# InvarGenT: Implementation

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#### Abstract

InvarGenT is a proof-of-concept system for invariant generation by full type inference with Guarded Algebraic Data Types and existential types encoded as automatically generated GADTs. This implementation documentation focuses on source code, refers to separate technical reports on theory and algorithms.

### 1 Data Structures and Concrete Syntax

Following [1], we have the following nodes in the abstract syntax of patterns and expressions:

- p-Empty. 0: Pattern that never matches. Concrete syntax: !. Constructor: Zero.
- p-Wild. 1: Pattern that always matches. Concrete syntax: \_. Constructor: One.
- p-And.  $p_1 \wedge p_2$ : Conjunctive pattern. Concrete syntax: e.g. p1 as p2. Constructor: PAnd.
- p-Var. x: Pattern variable. Concrete syntax: lower-case identifier e.g. x. Constructor: PVar.
- p-Cstr.  $Kp_1...p_n$ : Constructor pattern. Concrete syntax: e.g. K (p1, p2). Constructor: PCons.
- ${\tt Var.}\ x$ : Variable. Concrete syntax: lower-case identifier e.g.  ${\tt x}$ . Constructor:  ${\tt Var.}\$ External functions are represented as variables in global environment.
- Cstr.  $Ke_1...e_n$ : Constructor expression. Concrete syntax: e.g. K (e1, e2). Constructor: Cons.
- App.  $e_1 e_2$ : Application. Concrete syntax: e.g. x y. Constructor: App.
- LetRec. letrec  $x = e_1$  in  $e_2$ : Recursive definition. Concrete syntax: e.g. let rec f = function ... in ... Constructor: Letrec.
- Abs.  $\lambda(c_1...c_n)$ : Function defined by cases. Concrete syntax: for single branching via fun keyword, e.g. fun x y -> f x y translates as  $\lambda(x.\lambda(y.(fx)y))$ ; for multiple branching via match keyword, e.g. match e with ... translates as  $\lambda(...)e$ . Constructor: Lam.
- Clause. p.e: Branch of pattern matching. Concrete syntax: e.g. p -> e.
- CstrIntro. Does not figure in neither concrete nor abstract syntax. Scope of existential types is thought to retroactively cover the whole program.
- ExCases.  $\lambda[K](p_1.e_1...p_n.e_n)$ : Function defined by cases and abstracting over the type of result. Concrete syntax: function and ematch keywords e.g. function Nil -> ... | Cons (x,xs) -> ...; ematch 1 with ... Parsing introduces a fresh identifier for K. Constructor: ExLam.
- ExLetIn. let  $p = e_1$  in  $e_2$ : Elimination of existentially quantified type. Concrete syntax: e.g. let  $v = f e \dots$  in ... Constructor: Letin.

We also have one sort-specific type of expression, numerals.

For type and formula connectives, we have ASCII and unicode syntactic variants (the difference is only in lexer). Quantified variables can be space or comma separated. The table below is analogous to information for expressions above. Existential type construct introduces a fresh identifier for K. The abstract syntax of types is not sort-safe, but type variables carry sorts which are inferred after parsing. Existential type occurrence in user code introduces a fresh identifier, a new type constructor in global environment newtype\_env, and a new value constructor in global environment newcons\_env – the value constructor purpose is to store the content of the existential type, it is not used in the program.

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type variable	x	x		TVar
type constructor	List	List		TCons(CNamed)
number (type)	7	7		NCst
numeral (expr.)	7	7		Num
numerical sum (type)	a+b	a+b		Nadd
existential type	$\exists \alpha \beta [a \leqslant \beta].\tau$	ex a b [a<=b].t	$\exists a,b[a \leq b].t$	TCons(Extype)
type sort	$s_{ m ty}$	type		Type_sort
number sort	$s_R$	num		Num_sort
function type	$ au_1 \rightarrow  au_2$	t1 -> t2	$t1 \rightarrow t2$	Fun
equation	a = b	a = b		Eqty
inequation	$a \leqslant b$	a <= b	$a \leq b$	Leq
conjunction	$\varphi_1 \wedge \varphi_2$	a=b && b=a	a=b ∧ b=a	built-in lists

Toplevel expressions (corresponding to structure items in OCaml) introduce types, type and value constructors, global variables with given type (external names) or inferred type (definitions).

type constructor	newtype List : type * num	TypConstr
value constructor	newcons Cons : all n a. a * List(a,n)> List(a,n+1)	ValConstr
	$\texttt{newcons Cons} \; : \; \forall \texttt{n,a. a * List(a,n)} \; \longrightarrow \; \texttt{List(a,n+1)}$	
declaration	external filter : $\forall n,a. \ List(a,n) \rightarrow \exists k[k \le n]. List(a,k)$	PrimVal
rec. definition	let rec f =	LetRecVal
non-rec. definition	let v =	LetVal

For simplicity of theory and implementation, mutual non-nested recursion and or-patterns are not provided. For mutual recursion, nest one recursive definition inside another.

### 2 Generating and Normalizing Formulas

We inject the existential type and value constructors during parsing for user-provided existential types, and during constraint generation for inferred existential types, into the list of toplevel items, which allows to follow [1] despite removing extype construct from the language. It also faciliates exporting inference results as OCaml source code.

Functions constr\_gen\_pat and envfrag\_gen\_pat compute formulas according to table 2 in [1], and constr\_gen\_expr computes table 3. Due to the presentation of the type system, we ensure in ValConstr that bounds on type parameters are introduced in the formula rather than being substituted into the result type. We preserve the FOL language presentation in the type cnstrnt, only limiting the expressivity in ways not requiring any preprocessing. The toplevel definitions (from type struct\_item) LetRecVal and LetVal are processed by constr\_gen\_letrec and constr\_gen\_let respectively. They are analogous to Letrec and Letin or a Lam clause. We do not cover toplevel definitions in our formalism (without even a rudimentary module system, the toplevel is a matter of pragmatics rather than semantics).

To plevel definitions are intended as boundaries for constraint solving. This way the programmer can decompose functions that could be too complex for the solver. Let RecVal only binds a single identifier, while LetVal binds variables in a pattern. To preserve the flexibility of expression-level pattern matching, LetVal has to pack the constraints  $[\![\Sigma \vdash p \uparrow \alpha]\!]$  which the pattern makes available, into existential types. Each pattern variable is a separate entry to the global environment, therefore the connection between them is lost.

The formalism (in interests of parsimony) requires that only values of existential types be bound using Letin syntax. The implementation is enhanced in this regard: if the normalization step cannot determine which existential type is being eliminated, the constraint is replaced by one that would be generated for a pattern matching branch. This recovers the common use of the let...in syntax, with exception of polymorphic let cases, where let rec still needs to be used.

In the formalism, we use  $\mathcal{E} = \{\varepsilon_K, \chi_K | K :: \forall \alpha \gamma [\chi_K(\alpha, \gamma)]. \gamma \to \varepsilon_K(\alpha) \in \Sigma \}$  for brevity, as if all existential types  $\varepsilon_K(\alpha)$  were related with a predicate variable  $\chi_K(\alpha, \gamma)$ . In the implementation, we have user-defined existential types with explicit constraints in addition to inferred existential types. We keep track of existential types in cell ex\_types, storing arbitrary constraints. For LetVal, we form existential types after solving the generated constraint, to have less intermediate variables in them. The first argument of the predicate variable  $\chi_K(\alpha, \gamma)$  provides an "escape route" for free variables, e.g. precondition variables used in postcondition. It is used for convenience in the formalism. In the implementation, after the constraints are solved, we expand it to pass each free variable as a separate parameter, to increase readability of exported OCaml code.

For simplicity, only toplevel definitions accept type and invariant annotations from the user. The constraints are modified according to the  $[\![\Gamma, \Sigma \vdash \operatorname{ce}: \forall \bar{\alpha} [D].\tau]\!]$  rule. Where Letrec uses a fresh variable  $\beta$ , LetRecVal incorporates the type from the annotation. The annotation is considered partial, D becomes part of the constraint generated for the recursive function but more constraints will be added if needed. The polymorphism of  $\forall \bar{\alpha}$  variables from the annotation is preserved since they are universally quantified in the generated constraint.

The constraints solver returns three components: the *residue*, which implies the constraint when the predicate variables are instantiated, and the solutions to unary and binary predicate variables. The residue and the predicate variable solutions are separated into *solved variables* part, which is a substitution, and remaining constraints (which are currently limited to linear inequalities). To get a predicate variable solution we look for the predicate variable identifier association and apply it to one or two type variable identifiers, which will instantiate the parameters of the predicate variable. We considered several ways to deal with multiple solutions:

- 1. report a failure to the user;
- 2. ask the user for decision;
- 3. perform backtracking search for the first solution that satisfies the subsequent program.

We use an enhanced variant of approach 1 as it is closest to traditional type inference workflow. Upon "multiple solutions" failure the user can add assert clauses (e.g. assert false stating that a program branch is impossible), and test clauses. The test clauses are boolean expressions with operational semantics of run-time tests: the test clauses are executed right after the definition is executed, and run-time error is reported when a clause returns false. The constraints from test clauses are included in the constraint for the toplevel definition, thus propagate more efficiently than backtracking would. The assert clauses are: assert = type e1 e2 which translates as equality of types of e1 and e2, assert false which translates as CFalse, and assert e1 <= e2, which translates as inequality  $n_1 \leq n_2$  assuming that e1 has type Num n1 and e2 has type Num n2.

#### 2.1 Normalization

Rather than reducing to prenex-normal form as in our formalization, we preserve the scope relations and return a var\_scope-producing variable comparison function. Also, since we use let-in syntax to both eliminate existential types and for traditional (but not polymorphic) binding, we drop the Or1 constraints (in the formalism they ensure that let-in binds an existential type). During normalization, we compute unifiers of the type sort part of conclusions. This faciliates solving of the disjunctions in ImplOr2 constraints. We monitor for contradiction in conclusions, so that we can stop the Contradiction exception and remove an implication in case the premise is also contradictory.

Releasing constraints from under Impl0r2, when the corresponding let-in is interpreted as standard binding (instead of eliminating existential type), violates declarativeness. We cannot include all the released constraints in determining whether non-nested Impl0r2 constraints should be interpreted as eliminating existential types. While we could be more "aggresive" (we can modify the implementation to release the constraints one-by-one), it shouldn't be problematic, because nesting of Impl0r2 corresponds to nesting of let-in definitions.

After normalization, we simplify the constraints by removing redundant atoms. We remove atoms that bind variables not occurring anywhere else in the constraint, and in case of atoms not in premises, not universally quantified. The simplification step is not currently proven correct and might need refining.

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### 3 Abduction

The formal specification of abduction in [7] provides a scheme for combining sorts that substitutes number sort subterms from type sort terms with variables, so that a single-sort term abduction algorithm can be called. Since we implement term abduction over the two-sorted datatype typ, we keep these *alien subterms* in terms passed to term abduction.

#### 3.1 Simple constraint abduction for terms

Our initial implementation of simple constraint abduction for terms follows [?] p. 13. The mentioned algorithm only gives fully maximal answers which is loss of generality w.r.t. our requirements. To solve  $D\Rightarrow C$  the algorithm starts with with  $U(D\wedge C)$  and iteratively replaces subterms by fresh variables  $\alpha\in\bar{\alpha}$  for a final solution  $\exists\bar{\alpha}.A$ . To mitigate some of the limitations of fully maximal answers, we start from  $U_{\bar{\alpha}}(A(D\wedge C))$ , where  $\exists\bar{\alpha}.A$  is the solution to previous problems solved by the joint abduction algorithm, and  $A(\cdot)$  is the corresponding substitution. We follow top-down approach where bigger subterms are abstracted first – replaced by fresh variable, together with an arbitrary selection of other occurrences of the subterm. If replacing a subterm by fresh variable maintains  $T(F) \models A \wedge D \Rightarrow C$ , we proceed to neighboring subterm or next equation. If  $T(F) \models A \wedge D \Rightarrow C$  does not hold, we try all of: proceeding to subterms of the subterm; replacing the subterm by the fresh variable; replacing the subterm by variables corresponding to earlier occurrences of the subterm. This results in a single, branching pass over all subterms considered. TODO: avoiding branching when implication holds might lead to another loss of generality, does it? Finally, we clean up the solution by eliminating fresh variables when possible (i.e. substituting-out equations  $x \doteq \alpha$  for variable x and fresh variable  $\alpha$ ).

Although our formalism stresses the possibility of infinite number of abduction answers, there is always finite number of *fully maximal* answers that we compute. The formalism suggests computing them lazily using streams, and then testing all combinations – generate and test scheme. Instead, we use a search scheme that tests as soon as possible. The simple abduction algorithm takes a partial solution – a conjunction of candidate solutions for some other branches – and checks if the solution being generated is satisfiable together with the candidate partial solution. The algorithm also takes a number that determines how many correct solutions to skip.

### 3.2 Joint constraint abduction for terms

We further lose generality by using a heuristic search scheme instead of testing all combinations of simple abduction answers. If natural counterexamples are found, rather than ones contrived to demonstrate that our search scheme is not complete, it can be augmented. In particular, our search scheme returns from joint abduction for types with a single answer, which eliminates any interaction between the sort of types and other sorts.

We maintain an ordering of branches. We accumulate simple abduction answers into the partial abduction answer until we meet branch that does not have any answer satisfiable with the partial answer so far. Then we start over, but put the branch that failed in front of the sequence. If a branch i is at front for  $n_i$ th time, we skip the initial  $n_i - 1$  simple abduction answers in it. If the front branch i does not have at least  $n_i$  answers, the search fails.

As described in [?], to check validity of answers, we use a modified variant of unification under quantifiers: unification with parameters, where the parameters do not interact with the quantifiers and thus can be freely used and eliminated. Note that to compute conjunction of the candidate answer with a premise, unification does not check for validity under quantifiers.

Because it would be difficult to track other sort constraints while updating the partial answer, we discard numeric sort constraints in simple abduction algorithm, and recover them after the final answer for terms (i.e. for the type sort) is found.

## Bibliography