# Extending the Iris Proof Mode with Inductive Predicates using Elpi

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• Verify programs by specifying pre and post conditions

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- Specification happens in separation logic

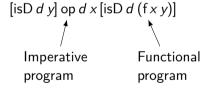
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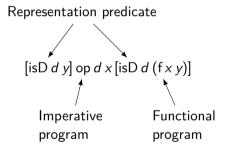
- Verify programs by specifying pre and post conditions
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- We make use of embeddings of separation logic in Coq
- Iris 2015 (Jung, Krebbers, et. al.)

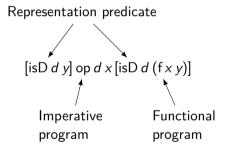
[isD d y] op d x [isD d (f x y)]

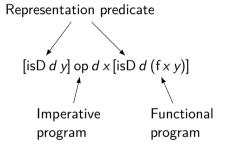
```
[isD dy] op dx [isD d(fxy)]

Imperative
program
```

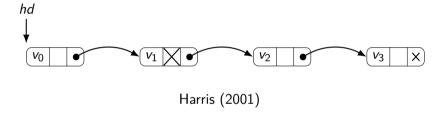


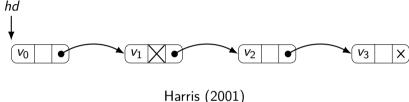






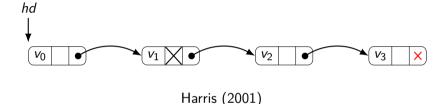
[isList  $hd \vec{v}$ ] delete hd i [isList hd (remove  $i \vec{v}$ )]



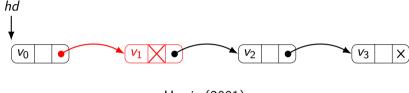


Harris (2001

$$\text{isMLL } \textit{hd} \, \overrightarrow{\textit{v}} = \, \left( \textit{hd} = \mathsf{none} * \overrightarrow{\textit{v}} = [] \right) \vee \\ \left( \exists \ell, \, \checkmark, \, tl. \, \textit{hd} = \mathsf{some} \, \ell * \ell \mapsto (\checkmark, \mathsf{true}, \, tl) * \mathsf{isMLL} \, tl \, \overrightarrow{\textit{v}} \right) \vee \\ \left( \begin{array}{c} \exists \ell, \, \checkmark, \, \overrightarrow{\textit{v}}'', \, tl. \, \textit{hd} = \mathsf{some} \, \ell * \ell \mapsto (\checkmark, \, \mathsf{false}, \, tl) * \\ \overrightarrow{\textit{v}} = \checkmark :: \, \overrightarrow{\textit{v}}'' * \mathsf{isMLL} \, tl \, \overrightarrow{\textit{v}}'' \end{array} \right)$$

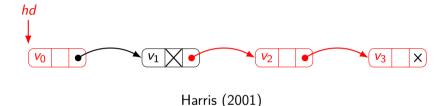


$$\text{isMLL } \textit{hd} \, \overrightarrow{\textit{v}} = \underbrace{(\textit{hd} = \texttt{none} * \overrightarrow{\textit{v}} = [])} \lor \\ (\exists \ell, \, \forall, \, \textit{tl. } \textit{hd} = \texttt{some} \, \ell * \ell \mapsto (\forall, \, \texttt{true}, \, \textit{tl}) * \texttt{isMLL} \, \textit{tl} \, \overrightarrow{\textit{v}}) \lor \\ \left( \exists \ell, \, \forall, \, \overrightarrow{\textit{v}}'', \, \textit{tl. } \textit{hd} = \texttt{some} \, \ell * \ell \mapsto (\forall, \, \texttt{false}, \, \textit{tl}) * \\ \overrightarrow{\textit{v}} = \forall \, :: \, \overrightarrow{\textit{v}}'' * \texttt{isMLL} \, \textit{tl} \, \overrightarrow{\textit{v}}'' \end{aligned} \right)$$

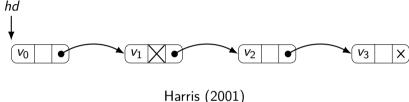


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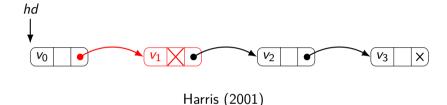


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Definition of is\_MLL

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- Proof of constructors,empty\_is\_MLL,mark\_is\_MLL,cons\_is\_MLL

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- Integration with IPM tactics

Theory

#### Theory

Define the pre fixpoint function

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- Define the pre fixpoint function
- Prove monotonicity

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#### Challenges in practice

• Deal with *n*-ary predicates

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- Proof search for monotonicity

#### Theory

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- Deal with *n*-ary predicates
- Proof search for monotonicity
- Integrating resulting definitions and lemmas into the Iris tactics language

# Monotone pre fixpoint function

$$\text{isMLL } \textit{hd} \, \overrightarrow{\textit{v}} = \, \left( \textit{hd} = \mathsf{none} * \overrightarrow{\textit{v}} = [] \right) \vee \\ \left( \exists \ell, \, \forall, \, tl. \, \textit{hd} = \mathsf{some} \, \textit{l} * \textit{l} \mapsto ( \forall, \mathsf{true}, \textit{tl} ) * \mathsf{isMLL} \, \textit{tl} \, \overrightarrow{\textit{v}} \right) \vee \\ \left( \begin{array}{c} \exists \ell, \, \forall, \, \overrightarrow{\textit{v}}'', \, \textit{tl.} \, \textit{hd} = \mathsf{some} \, \textit{l} * \textit{l} \mapsto ( \forall, \, \mathsf{false}, \textit{tl} ) * \\ \overrightarrow{\textit{v}} = \forall :: \, \overrightarrow{\textit{v}}'' * \mathsf{isMLL} \, \textit{tl} \, \overrightarrow{\textit{v}}'' \end{array} \right)$$

# Monotone pre fixpoint function

$$\text{isMLL}_{\mathsf{F}} \varPhi \, hd \, \overrightarrow{v} = \, \left( hd = \mathsf{none} * \overrightarrow{v} = [] \right) \lor \\ \left( \exists \ell, \, \forall, \, tl. \, hd = \mathsf{some} \, l * \, l \mapsto \left( \forall, \, \mathsf{true}, \, tl \right) * \varPhi \, tl \, \overrightarrow{v} \right) \lor \\ \left( \begin{array}{c} \exists \ell, \, \forall, \, \overrightarrow{v}'', \, tl. \, hd = \, \mathsf{some} \, l * \, l \mapsto \left( \forall, \, \mathsf{false}, \, tl \right) * \\ \overrightarrow{v} = \forall :: \, \overrightarrow{v}'' * \varPhi \, tl \, \overrightarrow{v}'' \end{array} \right)$$

# Monotone pre fixpoint function

$$\begin{split} \mathsf{isMLL_F}\,\varPhi\,hd\,\vec{\,v} = & \left( hd = \mathsf{none} * \vec{\,v} = [] \right) \lor \\ & \left( \exists \ell, \, \forall, \, tl. \, hd = \mathsf{some} \, l * \, l \mapsto (\forall, \, \mathsf{true}, \, tl) * \varPhi \, tl \, \vec{\,v} \right) \lor \\ & \left( \begin{array}{c} \exists \ell, \, \forall, \, \vec{\,v}'', \, tl. \, hd = \mathsf{some} \, l * \, l \mapsto (\forall, \, \mathsf{false}, \, tl) * \\ \vec{\,v} = \forall \, :: \, \vec{\,v}'' * \varPhi \, tl \, \vec{\,v}'' \end{array} \right) \end{split}$$

### Definition (Monotonicity)

Function F:  $(A \to B \to iProp) \to A \to B \to iProp$  is *monotone* when, for any  $\Phi, \Psi: A \to B \to iProp$ , it holds that

$$\Box(\forall x, y. \Phi xy \twoheadrightarrow \Psi xy) \vdash \forall x, y. F \Phi xy \twoheadrightarrow F \Psi xy$$

### Monotone signatures

### Definition (Respectful relation)

$$R \Longrightarrow R' \triangleq \lambda f, g. \ \forall x, y. \ R \times y \twoheadrightarrow R' (fx) (gy)$$

#### Definition (Pointwise relation)

$$>$$
  $R \triangleq \lambda f, g. \forall x. R(fx)(gx)$ 

(Sozeau 2009)

Connective	Туре	Signature
*	iProp  ightarrow iProp  ightarrow iProp	$(*) \Longrightarrow (*) \Longrightarrow (*)$

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### Definition (Proper element of a relation)

Given a relation R:  $iRel\ A$  and an element  $x\in A$ , x is a proper element of R if Rxx.

$$((-*) \Longrightarrow (-*) \Longrightarrow (-*))(*)(*) =$$
$$\forall P, P'. (P -* P') -* \forall Q, Q'. (Q -* Q') -* (P * Q) -* (P' * Q')$$

$$\Box \left( \forall hd \ \overrightarrow{v}. \Phi \ hd \ \overrightarrow{v} \ \twoheadrightarrow \Psi \ hd \ \overrightarrow{v} \right) \twoheadrightarrow$$

$$\left( \begin{array}{cc} \forall hd \ \overrightarrow{v}. & \text{isMLL}_F \Phi \ hd \ \overrightarrow{v} \ \twoheadrightarrow \\ & \text{isMLL}_F \Psi \ hd \ \overrightarrow{v} \end{array} \right)$$

#### Normalization

Introduce quantifiers and modalities
 → Application step

- Apply reflexivity
- Apply assumption
- $\bullet \ \, \mathsf{Apply} \ \mathsf{signature} \to \mathsf{Normalization} \ \mathsf{step}$

$$(hd = \textbf{none} * \overrightarrow{v} = []) \lor \\ \begin{pmatrix} \exists \ell, \lor, tl. hd = \textbf{some} \, I * \\ I \mapsto (\lor, \textbf{true}, tl) * \\ \varPhi \, tl \, \overrightarrow{v} \end{pmatrix} \lor \\ \begin{pmatrix} \exists \ell, \lor, \overrightarrow{v}'', tl. \, hd = \textbf{some} \, I * \\ I \mapsto (\lor, \textbf{false}, tl) * \\ \overrightarrow{v} = \lor :: \overrightarrow{v}'' * \varPhi \, tl \, \overrightarrow{v}'' \end{pmatrix}$$

$$\overrightarrow{v} = (hd = \textbf{none} * \overrightarrow{v} = []) \lor \\ \begin{pmatrix} \exists \ell, \lor, tl. hd = \textbf{some} \, I * \\ I \mapsto (\lor, \textbf{true}, tl) * \\ \Psi \, tl \, \overrightarrow{v} \end{pmatrix} \lor$$

 $\exists \ell, \sqrt{, \overrightarrow{v}''}, \textit{tl. hd} = \mathbf{some} \, \textit{I} *$ 

 $l \mapsto (\sqrt{l}, \mathbf{false}, tl) *$  $\vec{v} = \vec{v} :: \vec{v}'' * \Psi t l \vec{v}''$ 

### Normalization

- Introduce quantifiers and modalities
- ightarrow Application step

- Apply reflexivity
- Apply assumption
- ullet Apply signature o Normalization step

$$(hd = \mathbf{none} * \overrightarrow{v} = []) \lor \\ (\exists \ell, \lor, tl. hd = \mathbf{some} \, l * \\ l \mapsto (\lor, \mathbf{true}, tl) * \\ \varPhi \, tl \, \overrightarrow{v} ) \lor \\ (\exists \ell, \lor, \overrightarrow{v}'', tl. \, hd = \mathbf{some} \, l * \\ l \mapsto (\lor, \mathbf{false}, tl) * \\ \overrightarrow{v} = \lor :: \overrightarrow{v}'' * \varPhi \, tl \, \overrightarrow{v}'' )$$

$$\overset{*}{} (hd = \mathbf{none} * \overrightarrow{v} = []) \lor \\ (\exists \ell, \lor, tl. hd = \mathbf{some} \, l * \\ l \mapsto (\lor, \mathbf{true}, tl) * \\ \psi \, tl \, \overrightarrow{v} ) \\ (\exists \ell, \lor, \overrightarrow{v}'', tl. \, hd = \mathbf{some} \, l * )$$

 $l\mapsto (\sqrt{l},\mathsf{false},tl)*$ 

## Normalization

- Introduce quantifiers and modalities
- ightarrow Application step

- Apply reflexivity
- Apply assumption
- Apply signature → Normalization step

$$(hd = none * \overrightarrow{v} = [])$$
 $-*$ 
 $(hd = none * \overrightarrow{v} = [])$ 

#### Normalization

Introduce quantifiers and modalities
 → Application step

- Apply reflexivity
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- $\bullet \ \, \mathsf{Apply} \ \mathsf{signature} \to \mathsf{Normalization} \ \mathsf{step}$

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#### Normalization

 $\bullet \ \, \text{Introduce quantifiers and modalities} \\ \to \text{Application step}$ 

- Apply reflexivity
- Apply assumption
- $\bullet \ \, \mathsf{Apply} \ \mathsf{signature} \to \mathsf{Normalization} \ \mathsf{step}$

$$\left( \begin{array}{c} \exists \ell, \sqrt{,} \, tl. \, hd = \mathbf{some} \, I \, * \\ I \mapsto (\sqrt{,} \, \mathbf{true}, tl) \, * \\ \varPhi \, tl \, \overrightarrow{v} \end{array} \right) \vee$$

$$\left( \begin{array}{c} \exists \ell, \sqrt{,} \, \overrightarrow{v}'', \, tl. \, hd = \mathbf{some} \, I \, * \\ I \mapsto (\sqrt{,} \, \mathbf{false}, tl) \, * \\ \overrightarrow{v} = \sqrt{::} \, \overrightarrow{v}'' \, * \varPhi \, tl \, \overrightarrow{v}'' \end{array} \right)$$

$$-*$$

$$\left( \begin{array}{c} \exists \ell, \sqrt{,} \, tl. \, hd = \mathbf{some} \, I \, * \\ I \mapsto (\sqrt{,} \, \mathbf{true}, tl) \, * \\ \psi \, tl \, \overrightarrow{v} \end{array} \right) \vee$$

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#### Normalization

- Introduce quantifiers and modalities
  - $\rightarrow \mathsf{Application} \ \mathsf{step}$

- Apply reflexivity
- Apply assumption
- ullet Apply signature o Normalization step

$$\left( \begin{array}{c} \exists \ell, \sqrt{,} \ tl.hd = \textbf{some} \ l * \\ l \mapsto (\sqrt{,} \ \textbf{true}, \ tl) * \\ \varPhi \ tl \ \overrightarrow{v} \\ \end{array} \right) \lor$$
 
$$\left( \begin{array}{c} \exists \ell, \sqrt{,} \ \overrightarrow{v}'', \ tl. \ hd = \textbf{some} \ l * \\ l \mapsto (\sqrt{,} \ \textbf{false}, \ tl) * \\ \overrightarrow{v} = \sqrt{::} \ \overrightarrow{v}'' * \varPhi \ tl \ \overrightarrow{v}'' \\ \end{array} \right)$$

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#### Normalization

- Introduce quantifiers and modalities
   → Application step
- **Application** 
  - Apply reflexivity
  - Apply assumption
  - Apply signature  $\rightarrow$  Normalization step  $(-*) \Longrightarrow (-*) \Longrightarrow (-*)$

$$\Box (\forall hd \ \overrightarrow{v}. \Phi \ hd \ \overrightarrow{v} \twoheadrightarrow \Psi \ hd \ \overrightarrow{v})$$
$$\vdash \Phi \ tl \ \overrightarrow{v} \twoheadrightarrow \Psi \ tl \ \overrightarrow{v}$$

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Introduce quantifiers and modalities
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- Apply reflexivity
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# Least fixpoint

### Theorem (Least fixpoint)

Given a monotone function  $F: (A \rightarrow iProp) \rightarrow A \rightarrow iProp$ , called the pre fixpoint function, there exists the least fixpoint

$$\mu \mathsf{F} \colon A \to i \mathsf{Prop} \triangleq \lambda \mathsf{F} \, \mathsf{x} . \, \forall \Phi. \, \, \Box (\forall y. \, \mathsf{F} \, \Phi \, y \twoheadrightarrow \Phi \, y) \twoheadrightarrow \Phi \, \mathsf{x}$$

such that

The fixpoint equality holds

$$\mu \mathsf{F} x \dashv \vdash \mathsf{F} (\mu \mathsf{F}) x$$

The iteration property holds

$$\Box(\forall y. \, \mathsf{F} \, \varPhi \, y \twoheadrightarrow \varPhi \, y) \vdash \forall x. \, \mu \mathsf{F} \, x \twoheadrightarrow \varPhi \, x$$

# Elpi

ullet  $\lambda$ Prolog dialect (Dunchev, Guidi, Coen, and Tassi 2015)

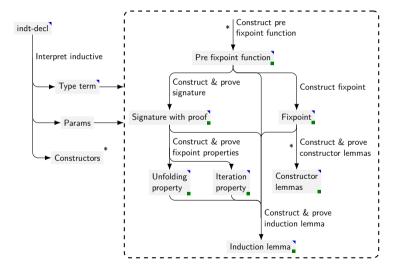
## Elpi

- ullet  $\lambda$ Prolog dialect (Dunchev, Guidi, Coen, and Tassi 2015)
- Coq meta-programming language (Tassi 2018)

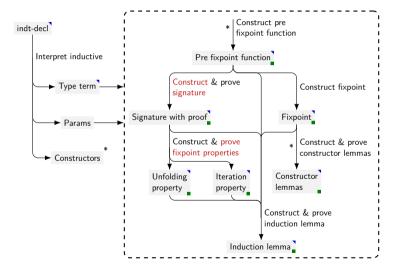
### Elpi

- ullet  $\lambda$ Prolog dialect (Dunchev, Guidi, Coen, and Tassi 2015)
- Coq meta-programming language (Tassi 2018)
- Derive (Tassi 2019)
- Hierarchy Builder (Cohen, Sakaguchi, and Tassi 2020)
- Trocq (Cohen, Crance, and Mahboubi 2024)

# Outline of implementation



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# Coq-Elpi HOAS

val → list val → iProp

# Coq-Elpi HOAS

```
1 val → list val → iProp Coq

1 \forall _:val. \forall _:list val. iProp Coq
```

# Coq-Elpi HOAS

```
val → list val → iProp

Coq

V _:val. ∀ _:list val. iProp

Coq
```

```
∀ _:val. ∀ _:list val. iProp
                                    Coq
                                             \square(\gg \gg (-*)) \Longrightarrow \gg \gg (-*)
                                                                 Elpi
pred type->signature i:term, i:term, o:term.
type->signature PreFixF Type Proper :-
     type->signature.aux Type P.
     cog.elaborate-skeleton
         {{ IProper (□> lp:P ==> lp:P) lp:PreFixF }}
         {{ Prop }} Proper ok.
pred type->signature.aux i:term, o:term.
type->signature (prod N T F) {{ .> lp:P }} :-
     pi x\ type->signature.aux (F x) P.
type->signature {{ iProp }} {{ bi wand }}.
```

```
∀ _:val. ∀ _:list val. iProp
                                    Coq
                                             \square(\gg \gg (-*)) \Longrightarrow \gg \gg (-*)
                                                                 Elpi
pred type->signature i:term, i:term, o:term.
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type->signature (prod N T F) {{ .> lp:P }} :-
     pi x\ type->signature.aux (F x) P.
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```

```
ı ∀ _:val. ∀ _:list val. iProp
                                      Coq
                                               \square(>>(*))\Longrightarrow >>(*)
                                                                  Elpi
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            {{ Prop }} Proper ok.
   pred type->signature.aux i:term, o:term.
   type->signature (prod N T F) {{ .> lp:P }} :-
        pi x\ type->signature.aux (F x) P.
   type->signature {{ iProp }} {{ bi wand }}.
```

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∀ _:val. ∀ _:list val. iProp
                                     Coq
                                              \square( \gt \gt (\neg *)) \Longrightarrow \gt \gt (\neg *)
                                                                  Elpi
pred type->signature i:term, i:term, o:term.
type->signature PreFixF Type Proper :-
     type->signature.aux Type P.
     cog.elaborate-skeleton
         {{ IProper (□> lp:P ==> lp:P) lp:PreFixF }}
         {{ Prop }} Proper ok.
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- We reuse the IPM lemmas written for its tactics
- We develop a strategy for modular proof term generators which employ the Coq API
- These modular proof term generators are also repackaged into a new set of IPM tactics, e.g. eiIntros (Elpi Iris Intros).

# Composing proof generators

```
is_MLL_pre is_MLL hd vs ⊣⊢ is_MLL hd vs
                                                           Elpi
pred mk-unfold.proof i:int, i:term, i:term, i:hole.
mk-unfold.proof Ps Unfold1 Unfold2 H:-
  do-iStartProof H (ihole N H'), !,
  do-iAndSplit H' H1 H2,
  std.map {std.iota Ps} (x\r = {\{ \}}) Holes1, !,
  do-iApplyLem (app [Unfold1 | Holes1]) (ihole N H1) [] [], !,
  std.map {std.iota Ps} (x\r = {\{ \}}) Holes2, !,
  do-iApplyLem (app [Unfold2 | Holes2]) (ihole N H2) [] [].
```

# Demo

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- Posed a strategy for defining modular tactics in Elpi
- Posed a syntactic proof search algorithm for finding a monotonicity proof of a pre fixpoint function
- Evaluated Elpi as a meta-programming language for the IPM

# Questions

#### Future work

- Non-expansive predicates
- Other fixpoint predicates
- Nested inductive predicates
- Mutual inductive predicates

# Holes in proofs

```
Elpi
kind hole type.
type hole term -> term -> hole.
pred do-iAndSplit i:hole, o:hole, o:hole.
do-iAndSplit (hole Type Proof) (hole LType LProof)
             (hole RType RProof) :-
  @no-tc! => cog.elaborate-skeleton
                {{ tac and split
                Type Proof ok,
  Proof = {{ tac and split
                           lp:FromAnd lp:LProof lp:RProof }},
  cog.ltac.collect-goals FromAnd [G1] _,
  open tc solve G1 [].
  cog.typecheck LProof LType ok,
  cog.typecheck RProof RType ok.
```

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Given a relation R:  $iRel\ A$  and an element  $x\in A$ , x is a proper element of R if Rxx.

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$$R \Longrightarrow R' \triangleq \lambda f, g. \, \forall x, y. \, R \times y \twoheadrightarrow R' \, (fx) \, (g \, y)$$

### Definition (Pointwise relation)

$$\Rightarrow R \triangleq \lambda f, g. \ \forall x. \ R(fx)(gx)$$

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