Proseminar: High Performance Computing Assignment 02

1 Exercise 1

1.1 Write a sequential application pi_seq in C or C++ that computes π for a given number of samples (command line argument). Test your application for various, large sample sizes to verify the correctness of your implementation.

```
#include <stdio.h>
2 #include <stdlib.h>
3 #include <math.h>
  double calculate_pi(int num_points) {
      int points_in_circle = 0;
6
      for (int count = 0; count < num_points; count++) {</pre>
           double random_x = (double)rand() / RAND_MAX;
9
           double random_y = (double)rand() / RAND_MAX;
10
           if (random_x * random_x + random_y * random_y <= 1.0) {</pre>
12
13
               points_in_circle++;
14
      }
15
16
       return 4.0 * points_in_circle / num_points;
17
18 }
19
int main(int argc, char *argv[]) {
      int total_points = atoi(argv[1]);
21
22
       double pi_approx = calculate_pi(total_points);
23
24
       printf("Approximation of Pi: %f\n", pi_approx);
25
26
       return 0;
27
28 }
```

Listing 1: Sequential Pi Approximation

1.2 Consider a parallelization strategy using MPI. Which communication pattern(s) would you choose and why?

As there are no dependencies while generating random points and checking if they lie in the circle, we can do that individually per rank. So we can just split the problem size N into $N \div n_{ranks}$ chunks. At the end one core have to retrieve the number of points in circle from all other cores, build a sum out of it and calculate π with it.

For this we would use MPI_Reduce(...) as it can collect a variable from all ranks and directly use operations as addition by giving reduce the operation type MPI_SUM.

1.3 Implement your chosen parallelization strategy as a second application pi_mpi. Run it with varying numbers of ranks and sample sizes and verify its correctness by comparing the output to pi_seq.

```
#include <stdio.h>
#include <stdlib.h>
#include <math.h>
#include <mpi.h>
```

```
6 void calculate_pi(int num_points, int rank, int numProcs) {
       // WTime Initialization
       double starttime, endtime;
       starttime = MPI_Wtime();
9
10
       // Define how many points each rank generates and generate them
       int points_for_rank = round(num_points / numProcs);
       int points_in_circle_in_rank = 0;
12
       int points_in_circle_global = 0;
13
14
15
       for (int count = 0; count < points_for_rank; count++) {</pre>
           double random_x = (double)rand() / RAND_MAX;
16
           double random_y = (double)rand() / RAND_MAX;
17
18
           if (random_x * random_x + random_y * random_y <= 1.0) {</pre>
19
20
                points_in_circle_in_rank++;
21
       }
22
       // Gather results from all ranks
23
       MPI_Reduce(&points_in_circle_in_rank, &points_in_circle_global, 1, MPI_INT, MPI_SUM, 0,
24
       MPI_COMM_WORLD);
25
       if (rank == 0) {
26
           double pi_approx = 4.0 * points_in_circle_global / num_points;
27
           endtime = MPI_Wtime();
28
           \label{lem:printf("WTime: \%f seconds n", endtime - starttime);} printf("Approximation of Pi: \%f n", pi_approx);
29
30
31
32 }
33
int main(int argc, char *argv[]) {
       // MPI Initialization
35
36
       MPI_Init(&argc, &argv);
       int rank, numProcs;
37
       MPI_Comm_rank(MPI_COMM_WORLD, &rank);
38
       MPI_Comm_size(MPI_COMM_WORLD, &numProcs);
39
40
41
       int total_points = atoi(argv[1]);
42
43
       if (rank == 0) {
           printf("Total Points used for Approximation: %i \n", total_points);
44
45
46
47
       calculate_pi(total_points, rank, numProcs);
48
       MPI_Finalize();
49
50
       return 0;
51 }
```

Listing 2: Parallel Pi Approximation

1.4 Discuss the effects and implications of your parallelization.

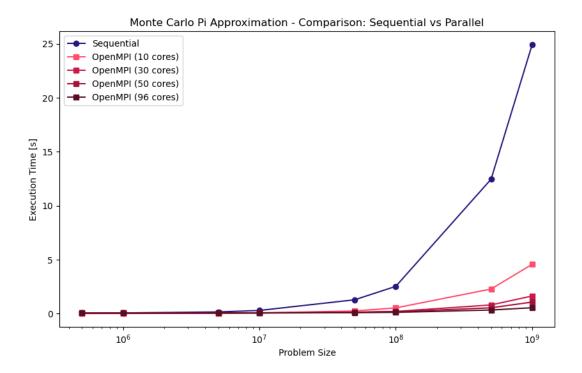


Figure 1: Monte Carlo Pi Approximation - Runtime Comparison

When running the experiment with a problem size below 10^7 the sequential code and the parallelized code have around the same runtimes. If more than 10^7 points are used the execution time of the the sequential program grows rapidly. By adding more cores the highest problem size (10^9) gets faster computed. The execution time for 10^9 points is 5x faster with 96 cores instead of just 10.

2 Exercise 2

2.1 A sequential implementation of a 1-D heat stencil is available in heat_stencil_1D_seq.c. Read the code and make sure you understand what happens. See the Wikipedia article on Stencil Codes for more information.

Iterative Stencil Loops

- 2.2 Consider a parallelization strategy using MPI. Which communication pattern(s) would you choose and why? Are there additional changes required in the code beyond calling MPI functions? If so, elaborate!
 - Boundary-Exchange-Pattern (using MPI_Sendrecv), because exchanging boundary values between processes is essential for correct calculations in each section.
 - Broadcast-Pattern (with MPI_Bcast), to efficiently distribute initial data to all processes.
 - Gather-Pattern (with MPI_Gather), to collect results from individual processes at the end of the computation.

Additional changes that need to be made include implementing functionality that splits the problem into chunks that can be distributed via MPI. This also includes additional error handling to ensure that the input fits our strategy.

2.3 Implement your chosen parallelization strategy as a second application heat_stencil_1D_mpi. Run it with varying numbers of ranks and problem sizes and verify its correctness by comparing the output to heat_stencil_1D_seq.

```
#include <stdio.h>
#include <stdlib.h>
3 #include <mpi.h>
5 typedef double value_t;
7 #define RESOLUTION 120
9 // -- vector utilities --
typedef value_t *Vector;
13 Vector createVector(int N);
14
void releaseVector(Vector m);
16
void printTemperature(Vector m, int N);
18
19 // -- simulation code ---
20
int main(int argc, char **argv) {
   // 'parsing' optional input parameter = problem size
    int N = 2000;
23
    if (argc > 1) {
24
     N = atoi(argv[1]);
25
26
    int T = N * 500;
27
28
    // MPI Initialization
29
    MPI_Init(&argc, &argv);
30
    int rank, numProcs;
31
    MPI_Comm_rank(MPI_COMM_WORLD, &rank);
32
    MPI_Comm_size(MPI_COMM_WORLD, &numProcs);
33
34
    // Time measurement variables
35
    double starttime, endtime;
37
    // Calculate chunk size, start and end point for each process
38
39
    int chunkSize = N / numProcs;
    int remainder = N % numProcs;
40
41
    if (rank == 0) {
42
43
     if (remainder > 0) {
       printf("The problem size can't be evenly distributed to the number of processes. Please
44
      redefine it.");
45
        return 0;
      }
46
47
48
    int startIdx = rank * chunkSize;
49
50
    int endIdx = startIdx + chunkSize;
    printf("[DEBUG] Rank: %i, ChunkSize: %i, startIdx: %i, endIdx: %i \n", rank, chunkSize, startIdx,
51
       endIdx);
52
53
    // create a buffer for storing temperature fields
54
    Vector A = createVector(N);
    int source_x = N / 4;
56
57
58
    if (rank == 0) {
59
60
      printf("Computing heat-distribution for room size N=%d for T=%d timesteps\n", N, T);
61
```

```
// ----- setup -----
62
       // set up initial conditions in A
63
       for (int i = 0; i < N; i++) {</pre>
64
        A[i] = 273; // temperature is 0 C everywhere (273 K)
65
66
67
       // and there is a heat source in one corner
68
       A[source_x] = 273 + 60;
69
70
       printf("Initial:\t");
71
       printTemperature(A, N);
72
       printf("\n");
73
74
75
     // Distribute A to all processes
76
     MPI_Bcast(A, N, MPI_DOUBLE, 0, MPI_COMM_WORLD);
77
     printf("[DEBUG] Broadcasted A to every rank for computation. \n");
78
79
     // Start time measurement before the computation begins
80
     starttime = MPI_Wtime();
81
82
     // ----- compute -----
83
84
     \ensuremath{//} create a second buffer for the computation and initialize with A
85
     Vector B = createVector(chunkSize);
86
87
     Vector C = createVector(chunkSize);
     for (int i = startIdx; i < endIdx; i++) {</pre>
88
         B[i - startIdx] = A[i];
89
90
91
     // create variables for the neighbours
     value_t rightNeighbour = 0;
92
93
     value_t leftNeighbour = 0;
94
95
     // for each time step ..
96
97
     for (int t = 0; t < T; t++) {</pre>
       // \ {\tt Exchange boundary values with neighboring processes}
98
       // printf("[DEBUG] Rank %i started with timestep %i. \n", rank, t);
99
       if ((rank > 0) & (rank < numProcs - 1)) {</pre>
100
         // printf("[DEBUG] Rank %i tries to send and receive right boundary element ... n, rank);
         MPI_Sendrecv(&B[0], 1, MPI_DOUBLE, rank - 1, 0, &rightNeighbour, 1, MPI_DOUBLE, rank + 1, 0,
       MPI_COMM_WORLD, MPI_STATUS_IGNORE);
         // printf("[DEBUG] Rank %i send and received right boundary element. \n", rank);
104
         //printf("[DEBUG] Rank %i tries to send and receive left boundary element ... \n", rank);
         MPI_Sendrecv(&B[chunkSize - 1], 1, MPI_DOUBLE, rank + 1, 1, &leftNeighbour, 1, MPI_DOUBLE,
106
       rank - 1, 1, MPI_COMM_WORLD, MPI_STATUS_IGNORE);
         //printf("[DEBUG] Rank %i send and received left boundary element. \n", rank);
108
       if (rank == 0) {
109
         //printf("[DEBUG] Rank %i tries to receive right boundary element \dots \n", rank);
         MPI_Sendrecv(&B[chunkSize - 1], 1, MPI_DOUBLE, rank + 1, 1, &rightNeighbour, 1, MPI_DOUBLE,
111
       rank + 1, 0, MPI_COMM_WORLD, MPI_STATUS_IGNORE);
         // printf("[DEBUG] Rank %i sent received right boundary element and sent left one. \n", rank)
112
113
       if (rank == numProcs - 1) {
114
         //printf("[DEBUG] Rank %i tries to receive left boundary element ... \n", rank);
         MPI_Sendrecv(&B[0], 1, MPI_DOUBLE, rank - 1, 0, &leftNeighbour, 1, MPI_DOUBLE, rank - 1, 1,
116
       MPI_COMM_WORLD , MPI_STATUS_IGNORE);
         //printf("[DEBUG] Rank %i received left boundary element and sent right one. \n", rank);
117
118
       // .. we propagate the temperature
120
       for (long long i = startIdx; i < endIdx; i++) {</pre>
121
         // center stays constant (the heat is still on)
         if (i == source_x) {
123
           C[i - startIdx] = B[i - startIdx];
```

```
continue;
125
126
127
         // get temperature at current position
128
         value_t tc = B[i - startIdx];
130
         // get temperatures of adjacent cells
131
         value_t tl;
132
         if (i == startIdx) {
           t1 = (rank > 0) ? leftNeighbour : tc;
134
         } else {
135
             tl = B[i - 1- startIdx];
136
137
         value_t tr;
138
139
         if (i == endIdx - 1) {
             tr = (rank < numProcs - 1) ? rightNeighbour : tc;</pre>
140
         } else {
141
             tr = B[i - startIdx + 1];
142
143
144
         // compute new temperature at current position
145
146
         C[i - startIdx] = tc + 0.2 * (tl + tr + (-2 * tc));
147
148
       Vector H = B;
149
       B = C;
150
       C = H;
151
152
       if (t % 10000 == 0) {
153
154
         MPI_Gather(B, chunkSize, MPI_DOUBLE, A, chunkSize, MPI_DOUBLE, 0, MPI_COMM_WORLD);
155
156
         if (rank == 0) {
           printf("Step t=%d:\t", t);
157
           printTemperature(A, N);
           printf("\n");
159
160
       }
161
     }
162
     MPI_Gather(B, chunkSize, MPI_DOUBLE, A, chunkSize, MPI_DOUBLE, O, MPI_COMM_WORLD);
164
165
     releaseVector(B);
166
167
168
     // End time measurement after computation
     endtime = MPI_Wtime();
169
170
     // ----- check -----
     int success = 1;
172
173
     if (rank == 0) {
174
175
       printf("Final:\t\t");
       printTemperature(A, N);
176
177
       printf("\n");
178
       for (long long i = 0; i < N; i++) {</pre>
179
         value_t temp = A[i];
180
         if (273 <= temp && temp <= 273 + 60)
181
           continue;
182
         success = 0;
183
         break;
184
185
186
       printf("Verification: %s\n", (success) ? "OK" : "FAILED");
187
188
       // Print the time
189
       printf("WTime: %f seconds\n", endtime - starttime);
190
191
```

```
// ----- cleanup -----
193
194
195
     releaseVector(A);
196
197
     // done
     MPI_Finalize();
198
     return (success) ? EXIT_SUCCESS : EXIT_FAILURE;
199
200 }
201
202 Vector createVector(int N) {
    // create data and index vector
203
     return malloc(sizeof(value_t) * N);
204
205 }
206
void releaseVector(Vector m) { free(m); }
208
void printTemperature(Vector m, int N) {
     const char *colors = " .-:=+*^X#%0";
210
     const int numColors = 12;
211
212
     // boundaries for temperature (for simplicity hard-coded)
213
     const value_t max = 273 + 30;
214
     const value_t min = 273 + 0;
215
216
     // set the 'render' resolution
217
     int W = RESOLUTION;
218
219
     // step size in each dimension
220
     int sW = N / W;
221
222
     // room
223
224
     // left wall
     printf("X");
225
     // actual room
     for (int i = 0; i < W; i++) {</pre>
227
228
       // get max temperature in this tile
       value_t max_t = 0;
229
       for (int x = sW * i; x < sW * i + sW; x++) {
230
         max_t = (max_t < m[x]) ? m[x] : max_t;
232
       value_t temp = max_t;
233
234
       // pick the 'color'
235
       int c = ((temp - min) / (max - min)) * numColors;
236
       c = (c \ge numColors) ? numColors - 1 : ((c < 0) ? 0 : c);
237
238
       // print the average temperature
239
       printf("%c", colors[c]);
240
241
     // right wall
242
243
     printf("X");
244 }
```

Listing 3: Parallel propagation

2.4 Discuss the effects and implications of your parallelization.

1. Performance Improvements

With MPI, the problem is split into parts, and each process (rank) works on one part. This way, the work is shared between cores or nodes, which makes the simulation faster compared to the sequential version.

2. Data Communication Overhead

The parallel version needs processes to exchange boundary information using MPI_Sendrecv. This adds communication overhead, especially as the number of processes increases. Also, collective functions like MPI_Bcast and MPI_Gather make all processes wait for each other, which can slow down the program if not managed well.

3. Scalability Considerations

Each process handles the same amount of work. But if the problem size does not divide evenly between processes (e.g., N%numProcs $\neq 0$), the program stops. More processes can also increase communication overhead, especially if there is too much communication compared to the actual computation.

4. Potential Bottlenecks

Global synchronization using MPI_Bcast and MPI_Gather can cause delays because all processes must wait for the slowest one to finish its work. This may lead to idle time, reducing efficiency.