

Extending the Iris Proof Mode with Inductive Predicates using Elpi

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Program verification

- Verify programs by specifying pre and post conditions
- Specification happens in separation logic
- We make use of embeddings of separation logic in a proof assistant
- Iris (Jung, Krebbers, Jourdan, Bizjak, Birkedal, and Dreyer 2018) & Coq (Huet, Kahn, and Paulin-Mohring 2002)


Separation logic with Hoare triples

$$[\text{isD } d \ y] \text{ op } d \times [\text{isD } d \ (f \times y)]$$

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Imperative
program



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Imperative
program

Functional
program

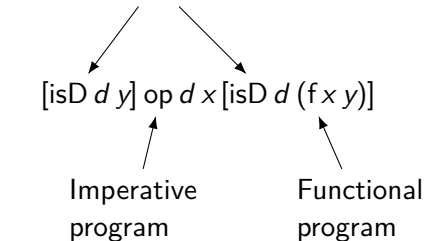
Separation logic with Hoare triples

Representation predicate

$[isD\ d\ y]\ op\ d\ x\ [isD\ d\ (f\ x\ y)]$

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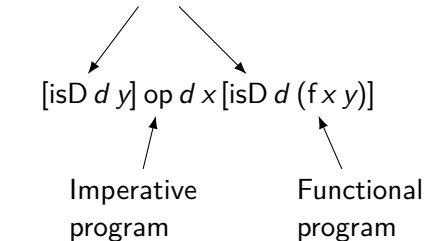
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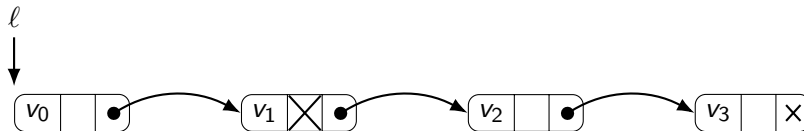
Imperative
program

Functional
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$[isList\ hd\ \vec{v}]\ delete\ hd\ i\ [isList\ hd\ (remove\ i\ \vec{v})]$

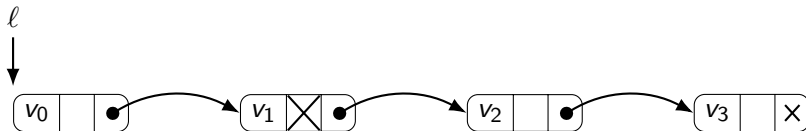
Representation predicates

Representation predicates



Harris (2001)

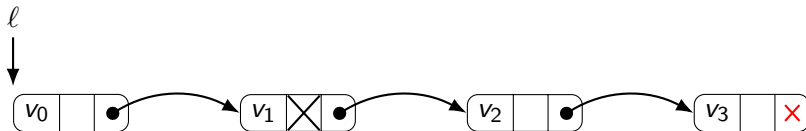
Representation predicates



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$$\begin{aligned} \text{isMLL } hd \vec{v} = & (hd = \mathbf{none} * \vec{v} = []) \vee \\ & (\exists \ell, \check{v}, tl. hd = \mathbf{some } l * l \mapsto (\check{v}, \mathbf{true}, tl) * \text{isMLL } tl \vec{v}) \vee \\ & \left(\begin{array}{l} \exists \ell, \check{v}, \vec{v}'', tl. hd = \mathbf{some } l * l \mapsto (\check{v}, \mathbf{false}, tl) * \\ \vec{v} = \check{v} :: \vec{v}'' * \text{isMLL } tl \vec{v}'' \end{array} \right) \end{aligned}$$

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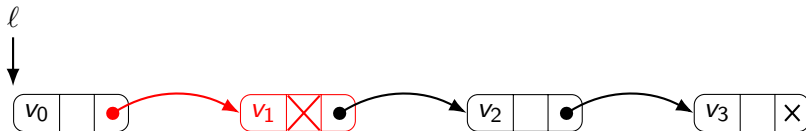
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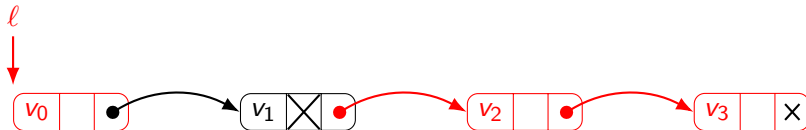
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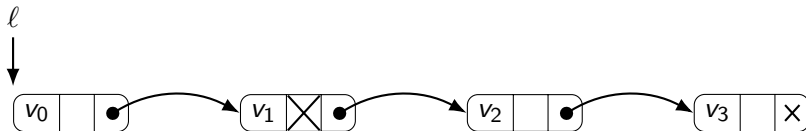
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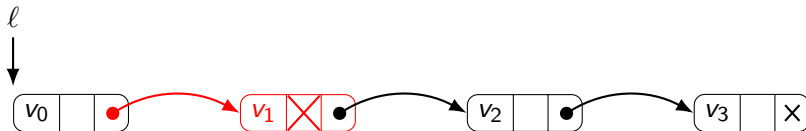
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Outline of our solution

```
1  eiInd                                                                    Coq
2  Inductive is_MLL : val → list val → iProp :=
3      | empty_is_MLL : is_MLL NONEV []
4      | mark_is_MLL v vs l tl :
5          l ↦ (v, #true, tl) -* is_MLL tl vs -*
6          is_MLL (SOMEV #l) vs
7      | cons_is_MLL v vs tl l :
8          l ↦ (v, #false, tl) -* is_MLL tl vs -*
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- Definition of `is_MLL`

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- Definition of `is_MLL`
- Proof of constructors, `empty_is_MLL`, `mark_is_MLL`, `cons_is_MLL`

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- Proof of induction principle

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```

- Definition of `is_MLL`
- Proof of constructors, `empty_is_MLL`, `mark_is_MLL`, `cons_is_MLL`
- Proof of induction principle
- Integration with IPM tactics

Approach

Theory

Challenges in practice

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- Define the pre fixpoint function

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- Prove monotonicity

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Challenges in practice

- Deal with n -ary predicates
- Proof search for monotonicity
- Integrating resulting definitions and lemmas into the Iris tactics language

Contributions

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- Posed a strategy for defining modular tactics in Elpi
- Posed a syntactic proof search algorithm for finding a monotonicity proof of a pre fixpoint function
- Evaluated Elpi as a meta-programming language for the IPM

Monotone pre fixpoint function

$$\begin{aligned} \text{isMLL } hd \vec{v} = & (hd = \mathbf{none} * \vec{v} = []) \vee \\ & (\exists \ell, v', tl. hd = \mathbf{some } l * l \mapsto (v', \mathbf{true}, tl) * \text{isMLL } tl \vec{v}) \vee \\ & \left(\begin{array}{l} \exists \ell, v', \vec{v}'', tl. hd = \mathbf{some } l * l \mapsto (v', \mathbf{false}, tl) * \\ \vec{v} = v' :: \vec{v}'' * \text{isMLL } tl \vec{v}'' \end{array} \right) \end{aligned}$$

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Definition (Monotone predicate)

Function $F: (A \rightarrow iProp) \rightarrow A \rightarrow iProp$ is *monotone* when, for any $\Phi, \Psi: A \rightarrow iProp$, it holds that

$$\Box(\forall y. \Phi y \multimap \Psi y) \vdash \forall x. F \Phi x \multimap F \Psi x$$

Monotonicity as a signature

Definition (Proper element of a relation (Sozeau 2009))

Given a relation $R: iRel\ A$ and an element $x \in A$, x is a proper element of R if $R\ x\ x$.

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$$R \Longrightarrow R' \triangleq \lambda f, g. \forall x, y. R\ x\ y \multimap R'\ (f\ x)\ (g\ y)$$

Definition (Pointwise relation)

$$\triangleright R \triangleq \lambda f, g. \forall x. R\ (f\ x)\ (g\ x)$$

Definition (Persistent relation)

$$\Box R \triangleq \lambda x, y. \Box(R\ x\ y)$$

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$$\text{isMLL}_F: (Val \rightarrow List\ Val \rightarrow iProp) \rightarrow \\ Val \rightarrow List\ Val \rightarrow iProp$$

$$\Box (\forall hd\ \vec{v}. \Phi\ hd\ \vec{v} \multimap \Psi\ hd\ \vec{v}) \multimap \\ \left(\begin{array}{c} \forall hd\ \vec{v}. \text{isMLL}_F\ \Phi\ hd\ \vec{v} \multimap \\ \text{isMLL}_F\ \Psi\ hd\ \vec{v} \end{array} \right)$$

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$\Box (\triangleright \triangleright (-)) \implies \triangleright \triangleright (-)$

Monotone signatures

Connective	Type	Signature
$*$	$iProp \rightarrow iProp \rightarrow iProp$	$(-*) \Longrightarrow (-*) \Longrightarrow (-*)$
\vee	$iProp \rightarrow iProp \rightarrow iProp$	$(-*) \Longrightarrow (-*) \Longrightarrow (-*)$
\neg	$iProp \rightarrow iProp \rightarrow iProp$	$\text{flip}(-*) \Longrightarrow (-*) \Longrightarrow (-*)$
\exists	$(A \rightarrow iProp) \rightarrow iProp$	$\triangleright(-*) \Longrightarrow (-*)$

Signature	Semantics
$(-*) \Longrightarrow (-*) \Longrightarrow (-*)$	$\forall P, P'. (P * P') \neg * \forall Q, Q'. (Q \neg * Q') \neg * (P * Q) \neg * (P' * Q')$
$(\triangleright(-*) \Longrightarrow (-*))$	$\forall \Phi, \Psi. (\forall x. \Phi x \neg * \Psi x) \neg * (\exists x. \Phi x) \neg * (\exists x. \Psi x)$

Proof search

$$\square (\forall hd \vec{v}. \Phi \, hd \, \vec{v} \multimap \Psi \, hd \, \vec{v}) \multimap$$
$$\left(\begin{array}{l} \forall hd \, \vec{v}. \text{isMLL}_F \, \Phi \, hd \, \vec{v} \multimap \\ \text{isMLL}_F \, \Psi \, hd \, \vec{v} \end{array} \right)$$

Normalization

- Introduce quantifiers and modalities
→ Application step

Application

- Apply reflexivity
- Apply assumption
- Apply signature → Normalization step

Proof search

$$\begin{aligned}
 & (hd = \mathbf{none} * \vec{v} = []) \vee \\
 & \left(\begin{array}{l} \exists \ell, \check{v}, tl. hd = \mathbf{some} \ell * \\ l \mapsto (\check{v}, \mathbf{true}, tl) * \\ \Phi \, tl \, \vec{v} \end{array} \right) \vee \\
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 & \rightarrow *
 \end{aligned}$$

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Proof search

$$(hd = \mathbf{none} * \vec{v} = [])$$
$$\rightarrow *$$
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Proof search

$(hd = \mathbf{none} * \vec{v} = [])$

\rightarrow^*

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$$\begin{aligned} &\Box (\forall hd \vec{v}. \Phi \text{ } hd \vec{v} \multimap \Psi \text{ } hd \vec{v}) \\ &\vdash \Phi \text{ } t / \vec{v} \multimap \Psi \text{ } t / \vec{v} \end{aligned}$$

Normalization

- Introduce quantifiers and modalities
→ Application step

Application

- Apply reflexivity
- Apply assumption
- Apply signature → Normalization step

Proof search

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Least fixpoint

Theorem (Least fixpoint)

Given a monotone function $F: (A \rightarrow iProp) \rightarrow A \rightarrow iProp$, called the pre fixpoint function, there exists the least fixpoint

$$\mu F: A \rightarrow iProp \triangleq \lambda F x. \forall \Phi. \Box(\forall y. F \Phi y \multimap \Phi y) \multimap \Phi x$$

such that

- 1 The fixpoint equality holds

$$\mu F x \dashv\vdash F(\mu F) x$$

- 2 The iteration property holds

$$\Box(\forall y. F \Phi y \multimap \Phi y) \vdash \forall x. \mu F x \multimap \Phi x$$

Elpi

- λ Prolog dialect (Dunchev, Guidi, Coen, and Tassi 2015)

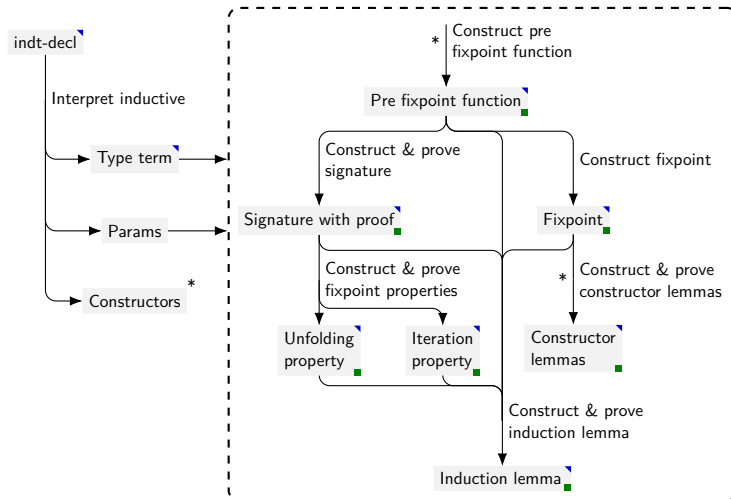
Elpi

- λ Prolog dialect (Dunchev, Guidi, Coen, and Tassi 2015)
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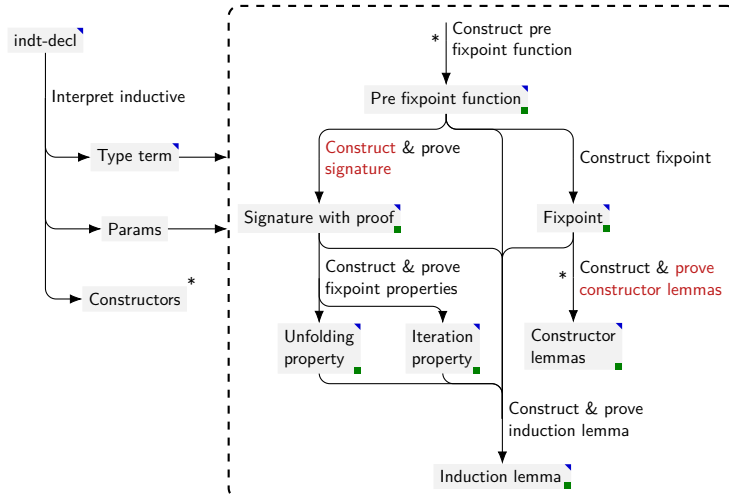
Elpi

- λ Prolog dialect (Dunchev, Guidi, Coen, and Tassi 2015)
- Coq meta-programming language (Tassi 2018)
- Derive (Tassi 2019)
- Hierarchy Builder (Cohen, Sakaguchi, and Tassi 2020)
- Trocq (Cohen, Crance, and Mahboubi 2024)

Outline of implementation



Outline of implementation



Coq-Elpi HOAS

1 `val → list val → iProp`

Coq

Coq-Elpi HOAS

1	<code>val → list val → iProp</code>	Coq
---	-------------------------------------	-----

1	<code>∀ _:val. ∀ _:list val. iProp</code>	Coq
---	---	-----

Coq-Elpi HOAS

```
1 val → list val → iProp
```

Coq

```
1 ∀ _:val. ∀ _:list val. iProp
```

Coq

```
1 prod `_` (global (indt «val»))
2   c0 \
3     prod `_` (app [global (indt «list»),
4                   global (indt «val»)]
5     c1 \
6       app [global (indt «uPred»),
7            app [global (const «iResUR»),
8                global (const «Σ»)]])
```

Elpi

Generating terms

```
1  pred type->proper i:term, i:term, o:term.
2  type->proper PreFixF Type Proper :-
3      type->proper.aux Type P,
4      coq.elaborate-skeleton
5          {{ IProp (□> lp:P ==> lp:P) lp:PreFixF }}
6          {{ Prop }} Proper ok.
7
8  pred type->proper.aux i:term, o:term.
9  type->proper (prod N T F) {{ .> lp:P }} :-
10     pi x\ type->proper (F x) P.
11 type->proper {{ iProp }} {{ bi_wand }}.
```

Elpi

Generating proofs

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- They depend on typeclass search to find the next step to prove
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- These modular proof term generators are also repackaged into a new set of IPM tactics, e.g. `eiIntros` (Elpi Iris Intros).

Holes in proofs

```
1 kind hole type.
2 type hole term -> term -> hole.
```

Elpi

```
1 pred do-iLeft i:hole, o:hole.
2 do-iLeft (hole Type Proof) (hole LeftType LeftProof) :-
3   @no-tc! => coq.elaborate-skeleton
4             {{ tac_or_l _ _ _ _ _ }}
5             Type Proof ok,
6   Proof = {{ tac_or_l _ _ _ _ lp:FromOr lp:LeftProof }},
7   coq.ltac.collect-goals FromOr [G1] _,
8   open tc_solve G1 [],
9   coq.typecheck LeftProof LeftType ok.
```

Elpi

Composing proof generators

```
1  hd : val
2  vs : list val
3  -----
4  is_MLL_pre is_MLL hd vs  $\dashv$  is_MLL hd vs
```

Coq

```
1  pred mk-unfold.proof i:int, i:term, i:term, i:hole.
2  mk-unfold.proof Ps Unfold1 Unfold2 H :-
3    do-iStartProof H (ihole N H'), !,
4    do-iAndSplit H' H1 H2,
5    std.map {std.iota Ps} (x\r\ r = {{ _ }}) Holes1, !,
6    do-iApplyLem (app [Unfold1 | Holes1]) (ihole N H1) [] [], !,
7    std.map {std.iota Ps} (x\r\ r = {{ _ }}) Holes2, !,
8    do-iApplyLem (app [Unfold2 | Holes2]) (ihole N H2) [] [].
```

Elpi

Demo

Evaluation of Elpi

Conclusion

- Proof search algorithm for monotonicity of pre fixpoint functions

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- Elpi implementation

Future work

- Non-expansive predicates
- Other fixpoint predicates
- Nested inductive predicates
- Mutual inductive predicates