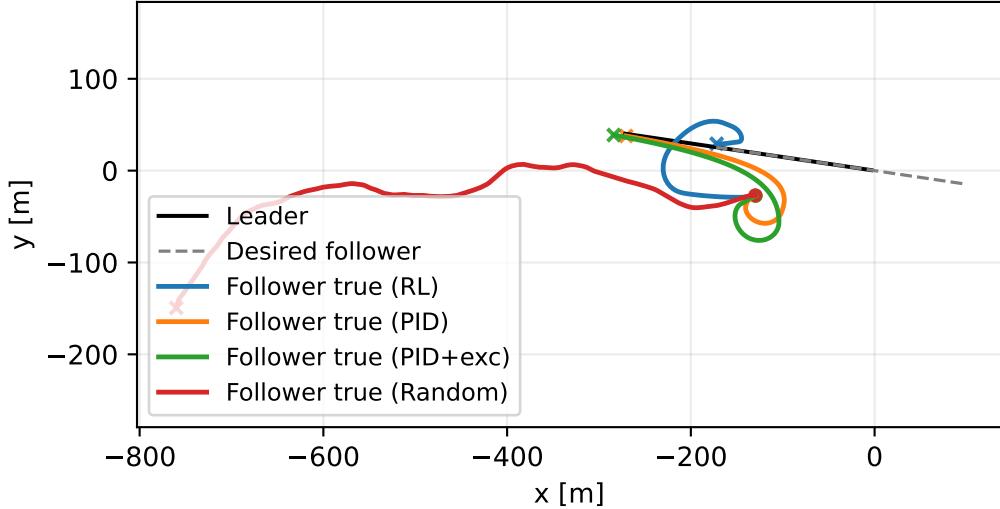
Follower course/heading



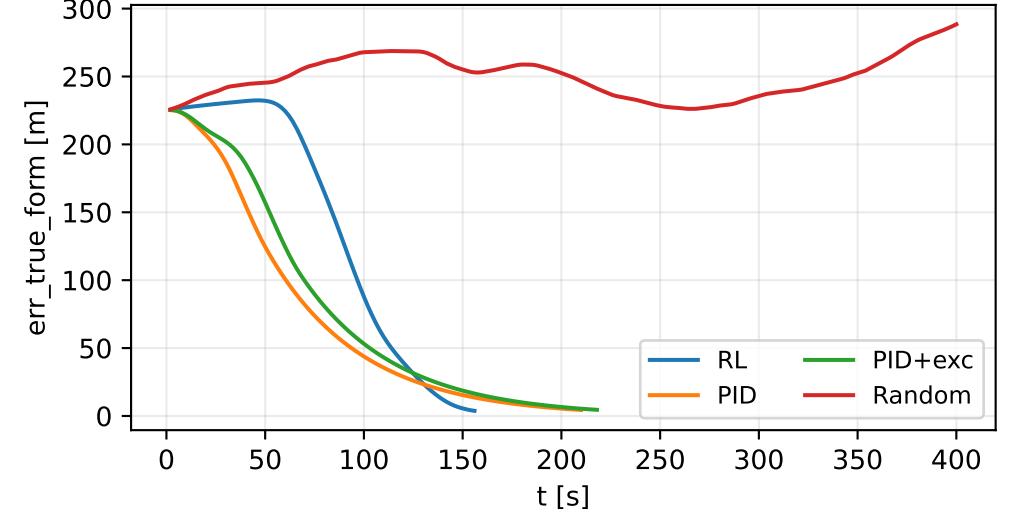
Follower angular rate



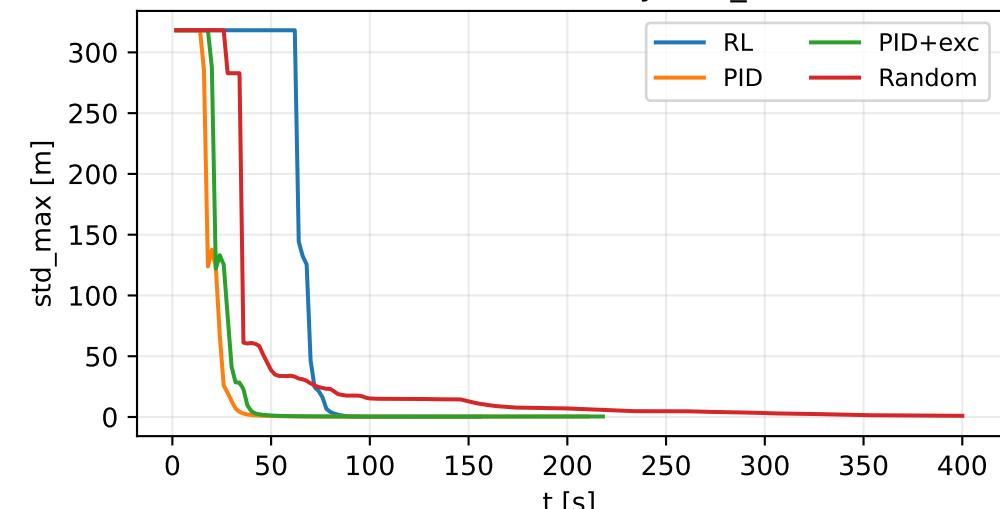
Trajectories (matched seed)



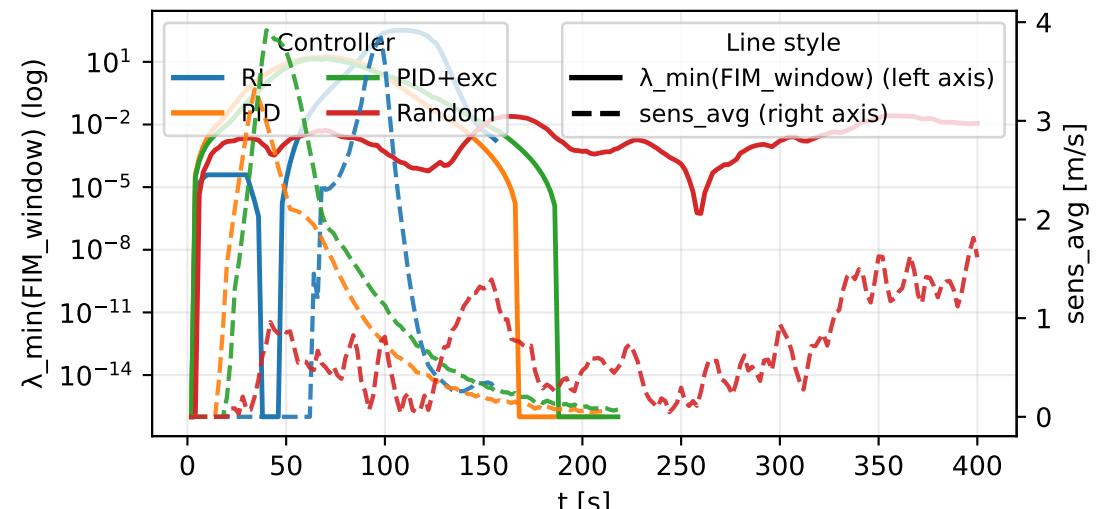
TRUE formation error



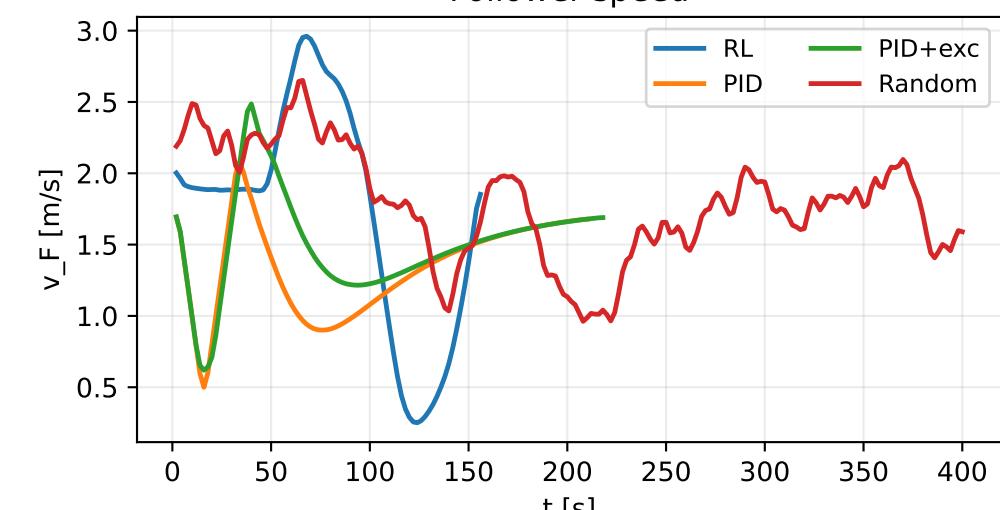
Estimator uncertainty (std_max)



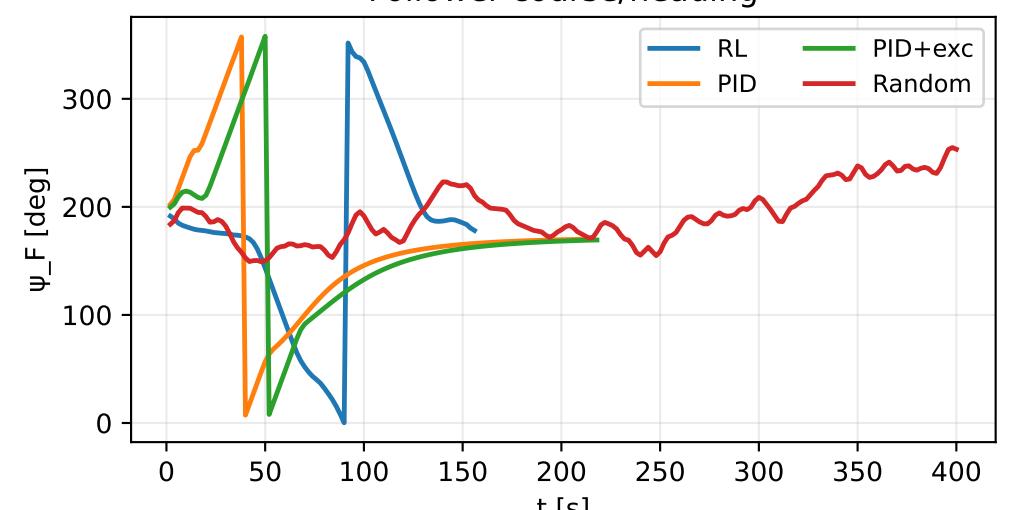
Information and excitation



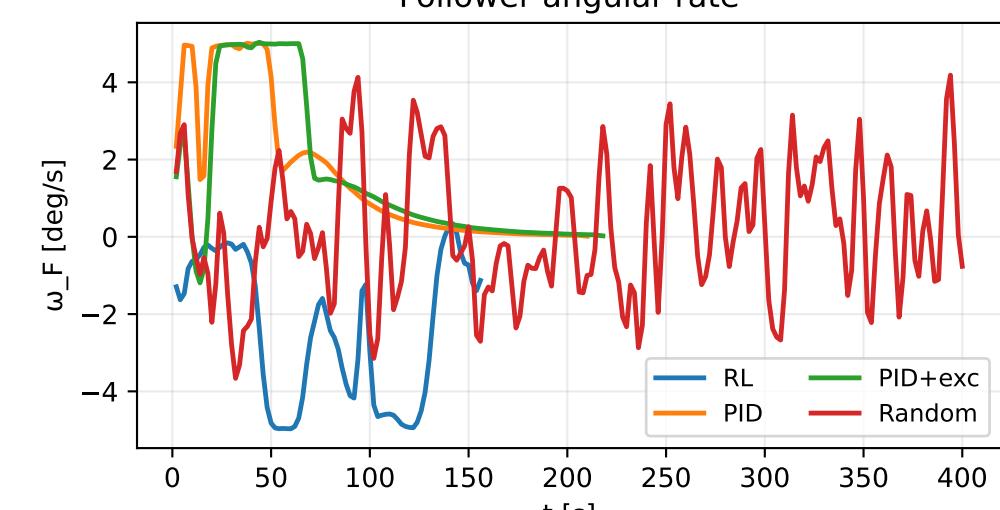
Follower speed



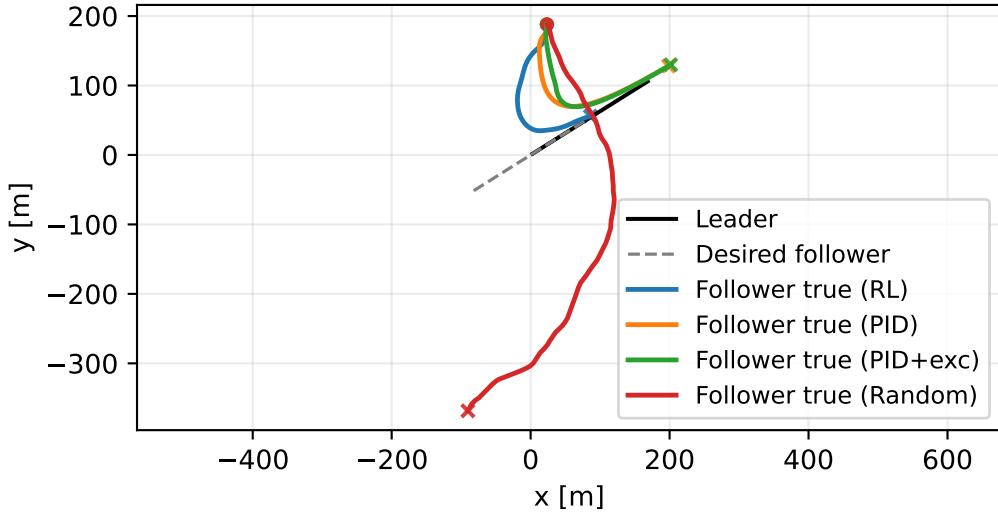
Follower course/heading



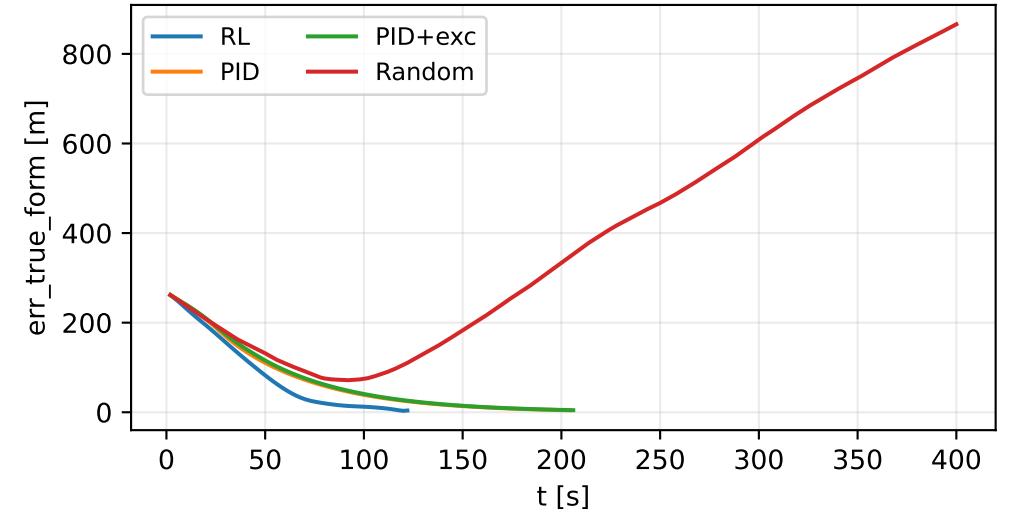
Follower angular rate



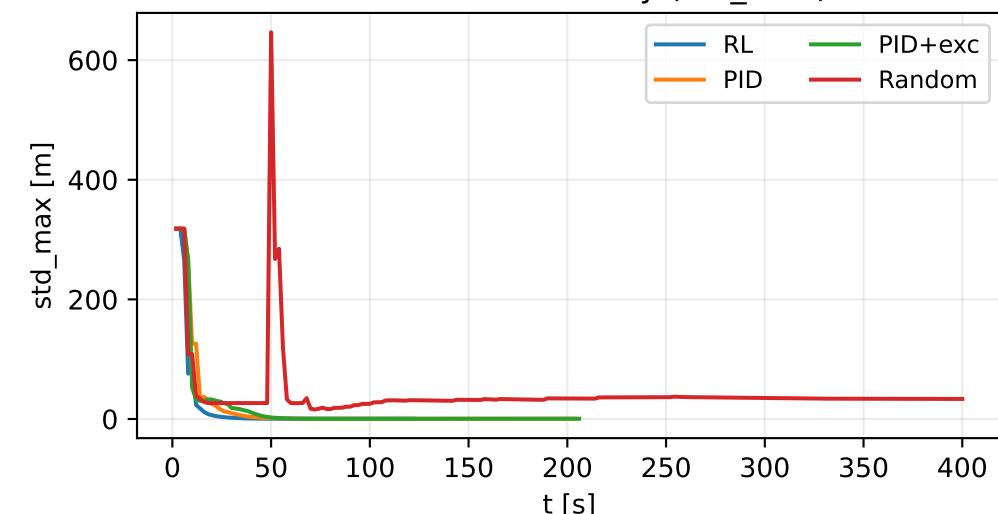
Trajectories (matched seed)



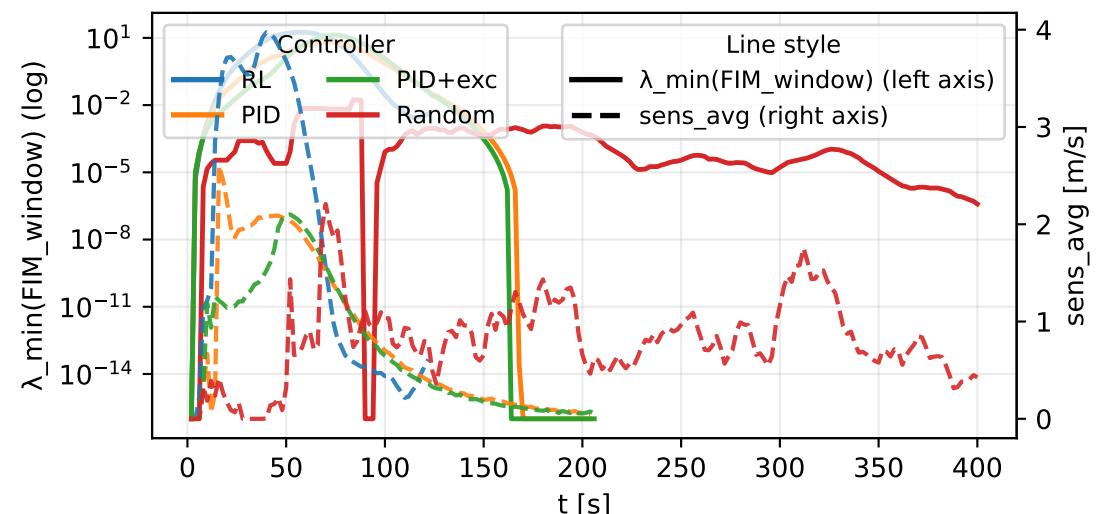
TRUE formation error



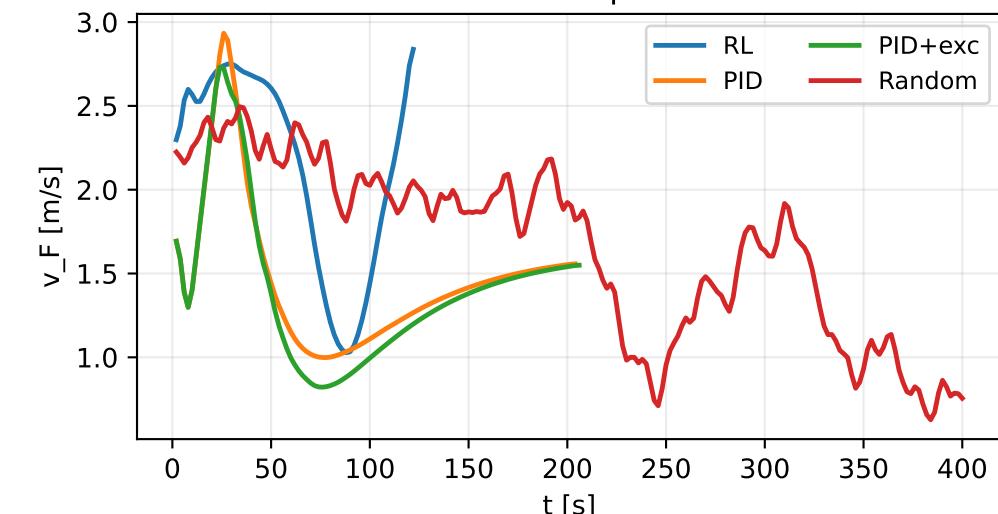
Estimator uncertainty (std_max)



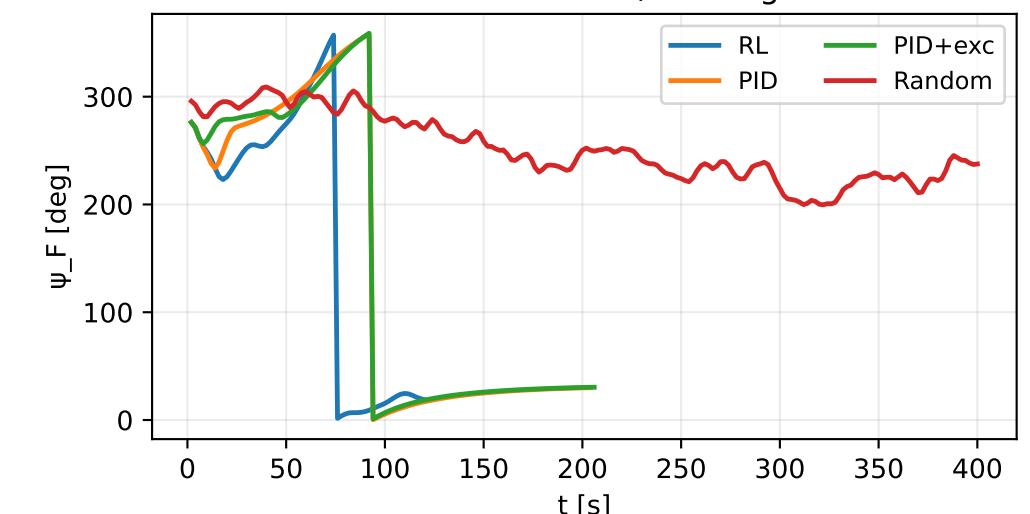
Information and excitation



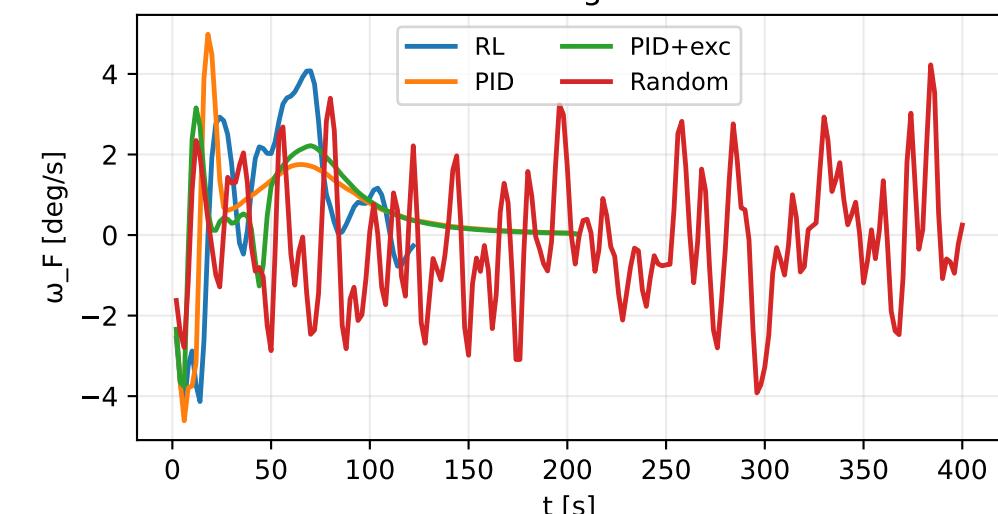
Follower speed



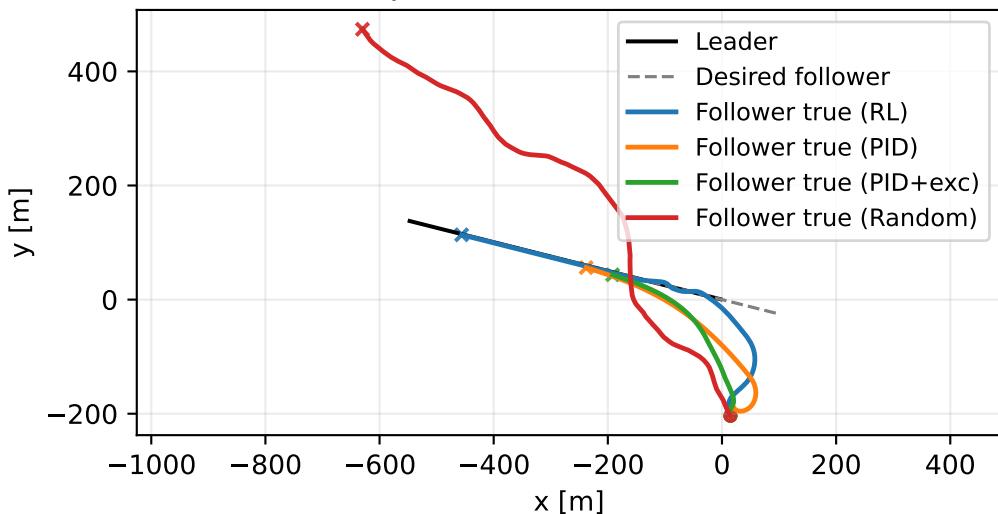
Follower course/heading



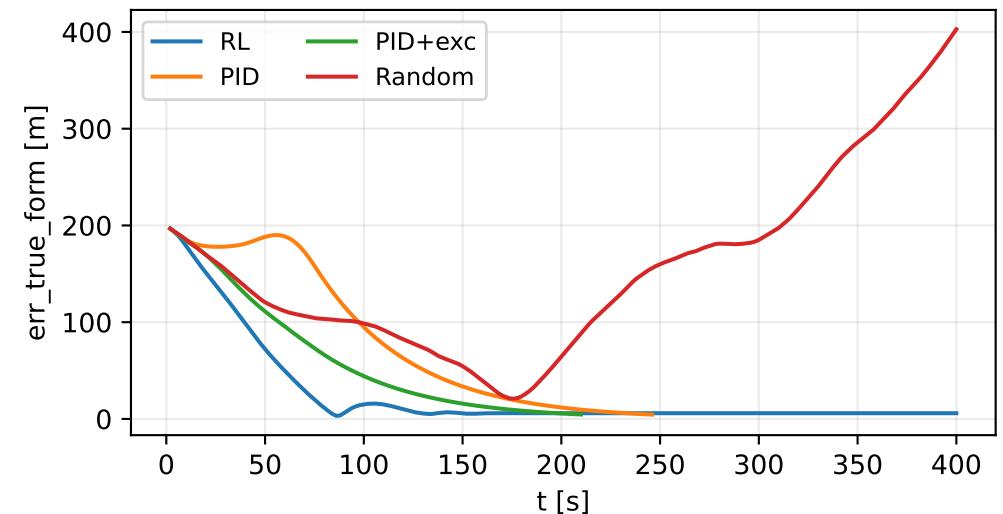
Follower angular rate



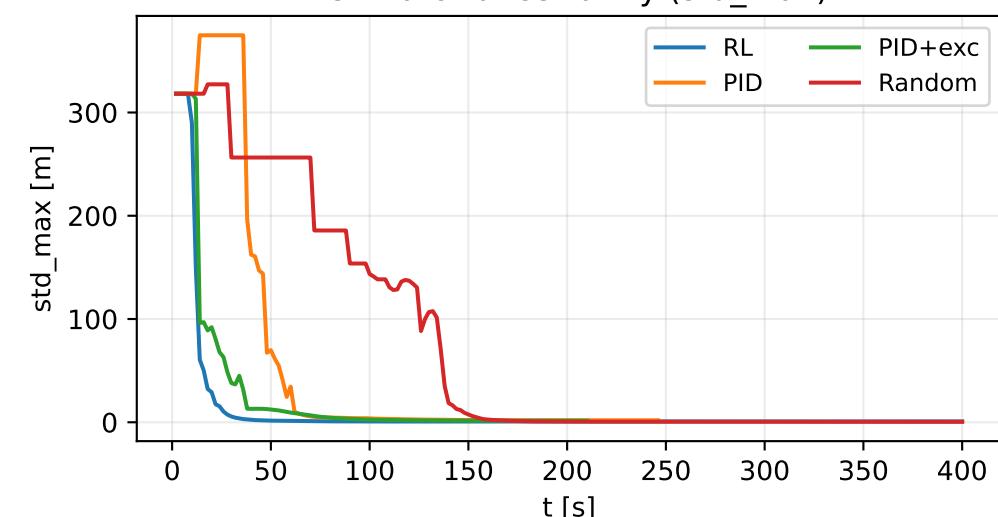
Trajectories (matched seed)



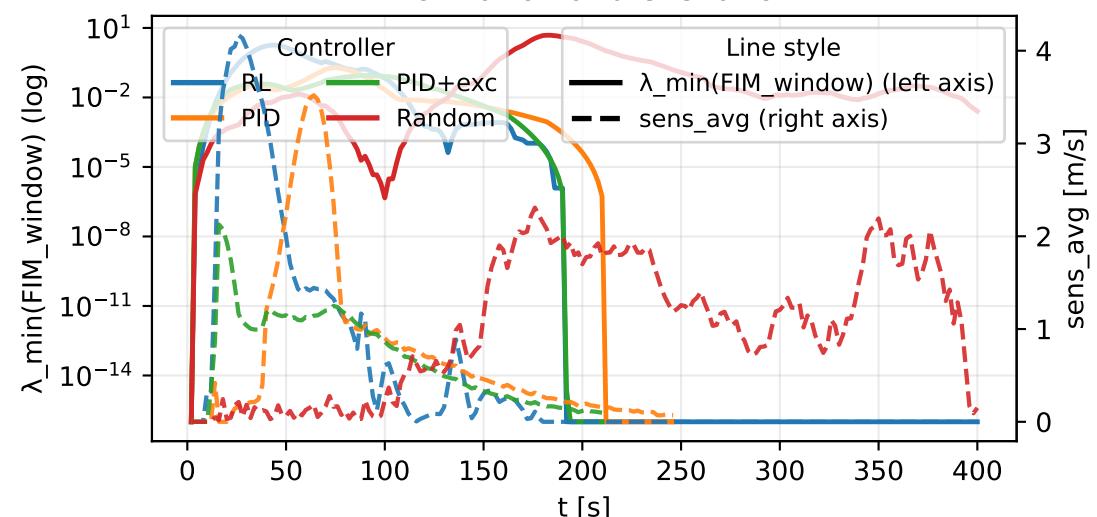
TRUE formation error



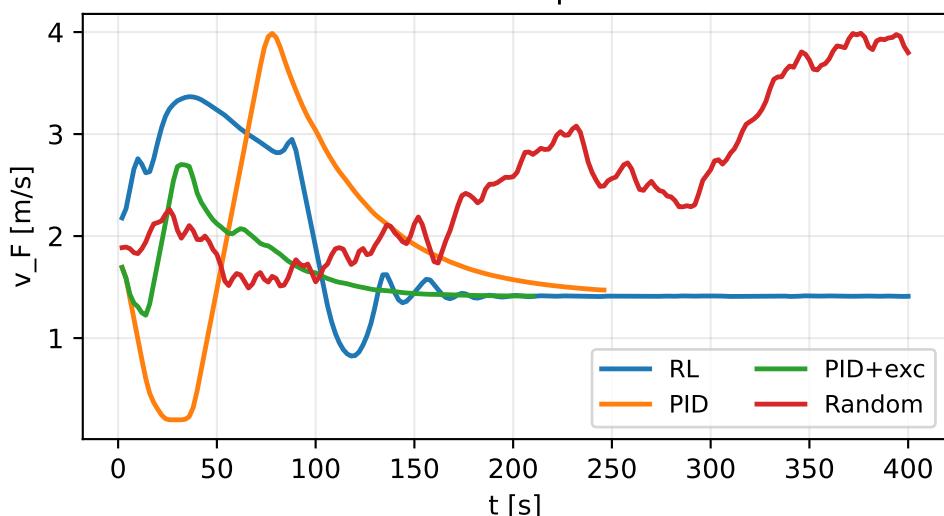
Estimator uncertainty (std_max)



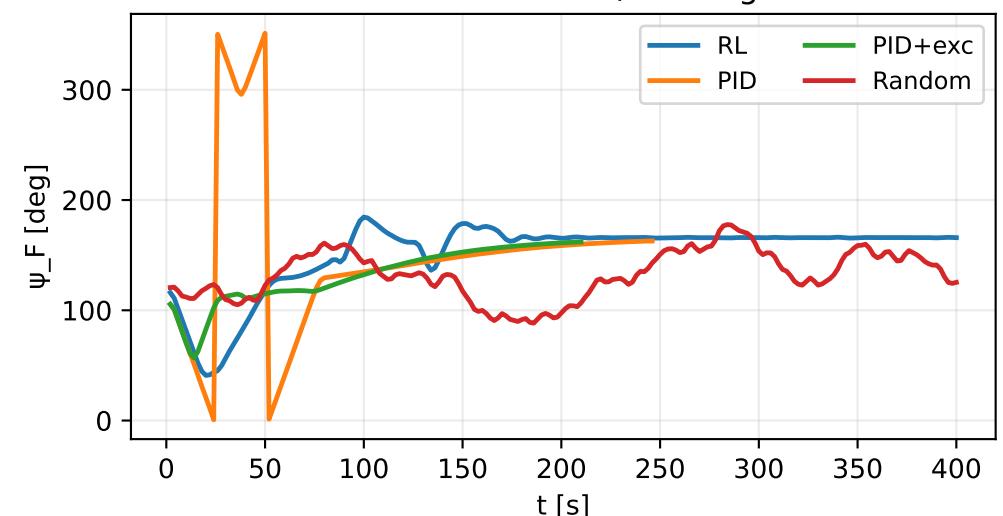
Information and excitation



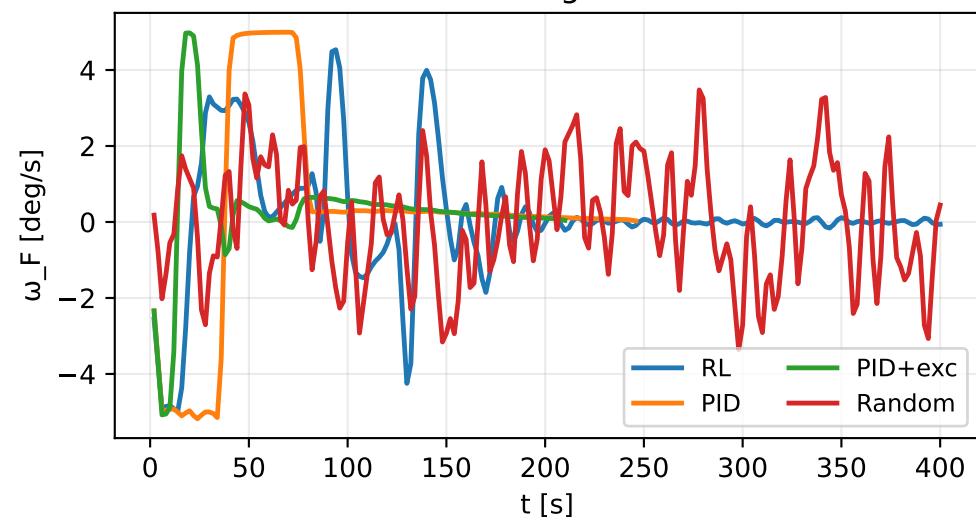
Follower speed



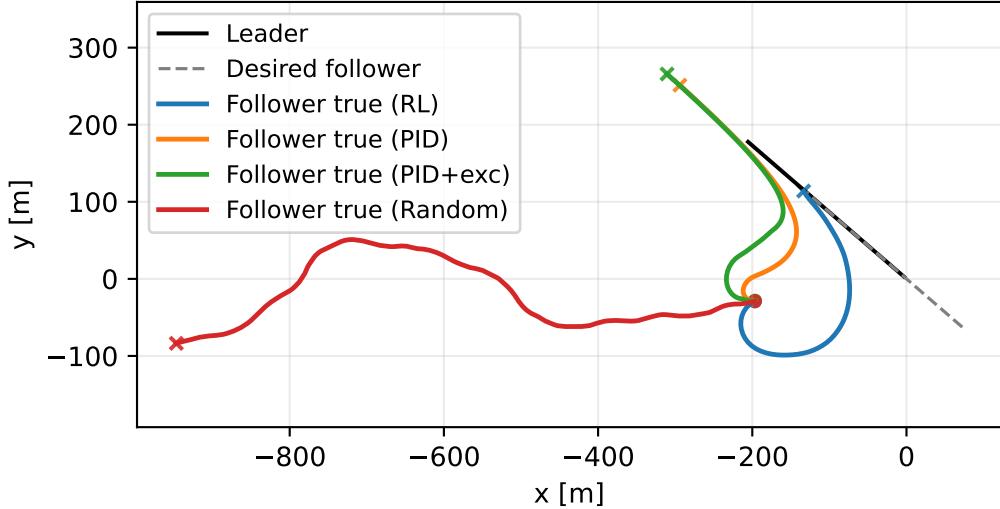
Follower course/heading



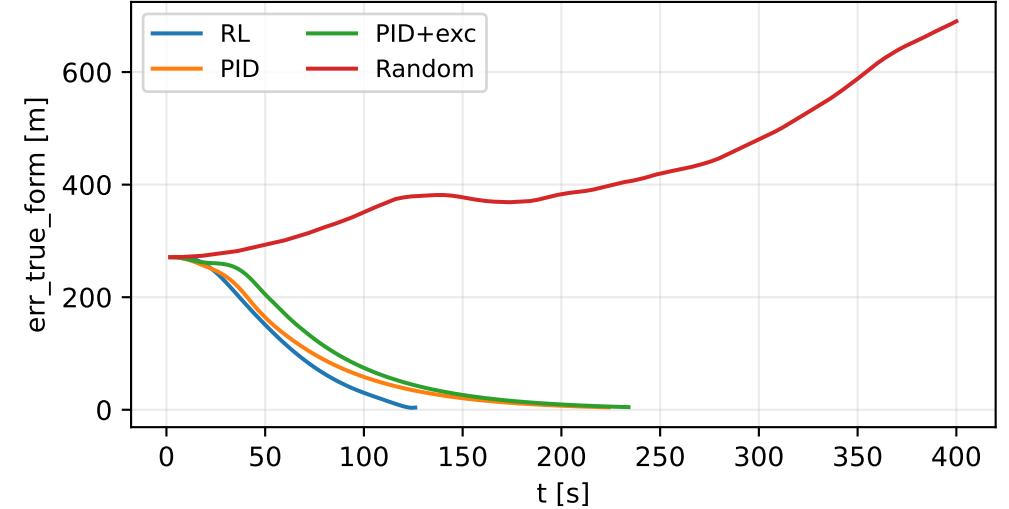
Follower angular rate



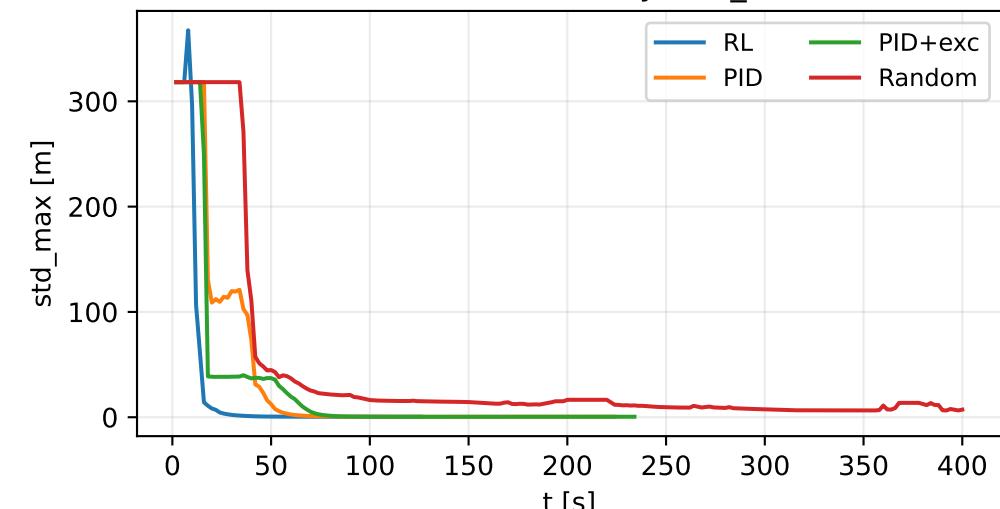
Trajectories (matched seed)



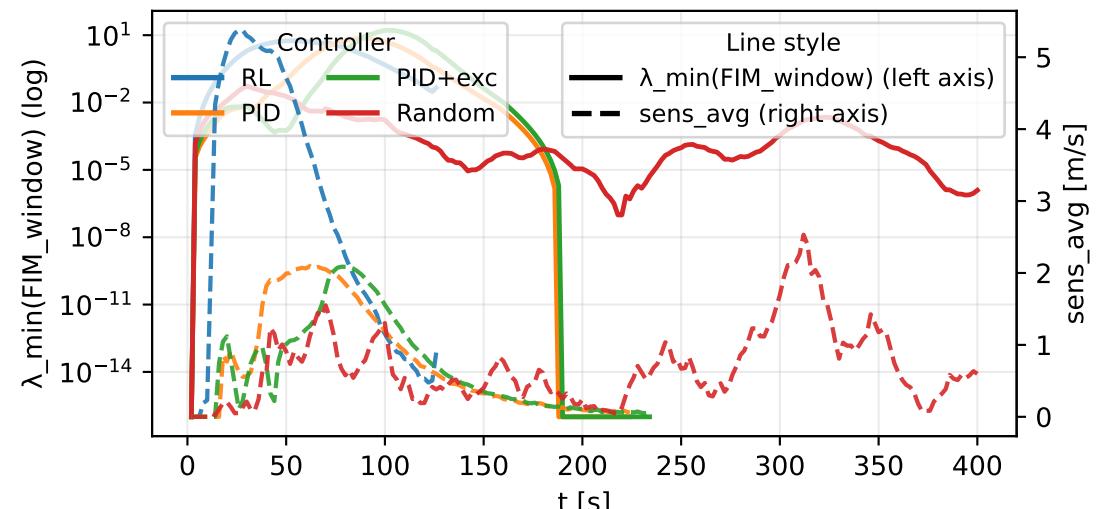
TRUE formation error



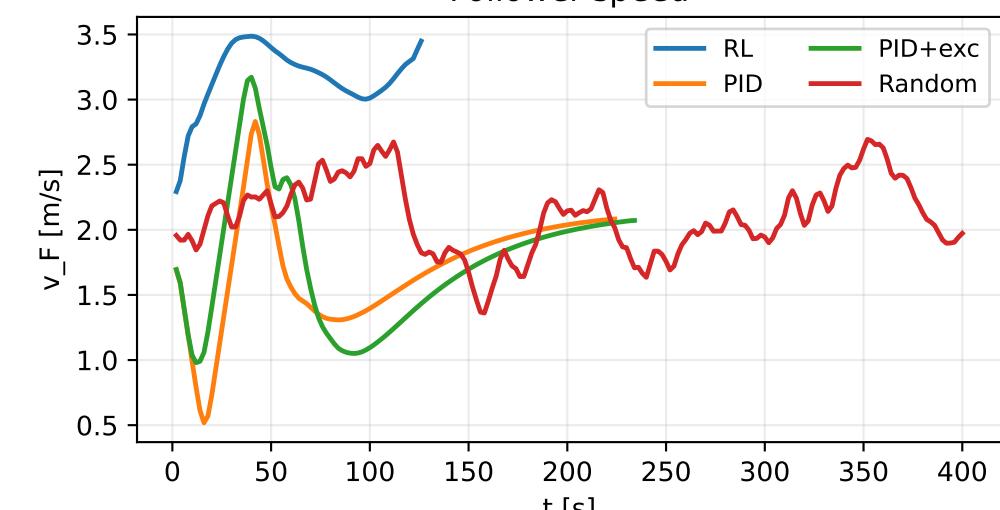
Estimator uncertainty (std_max)



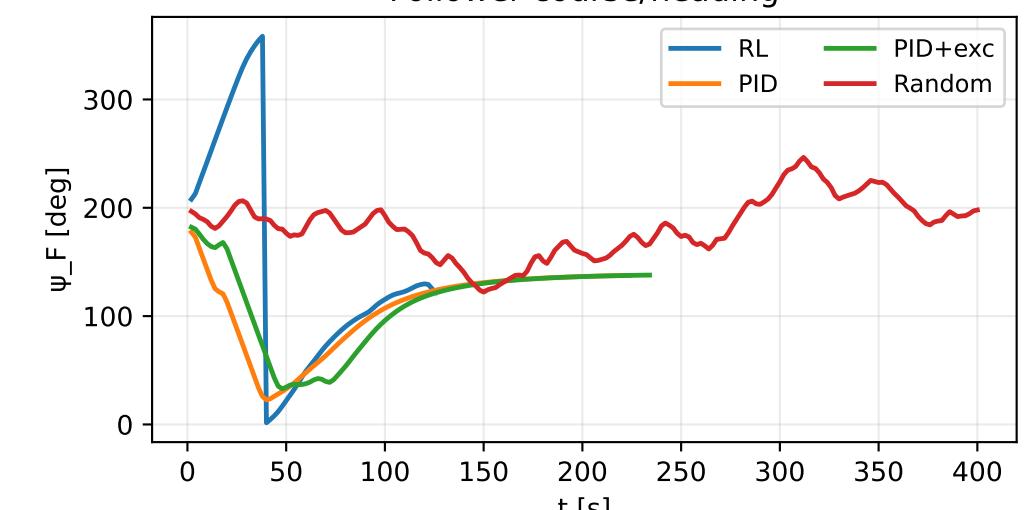
Information and excitation



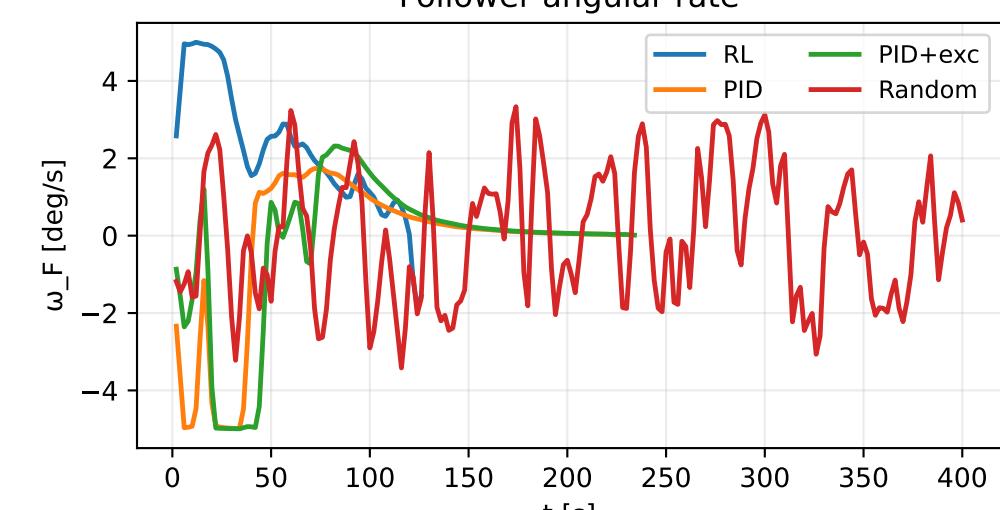
Follower speed



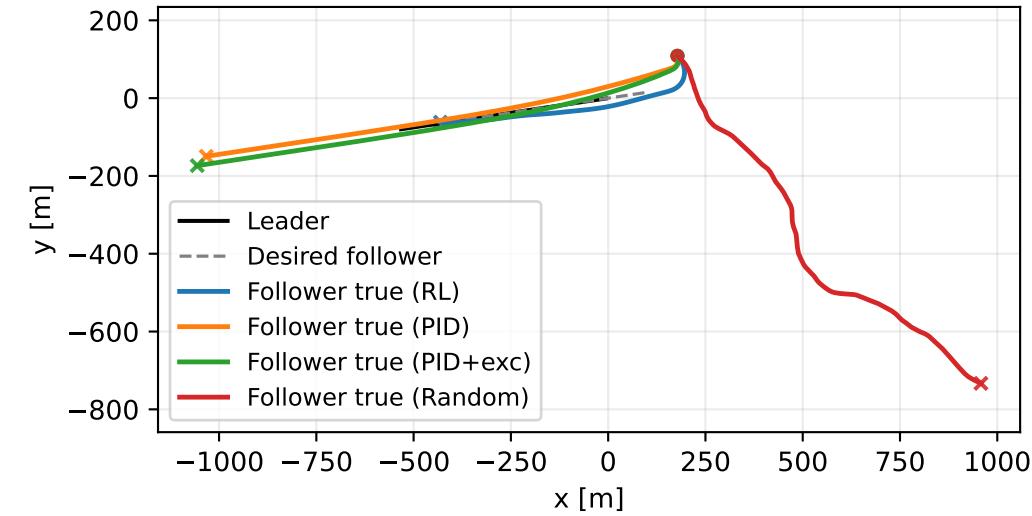
Follower course/heading



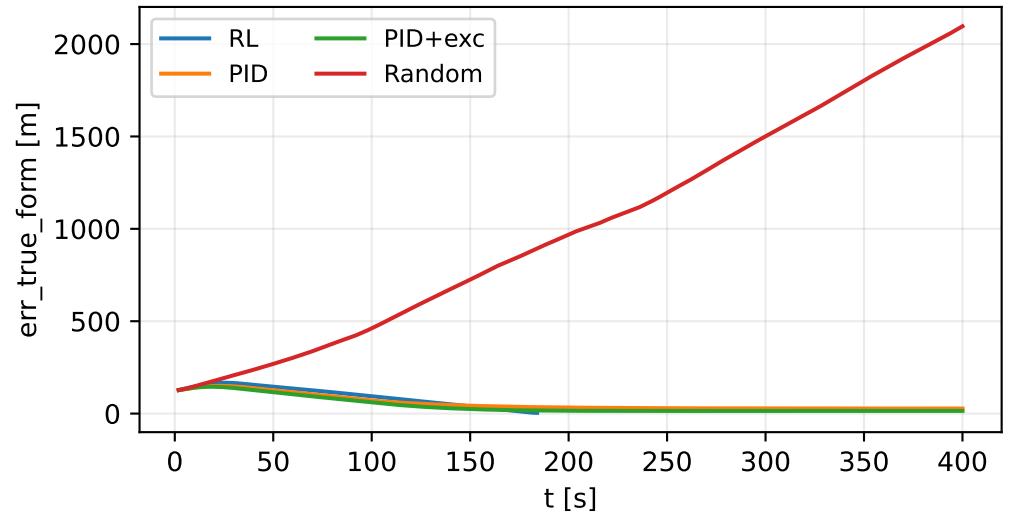
Follower angular rate



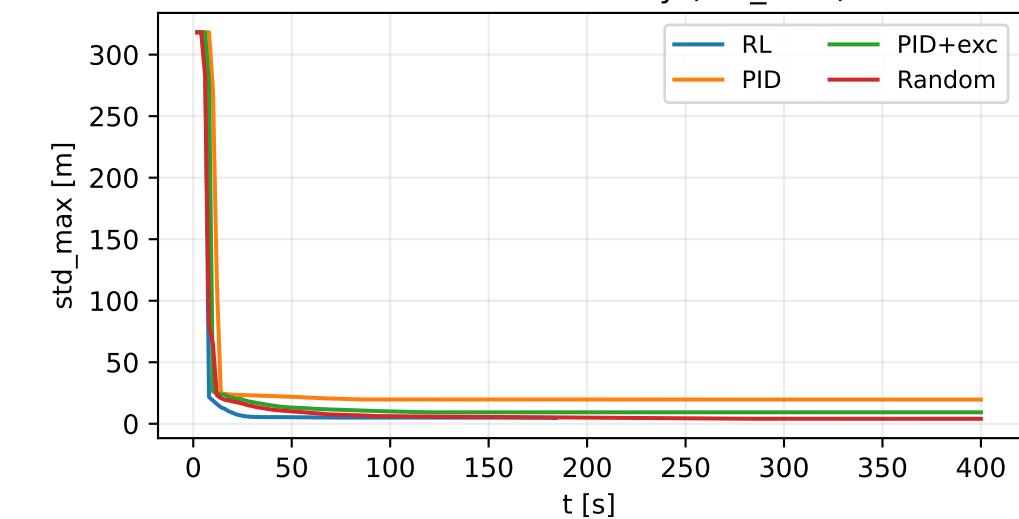
Trajectories (matched seed)



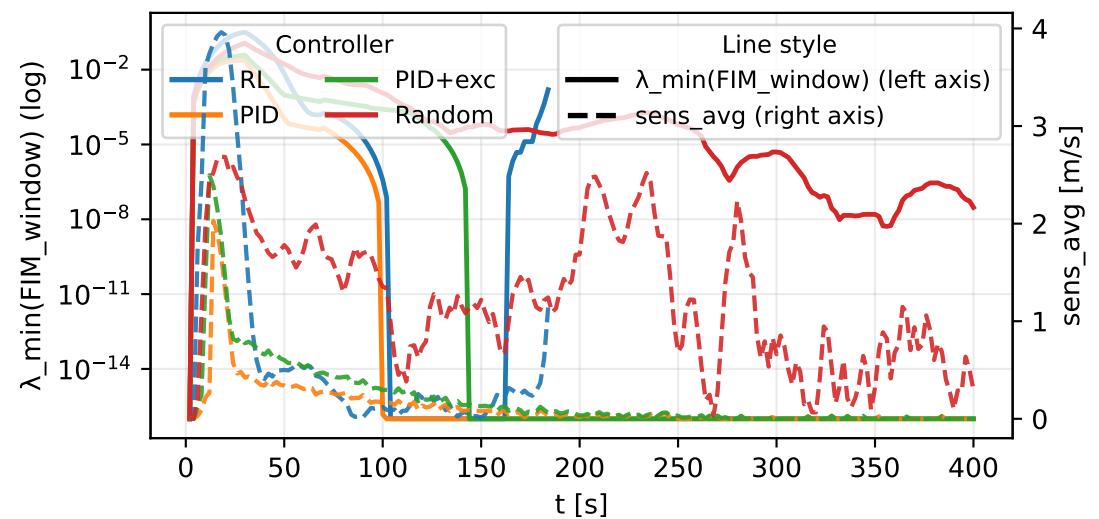
TRUE formation error



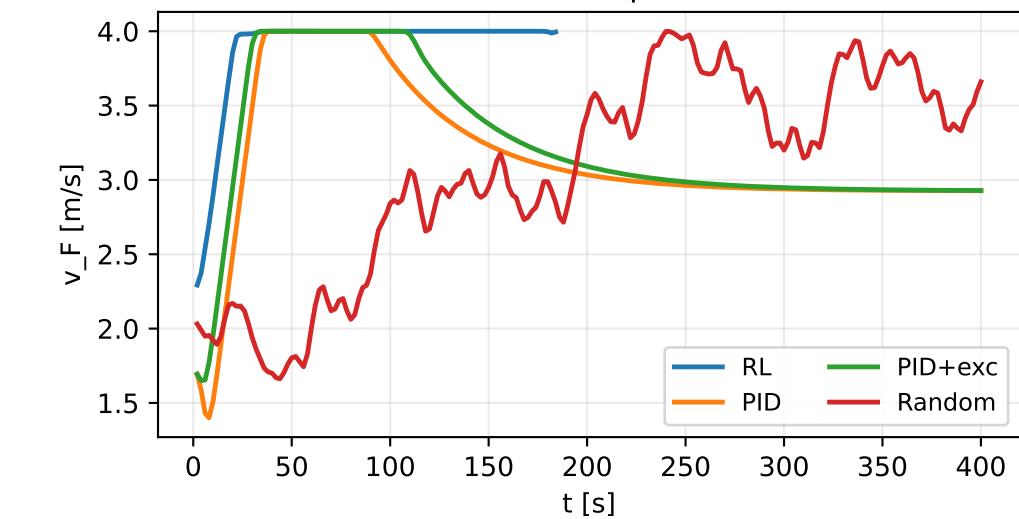
Estimator uncertainty (std_max)



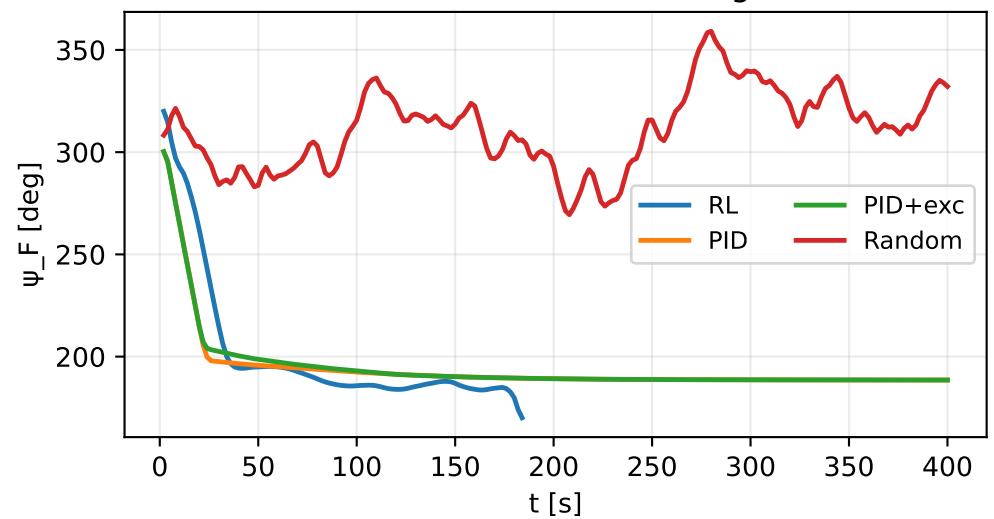
Information and excitation



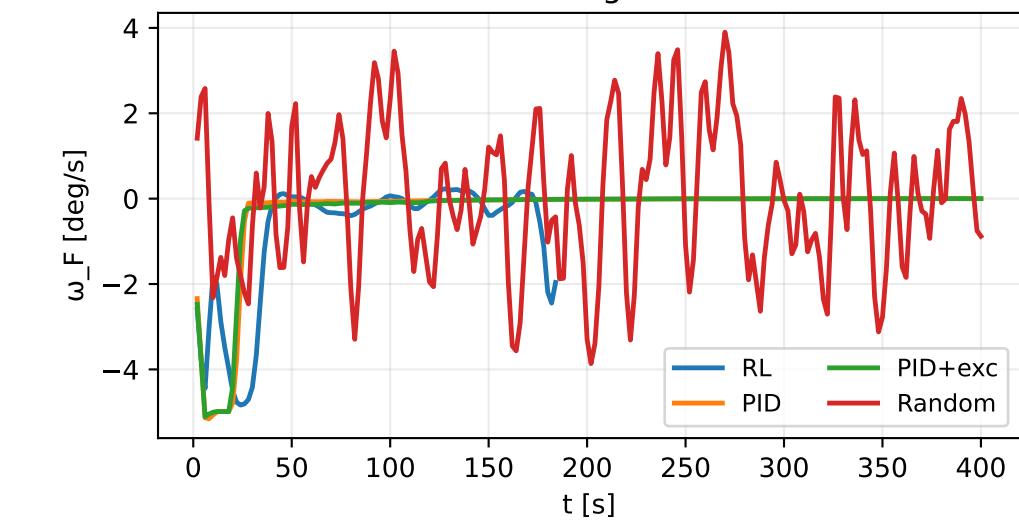
Follower speed



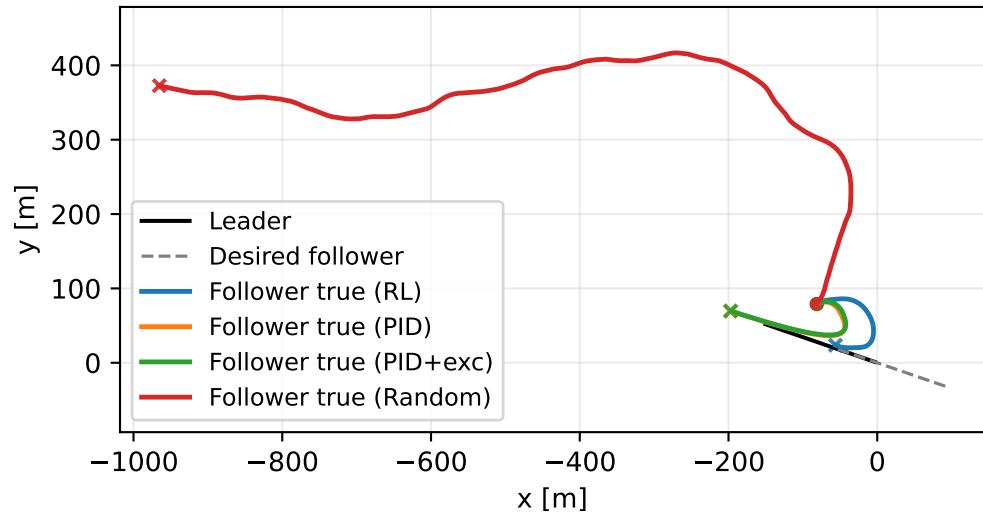
Follower course/heading



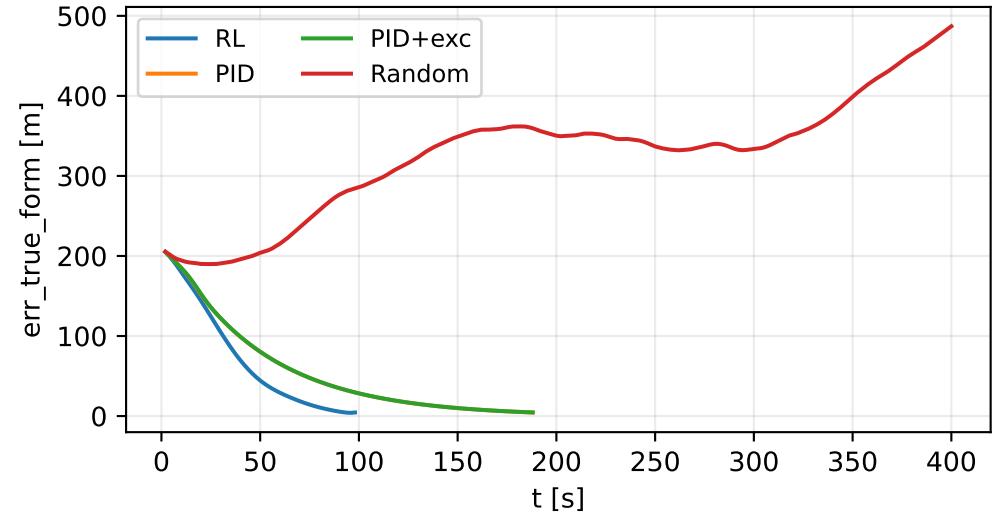
Follower angular rate



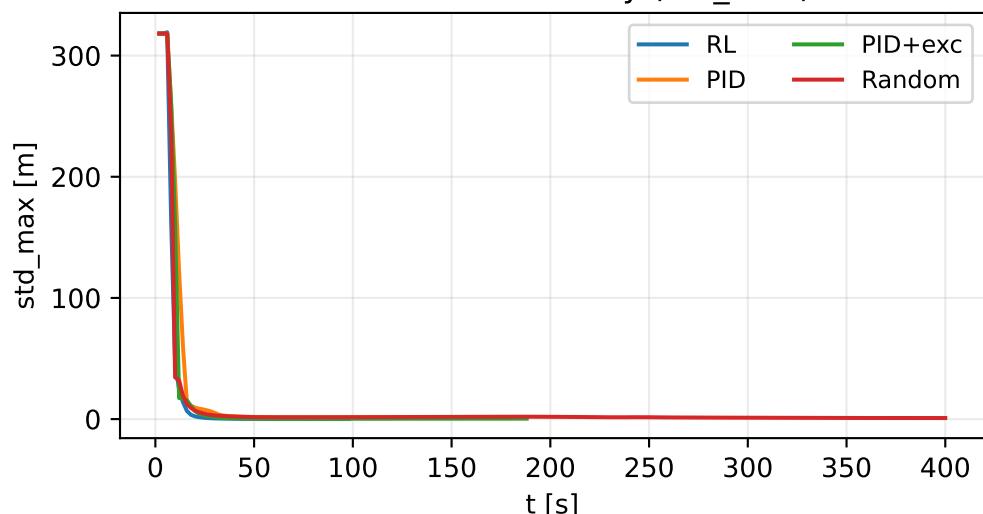
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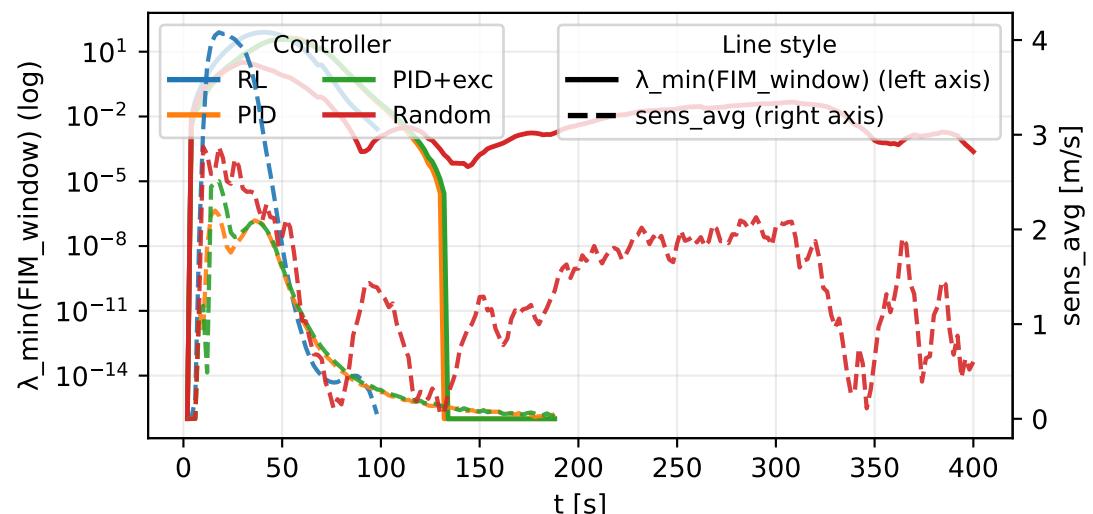
TRUE formation error



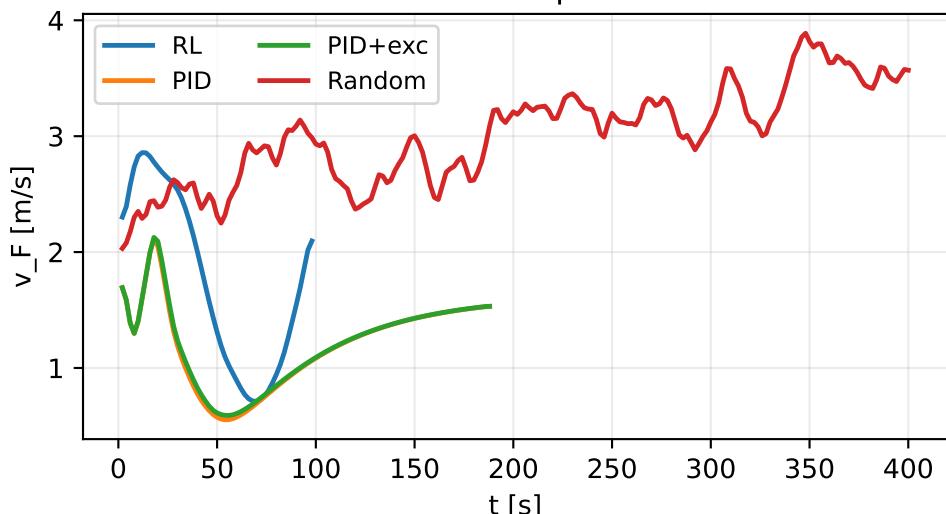
Estimator uncertainty (std_max)



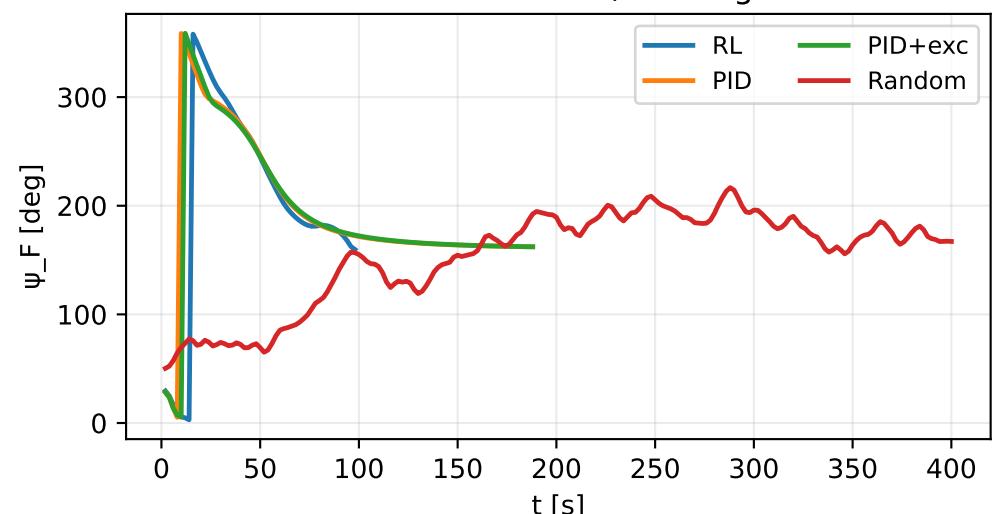
Information and excitation



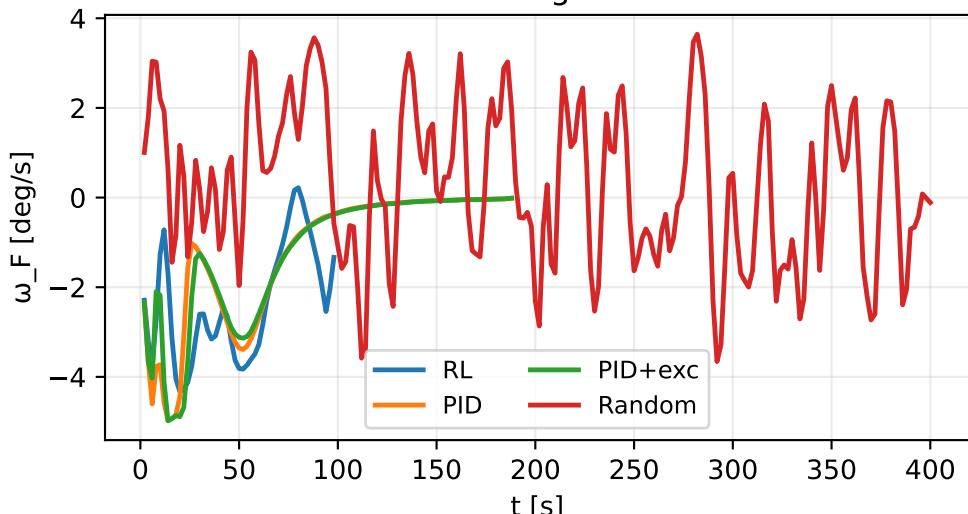
Follower speed



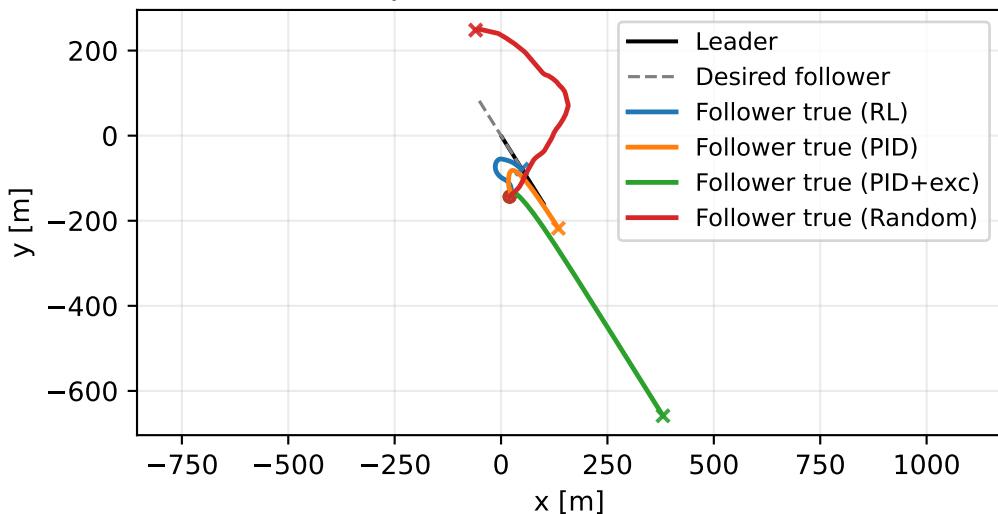
Follower course/heading



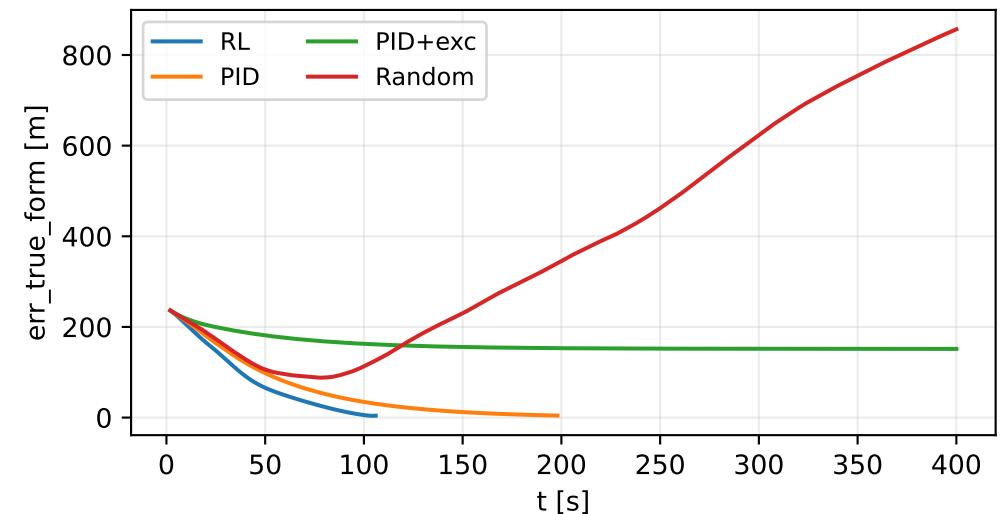
Follower angular rate



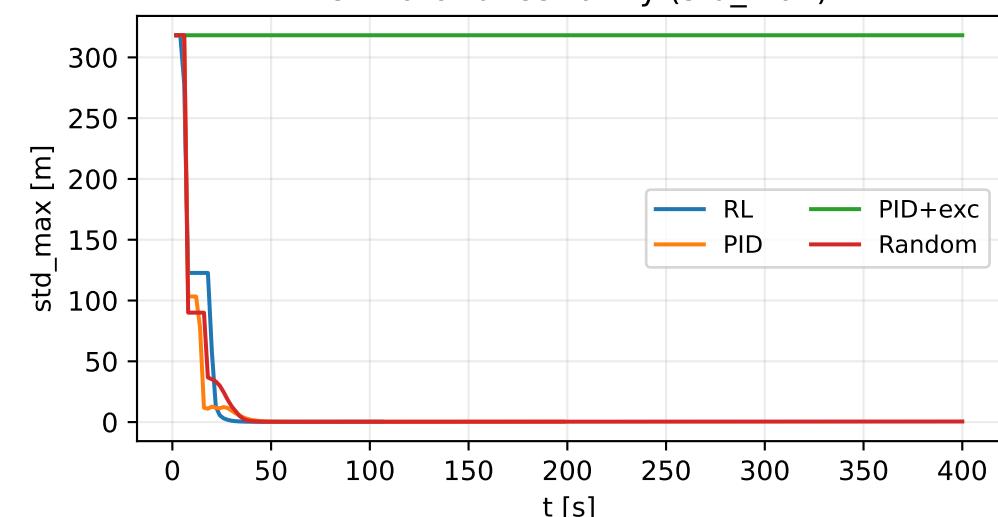
Trajectories (matched seed)



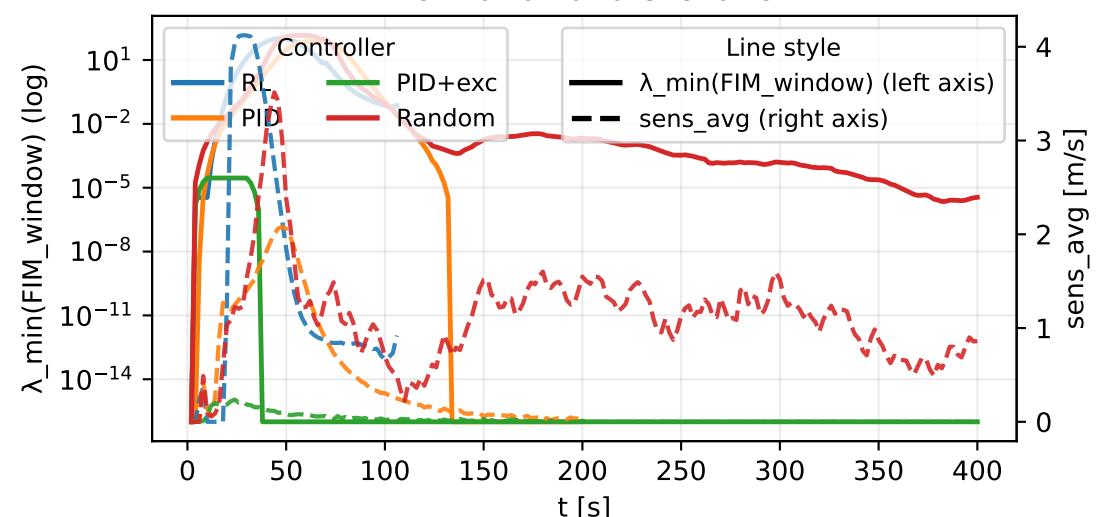
TRUE formation error



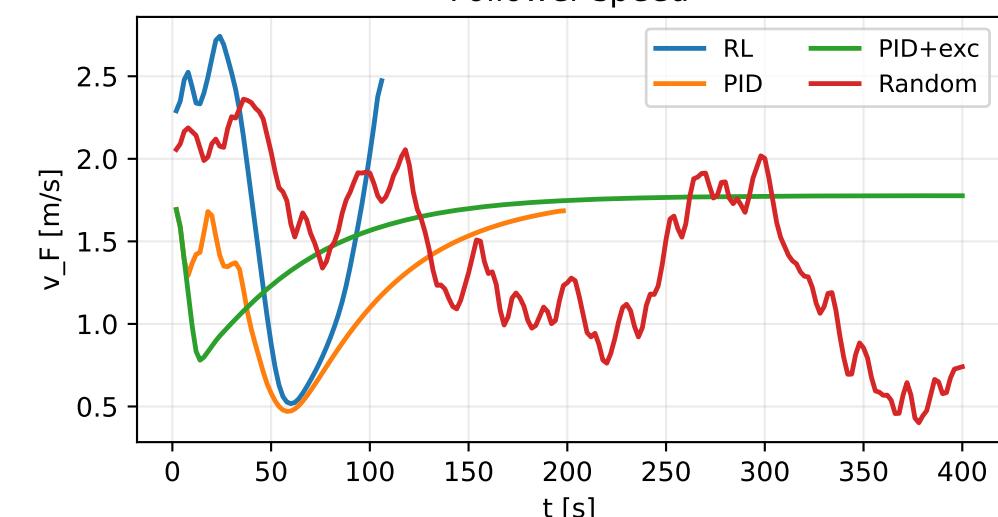
Estimator uncertainty (std_max)



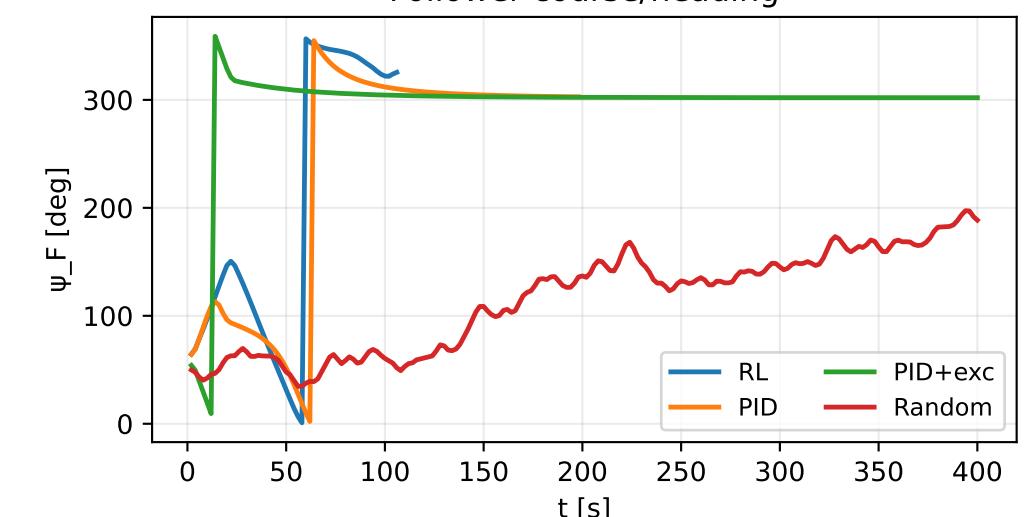
Information and excitation



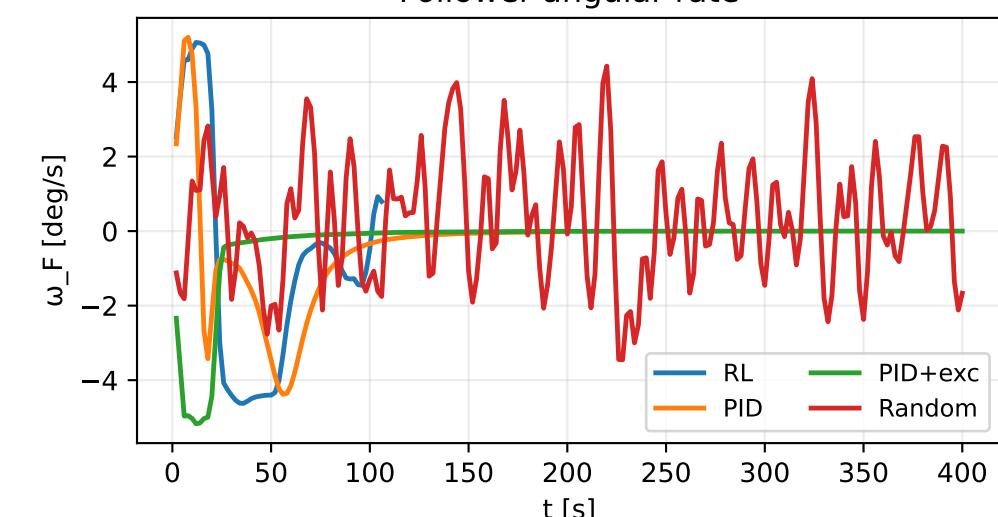
Follower speed



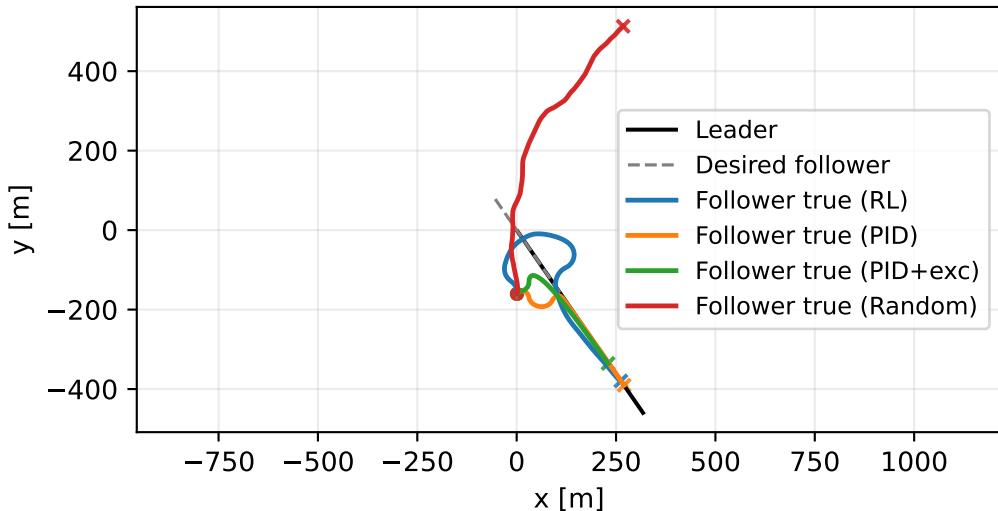
Follower course/heading



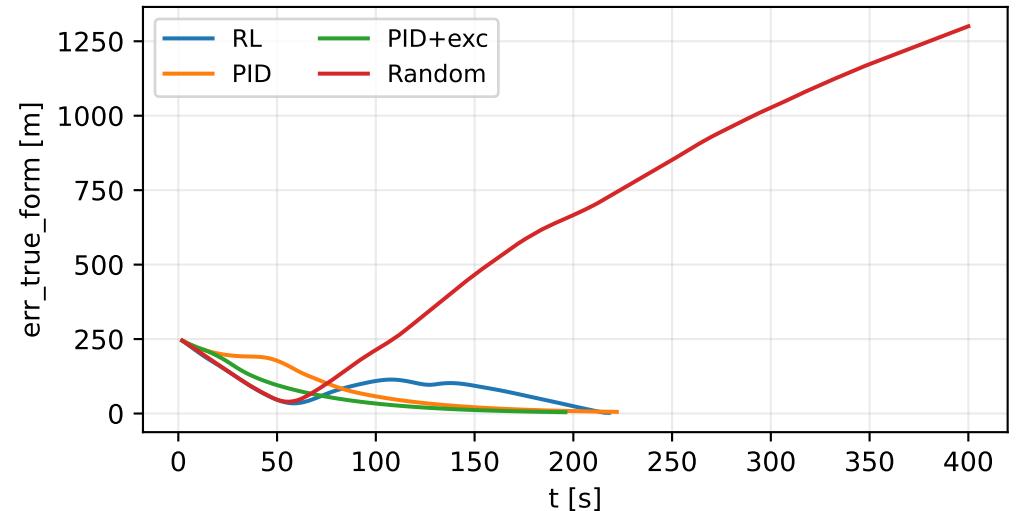
Follower angular rate



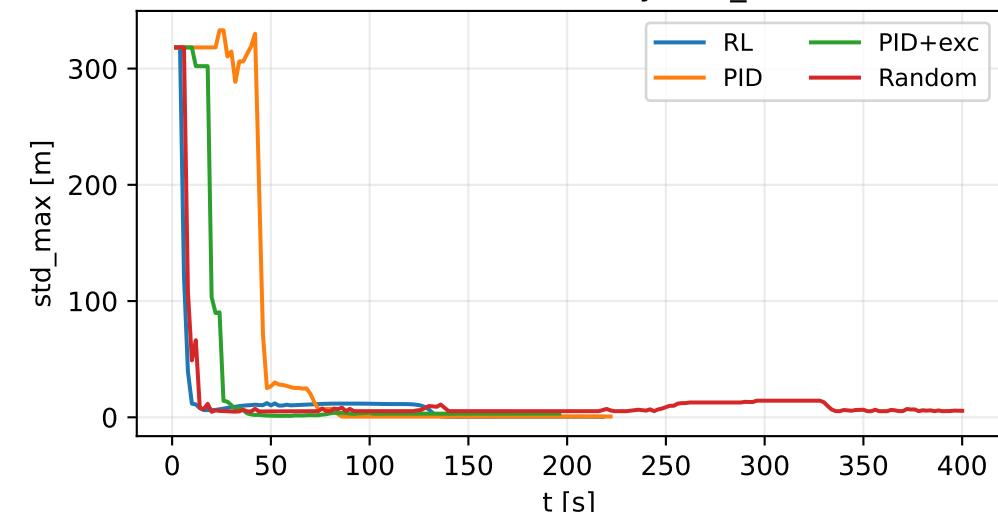
Trajectories (matched seed)



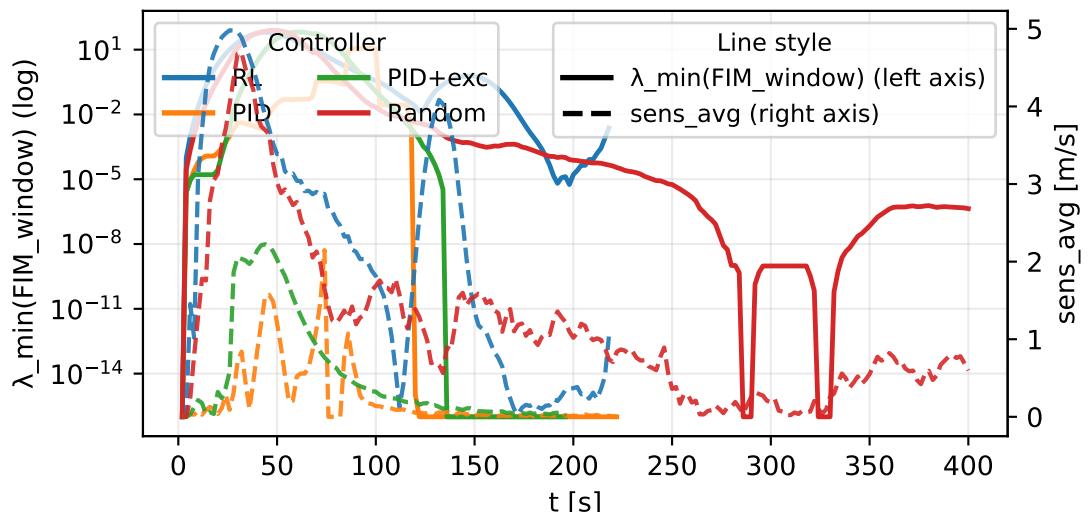
TRUE formation error



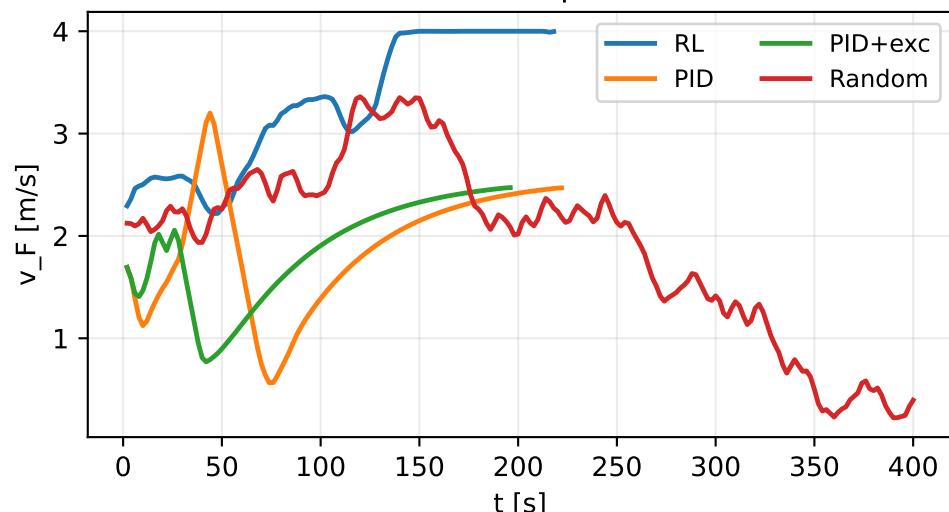
Estimator uncertainty (std_max)



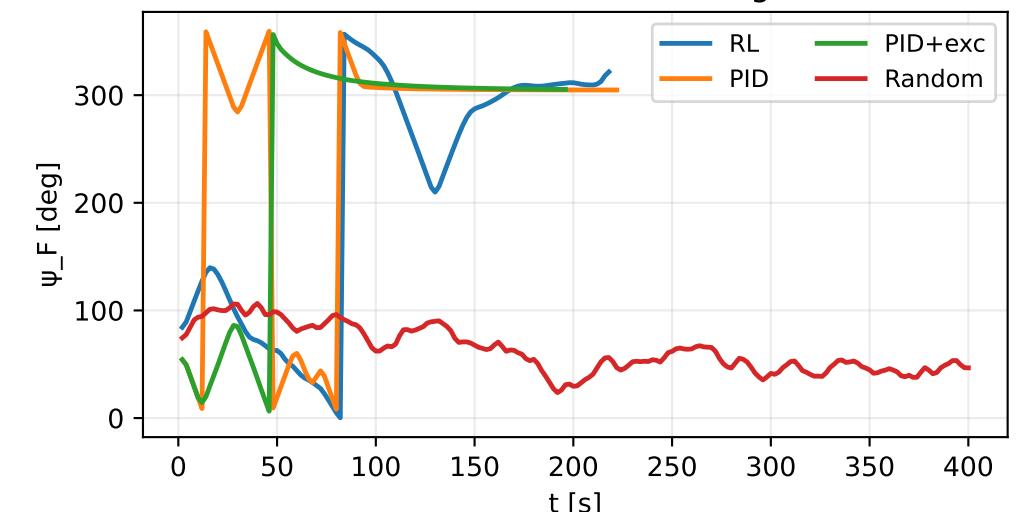
Information and excitation



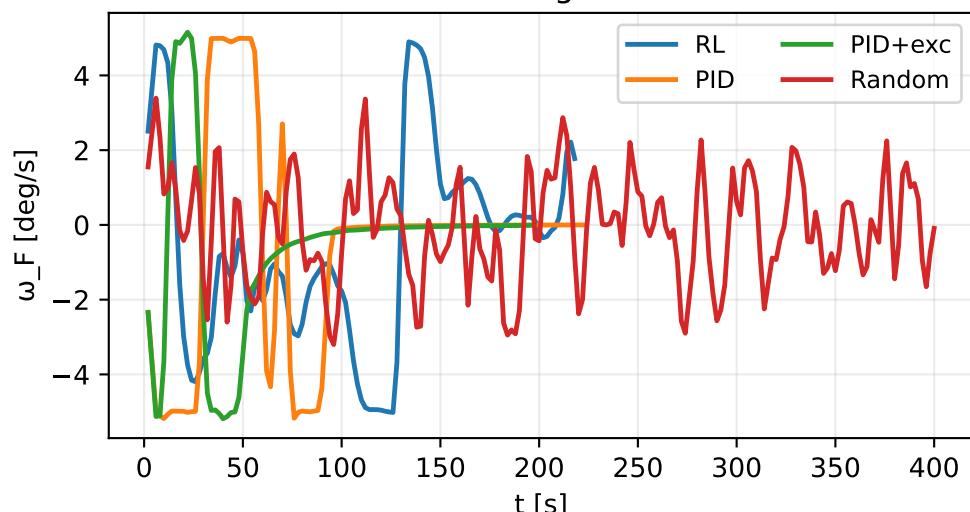
Follower speed



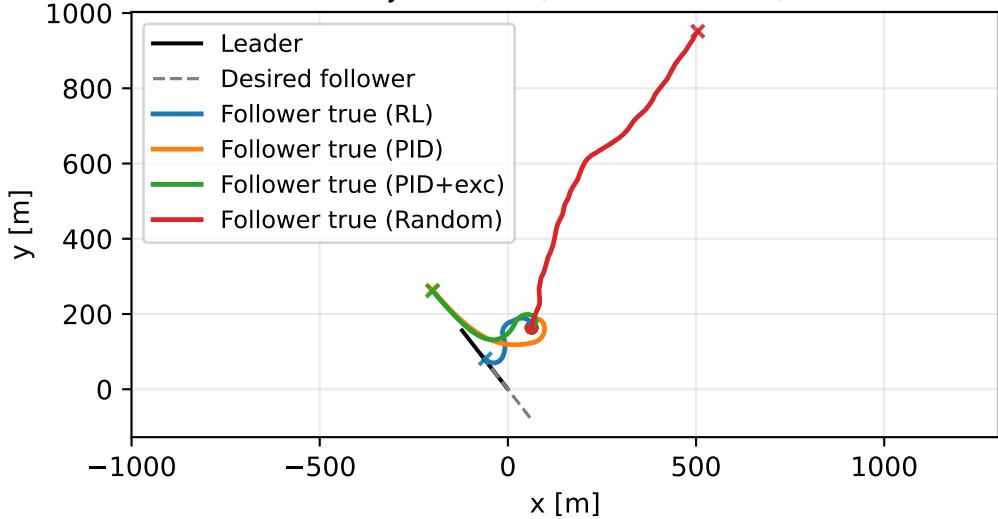
Follower course/heading



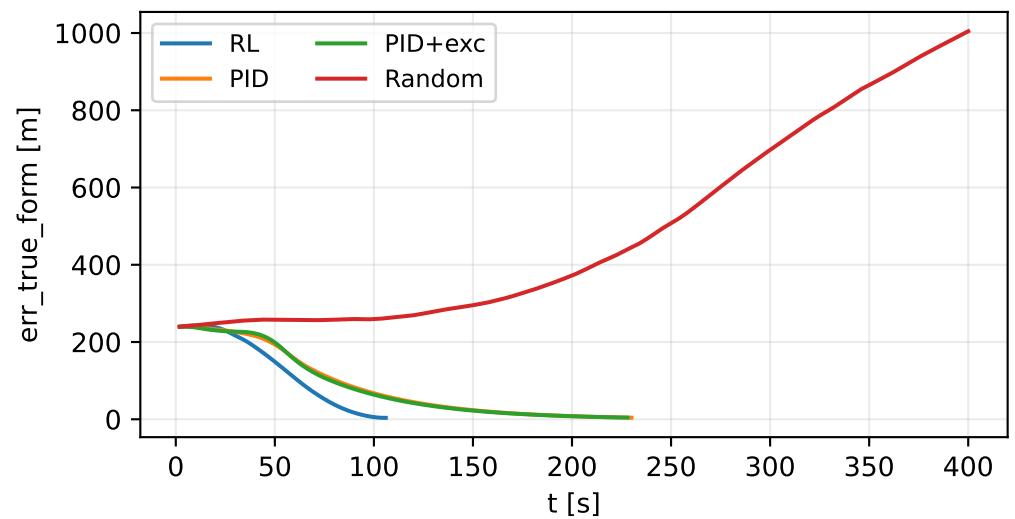
Follower angular rate



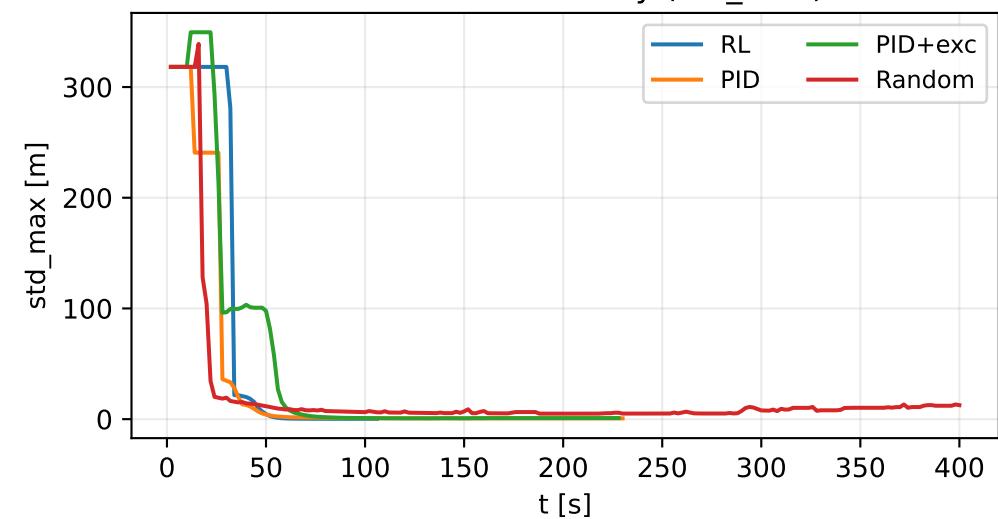
Trajectories (matched seed)



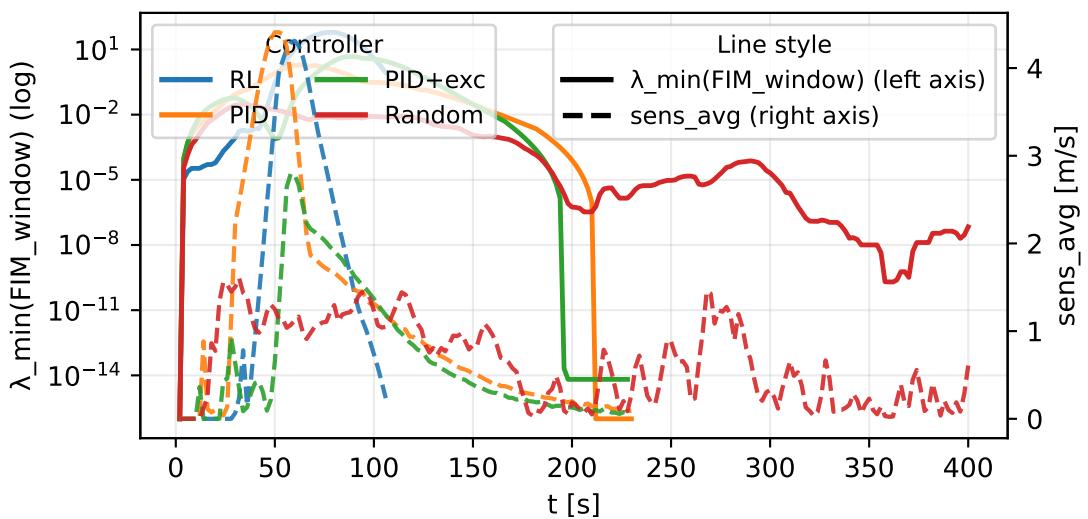
TRUE formation error



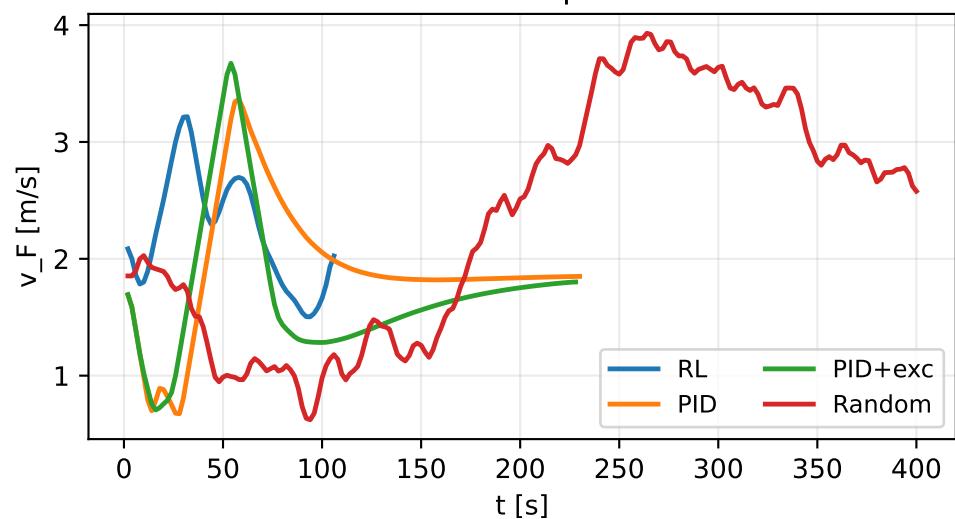
Estimator uncertainty (std_max)



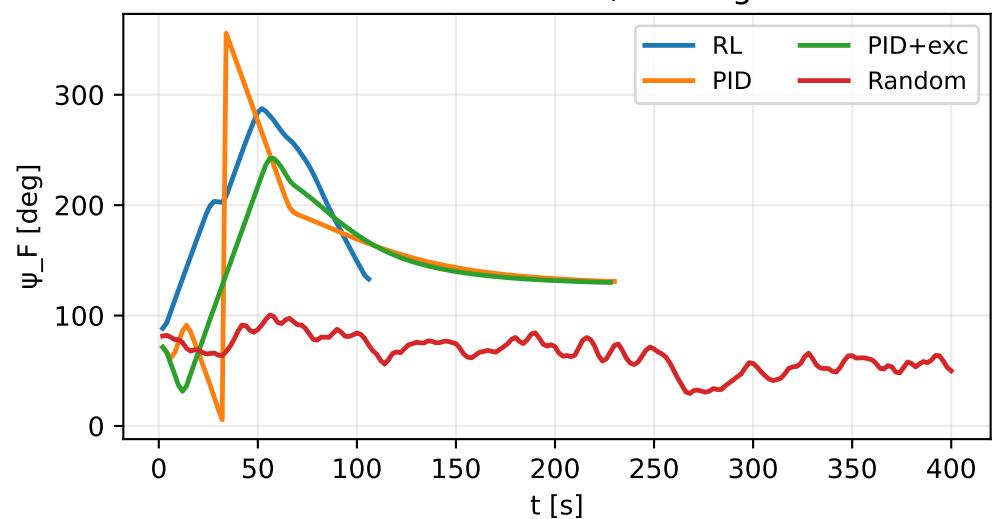
Information and excitation



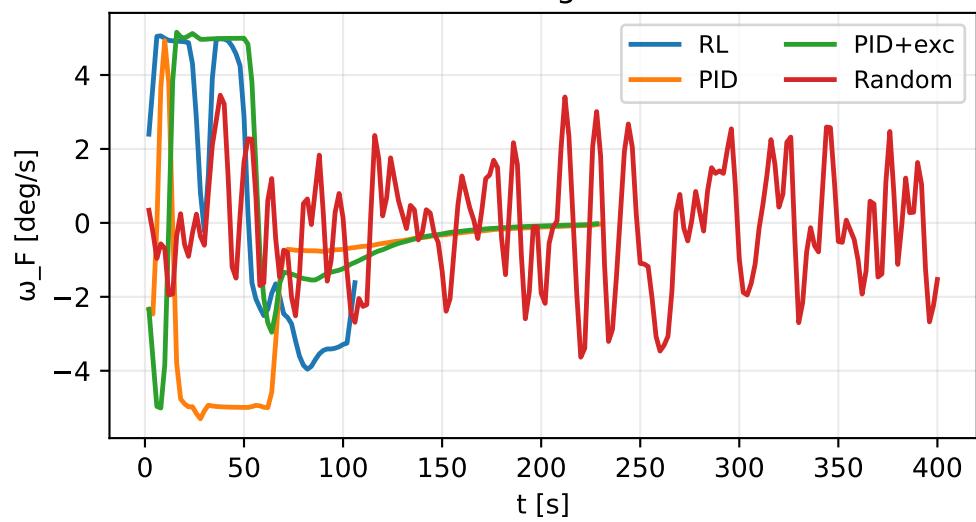
Follower speed



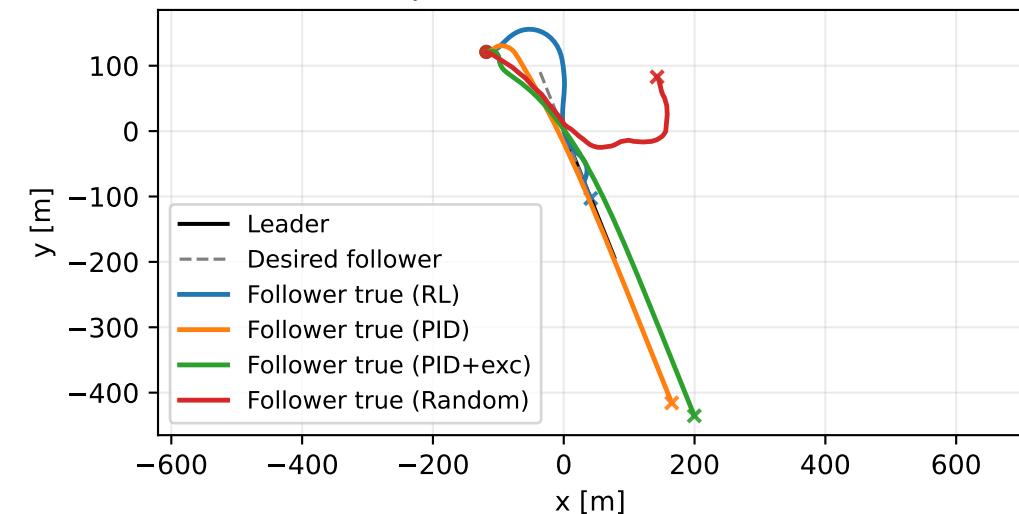
Follower course/heading



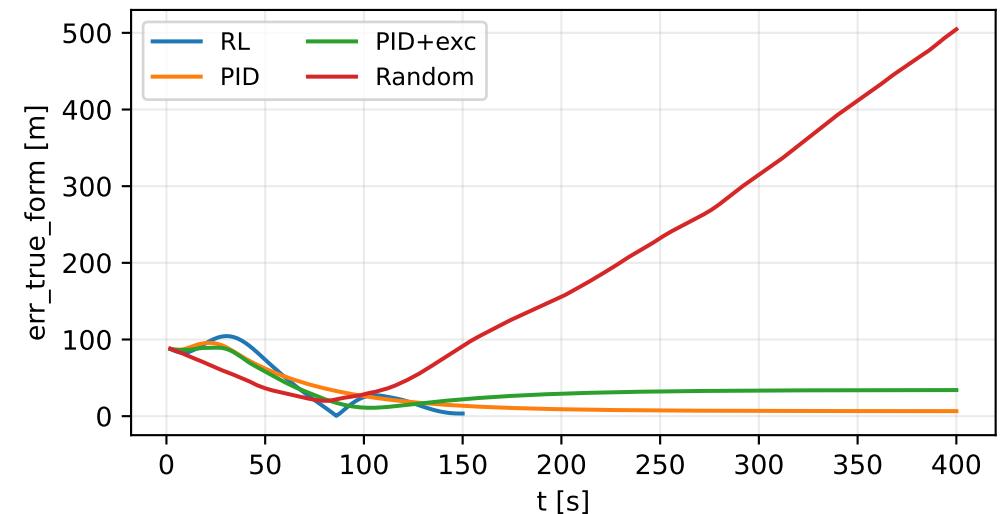
Follower angular rate



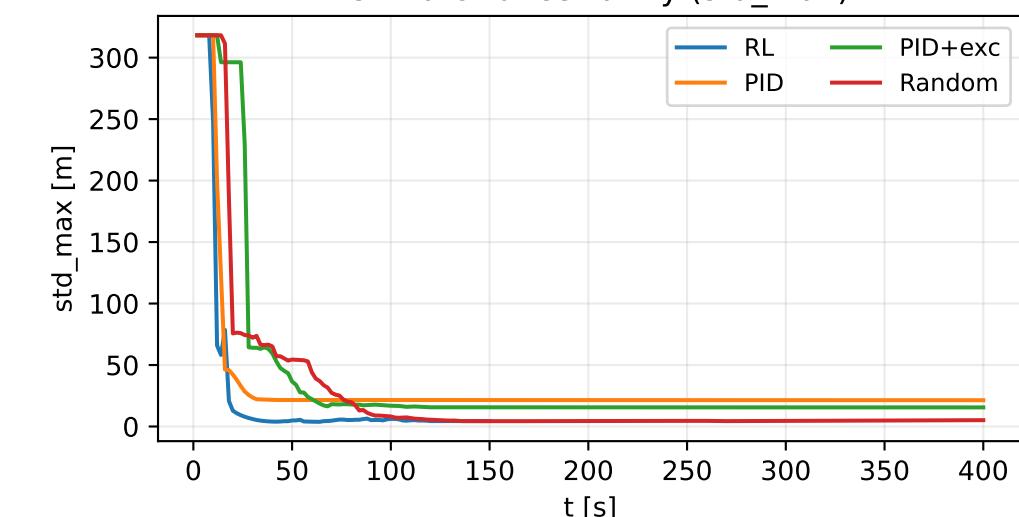
Trajectories (matched seed)



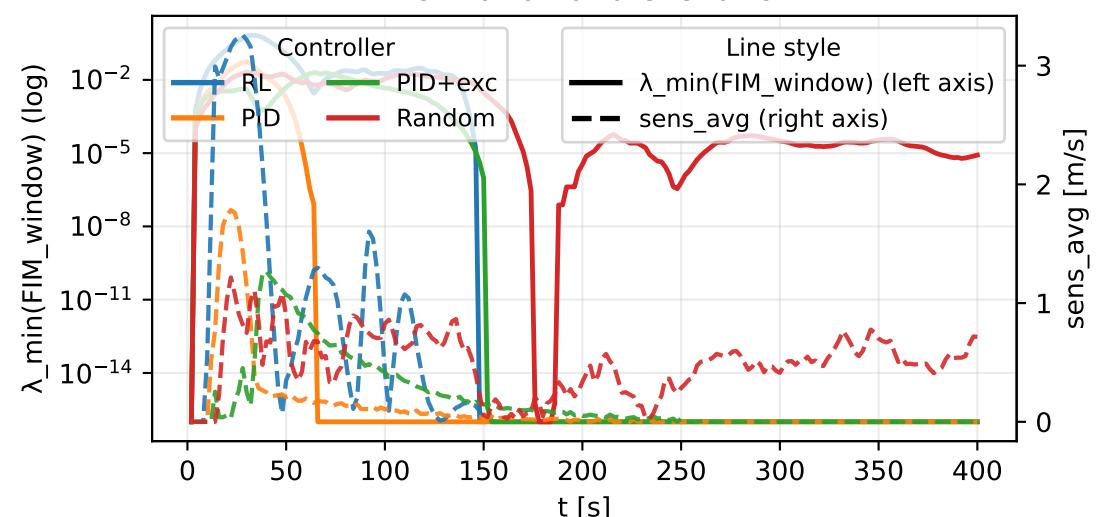
TRUE formation error



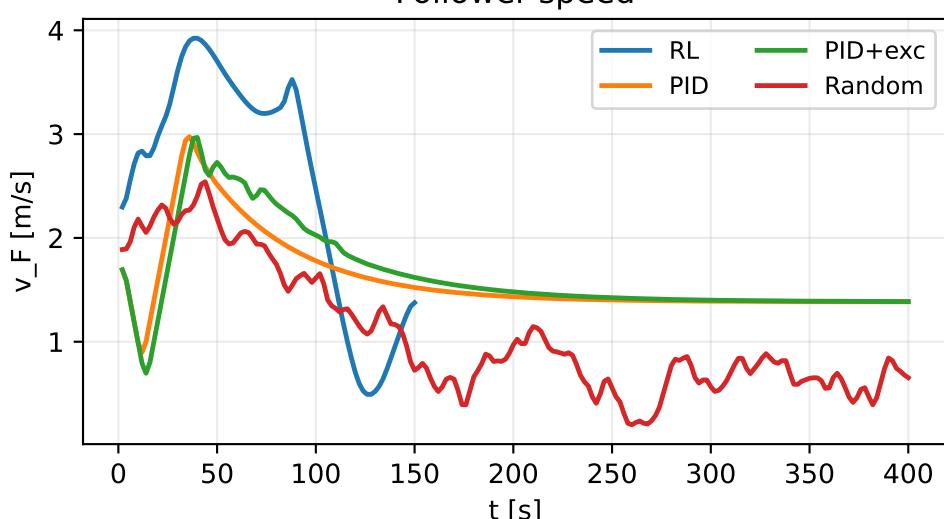
Estimator uncertainty (std_max)



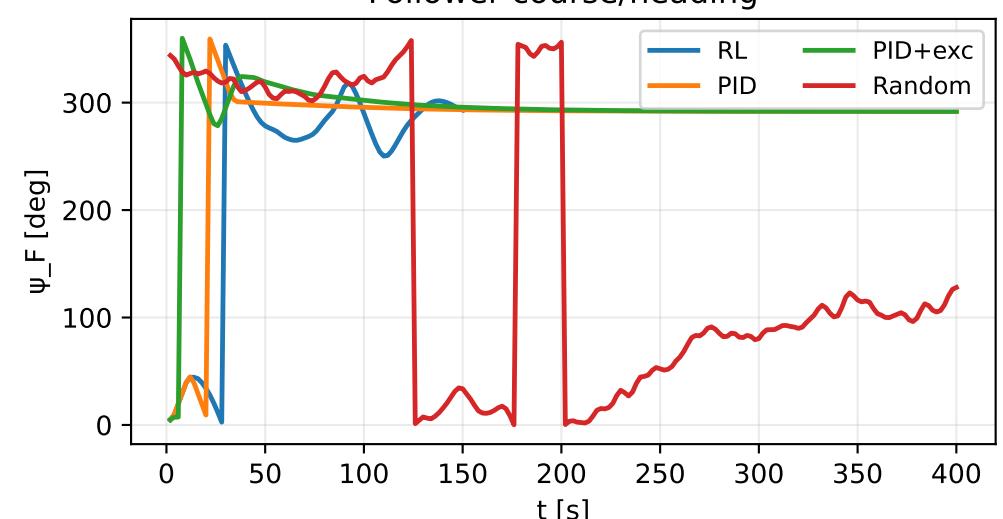
Information and excitation



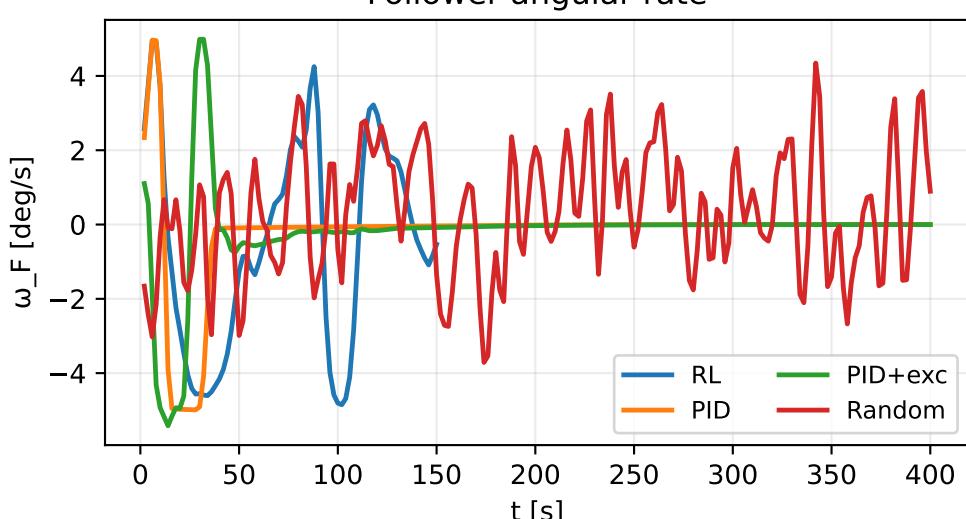
Follower speed



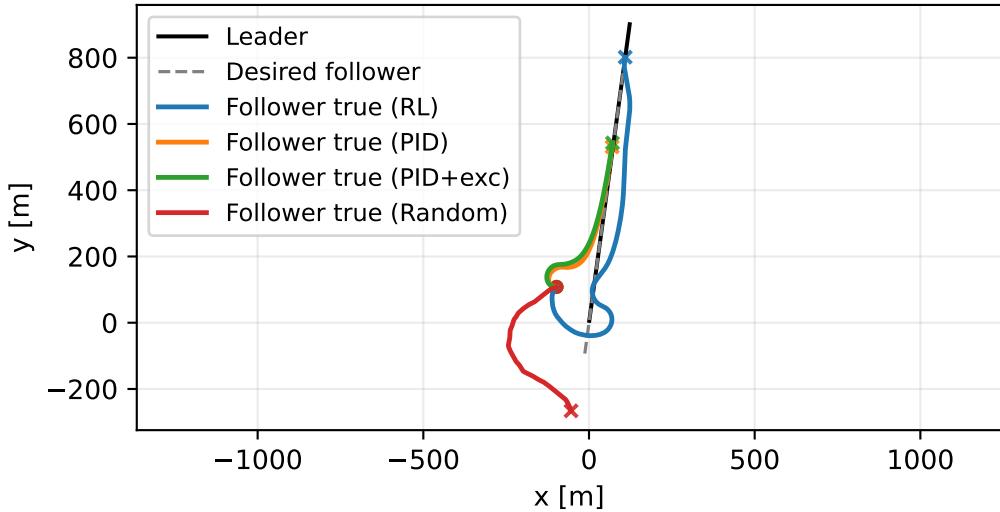
Follower course/heading



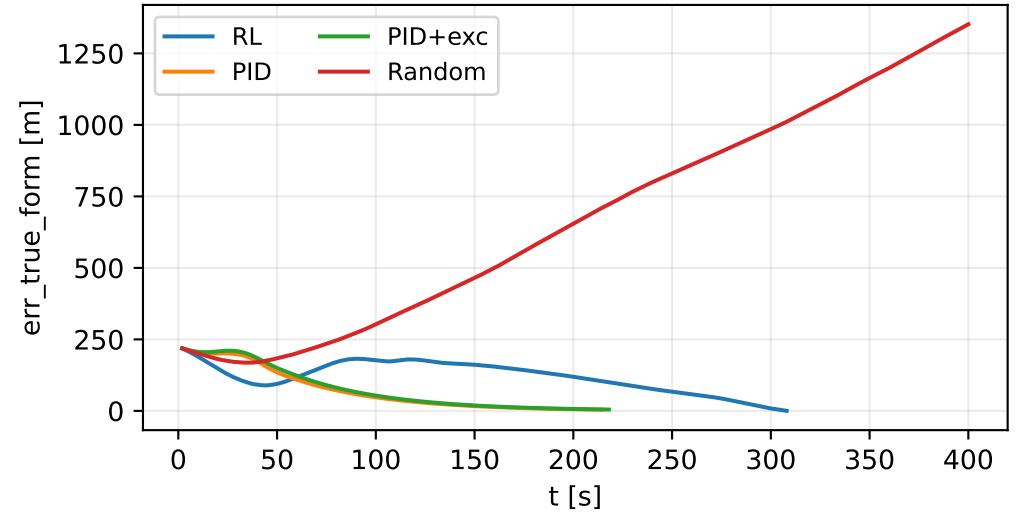
Follower angular rate



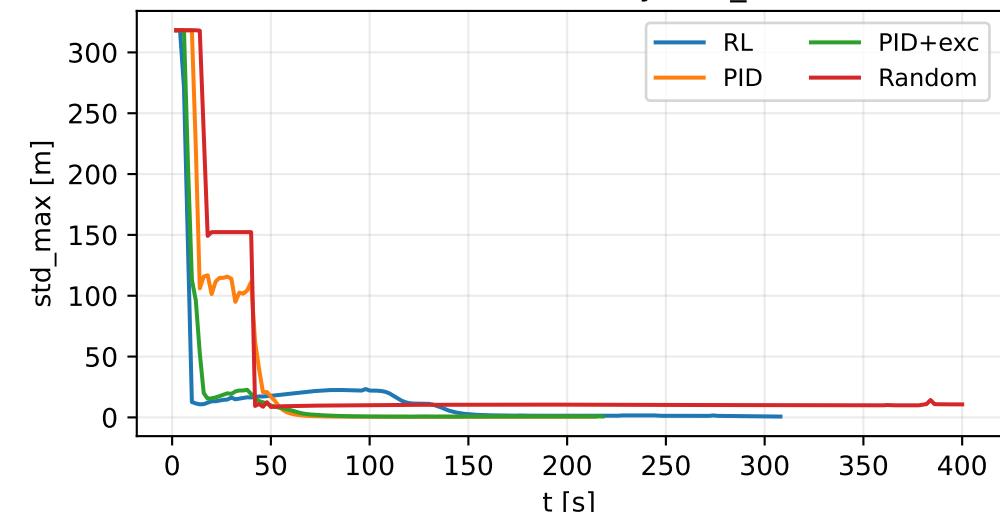
Trajectories (matched seed)



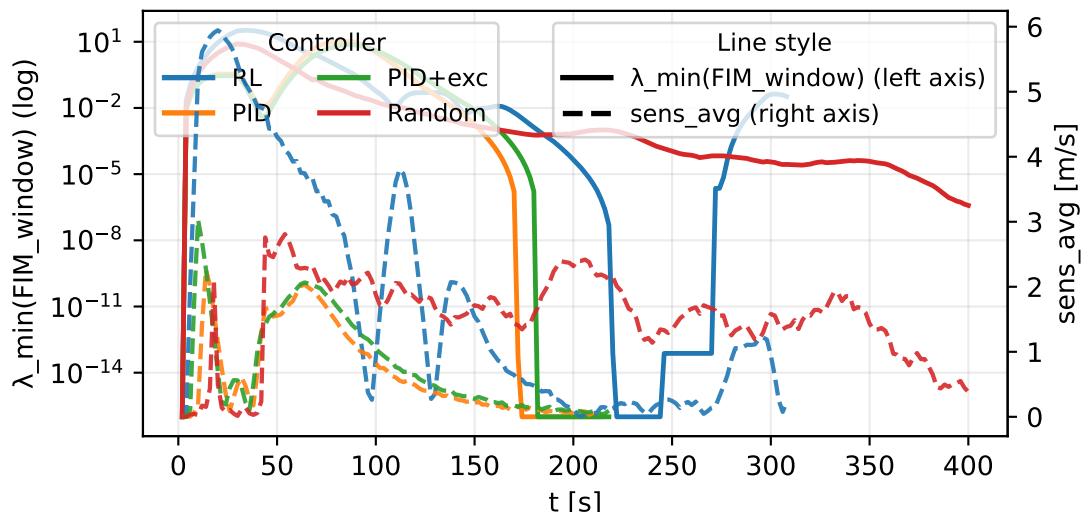
TRUE formation error



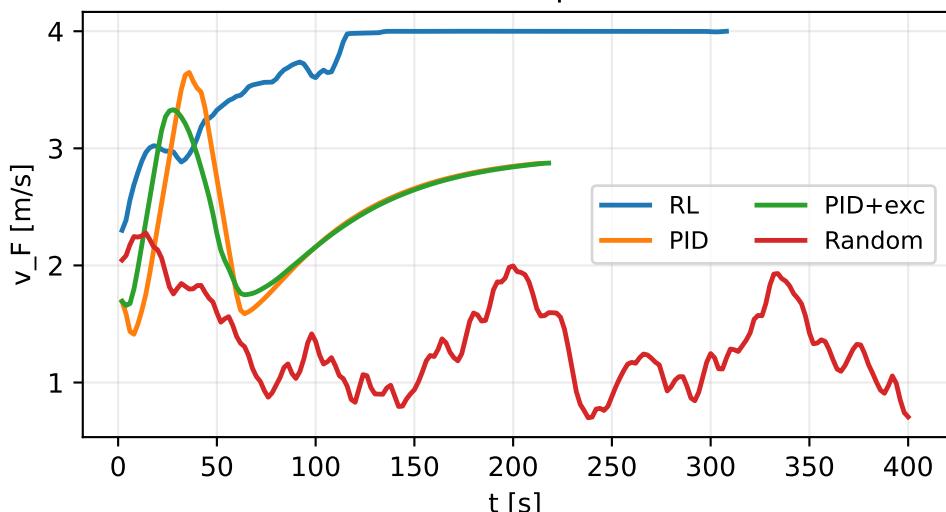
Estimator uncertainty (std_max)



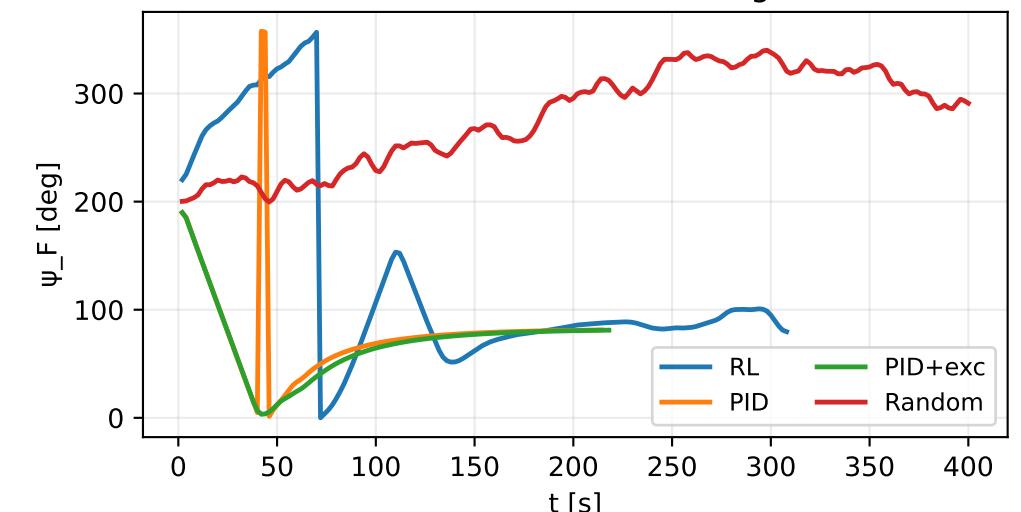
Information and excitation



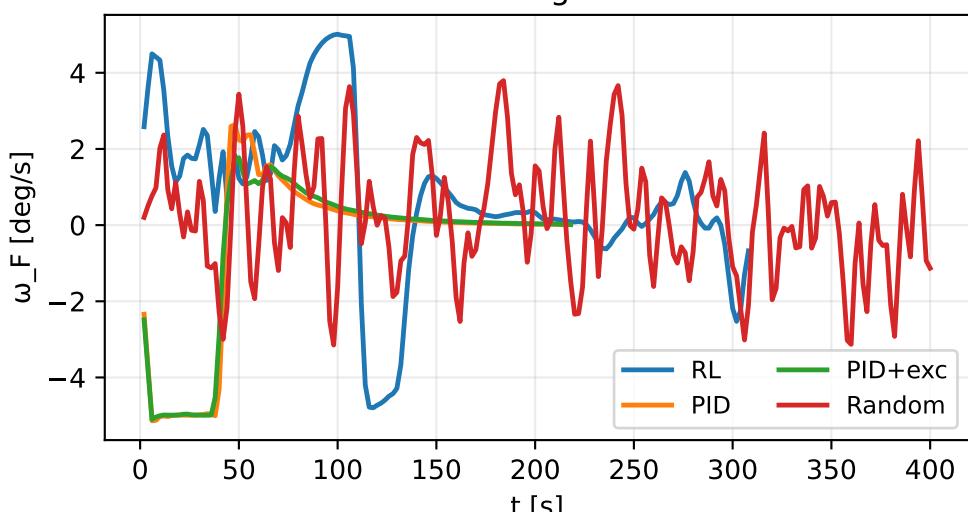
Follower speed



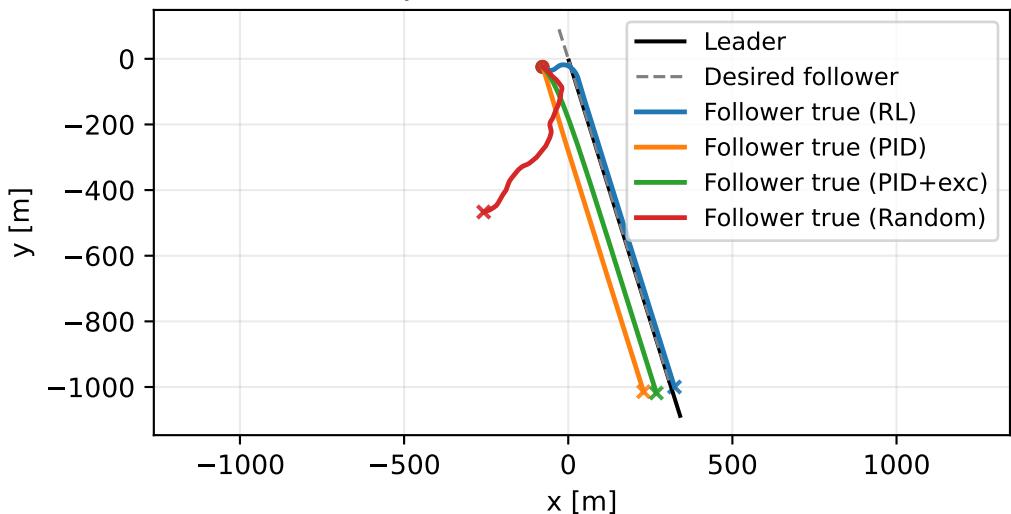
Follower course/heading



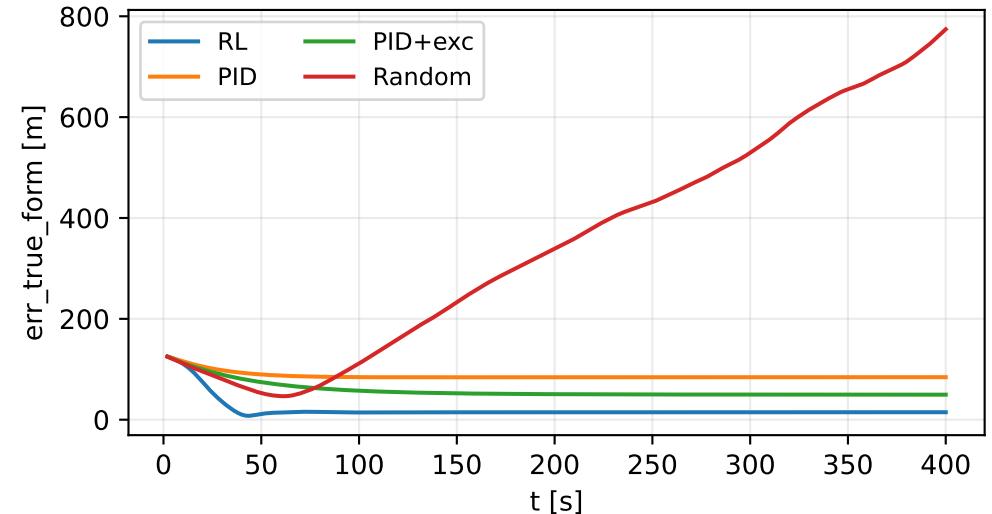
Follower angular rate



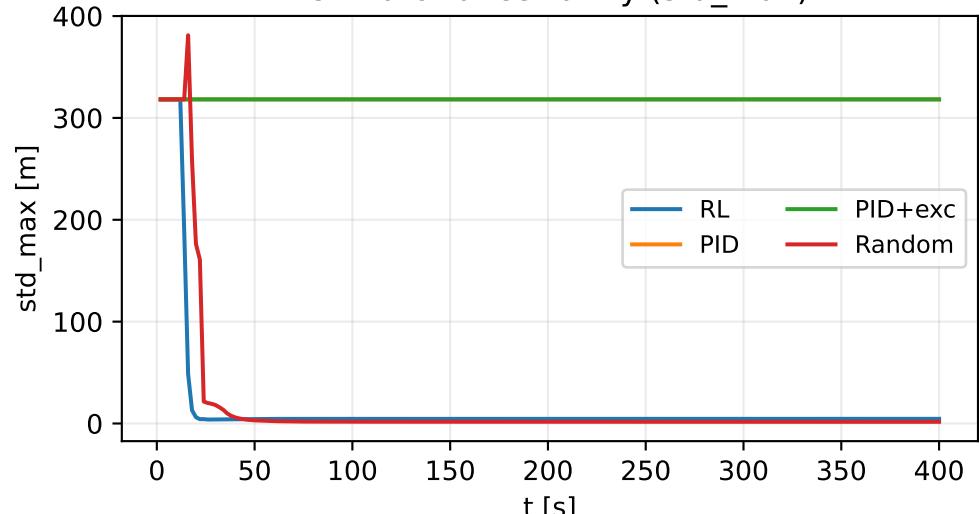
Trajectories (matched seed)



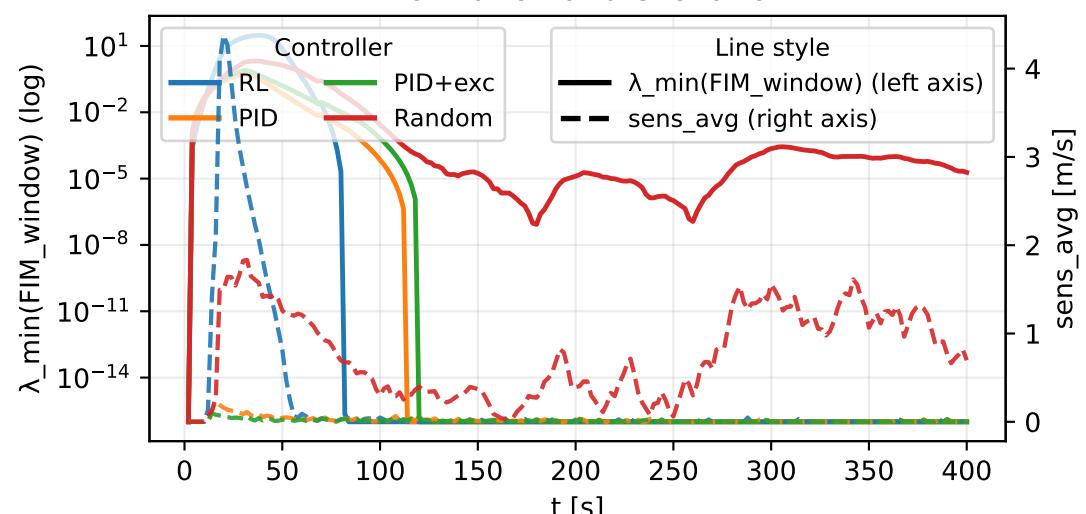
TRUE formation error



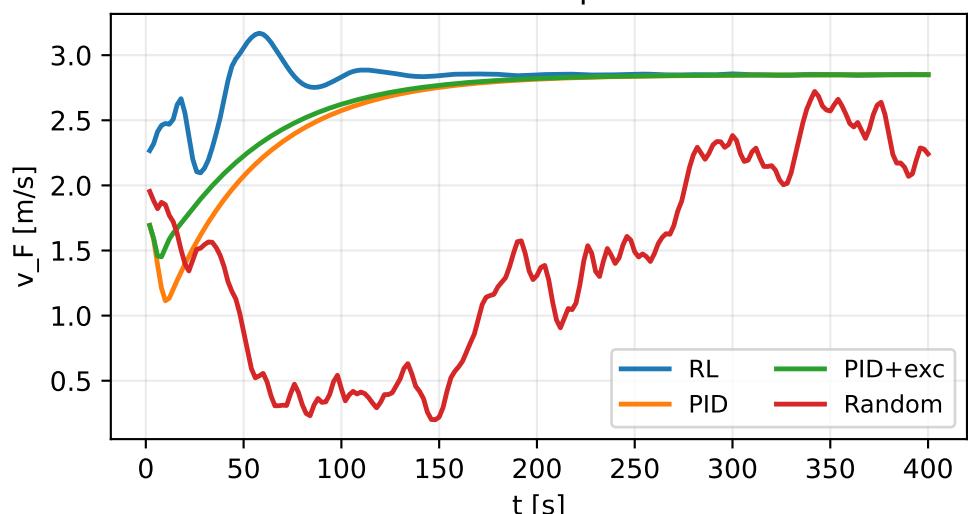
Estimator uncertainty (std_max)



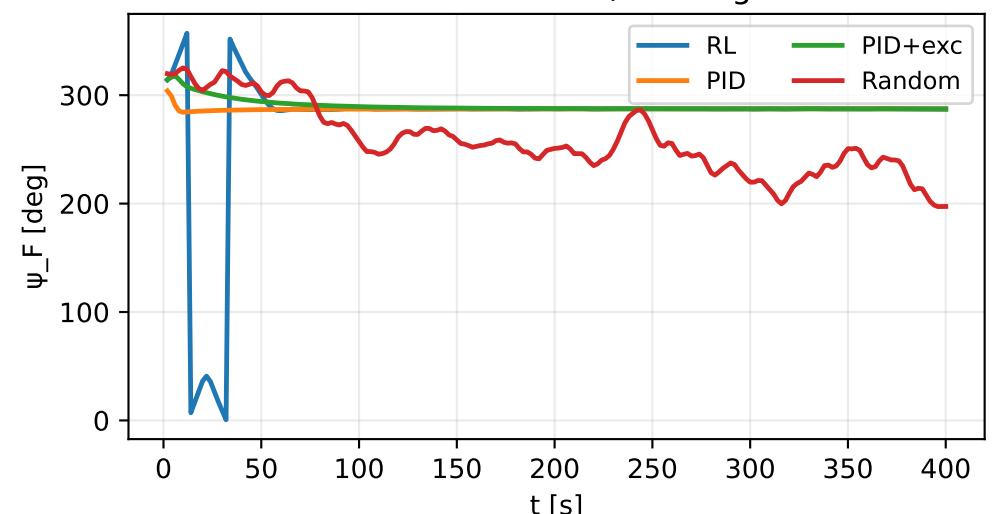
Information and excitation



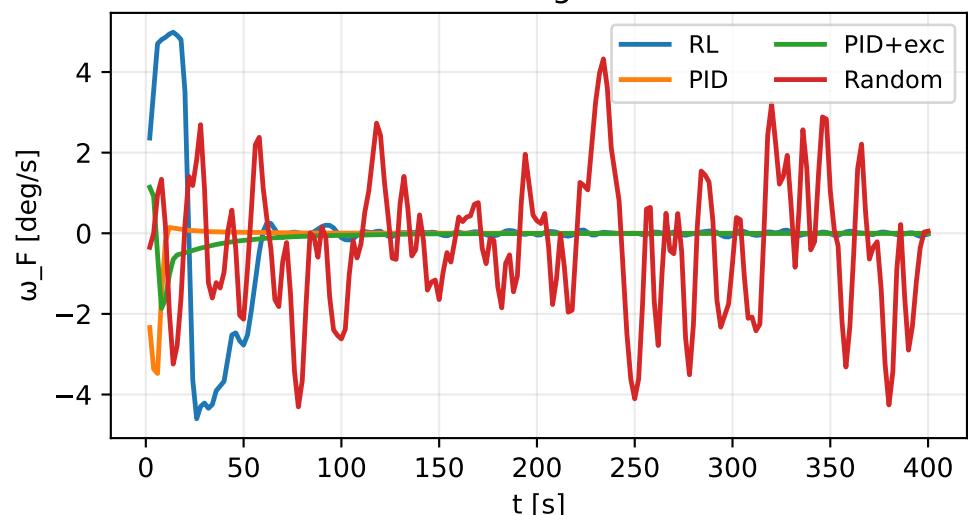
Follower speed



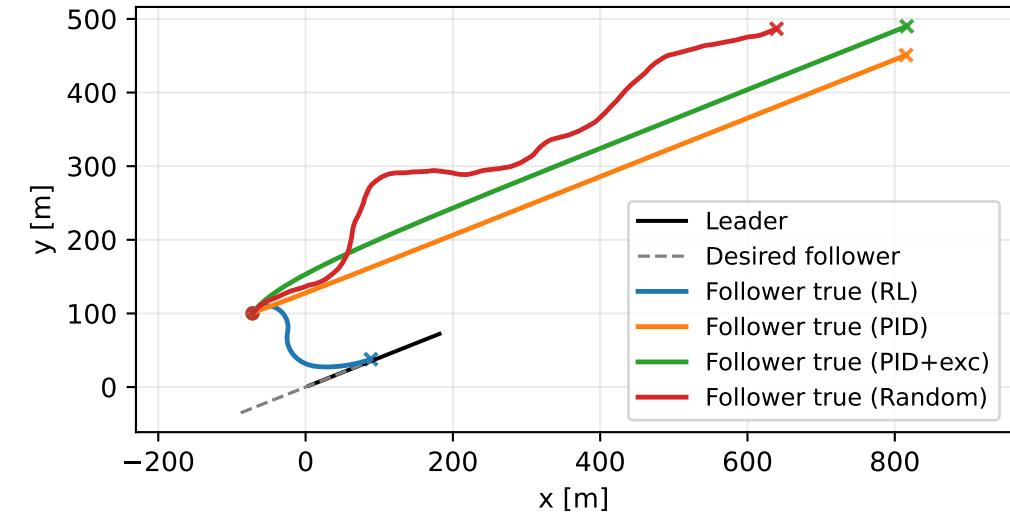
Follower course/heading



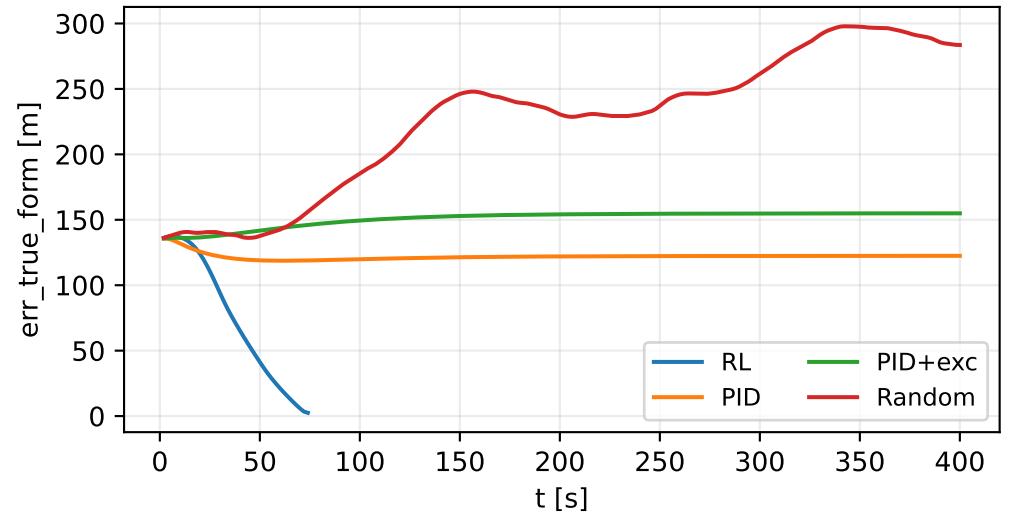
Follower angular rate



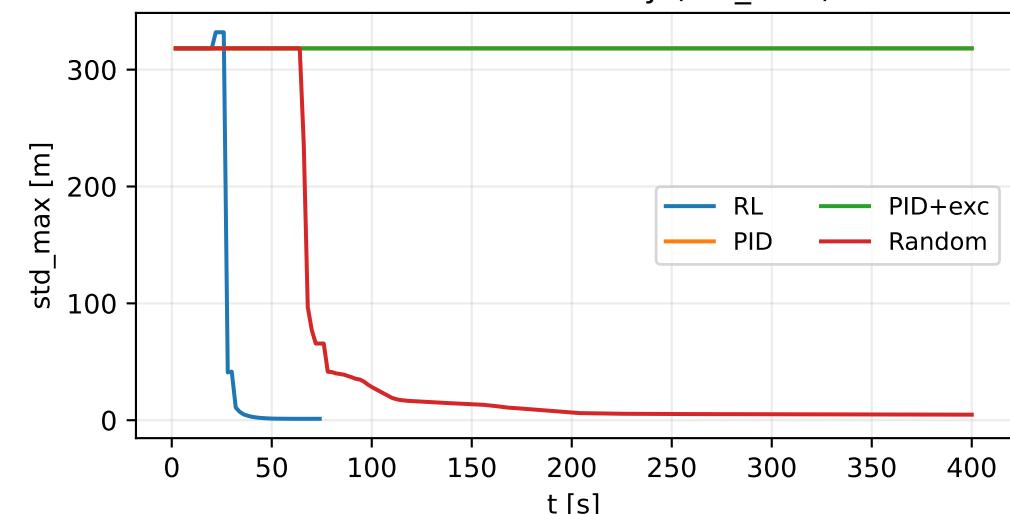
Trajectories (matched seed)



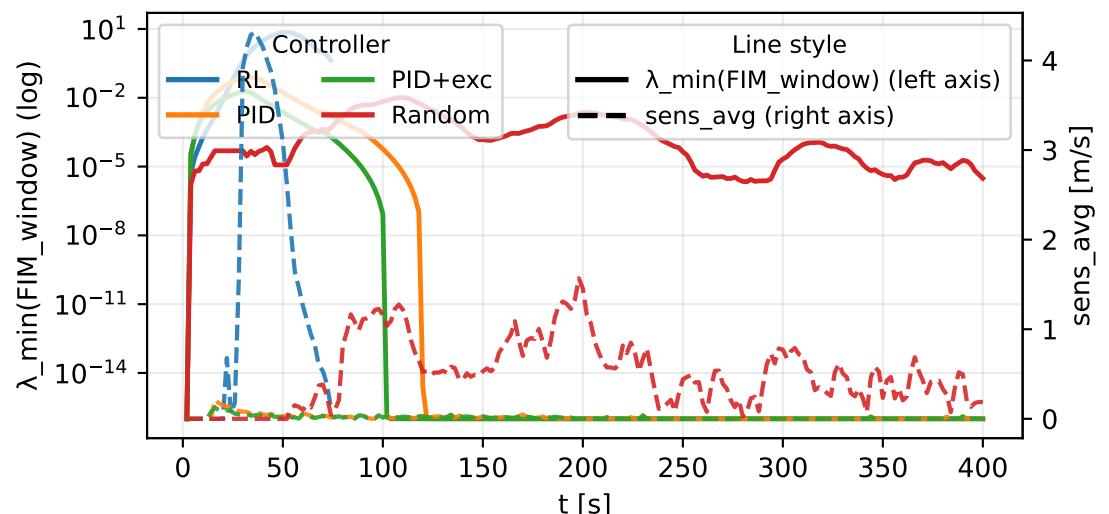
TRUE formation error



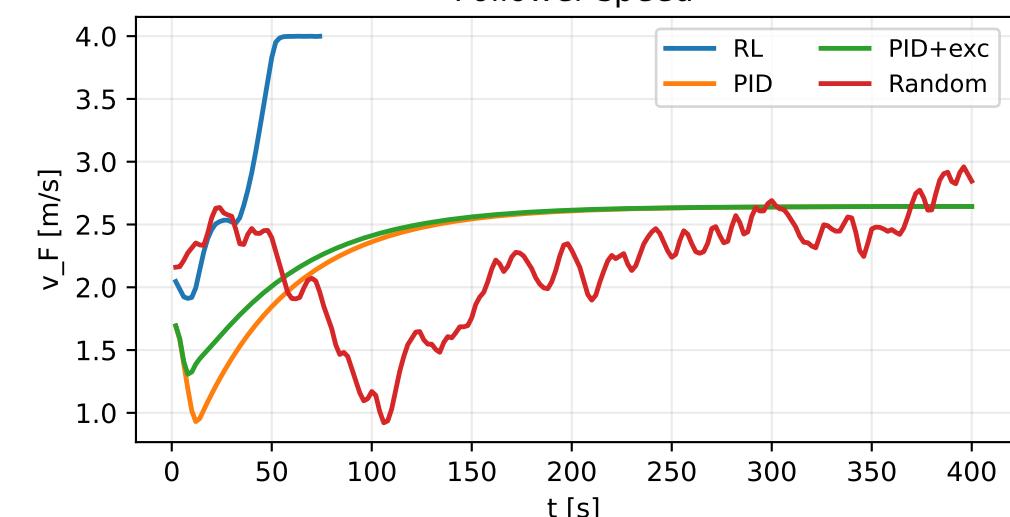
Estimator uncertainty (std_max)



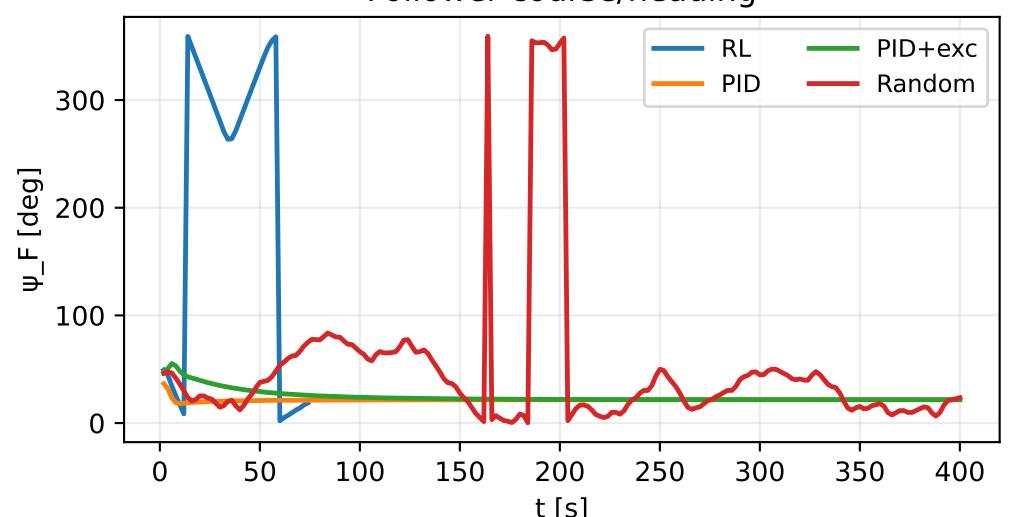
Information and excitation



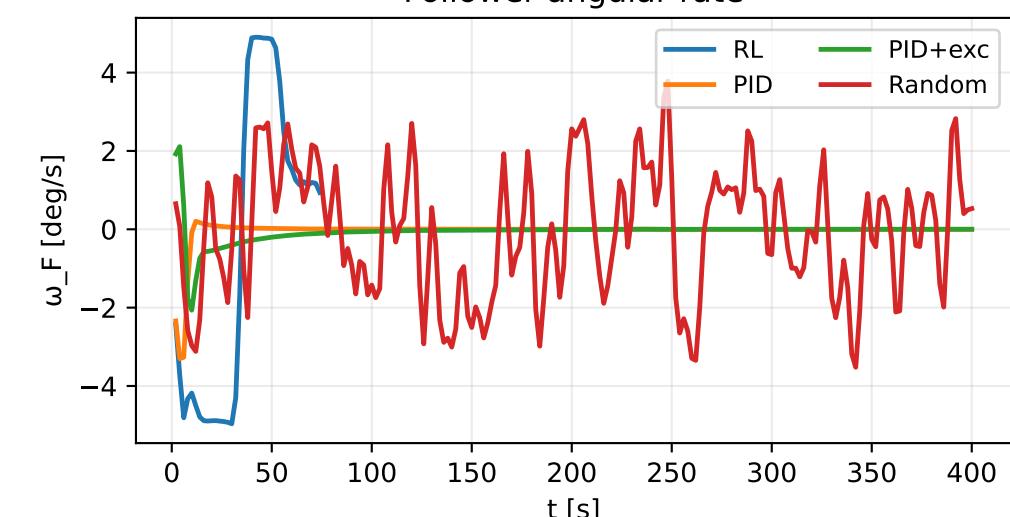
Follower speed



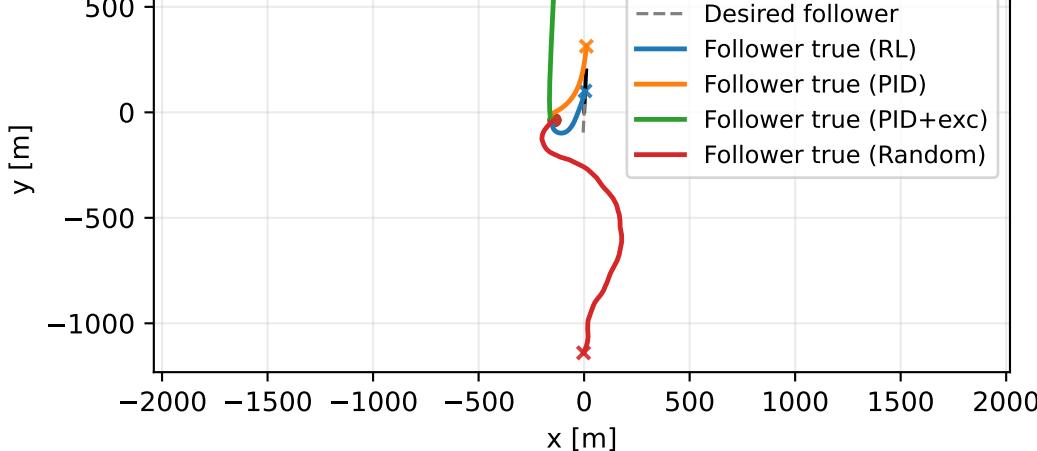
Follower course/heading



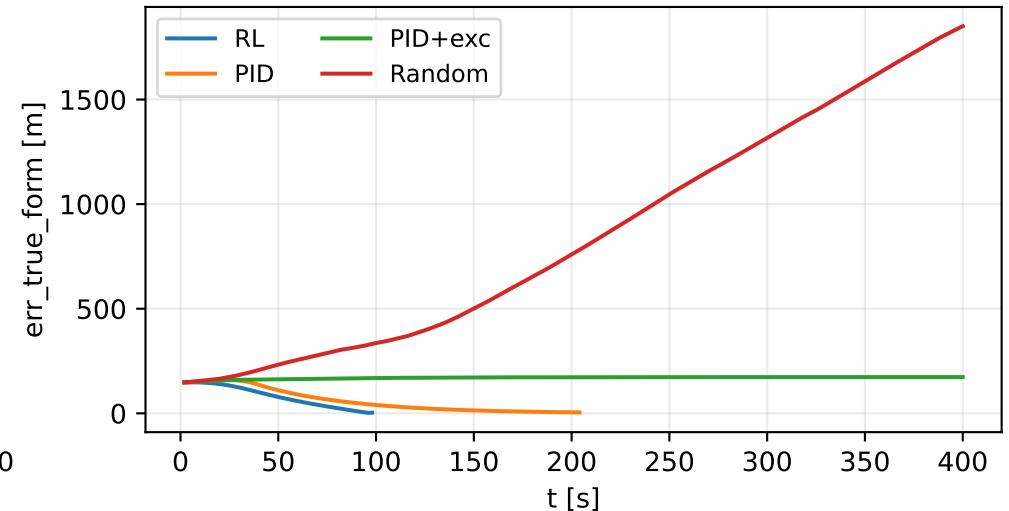
Follower angular rate



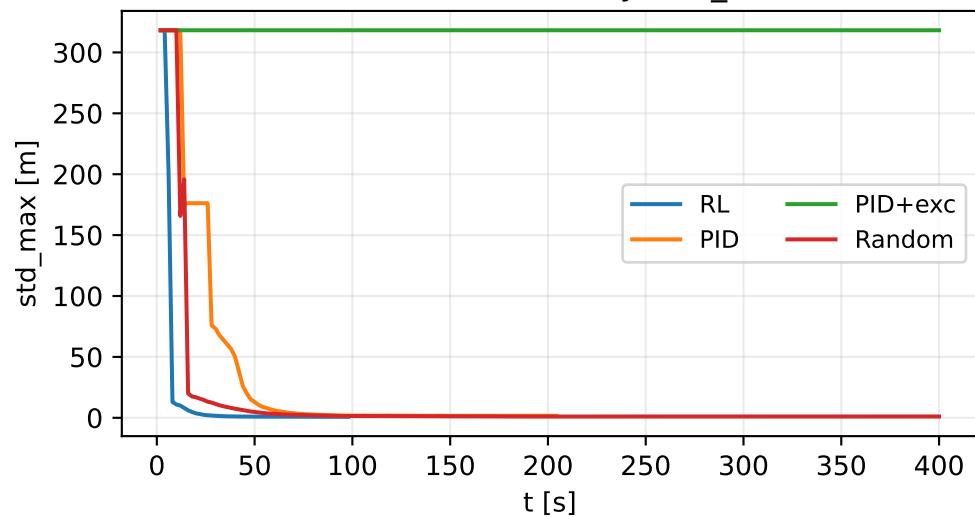
Trajectories (matched seed)



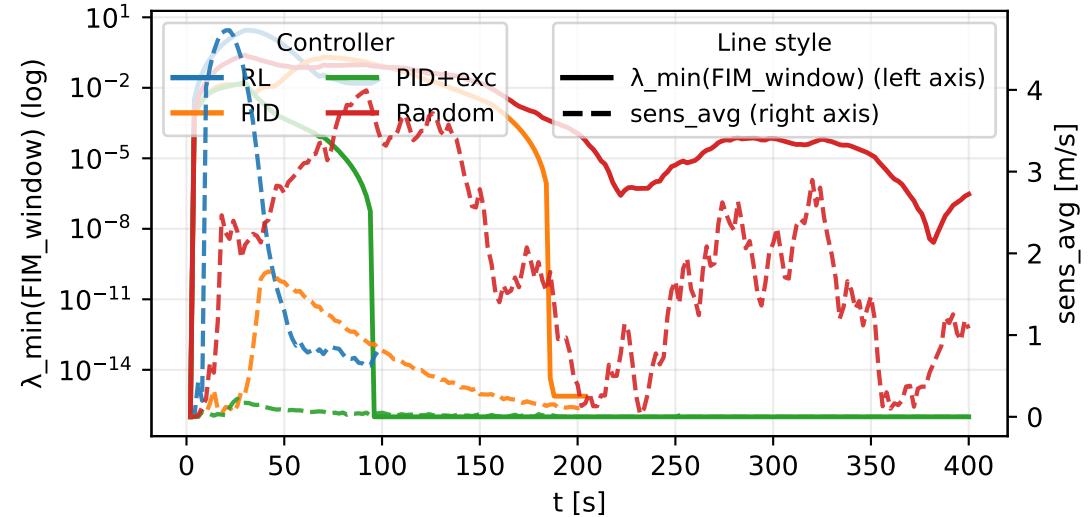
TRUE formation error



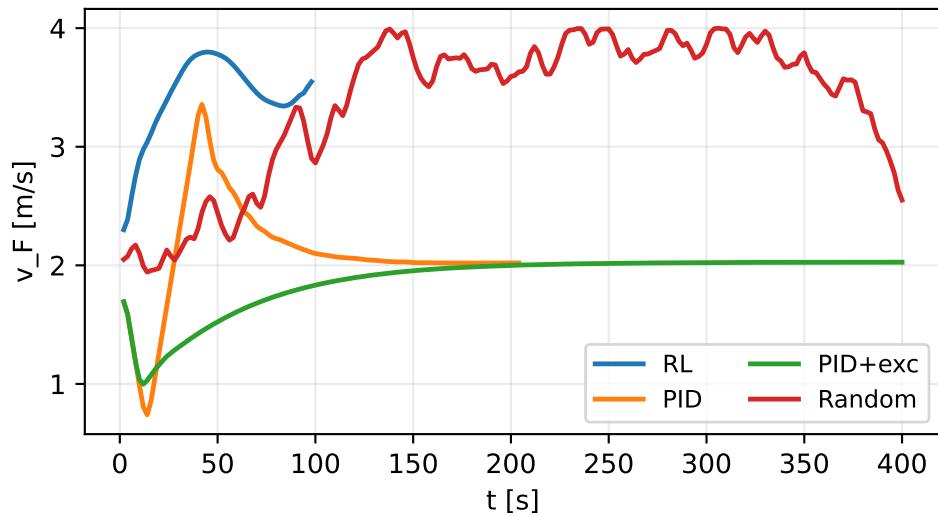
Estimator uncertainty (std_max)



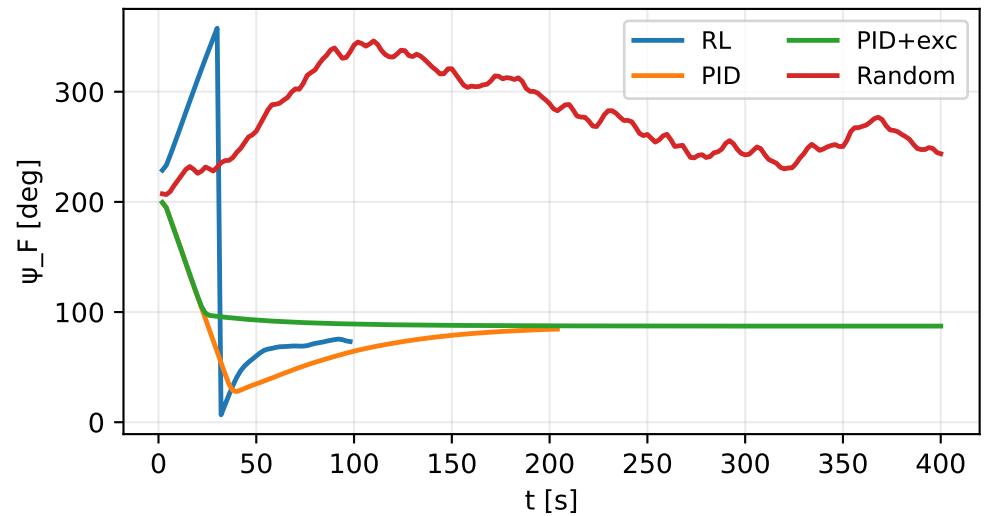
Information and excitation



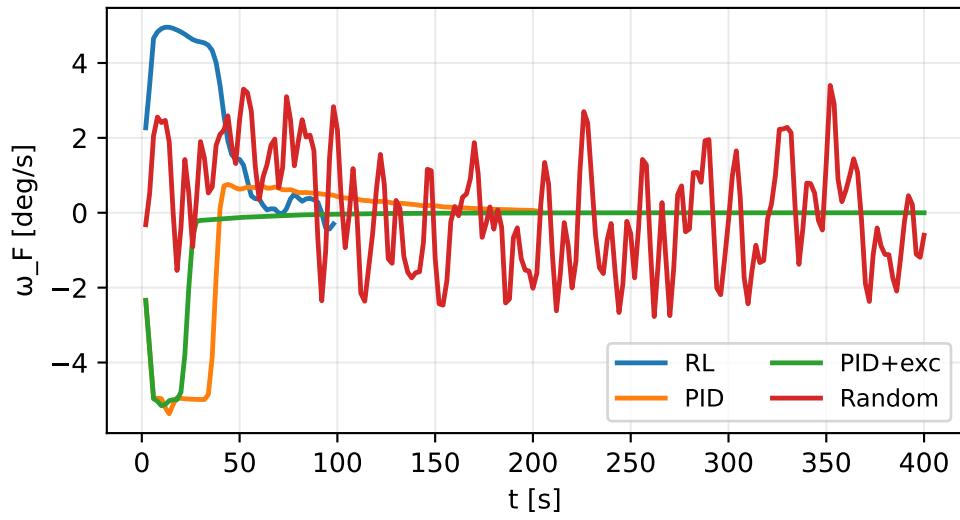
Follower speed



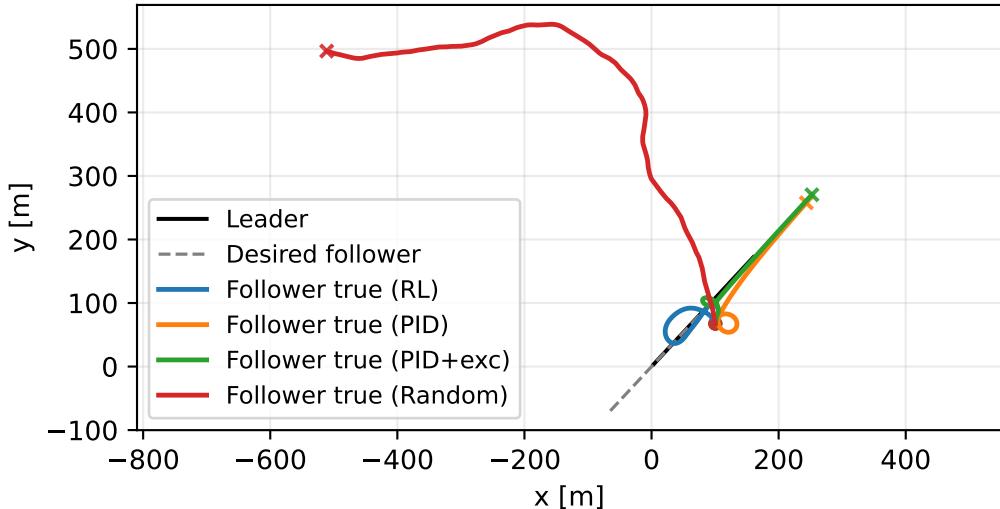
Follower course/heading



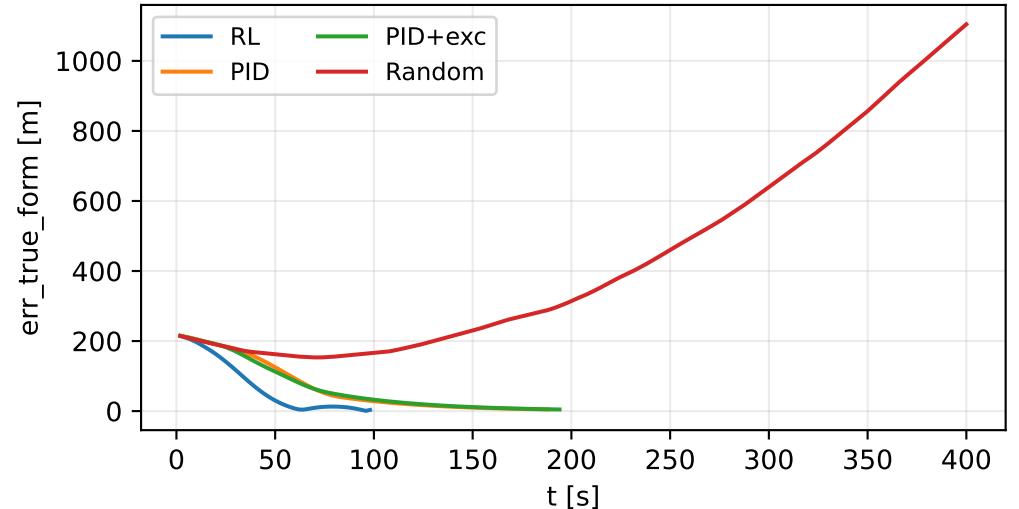
Follower angular rate



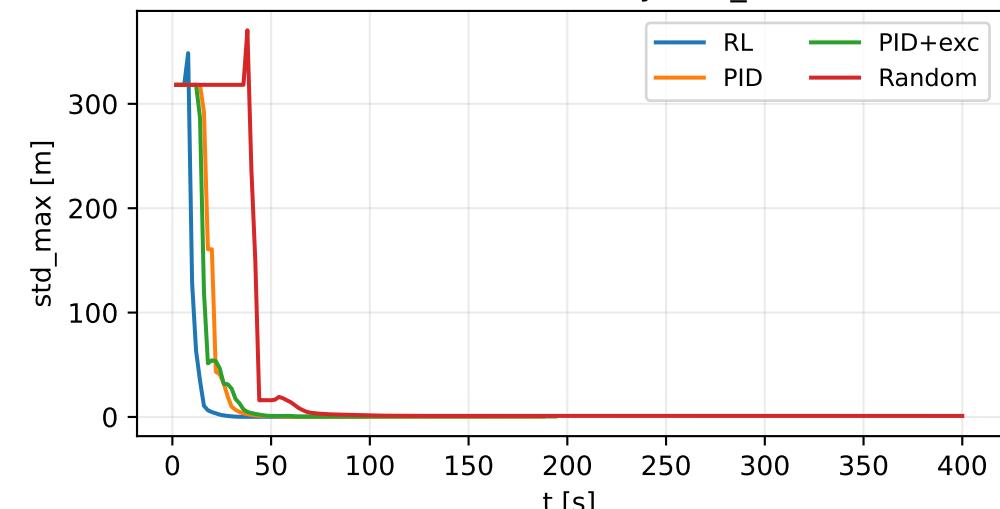
Trajectories (matched seed)



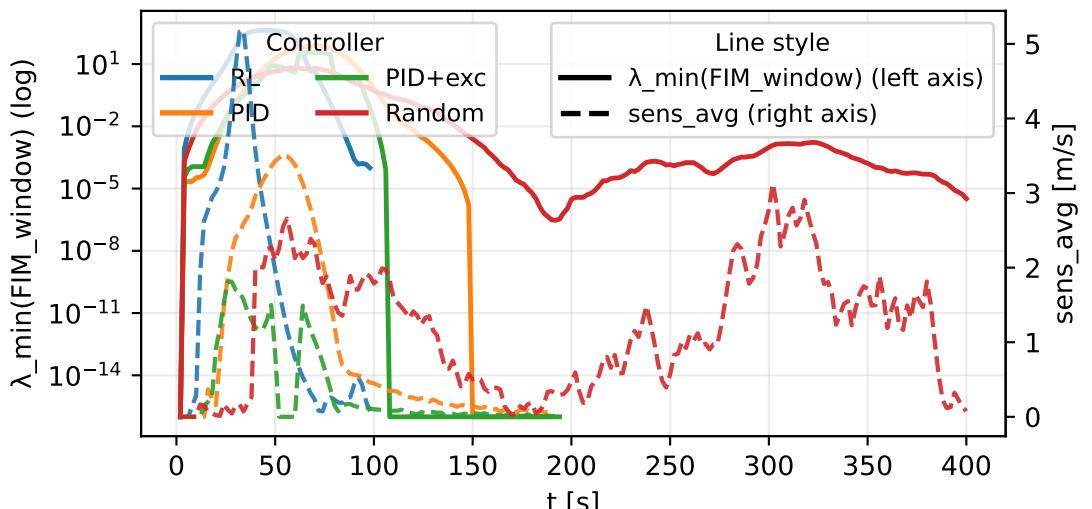
TRUE formation error



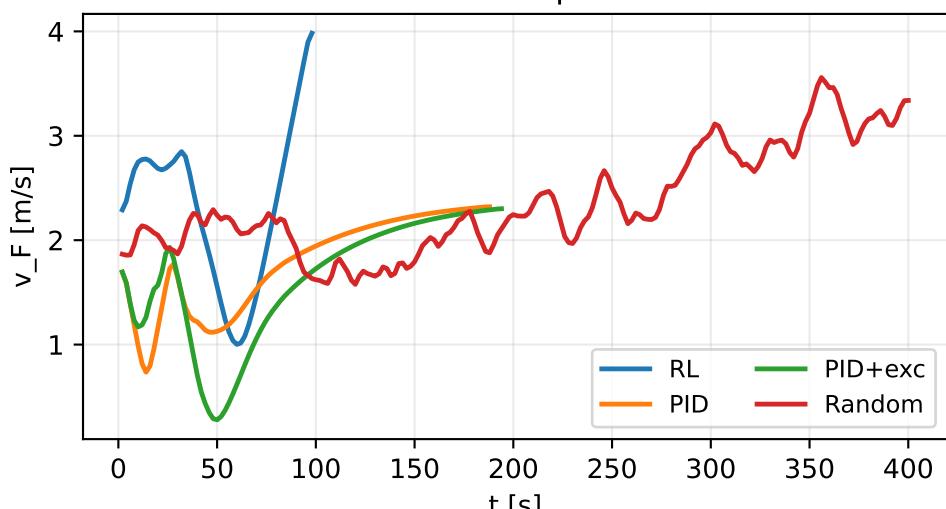
Estimator uncertainty (std_max)



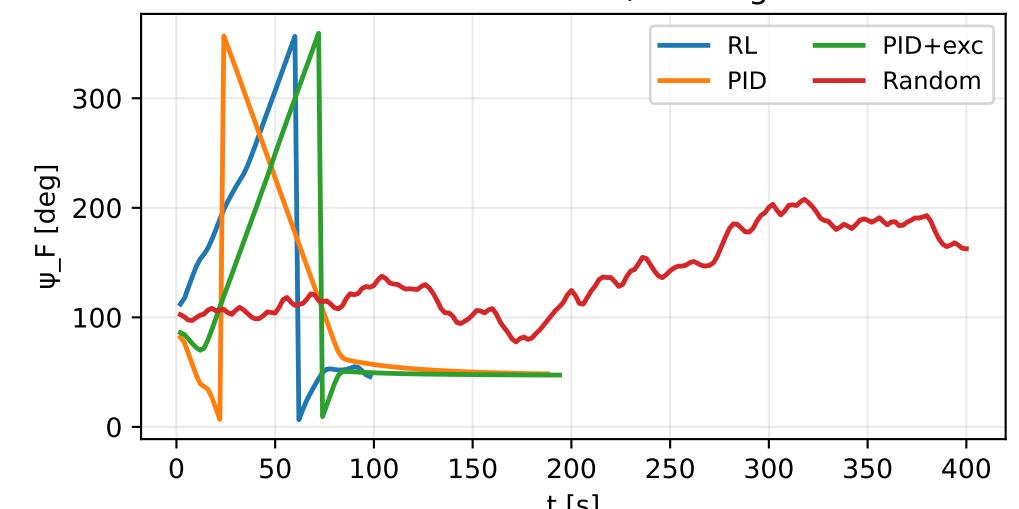
Information and excitation



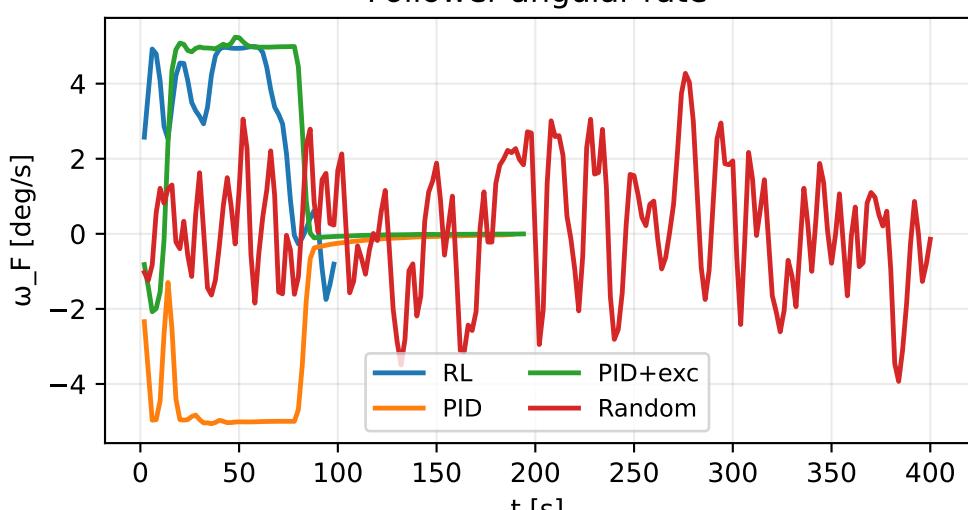
Follower speed



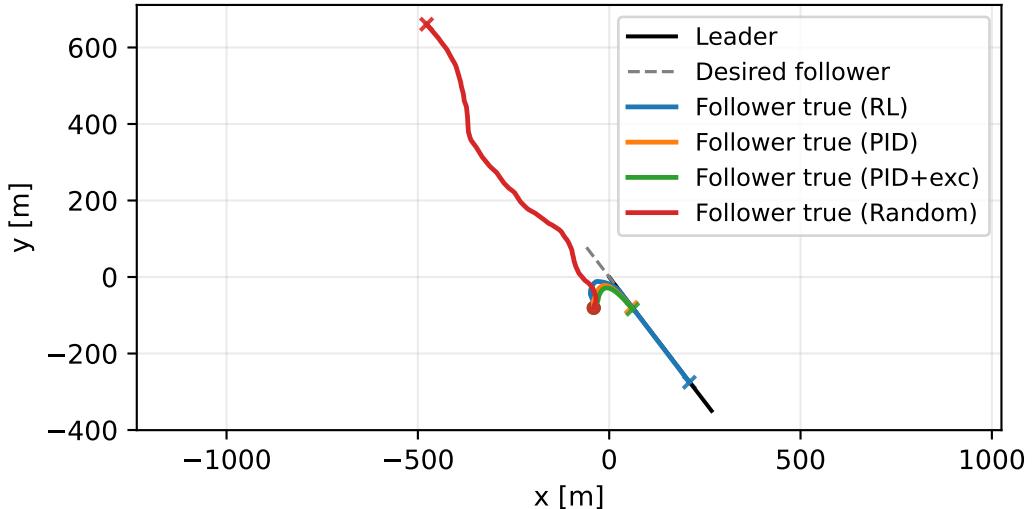
Follower course/heading



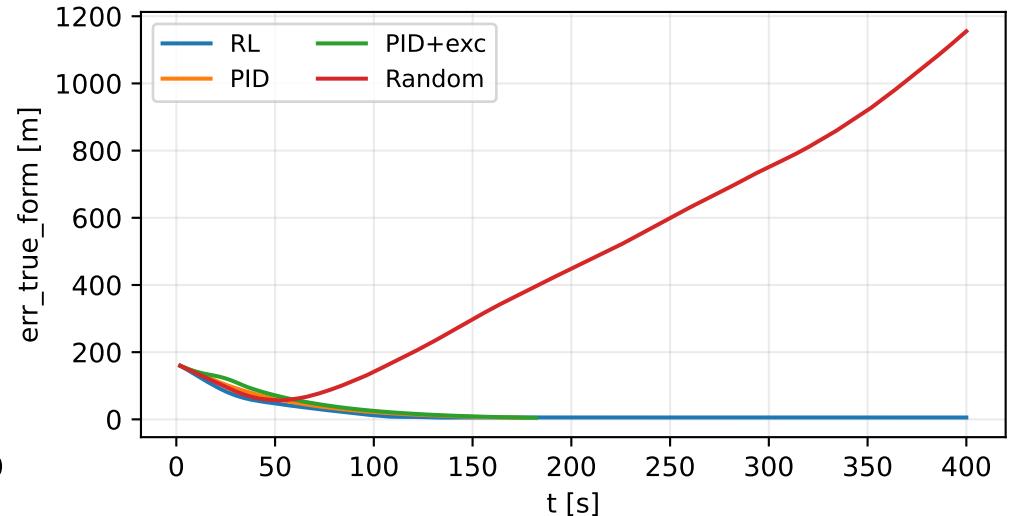
Follower angular rate



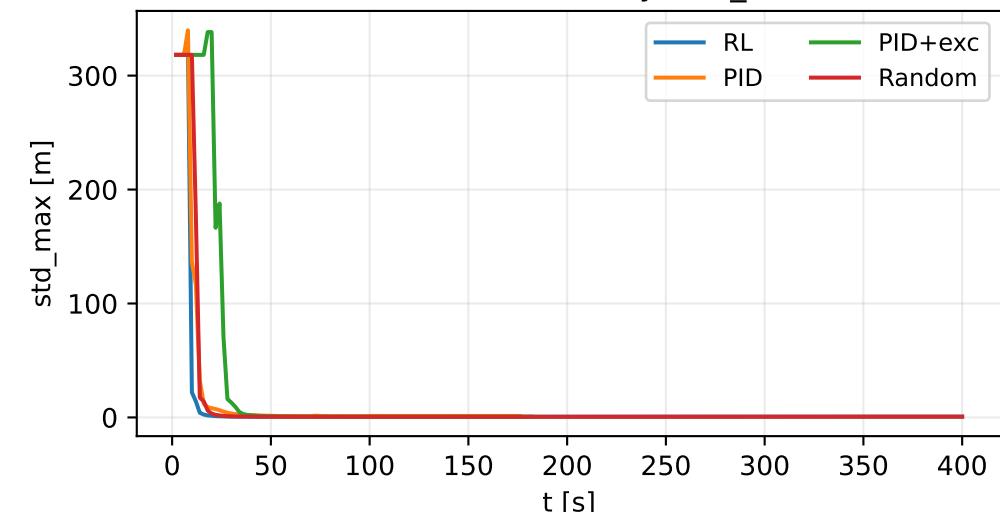
Trajectories (matched seed)



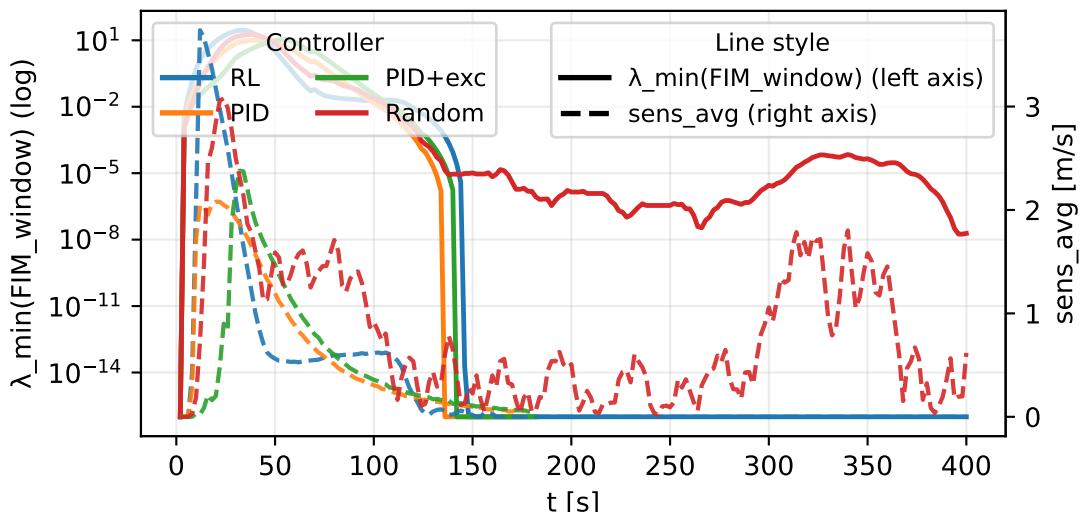
TRUE formation error



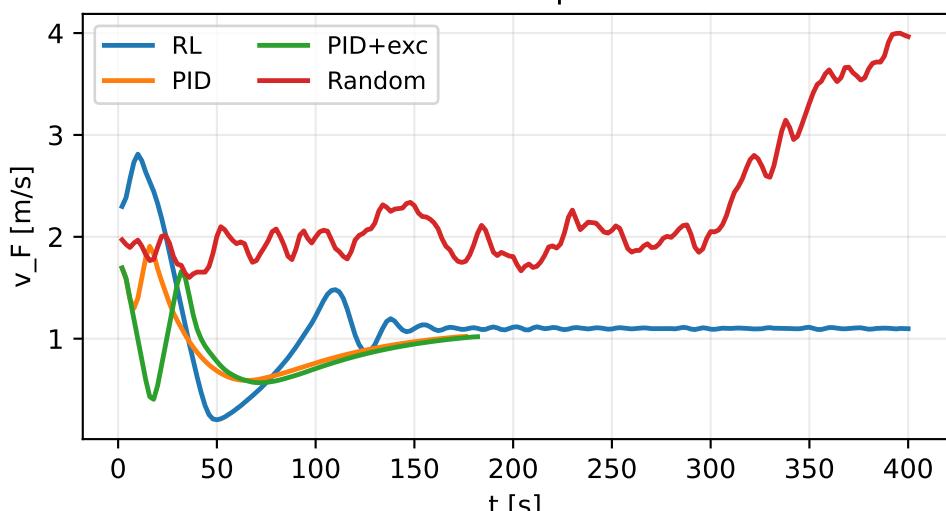
Estimator uncertainty (std_max)



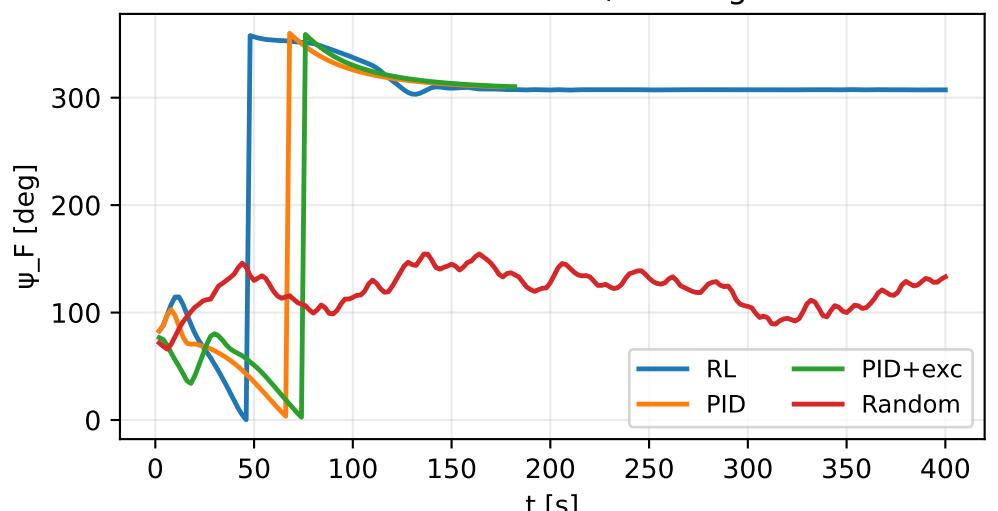
Information and excitation



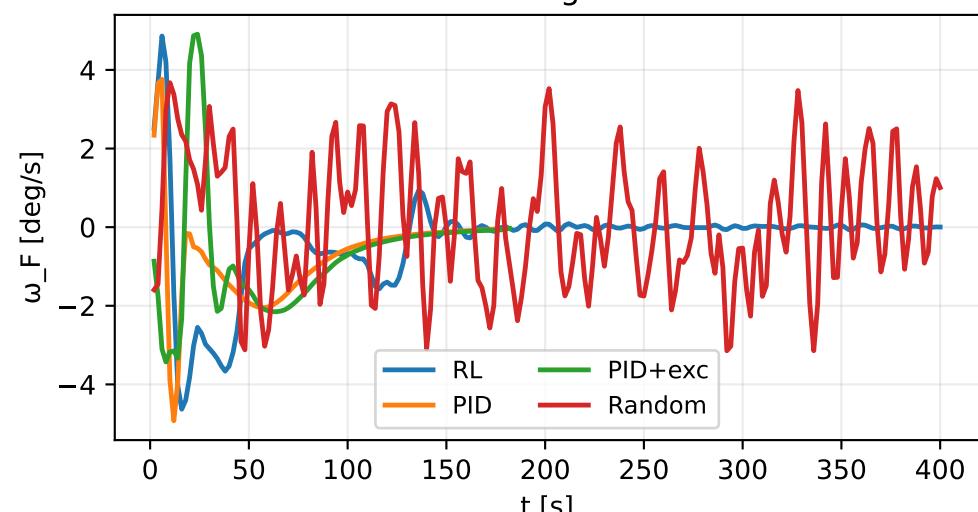
Follower speed



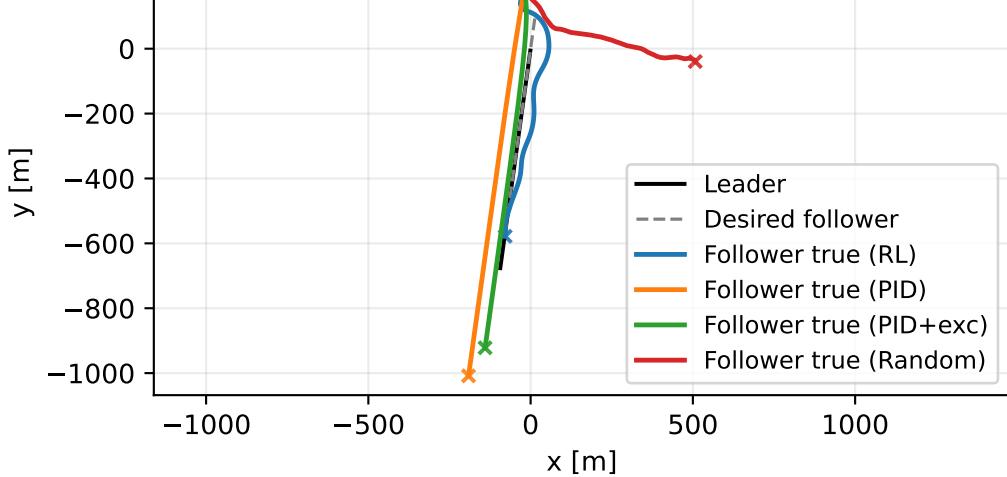
Follower course/heading



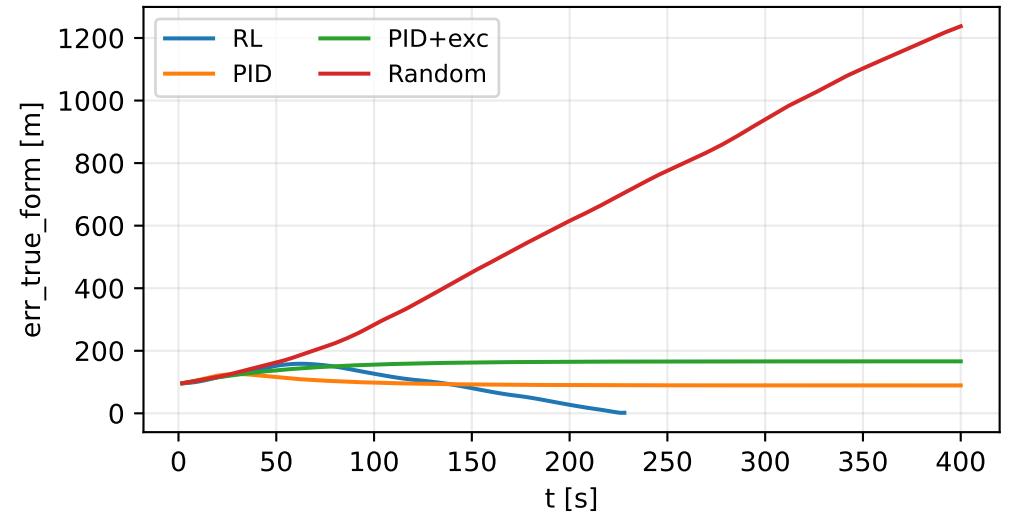
Follower angular rate



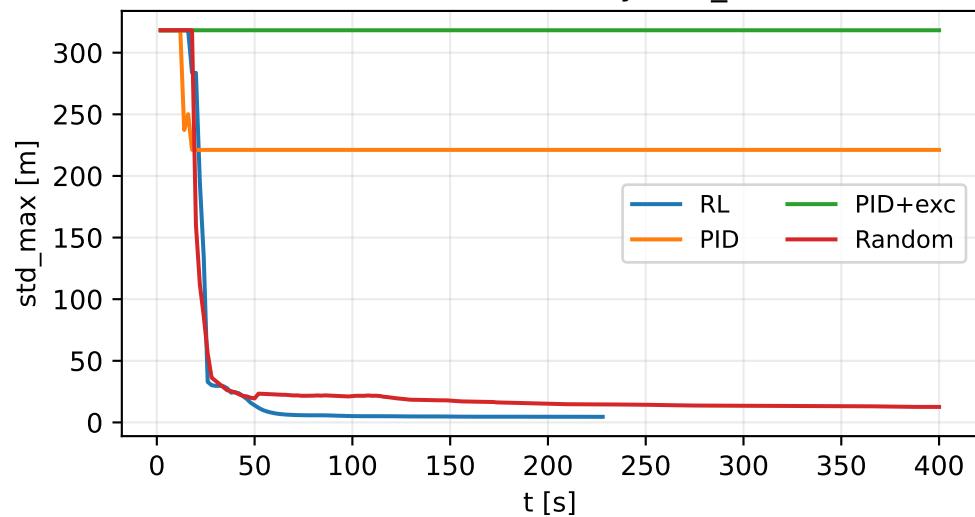
Trajectories (matched seed)



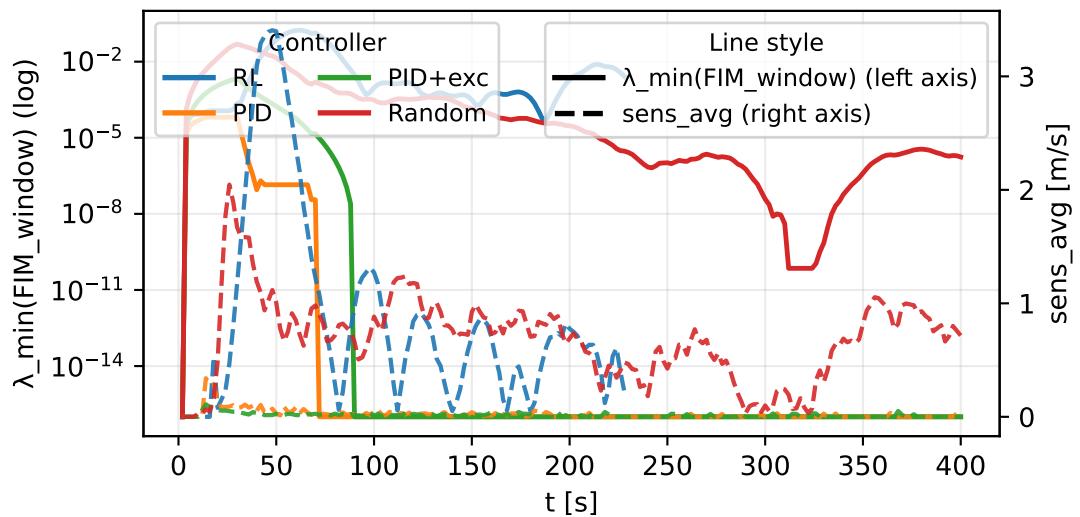
TRUE formation error



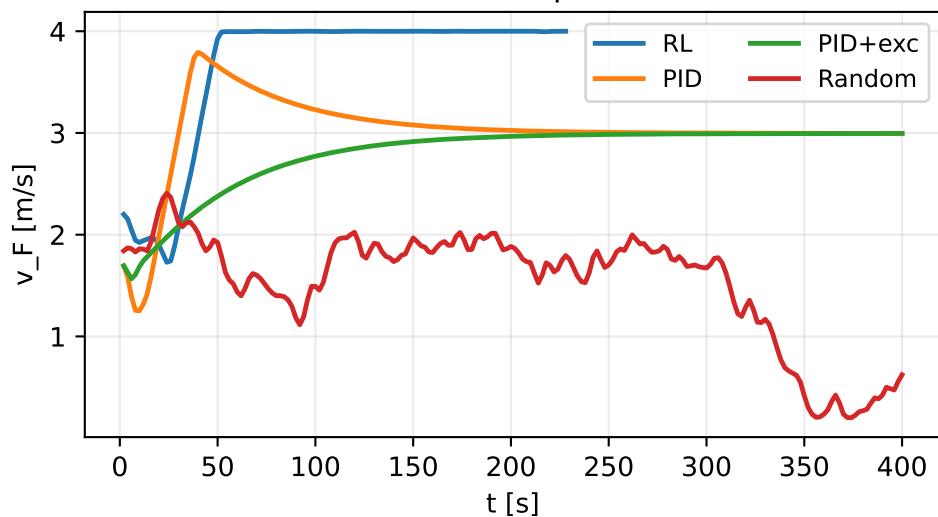
Estimator uncertainty (std_max)



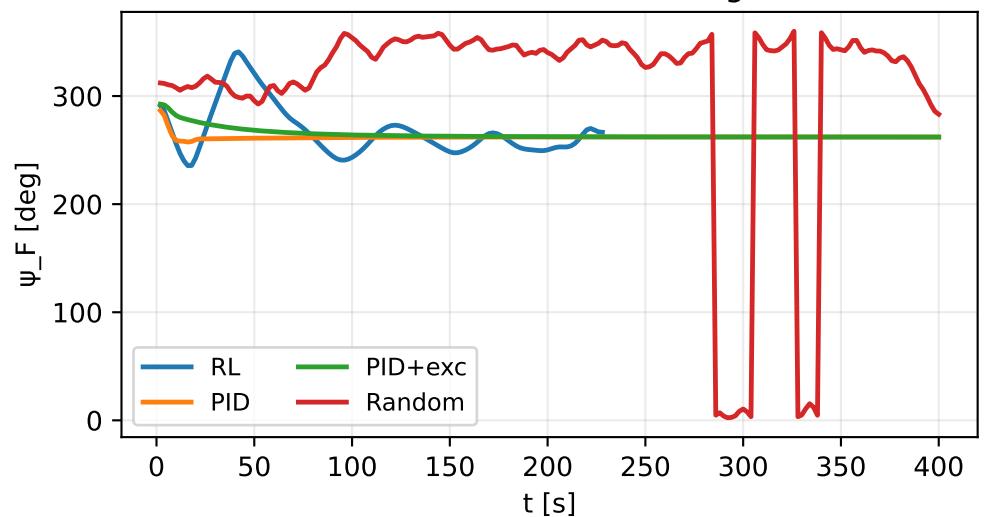
Information and excitation



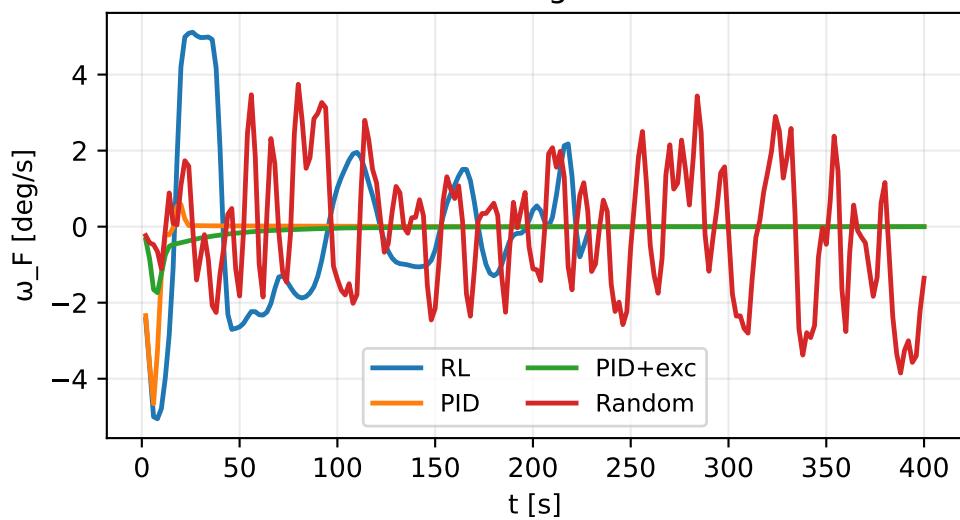
Follower speed



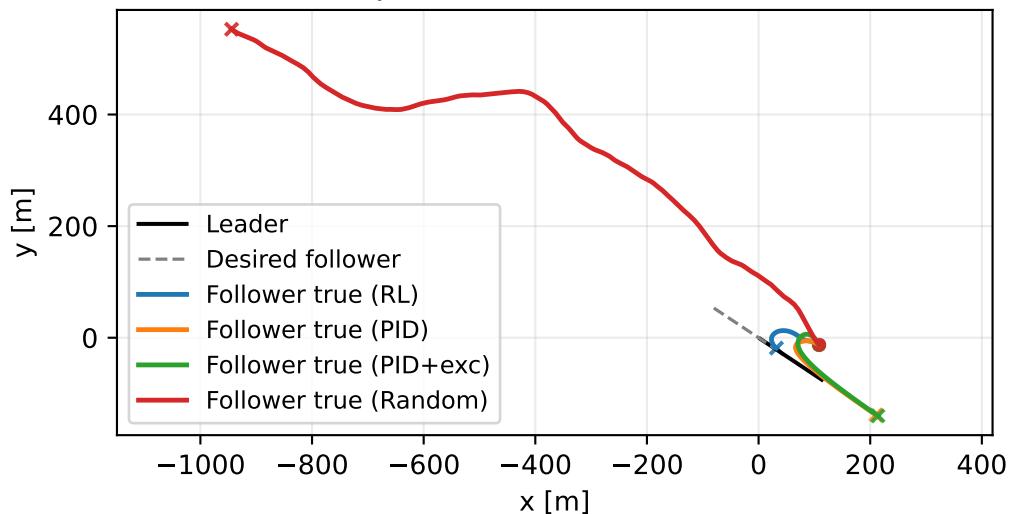
Follower course/heading



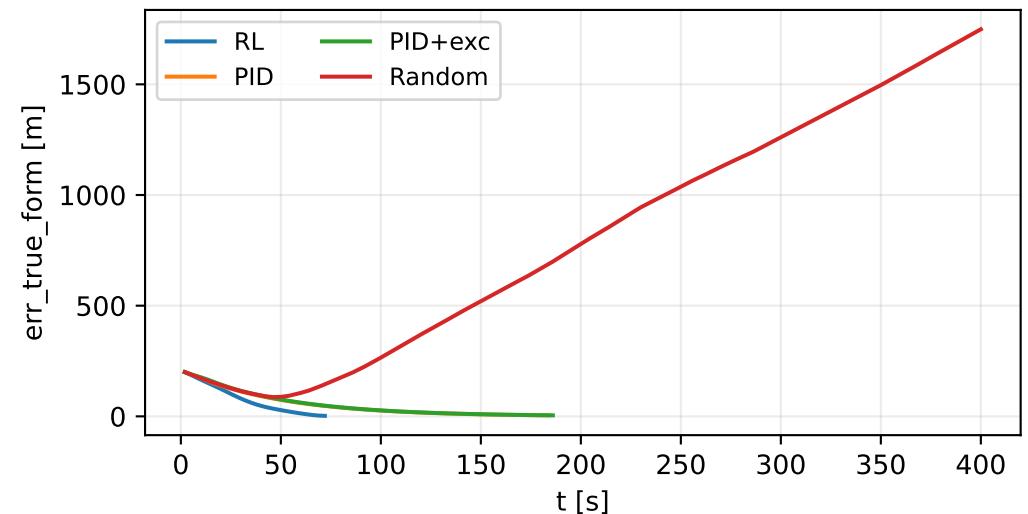
Follower angular rate



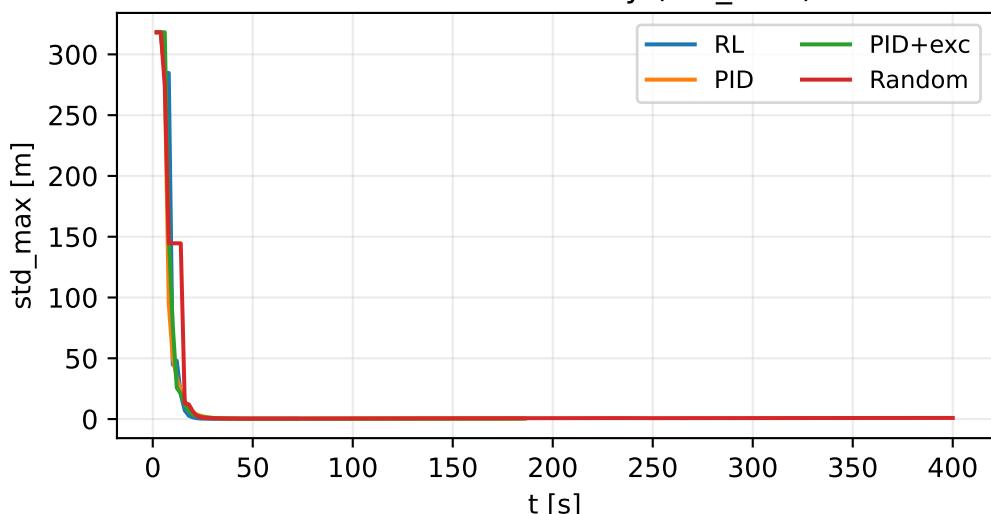
Trajectories (matched seed)



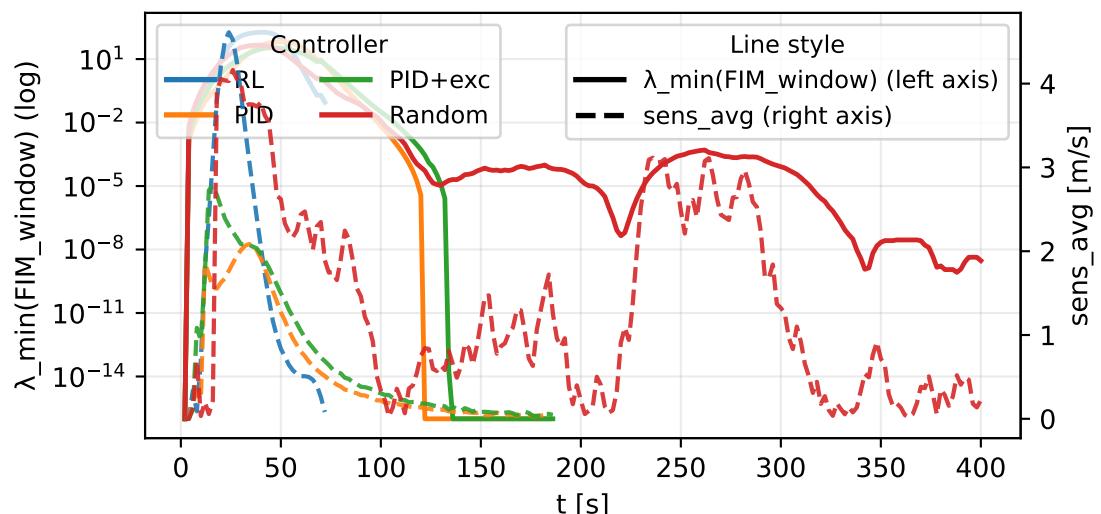
TRUE formation error



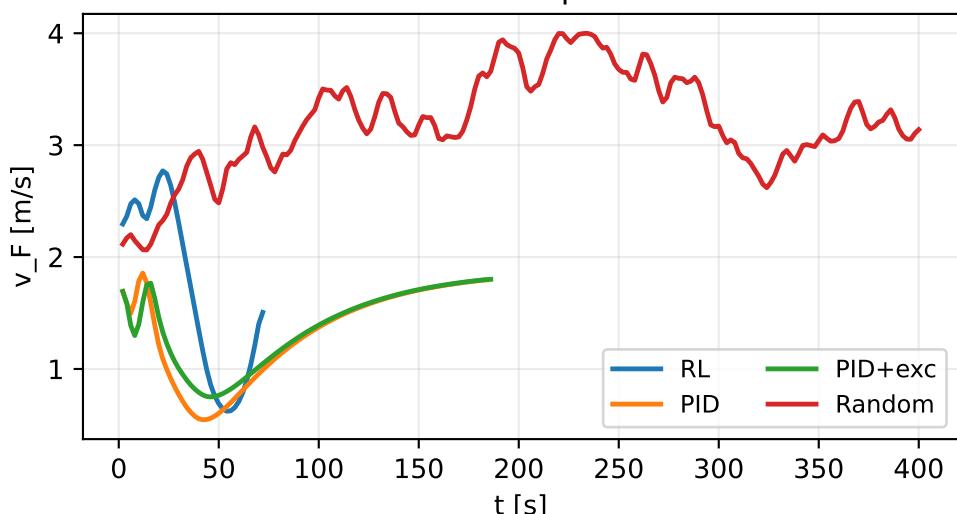
Estimator uncertainty (std_max)



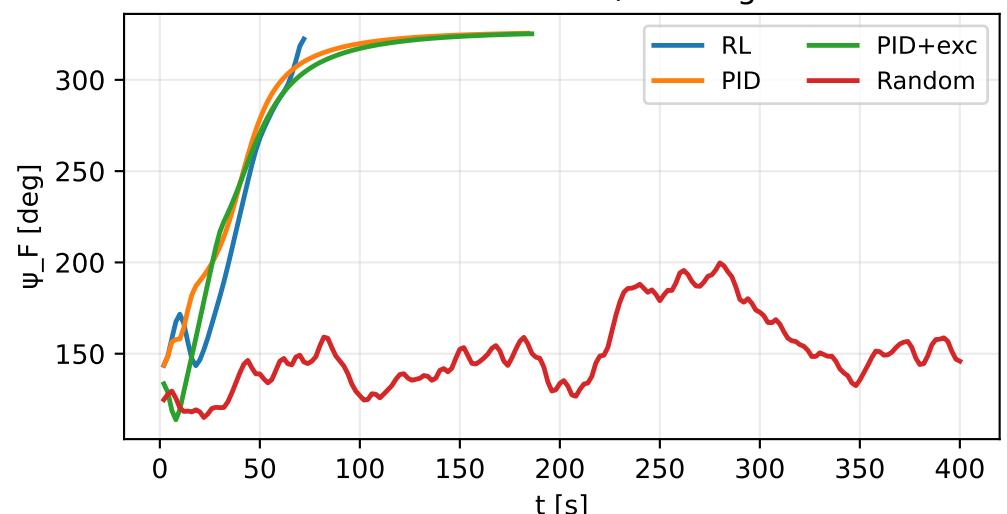
Information and excitation



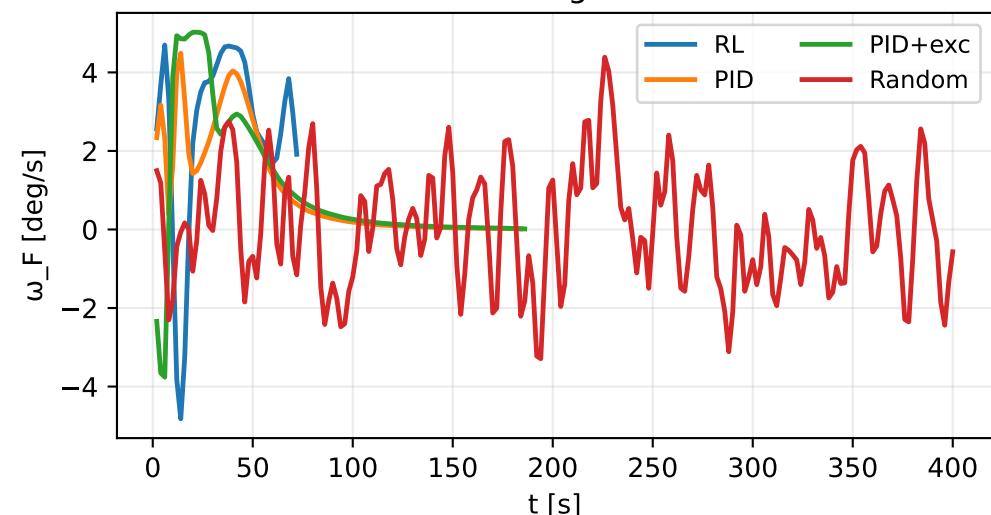
Follower speed



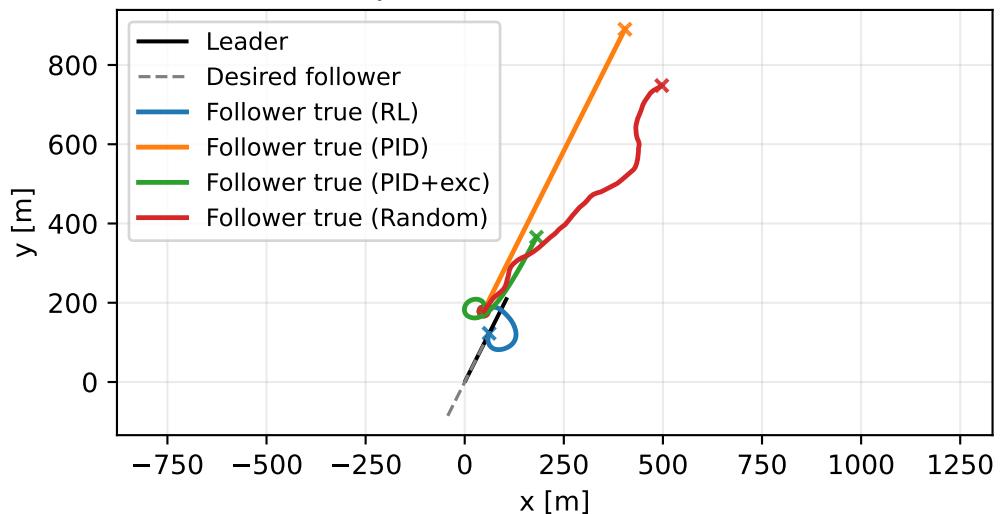
Follower course/heading



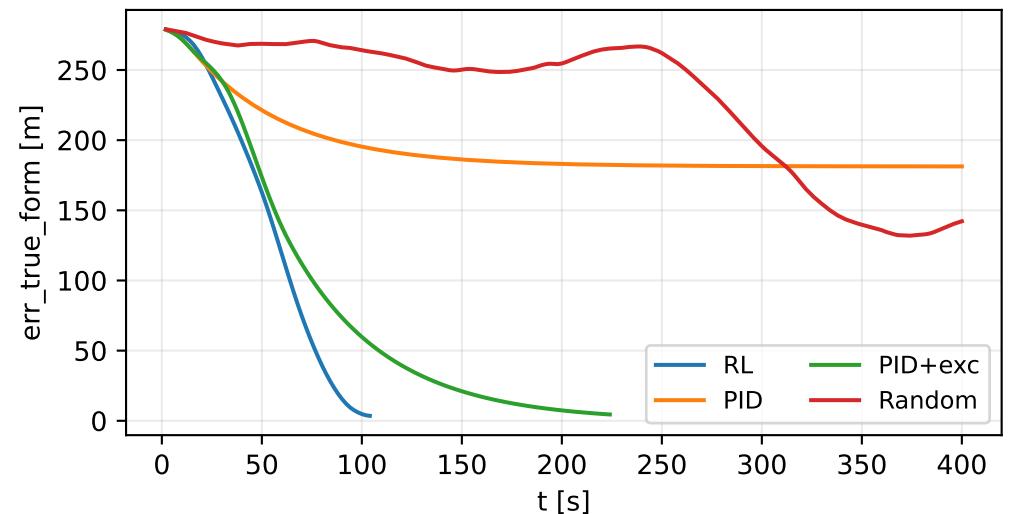
Follower angular rate



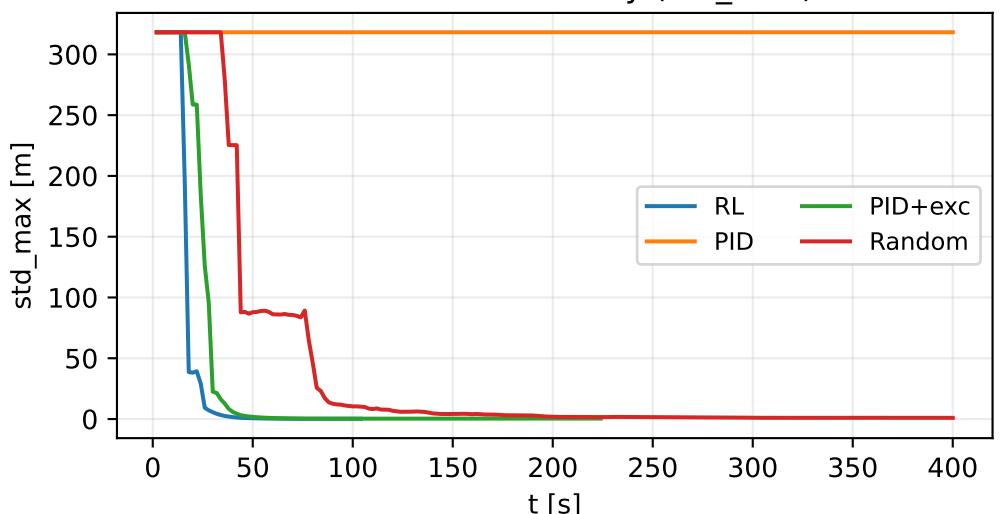
Trajectories (matched seed)



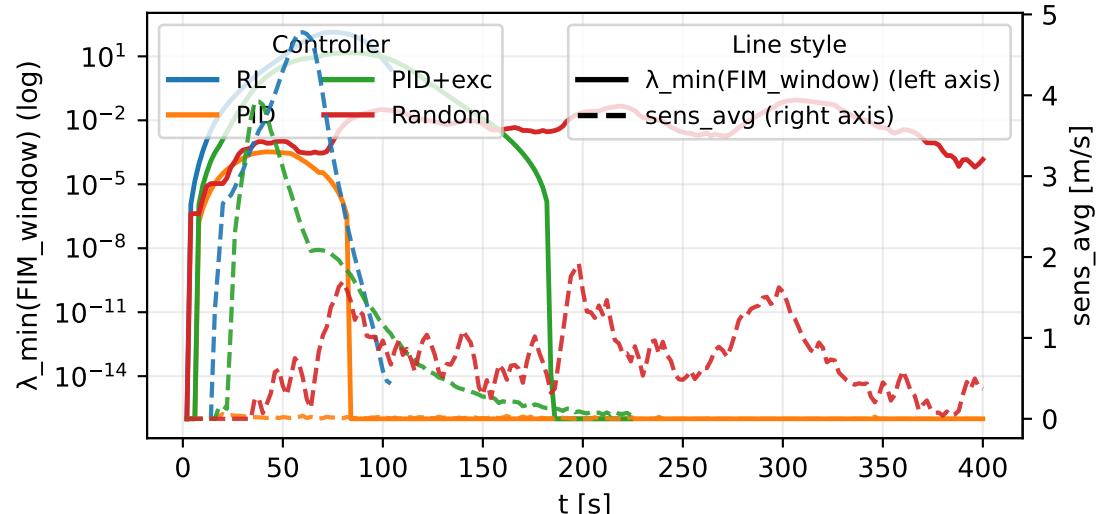
TRUE formation error



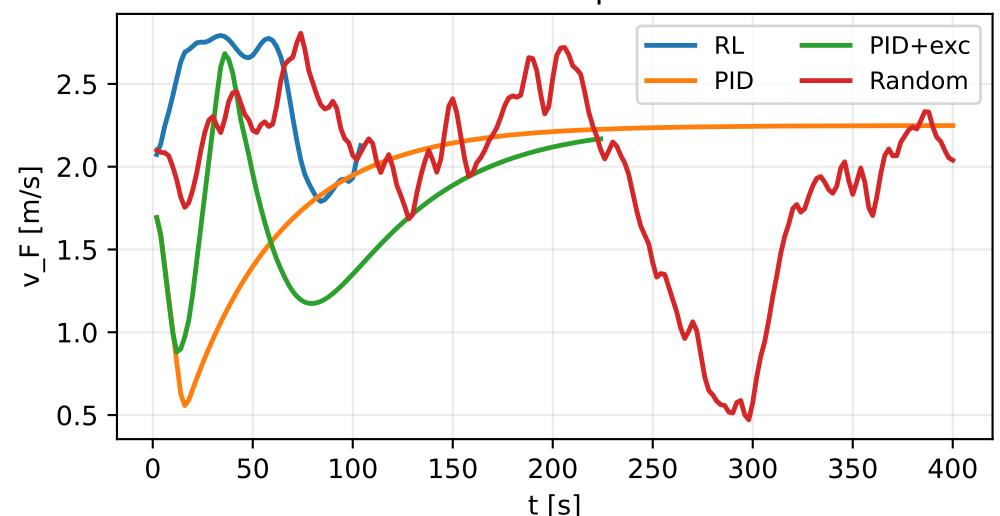
Estimator uncertainty (std_max)



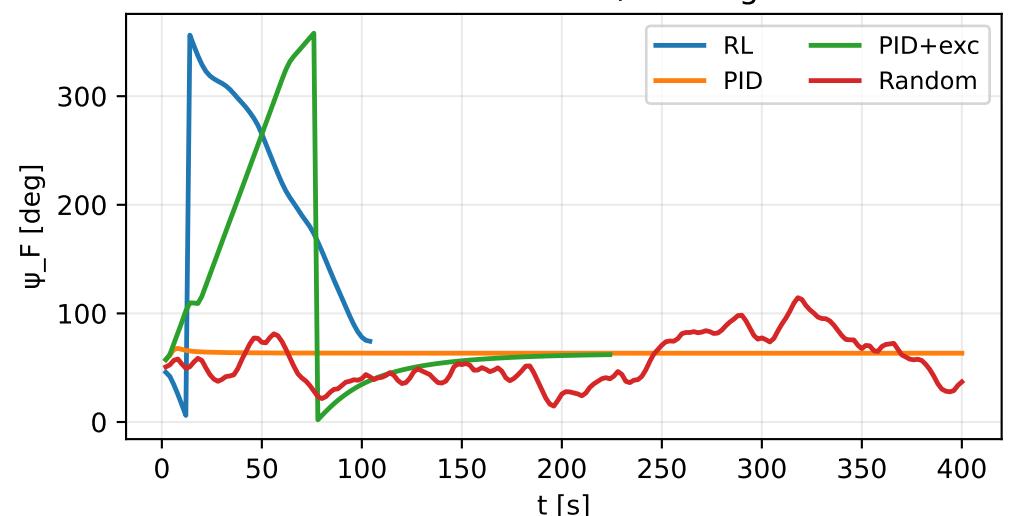
Information and excitation



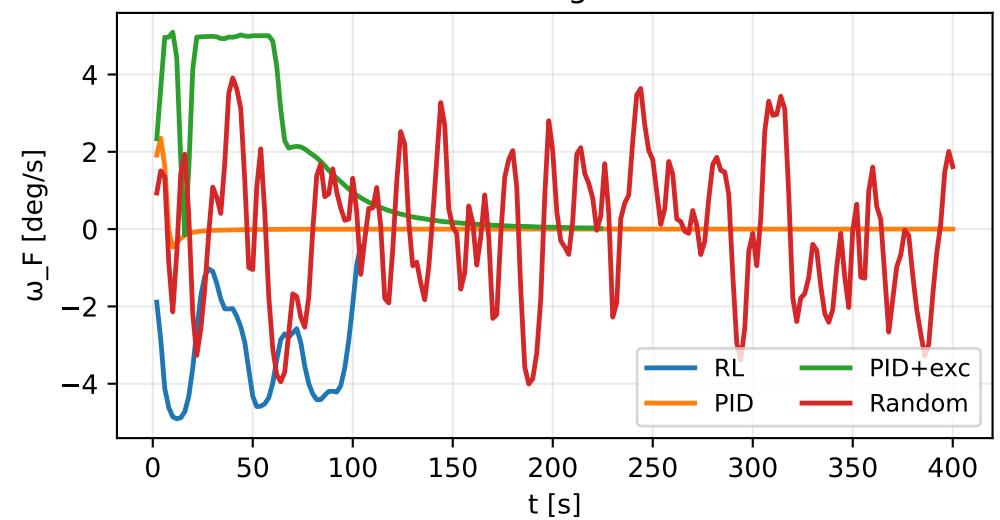
Follower speed



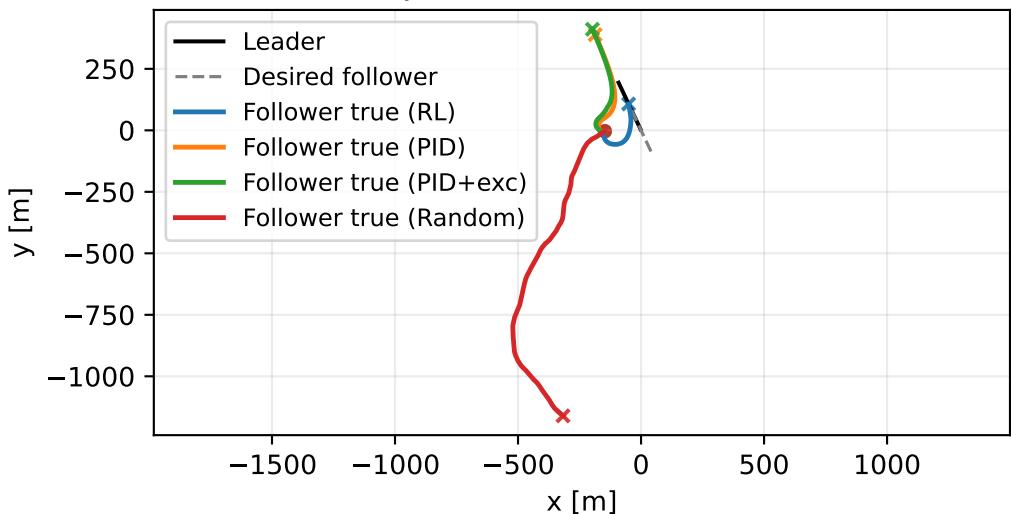
Follower course/heading



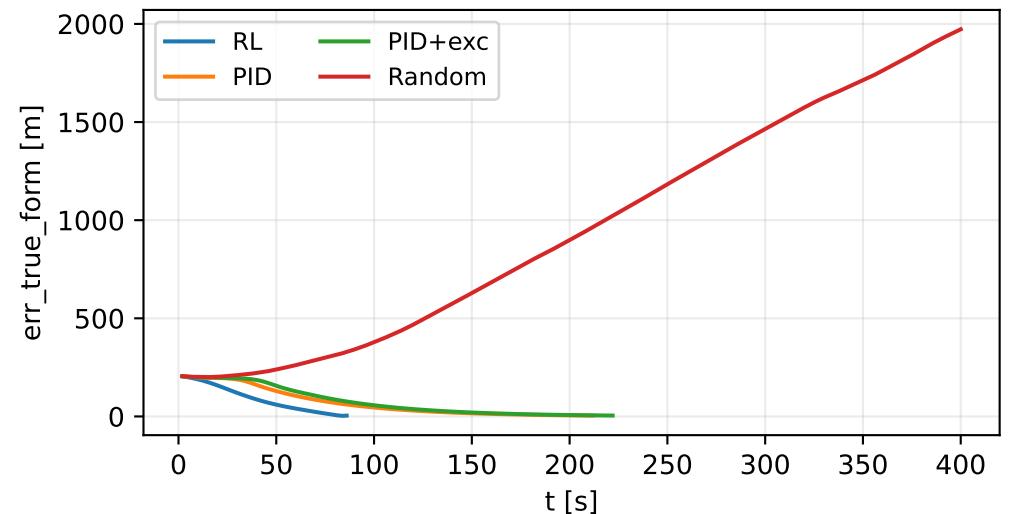
Follower angular rate



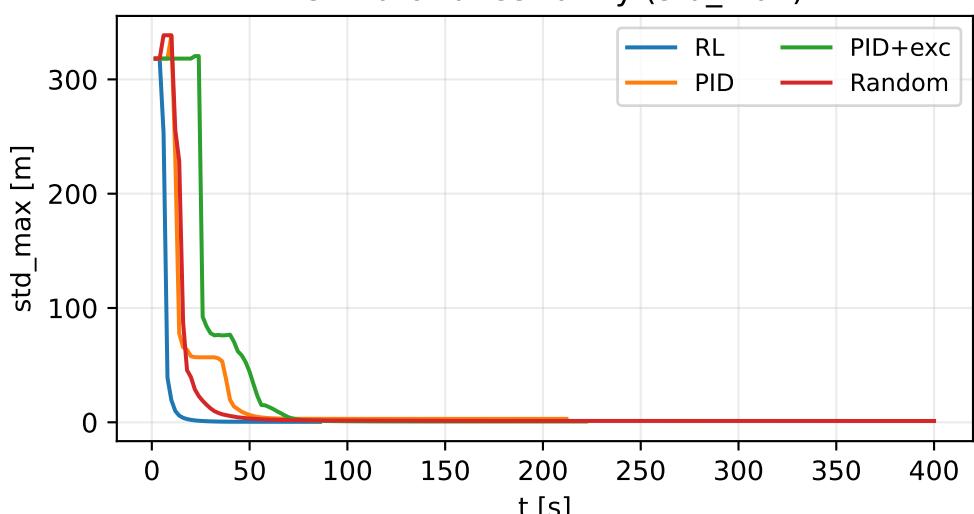
Trajectories (matched seed)



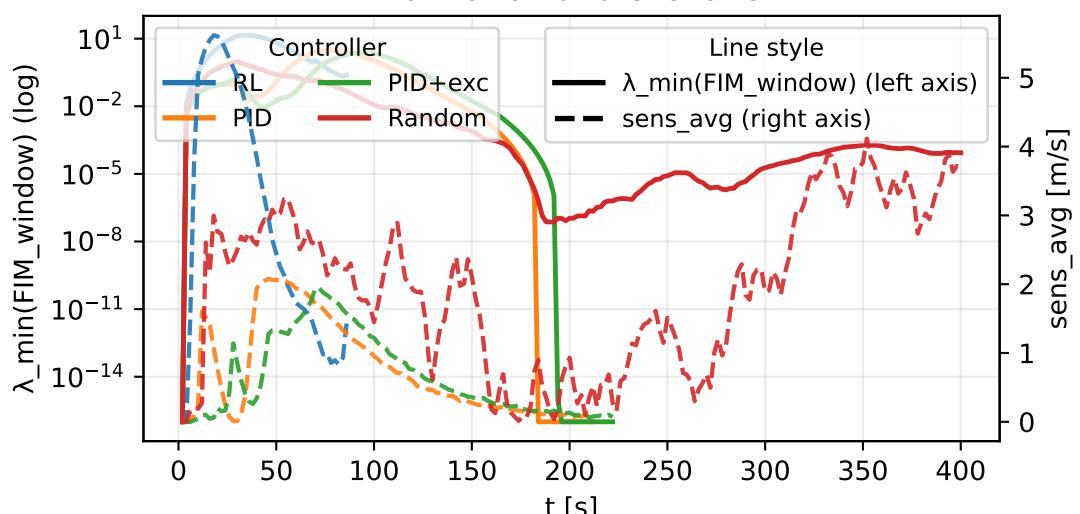
TRUE formation error



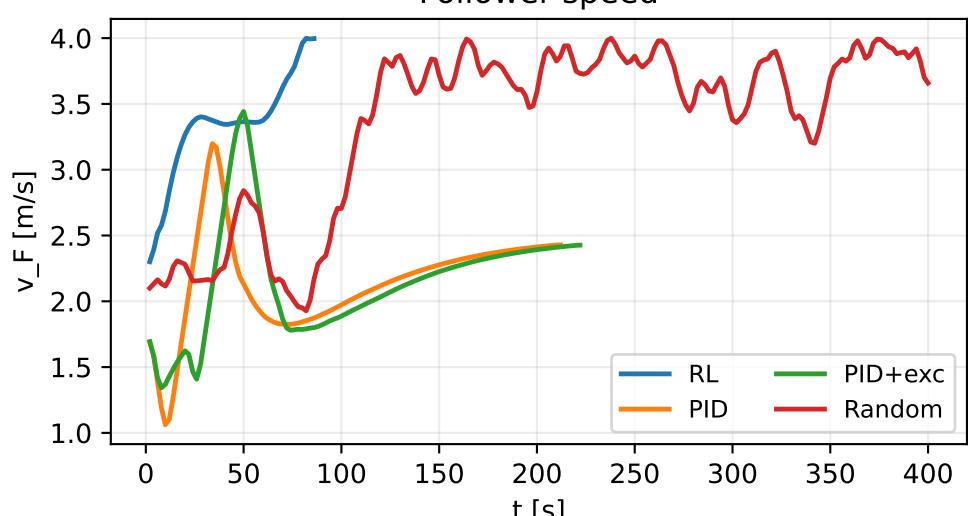
Estimator uncertainty (std_max)



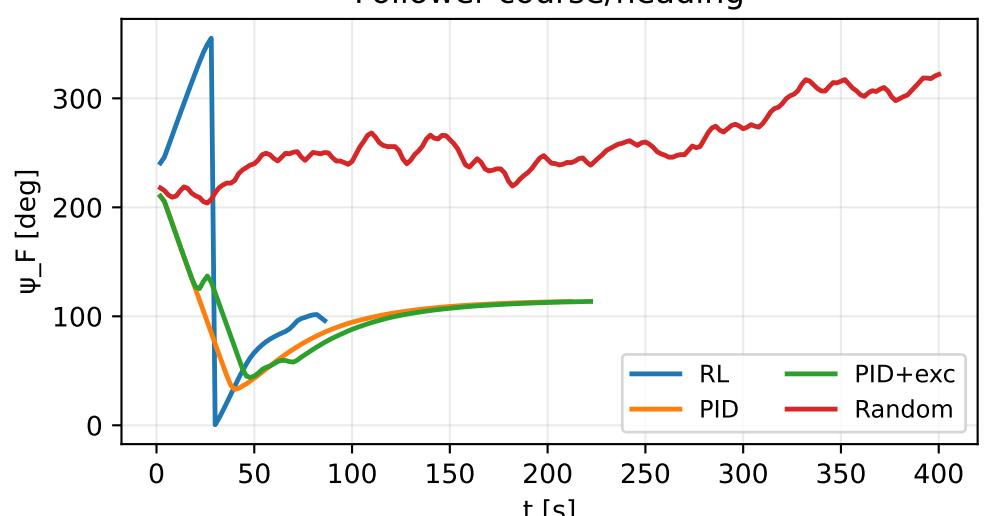
Information and excitation



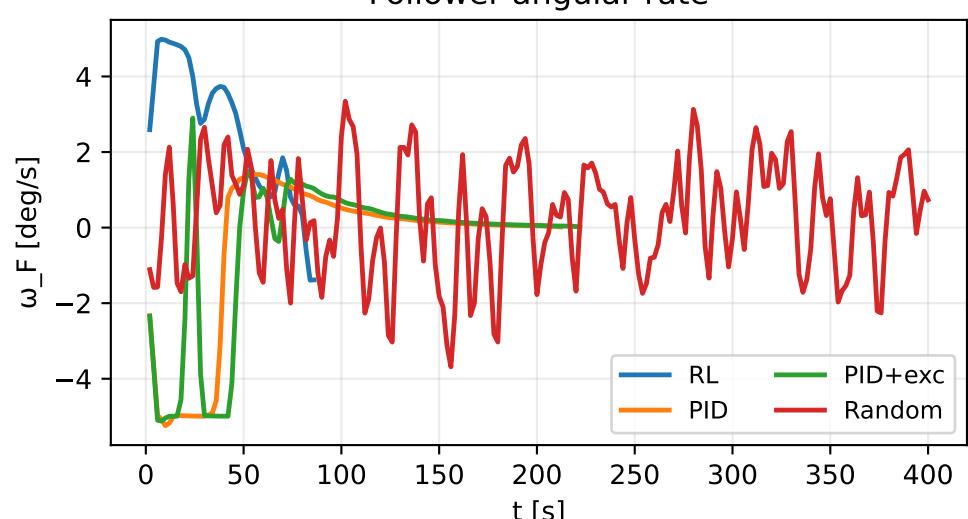
Follower speed



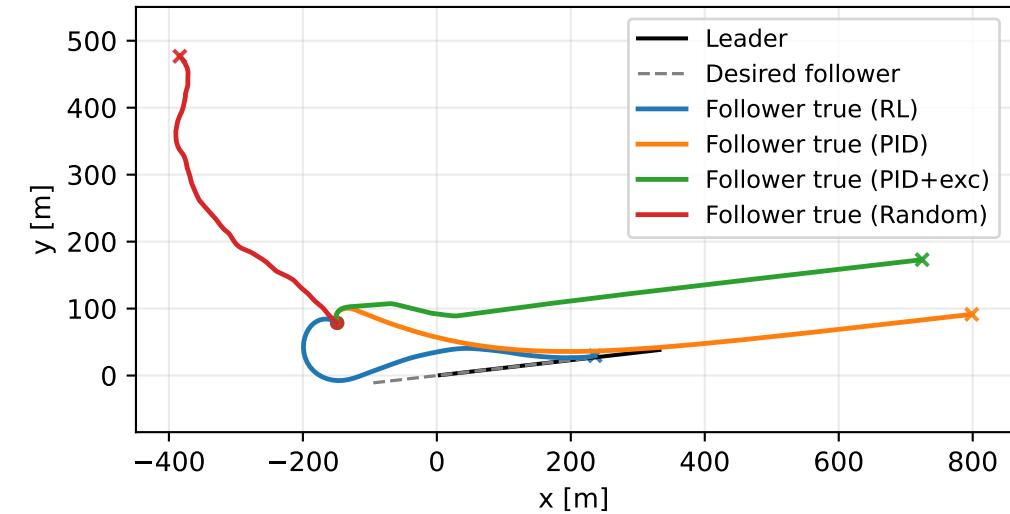
Follower course/heading



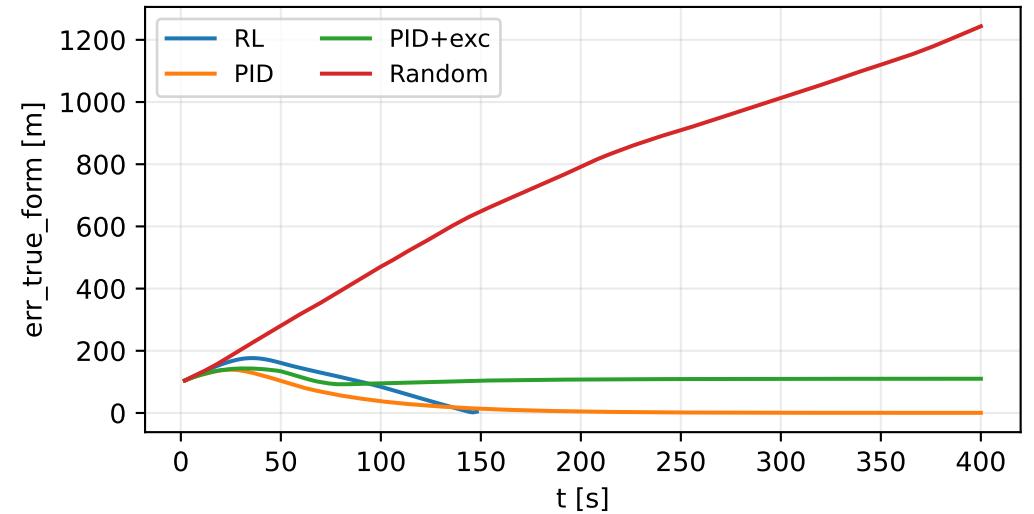
Follower angular rate



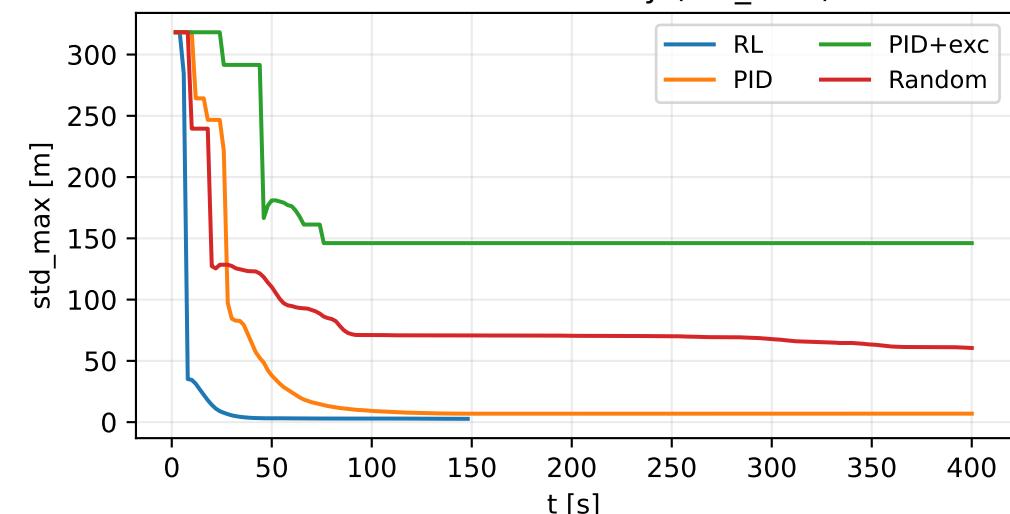
Trajectories (matched seed)



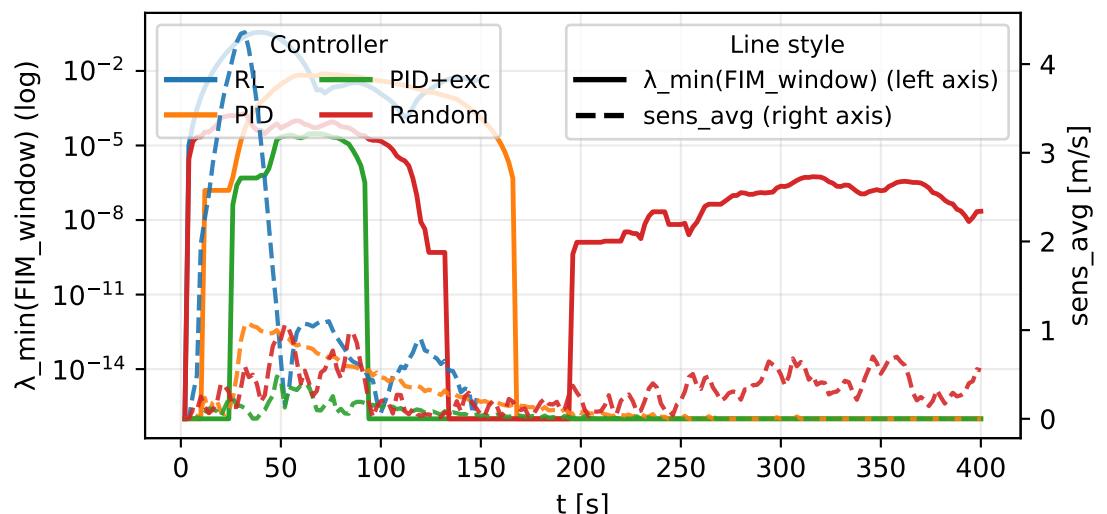
TRUE formation error



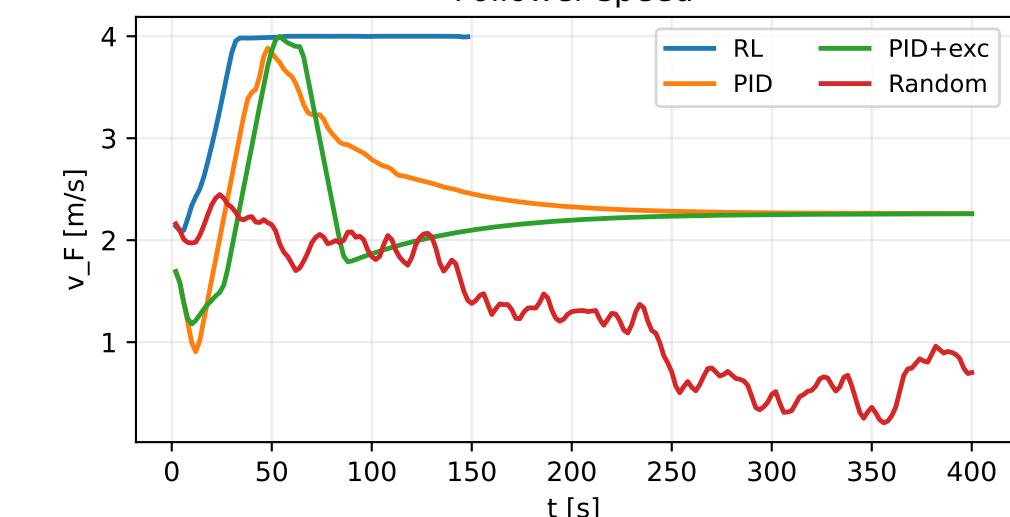
Estimator uncertainty (std_max)



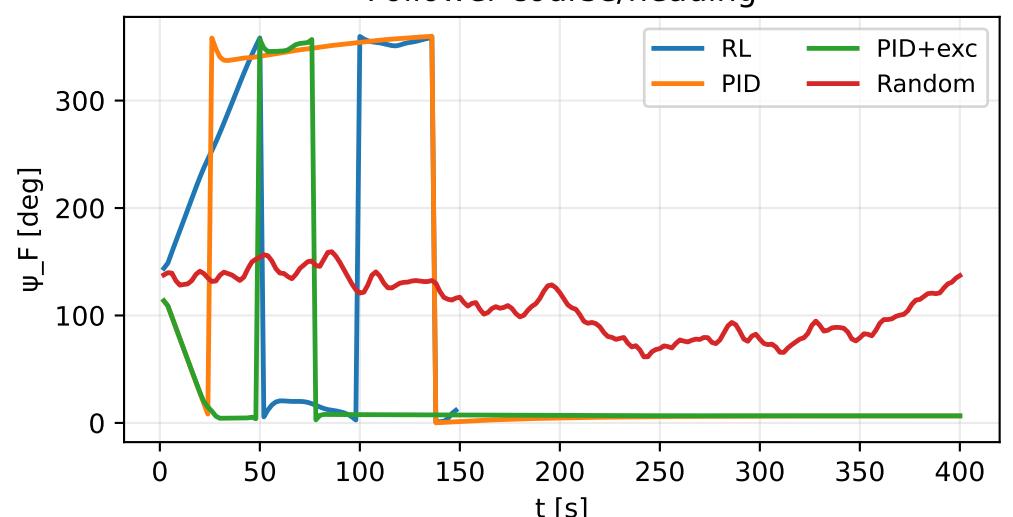
Information and excitation



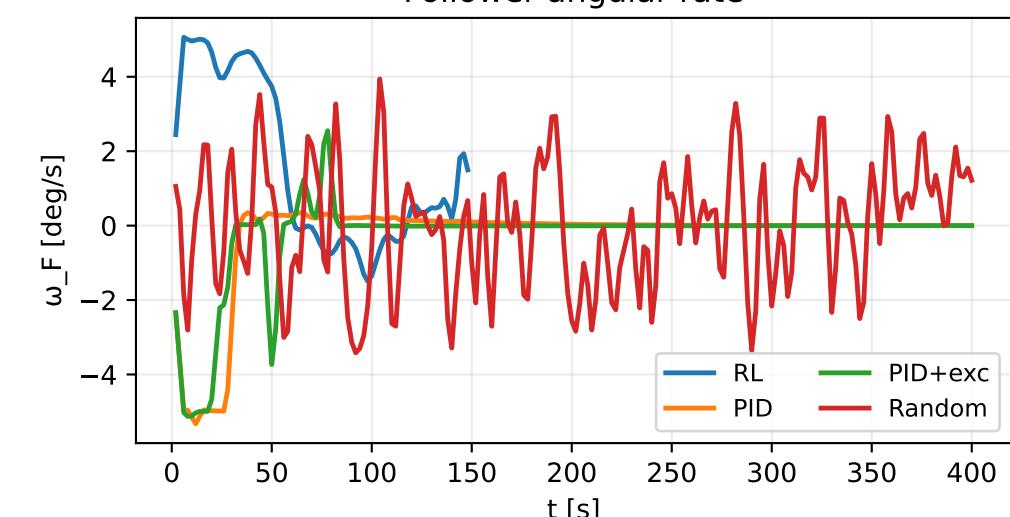
Follower speed



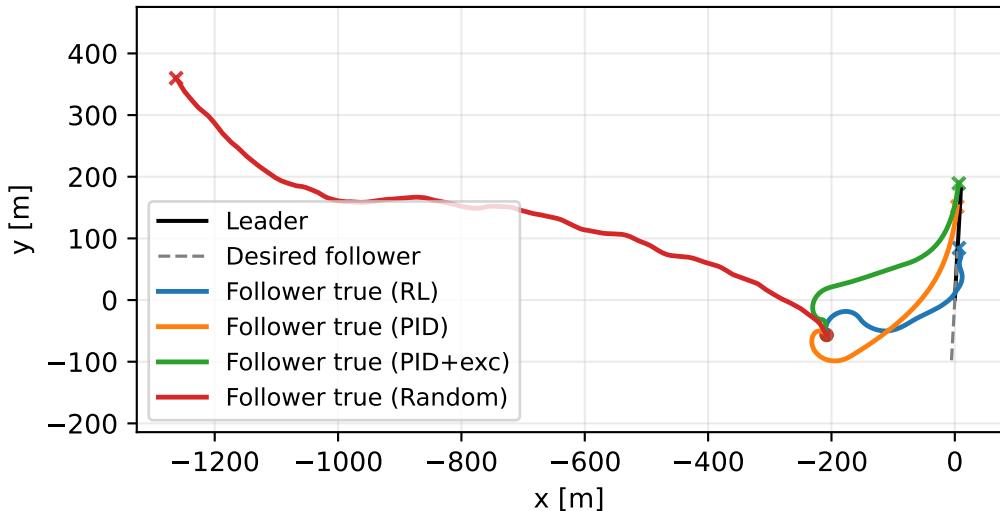
Follower course/heading



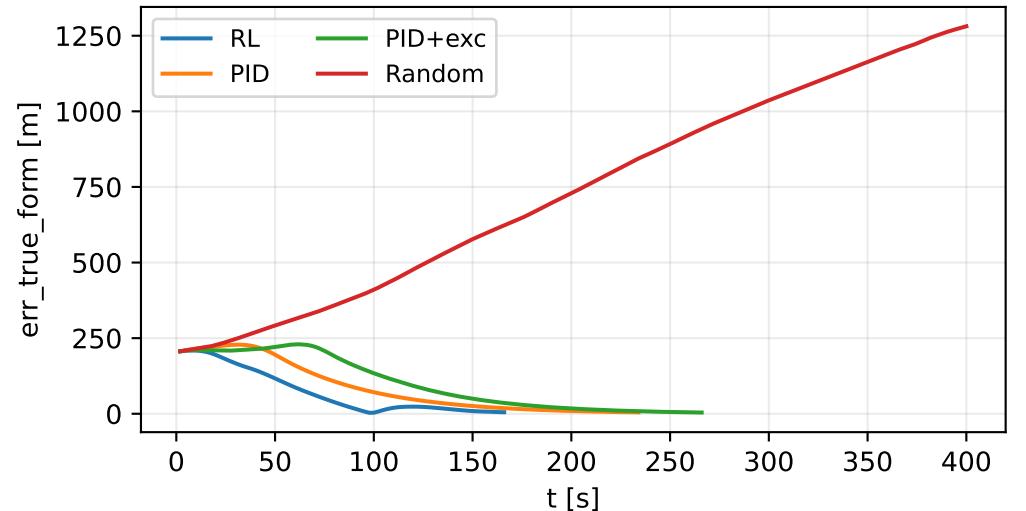
Follower angular rate



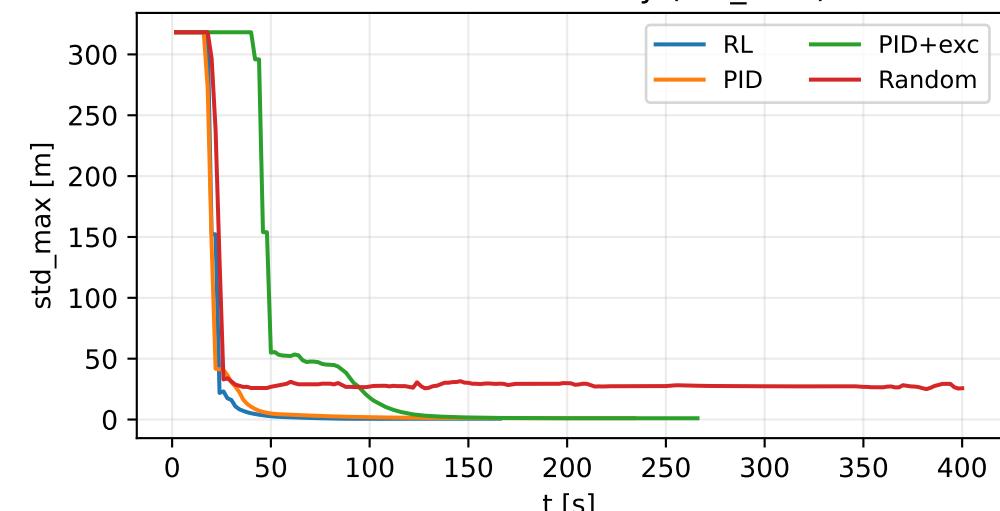
Trajectories (matched seed)



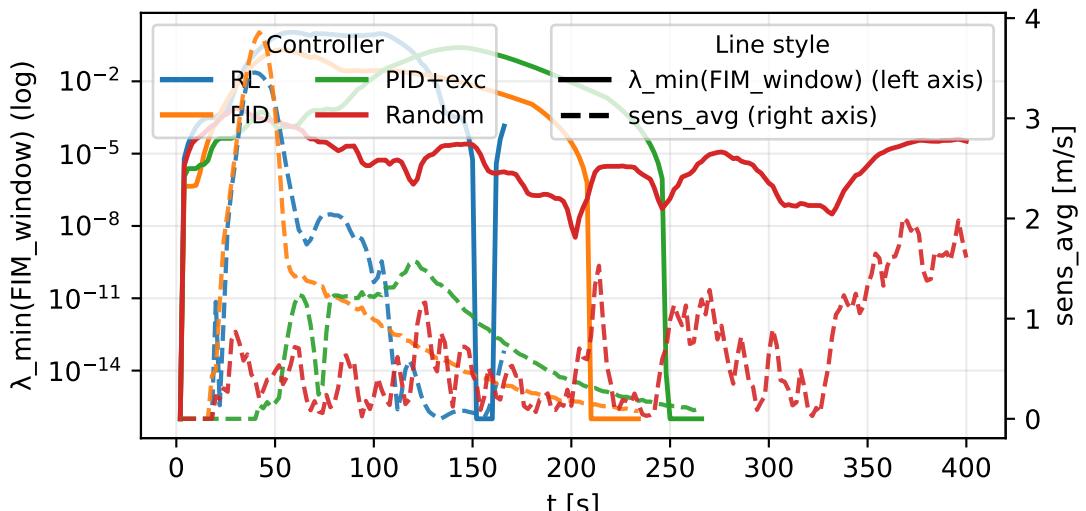
TRUE formation error



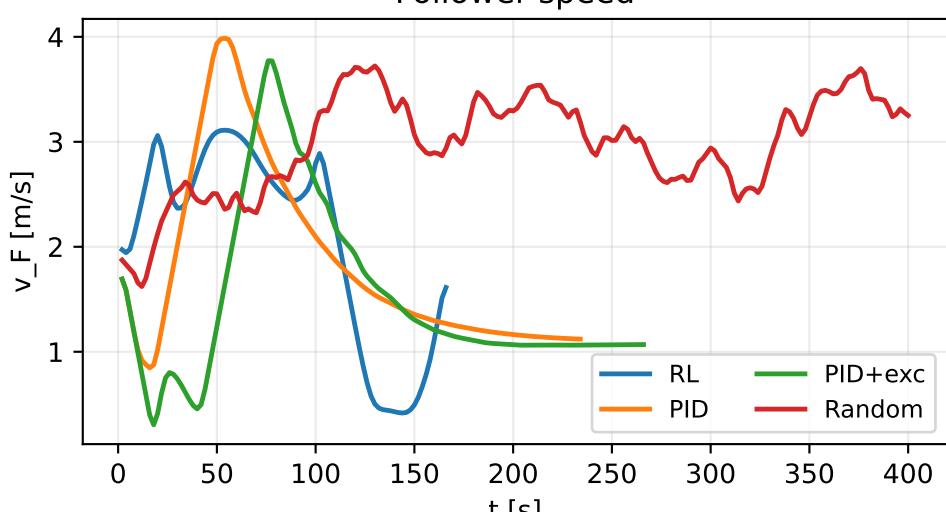
Estimator uncertainty (std_max)



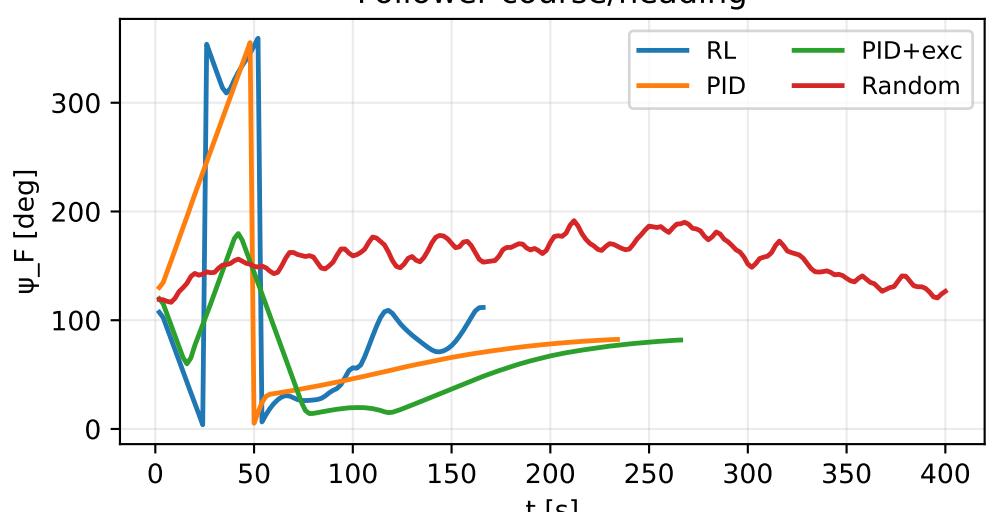
Information and excitation



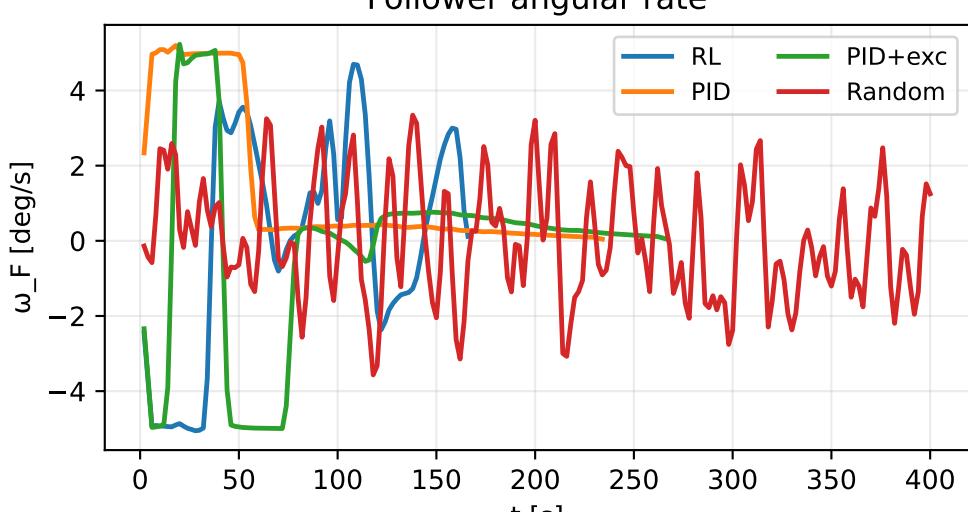
Follower speed



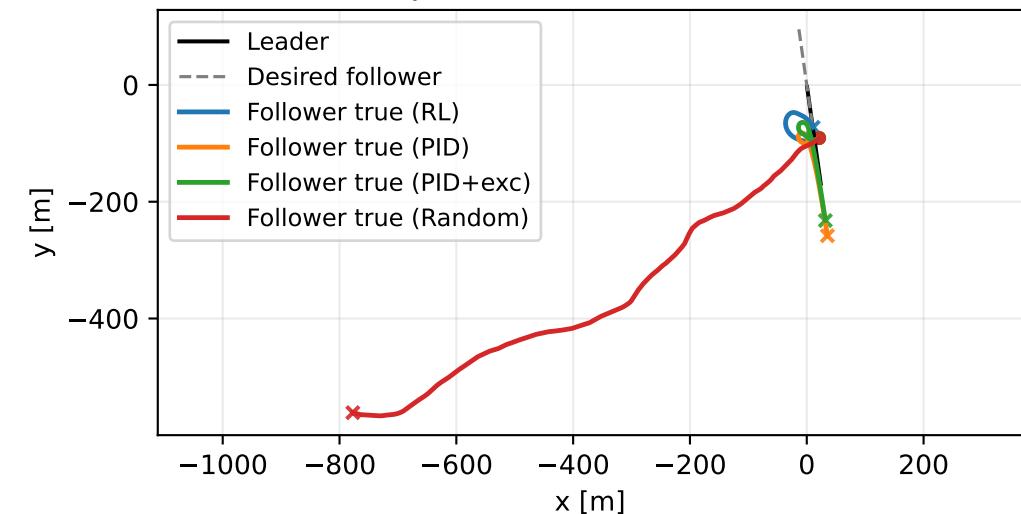
Follower course/heading



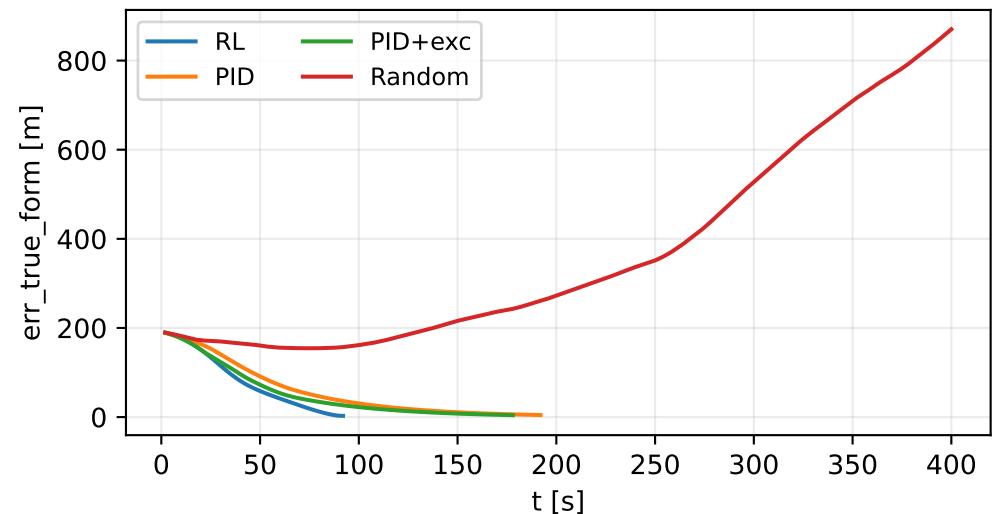
Follower angular rate



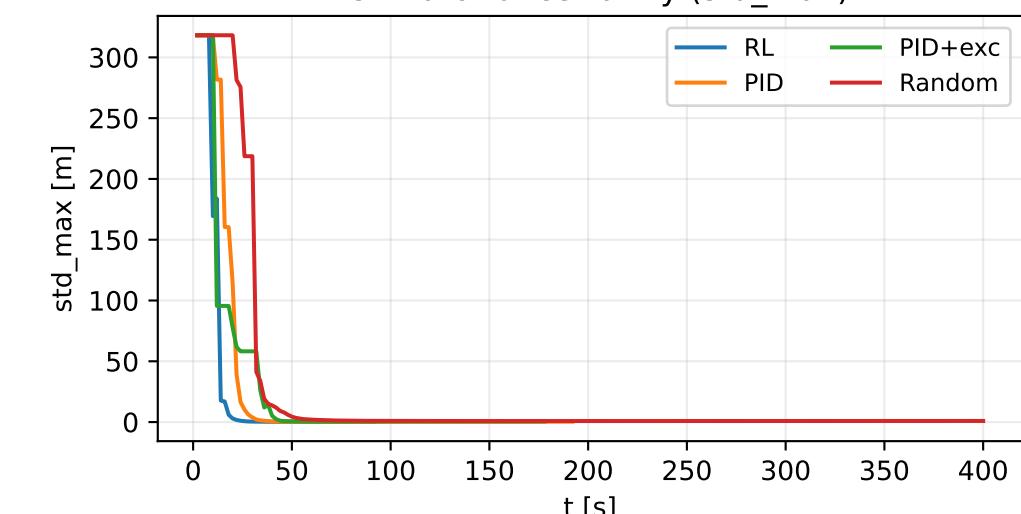
Trajectories (matched seed)



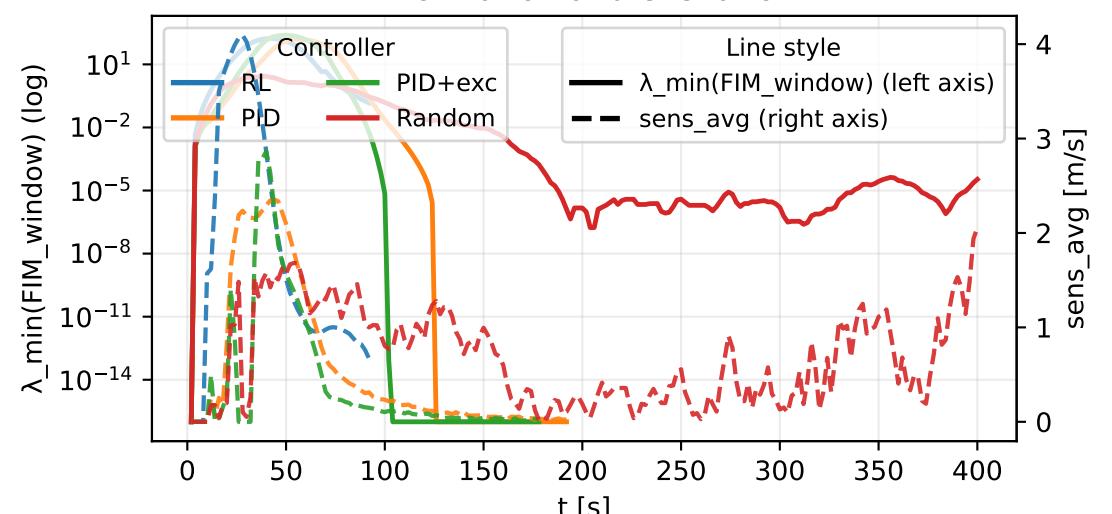
TRUE formation error



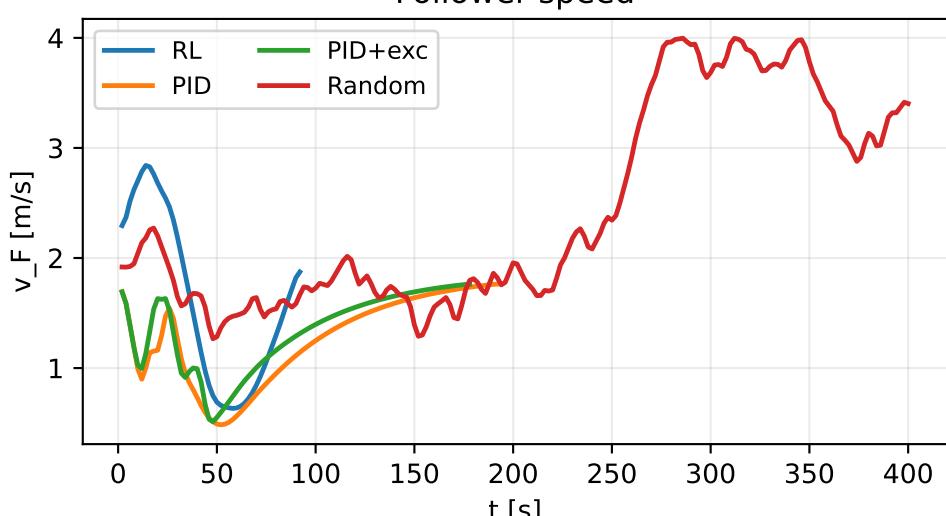
Estimator uncertainty (std_max)



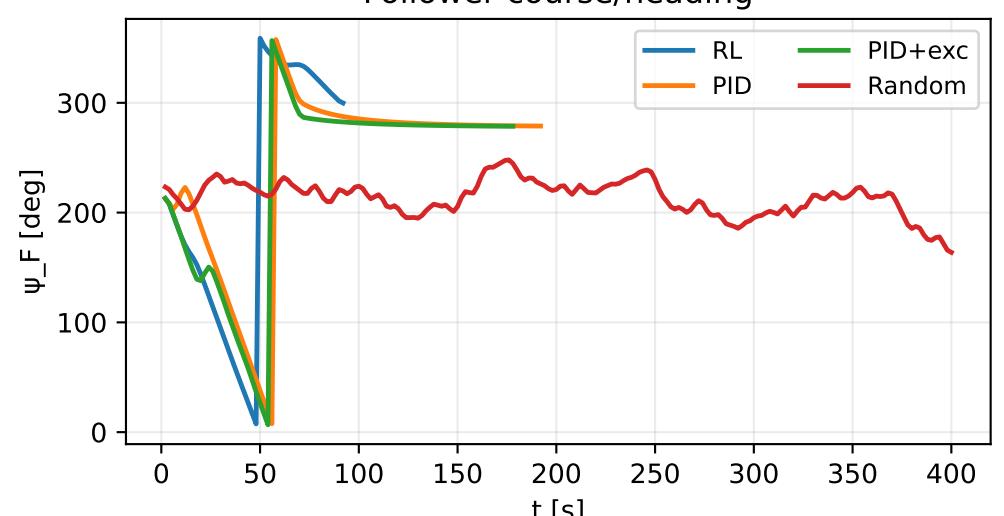
Information and excitation



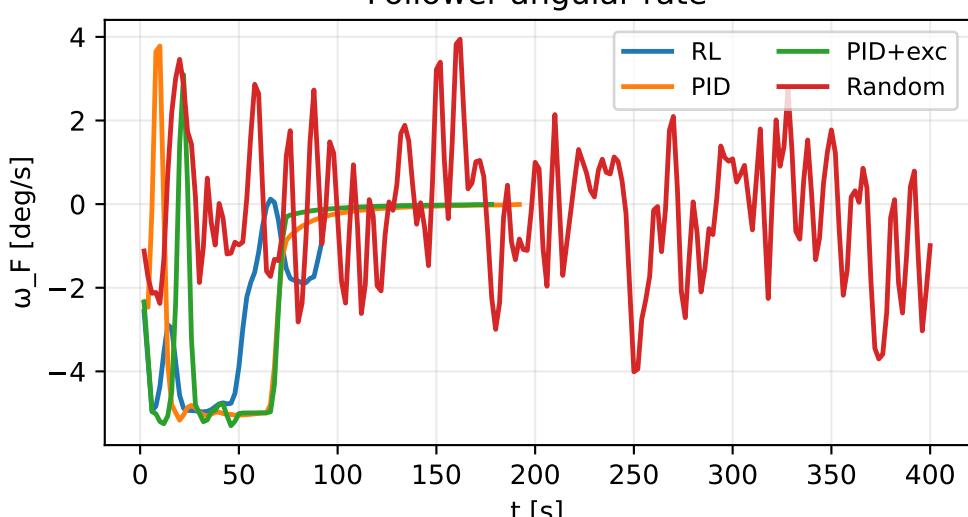
Follower speed



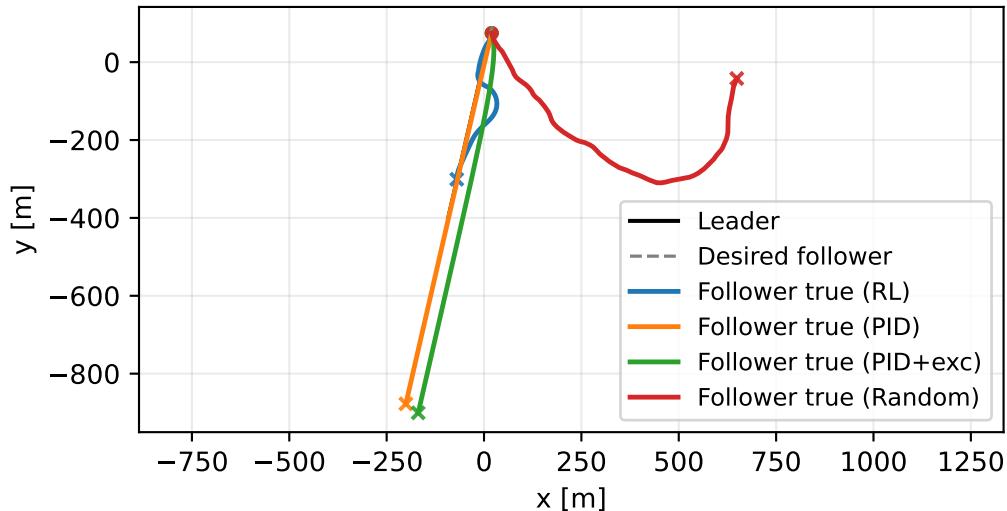
Follower course/heading



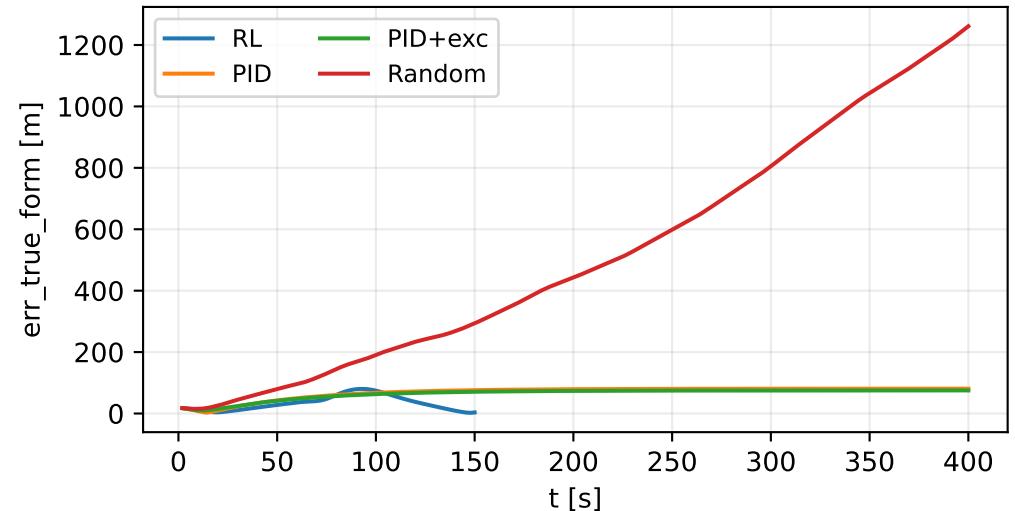
Follower angular rate



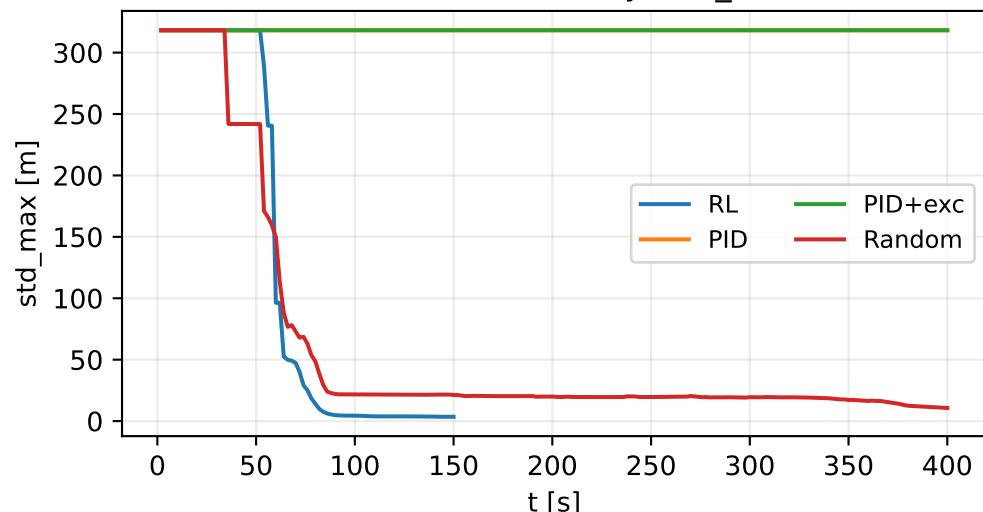
Trajectories (matched seed)



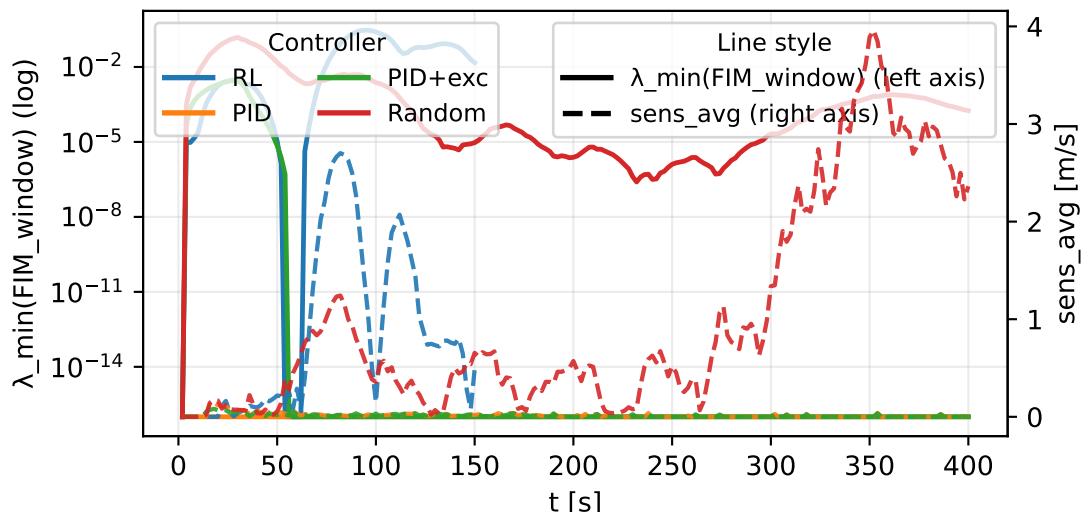
TRUE formation error



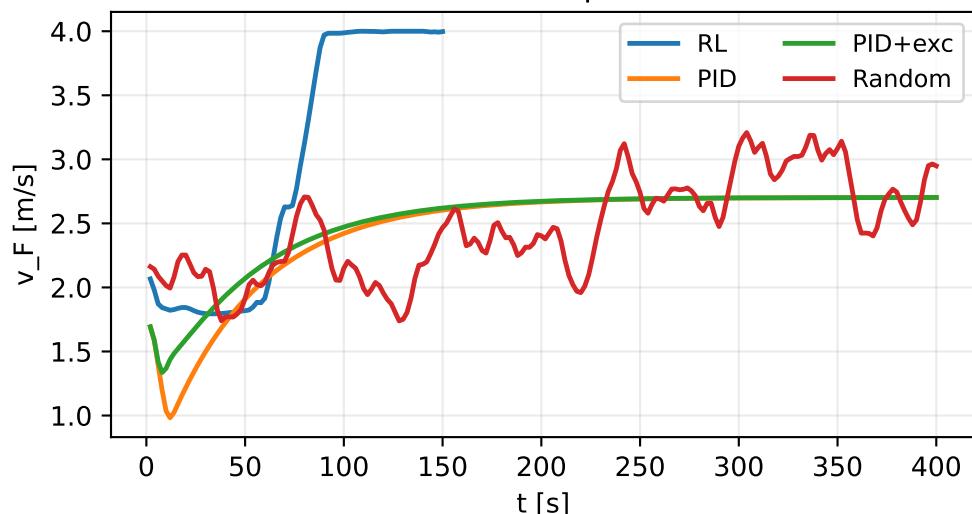
Estimator uncertainty (std_max)



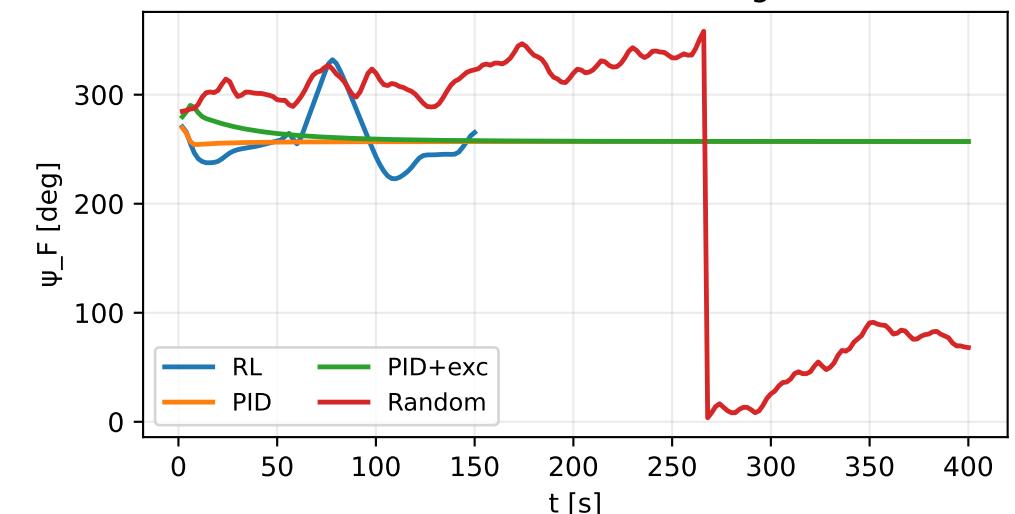
Information and excitation



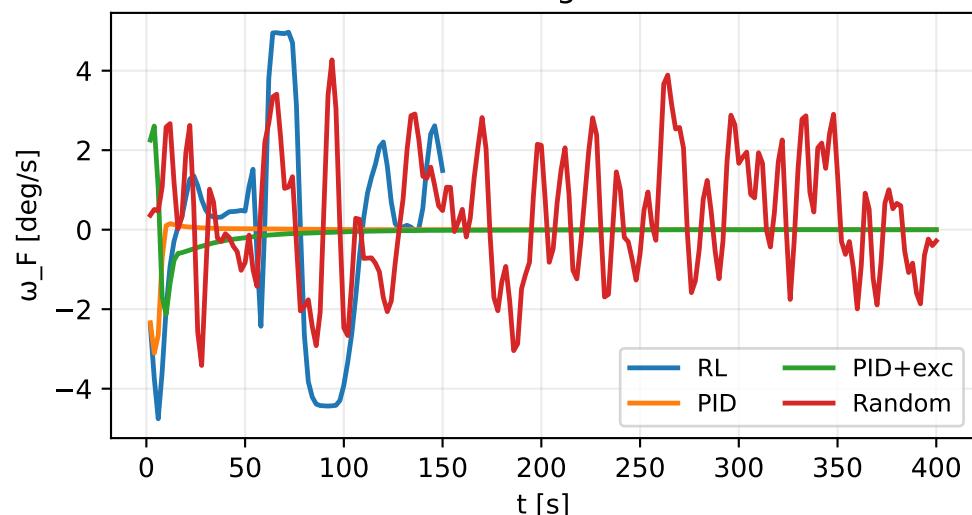
Follower speed



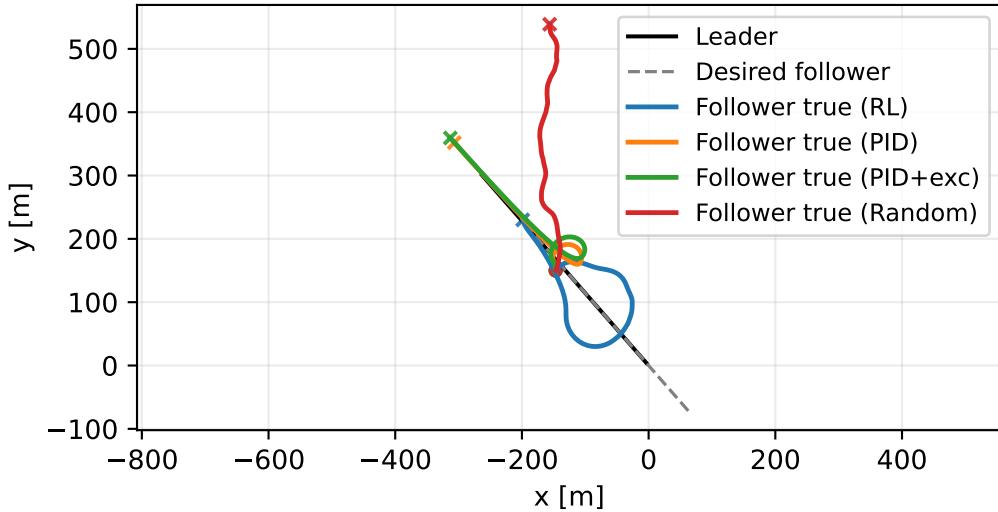
Follower course/heading



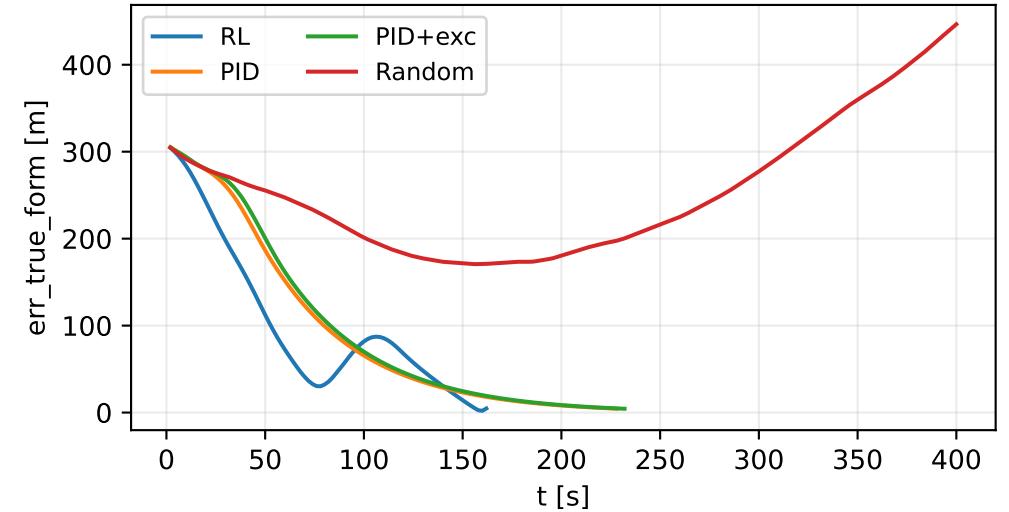
Follower angular rate



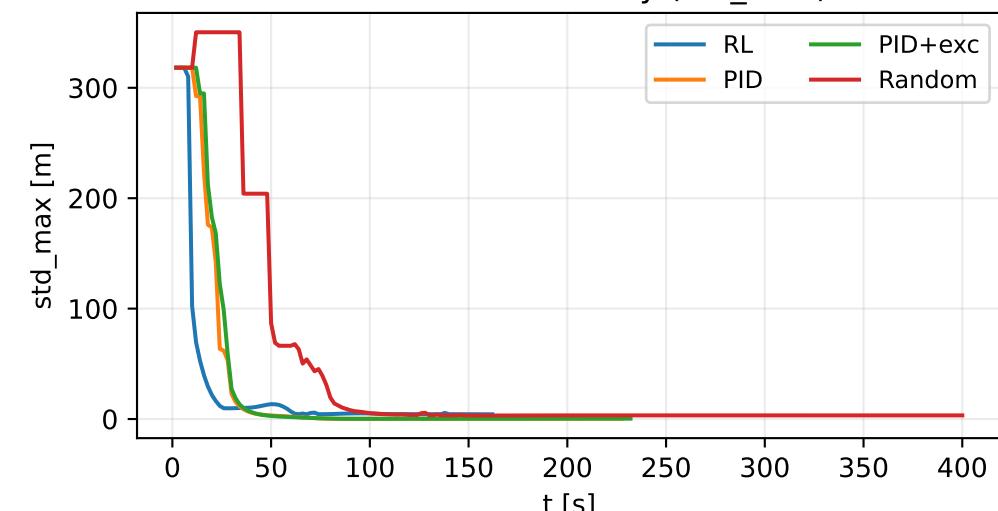
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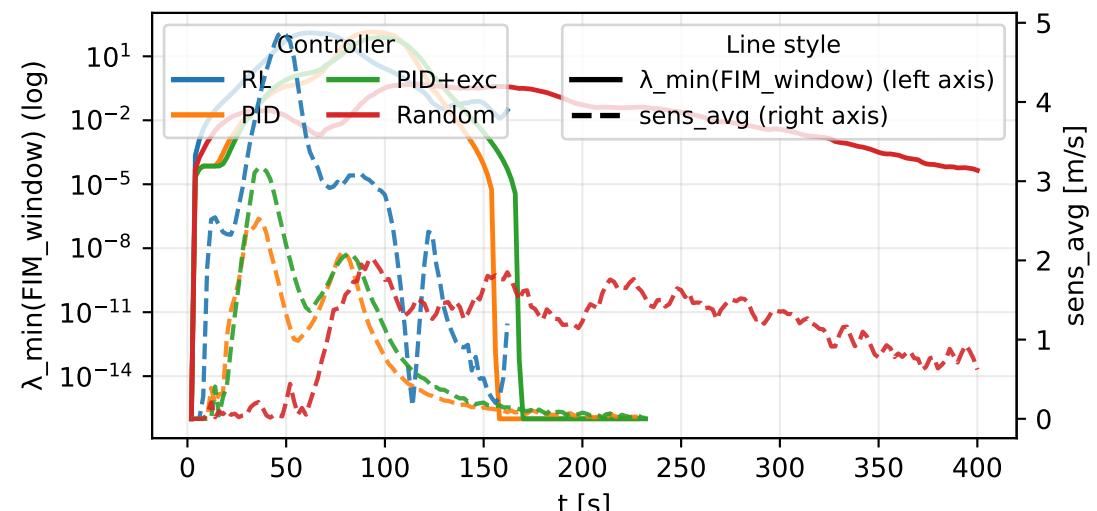
TRUE formation error



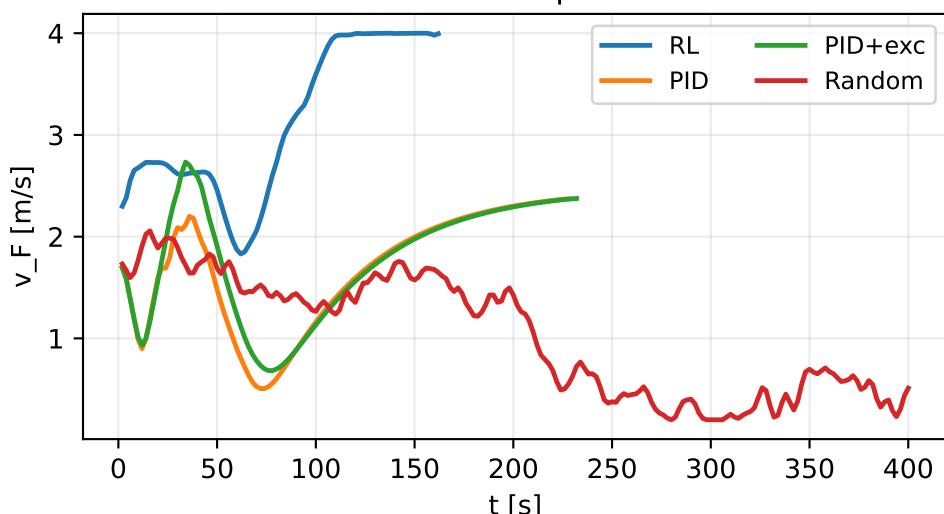
Estimator uncertainty (std_max)



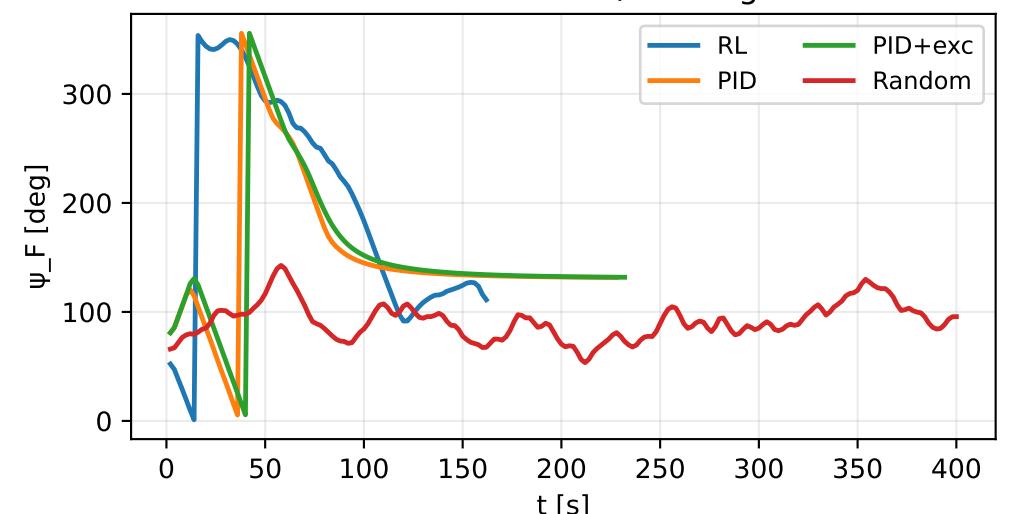
Information and excitation



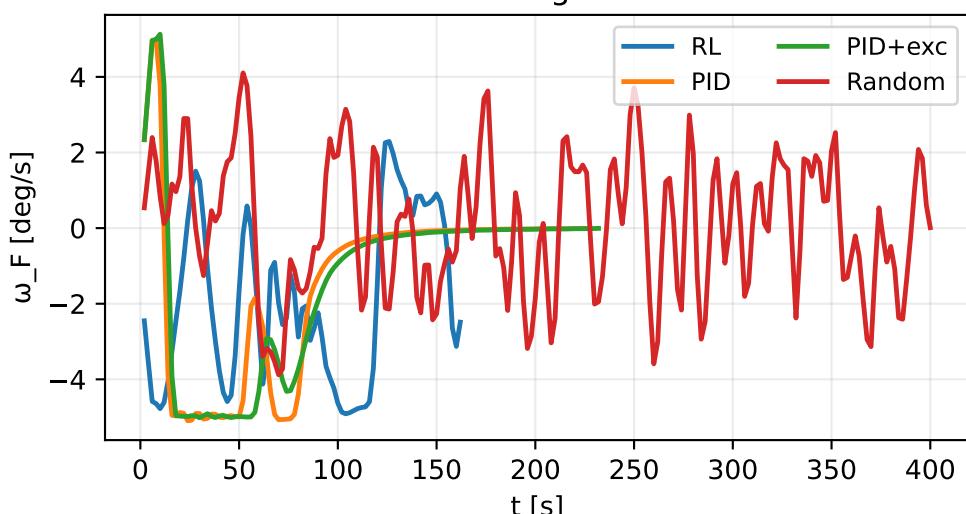
Follower speed



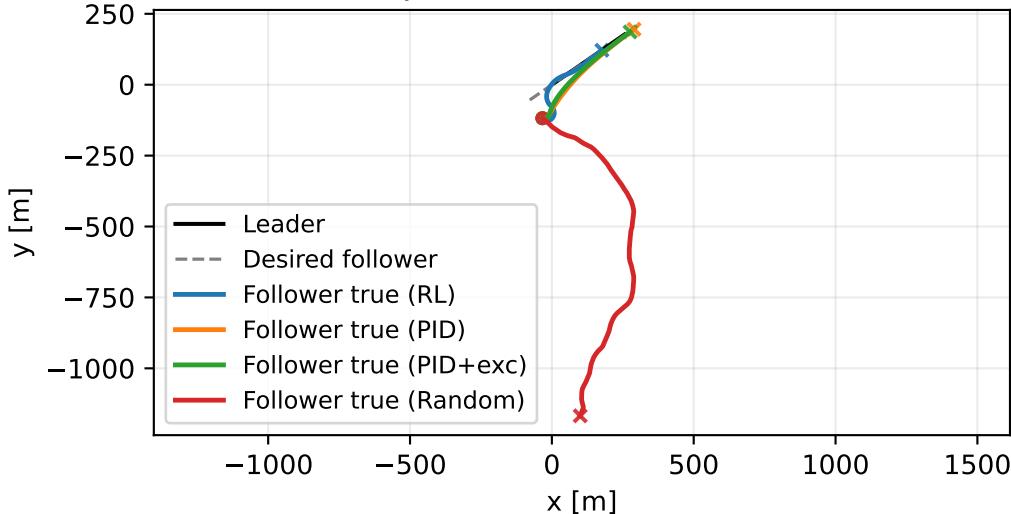
Follower course/heading



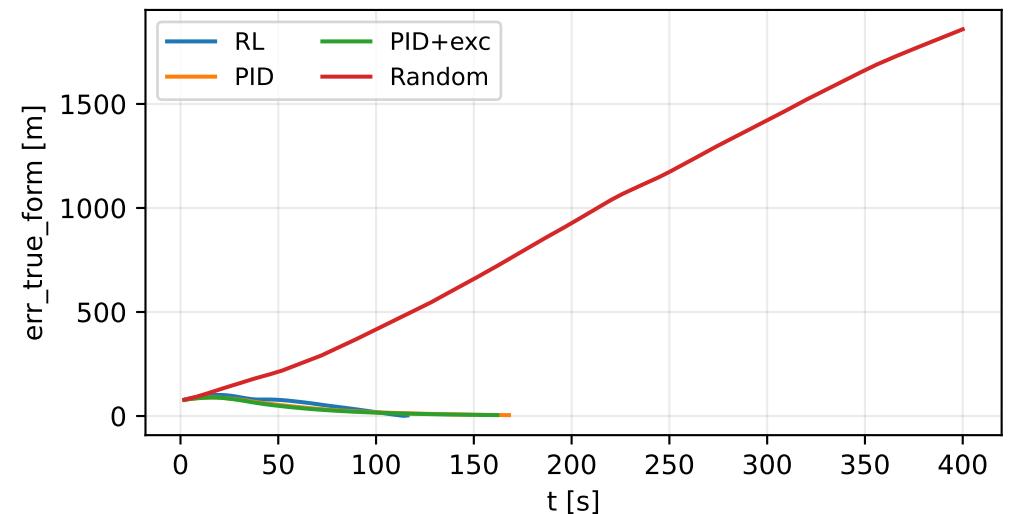
Follower angular rate



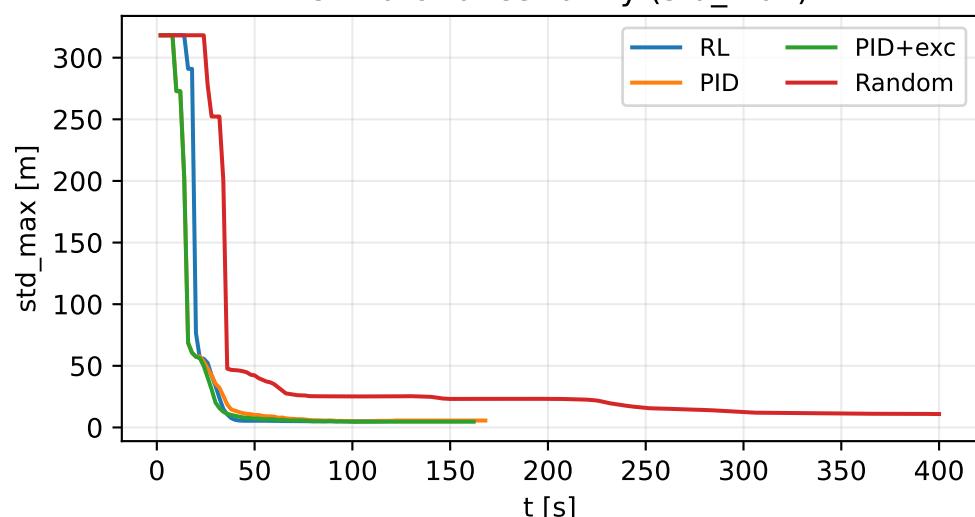
Trajectories (matched seed)



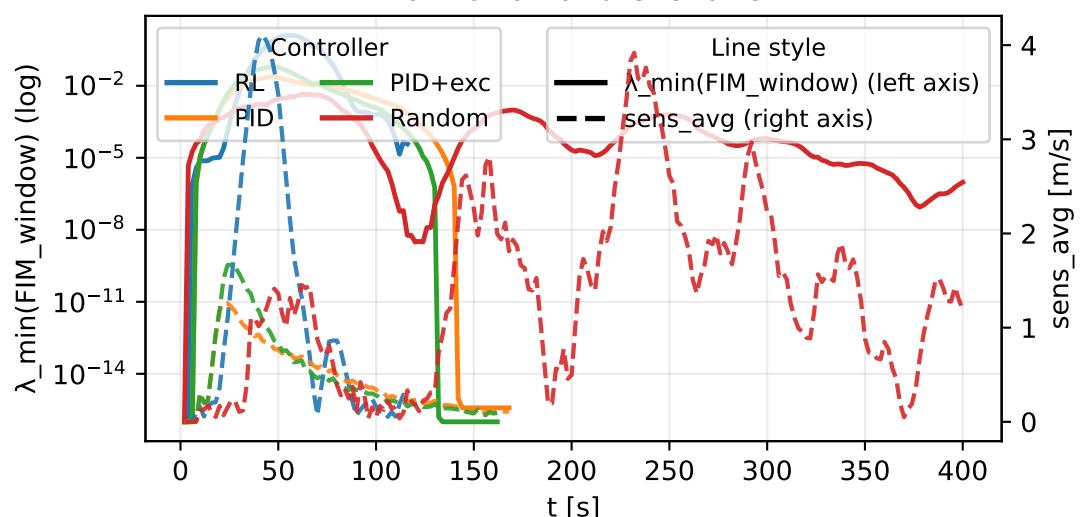
TRUE formation error



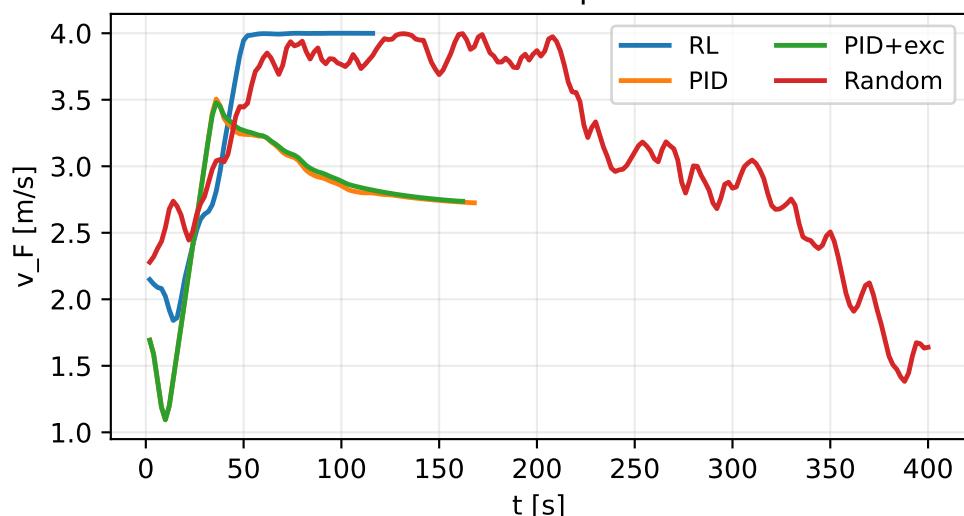
Estimator uncertainty (std_max)



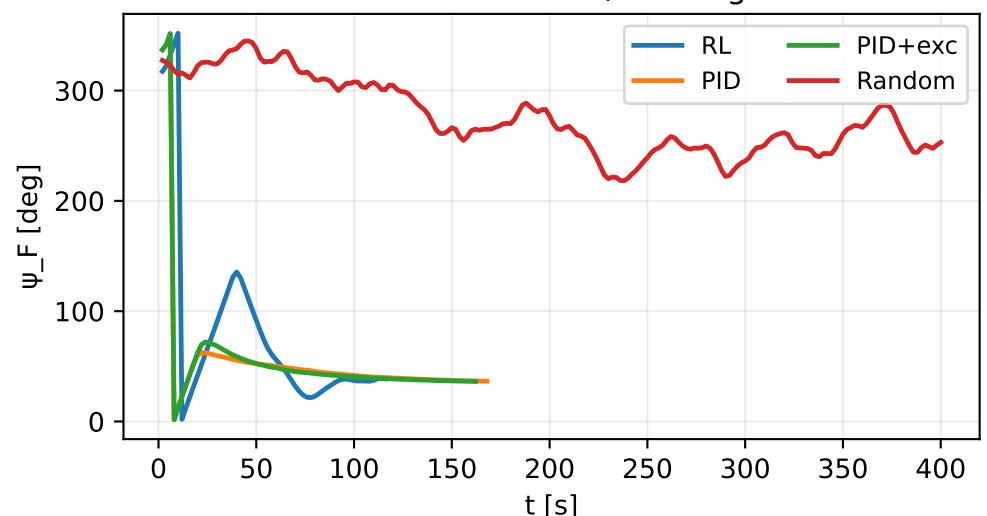
Information and excitation



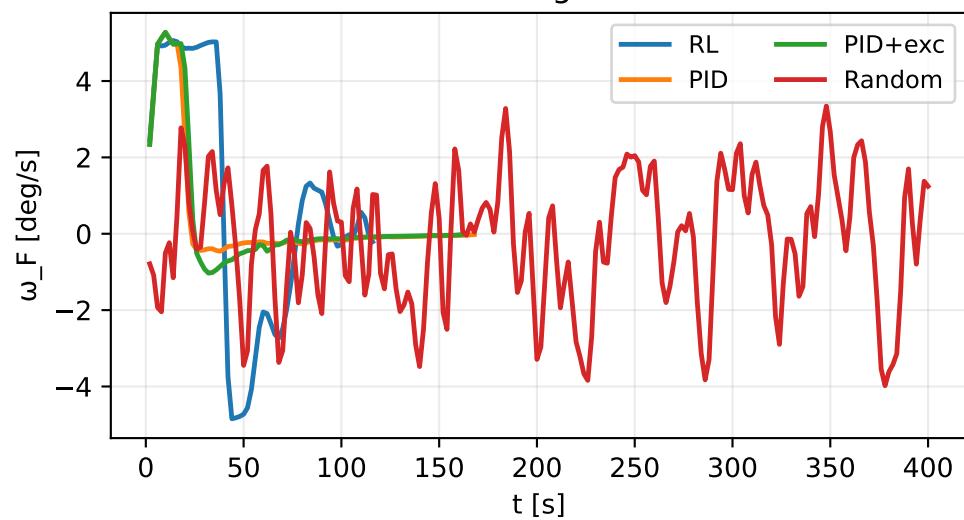
Follower speed



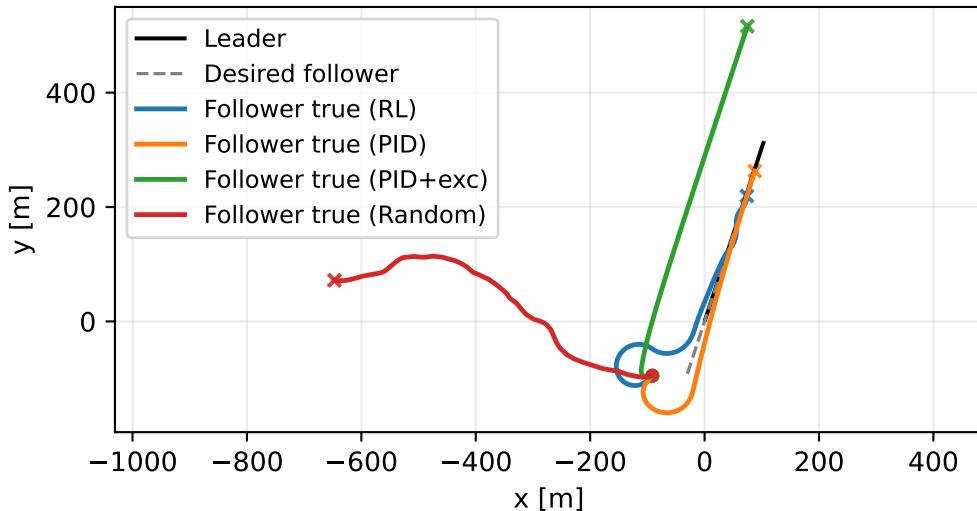
Follower course/heading



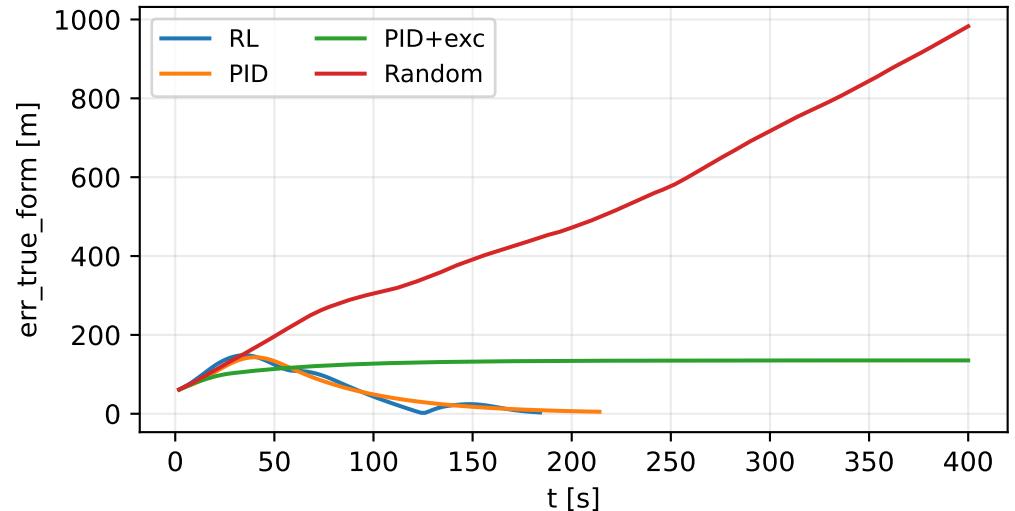
Follower angular rate



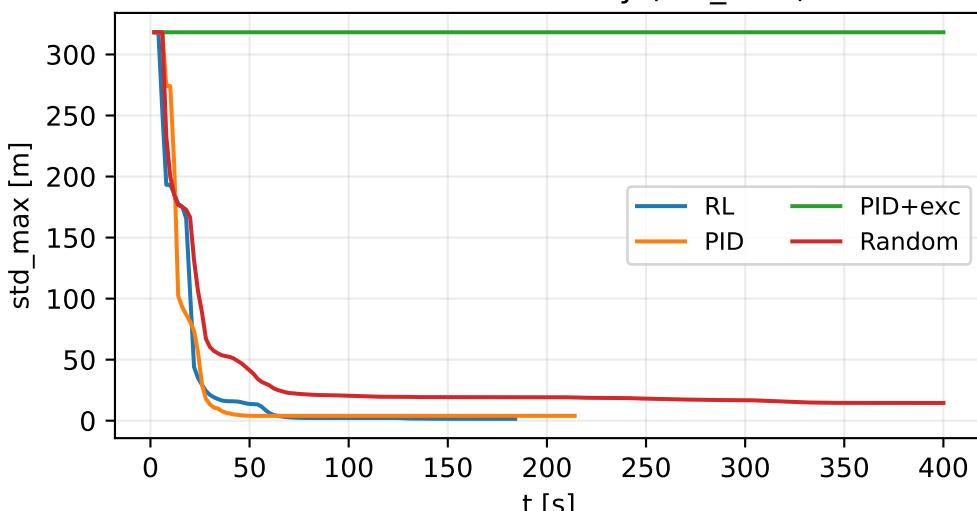
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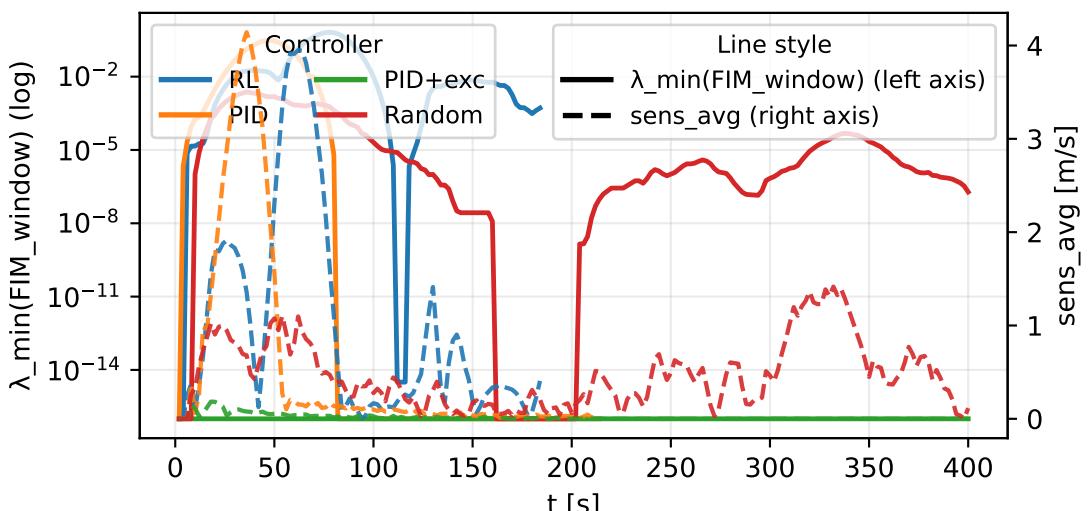
TRUE formation error



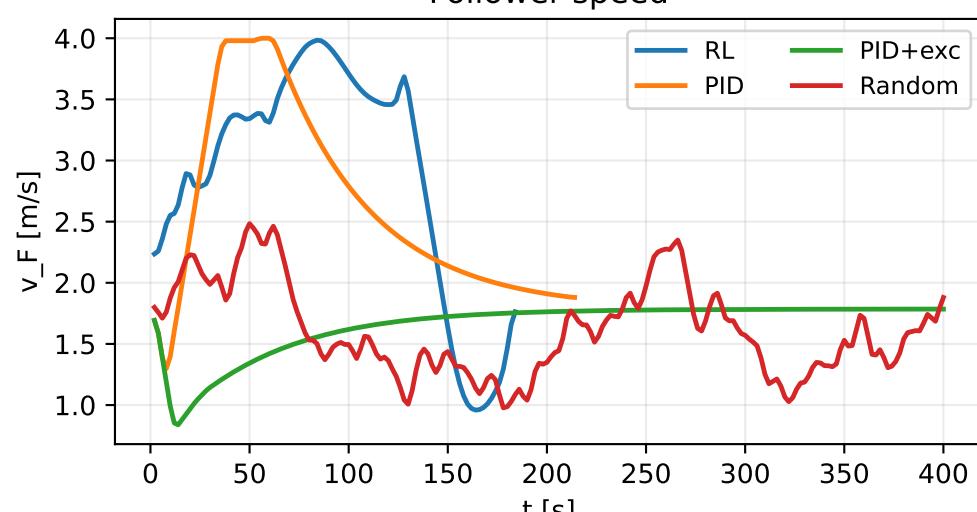
Estimator uncertainty (std_max)



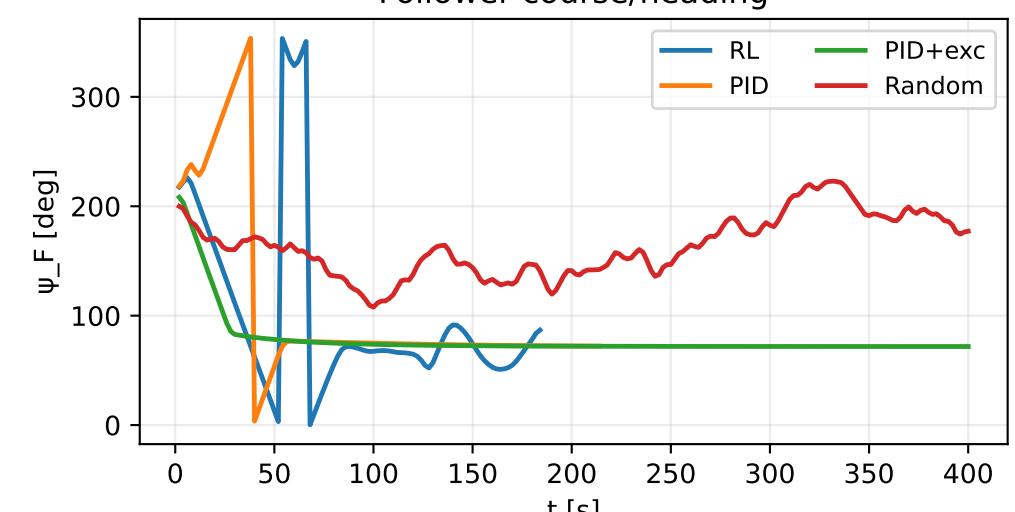
Information and excitation



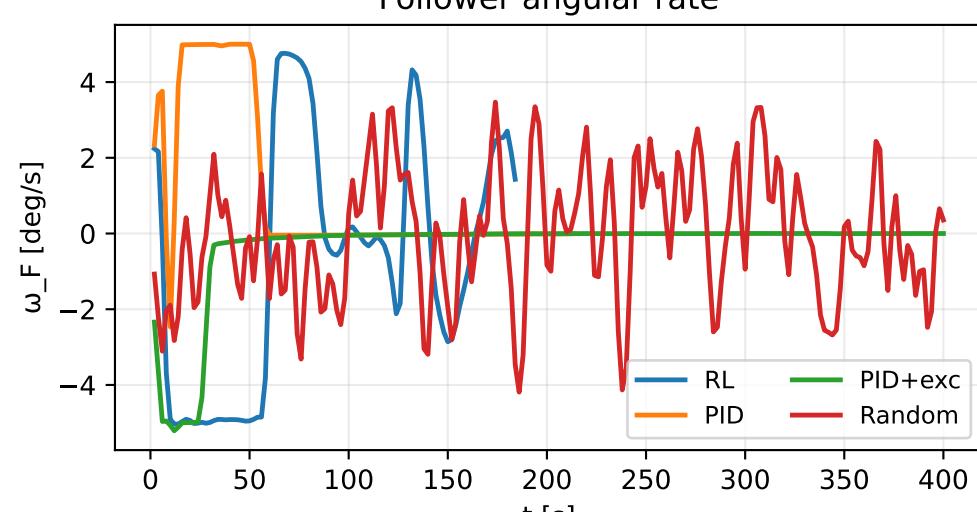
Follower speed



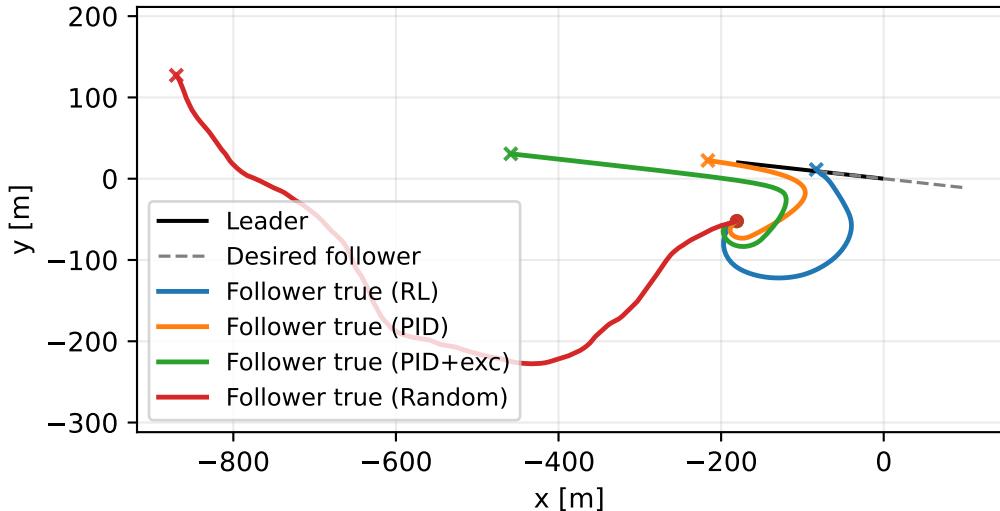
Follower course/heading



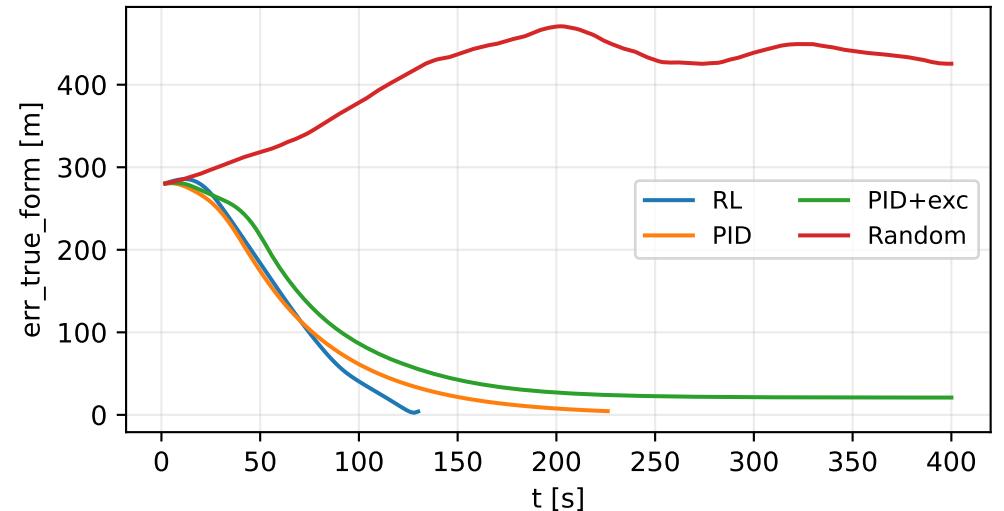
Follower angular rate



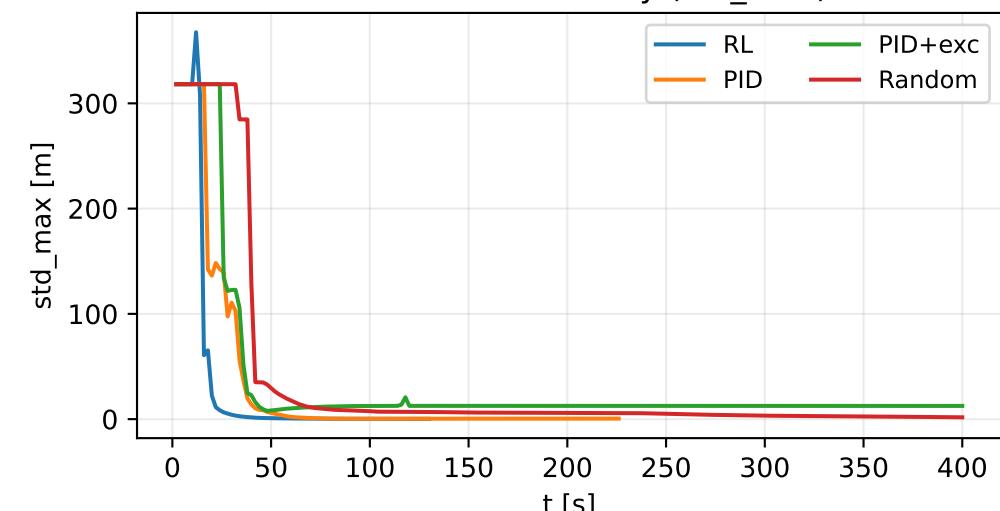
Trajectories (matched seed)



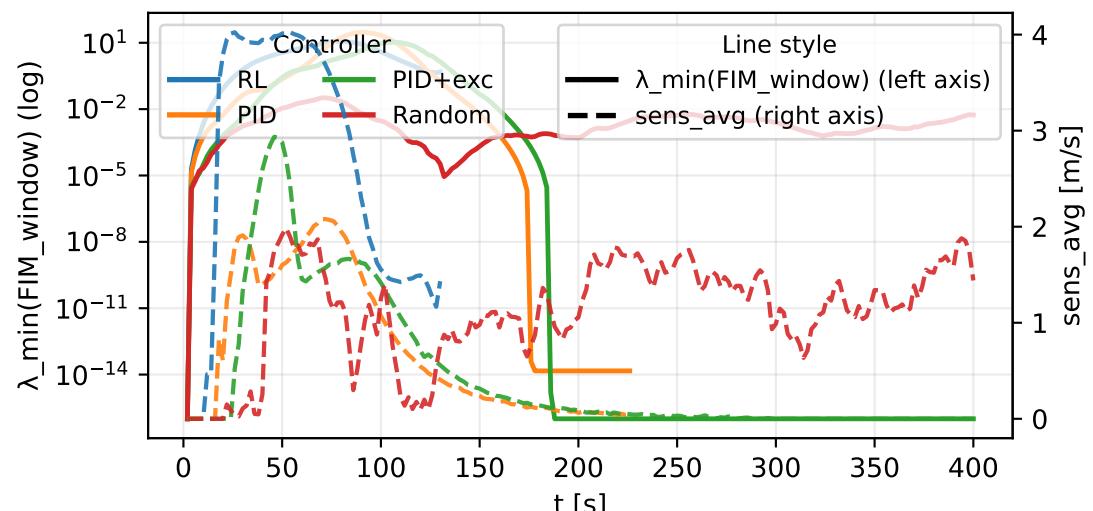
TRUE formation error



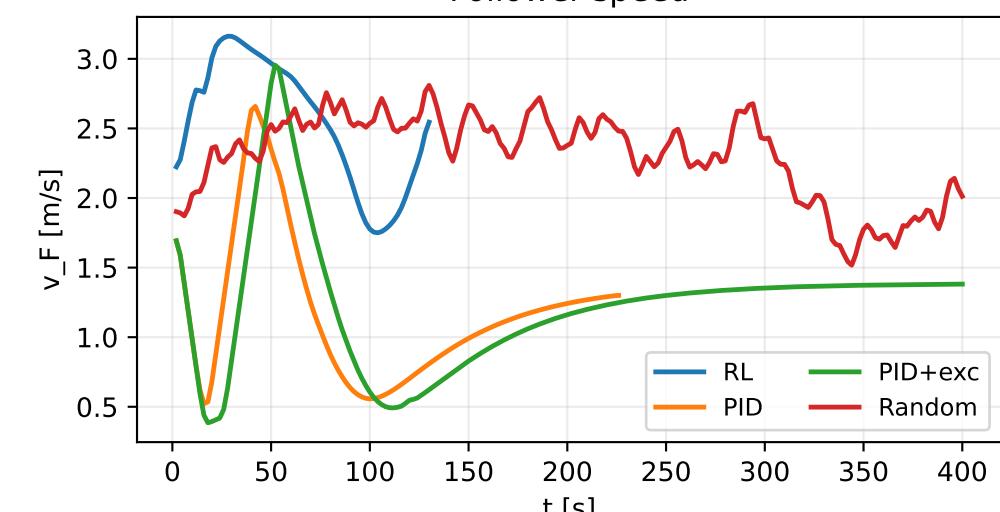
Estimator uncertainty (std_max)



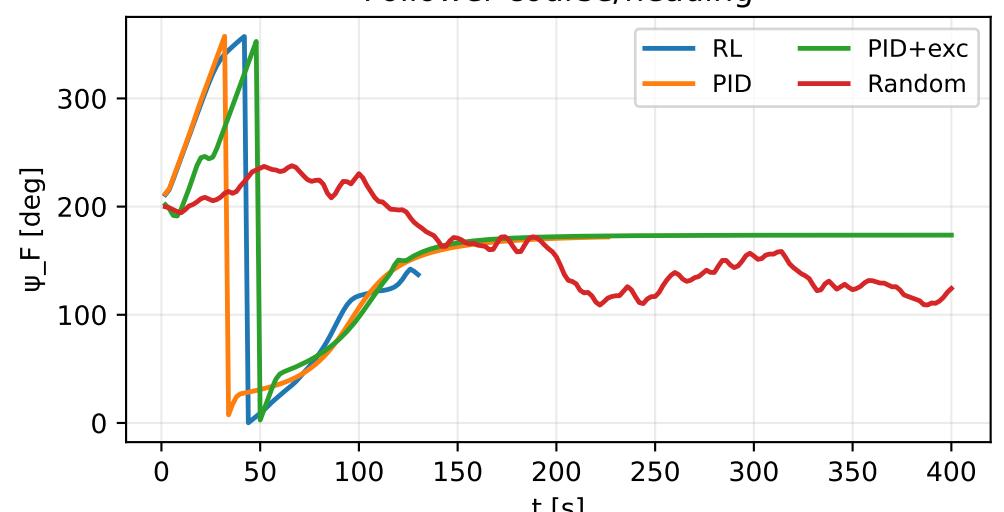
Information and excitation



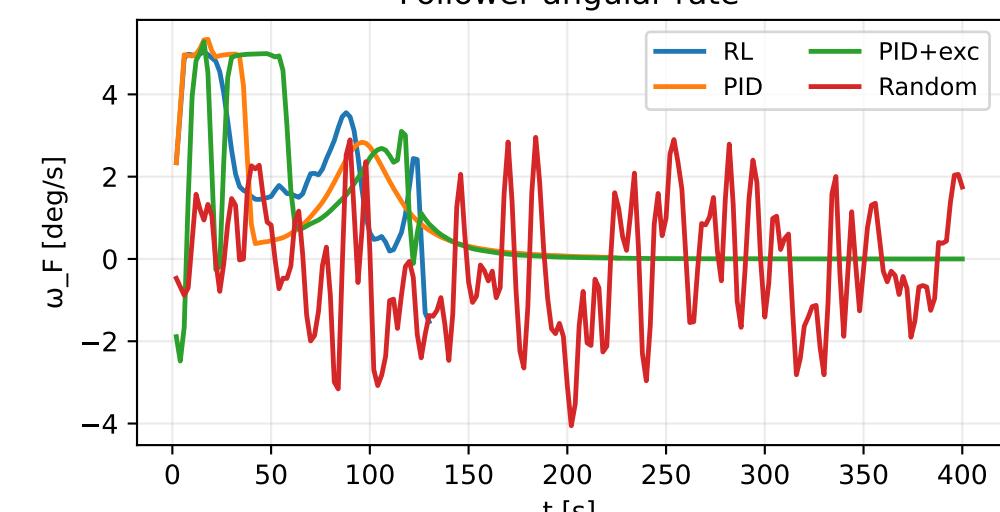
Follower speed



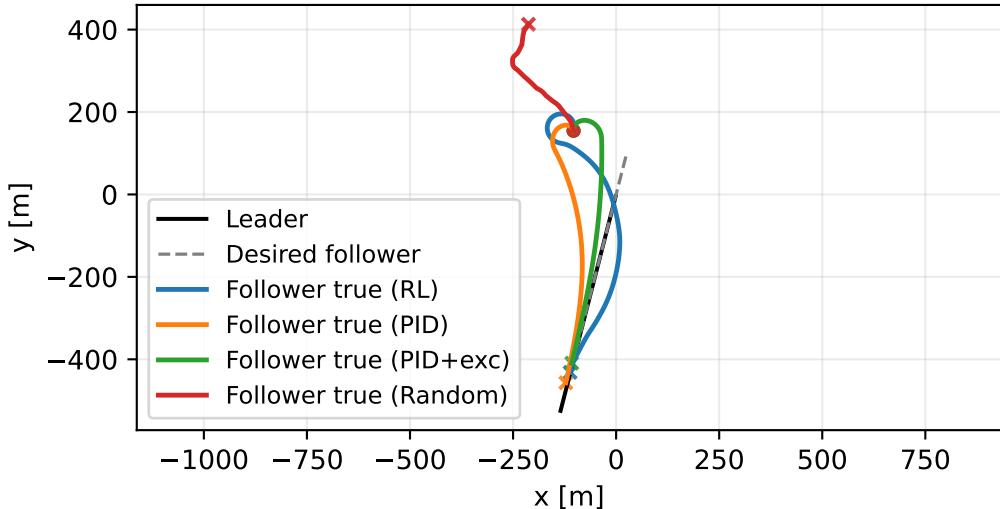
Follower course/heading



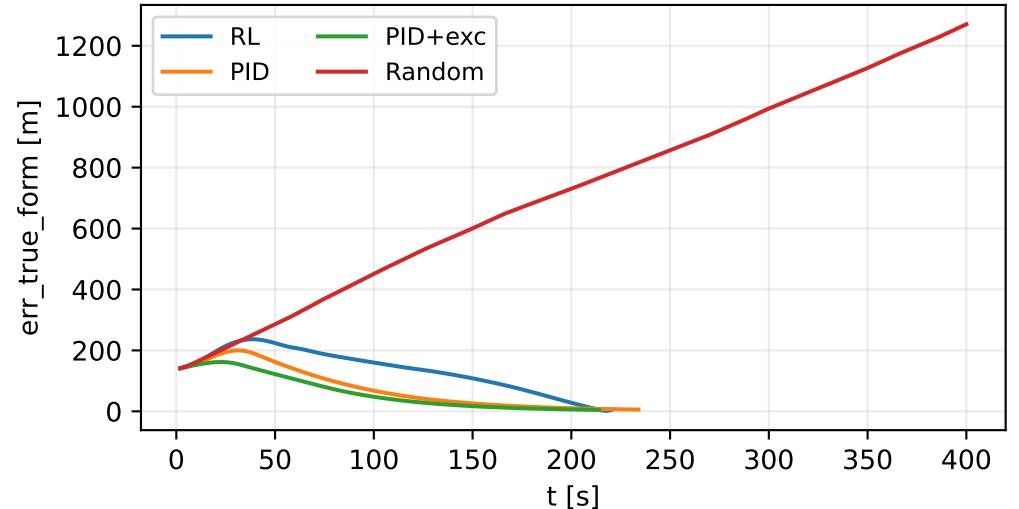
Follower angular rate



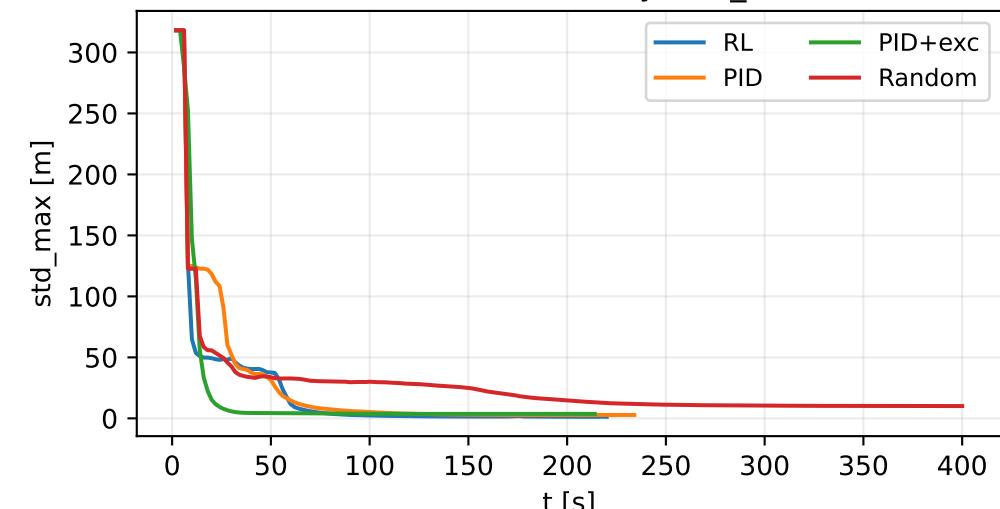
Trajectories (matched seed)



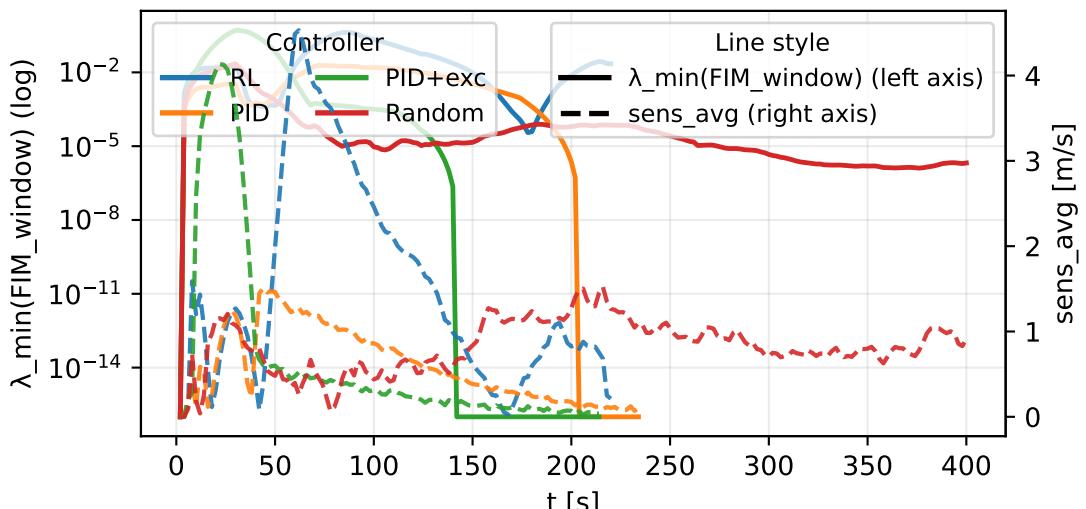
TRUE formation error



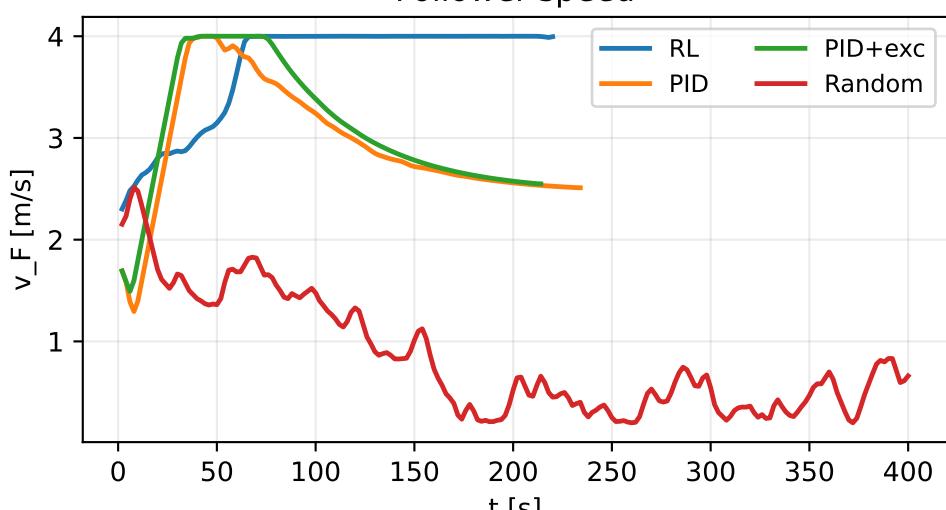
Estimator uncertainty (std_max)



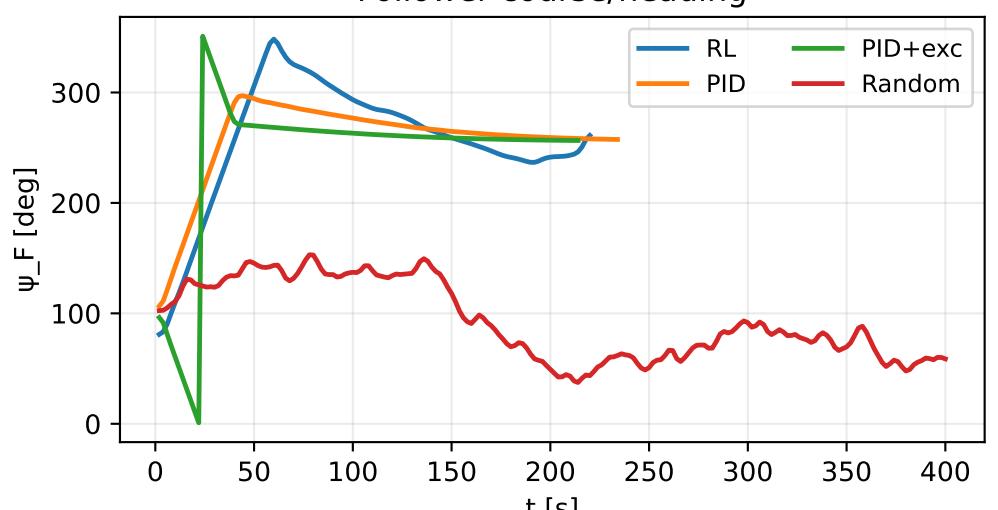
Information and excitation



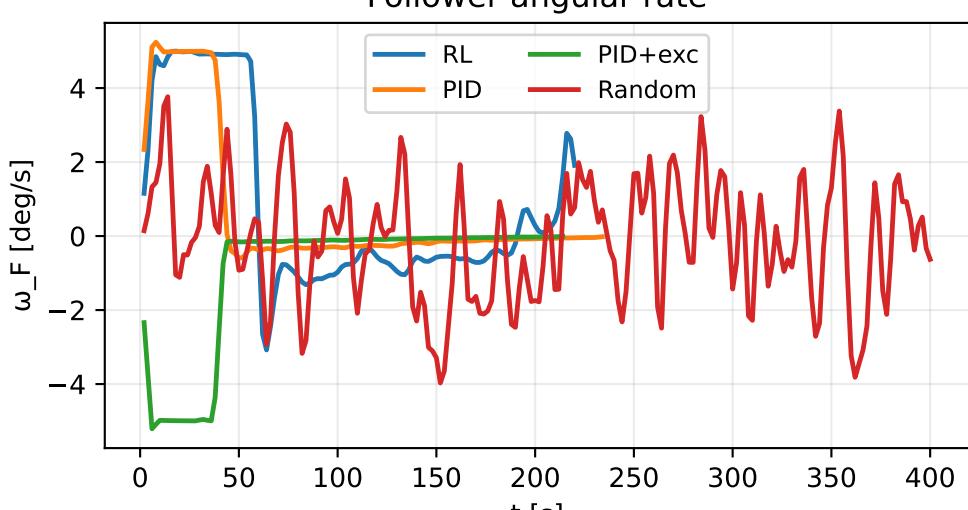
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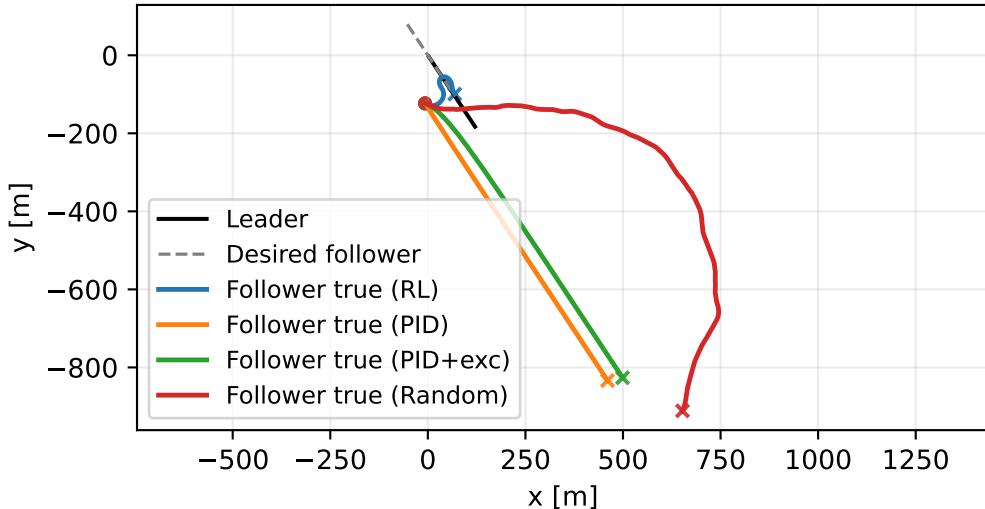
Follower course/heading



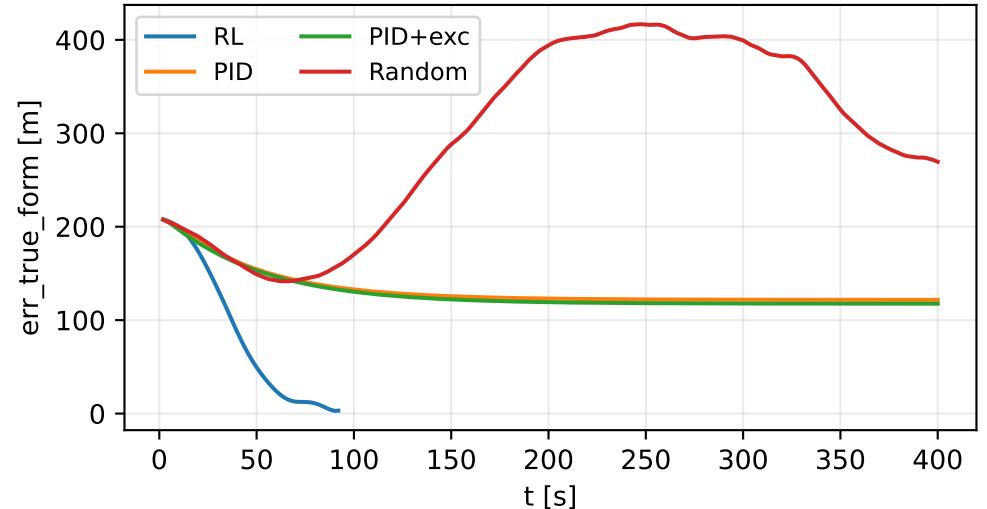
Follower angular rate



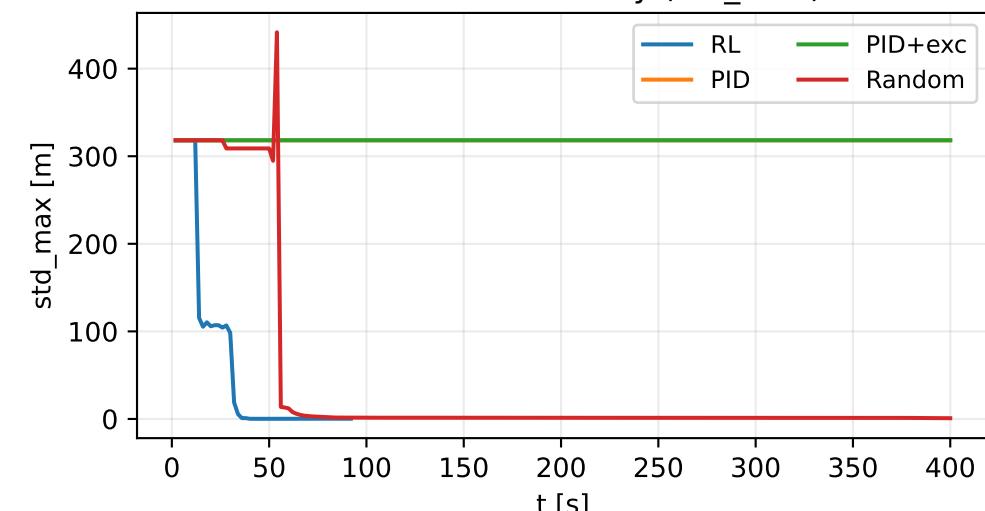
Trajectories (matched seed)



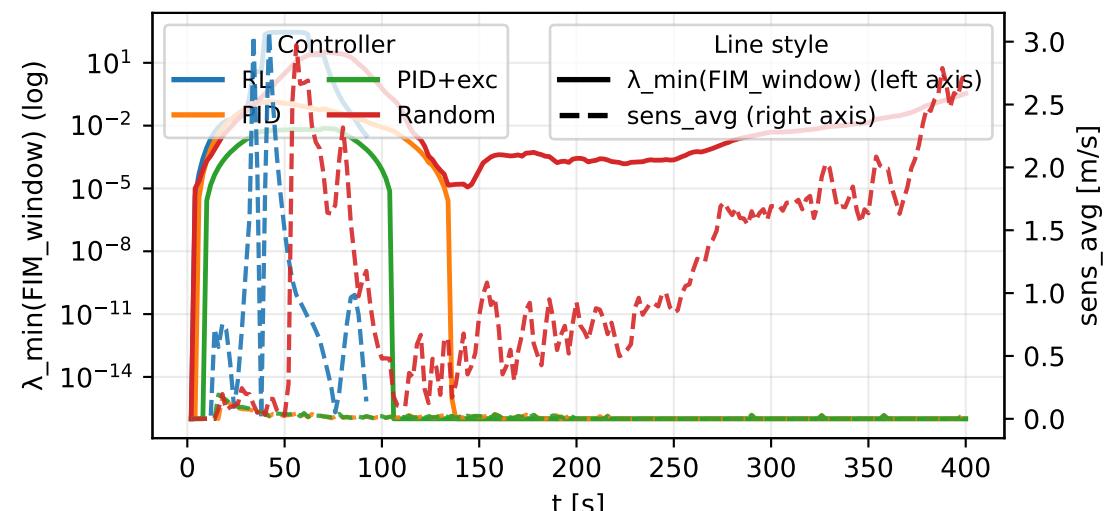
TRUE formation error



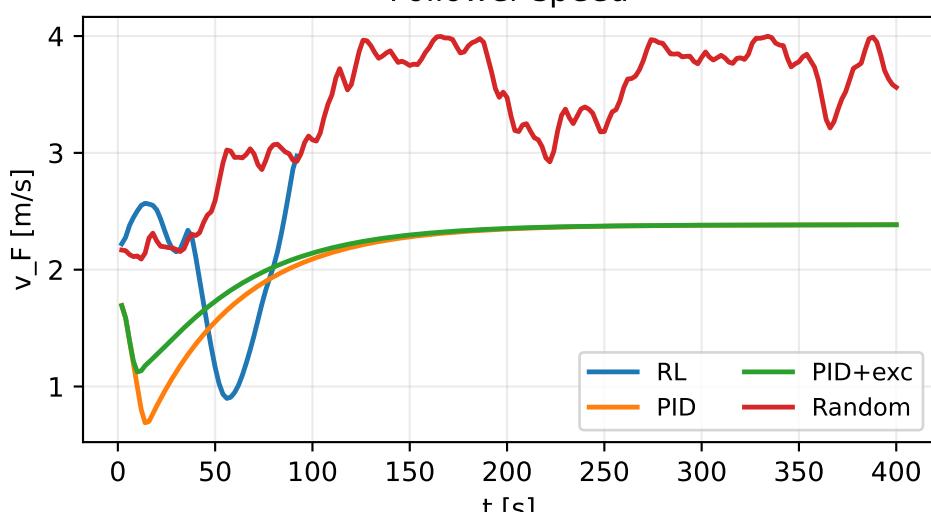
Estimator uncertainty (std_max)



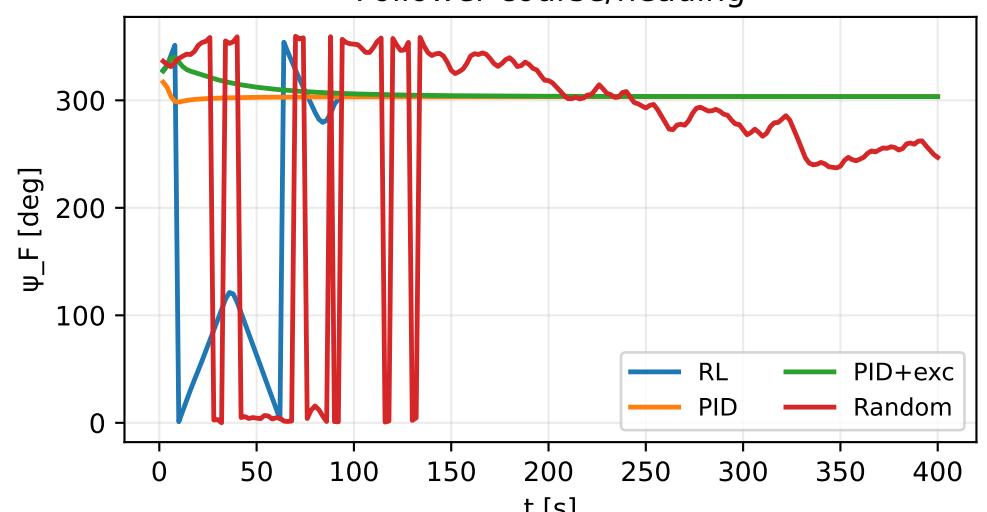
Information and excitation



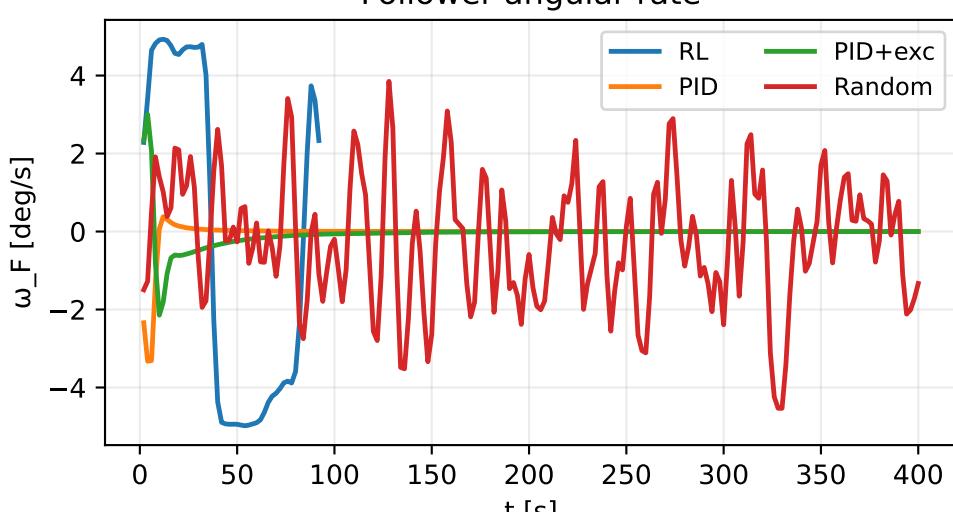
Follower speed



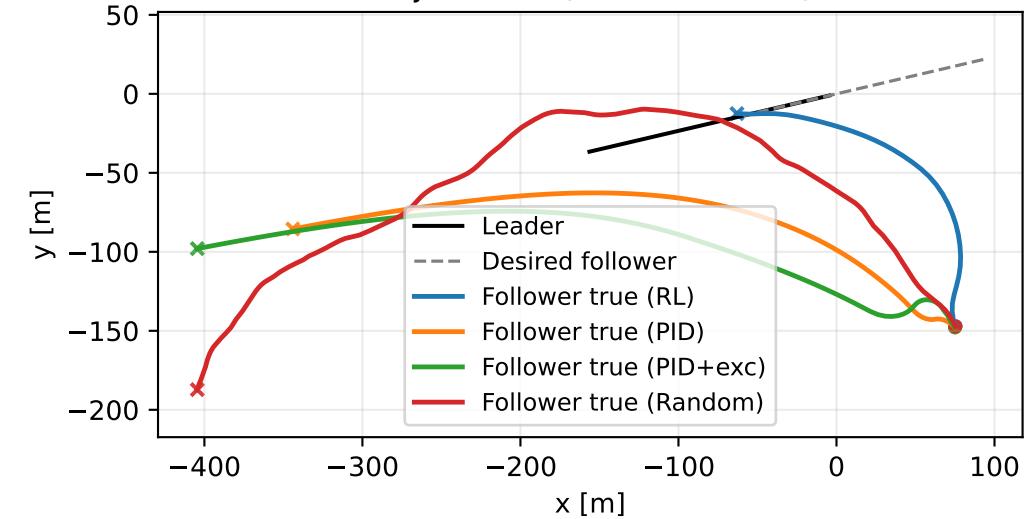
Follower course/heading



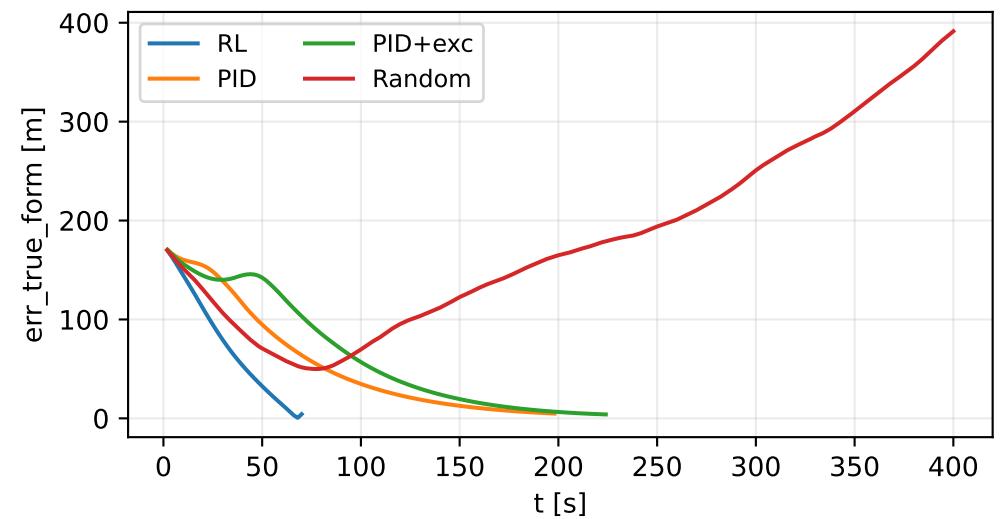
Follower angular rate



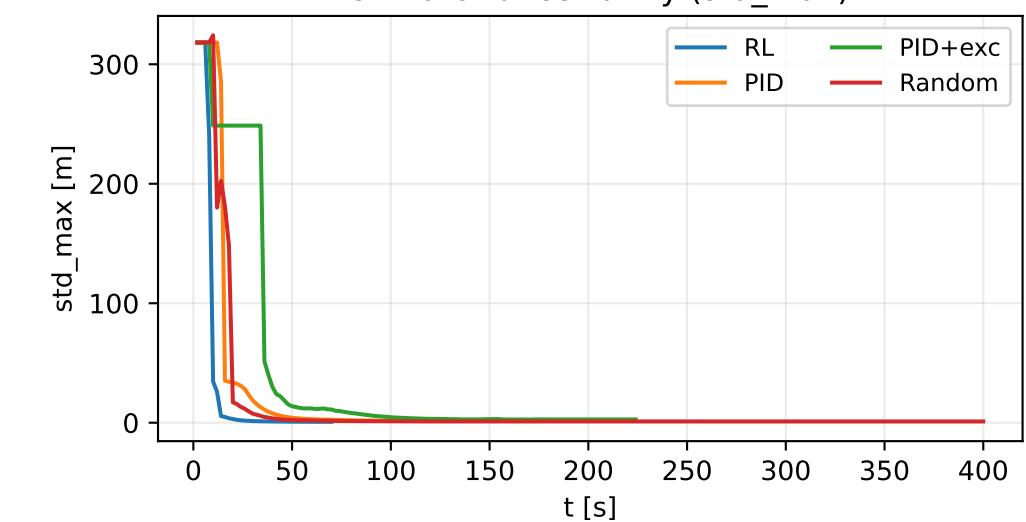
Trajectories (matched seed)



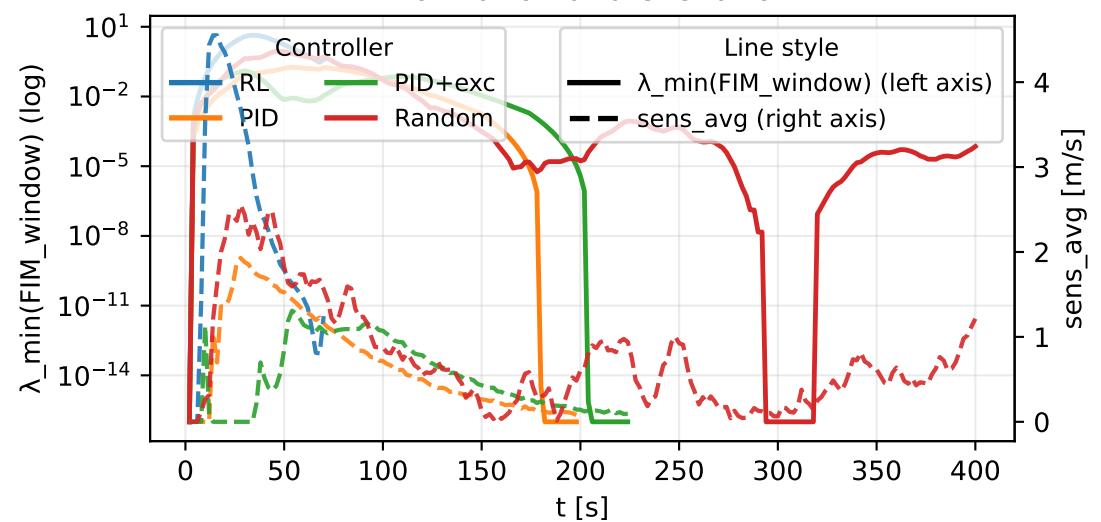
TRUE formation error



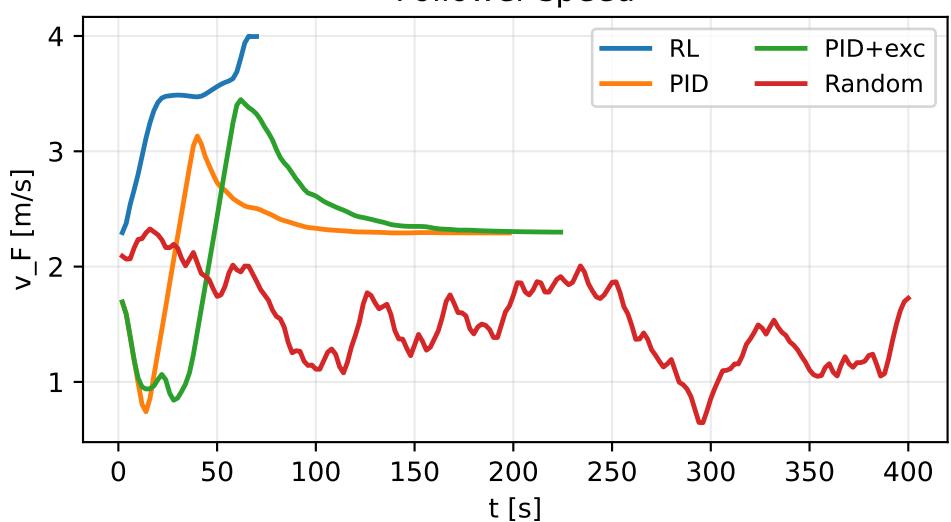
Estimator uncertainty (std_max)



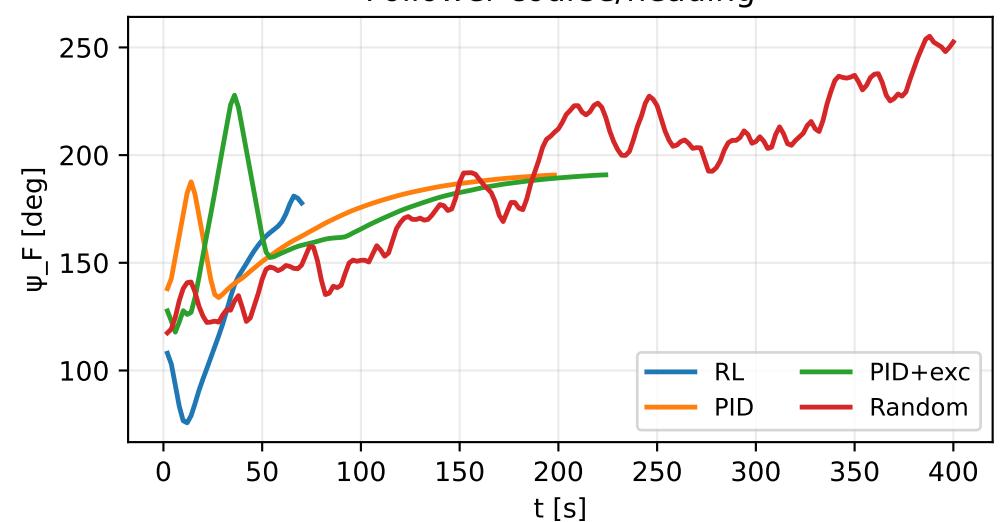
Information and excitation



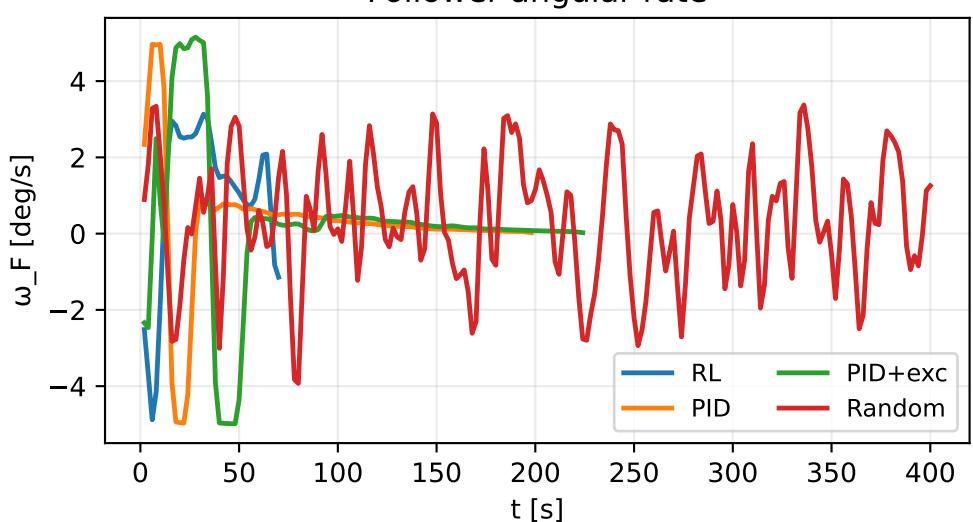
Follower speed



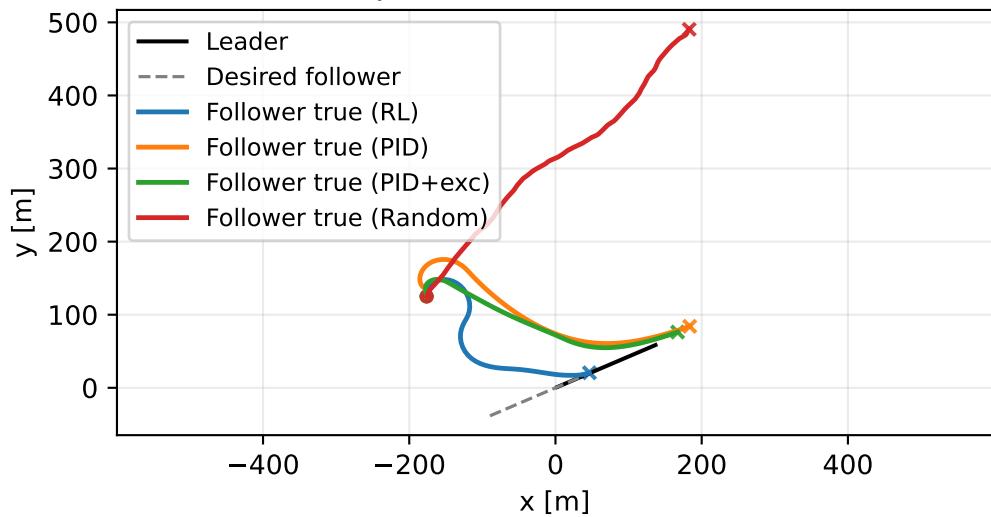
Follower course/heading



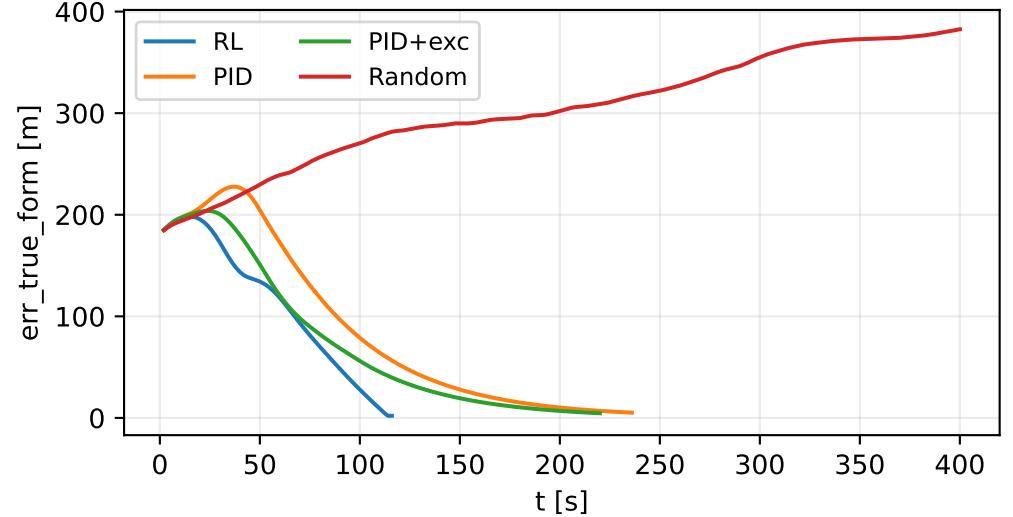
Follower angular rate



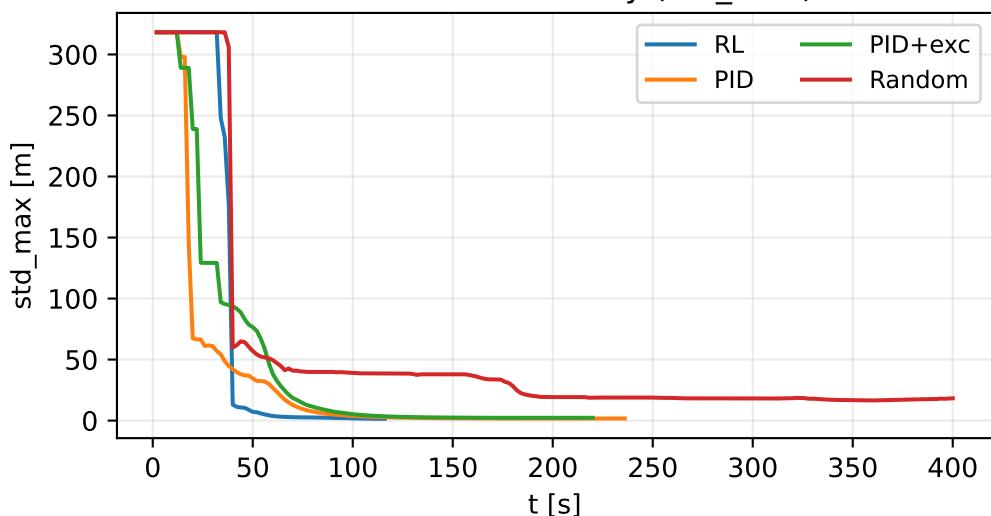
Trajectories (matched seed)



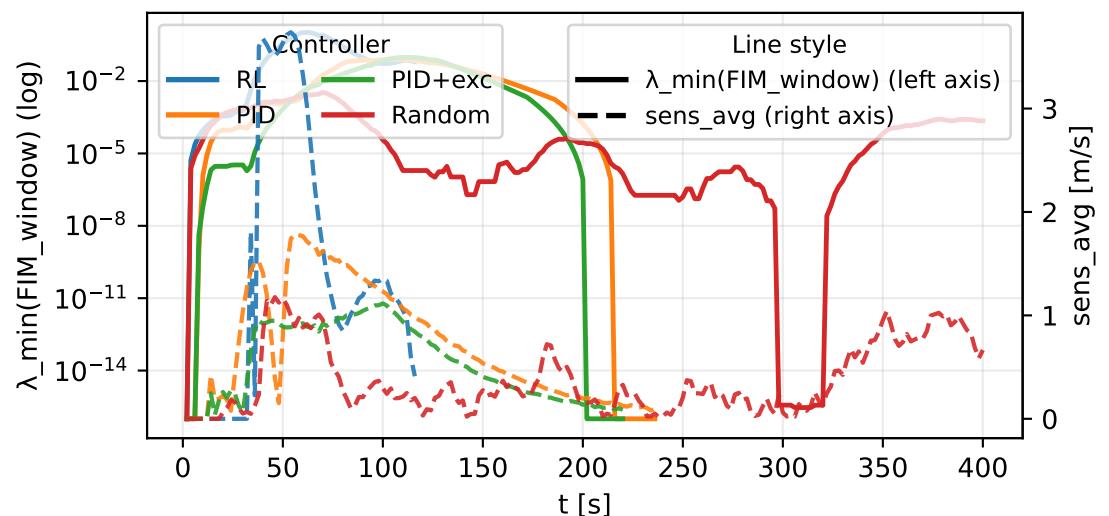
TRUE formation error



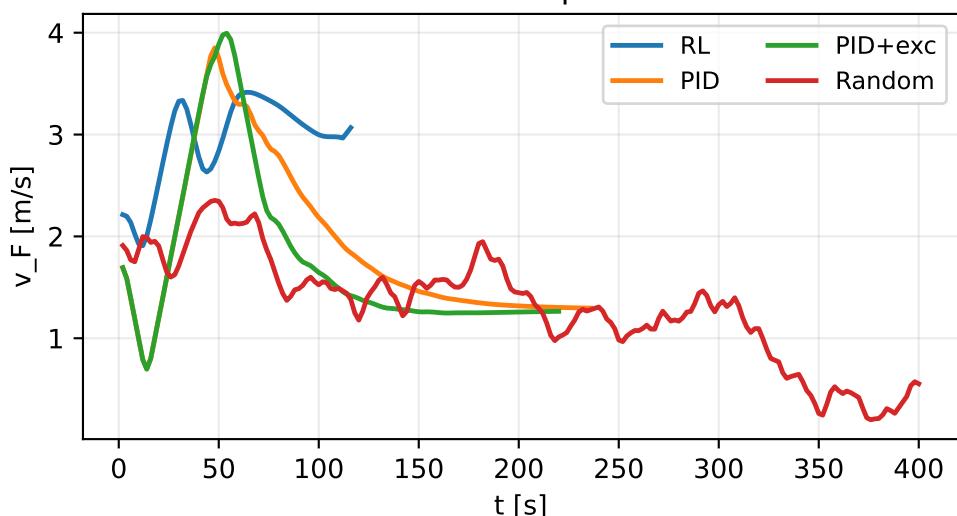
Estimator uncertainty (std_max)



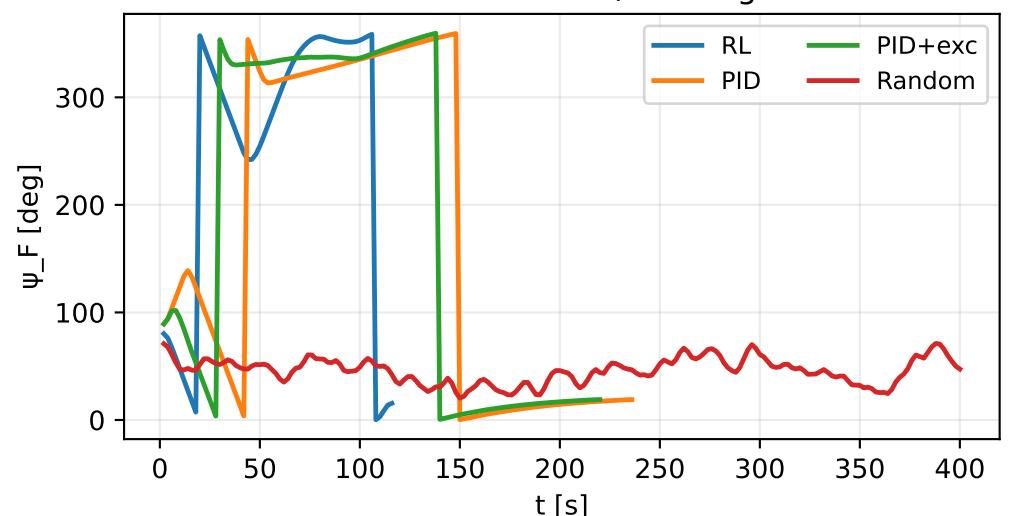
Information and excitation



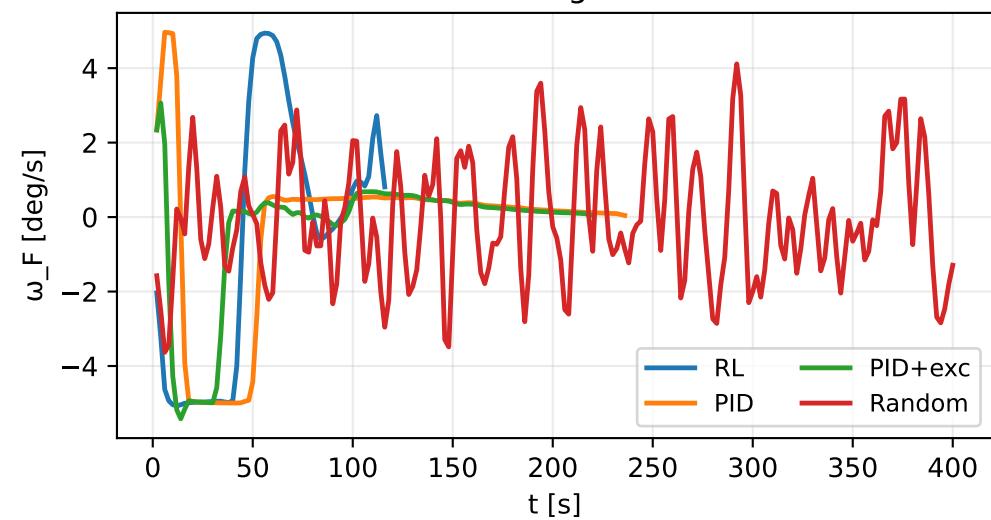
Follower speed



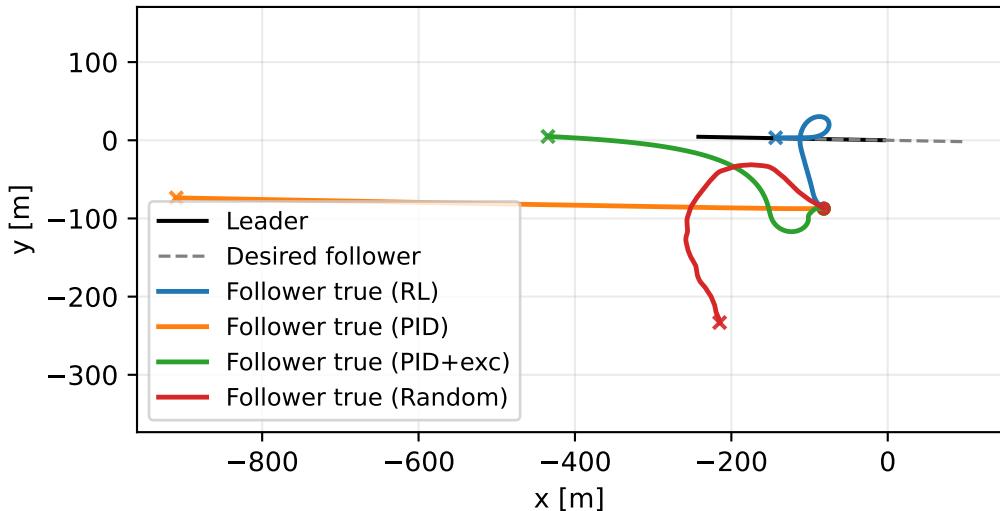
Follower course/heading



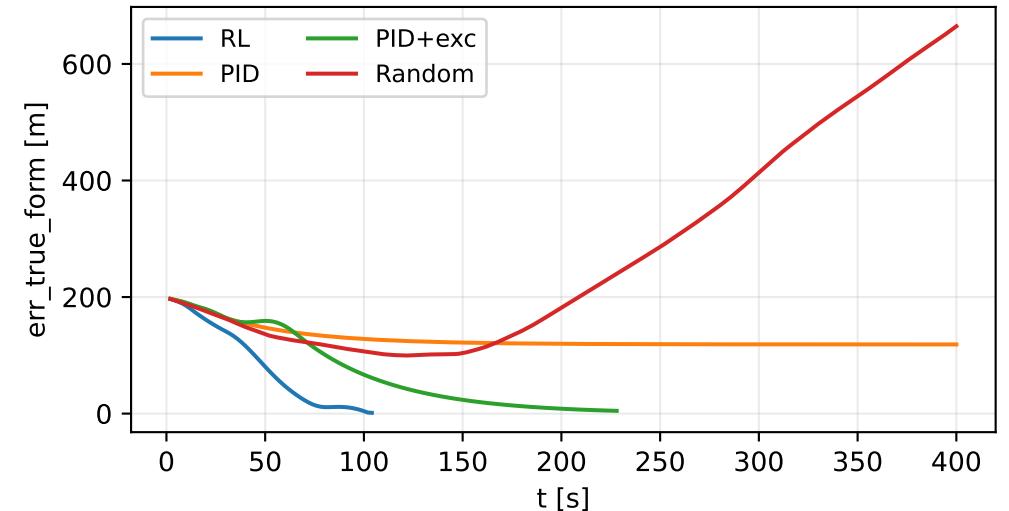
Follower angular rate



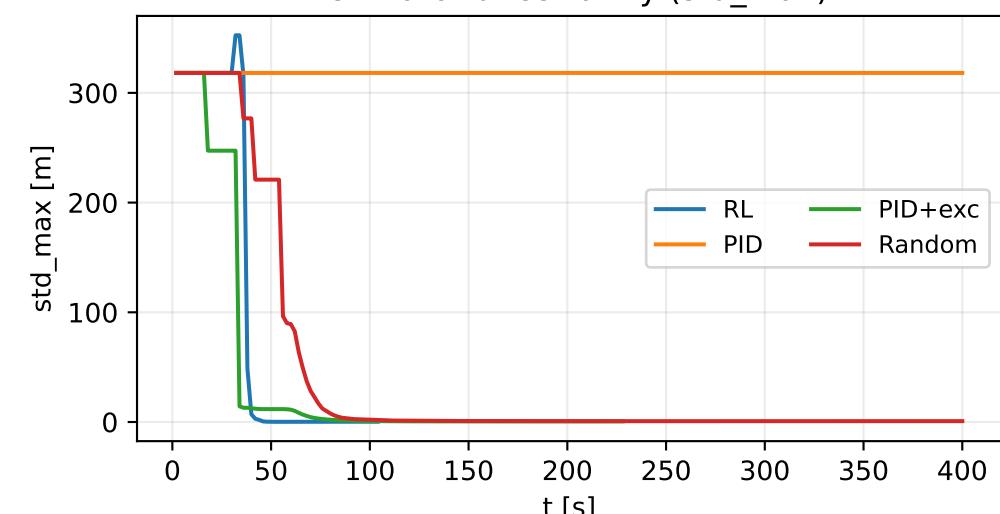
Trajectories (matched seed)



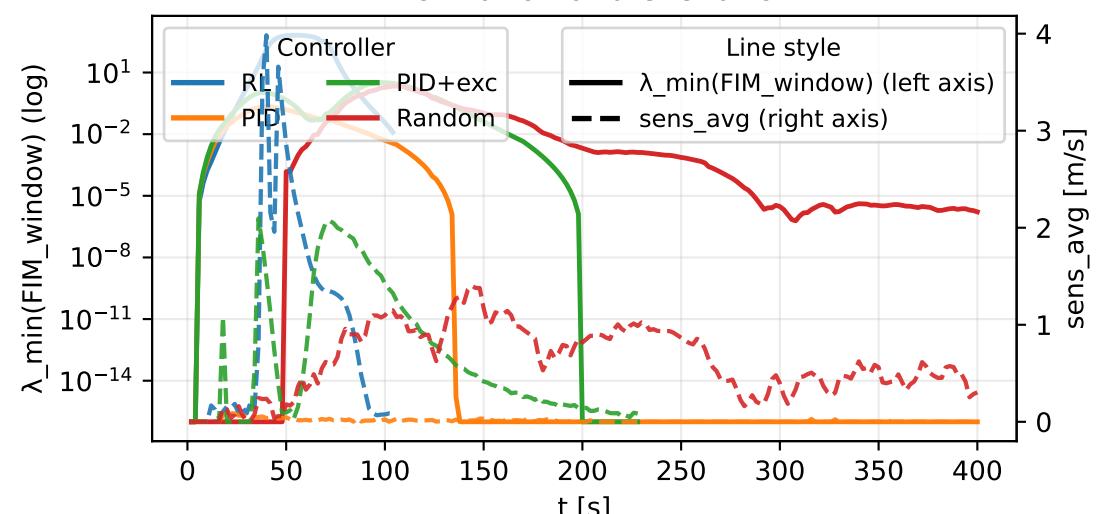
TRUE formation error



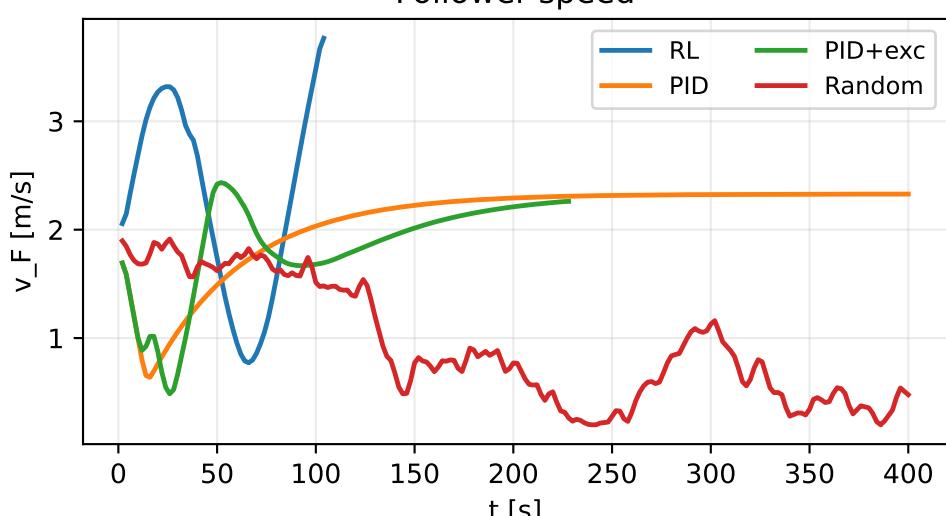
Estimator uncertainty (std_max)



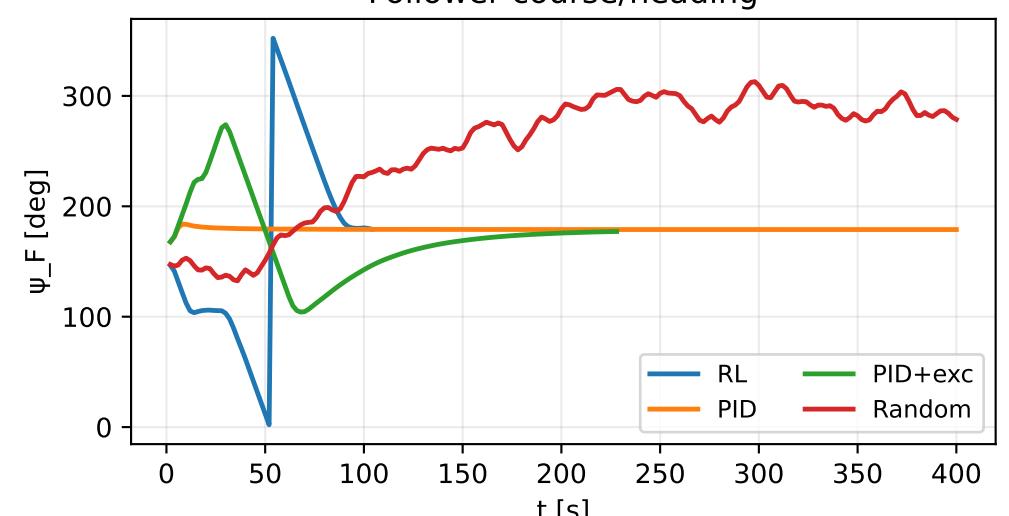
Information and excitation



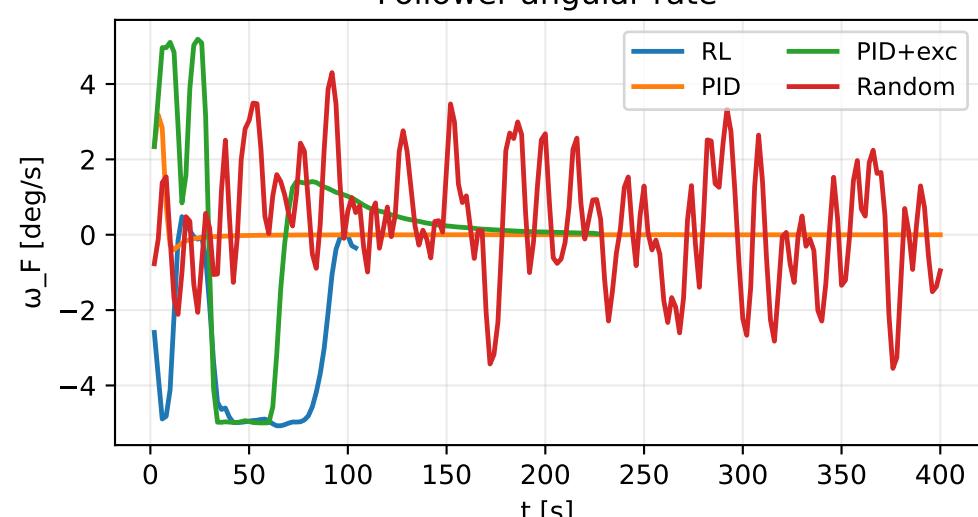
Follower speed



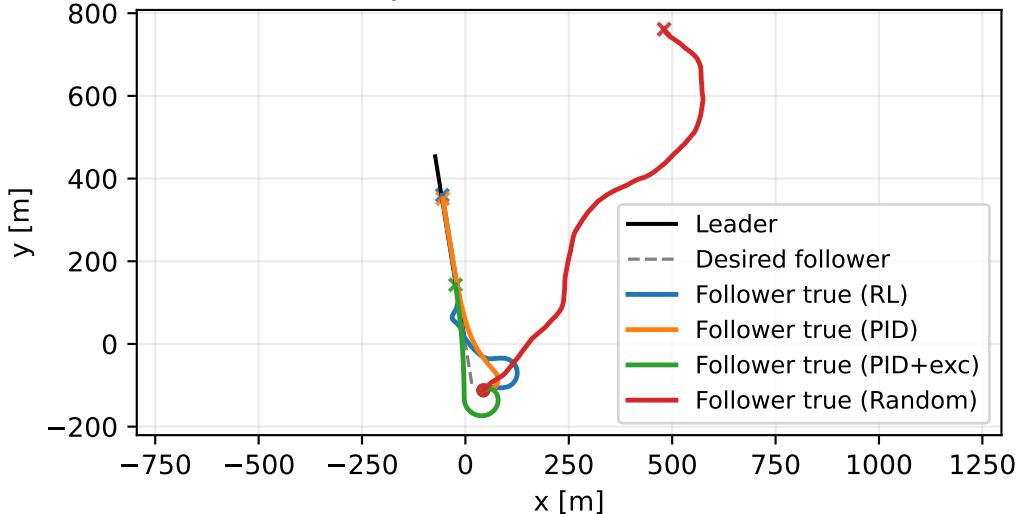
Follower course/heading



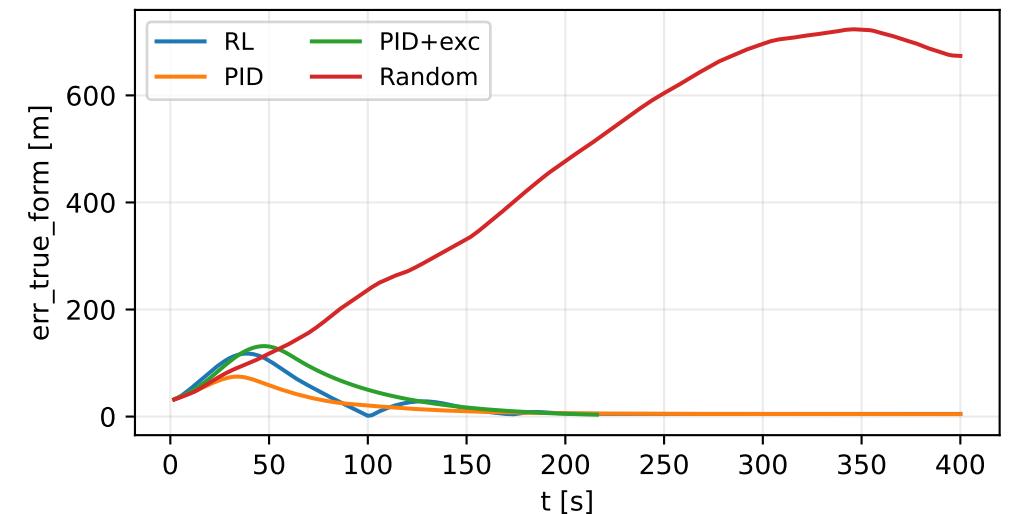
Follower angular rate



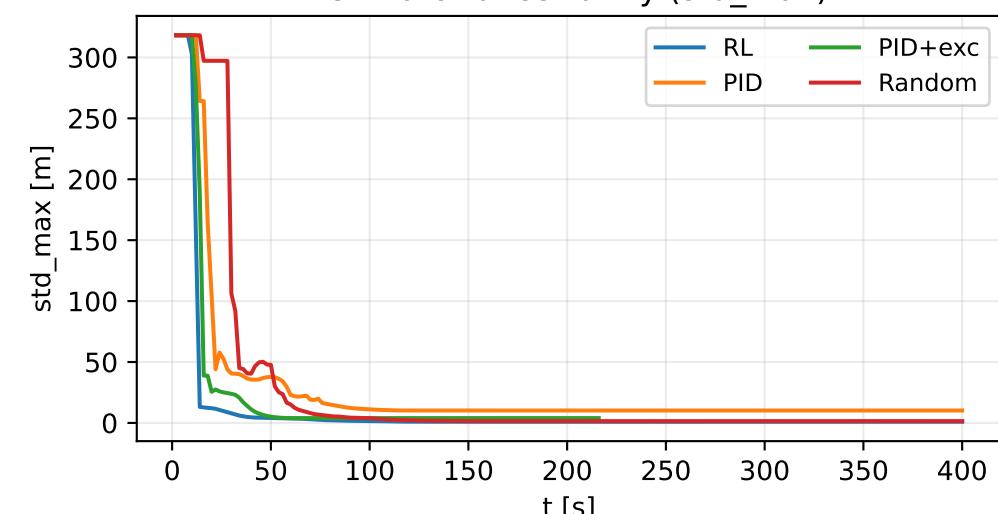
Trajectories (matched seed)



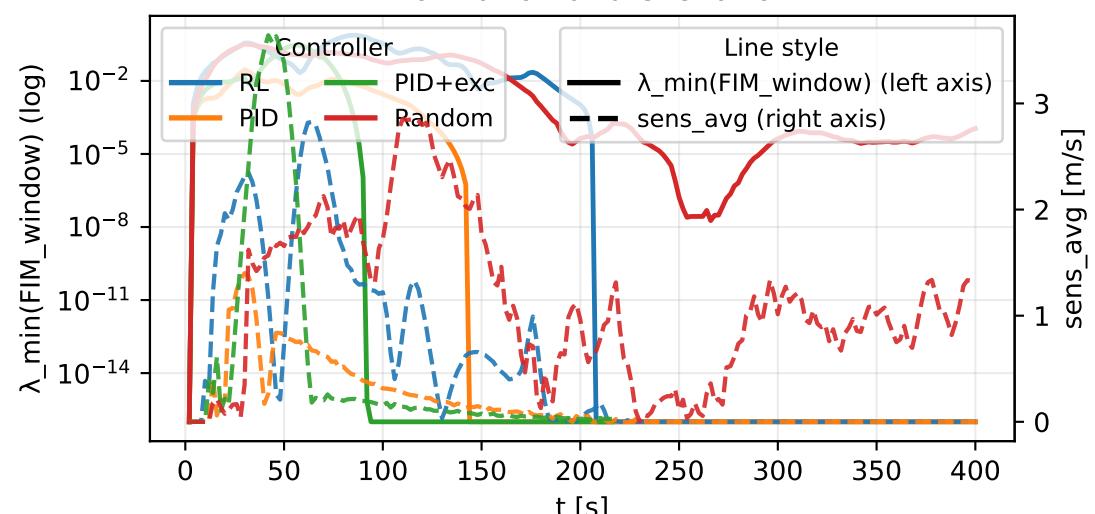
TRUE formation error



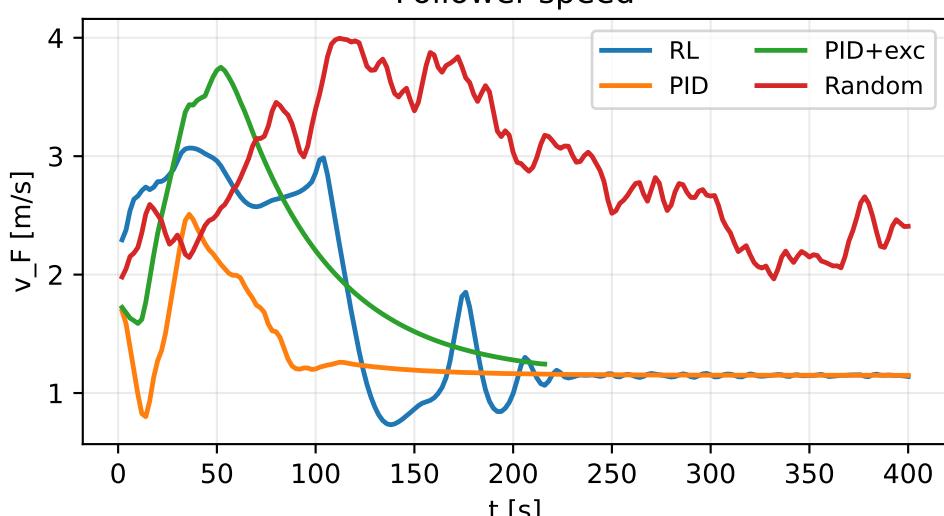
Estimator uncertainty (std_max)



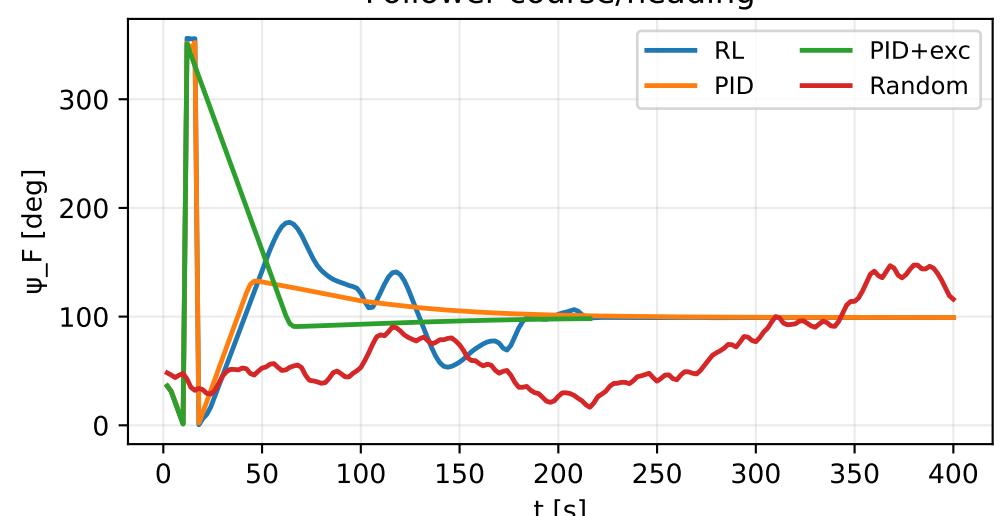
Information and excitation



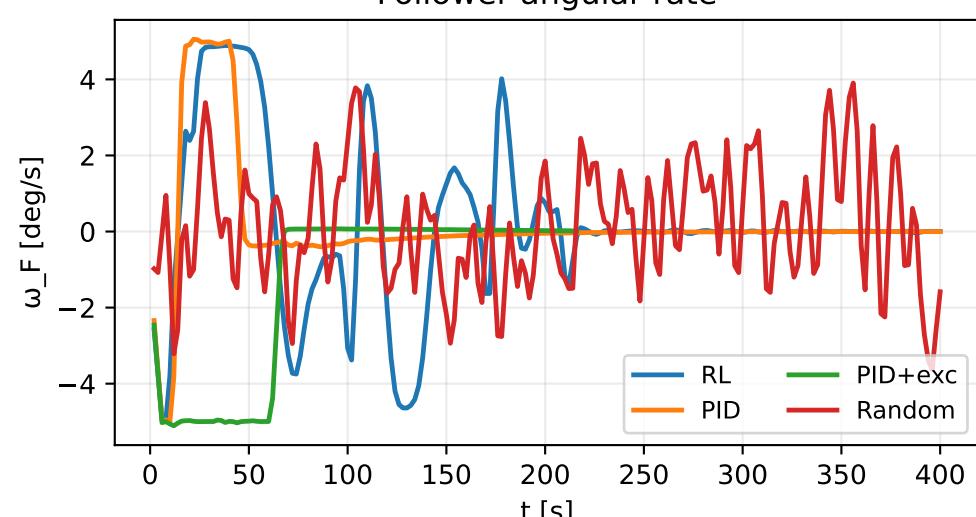
Follower speed



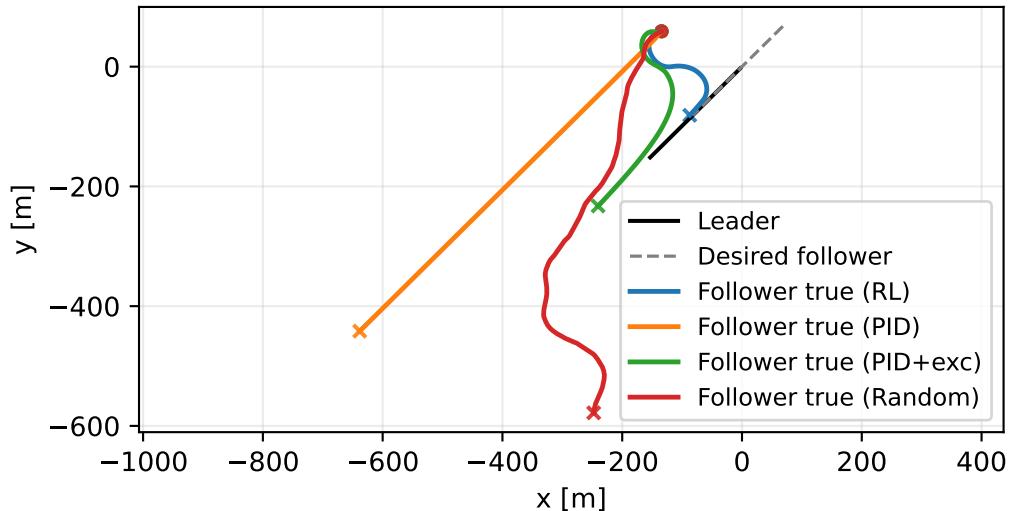
Follower course/heading



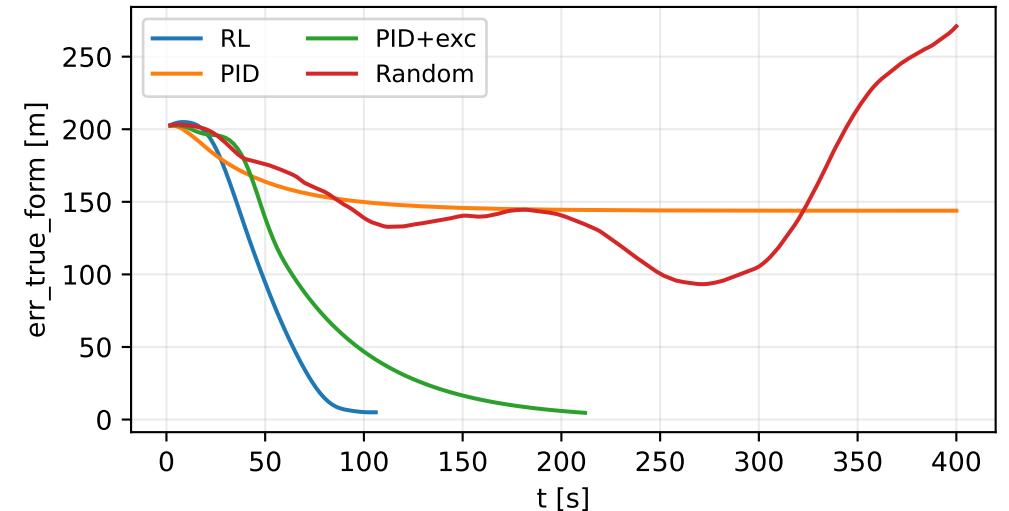
Follower angular rate



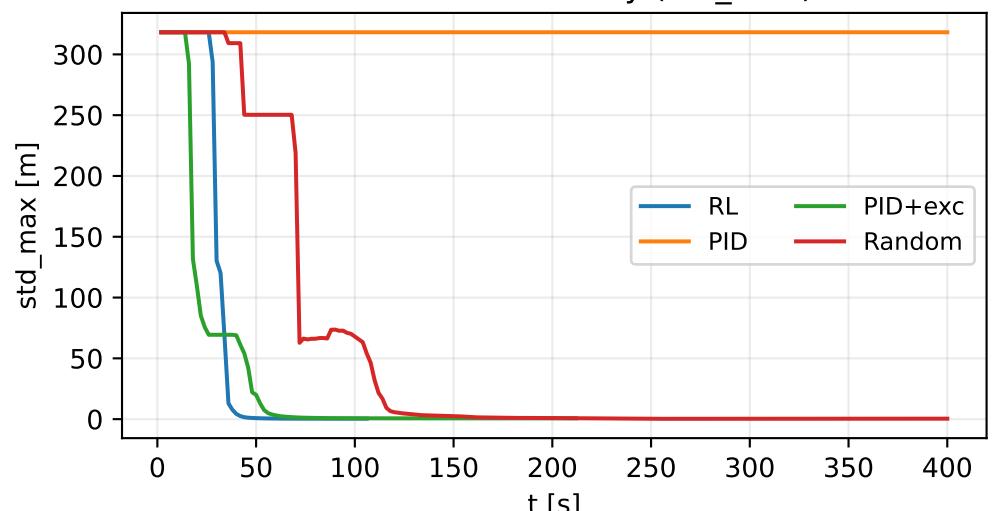
Trajectories (matched seed)



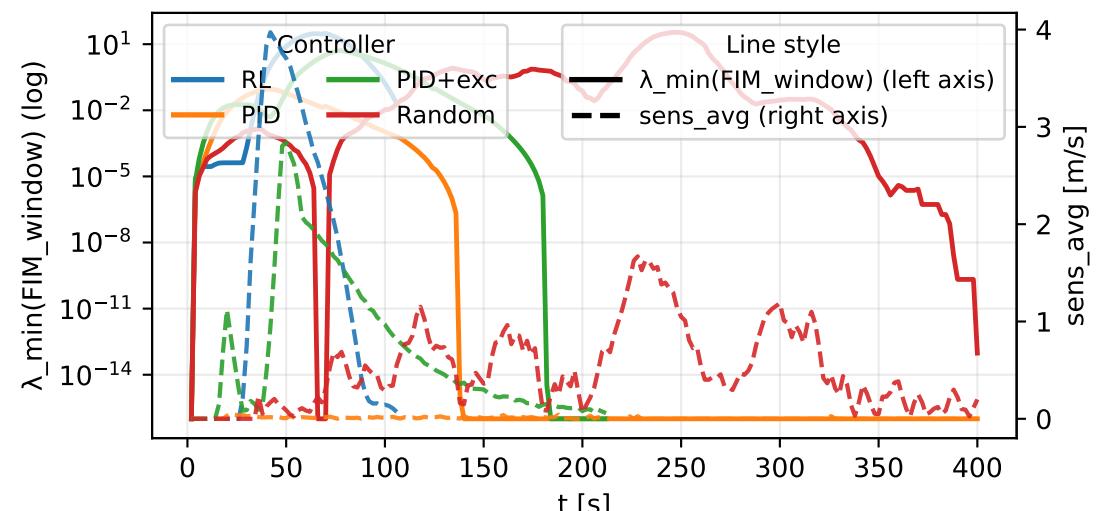
TRUE formation error



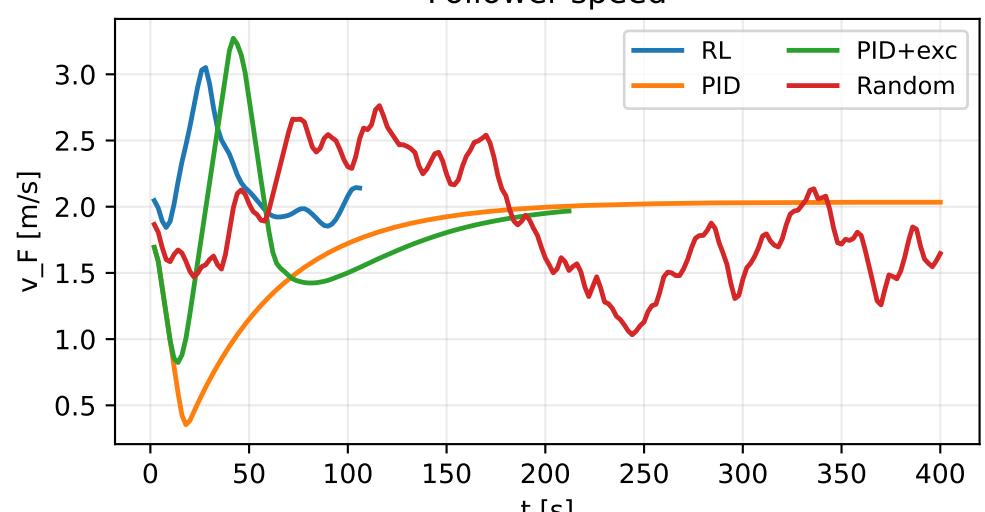
Estimator uncertainty (std_max)



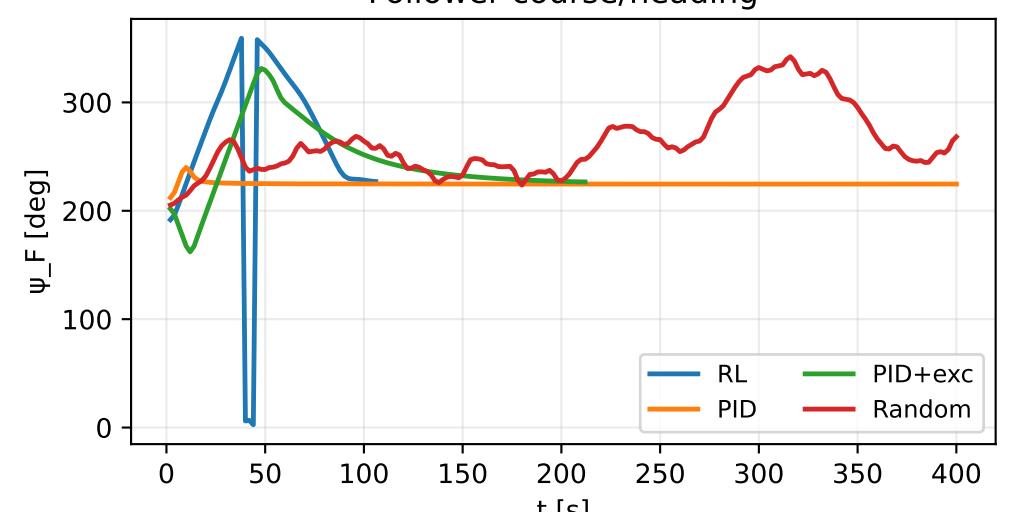
Information and excitation



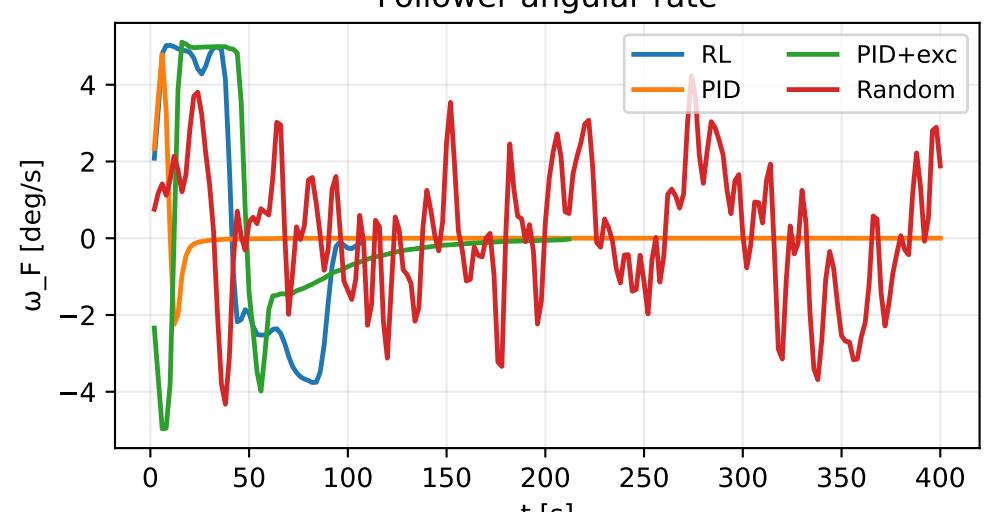
Follower speed



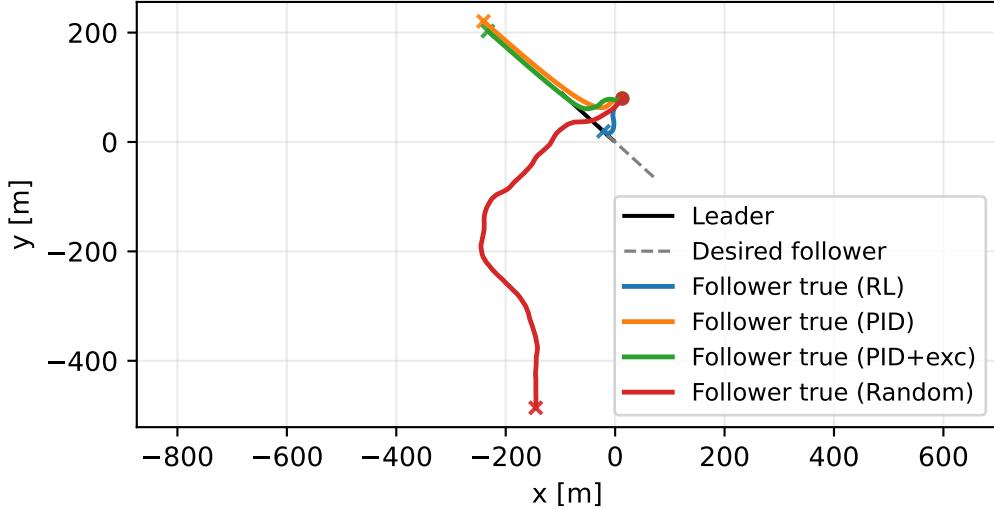
Follower course/heading



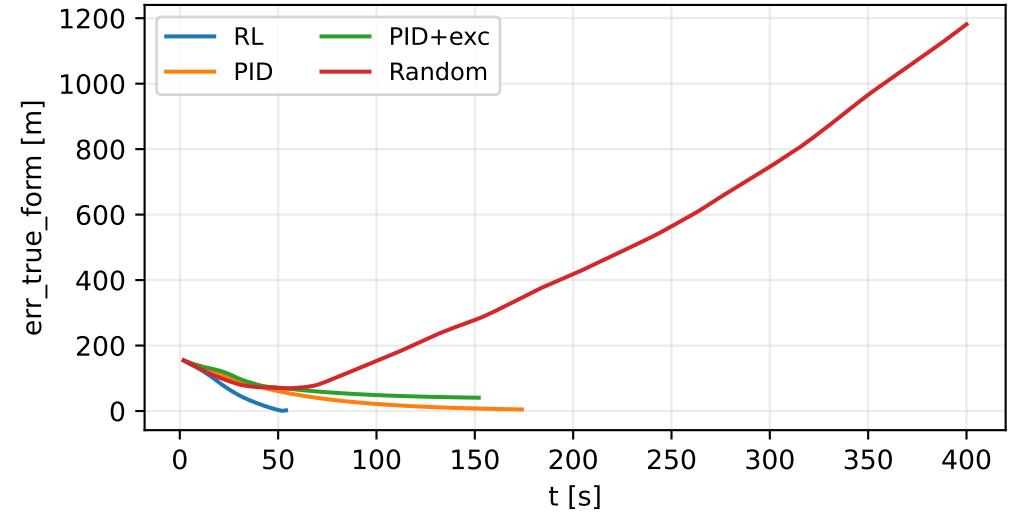
Follower angular rate



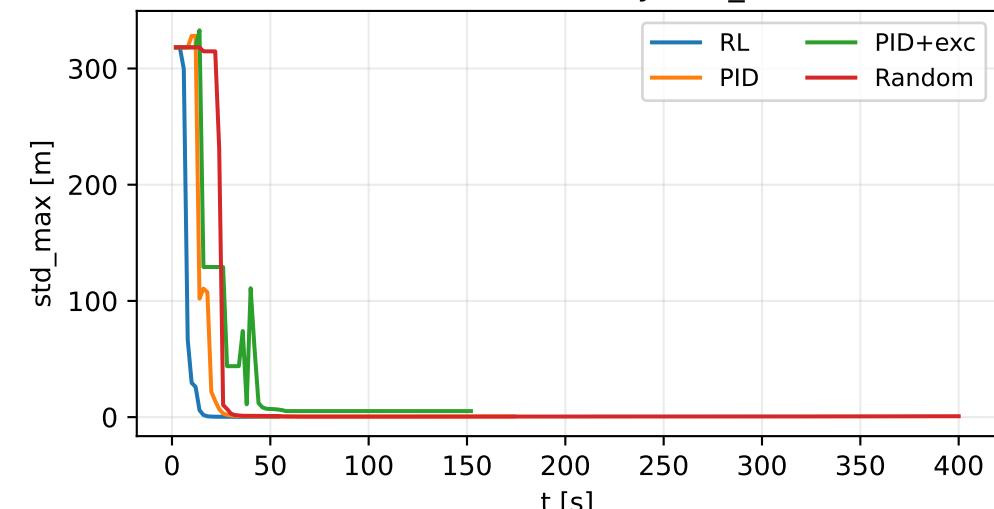
Trajectories (matched seed)



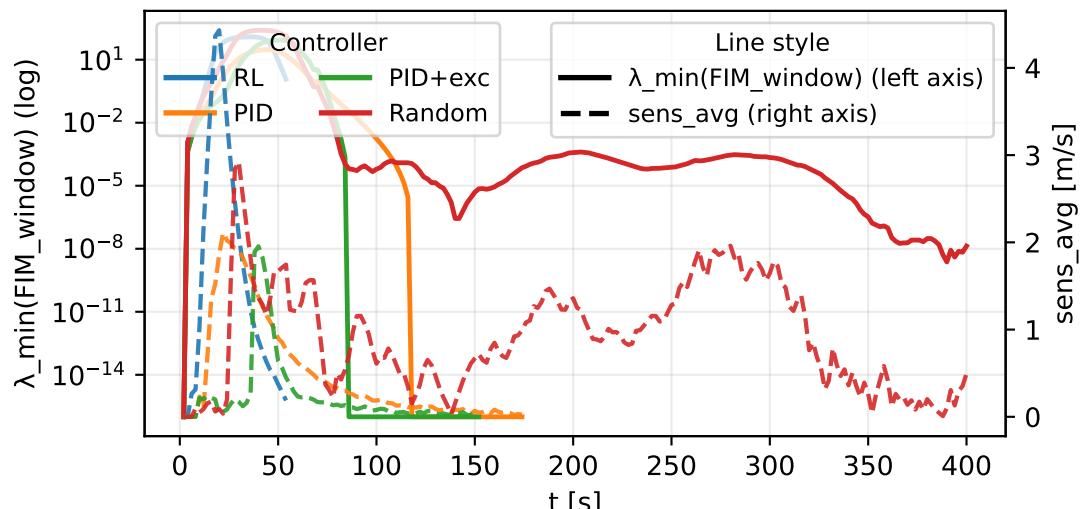
TRUE formation error



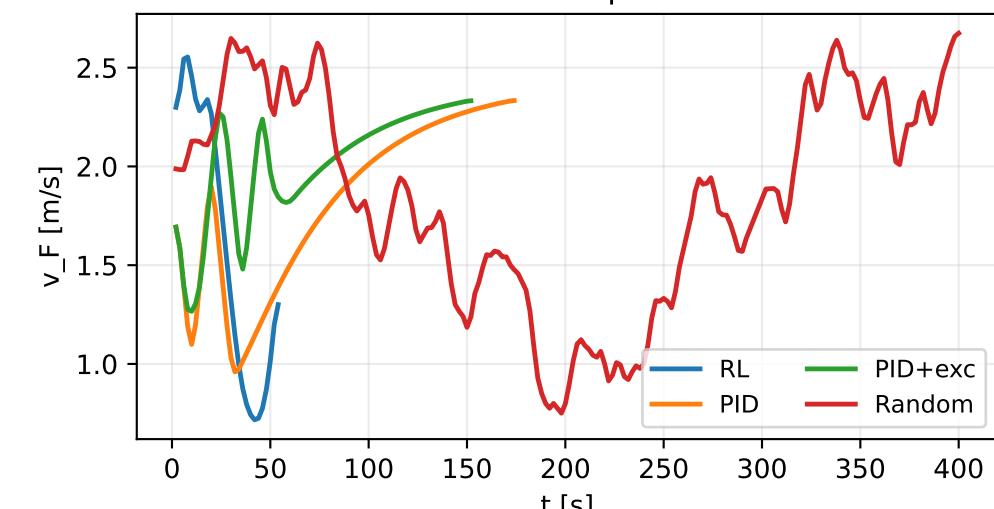
Estimator uncertainty (std_max)



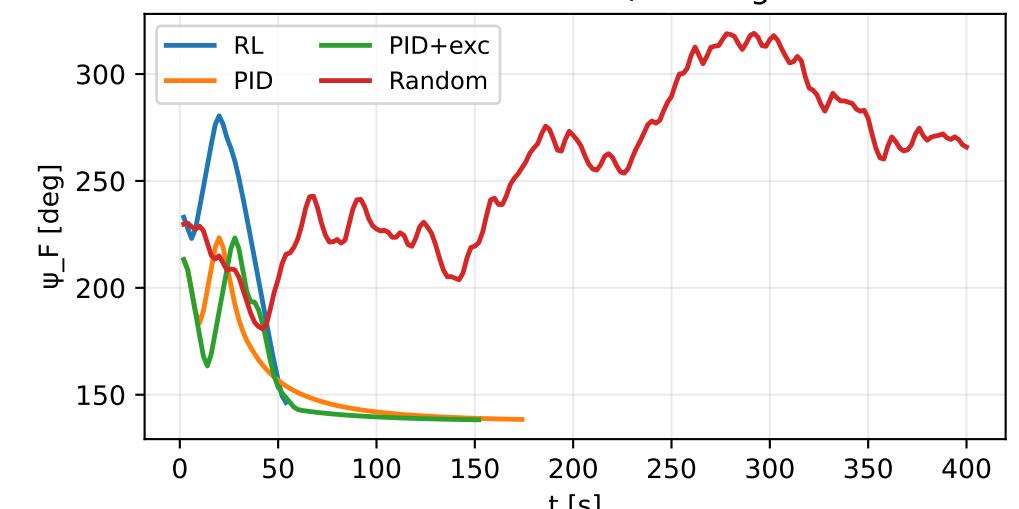
Information and excitation



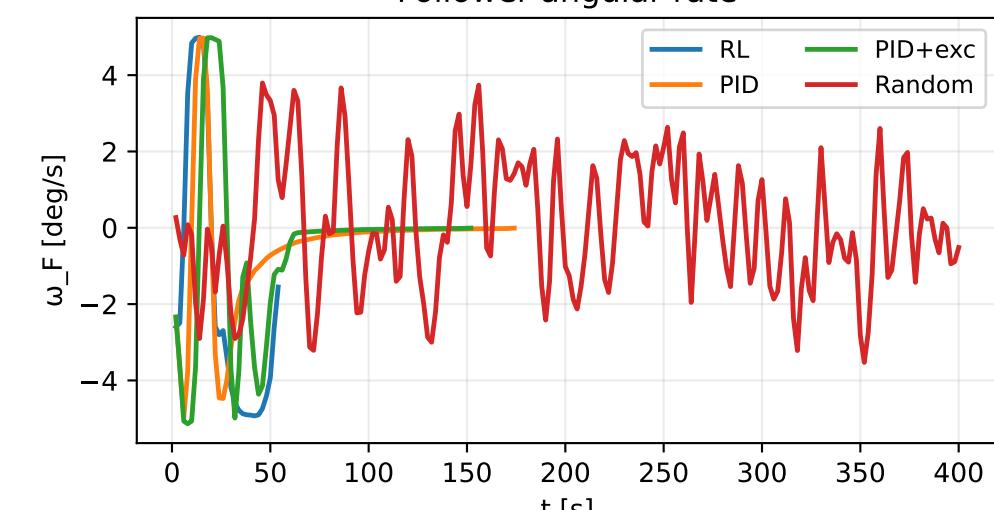
Follower speed



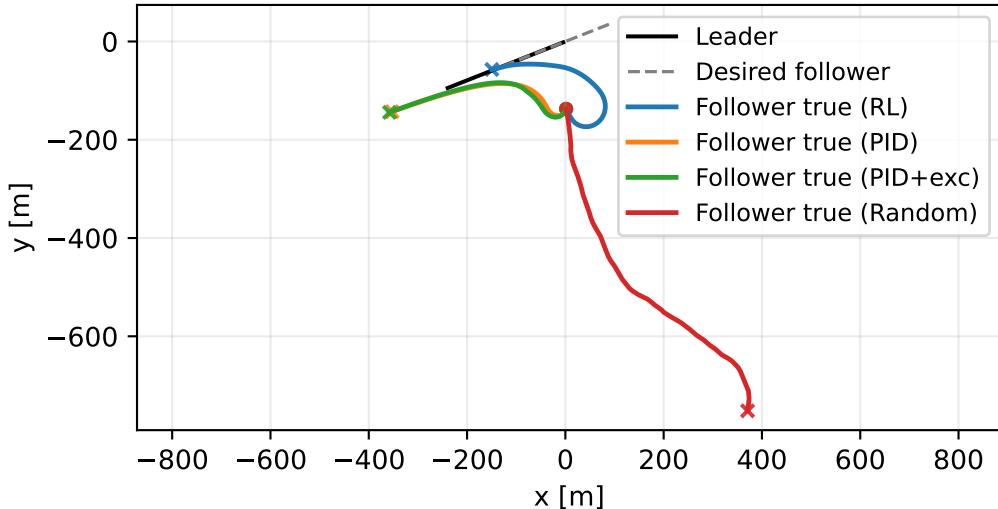
Follower course/heading



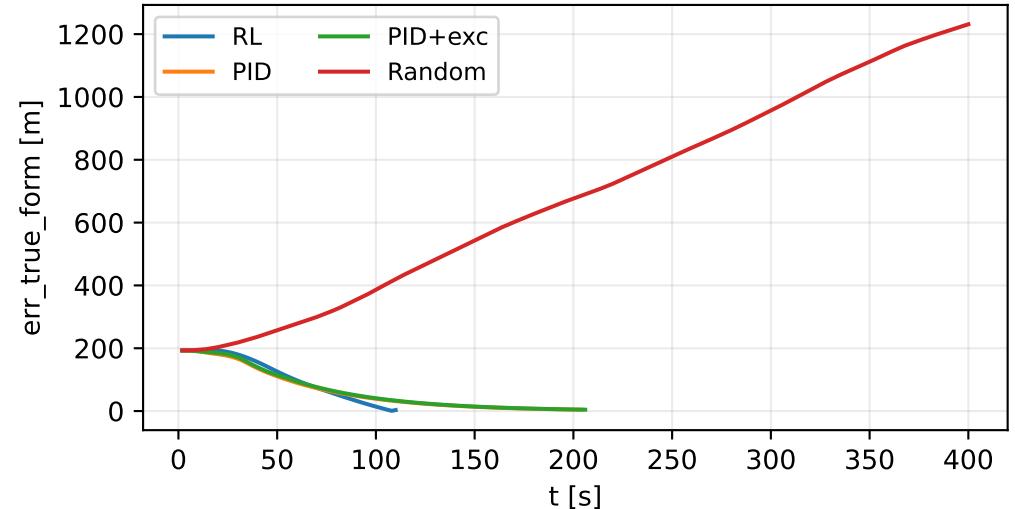
Follower angular rate



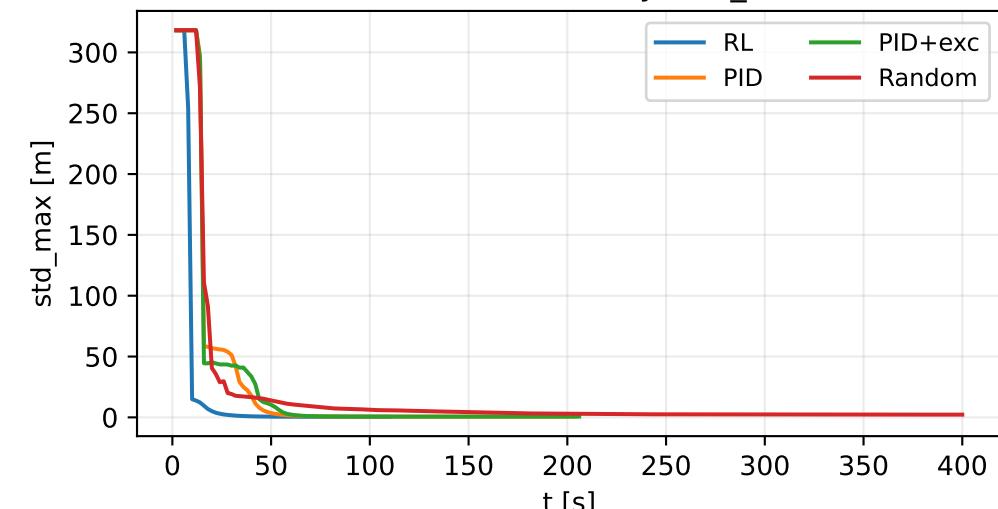
Trajectories (matched seed)



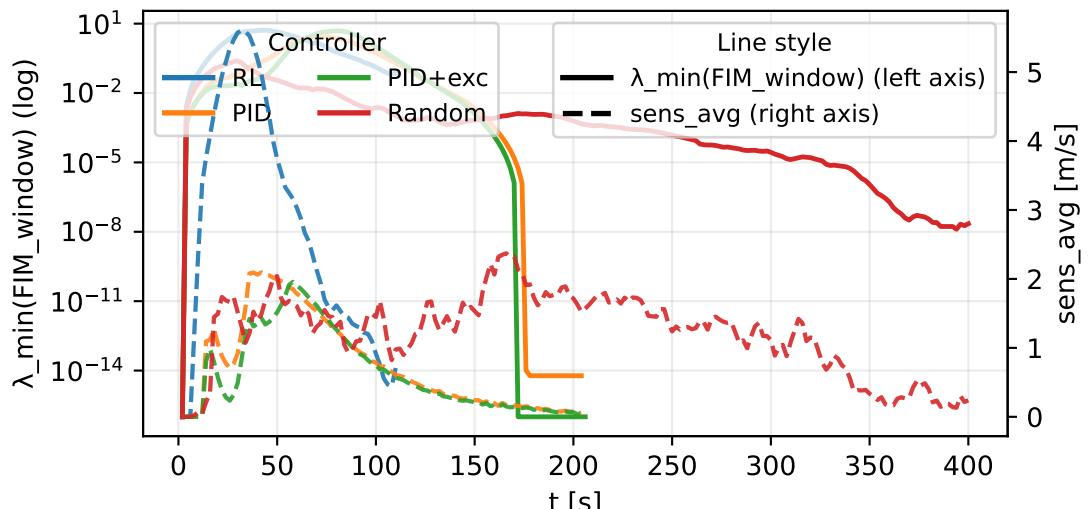
TRUE formation error



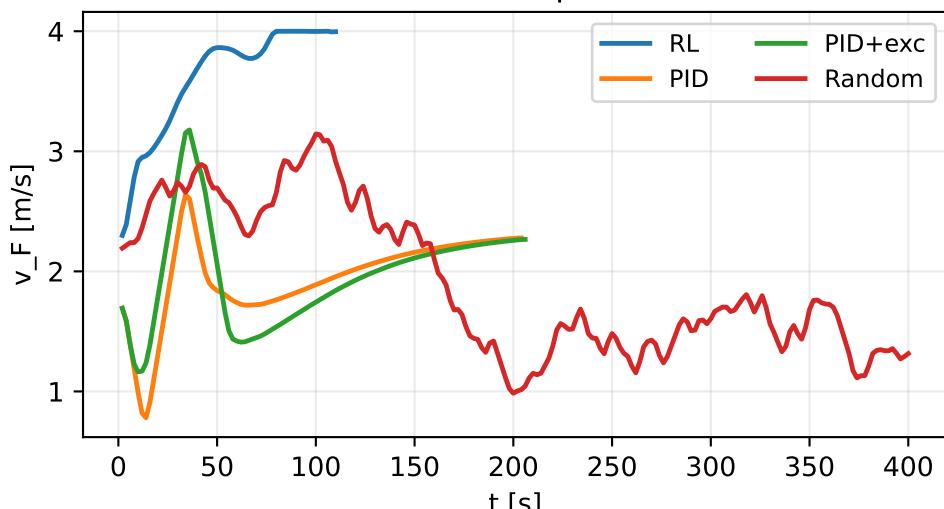
Estimator uncertainty (std_max)



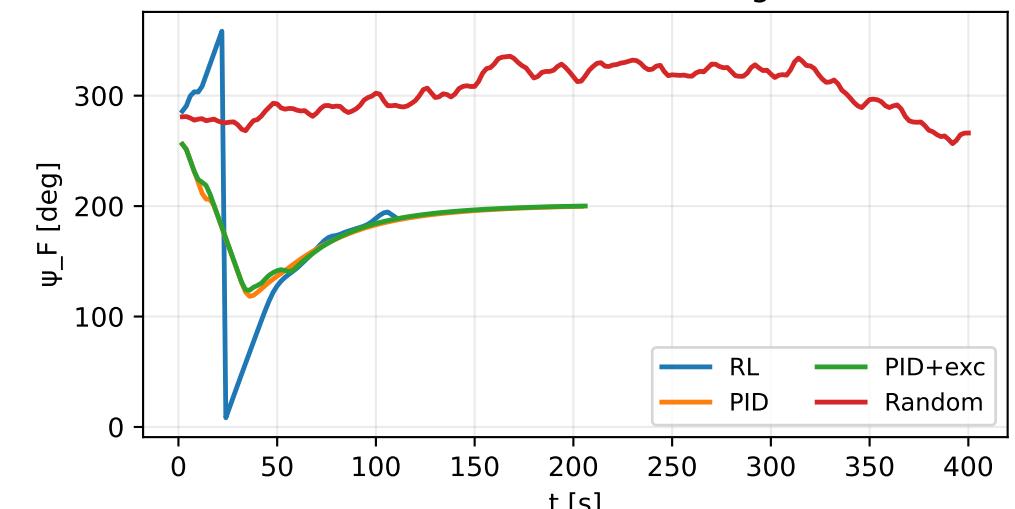
Information and excitation



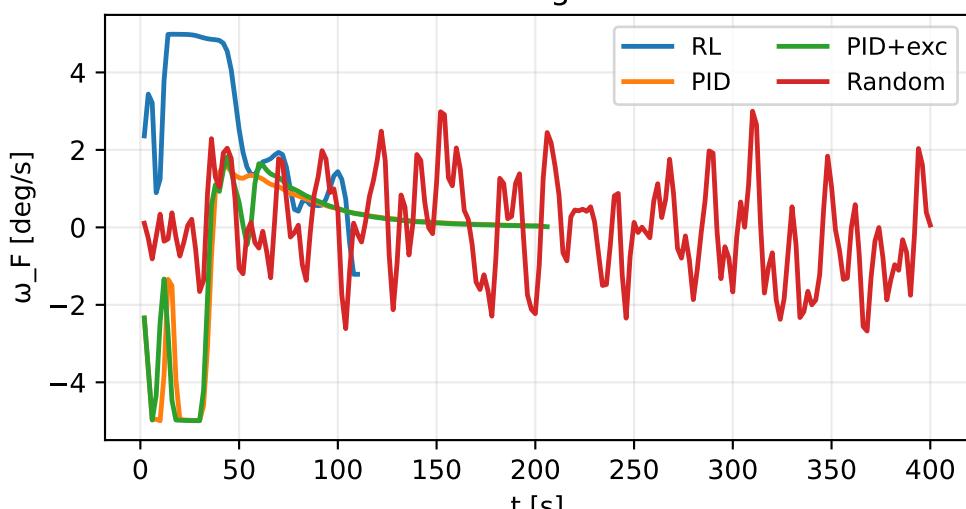
Follower speed



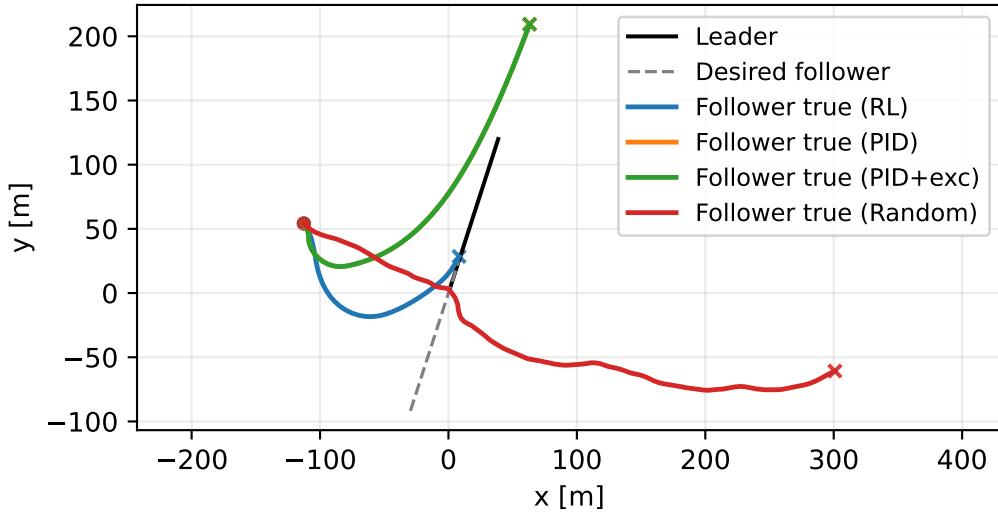
Follower course/heading



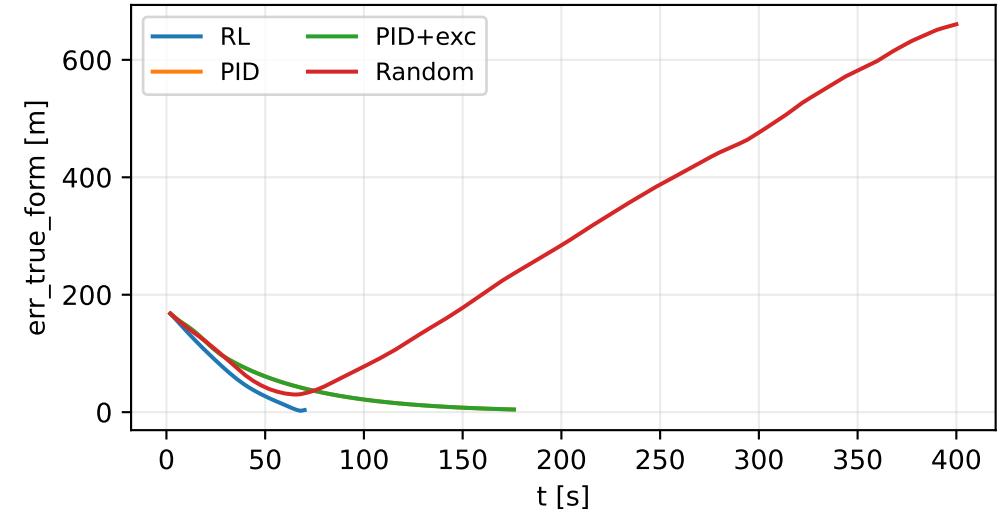
Follower angular rate



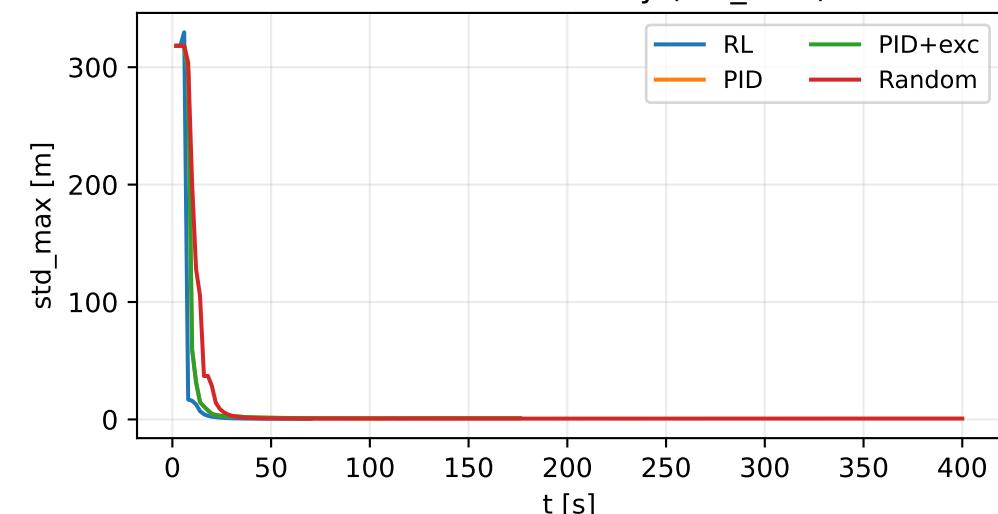
Trajectories (matched seed)



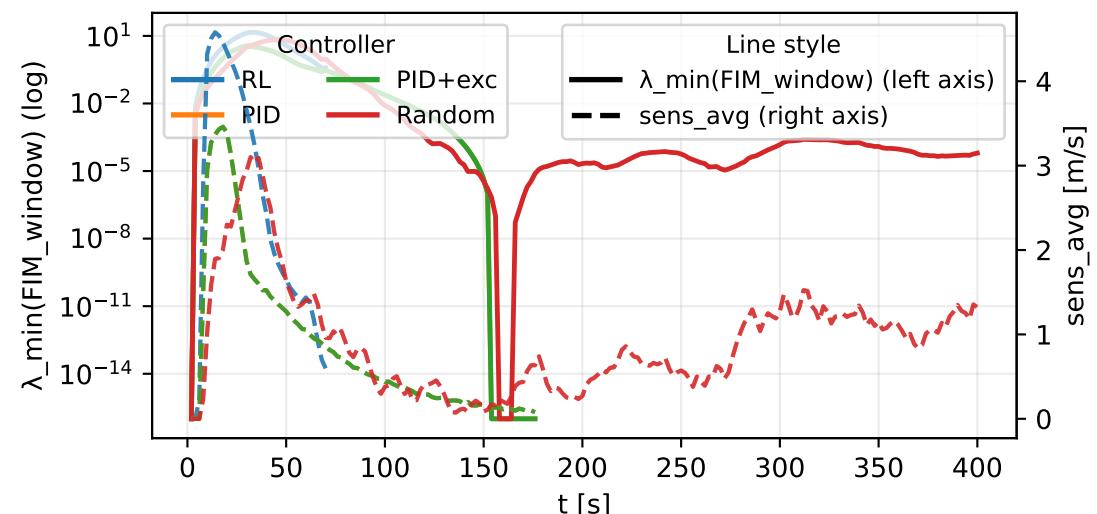
TRUE formation error



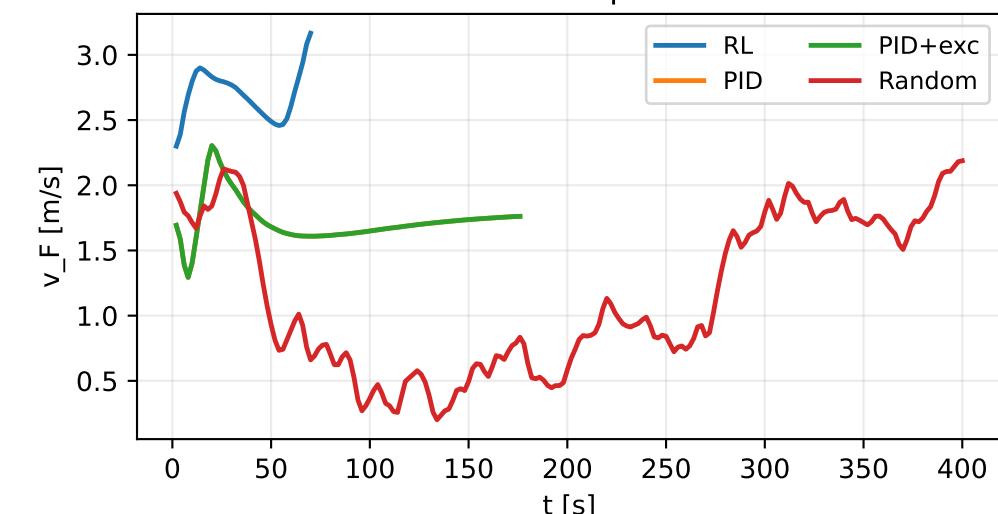
Estimator uncertainty (std_max)



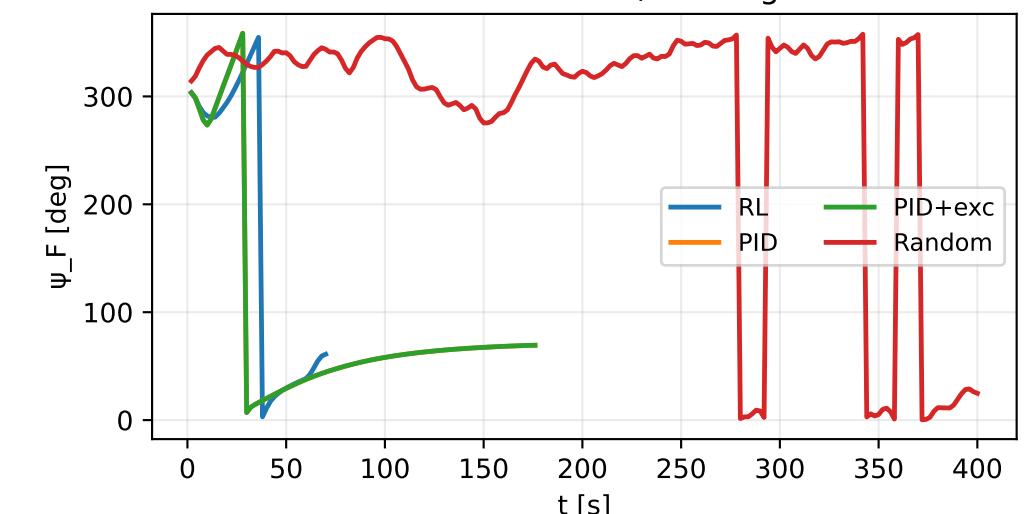
Information and excitation



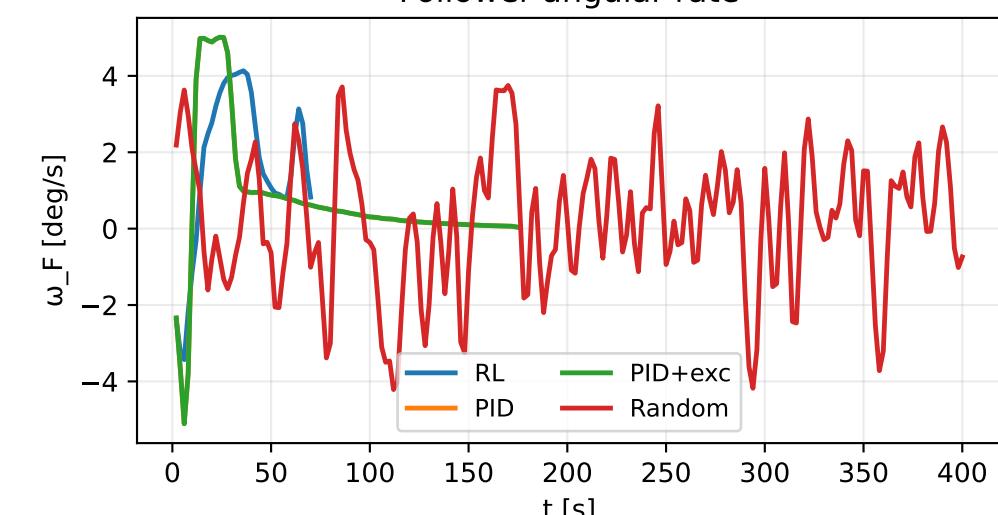
Follower speed



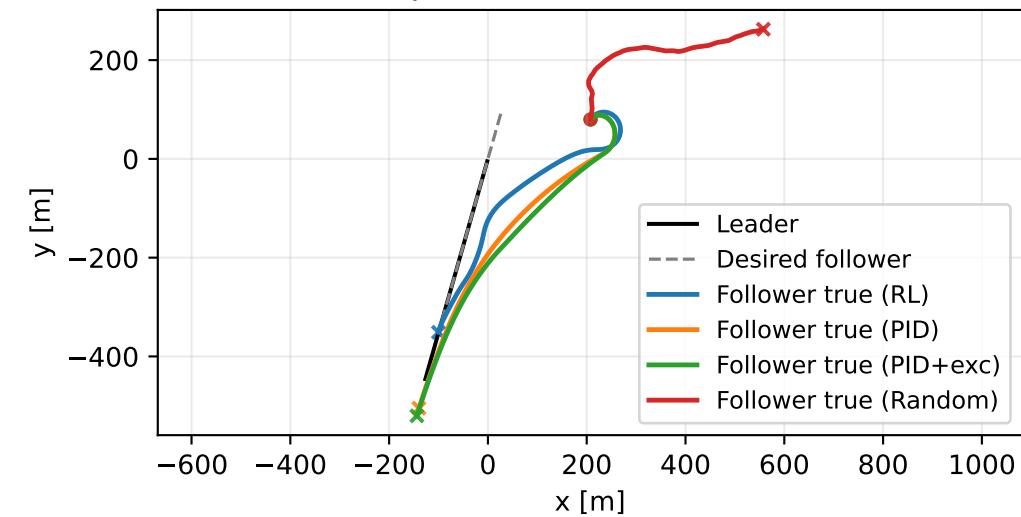
Follower course/heading



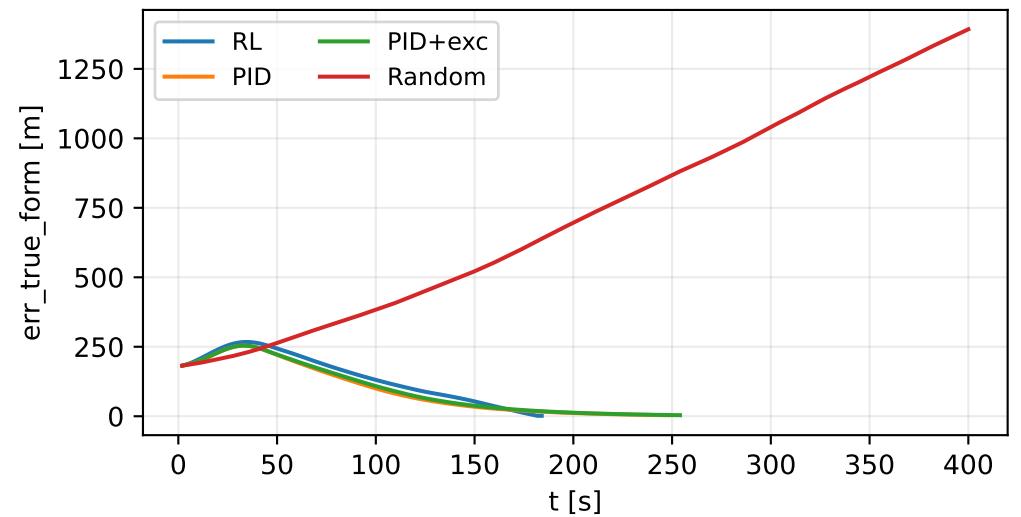
Follower angular rate



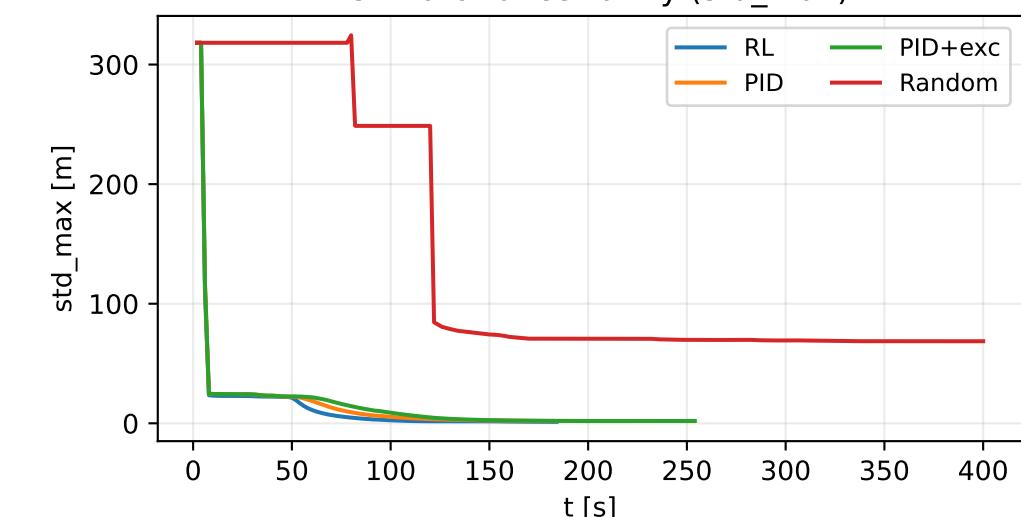
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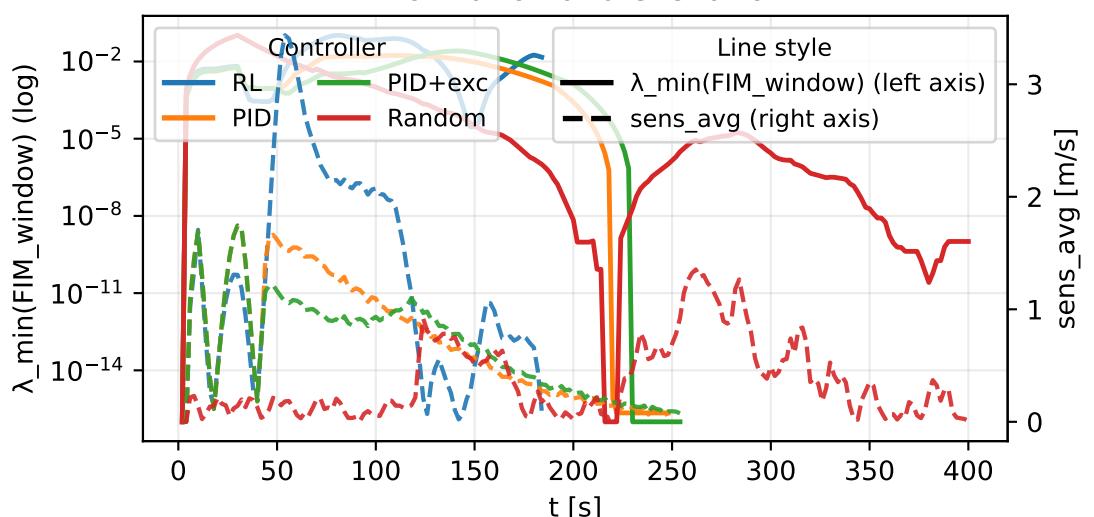
TRUE formation error



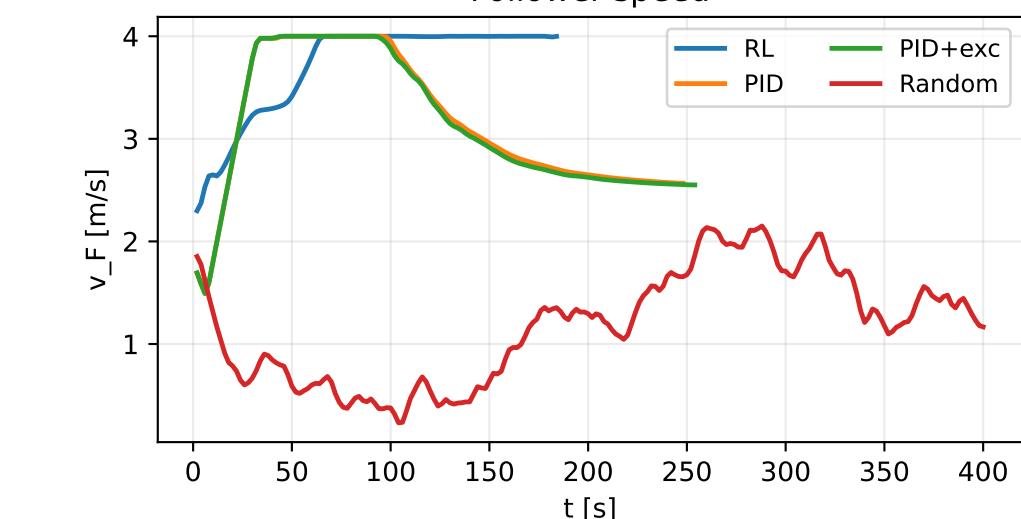
Estimator uncertainty (std_max)



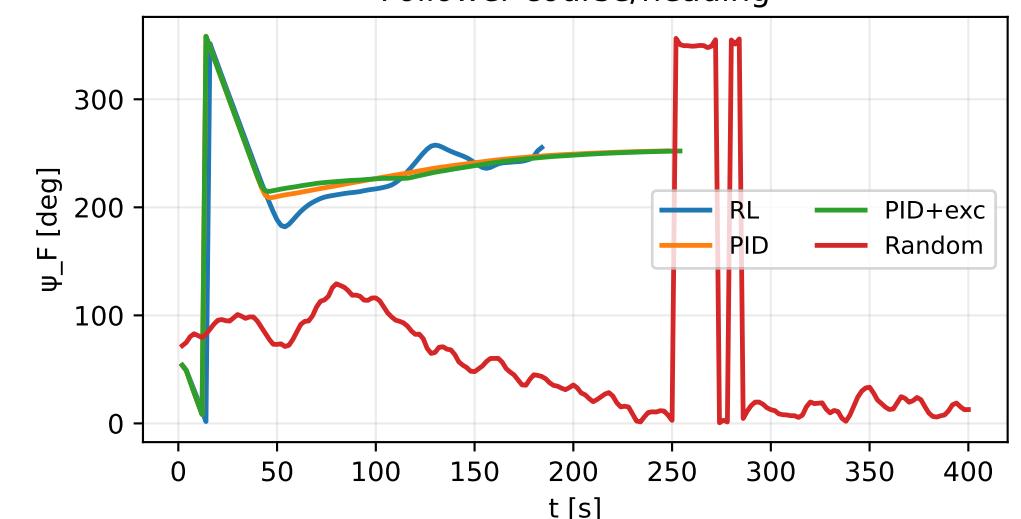
Information and excitation



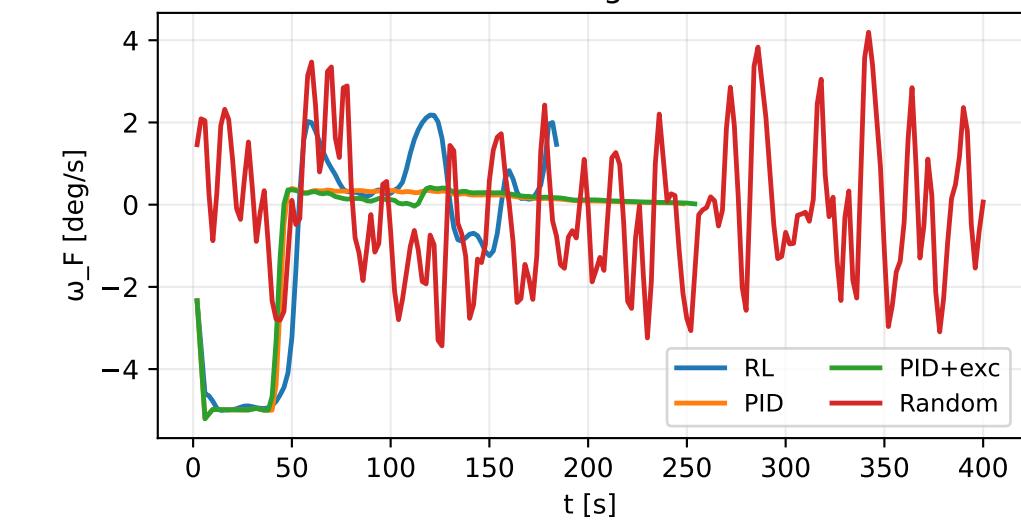
Follower speed



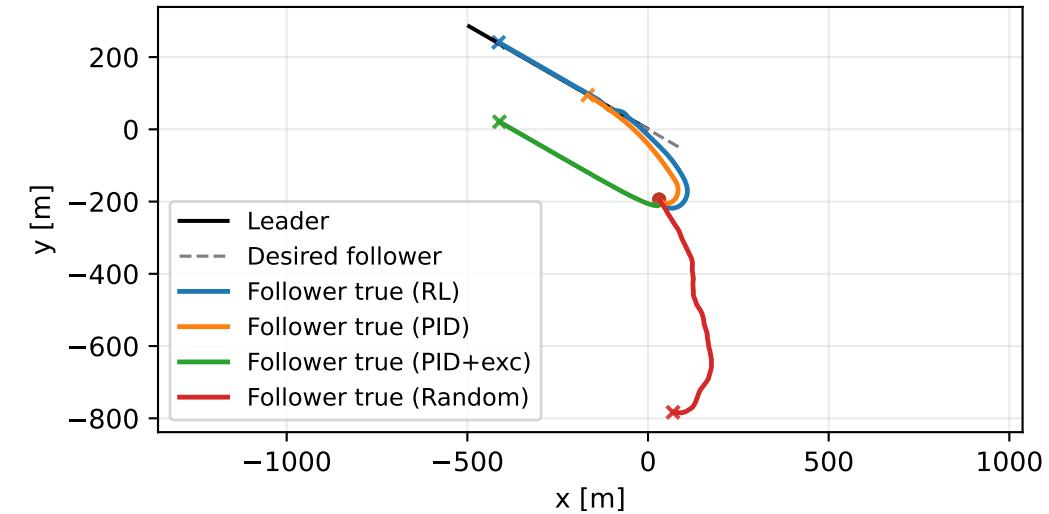
Follower course/heading



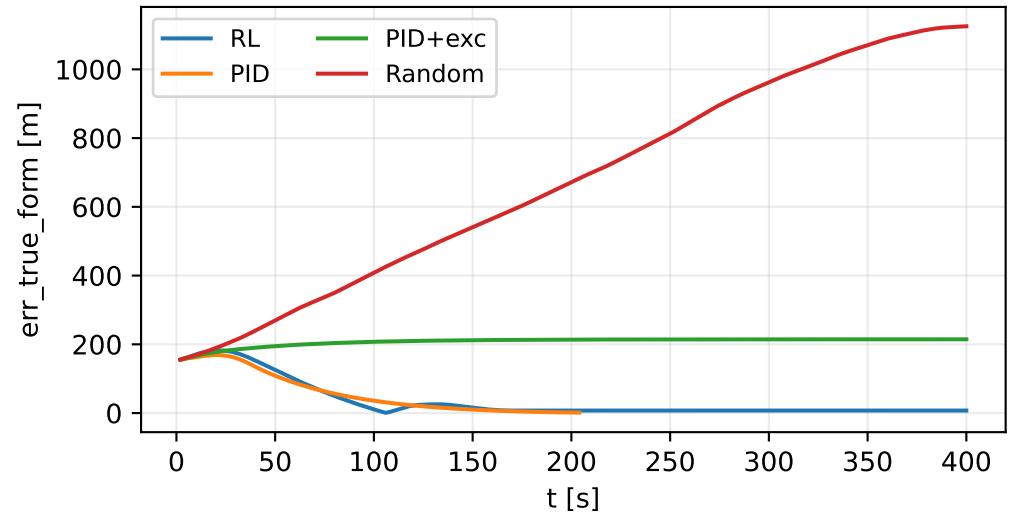
Follower angular rate



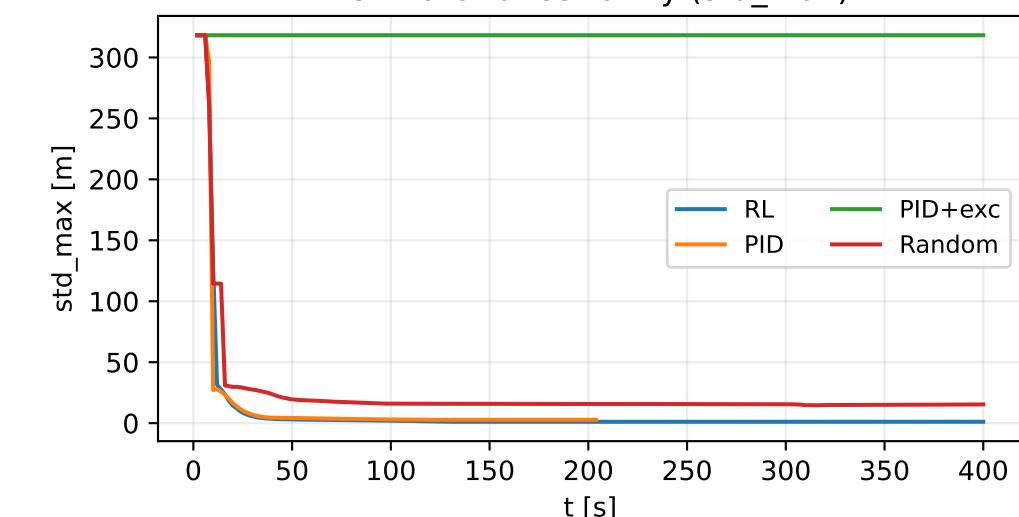
Trajectories (matched seed)



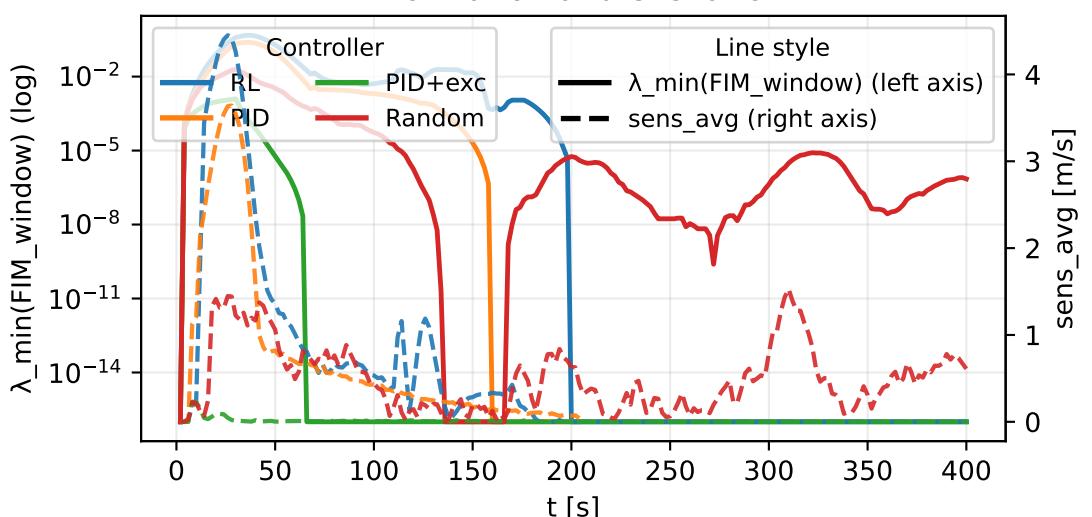
TRUE formation error



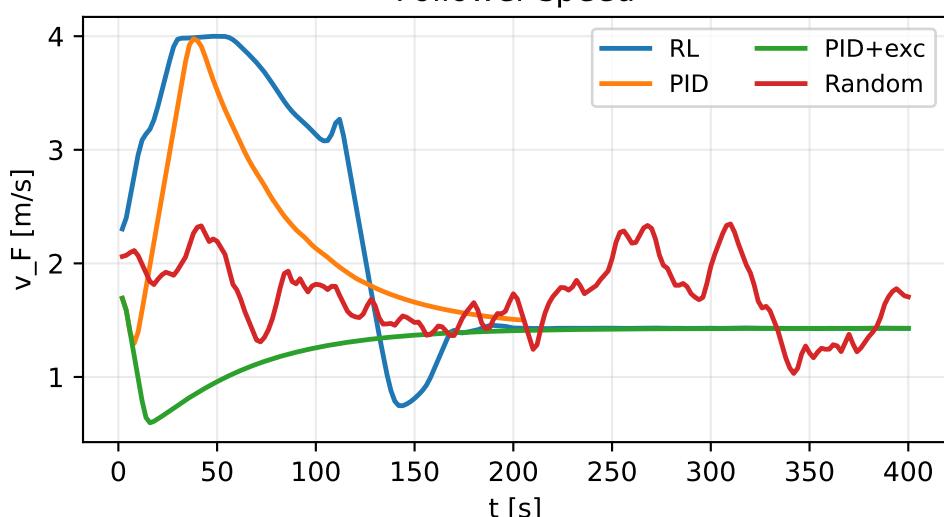
Estimator uncertainty (std_max)



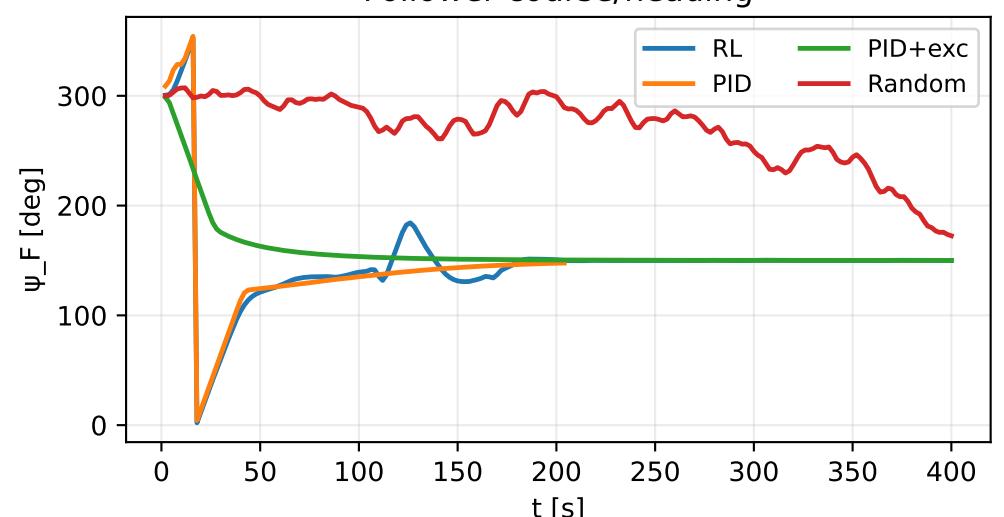
Information and excitation



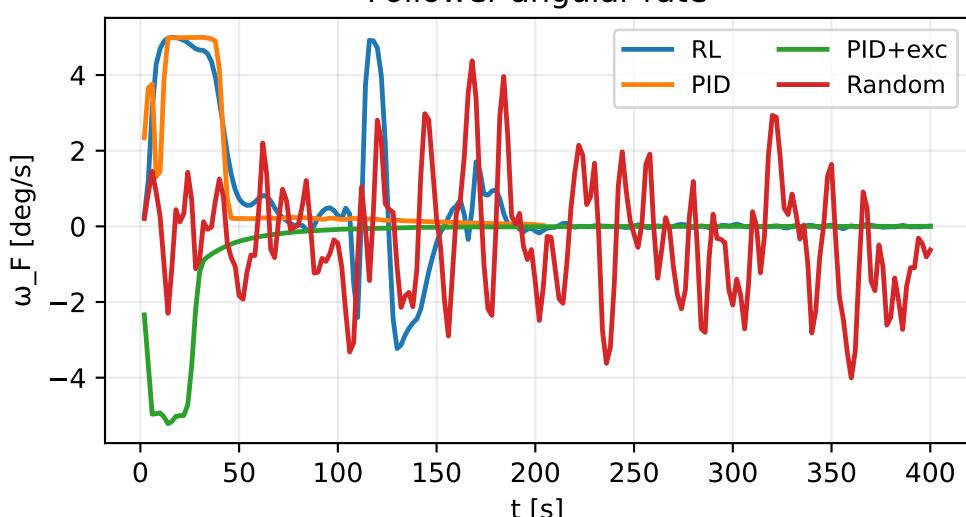
Follower speed



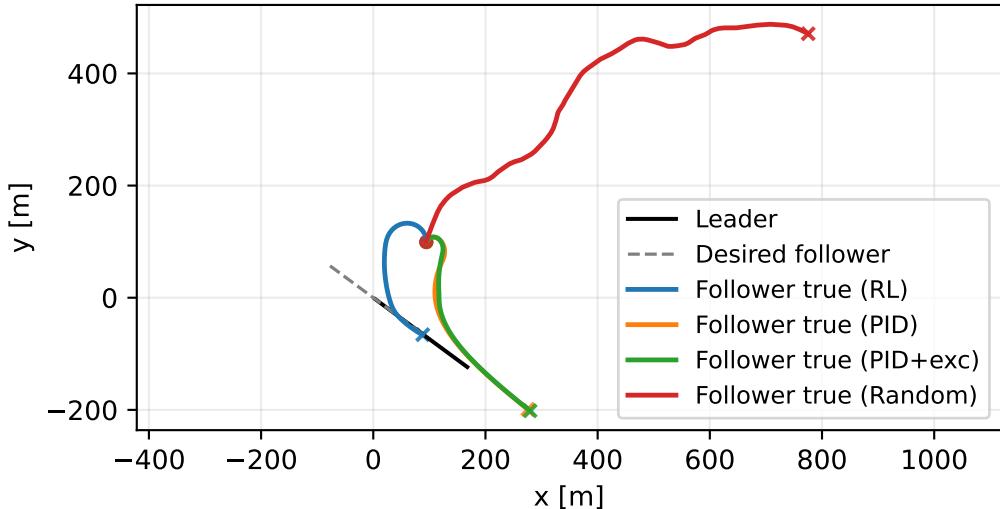
Follower course/heading



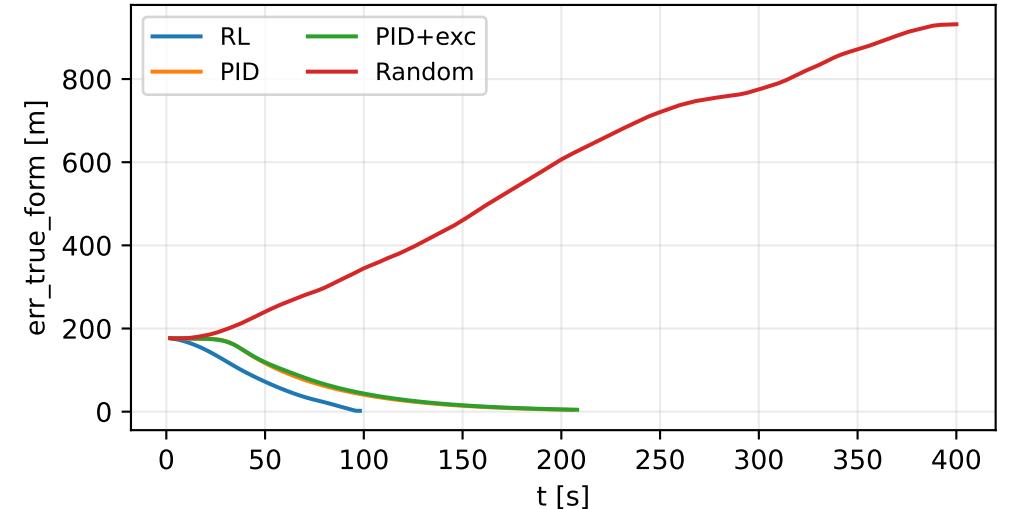
Follower angular rate



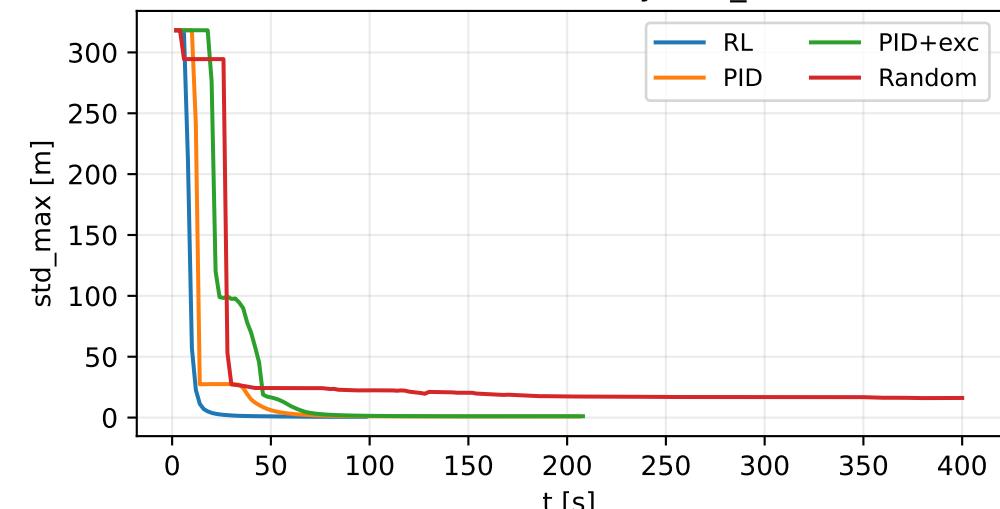
Trajectories (matched seed)



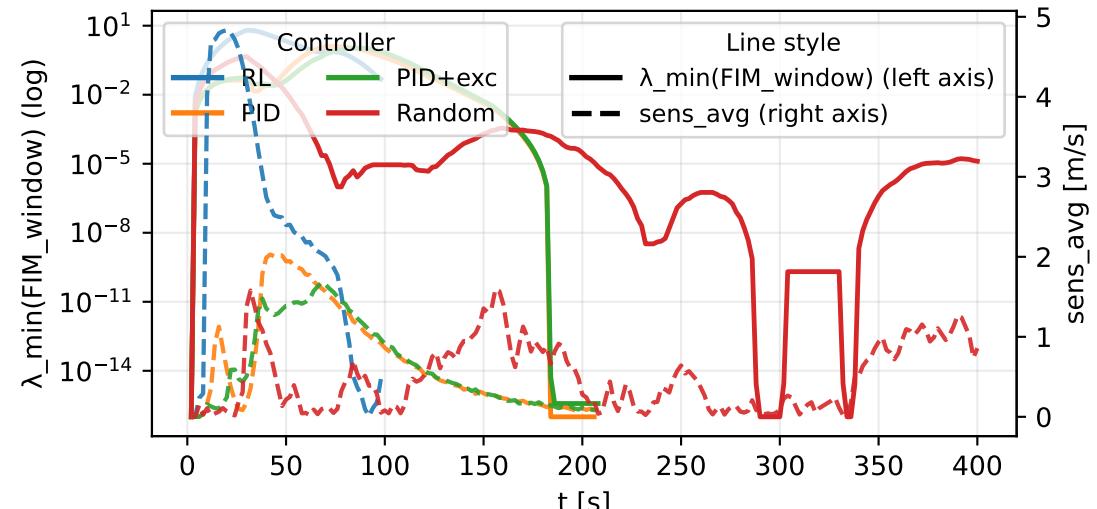
TRUE formation error



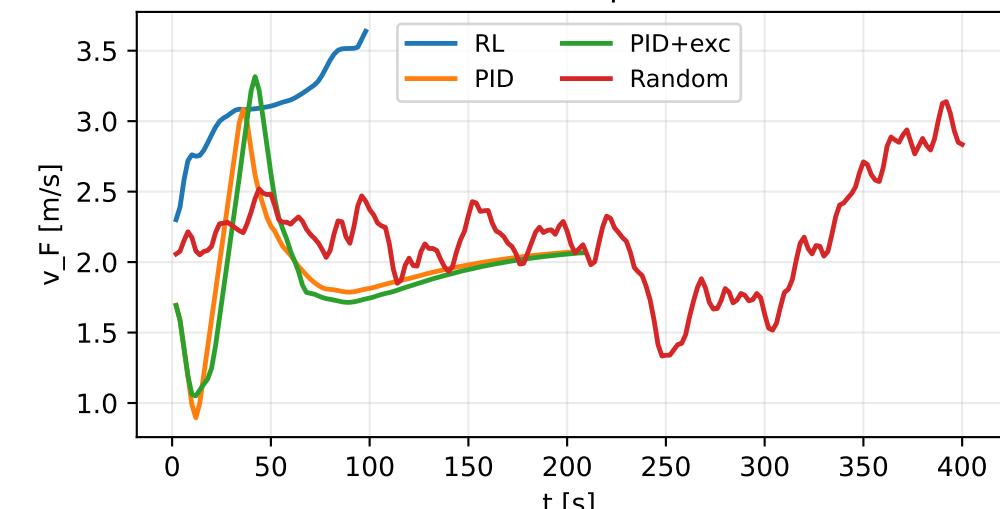
Estimator uncertainty (std_max)



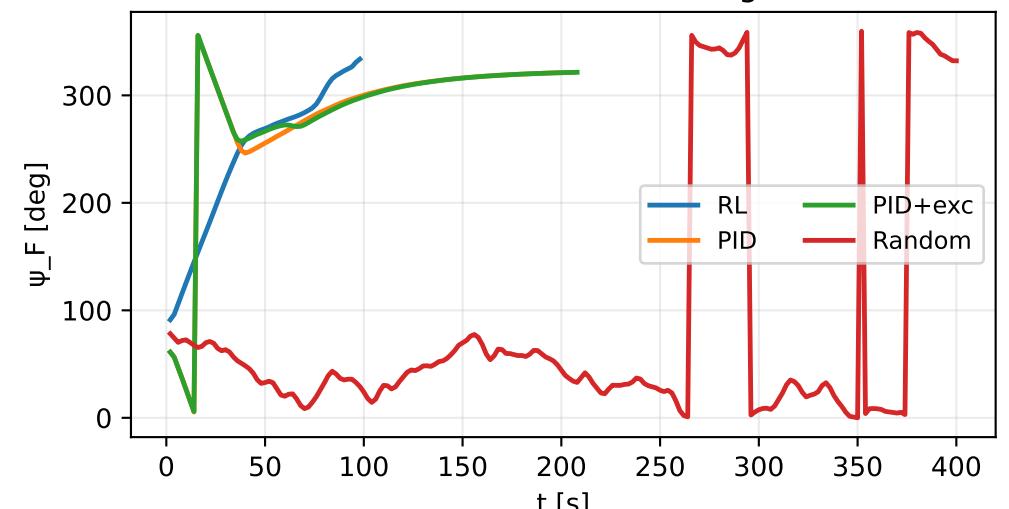
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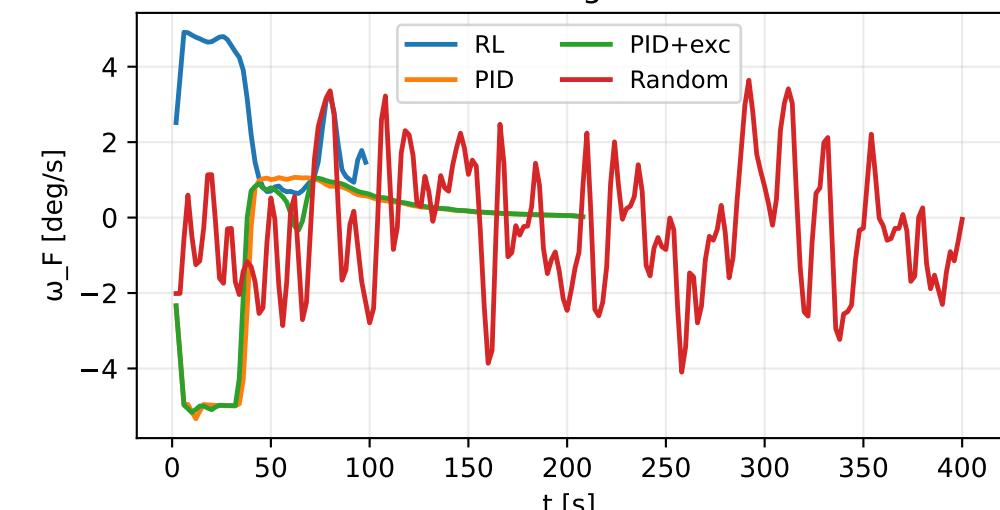
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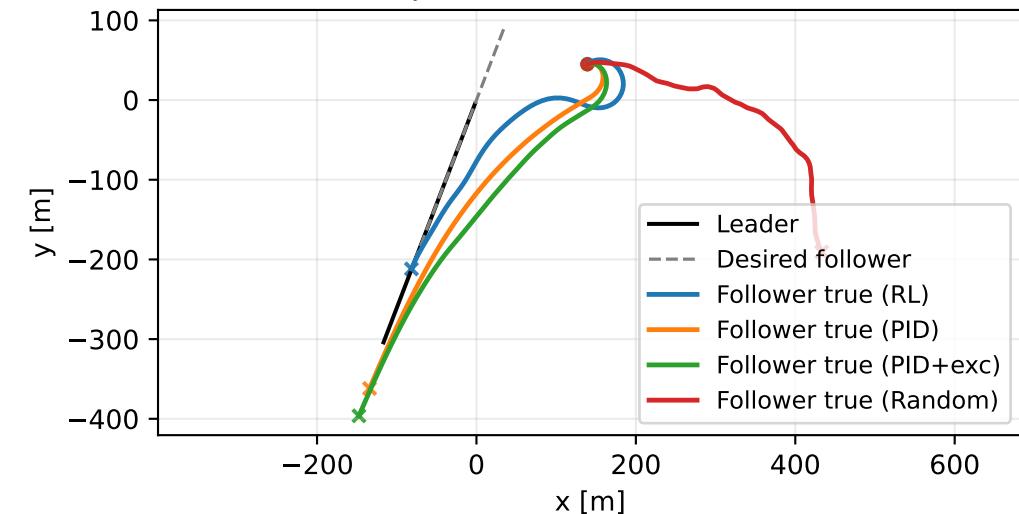
Follower course/heading



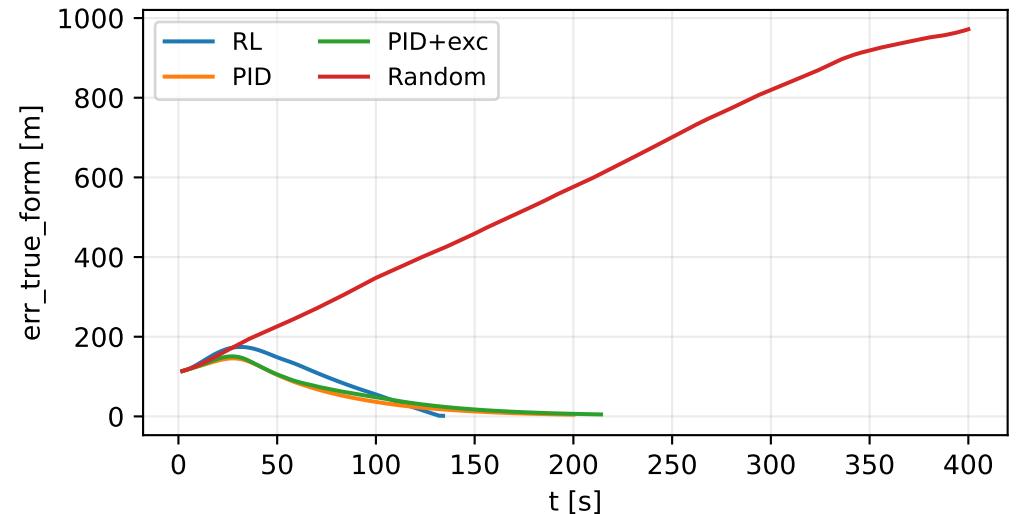
Follower angular rate



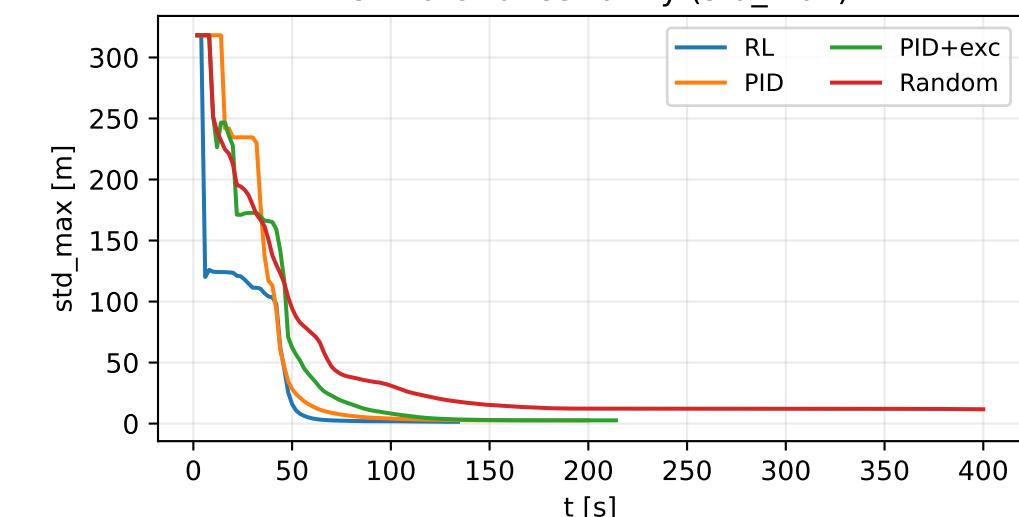
Trajectories (matched seed)



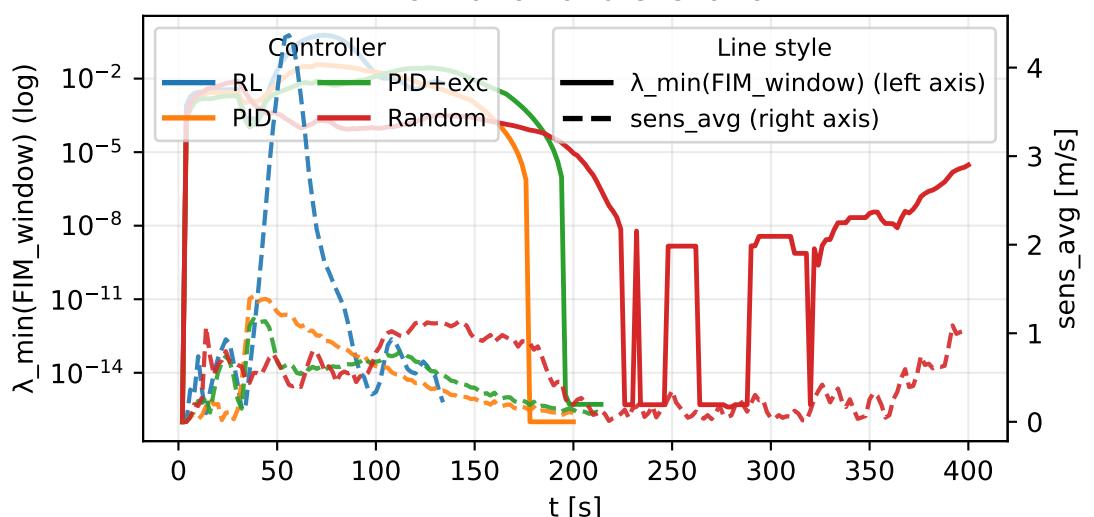
TRUE formation error



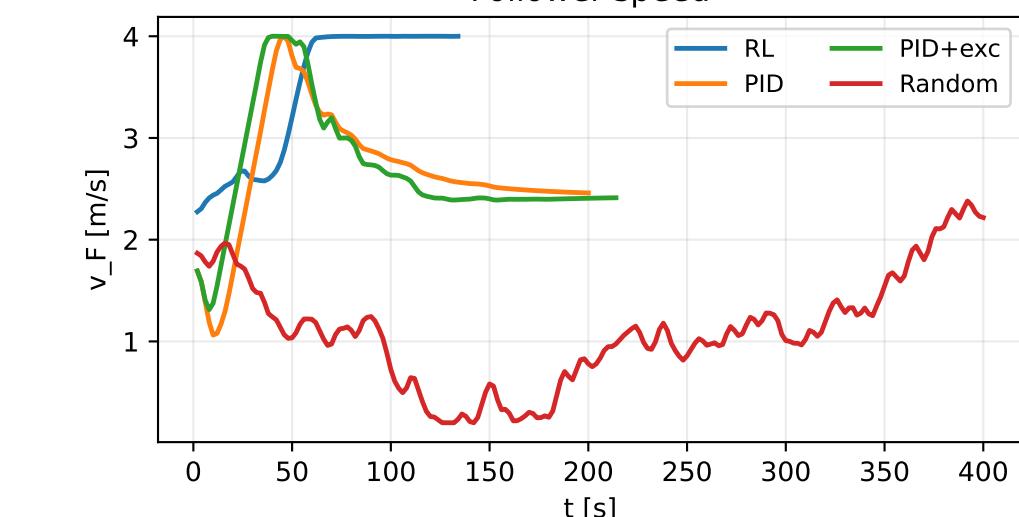
Estimator uncertainty (std_max)



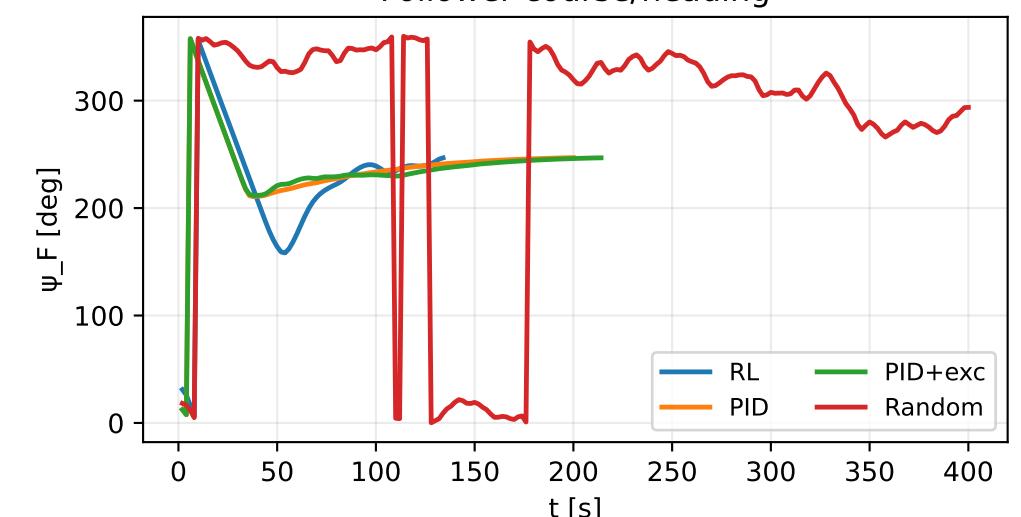
Information and excitation



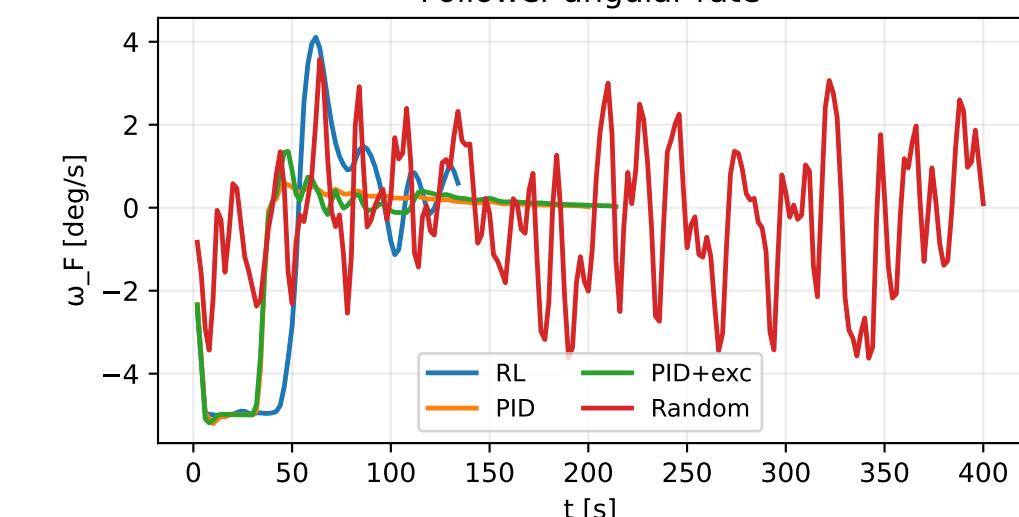
Follower speed



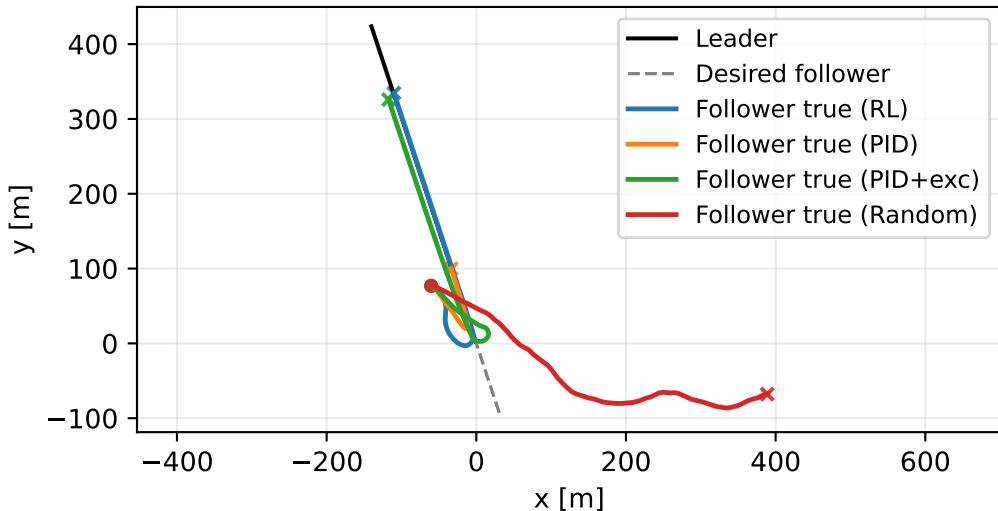
Follower course/heading



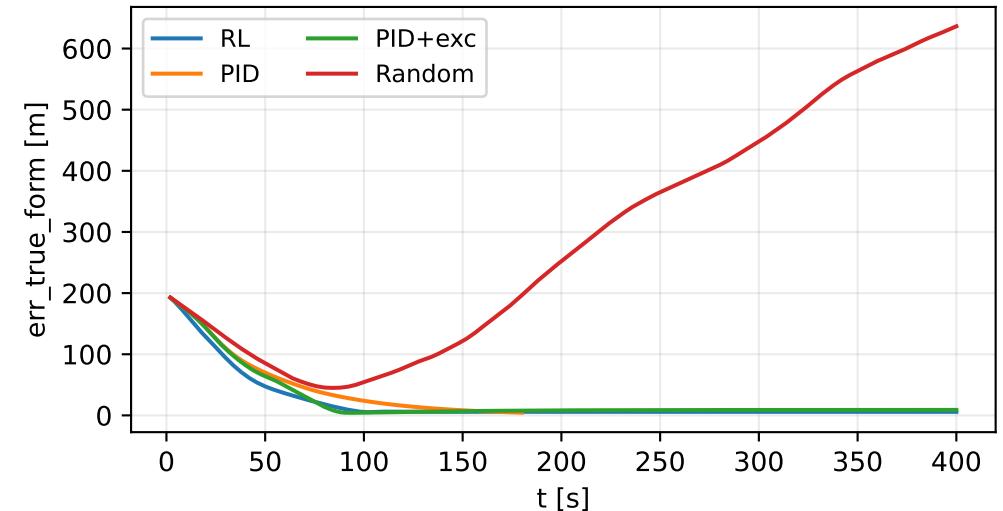
Follower angular rate



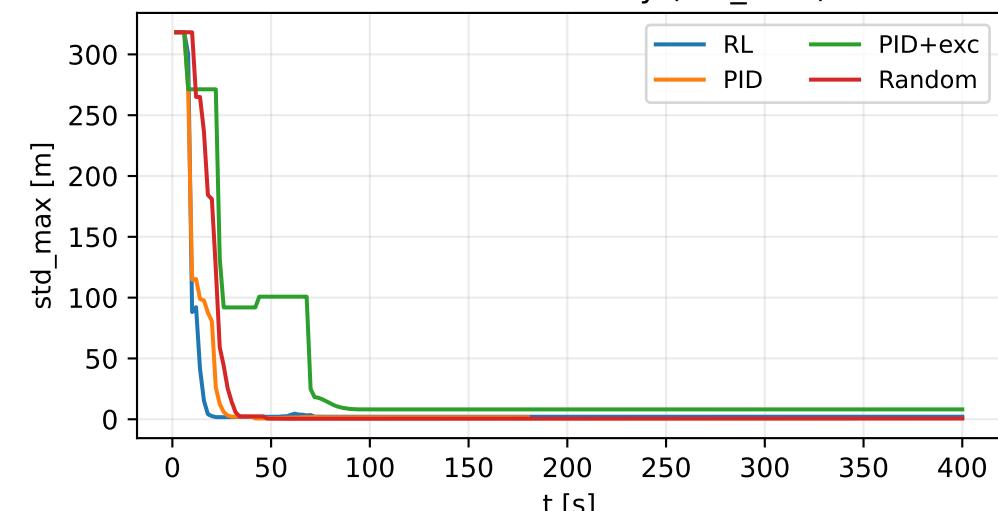
Trajectories (matched seed)



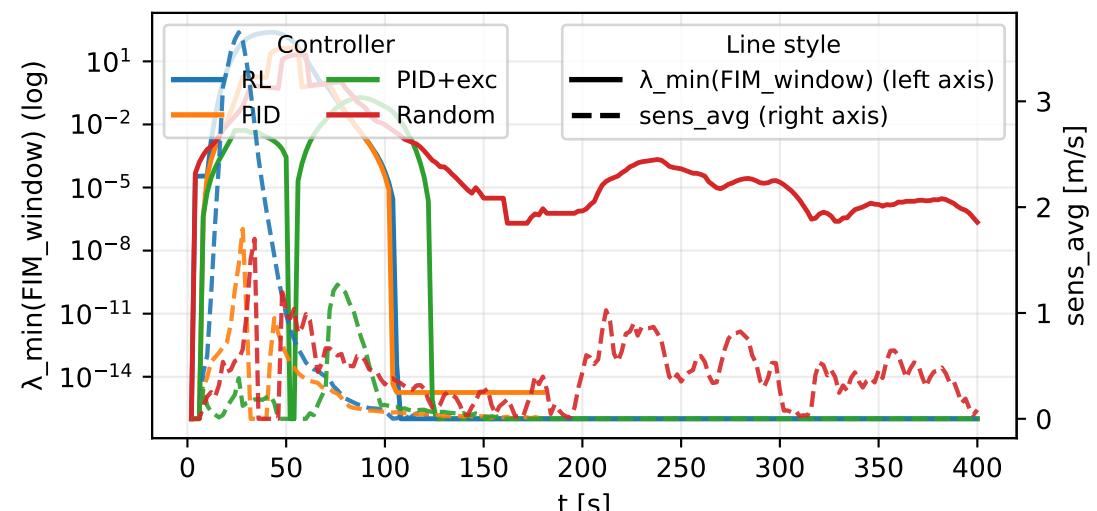
TRUE formation error



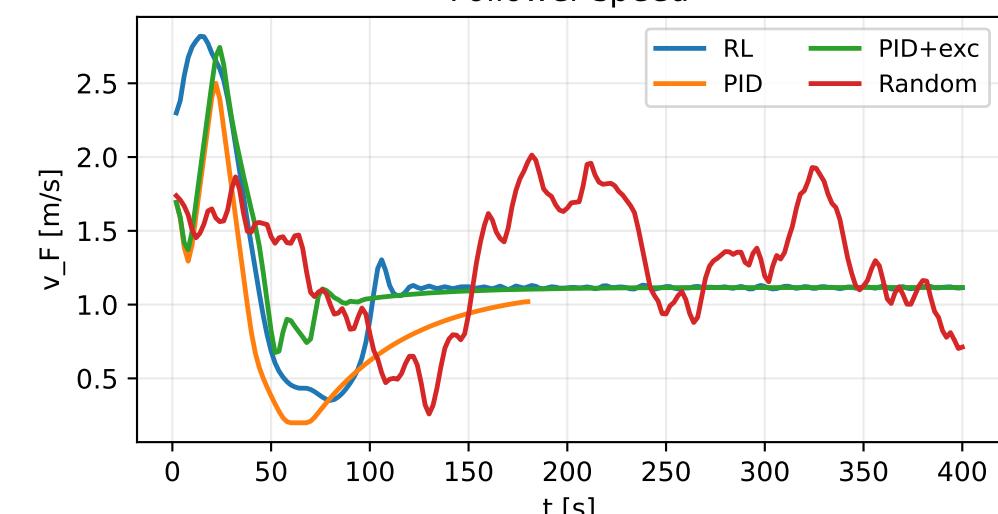
Estimator uncertainty (std_max)



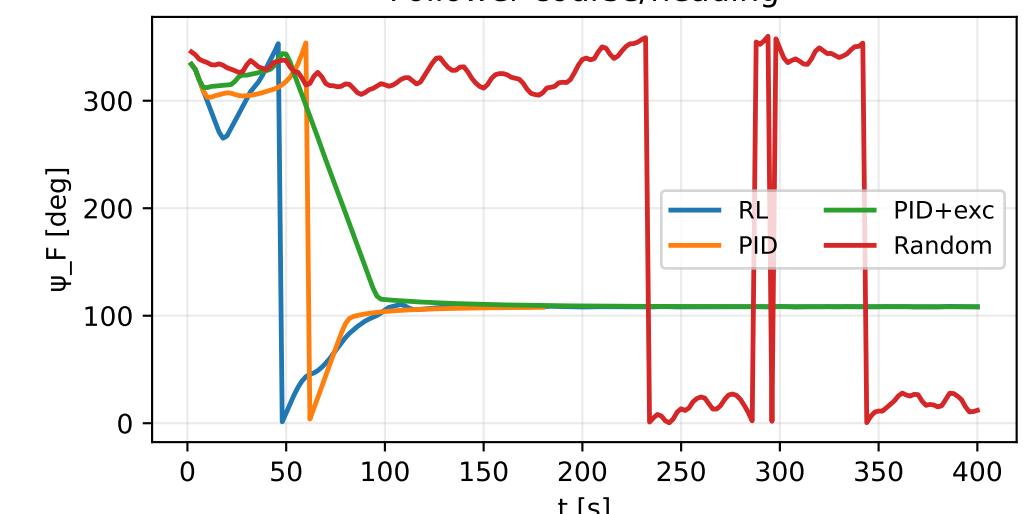
Information and excitation



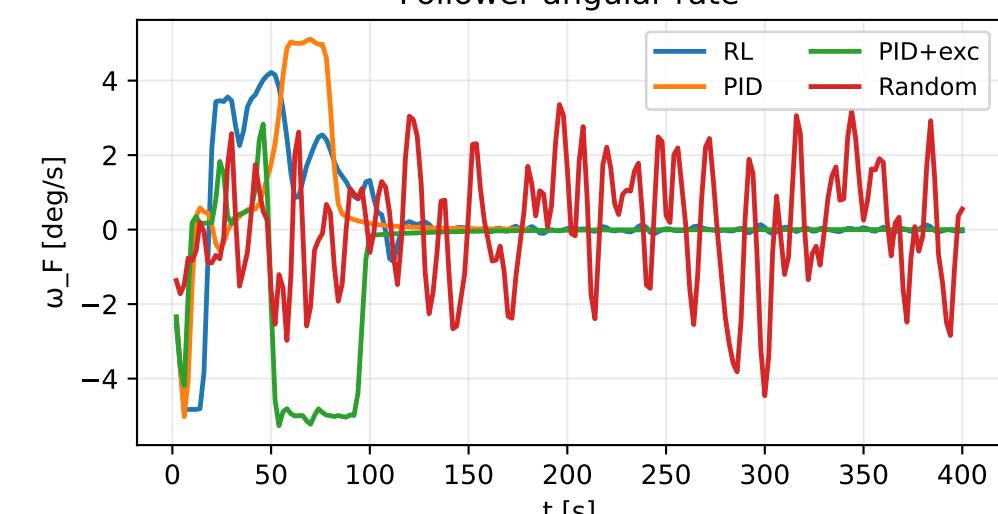
Follower speed



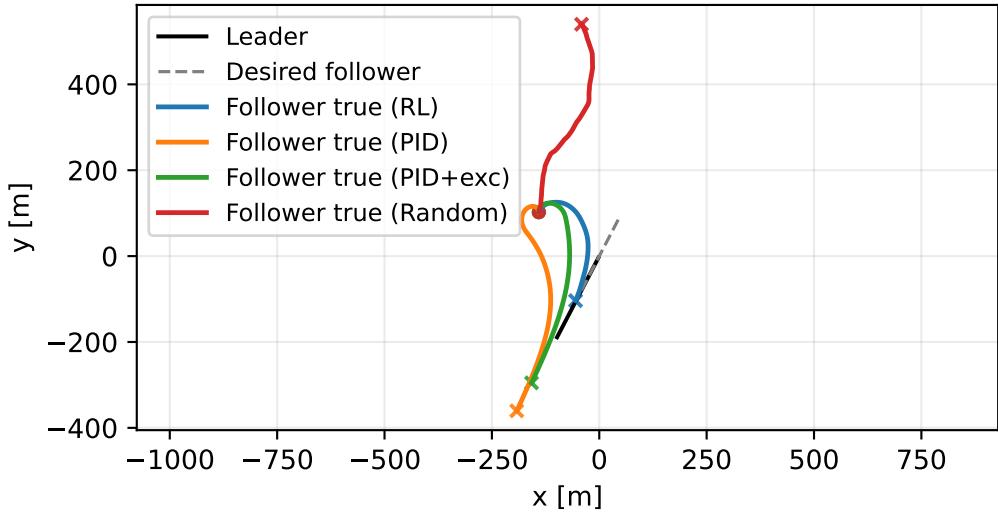
Follower course/heading



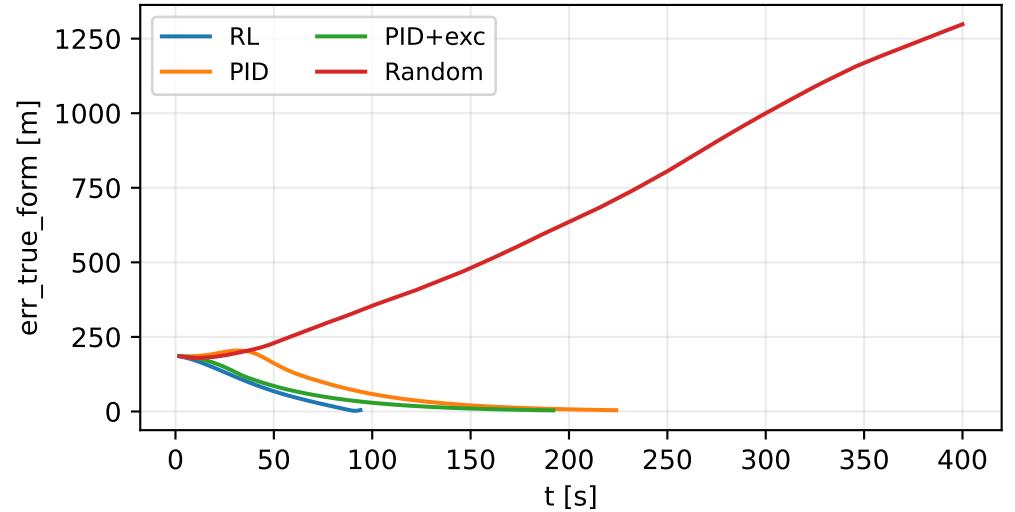
Follower angular rate



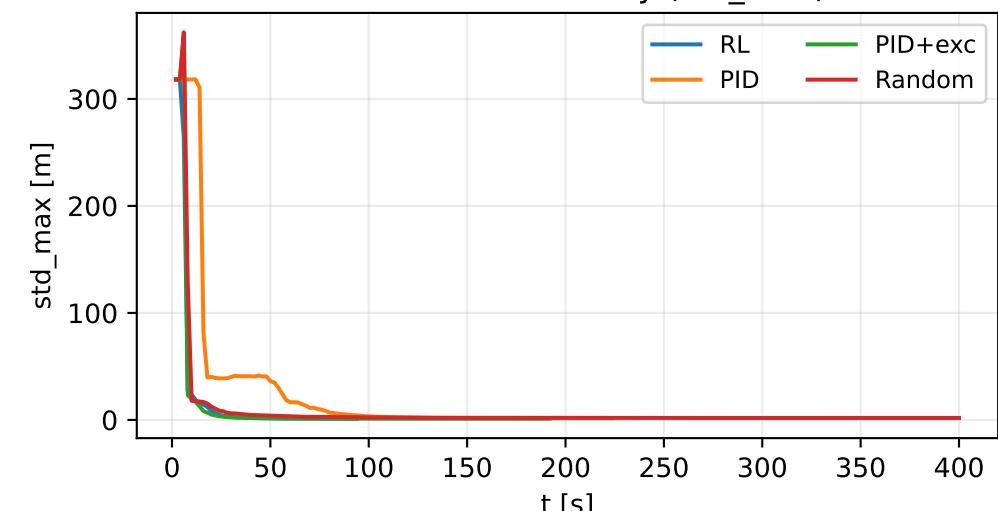
Trajectories (matched seed)



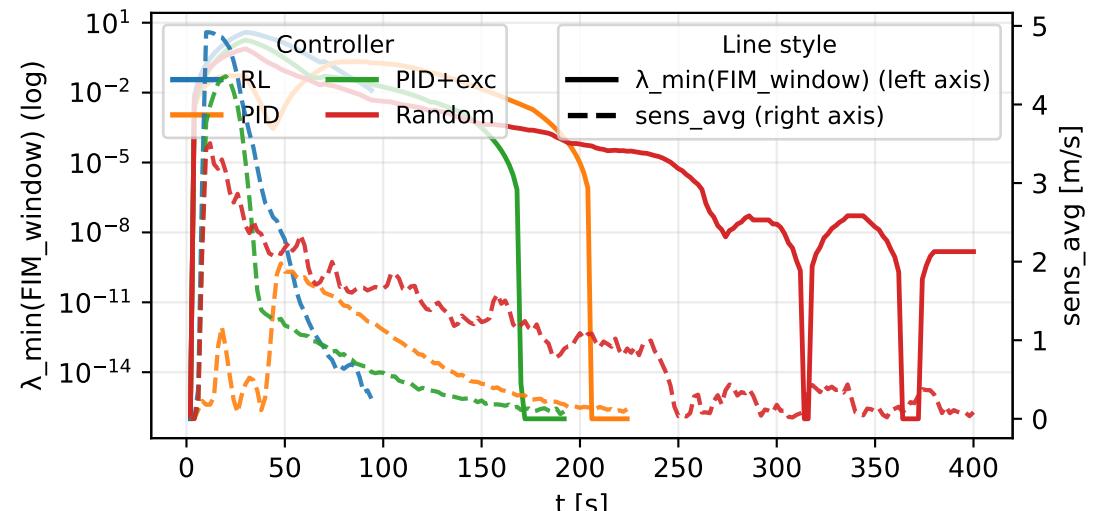
TRUE formation error



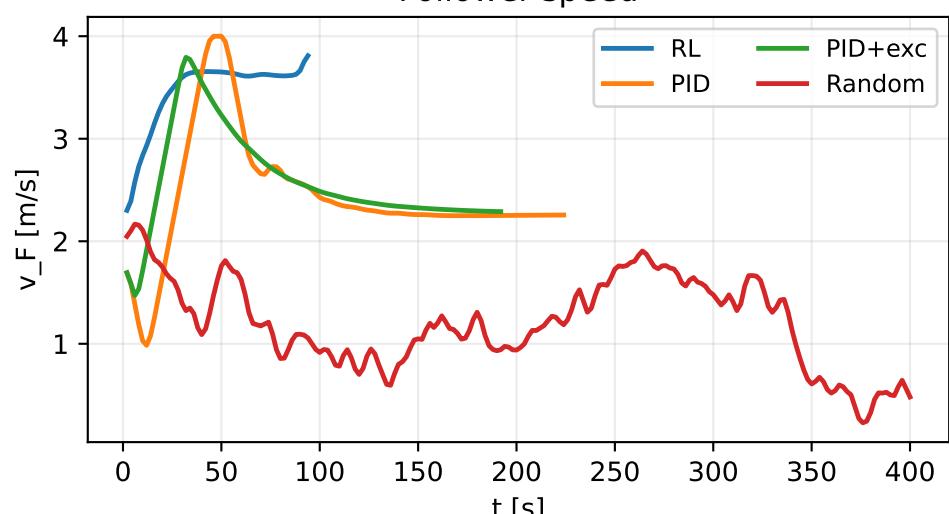
Estimator uncertainty (std_max)



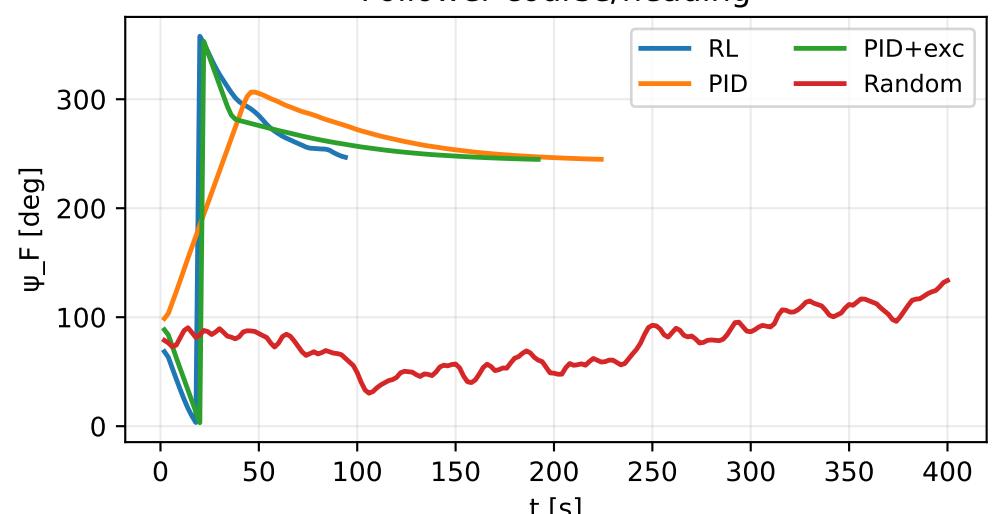
Information and excitation



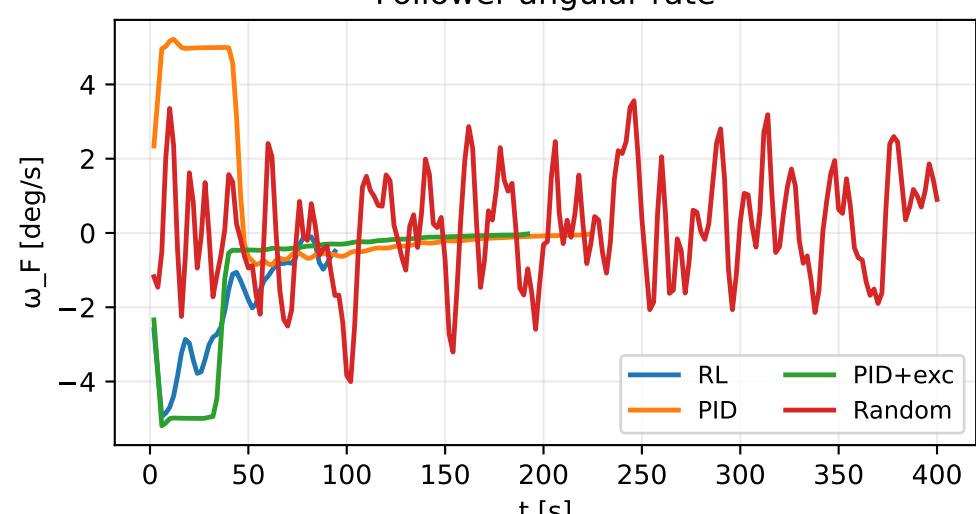
Follower speed



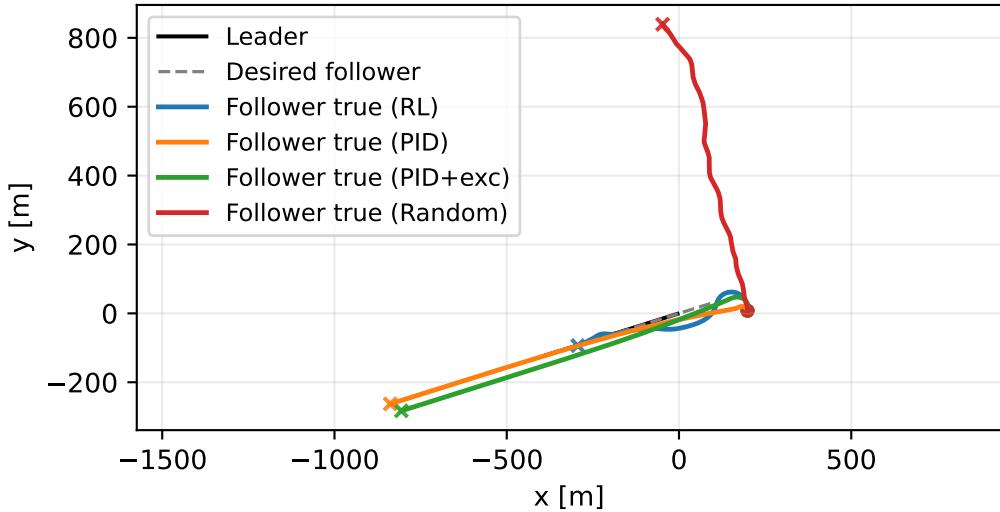
Follower course/heading



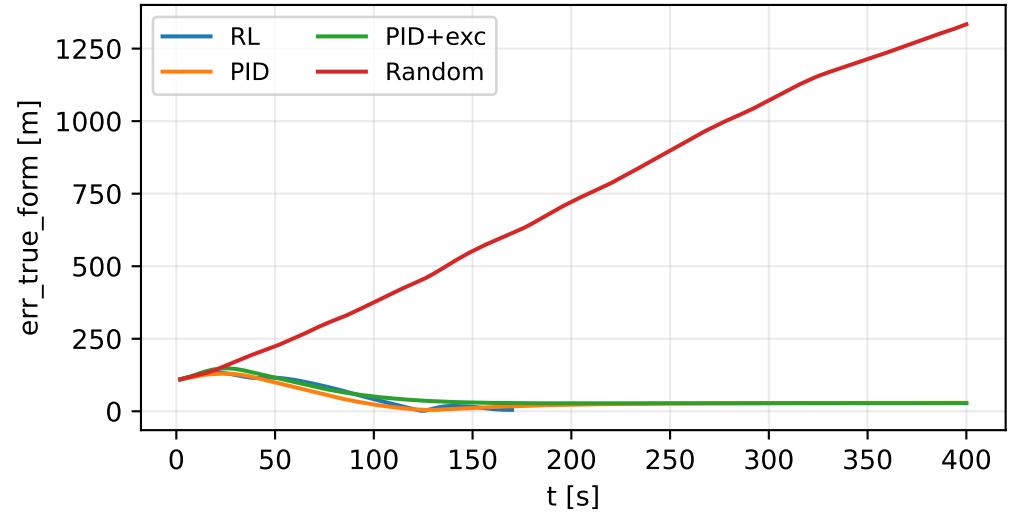
Follower angular rate



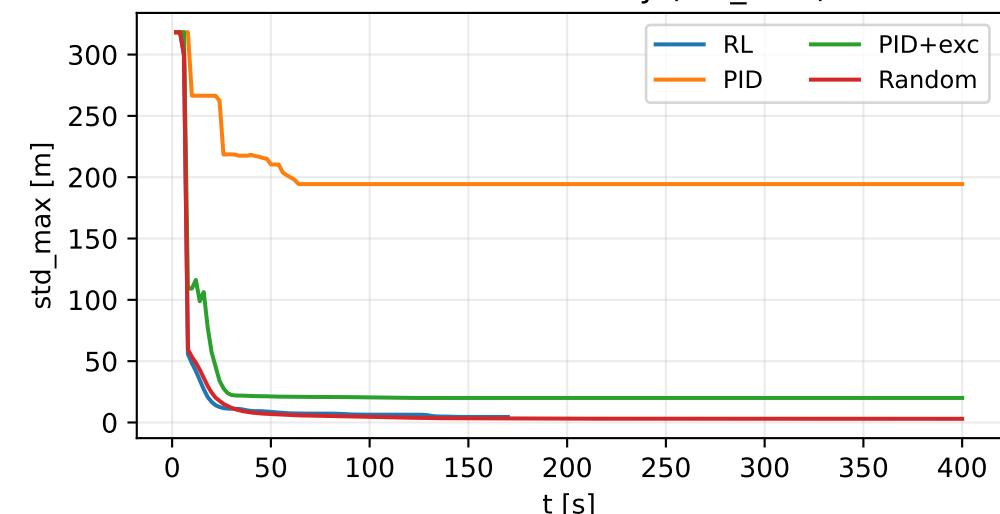
Trajectories (matched seed)



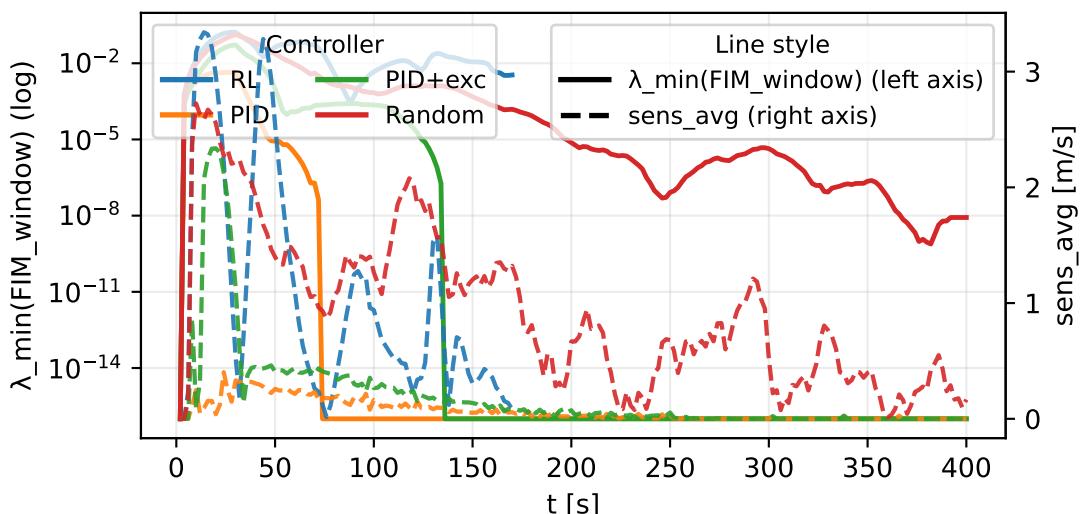
TRUE formation error



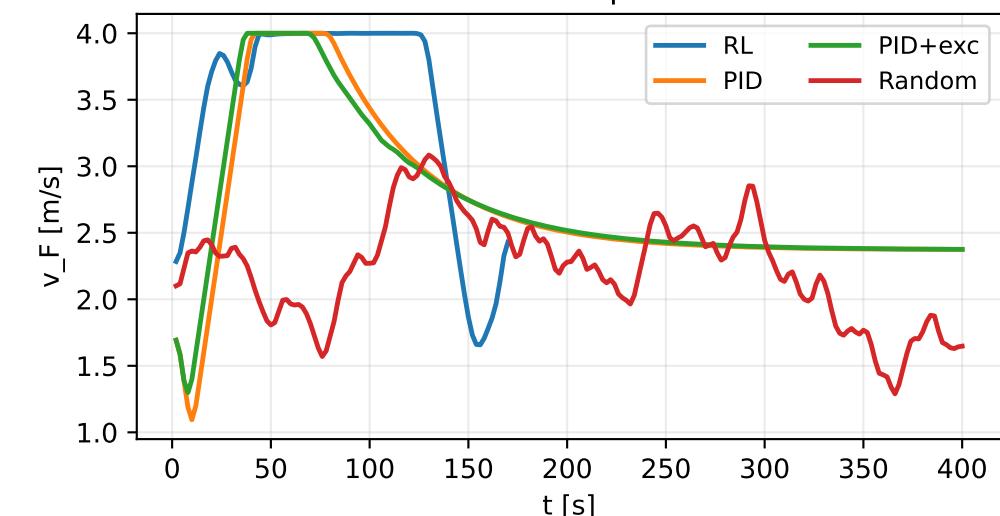
Estimator uncertainty (std_max)



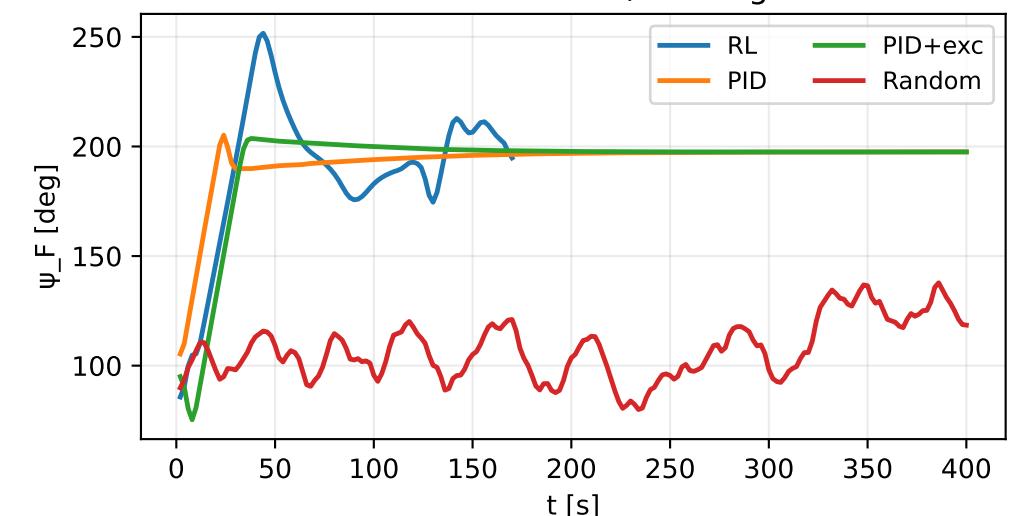
Information and excitation



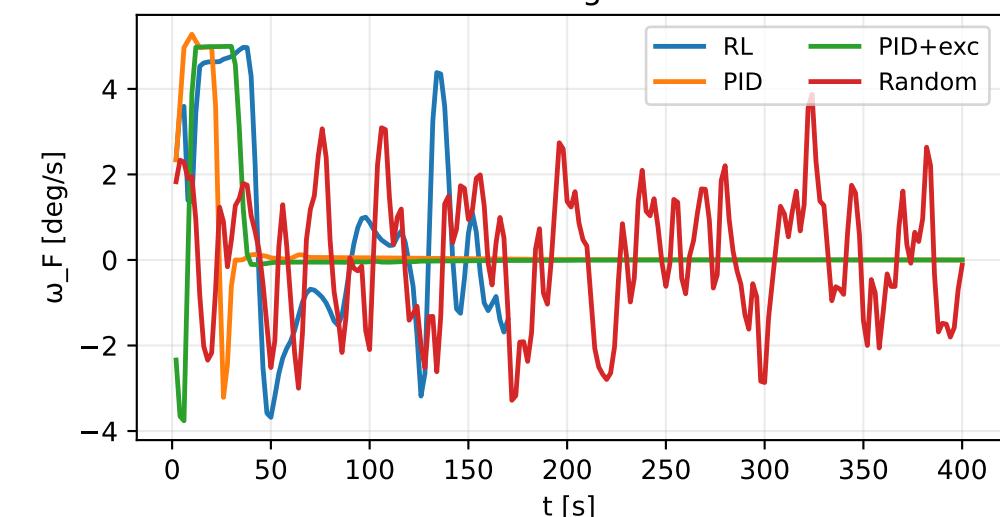
Follower speed



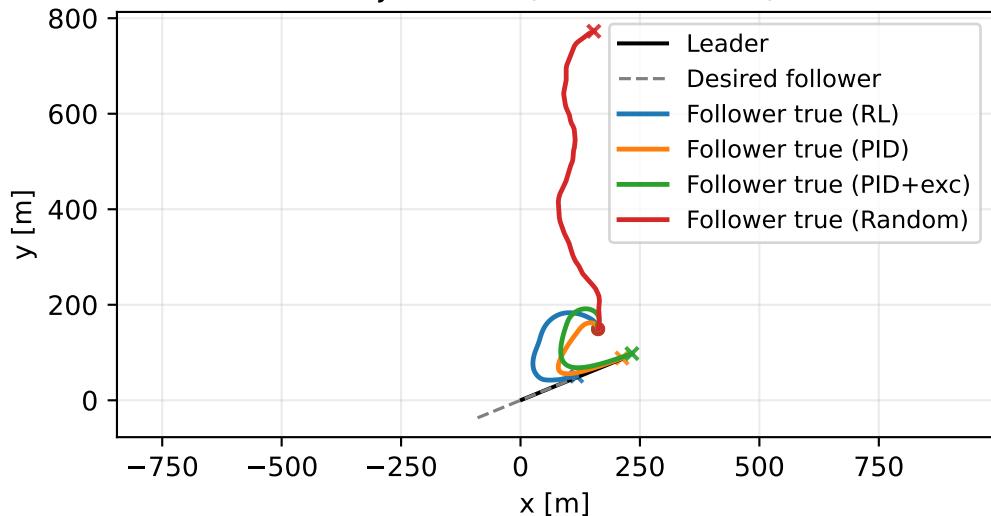
Follower course/heading



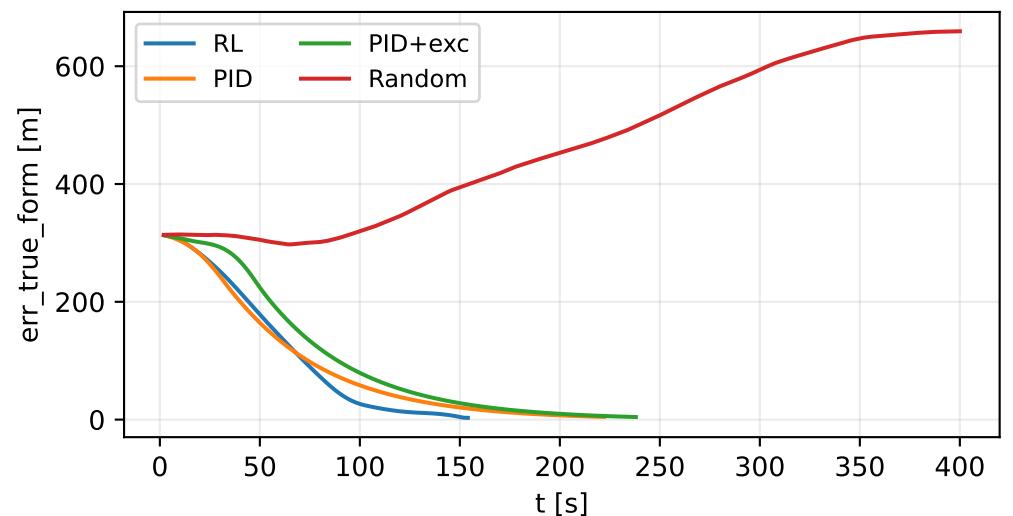
Follower angular rate



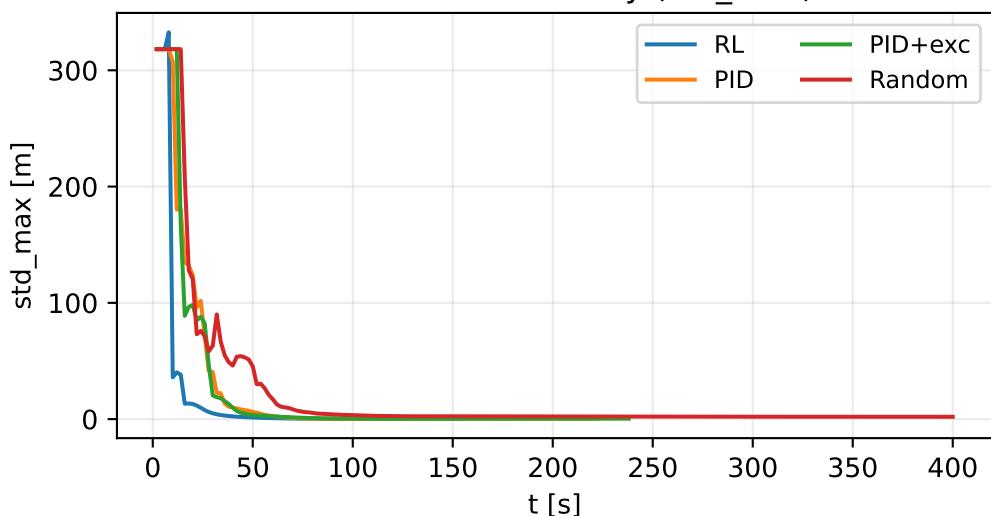
Trajectories (matched seed)



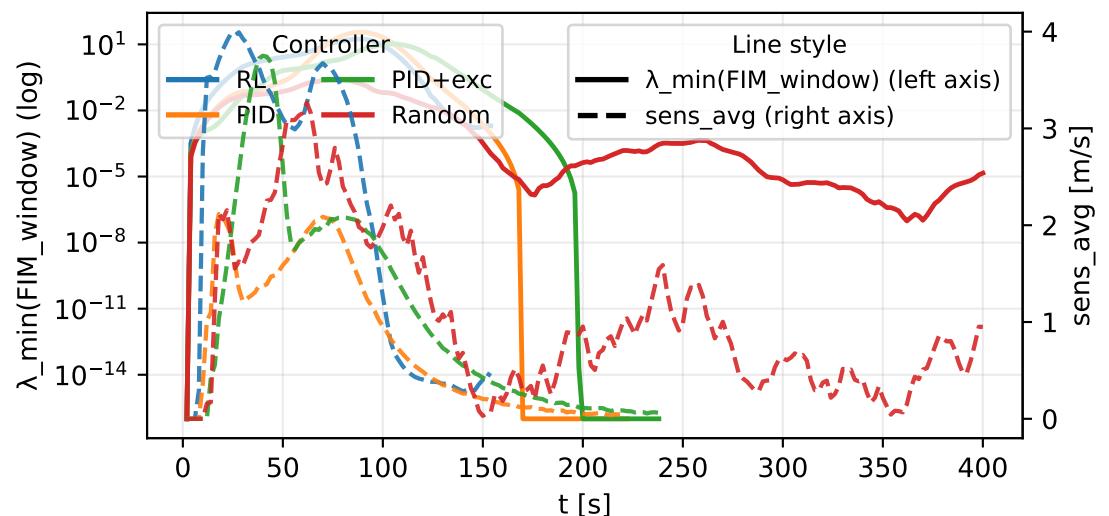
TRUE formation error



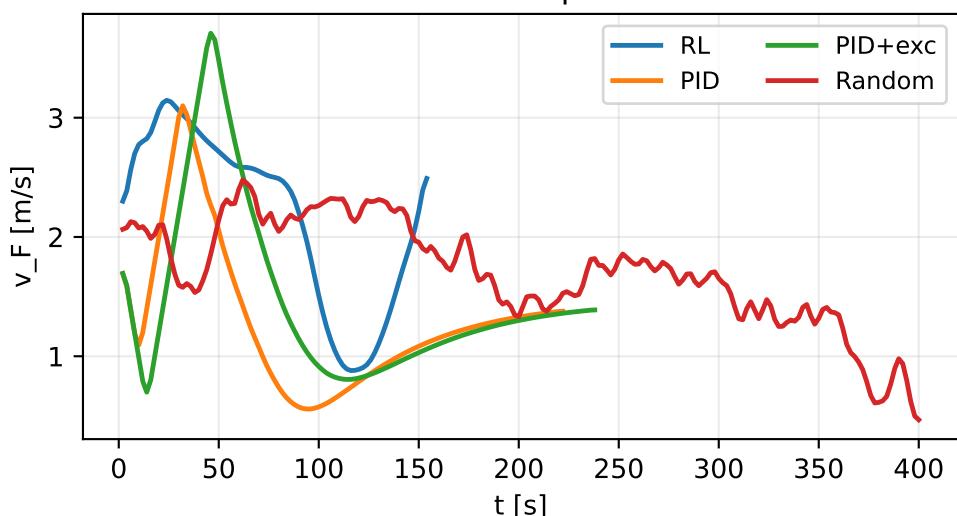
Estimator uncertainty (std_max)



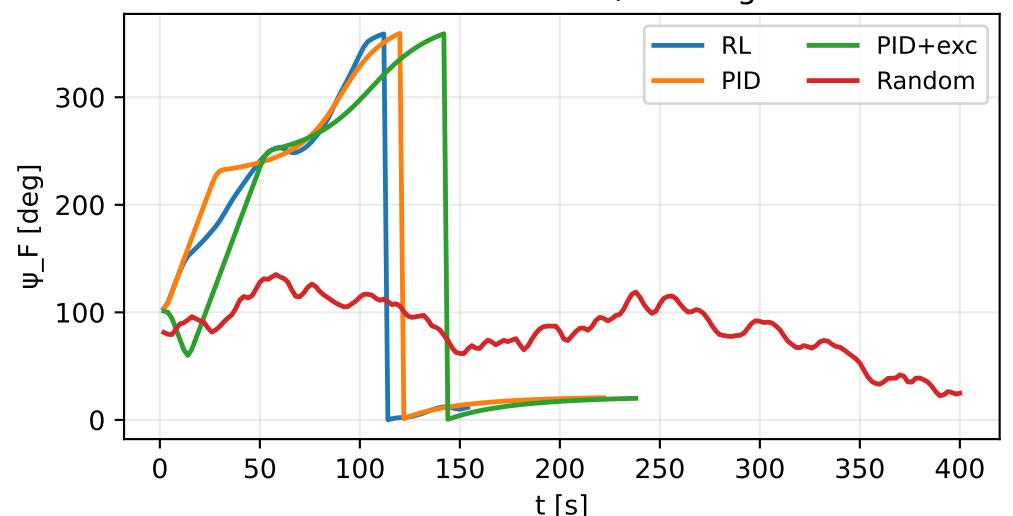
Information and excitation



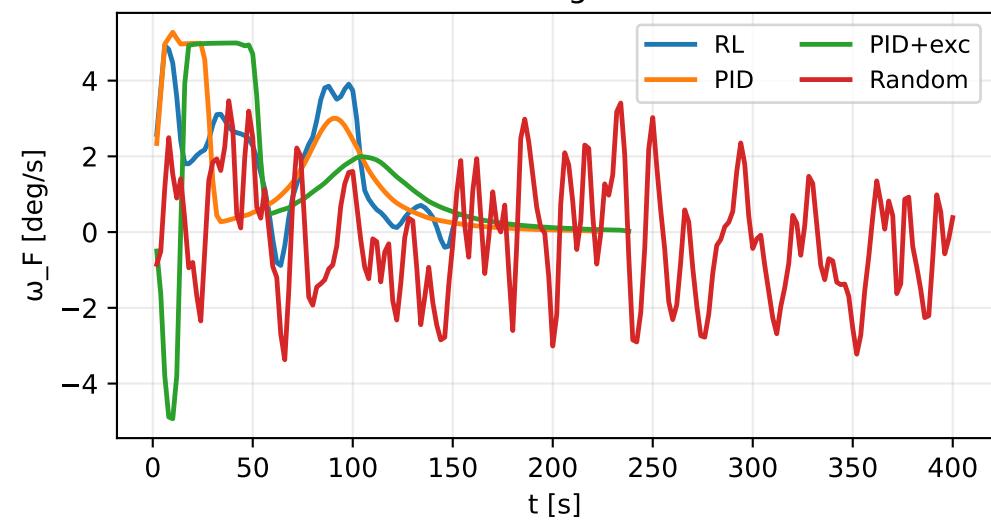
Follower speed



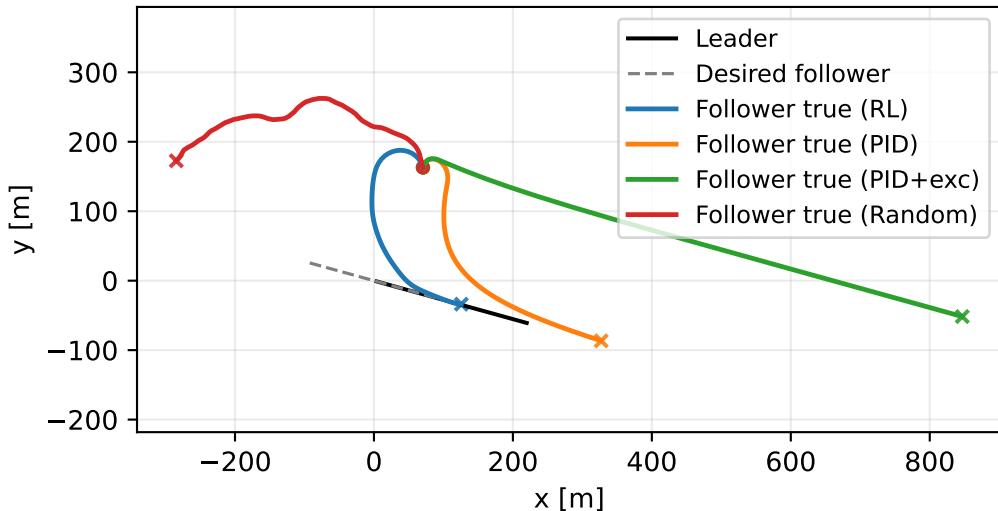
Follower course/heading



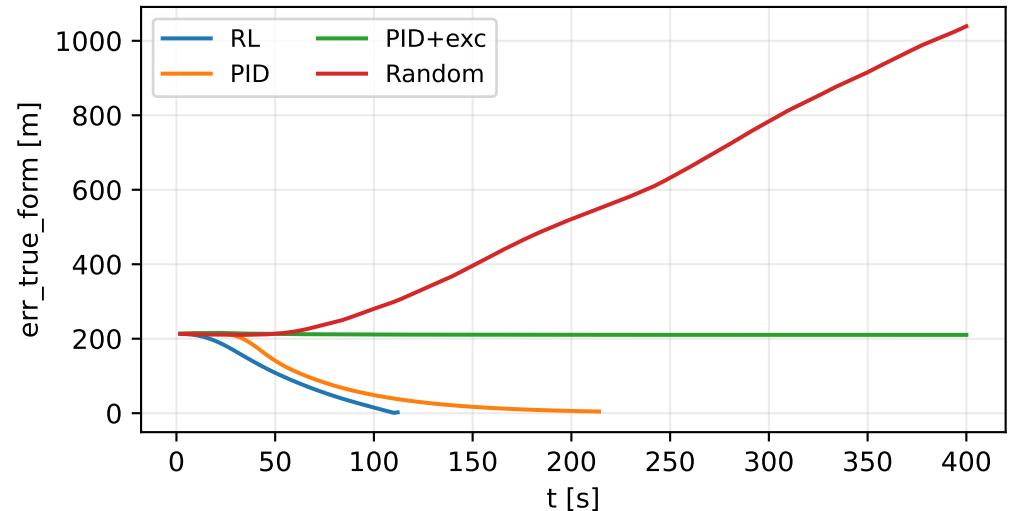
Follower angular rate



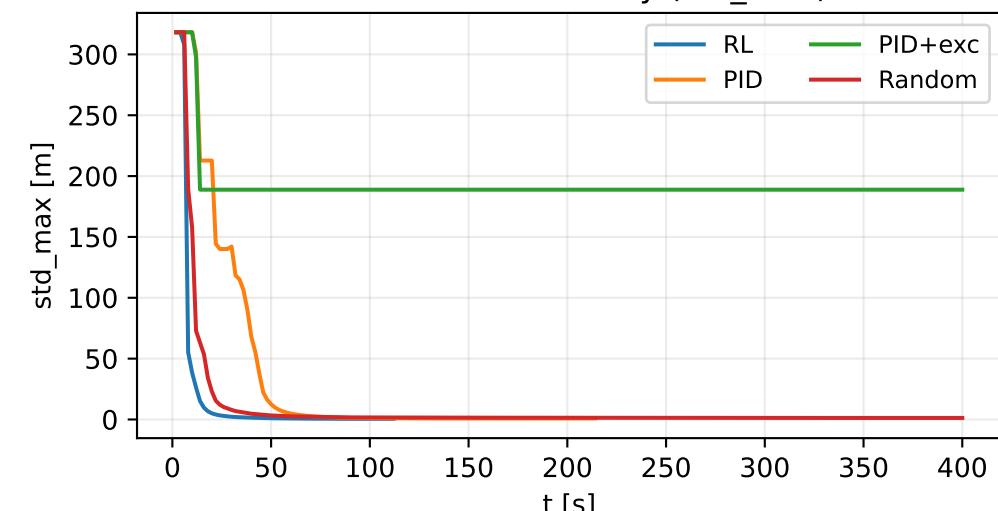
Trajectories (matched seed)



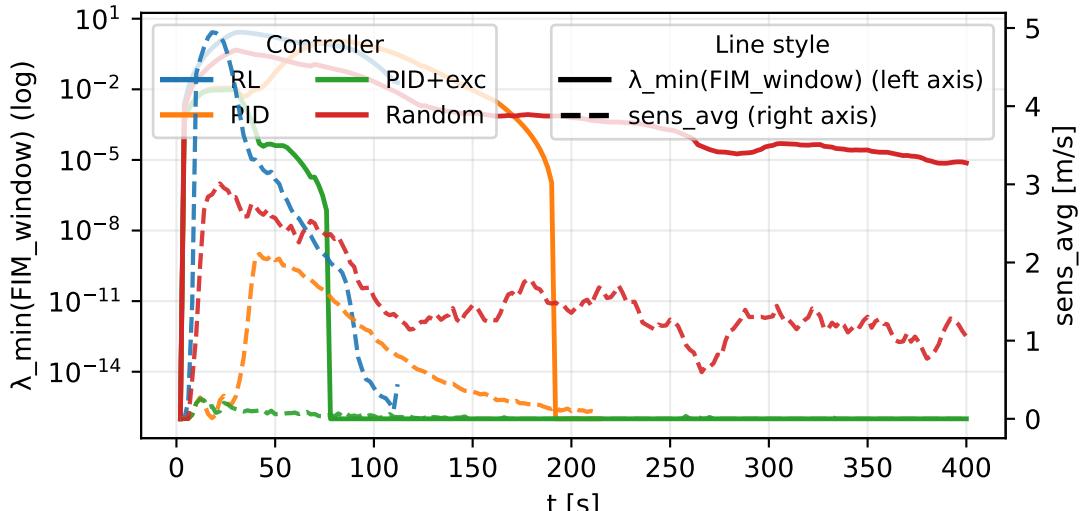
TRUE formation error



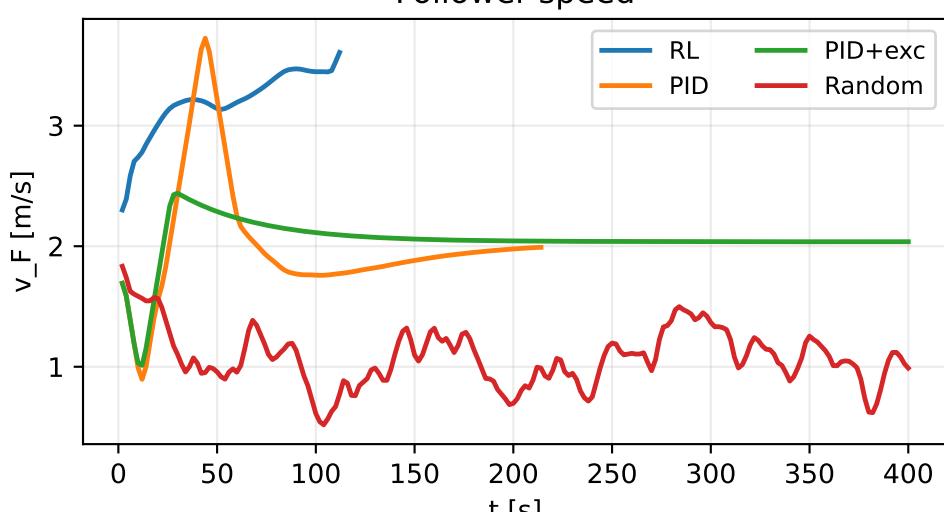
Estimator uncertainty (std_max)



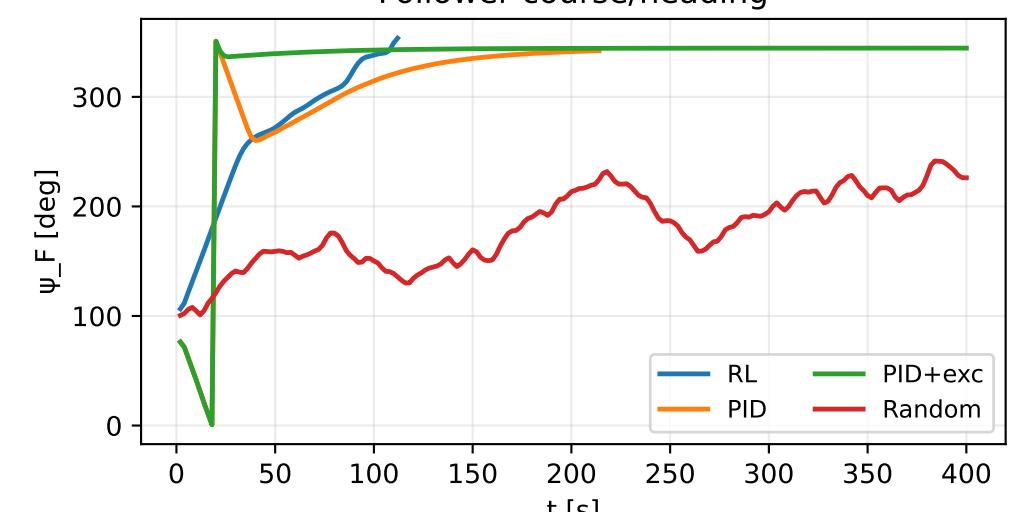
Information and excitation



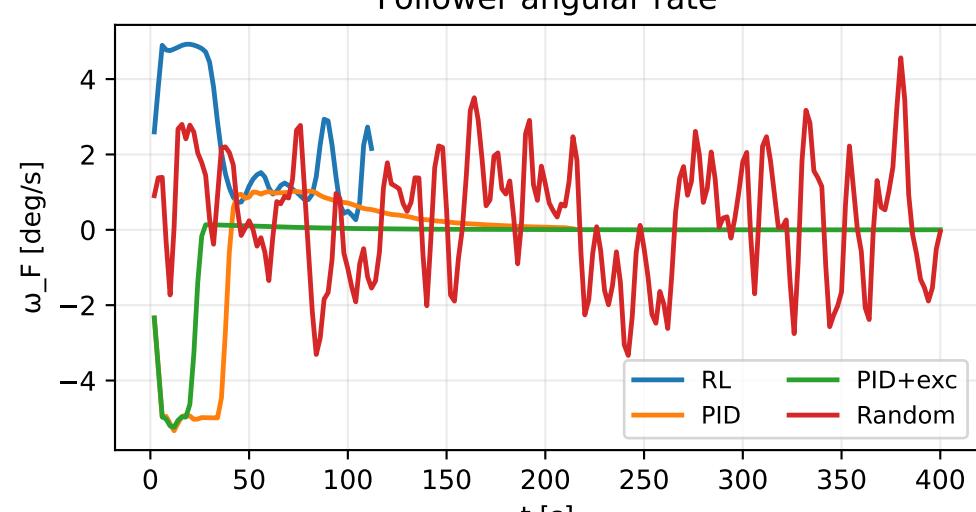
Follower speed



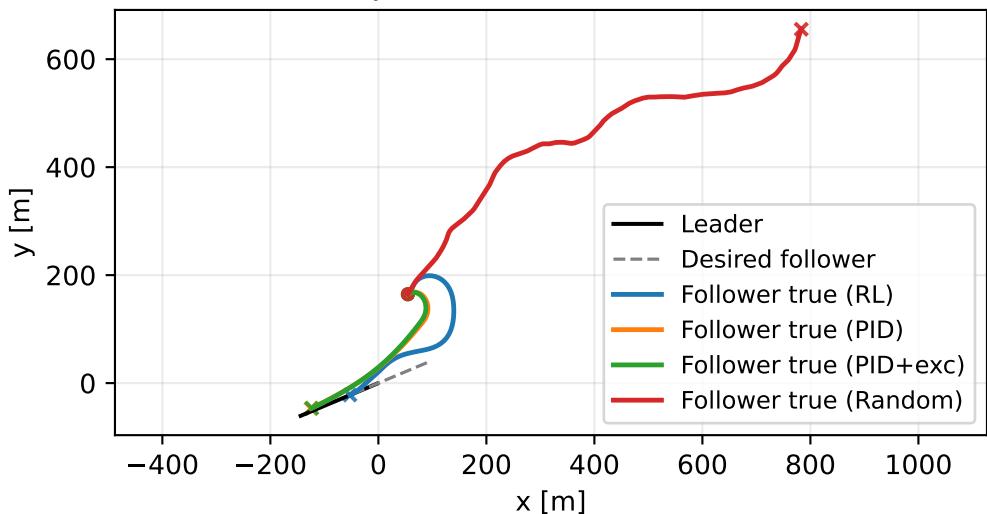
Follower course/heading



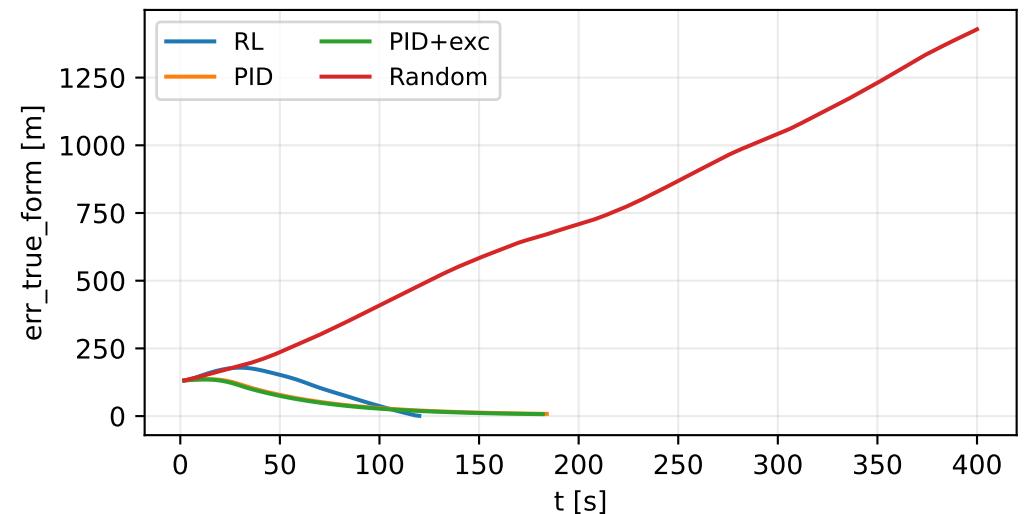
Follower angular rate



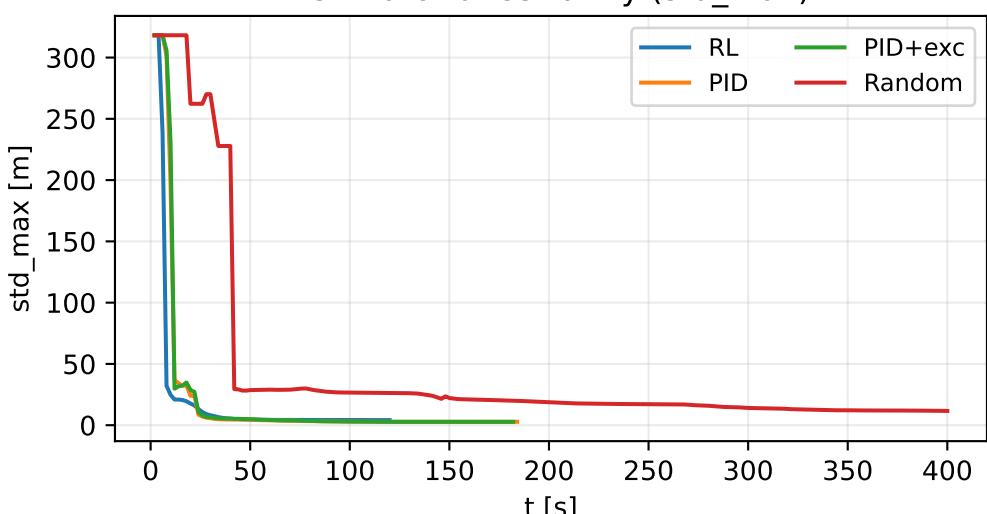
Trajectories (matched seed)



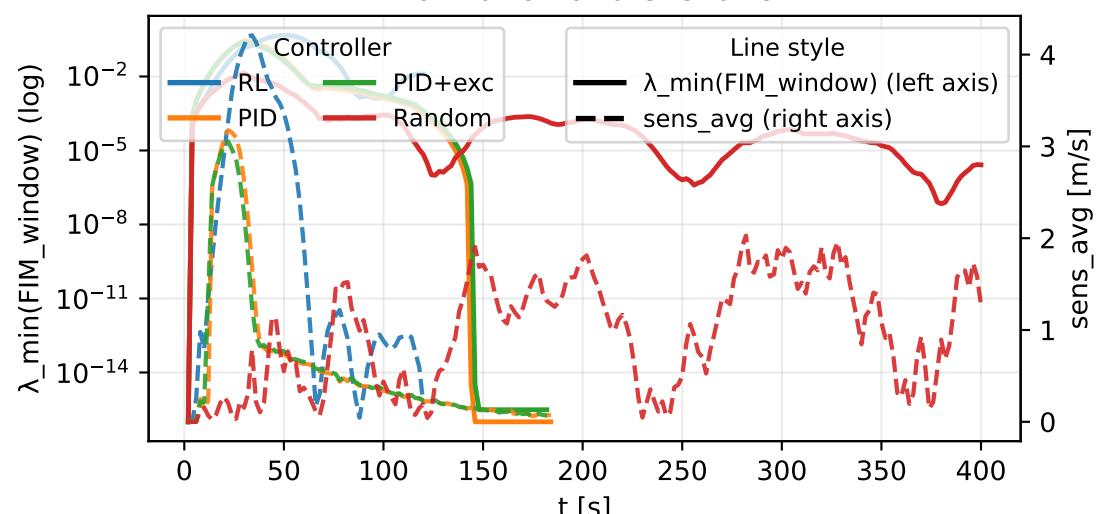
TRUE formation error



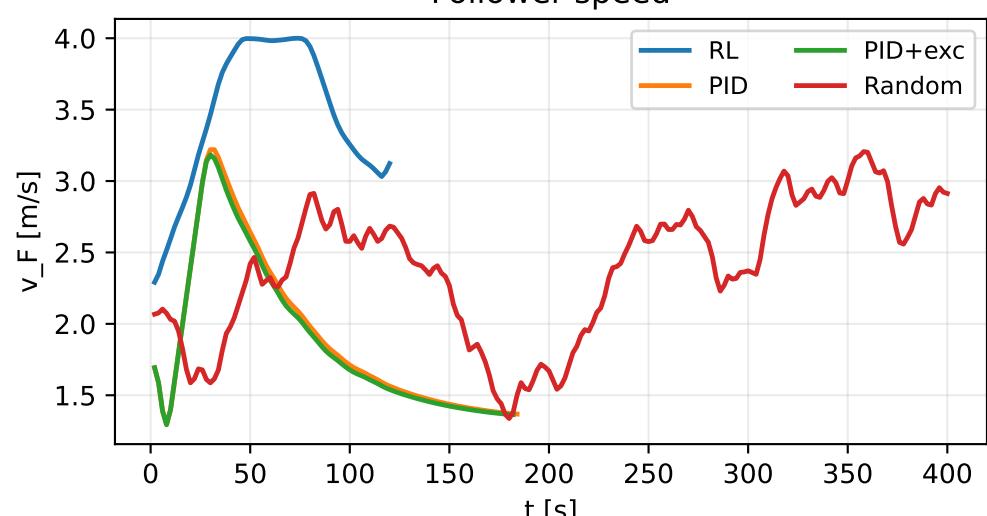
Estimator uncertainty (std_max)



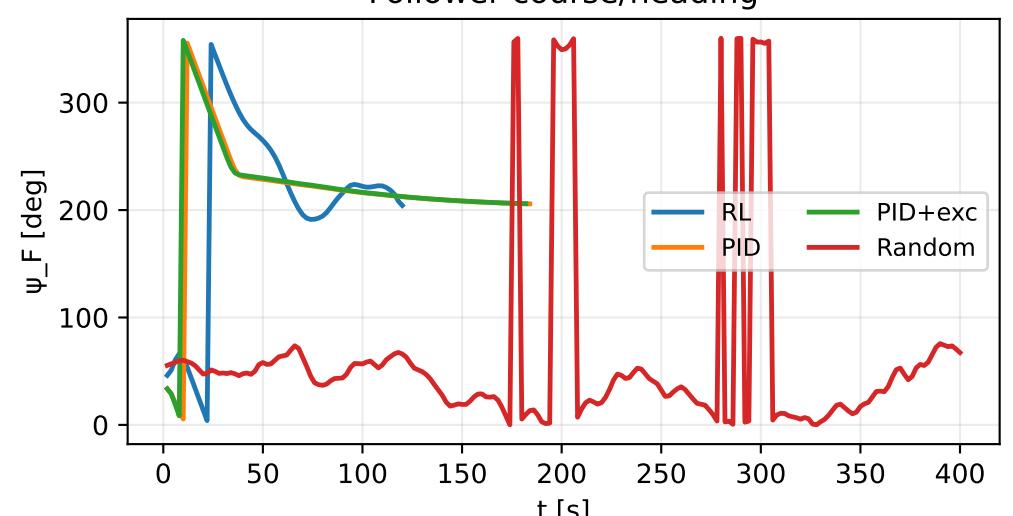
Information and excitation



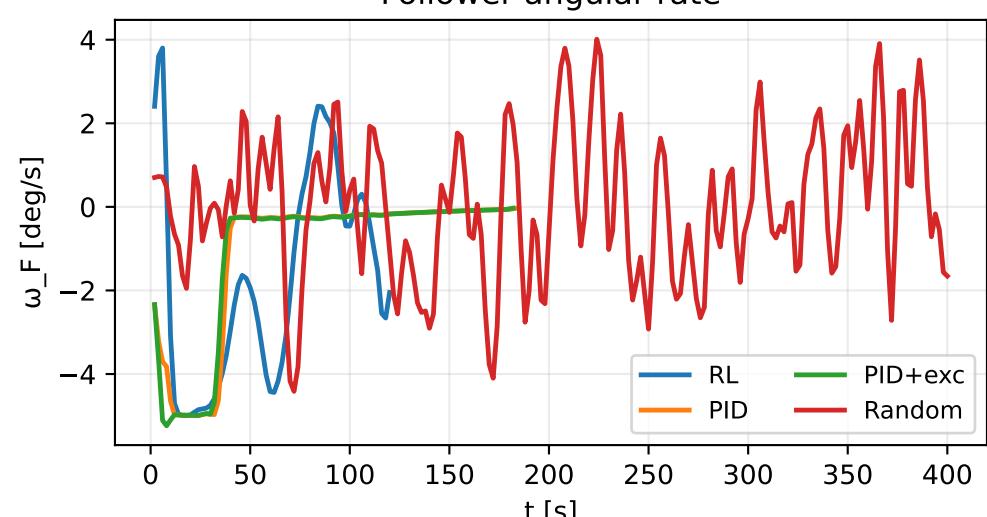
Follower speed



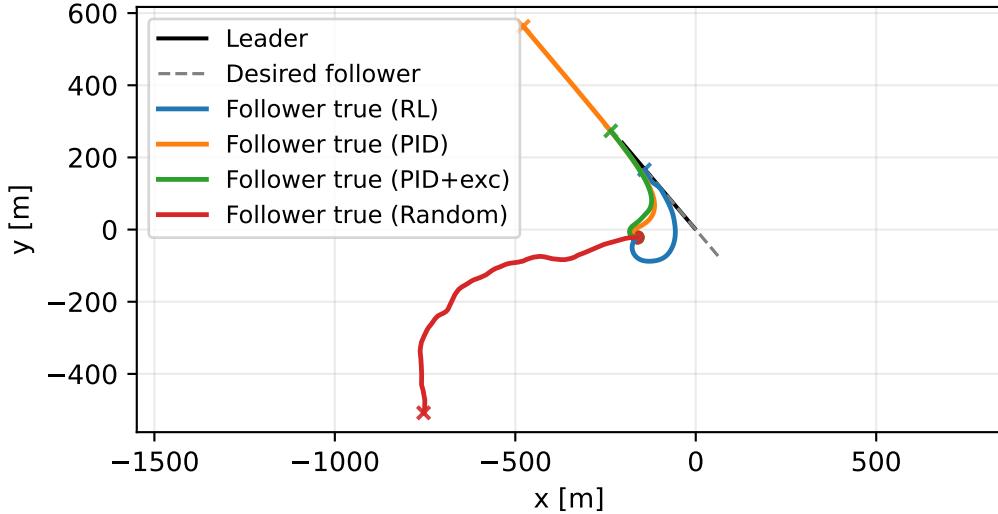
Follower course/heating



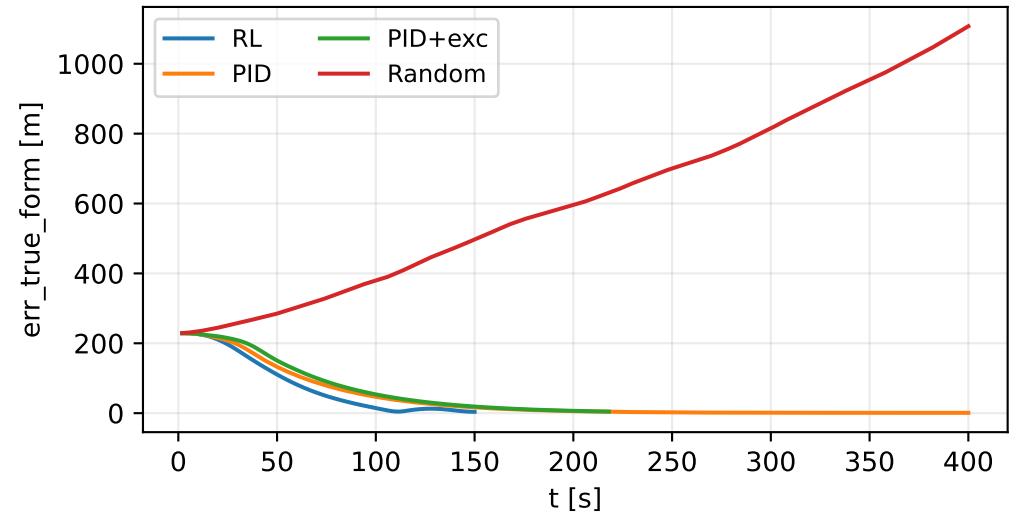
Follower angular rate



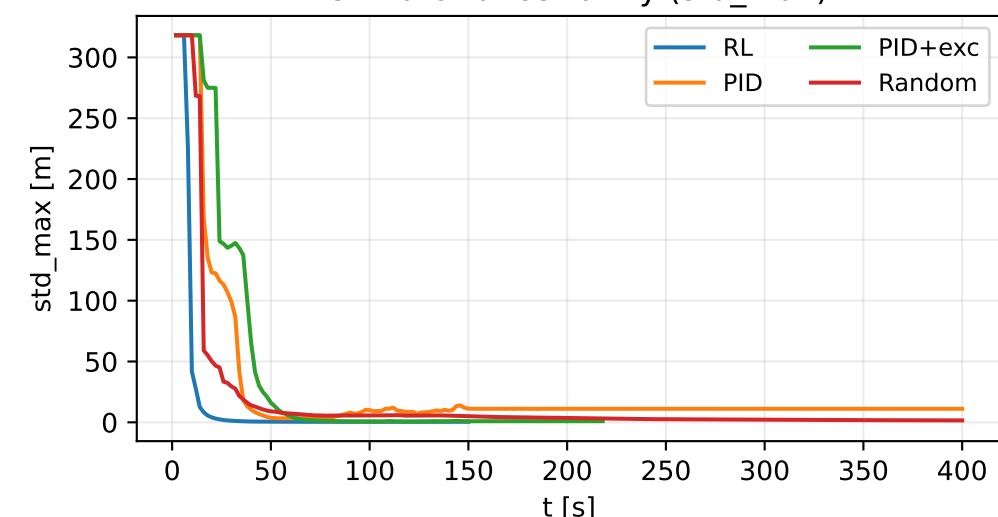
Trajectories (matched seed)



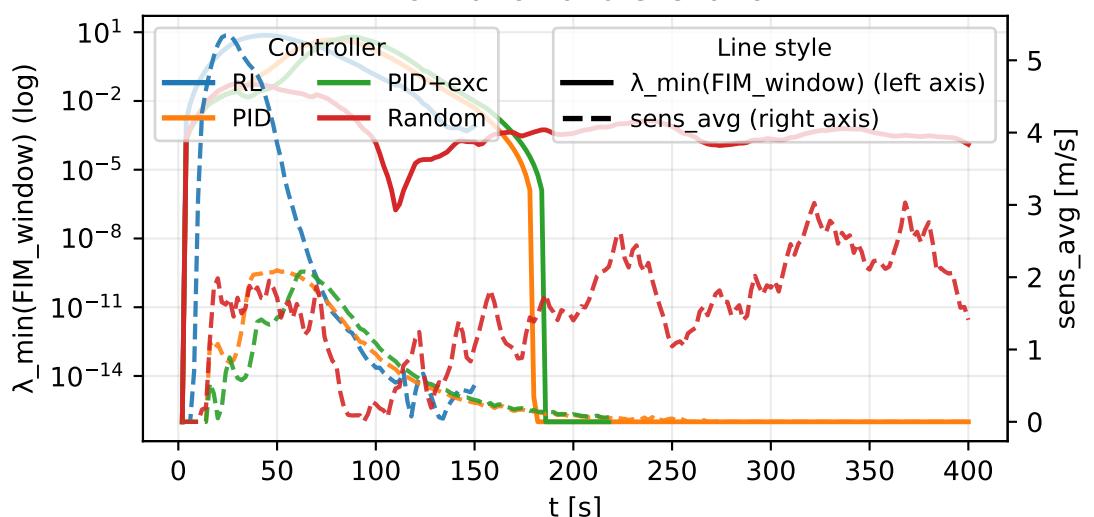
TRUE formation error



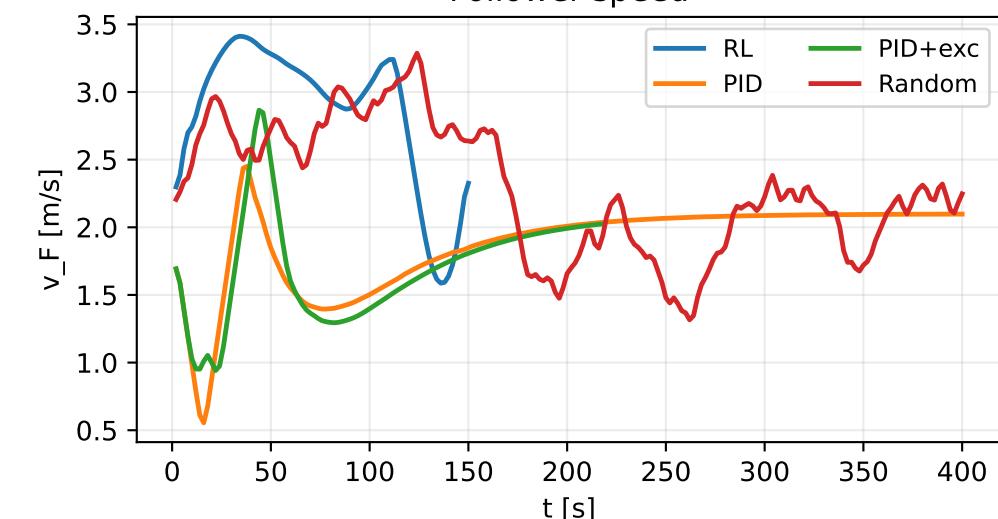
Estimator uncertainty (std_max)



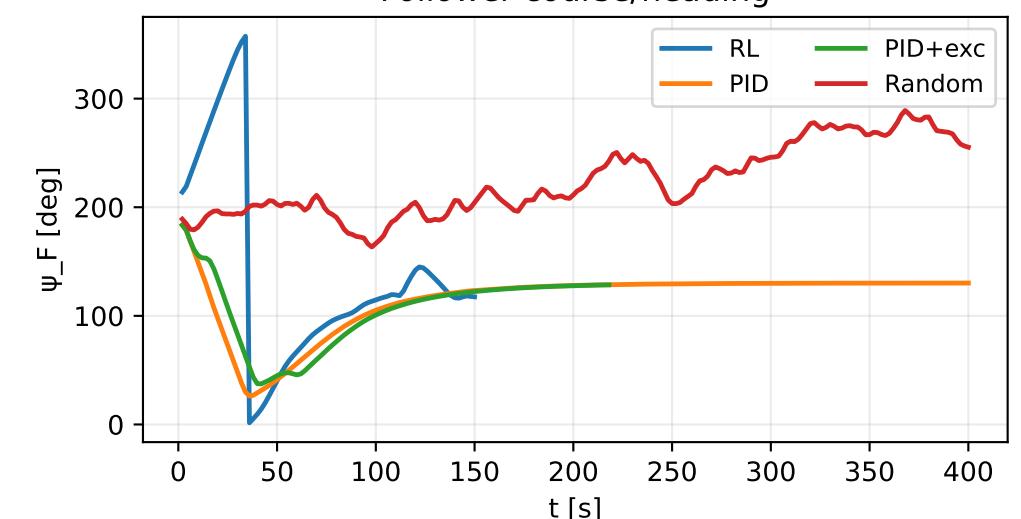
Information and excitation



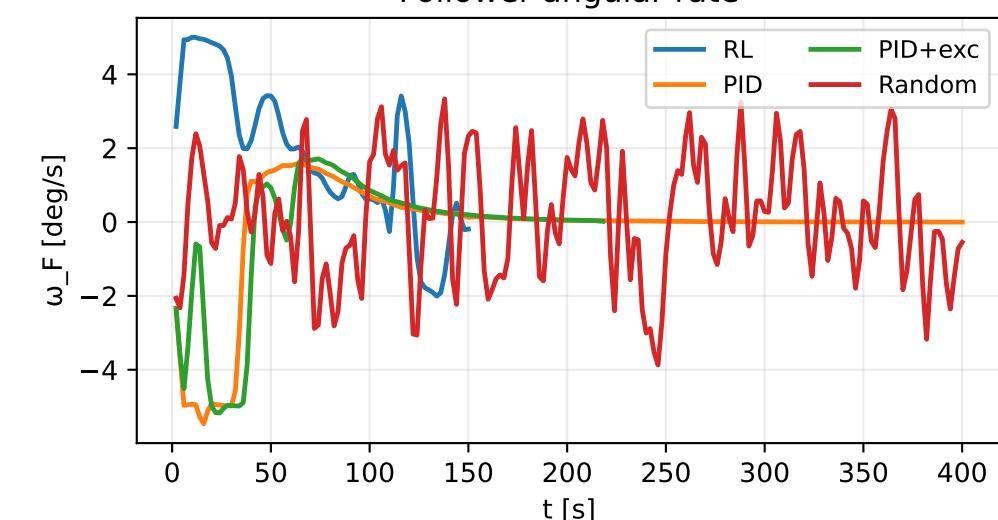
Follower speed



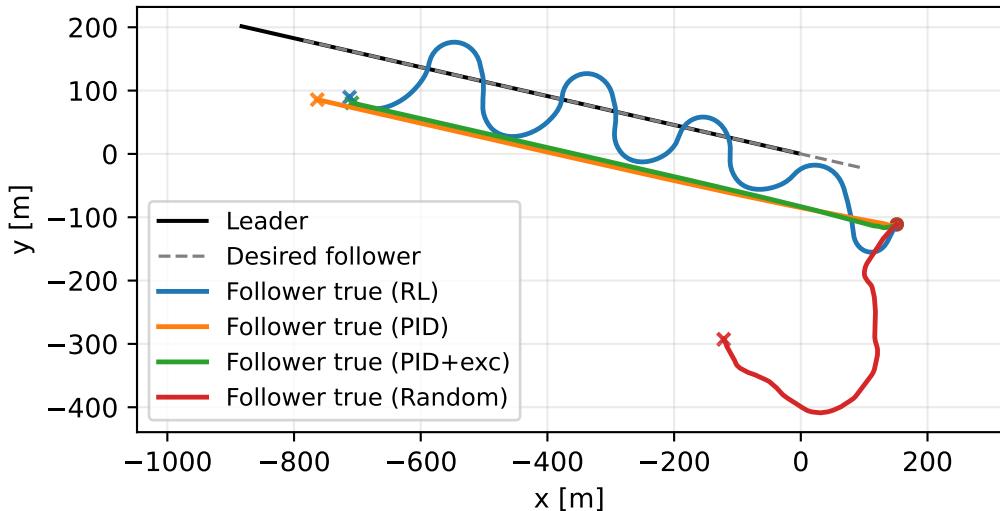
Follower course/heading



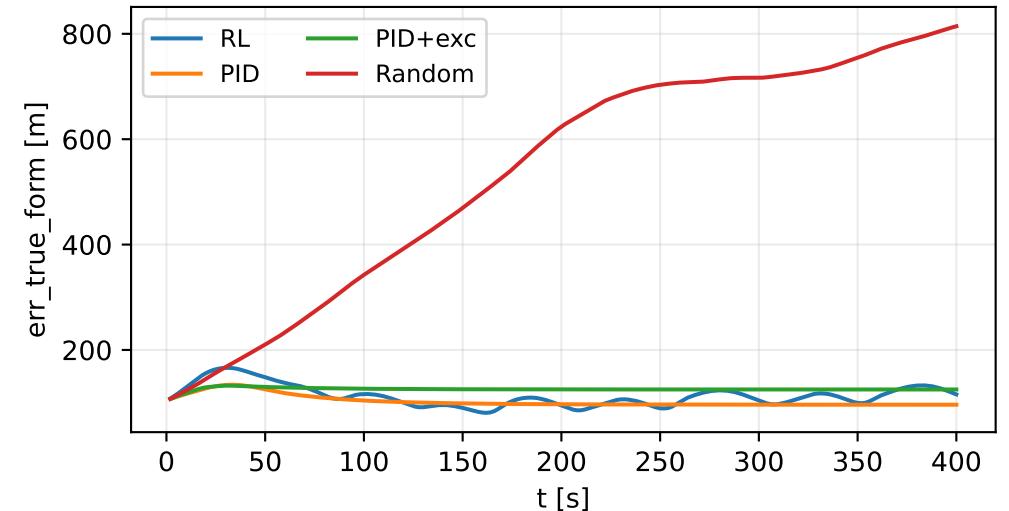
Follower angular rate



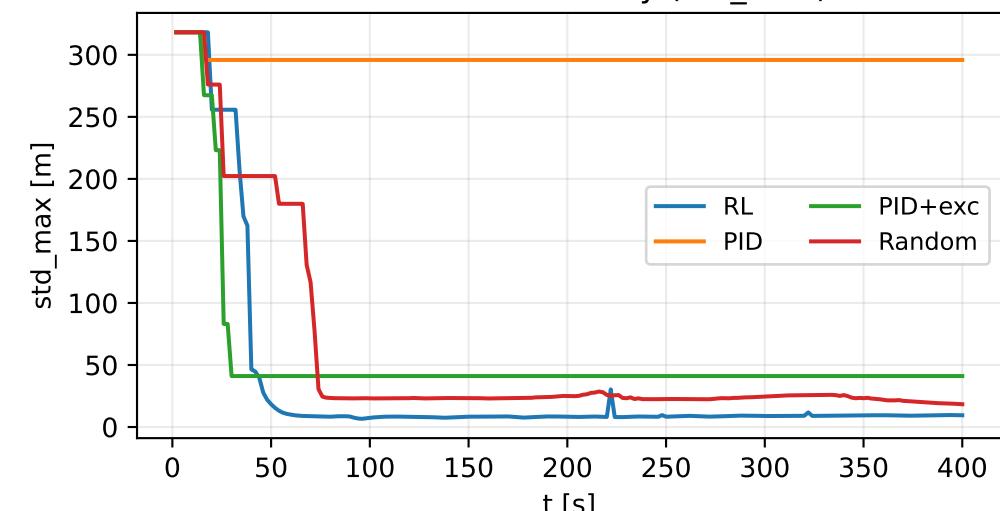
Trajectories (matched seed)



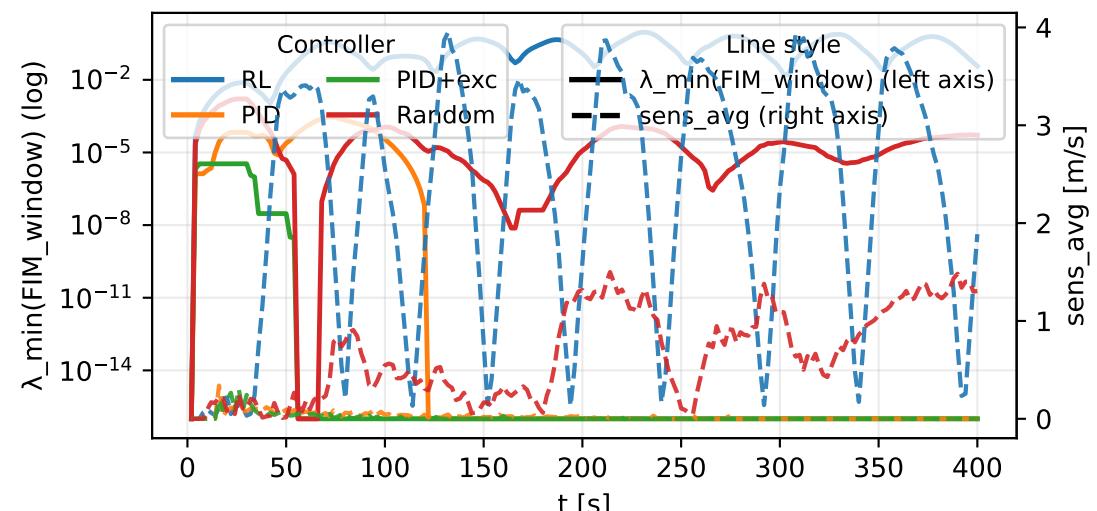
TRUE formation error



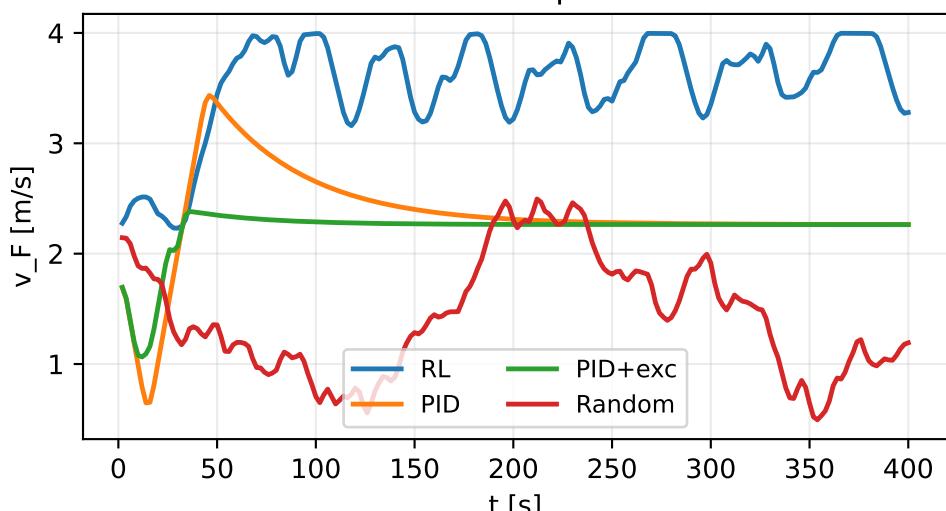
Estimator uncertainty (std_max)



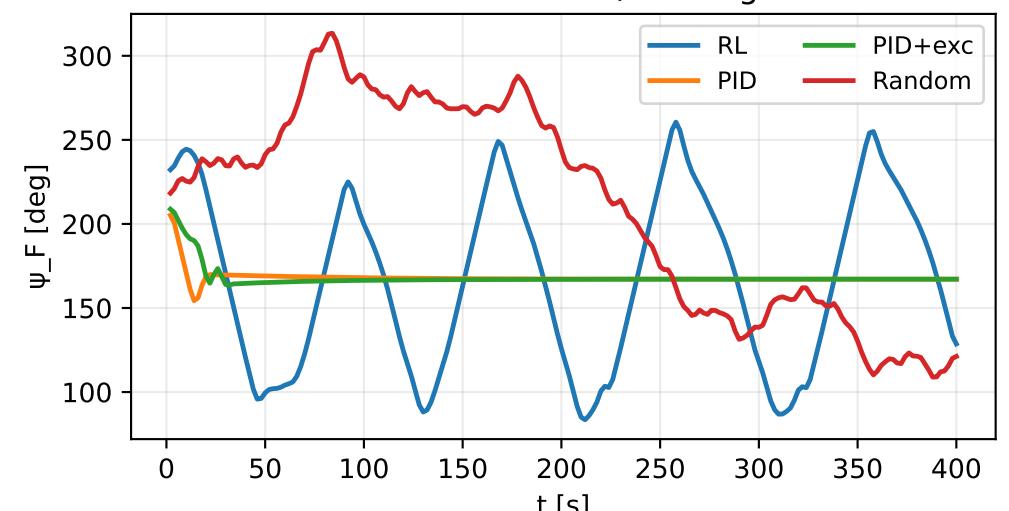
Information and excitation



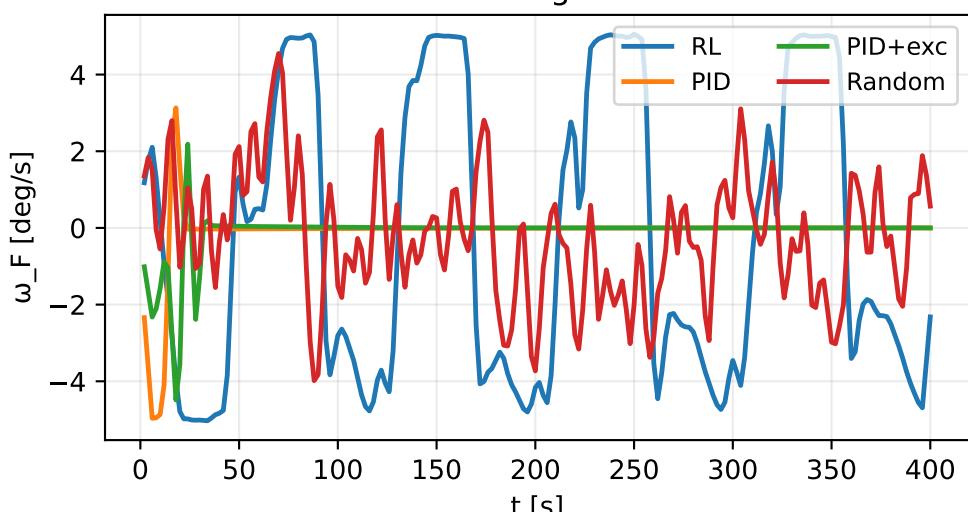
Follower speed



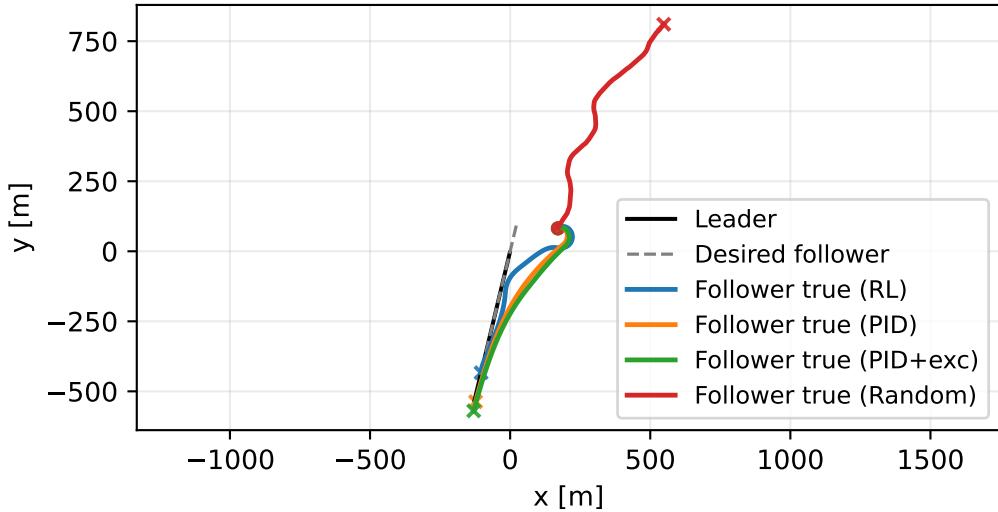
Follower course/heading



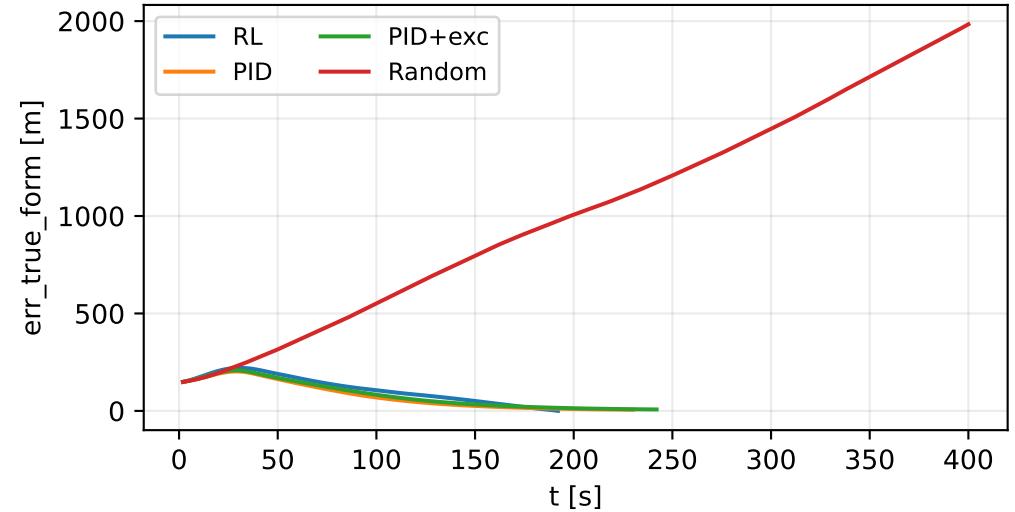
Follower angular rate



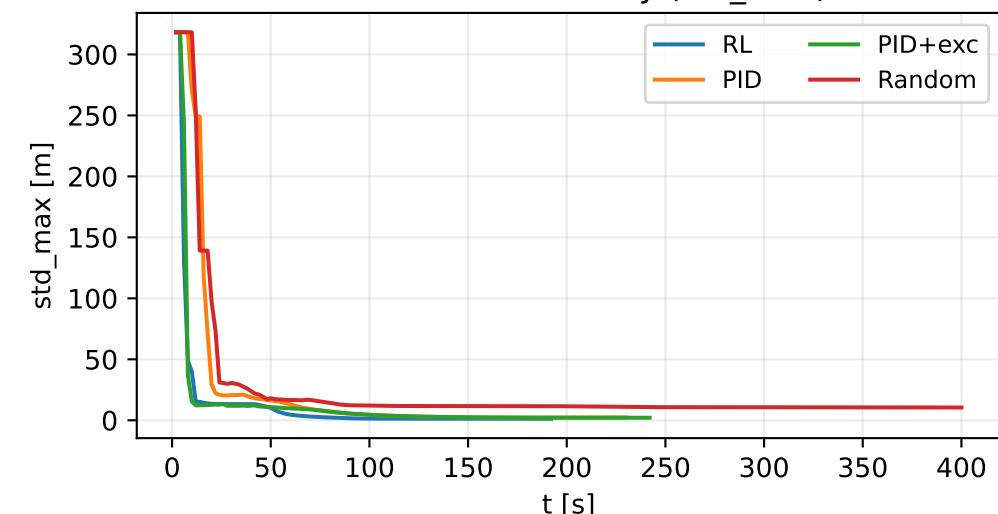
Trajectories (matched seed)



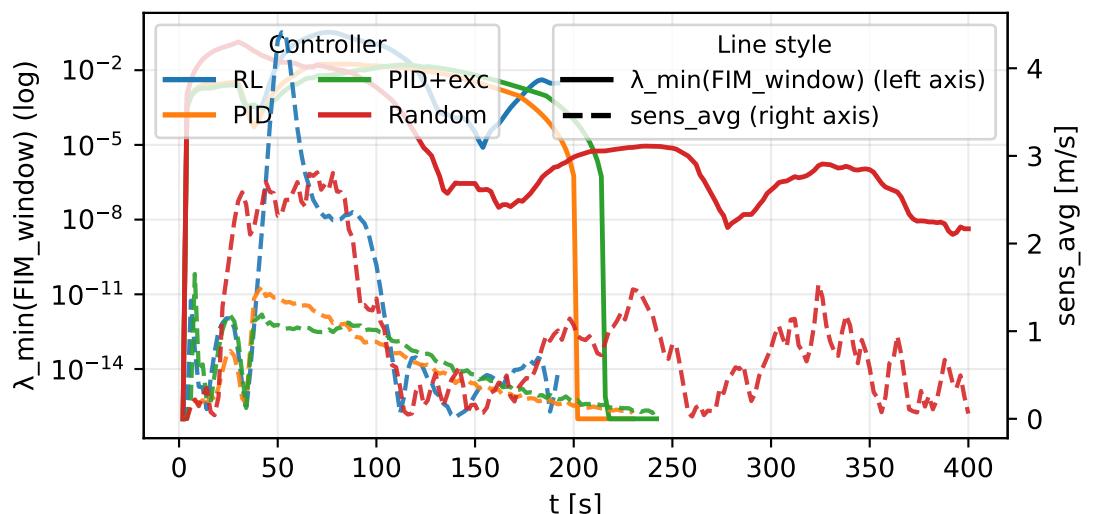
TRUE formation error



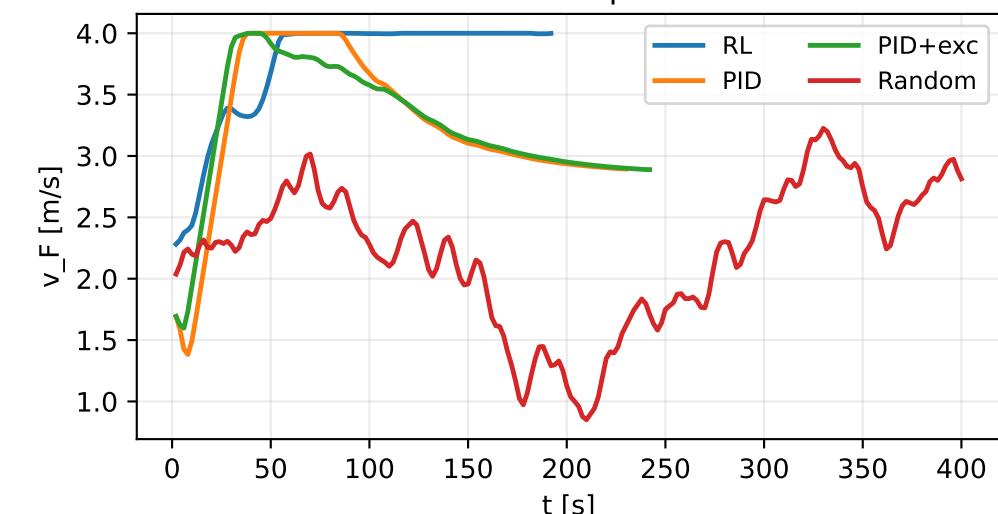
Estimator uncertainty (std_max)



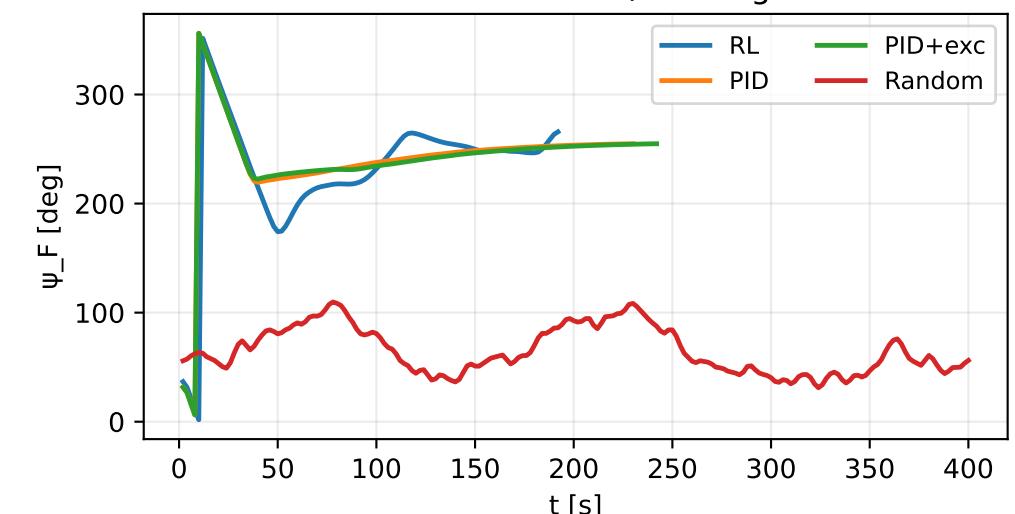
Information and excitation



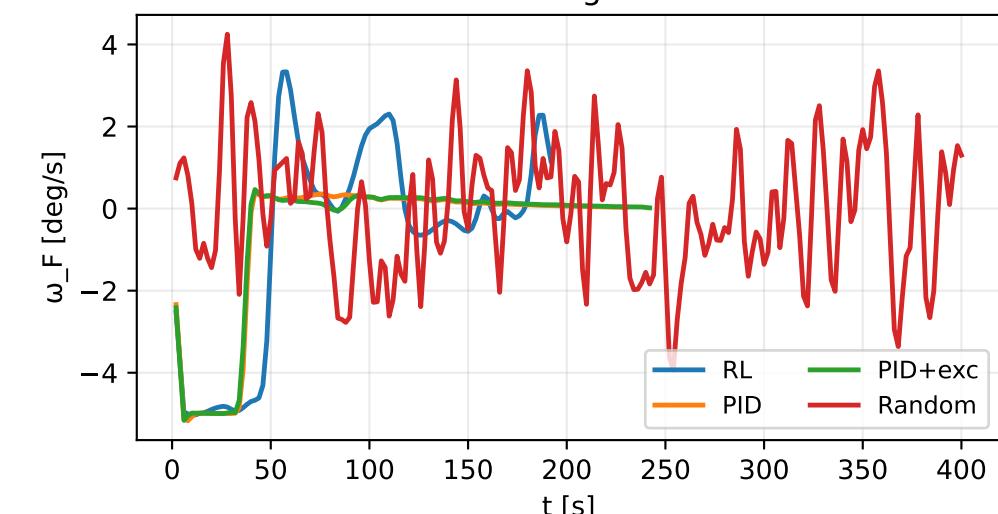
Follower speed



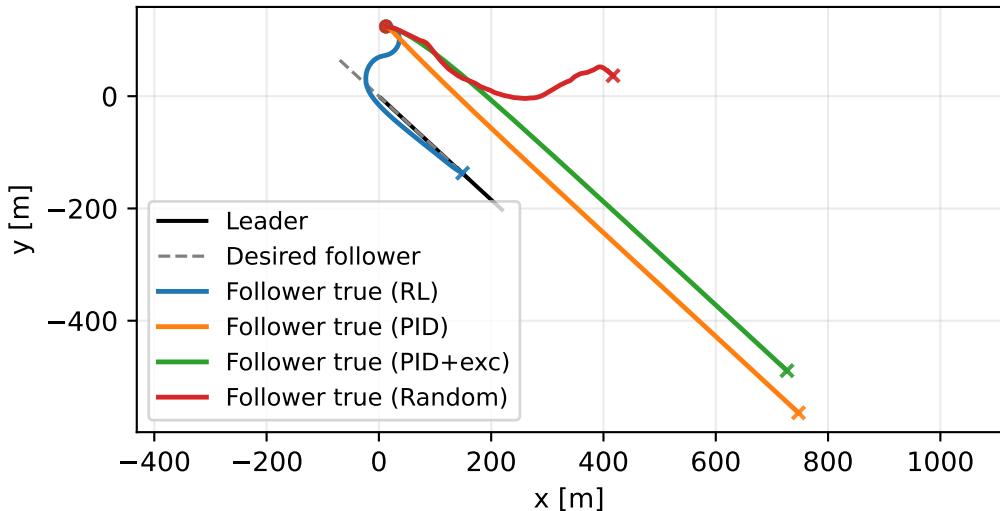
Follower course/heading



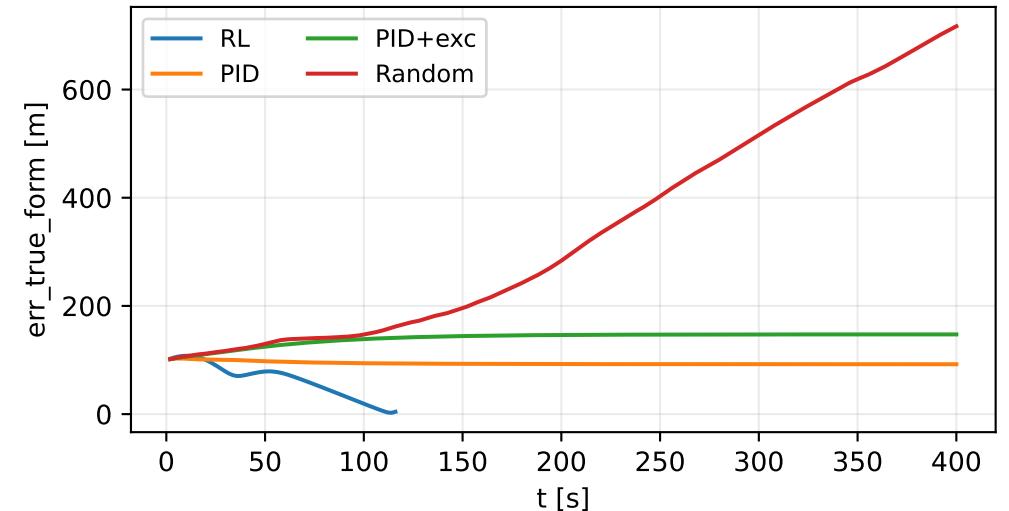
Follower angular rate



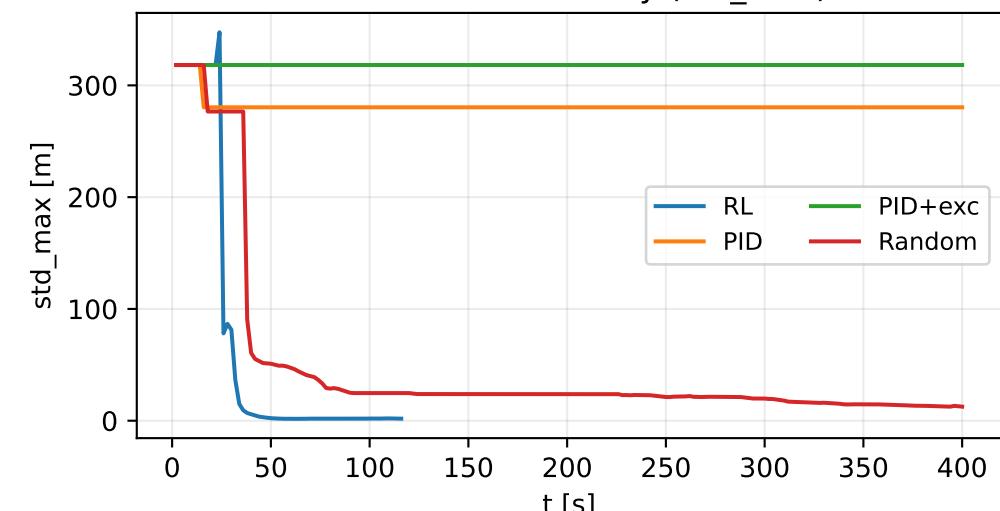
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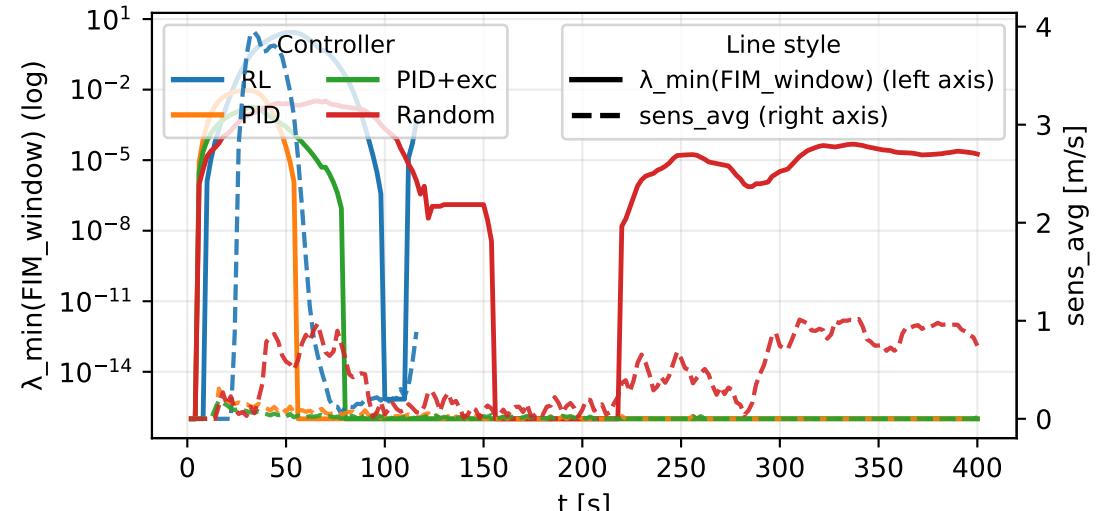
TRUE formation error



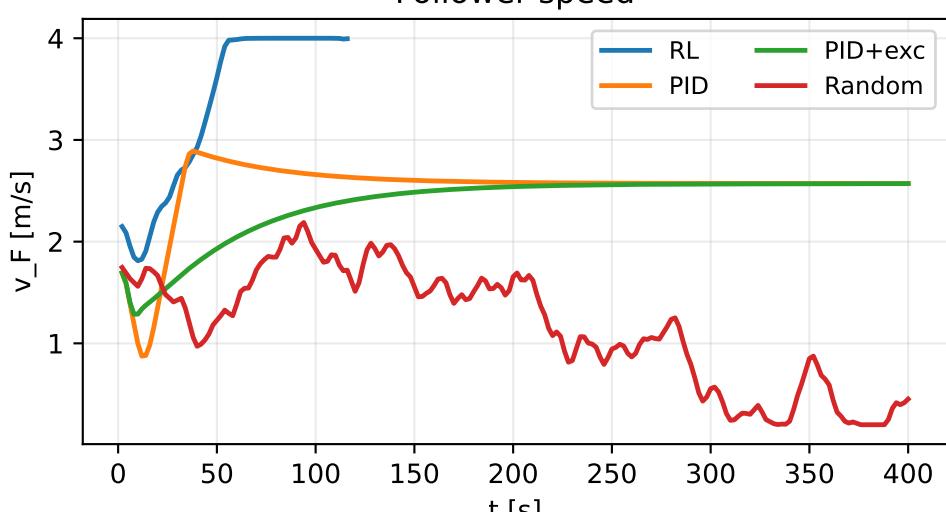
Estimator uncertainty (std_max)



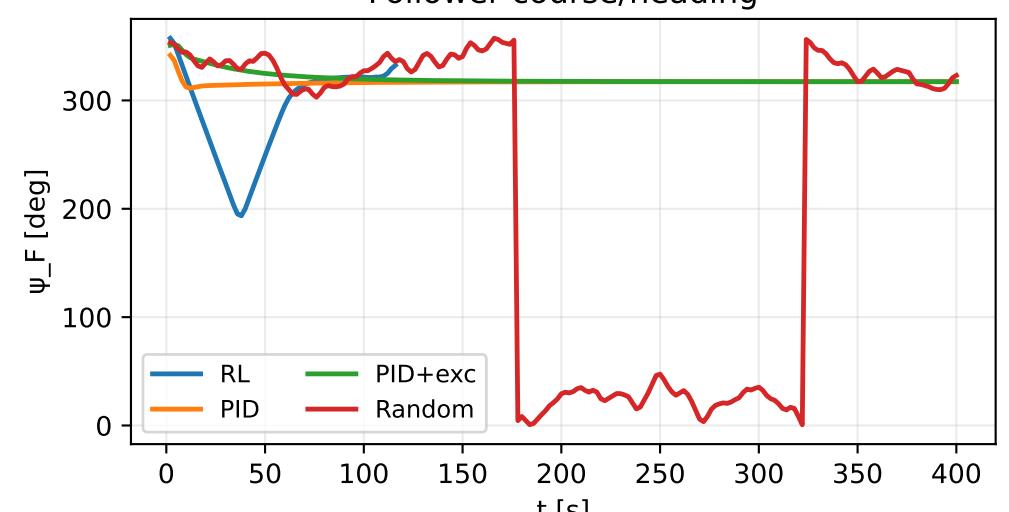
Information and excitation



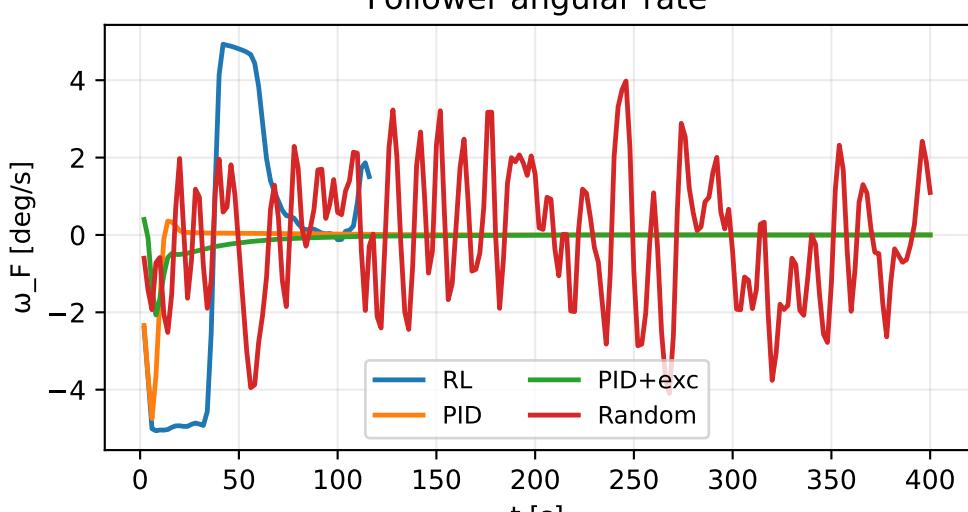
Follower speed



Follower course/heading



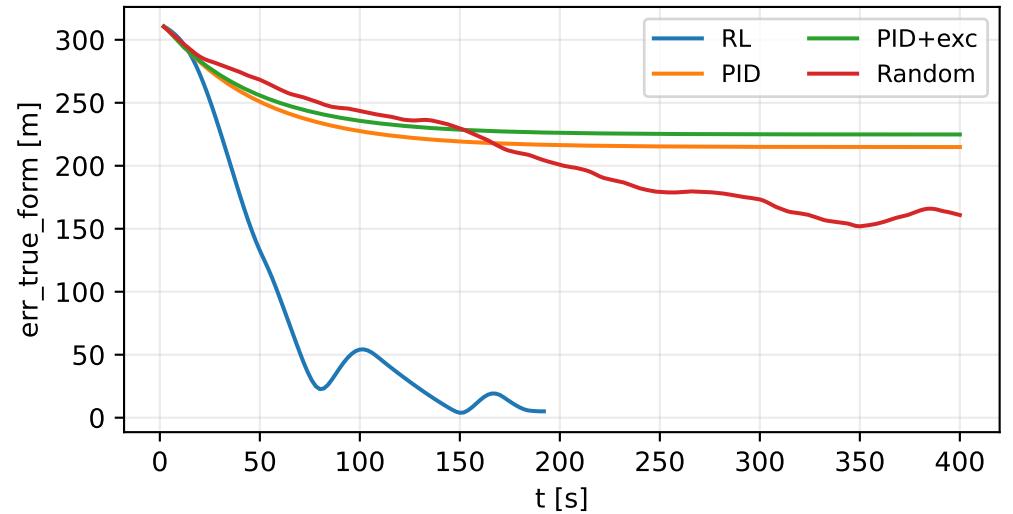
Follower angular rate



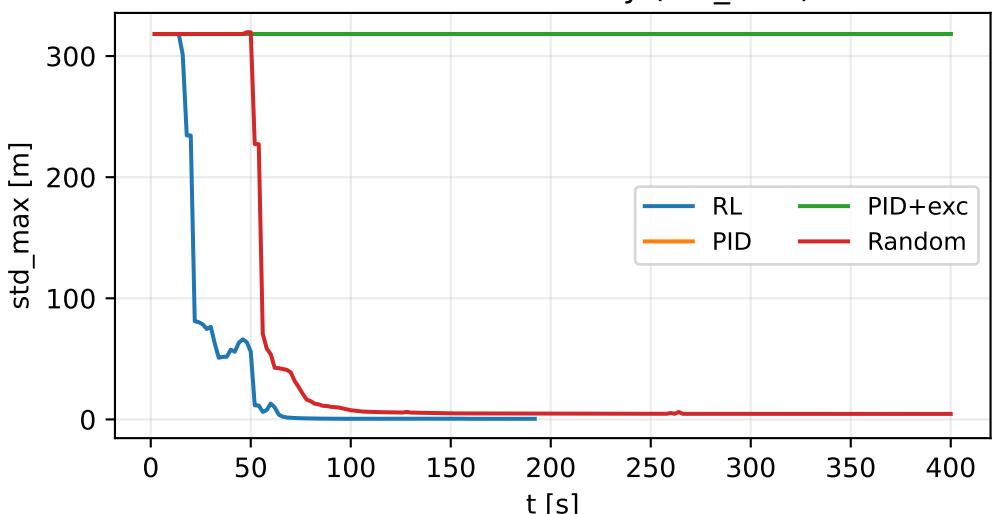
Trajectories (matched seed)



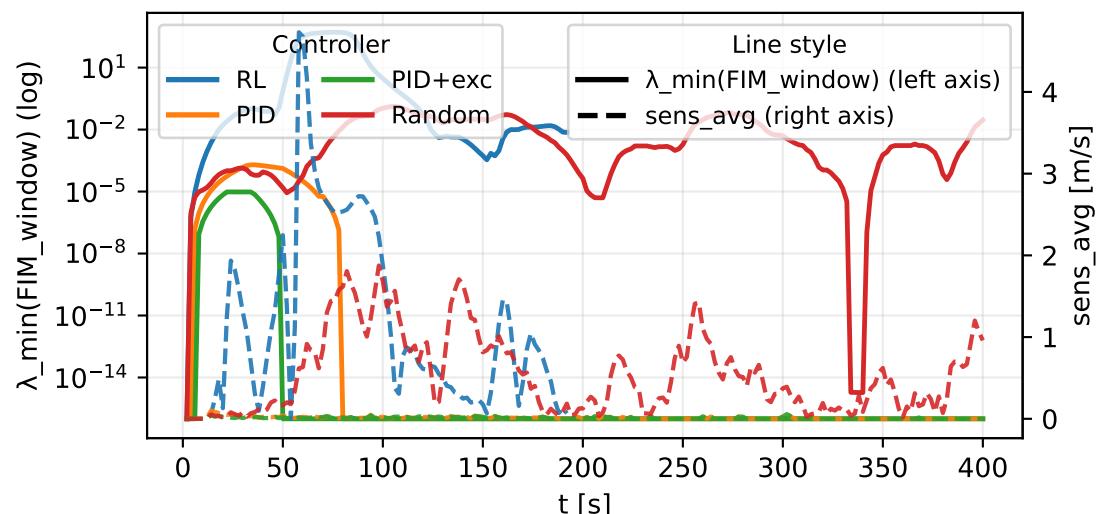
TRUE formation error



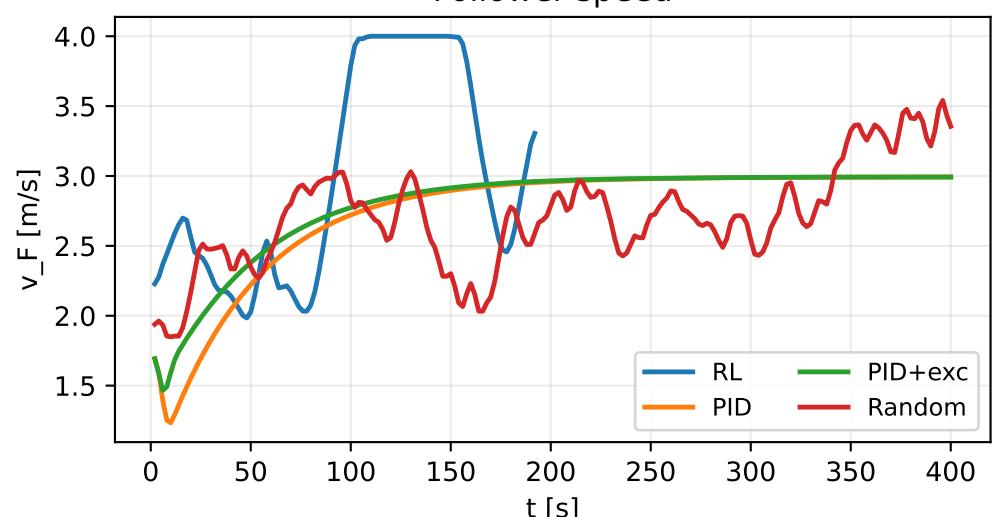
Estimator uncertainty (std_max)



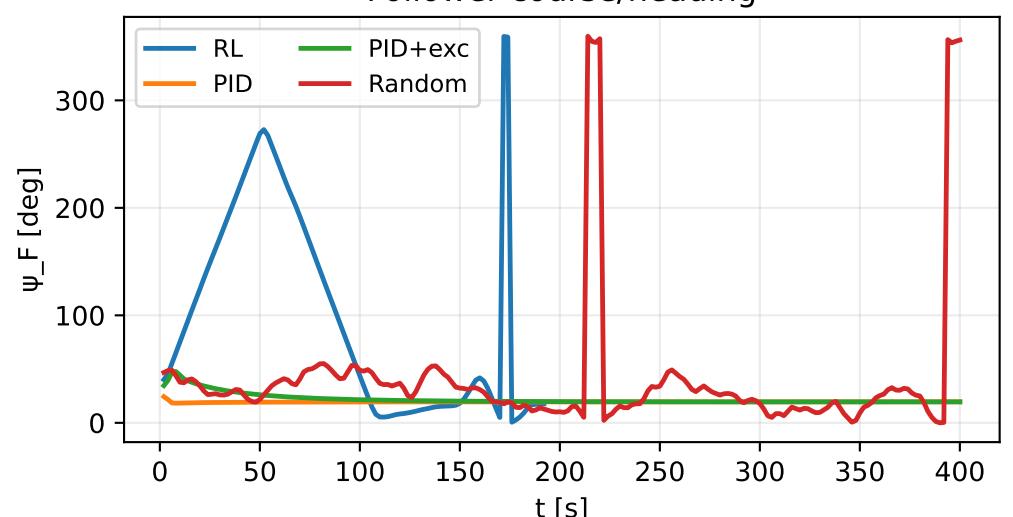
Information and excitation



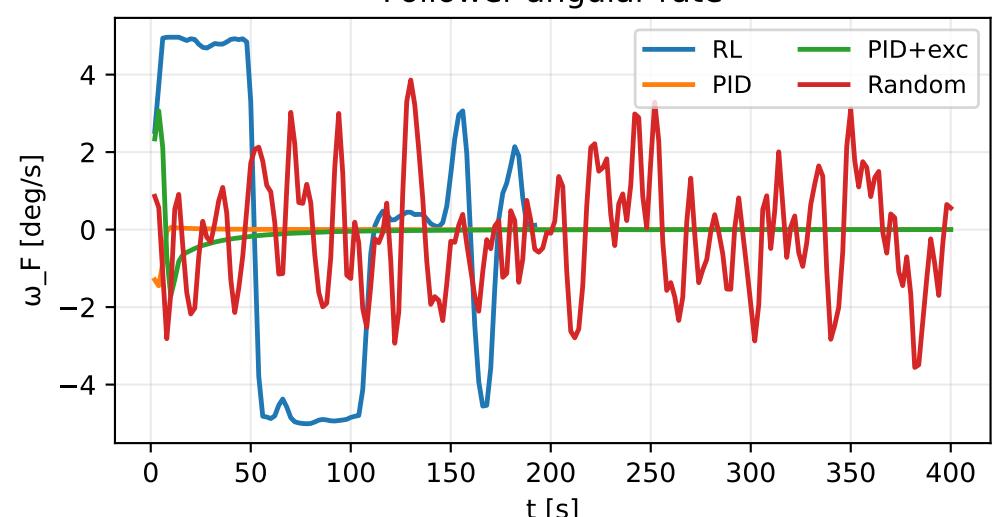
Follower speed



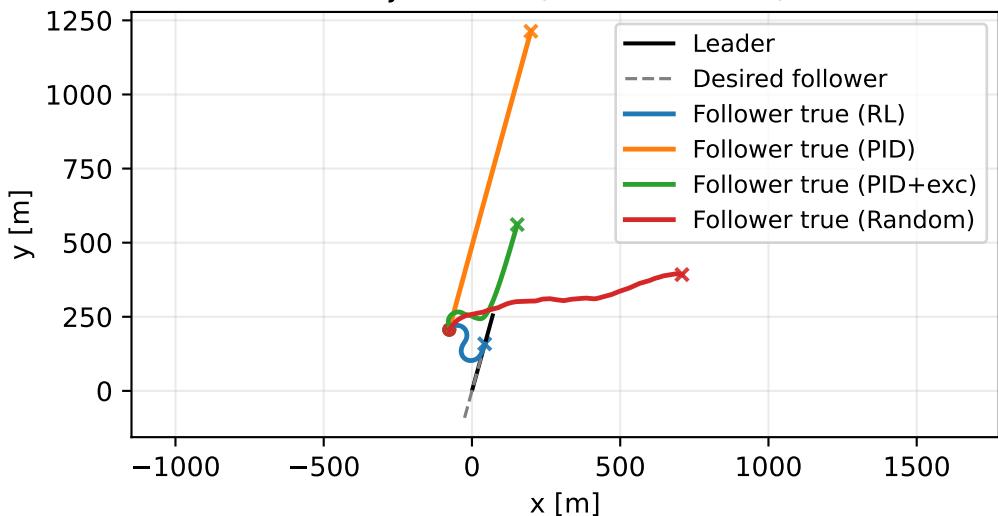
Follower course/heading



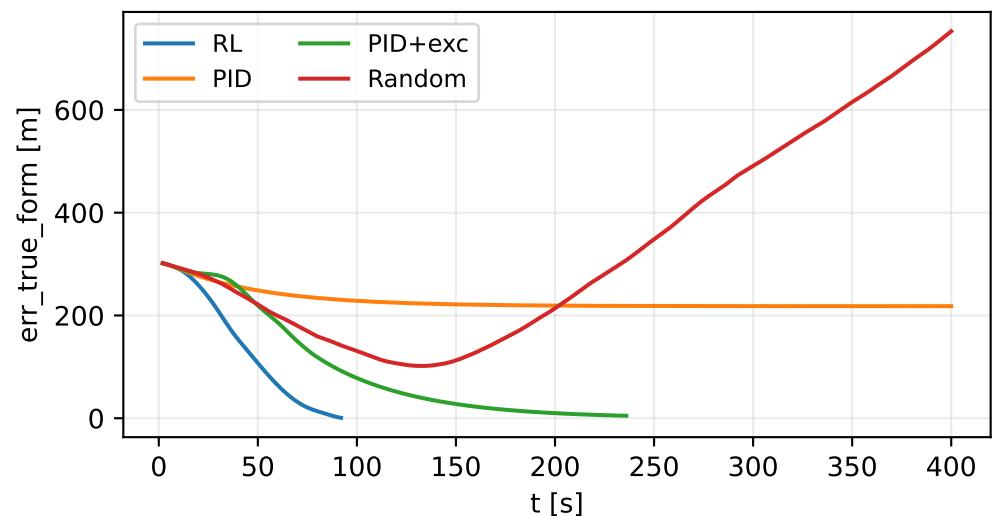
Follower angular rate



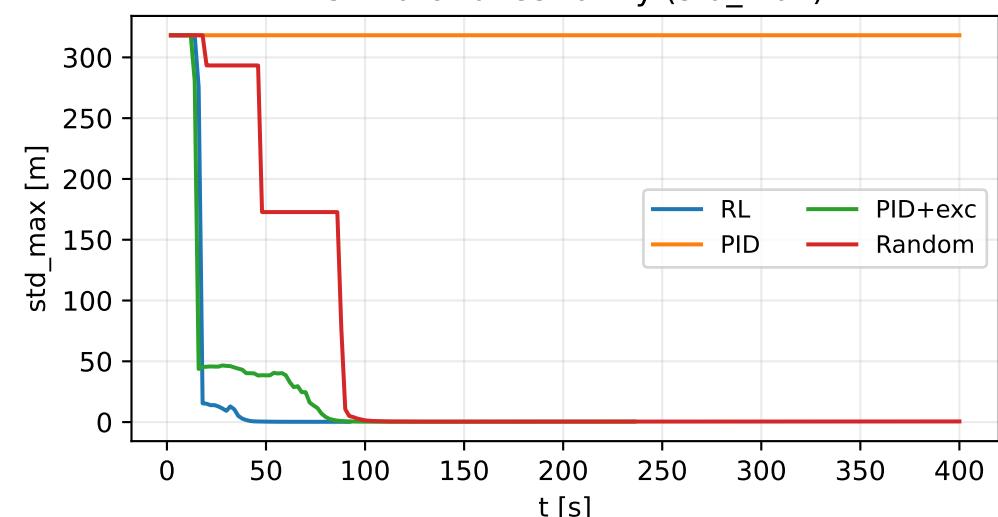
Trajectories (matched seed)



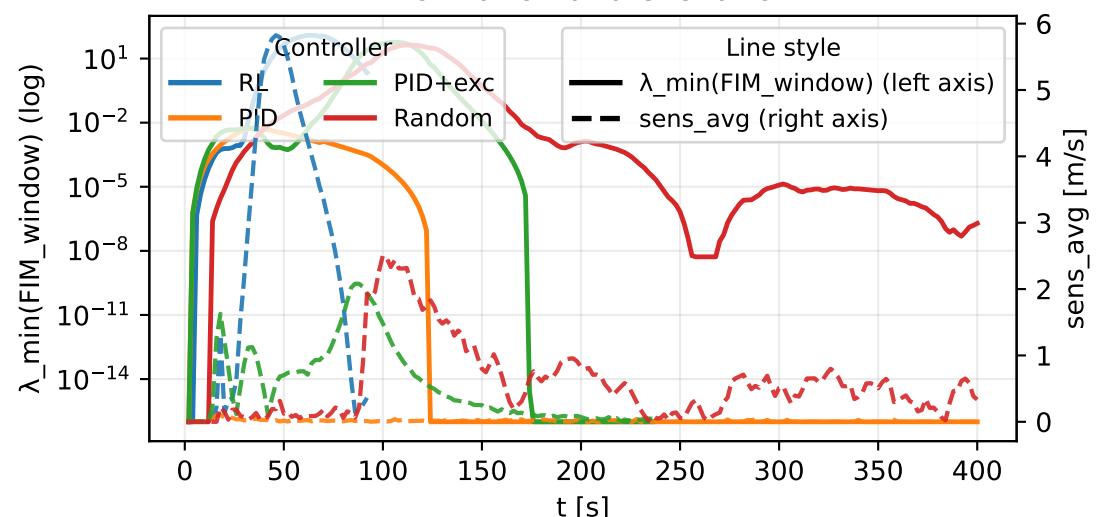
TRUE formation error



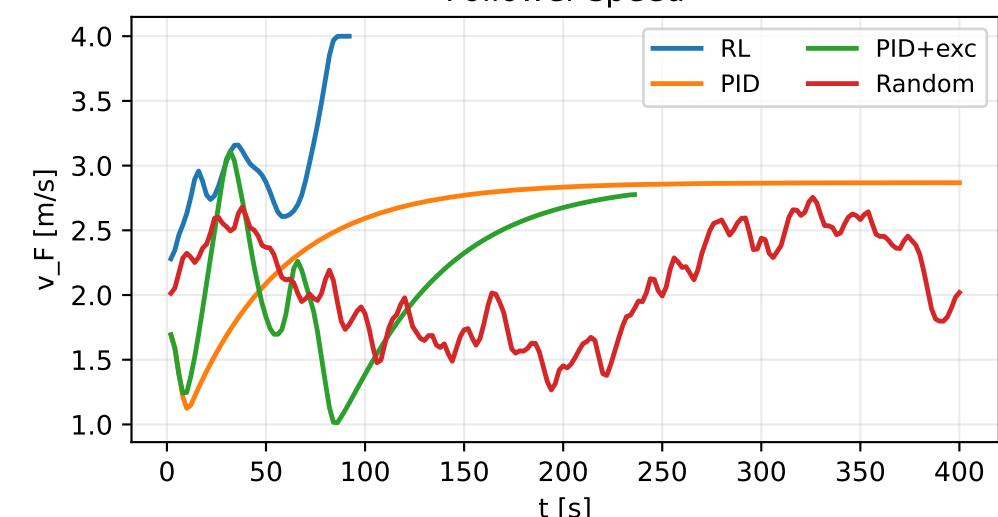
Estimator uncertainty (std_max)



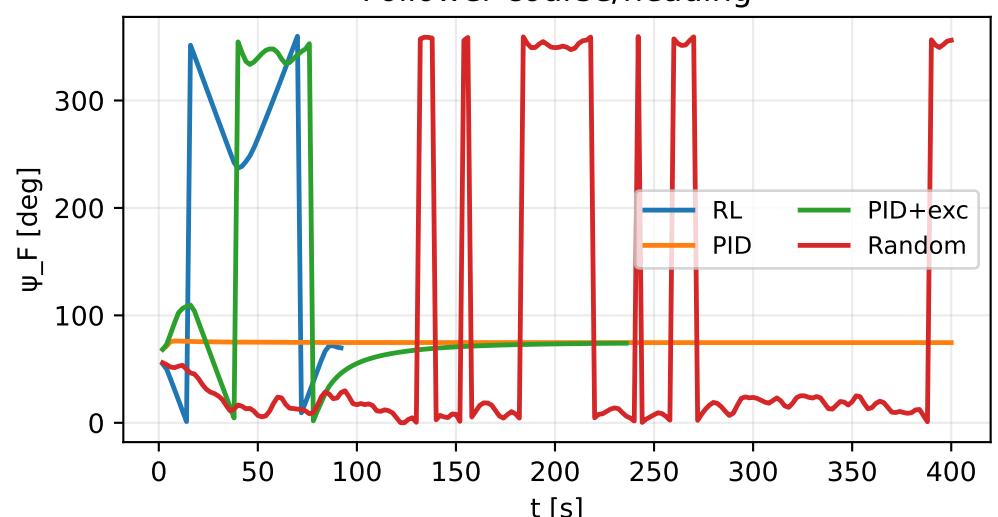
Information and excitation



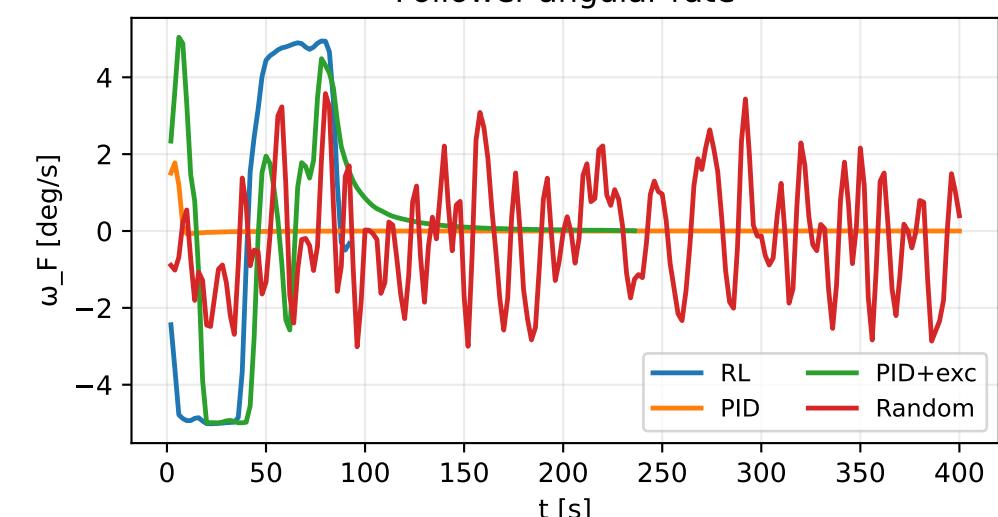
Follower speed



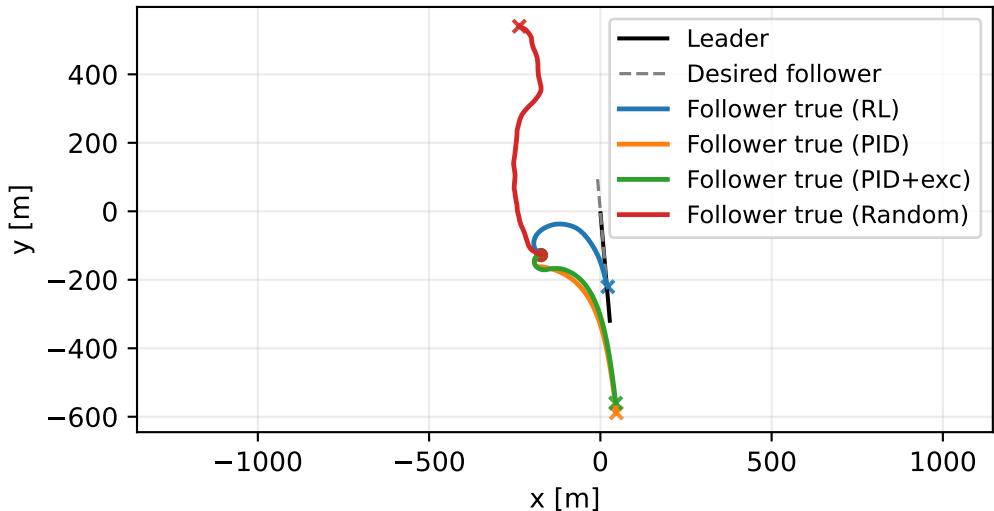
Follower course/heading



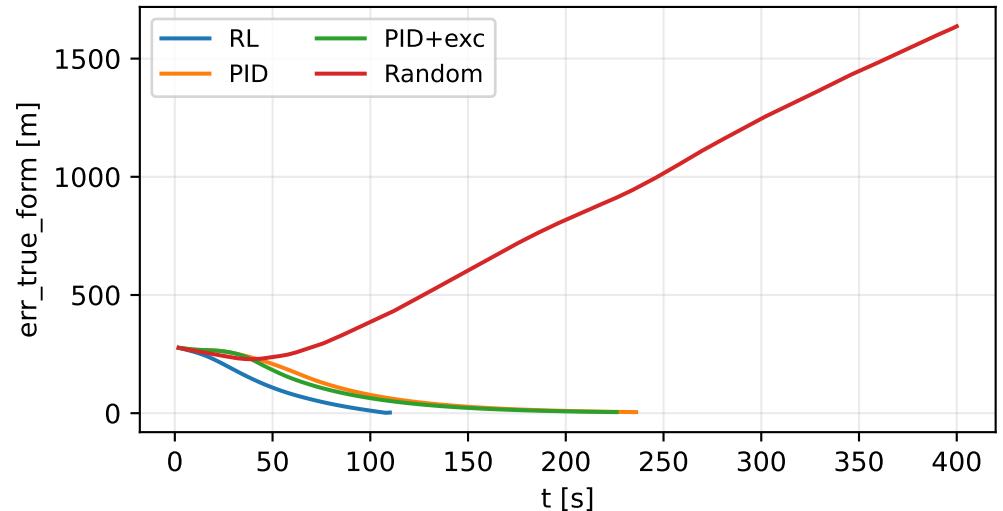
Follower angular rate



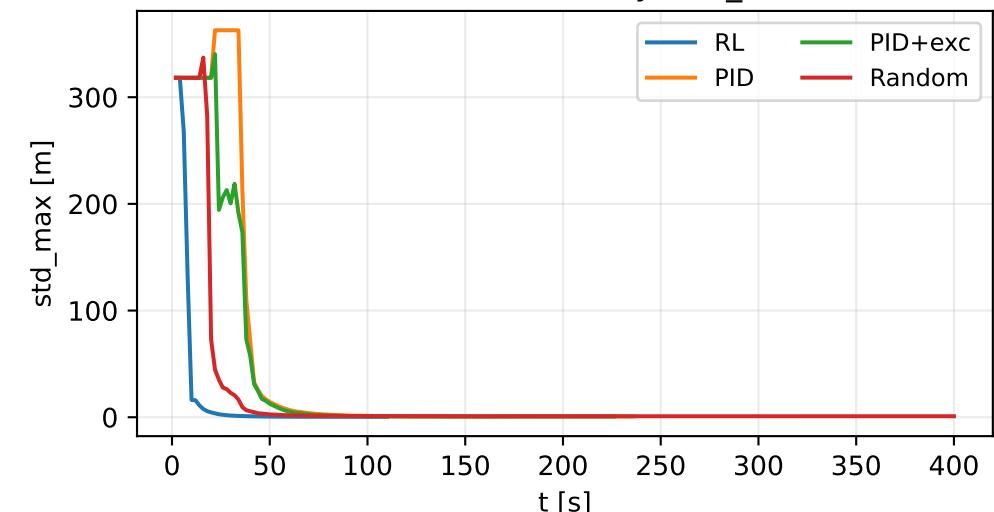
Trajectories (matched seed)



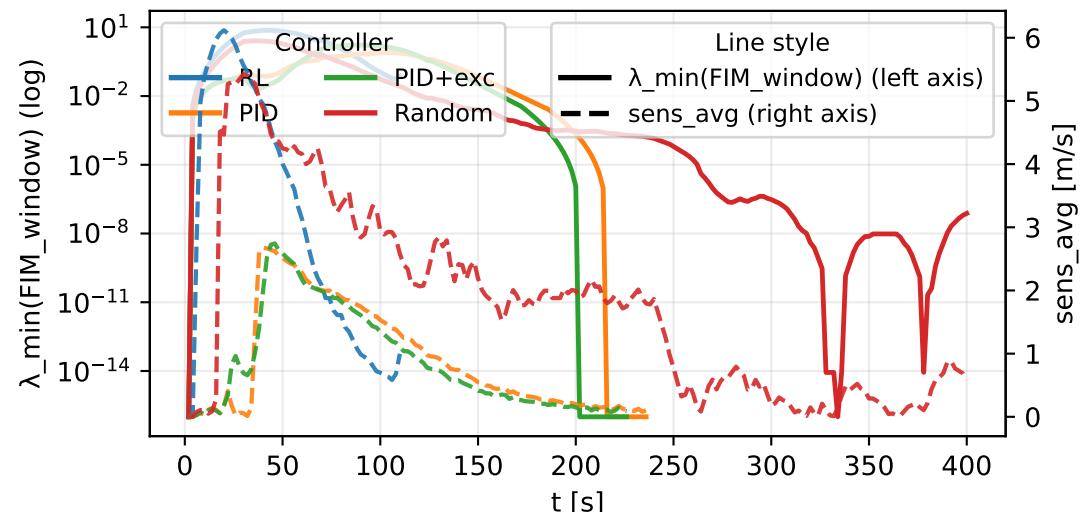
TRUE formation error



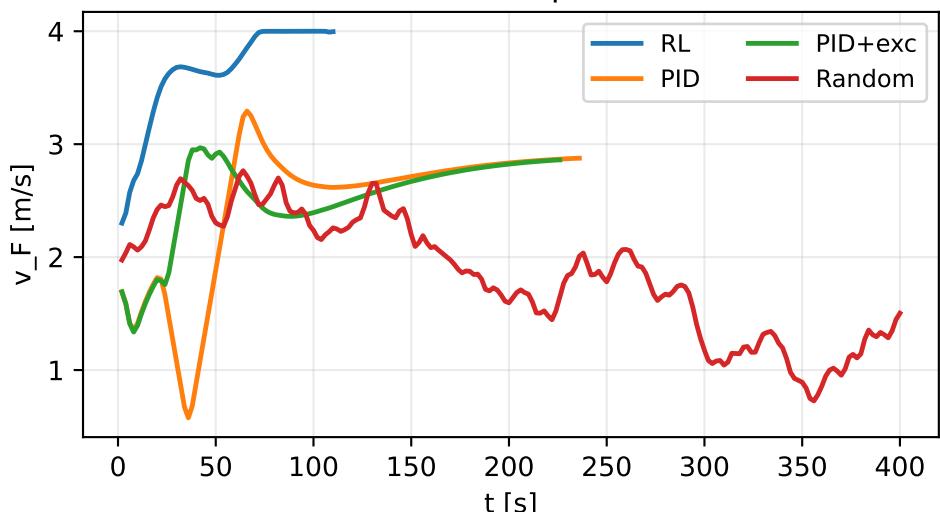
Estimator uncertainty (std_max)



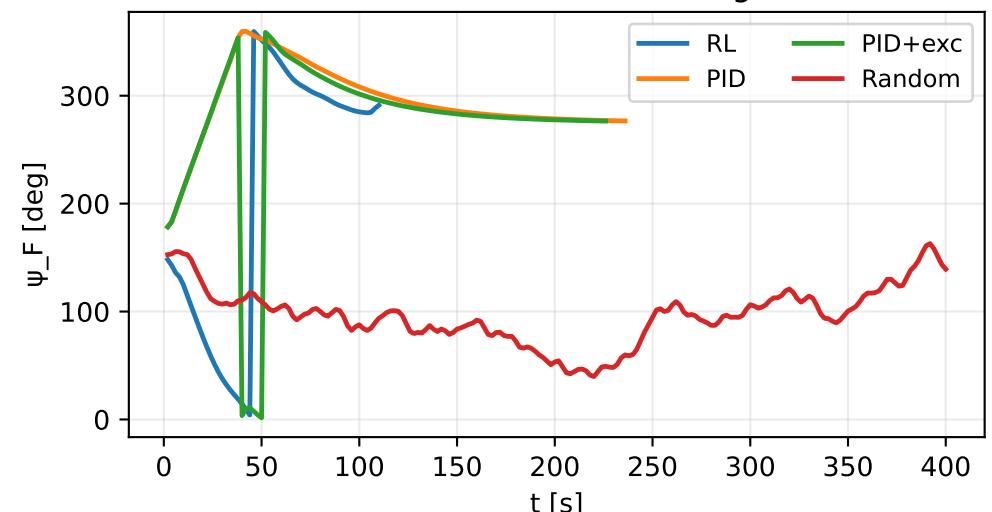
Information and excitation



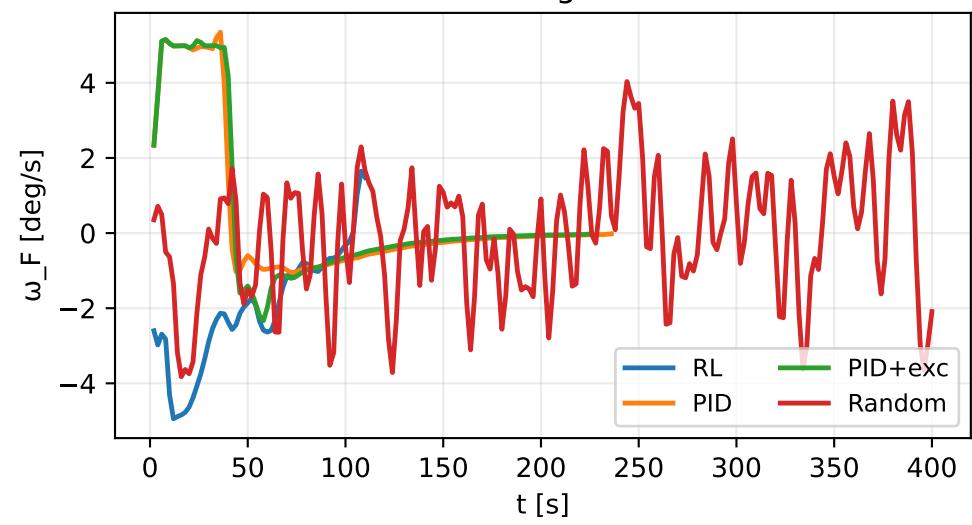
Follower speed



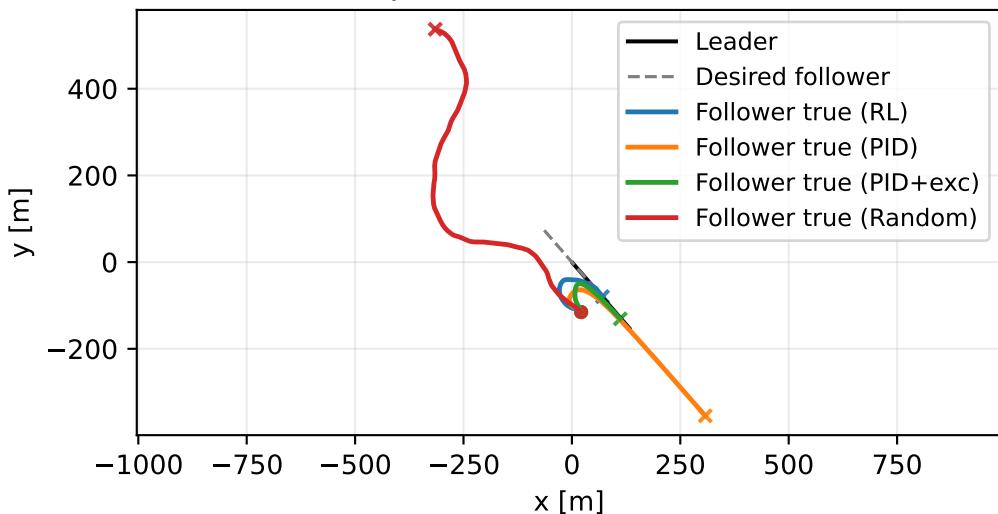
Follower course/heading



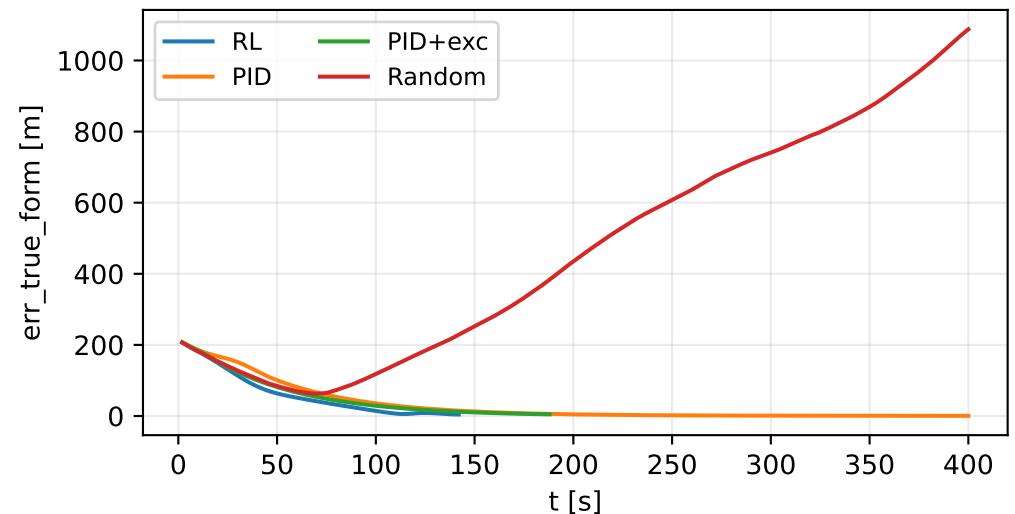
Follower angular rate



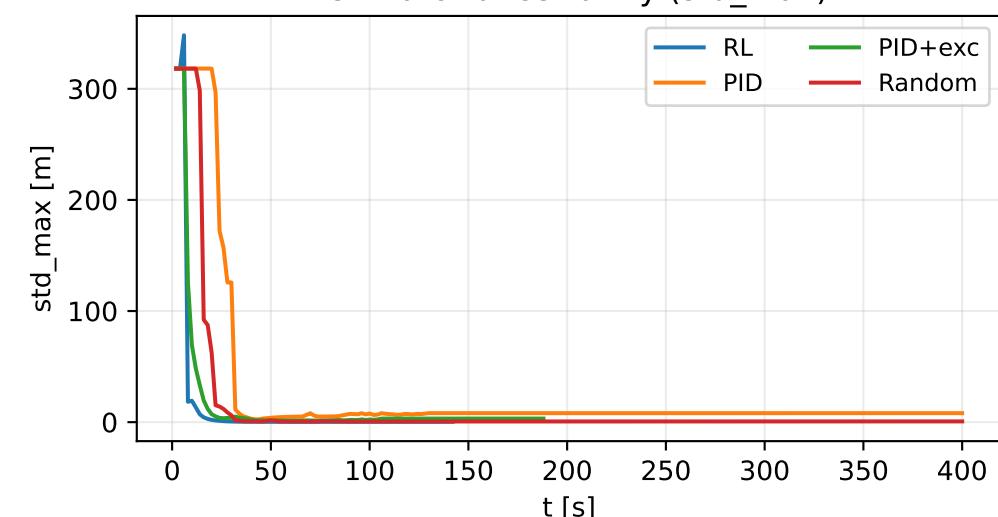
Trajectories (matched seed)



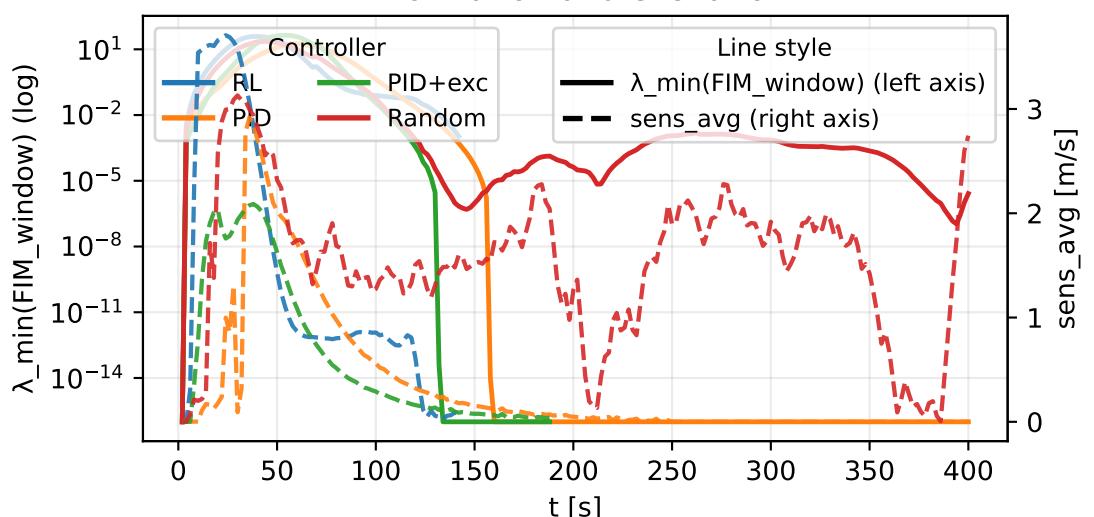
TRUE formation error



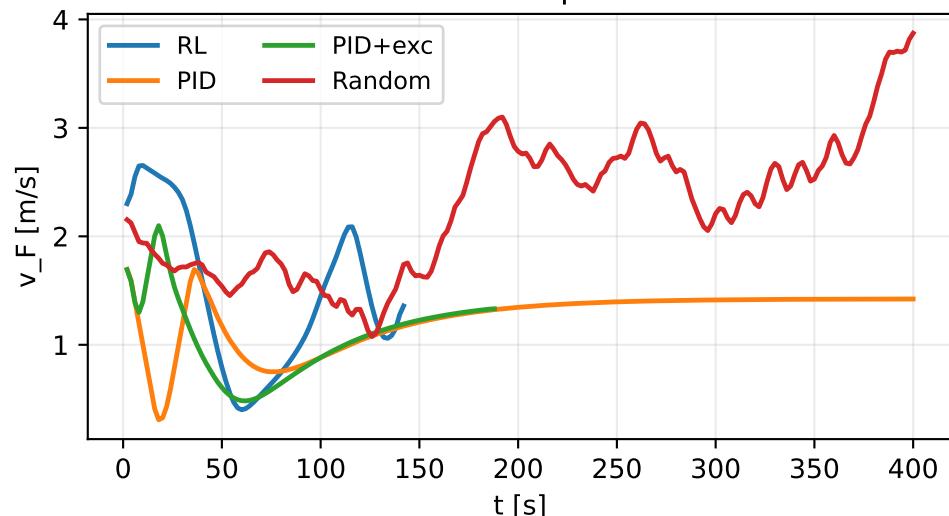
Estimator uncertainty (std_max)



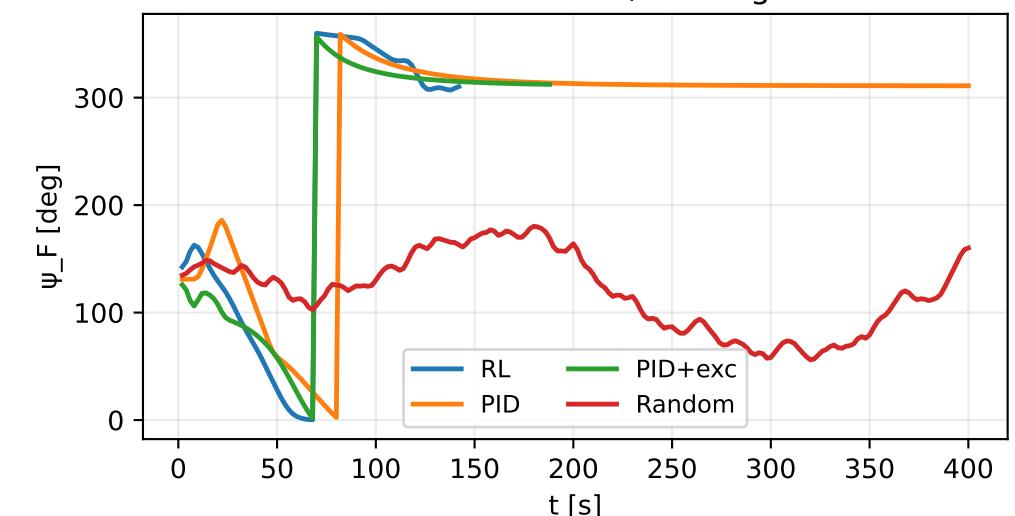
Information and excitation



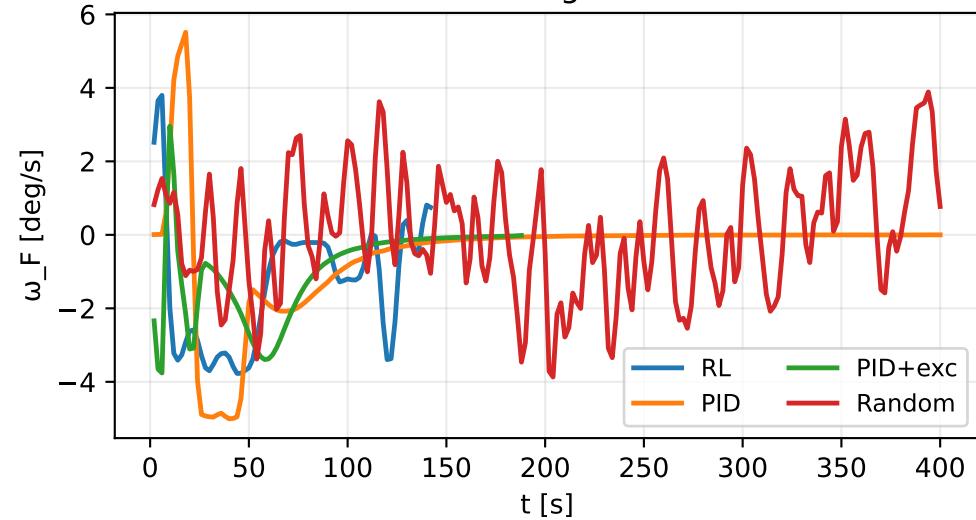
Follower speed



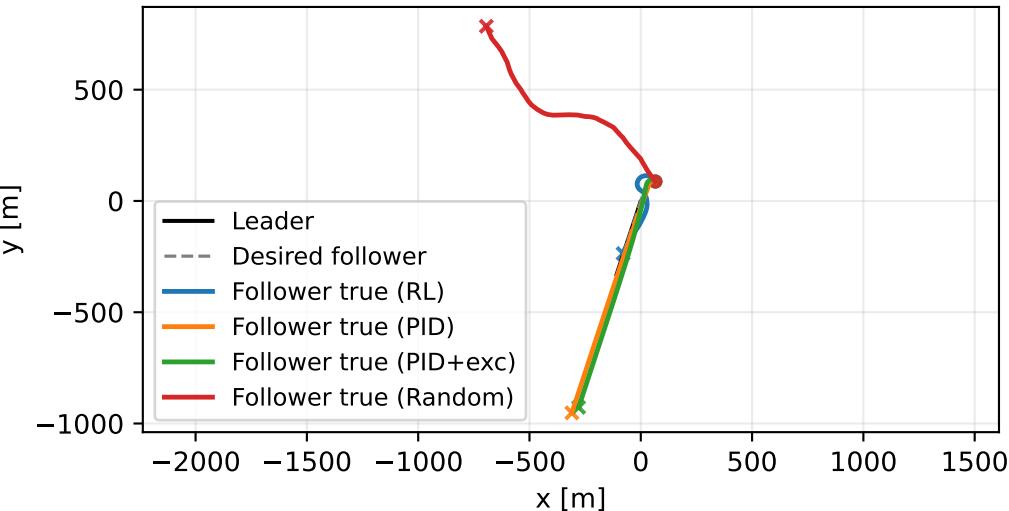
Follower course/heading



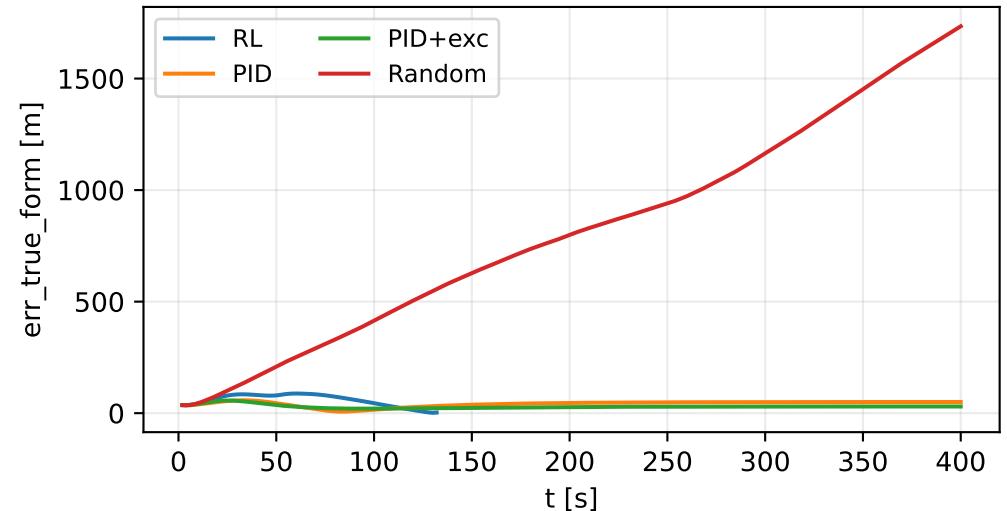
Follower angular rate



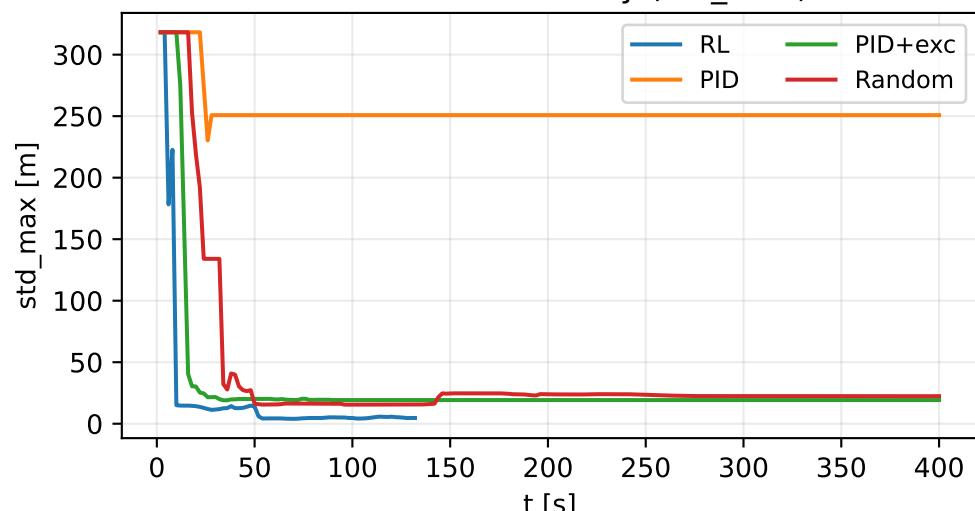
Trajectories (matched seed)



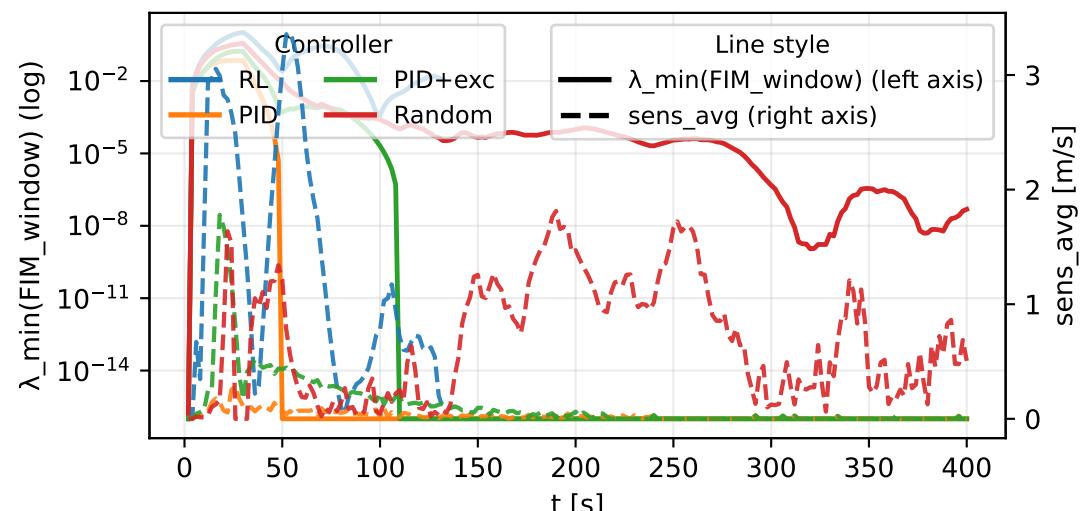
TRUE formation error



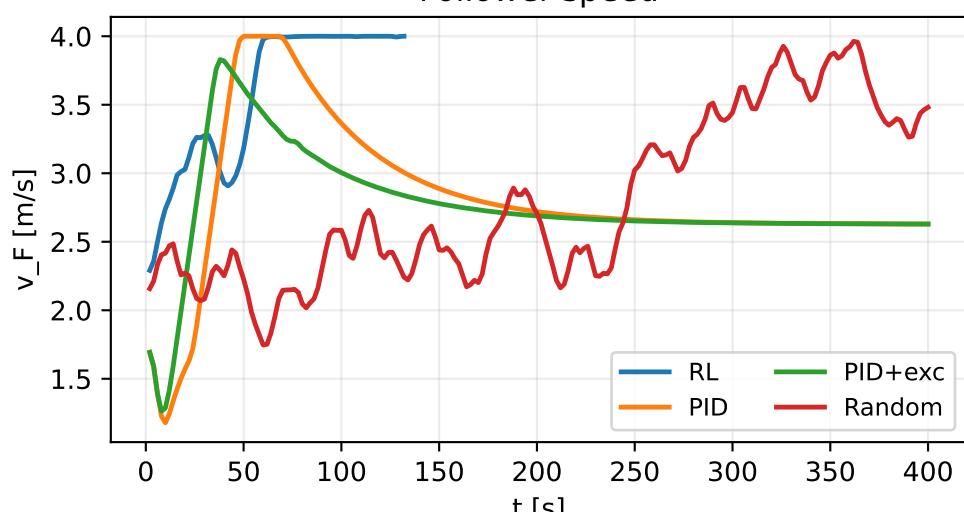
Estimator uncertainty (std_max)



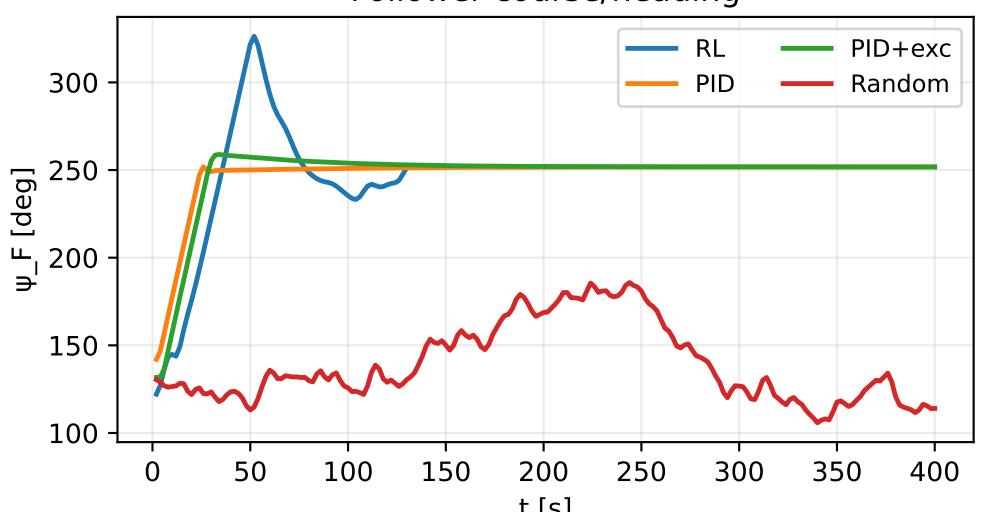
Information and excitation



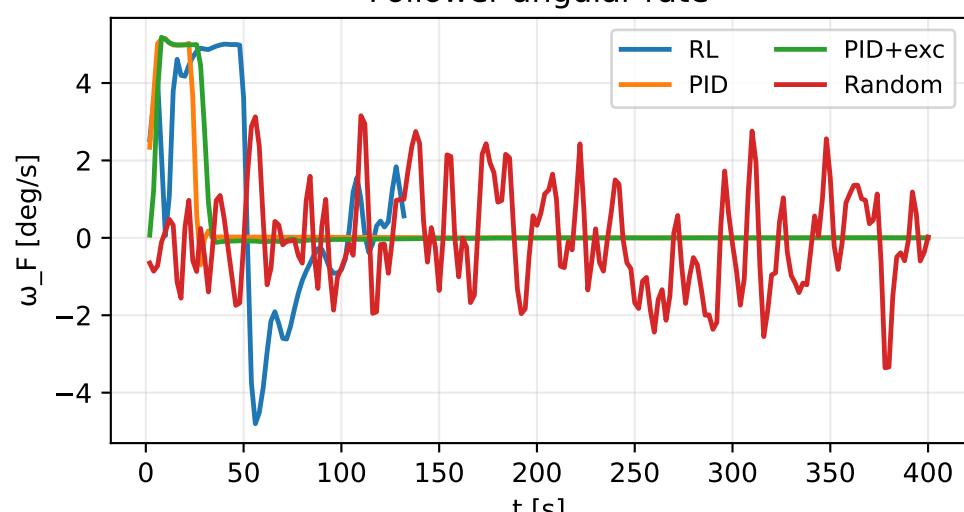
Follower speed



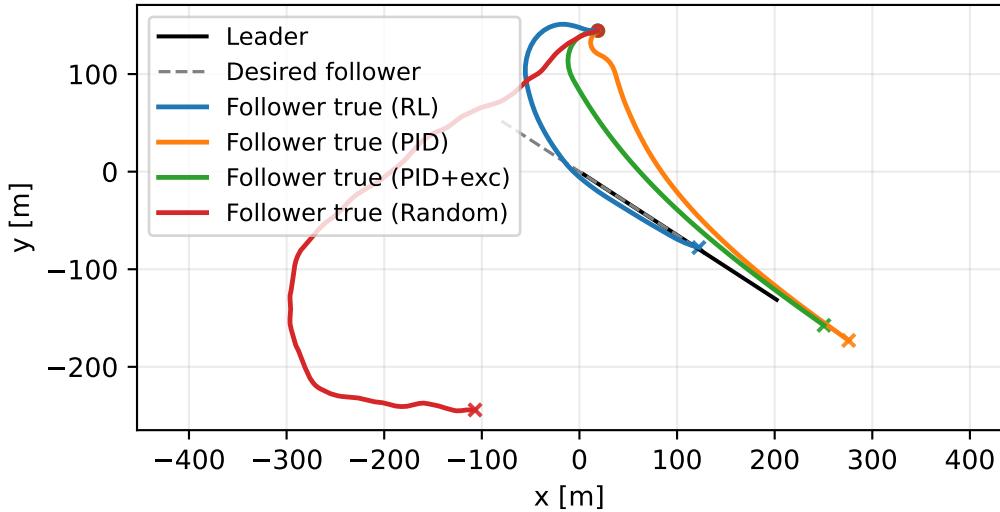
Follower course/heading



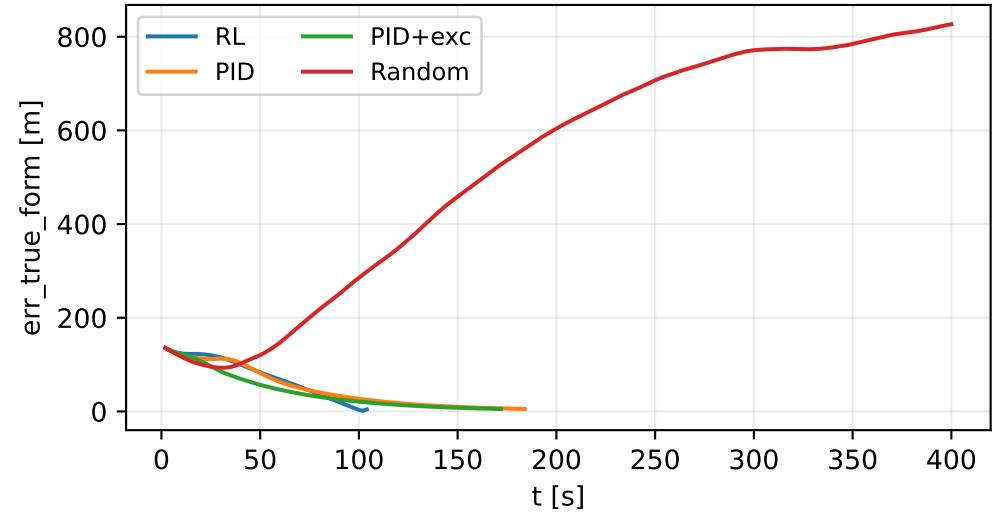
Follower angular rate



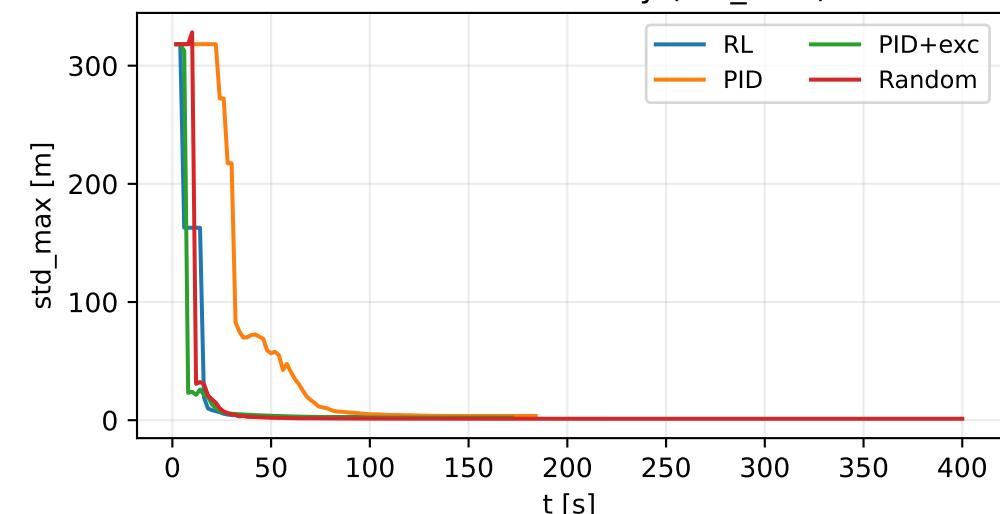
Trajectories (matched seed)



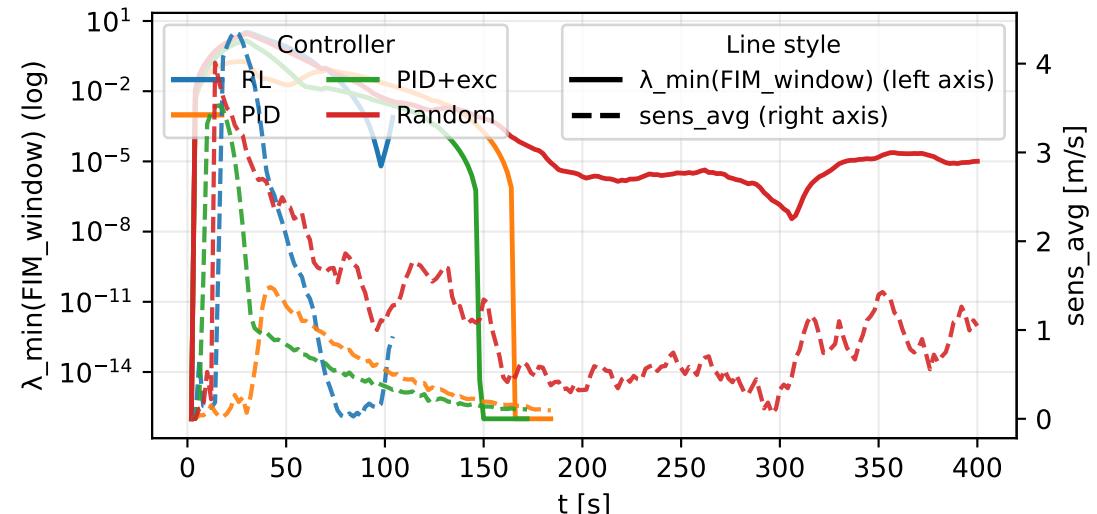
TRUE formation error



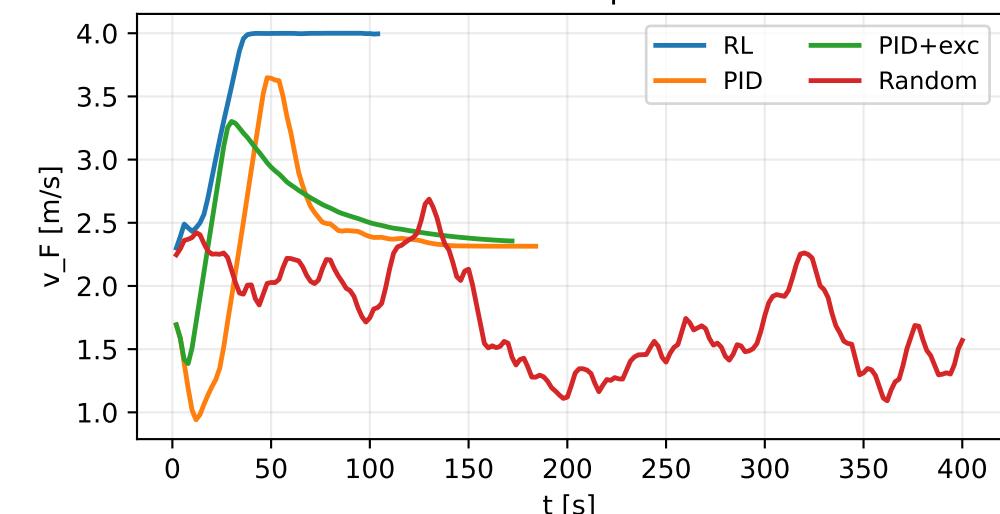
Estimator uncertainty (std_max)



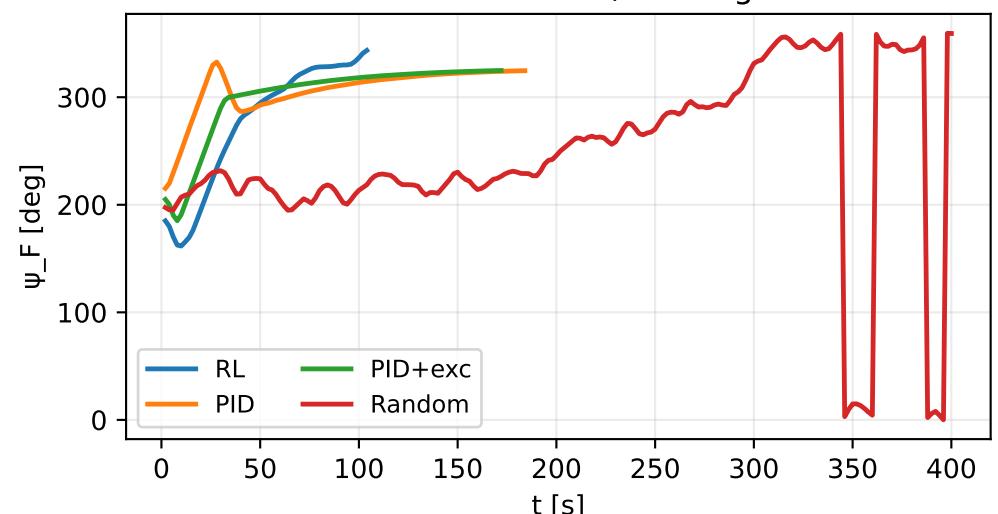
Information and excitation



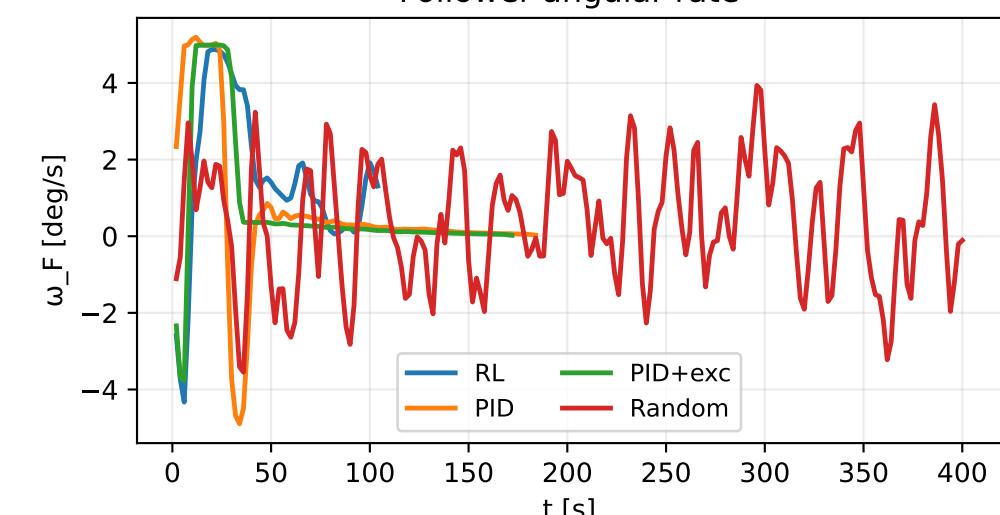
Follower speed



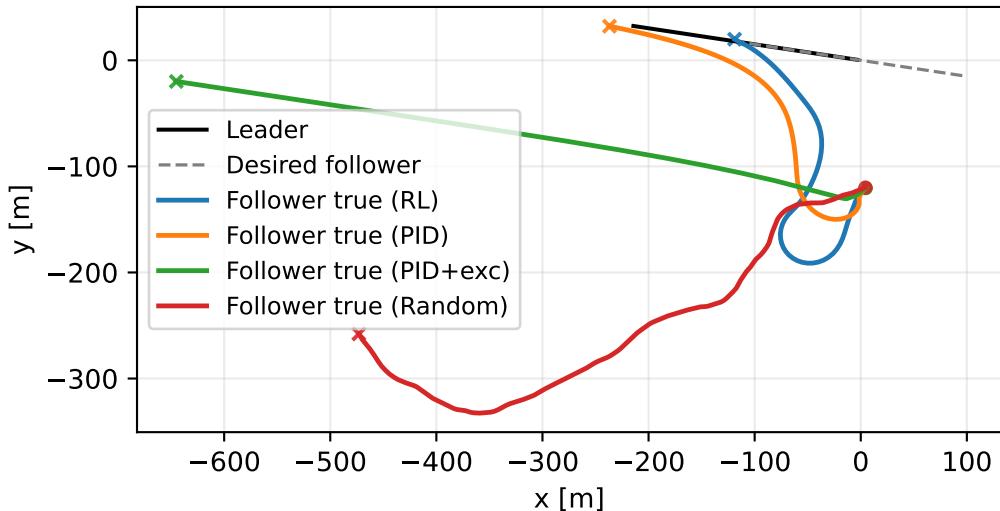
Follower course/heading



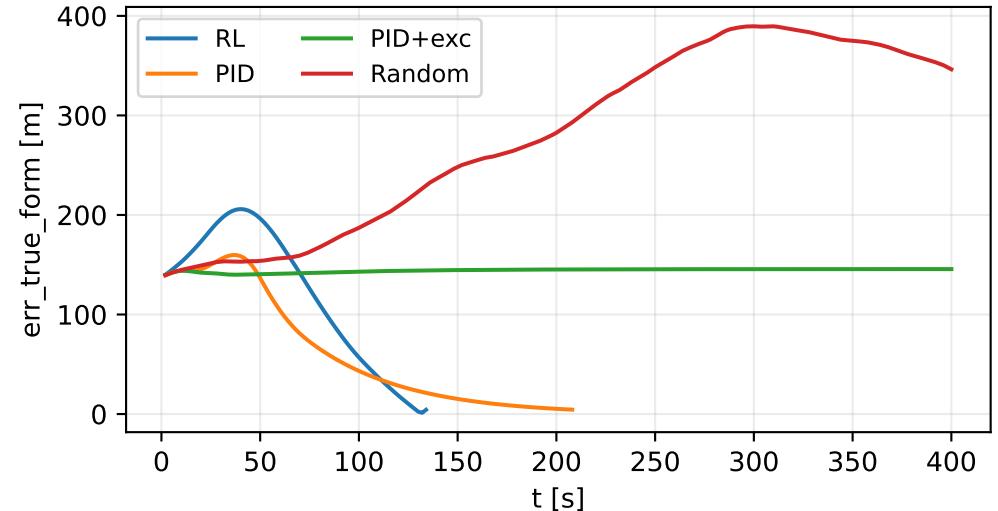
Follower angular rate



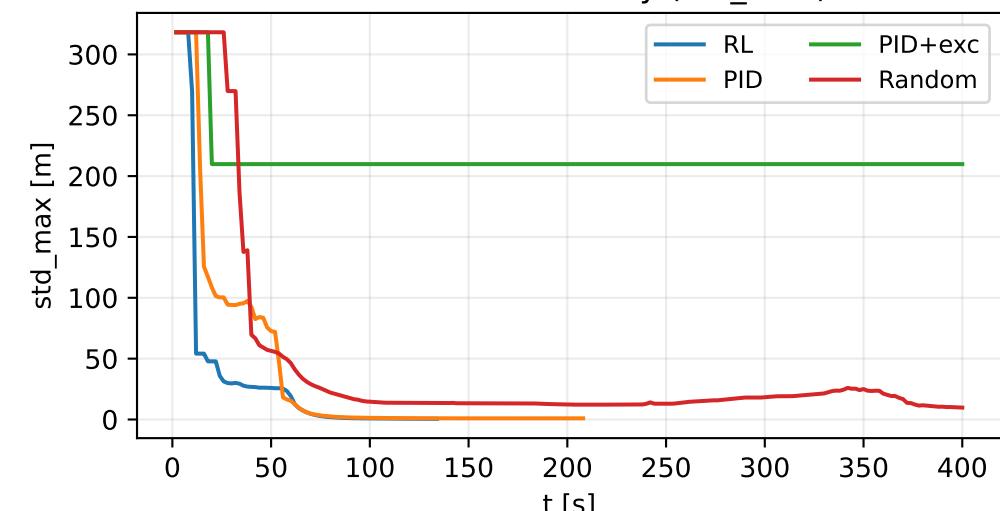
Trajectories (matched seed)



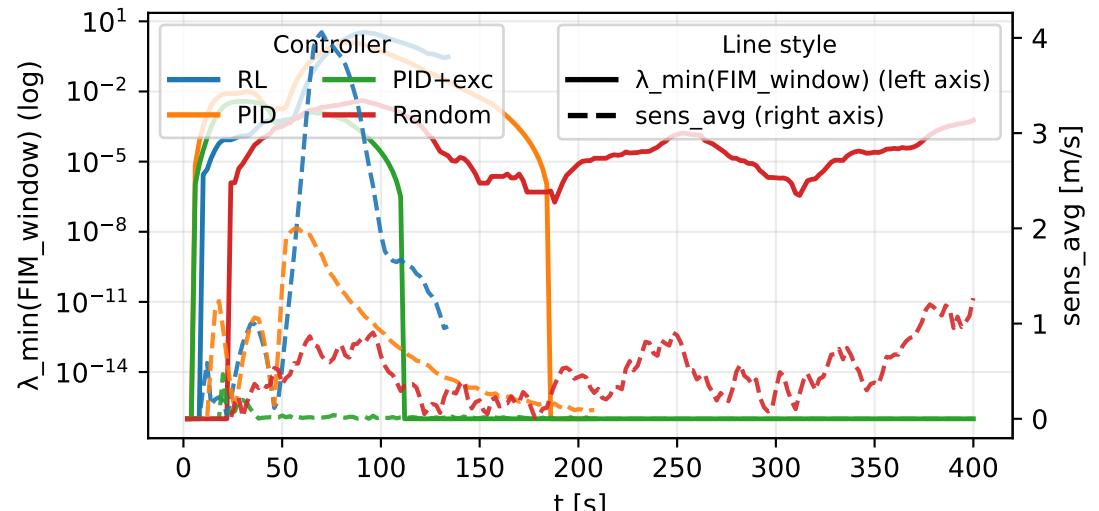
TRUE formation error



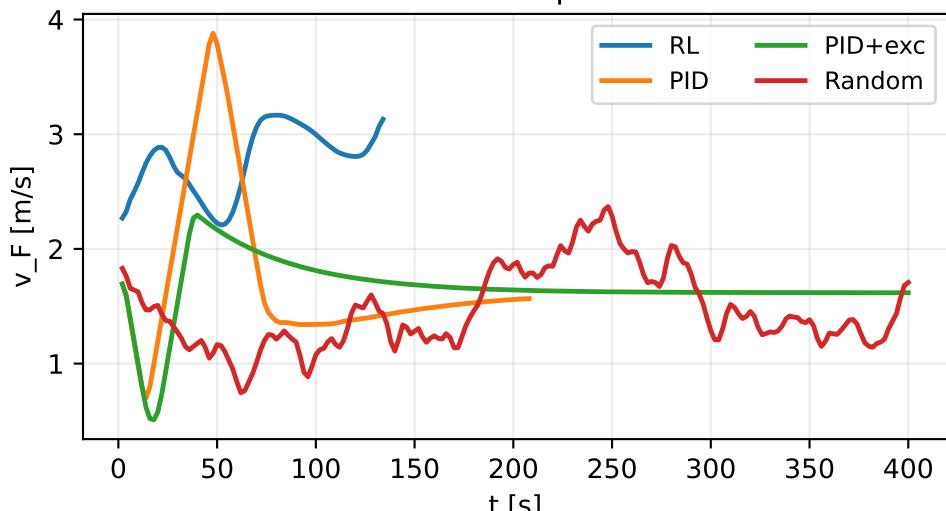
Estimator uncertainty (std_max)



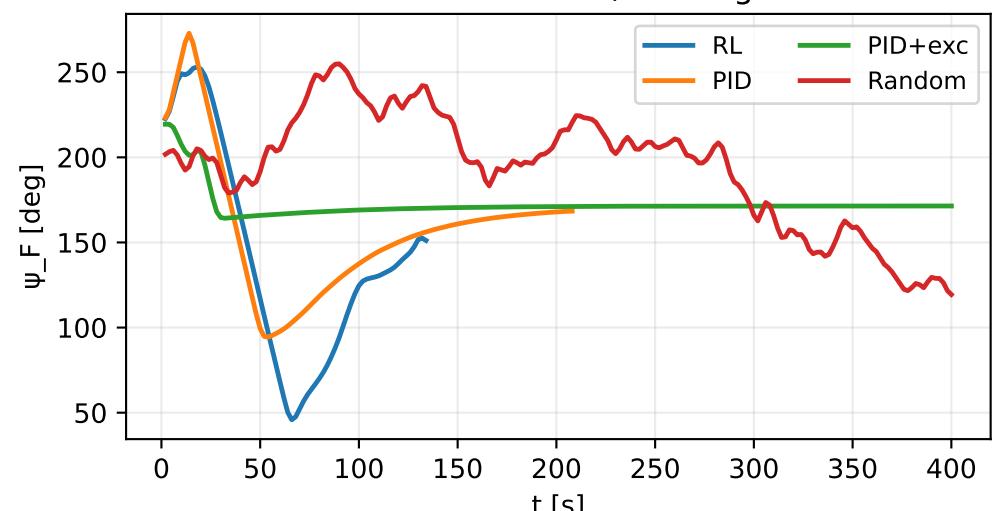
Information and excitation



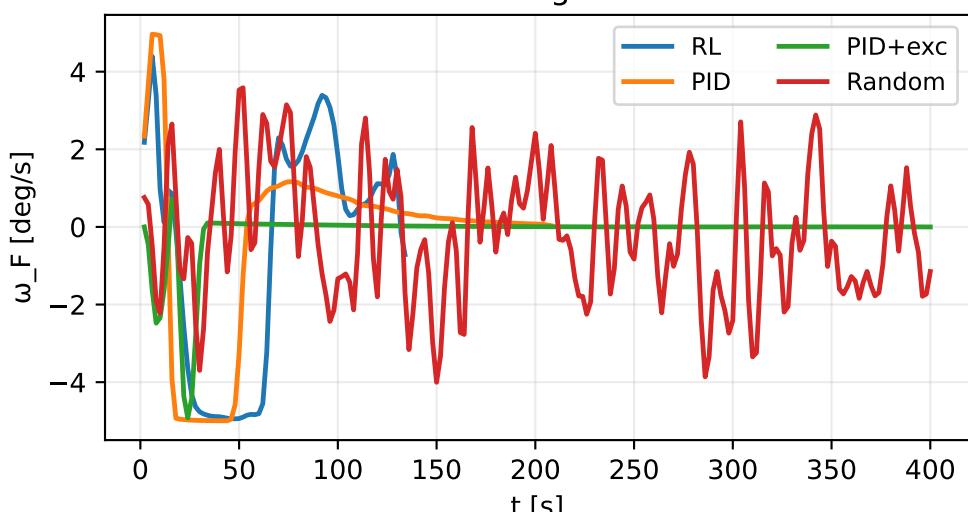
Follower speed



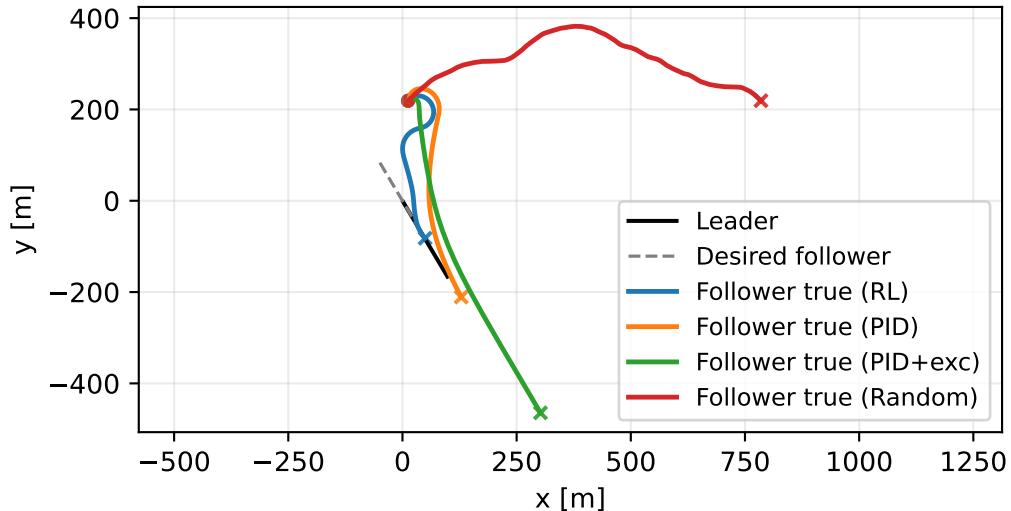
Follower course/heading



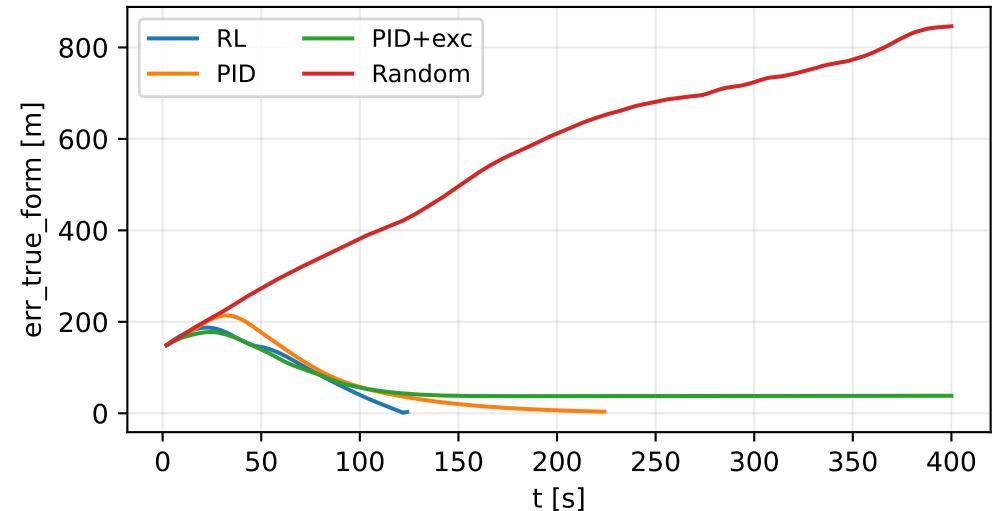
Follower angular rate



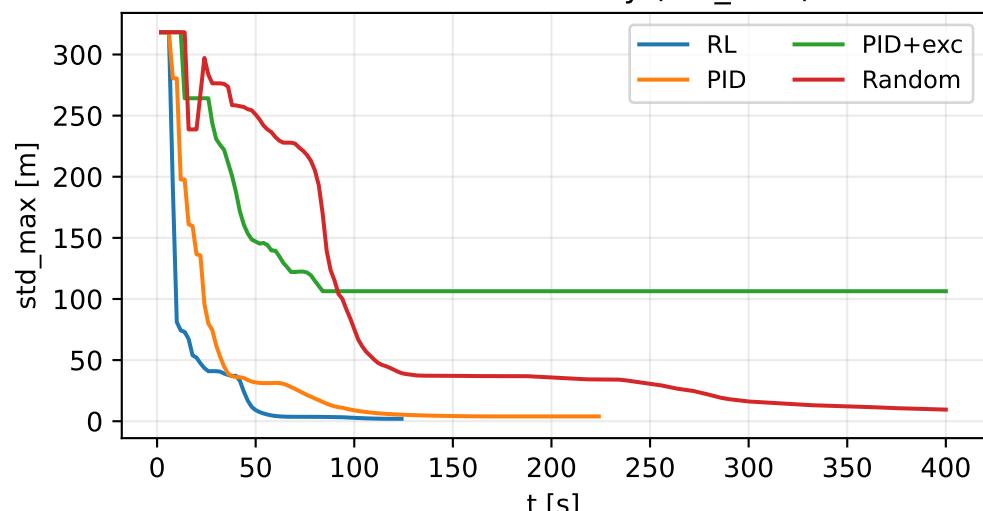
Trajectories (matched seed)



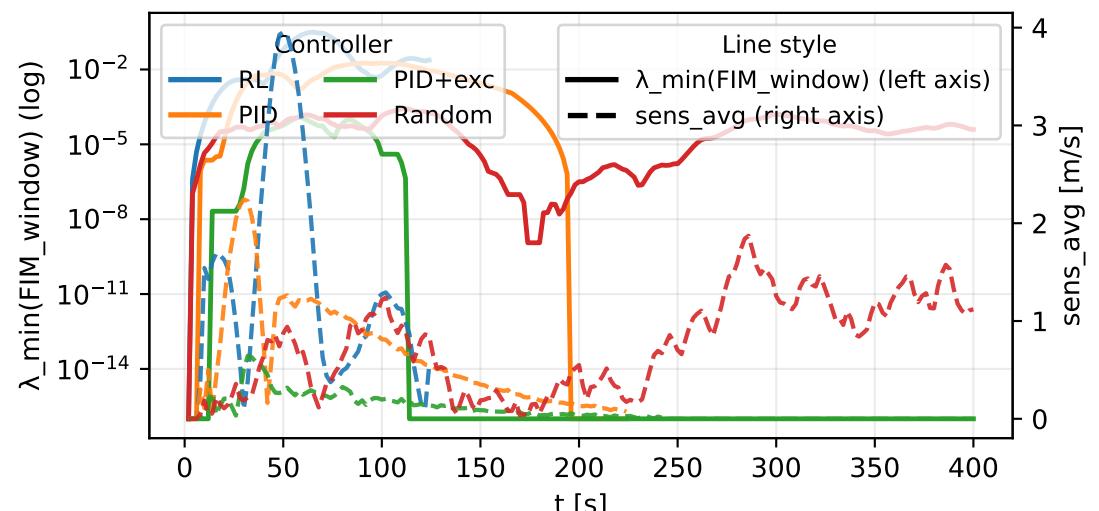
TRUE formation error



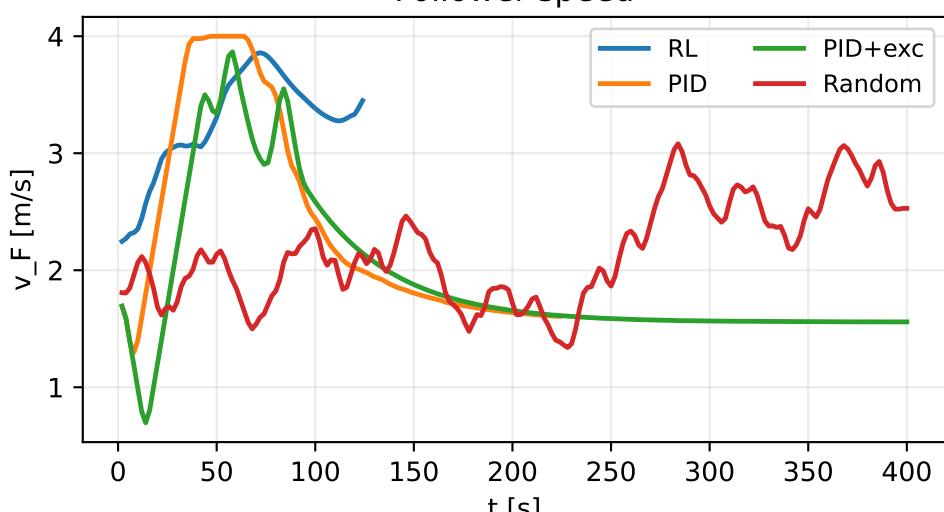
Estimator uncertainty (std_max)



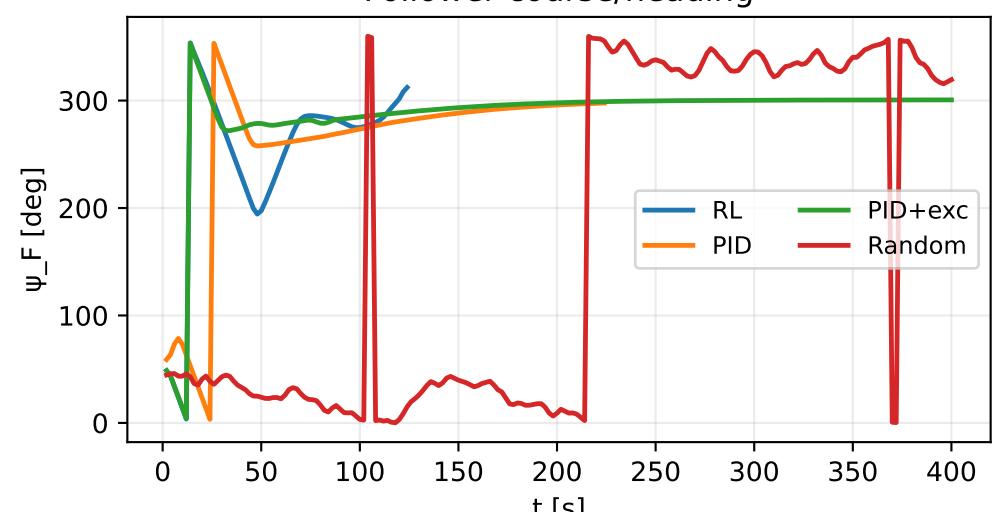
Information and excitation



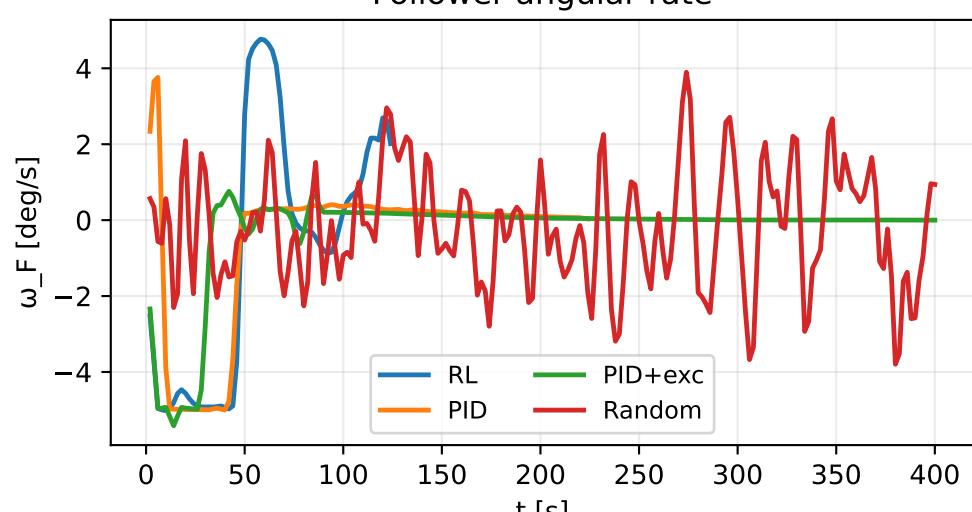
Follower speed



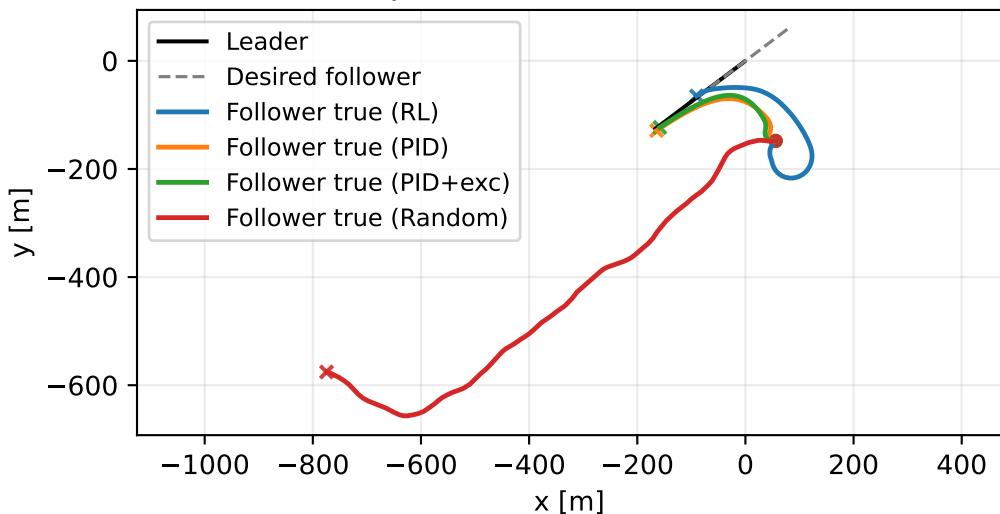
Follower course/heading



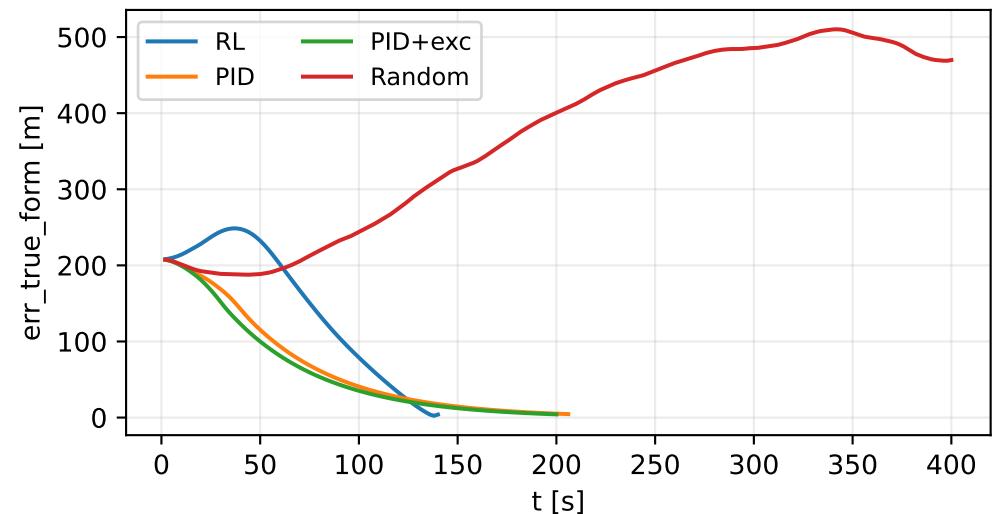
Follower angular rate



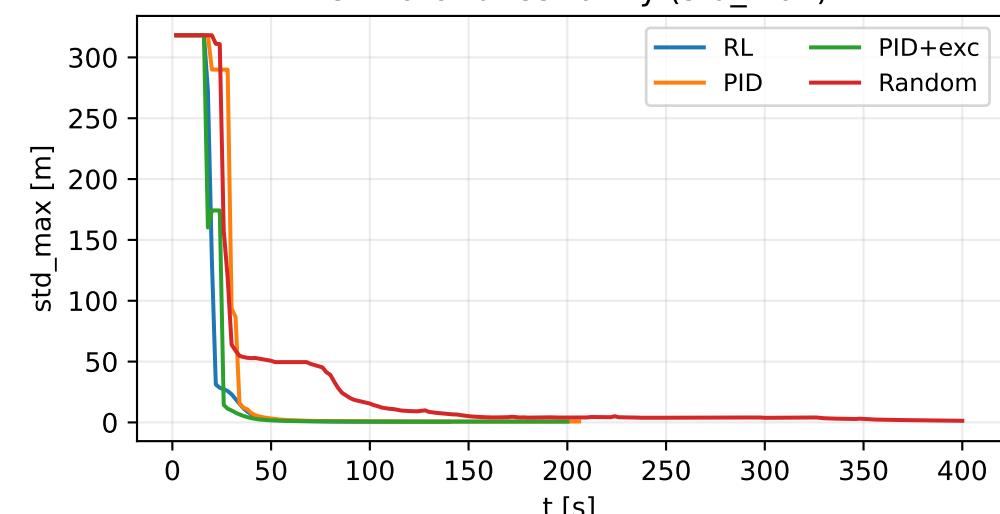
Trajectories (matched seed)



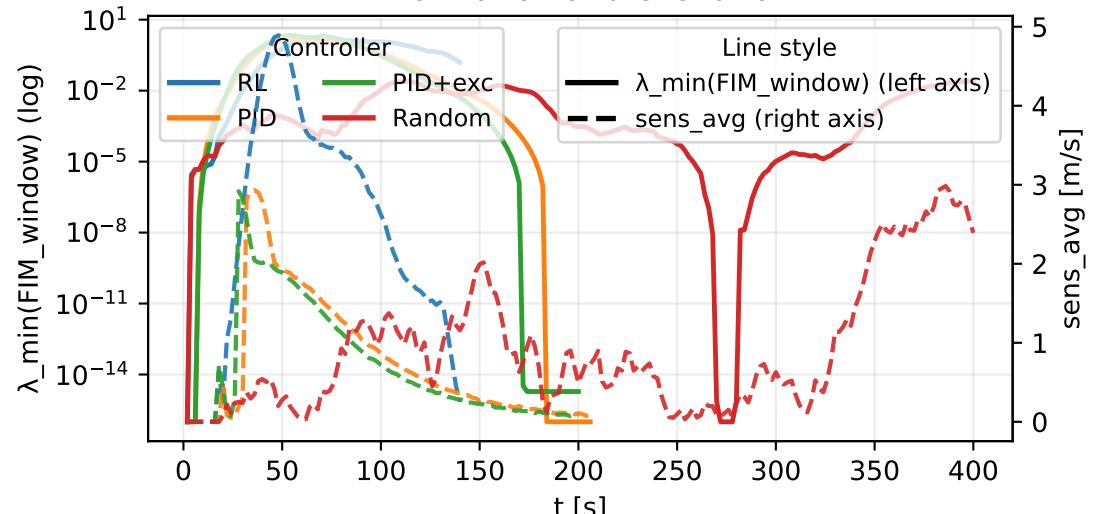
TRUE formation error



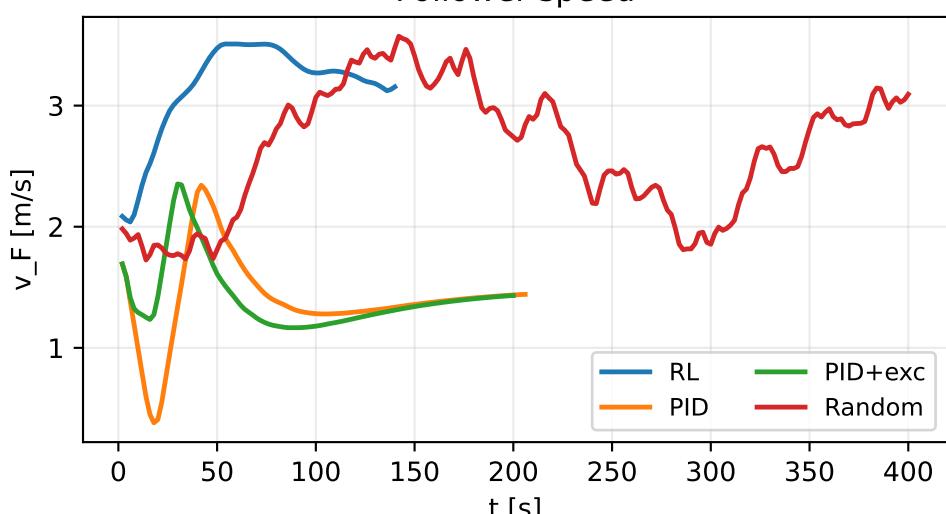
Estimator uncertainty (std_max)



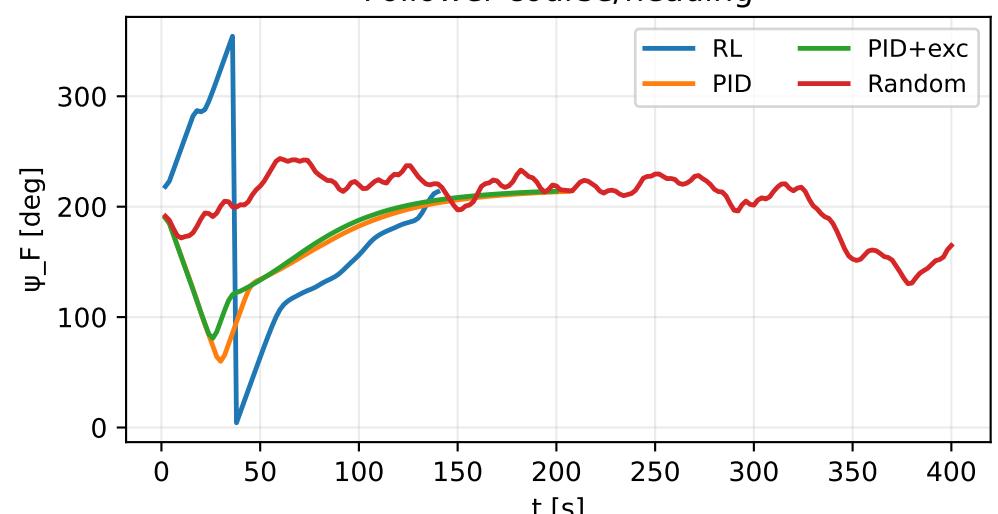
Information and excitation



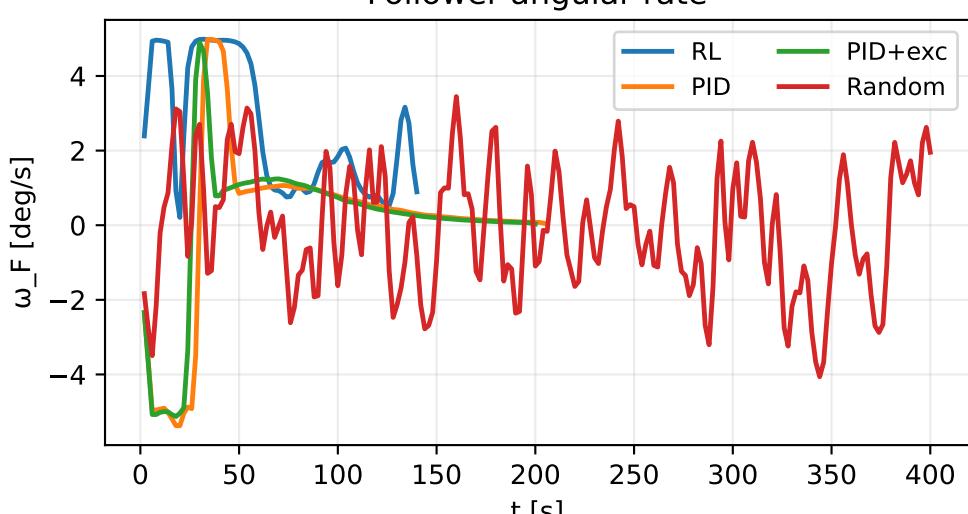
Follower speed



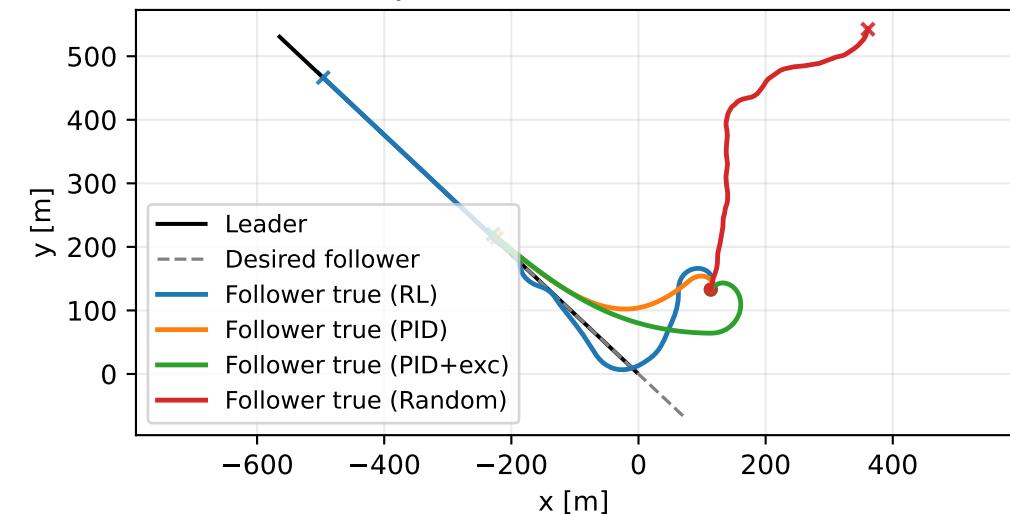
Follower course/heading



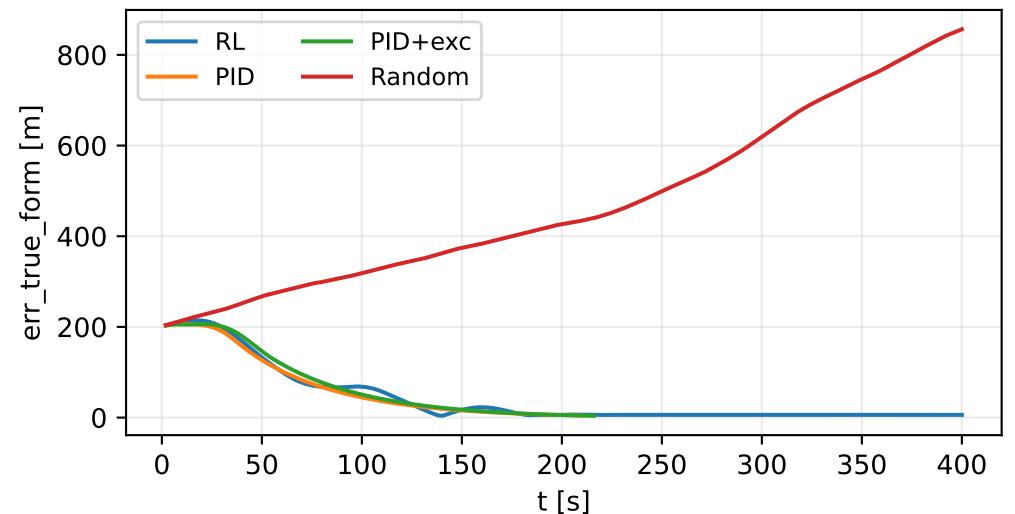
Follower angular rate



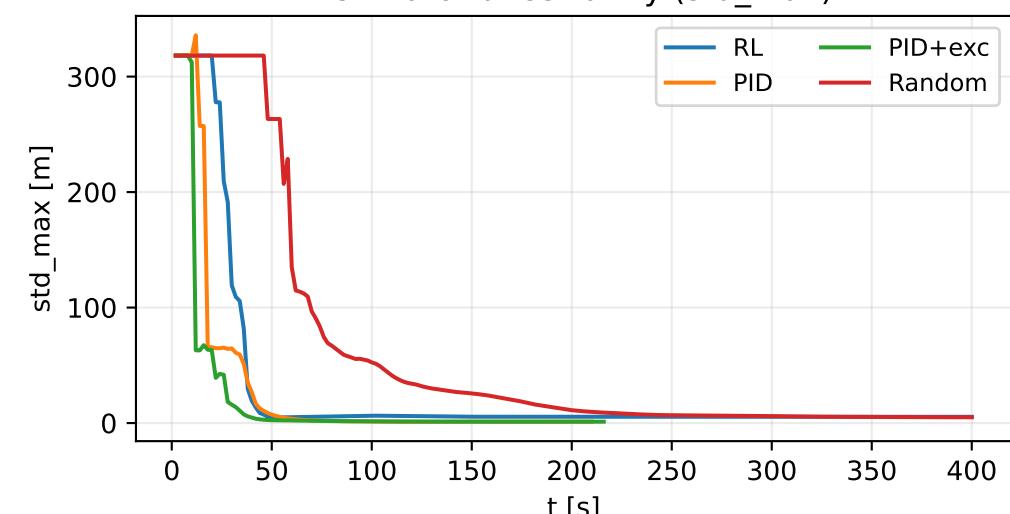
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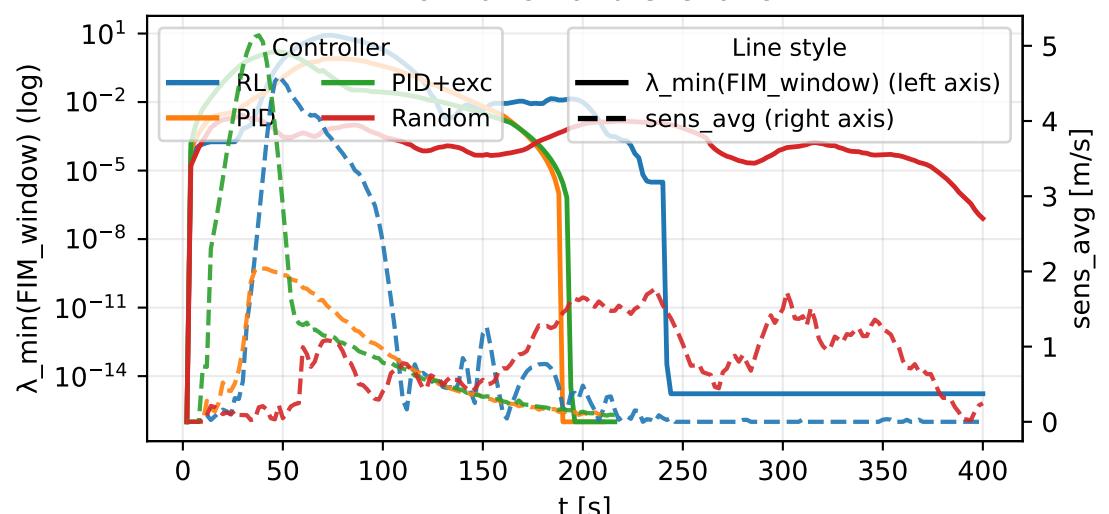
TRUE formation error



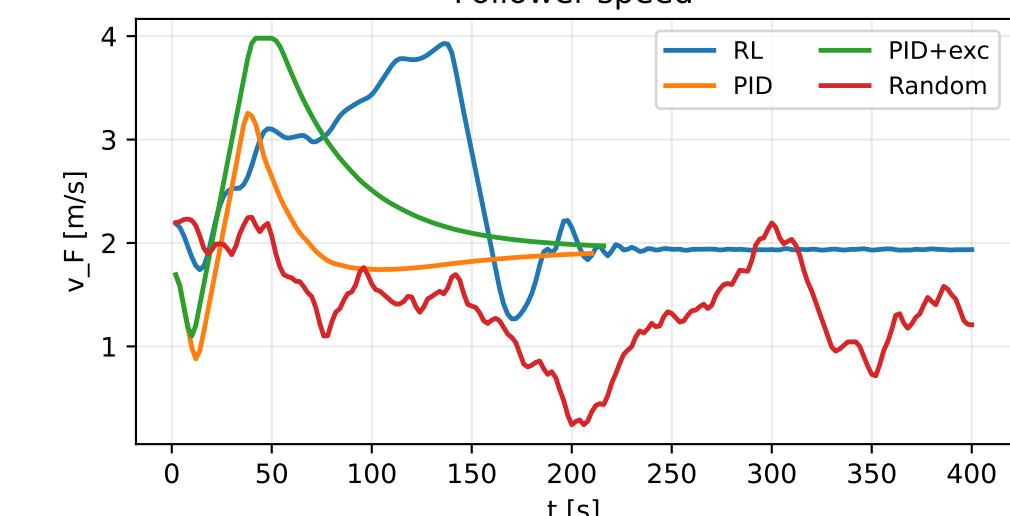
Estimator uncertainty (std_max)



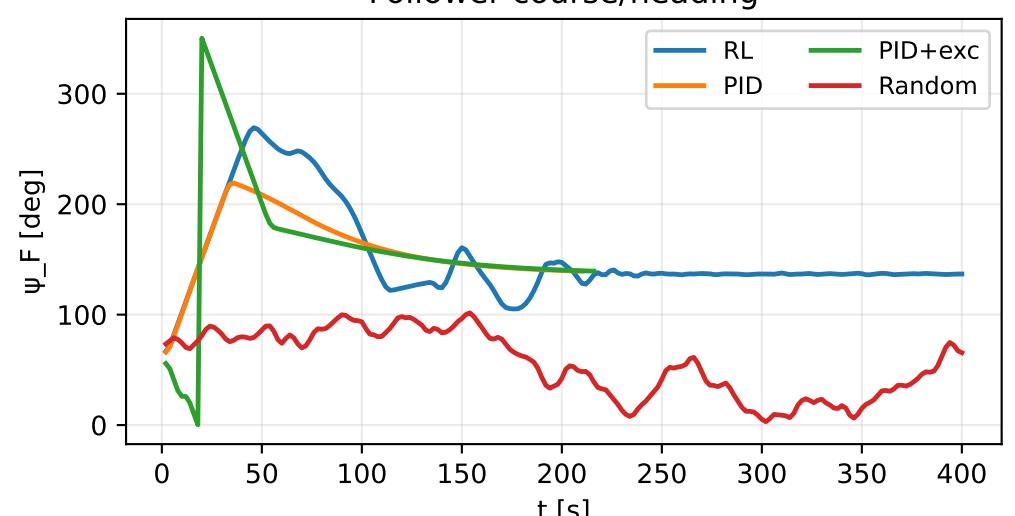
Information and excitation



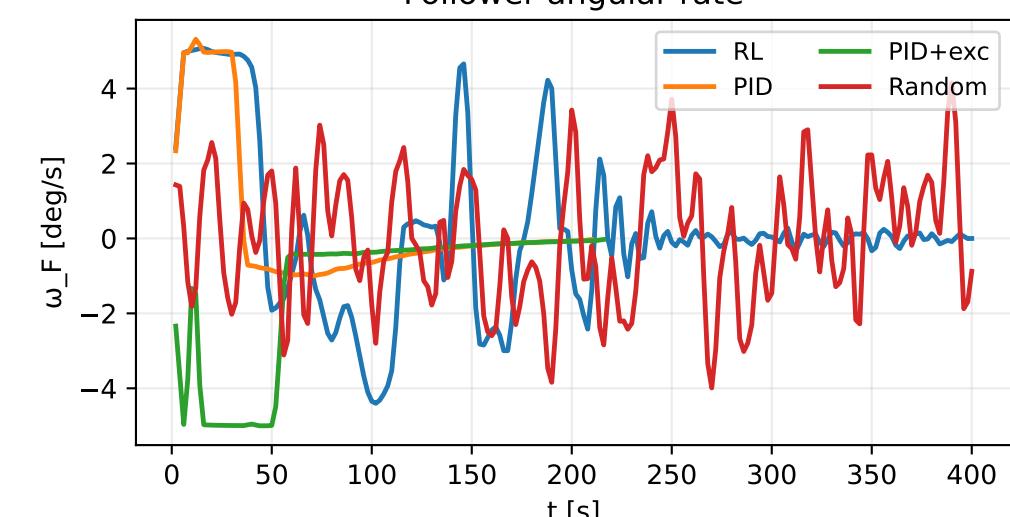
Follower speed



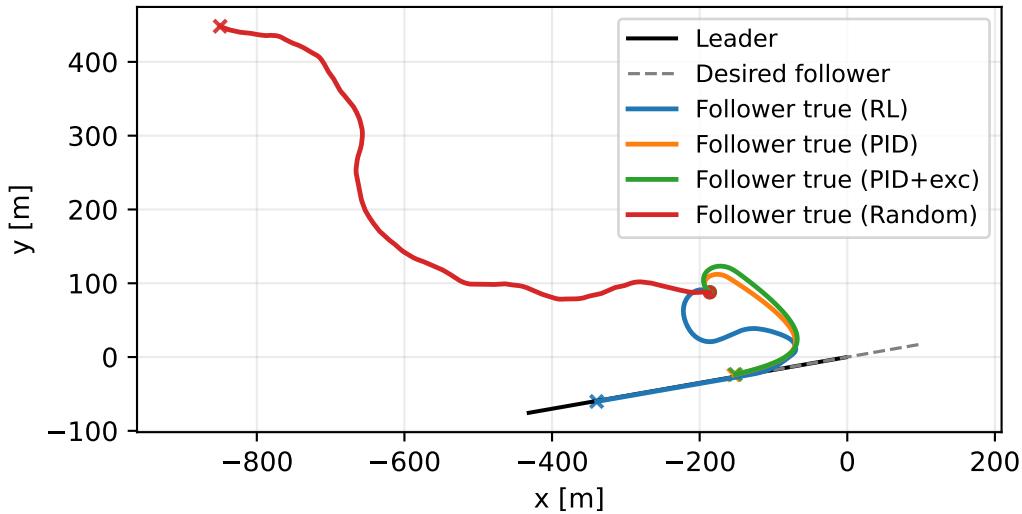
Follower course/heading



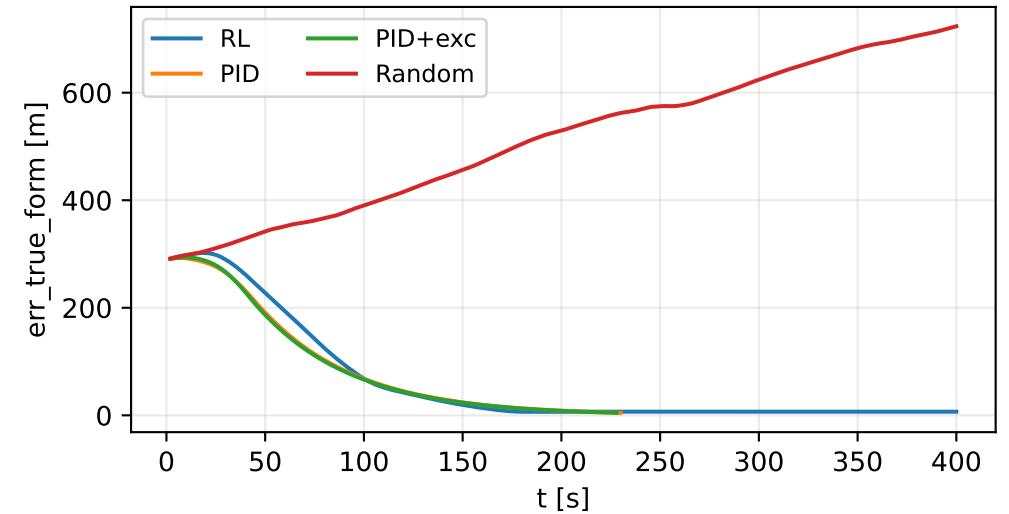
Follower angular rate



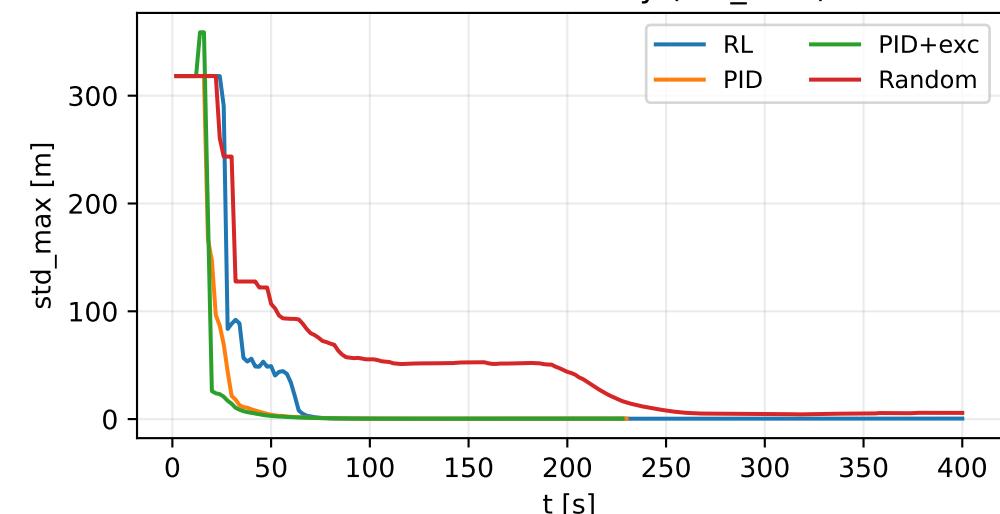
Trajectories (matched seed)



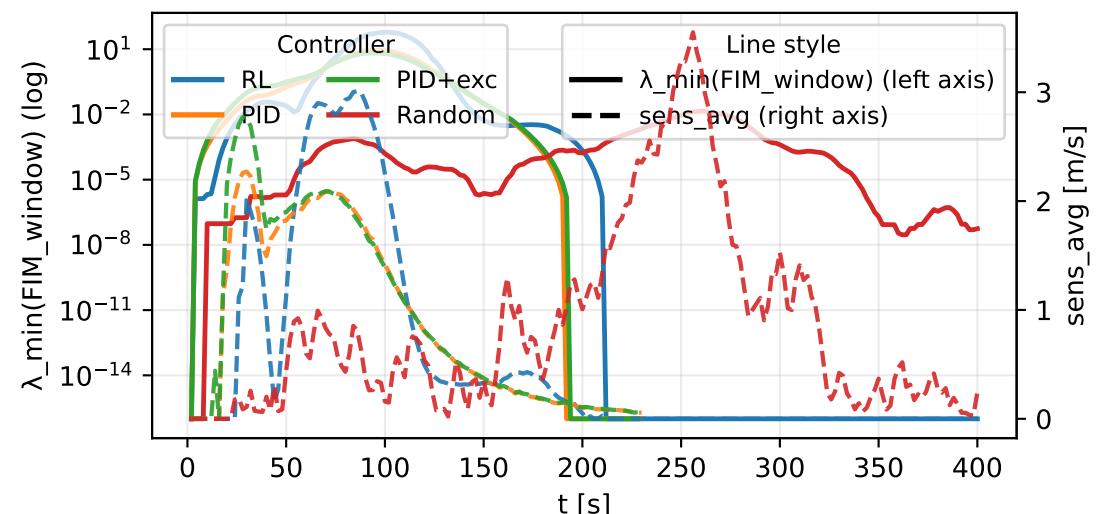
TRUE formation error



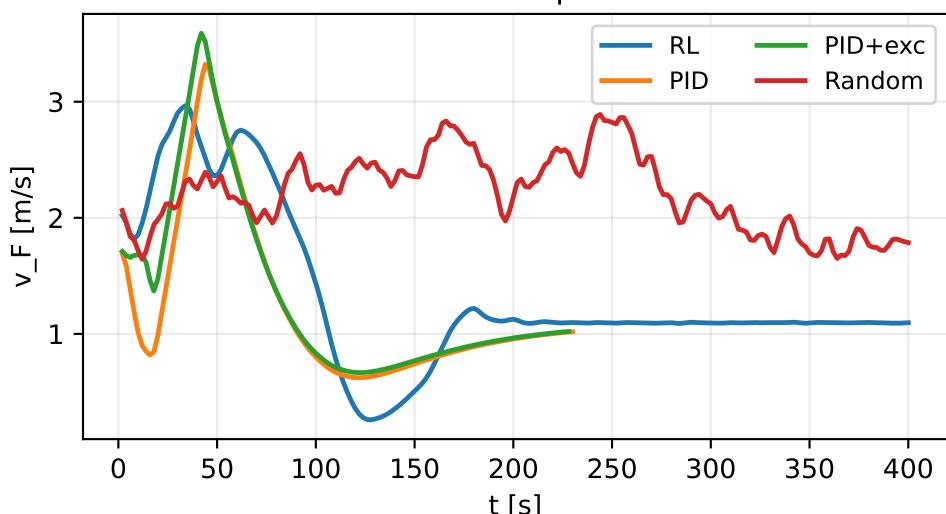
Estimator uncertainty (std_max)



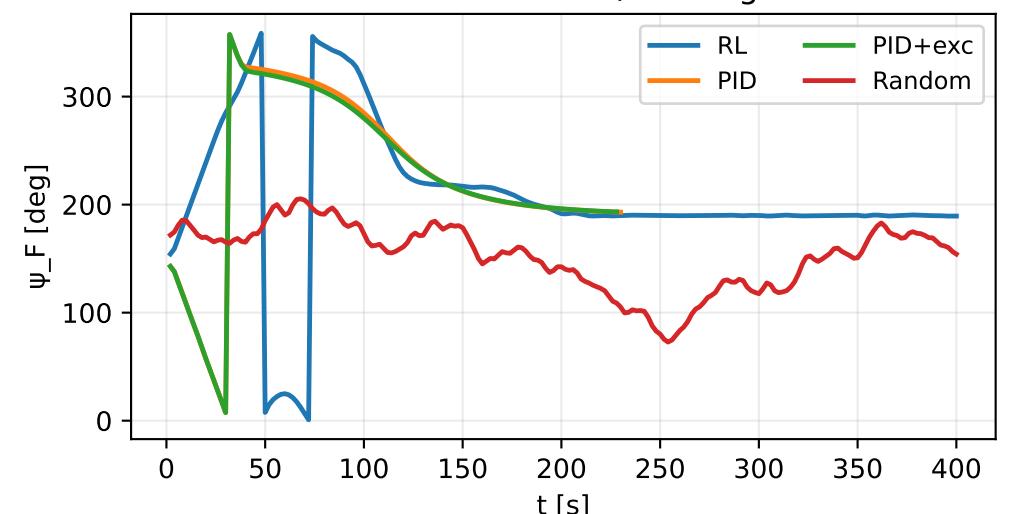
Information and excitation



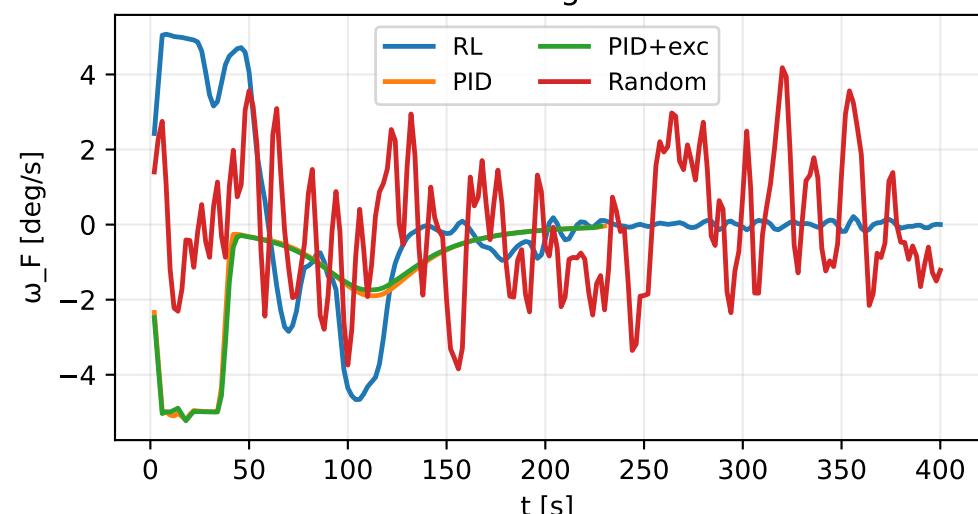
Follower speed



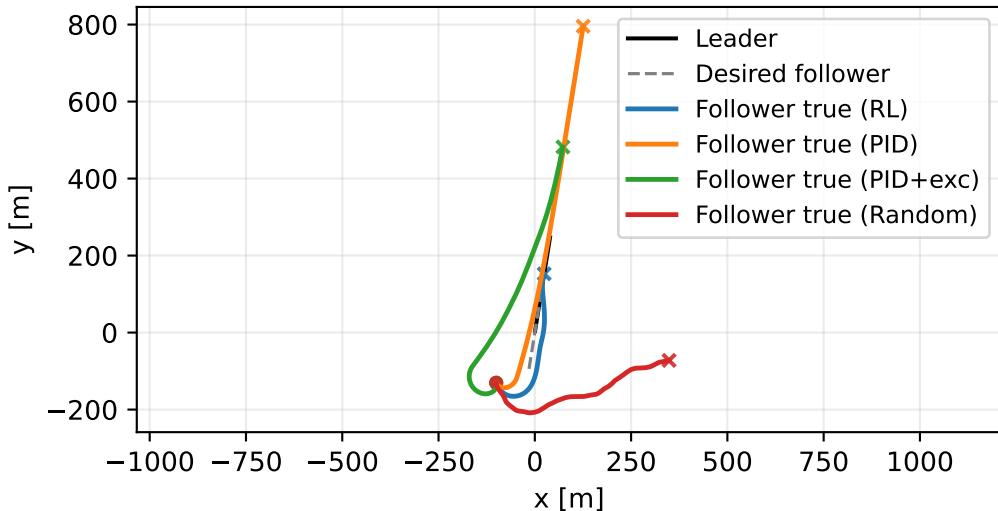
Follower course/heading



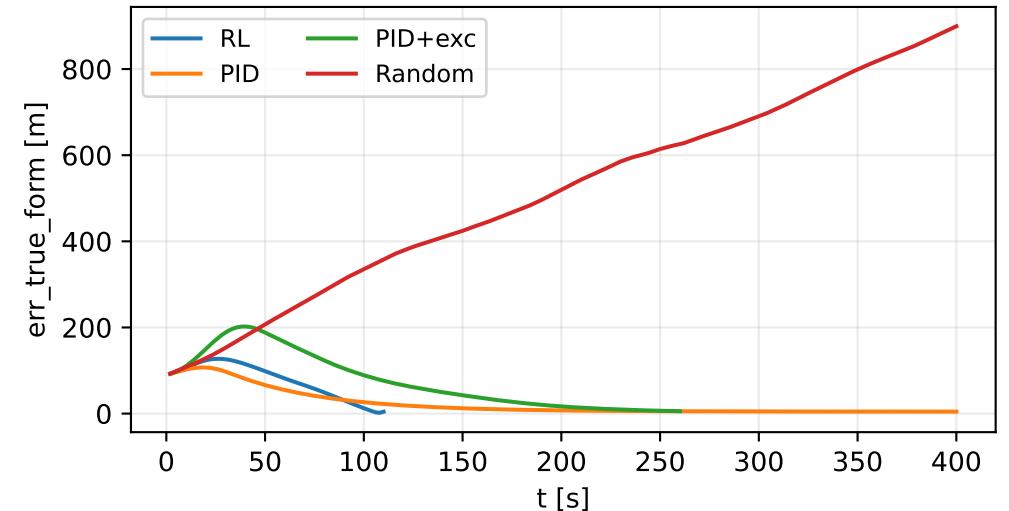
Follower angular rate



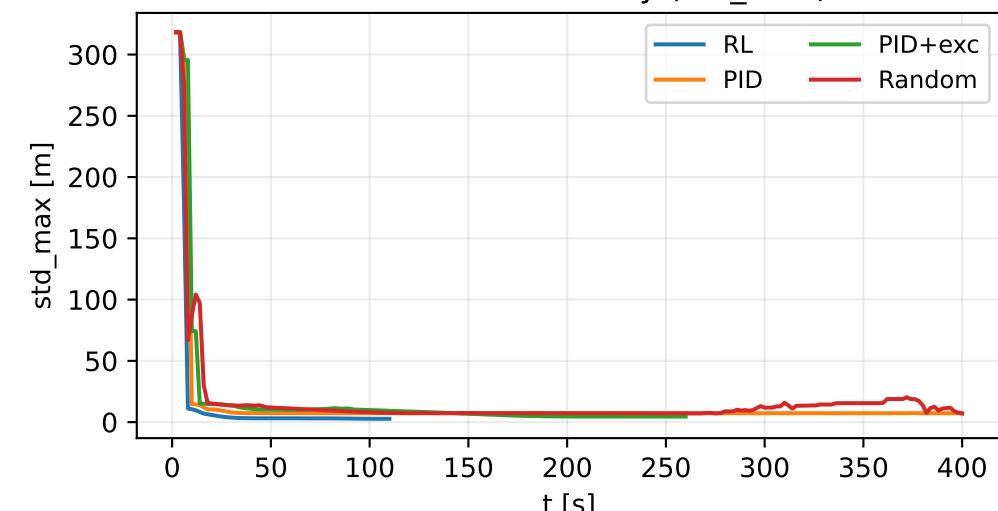
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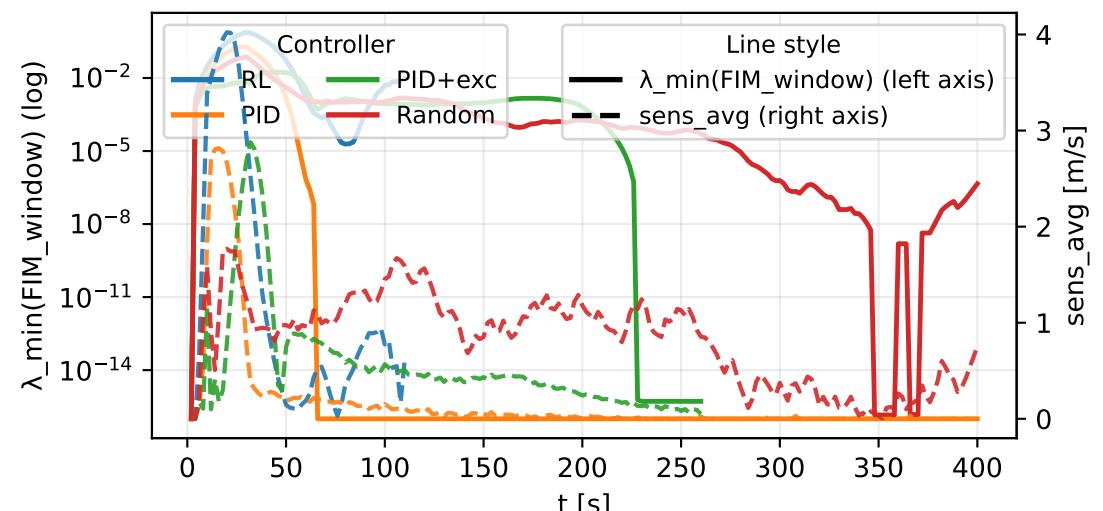
TRUE formation error



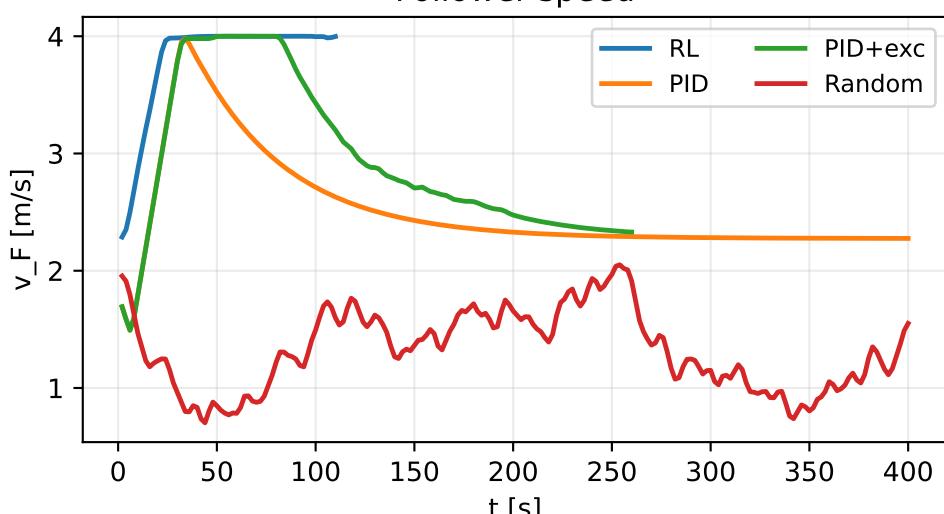
Estimator uncertainty (std_max)



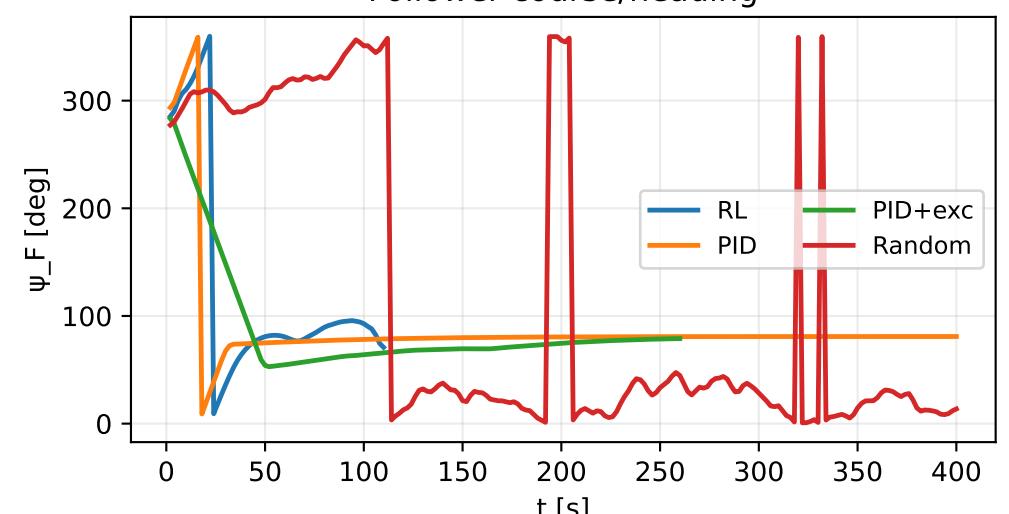
Information and excitation



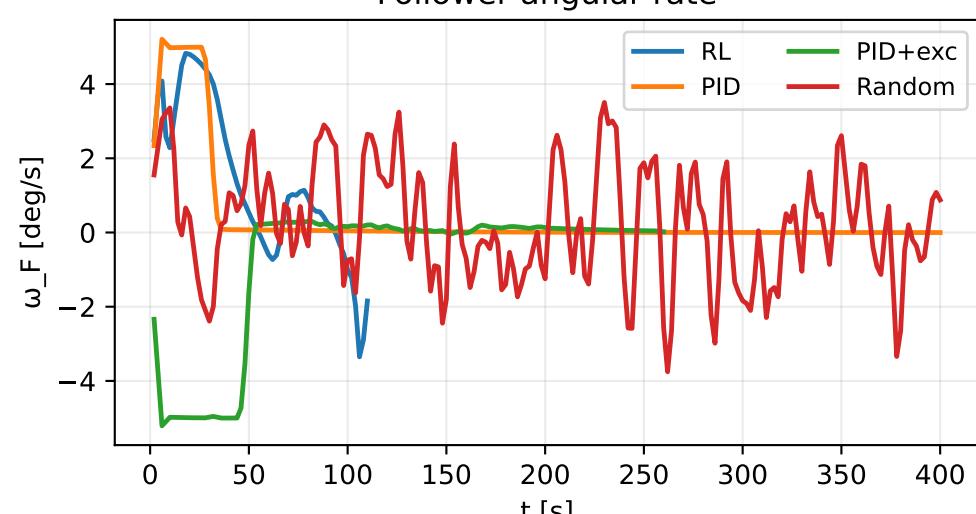
Follower speed



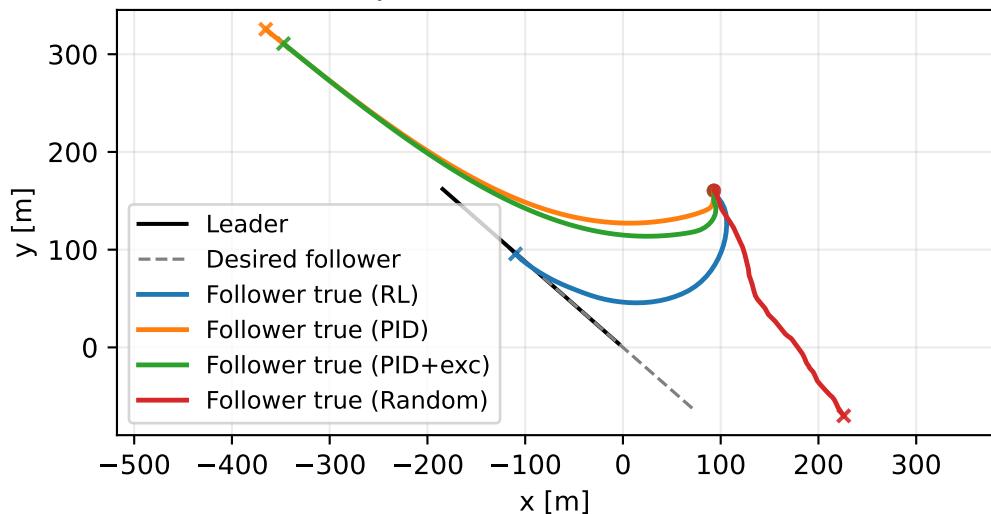
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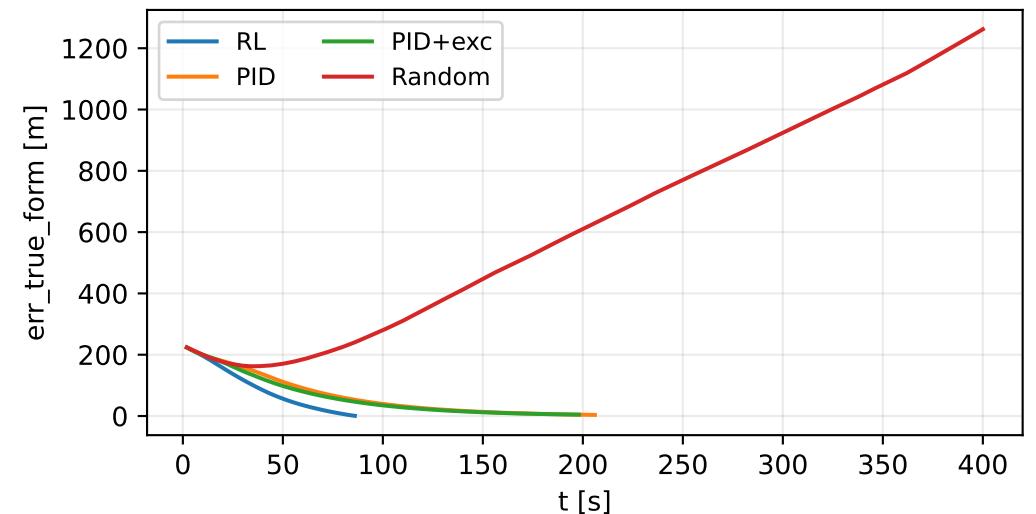
Follower angular rate



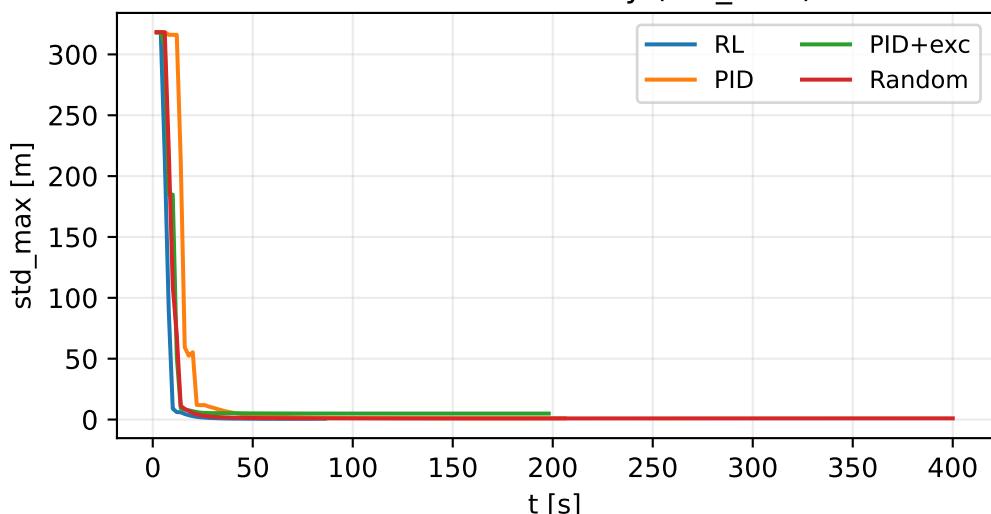
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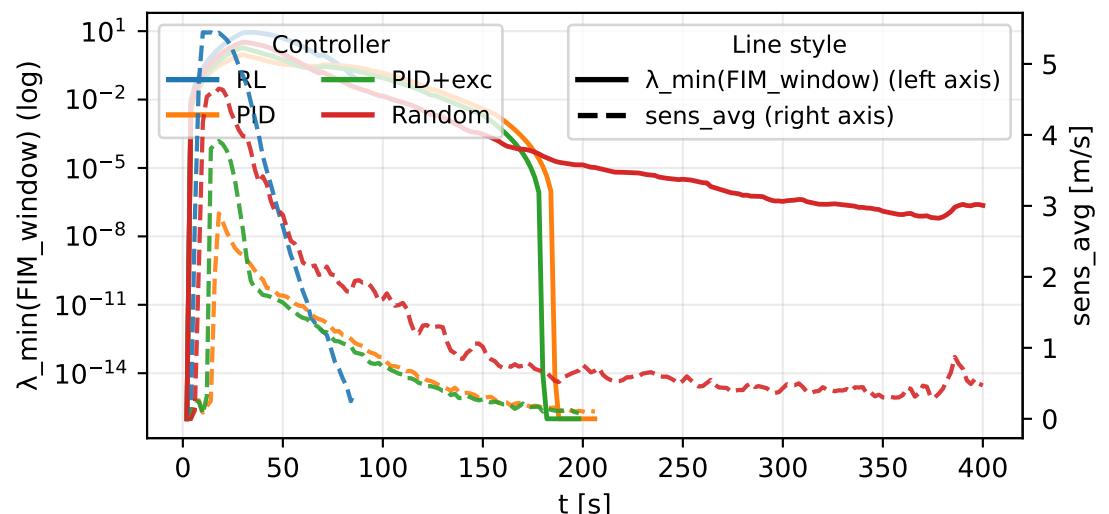
TRUE formation error



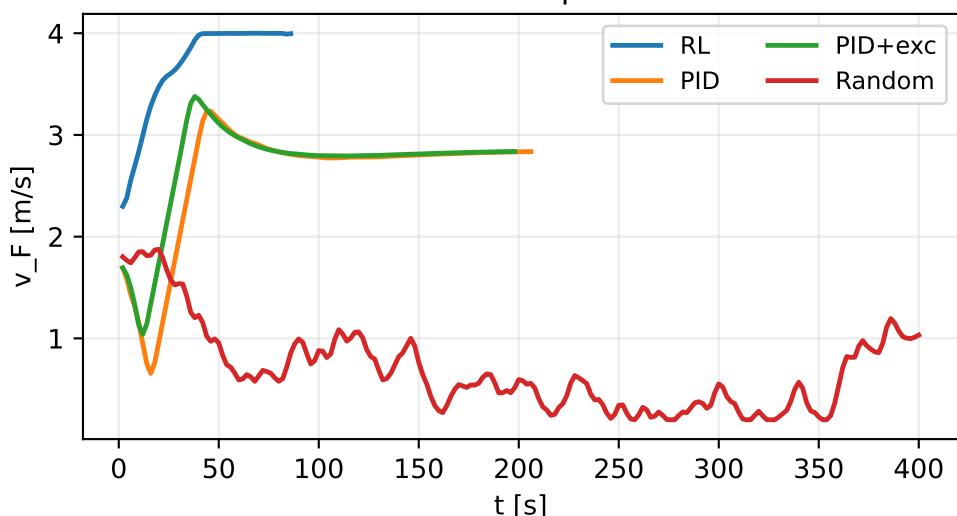
Estimator uncertainty (std_max)



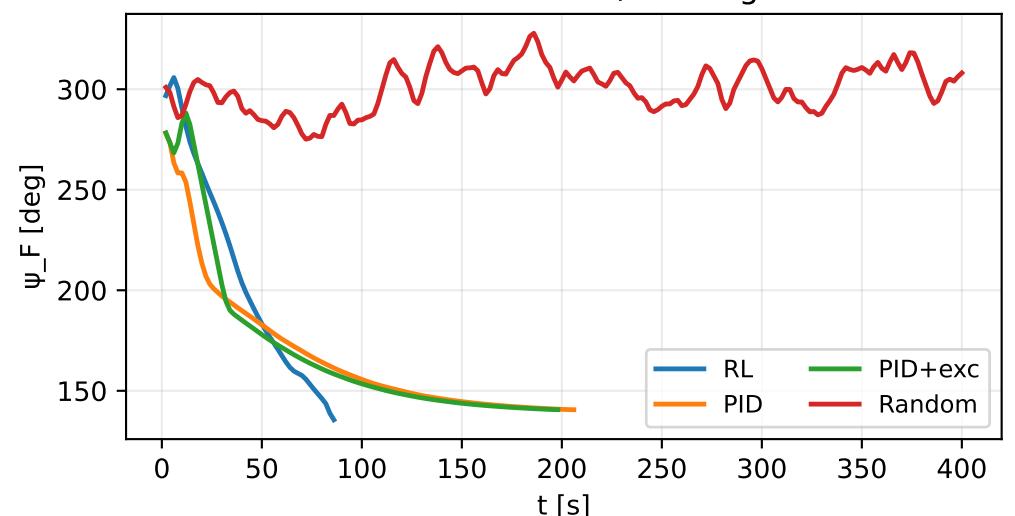
Information and excitation



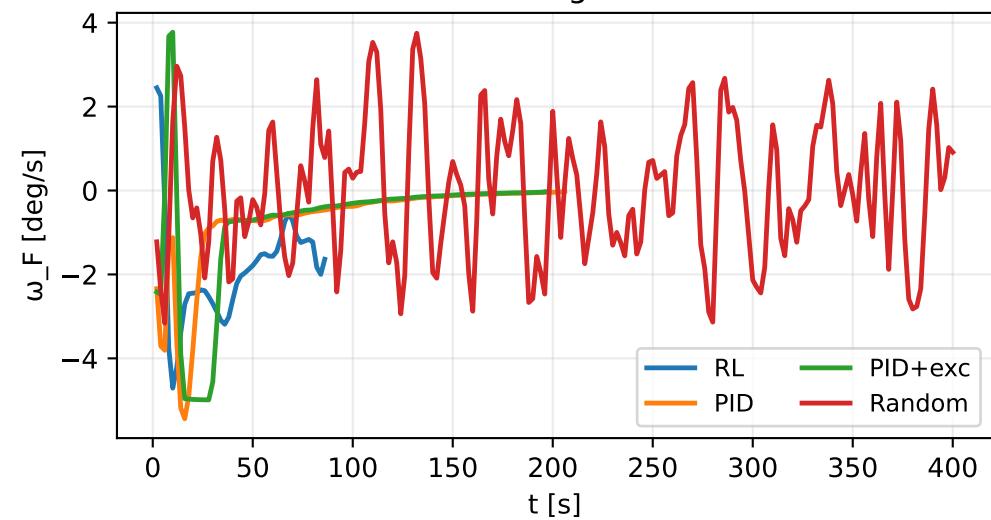
Follower speed



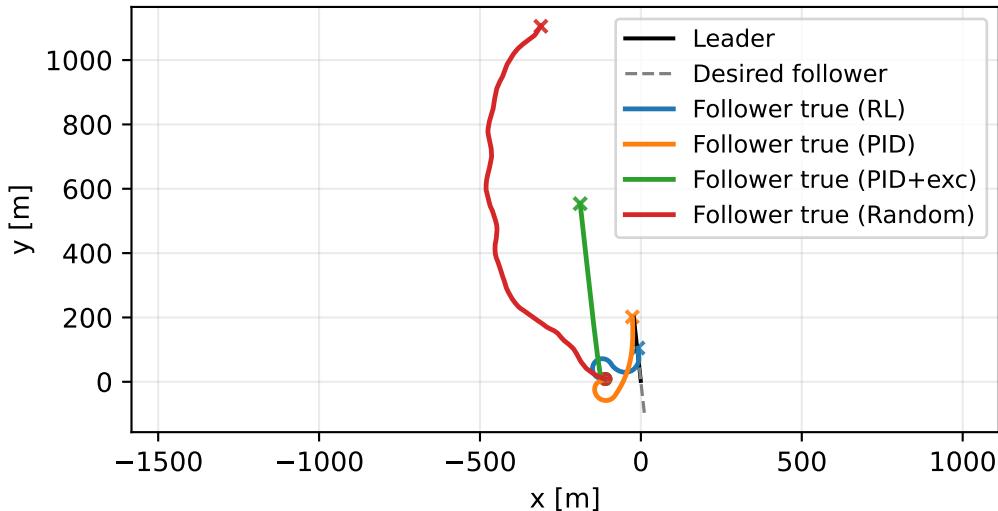
Follower course/heading



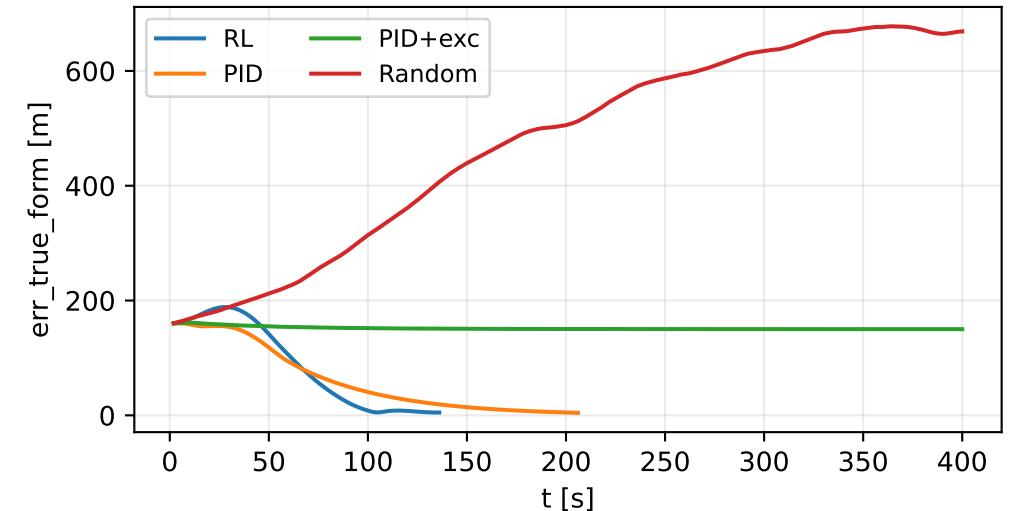
Follower angular rate



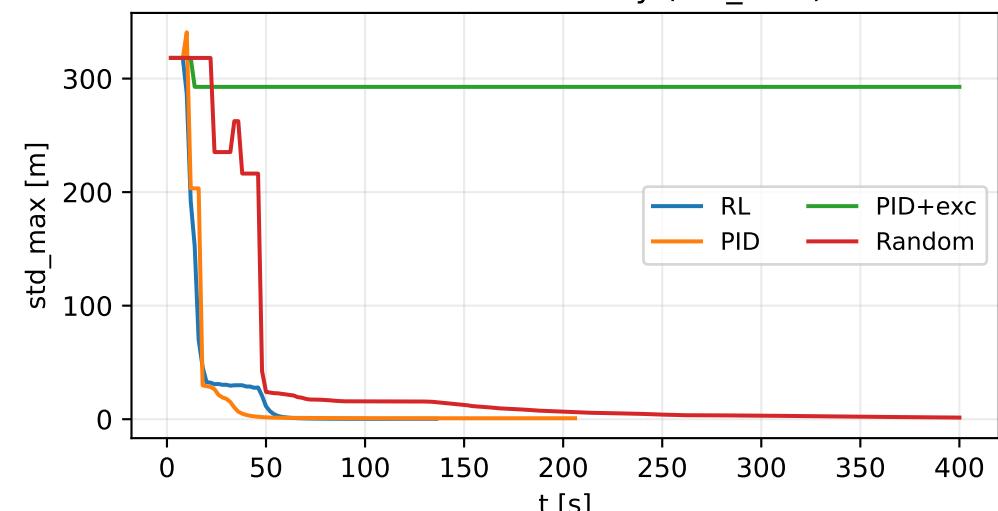
Trajectories (matched seed)



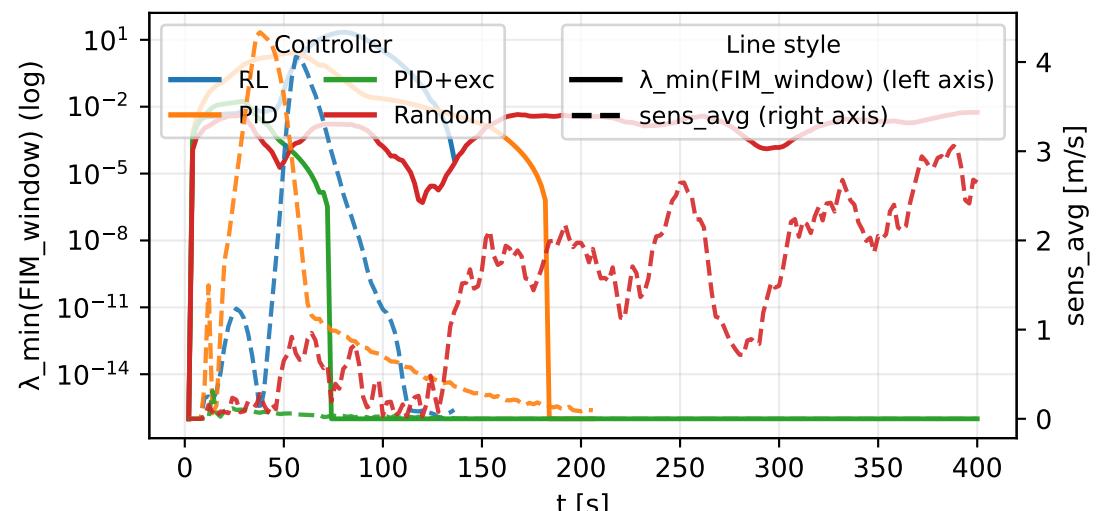
TRUE formation error



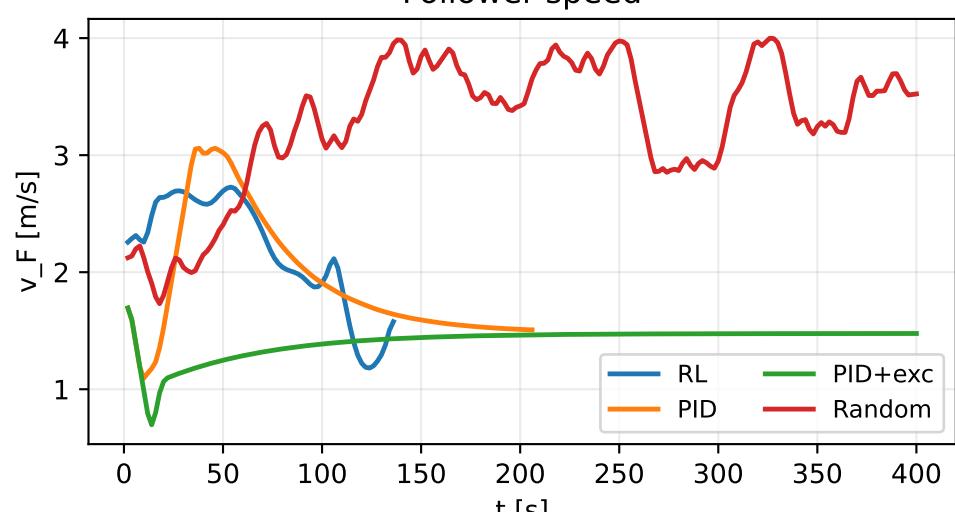
Estimator uncertainty (std_max)



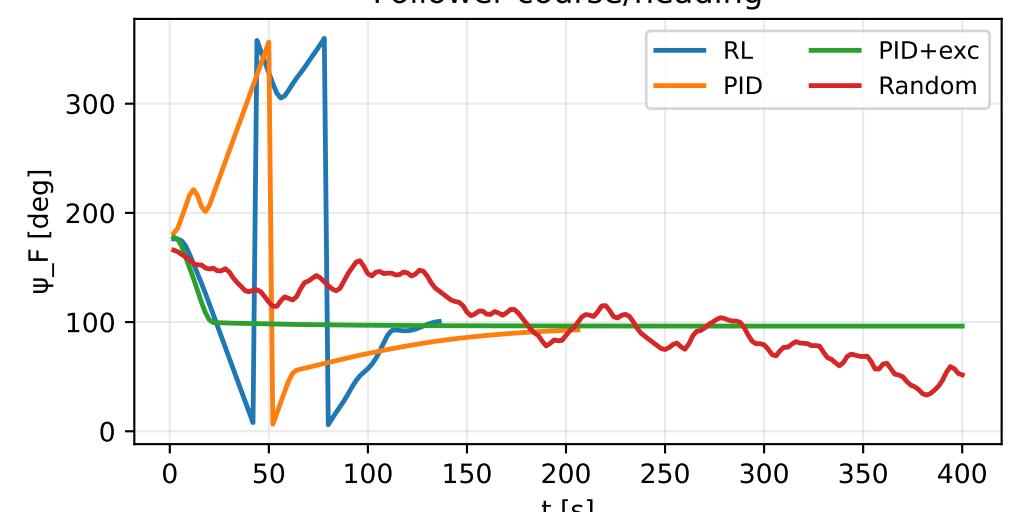
Information and excitation



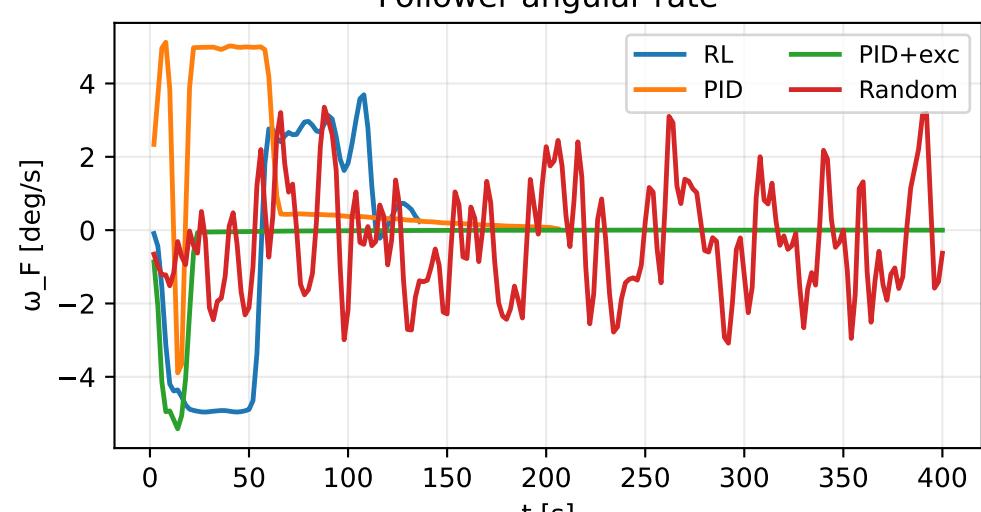
Follower speed



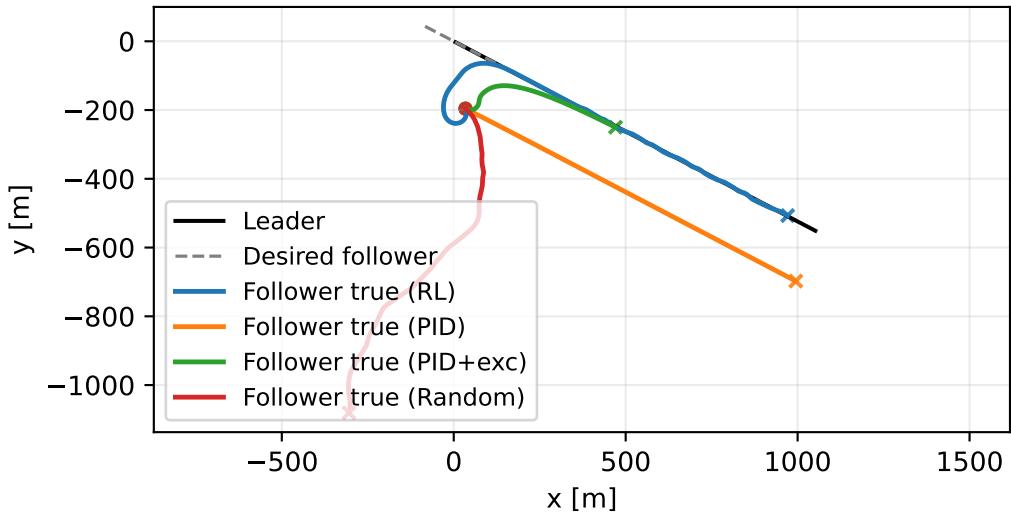
Follower course/heading



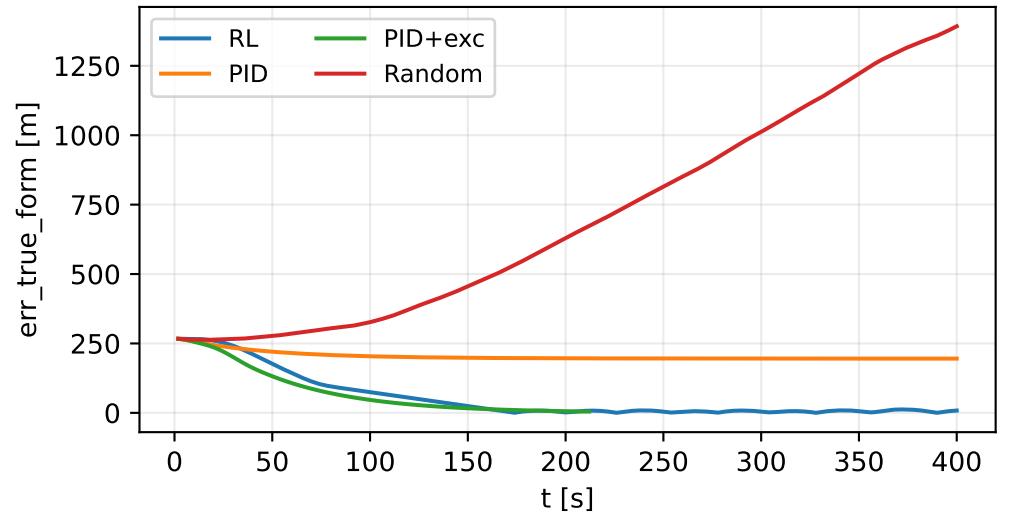
Follower angular rate



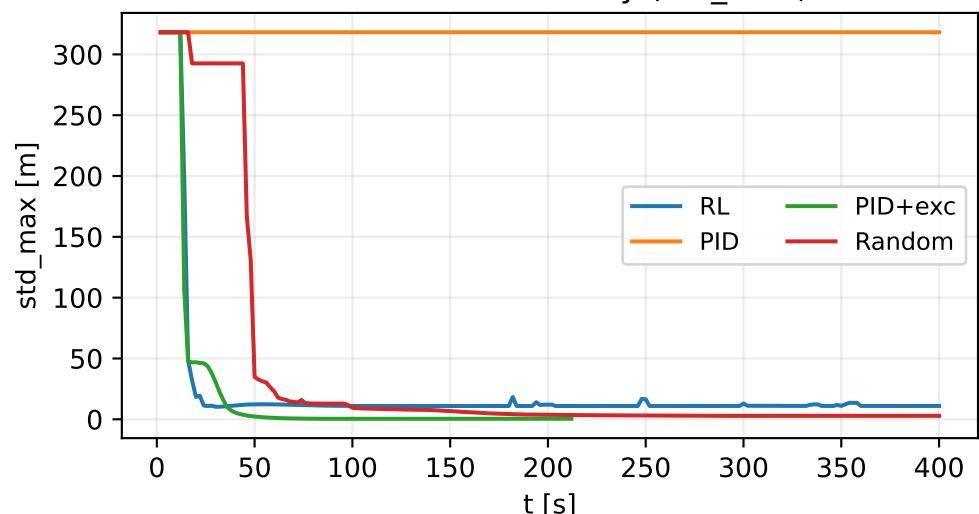
Trajectories (matched seed)



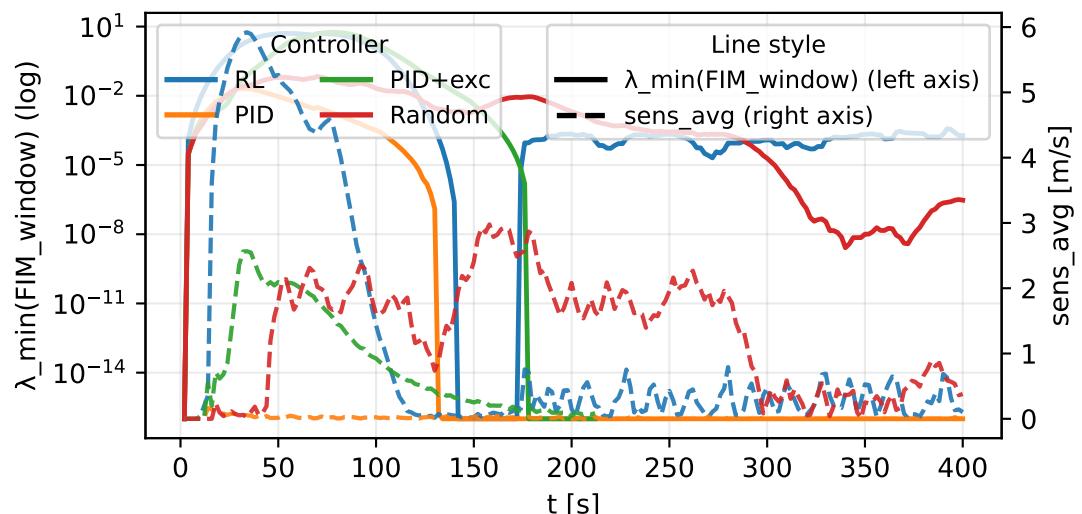
TRUE formation error



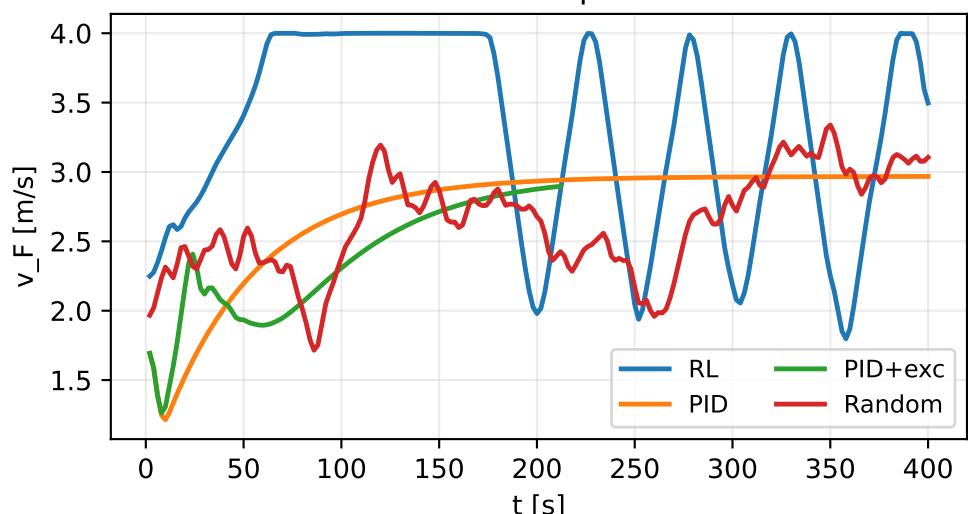
Estimator uncertainty (std_max)



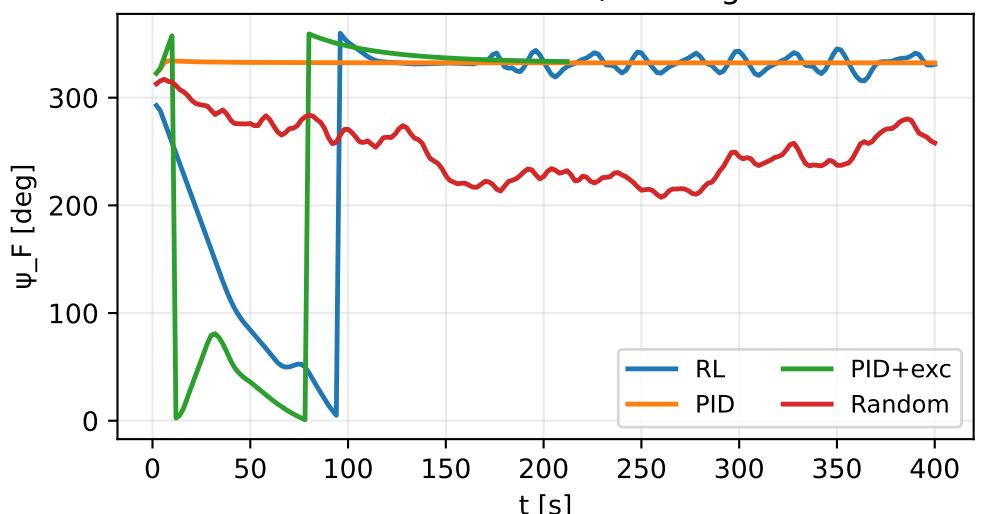
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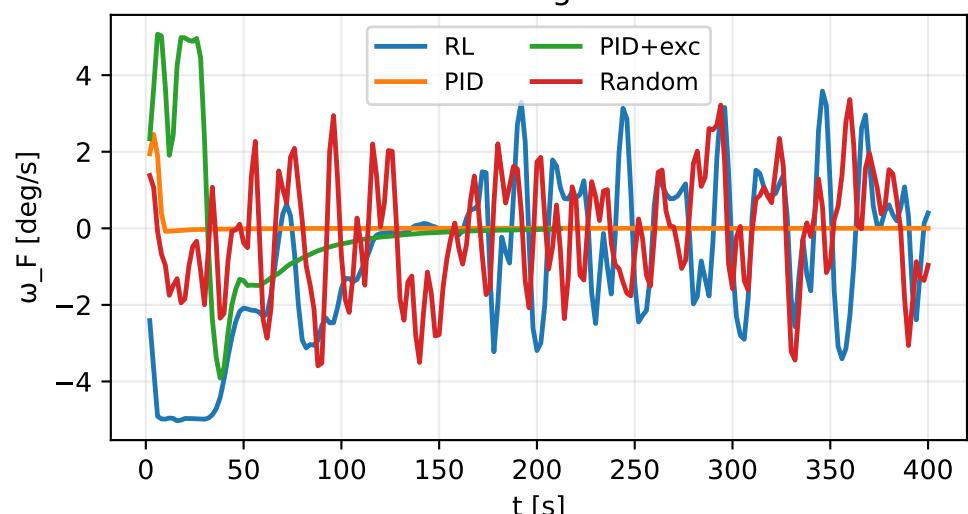
Follower speed



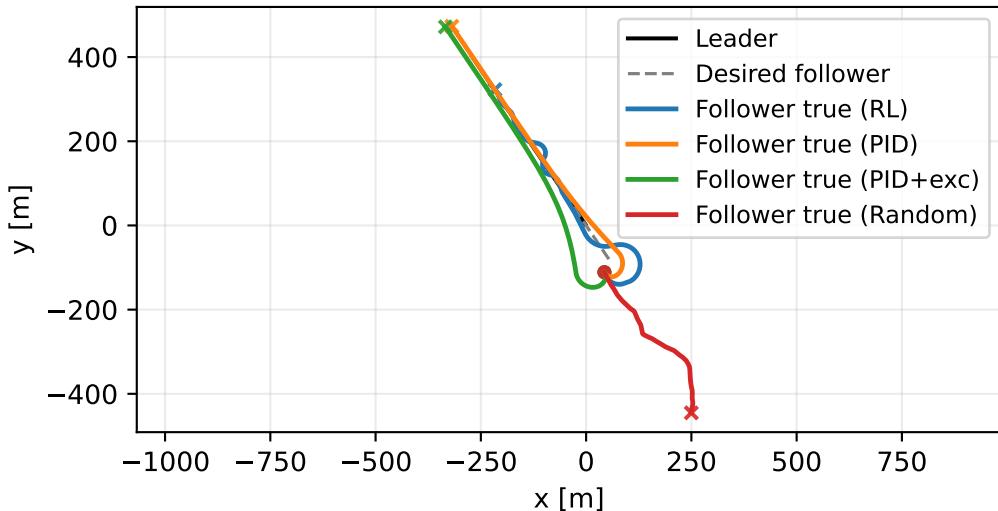
Follower course/heading



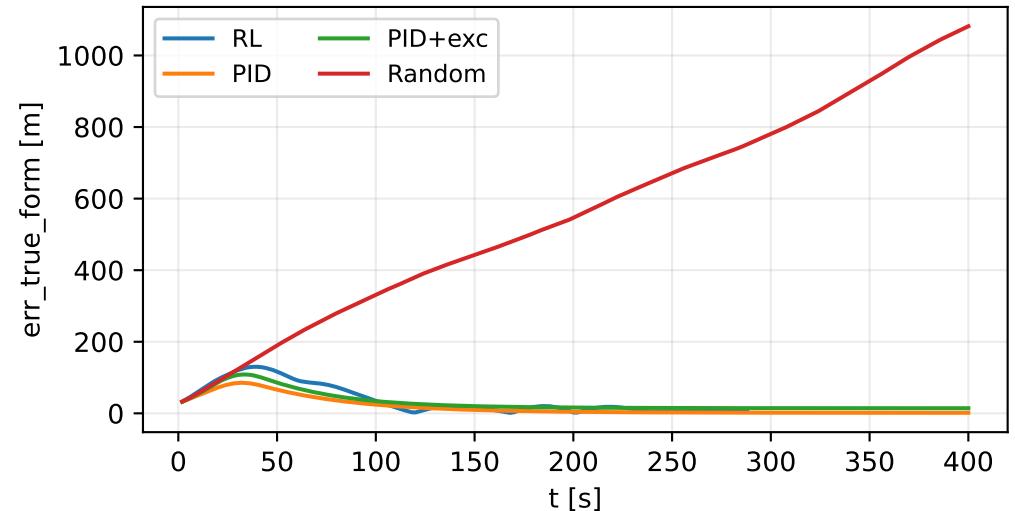
Follower angular rate



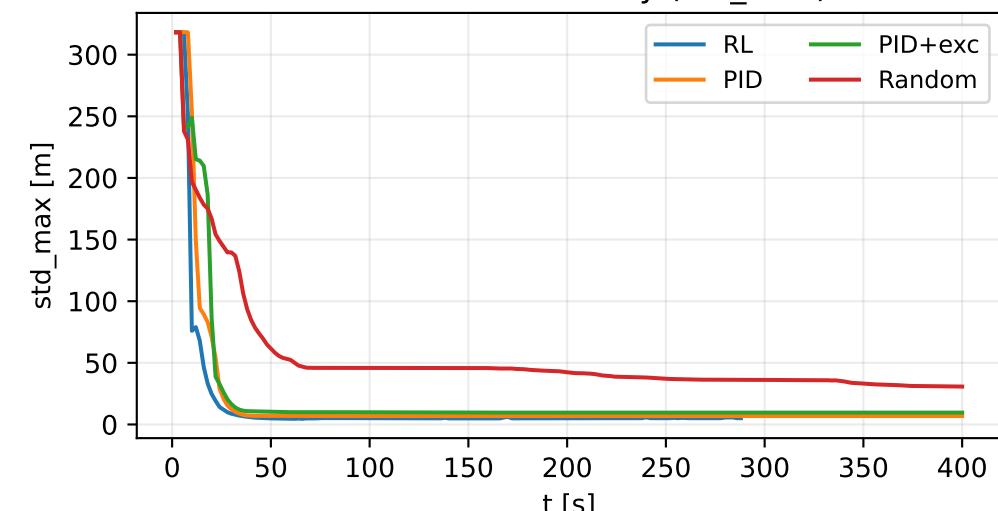
Trajectories (matched seed)



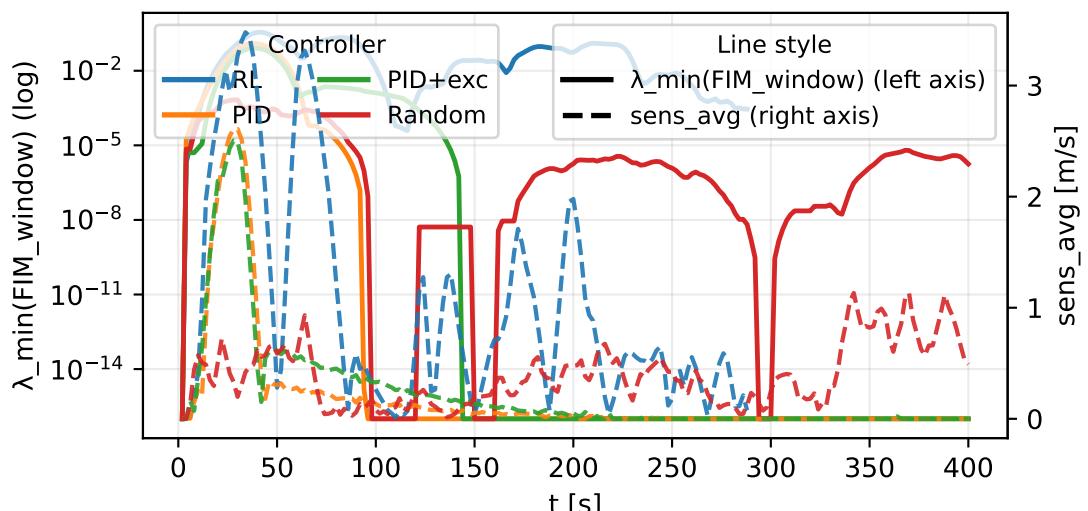
TRUE formation error



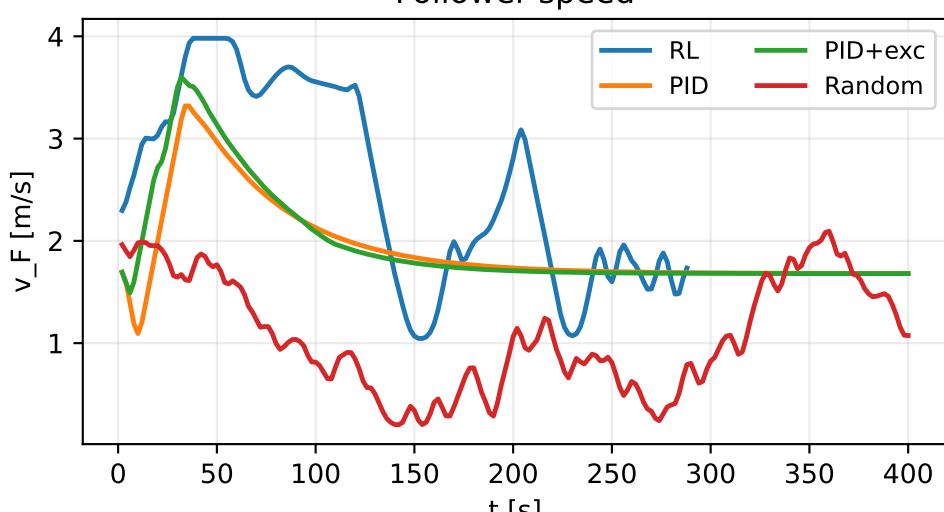
Estimator uncertainty (std_max)



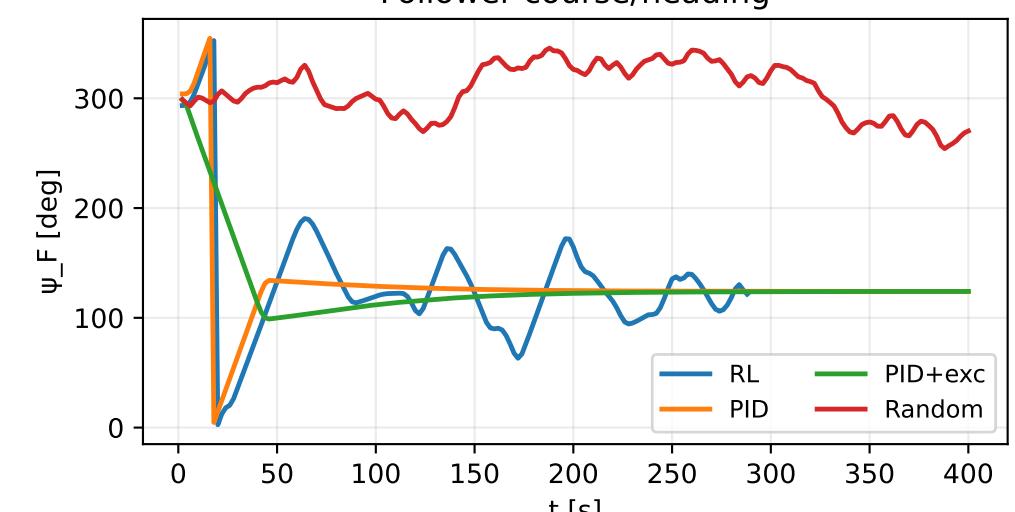
Information and excitation



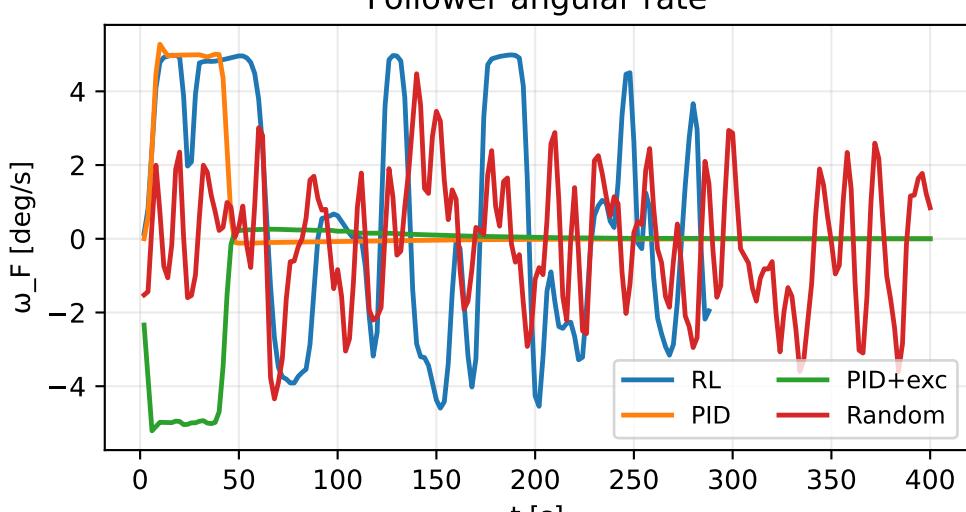
Follower speed



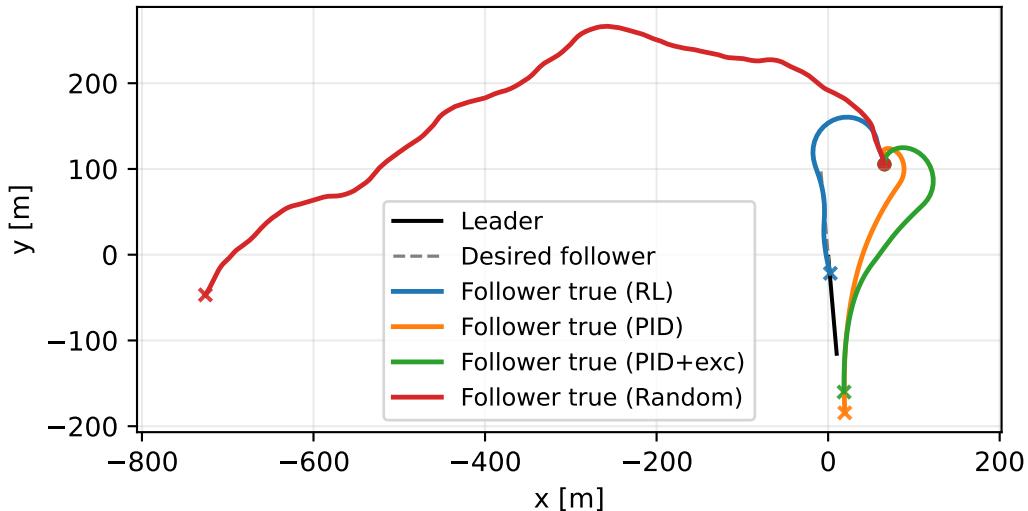
Follower course/heading



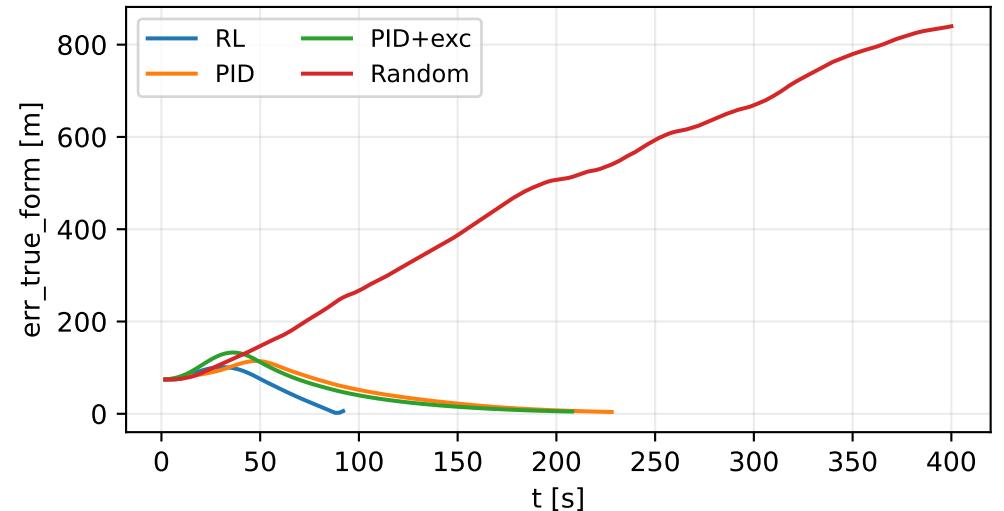
Follower angular rate



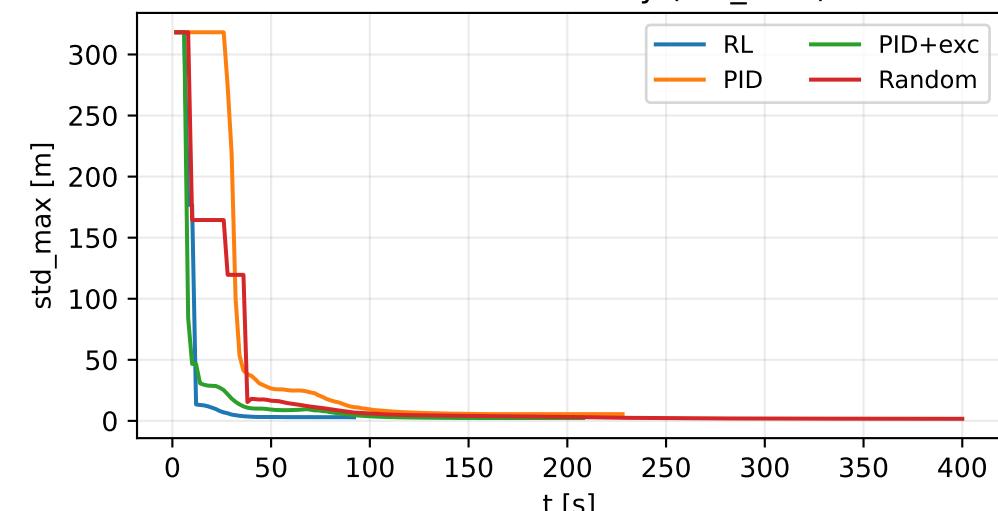
Trajectories (matched seed)



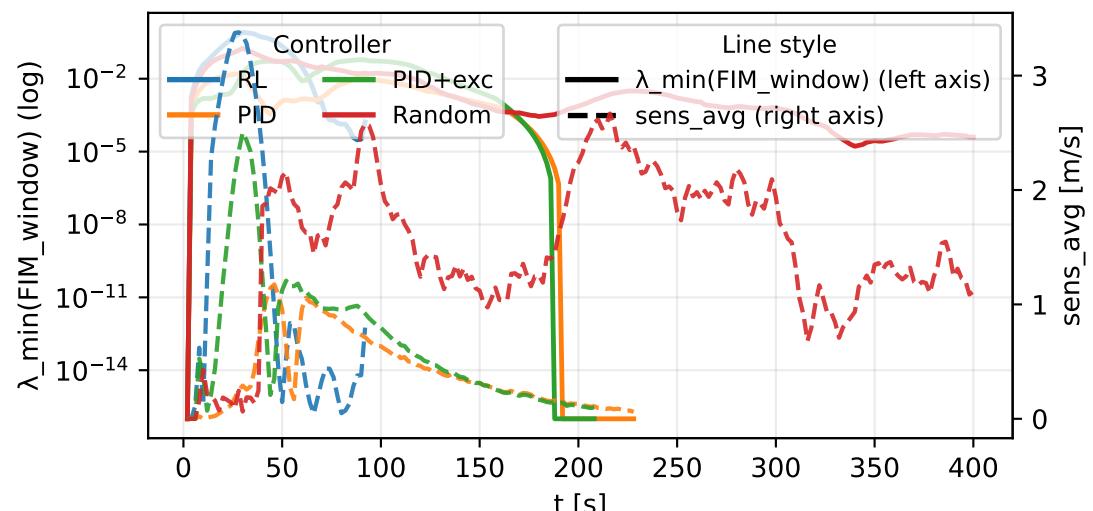
TRUE formation error



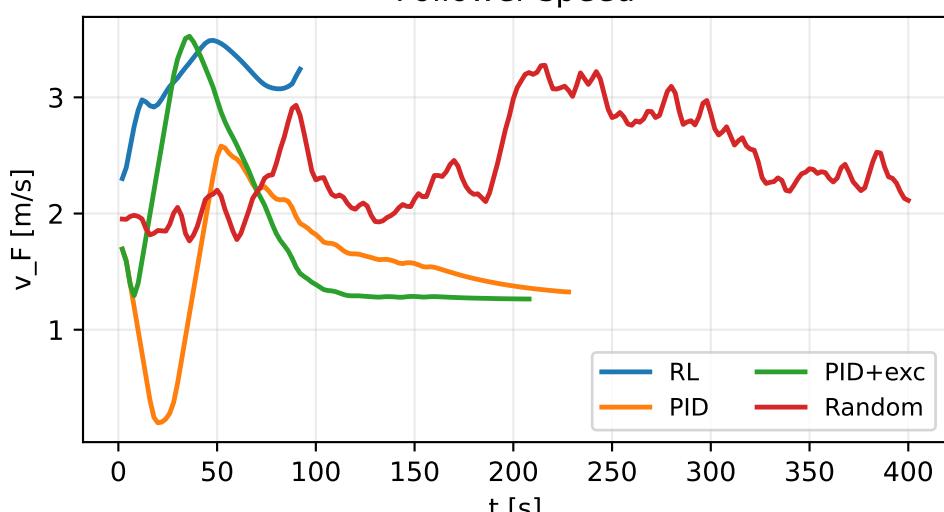
Estimator uncertainty (std_max)



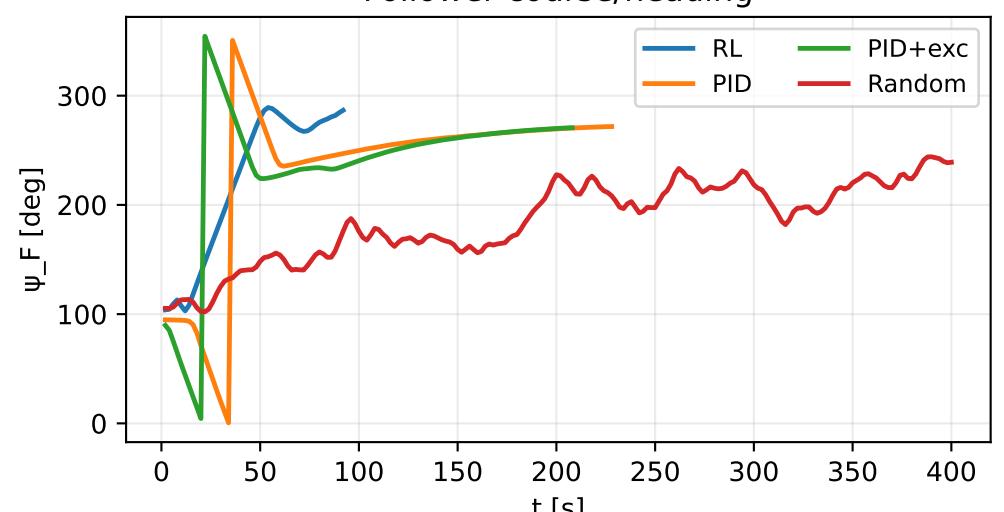
Information and excitation



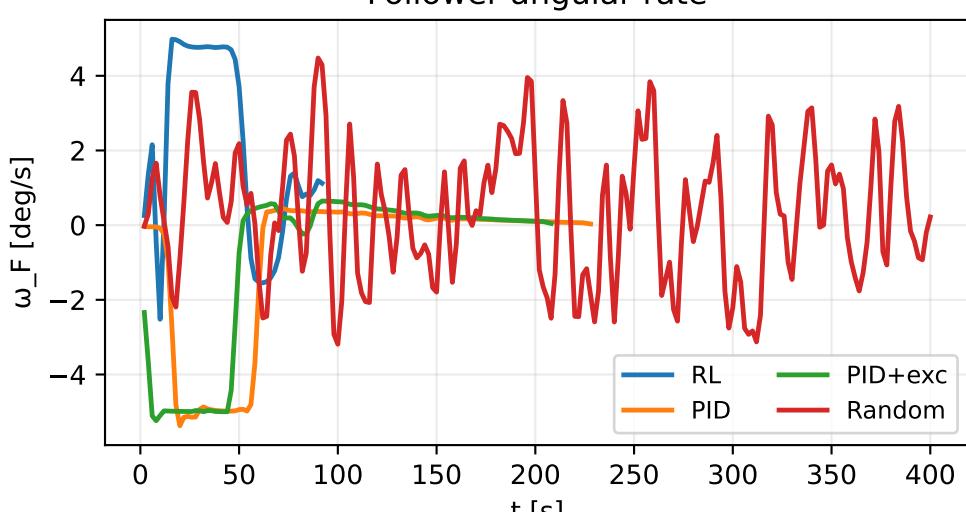
Follower speed



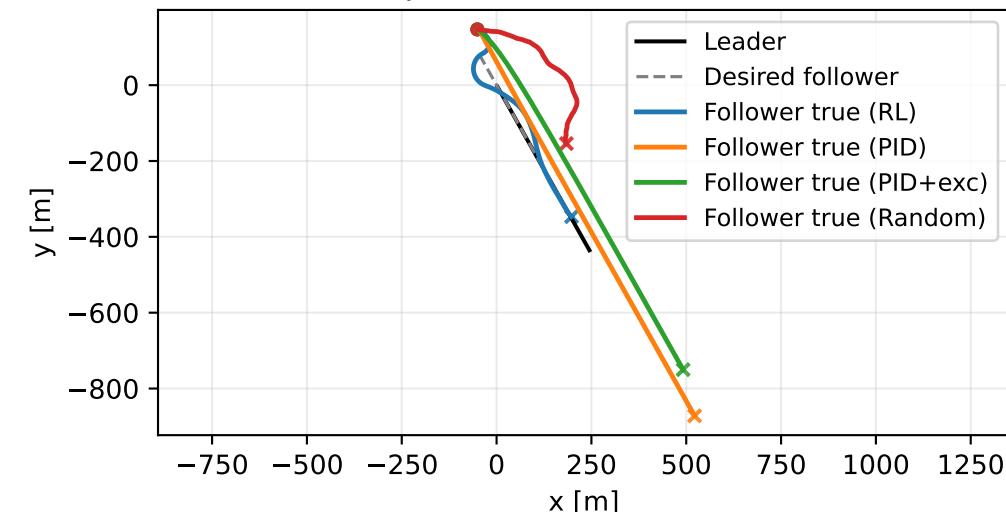
Follower course/heading



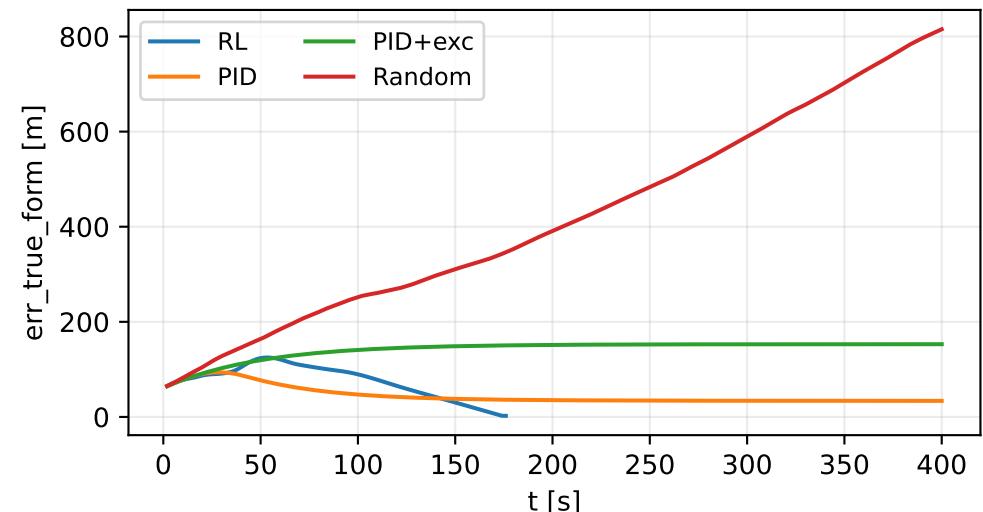
Follower angular rate



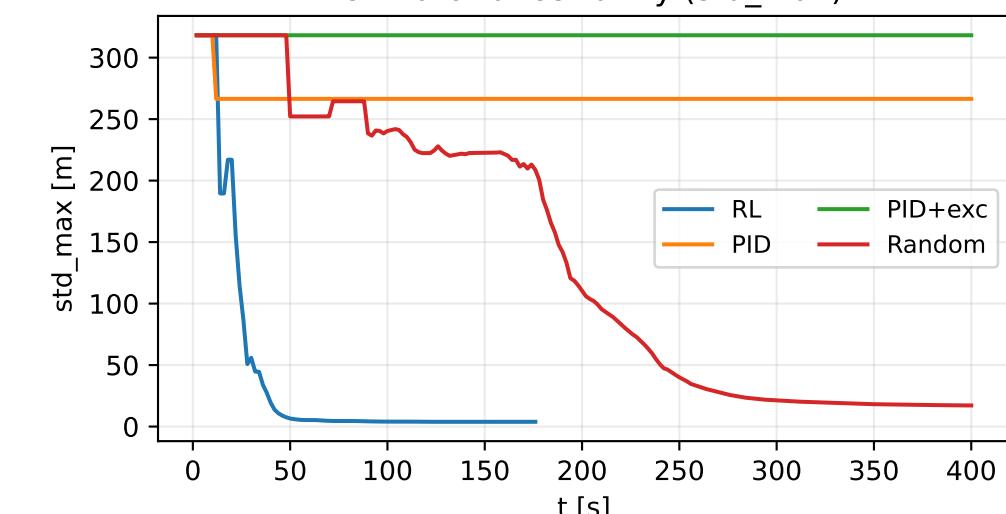
Trajectories (matched seed)



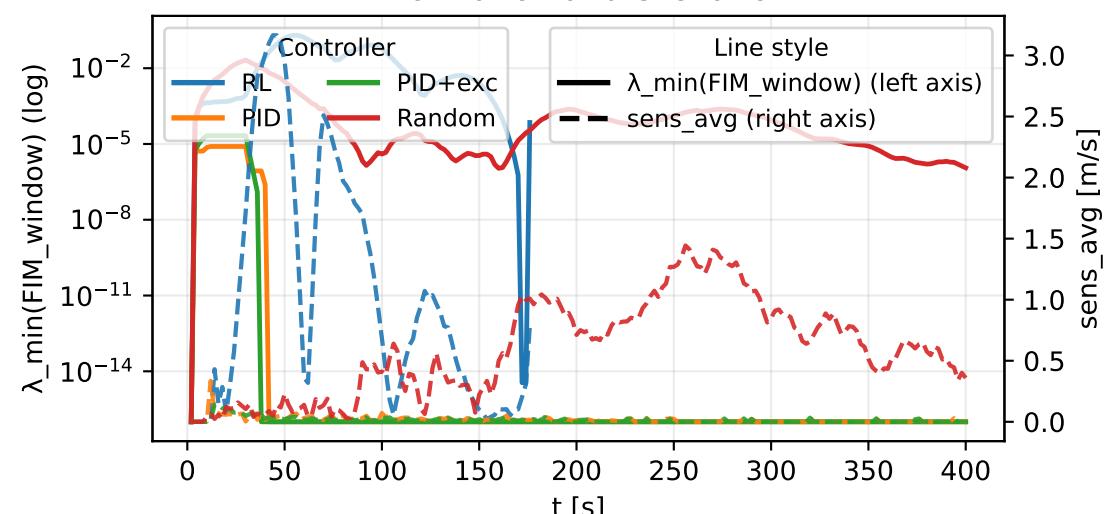
TRUE formation error



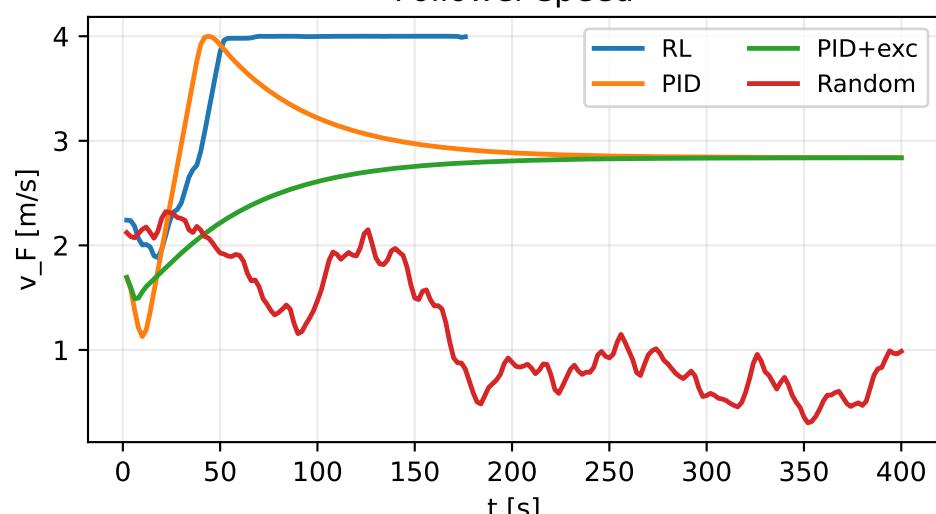
Estimator uncertainty (std_max)



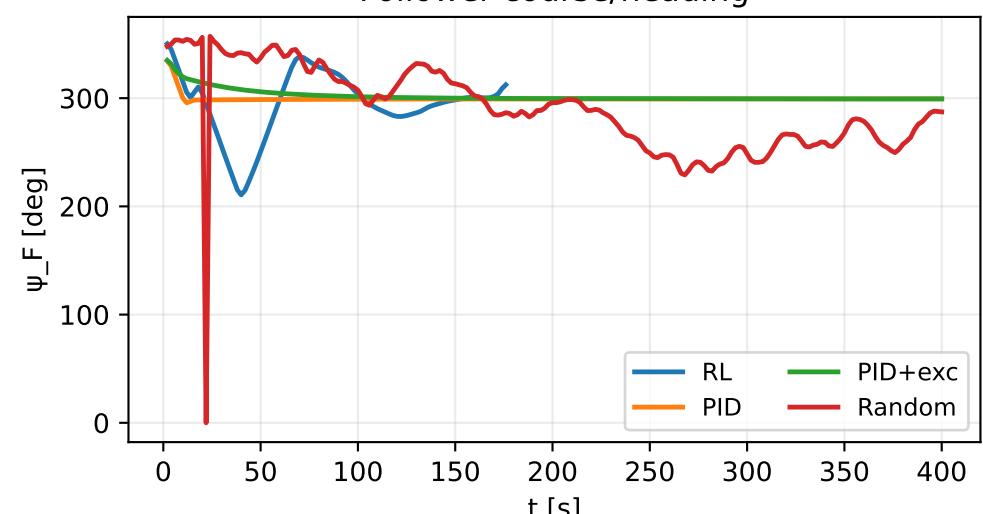
Information and excitation



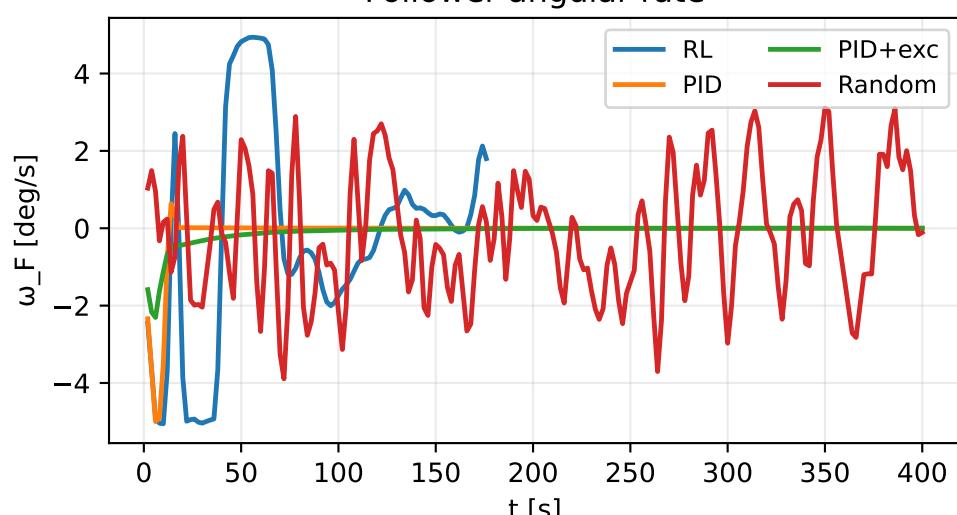
Follower speed



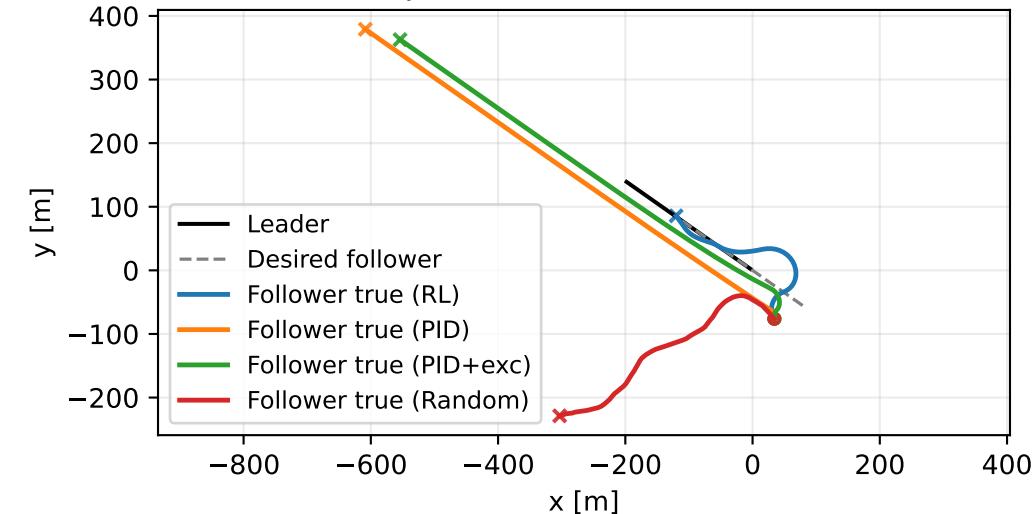
Follower course/heading



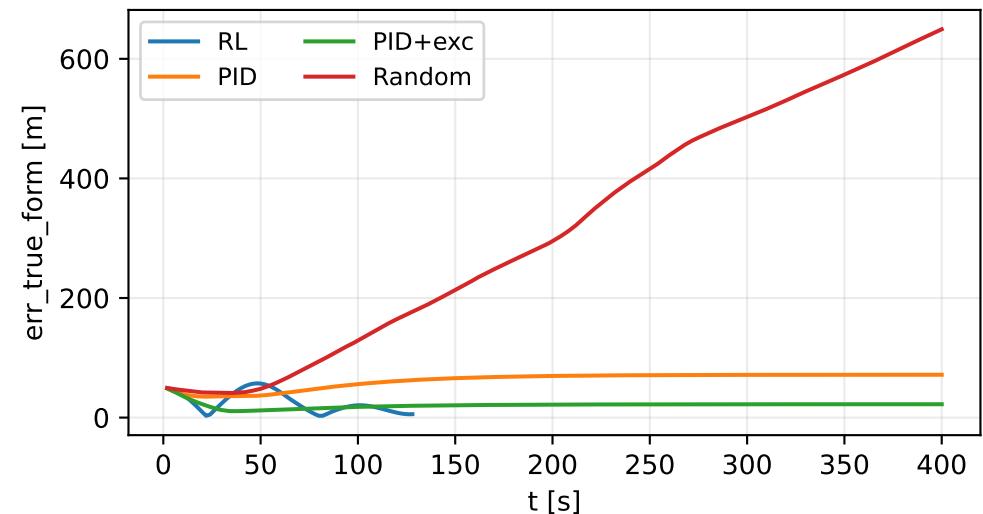
Follower angular rate



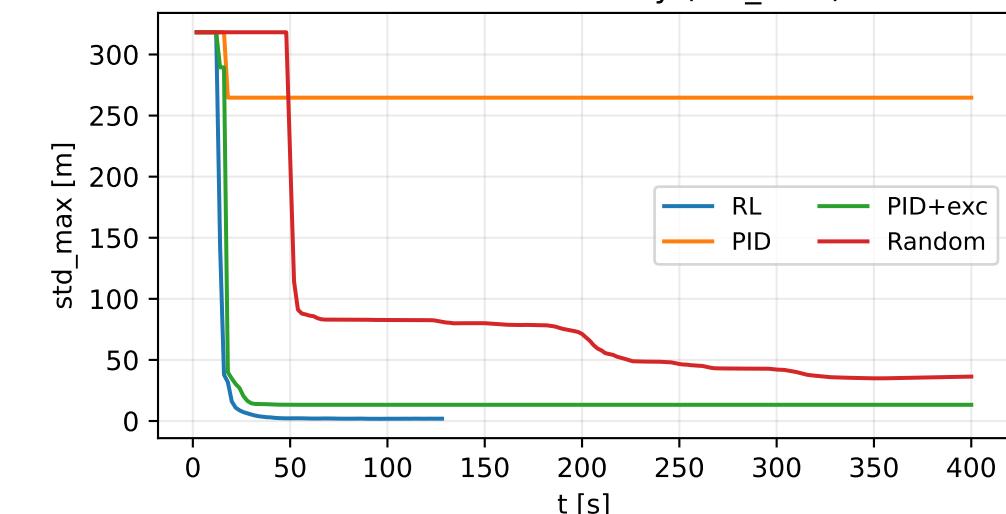
Trajectories (matched seed)



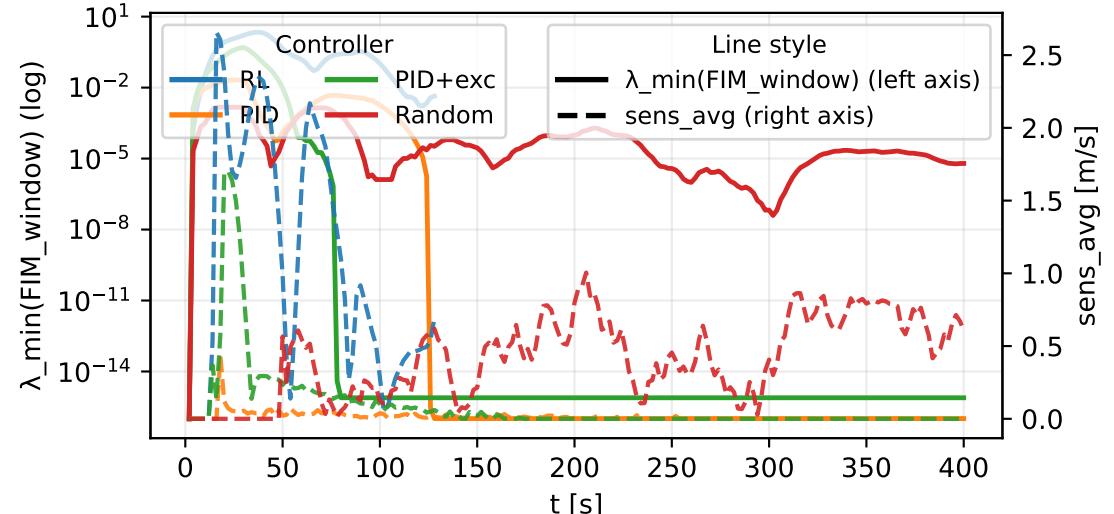
TRUE formation error



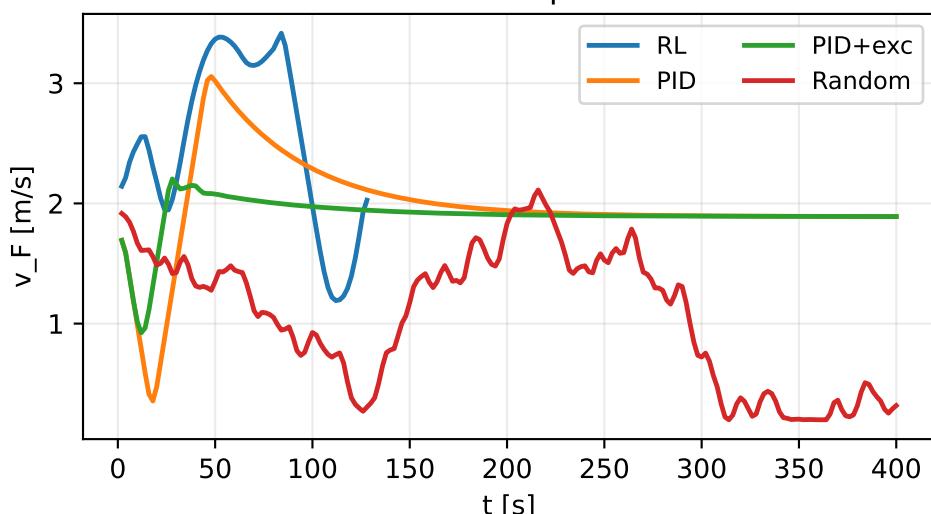
Estimator uncertainty (std_max)



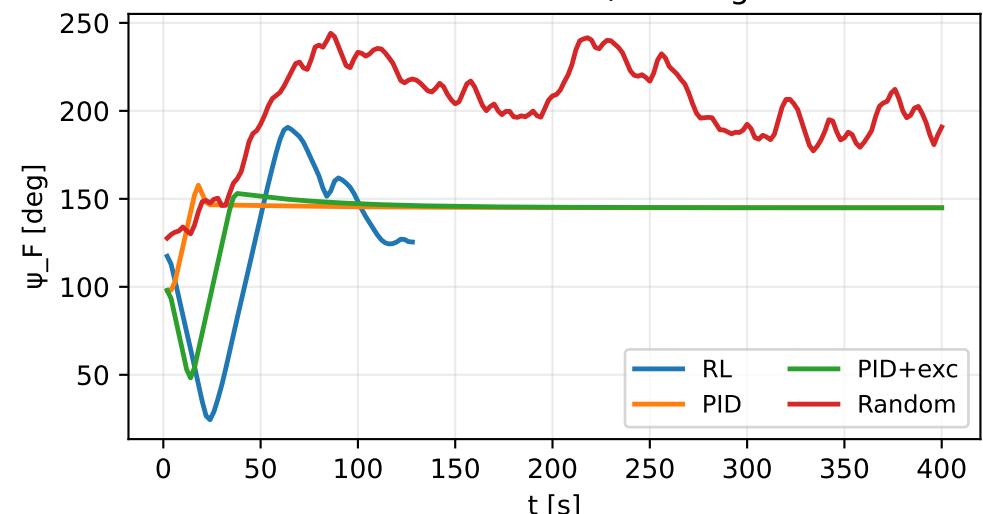
Information and excitation



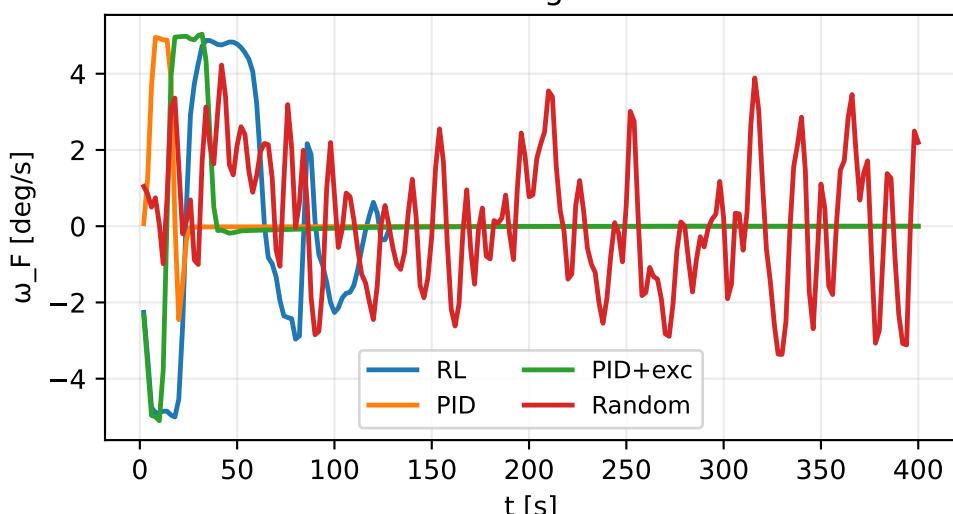
Follower speed



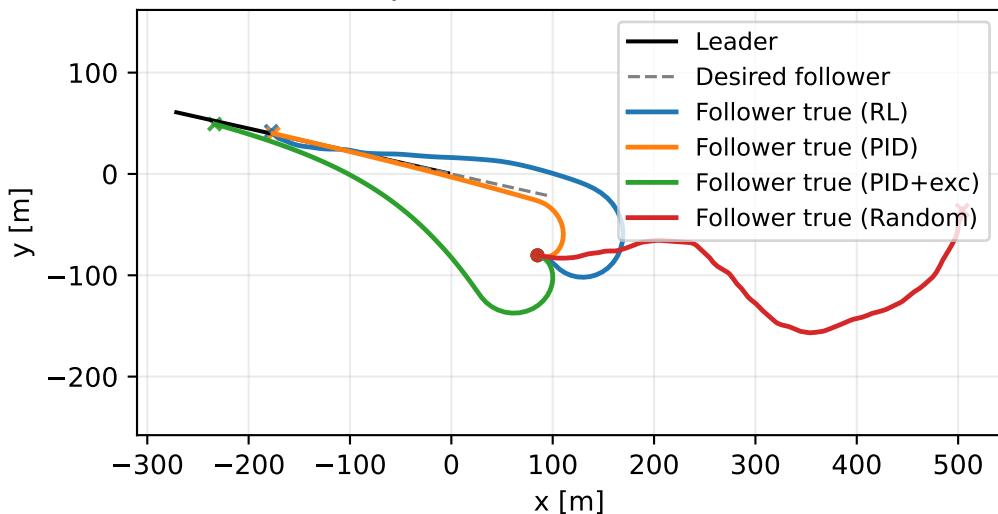
Follower course/heading



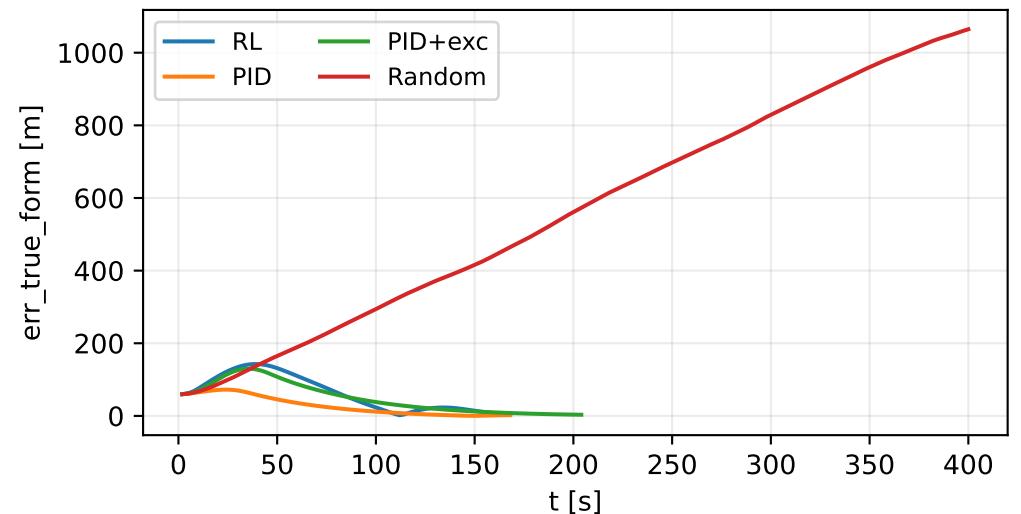
Follower angular rate



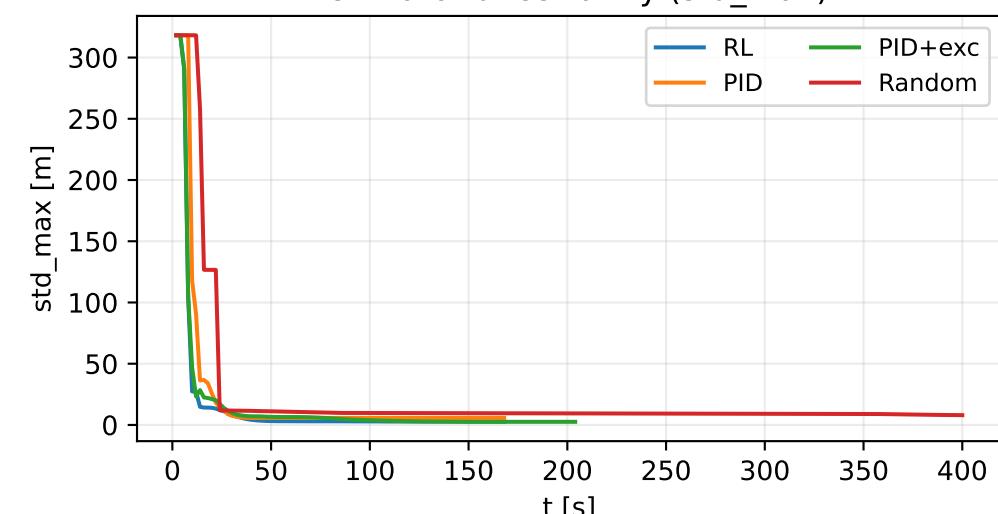
Trajectories (matched seed)



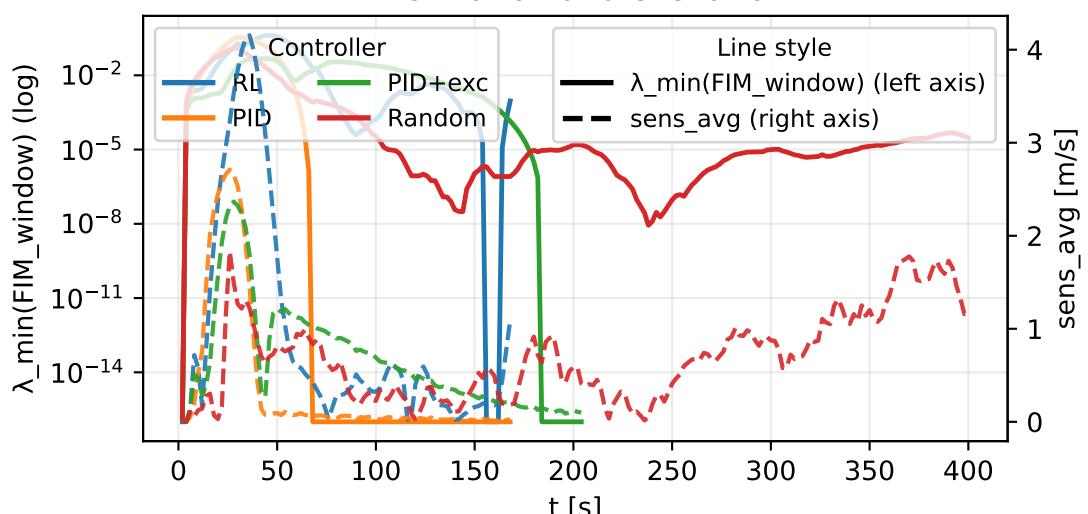
TRUE formation error



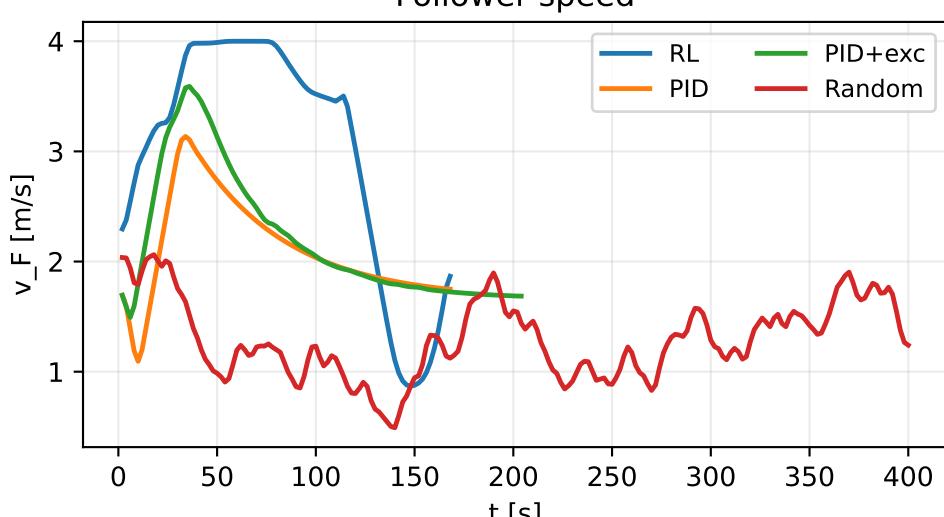
Estimator uncertainty (std_max)



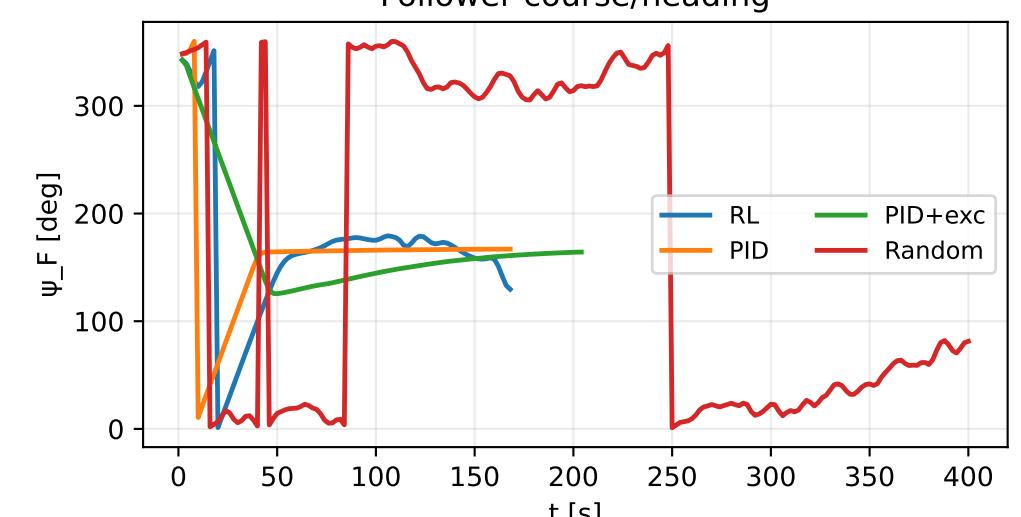
Information and excitation



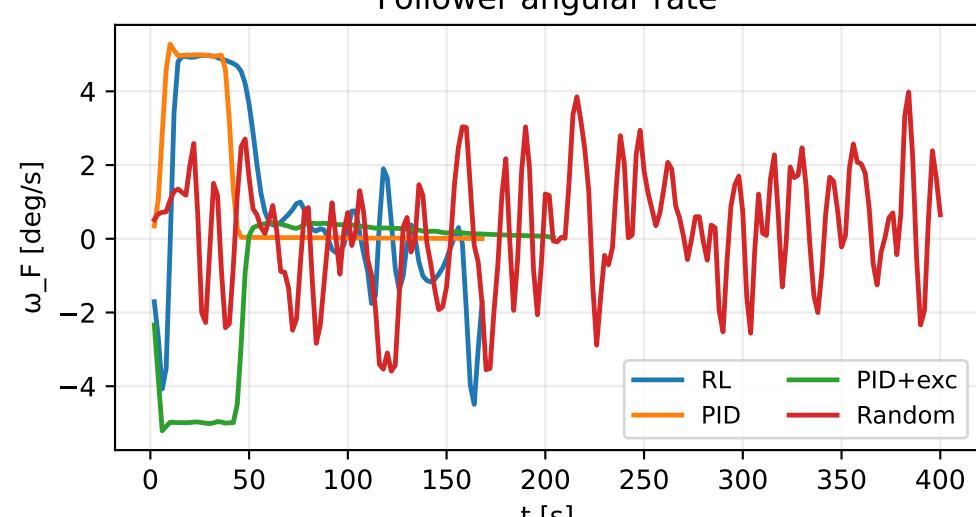
Follower speed



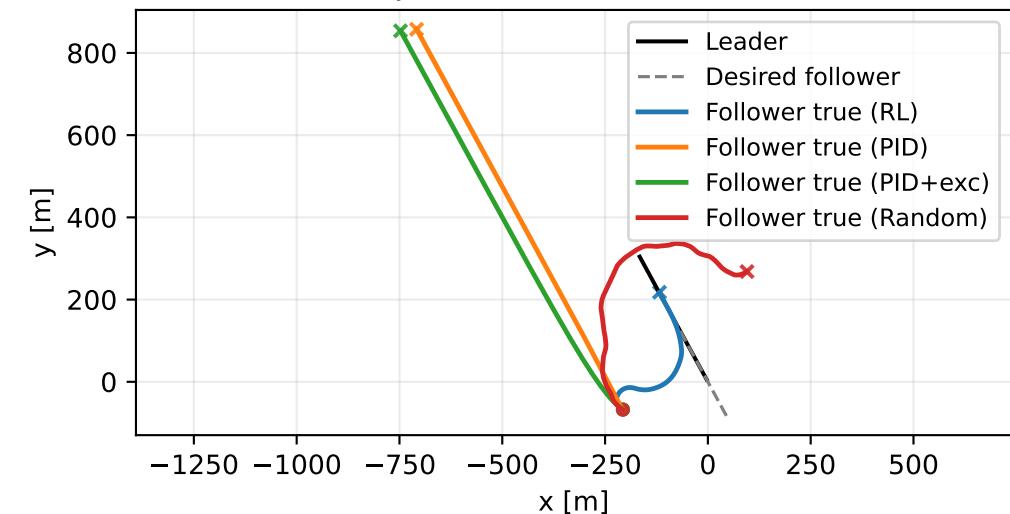
Follower course/heading



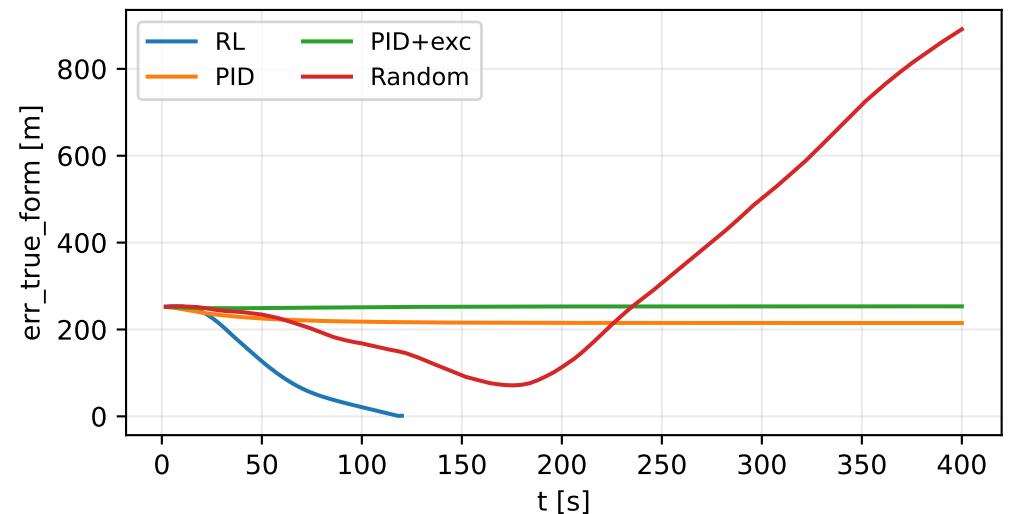
Follower angular rate



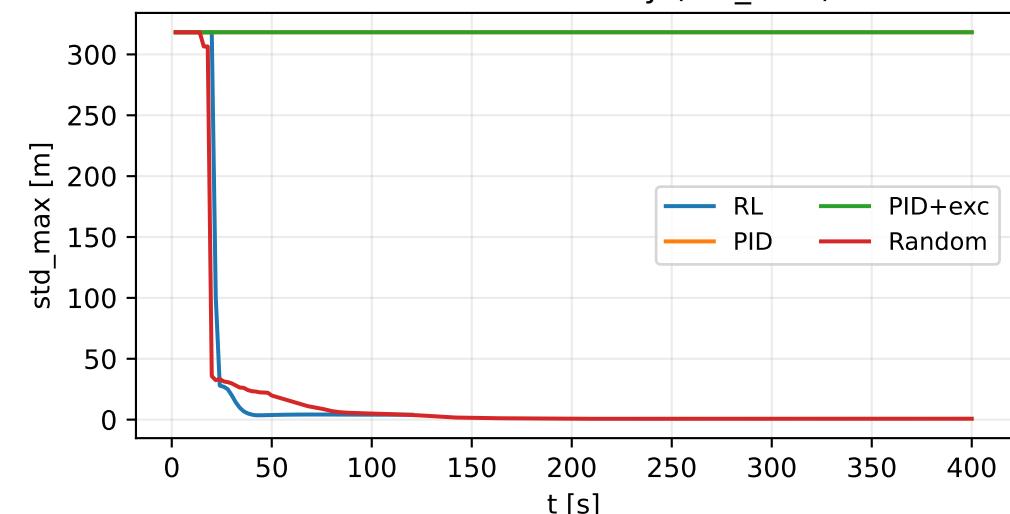
Trajectories (matched seed)



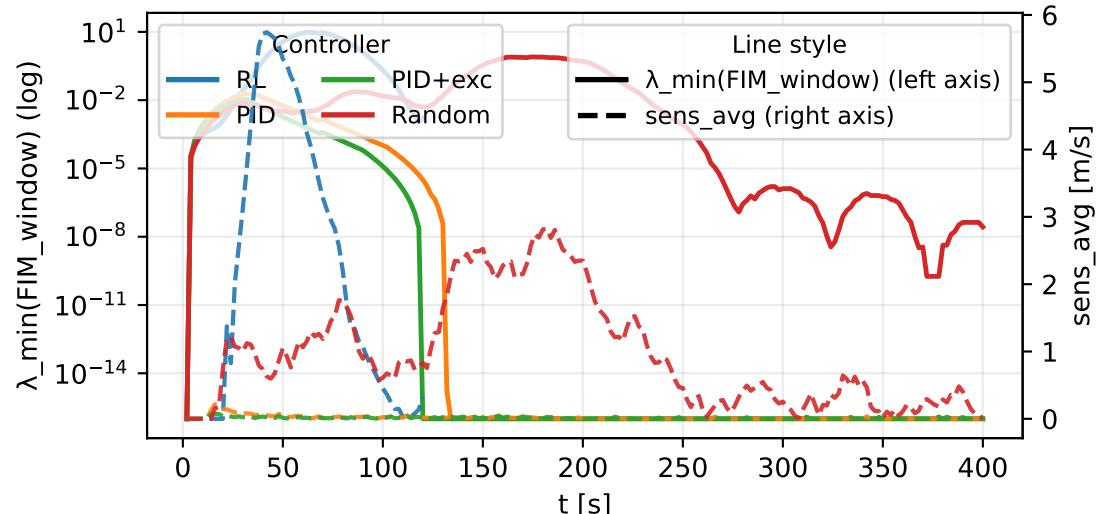
TRUE formation error



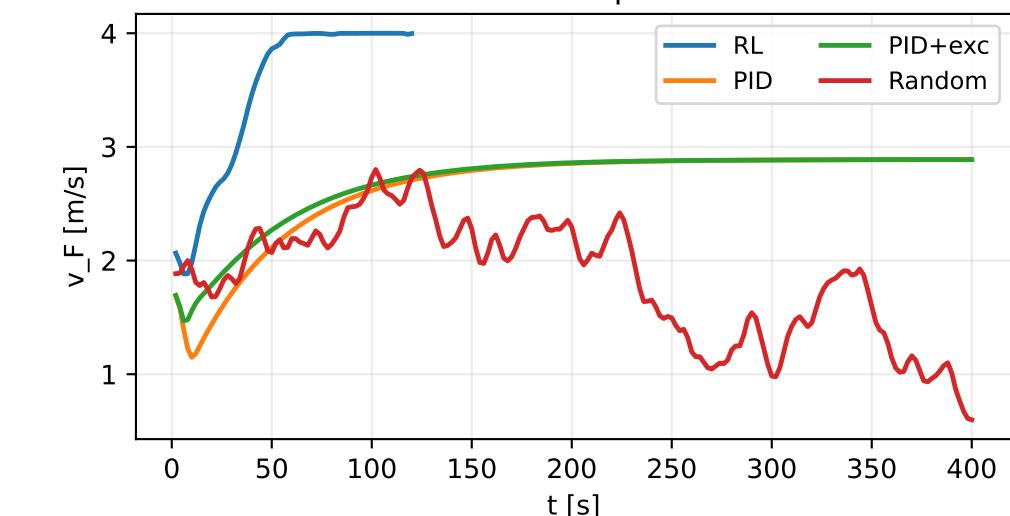
Estimator uncertainty (std_max)



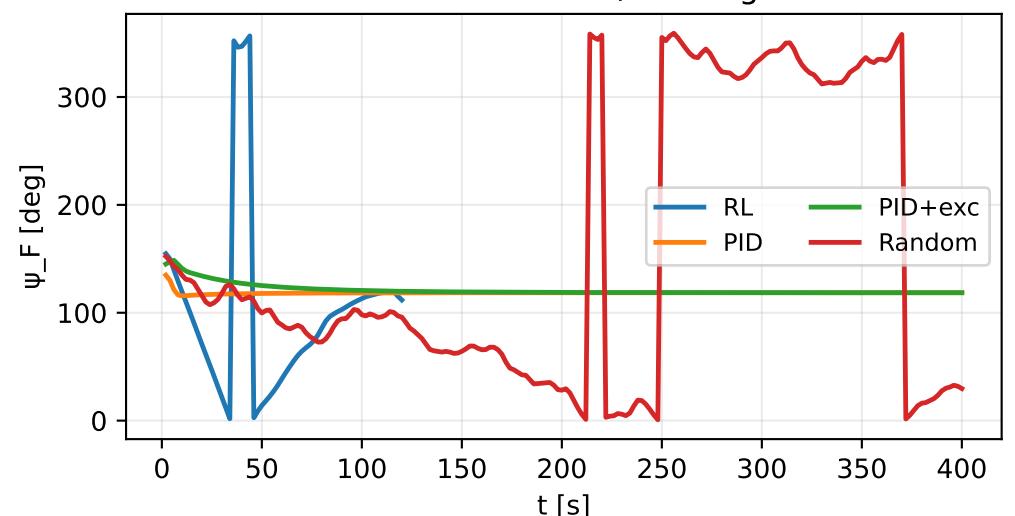
Information and excitation



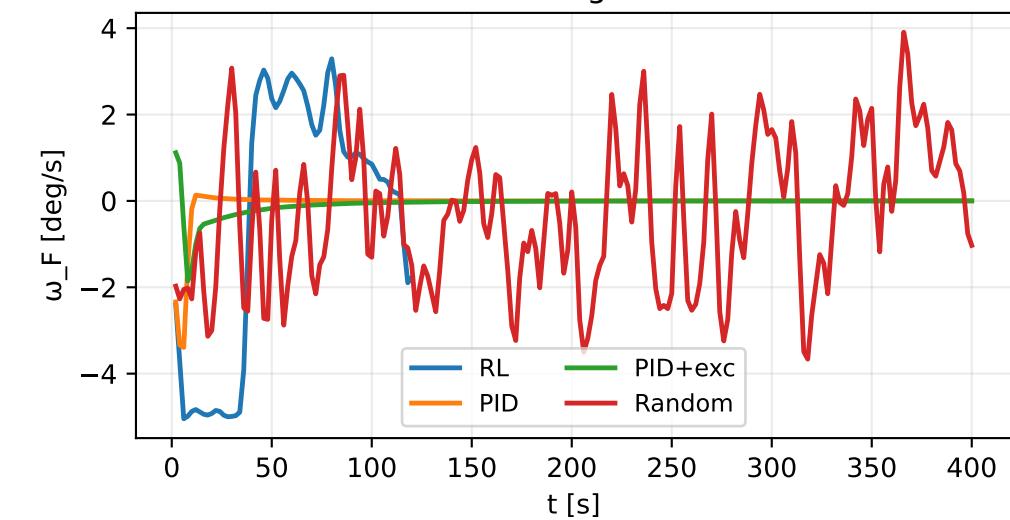
Follower speed



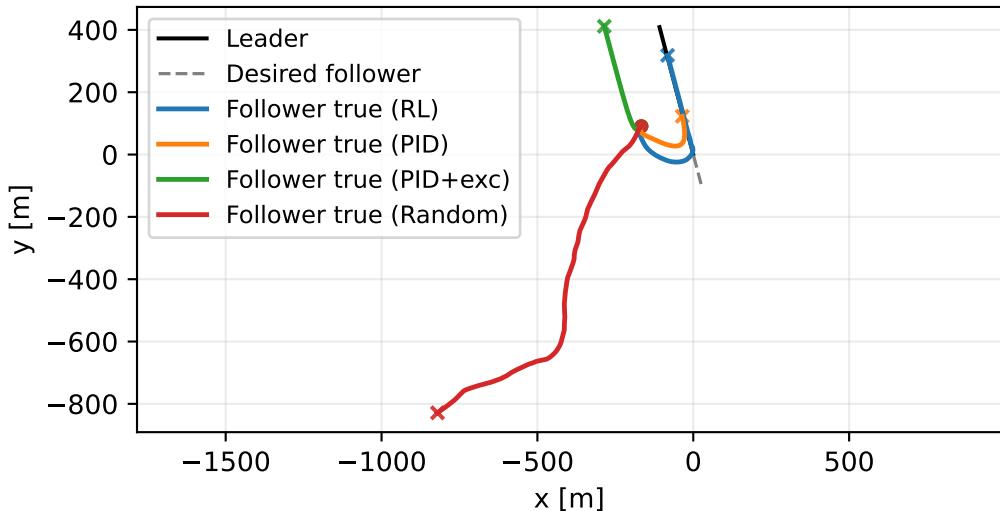
Follower course/heading



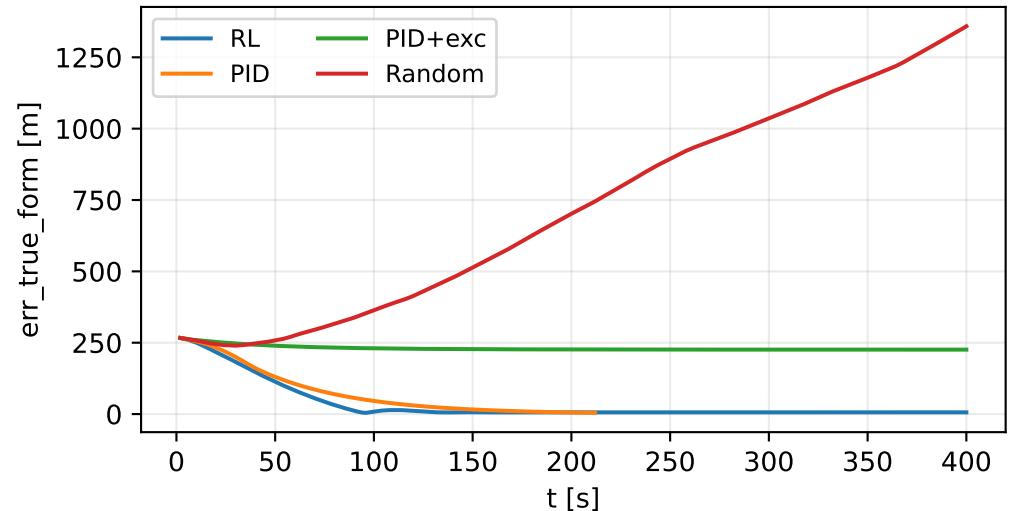
Follower angular rate



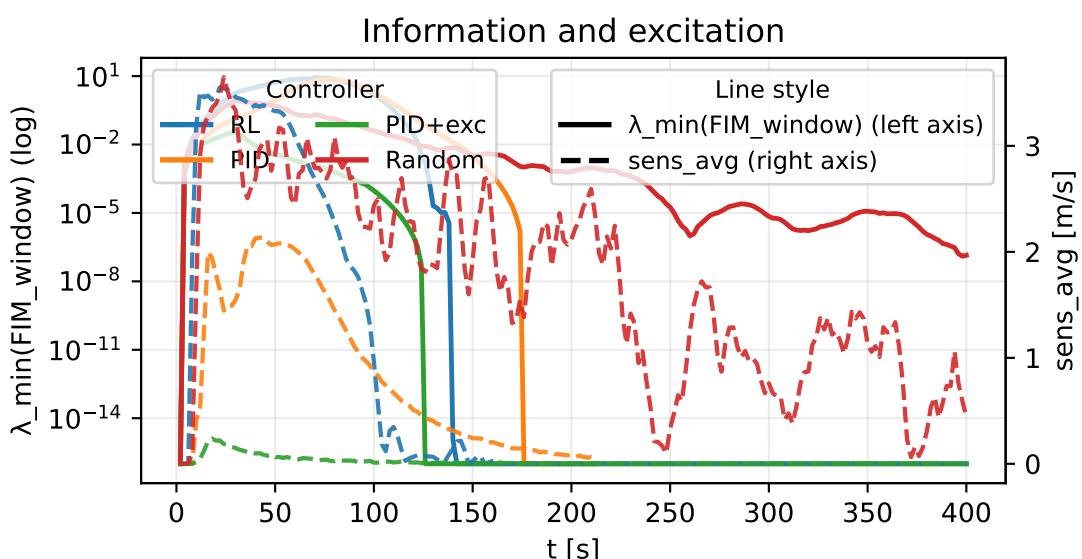
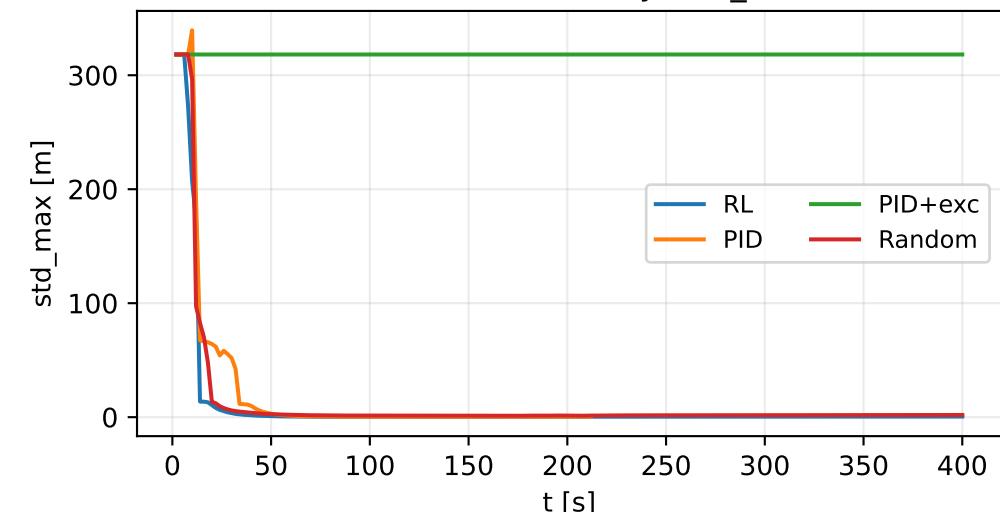
Trajectories (matched seed)



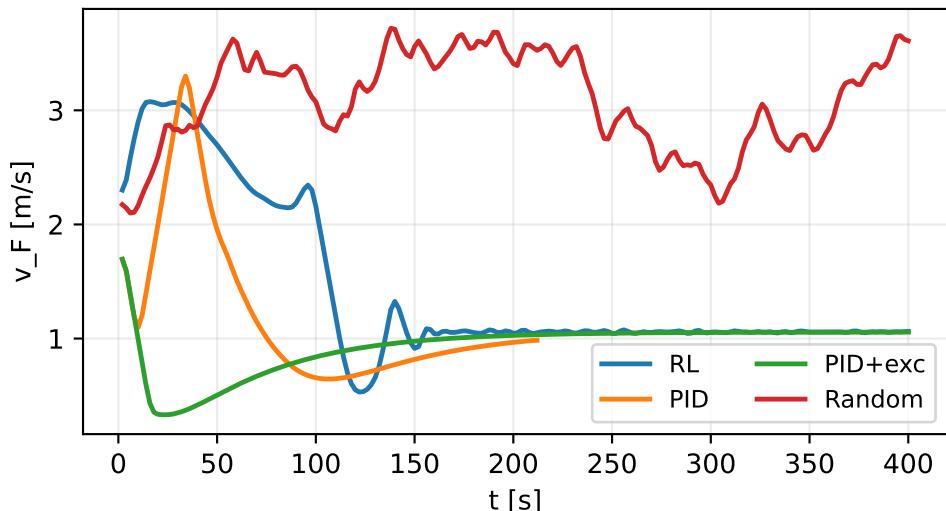
TRUE formation error



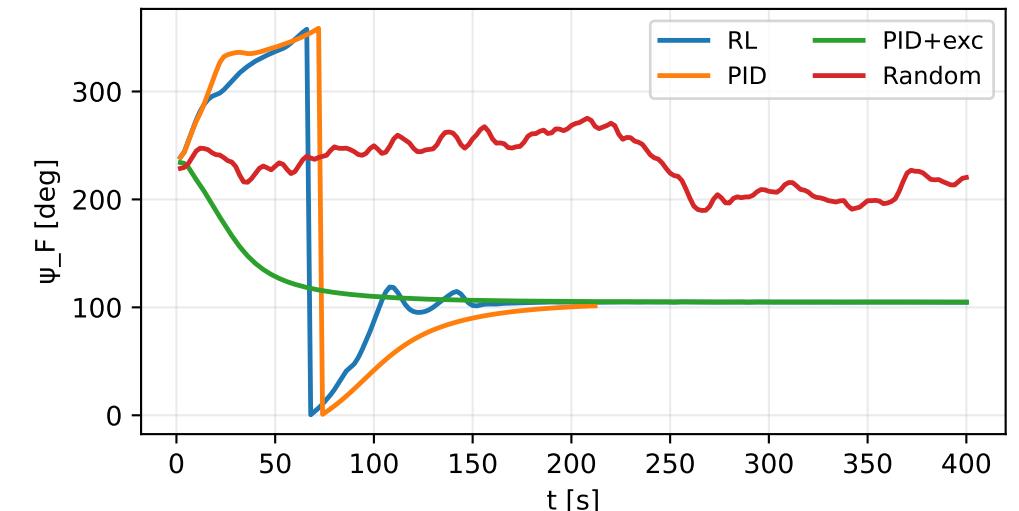
Estimator uncertainty (std_max)



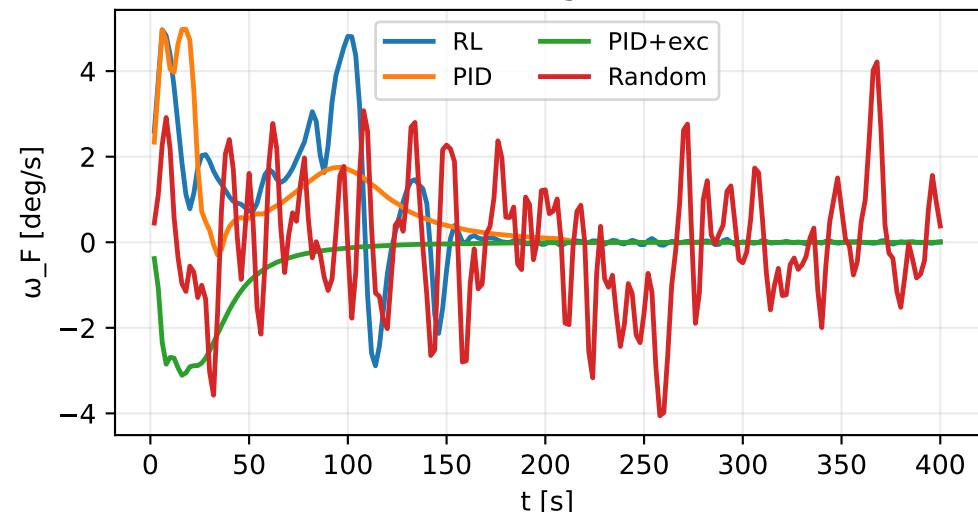
Follower speed



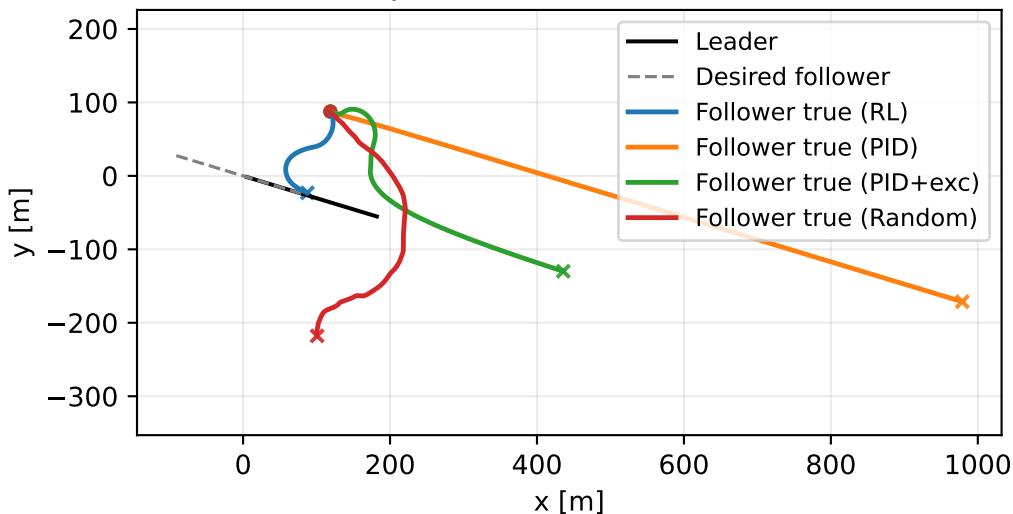
Follower course/heading



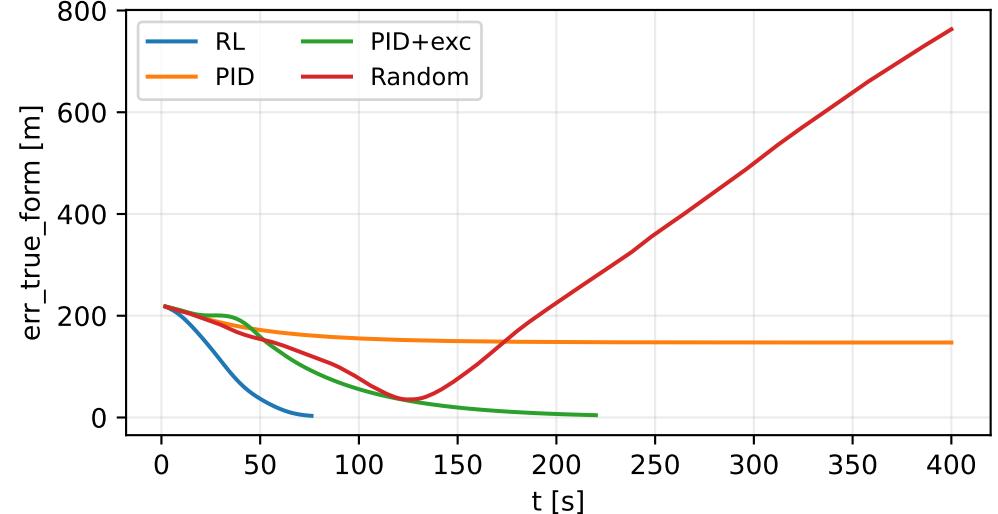
Follower angular rate



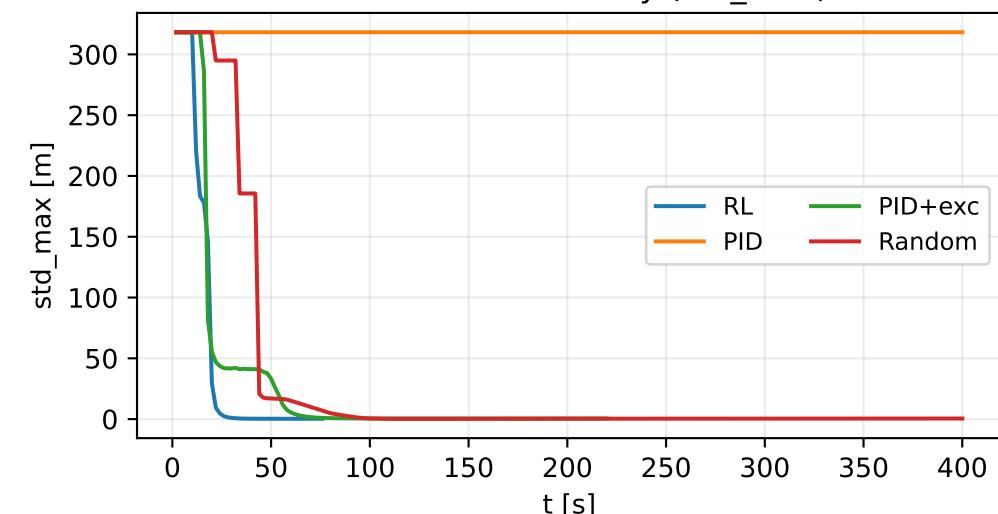
Trajectories (matched seed)



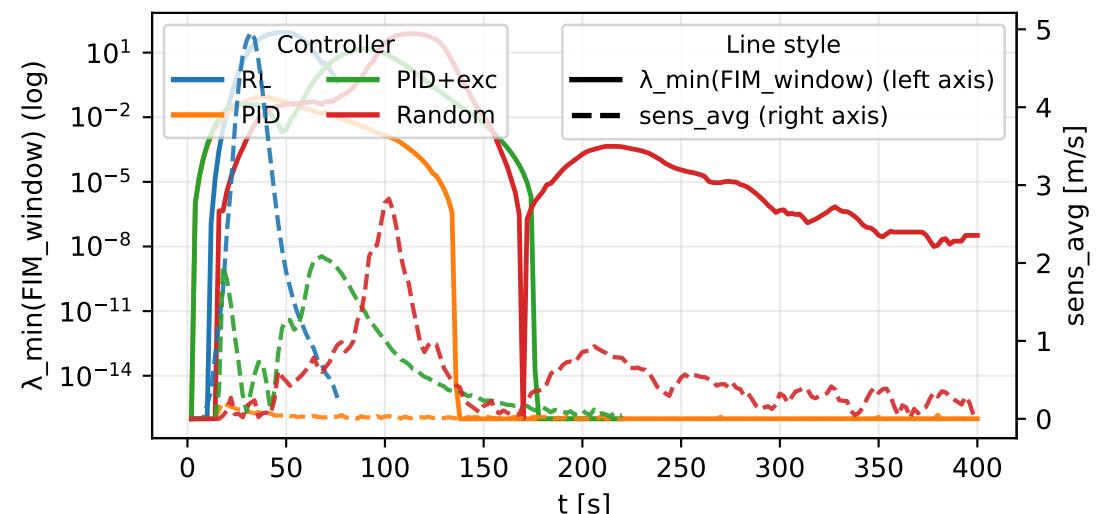
TRUE formation error



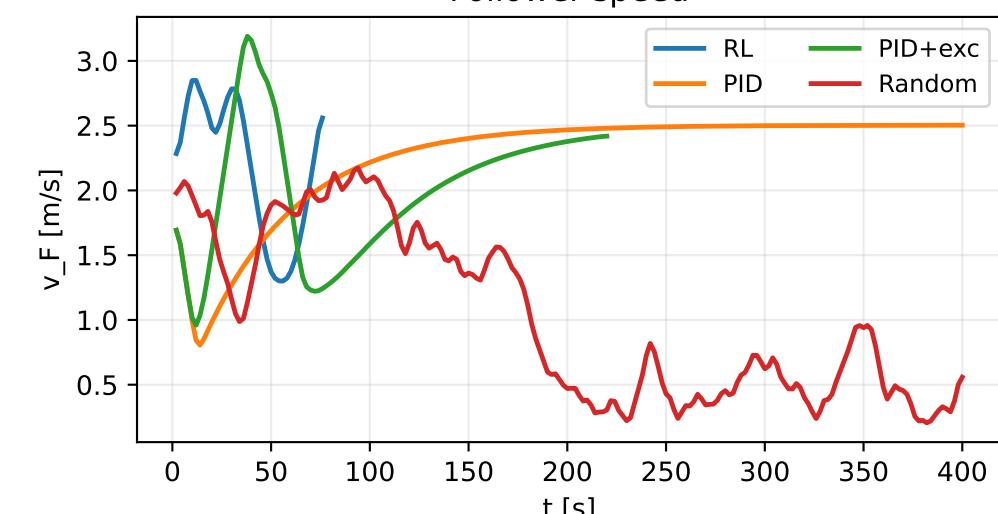
Estimator uncertainty (std_max)



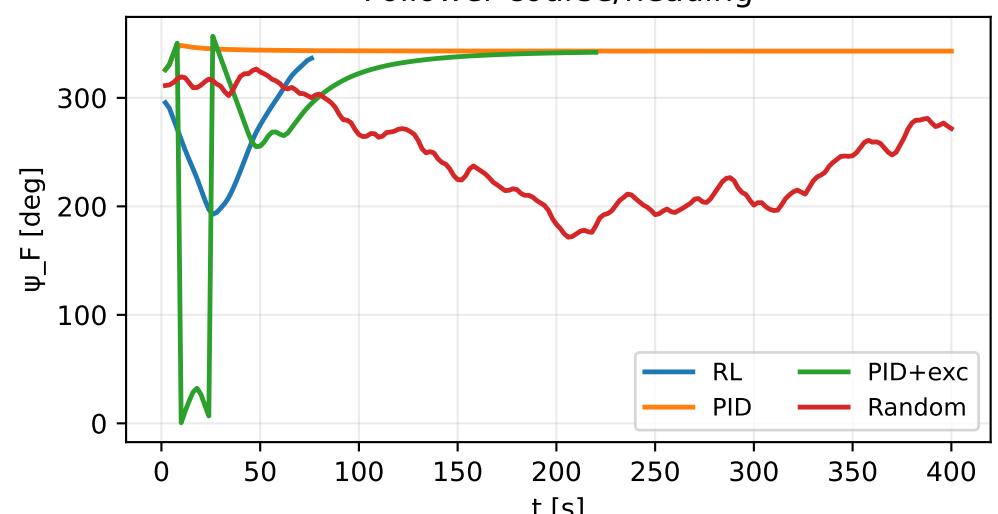
Information and excitation



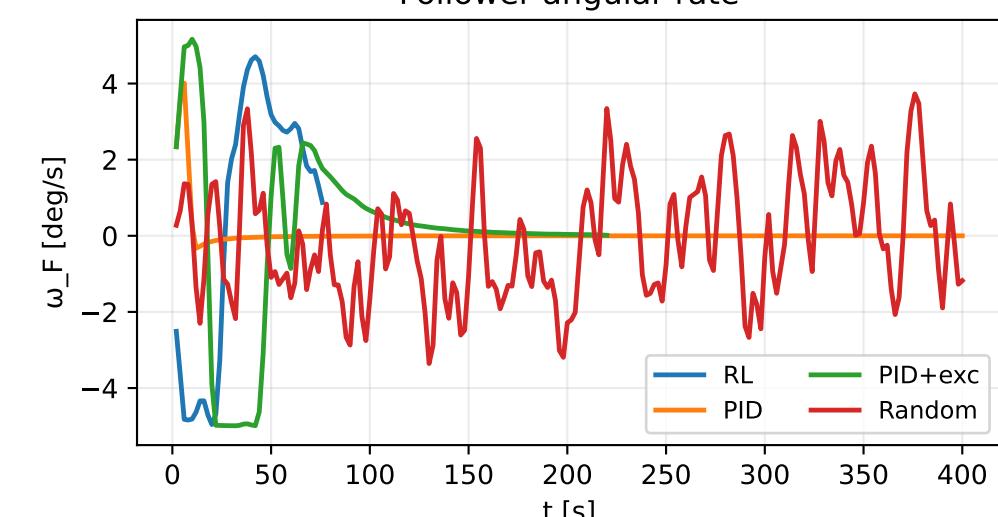
Follower speed



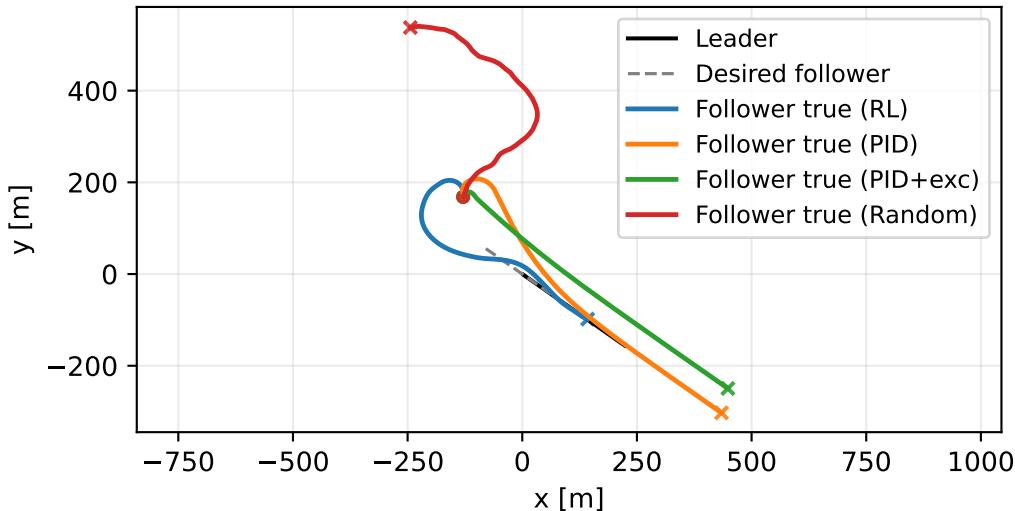
Follower course/heading



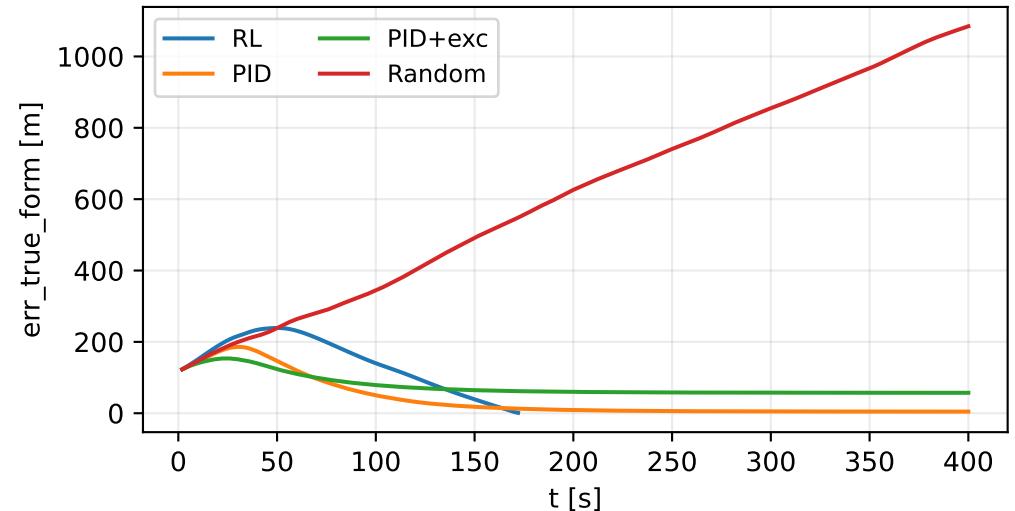
Follower angular rate



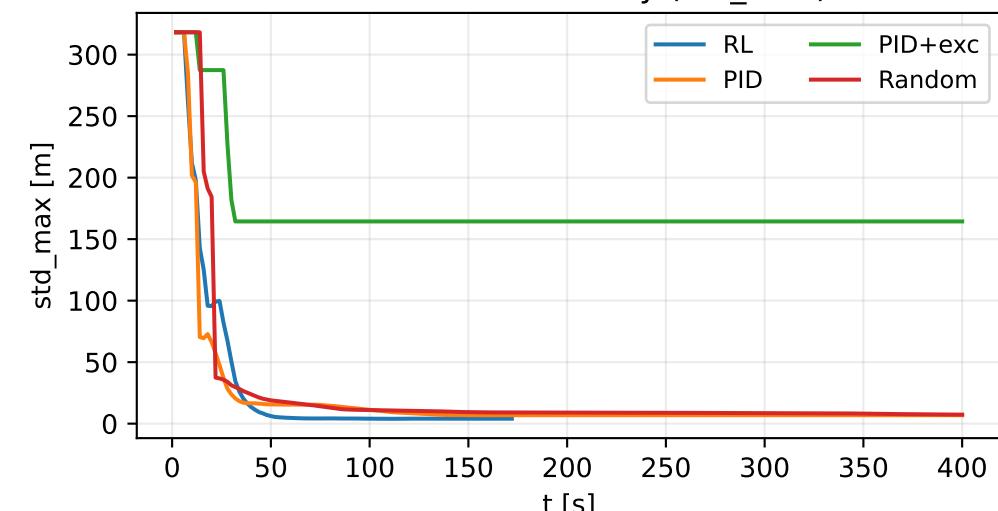
Trajectories (matched seed)



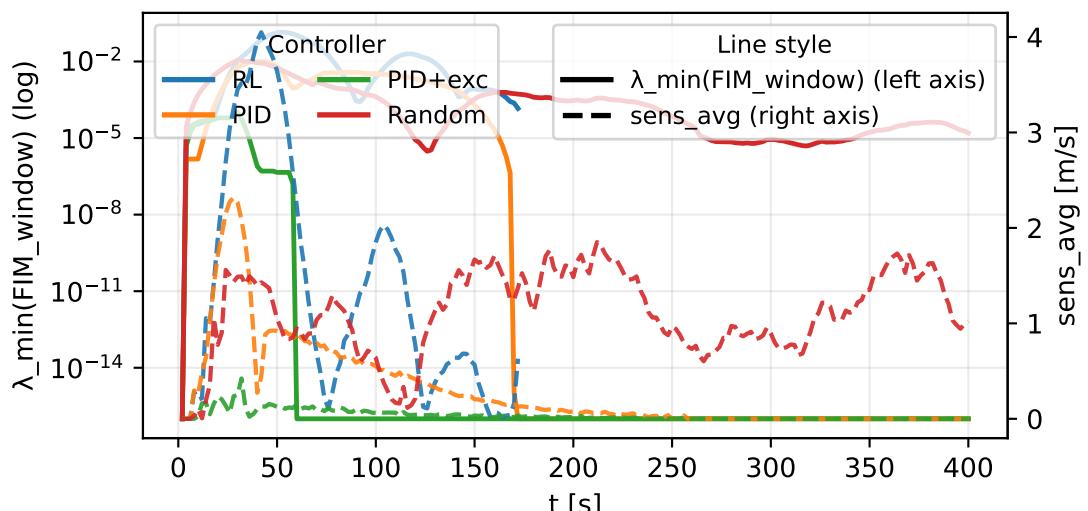
TRUE formation error



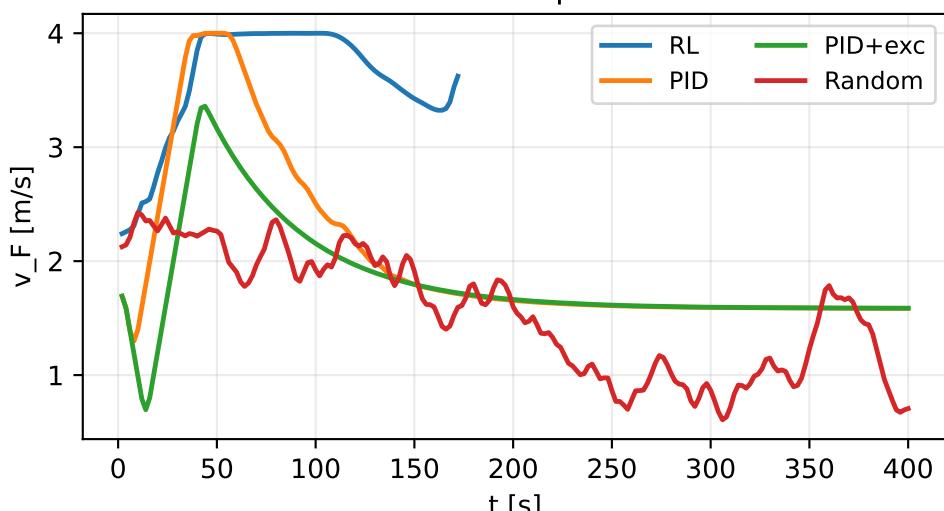
Estimator uncertainty (std_max)



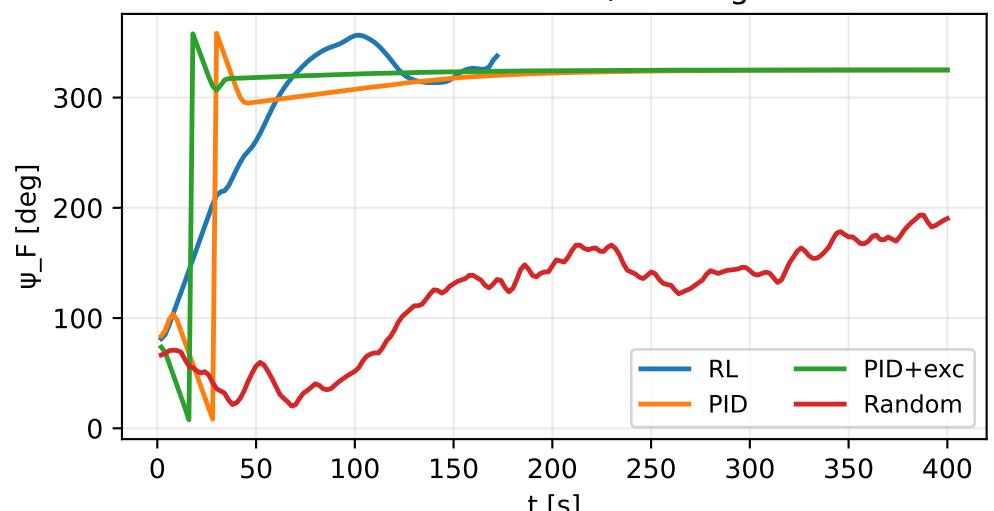
Information and excitation



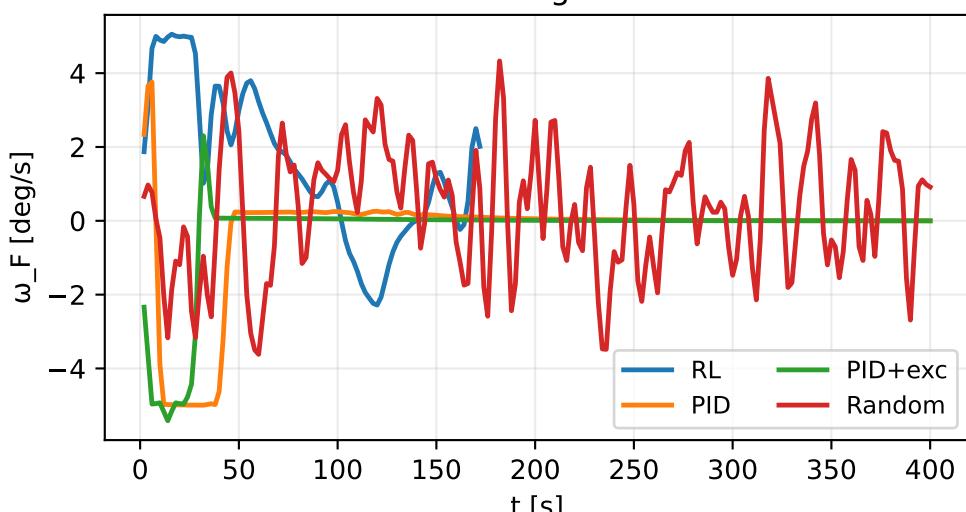
Follower speed



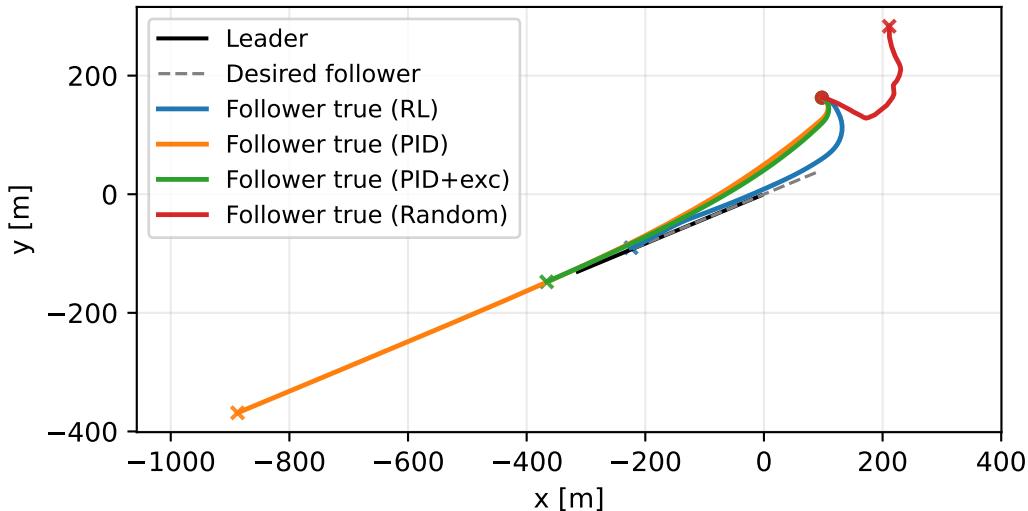
Follower course/heading



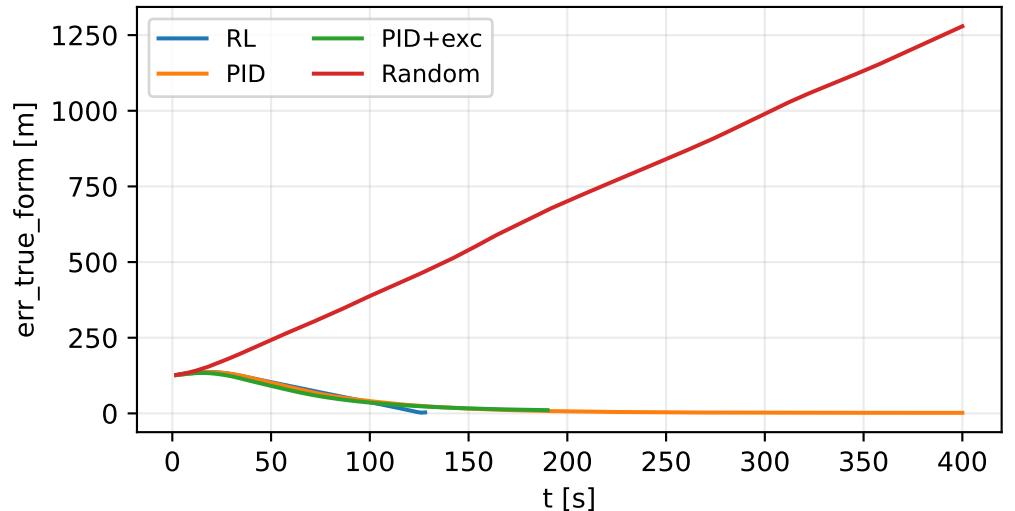
Follower angular rate



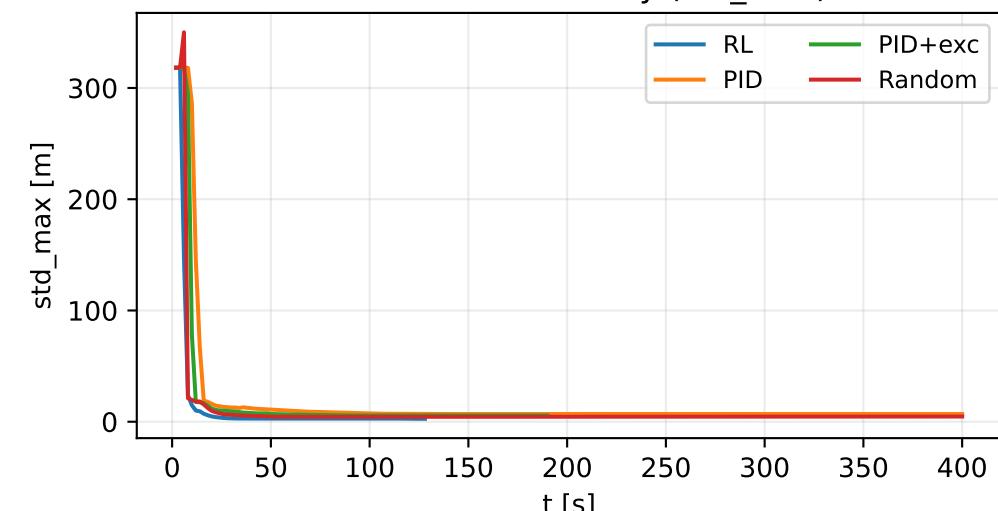
Trajectories (matched seed)



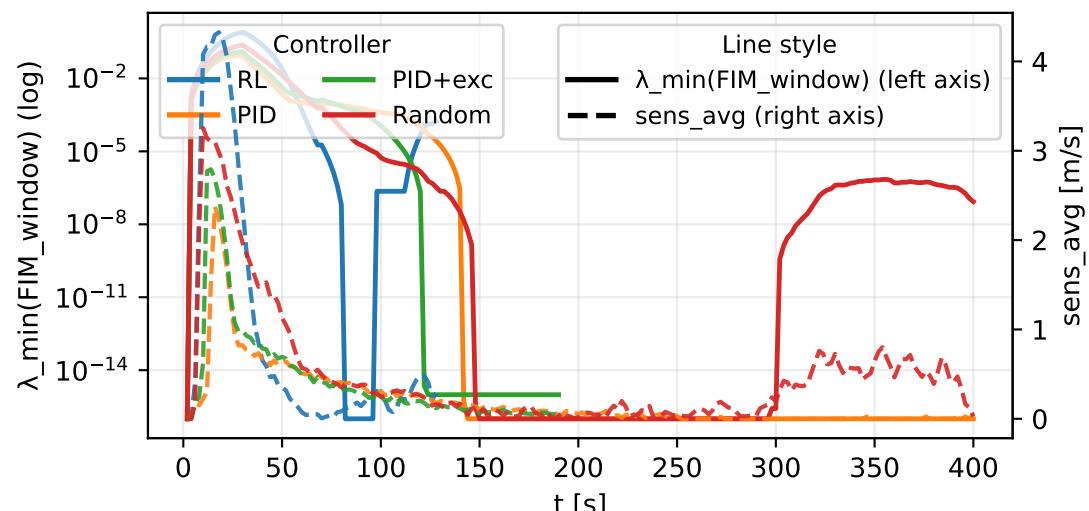
TRUE formation error



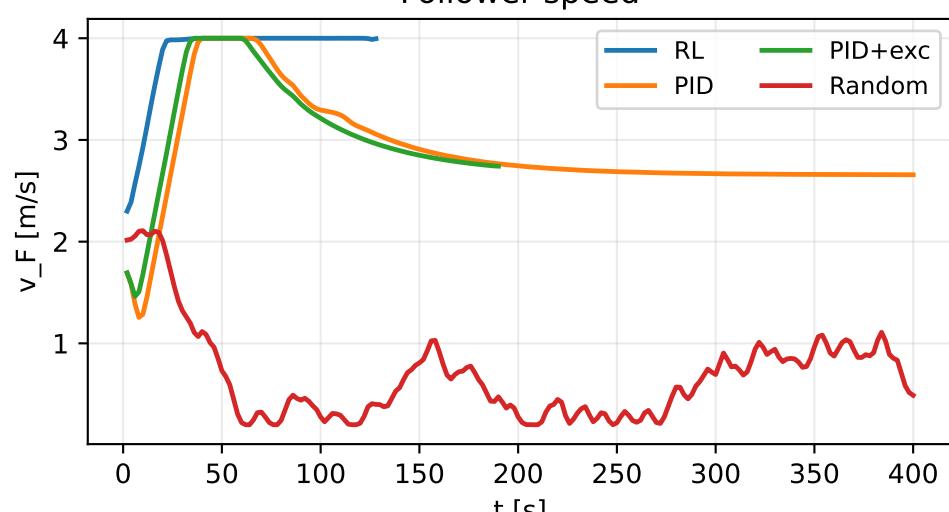
Estimator uncertainty (std_max)



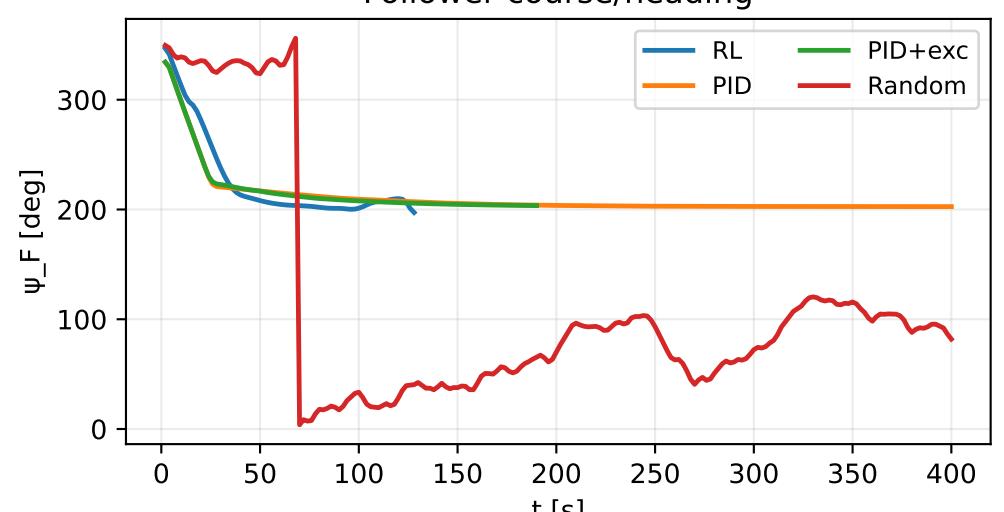
Information and excitation



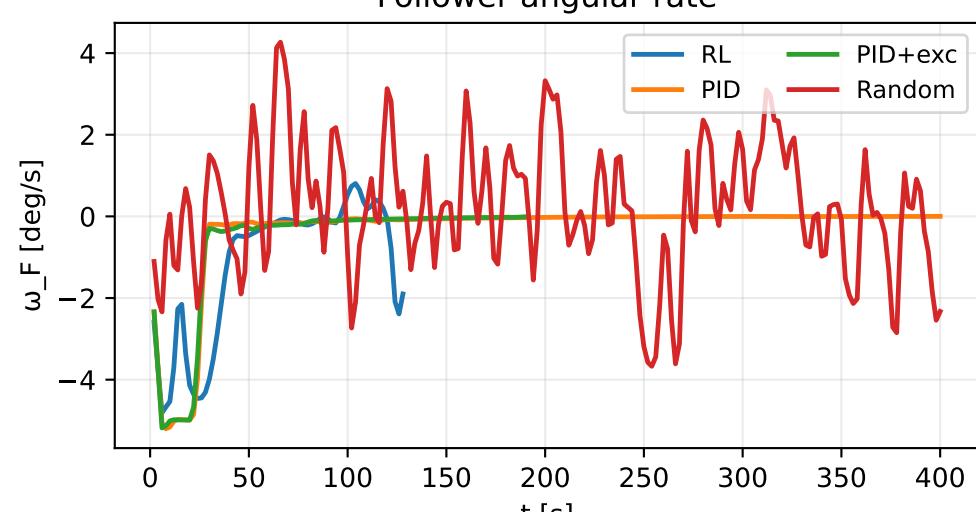
Follower speed



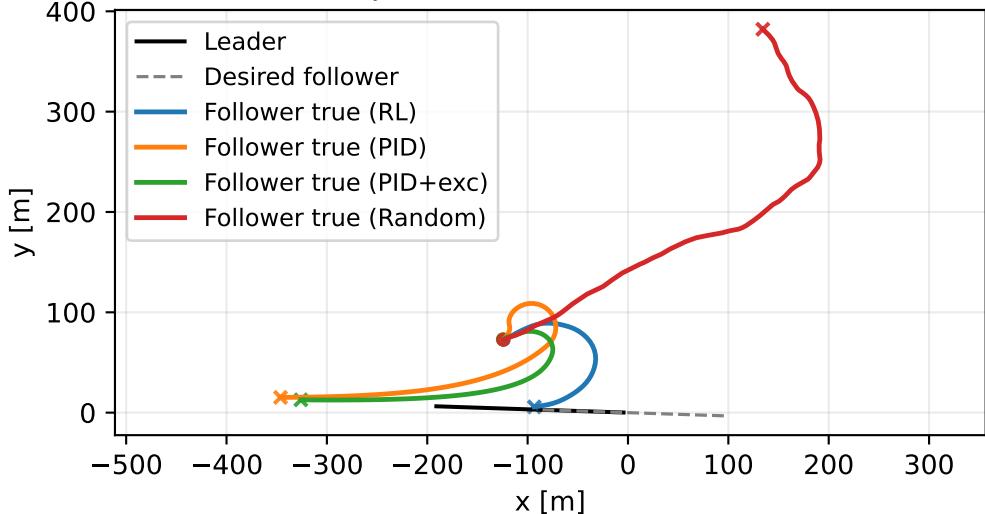
Follower course/heading



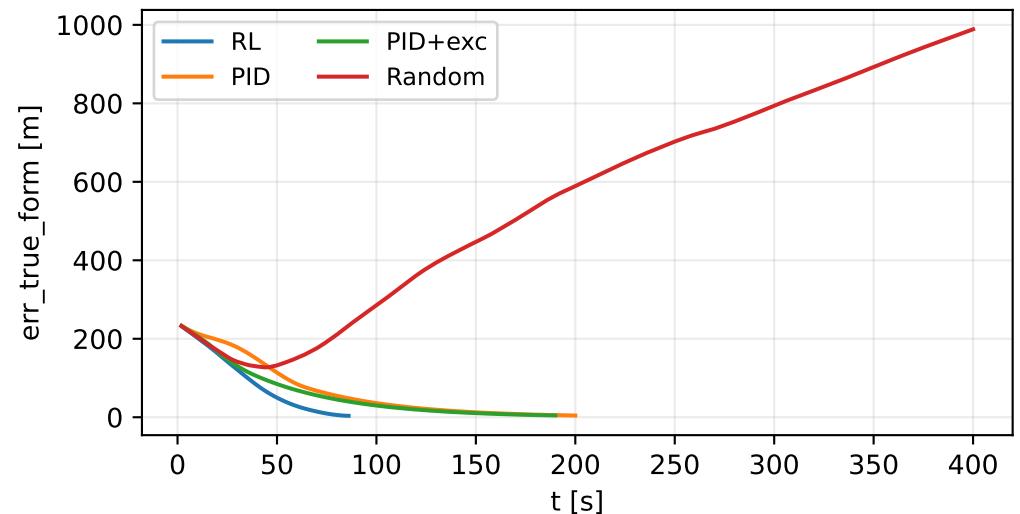
Follower angular rate



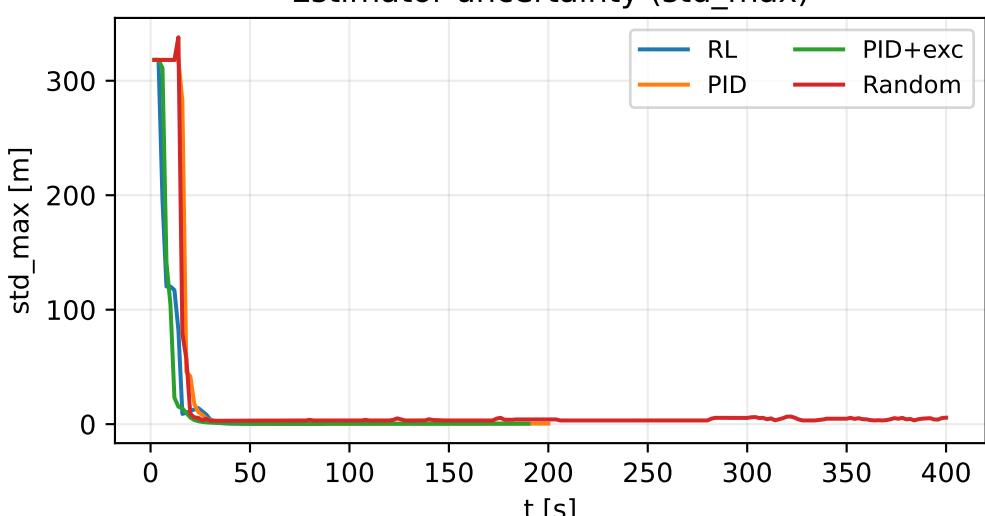
Trajectories (matched seed)



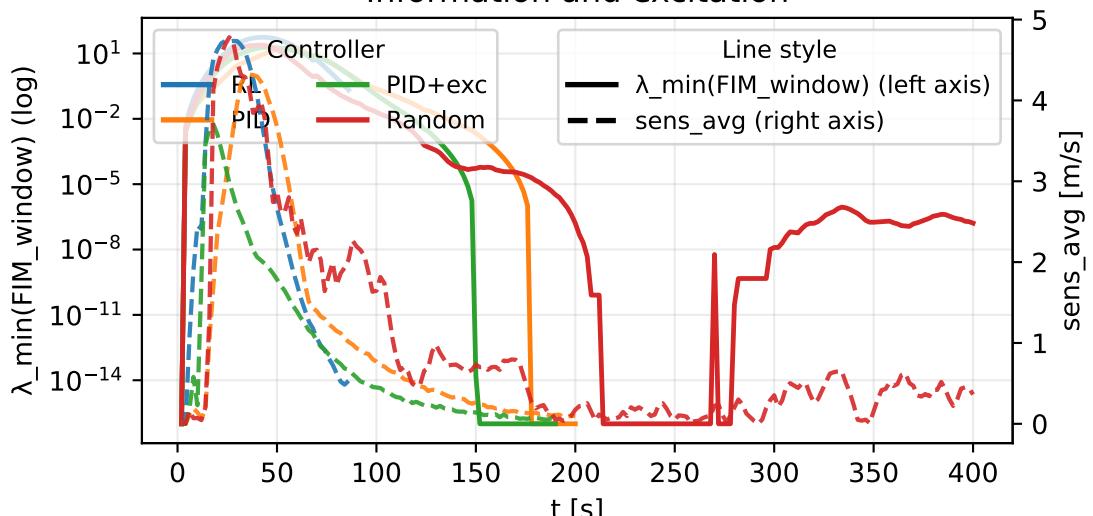
TRUE formation error



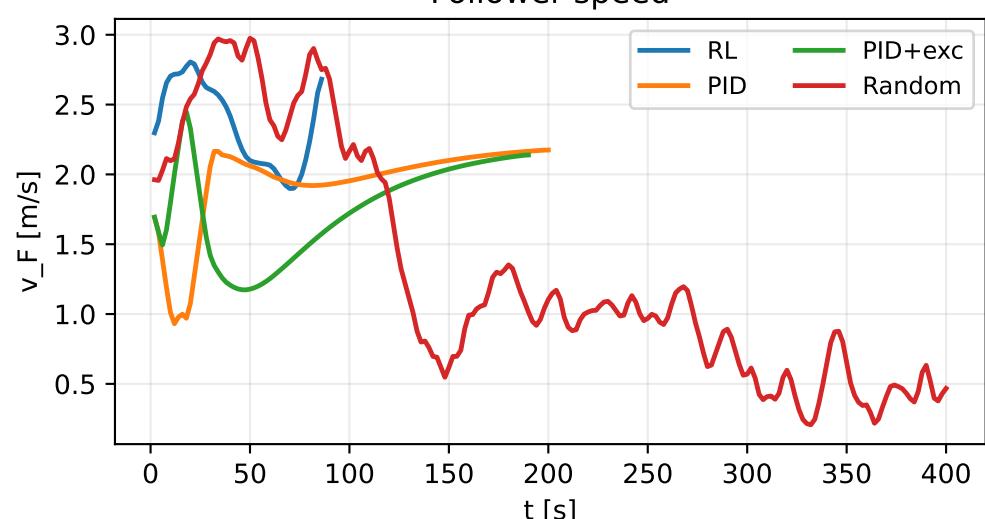
Estimator uncertainty (std_max)



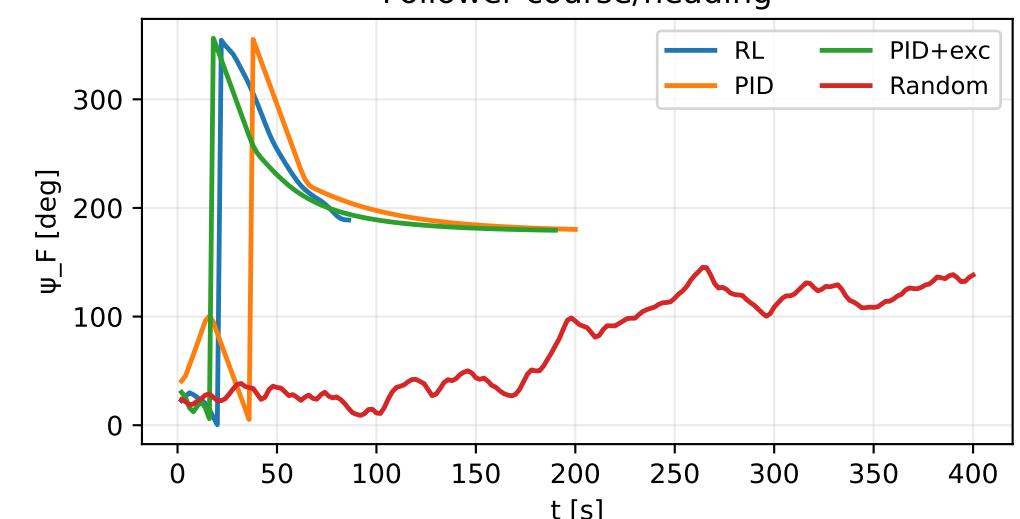
Information and excitation



Follower speed



Follower course/heating



Follower angular rate

